REJ09B0101-0112

Everywhere you imagine. RENESAS

16

M16C/29 Group

Hardware Manual

RENESAS MCU

M16C FAMILY / M16C/Tiny SERIES

Hardware Manual

All information contained in these materials, including products and product specifications, represents information on the product at the time of publication and is subject to change by Renesas Technology Corp. without notice. Please review the latest information published by Renesas Technology Corp. through various means, including the Renesas Technology Corp. website (http://www.renesas.com).

Rev. 1.12
Revision Date: Mar.30, 2007

Renesas Technology
www.renesas.com

Notes regarding these materials

1. This document is provided for reference purposes only so that Renesas customers may select the appropriate Renesas products for their use. Renesas neither makes warranties or representations with respect to the accuracy or completeness of the information contained in this document nor grants any license to any intellectual property rights or any other rights of Renesas or any third party with respect to the information in this document.
2. Renesas shall have no liability for damages or infringement of any intellectual property or other rights arising out of the use of any information in this document, including, but not limited to, product data, diagrams, charts, programs, algorithms, and application circuit examples.
3. You should not use the products or the technology described in this document for the purpose of military applications such as the development of weapons of mass destruction or for the purpose of any other military use. When exporting the products or technology described herein, you should follow the applicable export control laws and regulations, and procedures required by such laws and regulations.
4. All information included in this document such as product data, diagrams, charts, programs, algorithms, and application circuit examples, is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas products listed in this document, please confirm the latest product information with a Renesas sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas such as that disclosed through our website. (http://www.renesas.com)
5. Renesas has used reasonable care in compiling the information included in this document, but Renesas assumes no liability whatsoever for any damages incurred as a result of errors or omissions in the information included in this document.
6. When using or otherwise relying on the information in this document, you should evaluate the information in light of the total system before deciding about the applicability of such information to the intended application. Renesas makes no representations, warranties or guaranties regarding the suitability of its products for any particular application and specifically disclaims any liability arising out of the application and use of the information in this document or Renesas products.
7. With the exception of products specified by Renesas as suitable for automobile applications, Renesas products are not designed, manufactured or tested for applications or otherwise in systems the failure or malfunction of which may cause a direct threat to human life or create a risk of human injury or which require especially high quality and reliability such as safety systems, or equipment or systems for transportation and traffic, healthcare, combustion control, aerospace and aeronautics, nuclear power, or undersea communication transmission. If you are considering the use of our products for such purposes, please contact a Renesas sales office beforehand. Renesas shall have no liability for damages arising out of the uses set forth above.
8. Notwithstanding the preceding paragraph, you should not use Renesas products for the purposes listed below:
   (1) artificial life support devices or systems
   (2) surgical implantations
   (3) healthcare intervention (e.g., excision, administration of medication, etc.)
   (4) any other purposes that pose a direct threat to human life
   Renesas shall have no liability for damages arising out of the uses set forth in the above and purchasers who elect to use Renesas products in any of the foregoing applications shall indemnify and hold harmless Renesas Technology Corp., its affiliated companies and their officers, directors, and employees against any and all damages arising out of such applications.
9. You should use the products described herein within the range specified by Renesas, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas shall have no liability for malfunctions or damages arising out of the use of Renesas products beyond such specified ranges.
10. Although Renesas endeavors to improve the quality and reliability of its products, IC products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Please be sure to implement safety measures to guard against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other applicable measures. Among others, since the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
11. In case Renesas products listed in this document are detached from the products to which the Renesas products are attached or affixed, the risk of accident such as swallowing by infants and small children is very high. You should implement safety measures so that Renesas products may not be easily detached from your products. Renesas shall have no liability for damages arising out of such detachment.
12. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written approval from Renesas.
13. Please contact a Renesas sales office if you have any questions regarding the information contained in this document, Renesas semiconductor products, or if you have any other inquiries.

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

   Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

   — The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

   The state of the product is undefined at the moment when power is supplied.

   — The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

   In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

   In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

   Access to reserved addresses is prohibited.

   — The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

   After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

   — When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

   Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

   — The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

How to Use This Manual

1. Purpose and Target Readers

This manual is designed to provide the user with an understanding of the hardware functions and electrical characteristics of the MCU. It is intended for users designing application systems incorporating the MCU. A basic knowledge of electric circuits, logical circuits, and MCUs is necessary in order to use this manual.
The manual comprises an overview of the product; descriptions of the CPU, system control functions, peripheral functions, and electrical characteristics; and usage notes.

Particular attention should be paid to the precautionary notes when using the manual. These notes occur within the body of the text, at the end of each section, and in the Usage Notes section.

The revision history summarizes the locations of revisions and additions. It does not list all revisions. Refer to the text of the manual for details.

The following documents apply to the M16C/29 Group. Make sure to refer to the latest versions of these documents. The newest versions of the documents listed may be obtained from the Renesas Technology Web site.

Document Type	Description	Document Title	Document No.
Hardware manual	Hardware specifications (pin assignments, memory maps, peripheral function specifications, electrical characteristics, timing charts) and operation description Note: Refer to the application notes for details on using peripheral functions.	M16C/29 Group Hardware Manual	This hardware manual
Software manual	Description of CPU instruction set	M16C/60, M16C/20, M16C/Tiny Series Software Manual	REJ09B0137
Application note	Information on using peripheral functions and application examples Sample programs Information on writing programs in assembly language and C	Available from Renesas Technology Web site.	
Renesas technical update	Product specifications, updates on documents, etc.		

2. Notation of Numbers and Symbols

The notation conventions for register names, bit names, numbers, and symbols used in this manual are described below.

(1) Register Names, Bit Names, and Pin Names
Registers, bits, and pins are referred to in the text by symbols. The symbol is accompanied by the word "register," "bit," or "pin" to distinguish the three categories.
Examples the PM03 bit in the PM0 register
P3_5 pin, VCC pin

(2) Notation of Numbers
The indication "$_2$" is appended to numeric values given in binary format. However, nothing is appended to the values of single bits. The indication "$_{16}$" is appended to numeric values given in hexadecimal format. Nothing is appended to numeric values given in decimal format.
Examples Binary: 11_2
Hexadecimal: $EFA0_{16}$
Decimal: 1234

3. Register Notation

The symbols and terms used in register diagrams are described below.

XXX Register *1

b7	b6	b5	b4	b3	b2	b1	b0
				0	X		

Symbol	Address	After Reset
XXX	XXX	00_{16}

Bit Symbol	Bit Name	Function	RW *2
XXX0	XXX bits	b1 b0 1 0: XXX 0 1: XXX 1 0: Do not set. 1 1: XXX	RW
XXX1			RW
— (b2)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined.		—
— (b3)	Reserved bits *3	Set to 0.	RW
XXX4	XXX bits	Function varies according to the operating mode. *4	RW
XXX5			WO
XXX6			RW
XXX7	XXX bit	0: XXX 1: XXX	RO

*1

Blank: Set to 0 or 1 according to the application.
0: Set to 0.
1: Set to 1.
X: Nothing is assigned.

*2

RW: Read and write.
RO: Read only.
WO: Write only.
–: Nothing is assigned.

*3

- Reserved bit
  Reserved bit. Set to specified value.

*4

- Nothing is assigned
  Nothing is assigned to the bit. As the bit may be used for future functions, if necessary, set to 0.
- Do not set to a value
  Operation is not guaranteed when a value is set.
- Function varies according to the operating mode.
  The function of the bit varies with the peripheral function mode. Refer to the register diagram for information on the individual modes.

4. List of Abbreviations and Acronyms

Abbreviation	Full Form
ACIA	Asynchronous Communication Interface Adapter
bps	bits per second
CRC	Cyclic Redundancy Check
DMA	Direct Memory Access
DMAC	Direct Memory Access Controller
GSM	Global System for Mobile Communications
Hi-Z	High Impedance
IEBus	Inter Equipment bus
I/O	Input/Output
IrDA	Infrared Data Association
LSB	Least Significant Bit
MSB	Most Significant Bit
NC	Non-Connection
PLL	Phase Locked Loop
PWM	Pulse Width Modulation
SFR	Special Function Registers
SIM	Subscriber Identity Module
UART	Universal Asynchronous Receiver/Transmitter
VCO	Voltage Controlled Oscillator

All trademarks and registered trademarks are the property of their respective owners.

IEBus is a registered trademark of NEC Electronics Corporation.

Table of Contents

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0000_{16}			
0001_{16}			
0002_{16}			
0003_{16}			
0004_{16}	Processor mode register 0	PM0	44
0005_{16}	Processor mode register 1	PM1	44
0006_{16}	System clock control register 0	CM0	49
0007_{16}	System clock control register 1	CM1	50
0008_{16}			
0009_{16}	Address match interrupt enable register	AIER	88
$000A_{16}$	Protect register	PRCR	69
$000B_{16}$			
$000C_{16}$	Oscillation stop detection register	CM2	51
$000D_{16}$			
$000E_{16}$	Watchdog timer start register	WDTS	90
$000F_{16}$	Watchdog timer control register	WDC	90
0010_{16} 0011_{16} 0012_{16}	Address match interrupt register 0	RMAD0	88
0013_{16}			
0014_{16} 0015_{16} 0016_{16}	Address match interrupt register 1	RMAD1	88
0017_{16}			
0018_{16}			
0019_{16}	Voltage detection register 1	VCR1	41
$001A_{16}$	Voltage detection register 2	VCR2	41
$001B_{16}$			
$001C_{16}$	PLL control register 0	PLC0	53
$001D_{16}$			
$001E_{16}$	Processor mode register 2	PM2	52
$001F_{16}$	Low voltage detection interrupt register	D4INT	42
0020_{16} 0021_{16} 0022_{16}	DMA0 source pointer	SAR0	95
0023_{16}			
0024_{16} 0025_{16} 0026_{16}	DMA0 destination pointer	DAR0	95
0027_{16}			
0028_{16} 0029_{16}	DMA0 transfer counter	TCR0	95
$002A_{16}$			
$002B_{16}$			
$002C_{16}$	DMA0 control register	DM0CON	94
$002D_{16}$			
$002E_{16}$			
$002F_{16}$			
0030_{16} 0031_{16} 0032_{16}	DMA1 source pointer	SAR1	95
0033_{16}			
0034_{16} 0035_{16} 0036_{16}	DMA1 destination pointer	DAR1	95
0037_{16}			
0038_{16} 0039_{16}	DMA1 transfer counter	TCR1	95
$003A_{16}$			
$003B_{16}$			
$003C_{16}$	DMA1 control register	DM1CON	94
$003D_{16}$			
$003E_{16}$			
$003F_{16}$			

Note: The blank areas are reserved and cannot be accessed by users.

Address	Register	Symbol	Page
0040_{16}			
0041_{16}	CAN0 wakeup interrupt control register	C01WKIC	76
0042_{16}	CAN0 successful reception interrupt control register	C0RECIC	76
0043_{16}	CAN0 successful transmission interrupt control regiser	C0TRMIC	76
0044_{16}	INT3 interrupt control register	INT3IC	76
0045_{16}	IC/OC 0 interrupt control register	ICOC0IC	76
0046_{16}	IC/OC 1 interrupt control register, I²C bus interface interrupt control register	ICOC1IC IICIC	76 76
0047_{16}	IC/OC base timer interrupt control register, SCLSDA interrupt control register	BTIC SCLDAIC	76 76
0048_{16}	SI/O4 interrupt control register, INT5 interrupt control register	S4IC INT5IC	76 76
0049_{16}	SI/O3 interrupt control register, INT4 interrupt control register	S3IC INT4IC	76 76
$004A_{16}$	UART2 Bus collision detection interrupt control register	BCNIC	76
$004B_{16}$	DMA0 interrupt control register	DM0IC	76
$004C_{16}$	DMA1 interrupt control register	DM1IC	76
$004D_{16}$	CAN0 error interrupt control register	C01ERRIC	76
$004E_{16}$	A/D conversion interrupt control register Key input interrupt control register	ADIC KUPIC	76 76
$004F_{16}$	UART2 transmit interrupt control register	S2TIC	76
0050_{16}	UART2 receive interrupt control register	S2RIC	76
0051_{16}	UART0 transmit interrupt control register	S0TIC	76
0052_{16}	UART0 receive interrupt control register	S0RIC	76
0053_{16}	UART1 transmit interrupt control register	S1TIC	76
0054_{16}	UART1 receive interrupt control register	S1RIC	76
0055_{16}	Timer A0 interrupt control register	TA0IC	76
0056_{16}	Timer A1 interrupt control register	TA1IC	76
0057_{16}	Timer A2 interrupt control register	TA2IC	76
0058_{16}	Timer A3 interrupt control register	TA3IC	76
0059_{16}	Timer A4 interrupt control register	TA4IC	76
$005A_{16}$	Timer B0 interrupt control register	TB0IC	76
$005B_{16}$	Timer B1 interrupt control register	TB1IC	76
$005C_{16}$	Timer B2 interrupt control register	TB2IC	76
$005D_{16}$	INT0 interrupt control register	INT0IC	76
$005E_{16}$	INT1 interrupt control register	INT1IC	76
$005F_{16}$	INT2 interrupt control register	INT2IC	76
0060_{16} 0061_{16} 0062_{16} 0063_{16} 0064_{16} 0065_{16}	CAN0 message box 0: Identifier/DLC		289
0066_{16} 0067_{16} 0068_{16} 0069_{16} $006A_{16}$ $006B_{16}$ $006C_{16}$ $006D_{16}$	CAN 0 message box 0: Data field		289
$006E_{16}$ $006F_{16}$	CAN0 message box 0: Time stamp		289
0070_{16} 0071_{16} 0072_{16} 0073_{16} 0074_{16} 0075_{16}	CAN0 message box 1: Identifier/DLC		289
0076_{16} 0077_{16} 0078_{16} 0079_{16} $007A_{16}$ $007B_{16}$ $007C_{16}$ $007D_{16}$	CAN 0 message box 1: Data field		289
$007E_{16}$ $007F_{16}$	CAN0 message box 1: Time stamp		289

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0080_{16} 0081_{16} 0082_{16} 0083_{16} 0084_{16} 0085_{16}	CAN0 message box 2: Identifier/DLC		289
0086_{16} 0087_{16} 0088_{16} 0089_{16} $008A_{16}$ $008B_{16}$ $008C_{16}$ $008D_{16}$	CAN0 message box 2: Data field		289
$008E_{16}$ $008F_{16}$	CAN0 message box 2: time stamp		289
0090_{16} 0091_{16} 0092_{16} 0093_{16} 0094_{16} 0095_{16}	CAN0 message box 3: Identifier/DLC		289
0096_{16} 0097_{16} 0098_{16} 0099_{16} $009A_{16}$ $009B_{16}$ $009C_{16}$ $009D_{16}$	CAN0 message box 3: Data field		289
$009E_{16}$ $009F_{16}$	CAN0 message box 3: time stamp		289
$00A0_{16}$ $00A1_{16}$ $00A2_{16}$ $00A3_{16}$ $00A4_{16}$ $00A5_{16}$	CAN0 message box 4: Identifier/DLC		289
$00A6_{16}$ $00A7_{16}$ $00A8_{16}$ $00A9_{16}$ $00AA_{16}$ $00AB_{16}$ $00AC_{16}$ $00AD_{16}$	CAN0 message box 4: Data field		289
$00AE_{16}$ $00AF_{16}$	CAN0 message box 4: time stamp		289
$00B0_{16}$ $00B1_{16}$ $00B2_{16}$ $00B3_{16}$ $00B4_{16}$ $00B5_{16}$	CAN0 message box 5: Identifier/DLC		289
$00B6_{16}$ $00B7_{16}$ $00B8_{16}$ $00B9_{16}$ $00BA_{16}$ $00BB_{16}$ $00BC_{16}$ $00BD_{16}$	CAN0 message box 5: Data field		289
$00BE_{16}$ $00BF_{16}$	CAN0 message box 5: time stamp		289

Address	Register	Symbol	Page
$00C0_{16}$ $00C1_{16}$ $00C2_{16}$ $00C3_{16}$ $00C4_{16}$ $00C5_{16}$	CAN0 message box 6: Identifier/DLC		289
$00C6_{16}$ $00C7_{16}$ $00C8_{16}$ $00C9_{16}$ $00CA_{16}$ $00CB_{16}$ $00CC_{16}$ $00CD_{16}$	CAN0 message box 6: Data field		289
$00CE_{16}$ $00CF_{16}$	CAN0 message box 6: time stamp		289
$00D0_{16}$ $00D1_{16}$ $00D2_{16}$ $00D3_{16}$ $00D4_{16}$ $00D5_{16}$	CAN0 message box 7: Identifier/DLC		289
$00D6_{16}$ $00D7_{16}$ $00D8_{16}$ $00D9_{16}$ $00DA_{16}$ $00DB_{16}$ $00DC_{16}$ $00DD_{16}$	CAN0 message box 7: Data field		289
$00DE_{16}$ $00DF_{16}$	CAN0 message box 7: time stamp		289
$00E0_{16}$ $00E1_{16}$ $00E2_{16}$ $00E3_{16}$ $00E4_{16}$ $00E5_{16}$	CAN0 message box 8: Identifier/DLC		289
$00E6_{16}$ $00E7_{16}$ $00E8_{16}$ $00E9_{16}$ $00EA_{16}$ $00EB_{16}$ $00EC_{16}$ $00ED_{16}$	CAN0 message box 8: Data field		289
$00EE_{16}$ $00EF_{16}$	CAN0 message box 8: time stamp		289
$00F0_{16}$ $00F1_{16}$ $00F2_{16}$ $00F3_{16}$ $00F4_{16}$ $00F5_{16}$	CAN0 message box 9: Identifier/DLC		289
$00F6_{16}$ $00F7_{16}$ $00F8_{16}$ $00F9_{16}$ $00FA_{16}$ $00FB_{16}$ $00FC_{16}$ $00FD_{16}$	CAN0 message box 9: Data field		289
$00FE_{16}$ $00FF_{16}$	CAN0 message box 9: time stamp		289

Note: The blank areas are reserved and cannot be accessed by users.

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0100$_{16}$ 0101$_{16}$ 0102$_{16}$ 0103$_{16}$ 0104$_{16}$ 0105$_{16}$	CAN0 message box 10: Identifer/DLC		289
0106$_{16}$ 0107$_{16}$ 0108$_{16}$ 0109$_{16}$ 010A$_{16}$ 010B$_{16}$ 010C$_{16}$ 010D$_{16}$	CAN0 message box 10: Data field		289
010E$_{16}$ 010F$_{16}$	CAN0 message box 10: time stamp		289
0110$_{16}$ 0111$_{16}$ 0112$_{16}$ 0113$_{16}$ 0114$_{16}$ 0115$_{16}$	CAN0 message box 11: Identifier/DLC		289
0116$_{16}$ 0117$_{16}$ 0118$_{16}$ 0119$_{16}$ 011A$_{16}$ 011B$_{16}$ 011C$_{16}$ 011D$_{16}$	CAN0 message box 11: Data field		289
011E$_{16}$ 011F$_{16}$	CAN0 message box 11: time stamp		289
0120$_{16}$ 0121$_{16}$ 0122$_{16}$ 0123$_{16}$ 0124$_{16}$ 0125$_{16}$	CAN0 message box 12: Identifier/DLC		289
0126$_{16}$ 0127$_{16}$ 0128$_{16}$ 0129$_{16}$ 012A$_{16}$ 012B$_{16}$ 012C$_{16}$ 012D$_{16}$	CAN0 message box 12: Data field		289
012E$_{16}$ 012F$_{16}$	CAN0 message box 12: time stamp		289
0130$_{16}$ 0131$_{16}$ 0132$_{16}$ 0133$_{16}$ 0134$_{16}$ 0135$_{16}$	CAN0 message box 13: Identifier/DLC		289
0136$_{16}$ 0137$_{16}$ 0138$_{16}$ 0139$_{16}$ 013A$_{16}$ 013B$_{16}$ 013C$_{16}$ 013D$_{16}$	CAN0 message box 13: Data field		289
013E$_{16}$ 013F$_{16}$	CAN0 message box 13: time stamp		289

Address	Register	Symbol	Page
0140$_{16}$ 0141$_{16}$ 0142$_{16}$ 0143$_{16}$ 0144$_{16}$ 0145$_{16}$	CAN0 message box 14: Identifier/DLC		289
0146$_{16}$ 0147$_{16}$ 0148$_{16}$ 0149$_{16}$ 014A$_{16}$ 014B$_{16}$ 014C$_{16}$ 014D$_{16}$	CAN0 message box 14: Data field		289
014E$_{16}$ 014F$_{16}$	CAN0 message box 14: time stamp		289
0150$_{16}$ 0151$_{16}$ 0152$_{16}$ 0153$_{16}$ 0154$_{16}$ 0155$_{16}$	CAN0 message box 15: Identifier/DLC		289
0156$_{16}$ 0157$_{16}$ 0158$_{16}$ 0159$_{16}$ 015A$_{16}$ 015B$_{16}$ 015C$_{16}$ 015D$_{16}$	CAN0 message box 15: Data field		289
015E$_{16}$ 015F$_{16}$	CAN0 message box 15: time stamp		289
0160$_{16}$ 0161$_{16}$ 0162$_{16}$ 0163$_{16}$ 0164$_{16}$ 0165$_{16}$	CAN0 global mask register	C0GMR	291
0166$_{16}$ 0167$_{16}$ 0168$_{16}$ 0169$_{16}$ 016A$_{16}$ 016B$_{16}$	CAN0 local mask A register	C0LMAR	291
016C$_{16}$ 016D$_{16}$ 016E$_{16}$ 016F$_{16}$ 0170$_{16}$ 0171$_{16}$	CAN0 local mask B register	C0LMBR	291
0172$_{16}$			
0173$_{16}$			
0174$_{16}$			
0175$_{16}$			
0176$_{16}$			
0177$_{16}$			
0178$_{16}$			
0179$_{16}$			
017A$_{16}$			
017B$_{16}$			
017C$_{16}$			
017D$_{16}$			
017E$_{16}$			
017F$_{16}$			

Note: The blank areas are reserved and cannot be accessed by users.

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0180$_{16}$			
0181$_{16}$			
0182$_{16}$			
0183$_{16}$			
0184$_{16}$			
0185$_{16}$			
0186$_{16}$			
01B0$_{16}$			
01B1$_{16}$			
01B2$_{16}$			
01B3$_{16}$	Flash memory control register 4 (Note 2)	FMR4	342
01B4$_{16}$			
01B5$_{16}$	Flash memory control register 1 (Note 2)	FMR1	341
01B6$_{16}$			
01B7$_{16}$	Flash memory control register 0 (Note 2)	FMR0	341
01B8$_{16}$			
01B9$_{16}$			
01BA$_{16}$			
01BB$_{16}$			
01BC$_{16}$			
0200$_{16}$	CAN0 message control register 0	C0MCTL0	292
0201$_{16}$	CAN0 message control register 1	C0MCTL1	292
0202$_{16}$	CAN0 message control register 2	C0MCTL2	292
0203$_{16}$	CAN0 message control register 3	C0MCTL3	292
0204$_{16}$	CAN0 message control register 4	C0MCTL4	292
0205$_{16}$	CAN0 message control register 5	C0MCTL5	292
0206$_{16}$	CAN0 message control register 6	C0MCTL6	292
0207$_{16}$	CAN0 message control register 7	C0MCTL7	292
0208$_{16}$	CAN0 message control register 8	C0MCTL8	292
0209$_{16}$	CAN0 message control register 9	C0MCTL9	292
020A$_{16}$	CAN0 message control register 10	C0MCTL10	292
020B$_{16}$	CAN0 message control register 11	C0MCTL11	292
020C$_{16}$	CAN0 message control register 12	C0MCTL12	292
020D$_{16}$	CAN0 message control register 13	C0MCTL13	292
020E$_{16}$	CAN0 message control register 14	C0MCTL14	292
020F$_{16}$	CAN0 message control register 15	C0MCTL15	292
0210$_{16}$ 0211$_{16}$	CAN0 control register	C0CTLR	293
0212$_{16}$ 0213$_{16}$	CAN0 status register	C0STR	294
0214$_{16}$ 0215$_{16}$	CAN0 slot status register	C0SSTR	295
0216$_{16}$ 0217$_{16}$	CAN 0 interrupt control register	C0ICR	296
0218$_{16}$ 0219$_{16}$	CAN0 extended ID register	C0IDR	296
021A$_{16}$ 021B$_{16}$	CAN0 configuration register	C0CONR	297
021C$_{16}$	CAN0 receive error count register	C0RECR	298
021D$_{16}$	CAN0 transmit error count register	C0TECR	298
021E$_{16}$ 021F$_{16}$	CAN0 time stamp register	C0TSR	299
0210$_{16}$			
02FE$_{16}$			
02FF$_{16}$			

Address	Register	Symbol	Page
0240$_{16}$			
0241$_{16}$			
0242$_{16}$ 0243$_{16}$	CAN0 acceptance filter support register	C0AFS	299
0244$_{16}$			
0245$_{16}$			
0246$_{16}$			
0247$_{16}$			
0248$_{16}$			
0249$_{16}$			
024A$_{16}$			
024C$_{16}$			
024D$_{16}$			
024E$_{16}$			
024F$_{16}$			
0250$_{16}$			
0251$_{16}$			
0252$_{16}$			
0253$_{16}$			
0254$_{16}$			
0255$_{16}$			
0256$_{16}$			
0257$_{16}$			
0258$_{16}$			
0259$_{16}$			
025A$_{16}$	Three-phase protect control register	TPRC	139
025B$_{16}$			
025C$_{16}$	0n-chip oscillator control register	ROCR	50
025D$_{16}$	Pin assignment control register	PACR	177, 326
025E$_{16}$	Peripheral clock select register	PCLKR	52
025F$_{16}$	CAN0 clock select register	CCLKR	53
02E0$_{16}$	I^{2}C0 data shift register	S00	258
02E1$_{16}$			
02E2$_{16}$	I^{2}C0 address register	S0D0	257
02E3$_{16}$	I^{2}C0 control register 0	S1D0	259
02E4$_{16}$	I^{2}C0 clock control register	S20	258
02E5$_{16}$	I^{2}C0 start/stop condition control register	S2D0	263
02E6$_{16}$	I^{2}C0 control register 1	S3D0	261
02E7$_{16}$	I^{2}C0 control register 2	S4D0	262
02E8$_{16}$	I^{2}C0 status register	S10	260
02E9$_{16}$			
02EA$_{16}$			
02FE$_{16}$			
02FF$_{16}$			

Note 1: The blank areas are reserved and cannot be accessed by users.
Note 2: This register is included in the flash memory version.

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0300$_{16}$ 0301$_{16}$	TM, WG register 0	G1TM0, G1PO0	146,147
0302$_{16}$ 0303$_{16}$	TM, WG register 1	G1TM1, G1PO1	146,147
0304$_{16}$ 0305$_{16}$	TM, WG register 2	G1TM2, G1PO2	146,147
0306$_{16}$ 0307$_{16}$	TM, WG register 3	G1TM3, G1PO3	146,147
0308$_{16}$ 0309$_{16}$	TM, WG register 4	G1TM4, G1PO4	146,147
030A$_{16}$ 030B$_{16}$	TM, WG register 5	G1TM5, G1PO5	146,147
030C$_{16}$ 030D$_{16}$	TM, WG register 6	G1TM6, G1PO6	146,147
030E$_{16}$ 030F$_{16}$	TM, WG register 7	G1TM7, G1PO7	146,147
0310$_{16}$	WG control register 0	G1POCR0	146
0311$_{16}$	WG control register 1	G1POCR1	146
0312$_{16}$	WG control register 2	G1POCR2	146
0313$_{16}$	WG control register 3	G1POCR3	146
0314$_{16}$	WG control register 4	G1POCR4	146
0315$_{16}$	WG control register 5	G1POCR5	146
0316$_{16}$	WG control register 6	G1POCR6	146
0317$_{16}$	WG control register 7	G1POCR7	146
0318$_{16}$	TM control register 0	G1TMCR0	145
0319$_{16}$	TM control register 1	G1TMCR1	145
031A$_{16}$	TM control register 2	G1TMCR2	145
031B$_{16}$	TM control register 3	G1TMCR3	145
031C$_{16}$	TM control register 4	G1TMCR4	145
031D$_{16}$	TM control register 5	G1TMCR5	145
031E$_{16}$	TM control register 6	G1TMCR6	145
031F$_{16}$	TM control register 7	G1TMCR7	145
0320$_{16}$ 0321$_{16}$	Base timer register	G1BT	142
0322$_{16}$	Base timer control register 0	G1BCR0	142
0323$_{16}$	Base timer control register 1	G1BCR1	143
0324$_{16}$	TM prescale register 6	G1TPR6	145
0325$_{16}$	TM prescale register 7	G1TPR7	145
0326$_{16}$	Function enable register	G1FE	148
0327$_{16}$	Function select register	G1FS	148
0328$_{16}$ 0329$_{16}$	Base timer reset register	G1BTRR	144
032A$_{16}$	Divider register	G1DV	143
032B$_{16}$			
032C$_{16}$			
032D$_{16}$			
032E$_{16}$			
032F$_{16}$			
0330$_{16}$	Interrupt request register	G1IR	149
0331$_{16}$	Interrupt enable register 0	G1IE0	150
0332$_{16}$	Interrupt enable register 1	G1IE1	150
0333$_{16}$			
0334$_{16}$			
0335$_{16}$			
0336$_{16}$			
0337$_{16}$			
0338$_{16}$			
0339$_{16}$			
033A$_{16}$			
033B$_{16}$			
033C$_{16}$			
033D$_{16}$			
033E$_{16}$	NMI digital debounce register	NDDR	327
033F$_{16}$	P1$_7$ digital debounce register	P17DDR	327

Address	Register	Symbol	Page
0340$_{16}$			
0341$_{16}$			
0342$_{16}$ 0343$_{16}$	Timer A1-1 register	TA11	130
0344$_{16}$ 0345$_{16}$	Timer A2-1 register	TA21	130
0346$_{16}$ 0347$_{16}$	Timer A4-1 register	TA41	130
0348$_{16}$	Three-phase PWM control register 0	INVC0	127
0349$_{16}$	Three-phase PWM control register 1	INVC1	128
034A$_{16}$	Three-phase output buffer register 0	IDB0	129
034B$_{16}$	Three-phase output buffer register 1	IDB1	129
034C$_{16}$	Dead time timer	DTT	129
034D$_{16}$	Timer B2 interrupt occurrence frequency set counter	ICTB2	129
034E$_{16}$	Position-data-retain function contol register	PDRF	137
034F$_{16}$			
0350$_{16}$			
0351$_{16}$			
0352$_{16}$			
0353$_{16}$			
0354$_{16}$			
0355$_{16}$			
0356$_{16}$			
0357$_{16}$			
0358$_{16}$	Port function control register	PFCR	139
0359$_{16}$			
035A$_{16}$			
035B$_{16}$			
035C$_{16}$			
035D$_{16}$			
035E$_{16}$	Interrupt request cause select register 2	IFSR2A	77
035F$_{16}$	Interrupt request cause select register	IFSR	77, 85
0360$_{16}$	SI/O3 transmit/receive register	S3TRR	218
0361$_{16}$			
0362$_{16}$	SI/O3 control register	S3C	218
0363$_{16}$	SI/O3 bit rate generator	S3BRG	218
0364$_{16}$	SI/O4 transmit/receive register	S4TRR	218
0365$_{16}$			
0366$_{16}$	SI/O4 control register	S4C	218
0367$_{16}$	SI/O4 bit rate generator	S4BRG	218
0368$_{16}$			
0369$_{16}$			
036A$_{16}$			
036B$_{16}$			
036C$_{16}$			
036D$_{16}$			
036E$_{16}$			
036F$_{16}$			
0370$_{16}$			
0371$_{16}$			
0372$_{16}$			
0373$_{16}$			
0374$_{16}$	UART2 special mode register 4	U2SMR4	179
0375$_{16}$	UART2 special mode register 3	U2SMR3	179
0376$_{16}$	UART2 special mode register 2	U2SMR2	178
0377$_{16}$	UART2 special mode register	U2SMR	178
0378$_{16}$	UART2 transmit/receive mode register	U2MR	175
0379$_{16}$	UART2 bit rate generator	U2BRG	174
037A$_{16}$ 037B$_{16}$	UART2 transmit buffer register	U2TB	174
037C$_{16}$	UART2 transmit/receive control register 0	U2C0	176
037D$_{16}$	UART2 transmit/receive control register 1	U2C1	177
037E$_{16}$ 037F$_{16}$	UART2 receive buffer register	U2RB	174

Note : The blank areas are reserved and cannot be accessed by users.

Quick Reference to Pages Classified by Address

Address	Register	Symbol	Page
0380_{16}	Count start flag	TABSR	104, 118, 132
0381_{16}	Clock prescaler reset flag	CPSRF	105,118
0382_{16}	One-shot start flag	ONSF	105
0383_{16}	Trigger select register	TRGSR	105,132
0384_{16}	Up-down flag	UDF	104
0385_{16}			
0386_{16} 0387_{16}	Timer A0 register	TA0	104
0388_{16} 0389_{16}	Timer A1 register	TA1	104
$038A_{16}$ $038B_{16}$	Timer A2 register	TA2	104
$038C_{16}$ $038D_{16}$	Timer A3 register	TA3	104
$038E_{16}$ $038F_{16}$	Timer A4 register	TA4	104
0390_{16} 0391_{16}	Timer B0 register	TB0	118
0392_{16} 0393_{16}	Timer B1 register	TB1	118
0394_{16} 0395_{16}	Timer B2 register	TB2	118
0396_{16}	Timer A0 mode register	TA0MR	103
0397_{16}	Timer A1 mode register	TA1MR	133
0398_{16}	Timer A2 mode register	TA2MR	133
0399_{16}	Timer A3 mode register	TA3MR	103
$039A_{16}$	Timer A4 mode register	TA4MR	133
$039B_{16}$	Timer B0 mode register	TB0MR	117
$039C_{16}$	Timer B1 mode register	TB1MR	117
$039D_{16}$	Timer B2 mode register	TB2MR	133
$039E_{16}$	Timer B2 special mode register	TB2SC	131
$039F_{16}$			
$03A0_{16}$	UART0 transmit/receive mode register	U0MR	175
$03A1_{16}$	UART0 bit rate generator	U0BRG	174
$03A2_{16}$ $03A3_{16}$	UART0 transmit buffer register	U0TB	174
$03A4_{16}$	UART0 transmit/receive control register 0	U0C0	176
$03A5_{16}$	UART0 transmit/receive control register 1	U0C1	177
$03A6_{16}$ $03A7_{16}$	UART0 receive buffer register	U0RB	174
$03A8_{16}$	UART1 transmit/receive mode register	U1MR	175
$03A9_{16}$	UART1 bit rate generator	U1BRG	174
$03AA_{16}$ $03AB_{16}$	UART1 transmit buffer register	U1TB	174
$03AC_{16}$	UART1 transmit/receive control register 0	U1C0	176
$03AD_{16}$	UART1 transmit/receive control register 1	U1C1	177
$03AE_{16}$ $03AF_{16}$	UART1 receive buffer register	U1RB	174
$03B0_{16}$	UART transmit/receive control register 2	UCON	176
$03B1_{16}$			
$03B2_{16}$			
$03B3_{16}$			
$03B4_{16}$ $03B5_{16}$	CRC snoop address register	CRCSAR	314
$03B6_{16}$	CRC mode register	CRCMR	314
$03B7_{16}$			
$03B8_{16}$	DMA0 request cause select register	DM0SL	93
$03B9_{16}$			
$03BA_{16}$	DMA1 request cause select register	DM1SL	94
$03BB_{16}$			
$03BC_{16}$ $03BD_{16}$	CRC data register	CRCD	314
$03BE_{16}$	CRC input register	CRCIN	314
$03BF_{16}$			

Note : The blank areas are reserved and cannot be accessed by users.

Address	Register	Symbol	Page
$03C0_{16}$ $03C1_{16}$	A/D register 0	AD0	226
$03C2_{16}$ $03C3_{16}$	A/D register 1	AD1	226
$03C4_{16}$ $03C5_{16}$	A/D register 2	AD2	226
$03C6_{16}$ $03C7_{16}$	A/D register 3	AD3	226
$03C8_{16}$ $03C9_{16}$	A/D register 4	AD4	226
$03CA_{16}$ $03CB_{16}$	A/D register 5	AD5	226
$03CC_{16}$ $03CD_{16}$	A/D register 6	AD6	226
$03CE_{16}$ $03CF_{16}$	A/D register 7	AD7	226
$03D0_{16}$			
$03D1_{16}$			
$03D2_{16}$	A/D trigger control register	ADTRGCON	225
$03D3_{16}$	A/D convert status register 0	ADSTAT0	226
$03D4_{16}$	A/D control register 2	ADCON2	224
$03D5_{16}$			
$03D6_{16}$	A/D control register 0	ADCON0	224
$03D7_{16}$	A/D control register 1	ADCON1	224
$03D8_{16}$			
$03D9_{16}$			
$03DA_{16}$			
$03DB_{16}$			
$03DC_{16}$			
$03DD_{16}$			
$03DE_{16}$			
$03DF_{16}$			
$03E0_{16}$	Port P0 register	P0	324
$03E1_{16}$	Port P1 register	P1	324
$03E2_{16}$	Port P0 direction register	PD0	323
$03E3_{16}$	Port P1 direction register	PD1	323
$03E4_{16}$	Port P2 register	P2	324
$03E5_{16}$	Port P3 register	P3	324
$03E6_{16}$	Port P2 direction register	PD2	323
$03E7_{16}$	Port P3 direction register	PD3	323
$03E8_{16}$			
$03E9_{16}$			
$03EA_{16}$			
$03EB_{16}$			
$03EC_{16}$	Port P6 register	P6	324
$03ED_{16}$	Port P7 register	P7	324
$03EE_{16}$	Port P6 direction register	PD6	323
$03EF_{16}$	Port P7 direction register	PD7	323
$03F0_{16}$	Port P8 register	P8	324
$03F1_{16}$	Port P9 register	P9	324
$03F2_{16}$	Port P8 direction register	PD8	323
$03F3_{16}$	Port P9 direction register	PD9	323
$03F4_{16}$	Port P10 register	P10	324
$03F5_{16}$			
$03F6_{16}$	Port P10 direction register	PD10	323
$03F7_{16}$			
$03F8_{16}$			
$03F9_{16}$			
$03FA_{16}$			
$03FB_{16}$			
$03FC_{16}$	Pull-up control register 0	PUR0	325
$03FD_{16}$	Pull-up control register 1	PUR1	325
$03FE_{16}$	Pull-up control register 2	PUR2	325
$03FF_{16}$	Port control register	PCR	326

1. Overview

1.1 Features

The M16C/29 Group of single-chip control MCU incorporates the M16C/60 series CPU core, employing the high-performance silicon gate CMOS technology and sophisticated instructions for a high level of efficiency. The M16C/29 Group is housed in 64-pin and 80-pin plastic molded LQFP packages. These single-chip MCUs operate using sophisticated instructions featuring a high level of instruction efficiency. This MCU is capable of executing instructions at high speed and it has one CAN module, makes it suitable for control of cars and LAN system of FA. In addition, the CPU core boasts a multiplier and DMAC for high-speed processing to make adequate for office automation, communication devices, and other high-speed processing applications.

1.1.1 Applications

Automotive body, car audio, LAN system of FA, etc.

1.1.2 Specifications

Table 1.1 lists performance overview of M16C/29 Group 80-pin package.

Table 1.2 lists performance overview of M16C/29 Group 64-pin package.

Table 1.1 Performance Overview of M16C/29 Group (T-ver./V-ver.) (80-Pin Package)

Item		Performance
CPU	Number of basic instructions	91 instructions
	Shortest instruction excution time	50 ns (f(BCLK) = 20MHz, V_{CC} = 3.0 to 5.5 V) (Normal-ver./T-ver.) 100 ns(f(BCLK) = 10MHz, V_{CC} = 2.7 to 5.5 V) (Normal-ver.) 50 ns (f(BCLK) = 20MHz, V_{CC} = 4.2 to 5.5 V, -40 to 105°C) (V-ver.) 62.5 ns (f(BCLK) = 16MHz, V_{CC} = 4.2 to 5.5 V, -40 to 125°C) (V-ver.)
	Operation mode	Single chip mode
	Address space	1 Mbyte
	Memory capacity	ROM/RAM: See **Tables 1.3 to 1.5**
Peripheral Function	Port	Input/Output: 71 lines
	Multifunction timer	TimerA:16 bits x 5 channels, TimerB:16 bits x 3 channels Three-phase Motor Control Timer TimerS (Input Capture/Output Compare): 16 bit base timer x 1 channel (Input/Output x 8 channels)
	Serial I/O	2 channels (UART, clock synchronous serial I/O) 1 channel (UART, clock synchronous serial I/O, I^2C bus, or IEbus[1]) 2 channels (Clock synchronous serial I/O) 1 channel (Multi- master I^2C bus)
	A/D converter	10 bits x 27 channels
	DMAC	2 channels
	CRC calculation circuit	2 polynomial (CRC-CCITT and CRC-16) with MSB/LSB selectable
	CAN module	1 channel, supporting CAN 2.0B specification
	Watchdog timer	15 bits x 1 channel (with prescaler)
	Interrupt	29 internal and 8 external sources, 4 software sources, interrupt priority level: 7
	Clock generation circuit	4 circuits • Main clock } (These circuits contain a built-in feedback • Sub-clock } resistor) • On-chip oscillator(main-clock oscillation stop detect function) • PLL frequency synthesizer
	Oscillation stop detect Function	Main clock oscillation stop, re-oscillation detect function
	Voltage detection circuit	Available (Normal-ver.) / Not available (T-ver., V-ver.)
Electrical Charact-eristics	Power supply voltage	V_{CC} = 3.0 to 5.5 V (f(BCLK) = 20 MHz) (Normal-ver.) V_{CC} = 2.7 to 5.5 V (f(BCLK) = 10 MHz)
		V_{CC} = 3.0 to 5.5 V (T-ver.)
		V_{CC} = 4.2 to 5.5 V (V-ver.)
	Power consumption	18 mA (V_{CC} = 5 V, f(BCLK) = 20 MHz) 25 µA (f(X_{CIN}) = 32 kHz on RAM) 3 µA (V_{CC} = 5 V, f(X_{CIN}) = 32 kHz, in wait mode) 0.8 µA (V_{CC} = 5 V, in stop mode)
Flash memory	Program/erase supply voltage	2.7 to 5.5 V (Normal-ver.), 3.0 to 5.5V (T-ver.), 4.2 to 5.5 V (V-ver.)
	Program and erase endurance	100 times (all space) or 1,000 times (blocks 0 to 5)/ 10,000 times (blocks A and B[2])
Operating ambient temperature		-20 to 85°C/-40 to 85°C[2] (Normal-ver.)
		-40 to 85°C (T-ver.), -40 to 125°C (V-ver.)
Package		80-pin plastic mold LQFP

NOTES:

1. IEBus is a trademark of NEC Electronics Corporation.
2. Refer to **Table 1.6** to **Table 1.8 Product code**.

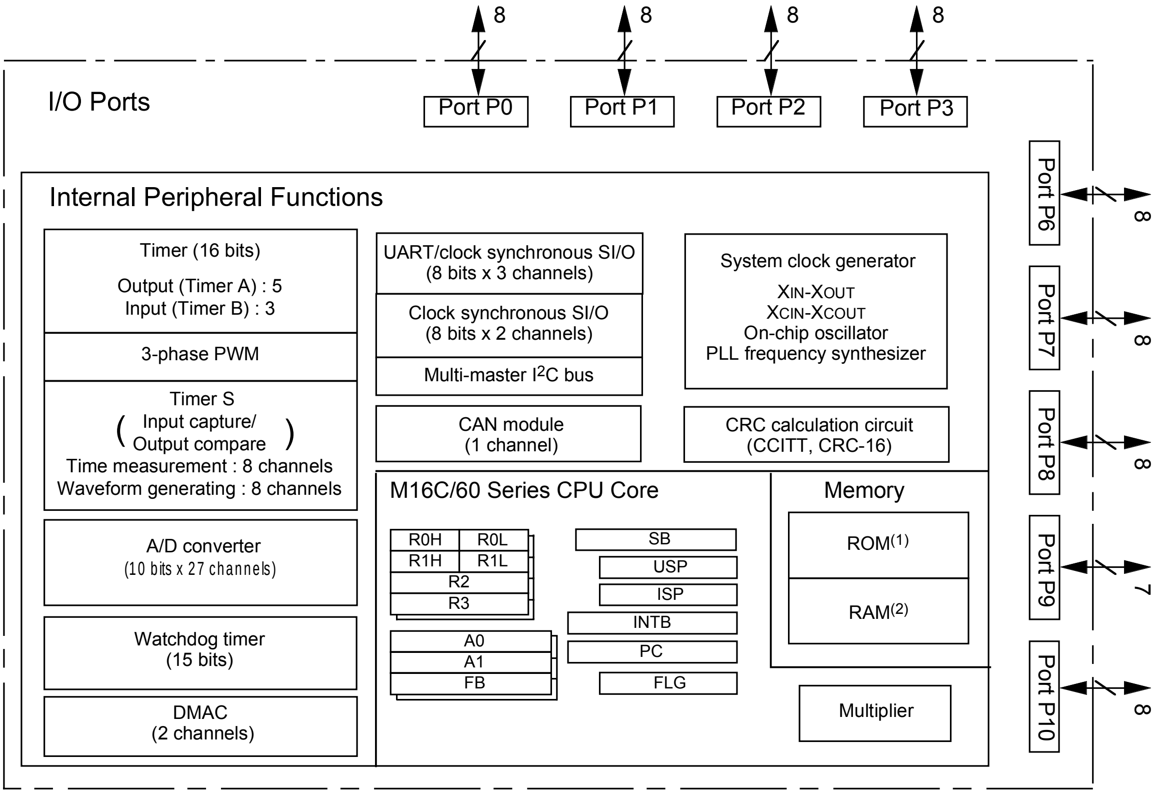
Table 1.2 Performance Overview of M16C/29 Group (64-Pin Package)

Item		Performance
CPU	Number of basic instructions	91 instructions
	Shortest instruction excution time	50 ns (f(BCLK) = 20MHz, VCC = 3.0 to 5.5 V) (Normal-ver./T-ver.) 100 ns(f(BCLK) = 10MHz, VCC = 2.7 to 5.5 V) (Normal-ver.) 50 ns (f(BCLK) = 20MHz, VCC = 4.2 to 5.5 V, -40 to 105°C) (V-ver.) 62.5 ns (f(BCLK) = 16MHz, VCC = 4.2 to 5.5 V, -40 to 125°C) (V-ver.)
	Operation mode	Single chip mode
	Address space	1 Mbytes
	Memory capacity	ROM/RAM: See **Tables 1.3 to 1.5**
Peripheral function	Port	Input/Output: 55 lines
	Multifunction timer	TimerA:16 bits x 5 channels, TimerB:16 bits x 3 channels Three-phase Motor Control Timer TimerS (Input Capture/Output Compare): 16bit base timer x 1 channel (Input/Output x 8 channels)
	Serial I/O	2 channels (UART, clock synchronous serial I/O) 1 channel (UART, clock synchronous serial I/O, I^{2}C bus, or IEbus(1)) 1 channel (Clock synchronous serial I/O) 1 channel (Multi-master I^{2}C bus)
	A/D converter	10 bits x 16 channels
	DMAC	2 channels
	CRC calculation circuit	2 polynomial (CRC-CCITT and CRC-16) with MSB/LSB selectable
	CAN module	1 channel, supporting CAN 2.0B specification
	Watchdog timer	15 bits x 1 channel (with prescaler)
	Interrupt	28 internal and 8 external sources, 4 software sources, interrupt priority level: 7
	Clock generation circuit	4 circuits • Main clock • Sub-clock (These circuits contain a built-in feedback resistor) • On-chip oscillator(main-clock oscillation stop detect function) • PLL frequency synthesizer
	Oscillation stop detect function	Main clock oscillation stop, re-oscillation detect function
	Voltage detection circuit	Available (Normal-ver.) / Not available (T-ver., V-ver.)
Electrical Charact-eristics	Power supply voltage	VCC = 3.0 to 5.5 V (f(BCLK) = 20 MHz) (Normal-ver.) VCC = 2.7 to 5.5 V (f(BCLK) = 10 MHz)
		VCC = 3.0 to 5.5 V (T-ver.)
		VCC = 4.2 to 5.5 V (V-ver.)
	Power consumption	18 mA (VCC = 5 V, f(BCLK) = 20 MHz) 25 µA (f(XCIN) = 32 kHz on RAM) 3 µA (VCC = 5 V, f(XCIN) = 32 kHz, in wait mode) 0.8 µA (VCC = 5 V, in stop mode)
Flash memory	Program/erase supply voltage	2.7 to 5.5 V (Normal-ver.), 3.0 to 5.5V (T-ver.), 4.2 to 5.5 V (V-ver.)
	Program and erase endurance	100 times (all space) or 1,000 times (blocks 0 to 5)/ 10,000 times (blocks A and B(2))
Operating ambient temperature		-20 to 85°C/-40 to 85°C(2) (Normal-ver.)
		-40 to 85°C (T-ver.), -40 to 125°C (V-ver.)
Package		64-pin plastic mold LQFP

NOTES:
1. IEBus is a trademark of NEC Electronics Corporation.
2. Refer to **Table 1.6** to **Table 1.8 Product code**.

1.2 Block Diagram

Figure 1.1 is a block diagram of the M16C/29 Group, 80-pin package.



NOTES:
1. The ROM capacity varies depending on each product.
2. The RAM capacity varies depending on each product.

Figure 1.1 M16C/29 Group, 80-Pin Block Diagram

Figure 1.2 is a block diagram of the M16C/29 Group, 64-pin package.

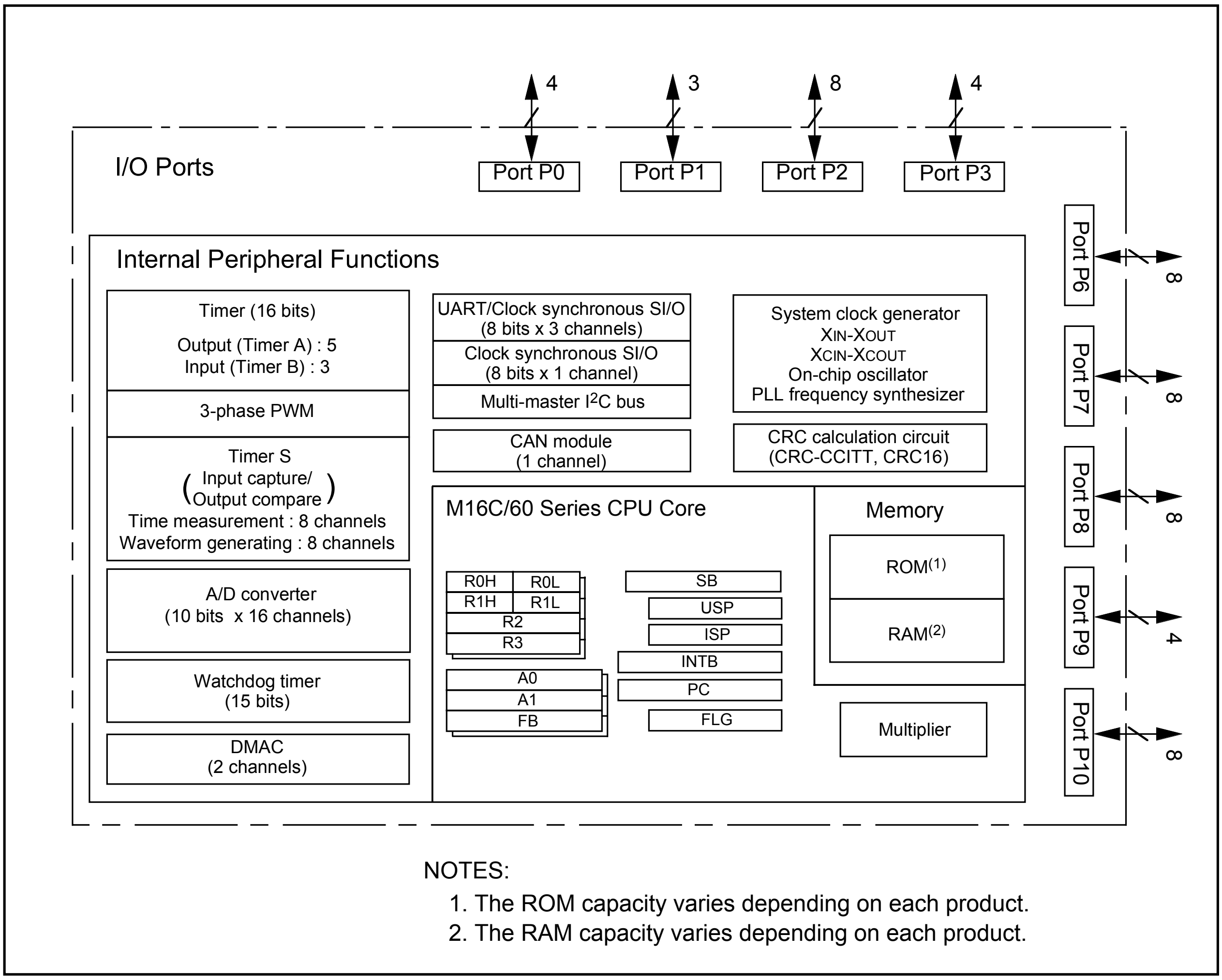


Figure 1.2 M16C/29 Group, 64-Pin Block Diagram

1.3 Product List

Tables 1.3 to 1.5 list the M16C/29 Group products and **Figure 1.3** shows the type numbers, memory sizes and packages. **Tables 1.6 to 1.8** list the product code of flash memory version for M16C/29 Group. **Figure 1.4 to Figure 1.6** show the marking diagram of flash memory version for M16C/29 Group.

Table 1.3 Product List (1) -Normal Version **As of March, 2007**

Type Number	ROM Capacity	RAM Capacity	Package Type	Remarks	Product Code
M30290FAHP	96 K + 4 K	8 K	PLQP0080KB-A (80P6Q-A)	Flash Memory	U3, U5, U7, U9
M30290FCHP	128 K + 4 K	12 K			
M30291FAHP	96 K + 4 K	8 K	PLQP0064KB-A (64P6Q-A)		
M30291FCHP	128 K + 4 K	12 K			
M30290M8-XXXHP	64 K	4 K	PLQP0080KB-A (80P6Q-A)	Mask ROM	U3, U5
M30290MA-XXXHP	96 K	8 K			
M30290MC-XXXHP	128 K	12 K			
M30291M8-XXXHP	64 K	4 K	PLQP0064KB-A (64P6Q-A)		
M30291MA-XXXHP	96 K	8 K			
M30291MC-XXXHP	128 K	12 K			

Table 1.4 Product List (2) -T Version **As of March, 2007**

Type Number	ROM Capacity	RAM Capacity	Package Type	Remarks	Product Code
M30290FATHP	96 K + 4 K	8 K	PLQP0080KB-A (80P6Q-A)	Flash Memory	U3, U5, U7, U9
M30290FCTHP	128 K + 4 K	12 K			
M30291FATHP	96 K + 4 K	8 K	PLQP0064KB-A (64P6Q-A)		
M30291FCTHP	128 K + 4 K	12 K			
M30290M8T-XXXHP	64 K	4 K	PLQP0080KB-A (80P6Q-A)	Mask ROM	U0
M30290MAT-XXXHP	96 K	8 K			
M30290MCT-XXXHP	128 K	12 K			
M30291M8T-XXXHP	64 K	4 K	PLQP0064KB-A (64P6Q-A)		
M30291MAT-XXXHP	96 K	8 K			
M30291MCT-XXXHP	128 K	12 K			

Table 1.5 Product List (3) -V Version **As of March, 2007**

Type Number	ROM Capacity	RAM Capacity	Package Type	Remarks	Product Code
M30290FAVHP	96 K + 4 K	8 K	PLQP0080KB-A (80P6Q-A)	Flash Memory	U3, U5, U7, U9
M30290FCVHP	128 K + 4 K	12 K			
M30291FAVHP	96 K + 4 K	8 K	PLQP0064KB-A (64P6Q-A)		
M30291FCVHP	128 K + 4 K	12 K			
M30290M8V-XXXHP	64 K	4 K	PLQP0080KB-A (80P6Q-A)	Mask ROM	U0
M30290MAV-XXXHP	96 K	8 K			
M30290MCV-XXXHP	128 K	12 K			
M30291M8V-XXXHP	64 K	4 K	PLQP0064KB-A (64P6Q-A)		
M30291MAV-XXXHP	96 K	8 K			
M30291MCV-XXXHP	128 K	12 K			

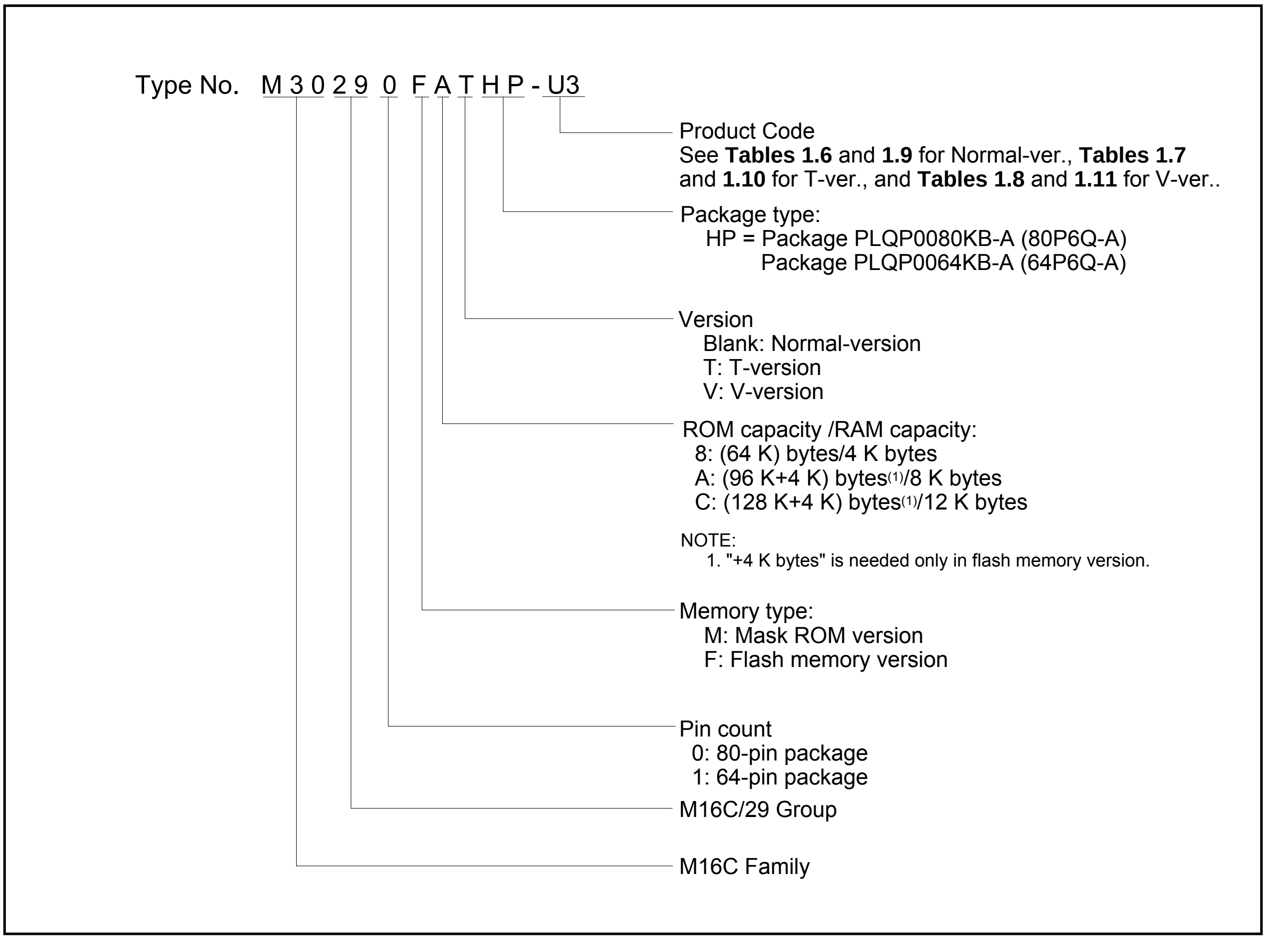


Figure 1.3 Type No., Memory Size, and Package

Table 1.6 Product Codes of Flash Memory Version -M16C/29 Group, Normal-ver.

Product Code	Package	Internal ROM (User Program Space: Blocks 0 to 5)		Internal ROM (Data Space: Blocks A and B)		Operating Ambient Temperature
		Program and Erase Endurance	Temperature Range	Program and Erase Endurance	Temperature Range	
U3	Lead-free	100	0 to 60℃	100	0 to 60℃	-40 to 85℃
U5						-20 to 85℃
U7		1,000		10,000	-40 to 85℃	-40 to 85℃
U9					-20 to 85℃	-20 to 85℃

Table 1.7 Product Codes of Flash Memory Version -M16C/29 Group, T-ver.

Product Code	Package	Internal ROM (User Program Space: Blocks 0 to 5)		Internal ROM (Data Space: Blocks A and B)		Operating Ambient Temperature
		Program and Erase Endurance	Temperature Range	Program and Erase Endurance	Temperature Range	
U3	Lead-free	100	0 to 60℃	100	-40 to 85℃	-40 to 85℃
U7		1,000		10,000		

Table 1.8 Product Codes of Flash Memory Version -M16C/29 Group, V-ver.

Product Code	Package	Internal ROM (User Program Space: Blocks 0 to 5)		Internal ROM (Data Space: Blocks A and B)		Operating Ambient Temperature
		Program and Erase Endurance	Temperature Range	Program and Erase Endurance	Temperature Range	
U3	Lead-free	100	0 to 60℃	100	-40 to 125℃	-40 to 125℃
U7		1,000		10,000		

Table 1.9 Product Codes of Mask ROM Version -M16C/29 Group, Normal-ver.

Product Code	Package	Operating Ambient Temperature
U3	Lead-free	-40 to 85℃
U5		-20 to 85℃

Table 1.10 Product Code of Mask ROM Version -M16C/29 Group, T-ver.

Product Code	Package	Operating Ambient Temperature
U0	Lead-free	-40 to 85℃

Table 1.11 Product Code of Mask ROM Version -M16C/29 Group, V-ver.

Product Code	Package	Operating Ambient Temperature
U0	Lead-free	-40 to 125℃

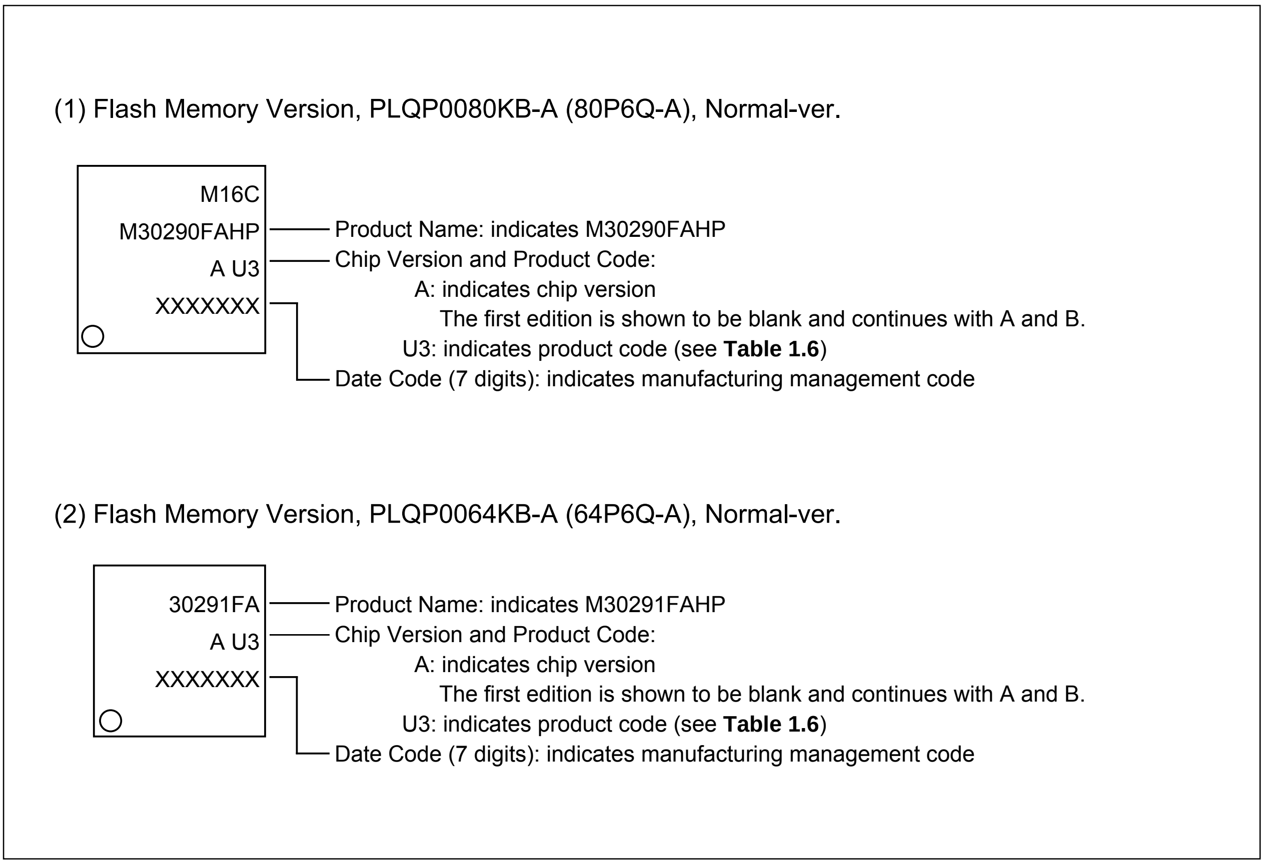


Figure 1.4 Marking Diagrams of Flash Memory Version - M16C/29 Group Normal-ver. (Top View)

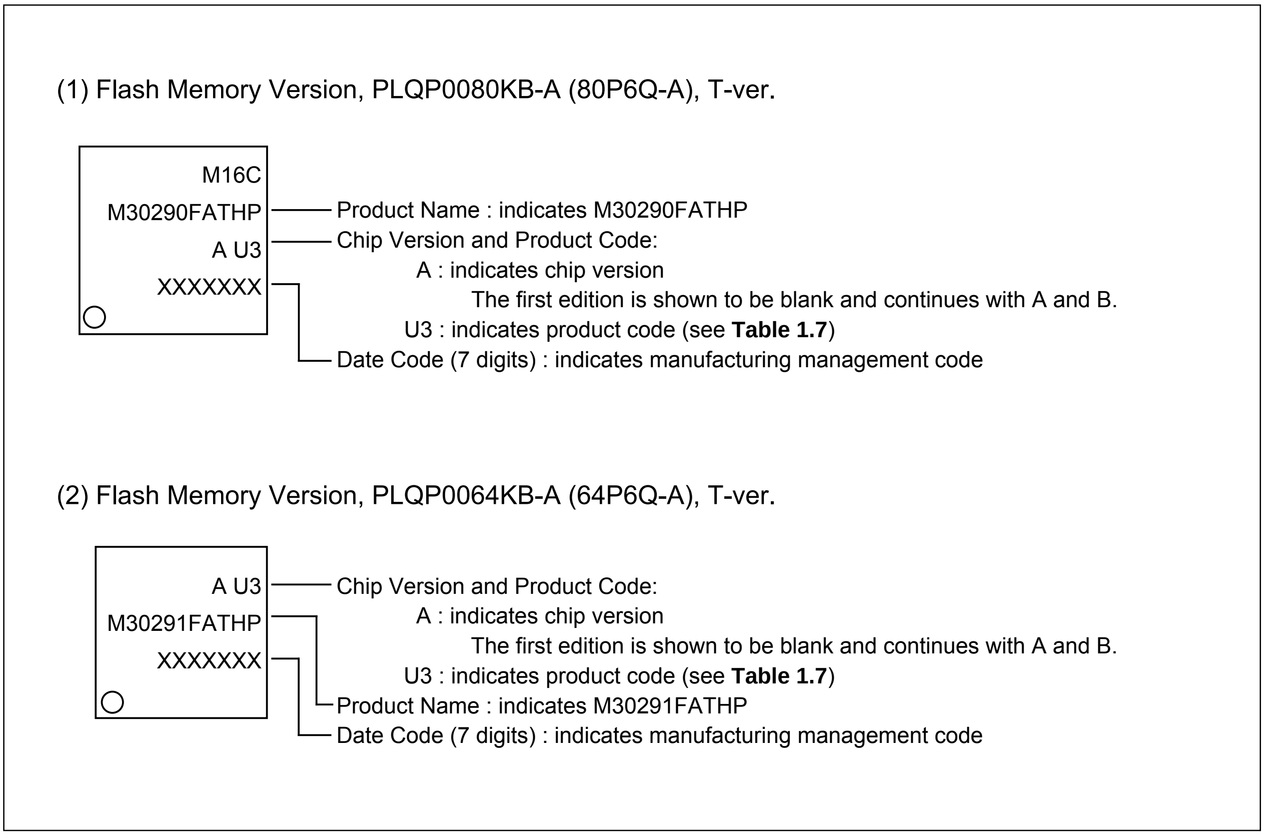


Figure 1.5 Marking Diagrams of Flash Memory Version - M16C/29 Group T-ver. (Top View)

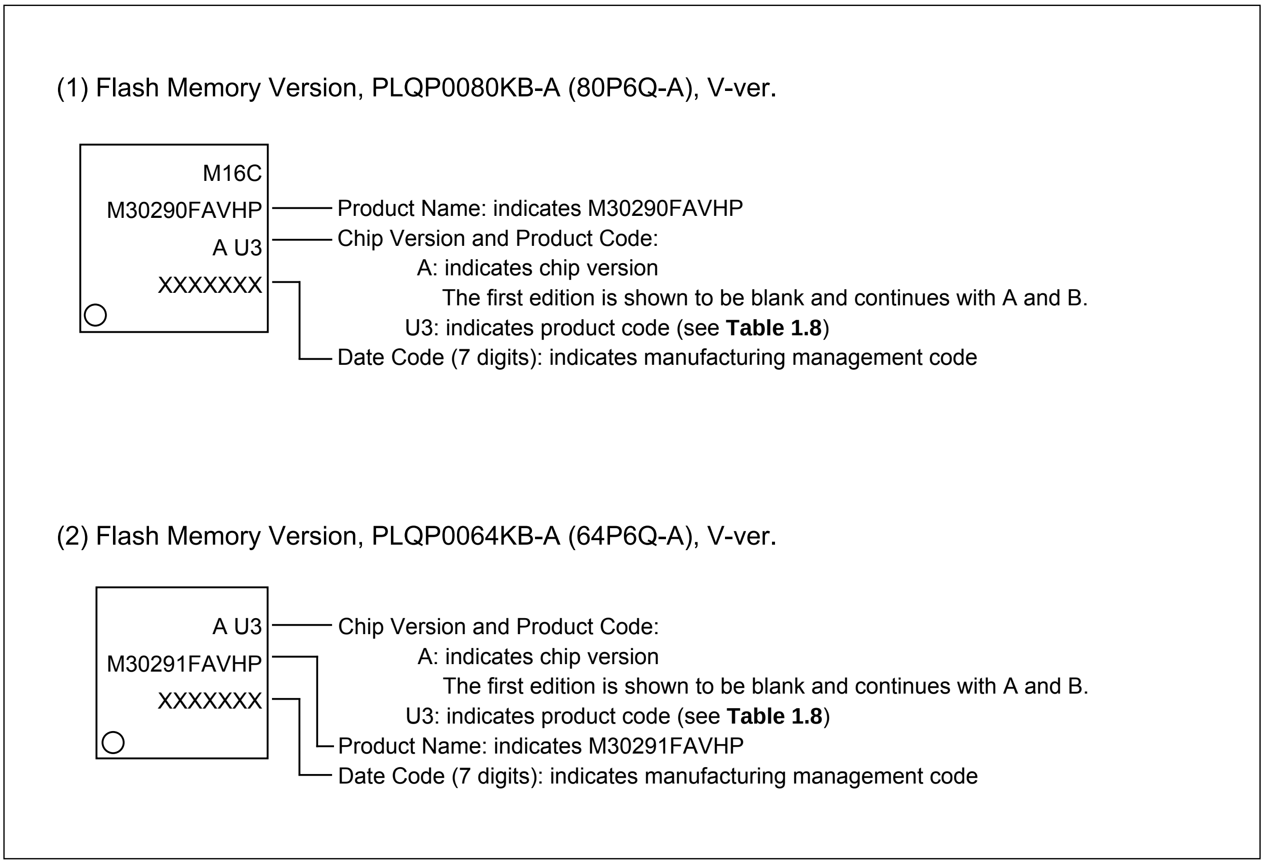


Figure 1.6 Marking Diagrams of Flash Memory Version - M16C/29 Group V-ver. (Top View)

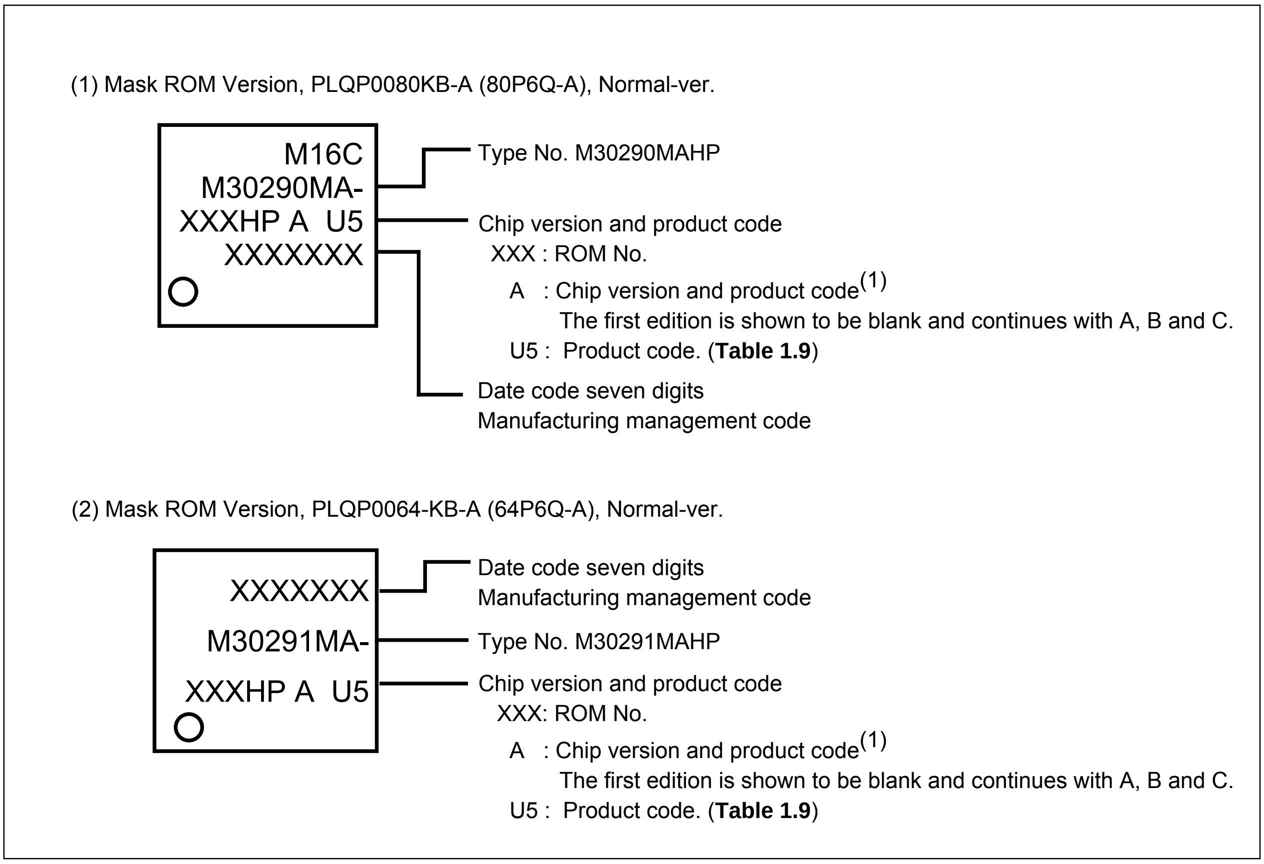
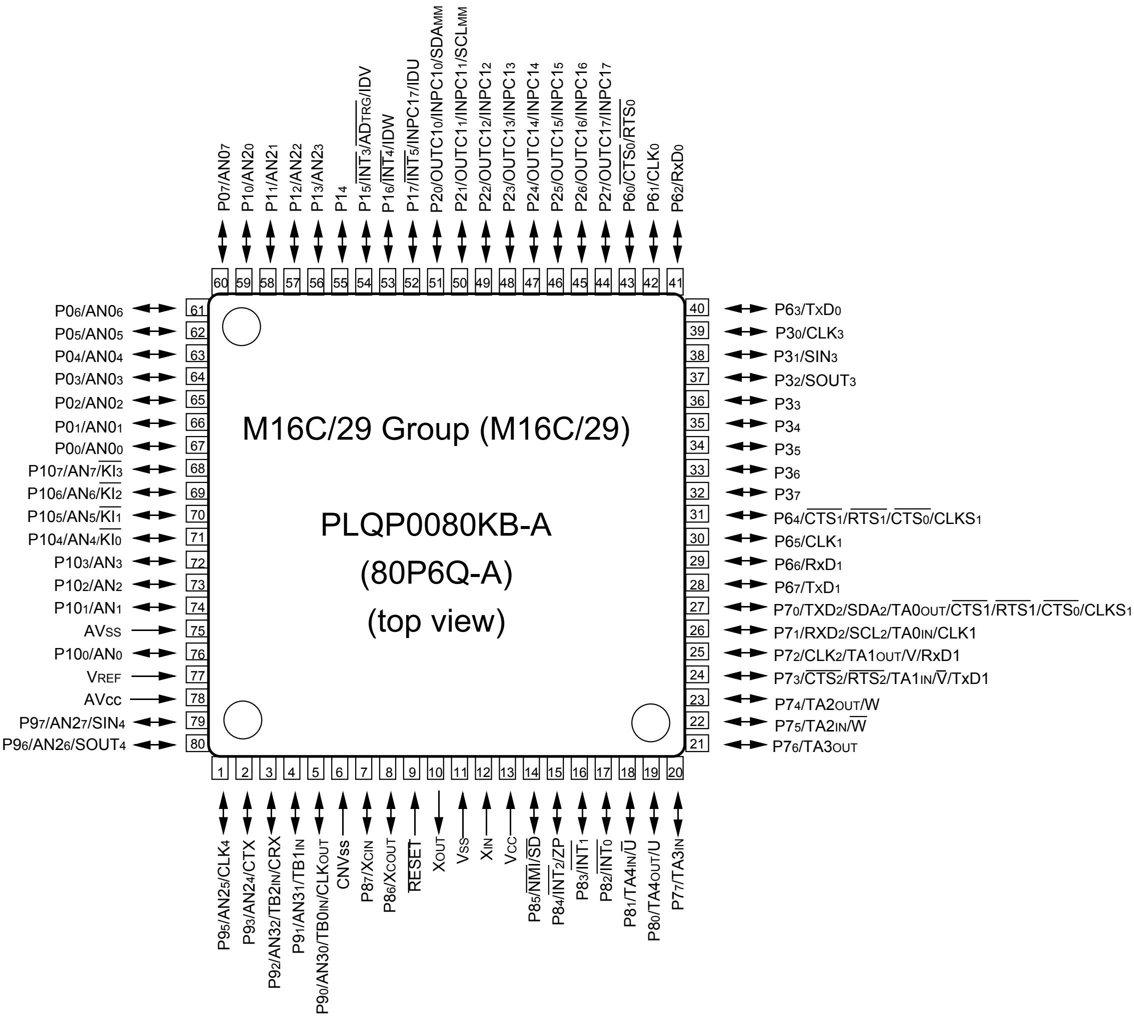


Figure 1.7 Marking Diagrams of Mask ROM Version - M16C/29 Group Normal-ver. (Top View)

1.4 Pin Assignments

Figures 1.7 and 1.8 show the pin assignments (top view).



NOTE:

1.Set bits PACR2 to PACR0 in the PACR register to "011_2" before signals are input or output to individual pins after reset. When the PACR register is not set, signals are not input or output for some

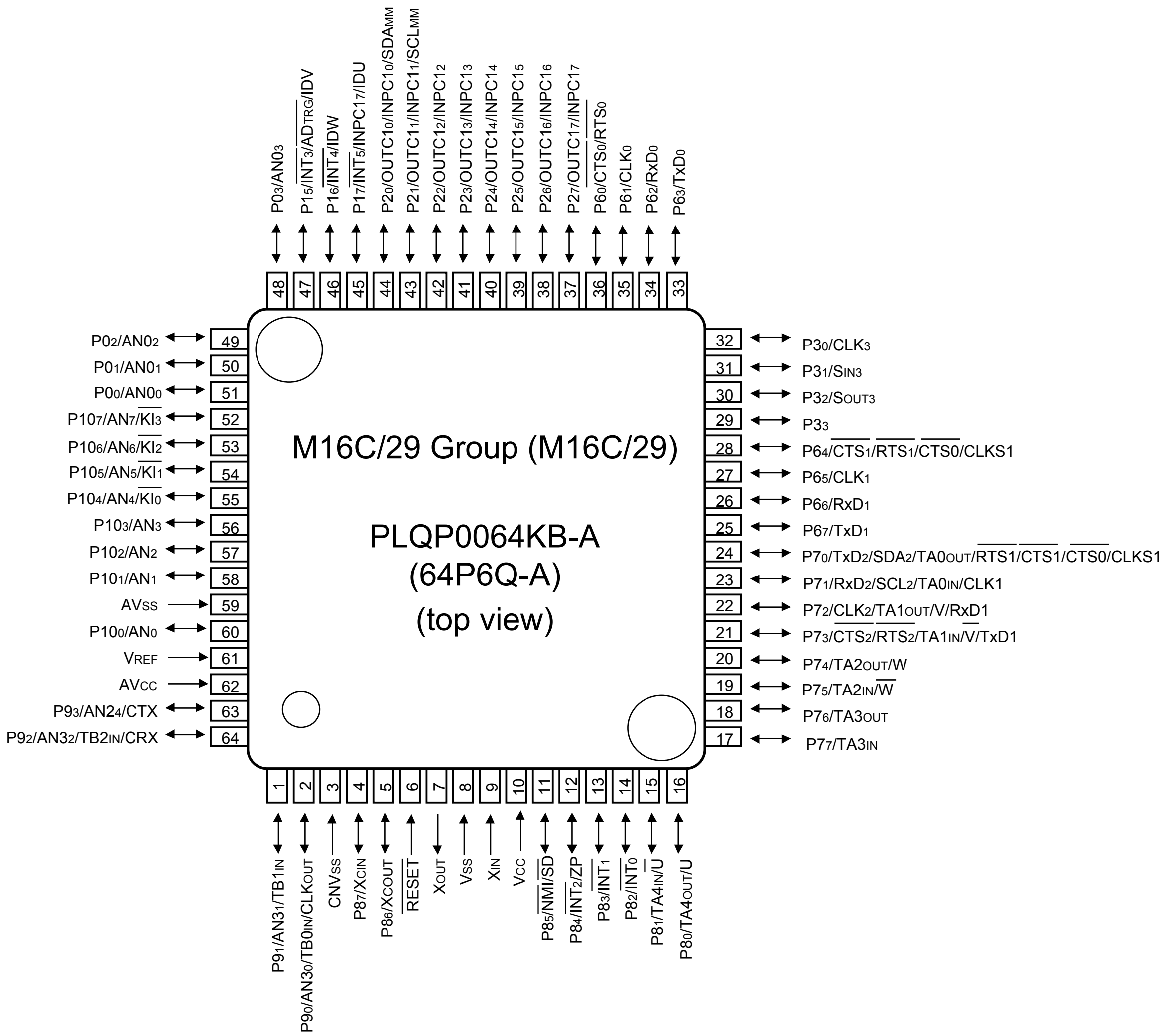
Figure 1.8 Pin Assignment (Top View) of 80-Pin Package

Table 1.12 Pin Characteristics for 80-Pin Package

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	Timer S Pin	UART/CAN Pin	Multi-master I^2C bus Pin	Analog Pin
1		$P9_5$				CLK_4		$AN2_5$
2		$P9_3$				CTX		$AN2_4$
3		$P9_2$		$TB2_{IN}$		CRX		$AN3_2$
4		$P9_1$		$TB1_{IN}$				$AN3_1$
5	CLK_{OUT}	$P9_0$		$TB0_{IN}$				$AN3_0$
6	CNVss							
7	X_{CIN}	$P8_7$						
8	X_{COUT}	$P8_6$						
9	$\overline{RESET}$							
10	X_{OUT}							
11	Vss							
12	X_{IN}							
13	Vcc							
14		$P8_5$	$\overline{NMI}$	SD				
15		$P8_4$	$\overline{INT_2}$	ZP				
16		$P8_3$	$\overline{INT_1}$					
17		$P8_2$	$\overline{INT_0}$					
18		$P8_1$		$TA4_{IN}$ / $\overline{U}$				
19		$P8_0$		$TA4_{OUT}$ / U				
20		$P7_7$		$TA3_{IN}$				
21		$P7_6$		$TA3_{OUT}$				
22		$P7_5$		$TA2_{IN}$ / $\overline{W}$				
23		$P7_4$		$TA2_{OUT}$ / W				
24		$P7_3$		$TA1_{IN}$ / $\overline{V}$		$\overline{CTS_2}$ / $\overline{RTS_2}$ / TxD_1		
25		$P7_2$		$TA1_{OUT}$ / V		CLK_2 / RxD_1		
26		$P7_1$		$TA0_{IN}$		RxD_2 / SCL_2 / CLK_1		
27		$P7_0$		$TA0_{OUT}$		TxD_2 / SDA_2 / $\overline{RTS_1}$ / $\overline{CTS_1}$ / $\overline{CTS_0}$ / $CLKS_1$		
28		$P6_7$				TxD_1		
29		$P6_6$				RxD_1		
30		$P6_5$				CLK_1		
31		$P6_4$				$\overline{RTS_1}$ / $\overline{CTS_1}$/ $\overline{CTS_0}$ / $CLKS_1$		
32		$P3_7$						
33		$P3_6$						
34		$P3_5$						
35		$P3_4$						
36		$P3_3$						
37		$P3_2$				S_{OUT3}		
38		$P3_1$				S_{IN3}		
39		$P3_0$				CLK_3		
40		$P6_3$				TxD_0		

Table 1.12 Pin Characteristics for 80-Pin Package (continued)

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	Timer S Pin	UART/CAN Pin	Multi-master I^2C bus Pin	Analog Pin
41		$P6_2$				RxD_0		
42		$P6_1$				CLK_0		
43		$P6_0$				$\overline{RTS_0}$ / $\overline{CTS_0}$		
44		$P2_7$			$OUTC1_7$ / $INPC1_7$			
45		$P2_6$			$OUTC1_6$ / $INPC1_6$			
46		$P2_5$			$OUTC1_5$ / $INPC1_5$			
47		$P2_4$			$OUTC1_4$ / $INPC1_4$			
48		$P2_3$			$OUTC1_3$ / $INPC1_3$			
49		$P2_2$			$OUTC1_2$ / $INPC1_2$			
50		$P2_1$			$OUTC1_1$ / $INPC1_1$		SCL_{MM}	
51		$P2_0$			$OUTC1_0$ / $INPC1_0$		SDA_{MM}	
52		$P1_7$	$\overline{INT_5}$	IDU	$INPC1_7$			
53		$P1_6$	$\overline{INT_4}$	IDW				
54		$P1_5$	$\overline{INT_3}$	IDV				$\overline{AD_{TRG}}$
55		$P1_4$						
56		$P1_3$						$AN2_3$
57		$P1_2$						$AN2_2$
58		$P1_1$						$AN2_1$
59		$P1_0$						$AN2_0$
60		$P0_7$						$AN0_7$
61		$P0_6$						$AN0_6$
62		$P0_5$						$AN0_5$
63		$P0_4$						$AN0_4$
64		$P0_3$						$AN0_3$
65		$P0_2$						$AN0_2$
66		$P0_1$						$AN0_1$
67		$P0_0$						$AN0_0$
68		$P10_7$	$\overline{KI_3}$					AN_7
69		$P10_6$	$\overline{KI_2}$					AN_6
70		$P10_5$	$\overline{KI_1}$					AN_5
71		$P10_4$	$\overline{KI_0}$					AN_4
72		$P10_3$						AN_3
73		$P10_2$						AN_2
74		$P10_1$						AN_1
75	AV_{SS}							
76		$P10_0$						AN_0
77	V_{REF}							
78	AV_{CC}							
79		$P9_7$				S_{IN4}		$AN2_7$
80		$P9_6$				S_{OUT4}		$AN2_6$



NOTES:
1.Set bits PACR2 to PACR0 in the PACR register to "010$_2$" before signals are input or output to individual pins after reset. When the PACR register is not set, signals are not input or output for some

Figure 1.9 Pin Assignment (Top View) of 64-Pin Package

Table 1.13 Pin Characteristics for 64-Pin Package

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	Timer S Pin	UART/CAN Pin	Mult-master I^2C bus Pin	Analog Pin
1		$P9_1$		$TB1_{IN}$				$AN3_1$
2	CLK_{OUT}	$P9_0$		$TB0_{IN}$				$AN3_0$
3	CNVss							
4	X_{CIN}	$P8_7$						
5	X_{COUT}	$P8_6$						
6	$\overline{\text{RESET}}$							
7	X_{OUT}							
8	Vss							
9	X_{IN}							
10	Vcc							
11		$P8_5$	$\overline{\text{NMI}}$	SD				
12		$P8_4$	$\overline{\text{INT2}}$	ZP				
13		$P8_3$	$\overline{\text{INT1}}$					
14		$P8_2$	$\overline{\text{INT0}}$					
15		$P8_1$		$TA4_{IN}$ / $\overline{U}$				
16		$P8_0$		$TA4_{OUT}$ / U				
17		$P7_7$		$TA3_{IN}$				
18		$P7_6$		$TA3_{OUT}$				
19		$P7_5$		$TA2_{IN}$ / $\overline{W}$				
20		$P7_4$		$TA2_{OUT}$ / W				
21		$P7_3$		$TA1_{IN}$ / $\overline{V}$		$\overline{CTS_2}$ / $\overline{RTS_2}$ / TxD_1		
22		$P7_2$		$TA1_{OUT}$ / V		CLK_2 / RxD_1		
23		$P7_1$		$TA0_{IN}$		RxD_2 / SCL_2 / CLK_1		
24		$P7_0$		$TA0_{OUT}$		TxD_2 / SDA_2 / $\overline{RTS_1}$ / $\overline{CTS_1}$ / $\overline{CTS_0}$ / $CLKS_1$		
25		$P6_7$				TxD_1		
26		$P6_6$				RxD_1		
27		$P6_5$				CLK_1		
28		$P6_4$				$\overline{RTS_1}$ / $\overline{CTS_1}$/ $\overline{CTS_0}$ / $CLKS_1$		
29		$P3_3$						
30		$P3_2$				S_{OUT3}		
31		$P3_1$				S_{IN3}		
32		$P3_0$				CLK_3		
33		$P6_3$				TxD_0		
34		$P6_2$				RxD_0		
35		$P6_1$				CLK_0		
36		$P6_0$				$\overline{RTS_0}$ / $\overline{CTS_0}$		
37		$P2_7$			$OUTC1_7$ / $INPC1_7$			
38		$P2_6$			$OUTC1_6$ / $INPC1_6$			
39		$P2_5$			$OUTC1_5$ / $INPC1_5$			
40		$P2_4$			$OUTC1_4$ / $INPC1_4$			

Table 1.13 Pin Characteristics for 64-Pin Package (continued)

Pin No.	Control Pin	Port	Interrupt Pin	Timer Pin	Timer S Pin	UART/CAN Pin	Multi-master I^2C bus Pin	Analog Pin
41		$P2_3$			$OUTC1_3$ / $INPC1_3$			
42		$P2_2$			$OUTC1_2$ / $INPC1_2$			
43		$P2_1$			$OUTC1_1$ / $INPC1_1$		SCL_{MM}	
44		$P2_0$			$OUTC1_0$ / $INPC1_0$		SDA_{MM}	
45		$P1_7$	$\overline{INT_5}$	IDU	$INPC1_7$			
46		$P1_6$	$\overline{INT_4}$	IDW				
47		$P1_5$	$\overline{INT_3}$	IDV				$\overline{AD_{TRG}}$
48		$P0_3$						$AN0_3$
49		$P0_2$						$AN0_2$
50		$P0_1$						$AN0_1$
51		$P0_0$						$AN0_0$
52		$P10_7$	$\overline{KI_3}$					AN_7
53		$P10_6$	$\overline{KI_2}$					AN_6
54		$P10_5$	$\overline{KI_1}$					AN_5
55		$P10_4$	$\overline{KI_0}$					AN_4
56		$P10_3$						AN_3
57		$P10_2$						AN_2
58		$P10_1$						AN_1
59	AVss							
60		$P10_0$						AN_0
61	V_{REF}							
62	AVcc							
63		$P9_3$				CTX		$AN2_4$
64		$P9_2$		$TB2_{IN}$		CRX		$AN3_2$

1.5 Pin Description

Table 1.14 Pin Description (64-pin and 80-pin packages)

Classification	Symbol	I/O Type	Function
Power supply	VCC, VSS	I	Apply 0V to the Vss pin. Apply following voltage to the Vcc pin. 2.7 to 5.5 V (Normal), 3.0 to 5.5 V (T-ver.), 4.2 to 5.5 V (V-ver.)
Analog power supply	AVCC AVSS	I	Supplies power to the A/D converter. Connect the AVCC pin to VCC and the AVSS pin to VSS
Reset input	$\overline{\text{RESET}}$	I	The microcomputer is in a reset state when "L" is applied to the $\overline{\text{RESET}}$ pin
CNVSS	CNVSS	I	Connect the CNVSS pin to VSS
Main clock input	XIN	I	I/O pins for the main clock oscillation circuit. Connect a ceramic resonator or crystal oscillator between XIN and XOUT. To apply external clock, apply it to XIN and leave XOUT open. If XIN is not used (for external oscillator or external clock) connect XIN pin to VCC and leave XOUT open
Main clock output	XOUT	O	
Sub clock input	XCIN	I	I/O pins for the sub clock oscillation circuit. Connect a crystal oscillator between XCIN and XCOUT
Sub clock output	XCOUT	O	
Clock output	CLKOUT	O	Outputs the clock having the same frequency as f1, f8, f32, or fC
$\overline{\text{INT}}$ interrupt input	$\overline{\text{INT0}}$ to $\overline{\text{INT5}}$	I	Input pins for the $\overline{\text{INT}}$ interrupt. $\overline{\text{INT2}}$ can be used for Timer A Z-phase function
$\overline{\text{NMI}}$ interrupt input	$\overline{\text{NMI}}$	I	Input pin for the $\overline{\text{NMI}}$ interrupt. $\overline{\text{NMI}}$ cannot be used as I/O port while the three-phase motor control is enabled. Apply a stable "H" to $\overline{\text{NMI}}$ after setting it's direction register to "0" when the three-phase motor control is enabled
Key input interrupt	$\overline{\text{KI0}}$ to $\overline{\text{KI3}}$	I	Input pins for the key input interrupt
Timer A	TA0OUT to TA4OUT	I/O	I/O pins for the timer A0 to A4
	TA0IN to TA4IN	I	Input pins for the timer A0 to A4
	ZP	I	Input pin for Z-phase
Timer B	TB0IN to TB2IN	I	Input pins for the timer B0 to B2
Three-phase motor control timer output	U, $\overline{\text{U}}$, V, $\overline{\text{V}}$, W, $\overline{\text{W}}$	O	Output pins for the three-phase motor control timer
	IDU, IDW, IDV, $\overline{\text{SD}}$	I/O	Input and output pins for the three-phase motor control timer
Serial I/O	$\overline{\text{CTS0}}$ to $\overline{\text{CTS2}}$	I	Input pins for data transmission control
	$\overline{\text{RTS0}}$ to $\overline{\text{RTS2}}$	O	Output pins for data reception control
	CLK0 to CLK3	I/O	Inputs and outputs the transfer clock
	RxD0 to RxD2	I	Inputs serial data
	SIN3	I	Inputs serial data
	TxD0 to TxD2	O	Outputs serial data
	SOUT3	O	Outputs serial data
	CLKS1	O	Output pin for transfer clock
I²C bus Mode	SDA2	I/O	Inputs and outputs serial data
	SCL2		Inputs and outputs the transfer clock
Multi-master I²C bus	SDAMM	I/O	Inputs and outputs serial data
	SCLMM		Inputs and outputs the transfer clock
Reference voltage input	VREF	I	Applies reference voltage to the A/D converter
A/D converter	AN0 to AN7 AN00 to AN03 AN24 AN30 to AN32	I	Analog input pins for the A/D converter
	$\overline{\text{ADTRG}}$	I	Input pin for an external A/D trigger

I: Input O: Output I/O: Input and output

Table 1.14 Pin Description (64-pin and 80-pin packages) (Continued)

Classification	Symbol	I/O Type	Function
Timer S	$INPC1_0$ to $INPC1_7$	I	Input pins for the time measurement function
	$OUTC1_0$ to $OUTC1_7$	O	Output pins for the waveform generating function
CAN	CRX	I	Input pin for the CAN communication function
	CTX	O	Output pin for the CAN communication function
I/O Ports	$P0_0$ to $P0_3$ $P1_5$ to $P1_7$ $P2_0$ to $P2_7$ $P3_0$ to $P3_3$ $P6_0$ to $P6_7$ $P7_0$ to $P7_7$ $P8_0$ to $P8_7$ $P9_0$ to $P9_3$ $P10_0$ to $P10_7$	I/O	CMOS I/O ports which have a direction register determines an individual pin is used as an input port or an output port. A pull-up resistor is selectable for every 4 input ports.

I: Input O: Output I/O: Input and output

Table 1.14 Pin Description (80-pin packages only) (Continued)

Classification	Symbol	I/O Type	Function
Serial I/O	CLK4	I/O	Inputs and outputs the transfer clock
	SIN4	I	Inputs serial data
	SOUT4	O	Outputs serial data
A/D Converter	$AN0_4$ to $AN0_7$ $AN2_0$ to $AN2_3$ $AN2_5$ to $AN2_7$	I	Analog input pins for the A/D converter
I/O Ports	$P0_4$ to $P0_7$ $P1_0$ to $P1_4$ $P3_4$ to $P3_7$ $P9_5$ to $P9_7$	I/O	CMOS I/O ports which have a direction register determines an individual pin is used as an input port or an output port. A pull-up resistor is selectable for every 4 input ports.

I : Input O : Output I/O : Input and output

2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU registers. The CPU has 13 registers. Of these, R0, R1, R2, R3, A0, A1 and FB comprise a register bank. There are two register banks.

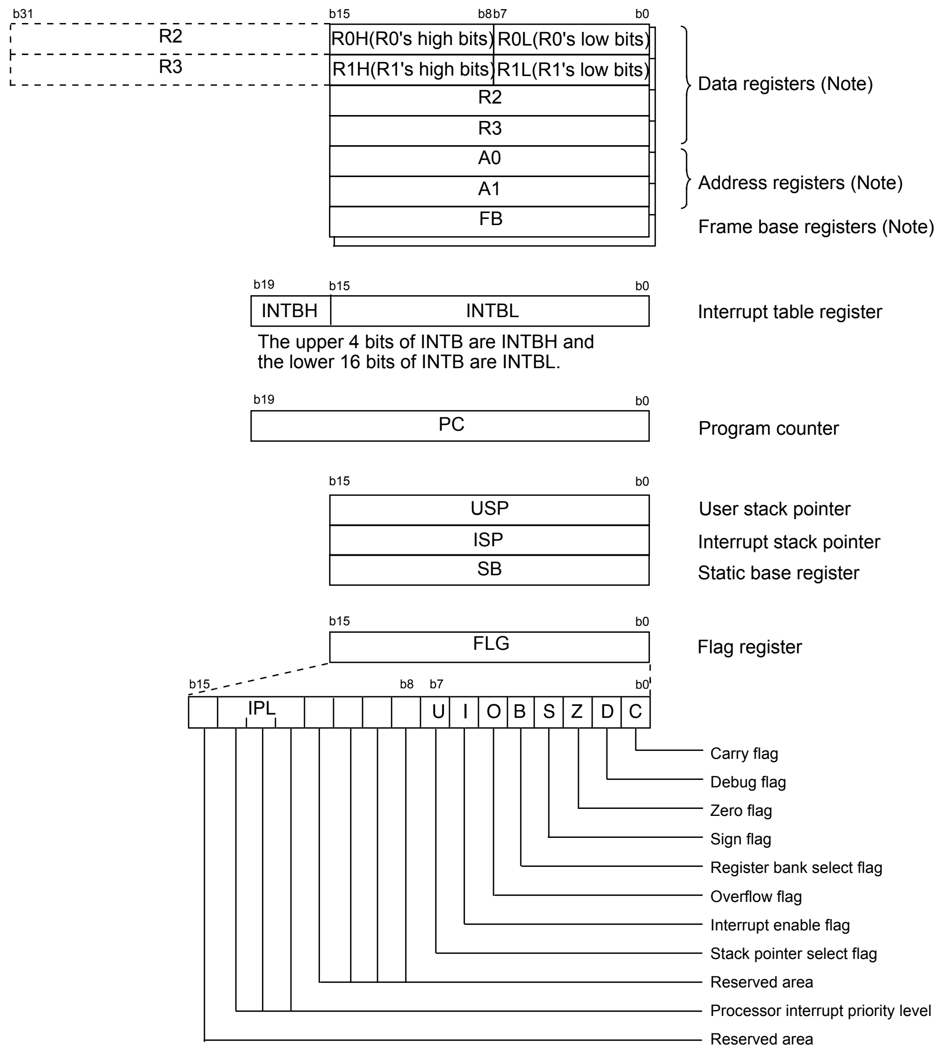


Figure 2.1. Central Processing Unit Register

2.1 Data Registers (R0, R1, R2 and R3)

The R0 register consists of 16 bits, and is used mainly for transfers and arithmetic/logic operations. R1 to R3 are the same as R0.

The R0 register can be separated between high (R0H) and low (R0L) for use as two 8-bit data registers. R1H and R1L are the same as R0H and R0L. Conversely, R2 and R0 can be combined for use as a 32-bit data register (R2R0). R3R1 is the same as R2R0.

2.2 Address Registers (A0 and A1)

The register A0 consists of 16 bits, and is used for address register indirect addressing and address register relative addressing. They also are used for transfers and arithmetic/logic operations. A1 is the same as A0.

In some instructions, registers A1 and A0 can be combined for use as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is configured with 16 bits, and is used for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is configured with 20 bits, indicating the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC is configured with 20 bits, indicating the address of an instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

Stack pointer (SP) comes in two types: USP and ISP, each configured with 16 bits.
Your desired type of stack pointer (USP or ISP) can be selected by the U flag of FLG.

2.7 Static Base Register (SB)

SB is configured with 16 bits, and is used for SB relative addressing.

2.8 Flag Register (FLG)

FLG consists of 11 bits, indicating the CPU status.

2.8.1 Carry Flag (C Flag)

This flag retains a carry, borrow, or shift-out bit that has occurred in the arithmetic/logic unit.

2.8.2 Debug Flag (D Flag)

The D flag is used exclusively for debugging purpose. During normal use, it must be set to 0.

2.8.3 Zero Flag (Z Flag)

This flag is set to 1 when an arithmetic operation resulted in 0; otherwise, it is 0.

2.8.4 Sign Flag (S Flag)

This flag is set to 1 when an arithmetic operation resulted in a negative value; otherwise, it is 0.

2.8.5 Register Bank Select Flag (B Flag)

Register bank 0 is selected when this flag is 0 ; register bank 1 is selected when this flag is 1.

2.8.6 Overflow Flag (O Flag)

This flag is set to 1 when the operation resulted in an overflow; otherwise, it is 0.

2.8.7 Interrupt Enable Flag (I Flag)

This flag enables a maskable interrupt.
Maskable interrupts are disabled when the I flag is 0, and are enabled when the I flag is 1.
The I flag is cleared to 0 when the interrupt request is accepted.

2.8.8 Stack Pointer Select Flag (U Flag)

ISP is selected when the U flag is 0; USP is selected when the U flag is 1.
The U flag is cleared to 0 when a hardware interrupt request is accepted or an INT instruction for software interrupt Nos. 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is configured with three bits, for specification of up to eight processor interrupt priority levels from level 0 to level 7.
If a requested interrupt has priority greater than IPL, the interrupt is enabled.

2.8.10 Reserved Area

When write to this bit, write 0. When read, its content is undefined.

3. Memory

Figure 3.1 is a memory map of the M16C/29 Group. M16C/29 Group provides 1-Mbyte address space from addresses 00000_{16} to $FFFFF_{16}$. The internal ROM is allocated lower addresses beginning with address $FFFFF_{16}$. For example, 64-Kbytes internal ROM is allocated addresses $F0000_{16}$ to $FFFFF_{16}$.

Two 2-Kbyte internal ROM areas, block A and block B, are available in the flash memory version. The blocks are allocated addresses $F000_{16}$ to $FFFF_{16}$.

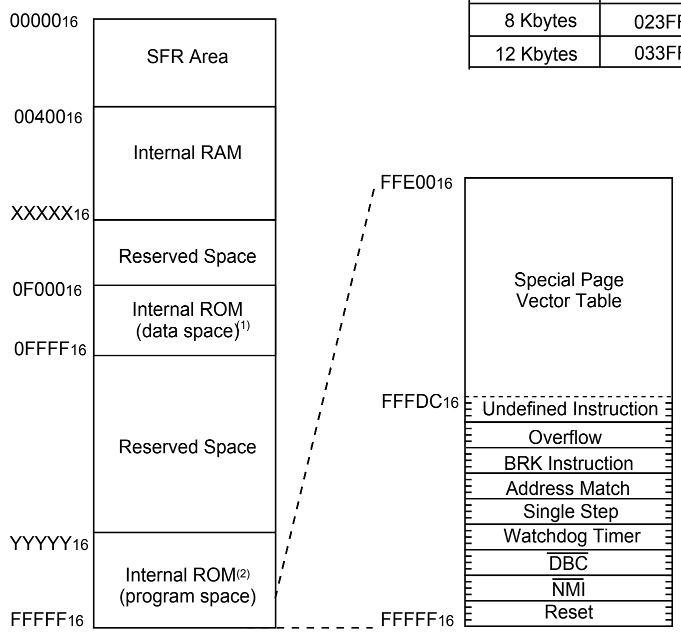
The fixed interrupt vector tables are allocated addresses $FFFDC_{16}$ to $FFFFF_{16}$. It stores the starting address of each interrupt routine. See the section on interrupts for details.

The internal RAM is allocated higher addresses beginning with address 00400_{16}. For example, 4-Kbytes internal RAM is allocated addresses 00400_{16} to $013FF_{16}$. Besides sotring data, it becomes stacks when the subroutines is called or an interrupt is acknowledged.

SFR, consisting of control registers for peripheral functions such as I/O port, A/D converter, serial I/O, timers is allocated addresses 00000_{16} to $003FF_{16}$. All blank spaces within SFR are reserved and cannot be accessed by users.

The special page vector table is allocated to the addresses $FFE00_{16}$ to $FFFDB_{16}$. This vector is used by the JMPS or JSRS instruction. For details, refer to the ***M16C/60 and M16C/20 Series Software Manual***.

Internal RAM area		Internal ROM area	
Memory size	$XXXXX_{16}$	Memory size	$YYYYY_{16}$
4 Kbytes	$013FF_{16}$	64 Kbytes	$F0000_{16}$
8 Kbytes	$023FF_{16}$	96 Kbytes	$E8000_{16}$
12 Kbytes	$033FF_{16}$	128 Kbytes	$E0000_{16}$



NOTES:
1. The block A (2K bytes) and block B (2K bytes) are shown (only flash memory).
2. Do not write to the internal ROM area in Mask ROM ver..

Figure 3.1 Memory Map

4. Special Function Registers (SFRs)

SFRs (Special Function Registers) are the control registers of peripheral functions. **Table 4.1** to **4.11** list the SFR address map.

Table 4.1 SFR Information (1)

Address	Register	Symbol	After reset
0000_{16}			
0001_{16}			
0002_{16}			
0003_{16}			
0004_{16}	Processor mode register 0	PM0	00_{16}
0005_{16}	Processor mode register 1	PM1	00001000_2
0006_{16}	System clock control register 0	CM0	01001000_2
0007_{16}	System clock control register 1	CM1	00100000_2
0008_{16}			
0009_{16}	Address match interrupt enable register	AIER	$XXXXXX00_2$
$000A_{16}$	Protect register	PRCR	$XX000000_2$
$000B_{16}$			
$000C_{16}$	Oscillation stop detection register (Note 2)	CM2	$0X000010_2$
$000D_{16}$			
$000E_{16}$	Watchdog timer start register	WDTS	XX_{16}
$000F_{16}$	Watchdog timer control register	WDC	$00XXXXXX_2$
0010_{16}	Address match interrupt register 0	RMAD0	00_{16}
0011_{16}			00_{16}
0012_{16}			$X0_{16}$
0013_{16}			
0014_{16}	Address match interrupt register 1	RMAD1	00_{16}
0015_{16}			00_{16}
0016_{16}			$X0_{16}$
0017_{16}			
0018_{16}			
0019_{16}	Voltage detection register 1 (Note 3,4)	VCR1	00001000_2
$001A_{16}$	Voltage detection register 2 (Note 3,4)	VCR2	00_{16}
$001B_{16}$			
$001C_{16}$	PLL control register 0	PLC0	$0001X010_2$
$001D_{16}$			
$001E_{16}$	Processor mode register 2	PM2	$XXX00000_2$
$001F_{16}$	Low voltage detection interrupt register (Note 4)	D4INT	00_{16}
0020_{16}	DMA0 source pointer	SAR0	XX_{16}
0021_{16}			XX_{16}
0022_{16}			XX_{16}
0023_{16}			
0024_{16}	DMA0 destination pointer	DAR0	XX_{16}
0025_{16}			XX_{16}
0026_{16}			XX_{16}
0027_{16}			
0028_{16}	DMA0 transfer counter	TCR0	XX_{16}
0029_{16}			XX_{16}
$002A_{16}$			
$002B_{16}$			
$002C_{16}$	DMA0 control register	DM0CON	$00000X00_2$
$002D_{16}$			
$002E_{16}$			
$002F_{16}$			
0030_{16}	DMA1 source pointer	SAR1	XX_{16}
0031_{16}			XX_{16}
0032_{16}			XX_{16}
0033_{16}			
0034_{16}	DMA1 destination pointer	DAR1	XX_{16}
0035_{16}			XX_{16}
0036_{16}			XX_{16}
0037_{16}			
0038_{16}	DMA1 transfer counter	TCR1	XX_{16}
0039_{16}			XX_{16}
$003A_{16}$			
$003B_{16}$			
$003C_{16}$	DMA1 control register	DM1CON	$00000X00_2$
$003D_{16}$			
$003E_{16}$			
$003F_{16}$			

Note 1: The blank areas are reserved and cannot be used by users.
Note 2: Bits CM20, CM21, and CM27 do not change at oscillation stop detection reset.
Note 3: This register does not change at software reset, watchdog timer reset and oscillation stop detection reset.
Note 4: This registe can not use for T-ver. and V-ver.

X : Undefined

Table 4.2 SFR Information (2)

Address	Register	Symbol	After reset
0040_{16}			
0041_{16}	CAN0 wakeup interrupt control register	C01WKIC	$XXXXX000_2$
0042_{16}	CAN0 successful reception interrupt control register	C0RECIC	$XXXXX000_2$
0043_{16}	CAN0 successful transmission interrupt control register	C0TRMIC	$XXXXX000_2$
0044_{16}	INT3 interrupt control register	INT3IC	$XX00X000_2$
0045_{16}	ICOC 0 interrupt control register	ICOC0IC	$XXXXX000_2$
0046_{16}	ICOC 1 interrupt control register, I^2C bus interface interrupt control register 1	ICOC1IC,IICIC	$XXXXX000_2$
0047_{16}	ICOC base timer interrupt control register, SCL/SDA interrupt control register 2	BTIC,SCLDAIC	$XXXXX000_2$
0048_{16}	SI/O4 interrupt control register, INT5 interrupt control register	S4IC, INT5IC	$XX00X000_2$
0049_{16}	SI/O3 interrupt control register, INT4 interrupt control register	S3IC, INT4IC	$XX00X000_2$
$004A_{16}$	UART2 Bus collision detection interrupt control register	BCNIC	$XXXXX000_2$
$004B_{16}$	DMA0 interrupt control register	DM0IC	$XXXXX000_2$
$004C_{16}$	DMA1 interrupt control register	DM1IC	$XXXXX000_2$
$004D_{16}$	CAN0 error interrupt control register	C01ERRIC	$XXXXX000_2$
$004E_{16}$	A/D conversion interrupt control register, Key input interrupt control register (Note 2)	ADIC, KUPIC	$XXXXX000_2$
$004F_{16}$	UART2 transmit interrupt control register	S2TIC	$XXXXX000_2$
0050_{16}	UART2 receive interrupt control register	S2RIC	$XXXXX000_2$
0051_{16}	UART0 transmit interrupt control register	S0TIC	$XXXXX000_2$
0052_{16}	UART0 receive interrupt control register	S0RIC	$XXXXX000_2$
0053_{16}	UART1 transmit interrupt control register	S1TIC	$XXXXX000_2$
0054_{16}	UART1 receive interrupt control register	S1RIC	$XXXXX000_2$
0055_{16}	TimerA0 interrupt control register	TA0IC	$XXXXX000_2$
0056_{16}	TimerA1 interrupt control register	TA1IC	$XXXXX000_2$
0057_{16}	TimerA2 interrupt control register	TA2IC	$XXXXX000_2$
0058_{16}	TimerA3 interrupt control register	TA3IC	$XXXXX000_2$
0059_{16}	TimerA4 interrupt control register	TA4IC	$XXXXX000_2$
$005A_{16}$	TimerB0 interrupt control register	TB0IC	$XXXXX000_2$
$005B_{16}$	TimerB1 interrupt control register	TB1IC	$XXXXX000_2$
$005C_{16}$	TimerB2 interrupt control register	TB2IC	$XXXXX000_2$
$005D_{16}$	INT0 interrupt control register	INT0IC	$XX00X000_2$
$005E_{16}$	INT1 interrupt control register	INT1IC	$XX00X000_2$
$005F_{16}$	INT2 interrupt control register	INT2IC	$XX00X000_2$
0060_{16}	CAN0 message box 0: Identifier/DLC		XX_{16}
0061_{16}			XX_{16}
0062_{16}			XX_{16}
0063_{16}			XX_{16}
0064_{16}			XX_{16}
0065_{16}			XX_{16}
0066_{16}	CAN0 message box 0 : Data field		XX_{16}
0067_{16}			XX_{16}
0068_{16}			XX_{16}
0069_{16}			XX_{16}
$006A_{16}$			XX_{16}
$006B_{16}$			XX_{16}
$006C_{16}$			XX_{16}
$006D_{16}$			XX_{16}
$006E_{16}$	CAN0 message box 0 : Time stamp		XX_{16}
$006F_{16}$			XX_{16}
0070_{16}	CAN0 message box 1 : Identifier/DLC		XX_{16}
0071_{16}			XX_{16}
0072_{16}			XX_{16}
0073_{16}			XX_{16}
0074_{16}			XX_{16}
0075_{16}			XX_{16}
0076_{16}	CAN0 message box 1 : Data field		XX_{16}
0077_{16}			XX_{16}
0078_{16}			XX_{16}
0079_{16}			XX_{16}
$007A_{16}$			XX_{16}
$007B_{16}$			XX_{16}
$007C_{16}$			XX_{16}
$007D_{16}$			XX_{16}
$007E_{16}$	CAN0 message box 1 : Time stamp		XX_{16}
$007F_{16}$			XX_{16}

Note 1: The blank areas are reserved and cannot be used by users.
Note 2: A/D conversion interrupt control register is effective when the bit1(Interrupt source select register (address 35Eh IFSR2A) is set to "0". Key input interrupt control register is effective when the bit1 is set to "1".
X : Undefined

Table 4.3 SFR Information (3)

Address	Register	Symbol	After reset
0080_{16}	CAN0 message box 2: Identifier/DLC		XX_{16}
0081_{16}			XX_{16}
0082_{16}			XX_{16}
0083_{16}			XX_{16}
0084_{16}			XX_{16}
0085_{16}			XX_{16}
0086_{16}	CAN0 message box 2 : Data field		XX_{16}
0087_{16}			XX_{16}
0088_{16}			XX_{16}
0089_{16}			XX_{16}
$008A_{16}$			XX_{16}
$008B_{16}$			XX_{16}
$008C_{16}$			XX_{16}
$008D_{16}$			XX_{16}
$008E_{16}$	CAN0 message box 2 : Time stamp		XX_{16}
$008F_{16}$			XX_{16}
0090_{16}	CAN0 message box 3 : Identifier/DLC		XX_{16}
0091_{16}			XX_{16}
0092_{16}			XX_{16}
0093_{16}			XX_{16}
0094_{16}			XX_{16}
0095_{16}			XX_{16}
0096_{16}	CAN0 message box 3 : Data field		XX_{16}
0097_{16}			XX_{16}
0098_{16}			XX_{16}
0099_{16}			XX_{16}
$009A_{16}$			XX_{16}
$009B_{16}$			XX_{16}
$009C_{16}$			XX_{16}
$009D_{16}$			XX_{16}
$009E_{16}$	CAN0 message box 3 : Time stamp		XX_{16}
$009F_{16}$			XX_{16}
$00A0_{16}$	CAN0 message box 4: Identifier/DLC		XX_{16}
$00A1_{16}$			XX_{16}
$00A2_{16}$			XX_{16}
$00A3_{16}$			XX_{16}
$00A4_{16}$			XX_{16}
$00A5_{16}$			XX_{16}
$00A6_{16}$	CAN0 message box 4 : Data field		XX_{16}
$00A7_{16}$			XX_{16}
$00A8_{16}$			XX_{16}
$00A9_{16}$			XX_{16}
$00AA_{16}$			XX_{16}
$00AB_{16}$			XX_{16}
$00AC_{16}$			XX_{16}
$00AD_{16}$			XX_{16}
$00AE_{16}$	CAN0 message box 4 : Time stamp		XX_{16}
$00AF_{16}$			XX_{16}
$00B0_{16}$	CAN0 message box 5 : Identifier/DLC		XX_{16}
$00B1_{16}$			XX_{16}
$00B2_{16}$			XX_{16}
$00B3_{16}$			XX_{16}
$00B4_{16}$			XX_{16}
$00B5_{16}$			XX_{16}
$00B6_{16}$	CAN0 message box 5 : Data field		XX_{16}
$00B7_{16}$			XX_{16}
$00B8_{16}$			XX_{16}
$00B9_{16}$			XX_{16}
$00BA_{16}$			XX_{16}
$00BB_{16}$			XX_{16}
$00BC_{16}$			XX_{16}
$00BD_{16}$			XX_{16}
$00BE_{16}$	CAN0 message box 5 : Time stamp		XX_{16}
$00BF_{16}$			XX_{16}

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.4 SFR Information (4)

Address	Register	Symbol	After reset
00C0$_{16}$	CAN0 message box 6: Identifier/DLC		XX$_{16}$
00C1$_{16}$			XX$_{16}$
00C2$_{16}$			XX$_{16}$
00C3$_{16}$			XX$_{16}$
00C4$_{16}$			XX$_{16}$
00C5$_{16}$			XX$_{16}$
00C6$_{16}$	CAN0 message box 6 : Data field		XX$_{16}$
00C7$_{16}$			XX$_{16}$
00C8$_{16}$			XX$_{16}$
00C9$_{16}$			XX$_{16}$
00CA$_{16}$			XX$_{16}$
00CB$_{16}$			XX$_{16}$
00CC$_{16}$			XX$_{16}$
00CD$_{16}$			XX$_{16}$
00CE$_{16}$	CAN0 message box 6 : Time stamp		XX$_{16}$
00CF$_{16}$			XX$_{16}$
00D0$_{16}$	CAN0 message box 7 : Identifier/DLC		XX$_{16}$
00D1$_{16}$			XX$_{16}$
00D2$_{16}$			XX$_{16}$
00D3$_{16}$			XX$_{16}$
00D4$_{16}$			XX$_{16}$
00D5$_{16}$			XX$_{16}$
00D6$_{16}$	CAN0 message box 7 : Data field		XX$_{16}$
00D7$_{16}$			XX$_{16}$
00D8$_{16}$			XX$_{16}$
00D9$_{16}$			XX$_{16}$
00DA$_{16}$			XX$_{16}$
00DB$_{16}$			XX$_{16}$
00DC$_{16}$			XX$_{16}$
00DD$_{16}$			XX$_{16}$
00DE$_{16}$	CAN0 message box 7 : Time stamp		XX$_{16}$
00DF$_{16}$			XX$_{16}$
00E0$_{16}$	CAN0 message box 8: Identifier/DLC		XX$_{16}$
00E1$_{16}$			XX$_{16}$
00E2$_{16}$			XX$_{16}$
00E3$_{16}$			XX$_{16}$
00E4$_{16}$			XX$_{16}$
00E5$_{16}$			XX$_{16}$
00E6$_{16}$	CAN0 message box 8: Data field		XX$_{16}$
00E7$_{16}$			XX$_{16}$
00E8$_{16}$			XX$_{16}$
00E9$_{16}$			XX$_{16}$
00EA$_{16}$			XX$_{16}$
00EB$_{16}$			XX$_{16}$
00EC$_{16}$			XX$_{16}$
00ED$_{16}$			XX$_{16}$
00EE$_{16}$	CAN0 message box 8 : Time stamp		XX$_{16}$
00EF$_{16}$			XX$_{16}$
00F0$_{16}$	CAN0 message box 9 : Identifier/DLC		XX$_{16}$
00F1$_{16}$			XX$_{16}$
00F2$_{16}$			XX$_{16}$
00F3$_{16}$			XX$_{16}$
00F4$_{16}$			XX$_{16}$
00F5$_{16}$			XX$_{16}$
00F6$_{16}$	CAN0 message box 9 : Data field		XX$_{16}$
00F7$_{16}$			XX$_{16}$
00F8$_{16}$			XX$_{16}$
00F9$_{16}$			XX$_{16}$
00FA$_{16}$			XX$_{16}$
00FB$_{16}$			XX$_{16}$
00FC$_{16}$			XX$_{16}$
00FD$_{16}$			XX$_{16}$
00FE$_{16}$	CAN0 message box 9 : Time stamp		XX$_{16}$
00FF$_{16}$			XX$_{16}$

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.5 SFR Information (5)

Address	Register	Symbol	After reset
0100_{16}	CAN0 message box 10: Identifier/DLC		XX_{16}
0101_{16}			XX_{16}
0102_{16}			XX_{16}
0103_{16}			XX_{16}
0104_{16}			XX_{16}
0105_{16}			XX_{16}
0106_{16}	CAN0 message box 10 : Data field		XX_{16}
0107_{16}			XX_{16}
0108_{16}			XX_{16}
0109_{16}			XX_{16}
$010A_{16}$			XX_{16}
$010B_{16}$			XX_{16}
$010C_{16}$			XX_{16}
$010D_{16}$			XX_{16}
$010E_{16}$	CAN0 message box 10 : Time stamp		XX_{16}
$010F_{16}$			XX_{16}
0110_{16}	CAN0 message box 11 : Identifier/DLC		XX_{16}
0111_{16}			XX_{16}
0112_{16}			XX_{16}
0113_{16}			XX_{16}
0114_{16}			XX_{16}
0115_{16}			XX_{16}
0116_{16}	CAN0 message box 11 : Data field		XX_{16}
0117_{16}			XX_{16}
0118_{16}			XX_{16}
0119_{16}			XX_{16}
$011A_{16}$			XX_{16}
$011B_{16}$			XX_{16}
$011C_{16}$			XX_{16}
$011D_{16}$			XX_{16}
$011E_{16}$	CAN0 message box 11 : Time stamp		XX_{16}
$011F_{16}$			XX_{16}
0120_{16}	CAN0 message box 12: Identifier/DLC		XX_{16}
0121_{16}			XX_{16}
0122_{16}			XX_{16}
0123_{16}			XX_{16}
0124_{16}			XX_{16}
0125_{16}			XX_{16}
0126_{16}	CAN0 message box 12: Data field		XX_{16}
0127_{16}			XX_{16}
0128_{16}			XX_{16}
0129_{16}			XX_{16}
$012A_{16}$			XX_{16}
$012B_{16}$			XX_{16}
$012C_{16}$			XX_{16}
$012D_{16}$			XX_{16}
$012E_{16}$	CAN0 message box 12 : Time stamp		XX_{16}
$012F_{16}$			XX_{16}
0130_{16}	CAN0 message box 13 : Identifier/DLC		XX_{16}
0131_{16}			XX_{16}
0132_{16}			XX_{16}
0133_{16}			XX_{16}
0134_{16}			XX_{16}
0135_{16}			XX_{16}
0136_{16}	CAN0 message box 13 : Data field		XX_{16}
0137_{16}			XX_{16}
0138_{16}			XX_{16}
0139_{16}			XX_{16}
$013A_{16}$			XX_{16}
$013B_{16}$			XX_{16}
$013C_{16}$			XX_{16}
$013D_{16}$			XX_{16}
$013E_{16}$	CAN0 message box 13 : Time stamp		XX_{16}
$013F_{16}$			XX_{16}

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.6 SFR Information (6)

Address	Register		Symbol	After reset
0140_{16}	CAN0 message box 14: Identifier/DLC			XX_{16}
0141_{16}				XX_{16}
0142_{16}				XX_{16}
0143_{16}				XX_{16}
0144_{16}				XX_{16}
0145_{16}				XX_{16}
0146_{16}	CAN0 message box 14 : Data field			XX_{16}
0147_{16}				XX_{16}
0148_{16}				XX_{16}
0149_{16}				XX_{16}
$014A_{16}$				XX_{16}
$014B_{16}$				XX_{16}
$014C_{16}$				XX_{16}
$014D_{16}$				XX_{16}
$014E_{16}$	CAN0 message box 14 : Time stamp			XX_{16}
$014F_{16}$				XX_{16}
0150_{16}	CAN0 message box 15 : Identifier/DLC			XX_{16}
0151_{16}				XX_{16}
0152_{16}				XX_{16}
0153_{16}				XX_{16}
0154_{16}				XX_{16}
0155_{16}				XX_{16}
0156_{16}	CAN0 message box 15 : Data field			XX_{16}
0157_{16}				XX_{16}
0158_{16}				XX_{16}
0159_{16}				XX_{16}
$015A_{16}$				XX_{16}
$015B_{16}$				XX_{16}
$015C_{16}$				XX_{16}
$015D_{16}$				XX_{16}
$015E_{16}$	CAN0 message box 15 : Time stamp			XX_{16}
$015F_{16}$				XX_{16}
0160_{16}	CAN0 global mask register		C0GMR	XX_{16}
0161_{16}				XX_{16}
0162_{16}				XX_{16}
0163_{16}				XX_{16}
0164_{16}				XX_{16}
0165_{16}				XX_{16}
0166_{16}	CAN0 local mask A register		C0LMAR	XX_{16}
0167_{16}				XX_{16}
0168_{16}				XX_{16}
0169_{16}				XX_{16}
$016A_{16}$				XX_{16}
$016B_{16}$				XX_{16}
$016C_{16}$	CAN0 local mask B register		C0LMBR	XX_{16}
$016D_{16}$				XX_{16}
$016E_{16}$				XX_{16}
$016F_{16}$				XX_{16}
0170_{16}				XX_{16}
0171_{16}				XX_{16}
≈				≈
$01B3_{16}$	Flash memory control register 4	(Note 2)	FMR4	$0100000X_2$
$01B4_{16}$				
$01B5_{16}$	Flash memory control register 1	(Note 2)	FMR1	$000XXX0X_2$
$01B6_{16}$				
$01B7_{16}$	Flash memory control register 0	(Note 2)	FMR0	01_{16}
≈				≈
$01FD_{16}$				
$01FE_{16}$				
$01FF_{16}$				

Note 1: The blank areas are reserved and cannot be used by users.
Note 2: This register is included in the flash memory version.

X : Undefined

Table 4.7 SFR Information (7)

Address	Register	Symbol	After reset
0200_{16}	CAN0 message control register 0	C0MCTL0	00_{16}
0201_{16}	CAN0 message control register 1	C0MCTL1	00_{16}
0202_{16}	CAN0 message control register 2	C0MCTL2	00_{16}
0203_{16}	CAN0 message control register 3	C0MCTL3	00_{16}
0204_{16}	CAN0 message control register 4	C0MCTL4	00_{16}
0205_{16}	CAN0 message control register 5	C0MCTL5	00_{16}
0206_{16}	CAN0 message control register 6	C0MCTL6	00_{16}
0207_{16}	CAN0 message control register 7	C0MCTL7	00_{16}
0208_{16}	CAN0 message control register 8	C0MCTL8	00_{16}
0209_{16}	CAN0 message control register 9	C0MCTL9	00_{16}
$020A_{16}$	CAN0 message control register 10	C0MCTL10	00_{16}
$020B_{16}$	CAN0 message control register 11	C0MCTL11	00_{16}
$020C_{16}$	CAN0 message control register 12	C0MCTL12	00_{16}
$020D_{16}$	CAN0 message control register 13	C0MCTL13	00_{16}
$020E_{16}$	CAN0 message control register 14	C0MCTL14	00_{16}
$020F_{16}$	CAN0 message control register 15	C0MCTL15	00_{16}
0210_{16} 0211_{16}	CAN0 control register	C0CTLR	$X0000001_2$ $XX0X0000_2$
0212_{16} 0213_{16}	CAN0 status register	C0STR	00_{16} $X0000001_2$
0214_{16} 0215_{16}	CAN0 slot status register	C0SSTR	00_{16} 00_{16}
0216_{16} 0217_{16}	CAN0 interrupt control register	C0ICR	00_{16} 00_{16}
0218_{16} 0219_{16}	CAN0 extended ID register	C0IDR	00_{16} 00_{16}
$021A_{16}$ $021B_{16}$	CAN0 configuration register	C0CONR	XX_{16} XX_{16}
$021C_{16}$	CAN0 receive error count register	C0RECR	00_{16}
$021D_{16}$	CAN0 transmit error count register	C0TECR	00_{16}
$021E_{16}$ $021F_{16}$	CAN0 time stamp register	C0TSR	00_{16} 00_{16}
≈			≈
0242_{16} 0243_{16}	CAN0 acceptance filter support register	C0AFS	XX_{16} XX_{16}
≈			≈
$025A_{16}$	Three-phase protect control register	TPRC	00_{16}
$025B_{16}$			
$025C_{16}$	On-chip oscillator control register	ROCR	00000101_2
$025D_{16}$	Pin assignment control register	PACR	00_{16}
$025E_{16}$	Peripheral clock select register	PCLKR	00000011_2
$025F_{16}$	CAN0 clock select register	CCLKR	00_{16}
≈			≈
$02E0_{16}$	I^2C0 data-shift register	S00	XX_{16}
$02E1_{16}$			
$02E2_{16}$	I^2C0 address register	S0D0	00_{16}
$02E3_{16}$	I^2C0 control register 0	S1D0	00_{16}
$02E4_{16}$	I^2C0 clock control register	S20	00_{16}
$02E5_{16}$	I^2C0 start/stop condition control register	S2D0	00011010_2
$02E6_{16}$	I^2C0 control register 1	S3D0	00110000_2
$02E7_{16}$	I^2C0 control register 2	S4D0	00_{16}
$02E8_{16}$	I^2C0 status register	S10	$0001000X_2$
≈			≈
$02FD_{16}$			
$02FE_{16}$			
$02FF_{16}$			

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.8 SFR Information (8)

Address	Register	Symbol	After reset
0300_{16} 0301_{16}	Time measurement, Pulse generation register 0	G1TM0,G1PO0	XX_{16} XX_{16}
0302_{16} 0303_{16}	Time measurement, Pulse generation register 1	G1TM1,G1PO1	XX_{16} XX_{16}
0304_{16} 0305_{16}	Time measurement, Pulse generation register 2	G1TM2,G1PO2	XX_{16} XX_{16}
0306_{16} 0307_{16}	Time measurement, Pulse generation register 3	G1TM3,G1PO3	XX_{16} XX_{16}
0308_{16} 0309_{16}	Time measurement, Pulse generation register 4	G1TM4,G1PO4	XX_{16} XX_{16}
$030A_{16}$ $030B_{16}$	Time measurement, Pulse generation register 5	G1TM5,G1PO5	XX_{16} XX_{16}
$030C_{16}$ $030D_{16}$	Time measurement, Pulse generation register 6	G1TM6,G1PO6	XX_{16} XX_{16}
$030E_{16}$ $030F_{16}$	Time measurement, Pulse generation register 7	G1TM7,G1PO7	XX_{16} XX_{16}
0310_{16}	Pulse generation control register 0	G1POCR0	$0X00XX00_2$
0311_{16}	Pulse generation control register 1	G1POCR1	$0X00XX00_2$
0312_{16}	Pulse generation control register 2	G1POCR2	$0X00XX00_2$
0313_{16}	Pulse generation control register 3	G1POCR3	$0X00XX00_2$
0314_{16}	Pulse generation control register 4	G1POCR4	$0X00XX00_2$
0315_{16}	Pulse generation control register 5	G1POCR5	$0X00XX00_2$
0316_{16}	Pulse generation control register 6	G1POCR6	$0X00XX00_2$
0317_{16}	Pulse generation control register 7	G1POCR7	$0X00XX00_2$
0318_{16}	Time measurement control register 0	G1TMCR0	00_{16}
0319_{16}	Time measurement control register 1	G1TMCR1	00_{16}
$031A_{16}$	Time measurement control register 2	G1TMCR2	00_{16}
$031B_{16}$	Time measurement control register 3	G1TMCR3	00_{16}
$031C_{16}$	Time measurement control register 4	G1TMCR4	00_{16}
$031D_{16}$	Time measurement control register 5	G1TMCR5	00_{16}
$031E_{16}$	Time measurement control register 6	G1TMCR6	00_{16}
$031F_{16}$	Time measurement control register 7	G1TMCR7	00_{16}
0320_{16} 0321_{16}	Base timer register	G1BT	XX_{16} XX_{16}
0322_{16}	Base timer control register 0	G1BCR0	00_{16}
0323_{16}	Base timer control register 1	G1BCR1	00_{16}
0324_{16}	Time measurement prescale register 6	G1TPR6	00_{16}
0325_{16}	Time measurement prescale register 7	G1TPR7	00_{16}
0326_{16}	Function enable register	G1FE	00_{16}
0327_{16}	Function select register	G1FS	00_{16}
0328_{16} 0329_{16}	Base timer reset register	G1BTRR	XX_{16} XX_{16}
$032A_{16}$	Count source division register	G1DV	00_{16}
$032B_{16}$			
$032C_{16}$			
$032D_{16}$			
$032E_{16}$			
$032F_{16}$			
0330_{16}	Interrupt request register	G1IR	XX_{16}
0331_{16}	Interrupt enable register 0	G1IE0	00_{16}
0332_{16}	Interrupt enable register 1	G1IE1	00_{16}
0333_{16}			
0334_{16}			
0335_{16}			
0336_{16}			
0337_{16}			
0338_{16}			
0339_{16}			
$033A_{16}$			
$033B_{16}$			
$033C_{16}$			
$033D_{16}$			
$033E_{16}$	NMI digital debounce register	NDDR	FF_{16}
$033F_{16}$	Port P17 digital debounce register	P17DDR	FF_{16}

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.9 SFR Information (9)

Address	Register	Symbol	After reset
0340_{16}			
0341_{16}			
0342_{16}	Timer A1-1 register	TA11	XX_{16}
0343_{16}			XX_{16}
0344_{16}	Timer A2-1 register	TA21	XX_{16}
0345_{16}			XX_{16}
0346_{16}	Timer A4-1 register	TA41	XX_{16}
0347_{16}			XX_{16}
0348_{16}	Three phase PWM control register 0	INVC0	00_{16}
0349_{16}	Three phase PWM control register 1	INVC1	00_{16}
$034A_{16}$	Three phase output buffer register 0	IDB0	00_{16}
$034B_{16}$	Three phase output buffer register 1	IDB1	00_{16}
$034C_{16}$	Dead time timer	DTT	XX_{16}
$034D_{16}$	Timer B2 Interrupt occurrence frequency set counter	ICTB2	XX_{16}
$034E_{16}$	Position - data - retain function control register	PDRF	$XXXX0000_2$
$034F_{16}$			
0350_{16}			
0351_{16}			
0352_{16}			
0353_{16}			
0354_{16}			
0355_{16}			
0356_{16}			
0357_{16}			
0358_{16}	Port function control register	PFCR	00111111_2
0359_{16}			
$035A_{16}$			
$035B_{16}$			
$035C_{16}$			
$035D_{16}$			
$035E_{16}$	Interrupt cause select register 2(2)	IFSR2A	$00XXX000_2$
$035F_{16}$	Interrupt cause select register	IFSR	00_{16}
0360_{16}	SI/O3 transmit/receive register	S3TRR	XX_{16}
0361_{16}			
0362_{16}	SI/O3 control register	S3C	01000000_2
0363_{16}	SI/O3 bit rate register	S3BRG	XX_{16}
0364_{16}	SI/O4 transmit/receive register	S4TRR	XX_{16}
0365_{16}			
0366_{16}	SI/O4 control register	S4C	01000000_2
0367_{16}	SI/O4 bit rate register	S4BRG	XX_{16}
0368_{16}			
0369_{16}			
$036A_{16}$			
$036B_{16}$			
$036C_{16}$			
$036D_{16}$			
$036E_{16}$			
$036F_{16}$			
0370_{16}			
0371_{16}			
0372_{16}			
0373_{16}			
0374_{16}	UART2 special mode register 4	U2SMR4	00_{16}
0375_{16}	UART2 special mode register 3	U2SMR3	$000X0X0X_2$
0376_{16}	UART2 special mode register 2	U2SMR2	$X0000000_2$
0377_{16}	UART2 special mode register	U2SMR	$X0000000_2$
0378_{16}	UART2 transmit/receive mode register	U2MR	00_{16}
0379_{16}	UART2 bit rate register	U2BRG	XX_{16}
$037A_{16}$	UART2 transmit buffer register	U2TB	XX_{16}
$037B_{16}$			XX_{16}
$037C_{16}$	UART2 transmit/receive control register 0	U2C0	00001000_2
$037D_{16}$	UART2 transmit/receive control register 1	U2C1	00000010_2
$037E_{16}$	UART2 receive buffer register	U2RB	XX_{16}
$037F_{16}$			XX_{16}

Note 1: The blank areas are reserved and cannot be used by users.
Note 2: Write 0 to the bit 0 after reset.

X : Undefined

Table 4.10 SFR Information (10)

Address	Register	Symbol	After reset
0380_{16}	Count start flag	TABSR	00_{16}
0381_{16}	Clock prescaler reset flag	CPSRF	$0XXXXXXX_2$
0382_{16}	One-shot start flag	ONSF	00_{16}
0383_{16}	Trigger select register	TRGSR	00_{16}
0384_{16}	Up-dowm flag	UDF	00_{16}
0385_{16}			
0386_{16} 0387_{16}	Timer A0 register	TA0	XX_{16} XX_{16}
0388_{16} 0389_{16}	Timer A1 register	TA1	XX_{16} XX_{16}
$038A_{16}$ $038B_{16}$	Timer A2 register	TA2	XX_{16} XX_{16}
$038C_{16}$ $038D_{16}$	Timer A3 register	TA3	XX_{16} XX_{16}
$038E_{16}$ $038F_{16}$	Timer A4 register	TA4	XX_{16} XX_{16}
0390_{16} 0391_{16}	Timer B0 register	TB0	XX_{16} XX_{16}
0392_{16} 0393_{16}	Timer B1 register	TB1	XX_{16} XX_{16}
0394_{16} 0395_{16}	Timer B2 register	TB2	XX_{16} XX_{16}
0396_{16}	Timer A0 mode register	TA0MR	00_{16}
0397_{16}	Timer A1 mode register	TA1MR	00_{16}
0398_{16}	Timer A2 mode register	TA2MR	00_{16}
0399_{16}	Timer A3 mode register	TA3MR	00_{16}
$039A_{16}$	Timer A4 mode register	TA4MR	00_{16}
$039B_{16}$	Timer B0 mode register	TB0MR	$00XX0000_2$
$039C_{16}$	Timer B1 mode register	TB1MR	$00XX0000_2$
$039D_{16}$	Timer B2 mode register	TB2MR	$00XX0000_2$
$039E_{16}$	Timer B2 special mode register	TB2SC	$X0000000_2$
$039F_{16}$			
$03A0_{16}$	UART0 transmit/receive mode register	U0MR	00_{16}
$03A1_{16}$	UART0 bit rate register	U0BRG	XX_{16}
$03A2_{16}$ $03A3_{16}$	UART0 transmit buffer register	U0TB	XX_{16} XX_{16}
$03A4_{16}$	UART0 transmit/receive control register 0	U0C0	00001000_2
$03A5_{16}$	UART0 transmit/receive control register 1	U0C1	00000010_2
$03A6_{16}$ $03A7_{16}$	UART0 receive buffer register	U0RB	XX_{16} XX_{16}
$03A8_{16}$	UART1 transmit/receive mode register	U1MR	00_{16}
$03A9_{16}$	UART1 bit rate register	U1BRG	XX_{16}
$03AA_{16}$ $03AB_{16}$	UART1 transmit buffer register	U1TB	XX_{16} XX_{16}
$03AC_{16}$	UART1 transmit/receive control register 0	U1C0	00001000_2
$03AD_{16}$	UART1 transmit/receive control register 1	U1C1	00000010_2
$03AE_{16}$ $03AF_{16}$	UART1 receive buffer register	U1RB	XX_{16} XX_{16}
$03B0_{16}$	UART transmit/receive control register 2	UCON	$X0000000_2$
$03B1_{16}$			
$03B2_{16}$			
$03B3_{16}$			
$03B4_{16}$ $03B5_{16}$	CRC snoop address register	CRCSAR	XX_{16} $00XXXXXX_2$
$03B6_{16}$	CRC mode register	CRCMR	$0XXXXXX0_2$
$03B7_{16}$			
$03B8_{16}$	DMA0 request cause select register	DM0SL	00_{16}
$03B9_{16}$			
$03BA_{16}$	DMA1 request cause select register	DM1SL	00_{16}
$03BB_{16}$			
$03BC_{16}$ $03BD_{16}$	CRC data register	CRCD	XX_{16} XX_{16}
$03BE_{16}$	CRC input register	CRCIN	XX_{16}
$03BF_{16}$			

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

Table 4.11 SFR Information (11)

Address	Register	Symbol	After reset
$03C0_{16}$ $03C1_{16}$	A/D register 0	AD0	XX_{16} XX_{16}
$03C2_{16}$ $03C3_{16}$	A/D register 1	AD1	XX_{16} XX_{16}
$03C4_{16}$ $03C5_{16}$	A/D register 2	AD2	XX_{16} XX_{16}
$03C6_{16}$ $03C7_{16}$	A/D register 3	AD3	XX_{16} XX_{16}
$03C8_{16}$ $03C9_{16}$	A/D register 4	AD4	XX_{16} XX_{16}
$03CA_{16}$ $03CB_{16}$	A/D register 5	AD5	XX_{16} XX_{16}
$03CC_{16}$ $03CD_{16}$	A/D register 6	AD6	XX_{16} XX_{16}
$03CE_{16}$ $03CF_{16}$	A/D register 7	AD7	XX_{16} XX_{16}
$03D0_{16}$			
$03D1_{16}$			
$03D2_{16}$	A/D trigger control register	ADTRGCON	$XXXX0000_2$
$03D3_{16}$	A/D status register 0	ADSTAT0	$00000X00_2$
$03D4_{16}$	A/D control register 2	ADCON2	00_{16}
$03D5_{16}$			
$03D6_{16}$	A/D control register 0	ADCON0	$00000XXX_2$
$03D7_{16}$	A/D control register 1	ADCON1	00_{16}
$03D8_{16}$			
$03D9_{16}$			
$03DA_{16}$			
$03DB_{16}$			
$03DC_{16}$			
$03DD_{16}$			
$03DE_{16}$			
$03DF_{16}$			
$03E0_{16}$	Port P0 register	P0	XX_{16}
$03E1_{16}$	Port P1 register	P1	XX_{16}
$03E2_{16}$	Port P0 direction register	PD0	00_{16}
$03E3_{16}$	Port P1 direction register	PD1	00_{16}
$03E4_{16}$	Port P2 register	P2	XX_{16}
$03E5_{16}$	Port P3 register	P3	XX_{16}
$03E6_{16}$	Port P2 direction register	PD2	00_{16}
$03E7_{16}$	Port P3 direction register	PD3	00_{16}
$03E8_{16}$			
$03E9_{16}$			
$03EA_{16}$			
$03EB_{16}$			
$03EC_{16}$	Port P6 register	P6	XX_{16}
$03ED_{16}$	Port P7 register	P7	XX_{16}
$03EE_{16}$	Port P6 direction register	PD6	00_{16}
$03EF_{16}$	Port P7 direction register	PD7	00_{16}
$03F0_{16}$	Port P8 register	P8	XX_{16}
$03F1_{16}$	Port P9 register	P9	XX_{16}
$03F2_{16}$	Port P8 direction register	PD8	00_{16}
$03F3_{16}$	Port P9 direction register	PD9	$000X0000_2$
$03F4_{16}$	Port P10 register	P10	XX_{16}
$03F5_{16}$			
$03F6_{16}$	Port P10 direction register	PD10	00_{16}
$03F7_{16}$			
$03F8_{16}$			
$03F9_{16}$			
$03FA_{16}$			
$03FB_{16}$			
$03FC_{16}$	Pull-up control register 0	PUR0	00_{16}
$03FD_{16}$	Pull-up control register 1	PUR1	00_{16}
$03FE_{16}$	Pull-up control register 2	PUR2	00_{16}
$03FF_{16}$	Port control register	PCR	00_{16}

Note 1: The blank areas are reserved and cannot be used by users.

X : Undefined

5. Resets

Hardware reset 1, brown-out detection reset (hardware reset 2), software reset, watchdog timer reset, and oscillation stop detection reset are implemented to reset the MCU.

5.1 Hardware Reset

Hardware reset 1 and brown-out detection reset are available as the hardware reset.

5.1.1 Hardware Reset 1

Pins, CPU, and SFRs are reset by using the $\overline{\text{RESET}}$ pin. When a low-level ("L") signal is applied to the $\overline{\text{RESET}}$ pin while the supply voltage meets the recommended operating condition, pins, CPU, and SFRs are reset (see **Table 5.1** Pin Status When $\overline{\text{RESET}}$ Pin Level is "L"). The oscillation circuit is also reset and the on-chip oscillator starts oscillating as the CPU clock. CPU and SFRs re reset when the signal applied to the $\overline{\text{RESET}}$ pin changes from "L" to high ("H"). The MCU executes a program beginning with the address indicated by the reset vector. The internal RAM is not reset. When an "L" signal is applied to the $\overline{\text{RESET}}$ pin while writing data to the internal RAM, the content of internal RAM is undefined.
Figure 5.1 shows an example of the reset circuit. **Figure 5.2** shows a reset sequence. **Table 5.1** shows status of the other pins while the $\overline{\text{RESET}}$ pin is held "L". **Figure 5.3** shows CPU register states after reset. Refer to **4. Special Function Register (SFR)** about SFR states after reset.

1. Reset on a stable supply voltage
(1) Apply an "L" signal to the $\overline{\text{RESET}}$ pin
(2) Wait *td(ROC)* or more
(3) Apply an "H" signal to the $\overline{\text{RESET}}$ pin

2. Power-on reset
(1) Apply an "L" signal to the $\overline{\text{RESET}}$ pin
(2) Increase the supply voltage until it meets the the recommended performance condition
(3) Wait for *td(P-R)* or more to allow the internal power supply to stabilize
(4) Wait *td(ROC)* or more
(5) Apply an "H" signal to the $\overline{\text{RESET}}$ pin

5.1.2 Brown-Out Detection Reset (Hardware Reset 2)

Note

Brown-out detection reset in the M16C/29 Group, T-ver. and V-ver. cannot be used.

Pins, CPU, and SFR are reset by using the on-chip voltage detection circuit, which monitors the voltage applied to VCC pin.
When the VC26 bit in the VCR2 register is set to 1 (reset level detection circuit enabled), pins, CPU, and SFR are reset as soon as the voltage applied to the VCC pin drops to Vdet3 or below.
Then, pins, CPU, and SFR are reset as soon as the voltage applied to the VCC pin reaches Vdet3r or above. The MCU executes the program in an address determined by the reset vector.
The MCU executes the program after detecting Vdet3r and waiting *td(S-R)* ms. The same pins and registers are reset by the hardware reset 1 and brown-out detection reset, and are also placed in the same reset state.
The MCU cannot exit stop mode by brown-out detection reset.

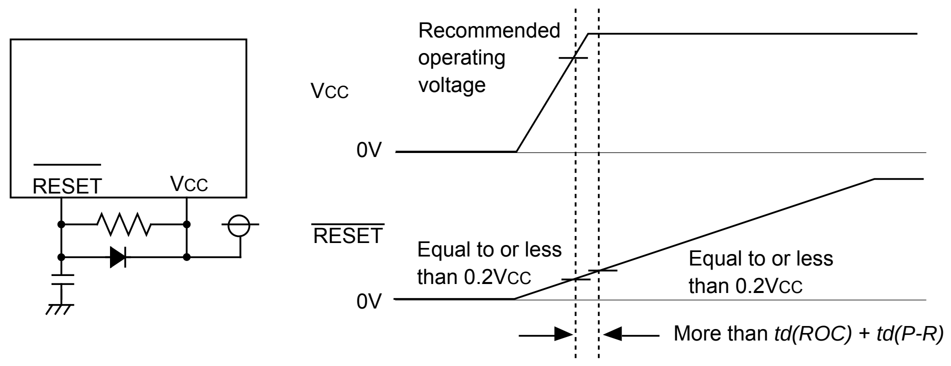


Figure 5.1 Example Reset Circuit

5.2 Software Reset

The MCU resets its pins, CPU, and SFRs when the PM03 bit in the PM0 register is set to 1 (reset) and the MCU executes a program in an address indicated by the reset vector. Then the on-chip oscillator is selected as the CPU clock.

The software reset does not reset some portions of the SFRs. Refer to **4. Special Function Registers (SFRs)** for details.

5.3 Watchdog Timer Reset

The MCU resets its pins, CPU, and SFRs when the PM12 bit in the PM1 register is set to 1 (watchdog timer reset) and the watchdog timer underflows. The MCU executes a program in an address indicated by the reset vector. Then the on-chip oscillator is selected as the CPU clock.

The watchdog timer reset does not reset some portions of the SFRs. Refer to **4. Special Function Registers (SFRs)** for details.

5.4 Oscillation Stop Detection Reset

The MCU resets its pins, CPU, and SFRs and stops if the main clock stop is detected when the CM20 bit in the CM2 register is set to 1 (oscillation stop, re-oscillation detection function enabled) and the CM27 bit in the CM2 register is 0 (reset at oscillation stop detection). Refer to the section **7.8 oscillation stop, re-oscillation detection function** for details.

The oscillation stop detection reset does not reset some portions of the SFRs. Refer to **4. Special Function Registers (SFRs)**.

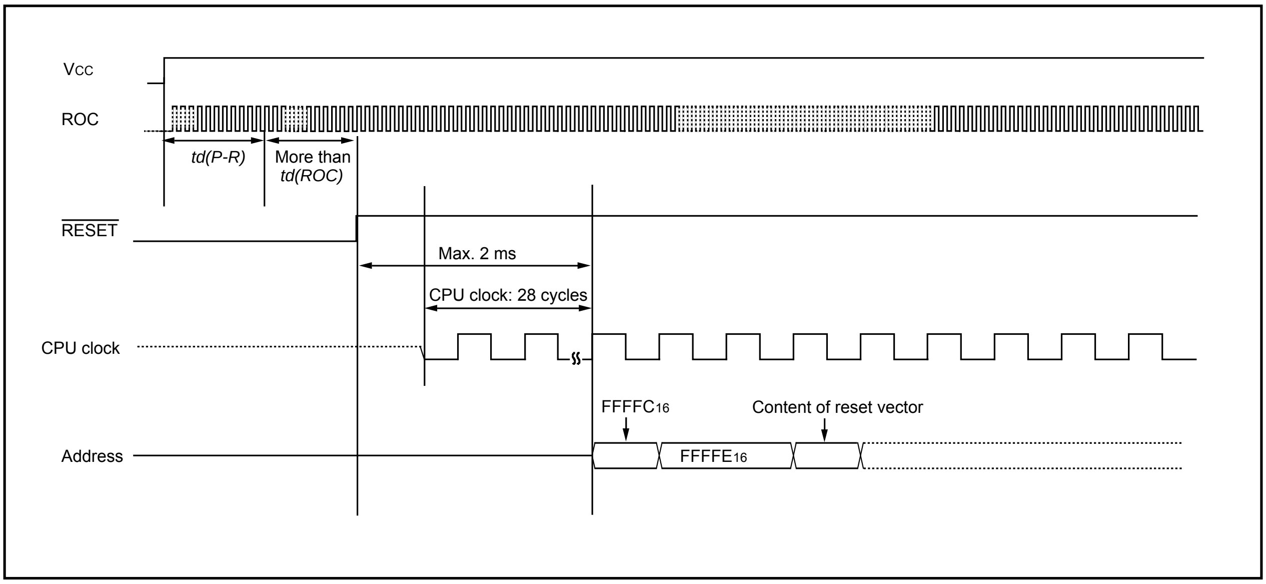


Figure 5.2 Reset Sequence

Table 5.1 Pin Status When RESET Pin Level is "L"

Pin name	Status
P0 to P3, P6 to P10	Input port (high impedance)

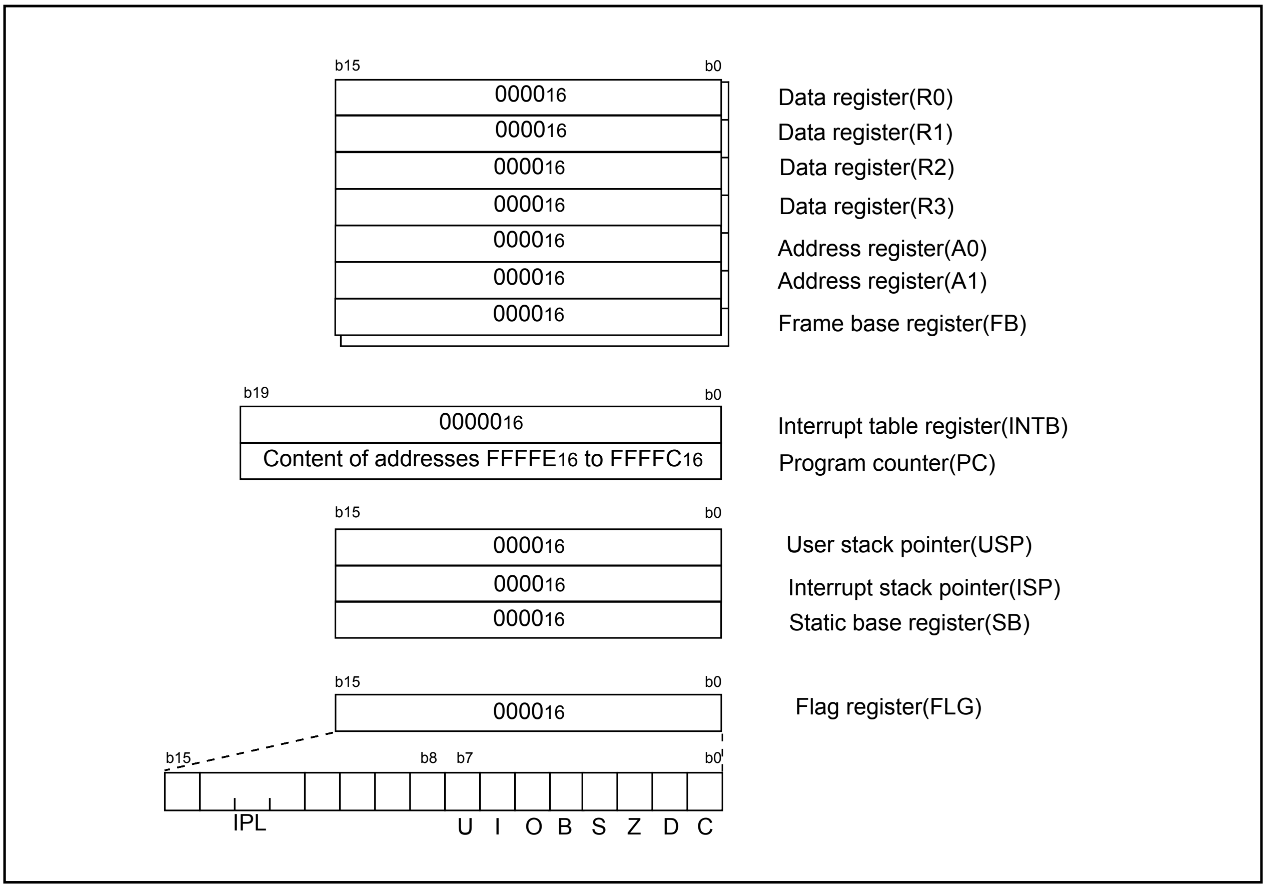


Figure 5.3 CPU Register Status After Reset

5.5 Voltage Detection Circuit

Note

VCC = 5 V is assumed in **5.5 Voltage Detection Circuit**.

Voltage detection circuit in the M16C/29 Group, T-ver. and V-ver. cannot be used.

The voltage detection circuit has the reset level detection circuit and the low voltage detection circuit. The reset level detection circuit monitors the voltage applied to the VCC pin. The MCU is reset if the reset level detection circuit detects VCC is Vdet3 or below. Use bits VC27 and VC26 in the VCR2 register to determine whether the individual circuit is enabled.

Use the reset level detection circuit for brown-out detection reset.

The low voltage detection circuit also monitors the voltage applied to the VCC pin. The low voltage detection circuit use the VC13 bit in the VCR1 register to detect VCC is above or below Vdet4. The low voltage detection interrupt can be used in the voltage detection circuit.

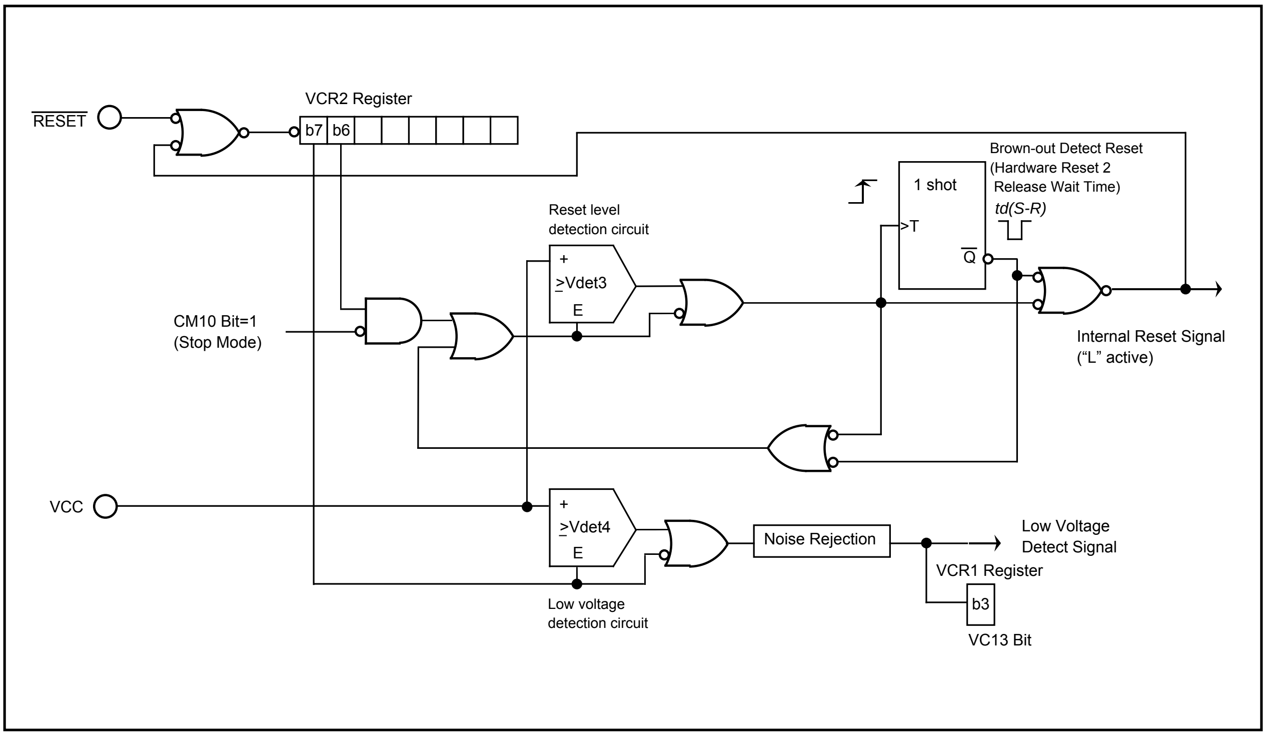


Figure 5.4 Voltage Detection Circuit Block

Voltage Detection Register 1

b7	b6	b5	b4	b3	b2	b1	b0
0	0	0	0		0	0	0

Symbol VCR1 Address 0019_{16} After Reset (2) 00001000_2

Bit Symbol	Bit Name	Function	RW
(b2-b0)	Reserved bit	Set to 0	RW
VC13	Low voltage monitor flag (1)	0:VCC < Vdet4 1:VCC ≥ Vdet4	RO
(b7-b4)	Reserved bit	Set to 0	RW

NOTES:
1. The VC13 bit is useful when the VC27 bit of VCR2 register is set to 1 (low voltage detection circuit enable). The VC13 bit is always 1 (VCC≥ Vdet4) when the VC27 bit in the VCR2 register is set to 0 (low voltage detection circuit disable).
2. This register does not change at software reset, watchdog timer reset and oscillation stop detection reset.

Voltage Detection Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
		0	0	0	0	0	0

Symbol VCR2 Address $001A_{16}$ After Reset (5) 00_{16}

Bit Symbol	Bit Name	Function	RW
(b5-b0)	Reserved bit	Set to 0	RW
VC26	Reset level monitor bit (2, 3, 6)	0: Disable reset level detection circuit 1: Enable reset level detection circuit	RW
VC27	Low voltage monitor bit (4, 6)	0: Disable low voltage detection circuit 1: Enable low voltage detection circuit	RW

NOTES:
1. Write to this register after setting the PRC3 bit in the PRCR register to 1 (write enable).
2. Set the VC26 bit to 1 to use brown-out reset.
3. VC26 bit is disabled in stop mode. (The MCU is not reset even if the voltage input to Vcc pin becomes lower than Vdet3.)
4. When the VC13 bit in the VCR1 register and D42 bit in the D4INT register are used or the D40 bit is set to 1 (low voltage detection interrupt enable), set the VC27 bit to 1.
5. This register does not change at software reset, watchdog timer reset and oscillation stop detection reset.
6. The detection circuit does not start operation until td(E-A) elapses after the VC26 bit or VC27 bit is set to 1.

Figure 5.5 VCR1 Register and VCR2 Register

Low Voltage Detection Interrupt Register [1]

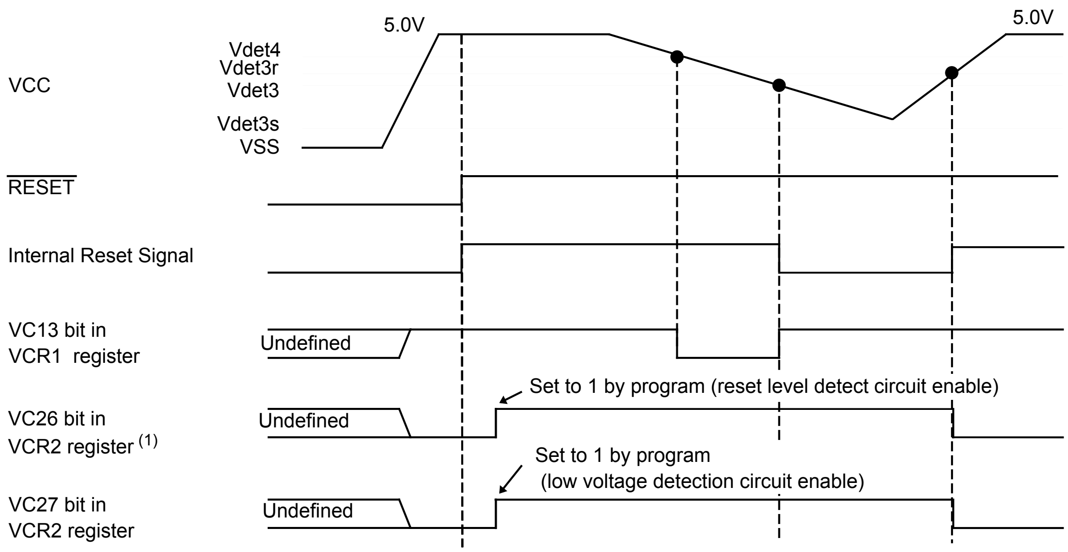
b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
D4INT	$001F_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
D40	Low voltage detection interrupt enable bit [5]	0 : Disable 1 : Enable	RW
D41	STOP mode deactivation control bit [4]	0: Disable (do not use the low voltage detection interrupt to exit stop mode) 1: Enable (use the low voltage detection interrupt to exit stop mode)	RW
D42	Voltage change detection flag [2]	0: Not detected 1: Vdet4 passing detection	RW [3]
D43	WDT overflow detect flag	0: Not detected 1: Detected	RW [3]
DF0	Sampling clock select bit	b5b4 00 : CPU clock divided by 8 01 : CPU clock divided by 16 10 : CPU clock divided by 32 11 : CPU clock divided by 64	RW
DF1			RW
(b7-b6)	Nothing is assigned. If necessary set to 0. When read, the content is 0		—

NOTES:
1. Write to this register after setting the PRC3 bit in the PRCR register to 1 (write enable).
2. Useful when the VC27 bit in the VCR2 register is set to 1 (low voltage detection circuit enabled). If the VC27 bit is set to 0 (low voltage detection circuit disable), the D42 bit is set to 0 (Not detect).
3. This bit is set to 0 by writing a 0 in a program. (Writing 1 has no effect.)
4. If the low voltage detection interrupt needs to be used to get out of stop mode again after once used for that purpose, reset the D41 bit by writing a 0 and then a 1.
5. The D40 bit is effective when the VC27 bit in the VCR2 register is set to 1. To set the D40 bit to 1, follow the procedure described below.
   (1) Set the VC27 bit to 1.
   (2) Wait for td(E-A) until the detection circuit is actuated.
   (3) Wait for the sampling time (refer to **Table 5.3 Sampling Clock Periods**).
   (4) Set the D40 bit to 1.

Figure 5.6 D4INT Register



NOTES :
1. VC26 bit is invalid in stop mode. (the MCU is not reset even if input voltage of VCC pin becomes lower than Vdet3).

Figure 5.7 Typical Operation of Brown-Out Detection Reset (Hardware Reset 2)

5.5.1 Low Voltage Detection Interrupt

If the D40 bit in the D4INT register is set to 1 (low voltge detection interrupt enabled), a low voltage detection interrupt request is generated when voltage applied to the VCC pin is above or below Vdet4. The low voltage detection interrupt shares the same interrupt vector with watchdog timer interrupt and oscillation stop, re-oscillation detection interrupt.

Set the D41 bit in the D4INT register to 1 (enabled) to use the low voltage detection interrupt to exit stop mode, set the D41 bit in the D4INT register to 1 (enable).

The D42 bit in the D4INT register is set to 1 (above or below Vdet4 detected) as soon as voltage applied to the VCC pin goes above or below Vdet4 due to the voltage change. When the D42 bit setting changes 0 to 1, a low voltage detection interrupt is generated. Set the D42 bit to 0 (not detected) by program. However, when the D41 bit is set to 1 and the MCU is in stop mode, a low voltage detection interrupt request is generated, regardless of the D42 bit setting, if voltage applies to the VCC pin is detected to rise above or drop below Vdet4. The MCU then exits stop mode.

Table 5.2 shows how a low voltage detection interrupt request is generated.

Bits DF1 and DF0 in the D4INT register determine sampling period that detects voltage applied to the VCC pin rises above or drops below Vdet4. **Table 5.3** shows sampling periods.

Table 5.2 Voltage Detection Interrupt Request Generation Conditions

<table>
<tr><th>Operation Mode</th><th>VC27 bit</th><th>D40 bit</th><th>D41 bit</th><th>D42 bit</th><th>CM02 bit</th><th>VC13 bit</th></tr>
<tr><td rowspan="2">Normal operation mode(1)</td><td rowspan="6">1</td><td rowspan="6">1</td><td rowspan="2">—</td><td rowspan="2">0 to 1</td><td rowspan="2">—</td><td>0 to 1 (3)</td></tr>
<tr><td>1 to 0 (3)</td></tr>
<tr><td rowspan="3">Wait mode (2)</td><td rowspan="3">—</td><td rowspan="2">0 to 1</td><td rowspan="2">0</td><td>0 to 1 (3)</td></tr>
<tr><td>1 to 0 (3)</td></tr>
<tr><td>—</td><td>1</td><td>0 to 1</td></tr>
<tr><td>Stop mode (2)</td><td>1</td><td>—</td><td>0 to 1</td></tr>
</table>

– : 0 or 1

NOTES:
1. The status except the wait mode and stop mode is handled as the normal mode. (Refer to **7. Clock generating circuit**)
2. Refer to **5.5.2 Limitations on stop mode** and **5.5.3 Limitations on wait mode**.
3. An interrupt request for voltage reduction is generated a sampling time after the value of the VC13 bit has changed. Refer to the **Figure 5.9** for details.

Table 5.3 Sampling Clock Periods

CPU clock (MHz)	Sampling clock (μs)			
	DF1 to DF0=00 (CPU clock divided by 8)	DF1 to DF0=01 (CPU clock divided by 16)	DF1 to DF0=10 (CPU clock divided by 32)	DF1 to DF0=11 (CPU clock divided by 64)
16	3.0	6.0	12.0	24.0

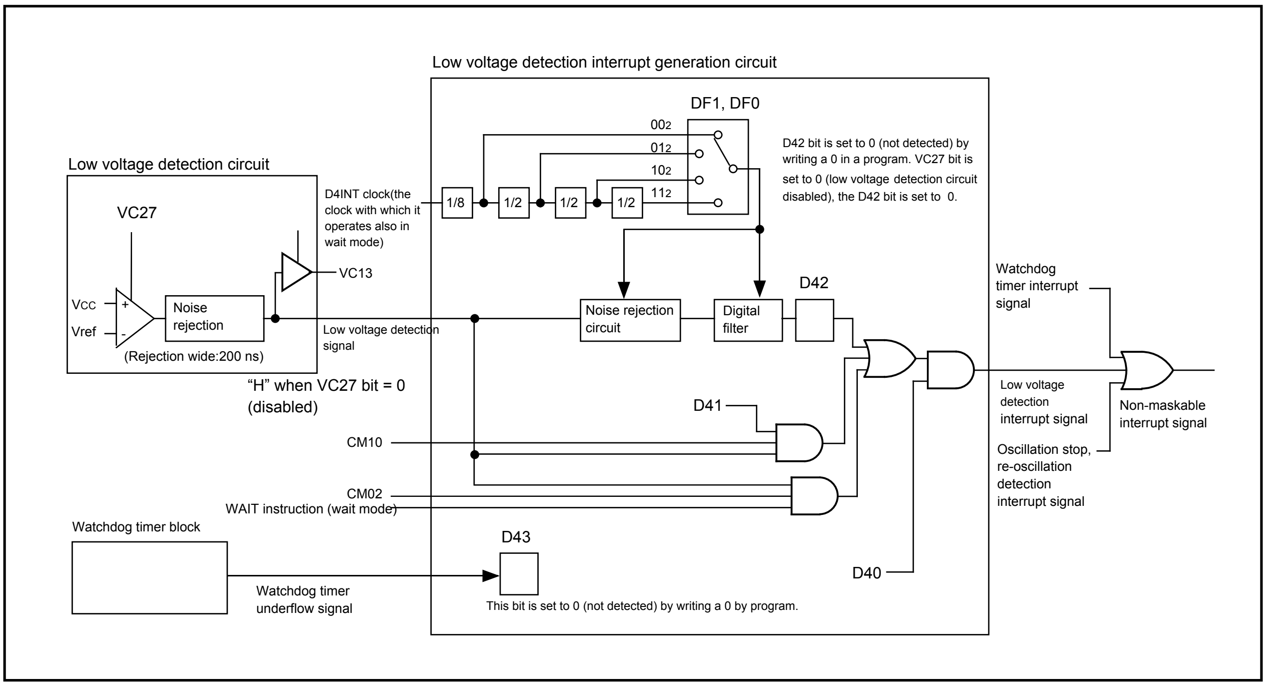
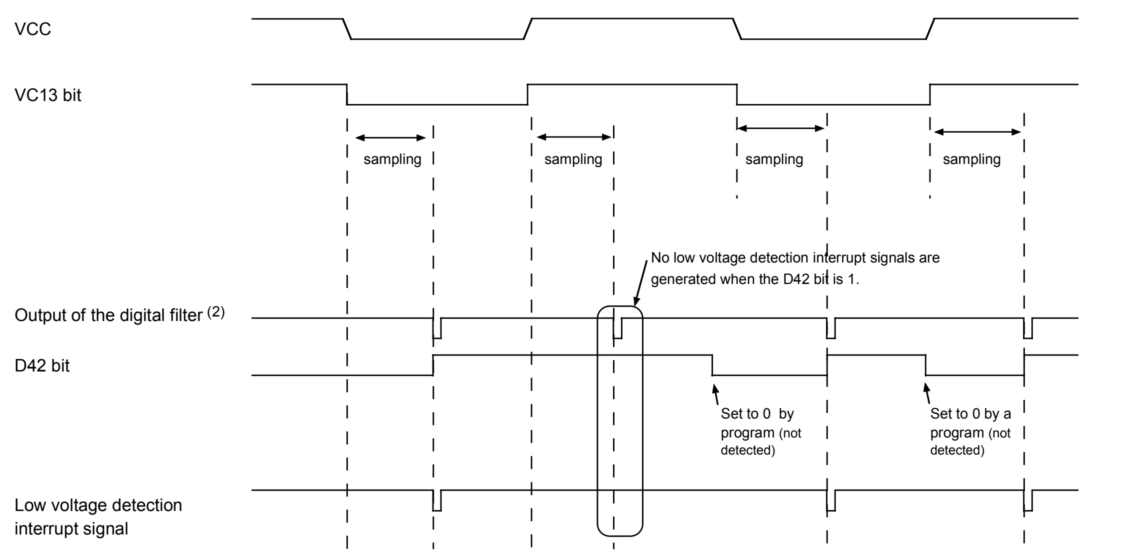


Figure 5.8 Low Voltage Detection Interrupt Generation Block



NOTES:
1. D40 bit in the D4INT register is set to 1 (low voltage detection interrupt enabled).
2. Output of the digital filter shown in **Figure 5.8**.

Figure 5.9 Low voltage Detection Interrupt Generation Circuit Operation Example

5.5.2. Limitations on Stop Mode

When all the conditions below are met, the low voltage detection interrupt is generated and the MCU exits stop mode as soon as the CM10 bit in the CM1 register is set to 1 (all clocks stopped).

- the VC27 bit in the VCR2 register is set to 1 (low voltage detection circuit enabled)
- the D40 bit in the D4INT register is set to 1 (low voltage detection interrupt enabled)
- the D41 bit in the D4INT register is set to 1 (low voltage detection interrupt is used to exit stop mode)
- the voltage applied to the VCC pin is higher than Vdet4 (the VC13 bit in the VCR1 register is 1)

Set the CM10 bit to 1 when the VC13 bit is set to set to 0 (VCC < Vdet4), if the MCU is configured to enter stop mode when voltage applied to the VCC pin drops Vdet4 or below and to exit stop mode when the voltage applied rises to Vdet4 or above.

5.5.3. Limitations on WAIT Instruction

When all the conditions below are met, the low voltage detection interrupt is generated and the MCU exits wait mode as soon as WAIT instruction is executed.

- the CM02 bit in the CM0 register is set to 1 (stop peripheral function clock)
- the VC27 bit in the VCR2 register is set to 1 (low voltage detection circuit enabled)
- the D40 bit in the D4INT register is set to 1 (low voltage detection interrupt enabled)
- the D41 bit in the D4INT register is set to 1 (low voltage detection interrupt is used to exit wait mode)
- the voltage applied to the VCC pin is higher than Vdet4 (the VC13 bit in the VCR1 register is 1)

Execute the WAIT instruction when the VC13 bit is set to set to 0 (VCC < Vdet4), if the MCU is configured to enter wait mode when voltage applied to the VCC pin drops Vdet4 or below and to exit wait mode when the voltage applied rises to Vdet4 or above.

6. Processor Mode

The MCU supports single-chip mode only. **Figures 6.1 and 6.2** show the associated registers.

Processor Mode Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
0	0	0	0		0	0	0

Symbol: PM0 Address: 0004_{16} After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
(b2-b0)	Reserved bit	Set to 0	RW
PM03	Software reset bit	The MCU is reset when this bit is set to 1. When read, its content is 0.	RW
(b7-b4)	Reserved bit	Set to 0	RW

NOTES:
1. Set the PM0 register after the PRC1 bit in the PRCR register is set to 1 (write enable).

Processor Mode Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
	0	0	0	1		0	

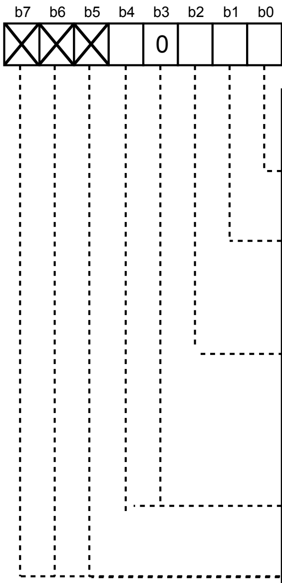
Symbol: PM1 Address: 0005_{16} After Reset: 00001000_2

Bit Symbol	Bit Name	Function	RW
PM10	Flash data block access bit (2)	0: Disabled 1: Enabled (3)	RW
(b1)	Reserved bit	Set to 0	RW
PM12	Watchdog timer function select bit	0 : Watchdog timer interrupt 1 : Watchdog timer reset (4)	RW
(b3)	Reserved bit	Set to 1	RW
(b6-b4)	Reserved bit	Set to 0	RW
PM17	Wait bit (5)	0 : No wait state 1 : Wait state (1 wait)	RW

NOTES:
1. Rewrite the PM1 register after the PRC1 bit in the PRCR register is set to 1 (write enable).
2. To access the two 2K-byte data spaces in data block A and data block B, set the PM10 bit to 1. The PM10 bit is not available in mask version.
3. When the FMR01 bit in the FMR0 register is set to 1 (enables CPU rewrite mode), the PM10 bit is automatically set to 1.
4. Set the PM12 bit to 1 by program. (Writing 0 by program has no effect)
5. When the PM17 bit is set to 1 (wait state), one wait is inserted when accessing the internal RAM or the internal ROM.

Figure 6.1 PM0 Register and PM1 Register

Processeor Mode Register 2 (1)



Symbol PM2 | Address $001E_{16}$ | After Reset $XXX00000_2$

Bit Symbol	Bit Name	Function	RW
PM20	Specifying wait when accessing SFR(2)	0: 2 waits 1: 1 wait	RW
PM21	System clock protective bit(3,4)	0: Clock is protected by PRCR register 1: Clock modification disabled	RW
PM22	WDT count source protective bit(3,5)	0: CPU clock is used for the watchdog timer count source 1: On-chip oscillator clock is used for the watchdog timer count source	RW
— (b3)	Reserved bit	Set to 0	RW
PM24	$P8_5$/$\overline{NMI}$ configuration bit(6,7)	0: $P8_5$ function ($\overline{NMI}$ disabled) 1: $\overline{NMI}$ function	RW
— (b7-b5)	Nothing is assigned. When write, set to 0. When read, thecontent is undefined		—

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enable).
2. The PM20 bit becomes effective when PLC07 bit in the PLC0 register is set to 1 (PLL on). Change the PM20 bit when the PLC07 bit is set to 0 (PLL off). Set the PM20 bit to 0 (2 waits) when PLL clock > 16MHz.
3. Once this bit is set to 1, it cannot be cleared to 0 by program.
4. Writting to the following bits has no effect when the PM21 bit is set to 1:
   - CM02 bit in the CM0 register
   - CM05 bit in the CM0 register (main clock is not halted)
   - CM07 bit in the CM0 register (CPU clock source does not change)
   - CM10 bit in the CM1 register (stop mode is not entered)
   - CM11 bit in the CM1 register (CPU clock source does not change)
   - CM20 bit in the CM2 register (oscillation stop, re-oscillation detection function settings do not change)
   - All bits in the PLC0 register (PLL frequency synthesizer setting do not change)

   Do not execute WAIT instruction when the PM21 bit is set to 1.
5. Setting the PM22 bit to 1 results in the following conditions:
   - The on-chip oscillator continues oscillating even if the CM21 bit in the CM2 register is set to "0" (main clock or PLL clock) (system clock of count source selected by the CM21 bit is valid)
   - The on-chip oscillator starts oscillating, and the on-chip oscillator clock becomes the watchdog timer count source.
   - The CM10 bit in the CM1 register cannnot be written. (Writing 1 has no effect, stop mode is not entered.)
   - The watchdog timer does not stop in wait mode.
6. For $\overline{NMI}$ function, the PM24 bit must be set to 1($\overline{NMI}$ function). Once this bit is set to 1, it cannot be set to 0 by program.
7. $\overline{SD}$ input is valid regardless of the PM24 setting.

Figure 6.2 PM2 Register

The internal bus consists of CPU bus, memory bus, and peripheral bus. Bus Interface Unit (BIU) is used to interfere with CPU, ROM/RAM, and perpheral functions by controling CPU bus, memory bus, and peripheral bus. **Figure 6.3** shows the block diagram of the internal bus.

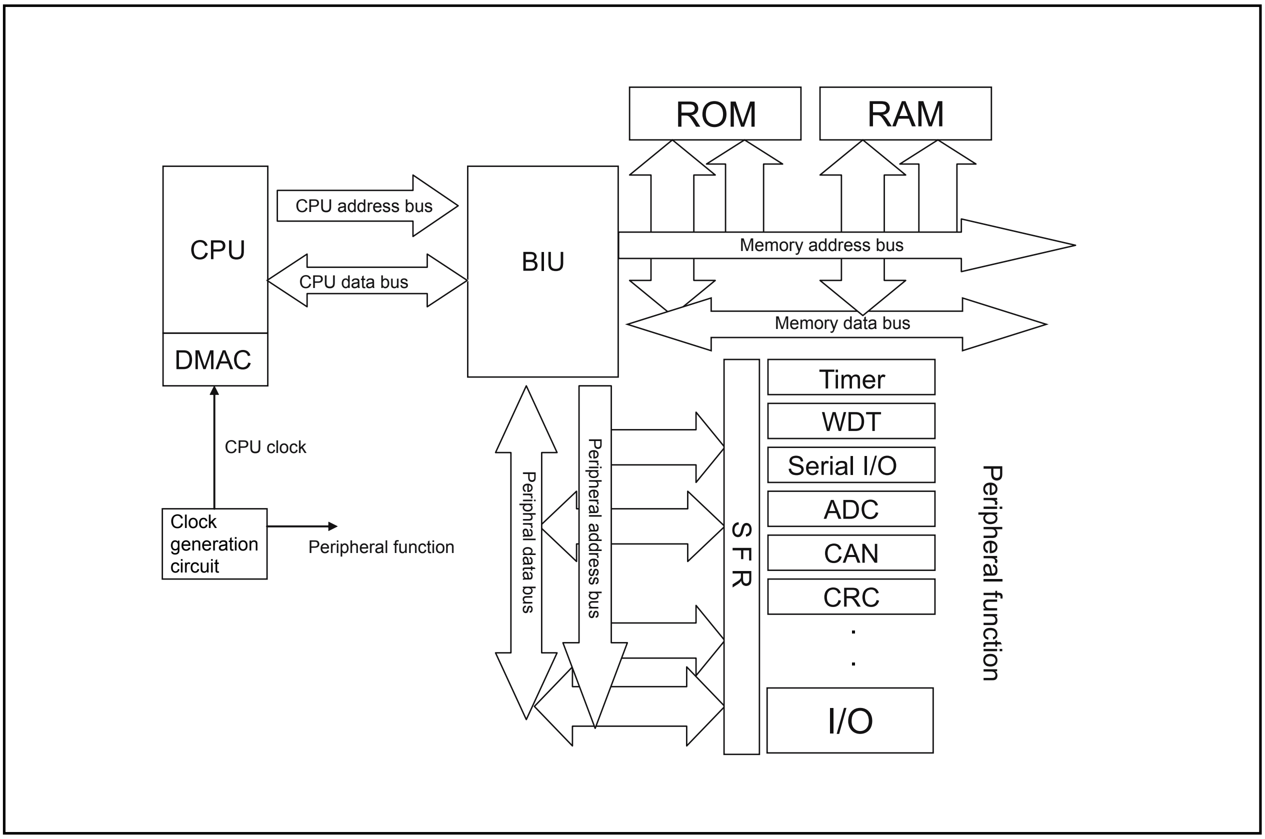


Figure 6.3 Bus Block Diagram

The number of bus cycle varies by the internal bus. Table 6.1 lists the accessible area and bus cycle.

Table 6.1 Accessible Area and Bus Cycle

	Accessible Area	Bus Cycle
SFR	PM20 bit = 0 (2 waits)	3 CPU clock cycles
	PM20 bit = 1 (1 wait)	2 CPU clock cycles
ROM/RAM	PM17 bit = 0 (no wait)	1 CPU clock cycle
	PM17 bit = 1 (1 wait)	2 CPU clock cycles

7. Clock Generation Circuit

The clock generation circuit contains four oscillator circuits as follows:

(1) Main clock oscillation circuit
(2) Sub clock oscillation circuit
(3) Variable on-chip oscillators
(4) PLL frequency synthesizer

Table 7.1 lists the specifications of the clock generation circuit. **Figure 7.1** shows the clock generation circuit. **Figures 7.2** to **7.7** show clock-associated registers.

Table 7.1 Clock Generation Circuit Specifications

Item	Main Clock Oscillation Circuit	Sub Clock Oscillation Circuit	Variable On-chip Oscillator	PLL Frequency Synthesizer
Use of clock	- CPU clock source - Peripheral function clock source	- CPU clock source - Timer A, B's clock source	- CPU clock source - Peripheral function clock source - CPU and peripheral function clock sources when the main clock stops oscillating	- CPU clock source - Peripheral function clock source
Clock frequency	0 to 20 MHz	32.768 kHz	Selectable source frequency: $f_{1(ROC)}$, $f_{2(ROC)}$, $f_{3(ROC)}$ Selectable divider: by 2, by 4, by 8	10 to 20 MHz
Usable oscillator	- Ceramic oscillator - Crystal oscillator	- Crystal oscillator	———	———
Pins to connect oscillator	XIN, XOUT	XCIN, XCOUT	———	———
Oscillation stop, restart function	Available	Available	Available	Available
Oscillator status after reset	Oscillating	Stopped	Oscillating (CPU clock source)	Stopped
Other	Externally derived clock can be input		———	———

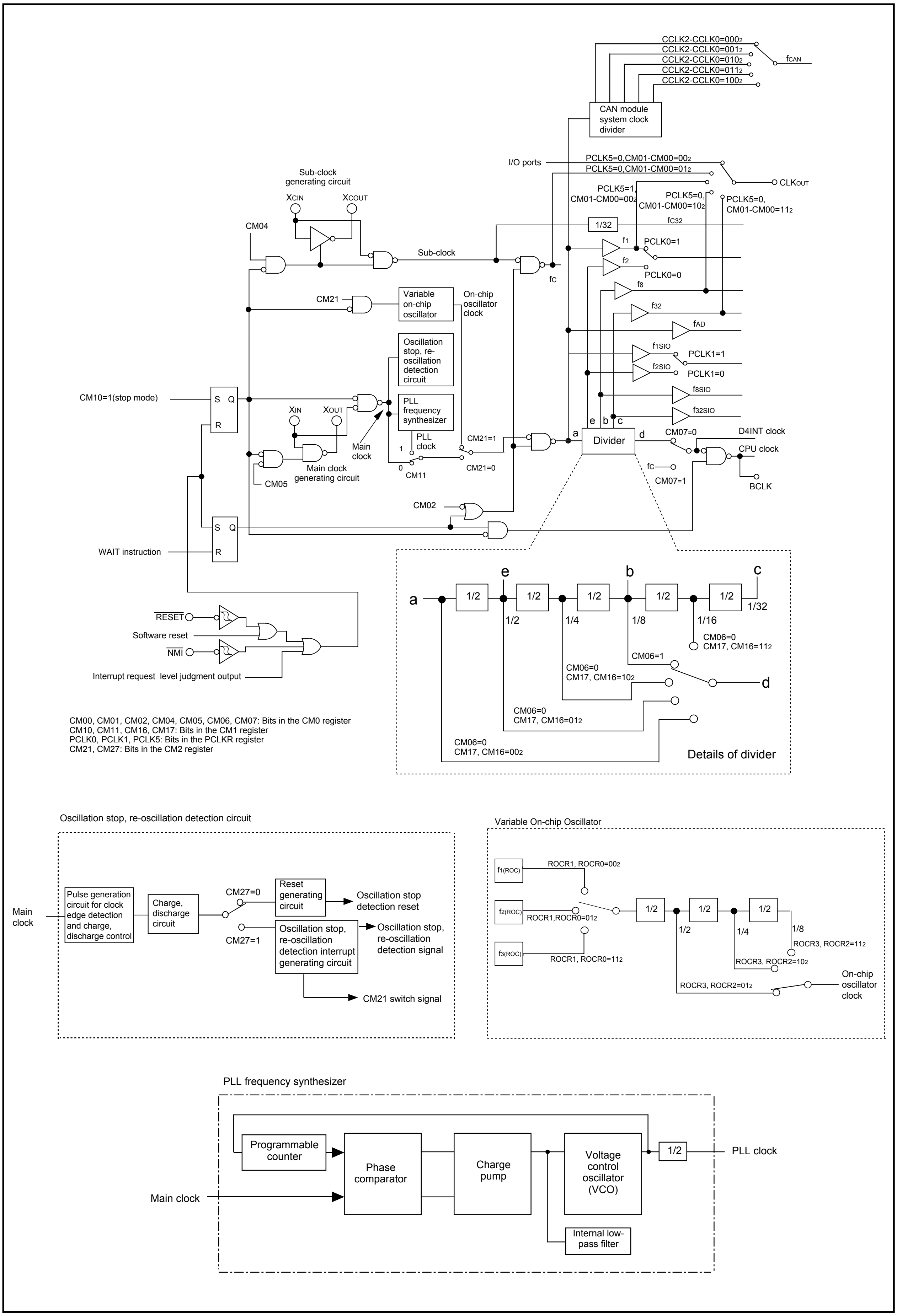


Figure 7.1 Clock Generation Circuit

System Clock Control Register 0 (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
CM0	0006_{16}	01001000_2

Bit Symbol	Bit Name	Function	RW
CM00	Clock output function select bit	See **Table 7.3**	RW
CM01			RW
CM02	Wait Mode peripheral function clock stop bit (10)	0: Do not stop peripheral function clock in wait mode 1: Stop peripheral function clock in wait mode (8)	RW
CM03	XCIN-XCOUT drive capacity select bit (2)	0: LOW 1: HIGH	RW
CM04	Port XC select bit (2)	0: I/O port P8 6, P87 1: XCIN-XCOUT generation function(9)	RW
CM05	Main clock stop bit (3, 10, 12, 13)	0: On (4) 1: Off (5)	RW
CM06	Main clock division select bit 0 (7, 13, 14)	0: CM16 and CM17 valid 1: Division by 8 mode	RW
CM07	System clock select bit (6, 10, 11, 12)	0: Main clock, PLL clock, or on-chip oscillator clock 1: Sub-clock	RW

NOTES:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).
2. The CM03 bit is set to 1 (high) when the CM04 bit is set to 0 (I/O port) or the MCU goes to a stop mode.
3. This bit is provided to stop the main clock when the low power dissipation mode or on-chip oscillator low power dissipation mode is selected. This bit cannot be used for detection as to whether the main clock stopped or not. To stop the main clock, the following setting is required:
   (1) Set the CM07 bit to 1 (Sub-clock select) or the CM21 bit in the CM2 register to 1 (on-chip oscillator select) with the sub-clock stably oscillating.
   (2) Set the CM20 bit in the CM2 register to 0 (Oscillation stop, re-oscillation detection function disabled).
   (3) Set the CM05 bit to 1 (Stop).
4. During external clock input, set the CM05 bit to 0 (On).
5. When CM05 bit is set to 1, the XOUT pin goes "H". Futhermore, because the internal feedback resistor remains connectes, the XIN pin is pulled "H" to the same level as XOUT via the feedback resistor.
6. After setting the CM04 bit to 1 (XCIN-XCOUT oscillator function), wait until the sub-clock oscillates stably before switching the CM07 bit from 0 to 1 (sub-clock).
7. When entering stop mode from high or middle speed mode, on-chip oscillator mode or on-chip oscillator low power mode, the CM06 bit is set to 1 (divided-by-8 mode).
8. The fC32 clock does not stop. During low speed or low power dissipation mode, do not set this bit to 1(peripheral clock turned off in wait mode).
9. To use a sub-clock, set this bit to 1. Also, make sure ports P86 and P87 are directed for input, with no pull-ups.
10. When the PM21 bit in the PM2 register is set to 1 (clock modification disable), writing to bits CM02, CM05, and CM07 has no effect.
11. If the PM21 bit needs to be set to 1, set the CM07 bit to 0 (main clock) before setting it.
12. To use the main clock a the clock source for the CPU clock, follow the procedure below.
   (1) Set the CM05 bit to 0 (oscillate).
   (2) Wait the main clock oscillation stabilized.
   (3) Set all bits CM11, CM21, and CM07 to 0.
13. When the CM21 bit is set to 0 (on-chip oscillaor turned off) and the CM05 bit is set to 1 (main clock turned off), the CM06 bit is fixed to 1 (divide-by-8 mode) and the CM15 bit is fixed to 1 (drive capability High).
14. To return from on-chip oscillator mode to high-speed or middle-speed mode set both bits CM06 and CM15 to 1.

Figure 7.2 CM0 Register

System Clock Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			0	0	0		

Symbol CM1 Address 0007_{16} After Reset 00100000_2

Bit Symbol	Bit Name	Function	RW
CM10	All clock stop control bit (4, 6)	0 : Clock on 1 : All clocks off (stop mode)	RW
CM11	System clock select bit 1 (6, 7)	0 : Main clock 1 : PLL clock (5)	RW
(b4-b2)	Reserved bit	Set to 0	RW
CM15	XIN-XOUT drive capacity select bit (2)	0 : LOW 1 : HIGH	RW
CM16	Main clock division select bits (3)	b7 b6 0 0 : No division mode 0 1 : Division by 2 mode 1 0 : Division by 4 mode 1 1 : Division by 16 mode	RW
CM17			RW

NOTES:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).
2. When entering stop mode from high or middle speed mode, or when the CM05 bit is set to 1 (main clock turned off) in low speed mode, the CM15 bit is set to 1 (drive capability high).
3. Effective when the CM06 bit is 0 (bits CM16 and CM17 enable).
4. If the CM10 bit is 1 (stop mode), XOUT goes “H” and the internal feedback resistor is disconnected. The XCIN and XCOUT pins are placed in the high-impedance state. When the CM11 bit is set to 1 (PLL clock), or the CM20 bit in the CM2 register is set to 1 (oscillation stop, re-oscillation detection function enabled), do not set the CM10 bit to 1.
5. After setting the PLC07 bit in the PLC0 register to 1 (PLL operation), wait until tsu (PLL) elapses before setting the CM11 bit to 1 (PLL clock).
6. When the PM21 bit in the PM2 register is set to 1 (clock modification disable), writing to bits CM10, CM11 has no effect. When the PM22 bit in the PM2 register is set to 1 (watchdog timer count source is on-chip oscillator clock), writing to the CM10 bit has no effect.
7. Effective when CM07 bit is 0 and CM21 bit is 0 .

Figure 7.3 CM1 Register

On-chip Oscillator Control Register (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	0	0	0				

Symbol ROCR Address $025C_{16}$ After Reset $X0000101_2$

Bit Symbol	Bit Name	Function	RW
ROCR0	Frequency select bits	b1 b0 0 0: f_1 (ROC) 0 1: f_2 (ROC) 1 0: Do not set to this value 1 1: f_3 (ROC)	RW
ROCR1			RW
ROCR2	Divider select bits	b3 b2 0 0: Do not set to this value 0 1: divide by 2 1 0: divide by 4 1 1: divide by 8	RW
ROCR3			RW
(b6-b4)	Reserved bit	Set to 0	RW
(b7)	Nothing is assigned. When write, set to 0. When read, its content is undefined		—

NOTE:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).

Figure 7.4 ROCR Register

Oscillation Stop Detection Register (1)

b7	b6	b5	b4	b3	b2	b1	b0
	X	0	0				

Symbol	Address	After Reset
CM2	$000C_{16}$	$0X000010_2$ (11)

Bit Symbol	Bit Name	Function	RW
CM20	Oscillation stop, re-oscillation detection bit (7, 9, 10, 11)	0: Oscillation stop, re-oscillation detection function disabled 1: Oscillation stop, re-oscillation detection function enabled	RW
CM21	System clock select bit 2 (2, 3, 6, 8, 11, 12)	0: Main clock or PLL clock 1: On-chip oscillator clock (On-chip oscillator oscillating)	RW
CM22	Oscillation stop, re-oscillation detection flag (4)	0: Main clock stop,or re-oscillation not detected 1: Main clock stop,or re-oscillation detected	RW
CM23	XIN monitor flag (5)	0: Main clock oscillating 1: Main clock not oscillating	RO
— (b5-b4)	Reserved bit	Set to 0	RW
— (b6)	Nothing is assigned. When write, set to 0. When read, its content is undefined		—
CM27	Operation select bit (when an oscillation stop, re-oscillation is detected) (11)	0: Oscillation stop detection reset 1: Oscillation stop, re-oscillation detection interrupt	RW

NOTES:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).
2. When the CM20 bit is 1 (oscillation stop, re-oscillation detection function enabled), the CM27 bit is set to 1 (oscillation stop, re-oscillation detection interrupt), and the CPU clock source is the main clock, the CM21 bit is automatically set to 1 (on-chip oscillator clock) if the main clock stop is detected.
3. If the CM20 bit is set to 1 and the CM23 bit is set to 1 (main clock not oscillating), do not set the CM21 bit to 0.
4. This flag is set to 1 when the main clock is detected to have stopped or when the main clock is detected to have restarted oscillating. When this flag changes state from 0 to 1, an oscillation stop, reoscillation restart detection interrupt is generated. Use this flag in an interrupt routine to discriminate the causes of interrupts between the oscillation stop, reoscillation detection interrupts and the watchdog timer interrupt. The flag is cleared to 0 by writing 0 by program. (Writing 1 has no effect. Nor is it cleared to 0 by an oscillation stop or an oscillation restart detection interrupt request acknowledged.) If when the CM22 bit is set to 1 an oscillation stoppage or an oscillation restart is detected, no oscillation stop, reoscillation restart detection interrupts are generated.
5. Read the CM23 bit in an oscillation stop, re-oscillation detection interrupt handling routine to determine the main clock status.
6. Effective when the CM07 bit in the CM0 register is set to 0.
7. When the PM21 bit in the PM2 register is 1 (clock modification disabled), writing to the CM20 bit has no effect.
8. When the CM20 bit is set to 1 (oscillation stop, re-oscillation detection function enabled), the CM27 bit is set 1 (oscillation stop, re-oscillation detection interrupt), and the CM11 bit is 1 (the CPU clock source is PLL clock), the CM21 bit remains unchanged even when main clock stop is detected. If the CM22 bit is set to 0 under these conditions, oscillation stop, re-oscillation detection interrupt occur at main clock stop detection; it is, therefore, necessary to set the CM21 bit to 1 (on-chip oscillator clock) inside the interrupt routine.
9. Set the CM20 bit to 0 (disable) before entering stop mode. After exiting stop mode, set the CM20 bit back to 1 (enable).
10. Set the CM20 bit to 0 (disable) before setting the CM05 bit in the CM0 register.
11. Bits CM20, CM21 and CM27 do not change at oscillation stop detection reset.
12. When the CM21 bit is set to 0 (on-chip oscillator turned off) and the CM05 bit is set to 1 (main clock turned off), the CM06 bit is fixed to 1 (divide-by-8 mode) and the CM15 bit is fixed to 1 (drive capability High).

Figure 7.5 CM2 Register

Peripheral Clock Select Register (1)

b7	b6	b5	b4	b3	b2	b1	b0
0	0		0	0	0		

Symbol	Address	After Reset
PCLKR	$025E_{16}$	00000011_2

Bit Symbol	Bit Name	Function	RW
PCLK0	Timers A, B clock select bit (Clock source for the timers A, B, the timer S, the dead timer, SI/O3, SI/O4 and multi-master I^2C bus)	0: f_2 1: f_1	RW
PCLK1	SI/O clock select bit (Clock source for UART0 to UART2)	0: f_{2SIO} 1: f_{1SIO}	RW
(b4-b2)	Reserved bit	Set to 0	RW
PCLK5	Clock output function expansion select bit	Refer to **Table 7.3**	RW
(b7-b6)	Reserved bit	Set to 0	RW

NOTE:
1. Write to this register after setting the PRC0 bit in PRCR register to 1 (write enable).

Processeor Mode Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	X		0			

Symbol	Address	After Reset
PM2	$001E_{16}$	$XXX00000_2$

Bit Symbol	Bit Name	Function	RW
PM20	Specifying wait when accessing SFR(2)	0: 2 waits 1: 1 wait	RW
PM21	System clock protective bit(3,4)	0: Clock is protected by PRCR register 1: Clock modification disabled	RW
PM22	WDT count source protective bit(3,5)	0: CPU clock is used for the watchdog timer count source 1: On-chip oscillator clock is used for the watchdog timer count source	RW
(b3)	Reserved bit	Set to 0	RW
PM24	$P8_5/\overline{NMI}$ configuration bit(6,7)	0: $P8_5$ function ($\overline{NMI}$ disabled) 1: $\overline{NMI}$ function	RW
(b7-b5)	Nothing is assigned. When write, set to 0. When read, thecontent is undefined		—

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enable).
2. The PM20 bit becomes effective when PLC07 bit in the PLC0 register is set to 1 (PLL on). Change the PM20 bit when the PLC07 bit is set to 0 (PLL off). Set the PM20 bit to 0 (2 waits) when PLL clock > 16MHz.
3. Once this bit is set to 1, it cannot be cleared to 0 by program.
4. Writing to the following bits has no effect when the PM21 bit is set to 1:
   CM02 bit in the CM0 register
   CM05 bit in the CM0 register (main clock is not halted)
   CM07 bit in the CM0 register (CPU clock source does not change)
   CM10 bit in the CM1 register (stop mode is not entered)
   CM11 bit in the CM1 register (CPU clock source does not change)
   CM20 bit in the CM2 register (oscillation stop, re-oscillation detection function settings do not change)
   All bits in the PLC0 register (PLL frequency synthesizer setting do not change)
   Do not execute WAIT instruction when the PM21 bit is set to 1.
5. Setting the PM22 bit to 1 results in the following conditions:
   • The on-chip oscillator continues oscillating even if the CM21 bit in the CM2 register is set to "0" (main clock or PLL clock) (system clock of count source selected by the CM21 bit is valid)
   • The on-chip oscillator starts oscillating, and the on-chip oscillator clock becomes the watchdog timer count source.
   • The CM10 bit in the CM1 register cannnot be written. (Writing 1 has no effect, stop mode is not entered.)
   • The watchdog timer does not stop in wait mode.
6. For $\overline{NMI}$ function, the PM24 bit must be set to 1($\overline{NMI}$ function). Once this bit is set to 1, it cannot be set to 0 by program.
7. $\overline{SD}$ input is valid regardless of the PM24 setting.

Figure 7.6 PCLKR Register and PM2 Register

PLL Control Register 0 [1,2]

b7	b6	b5	b4	b3	b2	b1	b0
	0	0	1	X			

Symbol	Address	After Reset
PLC0	$001C_{16}$	$0001X010_2$

Bit Symbol	Bit Name	Function	RW
PLC00	PLL multiplying factor select bit [3]	b2 b1 b0 0 0 0: Do not set 0 0 1: Multiply by 2 0 1 0: Multiply by 4 0 1 1: 1 0 0: 1 0 1: Do not set 1 1 0: 1 1 1:	RW
PLC01			RW
PLC02			RW
(b3)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
(b4)	Reserved bit	Set to 1	RW
(b6-b5)	Reserved bit	Set to 0	RW
PLC07	Operation enable bit [4]	0: PLL Off 1: PLL On	RW

NOTES:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).
2. When the PM21 bit in the PM2 register is 1 (clock modification disable), writing to this register has no effect.
3. These three bits can only be modified when the PLC07 bit is set to 0 (PLL turned off). The value once written to this bit cannot be modified.
4. Before setting this bit to 1 , set the CM07 bit to 0 (main clock), set bits CM17 to CM16 bits to 00_2 (main clock undivided mode), and set the CM06 bit to 0 (CM16 and CM17 bits enable).

CAN0 Clock Select Register [1]

b7	b6	b5	b4	b3	b2	b1	b0
X	X	X	X				

Symbol	Address	After Reset
CCLKR	$025F_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
CCLK0	CAN0 clock select bits [2]	b2 b1 b0 0 0 0 No division 0 0 1: Divide-by-2 0 1 0: Divide-by-4 0 1 1: Divide-by-8 1 0 0: Divide-by-16 1 0 1: 1 1 0: Inhibited 1 1 1:	RW
CCLK1			RW
CCLK2			RW
CCLK3	CAN0 CPU interface sleep bit [3]	0: CAN0 CPU interface operating 1: CAN0 CPU interface in sleep	RW
(b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		RW

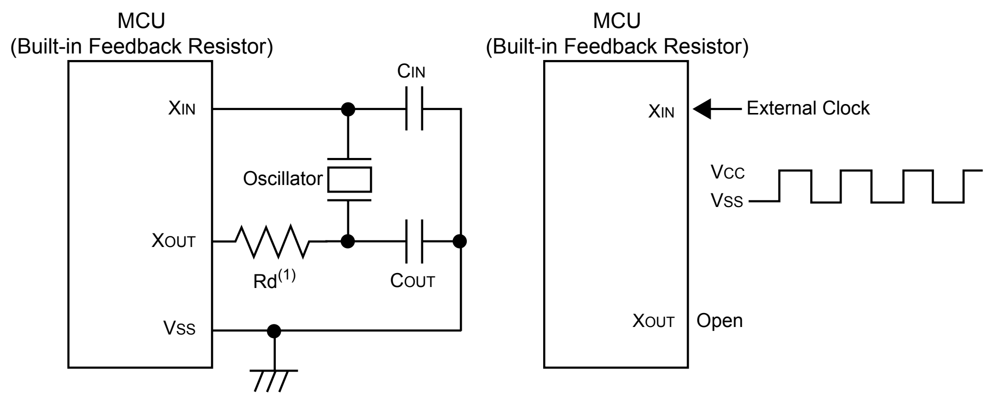
NOTES:
1. Write to this register after setting the PRC0 bit in the PRCR register to 1 (write enable).
2. Configuration of bits CCLK2 to CCLK0 can be done only when the Reset bit in the C0CTLR register is set to 1 (Reset/Initialization mode).
3. Before setting this bit to 1(CAN0 CPU interface in sleep), set the Sleep bit in C0CTLR register to 1 (Sleep mode).

Figure 7.7 PLC0 Register and CCLKR register

The following describes the clocks generated by the clock generation circuit.

7.1 Main Clock

The main clock is generated by the main clock oscillation circuit. This clock is used as the clock source for the CPU and peripheral function clocks. The main clock oscillator circuit is configured by connecting a resonator between the XIN and XOUT pins. The main clock oscillator circuit contains a feedback resistor, which is disconnected from the oscillator circuit during stop mode in order to reduce the amount of power consumed in the chip. The main clock oscillator circuit may also be configured by feeding an exter nally generated clock to the XIN pin. **Figure 7.8** shows the examples of main clock connection circuit.
The power consumption in the chip can be reduced by setting the CM05 bit in the CM0 register to 1 (main clock oscillator circuit turned off) after switching the clock source for the CPU clock to a sub clock or on-chip oscillator clock. In this case, XOUT goes "H". Furthermore, because the internal feedback resistor remains on, XIN is pulled "H" to XOUT via the feedback resistor.
During stop mode, all clocks including the main clock are turned off. Refer to "power control".
If the main clock is not used, it is recommended to connect the XIN pin to VCC to reduce power consumption during reset.



NOTE:
1. Insert a damping resistor if required. Resistance value varies depending on the oscillator setting. Use resistance value recommended by the oscillator manufacturer. If the oscillator manufacturer recommends that a feedback resistor be added to the chip externally, insert a feedback resistor between XIN and XOUT.
2. The external clock should not be stopped when it is connected to the XIN pin and the main clock is selected as the CPU clock.

Figure 7.8 Examples of Main Clock Connection Circuit

7.2 Sub Clock

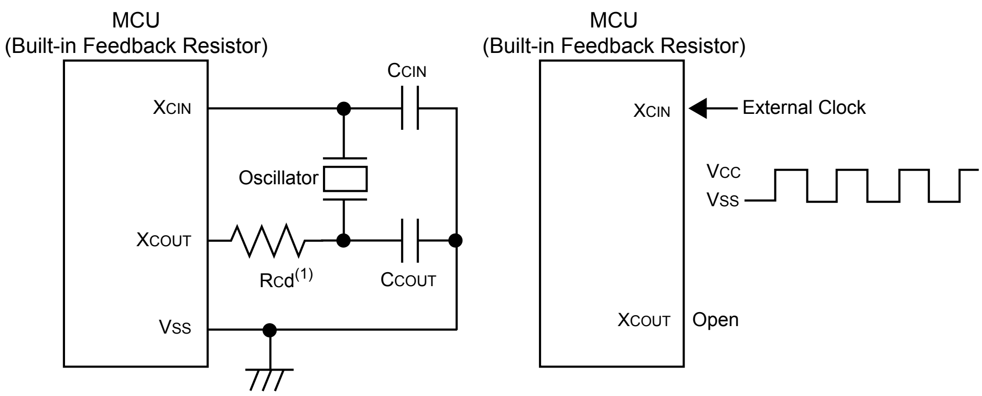
The sub clock is generated by the sub clock oscillation circuit. This clock is used as the clock source for the CPU clock, as well as the timer A and timer B count sources.

The sub clock oscillator circuit is configured by connecting a crystal resonator between the XCIN and XCOUT pins. The sub clock oscillator circuit contains a feedback resistor, which is disconnected from the oscillator circuit during stop mode in order to reduce the amount of power consumed in the chip. The sub clock oscillator circuit may also be configured by feeding an externally generated clock to the XCIN pin. **Figure 7.9** shows the examples of sub clock connection circuit.

After reset, the sub clock is turned off. At this time, the feedback resistor is disconnected from the oscillator circuit.

To use the sub clock for the CPU clock, set the CM07 bit in the CM0 register to 1 (sub clock) after the sub clock becomes oscillating stably.

During stop mode, all clocks including the sub clock are turned off. Refer to “power control”.



NOTE:
1. Place a damping resistor if required. Resistance values vary depending on the oscillator setting. Use values recommended by each oscillator manufacturer.
Place a feedback resistor between XCIN and XCOUT if the oscillator manufacturer recommends placing the resistor externally.

Figure 7.9 Examples of Sub Clock Connection Circuit

7.3 On-chip Oscillator Clock

This clock is supplied by a variable on-chip oscillator. This clock is used as the clock source for the CPU and peripheral function clocks. In addition, if the PM22 bit in the PM2 register is 1 (on-chip oscillator clock for the watchdog timer count source), this clock is used as the count source for the watchdog timer (Refer to 10. Watchdog Timer • Count source protective mode").

After reset, the on-chip oscillator clock divided by 16 is used for the CPU clock. It can also be turned on by setting the CM21 bit in the CM2 register to 1 (on-chip oscillator clock), and is used as the clock source for the CPU and peripheral function clocks. If the main clock stops oscillating when the CM20 bit in the CM2 register is 1 (oscillation stop, re-oscillation detection function enabled) and the CM27 bit is 1 (oscillation stop, re-oscillation detection interrupt), the on-chip oscillator automatically starts operating, supplying the necessary clock for the MCU.

7.4 PLL Clock

The PLL clock is generated from the main clock by a PLL frequency synthesizer. This clock is used as the clock source for the CPU and peripheral function clocks. After reset, the PLL clock is turned off. The PLL frequency synthesizer is activated by setting the PLC07 bit to 1 (PLL operation). When the PLL clock is used as the clock source for the CPU clock, wait t_{su}(PLL) for the PLL clock to be stable, and then set the CM11 bit in the CM1 register to 1.

Before entering wait mode or stop mode, be sure to set the CM11 bit to 0 (CPU clock source is the main clock). Furthermore, before entering stop mode, be sure to set the PLC07 bit in the PLC0 register to 0 (PLL stops). **Figure 7.10** shows the procedure for using the PLL clock as the clock source for the CPU.

The PLL clock frequency is determined by the equation below.

PLL clock frequency=f(X_{IN}) X (multiplying factor set by bits PLC02 to PLC00 in the PLC0 register

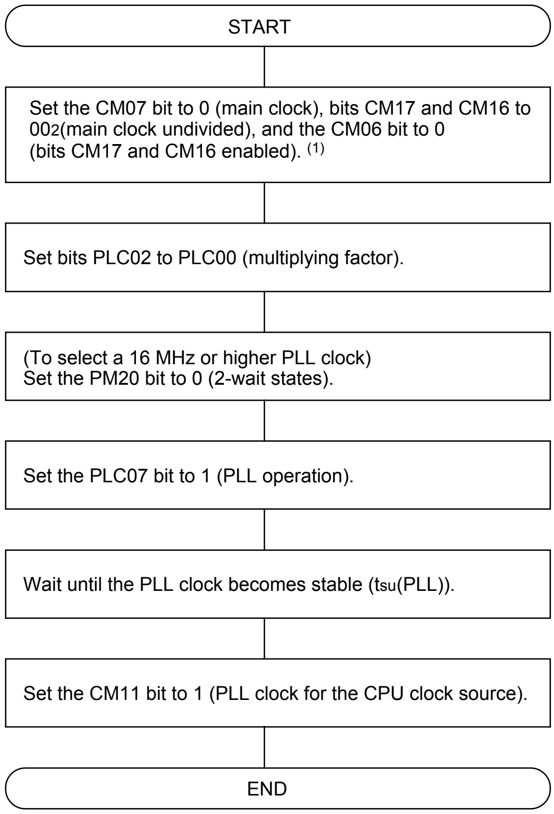
(However, 10 MHz ≤ PLL clock frequency ≤ 20 MHz)

Bits PLC02 to PLC00 can be set only once after reset. **Table 7.2** shows the example for setting PLL clock frequencies.

Table 7.2 Example for Setting PLL Clock Frequencies

X_{IN} (MHz)	PLC02	PLC01	PLC00	Multiplying factor	PLL clock (MHz)(1)
10	0	0	1	2	20
5	0	1	0	4	

NOTE:
1. 10MHz ≤ PLL clock frequency ≤ 20MHz.



NOTE:
1. PLL operation mode can be entered from high speed mode.

Figure 7.10 Procedure to Use PLL Clock as CPU Clock Source

7.5 CPU Clock and Peripheral Function Clock

The CPU clock is used to operate the CPU and peripheral function clocks are used to operate the peripheral functions.

7.5.1 CPU Clock

This is the operating clock for the CPU and watchdog timer.

The clock source for the CPU clock can be chosen to be the main clock, sub clock, on-chip oscillator clock or the PLL clock.

If the main clock or on-chip oscillator clock is selected as the clock source for the CPU clock, the selected clock source can be divided by 1 (undivided), 2, 4, 8 or 16 to produce the CPU clock. Use the CM06 bit in CM0 register and bits CM17 to CM16 in CM1 register to select the divide-by-n value.

When the PLL clock is selected as the clock source for the CPU clock, the CM06 bit should be set to 0 and bits CM17 and CM16 to 00_2 (undivided).

After reset, the on-chip oscillator clock divided by 16 provides the CPU clock.

Note that when entering stop mode from high or middle speed mode, on-chip oscillator mode or on-chip oscillator low power dissipation mode, or when the CM05 bit in the CM0 register is set to 1 (main clock turned off) in low-speed mode, the CM06 bit in the CM0 register is set to 1 (divide-by-8 mode).

7.5.2 Peripheral Function Clock(f_1, f_2, f_8, f_{32}, f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}, f_{AD}, f_{C32}, f_{CAN0})

These are operating clocks for the peripheral functions.

Of these, fi (i = 1, 2, 8, 32) and f_{iSIO} are derived from the main clock, PLL clock, or on-chip oscillator clock divided by i. The clock fi is used for Timer A, Timer B, SI/O3 and SI/O4 while fiSIO is used for UART0 to UART2. Additionally, the f1 and f2 clocks are also used for dead time timer, Timer S, multi-master I^{2}C bus.

The f_{AD} clock is produced from the main clock, PLL clock or on-chip oscillator clock, and is used for the A/D converter.

The f_{CAN0} clock is derived from the main clock, PLL clock or on-chip oscillator clock devided by 1 (undivided), 2, 4, 8, or 16, and is used for the CAN module.

When the WAIT instruction is executed after setting the CM02 bit in the CM0 register to 1 (peripheral function clock turned off during wait mode), or when the MCU is in low power dissipation mode, the fi, f_{iSIO}, f_{AD}, and f_{CAN0} clocks are turned off. (Note 1)

The f_{C32} clock is produced from the sub clock, and is used for timers A and B. This clock can only be used when the sub clock is on.

Note 1: f_{CAN0} clock stops at "H" in CAN0 sleep mode.

7.5.3 ClockOutput Function

The f_1, f_8, f_{32} or f_C clock can be output from the CLKOUT pin. Use the PCLK5 bit in the PCLKR register and bits CM01 to CM00 in the CM0 register to select. **Table 7.3** shows the function of the CLKOUT pin.

Table 7.3 The function of the CLKOUT pin

PCLK5	CM01	CM00	The function of the CLKOUT pin
0	0	0	I/O port P9$_0$
0	0	1	f_C
0	1	0	f_8
0	1	1	f_{32}
1	0	0	f_1
1	0	1	Do not set
1	1	0	Do not set
1	1	1	Do not set

7.6 Power Control

There are three power control modes. In this chapter, all modes other than wait and stop modes are referred to as normal operation mode.

7.6.1 Normal Operation Mode

Normal operation mode is further classified into seven modes.

In normal operation mode, because the CPU clock and the peripheral function clocks both are on, the CPU and the peripheral functions are operating. Power control is exercised by controlling the CPU clock frequency. The higher the CPU clock frequency, the greater the processing capability. The lower the CPU clock frequency, the smaller the power consumption in the chip. If the unnecessary oscillator circuits are turned off, the power consumption is further reduced.

Before the clock sources for the CPU clock can be switched over, the new clock source must be in stable oscillation. If the new clock source is the main clock, sub clock or PLL clock, allow a sufficient wait time in a program until it becomes oscillating stably.

Note that operation modes cannot be changed directly from low power dissipation mode to on-chip oscillator mode or on-chip oscillator low power dissipation mode. Nor can operation modes be changed directly from on-chip oscillator mode or on-chip oscillator low power dissipation mode to low power dissipation mode.

When the CPU clock source is changed from the on-chip oscillator to the main clock, change the operation mode to the medium speed mode (divided by 8 mode) after the clock was divided by 8 (the CM06 bit in the CM0 register was set to 1) in the on-chip oscillator mode.

7.6.1.1 High-speed Mode

The main clock divided by 1 provides the CPU clock. If the sub clock is on, f_{C32} can be used as the count source for timers A and B.

7.6.1.2 PLL Operation Mode

The main clock multiplied by 2 or 4 provides the PLL clock, and this PLL clock serves as the CPU clock. If the sub clock is on, f_{C32} can be used as the count source for timers A and B. PLL operation mode can be entered from high speed mode. If PLL operation mode is to be changed to wait or stop mode, first go to high speed mode before changing.

7.6.1.3 Medium-speed Mode

The main clock divided by 2, 4, 8 or 16 provides the CPU clock. If the sub clock is on, f_{C32} can be used as the count source for timers A and B.

7.6.1.4 Low-speed Mode

The sub clock provides the CPU clock. The main clock is used as the clock source for the peripheral function clock when the CM21 bit is set to 0 (on-chip oscillator turned off), and the on-chip oscillator clock is used when the CM21 bit is set to 1 (on-chip oscillator oscillating).

The f_{C32} clock can be used as the count source for timers A and B.

7.6.1.5 Low Power Dissipation Mode

In this mode, the main clock is turned off after being placed in low speed mode. The sub clock provides the CPU clock. The f_{C32} clock can be used as the count source for timers A and B. Peripheral function clock can use only f_{C32}.

Simultaneously when this mode is selected, the CM06 bit in the CM0 register becomes 1 (divided by 8 mode). In the low power dissipation mode, do not change the CM06 bit. Consequently, the medium speed (divided by 8) mode is to be selected when the main clock is operated next.

7.6.1.6 On-chip Oscillator Mode

The selected on-chip oscillator clock divided by 1 (undivided), 2, 4, 8 or 16 provides the CPU clock. The on-chip oscillator clock is also the clock source for the peripheral function clocks. If the sub clock is on, f_{C32} can be used as the count source for timers A and B. The on-chip oscillator frequency can be selected by bits ROCR3 to ROCR0 in the ROCR register. When the operation mode is returned to the high and medium speed modes, set the CM06 bit to 1 (divided by 8 mode).

7.6.1.7 On-chip Oscillator Low Power Dissipation Mode

The main clock is turned off after being placed in on-chip oscillator mode. The CPU clock can be selected as in the on-chip oscillator mode. The on-chip oscillator clock is the clock source for the peripheral function clocks. If the sub clock is on, f_{C32} can be used as the count source for timers A and B.

Table 7.4 Setting Clock Related Bit and Modes

Modes		CM2 Register	CM1 Register		CM0 Register			
		CM21	CM11	CM17, CM16	CM07	CM06	CM05	CM04
PLL operation mode		0	1	00_2	0	0	0	—
High-speed mode		0	0	00_2	0	0	0	—
Medium-speed mode	divided by 2	0	0	01_2	0	0	0	—
	divided by 4	0	0	10_2	0	0	0	—
	divided by 8	0	0	—	0	1	0	—
	divided by 16	0	0	11_2	0	0	0	—
Low-speed mode		—	—	—	1	—	0	1
Low power dissipation mode		—	—	—	1	1(1)	1(1)	1
On-chip oscillator mode(3)	divided by 1	1	—	00_2	0	0	0	—
	divided by 2	1	—	01_2	0	0	0	—
	divided by 4	1	—	10_2	0	0	0	—
	divided by 8	1	—	—	0	1	0	—
	divided by 16	1	—	11_2	0	0	0	—
On-chip oscillator low power dissipation mode		1	—	(2)	0	(2)	1	—

NOTES:
1. When the CM05 bit is set to 1 (main clock turned off) in low-speed mode, the mode goes to low power dissipation mode and CM06 bit is set to 1(divided by 8 mode) simultaneously.
2. The divide-by-n value can be selected the same way as in on-chip oscillator mode.
3. On-chip oscillator frequency can be any of those described in the section **7.6.1.6 On-chip Oscillator Mode**.

7.6.2 Wait Mode

In wait mode, the CPU clock is turned off, so are the CPU (because operated by the CPU clock) and the watchdog timer. However, if the PM22 bit in the PM2 register is 1 (on-chip oscillator clock for the watchdog timer count source), the watchdog timer remains active. Because the main clock, sub clock, on-chip oscillator clock and PLL clock all are on, the peripheral functions using these clocks keep operating.

7.6.2.1 Peripheral Function Clock Stop Function

When the CM02 bit is 1 (peripheral function clocks turned off during wait mode), f_1, f_2, f_8, f_{32}, f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}, and f_{AD} stop running in wait mode to reduce power consumption. However, f_{C32} remains active.

7.6.2.2 Entering Wait Mode

The MCU enters wait mode by executing the WAIT instruction.

When the CM11 bit is set to 1 (CPU clock source is the PLL clock), be sure to clear the CM11 bit to 0 (CPU clock source is the main clock) before going to wait mode. The power consumption of the chip can be reduced by clearing the PLC07 bit to 0 (PLL stops).

7.6.2.3 Pin Status During Wait Mode

Table 7.5 lists pin status during wait mode.

Table 7.5 Pin Status in Wait Mode

Pin		Status
I/O ports		Retains status before wait mode
CLKOUT	When fC selected	Does not stop
	When f1, f8, f32 selected	Does not stop when the CM02 bit is set to 0
		Retains status before wait mode when the CM02 bit is set to 1

7.6.2.4 Exiting Wait Mode

The MCU exits from wait mode by a hardware reset, $\overline{\text{NMI}}$ interrupt, or peripheral function interrupt.
If wait mode is exited by a hardware reset or $\overline{\text{NMI}}$ interrupt, set the peripheral function interrupt priority bits ILVL2 to ILVL0 to 000_2 (interrupts disabled) before executing the WAIT instruction.
The CM02 bit affects the peripheral function interrupts. If the CM02 bit is 0 (peripheral function clocks not turned off during wait mode), all peripheral function interrupts can be used to exit wait mode. If the CM02 bit is 1 (peripheral function clock stops during wait mode), the peripheral functions using the peripheral function clock stops operating, so that only the peripheral functions clocked by external signals can be used to exit wait mode.
Table 7.6 lists the interrupts to exit wait mode.

Table 7.6 Interrupts to Exit Wait Mode

Interrupt	CM02 = 0	CM02 = 1
NMI interrupt	Available	Available
Serial I/O interrupt	Available when internal and external clocks are used	Available when external clock is used
Multi-master I^{2}C interrupt	Available	Do not used
Key input interrupt	Available	Available
A/D conversion interrupt	Available in one-shot or single sweep mode	Do not use
Timer A interrupt Timer B interrupt	Available in all modes	Available in event counter mode or when count source is fC32
Timer S interrupt	Available in all modes	Do not use
$\overline{\text{INT}}$ interrupt	Available	Available
CAN0 wake_up interrupt	Available in CAN sleep mode	Available in CAN sleep mode

To use peripheral function interrupts to exit wait mode, set the followings before executing the WAIT instruction.

1. Set the interrupt priority level to the bits ILVL2 to ILVL0 in the interrupt control register of the peripheral function interrupts that are used to exit wait mode. Also, set bits ILVL2 to ILVL0 of all peripheral function interrupts that are not used to exit wait mode to 000_2 (interrupt disabled).
2. Set the I flag to 1.
3. Operate the peripheral functions that are used to exit wait mode.

When the peripheral function interrupts are used to exit wait mode, an interrupt routine is executed after an interrupt request is generated and the CPU is clocked.

The CPU clock used when exiting wait mode by a peripheral function interrupt is the same CPU clock that is used when executing the WAIT instruction.

7.6.3 Stop Mode

In stop mode, all oscillator circuits are turned off, so are the CPU clock and the peripheral function clocks. Therefore, the CPU and the peripheral functions clocked by these clocks stop operating. The least amount of power is consumed in this mode. If the voltage applied to Vcc pin is V_{RAM} or more, the internal RAM is retained. When applying 2.7 or less voltage to Vcc pin, make sure $Vcc \geq V_{RAM}$.
However, the peripheral functions clocked by external signals keep operating. The following interrupts can be used to exit stop mode.

- $\overline{\text{NMI}}$ interrupt
- Key interrupt
- $\overline{\text{INT}}$ interrupt
- Timer A, Timer B interrupt (when counting external pulses in event counter mode)
- Serial I/O interrupt (when external clock is selected)
- Low voltage detection interrup (refer to "**Low Voltage Detection Interrupt**" for an operating condition)
- CAN0 Wake_up interrupt (in CAN sleep mode)

7.6.3.1 Entering Stop Mode

The MCU is placed into stop mode by setting the CM10 bit in the CM1 register to 1 (all clocks turned off). At the same time, the CM06 bit in the CM0 register is set to 1 (divide-by-8 mode) and the CM15 bit in the CM10 register is set to 1 (main clock oscillator circuit drive capability high).
Before entering stop mode, set the CM20 bit to 0 (oscillation stop, re-oscillation detection function disable).
Also, if the CM11 bit is 1 (PLL clock for the CPU clock source), set the CM11 bit to 0 (main clock for the CPU clock source) and the PLC07 bit to 0 (PLL turned off) before entering stop mode.

7.6.3.2 Pin Status during Stop Mode

The I/O pins retain their status held just prior to entering stop mode.

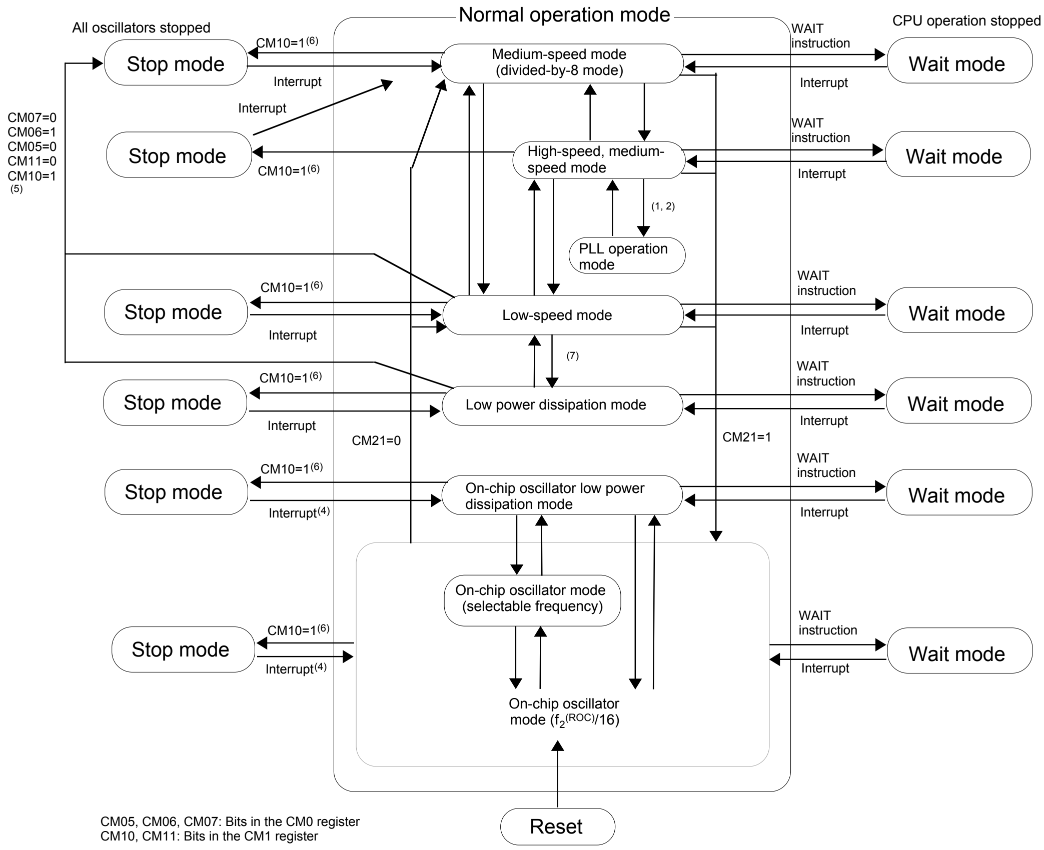
7.6.3.3 Exiting Stop Mode

The MCU is moved out of stop mode by a hardware reset, $\overline{\text{NMI}}$ interrupt or peripheral function interrupt.
If the MCU is to be moved out of stop mode by a hardware reset or $\overline{\text{NMI}}$ interrupt, set the peripheral function interrupt priority bits ILVL2 to ILVL0 to 000_2 (interrupts disable) before setting the CM10 bit to 1.
If the MCU is to be moved out of stop mode by a peripheral function interrupt, set up the following before setting the CM10 bit to 1.

1. In bits ILVL2 to ILVL0 of the interrupt control register, set the interrupt priority level of the peripheral function interrupt to be used to exit stop mode.
   Also, for all of the peripheral function interrupts not used to exit stop mode, set bits ILVL2 to ILVL0 to 000_2.
2. Set the I flag to 1.
3. Enable the peripheral function whose interrupt is to be used to exit stop mode.
   In this case, when an interrupt request is generated and the CPU clock is thereby turned on, an interrupt service routine is executed.

Which CPU clock will be used after exiting stop mode by a peripheral function or $\overline{\text{NMI}}$ interrupt is determined by the CPU clock that was on when the MCU was placed into stop mode as follows:
If the CPU clock before entering stop mode was derived from the sub clock: sub clock
If the CPU clock before entering stop mode was derived from the main clock: main clock divide-by-8
If the CPU clock before entering stop mode was derived from the on-chip oscillator clock: on-chip oscillator clock divide-by-8

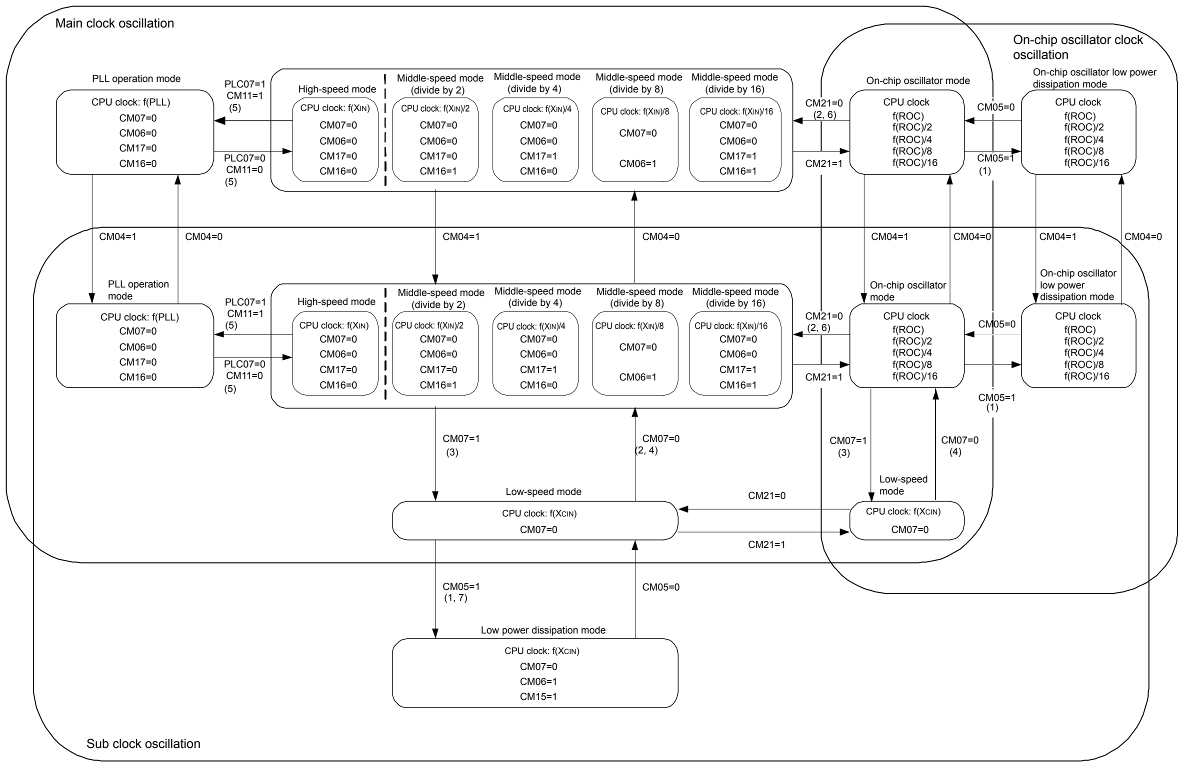
Figure 7.11 shows the state transition from normal operation mode to stop mode and wait mode. **Figure 7.12** shows the state transition in normal operation mode.
Table 7.7 shows a state transition matrix describing allowed transition and setting. The vertical line shows current state and horizontal line shows state after transition.



→ : Arrow shows mode can be changed. Do not change mode to another mode when no arrow is shown.

NOTES:
1. Do not go directly from PLL operation mode to wait or stop mode.
2. PLL operation mode can be entered from high speed mode. Similarly, PLL operation mode can be changed back to high speed mode.
3. When the PM21 bit is set to 0 (system clock protective function unused).
4. The on-chip oscillator clock divided by 8 provides the CPU clock.
5. Write to the CM0 register and CM1 register simultaneously by accessing in word units while CM21 bit is set to 0 (on-chip oscillator turned off). When the clock generated externally is input to the XCIN pin, transit to stop mode with this process.
6. Before entering stop mode, be sure to clear the CM20 bit in the CM2 register to 0 (oscillation stop and oscillation restart detection function disabled).
7. The CM06 bit is set to 1 (divide-by-8).

Figure 7.11 State Transition to Stop Mode and Wait Mode



→: Arrow shows mode can be changed. Do not change mode to another mode when no arrow is shown.

NOTES:

1. Avoid making a transition when the CM20 bit is set to 1 (oscillation stop, re-oscillation detection function enabled). Set the CM20 bit to 0 (oscillation stop, re-oscillation detection function disabled) before transiting.
2. Wait for the main clock oscillation stabilization time before switching over. Set the CM15 bit in the CM1 register to 1 (drive capacity High) until main clock oscillation is stabilized.
3. Switch clock after oscillation of sub-clock is sufficiently stable.
4. Change bits CM17 and CM16 before changing the CM06 bit.
5. The PM20 bit in the PM2 register becomes effective when the PLC07 bit in the PLC0 register is set to 1 (PLL on). Change the PM20 bit when the PLC07 bit is set to 0 (PLL off). Set the PM20 bit to 0 (2 waits) when PLL clock > 16MHz.
6. Set the CM06 bit to 1 (division by 8 mode) before changing back the operation mode from on-chip oscillator mode to high- or middle-speed mode.
7. When the CM21 bit is set to 0 (on-chip oscillator turned off) and the CM05 bit is set to 1 (main clock turned off), the CM06 bit is fixed to 1 (divide-by-8 mode) and the CM15 bit is fixed to 1 (drive capability High).

Figure 7.12 State Transition in Normal Mode

Table 7.7 Allowed Transition and Setting

Current state	State after transition: High-speed mode, middle-speed mode	Low-speed mode[2]	Low power dissipation mode	PLL operation mode[2]	On-chip oscillator mode	On-chip oscillator low power dissipation mode	Stop mode	Wait mode
High-speed mode, middle-speed mode	8	(9)[7]	--	(13)[3]	(15)	--	(16)[1]	(17)
Low-speed mode[2]	(8)		(11)[1, 6]	--	(8)	--	(16)[1]	(17)
Low power dissipation mode	--	(10)		--	--	--	(16)[1]	(17)
PLL operation mode[2]	(12)[3]	--	--		--	--	--	--
On-chip oscillator mode	(14)[4]	(9)[7]	--	--	8	(11)[1]	(16)[1]	(17)
On-chip oscillator low power dissipation mode	--	--	--	--	(10)	8	(16)[1]	(17)
Stop mode	(18)[5]	(18)	(18)	--	(18)[5]	(18)[5]		--
Wait mode	(18)	(18)	(18)	--	(18)	(18)	--	

--: Cannot transit

NOTES:
1. Avoid making a transition when the CM20 bit is set to 1 (oscillation stop, re-oscillation detection function enabled). Set the CM20 bit to 0 (oscillation stop, re-oscillation detection function disabled) before transiting.
2. On-chip oscillator clock oscillates and stops in low-speed mode. In this mode, the on-chip oscillator can be used as peripheral function clock. Sub clock oscillates and stops in PLL operation mode. In this mode, sub clock can be used as a clock for the timers A and B.
3. PLL operation mode can only be entered from and changed to high-speed mode.
4. Set the CM06 bit to 1 (division by 8 mode) before transiting from on-chip oscillator mode to high- or middle-speed mode.
5. When exiting stop mode, the CM06 bit is set to 1 (division by 8 mode).
6. If the CM05 bit is set to 1 (main clock stop), then the CM06 bit is set to 1 (division by 8 mode).
7. A transition can be made only when sub clock is oscillating.
8. State transitions within the same mode (divide-by-n values changed or subclock oscillation turned on or off) are shown in the table below.

		Sub clock oscillating					Sub clock turned off				
		No division	Divided by 2	Divided by 4	Divided by 8	Divided by 16	No division	Divided by 2	Divided by 4	Divided by 8	Divided by 16
Sub clock oscillating	No division		(4)	(5)	(7)	(6)	(1)	--	--	--	--
	Divided by 2	(3)		(5)	(7)	(6)	--	(1)	--	--	--
	Divided by 4	(3)	(4)		(7)	(6)	--	--	(1)	--	--
	Divided by 8	(3)	(4)	(5)		(6)	--	--	--	(1)	--
	Divided by 16	(3)	(4)	(5)	(7)		--	--	--	--	(1)
Sub clock turned off	No division	(2)	--	--	--	--		(4)	(5)	(7)	(6)
	Divided by 2	--	(2)	--	--	--	(3)		(5)	(7)	(6)
	Divided by 4	--	--	(2)	--	--	(3)	(4)		(7)	(6)
	Divided by 8	--	--	--	(2)	--	(3)	(4)	(5)		(6)
	Divided by 16	--	--	--	--	(2)	(3)	(4)	(5)	(7)	

--: Cannot transit

9. ( ) : setting method. Refer to following table.

	Setting	Operation
(1)	CM04 = 0	Sub clock turned off
(2)	CM04 = 1	Sub clock oscillating
(3)	CM06 = 0, CM17 = 0 , CM16 = 0	CPU clock no division mode
(4)	CM06 = 0, CM17 = 0 , CM16 = 1	CPU clock division by 2 mode
(5)	CM06 = 0, CM17 = 1 , CM16 = 0	CPU clock division by 4 mode
(6)	CM06 = 0, CM17 = 1 , CM16 = 1	CPU clock division by 16 mode
(7)	CM06 = 1	CPU clock division by 8 mode
(8)	CM07 = 0	Main clock, PLL clock, or on-chip oscillator clock selected
(9)	CM07 = 1	Sub clock selected
(10)	CM05 = 0	Main clock oscillating
(11)	CM05 = 1	Main clock turned off
(12)	PLC07 = 0, CM11 = 0	Main clock selected
(13)	PLC07 = 1, CM11 = 1	PLL clock selected
(14)	CM21 = 0	Main clock or PLL clock selected
(15)	CM21 = 1	On-chip oscillator clock selected
(16)	CM10 = 1	Transition to stop mode
(17)	wait instruction	Transition to wait mode
(18)	Hardware interrupt	Exit stop mode or wait mode

CM04, CM05, CM06, CM07 : Bits in the CM0 register
CM10, CM11, CM16, CM17 : Bits in the CM1 register
CM20, CM21 : Bits in the CM2 register
PLC07 : Bit in the PLC0 register

RENESAS

7.7 System Clock Protective Function

When the main clock is selected for the CPU clock source, this function protects the clock from modifications in order to prevent the CPU clock from becoming halted by run-away.

If the PM21 bit in the PM2 register is set to 1 (clock modification disabled), the following bits are protected against writes:

- Bits CM02, CM05, and CM07 in CM0 register
- Bits CM10 and CM11 in CM1 register
- CM20 bit in CM2 register
- All bits in the PLC0 register

Before the system clock protective function can be used, the following register settings must be made while the CM05 bit in the CM0 register is 0 (main clock oscillating) and CM07 bit is 0 (main clock selected for the CPU clock source):

(1) Set the PRC1 bit in the PRCR register to 1 (enable writes to PM2 register).

(2) Set the PM21 bit in the PM2 register to 1 (disable clock modification).

(3) Set the PRC1 bit in the PRCR register to 0 (disable writes to PM2 register).

Do not execute the WAIT instruction when the PM21 bit is 1.

7.8 Oscillation Stop and Re-oscillation Detect Function

The oscillation stop and re-oscillation detect function detects the re-oscillation after stop of main clock oscillation circuit. When the oscillation stop and re-oscillation detection occurs, the oscillation stop detect function is reset or oscillation stop and re-oscillation detection interrupt is generated, depending on the CM27 bit set in the CM2 register. The oscillation stop detect function is enabled or disabled by the CM20 bit in the CM2 register. **Table 7.8** lists a specification overview of the oscillation stop and re-oscillation detect function.

Table 7.8 Specification Overview of Oscillation Stop and Re-oscillation Detect Function

Item	Specification
Oscillation stop detectable clock and frequency bandwidth	$f(X_{IN}) \geq 2$ MHz
Enabling condition for oscillation stop, re-oscillation detection function	Set CM20 bit to 1(enable)
Operation at oscillation stop, re-oscillation detection	•Reset occurs (when CM27 bit =0) •Oscillation stop, re-oscillation detection interrupt occurs(when CM27 bit =1)

7.8.1 Operation When CM27 bit = 0 (Oscillation Stop Detection Reset)

When main clock stop is detected when the CM20 bit is 1 (oscillation stop, re-oscillation detection function enabled), the MCU is initialized, coming to a halt (oscillation stop reset; refer to “SFR”, “Reset”). This status is reset with hardware reset 1. Also, even when re-oscillation is detected, the MCU can be initialized and stopped; it is, however, necessary to avoid such usage. (During main clock stop, do not set the CM20 bit to 1 and the CM27 bit to 0.)

7.8.2 Operation When CM27 bit = 1 (Oscillation Stop and Re-oscillation Detect Interrupt)

When the main clock corresponds to the CPU clock source and the CM20 bit is 1 (oscillation stop and re-oscillation detect function enabled), the system is placed in the following state if the main clock comes to a halt:

- Oscillation stop and re-oscillation detect interrupt request occurs.
- The on-chip oscillator starts oscillation, and the on-chip oscillator clock becomes the CPU clock and clock
  source for peripheral functions in place of the main clock.
- CM21 bit = 1 (on-chip oscillator clock for CPU clock source)
- CM22 bit = 1 (main clock stop detected)
- CM23 bit = 1 (main clock stopped)

When the PLL clock corresponds to the CPU clock source and the CM20 bit is 1, the system is placed in the following state if the main clock comes to a halt: Since the CM21 bit remains unchanged, set it to 1 (on-chip oscillator clock) inside the interrupt routine.

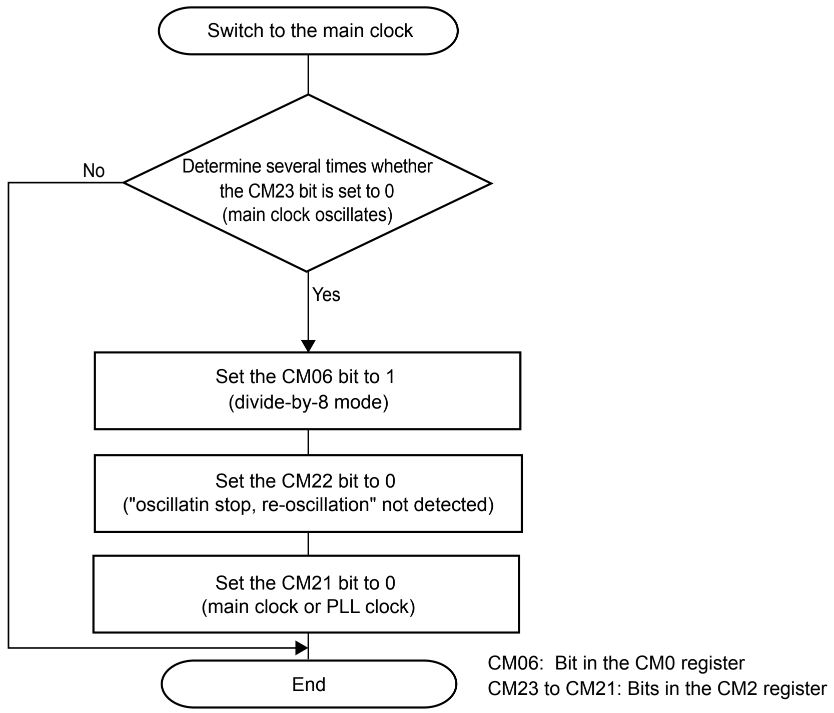
- Oscillation stop and re-oscillation detect interrupt request occurs.
- CM22 bit = 1 (main clock stop detected)
- CM23 bit = 1 (main clock stopped)
- CM21 bit remains unchanged

When the CM20 bit is 1, the system is placed in the following state if the main clock re-oscillates from the stop condition:

- Oscillation stop and re-oscillation detect interrupt request occurs.
- CM22 bit = 1 (main clock re-oscillation detected)
- CM23 bit = 0 (main clock oscillation)
- CM21 bit remains unchanged

7.8.3 How to Use Oscillation Stop and Re-oscillation Detect Function

- The oscillation stop and re-oscillation detect interrupt shares the vector with the watchdog timer interrupt. If the oscillation stop, re-oscillation detection and watchdog timer interrupts both are used, read the CM22 bit in an interrupt routine to determine which interrupt source is requesting the interrupt.
- Where the main clock re-oscillated after oscillation stop, return the main clock to the CPU clock and peripheral function clock source by program. **Figure 7.13** shows the procedure for switching the clock source from the on-chip oscillator to the main clock.
- Simultaneously with oscillation stop, re-oscillation detection interrupt occurrence, the CM22 bit becomes 1. When the CM22 bit is set at 1, oscillation stop, re-oscillation detection interrupt are disabled. By setting the CM22 bit to 0 by program, oscillation stop, re-oscillation detection interrupt are enabled.
- If the main clock stops during low speed mode where the CM20 bit is 1, an oscillation stop, re-oscillation detection interrupt request is generated. At the same time, the on-chip oscillator starts oscillating. In this case, although the CPU clock is derived from the sub clock as it was before the interrupt occurred, the peripheral function clocks now are derived from the on-chip oscillator clock.
- To enter wait mode while using the oscillation stop, re-oscillation detection function, set the CM02 bit to 0 (peripheral function clocks not turned off during wait mode).
- Since the oscillation stop, re-oscillation detection function is provided in preparation for main clock stop due to external factors, set the CM20 bit to 0 (Oscillation stop, re-oscillation detection function disabled) where the main clock is stopped or oscillated by program, that is where the stop mode is selected or the CM05 bit is altered.
- This function cannot be used if the main clock frequency is 2 MHz or less. In that case, set the CM20 bit to 0.



NOTE:
1. If the clock source for CPU clock is to be changed to PLL clock, set to PLL operation mode after set to high-speed mode.

Figure 7.13 Procedure to Switch Clock Source From On-chip Oscillator to Main Clock

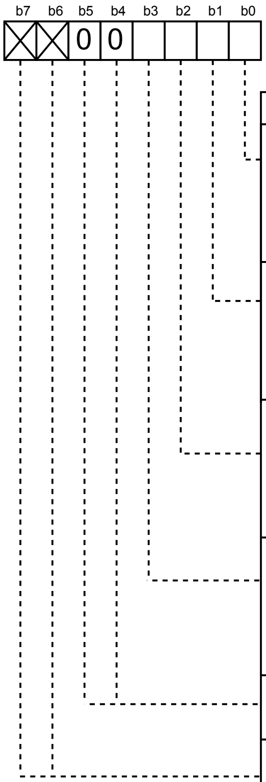
8. Protection

In the event that a program runs out of control, this function protects the important registers so that they will not be rewritten easily. **Figure 8.1** shows the PRCR register. The following lists the registers protected by the PRCR register.

- Registers protected by the PRC0 bit: CM0, CM1, CM2, PLC0, ROCR, PCLKR, and CCLKR
- Registers protected by the PRC1 bit: PM0, PM1, PM2, TB2SC, INVC0, and INVC1
- Registers protected by the PRC2 bit: PD9 , PACR, S4C, and NDDR
- Registers protected by the PRC3 bit: VCR2 and D4INT

The PRC2 bit is set to 0 (write enabled) when data is written to the SFR area after setting the PRC2 bit to 1 (write enable). Set registers PD9, PACR, S4C and NDDR immediately after setting the PRC2 bit in the PRCR register to 1 (write enable). Do not generate an interrupt or a DMA transfer between the instruction to set the PRC2 bit to 1 and the following instruction. Bits PRC3, PRC1, and PRC0 are not set to 0 even if data is written to the SFR area. Set bits PRC3, PRC1, and PRC0 to 0 by program.

Protect Register



Symbol: PRCR — Address: $000A_{16}$ — After Reset: $XX000000_2$

Bit Symbol	Bit Name	Function	RW
PRC0	Protect bit 0	Enable write to register CM0, CM1, CM2, ROCR, PLC0, PCLKR, and CCLKR 0: Write protected 1: Write enabled	RW
PRC1	Protect bit 1	Enable write to registers PM0, PM1, PM2, TB2SC, INVC0, and INVC1 0: Write protected 1: Write enabled	RW
PRC2	Protect bit 2	Enable write to registers PD9, PACR, S4C, and NDDR 0: Write protected 1: Write enabled(1)	RW
PRC3	Protect bit 3	Enable write to registers VCR2 and D4INT 0: Write protected 1: Write enabled	RW
(b5-b4)	Reserved bit	Set to 0	RW
(b7-b6)	Nothing is assigned. If necessary, set to 0. When read, its content is undefined		—

NOTE:
1. The PRC2 bit is set to 0 when writing into the SFR area after the PRC2 bit is set to 1. Bits PRC0, PRC1, and PRC3 are not automatically set to 0. Set them to 0 by program.

Figure 8.1 PRCR Register

9. Interrupts

Note

The SI/O4 interrupt of peripheral function interrupts is not available in the 64-pin package.
The low voltage detection function is not available in M16C/29 T-ver. and V-ver..

9.1 Type of Interrupts

Figure 9.1 shows types of interrupts.

- Interrupt
  - Software (Non-maskable interrupt)
    - Undefined instruction (UND instruction)
    - Overflow (INTO instruction)
    - BRK instruction
    - INT instruction
  - Hardware
    - Special (Non-maskable interrupt)
      - $\overline{\text{NMI}}$
      - $\overline{\text{DBC}}$ (2)
      - Watchdog timer
      - Oscillation stop and re-oscillation detection
      - Low voltage detection
      - Single step (2)
      - Address match
    - Peripheral function (1) (Maskable interrupt)

NOTES:
1. Peripheral function interrupts are generated by the MCU's internal functions.
2. Do not normally use this interrupt because it is provided exclusively for use by development tools.

Figure 9.1 Interrupts

- Maskable Interrupt: An interrupt which can be enabled (disabled) by the interrupt enable flag (I flag) or whose interrupt priority **can be changed** by priority level.
- Non-maskable Interrupt: An interrupt which cannot be enabled (disabled) by the interrupt enable flag (I flag) or whose interrupt priority **cannot be changed** by priority level.

9.1.1 Software Interrupts

A software interrupt occurs when executing certain instructions. Software interrupts are non-maskable interrupts.

9.1.1.1 Undefined Instruction Interrupt

An undefined instruction interrupt occurs when executing the UND instruction.

9.1.1.2 Overflow Interrupt

An overflow interrupt occurs when executing the INTO instruction with the O flag set to 1 (the operation resulted in an overflow). The following are instructions whose O flag changes by arithmetic: ABS, ADC, ADCF, ADD, CMP, DIV, DIVU, DIVX, NEG, RMPA, SBB, SHA, SUB

9.1.1.3 BRK Interrupt

A BRK interrupt occurs when executing the BRK instruction.

9.1.1.4 INT Instruction Interrupt

An INT instruction interrupt occurs when executing the INT instruction. Software interrupt Nos. 0 to 63 can be specified for the INT instruction. Because software interrupt Nos. 1 to 31 are assigned to peripheral function interrupts, the same interrupt routine as for peripheral function interrupts can be executed by executing the INT instruction.

In software interrupt Nos. 0 to 31, the U flag is saved to the stack during instruction execution and is cleared to 0 (ISP selected) before executing an interrupt sequence. The U flag is restored from the stack when returning from the interrupt routine. In software interrupt Nos. 32 to 63, the U flag does not change state during instruction execution, and the SP then selected is used.

9.1.2 Hardware Interrupts

Hardware interrupts are classified into two types — special interrupts and peripheral function interrupts.

9.1.2.1 Special Interrupts

Special interrupts are non-maskable interrupts.

9.1.2.1.1 $\overline{\text{NMI}}$ Interrupt

An $\overline{\text{NMI}}$ interrupt is generated when input on the $\overline{\text{NMI}}$ pin changes state from high to low. For details about the $\overline{\text{NMI}}$ interrupt, refer to the section "NMI interrupt".

9.1.2.1.2 $\overline{\text{DBC}}$ Interrupt

This interrupt is exclusively for debugger, do not use in any other circumstances.

9.1.2.1.3 Watchdog Timer Interrupt

Generated by the watchdog timer. Once a watchdog timer interrupt is generated, be sure to initialize the watchdog timer. For details about the watchdog timer, refer to the section "watchdog timer".

9.1.2.1.4 Oscillation Stop and Re-oscillation Detection Interrupt

Generated by the oscillation stop and re-oscillation detection function. For details about the oscillation stop and re-oscillation detection function, refer to the section "clock generating circuit".

9.1.2.1.5 Low Voltage Detection Interrupt

Generated by the voltage detection circuit. For details about the voltage detection circuit, refer to the section "voltage detection circuit".

9.1.2.1.6 Single-step Interrupt

Do not normally use this interrupt because it is provided exclusively for use by development tools.

9.1.2.1.7 Address Match Interrupt

An address match interrupt is generated immediately before executing the instruction at the address indicated by the RMAD0 or RMAD1 register, if the corresponding enable bit (AIER0 or AIER1 bit in the AIER register) is set to 1. For details about the address match interrupt, refer to the section “address match interrupt”.

9.1.2.2 Peripheral Function Interrupts

Peripheral function interrupts are maskable interrupts and generated by the MCU's internal functions. The interrupt sources for peripheral function interrupts are listed in **Table 9.2** Relocatable Vector Tables. For details about the peripheral functions, refer to the description of each peripheral function in this manual.

9.2 Interrupts and Interrupt Vector

One interrupt vector consists of 4 bytes. Set the start address of each interrupt routine in the respective interrupt vectors. When an interrupt request is accepted, the CPU branches to the address set in the corresponding interrupt vector. **Figure 9.2** shows the interrupt vector.

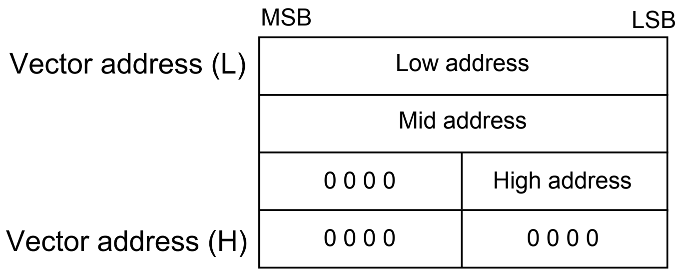


Figure 9.2 Interrupt Vector

9.2.1 Fixed Vector Tables

The fixed vector tables are allocated to the addresses from $FFFDC_{16}$ to $FFFFF_{16}$. **Table 9.1** lists the fixed vector tables. In the flash memory version of MCU, the vector addresses (H) of fixed vectors are used by the ID code check function. For details, refer to the section "flash memory rewrite disabling function".

Table 9.1 Fixed Vector Tables

Interrupt source	Vector table addresses Address (L) to address (H)	Remarks	Reference
Undefined instruction	$FFFDC_{16}$ to $FFFDF_{16}$	Interrupt on UND instruction	M16C/60, M16C/20 serise software maual
Overflow	$FFFE0_{16}$ to $FFFE3_{16}$	Interrupt on INTO instruction	
BRK instruction	$FFFE4_{16}$ to $FFFE7_{16}$	If the contents of address $FFFE7_{16}$ is FF_{16}, program execution starts from the address shown by the vector in the relocatable vector table	
Address match	$FFFE8_{16}$ to $FFFEB_{16}$		Address match interrupt
Single step (1)	$FFFEC_{16}$ to $FFFEF_{16}$		
Watchdog timer Oscillation stop and re-oscillation detection, low voltage detection	$FFFF0_{16}$ to $FFFF3_{16}$		Watchdog timer, clock generating circuit, voltage detection circuit
$\overline{\text{DBC}}$ (1)	$FFFF4_{16}$ to $FFFF7_{16}$		
$\overline{\text{NMI}}$	$FFFF8_{16}$ to $FFFFB_{16}$		$\overline{\text{NMI}}$ interrupt
Reset(2)	$FFFFC_{16}$ to $FFFFF_{16}$		Reset

NOTE:

1. Do not normally use this interrupt because it is provided exclusively for use by development tools.

9.2.2 Relocatable Vector Tables

The 256 bytes beginning with the start address set in the INTB register comprise a reloacatable vector table area. **Table 9.2** lists the relocatable vector tables. Setting an even address in the INTB register results in the interrupt sequence being executed faster than in the case of odd addresses.

Table 9.2 Relocatable Vector Tables

Interrupt source	Vector address (1) Address (L) to address (H)	Software interrupt number	Reference
BRK instruction (2)	+0 to +3 (0000_{16} to 0003_{16})	0	M16C/60, M16C/20 series software manual
CAN0 wakeup (3)	+4 to +7 (0004_{16} to 0007_{16})	1	CAN module
CAN0 receive completion	+8 to +11 (0008_{16} to $000B_{16}$)	2	
CAN0 transmit completion	+12 to +15 ($000C_{16}$ to $000F_{16}$)	3	
$\overline{INT3}$	+16 to +19 (0010_{16} to 0013_{16})	4	$\overline{INT}$ interrupt
IC/OC interrupt 0	+20 to +23 (0014_{16} to 0017_{16})	5	Timer S
IC/OC interrupt 1, I^{2}C bus interface (4)	+24 to +27 (0018_{16} to $001B_{16}$)	6	Timer S Multi-Master I^{2}C bus interface
IC/OC base timer, S_{CL}/S_{DA} (4)	+28 to +31 ($001C_{16}$ to $001F_{16}$)	7	
SI/O4, $\overline{INT5}$ (5)	+32 to +35 (0020_{16} to 0023_{16})	8	$\overline{INT}$ interrupt
SI/O3, $\overline{INT4}$ (5)	+36 to +39 (0024_{16} to 0027_{16})	9	Serial I/O
UART 2 bus collision detection (6)	+40 to +43 (0028_{16} to $002B_{16}$)	10	Serial I/O
DMA0	+44 to +47 ($002C_{16}$ to $002F_{16}$)	11	DMAC
DMA1	+48 to +51 (0030_{16} to 0033_{16})	12	
CAN0 state, error	+52 to +55 (0034_{16} to 0037_{16})	13	CAN module
A/D, Key input interrupt (7)	+56 to +59 (0038_{16} to $003B_{16}$)	14	A/D convertor, Key input interrupt
UART2 transmit, NACK2 (8)	+60 to +63 ($003C_{16}$ to $003F_{16}$)	15	Serial I/O
UART2 receive, ACK2 (8)	+64 to +67 (0040_{16} to 0043_{16})	16	
UART0 transmit	+68 to +71 (0044_{16} to 0047_{16})	17	
UART0 receive	+72 to +75 (0048_{16} to $004B_{16}$)	18	
UART1 transmit	+76 to +79 ($004C_{16}$ to $004F_{16}$)	19	
UART1 receive	+80 to +83 (0050_{16} to 0053_{16})	20	
Timer A0	+84 to +87 (0054_{16} to 0057_{16})	21	Timer
Timer A1	+88 to +91 (0058_{16} to $005B_{16}$)	22	
Timer A2	+92 to +95 ($005C_{16}$ to $005F_{16}$)	23	
Timer A3	+96 to +99 (0060_{16} to 0063_{16})	24	
Timer A4	+100 to +103 (0064_{16} to 0067_{16})	25	
Timer B0	+104 to +107 (0068_{16} to $006B_{16}$)	26	
Timer B1	+108 to +111 ($006C_{16}$ to $006F_{16}$)	27	
Timer B2	+112 to +115 (0070_{16} to 0073_{16})	28	
$\overline{INT0}$	+116 to +119 (0074_{16} to 0077_{16})	29	$\overline{INT}$ interrupt
$\overline{INT1}$	+120 to +123 (0078_{16} to $007B_{16}$)	30	
$\overline{INT2}$	+124 to +127 ($007C_{16}$ to $007F_{16}$)	31	
Software interrupt (2)	+128 to +131 (0080_{16} to 0083_{16}) to +252 to +255 ($00FC_{16}$ to $00FF_{16}$)	32 to 63	M16C/60, M16C/20 series software manual

NOTES:
1. Address relative to address in INTB.
2. These interrupts cannot be disabled using the I flag.
3. Set the IFSR22 bit in the IFSR register to 0.
4. Use bits IFSR26 and IFSR27 in the IFSR2A register to select.
5. Use bits IFSR6 and IFSR7 in the IFSR register to select.
6. Bus collision detection: In IEBus mode, this bus collision detection constitutes the cause of an interrupt. In I^{2}C bus mode, however, a start condition or a stop condition detection constitutes the cause of an interrupt.
7. Use the IFSR21 bit in the IFSR2A register to select.
8. During I^{2}C bus mode, NACK and ACK interrupts comprise the interrupt source.

9.3 Interrupt Control

The following describes how to enable/disable the maskable interrupts, and how to set the priority in which order they are accepted. What is explained here does not apply to nonmaskable interrupts.
Use I flag in the the FLG register, IPL, and bits ILVL2 to ILVL0 in the each interrupt control register to enable/disable the maskable interrupts. Whether an interrupt is requested is indicated by the IR bit in each interrupt control register.
Figure 9.3 shows the interrupt control registers.

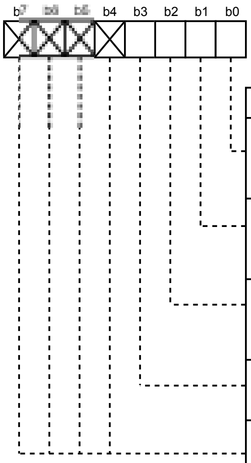
Also, the following interrupts share a vector and an interrupt control register.

- $\overline{\text{INT4}}$ and SIO3
- $\overline{\text{INT5}}$ and SIO4
- A/D converter and key input interrupt
- IC/OC base timer and SCL/SDA
- IC/OC interrupt 1 and I^2C bus interface

An interrupt request is set by bits IFSR6 and IFSR7 in the IFSR register and bits IFSR27, IFSR26, and IFSR21 in the IFSR2A register. **Figure 9.4** shows registers IFSR register and IFSR2A.

Interrupt Control Register(2)

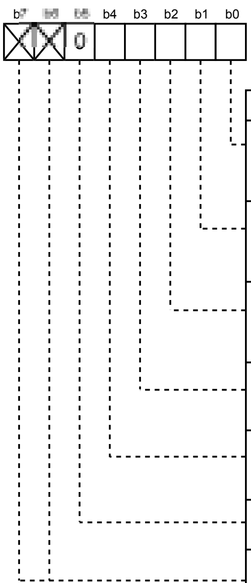
Symbol	Address	After reset
C01WKIC	0041_{16}	$XXXXX000_2$
C0RECIC	0042_{16}	$XXXXX000_2$
C0TRMIC	0043_{16}	$XXXXX000_2$
ICOC0IC	0045_{16}	$XXXXX000_2$
ICOC1IC, IICIC(3)	0046_{16}	$XXXXX000_2$
BTIC, SCLDAIC(3)	0047_{16}	$XXXXX000_2$
BCNIC	$004A_{16}$	$XXXXX000_2$
DM0IC, DM1IC	$004B_{16}$, $004C_{16}$	$XXXXX000_2$
C01ERRIC	$004D_{16}$	$XXXXX000_2$
ADIC, KUPIC(3)	$004E_{16}$	$XXXXX000_2$
S0TIC to S2TIC	0051_{16}, 0053_{16}, $004F_{16}$	$XXXXX000_2$
S0RIC to S2RIC	0052_{16}, 0054_{16}, 0050_{16}	$XXXXX000_2$
TA0IC to TA4IC	0055_{16} to 0059_{16}	$XXXXX000_2$
TB0IC to TB2IC	$005A_{16}$ to $005C_{16}$	$XXXXX000_2$



Bit Symbol	Bit Name	Function	RW
ILVL0	Interrupt priority level select bit	b2 b1 b0 0 0 0 : Level 0 (interrupt disabled) 0 0 1 : Level 1 0 1 0 : Level 2 0 1 1 : Level 3 1 0 0 : Level 4 1 0 1 : Level 5 1 1 0 : Level 6 1 1 1 : Level 7	RW
ILVL1			RW
ILVL2			RW
IR	Interrupt request bit	0: Interrupt not requested 1: Interrupt requested	RW(1)
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the contents are undefined		—

NOTES:
1. This bit can only be reset by writing 0 (Do not write 1).
2. To rewrite the interrupt control registers, do so at a point that does not generate the interrupt request for that register. For details, refer to **22. 4 Interrupts**.
3. Use the IFSR2A register to select.

Symbol	Address	After reset
INT3IC	0044_{16}	$XX00X000_2$
S4IC, INT5IC	0048_{16}	$XX00X000_2$
S3IC, INT4IC	0049_{16}	$XX00X000_2$
INT0IC to INT2IC	$005D_{16}$ to $005F_{16}$	$XX00X000_2$



Bit Symbol	Bit Name	Function	RW
ILVL0	Interrupt priority level select bit	b2 b1 b0 0 0 0 : Level 0 (interrupt disabled) 0 0 1 : Level 1 0 1 0 : Level 2 0 1 1 : Level 3 1 0 0 : Level 4 1 0 1 : Level 5 1 1 0 : Level 6 1 1 1 : Level 7	RW
ILVL1			RW
ILVL2			RW
IR	Interrupt request bit	0: Interrupt not requested 1: Interrupt requested	RW(1)
POL	Polarity select bit	0: Selects falling edge (3, 4) 1: Selects rising edge	RW
— (b5)	Reserved bit	Set to 0	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the contents are undefined		—

NOTES:
1. This bit can only be reset by writing 0 (Do not write 1).
2. To rewrite the interrupt control register, do so at a point that does not generate the interrupt request for that register. For details, refer to **22.4 Interrupts**.
3. If the IFSRi bit in the IFSR register (i = 0 to 5) is 1 (both edges), set the POL bit in the INTiIC register to 0 (falling edge).
4. Set the POL bit in register S3IC or S4IC to 0 (falling edge) when the IFSR6 bit in the IFSR register is set to 0 (SI/O3 selected) or IFSR7 bit in the IFSR register to 0 (SI/O4 selected), respectively.

Figure 9.3 Interrupt Control Registers

Interrupt Request Cause Select Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: IFSR — Address: 035F16 — After Reset: 0016

Bit Symbol	Bit Name	Function	RW
IFSR0	INT0 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR1	INT1 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR2	INT2 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR3	INT3 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR4	INT4 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR5	INT5 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR6	Interrupt request cause select bit	0 : SI/O3 (2) 1 : INT4	RW
IFSR7	Interrupt request cause select bit	0 : SI/O4 (2) 1 : INT5	RW

NOTES:
1. When setting this bit to 1 (both edges), make sure the POL bit in registers INT0IC to INT5IC is set to 0 (falling edge).
2. When setting this bit to 0 (SI/O3, SI/O4), make sure the POL bit in registers S3IC and S4IC is set to 0 (falling edge).

Interrupt Request Cause Select Register 2

b7 b6 b5 b4 b3 b2 b1 b0 (b0 = 0)

Symbol: IFSR2A — Address: 035E16 — After reset: 00XXX0002

Bit Symbol	Bit Name	Function	RW
IFSR20	Reserved bit	Set to 0	RW
IFSR21	Interrupt request cause select bit	0: A/D conversion 1: Key input	RW
IFSR22	Interrupt request cause select bit	0: CAN0 wakeup/error 1: Do not set	RW
— (b5-b3)	Nothing is assigned. If necessary, set to 0. When read, the contents are undefined		—
IFSR26	Interrupt request cause select bit	0: IC/OC base timer 1: SCL/SDA	RW
IFSR27	Interrupt request cause select bit	0: IC/OC interrupt 1 1: I2C bus interface	RW

Figure 9.4 IFSR Register and IFSR2A Register

9.3.1 I Flag

The I flag enables or disables the maskable interrupt. Setting the I flag to 1 (= enabled) enables the maskable interrupt. Setting the I flag to 0 (= disabled) disables all maskable interrupts.

9.3.2 IR Bit

The IR bit is set to 1 (= interrupt requested) when an interrupt request is generated. Then, when the interrupt request is accepted and the CPU branches to the corresponding interrupt vector, the IR bit is cleared to 0 (= interrupt not requested).
The IR bit can be cleared to 0 in a program. Note that do not write 1 to this bit.

9.3.3 ILVL2 to ILVL0 Bits and IPL

Interrupt priority levels can be set using bits ILVL2 to ILVL0.
Table 9.3 shows the settings of interrupt priority levels and **Table 9.4** shows the interrupt priority levels enabled by the IPL.

The following are conditions under which an interrupt is accepted:
· I flag = 1
· IR bit = 1
· interrupt priority level > IPL

The I flag, IR bit, bits ILVL2 to ILVL0, and IPL are independent of each other. In no case do they affect one another.

Table 9.3 Settings of Interrupt Priority Levels

ILVL2 to ILVL0 bits	Interrupt priority level	Priority order
000_2	Level 0 (interrupt disabled)	———
001_2	Level 1	Low
010_2	Level 2	↓
011_2	Level 3	↓
100_2	Level 4	↓
101_2	Level 5	↓
110_2	Level 6	↓
111_2	Level 7	High

Table 9.4 Interrupt Priority Levels Enabled by IPL

IPL	Enabled interrupt priority levels
000_2	Interrupt levels 1 and above are enabled
001_2	Interrupt levels 2 and above are enabled
010_2	Interrupt levels 3 and above are enabled
011_2	Interrupt levels 4 and above are enabled
100_2	Interrupt levels 5 and above are enabled
101_2	Interrupt levels 6 and above are enabled
110_2	Interrupt levels 7 and above are enabled
111_2	All maskable interrupts are disabled

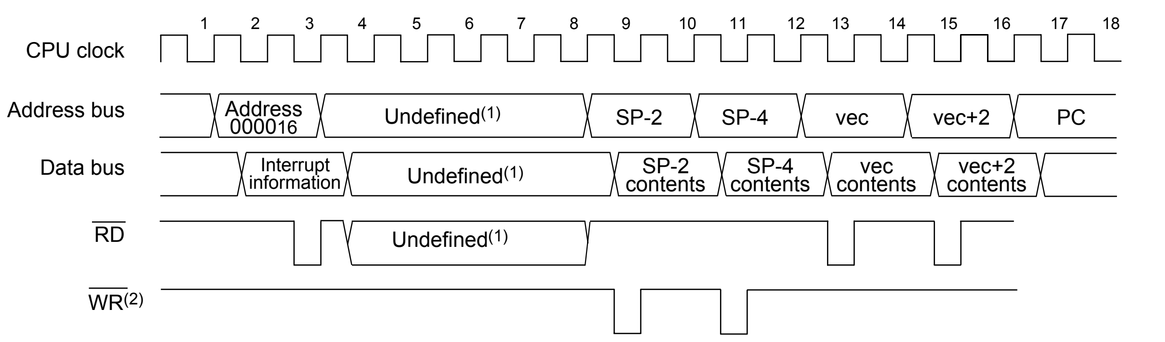
9.4 Interrupt Sequence

An interrupt sequence (the device behavior from the instant an interrupt is accepted to the instant the interrupt routine is executed) is described here.
If an interrupt occurs during execution of an instruction, the processor determines its priority when the execution of the instruction is completed, and transfers control to the interrupt sequence from the next cycle. If an interrupt occurs during execution of either the SMOVB, SMOVF, SSTR or RMPA instruction, the processor temporarily suspends the instruction being executed, and transfers control to the interrupt sequence.
The CPU behavior during the interrupt sequence is described below. **Figure 9.5** shows time required for executing the interrupt sequence.

(1) The CPU gets interrupt information (interrupt number and interrupt request priority level) by reading the address 00000_{16}. Then it clears the IR bit for the corresponding interrupt to 0 (interrupt not requested).
(2) The FLG register immediately before entering the interrupt sequence is saved to the CPU's internal temporary register(Note).
(3) The I, D and U flags in the FLG register become as follows:
The I flag is cleared to 0 (interrupts disabled).
The D flag is cleared to 0 (single-step interrupt disabled).
The U flag is cleared to 0 (ISP selected).
However, the U flag does not change state if an INT instruction for software interrupt Nos. 32 to 63 is executed.
(4) The CPU's internal temporary register(1) is saved to the stack.
(5) The PC is saved to the stack.
(6) The interrupt priority level of the accepted interrupt is set in the IPL.
(7) The start address of the relevant interrupt routine set in the interrupt vector is stored in the PC.

After the interrupt sequence is completed, the processor resumes executing instructions from the start address of the interrupt routine.

NOTE:
1. This register cannot be used by user.

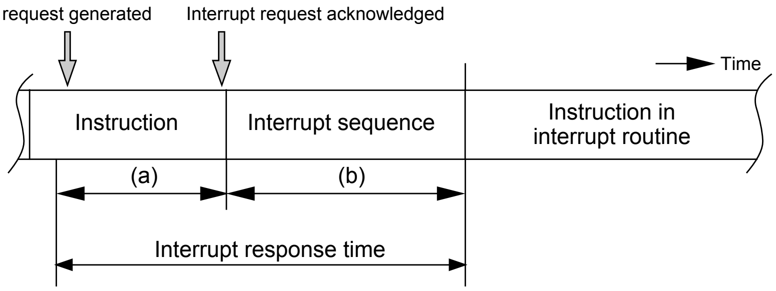


NOTES:
1. The undefined state depends on the instruction queue buffer. A read cycle occurs when the instruction queue buffer is ready to accept instructions.
2. When the stack is in the internal RAM, the WR signal indicates the write timing by changing high-level to low-level.

Figure 9.5 Time Required for Executing Interrupt Sequence

9.4.1 Interrupt Response Time

Figure 9.6 shows the interrupt response time. The interrupt response or interrupt acknowledge time denotes time from when an interrupt request is generated till when the first instruction in the interrupt routine is executed. Specifically, it consists of the time from when an interrupt request is generated till when the instruction then executing is completed ((a) in **Figure 9.6**) and the time during which the interrupt sequence is executed ((b) in **Figure 9.6**).



(a) The time from when an interrupt request is generated till when the instruction then executing is completed. The length of this time varies with the instruction being executed. The DIVX instruction requires the longest time, which is equal to 30 cycles (without wait state, the divisor being a register).

(b) The time during which the interrupt sequence is executed. For details, see the table below. Note, however, that the values in this table must be increased 2 cycles for the $\overline{\text{DBC}}$ interrupt and 1 cycle for the address match and single-step interrupts.

Interrupt vector address	SP value	Without wait
Even	Even	18 cycles
Even	Odd	19 cycles
Odd	Even	19 cycles
Odd	Odd	20 cycles

Figure 9.6 Interrupt response time

9.4.2 Variation of IPL when Interrupt Request is Accepted

When a maskable interrupt request is accepted, the interrupt priority level of the accepted interrupt is set in the IPL.

When a software interrupt or special interrupt request is accepted, one of the interrupt priority levels listed in **Table 9.5** is set in the IPL. Shown in **Table 9.5** are the IPL values of software and special interrupts when they are accepted.

Table 9.5 IPL Level That is Set to IPL When A Software or Special Interrupt Is Accepted

Interrupt sources	IPL setting
Watchdog timer, $\overline{\text{NMI}}$, Oscillation stop and re-oscillation detection, Low volage detection	7
Software, address match, $\overline{\text{DBC}}$, single-step	No change

9.4.3 Saving Registers

In the interrupt sequence, the FLG register and PC are saved to the stack.

At this time, the 4 high-order bits of the PC and the 4 high-order (IPL) and 8 low-order bits of the FLG register, 16 bits in total, are saved to the stack first. Next, the 16 low-order bits of the PC are saved. **Figure 9.7** shows the stack status before and after an interrupt request is accepted.

The other necessary registers must be saved in a program at the beginning of the interrupt routine. Use the PUSHM instruction, and all registers except SP can be saved with a single instruction.

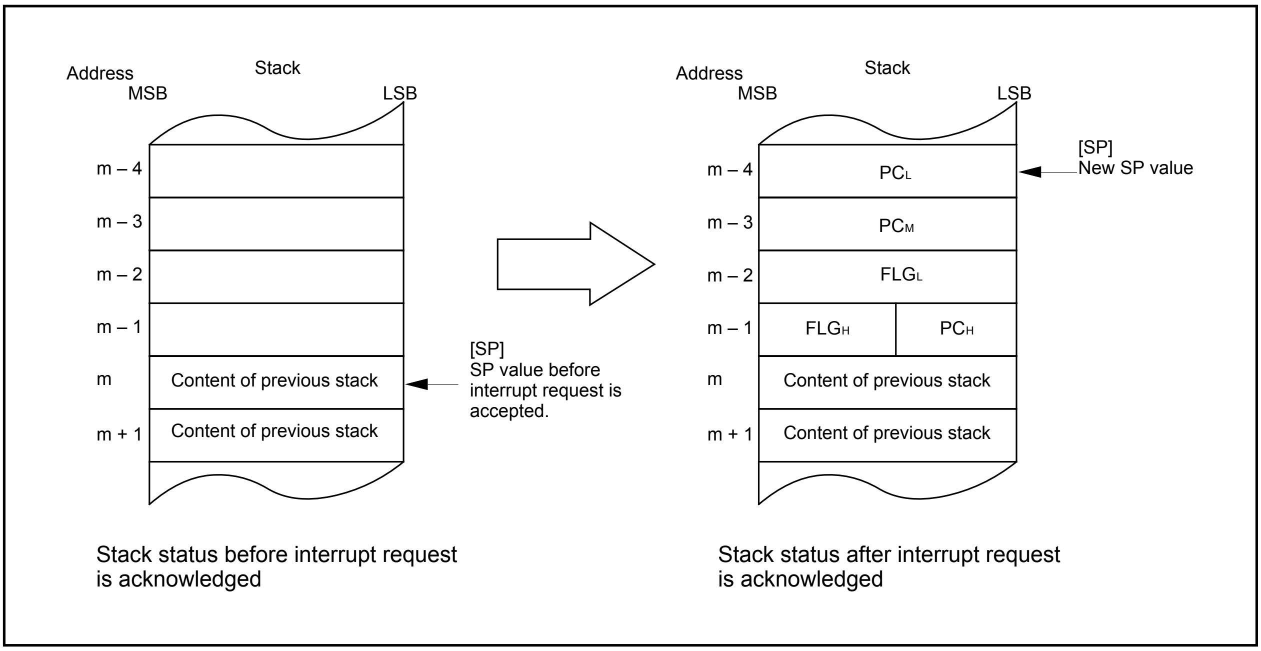
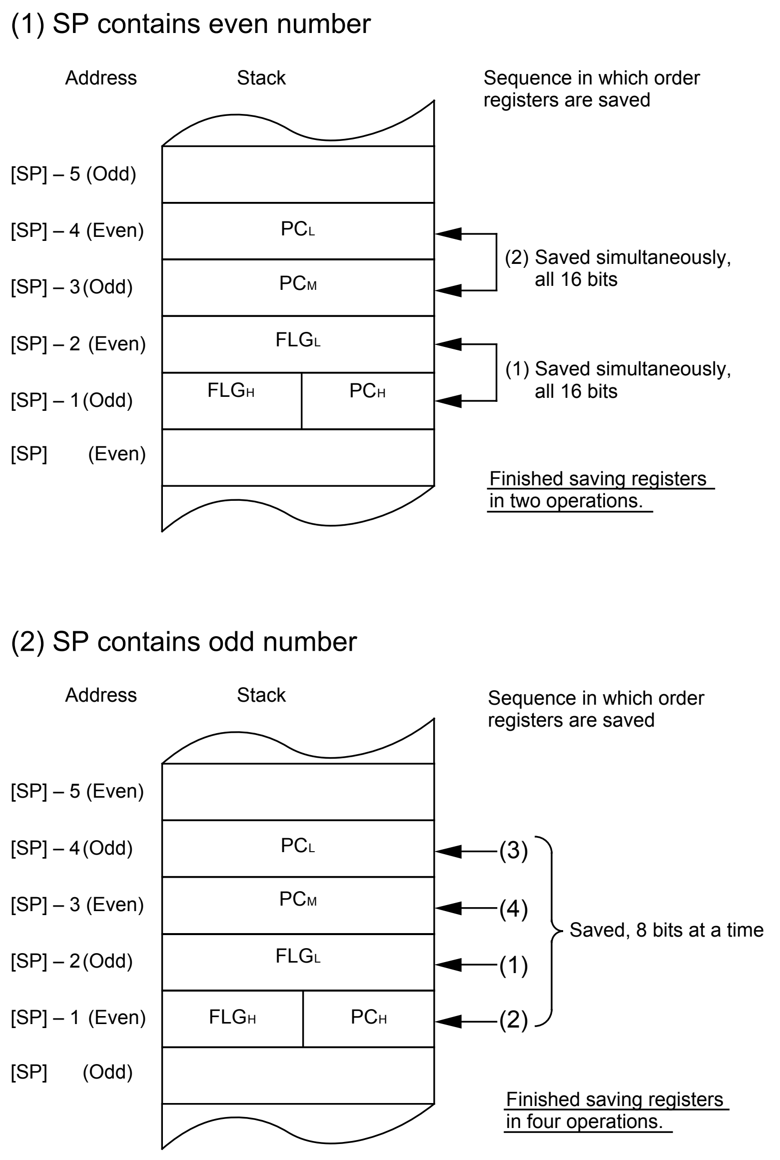


Figure 9.7 Stack Status Before and After Acceptance of Interrupt Request

The operation of saving registers carried out in the interrupt sequence is dependent on whether the SP(1), at the time of acceptance of an interrupt request, is even or odd. If the stack pointer (1) is even, the FLG register and the PC are saved, 16 bits at a time. If odd, they are saved in two steps, 8 bits at a time. **Figure 9.8** shows the operation of the saving registers.

NOTE:
1. When any INT instruction in software numbers 32 to 63 has been executed, this is the SP indicated by the U flag. Otherwise, it is the ISP.



NOTE:
1. [SP] denotes the initial value of the SP when interrupt request is acknowledged. After registers are saved, the SP content is [SP] minus 4.

Figure 9.8 Operation of Saving Register

9.4.4 Returning from an Interrupt Routine

The FLG register and PC in the state in which they were immediately before entering the interrupt sequence are restored from the stack by executing the REIT instruction at the end of the interrupt routine. Thereafter the CPU returns to the program which was being executed before accepting the interrupt request.

Return the other registers saved by a program within the interrupt routine using the POPM or similar instruction before executing the REIT instruction.

9.5 Interrupt Priority

If two or more interrupt requests are generated while executing one instruction, the interrupt request that has the highest priority is accepted.

For maskable interrupts (peripheral functions), any desired priority level can be selected using bits ILVL2 to ILVL0. However, if two or more maskable interrupts have the same priority level, their interrupt priority is resolved by hardware, with the highest priority interrupt accepted.

The watchdog timer and other special interrupts have their priority levels set in hardware. **Figure 9.9** shows the priorities of hardware interrupts.

Software interrupts are not affected by the interrupt priority. If an instruction is executed, control branches invariably to the interrupt routine.

Reset	High
$\overline{\text{NMI}}$	
$\overline{\text{DBC}}$	
Watchdog timer, oscillation stop, re-oscillation detection, low voltage detection	
Peripheral function	
Single step	
Address match	Low

Figure 9.9 Hardware Interrupt Priority

9.5.1 Interrupt Priority Resolution Circuit

The interrupt priority resolution circuit is used to select the interrupt with the highest priority among those requested.

Figure 9.10 shows the circuit that judges the interrupt priority level.

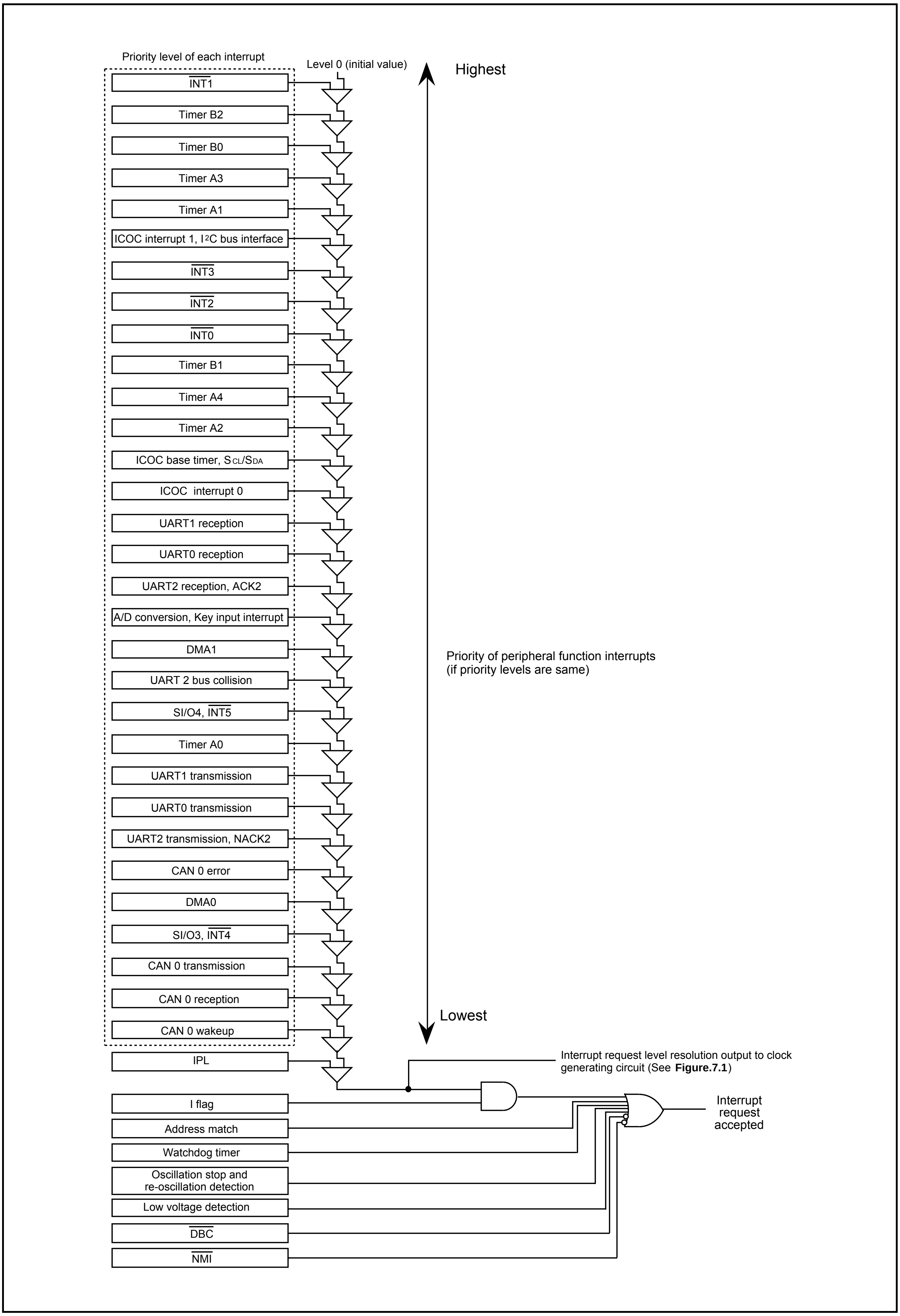


Figure 9.10 Interrupts Priority Select Circuit

9.6 $\overline{\mathrm{INT}}$ Interrupt

$\overline{\mathrm{INTi}}$ interrupt (i=0 to 5) is triggered by the edges of external inputs. The edge polarity is selected using the IFSRi bit in the IFSR register.

The $\overline{\mathrm{INT5}}$ input has an effective digital debounce function for a noise rejection. Refer to "**19.6 Digital Debounce function**" for this detail. When using $\overline{\mathrm{INT5}}$ interrupt to exit stop mode, set the P17DDR register to FF_{16} before entering stop mode.

To use the $\overline{\mathrm{INT4}}$ interrupt, set the IFSR6 bit in the IFSR register to 1 ($\overline{\mathrm{INT4}}$). To use the $\overline{\mathrm{INT5}}$ interrupt, set the IFSR7 bit in the IFSR register to 1 ($\overline{\mathrm{INT5}}$).

After modifiying bit IFSR6 or IFSR7, clear the corresponding IR bit to 0 (interrupt not requested) before enabling the interrupt.

Figure 9.11 shows the IFSR registers.

Interrupt Request Cause Select Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
IFSR	$035F_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
IFSR0	INT0 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR1	INT1 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR2	INT2 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR3	INT3 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR4	INT4 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR5	INT5 interrupt polarity switching bit	0 : One edge 1 : Both edges (1)	RW
IFSR6	Interrupt request cause select bit	0 : SI/O3 (2) 1 : $\overline{\mathrm{INT4}}$	RW
IFSR7	Interrupt request cause select bit	0 : SI/O4 (2) 1 : $\overline{\mathrm{INT5}}$	RW

NOTES:
1. When setting this bit to 1 (both edges), make sure the POL bit in registers INT0IC to INT5IC is set to 0 (falling edge).
2. When setting this bit to 0 (SI/O3, SI/O4), make sure the POL bit in registers S3IC and S4IC is set to 0 (falling edge).

Figure 9.11 IFSR Register

9.7 $\overline{\text{NMI}}$ Interrupt

An $\overline{\text{NMI}}$ interrupt request is generated when input on the $\overline{\text{NMI}}$ pin changes state from high to low, after the $\overline{\text{NMI}}$ interrupt was enabled by writing a 1 to bit 4 in the register PM2. The $\overline{\text{NMI}}$ interrupt is a non-maskable interrupt, once it is enabled.

The input level of this $\overline{\text{NMI}}$ interrupt input pin can be read by accessing the P8_5 bit in the P8 register.

$\overline{\text{NMI}}$ is disabled by default after reset (the pin is a GPIO pin, $P8_5$) and can be enabled using bit 4 in the PM2 register. Once enabled, it can only be disabled by a reset signal.

The $\overline{\text{NMI}}$ input has a digital debounce function for noise rejection. Refer to "**19.6 Digital Debounce function**" for details. When using $\overline{\text{NMI}}$ interrupt to exit stop mode, set the NDDR register to FF_{16} before entering stop mode.

9.8 Key Input Interrupt

A key input interrupt is generated when input on any of the $P10_4$ to $P10_7$ pins which has had bits PD10_7 to PD10_4 in the PD10 register set to 0 (= input) goes low. Key input interrupts can be used for a key-on wakeup function to get the MCU to exit stop or wait modes. However, if you intend to use the key input interrupt, do not use $P10_4$ to $P10_7$ as analog input ports. **Figure 9.12** shows the block diagram of the key input interrupt. Note, however, that while input on any pin which has had bits PD10_7 to PD10_4 set to 0 (= input mode) is pulled low, inputs on all other pins of the port are not detected as interrupts.

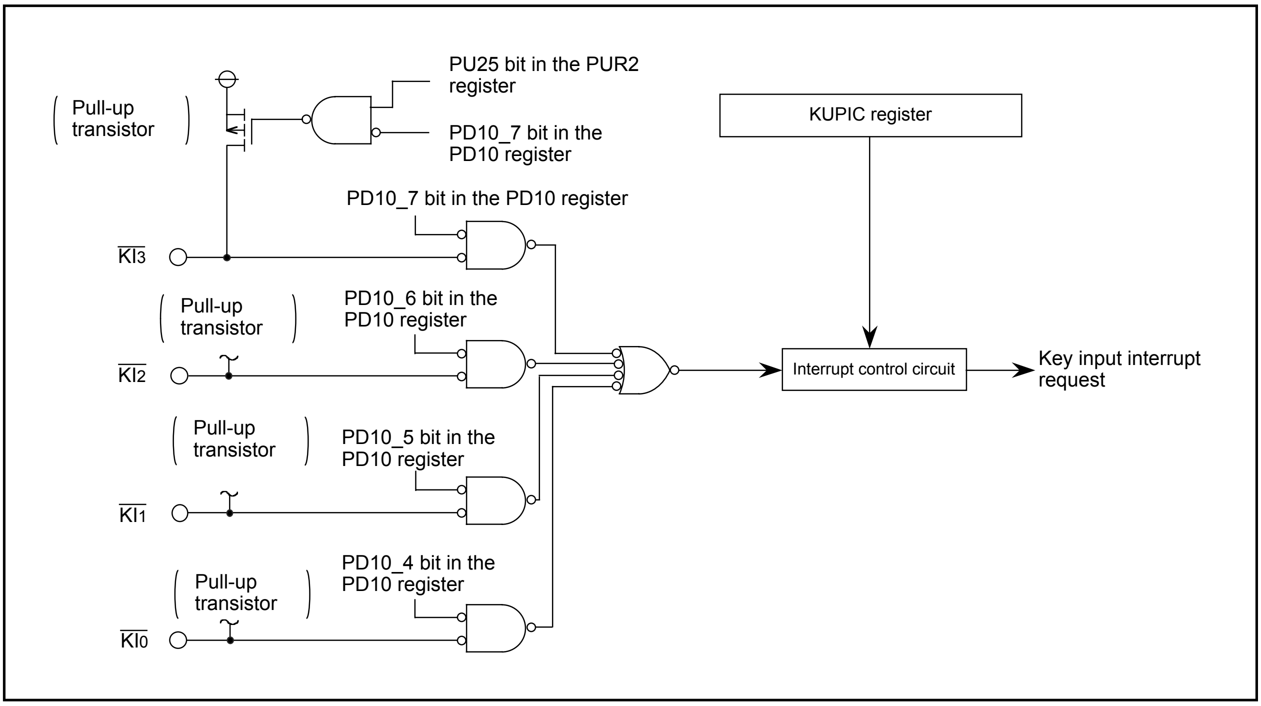


Figure 9.12 Key Input Interrupt

9.9 CAN0 Wake-up Interrupt

CAN0 wake-up interrupt occurs when a falling edge is input to CRX. The CAN0 wake-up interrupt is enabled when the PortEn bit is set to 1 (CTX/CRX function) and Sleep bit is set to 1(Sleep mode enabled) in the C0CTLR register. **Figure 9.13** shows the block diagram of the CAN0 wake-up interrupt.

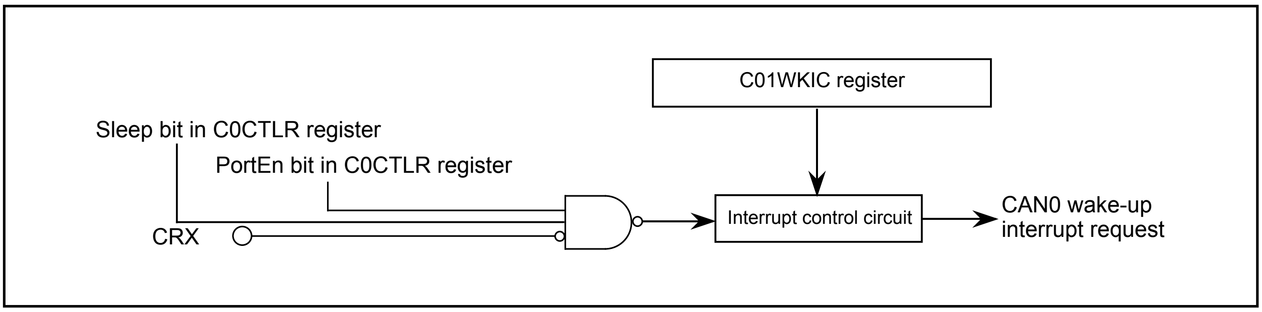


Figure 9.13 CAN0 Wake-up Interrupt Block Diagram

9.10 Address Match Interrupt

An address match interrupt request is generated immediately before executing the instruction at the address indicated by the RMADi register (i=0 to 1). Set the start address of any instruction in the RMADi register. Use bits AIER1 and AIER0 in the AIER register to enable or disable the interrupt. Note that the address match interrupt is unaffected by the I flag and IPL. For address match interrupts, the value of the PC that is saved to the stack area varies depending on the instruction being executed (refer to "**Saving Registers**").

(The value of the PC that is saved to the stack area is not the correct return address.) Therefore, follow one of the methods described below to return from the address match interrupt.

• Rewrite the content of the stack and then use the REIT instruction to return.

• Restore the stack to its previous state before the interrupt request was accepted by using the POP or similar other instruction and then use a jump instruction to return.

Table 9.6 shows the value of the PC that is saved to the stack area when an address match interrupt request is accepted.

aFigure 9.14 shows registers AIER, RMAD0, and RMAD1.

Table 9.6 PC Value Saved in Stack Area When Address Match Interrupt Request Is Acknowledged

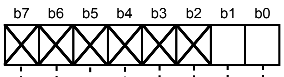
Instruction at the address indicated by the RMADi register	Value of the PC that is saved to the stack area
• 2-byte op-code instruction • 1-byte op-code instructions which are followed: ADD.B:S #IMM8,dest SUB.B:S #IMM8,dest AND.B:S #IMM8,dest OR.B:S #IMM8,dest MOV.B:S #IMM8,dest STZ.B #IMM8,dest STNZ.B #IMM8,dest STZX.B #IMM81,#IMM82,dest CMP.B:S #IMM8,dest PUSHM src POPM dest JMPS #IMM8 JSRS #IMM8 MOV.B:S #IMM,dest (However, dest=A0 or A1)	The address indicated by the RMADi register +2
Instructions other than the above	The address indicated by the RMADi register +1

Value of the PC that is saved to the stack area : Refer to “Saving Registers”.
Op-code is an abbreviation of Operation Code. It is a portion of instruction code.
Refer to Chapter 4 Instruction Code/Number of Cycles in M16C/60, M16C/20 Series Software Manual. Op-code is shown as a bold-framed figure directly below the Syntax.

Table 9.7 Relationship Between Address Match Interrupt Sources and Associated Registers

Address match interrupt sources	Address match interrupt enable bit	Address match interrupt register
Address match interrupt 0	AIER0	RMAD0
Address match interrupt 1	AIER1	RMAD1

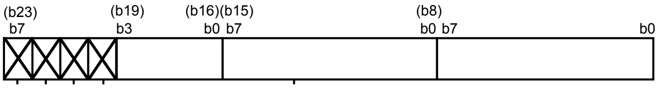
Address Match Interrupt Enable Register



Symbol	Address	After Reset
AIER	0009$_{16}$	XXXXXX00$_2$

Bit Symbol	Bit Name	Function	RW
AIER0	Address match interrupt 0 enable bit	0 : Interrupt disabled 1 : Interrupt enabled	RW
AIER1	Address match interrupt 1 enable bit	0 : Interrupt disabled 1 : Interrupt enabled	RW
— (b7-b2)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

Address Match Interrupt Register i (i = 0 to 1)



Symbol	Address	After Reset
RMAD0	0012$_{16}$ to 0010$_{16}$	X00000$_{16}$
RMAD1	0016$_{16}$ to 0014$_{16}$	X00000$_{16}$

Function	Setting Range	RW
Address setting register for address match interrupt	00000$_{16}$ to FFFFF$_{16}$	RW
Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

Figure 9.14 AIER Register, RMAD0 and RMAD1 Registers

10. Watchdog Timer

The watchdog timer is the function of detecting when the program is out of control. Therefore, we recommend using the watchdog timer to improve reliability of a system. The watchdog timer contains a 15-bit counter which counts down the clock derived by dividing the CPU clock using the prescaler. Whether to generate a watchdog timer interrupt request or apply a watchdog timer reset as an operation to be performed when the watchdog timer underflows after reaching the terminal count can be selected using the PM12 bit in the PM1 register. The PM12 bit can only be set to 1 (reset). Once this bit is set to 1, it cannot be set to 0 (watchdog timer interrupt) in a program. Refer to **5.3 Watchdog Timer Reset** for the details of watchdog timer reset.

When the main clock source is selected for CPU clock, on-chip oscillator clock, PLL clock, the WDC7 bit in the WDC register value for prescaler can be chosen to be 16 or 128. If a sub-clock is selected for CPU clock, the prescaler is always 2 no matter how the WDC7 bit is set. The period of watchdog timer can be calculated as given below. The period of watchdog timer is, however, subject to an error due to the prescaler.

With main clock source chosen for CPU clock, on-chip oscillator clock, PLL clock

$$\text{Watchdog timer period} = \frac{\text{Prescaler dividing (16 or 128) X Watchdog timer count (32768)}}{\text{CPU clock}}$$

With sub-clock chosen for CPU clock

$$\text{Watchdog timer period} = \frac{\text{Prescaler dividing (2) X Watchdog timer count (32768)}}{\text{CPU clock}}$$

For example, when CPU clock is set to 16 MHz and the divide-by-N value for the prescale ris set to 16, the watchdog timer period is approx. 32.8 ms.

The watchdog timer is initialized by writing to the WDTS register. The prescaler is initialized after reset. Note that the watchdog timer and the prescaler both are inactive after reset, so that the watchdog timer is activated to start counting by writing to the WDTS register.

Write the WDTS register with shorter cycle than the watchdog timer cycle. Set the WDTS register also in the beginning of the watchdog timer interrupt routine.

In stop mode and wait mode, the watchdog timer and prescaler are stopped. Counting is resumed from the held value when the modes or state are released.

Figure 10.1 shows the block diagram of the watchdog timer. Figure 10.2 shows the watchdog timer-related registers.

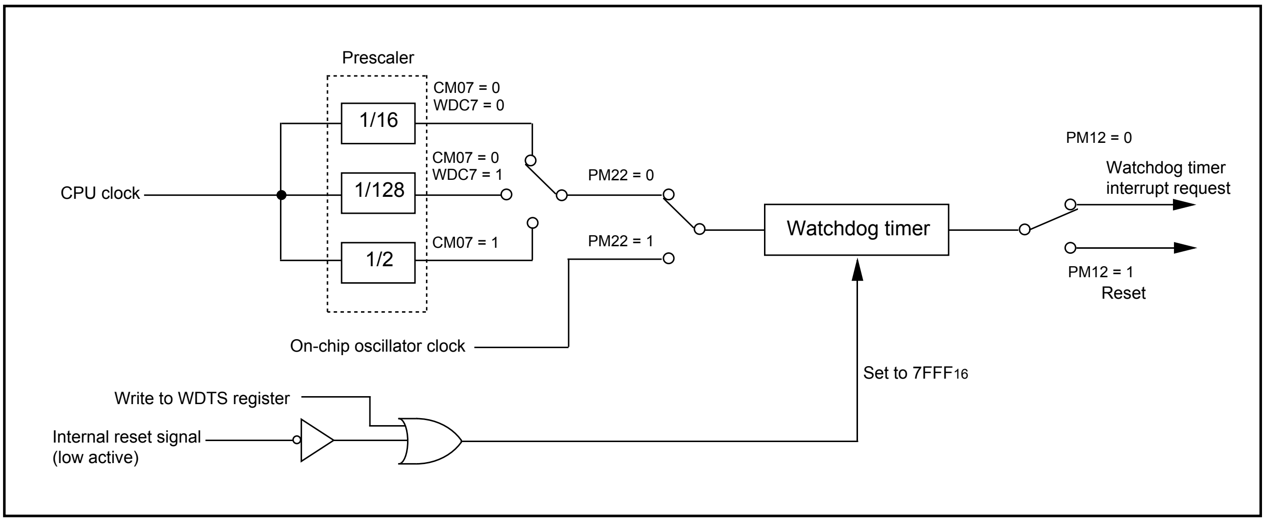


Figure 10.1 Watchdog Timer Block Diagram

Watchdog Timer Control Register

b7	b6	b5	b4	b3	b2	b1	b0
	0	0					

Symbol WDC — Address $000F_{16}$ — After Reset $00XXXXXX_2$

Bit Symbol	Bit Name	Function	RW
(b4-b0)	High-order bits of watchdog timer		RO
(b5)	Reserved bit	Set to 0	RW
(b6)	Reserved bit	Set to 0	RW
WDC7	Prescaler select bit	0 : Divided by 16 1 : Divided by 128	RW

Watchdog Timer Start Register

b7 … b0

Symbol WDTS — Address $000E_{16}$ — After Reset Undefined

Function	RW
The watchdog timer is initialized and starts counting after a write instruction to this register. The watchdog timer value is always initialized to $7FFF_{16}$ regardless of whatever value is written.	WO

Figure 10.2 WDC Register and WDTS Register

10.1 Count Source Protective Mode

In this mode, a on-chip oscillator clock is used for the watchdog timer count source. The watchdog timer can be kept being clocked even when CPU clock stops as a result of run-away.

Before this mode can be used, the following register settings are required:

(1) Set the PRC1 bit in the PRCR register to 1 (enable writes to PM1 and PM2 registers).

(2) Set the PM12 bit in the PM1 register to 1 (reset when the watchdog timer underflows).

(3) Set the PM22 bit in the PM2 register to 1 (on-chip oscillator clock used for the watchdog timer count source).

(4) Set the PRC1 bit in the PRCR register to 0 (disable writes to PM1 and PM2 registers).

(5) Write to the WDTS register (watchdog timer starts counting).

Setting the PM22 bit to 1 results in the following conditions

• The on-chip oscillator continues oscillating even if the CM21 bit in the CM2 register is set to "0" (main clock or PLL clock) (system clock of count source selected by the CM21 bit is valid)

• The on-chip oscillator starts oscillating, and the on-chip oscillator clock becomes the watchdog timer count source.

$$\text{Watchdog timer period} = \frac{\text{Watchdog timer count (32768)}}{\text{on-chip oscillator clock}}$$

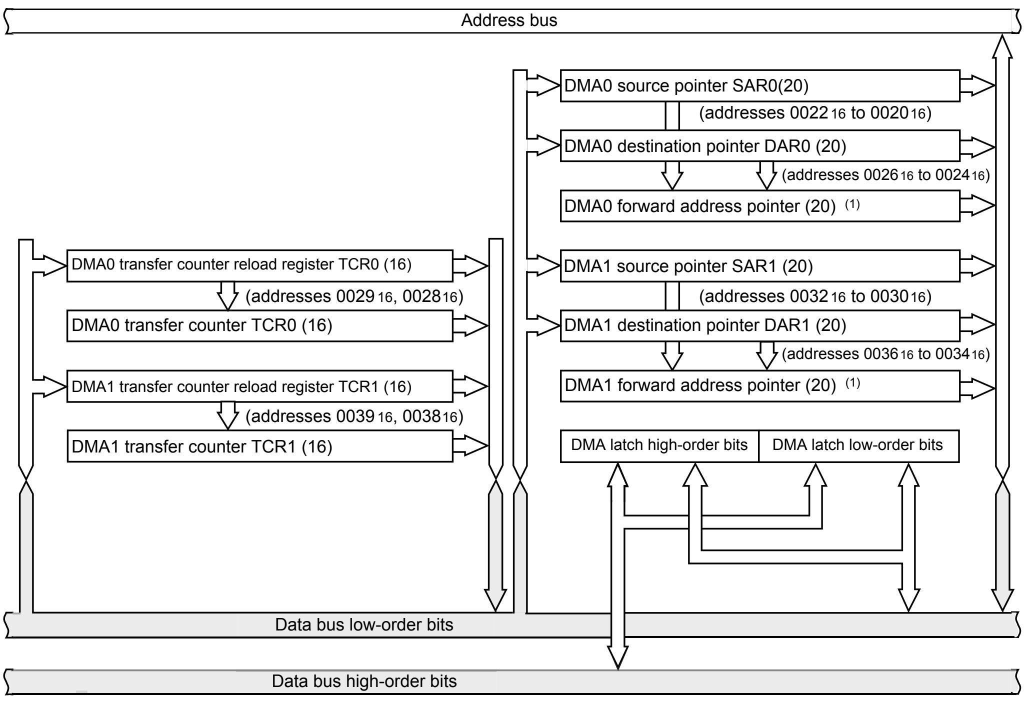
• The CM10 bit in the CM1 register is disabled against write. (Writing a 1 has no effect, nor is stop mode entered.)

• The watchdog timer does not stop when in wait mode.

11. DMAC

Note
Do not use SI/O4 interrupt request as a DMA request in the 64-pin package.

The DMAC (Direct Memory Access Controller) allows data to be transferred without the CPU intervention. Two DMAC channels are included. Each time a DMA request occurs, the DMAC transfers one (8 or 16-bit) data from the source address to the destination address. The DMAC uses the same data bus as used by the CPU. Because the DMAC has higher priority of bus control than the CPU and because it makes use of a cycle steal method, it can transfer one word (16 bits) or one byte (8 bits) of data within a very short time after a DMA request is generated. **Figure 11.1** shows the block diagram of the DMAC. **Table 11.1** shows the DMAC specifications. **Figures 11.2** to **11.4** show the DMAC-related registers.



NOTE:
1. Pointer is incremented by a DMA request.

Figure 11.1 DMAC Block Diagram

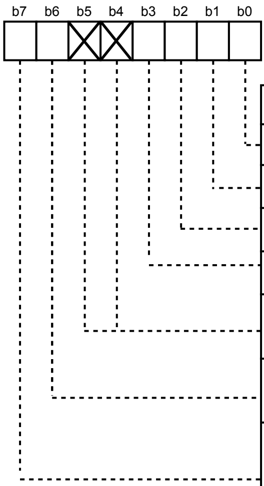
A DMA request is generated by a write to the DSR bit in the DMiSL register (i = 0,1), as well as by an interrupt request which is generated by any function specified by the DMS and bits DSEL3 to DSEL0 in the DMiSL register. However, unlike in the case of interrupt requests, DMA requests are not affected by the I flag and the interrupt control register, so that even when interrupt requests are disabled and no interrupt request can be accepted, DMA requests are always accepted. Furthermore, because the DMAC does not affect interrupts, the IR bit in the interrupt control register does not change state due to a DMA transfer.
A data transfer is initiated each time a DMA request is generated when the DMAE bit in the DMiCON register is set to 1 (DMA enabled). However, if the cycle in which a DMA request is generated is faster than the DMA transfer cycle, the number of transfer requests generated and the number of times data is transferred may not match. For details, refer to “DMA Requests”.

Table 11.1 DMAC Specifications

Item		Specification
No. of channels		2 (cycle steal method)
Transfer memory space		• From any address in the 1M bytes space to a fixed address • From a fixed address to any address in the 1M bytes space • From a fixed address to a fixed address
Maximum No. of bytes transferred		128K bytes (with 16-bit transfers) or 64K bytes (with 8-bit transfers)
DMA request factors (1, 2)		Falling edge of $\overline{\text{INT0}}$ or $\overline{\text{INT1}}$ Both edge of $\overline{\text{INT0}}$ or $\overline{\text{INT1}}$ Timer A0 to timer A4 interrupt requests Timer B0 to timer B2 interrupt requests UART0 transfer, UART0 reception interrupt requests UART1 transfer, UART1 reception interrupt requests UART2 transfer, UART2 reception interrupt requests SI/O3, SI/O4 interrupt requests A/D conversion interrupt requests Timer S(IC/OC) requests Software triggers
Channel priority		DMA0 > DMA1 (DMA0 takes precedence)
Transfer unit		8 bits or 16 bits
Transfer address direction		forward or fixed (The source and destination addresses cannot both be in the forward direction)
Transfer mode	Single transfer	Transfer is completed when the DMAi transfer counter (i = 0,1) underflows after reaching the terminal count
	Repeat transfer	When the DMAi transfer counter underflows, it is reloaded with the value of the DMAi transfer counter reload register and a DMA transfer is con tinued with it
DMA interrupt request generation timing		When the DMAi transfer counter underflowed
DMA startup the		Data transfer is initiated each time a DMA request is generated when DMAE bit in the DMAiCON register = 1 (enabled)
DMA shutdown	Single transfer	• When the DMAE bit is set to 0 (disabled) • After the DMAi transfer counter underflows
	Repeat transfer	When the DMAE bit is set to 0 (disabled)
Reload timing for forward address pointer and transfer counter		When a data transfer is started after setting the DMAE bit to 1 (en abled), the forward address pointer is reloaded with the value of the SARi or the DARi pointer whichever is specified to be in the forward direction and the DMAi transfer counter is reloaded with the value of the DMAi transfer counter reload register

NOTES:
1. DMA transfer is not effective to any interrupt. DMA transfer is affected neither by the I flag nor by the interrupt control register.
2. The selectable causes of DMA requests differ with each channel.
3. Make sure that no DMAC-related registers (addresses 0020_{16} to $003F_{16}$) are accessed by the DMAC.

DMA0 Request Cause Select Register



Symbol DM0SL — Address $03B8_{16}$ — After Reset 00_{16}

Bit Symbol	Bit Name	Function	RW
DSEL0	DMA request cause select bit	Refer to note (1)	RW
DSEL1			RW
DSEL2			RW
DSEL3			RW
— (b5-b4)	Nothing is assigned. When write, set to 0. When read, their content are 0		—
DMS	DMA request cause expansion select bit	0: Basic cause of request 1: Extended cause of request	RW
DSR	Software DMA request bit	A DMA request is generated by setting this bit to 1 when the DMS bit is 0 (basic cause) and bits DSEL3 to DSEL0 are 0001_2 (software trigger). The value of this bit when read is 0	RW

NOTE:
1. The causes of DMA0 requests can be selected by a combination of DMS bit and bits DSEL3 to DSEL0 in the manner described below.

DSEL3 to DSEL0	DMS=0(basic cause of request)	DMS=1(extended cause of request)
0 0 0 0_2	Falling edge of $\overline{\text{INT0}}$ pin	IC/OC base timer
0 0 0 1_2	Software trigger	–
0 0 1 0_2	Timer A0	IC/OC channel 0
0 0 1 1_2	Timer A1	IC/OC channel 1
0 1 0 0_2	Timer A2	–
0 1 0 1_2	Timer A3	–
0 1 1 0_2	Timer A4	Two edges of $\overline{\text{INT0}}$ pin
0 1 1 1_2	Timer B0	–
1 0 0 0_2	Timer B1	–
1 0 0 1_2	Timer B2	–
1 0 1 0_2	UART0 transmit	IC/OC channel 2
1 0 1 1_2	UART0 receive	IC/OC channel 3
1 1 0 0_2	UART2 transmit	IC/OC channel 4
1 1 0 1_2	UART2 receive	IC/OC channel 5
1 1 1 0_2	A/D conversion	IC/OC channel 6
1 1 1 1_2	UART1 transmit	IC/OC channel 7

Figure 11.2 DM0SL Register

DMA1 Request Cause Select Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
DM1SL	03BA16	0016

Bit Symbol	Bit Name	Function	RW
DSEL0	DMA request cause select bit	Refer to note (1)	RW
DSEL1			RW
DSEL2			RW
DSEL3			RW
— (b5-b4)	Nothing is assigned. If necessary, set to 0. When read, their contents are 0		—
DMS	DMA request cause expansion select bit	0: Basic cause of request 1: Extended cause of request	RW
DSR	Software DMA request bit	A DMA request is generated by setting this bit to 1 when the DMS bit is 0 (basic cause) and the DSEL3 to DSEL0 bits are 00012 (software trigger). The value of this bit when read is 0	RW

NOTES:
1. The causes of DMA1 requests can be selected by a combination of DMS bit and bits DSEL3 to DSEL0 in the manner described below.

DSEL3 to DSEL0	DMS=0(basic cause of request)	DMS=1(extended cause of request)
0 0 0 02	Falling edge of INT1 pin	IC/OC base timer
0 0 0 12	Software trigger	–
0 0 1 02	Timer A0	IC/OC channel 0
0 0 1 12	Timer A1	IC/OC channel 1
0 1 0 02	Timer A2	–
0 1 0 12	Timer A3	SI/O3
0 1 1 02	Timer A4	SI/O4
0 1 1 12	Timer B0	Two edges of INT1
1 0 0 02	Timer B1	–
1 0 0 12	Timer B2	–
1 0 1 02	UART0 transmit	IC/OC channel 2
1 0 1 12	UART0 receive	IC/OC channel 3
1 1 0 02	UART2 transmit	IC/OC channel 4
1 1 0 12	UART2 receive/ACK2	IC/OC channel 5
1 1 1 02	A/D conversion	IC/OC channel 6
1 1 1 12	UART1 receive	IC/OC channel 7

DMAi Control Register(i=0,1)

b7 b6 b5 b4 b3 b2 b1 b0

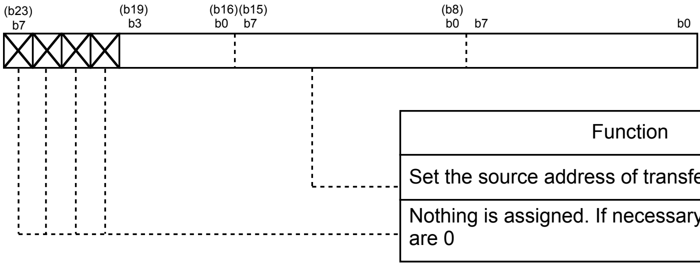
Symbol	Address	After Reset
DM0CON	002C16	00000X002
DM1CON	003C16	00000X002

Bit Symbol	Bit Name	Function	RW
DMBIT	Transfer unit bit select bit	0: 16 bits 1: 8 bits	RW
DMASL	Repeat transfer mode select bit	0: Single transfer 1: Repeat transfer	RW
DMAS	DMA request bit	0: DMA not requested 1: DMA requested	RW (1)
DMAE	DMA enable bit	0: Disabled 1: Enabled	RW
DSD	Source address direction select bit (2)	0: Fixed 1: Forward	RW
DAD	Destination address direction select bit (2)	0: Fixed 1: Forward	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, their contents are 0		—

NOTES:
1. The DMAS bit can be set to 0 by writing 0 by program (This bit remains unchanged even if 1 is written).
2. At least one of bits DAD and DSD must be set to 0 (address direction fixed).

Figure 11.3 DM1SL Register, DM0CON Register, and DM1CON Registers

DMAi Source Pointer (i = 0, 1) [1]

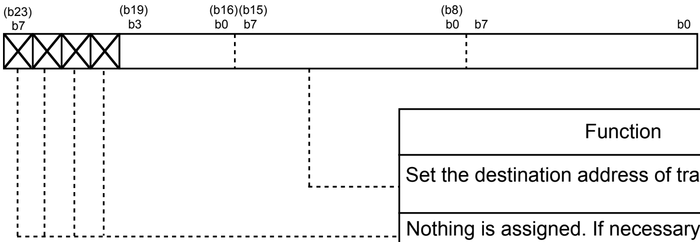


Symbol	Address	After Reset
SAR0	0022_{16} to 0020_{16}	Undefined
SAR1	0032_{16} to 0030_{16}	Undefined

Function	Setting Range	RW
Set the source address of transfer	00000_{16} to $FFFFF_{16}$	RW
Nothing is assigned. If necessary, set 0. When read, the contents are 0		—

NOTE:
1. If the DSD bit in the DMiCON register is 0 (fixed), this register can only be written to when the DMAE bit in the DMiCON register is set to 0 (DMA disabled).
If the DSD bit is set to 1 (forward direction), this register can be written to at any time.
If the DSD bit is set to 1 and the DMAE bit is set to 1 (DMA enabled), the DMAi forward address pointer can be read from this register. Otherwise, the value written to it can be read.

DMAi Destination Pointer (i = 0, 1)[1]

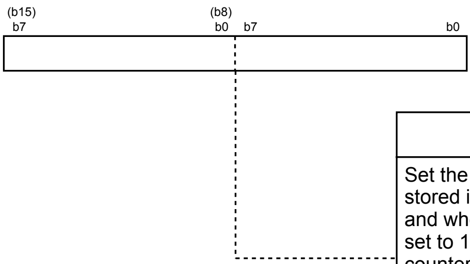


Symbol	Address	After Reset
DAR0	0026_{16} to 0024_{16}	Undefined
DAR1	0036_{16} to 0034_{16}	Undefined

Function	Setting Range	RW
Set the destination address of transfer	00000_{16} to $FFFFF_{16}$	RW
Nothing is assigned. If necessary, set 0. When read, the contents are 0		—

NOTE:
1. If the DAD bit in the DMiCON register is 0 (fixed), this register can only be written to when the DMAE bit in the DMiCON register is set to 0 (DMA disabled).
If the DAD bit is set to 1 (forward direction), this register can be written to at any time.
If the DAD bit is set to 1 and the DMAE bit is set to 1 (DMA enabled), the DMAi forward address pointer can be read from this register. Otherwise, the value written to it can be read.

DMAi Transfer Counter (i = 0, 1)



Symbol	Address	After Reset
TCR0	0029_{16}, 0028_{16}	Undefined
TCR1	0039_{16}, 0038_{16}	Undefined

Function	Setting Range	RW
Set the transfer count minus 1. The written value is stored in the DMAi transfer counter reload register, and when the DMAE bit in the DMiCON register is set to 1 (DMA enabled) or the DMAi transfer counter underflows when the DMASL bit in the DMiCON register is 1 (repeat transfer), the value of the DMAi transfer counter reload register is transferred to the DMAi transfer counter. When read, the DMAi transfer counter is read	0000_{16} to $FFFF_{16}$	RW

Figure 11.4 SAR0, SAR1, DAR0, DAR1, TCR0, and TCR1 Registers

11.1 Transfer Cycles

The transfer cycle consists of a memory or SFR read (source read) bus cycle and a write (destination write) bus cycle. The number of read and write bus cycles is affected by the source and destination addresses of transfer. Furthermore, the bus cycle itself is extended by a software wait.

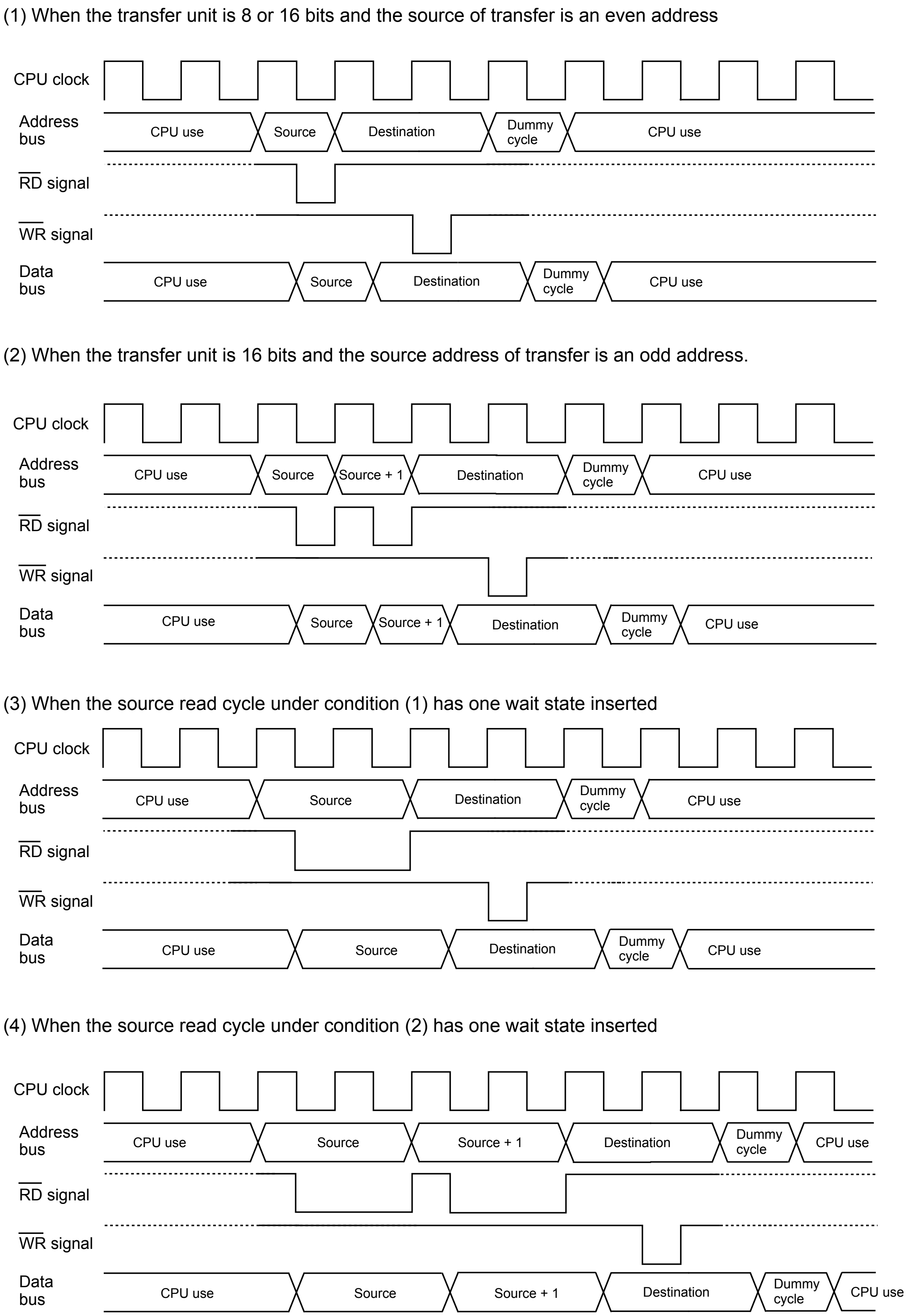
11.1.1 Effect of Source and Destination Addresses

If the transfer unit is 16 bits and the source address of transfer begins with an odd address, the source read cycle consists of one more bus cycle than when the source address of transfer begins with an even address.
Similarly, if the transfer unit is 16 bits and the destination address of transfer begins with an odd address, the destination write cycle consists of one more bus cycle than when the destination address of transfer begins with an even address.

11.1.2 Effect of Software Wait

For memory or SFR accesses in which one or more software wait states are inserted, the number of bus cycles required for that access increases by an amount equal to software wait states.

Figure 11.5 shows the example of the cycles for a source read. For convenience, the destination write cycle is shown as one cycle and the source read cycles for the different conditions are shown. In reality, the destination write cycle is subject to the same conditions as the source read cycle, with the transfer cycle changing accordingly. When calculating transfer cycles, take into consideration each condition for the source read and the destination write cycle, respectively. For example, when data is transferred in 16 bit units and when both the source address and destination address are an odd address ((2) in **Figure 11.5**), two source read bus cycles and two destination write bus cycles are required.



NOTE:
1. The same timing changes occur with the respective conditions at the destination as at the source.

Figure 11.5 Transfer Cycles for Source Read

11.2. DMA Transfer Cycles

Any combination of even or odd transfer read and write adresses is possible. **Table 11.2** shows the number of DMA transfer cycles. **Table 11.3** shows the Coefficient j, k.
The number of DMAC transfer cycles can be calculated as follows:

No. of transfer cycles per transfer unit = No. of read cycles x j + No. of write cycles x k

Table 11.2 DMA Transfer Cycles

Transfer unit	Access address	No. of read cycles	No. of write cycles
8-bit transfers (DMBIT= 1)	Even	1	1
	Odd	1	1
16-bit transfers (DMBIT= 0)	Even	1	1
	Odd	2	2

Table 11.3 Coefficient j, k

	Internal Area			
	Internal ROM, RAM		SFR	
	No wait	With wait	1 wait (1)	2 wait (1)
j	1	2	2	3
k	1	2	2	3

NOTE:
1. Depends on the set value of PM20 bit in PM2 register

11.3 DMA Enable

When a data transfer starts after setting the DMAE bit in the DMiCON register (i = 0, 1) to 1 (enabled), the DMAC operates as follows:

(a) Reload the forward address pointer with the SARi register value when the DSD bit in DMiCON register is 1 (forward) or the DARi register value when the DAD bit in the DMiCON register is 1 (forward).

(b) Reload the DMAi transfer counter with the DMAi transfer counter reload register value.

If the DMAE bit is set to 1 again while it remains set, the DMAC performs the above operation. However, if a DMA request may occur simultaneously when the DMAE bit is being written, follow the steps below.

(1) Write 1 to bits DMAE and DMAS in DMiCON register simultaneously.

(2) Make sure that the DMAi is in an initial state as described above (a) and (b) by program.

If the DMAi is not in an initial state, the above steps should be repeated.

11.4 DMA Request

The DMAC can generate a DMA request as triggered by the cause of request that is selected with the DMS bit and bits DSEL3 to DSEL0 in the DMiSL register (i = 0, 1) on either channel. **Table 11.4** shows the timing at which the DMAS bit changes state.

Whenever a DMA request is generated, the DMAS bit is set to 1 (DMA requested) regardless of whether or not the DMAE bit is set. If the DMAE bit was set to 1 (enabled) when this occurred, the DMAS bit is set to 0 (DMA not requested) immediately before a data transfer starts. This bit cannot be set to 1 by program (it can only be set to 0).

The DMAS bit may be set to 1 when the DMS or the DSEL3 to DSEL0 bits change state. Therefore, always be sure to set the DMAS bit to 0 after changing the DMS or the DSEL3 to DSEL0 bits.

Because if the DMAE bit is set to 1, a data transfer starts immediately after a DMA request is generated, the DMAS bit in almost all cases is 0 when read by program. Read the DMAE bit to determine whether the DMAC is enabled.

Table 11.4 Timing at Which the DMAS Bit Changes State

DMA Factor	DMAS Bit in the DMiCON Register	
	Timing at which the bit is set to 1	Timing at which the bit is set to 0
Software trigger	When the DSR bit in the DMiSL register is set to 1	• Immediately before a data transfer starts • When set by writing 0 by program
Peripheral function	When the interrupt control register for the peripheral function that is selected by bits DSEL3 to DSEL0 and the DMS bit in the DMiSL register has its IR bit set to 1	

11.5 Channel Priority and DMA Transfer Timing

If both DMA0 and DMA1 are enabled and DMA transfer request signals from DMA0 and DMA1 are detected active in the same sampling period (one period from a falling edge to the next falling edge of CPU clock), the DMAS bit on each channel is set to 1 (DMA requested) at the same time. In this case, the DMA requests are arbitrated according to the channel priority, DMA0 > DMA1. The following describes DMAC operation when DMA0 and DMA1 requests are detected active in the same sampling period. **Figure 11.6** shows an example of DMA transfer effected by external factors.

DMA0 request having priority is received first to start a transfer when a DMA0 request and DMA1 request are generated simultanelously. After one DMA0 transfer is completed, a bus arbitration is returned to the CPU. When the CPU has completed one bus access, a DMA1 transfer starts. After one DMA1 transfer is completed, the bus arbitration is again returned to the CPU.

In addition, DMA requsts cannot be counted up since each channel has one DMAS bit. Therefore, when DMA requests, as DMA1 in **Figure 11.6** occurs more than one time, the DAMS bit is set to 0 as soon as getting the bus arbitration. The bus arbitration is returned to the CPU when one transfer is completed.

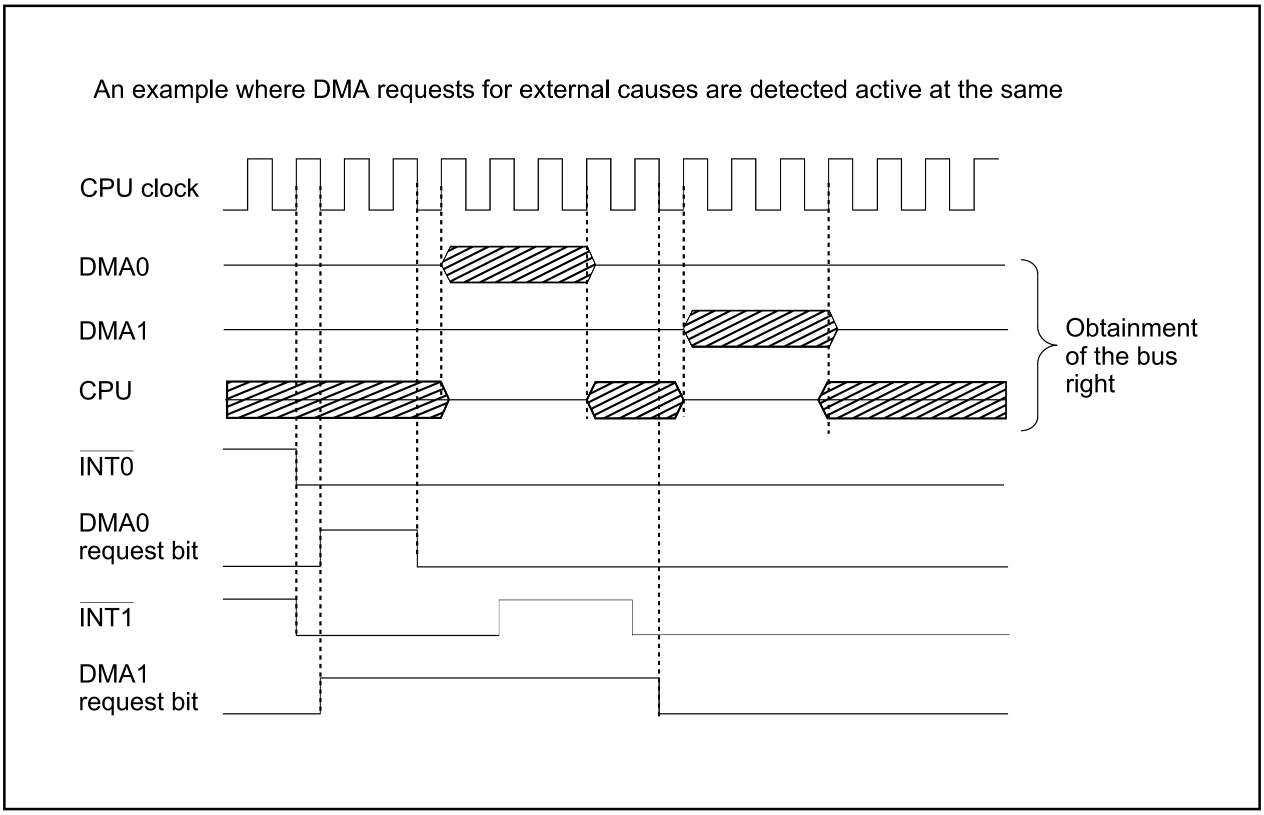


Figure 11.6 DMA Transfer by External Factors

12. Timers

Eight 16-bit timers, each capable of operating independently of the others, can be classified by function as either timer A (five) and timer B (three). The count source for each timer acts as a clock, to control such timer operations as counting, reloading, etc. **Figures 12.1** and **12.2** show block diagrams of timer A and timer B configuration, respectively.

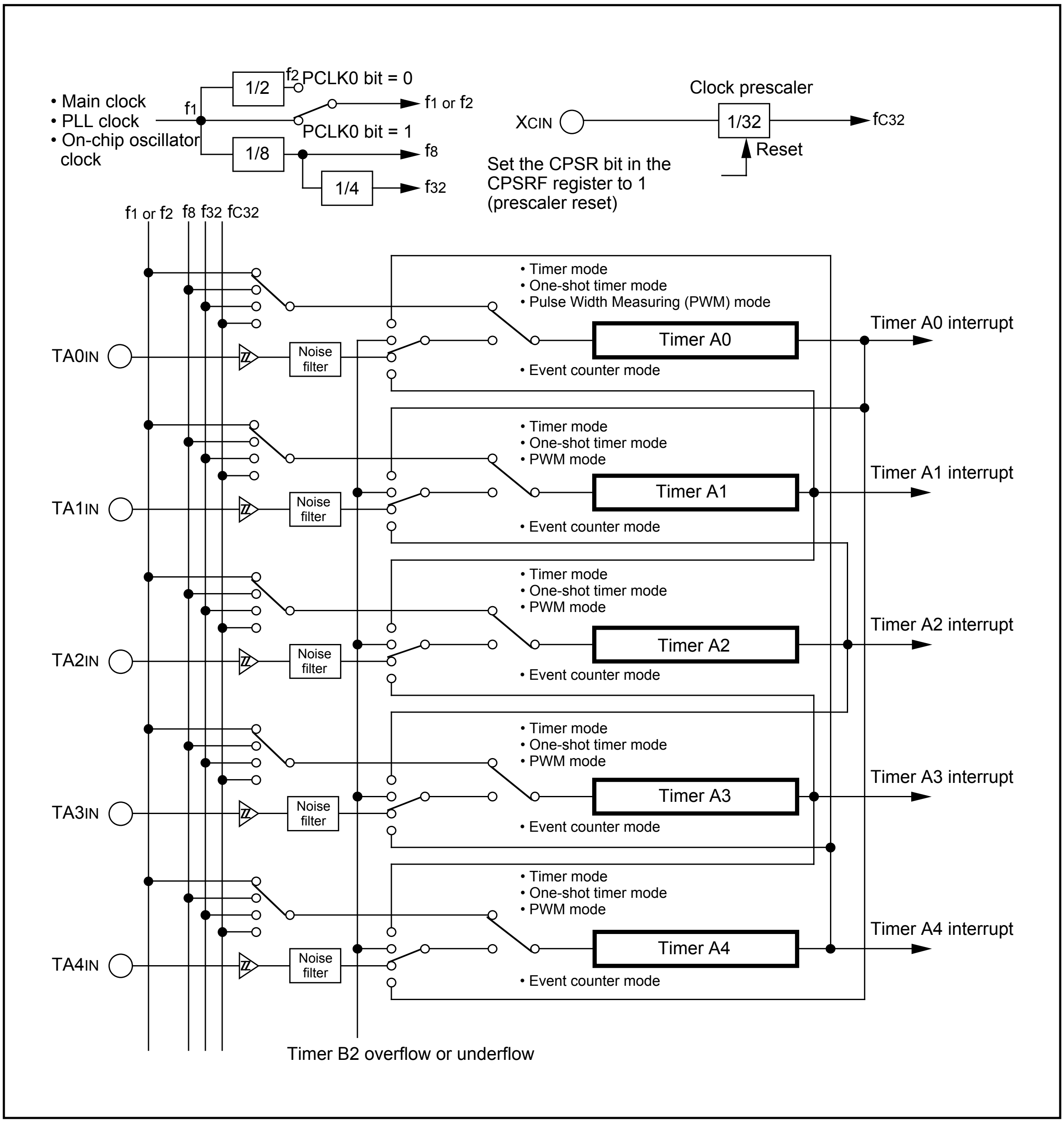


Figure 12.1 Timer A Configuration

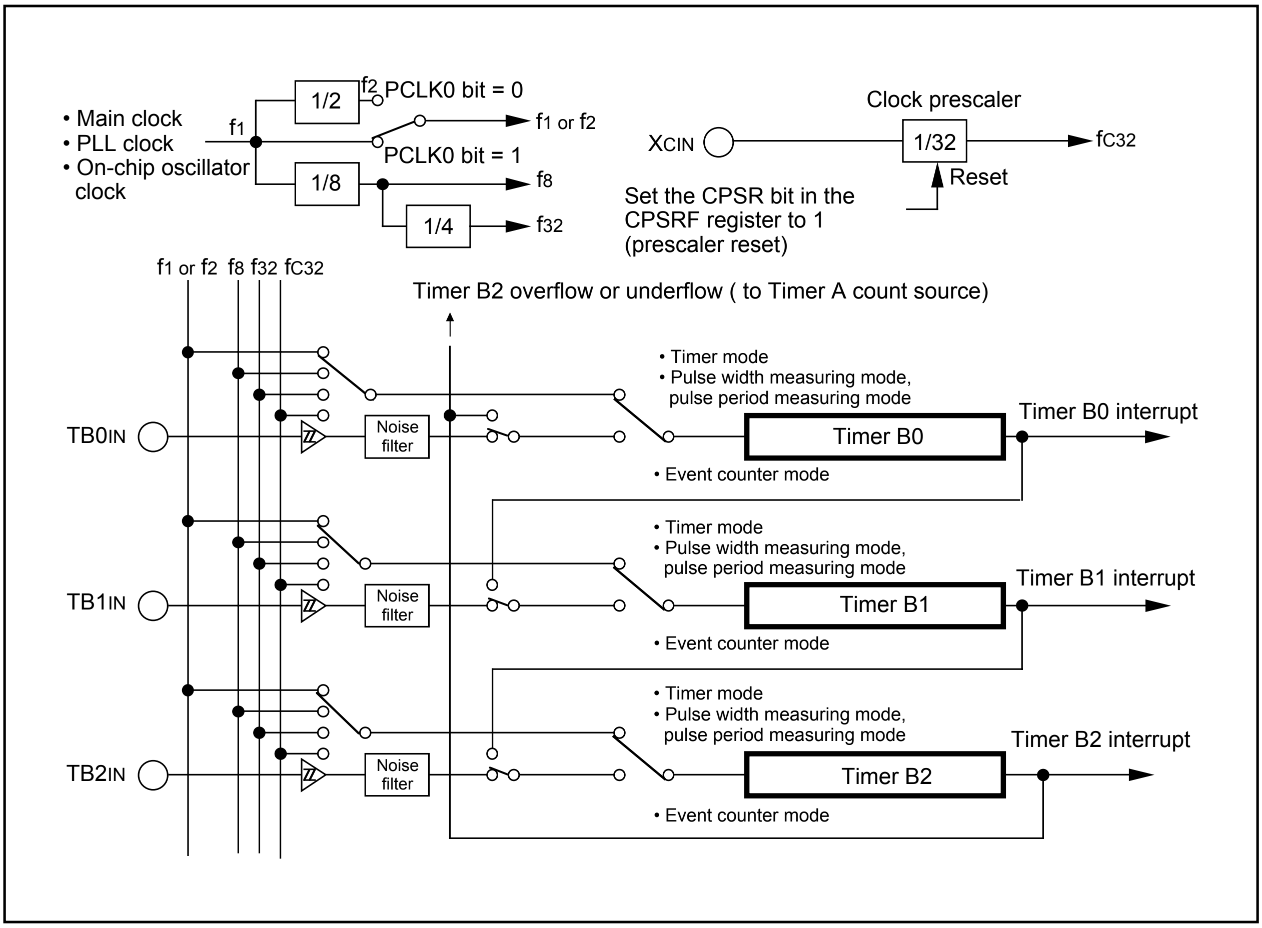


Figure 12.2. Timer B Configuration

12.1 Timer A

Figure 12.3 shows a block diagram of the timer A. **Figures 12.4** to **12.6** show registers related to the timer A. The timer A supports the following four modes. Except in event counter mode, timers A0 to A4 all have the same function. Use bits TMOD1 to TMOD0 in the TAiMR register (i = 0 to 4) to select the desired mode.

- Timer mode: The timer counts an internal count source.
- Event counter mode: The timer counts pulses from an external device or overflows and underflows of other timers.
- One-shot timer mode: The timer outputs a pulse only once before it reaches the minimum count 0000_{16}.
- Pulse width modulation (PWM) mode: The timer outputs pulses in a given width successively.

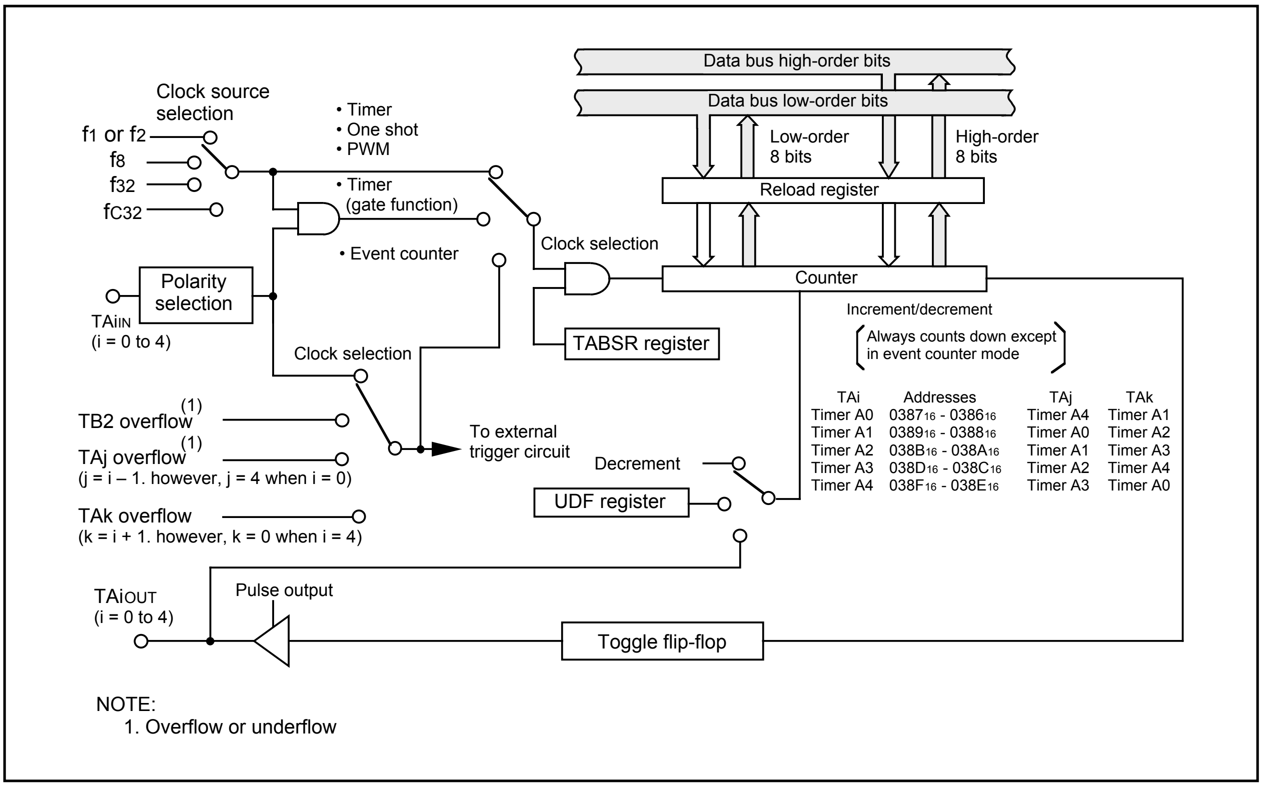


Figure 12.3 Timer A Block Diagram

Timer Ai Mode Register (i=0 to 4)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TA0MR to TA4MR	0396_{16} to $039A_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 0 : Timer mode 0 1 : Event counter mode 1 0 : One-shot timer mode 1 1 : Pulse width modulation (PWM) mode	RW
TMOD1			RW
MR0	————	Function varies with each operation mode	RW
MR1			RW
MR2			RW
MR3			RW
TCK0	Count source select bit	Function varies with each operation mode	RW
TCK1			RW

Figure 12.4 TA0MR to TA4MR Registers

Timer Ai Register (i= 0 to 4) (1)

(b15) b7 (b8) b0 b7 b0

Symbol	Address	After Reset
TA0	0387_{16}, 0386_{16}	Undefined
TA1	0389_{16}, 0388_{16}	Undefined
TA2	$038B_{16}$, $038A_{16}$	Undefined
TA3	$038D_{16}$, $038C_{16}$	Undefined
TA4	$038F_{16}$, $038E_{16}$	Undefined

Mode	Function	Setting Range	RW
Timer mode	Divide the count source by n + 1 where n = set value	0000_{16} to $FFFF_{16}$	RW
Event counter mode	Divide the count source by $FFFF_{16}$ – n + 1 where n = set value when counting up or by n + 1 when counting down(5)	0000_{16} to $FFFF_{16}$	RW
One-shot timer mode	Divide the count source by n where n = set value and cause the timer to stop	0000_{16} to $FFFF_{16}$ (2, 4)	WO
Pulse width modulation mode (16-bit PWM)	Modify the pulse width as follows: PWM period: $(2^{16} – 1) / fj$ High level PWM pulse width: n / fj where n = set value, fj = count source frequency	0000_{16} to $FFFE_{16}$ (3, 4)	WO
Pulse width modulation mode (8-bit PWM)	Modify the pulse width as follows: PWM period: $(2^8 – 1) \times (m + 1) / fj$ High level PWM pulse width: $(m + 1)n / fj$ where n = high-order address set value, m = low-order address set value, fj = count source frequency	00_{16} to FE_{16} (High-order address) 00_{16} to FF_{16} (Low-order address) (3, 4)	WO

NOTES:
1. The register must be accessed in 16 bit units.
2. If the TAi register is set to 0000_{16}, the counter does not work and timer Ai interrupt requests are not generated either. Furthermore, if “pulse output” is selected, no pulses are output from the TAiOUT pin.
3. If the TAi register is set to 0000_{16}, the pulse width modulator does not work, the output level on the TAiOUT pin remains low, and timer Ai interrupt requests are not generated either. The same applies when the 8 high-order bits of the timer TAi register are set to 00_{16} while operating as an 8-bit pulse width modulator.
4. Use the MOV instruction to write to the TAi register.
5. The timer counts pulses from an external device or overflows or underflows in other timers.

Count Start Flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TABSR	0380_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA0S	Timer A0 count start flag	0 : Stops counting 1 : Starts counting	RW
TA1S	Timer A1 count start flag		RW
TA2S	Timer A2 count start flag		RW
TA3S	Timer A3 count start flag		RW
TA4S	Timer A4 count start flag		RW
TB0S	Timer B0 count start flag		RW
TB1S	Timer B1 count start flag		RW
TB2S	Timer B2 count start flag		RW

Up/Down Flag (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
UDF	0384_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA0UD	Timer A0 up/down flag	0: Down count 1: Up count Enabled by setting the MR2 bit in the TAiMR register to 0 (= switching source in UDF register) during event counter mode	RW
TA1UD	Timer A1 up/down flag		RW
TA2UD	Timer A2 up/down flag		RW
TA3UD	Timer A3 up/down flag		RW
TA4UD	Timer A4 up/down flag		RW
TA2P	Timer A2 two-phase pulse signal processing select bit	0: two-phase pulse signal processing disabled 1: two-phase pulse signal processing enabled (2, 3)	WO
TA3P	Timer A3 two-phase pulse signal processing select bit		WO
TA4P	Timer A4 two-phase pulse signal processing select bit		WO

NOTES:
1. Use MOV instruction to write to this register.
2. Make sure the port direction bits for the TA2IN to TA4IN and TA2OUT to TA4OUT pins are set to 0 input mode.
3. When the two-phase pulse signal processing function is not used, set the corresponding bit to 0.

Figure 12.5 TA0 to TA4 Registers, TABSR Register, and UDF Register

One-shot Start Flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
ONSF	0382_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA0OS	Timer A0 one-shot start flag	The timer starts counting by setting this bit to 1 while bits TMOD1 and TMOD0 in the TAiMR register (i = 0 to 4) = 10_2 (= one-shot timer mode) and the MR2 bit in the TAiMR register = 0 (=TAiOS bit enabled). When read, its content is 0	RW
TA1OS	Timer A1 one-shot start flag		RW
TA2OS	Timer A2 one-shot start flag		RW
TA3OS	Timer A3 one-shot start flag		RW
TA4OS	Timer A4 one-shot start flag		RW
TAZIE	Z-phase input enable bit	0: Z-phase input disabled 1: Z-phase input enabled	RW
TA0TGL	Timer A0 event/trigger select bit	b7 b6 0 0: Input on $TA0_{IN}$ is selected (1) 0 1: TB2 overflow is selected (2) 1 0: TA4 overflow is selected (2) 1 1: TA1 overflow is selected (2)	RW
TA0TGH			RW

NOTES:
1. Make sure the PD7_1 bit in the PD7 register is set to 0 (input mode).
2. Overflow or underflow.

Trigger Select Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TRGSR	0383_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA1TGL	Timer A1 event/trigger select bit	b1 b0 0 0: Input on $TA1_{IN}$ is selected (1) 0 1: TB2 is selected (2) 1 0: TA0 is selected (2) 1 1: TA2 is selected (2)	RW
TA1TGH			RW
TA2TGL	Timer A2 event/trigger select bit	b3 b2 0 0: Input on $TA2_{IN}$ is selected (1) 0 1: TB2 is selected (2) 1 0: TA1 is selected (2) 1 1: TA3 is selected (2)	RW
TA2TGH			RW
TA3TGL	Timer A3 event/trigger select bit	b5 b4 0 0: Input on $TA3_{IN}$ is selected (1) 0 1: TB2 is selected (2) 1 0: TA2 is selected (2) 1 1: TA4 is selected (2)	RW
TA3TGH			RW
TA4TGL	Timer A4 event/trigger select bit	b7 b6 0 0: Input on $TA4_{IN}$ is selected (1) 0 1: TB2 is selected (2) 1 0: TA3 is selected (2) 1 1: TA0 is selected (2)	RW
TA4TGH			RW

NOTES:
1. Make sure the port direction bits for the $TA1_{IN}$ to $TA4_{IN}$ pins are set to 0 (input mode).
2. Overflow or underflow.

Clock Prescaler Reset Flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
CPSRF	0381_{16}	$0XXXXXXX_2$

Bit Symbol	Bit Name	Function	RW
— (b6-b0)	Nothing is assigned. If necessary, set to 0. When read, their contents are undefined		—
CPSR	Clock prescaler reset flag	Setting this bit to 1 initializes the prescaler for the timekeeping clock. (When read, its content is 0)	RW

Figure 12.6 ONSF Register, TRGSR Register, and CPSRF Register

12.1.1 Timer Mode

In timer mode, the timer counts a count source generated internally (see **Table 12.1**). **Figure 12.7** shows TAiMR register in timer mode.

Table 12.1 Specifications in Timer Mode

Item	Specification
Count source	f_1, f_2, f_8, f_{32}, fC_{32}
Count operation	• Decrement • When the timer underflows, it reloads the reload register contents and continues counting
Divide ratio	1/(n+1) n: set value of TAi register (i= 0 to 4) 0000_{16} to $FFFF_{16}$
Count start condition	Set TAiS bit in the TABSR register to 1 (start counting)
Count stop condition	Set TAiS bit to 0 (stop counting)
Interrupt request generation timing	Timer underflow
TAi_{IN} pin function	I/O port or gate input
TAi_{OUT} pin function	I/O port or pulse output
Read from timer	Count value can be read by reading TAi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TAi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TAi register is written to only reload register (Transferred to counter when reloaded next)
Select function	• Gate function Counting can be started and stopped by an input signal to TAi_{IN} pin • Pulse output function Whenever the timer underflows, the output polarity of TAi_{OUT} pin is inverted. When not counting, the pin outputs a low.

Timer Ai Mode Register (i=0 to 4)

b7	b6	b5	b4	b3	b2	b1	b0
		0				0	0

Symbol: TA0MR to TA4MR Address: 0396_{16} to $039A_{16}$ After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 0: Timer mode	RW
TMOD1			RW
MR0	Pulse output function select bit	0: Pulse is not output (TAi_{OUT} pin is a normal port pin) 1: Pulse is output (TAi_{OUT} pin is a pulse output pin)	RW
MR1	Gate function select bit	b4 b3 0 0: } Gate function not available 0 1: } (TAi_{IN} pin functions as I/O port) 1 0: Counts while input on the TAi_{IN} pin is low (1) 1 1: Counts while input on the TAi_{IN} pin is high(1)	RW
MR2			RW
MR3	Set to 0 in timer mode		RW
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: fC_{32}	RW
TCK1			RW

NOTE:
1. The port direction bit for the TAi_{IN} pin must be set to 0 (input mode).

Figure 12.7 Timer Ai Mode Register in Timer Mode

12.1.2 Event Counter Mode

In event counter mode, the timer counts pulses from an external device or overflows and underflows of other timers. Timers A2, A3, and A4 can count two-phase external signals. **Table 12.2** lists specifications in event counter mode (when not processing two-phase pulse signal). **Table 12.3** lists specifications in event counter mode (when processing two-phase pulse signal with the timers A2, A3 and A4). **Figure 12.8** shows TAiMR register in event counter mode (when not processing two-phase pulse signal). **Figure 12.9** shows TA2MR to TA4MR registers in event counter mode (when processing two-phase pulse signal with the timers A2, A3 and A4).

Table 12.2 Specifications in Event Counter Mode (when not processing two-phase pulse signal)

Item	Specification
Count source	• External signals input to TAiIN pin (i=0 to 4) (effective edge can be selected in program) • Timer B2 overflows or underflows, timer Aj (j=i-1, except j=4 if i=0) overflows or underflows, timer Ak (k=i+1, except k=0 if i=4) overflows or underflows
Count operation	• Increment or decrement can be selected by external signal or program • When the timer overflows or underflows, it reloads the reload register contents and continues counting. When operating in free-running mode, the timer continues counting without reloading.
Divided ratio	$1/(FFFF_{16} - n + 1)$ for increment $1/(n + 1)$ for down-count n : set value of TAi register 0000_{16} to $FFFF_{16}$
Count start condition	Set TAiS bit in the TABSR register to 1 (start counting)
Count stop condition	Set TAiS bit to 0 (stop counting)
Interrupt request generation timing	Timer overflow or underflow
TAiIN pin function	I/O port or count source input
TAiOUT pin function	I/O port, pulse output, or up/down-count select input
Read from timer	Count value can be read by reading TAi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TAi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TAi register is written to only reload register (Transferred to counter when reloaded next)
Select function	• Free-run count function Even when the timer overflows or underflows, the reload register content is not reloaded to it • Pulse output function Whenever the timer underflows or underflows, the output polarity of TAiOUT pin is inverted . When not counting, the pin outputs a low.

Timer Ai Mode Register (i=0 to 4)
(When not using two-phase pulse signal processing)

b7	b6	b5	b4	b3	b2	b1	b0
		0				0	1

Symbol	Address	After Reset
TA0MR to TA4MR	0396_{16} to $039A_{16}$	00_{16}

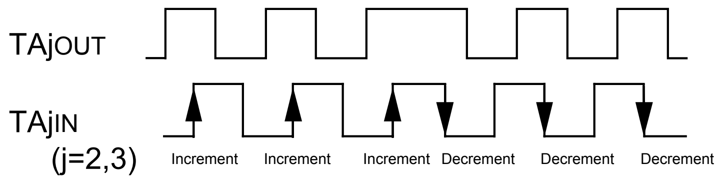
Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 1 : Event counter mode (1)	RW
TMOD1			RW
MR0	Pulse output function select bit	0: Pulse is not output (TAiOUT pin functions as I/O port) 1: Pulse is output (TAiOUT pin functions as pulse output pin)	RW
MR1	Count polarityselect bit (2)	0: Counts external signal's falling edge 1: Counts external signal's rising edge	RW
MR2	Up/down switching cause select bit	0: UDF register 1: Input signal to TAiOUT pin(3)	RW
MR3	Set to 0 in event counter mode		RW
TCK0	Count operation type select bit	0: Reload type 1: Free-run type	RW
TCK1	Can be 0 or 1 when not using two-phase pulse signal processing		RW

NOTES:
1. During event counter mode, the count source can be selected using registers ONSF and TRGSR.
2. Effective when bits TAiTGH and TAiTGL in the ONSF or TRGSR register are 00_2 (TAiIN pin input).
3. Decrement when input on TAiOUT pin is low or increment when input on that pin is high. The port direction bit for TAiOUT pin must be set to 0 (input mode).

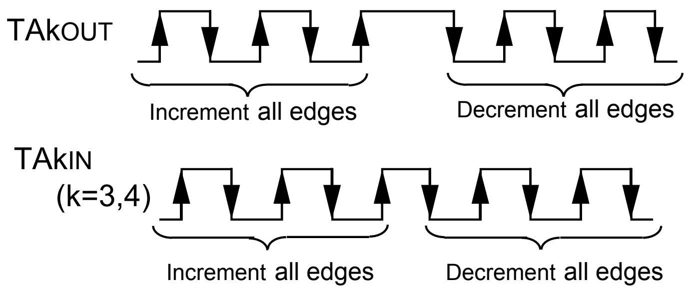
Figure 12.8 TAiMR Register in Event Counter Mode (when not using two-phase pulse signal processing)

Table 12.3 Specifications in Event Counter Mode
(when processing two-phase pulse signal with timers A2, A3 and A4)

<table>
<tr><th>Item</th><th>Specification</th></tr>
<tr><td>Count source</td><td>• Two-phase pulse signals input to TAiIN or TAiOUT pins (i = 2 to 4)</td></tr>
<tr><td>Count operation</td><td>• Increment or down-count can be selected by two-phase pulse signal
• When the timer overflows or underflows, it reloads the reload register contents and continues counting. When operating in free-running mode, the timer continues counting without reloading.</td></tr>
<tr><td>Divide ratio</td><td>1/ ($FFFF_{16}$ - n + 1) for increment
1/ (n + 1) for down-count n : set value of TAi register 0000_{16} to $FFFF_{16}$</td></tr>
<tr><td>Count start condition</td><td>Set TAiS bit in the TABSR register to 1 (start counting)</td></tr>
<tr><td>Count stop condition</td><td>Set TAiS bit to 0 (stop counting)</td></tr>
<tr><td>Interrupt request generation timing</td><td>Timer overflow or underflow</td></tr>
<tr><td>TAiIN pin function</td><td>Two-phase pulse input</td></tr>
<tr><td>TAiOUT pin function</td><td>Two-phase pulse input</td></tr>
<tr><td>Read from timer</td><td>Count value can be read by reading timer A2, A3 or A4 register</td></tr>
<tr><td>Write to timer</td><td>• When not counting and until the 1st count source is input after counting start
Value written to TAi register is written to both reload register and counter
• When counting (after 1st count source input)
Value written to TAi register is written to reload register
(Transferred to counter when reloaded next)</td></tr>
<tr><td>Select function (Note)</td><td>• Normal processing operation (timer A2 and timer A3)
The timer counts up rising edges or counts down falling edges on TAjIN pin when input signals on TAjOUT pin is “H”.



• Multiply-by-4 processing operation (timer A3 and timer A4)
If the phase relationship is such that TAkIN(k=3, 4) pin goes “H” when the input signal on TAkOUT pin is “H”, the timer counts up rising and falling edges on TAkOUT and TAkIN pins. If the phase relationship is such that TAkIN pin goes “L” when the input signal on TAkOUT pin is “H”, the timer counts down rising and falling edges on TAkOUT and TAkIN pins.



• Counter initialization by Z-phase input (timer A3)
The timer count value is initialized to 0 by Z-phase input.</td></tr>
</table>

NOTE:

1. Only timer A3 is selectable. Timer A2 is fixed to normal processing operation, and timer A4 is fixed to multiply-by-4 processing operation.

Timer Ai Mode Register (i=2 to 4)
(When using two-phase pulse signal processing)

b6	b5	b4	b3	b2	b1	b0
		0	1	0	0	0	1

Symbol	Address	After Reset
TA2MR to TA4MR	0398_{16} to $039A_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 1: Event counter mode	RW
TMOD1			RW
MR0	To use two-phase pulse signal processing, set this bit to 0		RW
MR1	To use two-phase pulse signal processing, set this bit to 0		RW
MR2	To use two-phase pulse signal processing, set this bit to 1		RW
MR3	To use two-phase pulse signal processing, set this bit to 0		RW
TCK0	Count operation type select bit	0: Reload type 1: Free-run type	RW
TCK1	Two-phase pulse signal processing operation select bit (1)(2)	0: Normal processing operation 1: Multiply-by-4 processing operation	RW

NOTES:
1. The TCK1 bit is valid for timer A3 mode register. No matter how this bit is set, timers A2 and A4 always operate in normal processing mode and x4 processing mode, respectively.
2. If two-phase pulse signal processing is desired, following register settings are required:
   • Set the TAiP bit in the UDF register to 1 (two-phase pulse signal processing function enabled).
   • Set bits TAiTGH and TAiTGL in the TRGSR register to 00_2 (TAiIN pin input).
   • Set the port direction bits for TAi_{IN} and TAi_{OUT} to 0 (input mode).

Figure 12.9 TA2MR to TA4MR Registers in Event Counter Mode (when using two-phase pulse signal processing with timer A2, A3 or A4)

12.1.2.1 Counter Initialization by Two-Phase Pulse Signal Processing

This function initializes the timer count value to 0 by Z-phase (counter initialization) input during two-phase pulse signal processing.

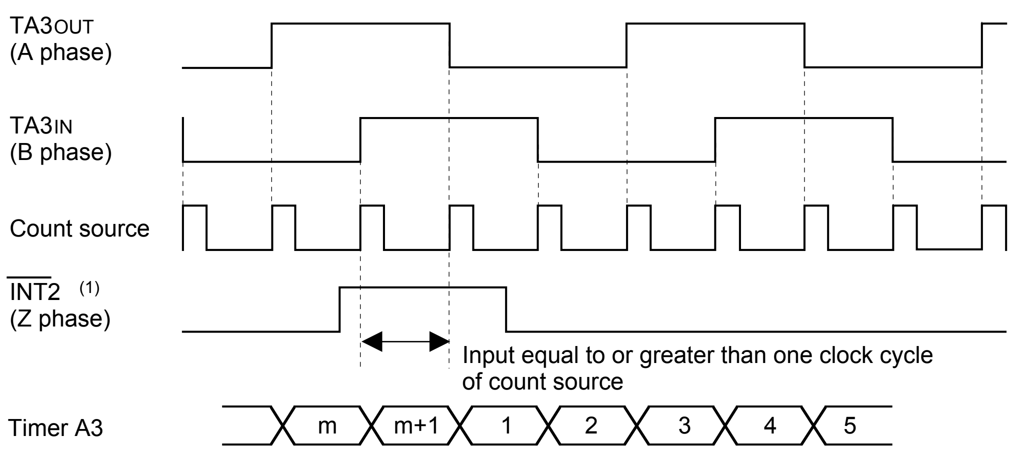
This function can only be used in timer A3 event counter mode during two-phase pulse signal processing, free-running type, x4 processing, with Z-phase entered from the $\overline{INT2}$ pin.

Counter initialization by Z-phase input is enabled by writing 0000_{16} to the TA3 register and setting the TAZIE bit in ONSF register to 1 (Z-phase input enabled).

Counter initialization is accomplished by detecting Z-phase input edge. The active edge can be chosen to be the rising or falling edge by using the POL bit in the INT2IC register. The Z-phase pulse width applied to the $\overline{INT2}$ pin must be equal to or greater than one clock cycle of the timer A3 count source.

The counter is initialized at the next count timing after recognizing Z-phase input. **Figure 12.10** shows the relationship between the two-phase pulse (A phase and B phase) and the Z phase.

If timer A3 overflow or underflow coincides with the counter initialization by Z-phase input, a timer A3 interrupt request is generated twice in succession. Do not use the timer A3 interrupt when using this function.



NOTE:
1. This timing diagram is for the case where the POL bit in the INT2IC register is set to 1 (rising edge).

Figure 12.10 Two-phase Pulse (A phase and B phase) and the Z Phase

12.1.3 One-shot Timer Mode

In one-shot timer mode, the timer is activated only once by one trigger. (See **Table 12.4**) When the trigger occurs, the timer starts up and continues operating for a given period. **Figure 12.11** shows the TAiMR register in one-shot timer mode.

Table 12.4 Specifications in One-shot Timer Mode

Item	Specification
Count source	f1, f2, f8, f32, fC32
Count operation	• Decrement • When the counter reaches 0000₁₆, it stops counting after reloading a new value • If a trigger occurs when counting, the timer reloads a new count and restarts counting
Divide ratio	1/n n : set value of TAi register 0000_{16} to $FFFF_{16}$ However, the counter does not work if the divide-by-n value is set to 0000_{16}.
Count start condition	TAiS bit in the TABSR register is set to 1 (start counting) and one of the following triggers occurs. • External trigger input from the TAiIN pin • Timer B2 overflow or underflow, timer Aj (j=i-1, except j=4 if i=0) overflow or underflow, timer Ak (k=i+1, except k=0 if i=4) overflow or underflow • The TAiOS bit in the ONSF register is set to 1 (timer starts)
Count stop condition	• When the counter is reloaded after reaching 0000_{16} • TAiS bit is set to 0 (stop counting)
Interrupt request generation timing	When the counter reaches 0000_{16}
TAiIN pin function	I/O port or trigger input
TAiOUT pin function	I/O port or pulse output
Read from timer	An undefined value is read by reading TAi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TAi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TAi register is written to only reload register (Transferred to counter when reloaded next)
Select function	• Pulse output function The timer outputs a low when not counting and a high when counting.

Timer Ai Mode Register (i=0 to 4)

b7	b6	b5	b4	b3	b2	b1	b0
		0				1	0

Symbol	Address	After Reset
TA0MR to TA4MR	396_{16} to $039A_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 1 0: One-shot timer mode	RW
TMOD1			RW
MR0	Pulse output function select bit	0: Pulse is not output (TAiOUT pin functions as I/O port) 1: Pulse is output (TAiOUT pin functions as a pulse output pin)	RW
MR1	External trigger select bit (1)	0: Falling edge of input signal to TAiIN pin (2) 1: Rising edge of input signal to TAiIN pin (2)	RW
MR2	Trigger select bit	0: TAiOS bit is enabled 1: Selected by bits TAiTGH to TAiTGL	RW
MR3	Set to 0 in one-shot timer mode		RW
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: f_{C32}	RW
TCK1			RW

NOTES:
1. Effective when bits TAiTGH and TAiTGL in the ONSF or TRGSR register are 00_2 (TAiIN pin input).
2. The port direction bit for the TAiIN pin must be set to 0 (input mode).

Figure 12.11 TAiMR Register in One-shot Timer Mode

12.1.4 Pulse Width Modulation (PWM) Mode

In PWM mode, the timer outputs pulses of a given width in succession (see **Table 12.5**). The counter functions as either 16-bit pulse width modulator or 8-bit pulse width modulator. **Figure 12.12** shows TAiMR register in pulse width modulation mode. **Figures 12.13** and **12.14** show examples of how a 16-bit pulse width modulator operates and how an 8-bit pulse width modulator operates.

Table 12.5 Specifications in Pulse Width Modulation Mode

Item	Specification
Count source	f_1, f_2, f_8, f_{32}, f_{C32}
Count operation	• Decrement (operating as an 8-bit or a 16-bit pulse width modulator) • The timer reloads a new value at a rising edge of PWM pulse and continues counting • The timer is not affected by a trigger that occurs during counting
16-bit PWM	• High level width n / fj n : set value of TAi register (i=o to 4) • Cycle time $(2^{16}-1)$ / fj fixed fj: count source frequency (f_1, f_2, f_8, f_{32}, f_{C32})
8-bit PWM	• High level width n x (m+1) / fj n : set value of TAi register high-order address • Cycle time (2^8-1) x (m+1) / fj m : set value of TAi register low-order address
Count start condition	• TAiS bit in the TABSR register is set to 1 (= start counting) • The TAiS bit = 1 and external trigger input from the TAi_{IN} pin • The TAiS bit = 1 and one of the following external triggers occurs • Timer B2 overflow or underflow, timer Aj (j=i-1, except j=4 if i=0) overflow or underflow, timer Ak (k=i+1, except k=0 if i=4) overflow or underflow
Count stop condition	TAiS bit is set to 0 (stop counting)
Interrupt request generation timing	PWM pulse goes “L”
TAi_{IN} pin function	I/O port or trigger input
TAi_{OUT} pin function	Pulse output
Read from timer	An undefined value is read by reading TAi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TAi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TAi register is written to only reload register (Transferred to counter when reloaded next)

Timer Ai Mode Register (i= 0 to 4)

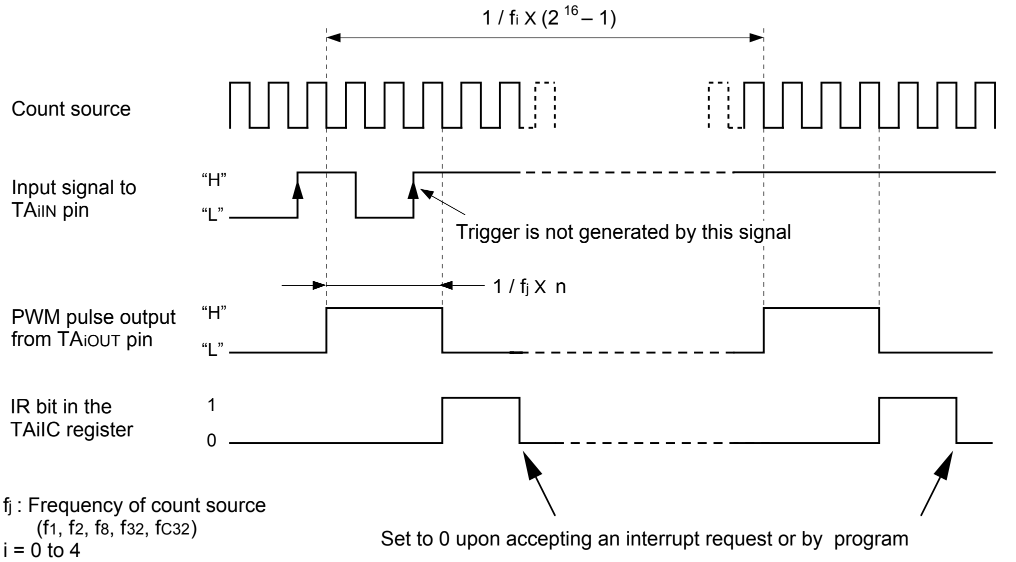
b7	b6	b5	b4	b3	b2	b1	b0
						1	1

Symbol	Address	After Reset
TA0MR to TA4MR	0396_{16} to $039A_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 1 1: PWM mode	RW
TMOD1			RW
MR0	Pulse output funcion select bit	0: Pulse is not output (TAiOUT pin functions as I/O port) 1: Pulse is output (TAiOUT pin functions as a pulse output pin)	RW
MR1	External trigger select bit (1)	0: Falling edge of input signal to TAiIN pin(2) 1: Rising edge of input signal to TAiIN pin(2)	RW
MR2	Trigger select bit	0: Write 1 to TAiS bit in the TASF register 1: Selected by bits TAiTGH to TAiTGL	RW
MR3	16/8-bit PWM mode select bit	0: Functions as a 16-bit pulse width modulator 1: Functions as an 8-bit pulse width modulator	RW
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: f_{C32}	RW
TCK1			RW

NOTES:
1. Effective when bits TAiTGH and TAiTGL in the ONSF or TRGSR register are 00_2 (TAiIN pin input).
2. The port direction bit for the TAiIN pin must be set to 0 (input mode).

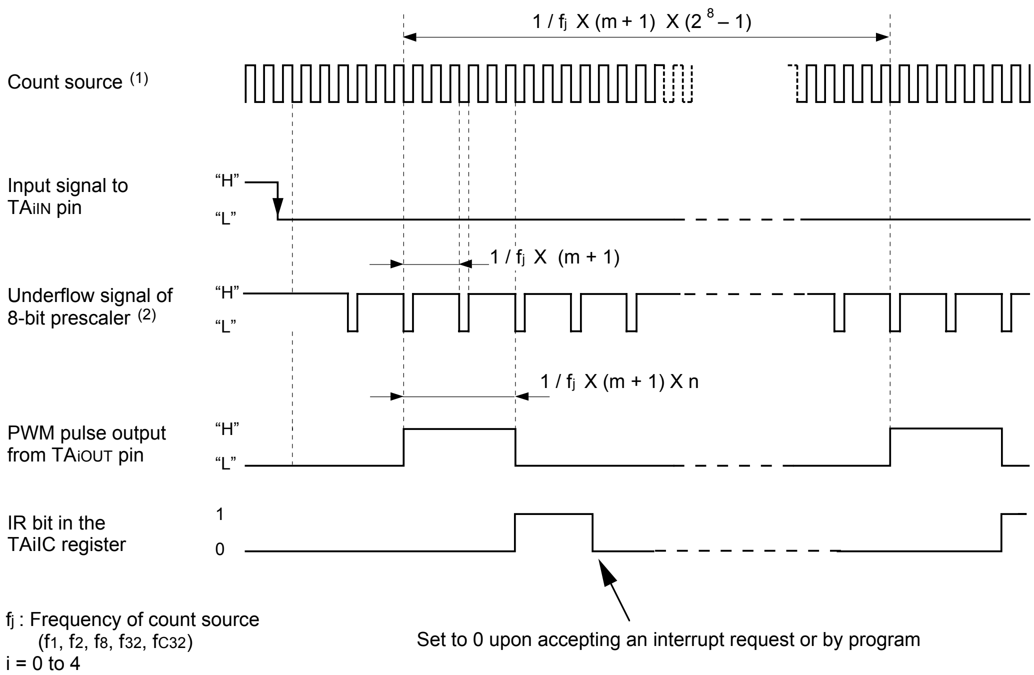
Figure 12.12 TAiMR Register in Pulse Width Modulation Mode



fj : Frequency of count source
(f1, f2, f8, f32, fC32)
i = 0 to 4

NOTES:
1. n = 0000_{16} to $FFFE_{16}$.
2. This timing diagram is for the case where the TAi register is 0003_{16}, bits TAiTGH and TAiTGL in the ONSF or TRGSR register is set to 00_2 (TAiIN pin input), the MR1 bit in the TAiMR register is set to 1 (rising edge), and the MR2 bit in the TAiMR register is set to 1 (trigger selected by TAiTGH and TAiTGL bits).

Figure 12.13 Example of 16-bit Pulse Width Modulator Operation



fj : Frequency of count source
(f1, f2, f8, f32, fC32)
i = 0 to 4

NOTES:
1. The 8-bit prescaler counts the count source.
2. The 8-bit pulse width modulator counts the 8-bit prescaler's underflow signal.
3. m = 00_{16} to FF_{16}; n = 00_{16} to FE_{16}.
4. This timing diagram is for the case where the TAi register is 0202_{16}, bits TAiTGH and TAiTGL in the ONSF or TRGSR register is set to 00_2 (TAiIN pin input), the MR1 bit in the TAiMR register is set to 0 (falling edge), and the MR2 bit in the TAiMR register is set to 1 (trigger selected by bits TAiTGH and TAiTGL).

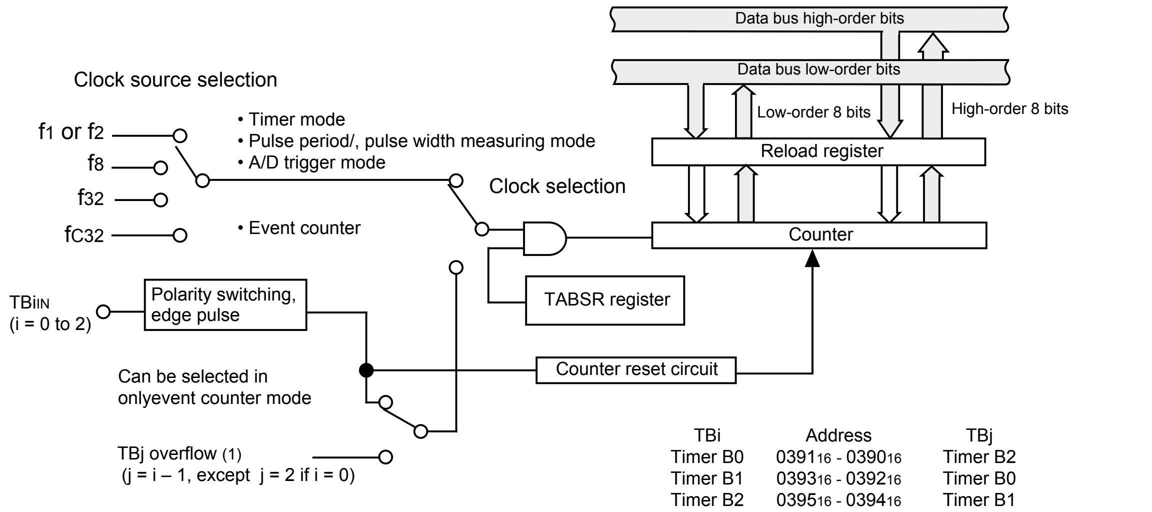
Figure 12.14 Example of 8-bit Pulse Width Modulator Operation

12.2 Timer B

Figure 12.15 shows a block diagram of the timer B. **Figures 12.16** and **12.17** show registers related to the timer B.

Timer B supports the following four modes. Use bits TMOD1 and TMOD0 in the TBiMR register (i = 0 to 2) to select the desired mode.

- Timer mode: The timer counts the internal count source.
- Event counter mode: The timer counts the external pulses or overflows and underflows of other timers.
- Pulse period/pulse width measurement mode: The timer measures the pulse period or pulse width of external signal.
- A/D trigger mode: The timer starts counting by one trigger until the count value becomes 0000_{16}. This mode is used together with simultaneous sample sweep mode or delayed trigger mode 0 of A/D converter to start A/D conversion.



NOTE:
1. Overflow or underflow.

Figure 12.15 Timer B Block Diagram

Timer Bi Mode Register (i=0 to 2)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TB0MR to TB2MR	$039B_{16}$ to $039D_{16}$	$00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 0 : Timer mode or A/D trigger mode 0 1 : Event counter mode 1 0 : Pulse period measurement mode, pulse width measurement mode 1 1 : Do not set	RW
TMOD1			RW
MR0	———	Function varies with each operation mode	RW
MR1			RW
MR2			RW(1) — (2)
MR3			RO
TCK0	Count source select bit	Function varies with each operation mode	RW
TCK1			RW

NOTES:
1. Timer B0.
2. Timer B1, Timer B2.

Figure 12.16 TB0MR to TB2MR Registers

Timer Bi Register (i=0 to 2)(1)

(b15) b7 (b8) b0 b7 b0

Symbol	Address	After Reset
TB0	0391_{16}, 0390_{16}	Undefined
TB1	0393_{16}, 0392_{16}	Undefined
TB2	0395_{16}, 0394_{16}	Undefined

Mode	Function	Setting Rrange	RW
Timer mode	Divide the count source by n + 1 where n = set value	0000_{16} to $FFFF_{16}$	RW
Event counter mode	Divide the count source by n + 1 where n = set value (2)	0000_{16} to $FFFF_{16}$	RW
Pulse period modulation mode, Pulse width modulation mode	Measures a pulse period or width	——	RO
A/D trigger mode (3)	Divide the count source by n + 1 where n = set value and cause the timer stop	0000_{16} to $FFFF_{16}$	RW

NOTES:
1. The register must be accessed in 16 bit units.
2. The timer counts pulses from an external device or overflows or underflows of other timers.
3. When this mode is used combining delayed trigger mode 0, set the larger value than the value in the timer B0 register to the timer B1 register.

Count Start Flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TABSR	0380_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA0S	Timer A0 count start flag	0: Stops counting 1: Starts counting	RW
TA1S	Timer A1 count start flag		RW
TA2S	Timer A2 count start flag		RW
TA3S	Timer A3 count start flag		RW
TA4S	Timer A4 count start flag		RW
TB0S	Timer B0 count start flag		RW
TB1S	Timer B1 count start flag		RW
TB2S	Timer B2 count start flag		RW

Clock Prescaler Reset flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
CPSRF	0381_{16}	$0XXXXXXX_{16}$

Bit Symbol	Bit Name	Function	RW
—— (b6-b0)	Nothing is assigned. If necessary, set to 0. When read, the contents are undefined		—
CPSR	Clock prescaler reset flag	Setting this bit to 1 initializes the prescaler for the timekeeping clock. (When read, the value of this bit is 0)	RW

Figure 12.17 TB0 to TB2 Registers, TABSR Register, CPSRF Register

12.2.1 Timer Mode

In timer mode, the timer counts a count source generated internally (see **Table 12.6**). **Figure 12.18** shows TBiMR register in timer mode.

Table 12.6 Specifications in Timer Mode

Item	Specification
Count source	f_1, f_2, f_8, f_{32}, f_{C32}
Count operation	• Decrement • When the timer underflows, it reloads the reload register contents and continues counting
Divide ratio	1/(n+1) n: set value of TBi register (i= 0 to 2) 0000_{16} to $FFFF_{16}$
Count start condition	Set TBiS bit[1] to 1 (start counting)
Count stop condition	Set TBiS bit to 0 (stop counting)
Interrupt request generation timing	Timer underflow
TBi_{IN} pin function	I/O port
Read from timer	Count value can be read by reading TBi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TBi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TBi register is written to only reload register (Transferred to counter when reloaded next)

NOTE:
1. Bits TB0S to TB2S are assigned to the bit 7 to bit 5 in the TABSR register.

Timer Bi Mode Register (i= 0 to 2)

b7	b6	b5	b4	b3	b2	b1	b0
						0	0

Symbol: TB0MR to TB2MR Address: $039B_{16}$ to $039D_{16}$ After Reset: $00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 0: Timer mode or A/D trigger mode	RW
TMOD1			RW
MR0	No effect in timer mode Can be set to 0 or 1		RW
MR1			RW
MR2	TB0MR register Set to 0 in timer mode		RW
	TB1MR, TB2MR registers Nothing is assigned. If necessary, set to 0. When read, its content is undefined		—
MR3	When write in timer mode, set to 0. When read in timer mode, its content is undefined		RO
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: f_{C32}	RW
TCK1			RW

Figure 12.18 TBiMR Register in Timer Mode

12.2.2 Event Counter Mode

In event counter mode, the timer counts pulses from an external device or overflows and underflows of other timers (see **Table 12.7**). **Figure 12.19** shows the TBiMR register in event counter mode.

Table 12.7 Specifications in Event Counter Mode

Item	Specification
Count source	• External signals input to TBiIN pin (i=0 to 2) (effective edge can be selected in program) • Timer Bj overflow or underflow (j=i-1, except j=2 if i=0)
Count operation	• Decrement • When the timer underflows, it reloads the reload register contents and continues counting
Divide ratio	1/(n+1) n: set value of TBi register 0000_{16} to $FFFF_{16}$
Count start condition	Set TBiS bit(1) to 1 (start counting)
Count stop condition	Set TBiS bit to 0 (stop counting)
Interrupt request generation timing	Timer underflow
TBiIN pin function	Count source input
Read from timer	Count value can be read by reading TBi register
Write to timer	• When not counting and until the 1st count source is input after counting start Value written to TBi register is written to both reload register and counter • When counting (after 1st count source input) Value written to TBi register is written to only reload register (Transferred to counter when reloaded next)

NOTE:
1. Bits TB2S to TB0S are assigned to the bit 7 to bit 5 in the TABSR register.

Timer Bi Mode Register (i=0 to 2)

b7	b6	b5	b4	b3	b2	b1	b0
						0	1

Symbol: TB0MR to TB2MR
Address: $039B_{16}$ to $039D_{16}$
After Reset: $00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 1: Event counter mode	RW
TMOD1			RW
MR0	Count polarity select bit (1)	b3 b2 0 0: Counts external signal's falling edges 0 1: Counts external signal's rising edges 1 0: Counts external signal's falling and rising edges 1 1: Do not set	RW
MR1			RW
MR2	TB0MR register Set to 0 in timer mode		RW
	TB1MR, TB2MR registers Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
MR3	When write in event counter mode, set to 0. When read in event counter mode, its content is undefined		RO
TCK0	No effect in event counter mode Can be set to 0 or 1		RW
TCK1	Event clock select	0 : Input from TBiIN pin (2) 1 : TBj overflow or underflow (j = i – 1, except j = 2 if i = 0)	RW

NOTES:
1. Effective when the TCK1 bit is set to 0 (input from TBiIN pin). If the TCK1 bit is set to 1 (TBj overflow or underflow), these bits can be set to 0 or 1.
2. The port direction bit for the TBiIN pin must be set to 0 (= input mode).

Figure 12.19 TBiMR Register in Event Counter Mode

12.2.3 Pulse Period and Pulse Width Measurement Mode

In pulse period and pulse width measurement mode, the timer measures pulse period or pulse width of an external signal (see **Table 12.8**). **Figure 12.20** shows the TBiMR register in pulse period and pulse width measurement mode. **Figure 12.21** shows the operation timing when measuring a pulse period. **Figure 12.22** shows the operation timing when measuring a pulse width.

Table 12.8 Specifications in Pulse Period and Pulse Width Measurement Mode

Item	Specification
Count source	f_1, f_2, f_8, f_{32}, fC_{32}
Count operation	• Increment • Counter value is transferred to reload register at an effective edge of measurement pulse. The counter value is set to 0000_{16} to continue counting.
Count start condition	Set TBiS (i=0 to 2) bit [3] to 1 (start counting)
Count stop condition	Set TBiS bit to 0 (stop counting)
Interrupt request generation timing	• When an effective edge of measurement pulse is input [1] • Timer overflow. When an overflow occurs, MR3 bit in the TBiMR register is set to 1 (overflowed) simultaneously. MR3 bit is cleared to 0 (no overflow) by writing to TBiMR register at the next count timing or later after MR3 bit was set to 1. At this time, make sure TBiS bit is set to 1 (start counting).
TBi_{IN} pin function	Measurement pulse input
Read from timer	Contents of the reload register (measurement result) can be read by reading TBi register [2]
Write to timer	Value written to TBi register is written to neither reload register nor counter

NOTES:
1. Interrupt request is not generated when the first effective edge is input after the timer started counting.
2. Value read from TBi register is undefined until the second valid edge is input after the timer starts counting.
3. Bits TB0S to TB2S are assigned to the bit 5 to bit 7 in the TABSR register .

Timer Bi Mode Register (i=0 to 2)

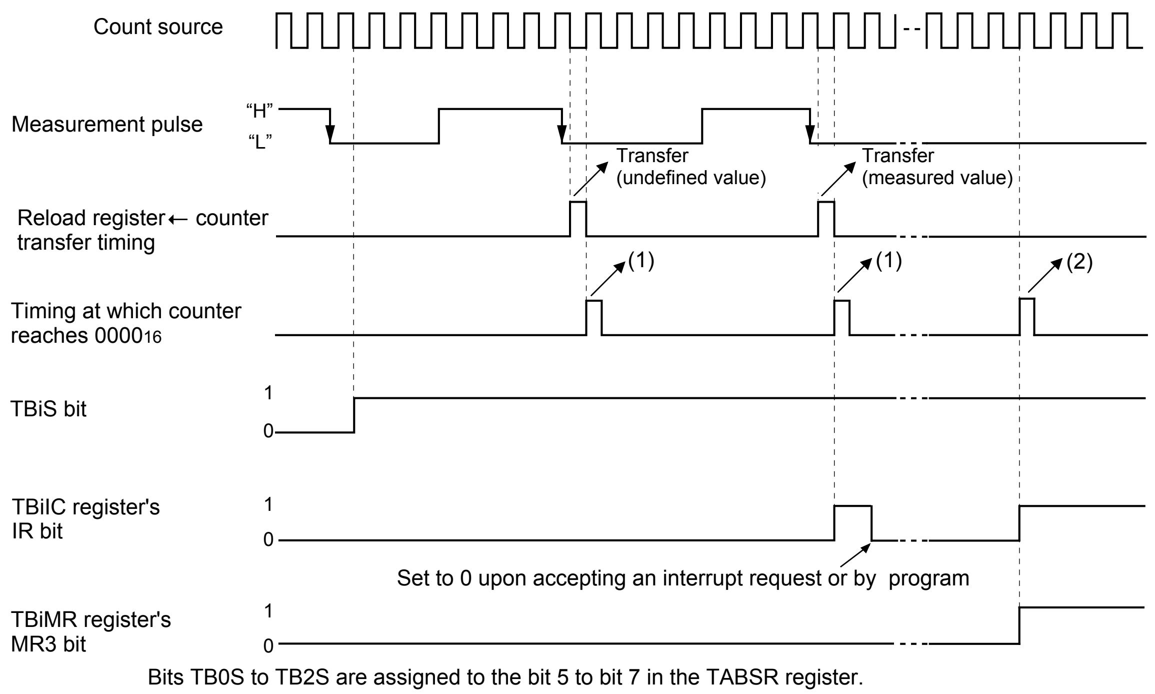
b7 b6 b5 b4 b3 b2 b1 b0: _ _ _ _ _ _ 1 0

Symbol: TB0MR to TB2MR   Address: $039B_{16}$ to $039D_{16}$ After Reset: $00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 1 0 : Pulse period / pulse width measurement mode	RW
TMOD1			RW
MR0	Measurement mode select bit	b3 b2 0 0: Pulse period measurement (Measurement between a falling edge and the next falling edge of measured pulse) 0 1: Pulse period measurement (Measurement between a rising edge and the next rising edge of measured pulse) 1 0: Pulse width measurement (Measurement between a falling edge and the next rising edge of measured pulse and between a rising edge and the next falling edge) 1 1: Do not set.	RW
MR1			RW
MR2	TB0MR register Set to 0 in pulse period and pulse width measurement mode		RW
	TB1MR, TB2MR registers Nothing is assigned. If necessary, set to 0. When read, its content is undefined		—
MR3	Timer Bi overflow flag [1]	0 : Timer did not overflow 1 : Timer has overflowed	RO
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: fC_{32}	RW
TCK1			RW

NOTE:
1.This flag is undefined after reset. When the TBiS bit is set to 1 (start counting), the MR3 bit is cleared to 0 (no overflow) by writing to the TBiMR register at the next count timing or later after the MR3 bit was set to 1 (overflowed). The MR3 bit cannot be set to 1 by program. Bits TB0S to TB2S are assigned to the bit 5 to bit 7 in the TABSR register.

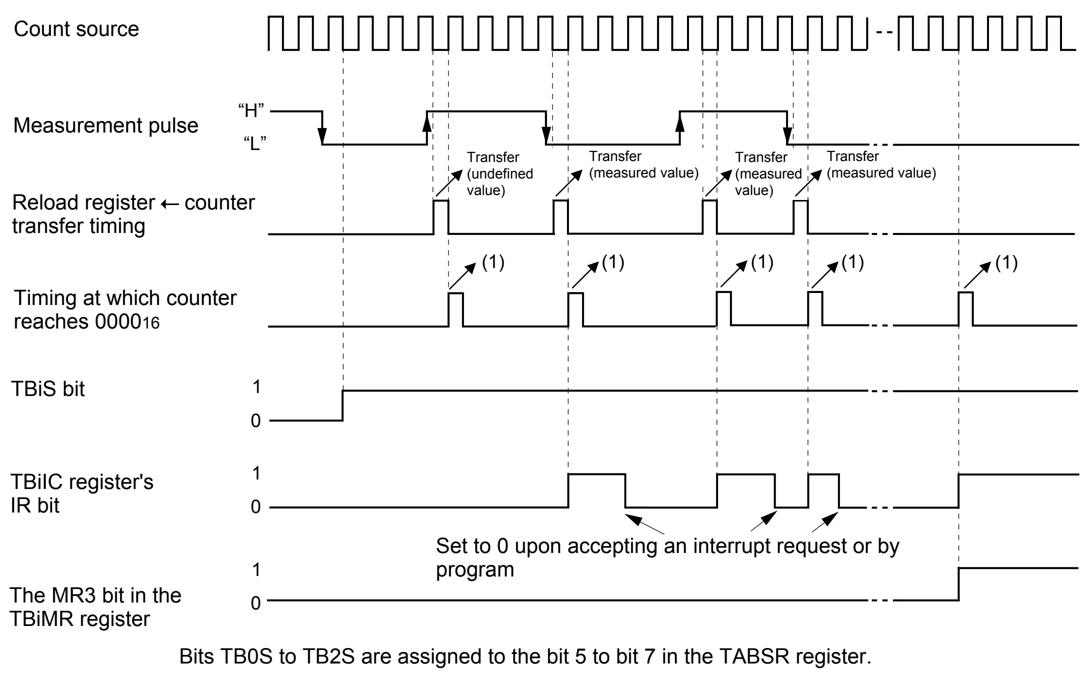
Figure 12.20 TBiMR Register in Pulse Period and Pulse Width Measurement Mode



i = 0 to 2

NOTES:
1. Counter is initialized at completion of measurement.
2. Timer has overflowed.
3. This timing diagram is for the case where bits MR1 and MR0 in the TBiMR register are 00_2 (measure the interval from falling edge to falling edge of the measurement pulse).

Figure 12.21 Operation timing when measuring a pulse period



i = 0 to 2

NOTES:
1. Counter is initialized at completion of measurement.
2. Timer has overflowed.
3. This timing diagram is for the case where bits MR1 to MR0 in the TBiMR register are 10_2 (measure the interval from a falling edge to the next rising edge and the interval from a rising edge to the next falling edge of the measurement pulse).

Figure 12.22 Operation timing when measuring a pulse width

12.2.4 A/D Trigger Mode

A/D trigger mode is used together with simultaneous sample sweep mode or delayed trigger mode 0 of A/D conversion to start A/D conversion. It is used in timer B0 and timer B1 only. In this mode, the timer starts counting by one trigger until the count value becomes 0000_{16}. **Figure 12.23** shows the TBiMR register in A/D trigger mode and **Figure 12.24** shows the TB2SC register.

Table 12.9 Specifications in A/D Trigger Mode

Item	Specification
Count Source	f_1, f_2, f_8, f_{32}, and f_{C32}
Count Operation	• Decrement • When the timer underflows, reload register contents are reloaded before stopping counting • When a trigger is generated during the count operation, the count is not affected
Divide Ratio	1/(n+1) n: Setting value of TBi register (i=0,1) 0000_{16}-$FFFF_{16}$
Count Start Condition	When the TBiS (i=0,1) bit in the TABSR register is 1(count started), TBiEN(i=0,1) in TB2SC register is 1 (A/D trigger mode) and the following trigger is generated.(Selection based on bits TB2SEL in the TB2SC) • Timer B2 interrupt • Underflow of Timer B2 interrupt generation frequency counter setting
Count Stop Condition	• After the count value is 0000_{16} and reload register contents are reloaded • Set the TBiS bit to 0 (count stopped)
Interrupt Request Generation Timing	Timer underflows (1)
TBiIN Pin Function	I/O port
Read From Timer	Count value can be read by reading TBi register
Write To Timer (2)	• When writing in the TBi register during count stopped. Value is written to both reload register and counter • When writing in the TBi register during count. Value is written to only reload register (Transfered to counter when reloaded next)

NOTES:
1: A/D conversion is started by the timer underflow. For details refer to **15. A/D Converter**.
2: When using in delayed trigger mode 0, set the larger value than the value of the timer B0 register to the timer B1 register.

Timer Bi Mode Register (i= 0 to 1)

b7	b6	b5	b4	b3	b2	b1	b0
						0	0

Symbol: TB0MR to TB1MR
Address: $039B_{16}$ to $039C_{16}$
After Reset: $00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	b1 b0 0 0: Timer mode or A/D trigger mode	RW
TMOD1			RW
MR0	Invalid in A/D trigger mode Either 0 or 1 is enabled		RW
MR1			RW
MR2	TB0MR register Set to 0 in A/D trigger mode		RW
	TB1MR register Nothing is assigned. If necessary, set to 0. When read, its content is undefined		—
MR3	When write in A/D trigger mode, set to 0. When read in A/D trigger mode, its content is undefined		RO
TCK0	Count source select bit (1)	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: fC_{32}	RW
TCK1			RW

NOTE:
1. When this bit is used in delayed trigger mode 0, set the same count source to the timer B0 and timer B1.

Figure 12.23 TBiMR Register in A/D Trigger Mode

Timer B2 special mode register (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	0	0		1	1		

Symbol: TB2SC
Address: $039E_{16}$
After Reset: $X0000000_2$

Bit Symbol	Bit Name	Function	RW
PWCON	Timer B2 reload timing switch bit (2)	0: Timer B2 underflow 1: Timer A output at odd-numbered	RW
IVPCR1	Three-phase output port $\overline{SD}$ control bit 1 (3, 4, 7)	0: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) disabled 1: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) enabled	RW
TB0EN	Timer B0 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode (5)	RW
TB1EN	Timer B1 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode (5)	RW
TB2SEL	Trigger select bit (6)	0: TB2 interrupt 1: Underflow of TB2 interrupt generation frequency setting counter [ICTB2]	RW
— (b6-b5)	Reserved bits	Set to 0	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enabled).
2. If the INV11 bit is 0 (three-phase mode 0) or the INV06 bit is 1 (triangular wave modulation mode), set this bit to 0 (timer B2 underflow).
3. When setting the IVPCR1 bit to 1 (three-phase output forcible cutoff by $\overline{SD}$ pin input enabled), Set the $PD8_5$ bit to 0 (= input mode).
4. Related pins are U($P8_0$), $\overline{U}$($P8_1$), V($P7_2$), $\overline{V}$($P7_3$), W($P7_4$), $\overline{W}$($P7_5$). When a high-level ("H") signal is applied to the $\overline{SD}$ pin and set the IVPCR1 bit to 0 after forcible cutoff, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are exit from the high-impedance state. If a low-level ("L") signal is applied to the $\overline{SD}$ pin, three-phase motor control timer output will be disabled (INV03=0). At this time, when the IVPCR1 bit is 0, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ become programmable I/O ports. When the IVPCR1 bit is set to 1, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are placed in a high-impedance state regardless of which function of those pins is used.
5. When this bit is used in delayed trigger mode 0, set bits TB0EN and TB1EN to 1 (A/D trigger mode).
6. When setting the TB2SEL bit to 1 (underflow of TB2 interrupt generation frequency setting counter[ICTB2]), set the INV02 bit to 1 (three-phase motor control timer function).

Figure 12.24 TB2SC Register in A/D Trigger Mode

12.3 Three-phase Motor Control Timer Function

Timers A1, A2, A4 and B2 can be used to output three-phase motor drive waveforms. **Table 12.10** lists the specifications of the three-phase motor control timer function. **Figure 12.24** shows the block diagram for three-phase motor control timer function. Also, the related registers are shown on **Figures 12.26** to **12.32.**

Table 12.10 Three-phase Motor Control Timer Function Specifications

Item	Specification
Three-phase waveform output pin	Six pins (U, $\overline{U}$, V, $\overline{V}$, W, $\overline{W}$)
Forced cutoff input (1)	Input "L" to $\overline{SD}$ pin
Used Timers	Timer A4, A1, A2 (used in the one-shot timer mode) Timer A4: U- and $\overline{U}$-phase waveform control Timer A1: V- and $\overline{V}$-phase waveform control Timer A2: W- and $\overline{W}$-phase waveform control Timer B2 (used in the timer mode) Carrier wave cycle control Dead time timer (3 eight-bit timer and shared reload register) Dead time control
Output waveform	Triangular wave modulation, Sawtooth wave modification Enable to output "H" or "L" for one cycle Enable to set positive-phase level and negative-phase level respectively
Carrier wave cycle	Triangular wave modulation: count source x (m+1) x 2 Sawtooth wave modulation: count source x (m+1) m: Setting value of TB2 register, 0 to 65535 Count source: f$_1$, f$_2$, f$_8$, f$_{32}$, fC$_{32}$
Three-phase PWM output width	Triangular wave modulation: count source x n x 2 Sawtooth wave modulation: count source x n n: Setting value of TA4, TA1 and TA2 register (of TA4, TA41, TA1, TA11, TA2 and TA21 registers when setting the INV11 bit to 1), 1 to 65535 Count source: f$_1$, f$_2$, f$_8$, f$_{32}$, fC$_{32}$
Dead time	Count source x p, or no dead time p: Setting value of DTT register, 1 to 255 Count source: f$_1$, f$_2$, f$_1$ divided by 2, f$_2$ divided by 2
Active level	Eable to select "H" or "L"
Positive and negative-phase concurrent	Positive and negative-phases concurrent active disable function Positive and negative-phases concurrent active detect function
Interrupt frequency	For Timer B2 interrupt, select a carrier wave cycle-to-cycle basis through 15 times carrier wave cycle-to-cycle basis

NOTE:
1. When the INV02 bit in the INVC0 register is set to 1 (three-phase motor control timer function), the $\overline{SD}$ function of the P8$_5$/$\overline{SD}$ pin is enabled. At this time, the P8$_5$ pin cannot be used as a programmable I/O port. When the $\overline{SD}$ function is not used, apply "H" to the P8$_5$/$\overline{SD}$ pin.
When the IVPCR1 bit in the TB2SC register is set to 1 (enable three-phase output forced cutoff by $\overline{SD}$ pin input), and "L" is applied to the $\overline{SD}$ pin, the related pins enter high-impedance state regardless of the functions which are used. When the IVPCR1 bit is set to 0 (disabled three-phase output forced cutoff by $\overline{SD}$ pin input) and "L" is applied to the $\overline{SD}$ pin, the related pins can be selected as a programmable I/O port and the setting of the port and port direction registers are enable.
Related pins: P7$_2$/CLK$_2$/TA1$_{OUT}$/V/RXD$_1$ P7$_3$/$\overline{CTS_2}$/$\overline{RTS_2}$/TA1$_{IN}$/$\overline{V}$/TXD$_1$
P7$_4$/TA2$_{OUT}$/W P7$_5$/TA2$_{IN}$/$\overline{W}$
P8$_0$/TA4$_{OUT}$/U P8$_1$/TA4$_{IN}$/$\overline{U}$

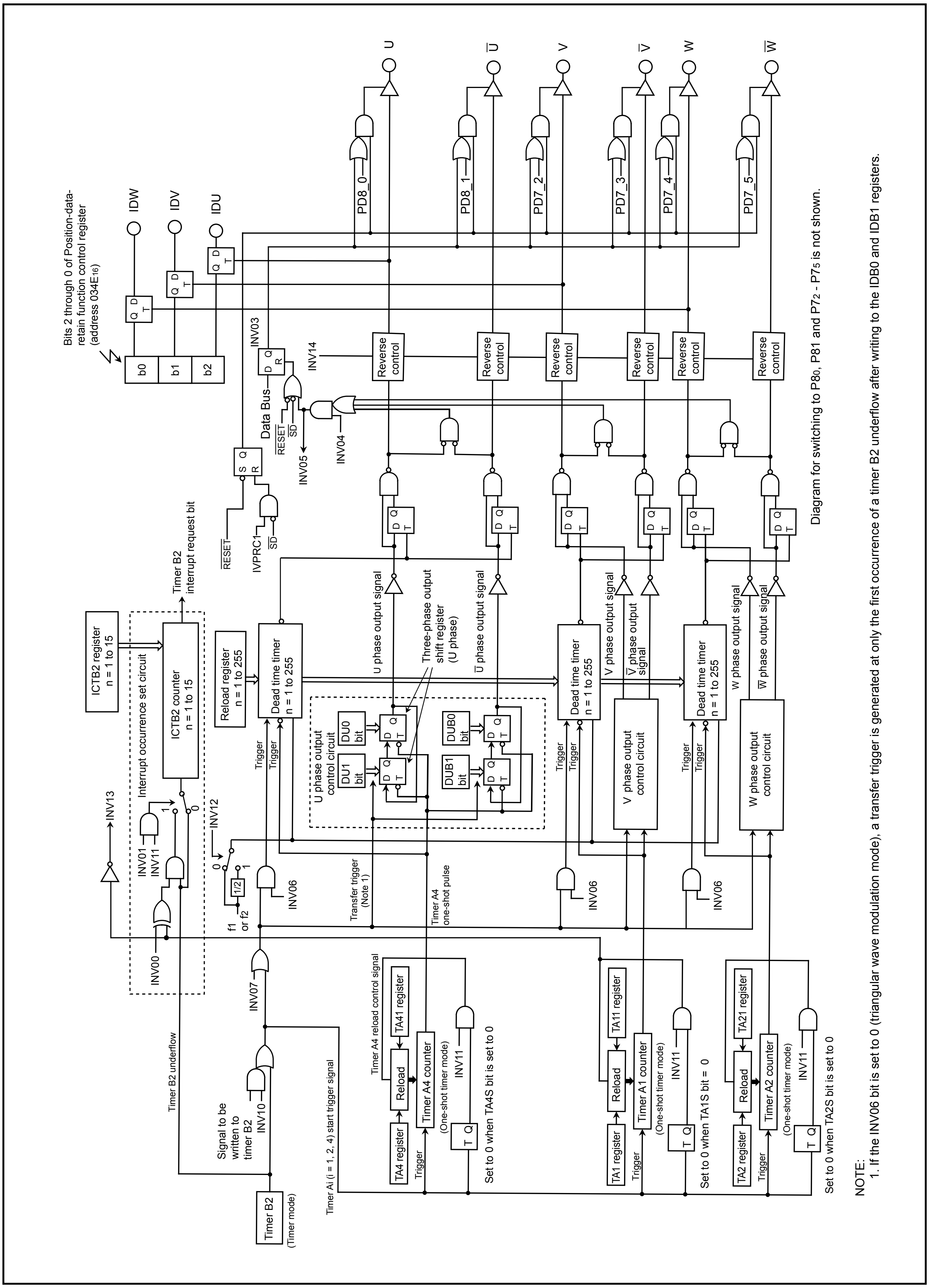


Figure 12.25 Three-phase Motor Control Timer Functions Block Diagram

Three-phase PWM Control Register 0 (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
INVC0	0348$_{16}$	00$_{16}$

Bit Symbol	Bit Name	Function	RW
INV00	Effective interrupt output polarity select bit(3)	0: ICTB2 counter is incremented by 1 on the rising edge of timer A1 reload control signal 1: ICTB2 counter is incremented by 1 on the falling edge of timer A1 reload control signal	RW
INV01	Effective interrupt output specification bit(2, 3)	0: ICTB2 counter incremented by 1 at a timer B2 underflow 1: Selected by INV00 bit	RW
INV02	Mode select bit(4)	0: Three-phase motor control timer function unused 1: Three-phase motor control timer function (5)	RW
INV03	Output control bit(6)	0: Three-phase motor control timer output disabled (5) 1: Three-phase motor control timer output enabled	RW
INV04	Positive and negative phases concurrent output disable bit	0: Simultaneous active output enabled 1: Simultaneous active output disabled	RW
INV05	Positive and negative phases concurrent output detect flag	0: Not detected yet 1: Already detected (7)	RW
INV06	Modulation mode select bit(8)	0: Triangular wave modulation mode 1: Sawtooth wave modulation mode (9)	RW
INV07	Software trigger select bit	Setting this bit to 1 generates a transfer trigger. If the INV06 bit is 1, a trigger for the dead time timer is also generated. The value of this bit when read is 0	RW

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enable). Note also that bits INV00 to INV02, bits INV04 and INV06 can only be rewritten when timers A1, A2, A4 and B2 are idle.
2. If this bit needs to be set to 1, set any value in the ICTB2 register before writing to it.
3. Effective when the INV11 bit in the INV1 register is 1 (three-phase mode 1). If INV11 is set to 0 (three-phase mode 0), the ICTB2 counter is incremented by 1 each time the timer B2 underflows, regardless of whether the INV00 and INV01 bits are set. When setting the INV01 bit to 1, the first interrupt is generated when the timer B2 underflows n-1 times, if n is the value set in the ICTB2 counter. Subsequent interrupts are generated every n times the timer B2 underflow.
4. Setting the INV02 bit to 1 activates the dead time timer, U/V/W-phase output control circuits and ICTB2 counter.
5. When the INV02 bit is set to 1 and the INV03 bit is set to 0, $\overline{U}$, U, $\overline{V}$, V, $\overline{W}$, W pins, including pins shared with other output functions, enter a high-impedance state. When INV03 is set to 1, U/V/W corresponding pins generate the three-phase PWM output.
6. The INV03 bit is set to 0 in the following cases:
   - When reset
   - When positive and negative go active (INV05 = 1) simultaneously while INV04 bit is 1
   - When set to 0 by program
   - When input on the $\overline{SD}$ pin changes state from “H” to “L” regardless of the value of the INVCR1 bit. (The INV03 bit cannot be set to 1 when $\overline{SD}$ input is “L”.) INV03 is set to 0 when both bits INV05 and INV04 are set to 1.

Item	INV06=0	INV06=1
Mode	Triangular wave modulation mode	Sawtooth wave modulation mode
Timing at which transferred from registers IDB0 to IDB1 to three-phase output shift register	Transferred only once synchronously with the transfer trigger after writing to registers IDB0 to IDB1	Transferred every transfer trigger
Timing at which dead time timer trigger is generated when INV16 bit is 0	Synchronous with the falling edge of timer A1, A2, or A4 one-shot pulse	Synchronous with the transfer trigger and the falling edge of timer A1, A2, or A4 one-shot pulse
INV13 bit	Effective when INV11 is set to 1 and INV06 is set to 0	No effect

Transfer trigger: Timer B2 underflow, write to the INV07 bit or write to the TB2 register when the INV10 bit is set to 1.

9: If the INV06 bit is set to 1, set the INV11 bit to 0 (three-phase mode 0) and set the PWCON bit to 0 (timer B2 reloaded by a timer B2 underflow)

10. When the PFCi (i = 0 to 5) bit in the PFCR register is set to 1 (three-phase PWM output), individual pins are enabled to output.

Figure 12.26 INVC0 Register

Three-phase PWM Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
0							

Symbol	Address	After Reset
INVC1	0349_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
INV10	Timer A1, A2, A4 start trigger signal select bit	0: Timer B2 underflow 1: Timer B2 underflow and write to the TB2 register(2)	RW
INV11	Timer A1-1, A2-1, A4-1 control bit (3)	0: Three-phase mode 0 1: Three-phase mode 1 (4)	RW
INV12	Dead time timer count source select bit	0: f_1 or f_2 1: f_1 divided by 2 or f_2 divided by 2	RW
INV13	Carrier wave detect flag (5)	0: Timer Reload control signal is set to 0 1: Timer Reload control signal is set to 1	RO
INV14	Output polarity control bit	0 : Output waveform “L” active 1 : Output waveform “H” active	RW
INV15	Dead time invalid bit	0: Dead time timer enabled 1: Dead time timer disabled	RW
INV16	Dead time timer trigger select bit	0: Falling edge of timer A4, A1 or A2 one-shot pulse 1: Rising edge of three-phase output shift register (U, V or W phase) output(6)	RW
— (b7)	Reserved bit	Set to 0	RW

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enable). Note also that this register can only be rewritten when timers A1, A2, A4 and B2 are idle.
2. A start trigger is generated by writing to the TB2 register only while timer B2 stops.
3. The effects of the INV11 bit are described in the table below.

Item	INV11=0	INV11=1
Mode	Three-phase mode 0	Three-phase mode 1
TA11, TA21, TA41 registers	Not Used	Used
INV00 bit, INV01 bit	Has no effect. ICTB2 counted every time timer B2 underflows regardless of whether bits INV00 and INV01 are set	Effect
INV13 bit	Has no effect	Effective when INV11 bit is 1 and INV06 bit is 0

4. If the INV06 bit is 1 (sawtooth wave modulation mode), set this bit to 0 (three-phase mode 0). Also, if the INV11 bit is 0, set the PWCON bit to 0 (timer B2 reloaded by a timer B2 underflow).
5. The INV13 bit is effective only when the INV06 bit is set to 0 (triangular wave modulation mode) and the INV11 bit is set to 1 (three-phase mode 1).
6. If all of the following conditions hold true, set the INV16 bit to 1 (dead time timer triggered by the rising edge of three-phase output shift register output)
   • The INV15 bit is 0 (dead time timer enabled)
   • When the INV03 bit is set to 1 (three-phase motor control timer output enabled), the Dij bit and DiBj bit (i:U, V, or W, j: 0 to 1) have always different values (the positive-phase and negative-phase always output different levels during the period other than dead time).

Conversely, if either one of the above conditions holds false, set the INV16 bit to 0 (dead time timer triggered by the falling edge of one-shot pulse).

Figure 12.27 INVC1 Register

Three-phase Output Buffer Register(i=0,1) (1)

b7	b6	b5	b4	b3	b2	b1	b0
0	0						

Symbol	Address	After Reset
IDB0	034A16	001111112
IDB1	034B16	001111112

Bit Symbol	Bit Name	Function	RW
DUi	U phase output buffer i	Write the output level 0: Active level 1: Inactive level When read, these bits show the three-phase output shift register value.	RW
DUBi	$\overline{U}$ phase output buffer i		RW
DVi	V phase output buffer i		RW
DVBi	$\overline{V}$ phase output buffer i		RW
DWi	W phase output buffer i		RW
DWBi	$\overline{W}$ phase output buffer i		RW
(b7-b6)	Nothing is assigned. If necessary, set to 0. When read, these contents are 0		RO

NOTE:
1. Registers IDB0 and IDB1 values are transferred to the three-phase shift register by a transfer trigger. The value written to the IDB0 register aftera transfer trigger represents the output signal of each phase, and the next value written to the IDB1 register at the falling edge of the timer A1, A2, or A4 one-shot pulse represents the output signal of each phase.

Dead Time Timer (1, 2)

b7 b0

Symbol	Address	After Reset
DTT	034C16	Undefined

Function	Setting Range	RW
Assuming the set value = n, upon a start trigger the timer starts counting the count souce selected by the INV12 bit and stops after counting it n times. The positive or negative phase whichever is going from an inactive to an active level changes at the same time the dead time timer stops.	1 to 255	WO

NOTES:
1. Use MOV instruction to write to this register.
2. Effective when the INV15 bit is set to 0 (dead time timer enable). If the INV15 bit is set to 1, the dead time timer is disabled and has no effect.

Timer B2 Interrupt Occurrences Frequency Set Counter

b7	b6	b5	b4	b3			b0
X	X	X	X				

Symbol	Address	After Reset
ICTB2	034D16	Undefined

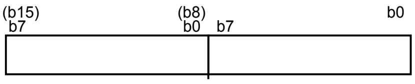
Function	Setting Range	RW
If the INV01 bit is 0 (ICTB2 counter counted every time timer B2 underflows), assuming the set value = n, a timer B2 interrupt is generated at every *n*th occurrence of a timer B2 underflow. If the INV01 bit is 1 (ICTB2 counter count timing selected by the INV00 bit), assuming the set value = n, a timer B2 interrupt is generated at every *n*th occurrence of a timer B2 underflow that meets the condition selected by the INV00 bit. (1)	1 to 15	WO
Nothing is assigned. When write, set to "0". When read, the content is undefined.		—

NOTE:
1. Use MOV instruction to write to this register.
If the INV01 bit is set to 1, make sure the TB2S bit also is set to 0 (timer B2 count stopped) when writing to this register. If the INV01 bit is set to 0, although this register can be written even when the TB2S bit is set to 1 (timer B2 count start), do not write synchronously with a timer B2 underflow.

Figure 12.28 IDB0 Register, IDB1Register, DTT Register, and ICTB2 Register

Timer Ai, Ai-1 Register (i=1, 2, 4) (1, 2, 3, 4, 5)

Symbol	Address	After reset
TA1	0389_{16}-0388_{16}	Undefined
TA2	$038B_{16}$-$038A_{16}$	Undefined
TA4	$038F_{16}$-$038E_{16}$	Undefined
TA11(6,7)	0343_{16}-0342_{16}	Undefined
TA21(6,7)	0345_{16}-0344_{16}	Undefined
TA41(6,7)	0347_{16}-0346_{16}	Undefined



Function	Setting Range	RW
Assuming the set value = n, upon a start trigger the timer starts counting the count source and stops after counting it n times. The positive and negative phases change at the same time timer A, A2 or A4 stops.	0000_{16} to $FFFF_{16}$	WO

NOTES:
1. The register must be accessed in 16 bit units.
2. When the timer Ai register is set to 0000_{16}, the counter does not operate and a timer Ai interrupt does not occur.
3. Use MOV instruction to write to these registers.
4. If the INV15 bit is 0 (dead time timer enable), the positive or negative phase whichever is going from an inactive to an active level changes at the same time the dead time timer stops.
5. If the INV11 bit is 0 (three-phase mode 0), the TAi register value is transferred to the reload register by a timer Ai (i = 1, 2 or 4) start trigger.
   If the INV11 bit is 1 (three-phase mode 1), the TAi1 register value is transferred to the reload register by a timer Ai start trigger first and then the TAi register value is transferred to the reload register by the next timer Ai start trigger. Thereafter, the TAi1 register and TAi register values are transferred to the reload register alternately.
6. Do not write to TAi1 registers synchronously with a timer B2 underflow In three-phase mode 1.
7. Write to the TAi1 register as follows:
   (1) Write a value to the TAi1 register
   (2) Wait for one cycle of timer Ai count source.
   (3) Write the same value to the TAi1 register again.

Figure 12.29 TA1, TA2, TA4, TA11, TA21, and TA41 Registers

Timer B2 Special Mode Register (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	0	0					

Symbol	Address	After Reset
TB2SC	$039E_{16}$	$X0000000_2$

Bit Symbol	Bit Name	Function	RW
PWCON	Timer B2 reload timing switch bit (2)	0: Timer B2 underflow 1: Timer A output at odd-numbered	RW
IVPCR1	Three-phase output port $\overline{SD}$ control bit 1 (3, 4, 7)	0: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) disabled 1: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) enabled	RW
TB0EN	Timer B0 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode (5)	RW
TB1EN	Timer B1 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode (5)	RW
TB2SEL	Trigger select bit (6)	0: TB2 interrupt 1: Underflow of TB2 interrupt generation frequency setting counter [ICTB2]	RW
— (b6-b5)	Reserved bits	Set to 0	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is 0.		—

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enabled).
2. If the INV11 bit is 0 (three-phase mode 0) or the INV06 bit is 1 (triangular wave modulation mode), set this bit to 0 (timer B2 underflow).
3. When setting the IVPCR1 bit to 1 (three-phase output forcible cutoff by $\overline{SD}$ pin input enabled), Set the $PD8_5$ bit to 0 (= input mode).
4. Related pins are U($P8_0$), $\overline{U}$($P8_1$), V($P7_2$), $\overline{V}$($P7_3$), W($P7_4$), $\overline{W}$($P7_5$). When a high-level ("H") signal is applied to the $\overline{SD}$ pin and set the IVPCR1 bit to 0 after forcible cutoff, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are exit from the high-impedance state. If a low-level ("L") signal is applied to the $\overline{SD}$ pin, three-phase motor control timer output will be disabled (INV03=0). At this time, when the IVPCR1 bit is 0, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ become programmable I/O ports. When the IVPCR1 bit is set to 1, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are placed in a high-impedance state regardless of which function of those pins is used.
5. When this bit is used in delayed trigger mode 0, set bits TB0EN and TB1EN to 1 (A/D trigger mode).
6. When setting the TB2SEL bit to 1 (underflow of TB2 interrupt generation frequency setting counter[ICTB2]), set the INV02 bit to 1 (three-phase motor control timer function).
7. Refer to "**19.6 Digital Debounce Function**" for the $\overline{SD}$ input.

The effect of $\overline{SD}$ pin input is below.

1.Case of INV03 = 1(Three-phase motor control timer output enabled)

IVPCR1 bit	$\overline{SD}$ pin inputs(3)	Status of U/V/W pins	Remarks
1 (Three-phase output forcible cutoff enable)	H	Three-phase PWM output	
	L(1)	High impedance(4)	Three-phase output forcible cutoff
0 (Three-phase output forcible cutoff disable)	H	Three-phase PWM output	
	L(1)	Input/output port(2)	

NOTES:
1. When "L" is applied to the $\overline{SD}$ pin, INV03 bit is changed to 0 at the same time.
2. The value of the port register and the port direction register becomes effective.
3. When $\overline{SD}$ function is not used, set to 0 (Input) in $PD8_5$ and pullup to "H" in $\overline{SD}$ pin from outside.
4. To leave the high-impedance state and restart the three-phase PWM signal output after the three-phase PWM signal output forced cutoff, set the IVPCR1 bit to 0 after the $\overline{SD}$ pin input level becomes high ("H").

2.Case of INV03 = 0(Three-phase motor control timer output disabled)

IVPCR1 bit	$\overline{SD}$ pin inputs	Status of U/V/W pins	Remarks
1 (Three-phase output forcible cutoff enable)	H	Peripheral input/output or input/output port	
	L	High impedance	Three-phase output forcible cutoff(1)
0 (Three-phase output forcible cutoff disable)	H	Peripheral input/output or input/output port	
	L	Peripheral input/output or input/output port	

NOTE:
1. The three-phase output forcrible cutoff function becomes effective if the INPCR1 bit is set to 1 (three-phase output forcrible cutoff function enable) even when the INV03 bit is 0 (three-phase motor control timer output disalbe)

Figure 12.30 TB2SC Register

Timer B2 Register (1)

(b15) b7 … (b8) b0 b7 … b0

Symbol	Address	After Reset
TB2	0395_{16}-0394_{16}	Undefined

Function	Setting Range	RW
Divide the count source by n + 1 where n = set value. Timer A1, A2 and A4 are started at every occurrence of underflow.	0000_{16} to $FFFF_{16}$	RW

NOTE:
1. Access the register by 16 bit units.

Trigger Select Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
TRGSR	0383_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA1TGL	Timer A1 event/trigger select bit	To use the V-phase output control circuit, set these bits to "01_2"(TB2 underflow).	RW
TA1TGH			RW
TA2TGL	Timer A2 event/trigger select bit	To use the W-phase output control circuit, set these bits to "01_2"(TB2 underflow).	RW
TA2TGH			RW
TA3TGL	Timer A3 event/trigger select bit	b5 b4 0 0 : Input on TA3IN is selected (1) 0 1 : TB2 is selected (2) 1 0 : TA2 is selected (2) 1 1 : TA4 is selected (2)	RW
TA3TGH			RW
TA4TGL	Timer A4 event/trigger select bit	To use the U-phase output control circuit, set these bits to "01_2"(TB2 underflow).	RW
TA4TGH			RW

NOTES:
1. Set the corresponding port direction bit to 0 (input mode).
2. Overflow or underflow.

Count Start Flag

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After reset
TABSR	0380_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
TA0S	Timer A0 count start flag	0 : Stops counting 1 : Starts counting	RW
TA1S	Timer A1 count start flag		RW
TA2S	Timer A2 count start flag		RW
TA3S	Timer A3 count start flag		RW
TA4S	Timer A4 count start flag		RW
TB0S	Timer B0 count start flag		RW
TB1S	Timer B1 count start flag		RW
TB2S	Timer B2 count start flag		RW

Figure 12.31 TB2 Register, TRGSR Register, and TABSR Register

Timer Ai Mode Register

b7	b6	b5	b4	b3	b2	b1	b0
		0	1		0	1	0

Symbol	Address	After Reset
TA1MR	0397_{16}	00_{16}
TA2MR	0398_{16}	00_{16}
TA4MR	$039A_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	Set to 10_2 (one-shot timer mode) for the three-phase motor control timer function	RW
TMOD1			RW
MR0	Pulse output function select bit	Set to 0 for the three-phase motor control timer function	RW
MR1	External trigger select bit	No effect for the three-phase motor control timer function	RW
MR2	Trigger select bit	Set to 1 (selected by event/trigger select register) for the three-phase motor control timer function	RW
MR3	Set to 0 for the three-phase motor control timer function		RW
TCK0	Count source select bit	b7 b6 0 0 : f_1 or f_2 0 1 : f_8 1 0 : f_{32} 1 1 : fC_{32}	RW
TCK1			RW

Timer B2 Mode Register

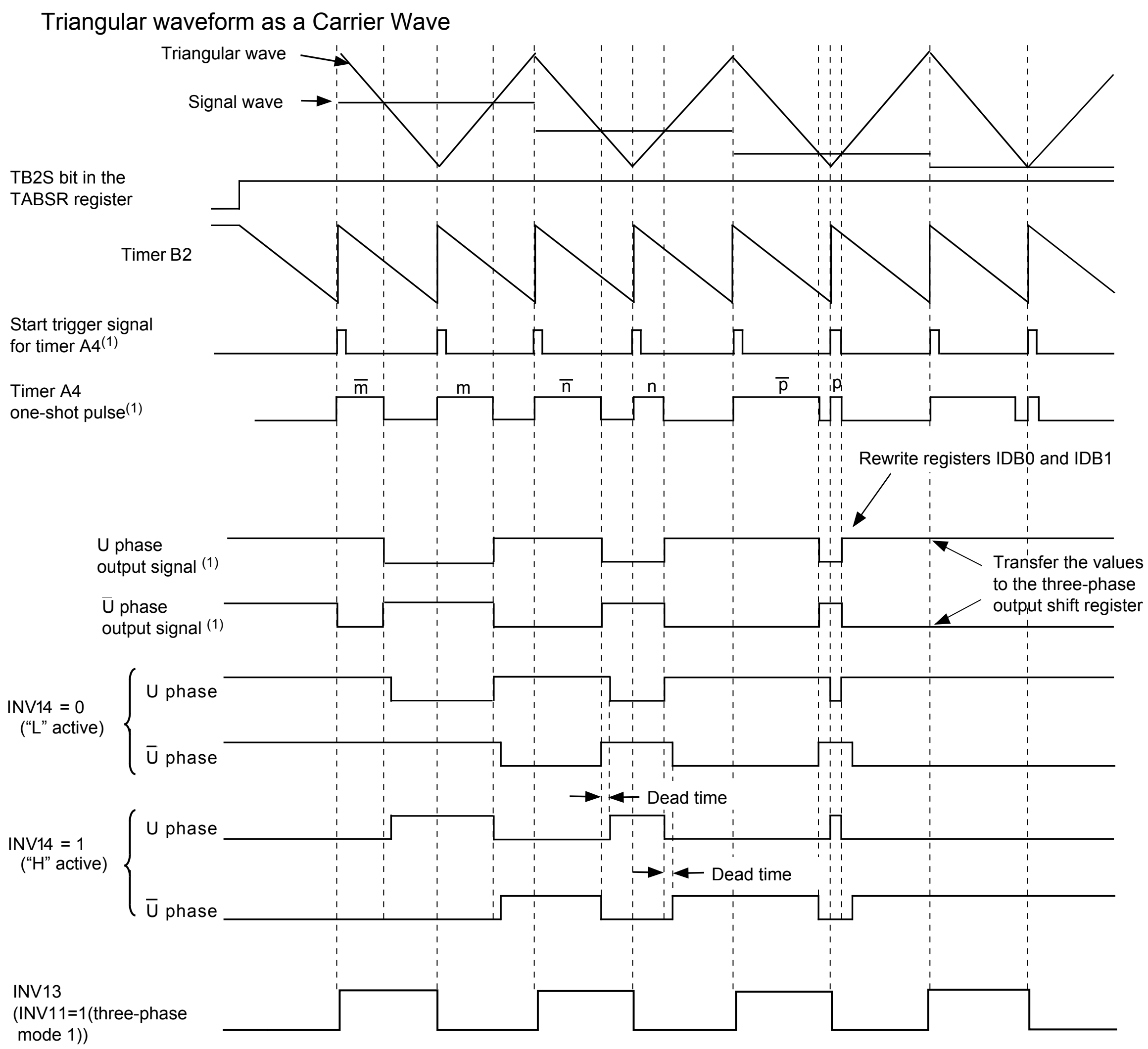
b7	b6	b5	b4	b3	b2	b1	b0
			0			0	0

Symbol	Address	After Reset
TB2MR	$039D_{16}$	$00XX0000_2$

Bit Symbol	Bit Name	Function	RW
TMOD0	Operation mode select bit	Set to 00_2 (timer mode) for the three-phase motor control timer function	RW
TMOD1			RW
MR0	No effect for the three-phase motor control timer function. If necessary, set to 0. When read, the contents are undefined		RW
MR1			RW
MR2	Set to 0 for the three-phase motor control timer function		RW
MR3	When write in three-phase motor control timer function, write 0. When read, the content is undefined		RO
TCK0	Count source select bit	b7 b6 0 0: f_1 or f_2 0 1: f_8 1 0: f_{32} 1 1: fC_{32}	RW
TCK1			RW

Figure 12.32 TA1MR, TA2MR, TA4MR, and TB2MR Registers

The three-phase motor control timer function is enabled by setting the INV02 bit in the INVC0 register to 1. When this function is on, timer B2 is used to control the carrier wave, and timers A4, A1 and A2 are used to control three-phase PWM outputs (U, $\overline{U}$, V, $\overline{V}$, W and $\overline{W}$). The dead time is controlled by a dedicated dead-time timer. **Figure 12.33** shows the example of triangular modulation waveform, and **Figure 12.34** shows the example of sawtooth modulation waveform.



NOTE:
1. Internal signals. See **Figure 12.25**.

The above applies under the following conditions:
INVC0 = $00XX11XX_2$ (X varies depending on each system) and INVC1 = $010XXXX0_2$.

Examples of PWM output change are:

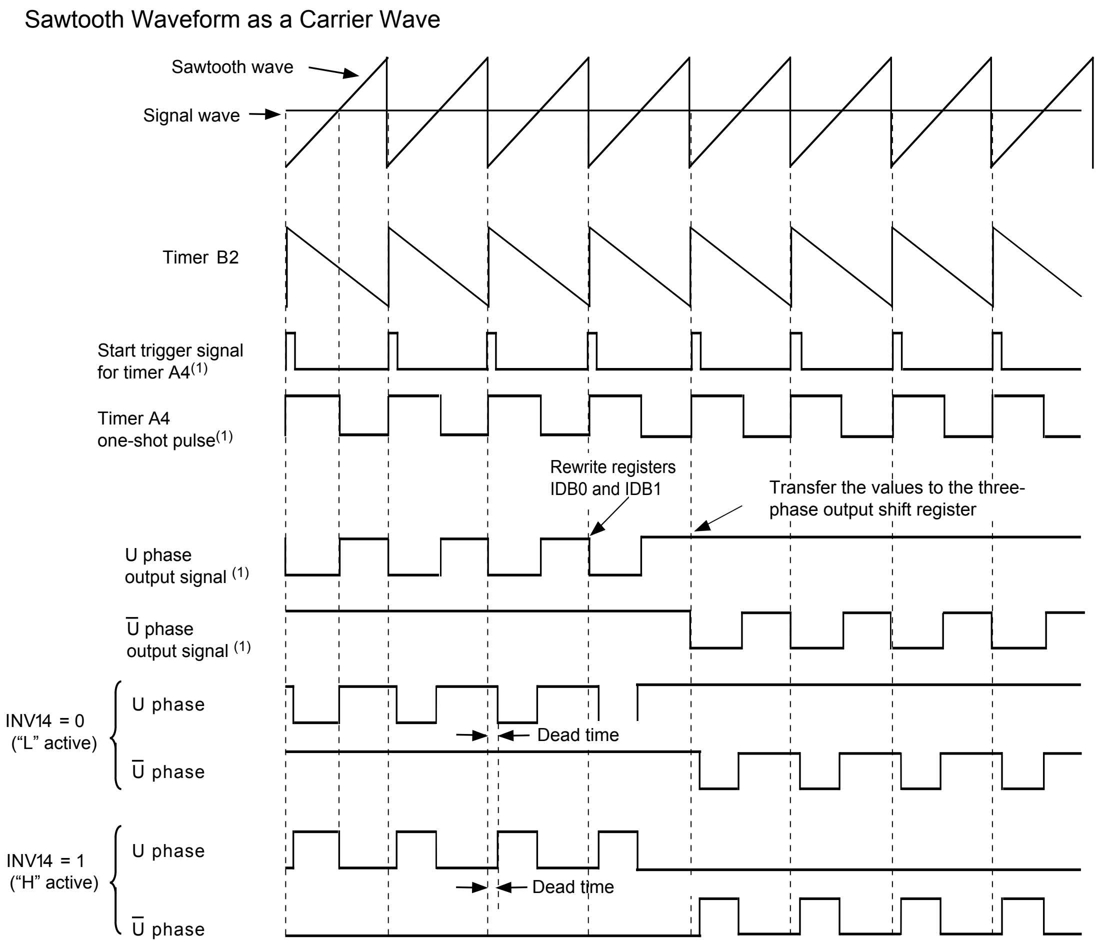
(1)When INV11 = 1 (three-phase mode 1)
- INV01 = 0 and ICTB2 = 2_{16} (the timer B2 interrupt is generated every two times the timer B2 underflows), or INV01 = 1, INV00 = 1, and ICTB2=1_{16} (the timer B2 interrupt is generated at the falling edge of the timer A1 reload control signal.)
- Default value of the timer: TA41 = $\overline{m}$, TA4 = m. Registers TA4 and TA41 are changed whenever the timer B2 interrupt is generated.
  First time, TA41 = $\overline{n}$, TA4 = n. Second time, TA41 = $\overline{p}$, TA4 = p.
- Default values of registers IDB0 and IDB1: DU0 = 1, DUB0 = 0, DU1 = 0, DUB1 = 1. They are changed to DU0 = 1, DUB0 = 0, DU1= 1 and DUB1 = 0 when the third timer B2 interrupt is generated.

(2)When INV11 = 0 (three-phase mode 0)
- INV01 = 0, ICTB2 = 1_{16} (the timer B2 interrupt is generated whenever timer B2 underflows)
- Default value of the timer: TA4 = $\overline{m}$. The TA4 register is changed whenever the timer B2 interrupt is generated.
  First time: TA4 = m. Second tim:, TA4 = $\overline{n}$.
  Third time: TA4 = n. Fourth time: TA4 = $\overline{p}$.
  Fifth time: TA4 = p.
- Default values of registers IDB0 and IDB1: DU0 = 1, DUB0 = 0, DU1 = 0, DUB1 = 1. They are changed to DU0 = 1, DUB0 = 0, DU1 = 1, and DUB1 = 0 when the sixth timer B2 interrupt is generated.

The value written to registers TA4 and TA41 becomes effective at the rising edge of the timer A1 reload control signal.

Figure 12.33 Triangular Wave Modulation Operation

RENESAS



NOTE:
1. Internal signals. See **Figure 12.25**.

The above applies under the following conditions:
INVC0 = 01XX110X2 (X varies depending on each system) and INVC1 = 010XXX002.

Examples of PWM output change are:
• Default value of registers IDB0 and IDB1: DU0=0, DUB0=1, DU1=1, DUB1=1.
They are changed to DU0=1, DUB0=0, DU1=1, DUB1=1 when the timer B2 interrupt is generated.

Figure 12.34 Sawtooth Wave Modulation Operation

12.3.1 Position-Data-Retain Function

This function is used to retain the position data synchronously with the three-phase waveform output.There are three position-data input pins for U, V, and W phases.

A trigger to retain the position data (hereafter, this trigger is referred to as "retain trigger") can be selected by the PDRT bit in the PDRF register. This bit selects the retain trigger to be the falling edge of each positive phase, or the rising edge of each positive phase.

12.3.1.1 Operation of the Position-data-retain Function

Figure 12.35 shows a usage example of the position-data-retain function (U phase) when the retain trigger is selected as the falling edge of the positive signal.

(1) At the falling edge of the U-phase waveform ouput, the state at pin IDU is transferred to the PDRU bit in the PDRF register.

(2) Until the next falling edge of the Uphase waveform output,the above value is retained.

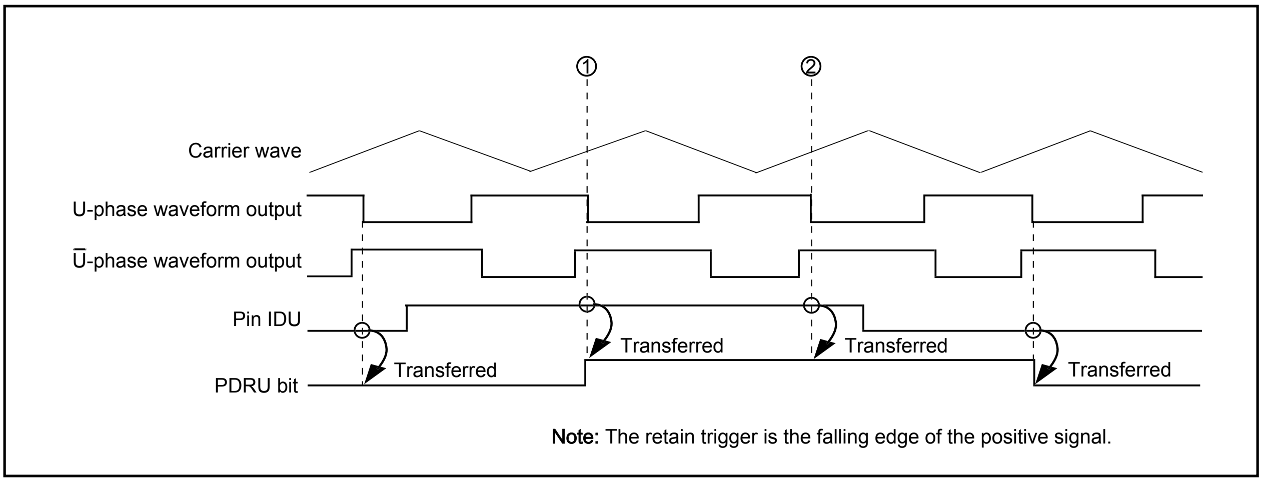


Figure 12.35 Usage Example of Position-data-retain Function (U phase)

12.3.1.2 Position-data-retain Function Control Register

Figure 12.36 shows the structure of the position-data-retain function contol register.

Position-Data-Retain Function Control Register (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
PDRF	$034E_{16}$	XXXX 0000_2

Bit Symbol	Bit Name	Function	RW
PDRW	W-phase position data retain bit	Input level at pin IDW is read out. 0: "L" level 1: "H" level	RO
PDRV	V-phase position data retain bit	Input level at pin IDV is read out. 0: "L" level 1: "H" level	RO
PDRU	U-phase position data retain bit	Input level at pin IDU is read out. 0: "L" level 1: "H" level	RO
PDRT	Retain-trigger polarity select bit	0: Rising edge of positive phase 1: Falling edge of positive phase	RW
(b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the contents are undefined		—

NOTE:
1.This register is valid only in the three-phase mode.

Figure 12.36 PDRF Register

12.3.1.2.1 W-phase Position Data Retain Bit (PDRW)

This bit is used to retain the input level at pin IDW.

12.3.1.2.2 V-phase Position Data Retain Bit (PDRV)

This bit is used to retain the input level at pin IDV.

12.3.1.2.3 U-phase Position Data Retain Bit (PDRU)

This bit is used to retain the input level at pin IDU.

12.3.1.2.4 Retain-trigger Polarity Select Bit (PDRT)

This bit is used to select the trigger polarity to retain the position data.
When this bit is set to 0, the rising edge of each positive phase selected.
When this bit is set to 1, the falling edge of each pocitive phase selected.

12.3.2 Three-phase/Port Output Switch Function

When the INVC03 bit in the INVC0 register set to 1 (Timer output enabled for three-phase motor control) and setting the PFCi (i=0 to 5) in the PFCR register to 0 (I/O port), the three-phase PWM output pin (U, $\overline{U}$, V, $\overline{V}$, W and $\overline{W}$) functions as I/O port. Each bit of the PFCi bits (i=0 to 5) is applicable for each one of three-phase PWM output pins. **Figure 12.37** shows the example of three-phase/port output switch function. **Figure 12.38** shows the PFCR register and the three-phase protect control register.

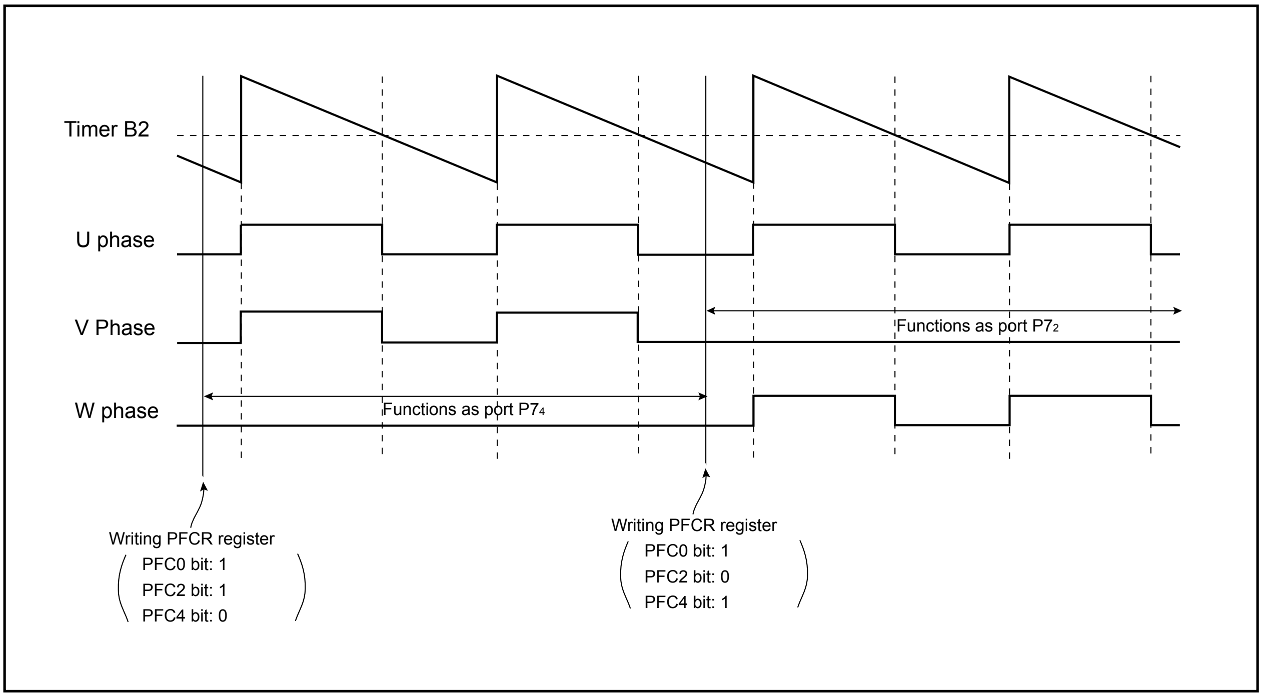


Figure 12.37 Usage Example of Three-phse/Port Output Switch Function

Port Function Control Register (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: PFCR | Address: 0358_{16} | After Reset: $0011\ 1111_2$

Bit Symbol	Bit Name	Function	RW
PFC0	Port $P8_0$ output function select bit	0: Input/Output port $P8_0$ 1: Three-phase PWM output (U phase output)	RW
PFC1	Port $P8_1$ output function select bit	0: Input/Output port $P8_1$ 1: Three-phase PWM output ($\overline{U}$ phase output)	RW
PFC2	Port $P7_2$ output function select bit	0: Input/Output port $P7_2$ 1: Three-phase PWM output (V phase output)	RW
PFC3	Port $P7_3$ output function select bit	0: Input/Output port $P7_3$ 1: Three-phase PWM output ($\overline{V}$ phase output)	RW
PFC4	Port $P7_4$ output function select bit	0: Input/Output port $P7_4$ 1: Three-phase PWM output (W phase output)	RW
PFC5	Port $P7_5$ output function select bit	0: Input/Output port $P7_5$ 1: Three-phase PWM output ($\overline{W}$ phase output)	RW
(b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the contents are 0		—

NOTE:
1. This register is valid only when the INVC03 bit in the INVC0 register is 1 (Three-phase motor control timer.

Three-phase Protect Control Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: TPRC | Address: $025A_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
TPRC0	Three-phase protect control bit	Enable write to PFCR register 0: Write protected 1: Write enabled	RW
(b7-b1)	Nothing is assigned. If necessary, set to 0. When read, the contents are 0		—

Figure 12.38 PFCR Register, and TPRC Register

13. Timer S

The Timer S (Input Capture/Output Compare : here after, Timer S is referred to as "IC/OC".) is a high-performance I/O port for time measurement and waveform generation.

The IC/OC has one 16-bit base timer for free-running operation and eight 16-bit registers for time measurement and waveform generation.

Table 13.1 lists functions and channels of the IC/OC.

Table 13.1 IC/OC Functions and Channels

Function		Description
Time measurement (1)		8 channels
	Digital filter	8 channels
	Trigger input prescaler	2 channels
	Trigger input gate	2 channels
Waveform generation (1)		8 channels
	Single-phase waveform output	Available
	Phase-delayed waveform output	Available
	Set/Reset waveform output	Available

NOTE:
1. The time measurement function and the waveform generating function share a pin.
   The time measurement function or waveform generating function can be selected for each channel.

Figure 13.1 shows the block diagram of the IC/OC.

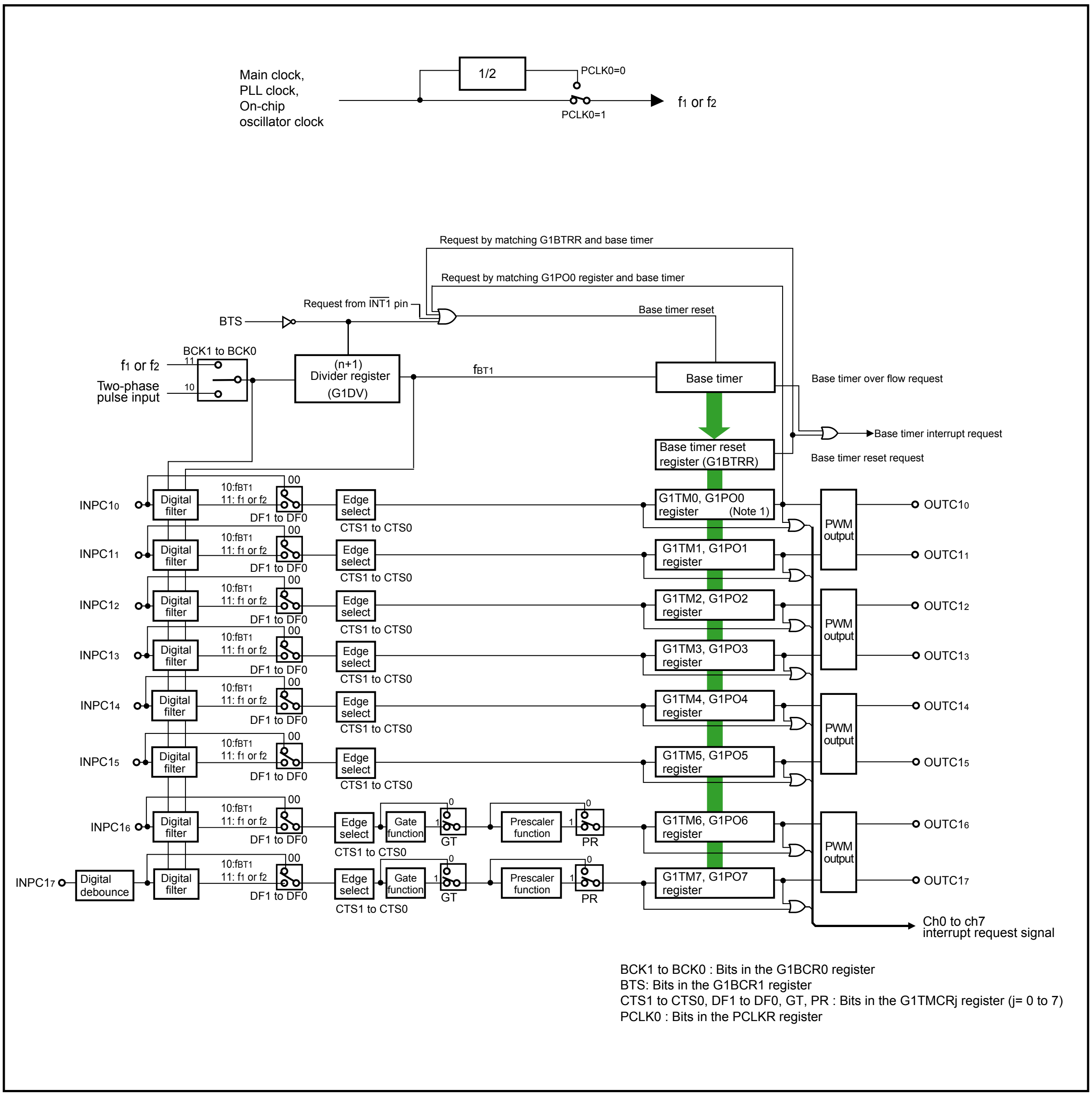


Figure 13.1 IC/OC Block Diagram

Figures 13.2 to **13.10** show registers associated with the IC/OC base timer, the time measurement function, and the waveform generating function.

Base Timer Register[1]

b15 (b7) b8 (b0) b7 b0

Symbol	Address	After Reset
G1BT	0321_{16} - 0320_{16}	Undefined

Function	Setting Range	RW
• When the base timer is operating: When read, the value of base timer plus 1 can be read. When write, the counter starts counting from the value written. When the base timer is reset, this register is set to 0000_{16}. [2] • When the base timer is reset: This register is set to 0000_{16} but a value read is undefined. No value is written. [2]	0000_{16} to $FFFF_{16}$	RW

NOTES:
1. The G1BT register reflects the value of the base timer, synchronizing with the count source f_{BT1} cycles.
2. This base timer stops only when bits BCK1 to BCK0 in the G1BCR0 register are set to 00_2 (count source clock stop). The base timer operates when bits BCK1 to BCK0 are set to other than 00_2. When the BTS bit in the G1BCR1 register is set to 0, the base timer is reset continuously, and remaining set to 0000_{16}. When the BTS bit is set to 1, this state is cleared and the timer starts counting.

Base Timer Control Register 0

b7	b6	b5	b4	b3	b2	b1	b0
		0	0	0			

Symbol	Address	After Reset
G1BCR0	0322_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
BCK0	Count source select bit	b1b0 0 0: Clock stop 0 1: Do not set to this value 1 0: Two-phase input [1] 1 1: f_1 or f_2 [2]	RW
BCK1			RW
RST4	Base timer reset cause select bit 4	0: Do not reset Base timer by matching G1BTRR 1: Reset Base timer by matching G1BTRR[3]	RW
— (b5-b3)	Reserved bit	Set to 0	RW
CH7INSEL	Channel 7 input select bit	0: $P2_7$/OUTC1_7/INPC1_7 pin 1: $P1_7$/$\overline{INT5}$/INPC1_7/IDU pin	RW
IT	Base timer interrupt select bit	0: Bit 15 in the base timer overflows 1: Bit 14 in the base timer overflows	RW

NOTES:
1. This setting can be used when bits UD1 to UD0 in the G1BCR1 register are set to 10_2 (two-phase signal processing mode). Do not set bits BCK1 and BCK0 to 10_2 in other modes.
2. When the PCLK0 bit in the PCLKR register is set to 0, the count source is f_2 cycles. And when the PCLK0 bit is set to set to 1, the count source is f_1 cycles.
3. When the RST4 bit is set to 1, set the RST1 bit in the G1BCR1 register to 0.

Figure 13.2 G1BT and G1BCR0 Registers

Divider Register

b7	b6	b5	b4	b3	b2	b1	b0

Symbol: G1DV Address: 032A16 After Reset: 0016

Function	Setting range	RW
Divide f1, f2 or two-phase pulse input by (n+1) for fBT1 clock cycles generation. n: the setting value of the G1DV register	0016 to FF16	RW

Base Timer Control Register 1

b7	b6	b5	b4	b3	b2	b1	b0
0				0			0

Symbol: G1BCR1 Address: 032316 After Reset: 0016

Bit Symbol	Bit Name	Function	RW
(b0)	Reserved bit	Set to 0	RW
RST1	Base timer reset cause select bit 1	0: The base timer is not reset by matching the G1PO0 register 1: The base timer is reset by matching with the G1PO0 register (1)	RW
RST2	Base timer reset cause select bit 2	0: The base timer is not reset by applying "L" to the $\overline{INT1}$ pin 1: The base timer is reset by applying "L" to the $\overline{INT1}$ pin	RW
(b3)	Reserved bit	Set to 0	RW
BTS	Base timer start bit	0: Base timer is reset 1: Base timer starts counting	RW
UD0	Counter increment/ decrement control bit	b6b5 0 0: Counter increment mode 0 1: Counter increment/decrement mode 1 0: Two-phase pulse signal processing mode 1 1: Do not set to this value	RW
UD1			RW
(b7)	Reserved bit	Set to 0	RW

NOTS:
1. The base timer is reset two fBT1 clock cycles after the base timer matches the value set in the G1PO0 register. (See **Figure 13.7** for details on the G1PO0 register) When the RST1 bit is set to 1, the value of the G1POj register (j=1 to 7) for the waveform generating function must be set to a value smaller than that of the G1PO0 register.
When the RST1 bit is set to 1, set the RST4 bit in the G1BCR0 register to 0.

Figure 13.3 G1DV Register and G1BCR1 Register

Base Timer Reset Register[1]

b15 (b7) b8 (b0) b7 b0

Symbol	Address	After Reset
G1BTRR	0329_{16} - 0328_{16}	Undefined

Function	Setting Range	RW
When enabled by the RST4 bit in the G1BCR0 register, the base timer is reset by matching the G1BTRR register setting value and the base timer setting value.	0000_{16} to $FFFF_{16}$	RW

NOTE:
1. The G1BTRR register reflects the value of the base timer, synchronizing with the count source f_{BT1} cycles.

Figure 13.4 G1BTRR Register

Time Measurement Control Register j (j=0 to 7)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
G1TMCR0 to G1TMCR3	0318_{16}, 0319_{16}, $031A_{16}$, $031B_{16}$	00_{16}
G1TMCR4 to G1TMCR7	$031C_{16}$, $031D_{16}$, $031E_{16}$, $031F_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
CTS0	Time measurement trigger select bit	b1 b0 0 0: No time measurement 0 1: Rising edge 1 0: Falling edge 1 1: Both edges	RW
CTS1			RW
DF0	Digital filter function select bit	b3 b2 0 0: No digital filter 0 1: Do not set to this value 1 0: f_{BT1} 1 1: f_1 or f_2 (1)	RW
DF1			RW
GT	Gate function select bit (2)	0: Gate function is not used 1: Gate function is used	RW
GOC	Gate function clear select bit (2, 3, 4)	0: Not cleared 1: The gate is cleared when the base timer matches the G1POk register	RW
GSC	Gate function clear bit (2, 3)	The gate is cleared by setting the GSC bit to 1	RW
PR	Prescaler function select bit (2)	0: Not used 1: Used	RW

NOTES:
1. When the PCLK0 bit in the PCLKR register is set to 0, the count source is f_2 cycles. And when the PCLK0 bit is set to 1, the count source is f_1 cycles.
2. These bits are in registers G1TMCR6 and G1TMCR7. Set all bits 4 to 7 in registers G1TMCR0 to G1TMCR5 to 0.
3. These bits are enabled when the GT bit is set to 1.
4. The GOC bit is set to 0 after the gate function is cleared. See **Figure 13.7** for details on the G1POk register (k=4 when j=6 and k=5 when j=7).

Time Measurement Prescale Register j (j=6,7)(1)

b7 b0

Symbol	Address	After Reset
G1TPR6 to G1TPR7	0324_{16}, 0325_{16}	00_{16}

Function	Setting Range	RW
As the setting value is n, time is measured whenever a trigger input is counted by *n+1* (2)	00_{16} to FF_{16}	RW

NOTES:
1. The G1TPR6 to G1TPR7 registers reflect the base timer value, synchronizing with the count source f_{BT1} cycles.
2. The first prescaler, after the PR bit in the G1TMCRj register is changed from 0 (not used) to 1 (used), may be divided by *n*, rather than *n+1*. The subsequent prescaler is divided by *n+1*.

Figure 13.5 G1TMCR0 to G1TMCR7 Registers, and G1TPR6 to G1TPR7 Registers

Waveform Generation Register j (j=0 to 7)

b15 (b7) b8 (b0) b7 b0

Symbol	Address	After Reset
G1TM0 to G1TM2	0301_{16}-0300_{16}, 0303_{16}-0302_{16}, 0305_{16}-0304_{16}	Indeterminte
G1TM3 to G1TM5	0307_{16}-0306_{16}, 0309_{16}-0308_{16}, $030B_{16}$-$030A_{16}$	Indeterminte
G1TM6 to G1TM7	$030D_{16}$-$030C_{16}$, $030F_{16}$-$030E_{16}$	Indeterminte

Function	Setting Range	RW
The base timer value is stored every measurement timing	————	RO

Waveform Generation Control Register j (j=0 to 7)

b7 b6 b5 b4 b3 b2 b1 b0

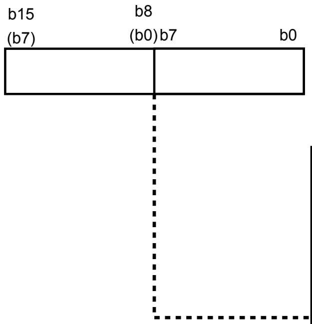
Symbol	Address	After Reset
G1POCR0 to G1POCR3	0310_{16}, 0311_{16}, 0312_{16}, 0313_{16}	$0X00\ XX00_2$
G1POCR4 to G1POCR7	0314_{16}, 0315_{16}, 0316_{16}, 0317_{16}	$0X00\ XX00_2$

Bit Symbol	Bit Name	Function	RW
MOD0	Operating mode select bit	b1b0 0 0: Single waveform output mode 0 1: SR waveform output mode (1) 1 0: Phase-delayed waveform output mode 1 1: Do not set to this value	RW
MOD1			RW
——— (b3-b2)	Nothing is assigned. If necessary, set to 0. When read, their contents are undefined		—
IVL	Output initial value select bit(4)	0: "L" output as a default value 1: "H" output as a default value	RW
RLD	G1POj register value reload timing select bit	0: Reloads the G1POj register when value is written 1: Reloads the G1POj register when the base timer is reset	RW
——— (b6)	Nothing is assigned. If necessary, set to 0. When read, its content is undefined		—
INV	Inverse output function select bit (2)	0: Output is not inversed 1: Output is inversed	RW

NOTES :
1. This setting is enabled only for even channels. In SR waveform output mode, values written to the corresponding odd channel (next channel after an even channel) are ignored. Even channels provide waveform output. Odd channels provide no waveform output.
2. The inverse output function is the final step in waveform generating process. When the INV bit is set to 1, and "H" signal is provided a default output by setting the IVL bit to 0, and an "L" signal is provided by setting it to 1.
3. In the SR waveform output mode, set not only the even channel but also the correspoinding even channel (next channel after the even channel).
4. To provide either "H" or "L" signal output set in the IVL bit, set the FSCj bit in the G1FS register to 0 (select waveform generating function) and IFEj bit in the G1FE register to 1 (functions for channel j enabled). Then set the IVL bit to 0 or 1.

Figure 13.6 G1TM0 to G1TM7 Registers, and G1POCR0 to G1POCR7 Registers

Waveform Generation Register j (j=0 to 7)



Symbol	Address	After Reset
G1PO0 to G1PO2	0301$_{16}$-0300$_{16}$, 0303$_{16}$-0302$_{16}$, 0305$_{16}$-0304$_{16}$	Undefined
G1PO3 to G1PO5	0307$_{16}$-0306$_{16}$, 0309$_{16}$-0308$_{16}$, 030B$_{16}$-030A$_{16}$	Undefined
G1PO6 to G1PO7	030D$_{16}$-030C$_{16}$, 030F$_{16}$-030E$_{16}$	Undefined

Function	Setting Range	RW
• When the RLD bit in the G1POCRj register is set to 0, value written is immediately reloaded into the G1POj register for output, for example, a waveform output,reflecting the value. • When the RLD bit is set to 1, value reloaded while the base timer is reset. The value written can be read until reloaded	0000$_{16}$ to FFFF$_{16}$	RW

Figure 13.7 G1PO0 to G1PO7 Registers

Function Select Register

b7	b6	b5	b4	b3	b2	b1	b0

Symbol: G1FS | Address: 0327₁₆ → 0327_{16} | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
FSC0	Channel 0 time measurement/waveform generating function select bit	0: Select the waveform generating function 1: Select the time measurement function	RW
FSC1	Channel 1 Time Measurement/Waveform Generating Function Select Bit		RW
FSC2	Channel 2 time measurement/waveform generating function select bit		RW
FSC3	Channel 3 time measurement/waveform generating function select bit		RW
FSC4	Channel 4 time measurement/waveform generating function select bit		RW
FSC5	Channel 5 time measurement/waveform generating function select bit		RW
FSC6	Channel 6 time measurement/waveform generating function select bit		RW
FSC7	Channel 7 time measurement/waveform generating function select bit		RW

Function Enable Register(1)

b7	b6	b5	b4	b3	b2	b1	b0

Symbol: G1FE | Address: 0326_{16} | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
IFE0	Channel 0 function enable bit	0 : Disable function s for channel j (2) 1 : Enable functions for channel j (j=0 to 7)	RW
IFE1	Channel 1 function enable bit		RW
IFE2	Channel 2 function enable bit		RW
IFE3	Channel 3 function enable bit		RW
IFE4	Channel 4 function enable bit		RW
IFE5	Channel 5 function enable bit		RW
IFE6	Channel 6 function enable bit		RW
IFE7	Channel 7 function enable bit		RW

NOTES:
1. The G1FE register reflects the base timer value, synchronizing with the count source f_{BT1} cycles.
2. When functions for the channel j are disabled, each pin functions as an I/O port.

Figure 13.8 G1FS and G1FE Registers

Interrupt Request Register (1)

b7	b6	b5	b4	b3	b2	b1	b0

Symbol	Address	After Reset
G1IR	0330_{16}	Undefined

Bit Symbol	Bit Name	Function	RW
G1IR0	Interrupt request, Ch0	0 : No interrupt request 1 : Interrupt requested	RW
G1IR1	Interrupt request, Ch1		RW
G1IR2	Interrupt request, Ch2		RW
G1IR3	Interrupt request, Ch3		RW
G1IR4	Interrupt request, Ch4		RW
G1IR5	Interrupt request, Ch5		RW
G1IR6	Interrupt request, Ch6		RW
G1IR7	Interrupt request, Ch7		RW

NOTE:
1. When writing 0 to each bit in the G1IR register, use the following instruction:
AND, BCLR

Figure 13.9 G1IR Register

Interrupt Enable Register 0

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
G1IE0	0331_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
G1IE00	Interrupt enable 0, CH0	0 : IC/OC interrupt 0 request disable 1 : IC/OC interrupt 0 request enable	RW
G1IE01	Interrupt enable 0, CH1		RW
G1IE02	Interrupt enable 0, CH2		RW
G1IE03	Interrupt enable 0, CH3		RW
G1IE04	Interrupt enable 0, CH4		RW
G1IE05	Interrupt enable 0, CH5		RW
G1IE06	Interrupt enable 0, CH6		RW
G1IE07	Interrupt enable 0, CH7		RW

Interrupt Enable Register 1

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
G1IE1	0332_{16}	00_{16}

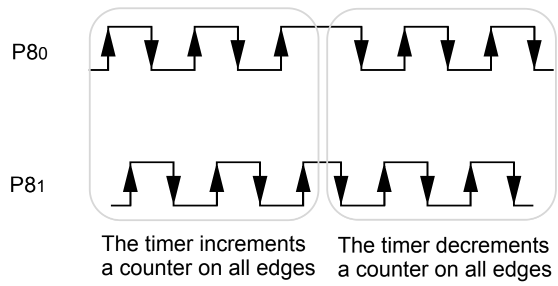
Bit Symbol	Bit Name	Function	RW
G1IE10	Interrupt enable 1, CH0	0 : IC/OC interrupt 1 request disable 1 : IC/OC interrupt 1 request enable	RW
G1IE11	Interrupt enable 1, CH1		RW
G1IE12	Interrupt enable 1, CH2		RW
G1IE13	Interrupt enable 1, CH3		RW
G1IE14	Interrupt enable 1, CH4		RW
G1IE15	Interrupt enable 1, CH5		RW
G1IE16	Interrupt enable 1, CH6		RW
G1IE17	Interrupt enable 1, CH7		RW

Figure 13.10 G1IE0 and G1IE1 Registers

13.1 Base Timer

The base timer is a free-running counter that counts an internally generated count source.
Table 13.2 lists specifications of the base timer. **Table 13.3** shows registers associated with the base timer. **Figure 13.11** shows a block diagram of the base timer. **Figure 13.12** shows an example of the base timer in counter increment mode. **Figure 13.13** shows an example of the base timer in counter increment/decrement mode. **Figure 13.14** shows an example of two-phase pulse signal processing mode.

Table 13.2 Base Timer Specifications

Item	Specification
Count source(f_{BT1})	f_1 or f_2 divided by *(n+1)*, two-phase pulse input divided by *(n+1)* n: determined by the DIV7 to DIV0 bits in the G1DV register. n=0 to 255 However, no division when n=0
Counting operation	The base timer increments the counter value The base timer increments/decrements the counter value Two-phase pulse signal processing
Count start condition	The BTS bit in the G1BCR1 register is set to 1 (base timer starts counting)
Count stop condition	The BTS bit in the G1BCR1 register is set to 0 (base timer reset)
Base timer reset condition	(1) The value of the base timer matches the value of the G1BTRR register (2) The value of the base timer matches the value of G1PO0 register. (3) Apply a low-level signal ("L") to external interrupt pin, $\overline{INT1}$ pin
Value for base timer reset	0000_{16}
Interrupt request	The base timer interrupt request is generated: (1) When the bit 14 or bit 15 in the base timer overflows (2) The value of the base timer value matches the value of the base timer reset register
Read from timer	• The G1BT register indicates a counter value while the base timer is running • The G1BT register is undefined when the base timer is reset
Write to timer	When a value is written while the base timer is running, the timer counter immediately starts counting from this value. No value can be written while the base timer is reset.
Selectable function	• Counter increment/decrement mode The base timer starts counting from 0000_{16}. After incrementing to $FFFF_{16}$, the timer counter is then decremented back to 0000_{16}. The base timer increments the counter value again when the timer counter reaches 0000_{16}. (See **Figure 13.13**) • Two-phase pulse processing mode Two-phase pulse signals from pins $P8_0$ and $P8_1$ are counted (See **Figure 13.14**) 

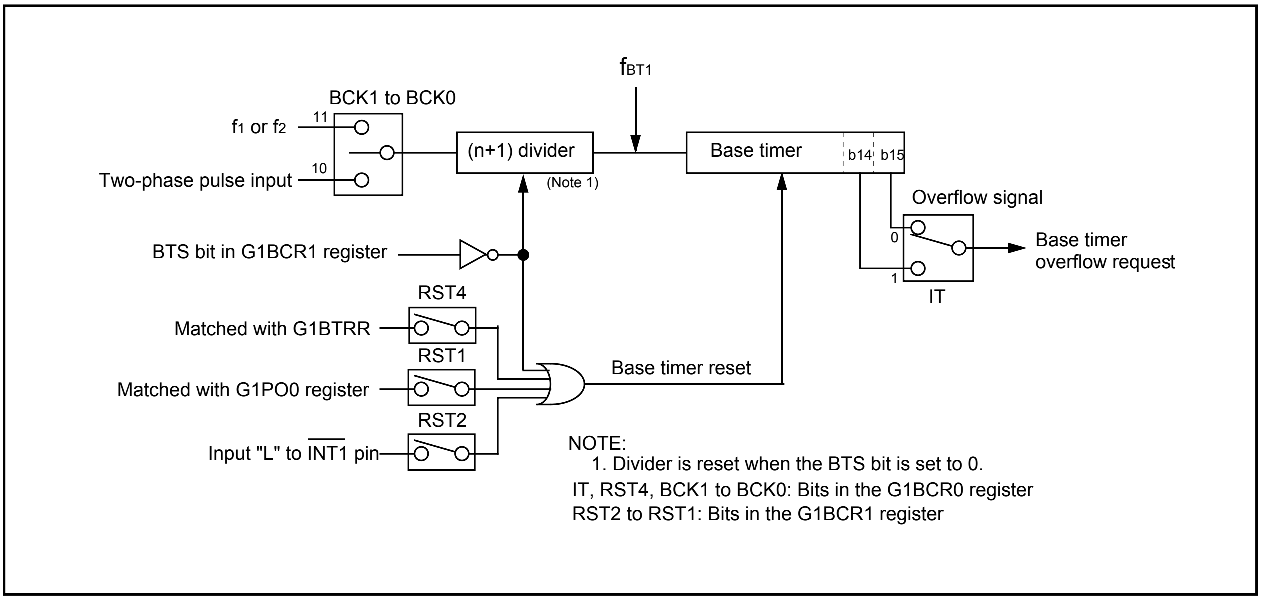


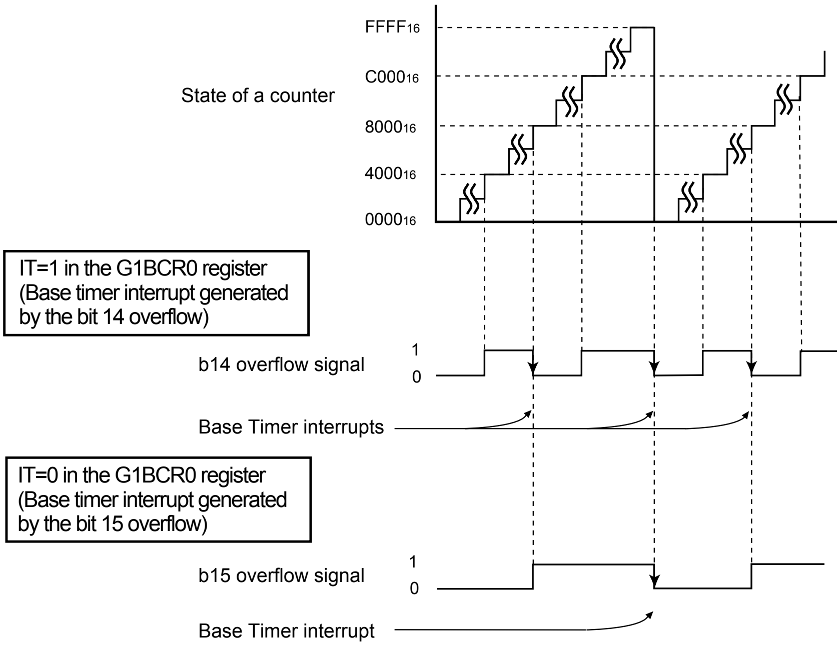
Figure 13.11 Base Timer Block Diagram

Table 13.3 Base Timer Associated Register Settings (Time Measurement Function, Waveform Generation Function, Communication Function)

Register	Bit	Function
G1BCR0	BCK1 to BCK0	Select a count source
	RST4	Select base timer reset timing
	IT	Select the base timer overflow
G1BCR1	RST2 to RST1	Select base timer reset timing
	BTS	Used to start the base timer
	UD1 to UD0	Select how to count
G1BT	-	Read or write base timer value
G1DV	-	Divide ratio of a count source

Set the following registers to set the RST1 bit to 1 (base timer reset by matching the base timer with the G1PO0 register)

G1POCR0	MOD1 to MOD0	Set to 00_2 (single-phase waveform output mode)
G1PO0	-	Set reset cycle
G1FS	FSC0	Set to 0 (waveform generating function)
G1FE	IFE0	Set to 1 (channel operation start)



The above applies to the following conditions.
- The RST4 bit in the G1BCR0 register is set to 0 (the base timer is not reset by matching the G1BTRR register)
- The RST1 bit in the G1BCR1 register is set to 0 (the base timer is not reset by matching the G1PO0 register)
- Bits UD1 to UD0 in the G1BCR1 register are set to 00_2 (counter increment mode)

Figure 13.12 Counter Increment Mode

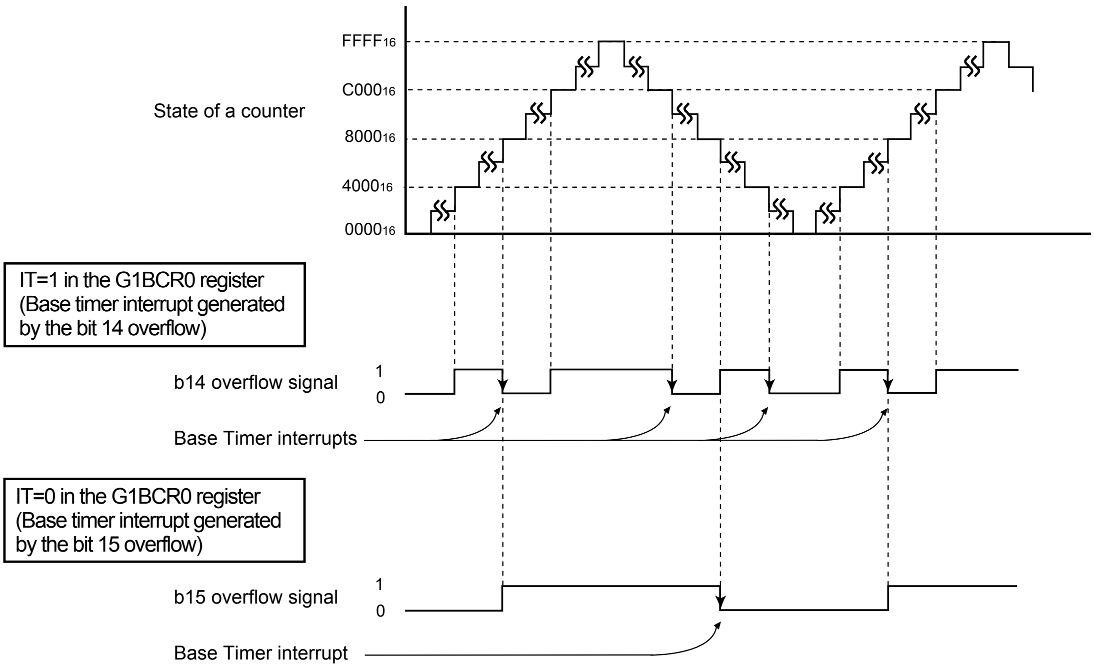
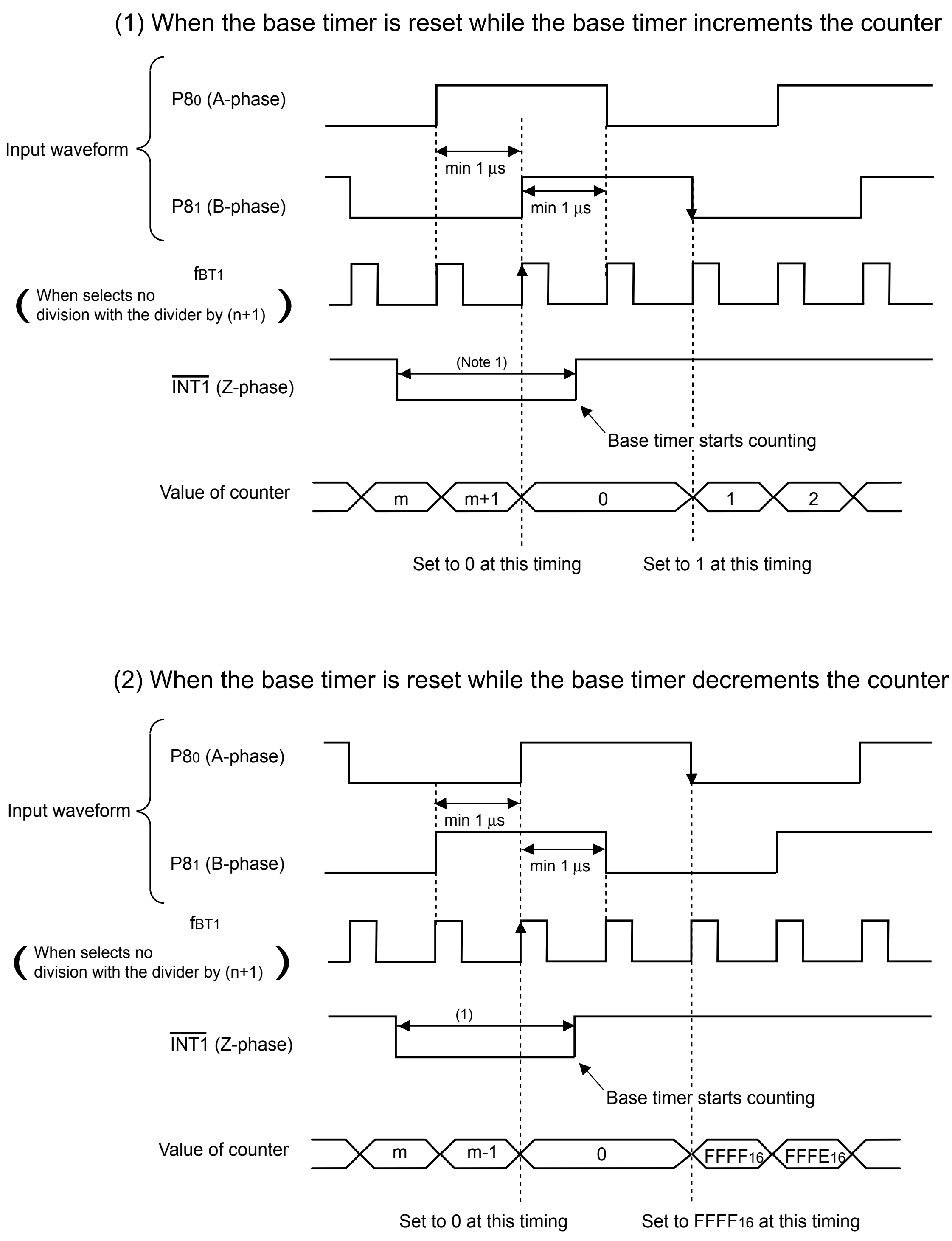


Figure 13.13 Counter Increment/Decrement Mode

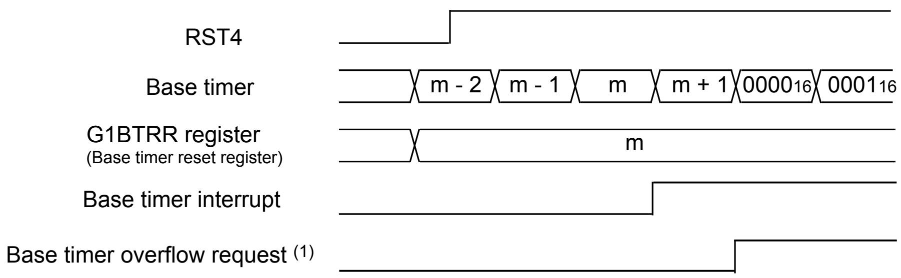


NOTE:
1. 1.5 f_{BT1} clock cycle or more are required.

Figure 13.14 Base Timer Operation in Two-phase Pulse Signal Processing Mode

13.1.1 Base Timer Reset Register(G1BTRR)

The G1BTRR register provides the capability to reset the base timer when the base timer count value matches the value stored in the G1BTRR register. The G1BTRR register is enabled by the RST4 bit in the G1BCR0 register. This function is identical in operation to the G1PO0 base timer reset that is enabled by the RST1 bit in the G1BCR0 reigster. If the free-running operation is not selected, the channel 0 can be used for a waveform generation when the base timer is reset by the G1BTRR register. Do not enable bits RST1 and RST4 simultaneously.



NOTE:
1. Following conditions are required to generate a base timer overflow request by resetting the base timer.
If the IT bit is set to 0: $07FFF_{16} \le m \le 0FFFE_{16}$
If the IT bit is set to 1: $07FFF_{16} \le m \le 0FFFE_{16}$ or $0BFFF_{16} \le m \le 0FFFE_{16}$

Figure 13.15 Base Timer Reset operation by Base Timer Reset Register

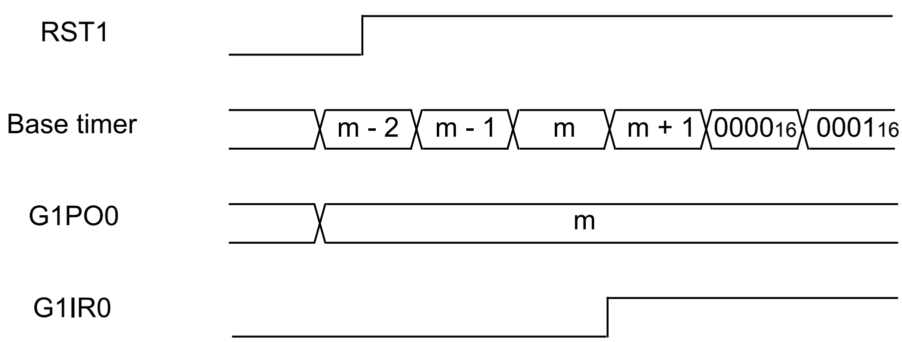
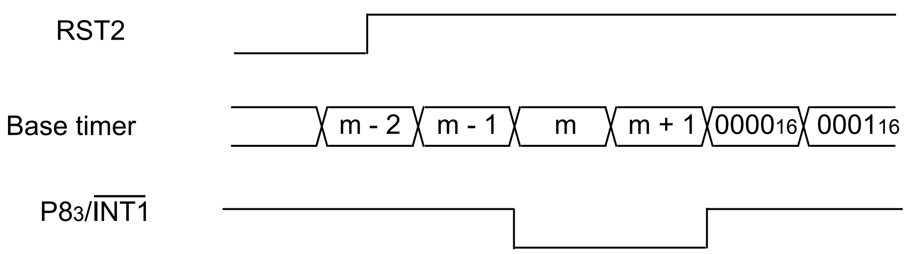


Figure 13.16 Base Timer Reset operation by G1PO0 register



NOTE:
1. $\overline{\text{INT1}}$ Base Timer reset does not generate a Base Timer interrupt. $\overline{\text{INT1}}$ may generate an interrupt if enabled.

Figure 13.17 Base Timer Reset operation by $\overline{\text{INT1}}$

13.2 Interrupt Operation

The IC/OC interrupt contains several request causes. **Figure 13.18** shows the IC/OC interrupt block diagram and **Table 13.4** shows the IC/OC interrupt assignation.

When either the base timer reset request or base timer overflow request is generated, the IR bit in the BTIC register corresponding to the IC/OC base timer interrupt is set to 1 (with an interrupt request). Also when an interrupt request in each eight channels (channel i) is generated, the bit i in the G1IR register is set to 1 (with an interrupt request). At this time, if the bit i in the G1IE0 register is 1 (IC/OC interrupt 0 request enabled), the IR bit in the ICOC0IC register corresponding to the IC/OC interrupt 0 is set to 1 (with an interrupt request). And if the bit i in the G1IE1 register is 1 (IC/OC interrupt 1 request enabled), the IR bit in the ICOC1IC register corresponding to the IC/OC interrupt 1 is set to 1(with an interrupt request).

Additionally, because each bit in the G1IR register is not automatically set to 0 even if the interrupt is acknowledged, set to 0 by program. If these bits are left as 1, all IC/OC channel interrupt causes, which are generated after setting the IR bit to 1, will be disabled.

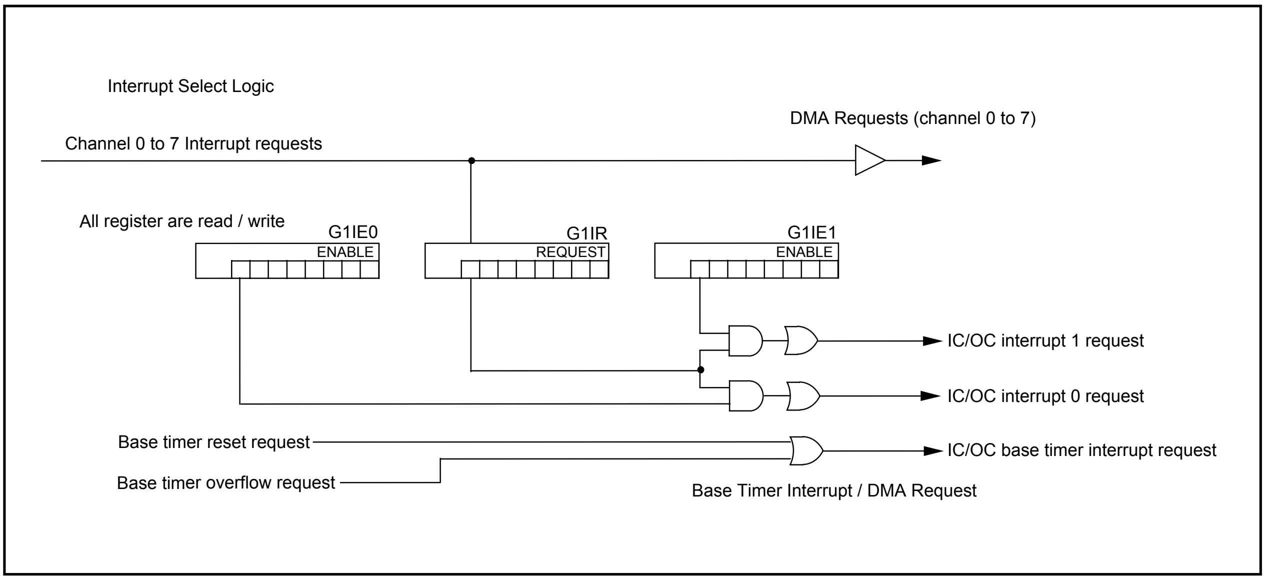


Figure 13.18 IC/OC Interrupt and DMA request generation

Table 13.4 Interrupt Assignment

Interrupt	Interrupt control register
IC/OC base timer interrupt	BTIC(0047_{16})
IC/OC interrupt 0	ICOC0IC(0045_{16})
IC/OC interrupt 1	ICOC0IC(0046_{16})

13.3 DMA Support

Each of the interrupt sources - the eight IC/OC channel interrupts and the one Base Timer interrupt - are capable of generating a DMA request.

13.4 Time Measurement Function

In synchronization with an external trigger input, the value of the base timer is stored into the G1TMj register (j=0 to 7). **Table 13.5** shows specifications of the time measurement function. **Table 13.6** shows register settings associated with the time measurement function. **Figures 13.19** and **13.20** display operational timing of the time measurement function. **Figure 13.21** shows operational timing of the prescaler function and the gate function.

Table 13.5 Time Measurement Function Specifications

Item	Specification
Measurement channel	Channels 0 to 7
Selecting trigger input polarity	Rising edge, falling edge, both edges of the INPC1j pin (1)
Measurement start condition	The IFEj bit in the G1FE register should be set to 1 (channels j function enabled) when the FSCj bit (j=0 to 7) in the G1FS register is set to 1 (time measurement function selected).
Measurement stop condition	The IFEj bit should be set to 0 (channel j function disabled)
Time measurement timing	•No prescaler : every time a trigger signal is applied •Prescaler (for channel 6 and channel 7): every *G1TPRk (k=6,7) register value +1* times a trigger signal is applied
Interrupt request generation timing	The G1IRi bit (i=0 to 7) in the interrupt request register (See **Figure 13.9**) is set to 1 at time measurement timing
INPC1j pin function (1)	Trigger input pin
Selectable function	• Digital filter function The digital filter samples a trigger input signal level every f_1, f_2 or f_{BT1} cycles and passes pulse signal matching trigger input signal level three times • Prescaler function (for channel 6 and channel 7) Time measurement is executed every *G1TPRk register value +1* times a trigger signal is applied • Gate function (for channel 6 and channel 7) After time measurement by the first trigger input, trigger input cannot be accepted. However, while the GOC bit in the G1TMCRk register is set to 1 (gate cleared by matching the base timer with the G1POp register (p=4 when k=6, p=5 when k=7)), trigger input can be accepted again by matching the base timer value with the G1POp register setting • Digital Debounce function (for channel7) See **13.6.2 Digital Debounce Function for P17/$\overline{\text{INT5}}$/INPC17** and **19.6 Digital Debounce Function** for details

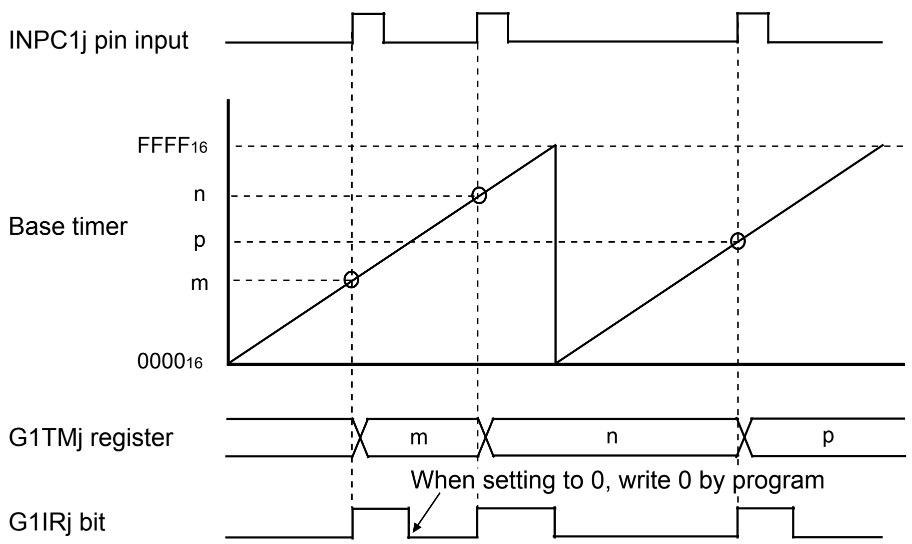
NOTE:

1. The INPC10 to INPC17 pins

Table 13.6 Register Settings Associated with the Time Measurement Function

Register	Bit	Function
G1TMCRj	CTS1 to CTS0	Select time measurement trigger
	DF1 to DF0	Select the digital filter function
	GT, GOC, GSC	Select the gate function
	PR	Select the prescaler function
G1TPRk	-	Setting value of prescaler
G1FS	FSCj	Set to 1 (time measurement function)
G1FE	IFEj	Set to 1 (channel j function enabled)

j = 0 to 7 k = 6, 7
Bit configurations and function varys with channels used.
Registers associated with the time measurement function must be set after setting registers associated with the base timer.



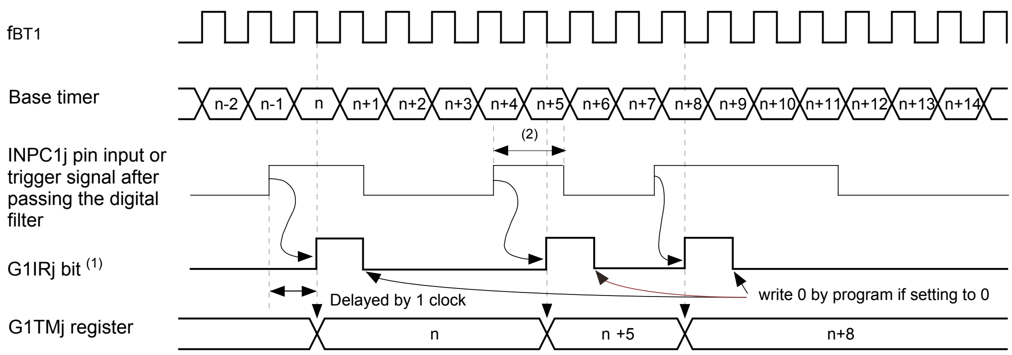
j = 0 to 7
G1IRj bit: Bits in the G1IR register

The above applies to the following condition.
- Bits CTS1 to CTS0 in the G1TMCRj registers are set to 01_2 (rising edge). The PR bit is set to 0 (no prescaler used) and the GT bit is set to 0 (no gate function used).
- Bits RTS4, RTS2, and RTS1 in registers G1BCR0 and G1BCR1 are set to 0 (no base timer reset). Bits UD1 to UD0 bits are set to 00_2 (counter increment mode).

Set the base timer to 0000_{16} (setting the RST1 bit to 1, and bits RST4 and RST2 to 0), when the base timer value matches the G1PO0 register setting. The base timer is set to 0000_{16} after it reaches *the G1PO0 register value + 2*.

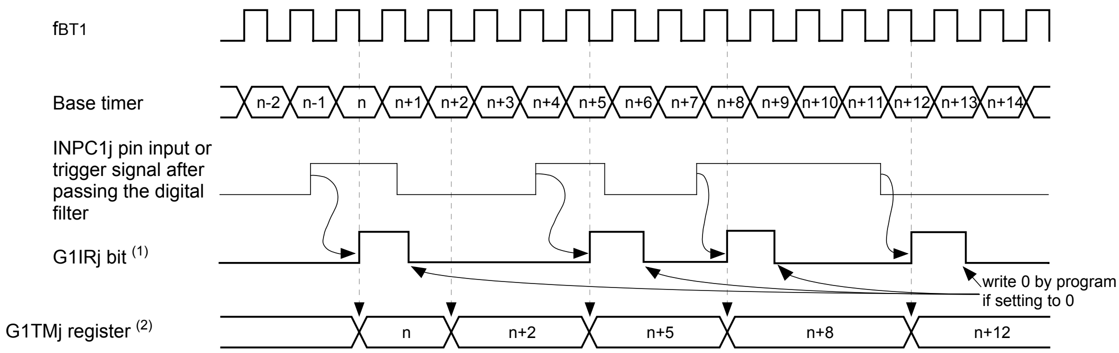
Figure 13.19 Time Measurement Function (1)

(a) When selecting the rising edge as a timer measurement trigger
(Bits CTS1 and CTS0 in the G1TMCRj register (j=0 to 7)=01_2)



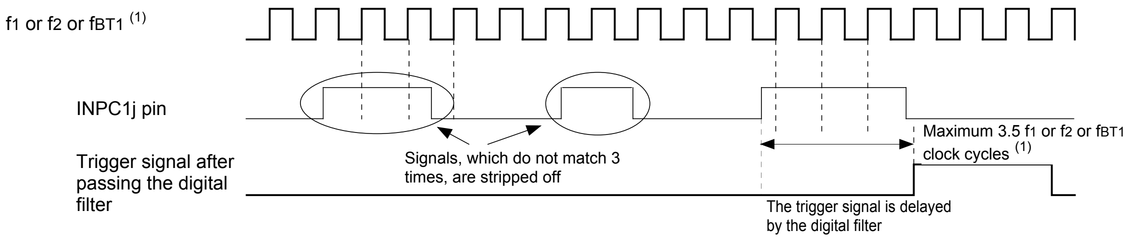
NOTES :
1. Bits in the G1IR register.
2. Input pulse applied to the INPC1j pin requires 1.5 fBT1 clock cycles or more.

(b) When selecting both edges as a timer measurement trigger
(Bits CTS1 and CTS0 = 11_2)



NOTES :
1. Bits in the G1IR register.
2. No interrupt is generated if the MCU receives a trigger signal when the G1IRj bit is set to 1.
However, the value of the G1TMj register is updated.

(c) Trigger signal when using digital filter
(Bits DF1 to DF0 in the G1TMCRj register =10_2 or 11_2)



NOTE:
1. fBT1 when bits DF1 to DF0 are set to 10_2, and f1 or f2 when set to 11_2.

Figure 13.20 Time Measurement Function (2)

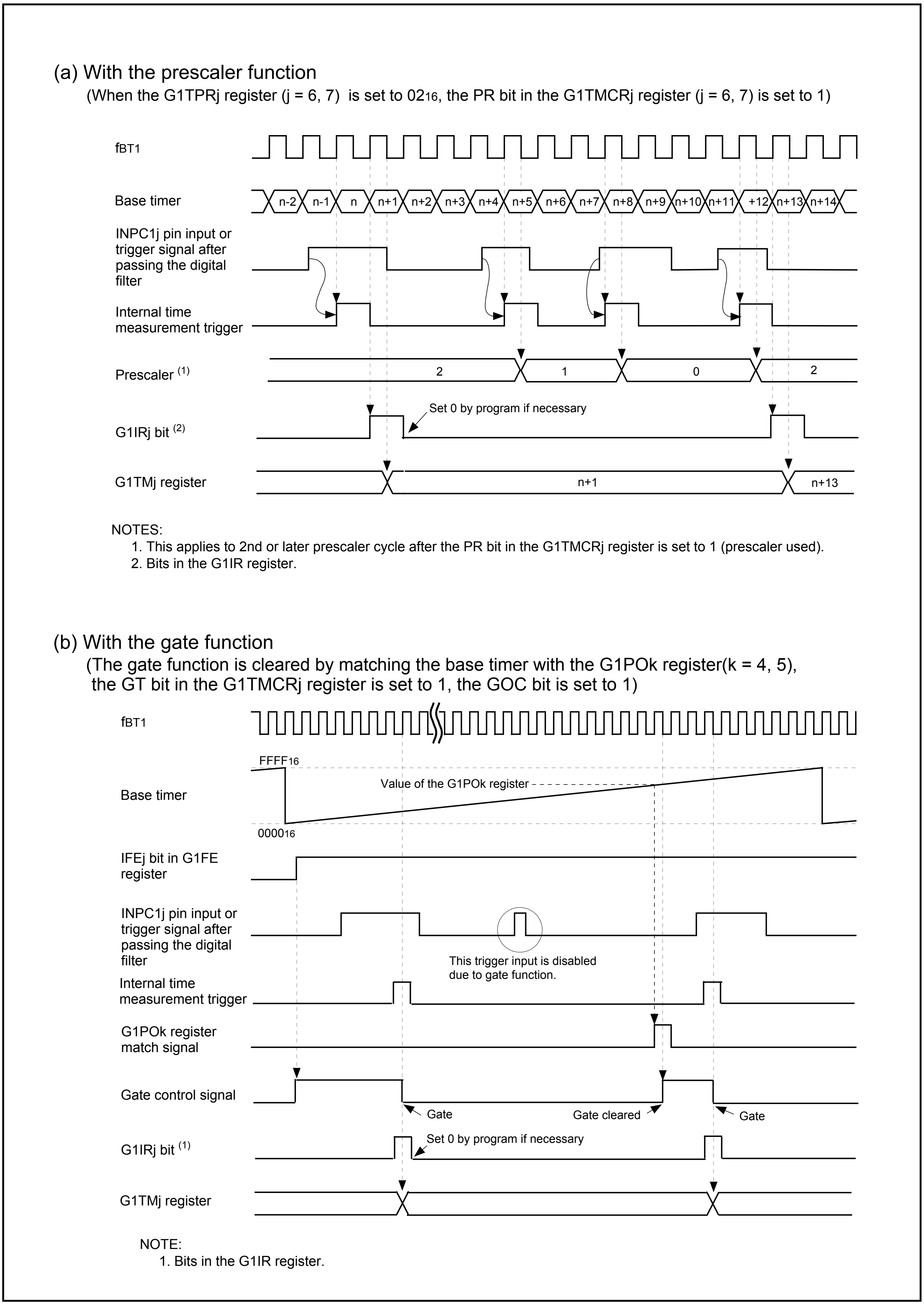


Figure 13.21 Prescaler Function and Gate Function

13.5 Waveform Generating Function

Waveforms are generated when the base timer value matches the G1POj (j=0 to 7) register value.

The waveform generating function has the following three modes :

- Single-phase waveform output mode
- Phase-delayed waveform output mode
- Set/Reset waveform output (SR waveform output) mode

Table 13.7 lists registers associated with the waveform generating function.

Table 13.7 Registers Related to the Waveform Generating Function Settings

Register	Bit	Function
G1POCRj	MOD1 to MOD0	Select output waveform mode
	IVL	Select default value
	RLD	Select G1POj register value reload timing
	INV	Select inverse output
G1POj	-	Select timing to output waveform inverted
G1FS	FSCj	Set to 0 (waveform generating function)
G1FE	IFEj	Set to 1 (enables function on channel j)

j = 0 to 7

Bit configurations and functions vary with channels used.

Registers associated with the waveform generating function must be set after setting registers associated with the base timer.

13.5.1 Single-Phase Waveform Output Mode

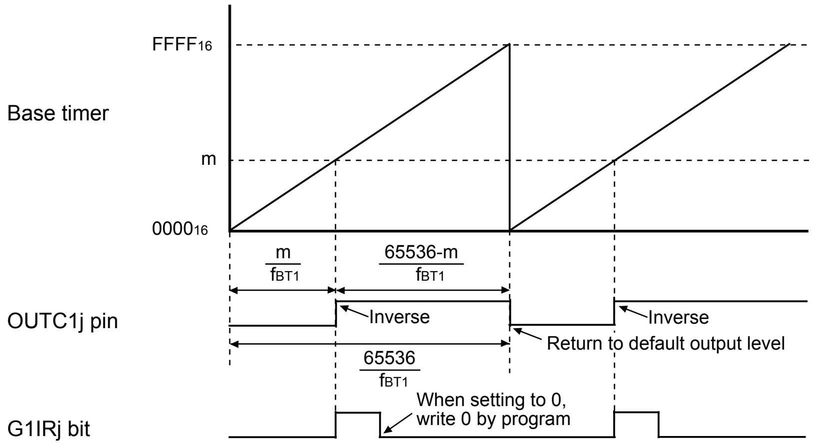
Output signal level of the OUTC1j pin becomes high ("H") when the INV bit in the G1POCRj (j=0 to 7) register is set to 0(output is not reversed) and the base timer value matches the G1POj (j=0 to 7) register value. The "H" signal switches to a low-level ("L") signal when the base timer reaches 0000_{16}. **Table 13.8** lists specifications of single-phase waveform mode. **Figure 13.22** lists an example of single-phase waveform mode operation.

Table 13.8 Single-phase Waveform Output Mode Specifications

Item	Specification
Output waveform	• Free-running operation (bits RST1, RST2, and RST4 of registers G1BCR1 and G1BCR0 are set to 0 (no reset)) Cycle : $\frac{65536}{f_{BT1}}$ Default output level width : $\frac{m}{f_{BT1}}$ Inverse level width : $\frac{65536-m}{f_{BT1}}$ • The base timer is cleared to 0000_{16} by matching the base timer with either following register (a) G1PO0 register (enabled by setting RST1 bit to 1, and RST4 and RST2 bits to 0), or (b) G1BTRR register (enabled by setting RST4 bit to 1, and RST2 and RST1 bits to 0) Cycle : $\frac{n+2}{f_{BT1}}$ Default output level width : $\frac{m}{f_{BT1}}$ Inverse level width $\frac{n+2-m}{f_{BT1}}$ m : setting value of the G1POj register (j=0 to 7), 0001_{16} to $FFFD_{16}$ n : setting value of the G1PO0 register or the G1BTRR register, 0001_{16} to $FFFD_{16}$
Waveform output start condition	The IFEj bit in the G1FE register is set to 1 (channel j function enabled)
Waveform output stop condition	The IFEj bit is set to 0 (channel j function disabled)
Interrupt request	The G1IRj bit in the G1IR register is set to 1 when the base timer value matches the G1POj register value (See **Figure 13.22**)
OUTC1j pin (1)	Pulse signal output pin
Selectable function	• Default value set function: Set starting waveform output level • Inverse output function: Waveform output signal is inversed and provided from the OUTC1j pin

NOTE:
1. Pins $OUTC1_0$ to $OUTC1_7$.

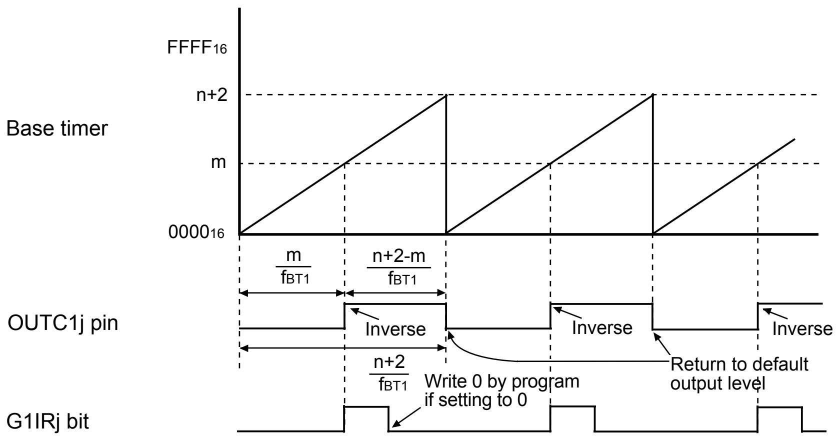
(1) Free-running operation
(The RST4, RST2, and RST1 bits in the G1BCR0 and G1BCR1 registers are set to 0)



j=0 to 7
m : Setting value of the G1POj register
G1IRj bit : Bits in the G1IR register

The above applies under the following conditions.
-The IVL bit in the G1POCRj register is set to 0 ("L" output as a default value) and the INV bit is set to 0 (not inversed).
-Bits UD1 to UD0 are set to 00_2 (counter increment mode).

(2) The base timer is reset when the base timer matches either following register
(a) G1PO0 (enabled by setting bit RST1 to 1, and bits RST4 and RST2 to 0), or
(b) G1BTRR (enabled by setting bit RST4 to 1, and bits RST2 and RST1 to 0)



j=1 to 7
m : Setting value of the G1POj register
n: Setting value of either G1PO0 register or G1BTRR register
G1IRj bit : Bits in the G1IR register

The above applies under the following conditions.
-The IVL bit in the G1POCRj register is set to 0 ("L" output as a default value) and the INV bit is set to 0 (not inversed).
-Bits UD1 to UD0 are set to 00_2 (counter increment mode).

Figure 13.22 Single-phase Waveform Output Mode

13.5.2 Phase-Delayed Waveform Output Mode

Output signal level of the OUTC1j pin is inversed every time the base timer value matches the G1POj register value (j=0 to 7). **Table 13.9** lists specifications of phase-delayed waveform mode. **Figure 13.23** shows an example of phase-delayed waveform mode operation.

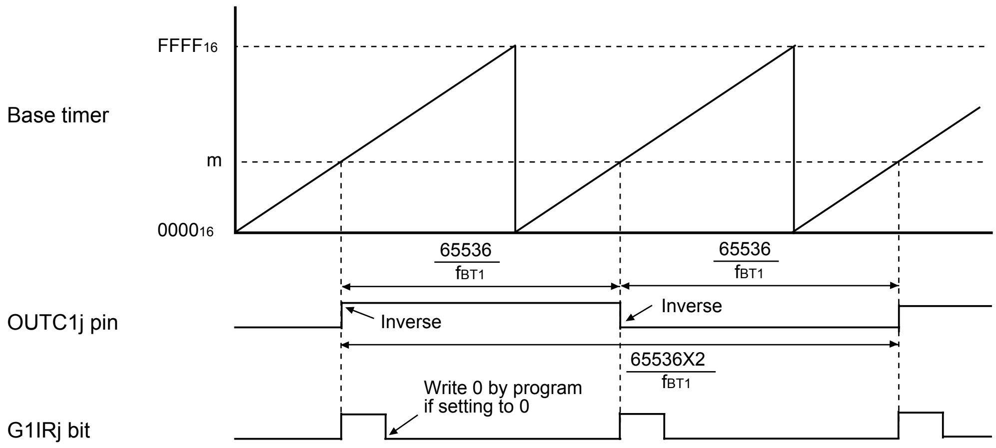
Table 13.9 Phase-delayed Waveform Output Mode Specifications

Item	Specification
Output waveform	• Free-running operation (bits RST1, RST2, and RST4 in registers G1BCR1 and G1BCR0 are set to 0 (no reset)) Cycle : $\frac{65536 \times 2}{f_{BT1}}$ "H" and "L" width : $\frac{65536}{f_{BT1}}$ • The base timer is cleared to 0000_{16} by matching the base timer with either following register (a) G1PO0 register (enabled by setting RST1 bit to 1, and bits RST4 and RST2 to 0), or (b) G1BTRR register (enabled by setting RST4 bit to 1, and bits RST2 and RST1 to 0) Cycle : $\frac{2(n+2)}{f_{BT1}}$ "H" and "L" width : $\frac{n+2}{f_{BT1}}$ n : setting value of either G1PO0 register or G1BTRR register
Waveform output start condition	The IFEj bit in the G1FE register is set to 1 (channel j function enabled)
Waveform output stop condition	The IFEj bit is set to 0 (channel j function disabled)
Interrupt request	The G1IRj bit in the interrupt request register is set to 1 when the base timer value matches the G1POj register value. (See **Figure 13.23**)
OUTC1j pin (1)	Pulse signal output pin
Selectable function	• Default value set function: Set starting waveform output level • Inverse output function : Waveform output signal is inversed and provided from the OUTC1j pin

NOTE:
1. Pins $OUTC1_0$ to $OUTC1_7$.

RENESAS

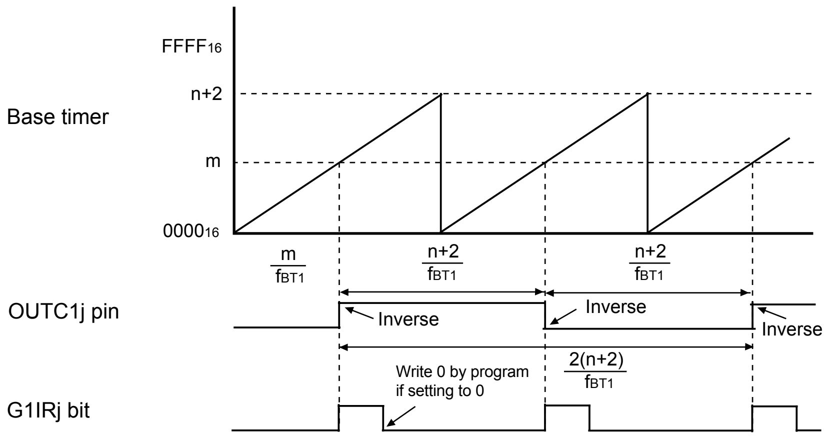
(1) Free-running operation
(Bits RST4, RST2, and RST1 in the registers G1BCR0 and G1BCR1 are set to 0)



j=0 to 7
m : Setting value of the G1POj register
G1IRj bit : Bits in the G1IR register

The above applies under the following conditions.
- The IVL bit in the G1POCRj register is set to 0 (L output as a default value). The INV bit is set to 0 (not inversed).
- Bits UD1 to UD0 are set to 00_2 (counter increment mode).

(2) Base timer is reset when the base timer matches either following register
(a) G1PO0 (enabled by setting bit RST1 to 1, and bits RST4 and RST2 to 0), or
(b) G1BTRR (enabled by setting bit RST4 to 1, and bits RST2 and RST1 to 0)



j=1 to 7
m : Setting value of the G1POj register n: Setting value of either register G1PO0 or G1BTRR
G1IRj bit : Bits in the G1IR register

The above applies under the following conditions.
- The IVL bit in the G1POCRj register is set to 0 (L output as a default value). The INV bit is set to 0 (not inversed).
- Bits UD1 to UD0 are set to 00_2 (counter increment mode).

Figure 13.23 Phase-delayed Waveform Output Mode

13.5.3 Set/Reset Waveform Output (SR Waveform Output) Mode

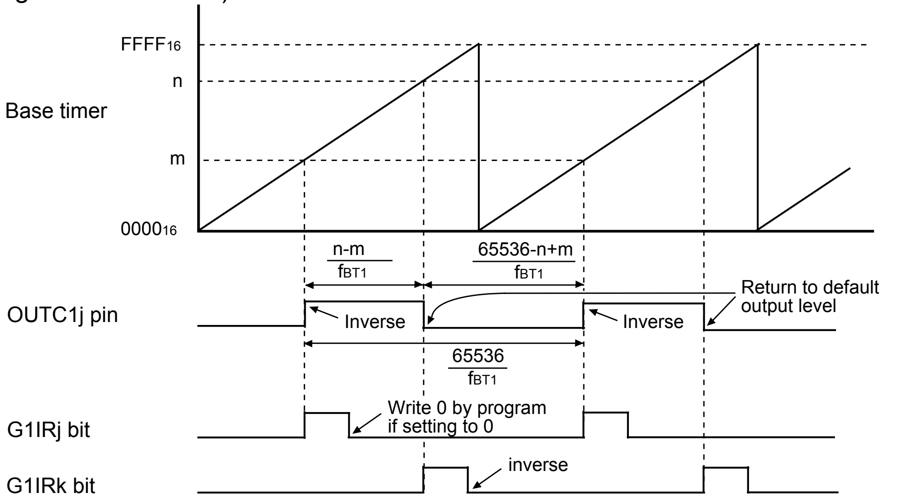
Output signal level of the OUTC1j pin becomes high ("H") when the INV bit in the G1POCRi (i=0 to 7) is set to 0 (output is not reversed) and the base timer value matches the G1POj register value (j=0, 2, 4, 6). The "H" signal switches to a low-level ("L") signal when the base timer value matches the G1POk (k=j+1) register value. **Table 13.10** lists specifications of SR waveform mode. **Figure 13.24** shows an example of the SR waveform mode operation.

Table 13.10 SR Waveform Output Mode Specifications

Item	Specification
Output waveform	• Free-running operation (the RST1, RTS2, and RST4 bits of the G1BCR1 and G1BCR0 registers are set to 0 (no reset)) Cycle : $\frac{65536}{f_{BT1}}$ Inverse level width[1] : $\frac{n-m}{f_{BT1}}$ • The base timer is cleared to 0000_{16} by matching the base timer with either following register (a) G1PO0 register (enabled by setting RST1 bit to 1, and bits RST4 and RST2 to 0)[2], or (b) G1BTRR register (enabled by setting RST4 bit to 1, and bits RST2 and RST1 to 0) Cycle : $\frac{p+2}{f_{BT1}}$ Inverse level width[1] : $\frac{n-m}{f_{BT1}}$ m : setting value of the G1POj register (j=0, 2, 4, 6) n : setting value of the G1POk register (k=j+1) p : setting value of the G1PO0 register or G1BTRR register value range of m, n, p: 0001_{16} to $FFFD_{16}$
Waveform output start condition	Bits IFEj and IFEk in the G1FE register is set to 1 (channel j function enabled)
Waveform output stop condition	Bits IFEj and IFEk are set to 0 (channel j function disabled)
Interrupt request	The G1IRj bit in the G1IR register is set to 1 when the base timer value matches the G1POj register value. The G1IRk bit in the interrupt request register is set to 1 when the base timer value matches the G1POk register value (See **Figure 13.24**)
OUTC1j pin [3]	Pulse signal output pin
Selectable function	• Default value set function : Set starting waveform output level • Inverse output function: Waveform output signal is inversed and provided from the OUTC1j pin

NOTES:
1. The odd channel's waveform generating register must have greater value than the even channel's.
2. When the G1PO0 register resets the base timer, the channel 0 and channel 1 SR waveform generating functions are not available.
3. Pins $OUTC1_0$, $OUTC1_2$, $OUTC1_4$, $OUTC1_6$.

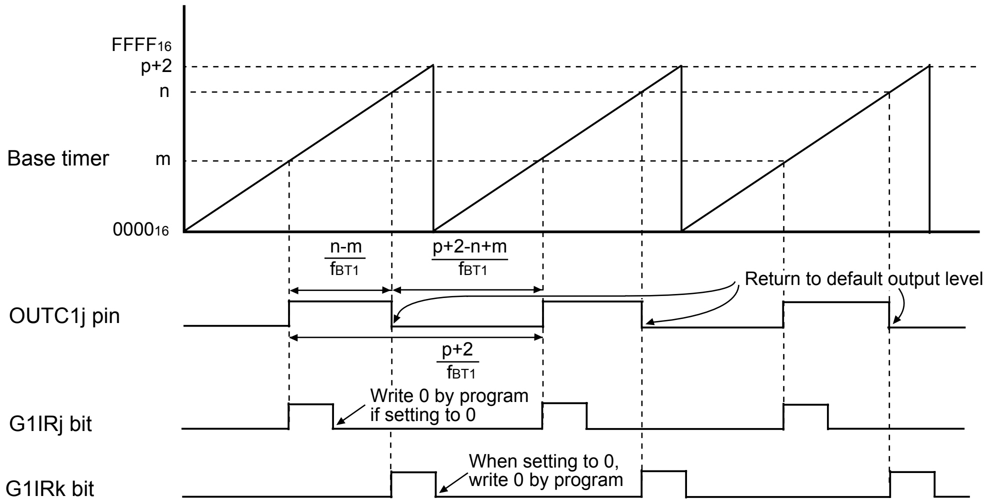
(1) Free-running operation
(Bits RST2 and RST1 in the G1BCR0 register and the RST4 bit in the G1BCR1 register are set to 0)



j=0, 2, 4, 6 k=j+1
m : Setting value of the G1POj register n: Setting value of the G1POk register
G1IRj, G1IRk bits: Bits in the G1IR register

The above applies under the following conditions.
- The IVL bit in the G1POCRj register is set to 0 (L output as a default value). The INV bit is set to 0 (not inversed).
- Bits UD1 and UD0 are set to 00_2 (counter increment mode).

(2) Base timer is reset when the base timer matches either following register
(a) G1PO0 (enabled by setting bit RST1 to 1, and bits RST4 and RST2 to 0), or
(b) G1BTRR (enabled by setting bit RST4 to 1, and bits RST2 and RST1 to 0)



j=2, 4, 6 k=j+1
m : Setting value of the G1POj register n: Setting value of the G1POk register
p: Setting value of either register G1PO0 or G1BTRR
G1IRj, G1IRk bits: Bits in the G1IR register

The above applies under the following conditions.
- The IVL bit in the G1POCRj register is set to 0 (L output as a default value). The INV bit is set to 0 (not inversed).
- Bits UD1 and UD0 are set to 00_2 (counter increment mode).

Figure 13.24 Set/Reset Waveform Output Mode

13.6 I/O Port Function Select

The value in the G1FE and G1FS registers decides which IC/OC pin to be an input or output pin.
In SR waveform generating mode, two channels, a set of even channel and odd channel, are used every output waveform, however, the waveform is output from an even channel only. In this case, the corresponding pin to the odd channel can be used as an I/O port.

Table 13.11 Pin setting for Time Measurement and Waveform Generating Functions

Pin	IFE	FSC	MOD1	MOD0	Port Direction	Port Data
$P2_7$/$INPC1_7$/ $OUTC1_7$	0	X	X	X	Determined by $PD2_7$	$P2_7$
	1	1	X	X	Determined by $PD2_7$, Input to $INPC1_7$ is always active	$P2_7$ or $INPC1_7$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_7$
	1	0	0	1	Determined by $PD2_7$, SR waveform output mode	$P2_7$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_7$
$P2_6$/$INPC1_6$/ $OUTC1_6$	0	X	X	X	Determined by $PD2_6$	$P2_6$
	1	1	X	X	Determined by $PD2_6$, Input to $INPC1_6$ is always active	$P2_6$ or $INPC1_6$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_6$
	1	0	0	1	SR Waveform Output	$OUTC1_6$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_6$
$P2_5$/$INPC1_5$/ $OUTC1_5$	0	X	X	X	Determined by $PD2_5$	$P2_5$
	1	1	X	X	Determined by $PD2_5$, Input to $INPC1_5$ is always active	$P2_5$ or $INPC1_5$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_5$
	1	0	0	1	Determined by $PD2_5$, SR Waveform Output mode	$P2_5$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_5$
$P2_4$/$INPC1_4$/ $OUTC1_4$	0	X	X	X	Determined by $PD2_4$	$P2_4$
	1	1	X	X	Determined by $PD2_4$, Input to $INPC1_4$ is always active	$P2_4$ or $INPC1_4$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_4$
	1	0	0	1	SR Waveform Output	$OUTC1_4$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_4$
$P2_3$/$INPC1_3$/ $OUTC1_3$	0	X	X	X	Determined by $PD2_3$	$P2_3$
	1	1	X	X	Determined by $PD2_3$, Input to $INPC1_3$ is always active	$P2_3$ or $INPC1_3$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_3$
	1	0	0	1	Determined by $PD2_3$, SR waveform output mode	$P2_3$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_3$
$P2_2$/$INPC1_2$/ $OUTC1_2$	0	X	X	X	Determined by $PD2_2$	$P2_2$
	1	1	X	X	Determined by $PD2_2$, Input to $INPC1_2$ is always active	$P2_2$ or $INPC1_2$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_2$
	1	0	0	1	SR Waveform Output	$OUTC1_2$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_2$
$P2_1$/$INPC1_1$/ $OUTC1_1$	0	X	X	X	Determined by $PD2_1$	$P2_1$
	1	1	X	X	Determined by $PD2_1$, Input to $INPC1_1$ is always active	$P2_1$ or $INPC1_1$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_1$
	1	0	0	1	Determined by $PD2_1$, SR waveform output mode	$P2_1$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_1$
$P2_0$/$INPC1_0$/ $OUTC1_0$	0	X	X	X	Determined by $PD2_0$	$P2_0$
	1	1	X	X	Determined by $PD2_0$, Input to $INPC1_0$ is always active	$P2_0$ or $INPC1_0$
	1	0	0	0	Single-phase Waveform Output	$OUTC1_0$
	1	0	0	1	SR Waveform Output	$OUTC1_0$
	1	0	1	0	Phase-delayed Waveform Output	$OUTC1_0$

IFE: IFEj (j=0 to 7) bits in the G1FE register.

FSC: FSCj (j=0 to 7) bits in the G1FS register.

MOD2 to MOD1: Bits in the G1POCRj (j=0 to 7) register.

13.6.1 INPC17 Alternate Input Pin Selection

The input capture pin for IC/OC channel 7 can be assigned to one of two package pins. The CH7INSEL bit in the G1BCR0 register selects IC/OC $INPC1_7$ from $P2_7$/$OUTC1_7$/$INPC1_7$ or P17/$\overline{\mathrm{INT5}}$/$INPC1_7$/IDU.

13.6.2 Digital Debounce Function for Pin P17/$\overline{\mathrm{INT5}}$/INPC17

The $\overline{\mathrm{INT5}}$/$INPC1_7$ input from the $P1_7$/$\overline{\mathrm{INT5}}$/$INPC1_7$/IDU pin has an effective digital debounce function against a noise rejection. Refer to **19.6 Digital Debounce function** for this detail.

14. Serial I/O

Note

The SI/O4 interrupt of peripheral function interrupt is not available in the 64-pin package.

Serial I/O is configured with five channels: UART0 to UART2, SI/O3 and SI/O4.

14.1 UARTi (i=0 to 2)

UARTi each have an exclusive timer to generate a transfer clock, so they operate independently of each other.

Figure 14.1 shows the block diagram of UARTi. **Figures 14.2** and **14.3** shows the block diagram of the UARTi transmit/receive.

UARTi has the following modes:

• Clock synchronous serial I/O mode
• Clock asynchronous serial I/O mode (UART mode).
• Special mode 1 (I^2C bus mode): UART2
• Special mode 2: UART2
• Special mode 3 (Bus collision detection function, IEBus mode): UART2
• Special mode 4 (SIM mode): UART2

Figures 14.4 to **14.9** show the UARTi-related registers.

Refer to tables listing each mode for register setting.

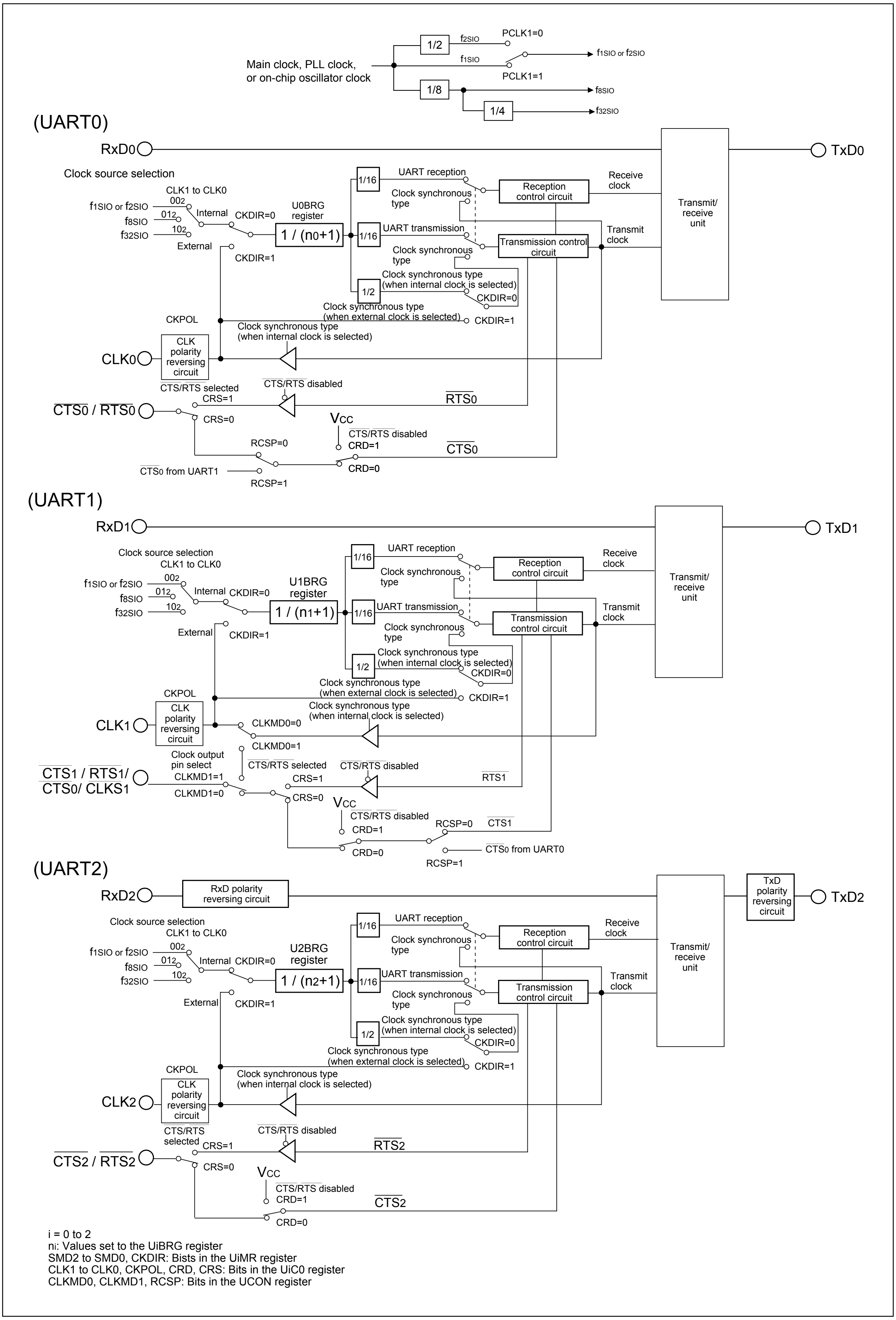


Figure 14.1 Block diagram of UARTi (i = 0 to 2)

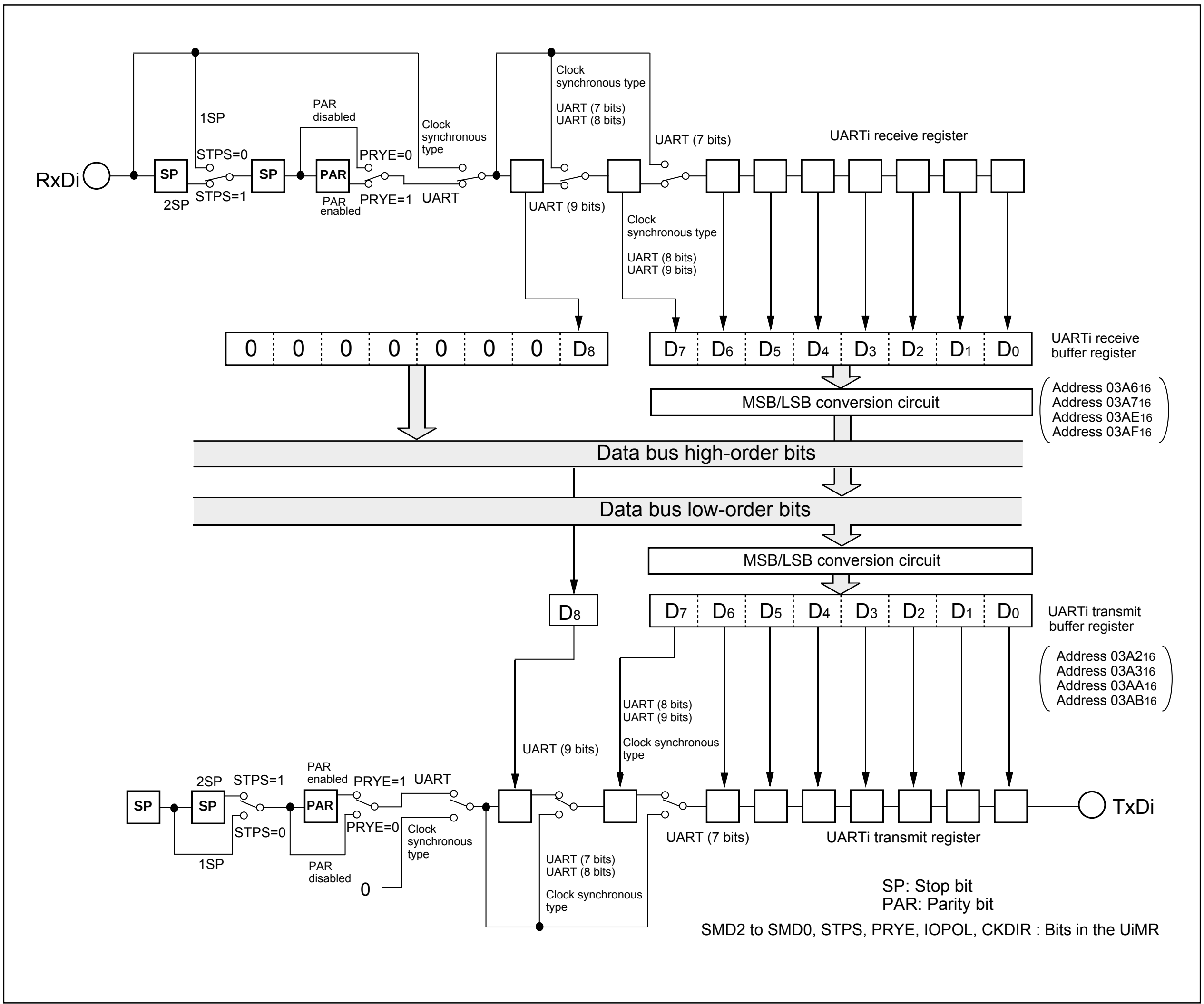


Figure 14.2 Block diagram of UARTi (i = 0, 1) transmit/receive unit

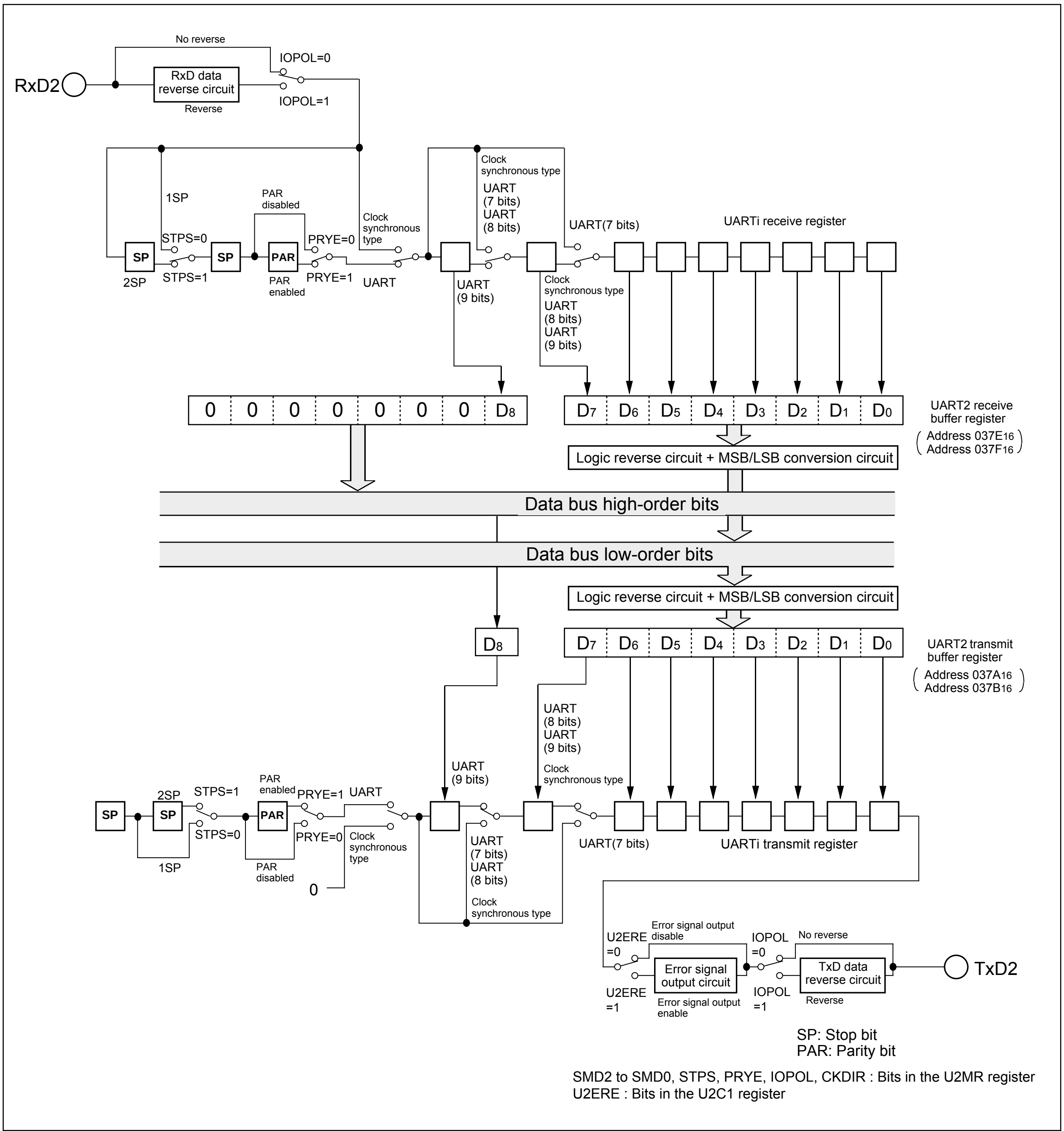
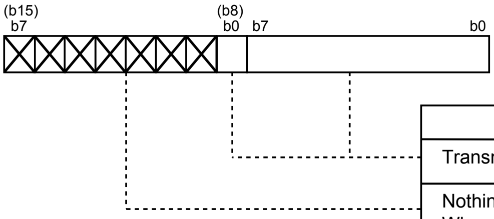


Figure 14.3 Block diagram of UART2 transmit/receive unit

UARTi Transmit Buffer Register (i=0 to 2)(1)

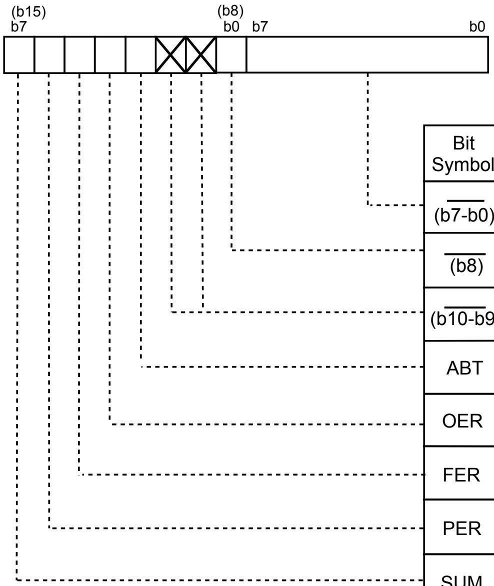


Symbol	Address	After Reset
U0TB	$03A3_{16}$-$03A2_{16}$	Undefined
U1TB	$03AB_{16}$-$03AA_{16}$	Undefined
U2TB	$037B_{16}$-$037A_{16}$	Undefined

Function	RW
Transmit data	WO
Nothing is assigned. If necessary, set to 0. When read, their contents are undefined	—

NOTES:
1. Use MOV instruction to write to this register.

UARTi Receive Buffer Register (i=0 to 2)

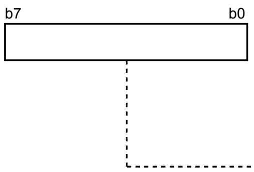


Symbol	Address	After Reset
U0RB	$03A7_{16}$-$03A6_{16}$	undefined
U1RB	$03AF_{16}$-$03AE_{16}$	undefined
U2RB	$037F_{16}$-$037E_{16}$	undefined

Bit Symbol	Bit Name	Function	RW
(b7-b0)	—	Receive data (D_7 to D_0)	RO
(b8)	—	Receive data (D_8)	RO
(b10-b9)	Nothing is assigned. If necessary, set to 0. When read, their contents are undefined		—
ABT	Arbitration lost detecting flag (2)	0 : Not detected 1 : Detected	RW
OER	Overrun error flag(1)	0 : No overrun error 1 : Overrun error found	RO
FER	Framing error flag(1)	0 : No framing error 1 : Framing error found	RO
PER	Parity error flag(1)	0 : No parity error 1 : Parity error found	RO
SUM	Error sum flag (1)	0 : No error 1 : Error found	RO

NOTES:
1. When the SMD2 to SMD0 bits in the UiMR register are set to 000_2 (serial I/O disabled) or the RE bit in the UiC1 register is set to 0 (reception disabled), all bits SUM, PER, FER and OER are set to 0 (no error). The SUM bit is set to 0 (no error) when all of the PER, FER and OER bits are set to 0 (no error). Also, bits PER and FER are set to 0 by reading the lower byte of the UiRB register.
2. The ABT bit is set to 0 by setting to 0 by program. (Writing 1 has no effect.) Nothing is assigned at the bit 11 in the U0RB and U1RB registers. If necessary, set to 0. When read, its content is 0.

UARTi Baud Rate Generation Register (i=0 to 2)(1, 2, 3)



Symbol	Address	After Reset
U0BRG	$03A1_{16}$	Undefined
U1BRG	$03A9_{16}$	Undefined
U2BRG	0379_{16}	Undefined

Function	Setting Range	RW
Assuming that set value = n, UiBRG divides the count source by n + 1	00_{16} to FF_{16}	WO

NOTES:
1. Write to this register while serial I/O is neither transmitting nor receiving.
2. Use MOV instruction to write to this register.
   The transfer clock is shown below when the setting value in the UiBRG register is set as n.
   (1) When the CKDIR bit in the UiMR register to 0 (internal clock)
   - Clock synchronous serial I/O mode : fj/(2(n+1))
   - Clock asynchronous serial I/O (UART) mode : fj/(16(n+1))

   (2) When the CKDIR bit in the UiMR register to 1 (external clock)
   - Clock synchronous serial I/O mode : f_{EXT}
   - Clock asynchronous serial I/O (UART) mode : f_{EXT}/(16(n+1))

   fj : f1SIO, f2SIO, f8SIO, f32SIO
   f_{EXT} : Input from CLKi pin
3. Set the UiBRG register after setting bits CLK1 and CLK0 in the registers UiC0.

Figure 14.4 U0TB to U2TB, U0RB to U2RB, U0BRG to U2BRG Registers

UARTi Transmit/receive Mode Register (i=0, 1)

b7 b6 b5 b4 b3 b2 b1 b0: 0 (b7)

Symbol	Address	After Reset
U0MR, U1MR	03A0$_{16}$, 03A8$_{16}$	00$_{16}$

Bit Symbol	Bit Name	Function	RW
SMD0	Serial I/O mode select bit (2)	b2 b1 b0 0 0 0 : Serial I/O disabled 0 0 1 : Clock synchronous serial I/O mode 1 0 0 : UART mode transfer data 7 bit long 1 0 1 : UART mode transfer data 8 bit long 1 1 0 : UART mode transfer data 9 bit long Do not set the value other than the above	RW
SMD1			RW
SMD2			RW
CKDIR	Internal/external clock select bit	0 : Internal clock 1 : External clock (1)	RW
STPS	Stop bit length select bit	0 : One stop bit 1 : Two stop bits	RW
PRY	Odd/even parity select bit	Effective when PRYE = 1 0 : Odd parity 1 : Even parity	RW
PRYE	Parity enable bit	0 : Parity disabled 1 : Parity enabled	RW
— (b7)	Reserve bit	Set to 0	RW

NOTES:
1. Set the corresponding port direction bit for each CLKi pin to 0 (input mode).
2. To receive data, set the corresponding port direction bit for each RxDi pin to 0.

UART2 Transmit/receive Mode Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
U2MR	0378$_{16}$	00$_{16}$

Bit Symbol	Bit Name	Function	RW
SMD0	Serial I/O mode select bit (2)	b2 b1 b0 0 0 0 : Serial I/O disabled 0 0 1 : Clock synchronous serial I/O mode 0 1 0 : I^{2}C bus mode(3) 1 0 0 : UART mode transfer data 7 bit long 1 0 1 : UART mode transfer data 8 bit long 1 1 0 : UART mode transfer data 9 bits long Do not set the value other than the above	RW
SMD1			RW
SMD2			RW
CKDIR	Internal/external clock select bit	0 : Internal clock 1 : External clock (1)	RW
STPS	Stop bit length select bit	0 : One stop bit 1 : Two stop bits	RW
PRY	Odd/even parity select bit	Effective when PRYE = 1 0 : Odd parity 1 : Even parity	RW
PRYE	Parity enable bit	0 : Parity disabled 1 : Parity enabled	RW
IOPOL	TxD, RxD I/O polarity reverse bit	0 : No reverse 1 : Reverse	RW

NOTES:
1. Set the corresponding port direction bit for each CLK2 pin to 0 (input mode).
2. To receive data, set the corresponding port direction bit for each RxD2 pin to 0 (input mode).
3. Set the corresponding port direction bit for SCL_2 and SDA_2 pins to 0 (input mode).

Figure 14.5 U0MR to U2MR Registers

UARTi Transmit/receive Control Rregister 0 (i=0 to 2)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
U0C0 to U2C0	$03A4_{16}$, $03AC_{16}$, $037C_{16}$	00001000_2

Bit Symbol	Bit Name	Function	RW
CLK0	BRG count source select bit[7]	b1 b0 0 0 : f_{1SIO} or f_{2SIO} is selected 0 1 : f_{8SIO} is selected 1 0 : f_{32SIO} is selected 1 1 : Do not set	RW
CLK1			RW
CRS	$\overline{\text{CTS}}$/$\overline{\text{RTS}}$ function select bit[3]	Effective when CRD is set to 0 0 : $\overline{\text{CTS}}$ function is selected [1] 1 : RTS function is selected	RW
TXEPT	Transmit register empty flag	0 : Data present in transmit register (during transmission) 1 : No data present in transmit register (transmission completed)	RO
CRD	$\overline{\text{CTS}}$/$\overline{\text{RTS}}$ disable bit	0 : $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ function enabled 1 : $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ function disabled (P6₀, P6₄ and P7₃ can be used as I/O ports)[6]	RW
NCH	Data output select bit[5]	0 : TxD2/SDA2 and SCLi pins are CMOS output 1 : TxD2/SDA2 and SCLi pins are N-channel open-drain output[4]	RW
CKPOL	CLK polarity select bit	0 : Transmit data is output at falling edge of transfer clock and receive data is input at rising edge 1 : Transmit data is output at rising edge of transfer clock and receive data is input at falling edge	RW
UFORM	Transfer format select bit[2]	0 : LSB first 1 : MSB first	RW

NOTES:
1. Set the corresponding port direction bit for each $\overline{\text{CTSi}}$ pin to 0 (input mode).
2. Effective when bits SMD2 to SMD0 in the UMR register to 001_2 (clock synchronous serial I/O mode) or 010_2 (UART mode transfer data 8 bits long). Set the UFORM bit to 1 when bits SMD2 to SMD0 are set to 101_2 (I²C bus mode) and 0 when they are set to 100_2.
3. $\overline{\text{CTS}_1}$/$\overline{\text{RTS}_1}$ can be used when the CLKMD1 bit in the UCON register is set to 0 (only CLK_1 output) and the RCSP bit in the UCON register is set to 0 ($\overline{\text{CTS}_0}$/$\overline{\text{RTS}_0}$ not separated).
4. SDA2 and SCL2 are effective when i = 2.
5. When bits SMD2 to SMD in the UiMR regiser are set to 000_2 (serial I/O disable), do not set NCH bit to 1 (TxDi/SDA2 and SCL2 pins are N-channel open-drain output).
6. When the U1MAP bit in PACR register is 1 ($P7_3$ to $P7_0$), $P7_0$ functions as $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ pin in UART1.
7. When the CLK1 and CLK0 bit settings are changed, set the UiBRG register.

UART Transmit/receive Control Register 2

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
UCON	$03B0_{16}$	$X0000000_2$

Bit Symbol	Bit Name	Function	RW
U0IRS	UART0 transmit interrupt cause select bit	0 : Transmit buffer empty (TI = 1) 1 : Transmission completed (TXEPT = 1)	RW
U1IRS	UART1 transmit interrupt cause select	0 : Transmit buffer empty (TI = 1) 1 : Transmission completed (TXEPT = 1)	RW
U0RRM	UART0 continuous receive mode enable bit	0 : Continuous receive mode disabled 1 : Continuous receive mode enable	RW
U1RRM	UART1 continuous receive mode enable bit	0 : Continuous receive mode disabled 1 : Continuous receive mode enabled	RW
CLKMD0	UART1 CLK/CLKS select bit 0	Effective when the CLKMD1 bit is set to 1 0 : Clock output from CLK1 1 : Clock output from CLKS1	RW
CLKMD1	UART1 CLK/CLKS select bit 1 [1]	0 : Output from CLK1 only 1 : Transfer clock output from multiple pins function selected	RW
RCSP	Separate UART0 $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ bit	0 : $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ shared pin [2] 1 : $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ separated ($P6_4$ pin functions as $\overline{\text{CTS}_0}$ pin)	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

NOTES:
1. When using multiple transfer clock output pins, make sure the following conditions are met:set the CKDIR bit in the U1MR register to 0 (internal clock)
2. When the U1MAP bit in PACR register is set to 1 ($P7_3$ to $P7_0$), $P7_0$ pin functions as $\overline{\text{CTS}_0}$ pin.

Figure 14.6 U0C0 to U2C0 and UCON Registers

UARTi Transmit/receive Control Register 1 (i=0, 1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: U0C1, U1C1 — Address: 03A5₁₆,03AD₁₆ — After Reset: 00000010₂

Bit Symbol	Bit Name	Function	RW
TE	Transmit enable bit	0 : Transmission disabled 1 : Transmission enabled	RW
TI	Transmit buffer empty flag	0 : Data present in UiTB register 1 : No data present in UiTB register	RO
RE	Receive enable bit	0 : Reception disabled 1 : Reception enabled	RW
RI	Receive complete flag	0 : No data present in UiRB register 1 : Data present in UiRB register	RO
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

UART2 Transmit/receive Control Register 1

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: U2C1 — Address: 037D₁₆ — After Reset: 00000010₂

Bit Symbol	Bit Name	Function	RW
TE	Transmit enable bit	0 : Transmission disabled 1 : Transmission enabled	RW
TI	Transmit buffer empty flag	0 : Data present in U2TB register 1 : No data present in U2TB register	RO
RE	Receive enable bit	0 : Reception disabled 1 : Reception enabled	RW
RI	Receive complete flag	0 : No data present in U2RB register 1 : Data present in U2RB register	RO
U2IRS	UART2 transmit interrupt cause select bit	0 : Transmit buffer empty (TI = 1) 1 : Transmit is completed (TXEPT = 1)	RW
U2RRM	UART2 continuous receive mode enable bit	0 : Continuous receive mode disabled 1 : Continuous receive mode enabled	RW
U2LCH	Data logic select bit	0 : No reverse 1 : Reverse	RW
U2ERE	Error signal output enable bit	0 : Output disabled 1 : Output enabled	RW

Pin Assignment Control Register (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbpl: PACR — Address: 025D₁₆ — After Reset: 00₁₆

Bit Symbol	Bit Name	Function	RW
PACR0	Pin enabling bit	010 : 64 pin 011 : 80 pin All other values are reserved. Do not use.	RW
PACR1			RW
PACR2			RW
— (b6-b3)	Reserved bits	Nothing is assigned. If necessary, set to 0. When read, the content is 0	—
U1MAP	UART1 pin remapping bit	UART1 pins assigned to 0 : P6₇ to P6₄ 1 : P7₃ to P7₀	RW

NOTE:
1. Set the PACR register by the next instruction after setting the PRC2 bit in the PRCR register to 1(write enable).

Figure 14.7 U0C1 to U2C1 Register, and PACR Register

UART2 Special Mode Register

b7 b6 b5 b4 b3 b2 b1 b0

b7	b6	b5	b4	b3	b2	b1	b0
X				0			

Symbol U2SMR Address 037716_{16} After Reset $X0000000_2$

Bit Symbol	Bit Name	Function	RW
IICM	I^2C bus mode select bit	0 : Other than I^2C bus mode 1 : I^2C bus mode	RW
ABC	Arbitration lost detecting flag control bit	0 : Update per bit 1 : Update per byte	RW
BBS	Bus busy flag	0 : STOP condition detected 1 : START condition detected (busy)	RW(1)
— (b3)	Reserved bit	Set to 0	RW
ABSCS	Bus collision detect sampling clock select bit	0 : Rising edge of transfer clock 1 : Underflow signal of timer A0	RW
ACSE	Auto clear function select bit of transmit enable bit	0 : No auto clear function 1 : Auto clear at occurrence of bus collision	RW
SSS	Transmit start condition select bit	0 : Not synchronized to RxD2 1 : Synchronized to RxD2(2)	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

NOTES:
1: The BBS bit is set to 0 by writing 0 by program. (Writing 1 has no effect).
2: When a transfer begins, the SSS bit is set to 0 (Not synchronized to RxD2).

UART2 Special Mode Register 2

b7	b6	b5	b4	b3	b2	b1	b0
X							

Symbol U2SMR2 Address 0376_{16} After Reset $X0000000_2$

Bit Symbol	Bit Name	Function	RW
IICM2	I^2C bus mode select bit 2	Refer to **Table 14.13**	RW
CSC	Clock-synchronous bit	0 : Disabled 1 : Enabled	RW
SWC	SCL2 wait output bit	0 : Disabled 1 : Enabled	RW
ALS	SDA2 output stop bit	0 : Disabled 1 : Enabled	RW
STAC	UART initialization bit	0 : Disabled 1 : Enabled	RW
SWC2	SCL2 wait output bit 2	0: Transfer clock 1: “L” output	RW
SDHI	SDA2 output disable bit	0: Enabled 1: Disabled (high impedance)	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

Figure 14.8 U2SMR and U2SMR2 Registers

UART2 Special Mode Register 3

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
U2SMR3	0375_{16}	$000X0X0X_2$

Bit Symbol	Bit Name	Function	RW
— (b0)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
CKPH	Clock phase set bit	0 : Without clock delay 1 : With clock delay	RW
— (b2)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
NODC	Clock output select bit	0 : CLK_2 is CMOS output 1 : CLK_2 is N-channel open drain output	RW
— (b4)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
DL0	SDA2 digital delay setup bit (1, 2)	b7 b6 b5 0 0 0 : Without delay 0 0 1 : 1 to 2 cycle(s) of U2BRG count source 0 1 0 : 2 to 3 cycles of U2BRG count source 0 1 1 : 3 to 4 cycles of U2BRG count source 1 0 0 : 4 to 5 cycles of U2BRG count source 1 0 1 : 5 to 6 cycles of U2BRG count source 1 1 0 : 6 to 7 cycles of U2BRG count source 1 1 1 : 7 to 8 cycles of U2BRG count source	RW
DL1			RW
DL2			RW

NOTES:
1. Bits DL2 to DL0 are used to generate a delay in SDA output by digital means during I^2C bus mode. In other than I^2C bus mode,set these bits to 000_2 (no delay).
2. The amount of delay varies with the load on pins SCL2 and SDA2. Also, when using an external clock, the amount of delay increases by about 100 ns.

UART2 Special Mode Register 4

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
U2SMR4	0374_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
STAREQ	Start condition generate bit (1)	0 : Clear 1 : Start	RW
RSTAREQ	Restart condition generate bit (1)	0 : Clear 1 : Start	RW
STPREQ	Stop condition generate bit (1)	0 : Clear 1 : Start	RW
STSPSEL	SCL_2,SDA_2 output select bit	0 : Start and stop conditions not output 1 : Start and stop conditions output	RW
ACKD	ACK data bit	0 : ACK 1 : NACK	RW
ACKC	ACK data output enable bit	0 : Serial I/O data output 1 : ACK data output	RW
SCLHI	SCL_2 output stop enable bit	0 : Disabled 1 : Enabled	RW
SWC9	SCL_2 wait bit 3	0 : SCL_2 "L" hold disabled 1 : SCL_2 "L" hold enabled	RW

NOTE:
1. Set to 0 when each condition is generated.

Figure 14.9 U2SMR3 and U2SMR4 Registers

14.1.1 Clock Synchronous serial I/O Mode

The clock synchronous serial I/O mode uses a transfer clock to transmit and receive data. **Table 14.1** lists the specifications of the clock synchronous serial I/O mode. **Table 14.2** lists the registers used in clock synchronous serial I/O mode and the register values set.

Table 14.1 Clock Synchronous Serial I/O Mode Specifications

Item	Specification
Transfer data format	• Transfer data length: 8 bits
Transfer clock	• The CKDIR bit in the UiMR(i=0 to 2) register is set to 0 (internal clock) : fj/ (2(n+1)) fj = f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}. n: Setting value of UiBRG register 00_{16} to FF_{16} • CKDIR bit is set to 1 (external clock) : Input from CLKi pin
Transmission, reception control	• Selectable from $\overline{CTS}$ function, $\overline{RTS}$ function or $\overline{CTS}/\overline{RTS}$ function disable
Transmission start condition	• Before transmission can start, the following requirements must be met (1) – The TE bit in the UiC1 register is set to 1 (transmission enabled) – The TI bit in the UiC1 register is set to 0 (data present in UiTB register) – If $\overline{CTS}$ function is selected, input on the $\overline{CTSi}$ pin is set to “L”
Reception start condition	• Before reception can start, the following requirements must be met (1) – The RE bit in the UiC1 register is set to 1 (reception enabled) – The TE bit in the UiC1 register is set to 1 (transmission enabled) – The TI bit in the UiC1 register is set to 0 (data present in the UiTB register)
Interrupt request generation timing	• For transmission, one of the following conditions can be selected – The UiIRS bit (3) is set to 0 (transmit buffer empty): when transferring data from the UiTB register to the UARTi transmit register (at start of transmission) – The UiIRS bit is set to 1 (transfer completed): when the serial I/O finished sending data from the UARTi transmit register • For reception When transferring data from the UARTi receive register to the UiRB register (at completion of reception)
Error detection	• Overrun error (2) This error occurs if the serial I/O started receiving the next data before reading the UiRB register and received the 7th bit in the the next data
Select function	• CLK polarity selection Transfer data input/output can be chosen to occur synchronously with the rising or the falling edge of the transfer clock • LSB first, MSB first selection Whether to start sending/receiving data beginning with bit 0 or beginning with bit 7 can be selected • Continuous receive mode selection Reception is enabled immediately by reading the UiRB register • Switching serial data logic (UART2) This function reverses the logic value of the transmit/receive data • Transfer clock output from multiple pins selection (UART1) The output pin can be selected in a program from two UART1 transfer clock pins that have been set • Separate $\overline{CTS}/\overline{RTS}$ pins (UART0) $\overline{CTS_0}$ and $\overline{RTS_0}$ are input/output from separate pins • UART1 pin remapping selection The UART1 pin can be selected from the $P6_7$ to $P6_4$ or $P7_3$ to $P7_0$

NOTES:
1. When an external clock is selected, the conditions must be met while if the CKPOL bit in the UiC0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock), the external clock is in the high state; if the CKPOL bit in the UiC0 register is set to 1 (transmit data output at the rising edge and the receive data taken in at the falling edge of the transfer clock), the external clock is in the low state.
2. If an overrun error occurs, bits 8 to 0 in the UiRB register are undefined. The IR bit in the SiRIC register remains unchanged.
3. The U0IRS and U1IRS bits respectively are the bits 0 and 1 in the UCON register; the U2IRS bit is bit 4 in the U2C1 register.

Table 14.2 Registers to Be Used and Settings in Clock Synchronous Serial I/O Mode

Register	Bit	Function
UiTB(3)	0 to 7	Set transmission data
UiRB(3)	0 to 7	Reception data can be read
	OER	Overrun error flag
UiBRG	0 to 7	Set bit rate
UiMR(3)	SMD2 to SMD0	Set to 001_2
	CKDIR	Select the internal clock or external clock
	IOPOL(i=2) (4)	Set to 0
UiC0	CLK1 to CLK0	Select the count source for the UiBRG register
	CRS	Select $\overline{CTS}$ or $\overline{RTS}$ to use
	TXEPT	Transmit register empty flag
	CRD	Enable or disable the $\overline{CTS}$ or $\overline{RTS}$ function
	NCH	Select TxDi pin output mode
	CKPOL	Select the transfer clock polarity
	UFORM	Select the LSB first or MSB first
UiC1	TE	Set this bit to 1 to enable transmission/reception
	TI	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception
	RI	Reception complete flag
	U2IRS (1)	Select the source of UART2 transmit interrupt
	U2RRM (1)	Set this bit to 1 to use UART2 continuous receive mode
	U2LCH (3)	Set this bit to 1 to use UART2 inverted data logic
	U2ERE (3)	Set to 0
U2SMR	0 to 7	Set to 0
U2SMR2	0 to 7	Set to 0
U2SMR3	0 to 2	Set to 0
	NODC	Select clock output mode
	4 to 7	Set to 0
U2SMR4	0 to 7	Set to 0
UCON	U0IRS, U1IRS	Select the source of UART0/UART1 transmit interrupt
	U0RRM, U1RRM	Set this bit to 1 to use continuous receive mode
	CLKMD0	Select the transfer clock output pin when CLKMD1 is set to 1
	CLKMD1	Set this bit to 1 to output UART1 transfer clock from two pins
	RCSP	Set this bit to 1 to accept as input the UART0 $\overline{CTS_0}$ signal from the $P6_4$ pin
	7	Set to 0

NOTES:

1. Set bits 5 and 4 in registers U0C1 and U1C1 to 0. Bits U0IRS, U1IRS, U0RRM, and U1RRM are in the UCON register.
2. Not all register bits are described above. Set those bits to 0 when writing to the registers in clock synchronous serial I/O mode.
3. Set bits 7 and 6 in registers U0C1 and U1C1 to 0.
4. Set the bit 7 in registers U0MR and U1MR to 0.

i=0 to 2

Table 14.3 lists pin functions for the case where the multiple transfer clock output pin select function is deselected. **Table 14.4** lists the $P6_4$ pin functions during clock synchronous serial I/O mode.
Note that for a period from when the UARTi operation mode is selected to when transfer starts, the TxDi pin outputs an “H”. (If the N-channel open-drain output is selected, this pin is in a high-impedance state.)

Table 14.3 Pin Functions (When Not Select Multiple Transfer Clock Output Pin Function)(1)

Pin Name	Function	Method of Selection
TxDi (i = 0 to 2) ($P6_3$, $P6_7$, $P7_0$)	Serial data output	(Outputs dummy data when performing reception only)
RxDi ($P6_2$, $P6_6$, $P7_1$)	Serial data input	Set the PD6_2 bit and PD6_6 bit in the PD6 register, and PD7_1 bit in the PD7 register to 0 (Can be used as an input port when performing transmission only)
CLKi ($P6_1$, $P6_5$, $P7_2$)	Transfer clock output	Set the CKDIR bit in the UiMR register to 0
	Transfer clock input	Set the CKDIR bit in the UiMR register to 1 Set the PD6_1 bit and PD6_5 bit in the PD6 register, and the PD7_2 bit in the PD7 register to 0
$\overline{CTSi}$/$\overline{RTSi}$ ($P6_0$, $P6_4$, $P7_3$)	$\overline{CTS}$ input	Set the CRD bit in the UiC0 register to 0 Set the CRS bit in the UiC0 register to 0 Set the PD6_0 bit and PD6_4 bit in the PD6 register is set to 0, the PD7_3 bit in the PD7 register to 0
	$\overline{RTS}$ output	Set the CRD bit in the UiC0 register to 0 Set the CRS bit in the UiC0 register to 1
	I/O port	Set the CRD bit in the UiC0 register to 1

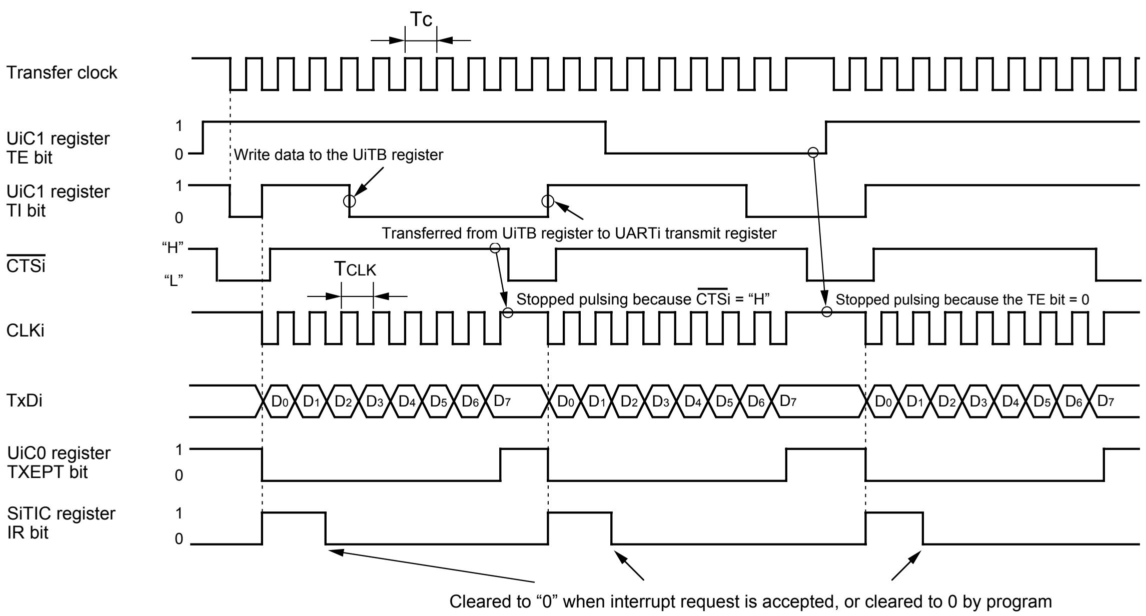
NOTE:
1: When the U1MAP bit in PACR register is 1 ($P7_3$ to $P7_0$), UART1 pin is assgined to $P7_3$ to $P7_0$.

Table 14.4 $P6_4$ Pin Functions(1)

Pin Function	Bit Set Value					
	U1C0 register		UCON register			PD6 register
	CRD	CRS	RCSP	CLKMD1	CLKMD0	PD6_4
$P6_4$	1	—	0	0	—	Input: 0, Output: 1
$\overline{CTS_1}$	0	0	0	0	—	0
$\overline{RTS_1}$	0	1	0	0	—	—
$\overline{CTS_0}$(2)	0	0	1	0	—	0
$CLKS_1$	—	—	—	1(3)	1	—

NOTES:
1. When the U1MAP bit in PACR register is 1 ($P7_3$ to $P7_0$), this table lists the $P7_0$ functions.
2. In addition to this, set the CRD bit in the U0C0 register to 0 ($\overline{CTS_0}$/$\overline{RTS_0}$ enabled) and the CRS bit in the U0C0 register to 1 ($\overline{RTS_0}$ selected).
3. When the CLKMD1 bit is set to 1 and the CLKMD0 bit is set to 0, the following logic levels are output:
   - High if the CLKPOL bit in the U1C0 register is set to 0
   - Low if the CLKPOL bit in the U1C0 register is set to 1

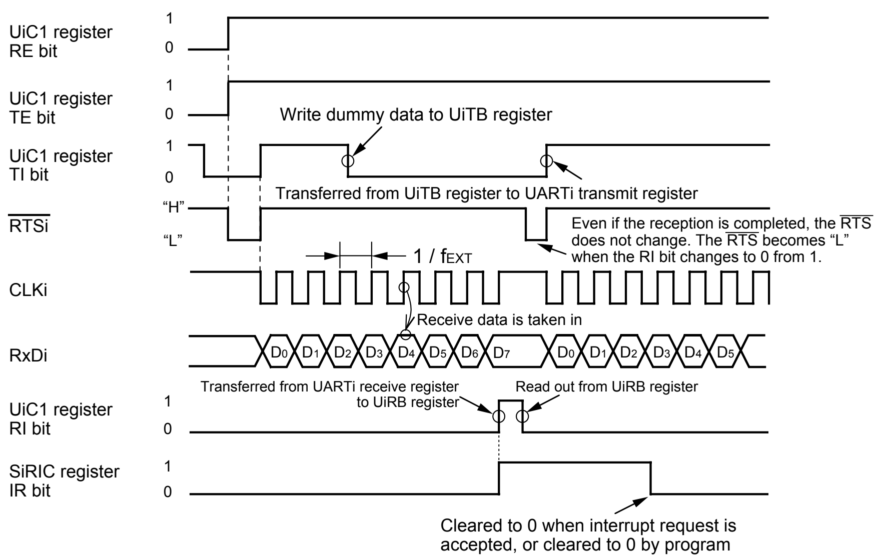
(1) Example of Transmit Timing (Internal clock is selected)



Tc = TCLK = 2(n + 1) / fj
fj: frequency of UiBRG count source (f1SIO, f2SIO, f8SIO, f32SIO)
n: value set to UiBRG register
i: 0 to 2

The above timing diagram applies to the case where the register bits are set as follows:
- The CKDIR bit in the UiMR register is set to 0 (internal clock)
- The CRD bit in the UiC0 register is set to 0 (CTS/RTS enabled); CRS bit is set to 0 (CTS selected)
- The CKPOL bit in the UiC0 register is set to 0 (transmit data output at the falling edge and receive data taken in at the rising edge of the transfer clock)
- The UiIRS bit is set to 0 (an interrupt request occurs when the transmit buffer becomes empty): U0IRS bit is the bit 0 in the UCON register U1IRS bit is the bit 1 in the UCON register, and U2IRS bit is the bit 4 in the U2C1 register.

(2) Example of Receive Timing (External clock is selected)



The above timing diagram applies to the case where the register bits are set as follows:
- The CKDIR bit in the UiMR register is set to 1 (external clock)
- The CRD bit in the UiC0 register is set to 0 (CTS/RTS enabled); The CRS bit is set to 1 (RTS selected)
- UiC0 register CKPOL bit is set to 0 (transmit data output at the falling edge and receive data taken in at the rising edge of the transfer clock)

fEXT: frequency of external clock

Make sure the following conditions are met when input to the CLKi pin before receiving data is high:
- UiC0 register TE bit is set to 1 (transmit enabled)
- UiC0 register RE bit is set to 1 (Receive enabled)
- Write dummy data to the UiTB register

Figure 14.10 Typical transmit/receive timings in clock synchronous serial I/O mode

14.1.1.1 Counter Measure for Communication Error Occurs

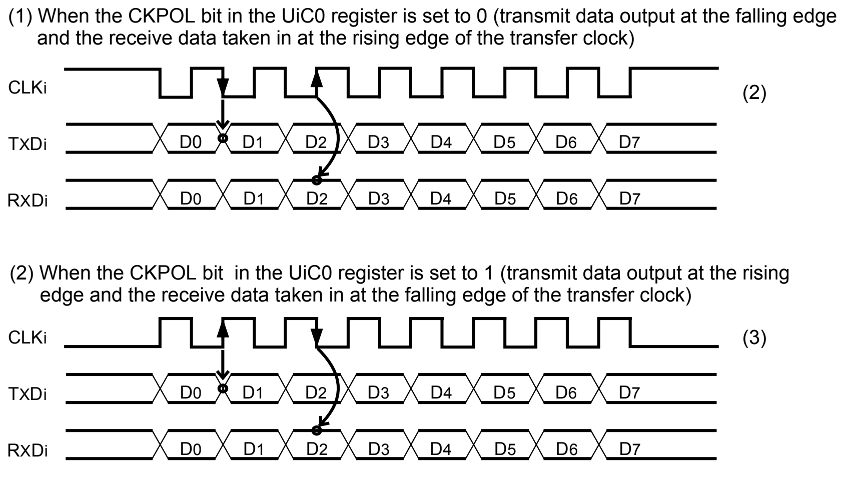
If a communication error occurs while transmitting or receiving in clock synchronous serial I/O mode, follow the procedures below.

•Resetting the UiRB register (i=0 to 2)
- (1) Set the RE bit in the UiC1 register to 0 (reception disabled)
- (2) Set bits SMD2 to SMD0 in the UiMR register to 000_2 (Serial I/O disabled)
- (3) Set bits SMD2 to SMD0 in the UiMR register to 001_2 (Clock synchronous serial I/O mode)
- (4) Set the RE bit in the UiC1 register to 1 (reception enabled)

•Resetting the UiTB register (i=0 to 2)
- (1) Set bits SMD2 to SMD0 in the UiMR register to 000_2 (Serial I/O disabled)
- (2) Set bits SMD2 to SMD0 in the UiMR register to 001_2 (Clock synchronous serial I/O mode)
- (3) 1 is written to TE bit in the UiC1 register (reception enabled), regardless to the TE bit.

14.1.1.2 CLK Polarity Select Function

Use the CKPOL bit in the UiC0 register (i=0 to 2) to select the transfer clock polarity. **Figure 14.11** shows the polarity of the transfer clock.



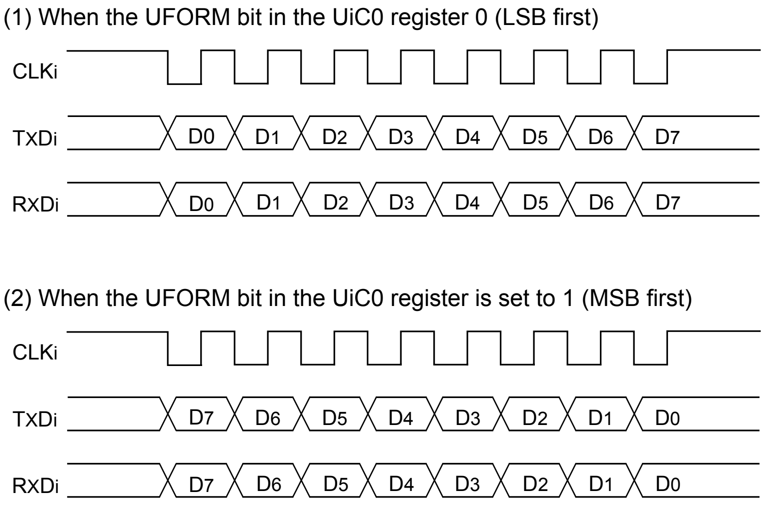
i = 0 to 2

NOTES:
1. This applies to the case where the UFORM bit in the UiC0 register is set to 0 (LSB first) and the UiLCH bit in the UiC1 register is set to 0 (no reverse).
2. When not transferring, the CLKi pin outputs a high signal.

Figure 14.11 Polarity of transfer clock

14.1.1.3 LSB First/MSB First Select Function

Use the UFORM bit in the UiC0 register (i=0 to 2) to select the transfer format. **Figure 14.12** shows the transfer format.



i = 0 to 2

NOTE:
1. This applies to the case where the CKPOL bit in the UiC0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock) and the UiLCH bit in the UiC1 register 0 (no reverse).

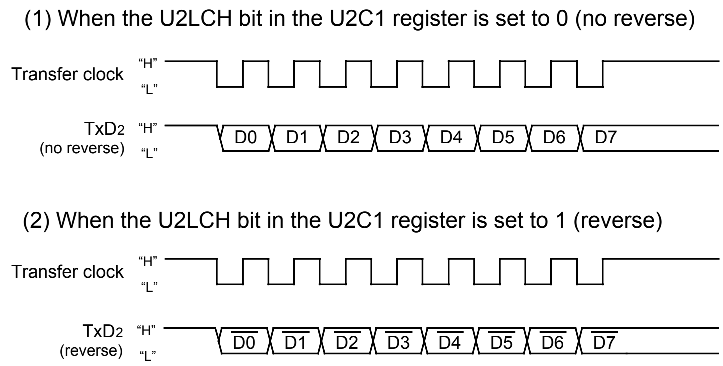
Figure 14.12 Transfer format

14.1.1.4 Continuous receive mode

When the UiRRM bit (i=0 to 2) is set to 1 (continuous receive mode), the TI bit in the UiC1 register is set to 0 (data present in the UiTB register) by reading the UiRB register. In this case, i.e., UiRRM bit is set to 1, do not write dummy data to the UiTB register in a program. The U0RRM and U1RRM bits are the bit 2 and bit 3 in the UCON register, respectively, and the U2RRM bit is the bit 5 in the U2C1 register.

14.1.1.5 Serial data logic switch function (UART2)

When the U2LCH bit in the U2C1 register is set to 1 (reverse), the data written to the U2TB register has its logic reversed before being transmitted. Similarly, the received data has its logic reversed when read from the U2RB register. **Figure 14.13** shows serial data logic.

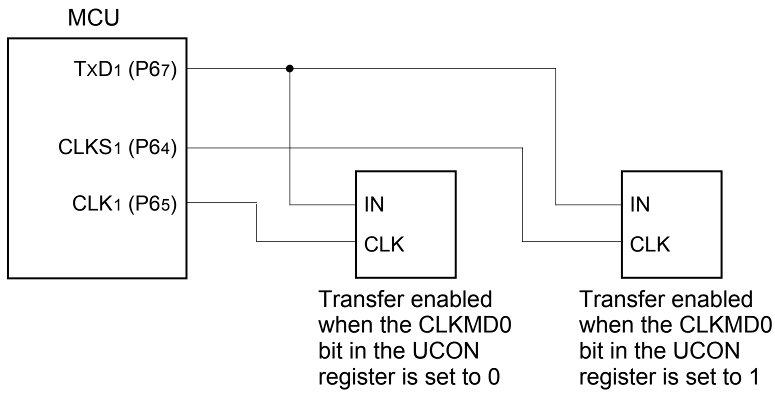


NOTE:
1. This applies to the case where the CKPOL bit in the U2C0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock) and the UFORM bit is set to 0 (LSB first).

Figure 14.13 Serial data logic switch timing

14.1.1.6 Transfer clock output from multiple pins function (UART1)

The CLKMD1 to CLKMD0 bits in the UCON register can choose one from two transfer clock output pins. (See **Figure 14.14**) This function is valid when the internal clock is selected for UART1.



NOTES:
1. This applies to the case where the CKDIR bit in the U1MRregister is set to 0 (internal clock) and the CLKMD1 bit in the UCON register is set to 1 (transfer clock output from multiple pins).
2. This applies to the case where U1MAP bit in PACR register is set to 0 (P67 to P64).

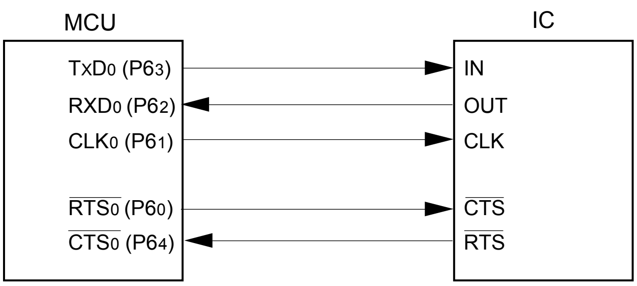
Figure 14.14 Transfer Clock Output From Multiple Pins

14.1.1.7 $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ separate function (UART0)

This function separates $\overline{\text{CTS}_0}$/$\overline{\text{RTS}_0}$, outputs $\overline{\text{RTS}_0}$ from the $P6_0$ pin, and accepts as input the $\overline{\text{CTS}_0}$ from the $P6_4$ pin or $P7_0$ pin. To use this function, set the register bits as shown below.

- The CRD bit in the U0C0 register is set to 0 (enables UART0 $\overline{\text{CTS}}$/$\overline{\text{RTS}}$)
- The CRS bit in the U0C0 register is set to 1 (outputs UART0 $\overline{\text{RTS}}$)
- The CRD bit in the U1C0 register is set to 0 (enables UART1 $\overline{\text{CTS}}$/$\overline{\text{RTS}}$)
- The CRS bit in the U1C0 register is set to 0 (inputs UART1 $\overline{\text{CTS}}$)
- The RCSP bit in the UCON register is set to 1 (inputs $\overline{\text{CTS}_0}$ from the $P6_4$ pin or $P7_0$ pin)
- The CLKMD1 bit in the UCON register is set to 0 ($CLKS_1$ not used)

Note that when using the $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ separate function, UART1 $\overline{\text{CTS}}$/$\overline{\text{RTS}}$ separate function cannot be used.



NOTE:
1. This applies to the case where the U1MAP bit in the PACR register is set to 0 ($P6_7$ to $P6_4$).

Figure 14.15 CTS/RTS separate function usage

14.1.2 Clock Asynchronous Serial I/O (UART) Mode

The UART mode allows transmitting and receiving data after setting the desired bit rate and transfer data format. **Table 14.5** lists the specifications of the UART mode.

Table 14.5 UART Mode Specifications

Item	Specification
Transfer data format	• Character bit (transfer data): Selectable from 7, 8 or 9 bits • Start bit: 1 bit • Parity bit: Selectable from odd, even, or none • Stop bit: Selectable from 1 or 2 bits
Transfer clock	• The CKDIR bit in the UiMR(i=0 to 2) register is set to 0 (internal clock) : fj/ (16(n+1)) fj = f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}. n: Setting value of UiBRG register 00_{16} to FF_{16} • CKDIR bit is set to 1 (external clock) : f_{EXT}/16(n+1) f_{EXT}: Input from CLKi pin. n :Setting value of UiBRG register 00_{16} to FF_{16}
Transmission, reception control	• Selectable from $\overline{CTS}$ function, $\overline{RTS}$ function or $\overline{CTS}/\overline{RTS}$ function disable
Transmission start condition	• Before transmission can start, the following requirements must be met – The TE bit in the UiC1 register is set to 1 (transmission enabled) – The TI bit in the UiC1 register is set to 0 (data present in UiTB register) – If $\overline{CTS}$ function is selected, input on the $\overline{CTSi}$ pin is set to “L”
Reception start condition	• Before reception can start, the following requirements must be met" – The RE bit in the UiC1 register is set to 1 (reception enabled) – Start bit detection
Interrupt request generation timing	• For transmission, one of the following conditions can be selected – The UiIRS bit (2) is set to 0 (transmit buffer empty): when transferring data from the UiTB register to the UARTi transmit register (at start of transmission) – The UiIRS bit is set to1 (transfer completed): when the serial I/O finished sending data from the UARTi transmit register • For reception When transferring data from the UARTi receive register to the UiRB register (at completion of reception)
Error detection	• Overrun error (1) This error occurs if the serial I/O started receiving the next data before reading the UiRB register and received the bit one before the last stop bit in the the next data • Framing error This error occurs when the number of stop bits set is not detected • Parity error This error occurs when if parity is enabled, the number of 1 in parity and character bits does not match the number of 1 set • Error sum flag This flag is set to 1 when any of the overrun, framing, and parity errors is encountered
Select function	• LSB first, MSB first selection Whether to start sending/receiving data beginning with bit 0 or beginning with bit 7 can be selected • Serial data logic switch (UART2) This function reverses the logic of the transmit/receive data. The start and stop bits are not reversed. • TxD, RxD I/O polarity switch (UART2) This function reverses the polarities of hte TxD pin output and RxD pin input. The logic levels of all I/O data is reversed. • Separate $\overline{CTS}/\overline{RTS}$ pins (UART0) $\overline{CTS_0}$ and $\overline{RTS_0}$ are input/output from separate pins • UART1 pin remapping selection The UART1 pin can be selected from the $P6_7$ to $P6_4$ or $P7_3$ to $P7_0$

NOTES:
1. If an overrun error occurs, bits 8 to 0 in the UiRB register are undefined. The IR bit in the SiRIC register remains unchange.
2. Bits U0IRS and U1IRS respectively are the UCON register bits 0 and 1; the U2IRS bit is the U2C1 register bit 4.

Table 14.6 Registers to Be Used and Settings in UART Mode

Register	Bit	Function
UiTB	0 to 8	Set transmission data (1)
UiRB	0 to 8	Reception data can be read (1)
	OER,FER,PER,SUM	Error flag
UiBRG	0 to 7	Set bit rate
UiMR	SMD2 to SMD0	Set these bits to 100_2 when transfer data is 7 bits long Set these bits to 101_2 when transfer data is 8 bits long Set these bits to 110_2 when transfer data is 9 bits long
	CKDIR	Select the internal clock or external clock
	STPS	Select the stop bit
	PRY, PRYE	Select whether parity is included and whether odd or even
	IOPOL(i=2) (4)	Select the TxD/RxD input/output polarity
UiC0	CLK0, CLK1	Select the count source for the UiBRG register
	CRS	Select $\overline{\text{CTS}}$ or $\overline{\text{RTS}}$ to use
	TXEPT	Transmit register empty flag
	CRD	Enable or disable the $\overline{\text{CTS}}$ or $\overline{\text{RTS}}$ function
	NCH	Select TxDi pin output mode
	CKPOL	Set to 0
	UFORM	LSB first or MSB first can be selected when transfer data is 8 bits long. Set this bit to 0 when transfer data is 7 or 9 bits long.
UiC1	TE	Set this bit to 1 to enable transmission
	TI	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception
	RI	Reception complete flag
	U2IRS (2)	Select the source of UART2 transmit interrupt
	U2RRM (2)	Set to 0
	UiLCH (3)	Set this bit to 1 to use UART2 inverted data logic
	UiERE (3)	Set to 0
UiSMR	0 to 7	Set to 0
UiSMR2	0 to 7	Set to 0
UiSMR3	0 to 7	Set to 0
UiSMR4	0 to 7	Set to 0
UCON	U0IRS, U1IRS	Select the source of UART0/UART1 transmit interrupt
	U0RRM, U1RRM	Set to 0
	CLKMD0	Invalid because CLKMD1 is set to 0
	CLKMD1	Set to 0
	RCSP	Set this bit to 1 to accept as input the UART0 $\overline{\text{CTS}_0}$ signal from the $P6_4$ pin
	7	Set to 0

NOTES:

1. The bits used for transmit/receive data are as follows: Bit 0 to bit 6 when transfer data is 7 bits long; bits 7 to 0 when transfer data is 8 bits long; bit 0 to bit 8 when transfer data is 9 bits long.
2. Set bits 5 and 4 in registers U0C1 and U1C1 to 0. Bits U0IRS, U1IRS, U0RRM and U1RRM are included in the UCON register.
3. Set bits 7 and 6 in registers U0C1 and U1C1 to 0.
4. Set the bit 7 in registers U0MR and U1MR to 0.

i=0 to 2

Table 14.7 lists the functions of the input/output pins in UART mode. **Table 14.8** lists the P64 pin functions during UART mode. Note that for a period from when the UARTi operation mode is selected to when transfer starts, the TxDi pin outputs an “H”. (If the N-channel open-drain output is selected, this pin is in a high-impedance state.)

Table 14.7 I/O Pin Functions in UART mode(1)

Pin Name	Function	Method of Selection
TxDi (i = 0 to 2) (P63, P67, P70)	Serial data output	(Outputs "H" when performing reception only)
RxDi (P62, P66, P71)	Serial data input	PD6_2 bit, PD6_6 bit in the PD6 register and the PD7_1 bit in the PD7 register (Can be used as an input port when performing transmission only)
CLKi (P61, P65, P72)	Input/output port	Set the CKDIR bit in the UiMR register to 0
	Transfer clock input	Set the CKDIR bit in the UiMR register to 1 Set the PD6_1 bit and PD6_5 bit in the PD6 register to 0, PD7_2 bit in the PD7 register to 0
$\overline{\mathrm{CTSi}}$/$\overline{\mathrm{RTSi}}$ (P60, P64, P73)	$\overline{\mathrm{CTS}}$ input	Set the CRD bit in the UiC0 register to 0 Set the CRS bit in the UiC0 register to 0 Set the PD6_0 bit and PD6_4 bit in the PD6 register to 0, the PD7_3 bit in the PD7 register 0
	$\overline{\mathrm{RTS}}$ output	Set the CRD bit in the UiC0 register to 0 Set the CRS bit in the UiC0 register to 1
	Input/output port	Set the CRD bit in the UiC0 register 1

NOTE:

1. When the U1MAP bit in PACR register is set to 1 (P73 to P70), UART1 pin is assgined to P73 to P70.

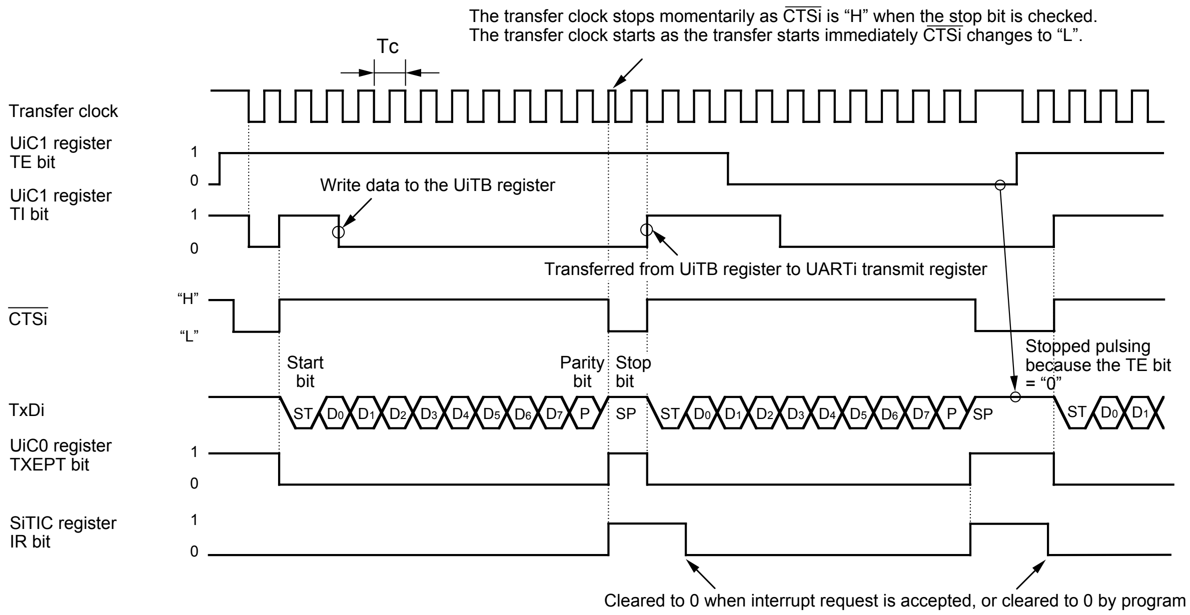
Table 14.8 P64 Pin Functions in UART mode (1)

Pin Function	Bit Set Value				
	U1C0 register		UCON register		PD6 register
	CRD	CRS	RCSP	CLKMD1	PD6_4
P64	1	—	0	0	Input: 0, Output: 1
$\overline{\mathrm{CTS1}}$	0	0	0	0	0
$\overline{\mathrm{RTS1}}$	0	1	0	0	—
$\overline{\mathrm{CTS0}}$ (2)	0	0	1	0	0

NOTES:

1. When the U1MAP bit in PACR register is 1 (P73 to P70), this table lists the P70 functions.
2. In addition to this, set the CRD bit in the U0C0 register to 0 ($\overline{\mathrm{CTS0}}$/$\overline{\mathrm{RTS0}}$ enabled) and the CRS bit in the U0C0 register to 1 ($\overline{\mathrm{RTS0}}$ selected).

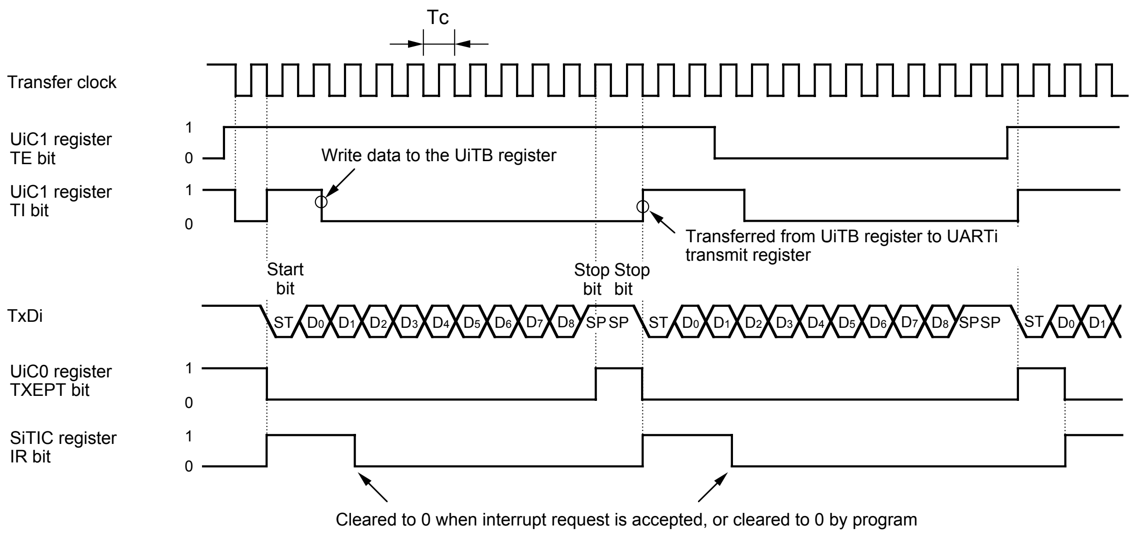
• Example of transmit timing when transfer data is 8-bit long (parity enabled, one stop bit)



The above timing diagram applies to the case where the register bits are set as follows:
- Set the PRYE bit in the UiMR register to 1 (parity enabled)
- Set the STPS bit in the UiMR register to 0 (1 stop bit)
- Set the CRD bit in the UiC0 register to 0 (CTS/RTS enabled), the CRS bit to 0 (CTS selected).
- Set the UiIRS bit to 1 (an interrupt request occurs when transmit completed): U0IRS bit is the UCON register bit 0, U1IRS bit is the UCON register bit 1, and U2IRS bit is the U2C1 register bit 4

Tc = 16 (n + 1) / fj or 16 (n + 1) / fEXT
fj: frequency of UiBRG count source (f1SIO, f2SIO, f8SIO, f32SIO)
fEXT: frequency of UiBRG count source (external clock)
n: value set to UiBRG
i = 0 to 2

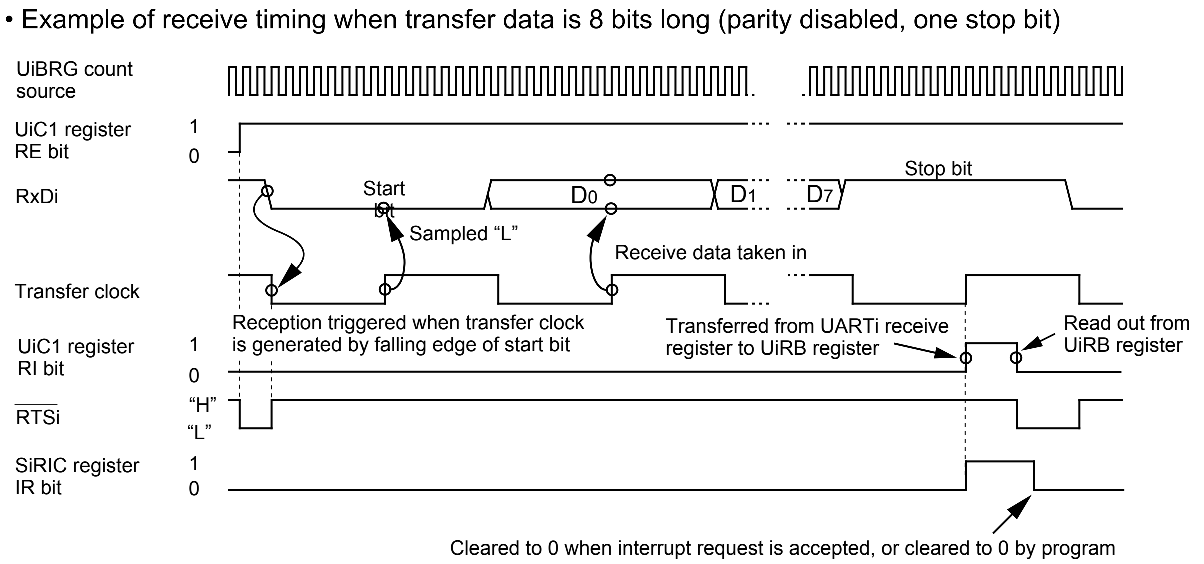
• Example of transmit timing when transfer data is 9-bit long (parity disabled, two stop bits)



The above timing diagram applies to the case where the register bits are set as follows:
- Set the PRYE bit in the UiMR register to 0 (parity disabled)
- Set the STPS bit in the UiMR register to 1 (2 stop bits)
- Set the CRD bit in the UiC0 register to 1 (CTS/RTS disabled)
- Set the UiIRS bit to 0 (an interrupt request occurs when transmit buffer becomes empty): U0IRS bit is the UCON register bit 0, U1IRS bit is the UCON register bit 1, and U2IRS bit is the U2C1 register bit 4

Tc = 16 (n + 1) / fj or 16 (n + 1) / fEXT
fj: frequency of UiBRG count source (f1SIO, f2SIO, f8SIO, f32SIO)
fEXT: frequency of UiBRG count source (external clock)
n: value set to UiBRG
i = 0 to 2

Figure 14.16 Typical transmit timing in UART mode (UART0, UART1)



The above timing diagram applies to the case where the register bits are set as follows:
• Set the PRYE bit in the UiMR register to 0 (parity disabled)
• Set the STPS bit in the UiMR register to 0 (1 stop bit)
• Set the CRD bit in the UiC0 register to 0 (CTSi/RTSi enabled), the CRS bit to 1 (RTSi selected)
i = 0 to 2

Figure 14.17 Receive Operation

14.1.2.1 Bit Rates

In UART mode, the frequency set by the UiBRG register (i=0 to 2) divided by 16 become the bit rates. **Table 14.9** lists example of bit rate and settings.

Table 14.9 Example of Bit Rates and Settings

Bit Rate (bps)	Count Source of BRG	Peripheral Function Clock : 16MHz		Peripheral Function Clock : 20MHz	
		Set Value of BRG : n	Actual Time (bps)	Set Value of BRG : n	Actual Time (bps)
1200	f8	103(67h)	1202	129(81h)	1202
2400	f8	51(33h)	2404	64(40h)	2404
4800	f8	25(19h)	4808	32(20h)	4735
9600	f1	103(67h)	9615	129(81h)	9615
14400	f1	68(44h)	14493	86(56h)	14368
19200	f1	51(33h)	19231	64(40h)	19231
28800	f1	34(22h)	28571	42(2Ah)	29070
31250	f1	31(1Fh)	31250	39(27h)	31250
38400	f1	25(19h)	38462	32(20h)	37879
51200	f1	19(13h)	50000	24(18h)	50000

14.1.2.2 Counter Measure for Communication Error

If a communication error occurs while transmitting or receiving in UART mode, follow the procedure below.

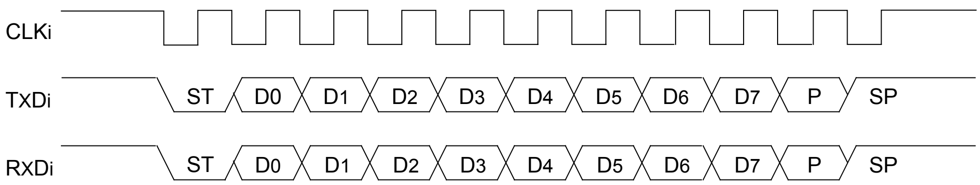
• Resetting the UiRB register (i=0 to 2)
(1) Set the RE bit in the UiC1 register to 0 (reception disabled)
(2) Set the RE bit in the UiC1 register to 1 (reception enabled)

• Resetting the UiTB register (i=0 to 2)
(1) Set bits SMD2 to SMD0 in UiMR register 000_2 (Serial I/O disabled)
(2) Set bits SMD2 to SMD0 in UiMR register 001_2, 101_2, 110_2
(3) 1 is written to TE bit in the UiC1 register (reception enabled), regardless of the TE bit

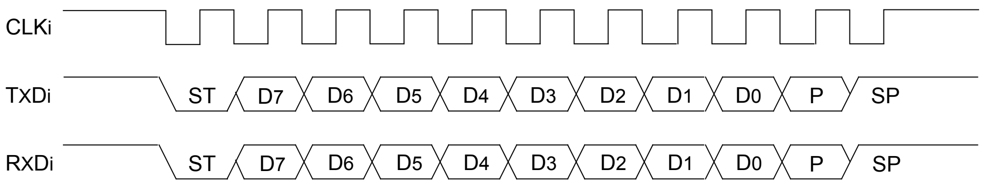
14.1.2.3 LSB First/MSB First Select Function

As shown in **Figure 14.18**, use the UFORM bit in the UiC0 register to select the transfer format. This function is valid when transfer data is 8 bits long.

(1) When the UFORM bit in the UiC0 register is set to 0 (LSB first)



(2) When the UFORM bit in the UiC0 register is set to 1 (MSB first)



ST : Start bit
P : Parity bit
SP : Stop bit
i = 0 to 2

NOTE:
1. This applies to the case where the CKPOL bit in the UiC0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock), the UiLCH bit in the UiC1 register is set to 0 (no reverse), the STPS bit in the UiMR register is set to 0 (1 stop bit) and the PRYE bit in the UiMR register is set to 1 (parity enabled).

Figure 14.18 Transfer Format

14.1.2.4 Serial Data Logic Switching Function (UART2)

The data written to the U2TB register has its logic reversed before being transmitted. Similarly, the received data has its logic reversed when read from the U2RB register. **Figure 14.19** shows serial data logic.

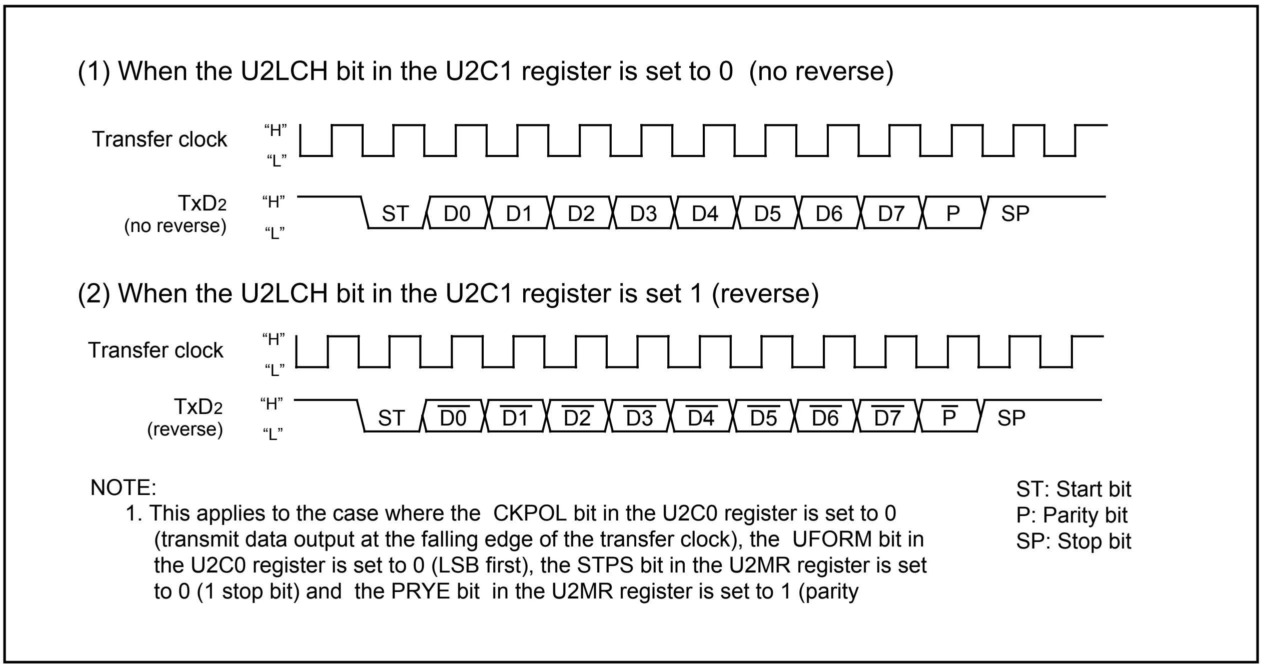


Figure 14.19 Serial Data Logic Switching

14.1.2.5 TxD and RxD I/O Polarity Inverse Function (UART2)

This function inverses the polarities of the TxD2 pin output and RxD2 pin input. The logic levels of all input/output data (including the start, stop and parity bits) are inversed. **Figure 14.20** shows the TxD pin output and RxD pin input polarity inverse.

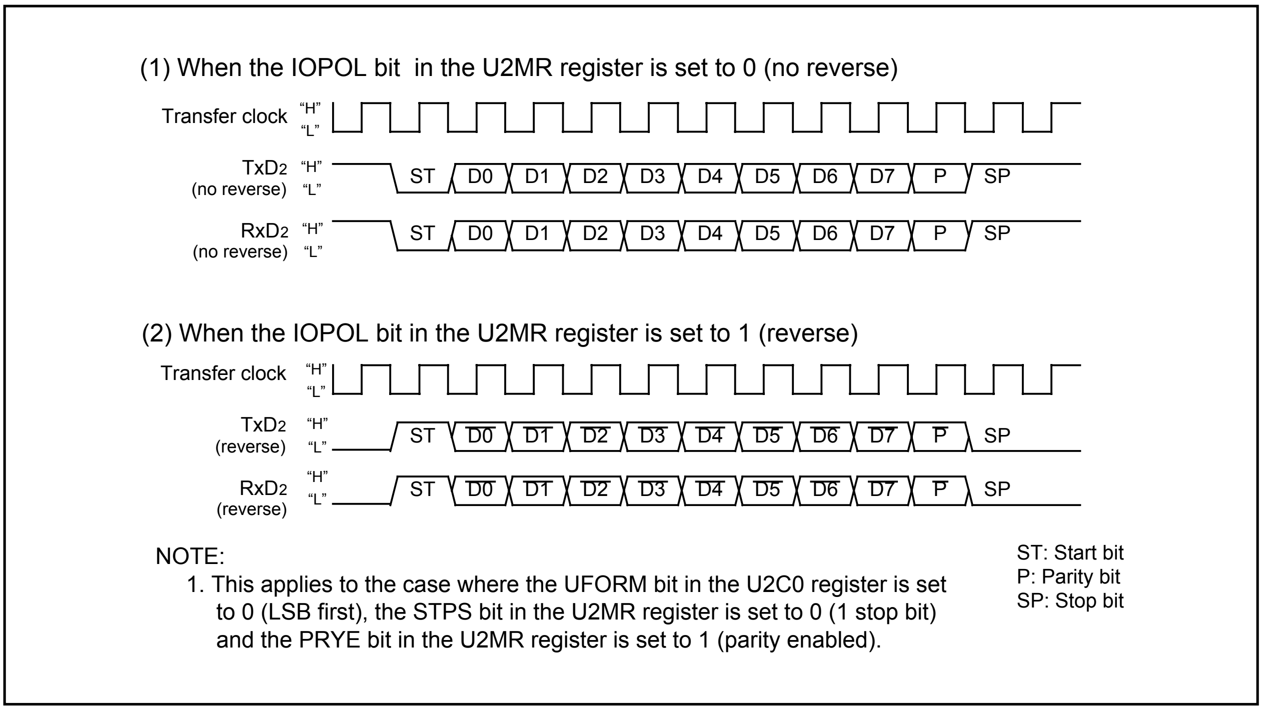


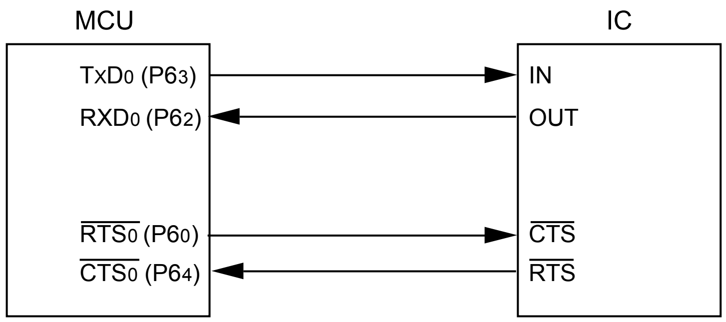
Figure 14.20 TxD and RxD I/O Polarity Inverse

14.1.2.6 $\overline{\text{CTS}}/\overline{\text{RTS}}$ Separate Function (UART0)

This function separates $\overline{\text{CTS}_0}/\overline{\text{RTS}_0}$, outputs $\overline{\text{RTS}_0}$ from the $P6_0$ pin, and accepts as input the $\overline{\text{CTS}_0}$ from the $P6_4$ pin or $P7_0$ pin. To use this function, set the register bits as shown below.

- The CRD bit in the U0C0 register is set to 0 (enables UART0 $\overline{\text{CTS}}/\overline{\text{RTS}}$)
- The CRS bit in the U0C0 register is set to 1 (outputs UART0 $\overline{\text{RTS}}$)
- The CRD bit in the U1C0 register is set to 0 (enables UART1 $\overline{\text{CTS}}/\overline{\text{RTS}}$)
- The CRS bit in the U1C0 register is set to 0 (inputs UART1 $\overline{\text{CTS}}$)
- The RCSP bit in the UCON register is set to 1 (inputs $\overline{\text{CTS}_0}$ from the $P6_4$ pin or $P7_0$ pin)
- The CLKMD1 bit in the UCON register is set to 0 ($CLKS_1$ not used)

Note that when using the $\overline{\text{CTS}}/\overline{\text{RTS}}$ separate function, UART1 $\overline{\text{CTS}}/\overline{\text{RTS}}$ separate function cannot be used.



NOTE:
1. This applies to the case where the U1MAP bit in the PACR register is set to 0 ($P6_7$ to $P6_4$).

Figure 14.21 $\overline{\text{CTS}}/\overline{\text{RTS}}$ Separate Function

14.1.3 Special Mode 1 (I^{2}C bus mode)(UART2)

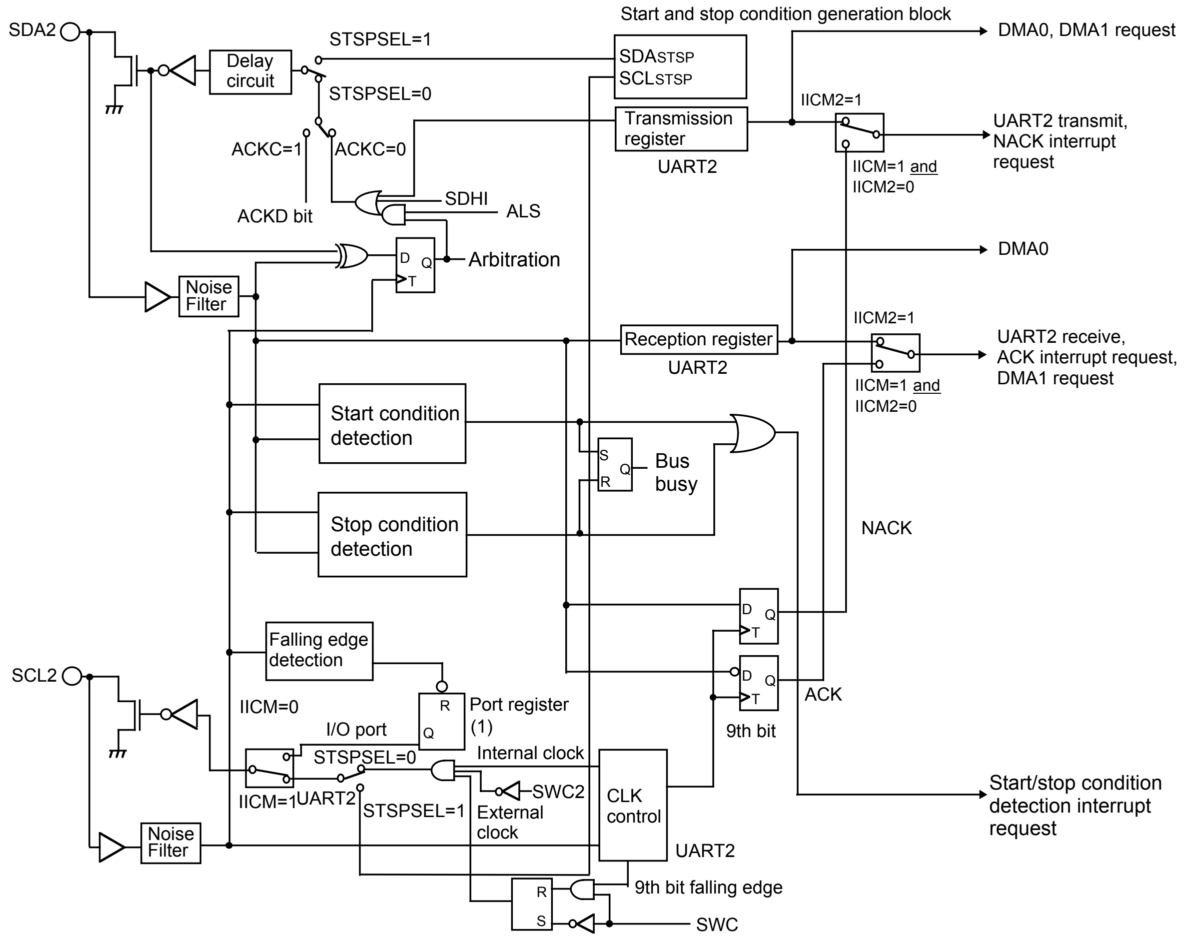
I^{2}C bus mode is provided for use as a simplifed I^{2}C bus interface compatible mode. **Table 14.10** lists the specifications of the I^{2}C bus mode. **Tables 14.11** and **14.12** list the registers used in the I^{2}C bus mode and the register values set. **Table 14.13** lists the I^{2}C bus mode fuctions. **Figure 14.22** shows the block diagram for I^{2}C bus mode. **Figure 14.23** shows SCL_2 timing.

As shown in **Table 14.13**, the MCU is placed in I^{2}C bus mode by setting bits SMD2 to SMD0 to 010_2 and the IICM bit to 1. Because SDA_2 transmit output has a delay circuit attached, SDA output does not change state until SCL_2 goes low and remains stably low.

Table 14.10 I^{2}C bus mode Specifications

Item	Specification
Transfer data format	• Transfer data length: 8 bits
Transfer clock	• During master the CKDIR bit in the U2MR register is set to 0 (internal clock) : fj/ (2(n+1)) fj = f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}. n: Setting value in the U2BRG register 00_{16} to FF_{16} • During slave CKDIR bit is set to 1 (external clock) : Input from SCL_2 pin
Transmission start condition	• Before transmission can start, the following requirements must be met (1) – The TE bit in the U2C1 register is set to 1 (transmission enabled) – The TI bit in the U2C1 register is set to 0 (data present in U2TB register)
Reception start condition	• Before reception can start, the following requirements must be met (1) – The RE bit in the U2C1 register is set to 1 (reception enabled) – The TE bit in the U2C1 register is set to 1 (transmission enabled) – The TI bit in the U2C1 register is set to 0 (data present in the UiTB register)
Interrupt request generation timing	When start or stop condition is detected, acknowledge undetected, and acknowledge detected
Error detection	• Overrun error (2) This error occurs if the serial I/O started receiving the next data before reading the U2RB register and received the 8th bit in the the next data
Select function	• Arbitration lost Timing at which the ABT bit in the U2RB register is updated can be selected • SDA digital delay No digital delay or a delay of 2 to 8 U2BRG count source clock cycles selectable • Clock phase setting With or without clock delay selectable

NOTES:
1. When an external clock is selected, the conditions must be met while the external clock is in the high state.
2. If an overrun error occurs, bits 8 to 0 in the U2RB register are undefined. The IR bit in the S2RIC register remains unchange.



This diagram applies to the case where bits SMD2 to SMD0 in the U2MR register is set to 010_2 and the IICM bit in the U2SMR register is set to 1.

IICM: Bit in the U2SMR register
IICM2, SWC, ALS, SWC2, SDHI: Bits in the U2SMR2 register
STSPSEL, ACKD, ACKC: Bits in the U2SMR4 register

NOTE:
1. If the IICM bit is set to 1, the pin can be read even when the PD7_1 bit is set to 1 (output mode).

Figure 14.22 I²C bus mode Block Diagram

Table 14.11 Registers to Be Used and Settings in I^2C bus mode (1) (Continued)

Register	Bit	Function	
		Master	Slave
U2TB	0 to 7	Set transmission data	Set transmission data
U2RB(1)	0 to 7	Reception data can be read	Reception data can be read
	8	ACK or NACK is set in this bit	ACK or NACK is set in this bit
	ABT	Arbitration lost detection flag	Invalid
	OER	Overrun error flag	Overrun error flag
U2BRG	0 to 7	Set bit rate	Invalid
U2MR(1)	SMD2 to SMD0	Set to 010_2	Set to 010_2
	CKDIR	Set to 0	Set to 1
	IOPOL	Set to 0	Set to 0
U2C0	CLK1, CLK0	Select the count source for the U2BRG register	Invalid
	CRS	Invalid because CRD = 1	Invalid because CRD = 1
	TXEPT	Transmit buffer empty flag	Transmit buffer empty flag
	CRD	Set to 1	Set to 1
	NCH	Set to 1	Set to 1
	CKPOL	Set to 0	Set to 0
	UFORM	Set to 1	Set to 1
U2C1	TE	Set this bit to 1 to enable transmission	Set this bit to 1 to enable transmission
	TI	Transmit buffer empty flag	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception	Set this bit to 1 to enable reception
	RI	Reception complete flag	Reception complete flag
	U2IRS	Invalid	Invalid
	U2RRM, U2LCH, U2ERE	Set to 0	Set to 0
U2SMR	IICM	Set to 1	Set to 1
	ABC	Select the timing at which arbitration-lost is detected	Invalid
	BBS	Bus busy flag	Bus busy flag
	3 to 7	Set to 0	Set to 0
U2SMR2	IICM2	Refer to **Table 14.13**	Refer to **Table 14.13**
	CSC	Set this bit to 1 to enable clock synchronization	Set to 0
	SWC	Set this bit to 1 to have SCL_2 output fixed to L at the falling edge of the 9th bit of clock	Set this bit to 1 to have SCL_2 output fixed to "L" at the falling edge of the 9^{th} bit of clock
	ALS	Set this bit to 1 to have SDA_2 output stopped when arbitration-lost is detected	Set to 0
	STAC	Set to 0	Set this bit to 1 to initialize UART2 at start condition detection
	SWC2	Set this bit to 1 to have SCL_2 output forcibly pulled low	Set this bit to 1 to have SCL_2 output forcibly pulled low
	SDHI	Set this bit to 1 to disable SDA_2 output	Set this bit to 1 to disable SDA_2 output
	7	Set to 0	Set to 0
U2SMR3	0, 2, 4 and NODC	Set to 0	Set to 0
	CKPH	Refer to **Table 14.13**	Refer to **Table 14.13**
	DL2 to DL0	Set the amount of SDA_2 digital delay	Set the amount of SDA_2 digital delay

NOTE:
1. Not all bits in the register are described above. Set those bits to 0 when writing to the registers in I^2C bus mode.

Table 14.12 Registers to Be Used and Settings in I^{2}C bus Mode (2) (Continued)

Register	Bit	Function	
		Master	Slave
U2SMR4	STAREQ	Set this bit to 1 to generate start condition	Set to 0
	RSTAREQ	Set this bit to 1 to generate restart condition	Set to 0
	STPREQ	Set this bit to 1 to generate stop condition	Set to 0
	STSPSEL	Set this bit to 1 to output each condition	Set to 0
	ACKD	Select ACK or NACK	Select ACK or NACK
	ACKC	Set this bit to 1 to output ACK data	Set this bit to 1 to output ACK data
	SCLHI	Set this bit to 1 to have SCL_2 output stopped when stop condition is detected	Set to 0
	SWC9	Set to 0	Set this bit to 1 to set the SCL_2 to “L” hold at the falling edge of the 9th bit of clock

NOTE:

1: Not all bits in the register are described above. Set those bits to 0 when writing to the registers in I^{2}C bus mode.

Table 14.13 I^{2}C bus mode Functions

Function	Clock synchronous serial I/O mode (SMD2 to SMD0 = 001_2, IICM = 0)	I^{2}C bus mode (SMD2 to SMD0 = 010_2, IICM = 1)			
		IICM2 = 0 (NACK/ACK interrupt)		IICM2 = 1 (UART transmit/ receive interrupt)	
		CKPH = 0 (No clock delay)	CKPH = 1 (Clock delay)	CKPH = 0 (No clock delay)	CKPH = 1 (Clock delay)
Factor of interrupt number 10 (1) (Refer to **Fig.14.23**)	———	Start condition detection or stop condition detection (Refer to **Table 14.14**)			
Factor of interrupt number 15 (1) (Refer to **Fig.14.23**)	UART2 transmission Transmission started or completed (selected by U2IRS)	No acknowledgment detection (NACK) Rising edge of SCL$_2$ 9th bit		UART2 transmission Rising edge of SCL$_2$ 9th bit	UART2 transmission Falling edge of SCL$_2$ next to the 9th bit
Factor of interrupt number 16 (1) (Refer to **Fig.14.23**)	UART2 reception When 8th bit received CKPOL = 0 (rising edge) CKPOL = 1 (falling edge)	Acknowledgment detection (ACK) Rising edge of SCL$_2$ 9th bit		UART2 transmission Falling edge of SCL$_2$ 9th bit	
Timing for transferring data from the UART reception shift register to the U2RB register	CKPOL = 0 (rising edge) CKPOL = 1 (falling edge)	Rising edge of SCL$_2$ 9th bit		Falling edge of SCL$_2$ 9th bit	Falling and rising edges of SCL$_2$ 9th bit
UART2 transmission output delay	Not delayed	Delayed			
Functions of P7$_0$ pin	TxD2 output	SDA$_2$ input/output			
Functions of P7$_1$ pin	RxD2 input	SCL$_2$ input/output			
Functions of P7$_2$ pin	CLK2 input or output selected	——— (Cannot be used in I^{2}C bus mode)			
Noise filter width	15ns	200ns			
Read RxD2 and SCL$_2$ pin levels	Possible when the corresponding port direction bit = 0	Always possible no matter how the corresponding port direction bit is set			
Initial value of TxD2 and SDA$_2$ outputs	CKPOL = 0 (H) CKPOL = 1 (L)	The value set in the port register before setting I^{2}C bus mode (2)			
Initial and end values of SCL$_2$	———	H	L	H	L
DMA1 factor (Refer to **Fig. 14.23**)	UART2 reception	Acknowledgment detection (ACK)		UART2 reception Falling edge of SCL$_2$ 9th bit	
Store received data	1st to 8th bits are stored in bits bit 7 to 0 in the U2RB register	1st to 8th bits are stored in bits bit 7 to 0 in the U2RB register		1st to 7th bits are stored into the bit 6 to bit 0 in the U2RB register, with 8th bit stored in the bit 8 in the U2RB register	1st to 8th bits are stored in U2RB register bit 7 to bit 0 (3)
Read received data	U2RB register status is read directly as is				Read U2RB register Bit 6 to bit 0 as bit 7 to bit 1, and bit 8 as bit 0 (4)

NOTES:
1. If the source or cause of any interrupt is changed, the IR bit in the interrupt control register for the changed interrupt may inadvertently be set to 1 (interrupt requested). (Refer to "Notes on interrupts" in Precautions.)
   If one of the bits shown below is changed, the interrupt source, the interrupt timing, etc. change. Therefore, always be sure to clear the IR bit to 0 (interrupt not requested) after changing those bits
   Bits SMD2 to the SMD0 in the U2MR register, the IICM bit in the U2SMR register, the IICM2 bit in the U2SMR2 register, the CKPH bit in the U2SMR3 register
2. Set the initial value of SDA$_2$ output while bits SMD2 to SMD0 in the U2MR register is set to 000_2 (serial I/O disabled).
3. Second data transfer to U2RB register (Rising edge of SCL$_2$ 9th bit)
4. First data transfer to U2RB register (Falling edge of SCL$_2$ 9th bit)

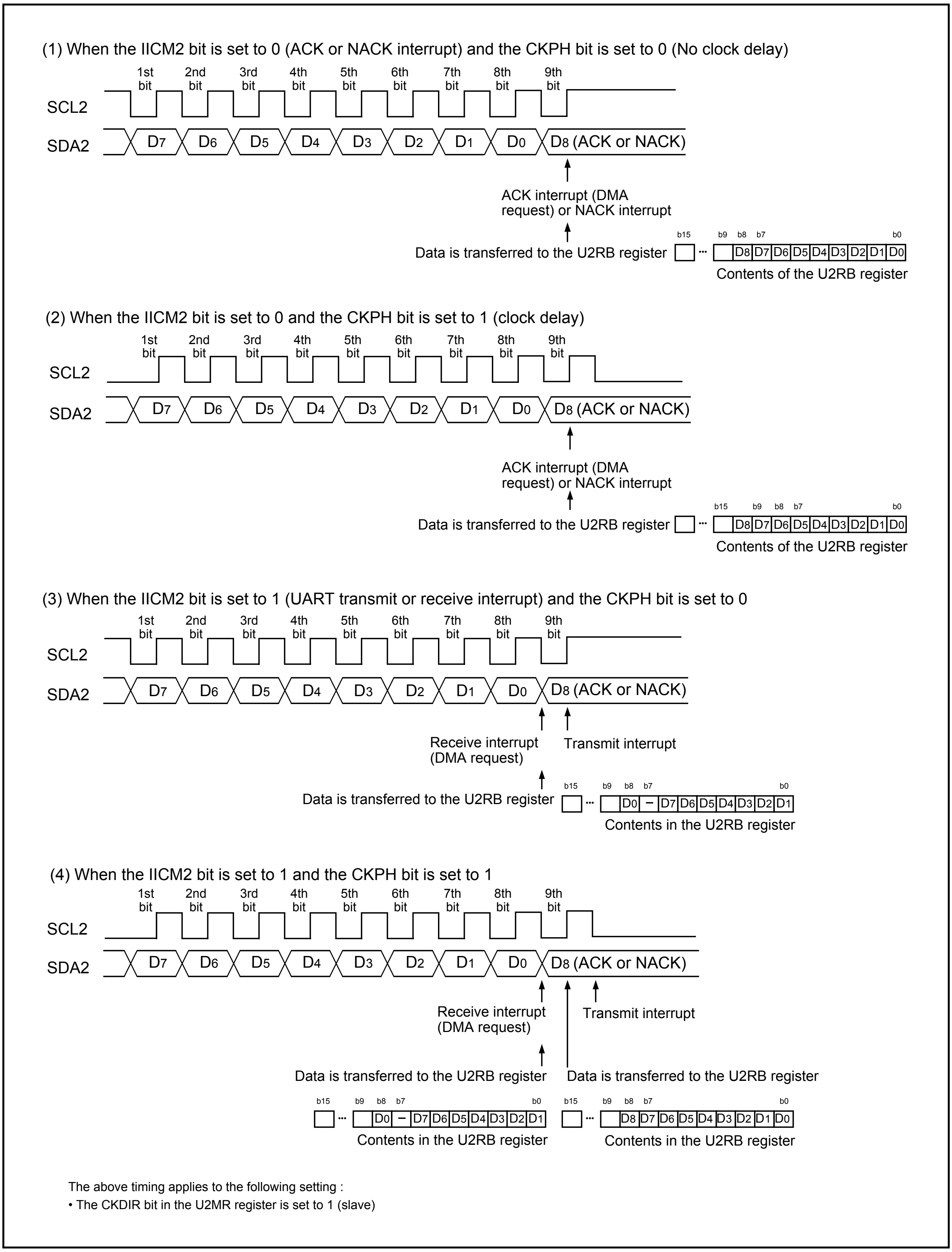


Figure 14.23 Transfer to U2RB Register and Interrupt Timing

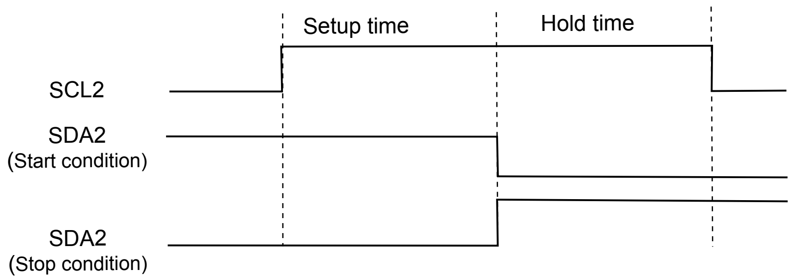
14.1.3.1 Detection of Start and Stop Condition

Whether a start or a stop condition has been detected is determined.

A start condition-detected interrupt request is generated when the SDA2 pin changes state from high to low while the SCL2 pin is in the high state. A stop condition-detected interrupt request is generated when the SDA2 pin changes state from low to high while the SCL2 pin is in the high state.

Because the start and stop condition-detected interrupts share the interrupt control register and vector, check the BBS bit in the U2SMR register to determine which interrupt source is requesting the interrupt.

3 to 6 cycles < setup time (1)
3 to 6 cycles < hold time (1)



NOTE:

1. When the PCLK1 bit in the PCLKR register is set to 1, the cycles indicates the f1SIO's generation frequency cycles; when PCLK1 bit is set to 0, the cycles indicated the f2SIO's generation frequency cycles.

Figure 14.24 Detection of Start and Stop Condition

14.1.3.2 Output of Start and Stop Condition

A start condition is generated by setting the STAREQ bit in the U2SMR4 register to 1 (start).

A restart condition is generated by setting the RSTAREQ bit in the U2SMR4 register to 1 (start).

A stop condition is generated by setting the STPREQ bit in the U2SMR4 register to 1 (start).

The output procedure is described below.

(1) Set the STAREQ bit, RSTAREQ bit or STPREQ bit to 1 (start).

(2) Set the STSPSEL bit in the U2SMR4 register to 1 (output).

Make sure that no interrupts or DMA transfers will occur between (1) and (2).

The function of the STSPSEL bit is shown in **Table 14.14** and **Figure 14.25**.

Table 14.14 STSPSEL Bit Functions

Function	STSPSEL = 0	STSPSEL = 1
Output of SCL2 and SDA2 pins	Output transfer clock and data/ Program with a port determines how the start condition or stop condition is output	The STAREQ, RSTAREQ and STPREQ bit determine how the start condition or stop condition is output
Start/stop condition interrupt request generation timing	Start/stop condition are detected	Start/stop condition generation are completed

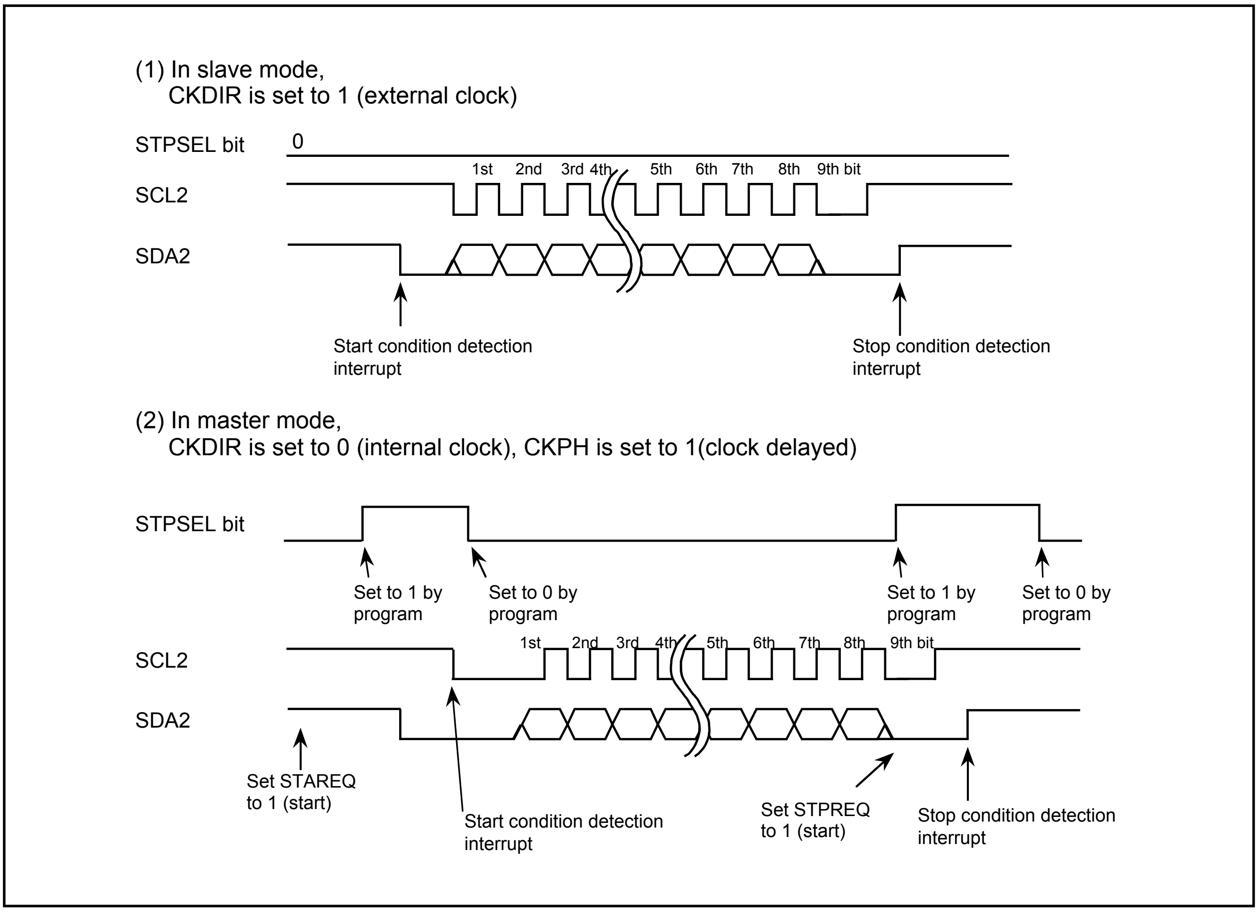


Figure 14.25 STSPSEL Bit Functions

14.1.3.3 Arbitration

Unmatching of the transmit data and SDA2 pin input data is checked synchronously with the rising edge of SCL2. Use the ABC bit in the U2SMR register to select the timing at which the ABT bit in the U2RB register is updated. If the ABC bit is set to 0 (updated bitwise), the ABT bit is set to 1 at the same time unmatching is detected during check, and is cleared to 0 when not detected. In cases when the ABC bit is set to 1, if unmatching is detected even once during check, the ABT bit is set to 1 (unmatching detected) at the falling edge of the clock pulse of 9th bit. If the ABT bit needs to be updated bytewise, clear the ABT bit to 0 (undetected) after detecting acknowledge in the first byte, before transferring the next byte.

Setting the ALS bit in the U2SMR2 register to 1 (SDA2 output stop enabled) causes arbitration-lost to occur, in which case the SDA2 pin is placed in the high-impedance state at the same time the ABT bit is set to 1 (unmatching detected).

14.1.3.4 Transfer Clock

Data is transmitted/received using a transfer clock like the one shown in **Figure 14.25**.

The CSC bit in the U2SMR2 register is used to synchronize the internally generated clock (internal SCL2) and an external clock supplied to the SCL_2 pin. In cases when the CSC bit is set to 1 (clock synchronization enabled), if a falling edge on the SCL_2 pin is detected while the internal SCL_2 is high, the internal SCL_2 goes low, at which time the U2BRG register value is reloaded with and starts counting in the low-level interval. If the internal SCL_2 changes state from low to high while the SCL_2 pin is low, counting stops, and when the SCL_2 pin goes high, counting restarts.

In this way, the UART2 transfer clock is comprised of the logical product of the internal SCL_2 and SCL_2 pin signal. The transfer clock works from a half period before the falling edge of the internal SCL_2 1st bit to the rising edge of the 9^{th} bit. To use this function, select an internal clock for the transfer clock.

The SWC bit in the U2SMR2 register allows to select whether the SCL_2 pin should be fixed to or freed from low-level output at the falling edge of the 9th clock pulse.

If the SCLHI bit in the U2SMR4 register is set to 1 (enabled), SCL_2 output is turned off (placed in the high-impedance state) when a stop condition is detected.

Setting the SWC2 bit in the U2SMR2 register is set to 1 (0 output) makes it possible to forcibly output a low-level signal from the SCL_2 pin even while sending or receiving data. Clearing the SWC2 bit to 0 (transfer clock) allows the transfer clock to be output from or supplied to the SCL_2 pin, instead of outputting a low-level signal.

If the SWC9 bit in the U2SMR4 register is set to 1 (SCL_2 hold low enabled) when the CKPH bit in the U2SMR3 register is set to 1, the SCL_2 pin is fixed to low-level output at the falling edge of the clock pulse next to the ninth. Setting the SWC9 bit to 0 (SCL_2 hold low disabled) frees the SCL_2 pin from low-level output.

14.1.3.5 SDA Output

The data written to the bit 7 to bit 0 (D_7 to D_0) in the U2TB register is sequentially output beginning with D_7. The ninth bit (D_8) is ACK or NACK.

The initial value of SDA_2 transmit output can only be set when IICM is set to 1 (I^2C bus mode) and bits SMD2 to SMD0 in the U2MR register is set to 000_2 (serial I/O disabled).

Bits DL2 to DL0 in the U2SMR3 register allow to add no delays or a delay of 2 to 8 U2BRG count source clock cycles to SDA_2 output.

Setting the SDHI bit in the U2SMR2 register to 1 (SDA_2 output disabled) forcibly places the SDA_2 pin in the high-impedance state. Do not write to the SDHI bit synchronously with the rising edge of the UART2 transfer clock. This is because the ABT bit may inadvertently be set to 1 (detected).

14.1.3.6 SDA Input

When the IICM2 bit is set to 0, the 1st to 8th bits (D_7 to D_0) in the received data are stored in bits 7 to 0 in the U2RB register. The 9th bit (D_8) is ACK or NACK.

When the IICM2 bit is set to 1, the 1st to 7th bits (D_7 to D_1) in the received data are stored in the bit 6 to bit 0 in the U2RB register and the 8th bit (D_0) is stored in the bit 8 in the U2RB register. Even when the IICM2 bit is set to 1, providing the CKPH bit is set to 1, the same data as when the IICM2 bit is set to 0 can be read out by reading the U2RB register after the rising edge of the corresponding clock pulse of 9th bit.

14.1.3.7 ACK and NACK

If the STSPSEL bit in the U2SMR4 register is set to 0 (start and stop conditions not generated) and the ACKC bit in the U2SMR4 register is set to 1 (ACK data output), the value of the ACKD bit in the U2SMR4 register is output from the SDA_2 pin.

If the IICM2 bit is set to 0, a NACK interrupt request is generated if the SDA_2 pin remains high at the rising edge of the 9th bit of transmit clock pulse. An ACK interrupt request is generated if the SDA_2 pin is low at the rising edge of the 9th bit of transmit clock pulse.

If ACK2 is selected for the cause of DMA1 request, a DMA transfer can be activated by detection of an acknowledge.

14.1.3.8 Initialization of Transmission/Reception

If a start condition is detected while the STAC bit is set to 1 (UART2 initialization enabled), the serial I/O operates as described below.

- The transmit shift register is initialized, and the content of the U2TB register is transferred to the transmit shift register. In this way, the serial I/O starts sending data synchronously with the next clock pulse applied. However, the UART2 output value does not change state and remains the same as when a start condition was detected until the first bit in the data is output synchronously with the input clock.
- The receive shift register is initialized, and the serial I/O starts receiving data synchronously with the next clock pulse applied.
- The SWC bit is set to 1 (SCL_2 wait output enabled). Consequently, the SCL_2 pin is pulled low at the falling edge of the ninth clock pulse.

Note that when UART2 transmission/reception is started using this function, the TI does not change state. Note also that when using this function, the selected transfer clock should be an external clock.

14.1.4 Special Mode 2 (UART2)

Multiple slaves can be serially communicated from one master. Transfer clock polarity and phase are selectable. **Table 14.15** lists the specifications of Special Mode 2. **Table 14.16** lists the registers used in Special Mode 2 and the register values set. **Figure 14.26** shows communication control example for Special Mode 2.

Table 14.15 Special Mode 2 Specifications

Item	Specification
Transfer data format	• Transfer data length: 8 bits
Transfer clock	• Master mode the CKDIR bit in the U2MR register is set to 0 (internal clock) : fj/ (2(n+1)) fj = f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}. n: Setting value in the U2BRG register 00_{16} to FF_{16} • Slave mode CKDIR bit is set to 1 (external clock selected) : Input from CLK2 pin
Transmit/receive control	Controlled by input/output ports
Transmission start condition	• Before transmission can start, the following requirements must be met (1) – The TE bit in the U2C1 register is set to 1 (transmission enabled) – The TI bit in the U2C1 register is set to 0 (data present in U2TB register)
Reception start condition	• Before reception can start, the following requirements must be met (1) – The RE bit in the U2C1 register is set to 1 (reception enabled) – The TE bit in the U2C1 register is set to 1 (transmission enabled) – The TI bit in the U2C1 register is set to 0 (data present in the U2TB register)
Interrupt request generation timing	• For transmission, one of the following conditions can be selected – The U2IRS bit in the U2C1 register is set to 0 (transmit buffer empty): when transferring data from the U2TB register to the UART2 transmit register (at start of transmission) – The U2IRS bit is set to 1 (transfer completed): when the serial I/O finished sending data from the UART2 transmit register • For reception When transferring data from the UART2 receive register to the U2RB register (at completion of reception)
Error detection	• Overrun error (2) This error occurs if the serial I/O started receiving the next data before reading the U2RB register and received the 7th bit in the the next data
Select function	• Clock phase setting Selectable from four combinations of transfer clock polarities and phases

NOTES:
1. When an external clock is selected, the conditions must be met while if the CKPOL bit in the U2C0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock), the external clock is in the high state; if the CKPOL bit in the U2C0 register is set to 1 (transmit data output at the rising edge and the receive data taken in at the falling edge of the transfer clock), the external clock is in the low state.
2. If an overrun error occurs, bits 8 to 0 in the U2RB register are undefined. The IR bit in the S2RIC register remains unchanged.

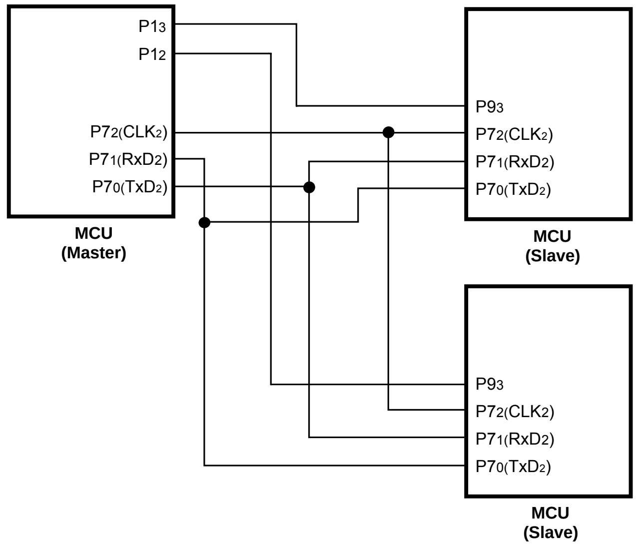


Figure 14.26 Serial Bus Communication Control Example (UART2)

Table 14.16 Registers to Be Used and Settings in Special Mode 2

Register	Bit	Function
U2TB(1)	0 to 7	Set transmission data
U2RB(1)	0 to 7	Reception data can be read
	OER	Overrun error flag
U2BRG	0 to 7	Set bit rate
U2MR(1)	SMD2 to SMD0	Set to 001_2
	CKDIR	Set this bit to 0 for master mode or 1 for slave mode
	IOPOL	Set to 0
U2C0	CLK1, CLK0	Select the count source for the U2BRG register
	CRS	Invalid because CRD is set to 1
	TXEPT	Transmit register empty flag
	CRD	Set to 1
	NCH	Select TxD2 pin output format
	CKPOL	Clock phases can be set in combination with the CKPH bit in the U2SMR3 register
	UFORM	Select the LSB first or MSB first
U2C1	TE	Set this bit to 1 to enable transmission
	TI	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception
	RI	Reception complete flag
	U2IRS	Select UART2 transmit interrupt cause
	U2RRM, U2LCH, U2ERE	Set to 0
U2SMR	0 to 7	Set to 0
U2SMR2	0 to 7	Set to 0
U2SMR3	CKPH	Clock phases can be set in combination with the CKPOL bit in the U2C0 register
	NODC	Set to 0
	0, 2, 4 to 7	Set to 0
U2SMR4	0 to 7	Set to 0

NOTE:
1. Not all bits in the registers are described above. Set those bits to 0 when writing to the registers in Special Mode 2.

14.1.4.1 Clock Phase Setting Function

One of four combinations of transfer clock phases and polarities can be selected using the CKPH bit in the U2SMR3 register and the CKPOL bit in the U2C0 register.
Make sure the transfer clock polarity and phase are the same for the master and slave to communicate.

14.1.4.1.1 Master (Internal Clock)

Figure 14.27 shows the transmission and reception timing in master (internal clock).

14.1.4.1.2 Slave (External Clock)

Figure 14.28 shows the transmission and reception timing (CKPH=0) in slave (external clock) while **Figure 14.29** shows the transmission and reception timing (CKPH=1) in slave (external clock).

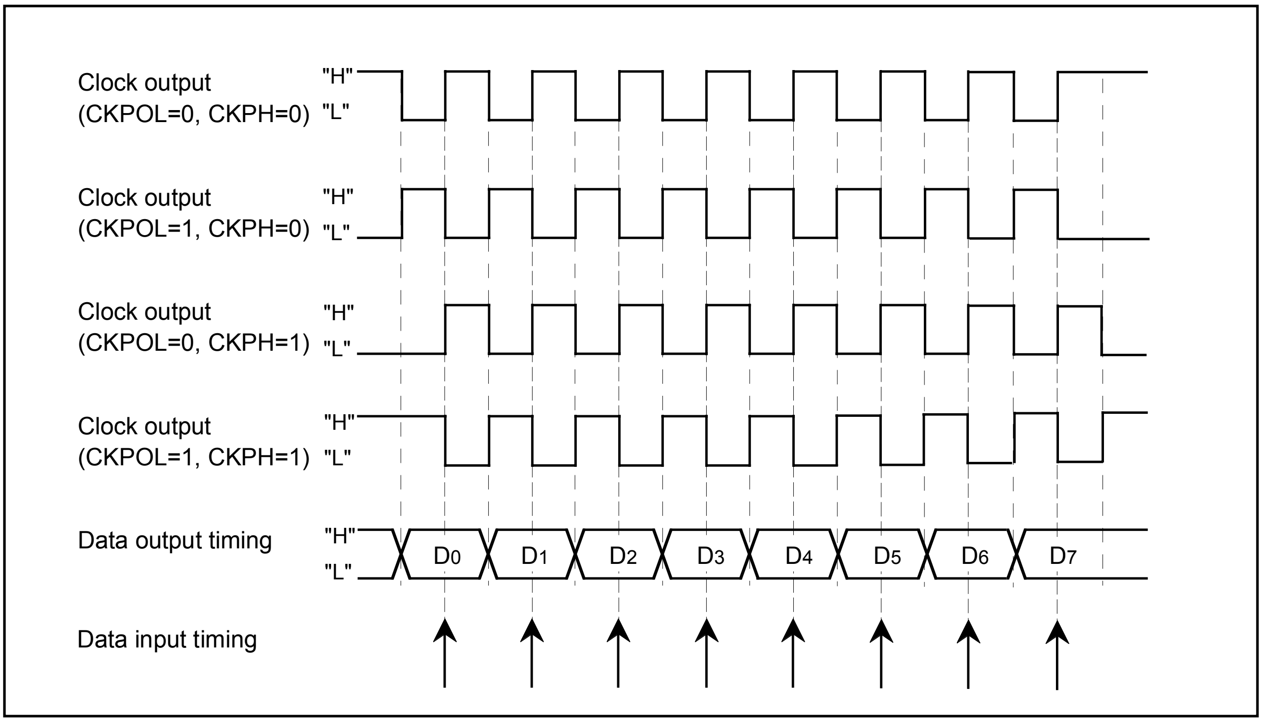


Figure 14.27 Transmission and Reception Timing in Master Mode (Internal Clock)

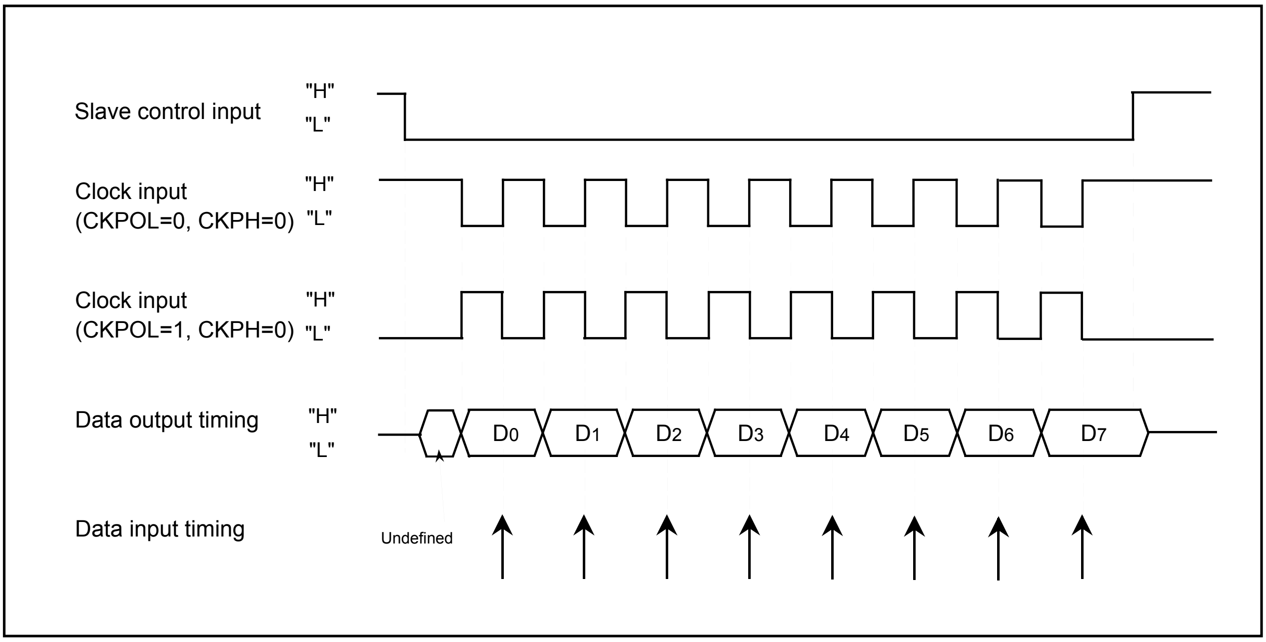


Figure 14.28 Transmission and Reception Timing (CKPH=0) in Slave Mode (External Clock)

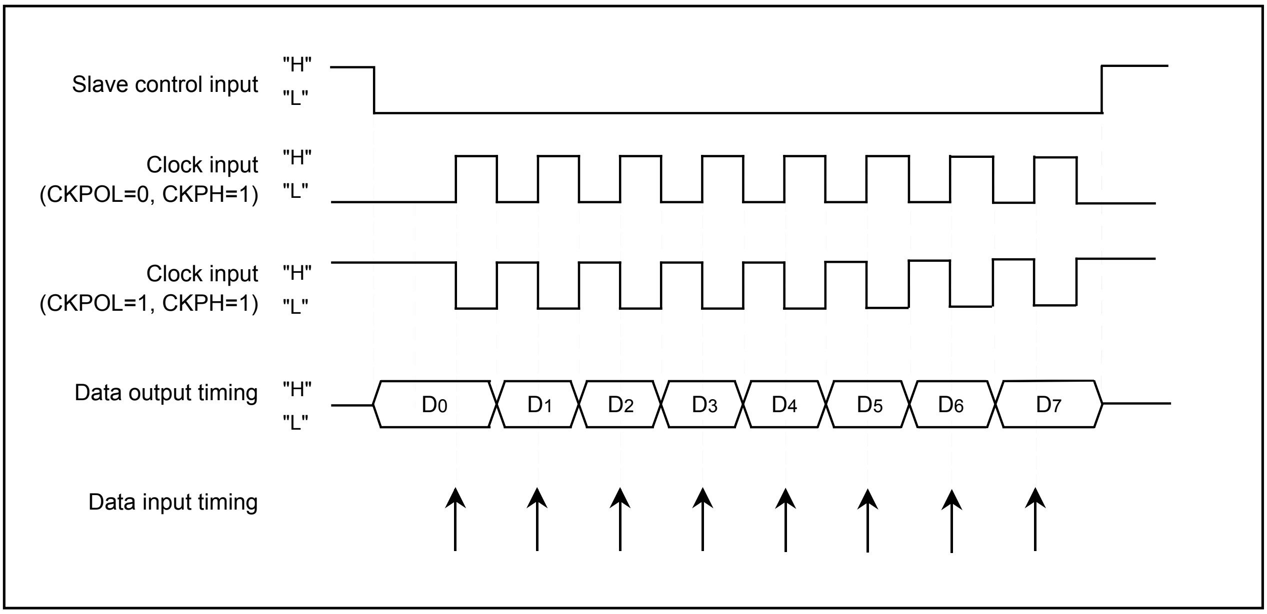


Figure 14.29 Transmission and Reception Timing (CKPH=1) in Slave Mode (External Clock)

14.1.5 Special Mode 3 (IEBus mode)(UART2)

In this mode, one bit in the IEBus is approximated with one byte of UART mode waveform.

Table 14.17 lists the registers used in IEBus mode and the register values set. **Figure 14.30** shows the functions of bus collision detect function related bits.

If the TxD2 pin output level and RxD2 pin input level do not match, a UART2 bus collision detect interrupt request is generated.

Table 14.17 Registers to Be Used and Settings in IEBus Mode

Register	Bit	Function
U2TB	0 to 8	Set transmission data
U2RB(1)	0 to 8	Reception data can be read
	OER,FER,PER,SUM	Error flag
U2BRG	0 to 7	Set bit rate
U2MR	SMD2 to SMD0	Set to 110_2
	CKDIR	Select the internal clock or external clock
	STPS	Set to 0
	PRY	Invalid because PRYE is set to 0
	PRYE	Set to 0
	IOPOL	Select the TxD/RxD input/output polarity
U2C0	CLK1, CLK0	Select the count source for the U2BRG register
	CRS	Invalid because CRDis set to 1
	TXEPT	Transmit register empty flag
	CRD	Set to 1
	NCH	Select TxD2 pin output mode
	CKPOL	Set to 0
	UFORM	Set to 0
U2C1	TE	Set this bit to 1 to enable transmission
	TI	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception
	RI	Reception complete flag
	U2IRS	Select the source of UART2 transmit interrupt
	U2RRM, U2LCH, U2ERE	Set to 0
U2SMR	0 to 3, 7	Set to 0
	ABSCS	Select the sampling timing at which to detect a bus collision
	ACSE	Set this bit to 1 to use the auto clear function of transmit enable bit
	SSS	Select the transmit start condition
U2SMR2	0 to 7	Set to 0
U2SMR3	0 to 7	Set to 0
U2SMR4	0 to 7	Set to 0

NOTE:
1. Not all register bits are described above. Set those bits to 0 when writing to the registers in IEBus mode.

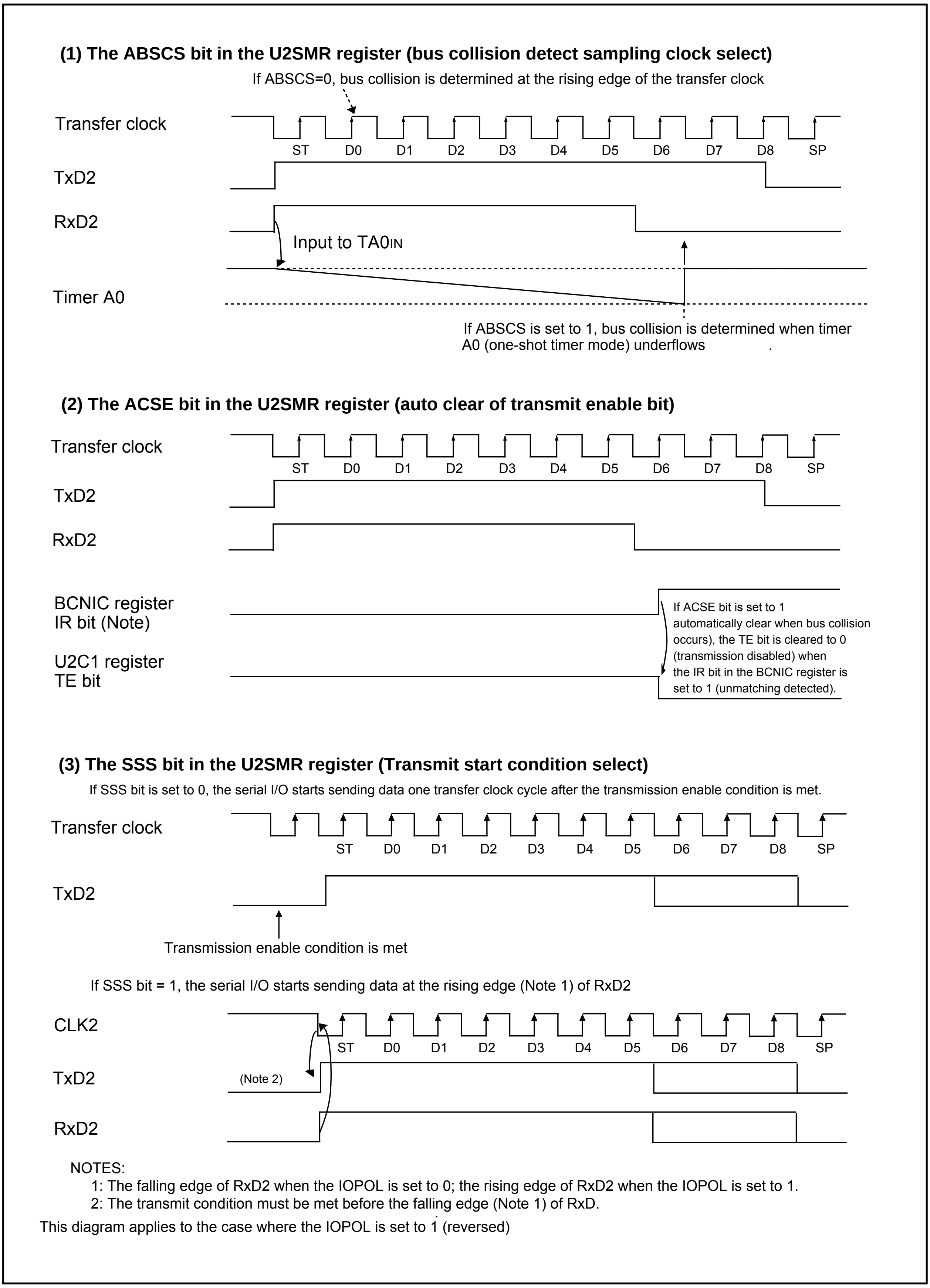


Figure 14.30 Bus Collision Detect Function-Related Bits

14.1.6 Special Mode 4 (SIM Mode) (UART2)

Based on UART mode, this is an SIM interface compatible mode. Direct and inverse formats can be implemented, and this mode allows output of a low from the TxD2 pin when a parity error is detected. **Table 14.18** lists the specifications of SIM mode. **Table 14.19** lists the registers used in the SIM mode and the register values set.

Table 14.18 SIM Mode Specifications

Item	Specification
Transfer data format	• Direct format • Inverse format
Transfer clock	• The CKDIR bit in the U2MR register is set to 0 (internal clock) : fi/ (16(n+1)) fi = f1SIO, f2SIO, f8SIO, f32SIO. n: Setting value of U2BRG register 00_{16} to FF_{16} • The CKDIR bit is set to 1 (external clock) : fEXT/16(n+1) fEXT: Input from CLK2 pin. n: Setting value of U2BRG register 00_{16} to FF_{16}
Transmission start condition	• Before transmission can start, the following requirements must be met – The TE bit in the U2C1 register is set to 1 (transmission enabled) – The TI bit in the U2C1 register is set to 0 (data present in U2TB register)
Reception start condition	• Before reception can start, the following requirements must be met – The RE bit in the U2C1 register is set to 1 (reception enabled) – Start bit detection
Interrupt request generation timing (2)	• For transmission When the serial I/O finished sending data from the U2TB transfer register (U2IRS bit =1) • For reception When transferring data from the UART2 receive register to the U2RB register (at completion of reception)
Error detection	• Overrun error (1) This error occurs if the serial I/O started receiving the next data before reading the U2RB register and received the bit one before the last stop bit in the the next data • Framing error This error occurs when the number of stop bits set is not detected • Parity error During reception, if a parity error is detected, parity error signal is output from the TxD2 pin. During transmission, a parity error is detected by the level of input to the RxD2 pin when a transmission interrupt occurs • Error sum flag This flag is set to 1 when any of the overrun, framing, and parity errors is encountered

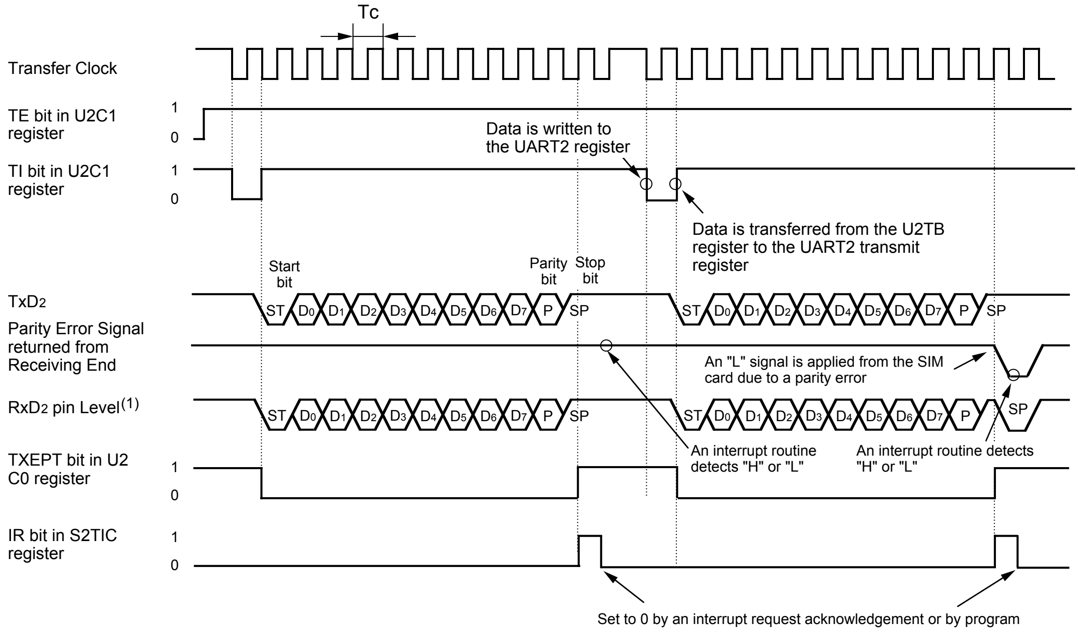
NOTES:
1. If an overrun error occurs, bits 8 to 0 in the U2RB register are undefined. The IR bit in the S2RIC register remains unchanged.
2. A transmit interrupt request is generated by setting the U2IRS bit in the U2C1 register to 1 (transmission complete) and U2ERE bit to 1 (error signal output) after reset. Therefore, when using SIM mode, be sure to clear the IR bit to 0 (no interrupt request) after setting these bits.

Table 14.19 Registers to Be Used and Settings in SIM Mode

Register	Bit	Function
U2TB(1)	0 to 7	Set transmission data
U2RB(1)	0 to 7	Reception data can be read
	OER,FER,PER,SUM	Error flag
U2BRG	0 to 7	Set bit rate
U2MR	SMD2 to SMD0	Set to 101_2
	CKDIR	Select the internal clock or external clock
	STPS	Set to 0
	PRY	Set this bit to 1 for direct format or 0 for inverse format
	PRYE	Set to 1
	IOPOL	Set to 0
U2C0	CLK1, CLK0	Select the count source for the U2BRG register
	CRS	Invalid because CRDis set to 1
	TXEPT	Transmit register empty flag
	CRD	Set to 1
	NCH	Set to 0
	CKPOL	Set to 0
	UFORM	Set this bit to 0 for direct format or 1 for inverse format
U2C1	TE	Set this bit to 1 to enable transmission
	TI	Transmit buffer empty flag
	RE	Set this bit to 1 to enable reception
	RI	Reception complete flag
	U2IRS	Set to 1
	U2RRM	Set to 0
	U2LCH	Set this bit to 0 for direct format or 1 for inverse format
	U2ERE	Set to 1
U2SMR(1)	0 to 3	Set to 0
U2SMR2	0 to 7	Set to 0
U2SMR3	0 to 7	Set to 0
U2SMR4	0 to 7	Set to 0

NOTE:
1. Not all register bits are described above. Set those bits to 0 when writing to the registers in SIM mode.

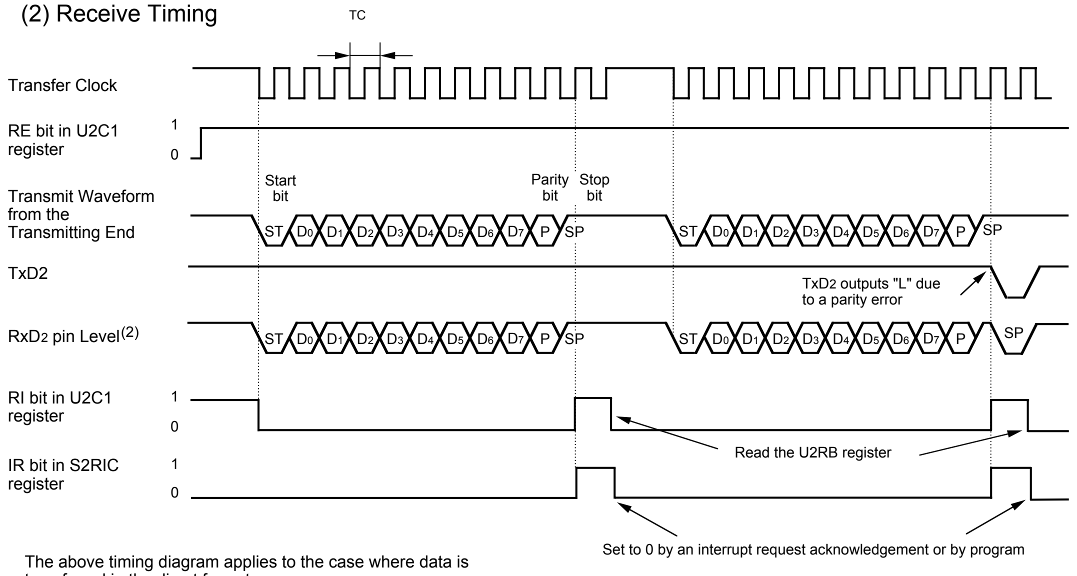
(1) Transmit Timing



The above timing diagram applies to the case where data is transferred in the direct format.
- U2MR register STPS bit = 0 (1 stop bit)
- U2MR register PRY bit = 1 (even)
- U2C0 register UFORM bit = 0 (LSB first)
- U2C1 register U2LCH bit = 0 (no reverse)
- U2C1 register U2IRSCH bit = 1 (transmit is completed)

Tc = 16 (n + 1) / fi or 16 (n + 1) / f_{EXT}
fi : frequency of U2BRG count source (f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO})
f_{EXT} : frequency of U2BRG count source (external clock)
n : value set to U2BRG

(2) Receive Timing



The above timing diagram applies to the case where data is transferred in the direct format.
- U2MR register STPS bit = 0 (1 stop bit)
- U2MR register PRY bit = 1 (even)
- U2C0 register UFORM bit = 0 (LSB first)
- U2C1 register U2LCH bit = 0 (no reverse)
- U2C1 register U2IRSCH bit = 1 (transmit is completed)

Tc = 16 (n + 1) / fi or 16 (n + 1) / f_{EXT}
fi : frequency of U2BRG count source (f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO})
f_{EXT} : frequency of U2BRG count source (external clock)
n : value set to U2BRG

NOTES:
1. Because TxD2 and RxD2 are connected, this is composite waveform consisting of the TxD2 output and the parity error signal sent back from receiver.
2. Because TxD2 and RxD2 are connected, this is composite waveform consisting of the transmitter's transmit waveform and the parity error signal received.

Figure 14.31 Transmit and Receive Timing in SIM Mode

Figure 14.32 shows the example of connecting the SIM interface. Connect TxD2 and RxD2 and apply pull-up.

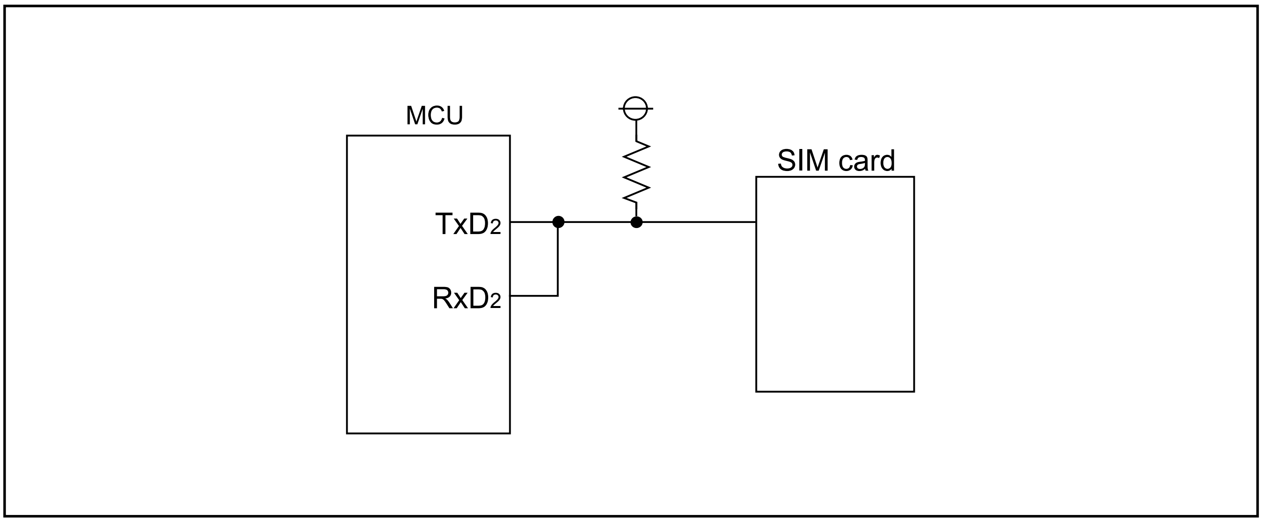


Figure 14.32 SIM Interface Connection

14.1.6.1 Parity Error Signal Output

The parity error signal is enabled by setting the U2ERE bit in theU2C1 register to 1.

• When receiving

The parity error signal is output when a parity error is detected while receiving data. This is achieved by pulling the TxD2 output low with the timing shown in **Figure 14.33**. If the R2RB register is read while outputting a parity error signal, the PER bit is cleared to 0 and at the same time the TxD2 output is returned high.

• When transmitting

A transmission-finished interrupt request is generated at the falling edge of the transfer clock pulse that immediately follows the stop bit. Therefore, whether a parity signal has been returned can be determined by reading the port that shares the RxD2 pin in a transmission-finished interrupt service routine.

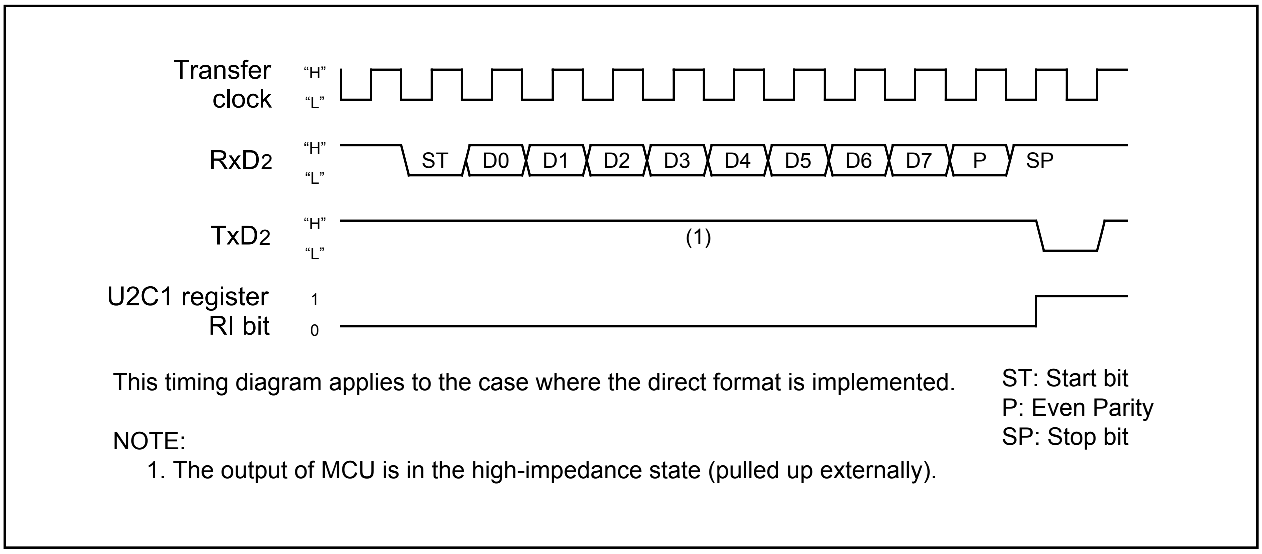


Figure 14.33 Parity Error Signal Output Timing

14.1.6.2 Format

• Direct Format

Set the PRY bit in the U2MR register to 1, the UFORM bit in U2C0 register to 0 and the U2LCH bit in U2C1 register to 0.

• Inverse Format

Set the PRY bit to 0, UFORM bit to 1 and U2LCH bit to 1.

Figure 14.34 shows the SIM interface format.

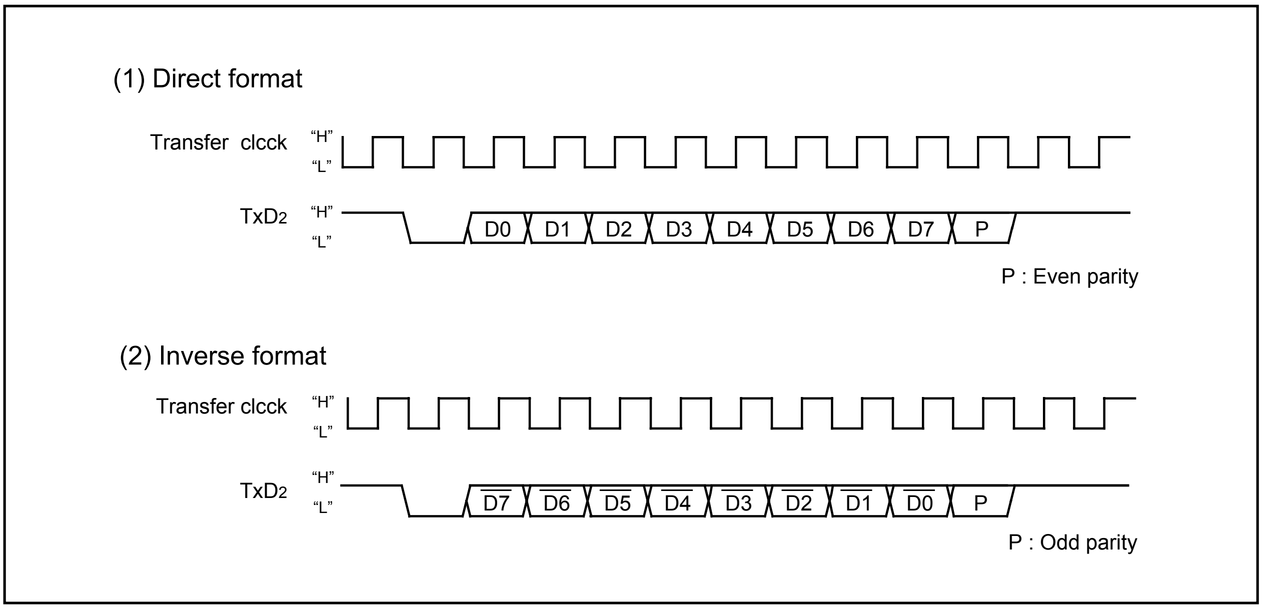


Figure 14.34 SIM Interface Format

14.2 SI/O3 and SI/O4

Note

The SI/O4 interrupt of peripheral function interrupt is not available in the 64-pin package.

SI/O3 and SI/O4 are exclusive clock-synchronous serial I/Os.

Figure 14.35 shows the block diagram of SI/O3 and SI/O4, and **Figure 14.36** shows the SI/O3 and SI/O4-related registers.

Table 14.20 shows the specifications of SI/O3 and SI/O4.

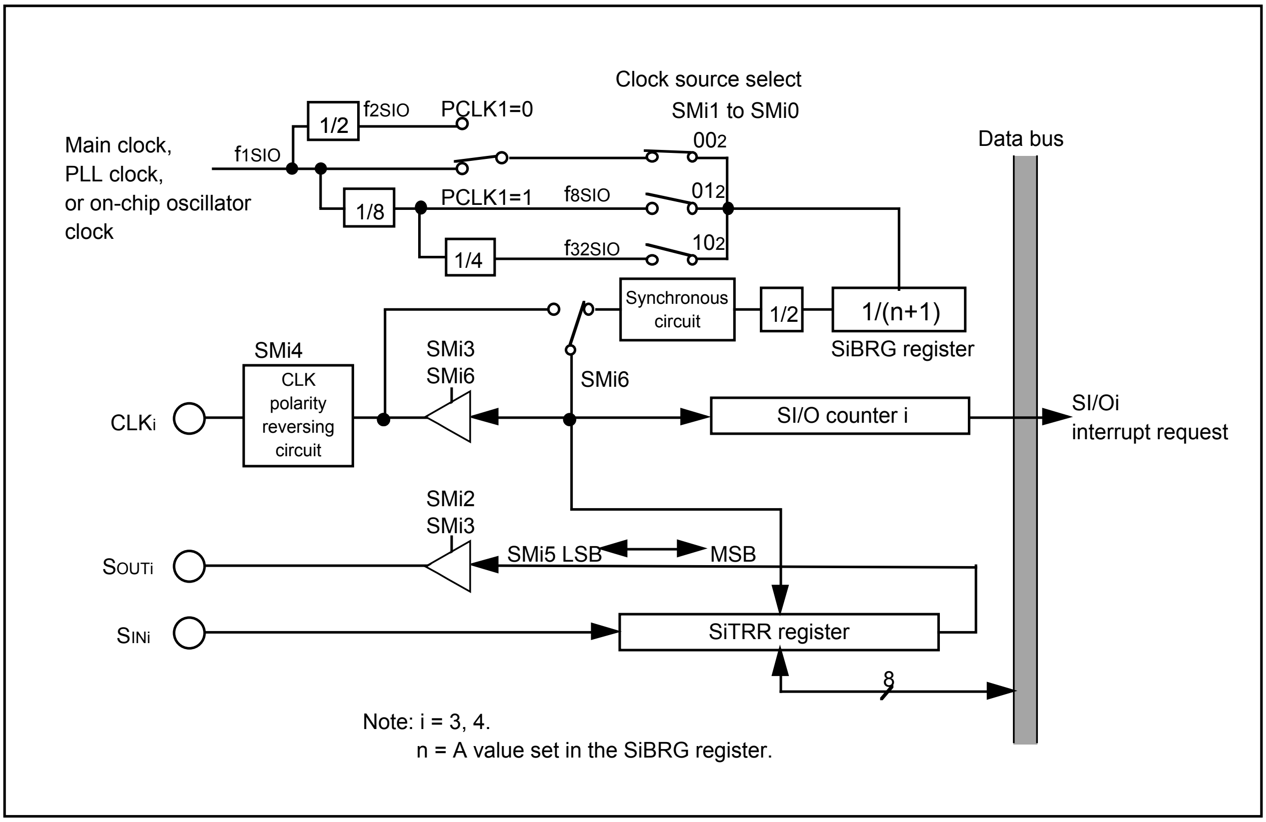
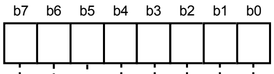


Figure 14.35 SI/O3 and SI/O4 Block Diagram

SI/Oi Control Register (i = 3, 4) (1)

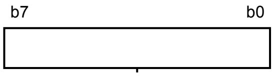


Symbol	Address	After Reset
S3C	0362_{16}	01000000_2
S4C	0366_{16}	01000000_2

Bit Symbol	Bit Name	Function	RW
SMi0	Internal synchronous clock select bit (5)	b1 b0 0 0 : Selecting f1 or f2 0 1 : Selecting f8 1 0 : Selecting f32 1 1 : Do not set	RW
SMi1			RW
SMi2	SOUTi output disable bit (4)	0 : SOUTi output 1 : SOUTi output disable(high impedance)	RW
SMi3	S I/Oi port select bit	0 : Input/output port 1 : SOUTi output, CLKi function	RW
SMi4	CLK polarity selct bit	0 : Transmit data is output at falling edge of transfer clock and receive data is input at rising edge 1 : Transmit data is output at rising edge of transfer clock and receive data is input at falling edge	RW
SMi5	Transfer direction select bit	0 : LSB first 1 : MSB first	RW
SMi6	Synchronous clock select bit	0 : External clock (2) 1 : Internal clock (3)	RW
SMi7	SOUTi initial value set bit	Effective when the SMi3 is set to 0 0 : “L” output 1 : “H” output	RW

NOTES:
1. Set the S4C register by the next instruction after setting the PRC2 bit in the PRCR register to 1 (write enable).
2. Set the SMi3 bit to 1 and the corresponding port direction bit to 0 (input mode).
3. Set the SMi3 bit to 1 (SOUTi output, CLKi function) .
4. When the SMi2 bit is set to 1, the corresponding pin goes to high-impedance regardless of the function in use.
5. When the SMi1 and SMi0 bit settings are changed, set the SiBRG register .

SI/Oi Bit Rate Generation Register (i = 3, 4) (1, 2, 3)

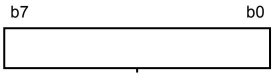


Symbol	Address	After Reset
S3BRG	0363_{16}	Undefined
S4BRG	0367_{16}	Undefined

Description	Setting Range	RW
Assuming that set value = n, BRGi divides the count source by n + 1	00_{16} to FF_{16}	WO

NOTES:
1. Write to this register while serial I/O is neither transmitting or receiving.
2. Use MOV instruction to write to this register.
3. Set the SiBRG register after setting bits SMi1 and SMi0 in the SiC register.

SI/Oi Transmit/Receive Register (i = 3, 4) (1, 2)



Symbol	Address	After Reset
S3TRR	0360_{16}	Undefined
S4TRR	0364_{16}	Undefined

Description	RW
Transmission/reception starts by writing transmit data to this register. After transmission/reception completion, reception data can be read by reading this register.	RW

NOTES:
1. Write to this register while serial I/O is neither transmitting or receiving.
2. To receive data, set the corresponding port direction bit for SINi to 0 (input mode).

Figure 14.36 S3C and S4C Registers, S3BRG and S4BRG Registers, and S3TRR and S4TRR Registers

Table 14.20 SI/O3 and SI/O4 Specifications

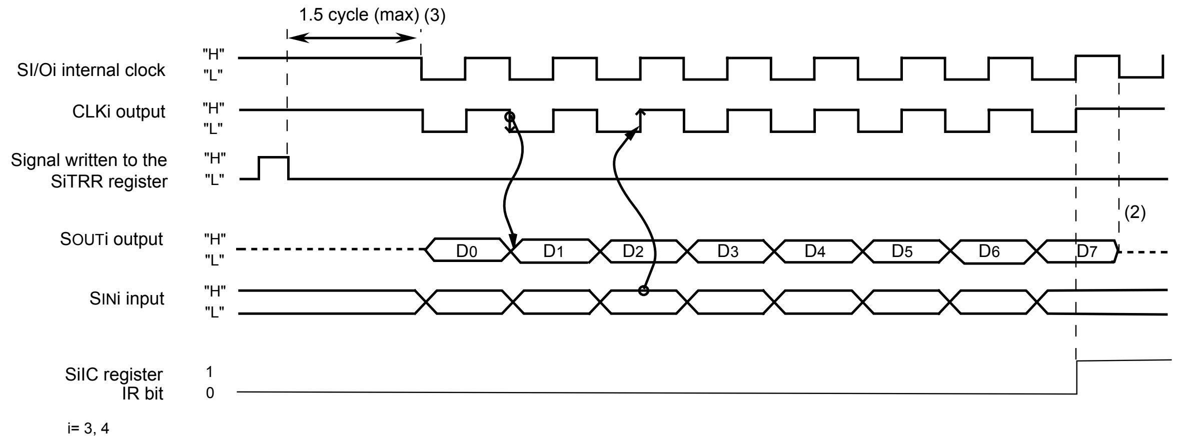
Item	Specification
Transfer data format	• Transfer data length: 8 bits
Transfer clock	• The SMi6 bit in the SiC (i=3, 4) register is set to 1 (internal clock) : fj/ (2(n+1)) fj = f1SIO, f2SIO, f8SIO, f32SIO. n=Setting value of SiBRG register 0016 to FF16. • SMi6 bit is set to 0 (external clock) : Input from CLKi pin (1)
Transmission/reception start condition	• Before transmission/reception can start, the following requirements must be met Write transmit data to the SiTRR register (2, 3)
Interrupt request generation timing	• When the SMi4 bit in the SiC register is set to 0 The rising edge of the last transfer clock pulse (4) • When SMi4 is set to 1 The falling edge of the last transfer clock pulse (4)
CLKi pin fucntion	I/O port, transfer clock input, transfer clock output
SOUTi pin function	I/O port, transmit data output, high-impedance
SINi pin function	I/O port, receive data input
Select function	• LSB first or MSB first selection Whether to start sending/receiving data beginning with bit 0 or beginning with bit 7 can be selected • Function for setting an SOUTi initial value set function When the SMi6 bit in the SiC register is set to 0 (external clock), the SOUTi pin output level while not tranmitting can be selected. • CLK polarity selection Whether transmit data is output/input timing at the rising edge or falling edge of transfer clock can be selected.

NOTE:

1. To set the SMi6 bit in the SiC register to 0 (external clock), follow the procedure described below.
   - If the SMi4 bit in the SiC register is set to 0, write transmit data to the SiTRR register while input on the CLKi pin is high. The same applies when rewriting the SMi7 bit in the SiC register.
   - If the SMi4 bit is set to 1, write transmit data to the SiTRR register while input on the CLKi pin is low. The same applies when rewriting the SMi7 bit.
   - Because shift operation continues as long as the transfer clock is supplied to the SI/Oi circuit, stop the transfer clock 2. Unlike UART0 to UART2, SI/Oi (i = 3 to 4) is not separated between the transfer register and buffer. Therefore, do not write the next transmit data to the SiTRR register during transmission.
3. When the SMi6 bit in the SiC register is set to 1 (internal clock), SOUTi retains the last data for a 1/2 transfer clock period after completion of transfer and, thereafter, goes to a high-impedance state. However, if transmit data is written to the SiTRR register during this period, SOUTi immediately goes to a high-impedance state, with the data hold time thereby reduced.
4. When the SMi6 bit in the SiC register is set to 1 (internal clock), the transfer clock stops in the high state if the SMi4 bit is set to 0, or stops in the low state if the SMi4 bit is set to 1.

14.2.1 SI/Oi Operation Timing

Figure 14.37 shows the SI/Oi operation timing

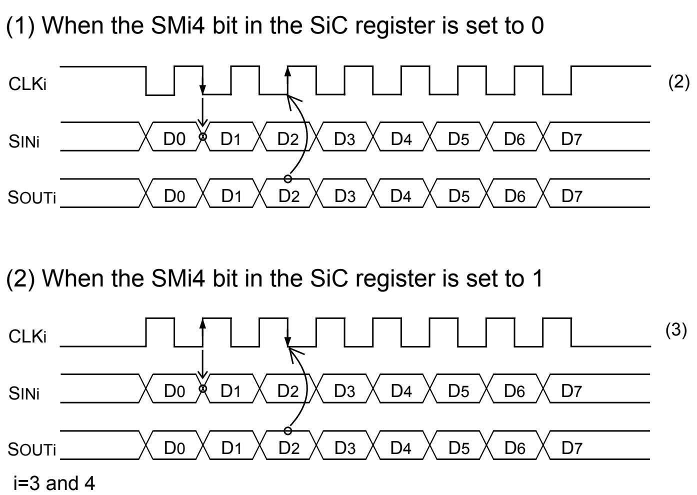


NOTES:
1. This diagram applies to the case where the SiC register bits are set as follows:
SMi2 = 0 (SOUTi output), SMi3 = 1 (SOUTi output, CLKi function), SMi4 = 0 (transmit data output at the falling edge and receive data input at the rising edge of the transfer clock), SMi5 = 0 (LSB first) and SMi6 = 1 (internal clock)
2. When the SMi6 bit is set to 0 (internal clock), the SOUTi pin is placed in the high-impedance state after the transfer is completed.
3. If the SMi6 bit is set to 0 (internal clock), the serial I/O starts sending or receiving data a maximum of 1.5 transfer clock cycles after writing to the SiTRR register.

Figure 14.37 SI/Oi Operation Timing

14.2.2 CLK Polarity Selection

The the SMi4 bit in the SiC register allows selection of the polarity of the transfer clock. **Figure 14.38** shows the polarity of the transfer clock.

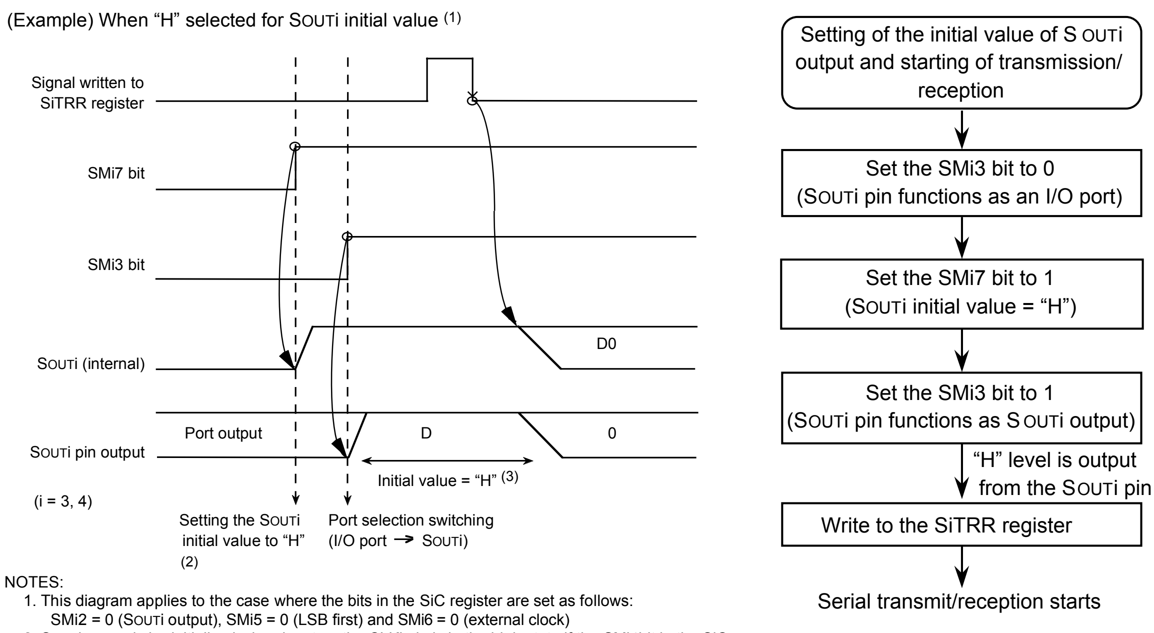


NOTES:
1. This diagram applies to the case where the SiC register bits are set as follows:
SMi5 = 0 (LSB first) and SMi6 = 1 (internal clock)
2. When the SMi6 bit is set to 1 (internal clock), a high level is output from the CLKi pin if not transferring data.
3 When the SMi6 bit is set to 1 (internal clock), a low level is output from the CLKi pin if not transferring data.

Figure 14.38 Polarity of Transfer Clock

14.2.3 Functions for Setting an SOUTi Initial Value

If the SMi6 bit in SiC register is set to 0 (external clock), the SOUTi pin output level can be fixed high or low when not transferring data. However, when transmitting data consecutively, the last bit (bit 0) value of the last transmitted data is retained between the sccessive data transmissions. **Figure 14.39** shows the timing chart for setting an SOUTi initial value and how to set it.



NOTES:
1. This diagram applies to the case where the bits in the SiC register are set as follows:
   SMi2 = 0 (SOUTi output), SMi5 = 0 (LSB first) and SMi6 = 0 (external clock)
2. SOUTi can only be initialized when input on the CLKi pin is in the high state if the SMi4bit in the SiC register is set to 0 (transmit data output at the falling edge of the transfer clock) or in the low state if the SMi4 bit is set to 1 (transmit data output at the rising edge of the transfer clock).
3. If the SMi6 bit is set to 1 (internal clock) or if the SMi2 bit is set to 1 (SOUTi output disabled), this output goes to the high-impedance state.

Figure 14.39 SOUTi Initial Value Setting

15. A/D Converter

Note

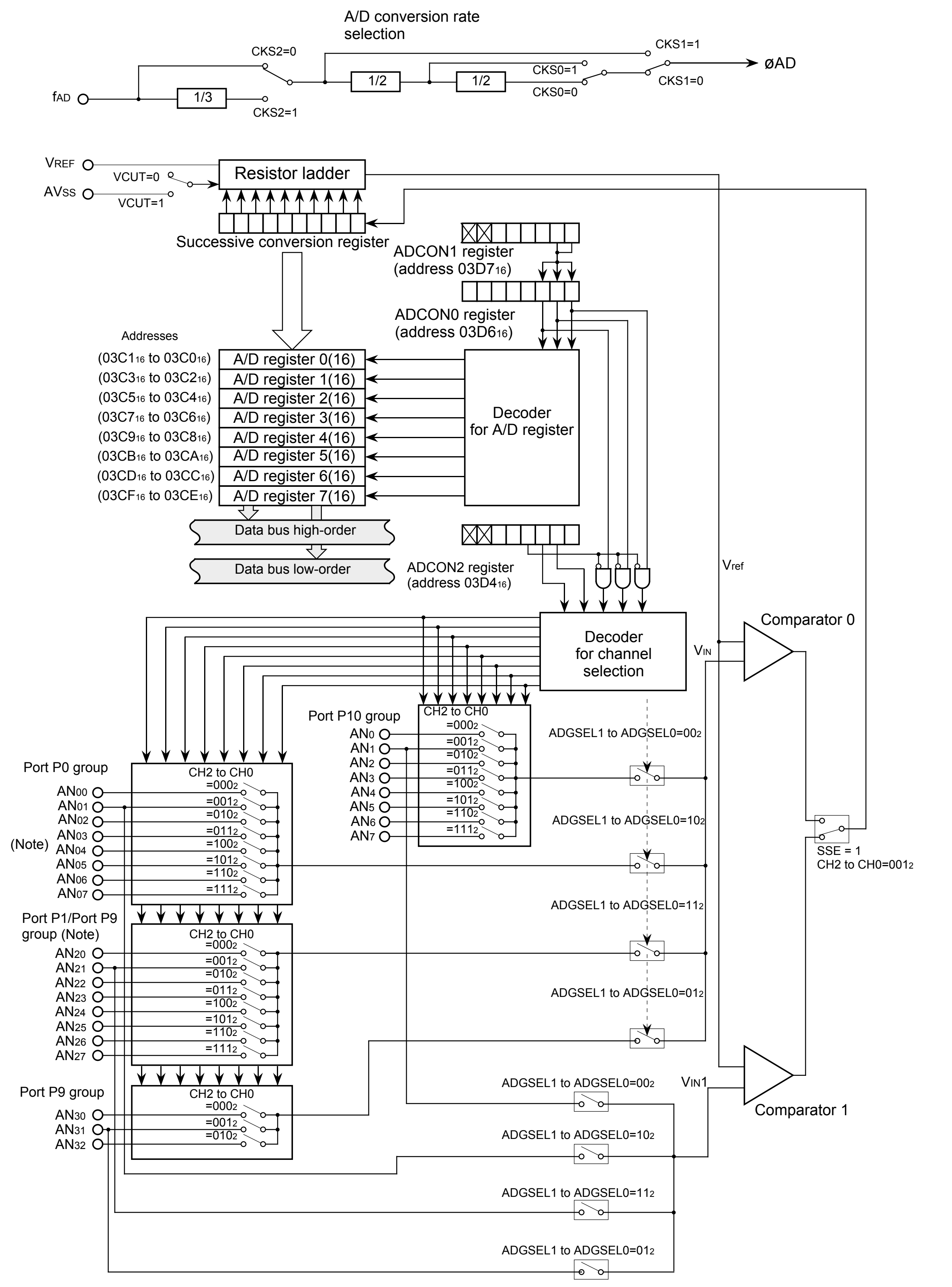
Ports P04 to P07(AN04 to AN07), P10 to P13(AN20 to AN23) and P95 to P97(AN25 to AN27) are not available in 64-pin package. Do not use port P04 to P07(AN04 to AN07), P10 to P13(AN20 to AN23) and P95 to P97(AN25 to AN27) as analog input pins in 64-pin package.

The MCU contains one A/D converter circuit based on 10-bit successive approximation method configured with a capacitive-coupling amplifier. The analog inputs share the pins with P100 to P107 (AN0 to AN7), P00 to P07 (AN00 to AN07), and P10 to P13, P93, P95 to P97 (AN20 to AN27), and P90 to P92 (AN30 to AN32). Similarly, $\overline{\text{ADTRG}}$ input shares the pin with P15. Therefore, when using these inputs, make sure the corresponding port direction bits are set to 0 (input mode).
When not using the A/D converter, set the VCUT bit to 0 (Vref unconnected), so that no current will flow from the Vref pin into the resistor ladder, helping to reduce the power consumption of the chip.
The A/D conversion result is stored in the ADi register bits for ANi, AN0i, AN2i (i = 0 to 7), and AN3i pins (i = 0 to 2). **Table 15.1** shows the A/D converter performance. **Figure 15.1** shows the A/D converter block diagram and **Figures 15.2** to **15.4** show the A/D converter associated with registers.

Table 15.1 A/D Converter Performance

Item	Performance
A/D Conversion Method	Successive approximation (capacitive coupling amplifier)
Analog Input Voltage (1)	0V to AVCC (VCC)
Operating Clock φAD (2)	fAD/divided-by-2 or fAD/divided-by-3 or fAD/divided-by-4 or fAD/divided-by-6 or fAD/divided-by-12 or fAD
Resolution	8-bit or 10-bit (selectable)
Integral Nonlinearity Error	When AVCC = Vref = 5V • With 8-bit resolution: ±2LSB • With 10-bit resolution: ±3LSB When AVCC = Vref = 3.3V • With 8-bit resolution: ±2LSB • With 10-bit resolution: ±5LSB
Operating Modes	One-shot mode, repeat mode, single sweep mode, repeat sweep mode 0, repeat sweep mode 1, simultaneous sample sweep mode and delayed trigger mode 0,1
Analog Input Pins	8 pins (AN0 to AN7) + 8 pins (AN00 to AN07) + 8 pins (AN20 to AN27) + 3 pins (AN30 to AN32) (80-pin package) 8 pins (AN0 to AN7) + 4 pins (AN00 to AN03) + 1 pin (AN24) + 3 pins (AN30 to AN32) (64-pin package)
Conversion Speed Per Pin	• Without sample and hold function 8-bit resolution: 49 φAD cycles, 10-bit resolution: 59 φAD cycles • With sample and hold function 8-bit resolution: 28 φAD cycles, 10-bit resolution: 33 φAD cycles

NOTES:
1. Not dependent on use of sample and hold function.
2. Set the φAD frequency to 10 MHz or less.
Without sample-and-hold function, set the φAD frequency to 250kHz or more.
With the sample and hold function, set the φAD frequency to 1MHz or more.



Note: AN04 to AN07, AN20 to AN23, and AN25 to AN27, is available for only 80-pin package.

Figure 15.1 A/D Converter Block Diagram

A/D Control Register 0 (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol ADCON0 | Address 03D6₁₆ | After Reset 00000XXX₂

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	Function varies with each operation mode	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 0 0: One-shot mode or Delayed trigger mode 0,1 0 1: Repeat mode 1 0: Single sweep mode or Simultaneous sample sweep mode 1 1: Repeat sweep mode 0 or Repeat sweep mode 1	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTE:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.

A/D Control Register 1 (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol ADCON1 | Address 03D7₁₆ | After Reset 00₁₆

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit	Function varies with each operation mode	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0 : Other than repeat sweep mode 1 1 : Repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0 : 8-bit mode 1 : 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect Bit (2)	0 : Vref not connected 1 : Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. If the VCUT bit is reset from 0 (VREF unconnected) to 1 (VREF connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2(1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol ADCON2 | Address 03D4₁₆ | After Reset 00₁₆

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	Function varies with each operation mode	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTS:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.2 ADCON0 to ADCON2 Registers

A/D Trigger Control Register (1, 2)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol: ADTRGCON | Address: $03D2_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
SSE	A/D Operation Mode Select Bit 2	0 : Other than simultaneous sample sweep mode or delayed trigger mode 0,1 1 : Simultaneous sample sweep mode or delayed trigger mode 0,1	RW
DTE	A/D Operation Mode Select Bit 3	0 : Other than delayed trigger mode 0,1 1 : Delayed trigger mode 0,1	RW
HPTRG0	AN0 Trigger Select Bit	Function varies with each operation mode	RW
HPTRG1	AN1 Trigger Select Bit	Function varies with each operation mode	RW
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. If the ADTRGCON register is rewritten during A/D conversion, the conversion result will be undefined.
2. Set 00_{16} in this register in one-shot mode, repeat mode, single sweep mode, repeat sweep mode 0 and repeat sweep mode 1.

Figure 15.3 ADTRGCON Register

Table 15.2 A/D Conversion Frequency Select

CKS2	CKS1	CKS0	ØAD
0	0	0	fAD divided by 4
0	0	1	fAD divided by 2
0	1	0	fAD
0	1	1	
1	0	0	fAD divided by 12
1	0	1	fAD divided by 6
1	1	0	fAD divided by 3
1	1	1	

NOTE:
1. ØAD frequency must be under 10 MHz. Combination of the CKS0 bit in the ADCON0 register, the CKS1 bit in the ADCON1 register, and the CKS2 bit in the ADCON2 register selects ØAD.

A/D Conversion Status Register 0 (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After reset
ADSTAT0	$03D3_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
ADERR0	AN1 trigger status flag	0: AN1 trigger did not occur during AN0 conversion 1: AN1 trigger occured during AN0 conversion	RW
ADERR1	Conversion termination flag	0: Conversion not terminated 1: Conversion terminated by Timer B0 underflow	RW
— (b2)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—
ADTCSF	Delayed trigger sweep status flag	0: Sweep not in progress 1: Sweep in progress	RO
ADSTT0	AN0 conversion status flag	0: AN0 conversion not in progress 1: AN0 conversion in progress	RO
ADSTT1	AN1 conversion status flag	0: AN1 conversion not in progress 1: AN1 conversion in progress	RO
ADSTRT0	AN0 conversion completion status flag	0: AN0 conversion not completed 1: AN0 conversion completed	RW
ADSTRT1	AN1 conversion completion status flag	0: AN1 conversion not completed 1: AN1 conversion completed	RW

NOTE:
1. ADSTAT0 register is valid only when the DTE bit in the ADTRGCON register is set to 1.

A/D Register i (i=0 to 7)

Symbol	Address	After Reset
AD0	$03C1_{16}$ to $03C0_{16}$	Undefined
AD1	$03C3_{16}$ to $03C2_{16}$	Undefined
AD2	$03C5_{16}$ to $03C4_{16}$	Undefined
AD3	$03C7_{16}$ to $03C6_{16}$	Undefined
AD4	$03C9_{16}$ to $03C8_{16}$	Undefined
AD5	$03CB_{16}$ to $03CA_{16}$	Undefined
AD6	$03CD_{16}$ to $03CC_{16}$	Undefined
AD7	$03CF_{16}$ to $03CE_{16}$	Undefined

(b15) b7 (b8) b0 b7 b0

Function		RW
When the BITS bit in the ADCON1 register is 1 (10-bit mode)	When the BITS bit in the ADCON1 register is 0 (8-bit mode)	RW
Eight low-order bits of A/D conversion result	A/D conversion result	RO
Two high-order bits of A/D conversion result	When read, its content is undefined	RO
Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

Figure 15.4 ADSTAT0 Register and AD0 to AD7 Registers

Timer B2 special mode register [1]

b7	b6	b5	b4	b3	b2	b1	b0
X	0	0					

Symbol	Address	After Reset
TB2SC	039E16	X00000002

Bit Symbol	Bit Name	Function	RW
PWCON	Timer B2 reload timing switch bit [2]	0: Timer B2 underflow 1: Timer A output at odd-numbered	RW
IVPCR1	Three-phase output port $\overline{SD}$ control bit 1 [3, 4, 7]	0: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) disabled 1: Three-phase output forcible cutoff by $\overline{SD}$ pin input (high impedance) enabled	RW
TB0EN	Timer B0 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode [5]	RW
TB1EN	Timer B1 operation mode select bit	0: Other than A/D trigger mode 1: A/D trigger mode [5]	RW
TB2SEL	Trigger select bit [6]	0: TB2 interrupt 1: Underflow of TB2 interrupt generation frequency setting counter [ICTB2]	RW
— (b6-b5)	Reserved bits	Set to 0	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. Write to this register after setting the PRC1 bit in the PRCR register to 1 (write enabled).
2. If the INV11 bit is 0 (three-phase mode 0) or the INV06 bit is 1 (triangular wave modulation mode), set this bit to 0 (timer B2 underflow).
3. When setting the IVPCR1 bit to 1 (three-phase output forcible cutoff by $\overline{SD}$ pin input enabled), Set the PD85 bit to 0 (= input mode).
4. Related pins are U(P80), $\overline{U}$(P81), V(P72), $\overline{V}$(P73), W(P74), $\overline{W}$(P75). When a high-level ("H") signal is applied to the $\overline{SD}$ pin and set the IVPCR1 bit to 0 after forcible cutoff, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are exit from the high-impedance state. If a low-level ("L") signal is applied to the $\overline{SD}$ pin, three-phase motor control timer output will be disabled (INV03=0). At this time, when the IVPCR1 bit is 0, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ become programmable I/O ports. When the IVPCR1 bit is set to 1, pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are placed in a high-impedance state regardless of which function of those pins is used.
5. When this bit is used in delayed trigger mode 0, set bits TB0EN and TB1EN to 1 (A/D trigger mode).
6. When setting the TB2SEL bit to 1 (underflow of TB2 interrupt generation frequency setting counter[ICTB2]), set the INV02 bit to 1 (three-phase motor control timer function).

Figure 15.5 TB2SC Register

15.1 Operating Modes

15.1.1 One-Shot Mode

In one-shot mode, analog voltage applied to a selected pin is once converted to a digital code. **Table 15.3** shows the one-shot mode specifications. **Figure 15.6** shows the operation example in one-shot mode. **Figure 15.7** shows registers ADCON0 to ADCON2 in one-shot mode.

Table 15.3 One-shot Mode Specifications

Item	Specification
Function	Bits CH2 to CH0 in the ADCON0 register and registers ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltage applied to a selected pin is once converted to a digital code
A/D Conversion Start Condition	• When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) • When the TRG bit in the ADCON0 register is 1 (hardware trigger) The $\overline{\text{ADTRG}}$ pin input changes state from “H” to “L” after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	• A/D conversion completed (If a software trigger is selected, the ADST bit is set to 0 (A/D conversion halted)). • Set the ADST bit to 0
Interrupt Request Generation Timing	A/D conversion completed
Analog Input Pin	Select one pin from AN_0 to AN_7, $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, $AN3_0$ to $AN3_2$
Readout of A/D Conversion Result	Readout one of registers AD0 to AD7 that corresponds to the selected pin

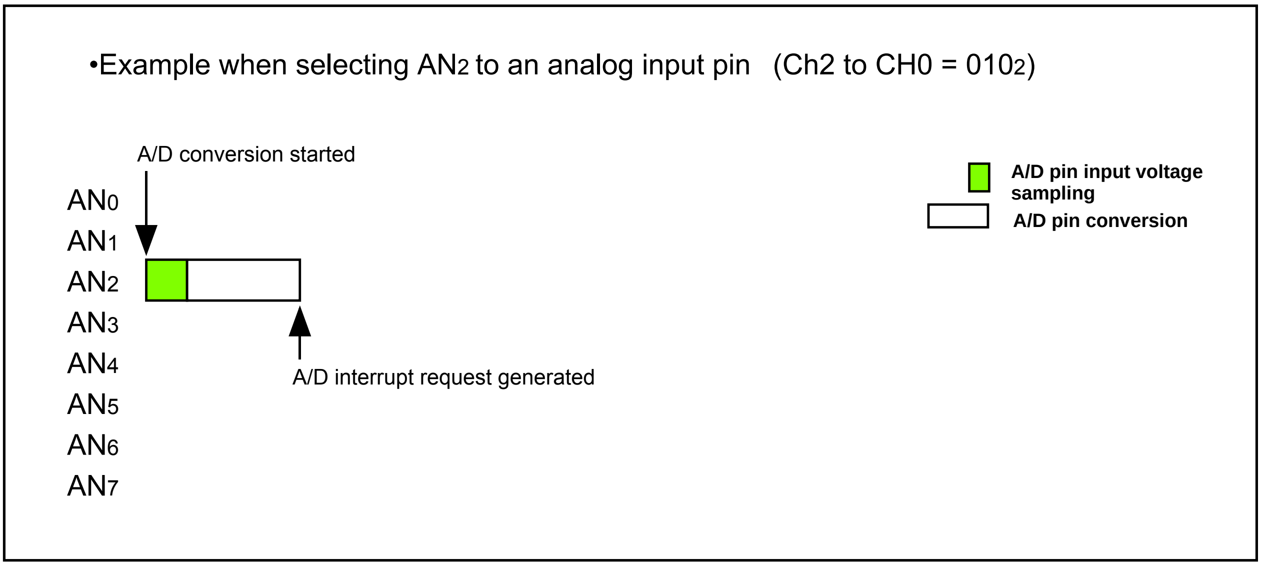


Figure 15.6 Operation Example in One-Shot Mode

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			0	0			

Symbol ADCON0 Address $03D6_{16}$ After Reset $00000XXX_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit (2, 3)	b2 b1 b0 0 0 0: Select AN_0 0 0 1: Select AN_1 0 1 0: Select AN_2 0 1 1: Select AN_3 1 0 0: Select AN_4 1 0 1: Select AN_5 1 1 0: Select AN_6 1 1 1: Select AN_7	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0 (3)	b4 b3 0 0: One-shot mode or delayed trigger mode 0,1	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger ($\overline{AD_{TRG}}$ trigger)	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTES:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.
2. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. After rewriting bits MD1 and MD0, set bits CH2 to CH0 over again using an another instruction.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol ADCON1 Address $03D7_{16}$ After Reset 00_{16}

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D Sweep Pin Select Bit	Invalid in one-shot mode	RW
SCAN1			RW
MD2	A/D Operation Mode Select Bit 1	0 : Any mode other than repeat sweep mode 1	RW
BITS	8/10-Bit Mode Select Bit	0 : 8-bit mode 1 : 10-bit mode	RW
CKS1	Frequency Select Bit 1	Refer to **Table 15.2**	RW
VCUT	Vref Connect Bit (2)	1 : Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the contents are 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			

Symbol ADCON2 Address $03D4_{16}$ After Reset 00_{16}

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit 1	Set to 0 in one-shot mode	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.7 ADCON0 to ADCON2 Registers in One-Shot Mode

15.1.2 Repeat mode

In repeat mode, analog voltage applied to a selected pin is repeatedly converted to a digital code. **Table 15.4** shows the repeat mode specifications. **Figure 15.8** shows the operation example in repeat mode. **Figure 15.9** shows the ADCON0 to ADCON2 registers in repeat mode.

Table 15.4 Repeat Mode Specifications

Item	Specification
Function	Bits CH2 to CH0 in the ADCON0 register and the ADGSEL1 to ADGSEL0 bits in the ADCON2 register select pins. Analog voltage applied to a selected pin is repeatedly converted to a digital code
A/D Conversion Start Condition	• When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) • When the TRG bit in the ADCON0 register is 1 (hardware trigger) The $\overline{ADTRG}$ pin input changes state from “H” to “L” after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	Set the ADST bit to 0 (A/D conversion halted)
Interrupt Request Generation Timing	None generated
Analog Input Pin	Select one pin from AN_0 to AN_7, $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$
Readout of A/D Conversion Result	Readout one of the AD0 to AD7 registers that corresponds to the selected pin

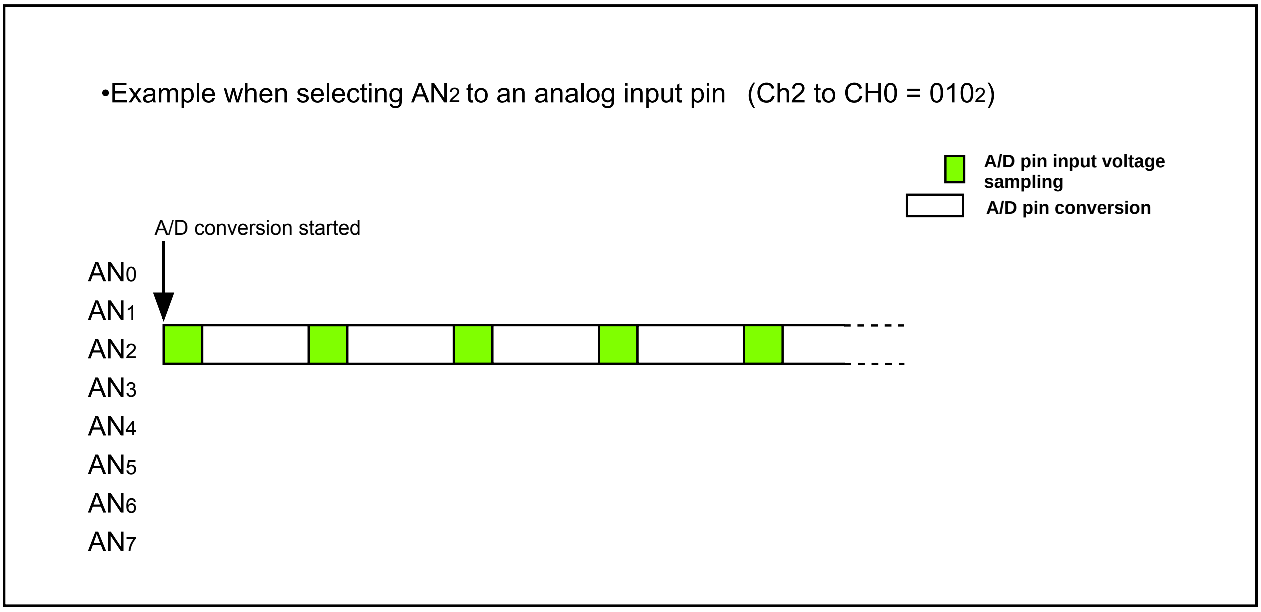


Figure 15.8 Operation Example in Repeat Mode

A/D Control Register 0 [1]

b7	b6	b5	b4	b3	b2	b1	b0
			0	1			

Symbol: ADCON0 — Address: $03D6_{16}$ — After Reset: $00000XXX_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit[2, 3]	b2 b1 b0 0 0 0: Select AN_0 0 0 1: Select AN_1 0 1 0: Select AN_2 0 1 1: Select AN_3 1 0 0: Select AN_4 1 0 1: Select AN_5 1 1 0: Select AN_6 1 1 1: Select AN_7	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0 [3]	b4 b3 0 1: Repeat mode	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger ($\overline{\text{ADTRG}}$ trigger)	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTES:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.
2. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. After rewriting bits MD1 and MD0, set bits CH2 to CH0 over again using an another instruction.

A/D Control Register 1 [1]

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol: ADCON1 — Address: $03D7_{16}$ — After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit	Invalid in repeat mode	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect bit [2]	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2[1]

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			

Symbol: ADCON2 — Address: $03D4_{16}$ — After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	Set to 0 in one-shot mode	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.9 ADCON0 to ADCON2 Registers in Repeat Mode

15.1.3 Single Sweep Mode

In single sweep mode, analog voltages applied to the selected pins are converted one-by-one to a digital code. **Table 15.5** shows the single sweep mode specifications. **Figure 15.10** shows the operation example in single sweep mode. **Figure 15.11** shows the ADCON0 to ADCON2 registers in single sweep mode.

Table 15.5 Single Sweep Mode Specifications

Item	Specification
Function	Bits SCAN1 to SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltage applied to the selected pins is converted one-by-one to a digital code
A/D Conversion Start Condition	• When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) • When the TRG bit in the ADCON0 register is 1 (hardware trigger) The $\overline{\text{ADTRG}}$ pin input changes state from “H” to “L” after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	• A/D conversion completed(When selecting a software trigger, the ADST bit is set to 0 (A/D conversion halted)). • Set the ADST bit to 0
Interrupt Request Generation Timing	A/D conversion completed
Analog Input Pin	Select from AN_0 to AN_1 (2 pins), AN_0 to AN_3 (4 pins), AN_0 to AN_5 (6 pins), AN_0 to AN_7 (8 pins) (1)
Readout of A/D Conversion Result	Readout one of registers AD0 to AD7 that corresponds to the selected pin

NOTE:
1. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

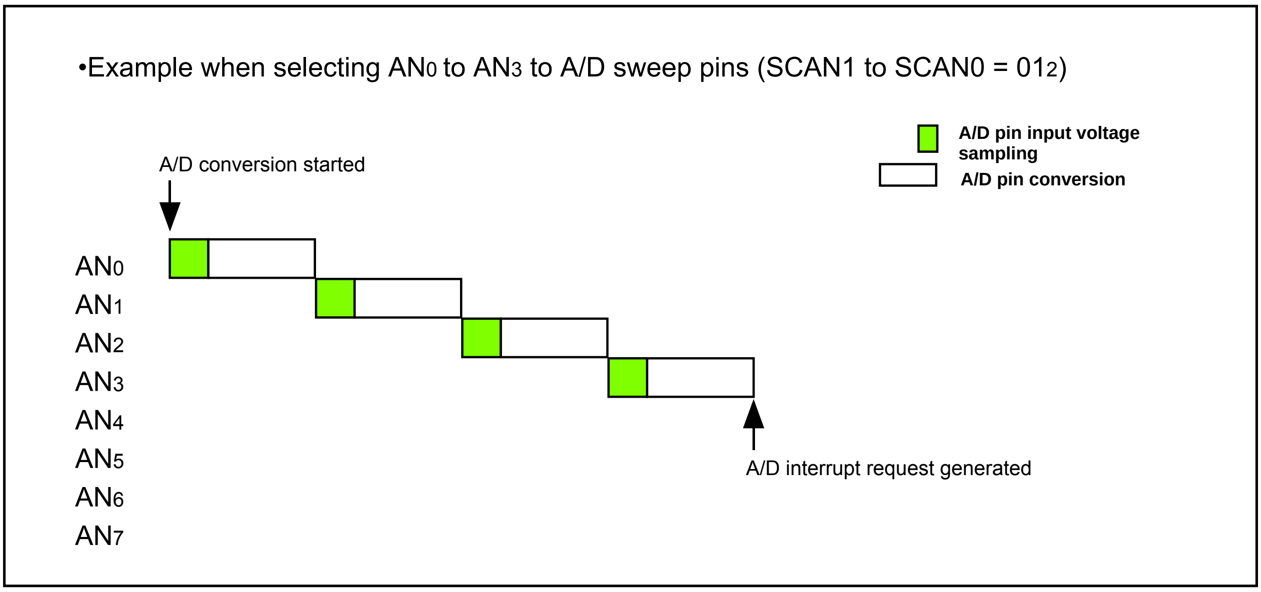


Figure 15.10 Operation Example in Single Sweep Mode

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			1	0			

Symbol: ADCON0 | Address: 03D6₁₆ | After Reset: 00000XXX₂

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	Invalid in single sweep mode	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 1 0: Single sweep mode or Simultaneous sample sweep mode	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger (ADTRG trigger)	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTE:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol: ADCON1 | Address: 03D7₁₆ | After Reset: 00₁₆

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit (2)	When single sweep mode is selected, b1 b0 0 0: AN0 to AN1 (2 pins) 0 1: AN0 to AN3 (4 pins) 1 0: AN0 to AN5 (6 pins) 1 1: AN0 to AN7 (8 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect Bit (3)	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. AN00 to AN07, AN20 to AN27, and AN30 to AN32 can be used in the same way as AN0 to AN7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2(1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			

Symbol: ADCON2 | Address: 03D4₁₆ | After Reset: 00₁₆

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	Set to 0 in single sweep mode	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.11 ADCON0 to ADCON2 Registers in Single Sweep Mode

15.1.4 Repeat Sweep Mode 0

In repeat sweep mode 0, analog voltages applied to the selected pins are repeatedly converted to a digital code. **Table 15.6** shows the repeat sweep mode 0 specifications. **Figure 15.12** shows the operation example in repeat sweep mode 0. **Figure 15.13** shows the ADCON0 to ADCON2 registers in repeat sweep mode 0.

Table 15.6 Repeat Sweep Mode 0 Specifications

Item	Specification
Function	Bits SCAN1 and SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltage applied to the selected pins is repeatedly converted to a digital code
A/D Conversion Start Condition	• When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) • When the TRG bit in the ADCON0 register is 1 (Hardware trigger) The $\overline{ADTRG}$ pin input changes state from "H" to "L" after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	Set the ADST bit to 0 (A/D conversion halted)
Interrupt Request Generation Timing	None generated
Analog Input Pin	Select from AN_0 to AN_1 (2 pins), AN_0 to AN_3 (4 pins), AN_0 to AN_5 (6 pins), AN_0 to AN_7 (8 pins) (1)
Readout of A/D Conversion Result	Readout one of registers AD0 to AD7 that corresponds to the selected pin

NOTES:

1. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

•Example when selecting AN_0 to AN_3 to A/D sweep pins (SCAN1 to SCAN0 = 01_2)

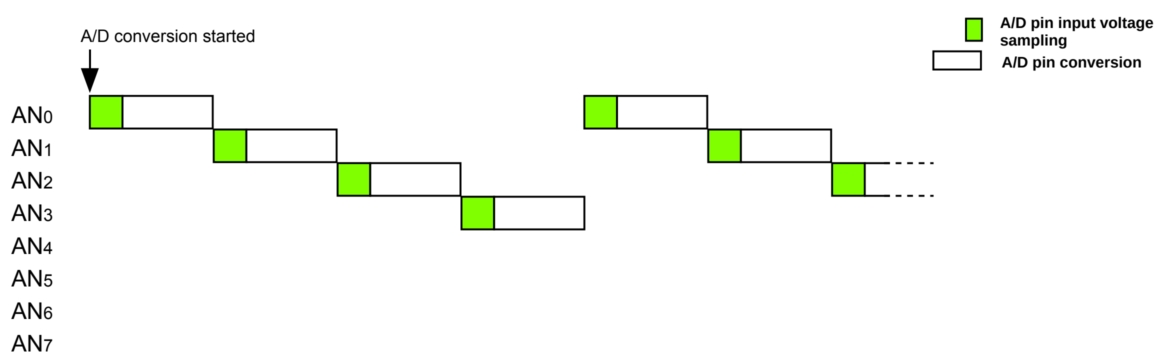


Figure 15.12 Operation Example in Repeat Sweep Mode 0

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			1	1			

Symbol: ADCON0 Address: 03D6$_{16}$ After Reset: 00000XXX$_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	Invalid in repeat sweep mode 0	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 1 1: Repeat sweep mode 0 or repeat sweep mode 1	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger ($\overline{ADTRG}$ trigger)	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTE:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol: ADCON1 Address: 03D7$_{16}$ After Reset: 00$_{16}$

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit (2)	When repeat sweep mode 0 is selected, b1 b0 0 0: AN0 to AN1 (2 pins) 0 1: AN0 to AN3 (4 pins) 1 0: AN0 to AN5 (6 pins) 1 1: AN0 to AN7 (8 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect Bit (3)	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. AN00 to AN07, AN20 to AN27, and AN30 to AN32 can be used in the same way as AN0 to AN7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			

Symbol: ADCON2 Address: 03D4$_{16}$ After Reset: 00$_{16}$

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	Set to 0 in repeat sweep mode 0	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.13 ADCON0 to ADCON2 Registers in Repeat Sweep Mode 0

15.1.5 Repeat Sweep Mode 1

In repeat sweep mode 1, analog voltage is applied to the all selected pins are converted to a digital code, with mainly used in the selected pins. **Table 15.7** shows the repeat sweep mode 1 specifications. **Figure 15.14** shows the operation example in repeat sweep mode 1. **Figure 15.15** shows registers ADCON0 to ADCON2 in repeat sweep mode 1.

Table 15.7 Repeat Sweep Mode 1 Specifications

Item	Specification
Function	Bits SCAN1 and SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register mainly select pins. Analog voltage applied to the all selected pins is repeatedly converted to a digital code Example : When selecting AN_0 Analog voltage is converted to a digital code in the following order $AN_0 \rightarrow AN_1 \rightarrow AN_0 \rightarrow AN_2 \rightarrow AN_0 \rightarrow AN_3$, and so on.
A/D Conversion Start Condition	• When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) • When the TRG bit in the ADCON0 register is 1 (hardware trigger) The $\overline{AD_{TRG}}$ pin input changes state from “H” to “L” after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	Set the ADST bit to 0 (A/D conversion halted)
Interrupt Request Generation Timing	None generated
Analog Input Pins Mainly Used in A/D Conversions	Select from AN_0 (1 pins), AN_0 to AN_1 (2 pins), AN_0 to AN_2 (3 pins), AN_0 to AN_3 (4 pins) (1)
Readout of A/D Conversion Result	Readout one of registers AD0 to AD7 that corresponds to the selected pin

NOTES:

1. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

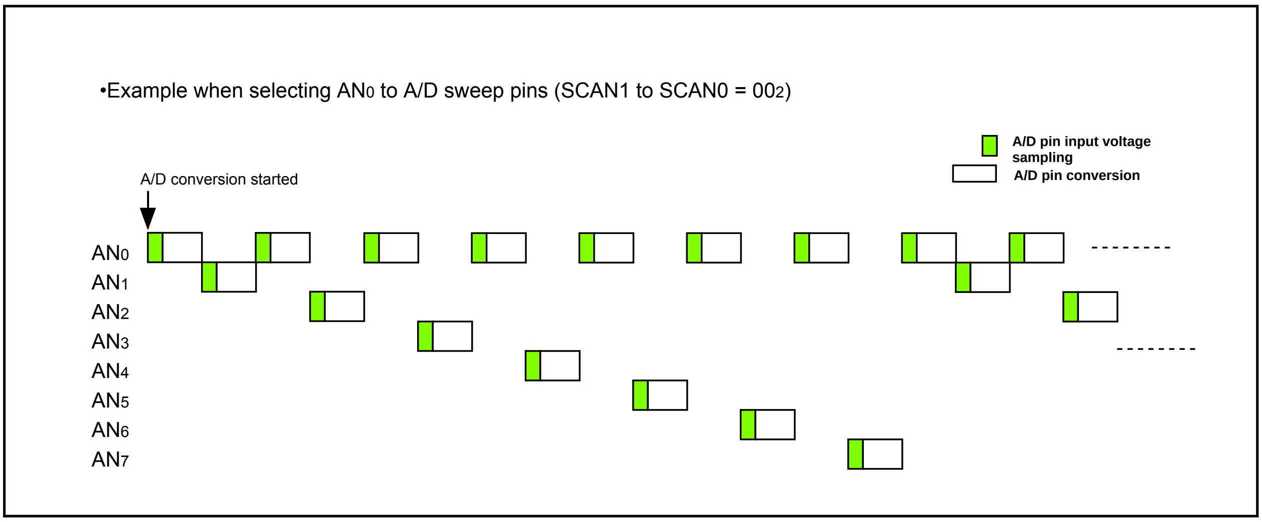


Figure 15.14 Operation Example in Repeat Sweep Mode 1

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			1	1			

Symbol	Address	After Reset
ADCON0	$03D6_{16}$	$00000XXX_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	Invalid in repeat sweep mode 1	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 1 1: Repeat sweep mode 0 or repeat sweep mode 1	RW
MD1			RW
TRG	Trigger select bit	0: Software trigger 1: Hardware trigger ($\overline{ADTRG}$ trigger)	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTE:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol	Address	After Reset
ADCON1	$03D7_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit (2)	When repeat sweep mode 0 is selected, b1 b0 0 0: AN_0 (1 pin) 0 1: AN_0 to AN_1 (2 pins) 1 0: AN_0 to AN_2 (3 pins) 1 1: AN_0 to AN_3 (4 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	1: Repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect Bit (3)	1: Vref connected	RW
$\overline{}$ (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2(1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			

Symbol	Address	After Reset
ADCON2	$03D4_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	0: Without sample and hold 1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
$\overline{\text{(b3)}}$	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	Set to 0 in repeat sweep mode 1	RW
$\overline{}$ (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.15 ADCON0 to ADCON2 Registers in Repeat Sweep Mode 1

15.1.6 Simultaneous Sample Sweep Mode

In simultaneous sample sweep mode, analog voltages applied to the selected pins are converted one-by-one to a digital code. The input voltages of AN0 and AN1 are sampled simultaneously using two circuits of sample and hold circuit. **Table 15.8** shows the simultaneous sample sweep mode specifications. **Figure 15.16** shows the operation example in simultaneous sample sweep mode. **Figure 15.17** shows registers ADCON0 to ADCON2 and **Figure 15.18** shows ADTRGCON registers in simultaneous sample sweep mode. **Table 15.9** shows the trigger select bit setting in simultaneous sample sweep mode. In simultaneous sample sweep mode, Timer B0 underflow can be selected as a trigger by combining software trigger, $\overline{ADTRG}$ trigger, Timer B2 underflow, Timer B2 interrupt generation frequency setting counter underflow or A/D trigger mode of Timer B.

Table 15.8 Simultaneous Sample Sweep Mode Specifications

Item	Specification
Function	Bits SCAN1 and SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltage applied to the selected pins is converted one-by-one to a digital code. At this time, the input voltage of AN_0 and AN_1 are sampled simultaneously.
A/D Conversion Start Condition	When the TRG bit in the ADCON0 register is 0 (software trigger) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) When the TRG bit in the ADCON0 register is 1 (hardware trigger) The trigger is selected by bits TRG1 and HPTRG0 (See **Table 15.9**) The $\overline{ADTRG}$ pin input changes state from “H” to “L” after setting the ADST bit to 1 (A/D conversion started) Timer B0, B2 or Timer B2 interrupt generation frequency setting counter underflow after setting the ADST bit to 1 (A/D conversion started)
A/D Conversion Stop Condition	A/D conversion completed (If selecting software trigger, the ADST bit is automatically set to 0). Set the ADST bit to 0 (A/D conversion halted)
Interrupt Generation Timing	A/D conversion completed
Analog Input Pin	Select from AN_0 to AN_1 (2 pins), AN_0 to AN_3 (4 pins), AN_0 to AN_5 (6 pins), or AN_0 to AN_7 (8 pins) (1)
Readout of A/D conversion result	Readout one of registers AN0 to AN7 that corresponds to the selected pin

NOTE:

1. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

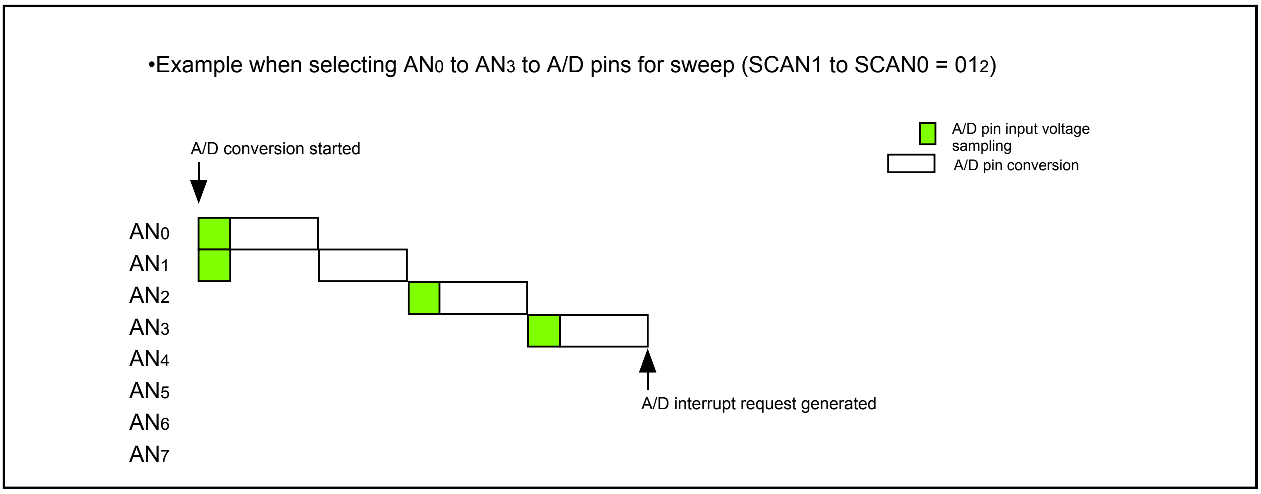


Figure 15.16 Operation Example in Simultaneous Sample Sweep Mode

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
			1	1			

Symbol: ADCON0 Address: $03D6_{16}$ After Reset: $00000XXX_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	Invalid in repeat sweep mode 0	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 1 0: Single sweep mode or simultaneous sample sweep mode	RW
MD1			RW
TRG	Trigger select bit	See **Table 15.9**	RW
ADST	A/D conversion start flag	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	See **Table 15.2**	RW

NOTE:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.

A/D Control Register 1(1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol: ADCON1 Address: $03D7_{16}$ After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit (2)	When simultaneous sample sweep mode is selected, b1 b0 0 0: AN0 to AN1 (2 pins) 0 1: AN0 to AN3 (4 pins) 1 0: AN0 to AN5 (6 pins) 1 1: AN0 to AN7 (8 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	See **Table 15.2**	RW
VCUT	Vref connect Bit (3)	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. AN00 to AN07, AN20 to AN27, and AN30 to AN32 can be used in the same way as AN0 to AN7. Use bits ADGSEL1 and ADGSEL 0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2(1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X			0			1

Symbol: ADCON2 Address: $03D4_{16}$ After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit	Set to 1 in simultaneous sample sweep mode	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	See **Table 15.2**	RW
TRG1	Trigger select bit	See **Table 15.9**	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.17 ADCON0 to ADCON2 Registers in Simultaneous Sample Sweep Mode

A/D Trigger Control Register (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	X	X	0		1	1

Symbol: ADTRGCON Address: 03D2$_{16}$ After Reset: 00$_{16}$

Bit Symbol	Bit Name	Function	RW
SSE	A/D operation mode select bit 2	1: Simultaneous sample sweep mode or delayed trigger mode 0, 1	RW
DTE	A/D operation mode select bit 3	0: Other than delayed trigger mode 0, 1	RW
HPTRG0	AN$_0$ trigger select bit	See **Table 15.9**	RW
HPTRG1	AN$_1$ trigger select bit	Set to 0 in simultaneous sample sweep mode	RW
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If ADTRGCON is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.18 ADTRGCON Register in Simultaneous Sample Sweep Mode

Table 15.9 Trigger Select Bit Setting in Simultaneous Sample Sweep Mode

TRG	TRG1	HPTRG0	TRIGGER
0	-	-	Software trigger
1	-	1	Timer B0 underflow (1)
1	0	0	$\overline{\text{ADTRG}}$
1	1	0	Timer B2 or Timer B2 interrupt generation frequency setting counter underflow (2)

NOTES:
1. A count can be started for Timer B2, Timer B2 interrupt generation frequency setting counter underflow or the INT5 pin falling edge as count start conditions of Timer B0.
2. Select Timer B2 or Timer B2 interrupt generation frequency setting counter using the TB2SEL bit in the TB2SC register.

15.1.7 Delayed Trigger Mode 0

In delayed trigger mode 0, analog voltages applied to the selected pins are converted one-by-one to a digital code. The delayed trigger mode 0 used in combination with A/D trigger mode of Timer B. The Timer B0 underflow starts a single sweep conversion. After completing the AN_0 pin conversion, the AN_1 pin is not sampled and converted until the Timer B1 underflow is generated. When the Timer B1 underflow is generated, the single sweep conversion is restarted with the AN_1 pin. **Table 15.10** shows the delayed trigger mode 0 specifications. **Figure 15.19** shows the operation example in delayed trigger mode 0. **Figures 15.20** and **15.21** show each flag operation in the ADSTAT0 register that corresponds to the operation example. **Figure 15.22** shows registers ADCON0 to ADCON2 in delayed trigger mode 0. **Figure 15.23** shows the ADTRGCON register in delayed trigger mode 0 and **Table 15.11** shows the trigger select bit setting in delayed trigger mode 0.

Table 15.10 Delayed Trigger Mode 0 Specifications

Item	Specification
Function	Bits SCAN1 and SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltage applied to the input voltage of the selected pins are converted one-by-one to the digital code. At this time, timer B0 underflow generation starts AN_0 pin conversion. Timer B1 underflow generation starts conversion after the AN_1 pin. (1)
A/D Conversion Start	AN_0 pin conversion start condition •When Timer B0 underflow is generated if Timer B0 underflow is generated again before Timer B1 underflow is generated , the conversion is not affected •When Timer B0 underflow is generated during A/D conversion of pins after the AN_1 pin, conversion is halted and the sweep is restarted from the AN_0 pin again AN_1 pin conversion start condition •When Timer B1 underflow is generated during A/D conversion of the AN_0 pin, the input voltage of the AN_1 pin is sampled. The AN_1 conversion and the rest of the sweep start when AN_0 conversion is completed.
A/D Conversion Stop Condition	•When single sweep conversion from the AN_0 pin is completed •Set the ADST bit to 0 (A/D conversion halted)(2)
Interrupt request generation timing	A/D conversion completed
Analog input pin	Select from AN_0 to AN_1 (2 pins), AN_0 to AN_3 (4 pins), AN_0 to AN_5 (6 pins) and AN_0 to AN_7 (8 pins)(3)
Readout of A/D conversion result	Readout one of registers AN0 to AN7 that corresponds to the selected pins

NOTES:
1. Set the larger value than the value of the timer B0 register to the timer B1 register. The count source for timer B0 and timer B1 must be the same.
2. Do not write 1 (A/D conversion started) to the ADST bit in delayed trigger mode 0. When write 1, unexpected interrupts may be generated.
3. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

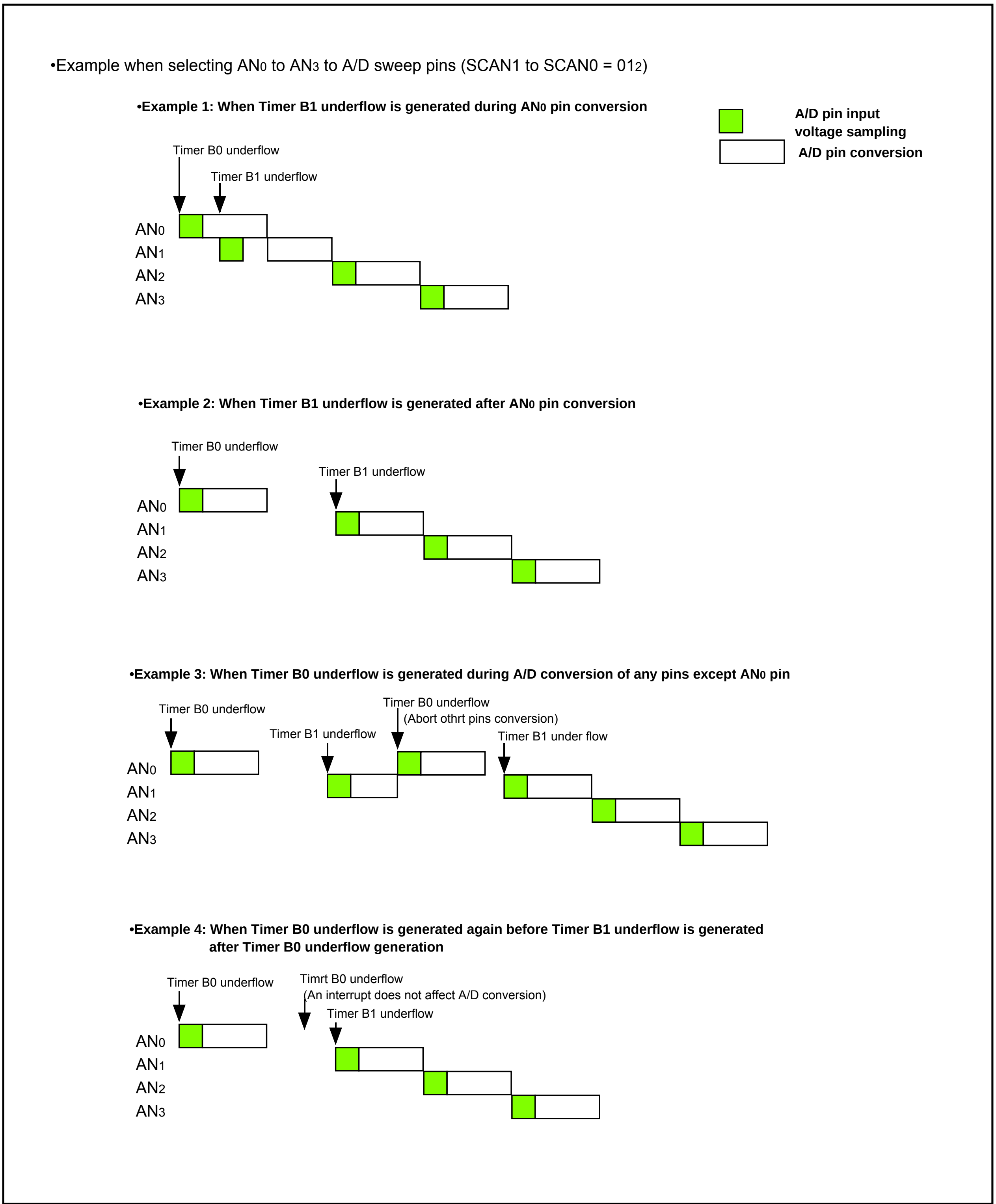


Figure 15.19 Operation Example in Delayed Trigger Mode 0

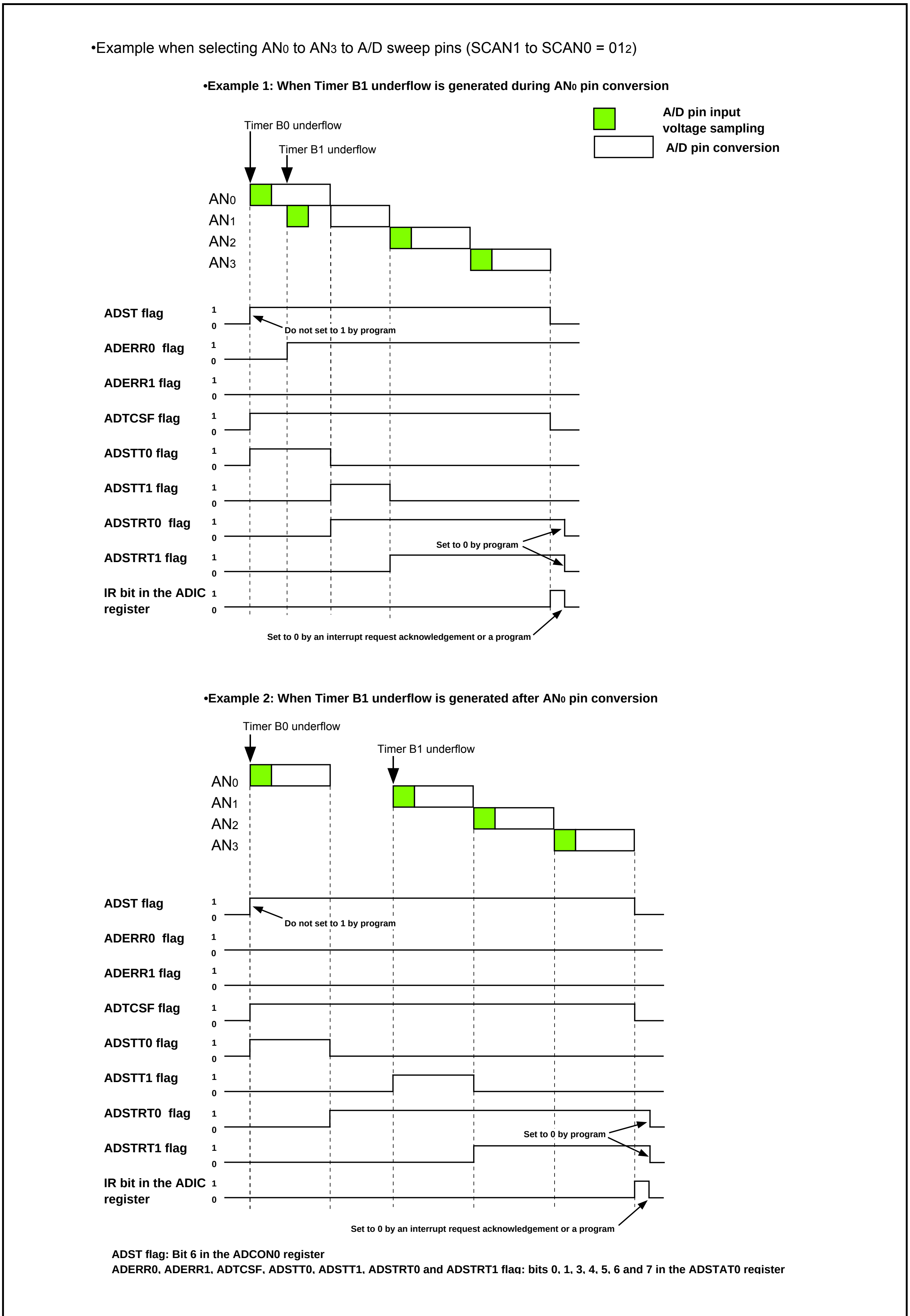
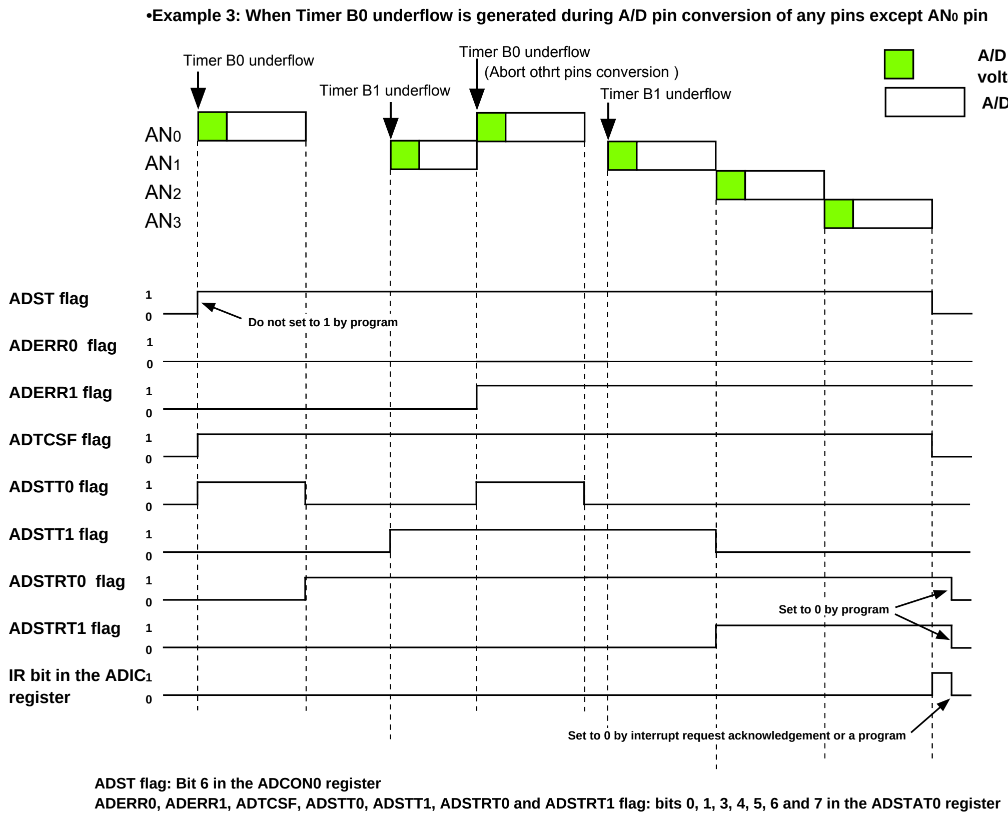


Figure 15.20 Each Flag Operation in ADSTAT0 Register Associated with the Operation Example in Delayed Trigger Mode 0 (1)



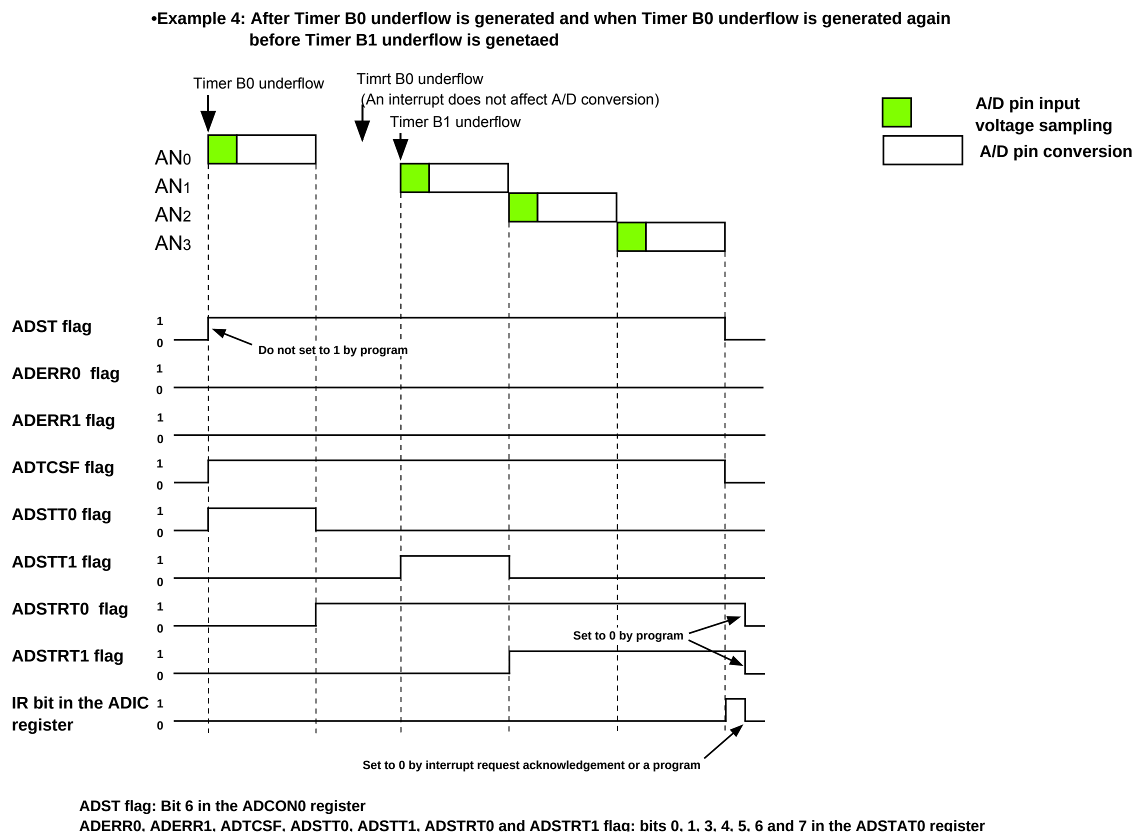


Figure 15.21 Each Flag Operation in ADSTAT0 Register Associated with the Operation Example in Delayed Trigger Mode 0 (2)

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
		0	0	0	1	1	1

Symbol ADCON0 — Address 03D6$_{16}$ — After Reset 00000XXX$_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	b2 b1 b0 1 1 1: Set to 111b in delayed trigger mode 0	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 0 0: One-shot mode or delayed trigger mode 0,1	RW
MD1			RW
TRG	Trigger select bit	Refer to **Table 15.11**	RW
ADST	A/D conversion start flag (2)	0: A/D conversion disabled 1: A/D conversion started	RW
CKS0	Frequency select bit 0	Refer to **Table 15.2**	RW

NOTES:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.
2. Do not write 1 in delayed trigger mode 0. When write, set to 0.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol ADCON1 — Address 03D7$_{16}$ — After Reset 00$_{16}$

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit (2)	When selecting delayed trigger sweep mode 0 b1 b0 0 0: AN$_0$ to AN$_1$ (2 pins) 0 1: AN$_0$ to AN$_3$ (4 pins) 1 0: AN$_0$ to AN$_5$ (6 pins) 1 1: AN$_0$ to AN$_7$ (8 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Any mode other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	Refer to **Table 15.2**	RW
VCUT	Vref connect bit (3)	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. AN0$_0$ to AN0$_7$, AN2$_0$ to AN2$_7$, and AN3$_0$ to AN3$_2$ can be used in the same way as AN$_0$ to AN$_7$. Use bits ADGSEL1 and ADGSEL0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	0		0			1

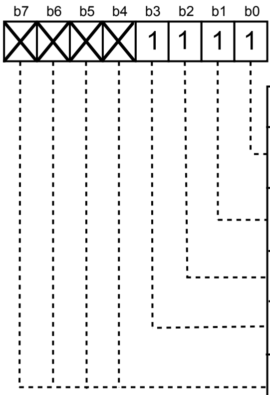
Symbol ADCON2 — Address 03D4$_{16}$ — After Reset 00$_{16}$

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit (2)	1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	Refer to **Table 15.2**	RW
TRG1	Trigger select bit 1	Refer to **Table 15.11**	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, its content is 0		—

NOTES:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.
2. Set to 1 in delayed trigger mode 0.

Figure 15.22 ADCON0 to ADCON2 Registers in Delayed Trigger Mode 0

A/D Trigger Control Register (1)



Symbol	Address	After Reset
ADTRGCON	$03D2_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
SSE	A/D operation mode select bit 2	Simultaneous sample sweep mode or delayed trigger mode 0, 1	RW
DTE	A/D operation mode select bit 3	Delayed trigger mode 0, 1	RW
HPTRG0	AN_0 trigger select bit	See **Table 15.11**	RW
HPTRG1	AN_1 trigger select bit	See **Table 15.11**	RW
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If ADTRGCON is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.23 ADTRGCON Register in Delayed Trigger Mode 0

Table 15.11 Trigger Select Bit Setting in Delayed Trigger Mode 0

TRG	TRG1	HPTRG0	HPTRG1	Trigger
0	0	1	1	Timer B0, B1 underflow

15.1.8 Delayed Trigger Mode 1

In delayed trigger mode 1, analog voltages applied to the selected pins are converted one-by-one to a digital code. When the input of the $\overline{\text{ADTRG}}$ pin (falling edge) changes state from “H” to “L”, a single sweep conversion is started. After completing the AN_0 pin conversion, the AN_1 pin is not sampled and converted until the second $\overline{\text{ADTRG}}$ pin falling edge is generated. When the second $\overline{\text{ADTRG}}$ falling edge is generated, the single sweep conversion of the pins after the AN_1 pin is restarted. **Table 15.12** shows the delayed trigger mode 1 specifications. **Figure 15.24** shows the operation example of delayed trigger mode 1. **Figure 15.25** and **15.26** show each flag operation in the ADSTAT0 register that corresponds to the operation example. **Figure 15.27** shows registers ADCON0 to ADCON2 in delayed trigger mode 1. **Figure 15.28** shows the ADTRGCON register in delayed trigger mode 1. **Table 15.13** shows the trigger select bit setting in delayed trigger mode 1.

Table 15.12 Delayed Trigger Mode 1 Specifications

Item	Specification
Function	Bits SCAN1 and SCAN0 in the ADCON1 register and bits ADGSEL1 and ADGSEL0 in the ADCON2 register select pins. Analog voltages applied to the selected pins are converted one-by-one to a digital code. At this time, the $\overline{\text{ADTRG}}$ pin falling edge starts AN_0 pin conversion and the second $\overline{\text{ADTRG}}$ pin falling edge starts conversion of the pins after AN_1 pin
A/D Conversion Start Condition	AN_0 pin conversion start condition The $\overline{\text{ADTRG}}$ pin input changes state from “H” to “L” (falling edge) (1) AN_1 pin conversion start condition (2) The $\overline{\text{ADTRG}}$ pin input changes state from “H” to “L” (falling edge) •When the second $\overline{\text{ADTRG}}$ pin falling edge is generated during A/D conversion of the AN_0 pin, input voltage of AN_1 pin is sampled or after at the time of $\overline{\text{ADTRG}}$ falling edge. The conversion of AN_1 and the rest of the sweep starts when AN_0 conversion is completed. •When the $\overline{\text{ADTRG}}$ pin falling edge is generated again during single sweep conversion of pins after the AN_1 pin, the conversion is not affected
A/D Conversion Stop Condition	•A/D conversion completed •Set the ADST bit to 0 (A/D conversion halted) (3)
Interrupt Request Generation Timing	Single sweep conversion completed
Analog Input Pin	Select from AN_0 to AN_1 (2 pins), AN_0 to AN_3 (4 pins), AN_0 to AN_5 (6 pins) and AN_0 to AN_7 (8 pins) (4)
Readout of A/D Conversion Result	Readout one of registers AN0 to AN7 that corresponds to the selected pins

NOTES:

1. Do not generate the next $\overline{\text{ADTRG}}$ pin falling edge after the AN1 pin conversion is started until all selected pins complete A/D conversion. When an $\overline{\text{ADTRG}}$ pin falling edge is generated again during A/D conversion, its trigger is ignored. The falling edge of $\overline{\text{ADTRG}}$ pin, which was input after all selected pins complete A/D conversion, is considered to be the next AN0 pin conversion start condition.
2. The $\overline{\text{ADTRG}}$ pin falling edge is detected synchronized with the operation clock fAD. Therefore, when the $\overline{\text{ADTRG}}$ pin falling edge is generated in shorter periods than fAD, the second $\overline{\text{ADTRG}}$ pin falling edge may not be detected. Do not generate the $\overline{\text{ADTRG}}$ pin falling edge in shorter periods than fAD.
3. Do not write 1 (A/D conversion started) to the ADST bit in delayed trigger mode 1. When write 1,unexpected interrupts may be generated.
4. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. However, all input pins need to belong to the same group.

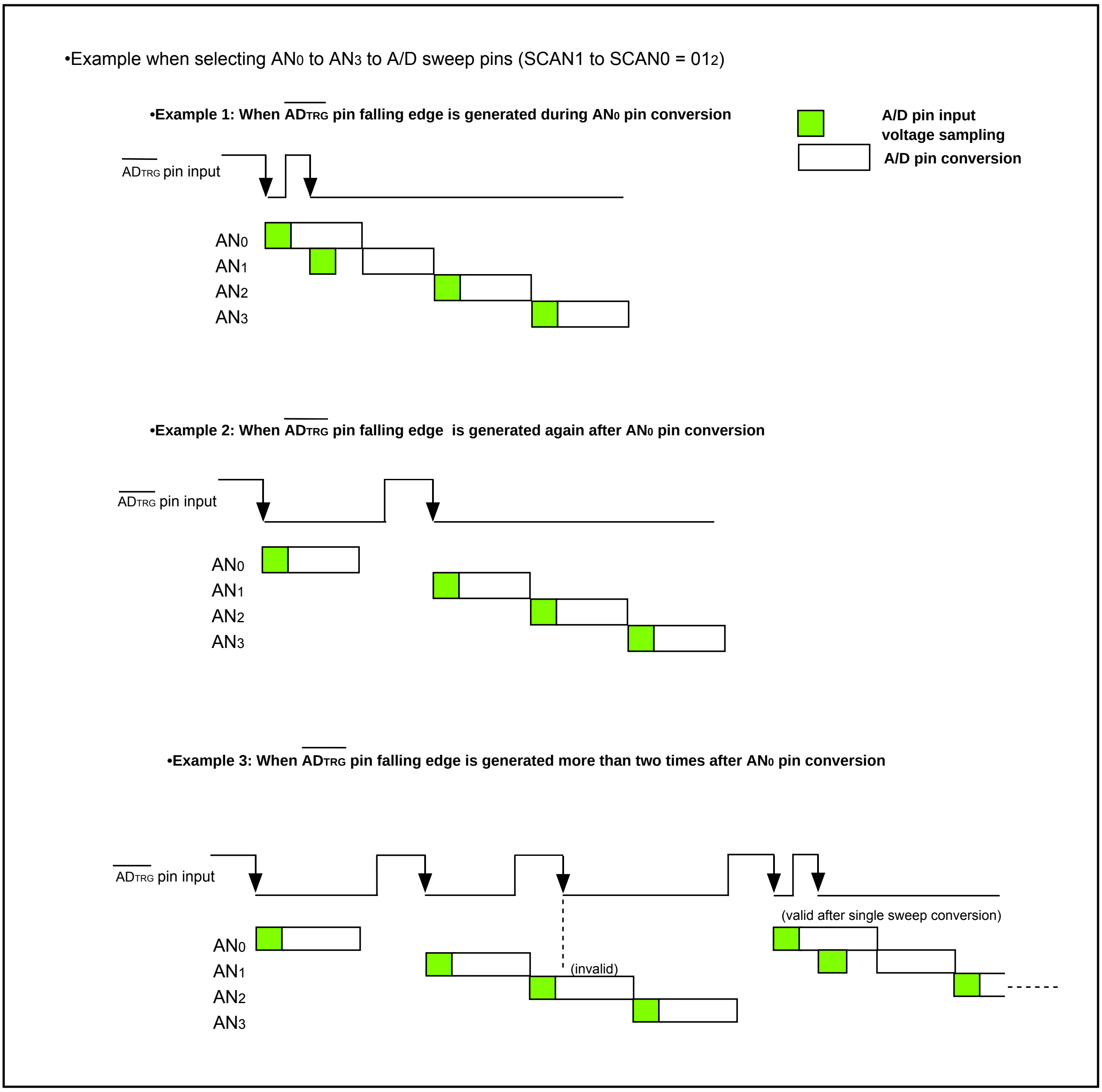
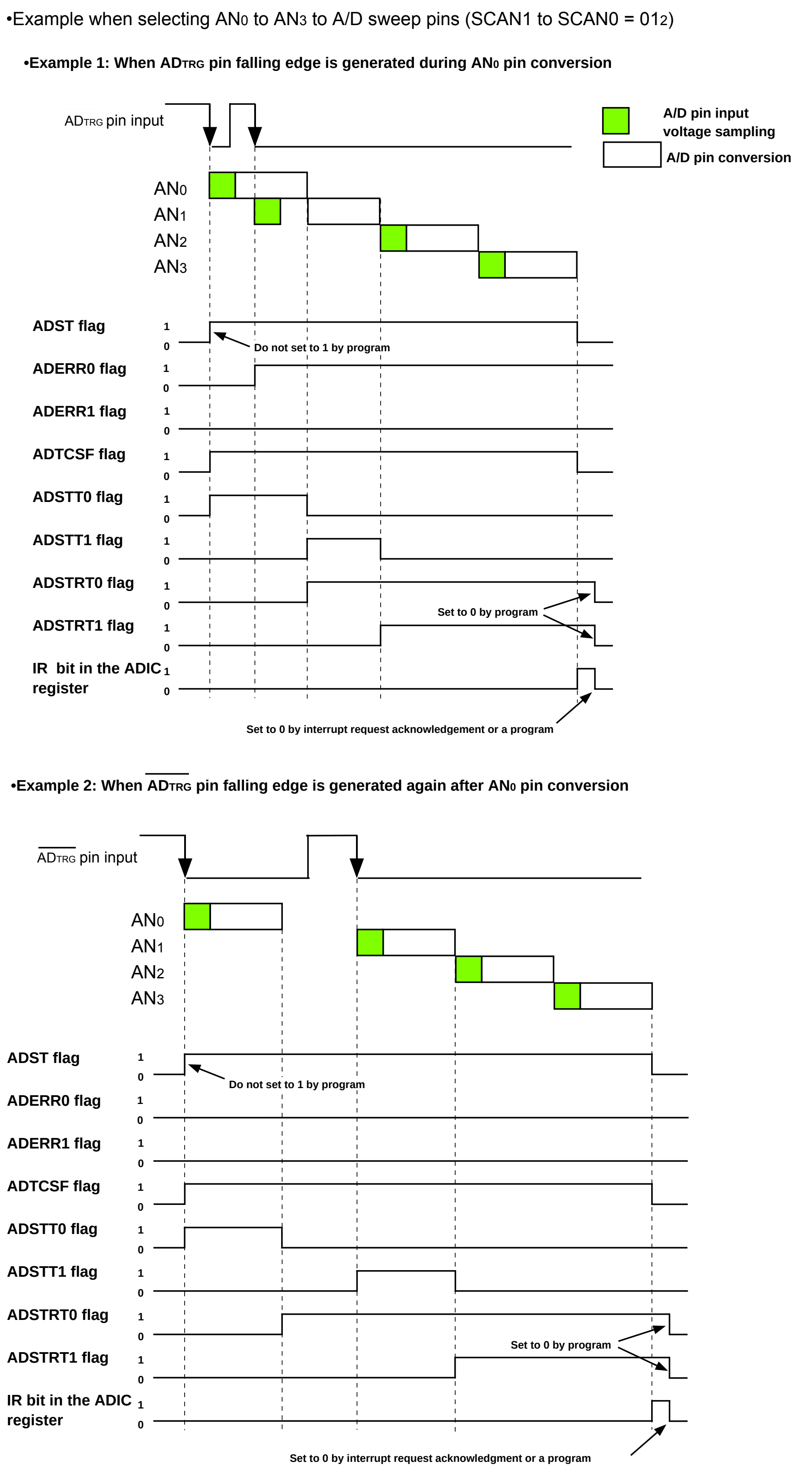


Figure 15.24 Operation Example in Delayed Trigger Mode1



ADST flag: Bit 6 in the ADCON0 register
ADERR0, ADERR1, ADTCSF, ADSTT0, ADSTT1, ADSTRT0 and ADSTRT1 flag: bits 0, 1, 3, 4, 5, 6 and 7 in the ADSTAT0 register

Figure 15.25 Each Flag Operation in ADSTAT0 Register Associated with the Operation Example in Delayed Trigger Mode 1 (1)

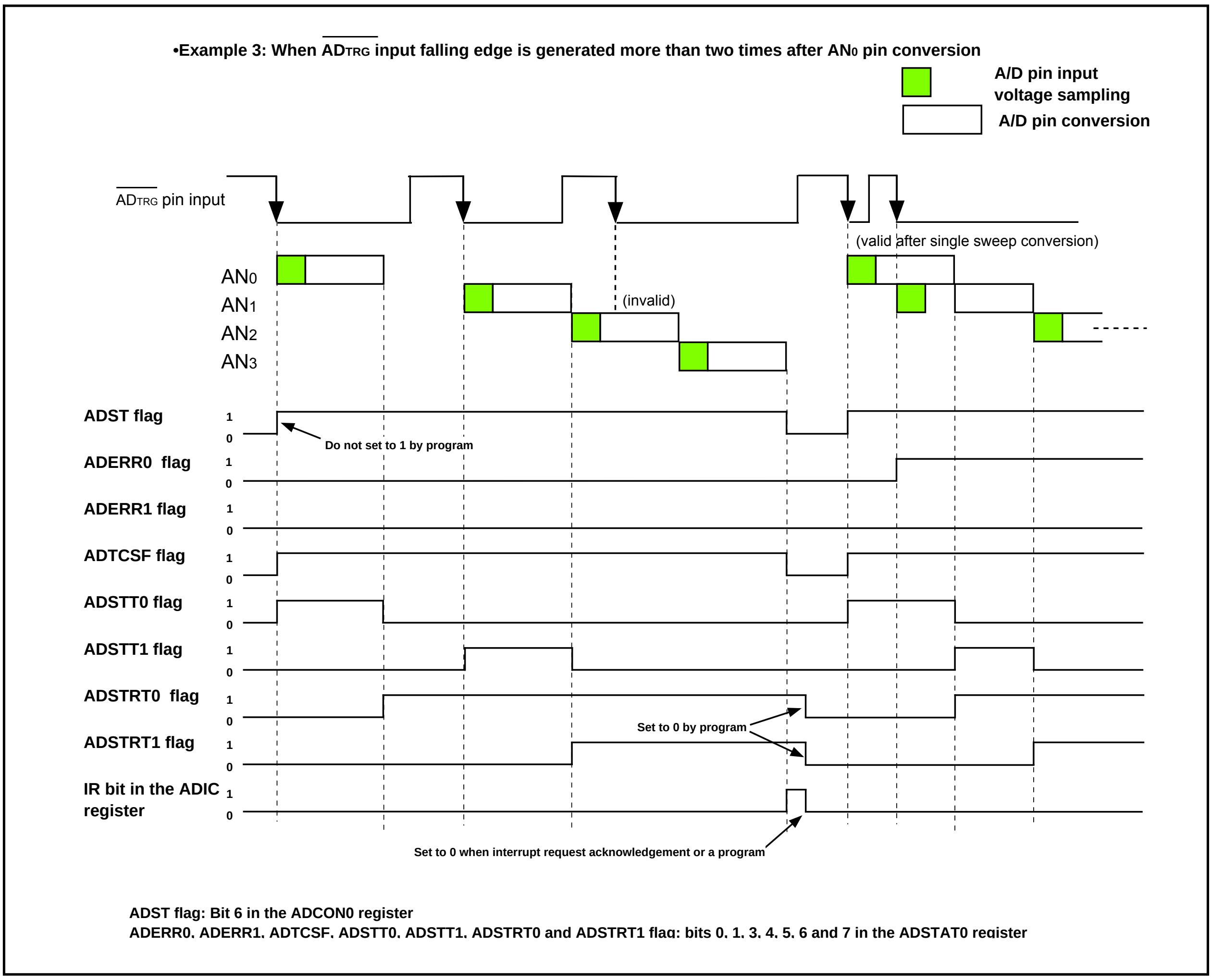


Figure 15.26 Each Flag Operation in ADSTAT0 Register Associated with the Operation Example in Delayed Trigger Mode 1 (2)

A/D Control Register 0 (1)

b7	b6	b5	b4	b3	b2	b1	b0
		0	0	0	1	1	1

Symbol ADCON0 Address $03D6_{16}$ After Reset $00000XXX_2$

Bit Symbol	Bit Name	Function	RW
CH0	Analog input pin select bit	b2 b1 b0 1 1 1: Set to 111b in delayed trigger mode 1	RW
CH1			RW
CH2			RW
MD0	A/D operation mode select bit 0	b4 b3 0 0 : One-shot mode or delayed trigger mode 0,1	RW
MD1			RW
TRG	Trigger select bit	Refer to **Table 15.13**	RW
ADST	A/D conversion start flag (2)	0 : A/D conversion disabled 1 : A/D conversion started	RW
CKS0	Frequency select bit 0	Refer to **Table 15.2**	RW

NOTES:
1. If the ADCON0 register is rewritten during A/D conversion, the conversion result will be undefined.
2. Do not write 1 in delayed trigger mode 1. If necessary, set to 0.

A/D Control Register 1 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1			0		

Symbol ADCON1 Address $03D7_{16}$ After Reset 00_{16}

Bit Symbol	Bit Name	Function	RW
SCAN0	A/D sweep pin select bit(2)	When selecting delayed trigger mode 1 b1 b0 0 0: AN_0 to AN_1 (2 pins) 0 1: AN_0 to AN_3 (4 pins) 1 0: AN_0 to AN_5 (6 pins) 1 1: AN_0 to AN_7 (8 pins)	RW
SCAN1			RW
MD2	A/D operation mode select bit 1	0: Any mode other than repeat sweep mode 1	RW
BITS	8/10-bit mode select bit	0: 8-bit mode 1: 10-bit mode	RW
CKS1	Frequency select bit 1	Refer to **Table 15.2**	RW
VCUT	Vref connect bit (3)	1: Vref connected	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

NOTES:
1. If the ADCON1 register is rewritten during A/D conversion, the conversion result will be undefined.
2. $AN0_0$ to $AN0_7$, $AN2_0$ to $AN2_7$, and $AN3_0$ to $AN3_2$ can be used in the same way as AN_0 to AN_7. Use bits ADGSEL1 and ADGSET0 in the ADCON2 register to select the desired pin.
3. If the VCUT bit is reset from 0 (Vref unconnected) to 1 (Vref connected), wait for 1 µs or more before starting A/D conversion.

A/D Control Register 2 (1)

b7	b6	b5	b4	b3	b2	b1	b0
X	X	1		0			1

Symbol ADCON2 Address $03D4_{16}$ After Reset 00_{16}

Bit Symbol	Bit Name	Function	RW
SMP	A/D conversion method select bit (2)	1: With sample and hold	RW
ADGSEL0	A/D input group select bit	b2 b1 0 0: Select port P10 group 0 1: Select port P9 group 1 0: Select port P0 group 1 1: Select port P1/P9 group	RW
ADGSEL1			RW
— (b3)	Reserved bit	Set to 0	RW
CKS2	Frequency select bit 2	Refer to **Table 15.2**	RW
TRG1	Trigger select bit 1	Refer to **Table 15.13**	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTES:
1. If the ADCON2 register is rewritten during A/D conversion, the conversion result will be undefined.
2. Set to 1 in delayed trigger mode 1.

Figure 15.27 ADCON0 to ADCON2 Registers in Delayed Trigger Mode 1

A/D Trigger Control Register [1]

b7	b6	b5	b4	b3	b2	b1	b0
X	X	X	X	0	0	1	1

Symbol	Address	After Reset
ADTRGCON	$03D2_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
SSE	A/D operation mode select bit 2	Simultaneous sample sweep mode or delayed trigger mode 0, 1	RW
DTE	A/D operation mode select bit 3	Delayed trigger mode 0, 1	RW
HPTRG0	AN_0 trigger select bit	See **Table 15.13**	RW
HPTRG1	AN_1 trigger select bit	See **Table 15.13**	RW
— (b7-b4)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. If ADTRGCON is rewritten during A/D conversion, the conversion result will be undefined.

Figure 15.28 ADTRGCON Register in Delayed Trigger Mode 1

Table 15.13 Trigger Select Bit Setting in Delayed Trigger Mode 1

TRG	TRG1	HPTRG0	HPTRG1	Trigger
0	1	0	0	$\overline{ADTRG}$

15.2 Resolution Select Function

The BITS bit in the ADCON1 register determines the resolution. When the BITS bit is set to 1 (10-bit precision), the A/D conversion result is stored into bits 0 to 9 in the ADi register (i=0 to 7). When the BITS bit is set to 0 (8-bit precision), the A/D conversion result is stored into bits 7 to 0 in the ADi register.

15.3 Sample and Hold

When the SMP bit in the ADCON 2 register is set to 1 (with the sample and hold function), A/D conversion rate per pin increases to 28 ϕAD cycles for 8-bit resolution or 33 ϕAD cycles for 10-bit resolution. The sample and hold function is available in one-shot mode, repeat mode, single sweep mode, repeat sweep mode 0 and repeat sweep mode 1. In these modes, start A/D conversion after selecting whether the sample and hold circuit is to be used or not. In simultaneous sample sweep mode, delayed trigger mode 0 or delayed trigger mode, set to use the Sample and Hold function before starting A/D conversion.

15.4 Power Consumption Reducing Function

When the A/D converter is not used, the VCUT bit in the ADCON1 register isolates the resistor ladder of the A/D converter from the reference voltage input pin (VREF). Power consumption is reduced by shutting off any current flow into the resistor ladder from the VREF pin.

When using the A/D converter, set the VCUT bit to 1 (Vref connected) before setting the ADST bit in the ADCON0 register to 1 (A/D conversion started). Do not set the ADST bit and VCUT bit to 1 simultaneously, nor set the VCUT bit to 0 (Vref unconnected) during A/D conversion.

15.5 Output Impedance of Sensor under A/D Conversion

To carry out A/D conversion properly, charging the internal capacitor C shown in **Figure 15.29** has to be completed within a specified period of time. T (sampling time) as the specified time. Let output impedance of sensor equivalent circuit be R0, MCU's internal resistance be R, precision (error) of the A/D converter be X, and the A/D converter's resolution be Y (Y is 1024 in the 10-bit mode, and 256 in the 8-bit mode).

VC is generally $VC = VIN\{1-e^{-\frac{1}{c(R0+R)}t}\}$

And when t = T, $VC = VIN - \frac{X}{Y}VIN = VIN(1-\frac{X}{Y})$

$$e^{-\frac{1}{c(R0+R)}T} = \frac{X}{Y}$$

$$-\frac{1}{C(R0+R)}T = \ln\frac{X}{Y}$$

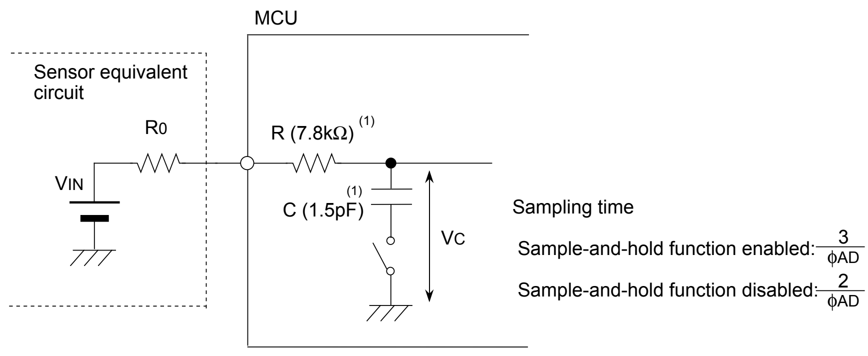
Hence, $R0 = -\frac{T}{C \bullet \ln\frac{X}{Y}} - R$

Figure 15.29 shows analog input pin and externalsensor equivalent circuit. When the difference between VIN and VC becomes 0.1 LSB, we find impedance R0 when voltage between pins. VC changes from 0 to VIN-(0.1/1024) VIN in timer T. (0.1/1024) means that A/D precision drop due to insufficient capacitor chage is held to 0.1LSB at time of A/D conversion in the 10-bit mode. Actual error however is the value of absolute precision added to 0.1LSB. When f(XIN) = 10MHz, T=0.3µs in the A/D conversion mode with sample & hold. Output inpedance R0 for sufficiently charging capacitor C within time T is determined as follows.

T = 0.3µs, R = 7.8kΩ, C = 1.5pF, X = 0.1, and Y = 1024. Hence,

$$R0 = -\frac{0.3X10^{-6}}{1.5X10^{-12} \bullet \ln\frac{0.1}{1024}} - 7.8 X 10^3 \cong 13.9 X 10^3$$

Thus, the allowable output impedance of the sensor circuit capable of thoroughly driving the A/D converter turns out of be approximately 13.9kΩ.



NOTE:
1. Reference value

Figure 15.29 Analog Input Pin and External Sensor Equivalent Circuit

16. Multi-master I2C bus Interface

The multi-master I2C bus interface is a serial communication circuit based on Philips I2C bus data transfer format, equipped with arbitration lost detection and synchronous functions. **Figure 16.1** shows a block diagram of the multi-master I2C bus interface and **Table 16.1** lists the multi-master I2C bus interface functions.

The multi-master I2C bus interface consists of the S0D0 register, the S00 register, the S20 register, the S3D0 register, the S4D0 register, the S10 register, the S2D0 register and other control circuits.

Figures 16.2 to **16.8** show the registers associated with the multi-master I2C bus.

Table 16.1 Multi-master I2C bus interface functions

Item	Function
Format	Based on Philips I2C bus standard: 7-bit addressing format High-speed clock mode Standard clock mode
Communication mode	Based on Philips I2C bus standard: Master transmit Master receive Slave transmit Slave receive
SCL clock frequency	16.1kHz to 400kHz (at V_{IIC} (1)= 4MHz)
I/O pin	Serial data line SDAMM(SDA) Serial clock line SDLMM(SCL)

NOTE:

1. V_{IIC}=I2C system clock

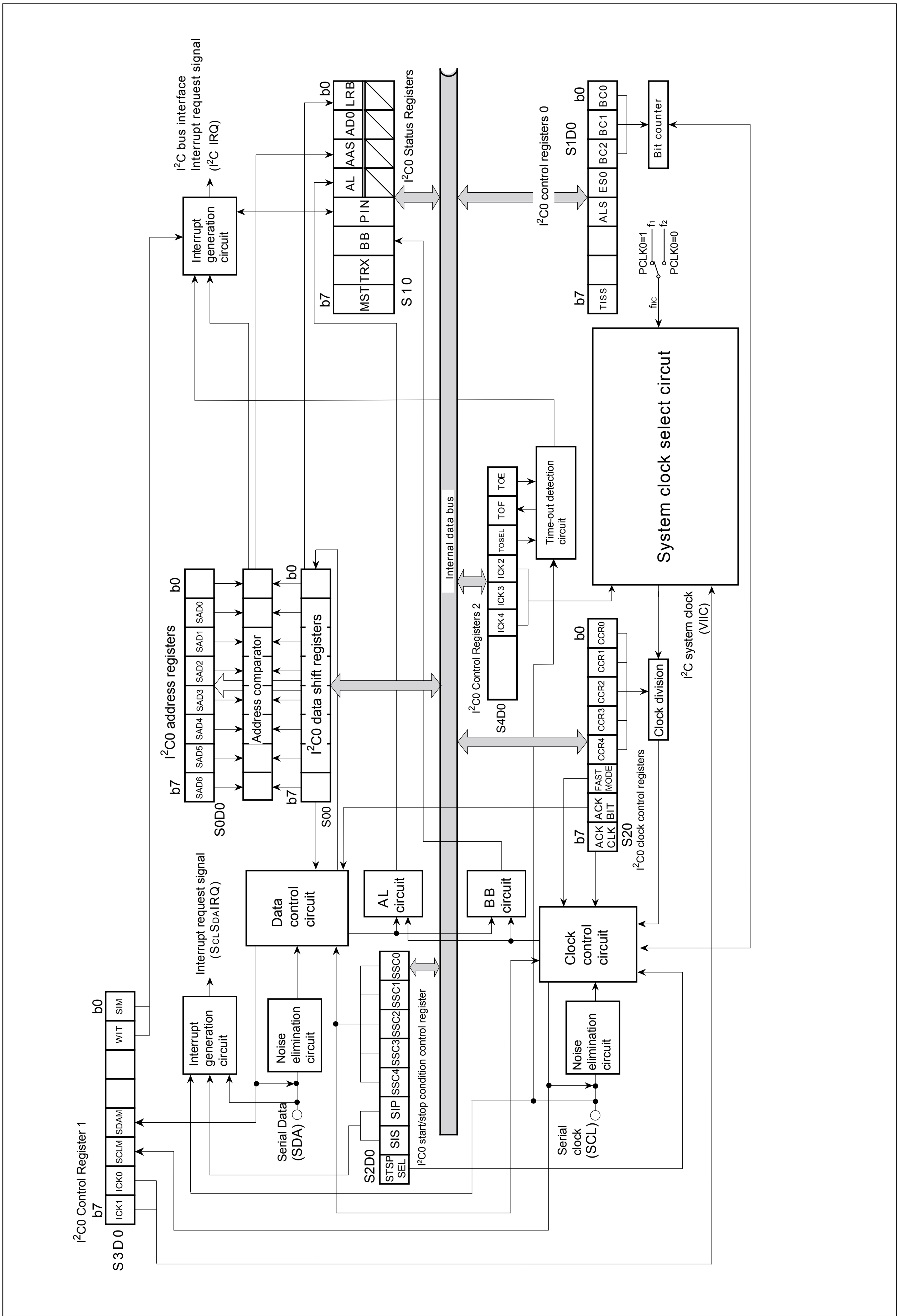


Figure 16.1 Block diagram of multi-master I^{2}C bus interface

I^{2}C0 Address Register

b7	b6	b5	b4	b3	b2	b1	b0
							0

Symbol	Address	After Reset
S0D0	$02E2_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
$\overline{\text{(b0)}}$	Reserved bit	Set to 0	RW
SAD0	Slave address	Compare with received address data	RW
SAD1			RW
SAD2			RW
SAD3			RW
SAD4			RW
SAD5			RW
SAD6			RW

Figure 16.2 S0D0 Register

I²C0 Data Shift Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
S00	$02E0_{16}$	XX_{16}

Function	RW
Transmit/receive data are stored. In master transmit mode, the start condition/stop condition are triggered by writing data to the register (refer to **16.9 START Condition Generation Method** and **16.11 STOP Condition Generation Method**). Start transmitting/receiving data while synchronizing with SCL	RW(1)

NOTE:
1. Write is enabled only when the ES0 bit in the S1D0 register is 1 (I²C bus interface is enabled). Write the transmit data after the receive data is read because the S00 register is used to store both the transmit and receive data. When the S00 register is set, bits BC2 to BC0 in the S1D0 register are set to 000_2, while bits LRB, AAS, and AL in the S10 register are set to 0 respectively.

I²C0 Clock Control Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
S20	$02E4_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
CCR0	SCL Frequency Control Bits	See **Table 16.3**	RW
CCR1			RW
CCR2			RW
CCR3			RW
CCR4			RW
FAST MODE	SCL Mode Specification Bit	0: Standard clock mode 1: High-speed clock mode	RW
ACKBIT	ACK Bit	0: ACK is returned 1: ACK is not returned	RW
ACK-CLK	ACK Clock Bit	0: No ACK clock 1: With ACK clock	RW

Figure 16.3 S00 and S20 Registers

I^{2}C0 Control Register 0

b7	b6	b5	b4	b3	b2	b1	b0
		0					

Symbol	Address	After Reset
S1D0	02E3$_{16}$	00$_{16}$

Bit Symbol	Bit Name	Function	RW
BC0	Bit counter (Number of transmit/receive bits)(1)	b2 b1 b0 0 0 0: 8 0 0 1: 7 0 1 0: 6 0 1 1: 5 1 0 0: 4 1 0 1: 3 1 1 0: 2 1 1 1: 1	RW
BC1			RW
BC2			RW
ES0	I^{2}C bus interface enable bit	0: Disabled 1: Enabled	RW
ALS	Data format select bit	0: Addressing format 1: Free data format	RW
$\overline{(b5)}$	Reserved bit	Set to 0	RW
IHR	I^{2}C bus interface reset bit	0: Reset release (automatic) 1: Reset	RW
TISS	I^{2}C bus interface pin input level select bit	0: I^{2}C bus input 1: SMBUS input	RW

NOTE:
1. In the following status, the bit counter is set to 000 automatically
   - Start condition/stop condition are detected
   - Immediately after the completion of 1-byte data transmit
   - Immediately after the completion of 1-byte data receive

Figure 16.4 S1D0 Register

I^{2}C0 Status Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
S10	$02E8_{16}$	$0001000X_2$

Bit Symbol	Bit Name	Function	RW
LRB	Last receive bit	0: Last bit = 0 1: Last bit = 1	RO(1)
ADR0	General call detecting flag	0: No general call detected 1: General call detected	RO(1)
AAS	Slave address comparison flag	0: No address matched 1: Address matched	RO(1)
AL	Arbitration lost detection flag	0: Not detected 1: Detected	RO(2)
PIN	I^{2}C bus interface interrupt request bit	0: Interrupt request issued 1: No interrupt request issued	RO(2)
BB	Bus busy flag	0: Bus free 1: Bus busy	RO(1)
TRX	Communication mode select bits 0	0: Receive mode 1: Transmit mode	RW(3)
MST	Communication mode select bit 1	0: Slave mode 1: Master mode	RW(3)

NOTES:
1. This bit is read only if it is used for the status check.
   To write to this bit, refer to **16.9 START Condition Generation Method** and **16.11 STOP Condition Generation Method**.
2. Read only. If necessary, set to 0.
3. To write to these bits, refer to **16.9 START Condition Generation Method** and **16.11 STOP Condition Generation Method.**

Figure 16.5 S10 Register

I²C0 Control Register 1

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
S3D0	$02E6_{16}$	00110000_2

Bit Symbol	Bit Name	Function	RW
SIM	The interrupt enable bit for STOP condition detection	0: Disable the I²C bus interface interrupt of STOP condition detection 1: Enable the I²C bus interface interrupt of STOP condition detection	RW
WIT	The interrupt enable bit for data receive completion	0: Disable the I²C bus interface interrupt of data receive completion 1: Enable the I²C bus interface interrupt of data receive completion When setting NACK (ACK bit = 0), write 0	RW
PED	SDA/port function switch bit[1]	0: SDA I/O pin 1: Port output pin	RW
PEC	SCL/port function switch bit[1]	0: SCL I/O pin 1: Port output pin	RW
SDAM	The logic value monitor bit of SDA output	0: SDA output logic value = 0 1: SDA output logic value = 1	RO
SCLM	The logic value monitor bit of SCL output	0: SCL output logic value = 0 1: SCL output logic value = 1	RO
ICK0	I²C bus system clock selection bits, if bits ICK4 to ICK2 in the S4D0 register is 000_2	b7 b6 0 0 : VIIC =1/2 fIIC 0 1 : VIIC =1/4 fIIC 1 0 : VIIC =1/8 fIIC 1 1 : Reserved (2)	RW
ICK1			RW

NOTE:
1. Bits PED and PEC are enabled when the ES0 bit in the S1D0 register is set to 1 (I²C bus interface enabled).
2. When the PCLK0 bit in the PCLKR register is set to 0, fIIC=f2. When the PCLK0 bit in the PCLKR register is set to 1, fIIC=f1.

Figure 16.6 S3D0 Register

I^{2}C0 Control Register 2

b7	b6	b5	b4	b3	b2	b1	b0
	0						

Symbol: S4D0 | Address: $02E7_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
TOE	Time out detection function enable bit	0: Disabled 1: Enabled	RW
TOF	Time out detection flag	0: Not detected 1: Detected	RO
TOSEL	Time out detection time select bit	0: Long time 1: Short time	RW
ICK2	I^{2}C bus system clock select bits	b5 b4 b3 0 0 0 V_{IIC} set by ICK1 and ICK0 bits in S3D0 register 0 0 1 V_{IIC} = 1/2.5 f_{IIC} 0 1 0 V_{IIC} = 1/3 f_{IIC} 0 1 1 V_{IIC} = 1/5 f_{IIC} 1 0 0 V_{IIC} = 1/6 f_{IIC} (1) Do not set other than the above values	RW
ICK3			RW
ICK4			RW
$\overline{\text{(b6)}}$	Reserved bit	Set to 0	RW
SCPIN	STOP condition detection interrupt request bit	0: No I^{2}C bus interface interrupt request 1: I^{2}C bus interface interrupt request	RW

NOTE:
1. When the PCLK0 bit in the PCLKR register is set to 0, f_{IIC} = f_2. When the PCLK0 bit is set to 1, f_{IIC}=f_1.

Figure 16.7 S4D0 Register

I²C0 Start/stop Condition Control Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
S2D0	02E5₁₆	00011010₂

Bit Symbol	Bit Name	Function	RW
SSC0	START/STOP condition setting bits(1)	Setting for detection condition of START/STOP condition. See **Table 16.2**	RW
SSC1			RW
SSC2			RW
SSC3			RW
SSC4			RW
SIP	SCL/SDA interrupt pin polarity select bit	0: Active in falling edge 1: Active in rising edge	RW
SIS	SCL/SDA interrupt pin select bit	0: SDA enabled 1: SCL enabled	RW
STSPSEL	START/STOP condition generation select bit	0: Short setup/hold time mode 1: Long setup/hold time mode	RW

NOTE:
1. Do not set 00000₂ or odd values.

Figure 16.8 S2D0 Register

Table 16.2 Recommended setting (SSC4-SSC0) start/stop condition at each oscillation frequency

Oscillation f1 (MHz)	I²C bus system clock select	I²C bus system clock(MHz)	SSC4-SSC0(1)	SCL release time (cycle)	Setup time (cycle)	Hold time (cycle)
10	1 / 2f1(2)	5	XXX11110	6.2 µs (31)	3.2 µs (16)	3.0 µs (15)
8	1 / 2f1(2)	4	XXX11010	6.75 µs(27)	3.5 µs (14)	3.25 µs(13)
			XXX11000	6.25 µs(25)	3.25 µs (13)	3.0 µs (12)
8	1 / 8f1(2)	1	XXX00100	5.0 µs (5)	3.0 µs (3)	2.0 µs (2)
4	1 / 2f1(2)	2	XXX01100	6.5 µs (13)	3.5 µs (7)	3.0 µs (6)
			XXX01010	5.5 µs (11)	3.0 µs (6)	2.5 µs (5)
2	1 / 2f1(2)	1	XXX00100	5.0 µs (5)	3.0 µs (3)	2.0 µs (2)

NOTES:
1. Do not set odd values or 00000₂ to START/STOP condition setting bits (SSC4 to SSC0)
2. When the PCLK0 bit in the PCLKR register is set to 1.

16.1 I2C0 Data Shift Register (S00 register)

The S00 register is an 8-bit data shift register to store a received data and to write a transmit data. When a transmit data is written to the S00 register, the transmit data is synchronized with a SCL clock and the data is transferred from bit 7. Then, every one bit of the data is transmitted, the register's content is shifted for one bit to the left. When the SCL clock and the data is imported into the S00 register from bit 0. Every one bit of the data is imported, the register's content is shifted for one bit to the left. **Figure 16.9** shows the timing to store the receive data to the S00 register.

The S00 register can be written when the ES0 bit in the S1D0 register is set to 1 (I2C0 bus interface enabled). If the S00 register is written when the ES0 bit is set to 1 and the MST bit in the S10 register is set to 1 (master mode), the bit counter is reset and the SCL clock is output. Write to the S00 register when the START condition is generatedor when an "L" signal is applied to the SCL pin. The S00 register can be read anytime regardless of the ES0 bit value.

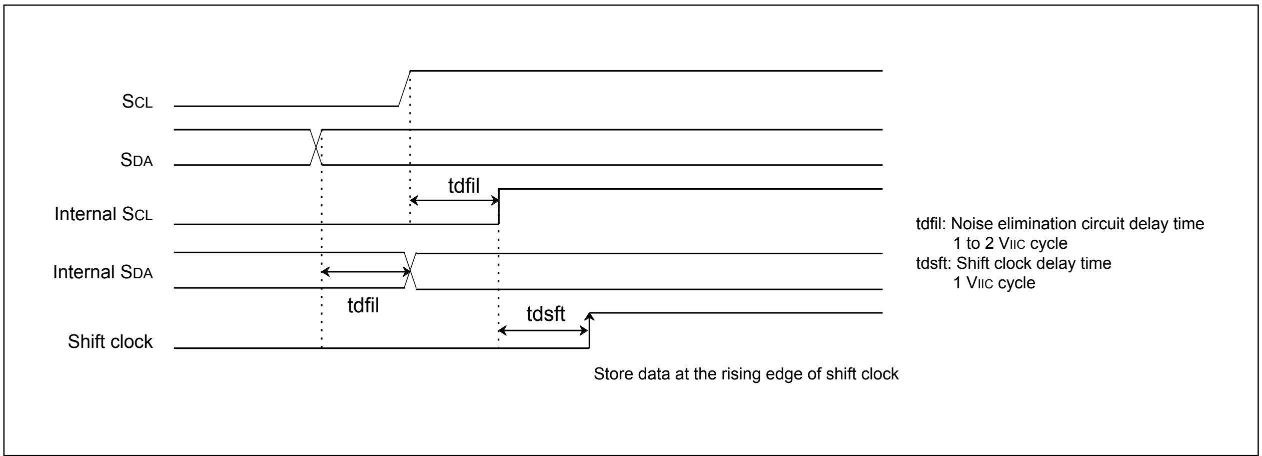


Figure 16.9 The Receive Data Storing Timing of S00 Register

16.2 I2C0 Address Register (S0D0 register)

The S0D0 register consists of bits SAD6 to SAD0, total of 7. At the addressing is formatted, slave address is detected automatically and the 7-bit received address data is compared with the contents of bits SAD6 to SAD0.

16.3 I²C0 Clock Control Register (S20 register)

The S20 register is used to set theACK control, SCL mode and the SCL frequency.

16.3.1 Bits 0 to 4: SCL Frequency Control Bits (CCR0–CCR4)

These bits control the SCL frequency. See **Table 16.3** .

16.3.2 Bit 5: SCL Mode Specification Bit (FAST MODE)

The FAST MODE bit selects SCL mode. When the FAST MODE bit is set to 0, standard clock mode is entered. When it is set to 1, high-speed clock mode is entered.
When using the high-speed clock mode I²C bus standard (400 kbit/s maximum) to connect buses, set the FAST MODE bit to 1 (select SCL mode as high-speed clock mode) and use the I²C bus system clock (V_{IIC}) at 4 MHz or more frequency.

16.3.3 Bit 6: ACK Bit (ACKBIT)

The ACKBIT bit sets the SDA status when an ACK clock(1) is generated. When the ACKBIT bit is set to 0, ACK is returned and te clock applied to SDA becomes "L" when ACK clock is generated. When it is set to 1, ACK is not returned and the clock clock applied to SDA maintains "H" at ACK clock generation.
When the ACKBIT bit is set to 0, the address data is received. When the slave address matches with the address data, SDA becomes "L" automatically (ACK is returned). When the slave address and the address data are not matched, SDA becomes "H" (ACK is not returned).

NOTE:

1. ACK clock: Clock for acknowledgment

16.3.4 Bit 7: ACK Clock Bit (ACK-CLK)

The ACK-CLK bit set a clock for data transfer acknowledgement. When the ACK-CLK bit is set to 0, ACK clock is not generated after data is transferred. When it is set to 1, a master generates ACK clock every one-bit data transfer is completed. The device, which transmits address data and control data, leave SDA pin open (apply "H" signal to SDA) when ACK clock is generated. The device which receives data, receives the generated ACKBIT bit.

NOTE:

1.Do not rewrite the S20 register, other than the ACKBIT bit during data transfer. If data is written to other than the ACKBIT bit during transfer, the I²C bus clock circuit is reset and the data may not be transferred successfully.

Table 16.3 Setting values of S20 register and SCL frequency

Setting value of CCR4 to CCR0					SCL frequency (at VIIC=4MHz, unit : kHz) (1)	
CCR4	CCR3	CCR2	CCR1	CCR0	Standard clock mode	High-speed clock mode
0	0	0	0	0	Setting disabled	Setting disabled
0	0	0	0	1	Setting disabled	Setting disabled
0	0	0	1	0	Setting disabled	Setting disabled
0	0	0	1	1	- (2)	333
0	0	1	0	0	- (2)	250
0	0	1	0	1	100	400 (3)
0	0	1	1	0	83.3	166
↓	↓	↓	↓	↓	500 / CCR value (3)	1000 / CCR value (3)
1	1	1	0	1	17.2	34.5
1	1	1	1	0	16.6	33.3
1	1	1	1	1	16.1	32.3

NOTES:

1. The duty of the SCL clock output is 50 %. The duty becomes 35 to 45 % only when high-speed clock mode is selected and the CCR value = 5 (400 kHz, at VIIC = 4 MHz). “H” duration of the clock fluctuates from –4 to +2 I2C system clock cycles in standard clock mode, and fluctuates from –2 to +2 I2C system clock cycles in high-speed clock mode. In the case of negative fluctuation, the frequency does not increase because the “L” is extended instead of “H” reduction. These are the values when the SCL clock synchronization by the synchronous function is not performed. The CCR value is the decimal notation value of the CCR4 to CCR0 bits.
2. Each value of the SCL frequency exceeds the limit at VIIC = 4 MHz or more. When using these setting values, use VIIC = 4 MHz or less. Refer to **Figure 16.6**.
3. The data formula of SCL frequency is described below:
   VIIC/(8 x CCR value) Standard clock mode
   VIIC/(4 x CCR value) High-speed clock mode (CCR value ≠ 5)
   VIIC/(2 x CCR value) High-speed clock mode (CCR value = 5)
   Do not set 0 to 2 as the CCR value regardless of the VIIC frequency. Set 100 kHz (max.) in standard clock mode and 400 kHz (max.) in high-speed clock mode to the SCL frequency by setting the CCR4 to CCR0 bits.

16.4 I^{2}C0 Control Register 0 (S1D0)

The S1D0 register controls data communication format.

16.4.1 Bits 0 to 2: Bit Counter (BC0–BC2)

Bits BC2 to BC0 decide how many bits are in one byte data transferred next. After the selected numbers of bits are transferred successfully, I^{2}C bus interface interrupt request is gnerated and bits BC2 to BC0 are reset to 000_2. At this time, if the ACK-CLK bit in the S20 register is set to 1 (with ACK clock), one bit for ACK clock is added to the numbers of bits selected by the BC2 to BC0 bits.
In addition, bits BC2 to BC0 become 000_2 even though the START condition is detected and the address data is transferred in 8 bits.

16.4.2 Bit 3: I^{2}C Interface Enable Bit (ES0)

The ES0 bit enables to use the multi-master I^{2}C bus interface. When the ES0 bit is set to 0, I^{2}C bus interface is disabled and the SDA and SCL pins are placed in a high-h-impedance state. When the ES0 bit is set to 1, the interface is enabled.
When the ES0 bit is set to 0, the process is followed.
1)The bits in the S10 register are set as MST = 0, TRX = 0, PIN = 1, BB = 0, AL = 0, AAS = 0, ADR0 = 0
2)The S00 register cannot be written.
3)The TOF bit in the S4D0 register is set to 0 (time-out detection flag is not detected)
4)The I^{2}C system clock (V_{IIC}) stops counting while the internal counter and flags are reset.

16.4.3 Bit 4: Data Format Select Bit (ALS)

The ALS bit determines whether the salve address is recognized. When the ALS bit is set to 0, an addressing format is selected and a address data is recognized. Only if the comparison is matched between the slave address stored into the S0D0 register and the received address data or if the general call is received, the data is transferred. When the ALS bit is set to 1, the free data format is selected and the slave address is not recognized.

16.4.4 Bit 6: I^{2}C bus Interface Reset Bit (IHR)

The IHR bit is used to reset the I^{2}C bus interface circuit when the error communication occurs.
When the ES0 bit in the S1D0 register is set to 1 (I^{2}C bus interface is enabled), the hardware is reset by writing 1 to the IHR bit. Flags are processed as follows:
1)The bits in the S10 register are set as MST = 0, TRX = 0, PIN to 1, BB = 0, AL = 0, AAS = 0, and ADR0 = 0
2)The TOF bit in the S4D0 register is set to 0 (time-out detection flag is not detected)
3)The internal counter and flags are reset.
The I^{2}C bus interface circuit is reset after 2.5 V_{IIC} cycles or less, and the IHR bit becomes 0 automatically by writing 1 to the IHR bit. **Figure 16.10** shows the reset timing.

16.4.5 Bit 7: I2C bus Interface Pin Input Level Select Bit (TISS)

The TISS bit selects the input level of the SCL and SDA pins for the multi-master I2C bus interface. When the TISS bit is set to 1, the $P2_0$ and $P2_1$ become the SMBus input level.

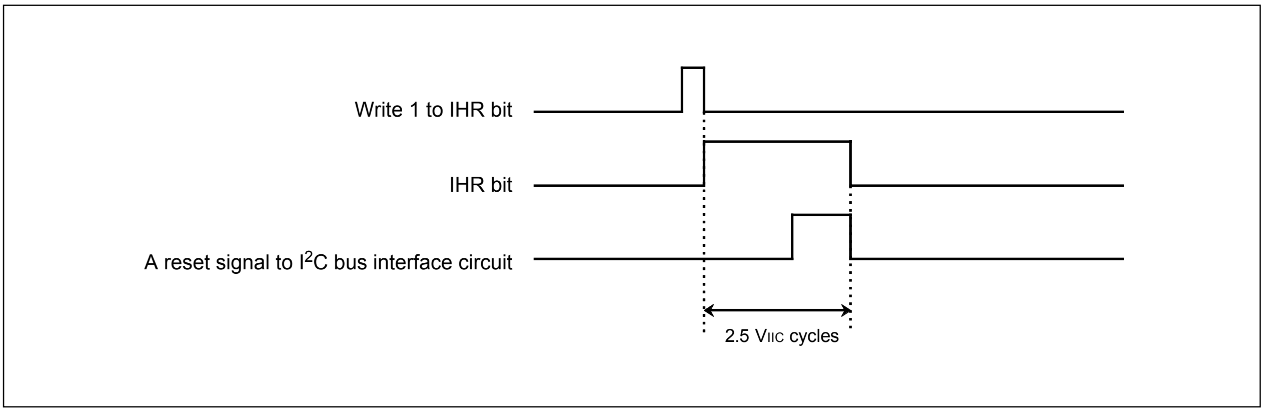


Figure 16.10 The timing of reset to the I2C bus interface circuit

16.5 I^2C0 Status Register (S10 register)

The S10 register monitors the I^2C bus interface status. When using the S10 register to check the status, use the 6 low-order bits for read only.

16.5.1 Bit 0: Last Receive Bit (LRB)

The LRB bit stores the last bit value of received data. It can also be used to confirm whether ACK is received. If the ACK-CLK bit in the S20 register is set to 1 (with ACK clock) and ACK is returned when the ACK clock is generated, the LRB bit is set to 0. If ACK is not returned, the LRB bit is set to 1. When the ACK-CLK bit is set to 0 (no ACK clock), the last bit value of received data is input. When writing data to the S00 register, the LRB bit is set to 0.

16.5.2 Bit 1: General Call Detection Flag (ADR0)

When the ALS bit in the S1D0 register is set to 0 (addressing format), this ADR0 flag is set to 1 by receiving the general calls(1),whose address data are all 0, in slave mode.
The ADR0 flag is set to 0 when STOP or START conditions is detected or when the IHR bit in the S1D0 register is set to 1 (reset).

NOTE:

1. General call: A master device transmits the general call address 00_{16} to all slaves. When the master device transmits the general call, all slave devices receive the controlled data after general call.

16.5.3 Bit 2: Slave Address Comparison Flag (AAS)

The AAS flag indicates a comparison result of the slave address data after enabled by setting the ALS bit in the S1D0 register to 0 (addressing format).
The AAS flag is set to 1 when the 7 bits of the address data are matched with the slave address stored into the S0D0 register, or when a general call is received, in slave receive mode. The AAS flag is set to 0 by writing data to the S00 register. When the ES0 bit in the S1D0 register is set to 0 (I^2C bus interface disabled) or when the IHR bit in the S1D0 register is set to 1 (reset), the AAS flag is also set to 0.

16.5.4 Bit 3: Arbitration Lost Detection Flag (AL)(1)

In master transmit mode, if an "L" signal is applied to the SDA pin by other than the MCU, the AL flag is set to 1 by determining that the arbitration is los and the TRX bit in the S10 register is set to 0 (receive mode) at the same time. The MST bit in the S10 register is set to 0 (slave mode) after transferring the bytes which lost the arbitration.
The arbitration lost can be detected only in master transmit mode. When writing data to the S00 register, the AL flag is set to 0. When the ES0 bit in the S1D0 register is set to 0 (I^2C bus interface disabled) or when the IHR bit in the S1D0 register is set to 1 (reset), the AL flag is set to 0.

NOTE:

1. Arbitration lost: communication disabled as a master

16.5.5 Bit 4: I^{2}C bus Interface Interrupt Request Bit (PIN)

The PIN bit generates an I^{2}C bus interface interrupt request signal. Every one byte data is ransferred, the PIN bit is changed from 1 to 0. At the same time, an I^{2}C bus interface interrupt request is generated. The PIN bit is synchronized with the last clock of the internal transfer clock (when ACK-CLK=1, the last clock is the ACK clock: when the ACK-CLK=0, the last clock is the 8th clock) and it becomes 0. The interrupt request is generated on the falling edge of the PIN bit. When the PIN bit is set to 0, the clock applied to SCL maintains "L" and further clock generation is disabled. When the ACK-CLK bit is set to 1 and the WIT bit in the S3D0 register is set to 1 (enable the I^{2}C bus interface interrupt of data receive completion). The PIN bit is synchronized with the last clock and the falling edge of the ACK clock. Then, the PIN bit is set to 0 and I^{2}C bus interface interrupt request is generated. **Figure 16.11** shows the timing of the I^{2}C bus interface interrupt request generation.

The PIN bit is set to 1 in one of the following conditions:

- •When data is written to the S00 register
- •When data is written to the S20 register (when the WIT bit is set to 1 and the internal WAIT flag is set to 1)
- •When the ES0 bit in the S1D0 register is set to 0 (I^{2}C bus interface disabled)
- •When the IHR bit in the S1D0 register is set to 1(reset)

The PIN bit is set to 0 in one of the following conditions:

- •With completion of 1-byte data transmit (including a case when arbitration lost is detected)
- •With completion of 1-byte data receive
- •When the ALS bit in the S1D0 register is set to 0 (addressing format) and slave address is matched or general call address is received successfully in slave receive mode
- •When the ALS bit is set to 1 (free format) and the address data is received successfully in slave receive mode

16.5.6 Bit 5: Bus Busy Flag (BB)

The BB flag indicates the operating conditions of the bus system. When the BB flag is set to 0, a bus system is not in use and a START condition can be generated. The BB flag is set and reset based on an input signal of the SCL and SDA pins either in master mode or in slave mode. When the START condition is detected, the BB flag is set to 1. On the other hand, when the STOP condition is detected, the BB flag is set to 0. Bits SSC4 to SSC0 in the S2D0 register decide to detect between the START condition and the STOP condition. When the ES0 bit in the S1D0 register is set to 0 (I^{2}C bus interface disabled) or when the IHR bit in the S1D0 register is set to 1 (reset), the BB flag is set to 0. Refer to **16.9 START Condition Generation Method and 16.11 STOP Condition Generation Method**.

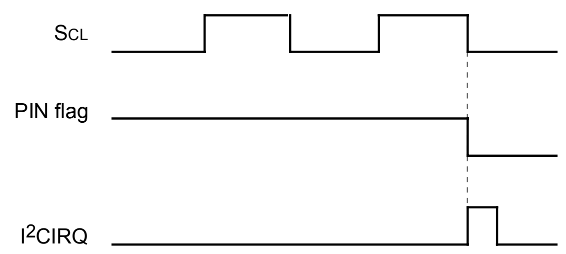


Figure 16.11 Interrupt request signal generation timing

16.5.7 Bit 6: Communication Mode Select Bit (Transfer Direction Select Bit: TRX)

This TRX bit decides a transfer direction for data communication. When the TRX bit is set to 0, receive mode is entered and data is received from a transmit device. When the TRX bit is set to 1, transmit mode is entered, and address data and control data are output to the SDAMM, synchronized with a clock generated in the SCLMM.

The TRX bit is set to 1 automatically in the following condition:

•In slave mode, when the ALS in the S1D0 register to 0(addressing format), the AAS flag is set to 1 (address match) after the address data is received, and the received R/$\overline{W}$ bit is set to 1

The TRX bit is set to 0 in one of the following conditions:

•When an arbitration lost is detected
•When a STOP condition is detected
•When a START condition is detected
•When a START condition is disabled by the START condition duplicate protect function (1)
•When the MST bit in the S10 register is set to 0(slave mode) and a start condition is detected
•When the MST bit is set to 0 and the ACK non-return is detected
•When the ES0 bit is set to 0(I^{2}C bus interface disabled)
•When the IHR bit in the S1D0 register is set to 1(reset)

16.5.8 Bit 7: Communication mode select bit (master/slave select bit: MST)

The MST bit selects either master mode or slave mode for data communication. When the MST bit is set to 0, slave mode is entered and the START/STOP condition generated by a master device are received. The data communication is synchronized with the clock generted by the master. When the MST bit is set to 1, master mode is entered and the START/STOP condition is generated.

Additionally, clocks required for the data communication are generated on the SCLMM.

The MST bit is set to 0 in one of the following conditions.

•After 1-byte data of a master whose arbtration is lost if arbitration lost is detected
•When a STOP condition is detected
•When a START condition is detected
•When a start condition is disabled by the START condition duplicate protect function (1)
•When the IHR bit in the S1D0 register is set to 1(reset)
•When the ES0 bit is set to 0(I^{2}C bus interface disabled)

NOTE:

1. START condition duplicate protect function:
When the START condition is generated, after confirming that the BB flag in the S1D0 register is set to 0 (bus free), all the MST, TRX and BB flags are set to 1 at the same time. However, if the BB flag is set to 1 immediately after the BB flag setting is confirmed because a START condition is generated by other master device, bits MST and TRX cannot be written. The duplicate protect function is valid from the rising edge of the BB flag until slave address is received. Refer to **16.9 START Condition Generation Method** for details.

16.6 I^2C0 Control Register 1 (S3D0 register)

The S3D0 register controls the I^2C bus interface circuit.

16.6.1 Bit 0 : Interrupt Enable Bit by STOP Condition (SIM)

The SIM bit enables the I^2C bus interface interrupt request by detecting a STOP condition. If the SIM bit is set to 1, the I^2C bus interface interrupt request is generated by the STOP condition detect (no need to change in the PIN flag).

16.6.2 Bit 1: Interrupt Enable Bit at the Completion of Data Receive (WIT)

If the WIT bit is set to 1 while the ACK-CLK bit in the S20 register is set to 1 (ACK clock), the I^2C bus interface interrupt request is generated and the PIN bit is set to 1 at the falling edge of the last data bit clock. Then an "L" signal is applied to the SCL_{MM} and the ACK clock generation is controlled. **Table 16.4** and **Figure 16.12** show the interrupt generation timing and the procedure of communication restart. After the communication is restarted, the PIN bit is set to 0 again, synchronized with the falling edge of the ACK clock, and the I^2C bus interface interrupt request is generated.

Table16.4 Timing of Interrupt Generation in Data Receive Mode

I^2C bus Interface Interrupt Generation Timing	Procedure of Communication Restart
1) Synchronized with the falling edge of the last data bit clock	Set the ACK bit in the S20 register. Set the PIN bit to 1. (Do not write to the S00 register. The ACK clock operation may be unstable.)
2) Synchronized with the falling edge of the ACK clock	Set the S00 register

The internal WAIT flag can be read by reading the WIT bit. The internal WAIT flag is set to 1 after writing data to the S00 register and it is set to 0 after writing to the S20 register.
Consequently, the I^2C bus interface interrupt request generated by the timing 1) or 2) can be determined. (See **Figure 16.12**)
When the data is transmitted and the address data is received immediately after the START condition, the WAIT flag remains 0 regardless of the WIT bit setting, and the I^2C bus interface interrupt request is only generated at the falling edge of the ACK clock. Set the WIT bit to 0 when the ACK-CLK bit in the S20 register is set to 0 (no ACK clock).

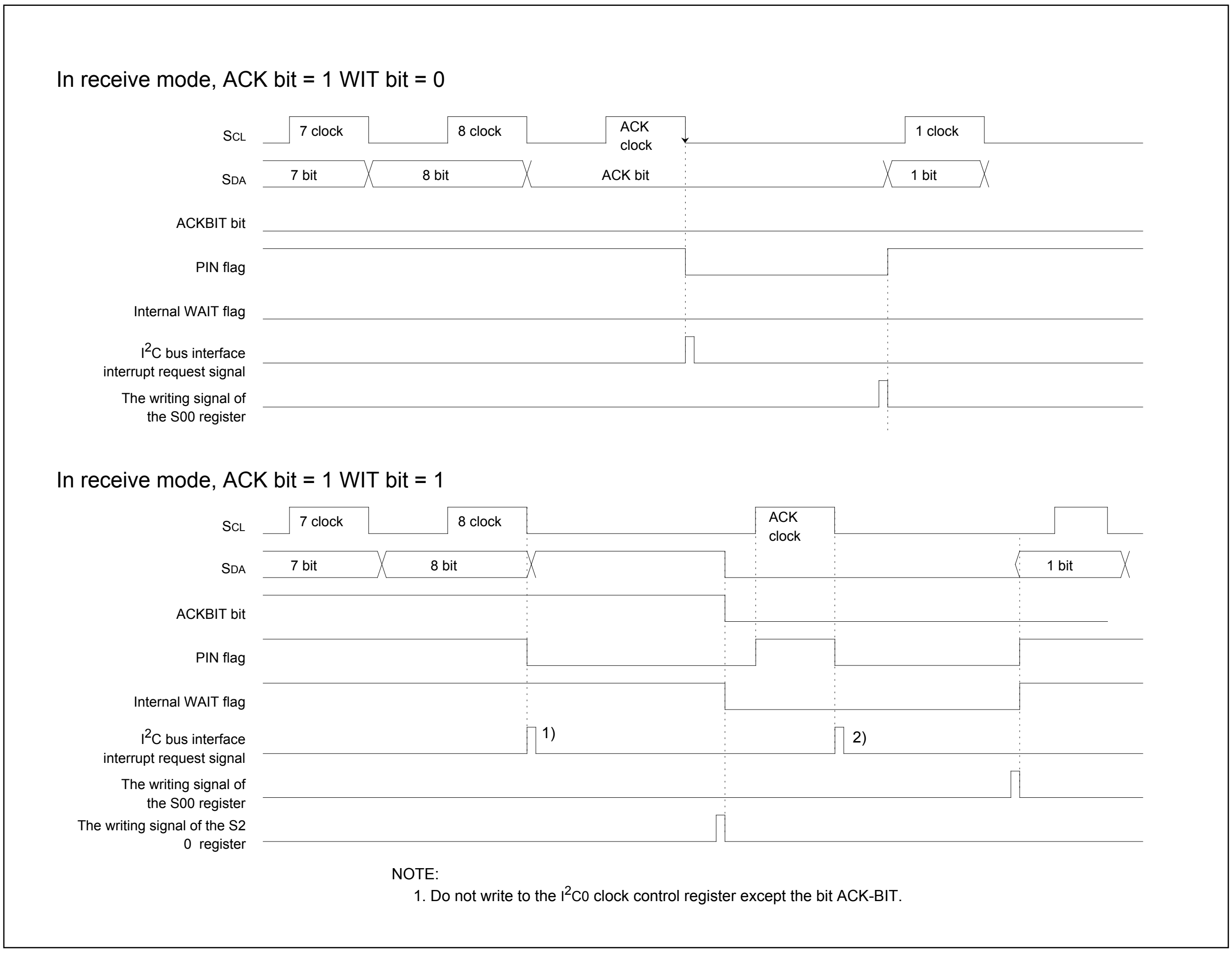


Figure 16.12 The timing of the interrupt generation at the completion of the data receive

16.6.3 Bits 2,3 : Port Function Select Bits PED, PEC

If the ES0 bit in the S1D0 register is set to 1 (I^2C bus interface enabled), the SDAMM functions as an output port. When the PED bit is set to 1 and the SCLMM functions as an output port when the PEC bit is set to 1. Then the setting values of bits P2_0 and P2_1 in the port P2 register are output to the I^2C bus, regardless of he internal SCL/SDA output signals. (SCL/SDA pins are onnected to I^2C bus interface circuit)

The bus data can be read by reading the port pi direction register in input mode, regardless of the setting values of the PED and PEC bits. **Table 16.5** shows the port specification.

Table 16.5 Port specifications

Pin Name	ES9 Bit	PED Bit	P20 Port Direction Register	Function
P20	0	-	0/1	Port I/O function
	1	0	-	SDA I/O function
	1	1	-	SDA input function, port output function
Pin Name	ES0 Bit	PEC Bit	P21 Port Direction Register	Function
P21	0	-	0/1	Port I/O function
	1	0	-	SCL I/O function
	1	1	-	SCL input function, port output funcion

16.6.4 Bits 4,5 : SDA/SCL Logic Output Value Monitor Bits SDAM/SCLM

Bits SDAM/SCLM can monitor the logic value of the SDA and SCL output signals from the I^2C bus interface circuit. The SDAM bit monitors the SDA output logic value. The SCLM bit monitors the SCL output logic value. The SDAM and SCLM bits are read-only. If necessary, set them to 0.

16.6.5 Bits 6,7 : I^2C System Clock Select Bits ICK0, ICK1

The ICK1 bit, ICK0 bit, bits ICK4 to ICK2 in the S4D0 register, and the PCLK0 bit in the PCLKR register can select the system clock (V_{IIC}) of the I^2C bus interface circuit.
The I^2C bus system clock V_{IIC} can be selected among 1/2 f_{IIC}, 1/2.5 f_{IIC}, 1/3 f_{IIC}, 1/4 f_{IIC}, 1/5 f_{IIC}, 1/6 f_{IIC} and 1/8 f_{IIC}. f_{IIC} can be selected between f_1 and f_2 by the PCLK0 bit setting.

Table 16.6 I^2C system clock select bits

I3CK4[S4D0]	ICK3[S4D0]	ICK2[S4D0]	ICK1[S3D0]	ICK0[S3D0]	I^2C system clock
0	0	0	0	0	V_{IIC} = 1/2 f_{IIC}
0	0	0	0	1	V_{IIC} = 1/4 f_{IIC}
0	0	0	1	0	V_{IIC} = 1/8 f_{IIC}
0	0	1	X	X	V_{IIC} = 1/2.5 f_{IIC}
0	1	0	X	X	V_{IIC} = 1/3 f_{IIC}
0	1	1	X	X	V_{IIC} = 1/5 f_{IIC}
1	0	0	X	X	V_{IIC} = 1/6 f_{IIC}

(Do not set the combination other than the above)

16.6.6 Address Receive in STOP/WAIT Mode

When WAIT mode is entered after the CM02 bit in the CM0 register is set to 0 (do not stop the peripheral function clock in wait mode), the I^2C bus interface circuit can receive address data in WAIT mode. However, the I^2C bus interface circuit is not operated in STOP mode or in low power consumption mode, because the I^2C bus system clock V_{IIC} is not supplied.

16.7 I2C0 Control Register 2 (S4D0 Register)

The S4D0 register controls the error communication detection.

If the SCL clock is stopped counting dring data transfer, each device is stopped, staying online. To avoid the situation, the I2C bus interface circuit has a function to detect the time-out when the SCL clock is stopped in high-level ("H") state for a specific period, and to generate an I2C bus interface interrupt request. See **Figure 16.13**.

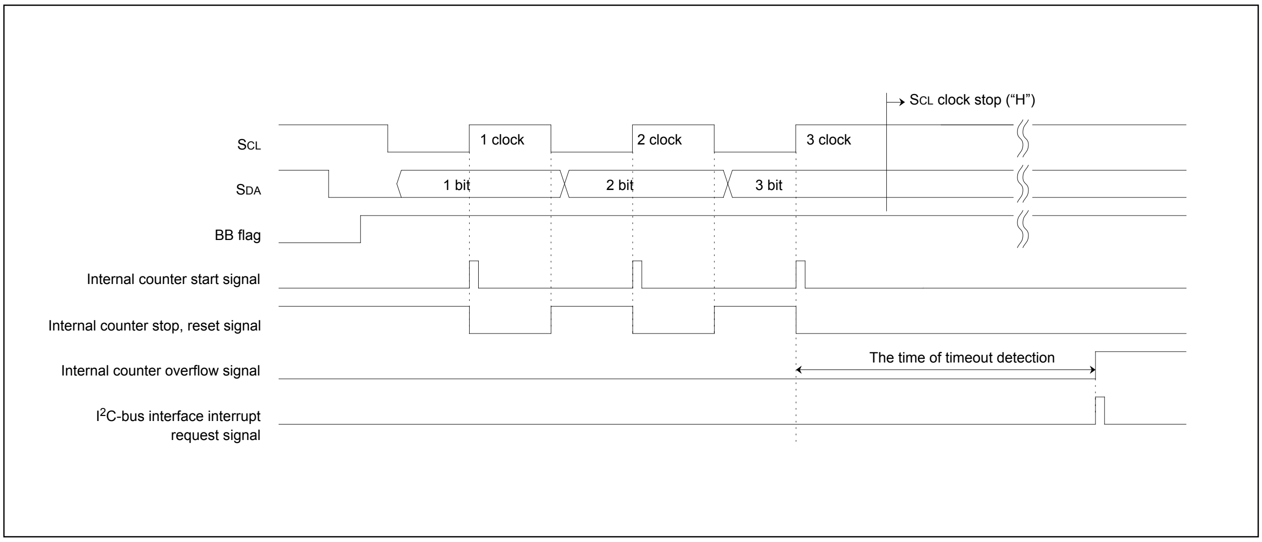


Figure 16.13 The timing of time-out detection

16.7.1 Bit0: Time-Out Detection Function Enable Bit (TOE)

The TOE bit enables the time-out detection function. When the TOE bit is set to 1, time-out is detected and the I^2C bus interface interrupt request is generated when the following conditions are met.

1) the BB flag in the S10 register is set to 1 (bus busy)
2) the SCL clock stops for time-out detection period while high-level ("H") signal is maintained (see **Table 16.7**)

The internal counter measures the time-out detection time and the TOSEL bit selects between two modes, long time and short time. When time-out is detected, set the ES0 bit to 0 (I^2C bus interface disabled) and reset the counter.

16.7.2 Bit1: Time-Out Detection Flag (TOF)

The TOF flag indicates the time-out detection. If the internal counter which measures the time-out period overflows, the TOF flag is set to 1 and the I^2C bus interface interrupt request is generated at the same time.

16.7.3 Bit2: Time-Out Detection Period Select Bit (TOSEL)

The TOSEL bit selects time-out detection period from long time mode and short time mode. When the TOSEL bit is set to 0, long time mode is selected. When it is set to 1, short time mode is selected, respectively. The internal counter increments as a 16-bit counter in long time mode, while the counter increments as a 14-bit counter in short time mode, based on the I^2C system clock (VIIC) as a counter source. **Table 16.7** shows examples of time-out detection period.

Table 16.7 Examples of Time-out Detection Period (Unit: ms)

VIIC(MHz)	Long time mode	Short time mode
4	16.4	4.1
2	32.8	8.2
1	65.6	16.4

16.7.4 Bits 3,4,5: I^2C System Clock Select Bits (ICK2-4)

Bits ICK4 to ICK2, and bits ICK1 and ICK0 in the S3D0 register, and the PCLK0 bit in the PCLKR register select the system clock (VIIC) of the I^2C bus interface circuit. See **Table 16.6** for the setting values.

16.7.5 Bit7: STOP Condition Detection Interrupt Request Bit (SCPIN)

The SCPIN bit monitors the stop condition detection interrupt. The SCPIN bit is set to 1 when the I^2C bus interface interrupt is generated by detecting the STOP condition. When this bit is set to 0 by program, it becomes 0. However, no change occurs even if it is set to 1.

16.8 I2C0 START/STOP Condition Control Register (S2D0 Register)

The S2D0 register controls the START/STOP condition detections.

16.8.1 Bit0-Bit4: START/STOP Condition Setting Bits (SSC0-SSC4)

The SCL release time and the set-up and hold times are mesured on the base of the I2C bus system clock (V_{IIC}). Therefore, the detection conditions changes, depending on the oscillation frequency (X_{IN}) and the I2C bus system clock select bits. It is necessary to set bits SSC4 to SSC0 to the appropriate value to set the SCL release time, the set-up and hold times by the system clock frequency (See **Table 16.10**). Do not set odd numbers or 00000_2 to bits SSC4 to SSC0. **Table 16.2** shows the reference value to bits SSC4 to SSC0 at each oscillation frequency in standard clock mode. The detection of START/STOP conditions starts immediately after the ES0 bit in the S1D0 register is set to 1 (I2C bus interface enabled).

16.8.2 Bit5: SCL/SDA Interrupt Pin Polarity Select Bit (SIP)

The The SIP bit detect the rising edge or the falling edge of the SCL_{MM} or SDA_{MM} to generate SCL/SDA interrupts. The SIP bit selects the polarity of the SCL_{MM} or the SDA_{MM} for interrupt.

16.8.3 Bit6 : SCL/SDA Interrupt Pin Select Bit (SIS)

The SIS bit selects a pin to enable SCL/SDA interrupt.

NOTE:

1. The SCL/SDA interrupt request may be set when changing the SIP, SIS and ES0 bit settings in the S1D0 register. When using the SCL/SDA interrupt, set the above bits, while the SCL/SDA interrupt is disabled. Then, enable the SCL/SDA interrupt after setting the SCL/SDA bit in the IR register to 0.

16.8.4 Bit7: START/STOP Condition Generation Select Bit (STSPSEL)

The STSPSEL bit selects the set-up/hold times, based on the I2C system clock cycles, when the START/ STOP condition is generated (See **Table 16.8**). Set the STSPSEL bit to 1 if the I2C bus system clock frequency is over 4MHz.

16.9 START Condition Generation Method

Set the MST bit, TRX bit and BB flags in the S10 register to 1 and set the PIN bit and 4 low-order bits in the S10 register to 0 simultaneously, to enter START condition standby mode, when the ES0 bit in the S1D0 register is set to 1 (I^2C bus interface enabled) and the BB flag is set to 0 (bus free). When the slave address is written to the S00 register next, START condition is generated and the bit counter is reset to 000_2 and 1-byte SCL signal is output. The START condition generation timing varies between standard clock mode and high-speed clock mode. See **Figure 16.16 and Table 16.8**.

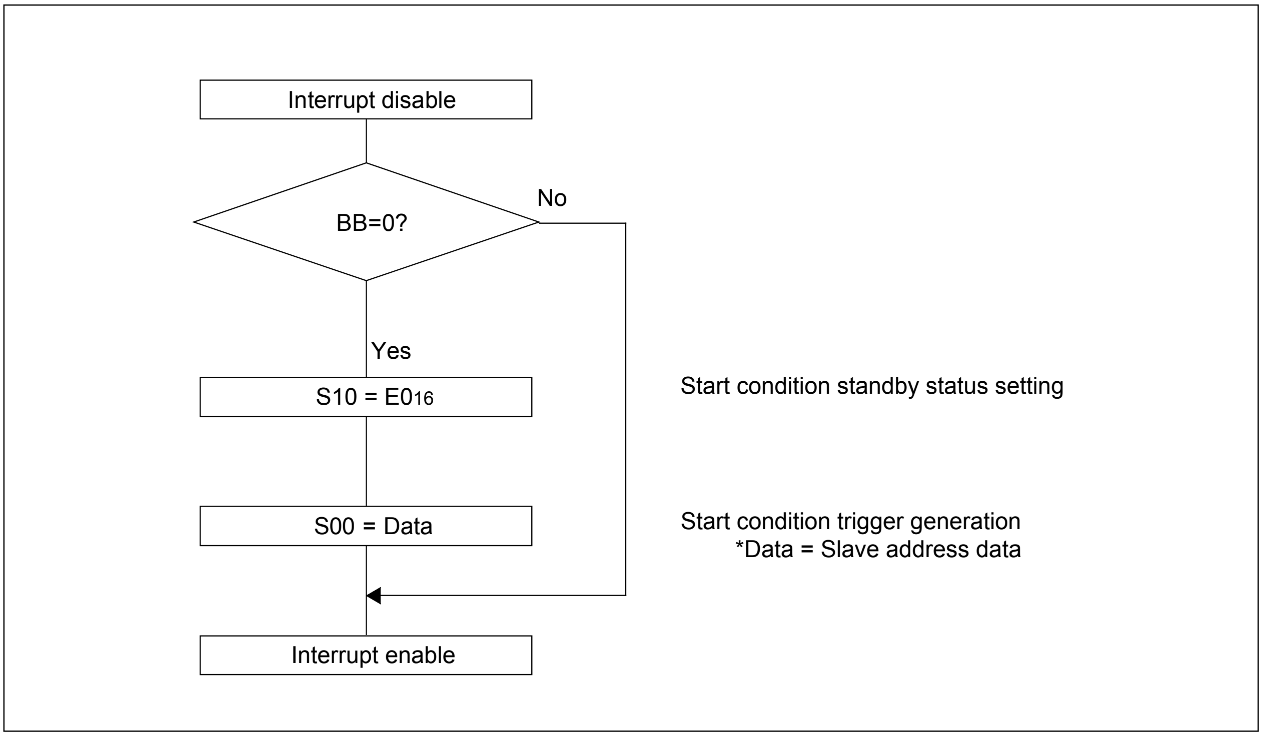


Figure 16.14 Start condition generation flow chart

16.10 START Condition Duplicate Protect Function

A START condition is generated when verifying that the BB flag in the S10 register does not use buses. However, if the BB flag is set to 1 (bus busy) by the START condition which other master device generates immediately after the BB flag is verified, the START condition is suspended by the START condition duplicate protect function. When the START condition duplicate protect function starts, it operates as follows:

•Disable the start condition standby setting
If the function has already been set, first exit START condition standby mode and then set bits MST and TRX in the S10 register to 0.

•Writing to the S00 register is disabled. (The START condition trigger generation is disabled)

•If the START condition generation is interrupted, the AL flag in the S10 register becomes 1.(arbitration lost detection)

The START condition duplicate protect function is valid between the SDA falling edge of the START condition and the receive completion of the slave address. **Figure16.15** shows the duration of the START condition duplicate protect function.

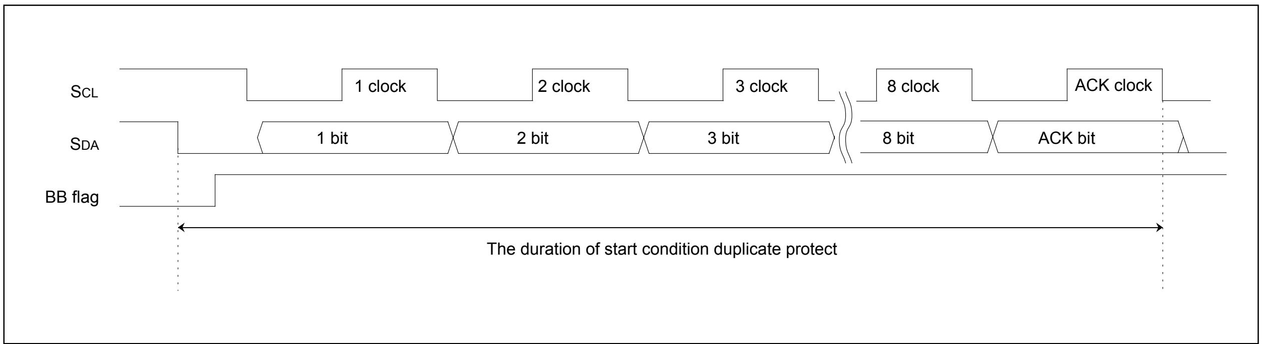


Figure 16.15 The duration of the start condition duplicate protect function

16.11 STOP Condition Generation Method

When the ES0 bit in the S1D0 register is set to 1 (I^2C bus interface enabled) and bits MST and TRX in the S10 register are set to 1 at the same time, set the BB flag, PIN bit and 4 low-order bits in the S10 register to 0 simultaneously, to enter STOP condition standby mode. When dummy data is written to the S00 register next, the STOP condition is generated. The STOP condition generation timing varies between standard clock mode and high-speed clock mode. See **Figure 16.17** and **Table 16.8**.

Until the BB flag in the S10 register becomes 0 (bus free) after an instruction to generate the STOP condition is executed, do not write data to registers S10 and S00. Otherwise, the STOP condition waveform may not be generated correctly.

If an input signal level of the SCL pin is set to low ("L") after the instruction to generate the STOP condition is executed, a signal level of the SCL pin becomes high ("H"), and the BB flag is set to 0 (bus free), the MCU outputs an "L" signal to SCL pin.

In that case, the MCU can stop an "L" signal output to the SCL pin by generating the STOP condition, writing 0 to the ES0 bit in the S1D0 register (disabled), or writing 1 to the IHR bit in the S1D0 register (reset release).

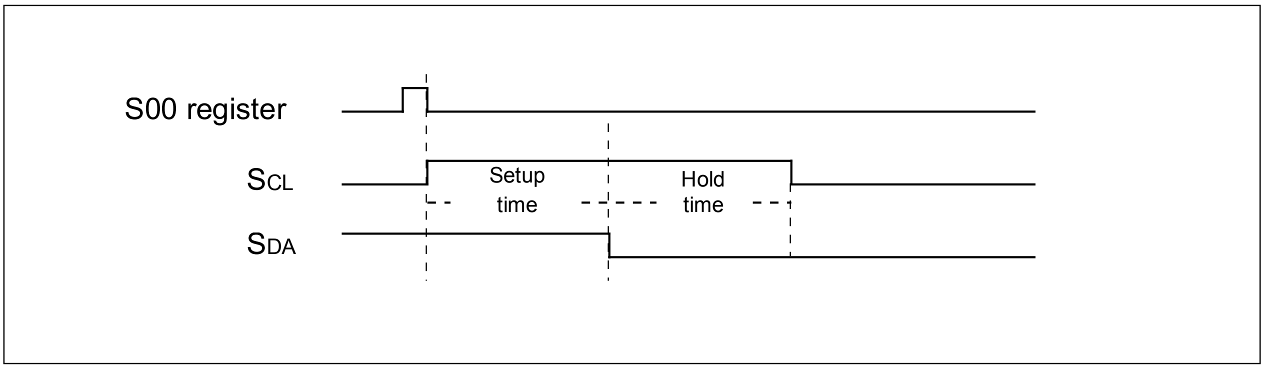


Figure 16.16 Start condition generation timing diagram

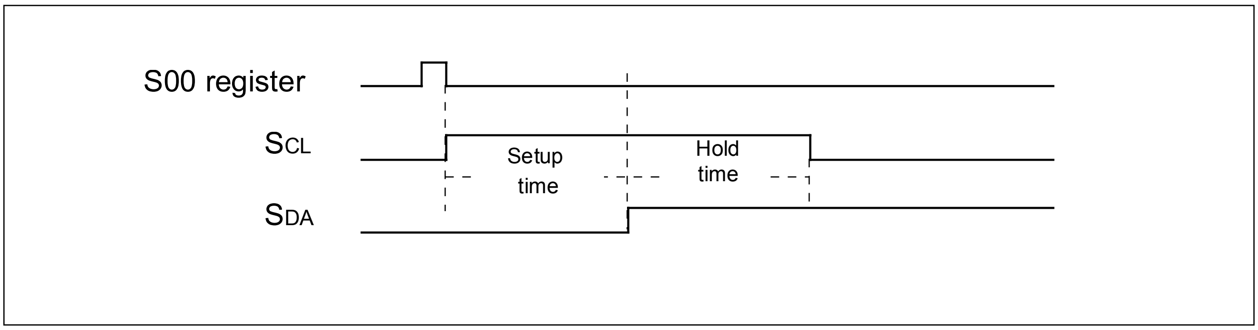


Figure 16.17 Stop condition generation timing diagram

Table 16.8 Start/Stop generation timing table

	Start/Stop Condition Generation Select Bit	Standard Clock Mode	High-speed Clock Mode
Setup time	0	5.0 μs (20 cycles)	2.5 μs (10 cycles)
	1	13.0 μs (52 cycles)	6.5 μs (26 cycles)
Hold time	0	5.0 μs (20 cycles)	2.5 μs (10 cycles)
	1	13.0 μs (52 cycles)	6.5 μs (26 cycles)

N OTE:
1. Actual time at the time of VIIC = 4MHz, The contents in () denote cycle numbers.

As mentioned above, when bits MST and TRX are set to 1, START condition or STOP condition mode is entered by writing 1 or 0 to the BB flag in the S10 register and writing 0 to the PIN bit and 4 low-order bits in the S10 register at the same time. Then SDAMM is left open in the START condition standby mode and SDAMM is set to low-level ("L") in the STOP condition standby mode. When the S00 register is set, the START/STOP conditions are generated. In order to set bits MST and TRX to 1 without generating the START/STOP conditions, write 1 to the 4 low-order bits simultaneously. **Table 16.9** lists functions along with the S10 register settings.

Table 16.9 S10 Register Settings and Functions

S10 Register Settings								Function
MST	TRX	BB	PIN	AL	AAS	AS0	LRB	
1	1	1	0	0	0	0	0	Setting up the START condition stand by in master transmit mode
1	1	0	0	0	0	0	0	Setting up the STOP condition stand by in master transmit mode
0/1	0/1	-	0	1	1	1	1	Setting up each communication mode (refer to **16.5 I²C status register**)

16.12 START/STOP Condition Detect Operation

Figure 16.18, **Figure 16.19** and **Table 16.10** show START/STOP condition detect operations. Bits SSC4 to SSC0 in the S2D0 register set the START/STOP conditions. The START/STOP condition can be detected only when the input signal of the SCLMM and SDAMM met the following conditions: the SCL release time, the set-up time, and the hold time (see **Table 16.10**). The BB flag in the S10 register is set to 1 when the START condition is detected and it is set to 0 when the STOP condition is detected. The BB flag set and reset timing varies between standard clock mode and high-speed clock mode. See **Table 16.10**.

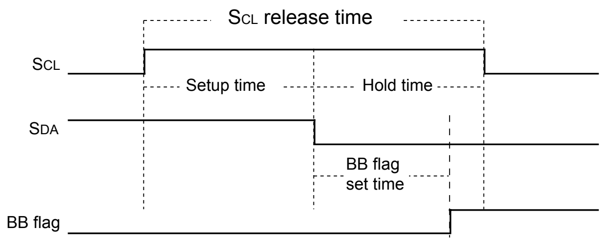


Figure 16.18 Start condition detection timing diagram

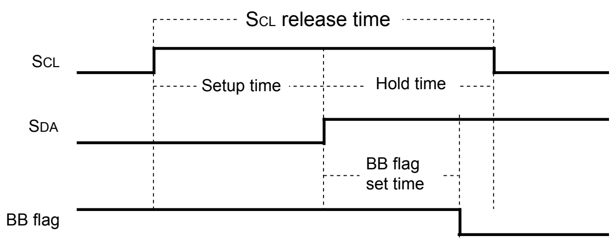


Figure 16.19 Stop condition detection timing diagram

Table 16.10 Start/Stop detection timing table

	Standard clock mode	High-speed clock mode
SCL release time	SSC value + 1 cycle (6.25µs)	4 cycles (1.0µs)
Setup time	$\frac{\text{SSC value}}{2}$ + 1 cycle < 4.0µs (3.25µs)	2 cycles (0.5µs)
Hold time	$\frac{\text{SSC value}}{2}$ cycle < 4.0µs (3.0µs)	2 cycles (0.5µs)
BB flag set/reset time	$\frac{\text{SSC value - 1}}{2}$ +2 cycles (3.375µs)	3.5 cycles (0.875µs)

NOTE:
1. Unit : number of cycle for I2C system clock VIIC
The SSC value is the decimal notation value of bits SSC4 to SSC0. Do not set 0 or odd numbers to the SSC setting. The values in ( ) are examples when the S2D0 register is set to 18_{16} at VIIC = 4 MHz.

16.13 Address Data Communication

This section describes data transmit control when a master transferes data or a slave receives data in 7-bit address format. **Figure 16.20 (1)** shows a master transmit format.

(1) A master transmit device transmits data to a receive device

S	Slave address	R/$\overline{W}$	A	Data	A	Data	A/$\overline{A}$	P
	7 bits	0		1 - 8 bits		1 - 8 bits		

(2) A master receive device receives data from a transmit device

S	Slave address	R/$\overline{W}$	A	Data	A	Data	$\overline{A}$	P
	7 bits	1		1 - 8 bits		1 - 8 bits		

S: START condition   P: STOP condition
A: ACK bit   R/$\overline{W}$: Read/$\overline{Write}$ bit

Figure 16.20 Address data communication format

16.13.1 Example of Master Transmit

For example, a master transmits data as shown below when following conditions are met: standard clock mode, SCL clock frequency of 100kHz and ACK clock added.

1) Set s slave address to the 7 high-order bits in the S0D0 register
2) Set 85_{16} to the S20 register, 000_2 to bits ICK4 to ICK2 in the S4D0 register and 00_{16} to the S3D0 registe to generate an ACK clock and set SCL clock frequency t 100 kHz (f_1=8MHz, f_{IIC}=f1)
3) Set 00_{16} to the S10 register to reset transmit/receive
4) Set 08_{16} to the S1D0 register to enable data communication
5) Confirm whether the bus is free by BB flag setting in the S10 register
6) Set $E0_{16}$ to the S10 register to enter START condition standby mode
7) Set the destination address in 7 high-order bits and 0 to a least significant bit in the S00 register to generate START condition. At this time, the first byte consisting of SCL and ACK clock are automatically generated
8) Set a transmit data to the S00 register. At this time, SCL and an ACK clock are automatically generated
9) When transmitting more than 1-byte control data, repeat the above step 8).
10) Set $C0_{16}$ in the S10 register to enter STOP condition standby mode if ACK is not returned from the slave receiver or if the transmit is completed
11) Write dummy data to the S00 regiser to generate STOP condition

16.13.2 Example of Slave Receive

For example, a slave receives data as shown below when following conditions are met: high-speed clock mode, SCL frequency of 400 kHz, ACK clock added and addressing format.

1) Set a slave address in the 7 high-order bits in the S0D0 register
2) Set $A5_{16}$ to the S20 register, 000_2 to bits ICK4 to ICK2 in the S4D0 register, and 00_{16} to the S3D0 register to generate an ACK clock and set SCL clock frequency at 400kHz (f_1 = 8 MHz, $f_{IIC} = f_1$)
3) Set 00_{16} to the S10 register to reset transmit/receive mode
4) Set 08_{16} to the S1D0 register to enable data communication
5) When a START condition is received, addresses are compared
6) •When the transmitted addresses are all 0 (general call), the ADR0 bit in the S10 register is set to 1 and an I^{2}C bus interface interrupt request signal is generated.
   •When the transmitted addresses match with the address set in 1), the ASS bit in the S10 register is set to 1 and an I^{2}C bus interface interrupt request signal is generated.
   •In other cases, bits ADR0 and AAS are set to 0 and I^{2}C bus interface interrupt request signal is not generated.
7) Write dummy data to the S00 register.
8) After receiving 1-byte data, an ACK-CLK bit is automatically returned and an I^{2}C bus interface interrupt request signal is generated.
9) To determine whether the ACK should be returned depending on contents in the received data, set dummy data to the S00 register to receive data after setting the WIT bit in te S3D0 register to 1 (enable the I^{2}C bus interface interrupt of data receive completion). Because the I^{2}C bus interface interrupt is generated when the 1-byte data is received, set the ACKBIT bit to 1 or 0 to output a signal from the ACKBIT bit.
10) When receiving more than 1-byte control data, repeat steps 7) and 8) or 7) and 9).
11) When a STOP condition is detected, the communication is ended.

16.14 Precautions

(1) Access to the registers of I^{2}C bus interface circuit

The following is precautions when read or write the control registers of I^{2}C bus interface circuit

•S00 register

Do not rewrite the S00 register during data transfer. If the bits in the S00 register are rewritten, the bit counter for transfer is reset and data may not be transferred successfully.

•S1D0 register

Bits BC2 o BC0 are set to 000_2 when START condition is detected or when 1-byte data transfer is completed. Do not read or write the S1D0 register at this timing. Otherwise, data may be read or written unsuccessfully. **Figure 16.22** and **Figure 16.23** show the bit counter reset timing.

•S20 register

Do not rewrite the S20 register except the ACKBIT bit during transfer. If the bits in the S20 register except ACKBIT bit are rewritten, the I^{2}C bus clock circuit is reset and data may be transferred incompletely.

•S3D0 register

Rewrite bits ICK4 to ICK0 in the S3D0 register when the ES0 bit in the S1D0 register is set to 0 (I^{2}C bus interface is disabled). When the WIT bit is read, the internal WAIT flag is read. Therefore, do not use the bit managing instruction(read-modify-write instruction) to access the S3D0 register.

•S10 register

Do not use the bit managing instruction (read-modify-write instruction) because all bits in the S10 register will be changed, depending on the communication conditions. Do not read/write when te communication mode select bits, bits MST and TRX, are changing their value. Otherwise, data may be read or written unsuccessfully. **Figure16.21** to **Figure 16.23** show the timing when bits MST and TRX change.

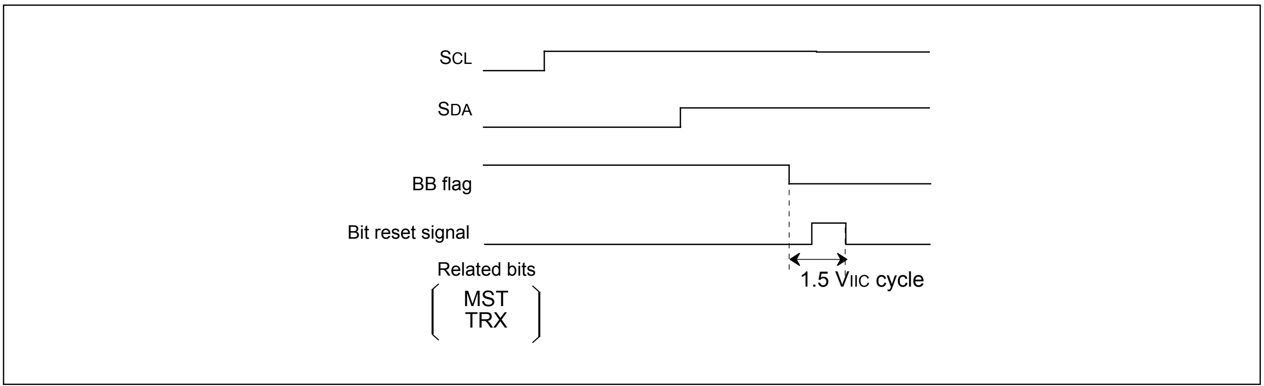


Figure 16.21 The bit reset timing (The STOP condition detection)

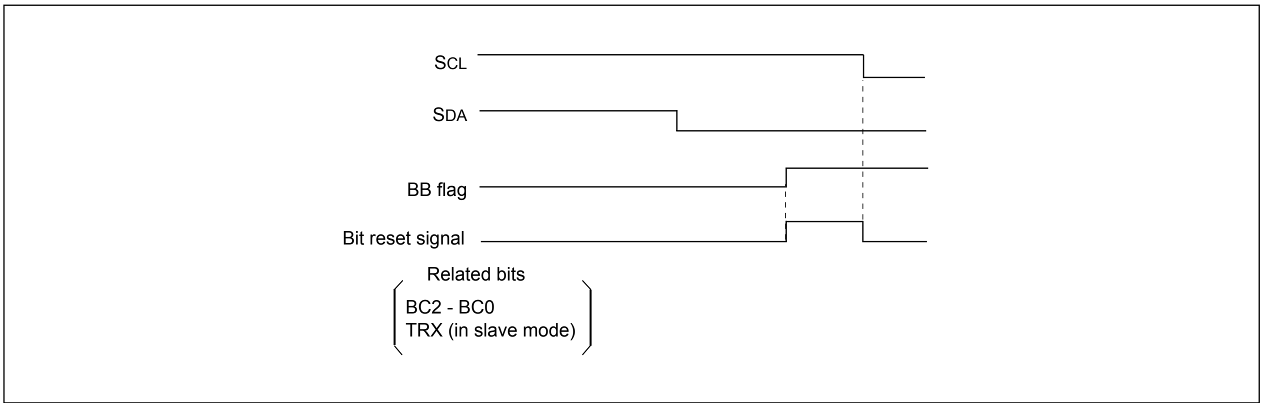


Figure 16.22 The bit reset timing (The START condition detection)

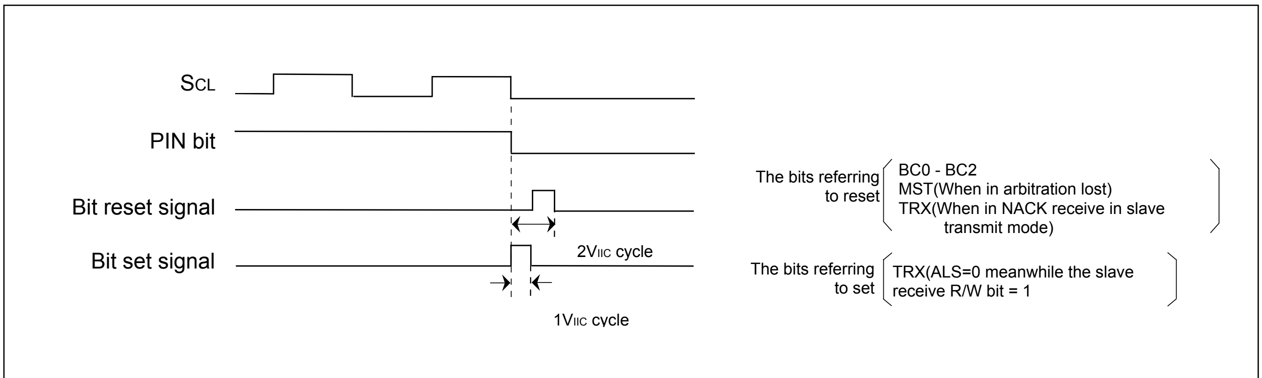


Figure 16.23 Bit set/reset timing (at the completion of data transfer)

(2) Generation of RESTART condition

In order to generate a RESTART condition after 1-byte data transfer, write $E0_{16}$ to the S10 register, enter START condition standby mode and leave the SDA_{MM} open. Generate a START condition trigger by setting the S00 register after inserting a sufficient software wait until the SDA_{MM} outputs a high-level ("H") signal. **Figure 16.24** shows the RESTART condition generation timing.

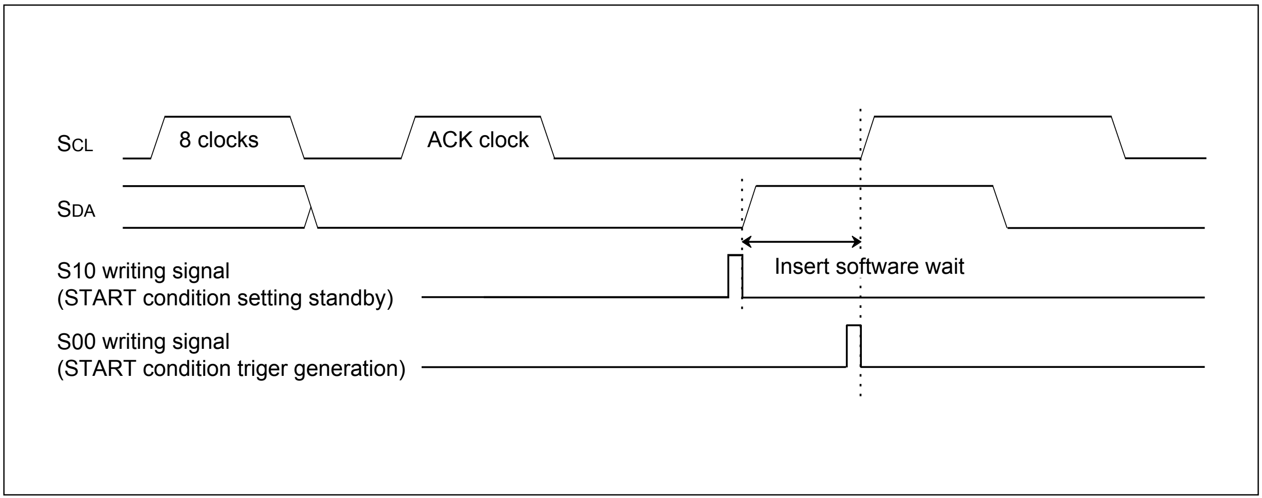


Figure 16.24 The time of generation of RESTART condition

(3) limitation of CPU clock

When the CM07 bit in the CM0 register is set to 1 (subclock), each register of the I2C bus interface circuit cannot be read or written. Read or write data when the CM07 bit is set to 0 (main clock, PLL clock, or on-chip oscillator clock).

17. CAN Module

The CAN (Controller Area Network) module for the M16C/29 Group of MCUs is a communication controller implementing the CAN 2.0B protocol. The M16C/29 Group contains one CAN module which can transmit and receive messages in both standard (11-bit) ID and extended (29-bit) ID formats.

Figure 17.1 shows a block diagram of the CAN module.

External CAN bus driver and receiver are required.

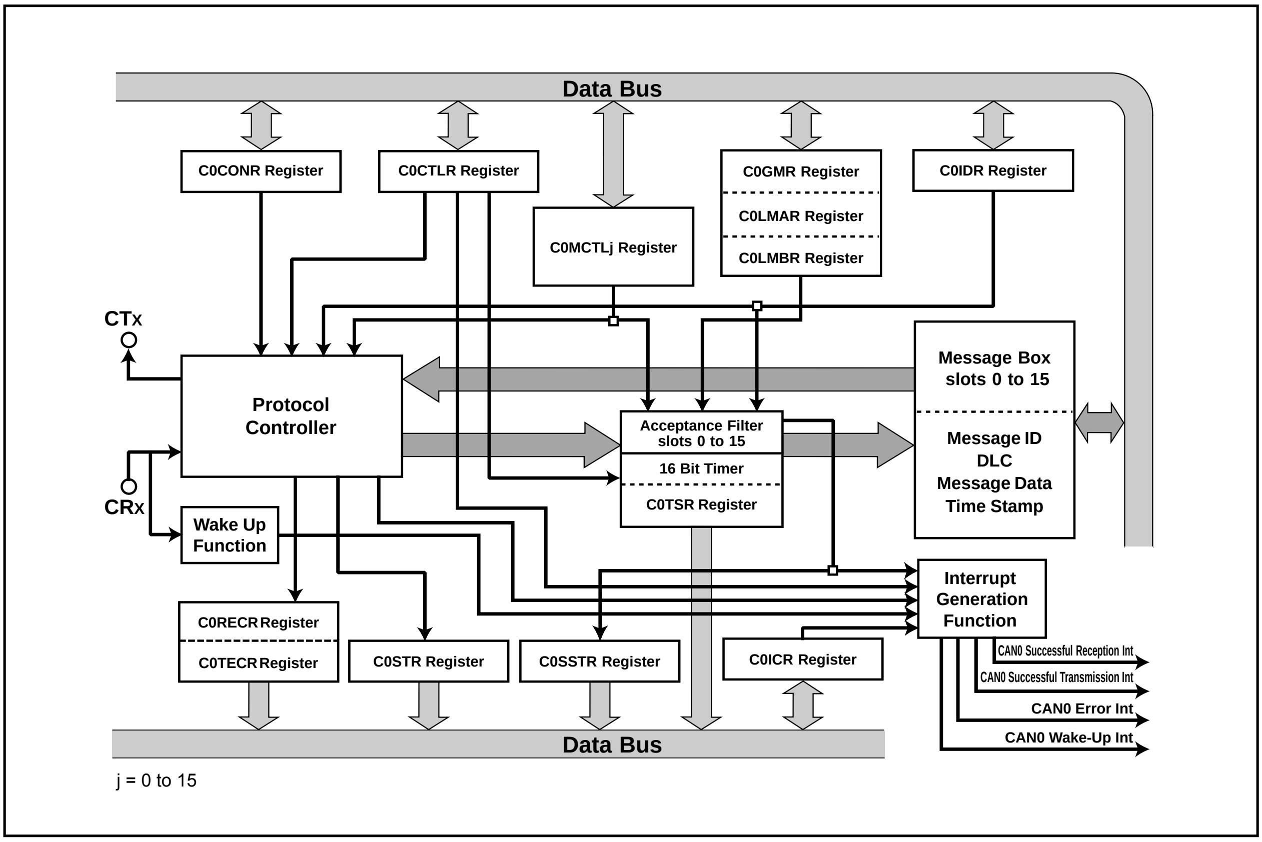


Figure 17.1 Block Diagram of CAN Module

CTx/CRx:	CAN I/O pins.
Protocol controller:	This controller handles the bus arbitration and the CAN protocol services, i.e. bit timing, stuffing, error status etc.
Message box:	This memory block consists of 16 slots that can be configured either as transmitter or receiver. Each slot contains an individual ID, data length code, a data field (8 bytes) and a time stamp.
Acceptance filter:	This block performs filtering operation for received messages. For the filtering operation, the C0GMR register, the C0LMAR register, or the C0LMBR register is used.
16 bit timer:	Used for the time stamp function. When the received message is stored in the message memory, the timer value is stored as a time stamp.
Wake-up function:	CAN0 wake-up interrupt request is generated by a message from the CAN bus.
Interrupt generation function:	The interrupt requests are generated by the CAN module. CAN0 successful reception interrupt, CAN0 successful transmission interrupt, CAN0 error interrupt and CAN0 wake-up interrupt.

17.1 CAN Module-Related Registers

The CAN0 module has the following registers.

(1) CAN Message Box

A CAN module is equipped with 16 slots (16 bytes or 8 words each). Slots 14 and 15 can be used as Basic CAN.

- Priority of the slots: The smaller the number of the slot, the higher the priority, in both transmission and reception.
- A program can define whether a slot is defined as transmitter or receiver.

(2) Acceptance Mask Registers

A CAN module is equipped with 3 masks for the acceptance filter.

- CAN0 global mask register (C0GMR register: 6 bytes)
  Configuration of the masking condition for acceptance filtering processing to slots 0 to 13
- CAN0 local mask A register (C0LMAR register: 6 bytes)
  Configuration of the masking condition for acceptance filtering processing to slot 14
- CAN0 local mask B register (C0LMBR register: 6 bytes)
  Configuration of the masking condition for acceptance filtering processing to slot 15

(3) CAN SFR Registers

- CAN0 message control register j (C0MCTLj register: 8 bits × 16) (j = 0 to 15)
  Control of transmission and reception of a corresponding slot
- CANi control register (CiCTLR register: 16 bits) (i = 0, 1)
  Control of the CAN protocol
- CAN0 status register (C0STR register: 16 bits)
  Indication of the protocol status
- CAN0 slot status register (C0SSTR register: 16 bits)
  Indication of the status of contents of each slot
- CAN0 interrupt control register (C0ICR register: 16 bits)
  Selection of “interrupt enabled or disabled” for each slot
- CAN0 extended ID register (C0IDR register: 16 bits)
  Selection of ID format (standard or extended) for each slot
- CAN0 configuration register (C0CONR register: 16 bits)
  Configuration of the bus timing
- CAN0 receive error count register (C0RECR register: 8 bits)
  Indication of the error status of the CAN module in reception: the counter value is incremented or decremented according to the error occurrence.
- CAN0 transmit error count register (C0TECR register: 8 bits)
  Indication of the error status of the CAN module in transmission: the counter value is incremented or decremented according to the error occurrence.
- CAN0 time stamp register (C0TSR register: 16 bits)
  Indication of the value of the time stamp counter
- CAN0 acceptance filter support register (C0AFS register: 16 bits)
  Decoding the received ID for use by the acceptance filter support unit

Explanation of each register is given as follows.

17.1.1 CAN0 Message Box

Table 17.1 shows the memory mapping of the CAN0 message box.
It is possible to access to the message box in byte or word.
Mapping of the message contents differs from byte access to word access. Byte access or word access can be selected by the MsgOrder bit of the C0CTLR register.

Table 17.1 Memory Mapping of CAN0 Message Box

Address	Message content (Memory mapping)	
	Byte access (8 bits)	Word access (16 bits)
0060_{16} + n • 16 + 0	SID_{10} to SID_6	SID_5 to SID_0
0060_{16} + n • 16 + 1	SID_5 to SID_0	SID_{10} to SID_6
0060_{16} + n • 16 + 2	EID_{17} to EID_{14}	EID_{13} to EID_6
0060_{16} + n • 16 + 3	EID_{13} to EID_6	EID_{17} to EID_{14}
0060_{16} + n • 16 + 4	EID_5 to EID_0	Data Length Code (DLC)
0060_{16} + n • 16 + 5	Data Length Code (DLC)	EID_5 to EID_0
0060_{16} + n • 16 + 6	Data byte 0	Data byte 1
0060_{16} + n • 16 + 7 ⋮ 0060_{16} + n • 16 + 13	Data byte 1 ⋮ Data byte 7	Data byte 0 ⋮ Data byte 6
0060_{16} + n • 16 + 14	Time stamp high-order byte	Time stamp low-order byte
0060_{16} + n • 16 + 15	Time stamp low-order byte	Time stamp high-order byte

n = 0 to 15: the number of the slot

Figures 17.2 and **17.3** show the bit mapping in each slot in byte access and word access. The content of each slot remains unchanged unless transmission or reception of a new message is performed.

bit 7							bit 0
			SID$_{10}$	SID$_{9}$	SID$_{8}$	SID$_{7}$	SID$_{6}$
		SID$_{5}$	SID$_{4}$	SID$_{3}$	SID$_{2}$	SID$_{1}$	SID$_{0}$
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$
EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_{9}$	EID$_{8}$	EID$_{7}$	EID$_{6}$
		EID$_{5}$	EID$_{4}$	EID$_{3}$	EID$_{2}$	EID$_{1}$	EID$_{0}$
				DLC$_{3}$	DLC$_{2}$	DLC$_{1}$	DLC$_{0}$
Data Byte 0							
Data Byte 1							
⋮							
Data Byte 7							
Time Stamp high-order byte							
Time Stamp low-order byte							

CAN Data Frame:

SID$_{10 \text{ to } 6}$	SID$_{5 \text{ to } 0}$	EID$_{17 \text{ to } 14}$	EID$_{13 \text{ to } 6}$	EID$_{5 \text{ to } 0}$	DLC$_{3 \text{ to } 0}$	Data Byte 0	Data Byte 1	--------------	Data Byte 7

NOTE:

1. When is read, the value is the one written upon the transmission slot configuration.
 The value is 0 when read on the reception slot configuration.

Figure 17.2 Bit Mapping in Byte Access

bit 15							bit 8	bit 7							bit 0
			SID$_{10}$	SID$_{9}$	SID$_{8}$	SID$_{7}$	SID$_{6}$			SID$_{5}$	SID$_{4}$	SID$_{3}$	SID$_{2}$	SID$_{1}$	SID$_{0}$
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_{9}$	EID$_{8}$	EID$_{7}$	EID$_{6}$
		EID$_{5}$	EID$_{4}$	EID$_{3}$	EID$_{2}$	EID$_{1}$	EID$_{0}$					DLC$_{3}$	DLC$_{2}$	DLC$_{1}$	DLC$_{0}$

Data Byte 0	Data Byte 1
Data Byte 2	Data Byte 3
Data Byte 4	Data Byte 5
Data Byte 6	Data Byte 7
Time Stamp high-order byte	Time Stamp low-order byte

CAN Data Frame:

SID$_{10 \text{ to } 6}$	SID$_{5 \text{ to } 0}$	EID$_{17 \text{ to } 14}$	EID$_{13 \text{ to } 6}$	EID$_{5 \text{ to } 0}$	DLC$_{3 \text{ to } 0}$	Data Byte 0	Data Byte 1	--------------	Data Byte 7

NOTE:

1. When is read, the value is the one written upon the transmission slot configuration.
 The value is "0" when read on the reception slot configuration.

Figure 17.3 Bit Mapping in Word Access

17.1.2 Acceptance Mask Registers

Figures 17.4 and **17.5** show the C0GMR register, the C0LMAR register, and the C0LMBR register, in which bit mapping in byte access and word access are shown.

bit 7							bit 0	Addresses CAN0	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$	0160$_{16}$	C0GMR register
		SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	0161$_{16}$	
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	0162$_{16}$	
EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	0163$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$	0164$_{16}$	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$	0166$_{16}$	C0LMAR register
		SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	0167$_{16}$	
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	0168$_{16}$	
EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	0169$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$	016A$_{16}$	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$	016C$_{16}$	C0LMBR register
		SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	016D$_{16}$	
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	016E$_{16}$	
EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	016F$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$	0170$_{16}$	

NOTES
1. is undefined.
2. These registers can be written in CAN reset/initialization mode of the CAN module.

Figure 17.4 Bit Mapping of Mask Registers in Byte Access

bit 15							bit 8	bit 7							bit 0	Addresses CAN0	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$			SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	0160$_{16}$	C0GMR register
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	0162$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$									0164$_{16}$	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$			SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	0166$_{16}$	C0LMAR register
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	0168$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$									016A$_{16}$	
			SID$_{10}$	SID$_9$	SID$_8$	SID$_7$	SID$_6$			SID$_5$	SID$_4$	SID$_3$	SID$_2$	SID$_1$	SID$_0$	016C$_{16}$	C0LMBR register
				EID$_{17}$	EID$_{16}$	EID$_{15}$	EID$_{14}$	EID$_{13}$	EID$_{12}$	EID$_{11}$	EID$_{10}$	EID$_9$	EID$_8$	EID$_7$	EID$_6$	016E$_{16}$	
		EID$_5$	EID$_4$	EID$_3$	EID$_2$	EID$_1$	EID$_0$									0170$_{16}$	

NOTES:
1. is undefined.
2. These registers can be written in CAN reset/initialization mode of the CAN module.

Figure 17.5 Bit Mapping of Mask Registers in Word Access

17.1.3 CAN SFR Registers

17.1.3.1 C0MCTLj Register (j = 0 to 15)

Figure 17.6 shows the C0MCTLj register.

CAN0 message control register j (j = 0 to 15) (4)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
C0MCTL0 to C0MCTL15	0200_{16} to $020F_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
NewData	Successful reception flag	When set to reception slot 0: The content of the slot is read or still under processing by the CPU 1 The CAN module has stored new data in the slot	RO (1)
SentData	Successful transmission flag	When set to transmission slot 0: Transmission is not started or completed yet 1: Transmission is successfully completed	RO (1)
InvalData	"Under reception" flag	When set to reception slot 0: The message is valid 1: The message is invalid (The message is being updated)	RO
TrmActive	"Under transmission" flag	When set to transmission slot 0: Waiting for bus idle or completion of arbitration 1: Transmitting	RO
MsgLost	Overwrite flag	When set to reception slot 0: No message has been overwritten in this slot 1: This slot already contained a message, but it has been overwritten by a new one	RO (1)
RemActive	Remote frame transmission/ reception status flag (2)	0: Data frame transmission/reception status 1: Remote frame automatic transfer status	RW
RspLock	Auto response lock mode select bit	When set to reception remote frame slot 0: After a remote frame is received, it will be answered automatically 1: After a remote frame is received, no transmission will be started as long as this bit is set to 1 (Not responding)	RW
Remote	Remote frame corresponding slot select bit	0: Slot not corresponding to remote frame 1: Slot corresponding to remote frame	RW
RecReq	Reception slot request bit (3)	0: Not reception slot 1: Reception slot	RW
TrmReq	Transmission slot request bit (3)	0: Not transmission slot 1: Transmission slot	RW

NOTES:
1. As for write, only writing 0 is possible. The value of each bit is written when the CAN module enters the respective state.
2. In Basic CAN mode, the slots 14 and 15 serve as data format identification flag. If the data frame is received, the RemActive bit is set to 0. If the remote frame is received, the bit is set to 1.
3. One slot cannot be defined as reception slot and transmission slot at the same time.
4. Set these registers only when the CAN module is in CAN operating mode.

Figure 17.6 C0MCTLj Register

17.1.3.2 C0CTLR Register

Figure 17.7 shows the C0CTLR register.

CAN0 Control Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After reset
C0CTLR	0210₁₆	X00000012

Bit Symbol	Bit Name	Function	RW
Reset	CAN module reset bit (Note 1)	0: Operation mode 1: Reset/initialization mode	RW
LoopBack	Loop back mode select bit (2)	0: Loop back mode disabled 1: Loop back mode enabled	RW
MsgOrder	Message order select bit (2)	0: Word access 1: Byte access	RW
BasicCAN	Basic CAN mode select bit (2)	0: Basic CAN mode disabled 1: Basic CAN mode enabled	RW
BusErrEn	Bus error interrupt enable bit (2)	0: Bus error interrupt disabled 1: Bus error interrupt enabled	RW
Sleep	Sleep mode select bit (2, 3)	0: Sleep mode disabled 1: Sleep mode enabled; clock supply stopped	RW
PortEn	CAN port enable bit (2, 3)	0: I/O port function 1: CTx/CRx function(4)	RW
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

NOTES:
1. When the Reset bit is set to 1 (CAN reset/initialization mode), check that the State_Reset bit in the C0STR register is set to 1 (Reset mode).
2. Change this bit only in the CAN reset/initialization mode.
3. When using CAN0 wake-up interrupt, set these bits to 1.
4. When the PortEn bit is set to 1, set the PD9_2 bit in the PD9 register to 0.

(b15) (b8)
b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After reset
C0CTLR	0211₁₆	XX0X00002

Bit Symbol	Bit Name	Function	RW
TSPreScale Bit1, Bit0	Time stamp prescaler(3)	b1 b0 0 0: Period of 1 bit time 0 1: Period of 1/2 bit time 1 0: Period of 1/4 bit time 1 1: Period of 1/8 bit time	RW
TSReset	Time stamp counter reset bit(1)	0: In an idle state 1: Force reset of the time stamp counter	RW
RetBusOff	Return from bus off command bit(2)	0: In an idle state 1: Force return from bus off	RW
— (b4)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
RXOnly	Listen-only mode select bit (3)	0: Listen-only mode disabled 1: Listen-only mode enabled (4)	RW
— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

NOTES:
1. When the TSReset bit is set to 1, the C0TSR register is set to 0000₁₆. After this, the bit is automatically set to 0.
2. When the RetBusOff bit is set to 1, registers C0RECR and C0TECR are set to 00₁₆. After this, the bit is automatically set to 0.
3. Change this bit only in the CAN reset/initialization mode.
4. When the listen-only mode is selected, do not request the transmission.

Figure 17.7 C0CTLR Register

17.1.3.3 C0STR Register

Figure 17.8 shows the C0STR register.

CAN0 Status Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
C0STR	0212_{16}	00_{16}

Bit Symbol	Bit Name	Function	RW
MBOX	Active slot bits(1)	b3 b2 b1 b0 0 0 0 0: Slot 0 0 0 0 1: Slot 1 0 0 1 0: Slot 2 : 1 1 1 0: Slot 14 1 1 1 1: Slot 15	RO
TrmSucc	Successful transmission flag(1)	0: No [successful] transmission 1: The CAN module has transmitted a message successfully	RO
RecSucc	Successful reception flag(1)	0: No [successful] reception 1: CAN module received a message successfully	RO
TrmState	Transmission flag (Transmitter)	0: CAN module is idle or receiver 1: CAN module is transmitter	RO
RecState	Reception flag (Receiver)	0: CAN module is idle or transmitter 1: CAN module is receiver	RO

NOTE:
1. These bits can be changed only when a slot which an interrupt is enabled by the C0ICR register is transmitted or received successfully.

(b15) b7 b6 b5 b4 b3 b2 b1 b0 (b8)

Symbol	Address	After Reset
C0STR	0213_{16}	$X0000001_2$

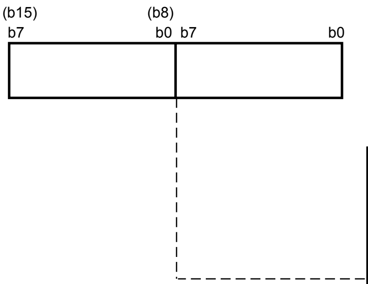
Bit Symbol	Bit Name	Function	RW
State_Reset	Reset state flag	0: Operation mode 1: Reset mode	RO
State_LoopBack	Loop back state flag	0: Loop back mode disabled 1: Loop back mode enabled	RO
State_MsgOrder	Message order state flag	0: Word access 1: Byte access	RO
State_BasicCAN	Basic CAN mode state flag	0: Basic CAN mode disabled 1: Basic CAN mode enabled	RO
State_BusError	Bus error state flag	0: No error has occurred. 1: A CAN bus error has occurred.	RO
State_ErrPass	Error passive state flag	0: The CAN module is not in error passive state. 1: The CAN module is in error passive state.	RO
State_BusOff	Error bus off state flag	0: The CAN module is not in error bus off state. 1: The CAN module is in error bus off state.	RO
— (b7)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—

Figure 17.8 C0STR Register

17.1.3.4 C0SSTR Register

Figure 17.9 shows the C0SSTR register.

CAN0 Slot Status Register



Symbol	Address	After Reset
C0SSTR	0215_{16}, 0214_{16}	0000_{16}

Function	Setting Values	RW
Slot status bits Each bit corresponds to the slot with the same number	0: Reception slot The message has been read. Transmission slot Transmission is not completed. 1: Reception slot The message has not been read. Transmission slot Transmission is completed	RO

Figure 17.9 C0SSTR Register

17.1.3.5 C0ICR Register

Figure 17.10 shows the C0ICR register.

CAN0 Interrupt Control Register (1)

(b15) b7 (b8) b0 b7 b0

Symbol	Address	After Reset
C0ICR	0217_{16}, 0216_{16}	0000_{16}

Function	Setting Values	RW
Interrupt enable bits: Each bit corresponds with a slot with the same number. Enabled/disabled of successful transmission interrupt or successful reception interrupt can be selected	0: Interrupt disabled 1: Interrupt enabled	RW

NOTE:
1. Set the C0ICR register only when the CAN module is in CAN operating mode.

Figure 17.10 C0ICR Register

17.1.3.6 C0IDR Register

Figure 17.11 shows the C0IDR register.

CAN0 extended ID register (1)

(b15) b7 (b8) b0 b7 b0

Symbol	Address	After Reset
C0IDR	0219_{16}, 0218_{16}	0000_{16}

Function	Setting Values	RW
Extended ID bits: Each bit corresponds with a slot with the same number. Selection of the ID format that each slot handles	0: Standard ID 1: Extended ID	RW

NOTE:
1. Set the C0IDR register only when the CAN module is in CAN operating mode.

Figure 17.11 C0IDR Register

17.1.3.7 C0CONR Register

Figure 17.12 shows the C0CONR register.

CAN0 Configuration Register(2)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After reset
C0CONR	$021A_{16}$	Undefined

Bit symbol	Bit name	Function	RW
BRP	Prescaler division ratio select bits	b3 b2 b1 b0 0 0 0 0: Divide-by-1 of fCAN 0 0 0 1: Divide-by-2 of fCAN 0 0 1 0: Divide-by-3 of fCAN ⋮ 1 1 1 0: Divide-by-15 of fCAN 1 1 1 1: Divide-by-16 of fCAN (1)	RW
SAM	Sampling control bit	0: One time sampling 1: Three times sampling	RW
PTS	Propagation time segment control bits	b7 b6 b5 0 0 0: 1Tq 0 0 1: 2Tq 0 1 0: 2Tq ⋮ 1 1 0: 7Tq 1 1 1: 8Tq	RW

NOTES:
1. fCAN serves for the CAN clock. The period is decided by configuration of the CCLKi bits (i = 0 to 2) in the CCLKR register.
2. Set the C0CONR register only when the CAN module is in CAN reset / initialization mode.

(b15) (b8)
b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
C0CONR	$021B_{16}$	Undefined

Bit symbol	Bit name	Function	RW
PBS1	Phase buffer segment 1 control bits	b2 b1b0 0 0 0: Do not set 0 0 1: 2Tq 0 1 0: 3Tq ⋮ 1 1 0: 7Tq 1 1 1: 8Tq	RW
PBS2	Phase buffer segment 2 control bits	b5 b4 b3 0 0 0: Do not set 0 0 1: 2Tq 0 1 0: 3Tq ⋮ 1 1 0: 7Tq 1 1 1: 8Tq	RW
SJW	Resynchronization jump width control bits	b7 b6 0 0: 1Tq 0 1: 2Tq 1 0: 3Tq 1 1: 4Tq	RW

Figure 17.12 C0CONR Register

17.1.3.8 C0RECR Register

Figure 17.13 shows the C0RECR register.

CAN0 Receive Error Count Register

b7 b0

Symbol	Address	After Reset
C0RECR	$021C_{16}$	00_{16}

Function	Counter Value	RW
Reception error counting function The value is incremented or decremented according to the CAN module's error status	00_{16} to FF_{16} (1)	RO

NOTE:
1. The value is undefined in bus off state.

Figure 17.13 C0RECR Register

17.1.3.9 C0TECR Register

Figure 17.14 shows the C0TECR register.

CAN0 Transmit Error Count Register (1)

b7 b0

Symbol	Address	After Reset
C0TECR	$021D_{16}$	00_{16}

Function	Counter Value	RW
Transmission error counting function The value is incremented or decremented according to the CAN module's error status	00_{16} to FF_{16}(1)	RO

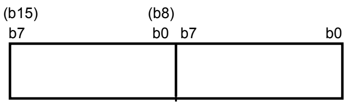
NOTE:
1. The value is undefined in bus off state.

Figure 17.14 C0TECR Register

17.1.3.10 C0TSR Register

Figure 17.15 shows the C0TSR register.

CAN0 Time Stamp Register(1)



Symbol	Address	After Reset
C0TSR	$021F_{16}$, $021E_{16}$	0000_{16}

Function	Counter Value	RW
Time stamp function	0000_{16} to $FFFF_{16}$	RO

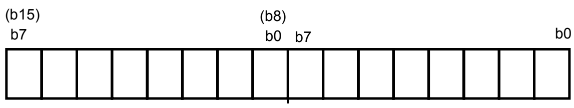
NOTE:
1. Use a 16-bit data for reading.

Figure 17.15 C0TSR Register

17.1.3.11 C0AFS Register

Figure 17.16 shows the C0AFS register.

CAN0 Acceptance Filter Support Register



Symbol	Address	After reset
C0AFS	0243_{16}, 0242_{16}	Undefined

Function	Setting Values	RW
Write the content equivalent to the standard frame ID of the received message. The value is "converted standard frame ID" when read	Standard frame ID	RW

Figure 17.16 C0AFS Register

17.2 Operating Modes

The CAN module has the following four operating modes.

- CAN Reset/Initialization Mode
- CAN Operating Mode
- CAN Sleep Mode
- CAN Interface Sleep Mode

Figure 17.17 shows transition between operating modes.

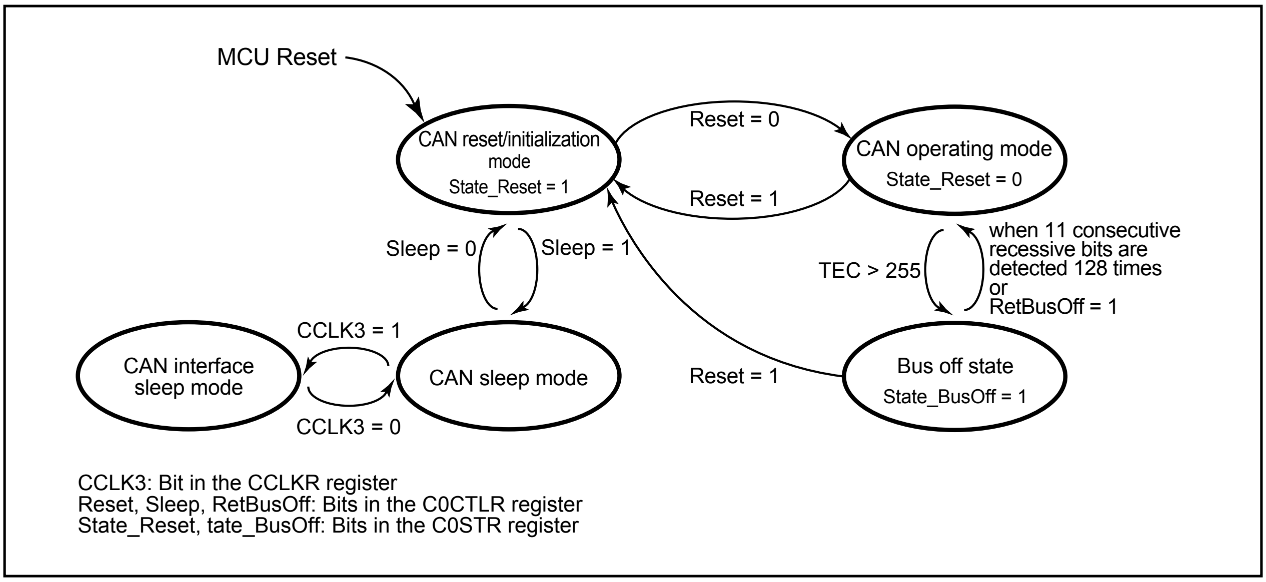


Figure 17.17 Transition Between Operating Modes

17.2.1 CAN Reset/Initialization Mode

The CAN reset/initialization mode is activated upon MCU reset or by setting the Reset bit in the C0CTLR register to 1. If the Reset bit is set to 1, check that the State_Reset bit in the C0STR register is set to 1. Entering the CAN reset/initialization mode initiates the following functions by the module:

- CAN communication is impossible.
- When the CAN reset/initialization mode is activated during an ongoing transmission in operation mode, the module suspends the mode transition until completion of the transmission (successful, arbitration loss, or error detection). Then, the State_Reset bit is set to 1, and the CAN reset/ initialization mode is activated.
- Registers C0MCTLj (j = 0 to 15), C0STR, C0ICR, C0IDR, C0RECR, C0TECR, and C0TSR are initialized. All these registers are locked to prevent CPU modification.
- Registers C0CTLR, C0CONR, C0GMR, C0LMAR, and C0LMBR and the CAN0 message box retain their contents and are available for CPU access.

17.2.2 CAN Operating Mode

The CAN operating mode is activated by setting the Reset bit in the C0CTLR register to 0. If the Reset bit is set to 0, check that the State_Reset bit in the C0STR register is set to 0.

If 11 consecutive recessive bits are detected after entering the CAN operating mode, the module initiates the following functions:

- The module's communication functions are released and it becomes an active node on the network and may transmit and receive CAN messages.
- Release the internal fault confinement logic including receive and transmit error counters. The module may leave the CAN operating mode depending on the error counts.

Within the CAN operating mode, the module may be in three different sub modes, depending on which type of communication functions are performed:

- Module idle : The modules receive and transmit sections are inactive.
- Module receives : The module receives a CAN message sent by another node.
- Module transmits : The module transmits a CAN message. The module may receive its own message simultaneously when the LoopBack bit in the C0CTLR register = 1 (Loop back mode enabled).

Figure 17.18 shows sub modes of the CAN operating mode.

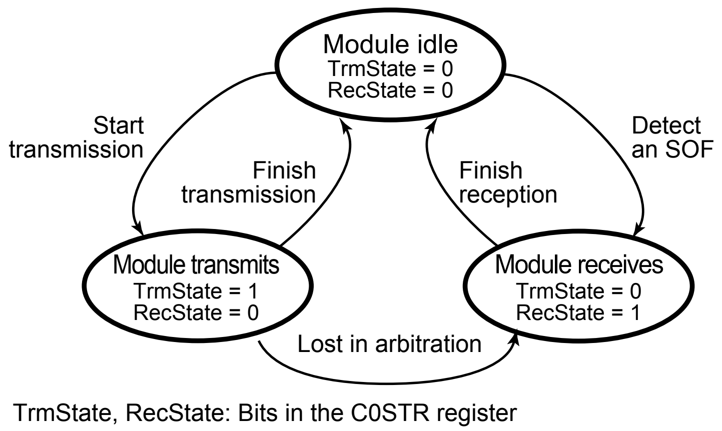


Figure 17.18 Sub Modes of CAN Operating Mode

17.2.3 CAN Sleep Mode

The CAN sleep mode is activated by setting the Sleep bit in the C0CTLR register to 1. It should never be activated from the CAN operating mode but only via the CAN reset/initialization mode.

Entering the CAN sleep mode instantly stops the clock supply to the module and thereby reduces power dissipation.

17.2.4 CAN Interface Sleep Mode

The CAN interface sleep mode is activated by setting the CCLK3 bit in the CCLKR register to 1. It should never be activated but only via the CAN sleep mode.
Entering the CAN interface sleep mode instantly stops the clock supply to the CPU Interface in the module and thereby reduces power dissipation.

17.2.5 Bus Off State

The bus off state is entered according to the fault confinement rules of the CAN specification. When returning to the CAN operating mode from the bus off state, the module has the following two cases.
In this time, the value of any CAN registers, except registers C0STR, C0RECR, and C0TECR, does not change.

(1) When 11 consecutive recessive bits are detected 128 times
The module enters instantly into error active state and the CAN communication becomes possible immediately.

(2) When the RetBusOff bit in the C0CTLR register = 1 (Force return from buss off)
The module enters instantly into error active state, and the CAN communication becomes possible again after 11 consecutive recessive bits are detected.

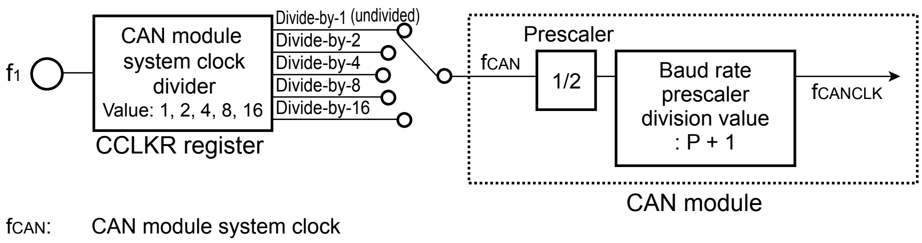
17.3 Configuration of the CAN Module System Clock

The M16C/29 Group has a CAN module system clock select circuit.

Configuration of the CAN module system clock can be done through manipulating the CCLKR register and the BRP bit in the C0CONR register.

For the CCLKR register, refer to **7. Clock Generation Circuit**.

Figure 17.19 shows a block diagram of the clock generation circuit of the CAN module system.



fCAN: CAN module system clock
P: The value written in the BRP bit of the C0CONR register. P = 0 to 15
fCANCLK: CAN communication clock fCANCLK = fCAN/2(P + 1)

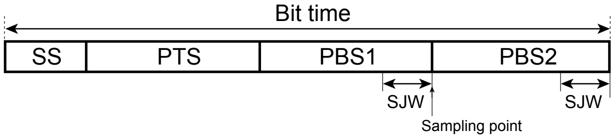
Figure 17.19 Block Diagram of CAN Module System Clock Generation Circuit

17.3.1 Bit Timing Configuration

The bit time consists of the following four segments:

- Synchronization segment (SS)
  This serves for monitoring a falling edge for synchronization.
- Propagation time segment (PTS)
  This segment absorbs physical delay on the CAN network which amounts to double the total sum of delay on the CAN bus, the input comparator delay, and the output driver delay.
- Phase buffer segment 1 (PBS1)
  This serves for compensating the phase error. When the falling edge of the bit falls later than expected, the segment can become longer by the maximum of the value defined in SJW.
- Phase buffer segment 2 (PBS2)
  This segment has the same function as the phase buffer segment 1. When the falling edge of the bit falls earlier than expected, the segment can become shorter by the maximum of the value defined in SJW.

Figure 17.20 shows the bit timing.



The range of each segment: Bit time = 8 to 25Tq
SS = 1Tq
PTS = 1Tq to 8Tq
PBS1 = 2Tq to 8Tq
PBS2 = 2Tq to 8Tq
SJW = 1Tq to 4Tq

Configuration of PBS1 and PBS2: PBS1 ≥ PBS2
PBS1 ≥ SJW
PBS2 ≥ 2 when SJW = 1
PBS2 ≥ SJW when 2 ≤ SJW ≤ 4

Figure 17.20 Bit Timing

17.3.2 Bit-rate

Bit-rate depends on f_1, the division value of the CAN module system clock, the division value of the baud rate prescaler, and the number of Tq of one bit.

Table 17.2 shows the examples of bit-rate.

Table 17.2 Examples of Bit-rate

Bit-rate	20MHz	16MHz	10MHz	8MHz
1Mbps	10Tq (1)	8Tq (1)	–	–
500kbps	10Tq (2) 20Tq (1)	8Tq (2) 16Tq (1)	10Tq (1) –	8Tq (1) –
125kbps	10Tq (8) 20Tq (4)	8Tq (8) 16Tq (4)	10Tq (4) 20Tq (2)	8Tq (4) 16Tq (2)
83.3kbps	10Tq (12) 20Tq (6)	8Tq (12) 16Tq (6)	10Tq (6) 20Tq (3)	8Tq (6) 16Tq (3)
33.3kbps	10Tq (30) 20Tq (15)	8Tq (30) 16Tq (15)	10Tq (15) –	8Tq (15) –

NOTE:

1. The number in ( ) indicates a value of "f_{CAN} division value" multiplied by "baud rate prescaler division value".

■ Calculation of Bit-rate

$$\frac{f_1}{2 \times \text{"}f_{CAN}\text{ division value (Note 1)"} \times \text{"baud rate prescaler division value (Note 2)"} \times \text{"number of Tq of one bit"}}$$

Note 1: f_{CAN} division value = 1, 2, 4, 8, 16
f_{CAN} division value: a value selected in the CCLKR register

Note 2: Baud rate prescaler division value = P + 1 (P: 0 to 15)
P: a value selected in the BRP bit in the C0CONR register

17.4 Acceptance Filtering Function and Masking Function

These functions serve the users to select and receive a facultative message. The C0GMR register, the C0LMAR register, and the C0LMBR register can perform masking to the standard ID and the extended ID of 29 bits. The C0GMR register corresponds to slots 0 to 13, the C0LMAR register corresponds to slot 14, and the C0LMBR register corresponds to slot 15. The masking function becomes valid to 11 bits or 29 bits of a received ID according to the value in the corresponding slot of the C0IDR register upon acceptance filtering operation. When the masking function is employed, it is possible to receive a certain range of IDs. **Figure 17.21** shows correspondence of the mask registers and slots, **Figure 17.22** shows the acceptance function.

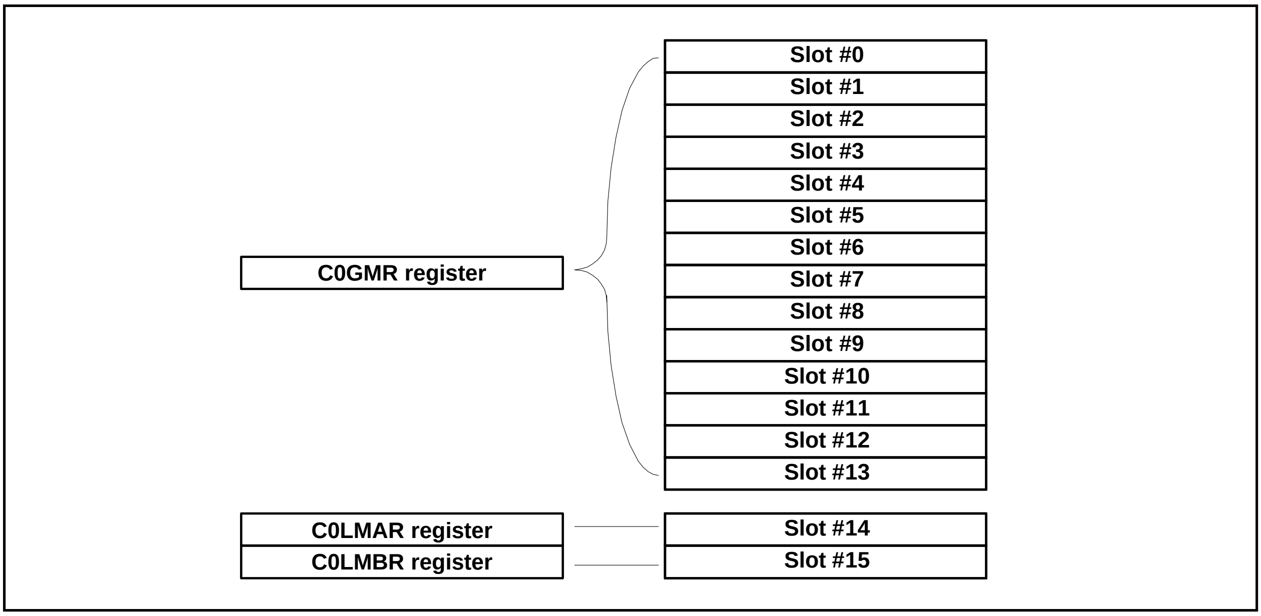


Figure 17.21 Correspondence of Mask Registers to Slots

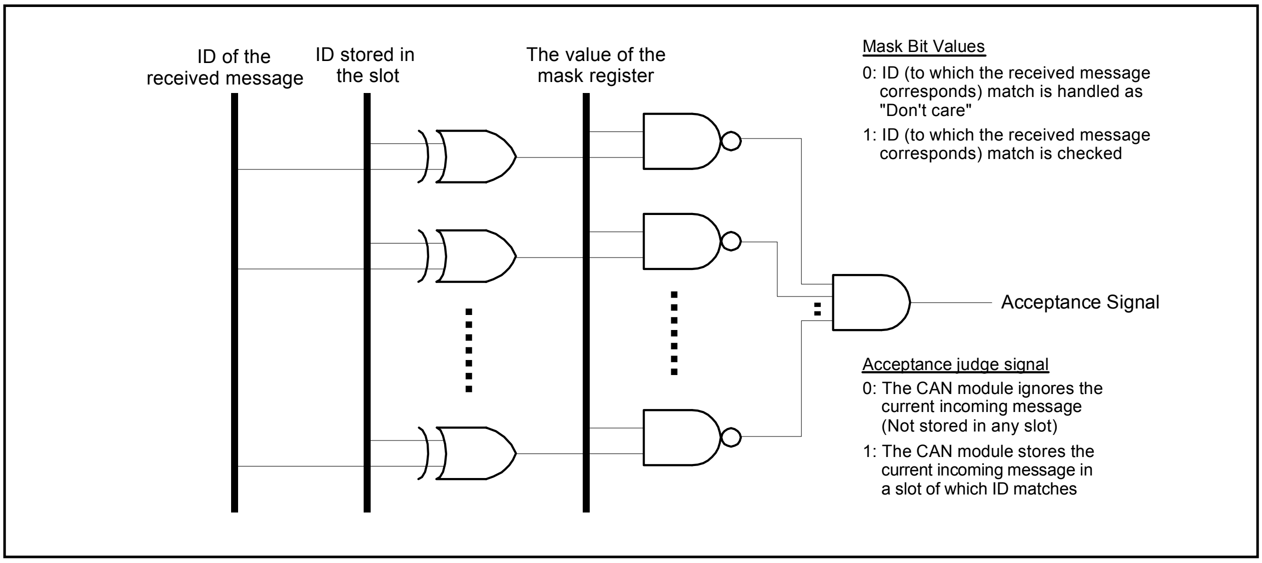


Figure 17.22 Acceptance Function

When using the acceptance function, note the following points.

(1) When one ID is defined in two slots, the one with a smaller number alone is valid.

(2) When it is configured that slots 14 and 15 receive all IDs with Basic CAN mode, slots 14 and 15 receive all IDs which are not stored into slots 0 to 13.

17.5 Acceptance Filter Support Unit (ASU)

The acceptance filter support unit has a function to judge valid/invalid of a received ID through table search. The IDs to receive are registered in the data table; a received ID is stored in the C0AFS register, and table search is performed with a decoded received ID. The acceptance filter support unit can be used for the IDs of the standard frame only.

The acceptance filter support unit is valid in the following cases.

• When the ID to receive cannot be masked by the acceptance filter.
 (Example) IDs to receive: 078_{16}, 087_{16}, 111_{16}

• When there are too many IDs to receive; it would take too much time to filter them by software.

Figure 17.23 shows the write and read of the C0AFS register in word access.

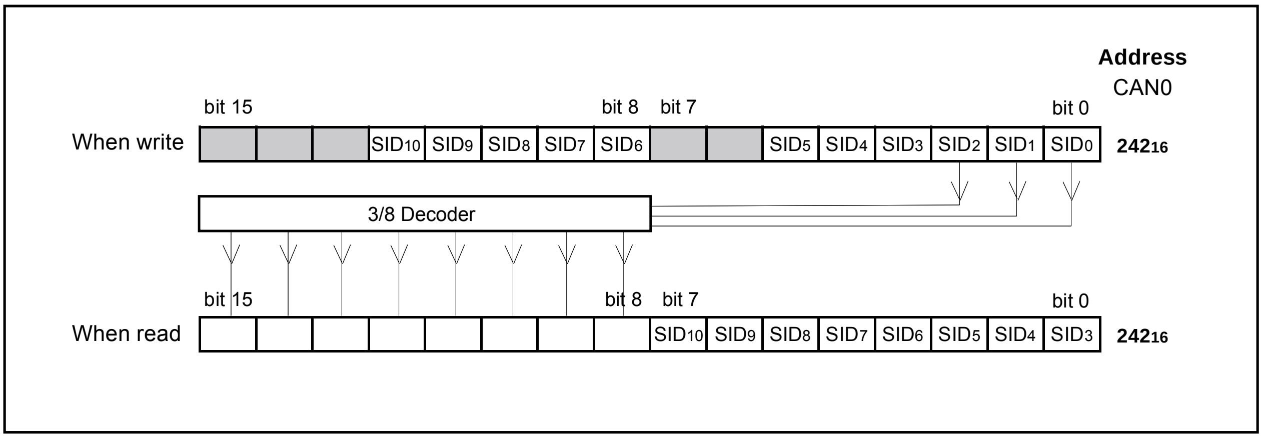


Figure 17.23 Write/read of C0AFS Register in Word Access

17.6 BasicCAN Mode

When the BasicCAN bit in the C0CTLR register is set to 1 (Basic CAN mode enabled), slots 14 and 15 correspond to Basic CAN mode. During normal operations, individual slots can select either data frame or remote frame by CPU setting. However, in Basic CAN mode, both frames can be selected.
When slots 14 and 15 are defined as reception slots in Basic CAN mode, received messages are stored in slots 14 and 15 alternately.
The received message data format can be determined by the RemActive bit in the C0MCTLj register (j = 0 to 15).
Figure 17.24 shows the operation of slots 14 and 15 in Basic CAN mode.

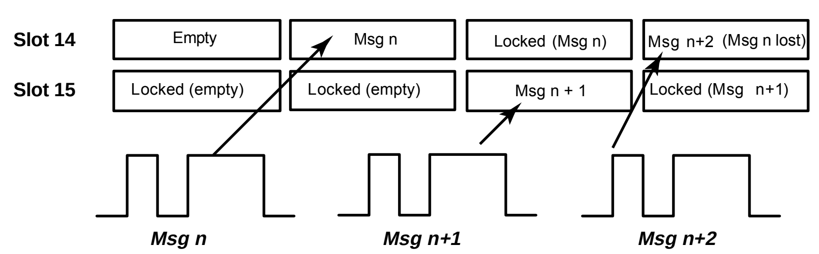


Figure 17.24 Operation of Slots 14 and 15 in Basic CAN Mode

When using Basic CAN mode, note the following points.
(1) Setting of Basic CAN mode has to be done in CAN reset/initialization mode.
(2) Select the same ID for slots 14 and 15. Also, setting of the C0LMAR and C0LMBR register has to be the same.
(3) Define slots 14 and 15 as reception slot only.
(4) There is no protection available against message overwrite. A message can be overwritten by a new message.
(5) Slots 0 to 13 can be used in the same way as in normal CAN operating mode.

17.7 Return from Bus off Function

When the protocol controller enters bus off state, it is possible to make it forced return from bus off state by setting the RetBusOff bit in the C0CTLR register to 1 (Force return from bus off). At this time, the error state changes from bus off state to error active state. If the RetBusOff bit is set to 1, registers C0RECR and C0TECR are initialized and the State_Reset bit in the C0STR register is set to 0 (The CAN module is not in error bus off state). However, registers of the CAN module such as C0CONR register and the content of each slot are not initialized.

17.8 Time Stamp Counter and Time Stamp Function

When the C0TSR register is read, the value of the time stamp counter at the moment is read. The period of the time stamp counter reference clock is the same as that of 1 bit time that is configured by the C0CONR register. The time stamp counter functions as a free run counter.

The 1 bit time period can be divided by 1 (undivided), 2, 4 or 8 to produce the time stamp counter reference clock. Use the TSPreScale bit in the C0CTLR register to select the divide-by-n value.

The time stamp counter is equipped with a register that captures the counter value when the protocol controller regards it as a successful reception. The captured value is stored when a time stamp value is stored in a reception slot.

17.9 Listen-Only Mode

When the RXOnly bit in the C0CTLR register is set to 1, the module enters listen-only mode.

In listen-only mode, no transmission -- data frames, error frames, and ACK response -- is performed to bus.

When listen-only mode is selected, do not request the transmission.

17.10 Reception and Transmission

Configuration of CAN Reception and Transmission Mode

Table 17.3 shows configuration of CAN reception and transmission mode.

Table 17.3 Configuration of CAN Reception and Transmission Mode

TrmReq	RecReq	Remote	RspLock	Communication mode of the slot
0	0	–	–	Communication environment configuration mode: configure the communication mode of the slot.
0	1	0	0	Configured as a reception slot for a data frame.
1	0	1	0	Configured as a transmission slot for a remote frame. (At this time the RemActive = 1.) After completion of transmission, this functions as a reception slot for a data frame. (At this time the RemActive = 0.) However, when an ID that matches on the CAN bus is detected before remote frame transmission, this immediately functions as a reception slot for a data frame.
1	0	0	0	Configured as a transmission slot for a data frame.
0	1	1	1/0	Configured as a reception slot for a remote frame. (At this time the RemActive = 1.) After completion of reception, this functions as a transmission slot for a data frame. (At this time the RemActive = 0.) However, transmission does not start as long as RspLock bit remains 1; thus no automatic response. Response (transmission) starts when the RspLock bit is set to 0.

TrmReq, RecReq, Remote, RspLock, RemActive, RspLock: Bits in the C0MCTLj register (j = 0 to 15)

When configuring a slot as a reception slot, note the following points.

(1) Before configuring a slot as a reception slot, be sure to set the C0MCTLj register (j = 0 to 15) to 00_{16}.

(2) A received message is stored in a slot that matches the condition first according to the result of reception mode configuration and acceptance filtering operation. Upon deciding in which slot to store, the smaller the number of the slot is, the higher priority it has.

(3) In normal CAN operating mode, when a CAN module transmits a message of which ID matches, the CAN module never receives the transmitted data. In loop back mode, however, the CAN module receives back the transmitted data. In this case, the module does not return ACK.

When configuring a slot as a transmission slot, note the following points.

(1) Before configuring a slot as a transmission slot, be sure to set the C0MCTLj registers to 00_{16}.

(2) Set the TrmReq bit in the C0MCTLj register to 0 (not transmission slot) before rewriting a transmission slot.

(3) A transmission slot should not be rewritten when the TrmActive bit in the C0MCTLj register is 1 (transmitting).
If it is rewritten, an undefined data will be transmitted.

17.10.1 Reception

Figure 17.25 shows the behavior of the module when receiving two consecutive CAN messages, that fit into the slot of the shown C0MCTLj register (j = 0 to 15) and leads to losing/overwriting of the first message.

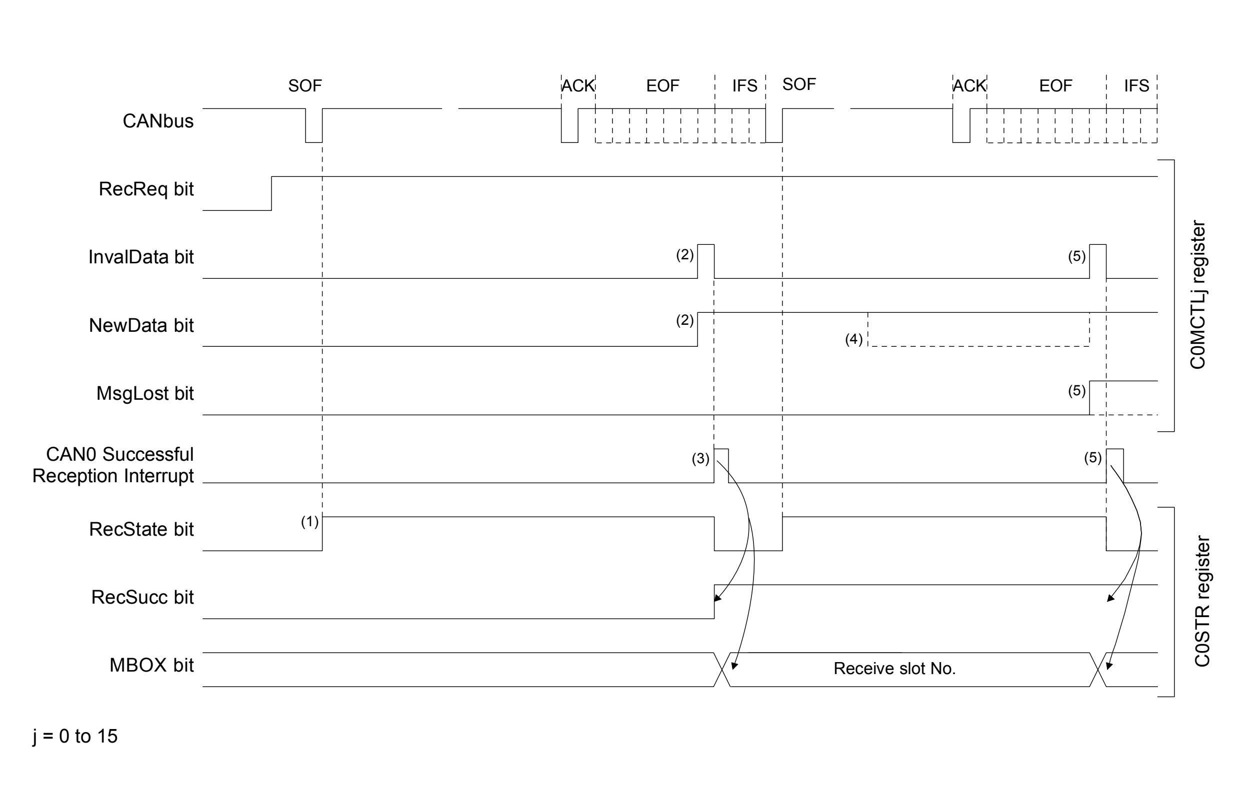


Figure 17.25 Timing of Receive Data Frame Sequence

(1) On monitoring a SOF on the CAN bus the RecState bit in the C0STR register becomes 1 (CAN module is receiver) immediately, given the module has no transmission pending.

(2) After successful reception of the message, the NewData bit in the C0MCTLj register (j = 0 to 15) of the receiving slot becomes 1 (stored new data in slot). The InvalData bit in the C0MCTLj register becomes 1 (message is being updated) at the same time and the InvalData bit becomes 0 (message is valid) again after the complete message was transferred to the slot.

(3) When the interrupt enable bit in the C0ICR register of the receiving slot = 1 (interrupt enabled), the CAN0 successful reception interrupt request is generated and the MBOX bit in the C0STR register is changed. It shows the slot number where the message was stored and the RecSucc bit in the C0STR register is active.

(4) Read the message out of the slot after setting the New Data bit to 0 (the content of the slot is read or still under processing by the CPU) by program.

(5) If the NewData bit is set to 0 by program or the next CAN message is received successfully before the receive request for the slot is canceled, the MsgLost bit in the C0MCTLj register is set to 1 (message has been overwritten). The new received message is transferred to the slot. Generating of an interrupt request and change of the C0STR register are same as in 3).

17.10.2 Transmission

Figure 17.26 shows the timing of the transmit sequence.

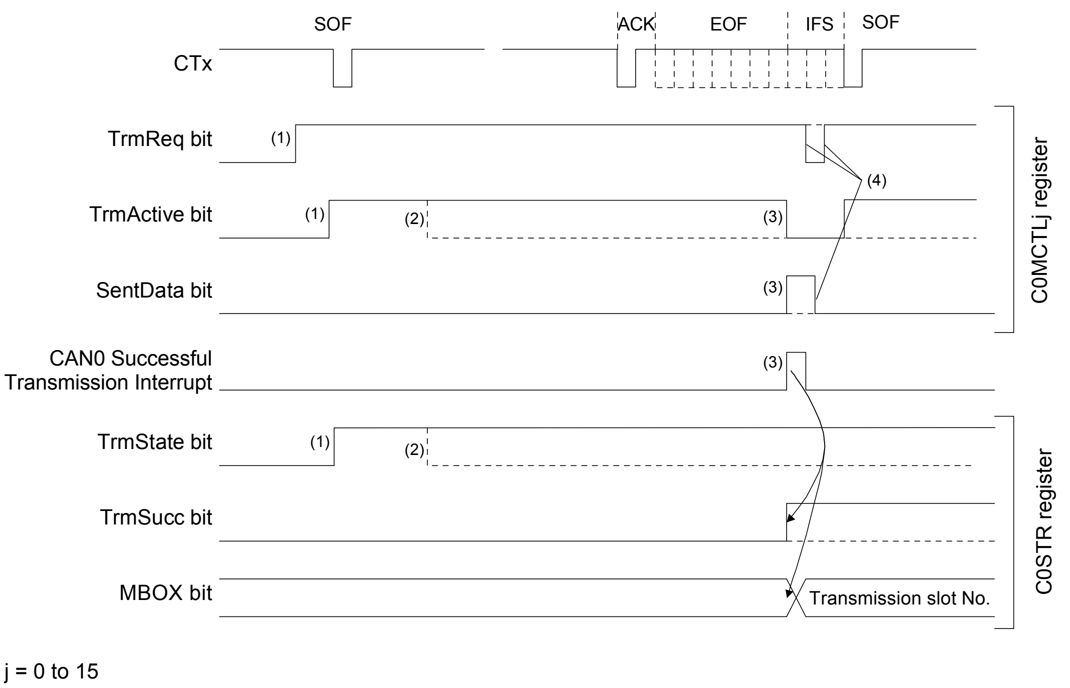


Figure 17.26 Timing of Transmit Sequence

(1) If the TrmReq bit in the C0MCTLj register (j = 0 to 15) is set to 1 (Transmission slot) in the bus idle state, the TrmActive bit in the C0MCTLj register and the TrmState bit in the C0STR register are set to 1 (Transmitting/Transmitter), and CAN module starts the transmission.

(2) If the arbitration is lost after the CAN module starts the transmission, the TrmActive and TrmState bits are set to 0.

(3) If the transmission has been successful without lost in arbitration, the SentData bit in the C0MCTLj register is set to 1 (Transmission is successfully completed) and TrmActive bit in the C0MCTLj register is set to 0 (Waiting for bus idle or completion of arbitration). And when the interrupt enable bits in the C0ICR register = 1 (Interrupt enabled), CAN0 successful transmission interrupt request is generated and the MBOX (the slot number which transmitted the message) and TrmSucc bit in the C0STR register are changed.

(4) When starting the next transmission, set bits SentData and TrmReq to 0. And set the TrmReq bit to 1 after checking that bits SentData and TrmReq are set to 0.

17.11 CAN Interrupts

The CAN module provides the following CAN interrupts.

- CAN0 Successful Reception Interrupt
- CAN0 Successful Transmission Interrupt
- CAN0 Error Interrupt
  - Error Passive State
  - Error BusOff State
  - Bus Error (this feature can be disabled separately)
- CAN0 Wake-up Interrupt

When the CPU detects the CAN0 successful reception/transmission interrupt request, the MBOX bit in the C0STR register must be read to determine which slot has generated the interrupt request.

18. CRC Calculation Circuit

The Cyclic Redundancy Check (CRC) calculation detects errors in blocks of data. The MCU uses a generator polynomial of CRC_CCITT ($X^{16} + X^{12} + X^5 + 1$) or CRC-16 ($X^{16} + X^{15} + X^2 + 1$) to generate CRC code.

The CRC code is a 16-bit code generated for a block of a given data length in multiples of bytes. The code is updated in the CRC data register everytime one byte of data is transferred to a CRC input register. The data register must be initialized before use. Generation of CRC code for one byte of data is completed in two machine cycles.

Figure 18.1 shows the block diagram of the CRC circuit. **Figure 18.2** shows the CRC-related registers. **Figure 18.3** shows the calculation example using the CRC_CCITT operation.

18.1 CRC Snoop

The CRC circuit includes the ability to snoop reads and writes to certain SFR addresses. This can be used to accumulate the CRC value on a stream of data without using extra bandwidth to explicitly write data into the CRCIN register. All SFR addresses after 002_{16} are subject to the CRC snoop. The CRC snoop is useful to snoop the writes to a UART TX buffer, or the reads from a UART RX buffer.

To snoop an SFR address, the target address is written to the CRC snoop Address Register (CRCSAR). The two most significant bits of this register enable snooping on reads or writes to the target address. If the target SFR is written to by the CPU or DMA, and the CRC snoop write bit is set (CRCSW=1), the CRC will latch the data into the CRCIN register. The new CRC code will be set in the CRCD register.

Similarly, if the target SFR is read by the CRC or DMA, and the CRC snoop read bit is set (CRCSR=1), the CRC will latch the data from the target into the CRCIN register and calculate the CRC.

The CRC circuit can only calculate CRC codes on data byte at a time. Therefore, if a target SFR is accessed in word (16 bit), only one low-order byte data is stored into the CRCIN register.

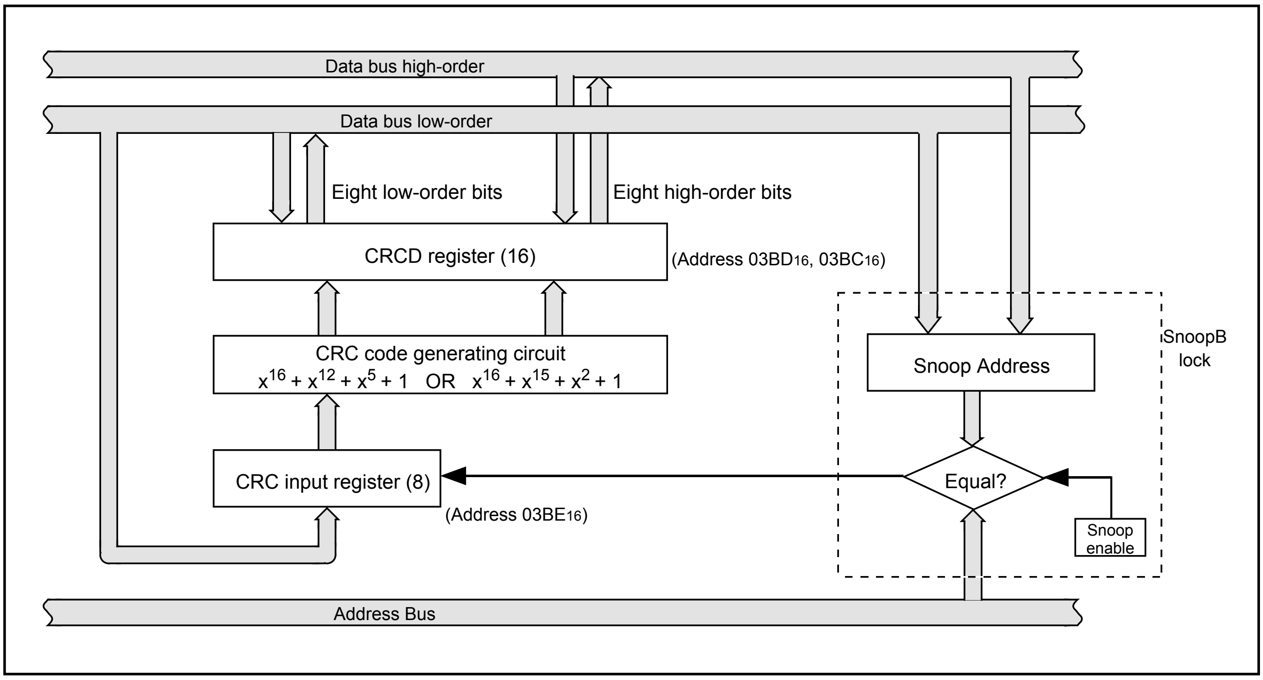


Figure 18.1 CRC circuit block diagram

CRC Data Register

Symbol	Address	After Reset
CRCD	$03BD_{16}$ to $03BC_{16}$	Undefined

Function	Setting Range	RW
CRC calculation result output	0000_{16} to $FFFF_{16}$	RW

CRC Input Register

Symbol	Address	After Reset
CRCIN	$03BE_{16}$	Undefined

Function	Setting Range	RW
Data input	00_{16} to FF_{16}	RW

CRC Mode Register

Symbol	Address	After Reset
CRCMR	$03B6_{16}$	$0XXXXXX0_2$

Bit Symbol	Bit Name	Function	RW
CRCPS	CRC mode polynomial selection bit	0: $X^{16}+X^{12}+X^5+1$ (CRC-CCITT) 1: $X^{16}+X^{15}+X^2+1$ (CRC-16)	RW
(b6-b1)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
CRCMS	CRC mode selection bit	0: LSB first 1: MSB first	RW

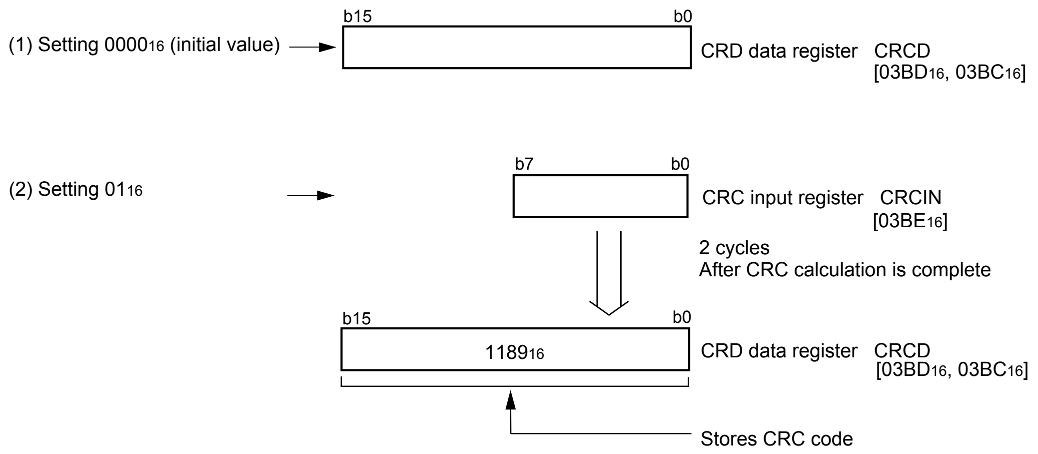
SFR Snoop Address Register

Symbol	Address	After Reset
CRCSAR	$03B5_{16}$ to $03B4_{16}$	$00XXXXXX\ XXXXXXXX_2$

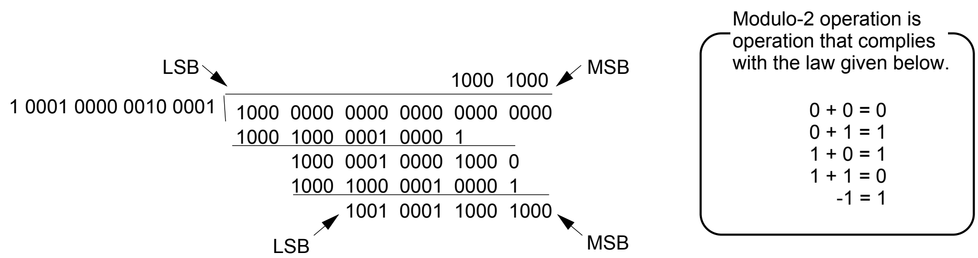
Bit Symbol	Bit Name	Function	RW
CRCSAR9-0	CRC mode polynomial selection bit	SFR address to snoop	RW
(b13-b10)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
CRCSR	CRC snoop on read enable bit	0: Disabled 1: Enabled(1)	RW
CRCSW	CRC snoop on write enable bit	0: Disabled 1: Enabled(1)	RW

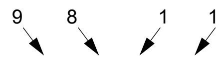
NOTE:
1. Set bits CRCSR and CRCSW to 0 if the PLC07 bit in the PLC0 register is set to 1 (PLL on) and the PM20 bit in the PM2 register is set to 0 (SFR access 2 wait).

Figure 18.2. CRCD, CRCIN, CRCMR, CRCSAR Register



The code resulting from sending 01_{16} in LSB first mode is (10000 0000).This the CRC code in the generating polynomial, $(X^{16} + X^{12} + X^{5} + 1)$, becomes the remainder resulting from dividing $(1000\ 0000)X^{16}$ by (1 0001 0000 0010 0001) in conformity with the modulo-2 operation.





Thus the CRC code becomes (1001 0001 1000 1000). Since the operation is in LSB first mode, the (1001 0001 1000 1000) corresponds to 1189_{16} in hexadecimal notation. If the CRC operation in MSB first mode is necessary, set the CRC mode selection bit to 1. CRC data register stores CRC code for MSB first mode.

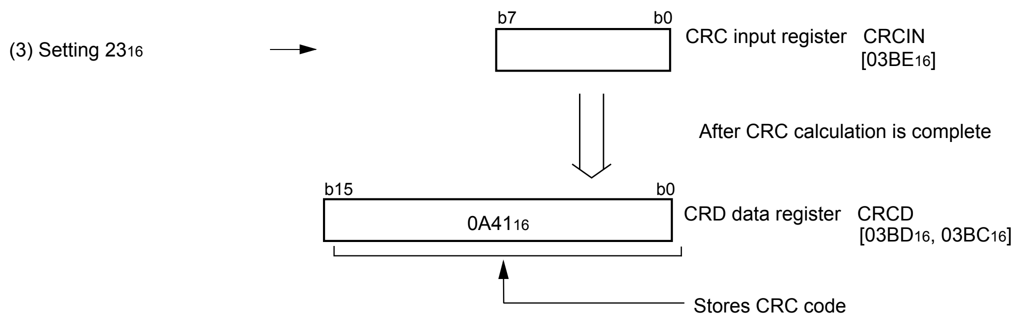


Figure 18.3. CRC Calculation

19. Programmable I/O Ports

Note
Ports $P0_4$ to $P0_7$, $P1_0$ to $P1_4$, $P3_4$ to $P3_7$ and $P9_5$ to $P9_7$ are not available in 64-pin package.

The programmable input/output ports (hereafter referred to simply as “I/O ports”) consist of 71 lines P0, P1, P2, P3, P6, P7, P8, P9, P10 (except $P9_4$) for the 80-pin package, or 55 lines $P0_0$ to $P0_3$, $P1_5$ to $P1_7$, P2, $P3_0$ to $P3_3$, P6, P7, P8, $P9_0$ to $P9_3$, P10 for the 64-pin package. Each port can be set for input or output every line by using a direction register, and can also be chosen to be or not be pulled high in sets of 4 lines.
Figures 19.1 to **19.4** show the I/O ports. **Figure 19.5** shows the I/O pins.
Each pin functions as an I/O port, a peripheral function input/output.
For details on how to set peripheral functions, refer to each functional description in this manual. If any pin is used as a peripheral function input, set the direction bit for that pin to 0 (input mode). Any pin used as an output pin for peripheral functions is directed for output no matter how the corresponding direction bit is set.

19.1 Port Pi Direction Register (PDi Register, i = 0 to 3, 6 to 10)

Figure 19.6 shows the direction registers.
This register selects whether the I/O port is to be used for input or output. The bits in this register correspond one for one to each port.

19.2 Port Pi Register (Pi Register, i = 0 to 3, 6 to 10)

Figure 19.7 shows the Pi registers.
Data input/output to and from external devices are accomplished by reading and writing to the Pi register. The Pi register consists of a port latch to hold the output data and a circuit to read the pin status. For ports set for input mode, the input level of the pin can be read by reading the corresponding Pi register, and data can be written to the port latch by writing to the Pi register.
For ports set for output mode, the port latch can be read by reading the corresponding Pi register, and data can be written to the port latch by writing to the Pi register. The data written to the port latch is output from the pin. The bits in the Pi register correspond one for one to each port.

19.3 Pull-up Control Register 0 to 2 (PUR0 to PUR2 Registers)

Figure 19.8 shows registers PUR0 to PUR2.
Registers PUR0 to PUR2 select whether the pins, divided into groups of four pins, are pulled up or not. The pins, selected by setting the bits in registers PUR0 to PUR2 to 1 (pull-up), are pulled up when the direction registers are set to 0 (input mode). The pins are pulled up regardless of the pins' function.

19.4 Port Control Register (PCR Register)

Figure 19.9 shows the port control register.
When the P1 register is read after setting the PCR0 bit in the PCR register to 1, the corresponding port latch can be read no matter how the PD1 register is set.

19.5 Pin Assignment Control Register (PACR)

Figure 19.10 shows the PACR register. After reset, set bits PACR2 to PACR0 in the PACR register before a signal is input or output to each pin. When bits PACR2 to PACR0 are not set, some pins do not function as I/O ports.

Bits PACR2 to PACR0: control pins to be used
Value after reset: 000_2.
To select the 80-pin package, set the bits to 011_2.
To select the 64-pin package, set the bits to 010_2.

U1MAP bit: controls pin assignments for the UART1 function.
To assign the UART1 function to $P6_4/\overline{CTS_1}/\overline{RTS_1}$, $P6_5/CLK_1$, $P6_6/RxD_1$, and $P6_7/TxD_1$, set the U1MAP bit to 0 ($P6_7$ to $P6_4$).
To assign the function to $P7_0/\overline{CTS_1}/\overline{RTS_1}$, $P7_1/CLK_1$, $P7_2/RxD_1$, and $P7_3/TxD_1$, set the U1MAP bit to 1 ($P7_3$ to $P7_0$)

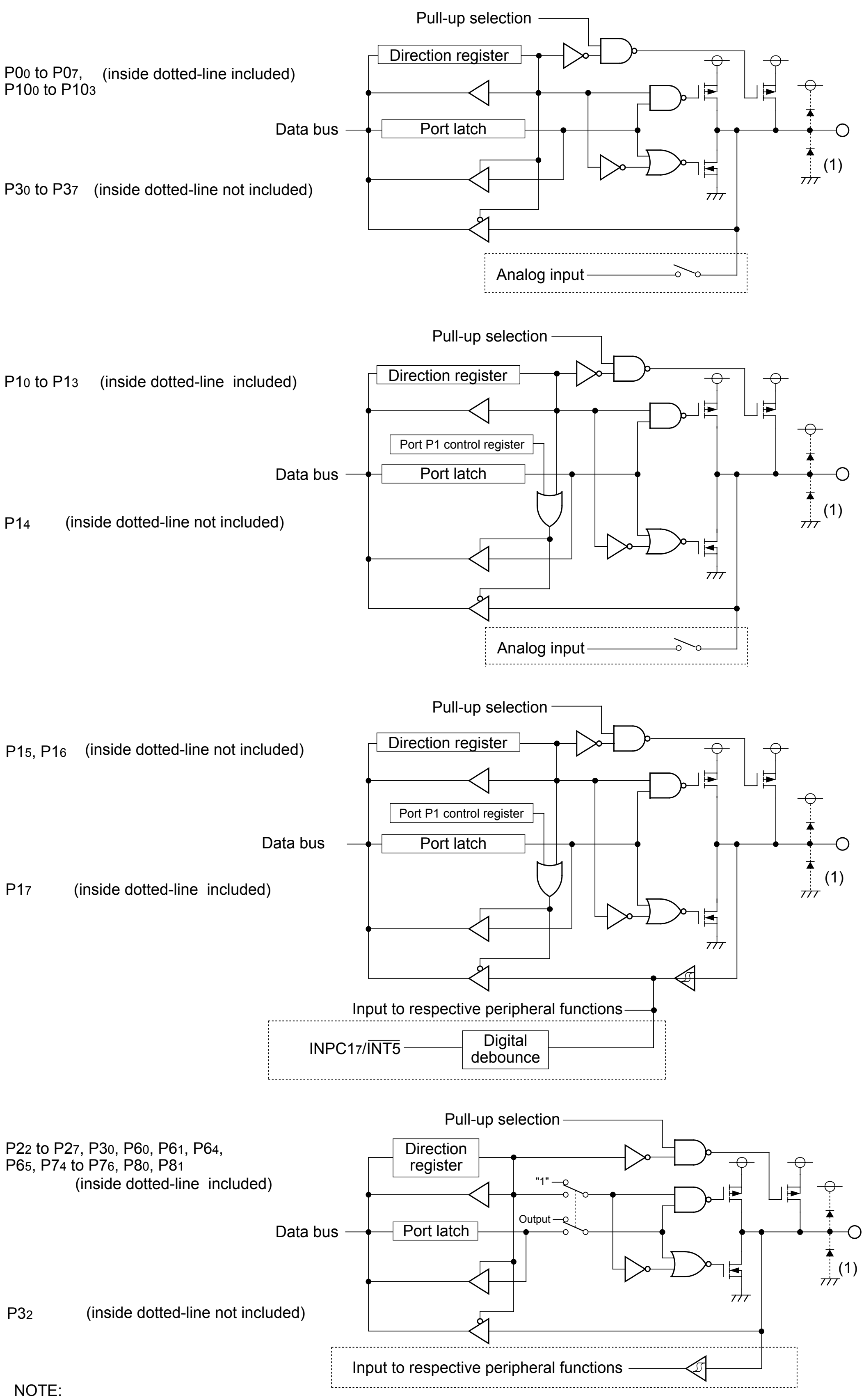
The PRC2 bit in the PRCR protects the PACR register. Set the PACR register after setting the PRC2 bit in the PRCR register.

19.6 Digital Debounce Function

Two digital debounce function circuits are provided. Level is determined when level is held, after applying either a falling edge or rising edge to the pin, longer than the programmed filter width time. This enables noise reduction.
This function is assigned to $\overline{INT5}$/INPC17 and $\overline{NMI}/\overline{SD}$. Digital filter width is set in the NDDR register and the P17DDR register respectively. **Figure 19.11** shows the NDDR register and the P17DDR register. Additionally, a digital debounce function is disabled to the port $P1_7$ input and the port $P8_5$ input.

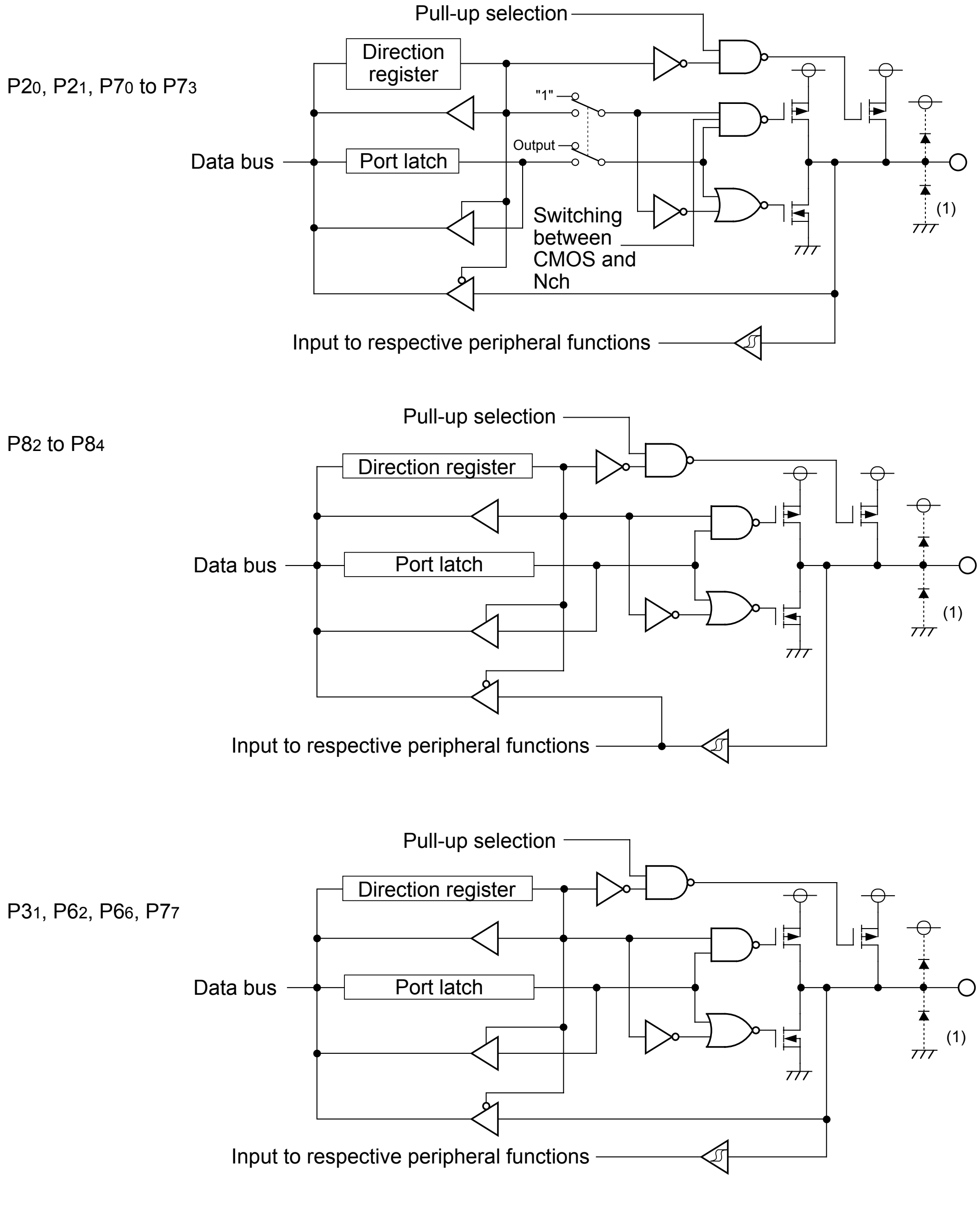
Filter width : (n+1) x 1/f8 n: count value set in the NDDR register and P17DDR register

The NDDR register and the P17DDR register decrement count value with f8 as the count source. The NDDR register and the P17DDR register indicate count time. Count value is reloaded if a falling edge or a rising edge is applied to the pin.
The NDDR register and the P17DDR register can be set 00_{16} to FF_{16} when using the digital debounce function. Setting to FF_{16} disables the digital filter. See **Figure 19.12** for details.



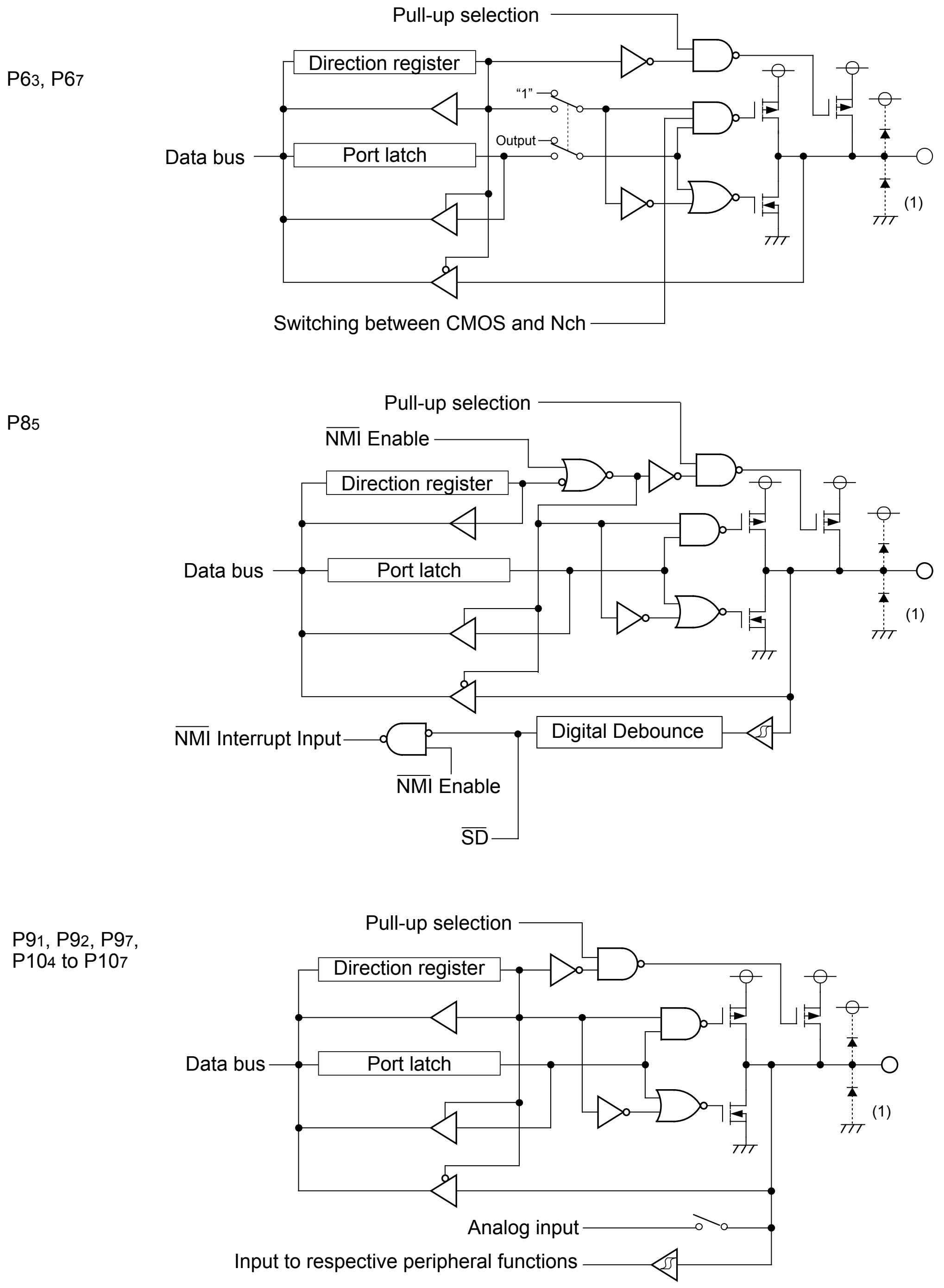
NOTE:
1. (parasitic diode symbol) symbolizes a parasitic diode.
Make sure the input voltage on each port will not exceed Vcc.

Figure 19.1 I/O Ports (1)



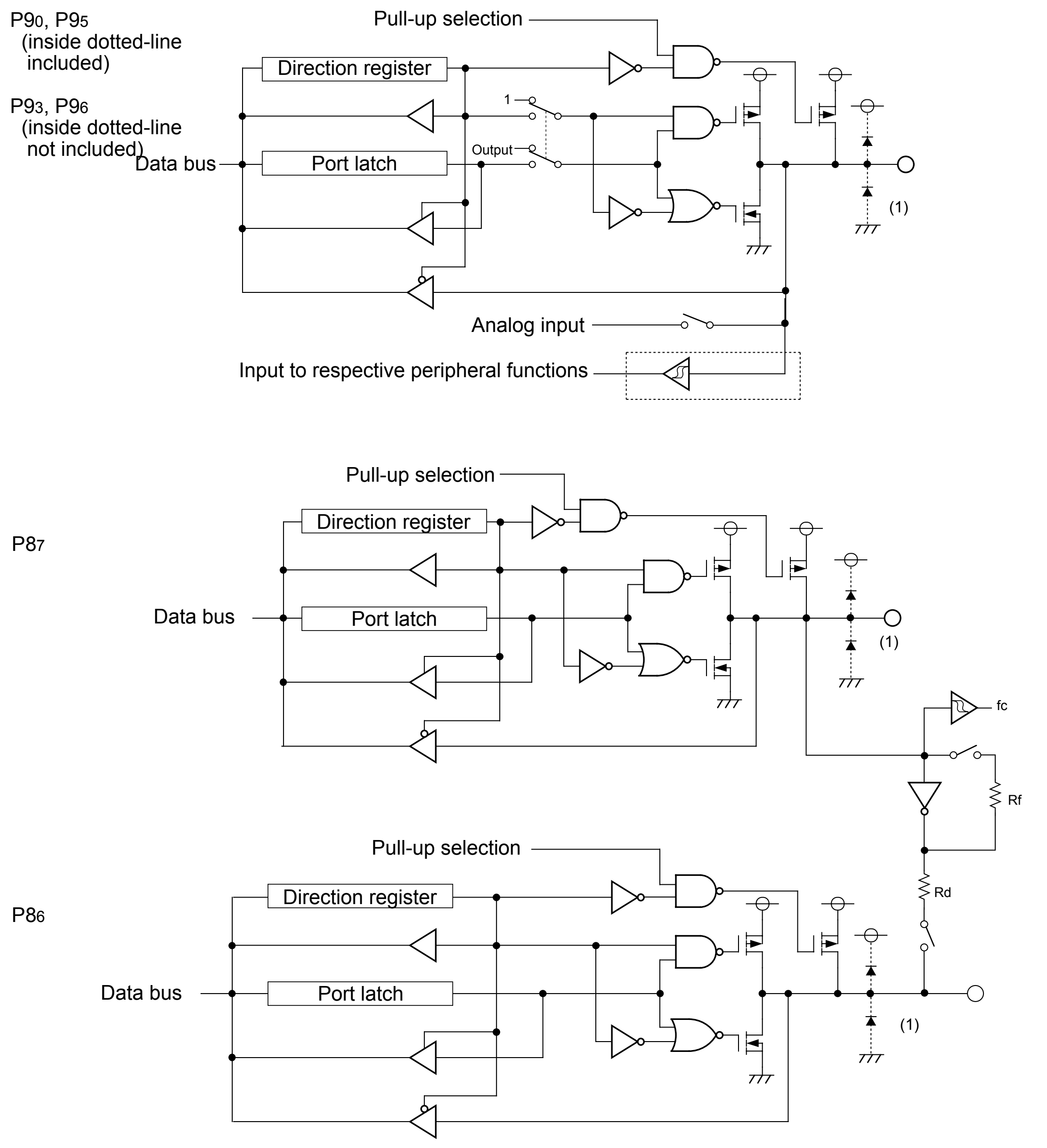
NOTE:
1. symbolizes a parasitic diode.
Make sure the input voltage on each port will not exceed Vcc.

Figure 19.2 I/O Ports (2)



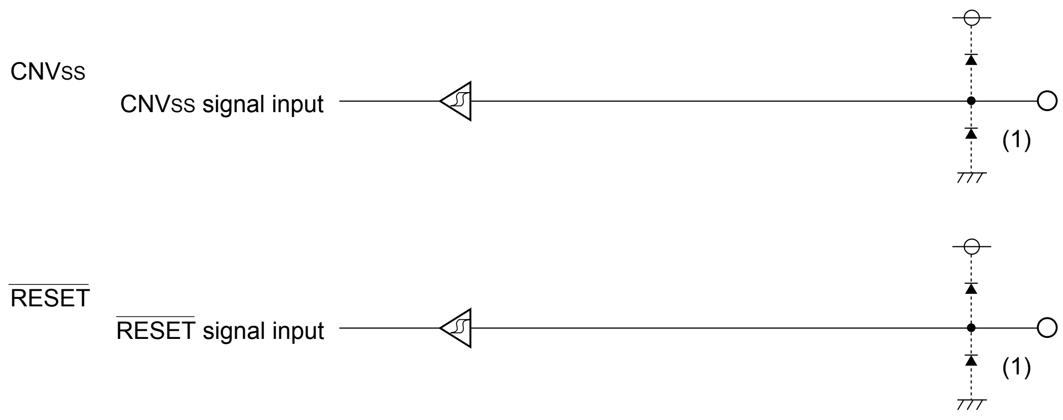
NOTE:
1. symbolizes a parasitic diode.
Make sure the input voltage on each port will not exceed Vcc.

Figure 19.3 I/O Ports (3)



NOTE:
1. symbolizes a parasitic diode.
Make sure the input voltage on each port will not exceed Vcc.

Figure 19.4 I/O Ports (4)



NOTE:
1. symbolizes a parasitic diode.
Make sure the input voltage on each port will not exceed Vcc.

Figure 19.5 I/O Pins

Port Pi Direction Register (i=0 to 3, 6 to 8, and 10) (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
PD0 to PD3	$03E2_{16}$, $03E3_{16}$, $03E6_{16}$, $03E7_{16}$	00_{16}
PD6 to PD8	$03EE_{16}$, $03EF_{16}$, $03F2_{16}$	00_{16}
PD10	$03F6_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
PDi_0	Port Pi0 direction bit	0: Input mode (Functions as an input port) 1: Output mode (Functions as an output port) (i = 0 to 3, 6 to 8, and 10)	RW
PDi_1	Port Pi1 direction bit		RW
PDi_2	Port Pi2 direction bit		RW
PDi_3	Port Pi3 direction bit		RW
PDi_4	Port Pi4 direction bit		RW
PDi_5	Port Pi5 direction bit		RW
PDi_6	Port Pi6 direction bit		RW
PDi_7	Port Pi7 direction bit		RW

NOTE:
1. Set the PACR register.
   In 80-pin package, set bits PACR2, PACR1, PACR0 to 011_2.
   In 64-pin package, set bits PACR2, PACR1, PACR0 to 010_2.

Port P9 Direction Register (1,2)

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
PD9	$03F3_{16}$	$000X0000_2$

Bit Symbol	Bit Name	Function	RW
PD9_0	Port P90 direction bit	0: Input mode (Functions as an input port) 1: Output mode (Functions as an output port)	RW
PD9_1	Port P91 direction bit		RW
PD9_2	Port P92 direction bit		RW
PD9_3	Port P93 direction bit		RW
— (b4)	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
PD9_5	Port P95 direction bit	0: Input mode (Functions as an input port) 1: Output mode (Functions as an output port)	RW
PD9_6	Port P96 direction bit		RW
PD9_7	Port P97 direction bit		RW

NOTES:
1. Make sure the PD9 register is written to by the next instruction after setting the PRC2 bit in the PRCR register to 1(write enabled).
2. Set the PACR register.
   In 80-pin package, set bits PACR2, PACR1, PACR0 to 011_2.
   In 64-pin package, set bits PACR2, PACR1, PACR0 to 010_2.

Figure 19.6 PD0 to PD3 and PD6 to PD10 Registers

Port Pi Register (i=0 to 3, 6 to 8 and 10)[1]

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
P0 to P3	$03E0_{16}$, $03E1_{16}$, $03E4_{16}$, $03E5_{16}$	Undefined
P6 to P8	$03EC_{16}$, $03ED_{16}$, $03F0_{16}$	Undefined
P10	$03F4_{16}$	Undefined

Bit Symbol	Bit Name	Function	RW
Pi_0	Port Pi_0 bit	The pin level on any I/O port which is set for input mode can be read by reading the corresponding bit in this register. The pin level on any I/O port which is set for output mode can be controlled by writing to the corresponding bit in this register 0: “L” level 1: “H” level (1) (i = 0 to 3, 6 to 8 and 10)	RW
Pi_1	Port Pi_1 bit		RW
Pi_2	Port Pi_2 bit		RW
Pi_3	Port Pi_3 bit		RW
Pi_4	Port Pi_4 bit		RW
Pi_5	Port Pi_5 bit		RW
Pi_6	Port Pi_6 bit		RW
Pi_7	Port Pi_7 bit		RW

NOTE:
1. Set the PACR register.
   In 80-pin package, set bits PACR2, PACR1, PACR0 to 011_2.
   In 64-pin package, set bits PACR2, PACR1, PACR0 to 010_2.

Port P9 Register [1]

b7 b6 b5 b4 b3 b2 b1 b0

Symbol	Address	After Reset
P9	$03F1_{16}$	Undefined

Bit Symbol	Bit Name	Function	RW
P9_0	Port $P9_0$ bit	The pin level on any I/O port which is set for input mode can be read by reading the corresponding bit in this register. The pin level on any I/O port which is set for output mode can be controlled by writing to the corresponding bit in this register (except for $P8_5$) 0: “L” level 1: “H” level	RW
P9_1	Port $P9_1$ bit		RW
P9_2	Port $P9_2$ bit		RW
P9_3	Port $P9_3$ bit		RW
(b4)	Nothing is assigned (2)		-
P9_5	Port $P9_5$ bit		RW
P9_6	Port $P9_6$ bit		RW
P9_7	Port $P9_7$ bit		RW

NOTES:
1. Set the PACR register.
   In 80-pin package, set bits PACR2, PACR1, PACR0 to 011_2.
   In 64-pin package, set bits PACR2, PACR1, PACR0 to 010_2.
2. Nothing is assigned. If necessary, set to 0. When read, the content is 0.

Figure 19.7 P0 to P3 and P6 to P10 Registers

Pull-up Control Register 0 (1)

Symbol: PUR0 | Address: $03FC_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
PU00	$P0_0$ to $P0_3$ pull-up	0: Not pulled up 1: Pulled up (1)	RW
PU01	$P0_4$ to $P0_7$ pull-up		RW
PU02	$P1_0$ to $P1_3$ pull-up		RW
PU03	$P1_4$ to $P1_7$ pull-up		RW
PU04	$P2_0$ to $P2_3$ pull-up		RW
PU05	$P2_4$ to $P2_7$ pull-up		RW
PU06	$P3_0$ to $P3_3$ pull-up		RW
PU07	$P3_4$ to $P3_7$ pull-up		RW

NOTE:
1. The pin for which this bit is 1 (pulled up) and the direction bit is 0 (input mode) is pulled up.

Pull-up Control Register 1

Symbol: PUR1 | Address: $03FD_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
—— (b3-b0)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—
PU14	$P6_0$ to $P6_3$ pull-up	0: Not pulled high 1: Pulled high (1)	RW
PU15	$P6_4$ to $P6_7$ pull-up		RW
PU16	$P7_0$ to $P7_3$ pull-up		RW
PU17	$P7_4$ to $P7_7$ pull-up		RW

NOTE:
1. The pin for which this bit is 1 (pulled up) and the direction bit is 0 (input mode) is pulled up.

Pull-up Control Register 2

Symbol: PUR2 | Address: $03FE_{16}$ | After Reset: 00_{16}

Bit Symbol	Bit Name	Function	RW
PU20	$P8_0$ to $P8_3$ pull-up	0: Not pulled up 1: Pulled up (1)	RW
PU21	$P8_4$ to $P8_7$ pull-up		RW
PU22	$P9_0$ to $P9_3$ pull-up		RW
PU23	$P9_5$ to $P9_7$ pull-up		RW
PU24	$P10_0$ to $P10_3$ pull-up		RW
PU25	$P10_4$ to $P10_7$ pull-up		RW
—— (b7-b6)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

NOTE:
1. The pin for which this bit is 1 (pulled up) and the direction bit is 0 (input mode) is pulled up.

Figure 19.8 PUR0 to PUR2 Registers

Port Control Register

b7 b6 b5 b4 b3 b2 b1 b0

Symbpl	Address	After Reset
PCR	$03FF_{16}$	00_{16}

Bit symbol	Bit Name	Function	RW
PCR0	Port P1 control bit	Operation performed when the P1 register is read 0: When the port is set for input, the input levels of $P1_0$ to $P1_7$ pins are read. When set for output, the port latch is read. 1: The port latch is read regardless of whether the port is set for input or output.	RW
— (b7-b1)	Nothing is assigned. If necessary, set to 0. When read, the content is 0		—

Figure 19.9 PCR Register

Pin Assignment Control Register (1)

b7 b6 b5 b4 b3 b2 b1 b0

Symbpl	Address	After Reset
PACR	$025D_{16}$	00_{16}

Bit Symbol	Bit Name	Function	RW
PACR0	Pin enabling bit	010 : 64 pin 011 : 80 pin All other values are reserved. Do not use.	RW
PACR1			RW
PACR2			RW
— (b6-b3)	Reserved bits	Nothing is assigned. If necessary, set to 0. When read, the content is 0	—
U1MAP	UART1 pin remapping bit	UART1 pins assigned to 0 : $P6_7$ to $P6_4$ 1 : $P7_3$ to $P7_0$	RW

NOTE:
1. Set the PACR register by the next instruction after setting the PRC2 bit in the PRCR register to 1 (write enable).

Figure 19.10 PACR Register

NMI Digital Debounce Register [1,2]

b7 b0

Symbol NDDR
Address 033E16
After Reset FF16

Function	Setting Range	RW
If the set value =n, - n = 0 to FE16; a signal with pulse width, greater than (n+1)/f8, is input into NMI / SD - n = FF16; the digital debounce filter is disabled and all signals are input	0016 to FF16	RW

NOTES:
1. Set the PACR register by the next instruction after setting the PRC2 bit in the PRCR register to 1 (write enable).
2. When using the NMI interrupt to exit from stop mode, set the NDDR registert to FF16 before entering stop mode.

P17 Digital Debounce Register[1]

b7 b0

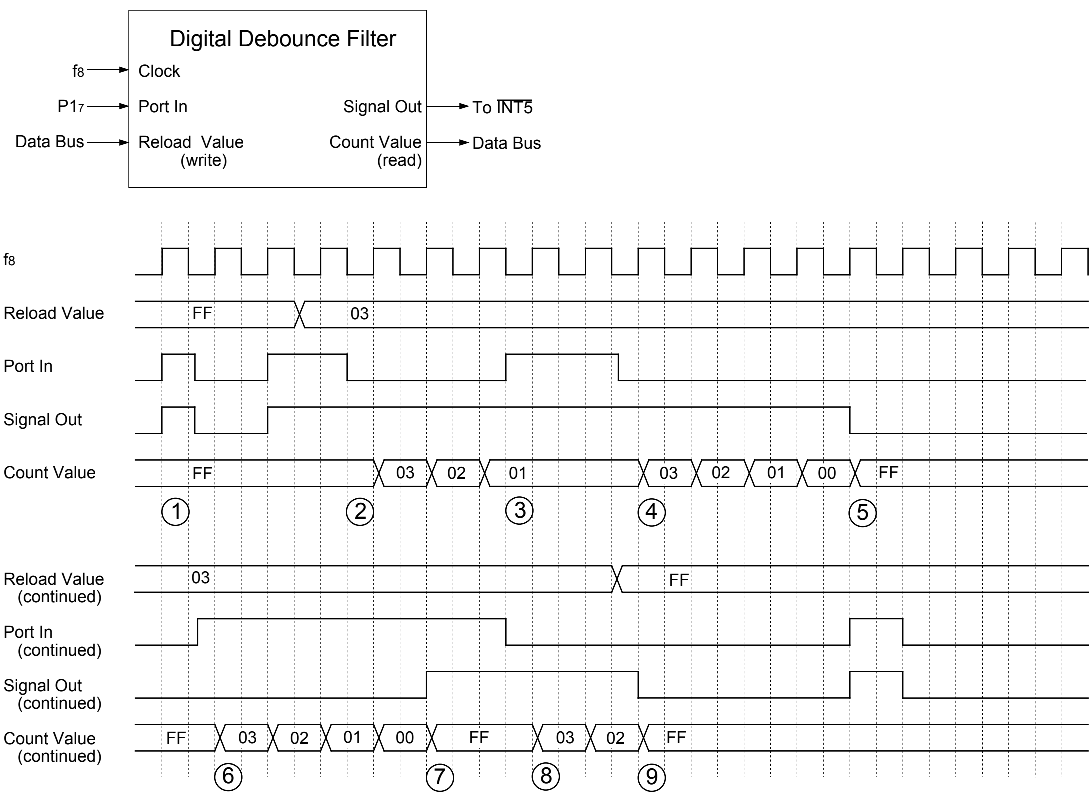
Symbol P17DDR
Address 033F16
After Reset FF16

Function	Setting Range	RW
If the set value =n, - n = 0 to FE16; a signal with pulse width, greater than (n+1)/f8, is input into INPC17/ INT5 - n = FF16; the digital debounce filter is disabled and all signals are input	0016 to FF16	RW

NOTE:
1. When using the INT5 interrupt to exit from stop mode, set the P17DDR registert to FF16 before entering stop mode.

Figure 19.11 NDDR and P17DDR Registers

• Example of $\overline{INT5}$ Digital Debounce Function (if P17DDR = 03_{16})



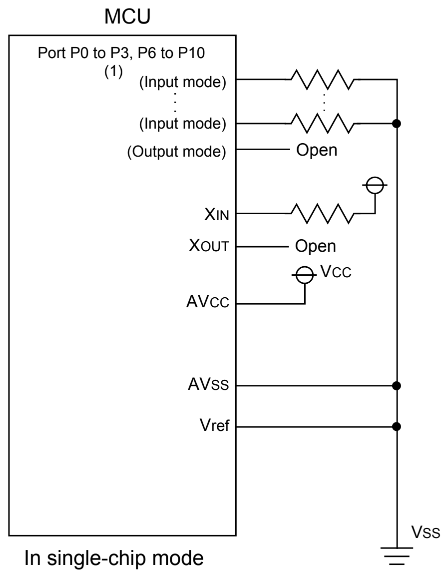
1. (Condition after reset). P17DDR=FF_{16}. Pin input signal will be output directly.
2. Set the P17DDR register to 03_{16}. The P17DDR register starts decrement along the f8 as a counter source, if the pin input level (e.g.,"L") and the signal output level (e.g.,"H") are not matched.
3. The P17DDR register will stops counting when the pin input level and the signal output level are matched (e.g., both levels are "H") while counting.
4. If the pin input level (e.g.,"L") and the signal output level (e.g.,"H") are not matched the P17DDR register will start decrement again after the setting value is reloaded.
5. When the P17DDR register is underflow, it stops counting and the signal output will output the same as pin input level (e.g."L").
6. If the pin input level (e.g.,"H") and the signal output level (e.g., "L") are not matched again, the P17DDR register will start decrement again after the setting value is reloaded.
7. When the P17DDR register is underflow, it stops counting and the signal output will output the same as pin input level (e.g."H").
8. If the pin input level (e.g.,"H") and the signal output level (e.g., "L") are not matched again, the P17DDR register will start decrement again after the setting value is reloaded.
9. Set the P17DDR register to FF_{16}. The P17DDR register starts counting after the setting value is reloaded. Pin input signal will be output directly.

Figure 19.12 Functioning of Digital Debounce Filter

Table 19.1 Unassigned Pin Handling in Single-chip Mode

Pin Name	Setting
Ports P0 to P3, P6 to P10	Enter input mode and connect each pin to VSS via a resistor (pull-down); or enter output mode and leave the pins open (1,2,4)
XOUT	Leave pin open (3)
XIN	Connect pin to VCC via a resistor (pull-up) (5)
AVCC	Connect pin to VCC
AVSS, VREF	Connect pin to VSS

NOTES:
1. If the port enters output mode and is left open, it is in input mode before output mode is entered by program after reset. While the port is in input mode, voltage level on the pins is indeterminate and power consumption may increase. Direction register setting may be changed by noise or failure caused by noise. Configure direction register settings regulary to increase the reliability of the program.
2. Use the shortest possible wiring to connect the MCU pins to unassigned pins (within 2 cm).
3. When the external clock is applied to the XIN pin, set the pin as written above.
4. In the 64-pin package, set bits PACR2, PACR1, and PACR0 in the PACR register to 010_2. In the 80-pin package, set bits PACR2, PACR1, and PACR0 to 011_2.
5. When the main clock oscillation is not used, set the CM05 bit in the CM0 register to 1 (main clock stops) to reduce power consumption.



NOTE:
1. When using the 64-pin package, set bits PACR2, PACR1, and PACR0 to 010_2.
When using the 80-pin package, set bits PACR2, PACR1, and PACR0 to 011_2.

Figure 19.13 Unassigned Pin Handling

20. Flash Memory Version

20.1 Flash Memory Performance

In the flash memory version, rewrite operation to the flash memory can be performed in four modes: CPU rewrite mode, standard serial I/O mode, parallel I/O mode, and CAN I/O mode.

Table 20.1 lists specifications of the flash memory version. (Refer to **Table 1.1** or **Table 1.2** for the items not listed in **Table 20.1.**

Table 20.1 Flash Memory Version Specifications

Item		Specification
Flash memory operating mode		4 modes (CPU rewrite, standard serial I/O, parallel I/O, CAN I/O)(3)
Erase block		See **Figures 20.1 to 20.3** Flash Memory Block Diagram
Program method		In units of word
Erase method		Block erase
Program, erase control method		Program and erase controlled by software command
Protect method		Blocks 0 to 5 are write protected by FMR16 bit. In addition, the block 0 and block 1 are write protected by FMR02 bit
Number of commands		5 commands
Program/Erase Endurance(1)	Block 0 to 5 (program area)	100 times 1,000 times (See **Tables 1.6 to 1.8**)
	Block A and B (data are) (2)	100 times 10,000 times (See **Tables 1.6 to 1.8**)
Data Retention		20 years (Topr = 55ЎC)
ROM code protection		Parallel I/O, standard serial I/O, and CAN I/O modes are supported.

NOTES:

1. Program and erase endurance definition
   Program and erase endurance are the erase endurance of each block. If the program and erase endurance are n times (n=100,1000,10000), each block can be erased n times. For example, if a 2-Kbyte block A is erased after writing 1 word data 1024 times, each to different addresses, this is counted as one program and erasure. However, data cannot be written to the same address more than once without erasing the block. (Rewrite disabled)
2. To use the limited number of erasure efficiently, write to unused address within the block instead of rewrite. Erase block only after all possible address are used. For example, an 8-word program can be written 128 times before erase is necessary. Maintaining an equal number of erasure between Block A and B will also improve efficiency. We recommend keeping track of the number of times erasure is used.
3. The M16C/29 Group, T-ver./V-ver. does not support the CAN I/O mode.

Table 20.2. Flash Memory Rewrite Modes Overview

Flash memory rewrite mode	CPU rewrite mode	Standard serial I/O mode	Parallel I/O mode	CAN I/O mode
Function	The user ROM area is rewritten when the CPU excutes software command from the CPU. EW0 mode: Rewrite in area other than flash memory EW1 mode: Rewrite in flash memory	The user ROM area is rewritten using a dedicated serial programmer. Standard serial I/O mode 1: Clock synchronous serial I/O Standard serial I/O mode 2: UART	The user ROM areas are rewritten using a dedicated parallel programmer.	The user ROM areas is rewritten using a dedicated CAN programmer.
Areas which can be rewritten	User ROM area	User ROM area	User ROM area	User ROM area
Operation mode	Single chip mode	Boot mode	Parallel I/O mode	Boot mode
ROM programmer	None	Serial programmer	Parallel programmer	CAN programmer

20.1.1 Boot Mode

The MCU enters boot mode when a hardware reset is performed while a high-level ("H") signal is applied to pins CNVSS and P86 or while an "H" signal is applied to pins CNVSS and P16 and a low-level ("L") signal is applied to the P85. A program in the boot ROM area is executed.

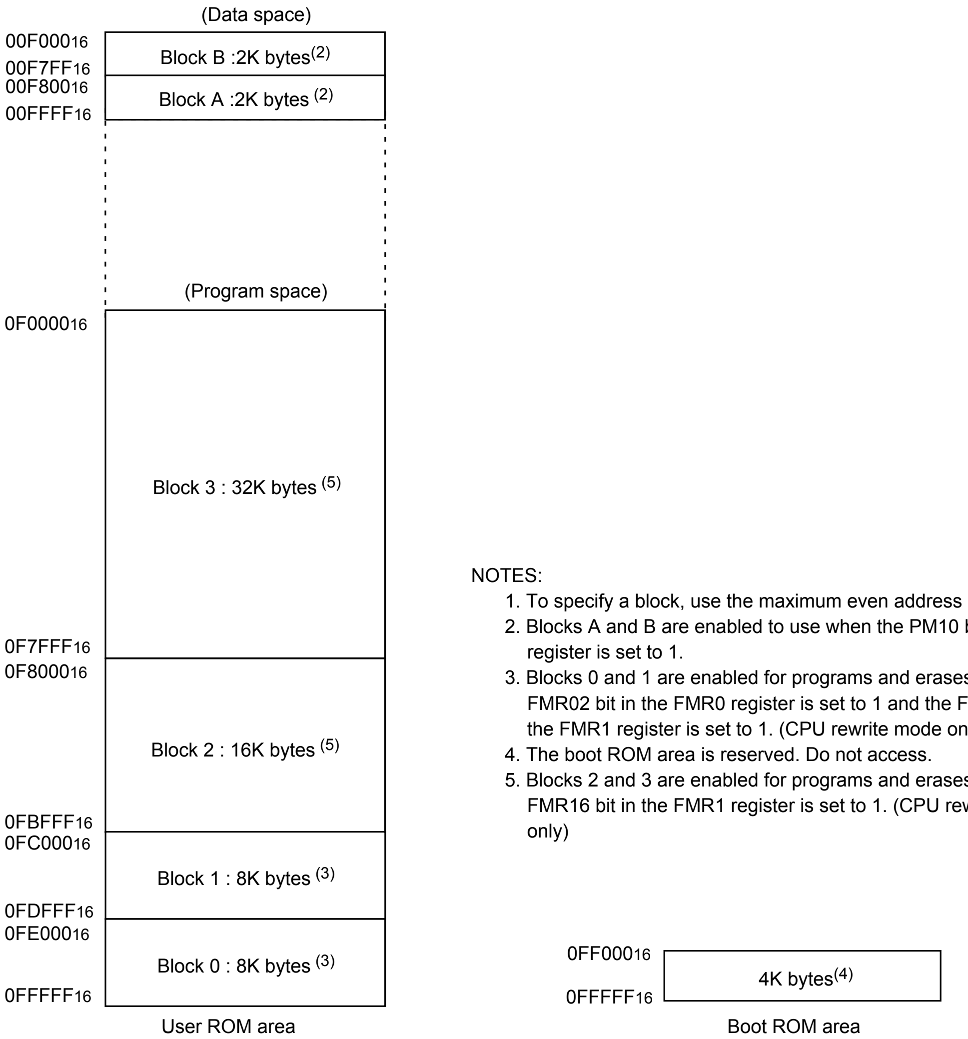
The boot ROM area is reserved. The boot ROM area stores the rewrite control program for a standard serial I/O mode before shipping. Do not rewrite the boot ROM area.

20.2 Memory Map

The flash memory contains the user ROM area and the boot ROM area (reserved area). **Figures 20.1** to **20.3** show a block diagram of the flash memory. The user ROM area has space to store the MCU operation program in single-chip mode and two 2-Kbyte spaces: the block A and B.

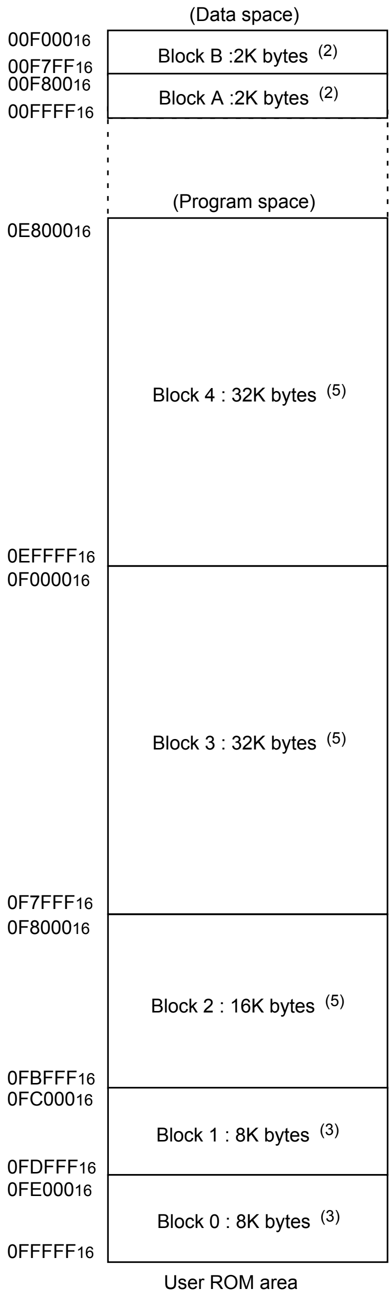
The user ROM area is divided into several blocks. The user ROM area can be rewritten in CPU rewrite, standard serial I/O, parallel I/O, or CAN I/O mode.

However, to rewrite program in block 0 and 1 in CPU rewrite mode, set the FMR02 bit in the FMR0 register to 1 (block 0, 1 rewrite enabled) and the FMR16 bit in the FMR1 register to 1 (blocks 0 to 5 rewrite enabled). Also, to rewrite program in blocks 2 to 5 in CPU rewrite mode, set the FMR16 bit in the FMR1 register to 1 (blocks 0 to 5 rewrite enabled). When the PM10 bit in the PM1 register is set to 1 (data space access enabled), blocks A and B can be available for use.



NOTES:
1. To specify a block, use the maximum even address in the block.
2. Blocks A and B are enabled to use when the PM10 bit in the PM1 register is set to 1.
3. Blocks 0 and 1 are enabled for programs and erases when the FMR02 bit in the FMR0 register is set to 1 and the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)
4. The boot ROM area is reserved. Do not access.
5. Blocks 2 and 3 are enabled for programs and erases when the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)

Figure 20.1 Flash Memory Block Diagram (ROM capacity 64 Kbytes)



NOTES:
1. To specify a block, use the maximum even address in the block.
2. Blocks A and B are enabled for use when the PM10 bit in the PM1 register is set to 1.
3. Blocks 0 and 1 are enabled for programs and erasure when the FMR02 bit in the FMR0 register is set to 1 and the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)
4. The Boot ROM area is reserved. Do not rewrite.
5. Blocks 2 to 4 are enabled for programs and erasure when the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)

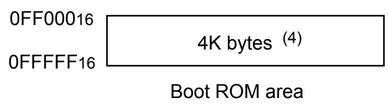
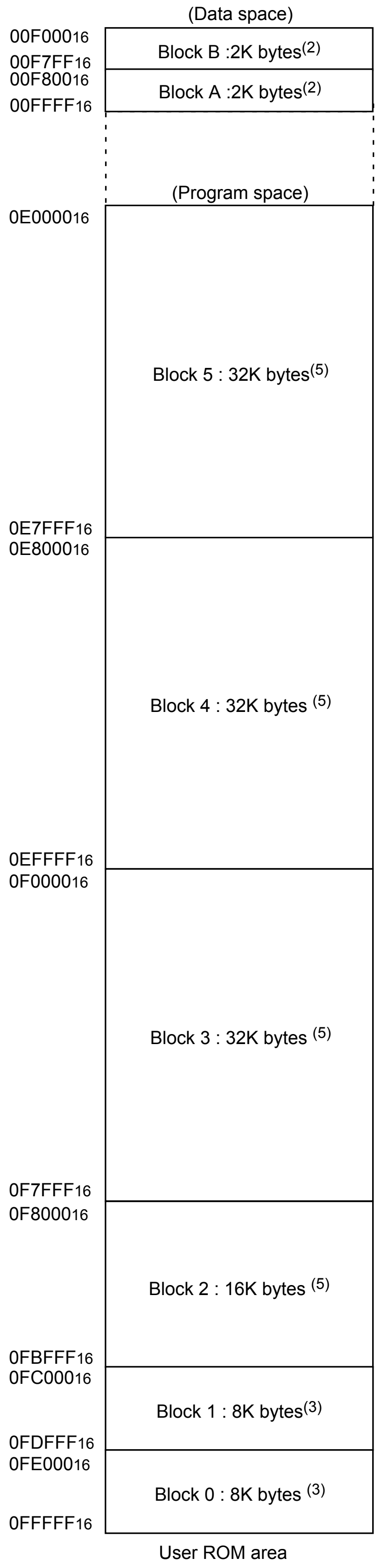


Figure 20.2 Flash Memory Block Diagram (ROM capacity 96 Kbytes)



NOTES:
1. To specify a block, use the maximum even address in the block.
2. Blocks A and B are enabled to use when the PM10 bit in the PM1 register is set to 1.
3. Blocks 0 and 1 are enabled for programs and erases when the FMR02 bit in the FMR0 register is set to 1 and the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)
4. The boot ROM area is reserved. Do not access.
5. Blocks 2 to 5 are enabled for programs and erases when the FMR16 bit in the FMR1 register is set to 1. (CPU rewrite mode only)

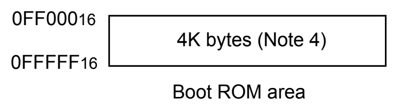


Figure 20.3 Flash Memory Block Diagram (ROM capacity 128 Kbytes)

20.3 Functions To Prevent Flash Memory from Rewriting

The flash memory has a built-in ROM code protect function for parallel I/O mode and a built-in ID code check function for standard input/output mode to prevent the flash memory from reading or rewriting.

20.3.1 ROM Code Protect Function

The ROM code protect function disables reading or changing the contents of the on-chip flash memory in parallel I/O mode. **Figure 20.4** shows the ROMCP address. The ROMCP address is located in a user ROM area. To enable ROM code protect, set the ROMCP1 bit to "00_2", "01_2", or "10_2" and set the bit 5 to bit 0 to "111111_2".

To cancel ROM code protect, erase the block including the the ROMCP register in CPU rewrite mode or standard serial I/O mode.

20.3.2 ID Code Check Function

Use the ID code check function in standard serial input/output mode. Unless the flash memory is blank, the ID code sent from the programmer and the 7-byte ID code written in the flash memory are compared for match. If the ID codes do not match, the commands sent from the programmer are not acknowledged. The ID code consists of 8-bit data, starting with the first byte, into addresses, $0FFFDF_{16}$, $0FFFE3_{16}$, $0FFFEB_{16}$, $0FFFEF_{16}$, $0FFFF3_{16}$, $0FFFF7_{16}$, and $0FFFFB_{16}$. The flash memory must have a program with the ID code set in these addresses.

ROM Code Protect Control Address(5)

b7	b6	b5	b4	b3	b2	b1	b0
				1	1	1	1

Symbol: ROMCP
Address: 0FFFFF$_{16}$
Factory Setting: FF$_{16}$ (4)

Bit Symbol	Bit Name	Function	RW
(b5-b0)	Reserved Bit	Set to 1	RW
ROMCP1	ROM Code Protect Level 1 Set Bit (1, 2, 3, 4)	b7 b6 00: } 01: } Enables protect 10: } 11: Disables protect	RW RW

NOTES:
1. When the ROM code protect is active by the ROMCP1 bit setting, the flash memory is protected against reading or rewriting in parallel I/O mode.
2. Set the bit 5 to bit 0 to 111111$_2$ when the ROMCP1 bit is set to a value other than 11$_2$. When the bit 5 to bit 0 are set to values other than 111111$_2$, the ROM code protection may not become active by setting the ROMCP1 bit to a value other than 11$_2$.
3. To make the ROM code protection inactive, erase a block including the ROMCP address in standard serial I/O mode or CPU rewrite mode.
4. The ROMCP address is set to FF$_{16}$ when a block, including the ROMCP address, is erased.
5. When a value of the ROMCP address is 00$_{16}$ or FF$_{16}$, the ROM code protect function is disabled.

Figure 20.4 ROMCP Address

Address		
0FFFDF$_{16}$ to 0FFFDC$_{16}$	ID1	Undefined instruction vector
0FFFE3$_{16}$ to 0FFFE0$_{16}$	ID2	Overflow vector
0FFFE7$_{16}$ to 0FFFE4$_{16}$		BRK instruction vector
0FFFEB$_{16}$ to 0FFFE8$_{16}$	ID3	Address match vector
0FFFEF$_{16}$ to 0FFFEC$_{16}$	ID4	Single step vector
0FFFF3$_{16}$ to 0FFFF0$_{16}$	ID5	Watchdog timer vector
0FFFF7$_{16}$ to 0FFFF4$_{16}$	ID6	$\overline{\text{DBC}}$ vector
0FFFFB$_{16}$ to 0FFFF8$_{16}$	ID7	$\overline{\text{NMI}}$ vector
0FFFFF$_{16}$ to 0FFFFC$_{16}$	ROMCP	Reset vector

4 bytes

Figure 20.5 Address for ID Code Stored

20.4 CPU Rewrite Mode

In CPU rewrite mode, the user ROM area can be rewritten when the CPU executes software commands. The user ROM area can be rewritten with MCU mounted on a board without using the ROM writer. The program and block erase commands are executed only in the user ROM area.

When the interrupt requests are generated during the erase operation in CPU rewirte mode, the flash memory offers an erase suspend function to suspend the erase operation and process the interrupt operation. During the erase suspend function is operated, the user ROM area can be read by program.

Erase-write(EW) 0 mode and erase-write 1 mode are provided as CPU rewrite mode. **Table 20.3** lists differences between EW mode 0 and EW mode 1. One wait is required for the CPU erase-write control.

Table 20.3 EW Mode 0 and EW Mode 1

Item	EW mode 0	EW mode 1
Operation mode	Single chip mode	Single chip mode
Areas in which a rewrite control program can be located	User ROM area	User ROM area
Areas where rewrite control program can be executed(2)	The rewrite control program must be transferred to any other than the flash memory (e.g., RAM) before being executed	The rewrite control program can be excuted in the user ROM area
Areas which can be rewritten	User ROM area	User ROM area However, this excludes blocks with the rewrite control program
Software command Restrictions	None	• Program, block erase command Cannot be executed in a block having the rewite control program • Read Status Register command Cannot be executed
Mode after programming or erasing	Read Status Register Mode	Read Array mode
CPU state during auto-write and auto-erase	Operating	In a hold state (I/O ports retain the state before the command is excuted(1)
Flash memory status detection	• Read the FMR00, FMR06, and FMR07 bits in the FMR0 register by program • Execute the read status register command to read bits SR7, SR5, and SR4.	Read the FMR00, FMR06, and FMR07 bits in the FMR0 registerby program
Condition for transferring to erase-suspend(3)	Set bits FMR40 and FMR41 in the FMR4 register to 1 by program.	The FMR40 bit in the FMR4 register is set to 1 and the interrupt request of an acknowledged interrupt is generated

NOTES:
1. Do not generate a DMA transfer.
2. Block 1 and Block 0 are enabled for rewrite by setting FMR02 bit in the FMR0 register to 1 and setting FMR16 bit in the FMR1 register to 1. Block 2 to Block 5 are enabled for rewrite by setting FMR16 bit in the FMR1 register to 1.
3. The time, until entering erase suspend and reading flash is enabled, is maximum *td(SR-ES)* after satisfying the conditions.

20.4.1 EW Mode 0

The MCU enters CPU rewrite mode by setting the FMR01 bit in the FMR0 register to 1 (CPU rewrite mode enabled) and is ready to accept software commands. EW mode 0 is selected by setting the FMR11 bit in the FMR1 register to 0.
To set the FMR01 bit to 1, set to 1 after first writing 0. The software commands control programming and erasing. The FMR0 register or the status register indicates whether a programming or erasing operations is completed.
When entering the erase-suspend during the auto-erasing, set the FMR40 bit to 1 (erase-suspend enabled) and the FMR41 bit to 1 (suspend request). After waiting for td(SR-ES) and verifying the FMR46 bit is set to 1 (auto-erase stop), access to the user ROM area. When setting the FMR41 bit to 0 (erase restart), auto-erasing is restarted.

20.4.2 EW Mode 1

EW mode 1 is selected by setting the FMR11 bit to 1 after the FMR01 bit is set to 1 (set to 1 after first writing 0).
The FMR0 register indicates whether or not a programming or an erasing operation is completed. Read status register cannot be read in EW mode 1.
When an erase/program command is initiated, the CPU halts all program execution until the command operation is completed or erase-suspend request is generated.
When enabling an erase-suspend function, set the FMR40 bit to 1 (erase suspend enabled) and execute block erase commands. Also, the interrupt to transfer to erase-suspend must be set enabled preliminarily. When entering erase-suspend after td(SR-ES) from an interrupt is requested, interrupts can be accepted.
When an interrupt request is generated, the FMR41 bit is automatically set to 1 (suspend request) and an auto-erasing is suspended. If an auto-erasing has not completed (when the FMR00 bit is 0) after an interrupt process is completed, set the FMR41 bit to 0 (erase restart) and execute block erase commands again.

20.5 Register Description

Figure 20.6 shows the flash memory control register 0 and flash memory control register 1. **Figure 20.7** shows the flash memory control register 4.

20.5.1 Flash Memory Control Register 0 (FMR0)

•FMR 00 Bit

The FMR00 bit indicates the operating state of the flash memory. Its value is 0 while the program, erase, or erase-suspend command is being executed, otherwise, it is 1.

•FMR01 Bit

The MCU can accept commands when the FMR01 bit is set to 1 (CPU rewrite mode). To set the FMR01 bit to 1, first set it to 0 and then 1. The FMR01 bit is set to 0 only by writing 0.

•FMR02 Bit

The combined settings of bits FMR02 and FMR16 enable program and erase in the user ROM area. See **Table 20.4** for setting details. To set the FMR02 bit to 1, first set it to 0 and then 1. The FMR02 bit is valid only when the FMR01 bit is set to 1 (CPU rewrite mode enable).

•FMSTP Bit

The FMSTP bit initializes the flash memory control circuits and minimizes power consumption in the flash memory. Access to the on-chip flash memory is disabled when the FMSTP bit is set to 1. Set the FMSTP bit by program in a space other than the flash memory.

Set the FMSTP bit to 1 if one of the following occurs:

•A flash memory access error occurs during erasing or programming in EW mode 0 (FMR00 bit does not switch back to 1 (ready)).

•Low-power consumption mode or on-chip oscillator low-power consumption mode is entered.

Figure 20.10 shows a flow chart illustrating how to start and stop the flash memory before and after entering low power mode. Follow the procedure in this flow chart.

When entering stop or wait mode while the CPU rewrite mode is disabled, do not set the FMR0 register because the on-chip flash memory is automatically turned off and turned back on when exiting.

•FMR06 Bit

The FMR06 bit is a read-only bit indicating an auto-program operation state. The FMR06 bit is set to 1 when a program error occurs; otherwise, it is set to 0. For details, refer to **20.8.4 Full Status Check**.

•FMR07 Bit

The FMR07 bit is a read-only bit indicating an auto-erase operation status. The FMR07 bit is set to 1 when an erase error occurs; otherwise, it is set to 0. For details, refer to **20.8.4 Full Status Check**.

Figure 20.8 shows a EW mode 0 set/reset flowchart, **Figure 20.9** shows a EW mode 1 set/reset flow-chart.

20.5.2 Flash Memory Control Register 1 (FMR1)

•FMR11 Bit

EW mode 1 is entered by setting the FMR11 bit to 1 (EW mode 1). The FMR11 bit is valid only when the FMR01 bit is set to 1.

•FMR16 Bit

The combined setting of bits FMR02 and FMR16 enables program and erase in the user ROM area. To set the FMR16 bit to 1, first set it to 0 and then 1. The FMR16 bit is valid only when the FMR01 bit is set to 1 (CPU rewrite mode enable).

•FMR17 Bit

If the FMR17 bit is set to 1 (with wait state), 1 wait state is inserted when blocks A and B are accessed, regardless of the content of the PM17 bit in the PM1 register. The PM17 bit setting is reflected to access other blocks and internal RAM, regardless of the FMR17 bit setting.
Set the FMR17 bit to 1 (with wait state) to rewrite more than 100 times (U7, U9).

Table 20.4 Protection using FMR16 and FMR02

FMR16	FMR02	Block A, Block B	Block 0, Block 1	other user block
0	0	write enabled	write disabled	write disabled
0	1	write enabled	write disabled	write disabled
1	0	write enabled	write disabled	write enabled
1	1	write enabled	write enabled	write enabled

20.5.3 Flash Memory Control Register 4 (FMR4)

•FMR40 Bit

The erase-suspend function is enabled when the FMR40 bit is set to 1 (enabled).

•FMR41 Bit

When the FMR41 bit is set to 1 by program during auto-erasing in EW mode 0, erase-suspend mode is entered. In EW mode 1, the FMR41 bit is automatically set to 1 (suspend request) to enter erase-suspend mode when an enabled interrupt request is generated. Set the FMR41 bit to 0 (erase restart) to restart an auto-erasing operation.

•FMR46 Bit

The FMR46 bit is set to 0 during auto-erasing. It is set to 1 in erase-suspend mode.
Do not access to flash memory when the FMR46 bit is set to 0.

Flash Memory Control Register 0

b7	b6	b5	b4	b3	b2	b1	b0
		0	0				

Symbol	Address	After Reset
FMR0	01B7$_{16}$	00000001$_2$

Bit Symbol	Bit Name	Function	RW
FMR00	RY/$\overline{BY}$ status flag	0: Busy (during writing or erasing) 1: Ready	RO
FMR01	CPU rewrite mode select bit (1)	0: Disables CPU rewrite mode (Disables software command) 1: Enables CPU rewrite mode (Enables software commands)	RW
FMR02	Block 0, 1 rewrite enable bit (2)	Set write protection for user ROM area (see **Table 20.4**)	RW
FMSTP	Flash memory stop bit (3, 5)	0: Starts flash memory operation 1: Stops flash memory operation (Enters low-power consumption state and flash memory reset)	RW
$\overline{(b5\text{-}b4)}$	Reserved bit	Set to 0	RW
FMR06	Program status flag (4)	0: Successfully completed 1: Completion error	RO
FMR07	Erase status flag (4)	0: Successfully completed 1: Completion error	RO

NOTES:
1. Set the FMR01 bit to 1 immediately after setting it first to 0. Do not generate an interrupt or a DMA transfer between setting the bit to 0 and setting it to 1. Set this bit while the P8$_5$/$\overline{NMI}$/$\overline{SD}$ pin is held "H" when selecting the $\overline{NMI}$ function. Set by program in a space other than the flash memory in EW mode 0. Set this bit to read alley mode and 0.
2. Set this bit to 1 immediately after setting it first to 0 while the FMR01 bit is set to 1. Do not generate an interrupt or a DMA transfer between setting this bit to 0 and setting it to 1.
3. Set this bit in a space other than the flash memory by program. When this bit is set to 1, access to flash memory will be denied. To set this bit to 0 after setting it to 1, wait for 10 usec. or more after setting it to 1. To read data from flash memory after setting this bit to 0, maintain tps wait time before accessing flash memory.
4. This bit is set to 0 by executing the clear status command.
5. This bit is enabled when the FMR01 bit is set to 1 (CPU rewrite mode). If the FMR01 bit is set to 0, this bit can be set to 1 by writing 1 to the FMR01 bit. However, the flash memory does not enter low-power consumption status and it is not initialized.

Flash Memory Control Register 1

b7	b6	b5	b4	b3	b2	b1	b0
		0	X	X	X		X

Symbol	Address	After Reset
FMR1	01B5$_{16}$	000XXX0X$_2$

Bit Symbol	Bit Name	Function	RW
$\overline{(b0)}$	Reserved bit	When read, the content is undefined	RO
FMR11	EW mode 1 select bit (1)	0: EW mode 0 1: EW mode 1	RW
$\overline{(b3\text{-}b2)}$	Reserved bit	When read, the content is undefined	RO
$\overline{(b4)}$	Nothing is assigned. If necessary, set to 0. When read, the content is undefined		—
$\overline{(b5)}$	Reserved bit	Set to 0	RW
FMR16	Block 0 to 5 rewrite enable bit (2)	Set write protection for user ROM space (see **Table 20.4**) 0: Disable 1: Enable	RW
FMR17	Block A, B access wait bit (3)	0: PM17 enabled 1: With wait state (1 wait)	RW

NOTES:
1. Set the FMR11 bit to 1 immediately after setting it first to 0 while the FMR01 bit is set to 1. Do not generate an interrupt or a DMA transfer between setting the bit to 0 and setting it to 1. Set this bit while the P8$_5$/$\overline{NMI}$/$\overline{SD}$ pin is held "H" when the $\overline{NMI}$ function is selected. If the FMR01 bit is set to 0, the FMR01 bit and FMR11 bit are both set to 0.
2. Set this bit to 1 immediately after setting it first to 0 while the FMR01 bit is set to 1. Do not generate an interrupt or a DMA transfer between setting this bit to 0 and setting it to 1.
3. When rewriting more than 100 times, set this bit to 1 (with wait state). When the FMR17 bit is set to1(with wait state), regardless of the PM17 bit setting, 1 wait state is inserted when accessing to blocks A and B. The PM17 bit setting is enabled, regardless of the FMR17 bit setting, as to the access to other block and the internal RAM.

Figure 20.6 FMR0 and FMR1 Registers

Flash Memory Control Register 4

b7	b6	b5	b4	b3	b2	b1	b0
0		0	0	0	0		

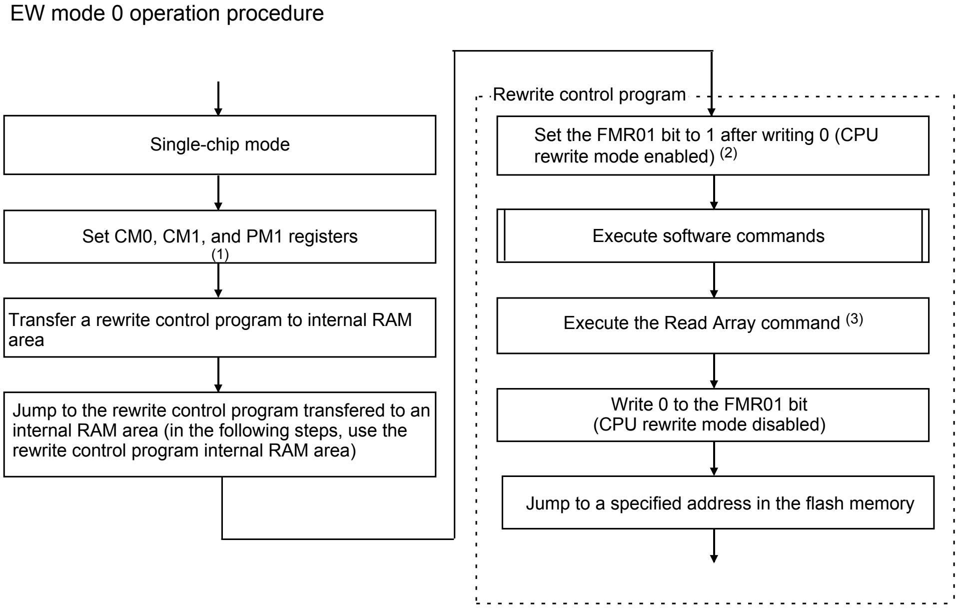
Symbol: FMR4 Address: $01B3_{16}$ After Reset: 01000000_2

Bit Symbol	Bit Name	Function	RW
FMR40	Erase suspend function enable bit (1)	0: Disabled 1: Enabled	RW
FMR41	Erase suspend request bit (2)	0: Erase restart 1: Suspend request	RW
(b5-b2)	Reserved bit	Set to 0	RO
FMR46	Erase status	0: During auto-erase operation 1: Auto-erase stop (erase suspend mode)	RO
(b7)	Reserved bit	Set to 0	RW

NOTES:

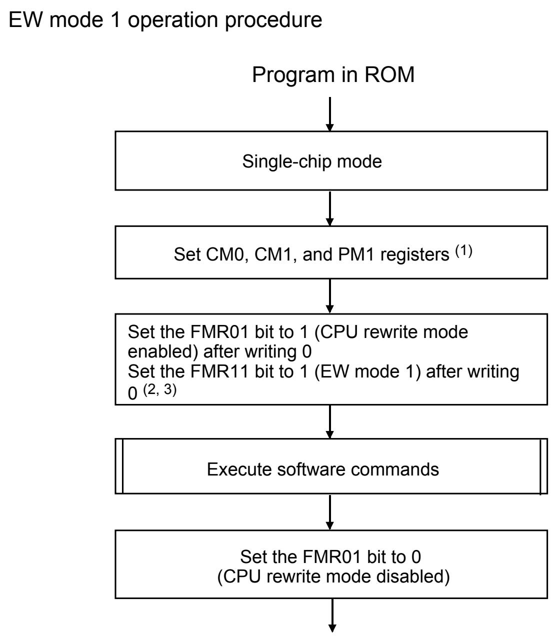
1. Set the FMR40 bit to 1 immediately after setting it first to 0. Do not generate any interrupt or DMA transfer between setting the bit to 0 and setting it to 1. Set by program in space other than the flash memory in EW mode 0.
2. The FMR41 bit is valid only when the FMR40 bit is set to 1. The FMR41 bit can be written only between executing an erase command and completing erase (this bit is set to 0 other than the above duration). The FMR41 bit can be set to 0 or 1 by program in EW mode 0. In EW mode 1, the FMR41 bit is automatically set to 1 when the FMR40 bit is 1 and a maskable interrupt is generated during erasing. The FMR41 bit cannot be set to 1 by program (it can be set to 0 by program).

Figure 20.7 FMR4 Register



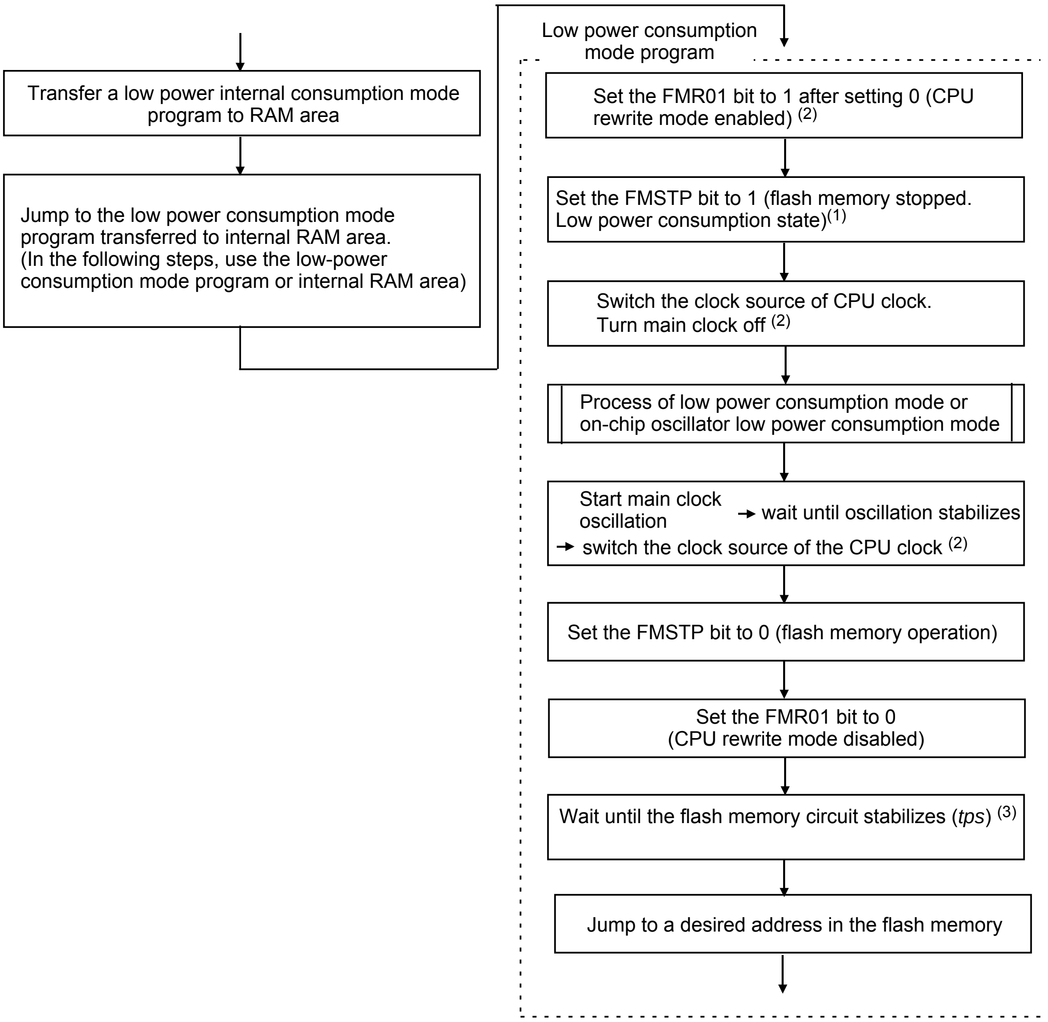
NOTES:
1. Select 10 MHz or below for CPU clock using the CM06 bit in the CM0 register and bits CM17 to 16 in the CM1 register. Also, set the PM17 bit in the PM1 register to 1 (with wait state).
2. Set the FMR01 bit to 1 immediately after setting it to 0. Do not generate an interrupt or a DMA transfer between setting the bit to 0 and setting it to 1. Set the FMR01 bit in a space other than the internal flash memory. Also, set only when the P85/NMI/SD pin is “H” at the time of the NMI function selected.
3. Disables the CPU rewrite mode after executing the read array command.

Figure 20.8 Setting and Resetting of EW Mode 0



NOTES:
1. Select 10 MHz or below for CPU clock using the CM06 bit in the CM0 register and bits CM17 to 16 in the CM1 register. Also, set the PM17 bit in the PM1 register to 1 (with wait state).
2. Set the FMR01 bits to 1 immediately after setting it to 0. Do not generate an interrupt or a DMA transfer between setting the bit to 0 and setting the bit to 1. Set the FMR01 bit in a space other than the internal flash memory. Set only when the P85/NMI/SD pin is “H” at the time of the NMI function selected.
3. Set the FMR11 bit to 1 immediately after setting it to 0 while the FMR01 bit is set to 1. Do not generate an interrupt or a DMA transfer between setting the FMR11 bit to 0 and setting it to 1.

Figure 20.9 Setting and Resetting of EW Mode 1



NOTES:
1. Set the FMRSTP bit to 1 after setting the FMR01 bit to 1 (CPU rewrite mode).
2. Wait until the clock stabilizes to switch the clock source of the CPU clock to the main clock or the sub clock.
3. Add a *tps* wait time by a program. Do not access the flash memory during this wait time.

Figure 20.10 Processing Before and After Low Power Dissipation Mode

20.6 Precautions in CPU Rewrite Mode

Described below are the precautions to be observed when rewriting the flash memory in CPU rewrite mode.

20.6.1 Operation Speed

When the CPU clock source is the main clock, set the CPU clock frequency at 10 MHz or less with the CM06 bit in the CM0 register and bits CM17 and CM16 in the CM1 register, before entering CPU rewrite mode (EW mode 0 or EW mode 1). Also, when selecting f_3(ROC) of a on-chip oscillator as a CPU clock source, set bits ROCR3 and ROCR2 in the ROCR register to the CPU clock division rate at “divide-by-4” or “divide-by-8”, before entering CPU rewrite mode (EW mode 0 or EW mode 1).
In both cases, set the PM17 bit in the PM1 register to 1 (with wait state).

20.6.2 Prohibited Instructions

The following instructions cannot be used in EW mode 0 because the CPU tries to read data in the flash memory: UND instruction, INTO instruction, JMPS instruction, JSRS instruction, and BRK instruction

20.6.3 Interrupts

EW Mode 0

- To use interrupts having vectors in a relocatable vector table, the vectors must be relocated to the RAM area.
- The $\overline{\text{NMI}}$ and watchdog timer interrupts are available since registers FMR0 and FMR1 are forcibly reset when either interrupt occurs. However, the interrupt program, which allocates the jump addresses for each interrupt routine to the fixed vector table, is needed. Flash memory rewrite operation is aborted when the $\overline{\text{NMI}}$ or watchdog timer interrupt occurs. Set the FMR01 bit to 1 and execute the rewrite and erase program again after exiting the interrupt routine.
- The address match interrupt can not be used since the CPU tries to read data in the flash memory.

EW Mode 1

- Do not acknowledge any interrupts with vectors in the relocatable vector table or the address match interrupt during the auto program period or auto erase period with erase-suspend function disabled.

20.6.4 How to Access

To set bit FMR01, FMR02, FMR11 or FMR16 to 1, write 1 immediately after setting to 0. Do not generate an interrupt or a DMA transfer between the instruction to set the bit to 0 and the instruction to set it to 1. When the $\overline{\text{NMI}}$ function is selected, set the bit while an “H” signal is applied to the $P8_5$/$\overline{\text{NMI}}$/$\overline{\text{SD}}$ pin.

20.6.5 Writing in the User ROM Area

20.6.5.1 EW Mode 0

- If the supply voltage drops while rewriting the block where the rewrite control program is stored, the flash memory can not be rewritten, because the rewrite control program is not correctly rewritten. If this error occurs, rewrite the user ROM area in standard serial I/O mode or parallel I/O mode.

20.6.5.2 EW Mode 1

- Do not rewrite the block where the rewrite control program is stored.

20.6.6 DMA Transfer

In EW mode 1, do not generate a DMA transfer while the FMR00 bit in the FMR0 register is set to 0. (during the auto-programming or auto-erasing).

20.6.7 Writing Command and Data

Write the command codes and data to even addresses in the user ROM area.

20.6.8 Wait Mode

When entering wait mode, set the FMR01 bit to 0 (CPU rewrite mode disabled) before executing the WAIT instruction.

20.6.9 Stop Mode

When entering stop mode, the following settings are required:

• Set the FMR01 bit to 0 (CPU rewrite mode disabled) and disable the DMA transfer before setting the CM10 bit to 1 (stop mode).

20.6.10 Low Power Consumption Mode and On-Chip Oscillator-Low Power Consumption Mode

If the CM05 bit is set to 1 (main clock stopped), do not execute the following commands.

• Program
• Block erase

20.7 Software Commands

Read or write 16-bit commands and data from or to even addresses in the user ROM area. When writing a command code, 8 high-order bits (D_{15}–D_8) are ignored.

Table 20.5 Software Commands

Command	First bus cycle			Second bus cycle		
	Mode	Address	Data (D_{15} to D_0)	Mode	Address	Data (D_{15} to D_0)
Read array	Write	X	$xxFF_{16}$			
Read status register	Write	X	$xx70_{16}$	Read	X	SRD
Clear status register	Write	X	$xx50_{16}$			
Program	Write	WA	$xx40_{16}$	Write	WA	WD
Block erase	Write	X	$xx20_{16}$	Write	BA	$xxD0_{16}$

SRD: Status register data (D_7 to D_0)
WA : Write address (However,even address)
WD : Write data (16 bits)
BA : Highest-order block address (However,even address)
X : Any even address in the user ROM area
xx : 8 high-order bits of command code (ignored)

20.7.1 Read Array Command (FF_{16})

The read array command reads the flash memory.

Read array mode is entered by writing command code $xxFF_{16}$ in the first bus cycle. Content of a specified address can be read in 16-bit unit after the next bus cycle. The MCU remains in read array mode until an another command is written. Therefore, contents of multiple addresses can be read consecutively.

20.7.2 Read Status Register Command (70_{16})

The read status register command reads the status register.

By writing command code $xx70_{16}$ in the first bus cycle, the status register can be read in the second bus cycle (Refer to **20.8 Status Register**). Read an even address in the user ROM area. Do not execute this command in EW mode 1.

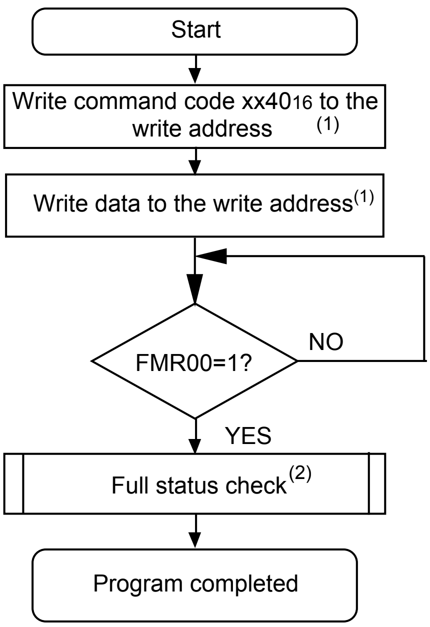
20.7.3 Clear Status Register Command (50_{16})

The clear status register command clears the status register to 0.

By writing $xx50_{16}$ in the first bus cycle, and bits FMR06 to FMR07 in the FMR0 register and bits SR4 to SR5 in the status register are set to 0.

20.7.4 Program Command (40_{16})

The program command writes 2-byte data to the flash memory.
Auto program operation (data program and verify) start by writing xx40_{16} in the first bus cycle and data to the write address specified in the second bus cycle. The address value specified in the first bus cycle must be the same even address as the write address secified in the second bus cycle.
The FMR00 bit in the FMR0 register indicates whether an auto-programming operation has been completed. The FMR00 bit is set to 0 during the auto-program and 1 when the auto-program operation is completed.
After the completion of auto-program operation, the FMR06 bit in the FMR0 register indicates whether or not the auto-program operation has been successfully completed. (Refer to **20.8.4 Full Status Check**).
Also, each block can disable programming command (Refer to **Table 20.4**).
An address that is already written cannot be altered or rewritten.
When commands other than the program command are executed immediately after executing the program command, set the same address as the write address specified in the second bus cycle of the program command, to the specified address value in the first bus cycle of the following command.
In EW mode 1, do not execute this command on the blocks where the rewrite control program is allocated.
In EW mode 0, the MCU enters read status register mode as soon as the auto-program operation starts and the status register can be read. The SR7 bit in the status register is set to 0 as soon as the auto-program operation starts. This bit is set to 1 when the auto-program operation is completed. The MCU remains in read status register mode until the read array command is written. After completion of the auto-program operation, the status register indicates whether or not the auto-program operation has been successfully completed.

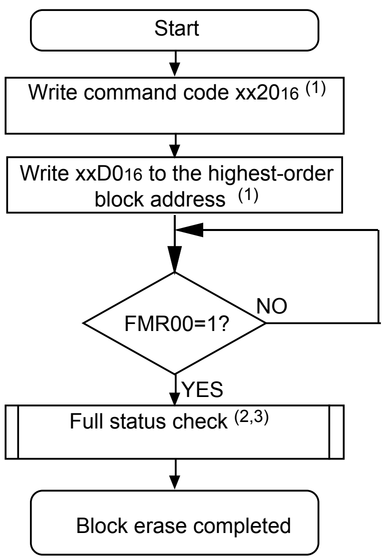


NOTES:
1. Write the command code and data at even address.
2. Refer to **Figure 20.14**.

Figure 20.11 Flow Chart of Program Command

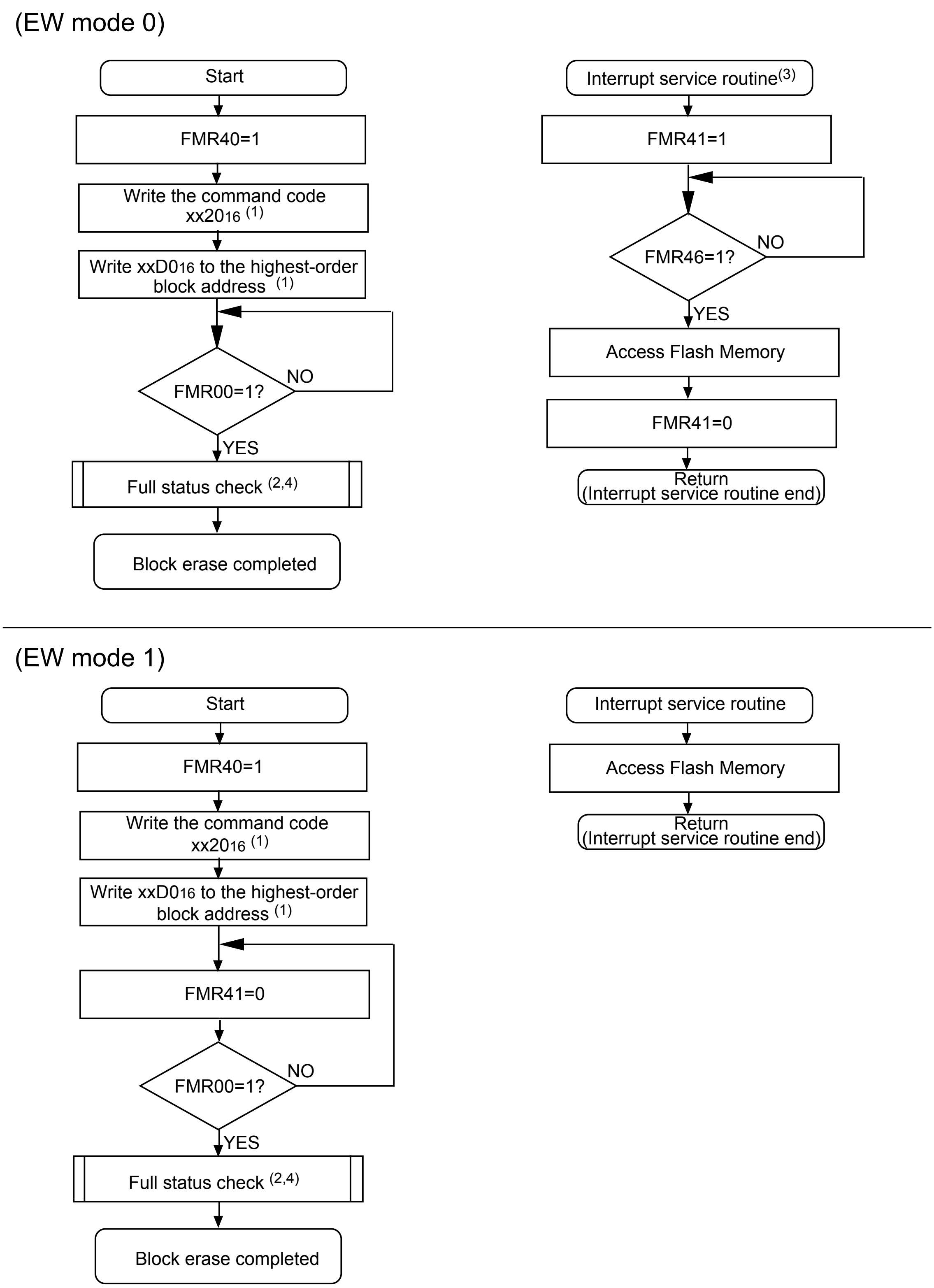
20.7.5 Block Erase

Auto erase operation (erase and verify) start in the specified block by writing xx2016 in the first bus cycle and xxD016 to the highest-order even addresse of a block in the second bus cycle.
The FMR00 bit in the FMR0 register indicates whether the auto-erase operation has been completed.
The FMR00 bit is set to 0 (busy) during the auto-erase and 1 (ready) when the auto-erase operation is completed.
When using the erase-suspend function in EW mode 0, verify whether a flash memory has entered erase suspend mode, by the FMR46 bit in the FMR4 register. The FMR46 bit is set to 0 during auto-erase operation and 1 when the auto-erase operation is completed (entering erase-suspend).
After the completion of an auto-erase operation, the FMR07 bit in the FMR0 register indicates whether or not the auto-erase operation has been successfully completed. (Refer to **20.8.4 Full Status Check**).
Also, each block can disable erasing. (Refer to **Table 20.4**).
Figure 20.12 shows a flow chart of the block erase command programming when not using the erase-suspend function. **Figure 20.12** shows a flow chart of the block erase command programming when using an erase-suspend function.
In EW mode 1, do not execute this command on the block where the rewrite control program is allocated.
In EW mode 0, the MCU enters read status register mode as soon as the auto-erase operation starts and the status register can be read. The SR7 bit in the status register is set to 0 at the same time the auto-erase operation starts. This bit is set to 1 when the auto-erase operation is completed. The MCU remains in read status register mode until the read array command is written.
When the erase error occurs, execute the clear status register command and block erase command at leaset three times until an erase error does not occur.



NOTES:
1. Write the command code and data at even address.
2. Refer to **Figure 20.14**.
3. Execute the clear status register command and block erase command at least 3 times until an erase error is not generated when an erase error is generated.

Figure 20.12 Flow Chart of Block Erase Command (when not using erase suspend function)



NOTES:
1. Write the command code and data to even address.
2. Execute the clear status register command and block erase command at least 3 times until an erase error is not generated when an erase error is generated.
3. In EW mode 0, allocate an interrupt vector table of an interrupt, to be used, to the RAM area
4. Refer to **Figure 20.14**.

Figure 20.13 Block Erase Command (at use erase suspend)

20.8 Status Register

The status register indicates the operating status of the flash memory and whether or not erase or program operation is successfully completed. Bits FMR00, FMR06, and FMR07 in the FMR0 register indicate the status of the status register.

Table 20.6 lists the status register.

In EW mode 0, the status register can be read in the following cases:

(1) Any even address in the user ROM area is read after writing the read status register command

(2) Any even address in the user ROM area is read from when the program or block erase command is executed until when the read array command is executed.

20.8.1 Sequence Status (SR7 and FMR00 Bits)

The sequence status indicates the flash memory operating status. It is set to 0 (busy) while the auto-program and auto-erase operation is being executed and 1 (ready) as soon as these operations are completed. This bit indicates 0 (busy) in erase-suspend mode.

20.8.2 Erase Status (SR5 and FMR07 Bits)

Refer to **20.8.4 Full Status Check**.

20.8.3 Program Status (SR4 and FMR06 Bits)

Refer to **20.8.4 Full Status Check**.

Table 20.6 Status Register

Bits in the SRD Register	Bits in the FMR0 Register	Status Name	Contents		Value After Reset
			0	1	
SR7 (D_7)	FMR00	Sequence status	Busy	Ready	1
SR6 (D_6)	——	Reserved	-	-	——
SR5 (D_5)	FMR07	Erase status	Completed normally	Terminated by error	0
SR4 (D_4)	FMR06	Program status	Completed normally	Terminated by error	0
SR3 (D_3)	——	Reserved	-	-	——
SR2 (D_2)	——	Reserved	-	-	——
SR1 (D_1)	——	Reserved	-	-	——
SR0 (D_0)	——	Reserved	-	-	——

• D_7 to D_0: Indicates the data bus which is read out when executing the read status register command.
• The FMR07 bit (SR5) and FMR06 bit (SR4) are set to 0 by executing the clear status register command.
• When the FMR07 bit (SR5) or FMR06 bit (SR4) is set to 1, the program and block erase command are not accepted.

20.8.4 Full Status Check

If an error occurs, bits FMR06 to FMR07 in the FMR0 register are set to 1, indicating a specific error. Therefore, execution results can be comfirmed by verifying these status bits (full status check).

Table 20.7 lists errors and FMR0 register state. **Figure 20.14** shows a flow chart of the full status check and handling procedure for each error.

Table 20.7 Errors and FMR0 Register Status

FMR0 register (SRD register) status		Error	Error occurrence condition
FMR07 (SR5)	FMR06 (SR4)		
1	1	Command sequence error	• An incorrect commands is written • A value other than xxD0$_{16}$ or xxFF$_{16}$ is written in the second bus cycle of the block erase command (1) • When the block erase command is executed on an protected block • When the program command is executed on protected blocks
1	0	Erase error	• The block erase command is executed on an unprotected block but the program operation is not successfully completed
0	1	Program error	• The program command is executed on an unprotected block but the program operation is not successfully completed

Note 1: The flash memory enters read array mode by writing command code xxFF$_{16}$ in the second bus cycle of these commands. The command code written in the first bus cycle becomes invalid.

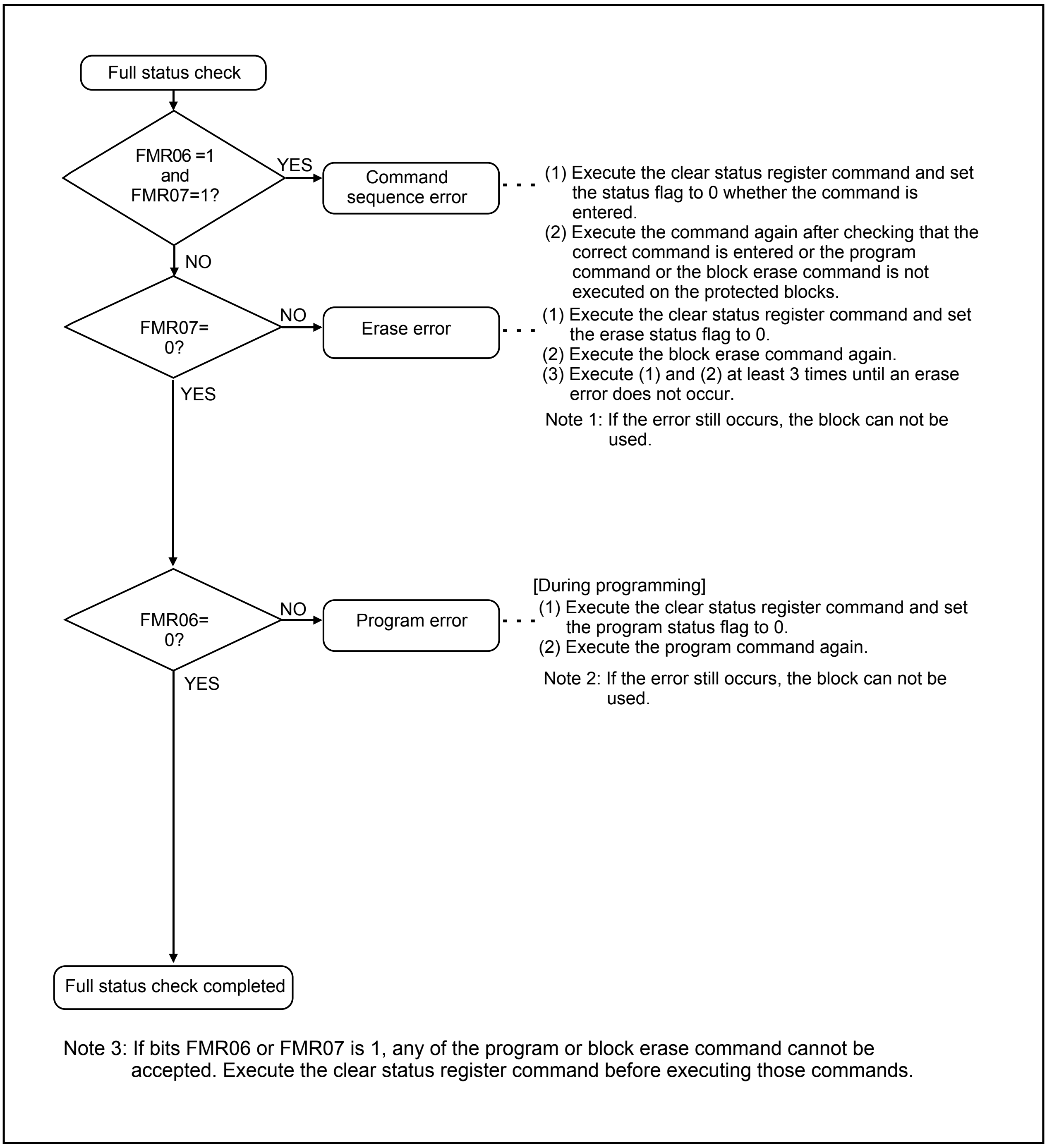


Figure 20.14 Full Status Check and Handling Procedure for Each Error

20.9 Standard Serial I/O Mode

In standard serial I/O mode, the serial programmer supporting the M16C/29 group can be used to rewrite the flash memory user ROM area, while the MCU is mounted on a board. For more information about the serial programmer, contact your serial programmer manufacturer. Refer to the user's manual included with your serial programmer for instruction.

Table 20.8 lists pin description (flash memory standard serial input/output mode). **Figures 20.15** and **20.16** show pin connections for standard serial input/output mode.

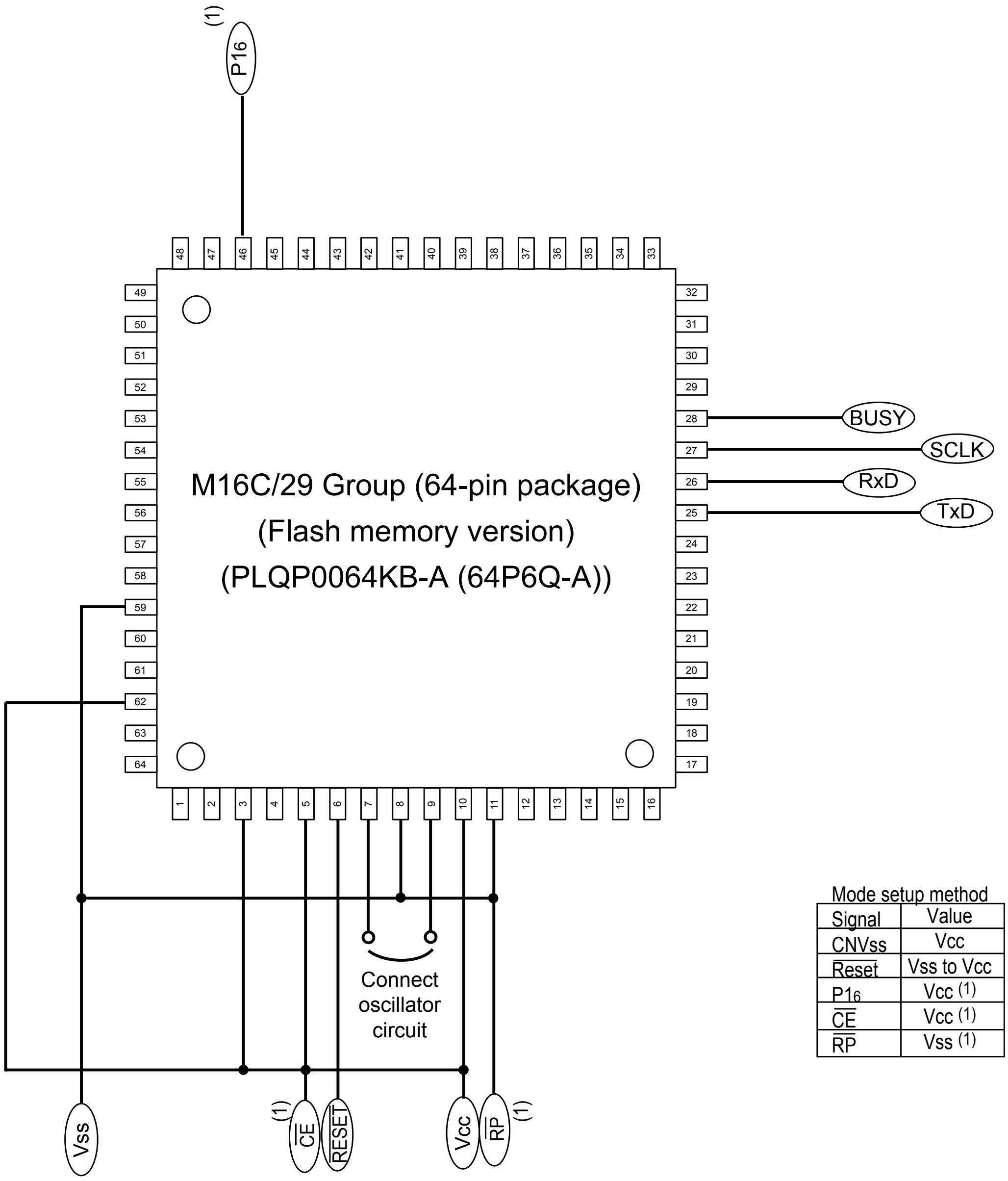
20.9.1 ID Code Check Function

The ID code check function determines whether or not the ID codes sent from the serial programmer matches those written in the flash memory. (Refer to **20.3 Functions To Prevent Flash Memory from Rewriting**.)

Table 20.8 Pin Descriptions (Flash Memory Standard Serial I/O Mode)

Pin	Name	I/O	Description
Vcc,Vss	Power input		Apply the voltage guaranteed for Program and Erase to Vcc pin and 0 V to Vss pin.
CNVss	CNVss	I	Connect to Vcc pin.
$\overline{\text{RESET}}$	Reset input	I	Reset input pin. While $\overline{\text{RESET}}$ pin is “L”, wait for td(ROC).
XIN	Clock input	I	Connect a ceramic resonator or crystal oscillator between XIN and XOUT pins. To input an externally generated clock, input it to XIN pin and open XOUT pin.
XOUT	Clock output	O	
AVcc, AVss	Analog power supply input		Connect AVss to Vss and AVcc to Vcc, respectively.
VREF	Reference voltage input	I	Enter the reference voltage for AD conversion.
P00 to P07	Input port P0	I	Input “H” or “L” signal or leave open.
P10 to P15, P17	Input port P1	I	Input “H” or “L” signal or leave open.
P16	Input port P1	I	Connect this pin to Vcc while $\overline{\text{RESET}}$ pin is “L”. (2)
P20 to P27	Input port P2	I	Input "H" or “L” level signal or leave open.
P30 to P37	Input port P3	I	Input "H" or “L” level signal or leave open.
P60 to P63	Input port P6	I	Input "H" or “L” level signal or leave open.
P64	BUSY output	O	Standard serial I/O mode 1: BUSY signal output pin Standard serial I/O mode 2: Monitor signal output pin for boot program operation check
P65	SCLK input	I	Standard serial I/O mode 1: Serial clock input pin Standard serial I/O mode 2: Input “L”.
P66	RxD input	I	Serial data input pin
P67	TxD output	O	Serial data output pin (1)
P70 to P77	Input port P7	I	Input “H” or “L” signal or leave open.
P80 to P84, P87	Input port P8	I	Input “H” or “L” signal or leave open.
P85	$\overline{\text{RP}}$ input	I	Connect this pin to Vss while $\overline{\text{RESET}}$ pin is “L”. (2)
P86	$\overline{\text{CE}}$ input	I	Connect this pin to Vcc while $\overline{\text{RESET}}$ pin is “L”. (2)
P90 to P92, P95 to P97	Input port P9	I	Input “H” or “L” signal or leave open.
P93	Input port P93 — Normal-ver.	I/O	“H” signal is output for specific time. Input “H” signal or leave open.
	Input port P93 — T-ver./V-ver.	I	Input “H” or “L” signal or leave open.
P100 to P107	Input port P10	I	Input “H” or “L” signal or leave open.

NOTES:
1. When using standard serial I/O mode 1, to input “H” to the TxD pin is necessary while the $\overline{\text{RESET}}$ pin is held “L”. Therefore, connect this pin to VCC via a resistor. Adjust the pull-up resistor value on a system not to affect a data transfer after reset, because this pin changes to a data-output pin
2. Set the following, either or both.
   -Connect the $\overline{\text{CE}}$ pin to VCC.
   -Connect the $\overline{\text{RP}}$ pin to VSS and P16 pin to VCC.

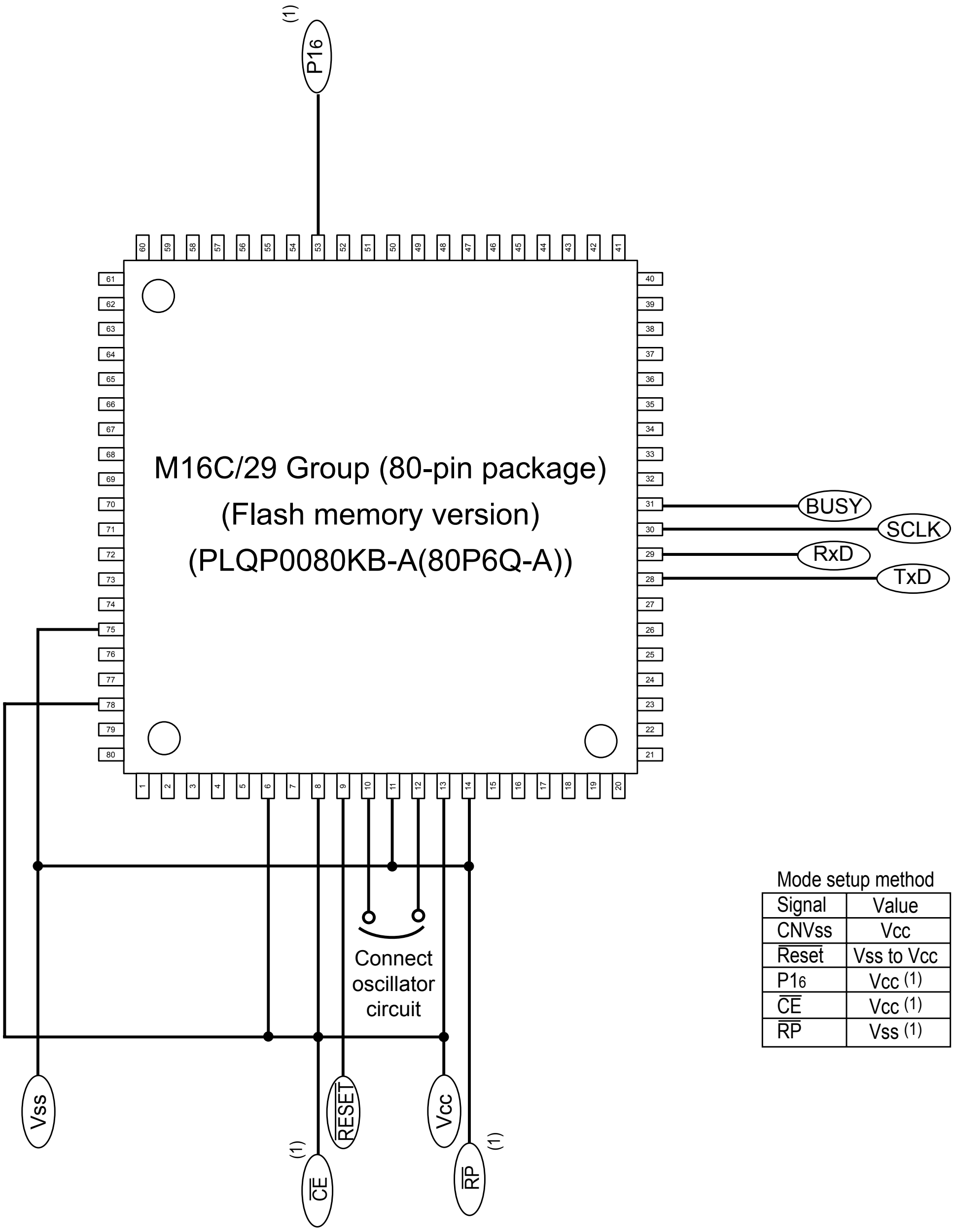


Mode setup method

Signal	Value
CNVss	Vcc
Reset	Vss to Vcc
P16	Vcc (1)
$\overline{CE}$	Vcc (1)
$\overline{RP}$	Vss (1)

NOTE:
1. Set the following, either or both, in serial I/O Mode, while the $\overline{\text{RESET}}$ pin is applied a low-level ("L") signal.
   - -Connect the $\overline{\text{CE}}$ pin to Vcc.
   - -Connect the $\overline{\text{RP}}$ pin to Vss and the P16 pin to Vcc.

Figure 20.15 Pin Connections for Serial I/O Mode (1)



Mode setup method

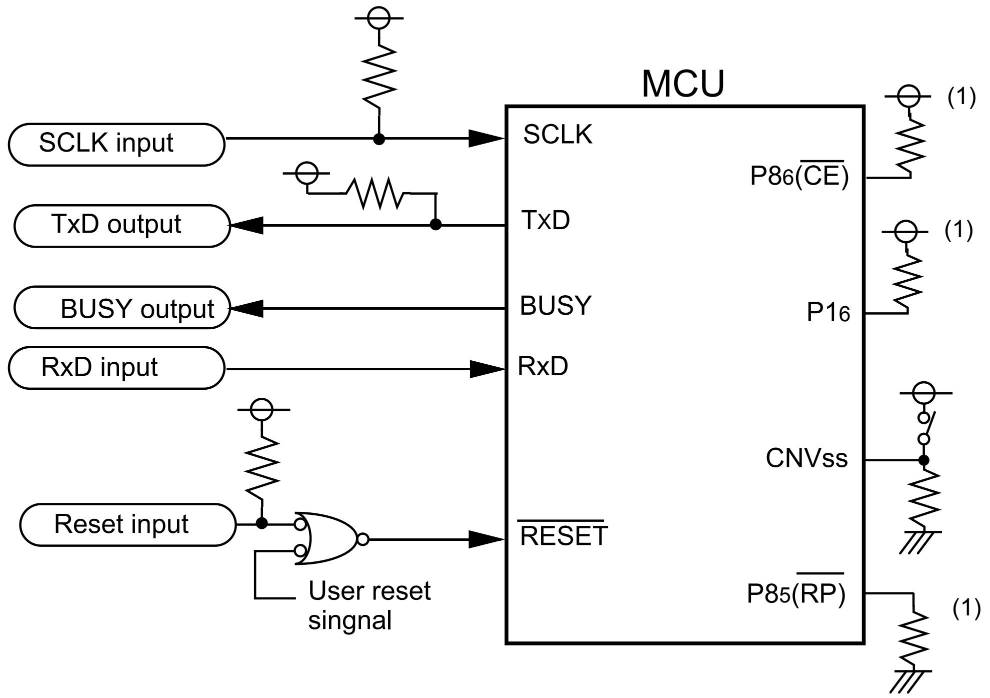
Signal	Value
CNVss	Vcc
Reset	Vss to Vcc
P16	Vcc (1)
CE	Vcc (1)
RP	Vss (1)

NOTE:
1. Set the following, either or both, in serial I/O Mode, while the RESET pin is applied a low-level ("L") signal.
   - Connect the CE pin to Vcc.
   - Connect the RP pin to Vss and the P16 pin to Vcc.

Figure 20.16 Pin Connections for Serial I/O Mode (2)

20.9.2 Example of Circuit Application in Standard Serial I/O Mode

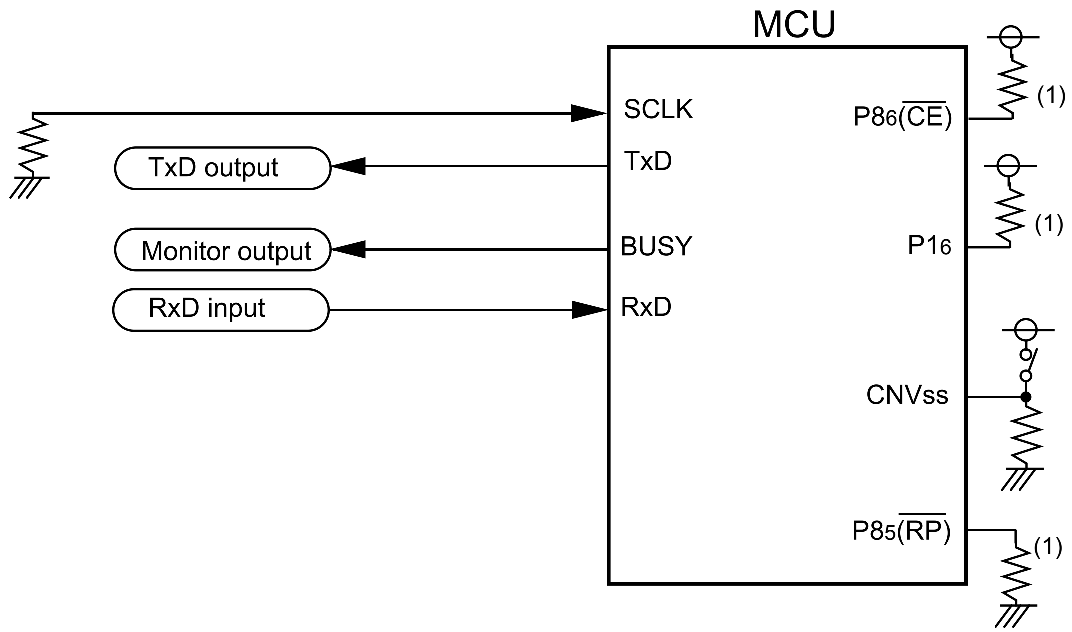
Figure 20.17 shows an example of a circuit application in standard serial I/O mode 1 and **Figure 20.18** shows an example of a circuit application in standard serial I/O mode 2. Refer to the user's manual of your serial programmer to handle pins controlled by the serial programmer.



(1) Controlling pins and external circuits vary with the serial programmer. For more information, refer to the user's manual included with the serial programmer.
(2) In this example, a selector controls the input voltage applied to CNVss to switch between single-chip mode and standard serial I/O mode.
(3) In standard serial input/output mode 1, if the user reset signal becomes “L” while the MCU is communicating with the serial programmer, break the connection between the user reset signal and the $\overline{\text{RESET}}$ pin using a jumper switch.

NOTE:
1. Set the following, either or both.
   - Connect the $\overline{\text{CE}}$ pin to Vcc
   - Connect the $\overline{\text{RP}}$ pin to Vss and the P16 pin to Vcc

Figure 20.17 Circuit Application in Standard Serial I/O Mode 1



(1) In this example, a selector controls the input voltage applied to CNVss to switch between single-chip mode and standard serial I/O mode.

NOTE:
1. Set the following, either or both.
- Connect the $\overline{CE}$ pin to Vcc
- Connect the $\overline{RP}$ pin to Vss and the $P1_6$ pin to Vcc

Figure 20.18 Circuit Application in Standard Serial I/O Mode 2

20.10 Parallel I/O Mode

In parallel input/output mode, the user ROM can be rewritten by a parallel programmer supporting the M16C/29 group. Contact your parallel programmer manufacturer for more information on the parallel programmer. Refer to the user's manual included with your parallel programmer for instructions.

20.10.1 ROM Code Protect Function

The ROM code protect function prevents the flash memory from being read or rewritten. (Refer to **20.3 Functions To Prevent Flash Memory from Rewriting**).

20.11 CAN I/O Mode

Note
The CAN I/O mode is not available in M16C/29 T-ver./V-ver.

In CAN I/O mode, the user ROM area can be rewritten while the MCU is mounted on-board by using a CAN programmer which is applicable for the M16C/29 group. For more information about CAN programmers, contact the manufacturer of your CAN programmer. For details on how to use, refer to the user's manual included with your CAN programmer.
Table 20.9 lists pin functions for CAN I/O mode. Figures 20.19 and 20.20 show pin connections for CAN I/O mode.

20.11.1 ID code check function

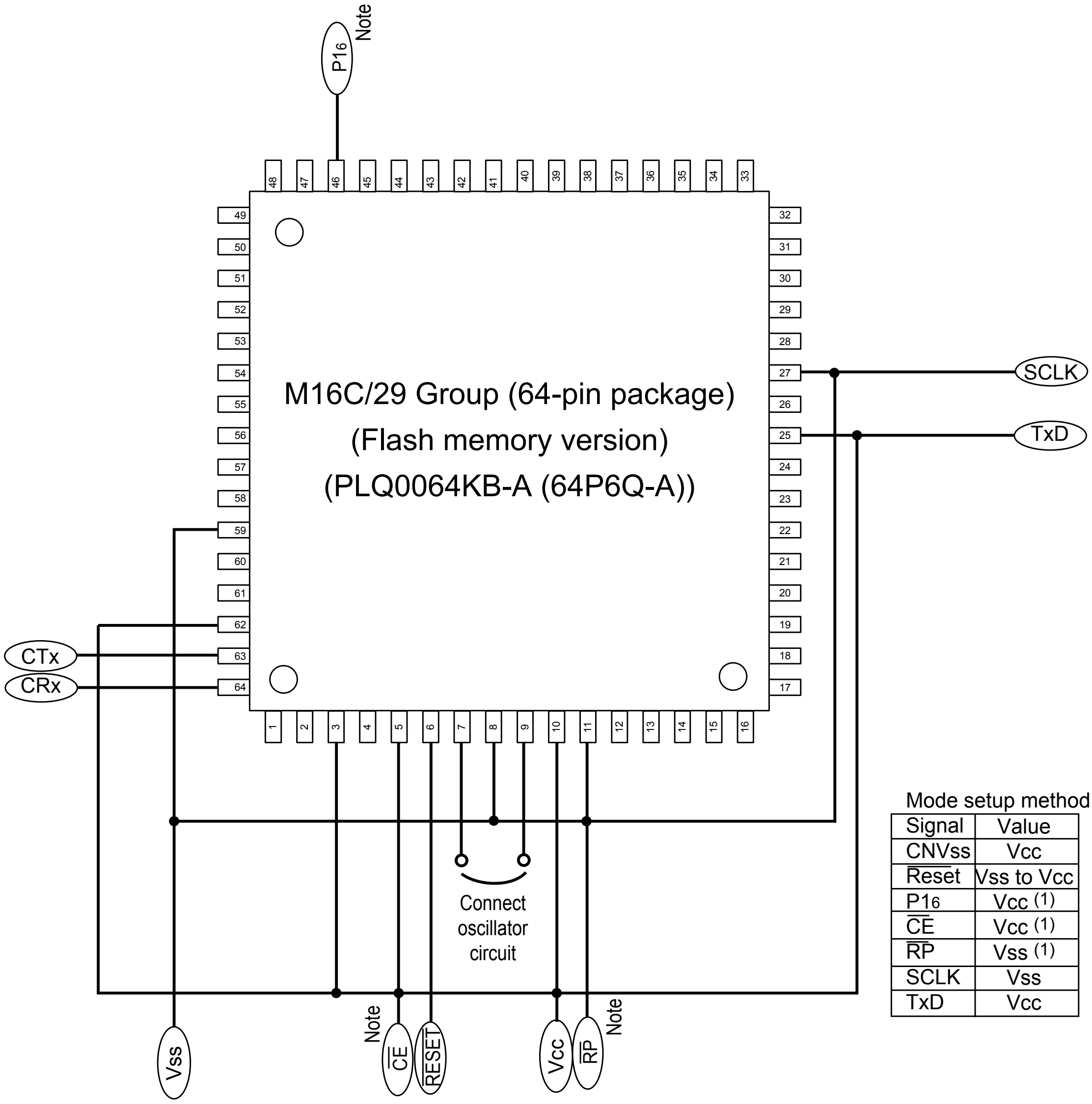
This function determines whether the ID codes sent from the CAN programmer and those written in the flash memory match.(Refer to **20.3 Functions To Prevent Flash Memory from Rewriting**.)

Table 20.9 Pin Functions for CAN I/O Mode

Pin	Name	I/O	Description
V_{CC},V_{SS}	Power input		Apply the voltage guaranteed for Program and Erase to Vcc pin and 0 V to Vss pin.
CNV_{SS}	CNV_{SS}	I	Connect to Vcc pin.
$\overline{RESET}$	Reset input	I	Reset input pin. While $\overline{RESET}$ pin is "L" level, wait for td(ROC).
X_{IN}	Clock input	I	Connect a ceramic resonator or crystal oscillator between X_{IN} and X_{OUT} pins. To input an externally generated clock, input it to X_{IN} pin and open X_{OUT} pin.
X_{OUT}	Clock output	O	
AV_{CC}, AV_{SS}	Analog power supply input		Connect AVss to Vss and AVcc to Vcc, respectively.
V_{REF}	Reference voltage input	I	Enter the reference voltage for AD from this pin.
$P0_0$ to $P0_7$	Input port P0	I	Input "H" or "L" level signal or leave open.
$P1_0$ to $P1_5$, $P1_7$	Input port P1	I	Input "H" or "L" level signal or leave open.
$P1_6$	Input port P1	I	Connect this pin to Vcc while RESET is low. (Note 1)
$P2_0$ to $P2_7$	Input port P2	I	Input "H" or "L" level signal or leave open.
$P3_0$ to $P3_7$	Input port P3	I	Input "H" or "L" level signal or leave open.
$P6_0$ to $P6_4$, $P6_6$	Input port P6	I	Input "H" or "L" level signal or leave open.
$P6_5$	SCLK input	I	Input "L" level signal.
$P6_7$	TxD output	O	Input "H" level signal.
$P7_0$ to $P7_7$	Input port P7	I	Input "H" or "L" level signal or leave open.
$P8_0$ to $P8_4$, $P8_7$	Input port P8	I	Input "H" or "L" level signal or leave open.
$P8_5$	$\overline{RP}$ input	I	Connect this pin to Vss while $\overline{RESET}$ is low. (Note 1)
$P8_6$	$\overline{CE}$ input	I	Connect this pin to Vcc while $\overline{RESET}$ is low. (Note 1)
$P9_0$ to $P9_1$, $P9_5$ to $P9_7$	Input port P9	I	Input "H" or "L" level signal or leave open.
$P9_2$	CRX input	I	Connect this pin to a CAN transceiver.
$P9_3$	CTX output	O	Connect this pin to a CAN transceiver.
$P10_0$ to $P10_7$	Input port P10	I	Input "H" or "L" level signal or leave open.

NOTE:

1. Set following either or both.
   - •Connect the $\overline{CE}$ pin to V_{CC}.
   - •Connect the $\overline{RP}$ pin to V_{SS} and the $P1_6$ pin to V_{CC}.

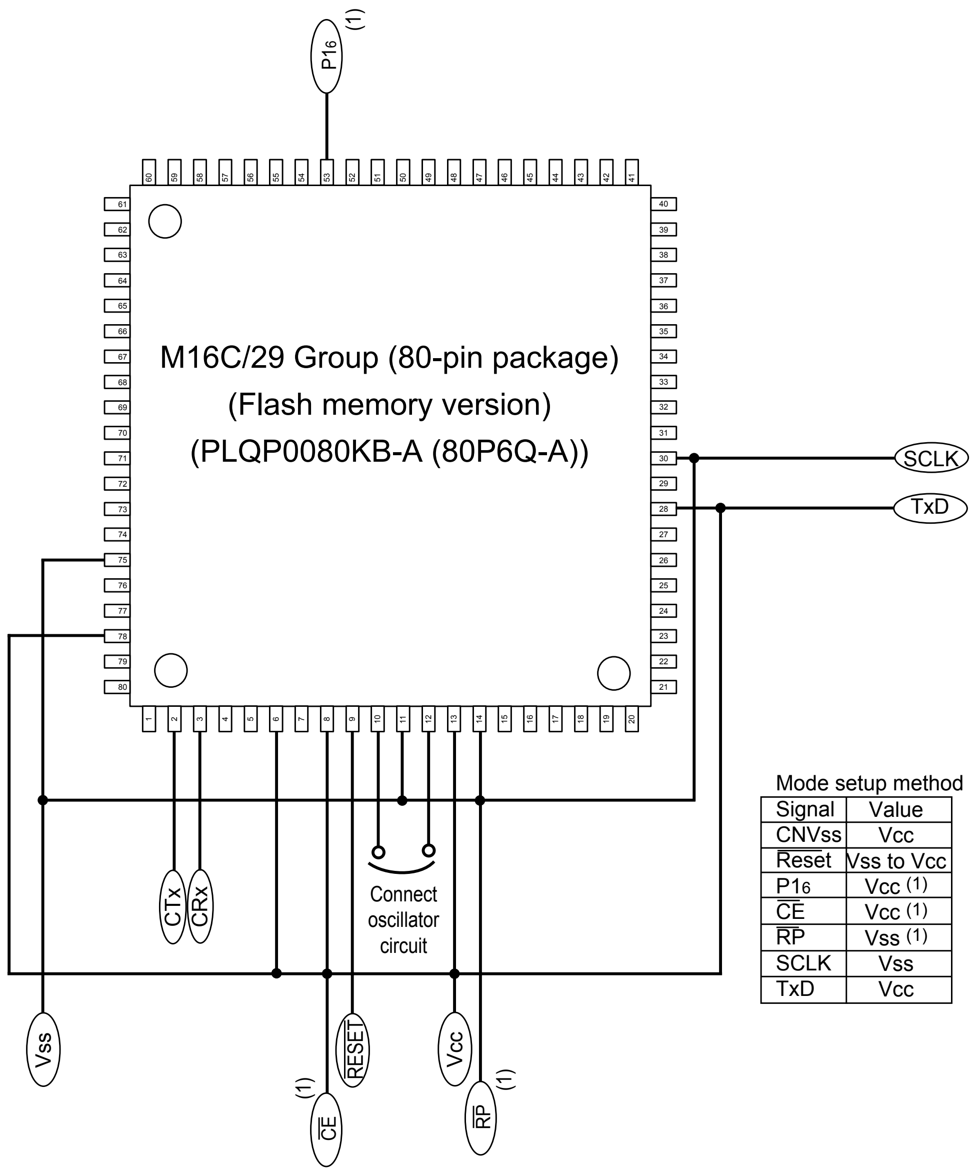


Mode setup method

Signal	Value
CNVss	Vcc
Reset	Vss to Vcc
P16	Vcc (1)
CE	Vcc (1)
RP	Vss (1)
SCLK	Vss
TxD	Vcc

NOTE:
1. Set following either or both in serial I/O mode while the RESET pin is held “L”.
   •Connect the CE pin to Vcc
   •Connect the RP pin to Vss and the P16 pin to Vcc

Figure 20.19 Pin Connections for CAN I/O Mode (1)



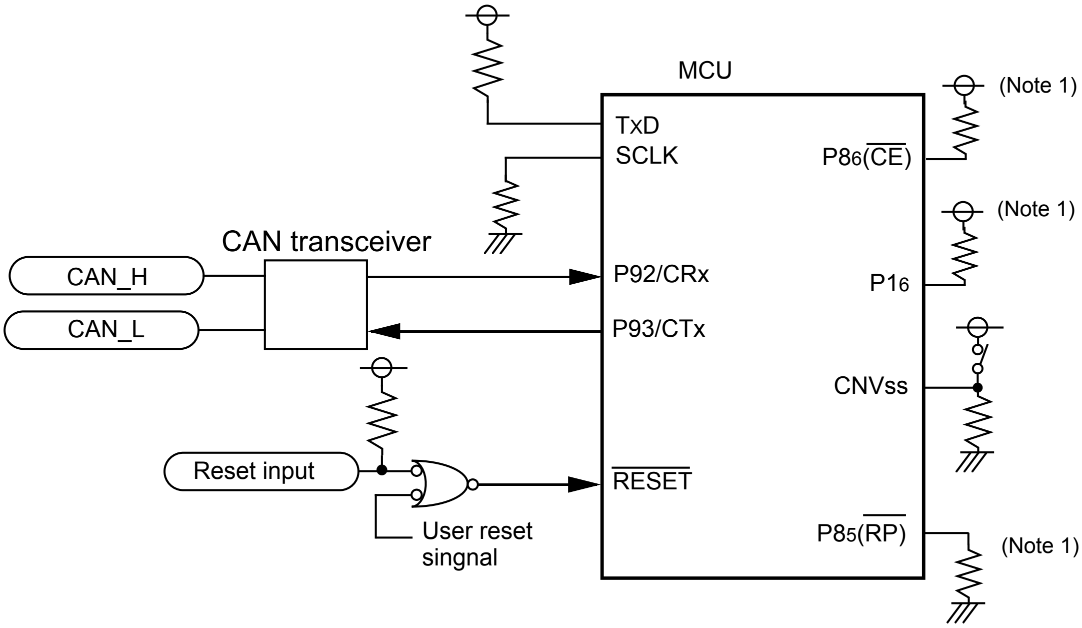
Signal	Value
CNVss	Vcc
Reset	Vss to Vcc
P16	Vcc (1)
CE	Vcc (1)
RP	Vss (1)
SCLK	Vss
TxD	Vcc

NOTE:
1. Set following either or both in serial I/O mode while the RESET pin is held "L".
   •Connect the CE pin to Vcc
   •Connect the RP pin to Vss and the P16 pin to Vcc

Figure 20.20 Pin Connections for CAN I/O Mode (2)

20.11.2 Example of Circuit Application in CAN I/O Mode

Figure 20.21 shows example of circuit application in CAN I/O mode. Refer to the user's manual for CAN programmer to handle pins controlled by a CAN programmer.



(1) Control pins and external circuits vary with the CAN programmer.
For more information, refer to the user's manual include with the CAN programmer.
(2) In this example, a selector controls the input voltage applied to CNVss to switch between single-chip mode and CAN I/O mode.

Note 1. Set following either or both.
•Connect the $\overline{\mathrm{CE}}$ pin to V_{CC}
•Connect the $\overline{\mathrm{RP}}$ pin to V_{SS} and the $P1_6$ pin to V_{CC}

Figure 20.21 Circuit Application in CAN I/O Mode

21. Electrical Characteristics

21.1 Normal version

Table 21.1 Absolute Maximum Ratings

<table>
<tr><th>Symbol</th><th colspan="3">Parameter</th><th>Condition</th><th>Value</th><th>Unit</th></tr>
<tr><td>V_{CC}</td><td colspan="3">Supply Voltage</td><td>V_{CC}=AV_{CC}</td><td>-0.3 to 6.5</td><td>V</td></tr>
<tr><td>AV_{CC}</td><td colspan="3">Analog Supply Voltage</td><td>V_{CC}=AV_{CC}</td><td>-0.3 to 6.5</td><td>V</td></tr>
<tr><td>V_I</td><td>Input Voltage</td><td colspan="2">$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$,
$P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$,
$P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$,
$P10_0$ to $P10_7$,
X_{IN}, V_{REF}, $\overline{RESET}$, CNV_{SS}</td><td></td><td>-0.3 to V_{CC}+0.3</td><td>V</td></tr>
<tr><td>V_O</td><td>Output Voltage</td><td colspan="2">$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$,
$P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$,
$P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$,
$P10_0$ to $P10_7$,
X_{OUT}</td><td></td><td>-0.3 to V_{CC}+0.3</td><td>V</td></tr>
<tr><td>Pd</td><td colspan="3">Power Dissipation</td><td>-40≤Topr≤85° C</td><td>300</td><td>mW</td></tr>
<tr><td rowspan="3">Topr</td><td rowspan="3">Operating Ambient Temperature</td><td colspan="2">during CPU operation</td><td></td><td>-20 to 85 /
-40 to 85(1)</td><td>° C</td></tr>
<tr><td rowspan="2">during flash memory program and erase operation</td><td>Program Space
(Block 0 to Block 5)</td><td></td><td>0 to 60</td><td>° C</td></tr>
<tr><td>Data Space
(Block A, Block B)</td><td></td><td>-20 to 85 /
-40 to 85(1)</td><td>° C</td></tr>
<tr><td>Tstg</td><td colspan="3">Storage Temperature</td><td></td><td>-65 to 150</td><td>° C</td></tr>
</table>

NOTE:

1. Refer to **Table 1.6**.

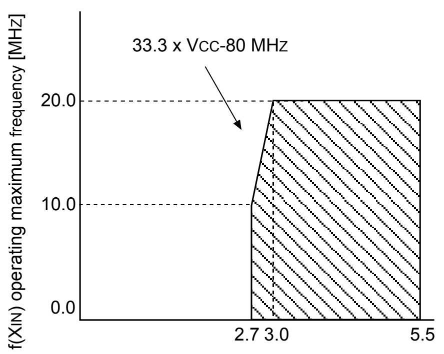
Table 21.2 Recommended Operating Conditions (Note 1)

Symbol	Parameter		Standard Min.	Standard Typ.	Standard Max.	Unit
V_{CC}	Supply Voltage		2.7		5.5	V
AV_{CC}	Analog Supply Voltage			V_{CC}		V
V_{SS}	Supply Voltage			0		V
AV_{SS}	Analog Supply Voltage			0		V
V_{IH}	Input High ("H") Voltage	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$	$0.7V_{CC}$		V_{CC}	V
		XIN, $\overline{RESET}$, CNVSS	$0.8V_{CC}$		V_{CC}	V
		SDA_{MM}, SCL_{MM}: When I^{2}C bus input level is selected	$0.7V_{CC}$		V_{CC}	V
		SDA_{MM}, SCL_{MM}: When SMBUS input level is selected	1.4		V_{CC}	V
V_{IL}	Input Low ("L") Voltage	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$	0		$0.3V_{CC}$	V
		XIN, $\overline{RESET}$, CNVSS	0		$0.2V_{CC}$	V
		SDA_{MM}, SCL_{MM}: When I^{2}C bus input level is selected	0		$0.3V_{CC}$	V
		SDA_{MM}, SCL_{MM}: When SMBUS input level is selected	0		0.6	V
$I_{OH(peak)}$	Peak Output High ("H") Current	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$			-10.0	mA
$I_{OH(avg)}$	Average Output High ("H") Current	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$			-5.0	mA
$I_{OL(peak)}$	Peak Output Low ("L") Current	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$			10.0	mA
$I_{OL(avg)}$	Average Output Low ("L") Current	P0$_0$ to P0$_7$, P1$_0$ to P1$_7$, P2$_0$ to P2$_7$, P3$_0$ to P3$_7$, P6$_0$ to P6$_7$, P7$_0$ to P7$_7$, P8$_0$ to P8$_7$, P9$_0$ to P9$_3$, P9$_5$ to P9$_7$, P10$_0$ to P10$_7$			5.0	mA
$f(X_{IN})$	Main Clock Input Oscillation Frequency(4)	V_{CC}=3.0 to 5.5V	0		20	MHz
		V_{CC}=2.7 to 3.0V	0		33 X V_{CC}-80	MHz
$f(X_{CIN})$	Sub Clock Oscillation Frequency			32.768	50	kHz
$f_1(ROC)$	On-chip Oscillator Frequency 1		0.5	1	2	MHz
f2(ROC)	On-chip Oscillator Frequency 2		1	2	4	MHz
f3(ROC)	On-chip Oscillator Frequency 3		8	16	26	MHz
f(PLL)	PLL Clock Oscillation Frequency(4)	V_{CC}=3.0 to 5.5V	10		20	MHz
		V_{CC}=2.7 to 3.0V	10		33 X V_{CC}-80	MHz
f(BCLK)	CPU Operation Clock Frequency		0		20	MHz
$t_{SU}(PLL)$	Wait Time to Stabilize PLL Frequency Synthesizer	V_{CC}=5.0V			20	ms
		V_{CC}=3.0V			50	ms

NOTES:

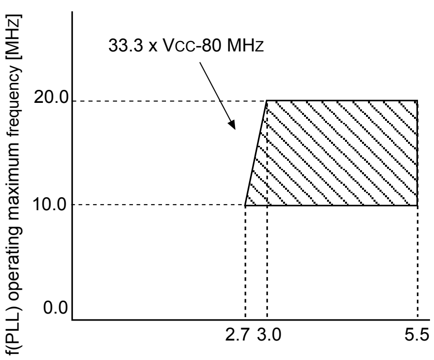
1. Referenced to V_{CC} = 2.7 to 5.5V at Topr = -20 to 85 ° C / -40 to 85 ° C unless otherwise specified.
2. The mean output current is the mean value within 100ms.
3. The total $I_{OL(peak)}$ for all ports must be 80mA or less. The total $I_{OH(peak)}$ for all ports must be -80mA or less.
4. Relationship among main clock oscillation frequency, PLL clock oscillation frequency and supply voltage.

Main clock input oscillation frequency



VCC[V] (main clock: no division)

PLL clock oscillation frequency



VCC[V] (PLL clock oscillation)

Table 21.3 A/D Conversion Characteristics (Note 1)

Symbol	Parameter		Measurement Condition	Standard			Unit
				Min.	Typ.	Max.	
-	Resolution		$V_{REF}=V_{CC}$			10	Bits
INL	Integral Nonlinearity Error	10 bit	$V_{REF}=V_{CC}$=5V			±3	LSB
			$V_{REF}=V_{CC}$=3.3V			±5	LSB
		8 bit	$V_{REF}=V_{CC}$=3.3V			±2	LSB
-	Absolute Accuracy	10 bit	$V_{REF}=V_{CC}$=5V			±3	LSB
			$V_{REF}=V_{CC}$=3.3V			±5	LSB
		8 bit	$V_{REF}=V_{CC}$=3.3V			±2	LSB
DNL	Differential Nonlinearity Error					±1	LSB
-	Offset Error					±3	LSB
-	Gain Error					±3	LSB
R_{LADDER}	Resistor Ladder		$V_{REF}=V_{CC}$	10		40	kΩ
t_{CONV}	10-bit Conversion Time Sample & Hold Function Available		$V_{REF}=V_{CC}$=5V, ϕAD=10MHz	3.3			µs
t_{CONV}	8-bit Conversion Time Sample & Hold Function Available		$V_{REF}=V_{CC}$=5V, ϕAD=10MHz	2.8			µs
V_{REF}	Reference Voltage			2.0		V_{CC}	V
V_{IA}	Analog Input Voltage			0		V_{REF}	V

NOTES:

1. Referenced to $V_{CC}=AV_{CC}=V_{REF}$= 3.3 to 5.5V, $V_{SS}=AV_{SS}$=0V at Topr = -20 to 85 ° C / -40 to 85° C unless otherwise specified.
2. Keep ϕAD frequency at 10 MHz or less. Additionally, divide the f_{AD} if V_{CC} is less than 4.2V, and make ϕAD frequency equal to or lower than f_{AD}/2.
3. When sample & hold function is disabled, keep ϕAD frequency at 250 kHz or more in addition to the limitation in Note 2. When sample & hold function is enabled, keep ϕAD frequency at 1 MHz or more in addition to the limitation in Note 2.
4. When sample & hold function is enabled, sampling time is 3/ ϕAD frequency. When sample & hold function is disabled, sampling time is 2/ ϕAD frequency.

Table 21.4 Flash Memory Version Electrical Characteristics (1) for 100/1000 E/W cycle products

[Program Space and Data Space in U3 and U5: Program Space in U7 and U9]

Symbol	Parameter		Standard Min.	Standard Typ.(2)	Standard Max.	Unit
-	Program and Erase Endurance(3)		100/1000(4, 11)			cycles
-	Word Program Time (V_{CC}=5.0V, Topr=25° C)			75	600	µs
-	Block Erase Time (V_{CC}=5.0V, Topr=25° C)	2-Kbyte Block		0.2	9	s
		8-Kbyte Block		0.4	9	s
		16-Kbyte Block		0.7	9	s
		32-Kbyte Block		1.2	9	s
td(SR-ES)	Duration between Suspend Request and Erase Suspend				8	ms
t_{PS}	Wait Time to Stabilize Flash Memory Circuit				15	µs
-	Data Hold Time (5)		20			years

Table 21.5 Flash Memory Version Electrical Characteristics (6) 10000 E/W cycle products (Option)

[Data Space in U7 and U9(7)]

Symbol	Parameter	Standard Min.	Standard Typ.(2)	Standard Max.	Unit
-	Program and Erase Endurance(3, 8, 9)	10000(4, 10)			cycles
-	Word Program Time (V_{CC} = 5.0 V, Topr = 25° C)		100		µs
-	Block Erase Time (V_{CC} = 5.0 V, Topr = 25° C) (2-Kbyte block)		0.3		s
td(SR-ES)	Duration between Suspend Request and Erase Suspend			8	ms
t_{PS}	Wait Time to Stabilize Flash Memory Circuit			15	µs
-	Data Hold Time (5)	20			years

NOTES:

1. Referenced to V_{CC} = 2.7 to 5.5 V at Topr = 0 to 60° C (program space), unless otherwise specified.
2. V_{CC} = 5.0 V; T_{opr} = 25° C
3. Program and erase endurance is defined as number of program-erase cycles per block.
   If program and erase endurance is *n* cycle (*n* = 100, 1000, 10000), each block can be erased and programmed *n* cycles.
   For example, if a 2-Kbyte block A is erased after programming one-word data to each address 1,024 times, this counts as one program and erase endurance. Data cannot be programmed to the same address more than once without erasing the block. (rewrite prohibited).
4. Number of E/W cycles for which operation is guranteed (1 to minimum value are guaranteed).
5. T_{opr} = 55° C
6. Referenced to V_{CC} = 2.7 to 5.5 V at T_{opr} = -40 to 85° C(U7) / -20 to 85° C (U9) unless otherwise specifie.
7. **Table 21.5** applies for data space in U7 and U9 when program and erase endurance is more than 1,000 cycles. Otherwise, use **Table 21.4**.
8. To reduce the number of program and erase endurance when working with systems requiring numerous rewrites, write to unused word addresses within the block instead of rewrite. Erase block only after all possible addresses are used. For example, an 8-word program can be written 128 times maximum before erase becomes necessary. Maintaining an equal number of times erasure between block A and block B will also improve efficiency. It is recommended to track the total number of erasure performed per block and to limit the number of erasure.
9. If an erase error is generated during block erase, execute the clear status register command and block erase command at least 3 times until an erase error is not generated.
10. When executing more than 100 times rewrites, set one wait state per block access by setting the FMR17 bit in the FMR1 register 1 to 1 (wait state). When accessing to all other blocks and internal RAM, wait state can be set by the PM17 bit, regardless of the FMR17 bit setting value.
11. The program and erase endurance is 100 cycles for program space and data space in U3 and U5; 1,000 cycles for program space in U7 and U9.
12. Please contact Renesas Technology Corp. or an authorized Renesas Technology Corp. product distributor for further details on the E/W failure rate.

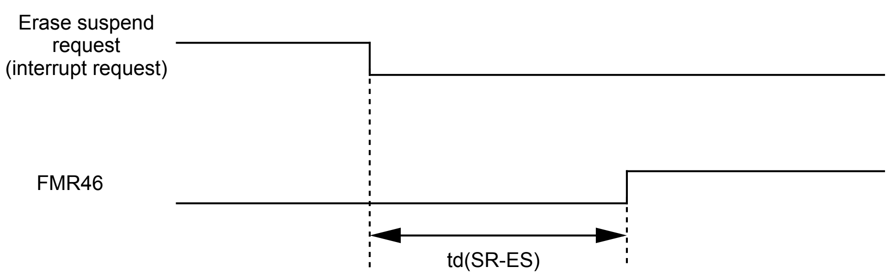


Table 21.6 Low Voltage Detection Circuit Electrical Characteristics (Note 1, Note 3)

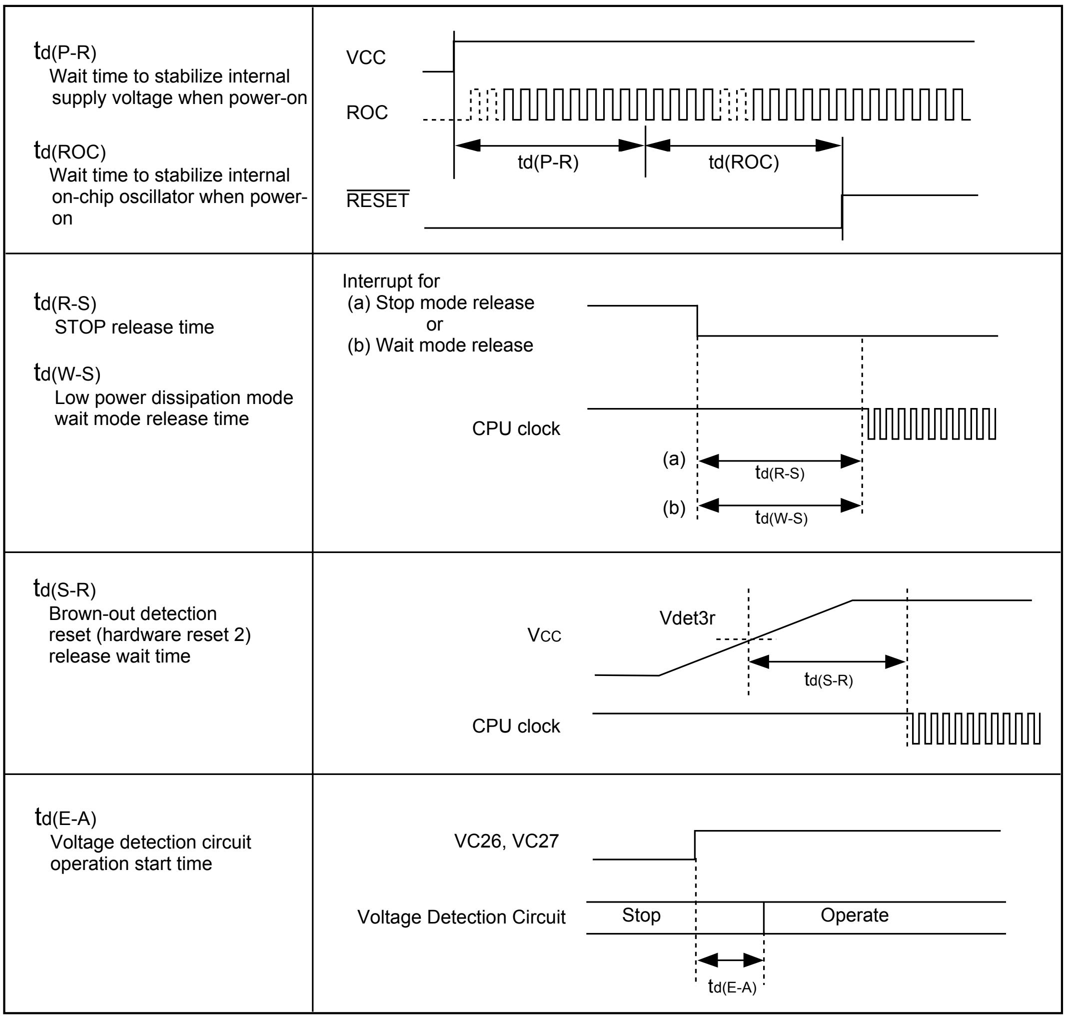
Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
Vdet4	Low Voltage Detection Voltage(1)	VCC=0.8 to 5.5V	3.2	3.8	4.45	V
Vdet3	Reset Space Detection Voltage(1)		2.3	2.8	3.4	V
Vdet3s	Low Voltage Reset Hold Voltage(2)				1.7	V
Vdet3r	Low Voltage Reset Release Voltage		2.35	2.9	3.5	V

NOTES:
1. Vdet4 >Vdet3
2. Vdet3s is the minmum voltage to maintain brown-out detection reset (hardware reset 2).
3. The low Voltage detection circuit is designed to use when VCC is set to 5V.
4. If the supply power voltage is greater than the reset level detection voltage when the reset level detection voltage is less than 2.7V, the operation at f(BCLK) < 10MHz is guranteed. However, A/D conversion, serial I/O, flash memory program and erase are excluded.

Table 21.7 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
td(P-R)	Wait Time to Stabilize Internal Supply Voltage when Power-on	VCC= 2.7 to 5.5 V			2	ms
td(ROC)	Wait Time to Stabilize Internal On-chip Oscillator when Power-on				40	µs
td(R-S)	STOP Release Time				150	µs
td(W-S)	Low Power Dissipation Mode Wait Mode Release Time				150	µs
td(S-R)	Hardware Reset 2 Release Wait Time	VCC= Vdet3r to 5.5 V		6(1)	20	ms
td(E-A)	Low Voltage Detection Circuit Operation Start Time	VCC= 2.7 to 5.5 V			20	µs

NOTE:
1. When VCC=5



$V_{CC} = 5V$

Table 21.8 Electrical Characteristics (Note 1)

Symbol	Parameter				Condition	Standard Min.	Standard Typ.	Standard Max.	Unit
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$			I_{OH}=-5mA	V_{CC}-2.0		V_{CC}	V
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$			I_{OH}=-200µA	V_{CC}-0.3		V_{CC}	V
V_{OH}	Output High ("H") Voltage		X_{OUT}	High Power	I_{OH}=-1mA	V_{CC}-2.0		V_{CC}	V
				Low Power	I_{OH}=-0.5mA	V_{CC}-2.0		V_{CC}	
	Output High ("H") Voltage		X_{COUT}	High Power	No load applied		2.5		V
				Low Power	No load applied		1.6		
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$			I_{OL}=5mA			2.0	V
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$			I_{OL}=200µA			0.45	V
V_{OL}	Output Low ("L") Voltage		X_{OUT}	High Power	I_{OL}=1mA			2.0	V
				Low Power	I_{OL}=0.5mA			2.0	
	Output Low ("L") Voltage		X_{COUT}	High Power	No load applied		0		V
				Low Power	No load applied		0		
V_{T+}-V_{T-}	Hysteresis	$TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB2_{IN}$, $\overline{INT_0}$-$\overline{INT_5}$, $\overline{NMI}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$-$\overline{CTS_2}$, SCL, SDA, CLK_0-CLK_2, $TA2_{OUT}$-$TA4_{OUT}$, $\overline{KI_0}$-$\overline{KI_3}$, R_{XD0}-R_{XD2}, S_{IN3}, S_{IN4}				0.2		1.0	V
V_{T+}-V_{T-}	Hysteresis	$\overline{RESET}$				0.2		2.5	V
V_{T+}-V_{T-}	Hysteresis	X_{IN}				0.2		0.8	V
I_{IH}	Input High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, $\overline{RESET}$, CNV_{SS}			V_I=5V			5.0	µA
I_{IL}	Input Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, $\overline{RESET}$, CNV_{SS}			V_I=0V			-5.0	µA
R_{PULLUP}	Pull-up Resistance	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$			V_I=0V	30	50	170	kΩ
R_{fXIN}	Feedback Resistance		X_{IN}				1.5		MΩ
R_{fXCIN}	Feedback Resistance		X_{CIN}				15		MΩ
V_{RAM}	RAM Standby Voltage				In stop mode	2.0			V

NOTES:

1. Referenced to V_{CC}=4.2 to 5.5V, V_{SS}=0V at Topr=-20 to 85 ° C / -40 to 85 ° C, f(BCLK)=20MHz unless otherwise specified.

VCC = 5V

Table 21.9 Electrical Characteristics (2) (Note 1)

Symbol	Parameter	Measurement Condition			Standard Min.	Standard Typ.	Standard Max.	Unit
I_{CC}	Power Supply Current (V_{CC}=4.2 to 5.5V)	Output pins are left open and other pins are connected to V_{SS}	Mask ROM	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory program	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Flash memory erase	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Mask ROM	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on ROM(3)		25		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		50		µA
			Flash memory	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on RAM(3)		25		µA
				f(BCLK) = 32 kHz, In low-power consumption mode, Program running on flash memory(3)		450		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode(4)		50		µA
			Mask ROM, Flash memory	f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity high		8.5		µA
				f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity low		3		µA
				While clock stops, Topr = 25° C		0.8	3	µA
Idet4	Low voltage detection dissipation current(4)					0.7	4	µA
Idet3	Reset area detection dissipation current(4)					1.2	8	µA

NOTES:

1. Referenced to V_{CC} = 4.2 to 5.5 V, V_{SS} = 0 V at Topr = -20 to 85° C / -40 to 85 ° C, f(BCLK) = 20 MHz unless otherwise specified.
2. With one timer operates, using f_{C32}.
3. This indicates the memory in which the program to be executed exists.
4. Idet is dissipation current when the following bit is set to 1 (detection circuit enabled).
   Idet4: VC27 bit in the VCR2 register
   Idet3: VC26 bit in the VCR2 register

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.10 External Clock Input (XIN input)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t_c	External Clock Input Cycle Time	50		ns
$t_{w(H)}$	External Clock Input High ("H") Width	20		ns
$t_{w(L)}$	External Clock Input Low ("L") Width	20		ns
t_r	External Clock Rise Time		9	ns
t_f	External Clock Fall Time		9	ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.11 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	100		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	40		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	40		ns

Table 21.12 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	400		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	200		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	200		ns

Table 21.13 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	200		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	100		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	100		ns

Table 21.14 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{w(TAH)}$	TAiIN input HIGH pulse width	100		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	100		ns

Table 21.15 Timer A Input (Counter Increment/decrement Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(UP)}$	TAiOUT input cycle time	2000		ns
$t_{w(UPH)}$	TAiOUT input HIGH pulse width	1000		ns
$t_{w(UPL)}$	TAiOUT input LOW pulse width	1000		ns
$t_{su(UP-TIN)}$	TAiOUT input setup time	400		ns
$t_{h(TIN-UP)}$	TAiOUT input hold time	400		ns

Table 21.16 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	800		ns
$t_{su(TAIN-TAOUT)}$	TAiOUT input setup time	200		ns
$t_{su(TAOUT-TAIN)}$	TAiIN input setup time	200		ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.17 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (counted on one edge)	100		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on one edge)	40		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on one edge)	40		ns
$t_{c(TB)}$	TBiIN input cycle time (counted on both edges)	200		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on both edges)	80		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on both edges)	80		ns

Table 21.18 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	400		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	200		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	200		ns

Table 21.19 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	400		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	200		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	200		ns

Table 21.20 A /D Trigger Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(AD)}$	$\overline{\text{ADTRG}}$ input cycle time (trigger able minimum)	1000		ns
$t_{w(ADL)}$	$\overline{\text{ADTRG}}$ input LOW pulse width	125		ns

Table 21.21 Serial I/O

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	200		ns
$t_{w(CKH)}$	CLKi input HIGH pulse width	100		ns
$t_{w(CKL)}$	CLKi input LOW pulse width	100		ns
$t_{d(C-Q)}$	TxDi output delay time		80	ns
$t_{h(C-Q)}$	TxDi hold time	0		ns
$t_{su(D-C)}$	RxDi input setup time	70		ns
$t_{h(C-D)}$	RxDi input hold time	90		ns

Table 21.22 External Interrupt $\overline{\text{INTi}}$ Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{\text{INTi}}$ input HIGH pulse width	250		ns
$t_{w(INL)}$	$\overline{\text{INTi}}$ input LOW pulse width	250		ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.23 Multi-master I^2C bus Line

Symbol	Parameter	Standard clock mode		High-speed clock mode		Unit
		Min.	Max.	Min.	Max.	
t_{BUF}	Bus free time	4.7		1.3		μs
$t_{HD;STA}$	The hold time in start condition	4.0		0.6		μs
t_{LOW}	The hold time in SCL clock 0 status	4.7		1.3		μs
t_R	SCL, SDA signals' rising time		1000	20+0.1Cb	300	ns
$t_{HD;DAT}$	Data hold time	0		0	0.9	μs
t_{HIGH}	The hold time in SCL clock 1 status	4.0		0.6		μs
t_F	SCL, SDA signals' falling time		300	20+0.1Cb	300	ns
$t_{SU;DAT}$	Data setup time	250		100		ns
$t_{SU;STA}$	The setup time in restart condition	4.7		0.6		μs
$t_{SU;STO}$	Stop condition setup time	4.0		0.6		μs

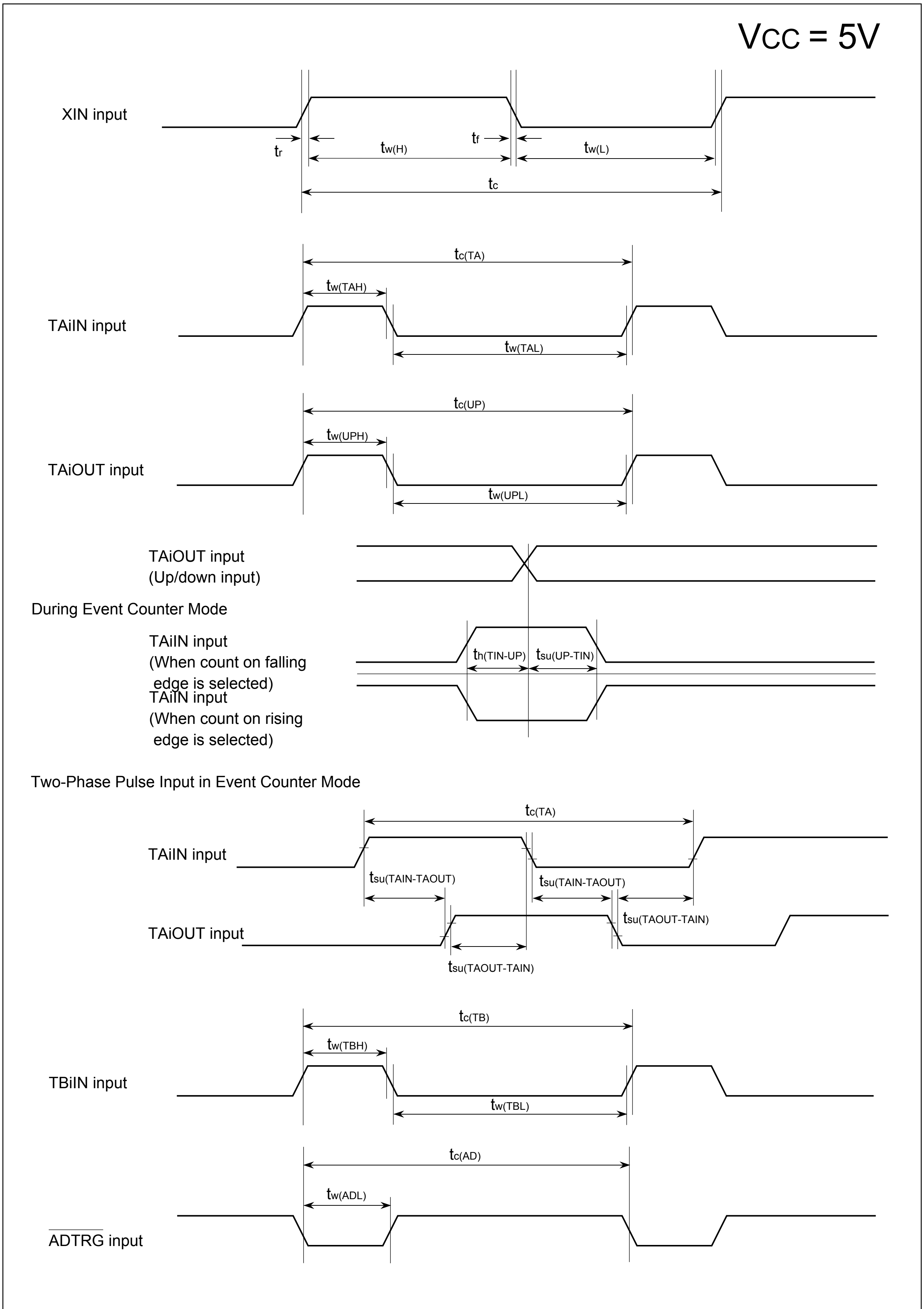


Figure 21.1 Timing Diagram (1)

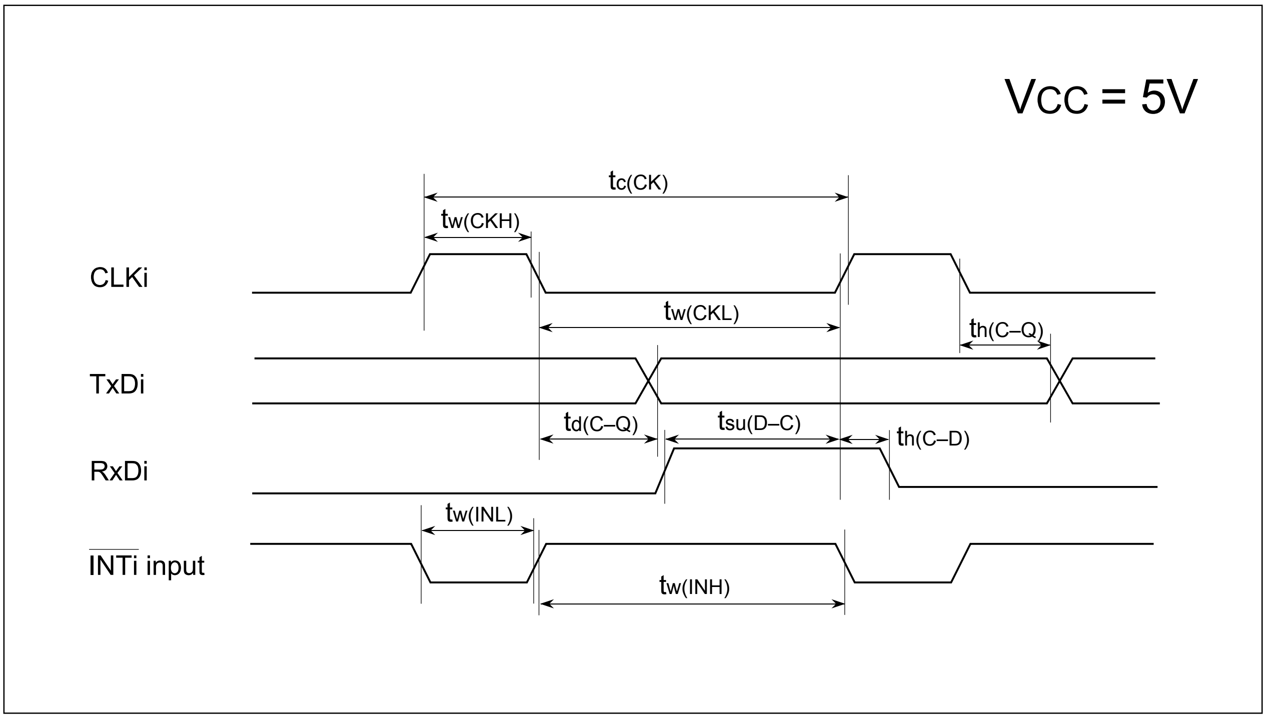


Figure 21.2 Timing Diagram (2)

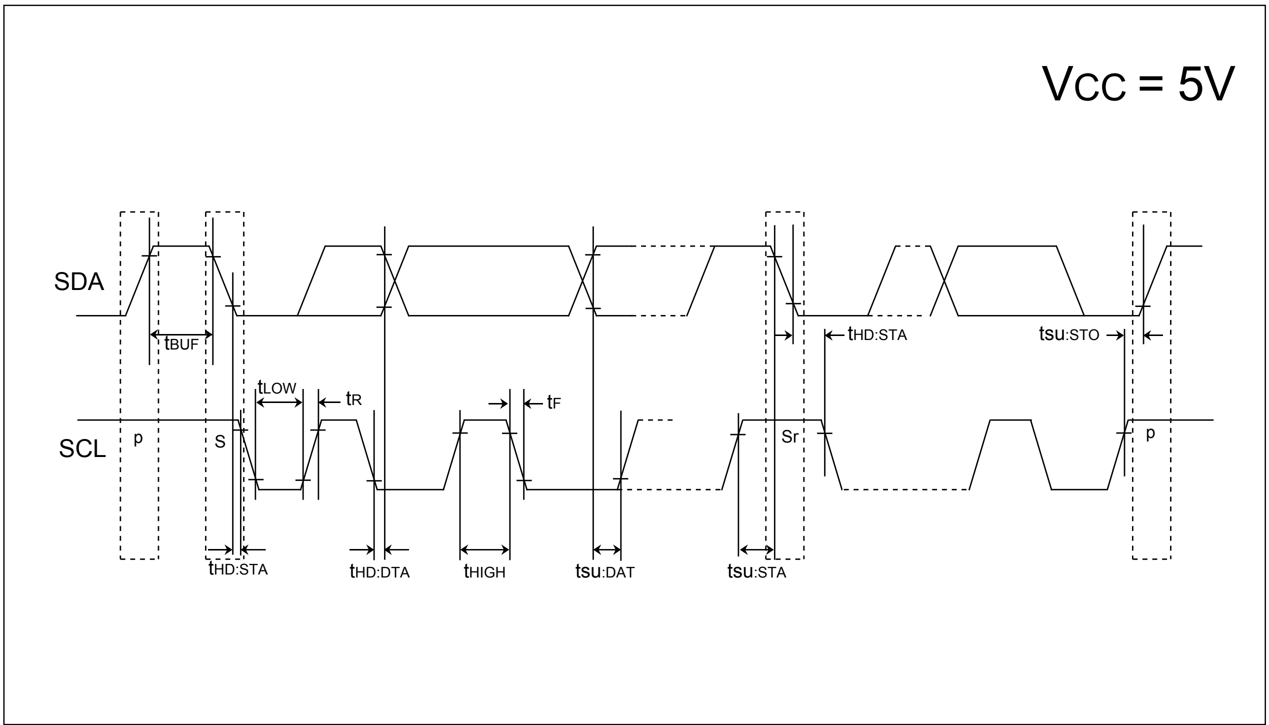


Figure 21.3 Timing Diagram (3)

V_{CC} = 3V

Table 21.24 Electrical Characteristics (Note 1)

Symbol	Parameter			Condition	Standard Min.	Standard Typ.	Standard Max.	Unit
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -1 mA	V_{CC}-0.5		V_{CC}	V
V_{OH}	Output High ("H") Voltage	X_{OUT}	High Power	I_{OH} = -0.1 mA	V_{CC}-0.5		V_{CC}	V
			Low Power	I_{OH} = -50 μA	V_{CC}-0.5		V_{CC}	
	Output High ("H") Voltage	X_{COUT}	High Power	No load applied		2.5		V
			Low Power	No load applied		1.6		
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 1 mA			0.5	V
V_{OL}	Output Low ("L") Voltage	X_{OUT}	High Power	I_{OL} = 0.1 mA			0.5	V
			Low Power	I_{OL} = 50 μA			0.5	
	Output Low ("L") Voltage	X_{COUT}	High Power	No load applied		0		V
			Low Power	No load applied		0		
V_{T+}-V_{T-}	Hysteresis	$TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB2_{IN}$, $\overline{INT_0}$-$\overline{INT_5}$, $\overline{NMI}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$-$\overline{CTS_2}$, SCL, SDA, CLK_0-CLK_2, $TA2_{OUT}$-$TA4_{OUT}$, $\overline{KI_0}$-$\overline{KI_3}$, R_{XD0}-R_{XD2}, S_{IN3}, S_{IN4}					0.8	V
V_{T+}-V_{T-}	Hysteresis	$\overline{RESET}$					1.8	V
V_{T+}-V_{T-}	Hysteresis	X_{IN}					0.8	V
I_{IH}	Input High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 3 V			4.0	μA
I_{IL}	Input Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 0 V			-4.0	μA
R_{PULLUP}	Pull-up Resistance	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		V_I = 0 V	50	100	500	kΩ
R_{fXIN}	Feedback Resistance	X_{IN}				3.0		MΩ
R_{fXCIN}	Feedback Resistance	X_{CIN}				25		MΩ
V_{RAM}	RAM Standby Voltage			In stop mode	2.0			V

NOTE:

1. Referenced to V_{CC} = 2.7 to 3.6 V, V_{SS} = 0 V at Topr = -20 to 85 ° C / -40 to 85 ° C, f(BCLK) = 10MHz unless otherwise specified.

V_{CC} = 3V

Table 21.25 Electrical Characteristics (2) (Note 1)

Symbol	Parameter	Measurement Condition			Standard			Unit
					Min.	Typ.	Max.	
I_{CC}	Power Supply Current (V_{CC} = 2.7 to 3.6V)	Output pins are left open and other pins are connected to V_{SS}	Mask ROM	f(BCLK) = 10 MHz, main clock, no division		8	13	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		1		mA
			Flash memory	f(BCLK) = 10 MHz, main clock, no division		8	13	mA
			Flash memory program	f(BCLK) = 10 MHz, Vcc = 3.0 V		11		mA
			Flash memory erase	f(BCLK) = 10 MHz, Vcc= 3.0 V		11		mA
			Mask ROM	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on ROM(3)		20		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		25		µA
			Flash memory	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on RAM(3)		20		µA
				f(BCLK) = 32 kHz, In low-power consumption mode, Program running on flash memory(3)		450		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode(4)		45		µA
			Mask ROM, Flash memory	f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity high		6.6		µA
				f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity low		2.2		µA
				While clock stops, Topr = 25° C		0.7	3	µA
Idet4	Low voltage detection dissipation current(4)					0.6	4	µA
Idet3	Reset level detection dissipation current(4)					1.0	5	µA

NOTES:

1. Referenced to V_{CC} = 2.7 to 3.6 V, V_{SS} = 0 V at Topr = -20 to 85 ° C / -40 to 85 ° C, f(BCLK) = 10 MHz unless otherwise specified.
2. With one timer operates, using f_{C32}.
3. This indicates the memory in which the program to be executed exists.
4. Idet is dissipation current when the following bit is set to 1 (detection circuit enabled).
   Idet4: the VC27 bit of the VCR2 register
   Idet3: the VC26 bit in the VCR2 register

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.26 External Clock Input (XIN input)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t_c	External clock input cycle time	100		ns
$t_{w(H)}$	External clock input HIGH pulse width	40		ns
$t_{w(L)}$	External clock input LOW pulse width	40		ns
t_r	External clock rise time		18	ns
t_f	External clock fall time		18	ns

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.27 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tc(TA)	TAiIN input cycle time	150		ns
tw(TAH)	TAiIN input HIGH pulse width	60		ns
tw(TAL)	TAiIN input LOW pulse width	60		ns

Table 21.28 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tc(TA)	TAiIN input cycle time	600		ns
tw(TAH)	TAiIN input HIGH pulse width	300		ns
tw(TAL)	TAiIN input LOW pulse width	300		ns

Table 21.29 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tc(TA)	TAiIN input cycle time	300		ns
tw(TAH)	TAiIN input HIGH pulse width	150		ns
tw(TAL)	TAiIN input LOW pulse width	150		ns

Table 21.30 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tw(TAH)	TAiIN input HIGH pulse width	150		ns
tw(TAL)	TAiIN input LOW pulse width	150		ns

Table 21.31 Timer A Input (Counter Increment/decrement Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tc(UP)	TAiOUT input cycle time	3000		ns
tw(UPH)	TAiOUT input HIGH pulse width	1500		ns
tw(UPL)	TAiOUT input LOW pulse width	1500		ns
tsu(UP-TIN)	TAiOUT input setup time	600		ns
th(TIN-UP)	TAiOUT input hold time	600		ns

Table 21.32 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
tc(TA)	TAiIN input cycle time	2		μs
tsu(TAIN-TAOUT)	TAiOUT input setup time	500		ns
tsu(TAOUT-TAIN)	TAiIN input setup time	500		ns

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.33 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (counted on one edge)	150		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on one edge)	60		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on one edge)	60		ns
$t_{c(TB)}$	TBiIN input cycle time (counted on both edges)	300		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on both edges)	120		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on both edges)	120		ns

Table 21.34 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	300		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	300		ns

Table 21.35 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	600		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	300		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	300		ns

Table 21.36 A/D Trigger Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(AD)}$	$\overline{AD_{TRG}}$ input cycle time (trigger able minimum)	1500		ns
$t_{w(ADL)}$	$\overline{AD_{TRG}}$ input LOW pulse width	200		ns

Table 21.37 Serial I/O

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	300		ns
$t_{w(CKH)}$	CLKi input HIGH pulse width	150		ns
$t_{w(CKL)}$	CLKi input LOW pulse width	150		ns
$t_{d(C-Q)}$	TxDi output delay time		160	ns
$t_{h(C-Q)}$	TxDi hold time	0		ns
$t_{su(D-C)}$	RxDi input setup time	100		ns
$t_{h(C-D)}$	RxDi input hold time	90		ns

Table 21.38 External Interrupt $\overline{INTi}$ Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{INTi}$ input HIGH pulse width	380		ns
$t_{w(INL)}$	$\overline{INTi}$ input LOW pulse width	380		ns

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 20 to 85°C / – 40 to 85°C unless otherwise specified)

Table 21.39 Multi-master I^2C bus Line

Symbol	Parameter	Standard clock mode		High-speed clock mode		Unit
		Min.	Max.	Min.	Max.	
tBUF	Bus free time	4.7		1.3		μs
tHD;STA	The hold time in start condition	4.0		0.6		μs
tLOW	The hold time in SCL clock 0 status	4.7		1.3		μs
tR	SCL, SDA signals' rising time		1000	20+0.1Cb	300	ns
tHD;DAT	Data hold time	0		0	0.9	μs
tHIGH	The hold time in SCL clock 1 status	4.0		0.6		μs
tF	SCL, SDA signals' falling time		300	20+0.1Cb	300	ns
tSU;DAT	Data setup time	250		100		ns
tSU;STA	The setup time in restart condition	4.7		0.6		μs
tSU;STO	Stop condition setup time	4.0		0.6		μs

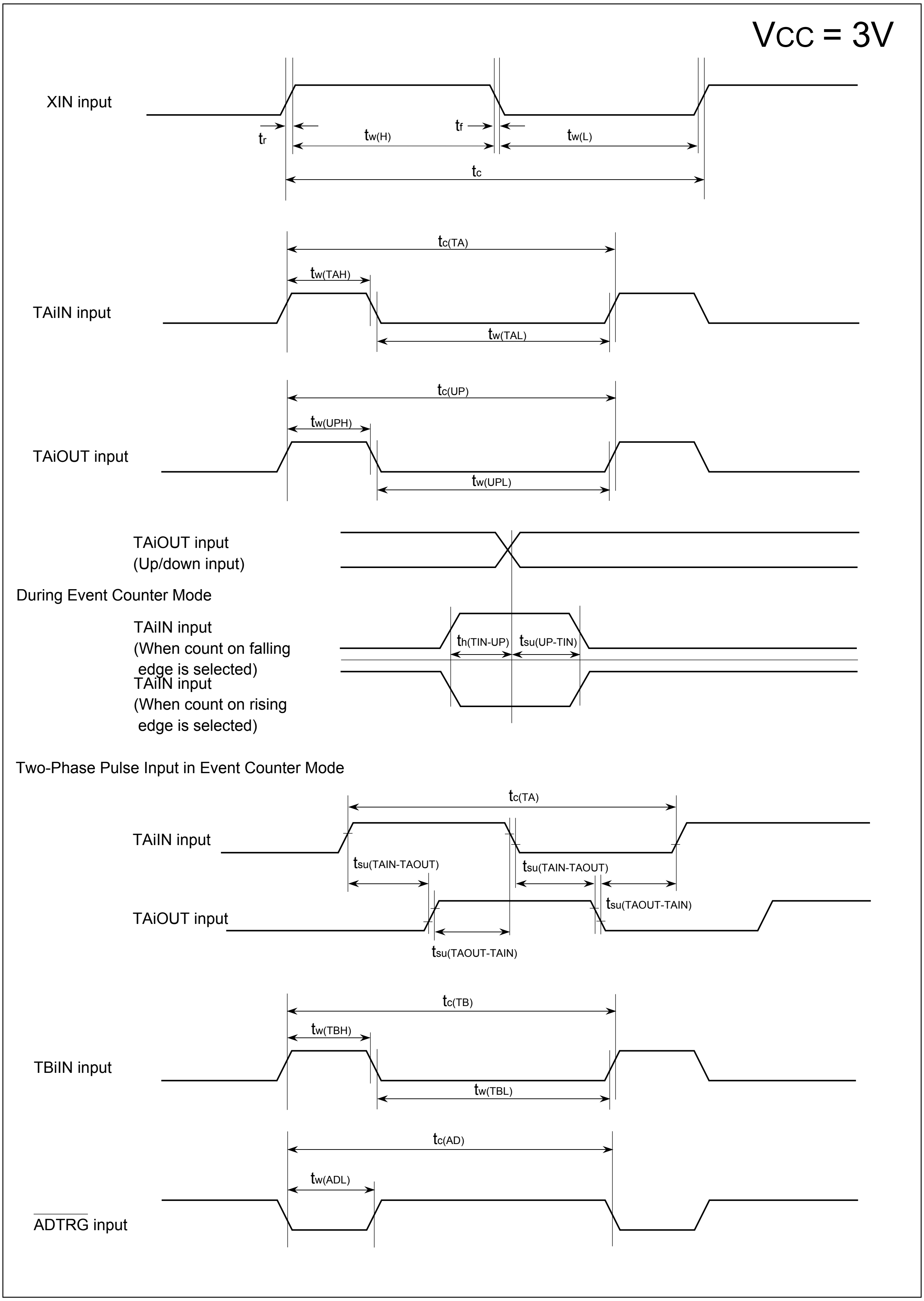


Figure 21.4 Timing Diagram (1)

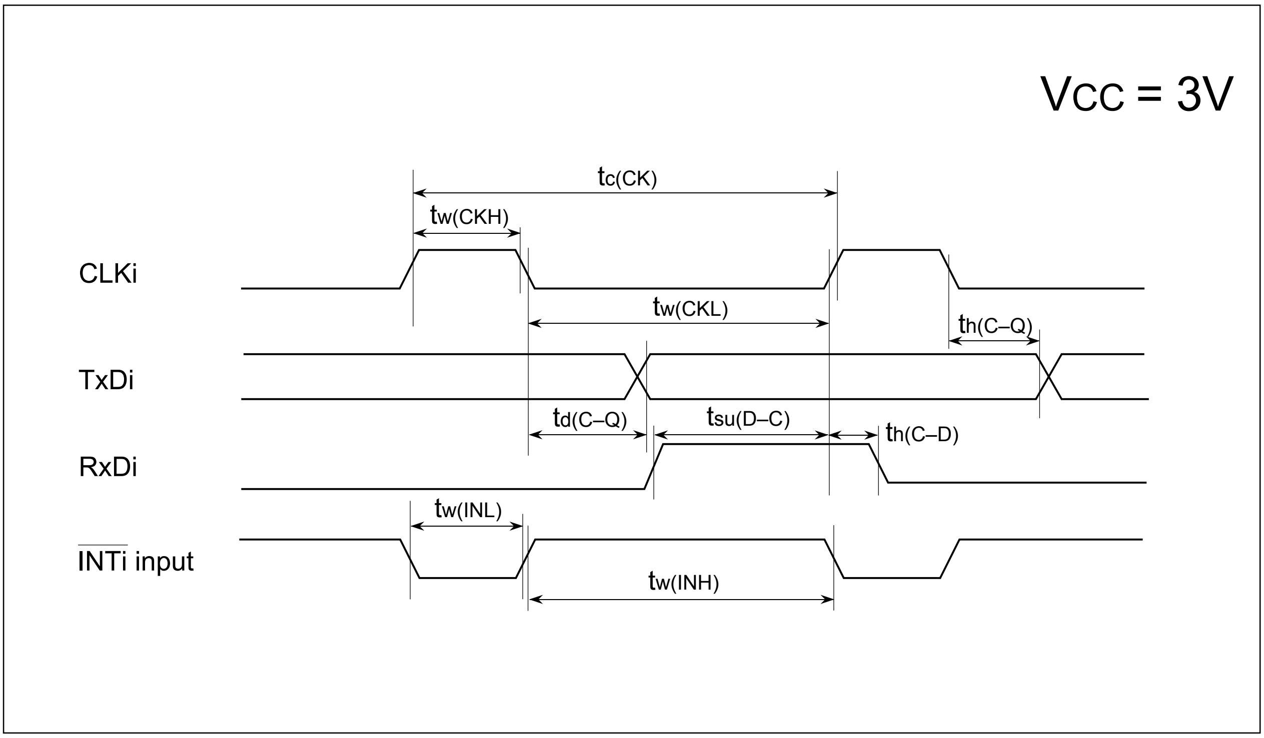


Figure 21.5 Timing Diagram (2)

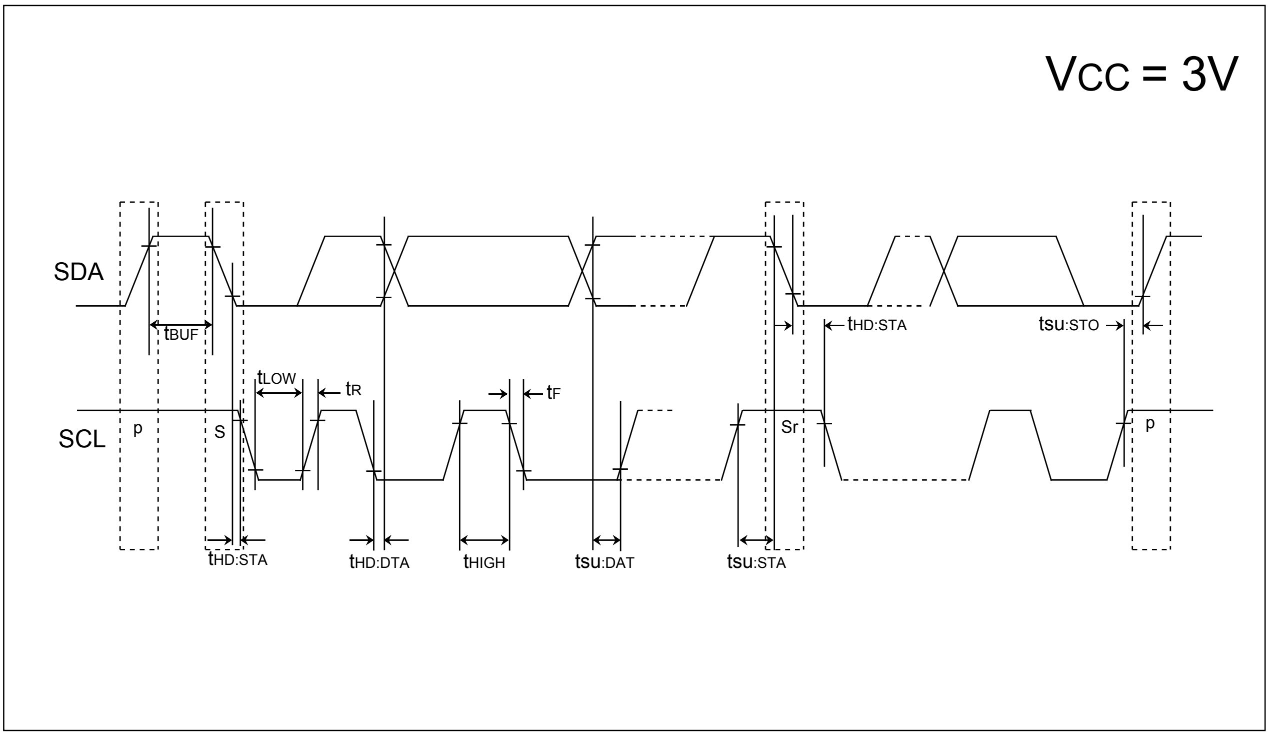


Figure 21.6 Timing Diagram (3)

21.2 T version

Table 21.40 Absolute Maximum Ratings

Symbol	Parameter			Condition	Value	Unit
V_{CC}	Supply Voltage			V_{CC}=AV_{CC}	-0.3 to 6.5	V
AV_{CC}	Analog Supply Voltage			V_{CC}=AV_{CC}	-0.3 to 6.5	V
V_I	Input Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, V_{REF}, $\overline{RESET}$, CNV_{SS}			-0.3 to V_{CC}+0.3	V
V_O	Output Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{OUT}			-0.3 to V_{CC}+0.3	V
Pd	Power Dissipation			$-40 \leq Topr \leq 85$° C	300	mW
Topr	Operating Ambient Temperature	during CPU operation			-40 to 85	° C
		during flash memory program and erase operation	Program Space (Block 0 to Block 5)		0 to 60	° C
			Data Space (Block A, Block B)		-40 to 85	° C
Tstg	Storage Temperature				-65 to 150	° C

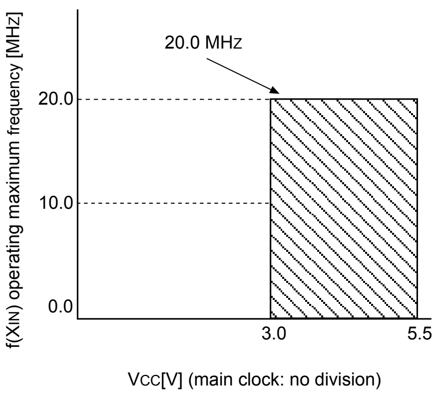
Table 21.41 Recommended Operating Conditions (Note 1)

Symbol	Parameter			Standard			Unit
				Min.	Typ.	Max.	
V_{CC}	Supply Voltage			3.0		5.5	V
AV_{CC}	Analog Supply Voltage				V_{CC}		V
V_{SS}	Supply Voltage				0		V
AV_{SS}	Analog Supply Voltage				0		V
V_{IH}	Input High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		$0.7V_{CC}$		V_{CC}	V
		XIN, $\overline{RESET}$, CNVSS		$0.8V_{CC}$		V_{CC}	V
		SDA_{MM}, SCL_{MM}	When I2C bus input level is selected	$0.7V_{CC}$		V_{CC}	V
			When SMBUS input level is selected	1.4		V_{CC}	V
V_{IL}	Input Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		0		$0.3V_{CC}$	V
		XIN, $\overline{RESET}$, CNVSS		0		$0.2V_{CC}$	V
		SDA_{MM}, SCL_{MM}	When I2C bus input level is selected	0		$0.3V_{CC}$	V
			When SMBUS input level is selected	0		0.6	V
$I_{OH(peak)}$	Peak Output High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				-10.0	mA
$I_{OH(avg)}$	Average Output High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				-5.0	mA
$I_{OL(peak)}$	Peak Output Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				10.0	mA
$I_{OL(avg)}$	Average Output Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				5.0	mA
$f(X_{IN})$	Main Clock Input Oscillation Frequency(4)			0		20	MHz
$f(X_{CIN})$	Sub Clock Oscillation Frequency				32.768	50	kHz
$f_1(ROC)$	On-chip Oscillator Frequency 1			0.5	1	2	MHz
f2(ROC)	On-chip Oscillator Frequency 2			1	2	4	MHz
f3(ROC)	On-chip Oscillator Frequency 3			8	16	26	MHz
f(PLL)	PLL Clock Oscillation Frequency(4)			10		20	MHz
f(BCLK)	CPU Operation Clock Frequency			0		20	MHz
$t_{SU}(PLL)$	Wait Time to Stabilize PLL Frequency Synthesizer		V_{CC}=5.0V			20	ms
			V_{CC}=3.0V			50	ms

NOTES:

1. Referenced to V_{CC} = 3.0 to 5.5V at Topr = -40 to 85 ° C unless otherwise specified.
2. The mean output current is the mean value within 100ms.
3. The total $I_{OL(peak)}$ for all ports must be 80mA or less. The total $I_{OH(peak)}$ for all ports must be -80mA or less.
4. Relationship among main clock oscillation frequency, PLL clock oscillation frequency and supply voltage.

Main clock input oscillation frequency



PLL clock oscillation frequency

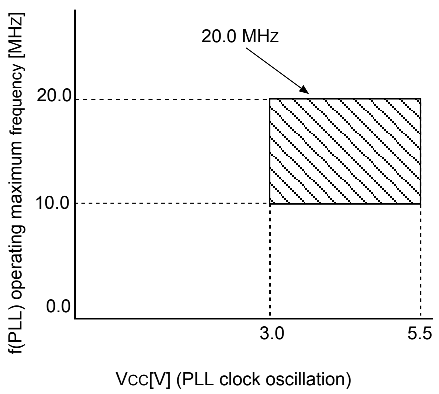


Table 21.42 A/D Conversion Characteristics (Note 1)

Symbol	Parameter		Measurement Condition	Standard			Unit
				Min.	Typ.	Max.	
-	Resolution		VREF = VCC			10	Bits
INL	Integral Nonlinearity Error	10 bit	VREF = VCC = 5 V			±3	LSB
			VREF = VCC = 3.3 V			±5	LSB
		8 bit	VREF = VCC = 3.3 V			±2	LSB
-	Absolute Accuracy	10 bit	VREF = VCC = 5 V			±3	LSB
			VREF = VCC = 3.3 V			±5	LSB
		8 bit	VREF = VCC = 3.3 V			±2	LSB
DNL	Differential Nonlinearity Error					±1	LSB
-	Offset Error					±3	LSB
-	Gain Error					±3	LSB
RLADDER	Resistor Ladder		VREF = VCC	10		40	kΩ
tCONV	10-bit Conversion Time Sample & Hold Function Available		VREF = VCC=5 V, øAD = 10 MHz	3.3			µs
tCONV	8-bit Conversion Time Sample & Hold Function Available		VREF = VCC = 5 V, øAD = 10 MHz	2.8			µs
VREF	Reference Voltage			2.0		VCC	V
VIA	Analog Input Voltage			0		VREF	V

NOTES:
1. Referenced to VCC = AVCC = VREF= 3.3 to 5.5 V, VSS = AVSS= 0 V at Topr = -40 to 85° C unless otherwise specified.
2. Keep φAD frequency at 10 MHz or less. Additionally, divide the fAD if VCC is less than 4.2 V, and make φAD frequency equal to or lower than fAD/2.
3. When sample & hold function is disabled, keep φAD frequency at 250 kHz or more in addition to the limitation in Note 2. When sample & hold function is enabled, keep φAD frequency at 1 MHz or more in addition to the limitation in Note 2.
4. When sample & hold function is enabled, sampling time is 3/ φAD frequency. When sample & hold function is disabled, sampling time is 2/ φAD frequency.

Table 21.43 Flash Memory Version Electrical Characteristics [1] for 100/1000 E/W cycle products [Program Space and Data Space in U3; Program Space in U7]

Symbol	Parameter		Standard Min.	Standard Typ.[2]	Standard Max.	Unit
-	Program and Erase Endurance[3]		100/1000[4, 11]			cycles
-	Word Program Time (V_{CC} = 5.0 V, Topr = 25° C)			75	600	µs
-	Block Erase Time (V_{CC} = 5.0 V, Topr = 25° C)	2-Kbyte Block		0.2	9	s
		8-Kbyte Block		0.4	9	s
		16-Kbyte Block		0.7	9	s
		32-Kbyte Block		1.2	9	s
td(SR-ES)	Duration between Suspend Request and Erase Suspend				8	ms
t_{PS}	Wait Time to Stabilize Flash Memory Circuit				15	µs
-	Data Hold Time [5]		20			years

Table 21.44 Flash Memory Version Electrical Characteristics [6] for 10000 E/W cycle products [Data Space in U7[7]]

Symbol	Parameter	Standard Min.	Standard Typ.[2]	Standard Max.	Unit
-	Program and Erase Endurance[3, 8, 9]	10000[4, 10]			cycles
-	Word Program Time (V_{CC} = 5.0 V, Topr = 25° C)		100		µs
-	Block Erase Time (V_{CC} = 5.0V, Topr = 25° C) (2-Kbyte block)		0.3		s
td(SR-ES)	Duration between Suspend Request and Erase Suspend			8	ms
t_{PS}	Wait Time to Stabilize Flash Memory Circuit			15	µs
-	Data Hold Time [5]	20			years

NOTES:

1. Referenced to VCC = 3.0 to 5.5 V at Topr = 0 to 60° C (program space)/ Topr = -40 to 85° C(data space), unless otherwise specified.
2. VCC = 5.0 V; TOPR = 25° C
3. Program and erase endurance is defined as number of program-erase cycles per block.
   If program and erase endurance is *n* cycle (*n* = 100, 1000, 10000), each block can be erased and programmed *n* cycles.
   For example, if a 2-Kbyte block A is erased after programming one-word data to each address 1,024 times, this counts as one program and erase endurance. Data cannot be programmed to the same address more than once without erasing the block. (rewrite prohibited).
4. Number of E/W cycles for which operation is guranteed (1 to minimum value are guranteed).
5. Topr = 55° C
6. Referenced to VCC = 3.0 to 5.5 V at Topr = -40 to 85° C unless otherwise specified.
7. **Table 21.44** applies for data space in U7 when program and erase endurance is more than 1,000 cycles. Otherwise, use **Table 21.43**.
8. To reduce the number of program and erase endurance when working with systems requiring numerous rewrites, write to unused word addresses within the block instead of rewrite. Erase block only after all possible addresses are used. For example, an 8-word program can be written 128 times maximum before erase becomes necessary. Maintaining an equal number of times erasure between block A and block B will also improve efficiency. It is recommended to track the total number of erasure performed per block and to limit the number of erasure.
9. If an erase error is generated during block erase, execute the clear status register command and block erase command at least 3 times until an erase error is not generated.
10. When executing more than 100 times rewrites, set one wait state per block access by setting the FMR17 bit in the FMR1 register to 1 (wait state). When accessing to all other blocks and internal RAM, wait state can be set by the PM17 bit, regardless of the FMR17 bit setting value.
11. The program and erase endurance is 100 cycles for program space and data space in U3; 1,000 cycles for program space in U7.
12. Please contact Renesas Technology Corp. or an authorized Renesas Technology Corp. product distributor for further details on the E/W failure rate.

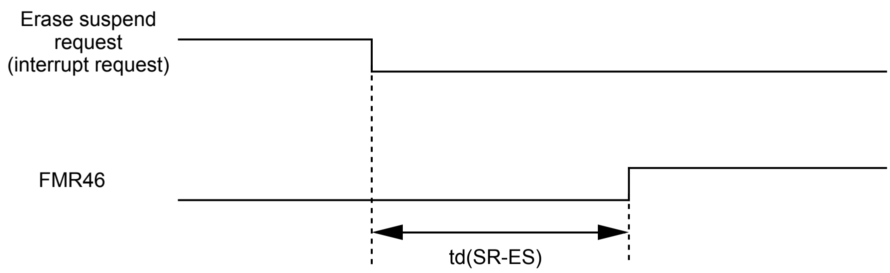
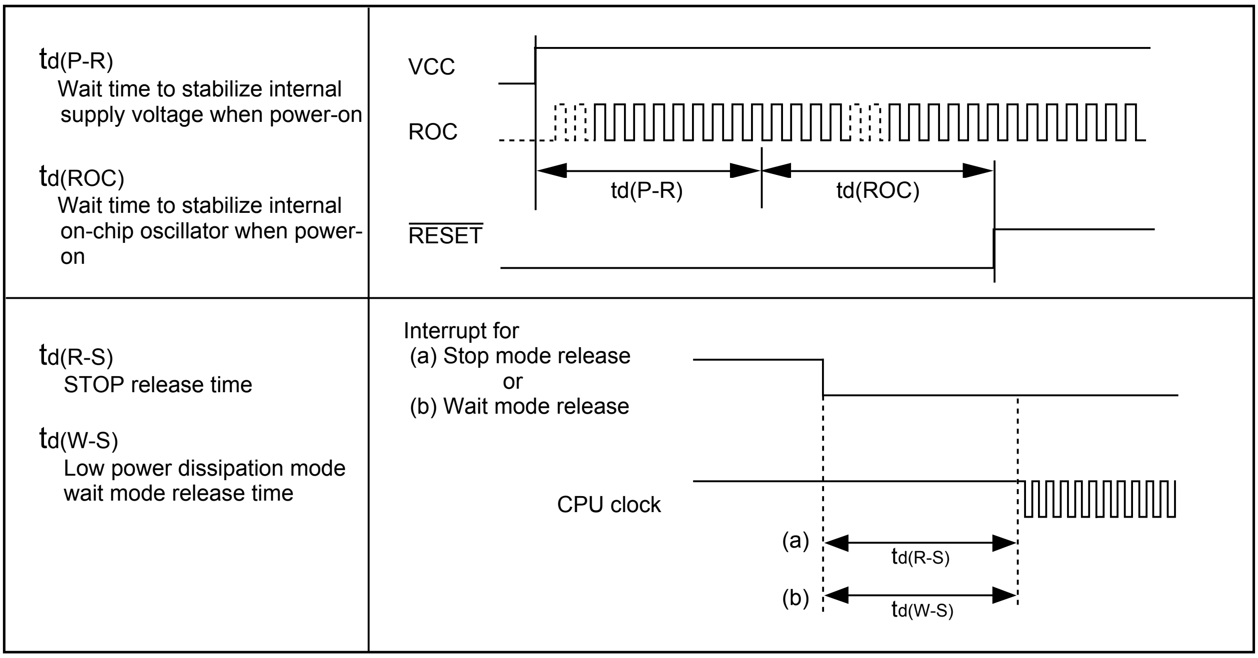


Table 21.45 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
td(P-R)	Wait Time to Stabilize Internal Supply Voltage when Power-on	Vcc = 3.0 to 5.5V			2	ms
td(ROC)	Wait Time to Stabilize Internal On-chip Oscillator when Power-on				40	µs
td(R-S)	STOP Release Time(1)				150	µs
td(W-S)	Low Power Dissipation Mode Wait Mode Release Time				150	µs



VCC = 5V

Table 21.46 Electrical Characteristics (Note 1)

Symbol	Parameter			Condition	Standard Min.	Standard Typ.	Standard Max.	Unit
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -5 mA	V_{CC}-2.0		V_{CC}	V
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -200 µA	V_{CC}-0.3		V_{CC}	V
V_{OH}	Output High ("H") Voltage	X_{OUT}	High Power	I_{OH} = -1 mA	V_{CC}-2.0		V_{CC}	V
			Low Power	I_{OH} = -0.5 mA	V_{CC}-2.0		V_{CC}	
	Output High ("H") Voltage	X_{COUT}	High Power	No load applied		2.5		V
			Low Power	No load applied		1.6		
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 5 mA			2.0	V
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 200 µA			0.45	V
V_{OL}	Output Low ("L") Voltage	X_{OUT}	High Power	I_{OL} = 1 mA			2.0	V
			Low Power	I_{OL} = 0.5 mA			2.0	
	Output Low ("L") Voltage	X_{COUT}	High Power	No load applied		0		V
			Low Power	No load applied		0		
V_{T+}-V_{T-}	Hysteresis	$TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB2_{IN}$, $\overline{INT_0}$-$\overline{INT_5}$, $\overline{NMI}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$-$\overline{CTS_2}$, SCL, SDA, CLK_0-CLK_2, $TA2_{OUT}$-$TA4_{OUT}$, $\overline{KI_0}$-$\overline{KI_3}$, R_{XD0}-R_{XD2}, S_{IN3}, S_{IN4}			0.2		1.0	V
V_{T+}-V_{T-}	Hysteresis	$\overline{RESET}$			0.2		2.5	V
V_{T+}-V_{T-}	Hysteresis	X_{IN}			0.2		0.8	V
I_{IH}	Input High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 5 V			5.0	µA
I_{IL}	Input Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 0 V			-5.0	µA
R_{PULLUP}	Pull-up Resistance	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		V_I = 0 V	30	50	170	kΩ
R_{fXIN}	Feedback Resistance	X_{IN}				1.5		MΩ
R_{fXCIN}	Feedback Resistance	X_{CIN}				15		MΩ
V_{RAM}	RAM Standby Voltage			In stop mode	2.0			V

NOTES:

1. Referenced to V_{CC}=4.2 to 5.5V, V_{SS}=0V at Topr=-40 to 85 ° C, f(BCLK)=20MHz unless otherwise specified.

VCC = 5V

Table 21.47 Electrical Characteristics (2) (Note 1)

Symbol	Parameter	Measurement Condition			Standard			Unit
					Min.	Typ.	Max.	
I_{CC}	Power Supply Current (V_{CC}=4.2 to 5.5V)	Output pins are left open and other pins are connected to V_{SS}	Mask ROM	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory program	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Flash memory erase	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Mask ROM	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on ROM(3)		25		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		50		µA
			Flash memory	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on RAM(3)		25		µA
				f(BCLK) = 32 kHz, In low-power consumption mode, Program running on flash memory(3)		450		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		50		µA
			Mask ROM, Flash memory	f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity high		8.5		µA
				f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity low		3		µA
				While clock stops, Topr = 25° C		0.8	3	µA

NOTES:

1. Referenced to V_{CC} = 4.2 to 5.5 V, V_{SS} = 0 V at Topr = -40 to 85 ° C, f(BCLK) = 20 MHz unless otherwise specified.
2. With one timer operates, using f_{C32}.
3. This indicates the memory in which the program to be executed exists.

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.48 External Clock Input (XIN input)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t_c	External Clock Input Cycle Time	50		ns
$t_{w(H)}$	External Clock Input High ("H") Width	20		ns
$t_{w(L)}$	External Clock Input Low ("L") Width	20		ns
t_r	External Clock Rise Time		9	ns
t_f	External Clock Fall Time		9	ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.49 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	100		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	40		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	40		ns

Table 21.50 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	400		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	200		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	200		ns

Table 21.51 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	200		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	100		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	100		ns

Table 21.52 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{w(TAH)}$	TAiIN input HIGH pulse width	100		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	100		ns

Table 21.53 Timer A Input (Counter Increment/decrement Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(UP)}$	TAiOUT input cycle time	2000		ns
$t_{w(UPH)}$	TAiOUT input HIGH pulse width	1000		ns
$t_{w(UPL)}$	TAiOUT input LOW pulse width	1000		ns
$t_{su(UP-TIN)}$	TAiOUT input setup time	400		ns
$t_{h(TIN-UP)}$	TAiOUT input hold time	400		ns

Table 21.54 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	800		ns
$t_{su(TAIN-TAOUT)}$	TAiOUT input setup time	200		ns
$t_{su(TAOUT-TAIN)}$	TAiIN input setup time	200		ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.55 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBiIN input cycle time (counted on one edge)	100		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on one edge)	40		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on one edge)	40		ns
$t_{c(TB)}$	TBiIN input cycle time (counted on both edges)	200		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width (counted on both edges)	80		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width (counted on both edges)	80		ns

Table 21.56 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBiIN input cycle time	400		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	200		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	200		ns

Table 21.57 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBiIN input cycle time	400		ns
$t_{w(TBH)}$	TBiIN input HIGH pulse width	200		ns
$t_{w(TBL)}$	TBiIN input LOW pulse width	200		ns

Table 21.58 A/D Trigger Input

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(AD)}$	$\overline{\text{ADTRG}}$ input cycle time (trigger able minimum)	1000		ns
$t_{w(ADL)}$	$\overline{\text{ADTRG}}$ input LOW pulse width	125		ns

Table 21.59 Serial I/O

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(CK)}$	CLKi input cycle time	200		ns
$t_{w(CKH)}$	CLKi input HIGH pulse width	100		ns
$t_{w(CKL)}$	CLKi input LOW pulse width	100		ns
$t_{d(C-Q)}$	TxDi output delay time		80	ns
$t_{h(C-Q)}$	TxDi hold time	0		ns
$t_{su(D-C)}$	RxDi input setup time	70		ns
$t_{h(C-D)}$	RxDi input hold time	90		ns

Table 21.60 External Interrupt $\overline{\text{INTi}}$ Input

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{w(INH)}$	$\overline{\text{INTi}}$ input HIGH pulse width	250		ns
$t_{w(INL)}$	$\overline{\text{INTi}}$ input LOW pulse width	250		ns

VCC = 5V

Timing Requirements

(VCC = 5V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.61 Multi-master I²C bus Line

Symbol	Parameter	Standard clock mode		High-speed clock mode		Unit
		Min.	Max.	Min.	Max.	
t_{BUF}	Bus free time	4.7		1.3		µs
$t_{HD;STA}$	The hold time in start condition	4.0		0.6		µs
t_{LOW}	The hold time in SCL clock 0 status	4.7		1.3		µs
t_R	SCL, SDA signals' rising time		1000	20+0.1Cb	300	ns
$t_{HD;DAT}$	Data hold time	0		0	0.9	µs
t_{HIGH}	The hold time in SCL clock 1 status	4.0		0.6		µs
t_F	SCL, SDA signals' falling time		300	20+0.1Cb	300	ns
$t_{SU;DAT}$	Data setup time	250		100		ns
$t_{SU;STA}$	The setup time in restart condition	4.7		0.6		µs
$t_{SU;STO}$	Stop condition setup time	4.0		0.6		µs

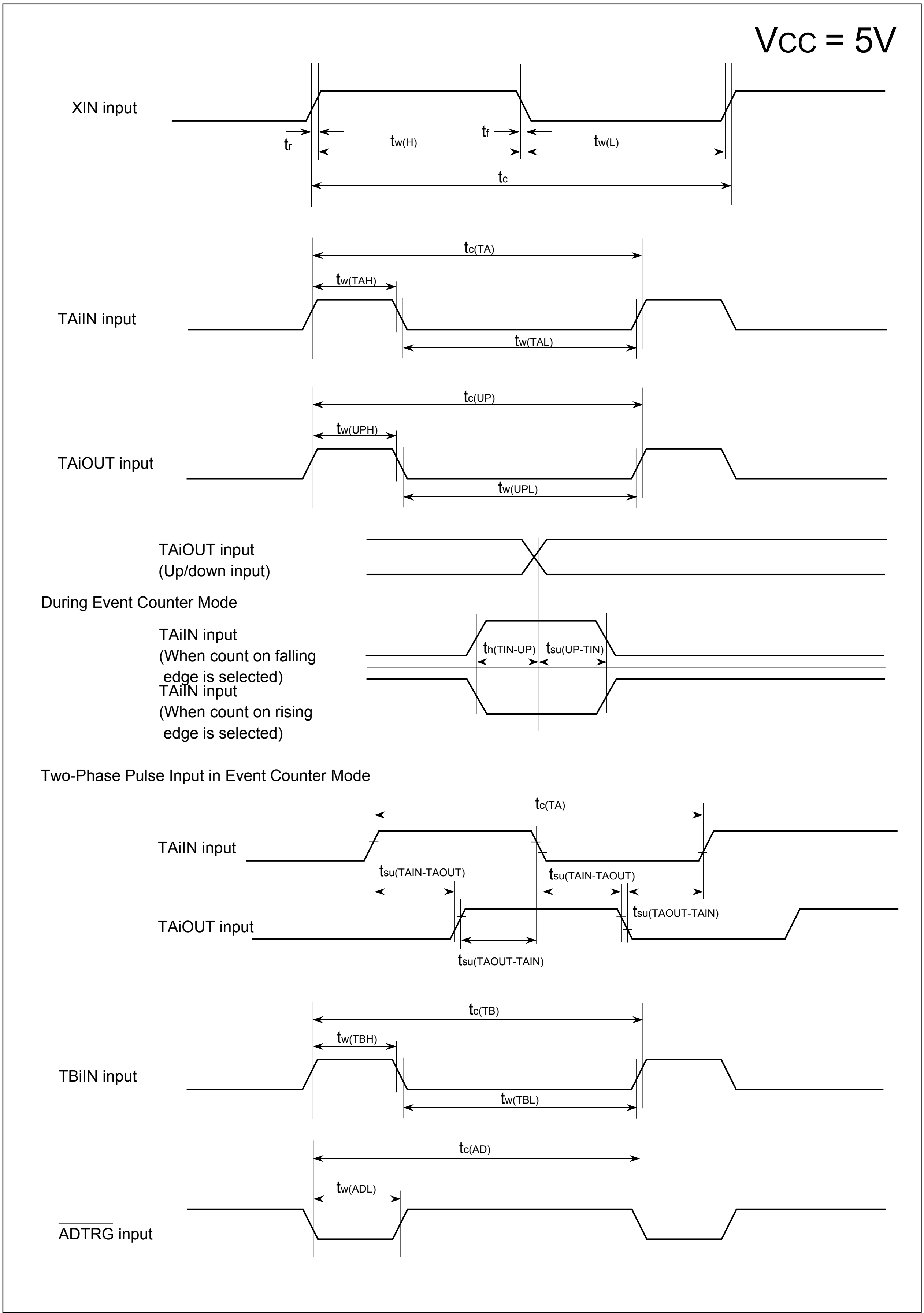


Figure 21.7 Timing Diagram (1)

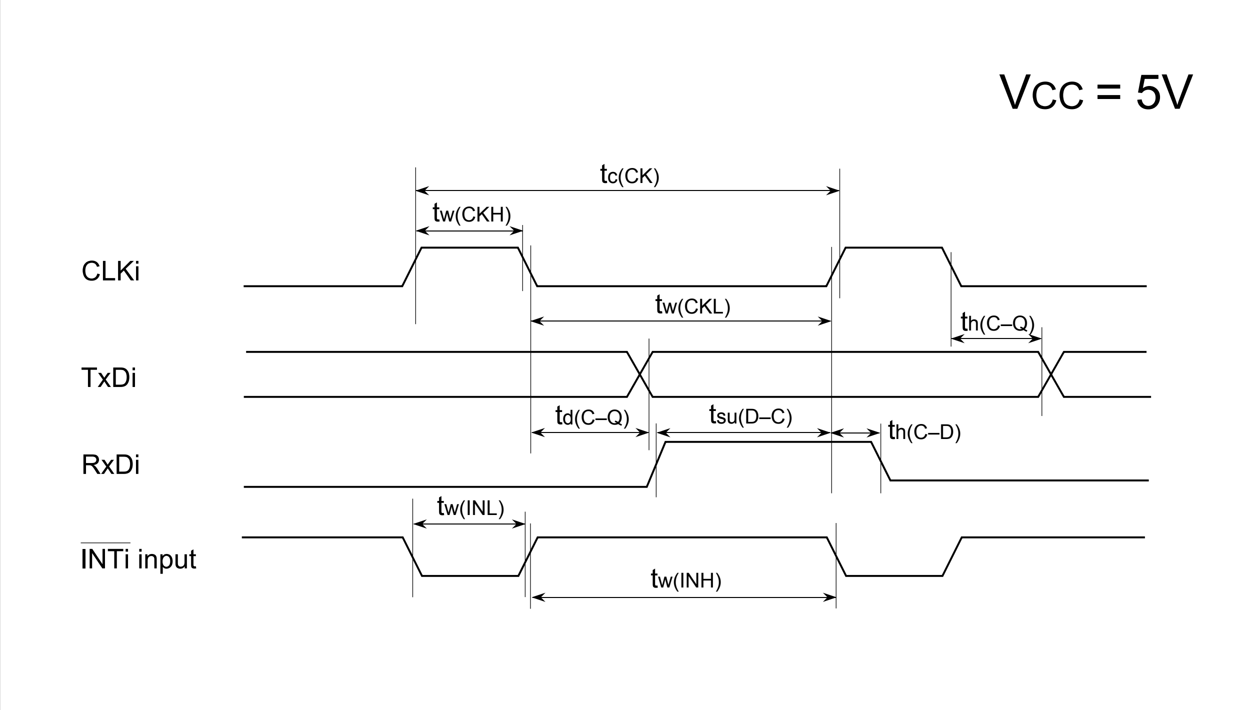


Figure 21.8 Timing Diagram (2)

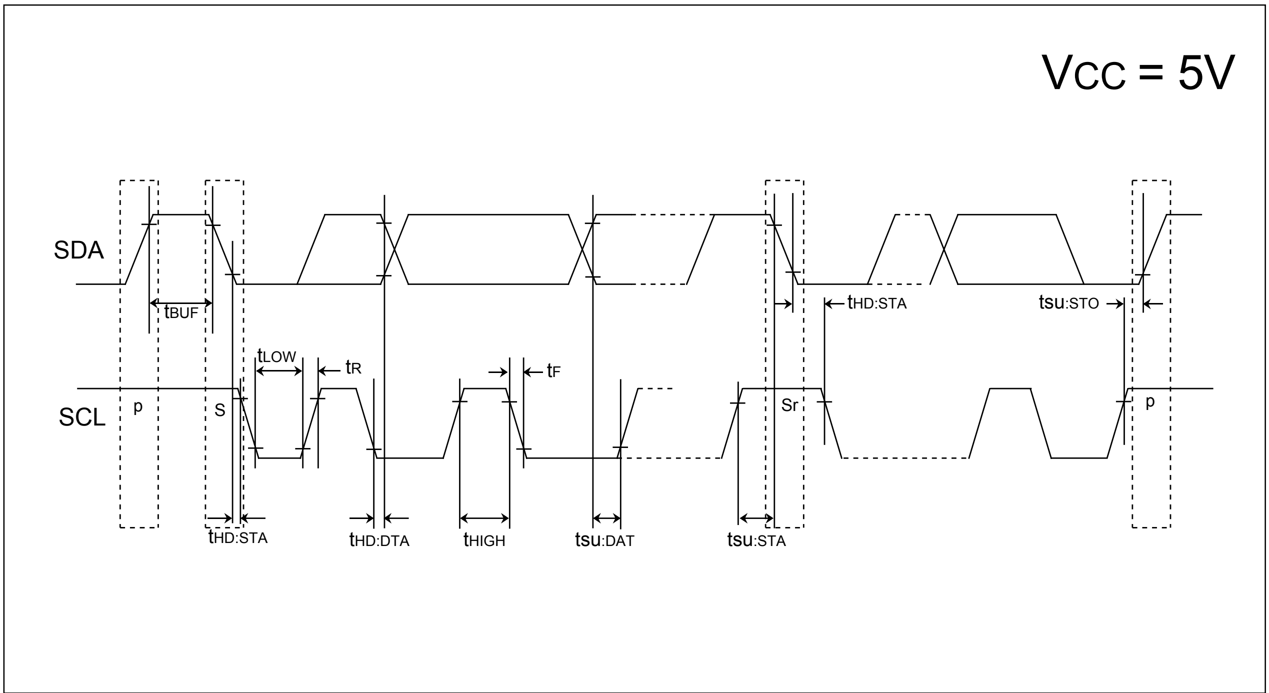


Figure 21.9 Timing Diagram (3)

V_{CC} = 3V

Table 21.62 Electrical Characteristics (Note)

Symbol	Parameter			Condition	Standard Min.	Standard Typ.	Standard Max.	Unit
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -1 mA	V_{CC}-0.5		V_{CC}	V
V_{OH}	Output High ("H") Voltage	X_{OUT}	High Power	I_{OH} = -0.1 mA	V_{CC}-0.5		V_{CC}	V
			Low Power	I_{OH} = -50 µA	V_{CC}-0.5		V_{CC}	
	Output High ("H") Voltage	X_{COUT}	High Power	No load applied		2.5		V
			Low Power	No load applied		1.6		
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 1 mA			0.5	V
V_{OL}	Output Low ("L") Voltage	X_{OUT}	High Power	I_{OL} = 0.1 mA			0.5	V
			Low Power	I_{OL} = 50 µA			0.5	
	Output Low ("L") Voltage	X_{COUT}	High Power	No load applied		0		V
			Low Power	No load applied		0		
V_{T+}-V_{T-}	Hysteresis	$TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB2_{IN}$, $\overline{INT_0}$-$\overline{INT_5}$, $\overline{NMI}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$-$\overline{CTS_2}$, SCL, SDA, CLK_0-CLK_2, $TA2_{OUT}$-$TA4_{OUT}$, $\overline{KI_0}$-$\overline{KI_3}$, R_{XD0}-R_{XD2}, S_{IN3}, S_{IN4}					0.8	V
V_{T+}-V_{T-}	Hysteresis	$\overline{RESET}$					1.8	V
V_{T+}-V_{T-}	Hysteresis	X_{IN}					0.8	V
I_{IH}	Input High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 3 V			4.0	µA
I_{IL}	Input Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 0 V			-4.0	µA
R_{PULLUP}	Pull-up Resistance	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		V_I = 0 V	50	100	500	kΩ
R_{fXIN}	Feedback Resistance	X_{IN}				3.0		MΩ
R_{fXCIN}	Feedback Resistance	X_{CIN}				25		MΩ
V_{RAM}	RAM Standby Voltage			In stop mode	2.0			V

NOTE:

1. Referenced to V_{CC} = 3.0 to 3.6 V, V_{SS} = 0 V at Topr = -40 to 85 ° C, f(BCLK) = 20 MHz unless otherwise specified.

VCC = 3V

Table 21.63 Electrical Characteristics (2) (Note 1)

Symbol	Parameter	Measurement Condition			Standard Min.	Standard Typ.	Standard Max.	Unit
I_{CC}	Power Supply Current (V_{CC}=3.0 to 3.6V)	Output pins are left open and other pins are connected to V_{SS}	Mask ROM	f(BCLK) = 10 MHz, main clock, no division		8	13	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		1		mA
			Flash memory	f(BCLK) = 10 MHz, main clock, no division		8	13	mA
			Flash memory program	f(BCLK) = 10 MHz, Vcc = 3.0 V		11		mA
			Flash memory erase	f(BCLK) = 10MHz, Vcc = 3.0 V		11		mA
			Mask ROM	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on ROM(3)		20		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		25		µA
			Flash memory	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on RAM(3)		20		µA
				f(BCLK) = 32 kHz, In low-power consumption mode, Program running on flash memory(3)		450		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		45		µA
			Mask ROM, Flash memory	f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity high		6.6		µA
				f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity low		2.2		µA
				While clock stops, Topr = 25° C		0.7	3	µA

NOTES:
1. Referenced to V_{CC} = 3.0 to 3.6 V, V_{SS} = 0 V at Topr = -40 to 85 ° C, f(BCLK) = 20 MHz unless otherwise specified.
2. With one timer operates, using f_{C32}.
3. This indicates the memory in which the program to be executed exists.

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.64 External Clock Input (XIN input)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
t_c	External clock input cycle time	100		ns
$t_{w(H)}$	External clock input HIGH pulse width	40		ns
$t_{w(L)}$	External clock input LOW pulse width	40		ns
t_r	External clock rise time		18	ns
t_f	External clock fall time		18	ns

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.65 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	150		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	60		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	60		ns

Table 21.66 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	600		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	300		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	300		ns

Table 21.67 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	300		ns
$t_{w(TAH)}$	TAiIN input HIGH pulse width	150		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	150		ns

Table 21.68 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{w(TAH)}$	TAiIN input HIGH pulse width	150		ns
$t_{w(TAL)}$	TAiIN input LOW pulse width	150		ns

Table 21.69 Timer A Input (Counter Increment/decrement Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(UP)}$	TAiOUT input cycle time	3000		ns
$t_{w(UPH)}$	TAiOUT input HIGH pulse width	1500		ns
$t_{w(UPL)}$	TAiOUT input LOW pulse width	1500		ns
$t_{su(UP-TIN)}$	TAiOUT input setup time	600		ns
$t_{h(TIN-UP)}$	TAiOUT input hold time	600		ns

Table 21.70 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TA)}$	TAiIN input cycle time	2		μs
$t_{su(TAIN-TAOUT)}$	TAiOUT input setup time	500		ns
$t_{su(TAOUT-TAIN)}$	TAiIN input setup time	500		ns

$V_{CC} = 3V$

Timing Requirements

(V_{CC} = 3V, V_{SS} = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.71 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBi_{IN} input cycle time (counted on one edge)	150		ns
$t_{w(TBH)}$	TBi_{IN} input HIGH pulse width (counted on one edge)	60		ns
$t_{w(TBL)}$	TBi_{IN} input LOW pulse width (counted on one edge)	60		ns
$t_{c(TB)}$	TBi_{IN} input cycle time (counted on both edges)	300		ns
$t_{w(TBH)}$	TBi_{IN} input HIGH pulse width (counted on both edges)	120		ns
$t_{w(TBL)}$	TBi_{IN} input LOW pulse width (counted on both edges)	120		ns

Table 21.72 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBi_{IN} input cycle time	600		ns
$t_{w(TBH)}$	TBi_{IN} input HIGH pulse width	300		ns
$t_{w(TBL)}$	TBi_{IN} input LOW pulse width	300		ns

Table 21.73 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(TB)}$	TBi_{IN} input cycle time	600		ns
$t_{w(TBH)}$	TBi_{IN} input HIGH pulse width	300		ns
$t_{w(TBL)}$	TBi_{IN} input LOW pulse width	300		ns

Table 21.74 A/D Trigger Input

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(AD)}$	$\overline{AD_{TRG}}$ input cycle time (trigger able minimum)	1500		ns
$t_{w(ADL)}$	$\overline{AD_{TRG}}$ input LOW pulse width	200		ns

Table 21.75 Serial I/O

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{c(CK)}$	CLKi input cycle time	300		ns
$t_{w(CKH)}$	CLKi input HIGH pulse width	150		ns
$t_{w(CKL)}$	CLKi input LOW pulse width	150		ns
$t_{d(C-Q)}$	TxDi output delay time		160	ns
$t_{h(C-Q)}$	TxDi hold time	0		ns
$t_{su(D-C)}$	RxDi input setup time	100		ns
$t_{h(C-D)}$	RxDi input hold time	90		ns

Table 21.76 External Interrupt $\overline{INTi}$ Input

Symbol	Parameter	Standard Min.	Standard Max.	Unit
$t_{w(INH)}$	$\overline{INTi}$ input HIGH pulse width	380		ns
$t_{w(INL)}$	$\overline{INTi}$ input LOW pulse width	380		ns

VCC = 3V

Timing Requirements

(VCC = 3V, VSS = 0V, at Topr = – 40 to 85°C unless otherwise specified)

Table 21.77 Multi-master I²C bus Line

Symbol	Parameter	Standard clock mode		High-speed clock mode		Unit
		Min.	Max.	Min.	Max.	
t_{BUF}	Bus free time	4.7		1.3		μs
$t_{HD;STA}$	The hold time in start condition	4.0		0.6		μs
t_{LOW}	The hold time in SCL clock 0 status	4.7		1.3		μs
t_R	SCL, SDA signals' rising time		1000	20+0.1Cb	300	ns
$t_{HD;DAT}$	Data hold time	0		0	0.9	μs
t_{HIGH}	The hold time in SCL clock 1 status	4.0		0.6		μs
t_F	SCL, SDA signals' falling time		300	20+0.1Cb	300	ns
$t_{SU;DAT}$	Data setup time	250		100		ns
$t_{SU;STA}$	The setup time in restart condition	4.7		0.6		μs
$t_{SU;STO}$	Stop condition setup time	4.0		0.6		μs

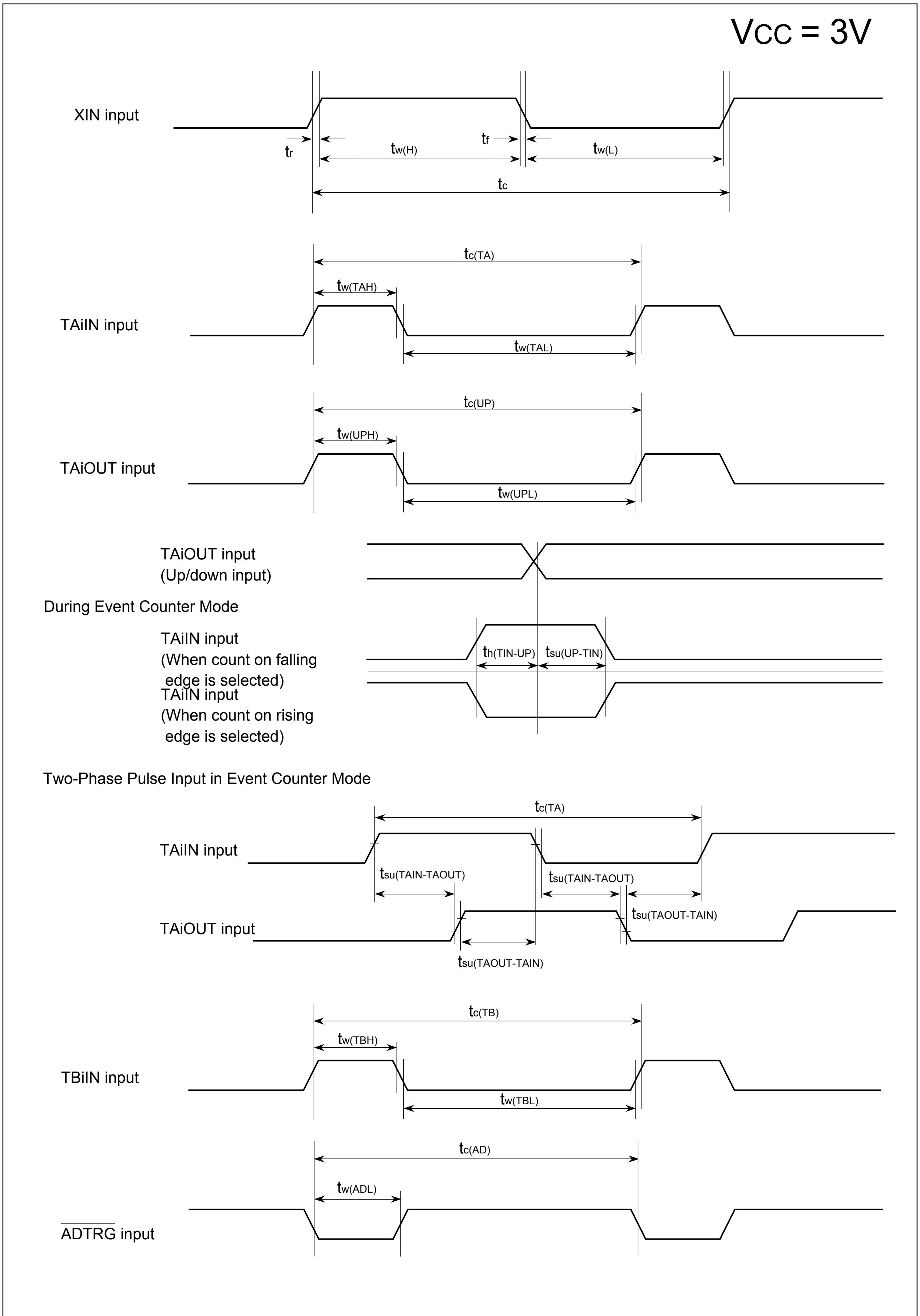


Figure 21.10 Timing Diagram (1)

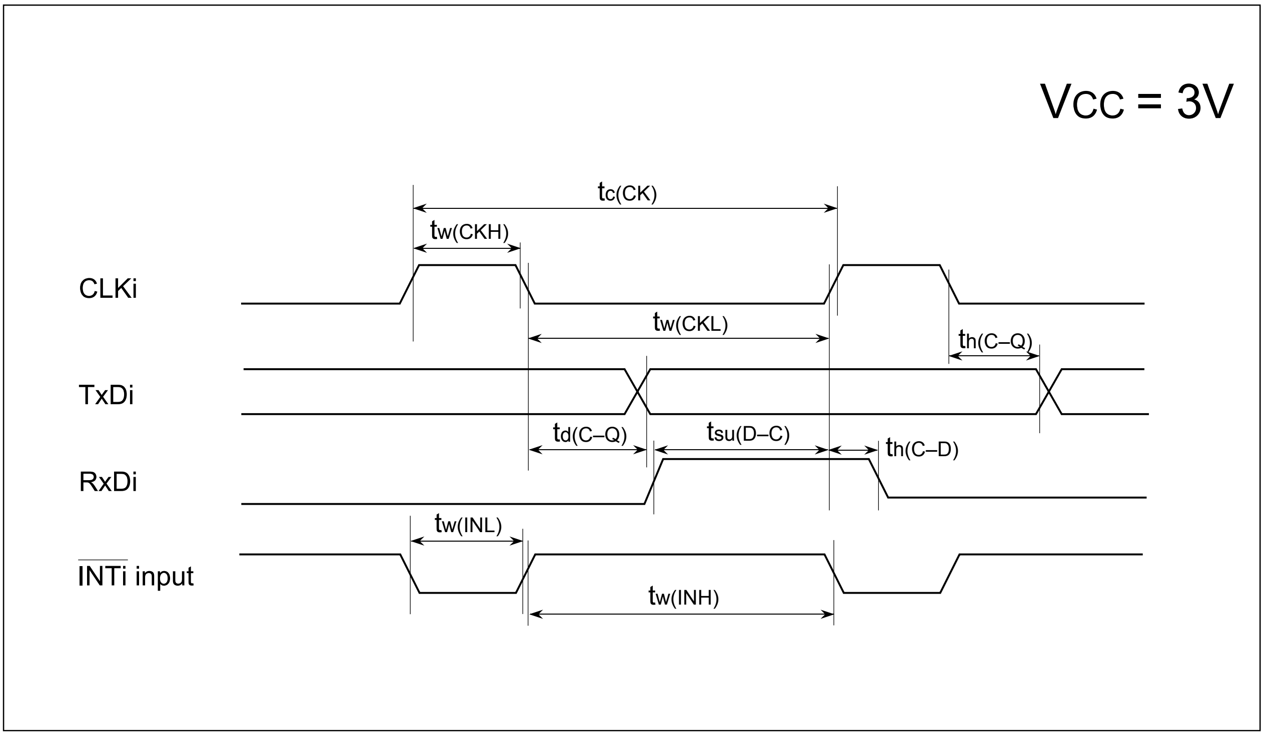


Figure 21.11 Timing Diagram (2)

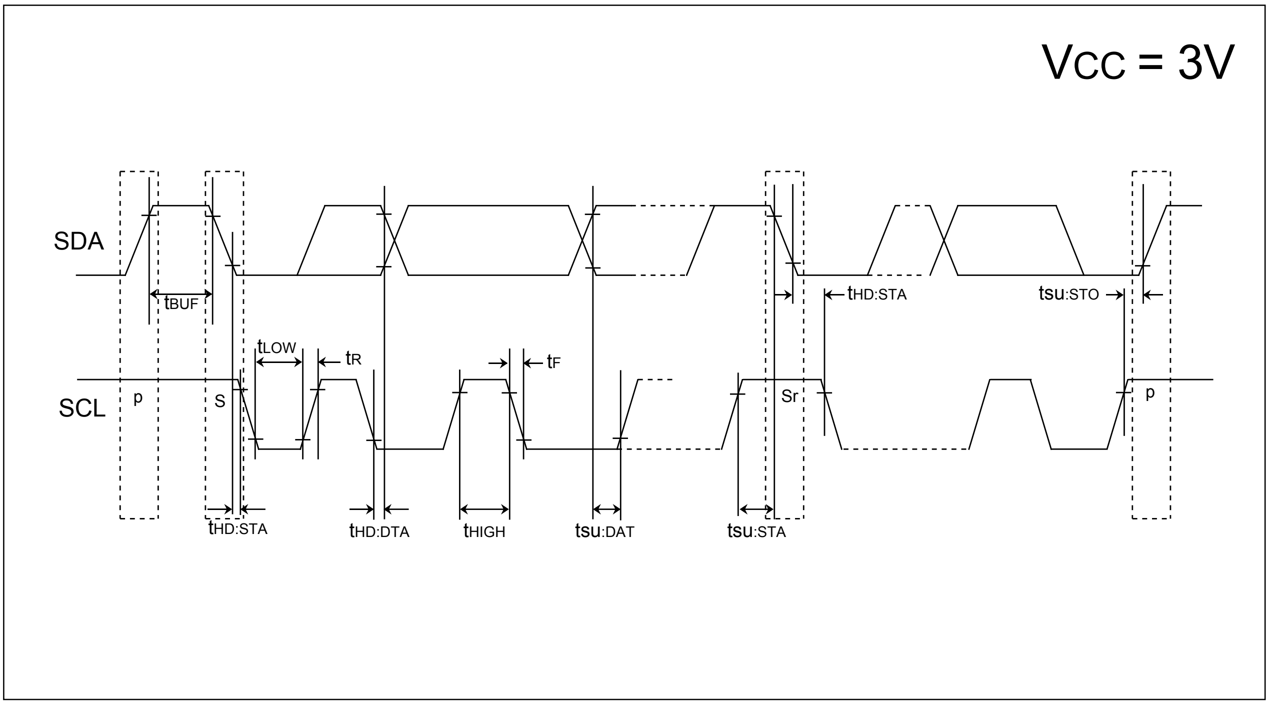


Figure 21.12 Timing Diagram (3)

21.3 V Version

Table 21.78 Absolute Maximum Ratings

Symbol	Parameter			Condition	Value	Unit
V_{CC}	Supply Voltage			V_{CC}=AV_{CC}	-0.3 to 6.5	V
AV_{CC}	Analog Supply Voltage			V_{CC}=AV_{CC}	-0.3 to 6.5	V
V_I	Input Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{IN}, V_{REF}, $\overline{RESET}$, CNV_{SS}			-0.3 to V_{CC}+0.3	V
V_O	Output Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$, X_{OUT}			-0.3 to V_{CC}+0.3	V
Pd	Power Dissipation			$-40 \le Topr \le 85$° C	300	mW
				$85 \le Topr \le 125$° C	200	mW
Topr	Operating Ambient Temperature	during CPU operation			-40 to 125	° C
		during flash memory program and erase operation	Program Space (Block 0 to Block 5)		0 to 60	° C
			Data Space (Block A, Block B)		-40 to 125	° C
Tstg	Storage Temperature				-65 to 150	° C

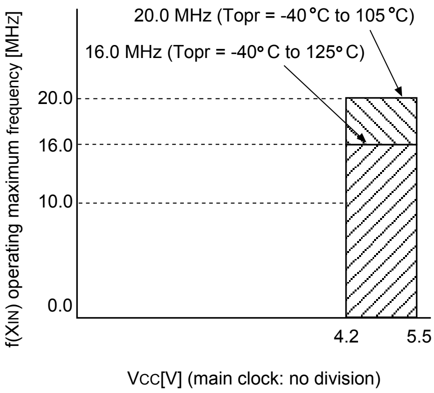
Table 21.79 Recommended Operating Conditions (1)

Symbol	Parameter			Standard Min.	Standard Typ.	Standard Max.	Unit
V_{CC}	Supply Voltage			4.2		5.5	V
AV_{CC}	Analog Supply Voltage				V_{CC}		V
V_{SS}	Supply Voltage				0		V
AV_{SS}	Analog Supply Voltage				0		V
V_{IH}	Input High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		0.7 V_{CC}		V_{CC}	V
		XIN, $\overline{\text{RESET}}$, CNVSS		0.8 V_{CC}		V_{CC}	V
		SDA_{MM}, SCL_{MM}	When I^2C bus input level is selected	0.7 V_{CC}		V_{CC}	V
			When SMBUS input level is selected	1.4		V_{CC}	V
V_{IL}	Input Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		0		0.3V_{CC}	V
		XIN, $\overline{\text{RESET}}$, CNVSS		0		0.2V_{CC}	V
		SDA_{MM}, SCL_{MM}	When I^2C bus input level is selected	0		0.3V_{CC}	V
			When SMBUS input level is selected	0		0.6	V
$I_{OH(peak)}$	Peak Output High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				-10.0	mA
$I_{OH(avg)}$	Average Output High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				-5.0	mA
$I_{OL(peak)}$	Peak Output Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				10.0	mA
$I_{OL(avg)}$	Average Output Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$				5.0	mA
$f(X_{IN})$	Main Clock Input Oscillation Frequency(4)		Topr = -40 to 105 ° C	0		20	MHz
			Topr = -40 to 125 ° C	0		16	MHz
$f(X_{CIN})$	Sub Clock Oscillation Frequency				32.768	50	kHz
f_1(ROC)	On-chip Oscillator Frequency 1			0.5	1	2	MHz
f2(ROC)	On-chip Oscillator Frequency 2			1	2	4	MHz
f3(ROC)	On-chip Oscillator Frequency 3			8	16	26	MHz
f(PLL)	PLL Clock Oscillation Frequency(4)		Topr = -40 to 105 ° C	10		20	MHz
			Topr = -40 to 125 ° C	10		16	MHz
f(BCLK)	CPU Operation Clock Frequency		Topr = -40 to 105 ° C	0		20	MHz
			Topr = -40 to 125 ° C	0		16	MHz
t_{SU}(PLL)	Wait Time to Stabilize PLL Frequency Synthesizer		Vcc = 5.0 V			20	MHz

NOTES:

1. Referenced to V_{CC} = 4.2 to 5.5 V at Topr = -40 to 125 ° C unless otherwise specified.
2. The mean output current is the mean value within 100ms.
3. The total $I_{OL(peak)}$ for all ports must be 80 mA or less. The total $I_{OH(peak)}$ for all ports must be -80 mA or less.
4. Relationship among main clock oscillation frequency, PLL clock oscillation frequency and supply voltage.

Main clock input oscillation frequency



PLL clock oscillation frequency

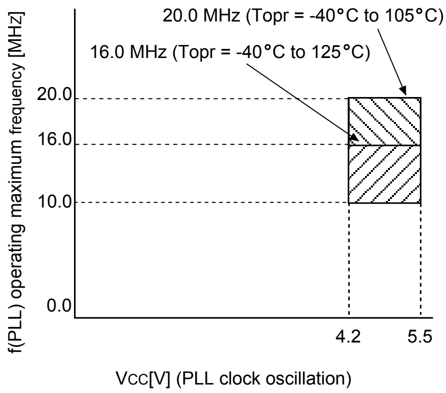


Table 21.80 A/D Conversion Characteristics (1)

Symbol	Parameter		Measurement Condition	Standard			Unit
				Min.	Typ.	Max.	
-	Resolution		$V_{REF} = V_{CC}$			10	Bits
INL	Integral Nonlinearity Error	10 bit	$V_{REF} = V_{CC} = 5$ V			±3	LSB
		8 bit	$V_{REF} = V_{CC} = 5$ V			±2	LSB
-	Absolute Accuracy	10 bit	$V_{REF} = V_{CC} = 5$ V			±3	LSB
		8 bit	$V_{REF} = V_{CC} = 5$ V			±2	LSB
DNL	Differential Nonlinearity Error					±1	LSB
-	Offset Error					±3	LSB
-	Gain Error					±3	LSB
R_{LADDER}	Resistor Ladder		$V_{REF} = V_{CC}$	10		40	kΩ
t_{CONV}	10-bit Conversion Time Sample & Hold Function Available		$V_{REF} = V_{CC} = 5$ V, $\phi AD = 10$ MHz	3.3			µs
t_{CONV}	8-bit Conversion Time Sample & Hold Function Available		$V_{REF} = V_{CC} = 5$ V, $\phi AD = 10$ MHz	2.8			µs
V_{REF}	Reference Voltage			2.0		V_{CC}	V
V_{IA}	Analog Input Voltage			0		V_{REF}	V

NOTES:

1. Referenced to $V_{CC} = AV_{CC} = V_{REF} = 4.2$ to 5.5 V, $V_{SS} = AV_{SS} = 0$ V at Topr = -40 to 125 ° C unless otherwise specified.
2. Keep ϕAD frequency at 10 MHz or less.
3. When sample & hold function is disabled, keep ϕAD frequency at 250kHz or more in addition to the limitation in Note 2.
   When sample & hold function is enabled, keep ϕAD frequency at 1MHz or more in addition to the limitation in Note 2.
4. When sample & hold function is enabled, sampling time is 3/ ϕAD frequency.
   When sample & hold function is disabled, sampling time is 2/ ϕAD frequency.

Table 21.81 Flash Memory Version Electrical Characteristics (1) for 100/1000 E/W cycle products [Program Space and Data Space in U3; Program Space in U7]

Symbol	Parameter		Standard			Unit
			Min.	Typ.(2)	Max.	
-	Program and Erase Endurance(3)		100/1000(4, 11)			cycles
-	Word Program Time (Vcc = 5.0 V, Topr = 25° C)			75	600	µs
-	Block Erase Time (Vcc = 5.0 V, Topr = 25° C)	2-Kbyte Block		0.2	9	s
		8-Kbyte Block		0.4	9	s
		16-Kbyte Block		0.7	9	s
		32-Kbyte Block		1.2	9	s
td(SR-ES)	Duration between Suspend Request and Erase Suspend				8	ms
tPS	Wait Time to Stabilize Flash Memory Circuit				15	µs
-	Data Hold Time (5)		20			years

Table 21.82 Flash Memory Version Electrical Characteristics (6) for 10000 E/W cycle products [Data Space in U7 (7)]

Symbol	Parameter	Standard			Unit
		Min.	Typ.(2)	Max.	
-	Program and Erase Endurance(3, 8, 9)	10000(4, 10)			cycles
-	Word Program Time (Vcc = 5.0 V, Topr = 25° C)		100		µs
-	Block Erase Time (Vcc = 5.0V, Topr = 25° C) (2-Kbyte block)		0.3		s
td(SR-ES)	Duration between Suspend Request and Erase Suspend			8	ms
tPS	Wait Time to Stabilize Flash Memory Circuit			15	µs
-	Data Hold Time (5)	20			years

NOTES:
1. Referenced to VCC = 4.2 to 5.5 V at Topr = 0 to 60° C (program space)/ Topr = -40 to 125° C(data space), unless otherwise specified.
2. VCC = 5.0 V; TOPR = 25° C
3. Program and erase endurance is defined as number of program-erase cycles per block.
   If program and erase endurance is *n* cycle (*n* = 100, 1000, 10000), each block can be erased and programmed *n* cycles.
   For example, if a 2-Kbyte block A is erased after programming one-word data to each address 1,024 times, this counts as one program and erase endurance. Data cannot be programmed to the same address more than once without erasing the block. (rewrite prohibited).
4. Number of E/W cycles for which operation is guranteed (1 to minimum value are guranteed).
5. Topr = 55° C
6. Referenced to VCC = 4.2 to 5.5 V at Topr = -40 to 125° C unless otherwise specified.
7. **Table 21.82** applies for data space in U7 when program and erase endurance is more than 1,000 cycles. Otherwise, use **Table 21.81**.
8. To reduce the number of program and erase endurance when working with systems requiring numerous rewrites, write to unused word addresses within the block instead of rewrite. Erase block only after all possible addresses are used. For example, an 8-word program can be written 128 times maximum before erase becomes necessary. Maintaining an equal number of times erasure between block A and block B will also improve efficiency. It is recommended to track the total number of erasure performed per block and to limit the number of erasure.
9. If an erase error is generated during block erase, execute the clear status register command and block erase command at least 3 times until an erase error is not generated.
10. When executing more than 100 times rewrites, set one wait state per block access by setting the FMR17 bit in the FMR1 register to 1 (wait state). When accessing to all other blocks and internal RAM, wait state can be set by the PM17 bit, regardless of the FMR17 bit setting value.
11. The program and erase endurance is 100 cycles for program space and data space in U3; 1,000 cycles for program space in U7.
12. Please contact Renesas Technology Corp. or an authorized Renesas Technology Corp. product distributor for further details on the E/W failure rate.

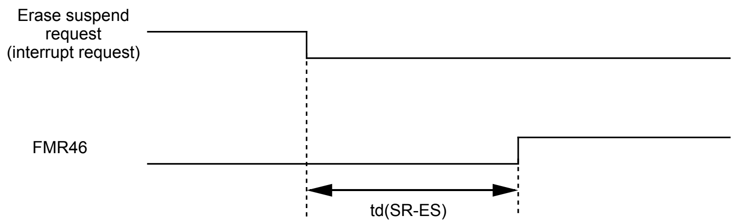
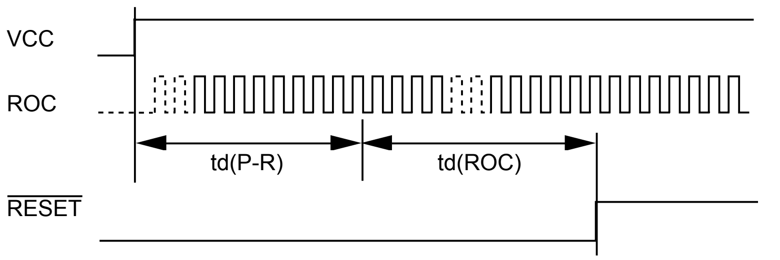


Table 21.83 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Measurement Condition	Standard			Unit
			Min.	Typ.	Max.	
td(P-R)	Wait Time to Stabilize Internal Supply Voltage when Power-on	V_{CC}=4.2 to 5.5V			2	ms
td(ROC)	Wait Time to Stabilize Internal On-chip Oscillator when Power-on				40	µs
td(S-R)	STOP Release Time				150	µs
td(E-A)	Low Power Dissipation Mode Wait Mode Release Time				150	µs

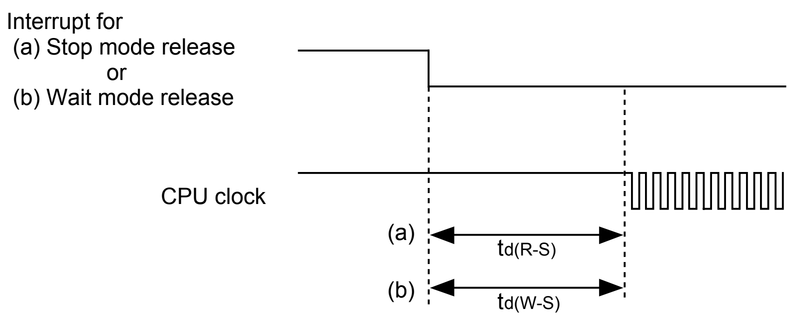
td(P-R)
Wait time to stabilize internal supply voltage when power-on

td(ROC)
Wait time to stabilize internal on-chip oscillator when power-on



td(R-S)
STOP release time

td(W-S)
Low power dissipation mode wait mode release time



$V_{CC} = 5V$

Table 21.84 Electrical Characteristics (1)

Symbol	Parameter			Condition	Standard Min.	Standard Typ.	Standard Max.	Unit
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -5 mA	V_{CC}-2.0		V_{CC}	V
V_{OH}	Output High ("H") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OH} = -200 µA	V_{CC}-0.3		V_{CC}	V
V_{OH}	Output High ("H") Voltage	X_{OUT}	High Power	I_{OH} = -1 mA	V_{CC}-2.0		V_{CC}	V
			Low Power	I_{OH} = -0.5 mA	V_{CC}-2.0		V_{CC}	
	Output High ("H") Voltage	X_{COUT}	High Power	No load applied		2.5		V
			Low Power	No load applied		1.6		
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 5 mA			2.0	V
V_{OL}	Output Low ("L") Voltage	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		I_{OL} = 200 µA			0.45	V
V_{OL}	Output Low ("L") Voltage	X_{OUT}	High Power	I_{OL} = 1 mA			2.0	V
			Low Power	I_{OL} = 0.5 mA			2.0	
	Output Low ("L") Voltage	X_{COUT}	High Power	No load applied		0		V
			Low Power	No load applied		0		
V_{T+}-V_{T-}	Hysteresis	$TA0_{IN}$-$TA4_{IN}$, $TB0_{IN}$-$TB2_{IN}$, $\overline{INT_0}$-$\overline{INT_5}$, $\overline{NMI}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$-$\overline{CTS_2}$, SCL, SDA, CLK_0-CLK_2, $TA2_{OUT}$-$TA4_{OUT}$, $\overline{KI_0}$-$\overline{KI_3}$, R_{XD0}-R_{XD2}, S_{IN3}, S_{IN4}			0.2		1.0	V
V_{T+}-V_{T-}	Hysteresis	$\overline{RESET}$			0.2		2.5	V
V_{T+}-V_{T-}	Hysteresis	X_{IN}			0.2		0.8	V
I_{IH}	Input High ("H") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 5 V			5.0	µA
I_{IL}	Input Low ("L") Current	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$ X_{IN}, $\overline{RESET}$, CNV_{SS}		V_I = 0 V			-5.0	µA
R_{PULLUP}	Pull-up Resistance	$P0_0$ to $P0_7$, $P1_0$ to $P1_7$, $P2_0$ to $P2_7$, $P3_0$ to $P3_7$, $P6_0$ to $P6_7$, $P7_0$ to $P7_7$, $P8_0$ to $P8_7$, $P9_0$ to $P9_3$, $P9_5$ to $P9_7$, $P10_0$ to $P10_7$		V_I = 0 V	30	50	170	kΩ
R_{fXIN}	Feedback Resistance	X_{IN}				1.5		MΩ
R_{fXCIN}	Feedback Resistance	X_{CIN}				15		MΩ
V_{RAM}	RAM Standby Voltage			In stop mode	2.0			V

NOTE:

1. Referenced to V_{CC} = 4.2 to 5.5 V, V_{SS} = 0 V at Topr = -40 to 105 ° C, f(BCLK) = 20 MHz / V_{CC} = 4.2 to 5.5 V, V_{SS} = 0 V at Topr = -40 to 125 ° C, f(BCLK) = 16 MHz, unless otherwise specified.

VCC = 5V

Table 21.85 Electrical Characteristics (2) (1)

Symbol	Parameter	Measurement Condition			Standard Min.	Standard Typ.	Standard Max.	Unit
I_{CC}	Power Supply Current (V_{CC}=4.2 to 5.5V)	Output pins are left open and other pins are connected to V_{SS}	Mask ROM	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				f(BCLK) = 16 MHz, main clock, no division		14	20	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory	f(BCLK) = 20 MHz, main clock, no division		18	25	mA
				f(BCLK) = 16 MHz, main clock, no division		14	20	mA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz		2		mA
			Flash memory program	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Flash memory erase	f(BCLK) = 10 MHz, Vcc = 5.0 V		11		mA
			Mask ROM	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on ROM(3)		25		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		50		µA
			Flash memory	f(BCLK) = 32 kHz, In low-power consumption mode, Program running on RAM(3)		25		µA
				f(BCLK) = 32 kHz, In low-power consumption mode, Program running on flash memory(3)		450		µA
				On-chip oscillation, $f_{2(ROC)}$ selected, f(BCLK) = 1 MHz, In wait mode		50		µA
			Mask ROM, Flash memory	f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity high		8.5		µA
				f(BCLK) = 32 kHz, In wait mode(2), Oscillation capacity low		3		µA
				While clock stops, Topr = 25° C		0.8	3	µA

NOTES:

1. Referenced to V_{CC} = 4.2 to 5.5 V, V_{SS} = 0 V at Topr = -40 to 105 ° C, f(BCLK) = 20MHz / V_{CC} = 4.2 to 5.5 V, V_{SS} = 0V at Topr = -40 to 125 ° C, f(BCLK) = 16 MHz, unless otherwise specified.
2. With one timer operates, using f_{C32}.
3. This indicates the memory in which the program to be executed exists.

VCC = 5V

Timing Requirements

(Vcc=5V, Vss=0V, at Topr=-40 to 125°C unless otherwise specified)

Table 21.86 External Clock Input (XIN input)

Symbol	Parameter		Standard		Unit
			Min.	Max.	
tc	External Clock Input Cycle Time	Topr=-40° C to 105° C	50		ns
		Topr=-40° C to 125° C	62.5		ns
$t_{w(H)}$	External Clock Input High ("H") Width	Topr=-40° C to 105° C	20		ns
		Topr=-40° C to 125° C	25		ns
$t_{w(L)}$	External Clock Input Low ("L") Width	Topr=-40° C to 105° C	20		ns
		Topr=-40° C to 125° C	25		ns
tr	External Clock Rise Time	Topr=-40° C to 105° C		9	ns
		Topr=-40° C to 125° C		15	ns
tf	External Clock Fall Time	Topr=-40° C to 105° C		9	ns
		Topr=-40° C to 125° C		15	ns

VCC = 5V

Timing Requirements

(VCC=5V, VSS=0V, at Topr=-40 to 125°C unless otherwise specified)

Table 21.87 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	100		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	40		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	40		ns

Table 21.88 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	400		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	200		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	200		ns

Table 21.89 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	200		ns
$t_{w(TAH)}$	TAiIN Input High ("H") Width	100		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	100		ns

Table 21.90 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(TAH)}$	TAiIN Input High ("H") Width	100		ns
$t_{w(TAL)}$	TAiIN Input Low ("L") Width	100		ns

Table 21.91 Timer A Input (Counter Increment/decrement Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(UP)}$	TAiOUT Input Cycle Time	2000		ns
$t_{w(UPH)}$	TAiOUT Input High ("H") Width	1000		ns
$t_{w(UPL)}$	TAiOUT Input Low ("L") Width	1000		ns
$t_{su(UP-TIN)}$	TAiOUT Input Setup Time	400		ns
$t_{h(TIN-UP)}$	TAiOUT Input Hold Time	400		ns

Table 21.92 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN Input Cycle Time	800		ns
$t_{su(TAIN-TAOUT)}$	TAiOUT Input Setup Time	200		ns
$t_{su(TAOUT-TAIN)}$	TAiIN Input Setup Time	200		ns

VCC = 5V

Timing Requirements

(VCC=5V, VSS=0V, at Topr=-40 to 125°C unless otherwise specified)

Table 21.93 Timer B Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN Input Cycle Time (counted on one edge)	100		ns
$t_{w(TBH)}$	TBiIN Input High ("H") Width (counted on one edge)	40		ns
$t_{w(TBL)}$	TBiIN Input Low ("L") Width (counted on one edge)	40		ns
$t_{c(TB)}$	TBiIN Input Cycle Time (counted on both edges)	200		ns
$t_{w(TBH)}$	TBiIN Input High ("H") Width (counted on both edges)	80		ns
$t_{w(TBL)}$	TBiIN Input Low ("L") Width (counted on both edges)	80		ns

Table 21.94 Timer B Input (Pulse Period Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN Input Cycle Time	400		ns
$t_{w(TBH)}$	TBiIN Input High ("H") Width	200		ns
$t_{w(TBL)}$	TBiIN Input Low ("L") Width	200		ns

Table 21.95 Timer B Input (Pulse Width Measurement Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN Input Cycle Time	400		ns
$t_{w(TBH)}$	TBiIN Input High ("H") Width	200		ns
$t_{w(TBL)}$	TBiIN Input Low ("L") Width	200		ns

Table 21.96 A/D Trigger Input

Symbol	Parameter	Standard		Unit
		Min.	Max	
$t_{c(AD)}$	$\overline{\text{ADTRG}}$ Input Cycle Time (required for trigger)	1000		ns
$t_{w(ADL)}$	$\overline{\text{ADTRG}}$ Input Low ("L") Width	125		ns

Table 21.97 Serial I/O

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi Input Cycle Time	200		ns
$t_{w(CKH)}$	CLKi Input High ("H") Width	100		ns
$t_{w(CKL)}$	CLKi Input Low ("L") Width	100		ns
$t_{d(C-Q)}$	TxDi Output Delay Time		80	ns
$t_{h(C-Q)}$	TxDi Hold Time	0		ns
$t_{su(D-C)}$	RxDi Input Setup Time	70		ns
$t_{h(C-Q)}$	RxDi Input Hold Time	90		ns

Table 21.98 External Interrupt $\overline{\text{INTi}}$ Input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{\text{INTi}}$ Input High ("H") Width	250		ns
$t_{w(INL)}$	$\overline{\text{INTi}}$ Input Low ("L") Width	250		ns

Vcc = 5V

Timing Requirements

(Vcc=5V, Vss=0V, at Topr=-40 to 125°C unless otherwise specified)

Table 21.99 Multi-master I²C Bus Line

Symbol	Parameter	Standard clock mode		High-speed clock mode		Unit
		Min.	Max.	Min.	Max.	
t_{BUF}	Bus free time	4.7		1.3		μs
$t_{HD;STA}$	The hold time in start condition	4.0		0.6		μs
t_{LOW}	The hold time in SCL clock "0" status	4.7		1.3		μs
t_R	SCL, SDA signals' rising time		1000	20+0.1Cb	300	ns
$t_{HD;DAT}$	Data hold time	0		0	0.9	μs
t_{HIGH}	The hold time in SCL clock "1" status	4.0		0.6		μs
t_F	SCL, SDA signals' falling time		300	20+0.1Cb	300	ns
$t_{SU;DAT}$	Data setup time	250		100		ns
$t_{SU;STA}$	The setup time in restart condition	4.7		0.6		μs
$t_{SU;STO}$	Stop condition setup time	4.0		0.6		μs

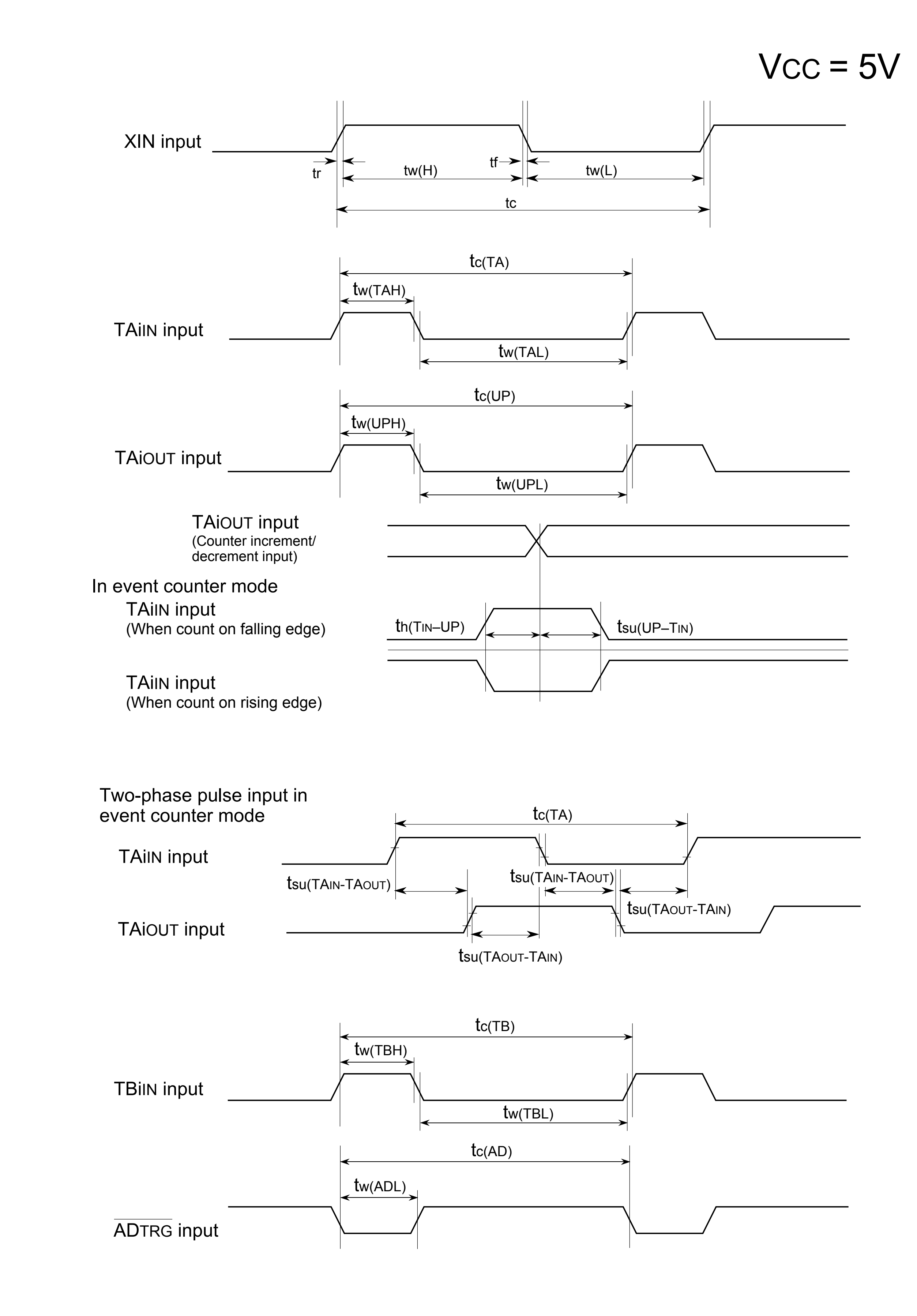


Figure 21.13 Timing Diagram (1)

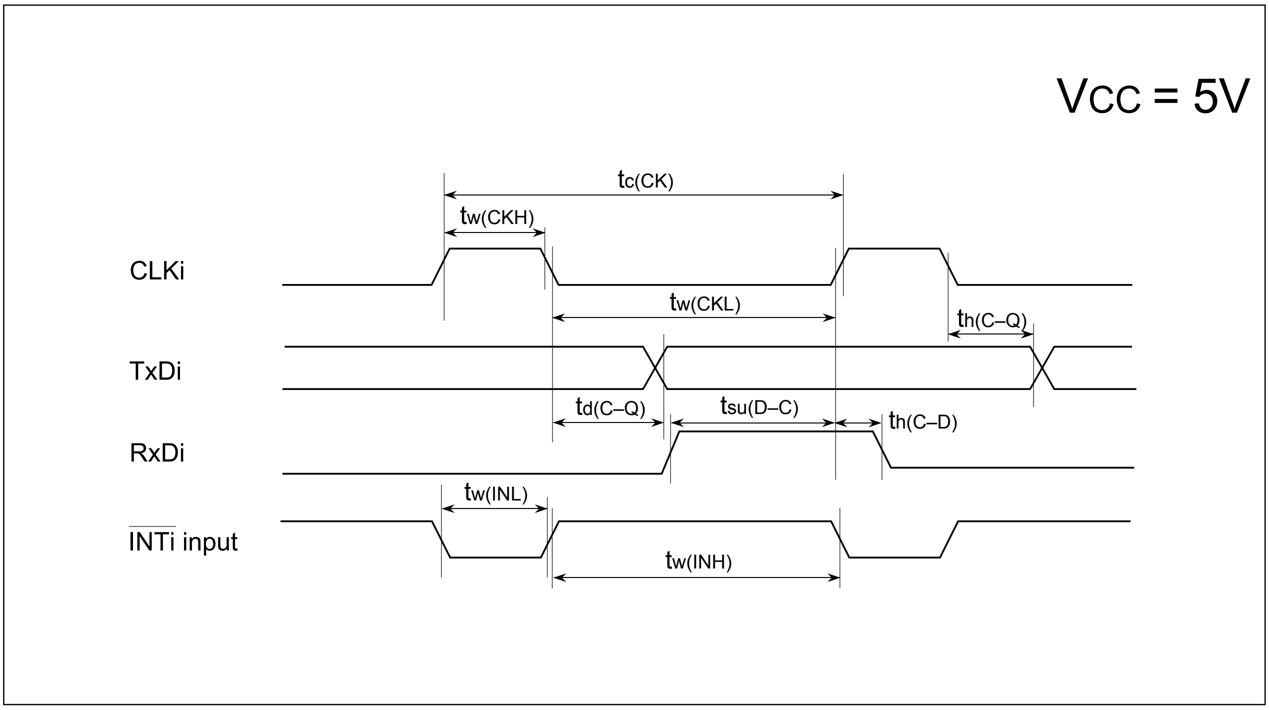


Figure 21.14 Timing Diagram (2)

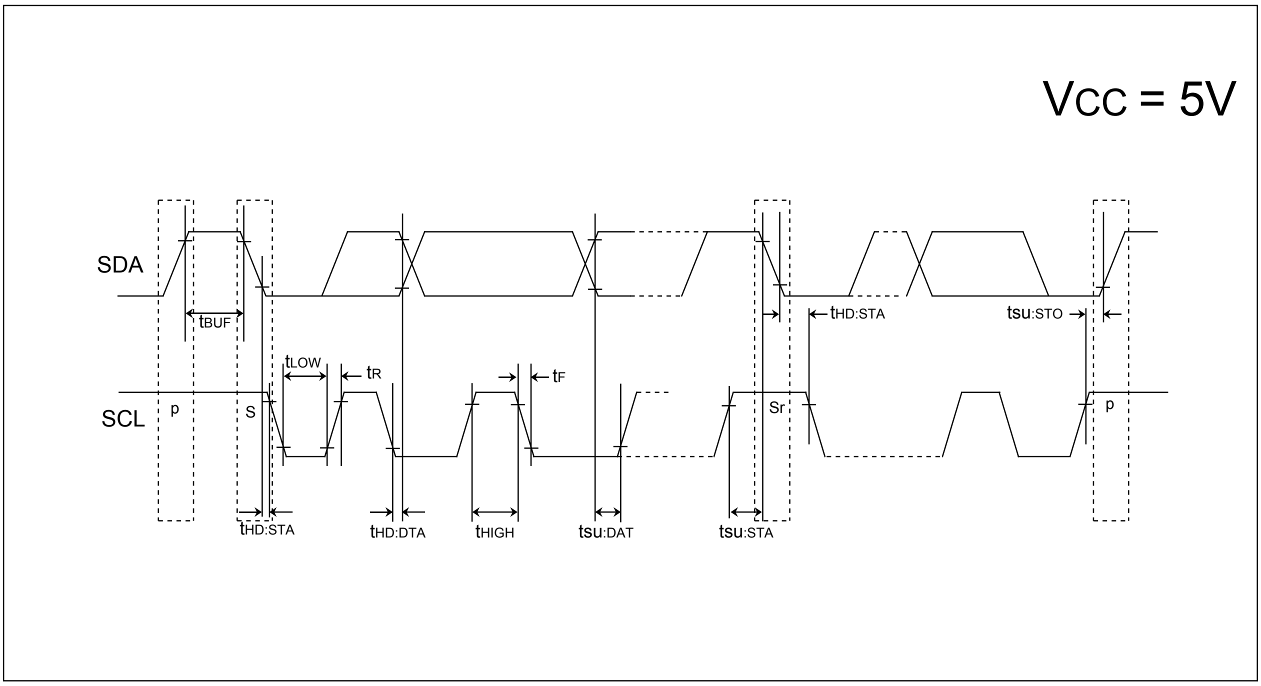


Figure 21.15 Timing Diagram (3)

22. Usage Notes

22.1 SFRs

22.1.1 For 80-Pin Package

Set the IFSR20 bit in the IFSR2A register to 0 after reset and set bits PACR2 to PACR0 in the PACR register to 011_2.

22.1.2 For 64-Pin Package

Set the IFSR20bit in the IFSR2A register to 0 after reset and set bits PACR2 to PACR0 in the PACR register to 010_2.

22.1.3 Register Setting

Immediate values should be set in the registers containing write-only bits. When establishing a new value by modifying a previous value, write the previous value into RAM as well as the register. Change the contents of the RAM and then transfer the new value to the register.

22.2 Clock Generation Circuit

22.2.1 PLL Frequency Synthesizer

Stabilize supply voltage so that the standard of the power supply ripple is met.

Symbol	Parameter		Standard			Unit
			Min.	Typ.	Max.	
$f_{(ripple)}$	Power supply ripple allowable frequency(V_{CC})				10	kHz
$V_{p-p(ripple)}$	Power supply ripple allowabled amplitude voltage	(V_{CC}=5V)			0.5	V
		(V_{CC}=3V)			0.3	V
$V_{CC(\|DV/DT\|)}$	Power supply ripple rising/falling gradient	(V_{CC}=5V)			0.3	V/ms
		(V_{CC}=3V)			0.3	V/ms

$f_{(ripple)}$
Power supply ripple allowable frequency (V_{CC})
$V_{p-p(ripple)}$
Power supply ripple allowable amplitude voltage

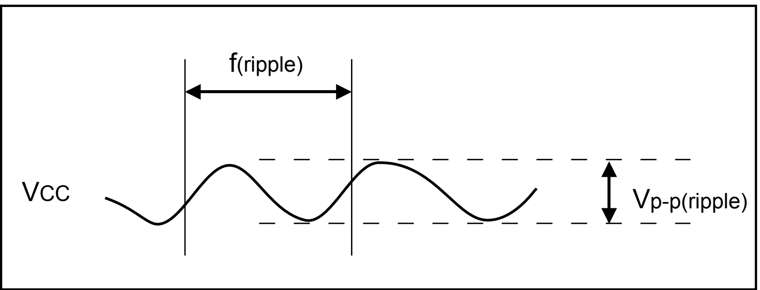


Figure 22.1 Voltage Fluctuation Timing

22.2.2 Power Control

1. When exiting stop mode by hardware reset, the device will startup using the on-chip oscillator.

2. Set the MR0 bit in the TAiMR register(i=0 to 4) to 0 (pulse is not output) to use the timer A to exit stop mode.

3. When entering wait mode, insert a JMP.B instruction before a WAIT instruction. Do not excute any instructions which can generate a write to RAM between the JMP.B and WAIT instructions. Disable the DMA transfers, if a DMA transfer may occur between the JMP.B and WAIT instructions. After the WAIT instruction, insert at least 4 NOP instructions. When entering wait mode, the instruction queue reads ahead the instructions following WAIT, and depending on timing, some of these may execute before the MCU enters wait mode.

Program example when entering wait mode

```
Program Example:        JMP.B     L1      ; Insert JMP.B instruction before WAIT instruction
                 L1:
                        FSET      I       ;
                        WAIT              ; Enter wait mode
                        NOP               ; More than 4 NOP instructions
                        NOP
                        NOP
                        NOP
```

4. When entering stop mode, insert a JMP.B instruction immediately after executing an instruction which sets the CM10 bit in the CM1 register to 1, and then insert at least 4 NOP instructions. When entering stop mode, the instruction queue reads ahead the instructions following the instruction which sets the CM10 bit to 1 (all clock stops), and, some of these may execute before the MCU enters stop mode or before the interrupt routine for returning from stop mode.

Program example when entering stop mode

```
Program Example:        FSET      I
                        BSET      CM10      ; Enter stop mode
                        JMP.B     L2        ; Insert JMP.B instruction
                 L1:
                        NOP                 ; More than 4 NOP instructions
                        NOP
                        NOP
                        NOP
```

5. Wait until the main clock oscillation stabilization time, before switching the CPU clock source to the main clock.
Similarly, wait until the sub clock oscillates stably before switching the CPU clock source to the sub clock.

6. Suggestions to reduce power consumption

(a) Ports

The processor retains the state of each I/O port even when it goes to wait mode or to stop mode. A current flows in active I/O ports. A dash current may flow through the input ports in high impedance state, if the input is floating. When entering wait mode or stop mode, set non-used ports to input and stabilize the potential.

(b) A/D converter

When A/D conversion is not performed, set the VCUT bit in ADiCON1 register to 0 (no Vref connection). When A/D conversion is performed, start the A/D conversion at least 1 µs or longer after setting the VCUT bit to 1 (Vref connection).

(c) Stopping peripheral functions

Use the CM0 register CM02 bit to stop the unnecessary peripheral functions during wait mode. However, because the peripheral function clock (f_{C32}) generated from the sub-clock does not stop, this measure is not conducive to reducing the power consumption of the chip. If low speed mode or low power dissipation mode is to be changed to wait mode, set the CM02 bit to 0 (do not peripheral function clock stopped when in wait mode), before changing wait mode.

(d) Switching the oscillation-driving capacity

Set the driving capacity to “LOW” when oscillation is stable.

22.3 Protection

Set the PRC2 bit to 1 (write enabled) and then write to any address, and the PRC2 bit will be cleared to 0 (write protected). The registers protected by the PRC2 bit should be changed in the next instruction after setting the PRC2 bit to 1. Make sure no interrupts or DMA transfers will occur between the instruction in which the PRC2 bit is set to 1 and the next instruction.

22.4 Interrupts

22.4.1 Reading Address 00000_{16}

Do not read the address 00000_{16} in a program. When a maskable interrupt request is accepted, the CPU reads interrupt information (interrupt number and interrupt request priority level) from the address 00000_{16} during the interrupt sequence. At this time, the IR bit for the accepted interrupt is cleared to 0.
If the address 00000_{16} is read in a program, the IR bit for the interrupt which has the highest priority among the enabled interrupts is cleared to 0. This causes a problem that the interrupt is canceled, or an unexpected interrupt request is generated.

22.4.2 Setting the SP

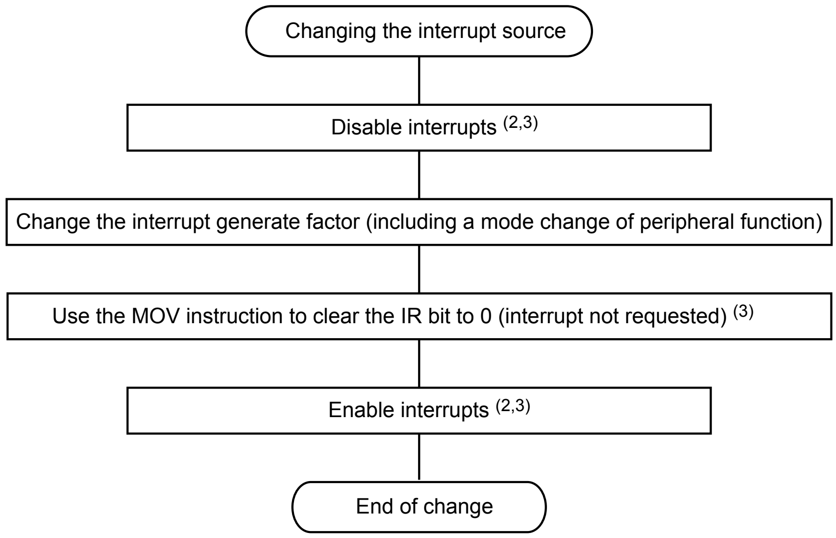
Set any value in the SP(USP, ISP) before accepting an interrupt. The SP(USP, ISP) is cleared to 0000_{16} after reset. Therefore, if an interrupt is accepted before setting any value in the SP(USP, ISP), the program may go out of control.

22.4.3 $\overline{\text{NMI}}$ Interrupt

1. The $\overline{\text{NMI}}$ interrupt is invalid after reset. The $\overline{\text{NMI}}$ interrupt becomes effective by setting the PM24 bit in the PM2 register to “1”. Set the PM24 bit to "1" when a high-level signal ("H") is applied to the $\overline{\text{NMI}}$ pin. If the PM24 bit is set to "1" when a low-level signal ("L") is applied, $\overline{\text{NMI}}$ interrupt is generated. Once $\overline{\text{NMI}}$ interrupt is enabled, it will not be disabled unless a reset is applied.
2. The input level of the $\overline{\text{NMI}}$ pin can be read by accessing the P8_5 bit in the P8 register.
3. When selecting $\overline{\text{NMI}}$ function, stop mode cannot be entered into while input on the $\overline{\text{NMI}}$ pin is low. This is because while input on the $\overline{\text{NMI}}$ pin is low the CM1 register’s CM10 bit is fixed to 0.
4. When selecting $\overline{\text{NMI}}$ function, do not go to wait mode while input on the $\overline{\text{NMI}}$ pin is low. This is because when input on the $\overline{\text{NMI}}$ pin goes low, the CPU stops but CPU clock remains active; therefore, the current consumption in the chip does not drop. In this case, normal condition is restored by an interrupt generated thereafter.
5. When selecting $\overline{\text{NMI}}$ function, the low and high level durations of the input signal to the $\overline{\text{NMI}}$ pin must each be 2 CPU clock cycles + 300 ns or more.
6. When using the $\overline{\text{NMI}}$ interrupt for exiting stop mode, set the NDDR register to FF_{16} (disable digital debounce filter) before entering stop mode.

22.4.4 Changing the Interrupt Generate Factor

If the interrupt generate factor is changed, the IR bit in the interrupt control register for the changed interrupt may inadvertently be set to 1 (interrupt requested). If you changed the interrupt generate factor for an interrupt that needs to be used, be sure to clear the IR bit for that interrupt to 0 (interrupt not requested).
“Changing the interrupt generate factor” referred to here means any act of changing the source, polarity or timing of the interrupt assigned to each software interrupt number. Therefore, if a mode change of any peripheral function involves changing the generate factor, polarity or timing of an interrupt, be sure to clear the IR bit for that interrupt to 0 (interrupt not requested) after making such changes. Refer to the description of each peripheral function for details about the interrupts from peripheral functions.
Figure 22.2 shows the procedure for changing the interrupt generate factor.



IR bit: A bit in the interrupt control register for the interrupt whose interrupt generate factor is to be changed

NOTES:
1. The above settings must be executed individually. Do not execute two or more settings simultaneously (using one instruction).
2. Use the I flag for the INTi interrupt (i = 0 to 5).
   For the interrupts from peripheral functions other than the INTi interrupt, turn off the peripheral function that is the source of the interrupt in order not to generate an interrupt request before changing the interrupt generate factor. In this case, if the maskable interrupts can all be disabled without causing a problem, use the I flag. Otherwise, use the corresponding bits ILVL2 to ILVL0 for the interrupt whose interrupt generate factor is to be changed.
3. Refer to **22.4.6 Rewrite the Interrupt Control Register** for details about the instructions to use and the notes to be taken for instruction execution.

Figure 22.2 Procedure for Changing the Interrupt Generate Factor

22.4.5 $\overline{\text{INT}}$ Interrupt

1. Either an “L” level of at least $t_{W(INH)}$ or an “H” level of at least $t_{W(INL)}$ width is necessary for the signal input to pins INT_0 through INT_5 regardless of the CPU operation clock.
2. If the POL bit in registers INT0IC to INT5IC or bits IFSR7 to IFSR0 in the IFSR register are changed, the IR bit may inadvertently set to 1 (interrupt requested). Be sure to clear the IR bit to 0 (interrupt not requested) after changing any of those register bits.
3. When using the INT_5 interrupt for exiting stop mode, set the P17DDR register to FF_{16} (disable digital debounce filter) before entering stop mode.

22.4.6 Rewrite the Interrupt Control Register

(1) The interrupt control register for any interrupt should be modified in places where no requests for that interrupt may occur. Otherwise, disable the interrupt before rewriting the interrupt control register.

(2) To rewrite the interrupt control register for any interrupt after disabling that interrupt, be careful with the instruction to be used.

Changing any bit other than the IR bit

If while executing an instruction, a request for an interrupt controlled by the register being modified occurs, the IR bit in the register may not be set to 1 (interrupt requested), with the result that the interrupt request is ignored. If such a situation presents a problem, use the instructions shown below to modify the register.

Usable instructions: AND, OR, BCLR, BSET

Changing the IR bit

Depending on the instruction used, the IR bit may not always be cleared to 0 (interrupt not requested). Therefore, be sure to use the MOV instruction to clear the IR bit.

(3) When using the I flag to disable an interrupt, refer to the sample program fragments shown below as you set the I flag. (Refer to (2) for details about rewrite the interrupt control registers in the sample program fragments.)

Examples 1 through 3 show how to prevent the I flag from being set to 1 (interrupts enabled) before the interrupt control register is rewrited, due to the internal bus and the instruction queue buffer.

Example 1: Using the NOP instruction to keep the program waiting until the interrupt control register is modified

```
INT_SWITCH1:
        FCLR    I               ; Disable interrupts
        AND.B   #00h, 0055h     ;Set the TA0IC register to 0016
        NOP                     ;
        NOP
        FSET    I               ; Enable interrupts
```

The number of NOP instruction is as follows.
PM20 = 1 (1 wait) : 2, PM20 = 0 (2 waits): 3

Example 2:Using the dummy read to keep the FSET instruction waiting

```
INT_SWITCH2:
        FCLR    I               ; Disable interrupts
        AND.B   #00h, 0055h     ; Set the TA0IC register to 0016
        MOV.W   MEM, R0         ; Dummy read
        FSET    I               ; Enable interrupts
```

Example 3:Using the POPC instruction to changing the I flag

```
INT_SWITCH3:
        PUSHC   FLG
        FCLR    I               ; Disable interrupts
        AND.B   #00h, 0055h     ; Set the TA0IC register to 0016
        POPC    FLG             ; Enable interrupts
```

22.4.7 Watchdog Timer Interrupt

Initialize the watchdog timer after the watchdog timer interrupt occurs.

22.5 DMAC

22.5.1 Write to DMAE Bit in DMiCON Register

When both of the conditions below are met, follow the steps below.

(a) Conditions

- The DMAE bit is set to 1 again while it remains set (DMAi is in an active state).
- A DMA request may occur simultaneously when the DMAE bit is being written.

(b) Procedure

(1) Write 1 to the DMAE bit and DMAS bit in DMiCON register simultaneously(1).

(2) Make sure that the DMAi is in an initial state(2) in a program.

If the DMAi is not in an initial state, the above steps should be repeated.

NOTES:

1. The DMAS bit remains unchanged even if 1 is written. However, if 0 is written to this bit, it is set to 0 (DMA not requested). In order to prevent the DMAS bit from being modified to 0, 1 should be written to the DMAS bit when 1 is written to the DMAE bit. In this way the state of the DMAS bit immediately before being written can be maintained.
   Similarly, when writing to the DMAE bit with a read-modify-write instruction, 1 should be written to the DMAS bit in order to maintain a DMA request which is generated during execution.

2. Read the TCRi register to verify whether the DMAi is in an initial state. If the read value is equal to a value which was written to the TCRi register before DMA transfer start, the DMAi is in an initial state. (If a DMA request occurs after writing to the DMAE bit, the value written to the TCRi register is 1.) If the read value is a value in the middle of transfer, the DMAi is not in an initial state.

22.6 Timers

22.6.1 Timer A

22.6.1.1 Timer A (Timer Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using the TAiMR (i = 0 to 4) register and the TAi register before setting the TAiS bit in the TABSR register to 1 (count starts).
   Always make sure the TAiMR register is modified while the TAiS bit remains 0 (count stops) regardless whether after reset or not.

2. While counting is in progress, the counter value can be read out at any time by reading the TAi register. However, if the TAi register is read at the same time the counter is reloaded, the read value is always $FFFF_{16}$. If the TAi register is read after setting a value in it, but before the counter starts counting, the read value is the one that has been set in the register.

3. If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the $TA1_{OUT}$, $TA2_{OUT}$ and $TA4_{OUT}$ pins go to a high-impedance state.

22.6.1.2 Timer A (Event Counter Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using the TAiMR (i = 0 to 4) register, the TAi register, the UDF register, bits TAZIE, TA0TGL, and TA0TGH in the ONSF register and the TRGSR register before setting the TAiS bit in the TABSR register to 1 (count starts).
   Always make sure bits TAZIE, TA0TGL, and TA0TGH in the TAiMR register, the UDF register, the ONSF register, and the TRGSR register are modified while the TAiS bit remains 0 (count stops) regardless whether after reset or not.

2. While counting is in progress, the counter value can be read out at any time by reading the TAi register. However, if the TAi register is read at the same time the counter is reloaded, the read value is always $FFFF_{16}$ when the timer counter underflows and 0000_{16} when the timer counter overflows. If the TAi register is read after setting a value in it, but before the counter starts counting, the read value is the one that has been set in the register.

3. If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the $TA1_{OUT}$, $TA2_{OUT}$ and $TA4_{OUT}$ pins go to a high-impedance state.

22.6.1.3 Timer A (One-shot Timer Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using the TAiMR (i = 0 to 4) register, the TAi register, bits TA0TGL and TA0TGH in the ONSF register and the TRGSR register before setting the TAiS bit in the TABSR register to 1 (count starts).
   Always make sure bits TA0TGL and TA0TGH in the TAiMR register, the ONSF register, and the TRGSR register are modified while the TAiS bit remains 0 (count stops) regardless whether after reset or not.

2. When setting TAiS bit to 0 (count stop), the followings occur:
   • A counter stops counting and a content of reload register is reloaded.
   • TAi_{OUT} pin outputs "L".
   • After one cycle of the CPU clock, the IR bit in TAiIC register is set to 1 (interrupt request).

3. Output in one-shot timer mode synchronizes with a count source internally generated. When the external trigger has been selected, a maximun delay of one cycle of the count source occurs between the trigger input to TAi_{IN} pin and output in one-shot timer mode.

4. The IR bit is set to 1 when timer operation mode is set with any of the following procedures:
   • Select one-shot timer mode after reset.
   • Change an operation mode from timer mode to one-shot timer mode.
   • Change an operation mode from event counter mode to one-shot timer mode.
   To use the timer Ai interrupt (the IR bit), set the IR bit to 0 after the changes listed above have been made.

5. When a trigger occurs while the timer is counting, the counter reloads the reload register value, and continues counting after a second trigger is generated and the counter is decremented once. To generate a trigger while counting, space more than one cycle of the timer count source from the first trigger and generate again.

6. When selecting the external trigger for the count start conditions in timer A one-shot timer mode, do generate an external trigger 300ns before the count value of timer A is set to 0000_{16}. The one-shot timer does not continue counting and may stop.

7. If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the $TA1_{OUT}$, $TA2_{OUT}$ and $TA4_{OUT}$ pins go to a high-impedance state.

22.6.1.4 Timer A (Pulse Width Modulation Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using bits TA0TGL and TA0TGH in the TAiMR (i = 0 to 4) register, the TAi register, the ONSF register and the TRGSR register before setting the TAiS bit in the TABSR register to 1 (count starts).
   Always make sure bits TA0TGL and TA0TGH in the TAiMR register, the ONSF register and the TRGSR register are modified while the TAiS bit remains 0 (count stops) regardless whether after reset or not.

2. The IR bit is set to 1 when setting a timer operation mode with any of the following procedures:
   • Select the PWM mode after reset.
   • Change an operation mode from timer mode to PWM mode.
   • Change an operation mode from event counter mode to PWM mode.
   To use the timer Ai interrupt (interrupt request bit), set the IR bit to 0 by program after the above listed changes have been made.

3. When setting TAiS register to 0 (count stop) during PWM pulse output, the following action occurs:
   • Stop counting.
   • When TAi_{OUT} pin is output “H”, output level is set to “L” and the IR bit is set to 1.
   • When TAi_{OUT} pin is output “L”, both output level and the IR bit remains unchanged.

4. If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the $TA1_{OUT}$, $TA2_{OUT}$ and $TA4_{OUT}$ pins go to a high-impedance state.

22.6.2 Timer B

22.6.2.1 Timer B (Timer Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using the TBiMR (i = 0 to 2) register and TBi register before setting the TBiS bit in the TABSR register to 1 (count starts).
   Always make sure the TBiMR register is modified while the TBiS bit remains 0 (count stops) regardless whether after reset or not.

2. The counter value can be read out at any time by reading the TBi register. However, if this register is read at the same time the counter is reloaded, the read value is always $FFFF_{16}$. If the TBi register is read after setting a value in it but before the counter starts counting, the read value is the one that has been set in the register.

22.6.2.2 Timer B (Event Counter Mode)

1. The timer remains idle after reset. Set the mode, count source, counter value, etc. using the TBiMR (i = 0 to 2) register and TBi register before setting the TBiS bit in the TABSR register to 1 (count starts).
   Always make sure the TBiMR register is modified while the TBiS bit remains 0 (count stops) regardless whether after reset or not.

2. The counter value can be read out at any time by reading the TBi register. However, if this register is read at the same time the counter is reloaded, the read value is always $FFFF_{16}$. If the TBi register is read after setting a value in it but before the counter starts counting, the read value is the one that has been set in the register.

22.6.2.3 Timer B (Pulse Period/pulse Width Measurement Mode)

1. The timer remains idle after reset. Set the mode, count source, etc. using the TBiMR (i = 0 to 2) register before setting the TBiS bit in the TABSR or the TBSR register to 1 (count starts).
   Always make sure the TBiMR register is modified while the TBiS bit remains 0 (count stops) regardless whether after reset or not. To clear the MR3 bit to 0 by writing to the TBiMR register while the TBiS bit is set to 1 (count starts), be sure to write the same value as previously written to bits TM0D0, TM0D1, MR0, MR1, TCK0, and TCK1 and a 0 to the MR2 bit.

2. The IR bit in TBiIC register (i=0 to 2) goes to 1 (interrupt request), when an effective edge of a measurement pulse is input or timer Bi is overflowed. The factor of interrupt request can be determined by use of the MR3 bit in TBiMR register within the interrupt routine.

3. If the source of interrupt cannot be identified by the MR3 bit such as when the measurement pulse input and a timer overflow occur at the same time, use another timer to count the number of times timer B has overflowed.

4. To set the MR3 bit to 0 (no overflow), set TBiMR register with setting the TBiS bit to 1 and counting the next count source after setting the MR3 bit to 1 (overflow).

5. Use the IR bit in TBiIC register to detect only overflows. Use the MR3 bit only to determine the interrupt factor within the interrupt routine.

6. When a count is started and the first effective edge is input, an undefined value is transferred to the reload register. At this time, timer Bi interrupt request is not generated.

7. A value of the counter is undefined at the beginning of a count. MR3 may be set to 1 and timer Bi interrupt request may be generated between a count start and an effective edge input.

8. For pulse width measurement, pulse widths are successively measured. Use program to check whether the measurement result is an “H” level width or an “L” level width.

22.6.3 Three-phase Motor Control Timer Function

When the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forced cutoff by SD pin input (high-impedance) enabled), the INV03 bit in the INVC0 register is set to 1 (three-phase motor control timer output enabled), and a low-level ("L") signal is applied to the $\overline{SD}$ pin while a three-phase PWM signal is output, the MCU is forced to cutoff and pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$ are placed in a high-impedance state and the INV03 bit is set to 0 (three-phase motor control timer output disabled).
To resume the three-phase PWM signal output from pins U, $\overline{U}$, V, $\overline{V}$, W, and $\overline{W}$, set the INV03 bit to 1 and the IVPCR1 bit to 0 (three-phase output forced cutoff disabled) after the $\overline{SD}$ pin level becomes "H". Then set the IVPCR1 bit to 1 (three-phase output forced cutoff enabled) in order to enable the three-phase output forced cutoff function by input to the SD pin again.
The INV03 bit cannot be set to 1 while an "L" signal is input to the $\overline{SD}$ pin. To set the INV03 bit to 1 after forcible cutoff, write 1 to the INV03 bit and read the bit to ensure that it is set to 1 by program. Then set the IVPCR1 bit to 1 after setting it to 0.

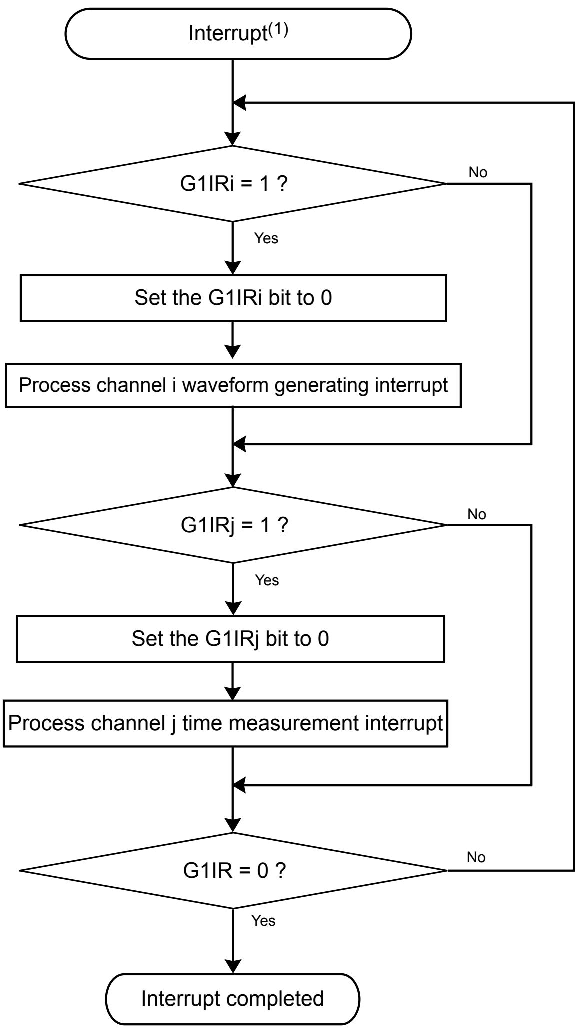
22.7 Timer S

22.7.1 Rewrite the G1IR Register

Bits in the G1IR register are not automatically set to 0 (no interrupt requested) even if a requested interrupt is acknowledged. Set each bit to 0 by program after the interrupt requests are verified.
The IC/OC interrupt is generated when any bit in the G1IR register is set to 1 (interrupt requested) after all the bits are set to 0. If conditions to generate an interrupt are met when the G1IR register holds the value other than 00_{16}, the IC/OC interrupt request will not be generated. In order to enable an IC/OC interrupt request again, clear the G1IR register to 00_{16}. Use the following instructions to set each bit in the G1IR register to 0.

Subject instructions: AND, BCL

Figure 22.3 shows an example of IC/OC interrupt i flow chart.



NOTE:
1. Example for the interrupt operation when using the channel i waveform generating interrupt and channel j time measurement interrupt.

Figure 22.3 IC/OC Interrupt i Flow Chart

22.7.2 Rewrite the ICOCiIC Register

When the interrupt request to the ICOCiIC register is generated during the instruction process, the IR bit may not be set to 1 (interrupt requested) and the interrupt request may not be acknowledged. At that time, when the bit in the G1IR register is held to 1 (interrupt requested), the following IC/OC interrupt request will not be generated. When changing the ICOCiIC register settiing, use the following instruction.

Subject instructions: AND, OR, BCLR, BSET

When initializing Timer S, change the ICOCiIC register setting with the request again after setting registers IOCiIC and G1IR to 00_{16}.

22.7.3 Waveform Generating Function

1. If the BTS bit in the G1BCR1 register is set to 0 (base timer is reset) when the waveform is generating and the base timer is stopped counting, the waveform output pin keeps the same output level. The output level will be changed when the base timer and the G1POj register match the setting value next time after the base timer starts counting again.
2. If the G1POCRj register is set when the waveform is generated, the same setting value of the IVL bit is applied to the waveform generating pin. Do not set the G1POCRj register when the waveform is generating.
3. When the RST1 bit in the G1BCR1 register is set to 1 (the base timer is reset by matching the G1PO0 register), the base timer is reset after two clock cycles of f_{BT1} when the base timer value matches the G1PO0 register value. A high-level ("H") signal is applied to the OUTC10 pin between the base timer value match to the base timer reset.

22.7.4 IC/OC Base Timer Interrupt

If the MCU is operated in the combination selected from **Table 22.1** for use when the RST4 bit in the G1BCR0 register is set to 1 (reset the base timer that matches the G1BTRR register) to reset the base timer, an IC/OC base timer interrupt request is generated twice.

Table 22.1 Uses of IT Bit in the G1BCR0 Register and G1BTRR Register

IT Bit in the G1BCR0 Register	G1BTRR Register
0 (bit 15 in the base timer overflows)	$07FFF_{16}$ to $0FFFE_{16}$
1 (bit 14 in the base timer overflows)	$03FFF_{16}$ to $0FFFE_{16}$ or $0BFFF_{16}$ to $0FFFE_{16}$

The second IC/OC base timer interrupt request is generated because the base timer overflow request is generated after one fBT1 clock cycle as soon as the base timer is reset.

One of the following conditions must be met in order not to generate the IC/OC base timer interrupt request twice:

1) When the RST4 bit is set to 1, set the G1BTRR register with a combination other than what is listed in **Table 22.1**.

2) Do not reset the base timer by matching the G1BTRR register. Reset the base timer by matching the G1P00 register. In other words, do not set the RST4 bit to 1 to reset the base timer. Set the RST1 bit in the G1BCR1 register to 1 (reset the base timer that matches the G1P00 register).

22.8 Serial I/O

22.8.1 Clock-Synchronous Serial I/O

22.8.1.1 Transmission/reception

1. With an external clock selected, and choosing the $\overline{\text{RTS}}$ function, the output level of the $\overline{\text{RTSi}}$ pin goes to “L” when the data-receivable status becomes ready, which informs the transmission side that the reception has become ready. The output level of the $\overline{\text{RTSi}}$ pin goes to “H” when reception starts. So if the $\overline{\text{RTSi}}$ pin is connected to the $\overline{\text{CTSi}}$ pin on the transmission side, the circuit can transmission and reception data with consistent timing. With the internal clock, the $\overline{\text{RTS}}$ function has no effect.

2. If a low-level signal is applied to the $\overline{\text{SD}}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{\text{SD}}$ pin enabled), the $P7_3/RTS_2/TxD1$(when the U1MAP bit in PACR register is 1) and CLK_2 pins go to a high-impedance state.

22.8.1.2 Transmission

When an external clock is selected, the conditions must be met while if the CKPOL bit in the UiC0 register is set to 0 (transmit data output at the falling edge and the receive data taken in at the rising edge of the transfer clock), the external clock is in the high state; if the CKPOL bit in the UiC0 register is set to 1 (transmit data output at the rising edge and the receive data taken in at the falling edge of the transfer clock), the external clock is in the low state.

- The TE bit in UiC1 register is set to 1 (transmission enabled)
- The TI bit in UiC1 register is set to 0 (data present in UiTB register)
- If $\overline{\text{CTS}}$ function is selected, input on the $\overline{\text{CTSi}}$ pin is set to “L”

22.8.1.3 Reception

1. In operating the clock-synchronous serial I/O, operating a transmitter generates a shift clock. Fix settings for transmission even when using the device only for reception. Dummy data is output to the outside from the TxDi pin when receiving data.

2. When an internal clock is selected, set the TE bit in the UiC1 register (i = 0 to 2) to 1 (transmission enabled) and write dummy data to the UiTB register, and the shift clock will thereby be generated. When an external clock is selected, set the TE bit in the UiC1 register (i = 0 to 2) to 1 and write dummy data to the UiTB register, and the shift clock will be generated when the external clock is fed to the CLKi input pin.

3. When successively receiving data, if all bits of the next receive data are prepared in the UARTi receive register while the RE bit in the UiC1 register (i = 0 to 2) is set to 1 (data present in the UiRB register), an overrun error occurs and the UiRB register OER bit is set to 1 (overrun error occurred). In this case, because the content of the UiRB register is undefined, a corrective measure must be taken by programs on the transmit and receive sides so that the valid data before the overrun error occurred will be retransmitted. Note that when an overrun error occurred, the SiRIC register IR bit does not change state.

4. To receive data in succession, set dummy data in the lower-order byte of the UiTB register every time reception is made.

5. When an external clock is selected, make sure the external clock is in high state if the CKPOL bit is set to 0, and in low state if the CKPOL bit is set to 1 before the following conditions are met:
   - The RE bit in the UiC1 register is set to 1 (reception enabled)
   - The TE bit in the UiC1 register is set to 1 (transmission enabled)
   - The TI bit in the UiC1 register= 0 (data present in the UiTB register)

22.8.2 UART Mode

22.8.2.1 Special Mode 1 (I^2C bus Mode)

When generating start, stop and restart conditions, set the STSPSEL bit in the U2SMR4 register to 0 and wait for more than half cycle of the transfer clock before setting each condition generate bit (STAREQ, RSTAREQ and STPREQ) from 0 to 1.

22.8.2.2 Special Mode 2

If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the RTS_2 and CLK_2 pins go to a high-impedance state.

22.8.2.3 Special Mode 4 (SIM Mode)

A transmit interrupt request is generated by setting the U2C1 register U2IRS bit to 1 (transmission complete) and U2ERE bit to 1 (error signal output) after reset. Therefore, when using SIM mode, be sure to clear the IR bit to 0 (no interrupt request) after setting these bits.

22.8.3 SI/O3, SI/O4

The SOUTi default value which is set to the SOUTi pin by the SMi7 bit approximately 10ns may be output when changing the SMi3 bit from 0 (I/O port) to 1 (SOUTi output and CLKfunction) while the SMi2 bit in the SiC (i=3 and 4) to 0 (SOUTi output) and the SMi6 bit is set to 1 (internal clock). And then the SOUTi pin is held high-impedance.

If the level which is output from the SOUTi pin is a problem when changing the SMi3 bit from 0 to 1, set the default value of the SOUTi pin by the SMi7 bit.

22.9 A/D Converter

1. Set registers ADCON0 (except bit 6), ADCON1, ADCON2 and ADTRGCON when A/D conversion is stopped (before a trigger occurs).

2. When the VCUT bit in ADCON1 register is changed from 0 (Vref not connected) to 1 (Vref connected), start A/D conversion after passing 1 µs or longer.

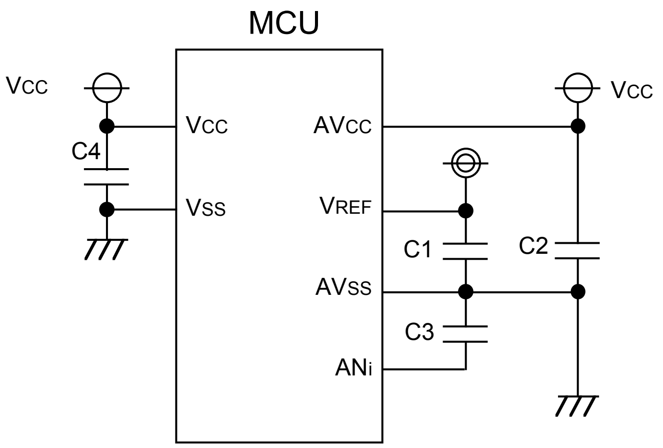
3. To prevent noise-induced device malfunction or latchup, as well as to reduce conversion errors, insert capacitors between the AVCC, VREF, and analog input pins (ANi, AN0i, AN2i(i=0 to 7), and AN3i(i=0 to 2)) each and the AVSS pin. Similarly, insert a capacitor between the VCC1 pin and the VSS pin. **Figure 22.4** is an example connection of each pin.

4. Make sure the port direction bits for those pins that are used as analog inputs are set to 0 (input mode). Also, if the TGR bit in the ADCON0 register is set to 1 (external trigger), make sure the port direction bit for the $\overline{\text{ADTRG}}$ pin is set to 0 (input mode).

5. When using key input interrupts, do not use any of the four AN4 to AN7 pins as analog inputs. (A key input interrupt request is generated when the A/D input voltage goes low.)

6. The φAD frequency must be 10 MHz or less. Without sample-and-hold function, limit the φAD frequency to 250kHz or more. With the sample and hold function, limit the φAD frequency to 1MHz or more.

7. When changing an A/D operation mode, select analog input pin again in bits CH2 to CH0 in the ADCON0 register and bits SCAN1 to SCAN0 in the ADCON1 register.



ANi: ANi, AN0i, AN2i (i=0 to 7), and AN3i (i=0 to 2)

NOTES:
1. C1 ≥ 0.47 µF, C2 ≥ 0.47 µF, C3 ≥ 100 pF, C4 ≥ 0.1 µF (reference)
2. Use thick and shortest possible wiring to connect capacitors.

Figure 22.4 Use of capacitors to reduce noise

8. If the CPU reads the ADi register (i = 0 to 7) at the same time the conversion result is stored in the ADi register after completion of A/D conversion, an incorrect value may be stored in the ADi register. This problem occurs when a divide-by-n clock derived from the main clock or a subclock is selected for CPU clock.
   - When operating in one-shot, single-sweep mode, simultaneous sample sweep mode, delayed trigger mode 0 or delayed trigger mode 1

     Check to see that A/D conversion is completed before reading the target ADi register. (Check the ADIC register's IR bit to see if A/D conversion is completed.)
   - When operating in repeat mode or repeat sweep mode 0 or 1

     Use the main clock for CPU clock directly without dividing it.

9. If A/D conversion is forcibly terminated while in progress by setting the ADST bit in the ADCON0 register to 0 (A/D conversion halted), the conversion result of the A/D converter is undefined. The contents of ADi registers irrelevant to A/D conversion may also become undefined. If while A/D conversion is underway the ADST bit is cleared to 0 in a program, ignore the values of all ADi registers.

10. When setting the ADST bit in the ADCON register to 0 and terminating forcefully by a program in single sweep conversion mode, A/D delayed trigger mode 0 and A/D delayed trigger mode 1 during A/D converting operation, the A/D interrupt request may be generated. If this causes a problem, set the ADST bit to 0 after an interrupt is disabled.

22.10 Multi-Master I^2C bus Interface

22.10.1 Writing to the S00 Register

When the start condition is not generated, the SCL pin may output the short low-signal ("L") by setting the S00 register. Set the register when the SCL pin outputs an "L" signal.

22.10.2 AL Flag

When the arbitration lost is generated and the AL flag in the S10 register is set to 1 (detected), the AL flag can be cleared to 0 (not detected) by writing a transmit data to the S00 register. The AL flag should be cleared at the timing when master geneates the start condition to start a new transfer.

22.11 CAN Module

22.11.1 Reading C0STR Register

The CAN module on the M16C/29 Group updates the status of the C0STR register in a certain period. When the CPU and the CAN module access to the C0STR register at the same time, the CPU has the access priority; the access from the CAN module is disabled. Consequently, when the updating period of the CAN module matches the access period from the CPU, the status of the CAN module cannot be updated. (See **Figure 22.5**)

Accordingly, be careful about the following points so that the access period from the CPU should not match the updating period of the CAN module:

(1) There should be a wait time of $3f_{CAN}$ or longer (see **Table 22.2**) before the CPU reads the C0STR register. (See **Figure 22.6**)

(2) When the CPU polls the C0STR register, the polling period must be $3f_{CAN}$ or longer. (See **Figure 22.7**)

Table 22.2 CAN Module Status Updating Period

$3f_{CAN}$ period = 3 × X_{IN} (Original oscillation period) × Division value of the CAN clock (CCLK)	
(Example 1) Condition X_{IN} 16 MHz CCLK: Divided by 1	$3f_{CAN}$ period = 3 × 62.5 ns × 1 = 187.5 ns
(Example 2) Condition X_{IN} 16 MHz CCLK: Divided by 2	$3f_{CAN}$ period = 3 × 62.5 ns × 2 = 375 ns
(Example 3) Condition X_{IN} 16 MHz CCLK: Divided by 4	$3f_{CAN}$ period = 3 × 62.5 ns × 4 = 750 ns
(Example 4) Condition X_{IN} 16 MHz CCLK: Divided by 8	$3f_{CAN}$ period = 3 × 62.5 ns × 8 = 1.5 µs
(Example 5) Condition X_{IN} 16 MHz CCLK: Divided by 16	$3f_{CAN}$ period = 3 × 62.5 ns × 16 = 3 µs

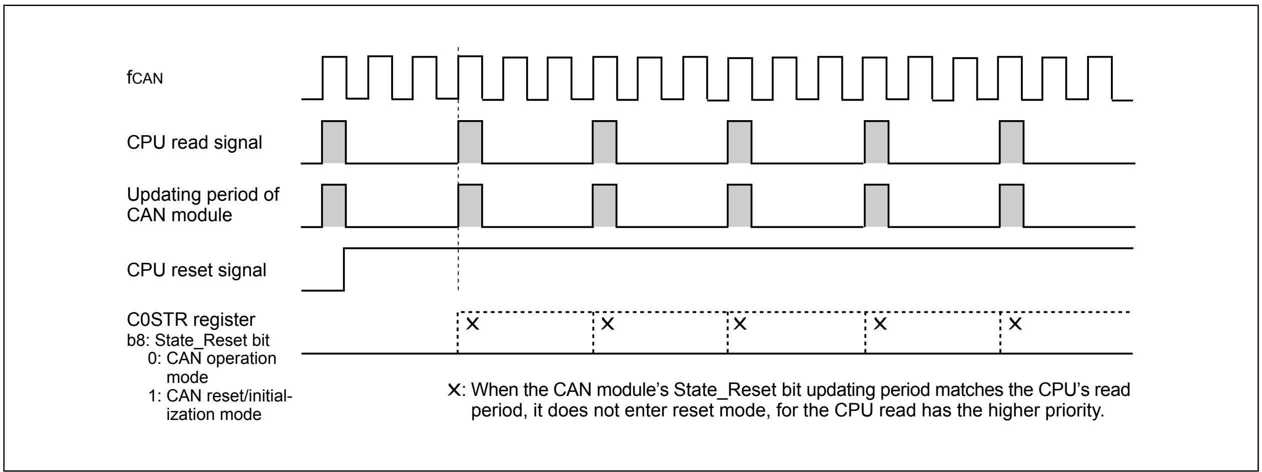


Figure 22.5 When Updating Period of CAN Module Matches Access Period from CPU

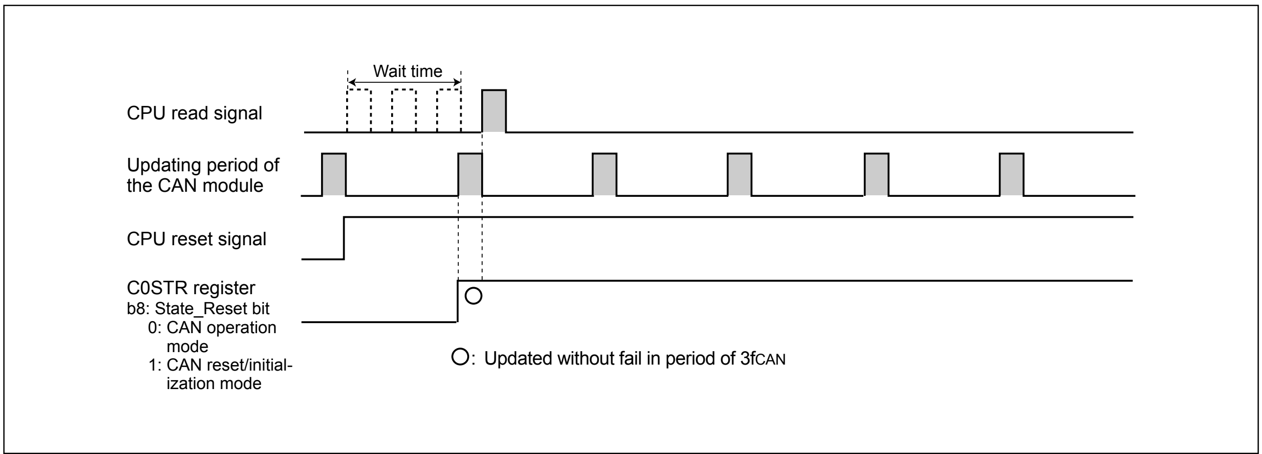


Figure 22.6 With a Wait Time of 3fCAN Before CPU Read

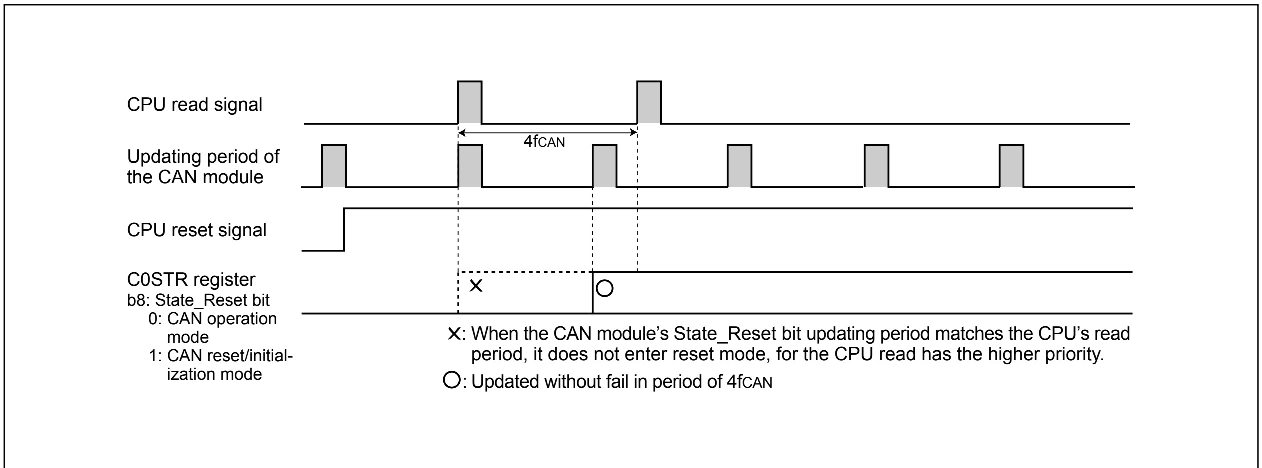
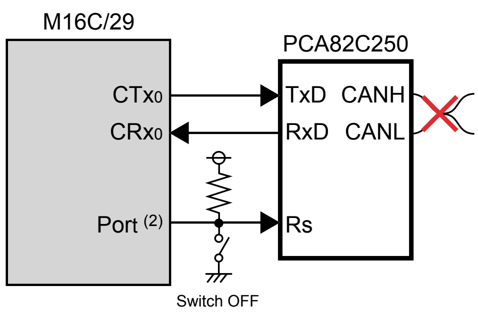
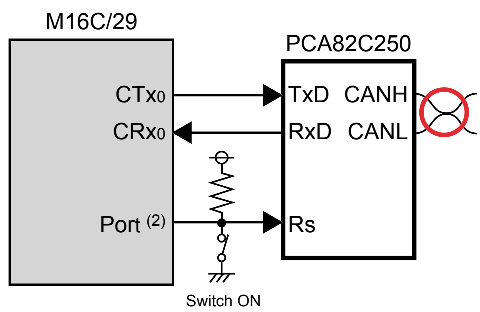


Figure 22.7 When Polling Period of CPU is 3fCAN or Longer

22.11.2 CAN Transceiver in Boot Mode

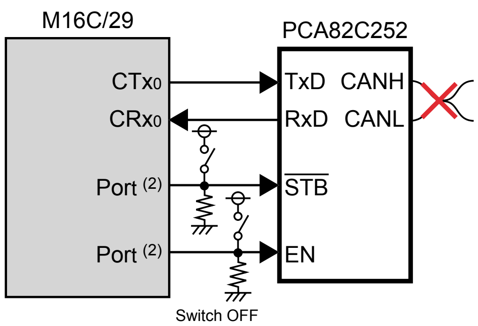
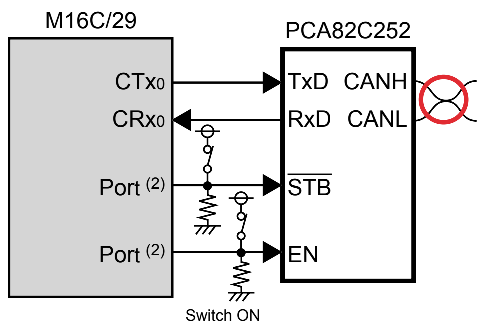
When programming the flash memory in boot mode via CAN bus, the operation mode of CAN transceiver should be set to “high-speed mode” or “normal operation mode”. If the operation mode is controlled by the MCU, CAN transceiver must be set the operation mode to “high-speed mode” or “normal operation mode” before programming the flash memory by changing the switch etc. **Tables 22.3 and 22.4** show pin connections of CAN transceiver.

Table 22.3 Pin Connections of CAN Transceiver (In case of PCA82C250: Philips product)

	Standby mode	High-speed mode
Rs pin (Note 1)	“H”	“L”
CAN communication	impossible	possible
Connection		

Note 1: The pin which controls the operation mode of CAN transceiver.
Note 2: Connect to enabled port to control CAN transceiver.

Table 22.4 Pin Connections of CAN Transceiver (In case of PCA82C252: Philips product)

	Sleep mode	Normal operation mode
$\overline{STB}$ pin (Note 1)	“L”	“H”
EN pin (Note 1)	“L”	“H”
CAN communication	impossible	possible
Connection		

Note 1: The pin which controls the operation mode of CAN transceiver.
Note 2: Connect to enabled port to control CAN transceiver.

22.12 Programmable I/O Ports

1. If a low-level signal is applied to the $\overline{SD}$ pin when the IVPCR1 bit in the TB2SC register is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the $P7_2$ to $P7_5$, $P8_0$ and $P8_1$ pins go to a high-impedance state.

2. The input threshold voltage of pins differs between programmable input/output ports and peripheral functions.
   Therefore, if any pin is shared by a programmable input/output port and a peripheral function and the input level at this pin is outside the range of recommended operating conditions V_{IH} and V_{IL} (neither "high" nor "low"), the input level may be determined differently depending on which side—the programmable input/output port or the peripheral function—is currently selected.

3. When the SM32 bit in the S3C register is set to 1, the $P3_2$ pin goes to high-impedance state. When the SM42 bit in the S4C register is set to 1, the $P9_6$ pin goes to high-imepdance state.

4. When the INV03 bit in the INVC0 register is 1(three-phase motor control timer output enabled), an "L" input on the $P8_5$ $\overline{/NMI}/\overline{SD}$ pin, has the following effect.

   •When the TB2SC register IVPCR1 bit is set to 1 (three-phase output forcible cutoff by input on $\overline{SD}$ pin enabled), the U/ $\overline{U}$/ V/ $\overline{V}$/ W/ $\overline{W}$ pins go to a high-impedance state.
   •When the TB2SC register IVPCR1 bit is set to 0 (three-phase output forcible cutoff by input on $\overline{SD}$ pin disabled), the U/ $\overline{U}$/ V/ $\overline{V}$/ W/ $\overline{W}$ pins go to a normal port.

   Therefore, the $P8_5$ pin can not be used as programmable I/O port when the INV03 bit is set to 1.
   When the $\overline{SD}$ function isn't used, set to 0 (Input) in $PD8_5$ and pullup to H in the $P8_5$ $\overline{/NMI}/\overline{SD}$ pin from outside.

22.13 Electric Characteristic Differences Between Mask ROM and Flash Memory Version

Flash memory version and mask ROM version may have different characteristics, operating margin, noise tolerated dose, noise width dose in electrical characteristics due to internal ROM, different layout pattern, etc. When switching to the mask ROM version, conduct equivalent tests as system evaluation tests conducted in the flash memory version.

22.14 Mask ROM Version

22.14.1 Internal ROM Area

In the masked ROM version, do not write to internal ROM area. Writing to the area may increase power consumption.

22.14.2 Reserved Bit

The b3 to b0 in addresses $0FFFFF_{16}$ are reserved bits. Set these bits to 1111_2.

22.15 Flash Memory Version

22.15.1 Functions to Inhibit Rewriting Flash Memory Rewrite

ID codes are stored in addresses $0FFFDF_{16}$, $0FFFE3_{16}$, $0FFFEB_{16}$, $0FFFEF_{16}$, $0FFFF3_{16}$, $0FFFF7_{16}$, and $0FFFFB_{16}$. If wrong data are written to theses addresses, the flash memory cannot be read or written in standard serial I/O mode.

The ROMCP register is mapped in address $0FFFFF_{16}$. If wrong data is written to this address, the flash memory cannot be read or written in parallel I/O mode.

In the flash memory version of MCU, these addresses are allocated to the vector addresses ("H") of fixed vectors. The b3 to b0 in address $0FFFFF_{16}$ are reserved bits. Set these bits to 1111_2.

22.15.2 Stop Mode

When the MCU enters stop mode, execute the instruction which sets the CM10 bit to 1 (stop mode) after setting the FMR01 bit to 0 (CPU rewrite mode disabled) and disabling the DMA transfer.

22.15.3 Wait Mode

When the MCU enters wait mode, excute the WAIT instruction after setting the FMR01 bit to 0 (CPU rewrite mode disabled).

22.15.4 Low PowerDissipation Mode, On-Chip Oscillator Low Power Dissipation Mode

If the CM05 bit is set to 1 (main clock stop), the following commands must <u>not</u> be executed.

- Program
- Block erase

22.15.5 Writing Command and Data

Write the command code and data at even addresses.

22.15.6 Program Command

Write $xx40_{16}$ in the first bus cycle and write data to the write address in the second bus cycle, and an auto program operation (data program and verify) will start. Make sure the address value specified in the first bus cycle is the same even address as the write address specified in the second bus cycle.

22.15.7 Operation Speed

When CPU clock source is main clock, before entering CPU rewrite mode (EW mode 0 or 1), select 10 MHz or less for BCLK using the CM06 bit in the CM0 register and bits CM17 to CM16 in the CM1 register. Also, when CPU clock is f_3(ROC) on-chip oscillator clock, before entering CPU rewrite mode (EW mode 0 or 1), set the ROCR3 to ROCR2 bits in the ROCR register to “divied by 4” or “divide by 8”.

On both cases, set the PM17 bit in the PM1 register to 1 (with wait state).

22.15.8 Instructions Inhibited Against Use

The following instructions cannot be used in EW mode 0 because the flash memory’s internal data is referenced: UND instruction, INTO instruction, JMPS instruction, JSRS instruction, and BRK instruction

22.15.9 Interrupts

EW Mode 0

- Any interrupt which has a vector in the variable vector table can be used providing that its vector is transferred into the RAM area.
- The $\overline{NMI}$ and watchdog timer interrupts can be used because the FMR0 register and FMR1 register are initialized when one of those interrupts occurs. The jump addresses for those interrupt service routines should be set in the fixed vector table.

  Because the rewrite operation is halted when a $\overline{NMI}$ or watchdog timer interrupt occurs, the rewrite program must be executed again after exiting the interrupt service routine.
- The address match interrupt cannot be used because the flash memory's internal data is referenced.

EW Mode 1

- Make sure that any interrupt which has a vector in the variable vector table or address match interrupt will not be accepted during the auto program period or auto erase period with erase-suspend function disabled.
- The $\overline{NMI}$ interrupt can be used because the FMR0 register and FMR1 register are initialized when this interrupt occurs. The jump address for the interrupt service routine should be set in the fixed vector table.

  Because the rewrite operation is halted when a $\overline{NMI}$ interrupt occurs, the rewrite program must be executed again after exiting the interrupt service routine.

22.15.10 How to Access

To set the FMR01, FMR02, FMR11 or FMR16 bit to 1, set the subject bit to 1 immediately after setting to 0. Do not generate an interrupt or a DMA transfer between the instruction to set the bit to 0 and the instruction to set the bit to 1. Set the bit when the PM24 bit is set to 1 ($\overline{NMI}$ funciton) and an high-level ("H") signal is applied to the $\overline{NMI}$ pin.

22.15.11 Writing in the User ROM Area

EW Mode 0

- If the power supply voltage drops while rewriting any block in which the rewrite control program is stored, a problem may occur that the rewrite control program is not correctly rewritten and, consequently, the flash memory becomes unable to be rewritten thereafter. In this case, standard serial I/O or parallel I/O mode should be used.

EW Mode 1

- Avoid rewriting any block in which the rewrite control program is stored.

22.15.12 DMA Transfer

In EW mode 1, make sure that no DMA transfers will occur while the FMR00 bit in the FMR0 register is set to 0(during the auto program or auto erase period).

22.15.13 Regarding Programming/Erasure Times and Execution Time

As the number of programming/erasure times increases, so does the execution time for software commands (Program, and Block Erase).

The software commands are aborted by hardware reset 1, brown-out detection reset (hardware reset 2), $\overline{NMI}$ interrupt, and watchdog timer interrupt. If a software command is aborted by such reset or interrupt, the affected block must be erased before reexecuting the aborted command.

22.15.14 Definition of Programming/Erasure Times

"Number of programs and erasure" refers to the number of erasure per block.
If the number of program and erasure is n (n=100 1,000 10,000) each block can be erased n times.
For example, if a 2K byte block A is erased after writing 1 word data 1024 times, each to a different address, this is counted as one program and erasure. However, data cannot be written to the same adrress more than once without erasing the block. (Rewrite prohibited)

22.15.15 Flash Memory Version Electrical Characteristics 10,000 E/W cycle products (Normal: U7, U9; T-ver./V-ver.: U7)

When Block A or B E/W cycles exceed 100, set the FMR17 bit in the FMR1 register to 1 (1 wait) to select one wait state per block access for products U7 and U9. When the FMR17 bit is set to 1, one wait state is inserted per access to Block A or B - regardless of the value of the PM17 bit. Wait state insertion during access to all other blocks, as well as to internal RAM, is controlled by the PM17 bit - regardless of the setting of the FMR17 bit.
To use the limited number of erasure efficiently, write to unused address within the block instead of rewite. Erase block only after all possible address are used. For example, an 8-word program can be written 128 times before erase becomes necessary.
Maintaining an equal number of erasure between Block A and B will also improve efficiency.
We recommend keeping track of the number of times erasure is used.

22.15.16 Boot Mode

An undefined value is sometimes output in the I/O port until the internal power supply becomes stable when "H" is applied to the CNVSS pin and "L" is applied to the $\overline{\text{RESET}}$ pin.
When setting the CNVSS pin to "H", the following procedure is required:

(1) Apply an "L" signal to the $\overline{\text{RESET}}$ pin and the CNVSS pin.
(2) Bring VCC to more than 2.7V, and wait at least 2 msec. (Internal power supply stable waiting time)
(3) Apply an "H" signal to the CNVSS pin.
(4) Apply an "H" signal to the $\overline{\text{RESET}}$ pin.

When the CNVSS pin is “H” and RESET pin is “L”, P67 pin is connected to the pull-up resister.

22.16 Noise

Connect a bypass capacitor (approximately 0.1µF) across the VCC and VSS pins using the shortest and thicker possible wiring. **Figure 22.8** shows the bypass capacitor connection.

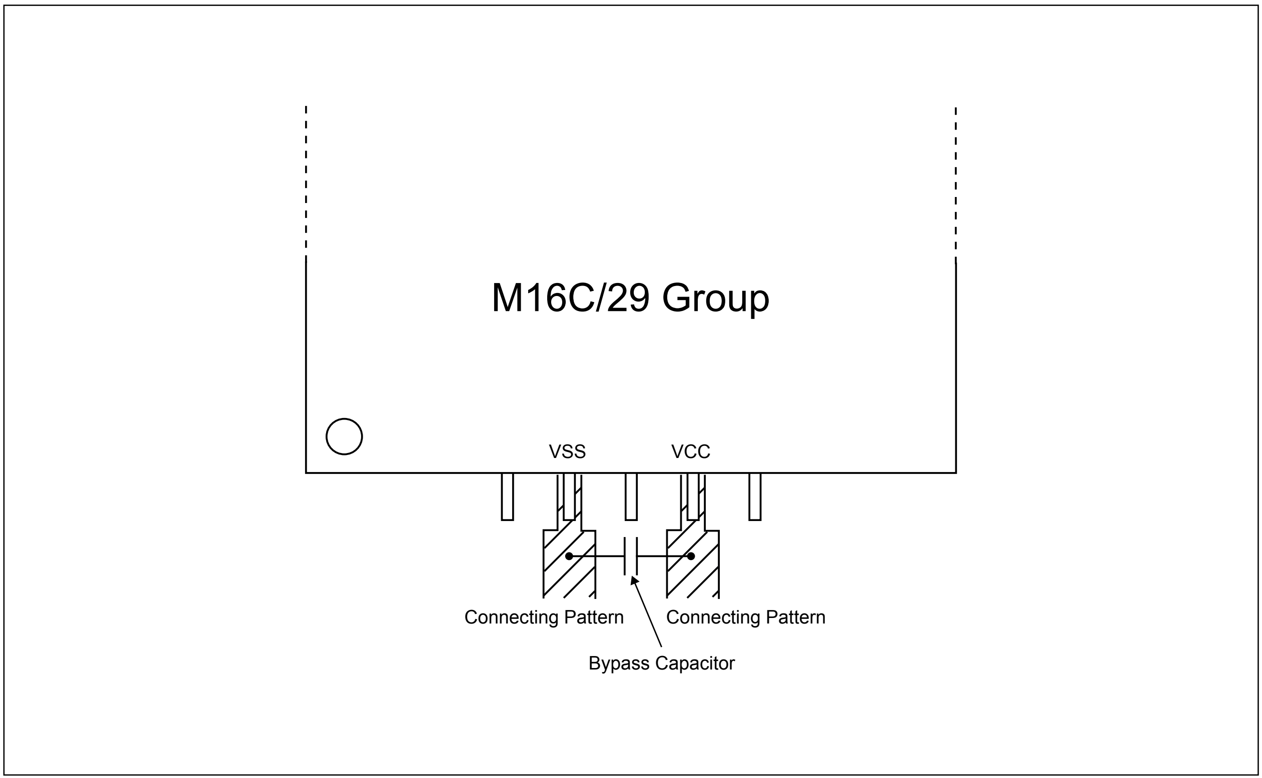


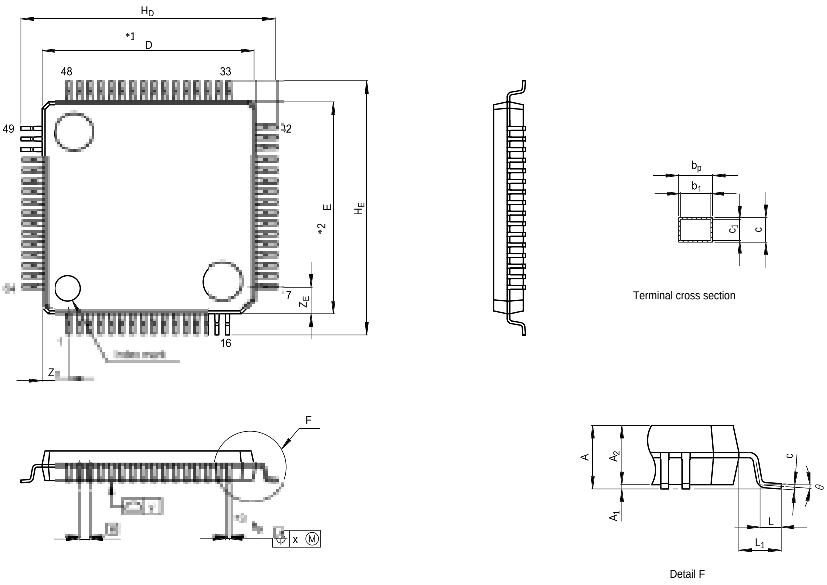
Figure 22.8 Bypass Capacitor Connection

22.17 Instruction for a Device Use

When handling a device, extra attention is necessary to prevent it from crashing during the electrostatic discharge period.

Appendix 1. Package Dimensions

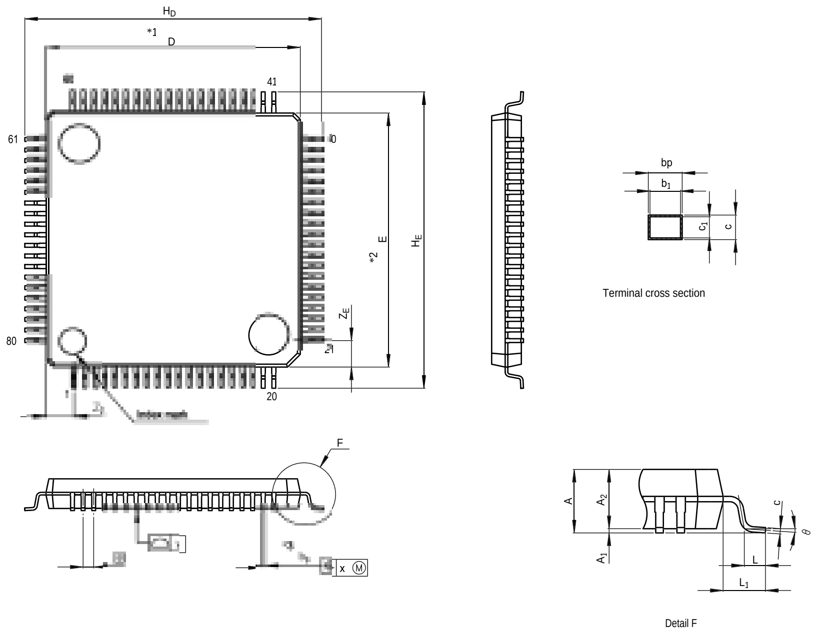
JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-LQFP64-10x10-0.50	PLQP0064KB-A	64P6Q-A / FP-64K / FP-64KV	0.3g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters Min	Nom	Max
D	9.9	10.0	10.1
E	9.9	10.0	10.1
A_2	—	1.4	—
H_D	11.8	12.0	12.2
H_E	11.8	12.0	12.2
A	—	—	1.7
A_1	0.05	0.1	0.15
b_p	0.15	0.20	0.25
b_1	—	0.18	—
c	0.09	0.145	0.20
c_1	—	0.125	—
θ	0°	—	8°
e	—	0.5	—
x	—	—	0.08
y	—	—	0.08
Z_D	—	1.25	—
Z_E	—	1.25	—
L	0.35	0.5	0.65
L_1	—	1.0	—

JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-LQFP80-12x12-0.50	PLQP0080KB-A	80P6Q-A	0.5g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters Min	Nom	Max
D	11.9	12.0	12.1
E	11.9	12.0	12.1
A_2	—	1.4	—
H_D	13.8	14.0	14.2
H_E	13.8	14.0	14.2
A	—	—	1.7
A_1	0	0.1	0.2
b_p	0.15	0.20	0.25
b_1	—	0.18	—
c	0.09	0.145	0.20
c_1	—	0.125	—
θ	0°	—	10°
e	—	0.5	—
x	—	—	0.08
y	—	—	0.08
Z_D	—	1.25	—
Z_E	—	1.25	—
L	0.3	0.5	0.7
L_1	—	1.0	—

Appendix 2. Functional Comparison

Appendix 2.1 Difference between M16C/28 Group and M16C/29 Group (Normal-ver.) (1)

Item	Description	M16C/28(Normal-ver.)	M16C/29(Normal-ver.)
Clock Generation Circuit	Clock output function (function of b1 to b0 bits in the CM0 register)	Not available (reserved bit)	Available (clock output function select bit)
Protection	Function of the PRC0 bit	Enable to set the CM0, CM1, CM2, POCR, PLC0 and PCLKR registers	Enable to set the CM0, CM1, CM2, POCR, PLC0, PCLKR and CCLKR registers
Interrupt	The IFSR20 bit setting in the IFSR2A register	Set to 1	Set to 0
	The b1 bit in the IFSR2A register	Not available (reseved bit)	Interrupt cause switching bit (0: A/D conversion, 1:key input)
	The b2 bit in the IFSR2A register	Not available (reseved bit)	Interrupt cause switching bit (0: CAN0 wake-up/ error)
	Interrupt cause in the Interrupt number 13	Key input interrupt	CAN0 error
	Interrupt cause in the Interrupt number 14	Key input interrupt	A/D, key input interrupt
Three-phase Motor Control Timer	Three-phase port switching function (function of 0358_{16})	Not available (reserved register)	Available (port function select register)
A/D	Number of A/D input pin	24 channels (excluding $AN3_0$ to $AN3_2$)	27 channels (including $AN3_0$ to $AN3_2$)
	Delayed trigger mode 0	Not available in the 1st chip version and chip version A	Available
	Delayed trigger mode 1	Not available in the 1st chip version and chip version A	Available
CAN module	compatible to 2.0B	Not available (all related registers are reserved registers)	Available (1 channel)
CRC Calculation	Available (compatible to CRC-CCITT and CRC-16 methods)	Not available (all related registers are reserved registers)	Available (1 circuit)
Pin Function	2 pins (80-pin/85-pin package), 62 pins (64-pin package)	$P9_3/AN2_4$	$P9_3/AN2_4$/CTX
	3 pins (80-pin/85-pin package), 64 pins (64-pin package)	$P9_2/TB2_{IN}$	$P9_2/AN3_2/TB2_{IN}$/CRX
	4 pins (80-pin/85-pin package), 1 pin (64-pin package)	$P9_1/TB1_{IN}$	$P9_1/AN3_1/TB1_{IN}$
	5 pins (80-pin/85-pin package), 2 pins (64-pin package)	$P9_0/TB0_{IN}$	$P9_0/AN3_0/TB0_{IN}/CLK_{OUT}$
Flash Memory	$P9_3$ in standard serial I/O mode	I (other than 128 Kbyte version) I/O (128 Kbyte version)	CTX output

I: Input O: Output I/O: Input and output

NOTE:
1. Since the M16C/28 group uses the common emulator used in the M16C/29 group, all the functions are available for M16C/28. When evaluating M16C/28 group, do not access to the SFR which is not built-in the M16C/28 gorup. Refere to hardware manual for details and electrical characteristics.

Appendix 2.2 Difference between M16C/28 and M16C/29 Group (T-ver./V-ver.) (1)

Item	Description	M16C/28(T-ver./V-ver.)	M16C/29(T-ver./V-ver.)
Protection	Function of the PRC0 bit	Enable to set the CM0, CM1, CM2, POCR, PLC0 and PCLKR registers	Enable to set the CM0, CM1, CM2, POCR, PLC0, PCLKR and CCLKR registers
Interrupt	The IFSR20 bit setting in the IFSR2A register	Set to 1	Set to 0
	The b1 bit in the IFSR2A register	Not available (reserved bit)	Interrupt cause switching bit (0: A/D conversion, 1:key input)
	The b2 bit in the IFSR2A register	Not available (reserved bit)	Interrupt cause switching bit (0: CAN0 wake-up/ error)
	Interrupt cause in the Interrupt number 13	Key input interrupt	CAN0 error
	Interrupt cause in the Interrupt number 14	Key input interrupt	A/D, key input interrupt
CAN module	compatible to 2.0B	Not available (all related registers are reserved registers)	Available (1 channel)
Pin Function	2 pins (80-pin/85-pin package), 62 pins (64-pin package)	$P9_3$/$AN2_4$	$P9_3$/$AN2_4$/CTX
	3 pins (80-pin/85-pin package), 64 pins (64-pin package)	$P9_2$/$TB2_{IN}$	$P9_2$/$AN3_2$/$TB2_{IN}$/CRX

I: Input O: Output I/O: Input and output

NOTE:
1. Since the M16C/28 group uses the common emulator used in the M16C/29 group, all the functions are available for M16C/28. When evaluating M16C/28 group, do not access to the SFR which is not built-in the M16C/28 gorup. Refere to hardware manual for details and electrical characteristics.

Register Index

K

N

O

P

R

S

T

U

V

W

Rev.	Date	Description	
		Page	Summary
0.70	Mar/ 29/Y04	1	“1. Overview” and “1.1. Application” are partly revised.
		2, 3	Table 1.2.1 and 1.2.2 are partly revised.
		8, 9	Figure 1.5.1 and 1.5.2 are partly revised.
		10	Table 1.6.1 is revised.
		22	Figure 4.8 is partly revised.
		28	Section “5.5 Voltage Detection Circuit” and Figure 5.5.2 are partly revised.
		30	Figure 5.5.3 is partly revised.
		31	Figure 5.5.4 is partly revised.
		32	Section “5.5.1 Voltage Detection Interrupt” and “5.5.1.1.1 Limitations of Stop Mode” are partly revised.
		36	Figure 7.1 is partly revised.
		37	Figure 7.2 is partly revised.
		38	Figure 7.3 is partly revised.
		39	Figure 7.5 is partly revised.
		40	Figure 7.6 is partly revised.
		41	“CCLKR register” of Figure 7.7 is partly revised.
		42	Section “7.1 Main clock” is partly revised.
		45	Figure 7.4.1 is partly revised.
		46	Section “7.5 CPU Clock and Peripheral Function Clock” and “7.5.2 Peripheral Function Clock” are partly revised.
		54	Section “7.7 System Clock Protective Function” and “7.8 Oscillation Stop and Re-oscillation Detect Function” are partly revised.
		57	Figure 8.1 is partly revised.
		64	Figure 9.3.1 is partly revised.
		65	IFSR2A registerin Figure 9.3.2 is partly revised.
		66	Section “9.3.2 IR Bit” is partly revised.
		67	Section “9.4 Interrupt Sequence” is partly revised.
		68	Section “9.4.1 Interrupt Response Time” and Figure9.4.1.1 are partly revised.
		73	Section “9.6 INT Interrupt” is partly revised.
		74	Section “9.9 CAN0 Wake-up Interrupt” is partly revised.
		94	“Divide ratio” of Table 12.1.1.1 is partly revised.
		102	“8-bit PWM” of Table 12.1.4.1 is partly revised.
		106	“Timer Bi register” in Figure 12.2.3 is partly revised.
		111	Section “12.2.4 A-D Trigger mode” and Table 12.2.4.1 are partly revised.
		112	Figure 12.2.4.2 is partly revised.
		115	Figure 12.3.2 is partly revised.
		117	“Timer B2 interrupt occurences fequency set counter” in Figure 12.3.4 is partly revised.
		119	Figure 12.3.6 is partly revised.

Rev.	Date	Description	
		Page	Summary
		122	“Figure 12.3.9 PFCR register and TPRC register” is deleted.
		125	Figure 12.3.1.2.1 and the section 12.3.1.2.4 are partly revised.
		126	Section “Three-phase/Port Output Switch Function” and “Figure 12.3.2.1 PFCR register and TPRC register” are added.
		166	“UART 2 special mode register 2” in Figure 14.1.8 is partly revised.
		167	“UART 2 special mode register 3” in Figure 14.1.9 is partly revised.
		210	Note 1 in Table 15.1.1.1 is deleted.
		213	Figure 15.4 is partly revised.
		214	Figure 15.5 is partly revised.
		219	Section “15.1.3 Single Sweep mode” is partly revised.
		221	Section “15.1.4 Repeat Sweep mode 0” is partly revised.
		223	Section “15.1.5 Repeat Sweep mode 1” is partly revised.
		225	Section “15.1.6 Simultaneous Sample Sweep Mode”, Table 15.1.6.1, and Figure 15.1.6.1 are partly revised.
		228	Section “15.1.7 Delayed Trigger Mode 0” and Table 15.1.7.1 are partly revised.
		229	Figure 15.1.7.1 is partly revised.
		230, 231	Figure 15.1.7.2 and 15.1.7.3 are partly revised.
		232	Figure 15.1.7.3 is deleted.
		235	Section “15.1.8 Delayed Trigger Mode 1” and Table 15.1.8.1 are partly revised.
		241	Figure 15.5.1 is partly revised.
		276 to 300	Chapter “17. CAN Module” is revised.
		301	Chapter “18. CRC Calculation Circuit” is partly revised.
		303	Figure 18.3 is partly revised.
		304	Chapter “19. Programmable I/O ports” is partly revised.
		305	Section “19.5 Pin Assignment Control Register” is partly revised.
		313	“Pull-up control register” in Figure 19.3.1 is partly revised.
		320	Table 20.4 and 20.5 and Note 6 and 10 are partly revised.
		321	Note 3 in Table 20.6 is added.
		342	Table 20.43 and 20.44 and Note 10 are partly revised.
		343	Note 3 in Table 20.45 is added.
		360 to 372	Section “20.3 V version” is deleted.
		373	Table 21.1 is partly revised.
		282	Section “•FMR01 Bit”, “•FMR02 Bit” and “•FMSTP Bit” are partly revised.
		383	Section “•FMR16 Bit”, “• FMR17 Bit” and “FMR41 Bit” are partly revised.
		384	Figure 21.5.1 is revised.
		387	Figure 21.5.1.3 is partly revised.
		392	Section “21.4.2 EW1 Mode” is partly revised.
			Section “21.6.4 How to Access” is partly revised.
			Section “21.7.5. Block Erase” is partly revised.

Rev.	Date	Description	
		Page	Summary
		399	Figure 21.9.1 is partly revised.
		400	Figure 21.9.2 is partly revised.
		403	Section “21.10.1 ROM Code Protect Function” is partly revised.
		404	Section “21.11.1 ROM Code Protect Function” is partly revised.
			Table 21.11.1 is revised.
		405	Figure 21.11.1 is revised.
		406	Figure 21.11.2 is revised.
		407	Figure 21.11.3 is revised.
0.71	April/15/Y04	B-1 to B-3	“Quick Reference to Page Classified by Address” are revised.
		B-4, B-5	“Quick Reference to Page Classified by Address” are partly revised.
		2,3	Table 1.2.1 and Table 1.2.2 is partly revised.
		6,7	Table 1.4.1 to 1.4.3 is partly revised.
		14	Not e2 in Figure 3.1 is added.
		15 to 20	Figure 4.1 to Figure 4.6 are revised.
		21, 22, 25	Figure 4.7, Figure 4.8 and Figure 4.11 are partly revised.
		29	Section “5.5 Voltage Detection Circuit” is partly revised.
		33	Figure 5.5.1.1.2.1 is partly revised.
		34	Figure 6.2 is partly revised.
		40	The PM2 register in Figure 7.6 is partly revised.
		64	Figure 9.3.1 is partly revised.
		65	The IFSR2A register in Figure 9.3.2 is partly revised.
		112	Figure 12.2.4.2 is partly revised.
		119	Figure 12.3.6 is partly revised.
		126	Section “12.3.2 Three-phase/Port Output Switch Function” is revised. Figure “12.3.2.1. Usage Example of Three-phse/Port output switch function” is added.
		130	Figure 13.2 is partly revised.
		134	Figure 13.6 is partly revised.
		137	Figure 13.10 is partly revised.
		162	“UARTi receive buffer register” in Figure 14.1.4 is partly revised.
		170	Table 14.1.1.2 is partly revised.
		177	Table 14.1.2.2 is partly revised.
		184	Figure 14.1.3.1 is partly revised.
		214	Figure 15.5 is partly revised.
		230, 231	Figure 15.1.7.2 and Figure 15.1.7.3 are partly revised.
		233	Figure 15.1.7.5 is partly revised.
		235	Section “15.1.8 Delayed Trigger Mode 1” is partly revised.
		236, 237	Figure 15.1.8.2 and Figure 15.1.8.3 are partly revised.
		240	Section “15.3 Sample and Hold” and Figure 15.5.1 are partly revised.
		244	Figure 16.2 is partly revised.
		321	Table 20.4 and Table 20.5 are partly revised.
		342	Table 20.43 and Table 20.44 are partly revised.

Rev.	Date	Description	
		Page	Summary
		360	Table 21.1 is partly revised.
		368	Section “21.4.2 EW1 Mode” is partly revised.
0.80	Sep/03/Y04	2,3	Table 1.2.1 and Table 1.2.2 are partly revised.
		6,7	Table 1.4.1 to Table 1.4.3 are partly revised.
		7	Figure 1.4.1 is partly revised.
		8,9	Figure 1.5.1 and Figure 1.5.2 are partly revised.
		21	Figure 4.7 is partly revised.
		24	Figure 4.10 is partly revised.
		26	Section “5.1.2 Hardware Reset 2” is partly revised.
		29 to 34	Section “5.5 Voltage Detection Circuit” is revised.
		80	Section “10.2 Cold start / Warm start” is added.
		322	Table 20.2 is partly revised.
		323	Table 20.3 is partly revised.
		325	Table 20.6 and Table 20.7 are partly revised.
		327	Table 20.9 is partly revised.
		331	Title of Table 20.23 is partly revised.
		335	Table 20.25 is partly revised.
		339	Title of Table 20.39 is partly revised.
		343	Table 20.41 is partly revised.
		344	Table 20.42 is partly revised.
		346	“Low Voltage Detection Circuit Electrical Characteristics” is deleted.
			Talbe 20.45 is partly revised.
		348	Table 20.47 is partly revised.
		352	Title of Table 20.61 is partly revised.
		356	Talbe 20.63 is partly revised.
		360	Title of Table 20.77 is partly revised.
		398	64P6Q-A package is revised.
1.00	Nov/01/Y04	All pages	Words standardized (on-chip oscillator, A/D)
		2, 3	Table1.2.1 and Table 1.2.2 are partly revised.
		8, 9	Table 1.4.4 to 1.4.6 and figure1.4.2 to 1.4.6 are added.
		28	“5.1.2 Hardware Reset 2” is partly revised.
		29	“5.4 Oscillation Stop Detection Reset” is partly revised.
		38	Table 7.1 is partly revised.
		41	Note 6 in Figure 7.3 is partly revised. b7 to b4 bit in Figure 7.4 is revised.
		42	Figure 7.5 is partly revised.
		43	“PCLKR register” in Figure 7.6 is partly revised.
		50	“7.6.1 Normal Operation Mode” is partly revised.
		51	Note 1 in Table 7.6.1.1 is partly revised.
		57	“7.8 Oscillation Stop and Re-oscillation Detect Function” is partly revised.

Rev.	Date	Description: Page	Description: Summary
		66	“9.3 Interrupt Control” is partly revised.
		76	“9.6 $\overline{\text{INT}}$ Interrupt” and “9.7 $\overline{\text{NMI}}$ Interrupt” are partly revised.
		77	“9.8 Key Input Interrupt” and “9.9 CAN0 Wake-up Interrupt” are partly revised.
		80	“10. Watchdog Timer” is partly revised.
		80, 81	“10.1 Count source protective mode” is partly revised.
		81	Note 2 in Figure 10.2 is revised.
		118	Figure 12.3.1 is partly revised.
		121	“Three-phase output buffer register” in Figure 12.3.4 is partly revised.
		133 to 138	Figure 13.1 to 13.6 are partly revised.
		141	“Function enable register” in Figure 13.9 is partly revised.
		150	Table 13.4.1 is partly revised.
		161	“13.6 I/O Port Function Select” is partly revised.
		198	Figure 14.1.4.1 is partly revised.
		209	Figure 14.2.1 is partly revised.
		210	Figure 14.2.2 is partly revised.
		214	“Integral Nonlinearity Error” in Table 15.1 is partly revised.
		253,254	Figure 16.6 and Figure 16.7 are partly revised.
		261	“16.5.4 Bit 3: Arbitration lost detection flag” is partly revised.
		266	“16.6.5 I2C system clock select bits” and Talbe 16.6 are partly revised.
		275	“9)” in “16.13.2 Example of Slave Receive” is revised.
		296	“17.3 Configuration of the CAN Module System Clock” is partly revised.
		306	“18.1 CRC snoop” is partly revised.
		337	Table 20.25 is partly revised.
		368	“21.1 Flash Memory Performance” is partly revised.
		367,368	“21.2 Memory Map” is partly revised.
		372	“21.4 CPU Rewrite Mode” is partly revised.
		373	“21.4.1 EW0 Mode” and “21.4.2 EW1 Mode” are partly revised.
		374	“FMR01 Bit” is partly revised.
		375	“FMR17 Bit” is partly revised.
		383	“21.7.4 Program Command (40_{16})” is partly revised.
		390	Table 21.9.1 and Note 2 are partly revised.
		391,392	Figure 21.9.1 and Figure 21.9.2 are partly revised.
		393,394	Figure 21.9.2.1 and Figure 21.9.2.2 are partly revised.
		396	Table 21.11.1 and Note 1 are partly revised.
		397,398	Figure 21.11.1 and Figure 21.11.2 are partly revised.
		399	Figure 21.11.3 is partly revised.
1.10	10/10/06	All Pages	Package code changed: 80P6Q-A to PLQP0080KB-A, 64P6Q-A to PLQP0064KB-A Words standardized: Low voltage detection, CPU clock, MCU, SDA_2, SCL_2

Rev.	Date	Page	Summary
			Overview
		2	• **Table 1.1 and 1.2 Performance Outline** Voltage detection circuit are modified, note 3 is modified
		4 - 5	• **Figure 1.1 and 1.2 Block Diagrams** are updated
		6 - 7	• **Table 1.3 to 1.5 Product Lists** are updated
		8	• **Figure 1.3 Produt Numbering System** is modified
		9	• **Tables 1.6 to 1.8 Product Code** B3, B7, D3, D5, D7, D9 are deleted
			• **Tables 1.9 to 1.11 Product Code** Mask ROM versions are newly added
		13 - 17	• **Table 1.9 and 1.10 Pin Characteristics for 80-, and 64-pin Packages** are added
		18	• **Table 1.11 Pin Description** Tables are modified
			Memory
		23	• Figure 3.1 Memory Map 48Kbyte memory size is deleted
			Special Function Register
		24 - 34	• **Table 4.1 to 4.11 SFR Information** values after reset
		24	• **Table 4.1 SFR Information(1)** Note 3 is deleted
			Reset
		35	• **5.1.2 Hardware Reset 2** Note is modified, description is modified
		38	• **5.5 Voltage Dection Circuit** modified
			• **Figure 5.4 Voltage Detection Circuit Block** modified, WDC5 bit circuit deleted
			Processor Mode
		44	• **Figure 6.1 PM1 Register** Note 2 information partially added
		45	• **Figure 6.2 PM2 Register** added
		46	• **Figure 6.3 Bus Block Diagram and Table 6.1 Accessible Area and Bus Cycle** added
			Clock Generation Circuit
		47	• **Table 7.1 Clock Generation Circuit Specifications** Oscillation stop, restart function modified
		48	• **Figure 7.1 Clock Generation Circuit** Upper portion of figure is modified
		50	• **Figure 7.4 ROCR Register** Bit conents are modified
		52	• **Figure 7.6 PCLKR Register and PM2 Register** Note 2 is modified
		54	• **Figure 7.8 Examples of Main Clock Connection Circuit** is modified
		55	• **Figure 7.9 Examples of Sub Clock Connection Circuit** is modified
			• **7.5.2 Peripheral Function Clock (f_1, f_2, f_8, f_{32}, f_{1SIO}, f_{2SIO}, f_{8SIO}, f_{32SIO}, f_{AD}, fc_{32}, f_{CAN0})** revised
		59	• **7.6.1 Normal Operation Mode** Information is modified
		60	• **Table 7.4 Setting Clock Related Bit and Modes** Multi-master I2C bus interrupt and Timer S interrupt added
		61	• **Table 7.5 Pin Status in Wait Mode** newly added
			• **Table 7.6 Interrupts to Exit Wait Mode** modified

Rev.	Date	Description: Page	Description: Summary
		63	• **Figure 7.11 State Transition to Stop Mode and Wait Mode** modified, Note 7 is added
		64	• **Figure 7.12 State Transition in Normal Mode** modified, note 5 deleted, note 6 and 7 are simplified
		65	• **Table 7.7 Allowed Transition and Setting** note 2 partially modified, table con tents are partially modified
		68	• **Figure 7.13 Procedure to Switch Clock Source From On-chip Oscillator Clock to Main Clock** is modified
			Interrupt
		70	• Note is newly added
		73	• **Table 9.1 Fixed Vector Tables** Note 2 is added
			Watchdog Timer
		89	• Additional information of the WDTS register is inserted
		90	• **Figure 10.1 Watchdog Timer Block Diagram** modified
			• **Figure 10.2 WDC Register and WDTS Register** All notes are deleted
		-	• **10.2 Cold Start/Warm Start** Section is deleted
			DMAC
		96	• Note is added
			Timer
		105	• **Figure 12.6 TRGSR Register** Note 2 added
		117	• **12.2 Timer B** Description of A/D trigger mode modified
			• **Figure 12.15 Timer B Block Diagram** "A/D trigger mode" is added
		123	• **12.2.4 A/D Trigger Mode** Description modified
		129	• **Figure 12.28 IDB0 Register, IDB1 Register, DTT Register, and ICTB2 Register** Information of bit 7 and 6 modified
		131	• **Figure 12.30 TB2SC Register** Note 4 added, contents modified
		133	• **Figure 12.32 TA1MR Register, TA2MR Register, TA4MR Register** MR0 bit is modified
		134	• **Figure 12.33 Triangular Wave Modulation Operation** Description modified
		135	• **Figure 12.34 Sawtooth Wave Modulation Operation** Description modified
		139	• **Figure 12.38 TPRC Register** Bit map is modified
			Timer S
		142	• **Figure 13.2 G1BT and G1BCR0 Registers** Function of G1BT register modified, note 3 is added, function of bits 5 to 3 modified, description patially modified
		143	• **Figure 13.3 G1BCR1 Register** Note 1 is partially added
		146	• **Figure 13.6 G1TM0 to G1TM7 Registers** Note 3 and 4 are added
		151-166	• **Table 13.2, 13.5, 13,8, 13.9 and 13.10** Output wave form and Selectable function are modified
		155	• **Figure 13.15 Base Timer Reset Operation by Base Timer Reset Register** Base timer overflow request line is added, base timer interrupt line is modified,

Rev.	Date	Page	Summary
			note 1 is added
		160	• **Figure 13.21 Prescaler Function and Gate Function** Note 1 modified
		166	• **Table 13.10 SR Waveform Output Mode Specifications** Specification modified
		167	• **Figure 13.24 Set/Reset Waveform Output Mode** Description for (1) Free-running operation modified, register names modified
		168	• **Table 13.11 Pin Setting for Time Measurement and Waveform Generating Functions** Description of port direction modified
			Serial I/O
		170	• Note is modified
		171	• **Figure 14.1 Block Diagram of UARTi (i = 0 to 2)** PLL clock is added to the upper portion of diagram
		174	• **Figure 14.4 U0TB to U2TB, U0RB to U2RB, U0BRG to U2BRG Registers** Note 2 is modified, note 3 is newly added
		175	• **Figure 14.5 U0MR Register, U1MR Register** Bit map is modified
		176	• **Figure 14.6 U0C0 Register** Note 3 modified, Note 4 to 7 are added
			• **Figure 14.6 U2C0 Register** Note 2 is added
		177	• **Figure 14.7 PACR Register** added
		180	• **Table 14.1 Clock Synchronous Serial I/O Mode Specifications** Select function modified, note 2 modified
		182	• **Table 14.3 Pin Functions** Note 1 added
			• **Table 14.4 $P6_4$ Pin Functions** Note 1 added
		183	• **Figure 14.10 Typical transmit/receive timings in clock synchronous serial I/O mode** Example of receive timing: figure modified
		184	• **14.1.1.1 Counter Measre for Communication Error Occurs** newly added
		185	• **14.1.1.2 CLK Polarity Select Function** Newly added
		186	• **Figure 14.14 Transfer Clock Output From Multiple Pins** Note 2 added
		187	• **14.1.1.7 $\overline{CTS}$/$\overline{RTS}$ separate function (UART0)** modified
			• **Figure 14.15 CTS/RTS Separate Function Usage** Note 1 added
		188	• **Table 14.5 UART Mode Specifications** Select function modified, note 1 modified
		190	• **Table 14.7 I/O Pin Functions in UART Mode** Note 1 added
			• **Table 14.8 $P6_4$ Pin Functions in UART Mode** Note 2 added
		192	• **Figure 14.17 Receive Operation** $\overline{RTSi}$ line is modified
			• **14.1.2.1 Bit Rates** newly added
			• **Table 14.9 Example of Bit Rates and Settings** newly added
		193	• **14.1.2.2 Counter Measure for Communication Error** newly added
		195	• **14.1.2.6 CTS/RTS Separate Function (UART0)** $P7_0$ pin is added
			• **Figure 14.21 CTS/RTS Separate Function** Note 1 added
		196	• **Table 14.10 I^2C mode Specifications** Note 2 modified

Rev.	Date	Page	Summary
		214	• **Figure 14.31 Transmit and Received Timing in SIM Mode** partially modified
		217	• **14.2 SI/O3 and SI/O4** Note added
		218	• **Figure 14.36 S3C and S4C Registers** Note 5 is added
			• **Figure 14.36 S3BRG and S4BRG Registers** Note 3 is added
		220	• **Figure 14.38 Polarity of Transfer Clock** figure modified
		221	• **14.2.3 Functions for Setting an SOUTi Initial Value** Description modified
			A/D Converter
		222	• Note added
			• **Table 15.1 A/D Converter Performance** Integral Nonlinearity Error modified
		224	• **Figure 15.2 ADCON2 Registers** b2-b1 function modified
		227	• **Figure 15.5 TB2SC Register** Reserved bit map modified
		229	• **Figure 15.7 ADCON0 to ADCON2 Registers in One-shot Mode** ADCON2 register: b2-b1 function modified
		231	• **Figure 15.9 ADCON0 to ADCON2 Registers in Repeat Mode** ADCON2 register: b2-b1 function modified
		233	• **Figure 15.11 ADCON0 to ADCON2 Registers in Single Sweep Mode** ADCON2 register: b2-b1 function modified
		235	• **Figure 15.13 ADCON0 to ADCON2 Registers in Repeat Sweep Mode 0** ADCON2 register: b2-b1 function modified
		237	• **Figure 15.15 ADCON0 to ADCON2 Registers in Repeat Sweep Mode 1** ADCON2 register: b2-b1 function modified
		239	• **Figure 15.17 ADCON0 to ADCON2 Registers in Simultaneous Sample Sweep Mode** ADCON2 register: b2-b1 function modified
		241	• **Table 15.10 Delayed Trigger Mode 1 Specifications** Note 1 is modified
		245	• **Figure 15.22 ADCON0 to ADCON2 Registers in Delayed Trigger Mode 0** ADCON2 register: b2-b1 function modified
		251	• **Figure 15.27 ADCON0 to ADCON2 Registers in Delayed Trigger Mode 1** ADCON2 register: b2-b1 function modified
		254	• **15.5 Analog Input Pin and External Sensor Equivalent Circuit Example** is deleted
			• **15.5 Output Impedance of Sensor under A/D Conversion** is added
			• **Figure 15.29 Analog Input Pin and External Sensor Equivalent Circuit** Note 1 is added
		-	• **Precaution of Using A/D Converter** deleted
			Multi-master I^{2}C bus INTERFACE
		255	• **Table 16.1 Multi-master I^{2}C bus Interface Functions** I/O pin added
		256	• **Figure 16.1 Block Diagram of Multi-master I^{2}C bus Interface** Bit name and register name are modified
		257	• **Figure 16.2 S0D0 Register** Bit map is modified

Rev.	Date	Page	Summary
		258	• **Figure 16.3 S00 Register** Note is modified
		259	• **Figure 16.4 S1D0 Register** Reserved bit map modified
		260	• **Figure 16.5 S10 Register** b7-b6 modified
		262	• **Figure 16.7 S4D0 Register** Bit reserved map is modified
		269	• **16.5.1 Bit 0: Last Receive Bit (LRB)** modified
			• **16.5.2 Bit 1: General call detection flag (ADR0)** modified, note 1 modified
			• **16.5.3 Bit 2: Slave address comparison flag (AAS)** modified
		270	• **16.5.5 Bit 4: I^2C Bus Interface Interrupt Request Bit (PIN)** modified
			• **16.5.6 Bit 5: Bus Busy Flag (BB)** Bit names are modified
		271	• **16.5.8 Bit 7: Communication Mode Select bit (MST)** modified
		276	• **16.7.1 Bit0: Time-Out Detection Function Enable Bit (TOE)** is modified
			• **16.7.5 Bit7: STOP Condition Detection Interrupt Request Bit (SCPIN)** is modified
		279	• **16.11 Stop Condition Generation Method** Description added
		282	• **16.13 Address Data Communication** modified
			CAN Module
		292	• **Figure 17.6 C0MCTLj Register** RspLock bit’s name changed, note 2 revised
		293	• **Figure 17.7 C0CTLR Register** Note 4 added, functions partially modified
		294	• **Figure 17.8 C0STR Register** Note 1 deleted, functions partially modified
		298	• **Figure 17.13 C0RECR Register** Note 2 deleted, note 1 partially modified
			• **Figure 17.14 C0TECR Register** Note 1 modified, note is relocated
		299	• **Figure 17.15 C0TSR Register** Note 1 modified
		300	• **Figure 17.17 Transition Between Operational Modes** Partially modified
		301	• **17.2.3 CAN Sleep Mode** Partially deleted
		304	• **Table 17.2 Example of Bit-Rate** 24-MHz is deleted
		308	• **17.8 Time Stamp Counter and Time Stamp Function** Partially deleted
		310	• **Figure 17.25 Timing of Receive Data Frame Sequence** IF to IFS
		311	• **Figure 17.26 Timing of Transmit Sequence** IF to IFS
			CRC Calculation Circuit
		313	• **18.1 CRC Snoop** Description partially added
			Programmable I/O Ports
		316	• Note added
			• **19.3 Pull-up Control Register 0 to 2** Description partially added
		317	• **19.6 Digital Debounce Function** Filter width formula modified
		318-321	• **Figure 19.1 I/O Ports (1) to Figure 19.4 I/O Ports (4)** are modified
		326	• **Figure 19.10 PACR Register** Note 1 is modified
		327	• **Figure 19.11 NDDR and P17DDR Register** Functions modified, notes are added
		328	• **Figure 19.12 Functioning of Digital Debounce Filter** modified, procedure note modified

Rev.	Date	Page	Summary
		329	• **Table 19.1 Unassigned Pin Handling in Single-chip Mode** Note 5 added
			Flash Memory Version
		330	• **20.1 Flash Memory Performance** Description partially deleted
			• **Table 20.14 Flash Memory Version Specifications** Note 3 added
		331	• **20.1.1 Boot Mode** added
		332	• **20.2 Memory Map** Description is modified
		335	• **20.3.1 ROM Code Protect Function** Description is modified
		336	• **Figure 20.4 ROMCP Address** is modified
		337	• **Table 20.3 EW Mode 0 and EW Mode 1** Note 2 is modified
		339	• **20.5.1 Flash Memory Control Register 0 FMR01 Bit** and **FMR02 Bit**: description is modified
		340	• **20.5.2 Flash Memory Control Register 1 (FMR1) FMR6 Bit i**s modified, **FMR17 Bit** is modified
		341	• **Figure 20.6 FMR0 and FMR1 Registers** FMR0 register: note 3 modified, value after reset modified; FMR1 register: note 3 modified, reserved bit map modified
		342	• **Figure 20.7 FMR4 Register** Note 2 is modified
		345	• **20.6.3 Interrupts** EW1 mode modified
			• **20.6.4 How to Access** FMR16 bit is added
		346	• **20.6.9 Stop Mode** modified
		352	• **Table 20.7 Errors and FMR0 Register Status** Register name modified
		355	• **Table 20.8 Pin Functions** Pin settings are partially modified
			Electrical Characteristics
			• **V version is newly added**
		366	• **Table 21.1 Absolute Maximum Ratings** Parameters of Pd and Topr are modified
		367	• **Table 21.2 Recommended Operating Conditions** V_{IH} and V_{IL} are modified
		368	• **Table 21.3 A/D Conversion Characeristics** t_{SAMP} deleted, note 4 added
		369	• **Table 21.4 Flash Memory Version Electrical Characteristics:** Standard values of Program and Erase Endrance cycle modified, tps added
			• **Table 21.5 Flash Memory Version Electrical Characteristics:** tps added, data hold time added, note 1, 3, 8 modified, note 11 and 12 added
		370	• **Table 21.6 Low Voltage Detection Circuit Electrical Characteristics** Note 4 added
			• **Table 21.7 Power Supply Circuit from Timing CharacteristicsL** Note 2 & 3 are deleted, figure modified
		372	• **Table 21.9 Electrical Characteristics(2)** Note 5 is added
		380	• **Table 21.25 Electrical Characteristics(2)** Note 5 is added
		387	• **Table 21.40 Absolute Maximum Ratings** Parameters of Pd and Topr are modified

Rev.	Date	Description: Page	Description: Summary
		388	• **Table 21.41 Recommended Operating Conditions** VIH and VIL are modified
		389	• **Table 21.42 A/D Conversion Characeristics** tSAMP deleted, note 4 added
		390	• **Table 21.43 Flash Memory Version Electrical Characteristics:** Standard values of Program and Erase Endrance cycle modified, tps added
			• **Table 21.44 Flash Memory Version Electrical Characteristics:** tps added, data hold time added, note 1, 3, 8 modified, note 11 and 12 added
		391	• **Table 21.45 Power Supply Circuit from Timing CharacteristicsL** Note 2 & 3 are deleted, td(S-R) and td(E-A) are deleted, figure modified
		393	• **Table 21.47 Electrical Characteristics(2)** Note 4 is added
		401	• **Table 21.63 Electrical Characteristics(2)** Note 4 is added
			Precautions
		422	• **22.2.1 PLL Frequency Synthesizer** modified
		423	• **22.2.2 Power Control** Subsection sequence modified, 2., 3. and 4. information modified
		425	• **22.4.3 $\overline{\text{NMI}}$ Interrupt** 2. information partially deleted, 6. information added
		426	• **22.4.5 $\overline{\text{INT}}$ Interrupt** 3. information added
		427	• **22.4.6 Rewrite the Interrupt Control Register** Example 1 is modified
		431	• **22.6.1.3 Timer A (One-shot Timer Mode)** 6. information added
		434	• **22.6.3 Three-phase Motor Control Timer Function** newly added
		435	• **22.7.1 Rewrite the G1 IR Register description modified**
			• **Figure 22.3 IC/OC Interrupt Flow Chart** newly added
		436	• **22.7.2 Rewrite the ICOCiIC Register** newly added
			• **22.7.3 Waveform Generating Function** newly added
			• **22.7.4 IC/OC Base Timer Interrupt** newly added
		438	• **22.8.2.1 Special Mode (I^2C bus Mode)** added
			• **22.8.2.3 SI/O3, SI/O4** added
		441	• **22.10 Multi-master I^2C bus Interface** added
		445	• **22.12 Programmable I/O Ports** 2. and 3. information modified
		447	• **20.14 Mask ROM Version** is added
		448	• **22.15.1 Functions to Inhibit Rewriting Flash Memory Rewrite** modified
			• **22.15.2 Stop Mode** modified
			• **22.16.4 Low Power Disspation Mode, On-chip Oscillator Low Power Dissipation Mode** modified
			• **22.15.7 Operating Speed** modified
		449	• **22.15.9 Interrupts** modified
			• **22.15.13 Regarding Programming/Erasure Times and Execution Time** modified
		450	• **22.15.14 Definition of Programming/Erasure Times** added
			• **22.15.15 Flash Memory version Electrical Characteristics 10,000 E/W cycle**

Rev.	Date	Description: Page	Description: Summary
			products (U7, U9) added
			• **22.15.16 Boot Mode** added
		451	• **22.16 Noise** added
		452	• **20.17 Instruction fo Device Use** added
			Appendix 1. Package Dimensions
		453	• Dimensions are updated
		454-455	**Appendix 2. Functional Comparison** added
1.11	Dec.11,2006		**Clock Generation Circuit**
		54	• **Figure 7.8 Examples of Main Clock Connection Circuit** Note 2 added
			Interrupts
		88	• **Table 9.6 PC Value Saved in Stack Area When Address Match Interrupt Request Is Acknowledged** Table contents partially modified, note added
			Serial I/O
		198	• **Table 14.11 Registers to Be Used and Settings in I^2C bus Mode** Note Relocated
			CAN Module
		297	• **Figure 17.12 C0CONR Register** Note 2 modified
			Electrical Characteristics
		372	• **Table 21.9 Electrical Characteristics (2)** Mask ROM data added, value partially changed: 420 to 450
		379	• **Table 21.24 Electrical Characteristics** Note 1 modified
		380	• **Table 21.25 Electrical Characteristics** Mask ROM data added, note 1 modified
		391	• **Table 21.45 Power Supply Circuit Timing Characteristics** figure for td(P-R) and td(ROC) added, Mask ROM data added
		393	• **Table 21.47 Electrical Characteristics (2)** Mask ROM data added, value paritally changed
		400	• **Table 21.62 Electrical Characteristics** Note 1 modified
		401	• **Table 21.63 Electrical Characteristics** Mask ROM data added, note 1 modified
		412	• **Table 21.83 Power Supply Circuit Timing Characteristics** figure for td(P-R) and td(ROC) added, Mask ROM data added
		414	• **Table 21.85 Electrical Characteristics (2)** Mask ROM data added, value paritally changed
			Usage Notes
		-	• Table numbers and Figure numbers are revised
		421	• **22.1.3 Register Setting** added
		447	• **22.14.1 Internal ROM Area** Description added
1.12	Mar.30, 2007		**Overview**
		1	• **1.1 Features** modified
		2, 3	• note on trademark modified

Rev.	Date	Page	Description Summary
		9	• **Tables 1.6** to **1.8** Product Codes modified
		19, 20	• **Table 1.14 Pin Description** pin description on I/O ports modified
			Reset
		37	• **Figure 5.2 Reset Sequence** Vcc and ROC timings modified
			Processor Mode
		45	• **Figure 6.2 PM2 Register** Description on notes 5 and 6 modified
			Clock Generation Circuit
		52	• **Figure 7.6 PM2 Register** Description on notes 5 and 6 modified
		64	• **Figure 7.12 State Transition in Normal Mode** note 2 modified
			Protection
		69	• Description on protection modified • **Figure 8.1 PRCR Register** note 1 modified
			Interrupts
		88	• **Table 9.6 PC Value Saved in Stack Area When Address Match Interrupt Request I Acknowledged** instruction modified
			Watchdog Timer
		90	• **Figure10.2 WDTS Register** modified • **10.1 Count Source Protective Mode** description modified
			Timer
		129	• **Figure 12.28 ICTB2 Register** modified
			Multi-Master I^2C bus Interface
		256	• **Figure 16.1 Block Diagram of Multi-Master I^2C bus Interface** modified
			Flash Memory Version
		335	• **20.3.1 ROM Code Protect Function** register name modified
		340	• **20.5.2 Flash Memory Control Register 1** description on FMR17 bit modified
		341	• **Figure 20.6 FMR1 Register** note 2 modified
		343	• **Figure 20.9 Setting and Resetting of EW Mode 1** modified
			Electrical Characteristics
		369	• **Table 21.5 Flash Memory Version Electrical Characteristics** note 10 modified
		370	• Timing figure for td(P-R) and td(ROC) modified
		372	• **Table 21.9 Electrical Characteristics** parameter and measurement condition modified, note 5 deleted
		380	• **Table 21.25 Electrical Characteristics** measurement condition modified, note 5 deleted
		390	• **Tables 21.43 and 44 Flash Memory Version Electrical Characteristics** note 10 modified
		391	• Timing figure for td(P-R) and td(ROC) modified
		393	• **Table 21.47 Electrical Characteristics** parameter and condition modified, note

Rev.	Date	Page	Summary
			4 deleted
		401	• **Table 21.63 Elctrical Characteristics** measurement condition modified, note 4 deleted
		411	•**Tables 21.81 and 21.82 Flash Memory Version Electrical Characteristics** note 10 modified
		412	•Timing figure for td(P-R) and td(ROC) modified
		414	•**Table 21.85 Electrical Characteristics** measurment condition modified, note 4 deleted
			Usage Notes
		439	•**Figure 22.4 Use of Capacitors to Reduce Noise** note 1 modified
		449	•**22.15.10 How to Access** description modified
		450	•**22.15.15 Flash Memory Version Electrical Characteristics** 10,000 E/W Cycle Products description modified

RENESAS 16-BIT SINGLE-CHIP MICROCOMPUTER
HARDWARE MANUAL
M16C/29 Group

Publication Data : Rev.0.70 Mar. 29, 2004
Rev.1.12 Mar. 30, 2007

Published by : Sales Strategic Planning Div.
Renesas Technology Corp.

© 2007. Renesas Technology Corp., All rights reserved. Printed in Japan.

M16C/29 Group
Hardware Manual

Renesas Technology Corp.
2-6-2, Ote-machi, Chiyoda-ku, Tokyo, 100-0004, Japan