

TPS549B22EVM-847, 25-A Single Synchronous Step-Down Converter With Full Differential Sense and PMBus™

This user's guide describes the characteristics, operation, and use of the TPS549B22 Evaluation Module (EVM). The user's guide includes test information, descriptions, and results. A complete schematic diagram, printed-circuit board layouts, and bill of materials are also included in this document. Throughout this user's guide, the abbreviations EVM, TPS549B22EVM, and the term evaluation module are synonymous with the TPS549B22EVM-847, unless otherwise noted.

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Introduction

1 Introduction

The PWR847EVM evaluation module uses the TPS549B22 device. The TPS549B22 is a highly integrated synchronous buck converter that is designed for up to 25-A current output.

1.1 Before You Begin

The following warnings and cautions are noted for the safety of anyone using or working close to the TPS549B22EVM-847. Observe all safety precautions.



Warning

The TPS549B22EVM-847 circuit module may become hot during operation due to dissipation of heat. Avoid contact with the board. Follow all applicable safety procedures applicable to your laboratory.

Caution

Do not leave the EVM powered when unattended.

WARNING

The circuit module has signal traces, components, and component leads on the bottom of the board. This may result in exposed voltages, hot surfaces or sharp edges. Do not reach under the board during operation.

CAUTION

The circuit module may be damaged by over temperature. To avoid damage, monitor the temperature during evaluation and provide cooling, as needed, for your system environment.

CAUTION

Some power supplies can be damaged by application of external voltages. If using more than 1 power supply, check your equipment requirements and use blocking diodes or other isolation techniques, as needed, to prevent damage to your equipment.

CAUTION

The communication interface is not isolated on the EVM. Be sure no ground potential exists between the computer and the EVM. Also be aware that the computer is referenced to the Battery- potential of the EVM.



Description

2 Description

The PWR-847EVM is designed as a single output DC-DC converter that demonstrates the TPS549B22 in a typical low-voltage application while providing a number of test points to evaluate the performance. It uses a nominal 12-V input bus to produce a regulated 1-V output at up to 25-A load current.

2.1 Typical End-User Applications

- Enterprise Storage, SSD, NAS
- Wireless and Wired Communication Infrastructure
- Industrial PCs, Automation, ATE, PLC, Video Surveillance
- Enterprise Server, Switches, Routers
- ASIC, SoC, FPGA, DSP Core and I/O Rails

2.2 EVM Features

- Regulated 1-V output up to 25-A, steady-state output current
- · Convenient test points for probing critical waveforms
- PMBus[™] connector for easy connection with the TI USB adapter



EVM Electrical Performance Specifications

3 EVM Electrical Performance Specifications

Table 1 lists the PWR-847EVM electrical performance specifications.

Table 1. PWR-847EVM Electrical Performance Specifications

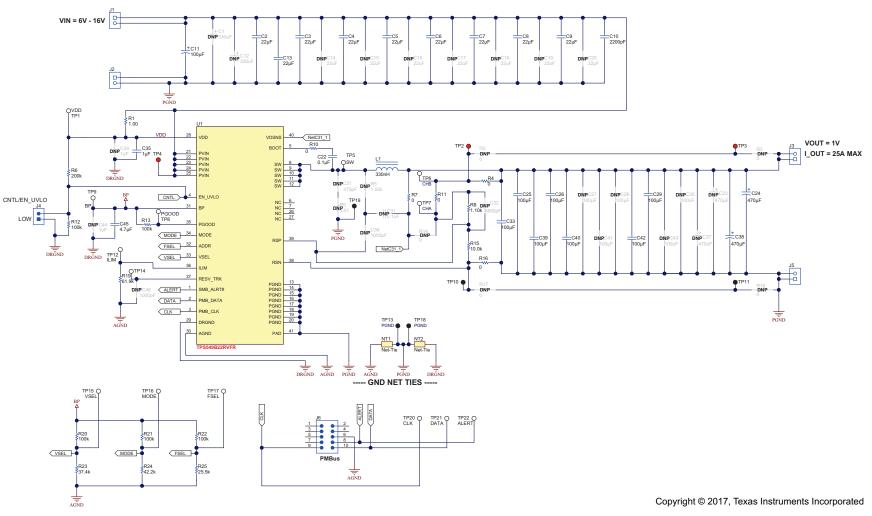
	Parameter	Test Conditions	Min	Тур	Max	Units
Input Characteristics						
	Voltage range	V _{IN} tied to VDD	5	12	14	V
	Maximum input current	V _{IN} = 12 V, I _O = 25 A			12	А
	No load input current	V _{IN} = 12 V, I _O = 0 A		60		mA
Outpu	It Characteristics				1	
V _{OUT}	Output voltage	Output current = 10 A		1		V
I _{OUT}	Output load current	I _{OUT(min)} to I _{OUT(max)}	0		25	А
	Output voltage regulation	Line regulation: input voltage = 5 V to 14 V		0.5%		
	Output voltage regulation	Load regulation: output current = 0 A to $I_{OUT(max)}$		0.5%		
V _{OUT}	Output voltage ripple	V _{IN} = 12 V, I _{OUT} = 25 A		10		$\mathrm{mV}_{\mathrm{PP}}$
V _{OUT}	Output overcurrent			32		А
Syste	ms Characteristics				•	
	Switching frequency	F _{sw}		650		kHz
V _{OUT}	Peak efficiency	V _{IN} = 12 V, I _O = 12 A, F _{SW} = 650 kHz		90%		
	Operating temperature	T _{oper}	0		85	°C

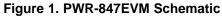


Schematic

4 Schematic

Figure 1 illustrates the PWR-847EVM schematic.







5 Test Setup

7

5.1 Test and Configuration Software

To change any of the default configuration parameters on the EVM, it is necessary to obtain the TI Fusion Digital Power Designer software. This can be downloaded from the TI website.

5.1.1 Description

The Fusion Digital Power Designer is the graphical user interface (GUI) used to configure and monitor the Texas Instruments TPS549B22 power converter installed on this evaluation module. The application uses the PMBus protocol to communicate with the controller over serial bus by way of a TI USB adapter. This adapter can be purchased at http://www.ti.com/tool/usb-to-gpio.

NOTE: The TI USB adapter must be purchased separately. It is not included with this EVM kit.

5.1.2 Features

Some of the tasks performed with the GUI include:

- Turn on or off the power supply output, either through the hardware control line or the PMBus operation command.
- Monitor status registers. Items such as input voltage, output voltage, output current, temperature, and warnings and faults are continuously monitored and displayed by the GUI.
- Configure common operating characteristics such as VOUT, UVLO, soft-start time, warning and fault thresholds, fault response, and ON/OFF.

This software is available for download at http://www.ti.com/tool/fusion_digital_power_designer.



6 Test Equipment

Voltage Source: The input voltage source VIN must be a 0-V to 18-V variable DC source capable of supplying at least 12 A_{DC} .

Multimeters: It is recommended to use two separate multimeters Figure 2. One meter is used to measure V_{IN} and one to measure V_{OUT} .

Output Load: A variable electronic load is recommended for testing Figure 2. It must be capable of 25 A at voltages as low as 0.6 V.

Oscilloscope: An oscilloscope is recommended for measuring output noise and ripple. Output ripple must be measured using a tip-and-barrel method or better as shown in Figure 3. The scope must be adjusted to 20-MHz bandwidth, AC coupling at 50 mV/division, and must be set to 1-µs/division.

Fan: During prolonged operation at high loads, it may be necessary to provide forced air cooling with a small fan aimed at the EVM. Temperature of the devices on the EVM must be maintained below 105°C.

USB-to-GPIO Interface Adapter: A communications adapter is required between the EVM and the host computer. This EVM was designed to use TI's USB-to-GPIO adapter. Purchase this adapter at http://www.ti.com/tool/usb-to-gpio.

Recommended Wire Gauge: The voltage drop in the load wires must be kept as low as possible in order to keep the working voltage at the load within its operating range. Use the AWG 14 wire (2 wires parallel for VOUT positive and 2 wires parallel for the VOUT negative) of no more than 1.98 feet between the EVM and the load. This recommended wire gauge and length should achieve a voltage drop of no more than 0.2 V at the maximum 25-A load.



7 PWR-847EVM

Figure 2 and Figure 3 illustrate the PWR-847EVM overview, tip and barrel measurement.

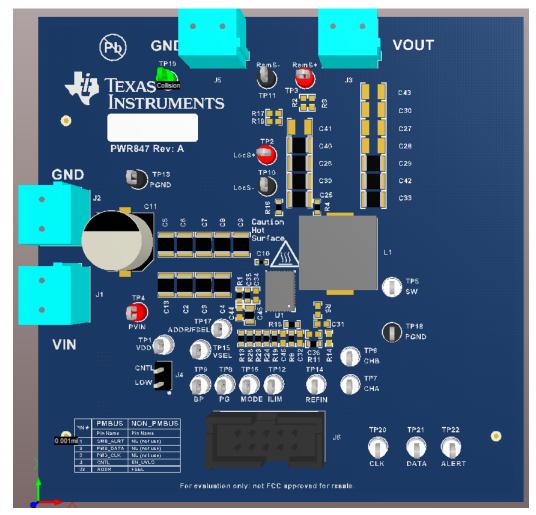


Figure 2. PWR-847EVM Overview

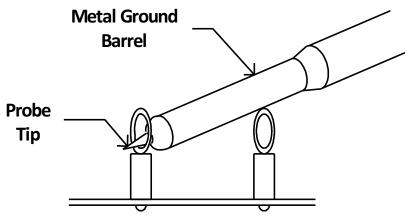


Figure 3. Tip and Barrel Measurement



PWR-847EVM

Figure 4 illustrates the EVM and USB interface adapter.

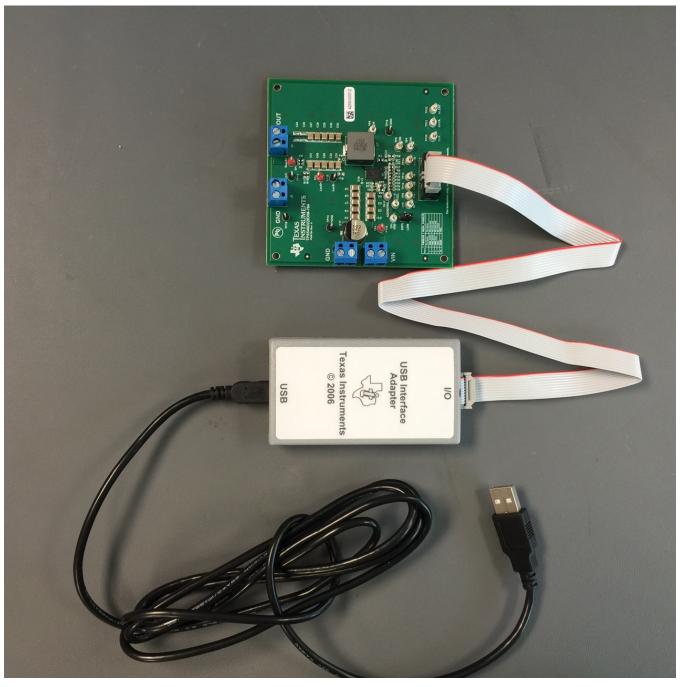


Figure 4. EVM and USB Interface Adapter

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8 List of Test Points, Jumpers, and Switch

Table 2 lists the test points and their descriptions.

Item	Туре	Name	Description			
TP5	T-H loop	SW	Power supply Switch node			
TP7	T-H loop	CH-A	Measure loop stability			
TP6	T-H loop	CH-B	Measure loop stability			
TP2	T-H loop	LocS+	Sense VOUT + locally across C25. Use for efficiency and ripple measurements			
TP10	T-H loop	LocS-	Sense VOUT– locally across C25. Use for efficiency and ripple measurements			
TP3	T-H loop	RemS+	Remote sense +			
TP11	T-H loop	RemS-	Remote sense –			
TP4	T-H loop	PVIN	Sense VIN + across C10			
TP13	T-H loop	PGND	Sense VIN – across C10			
TP1	T-H loop	VDD	Supplies the internal circuitry			
TP17	T-H loop	ADDR	Monitor the ADDR external resistor divider ratio during initial power up.			
TP15	T-H loop	VSEL	Monitor the VSEL external resistor divider ratio during initial power up.			
TP9	T-H loop	BP	LDO output			
TP8	T-H loop	PG	Power good			
TP16	T-H loop	MODE	Monitor the MODE external resistor divider ratio during initial power up.			
TP12	T-H loop	ILIM	Program over-current limit.			
TP14	T-H loop	RESV_TRK	Do not connect.			
TP19	T-H loop	PGND	Common GND			
TP18	T-H loop	PGND	Common GND			
TP20	T-H loop	PMB_CLK	Clock input for the PMBus interface.			
TP21	T-H loop	PMB_DATA	Data I/O for the PMBus interface.			
TP22	T-H loop	SMB_ALRT#	Alert output for the PMBus interface.			
JP4	2-pin jumper	CNTL	Shunts control pin to GND			

Table 2. Test Point Functions



9 EVM Configuration Using the Fusion GUI

The TPS549B22 installed on this EVM leave the factory pre-configured. See Table 3 for a short list of key factory configuration parameters as obtained from the configuration file.

Cmd ID With Phase	Cmd Code Hex	Encoded Hex [HiByte LoByte]	Comments	
CAPABILITY	0x19	0xD0	Max Bus: 1000 kHz; PEC: Yes; SMBALERT#: Yes	
MFR_00	0xD0	0x00	0	
MFR_01 (PGOOD_DLY)	0xD1	0x12	PGD:1024?s [010b], POD:1024?s [010b]	
MFR_02	0xD2	0x13	CM: True, HICLOFF: True, SST: 0x00, FORCESKIPSS: True, SEQ: False, TRK: False	
MFR_03	0xD3	0x93	FS:650 kHz [011b], RCSP:R ? 1 [01b], DCAP3:True	
MFR_04	0xD4	0x80	DCAP3_Offset:0mV [00b], DCAP3_Offset_Sel:True	
MFR_06	0xD6	0x05	VDDUVLO:4.25V [101b]	
MFR_07	0xD7	0x8F	VTRKIN:1.25V [1111b], TRKOPTION:False, SPARE:False, VPBAD:True	
MFR_33	0xF1	0x00	0	
MFR_42	0xFA	0x00	0	
MFR_44	0xFC	0x0201	ID: 0x020 (TPS549B22), Revision: 0x8	
ON_OFF_CONFIG	0x02	0x17	Mode: CONTROL Pin Only; Control: Active High, Turn off Immediately	
OPERATION	0x01	0x00	Operation is not used to enable regulatio; Unit: ImmediateOff; Margin: None	
STATUS_BYTE	0x78	0x00	Status: Output Off, Vout OV Fault, IOUT OC Fault, Vin UV Fault, Temperature, CML	
STATUS_CML	0x7E	0x00	Status: Invalid Command, Invalid Data, PEC Fault, Other Comms Fault	
STATUS_IOUT	0x7B	0x00	Status: lout OC Fault, lout OC Fault with LV Shutdown, lout UC Fault	
STATUS_VOUT	0x7A	0x00	Status: Vout OV Fault, OV Warning, UV Fault, UV Warning	
VOUT_COMMAND	0x21	0x01CD	VOUT_COMMAND=0.900 V	
VOUT_MARGIN_HIGH	0x25	0x0266	VOUT_MARGIN_HIGH=1.199 V	
VOUT_MARGIN_LOW	0x26	0x0266	VOUT_MARGIN_LOW=1.199 V	
WRITE_PROTECT	0x10	0x00	Enable Writes To All Commands	

If it is desired to configure the EVM to settings other than the factory settings shown in Table 3, the TI Fusion Digital Power Designer software can be used for reconfiguration. It is necessary to have input voltage applied to the EVM prior to launching the software so that the TPS549B22 installed is active and able to respond to the GUI and the GUI can recognize the device.



10 Test Procedure

10.1 Line and Load Regulation Measurement Procedure

Use the following procedures for line and load regulation measurement.

- 1. Connect VOUT to J3 and VOUT_GND to J5 Figure 2.
- 2. Ensure that the electronic load is set to draw $0 A_{DC}$.
- 3. Connect VIN to J1 and VIN_GND to J2 Figure 2.
- 4. Connect the USB interface adapter as shown in Figure 4.
- 5. Increase V_{IN} from 0 V to 12 V using the digital multimeter to measure input voltage.
- 6. Launch the Fusion GUI software. See the screen shots in Section 12 for more information.
- 7. Configure the EVM operating parameters as desired.
- 8. Use the other digital multimeter or the oscilloscope to measure output voltage V_{OUT} at TP2 and TP10 as you vary the external voltage source.

Test Point Node Name		Description		
TP2	LocS+	Sense VOUT + locally across C5. Use for efficiency and ripple measurements		
TP10	LocS-	Sense VOUT - locally across C5. Use for efficiency and ripple measurements		
TP4	PVIN	Sense VIN + across C10		
TP13	PGND	Sense VIN - across C10		

Table 4. List of Test Points for Line and Load Measurements

- Vary the load from 0 A_{DC} to maximum rated output 25 A_{DC}. V_{OUT} must remain in regulation as defined in Table 1.
- 10. Vary V_{IN} from 5 V to 14 V. V_{OUT} must remain in regulation as defined in Table 1.
- 11. Decrease the load to 0 A.
- 12. Decrease V_{IN} to 0 V or turn off the supply.

10.2 Efficiency

To measure the efficiency of the power train on the EVM, it is important to measure the voltages at the correct location. This is necessary because otherwise the measurements will include losses in efficiency that are not related to the power train itself. Losses incurred by the voltage drop in the copper traces and in the input and output connectors are not related to the efficiency of the power train, and they must not be included in efficiency measurements.

Test Point	Node Name	Description		
TP2	LocS+	Sense VOUT + locally across C25. Use for efficiency and ripple measurements		
TP10	LocS-	Sense VOUT - locally across C25. Use for efficiency and ripple measurements		
TP4	PVIN	Sense VIN + across C10		
TP13	PGND	Sense VIN - across C10		

Table 5. List of Test I	Points for Efficiency	y Measurements
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Input current can be measured at any point in the input wires, and output current can be measured anywhere in the output wires of the output being measured. Using these measurement points result in efficiency measurements that do not include losses due to the connectors and PCB traces.

10.3 Equipment Shutdown

- 1. Reduce the load current to 0 A.
- 2. Reduce input voltage to 0 V.
- 3. Shut down the external fan if in use.
- 4. Shut down equipment.



11 Performance Data and Typical Characteristic Curves

Figure 5 through Figure 18 present typical performance curves for the PWR-847EVM.

11.1 Efficiency

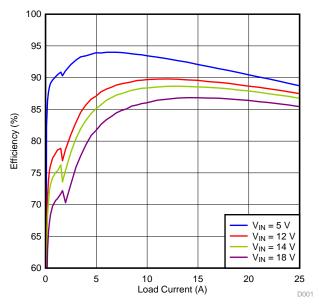


Figure 5. Efficiency vs Output Current SKIP Mode

11.2 Load Regulation

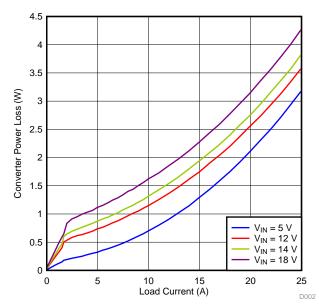
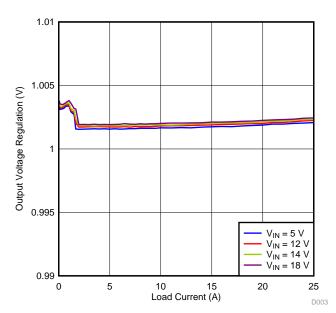


Figure 6. Power Loss vs Output Current SKIP Mode



11.3 Line Regulation



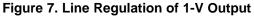




Figure 8. PMBus V_{out} Step-Up = 0.6 V to 1.2 V at 0 A



Performance Data and Typical Characteristic Curves



Figure 9. PMBus V_{out} Step-Down = 1.2 V to 0.6 V at 0 A



Figure 10. PMBus V_{OUT} Step-Up = 0.6 V to 1.2 V at 25 A



Figure 11. PMBus V_{OUT} Step-Down = 1.2 V to 0.6 V at 25 A

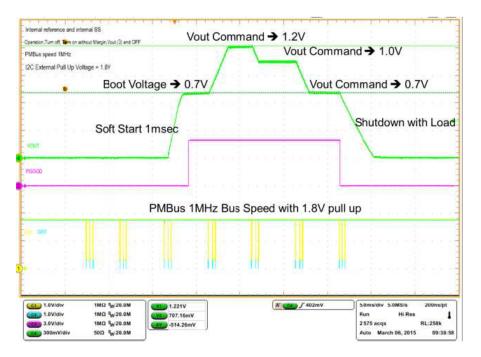


Figure 12. PMBUS Multiple Commands

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11.4 Transient Response



Figure 13. Transient Response of 1-V Output at 12 $V_{\mbox{\tiny IN}},$ Transient is 0.5 A to 15.5 A, the Step is 15 A at 40 A/ $\mbox{\mu s}$



11.5 Output Ripple

Figure 14. Output Ripple and SW Node of 1-V Output at 12 V_{IN} , 25-A Output

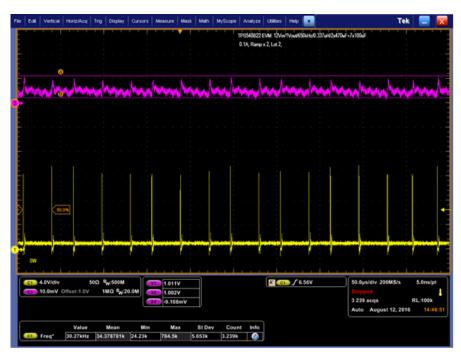


Figure 15. Output Ripple and SW Node of 1-V Output at 12 $V_{\mbox{\tiny IN}},$ 0-A Output

11.6 Control On



Figure 16. Start up from Control, 1-V Output at 12 $V_{\mbox{\tiny IN}}$, 0-A Output



Performance Data and Typical Characteristic Curves

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Figure 17. 0.5-V Pre-bias start up from Control, 1-V Output at 12 V $_{\rm IN}$, 10-A Output

11.7 Control Off



Figure 18. Start-Up and Shutdown, 1-V Output at 12 V_{IN} , 0.5-A Output



Performance Data and Typical Characteristic Curves

11.8 Thermal Image

Figure 19 illustrates the thermal image at 1-V output at 12 V_{IN} , 25-A output, 650 kHz at 25°C ambient.

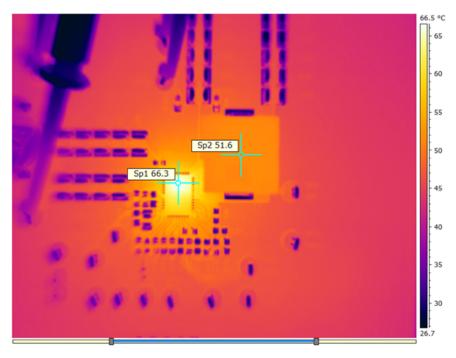


Figure 19. Thermal Image at 1-V Output at 12 V_{IN} , 25-A Output, 650 kHz at 25°C Ambient



Fusion GUI

12 Fusion GUI

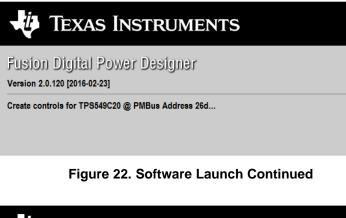
Figure 20 through Figure 23 illustrate the Fusion GUI launch and installation dialog windows.

Texas Instruments	
Fusion Digital Power Designer Version 2.0.120 [2016-02-23]	
Restoring user preferences and data	

Figure 20. First Window at Fusion Launch



Figure 21. Scan Finds Device Successfully









Use the *All Config* tab to configure all of the configurable parameters (Figure 24). The screen also shows other details like hexadecimal (hex) encoding. Use this screen to configure:

- Power Good Delay
- Power On Delay
- Mode Settings
- Frequency, RAMP, DCAP3
- VDD UVLO
- On/Off Configuration
- Track and Sequencing
- Write Protect
- VOUT Command Voltage
- VOUT Margin
- Operation

🖗 Fusion Digital Power D	esigner - TPS549C20 @ PMBus Add	iress 26d (1Ah) - Tex	as Instruments					
File Device Tools I	Help						TPS	549C20 @ 26d (1
Configure	All Config							
Write to Hardware	Command	Code	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit
Auto write on rail or device change	▼ Configuration				▼ Status			
Discard Changes	MFR_01 (PG00D_DLY)	0xD1	PGD:102 🗸	0x12	STATUS_BYTE	0×78	00000000 🗸	
	MFR_02	0xD2	CM: Tru 🗸	0x03	STATUS_CML	0×7E	00000000 🗸	
itore Config to NVM	MFR_03	0xD3	FS:625k 🗸	0x83	STATUS_IOUT	0×7B	00000000 🗸	
estore NVM Config	MFR_04	0xD4	DCAP3 🗸	0x80	STATUS_YOUT	0×7A	00000000 🗸	
ar Restore Notices	MFR_06	0xD6	VDDUVL 🗸	0x05	STATUS_WORD	0×79	Click 🗸	
Parameters By:	MFR_07	0xD7	VTRKIN: 🗸	0x8F	▼ User Parameters			
Command Name	MFR_33	0×F1	0x00	0x00	MFR_00	0×D0	0x00	0x00
Command Code	MFR_42	0×FA	0x00	0x00				
Group by Category	MFR_44	0×FC	0x0201 🗸	0x0201				
	YOUT_COMMAND	0x21	1.199 🔍 V	0x0266				
	VOUT_MARGIN_HIGH	0x25	1.199 🔷 V	0x0266				
	VOUT_MARGIN_LOW	0×26	1.199 🔷 V	0x0266				
	VOUT_MODE	0×20	EXP -9		-			
	WRITE_PROTECT	0×10	0x00 🗸	0x00				
	▼ Manufacturer Info							
	CAPABILITY	0×19	0xD0 🗸	0xD0				
	▼ On/Off Configuration							
	ON_OFF_CONFIG	0×02	0x17 🗸	0x17				
	OPERATION	0×01	0x00 🗸	0x00				
	Tips & Hints			PME	Bus Log			
Configure	MFR_00 [0xD0] User scratch pad.							
Monitor				\sim				
Status				С РМ	Bus Log			
sion Digital Power Desig	ner v2.0.120 [2016-02-23] TPS549C2	0 @ PMBus Address 26	5d (1Ah) USB Adar	ter v1.0.10 [N	lo PEC: 400 kHz]			😽 Texas

Figure 24. First Screen After Successful Launch Configure: Limits and On/Off



Fusion GUI

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Changing the frequency prompts a pop-up window with details of the options Figure 25).

All Config Command Configuration MFR_01 (PG00D_0LY)	Code					11 00 15020	@ 23d (17h) - Rail
▼ Configuration	C.A.						
	Loae	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit
MFR_01 (PG00D_DLY)				▼ Status			
	0xD1	PGD: 102 🗸	0x12	STATUS_BYTE	0x78	00000010 🗸	0x02
MFR_02	0xD2	CM: Tru 🗸	0x13	STATUS_CML	0×7E	1000000 🗸	0x80
MFR_03	0xD3	FS:625k 🗸	0x93	STATUS_IOUT	0×78	00000000	0x00
MFR_04	0xD4	DCAP3 🗸	RCSP: R ÷ 1				×00
MFR_06	0xD6	VDDUVL 🗸	These bits allow	v the user to read/configure the D-C/ f these bits are output directly from	AP3 ramp generator's resisto	r value selection.	×0002
MFR_07	0xD7	VTRKIN: 🖂	The condition of	in these bits are output directly from	the digital block on the pRCS	P[1:0] signal bus	
MFR_33	0xF1	0x00	FS: 625	√ kHz			x00
MFR_42	0×FA	0x00	These t 325 these b 425		ce's PWM switching frequent in the pFS[2:0] signal bus	cy. The condition of	
MFR_44	0xFC	0x0201 🗸	525	Cal Diock C	n and projetoj signal bus		
VOUT_COMMAND	0x21	1. 199 🐳	DCAP 625				
YOUT_MARGIN_HIGH	0x25	1. 199 💭	This bit 750 and ref 850	he device can also	's internal DCAP-3 mode. It be overwritten by PMBus. Tl	will initially be loaded he condition of this bit is	s
VOUT_MARGIN_LOW	0x26	1.199 💭	output 1000 0: Inte 1350	a P_DCAP			
YOUT_MODE	0x20	EXP -9	1: Internation	service in chapical (resp-VCSN r	amp injection is enabled)		
WRITE_PROTECT	0x10	0x00 🗸	×				.::
▼ Manufacturer Info			, <u></u>	Í .			
CAPABILITY	0×19	0xD0 🗸	0xD0	_			
▼ On/Off Configuration							
ON_OFF_CONFIG	0x02	0x17 🗸	0x17				
OPERATION	0x01	0x00 🗸	0x00				

Figure 25. Configure: Frequency- FS Configuration Pop-up

After a change is selected, orange **U** icon is displayed to offer *Undo Change* option. Change is not retained until either *Write to Hardware* or *Store Config to NVM* is selected. When *Write to Hardware* is selected, change is committed to volatile memory and defaults back to previous setting on input power cycle. When *Store Config to NVM* is selected, change is committed to nonvolatile memory and becomes the new default (Figure 26).

Fusion Digital Power Designer - TP5549C20 @ PMBus Address 23d	(17h) - Te	kas Instruments	;					_
ile Device Tools Help						TPS549C	20 @ 23d (17h) - Rail #1	
nfigure All Config								
Write to Hardware Command	Code	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit	
Auto write on rail or device change				▼ Status				
Discard Changes MFR_01 (PG00D_DLY)	0×D1	PGD: 102 🗸	0x12	STATUS_BYTE	0×78	00000010 🗸	0x02	
MFR_02	0xD2	CM: Tru 🗸	0x13	STATUS_CML	0×7E	1000000 🗸	0x80	
re Config to NVM MFR_03	🕛 0xD3	FS:525k 🗸	0x92	STATUS_IOUT	0x7B	00000000 🗸	0x00	
tore NVM Config MFR_04	0xD4	DCAP3 🗸	RCSP: R ÷	1			×00	
r Restore Notices MFR_06	0×D6	VDDUVL 🗸		ow the user to read/configure the D-CAP of these bits are output directly from th			×0002	
arameters By:	0xD7	VTRKIN: 🗸	The condition	for these bits are output thready from th	e ugrai block on the pres	-[1:0] signal bus		
Command Name MFR_33	0xF1	0x00	FS: 525	kHz			ix00	
Command Code MFR_42	0×FA	0x00	These bits al	ow the user to read/configure the device e output directly from the digital block on	's PWM switching frequence the pES[2:0] signal bus	y. The condition o	f	
up by Category MFR_44	0xFC	0x0201 🗸	ulese bits an	e output directly noin the digital block on	ure protz.oj signarbus			
VOUT_COMMAND	0x21	1. 199 🗘	DCAP3					
VOUT_MARGIN_HIGH	0×25	1. 199 🗘		s the user to read/configure the device's ne value of the pinstrap; but, can also be				
YOUT_MARGIN_LOW	0x26	1.199 🗘	output direct	ly from the digital block on the P_DCAP3 D-CAP3 mode is disabled. (VCSP-VCSN ra	signal			
YOUT_MODE	0x20	EXP -9	1: Internal D	O-CAP3 mode is enabled. (VCSP-VCSN ra	mp injection is enabled)			
WRITE_PROTECT	0×10	0x00 🗸						
▼ Manufacturer Info								
CAPABILITY	0x19	0xD0 🗸	0xD0	_				
▼ On/Off Configuration								
ON_OFF_CONFIG	0×02	0x17 🗸	0x17					
OPERATION	0×01	0x00 🗸	0x00					
Tips & Hints			PMB	us Log				
MFR_04 [0xD4] allows the user to configure the D-CAP offset red	uction and f	ixed offset correction		5:50.464: USB-SAA #1: CONTROL1 now 8:07.286: TPS549C20 @ 23d: MFR_03 [111b], RCSP:R ÷ 1	[01b], DCAP3:True [0x93] to RAI	4
Ionitor			~					
tatus			E PMB	us Log				(
Digital Power Designer v2.0.141 [2016-04-23] TPS549C20 @ PMBu	vs. Addross ?	24 (176)	January 1 0 10 1	N- DEC: 400 H =1			TEXAS INSTRUMENTS JUSIO	

Figure 26. Configure: Frequency- FS Config Pop-Up with Change



Fusion GUI

After making changes to one or more configurable parameters, the changes can be committed to nonvolatile memory by selecting *Store Config to NVM*. This action prompts a *confirm selection* pop-up, and if confirmed, the changes are committed to nonvolatile memory (Figure 27).

🕴 Fusion Digital Power (
File Device Tools	Help						TPS549C2	20 @ 23d (17h) - Rail #1	[
Configure	All Config								
Write to Hardware	Command	Code	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit	
Auto write on rail or device change	▼ Configuration				▼ Status				
Discard Changes	MFR_01 (PGOOD_DLY)	0xD1	PGD:102 🗸	0x12	STATUS_BYTE	0×78	00000010 🗸	0x02	
	MFR_02	0xD2	CM: Tru 🗸	0x13	STATUS_CML	0×7E	1000000 🗸	0x80	
Store Config to NVM	MFR_03	0xD3	FS:625k 🗸	0x93	STATUS_IOUT	0×7B	0000000 🗸	0x00	
Restore NVM Config	MFR_04	0xD4	DCAP3 🗸	0x80	STATUS_VOUT	0×7A	0000000 🗸	0x00	
Clear Restore Notices	MFR_06	0xD6	VDDUVL 🗸	0x05	STATUS_WORD	0×79	Click 🗸	0x0002	
Sort Parameters By:	MFR_07	0xD7	VTRKIN: 🗸	0x8F	▼ User Parameters				
Command Name	MFR_33	0xF1	0x00	0x00	MFR_00	0xD0	0x00	0x00	
O Command Code	MFR_42	0×FA	0x00	0x00					
Group by Category	MFR_44	0xFC	0x0201 🗸	0x0201					
	VOUT_COMMAND	0x21	1. 199 🐳 V	0x0266	-				
	YOUT_MARGIN_HIGH	0x25	1.199 🚔 V	0x0266		D			
	VOUT_MARGIN_LOW	Confirm	Store to Flash	1000	~				
	YOUT_MODE		This operation	will store all co	onfiguration values to flash				
	WRITE_PROTECT	4			PMBus Address 23d. Do you wish to				
	▼ Manufacturer Info		proceeus						
	CAPABILITY								
	▼ On/Off Configuration				Yes No				
	ON_OFF_CONFIG					9			
	OPERATION	0×01	0x00 🗸	0x00					
	Tips & Hints			PMBus I	•				ħ
	MFR_04 [0xD4] allows the user to configure the D-CAP o	ffset reduction and fi	xed offset correction	16:48:0	50.464: USB-SAA #1: CONTROL1 now Low 07.286: TPS549C20 @ 23d: MFR_03 [0xD3]: wro	ote FS:625kHz [()11b], RCSP:R ÷ 1 [0	01b], DCAP3:True [0x93] to	RAM
🌵 Configure	-			17:07:	11.499: TPS549C20 @ 23d: OPERATION [0x01]: 13.664: TPS549C20 @ 23d: OPERATION [0x01]:	wrote Unit: On; wrote Unit: Imr	Margin: None [0x80 nediateOff; Margin: N	l] to RAM None [0x00] to RAM	
🌵 Monitor				~					~
🚸 Status				PMBus	Log				Fa 🗑
Fusion Digital Power Desig	gner v2.0.141 [2016-04-23] TPS549C20 (@ PMBus Address 2	3d (17h) USB Ada	pter v1.0.10 [No	o PEC; 400 kHz]			TEXAS INSTRUMENTS	fusion digital power

Figure 27. Configure: Store Config to NVM



In the lower left corner, the different view screens can be changed. The view screens can be changed between *Configure*, *Monitor* and *Status* as needed (Figure 28).

nand onfiguration 01 (PG00D_DLY) 02 03	Code 0xD1	¥alue/Edit			
onfiguration 01 (PGOOD_DLY) 02		Value/Edit			
01 (PGOOD_DLY) 02	0xD1		Hex/Edi	Command Code Value/Edit Hex/Edit	
02	0×D1			▼ Status	
		PGD: 102 🗸	0x12	STATU5_BYTE 0x78 00000010 ☑ 0x02	
03	0xD2	CM: Tru 🗸	0x13	STATU5_CML 0x7E 10000000 ♥ 0x80	
03	0xD3	FS:625k 🗸	0x93	STATUS_IOUT 0x78 0000000 0x00	
<u>0</u> 4	0×D4	DCAP3 🗸	0x80	STATUS_VOUT 0x7A 00000000 ♥ 0x00	
.06	0xD6	VDDUVL 🗸	0x05	STATUS_WORD 0x79 Click 0x0002	
07	0xD7	VTRKIN: 🗸	0x8F	▼ User Parameters	
.33	0×F1	0x00	0x00	MFR_00 0x00 0x00 0x00	
.42	0×FA	0x00	0x00		
.44	0xFC	0x0201 🗸	0x0201		
_COMMAND	0x21	1.199 🔷 V	0x0266		
_MARGIN_HIGH	0x25	1.199 🐳 V	0x0266		
_MARGIN_LOW	0x26	1.199 🔷 V	0x0266		
_MODE	0x20	EXP -9			
E_PROTECT	0×10	0x00 🗸	0x00		
anufacturer Info					
BILITY	0×19	0xD0 🗸	0xD0		
n/Off Configuration					
FF_CONFIG	0×02	0x17 🗸	0x17		
ATION	0x01	0x00 🖂	0x00		
	07 33 42 44 44 MARGIN_HIGH MARGIN_HIGH MARGIN_LOW MODE E_PROTECT anufacturer Info BILITY n/Off Configuration FF_CONFIG	0x7 0x7 033 0x71 42 0x7A 44 0x7C COMMAND 0x21 MARGIN_HIGH 0x25 MARGIN_LOW 0x26 MODE 0x20 E_PROTECT 0x10 anufacturer Info 101 anufacturer Info 119 n/Off Configuration 119	0x07 0x07 YTRKIN:	07 0x07 VTRKIN:	07 0x07 VTRKUN:

Figure 28. Change View Screen to Monitor Screen



Fusion GUI

Selecting System Dashboard from mid-left screen adds a new window which displays system-level information (Figure 29).

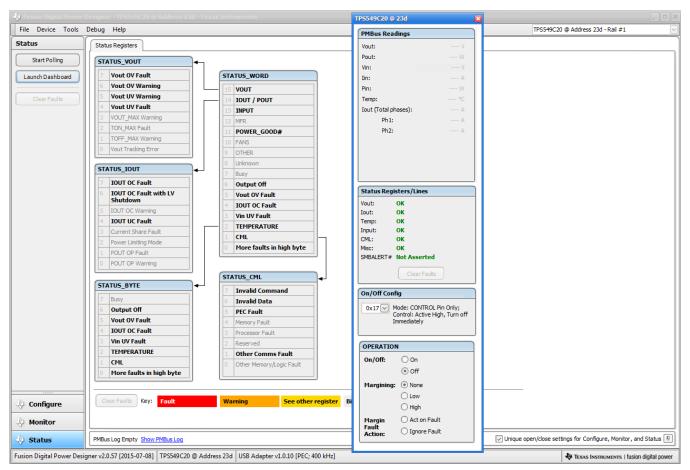


Figure 29. System Dashboard



Selecting Status from lower left corner shows the status of the controller (Figure 30).

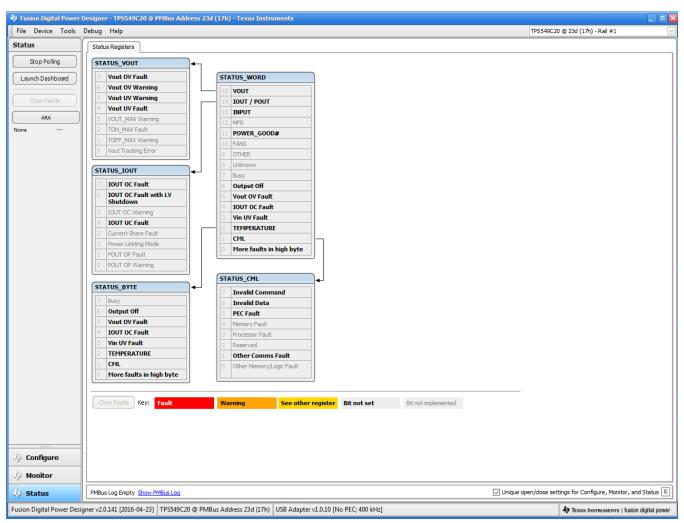


Figure 30. Status Screen



Fusion GUI

Selecting *Store User Configuration to Flash Memory* from the device pull-down menu has the same functionality as the *Store Config to NVM* button from the configure screen. It results in committing the current configuration to nonvolatile memory (Figure 31).

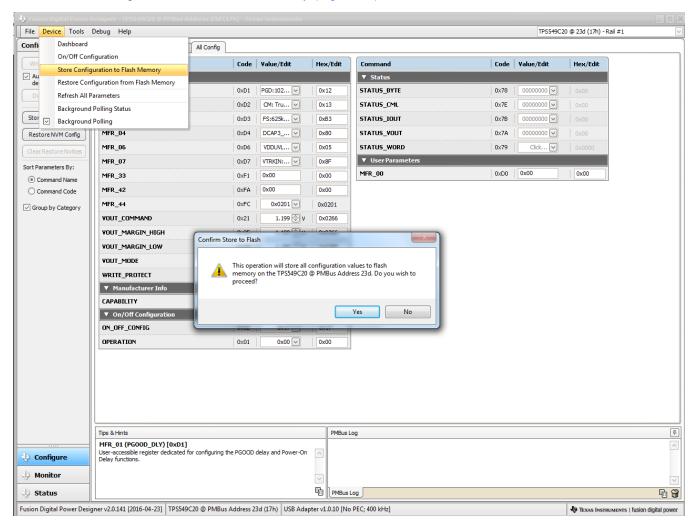


Figure 31. Store Configuration To Memory



Selecting *PMBus Logging* (Figure 32) from the Tools drop-down menu enables the logging of all PMBus activity. This includes communications traffic for each polling loop between the GUI and the device. The user is prompted to select a location for the file to be stored. See next screen (Figure 33).

ce chang ce chang ce chang card Cha config t config t config t		Code						
rite to Hard uto write or levice chang Siscard Char Discard Char Device Re Device Re Group Co	ogging	Code						
Auto write of device chang SMBus & Discard Cha Store Config t Group Co	SAA Tool	Lone	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit
device chang SMBus & Discard Cha Numeric Device Re Store Config t Group Co			value/Eult	nes/cuit	▼ Status	Code	Value/Eult	Hex/Cold
tore Config t Group Co	Encode/Decode Tester	0.04	202.402	0.40		0.70		
Store Config t Group Co		0xD1	PGD: 102 🗸	0x12	STATUS_BYTE	0x78	0000000	0x00
Group CC	ead/Write Stress Tester	0xD2	CM: Tru 🗸	0x13	STATUS_CML	0×7E	00000000 🗸	0x00
	ommand Protocol Tester	0xD3	FS:625k 🗸	0xB3	STATUS_IOUT	0x7B	0000000	0x00
Restore NVM Configura	ation Import Tester	0xD4	DCAP3 🗸	0x80	STATUS_VOUT	0×7A	00000000	0x00
ear Restore ASCII Too	bl	0xD6	VDDUVL 🖂	0x05	STATUS_WORD	0x79	Click 🗸	0x0000
EEPROM	File Tool	0xD7	VTRKIN: 🖂	0x8F	▼ User Parameters			
Command N	File Compare Tool	0xF1	0x00	0x00	MFR_00	0xD0	0x00	0x00
Command C PEC & SN	MBus -> I2C Translation Tool	0×FA	0x00	0x00				
Downloa	d USB Adapter Firmware	0xFC	0x0201 ~	0x0201				
Group by Category	IUT_COMMAND	0x1 C	1.199 🗘 V	0x0261				
	UT_MARGIN_HIGH	0x25	1. 199 🕀 V	0x0266				
VO	UT_MARGIN_LOW	0x26	1.199 😴 V	0x0266				
YO	IUT_MODE	0x20	EXP -9					
w	RITE_PROTECT	0×10	0x00 🗸	0x00				
	Manufacturer Info							
CA	PABILITY	0x19	0xD0 🗸	0xD0				
	On/Off Configuration							
ON	_OFF_CONFIG	0×02	0x17 🗸	0x17				
OP	ERATION	0x01	0x00 🗸	0x00				

Figure 32. PMBus Logging



Fusion GUI

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Select the storage location for the file and the type of file. As shown (Figure 33), the file is a CSV file to be stored in the directory path shown. Logging begins when the *Start Logging* button is selected, and stops when it is reselected (as *Stop Logging*). This file can rapidly grow in size, so caution is advised when using this function.

Debug Help						TPS549C	20 @ 23d (17h) - Ra			
Trim Commands Test Commands All Config										
Command	Code	Value/Edit	Hex/Edit	Command	Code	Value/Edit	Hex/Edit			
▼ Configuration				▼ Status						
MFR_01 (PG00D_DLY)	0xD1	PGD:102 🗸	0x12	12 STATUS_BYTE		00000000 🗸	0x00			
MFR_02	0xD2	CM: Tru 🗸	0x13	STATUS_CML	0×7E	00000000 🗸	0x00			
MFR_03	0xD3	FS:425k 🗸	0x91	STATUS_IOUT	0x7B	00000000 🗸	0x00			
MFR_04		Global PMBus Logg	jing		0×7A	00000000 🗸	0x00			
MFR_06		Overview			0x79	Click 🗸	0x0000			
MFR_07	d	etected. When PMBu	s logging has bee	s logging for all devices the GUI has n turned on, the result of every PMBus						
MFR_33		ead and write will be s			0xD0	0x00	0x00			
MFR_42	la	or dynamic parameters, only those which the GUI is currently polling will be ogged. This varies depending on whether you have background polling turned In and what task you are performing on a device. For example, when you are								
MFR_44	0	n the advanced confi								
VOUT_COMMAND		when the monitor scre	en is active, only	a subset are polied.						
VOUT_MARGIN_HIGH	5	Options	ave log file(s) to.	A unique filename is automatically						
VOUT_MARGIN_LOW		generated for each log file.								
VOUT_MODE	D	Directory: C:\Users\a0272935\Desktop\newey \Sword fish\Application Plan\PMBUS \FUSION GUI modifications								
WRITE_PROTECT										
▼ Manufacturer Info	F	File Format:								
CAPABILITY		Tab Separate								
▼ On/Off Configuration		Comma Separation	rated Value (CSV)							
ON_OFF_CONFIG		Always start PMBu (new file(s) will be								
OPERATION		,								
		Status Not logging								
		Start Logging OK								
		C		h.						
Tips & Hints			PMBus I	.og						
MFR_07 [0xD7]				54.760: TPS549C20 @ 23d: VOUT_COMMAND [0x2	1]: wrote 0.6	00 V [0x0133] to RA	M			
Allows user to read the configuration of various them. Note, that any overwritten values here a	e only good	until the next power-	14:13:	54.907: USB-SAA #1: CONTROL1 now Low 54.912: USB-SAA #1: CONTROL2 now Low 54.915: USB-SAA #1: CONTROL3 now Low						
on-reset; when all parameters will revert back to	their pinstra	p configurations	14:13:	94.915: USB-SAA #1: CONTROL3 now Low 54.919: USB-SAA #1: CONTROL4 now Low 54.921: USB-SAA #1: CONTROL5 now Low						
Ĺ			PMBus							

Figure 33. PMBus Log Details



EVM Assembly Drawing and PCB Layout

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13 EVM Assembly Drawing and PCB Layout

Figure 34 through Figure 43 show the design of the PWR-847EVM printed-circuit board (PCB). The PWR-847EVM has a 2-oz. copper finish for all layers.

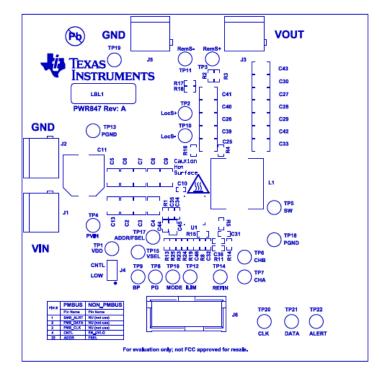


Figure 34. PWR-847EVM Top Layer Assembly Drawing (Top View)

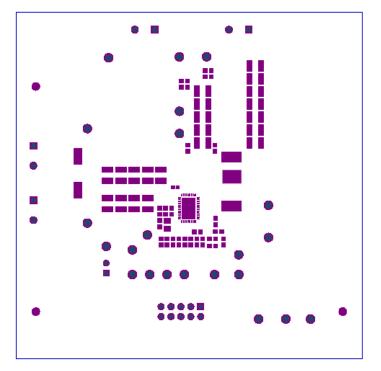


Figure 35. PWR-847EVM Top Solder Mask (Top View)



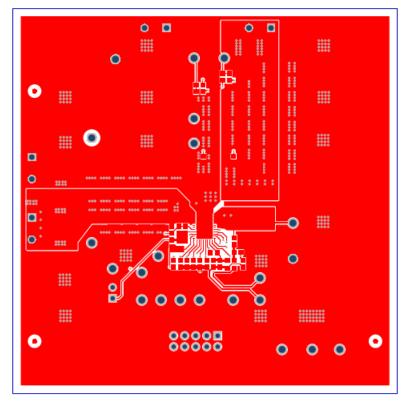


Figure 36. PWR-847EVM Top Layer (Top View)

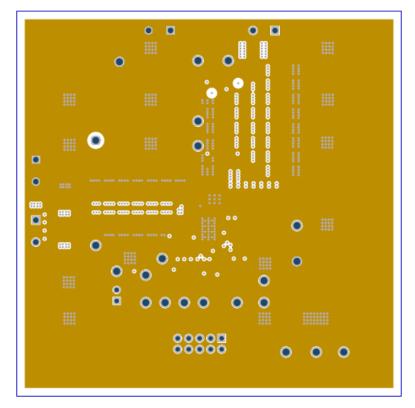


Figure 37. PWR-847EVM Inner Layer 1 (Top View)



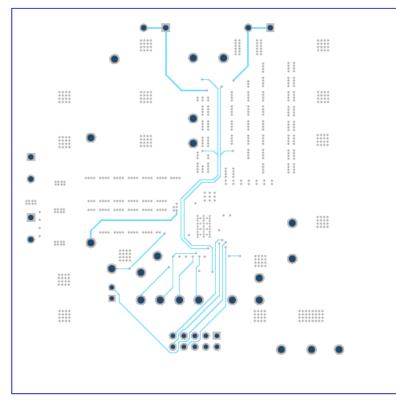
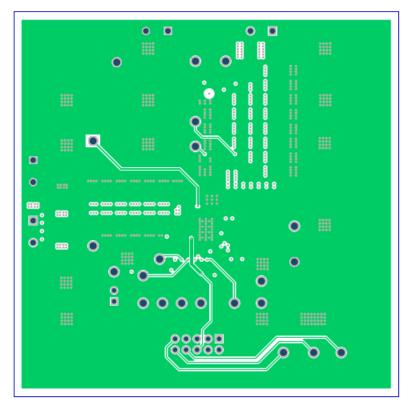


Figure 38. PWR-847EVM Inner Layer 2 (Top View)







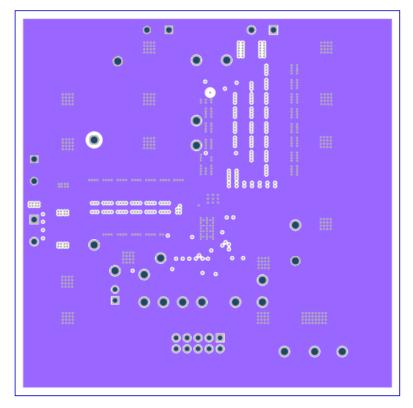


Figure 40. PWR-847EVM Inner Layer 4 (Top View)

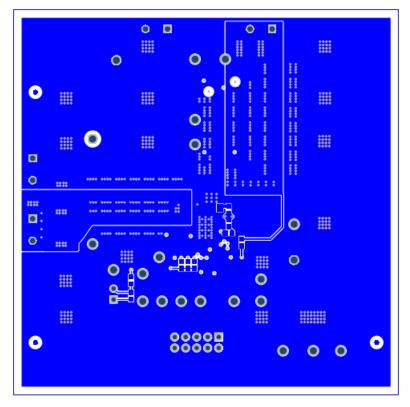


Figure 41. PWR-847EVM Bottom Layer (Top View)



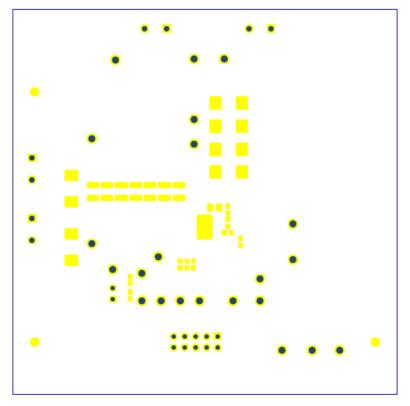
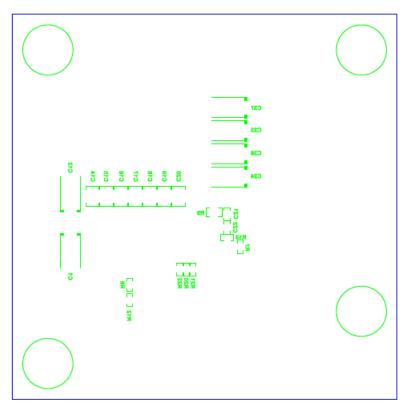


Figure 42. PWR-847EVM Bottom Solder Mask (Top View)







List of Materials

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14 List of Materials

The EVM components list, according to the schematic, is shown in Table 6.

Table 6. PWR847 List of Materials

Designator	Qty	Value	Description	Package Reference	Part Number	Manufacturer	Alternate Part Number	Alternate Manufacturer
!PCB1	1		Printed Circuit Board		PWR847	Any		
C2, C3, C4, C5, C6, C7, C8, C9, C13	9	22uF	CAP, CERM, 22 µF, 25 V, +/- 10%, X7R, 1210	1210	GRM32ER71E226KE15L	Murata		
C10	1	2200pF	CAP, CERM, 2200 pF, 25 V, +/- 10%, X5R, 0402	0402	GRM155R61E222KA01D	Murata		
C11	1	100uF	CAP, AL, 100uF, 35V, +/-20%, 0.15 ohm, SMD	SMT Radial G	EEE-FC1V101P	Panasonic		
C22	1	0.1uF	CAP, CERM, 0.1 µF, 50 V, +/- 10%, X7R, 0603	0603	GRM188R71H104KA93D	Murata		
C24, C38	2	470uF	CAP, Tantalum Polymer, 470 µF, 2.5 V, +/- 20%, 0.006 ohm, 7.3x2.8x4.3mm SMD	7.3x2.8x4.3mm	2R5TPF470M6L	Panasonic		
C25, C26, C29, C33, C39, C40, C42	7	100uF	CAP, CERM, 100 µF, 6.3 V, +/- 20%, X5R, 1210	1210	GRM32ER60J107ME20L	Murata		
C35	1	1uF	CAP, CERM, 1 µF, 16 V, +/- 10%, X5R, 0603	0603	C0603C105K4PACTU	Kemet		
C45	1	4.7uF	CAP, CERM, 4.7 μF, 16 V, +/- 10%, X7R, 0805	0805	GRM21BR71C475KA73L	Murata		
H9, H10, H11, H12	4		Bumpon, Hemisphere, 0.44 X 0.20, Clear	Transparent Bumpon	SJ-5303 (CLEAR)	3M		
J1, J2, J3, J5	4		TERMINAL BLOCK 5.08MM VERT 2POS, TH	TERM_BLK, 2pos, 5.08mm	ED120/2DS	On-Shore Technology		
J4	1		Header, 100mil, 2x1, Tin, TH	Header, 2 PIN, 100mil, Tin	PEC02SAAN	Sullins Connector Solutions		
J6	1		Header (shrouded), 100mil, 5x2, Gold, TH	5x2 Shrouded header	5103308-1	TE Connectivity		
L1	1	330nH	Inductor, Shielded Drum Core, Ferrite, 330 nH, 50 A, 0.000165 ohm, SMD	12.5x13mm	744309033	Wurth Elektronik		
LBL1	1		Thermal Transfer Printable Labels, 0.650" W x 0.200" H - 10,000 per roll	PCB Label 0.650"H x 0.200"W	THT-14-423-10	Brady		
R1	1	1.00	RES, 1.00, 1%, 0.1 W, 0603	0603	RC0603FR-071RL	Yageo America		
R4, R7, R10, R11, R16	5	0	RES, 0, 5%, 0.1 W, 0603	0603	CRCW06030000Z0EA	Vishay-Dale		
R6	1	200k	RES, 200 k, 1%, 0.1 W, 0603	0603	CRCW0603200KFKEA	Vishay-Dale		
R8	1	1.10k	RES, 1.10 k, 1%, 0.1 W, 0603	0603	CRCW06031K10FKEA	Vishay-Dale		
R12, R13, R20, R21, R22	5	100k	RES, 100 k, 1%, 0.1 W, 0603	0603	CRCW0603100KFKEA	Vishay-Dale		
R15	1	10.0k	RES, 10.0k ohm, 1%, 0.1W, 0603	0603	CRCW060310K0FKEA	Vishay-Dale		
R19	1	61.9k	RES, 61.9 k, 1%, 0.1 W, 0603	0603	CRCW060361K9FKEA	Vishay-Dale		
R23	1	37.4k	RES, 37.4 k, 1%, 0.1 W, 0603	0603	CRCW060337K4FKEA	Vishay-Dale		
R24	1	42.2k	RES, 42.2 k, 1%, 0.1 W, 0603	0603	CRCW060342K2FKEA	Vishay-Dale		
R25	1	25.5k	RES, 25.5 k, 1%, 0.1 W, 0603	0603	CRCW060325K5FKEA	Vishay-Dale		



Table 6. PWR847 List of Materials (continued)

Designator	Qty	Value	Description	Package Reference	Part Number	Manufacturer	Alternate Part Number	Alternate Manufacturer
TP1, TP5, TP6, TP7, TP8, TP9, TP12, TP14, TP15, TP16, TP17, TP20, TP21, TP22	14	White	Test Point, Multipurpose, White, TH	White Multipurpose Testpoint	5012	Keystone		
TP2, TP3, TP4	3	Red	Test Point, Multipurpose, Red, TH	Red Multipurpose Testpoint	5010	Keystone		
TP10, TP11, TP13, TP18, TP19	5	Black	Test Point, Multipurpose, Black, TH	Black Multipurpose Testpoint	5011	Keystone		
U1	1		1.5-V to 16-V VIN, 4.5-V to 22-V VDD, 25-A SWIFT Synchronous Step-Down Converter with Full Differential Sense, RVF0040A (LQFN-CLIP-40)	RVF0040A	TPS549B22RVFR	Texas Instruments	TPS549B22RVFT	Texas Instruments
C1, C12	0	330uF	CAP, TA, 330 µF, 6.3 V, +/- 20%, 0.025 ohm, SMD	7.3x2.8x4.3mm	6TPE330ML	Sanyo		
C14, C15, C16, C17, C18, C19, C20	0	22uF	CAP, CERM, 22 µF, 25 V, +/- 10%, X7R, 1210	1210	GRM32ER71E226KE15L	Murata		
C21	0	470pF	CAP, CERM, 470 pF, 50 V, +/- 10%, X7R, 0603	0603	GRM188R71H471KA01D	Murata		
C23, C37	0	470uF	CAP, Tantalum Polymer, 470 µF, 2.5 V, +/- 20%, 0.006 ohm, 7.3x2.8x4.3mm SMD	7.3x2.8x4.3mm	2R5TPF470M6L	Panasonic		
C27, C28, C30, C41, C43	0	100uF	CAP, CERM, 100 µF, 6.3 V, +/- 20%, X5R, 1210	1210	GRM32ER60J107ME20L	Murata		
C31	0	0.1uF	CAP, CERM, 0.1 μF, 50 V, +/- 10%, X7R, 0603	0603	GRM188R71H104KA93D	Murata		
C32	0	6800pF	CAP, CERM, 6800 pF, 50 V, +/- 10%, X7R, 0603	0603	GRM188R71H682KA01D	Murata		
C34, C44	0	1uF	CAP, CERM, 1 µF, 16 V, +/- 10%, X5R, 0603	0603	C0603C105K4PACTU	Kemet		
C36	0	1000pF	CAP, CERM, 1000 pF, 25 V, +/- 10%, X7R, 0603	0603	GRM188R71E102KA01D	Murata		
C46	0	1000pF	CAP, CERM, 1000 pF, 50 V, +/- 5%, C0G/NP0, 0603	0603	C0603C102J5GACTU	Kemet		
FID1, FID2, FID3, FID4, FID5, FID6	0		Fiducial mark. There is nothing to buy or mount.	Fiducial	N/A	N/A		
R2, R3, R14, R17, R18	0	0	RES, 0, 5%, 0.1 W, 0603	0603	CRCW06030000Z0EA	Vishay-Dale		
R5	0	1.50k	RES, 1.50 k, 1%, 0.1 W, 0603	0603	RC0603FR-071K5L	Yageo America		
R9	0	3.01	RES, 3.01 ohm, 1%, 0.125W, 0805	0805	CRCW08053R01FKEA	Vishay-Dale		
	Notes:	Unless of	therwise noted in the Alternate Part Number or Alterna	te Manufacturer column	s, all parts may be substituted w	ith equivalents.		1

STANDARD TERMS FOR EVALUATION MODULES

- 1. Delivery: TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, and/or documentation which may be provided together or separately (collectively, an "EVM" or "EVMs") to the User ("User") in accordance with the terms set forth herein. User's acceptance of the EVM is expressly subject to the following terms.
 - 1.1 EVMs are intended solely for product or software developers for use in a research and development setting to facilitate feasibility evaluation, experimentation, or scientific analysis of TI semiconductors products. EVMs have no direct function and are not finished products. EVMs shall not be directly or indirectly assembled as a part or subassembly in any finished product. For clarification, any software or software tools provided with the EVM ("Software") shall not be subject to the terms and conditions set forth herein but rather shall be subject to the applicable terms that accompany such Software
 - 1.2 EVMs are not intended for consumer or household use. EVMs may not be sold, sublicensed, leased, rented, loaned, assigned, or otherwise distributed for commercial purposes by Users, in whole or in part, or used in any finished product or production system.
- 2 Limited Warranty and Related Remedies/Disclaimers:
 - 2.1 These terms do not apply to Software. The warranty, if any, for Software is covered in the applicable Software License Agreement.
 - 2.2 TI warrants that the TI EVM will conform to TI's published specifications for ninety (90) days after the date TI delivers such EVM to User. Notwithstanding the foregoing, TI shall not be liable for a nonconforming EVM if (a) the nonconformity was caused by neglect, misuse or mistreatment by an entity other than TI, including improper installation or testing, or for any EVMs that have been altered or modified in any way by an entity other than TI, (b) the nonconformity resulted from User's design, specifications or instructions for such EVMs or improper system design, or (c) User has not paid on time. Testing and other quality control techniques are used to the extent TI deems necessary. TI does not test all parameters of each EVM. User's claims against TI under this Section 2 are void if User fails to notify TI of any apparent defects in the EVMs within ten (10) business days after delivery, or of any hidden defects with ten (10) business days after the defect has been detected.
 - 2.3 TI's sole liability shall be at its option to repair or replace EVMs that fail to conform to the warranty set forth above, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.
- 3 Regulatory Notices:

3.1 United States

3.1.1 Notice applicable to EVMs not FCC-Approved:

FCC NOTICE: This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

3.1.2 For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

- 3.3 Japan
 - 3.3.1 Notice for EVMs delivered in Japan: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page 日本国内に 輸入される評価用キット、ボードについては、次のところをご覧ください。 http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_01.page
 - 3.3.2 Notice for Users of EVMs Considered "Radio Frequency Products" in Japan: EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

- 1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
- 2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
- 3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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- 2. 実験局の免許を取得後ご使用いただく。
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- 3.3.3 Notice for EVMs for Power Line Communication: Please see http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page 電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧ください。http://www.tij.co.jp/lsds/ti_ja/general/eStore/notice_02.page
- 3.4 European Union
 - 3.4.1 For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive):

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

- 4 EVM Use Restrictions and Warnings:
 - 4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.
 - 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
 - 4.3 Safety-Related Warnings and Restrictions:
 - 4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.
 - 4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.
 - 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
- Accuracy of Information: To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.

6. Disclaimers:

- 6.1 EXCEPT AS SET FORTH ABOVE, EVMS AND ANY MATERIALS PROVIDED WITH THE EVM (INCLUDING, BUT NOT LIMITED TO, REFERENCE DESIGNS AND THE DESIGN OF THE EVM ITSELF) ARE PROVIDED "AS IS" AND "WITH ALL FAULTS." TI DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, REGARDING SUCH ITEMS, INCLUDING BUT NOT LIMITED TO ANY EPIDEMIC FAILURE WARRANTY OR IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF ANY THIRD PARTY PATENTS, COPYRIGHTS, TRADE SECRETS OR OTHER INTELLECTUAL PROPERTY RIGHTS.
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 - 8.2 Specific Limitations. IN NO EVENT SHALL TI'S AGGREGATE LIABILITY FROM ANY USE OF AN EVM PROVIDED HEREUNDER, INCLUDING FROM ANY WARRANTY, INDEMITY OR OTHER OBLIGATION ARISING OUT OF OR IN CONNECTION WITH THESE TERMS, EXCEED THE TOTAL AMOUNT PAID TO TI BY USER FOR THE PARTICULAR EVM(S) AT ISSUE DURING THE PRIOR TWELVE (12) MONTHS WITH RESPECT TO WHICH LOSSES OR DAMAGES ARE CLAIMED. THE EXISTENCE OF MORE THAN ONE CLAIM SHALL NOT ENLARGE OR EXTEND THIS LIMIT.
- 9. Return Policy. Except as otherwise provided, TI does not offer any refunds, returns, or exchanges. Furthermore, no return of EVM(s) will be accepted if the package has been opened and no return of the EVM(s) will be accepted if they are damaged or otherwise not in a resalable condition. If User feels it has been incorrectly charged for the EVM(s) it ordered or that delivery violates the applicable order, User should contact TI. All refunds will be made in full within thirty (30) working days from the return of the components(s), excluding any postage or packaging costs.
- 10. Governing Law: These terms and conditions shall be governed by and interpreted in accordance with the laws of the State of Texas, without reference to conflict-of-laws principles. User agrees that non-exclusive jurisdiction for any dispute arising out of or relating to these terms and conditions lies within courts located in the State of Texas and consents to venue in Dallas County, Texas. Notwithstanding the foregoing, any judgment may be enforced in any United States or foreign court, and TI may seek injunctive relief in any United States or foreign court.

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