Documents

# TPS62134x, 17-V Input, Step-down Converter With Low-Power Mode Input for Intel Skylake Platform 

## 1 Features

- DCS-Control ${ }^{\text {TM }}$ Architecture
- Supports Low-Power Mode for System Standby Mode
- Power Save Mode for Light Load Efficiency
- Selectable Fixed Output Voltage (0.7 V to 1.05 V )
- Low Power Mode Logic Input
- Quiescent Current of $20 \mu \mathrm{~A}$
- Input Voltage Range: 3 V to 17 V
- Output Current: up to 3.2 A
- Programmable Soft Start
- Power Good Output
- Short Circuit Protection
- Single-ended Remote Sense
- Thermal Shutdown Protection
- Available in a 3-mm $\times$ 3-mm, VQFN-16 Package


## 2 Applications

- Intel Skylake ${ }^{\text {TM }}$ Platform Ultrabook, Notebook, PC
- Standard 12-V Rail Supply
- POL Supply from 1 to 4 Cells Li-Ion Battery
- Solid-State Disk Drive
- Embedded System


## 3 Description

The TPS62134x family of devices is an easy-to-use, synchronous step-down DC-DC converter, compatible with Intel Skylake platform applications such as Ultrabooks ${ }^{\text {TM }}$ and notebooks. The high performance DCS-Control ${ }^{T M}$ architecture provides fast transient response as well as high output voltage accuracy.

With a wide operating input-voltage range of 3 to 17 V , the devices are ideally suited for systems powered from either a Li-lon or other batteries as well as from $12-\mathrm{V}$ intermediate power rails. The devices have a low-power mode where the output voltage is reduced by using the LPM pin. In addition, the devices support dynamic output-voltage change by using the VIDx pins. The $\overline{L P M}$ and VIDx pins help the system minimize power consumption in different operating modes.

The output-voltage startup ramp is controlled by the SS pin. The power sequencing is configurable by the enable (EN) and power good (PG) pins. In powersave mode, the devices show quiescent current of approximately $20 \mu \mathrm{~A}$ which maintains high efficiency over the entire load range. Short circuit protection and thermal shutdown protect the IC and external components from heavy current when the output is shorted to ground. The device is available in a $3-\mathrm{mm}$ $\times 3-\mathrm{mm}$ 16-pin VQFN package with thermal pad.

## Device Information ${ }^{(1)}$

| PART NUMBER | PACKAGE | BODY SIZE (NOM) |
| :--- | :--- | :--- |
| TPS62134A |  |  |
| TPS62134B | VQFN | $3.00 \mathrm{~mm} \times 3.00 \mathrm{~mm}$ |
| TPS62134C |  |  |
| TPS62134D |  |  |

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Application Circuit



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## 4 Revision History

Changes from Revision D (April 2015) to Revision E Page

- Added Note to Power-Good Output (PG). PG blanking time condition for TPS62134A and TPS62134C ..... 9
Changes from Revision C (January 2015) to Revision D Page
- Added the Program Output Voltage with External Resistor Divider section ..... 14
Changes from Revision B (August 2014) to Revision C Page
- Changed the Device Information table ..... 1
- Added the Device Comparison Table ..... 3
- Moved the Storage temperature From the Handling Ratings table to the Absolute Maximum Ratings ${ }^{(1)}$ table. ..... 4
- Changed the Handling Ratings table to the ESD Ratings table ..... 4
- Changed the Output voltage accuracy, PSM mode MAX value From: $2 \%$ To: $3 \%$, Add test condition: $\overline{\mathrm{LPM}}=$ High. ..... 5
Changes from Revision A (August 2014) to Revision B Page
- Add new device to Device Comparison Table ..... 3
- Updated the Functional Block Diagram image ..... 7
- Add new device to Table 1 ..... 9
- Updated the Figure 16 in the Application Curves section ..... 15
- Updated Equation 8 ..... 17
Changes from Original (August 2014) to Revision A Page
- Switched the pin names of pin 8 and 9 in the Pin Functions table ..... 3


## 5 Device Comparison Table

| PART NUMBER | PACKAGE MARKING |  |
| :--- | :--- | :--- |
| TPS62134A | OUTPUT VOLTAGE |  |
| TPS62134B | 134 A |  |
| TPS62134C | 134 B |  |
| TPS62134D | See Table 1 |  |

## 6 Pin Configuration and Functions

RGT Package
16-Pin VQFN With Thermal Pad
Top View


Pin Functions

| PIN |  | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :---: |
| NO. | NAME |  |  |
| 1 | VOS | 1 | Output voltage sense pin and connection for the control loop circuitry. The VOS pin must be connected directly at the output capacitor. |
| 2 | SW | PWR | This pin is a switch node and is connected to the internal MOSFET switches. Connect an inductor between the SW pin and output capacitor. |
| 4 | PG | 0 | Output power-good pin. The PG pin is an open drain and requires a pullup resistor. If this pin is not in use, leave it floating. |
| 5 | FBS | 1 | Output-voltage feedback pin. This pin is used for a positive remote sense of the load voltage. The FBS pin must be connected close to the load-supply node on the output bus. |
| 6 | AGND | - | Analog ground pin. The AGND pin must be connected directly to the exposed thermal pad and common ground plane. |
| 7 | SS | 0 | Soft-start pin. An external capacitor connected to this pin sets the soft-start time. |
| 8 | VID1 | 1 | Output-voltage selection pins (VIDx). |
| 9 | VID0 |  |  |
| 10 | AVIN | 1 | Supply-voltage pin for the internal control circuitry. Connect the AVIN pin to the same source as the PVIN pin. |
| 11 | PVIN | PWR | Supply-voltage pins for the internal power stage. |
| 12 |  |  |  |
| 13 | EN | 1 | Enable and disable input pin. An internal pulldown resistor maintains logic-level low if the pin is floating. |
| 14 | $\overline{\text { LPM }}$ | 1 | Low-power-mode input pin. |
| 15 | PGND | - | Power ground. The PGND pin must be connected directly to the exposed thermal pad and common ground plane. |
| 16 |  |  |  |
| - | Exposed Thermal Pad | - | The exposed thermal pad must be connected to the AGND (6) pin, PGND (15 and 16) pins, and common ground plane. The thermal pad must be soldered to achieve appropriate power dissipation and mechanical reliability. |

## 7 Specifications

### 7.1 Absolute Maximum Ratings ${ }^{(1)}$

over operating junction temperature range (unless otherwise noted)

|  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| Voltage at pins ${ }^{(2)}$ | AVIN, PVIN | -0.3 | 20 | V |
|  | EN, SW | -0.3 | $\mathrm{V}_{1}+0.3$ |  |
|  | SS, PG, VOS, VID0, VID1, $\overline{\text { LPM }}$ | -0.3 | 7 |  |
|  | FBS | -0.3 | 3 |  |
| Sink current | PG | 0 | 2 | mA |
| Operating junction temperature, $\mathrm{T}_{J}$ |  | -40 | 150 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature, $\mathrm{T}_{\text {stg }}$ |  | -65 | 150 | ${ }^{\circ} \mathrm{C}$ |

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values are with respect to network ground pin.

### 7.2 ESD Ratings

|  |  |  | VALUE | UNIT |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ${ }^{(1)}$ | $\pm 2000$ |  |
| $\mathrm{V}_{\text {(ESD) }}$ | Electrostatic discharge | Charged device model (CDM), per JEDEC specification JESD22C101 ${ }^{(2)}$ | $\pm 500$ | V |

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommend Operating Conditions

over operating junction temperature range, unless otherwise noted.

|  |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{1}$ | Input voltage (AVIN, PVIN) |  | 3 | 17 | V |
| $\mathrm{V}_{(\mathrm{PG})}$ | PG pin pullup resistor voltage |  | 0 | 6 | V |
| 10 | Output current | $3 \mathrm{~V} \leq \mathrm{V}_{1}<5 \mathrm{~V}$ | 0 | 3 | A |
|  |  | $5 \mathrm{~V} \leq \mathrm{V}_{1} \leq 17 \mathrm{~V}$ | 0 | 3.2 |  |
| $\mathrm{T}_{\mathrm{J}}$ | Operating junction temperature |  | -40 | 125 | ${ }^{\circ} \mathrm{C}$ |

### 7.4 Thermal Information

|  |  |  |
| :--- | :---: | :---: |
|  |  | TPS62134x |

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report.

### 7.5 Electrical Characteristic

$\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ and $\mathrm{V}_{1}=3 \mathrm{~V}$ to 17 V . Typical values at $\mathrm{V}_{1}=12 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{J}}=25^{\circ} \mathrm{C}$, unless otherwise noted.

|  | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SUPPLY |  |  |  |  |  |  |
| $V_{1}$ | Input voltage range |  | 3 |  | 17 | V |
| $\mathrm{I}_{Q}$ | Operating quiescent current | EN = High, no load, device not switching $\mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |  | 20 | 35 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{T}_{\mathrm{J}}=125^{\circ} \mathrm{C}$ |  |  | 58 |  |
| ISD | Shutdown current into AVIN and PVIN | $\begin{aligned} & \mathrm{EN}=\text { Low } \\ & \mathrm{T}_{\mathrm{J}}=-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C} \end{aligned}$ |  | 2 | 9 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{T}_{\mathrm{J}}=125^{\circ} \mathrm{C}$ |  |  | 18 |  |
| $\mathrm{V}_{\text {(UVLO) }}$ | Undervoltage lockout threshold | $\mathrm{V}_{1}$ falling | 2.6 | 2.7 | 2.8 | V |
|  |  | $V_{1}$ rising | 2.8 | 2.9 | 3 |  |
| $\mathrm{T}_{\text {SD(th) }}$ | Thermal shutdown threshold | $\mathrm{T}_{J}$ rising |  | 160 |  |  |
| $\mathrm{T}_{\text {SD(hys) }}$ | Thermal shutdown hysteresis | $\mathrm{T}_{\mathrm{J}}$ falling |  | 20 |  |  |

CONTROL (EN, SS, PG, VIDx, $\overline{\text { LPM }}$ )

| $\mathrm{V}_{1 \mathrm{H}}$ | High-level input threshold voltage (EN, VIDx, $\overline{\text { LPM }}$ ) |  | 0.8 | 0.54 |  | V |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VIL | Low-level input threshold voltage (EN, VIDx, $\overline{\text { LPM }}$ ) |  |  | 0.47 | 0.3 | V |
| $\mathrm{R}_{\text {(PD) }}$ | Pull down resistor at EN, VIDx, $\overline{\text { LPM }}$ | EN, VIDx, $\overline{\text { LPM }}=$ low |  | 400 |  | $\mathrm{k} \Omega$ |
| $\mathrm{R}_{\text {(DIS) }}$ | Output discharge resistor | $\mathrm{EN}=$ Low, $\mathrm{V}_{\mathrm{O}}=1 \mathrm{~V}$ |  | 20 |  | $\mathrm{k} \Omega$ |
| 1 lkg | Input leakage current at EN, VIDx, $\overline{\text { LPM }}$ | EN, VIDx, $\overline{\text { LPM }}=3.3 \mathrm{~V}$ |  | 0.01 | 1 | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {TH(PG) }}$ | Power good threshold DC voltage | $\mathrm{V}_{\mathrm{O}}$ rising | 736 | 760 | 784 | mV |
|  |  | $\mathrm{V}_{\mathrm{O}}$ falling | 696 | 720 | 752 |  |
| $\mathrm{V}_{\mathrm{OL}(\mathrm{PG})}$ | Power good output low voltage | $\mathrm{I}_{(\mathrm{PG})}=-2 \mathrm{~mA}$ |  | 0.07 | 0.3 | V |
| $\mathrm{l}_{\mathrm{kg}(\mathrm{PG})}$ | Input leakage current at PG | $\mathrm{V}_{(\mathrm{PG})}=1.8 \mathrm{~V}$ |  | 1 | 400 | nA |
| $\mathrm{t}_{\mathrm{d}(\mathrm{PG})}$ | Power good delay time | PG rising |  | 140 |  | $\mu \mathrm{s}$ |
|  |  | PG falling |  | 20 |  |  |
| ${ }^{\prime}$ (SS) | SS pin source current |  | 2.3 | 2.5 | 2.7 | $\mu \mathrm{A}$ |
| POWER SWITCH |  |  |  |  |  |  |
| $\mathrm{r}_{\text {DS(on_H) }}$ | High-side MOSFET on-resistance | $\mathrm{V}_{1} \geq 6 \mathrm{~V}$ |  | 90 | 170 | $\mathrm{m} \Omega$ |
| $\mathrm{r}_{\text {DS }}^{\text {(on } \_ \text {L) }}$ | Low-side MOSFET on-resistance | $\mathrm{V}_{1} \geq 6 \mathrm{~V}$ |  | 40 | 70 |  |
| LL | High-side MOSFET DC current-limit | $\mathrm{V}_{1} \geq 5 \mathrm{~V}, \mathrm{~T}_{\mathrm{J}}=25^{\circ} \mathrm{C}$ | 3.6 | 4.4 | 5.4 | A |
| L(LOW) | High-side MOSFET DC current-limit at low output voltage | $\mathrm{V}_{\mathrm{O}} \leq 0.3 \mathrm{~V}$ |  | 1.6 |  |  |
| OUTPUT |  |  |  |  |  |  |
| $\mathrm{l}_{\mathrm{kgg}}$ (FBS) | Input leakage current at FBS | $\mathrm{V}_{(\mathrm{FBS})}=1.1 \mathrm{~V}$ |  | 1 | 100 | nA |
| $\mathrm{V}_{\mathrm{O}(\mathrm{A})}$ | Output voltage accuracy | PWM mode | -1\% |  | 1\% |  |
|  |  | PSM mode, $\overline{\text { LPM }}=\operatorname{High}^{(1)}$ | -1\% |  | 3\% |  |
| $\Delta \mathrm{V}_{\mathrm{O}(\Delta 1 \mathrm{O})}$ | Load regulation ${ }^{(2)}$ | $\mathrm{V}_{\mathrm{I}}=7.2 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}=0.5 \mathrm{~A}$ to 3.2 A | 0.01 |  |  | \%/A |
| $\Delta \mathrm{V}_{\mathrm{O}(\Delta \mathrm{VI})}$ | Line regulation ${ }^{(2)}$ | $3 \mathrm{~V} \leq \mathrm{V}_{1} \leq 17 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}=1 \mathrm{~A}$ | 0.003 |  |  | \%/V |

(1) This is the accuracy provided by the device itself (line and load regulation effects are not included). External components effective value: $\mathrm{L}=1 \mu \mathrm{H}$ and $\mathrm{C}_{\text {(OUT) }}=47 \mu \mathrm{~F}$.
(2) Line and load regulation depend on external component selection and layout.

### 7.6 Typical Characteristics



Figure 1. Quiescent Current into PVIN and AVIN


Figure 2. Shutdown Current into PVIN and AVIN

## 8 Detailed Description

### 8.1 Overview

The TPS62134x synchronous switched-mode power converters are based on DCS-Control ${ }^{\text {TM }}$ (direct control with seamless transition into power-save mode), an advanced regulation topology that combines the advantages of hysteretic, voltage-mode, and current-mode control including an AC loop that is directly associated to the output voltage. This control loop uses information about output voltage changes and feeds the information directly to a fast comparator stage. The control loop provides immediate response to dynamic load changes. For accurate DC load regulation, a voltage feedback loop is used. The internally compensated regulation network achieves fast and stable operation with small external components and low ESR capacitors.
The DCS-Control ${ }^{T M}$ topology supports PWM (pulse width modulation) mode for medium and heavy load conditions and a power-save mode (PSM) at light loads. During PWM mode, the devices operate at the nominal switching frequency in continuous conduction mode (CCM). This frequency is approximately 1 MHz (typical) with a controlled frequency variation depending on the input voltage. If the load current decreases, the converter enters PSM to sustain high efficiency down to very light loads. In PSM, the switching frequency decreases linearly with the load current. Because DCS-Control ${ }^{T M}$ supports both operation modes within one single building block, the transition from PWM to PSM is seamless without effects on the output voltage.

### 8.2 Functional Block Diagram



### 8.3 Feature Description

### 8.3.1 Enable and Shutdown (EN)

When the EN pin is set high, the device begins operation. The EN pin allows sequencing from a host or powergood output of another device.
The devices enter shutdown mode if the EN pin is pulled low with a shutdown current of $2 \mu \mathrm{~A}$ (typical). During shutdown, the internal power MOSFETs as well as the entire control circuitry are turned off. The output capacitor is smoothly discharged by a $20-\mathrm{k} \Omega$ internal resistor through the VOS pin. An internal pulldown resistor of approximately $400 \mathrm{k} \Omega$ is connected and maintains EN logic low, if the pin is floating. The pulldown resistor is disconnected if the EN pin is high.

### 8.3.2 Undervoltage Lockout (UVLO)

If the input voltage drops, the undervoltage lockout prevents misoperation of the device by switching off both power MOSFETs. The UVLO threshold is set to 2.7 V (typical). The device is fully operational for voltages above the UVLO threshold and turns off if the input voltage trips the threshold. The converter begins operation again when the input voltage exceeds the threshold by a hysteresis of 200 mV (typical).

### 8.3.3 Soft-Start (SS) Circuitry

The internal soft-start circuitry controls the output-voltage slope during startup. This control avoids excessive inrush current and ensures a controlled output-voltage rise time. The control also prevents unwanted voltage drops from high-impedance power sources or batteries. When the EN pin is set high to begin device operation, the device begins switching after a delay of approximately $50 \mu \mathrm{~s}$ and $\mathrm{V}_{0}$ rises up to the nominal value set by the VIDx pins with a slope controlled by an external capacitor connected to the SS pin. Leave the SS pin floating for the fastest startup.

The device can startup into a pre-biased output. During monotonic pre-biased startup, both power MOSFETs are not allowed to turn on until the internal ramp of the device sets an output voltage above the pre-bias voltage.
If the device is in shutdown mode, undervoltage lockout, or thermal shutdown, an internal resistor pulls the SS pin down to ensure a proper low level. Returning from those states causes a new startup sequence.

### 8.3.4 Switch Current-Limit and Short Circuit Protection

The TPS62134x family of devices is protected against heavy load and short circuit events. If an output short circuit is detected ( $\mathrm{V}_{\mathrm{O}}$ drops below 0.3 V ), the switch current limit is reduced to 1.6 A (typical). If the output voltage rises above 0.4 V , the device operates in normal operation again.
At heavy loads, the current-limit determines the maximum output current. The current-limit supports output currents of 3 A with input voltages below 5 V and 3.2 A with higher input voltages. If the peak current-limit ( $\mathrm{I}_{\mathrm{L}}$ ) is reached, the high-side MOSFET is turned off. Avoiding shoot-through current, the low-side MOSFET is switched on to sink the inductor current. The high-side MOSFET turns on again, only if the current in the low-side MOSFET has decreased below the low-side current-limit threshold of 3.2 A (typical).
Because of the internal propagation delay, the actual peak current of the high-side switch typically occurs above the DC value listed in the Electrical Characteristic table, especially in low duty-cycle applications. Use Equation 1 to calculate the dynamic current-limit.

$$
\begin{equation*}
\mathrm{L}_{\mathrm{L}(\text { dynamic })}=\mathrm{I}_{\mathrm{L}}+\frac{\mathrm{V}_{\mathrm{I}}-\mathrm{V}_{\mathrm{O}}}{\mathrm{~L}} \times 30 \mathrm{~ns} \tag{1}
\end{equation*}
$$

### 8.3.5 Output Voltage and LPM Logic Selection (VIDx and $\overline{\text { LPM }}$ )

The output voltage of the TPS62134x family of devices is selected by two VIDx pins and one $\overline{\mathrm{LPM}}$ pin as listed in Table 1. A pulldown resistor of $400 \mathrm{k} \Omega$ is internally connected to the VIDx pins and $\overline{\text { LPM }}$ pin to ensure a proper logic level if the pin is high impedance or floating. The pulldown resistors are disconnected if the pins are pulled High.

## Feature Description (continued)

The device has a low power mode (LPM) where the output voltage is reduced or disabled by using the $\overline{\mathrm{LPM}}$ pin. While the LPM pin is asserted, the PG output remains high impedance. The device also achieves a dynamic output-voltage change by using the VIDx pins. This feature helps the system to minimize power consumption in standby or idle mode. The TPS62134B/D devices provide the full current even if the output voltage is set at 0.7 V in LPM mode.

Table 1. Output Voltage Selection

| PART NUMBER <br> (INTEL SKYLAKE VRs) | $\overline{\text { LPM LOGIC }}$ | VID1 LOGIC | VIDO LOGIC | OUTPUT VOLTAGE (V) |
| :---: | :---: | :---: | :---: | :---: |
| TPS62134A <br> ( $\mathrm{V}_{\mathrm{CC}(I)}$ Rail) | 0 | x | x | 0 (LPM) |
|  | 1 | 0 | 0 | 0.850 |
|  | 1 | 0 | 1 | 0.875 |
|  | 1 | 1 | 0 | 0.950 |
|  | 1 | 1 | 1 | 0.975 |
| TPS62134B <br> ( $\mathrm{V}_{\text {CC(PRIM_CORE) }}$ Rail) | 0 | x | x | 0.7 (LPM) |
|  | 1 | 0 | 0 | 0.80 |
|  | 1 | 0 | 1 | 0.85 |
|  | 1 | 1 | 0 | 0.90 |
|  | 1 | 1 | 1 | 0.95 |
| $\begin{gathered} \text { TPS62134C } \\ \left(\mathrm{V}_{\mathrm{CC}(\text { EDRAM })} / \mathrm{V}_{\mathrm{CC}(\text { EOPIO })} \text { Rail }\right) \end{gathered}$ | 0 | x | x | 0 (LPM) |
|  | 1 | 0 | 0 | 0.80 |
|  | 1 | 0 | 1 | 0.95 |
|  | 1 | 1 | 0 | 1.00 |
|  | 1 | 1 | 1 | 1.05 |
| TPS62134D <br> ( $\mathrm{V}_{\text {CC(PRIM_Core) }}$ Rail) | 0 | x | x | 0.7 (LPM) |
|  | 1 | 0 | 0 | 0.85 |
|  | 1 | 0 | 1 | 0.90 |
|  | 1 | 1 | 0 | 0.95 |
|  | 1 | 1 | 1 | 1.00 |

### 8.3.6 Power-Good Output (PG)

The TPS62134x family of devices has a built-in power-good indicator. The PG signal can be used for startup sequencing of multiple rails. The PG pin is an open-drain output that requires a pullup resistor to any voltage below 6 V . The device has a fixed power-good threshold of 760 mV (rising edge) and 720 mV (falling edge). The PG rising edge has a delay time of $140 \mu \mathrm{~s}$ (typical) and a falling edge has a delay time of $20 \mu \mathrm{~s}$ (typical). The PG pin can sink 2-mA of current and maintain the specified logic low level. Table 2 lists the PG logic status in different operation conditions. The PG pin can be left floating if not used.
In LPM, the PG signal is latched as high impedance. When the device exits LPM, the PG has a $500-\mu s$ blanking time to ensure that the output voltage returns to the nominal value.

## NOTE

For the TPS62134A and TPS62134C, if LPM is exited when the output voltage is between 0.5 V to 0.75 V , the PG pin may not have its $500-\mu \mathrm{s}$ blanking time and may go briefly low as the output voltage returns to its set-point. To avoid this behavior, do not enter LPM or adjust the load and/or output capacitance or add an extra output discharge circuit to avoid this output voltage range when LPM is exited.
The TPS62134A and TPS62134C are not recommended for new Skylake or KabyLake, Intel designs. The TPS62134B or TPS62134D should be used in their place. These parts are pin to pin compatible facilitating a simple replacement. See Table 1 for VID related changes.

Table 2. Power Good Logic

| CONDITIONS |  | PG LOGIC STATUS |  |
| :---: | :---: | :---: | :---: |
|  |  | HIGH IMPEDANCE | LOW |
| Enable | $\mathrm{EN}=$ high, $\overline{\mathrm{LPM}}=$ high, $\mathrm{V}_{\mathrm{O}}>760 \mathrm{mV}$ | $\checkmark$ |  |
|  | $\mathrm{EN}=$ high, $\overline{\mathrm{LPM}}=$ high, $\mathrm{V}_{\mathrm{O}}<720 \mathrm{mV}$ |  | $\checkmark$ |
| LPM | $\mathrm{EN}=$ high, $\overline{\mathrm{LPM}}=$ low | $\checkmark$ |  |
| LPM, TPS62134B/D | $\mathrm{EN}=$ high, $\overline{\mathrm{LPM}}=$ Low, $\mathrm{V}_{\mathrm{O}}<0.3 \mathrm{~V}$ |  | $\checkmark$ |
| Shutdown | EN = Low |  | $\checkmark$ |
| Thermal shutdown |  |  | $\checkmark$ |
| UVLO | $0.5 \mathrm{~V}<\mathrm{V}_{\text {(AVIN) }}<\mathrm{V}_{(\text {UVLO }}$ |  | $\checkmark$ |
| Power supply removal | $\mathrm{V}_{(\mathrm{AVIN})}<0.5 \mathrm{~V}$ | $\checkmark$ |  |

### 8.3.7 Single-Ended Remote Sense (FBS)

The devices allow a single-ended remote sense by connecting the FBS pin at the load. This function overcomes the parasitic resistance of the PCB traces and achieves an improved output-voltage regulation at the load. Avoid any noise coupled into the FBS trace. Use a solid ground plane to connect the ground return of the load with the AGND and PGND pins of the device. Connect the AGND and PGND pins directly to exposed thermal pad of the device. Figure 3 shows an example.


Figure 3. Remote Sense Connection

### 8.3.8 Thermal Shutdown

The junction temperature ( $T_{J}$ ) of the device is monitored by an internal temperature sensor. If $T_{J}$ exceeds $160^{\circ} \mathrm{C}$ (typical), the device goes into thermal shutdown. Both the high-side and low-side power MOSFETs are turned off. When $\mathrm{T}_{j}$ decreases below the hysteresis of $20^{\circ} \mathrm{C}$, the converter resumes normal operation, beginning with a soft start.

### 8.4 Device Functional Modes

### 8.4.1 PWM Operation and Power Save Mode

The device operates with pulse width modulation (PWM) in medium and heavy load with a fixed on-time circuitry $\left(\mathrm{t}_{\mathrm{on}}\right)$. Use Equation 2 to calculate the on-time in steady-state operation.

$$
\begin{equation*}
\mathrm{t}_{\mathrm{on}}=1 \mu \mathrm{~s} \times \frac{\mathrm{V}_{\mathrm{O}}}{\mathrm{~V}_{\mathrm{l}}} \tag{2}
\end{equation*}
$$

The typical PWM switching frequency is 1 MHz . The frequency variation in PWM is controlled and depends on $\mathrm{V}_{\mathrm{I}}, \mathrm{V}_{\mathrm{O}}$, and the inductance. The switching frequency decreases with the input voltage to improve the efficiency in small duty-cycle applications.
To maintain high efficiency at light loads, the device enters PSM at the boundary to discontinuous conduction mode (DCM). In PSM, the switching frequency decreases linearly with the load current maintaining high efficiency. Use Equation 3 to calculate the switching frequency in PSM mode.

$$
\begin{equation*}
f_{\mathrm{S}(\mathrm{PSM})}=\frac{2 \times \mathrm{I}_{\mathrm{O}}}{\mathrm{t}_{\mathrm{on}}{ }^{2} \times \frac{V_{1}}{V_{\mathrm{O}}} \times \frac{\mathrm{V}_{1}-\mathrm{V}_{\mathrm{O}}}{\mathrm{~L}}} \tag{3}
\end{equation*}
$$

See Figure 12 for the switching frequency variation over load and input voltage.

## 9 Application and Implementation

## NOTE

Information in the following applications sections is not part of the Tl component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The TPS62134x family of devices are synchronous step-down converters based on the DCS-Control ${ }^{\text {TM }}$ topology. The following section discusses the design of the external components to complete the power-supply design for power rails in the Intel Skylake platform.

### 9.2 Typical Application



Figure 4. TPS62134A Typical Application

### 9.2.1 Design Requirements

The design guideline provides component selection to operate the device within the values listed in the Recommend Operating Conditions section. Meanwhile, the design meets the time and slew rate requirements of the Intel Skylake platform for $\mathrm{V}_{\mathrm{CC}(I)}$, $\mathrm{V}_{\mathrm{CC}(\text { PRIM_CORE) }}, \mathrm{V}_{\mathrm{CC}(\text { EDRAM) }}$, and $\mathrm{V}_{\mathrm{CC}(E O P I O)}$ rails. Table 3 lists the components used for the curves in the Application Curves section.

Table 3. List of Components

| REFERENCE | DESCRIPTION | MANUFACTURER |
| :---: | :--- | :--- |
| TPS62134x | High efficiency step down converter | TI |
| L 1 | Inductor, $1 \mu \mathrm{H}, \mathrm{XFL4020}$-102ME | Coilcraft |
| C 1 | Ceramic capacitor, $22 \mu \mathrm{~F}$, GRM21BR61E226ME44L | Murata |
| C 2 | Ceramic capacitor, $47 \mu \mathrm{~F}$, GRM21BR60J476ME15L | Murata |
| C 3 | Ceramic capactor, 470 pF, GRM188R71H471KA01D | Murata |
| R3 | Resistor, $499 \mathrm{k} \Omega$ | Standard |

### 9.2.2 Detailed Design Procedure

### 9.2.2.1 Output Filter Selection

The first step of the design procedure is the selection of the output-filter components. The combinations listed in Table 4 are used to simplify the output filter component selection.

Table 4. Recommended LC Output Filter Combinations ${ }^{(1)}$

| INDUCTOR | OUTPUT CAPACITOR |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{2 2} \boldsymbol{\mu} \mathbf{F}$ | $\mathbf{4 7} \boldsymbol{\mu F}$ | $\mathbf{1 0 0} \boldsymbol{\mu F}$ | $\mathbf{2 0 0} \boldsymbol{\mu} \mathbf{F}$ | $\mathbf{4 0 0} \boldsymbol{\mu} \mathbf{F}$ |
| $0.47 \mu \mathrm{H}$ |  |  |  |  |  |
| $1 \mu \mathrm{H}$ |  | $\checkmark(2)$ | $\checkmark$ | $\checkmark$ |  |
| $2.2 \mu \mathrm{H}$ |  |  |  |  |  |

(1) The values in the table are nominal values, including device tolerances.
(2) This LC combination is the standard value and recommended for most applications.

### 9.2.2.2 Inductor Selection

The inductor selection is affected by several effects such as inductor-ripple current, output-ripple voltage, PWM-to-PSM transition point, and efficiency. In addition, the selected inductor must be rated for appropriate saturation current and DC resistance (DCR). Use Equation 4 to calculate the maximum inductor current under static load conditions.

$$
\begin{aligned}
& \mathrm{I}_{(\mathrm{L})} \max =\mathrm{I}_{\mathrm{O}} \max +\frac{\Delta \mathrm{l}_{(\mathrm{L})} \max }{2} \\
& \Delta \mathrm{I}_{(\mathrm{L})} \max =\frac{\mathrm{V}_{\mathrm{O}}}{\mathrm{~L}_{\min } \times f_{\mathrm{S}}} \times\left(1-\frac{\mathrm{V}_{\mathrm{O}}}{\mathrm{~V}_{\mathrm{I}}}\right)
\end{aligned}
$$

where

- $I_{(L)}$ max is the maximum inductor current
- $\Delta_{(L)}$ max is the maximum peak-to-peak inductor ripple current
- $L_{\text {min }}$ is the minimum effective inductor value
- $f_{\mathrm{s}}$ is the actual PWM switching frequency

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current. A margin of approximately $20 \%$ is recommended to be added. The inductor value also determines the load current at which power save mode is entered:

$$
\begin{equation*}
\mathrm{I}_{\mathrm{O}(\mathrm{PSM})}=\frac{\Delta \mathrm{l}_{(\mathrm{L})}}{2} \tag{5}
\end{equation*}
$$

Table 5 lists inductors that are recommended to use with the TPS62134x device.
Table 5. List of Inductors

| TYPE | INDUCTANCE $(\mu \mathrm{H})$ | CURRENT (A) | DIMENSIONS (L $\times \mathbf{B} \times$ <br> $\mathbf{H}, \mathbf{m m})$ | MANUFACTURER |
| :---: | :---: | :---: | :---: | :---: |
| XFL4020-102ME | $1 \mu \mathrm{H}$ | 4.7 | $4 \times 4 \times 2$ |  |
| DFE252012F | $1 \mu \mathrm{H}$ | 5.0 | $2.5 \times 2 \times 1.2$ | Coilcraft |
| DFE201612E | $1 \mu \mathrm{H}$ | 4.1 | $2 \times 1.6 \times 1.2$ | Toko |
| PISB25201T | $1 \mu \mathrm{H}$ | 3.9 | $2.5 \times 2 \times 1$ | Toko |
| PIME031B | $1 \mu \mathrm{H}$ | 5.4 | $3.1 \times 3.4 \times 1.2$ | Cyntec |

### 9.2.2.3 Output Capacitor

The recommended value for the output capacitor is $47 \mu \mathrm{~F}$. The architecture of the TPS62134x family of devices allows the use of tiny ceramic output capacitors which have low equivalent series resistance (ESR). These capacitors provide low output-voltage ripple and are recommended. Using an X7R or X5R dielectric is recommended to maintain low resistance up to high frequencies and to achieve narrow capacitance variation with temperature. Using a higher value can have some advantages such as smaller voltage ripple and a tighter DC output accuracy in PWM. See Optimizing the TPS62130/40/50/60/70 Output Filter, SLVA463 for additional information.

Note that in power save mode, the output voltage ripple depends on the output capacitance, ESR, and peak inductor current. Using ceramic capacitors provides small ESR and low ripple.

### 9.2.2.4 Input Capacitor

For most applications, using a capacitor with a value of $22 \mu \mathrm{~F}$ is a recommended. Larger values further reduce input-current ripple. The input capacitor buffers the input voltage for transient events and also decouples the converter from the supply. A ceramic capacitor which has low ESR is recommended for best filtering and should be placed between the PVIN and PGND pins and as close as possible to those pins.

### 9.2.2.5 Soft-Start Capacitor

A capacitor connected between the SS pin and the AGND pin allows a user programmable startup slope of the output voltage. A constant current source supports $2.5 \mu \mathrm{~A}$ to charge the external capacitance. Use Equation 6 to calculate the capacitor value required for a given soft-start time.

$$
\mathrm{C}_{(\mathrm{ss})}=\mathrm{t}_{(\mathrm{ss})} \times \frac{2.5 \mu \mathrm{~A}}{\mathrm{~V}_{\mathrm{O}}}
$$

where

- $\mathrm{C}_{(\mathrm{SS})}$ is the capacitance ( F ) required at the SS pin
- $\mathrm{t}_{(\mathrm{SS}}$ is the desired soft-start time (s)

Leave the SS pin floating for fastest startup.

### 9.2.2.6 Program Output Voltage with External Resistor Divider

The TPS62134x family of devices extends the output voltage range by an external resistor divider, shown in Figure 5. The output voltage is then set by Equation 7.

$$
V_{O}=V_{F B S} \times\left(1+\frac{R 1}{R 2}\right)
$$

where

- $\mathrm{V}_{\text {FBS }}$ is the FBS pin voltage setting by the VIDx pins, as shown in Table 1

The maximum output voltage must be less than 1.9 V . The required feed forward capacitor, C 4 , improves the loop stability performance. 5 pF is sufficient for most of applications with the R1 and R2 values shown. R1, R2 and C4 must be located close to the IC.


Figure 5. TPS62134C 1.1-V Output

### 9.2.3 Application Curves

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ and $\mathrm{V}_{\mathrm{I}}=7.2 \mathrm{~V}$, unless otherwise noted.

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ and $\mathrm{V}_{1}=7.2 \mathrm{~V}$, unless otherwise noted.


Figure 12. TPS62134A Switching Frequency


Time $=1 \mu \mathrm{~s} / \mathrm{div}$

$$
\mathrm{V}_{\mathrm{O}}=0.95 \mathrm{~V} \quad \mathrm{I}_{\mathrm{O}}=2 \mathrm{~A}
$$

Figure 14. TPS62134A Output Ripple


Time $=10 \mu \mathrm{~s} / \mathrm{div}$

$$
\mathrm{V}_{\mathrm{O}}=0.95 \mathrm{~V}
$$

Figure 16. TPS62134A Load Transient


Figure 13. TPS62134A Output Ripple


Figure 15. TPS62134A Startup and Shutdown


Time $=50 \mu \mathrm{~s} / \mathrm{div}$
$R_{(\text {LOAD })}=0.47 \Omega$

Figure 17. TPS62134C LPM Entry and Exit
$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ and $\mathrm{V}_{\mathrm{I}}=7.2 \mathrm{~V}$, unless otherwise noted.


Figure 18. TPS62134C Minimum Speed Mode (MSM) Entry and Exit

## 10 Power Supply Recommendations

The device is designed to operate from an input voltage supply range between 3 V and 17 V . Use Equation 8 to calculate the average input current of the TPS62134x device.

$$
\mathrm{I}_{\mathrm{I}}=\frac{1}{\eta} \times \frac{\mathrm{V}_{\mathrm{O}} \times \mathrm{I}_{\mathrm{O}}}{\mathrm{~V}_{\mathrm{I}}}
$$

Ensure that the input power supply has a sufficient current rating for the application.

## 11 Layout

### 11.1 Layout Guidelines

- TI recommends to place all components as close as possible to the device. Ensure that the input capacitor placement is as close as possible to the PVIN and PGND pins of the device.
- The VOS pin is noise sensitive and must be routed short and directly to the output of the output capacitor. This routing minimizes switch node jitter and ensures reliability.
- The direct common-ground connection of the AGND and PGND pins to the exposed thermal pad and the system ground (ground plane) is mandatory. To enhance heat dissipation of the device, the exposed thermal pad should be connected to bottom or internal layer ground planes using vias.
- Use wide and short traces for the main current paths to reduce the parasitic inductance and resistance.
- The capacitor on the SS pin should be placed close to the device and connected directly to those pins and the AGND pin.
- The inductor should be placed close to the SW pins, keeping this area small.
- Finally, the ground of the output capacitor should be located close to the PGND pins of the device.
- See Figure 19 for an example of component placement, routing, and thermal design.


### 11.2 Layout Example



Figure 19. TPS62134x Layout Example

### 11.3 Thermal Considerations

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the powerdissipation limits of a given component.
The following lists three basic approaches for enhancing thermal performance:

- Improving the power dissipation capability of the PCB design
- Improving the thermal coupling of the component to the PCB by soldering the exposed thermal pad
- Introducing airflow in the system

For more details on how to use the thermal parameters, see the application notes, Thermal Characteristics of Linear and Logic Packages Using JEDEC PCB Designs (SZZA017), and Semiconductor and IC Package Thermal Metrics (SPRA953).

## 12 Device and Documentation Support

### 12.1 Device Support

### 12.1.1 Third-Party Products Disclaimer

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### 12.2 Documentation Support

### 12.2.1 Related Documentation

- Optimizing the TPS62130/40/50/60/70 Output Filter, SLVA463
- Semiconductor and IC Package Thermal Metrics, SPRA953
- Thermal Characteristics of Linear and Logic Packages Using JEDEC PCB Designs, SZZA017


### 12.3 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 6. Related Links

| PARTS | PRODUCT FOLDER | TECHNICAL <br> DOCUMENTS | TOOLS \& SOFTWARE |  <br> COMMUNITY |
| :---: | :---: | :---: | :---: | :---: |
| TPS62134A | Click here | Click here | Click here | Click here |
| TPS62134B | Click here | Click here | Click here | Click here |
| TPS62134C | Click here | Click here | Click here | Click here |
| TPS62134D | Click here | Click here | Click here | Click here |

### 12.4 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on Alert me to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.5 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect Tl's views; see TI's Terms of Use.

TI E2E ${ }^{\text {TM }}$ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.
Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 12.6 Trademarks

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### 12.7 Electrostatic Discharge Caution

[^0] during storage or handling to prevent electrostatic damage to the MOS gates.

### 12.8 Glossary

SLYZ022 - TI Glossary.
This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

| Orderable Device | Status <br> (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <br> (2) | Lead/Ball Finish <br> (6) | MSL Peak Temp <br> (3) | Op Temp ( ${ }^{\circ} \mathrm{C}$ ) | Device Marking (4/5) | Samples |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS62134ARGTR | ACTIVE | VQFN | RGT | 16 | 3000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134A | Samples |
| TPS62134ARGTT | ACTIVE | VQFN | RGT | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134A | Samples |
| TPS62134BRGTR | ACTIVE | VQFN | RGT | 16 | 3000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134B | Samples |
| TPS62134BRGTT | ACTIVE | VQFN | RGT | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134B | Samples |
| TPS62134CRGTR | ACTIVE | VQFN | RGT | 16 | 3000 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134C | Samples |
| TPS62134CRGTT | ACTIVE | VQFN | RGT | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134C | Samples |
| TPS62134DRGTR | ACTIVE | VQFN | RGT | 16 | 3000 | Green (RoHS \& no Sb/Br) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134D | Samples |
| TPS62134DRGTT | ACTIVE | VQFN | RGT | 16 | 250 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | NIPDAU | Level-2-260C-1 YEAR | -40 to 85 | 134D | Samples |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free"
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the $<=1000 \mathrm{ppm}$ threshold requirement.
${ }^{(3)}$ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
${ }^{(4)}$ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
${ }^{(5)}$ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
${ }^{(6)}$ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width

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## TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

| Device | Package <br> Type | Package <br> Drawing | Pins | SPQ | Reel <br> Diameter <br> $(\mathbf{m m})$ | Reel <br> Width <br> W1 $(\mathbf{m m})$ | $\mathbf{A 0}$ <br> $(\mathbf{m m})$ | B0 <br> $(\mathbf{m m})$ | K0 <br> $(\mathbf{m m})$ | $\mathbf{P 1}$ <br> $(\mathbf{m m})$ | $\mathbf{W}$ <br> $(\mathbf{m m})$ | Pin1 <br> Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS62134ARGTR | VQFN | RGT | 16 | 3000 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134ARGTT | VQFN | RGT | 16 | 250 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134BRGTR | VQFN | RGT | 16 | 3000 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134BRGTR | VQFN | RGT | 16 | 3000 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134BRGTT | VQFN | RGT | 16 | 250 | 180.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134BRGTT | VQFN | RGT | 16 | 250 | 180.0 | 12.5 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134CRGTR | VQFN | RGT | 16 | 3000 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134CRGTT | VQFN | RGT | 16 | 250 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134DRGTR | VQFN | RGT | 16 | 3000 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |
| TPS62134DRGTT | VQFN | RGT | 16 | 250 | 330.0 | 12.4 | 3.3 | 3.3 | 1.1 | 8.0 | 12.0 | Q2 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TPS62134ARGTR | VQFN | RGT | 16 | 3000 | 338.0 | 355.0 | 50.0 |
| TPS62134ARGTT | VQFN | RGT | 16 | 250 | 338.0 | 355.0 | 50.0 |
| TPS62134BRGTR | VQFN | RGT | 16 | 3000 | 338.0 | 355.0 | 50.0 |
| TPS62134BRGTR | VQFN | RGT | 16 | 3000 | 552.0 | 367.0 | 36.0 |
| TPS62134BRGTT | VQFN | RGT | 16 | 250 | 552.0 | 185.0 | 36.0 |
| TPS62134BRGTT | VQFN | RGT | 16 | 250 | 205.0 | 200.0 | 33.0 |
| TPS62134CRGTR | VQFN | RGT | 16 | 3000 | 338.0 | 355.0 | 50.0 |
| TPS62134CRGTT | VQFN | RGT | 16 | 250 | 338.0 | 355.0 | 50.0 |
| TPS62134DRGTR | VQFN | RGT | 16 | 3000 | 338.0 | 355.0 | 50.0 |
| TPS62134DRGTT | VQFN | RGT | 16 | 250 | 338.0 | 355.0 | 50.0 |



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.


NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.


SOLDER MASK DETAILS

NOTES: (continued)
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.


NOTES: (continued)
6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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[^0]:    These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam

