

DRV8860 Customer Evaluation Module

This user guide for the DRV8860 customer evaluation module (EVM) supplements the DRV8860 device. It details the hardware and GUI implementation of the EVM. DRV8860 EVM is a complete solution for evaluating the DRV8860 8-channel serial-interface low-side driver.

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1 Introduction

The evaluation module includes two DRV8860 devices in a daisy-chain connection and an on-board MSP430F2350 microcontroller (MCU). A USB-to-UART interface on the board allows communication between the PC and the EVM. To setup the evaluation functions, connect the device with a USB wire to a computer USB port, apply 8-V to 38-V VM power to EVM, and install and launch the GUI software. The following functions are available through the DRV8860 device evaluation:

- Send specific output data from GUI to DRV8860.
- Read back the output states of DRV8860 and display on GUI.
- Read back the fault register of DRV8860 and display on GUI.
- Enable or disable the output of DRV8860 via GUI.
- Send control register including the energizing time and PWM duty to DRV8860.
- Provide an optional VM switch and can be controlled via GUI.
- Run four unipolar stepper motors with direction and micro-stepping (full or half) control.
- Send the same output pattern to up to 255 DRV8860 devices in daisy-chain connection.

After the functions are evaluated on this EVM, the board can separate the two DRV8860 circuits from the main board. This separation allows customers to apply their own systems for quick prototype verification. The board has spare connector pins, GPIOs, switches, and LEDs for customized tests or re-development.

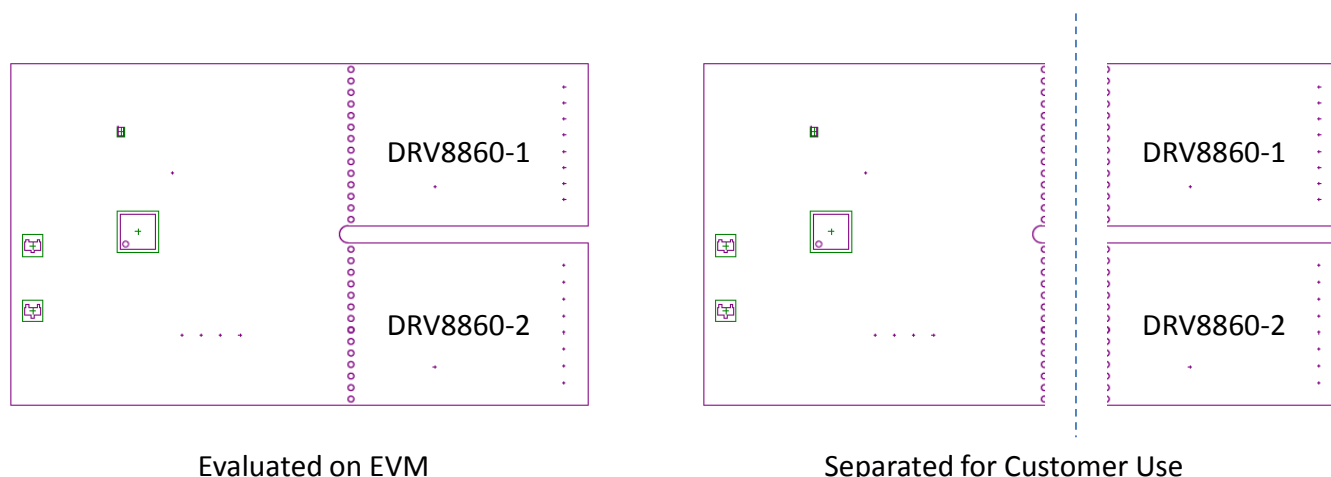


Figure 1. Two Evaluation Methods for the EVM Board

2 EVM Hardware

2.1 PCB Overview

The EVM is 60 mm × 101 mm, The DRV8860 sub-module is 28 mm × 41 mm after separation. Refer to the following views of the top and bottom of the circuit board.

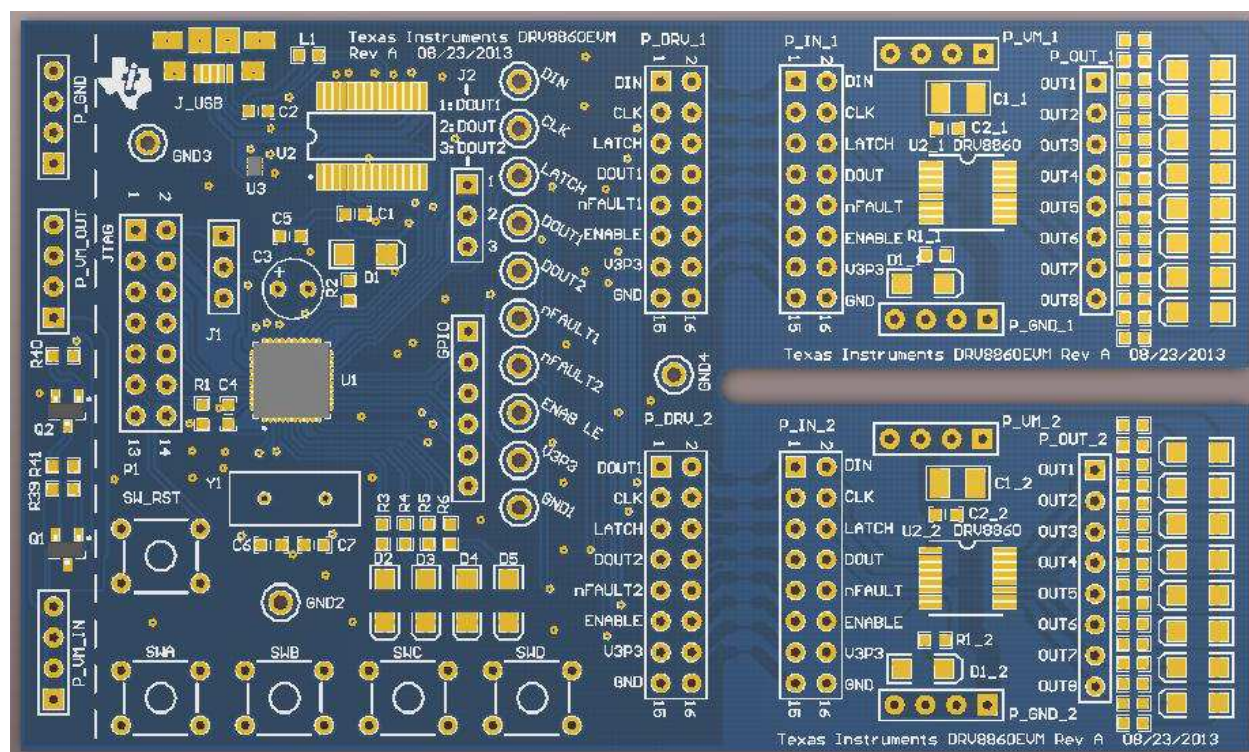


Figure 2. Top View

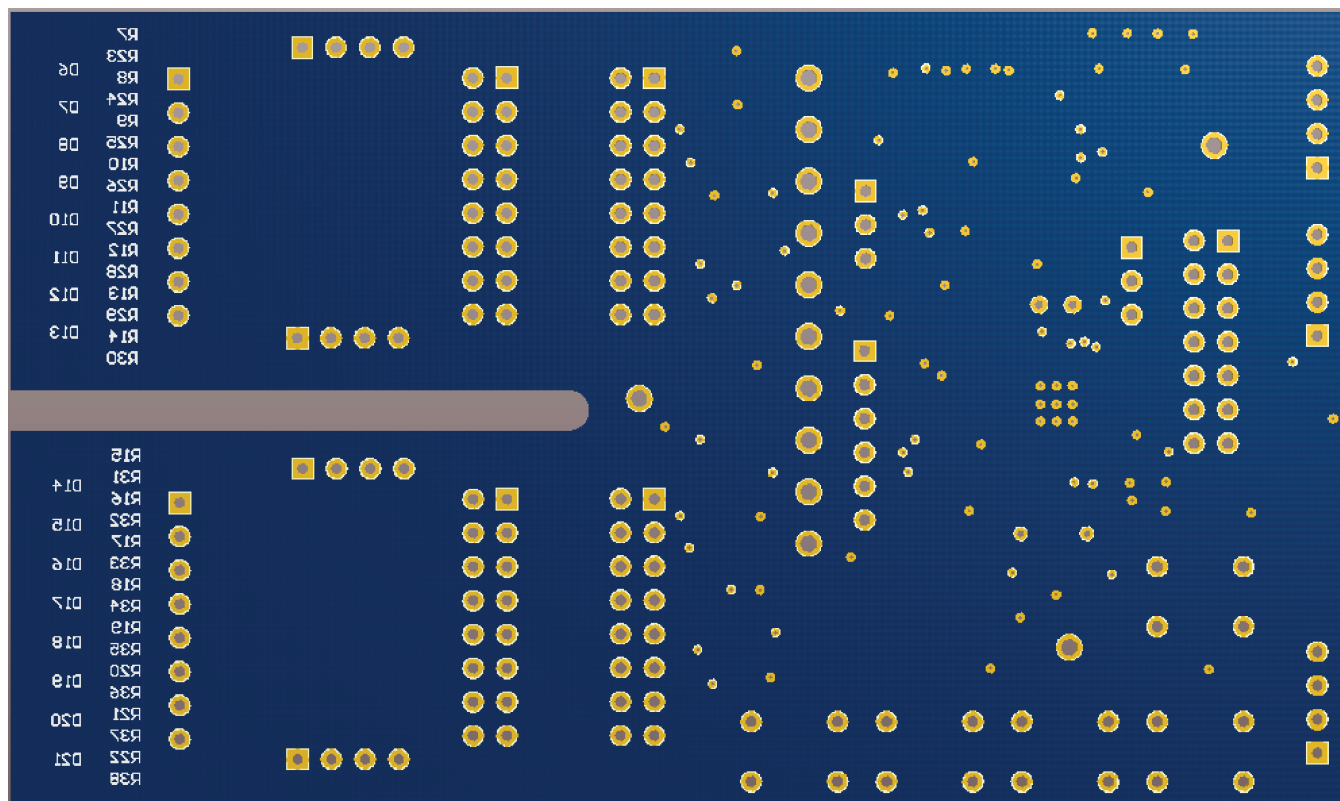


Figure 3. Bottom View (Includes Overlay of Output LEDs and Resistors)

2.2 EVM Connections

The evaluation module includes six connections.

- Power connection
- Optional VM switch connection
- Computer USB connection
- Normal-load connection
- LED-load connection
- Motor-load connection

2.2.1 Power Connection

TI recommends a lab power supply within the 8-V to 38-V range and a 2-A current limit function for the evaluation process.



DRV8860 has an on-chip open-load detect function. This function causes an additional 30- μ A current consumption by each channel. An optional VM switch on the board shuts down the DRV8860 circuit from the power supply.



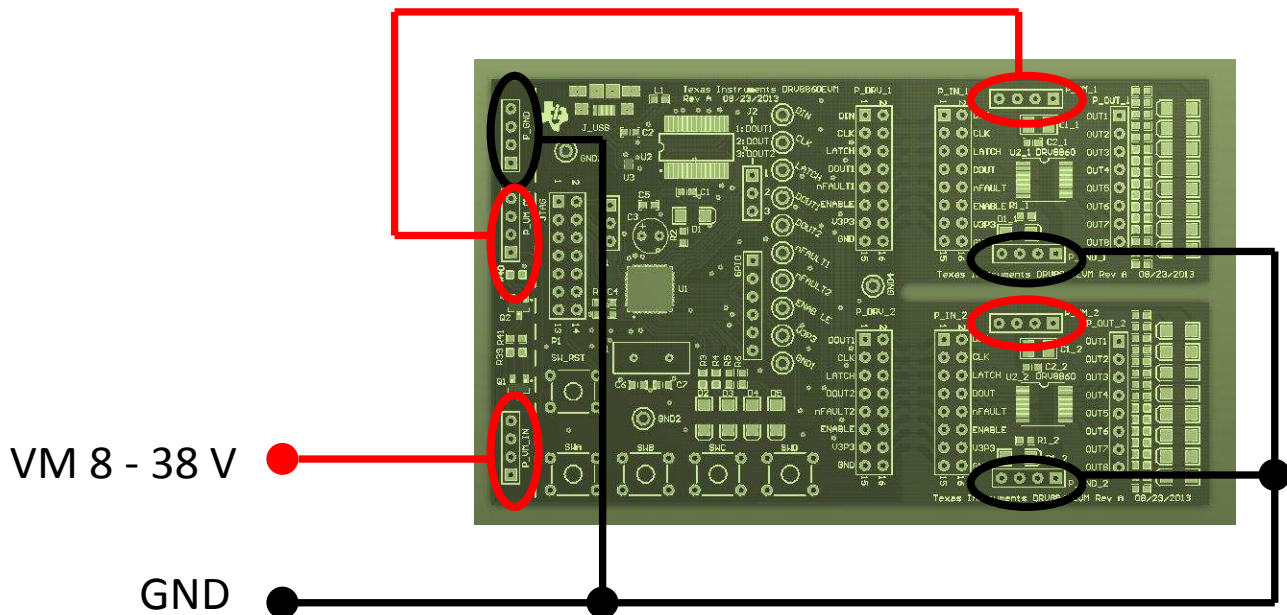


Figure 6. Connected Power Supply With the VM Switch

2.2.3 Computer USB Connection

Use the micro-USB wire along with the EVM kit to connect to any computer with the USB-to-UART interface driver already installed. (Refer to [Section 3.2](#) to learn how to install the driver.) This USB connection serves as the data transfer as well as the 5-V power supply for the on-board FT232 part and the 3.3-V out of the FT232 to the MSP430 MCU.

After the USB wire connects, LED D1 starts flashing.

2.2.4 Load Connection

Eight LEDs serve as virtual load indicators on the board. Other loads such as relays, solenoids, heaters, bulbs, and motors can connect between each of the outputs to VM in a single connection or parallel. Refer to the DRV8860 device specifications for more information on current capability and power consumption.

2.2.5 LED Load Connection

If the LED is driven (similar to the EVM) beside the current-limit resistor, TI recommends connecting an additional resistor of 27 k Ω from the output to the VM. During the output off state, the open-load detection circuit inside DRV8860 sinks 30 μ A from the load path. Although the 30- μ A current is low, it causes the LED to emit a dim light during the off state. A 27 k Ω bypass resistor clamps the voltage drop to < 1 V in 30- μ A condition, so that the LED can be totally shut off because 1 V does not suffice to reach the light threshold for most types of LED.

2.2.6 Motor Connection

For the unipolar motor connection, connect the motor wires to the driver (see [Figure 7](#)) to get the motor driven properly with the sequence built in the firmware of the MCU on board. (The unipolar motor is not included in the EVM kit. The current of the motor should be within the OCP 500-mA range. For example, if VM is 12 V, the DC resistance of the motor phase-to-CT should > 24 Ω).

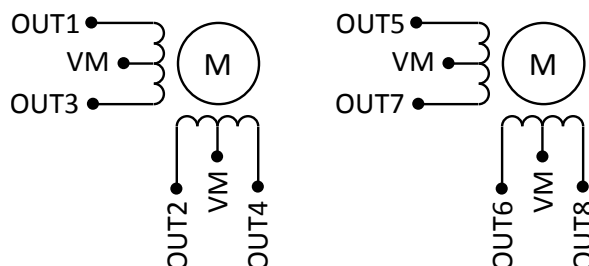


Figure 7. Unipolar Motor Connection (Identical for 1 and 2)

2.3 Jumper

The only jumper in the EVM is J2. See [Figure 8](#) for jumper settings.

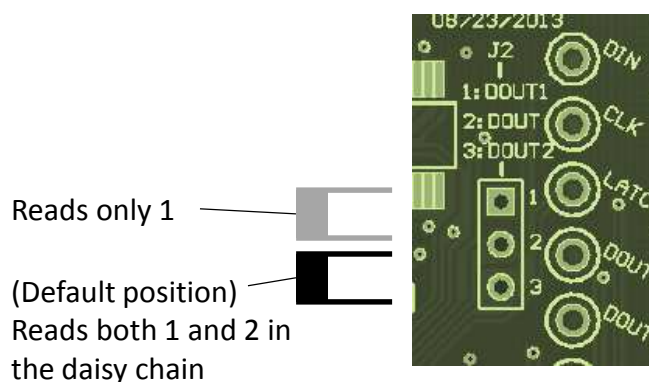


Figure 8. Jumper Settings

2.4 Test Points

All the test points on EVM have clear labels beside them. The dual header can be both a connection and test point. All test points (or pins) with the same label are physically connected and have the same net. GND, GND1, GND2, GND3, and GND4 have the same net GND.

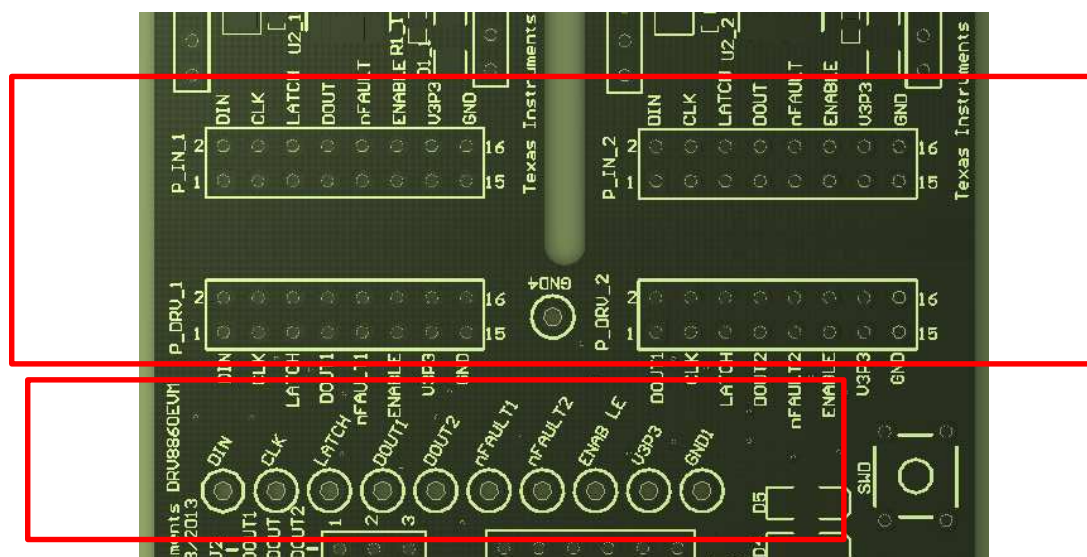
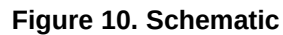


Figure 9. Test Points in the EVM

2.5 Schematic

For a more detailed schematic, refer to the schematic file in the EVM reference package.



2.6 Bill of Materials

Items	Designator	Vendor	Vendor Part #	Quantity	Description
1	C1, C2, C4, C5	Digi-Key	311-1341-1-ND	4	CAP CER 0.1UF 25V 10% X7R 0603
2	C1_1, C1_2	Digi-Key	587-3248-1-ND	2	CAP CER 10UF 50V 20% X5R 1206
3	C2_1, C2_2	Digi-Key	311-1343-1-ND	2	CAP CER 0.1UF 50V Y5V 0603
4	C3	Digi-Key	493-1057-ND	1	CAP ALUM 10UF 25V 20% RADIAL
5	C6, C7	Digi-Key	478-6211-1-ND	2	CAP CER 33PF 16V 5% X7R 0603
6	CLK, DIN, DOUT1, DOUT2, ENAB LE, LATCH, nFAULT1, nFAULT2, V3P3	Digi-Key	5007K-ND	9	TEST POINT PC COMPACT .063"D WHT
7	GND1, GND2, GND3, GND4	Digi-Key	5006K-ND	4	TEST POINT PC COMPACT .063"D BLK
8	D1, D2, D3, D4, D5	Digi-Key	P11532CT-ND	5	LED RED FACE UP 1206
9	D1_1	Digi-Key	P11532CT-ND	1	LED RED FACE UP 1206
10	D1_2	Digi-Key	P11532CT-ND	1	LED RED FACE UP 1206
11	D6, D7, D8, D9, D10, D11, D12, D13, D14, D15, D16, D17, D18, D19, D20, D21	Digi-Key	P11532CT-ND	16	LED RED FACE UP 1206
12	GPIO	Digi-Key	929647-09-05-ND	1	CONN HEADER .100 SNGL STR 5POS
13	J1	Digi-Key	929647-09-03-ND	1	CONN HEADER .100 SNGL STR 3POS
14	J2	Digi-Key	929647-09-03-ND	1	CONN HEADER .100 SNGL STR 3POS
15	J_USB	Digi-Key	A97799CT-ND	1	CONN RCPT MICRO USB TYPE AB
16	L1	Digi-Key	445-2988-1-ND	1	FERRITE CHIP 100 OHM 1A 0603
17	P1	Digi-Key	929665-09-07-ND	1	CONN HEADER .100 DUAL STR 14POS
18	P_DRV_1, P_DRV_2, P_IN_1, P_IN_2	Digi-Key	929665-09-08-ND	4	CONN HEADER .100 DUAL STR 16POS
19	P_GND, P_GND_1, P_GND_2, P_VM_1, P_VM_2, P_VM_IN, P_VM_OUT	Digi-Key	929647-09-04-ND	7	CONN HEADER .100 SNGL STR 4POS
20	P_OUT_1, P_OUT_2	Digi-Key	929647-09-08-ND	2	CONN HEADER .100 SNGL STR 8POS
21	Q1	Digi-Key	SI2319CDS-T1-GE3CT-ND	1	MOSFET P-CH 40V SOT-23
22	Q2	Digi-Key	MMBT3904-FDICT-ND	1	TRANS NPN 40V 350MW SMD SOT23-3
23	R1	Digi-Key	P3.3KGCT-ND	1	RES 3.3K OHM 1/10W 5% 0603 SMD
24	R1_1, R1_2	Digi-Key	P330GCT-ND	2	RES 330 OHM 1/10W 5% 0603 SMD
25	R2, R3, R4, R5, R6	Digi-Key	P330GCT-ND	5	RES 330 OHM 1/10W 5% 0603 SMD
26	R7, R8, R9, R10, R11, R12, R13, R14, R15, R16, R17, R18, R19, R20, R21, R22	Digi-Key	P10KGCT-ND	16	RES 10K OHM 1/10W 5% 0603 SMD
27	R23, R24, R25, R26, R27, R28, R29, R30, R31, R32, R33, R34, R35, R36, R37, R38	Digi-Key	P27KGCT-ND	16	RES 27K OHM 1/10W 5% 0603 SMD
28	R39, R40	Digi-Key	P10KGCT-ND	2	RES 10K OHM 1/10W 5% 0603 SMD
29	R41	Digi-Key	P22KGCT-ND	1	RES 22K OHM 1/10W 5% 0603 SMD
30	SW_RST, SWA, SWB, SWC, SWD	Digi-Key	SW400-ND	5	SWITCH TACTILE SPST-NO 0.05A 24V
31	U1	Digi-Key	296-21749-2-ND	1	IC MCU 16BIT 16KB FLASH 40VQFN
32	U2	Digi-Key	768-1007-1-ND	1	IC USB FS SERIAL UART 28-SSOP
33	U2_1, U2_2	N/A	N/A	2	(Supplied) 8 Channel Serial Interface Low-Side Driver
34	U3	Digi-Key	296-21884-1-ND	1	IC ESD-PROT ARRAY 2CH 6-SON
35	Y1	Digi-Key	X1094-ND	1	CRYSTAL 8.00 MHZ 20PF 49US

3 GUI Installation and Operation

Before running the GUI and commands, be familiar with the EVM hardware and the DRV8860 device specifications and functions. The following steps explain the GUI installation and operation.

3.1 Install the GUI Software

To install the GUI software, double click setup.exe in the install package folder. Follow the prompts until the installation is complete. A system restart may be necessary to properly launch the software after installation.

3.2 Install the USB Driver

The USB driver is for the FT232RL device. Windows 7 or 8 systems can experience issues installing the driver. One method to install the driver on a Windows 7 or 8 system is to change the properties of the driver (see [Figure 11](#)).

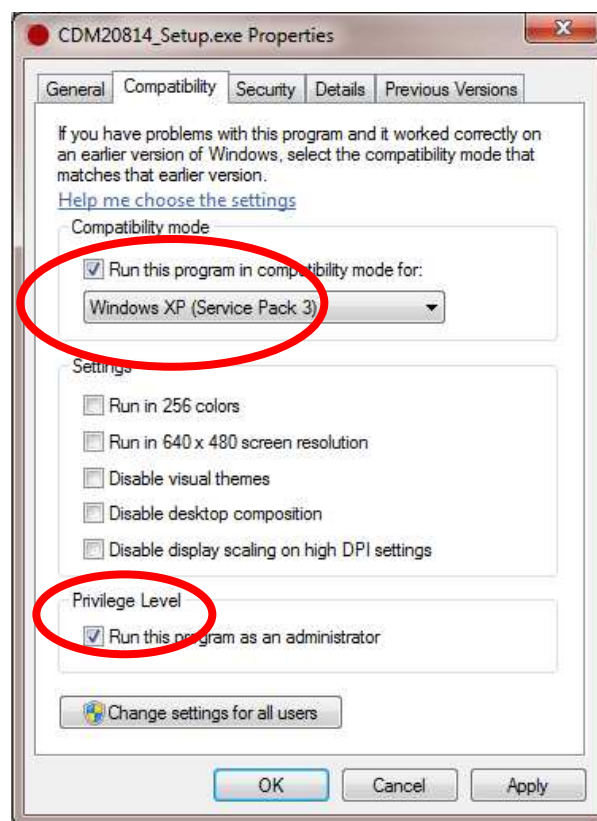


Figure 11. USB Driver Installation for Windows 7 and 8

3.3 GUI Overview

There are six main areas in the GUI. Refer to the following sections for more information and operating procedures.

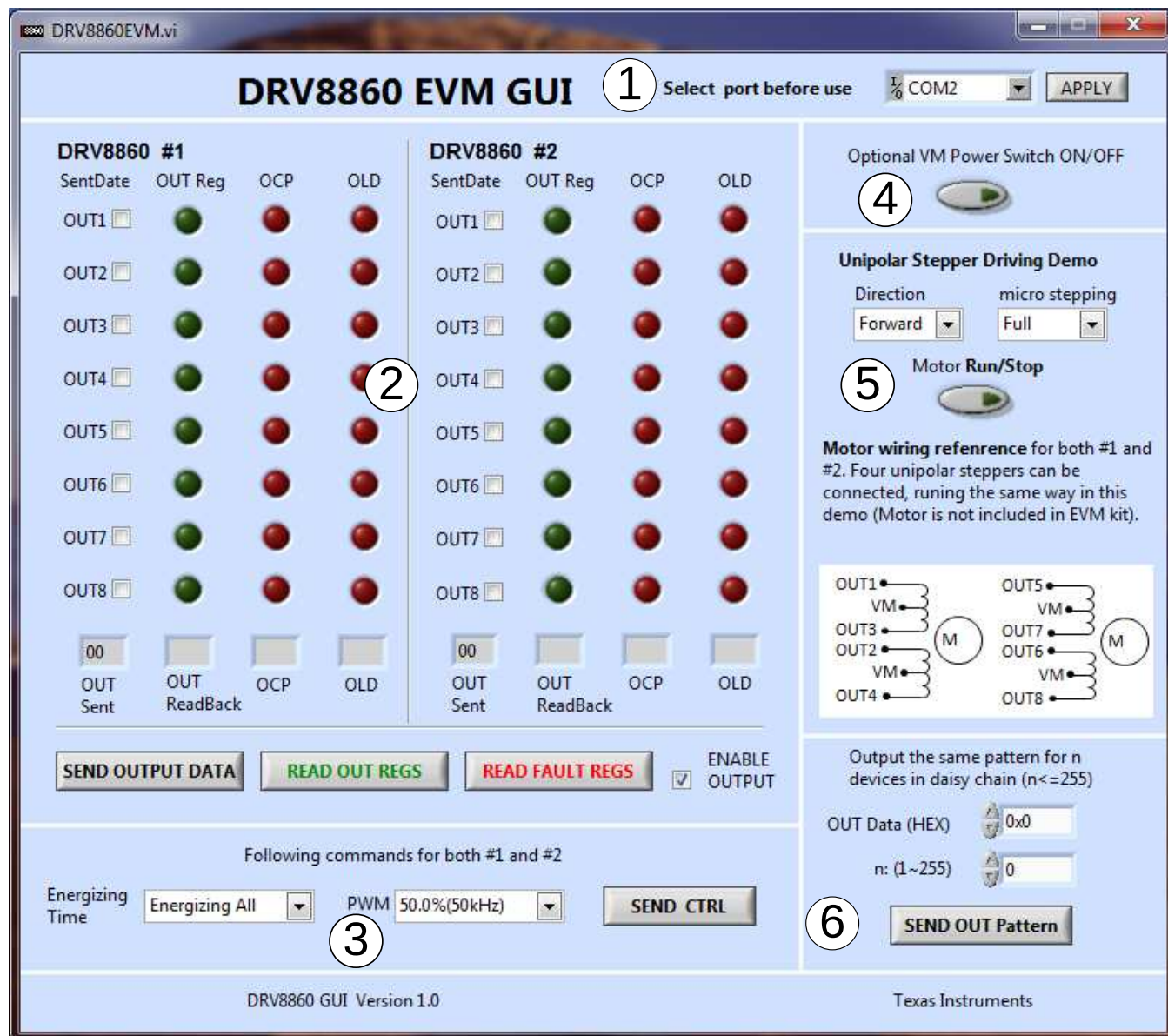


Figure 12. GUI Interface

3.3.1 COM Port Selection

After launching the GUI, the first step is to select the proper COM port. Although this port value is designed so it can be changed after other operations, TI recommends setting it correctly in the beginning. Check the COM port information in the my computer properties in your system to be sure of the COM port value for the EVM kit. COM2 is commonly assigned to the port.

Note: if the COM number is set incorrectly, no prompts or errors appear, nor a response from the EVM.

3.3.2 Send Output Data, Read Back Output Register States, and Read Back Fault Register and Enable.

Operation flow: Select the check box SEND OUTPUT DATA, READ OUT REGS, then READ FAULT REGS.

1. Check the box of OUT1 to OUT8 as needed, then click SEND OUTPUT DATA. The output of DRV8860 changes the state accordingly. There is a HEX indicator below the check box that displays the output data in HEX format.

2. Click READ OUT REGS. The real output register value of the current state reads back to the MCU and sends back to GUI. The green bulbs light according to the states. If the command correctly sends to the MCU, the MCU gives SPI control to DRV8860, and after read-back, the green bulbs match the checked boxes.
3. Click the READ FAULT REGS button. The 16-bit fault register, including 8-bit OCP and 8-bit OLD information, read back to GUI. Note that real OCP occurs when the output bit is in the ON state. Real OLD information detects when the output bit is in the OFF state.
4. The ENABLE OUTPUT check box controls the ENABLE pin of the two DRV8860 devices. If it is checked off, the ENABLE pin drives low. All outputs shut off even if the output register is on.

3.3.3 Energizing Time and PWM Duty Selection

Select the energizing time and PWM duty cycle to control register value builds. After clicking SEND CTRL, the output states change immediately according to the control register value. To recover 100% duty operation, select Energizing All Time in the drop-down options of the energizing menu and click SEND CTRL.

3.3.4 Control the Optional VM Power Switch

Controls the optional VM power switch by selecting on or off.

3.3.5 Running Unipolar Stepper Motors.

The motor wire connections to the output pins are shown in the GUI. Refer to [Section 2](#) for more information.

The driving full-step and half-step sequences are shown in [Table 1](#) and [Table 2](#).

Table 1. Full-Step Sequence

Step Index	OUT1 (5)	OUT2 (6)	OUT3 (7)	OUT4 (8)
1	1	0	0	1
2	1	1	0	0
3	0	1	1	0
4	0	0	1	1

Table 2. Half-Step Sequence

Step Index	OUT1 (5)	OUT2 (6)	OUT3 (7)	OUT4 (8)
1	1	0	0	0
2	1	1	0	0
3	0	1	0	0
4	0	1	1	0
5	0	0	1	0
6	0	0	1	1
7	0	0	0	1
8	1	0	0	1

3.3.6 Output the Same Pattern to n Devices in Daisy Chain.

This function sends the same output pattern to as many as 255 devices in the daisy chain. If $n = 2$, the function is the same as the output data sent in block two. To function on more than two parts, the hardware daisy chain connection needs more than two devices ready.

3.4 Start-Up Operation

If VM power is applied first, then the USB wire is connected, the output LEDs start a self-checking process in two seconds. LEDs flash in a scrolling-line pattern, then as a pulsing on-and-off pattern.

This startup procedure serves as a self check on the outputs and SPI communication. In any operation state, press the SW_RST button to restart the MCU code and start-up the self-checking process again.

3.5 KEY and Indicator Function of the EVM

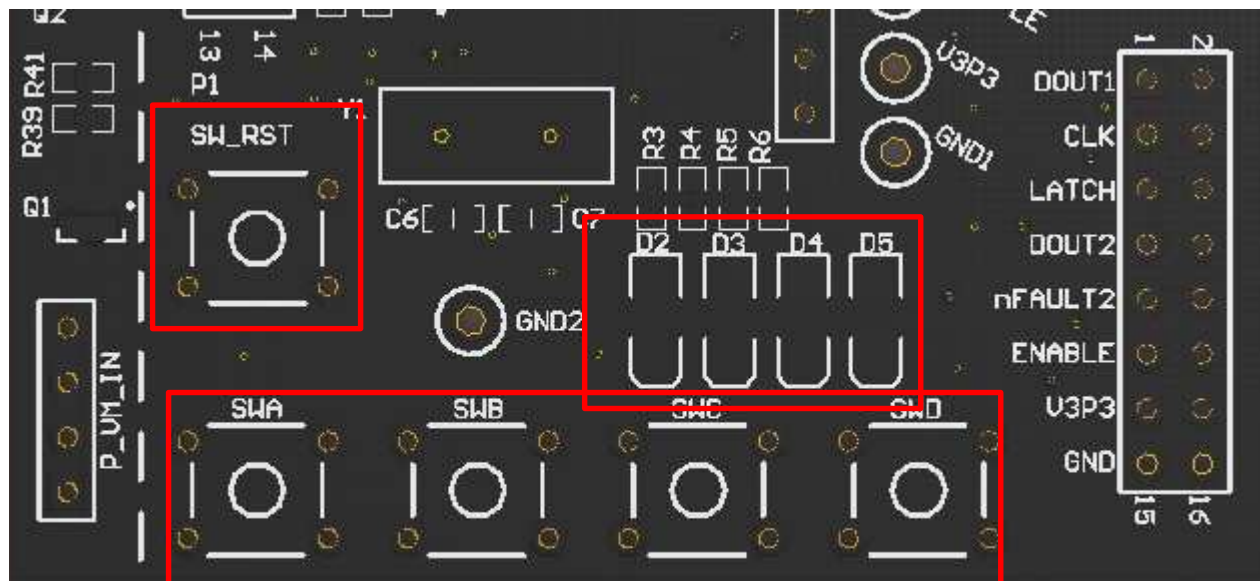


Figure 13. KEY and LED Indicators

SW_RST is the MCU reset key. SWA to SWD are designed as toggling switches for EN, LATCH, CLK, and DIN signals. D2 to D5 turn the light on or off according to the high or low state of these signals. Refer to [Table 3](#) for more information.

Table 3. Key and Indicator Function

Key	Function	LED
SWA Pressed	Toggle EN: H	D2 : Light
	Toggle EN: L	D2 : Dark
SWB Pressed	Toggle LATCH: H	D3 : Light
	Toggle LATCH: L	D3 : Dark
SWC Pressed	Toggle CLK: H	D4 : Light
	Toggle CLK: L	D4 : Dark
SWD Pressed	Toggle DIN: H	D5 : Light
	Toggle DIN: L	D5 : Dark

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As noted in the EVM User's Guide and/or EVM itself, this EVM and/or accompanying hardware may or may not be subject to the Federal Communications Commission (FCC) and Industry Canada (IC) rules.

For EVMs **not** subject to the above rules, this evaluation board/kit/module is intended for use for ENGINEERING DEVELOPMENT, DEMONSTRATION OR EVALUATION PURPOSES ONLY and is not considered by TI to be a finished end product fit for general consumer use. It generates, uses, and can radiate radio frequency energy and has not been tested for compliance with the limits of computing devices pursuant to part 15 of FCC or ICES-003 rules, which are designed to provide reasonable protection against radio frequency interference. Operation of the equipment may cause interference with radio communications, in which case the user at his own expense will be required to take whatever measures may be required to correct this interference.

General Statement for EVMs including a radio

User Power/Frequency Use Obligations: This radio is intended for development/professional use only in legally allocated frequency and power limits. Any use of radio frequencies and/or power availability of this EVM and its development application(s) must comply with local laws governing radio spectrum allocation and power limits for this evaluation module. It is the user's sole responsibility to only operate this radio in legally acceptable frequency space and within legally mandated power limitations. Any exceptions to this are strictly prohibited and unauthorized by Texas Instruments unless user has obtained appropriate experimental/development licenses from local regulatory authorities, which is responsibility of user including its acceptable authorization.

For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant

Caution

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

For EVMs annotated as IC – INDUSTRY CANADA Compliant

This Class A or B digital apparatus complies with Canadian ICES-003.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Concerning EVMs including radio transmitters

This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concerning EVMs including detachable antennas

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Cet appareil numérique de la classe A ou B est conforme à la norme NMB-003 du Canada.

Les changements ou les modifications pas expressément approuvés par la partie responsable de la conformité ont pu vider l'autorité de l'utilisateur pour actionner l'équipement.

Concernant les EVMs avec appareils radio

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

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This development kit is NOT certified as Confirming to Technical Regulations of Radio Law of Japan

If you use this product in Japan, you are required by Radio Law of Japan to follow the instructions below with respect to this product:

1. Use this product in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use this product only after you obtained the license of Test Radio Station as provided in Radio Law of Japan with respect to this product, or
3. Use of this product only after you obtained the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to this product. Also, please do not transfer this product, unless you give the same notice above to the transferee. Please note that if you could not follow the instructions above, you will be subject to penalties of Radio Law of Japan.

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For Feasibility Evaluation Only, in Laboratory/Development Environments. Unless otherwise indicated, this EVM is not a finished electrical equipment and not intended for consumer use. It is intended solely for use for preliminary feasibility evaluation in laboratory/development environments by technically qualified electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems and subsystems. It should not be used as all or part of a finished end product.

Your Sole Responsibility and Risk. You acknowledge, represent and agree that:

1. You have unique knowledge concerning Federal, State and local regulatory requirements (including but not limited to Food and Drug Administration regulations, if applicable) which relate to your products and which relate to your use (and/or that of your employees, affiliates, contractors or designees) of the EVM for evaluation, testing and other purposes.
2. You have full and exclusive responsibility to assure the safety and compliance of your products with all such laws and other applicable regulatory requirements, and also to assure the safety of any activities to be conducted by you and/or your employees, affiliates, contractors or designees, using the EVM. Further, you are responsible to assure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard.
3. Since the EVM is not a completed product, it may not meet all applicable regulatory and safety compliance standards (such as UL, CSA, VDE, CE, RoHS and WEEE) which may normally be associated with similar items. You assume full responsibility to determine and/or assure compliance with any such standards and related certifications as may be applicable. You will employ reasonable safeguards to ensure that your use of the EVM will not result in any property damage, injury or death, even if the EVM should fail to perform as described or expected.
4. You will take care of proper disposal and recycling of the EVM's electronic components and packing materials.

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