*Click **here** for production status of specific part numbers.*

MAX40016

4-Decade Current Sense Amplifier with Integrated Current Sense Element

General Description

The MAX40016 is a very wide range current sense amplifier (CSA) with internal sense element that senses from less than 300µA to greater than 3A current range. The 4-decade sensed current functions with 1% (typical) gain error and offers three, multiplexed programmable output ranges in order to interface with 12-bit ADCs. Having an integrated sense element has the extra advantage that the entire current measuring path can be factory-trimmed, saving the user from having to calibrate independent sense resistors and CSAs. The MAX40016 (WLP package) drops a typical of 60mV at 3A from the voltage input to load output.

The MAX40016's integrated current-sensing element saves the space and cost of an external high-power, precision current sense resistor. The MAX40016 is offered in an ultra-tiny, 1.98mm x 1.31mm, 15-bump wafer-level package (WLP), further reducing board space. The MAX40016 is also available in a 4mm x 4mm 16-pin TQFN package.

The MAX40016 operates with a supply voltage from 2.5V to 5.5V. The device features a low-power mode in which the current-sensing element remains on, but the outputs are turned off to reduce the total supply current below 10µA (max).

The MAX40016 also includes a committed on-board amplifier with an internal gain of 1.5V/V. The MAX40016 operates over the -40°C to +125°C temperature range.

Applications

- Mobile Devices
- RF Power Monitoring
- Portable Instruments

Benefits and Features

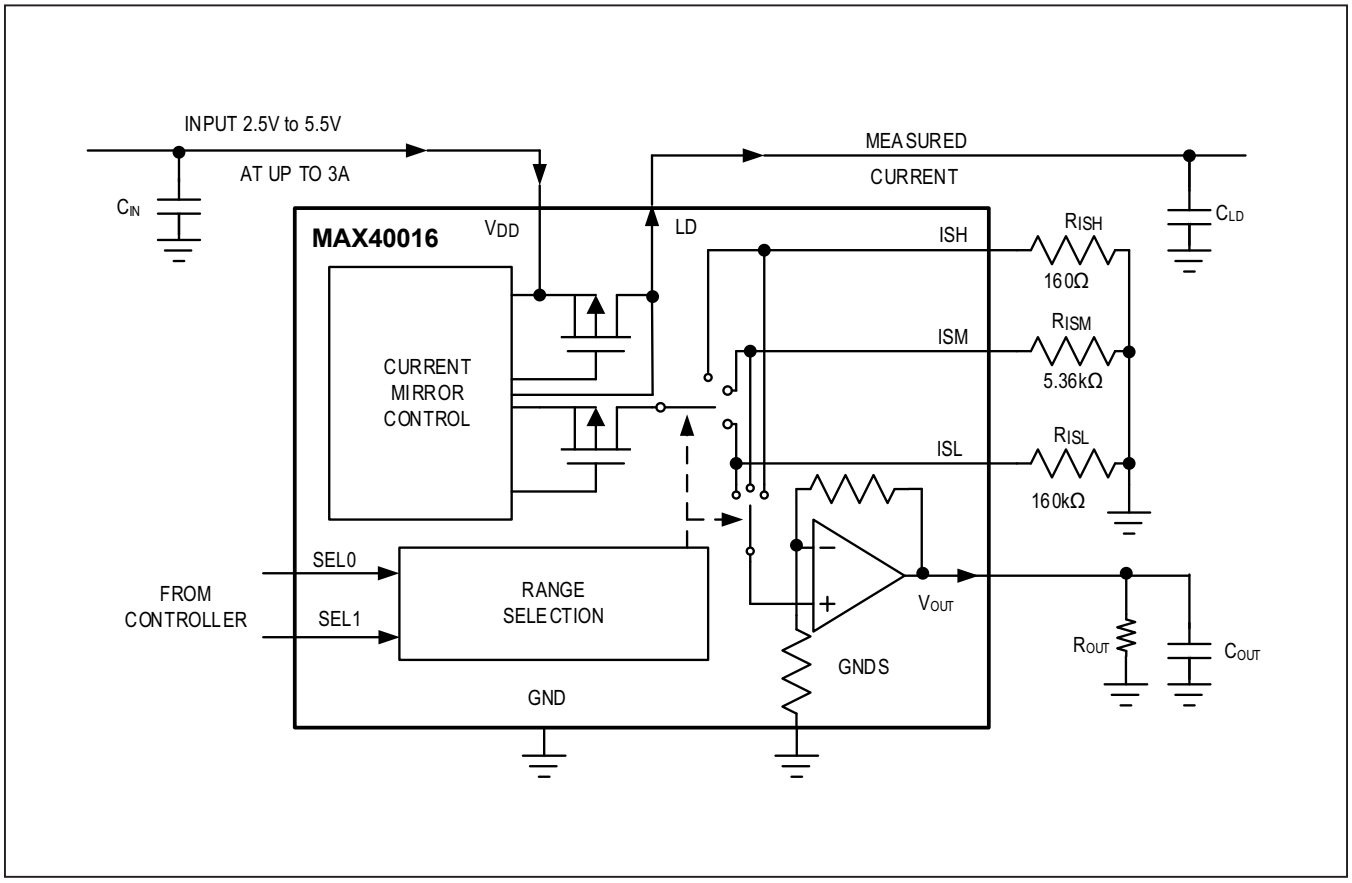
- Integrated Current Sense Element Saves The Space and Cost of Expensive Precision Sense Resistors
- 4-Decade Measurement Range
  - Maintains Accuracy from < 300µA to > 3A
- Withstands Overloads to 4A
- Low Voltage Drop Across Sense Element
  - 60mV (Active Mode, 3A Load, WLP Package)
  - 35mV (Low Power Mode, 3A Load, WLP Package)
- Three Multiplexed Scaling Resistor Outputs Allow Full Dynamic Range while Interfaced to 12-bit ADCs
- +2.5V to +5.5V Input Supply Voltage Range
- Low Power Mode Reduces Supply Current to 10µA Max
- Space-Saving
  - Tiny 1.98mm x 1.3mm, 15-Bump WLP
  - 4mm x 4mm 16-Pin TQFN
- -40°C to +125°C Operating Temperature Range

***Ordering Information** appears at end of data sheet.*

19-100232; Rev 2; 11/18

maxim integrated™

Simplified Block Diagram



Absolute Maximum Ratings

V_{DD} to GND .....-0.3V to +6V
GND to GNDS .....-0.3V to +0.3V
SEL0, SEL1, ISL, ISM, ISH, V_{OUT} to GND ..-0.3V to V_{DD}+0.3V
V_{DD} to LD .....-0.3V to 0.3V
LD to GND ..... V_{DD} - 0.3V to V_{DD} + 0.3V
Maximum Current
(All pins except V_{DD}, LD, continuous).....20mA
Current from V_{DD} to LD (Continuous).....4A

Continuous Power Dissipation (T_A = +70°C)
15-Bump WLP (derate 14.39mW/°C above +70°C).....1151.2mW
16-Pin TQFN (derate 25mW/°C above +70°C) 2000mW
Operating Temperature Range..... -40°C to +125°C
Junction Temperature.....+150°C
Storage Temperature Range..... -65°C to +150°C
Soldering Temperature (reflow).....+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

15 WLP

PACKAGE CODE	N151B1+1
Outline Number	21-100213
Land Pattern Number	Refer to Application Note 1891
THERMAL RESISTANCE, MULTI-LAYER BOARD:	
Junction to Ambient (θ_{JA})	69.5°C/W
Junction to Case (θ_{JC})	N/A

16 TQFN

PACKAGE CODE	T1644+4
Outline Number	21-0139
Land Pattern Number	90-0070
THERMAL RESISTANCE, MULTI-LAYER BOARD:	
Junction to Ambient (θ_{JA})	40°C/W
Junction to Case (θ_{JC})	6°C/W

For the latest package outline information and land patterns (footprints), go to **www.maximintegrated.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to **www.maximintegrated.com/thermal-tutorial**.

Electrical Characteristics

(V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, SEL0 = V_{DD}, SEL1 = V_{DD} (ISH range is selected), T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C (Note 1))

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CURRENT SENSING						
Supply Voltage	V_{DD}	Guaranteed by PSRR	2.5		5.5	V
Supply Current (Active)	I_{DD}	No I_{LD} current, V_{ISX} = 0V		0.8	1.2	mA
Supply Current (Low-Power Mode)	I_{DD_LP}	Low-power mode (SEL0 = 0V, SEL1 = 0V), no I_{LD} current, V_{ISX} = 0V		5	10	µA
Power-Up Time		Measure at 50% of VOUT.		100		µs
Power Supply Rejection Ratio	PSRR	ΔGain Error/ΔV_{DD}, measured at ISX (Note 2)	-0.6	+0.2	+0.6	%/V

Electrical Characteristics (continued)

(V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, SEL0 = V_{DD}, SEL1 = V_{DD} (ISH range is selected), T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C (Note 1))

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Voltage Drop (V_{DD} to LD) (WLP)		Active mode, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C		60	90	mV
			-40°C < T_A < +125°C			100	
		Active mode, I_{LD} = 2A	-40°C < T_A < +85°C		50	80	
			-40°C < T_A < +125°C			95	
		Low power mode, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C		35	50	
			-40°C < T_A < +125°C			55	
		Low power mode, I_{LD} = 2A	-40°C < T_A < +85°C		23	35	
			-40°C < T_A < +125°C			35	
Voltage Drop (V_{DD} to LD) (TQFN)		Active mode, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C		160	230	mV
			-40°C < T_A < +125°C		160	250	
		Active mode, I_{LD} = 2A	-40°C < T_A < +85°C		120	180	
			-40°C < T_A < +125°C		120	200	
		Low power mode, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C		150	220	
			-40°C < T_A < +125°C		150	230	
		Low power mode, I_{LD} = 2A	-40°C < T_A < +85°C		100	150	
			-40°C < T_A < +125°C		100	160	
Current Gain	G_I	I_{ISX}/I_{LD}, measured at ISX			2		mA/A
Current Gain Error	G_{I_ERR}	R_{ISX} = 160Ω, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C	-4	+0.9	+4	%
			-40°C < T_A < +125°C	-4	+0.9	+4	
		R_{ISX} = 160Ω, I_{LD} = 300mA	-40°C < T_A < +85°C	-3.5	+0.9	+3.5	
			-40°C < T_A < +125°C	-4		+4	
		R_{ISX} = 5.36kΩ, I_{LD} = 30mA	-40°C < T_A < +85°C	-3.5	+0.7	+3.5	
			-40°C < T_A < +125°C	-4		+4	
		R_{ISX} = 160kΩ, I_{LD} = 3mA	-40°C < T_A < +85°C	-6	+1.4	+6	
			-40°C < T_A < +125°C	-7		+7	
		R_{ISX} = 160kΩ, I_{LD} = 1mA	-40°C < T_A < +85°C	-12	+1.7	+12	
			-40°C < T_A < +125°C	-15		+15	
		R_{ISX} = 160kΩ, I_{LD} = 300µA	-40°C < T_A < +85°C	-25	+2.8	+25	
			-40°C < T_A < +125°C	-30		+30	
Nonlinearity Current Gain Error	$G_{I_ERR(NON)}$	Measured at ISX	R_{ISX} = 160Ω, I_{LD} = 30mA to 3A		0.4		%
			R_{ISX} = 5.36kΩ, I_{LD} = 3mA to 30mA		0.8		
			R_{ISX} = 160kΩ, I_{LD} = 300µA to 3mA		1.7		

Electrical Characteristics (continued)

(V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, SEL0 = V_{DD}, SEL1 = V_{DD} (ISH range is selected), T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C (Note 1))

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
CMRR_ISX (Note 3)		Measured at ISX, 0V < V_{ISX} < 1.1V	R_{ISX} = 160Ω, I_{LD} = 2A		0.02		%/V
			R_{ISX} = 5.36kΩ, I_{LD} = 100mA		0.02		
			R_{ISX} = 160kΩ, I_{LD} = 1mA		0.06		
ISX Residual Current		I_{LD} = 0			20		nA
AMPLIFIER/DC CHARACTERISTICS							
Typical Input Voltage		Guaranteed by Output Amplifier Gain Error			0.01 to 1.0		V
Offset Voltage	V_{OS}	Input referred (Note 4)			20		µV
PSRR_VOUT		$\Delta V_{OUT}/\Delta V_{DD}$, V_{ISX} = 1.0V, 2.5V < V_{DD} < 5.5V			0.2		mV/V
Output Amplifier Gain	G_V				1.5		V/V
Output Amplifier Gain Error	G_{V_ERR}	0.01V < V_{ISX} < 1V		-1	+0.2	+1	%
Output Load Regulation		$\Delta V_{OUT}/\Delta I_{OUT}$, sourcing 0 and 2mA, V_{ISX} = 1.0V,			0.1	1	Ω
		$\Delta V_{OUT}/\Delta I_{OUT}$, sinking 0 and 500µA, V_{ISX} = 10mV			0.1	1	
Leakage Current Into V_{OUT} (Low Power Mode)		SEL0 = 0V, SEL1 = 0V, at V_{OUT} = 1.5V			5	100	nA
Max Sink Current		V_{ISX} = 0V, V_{OUT} = 1.65V, pulsed test			28		mA
Max Source Current		V_{ISX} = 1.1V, V_{OUT} = 0V, pulsed test			28		mA
Total Transimpedance Gain		R_{ISX} connected to ISX pins			0.003 x R_{ISX}		
Total Transimpedance Gain Error (Measured at V_{OUT})		R_{ISX} = 160Ω, I_{LD} = 3A (Note 6)	-40°C < T_A < +85°C	-4	+0.9	+4	%
			-40°C < T_A < +125°C	-4	+0.9	+4	
		R_{ISX} = 160Ω, I_{LD} = 300mA	-40°C < T_A < +85°C	-3.5	1	+3.5	
			-40°C < T_A < +125°C	-4		+4	
		R_{ISX} = 5.36kΩ, I_{LD} = 30mA	-40°C < T_A < +85°C	-3.5	+0.8	+3.5	
			-40°C < T_A < +125°C	-4		+4	
		R_{ISX} = 160kΩ, I_{LD} = 3mA	-40°C < T_A < +85°C	-6	+1.5	+6	
			-40°C < T_A < +125°C	-7		+7	
		R_{ISX} = 160kΩ, I_{LD} = 1mA	-40°C < T_A < +85°C	-12	+1.8	+12	
			-40°C < T_A < +125°C	-15		+15	
		R_{ISX} = 160kΩ, I_{LD} = 300µA	-40°C < T_A < +85°C	-25	+3	+25	
			-40°C < T_A < +125°C	-30		+30	

Electrical Characteristics (continued)

(V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, SEL0 = V_{DD}, SEL1 = V_{DD} (ISH range is selected), T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C (Note 1))

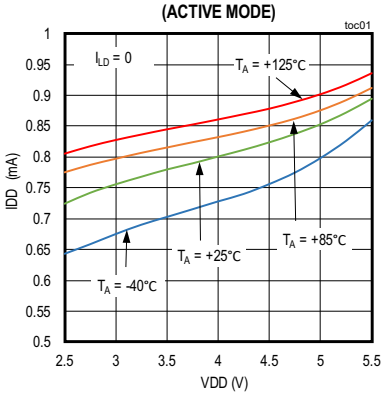
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Nonlinearity Total Transimpedance Gain Error (Measured at V_{OUT})		R_{ISX} = 160Ω, I_{LD} = 100mA to 3A		0.4		%
		R_{ISX} = 5.36kΩ, I_{LD} = 3mA to 100mA		0.8		
		R_{ISX} = 160kΩ, I_{LD} = 300µA to 3mA		1.7		
AMPLIFIER/AC CHARACTERISTICS						
Small Signal Bandwidth		R_{ISX} = 160kΩ, I_{LD} = 3mA DC and 30μA_{PP}, C_{LD} = 0		1		MHz
		R_{ISX} = 160Ω, I_{LD} = 300mA_DC and 3mA_{PP}, C_{LD} = 0		0.7		
Large Signal Bandwidth		R_{ISX} = 160Ω, I_{LD} = 2A_DC and 1A_{PP}, C_{LD} = 0		300		kHz
Load Transient Response Time		R_{ISX} = 160kΩ, I_{LD} = 1mA ↔ 2mA		220		µs
		R_{ISX} = 5.36kΩ, I_{LD} = 30mA ↔ 60mA		70		µs
		R_{ISX} = 160Ω, I_{LD} = 1A ↔ 2A		60		µs
Output Noise 1/f		0.1Hz to 10Hz		25		μV_{PP}
Output Integrated Noise		100Hz to 10kHz		11		μV_{RMS}
RANGE SELECT INPUTS (SEL0, SEL1)						
Input High Level	V_{IH}	SEL0 and SEL1	1			V
Input Low Level	V_{IL}	SEL0 and SEL1			0.5	V
Input Current	I_{IH}	V_{IH} = V_{VDD}, SEL0 and SEL1 have weak pulldowns			0.5	µA
	I_{IL}	V_{IL} = 0V, SEL0 and SEL1 have weak pulldowns			0.5	
Low Power Mode, Sleep Delay	t_{DIS}	I_{LD} = 30mA (Note 5)		5		µs
Low Power Mode, Waking Delay	t_{EN}	R_{ISX} = 160Ω, I_{LD} = 300mA (Note 5)		30		µs
		R_{ISX} = 5.36kΩ, I_{LD} = 30mA (Note 5)		50		
		R_{ISX} = 160kΩ, I_{LD} = 1mA (Note 6)		550		
Range Control Delay		Measured from 50% level of SEL0 or SEL1 to the 50% rise of the ISX current		6		µs

Note 1: Limits are 100% tested at T_A = +25°C. Limits over the temperature range and relevant supply voltage range are guaranteed by design and characterization.
Note 2: ISX is any one of the ISL, ISM or ISH pins.
Note 3: CMRR_ISX is calculated as (ΔI_{ISX} / I_{ISX}) / ΔV_{ISX}.
Note 4: Guaranteed by circuit architecture.
Note 5: Measured from 50% level of SEL0 or SEL1 edge to 50% reduction in the ISX current.
Note 6: Guaranteed by design.

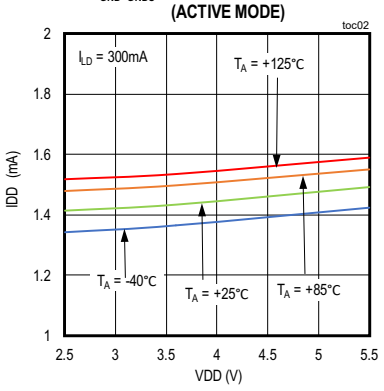
Typical Operating Characteristics

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

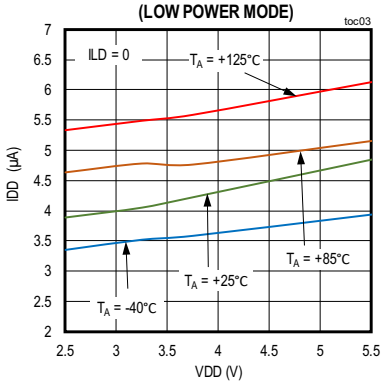
IDD vs. VDD vs. TEMPERATURE
(ACTIVE MODE)



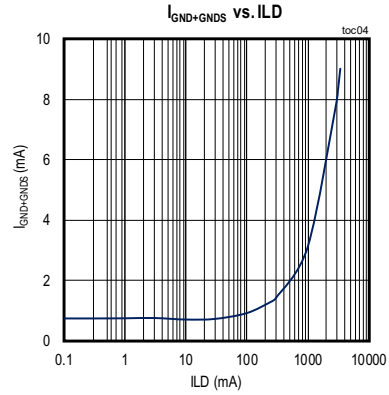
$I_{GND+GNDS}$ vs. VDD vs. TEMPERATURE
(ACTIVE MODE)



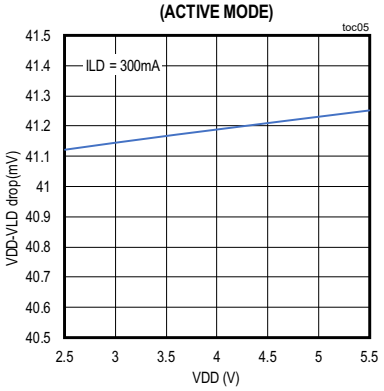
IDD vs. VDD vs. TEMPERATURE
(LOW POWER MODE)



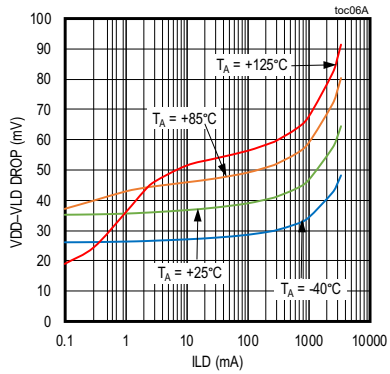
$I_{GND+GNDS}$ vs. ILD



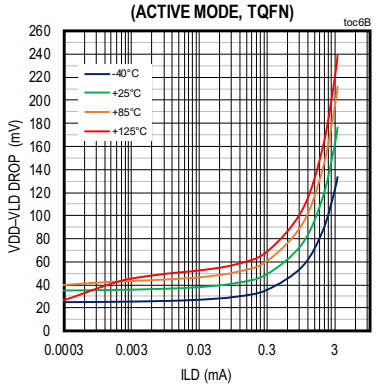
VDD-VLD DROP vs. VDD
(ACTIVE MODE)



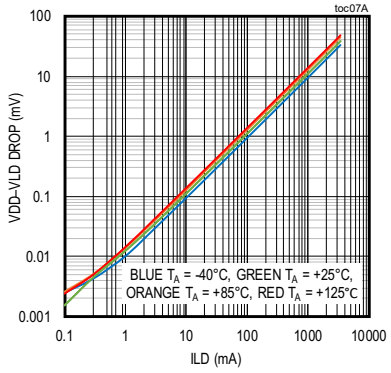
VDD–VLD DROP vs. ILD
(ACTIVE MODE, WLP)



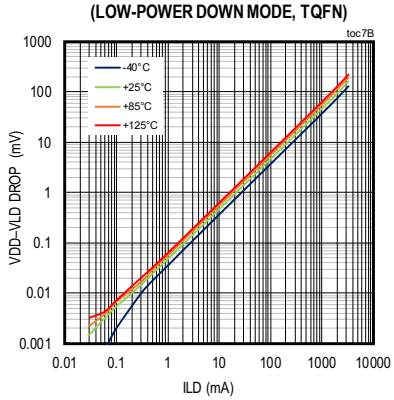
VDD–VLD DROP vs. ILD
(ACTIVE MODE, TQFN)



VDD-VLD DROP vs. ILD
(LOW-POWER DOWN MODE, WLP)



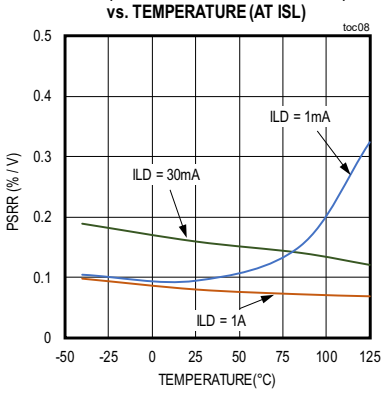
VDD-VLD DROP vs. ILD
(LOW-POWER DOWN MODE, TQFN)



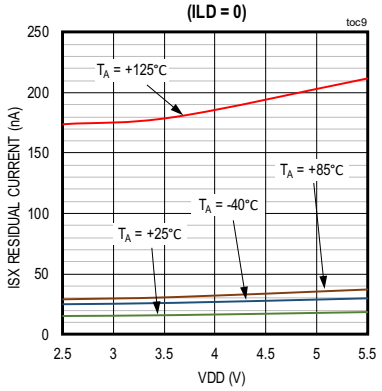
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

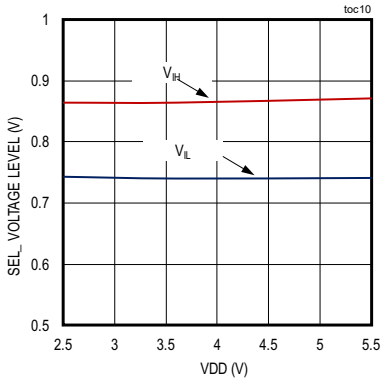
PSRR (ΔCURRENT GAIN ERROR/ΔVDD) vs. TEMPERATURE (AT ISL)



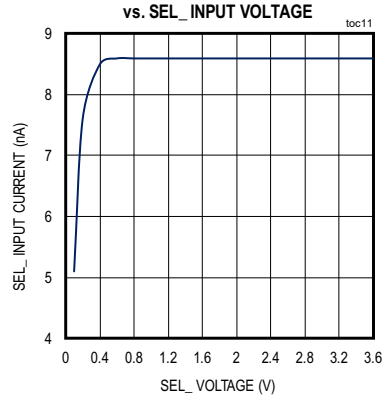
ISX RESIDUAL CURRENT vs. VDD (ILD = 0)



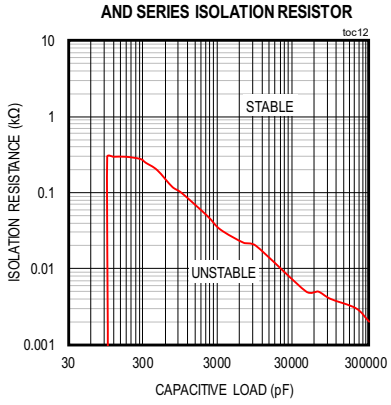
SEL_ VOLTAGE LEVELS vs. VDD



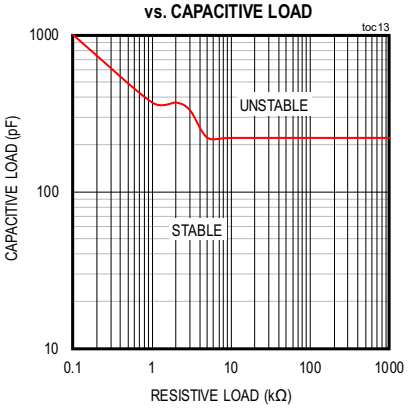
SEL_ INPUT CURRENT vs. SEL_ INPUT VOLTAGE



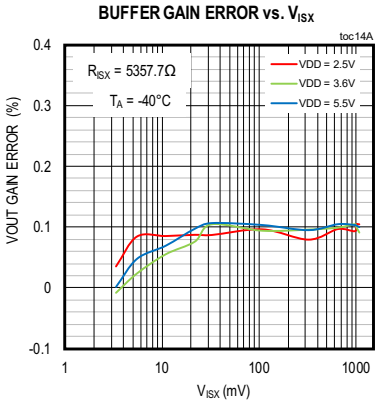
BUFFER STABILITY vs. CAPACITIVE LOAD AND SERIES ISOLATION RESISTOR



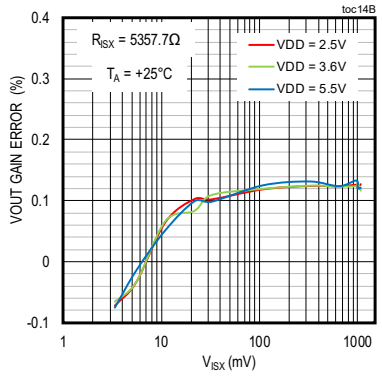
BUFFER STABILITY RESISTIVE LOAD vs. CAPACITIVE LOAD



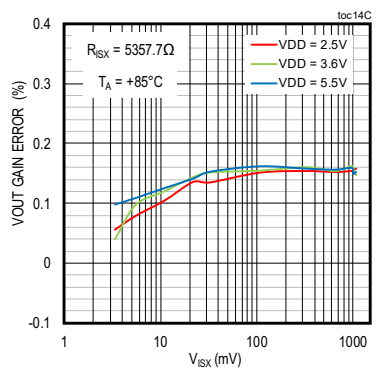
BUFFER GAIN ERROR vs. V_{ISX}



BUFFER GAIN ERROR vs. V_{ISX}



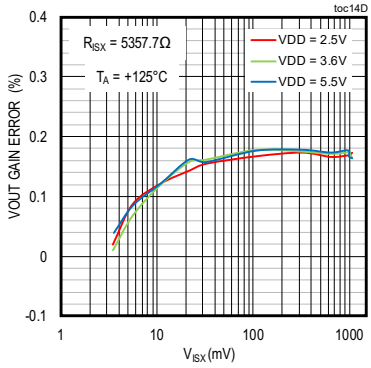
BUFFER GAIN ERROR vs. V_{ISX}



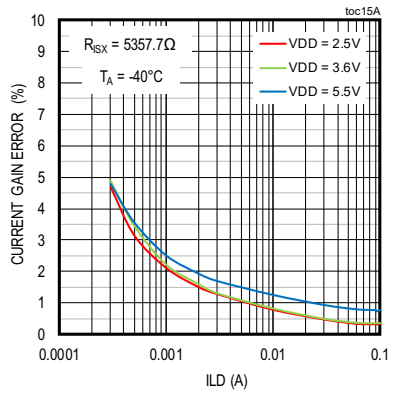
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

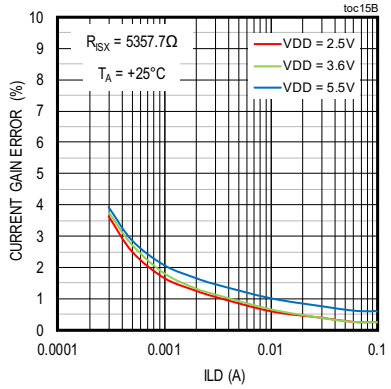
BUFFER GAIN ERROR vs. V_{ISX}



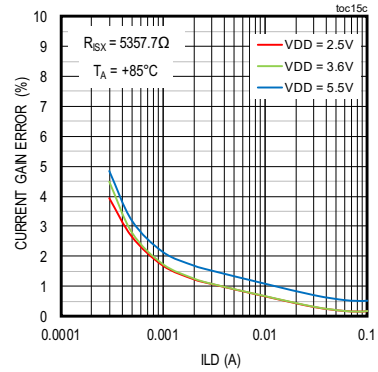
CURRENT GAIN ERROR vs. I_{LD}



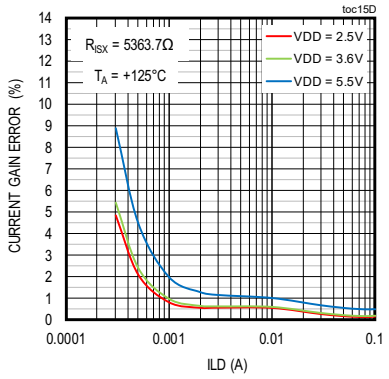
CURRENT GAIN ERROR vs. I_{LD}



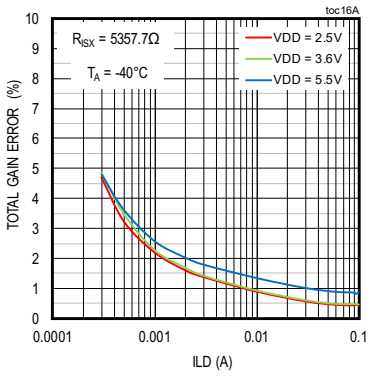
CURRENT GAIN ERROR vs. I_{LD}



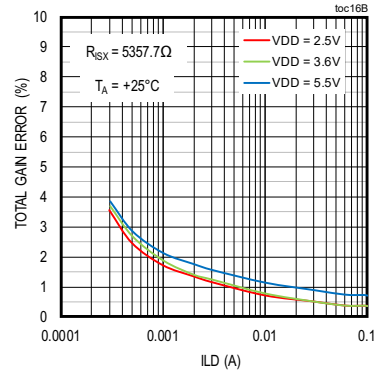
CURRENT GAIN ERROR vs. I_{LD}



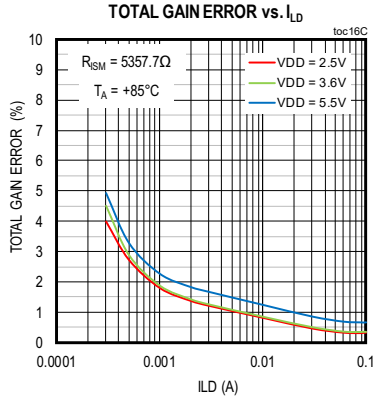
TOTAL GAIN ERROR vs. I_{LD}



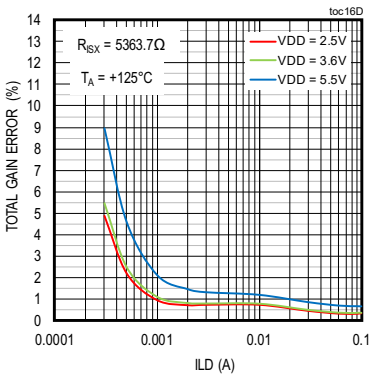
TOTAL GAIN ERROR vs. I_{LD}



TOTAL GAIN ERROR vs. I_{LD}



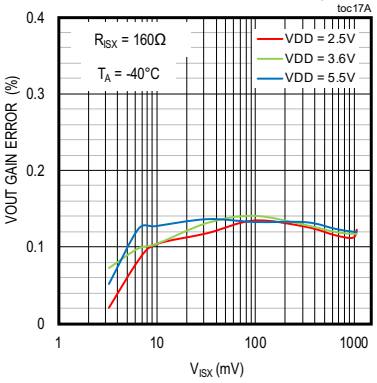
TOTAL GAIN ERROR vs. I_{LD}



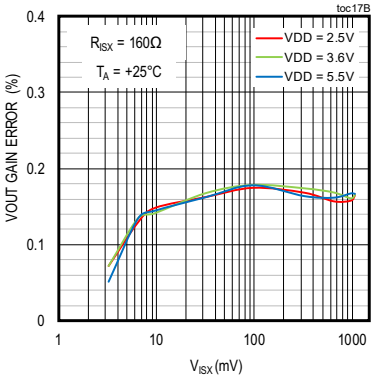
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

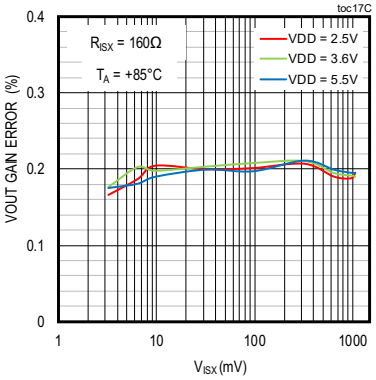
BUFFER GAIN ERROR vs. V_{ISX}



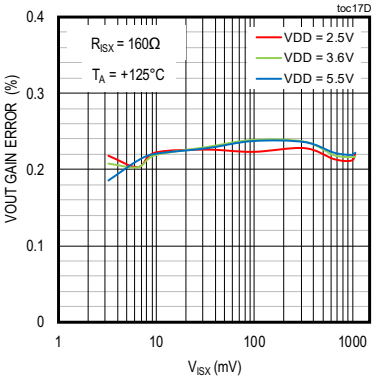
BUFFER GAIN ERROR vs. V_{ISX}



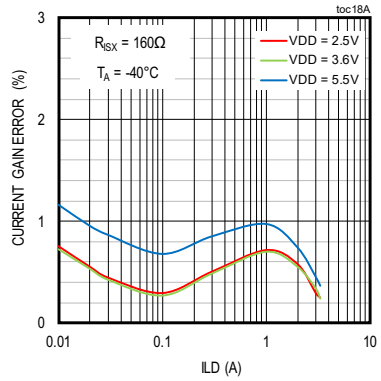
BUFFER GAIN ERROR vs. V_{ISX}



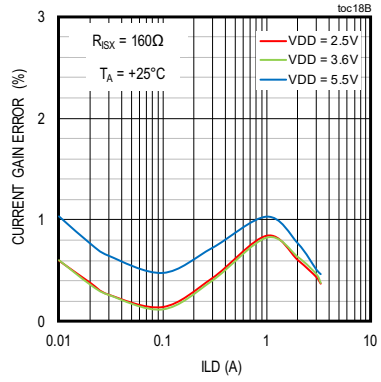
BUFFER GAIN ERROR vs. V_{ISX}



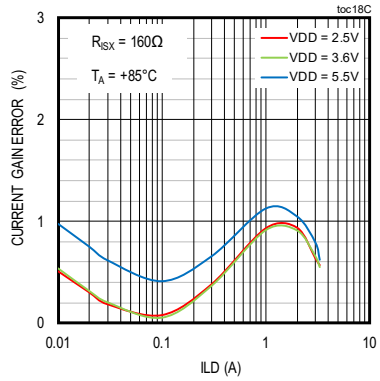
CURRENT GAIN ERROR vs. I_{LD}



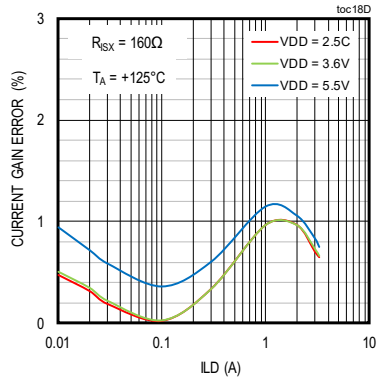
CURRENT GAIN ERROR vs. I_{LD}



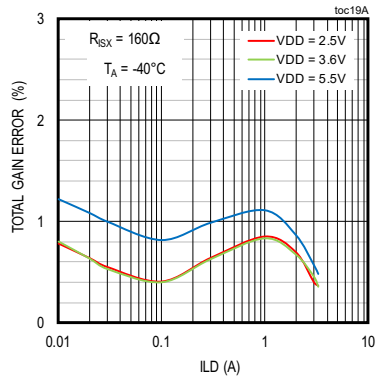
CURRENT GAIN ERROR vs. I_{LD}



CURRENT GAIN ERROR vs. I_{LD}



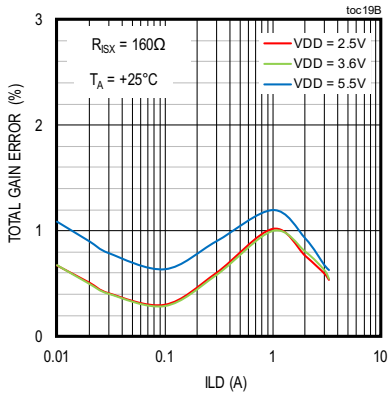
TOTAL GAIN ERROR vs. I_{LD}



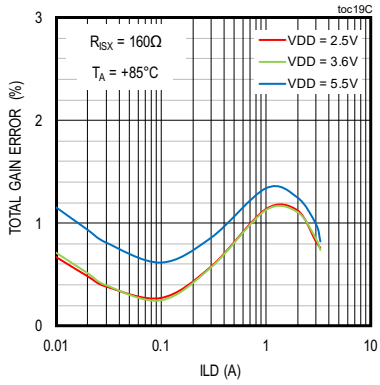
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

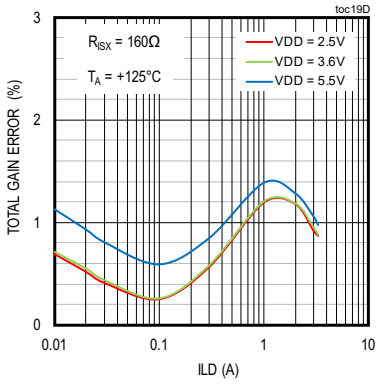
TOTAL GAIN ERROR vs. I_{LD}



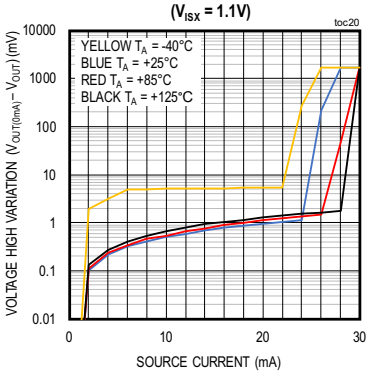
TOTAL GAIN ERROR vs. I_{LD}



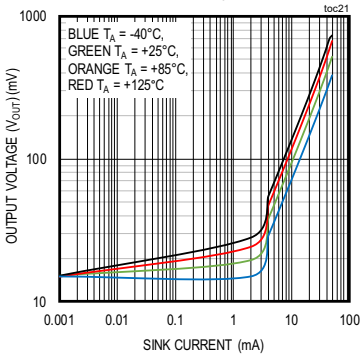
TOTAL GAIN ERROR vs. I_{LD}



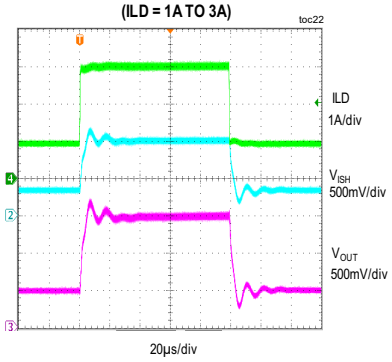
BUFFER OUTPUT VOTLAGE HIGH VARIATION vs. OUTPUT SOURCE CURRENT AT FULL SCALE (V_{ISX} = 1.1V)



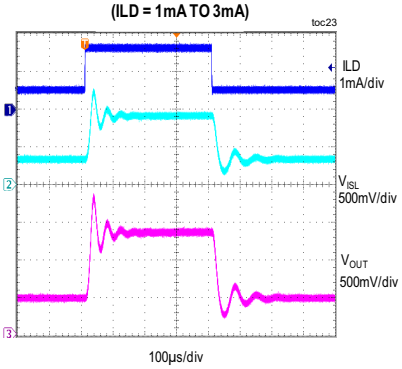
BUFFER OUTPUT VOTLAGE LOW vs. OUTPUT SINK CURRENT (V_{ISX} = 10mV)



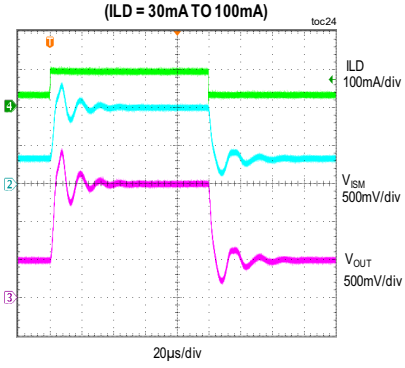
ISH LOAD TRANSIENT RESPONSE (ILD = 1A TO 3A)



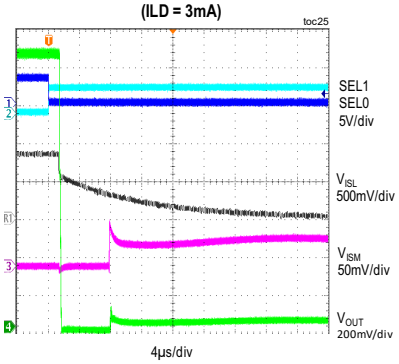
ISL LOAD TRANSIENT RESPONSE (ILD = 1mA TO 3mA)



ISM LOAD TRANSIENT RESPONSE (ILD = 30mA TO 100mA)



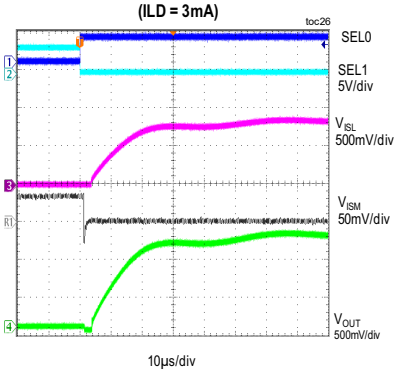
ISL-TO-ISM RANGE-SWITCH RESPONSE (ILD = 3mA)



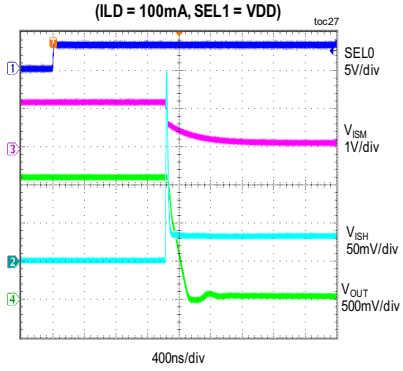
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

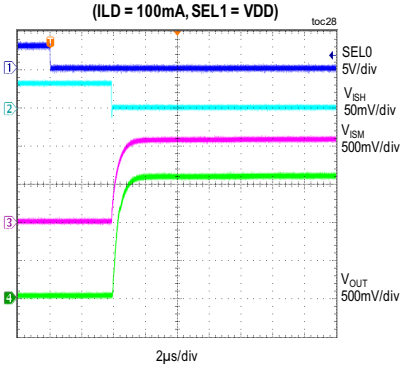
ISM-TO-ISL RANGE-SWITCH RESPONSE (ILD = 3mA)



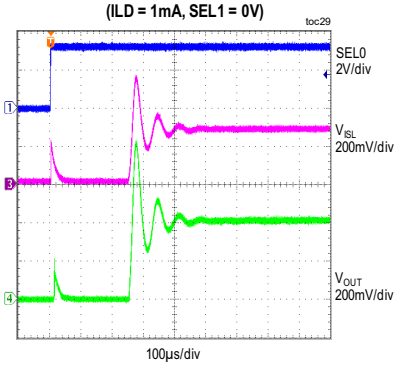
ISM-TO-ISH RANGE-SWITCH RESPONSE (ILD = 100mA, SEL1 = VDD)



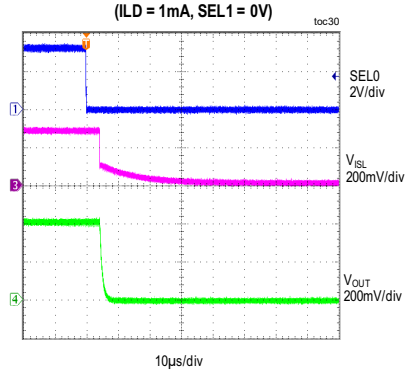
ISH-TO-ISM RANGE-SWITCH RESPONSE (ILD = 100mA, SEL1 = VDD)



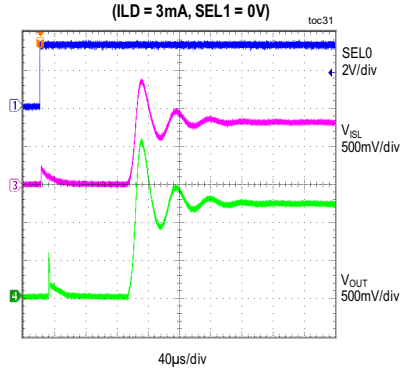
ISL ENABLE DELAY (ILD = 1mA, SEL1 = 0V)



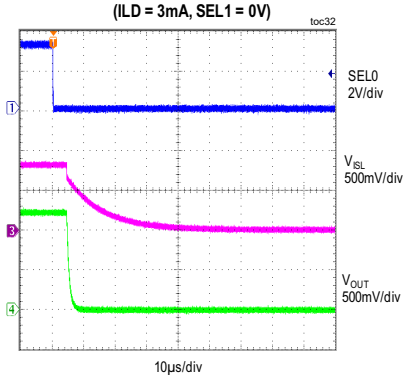
ISL DISABLE DELAY (ILD = 1mA, SEL1 = 0V)



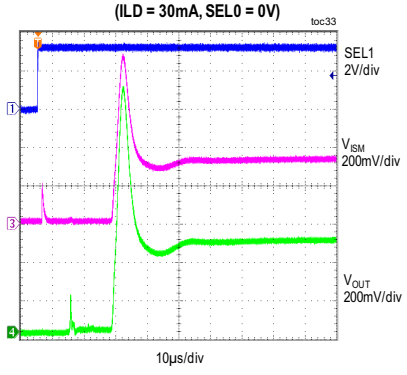
ISL ENABLE DELAY (ILD = 3mA, SEL1 = 0V)



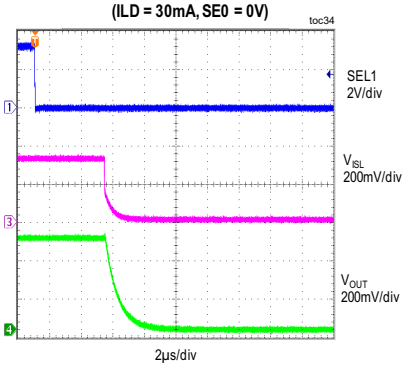
ISL DISABLE DELAY (ILD = 3mA, SEL1 = 0V)



ISM ENABLE DELAY (ILD = 30mA, SEL0 = 0V)



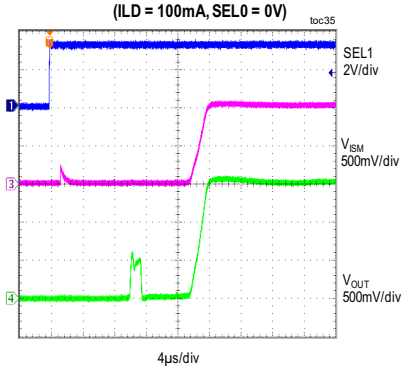
ISM DISABLE DELAY (ILD = 30mA, SE0 = 0V)



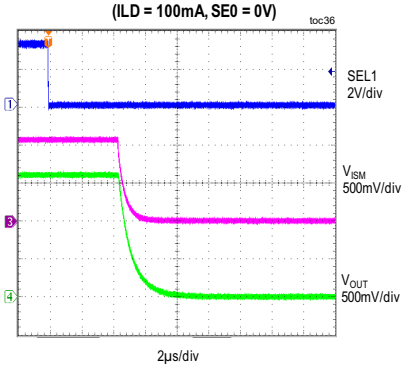
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

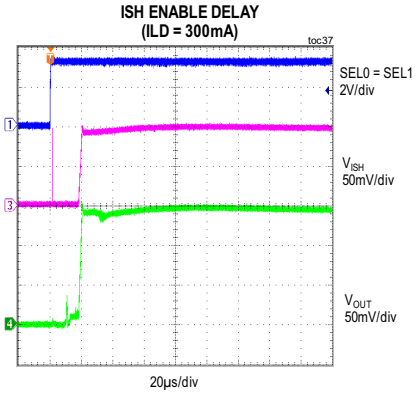
ISM ENABLE DELAY
(ILD = 100mA, SEL0 = 0V)



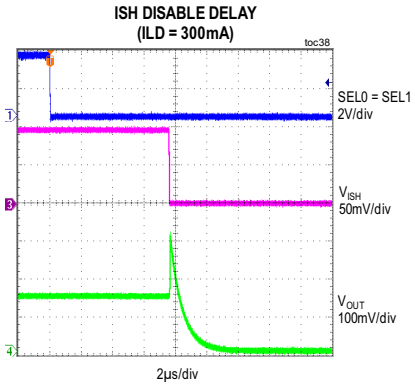
ISM DISABLE DELAY
(ILD = 100mA, SE0 = 0V)



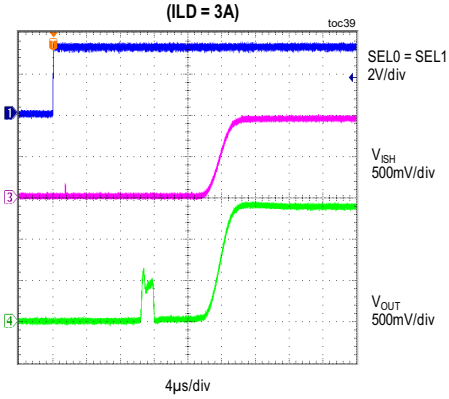
ISH ENABLE DELAY
(ILD = 300mA)



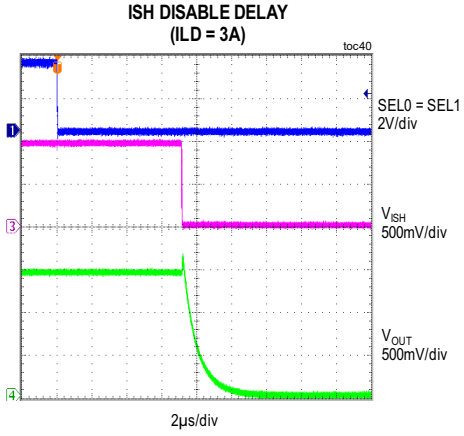
ISH DISABLE DELAY
(ILD = 300mA)



ISH ENABLE DELAY
(ILD = 3A)



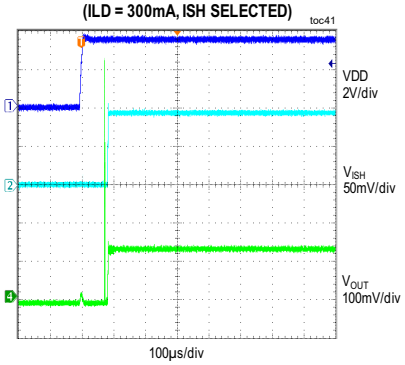
ISH DISABLE DELAY
(ILD = 3A)



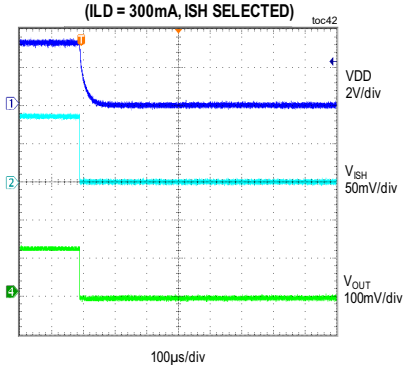
Typical Operating Characteristics (continued)

V_{DD} = 3.6V, I_{LD} = 300mA, C_{LD} = 10µF, R_{OUT} = 10kΩ, C_{OUT} = 10pF, R_{ISH} = 160Ω, R_{ISM} = 5.36kΩ, R_{ISL} = 160kΩ (per the MAX40016 EV kit). Typical values are at T_A = +25°C, unless otherwise noted. (ISX is any one of the ISL, ISM or ISH pins.)

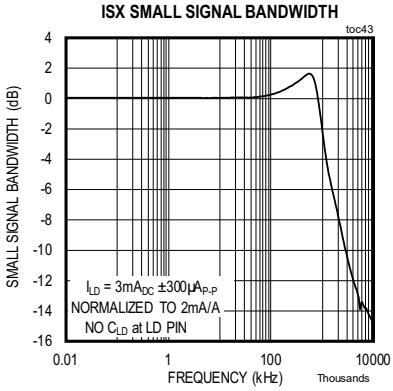
POWER-UP TIME
(ILD = 300mA, ISH SELECTED)



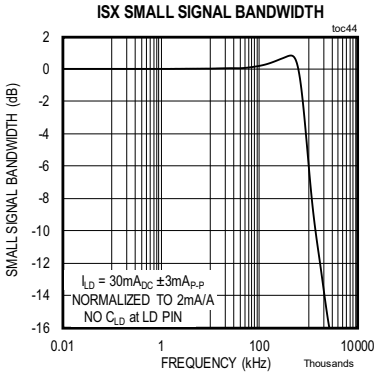
POWER-DOWN TIME
(ILD = 300mA, ISH SELECTED)



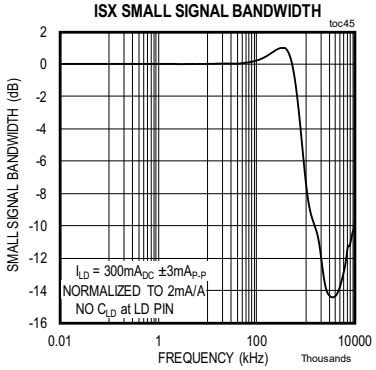
ISX SMALL SIGNAL BANDWIDTH



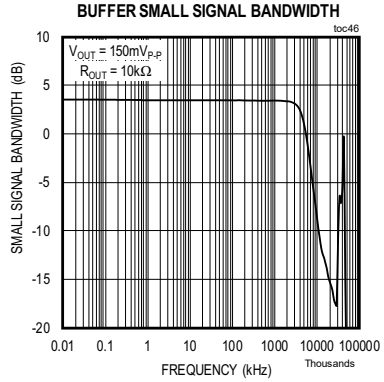
ISX SMALL SIGNAL BANDWIDTH



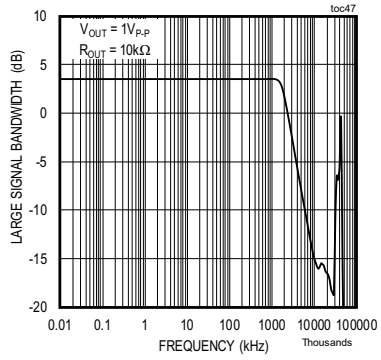
ISX SMALL SIGNAL BANDWIDTH



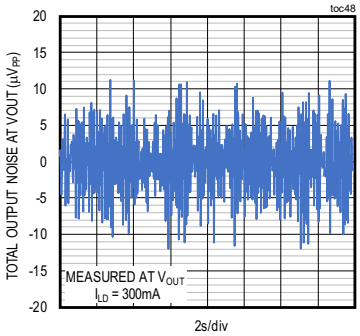
BUFFER SMALL SIGNAL BANDWIDTH



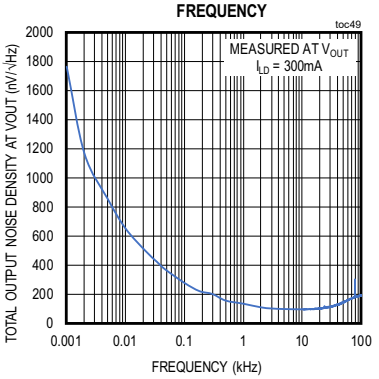
BUFFER LARGE SIGNAL BANDWIDTH



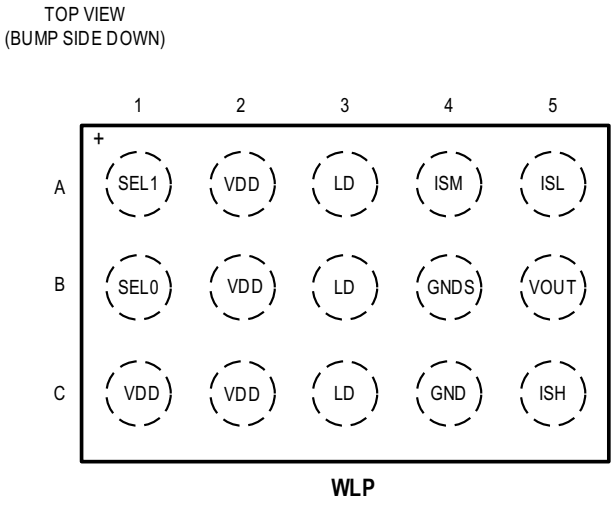
0.1 TO 10 Hz PEAK TO PEAK
TOTAL OUTPUT NOISE



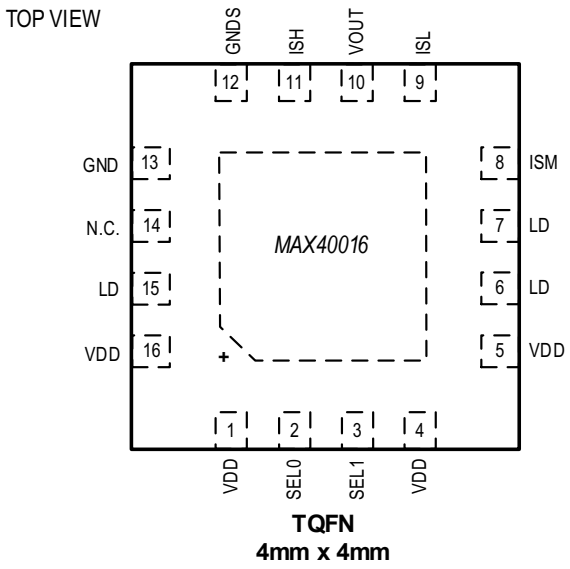
TOTAL OUTPUT VOLTAGE NOISE DENSITY vs.
FREQUENCY



Pin Configuration



WLP



TQFN
4mm x 4mm

Pin Description

PIN		NAME	FUNCTION
WLP	TQFN		
C1, A2, B2, C2	1, 4, 5, 16	V_{DD}	Device V_{DD} Supply and Measured Current Input. Bypass V_{DD} to GND with a 0.1µF and a 10µF ceramic capacitors in parallel as close to the device as possible.
A3, B3, C3	6, 7, 15	LD	Measured Current Output. Connect LD to the load side. Bypass LD to GND with a 10µF ceramic capacitor.
C5	11	ISH*	High Current Range Output. Connect a resistor from ISH to GND to scale the V_{OUT} range.
A4	8	ISM*	Middle Current Range Output. Connect a resistor from ISM to GND to scale the V_{OUT} range.
A5	9	ISL*	Low Current Range Output. Connect a resistor from ISL to GND to scale the V_{OUT} range.
B4	12	GNDS	Ground. Return of the output amplifier's gain setting network. Connect GNDS to GND.
C4	13	GND	Circuit Ground. All signals are referenced to GND.
B1	2	SEL0	Logic Selection Input 0 (see Table 1).
A1	3	SEL1	Logic Selection Input 1 (see Table 1).
B5	10	V_{OUT}	Amplifier Output Voltage. V_{OUT} is proportional to the VDD to ILD current. The scaling factor depends on the resistor values on the ISL, ISM, and ISH inputs.
—	14	N.C.	No Connect. Internally not connected.
—	EP	EP	Exposed Pad. Internally connected to GND. Connect to a large ground plane to maximize thermal performance. Do not use EP as the only ground connection.

**ISL, ISM, and ISH are electrically identical and named to differentiate among the three selectable outputs. Each output when selected is able to support the full-scale sense current range.*

Detailed Description

The MAX40016 CSA contains an integrated current-sensing element saving the space and cost of an external sense resistor. Having an integrated sense element has the extra advantage that the entire current measuring path can be factory trimmed, saving the user from having to calibrate independent sense resistors and CSAs.

The CSA has a low power mode in which the current-sensing element remains on, but the output and internal circuitry are turned off to bring the total supply current well below 10µA. In this mode, the pass element is turned fully on and will therefore drop slightly less voltage than while it is measuring current. Low power mode is selected by applying a logic-low to both SEL0 and SEL1 (see Table 1).

Three multiplexed scaling outputs from the wide range CSA allow the use of different scaling resistors so that a 12-bit ADC can be sufficient with simple resistor range selection. If only one output is used, an ADC with at least 15 bits of resolution will be needed to realize the full dynamic range of the CSA. See the applications section for details. Each of the scaled outputs are available as a voltage from the V_{OUT} pin.

The V_{OUT} amplifier output is capable of driving a wide range of ADCs and has a gain of 1.5V/V to provide a full-scale of 1.5V. Most of the values shown in this document are for a full-scale output of 1.5V, suited for 1.8V controllers with embedded 10 to 16-bit ADCs.

The MAX40016 senses from less than 300µA to greater than 3A current range. The output maintains less than 5% error specification over a 10,000:1 ratio. In theory, this requires an ADC with a resolution exceeding 13 bits to realize its full dynamic range. While such ADCs are readily available, the system microcontroller already has an embedded 12-bit ADC in many cases.

The three multiplexed scaling current outputs from MAX40016 allow the span to be divided into three ranges that are well within a lower-resolution ADC's capability. Note that it is the same current that is switched to one of the three outputs at a time. The ISH, ISM and ISL pin names are mainly to indicate which output pin is selected. The MAX40016 has its ranges selected using the SEL0 and SEL1 pins. See *Current Sense Range Selection (SEL0, SEL1)* section and (Table 1) for all the modes.

Scaling Resistors

The multiplexed scaling resistors' values (R_{ISH}, R_{ISM}, R_{ISL}) should be chosen to suit the ADC's full-scale, usually defined by its reference voltage (V_{REF}). Care should be taken to account for all tolerances to avoid overloading the ADC. The typical current from the MAX40016's ISL, or ISM, or ISH pin is specified as 2mA/A. The internal amplifier has a gain of 1.5V/V. Resistors of 0.1% are readily available and so the nominal resistance value is given by:

$$R_{ISX} = \frac{VREF / 1.5}{\left(I_{FS} \times 0.002\right)} (\Omega)$$

The R_{ISX} determined from the above equation, where the voltage across the scaling resistor should be limited to 1V, which corresponds to 1.5V full-scale after the amplifier. The closest E192 available value is 167Ω which gives very little over-current margin. A 160Ω R_{ISX} value offers a little more margin towards a conservative design.

Current Sense Range Selection (SEL0, SEL1)

SEL0 and SEL1 are digital inputs decoded to control the mirroring of the sense current on the V_{DD} to LD path to one of three scaled current outputs (ISH, ISM, or ISL), as shown in Table 1. When both SEL0 and SEL1 are at logic 0, the MAX40016 enters its low power operating mode.

Table 1. Current Sense Range Selection

SEL0	SEL1	OPERATING MODE/RANGE
0	0	Low Power Mode is Enabled. V_{OUT} is high impedance. In low power mode, the current-sensing element still passes current just as an external sense resistor would. There is no capability to turn off the current.
0	1	Middle Current Sense Range (ISM) is Enabled. The resistor R_{ISM} connected at this current output terminal defines the full-scale voltage of 1V to the internal amplifier.
1	0	Low Current Sense Range (ISL) is Enabled. The resistor R_{ISL} connected at this current output terminal defines the full-scale voltage of 1V to the internal amplifier.
1	1	High Current Sense Range (ISH) is Enabled. The resistor R_{ISH} connected at this current output terminal defines the full-scale voltage of 1V to the internal amplifier.

Note: *ISL, ISM, ISH can support all current range from low end to high end. The only difference is that they are selected by different SEL0/SEL1 combination.*

Low Power Mode

The MAX40016 has a low power mode that is activated by pulling both SEL0 and SEL1 low. In this mode, all of the internal circuitry is shut down to save power. The output amplifier is placed in a high impedance state to allow multiplexing of the output line with another MAX40016 for example. In low power mode, the current-sensing element still passes current just as an external sense resistor would. There is no capability to turn off the current.

ISX Residual Current

When at no load current (I_{LD} = 0), there is a small internal residual current at ISX pin due to the internal current mirror block mechanism. This residual current is not an offset current and should not have effect when there is a load current being sensed. Refer to *Typical Operating Characteristics* for the typical information of this residual current over the the temperature range and V_{DD} supply voltage range.

Device Power Up

Initially, the MAX40016 powers up in low power mode, regardless of the state of SEL0 and SEL1. After the power-up delay time (100µs), the part reverts to the mode selected by SEL0 and SEL1.

Applications Information

ESD Clamps

The diagram shows the internal ESD clamping diodes that protect the MAX40016 against electrostatic discharge.

Power Supplies and Bypassing

The MAX40016 operates from single supply voltage +2.5V to +5.5V. The V_{DD} supply input is also the measured current input terminal. Pay extra attention to bypassing and grounding the MAX40016. Peak supply and measured output currents may exceed 3A when the load side experiences large current transients with large external capacitive loads. Supply drops and ground shifts may degrade the device performance. Ground shifts due to insufficient device grounding may also disturb other circuits sharing the same AC ground return path. Any series inductance in the V_{DD}, LD and/or GND paths can cause oscillations due to the very high di/dt when switching the MAX40016 with any capacitive load. Bypass V_{DD} supply to ground with a 0.1µF in parallel with a 10µF ceramic capacitors as close as possible to the device. Bypass the measured current output, LD terminal, with a 10µF ceramic capacitor or larger depending on the sensing load current, additional bypassing may be needed to keep the device stable during large load output transitions.

Layout Guidelines

Due to the high currents that may flow through the integrated sensing element based on the application, take care to eliminate solder and parasitic trace resistance from causing errors. Using thicker copper in the PCB construction for these high currents is recommended. Use of Kelvin (force and sense) PCB layout techniques or use of a multilayer PCB with separate ground, power supply and load planes is recommended for noisy digital environments (see the MAX40016EVKIT# data sheet for a layout example). Keep digital signals far away from the sensitive analog inputs. Unshielded long traces at the input and output sense terminals of the device can degrade performance due to noise pick-up.

Application Information

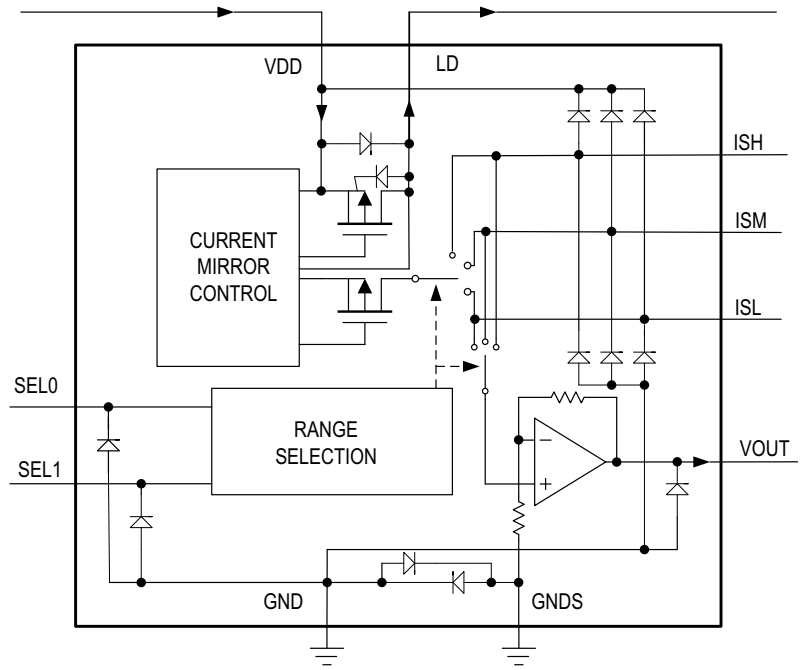


Figure 1. Functional Diagram Showing ESD Clamps

Typical Application Circuits

When the chosen ADC has sufficient resolution to handle the MAX40016 full dynamic range (4-decade of sensing range), only the R_{ISH} resistor is required (Figure 2). For a full-scale of 3A the value of R_{ISH} is 160Ω for a 1V full-scale at the ISH pin, which corresponds to 1.5V output at V_{OUT}.

Determining the nominal value of R_{ISH}:

The amplifier has a nominal gain of 1.5V/V and the output full-scale voltage is optimized to be 1.5V. So the full-scale voltage across R_{ISH} is 1V.

The current division factor F_{DV} (from sensing channel to ISH) is 500 (i.e., 2mA/A).

The full-scale sensed current (I_{FS}) is divided by F_{DV} and the divided current flows through R_{ISH}.

Thus, $I_{RSH} = I_{FS}/F_{DV}$, giving $R_{ISH} = F_{DV}/I_{FS}$.

Example #1: Using a MAX11214 (24-bit at 64ksps).

The high sampling rate of the MAX11214 renders an anti-aliasing filter unnecessary. Only the R_{ISH} resistor is needed to define the gain and the internal programmable gain amplifier inside the ADC allows the selection of reference voltages to match with the 1.5V full-scale from MAX40016. Alternatively, the MAX40016's output buffer can be bypassed and the ADC can be connected directly to the ISH pin, to read the voltage across R_{ISH} directly (see Figure 3). If the PCB layout requires a long distance between the MAX40016 and the ADC, the current output from ISH should be run across the PCB and the R_{ISH} terminating resistor placed as close as possible to the ADC's input. This helps reduce errors caused by voltage drops across the PCB.

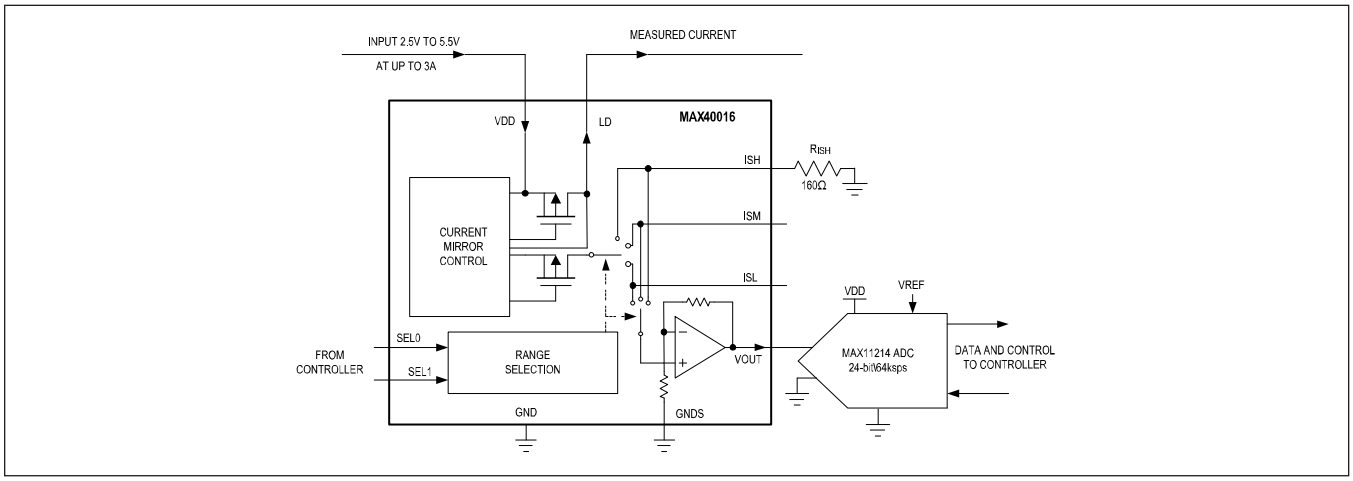


Figure 2. Using the MAX40016 with MAX11214 24-Bit, 64ksps ADC (Single Scaling Resistor with Internal Buffer)

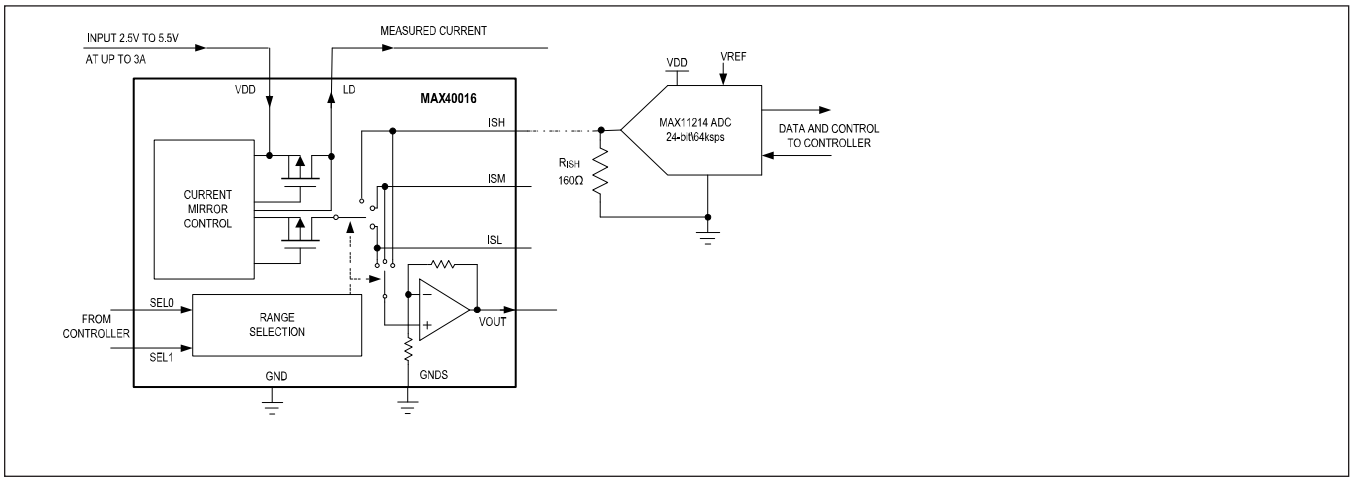


Figure 3. Using the MAX40016 with MAX11214 24-Bit, 64ksps ADC (Single Scaling Resistor without Internal Buffer)

Implementation with Lower Resolution ADCs

When two or three ranges are required, as in the case of a 10-bit to 12-bit ADC, the higher range resistor (R_{ISH}) is calculated as described above. Calculating R_{ISM} and or R_{ISL} follows the same method with the only difference being the full-scale current is now the lower-range full-scale current. Exactly where it is optimum to arrange this current will depend on the system. Typically splitting the ranges in the region of 30:1 is suitable for most applications. Using R_{ISH} = 160Ω, R_{ISM} = 5.3kΩ, and R_{ISL} = 160kΩ to split the range up equally (Figure 4). However, this range transition value can be chosen such that the most commonly expected readings would have the better resolution. Selecting too low a transition point leads to more, presumably unnecessary, quantization noise in the higher range.

Example #2: Using an Embedded 12-bit ADC

The following example uses a typical moderate-speed SAR ADC with a 25pF sampling capacitor (CIN) and 1.5us acquisition time (T_{ACQ}).

In the idle state, the ADC's input impedance is high. When the ADC begins its acquisition phase the input impedance becomes C_{IN} in series with R_{IN}. The amplifier is thus presented with a transient change in load impedance. Adding an RC network (R_F and C_F), as shown in Figure 4, serves to reduce the load transient seen by the amplifier.

Begin by selecting the value of C_F which serves as a "charge reservoir" for the ADC's input stage. When the ADC begins its acquisition phase, C_F should be able to provide the charge required by the internal sampling capacitor (C_{IN}) without excessive droop. A sufficiently large C_F therefore reduces the load transient seen by the amplifier. It is generally appropriate to target between 2% and 5% droop at ADC input. This then results in a value of C_F that is between 20 and 50 times the value of C_{IN}. For the capacitor type use a C0G (or NP0) ceramic chip capacitor and place it between ADC input and the ground plane, as close as possible to the ADC. In this example, with C_{IN} = 25pF, the external capacitance value should be between 500pF and 1,250pF and a good choice is a 1.2nF C0G capacitor.

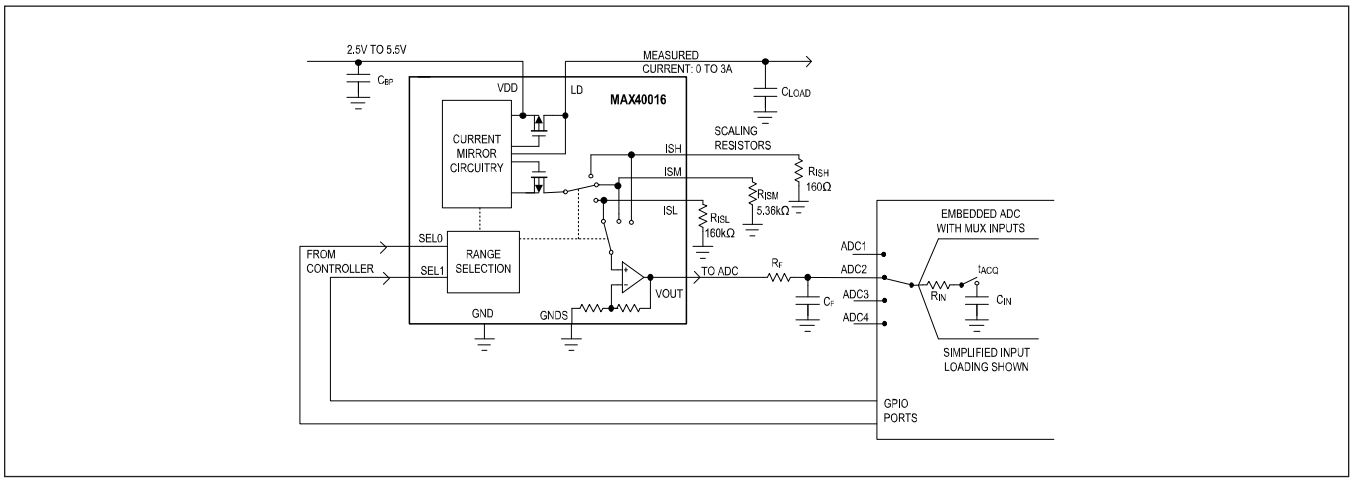


Figure 4. Using the MAX40016 with an Embedded 12-Bit ADC

The next step is to choose the value of R_F. Two characteristics of the ADC should be considered when calculating R_F: the acquisition time of converter (T_{ACQ}) and the ADC sampling capacitance (C_{IN}). In addition, the RC network will require several time constants to settle once the sampling switch is closed. If the ADC's resolution is 12 bits, and the input needs to settle to less than 0.5LSB, then 9 time constants will be required. Because settling must occur during the acquisition period, $R_F * C_F * 9$ must be less than or equal to T_{ACQ} if the error introduced by the external RC network is to be less than 0.5LSB. This results in a value of 139Ω or less for R_F.

Finally, to ensure stability, the cutoff frequency of the R_F-C_F low-pass filter should be smaller than the gain-bandwidth product of the amplifier. Choosing 130Ω and 1.2nF yields about 1MHz which is smaller than the 1.5MHz gain-bandwidth product of the amplifier. Note that Voltage at ISH, ISM, ISL pins should not exceed 1.1V for proper operation (see *Input Voltage Range Under Amplifier* section of the Electrical Characteristics table).

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	TOP MARK
MAX40016ANL+T	-40°C to +125°C	15 WLP	+AAB
MAX40016ATE+T	-40°C to +125°C	16 TQFN	—

+Denotes a lead(Pb)-free/RoHS-compliant package.
T = Denotes tape-and-reel.

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	1/18	Initial release	—
1	8/18	Updated *Benefits and Features*, *Absolute Maximum Ratings, Package Information, Electrical Characteristics, Typical Operating Characteristics, Pin Description,* and *Ordering Information*	1, 3–5, 7–15, 22
2	11/18	Updated *General Description*, *Benefits and Features*, data sheet title, *Simplified Block Diagram, Typical Operating Characteristics* global conditions and graphs, and *Typical Application Circuits*	1, 2, 7, 14, 21

For pricing, delivery, and ordering information, please visit Maxim Integrated's online storefront at https://www.maximintegrated.com/en/storefront/storefront.html.

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