NEMA 4, Modulating, Spring Return, AC 100...240 V, for DC 2...10 V or 4...20 mA Control Signal









Technical Data         Power Supply       100240 VAC, -20% / +10%, 50/60 Hz, 100125 VDC, ±10%         Power consumption in operation       9.5 W         Power consumption in rest position       4.5 W         Transformer sizing       21 VA @ AC 100 V, 29 VA @ AC 240 V         Shaft Diameter       1/21.05" round, centers on 3/4" with insert, 1.05" without insert         Electrical Connection       Terminal block(s) inside junction box with knockouts         Overload Protection       electronic throughout 095" rotation         Electrical Protection       actuators are double insulated         Operating Range       210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)         Input Impedance       100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA         Position Feedback       210 V, Max. 0.5 mA         Angle of rotation       Max. 95°, adjustable with mechanical enstop, 3595°         Torque motor       270 in-lb [30 Nm]         Direction of motion motor       selectable with switch 0/1         Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override       5 mm hex crank (3/16" Allen), supplied         Running Time (Motor)       95 s         Running time fail-safe       <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]<	
100125 VDC, ±10%         Power consumption in operation         Power consumption in rest position         Transformer sizing       21 VA @ AC 100 V, 29 VA @ AC 240 V         Shaft Diameter         1/21.05" round, centers on 3/4" with insert, 1.05" without insert         Electrical Connection       Terminal block(s) inside junction box witknockouts         Overload Protection         Electrical Protection         Coverload Protection         Directical Protection         Coverload Protection         Direction Protection         Coverload Protection         Divection Protection         Divection Protection         Divection Feedback         210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)         Divection Feedback         210 V, 0.1 mA), 500 Ω for 420 mA         Position Feedback         Angle of rotation         Max. 95°, adjustable with mechanical enstop, 3595°         Direction of motion motor         Selectable with switch 0/1         Direction of motion fail-safe <td< th=""><th></th></td<>	
Power consumption in operation       9.5 W         Power consumption in rest position       4.5 W         Transformer sizing       21 VA @ AC 100 V, 29 VA @ AC 240 V         Shaft Diameter       1/21.05" round, centers on 3/4" with insert, 1.05" without insert         Electrical Connection       Terminal block(s) inside junction box with knockouts         Overload Protection       electronic throughout 095° rotation         Electrical Protection       actuators are double insulated         Operating Range       210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)         Input Impedance       100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA         Position Feedback       210 V, Max. 0.5 mA         Angle of rotation       Max. 95°, adjustable with mechanical enstop, 3595°         Torque motor       270 in-lb [30 Nm]         Direction of motion motor       selectable with switch 0/1         Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override       5 mm hex crank (3/16" Allen), supplied         Running Time (Motor)       95 s         Running time fail-safe       <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
Power consumption in rest position       4.5 W         Transformer sizing       21 VA @ AC 100 V, 29 VA @ AC 240 V         Shaft Diameter       1/21.05" round, centers on 3/4" with insert, 1.05" without insert         Electrical Connection       Terminal block(s) inside junction box with knockouts         Overload Protection       electronic throughout 095° rotation         Electrical Protection       actuators are double insulated         Operating Range       210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)         Input Impedance       100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA         Position Feedback       210 V, Max. 0.5 mA         Angle of rotation       Max. 95°, adjustable with mechanical enstop, 3595°         Torque motor       270 in-lb [30 Nm]         Direction of motion motor       selectable with switch 0/1         Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override       5 mm hex crank (3/16" Allen), supplied         Running Time (Motor)       95 s         Running time fail-safe       <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
position         Transformer sizing       21 VA @ AC 100 V, 29 VA @ AC 240 V         Shaft Diameter       1/21.05" round, centers on 3/4" with insert, 1.05" without insert         Electrical Connection       Terminal block(s) inside junction box with knockouts         Overload Protection       electronic throughout 095° rotation         Electrical Protection       actuators are double insulated         Operating Range       210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)         Input Impedance       100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA         Position Feedback       210 V, Max. 0.5 mA         Angle of rotation       Max. 95°, adjustable with mechanical enstop, 3595°         Torque motor       270 in-lb [30 Nm]         Direction of motion motor       selectable with switch 0/1         Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override       5 mm hex crank (3/16" Allen), supplied         Running Time (Motor)       95 s         Running time fail-safe       <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]	
Transformer sizing  21 VA @ AC 100 V, 29 VA @ AC 240 V  Shaft Diameter  1/21.05" round, centers on 3/4" with insert, 1.05" without insert  Electrical Connection  Terminal block(s) inside junction box with knockouts  Overload Protection  Electrical Protection  Electrical Protection  Operating Range  210 V, 420 mA w/ ZG-R01 (500 Ω, 1 W resistor)  Input Impedance  100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA  Position Feedback  210 V, Max. 0.5 mA  Angle of rotation  Max. 95°, adjustable with mechanical enstop, 3595°  Torque motor  270 in-lb [30 Nm]  Direction of motion motor  Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  max. 95% r.H., non-condensing  Ambient temperature  -22122°F [-3050°C]  Storage temperature  1/21.25" round, centers on 3/4" with insert, 1.05" without insert  Terminal block(s) inside junction box with knockouts  1/2105" without insert  1/21.05" without insert  1/21.05" without insert  1/210 V, Max. 20 mA w/ ZG-R01 (500 Ω, 1 w conditions)  420 mA  Angle of rotation  Max. 95°, adjustable with mechanical enstop, 3595°  Torque motor  270 in-lb [30 Nm]  Direction of motion fail-safe  reversible with cw/ccw mounting  Position indication  Mechanical  Manual override  5 mm hex crank (3/16" Allen), supplied  720 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  8 conditions in direction in	
$\begin{array}{c} \text{insert, 1.05" without insert} \\ \text{Electrical Connection} \\ \text{Terminal block(s) inside junction box with knockouts} \\ \text{Overload Protection} \\ \text{electronic throughout 095° rotation} \\ \text{Electrical Protection} \\ \text{actuators are double insulated} \\ \text{Operating Range} \\ \text{210 V, 420 mA w/ ZG-R01 (500 $\Omega$, 1 W resistor)} \\ \text{Input Impedance} \\ \text{100 k} \Omega \text{ for 210 V (0.1 mA), 500 } \Omega \text{ for 420 mA} \\ \text{Position Feedback} \\ \text{210 V, Max. 0.5 mA} \\ \text{Angle of rotation} \\ \text{Max. 95°, adjustable with mechanical enstop, 3595°} \\ \text{Torque motor} \\ \text{270 in-lb [30 Nm]} \\ \text{Direction of motion motor} \\ \text{Direction of motion fail-safe} \\ \text{Position indication} \\ \text{Manual override} \\ \text{Running Time (Motor)} \\ \text{Running Time (Motor)} \\ \text{Running time fail-safe} \\ \text{20 s} @ -4122°F [-2050°C], <60 s} @ -22°F [-30°C] \\ \text{Angle of rotation adaptation} \\ \text{Ambient humidity} \\ \text{max. 95% r.H., non-condensing} \\ \text{Ambient temperature} \\ \text{-22122°F [-3050°C]} \\ \text{Storage temperature} \\ \text{-40176°F [-4080°C]} \\ \text{Degree of Protection} \\ \text{IP66, NEMA 4, UL Enclosure Type 4} \\ \end{array}$	
Electrical Connection       Terminal block(s) inside junction box witknockouts         Overload Protection       electronic throughout 095° rotation         Electrical Protection       actuators are double insulated         Operating Range $210 \text{ V}$ , $420 \text{ mA w/ ZG-R01 (500 } Ω$ , $1 \text{ W resistor}$ )         Input Impedance $100 \text{ k}Ω$ for $210 \text{ V}$ (0.1 mA), $500 \Omega$ for $420 \text{ mA}$ Position Feedback $210 \text{ V}$ , Max. $0.5 \text{ mA}$ Angle of rotation       Max. $95^\circ$ , adjustable with mechanical enstop, $3595^\circ$ Torque motor $270 \text{ in-lb [30 Nm]}$ Direction of motion motor       selectable with switch $0/1$ Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override $5 \text{ mm}$ hex crank ( $3/16$ " Allen), supplied         Running Time (Motor) $95 \text{ s}$ Running time fail-safe $<20 \text{ s} @ -4122^\circ \text{F [-}2050^\circ \text{C]}, <60 \text{ s} @ -22^\circ \text{F [-}30^\circ \text{C]}$ Angle of rotation adaptation       manual, by two full cycles of $0/1 \text{ switch}$ Ambient humidity       max. $95\%$ r.H., non-condensing         Ambient temperature $-22122^\circ \text{F [-}3050^\circ \text{C]}$ Storage temperature $-40176^\circ \text{F [-}4080^\circ \text{C]}$ Degree of Prote	
$\begin{array}{c} & \text{knockouts} \\ \hline \text{Overload Protection} & \text{electronic throughout 095° rotation} \\ \hline \text{Electrical Protection} & \text{actuators are double insulated} \\ \hline \text{Operating Range} & 210 \text{ V, 420 mA w/ ZG-R01 (500 }\Omega, 1 \\ \hline \text{W resistor)} \\ \hline \text{Input Impedance} & 100 \text{ k}\Omega \text{ for 210 V (0.1 mA), 500 }\Omega \text{ for 420 mA} \\ \hline \text{Position Feedback} & 210 \text{ V, Max. 0.5 mA} \\ \hline \text{Angle of rotation} & \text{Max. 95°, adjustable with mechanical enstop, 3595°} \\ \hline \text{Torque motor} & 270 \text{ in-lb [30 Nm]} \\ \hline \text{Direction of motion motor} & \text{selectable with switch 0/1} \\ \hline \text{Direction of motion fail-safe} & \text{reversible with cw/ccw mounting} \\ \hline \text{Position indication} & \text{Mechanical} \\ \hline \text{Manual override} & 5 \text{ mm hex crank (3/16" Allen), supplied} \\ \hline \text{Running Time (Motor)} & 95 \text{ s} \\ \hline \text{Running time fail-safe} & <20 \text{ s} @ -4122 \text{°F [-2050°C], <60 s} @ -22 \text{°F [-30°C]} \\ \hline \text{Angle of rotation adaptation} & \text{manual, by two full cycles of 0/1 switch} \\ \hline \text{Ambient humidity} & \text{max. 95\% r.H., non-condensing} \\ \hline \text{Ambient temperature} & -22122 \text{°F [-3050°C]} \\ \hline \text{Storage temperature} & -40176 \text{°F [-4080°C]} \\ \hline \text{Degree of Protection} & \text{IP66, NEMA 4, UL Enclosure Type 4} \\ \hline \end{array}$	
Electrical Protection       actuators are double insulated         Operating Range $210 \text{ V}$ , $420 \text{ mA w}/ \text{ ZG-R01}$ ( $500 \Omega$ , $1 \text{ W}$ resistor)         Input Impedance $100 \text{ k}\Omega$ for $210 \text{ V}$ ( $0.1 \text{ mA}$ ), $500 \Omega$ for $420 \text{ mA}$ Position Feedback $210 \text{ V}$ , Max. $0.5 \text{ mA}$ Angle of rotation       Max. $95^\circ$ , adjustable with mechanical enstop, $3595^\circ$ Torque motor $270 \text{ in-lb } [30 \text{ Nm}]$ Direction of motion motor       selectable with switch $0/1$ Direction of motion fail-safe       reversible with cw/ccw mounting         Position indication       Mechanical         Manual override $5 \text{ mm}$ hex crank ( $3/16^\circ$ Allen), supplied         Running Time (Motor) $95 \text{ s}$ Running time fail-safe $<20 \text{ s} @ -4122^\circ\text{F} [-2050^\circ\text{C}], <60 \text{ s} @ -22^\circ\text{F} [-30^\circ\text{C}]$ Angle of rotation adaptation       manual, by two full cycles of $0/1$ switch         Ambient humidity       max. $95\%$ r.H., non-condensing         Ambient temperature $-22122^\circ\text{F} [-3050^\circ\text{C}]$ Storage temperature $-40176^\circ\text{F} [-4080^\circ\text{C}]$ Degree of Protection       IP66, NEMA 4, UL Enclosure Type 4	h
Operating Range $ \begin{array}{c} 210 \text{ V, } 420 \text{ mA w/ ZG-R01 (500 } \Omega, 1 \\ \text{W resistor)} \\ \\ \text{Input Impedance} \\ \\ 100 \text{ k} \Omega \text{ for } 210 \text{ V (0.1 mA), } 500 \Omega \text{ for } 420 \text{ mA} \\ \\ \text{Position Feedback} \\ \text{Angle of rotation} \\ \\ \text{Max. } 95^\circ, \text{ adjustable with mechanical enstop, } 3595^\circ \\ \\ \text{Torque motor} \\ \text{Direction of motion motor} \\ \text{Direction of motion fail-safe} \\ \text{Position indication} \\ \text{Manual override} \\ \text{Running Time (Motor)} \\ \text{Running time fail-safe} \\ \text{Running time fail-safe} \\ \text{Value of rotation adaptation} \\ \text{Angle of rotation adaptation} \\ \text{Ambient humidity} \\ \text{Ambient temperature} \\ \text{Calue of Potection} \\ \text{Calue of Potection} \\ \text{Degree of Protection} \\ \text{IP66, NEMA 4, UL Enclosure Type 4} \\ \end{array}$	
$\begin{array}{c} W \ resistor) \\ Input \ Impedance \\ Input \ Input \ Input \ Impedance \\ Input \ Input \ Input \ Impedance \\ Input \ Inp$	
$\begin{array}{c} W \ resistor) \\ Input \ Impedance \\ Input \ Input \ Impedance \\ Input \ Input \ Impedance \\ Input \ Input \ Input \ Input \ Input \\ Input \ Inp$	/4
420 mA  Position Feedback  210 V, Max. 0.5 mA  Angle of rotation  Max. 95°, adjustable with mechanical enstop, 3595°  Torque motor  270 in-lb [30 Nm]  Direction of motion motor  Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  IP66, NEMA 4, UL Enclosure Type 4	
Position Feedback  Angle of rotation  Max. 95°, adjustable with mechanical enstop, 3595°  Torque motor  Direction of motion motor  Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  Angle of rotation adaptation  Ambient humidity  Ambient temperature  Degree of Protection  Max. 95°, adjustable with mechanical enstop, 3595°  Roy in Jo Nm  Selectable with switch 0/1  reversible with cw/ccw mounting  Mechanical  Mechanical  Mechanical  S mm hex crank (3/16" Allen), supplied  S manual override  -20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Torque motor  270 in-lb [30 Nm]  Selectable with mechanical enstop, 3595°  meversible with cw/ccw mounting  Mechanical  S mm hex crank (3/16" Allen), supplied  Torque motor  S manual, by two full cycles of 0/1 switch  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  IP66, NEMA 4, UL Enclosure Type 4	
Angle of rotation  Max. 95°, adjustable with mechanical enstop, 3595°  Torque motor  Direction of motion motor  Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  Ambient temperature  -20176°F [-4080°C]  Degree of Protection  Max. 95°, adjustable with mechanical enstops and just a proper stops, and just a proper stops, and just a proper stops and just a proper stop and just a proper stops and just a proper stop and	
stop, 3595°  Torque motor 270 in-lb [30 Nm]  Direction of motion motor selectable with switch 0/1  Direction of motion fail-safe reversible with cw/ccw mounting  Position indication Mechanical  Manual override 5 mm hex crank (3/16" Allen), supplied  Running Time (Motor) 95 s  Running time fail-safe <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation manual, by two full cycles of 0/1 switch  Ambient humidity max. 95% r.H., non-condensing  Ambient temperature -22122°F [-3050°C]  Storage temperature -40176°F [-4080°C]  Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Direction of motion motor  Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  Angle of rotation adaptation  Ambient humidity  Ambient temperature  Direction of motion motor  Selectable with switch 0/1  reversible with cw/ccw mounting  Mechanical  Mechanical  5 mm hex crank (3/16" Allen), supplied  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  manual, by two full cycles of 0/1 switch  max. 95% r.H., non-condensing  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  IP66, NEMA 4, UL Enclosure Type 4	d
Direction of motion fail-safe  Position indication  Manual override  Running Time (Motor)  Running time fail-safe  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  Rectanting metally with cw/ccw mounting  Allen), supplied  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  -22°F [-30°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection	
Position indication Mechanical  Manual override 5 mm hex crank (3/16" Allen), supplied  Running Time (Motor) 95 s  Running time fail-safe <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation manual, by two full cycles of 0/1 switch  Ambient humidity max. 95% r.H., non-condensing  Ambient temperature -22122°F [-3050°C]  Storage temperature -40176°F [-4080°C]  Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Manual override 5 mm hex crank (3/16" Allen), supplied Running Time (Motor) 95 s Running time fail-safe <20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C] Angle of rotation adaptation manual, by two full cycles of 0/1 switch Ambient humidity max. 95% r.H., non-condensing Ambient temperature -22122°F [-3050°C] Storage temperature -40176°F [-4080°C] Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Running Time (Motor)  Running time fail-safe  20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  95 s  -40122°F [-2050°C], <60 s @ -4122°F [-30°C], <60 s @ -4122°F [-30°C]  -22°F [-30°C]  -40176°F [-4080°C]  1P66, NEMA 4, UL Enclosure Type 4	
Running time fail-safe  -20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]  Angle of rotation adaptation  Ambient humidity  max. 95% r.H., non-condensing  Ambient temperature  -22122°F [-3050°C]  Storage temperature  -40176°F [-4080°C]  Degree of Protection  IP66, NEMA 4, UL Enclosure Type 4	
-22°F [-30°C]  Angle of rotation adaptation manual, by two full cycles of 0/1 switch  Ambient humidity max. 95% r.H., non-condensing  Ambient temperature -22122°F [-3050°C]  Storage temperature -40176°F [-4080°C]  Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Ambient humidity max. 95% r.H., non-condensing  Ambient temperature -22122°F [-3050°C]  Storage temperature -40176°F [-4080°C]  Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	)
Ambient temperature -22122°F [-3050°C] Storage temperature -40176°F [-4080°C] Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Storage temperature -40176°F [-4080°C]  Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Degree of Protection IP66, NEMA 4, UL Enclosure Type 4	
Housing material Die cast aluminium and plastic casing	
Agency Listing CULus acc. to UL60730-1A/-2-14, CAN/0 E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU	
Noise level, motor 56 dB(A)	
Noise level, fail-safe 71 dB(A)	
Servicing maintenance-free	
Quality Standard ISO 9001	
Weight 12 lb [5.3 kg]	
Auxiliary switch 2 x SPDT, 3 A resistive (0.5 A inductive) AC 250 V, one set at 10°, one set at 85°	@

†Rated Impulse Voltage 4kV, Type of action 1.AA, Control Pollution Degree 4.

#### Torque min. 270 in-lb, for control of air dampers

### Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a DC 2…10 Vor, with the addition of a  $500\Omega$  resistor, a 4...20 mA control input from an electronic controller or positioner. A DC 2…10 V feedback signal is provided for position indication.

A common installation technique for control of multi-section dampers is to use the U5 position feedback of one actuator (Master) to control multiple actuators (Slaves). Belimo refers to this as Master/Slave control. The only requirement is that the actuators are installed on MECHANICALLY SEPARATE damper shafts.

#### **Adaptation and Synchronization**

An adaption can be triggered by manually rotating the direction of rotation switch TWO full cycles. Adaption will detect the applications mechanical end stops by driving to each stop. An adaption will scale the control signal input, position feedback voltage, and running time to the new working mechanical angle of rotation. It is good practice to initiate an adaption on each actuator when mounting and controlling EF.-SR.. actuators in Piggy-back mode.

If the manual override is used, with power applied, the actuator will perform a Synchronization upon release of the manual override hand crank. The actuator drives from the current control position to the synchronize reference of 0%. The actuator then drives back to the control position defined by the input signal.

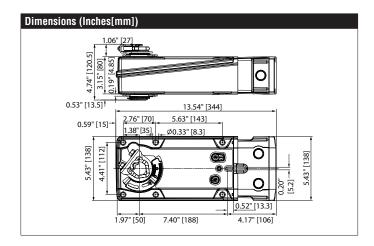
#### Operation

The EF..120-SR-S N4 series actuators provide true spring return operation for reliable failsafe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The EF..120-SR-S N4 series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The EF..120-SR-S N4 uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF. 120-SR-S N4 versions are provided with two built-in auxiliary switches. These SPDT switches provide safety interfacing or signaling, for example, for fan start-up. The switching function at the fail-safe position is fixed at 10°, the other switch function is fixed at 85°. The EF..120-SR-S N4 actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Installation Note: Use 60°C/75°C copper (CU) conductor and wire size range 12-26 AWG, stranded or solid. If conduit is used, use flexible metal conduit; UL listed and CSA certified strain relief or conduit fitting suitable for outdoor applications, rated NEMA type 4, 4X, 6 or 6X or watertight.



NEMA 4, Modulating, Spring Return, AC 100...240 V, for DC 2...10 V or 4...20 mA Control Signal



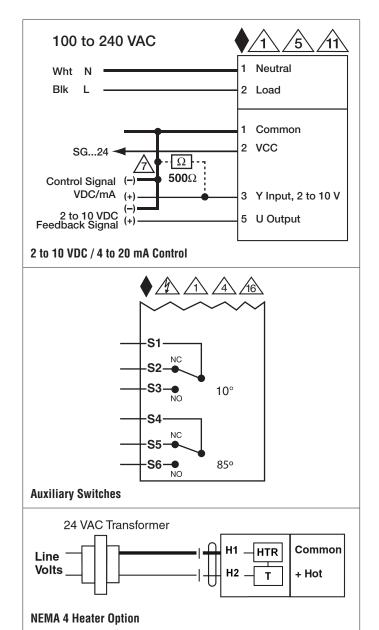
NEMA 4, Modulating, Spring Return, AC 100...240 V, for DC 2...10 V or 4...20 mA Control Signal



Accessorie	25
AV8-25	Shaft extension
EF-P	Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).
IND-EFB	End stop indicator
K9-2	Shaft clamp reversible
KG10A	Ball joint
KH10	Damper crank arm
KH-EFB	Actuator arm
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).
T00L-07	13 mm wrench.
ZG-100	Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase).
ZG-120	Jackshaft mounting bracket.
ZG-DC1	Damper clip for damper blade, 3.5" width.
ZG-DC2	Damper clip for damper blade, 6" width.
ZG-EFB	Mounting kit for linkage operation
ZG-JSA-3	1.05" diameter jackshaft adaptor (12" L).
IRM-100	Input rescaling module for modulating actuators.
P475	Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.
P475-1	Shaft mount, non-Mercury aux. switch for 1" dia. shafts.
PS-100	Low voltage and control signal simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR
SGF24	Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR
ZG-R01	4 to 20 mA adaptor, $500\Omega$ , $1/4$ W resistor w 6" pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.

### Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



NEMA 4, Modulating, Spring Return, AC 100...240 V, for DC 2...10 V or 4...20 mA Control Signal

### Wiring Diagrams



### WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground



Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.



Provide overload protection and disconnect as required.



Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.



Only connect common to negative (-) leg of control circuits.



A 500  $\Omega$  resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



Actuators are provided with a numbered screw terminal strip instead of a cable.