











TPS25940A, TPS25940L

SLVSCF3A - JUNE 2014-REVISED MARCH 2015

# TPS25940x 2.7 – 18V eFuse with True Reverse Blocking and DevSleep Support for SSDs

#### Features

- 2.7 V 18 V Operating Voltage, 20 V (Max)
- 42 mΩ R<sub>ON</sub> (Typical)
- 0.6 A to 5.3 A Adjustable Current Limit (±8%)
- IMON Current Indicator Output (±8%)
- 200 μA Operating I<sub>O</sub> (Typical)
- 95 μA DevSleep Mode I<sub>Q</sub> (Typical)
- 15 μA Disabled I<sub>O</sub> (Typical)
- ±2% Overvoltage, Undervoltage Threshold
- Reverse Current Blocking
- 1 µs Reverse Voltage Shutoff
- Programmable dV<sub>o</sub>/dt Control
- Power Good and Fault Outputs
- -40°C to 125°C Junction Temperature Range
- UL 2367 Recognized
  - File No. 169910
  - R<sub>ILIM</sub> ≥ 20 kΩ (4.81 A max)
- UL60950 Safe during Single Point Failure Test
  - Open/Short ILIM detection

# 2 Applications

- PCIe/SATA/SAS HDD and SSD Drives
- **Enterprise and Micro Servers**
- Smart Load Switch
- Set-Top-Box (STB), DTVs and Game Consoles
- RAID Cards Holdup Power Management
- Telecom Switches and Routers
- Adapter Powered Devices

### 3 Description

The TPS25940 eFuse Power Switch is a compact, feature rich power management device with a full suite of protection functions, including a low power DevSleep™ mode that supports compliance with the SATA™ Device Sleep standard. The wide operating range allows control of many popular DC bus voltages. Integrated back to back FETs provide bidirectional current control making the device well suited for systems with load side holdup energy that must not drain back to a failed supply bus.

Load, source and device protection are provided with many programmable features including overcurrent, dV<sub>o</sub>/dt ramp and overvoltage, undervoltage thresholds. For system status monitoring and downstream load control, the device provides PGOOD, FLT and precise current monitor output. Precise programmable undervoltage, overvoltage thresholds and the low IQ DevSleep mode simplify SSD power management design.

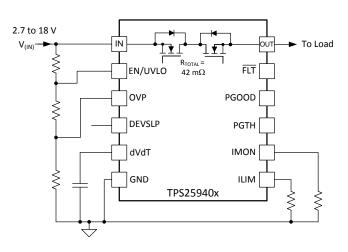
The TPS25940 monitors  $V_{(IN)}$  and  $V_{(OUT)}$  to provide true reverse current blocking when  $V_{(IN)} < (V_{(OUT)} - 10)$ mV). This function supports swift changeover to a boosted voltage energy storage element in systems where backup voltage is greater than bus voltage.

### Device Information<sup>(1)</sup>

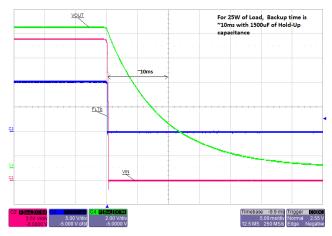
PART NUMBER(2)	PACKAGE	BODY SIZE (NOM)
TPS25940A	WOEN (20)	3.00 mm x 4.00 mm
TPS25940L	WQFN (20)	3.00 mm x 4.00 mm

- (1) For all available packages, see the orderable addendum at the end of the datasheet.
- (2) TPS25940L = Latched, TPS25940A = Auto Retry

# Simplified Schematic



### Power Fail Detection and Blocking





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# 5 Revision History

# Changes from Original (June 2014) to Revision A

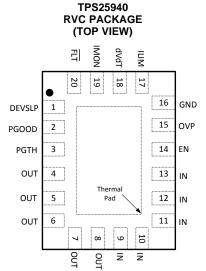
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•	Changed Features From: UL2367 Recognition Pending To: UL 2367 Recognized, $R_{ILIM} \ge 20 \text{ k}\Omega$ (4.81 A max), File No. 169910	1
•	Moved the Storage Temperature From the Handling Ratings table To Absolute Maximum Ratings table	4
•	Changed the Handling Ratings table To: ESD Ratings table	4
•	Added Test Condition to $I_{(LIM)}$ : " $R_{(ILIM)} = 20 \text{ k}\Omega$ " in the <i>Electrical Characteristics</i>	5
•	Changed Figure 24.	10
•	Added condition $R_{(ILIM)} = 17.8 \text{ k}\Omega$ to Figure 40 and Figure 41	13
•	Changed Figure 43	17
•	Changed Equation 6 to include I <sub>(IMON_OS)</sub>	21
	Added the NOTE to Application and Implementation	
•	Added Note to Figure 57	28
	Changed Equation 35 From: V <sub>(IN)</sub> x I <sub>(LOAD)</sub> To: V <sub>(IN)</sub> + I <sub>(LOAD)</sub>	

Submit Documentation Feedback



# 6 Pin Configuration and Functions



### **Pin Functions**

NAME	NO.	1/0	DESCRIPTION
DEVSLP	1	- 1	Active High. DevSleep Mode control. A high at this pin will activate the DevSleep mode(Low Power Mode).
PGOOD	2	0	Active High. A high indicates PGTH has crossed the threshold value. It is an open drain output.
PGTH	3	- 1	Positive input of PGOOD comparator.
OUT	4 - 8	0	Power Output of the device.
IN	9 - 13	- 1	Power Input and supply voltage of the device.
EN/UVLO	14	I	Input for setting programmable undervoltage lockout threshold. An undervoltage event will open internal FET and assert FLT to indicate power-failure. When pulled to GND, resets the fault latch in TPS25940L.
OVP	15	I	Input for setting programmable overvoltage protection threshold. An overvoltage event will open the internal FET and assert FLT to indicate overvoltage.
GND	16	_	Ground.
ILIM	17	I/O	A resistor from this pin to GND sets the overload and short-circuit current limit.
dVdT	18	I/O	A capacitor from this pin to GND sets the ramp rate of output voltage.
IMON	19	0	This pin sources a scaled down ratio of current through the internal FET. A resistor from this pin to GND converts current to proportional voltage, used as analog current monitor.
FLT	20	0	Fault event indicator, goes low to indicate fault condition due to Undervoltage, Overvoltage, Reverse voltage and Thermal shutdown event. It is an open drain output.
PowerPAD <sup>TM</sup>			The GND terminal must be connected to the exposed PowerPAD. This PowerPAD must be connected to a PCB ground plane using multiple vias for good thermal performance.



# 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating temperature range (unless otherwise noted) (1)

		VALU	VALUE	
		MIN	MAX	UNIT
	IN, OUT, PGTH, PGOOD, EN/UVLO, OVP, DEVSLP, FLT	-0.3	20	
Input voltage range	IN (10 ms Transient)		22	V
	dVdT, ILIM	-0.3	3.6	V
	IMON	-0.3	7	
Sink current	PGOOD, FLT, dVdT		10	mA
Source current	dVdT, ILIM, IMON	Internally L	_imited	
Maximum junction, T <sub>J</sub>		-40	150	°C
Storage temperature range, T <sub>stg</sub>		-65	150	°C
Continuous power dissipa	tion	See the Thermal Characteristics		

Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

			VALUE	UNIT
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	±2000	
V <sub>ESD</sub>	Electrostatic discharge	Charged device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	V

JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Input voltage range	IN	2.7		18	
	EN/UVLO, OVP, DEVSLP, OUT, PGTH, PGOOD, FLT	0		18	V
	dVdT, ILIM	0		3	V
	IMON	0		6	
Resistance  External capacitance	ILIM	16.9		150	rO.
	IMON	1			kΩ
External capacitance	OUT	0.1			μF
	dVdT			470	nF
Operating junction ten	nperature range, T <sub>J</sub>	-40	25	125	°C

### 7.4 Thermal Characteristics(1)

	THEOMAL METRIC	TPS25940	LINUT
	THERMAL METRIC	RVC (20) PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	38.1	
$R_{\theta JCtop}$	Junction-to-case (top) thermal resistance	40.5	
$R_{\theta JB}$	Junction-to-board thermal resistance	13.6	00 111
$\Psi_{JT}$	Junction-to-top characterization parameter	0.6	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	13.7	
$R_{\theta JCbot}$	Junction-to-case (bottom) thermal resistance	3.4	

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



### 7.5 Electrical Characteristics

Conditions are  $-40^{\circ}\text{C} \le \text{T}_J = \text{T}_A \le 125^{\circ}\text{C}$ ,  $2.7 \text{ V} \le \text{V}_{(IN)} = 18 \text{ V}$ ,  $\text{V}_{(EN/UVLO)} = 2 \text{ V}$ ,  $\text{V}_{(OVP)} = \text{V}_{(DEVSLP)} = \text{V}_{(PGTH)} = 0 \text{ V}$ ,  $\text{R}_{(ILIM)} = 150 \text{ k}\Omega$ ,  $\text{C}_{(OUT)} = 1 \text{ } \mu\text{F}$ ,  $\text{C}_{(dVdT)} = \text{OPEN}$ , PGOOD =  $\overline{\text{FLT}} = \text{IMON} = \text{OPEN}$ . Positive current into terminals. All voltages referenced to GND (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY VOLT	AGE AND INTERNAL UNDERVOLTAG	E LOCKOUT				
$V_{(IN)}$	Operating Input Voltage		2.7		18	V
$V_{(UVR)}$	Internal UVLO threshold, rising		2.2	2.3	2.4	V
V <sub>(UVRhys)</sub>	Internal UVLO hysteresis		105	116	125	mV
		$V_{(EN/UVLO)} = 2 \text{ V}, V_{(IN)} = 3 \text{ V}$	140	210	300	
$I_{Q(ON)}$	Supply current, Enabled	$V_{(EN/UVLO)} = 2 \text{ V}, V_{(IN)} = 12 \text{ V}$	140	199	260	μΑ
		$V_{(EN/UVLO)} = 2 \text{ V}, V_{(IN)} = 18 \text{ V}$	140	202	270	
		$V_{(EN/UVLO)} = 0 V, V_{(IN)} = 3 V$	4	8.6	15	
$I_{Q(OFF)}$	Supply current, Disabled	$V_{(EN/UVLO)} = 0 \text{ V}, V_{(IN)} = 12 \text{ V}$	6	15	20	μΑ
		$V_{(EN/UVLO)} = 0 \text{ V}, V_{(IN)} = 18 \text{ V}$	8	18.5	25	
I <sub>Q(DEVSLP)</sub>	Supply current, DevSleep Mode	V <sub>(DEVSLP)</sub> = 0 V, V <sub>(IN)</sub> = 2.7V to 18V	70	95	130	μΑ
ENABLE AND	UNDERVOLTAGE LOCKOUT (EN/UVL	O) INPUT			,	
$V_{(ENR)}$	EN/UVLO threshold voltage, rising		0.97	0.99	1.01	V
V <sub>(ENF)</sub>	EN/UVLO threshold voltage, falling		0.9	0.92	0.94	V
V <sub>(SHUTF)</sub>	EN threshold voltage for Low I <sub>Q</sub> shutdown, falling		0.3	0.47	0.63	V
V <sub>(SHUTFhys)</sub>	EN hysteresis for low I <sub>Q</sub> shutdown, hysteresis <sup>(1)</sup>			66		mV
I <sub>EN</sub>	EN Input leakage current	0 V ≤ V <sub>(EN/UVLO)</sub> ≤ 18 V	-100	0	100	nA
OVER VOLTAG	GE PROTECTION (OVP) INPUT				,	
V <sub>(OVPR)</sub>	Overvoltage Threshold Voltage, Rising,		0.97	0.99	1.01	٧
V <sub>(OVPF)</sub>	Overvoltage Threshold Voltage, Falling		0.9	0.92	0.94	٧
I <sub>(OVP)</sub>	OVP Input Leakage Current	0 V ≤ V <sub>(OVP)</sub> ≤ 5 V	-100	0	100	nA
DEVSLP MODI	E INPUT (DEVSLP): ACTIVE HIGH				,	
V <sub>(DEVSLPR)</sub>	DEVSLP threshold voltage, rising		1.6	1.85	2	V
V <sub>(DEVSLPF)</sub>	DEVSLP threshold voltage, falling		0.8	0.96	1.1	V
I <sub>(DEVSLP)</sub>	DEVSLP input leakage current	0.2 V ≤ V <sub>(DEVSLP)</sub> ≤ 18 V	0.6	1	1.25	μΑ
OUTPUT RAMI	P CONTROL (dVdT)		1		'	
I <sub>(dVdT)</sub>	dVdT charging current	$V_{(dVdT)} = 0 V$	0.85	1	1.15	μΑ
R <sub>(dVdT)</sub>	dVdT discharging resistance	EN/UVLO = 0 V, I <sub>(dVdT)</sub> = 10 mA sinking		16	24	Ω
V <sub>(dVdTmax)</sub>	dVdT maximum capacitor voltage		2.6	2.88	3.1	V
GAIN <sub>(dVdT)</sub>	dVdT to OUT gain	$\Delta V_{(OUT)}/\Delta V_{(dVdT)}$	11.65	11.9	12.05	V/V
	IT PROGRAMMING (ILIM)					
V <sub>(ILIM)</sub>	ILIM bias voltage			0.87		V
		$R_{(ILIM)} = 150 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	0.53	0.58	0.63	
		$R_{(ILIM)} = 88.7 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	0.9	0.99	1.07	
		$R_{(ILIM)} = 42.2 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	1.92	2.08	2.25	
		$R_{(ILIM)} = 24.9 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	3.25	3.53	3.81	
I <sub>(LIM)</sub>	Current limit (2)	$R_{(ILIM)} = 20 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	4.09	4.45	4.81	Α
-(LIVI)		$R_{(ILIM)} = 16.9 \text{ k}\Omega, (V_{(IN)} - V_{(OUT)}) = 1 \text{ V}$	4.78	5.2	5.62	,,
		R <sub>(ILIM)</sub> = OPEN, Open resistor current limit (Single Point Failure Test: UL60950)	0.35	0.45	0.55	
		R <sub>(ILIM)</sub> = SHORT, Shorted resistor current limit (Single Point Failure Test: UL60950)	0.55	0.67	0.8	
I <sub>(DEVSLP(LIM))</sub>	DevSleep Mode Current Limit	·	0.55	0.67	0.8	Α

<sup>(1)</sup> These parameters are provided for reference only and do not constitute part of TI's published device specifications for purposes of TI's product warranty.

<sup>(2)</sup> Pulse-testing techniques maintain junction temperature close to ambient temperature. Thermal effects must be taken into account separately.



# **Electrical Characteristics (continued)**

Conditions are  $-40^{\circ}\text{C} \le \text{T}_J = \text{T}_A \le 125^{\circ}\text{C}$ ,  $2.7 \text{ V} \le \text{V}_{(IN)} = 18 \text{ V}$ ,  $\text{V}_{(EN/UVLO)} = 2 \text{ V}$ ,  $\text{V}_{(OVP)} = \text{V}_{(DEVSLP)} = \text{V}_{(PGTH)} = 0 \text{ V}$ ,  $\text{R}_{(ILIM)} = 150 \text{ k}\Omega$ ,  $\text{C}_{(OUT)} = 1 \text{ µF}$ ,  $\text{C}_{(dVdT)} = \text{OPEN}$ , PGOOD = FLT = IMON = OPEN. Positive current into terminals. All voltages referenced to GND (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		$R_{\text{(ILIM)}} = 42.2 \text{ k}\Omega, V_{\text{(VIN)}} = 12 \text{ V}, (V_{\text{(IN)}} - V_{\text{(OUT)}}) = 5 \text{ V}$	1.91	2.07	2.24	
Ios	Short-circuit current limit (2)	$R_{(ILIM)} = 24.9 \text{ k}\Omega, V_{(VIN)} = 12 \text{ V}, (V_{(IN)} - V_{(OUT)}) = 5 \text{ V}$	3.21	3.49	3.77	Α
OS	Griori circuit current iirint	$ \hline R_{(ILIM)} = 16.9 \; k\Omega, \; V_{(VIN)} = 12 \; V, \; (V_{(IN)} \; \text{-V}_{(OUT)}) = 5 \; V, \; \text{-40} ^{\circ} C \leq T_J \leq 85 ^{\circ} C \\ \hline $	4.7	5.11	5.52	Α,
I <sub>(FASTRIP)</sub>	Fast-Trip comparator threshold <sup>(1)(2)</sup>			1.5 x I <sub>(LIM)</sub> + 0.375		Α
CURRENT M	ONITOR OUTPUT (IMON)					
GAIN <sub>(IMON)</sub>	Gain Factor I <sub>(IMON)</sub> :I <sub>(OUT)</sub>	1 A ≤ I <sub>(OUT)</sub> ≤ 5 A	47.78	52.3	57.23	μA/A
MOSFET - P	OWER SWITCH					
R <sub>ON</sub>	IN to OUT - ON Resistance	1 A ≤ I <sub>(OUT)</sub> ≤ 5 A, T <sub>J</sub> = 25°C	34	42	49	
		1 A ≤ I <sub>(OUT)</sub> ≤ 5 A, -40°C ≤ T <sub>J</sub> ≤ 85°C	26	42	58	$m\Omega$
		1 A ≤ I <sub>(OUT)</sub> ≤ 5 A, -40°C ≤ T <sub>J</sub> ≤ 125°C	26	42	64	
PASS FET O	UTPUT (OUT)					
_	OUT lastes as surrent in all state	$V_{(IN)} = 18 \text{ V}, V_{(EN/UVLO)} = 0 \text{ V}, V_{(OUT)} = 0 \text{ V (Sourcing)}$	-2	0	2	
I <sub>lkg(OUT)</sub>	OUT leakage current in off state	V <sub>(IN)</sub> = 2.7 V, V <sub>(EN/UVLO)</sub> = 0 V, V <sub>(OUT)</sub> = 18 V (Sinking)	6	13	20	μA
V <sub>(REVTH)</sub>	V <sub>(IN)</sub> -V <sub>(OUT)</sub> threshold for reverse protection comparator, falling		-15	-9.3	-3	mV
V <sub>(FWDTH)</sub>	V <sub>(IN)</sub> -V <sub>(OUT)</sub> threshold for reverse protection comparator, rising		86	100	114	mV
FAULT FLAG	(FLT): ACTIVE LOW					
R <sub>(FLT)</sub>	FLT internal pull-down resistance	$V_{(OVP)} = 2 \text{ V}, I_{\overline{(FLT)}} = 5 \text{ mA sinking}$	10	18	30	Ω
I <sub>(FLT)</sub>	FLT input leakage current	0 V ≤ V <sub>(FLT)</sub> ≤ 18 V	-1	0	1	μA
POSITIVE INI	PUT for POWER-GOOD COMPARATOR	(PGTH)				
V <sub>(PGTHR)</sub>	PGTH threshold voltage, rising		0.97	0.99	1.01	V
V <sub>(PGTHF)</sub>	PGTH threshold voltage, falling		0.9	0.92	0.94	V
I <sub>(PGTH)</sub>	PGTH input leakage current	0 V ≤ V <sub>(PGTH)</sub> ≤ 18 V	-100	0	100	nA
POWER-GOO	DD COMPARATOR OUTPUT (PGOOD):	ACTIVE HIGH				
R <sub>(PGOOD)</sub>	PGOOD internal pull-down resistance	V <sub>(PGTH)</sub> = 0V, I <sub>(PGOOD)</sub> = 5 mA sinking	10	20	35	Ω
I <sub>(PGOOD)</sub>	PGOOD input leakage current	0 V ≤ V <sub>(PGOOD)</sub> ≤ 18 V	-1	0	1	μA
THERMAL SH	HUT DOWN (TSD)				•	
T <sub>(TSD)</sub>	TSD Threshold <sup>(1)</sup>			160		°C
T <sub>(TSDhys)</sub>	TSD Hysteresis <sup>(1)</sup>			12		°C
	T. 15 10 (1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TPS25940L		LATCHED		
	Thermal Fault: (Latched or Auto- Retry)	TPS25940A		AUTO- RETRY		



# 7.6 Timing Requirements

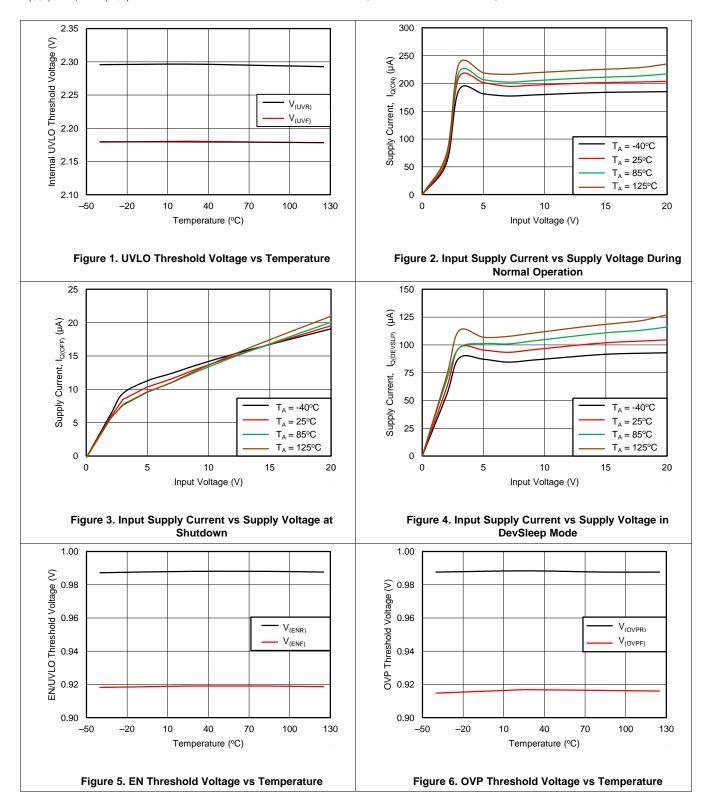
Conditions are  $-40^{\circ}\text{C} \le \text{T}_J = \text{T}_A \le 125^{\circ}\text{C}$ ,  $2.7 \text{ V} \le \text{V}_{(IN)} = 18 \text{ V}$ ,  $\text{V}_{(EN/UVLO)} = 2 \text{ V}$ ,  $\text{V}_{(OVP)} = \text{V}_{(DEVSLP)} = \text{V}_{(PGTH)} = 0 \text{ V}$ ,  $\text{R}_{(ILIM)} = 150 \text{ k}\Omega$ ,  $\text{C}_{(OUT)} = 1 \text{ } \mu\text{F}$ ,  $\text{C}_{(dVdT)} = \text{OPEN}$ , PGOOD = FLT = IMON = OPEN. Positive current into terminals. All voltages referenced to GND (unless otherwise noted). Refer to Figure 42 for the timing diagrams.

PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
LO INPUT				
EN Aura de delevi	EN/UVLO $\uparrow$ (100mV above V <sub>(ENR)</sub> ) to V <sub>(OUT)</sub> = 100 mV, $C_{(dVdT)}$ < 0.8 nF	220		μs
EN turn on delay	EN/UVLO $\uparrow$ (100mV above V <sub>(ENR)</sub> ) to V <sub>(OUT)</sub> = 100 mV, C <sub>(dVdT)</sub> $\geq$ 0.8 nF, [C <sub>(dVdT)</sub> in nF]	100 + 150 x C <sub>(dVdT)</sub>		μs
EN turn off delay	EN/UVLO $\downarrow$ (100mV below V <sub>(ENF)</sub> ) to $\overline{\text{FLT}}\downarrow$	2		μs
PROTECTION INPUT (OVP)				
OVP disable delay	OVP↑ (100mV above V <sub>(OVPR)</sub> ) to FLT↓	2		μs
CONTROL (dV/dT )				
	EN/UVLO $\uparrow$ to V <sub>(OUT)</sub> = 4.5 V, with C <sub>(dVdT)</sub> = open	0.12		
Output ramp time	EN/UVLO $\uparrow$ to $V_{(OUT)} = 11 \text{ V}$ , with $C_{(dVdT)} = \text{open}$	0.25 0.37	0.5	ms
	EN/UVLO $\uparrow$ to $V_{(OUT)} = 11 \text{ V}$ , with $C_{(dVdT)} = 1 \text{ nF}$	0.97		
Fast-Trip comparator delay	$I_{(OUT)} > I_{(FASTRIP)}$	200		ns
ECTION COMPARATOR				
	$(V_{(IN)} - V_{(OUT)})\downarrow (1 \text{ mV overdrive below } V_{(REVTH)}) \text{ to } \overline{FLT}\downarrow$	10		
·	$(V_{(IN)} - V_{(OUT)})\downarrow (10 \text{ mV overdrive below } V_{(REVTH)}) \text{ to } \overline{FLT}\downarrow$	1		μs
	$(V_{(IN)} - V_{(OUT)})\uparrow$ (10 mV overdrive above $V_{(FWDTH)}$ ) to $\overline{FLT}\uparrow$	3.1		
COMPARATOR OUTPUT (PGOOD):	ACTIVE HIGH			
DCOOD doloy (do glitch) tirr-	Rising edge	0.42 0.54	0.66	ms
- PGOOD delay (de-glitch) time	Falling edge	0.42 0.54	0.66	ms
DOWN (TSD)				
Retry delay in TSD	TPS25940A Only	128		ms
	EN turn on delay  EN turn off delay  PROTECTION INPUT (OVP)  OVP disable delay  CONTROL (dV/dT )  Output ramp time  Fast-Trip comparator delay  ECTION COMPARATOR  Reverse protection comparator delay  COMPARATOR OUTPUT (PGOOD):  PGOOD delay (de-glitch) time		EN/UVLO ↑ (100mV above $V_{(ENR)}$ ) to $V_{(OUT)} = 100$ mV,   220   EN turn on delay   EN/UVLO ↑ (100mV above $V_{(ENR)}$ ) to $V_{(OUT)} = 100$ mV,   100 + 150 x   $C_{(dVdT)} \ge 0.8$ nF,   $C_$	EN turn on delay



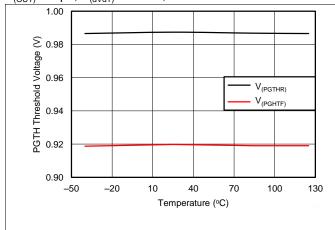
# 7.7 Typical Characteristics

Conditions are  $-40^{\circ}\text{C} \le T_{\text{A}} = T_{\text{J}} \le 125^{\circ}\text{C}, \ \underline{V_{(\text{IN})}} = 12 \text{ V}, \ V_{(\text{EN/UVLO})} = 2 \text{ V}, \ V_{(\text{OVP})} = V_{(\text{DEVSLP})} = V_{(\text{PGTH})} = 0 \text{ V}, \ R_{(\text{ILIM})} = 150 \text{ k}\Omega, \ C_{(\text{OUT})} = 1 \ \mu\text{F}, \ C_{(\text{dVdT})} = \text{OPEN}, \ \text{PGOOD} = \overline{\text{FLT}} = \text{IMON} = \text{OPEN}. \ \text{(unless stated otherwise)}$ 





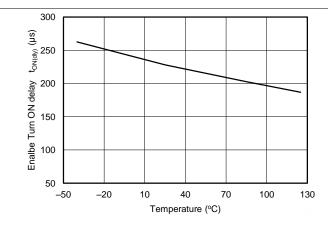
Conditions are  $-40^{\circ}\text{C} \leq T_{A} = T_{J} \leq 125^{\circ}\text{C}$ ,  $\frac{V_{(IIN)}}{IIN} = 12 \text{ V}$ ,  $V_{(EN/UVLO)} = 2 \text{ V}$ ,  $V_{(OVP)} = V_{(DEVSLP)} = V_{(PGTH)} = 0 \text{ V}$ ,  $R_{(ILIM)} = 150 \text{ k}\Omega$ ,  $R_{(OUT)} = 1 \text{ \mu}$ F,  $R_{(dVdT)} = 10 \text{ N}$ ,  $R_{(dVdT)} = 10 \text{ N}$ ,



0.60 EN Threshold Voltage for Low I<sub>Q</sub> Mode (V)  $V_{\text{(SHUTR)}}$  $V_{(SHUTF)}$ 0.55 0.50 0.45 0.40 70 -50 -20 10 40 100 130 Temperature (°C)

Figure 7. PGTH Threshold Voltage vs Temperature

Figure 8. EN Threshold Voltage for Low IQ mode vs
Temperature



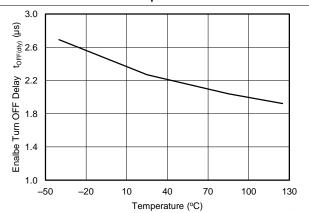


Figure 9. Enable Turn ON Delay vs Temperature

Figure 10. Enable Turn OFF Delay vs Temperature

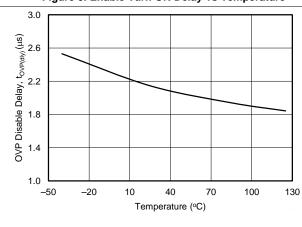


Figure 11. OVP Disable Delay vs Temperature

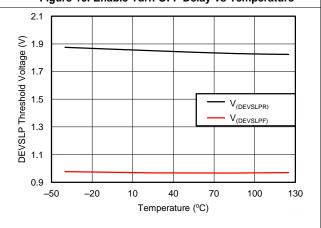
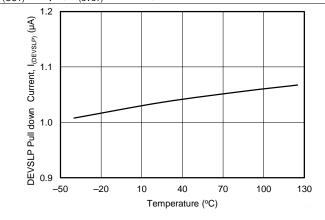


Figure 12. DEVSLP Threshold Voltage vs Temperature



Conditions are  $-40^{\circ}\text{C} \leq T_{A} = T_{J} \leq 125^{\circ}\text{C}$ ,  $\frac{V_{(IIN)}}{IIN} = 12 \text{ V}$ ,  $V_{(EN/UVLO)} = 2 \text{ V}$ ,  $V_{(OVP)} = V_{(DEVSLP)} = V_{(PGTH)} = 0 \text{ V}$ ,  $R_{(ILIM)} = 150 \text{ k}\Omega$ ,  $R_{(OUT)} = 1 \text{ \mu}$ F,  $R_{(dVdT)} = 10 \text{ N}$ ,  $R_{(dVdT)} = 10 \text{ N}$ ,



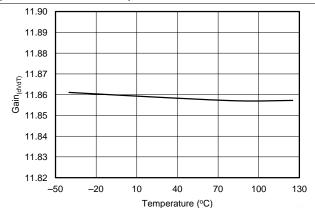
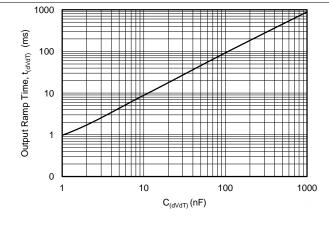


Figure 13. DEVSLP Pull Down Current vs Temperature

Figure 14. GAIN<sub>(dVdT)</sub> vs Temperature



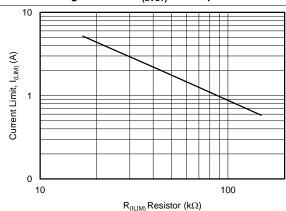
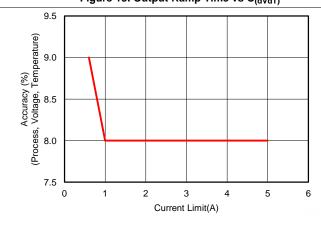


Figure 15. Output Ramp Time vs C<sub>(dVdT)</sub>

Figure 16. Current Limit vs Current Limit Resistor



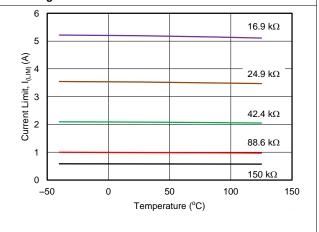


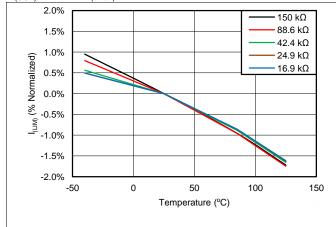
Figure 17. Current Limit Accuracy vs Current Limit

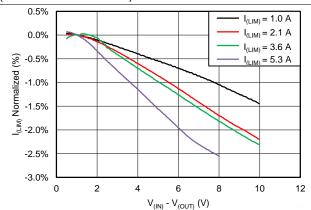
Figure 18. Current Limit vs Temperature Across R<sub>(ILIM)</sub>

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Conditions are  $-40^{\circ}\text{C} \leq \text{T}_{\text{A}} = \text{T}_{\text{J}} \leq 125^{\circ}\text{C}, \ \underline{V_{(\text{IN})}} = 12 \text{ V}, \ V_{(\text{EN/UVLO})} = 2 \text{ V}, \ V_{(\text{OVP})} = V_{(\text{DEVSLP})} = V_{(\text{PGTH})} = 0 \text{ V}, \ R_{(\text{ILIM})} = 150 \text{ k}\Omega, \ \underline{C_{(\text{OUT})}} = 1 \text{ \muF}, \ C_{(\text{dVdT})} = \text{OPEN}, \ \text{PGOOD} = \overline{\text{FLT}} = \text{IMON} = \text{OPEN}. \ \text{(unless stated otherwise)}$ 





Thermal shutdown occurs when  $I_{(LIM)} = 5.3 A$ and  $[V_{(IN)} - V_{(OUT)}] > 8 \text{ V}$ 

Figure 19. Current Limit (% Normalized) vs R(LIMIT) Resistor

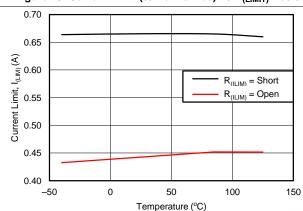


Figure 20. Current Limit Normalized (%) vs V(IN) - V(OUT)

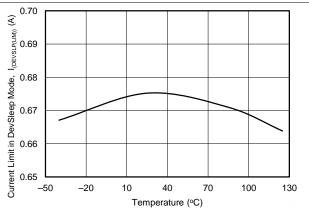


Figure 21. Current Limit for  $R_{(ILIM)}$  = Open and Short vs Temperaturé



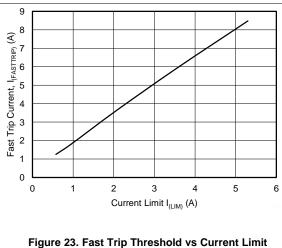


Figure 22. Current Limit in DevSleep Mode vs Temperature

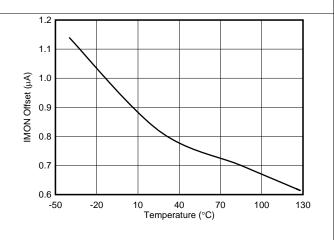
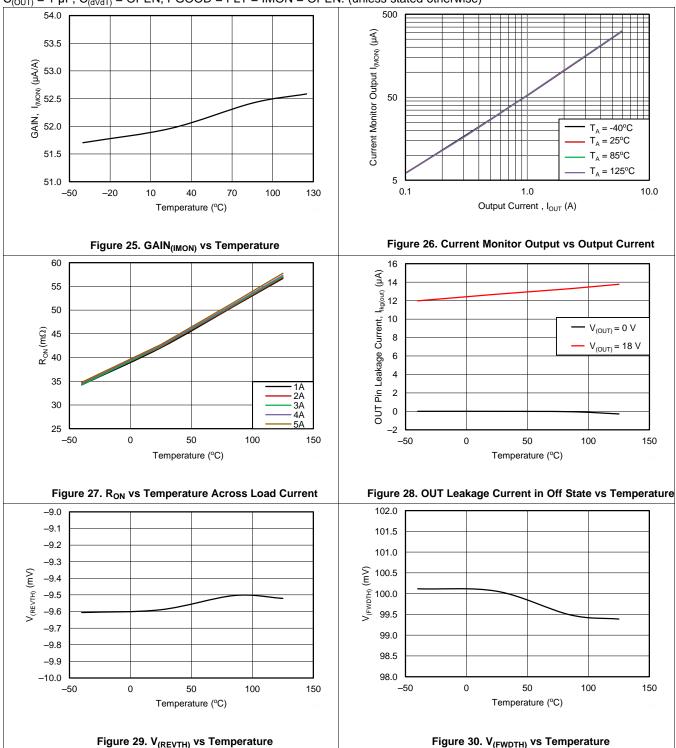


Figure 24. IMON Offset vs Temperature



Conditions are  $-40^{\circ}\text{C} \le T_{\text{A}} = T_{\text{J}} \le 125^{\circ}\text{C}, \ \underline{V_{(\text{IN})}} = 12 \text{ V}, \ V_{(\text{EN/UVLO})} = 2 \text{ V}, \ V_{(\text{OVP})} = V_{(\text{DEVSLP})} = V_{(\text{PGTH})} = 0 \text{ V}, \ R_{(\text{ILIM})} = 150 \text{ k}\Omega, \ \underline{C_{(\text{OUT})}} = 1 \text{ } \mu\text{F}, \ C_{(\text{dVdT})} = \text{OPEN}, \ \text{PGOOD} = \overline{\text{FLT}} = \text{IMON} = \text{OPEN}. \ \text{(unless stated otherwise)}$ 



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Conditions are  $-40^{\circ}\text{C} \leq T_{\text{A}} = T_{\text{J}} \leq 125^{\circ}\text{C}, \ \underline{V_{(\text{IN})}} = 12 \text{ V}, \ V_{(\text{EN/UVLO})} = 2 \text{ V}, \ V_{(\text{OVP})} = V_{(\text{DEVSLP})} = V_{(\text{PGTH})} = 0 \text{ V}, \ R_{(\text{ILIM})} = 150 \text{ k}\Omega, \ C_{(\text{OUT})} = 1 \ \mu\text{F}, \ C_{(\text{dVdT})} = \text{OPEN}, \ \text{PGOOD} = \overline{\text{FLT}} = \text{IMON} = \text{OPEN}. \ \text{(unless stated otherwise)}$ 

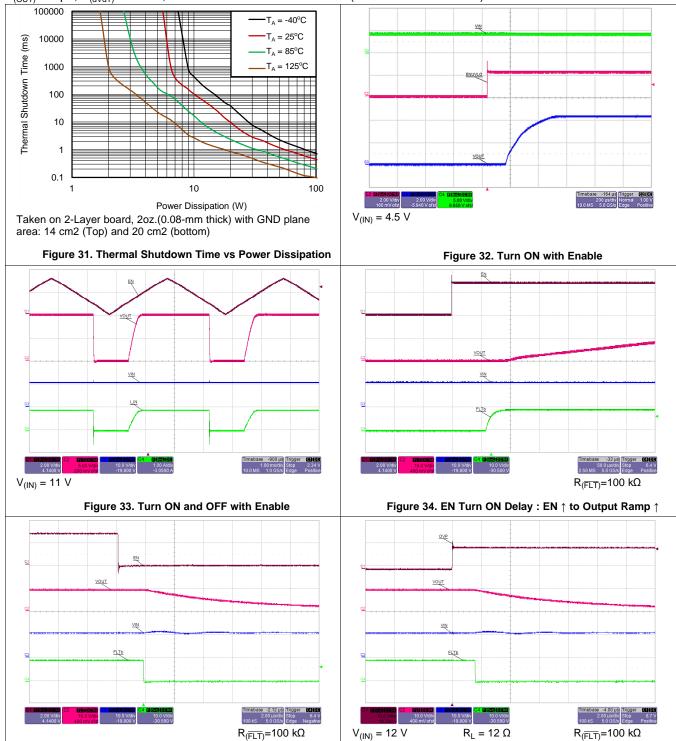
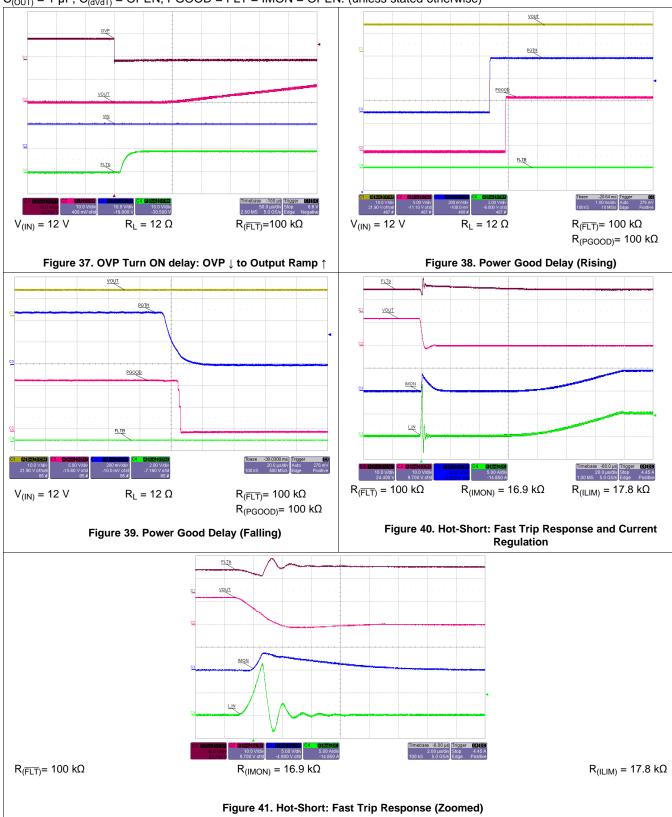


Figure 35. EN Turn OFF Delay : EN ↓ to Fault ↓

Figure 36. OVP Turn OFF delay: OVP ↑ to Fault ↓



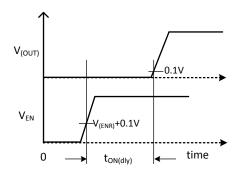
Conditions are  $-40^{\circ}\text{C} \leq T_{\text{A}} = T_{\text{J}} \leq 125^{\circ}\text{C}, \ \underline{V_{(\text{IN})}} = 12 \text{ V}, \ V_{(\text{EN/UVLO})} = 2 \text{ V}, \ V_{(\text{OVP})} = V_{(\text{DEVSLP})} = V_{(\text{PGTH})} = 0 \text{ V}, \ R_{(\text{ILIM})} = 150 \text{ k}\Omega, \ C_{(\text{OUT})} = 1 \ \mu\text{F}, \ C_{(\text{dVdT})} = \text{OPEN}, \ \text{PGOOD} = \overline{\text{FLT}} = \text{IMON} = \text{OPEN}. \ \text{(unless stated otherwise)}$ 

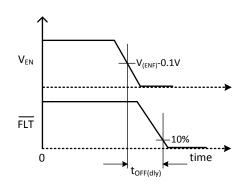


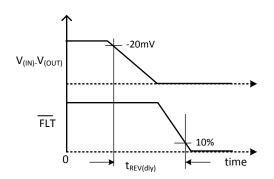
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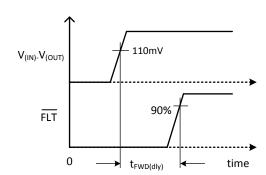


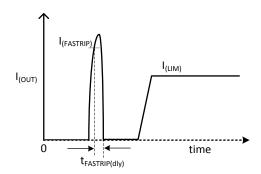
# 8 Parametric Measurement Information











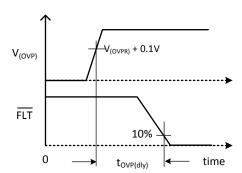


Figure 42. Timing Diagrams



### 9 Detailed Description

#### 9.1 Overview

TPS25940 is a smart eFuse with integrated back-to-back FETs and enhanced built-in protection circuitry. It provides robust protection for all systems and applications powered from 2.7 V to 18 V.

For hot-plug-in boards, the device provides hot-swap power management with in-rush current control and programmable output ramp-rate. The device integrates overcurrent and short circuit protection. The precision overcurrent limit helps to minimize over design of the input power supply, while the fast response short circuit protection immediately isolates the load from input when a short circuit is detected. The device allows the user to program the overcurrent limit threshold between 0.6 A and 5.3 A via an external resistor.

The device provides precise monitoring of voltage bus for brown-out and overvoltage conditions and asserts fault for downstream system. Its overall threshold accuracy of 2% ensures tight supervision of bus, eliminating the need for a separate supply voltage supervisor chip.

The device is designed to protect systems such as enterprise SSD drives against sudden power loss events. The device monitors  $V_{(IN)}$  and  $V_{(OUT)}$  to provide true reverse blocking from output when reverse condition or input power fail condition is detected. Also, the device signals the downstream controller to initiate transfer of power to the hold-up capacitor for data hardening.

The additional features include:

- Precise current monitor output for health monitoring of the system
- Additional power good comparator with precision internal reference for output or any other rail voltage monitoring
- Over temperature protection to safely shutdown in the event of an overcurrent event
- De-glitched fault reporting for brown-out and overvoltage faults
- A choice of latched or automatic restart mode

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# 9.2 Functional Block Diagram

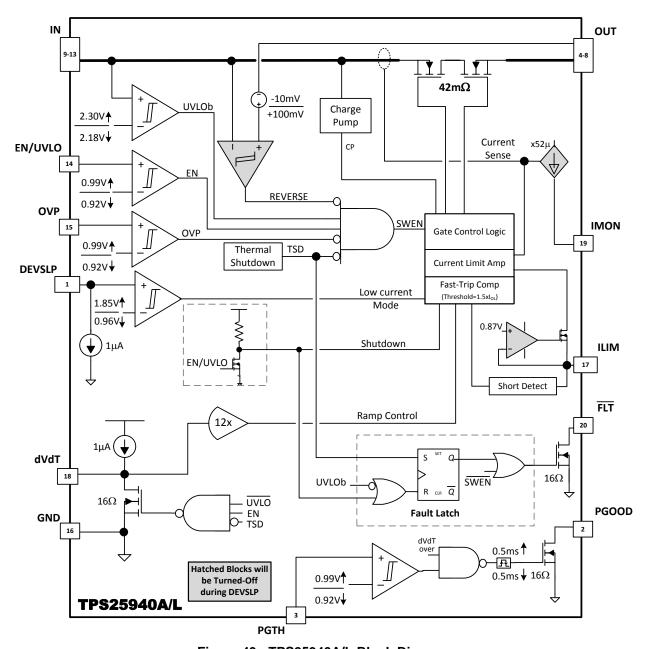


Figure 43. TPS25940A/L Block Diagram

#### 9.3 Feature Description

#### 9.3.1 Enable and Adjusting Undervoltage Lockout

The EN/UVLO pin controls the ON/OFF state of the internal FET. A voltage  $V_{(EN/UVLO)} < V_{(ENF)}$  on this pin will turn off the internal FET, thus disconnecting IN from OUT, while voltage below  $V_{(SHUTF)}$  will take the device into shutdown mode, with  $I_Q$  less than 15  $\mu$ A to ensure minimal power loss. Cycling EN/UVLO low and then back high resets the TPS25940L that has latched off due to a fault condition.

The internal de-glitch delay on EN/UVLO falling edge is kept low for quick detection of power failure. For applications where a higher de-glitch delay on EN/UVLO is desired, or when the supply is particularly noisy, it is recommended to use an external bypass capacitor from EN/UVLO terminal to GND.

The undervoltage lock out can be programmed by using an external resistor divider from supply IN terminal to EN/UVLO terminal to GND as shown in Figure 44. When an undervoltage or input power fail event is detected, the internal FET is quickly turned off, and FLT is asserted. If the Under-Voltage Lock-Out function is not needed, the EN/UVLO terminal should be connected to the IN terminal. EN/UVLO terminal should not be left floating.

The device also implements internal undervoltage-lockout (UVLO) circuitry on the IN terminal. The device disables when the IN terminal voltage falls below internal UVLO Threshold  $V_{(UVF)}$ . The internal UVLO threshold has a hysteresis of 115mV.

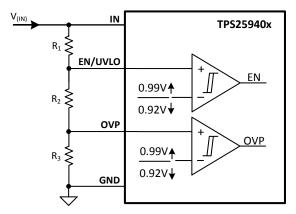


Figure 44. UVLO and OVP Thresholds Set By R<sub>1</sub>, R<sub>2</sub> and R<sub>3</sub>

### 9.3.2 Overvoltage Protection (OVP)

The device incorporates circuit to protect system during overvoltage conditions. A resistor divider connected from the supply to OVP terminal to GND (as shown in Figure 44) programs the overvoltage threshold. A voltage more than  $V_{(OVPR)}$  on OVP pin turns off the internal FET and protects the downstream load. This pin should be tied to GND when not used.

### 9.3.3 Hot Plug-in and In-Rush Current Control

The device is designed to control the in-rush current upon insertion of a card into a live backplane or other "hot" power source. This limits the voltage sag on the backplane's supply voltage and prevents unintended resets of the system power. A slew rate controlled startup (dVdT) also helps to eliminate conductive and radiative interferences. An external capacitor connected from the dVdT pin to GND defines the slew rate of the output voltage at power-on (as shown in Figure 45). Equation governing slew rate at start-up is shown in Equation 1:



### **Feature Description (continued)**

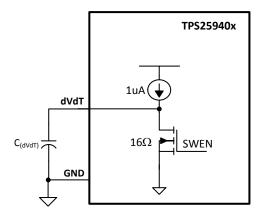


Figure 45. Output Ramp Up Time t<sub>dVdT</sub> is Set by C<sub>(dVdT)</sub>

$$I_{(dVdT)} = \left(\frac{C_{(dVdT)}}{GAIN_{(dVdT)}}\right) \times \left(\frac{dV_{(OUT)}}{dt}\right)$$
(1)

### Where:

•  $I_{(dVdT)} = 1 \mu A \text{ (typical)}$ 

dV(OUT)

- dt = Desired output slew rate
- GAIN<sub>(dVdT)</sub> = dVdT to OUT gain = 12

The total ramp time  $(t_{dVdT})$  of  $V_{(OUT)}$  for 0 to  $V_{(IN)}$  can be calculated using Equation 2:

$$t_{dVdT} = 8.3 \times 10^4 \times V_{(IN)} \times C_{(dVdT)}$$
 (2)

The inrush current, I(INRUSH) can be calculated as

$$I_{\text{(INRUSH)}} = C_{\text{(OUT)}} \times V_{\text{(IN)}} / t_{\text{dVdT}}. \tag{3}$$

The dVdT pin can be left floating to obtain a predetermined slew rate  $(t_{dVdT})$  on the output. When terminal is left floating, the device sets an internal ramp rate of 12V/ms for output  $(V_{(OUT)})$  ramp.

Figure 58 and Figure 59 illustrate the inrush current control behavior of the device. For systems where load is present during start-up, the current never exceeds the overcurrent limit set by  $R_{(ILIM)}$  resistor for the application. For defining appropriate charging time/rate under different load conditions, refer to the *Setting Output Voltage Ramp time* ( $t_{dVdT}$ ) section.

### 9.3.4 Overload and Short Circuit Protection:

At all times load current is monitored by sensing voltage across an internal sense resistor. During overload events, current is limited to the current limit ( $I_{(LIM)}$ ) programmed by  $R_{(ILIM)}$  resistor

$$I_{(LIM)} = \frac{89}{R_{(ILIM)}} \tag{4}$$

- I<sub>(LIM)</sub> is overload current limit in Ampere
- R<sub>(ILIM)</sub> is the current limit resistor in kΩ

The device incorporates two distinct levels: a current limit  $(I_{(LIM)})$  and a fast-trip threshold  $(I_{(FASTRIP)})$ . Fast trip and current limit operation are shown in Figure 46.

Bias current on ILIM pin directly controls current-limiting behavior of the device, and PCB routing of this node must be kept away from any noisy (switching) signals.

### **Feature Description (continued)**

#### 9.3.4.1 Overload Protection

For overload conditions, the internal current-limit amplifier regulates the output current to  $I_{(LIM)}$ . The output voltage droops during the current regulation, resulting in increased power dissipation in the device. If the device junction temperature reaches the thermal shutdown threshold  $(T_{(TSD)})$ , the internal FET is turned off. Once in thermal shutdown, The TPS25940L version stays latched off, whereas TPS25940A commences an auto-retry cycle 128 ms after  $T_J < [T_{(TSD)} - 12^{\circ}C]$ . During thermal shutdown, the fault pin  $\overline{FLT}$  pulls low to signal a fault condition. Figure 62 and Figure 63 illustrate overload behavior.

#### 9.3.4.2 Short Circuit Protection

During a transient short circuit event, the current through the device increases very rapidly. As current-limit amplifier cannot respond quickly to this event due to its limited bandwidth, the device incorporates a fast-trip comparator, with a threshold  $I_{(FASTRIP)}$ . This comparator shuts down the pass device within 1µs, when the current through internal FET exceeds  $I_{(FASTRIP)}$  ( $I_{(OUT)} > I_{(FASTRIP)}$ ), and terminates the rapid short-circuit peak current. The trip threshold is set to more than 50% of the programmed overload current limit ( $I_{(FASTRIP)} = 1.5 \times I_{(LIM)} + 0.375$ ). The fast-trip circuit holds the internal FET off for only a few microseconds, after which the device turns back on slowly, allowing the current-limit loop to regulate the output current to  $I_{(LIM)}$ . Then, device behaves similar to overload condition. Figure 64 through Figure 66 illustrate the behavior of the system when the current exceeds the fast-trip threshold.

### 9.3.4.3 Start-Up with Short on Output

During start-up into a short circuit current is limited to  $I_{(LIM)}$ . Figure 67 and Figure 68 illustrate start-up with a short on the output. This feature helps in quick fault isolation and hence ensures stability of the DC bus.

### 9.3.4.4 Constant Current Limit Behavior During Overcurrent Faults

When power dissipation in the internal FET [ $P_D = (V_{(IN)} - V_{(OUT)}) \times I_{(OUT)}$ ] > 10 W, there is a ~0 to 5 % thermal fold back in the current limit value so that  $I_{(LIM)}$  drops to  $I_{OS}$ . Eventually, the device shuts down due to over temperature.

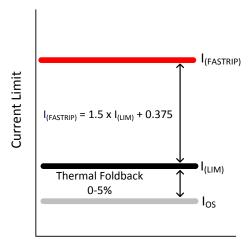


Figure 46. Fast-Trip Current

#### 9.3.5 FAULT Response

The FLT open-drain output is asserted (active low) during undervoltage, overvoltage, reverse voltage/current and thermal shutdown conditions. The FLT signal remains asserted until the fault condition is removed and the device resumes normal operation. The device is designed to eliminate false fault reporting by using an internal "deglitch" circuit for undervoltage and overvoltage (2.2-µs typical) conditions without the need for external circuitry. This ensures that fault is not accidentally asserted during transients on input bus.

Connect  $\overline{FLT}$  with a pull up resistor to Input or Output voltage rail.  $\overline{FLT}$  may be left open or tied to ground when not used.  $V_{(IIN)}$  falling below  $V_{(UVF)} = 2.1 \text{ V}$  resets  $\overline{FLT}$ .

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### **Feature Description (continued)**

### 9.3.6 Current Monitoring:

The current source at IMON terminal is configured to be proportional to the current flowing from IN to OUT. This current can be converted to a voltage using a resistor  $R_{(IMON)}$  from IMON terminal to GND terminal. This voltage, computed using Equation 6, can be used as a means of monitoring current flow through the system.

The maximum voltage range for monitoring the current ( $V_{(IMONmax)}$ ) is limited to minimum([ $V_{(IN)}$ - 2.2 V], 6.0 V) to ensure linear output. This puts limitation on maximum value of  $R_{(IMON)}$  resistor and is determined by Equation 5.

$$R_{(IMONmax)} = \frac{\text{minimum } (V_{(IN)} - 2.2, 6)}{1.6 \times I_{(LIM)} \times GAIN_{(IMON)}}$$
(5)

The output voltage at IMON terminal is calculated from Equation 6.

$$V_{(IMON)} = [I_{(OUT)} \times GAIN_{(IMON)} + I_{(IMON_OS)}] \times R_{(IMON)}$$
(6)

Where

- GAIN<sub>(IMON)</sub> = Gain factor I<sub>(IMON)</sub>:I<sub>(OUT)</sub> = 52 μA/A
- I<sub>(OUT)</sub> = Load current
- $I_{(IMON_OS)} = 0.8 \, \mu A \, (typ)$

This pin should not have a bypass capacitor to avoid delay in the current monitoring information.

The voltage at IMON pin can be digitized using an ADC (such as ADS1100, SBAS239) to read the current monitor information over an I2C bus.

#### 9.3.7 Power Good Comparator

The device incorporates a Power Good comparator for co-ordination of status to downstream DC-DC converters or system monitoring circuits. The comparator has an internal reference of  $V_{(PGTHR)} = 0.99 \text{ V}$  at negative terminal and positive terminal PGTH can be utilized for monitoring of either input or output of the device. The comparator output PGOOD is an open-drain active high signal, which can be used to indicate the status to downstream units. PGOOD is asserted high when internal FET is fully enhanced and PGTH pin voltage is higher than internal reference  $V_{(PGTHR)}$ .

The PGOOD signal has deglitch time incorporated to ensure that internal FET is fully enhanced before heavy load is applied by downstream converters. Rising de-glitch delay is determined by Equation 7.

$$t_{PGOOD(deal)} = Maximum\{(3.5 \times 10^6 \times C_{(dVdT)}), t_{PGOODR}\}$$
(7)

Connect the PGOOD pin with a pull up resistor to Input or Output voltage rail. PGOOD may be left open or tied to ground when not used.

#### 9.3.8 IN, OUT and GND Pins

The device has multiple pins for input (IN) and output (OUT).

All IN pins should be connected together and to the power source. A ceramic bypass capacitor close to the device from IN to GND is recommended to alleviate bus transients. The recommended operating voltage range is 2.7 V - 18 V.

Similarly all OUT pins should be connected together and to the load.  $V_{(OUT)}$  in the ON condition, is calculated using the Equation 8

$$V_{(OUT)} = V_{(IN)} - (R_{ON} \times I_{(OUT)})$$
(8)

where, R<sub>ON</sub> is the total ON resistance of the internal FET.

GND terminal is the most negative voltage in the circuit and is used as a reference for all voltage reference unless otherwise specified.

#### 9.3.9 Thermal Shutdown:

Internal over temperature shutdown disables turns off the FET when  $T_J > 160^{\circ}\text{C}$  (typical). The TPS25940L version latches off the internal FET, whereas TPS25940A commences an auto-retry cycle128 ms after  $T_J$  drops below  $[T_{(TSD)} - 12^{\circ}\text{C}]$ . During the thermal shutdown, the fault pin  $\overline{FLT}$  pulls low to signal a fault condition.



#### 9.4 Device Functional Modes

#### 9.4.1 DevSleep Mode for SATA® Interface Devices

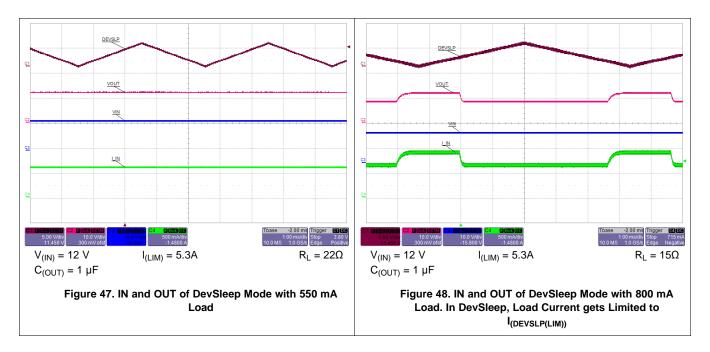
DevSleep is a new state introduced in the SATA® specification, which requires SATA-based storage solutions to reach a level of low power operation. This is appended to meet the aggressive power/battery life requirements of SATA-based mobile devices. DevSleep enables hosts and devices to completely hibernate the SATA interface. This saves more power versus the existing Partial and Slumber interface power states, which require that the PHY be left powered. In this mode, power consumption is limited to 5 mW or less for SSDs.

Detailed information on DevSleep is available in document 'SATA-DevSleep' and on www.sata-io.org

TPS25940 provides a dedicated DevSleep interface terminal (DEVSLP) to drive the device in low power mode. The DEVSLP terminal is compatible with standard hardware signals asserted from the host controller. When pulled high, it puts the device in low power DevSleep mode. In this mode, the quiescent current consumption of the device is limited to less than 130  $\mu$ A (95  $\mu$ A typical). During this mode, the output voltage remains active, the overload current limit is set to  $I_{(DEVSLP(LIM))}$  and functionality of reverse comparator and current monitoring is disabled. All other protections are kept active ensuring the safety of the system even in DevSleep mode.

User must ensure that load currents on the bus are limited to less than  $I_{(DEVSLP(LIM))}$ , when the device is driven to DevSleep mode. Also, while coming out of DevSleep, it is important to sequence the TPS25940 earlier than the load. Otherwise, the load can exceed  $I_{(DEVSLP(LIM))}$  and cause TPS25940 to enter the overload mode.

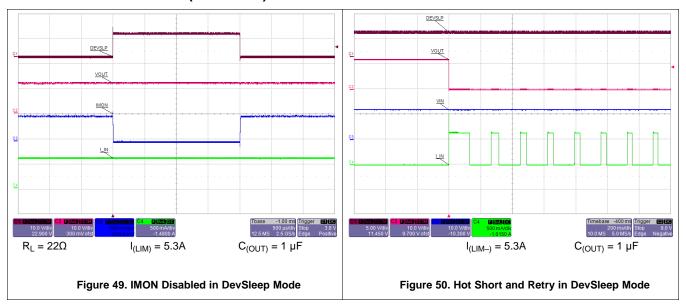
Figure 47 through Figure 50 illustrate the behavior of the system in DevSleep mode.



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### **Device Functional Modes (continued)**



#### 9.4.2 Shutdown Control

The internal FET and hence the load current can be remotely switched off by taking the UVLO pin below its 0.6 V threshold with an open collector or open drain device as shown in Figure 51. The device quiescent current is reduced to less than 20 µA in this state. Upon releasing the UVLO pin the device turns on with soft-start cycle.

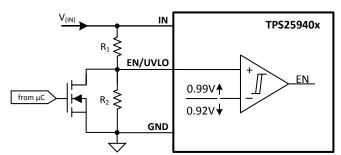


Figure 51. Shutdown Control



# 10 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

# 10.1 Application Information

The TPS25940 is a smart eFuse. It is typically used for Hot-Swap and Power rail protection applications. It operates from 2.7 V to 18 V with programmable current limit, overvoltage and undervoltage protection. The device aids in controlling the in-rush current and provides fast turn-off during reverse voltage conditions for systems such as Enterprise SSDs, HDDs, Servers, Power Back-up Storage units and RAID cards. The device also provides robust protection for multiple faults on the sub-system rail.

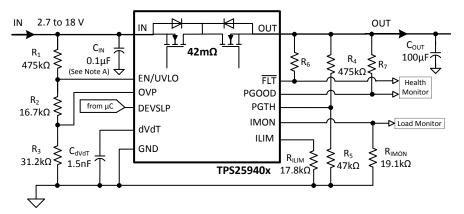
The following design procedure can be used to select component values for the device.

Alternatively, the WEBENCH® software may be used to generate a complete design. The WEBENCH® software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. Additionally, a spreadsheet design tool *TPS25940 Design Calculator* is available on web folder.

This section presents a simplified discussion of the design process.

### 10.2 Typical Application

#### 10.2.1 eFuse for Enterprise SSDs



A. C<sub>IN</sub>: Optional and only for noise suppression.

Figure 52. Typical Application Schematics: eFuse for Enterprise SSDs



# **Typical Application (continued)**

### 10.2.1.1 Design Requirements

**Table 1. Design Parameters** 

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage range, V <sub>(IN)</sub>	12 V
Undervoltage lockout set point, V <sub>(UV)</sub>	10.8 V
Overvoltage protection set point , V <sub>(LIM)</sub>	16.5 V
Load at Start-Up , R <sub>L(SU)</sub>	4.8 Ω
Current limit, I <sub>(LIM)</sub>	5 A
Load capacitance , C <sub>(OUT)</sub>	100 μF
Maximum ambient temperatures , T <sub>A</sub>	85°C

#### 10.2.1.2 Detailed Design Procedure

The following design procedure can be used to select component values for the TPS25940A and TPS25940L.

#### 10.2.1.2.1 Step by Step Design Procedure

To begin the design process a few parameters must be decided upon. The designer needs to know the following:

- Normal input operation voltage
- Maximum output capacitance
- Maximum current Limit
- Load during start-up
- Maximum ambient temperature of operation

This design procedure below seeks to control the junction temperature of device under both static and transient conditions by proper selection of output ramp-up time and associated support components. The designer can adjust this procedure to fit the application and design criteria.

### 10.2.1.2.2 Programming the Current-Limit Threshold: R<sub>(ILIM)</sub> Selection

The R<sub>(ILIM)</sub> resistor at the ILIM pin sets the over load current limit, this can be set using Equation 4.

$$R_{\text{(ILIM)}} = \frac{89}{5} = 17.8 \text{k}\Omega \tag{9}$$

Choose closest standard value: 17.8k, 1% standard value resistor.

#### 10.2.1.2.3 Undervoltage Lockout and Overvoltage Set Point

The undervoltage lockout (UVLO) and overvoltage trip point are adjusted using the external voltage divider network of  $R_1$ ,  $R_2$  and  $R_3$  as connected between IN, EN, OVP and GND pins of the device. The values required for setting the undervoltage and overvoltage are calculated solving Equation 10 and Equation 11.

$$V_{(OVPR)} = \frac{R_3}{R_1 + R_2 + R_3} \times V_{(OV)}$$
(10)

$$V_{(ENR)} = \frac{R_2 + R_3}{R_1 + R_2 + R_3} \times V_{(UV)}$$
 (11)

For minimizing the input current drawn from the power supply  $\{I_{(R123)} = V_{(IN)}/(R_1 + R_2 + R_3)\}$ , it is recommended to use higher values of resistance for  $R_1$ ,  $R_2$  and  $R_3$ .

However, leakage currents due to external active components connected to the resistor string can add error to these calculations. So, the resistor string current,  $I_{(R123)}$  must be chosen to be 20x greater than the leakage current expected.

From the device electrical specifications,  $V_{(OVPR)} = 0.99 \text{ V}$  and  $V_{(ENR)} = 0.99 \text{ V}$ . For design requirements,  $V_{(OV)}$  is 16.5 V and  $V_{(UV)}$  is 10.8 V. To solve the equation, first choose the value of  $R_3 = 31.2 \text{ k}\Omega$  and use Equation 10 to solve for  $(R_1 + R_2) = 488.8 \text{ k}\Omega$ . Use Equation 11 and value of  $(R_1 + R_2)$  to solve for  $R_2 = 16.47 \text{ k}\Omega$  and finally  $R_1 = 472.33 \text{ k}\Omega$ .



Using the closest standard 1% resistor values gives  $R_1 = 475 \text{ k}\Omega$ ,  $R_2 = 16.7 \text{ k}\Omega$ , and  $R_3 = 31.2 \text{ k}\Omega$ .

The power failure threshold is detected on the falling edge of supply. This threshold voltage is 7% lower than the rising threshold,  $V_{(UV)}$ . This is calculated using Equation 12.

$$V_{(PFAIL)} = 0.93 \times V_{(UV)} \tag{12}$$

### 10.2.1.2.4 Programming Current Monitoring Resistor - R<sub>IMON</sub>

Voltage at IMON pin  $V_{(IMON)}$  represents the voltage proportional to load current. This can be connected to an ADC of the downstream system for health monitoring of the system. The  $R_{(IMON)}$  need to be configured based on the maximum input voltage range of the ADC used.  $R_{(IMON)}$  is set using Equation 13.

$$R_{(IMON)} = \frac{V_{(IMONmax)}}{I_{(LIM)} \times 52 \times 10^{-6}} \text{ k}\Omega$$
(13)

For  $I_{(LIM)} = 5$  A, and considering the operating range of ADC from 0 V to 5 V,  $V_{(IMONmax)}$  is 5 V and  $R_{(IMON)}$  is determined by:

$$R_{\text{(IMON)}} = \frac{5}{5 \times 52 \times 10^{-6}} = 19.23 \text{ k}\Omega \tag{14}$$

Selecting  $R_{(IMON)}$  value less than determined by Equation 14 ensures that ADC limits are not exceeded for maximum value of load current.

If the IMON pin voltage is not being digitized with an ADC,  $R_{(IMON)}$  can be selected to produce a 1V/1A voltage at the IMON pin, using Equation 13.

Choose closest 1 % standard value: 19.1 k $\Omega$ .

If current monitoring up to  $I_{(FASTRIP)}$  is desired,  $R_{(IMON)}$  can be reduced by a factor of 1.6, as in Equation 5.

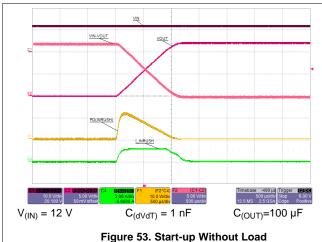
### 10.2.1.2.5 Setting Output Voltage Ramp time (t<sub>dVdT</sub>)

For a successful design, the junction temperature of device should be kept below the absolute-maximum rating during both dynamic (start-up) and steady state conditions. Dynamic power stresses often are an order of magnitude greater than the static stresses, so it is important to determine the right start-up time and in-rush current limit required with system capacitance to avoid thermal shutdown during start-up with and without load.

The ramp-up capacitor  $C_{(dVdT)}$  needed is calculated considering the two possible cases:

### 10.2.1.2.5.1 Case1: Start-up Without Load: Only Output Capacitance C<sub>(OUT)</sub> Draws Current During Start-up

During start-up, as the output capacitor charges, the voltage difference across the internal FET decreases, and the power dissipated decreases as well. Typical ramp-up of output voltage  $V_{(OUT)}$  with inrush current limit of 1.2A and power dissipated in the device during start-up is shown in Figure 53. The average power dissipated in the device during start-up is equal to area of triangular plot (red curve in Figure 54) averaged over  $t_{dVdT}$ .



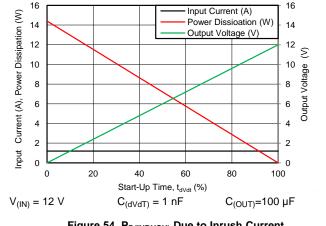


Figure 54. P<sub>D(INRUSH)</sub> Due to Inrush Current

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For TPS25940 device, the inrush current is determined as,

$$I = C \times \frac{dV}{dT} = > I_{(INRUSH)} = C_{(OUT)} \times \frac{V_{(IN)}}{t_{dVdT}}$$
(15)

Power dissipation during start-up is:

$$P_{D(INRUSH)} = 0.5 \times V_{(IN)} \times I_{(INRUSH)}$$
(16)

Equation 16 assumes that load does not draw any current until the output voltage has reached its final value.

### 10.2.1.2.5.2 Case 2: Start-up With Load: Output Capacitance C(OUT) and Load Draws Current During Start-up

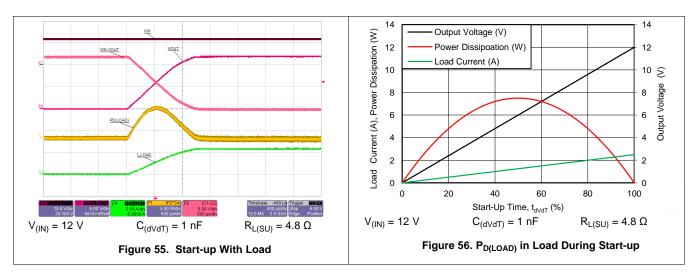
When load draws current during the turn-on sequence, there will be additional power dissipated. Considering a resistive load  $R_{L(SU)}$  during start-up, load current ramps up proportionally with increase in output voltage during  $t_{dVdT}$  time. Typical ramp-up of output voltage, Load current and power dissipation in the device is shown in Figure 55 and power dissipation with respect to time is plotted in Figure 56. The additional power dissipation during start-up phase is calculated as follows.

$$(V_{I} - V_{O})(t) = V_{(IN)} \times \left(1 - \frac{t}{t_{dVdT}}\right)$$
(17)

$$I_{L}(t) = \left(\frac{V_{(IN)}}{R_{L}(SU)}\right) \times \frac{t}{t_{dVdT}}$$
(18)

Where  $R_{L(SU)}$  is the load resistance present during start-up. Average energy loss in the internal FET during charging time due to resistive load is given by:

$$W_{t} = \int_{0}^{tdVdT} V_{(IN)} \times \left(1 - \frac{t}{t_{dVdT}}\right) \times \left(\frac{V_{(IN)}}{R_{L(SU)}} \times \frac{t}{t_{dVdT}}\right) dt$$
(19)



On solving Equation 19 the average power loss in the internal FET due to load is:

$$P_{D(LOAD)} = \left(\frac{1}{6}\right) \times \frac{V^2_{(IN)}}{R_{L(SU)}}$$
(20)

Total power dissipated in the device during startup is:

$$P_D(STARTUP) = P_D(INRUSH) + P_D(LOAD)$$
 (21)

Total current during startup is given by:

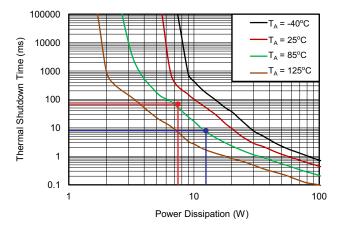
$$I(STARTUP) = I(INRUSH) + I_L(t)$$
 (22)

If  $I_{(STARTUP)} > I_{(LIM)}$ , the device limits the current to  $I_{(LIM)}$  and the current limited charging time is determined by:

$$t_{dVdT(current \ limited)} = C_{(OUT)} \times \frac{V_{(IN)}}{I_{(LIM)}}$$
 (23)



The power dissipation, with and without load, for selected start-up time should not exceed the shutdown limits as shown in Figure 57.



Taken on 2-Layer board, 2oz.(0.08-mm thick) with GND plane area: 14 cm2 (Top) and 20 cm2 (bottom)

Figure 57. Thermal Shutdown Limit Plot

For the design example under discussion,

Select ramp-up capacitor  $C_{(dVdT)} = 1nF$ , using Equation 2.

$$t_{\text{dvdt}} = 8.3 \times 10^4 \times 12 \times 1 \times 10^{-9} = 0.996 \text{ms} = \sim 1 \text{ms}$$
 (24)

The inrush current drawn by the load capacitance  $(C_{(OUT)})$  during ramp-up using Equation 3.

$$I_{\text{(INRUSH)}} = \left(100 \times 10^{-6}\right) \times \left(\frac{12}{1 \times 10^{-3}}\right) = 1.2 \text{ A}$$
 (25)

The inrush Power dissipation is calculated, using Equation 16.

$$P_{D(INRUSH)} = 0.5 \times 12 \times 1.2 = 7.2 \text{ W}$$
 (26)

For 7.2 W of power loss, the thermal shut down time of the device should not be less than the ramp-up time  $t_{dVdT}$  to avoid the false trip at maximum operating temperature. From thermal shutdown limit graph Figure 57 at  $T_A = 85^{\circ}\text{C}$ , for 7.2 W of power the shutdown time is ~60 ms. So it is safe to use 1 ms as start-up time without any load on output.

Considering the start-up with load 4.8  $\Omega$ , the additional power dissipation, when load is present during start up is calculated, using Equation 20.

$$P_{D(LOAD)} = \left(\frac{1}{6}\right) \times \frac{12 \times 12}{4.8} = 5 \text{ W}$$
 (27)

The total device power dissipation during start up is:

$$P_{D(STARTUP)} = (7.2+5) = 12.2 \text{ W}$$
 (28)

From thermal shutdown limit graph at  $T_A = 85^{\circ}$ C, the thermal shutdown time for 12.2 W is close to 7.5 ms. It is safe to have 30% margin to allow for variation of system parameters such as load, component tolerance, and input voltage. So it is well within acceptable limits to use the 1 nF capacitor with start-up load of 4.8  $\Omega$ .

If there is a need to decrease the power loss during start-up, it can be done with increase of  $C_{(dVdT)}$  capacitor.

To illustrate, choose  $C_{(dVdT)} = 1.5 \text{ nF}$  as an option and recalculate:

$$t_{\text{dvdt}} = 1.5 \text{ms} \tag{29}$$

$$I_{\text{(INRUSH)}} = \left(100 \times 10^{-6}\right) \times \left(\frac{12}{1.5 \times 10^{-3}}\right) = 0.8 \text{ A}$$
 (30)

$$P_{D(INRUSH)} = 0.5 \text{ x } 12 \text{x } 0.8 = 4.8 \text{ W}$$
 (31)

$$P_{D(LOAD)} = \left(\frac{1}{6}\right) \times \left(\frac{12 \times 12}{4.8}\right) = 5 \text{ W}$$
 (32)



$$P_{D(STARTUP)} = 4.8 + 5 = 9.8 \text{ W}$$
 (33)

From thermal shutdown limit graph at  $T_A = 85^{\circ}$ C, the shutdown time for 10 W power dissipation is ~17 ms, which increases the margins further for shutdown time and ensures successful operation during start up and steady state conditions.

The spreadsheet tool available on the web can be used for iterative calculations.

#### 10.2.1.2.6 Programing the Power Good Set Point

As shown in Figure 52,  $R_4$  and  $R_5$  sets the required limit for PGOOD signal as needed for the downstream converters. Considering a power good threshold of 11 V for this design, the values of  $R_4$  and  $R_5$  are calculated using Equation 34.

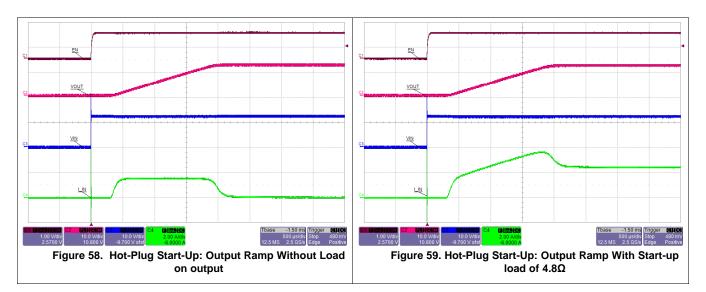
$$V_{(PGTH)} = 0.99 \times \left(1 + \frac{R_4}{R_5}\right)$$
 (34)

It is recommended to have high values for these resistors to limit the current drawn from the output node. Choosing a value of  $R_4 = 475 \text{ k}\Omega$ ,  $R_5 = 47 \text{ k}\Omega$  provides  $V_{(PGTH)} = 11 \text{ V}$ .

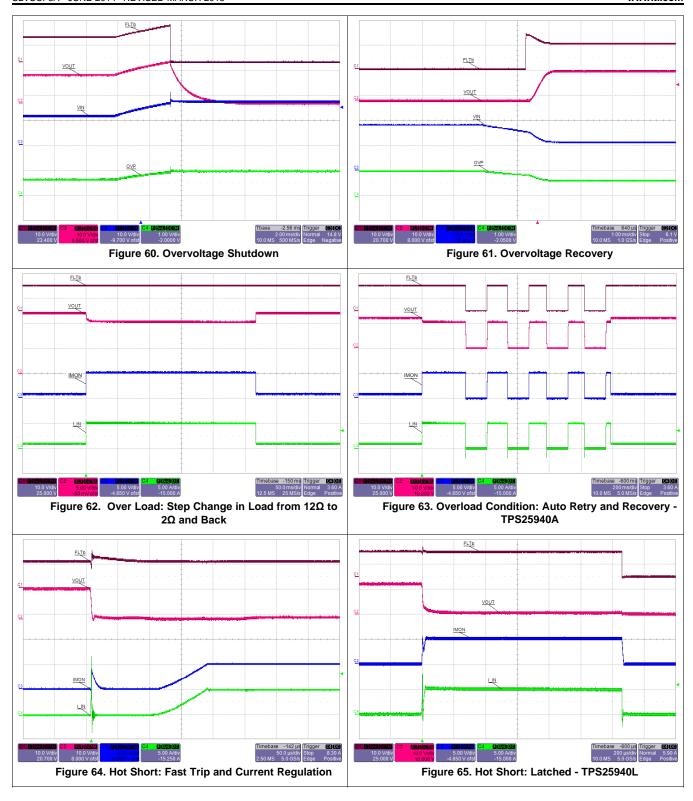
### 10.2.1.2.7 Support Component Selections - R<sub>6</sub>, R<sub>7</sub> and C<sub>IN</sub>

Reference to application schematics,  $R_6$  and  $R_7$  are required only if PGOOD and  $\overline{FLT}$  are used; these resistors serve as pull-ups for the open-drain output drivers. The current sunk by each of these pins should not exceed 10 mA (refer to the Absolute Maximum Ratings table).  $C_{IN}$  is a bypass capacitor to help control transient voltages, unit emissions, and local supply noise. Where acceptable, a value in the range of 0.001  $\mu F$  to 0.1  $\mu F$  is recommended for  $C_{(IN)}$ .

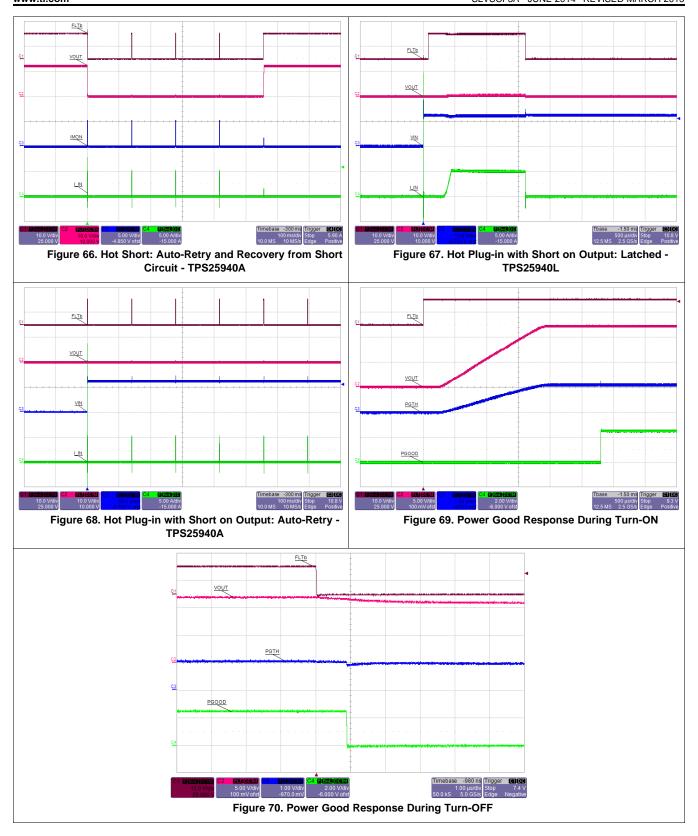
### 10.2.1.3 Application Curves













### 10.3 System Examples

#### 10.3.1 Power Failure Protection and Data Retention in SSDs

For enterprise and Industrial SSDs, it is necessary to have hold-up circuit and capacitor bank to ensure that critical user data is never lost during power-failure to the drive. The power-failure event could be due to momentary loss of power regulation (transient brown-out condition) or due to loss of power when drive is hotplugged out.

The TPS25940 continuously monitors the supply voltage at EN/UVLO pin and swiftly disconnects the input bus from output when the voltage drops below a predefined threshold (power fail detection). The TPS25940 also monitors the reverse voltage from IN to OUT and when it exceeds -10 mV, it stops the flow of reverse current. In addition, it provides an instant warning signal ( $\overline{FLT}$ ) to the SSD controller to initiate the data hardening process. Its swift true reverse blocking feature reacts in 1  $\mu$ s (typical) ensuring that the capacitor bank charge is retained. This helps the drive to have power for longer time to harden data and reduces the capacitance required in the hold-up bank, saving system cost.

The typical application diagram and application schematic of TPS25940 usage for enterprise SSD are shown in Figure 71 and Figure 72

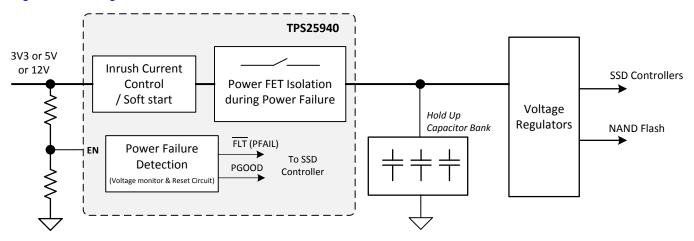


Figure 71. Power Circuit Block Diagram of Enterprise and Industrial SSDs

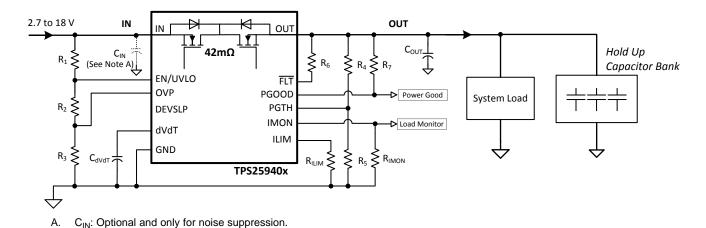


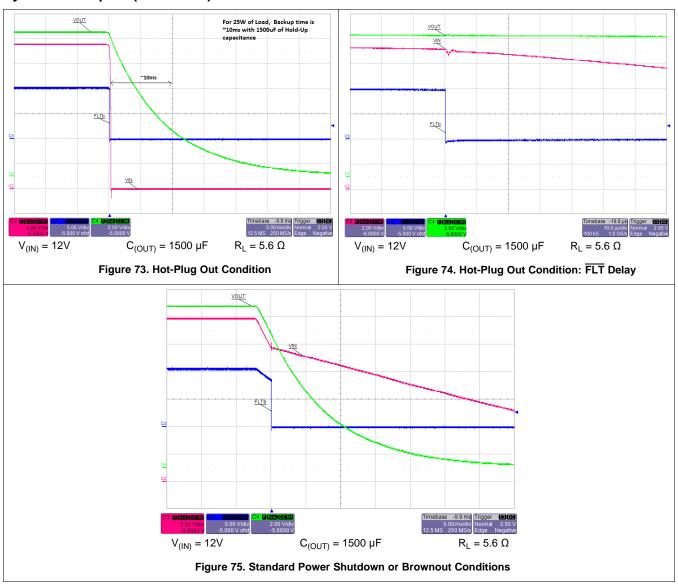
Figure 72. Enterprise SSD - Holdup Capacitor Implementation using TPS25940

The oscilloscope plots demonstrating the true reverse blocking, fast turn-off and FLT signal delay are shown in Figure 73 through Figure 75.

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### System Examples (continued)



# 10.3.2 Boost Power Rail Configuration for Data Retention in Enterprise SSDs

In certain enterprise SSD architectures, the hold-up capacitor voltage is boosted to value higher than the input bus voltage to optimize the storage capacitor bank. A typical boosted hold-up voltage ranges from 12 V to 18 V. A typical power circuit block diagram is shown in Figure 76. For these applications, TPS25940 provides quick and smooth changeover of the power from main input bus to boosted backup voltage.



### System Examples (continued)

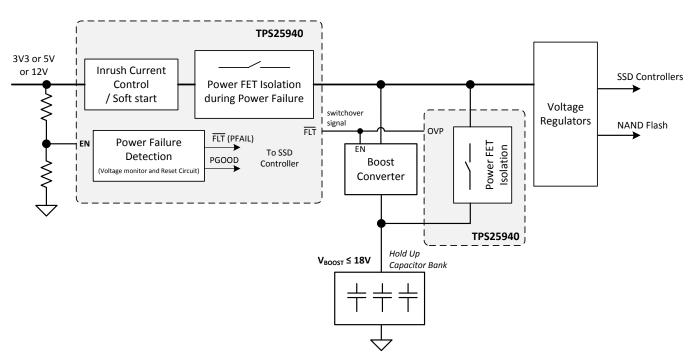
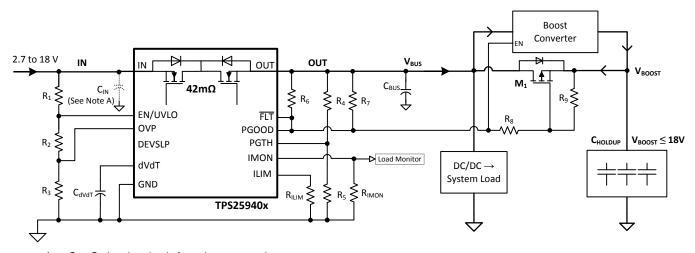


Figure 76. Power Circuit Block Diagram with Boosted Backup Power for Enterprise SSD

A typical application schematic for implementation of boosted backup power configuration is shown in Figure 77. During startup TPS25940 provides the inrush current control to charge up the  $C_{(BUS)}$  as well as  $C_{(HOLDUP)}$  close to  $V_{(IN)}$ . Once  $V_{(BUS)}$  reaches the programmed PGOOD threshold, the boost converter is enabled to charge  $C_{(HOLDUP)}$  to  $V_{(BOOST)}$ . When  $V_{(IN)}$  fails, TPS25940 detects power failure and asserts the fault signal (FLT), which in turn disables the boost converter and shorts  $V_{(BOOST)}$  to  $V_{(BUS)}$ , through  $M_1$ . The FLT signal can be interfaced to SSD controller to initiate the data hardening process. If current limit protection is desired during data hardening process (when holdup capacitor is supplying system bus),  $M_1$  can be replaced by another TPS25940.

The oscilloscope plot demonstrating change over from Main (12 V) to Boosted backup power (14.5 V) is shown in Figure 78.



A.  $C_{IN}$ : Optional and only for noise suppression.

Figure 77. Enterprise SSDs: Boosted Backup Power Multiplexing Circuit Implementation

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# System Examples (continued)

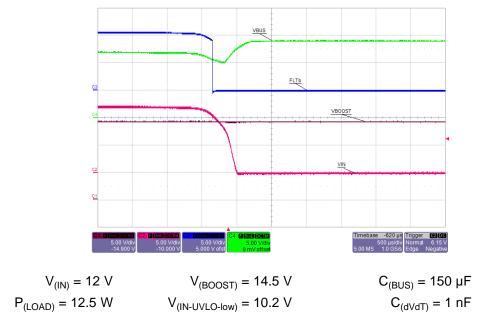


Figure 78. Brownout (Power Fail) Condition: Switch over to Boosted Backup Power

### 11 Power Supply Recommendations

The TPS25940 device is designed for supply voltage range of 2.7 V  $\leq$  V<sub>IN</sub>  $\leq$  18 V. If the input supply is located more than a few inches from the device an input ceramic bypass capacitor higher than 0.1  $\mu$ F is recommended. Power supply should be rated higher than the current limit set to avoid voltage droops during over current and short-circuit conditions.

#### 11.1 Transient Protection

In case of short circuit and over load current limit, when the device interrupts current flow, input inductance generates a positive voltage spike on the input and output inductance generates a negative voltage spike on the output. The peak amplitude of voltage spikes (transients) is dependent on value of inductance in series to the input or output of the device. Such transients can exceed the *Absolute Maximum Ratings* of the device if steps are not taken to address the issue.

Typical methods for addressing transients include

- · Minimizing lead length and inductance into and out of the device
- Using large PCB GND plane
- Schottky diode across the output to absorb negative spikes
- A low value ceramic capacitor ( $C_{(IN)} = 0.001~\mu\text{F}$  to 0.1  $\mu\text{F}$ ) to absorb the energy and dampen the transients. The approximate value of input capacitance can be estimated with Equation 35.

$$V_{\text{SPIKE}(\text{Absolute})} = V_{\text{(IN)}} + I_{\text{(LOAD)}} \times \sqrt{\frac{L_{\text{(IN)}}}{C_{\text{(IN)}}}}$$
(35)

#### Where:

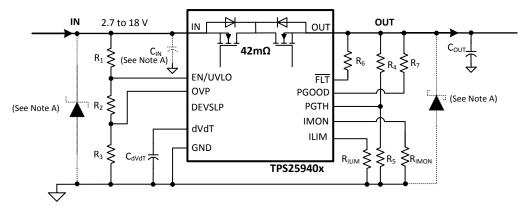
- V<sub>(IN)</sub> is the nominal supply voltage
- I<sub>(LOAD)</sub> is the load current,
- L<sub>(IN)</sub> equals the effective inductance seen looking into the source
- C<sub>(IN)</sub> is the capacitance present at the input



### **Transient Protection (continued)**

Some applications may require the addition of a Transient Voltage Suppressor (TVS) to prevent transients from exceeding the *Absolute Maximum Ratings* of the device.

The circuit implementation with optional protection components (a ceramic capacitor, TVS and schottky diode) is shown in Figure 79.



A. Optional components needed for suppression of transients

Figure 79. Circuit Implementation With Optional Protection Components

### 11.2 Output Short-Circuit Measurements

It is difficult to obtain repeatable and similar short-circuit testing results. Source bypassing, input leads, circuit layout and component selection, output shorting method, relative location of the short, and instrumentation all contribute to variation in results. The actual short itself exhibits a certain degree of randomness as it microscopically bounces and arcs. Care in configuration and methods must be used to obtain realistic results. Do not expect to see waveforms exactly like those in the data sheet; every setup differs.



# 12 Layout

# 12.1 Layout Guidelines

- For all applications, a 0.1-uF or greater ceramic decoupling capacitor is recommended between IN terminal and GND. For hot-plug applications, where input power path inductance is negligible, this capacitor can be eliminated/minimized.
- The optimum placement of decoupling capacitor is closest to the IN and GND terminals of the device. Care
  must be taken to minimize the loop area formed by the bypass-capacitor connection, the IN terminal, and the
  GND terminal of the IC. See Figure 80 for a PCB layout example.
- High current carrying power path connections should be as short as possible and should be sized to carry at least twice the full-load current.
- Low current signal ground (SGND), which is the reference ground for the device should be a copper plane or island.
- Locate all TPS25940 support components: R<sub>(ILIM)</sub>, C<sub>dVdT</sub>, R<sub>(IMON)</sub>, and resistors for UVLO and OVP, close to their connection pin. Connect the other end of the component to the SGND with shortest trace length.
- The trace routing for the R<sub>ILIM</sub> and R<sub>(IMON)</sub> components to the device should be as short as possible to reduce parasitic effects on the current limit and current monitoring accuracy. These traces should not have any coupling to switching signals on the board.
- The SGND plane must be connected to high current ground (main power ground) at a single point, that is at the negative terminal of input capacitor
- Protection devices such as TVS, snubbers, capacitors, or diodes should be placed physically close to the
  device they are intended to protect, and routed with short traces to reduce inductance. For example, a
  protection Schottky diode is recommended to address negative transients due to switching of inductive loads,
  and it should be physically close to the OUT pins.
- Thermal Considerations: When properly mounted the PowerPAD<sup>™</sup> package provides significantly greater cooling ability than an ordinary package. To operate at rated power, the PowerPAD must be soldered directly to the board GND plane directly under the device. The PowerPAD is at GND potential and can be connected using multiple vias to inner layer GND. Other planes, such as the bottom side of the circuit board can be used to increase heat sinking in higher current applications. Refer to Technical Briefs: PowerPad<sup>™</sup> Thermally Enhanced Package (TI literature Number SLMA002) and PowerPAD<sup>™</sup> Made Easy (TI Literature Number SLMA004) or more information on using this PowerPAD<sup>™</sup> package
- The thermal via land pattern specific to TPS25940 can be downloaded from device webpage
- Obtaining acceptable performance with alternate layout schemes is possible; however this layout has been shown to produce good results and is intended as a guideline.



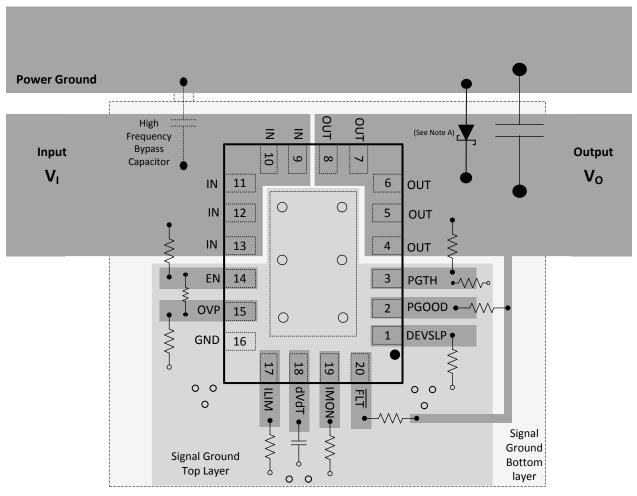
### 12.2 Layout Example

Top layer

Top layer signal ground plane

Bottom layer signal ground plane

O Via to signal ground plane



A. Optional: Needed only to suppress the transients caused by inductive load switching

Figure 80. Board Layout



# 13 Device and Documentation Support

#### 13.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 2. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY	
TPS25940A	Click here	Click here	Click here	Click here	Click here	
TPS25940L	Click here	Click here	Click here	Click here	Click here	

### 13.2 Trademarks

DevSleep, SATA are trademarks of The Serial ATA International Organization (SATA-IO). All other trademarks are the property of their respective owners.

### 13.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 13.4 Glossary

SLYZ022 — TI Glossary.

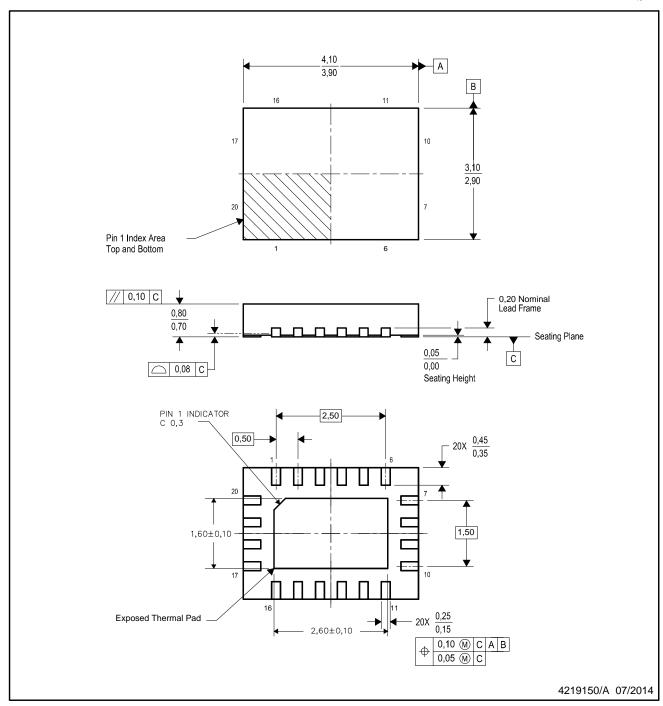
This glossary lists and explains terms, acronyms, and definitions.

# 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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WOFN

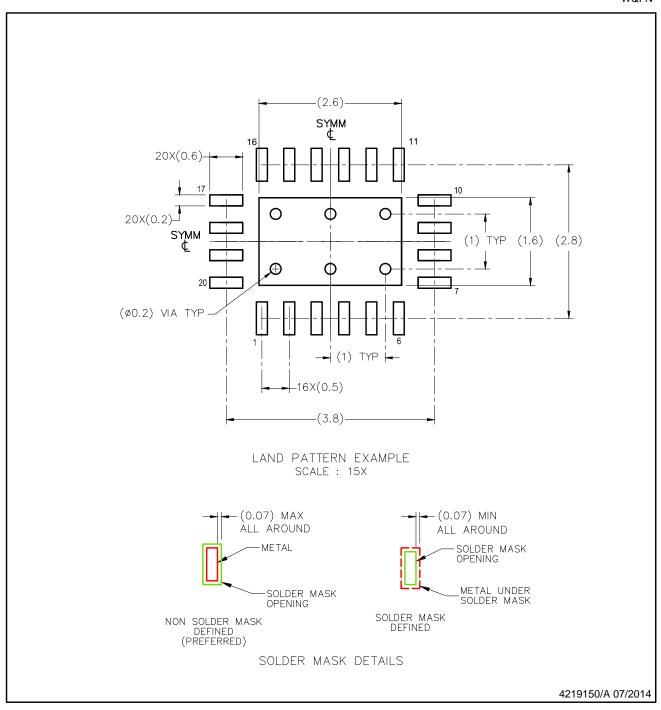


#### NOTES:

- All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



WOEN

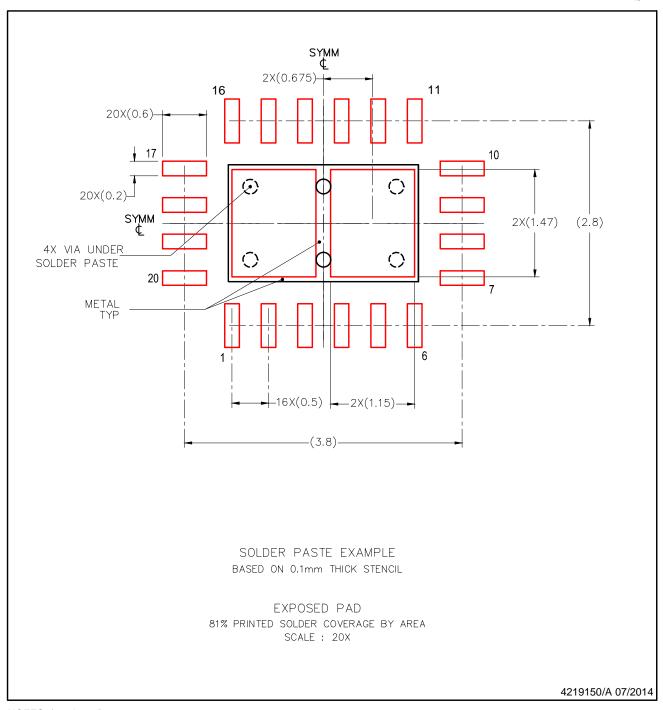


NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, refer to QFN/SON PCB application note in literature No. SLUA271 (www.ti.com/lit/slua271) .



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NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.







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#### **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
TPS25940ARVCR	ACTIVE	WQFN	RVC	20	3000	Green (RoHS & no Sb/Br)	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	25940A	Samples
TPS25940ARVCT	ACTIVE	WQFN	RVC	20	250	Green (RoHS & no Sb/Br)	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	25940A	Samples
TPS25940LRVCR	ACTIVE	WQFN	RVC	20	3000	Green (RoHS & no Sb/Br)	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	(25940A, 25940L)	Samples
TPS25940LRVCT	ACTIVE	WQFN	RVC	20	250	Green (RoHS & no Sb/Br)	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	25940L	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead/Ball Finish Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

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continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF TPS25940:

Automotive: TPS25940-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

# **PACKAGE MATERIALS INFORMATION**

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# TAPE AND REEL INFORMATION





_		
		Dimension designed to accommodate the component width
		Dimension designed to accommodate the component length
		Dimension designed to accommodate the component thickness
	W	Overall width of the carrier tape
Γ	P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

All difficultions are nominal												
Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS25940ARVCR	WQFN	RVC	20	3000	330.0	12.4	3.3	4.3	1.1	8.0	12.0	Q1
TPS25940ARVCT	WQFN	RVC	20	250	180.0	12.4	3.3	4.3	1.1	8.0	12.0	Q1
TPS25940LRVCR	WQFN	RVC	20	3000	330.0	12.4	3.3	4.3	1.1	8.0	12.0	Q1
TPS25940LRVCT	WQFN	RVC	20	250	180.0	12.4	3.3	4.3	1.1	8.0	12.0	Q1

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\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS25940ARVCR	WQFN	RVC	20	3000	367.0	367.0	35.0
TPS25940ARVCT	WQFN	RVC	20	250	210.0	185.0	35.0
TPS25940LRVCR	WQFN	RVC	20	3000	367.0	367.0	35.0
TPS25940LRVCT	WQFN	RVC	20	250	210.0	185.0	35.0

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