

# HI-3282

February 2006

### ARINC 429 SERIAL TRANSMITTER AND DUAL RECEIVER

### **GENERAL DESCRIPTION**

The HI-3282 is a silicon gate CMOS device for interfacing the ARINC 429 serial data bus to a 16-bit parallel data bus. Two receivers and an independent transmitter are provided. The receiver input circuitry and logic are designed to meet the ARINC 429 specifications for loading, level detection, timing, and protocol. The ARINC inputs of the HI-3282-10 configurations also have internal lightning protection to DO-160D, Level 3. The transmitter section provides the ARINC 429 communication protocol. An external ARINC 429 Line Driver such as the Holt HI-3182 or HI-8585 is required to translate the 5 volt logic outputs to ARINC 429 drive levels.

The 16-bit parallel data bus exchanges the 32-bit ARINC data word in two steps when either loading the transmitter or interrogating the receivers. The data bus interfaces with CMOS and TTL.

Timing of all the circuitry begins with the master clock input, CLK. For ARINC 429 applications, the master clock frequency is 1 MHz.

Each independent receiver monitors the data stream with a sampling rate 10 times the data rate. The sampling rate is software selectable at either 1MHz or 125KHz. The results of a parity check are available as the 32nd ARINC bit.

The transmitter has a First In, First Out (FIFO) memory to store 8 ARINC words for transmission. The data rate of the transmitter is software selectable by dividing the master clock, CLK, by either 10 or 80. The master clock is used to set the timing of the ARINC transmission within the required resolution.

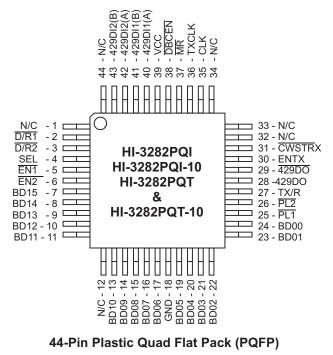
### **APPLICATIONS**

- Avionics data communication
- Serial to parallel conversion
- Parallel to serial conversion

### FEATURES

- ARINC specification 429 compatible
- Compatible with Industry-standard alternate parts
- Small footprint 44-pin PQFP package option
- 16-Bit parallel data bus
- Direct receiver interface to ARINC bus
- Internal Lightning Protection of ARINC inputs per DO-160D, Level 3 in -10 configurations
- Timing control 10 times the data rate
- Selectable data clocks
- Automatic transmitter data timing
- Self test mode
- Parity functions
- Low power, single 5 volt supply
- Industrial & full military temperature ranges

### PIN CONFIGURATION (Top View)



(See page 10 for additional pin configurations)

### **PIN DESCRIPTION**

SYMBOL	FUNCTION	DESCRIPTION
VCC	POWER	+5V ±5%
429DI1 (A)	INPUT	ARINC receiver 1 positive input
429DI1 (B)	INPUT	ARINC receiver 1 negative input
429DI2 (A)	INPUT	ARINC receiver 2 positive input
429DI2 (B)	INPUT	ARINC receiver 2 negative input
D/R1	OUTPUT	Receiver 1 data ready flag
D/R2	OUTPUT	Receiver 2 data ready flag
SEL	INPUT	Receiver data byte selection (0 = BYTE 1) (1 = BYTE 2)
EN1	INPUT	Data Bus control, enables receiver 1 data to outputs
EN2	INPUT	Data Bus control, enables receiver 2 data to outputs if EN1 is high
BD15	I/O	Data Bus
BD14	I/O	Data Bus
BD13	I/O	Data Bus
BD12	I/O	Data Bus
BD11	I/O	Data Bus
BD10	I/O	Data Bus
BD09	I/O	Data Bus
BD08	I/O	Data Bus
BD07	I/O	Data Bus
BD06	I/O	Data Bus
GND	POWER	0 V
BD05	I/O	Data Bus
BD04	I/O	Data Bus
BD03	I/O	Data Bus
BD02	I/O	Data Bus
BD01	I/O	Data Bus
BD00	I/O	Data Bus
PL1	INPUT	Latch enable for byte 1 entered from data bus to transmitter FIFO.
PL2	INPUT	Latch enable for byte 2 entered from data bus to transmitter FIFO. Must follow PL1.
TX/R	OUTPUT	Transmitter ready flag. Goes low when ARINC word loaded into FIFO. Goes high after transmission and FIFO empty.
429DO	OUTPUT	"ONES" data output from transmitter.
429DO	OUTPUT	"ZEROES" data output from transmitter.
ENTX	INPUT	Enable Transmission
CWSTR	INPUT	Clock for control word register
CLK	INPUT	Master Clock input
TX CLK	OUTPUT	Transmitter Clock equal to Master Clock (CLK), divided by either 10 or 80.
MR	INPUT	Master Reset, active low
DBCEN	INPUT	Data bit control Enable. (Active low, with internal pull up to VDD).

### FUNCTIONAL DESCRIPTION

#### CONTROL WORD REGISTER

The HI-3282 contains 11 data flip flops whose D inputs are connected to the data bus and clocks connected to CWSTR. Each flip flop provides options to the user as follows:

DATA BUS PIN	FUNCTION	CONTROL	DESCRIPTION
BD04	PAREN		Enables parity bit insertion into Transmitter data bit 32
BDO5	SELF TEST	0 = ENABLE	If enabled, an internal connection is made passing 429DO and 429DO to the receiver logic inputs
BDO6	BDO6 RECEIVER 1 DECODER 1		If enabled, ARINC bits 9 and, 10 must match the next two control word bits
BDO7	-	-	If Receiver 1 Decoder is enabled, the ARINC bit 9 must match this bit
BDO8	D8		If Receiver 1 Decoder is enabled, the ARINC bit 10 must match this bit
BDO9	RECEIVER 2 DECODER	1 = ENABLE	If enabled, ARINC bits 9 and 10 must match the next two control word bits
BD10	-	-	If Receiver 2 Decoder is enabled, then ARINC bit 9 must match this bit
BD11	-	-	If Receiver 2 Decoder is enabled, then ARINC bit 10 must match this bit
BD12	INVERT XMTR PARITY	1 = ENABLE	Logic 0 enables normal odd parity and Logic 1 enables even parity output in transmitter 32nd bit
BD13	3 XMTR DATA CLK SELECT 0 = +10 1 = +80		CLK is divided either by 10 or 80 to obtain XMTR data clock
BD14	RCVR DTA CLK SELECT	0 = ÷10 1 = ÷80	CLK is divided either by 10 or 80 to obtain RCVR data clock

#### **ARINC 429 DATA FORMAT**

The following table shows the bit positions in exchanging data with the receiver or the transmitter. ARINC bit 1 is the first bit transmitted or received.

	BYTE 1															
DATA BUS	BD 15	BD 14	BD 13	BD 12	BD 11	BD 10	BD 09	BD 08	BD 07	BD 06	BD 05			BD 02	BD 01	BD 00
ARINC BIT	13	12	11	10	9	31	30	32	1	2	3	4	5	6	7	8

					B	YTE	2									
DATA BUS	BD 15	BD 14	BD 13	BD 12	BD 11	BD 10	BD 09	BD 08	BD 07	BD 06	BD 05	BD 04		BD 02	BD 01	BD 00
ARINC BIT	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14

#### **THE RECEIVERS**

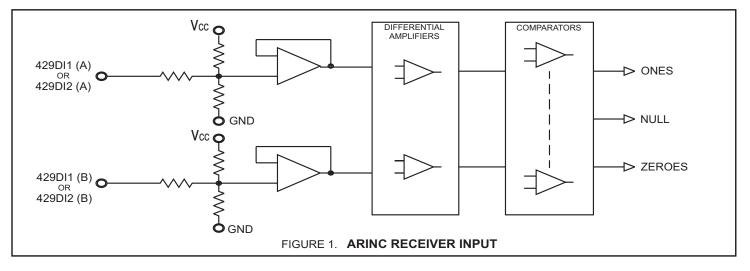
#### **ARINC BUS INTERFACE**

Figure 1 shows the input circuit for each receiver. The ARINC 429 specification requires the following detection levels:

STATE	DIFFERENTI	AL	VOLTAGE
ONE	+6.5 Volts	to	+13 Volts
NULL	+2.5 Volts	to	-2.5 Volts
ZERO	-6.5 Volts	to	-13 Volts

The HI-3282 guarantees recognition of these levels with a common mode Voltage with respect to GND less than  $\pm 5V$  for the worst case condition (4.75V supply and 13V signal level).

The tolerances in the design guarantee detection of the above levels, so the actual acceptance ranges are slightly larger. If the ARINC signal is out of the actual acceptance ranges, including the nulls, the chip rejects the data.



### **FUNCTIONAL DESCRIPTION (cont.)**

#### **RECEIVER LOGIC OPERATION**

Figure 2 shows a block diagram of the logic section of each receiver.

#### **BIT TIMING**

The ARINC 429 specification contains the following timing specification for the received data:

	HIGH SPEED	LOW SPEED
BIT RATE	100K BPS ± 1%	12K -14.5K BPS
PULSE RISE TIME	1.5 ± 0.5 µsec	10 ± 5 µsec
PULSE FALL TIME	1.5 ± 0.5 µsec	10 ± 5 µsec
PULSE WIDTH	5 µsec ± 5%	34.5 to 41.7 µsec

#### **RECEIVER PARITY**

The receiver parity circuit counts Ones received, including the parity bit, ARINC bit 32. If the result is odd, then "0" will appear in the 32nd bit.

#### **RETRIEVING DATA**

Once 32 valid bits are recognized, the receiver logic generates an End of Sequence (EOS). If the receiver decoder is enabled and the 9th and 10th ARINC bits match the control word program bits or if the receiver decoder is disabled, then EOS clocks the data ready flag flip flop to a "1",  $\overline{D/R1}$  or  $\overline{D/R2}$  (or both) will go low. The data flag for a receiver will remain low until after both ARINC bytes from that receiver are retrieved. This is accomplished by activating  $\overline{EN}$  with SEL, the byte selector, low to retrieve the first byte and activating  $\overline{EN}$  with SEL high to retrieve the second byte.

 $\overline{\text{EN1}}$  retrieves data from receiver 1 and  $\overline{\text{EN2}}$  retrieves data from receiver 2.

If another ARINC word is received and a new EOS occurs before the two bytes are retrieved, the data is overwritten by the new word.

#### **INTERNAL LIGHTNING PROTECTION (-10 Only)**

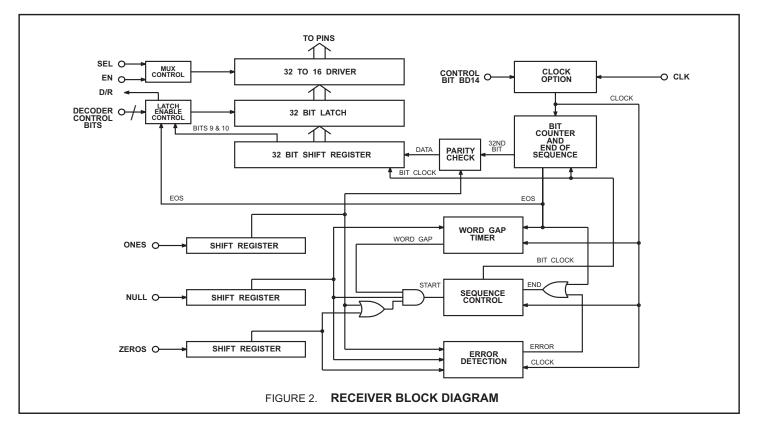
The HI-3282-10 configurations are similar to the HI-3282 except that the ARINC inputs are internally lightning protected to DO-160D, Level 3 through 10 Kohm resistors that <u>must</u> be connected in series with each input from the ARINC bus.

The design of the HI-3282-10 device requires the external 10 Kohm series resistors for proper ARINC level detection. The typical 10 volt differential signal is translated and input to a window comparator and latch. The comparator levels are set so that, with the external 10 Kohm resistors, they are just below the standard 6.5 V minimum ARINC data threshold and just above the 2.5 V maximum ARINC null threshold.

The receivers of the HI-3282-10 when used with external 10 Kohm resistors will withstand DO-160D, Level 3, waveforms 3, 4 and 5A. No additional lightning protection circuit is necessary.

#### **APPLICATION NOTE 300**

Please refer to the Holt AN-300 Application Note for additional information and recommendations on lightning protection of Holt Line Drivers and Receivers.



### **FUNCTIONAL DESCRIPTION (cont.)**

#### TRANSMITTER

A block diagram of the transmitter section is shown in Figure 3.

#### **FIFO OPERATION**

The FIFO is loaded sequentially by first pulsing  $\overline{PL1}$  to load byte 1 and then  $\overline{PL2}$  to load byte 2. The control logic automatically loads the 31 bit word in the next available position of the FIFO. If TX/R, the transmitter ready flag, is high (FIFO empty), then 8 words, each 31 bits long, may be loaded. If TX/R is low, then only the available positions may be loaded. If all 8 positions are full, the FIFO ignores further attempts to load data.

#### DATA TRANSMISSION

When ENTX goes high, enabling transmission, the FIFO positions are incremented with the top register loading into the data transmission shift register. Within 2.5 data clocks the first data bit appears at either 429DO or 429DO. The 31 bits in the data transmission shift register are presented sequentially to the outputs in the ARINC 429 format with the following timing:

	<u>HIGH SPEED</u>	LOW SPEED
ARINC DATA BIT TIME	10 Clocks	80 Clocks
DATA BIT TIME	5 Clocks	40 Clocks
NULLBITTIME	5 Clocks	40 Clocks
WORD GAP TIME	40 Clocks	320 Clocks

The word counter detects when all loaded positions are transmitted and sets the transmitter ready flag, TX/R, high.

#### **TRANSMITTER PARITY**

Control register bit BD04 (PAREN) enables parity bit insertion into transmitter data bit 32. Parity is always inserted if DBCEN is open or high. If DBCEN is low, logic 0 on PAREN inserts data on bit 32, and logic 1 on PAREN inserts parity on bit 32.

The parity generator counts the ONES in the 31-bit word. If the BD12 control word bit is set low, the 32nd bit transmitted will make parity odd. If the control bit is high, the parity is even.

#### SELF TEST

If the BD05 control word bit is set low, 429DO or  $\overline{429DO}$  are internally connected to the receivers inputs, bypassing the interface circuitry. Data to Receiver 1 is as transmitted and data to Receiver 2 is the complement. 429DO and  $\overline{429DO}$  outputs remain active during self test.

#### SYSTEM OPERATION

The two receivers are independent of the transmitter. Therefore, control of data exchanges is strictly at the option of the user. The only restrictions are:

1. The received data may be overwritten if not retrieved within one ARINC word cycle.

2. The FIFO can store 8 words maximum and ignores attempts to load addition data if full.

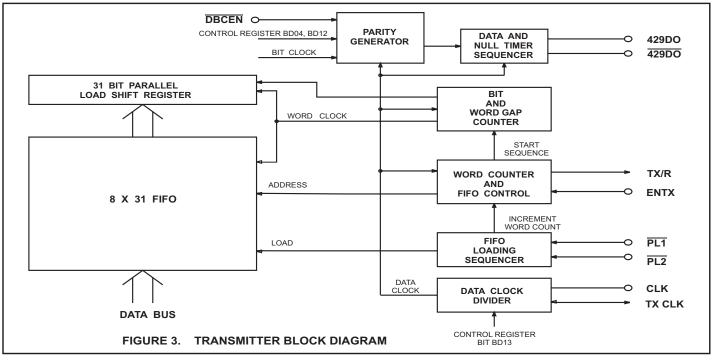
3. Byte 1 of the transmitter data must be loaded first.

4. Either byte of the received data may be retrieved first. Both bytes must be retrieved to clear the data ready flag.

5. After ENTX, transmission enable, goes high it cannot go low until TX/R, transmitter ready flag, goes high. Otherwise, one ARINC word is lost during transmission.

#### MASTER RESET (MR)

On a Master Reset data transmission and reception are immediately terminated, the transmit FIFO and receivers cleared as are the transmit and receive flags. The Control Register is not affected by a Master Reset.



### FUNCTIONAL DESCRIPTION (cont.)

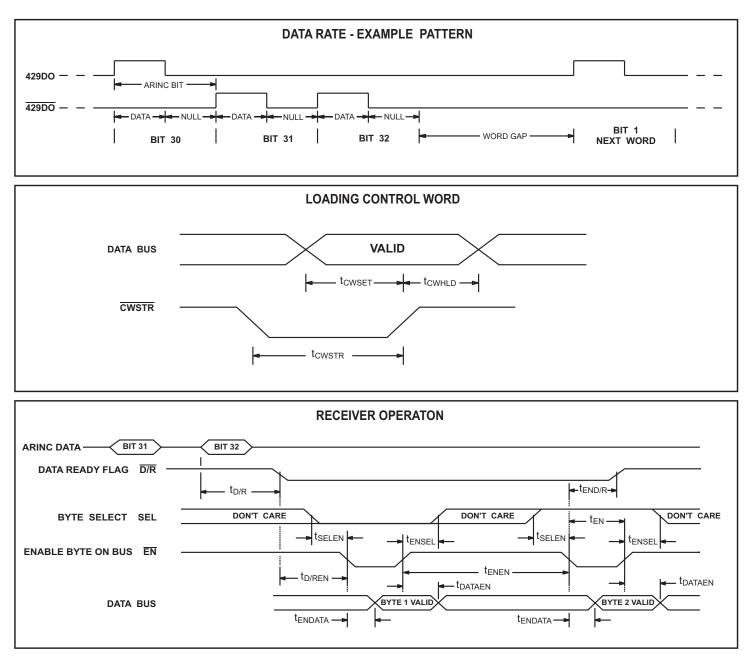
#### **REPEATER OPERATION**

The repeater mode of operation allows a data word that has been received by the HI-3282 to be placed directly into its FIFO for transmission. After a 32-bit word has been shifted into the receiver shift register, the  $\overline{D/R}$  flag will go low. A logic "0" is placed on the SEL line and  $\overline{EN}$  is strobed. This is the same procedure as for normal receiver operation and it places the lower byte (16) of the data word on the data bus. By strobing  $\overline{PL1}$  at the same time as  $\overline{EN}$ , the byte

will also be placed into the transmitter FIFO. SEL is then taken high and  $\overline{\text{EN}}$  is strobed again to place the upper byte of the data word on the data bus. By strobing  $\overline{\text{PL2}}$  at the same time as  $\overline{\text{EN}}$ , the second byte will also be placed into the FIFO. The data word is now ready to be transmitted according to the parity programmed into the control word register.

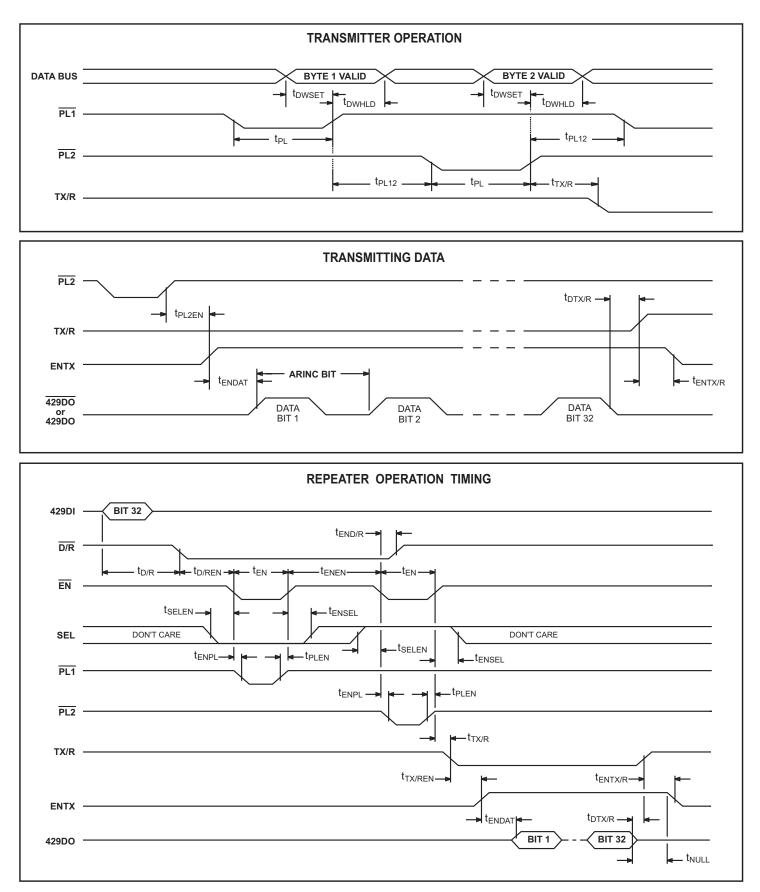
In normal operation, either byte of a received data word may be read from the receiver latches first by use of SEL input. During repeater operation however, the lower byte of the data word must be read first. This is necessary because, as the data is being read, it is also being loaded into the FIFO and the transmitter FIFO is always loaded with the lower byte of the data word first.

### TIMING DIAGRAMS



HI-3282

### **TIMING DIAGRAMS (cont.)**



### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage Vcc	Power Dissipation 500mW
Voltage at ARINC input pins	Operating Temperature Range: (Industrial)40°C to +85°C
Voltage at any other pin0.3V to Vcc +0.3V	(Military) · · · · · -55°C to +125°C
DC Current Drain per input pin 10mA	Storage Temperature Range:

NOTE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### DC ELECTRICAL CHARACTERISTICS

Vcc = 5V  $\pm$ 5%, GND = 0V, TA = Operating Temperature Range (unless otherwise specified).

PARAME	TER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNIT
ARINC INPUTS - Pins: 429	DI1(A), 429DI1(B), 429DI2(A), 42	9DI2(B)					
Differential Input Voltage:	ONE ZERO NULL	Vih Vil Vnul	Common mode voltage less than ±5V with respect to GND	6.5 -13.0 -2.5	10.0 -10.0 0	13.0 -6.5 2.5	V V V
Input Resistance:	Differential To GND To Vcc	Rı Rg Rн	Includes the external 10KΩ resistors in series with each ARINC input of a -10 configuration	12 12 12	27 27		ΚΩ ΚΩ ΚΩ
Input Current:	Input Sink Input Source	Ін І∟		-450		200	μΑ μΑ
Input Capacitance: (Guaranteed but not tested)	Differential To GND To Vcc	Сі Сд Сн				20 20 20	pF pF pF
BI-DIRECTIONAL INPUTS - P	ins:BD00-BD15	-					-
Input Voltage:	Input Voltage HI Input Voltage LO	Vih Vil		2.0		0.8	V V
Input Current:	Input Sink Input Source	Iн I∟		-1.5		1.5	μΑ μΑ
ALL OTHER INPUTS							
Input Voltage:	Input Voltage HI Input Voltage LO	Vih Vil		2.0		0.8	V V
Input Current:	Input Sink Input Source Pull-up Current (DCBEN Pin)	IIH IIL IPU		-10 -150		10 -50	μΑ μΑ μΑ
OUTPUTS							
Output Voltage:	Logic "1" Output Voltage Logic "0" Output Voltage	Vон Vol	Iон = -1.5mA Iо∟ = 1.6mA	2.7		0.4	V V
Output Current: (Bi-directional Pins)	Output Sink Output Source	Iol Ioн	Vout = 0.4V Vout = Vcc - 0.4V	1.6		-1.0	mA mA
Output Current: (All Other Outputs)	Output Sink Output Source	Iol Ioн	Vout = 0.4V Vout = Vcc - 0.4V	1.6		-1.0	mA mA
Output Capacitance:		Co				15	pF
SUPPLY INPUT							
Standby Supply Current:		Icc1				10	mA
Operating Supply Current:		ICC2				10	mA

### AC ELECTRICAL CHARACTERISTICS

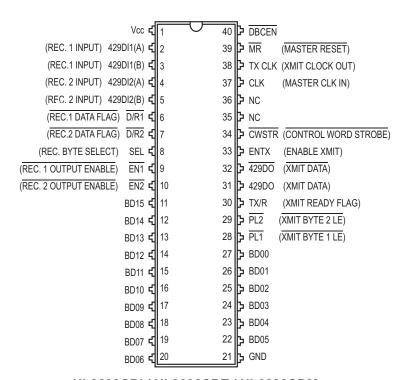
Vcc = 5V, GND = 0V, TA = Operating Temperature Range and fclk = 1mhz ±0.1% with 60/40 duty cycle

			LIMITS		
PARAMETER	SYMBOL				UNITS
		MIN	TYP	MAX	
CONTROL WORD TIMING					
Pulse Width - CWSTR	tcwstr	50			ns
Setup - DATA BUS Valid to CWSTR HIGH Hold - CWSTR HIGH to DATA BUS Hi-Z	tcwset tcwhld	50 0			ns ns
RECEIVER TIMING		· ·		•	
Delay - Start ARINC 32nd Bit to D/R LOW: High Speed Low Speed	tD/R tD/R			16 128	μs μs
Delay - D/R LOW to EN L0W Delay - EN LOW to D/R HIGH	td/ren tend/r	0		200	ns ns
Setup - SEL to EN L0W Hold - SEL to EN HIGH	tselen tensel	0 0			ns ns
Delay - EN L0W to DATA BUS Valid Delay - EN HIGH to DATA BUS Hi-Z	tendata tdataen		50	80 30	ns ns
Pulse Width - EN1 or EN2 Spacing - EN HIGH to next EN LOW	ten tenen	80 50	50		ns ns
FIFO TIMING					
Pulse Width - PL1 or PL2	tPL	50			ns
Setup - DATA BUS Valid to PL HIGH Hold - PL HIGH to DATA BUS Hi-Z	tDWSET tDWHLD	50 10			ns ns
Spacing - PL1 or PL2	tPL12	0			ns
Delay - PL2 HIGH to TX/R LOW	ttx/R			840	ns
TRANSMISSION TIMING					
Spacing - PL2 HIGH to ENTX HIGH	<b>t</b> PL2EN	0			μs
Delay - ENTX HIGH to 429DO or 429D0: High Speed Delay - ENTX HIGH to 429DO or 429D0: Low Speed	tendat tendat			25 200	μs μs
Delay - 32nd ARINC Bit to TX/R HIGH	tdtx/R			50	ns
Spacing - TX/R HIGH to ENTX L0W	tentx/r	0			ns
REPEATER OPERATION TIMING		<u> </u>			
Delay - EN LOW to PL LOW	tenpl	0			ns
Hold - PL HIGH to EN HIGH	<b>t</b> PLEN	0			ns
Delay - TX/R LOW to ENTX HIGH	ttx/ren	0			ns
Master Reset Pulse Width	tmr	50			ns
ARINC Data Rate and Bit Timing				± 1%	

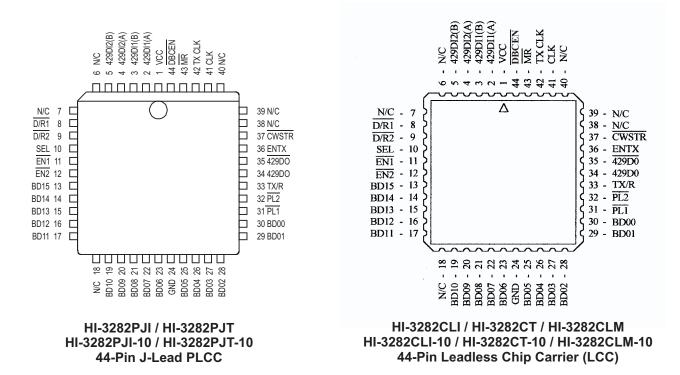
#### HI-3282

ADDITIONAL HI-3282 PIN CONFIGURATIONS (See page 1 for the 44-pin Plastic QFP)

**PIN CONFIGURATION (Top View)** 



#### HI-3282CDI / HI-3282CDT / HI-3282CDM HI-3282CDI-10 / HI-3282CDT-10 / HI-3282CDM-10 40-PIN CERAMIC SIDE-BRAZED DIP



### **ORDERING INFORMATION**

## HI - 3282 <u>Cx x</u> -<u>xx</u> (Ceramic)

	PART		INPUT	SERIES R	ESISTANCE		
	NUMBER		BUILT-IN	REQUIR	ED EXTER	NALLY	
	No dash nu	Imber	35 Kohm		0		
	-10 (	Note 1)	25 Kohm		10 Kohm		
	DADT	TEAR			DUDN		
 	PART NUMBER		PERATURE GE	FLOW	BURN	LEAD FINISH	
	I	-40°	C TO +85°C	1	NO	Gold	
	Т	-55°	-55°C TO +125°C		NO	Gold	
	М	-55°	C TO +125°C	M	YES	Tin / Le	ead (Sn / Pb) Solder
	PART	PACK					1
	NUMBER		RIPTION				
	CD	40 PI	N CERAMIC	SIDE BRA	ZED DIP		1
	CL	44 PI	N CERAMIC	LEADLES	S CHIP CA	RRIER	]

### HI - 3282 <u>Px x x -xx</u> (Plastic)

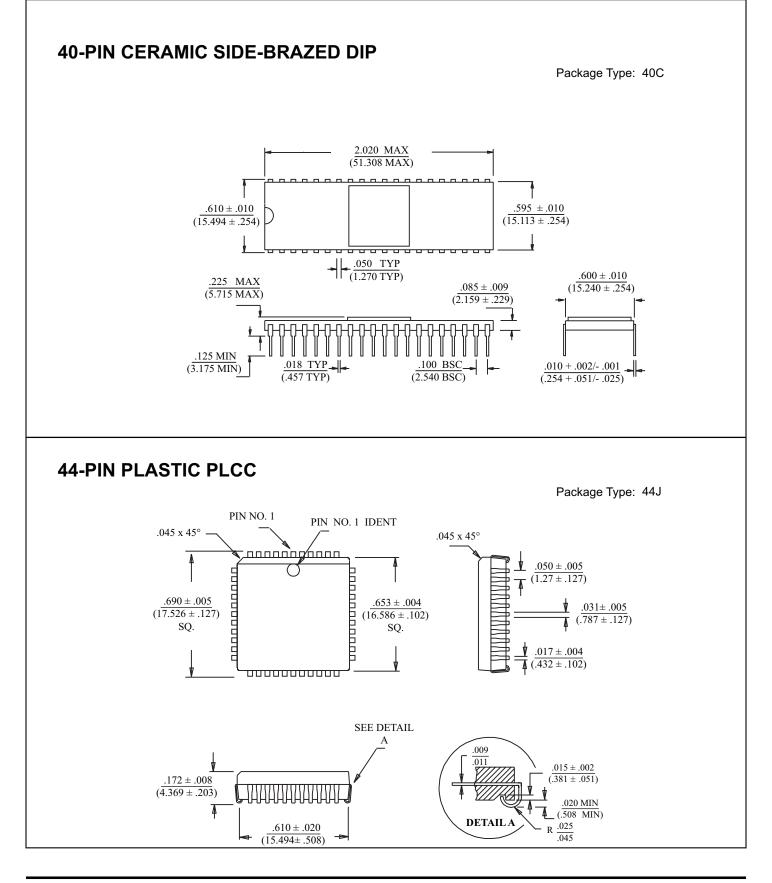
		PART		INPUT	SE	RIES RE	SISTANCE			
		NUMBER		BUILT-IN		REQUIRE		ALLY		
		No dash nu	mber	35 Kohm		0				
		-10 (	Note 1)	25 Kohm	10 Kohm					
		PART NUMBER	LEAD FINIS							
		Blank	Tin /	Lead (Sn / Pl	b) S	Solder				
		F	100% Matte Tin (Pb-free, RoHS compliant)							
L		PART NUMBER	TEMF RANC	PERATURE GE		FLOW	BURN IN			
		I	-40°	C TO +85°C		Ι	NO			
		Т	-55°(	C TO +125°C		Т	NO			
		М	-55°(	C TO +125°C		М	YES			
	 	PART NUMBER	PACKAGE DESCRIPTION							
		PJ	44 PI	N PLASTIC	J-LI	EAD PLCC (Note 2)				
		PQ	44 PI	N PLASTIC	QU	AD FLAT	PACK			

- (1) Internal lightning protection to DO-160D, Level 3 (-10 configurations only). Requires a 10 Kohm resistor in series with each ARINC input to guarantee specified voltage thresholds.
- (2) The 44-pin J-Lead PLCC package is rated as Moisture Sensitivity Level (MSL) 1 and does not require special moisture handling precautions.

# HOLT INTEGRATED CIRCUITS

### **HI-3282 PACKAGE DIMENSIONS**

inches (millimeters)





inches (millimeters)

