

## Temperature and Power Supply System Monitors

Check for Samples: [TMP512](#), [TMP513](#)

### FEATURES

- $\pm 1^{\circ}\text{C}$  REMOTE DIODE SENSORS
- $\pm 1^{\circ}\text{C}$  LOCAL TEMPERATURE SENSOR
- SERIES RESISTANCE CANCELLATION
- n-FACTOR CORRECTION
- TEMPERATURE ALERT FUNCTION
- AVERAGING
- 12-BIT RESOLUTION
- DIODE FAULT DETECTION
- SENSES BUS VOLTAGES FROM 0V TO +26V
- REPORTS CURRENT IN AMPS, VOLTAGE IN VOLTS AND POWER IN WATTS
- HIGH ACCURACY: 1% MAX OVER TEMP
- WATCHDOG LIMITS:
  - Upper Over-Limit
  - Lower Under-Limit

### APPLICATIONS

- DESKTOP AND NOTEBOOK COMPUTERS
- SERVERS
- INDUSTRIAL CONTROLLERS
- CENTRAL OFFICE TELECOM EQUIPMENT
- LCD/ DLP®/LCOS PROJECTORS
- STORAGE AREA NETWORKS (SAN)

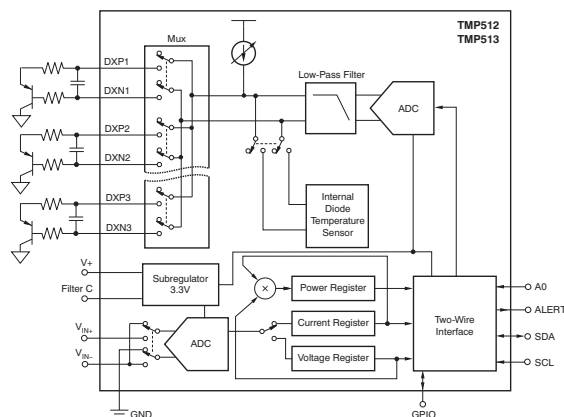
### DESCRIPTION

The TMP512 (dual-channel) and TMP513 (triple-channel) are system monitors that include remote sensors, a local temperature sensor, and a high-side current shunt monitor. These system monitors have the capability of measuring remote temperatures, on-chip temperatures, and system voltage/power/current consumption.

The remote temperature sensor diode-connected transistors are typically low-cost, NPN- or PNP-type transistors or diodes that are an integral part of microcontrollers, microprocessors, or FPGAs. Remote accuracy is  $\pm 1^{\circ}\text{C}$  for multiple IC manufacturers, with no calibration needed. The two-wire serial interface accepts SMBus™ or two-wire write and read commands.

The onboard current shunt monitor is a high-side current shunt and power monitor. It monitors both the shunt drop and supply voltage. A programmable calibration value (along with the TMP512/TMP513 internal digital multiplier) enables direct readout in amps; an additional multiplication calculates power in watts. The TMP512 and TMP513 both feature two separate onboard watchdog capabilities: an over-limit comparator and a lower-limit comparator.

These devices use a single +3V to +26V supply, drawing a maximum of 1.4mA of supply current, and they are specified for operation from  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .



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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### PACKAGE INFORMATION<sup>(1)</sup>

| PRODUCT | PACKAGE-LEAD          | PACKAGE DESIGNATOR | PACKAGE MARKING |
|---------|-----------------------|--------------------|-----------------|
| TMP512  | SO-14                 | D                  | TMP512A         |
| TMP513  | SO-16                 | D                  | TMP513A         |
|         | QFN-16 <sup>(2)</sup> | RSA                | TMP513A         |

(1) For the most current package and ordering information see the Package Option Addendum at the end of this document, or visit the [TMP512/TMP513 product folder](http://www.ti.com) at [www.ti.com](http://www.ti.com).

(2) Product preview device.

### ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

Over operating free-air temperature range (unless otherwise noted).

|                                                    |                                                                       | TMP512, TMP513        | UNIT |
|----------------------------------------------------|-----------------------------------------------------------------------|-----------------------|------|
| Supply Voltage, V+                                 |                                                                       | 26                    | V    |
| Filter C                                           | Voltage                                                               | GND – 0.3 to +6       | V    |
|                                                    | Current                                                               | 10                    | mA   |
| Analog Inputs, V <sub>IN+</sub> , V <sub>IN–</sub> | Differential (V <sub>IN+</sub> ) – (V <sub>IN–</sub> ) <sup>(2)</sup> | –26 to +26            | V    |
|                                                    | Common-Mode                                                           | –0.3 to +26           | V    |
| Open-Drain Digital Outputs                         |                                                                       | GND – 0.3 to +6       | V    |
| GPIO, DXP, DXN                                     |                                                                       | GND – 0.3 to V+ + 0.3 | V    |
| Input Current Into Any Pin                         |                                                                       | 5                     | mA   |
| Open-Drain Digital Output Current                  |                                                                       | 10                    | mA   |
| Storage Temperature                                |                                                                       | –65 to +150           | °C   |
| Junction Temperature                               |                                                                       | +150                  | °C   |
| ESD Ratings                                        | Human Body Model (HBM)                                                | 2000                  | V    |
|                                                    | Charged-Device Model (CDM)                                            | 1000                  | V    |
|                                                    | Machine Model (MM)                                                    | 150                   | V    |

(1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.

(2) V<sub>IN+</sub> and V<sub>IN–</sub> may have a differential voltage of –26V to +26V; however, the voltage at these pins must not exceed the range –0.3V to +26V.

## THERMAL INFORMATION

| THERMAL METRIC <sup>(1)</sup> |                                                             | TMP512   | TMP513AID | TMP513AIRSAR<br>TMP513AIRSAT | UNITS |
|-------------------------------|-------------------------------------------------------------|----------|-----------|------------------------------|-------|
|                               |                                                             | D (SOIC) | D (SOIC)  | RSA                          |       |
|                               |                                                             | 14       | 16        | 16                           |       |
| $\theta_{JA}$                 | Junction-to-ambient thermal resistance <sup>(2)</sup>       | 91.1     | 77.6      | 44.8                         | °C/W  |
| $\theta_{JC(top)}$            | Junction-to-case(top) thermal resistance <sup>(3)</sup>     | 10.6     | 55.0      | 43.8                         |       |
| $\theta_{JB}$                 | Junction-to-board thermal resistance <sup>(4)</sup>         | 40.3     | 49.9      | 14.7                         |       |
| $\psi_{JT}$                   | Junction-to-top characterization parameter <sup>(5)</sup>   | 49.1     | 3.5       | 0.4                          |       |
| $\psi_{JB}$                   | Junction-to-board characterization parameter <sup>(6)</sup> | 47.5     | 32.2      | 14.5                         |       |
| $\theta_{JC(bottom)}$         | Junction-to-case(bottom) thermal resistance <sup>(7)</sup>  | n/a      | n/a       | 2.6                          |       |

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).
- (2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
- (3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDEC-standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
- (4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
- (5) The junction-to-top characterization parameter,  $\psi_{JT}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).
- (6) The junction-to-board characterization parameter,  $\psi_{JB}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).
- (7) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.

## ELECTRICAL CHARACTERISTICS: V+ = +12V

**Boldface** limits apply over the specified temperature range,  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

At  $T_A = +25^{\circ}\text{C}$ ,  $V_+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG}^{(1)} = 1$ , unless otherwise noted.

| PARAMETER                                        |                      | TEST CONDITIONS              | TMP512, TMP513                                  |           |      | UNIT     |
|--------------------------------------------------|----------------------|------------------------------|-------------------------------------------------|-----------|------|----------|
|                                                  |                      |                              | MIN                                             | TYP       | MAX  |          |
| INPUT                                            |                      |                              |                                                 |           |      |          |
| Current Sense (Input) Voltage Range              |                      | PGA = ÷ 1                    | 0                                               |           | ±40  | mV       |
|                                                  |                      | PGA = ÷ 2                    | 0                                               |           | ±80  | mV       |
|                                                  |                      | PGA = ÷ 4                    | 0                                               |           | ±160 | mV       |
|                                                  |                      | PGA = ÷ 8                    | 0                                               |           | ±320 | mV       |
| Bus Voltage (Input Voltage) Range <sup>(2)</sup> |                      | BRNG = 0                     | 0                                               |           | 16   | V        |
|                                                  |                      | BRNG = 1                     | 0                                               |           | 32   | V        |
| Common-Mode Rejection                            | CMRR                 | V <sub>IN+</sub> = 0V to 26V | 100                                             | 120       |      | dB       |
| Offset Voltage, RTI <sup>(3)</sup>               | V <sub>OS</sub>      | PGA = ÷ 1                    |                                                 | ±10       | ±100 | μV       |
|                                                  |                      | PGA = ÷ 2                    |                                                 | ±20       | ±125 | μV       |
|                                                  |                      | PGA = ÷ 4                    |                                                 | ±30       | ±150 | μV       |
|                                                  |                      | PGA = ÷ 8                    |                                                 | ±40       | ±200 | μV       |
|                                                  | vs Temperature       |                              |                                                 | 0.2       |      | μV/°C    |
|                                                  | vs Power Supply      | PSRR                         | V+ = 3V to 5.5V, Configuration 3 <sup>(4)</sup> | 10        |      | μV/V     |
|                                                  |                      |                              | V+ = 4.5V to 26V, subregulator supply           | 0.1       |      | μV/V     |
| Current Sense Gain Error                         |                      |                              |                                                 | ±0.04     |      | %        |
|                                                  | vs Temperature       |                              |                                                 | 0.0025    |      | %        |
| Input Impedance                                  |                      | Active Mode                  |                                                 |           |      |          |
|                                                  | V <sub>IN+</sub> Pin |                              |                                                 | 20        |      | μA       |
|                                                  | V <sub>IN-</sub> Pin |                              |                                                 | 20    320 |      | μA    kΩ |
| Input Leakage                                    |                      | Power-Down Mode              |                                                 |           |      |          |
|                                                  | V <sub>IN+</sub> Pin |                              |                                                 | 0.1       | 0.5  | μA       |
|                                                  | V <sub>IN-</sub> Pin |                              |                                                 | 0.1       | 0.5  | μA       |
| DC ACCURACY                                      |                      |                              |                                                 |           |      |          |
| ADC Basic Resolution                             |                      |                              |                                                 | 12        |      | Bits     |
| 1 LSB Step Size                                  |                      |                              |                                                 |           |      |          |
|                                                  | Shunt Voltage        |                              |                                                 | 10        |      | μV       |
|                                                  | Bus Voltage          |                              |                                                 | 4         |      | mV       |
| Current Measurement Error                        |                      |                              |                                                 | ±0.2      | ±0.5 | %        |
|                                                  | over Temperature     |                              |                                                 |           | ±1   | %        |
| Bus Voltage Measurement Error                    |                      |                              |                                                 | ±0.2      | ±0.5 | %        |
|                                                  | over Temperature     |                              |                                                 |           | ±1   | %        |
| Differential Nonlinearity                        |                      |                              |                                                 | ±0.1      |      | LSB      |
| ADC TIMING                                       |                      |                              |                                                 |           |      |          |
| ADC Conversion Time                              |                      | 12-Bit                       |                                                 | 665       | 733  | μs       |
|                                                  |                      | 11-Bit                       |                                                 | 345       | 380  | μs       |
|                                                  |                      | 10-Bit                       |                                                 | 185       | 204  | μs       |
|                                                  |                      | 9-Bit                        |                                                 | 105       | 117  | μs       |

(1) BRNG is bit 13 of [Configuration Register 1](#).

(2) This parameter only expresses the full-scale range of the ADC scaling. In no event should more than 26V be applied to this device.

(3) Referred-to-input (RTI).

(4) See [Subregulator](#) section.

**ELECTRICAL CHARACTERISTICS: V+ = +12V (continued)**

**Boldface** limits apply over the specified temperature range,  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

At  $T_A = +25^{\circ}\text{C}$ ,  $V+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG}^{(1)} = 1$ , unless otherwise noted.

| PARAMETER                                     |                   | TEST CONDITIONS           | TMP512, TMP513                                                                           |     |       | UNIT |      |
|-----------------------------------------------|-------------------|---------------------------|------------------------------------------------------------------------------------------|-----|-------|------|------|
|                                               |                   |                           | MIN                                                                                      | TYP | MAX   |      |      |
| TEMPERATURE ERROR                             |                   |                           |                                                                                          |     |       |      |      |
| Local Temperature Sensor                      |                   | TE <sub>LOCAL</sub>       | T <sub>A</sub> = −40°C to +125°C                                                         |     | ±1.25 | ±2.5 | °C   |
|                                               |                   |                           | T <sub>A</sub> = +15°C to +85°C, V <sub>+</sub> = 12V                                    |     | ±0.25 | ±1   | °C   |
| Remote Temperature Sensor <sup>(5)</sup>      |                   | TE <sub>REMOTE</sub>      | T <sub>A</sub> = +15°C to +85°C, T <sub>D</sub> = −40°C to +150°C, V <sub>+</sub> = 12V  |     | ±0.25 | ±1   | °C   |
|                                               |                   |                           | T <sub>A</sub> = −40°C to +100°C, T <sub>D</sub> = −40°C to +150°C, V <sub>+</sub> = 12V |     | ±1    | ±3   | °C   |
|                                               |                   |                           | T <sub>A</sub> = −40°C to +125°C, T <sub>D</sub> = −40°C to +150°C                       |     | ±3    | ±5   | °C   |
|                                               | vs Supply, Local  |                           | V <sub>+</sub> = 3V to 5.5V, Configuration 3 <sup>(6)</sup>                              |     | 0.2   | 0.5  | °C/V |
|                                               | vs Supply, Remote |                           | V <sub>+</sub> = 3V to 5.5V, Configuration 3 <sup>(6)</sup>                              |     | 0.2   | 0.5  | °C/V |
|                                               |                   |                           | V <sub>+</sub> = 4.5V to 26V, subregulator supply                                        |     | 0.01  | 0.05 | °C/V |
| TEMPERATURE MEASUREMENT                       |                   |                           |                                                                                          |     |       |      |      |
| Conversion Time (per channel)                 |                   |                           | 100                                                                                      | 115 | 130   | ms   |      |
| Resolution                                    |                   |                           |                                                                                          |     |       |      |      |
| Local Temperature Sensor                      |                   |                           |                                                                                          | 13  |       | Bits |      |
| Remote Temperature Sensor                     |                   |                           |                                                                                          | 13  |       | Bits |      |
| Remote Sensor Source Currents                 |                   | Series Resistance 3kΩ max |                                                                                          |     |       |      |      |
| High                                          |                   |                           |                                                                                          | 120 |       | μA   |      |
| Medium High                                   |                   |                           |                                                                                          | 60  |       | μA   |      |
| Medium Low                                    |                   |                           |                                                                                          | 12  |       | μA   |      |
| Low                                           |                   |                           |                                                                                          | 6   |       | μA   |      |
| Default Non-Ideality Factor                   |                   | n                         | TMP512/12 Optimized Ideality Factor                                                      |     | 1.008 |      |      |
| SMBus                                         |                   |                           |                                                                                          |     |       |      |      |
| Logic Input High Voltage (SCL, SDA, GPIO, A0) |                   | V <sub>IH</sub>           |                                                                                          | 2.1 |       | V    |      |
| Logic Input Low Voltage (SCL, SDA, GPIO, A0)  |                   | V <sub>IL</sub>           |                                                                                          |     | 0.8   | V    |      |
| Hysteresis                                    |                   |                           |                                                                                          | 500 |       | mV   |      |
| SMBus Output Low Sink Current                 |                   |                           | 6                                                                                        |     |       | mA   |      |
| SDA Output Low Voltage                        |                   | V <sub>OL</sub>           | I <sub>OUT</sub> = 6mA                                                                   |     | 0.15  | 0.4  | V    |
| Logic Input Current                           |                   |                           | 0 ≤ V <sub>IN</sub> ≤ 6V                                                                 | −1  |       | 1    | μA   |
| SMBus Input Capacitance (SCL, SDA, GPIO, A0)  |                   |                           |                                                                                          |     | 3     |      | pF   |
| SMBus Clock Frequency                         |                   |                           |                                                                                          |     |       | 3.4  | MHz  |
| SMBus Timeout <sup>(7)</sup>                  |                   |                           |                                                                                          | 25  | 30    | 35   | ms   |
| SCL Falling Edge to SDA Valid Time            |                   |                           |                                                                                          |     |       | 1    | μs   |
| POWER SUPPLY                                  |                   |                           |                                                                                          |     |       |      |      |
| Specified Supply Range <sup>(6)</sup>         |                   | V <sub>+</sub>            |                                                                                          | +3  |       | +26  | V    |
| Quiescent Current                             |                   |                           |                                                                                          |     | 1     | 1.4  | mA   |
| Quiescent Current, Power-Down Mode            |                   |                           |                                                                                          |     | 55    | 100  | μA   |
| Power-On Reset Threshold                      |                   |                           |                                                                                          |     | 2     |      | V    |
| TEMPERATURE RANGE                             |                   |                           |                                                                                          |     |       |      |      |
| Specified Temperature Range                   |                   |                           |                                                                                          | −40 |       | +125 | °C   |

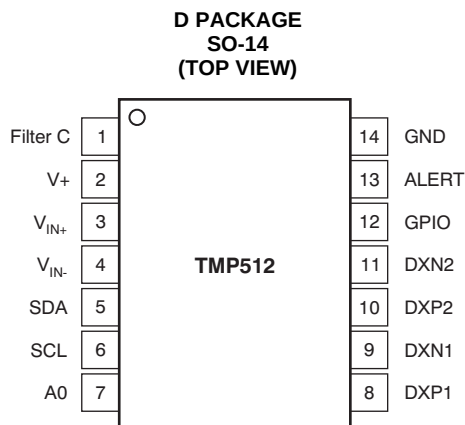
(5) Tested with one-shot measurements, and with less than  $5\Omega$  effective series resistance, and with  $100\text{pF}$  differential input capacitance.

(6) See [Subregulator](#) section.

(7) SMBus timeout in the TMP512/13 resets the interface any time SCL or SDA is low for over 28ms.

## PIN CONFIGURATIONS

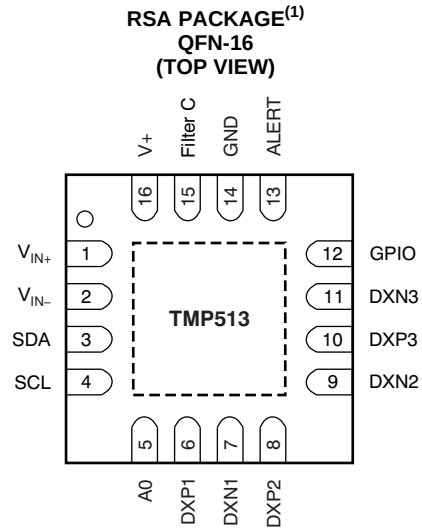
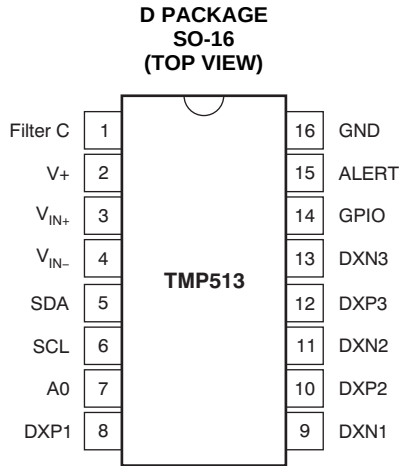
### TMP512



### TMP512: PIN DESCRIPTIONS

| PIN NO. | NAME             | DESCRIPTION                                                                                                                                                   |
|---------|------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1       | Filter C         | Subregulator output and filter capacitor pin.                                                                                                                 |
| 2       | V+               | Positive supply voltage (3V to 26V) See <a href="#">Figure 20</a> .                                                                                           |
| 3       | V <sub>IN+</sub> | Positive differential shunt voltage. Connect to positive side of shunt resistor.                                                                              |
| 4       | V <sub>IN-</sub> | Negative differential shunt voltage. Connect to negative side of shunt resistor. Bus voltage is measured from this pin to ground.                             |
| 5       | SDA              | Serial bus data line for SMBus, open-drain; requires pull-up resistor.                                                                                        |
| 6       | SCL              | Serial bus clock line for SMBus, open-drain; requires pull-up resistor.                                                                                       |
| 7       | A0               | Address pin                                                                                                                                                   |
| 8       | DXP1             | Channel 1 positive connection to remote temperature sensor.                                                                                                   |
| 9       | DXN1             | Channel 1 negative connection to remote temperature sensor.                                                                                                   |
| 10      | DXP2             | Channel 2 positive connection to remote temperature sensor.                                                                                                   |
| 11      | DXN2             | Channel 2 negative connection to remote temperature sensor.                                                                                                   |
| 12      | GPIO             | General-purpose, user-programmable input/output. Totem-pole output. Connect to ground or supply through a resistor if not used. Default state is as an input. |
| 13      | ALERT            | Open-drain SMBus alert output. Controlled in SMBus Alert Mask Register. Default state is disabled.                                                            |
| 14      | GND              | Ground                                                                                                                                                        |

## TMP513



(1) Product preview device.

### TMP513: PIN DESCRIPTIONS

| D PACKAGE<br>SO-16 | RSA<br>PACKAGE<br>QFN-16 | NAME             | DESCRIPTION                                                                                                                                                   |
|--------------------|--------------------------|------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1                  | 15                       | Filter C         | Subregulator output and filter capacitor pin.                                                                                                                 |
| 2                  | 16                       | V+               | Positive supply voltage (3V to 26V) See <a href="#">Figure 20</a> .                                                                                           |
| 3                  | 1                        | V <sub>IN+</sub> | Positive differential shunt voltage. Connect to positive side of shunt resistor.                                                                              |
| 4                  | 2                        | V <sub>IN-</sub> | Negative differential shunt voltage. Connect to negative side of shunt resistor. Bus voltage is measured from this pin to ground.                             |
| 5                  | 3                        | SDA              | Serial bus data line for SMBus, open-drain; requires pull-up resistor.                                                                                        |
| 6                  | 4                        | SCL              | Serial bus clock line for SMBus, open-drain; requires pull-up resistor.                                                                                       |
| 7                  | 5                        | A0               | Address pin                                                                                                                                                   |
| 8                  | 6                        | DXP1             | Channel 1 positive connection to remote temperature sensor.                                                                                                   |
| 9                  | 7                        | DXN1             | Channel 1 negative connection to remote temperature sensor.                                                                                                   |
| 10                 | 8                        | DXP2             | Channel 2 positive connection to remote temperature sensor.                                                                                                   |
| 11                 | 9                        | DXN2             | Channel 2 negative connection to remote temperature sensor.                                                                                                   |
| 12                 | 10                       | DXP3             | Channel 3 positive connection to remote temperature sensor.                                                                                                   |
| 13                 | 11                       | DXN3             | Channel 3 negative connection to remote temperature sensor.                                                                                                   |
| 14                 | 12                       | GPIO             | General-purpose, user-programmable input/output. Totem-pole output. Connect to ground or supply through a resistor if not used. Default state is as an input. |
| 15                 | 13                       | ALERT            | Open-drain SMBus alert output. Controlled in SMBus Alert Mask Register. Default state is disabled.                                                            |
| 16                 | 14                       | GND              | Ground                                                                                                                                                        |

## TYPICAL CHARACTERISTICS: V+ = +12V

At  $T_A = +25^\circ\text{C}$ ,  $V_+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG} = 1$ , unless otherwise noted.

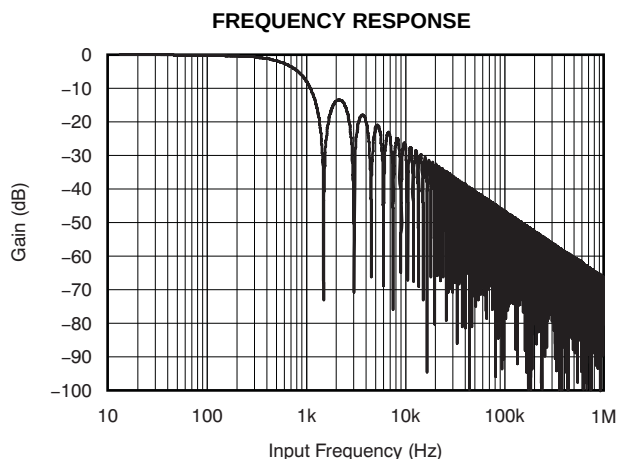


Figure 1.

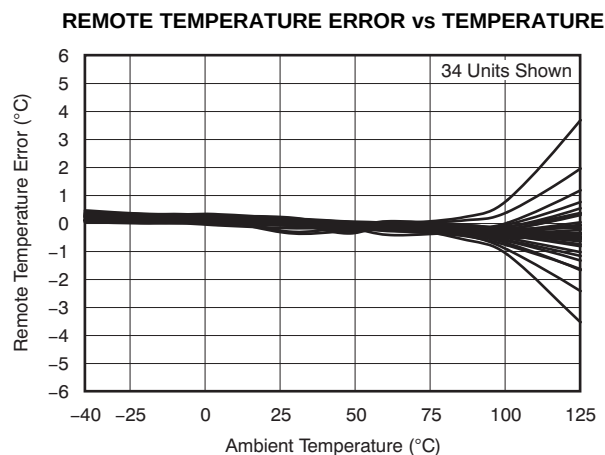


Figure 2.

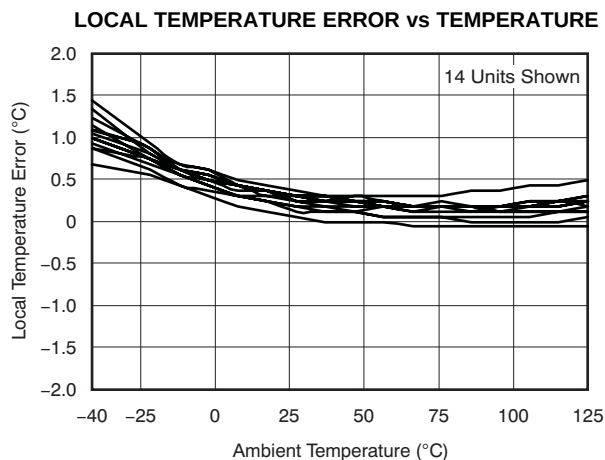


Figure 3.

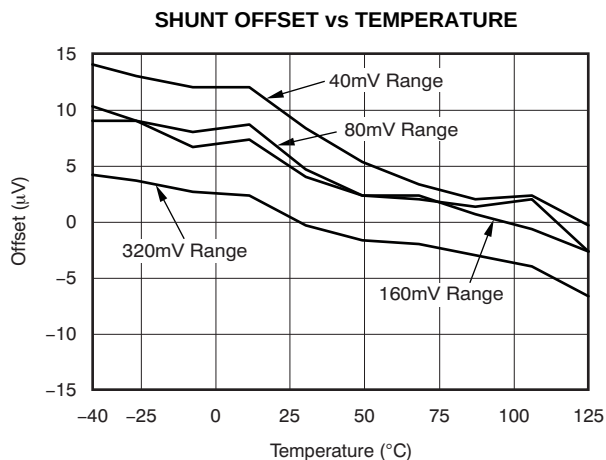


Figure 4.

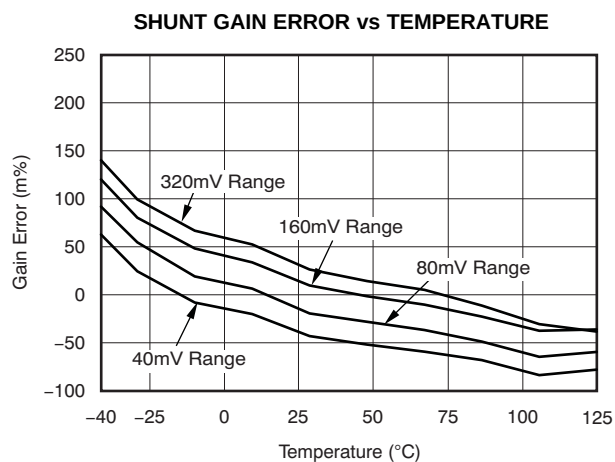


Figure 5.

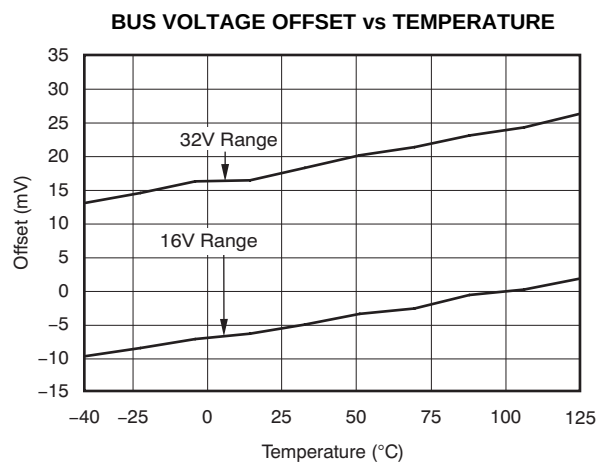


Figure 6.

## TYPICAL CHARACTERISTICS: $V_+ = +12\text{V}$ (continued)

At  $T_A = +25^\circ\text{C}$ ,  $V_+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG} = 1$ , unless otherwise noted.

**BUS GAIN ERROR vs TEMPERATURE**

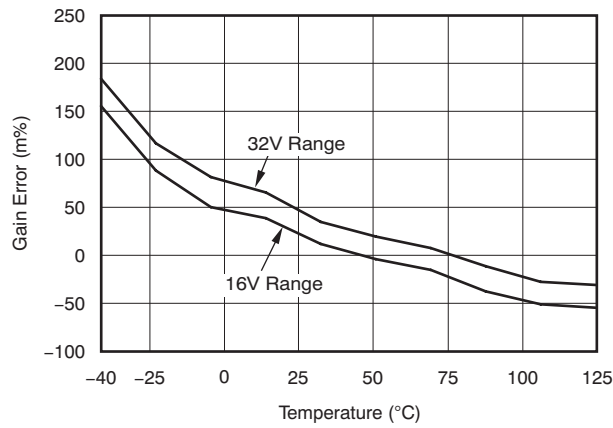


**Figure 7.**

**INTEGRAL NONLINEARITY vs INPUT VOLTAGE**

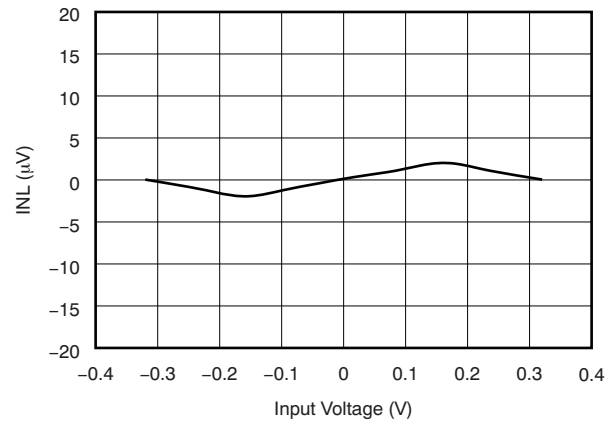


**Figure 8.**

**INPUT CURRENTS WITH LARGE DIFFERENTIAL VOLTAGES  
( $V_{\text{IN}+}$  at 12V, Sweep of  $V_{\text{IN}-}$ )**

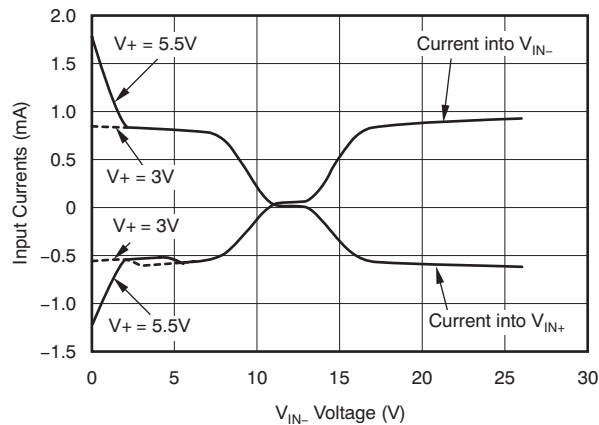


**Figure 9.**

**ACTIVE  $I_Q$  vs TEMPERATURE**

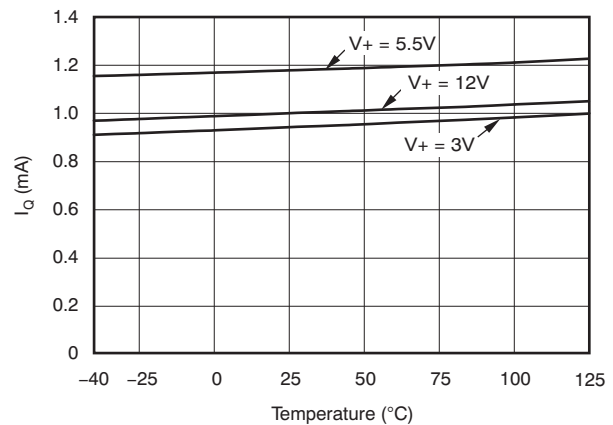


**Figure 10.**

## TYPICAL CHARACTERISTICS: V+ = +12V (continued)

At  $T_A = +25^\circ\text{C}$ ,  $V_+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG} = 1$ , unless otherwise noted.

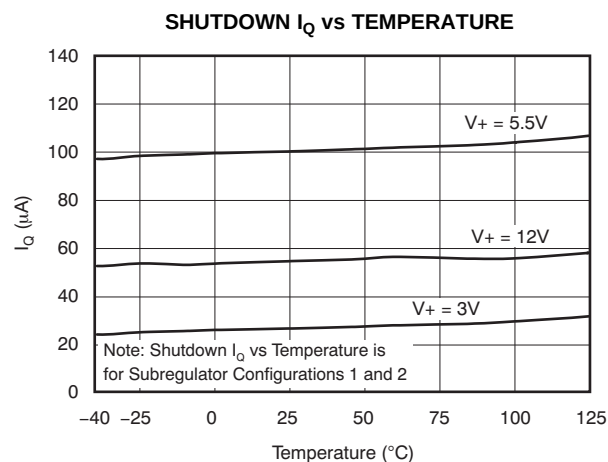


Figure 11.

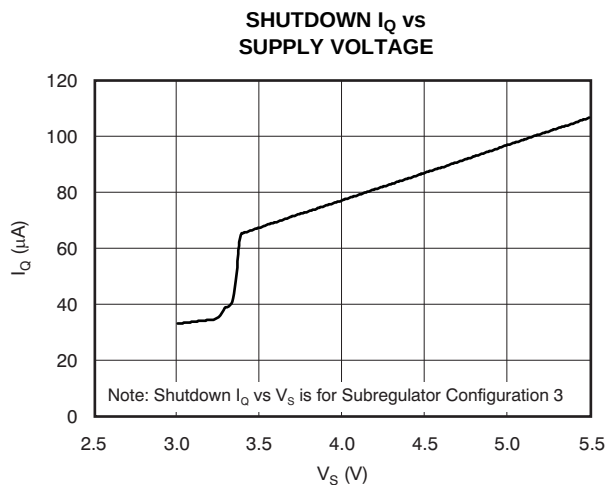


Figure 12.

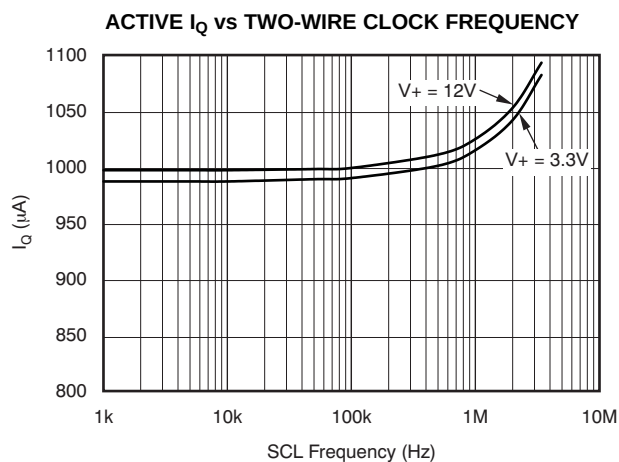


Figure 13.

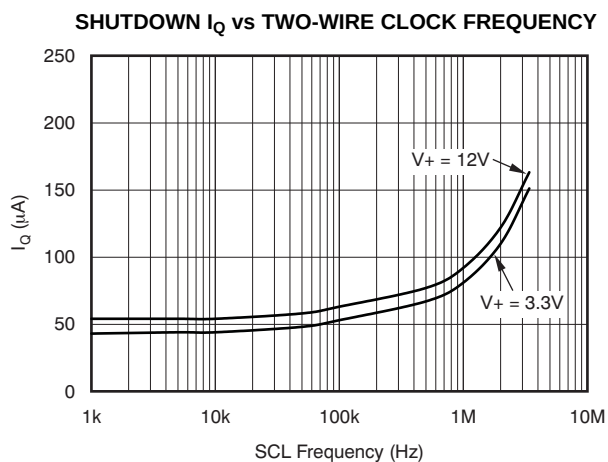


Figure 14.

## TYPICAL CHARACTERISTICS: V+ = +12V (continued)

At  $T_A = +25^\circ\text{C}$ ,  $V_+ = 12\text{V}$ ,  $V_{\text{SENSE}} = (V_{\text{IN}+} - V_{\text{IN}-}) = 32\text{mV}$ ,  $\text{PGA} = \div 1$ , and  $\text{BRNG} = 1$ , unless otherwise noted.

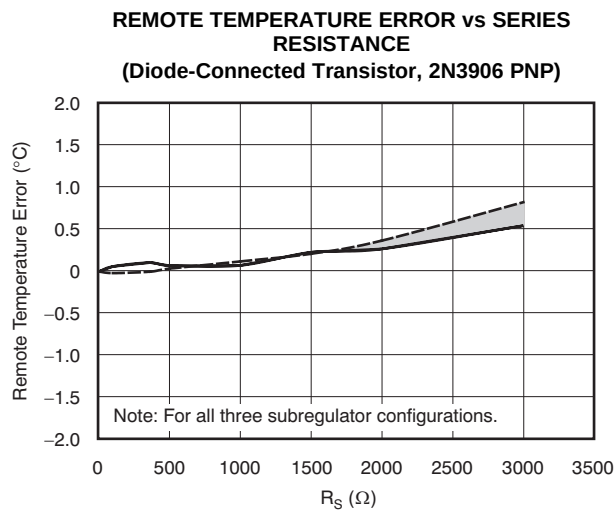


Figure 15.

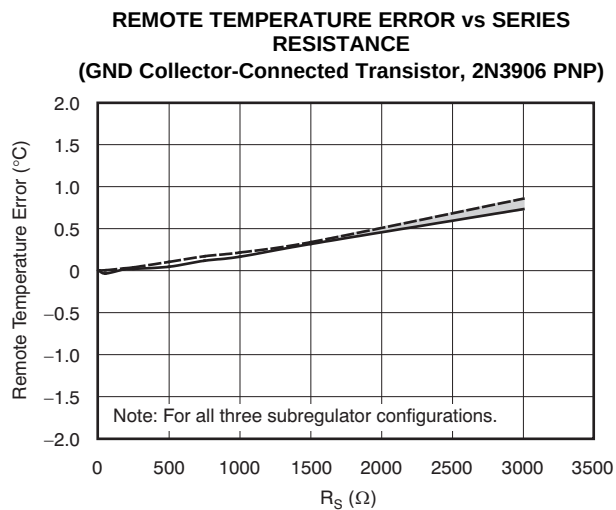


Figure 16.

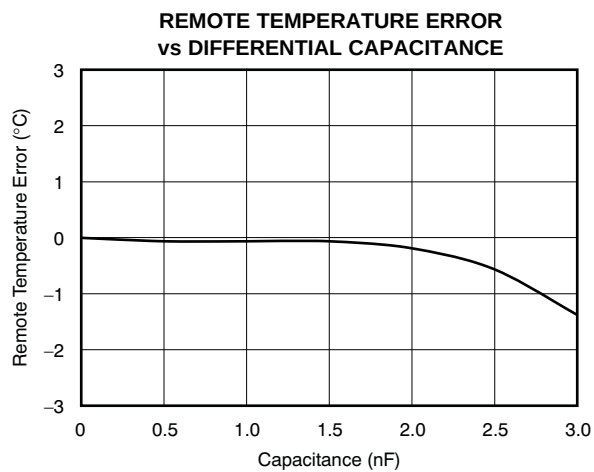


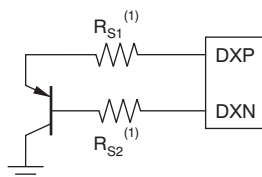
Figure 17.

## PARAMETRIC MEASUREMENT INFORMATION

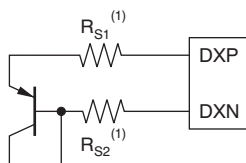
### TYPICAL CONNECTIONS

#### SERIES RESISTANCE CONFIGURATION

(a) GND Collector-Connected Transistor



(b) Diode-Connected Transistor

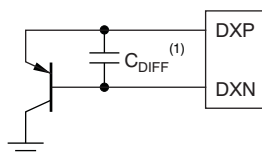


(1)  $R_{S1} + R_{S2}$  should be less than 1k $\Omega$ ; see [Filtering](#) section.

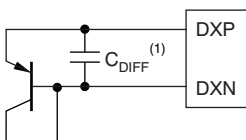
**Figure 18.**

#### DIFFERENTIAL CAPACITANCE CONFIGURATION

(a) GND Collector-Connected Transistor



(b) Diode-Connected Transistor



(1)  $C_{DIFF}$  should be less than 2200pF; see [Filtering](#) section.

**Figure 19.**

## APPLICATION INFORMATION

### DESCRIPTION

The TMP512/13 are digital temperature sensors with a digital current-shunt monitor that combine a local die temperature measurement channel and remote junction temperature measurement channels: two for the TMP512 and three for the TMP513. The TMP512/13 contain multiple registers for holding configuration information, temperature, and voltage measurement results. These devices provide digital current, voltage, and power readings necessary for accurate decision-making in precisely-controlled systems. Programmable registers allow flexible configuration for setting warning limits, measurement resolution, and continuous-versus-triggered operation. Detailed register information appears at the end of this data sheet, beginning with [Table 3](#).

For proper remote temperature sensing operation, the TMP512 requires transistors connected between DXP1 and DXN1 and between DXP2 and DXN2, and for the TMP513, between DXP3 and DXN3 as well. Unused channels on the TMP512/13 must be connected to GND.

The TMP512/13 offer compatibility with two-wire and SMBus interfaces. The two-wire and SMBus protocols are essentially compatible with each other. Two-wire is used throughout this data sheet, with SMBus being specified only when a difference

between the two systems is being addressed. Two bi-directional lines, SCL and SDA, connect the TMP512/13 to the bus. SDA is an open-drain connection. See [Figure 21](#) for a typical application circuit.

### SUBREGULATOR

The subregulator can be configured to three different modes of operation. Each mode has its advantage and limitation. [Figure 20](#) shows the three configuration arrangements. The minimum capacitance on the Filter C pin for Configurations 1 and 2 is 470nF. The minimum capacitance on the Filter C pin for Configuration 3 is 100nF.

Configuration 1 has  $V+$  and  $V_{IN+}$  tied together.  $V+$  supplies the subregulator, which in turn supplies the 3.3V to the Filter C pin and the internal die. With the  $V+$  supply range of 4.5V to 26V connected to the shunt voltage, the bus voltage range cannot go to zero and is limited to 4.5V to 26V.

Configuration 2 has  $V+$  to the subregulator without any other connections. Under this configuration, the bus voltage range can go from 0V to 26V, because it is not limited to 4.5V as in Configuration 1.

Configuration 3 has the subregulator  $V+$  and Filter C pins shorted together.  $V+$  is limited to 3V to 5.5V because the Filter C pin supplies the internal die; it cannot exceed this voltage range. The bus voltage range can go from 0V to 26V, because it is not limited to 4.5V as in Configuration 1.

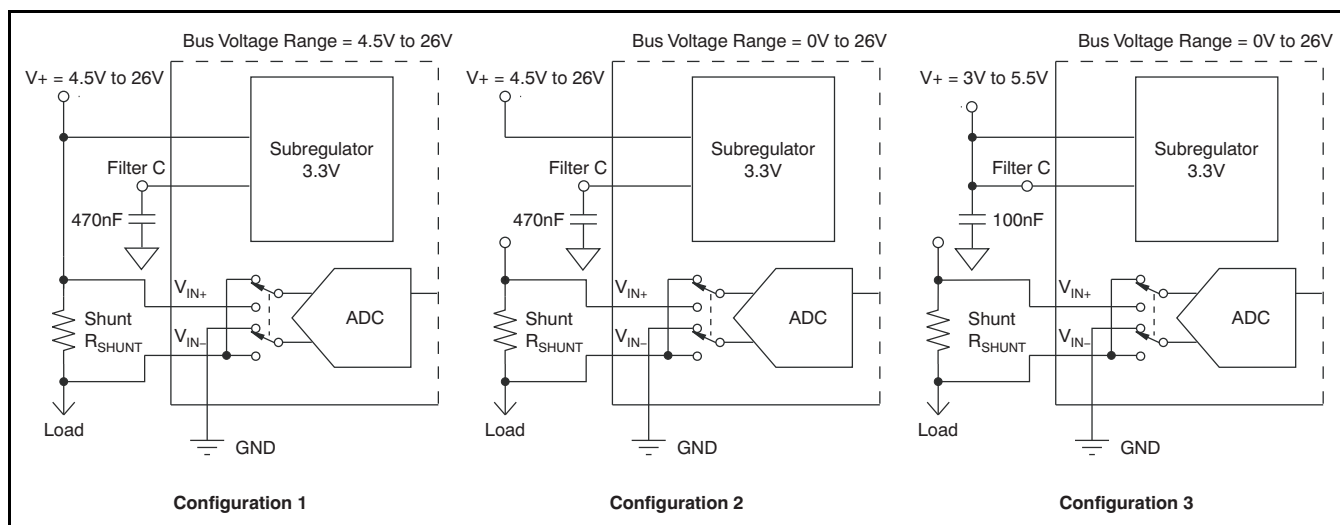


Figure 20. Typical Subregulator Configurations

## SERIES RESISTANCE CANCELLATION

Series resistance in an application circuit that typically results from printed circuit board (PCB) trace resistance and remote line length is automatically cancelled by the TMP512/13, preventing what would otherwise result in a temperature offset. A total of up to 3k $\Omega$  of series line resistance is cancelled by the TMP512/13, eliminating the need for additional characterization and temperature offset correction. See the *Remote Temperature Error vs Series Resistance* typical characteristic curves ([Figure 15](#)) for details on the effects of series resistance and power-supply voltage on sensed remote temperature error.

## DIFFERENTIAL INPUT CAPACITANCE

The TMP512/13 can tolerate differential input capacitance of up to 2200pF with minimal change in temperature error. The effect of capacitance on sensed remote temperature error is illustrated in [Figure 16](#), *Remote Temperature Error vs Differential Capacitance*. See the [Filtering](#) section for suggested component values where filtering unwanted coupled signals is needed.

## TEMPERATURE MEASUREMENT DATA

Temperature measurement data may be taken over an operating range of –40°C to +125°C for both local and remote locations.

The Temperature Register of the TMP512/13 is configured as a 13-bit, read-only register that stores the output of the most recent conversion. Two bytes must be read to obtain data, and are described in the

[Local Temperature Result Register](#) and the [Remote Temperature Result Registers](#). Note that byte 1 is the most significant byte, followed by byte 2, the least significant byte. The first 13 bits are used to indicate temperature. The least significant byte does not have to be read if that information is not needed. The data format for temperature is summarized in [Table 10](#). One LSB equals 0.0625°C. Negative numbers are represented in binary twos complement format. Following power-up or reset, the Temperature Register will read 0°C until the first conversion is complete. Unused bits in the Temperature Register always read '0'.

## REGISTER INFORMATION

The TMP512/13 contain multiple registers for holding configuration information, temperature and voltage measurement results, and status information. These registers are described in [Table 3](#).

## POINTER REGISTER

The 8-bit Pointer Register is used to address a given data register. The Pointer Register identifies which of the data registers should respond to a read or write command on the two-wire bus. This register is set with every write command. A write command must be issued to set the proper value in the Pointer Register before executing a read command. [Table 3](#) describes the pointer address of the TMP512/13 registers. The power-on reset (POR) value of the Pointer Register is 00h (0000 0000b).

## n-FACTOR CORRECTION REGISTER

The TMP512/13 allow for a different n-factor value to be used for converting remote channel measurements to temperature. The remote channel uses sequential current excitation to extract a differential  $V_{BE}$  voltage measurement to determine the temperature of the remote transistor. Equation 1 describes this voltage and temperature.

$$V_{BE2} - V_{BE1} = \frac{nkT}{q} \ln\left(\frac{I_2}{I_1}\right) \quad (1)$$

The value  $n$  in Equation 1 is a characteristic of the particular transistor used for the remote channel. The power-on reset value for the TMP512/13 is  $n = 1.008$ . The value in the n-Factor Correction Register may be used to adjust the effective n-factor according to Equation 2 and Equation 3.

$$n_{eff} = \frac{1.008 \times 300}{(300 - N_{ADJUST})} \quad (2)$$

$$N_{ADJUST} = 300 - \left( \frac{300 \times 1.008}{n_{eff}} \right) \quad (3)$$

The n-factor value must be stored in

two's-complement format, yielding an effective data range from  $-128$  to  $+127$ . The n-factor value may be written to and read from pointer address 16h for remote channel 1, pointer address 17h for remote channel 2, and pointer address 18h for remote channel 3. The register power-on reset value is 00h, thus having no effect unless the register is written to.

## BUS OVERVIEW

The device that initiates the transfer is called a *master*, and the devices controlled by the master are *slaves*. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates START and STOP conditions.

To address a specific device, the master initiates a START condition by pulling the data signal line (SDA) from a HIGH to a LOW logic level while SCL is HIGH. All slaves on the bus shift in the slave address byte on the rising edge of SCL, with the last bit indicating whether a read or write operation is intended. During the ninth clock pulse, the slave being addressed responds to the master by generating an Acknowledge and pulling SDA LOW.

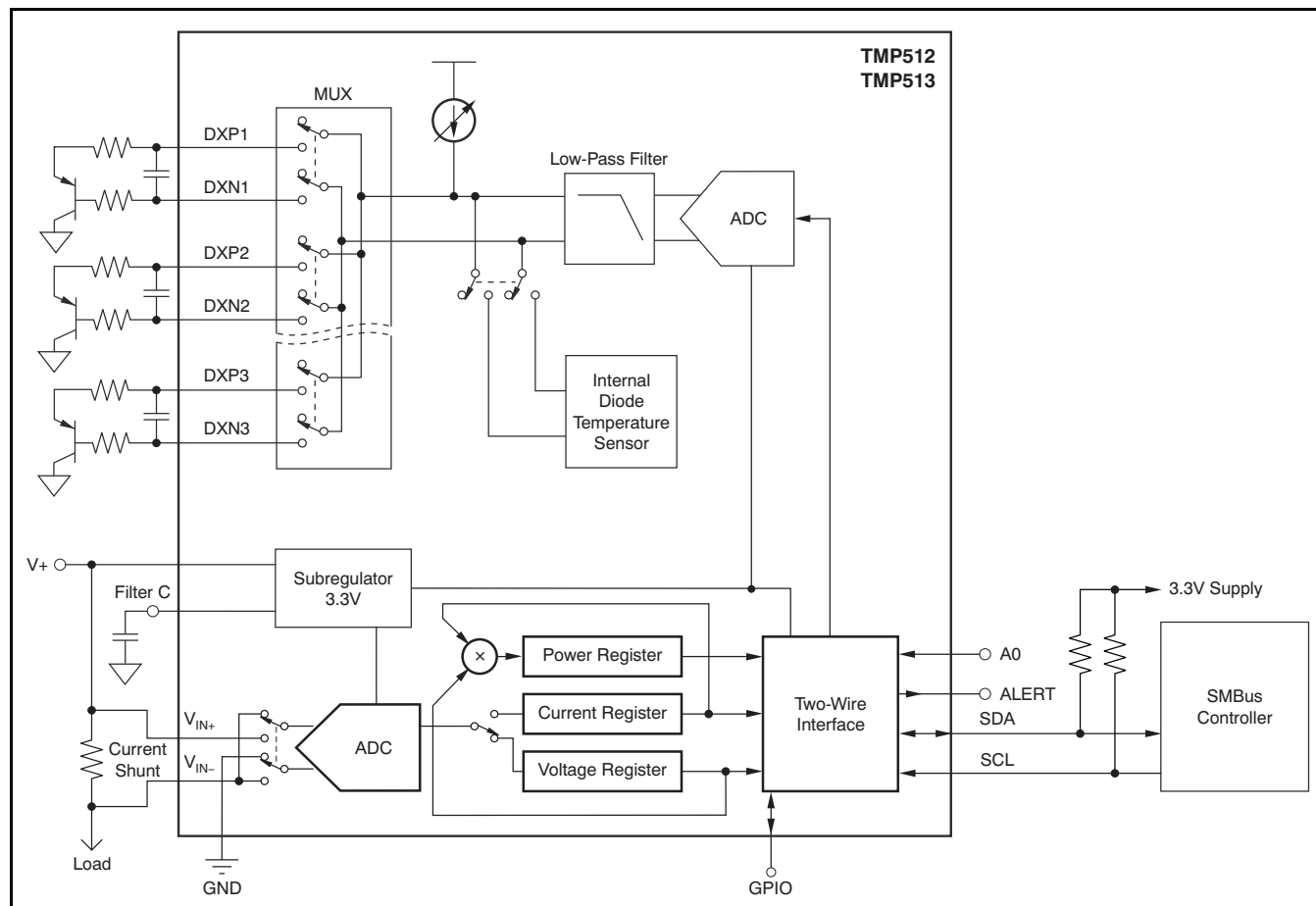


**Figure 21. Typical Application Circuit**

Data transfer is then initiated and eight bits of data are sent, followed by an *Acknowledge* bit. During data transfer, SDA must remain stable while SCL is HIGH. Any change in SDA while SCL is HIGH is interpreted as a START or STOP condition.

Once all data have been transferred, the master generates a STOP condition, indicated by pulling SDA from LOW to HIGH while SCL is HIGH. The TMP512/13 includes a 28ms timeout on its interface to prevent locking up an SMBus.

## SERIAL BUS ADDRESS

To communicate with the TMP512/13, the master must first address slave devices via a slave address byte. The slave address byte consists of seven address bits, and a direction bit indicating the intent of executing a read or write operation.

The TMP512/13 feature an address pin to allow up to four devices to be addressed on a single bus. [Table 1](#) describes the pin logic levels used to properly connect up to four devices. The state of the A0 pin is sampled on every bus communication and should be set before any activity on the interface occurs. The address pin is read at the start of each communication event.

**Table 1. TMP512/13 Address Pins and Slave Addresses**

| DEVICE TWO-WIRE ADDRESS | A0 PIN CONNECTION |
|-------------------------|-------------------|
| 1011100                 | Ground            |
| 1011101                 | V+                |
| 1011110                 | SDA               |
| 1011111                 | SCL               |

## SERIAL INTERFACE

The TMP512/13 operate only as slave devices on the two-wire bus and SMBus. SCL is an input only, and TMP512/13 cannot drive it. Connections to the bus are made via the open-drain I/O lines SDA and SCL. The SDA and SCL pins feature integrated spike suppression filters and Schmitt triggers to minimize the effects of input spikes and bus noise. The TMP512/13 support the transmission protocol for fast (1kHz to 400kHz) and high-speed (1kHz to 3.4MHz) modes. All data bytes are transmitted MSB first.

## WRITING TO/READING FROM THE TMP512/13

Accessing a particular register on the TMP512/13 is accomplished by writing the appropriate value to the register pointer. Refer to [Table 3](#) for a complete list of registers and corresponding addresses. The value for the register pointer as shown in [Figure 24](#) is the first byte transferred after the slave address byte with the R/W bit LOW. Every write operation to the TMP512/13 requires a value for the register pointer.

Writing to a register begins with the first byte transmitted by the master. This byte is the slave address, with the R/W bit LOW. The TMP512/13 then acknowledge receipt of a valid address. The next byte transmitted by the master is the address of the register to which data will be written. This register address value updates the register pointer to the desired register. The next two bytes are written to the register addressed by the register pointer. The TMP512/13 acknowledge receipt of each data byte. The master may terminate data transfer by generating a START or STOP condition.

When reading from the TMP512/13, the last value stored in the register pointer by a write operation determines which register is read during a read operation. To change the register pointer for a read operation, a new value must be written to the register pointer. This write is accomplished by issuing a slave address byte with the R/W bit LOW, followed by the register pointer byte. No additional data are required. The master then generates a START condition and sends the slave address byte with the R/W bit HIGH to initiate the read command. The next byte is transmitted by the slave and is the most significant byte of the register indicated by the register pointer. This byte is followed by an *Acknowledge* from the master; then the slave transmits the least significant byte. The master acknowledges receipt of the data byte. The master may terminate data transfer by generating a *Not-Acknowledge* after receiving any data byte, or generating a START or STOP condition. If repeated reads from the same register are desired, it is not necessary to continually send the register pointer bytes; the TMP512/13 retain the register pointer value until it is changed by the next write operation.

[Figure 22](#) and [Figure 23](#) show read and write operation timing diagrams, respectively. Note that register bytes are sent most-significant byte first, followed by the least significant byte. See [Figure 25](#) for an illustration of a typical register pointer configuration.

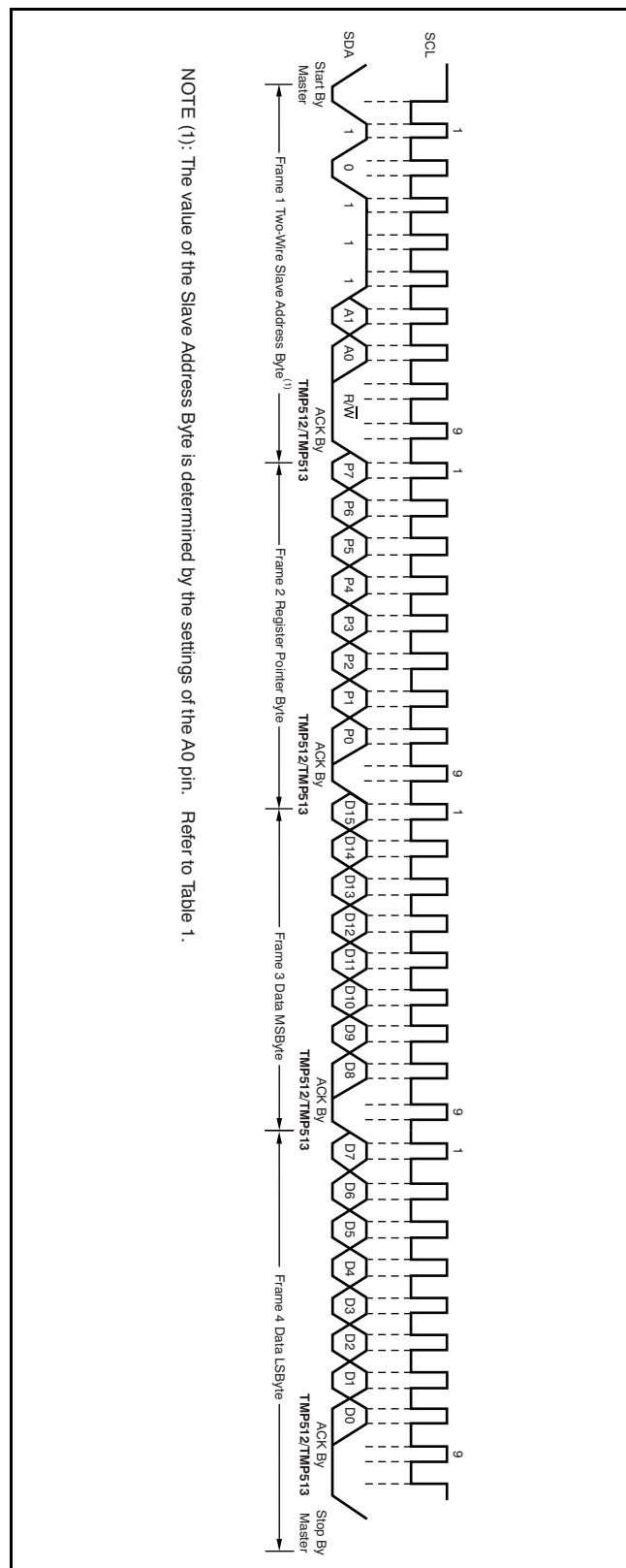


Figure 22. Timing Diagram for Write Word Format

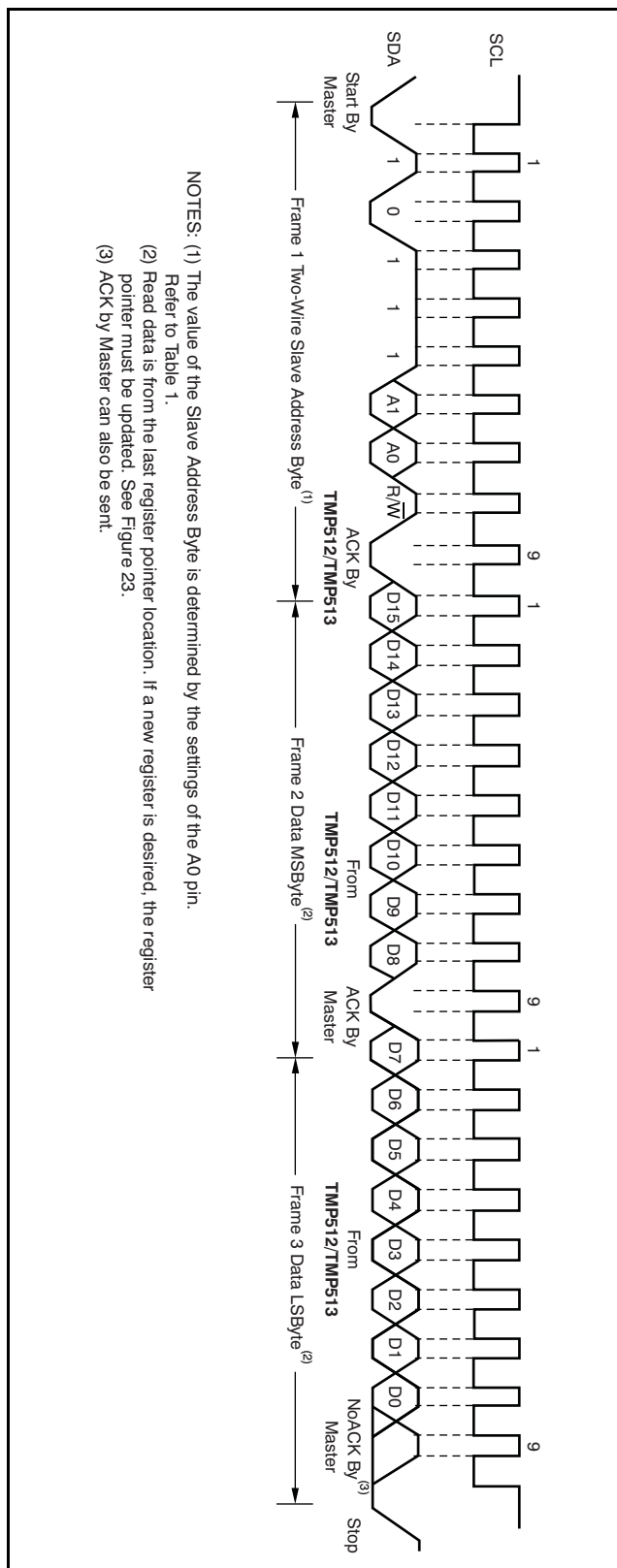


Figure 23. Timing Diagram for Read Word Format

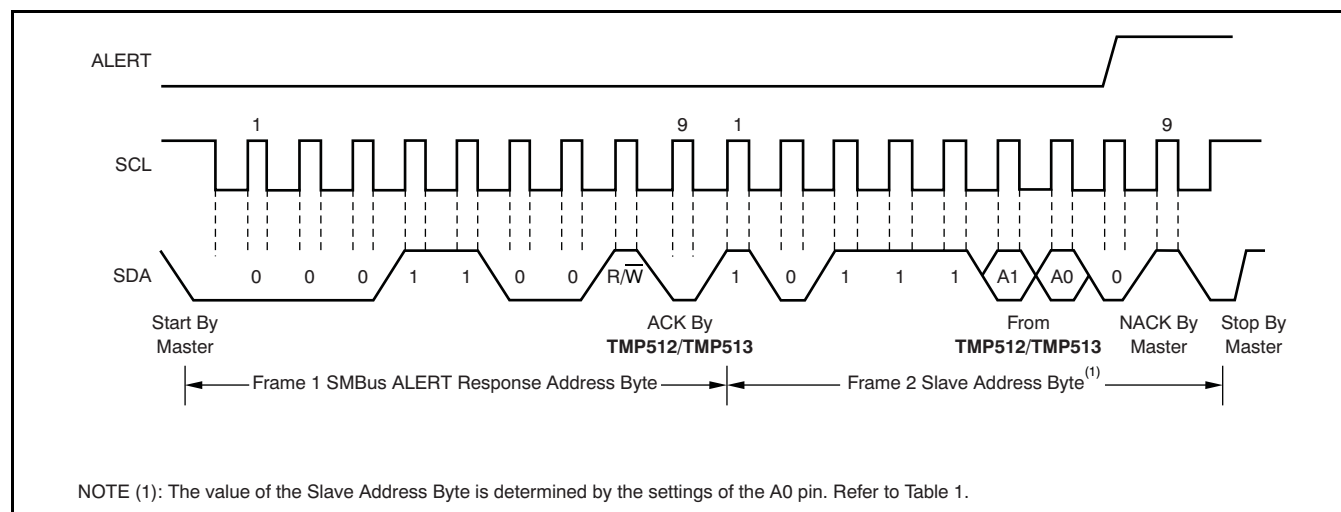


**Figure 24. Timing Diagram for SMBus ALERT**

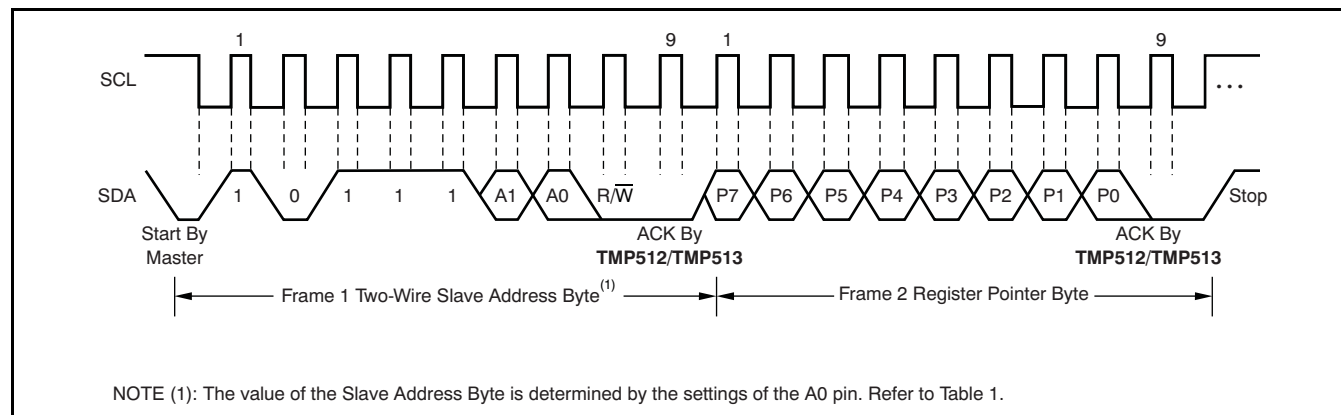


**Figure 25. Typical Register Pointer Set**

## TIMING DIAGRAMS

Figure 26 describes the timing operations on the TMP512/13. Parameters for Figure 26 are defined in Table 2. Bus definitions are:

**Bus Idle:** Both SDA and SCL lines remain high.

**Start Data Transfer:** A change in the state of the SDA line, from high to low, while the SCL line is high, defines a START condition. Each data transfer initiates with a START condition. Denoted as S in Figure 26.

**Stop Data Transfer:** A change in the state of the SDA line from low to high while the SCL line is high defines a STOP condition. Each data transfer terminates with a repeated START or STOP condition. Denoted as P in Figure 26.

**Data Transfer:** The number of data bytes transferred between a START and a STOP condition is not limited and is determined by the master device. The receiver acknowledges data transfer.

**Acknowledge:** Each receiving device, when addressed, is obliged to generate an Acknowledge bit. A device that acknowledges must pull down the SDA line during the Acknowledge clock pulse in such a way that the SDA line is stable low during the high period of the Acknowledge clock pulse. Setup and hold times must be taken into account. On a master receive, data transfer termination can be signaled by the master generating a Not-Acknowledge on the last byte that has been transmitted by the slave.

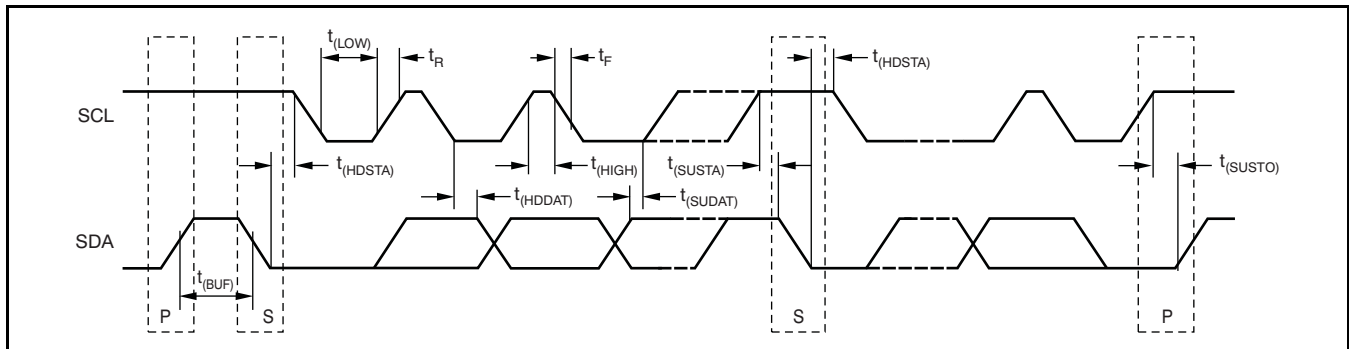


Figure 26. Two-Wire Timing Diagram

Table 2. Timing Characteristics for Figure 26

| PARAMETER                                                                                  |               | FAST MODE        |      | HIGH-SPEED MODE  |     | UNIT |
|--------------------------------------------------------------------------------------------|---------------|------------------|------|------------------|-----|------|
|                                                                                            |               | MIN              | MAX  | MIN              | MAX |      |
| SCL Operating Frequency                                                                    | $f_{(SCL)}$   | 0.001            | 0.4  | 0.001            | 3.4 | MHz  |
| Bus Free Time Between STOP and START Condition                                             | $t_{(BUF)}$   | 600              |      | 160              |     | ns   |
| Hold time after repeated START condition. After this period, the first clock is generated. | $t_{(HDSTA)}$ | 100              |      | 100              |     | ns   |
| Repeated START Condition Setup Time                                                        | $t_{(SUSTA)}$ | 100              |      | 100              |     | ns   |
| STOP Condition Setup Time                                                                  | $t_{(SUSTO)}$ | 100              |      | 100              |     | ns   |
| Data Hold Time                                                                             | $t_{(HDDAT)}$ | 0 <sup>(1)</sup> |      | 0 <sup>(2)</sup> |     | ns   |
| Data Setup Time                                                                            | $t_{(SUDAT)}$ | 100              |      | 10               |     | ns   |
| SCL Clock LOW Period                                                                       | $t_{(LOW)}$   | 1300             |      | 160              |     | ns   |
| SCL Clock HIGH Period                                                                      | $t_{(HIGH)}$  | 600              |      | 60               |     | ns   |
| Clock/Data Fall Time                                                                       | $t_F$         |                  | 300  |                  | 160 | ns   |
| Clock/Data Rise Time                                                                       | $t_R$         |                  | 300  |                  | 160 | ns   |
| for SCL ≤ 100kHz                                                                           | $t_R$         |                  | 1000 |                  |     | ns   |

- (1) For cases with fall time of SCL less than 20ns and/or the rise or fall time of SDA less than 20ns, the hold time should be greater than 20ns.
- (2) For cases with a fall time of SCL less than 10ns and/or the rise or fall time of SDA less than 10ns, the hold time should be greater than 10ns.

## HIGH-SPEED MODE

In order for the two-wire bus to operate at frequencies above 400kHz, the master device must issue a High-Speed mode (Hs-mode) master code (0000 1xxx) as the first byte after a START condition to switch the bus to high-speed operation. The TMP512/13 do not acknowledge this byte, but switch the input filters on SDA and SCL and the output filter on SDA to operate in Hs-mode, allowing transfers at up to 3.4MHz. After the Hs-mode master code has been issued, the master transmits a START condition to a two-wire slave address that initiates a data transfer operation. The bus continues to operate in Hs-mode until a STOP condition occurs on the bus. Upon receiving the STOP condition, the TMP512/13 switch the input and output filters back to Fast mode operation.

## POWER-UP CONDITIONS

Power-up conditions apply to a software reset via the RST bit (bit 15) in the Configuration Register, or the two-wire bus General Call Reset. At device power up, all Status bits are masked, and the SMBus Alert function is disabled. All watchdog outputs default to active low and transparent (non-latched) modes.

## SHUTDOWN MODE

The TMP512/13 shutdown mode of operation allows the user flexibility to shut down the shunt/bus voltage measurement and the temperature measurement functions individually.

To shut down the shunt/bus voltage measurement function immediately, set bits 2 through 0 in Configuration Register 1 (00h) to '000' respectively. To shut down the shunt/bus voltage measurement after the end of the current conversion, set bits 2 through 0 in Configuration Register 1 (00h) to '100' respectively.

To shut down the temperature measurement function immediately, set bits 15 through 11 in Configuration Register 2 (01h) to '00000' respectively. To shut down the temperature measurement after the end of the current conversion, set bit 15 in Configuration Register 2 (01h) to '0'.

## ONE-SHOT COMMAND

For the TMP512/13, when the temperature core is in shutdown and the voltage core is in triggered mode, a single conversion is started on all enabled channels by writing a '1' to the OS bit in Configuration Register 1. This write operation starts one conversion; the TMP512/13 returns to shutdown mode when that conversion completes. At the end of the conversion, the Conversion Ready flags (bit 6 and bit 5) in the Status Register are set to indicate end of conversion.

## SENSOR FAULT

The TMP512/13 can sense an open circuit. Short-circuit conditions return a value of  $-256^{\circ}\text{C}$ . The detection circuitry consists of a voltage comparator that trips when the voltage at DXP exceeds  $(V+) - 0.6\text{V}$  (typical). The comparator output is continuously checked during a conversion. If a fault is detected, the OPEN bit (bit 0) in the temperature result register is set to '1' and the rest of the register bits should be ignored.

When not using the remote sensor with the TMP512/13, the DXP and DXN inputs must be connected together to prevent meaningless fault warnings.

## UNDERVOLTAGE LOCKOUT

The TMP512/13 sense when the power-supply voltage has reached a minimum voltage level for the ADC to function. The detection circuitry consists of a voltage comparator that enables the ADC after the power supply  $(V+)$  exceeds 2.7V (typical). The comparator output is continuously checked during a conversion. The TMP512/13 do not perform a temperature conversion if the power supply is not valid. The PVLD bit (see [Status Register](#); Local Temperature Reset Register; Remote Temperature Reset 1, 2 and 3 Registers) of the individual Local/Remote Temperature Result Registers are set to '1' and the temperature result may be incorrect.

## TEMPERATURE AVERAGING

The TMP512/13 average the input diode voltages that determine the remote temperature by sampling multiple times throughout a conversion. The temperature result can be extracted from four different  $V_{BE}$  readings and is sampled 600 times in 130ms (max). Each  $V_{BE}$  voltage is sampled 150 times through integration capacitors that average the results throughout the conversion time. A delta-sigma ( $\Delta\Sigma$ ) modulator and digital filter integrate the  $V_{BE}$  voltages and create a sync filter averaging system. In addition, a low-pass filter is present at the input of the converter with a cutoff frequency of 65kHz. This integrating topology offers superior noise immunity.

## FILTERING

Remote junction temperature sensors are usually implemented in a noisy environment. Noise is frequently generated by fast digital signals and if not filtered properly will induce errors that can corrupt temperature measurements. The TMP512/13 have a built-in 65kHz filter on the inputs of DXP and DXN to minimize the effects of noise. However, a bypass capacitor placed differentially across the inputs of the remote temperature sensor is recommended to make the application more robust against unwanted

coupled signals. The value of this capacitor should be between 100pF and 1nF. Some applications attain better overall accuracy with additional series resistance; however, this increased accuracy is application-specific. When series resistance is added, the total value should not be greater than 3kΩ. If filtering is needed, suggested component values are 100pF and 50Ω on each input; exact values are application-specific.

## GENERAL CALL RESET

The TMP512/13 support reset via the two-wire General Call address 00h (0000 0000b). The TMP512/13 acknowledge the General Call address and respond to the second byte. If the second byte is 06h (0000 0110b), the TMP512/13 execute a software reset state to all TMP512/13 registers, and abort any conversion in progress. The TMP512/13 take no action in response to other values in the second byte.

## REMOTE SENSING

The TMP512/13 are designed to be used with either discrete transistors or substrate transistors built into processor chips and ASICs. Either NPN or PNP transistors can be used, as long as the base-emitter junction is used as the remote temperature sense. NPN transistors must be diode-connected. PNP transistors can either be transistor- or diode-connected, as [Figure 18](#) and [Figure 19](#) show.

Errors in remote temperature sensor readings are typically the consequence of the ideality factor and current excitation used by the TMP512/13 versus the manufacturer-specified operating current for a given transistor. Some manufacturers specify a high-level and low-level current for the temperature-sensing substrate transistors. The TMP512/13 use 6μA for  $I_{LOW}$  and 120μA for  $I_{HIGH}$ .

The ideality factor (n) is a measured characteristic of a remote temperature sensor diode as compared to an ideal diode. The TMP512/13 allow for different n-factor values; see the [n-Factor Correction Register](#) section.

The ideality factor for the TMP512/13 is trimmed to be 1.008. For transistors that have an ideality factor that does not match the TMP512/13, [Equation 4](#) can be used to calculate the temperature error. Note that for the equation to be used correctly, actual temperature (°C) must be converted to kelvins (K).

$$T_{ERR} = \left( \frac{n - 1.008}{1.008} \right) \times [273.15 + T(^{\circ}C)] \quad (4)$$

Where:

n = ideality factor of remote temperature sensor.

T(°C) = actual temperature.

T<sub>ERR</sub> = error in TMP512/13 because n ≠ 1.008.

Degree delta is the same for °C and K.

For n = 1.004 and T(°C) = 100°C:

$$T_{ERR} = \left( \frac{1.004 - 1.008}{1.008} \right) \times (273.15 + 100^{\circ}C)$$

$$T_{ERR} = 1.48^{\circ}C \quad (5)$$

If a discrete transistor is used as the remote temperature sensor with the TMP512/13, the best accuracy can be achieved by selecting the transistor according to the following criteria:

1. Base-emitter voltage > 0.25V at 6μA, at the highest sensed temperature.
2. Base-emitter voltage < 0.95V at 120μA, at the lowest sensed temperature.
3. Base resistance < 100Ω.
4. Tight control of V<sub>BE</sub> characteristics indicated by small variations in h<sub>FE</sub> (that is, 50 to 150).

Based on these criteria, two recommended small-signal transistors are the 2N3904 (NPN) or 2N3906 (PNP).

## BASIC ADC FUNCTIONS

The two analog inputs to the TMP512/13, V<sub>IN+</sub> and V<sub>IN-</sub>, connect to a shunt resistor in the bus of interest. The TMP512/13 are powered by an internal subregulator, which has a typical output of 3.3V. The bus being sensed can vary from 0V to 26V. There are no special considerations for power-supply sequencing (for example, a bus voltage can be present with the supply voltage off, and vice-versa). The TMP512/13 sense the small drop across the shunt for shunt voltage, and sense the voltage with respect to ground from V<sub>IN-</sub> for the bus voltage. See [Figure 27](#) for an illustration of this operation.

When the TMP512/13 are in the normal operating mode (that is, MODE bits of Configuration Register 1 are set to '111'), the devices continuously convert the shunt voltage up to the number set in the shunt voltage averaging function (Configuration Register 1, SADC bits). The devices then convert the bus voltage up to the number set in the bus voltage averaging (Configuration Register 1, BADC bits). The Mode control in Configuration Register 1 also permits selecting modes to convert only voltage or current, either continuously or in response to a two-wire command.

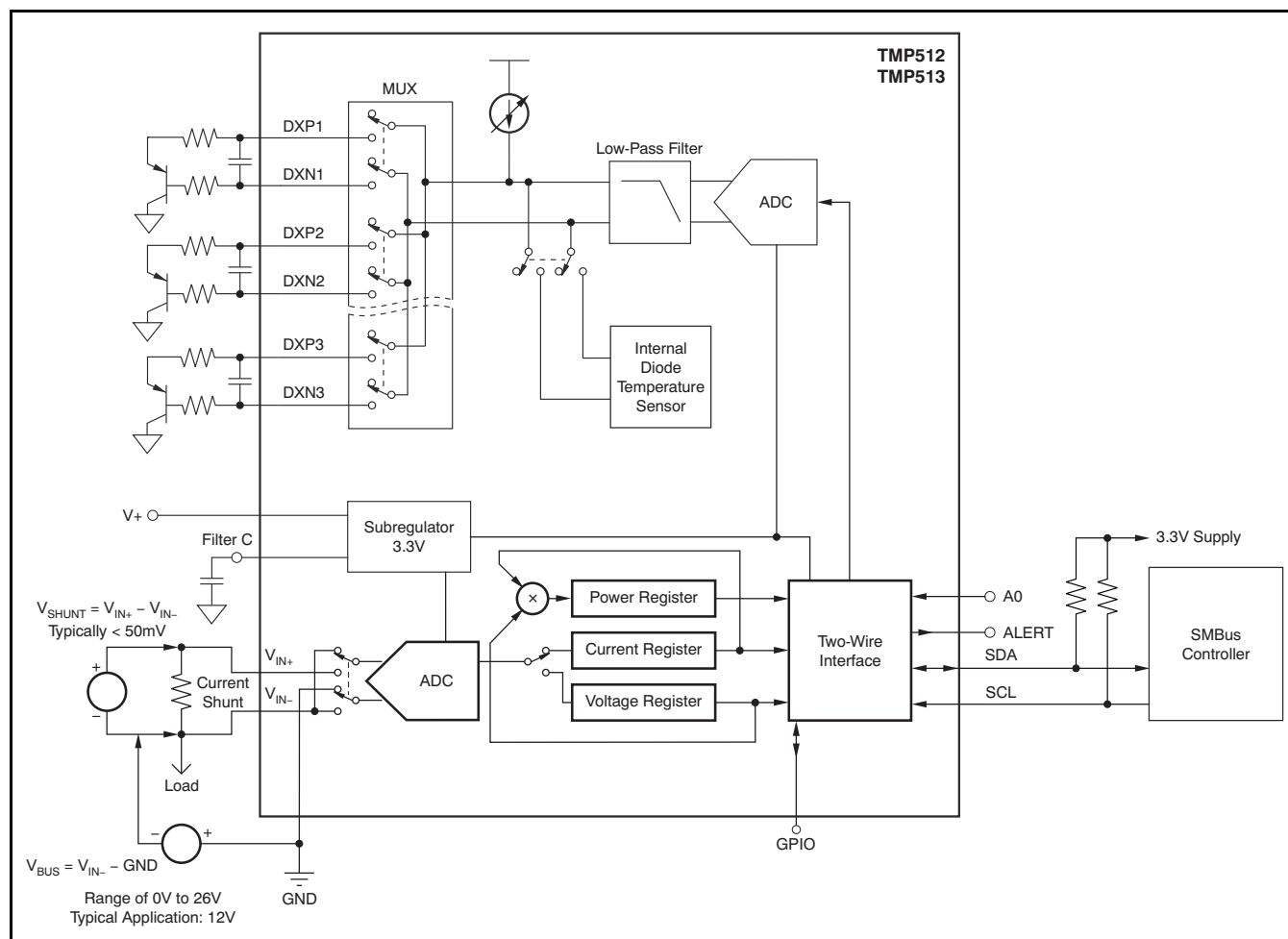


**Figure 27. TMP512/13 Configured for Shunt and Bus Voltage Measurement**

All current and power calculations are performed in the background and do not contribute to conversion time; conversion times shown in the [Electrical Characteristics](#) table can be used to determine the actual conversion time.

Power-Down mode reduces the quiescent current and turns off current into the TMP512/13 inputs, avoiding any supply drain. Full recovery from Power-Down requires 40μs. ADC Off mode (set by Configuration Register 1, MODE bits) stops all conversions.

Although the TMP512/13 can be read at any time, and the data from the last conversion remain available, the Conversion Ready bit and the Conversion Ready Temperature bit (Status Register, CVR and CRT) are provided to help co-ordinate one-shot or triggered conversions. The Conversion Ready bit and the Conversion Ready Temperature bit are set after all conversions, averaging, and multiplication operations are complete.

The Conversion Ready bit and the Conversion Ready Temperature bit clear when reading the Status Register or triggering a single-shot conversion.

## POWER MEASUREMENT

Current and bus voltage are converted at different points in time, depending on the resolution and averaging mode settings. For instance, when configured for 12-bit and 128 sample averaging, up to 81ms in time between sampling these two values is possible. Again, these calculations are performed in the background and do not add to the overall conversion time.

## PGA FUNCTION

If larger full-scale shunt voltages are desired, the TMP512/13 provide a PGA function that increases the full-scale range up to 2, 4, or 8 times (320mV). Additionally, the bus voltage measurement has two full-scale ranges: 16V or 32V.

## COMPATIBILITY WITH TI HOT-SWAP CONTROLLERS

The TMP512/13 are designed for compatibility with hot-swap controllers such as the TI [TPS2490](#). The TPS2490 uses a high-side shunt with a limit at 50mV; the TMP512/13 full-scale range of 40mV enables the use of the same shunt for current sensing below this limit. When sensing is required at (or through) the 50mV sense point of the TPS2490, the PGA of the TMP512/13 can be set to  $\times 2$  to provide an 80mV full-scale range.

## FILTERING AND INPUT CONSIDERATIONS

Measuring current is often noisy, and such noise can be difficult to define. The TMP512/13 offer several options for filtering by choosing resolution and averaging in Configuration Register 1. These filtering options can be set independently for either voltage or current measurement.

The internal ADC is based on a delta-sigma ( $\Delta\Sigma$ ) front-end with a 500kHz ( $\pm 10\%$ ) typical sampling rate.

This architecture has good inherent noise rejection; however, transients that occur at or very close to the sampling rate harmonics can cause problems. Because these signals are at 1MHz and higher, they can be dealt with by incorporating filtering at the input of the TMP512/13. The high frequency enables the use of low-value series resistors on the filter for negligible effects on measurement accuracy. [Figure 28](#) shows the TMP512/13 with an additional filter added at the input.

Overload conditions are another consideration for the TMP512/13 inputs. The TMP512/13 inputs are specified to tolerate 26V across the inputs. A large differential scenario might be a short to ground on the load side of the shunt. This type of event can result in full power-supply voltage across the shunt (as long as the power supply or energy storage capacitors support it). It must be remembered that removing a short to ground can result in inductive kickbacks that could exceed the 26V differential and common-mode rating of the TMP512/13. Inductive kickback voltages are best dealt with by zener-type transient-absorbing devices (commonly called *transzorbs*) combined with sufficient energy storage capacitance.

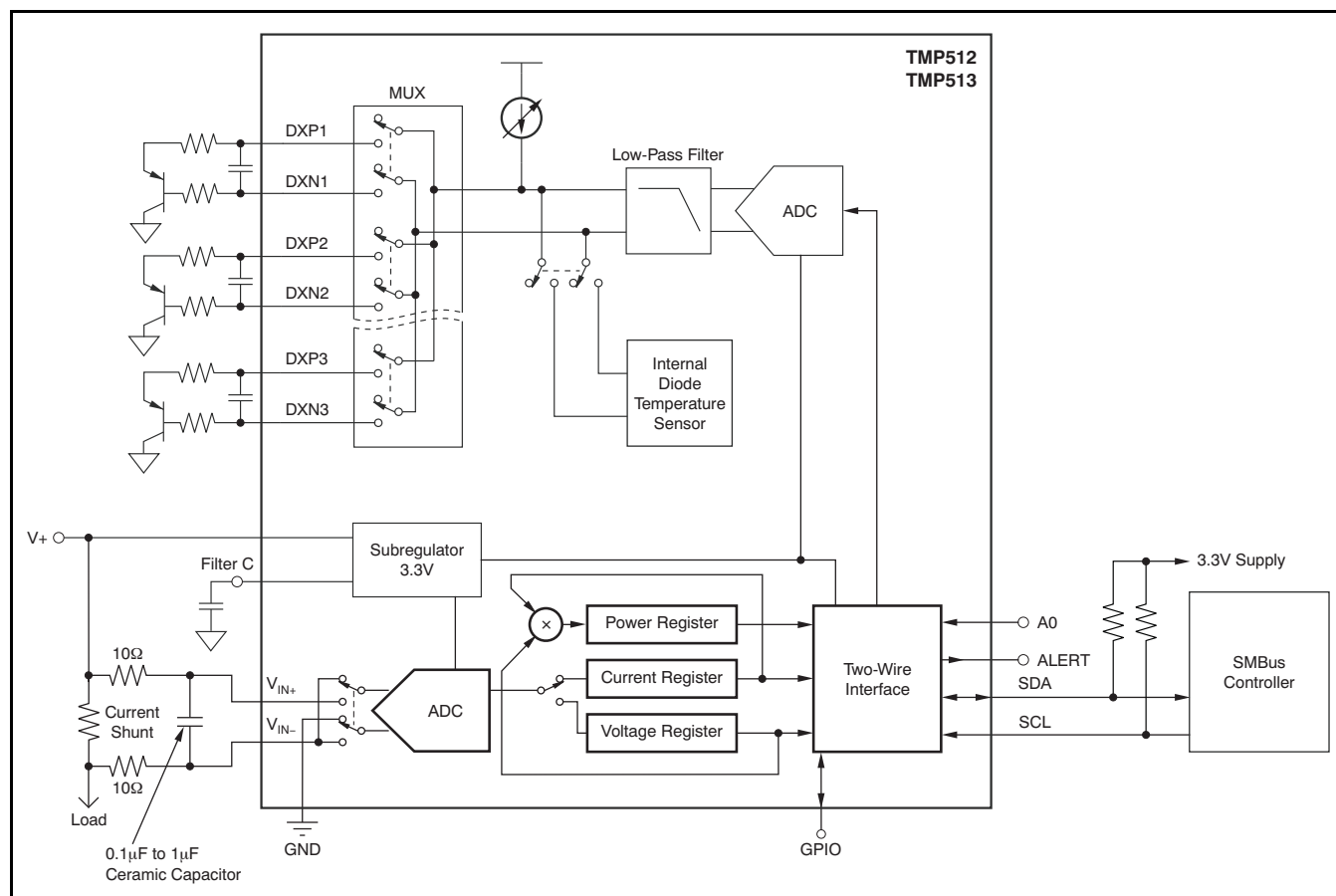


Figure 28. TMP512/13 with Input Filtering

In applications that do not have large energy storage electrolytics on one or both sides of the shunt, an input overstress condition may result from an excessive  $dV/dt$  of the voltage applied to the input. A hard physical short is the most likely cause of this event, particularly in applications with no large electrolytics present. This problem occurs because an excessive  $dV/dt$  can activate the ESD protection in the TMP512/13 in systems where large currents are available. Testing has demonstrated that the addition of  $10\Omega$  resistors in series with each input of the TMP512/13 sufficiently protects the inputs against  $dV/dt$  failure up to the 26V rating of the TMP512/13. These resistors have no significant effect on accuracy.

### SMBus ALERT RESPONSE

The SMBus alert response functions only when the Alert pin is active and in latch mode (03h, bit 0 = 1); see [Figure 24](#). The ALERT interrupt output signal is latched and can be cleared only by either reading the Status Register or by successfully responding to an alert response address. If the fault is still present, the ALERT pin re-asserts. Asserting the ALERT pin does not halt automatic conversions that are already in progress. The ALERT output pin is open-drain, allowing multiple devices to share a common interrupt line.

The TMP512/13 respond to the SMBus alert response address, an interrupt pointer return-address feature. The SMBus alert response interrupt pointer provides quick fault identification for simple slave devices. When an ALERT occurs, the master can broadcast the alert response slave address (0001 100). Following this alert response, any slave devices that generated interrupts identify themselves by putting the respective addresses on the bus.

The alert response can activate several different slave devices simultaneously, similar to the two-wire General Call. If more than one slave attempts to respond, bus arbitration rules apply; the device with the lower address code wins. The losing device does

not generate an Acknowledge and continues to hold the ALERT line low until the interrupt is cleared. Successful completion of the read alert response protocol clears the SMBus ALERT pin, provided that the condition causing the alert no longer exists. The SMBus Alert flag is cleared separately by either reading the Status Register or by disabling the SMBus Alert function.

The Status Register flags indicate which (if any) of the watchdogs have been activated. After power-on reset (POR), the normal state of all flag bits is '0', assuming that no alarm conditions exist.

### EXTERNAL CIRCUITRY FOR ADDITIONAL $V_{BUS}$ INPUT

The TMP512/13 GPIO can be used to control an external circuit to switch the  $V_{BUS}$  measurement to an alternate location. Switching is most often done to perform bus voltage measurements on the opposite side of a MOSFET switch in series with the shunt resistor.

Consideration must be given to the typical  $20\mu A$  input current of each TMP512/13 input, along with the  $320k\Omega$  impedance present at the  $V_{IN-}$  input where the bus voltage is measured. These effects can create errors through the resistance of any external switching method used. The easiest way to avoid these errors is by reducing this resistance to a minimum; select switching MOSFETs with the lowest possible  $R_{DS(on)}$  values.

The circuit shown in [Figure 29](#) uses MOSFET pairs to reduce package count. Back-to-back MOSFETs must be used in each leg because of the built-in back diodes from source-to-drain. In this circuit, the normal connection for  $V_{IN-}$  is at the shunt, with the optional voltage measurement at the output of the control FET.

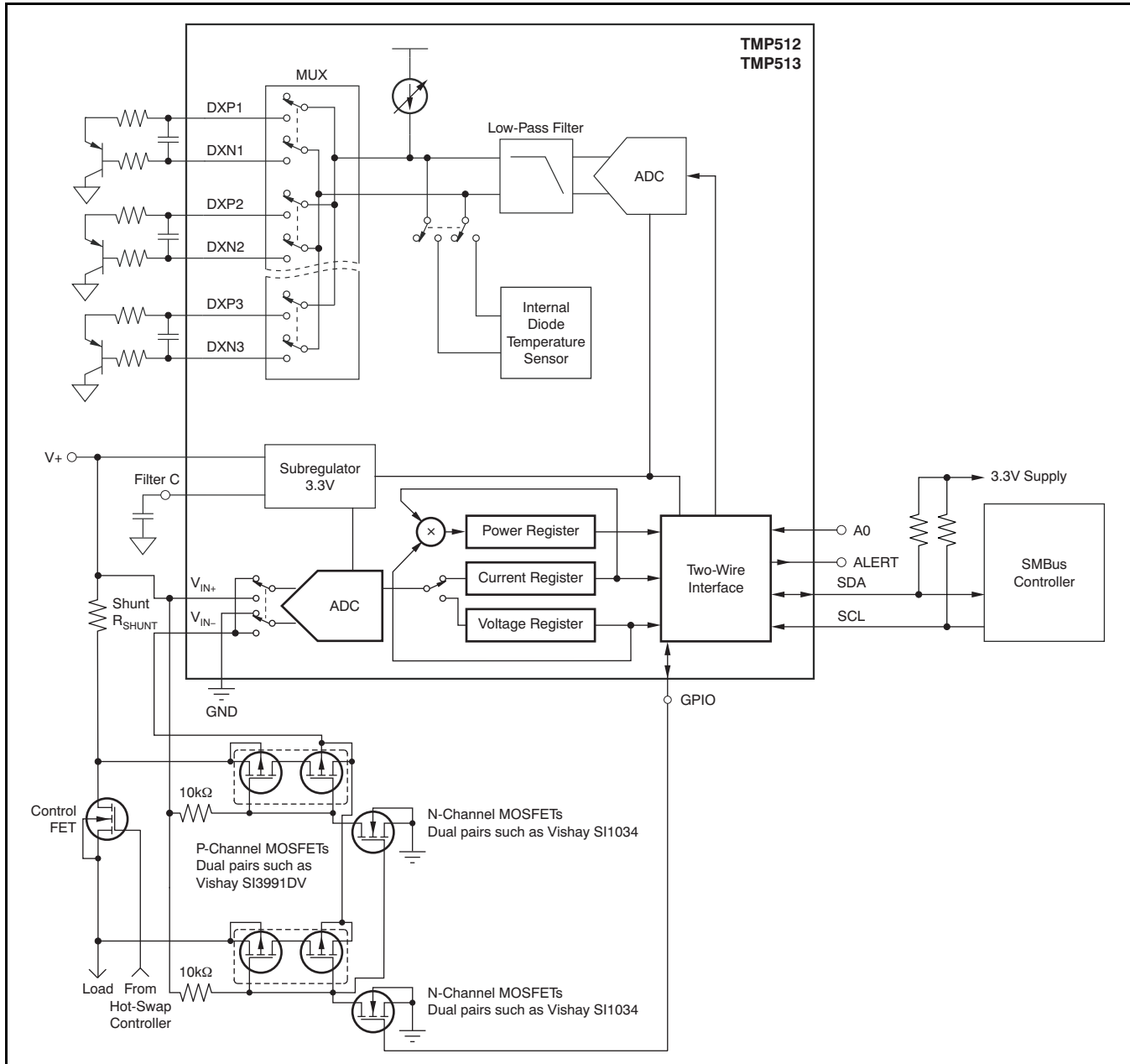


Figure 29. External Circuitry for Additional  $V_{BUS}$  Input

## PROGRAMMING THE TMP512/13 POWER MEASUREMENT ENGINE

### Calibration Register and Scaling

The Calibration Register makes it possible to set the scaling of the Current and Power Registers to whatever values are most useful for a given application. One strategy may be to set the Calibration Register such that the largest possible number is generated in the Current Register or Power Register at the expected full-scale point; this approach yields the highest resolution. The Calibration Register can also be selected to provide values in the Current and Power Registers that either provide direct decimal equivalents of the values being measured, or yield a round LSB number. After these choices have been made, the Calibration Register also offers possibilities for end user system-level calibration, where the value is adjusted slightly to cancel total system error.

This section presents two examples for configuring the TMP512/13 calibration. Both examples are written so the information relates directly to the calibration setup found in the TMP512/13EVM software.

#### Calibration Example 1: Calibrating the TMP512/13 with no possibility for overflow.

##### NOTE

The numbers used in this example are the same used with the TMP512/13EVM software as shown in [Figure 30](#).

1. Establish the following parameters:

$$V_{BUS\_MAX} = 32$$

$$V_{SHUNT\_MAX} = 0.32$$

$$R_{SHUNT} = 0.5$$

2. Use [Equation 6](#) to determine the maximum possible current .

$$\text{MaxPossible\_I} = \frac{V_{SHUNT\_MAX}}{R_{SHUNT}}$$

$$\text{MaxPossible\_I} = 0.64$$

(6)

3. Choose the desired maximum current value. This value is selected based on system expectations.

$$\text{Max\_Expected\_I} = 0.6$$

4. Calculate the possible range of current LSBs. To calculate this range, first compute a range of LSBs that is appropriate for the design. Next, select an LSB within this range. Note that the results will have the most resolution when the minimum LSB is selected. Typically, an LSB is selected to be the nearest round number to the minimum LSB value.

$$\text{Minimum\_LSB} = \frac{\text{Max\_Expected\_I}}{32767}$$

$$\text{Minimum\_LSB} = 18.311 \times 10^{-6}$$

(7)

$$\text{Maximum\_LSB} = \frac{\text{Max\_Expected\_I}}{4095}$$

$$\text{Maximum\_LSB} = 146.520 \times 10^{-6}$$

(8)

Choose an LSB in the range:  $\text{Minimum\_LSB} < \text{Selected\_LSB} < \text{Maximum\_LSB}$

$$\text{Current\_LSB} = 20 \times 10^{-6}$$

##### Note:

This value was selected to be a round number near the Minimum\_LSB. This selection allows for good resolution with a rounded LSB.

5. Compute the Calibration Register value using [Equation 9](#):

$$\text{Cal} = \text{trunc} \left( \frac{0.04096}{\text{Current\_LSB} \times R_{SHUNT}} \right)$$

$$\text{Cal} = 4096$$

(9)

6. Calculate the Power LSB with Equation 10. Equation 10 shows a general formula; because the bus voltage measurement LSB is always 4mV, the power formula reduces to the calculated result.

$$\text{Power\_LSB} = 20 \text{ Current\_LSB}$$

$$\text{Power\_LSB} = 400 \times 10^{-6} \quad (10)$$

7. Compute the maximum current and shunt voltage values (before overflow), as shown by Equation 11 and Equation 12. Note that both Equation 11 and Equation 12 involve an *If - then* condition:

$$\text{Max\_Current} = \text{Current\_LSB} \times 32767$$

$$\text{Max\_Current} = 0.65534 \quad (11)$$

If  $\text{Max\_Current} \geq \text{MaxPossible\_I}$  then

$$\text{Max\_Current\_Before\_Overflow} = \text{MaxPossible\_I}$$

Else

$$\text{Max\_Current\_Before\_Overflow} = \text{Max\_Current}$$

End If

(Note that Max\_Current is greater than MaxPossible\_I in this example.)

$$\text{Max\_Current\_Before\_Overflow} = 0.64$$

$$\text{Max\_ShuntVoltage} = \text{Max\_Current\_Before\_Overflow} \times R_{\text{SHUNT}}$$

$$\text{Max\_ShuntVoltage} = 0.32 \quad (12)$$

If  $\text{Max\_ShuntVoltage} \geq V_{\text{SHUNT\_MAX}}$

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = V_{\text{SHUNT\_MAX}}$$

Else

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = \text{Max\_ShuntVoltage}$$

End If

(Note that Max\_ShuntVoltage is greater than  $V_{\text{SHUNT\_MAX}}$  in this example.)

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = 0.32$$

8. Compute the maximum power with Equation 13.

$$\text{MaximumPower} = \text{Max\_Current\_Before\_Overflow} \times V_{\text{BUS\_MAX}}$$

$$\text{MaximumPower} = 20.48 \quad (13)$$

9. (Optional second Calibration step.) Compute corrected full-scale calibration value based on measured current.

$$\text{TMP513\_Current} = 0.63484$$

$$\text{MeasShuntCurrent} = 0.55$$

$$\text{Corrected\_Full\_Scale\_Cal} = \text{trunc} \left( \frac{\text{Cal} \times \text{MeasShuntCurrent}}{\text{TMP513\_Current}} \right)$$

$$\text{Corrected\_Full\_Scale\_Cal} = 3548 \quad (14)$$

Figure 30 illustrates how to perform the same procedure discussed in this example using the automated TMP512/13EVM software. Note that the same numbers used in this nine-step example are used in the software example. Note also that Figure 30 illustrates which results correspond to which step (for example, the information entered in Step 1 is enclosed in a box in Figure 30 and labeled).

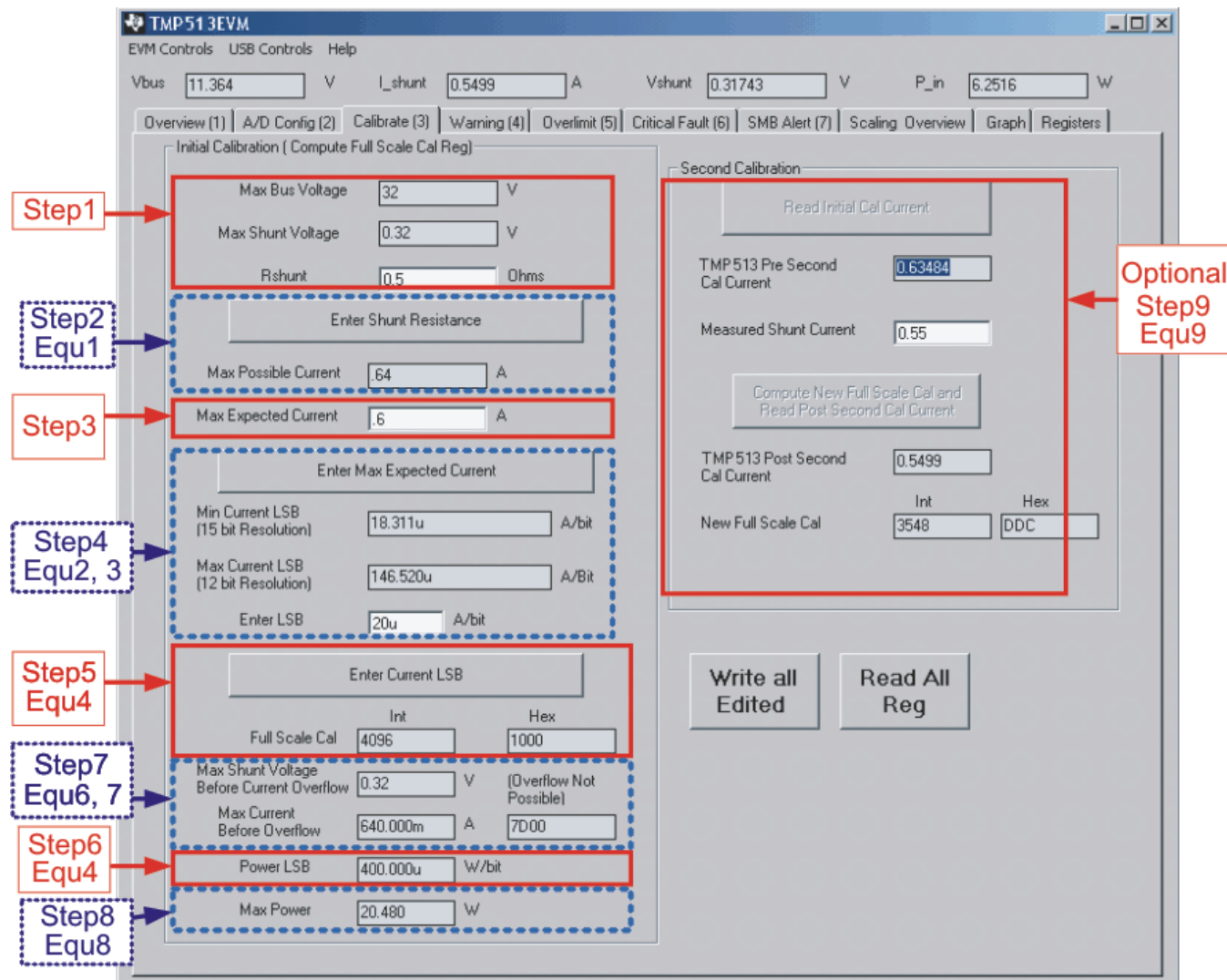


Figure 30. TMP512/513EVM Calibration Software Automatically Computes Calibration Steps 1-9

## Calibration Example 2 (Overflow Possible)

This design example uses the nine-step procedure for calibrating the TMP512/13 where overflow is possible. [Figure 31](#) illustrates how the same procedure is performed using the automated TMP512/13EVN software. The same numbers used in the nine-step example are used in the software example shown in [Figure 31](#). Note also that [Figure 31](#) illustrates which results correspond to which step (for example, the information entered in Step 1 is circled in [Figure 31](#) and labeled).

1. Establish the following parameters:

$$V_{BUS\_MAX} = 32$$

$$V_{SHUNT\_MAX} = 0.32$$

$$R_{SHUNT} = 5$$

2. Determine the maximum possible current using [Equation 15](#):

$$\text{MaxPossible\_I} = \frac{V_{SHUNT\_MAX}}{R_{SHUNT}}$$

$$\text{MaxPossible\_I} = 0.064 \quad (15)$$

3. Choose the desired maximum current value:  $\text{Max\_Expected\_I}, \leq \text{MaxPossible\_I}$ . This value is selected based on system expectations.

$$\text{Max\_Expected\_I} = 0.06$$

4. Calculate the possible range of current LSBs. This calculation is done by first computing a range of LSB's that is appropriate for the design. Next, select an LSB within this range. Note that the results will have the most resolution when the minimum LSB is selected. Typically, an LSB is selected to be the nearest round number to the minimum LSB.

$$\text{Minimum\_LSB} = \frac{\text{Max\_Expected\_I}}{32767}$$

$$\text{Minimum\_LSB} = 1.831 \times 10^{-6} \quad (16)$$

$$\text{Maximum\_LSB} = \frac{\text{Max\_Expected\_I}}{4095}$$

$$\text{Maximum\_LSB} = 14.652 \times 10^{-6} \quad (17)$$

Choose an LSB in the range:  $\text{Minimum\_LSB} < \text{Selected\_LSB} < \text{Maximum\_LSB}$

$$\text{Current\_LSB} = 1.9 \times 10^{-6}$$

**Note:**

This value was selected to be a round number near the Minimum\_LSB. This section allows for good resolution with a rounded LSB.

5. Compute the calibration register using [Equation 18](#):

$$\text{Cal} = \text{trunc} \left[ \frac{0.04096}{\text{Current\_LSB} \times R_{SHUNT}} \right] \quad \text{Cal} = 4311 \quad (18)$$

6. Calculate the Power LSB using [Equation 19](#). [Equation 19](#) shows a general formula; because the bus voltage measurement LSB is always 4mV, the power formula reduces to calculate the result.

$$\text{Power\_LSB} = 20 \text{ Current\_LSB}$$

$$\text{Power\_LSB} = 38 \times 10^{-6} \quad (19)$$

7. Compute the maximum current and shunt voltage values (before overflow), as shown by [Equation 20](#) and [Equation 21](#). Note that both [Equation 20](#) and [Equation 21](#) involve an *If - then* condition.

$$\text{Max\_Current} = \text{Current\_LSB} \times 32767$$

$$\text{Max\_Current} = 0.06226 \quad (20)$$

If  $\text{Max\_Current} \geq \text{MaxPossible\_I}$  then

$$\text{Max\_Current\_Before\_Overflow} = \text{MaxPossible\_I}$$

Else

$$\text{Max\_Current\_Before\_Overflow} = \text{Max\_Current}$$

End If

(Note that  $\text{Max\_Current}$  is less than  $\text{MaxPossible\_I}$  in this example.)

$$\text{Max\_Current\_Before\_Overflow} = 0.06226$$

$$\text{Max\_ShuntVoltage} = \text{Max\_Current\_Before\_Overflow} \times R_{\text{SHUNT}}$$

$$\text{Max\_ShuntVoltage} = 0.3113 \quad (21)$$

If  $\text{Max\_ShuntVoltage} \geq V_{\text{SHUNT\_MAX}}$

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = V_{\text{SHUNT\_MAX}}$$

Else

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = \text{Max\_ShuntVoltage}$$

End If

(Note that  $\text{Max\_ShuntVoltage}$  is less than  $V_{\text{SHUNT\_MAX}}$  in this example.)

$$\text{Max\_ShuntVoltage\_Before\_Overflow} = 0.3113$$

8. Compute the maximum power with [Equation 22](#).

$$\text{MaximumPower} = \text{Max\_Current\_Before\_Overflow} \times V_{\text{BUS\_MAX}}$$

$$\text{MaximumPower} = 1.992 \quad (22)$$

9. (Optional second calibration step.) Compute the corrected full-scale calibration value based on measured current.

$$\text{TMP513\_Current} = 0.06226$$

$$\text{MeasShuntCurrent} = 0.05$$

$$\text{Corrected\_Full\_Scale\_Cal} = \text{trunc} \left[ \frac{\text{Cal} \times \text{MeasShuntCurrent}}{\text{TMP513\_Current}} \right]$$

$$\text{Corrected\_Full\_Scale\_Cal} = 3462 \quad (23)$$

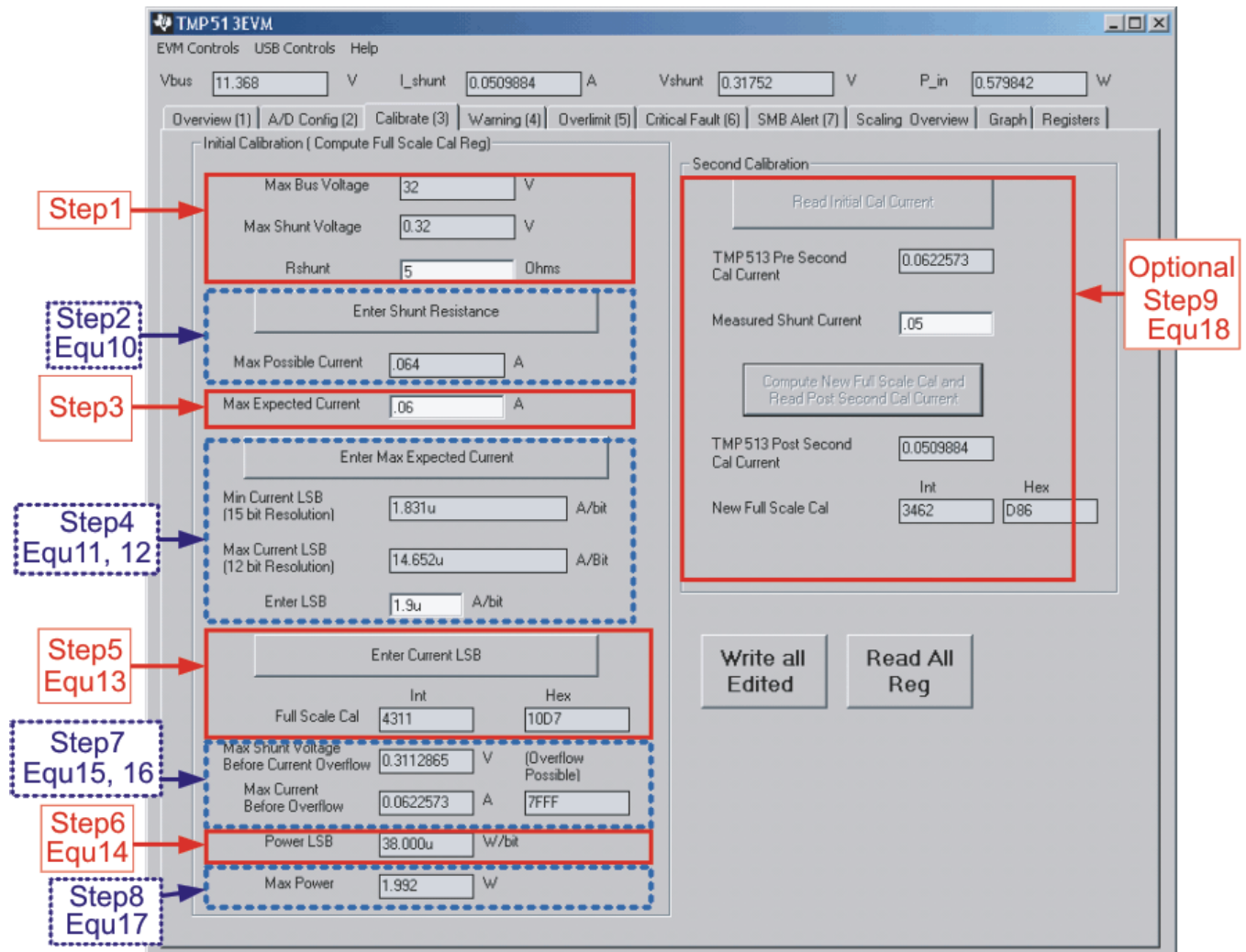


Figure 31. TMP512/513EVM Calibration Software Automatically Computes Calibration Steps 1-9

## REGISTER INFORMATION

The TMP512/13 uses a bank of registers for holding configuration settings, measurement results, maximum/minimum limits, and status information. [Table 3](#) summarizes the TMP512/13 registers. Register contents are updated 4 $\mu$ s after completion of

the write command. Therefore, a 4 $\mu$ s delay is required between the completion of a write to a given register and a subsequent read of that register (without changing the pointer) when using SCL frequencies in excess of 1MHz.

**Table 3. Summary of Register Set**

| POINTER ADDRESS   | REGISTER NAME                            | FUNCTION                                                                                                                                                                          | POWER-ON RESET    |           | TYPE <sup>(1)</sup> |
|-------------------|------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------|-----------|---------------------|
|                   |                                          |                                                                                                                                                                                   | BINARY            | HEX       |                     |
| 00                | Configuration Register 1                 | All-register reset, settings for bus voltage range, PGA Gain, Bus ADC resolution/averaging, Shunt ADC resolution/averaging, one-shot, Operation Mode.                             | 00111001 10011111 | 399F      | R/W                 |
| 01                | Configuration Register 2 TMP512          | Settings for Temperature Continuous conversion, Remote Channels enable, Local Channel enable, resistance correction enable, Conversion rate bits, and GPIO mode bit and readback. | 10111111 10000x00 | BF80/BF84 | R/W                 |
| 01                | Configuration Register 2 TMP513          | Settings for Temperature Continuous conversion, Remote Channels enable, Local Channel enable, resistance correction enable, Conversion rate bits, and GPIO mode bit and readback. | 11111111 10000x00 | FF80/FF84 | R/W                 |
| 02                | Status Register                          | Contains the alert and conversion ready flags.                                                                                                                                    | 00000000 00000000 | 0000      | R                   |
| 03                | SMBus Alert Mask/Enable Control Register | Contains masks to enable/disable the alert functions.                                                                                                                             | 00000000 00000000 | 0000      | R/W                 |
| 04                | Shunt Voltage Result                     | Shunt voltage measurement result.                                                                                                                                                 | 00000000 00000000 | 0000      | R                   |
| 05                | Bus Voltage Result                       | Bus voltage measurement result.                                                                                                                                                   | 00000000 00000000 | 0000      | R                   |
| 06                | Power Result                             | Power measurement result.                                                                                                                                                         | 00000000 00000000 | 0000      | R                   |
| 07                | Shunt Current Result <sup>(2)</sup>      | Contains the value of the current flowing through the shunt resistor.                                                                                                             | 00000000 00000000 | 0000      | R                   |
| 08                | Local Temperature Result                 | Contains local temperature measurement result.                                                                                                                                    | 00000000 00000000 | 0000      | R                   |
| 09                | Remote Temperature Result 1              | Contains remote temperature measurement result.                                                                                                                                   | 00000000 00000000 | 0000      | R                   |
| 0A                | Remote Temperature Result 2              | Contains remote temperature measurement result.                                                                                                                                   | 00000000 00000000 | 0000      | R                   |
| 0B <sup>(3)</sup> | Remote Temperature Result 3              | Contains remote temperature measurement result.                                                                                                                                   | 00000000 00000000 | 0000      | R                   |
| 0C                | Shunt Voltage Positive Limit             | Contains the positive limit for Shunt Voltage.                                                                                                                                    | 00000000 00000000 | 0000      | R/W                 |
| 0D                | Shunt Voltage Negative Limit             | Contains the negative limit for Shunt Voltage.                                                                                                                                    | 00000000 00000000 | 0000      | R/W                 |
| 0E                | Bus Voltage Positive Limit               | Contains the positive limit for Bus Voltage.                                                                                                                                      | 00000000 00000000 | 0000      | R/W                 |
| 0F                | Bus Voltage Negative Limit               | Contains the negative limit for Bus Voltage.                                                                                                                                      | 00000000 00000000 | 0000      | R/W                 |
| 10                | Power Limit                              | Contains the positive limit for Power.                                                                                                                                            | 00000000 00000000 | 0000      | R/W                 |
| 11                | Local Temperature Limit                  | Contains positive limit for local temperature.                                                                                                                                    | 00101010 10000000 | 2A80      | R/W                 |

(1) Type: **R** = Read-Only, **R/W** = Read/Write.

(2) Current Register defaults to '0' because the Calibration Register defaults to '0', yielding a zero current value until the Calibration Register is programmed.

(3) For TMP513 only.

**Table 3. Summary of Register Set (continued)**

| POINTER ADDRESS   | REGISTER NAME              | FUNCTION                                                                                | POWER-ON RESET    |      | TYPE <sup>(4)</sup> |
|-------------------|----------------------------|-----------------------------------------------------------------------------------------|-------------------|------|---------------------|
|                   |                            |                                                                                         | BINARY            | HEX  |                     |
| 12                | Remote Temperature Limit 1 | Contains positive limit for remote temperature.                                         | 00101010 10000000 | 2A80 | R/W                 |
| 13                | Remote Temperature Limit 2 | Contains positive limit for remote temperature.                                         | 00101010 10000000 | 2A80 | R/W                 |
| 14 <sup>(4)</sup> | Remote Temperature Limit 3 | Contains positive limit for remote temperature.                                         | 00101010 10000000 | 2A80 | R/W                 |
| 15                | Shunt Calibration Register | Sets the current that corresponds to a full-scale drop across the shunt.                | 00000000 00000000 | 0000 | R/W                 |
| 16                | n-Factor 1                 | Contains the N-factor value for Remote Channel 1 and Hysteresis for temperature limits. | 00000000 00000000 | 0000 | R/W                 |
| 17                | n-Factor 2                 | Contains the N-factor value for Remote Channel 2.                                       | 00000000 00000000 | 0000 | R/W                 |
| 18 <sup>(4)</sup> | n-Factor 3                 | Contains the N-factor value for Remote Channel 3.                                       | 00000000 00000000 | 0000 | R/W                 |
| 1E/FE             | Manufacturer ID Register   | Contains the Manufacturer ID.                                                           | 01010101 11111111 | 55FF | R                   |
| 1F/FF             | TMP512 Device ID Register  | Contains the Device ID.                                                                 | 00100010 11111111 | 22FF | R                   |
| 1F/FF             | TMP513 Device ID Register  | Contains the Device ID.                                                                 | 00100011 11111111 | 23FF | R                   |

(4) For TMP513 only.

## REGISTER DETAILS

All TMP512/13 registers are 16-bit registers. 16-bit register data are sent in two 8-bit bytes via the two-wire interface.

**Configuration Register 1—Shunt Measurement Configuration 00h (Read/Write)**

| BIT #     | D15 | D14      | D13  | D12 | D11 | D10   | D9    | D8    | D7    | D6    | D5    | D4    | D3    | D2    | D1    | D0    |
|-----------|-----|----------|------|-----|-----|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIT NAME  | RST | ONE-SHOT | BRNG | PG1 | PG0 | BADC4 | BADC3 | BADC2 | BADC1 | SADC4 | SADC3 | SADC2 | SADC1 | MODE3 | MODE2 | MODE1 |
| POR VALUE | 0   | 0        | 1    | 1   | 1   | 0     | 0     | 1     | 1     | 0     | 0     | 1     | 1     | 1     | 1     | 1     |

## Bit Descriptions

|                 |                                                                                                                                                                  |
|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>RST:</b>     | <b>Reset Bit</b>                                                                                                                                                 |
| Bit 15          | Setting this bit to '1' generates a system reset that is the same as power-on reset. Resets all registers to default values; this bit self-clears.               |
| <b>ONE-SHOT</b> | <b>One-Shot Bit</b>                                                                                                                                              |
| Bit 14          | Setting this bit to '1' generates a one-shot command.                                                                                                            |
| <b>BRNG:</b>    | <b>Bus Voltage Range</b>                                                                                                                                         |
| Bit 13          | 0 = 16V FSR<br>1 = 32V FSR (default value)                                                                                                                       |
| <b>PG:</b>      | <b>PGA (Shunt Voltage Only)</b>                                                                                                                                  |
| Bits 12, 11     | Sets PGA gain and range. Note that the PGA defaults to ÷8 (320mV range). <a href="#">Table 4</a> shows the gain and range for the various product gain settings. |

**Table 4. PG Bit Settings<sup>(1)</sup>**

| PG1 | PG0 | GAIN | RANGE  |
|-----|-----|------|--------|
| 0   | 0   | 1    | ±40mV  |
| 0   | 1   | ÷2   | ±80mV  |
| 1   | 0   | ÷4   | ±160mV |
| 1   | 1   | ÷8   | ±320mV |

(1) Shaded values are default.

**BADC:** **BADC Bus ADC Resolution/Averaging**

Bits 10–7

These bits adjust the Bus ADC resolution (9-, 10-, 11-, or 12-bit) or set the number of samples used when averaging results for the Bus Voltage Register (05h).

**SADC:** **SADC Shunt ADC Resolution/Averaging**

Bits 6–3

These bits adjust the Shunt ADC resolution (9-, 10-, 11-, or 12-bit) or set the number of samples used when averaging results for the Shunt Voltage Register (04h).

BADC (Bus) and SADC (Shunt) ADC resolution/averaging and conversion time settings are shown in [Table 5](#).

**Table 5. ADC Settings<sup>(1)</sup>**

| ADC4 | ADC3             | ADC2 | ADC1 | MODE/SAMPLES | CONVERSION TIME |
|------|------------------|------|------|--------------|-----------------|
| 0    | X <sup>(2)</sup> | 0    | 0    | 9-bit        | 105µs           |
| 0    | X <sup>(2)</sup> | 0    | 1    | 10-bit       | 185µs           |
| 0    | X <sup>(2)</sup> | 1    | 0    | 11-bit       | 345µs           |
| 0    | X <sup>(2)</sup> | 1    | 1    | 12-bit       | 665µs           |
| 1    | 0                | 0    | 0    | 12-bit       | 665µs           |
| 1    | 0                | 0    | 1    | 2            | 1.3ms           |
| 1    | 0                | 1    | 0    | 4            | 2.58ms          |
| 1    | 0                | 1    | 1    | 8            | 5.13ms          |
| 1    | 1                | 0    | 0    | 16           | 10.25ms         |
| 1    | 1                | 0    | 1    | 32           | 20.49ms         |
| 1    | 1                | 1    | 0    | 64           | 40.97ms         |
| 1    | 1                | 1    | 1    | 128          | 81.92ms         |

(1) Shaded values are default.

(2) X = Don't care.

**MODE:** **Operating Mode**

Bits 2–0

Selects continuous, triggered, or power-down mode of operation. These bits default to continuous shunt and bus measurement mode. The mode settings are shown in [Table 6](#).

**Table 6. Mode Settings<sup>(1)</sup>**

| MODE3 | MODE2 | MODE1 | MODE                                    |
|-------|-------|-------|-----------------------------------------|
| 0     | 0     | 0     | Power-Down <sup>(2)</sup>               |
| 0     | 0     | 1     | Shunt Voltage, Triggered <sup>(3)</sup> |
| 0     | 1     | 0     | Bus Voltage, Triggered <sup>(3)</sup>   |
| 0     | 1     | 1     | Shunt and Bus, Triggered <sup>(3)</sup> |
| 1     | 0     | 0     | ADC Off (disabled) <sup>(4)</sup>       |
| 1     | 0     | 1     | Shunt Voltage, Continuous               |
| 1     | 1     | 0     | Bus Voltage, Continuous                 |
| 1     | 1     | 1     | Shunt and Bus, Continuous               |

(1) Shaded values are default.

(2) Combination '000' stops converter immediately.

(3) In triggered modes the converter goes to power down. It can be triggered by a write of '1' to bit 14 (One-Shot) in Configuration Register 1 or by the delay scheme of the temperature sensor core. See [Table 7](#).

(4) Combination '100' stops the converter at conversion end.

**Configuration Register 2—Temperature Measurement Configuration 01h (Read/Write)**

| BIT #            | D15  | D14  | D13  | D12  | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1   | D0   |
|------------------|------|------|------|------|-----|-----|----|----|----|----|----|----|----|----|------|------|
| BIT NAME         | CONT | REN3 | REN2 | REN1 | LEN | RC  | R2 | R1 | R0 | —  | —  | —  | —  | GP | GPM1 | GPM0 |
| TMP512 POR VALUE | 1    | 0    | 1    | 1    | 1   | 1   | 1  | 1  | 1  | 0  | 0  | 0  | 0  | X  | 0    | 0    |
| TMP513 POR VALUE | 1    | 1    | 1    | 1    | 1   | 1   | 1  | 1  | 1  | 0  | 0  | 0  | 0  | X  | 0    | 0    |

**CONT:**
**Continuous Conversion**

Bit 15

0: When all bits 14 to 11 are '0', the temp sensor core goes immediately to shutdown mode. When all bits 14 to 11 are not '0', the temp sensor core stops when all enabled conversions are done. When this bit is '0', a one-shot command can be triggered by writing a "1" to bit 14 of Configuration Register 1.  
1: Continuous temperature conversion mode.

**REN3:**
**Remote Channel 3 Enable (TMP513 only)**

Bit 14

0: Remote channel 3 disabled.  
1: Remote channel 3 enabled.

**REN2:**
**Remote Channel 2 Enable**

Bit 13

0: Remote channel 2 disabled.  
1: Remote channel 2 enabled.

**REN1:**
**Remote Channel 1 Enable**

Bit 12

0: Remote channel 1 disabled.  
1: Remote channel 1 enabled.

**LEN:**
**Local Temperature Enable**

Bit 11

0: Local temperature disabled.  
1: Local temperature enabled.

**RC:**
**Resistance Correction**

Bit 10

0: Resistance correction disabled.  
1: Resistance correction enabled.

**R2, R1, R0:**
**Conversion Rate**

Bits 9-7

These bits set the conversion rate as shown in [Table 7](#).

**Table 7. Conversion Rate Settings<sup>(1)</sup>**

| R2 | R1 | R0 | CONVERSIONS/SEC  |
|----|----|----|------------------|
| 0  | 0  | 0  | 0.0625           |
| 0  | 0  | 1  | 0.125            |
| 0  | 1  | 0  | 0.25             |
| 0  | 1  | 1  | 0.5              |
| 1  | 0  | 0  | 1                |
| 1  | 0  | 1  | 2                |
| 1  | 1  | 0  | 4 <sup>(2)</sup> |
| 1  | 1  | 1  | 8 <sup>(3)</sup> |

(1) Shaded values are default.

(2) Conversion rate shown is for only one or two enabled measurement channels. When three channels are enabled, the conversion rate is 2 and 2/3 conversions per second. When four channels are enabled, the conversion rate is 2 per second.

(3) Conversion rate shown is for only one enabled measurement channel. When two channels are enabled, the conversion rate is 4 conversions per second. When three channels are enabled, the conversion rate is 2 and 2/3 conversions per second.

When all of the following conditions are met, the temperature sensor core triggers a single conversion of the voltage measurement core at the same rate as the conversion rate shown by bits R2 to R0.

- The conversion rate is different than '111';
- There is at least one enabled temperature channel; and
- The voltage measurement core is in triggered mode of operation.

The temperature sensor core triggers a single conversion of the ADC core at the same rate as the conversion rate shown by R2 to R0.

**GP:** **GPIO Read-Back**

Bit 2 Shows the state of the GPIO pin.

**GPM:** **GPIO Mode**

Bits 1-0 The GPIO mode settings are shown in [Table 8](#). GPIO should not be left floating at start-up.

**Table 8. GPIO Mode Settings<sup>(1)</sup>**

| GPM[1] | GPM[0] | GPIO PIN | DESCRIPTION                                |
|--------|--------|----------|--------------------------------------------|
| 0      | 0      | Hi-Z     | Use as an input for either of these modes. |
| 0      | 1      | Hi-Z     |                                            |
| 1      | 0      | 0        | Use to output 0 to GPIO pin                |
| 1      | 1      | 1        | Use to output 1 to GPIO pin                |

(1) Shaded values are default.

### Status Register 02h (Read)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9  | D8  | D7  | D6  | D5  | D4   | D3   | D2  | D1 | D0 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|-----|----|----|
| BIT NAME  | SHP | SHN | BVP | BVN | PWR | LCL | RM1 | RM2 | RM3 | CVR | CRT | PVLD | SMBA | OVF | —  | —  |
| POR VALUE | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0    | 0    | 0   | 0  | 0  |

The Status Register flags activate whenever any limit is violated, and latch if the alert is in *latch* mode. In latch mode, these flags are cleared when the Status Register is read (if the limit is exceeded, then at next conversion end, the flag sets again). In transparent mode, these flags are cleared when any corresponding limit is not violated any longer.

After power-up and initial setup, the Status Register should be read once to clear any flags set as a result of power-up values prior to setup.

### Bit Descriptions

**SHP: Shunt Positive Over-Voltage**

Bit 15 This bit is set to '1' when the result in the Shunt Voltage Register (04h) exceeds the level set in the Shunt Positive Limit Register (0Ch).

**SHN: Shunt Negative Under-Voltage**

Bit 14 This bit is set to '1' when the result in the Shunt Voltage Register (04h) goes below the level set in the Shunt Negative Limit Register (0Dh).

**BVP: Bus Positive Over-Voltage**

Bit 13 This bit is set to '1' when the result in the Bus Voltage Register (05h) exceeds the level set in the Bus Voltage Positive Limit Register (0Eh).

**BVN: Bus Negative Under-Voltage**

Bit 12 This bit is set to '1' when the result in the Bus Voltage Register (05h) goes below the level set in the Bus Voltage Negative Limit Register (0Fh).

**PWR: Power Over-Limit**

Bit 11 This bit is set to '1' when the result in the Power Register (06h) exceeds the level set in the Power Limit Register (10h).

**LCL: Local Temperature Over-Limit**

Bit 10 This bit is set to '1' when the result in the Local Temperature Result Register (08h) exceeds the level set in the Local Temperature Limit Register (11h) plus half of the temperature hysteresis. It clears in transparent mode when the result in the Local Temperature Result Register (08h) is below the level set in the Local Temperature Limit Register (11h) minus half of the temperature hysteresis.

**RM1: Remote Temperature 1 Over-Limit**

Bit 9 This bit is set to '1' when the result in the Remote Temperature Result 1 Register (09h) exceeds the level set in the Remote Temperature Limit 1 Register (12h) plus half of the temperature hysteresis. It also sets if, during conversion of remote channel 1, an open diode condition was detected. It clears in transparent mode when the result in the Remote Temperature Result 1 Register (09h) is below the level set in the Remote Temperature Limit 1 Register (12h) minus half of the temperature hysteresis, and the last conversion of channel 1 was done without *open-diode* detection.

**RM2: Remote Temperature 2 Over-Limit**

Bit 8 This bit is set to '1' when the result in the Remote Temperature Result 2 Register (0Ah) exceeds the level set in the Remote Temperature Limit 2 Register (13h) plus half of the temperature hysteresis. It also sets if, during conversion of remote channel 2, an open diode condition was detected. It clears in transparent mode when the result in the Remote Temperature Result 2 Register (0Ah) is below the level set in the Remote Temperature Limit 2 Register (13h) minus half of the temperature hysteresis, and the last conversion of channel 2 was done without *open-diode* detection.

## Bit Descriptions (continued)

|              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
|--------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>RM3:</b>  | <b>Remote Temperature 3 Over-Limit (TMP513 only)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| Bit 7        | This bit is set to '1' when the result in the Remote Temperature Result 3 Register (0Bh) exceeds the level set in the Remote Temperature Limit 3 Register (14h) plus half of the temperature hysteresis. It sets also if during conversion of remote channel 3 an open diode condition was detected. It clears in transparent mode when the result in the Remote Temperature Result 3 Register (0Bh) is below the level set in the Remote Temperature Limit 3 Register (14h) minus half of the temperature hysteresis and the last conversion of channel 3 was done without <i>open-diode</i> detection. |
| <b>CVR:</b>  | <b>Conversion Ready</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| Bit 6        | The Conversion Ready line is provided to help coordinate one-shot conversions for shunt voltage, bus voltage, current and power measurements. The Conversion bit is set after all conversions, averaging, and multiplication events are complete. Conversion Ready clears under the following conditions: <ul style="list-style-type: none"> <li>1. Writing to the One-Shot bit in Configuration Register 1.</li> <li>2. Reading the Status Register.</li> </ul>                                                                                                                                         |
| <b>CRT:</b>  | <b>Conversion Ready Temperature</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
| Bit 5        | The Conversion Ready Temperature line is provided to help coordinate one-shot conversions for local and remote temperature measurements. The Conversion bit is set after all enabled channels complete the respective conversions. Conversion Ready Temperature clears under the following conditions: <ul style="list-style-type: none"> <li>1. Writing to the One-Shot bit in Configuration Register 1.</li> <li>2. Reading the Status Register.</li> </ul>                                                                                                                                            |
| <b>PVLD:</b> | <b>Power Valid Error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| Bit 4        | In latch mode, this bit is set to '1' when the brown-out detect fires during a conversion. The flag sets to '1' at the conversion end. It clears by reading the Status Register.                                                                                                                                                                                                                                                                                                                                                                                                                         |
| <b>SMBA:</b> | <b>SMBus Alert</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| Bit 3        | This bit is set when the Alert pin is active. When in latch mode, it clears only on reading the Status Register, disabling the SMBus Alert function, or using SMBus Alert Response. In transparent mode, it clears when the triggering condition is not present.                                                                                                                                                                                                                                                                                                                                         |
| <b>OVF:</b>  | <b>Math Overflow</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| Bit 2        | This bit is set to '1' if an arithmetic operation resulted in an overflow error. It indicates that current and power data may be meaningless. It does not set the Alert pin.                                                                                                                                                                                                                                                                                                                                                                                                                             |

**SMBus Alert Register—Mask and Alert Control Functions 03h (Read/Write)**

| BIT #     | D15  | D14  | D13  | D12  | D11  | D10  | D9  | D8  | D7  | D6   | D5   | D4   | D3  | D2  | D1  | D0    |
|-----------|------|------|------|------|------|------|-----|-----|-----|------|------|------|-----|-----|-----|-------|
| BIT NAME  | SHPM | SHNM | BVPM | BVNM | PWRM | LCLM | R1M | R2M | R3M | CVRM | CRTM | PVLM | FC1 | FC0 | POL | LATCH |
| POR VALUE | 0    | 0    | 0    | 0    | 0    | 0    | 0   | 0   | 0   | 0    | 0    | 0    | 0   | 0   | 0   | 0     |

Bits D4–D15 of the SMBus Alert Register mask correspond to bits D4 to D15 of the Status Register to prevent them from initiating an SMBus Alert. It does not prevent the Status Register bit from setting. Writing a '0' to an SMBus Alert Mask bit masks it from activating the SMBus Alert. All default values are '0'.

**Bit Descriptions**

|              |                                                                                                                                      |
|--------------|--------------------------------------------------------------------------------------------------------------------------------------|
| <b>SHPM:</b> | <b>Shunt Positive Over-Voltage Mask</b>                                                                                              |
| Bit 15       | 0: SHP flag in Status Register cannot activate Alert pin.<br>1: SHP flag (when set to '1') in Status Register activates Alert pin.   |
| <b>SHNM:</b> | <b>Shunt Negative Under-Voltage Mask</b>                                                                                             |
| Bit 14       | 0: SHN flag in Status Register cannot activate Alert pin.<br>1: SHN flag (when set to '1') in Status Register activates Alert pin.   |
| <b>BVPM:</b> | <b>Bus Voltage Positive Over-Voltage Mask</b>                                                                                        |
| Bit 13       | 0: BVP flag in Status Register cannot activate Alert pin.<br>1: BVP flag (when set to '1') in Status Register activates Alert pin.   |
| <b>BVNM:</b> | <b>Bus Voltage Negative Under-Voltage Mask</b>                                                                                       |
| Bit 12       | 0: BVN flag in Status Register cannot activate Alert pin.<br>1: BVN flag (when set to '1') in Status Register activates Alert pin.   |
| <b>PWRM:</b> | <b>Power Over-Limit Mask</b>                                                                                                         |
| Bit 11       | 0: PWR flag in Status Register cannot activate Alert pin.<br>1: PWR flag (when set to '1') in Status Register activates Alert pin.   |
| <b>LCLM:</b> | <b>Local Temperature Over-Limit Mask</b>                                                                                             |
| Bit 10       | 0: LCL flag in Status Register cannot activate Alert pin.<br>1: LCL flag (when set to '1') in Status Register activates Alert pin.   |
| <b>R1M:</b>  | <b>Remote Temperature1 Over-Limit Mask</b>                                                                                           |
| Bit 9        | 0: RM1 flag in Status Register cannot activate Alert pin.<br>1: RM1 flag (when set to '1') in Status Register activates Alert pin.   |
| <b>R2M:</b>  | <b>Remote Temperature2 Over-Limit Mask</b>                                                                                           |
| Bit 8        | 0: RM2 flag in Status Register cannot activate Alert pin.<br>1: RM2 flag (when set to '1') in Status Register activates Alert pin.   |
| <b>R3M:</b>  | <b>Remote Temperature3 Over-Limit Mask (TMP513 only)</b>                                                                             |
| Bit 7        | 0: RM3 flag in Status Register cannot activate Alert pin.<br>1: RM3 flag (when set to '1') in Status Register activates Alert pin.   |
| <b>CVRM:</b> | <b>Conversion Ready Mask</b>                                                                                                         |
| Bit 6        | 0: CVR flag in Status Register cannot activate Alert pin.<br>1: CVR flag (when set to '1') in Status Register activates Alert pin.   |
| <b>CRTM:</b> | <b>Conversion Ready Temperature Mask</b>                                                                                             |
| Bit 5        | 0: CRT flag in Status Register cannot activate Alert pin.<br>1: CRT flag (when set to '1') in Status Register activates Alert pin.   |
| <b>PVLM:</b> | <b>Power Valid Limit Mask</b>                                                                                                        |
| Bit 4        | 0: PVLD flag in Status Register cannot activate Alert pin.<br>1: PVLD flag (when set to '1') in Status Register activates Alert pin. |

## Bit Descriptions (continued)

### FC0, FC1

#### Fault Count Control Bits

The Fault Count Control Bits affect flags in SMBus Alert Register bits D15-D7.

Bit 3, 2

00: These flags are activated after the first conversion result with a violated limit.

01: These flags are activated after the second consecutive conversion result with a violated limit.

10: These flags are activated after the fourth consecutive conversion result with a violated limit.

11: These flags are activated after the eighth consecutive conversion result with a violated limit.

### POL:

#### Alert Polarity

Bit 1

0: Alert pin is active low.

1: Alert pin is active high.

### LATCH:

#### Alert Mode of Operation

Bit 0

0: Alert pin works in transparent mode. The SMB alert response function does not function. Alert is deasserted when the triggering condition goes away.

1: Alert pin works in latch mode. The SMB alert response function functions when Alert pin is active. Alert will remain asserted even if the triggering condition goes away. Alert can be deasserted by reading the Status register (02h), using the SMBus Alert response function, resetting the part, or by disabling the alert function using the mask bits.

## Shunt Voltage Register 04h (Read-Only)

The Shunt Voltage Register stores the current shunt voltage reading,  $V_{SHUNT}$ . Shunt Voltage Register bits are shifted according to the PGA setting selected in Configuration Register 1 (00h). When multiple sign bits are present, they will all be the same value. Negative numbers are represented in twos complement format. Generate the twos complement of a negative number by complementing the absolute value binary number and adding 1. Extend the sign, denoting a negative number by setting the MSB = '1'. Extend the sign to any additional sign bits to form the 16-bit word.

Example: For a value of  $V_{SHUNT} = -320\text{mV}$ :

1. Take the absolute value (include accuracy to 0.01mV) ==> 320.00
2. Translate this number to a whole decimal number ==> 32000
3. Convert it to binary ==> 111 1101 0000 0000
4. Complement the binary result : 000 0010 1111 1111
5. Add 1 to the Complement to create the twos complement formatted result ==> 000 0011 0000 0000
6. Extend the sign and create the 16-bit word: 1000 0011 0000 0000 = 8300h (Remember to extend the sign to all sign-bits, as necessary based on the PGA setting.)

At PGA =  $\div 8$ , full-scale range =  $\pm 320\text{mV}$  (decimal = 32000, positive value hex = 7D00, negative value hex = 8300), and LSB =  $10\mu\text{V}$ .

| BIT #     | D15  | D14    | D13    | D12    | D11    | D10    | D9    | D8    | D7    | D6    | D5    | D4    | D3    | D2    | D1    | D0    |
|-----------|------|--------|--------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIT NAME  | SIGN | SD14_8 | SD13_8 | SD12_8 | SD11_8 | SD10_8 | SD9_8 | SD8_8 | SD7_8 | SD6_8 | SD5_8 | SD4_8 | SD3_8 | SD2_8 | SD1_8 | SD0_8 |
| POR VALUE | 0    | 0      | 0      | 0      | 0      | 0      | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

At PGA =  $\div 4$ , full-scale range =  $\pm 160\text{mV}$  (decimal = 16000, positive value hex = 3E80, negative value hex = C180), and LSB =  $10\mu\text{V}$ .

| BIT #     | D15  | D14  | D13    | D12    | D11    | D10    | D9    | D8    | D7    | D6    | D5    | D4    | D3    | D2    | D1    | D0    |
|-----------|------|------|--------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIT NAME  | SIGN | SIGN | SD13_4 | SD12_4 | SD11_4 | SD10_4 | SD9_4 | SD8_4 | SD7_4 | SD6_4 | SD5_4 | SD4_4 | SD3_4 | SD2_4 | SD1_4 | SD0_4 |
| POR VALUE | 0    | 0    | 0      | 0      | 0      | 0      | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

At PGA =  $\div 2$ , full-scale range =  $\pm 80\text{mV}$  (decimal = 8000, positive value hex = 1F40, negative value hex = E0C0), and LSB =  $10\mu\text{V}$ .

| BIT #     | D15  | D14  | D13  | D12    | D11    | D10    | D9    | D8    | D7    | D6    | D5    | D4    | D3    | D2    | D1    | D0    |
|-----------|------|------|------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIT NAME  | SIGN | SIGN | SIGN | SD12_2 | SD11_2 | SD10_2 | SD9_2 | SD8_2 | SD7_2 | SD6_2 | SD5_2 | SD4_2 | SD3_2 | SD2_2 | SD1_2 | SD0_2 |
| POR VALUE | 0    | 0    | 0    | 0      | 0      | 0      | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

At PGA =  $\div 1$ , full-scale range =  $\pm 40\text{mV}$  (decimal = 4000, positive value hex = 0FA0, negative value hex = F060), and LSB =  $10\mu\text{V}$ .

| BIT #     | D15  | D14  | D13  | D12  | D11    | D10    | D9    | D8    | D7    | D6    | D5    | D4    | D3    | D2    | D1    | D0    |
|-----------|------|------|------|------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| BIT NAME  | SIGN | SIGN | SIGN | SIGN | SD11_1 | SD10_1 | SD9_1 | SD8_1 | SD7_1 | SD6_1 | SD5_1 | SD4_1 | SD3_1 | SD2_1 | SD1_1 | SD0_1 |
| POR VALUE | 0    | 0    | 0    | 0    | 0      | 0      | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     | 0     |

**Table 9. Shunt Voltage Register Format<sup>(1)</sup>**

| V <sub>SHUNT</sub><br>Reading (mV) | Decimal<br>Value | PGA = ÷ 8<br>(D15.....D0) | PGA = ÷ 4<br>(D15.....D0) | PGA = ÷ 2<br>(D15.....D0) | PGA = ÷ 1<br>(D15.....D0) |
|------------------------------------|------------------|---------------------------|---------------------------|---------------------------|---------------------------|
| 320.02                             | 32002            | 0111 1101 0000 0000       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 320.01                             | 32001            | 0111 1101 0000 0000       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 320.00                             | 32000            | 0111 1101 0000 0000       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 319.99                             | 31999            | 0111 1100 1111 1111       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 319.98                             | 31998            | 0111 1100 1111 1110       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| 160.02                             | 16002            | 0011 1110 1000 0010       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 160.01                             | 16001            | 0011 1110 1000 0001       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 160.00                             | 16000            | 0011 1110 1000 0000       | 0011 1110 1000 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 159.99                             | 15999            | 0011 1110 0111 1111       | 0011 1110 0111 1111       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 159.98                             | 15998            | 0011 1110 0111 1110       | 0011 1110 0111 1110       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| 80.02                              | 8002             | 0001 1111 0100 0010       | 0001 1111 0100 0010       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 80.01                              | 8001             | 0001 1111 0100 0001       | 0001 1111 0100 0001       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 80.00                              | 8000             | 0001 1111 0100 0000       | 0001 1111 0100 0000       | 0001 1111 0100 0000       | 0000 1111 1010 0000       |
| 79.99                              | 7999             | 0001 1111 0011 1111       | 0001 1111 0011 1111       | 0001 1111 0011 1111       | 0000 1111 1010 0000       |
| 79.98                              | 7998             | 0001 1111 0011 1110       | 0001 1111 0011 1110       | 0001 1111 0011 1110       | 0000 1111 1010 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| 40.02                              | 4002             | 0000 1111 1010 0010       | 0000 1111 1010 0010       | 0000 1111 1010 0010       | 0000 1111 1010 0000       |
| 40.01                              | 4001             | 0000 1111 1010 0001       | 0000 1111 1010 0001       | 0000 1111 1010 0001       | 0000 1111 1010 0000       |
| 40.00                              | 4000             | 0000 1111 1010 0000       | 0000 1111 1010 0000       | 0000 1111 1010 0000       | 0000 1111 1010 0000       |
| 39.99                              | 3999             | 0000 1111 1001 1111       | 0000 1111 1001 1111       | 0000 1111 1001 1111       | 0000 1111 1001 1111       |
| 39.98                              | 3998             | 0000 1111 1001 1110       | 0000 1111 1001 1110       | 0000 1111 1001 1110       | 0000 1111 1001 1110       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| 0.02                               | 2                | 0000 0000 0000 0010       | 0000 0000 0000 0010       | 0000 0000 0000 0010       | 0000 0000 0000 0010       |
| 0.01                               | 1                | 0000 0000 0000 0001       | 0000 0000 0000 0001       | 0000 0000 0000 0001       | 0000 0000 0000 0001       |
| 0                                  | 0                | 0000 0000 0000 0000       | 0000 0000 0000 0000       | 0000 0000 0000 0000       | 0000 0000 0000 0000       |
| –0.01                              | –1               | 1111 1111 1111 1111       | 1111 1111 1111 1111       | 1111 1111 1111 1111       | 1111 1111 1111 1111       |
| –0.02                              | –2               | 1111 1111 1111 1110       | 1111 1111 1111 1110       | 1111 1111 1111 1110       | 1111 1111 1111 1110       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| –39.98                             | –3998            | 1111 0000 0110 0010       | 1111 0000 0110 0010       | 1111 0000 0110 0010       | 1111 0000 0110 0010       |
| –39.99                             | –3999            | 1111 0000 0110 0001       | 1111 0000 0110 0001       | 1111 0000 0110 0001       | 1111 0000 0110 0001       |
| –40.00                             | –4000            | 1111 0000 0110 0000       | 1111 0000 0110 0000       | 1111 0000 0110 0000       | 1111 0000 0110 0000       |
| –40.01                             | –4001            | 1111 0000 0101 1111       | 1111 0000 0101 1111       | 1111 0000 0101 1111       | 1111 0000 0110 0000       |
| –40.02                             | –4002            | 1111 0000 0101 1110       | 1111 0000 0101 1110       | 1111 0000 0101 1110       | 1111 0000 0110 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| –79.98                             | –7998            | 1110 0000 1100 0010       | 1110 0000 1100 0010       | 1110 0000 1100 0010       | 1111 0000 0110 0000       |
| –79.99                             | –7999            | 1110 0000 1100 0001       | 1110 0000 1100 0001       | 1110 0000 1100 0001       | 1111 0000 0110 0000       |
| –80.00                             | –8000            | 1110 0000 1100 0000       | 1110 0000 1100 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –80.01                             | –8001            | 1110 0000 1011 1111       | 1110 0000 1011 1111       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –80.02                             | –8002            | 1110 0000 1011 1110       | 1110 0000 1011 1110       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| –159.98                            | –15998           | 1100 0001 1000 0010       | 1100 0001 1000 0010       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –159.99                            | –15999           | 1100 0001 1000 0001       | 1100 0001 1000 0001       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –160.00                            | –16000           | 1100 0001 1000 0000       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –160.01                            | –16001           | 1100 0001 0111 1111       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –160.02                            | –16002           | 1100 0001 0111 1110       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| ⋮                                  | ⋮                | ⋮                         | ⋮                         | ⋮                         | ⋮                         |
| –319.98                            | –31998           | 1000 0011 0000 0010       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –319.99                            | –31999           | 1000 0011 0000 0001       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –320.00                            | –32000           | 1000 0011 0000 0000       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –320.01                            | –32001           | 1000 0011 0000 0000       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |
| –320.02                            | –32002           | 1000 0011 0000 0000       | 1100 0001 1000 0000       | 1110 0000 1100 0000       | 1111 0000 0110 0000       |

(1) Out-of-range values are shaded.

### Bus Voltage Register 05h (Read-Only)

The Bus Voltage Register stores the most recent bus voltage reading,  $V_{BUS}$ .

At full-scale range = 32V (decimal = 8000, hex = 1F40), and LSB = 4mV.

| BIT #     | D15  | D14  | D13  | D12 | D11 | D10 | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2 | D1 | D0 |
|-----------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|
| BIT NAME  | BD12 | BD11 | BD10 | BD9 | BD8 | BD7 | BD6 | BD5 | BD4 | BD3 | BD2 | BD1 | BD0 | —  | —  | —  |
| POR VALUE | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0  | 0  |

At full-scale range = 16V (decimal = 4000, hex = 0FA0), and LSB = 4mV.

| BIT #     | D15 | D14  | D13  | D12 | D11 | D10 | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2 | D1 | D0 |
|-----------|-----|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|
| BIT NAME  | 0   | BD11 | BD10 | BD9 | BD8 | BD7 | BD6 | BD5 | BD4 | BD3 | BD2 | BD1 | BD0 | —  | —  | —  |
| POR VALUE | 0   | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0  | 0  |

### Power Register 06h (Read-Only)

Full-scale range and LSB are set by the Calibration Register. See the [Programming the TMP512/13 Power Measurement Engine](#) section.

| BIT #     | D15  | D14  | D13  | D12  | D11  | D10  | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2  | D1  | D0  |
|-----------|------|------|------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| BIT NAME  | PD15 | PD14 | PD13 | PD12 | PD11 | PD10 | PD9 | PD8 | PD7 | PD6 | PD5 | PD4 | PD3 | PD2 | PD1 | PD0 |
| POR VALUE | 0    | 0    | 0    | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   |

The Power Register records power in watts by multiplying the values of the current with the value of the bus voltage according to the equation:

$$\text{Power} = \frac{\text{Current} \times \text{BusVoltage}}{5000}$$

### Current Register 07h (Read-Only)

Full-scale range and LSB depend on the value entered in the Calibration Register. See the [Programming the TMP512/13 Power Measurement Engine](#) section. Negative values are stored in twos complement format.

| BIT #     | D15   | D14  | D13  | D12  | D11  | D10  | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2  | D1  | D0  |
|-----------|-------|------|------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| BIT NAME  | CSIGN | CD14 | CD13 | CD12 | CD11 | CD10 | CD9 | CD8 | CD7 | CD6 | CD5 | CD4 | CD3 | CD2 | CD1 | CD0 |
| POR VALUE | 0     | 0    | 0    | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   |

The value of the Current Register is calculated by multiplying the value in the Shunt Voltage Register with the value in the Calibration Register according to the equation:

$$\text{Current} = \frac{\text{ShuntVoltage} \times \text{Calibration Register}}{4096}$$

## Local Temperature Result Register 08h (Read-Only)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1                       | D0 |
|-----------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|--------------------------|----|
| BIT NAME  | T12 | T11 | T10 | T9  | T8  | T7  | T6 | T5 | T4 | T3 | T2 | T1 | T0 | —  | $\overline{\text{PVLD}}$ | —  |
| POR VALUE | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0                        | 0  |

The data format is 13 bits, 0.0625°C per bit. Full-scale allows display up to ±256°C.

**T12–T0:** **Temperature Result**

Bits 15-3 Shows the temperature result according to the format shown in [Table 10](#).

**Table 10. 13-Bit Temperature Data Format**

| TEMPERATURE (°C) | DIGITAL OUTPUT (BINARY) | HEX  |
|------------------|-------------------------|------|
| 150              | 0 1001 0110 0000        | 0960 |
| 128              | 0 1000 0000 0000        | 0800 |
| 127.9375         | 0 0111 1111 1111        | 07FF |
| 100              | 0 0110 0100 0000        | 0640 |
| 80               | 0 0101 0000 0000        | 0500 |
| 75               | 0 0100 1011 0000        | 04B0 |
| 50               | 0 0011 0010 0000        | 0320 |
| 25               | 0 0001 1001 0000        | 0190 |
| 0.25             | 0 0000 0000 0100        | 0004 |
| 0                | 0 0000 0000 0000        | 0000 |
| –0.25            | 1 1111 1111 1100        | 1FFC |
| –25              | 1 1110 0111 0000        | 1E70 |
| –55              | 1 1100 1001 0000        | 1C90 |

For positive temperatures (for example, +50°C):

Twos complement is not performed on positive numbers. Therefore, simply convert the number to binary code with the 13-bit, left-justified format, and MSB = 0 to denote a positive sign.

Example: (+50°C)/(0.0625°C/count) = 800 = 320h = 0011 0010 0000

For negative temperatures (for example, –25°C):

Generate the twos complement of a negative number by complementing the absolute value binary number and adding 1. Denote a negative number with MSB = 1.

Example: (–25°C)/(0.0625°C/count) = 400 = 190h = 0001 1001 0000

Twos complement format: 1110 0110 1111 + 1 = 1110 0111 0000

**PVLD** **Power Valid Flag**

Bit 1 This bit is the power valid flag.

The TMP512/13 do not start a temperature conversion if the power supply is not valid. If the voltage is less than 2.7V during a conversion, the PVLD bit is set to '1' and the temperature result may be incorrect.

## Remote Temperature Result 1 Register 09h, Remote Temperature Result 2 Register 0Ah, Remote Temperature Result 3 Register (TMP513 Only) 0Bh (Read-Only)

| BIT #     | D15  | D14  | D13  | D12 | D11 | D10 | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2 | D1   | D0 |
|-----------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|------|----|
| BIT NAME  | RT12 | RT11 | RT10 | RT9 | RT8 | RT7 | RT6 | RT5 | RT4 | RT3 | RT2 | RT1 | RT0 | —  | PVLD | DO |
| POR VALUE | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0    | 0  |

The data format is 13 bits, 0.0625°C per bit. Full-scale allows display up to ±256°C.

### RT12–RT0: Remote Temperature Result

Bits 3-15 Shows the remote temperature measurement result.

### PVLD Power Valid Flag

Bit 1 This bit is the power valid flag.

The TMP512/13 do not start a temperature conversion if the power supply is not valid. If the voltage is less than 2.7V during a conversion, the PVLD bit is set to '1' and the temperature result may be incorrect.

### DO Diode Open Flag

Bit 0 This bit is the diode open flag.

If the Remote Channels are open during a conversion, then Diode Open bit is set at the end of the conversion.

## Shunt Positive Limit Register 0Ch (Read/Write)

At full-scale range = ±320mV, 15-bit + sign, LSB = 10μV (decimal = 32000, positive value hex = 7D00, negative value hex = 8300).

| BIT #     | D15      | D14   | D13   | D12   | D11   | D10   | D9   | D8   | D7   | D6   | D5   | D4   | D3   | D2   | D1   | D0   |
|-----------|----------|-------|-------|-------|-------|-------|------|------|------|------|------|------|------|------|------|------|
| BIT NAME  | SWP SIGN | SWP14 | SWP13 | SWP12 | SWP11 | SWP10 | SWP9 | SWP8 | SWP7 | SWP6 | SWP5 | SWP4 | SWP3 | SWP2 | SWP1 | SWP0 |
| POR VALUE | 0        | 0     | 0     | 0     | 0     | 0     | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    |

## Shunt Negative Limit Register 0Dh (Read/Write)

At full-scale range = ±320mV (decimal = 32000, positive value hex = 7D00, negative value hex = 8300). 15 bit + sign, LSB = 10μV.

| BIT #     | D15      | D14   | D13   | D12   | D11   | D10   | D9   | D8   | D7   | D6   | D5   | D4   | D3   | D2   | D1   | D0   |
|-----------|----------|-------|-------|-------|-------|-------|------|------|------|------|------|------|------|------|------|------|
| BIT NAME  | SWN SIGN | SWN14 | SWN13 | SWN12 | SWN11 | SWN10 | SWN9 | SWN8 | SWN7 | SWN6 | SWN5 | SWN4 | SWN3 | SWN2 | SWN1 | SWN0 |
| POR VALUE | 0        | 0     | 0     | 0     | 0     | 0     | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    |

## Bus Voltage Positive Limit Register 0Eh (Read/Write)

At full-scale range = 32V (decimal = 8000, hex = 1F40), and LSB = 4mV.

| BIT #     | D15   | D14   | D13   | D12  | D11  | D10  | D9   | D8   | D7   | D6   | D5   | D4   | D3   | D2 | D1 | D0 |
|-----------|-------|-------|-------|------|------|------|------|------|------|------|------|------|------|----|----|----|
| BIT NAME  | BWU12 | BWU11 | BWU10 | BWU9 | BWU8 | BWU7 | BWU6 | BWU5 | BWU4 | BWU3 | BWU2 | BWU1 | BWU0 | —  | —  | —  |
| POR VALUE | 0     | 0     | 0     | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0  | 0  | 0  |

## Bus Voltage Negative Limit Register 0Fh (Read/Write)

At full-scale range = 32V (decimal = 8000, hex = 1F40), and LSB = 4mV.

| BIT #     | D15   | D14   | D13   | D12  | D11  | D10  | D9   | D8   | D7   | D6   | D5   | D4   | D3   | D2 | D1 | D0 |
|-----------|-------|-------|-------|------|------|------|------|------|------|------|------|------|------|----|----|----|
| BIT NAME  | BUO12 | BUO11 | BUO10 | BUO9 | BUO8 | BUO7 | BUO6 | BUO5 | BUO4 | BUO3 | BUO2 | BUO1 | BUO0 | —  | —  | —  |
| POR VALUE | 0     | 0     | 0     | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0  | 0  | 0  |

## Power Limit Register 10h (Read/Write)

At full-scale range, same as the Power Register (06h).

| BIT #     | D15  | D14  | D13  | D12  | D11  | D10  | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2  | D1  | D0  |
|-----------|------|------|------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| BIT NAME  | PW15 | PW14 | PW13 | PW12 | PW11 | PW10 | PW9 | PW8 | PW7 | PW6 | PW5 | PW4 | PW3 | PW2 | PW1 | PW0 |
| POR VALUE | 0    | 0    | 0    | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   |

## Local Temperature Limit Register 11h, Remote Temperature Limit 1 Register 12h, Remote Temperature Limit 2 Register 13h, Remote Temperature Limit 3 Register 14h (TMP513 Only) (Read/Write)

| BIT #     | D15  | D14  | D13  | D12 | D11 | D10 | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2 | D1 | D0 |
|-----------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|
| BIT NAME  | TH12 | TH11 | TH10 | TH9 | TH8 | TH7 | TH6 | TH5 | TH4 | TH3 | TH2 | TH1 | TH0 | —  | —  | —  |
| POR VALUE | 0    | 0    | 1    | 0   | 1   | 0   | 1   | 0   | 1   | 0   | 0   | 0   | 0   | 0  | 0  | 0  |

The data format is 13 bits.

**TH12–TH0:**                      **Temperature Limit**  
Bits 15-3                      Shows the temperature limit.

## Shunt Calibration Register 15h (Read/Write)

Current and power calibration are set in the Calibration Register. Note that bit D0 is not used in the calculation. This register sets the current that corresponds to a full-scale drop across the shunt. Full-scale range and the LSB of the current and power measurement depend on the value entered in this register. See the [Programming the TMP512/13 Power Measurement Engine](#) section. This register is suitable for use in overall system calibration. Note that the '0' POR values are all default.

| BIT #     | D15  | D14  | D13  | D12  | D11  | D10  | D9  | D8  | D7  | D6  | D5  | D4  | D3  | D2  | D1  | D0 <sup>(1)</sup> |
|-----------|------|------|------|------|------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-------------------|
| BIT NAME  | FS15 | FS14 | FS13 | FS12 | FS11 | FS10 | FS9 | FS8 | FS7 | FS6 | FS5 | FS4 | FS3 | FS2 | FS1 | FS0               |
| POR VALUE | 0    | 0    | 0    | 0    | 0    | 0    | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0                 |

(1) D0 is a void bit and is always '0'. It is not possible to write a '1' to D0.

## n-Factor 1 Register 16h (Read/Write)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9  | D8  | D7   | D6   | D5   | D4   | D3   | D2   | D1   | D0   |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|
| BIT NAME  | NF7 | NF6 | NF5 | NF4 | NF3 | NF2 | NF1 | NF0 | HST7 | HST6 | HST5 | HST4 | HST3 | HST2 | HST1 | HST0 |
| POR VALUE | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0    | 0    | 0    | 0    | 0    | 0    | 0    | 0    |

**NF7–NF0:**
**n-Factor Bits**

Bits 15-8

Shows the n-factor for Channel 1 according to the range indicated in [Table 11](#).

**Table 11. n-Factor Range<sup>(1)</sup>**

| N <sub>ADJUST</sub> |     |         | n        |
|---------------------|-----|---------|----------|
| BINARY              | HEX | DECIMAL |          |
| 0111 1111           | 7F  | 127     | 1.747977 |
| 0000 1010           | 0A  | 10      | 1.042759 |
| 0000 1000           | 08  | 8       | 1.035616 |
| 0000 0110           | 06  | 6       | 1.028571 |
| 0000 0100           | 04  | 4       | 1.021622 |
| 0000 0010           | 02  | 2       | 1.014765 |
| 0000 0001           | 01  | 1       | 1.011371 |
| 0000 0000           | 00  | 0       | 1.008    |
| 1111 1111           | FF  | –1      | 1.004651 |
| 1111 1110           | FE  | –2      | 1.001325 |
| 1111 1100           | FC  | –4      | 0.994737 |
| 1111 1010           | FA  | –6      | 0.988235 |
| 1111 1000           | F8  | –8      | 0.981818 |
| 1111 0110           | F6  | –10     | 0.975484 |
| 1000 0000           | 80  | –128    | 0.706542 |

<sup>(1)</sup> Shaded values are default.

**HST7–HST0:**
**Hysteresis Register Bits**

Bits 7-0

The hysteresis register is binary coded. 1LSB is equal to 0.5°C, so the possible hysteresis range is 0°C to 127.5°C.

## n-Factor 2 Register 17h (Read/Write)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9  | D8  | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|
| BIT NAME  | NF7 | NF6 | NF5 | NF4 | NF3 | NF2 | NF1 | NF0 | —  | —  | —  | —  | —  | —  | —  | —  |
| POR VALUE | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  |

**NF7–NF0:**
**n-Factor Bits**

Bits 15-8

Shows the n-factor for Channel 2 according to the range indicated in [Table 11](#).

## n-Factor 3 Register 18h (TMP513 Only) (Read/Write)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9  | D8  | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|
| BIT NAME  | NF7 | NF6 | NF5 | NF4 | NF3 | NF2 | NF1 | NF0 | —  | —  | —  | —  | —  | —  | —  | —  |
| POR VALUE | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0   | 0  | 0  | 0  | 0  | 0  | 0  | 0  | 0  |

**NF7–NF0:**
**n-Factor Bits**

Bits 15-8

Shows the n-factor for Channel 3 according to the range indicated in [Table 11](#).

## Manufacturer ID Register 1Eh and FEh (Read-Only)

| BIT #     | D15 | D14 | D13 | D12 | D11 | D10 | D9  | D8  | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|
| BIT NAME  | ID7 | ID6 | ID5 | ID4 | ID3 | ID2 | ID1 | ID0 | —  | —  | —  | —  | —  | —  | —  | —  |
| POR VALUE | 0   | 1   | 0   | 1   | 0   | 1   | 0   | 1   | 1  | 1  | 1  | 1  | 1  | 1  | 1  | 1  |

**ID7–ID0:** **Identification Register Bits**  
 Bits 15-8 These bits provide the manufacturer ID.

## Device ID Register 1Fh and FFh (Read-Only)

| BIT #            | D15  | D14  | D13  | D12  | D11  | D10  | D9   | D8   | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------------|------|------|------|------|------|------|------|------|----|----|----|----|----|----|----|----|
| BIT NAME         | DID7 | DID6 | DID5 | DID4 | DID3 | DID2 | DID1 | DID0 | —  | —  | —  | —  | —  | —  | —  | —  |
| TMP512 POR VALUE | 0    | 0    | 1    | 0    | 0    | 0    | 1    | 0    | 1  | 1  | 1  | 1  | 1  | 1  | 1  | 1  |
| TMP513 POR VALUE | 0    | 0    | 1    | 0    | 0    | 0    | 1    | 1    | 1  | 1  | 1  | 1  | 1  | 1  | 1  | 1  |

**DID7–DID0:** **Identification Register Bits**  
 Bits 15-8 These bits provide the device ID.

## PACKAGING INFORMATION

| Orderable Device | Status <sup>(1)</sup> | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <sup>(2)</sup> | Lead/ Ball Finish | MSL Peak Temp <sup>(3)</sup> | Samples (Requires Login)             |
|------------------|-----------------------|--------------|-----------------|------|-------------|-------------------------|-------------------|------------------------------|--------------------------------------|
| TMP512AID        | ACTIVE                | SOIC         | D               | 14   | 50          | Green (RoHS & no Sb/Br) | CU NIPDAU         | Level-2-260C-1 YEAR          | <a href="#">Purchase Samples</a>     |
| TMP512AIDR       | ACTIVE                | SOIC         | D               | 14   | 2500        | Green (RoHS & no Sb/Br) | CU NIPDAU         | Level-2-260C-1 YEAR          | <a href="#">Request Free Samples</a> |
| TMP513AID        | ACTIVE                | SOIC         | D               | 16   | 40          | Green (RoHS & no Sb/Br) | CU NIPDAU         | Level-2-260C-1 YEAR          | <a href="#">Purchase Samples</a>     |
| TMP513AIDR       | ACTIVE                | SOIC         | D               | 16   | 2500        | Green (RoHS & no Sb/Br) | CU NIPDAU         | Level-2-260C-1 YEAR          | <a href="#">Request Free Samples</a> |

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

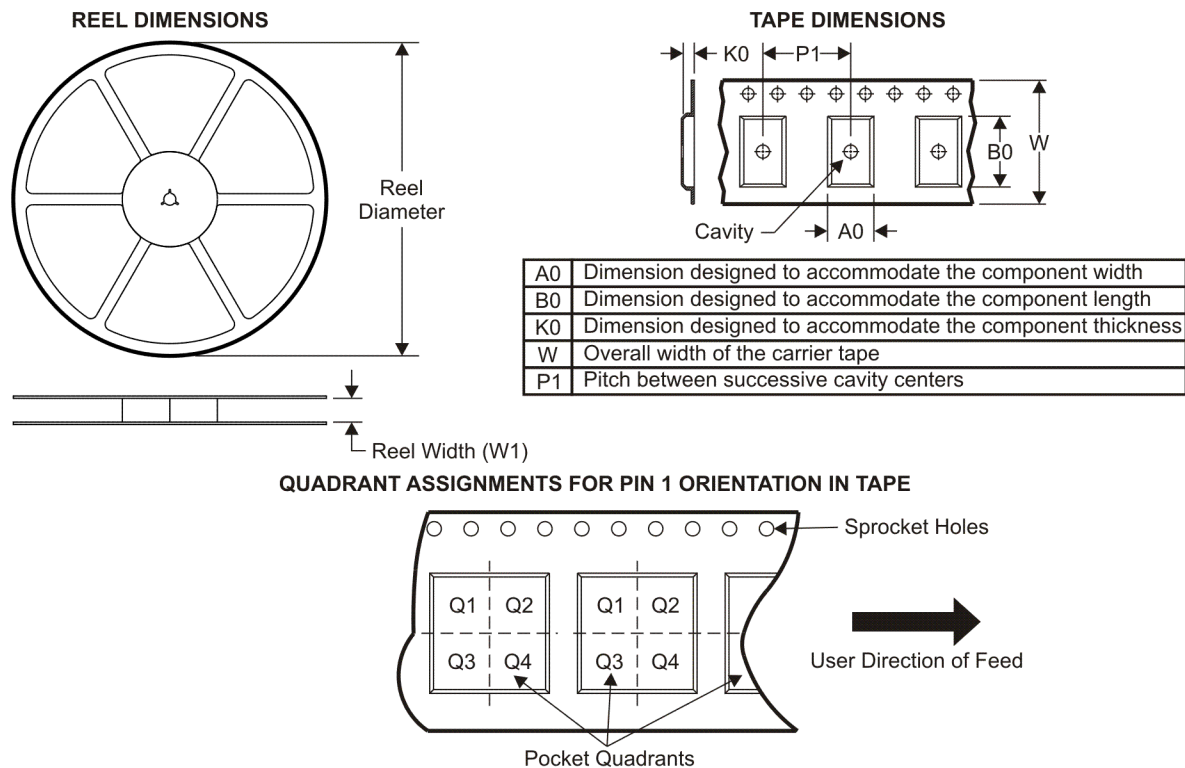
**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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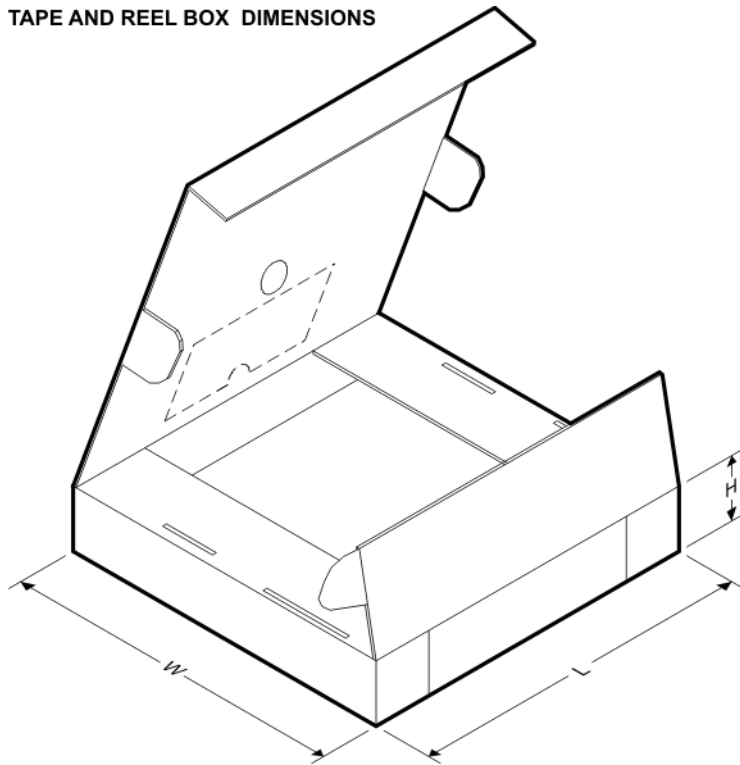
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**TAPE AND REEL INFORMATION**


\*All dimensions are nominal

| Device     | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TMP512AIDR | SOIC         | D               | 14   | 2500 | 330.0              | 16.4               | 6.5     | 9.0     | 2.1     | 8.0     | 16.0   | Q1            |

## TAPE AND REEL BOX DIMENSIONS

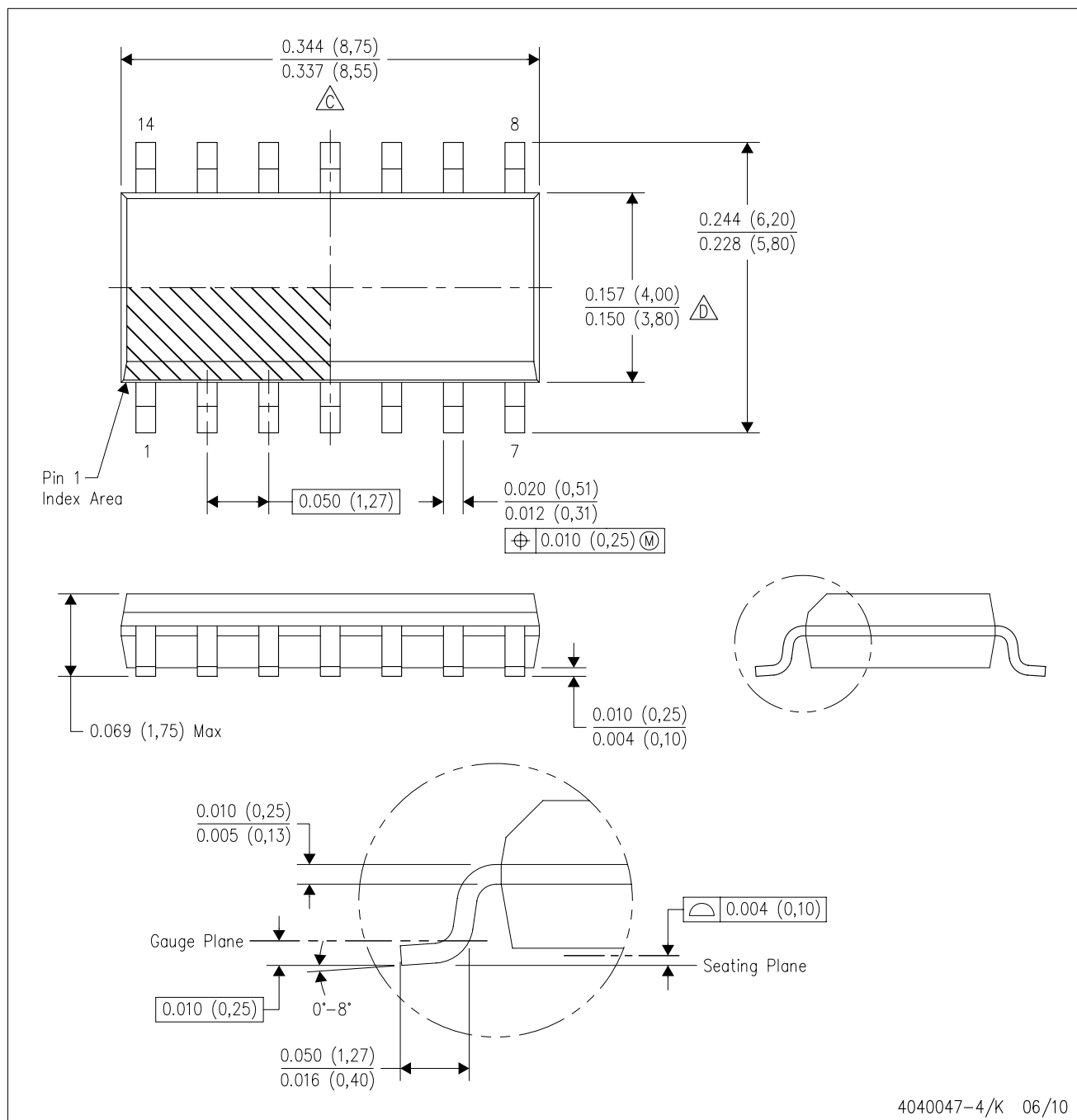


\*All dimensions are nominal

| Device     | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TMP512AIDR | SOIC         | D               | 14   | 2500 | 346.0       | 346.0      | 33.0        |

D (R-PDSO-G14)

PLASTIC SMALL-OUTLINE PACKAGE



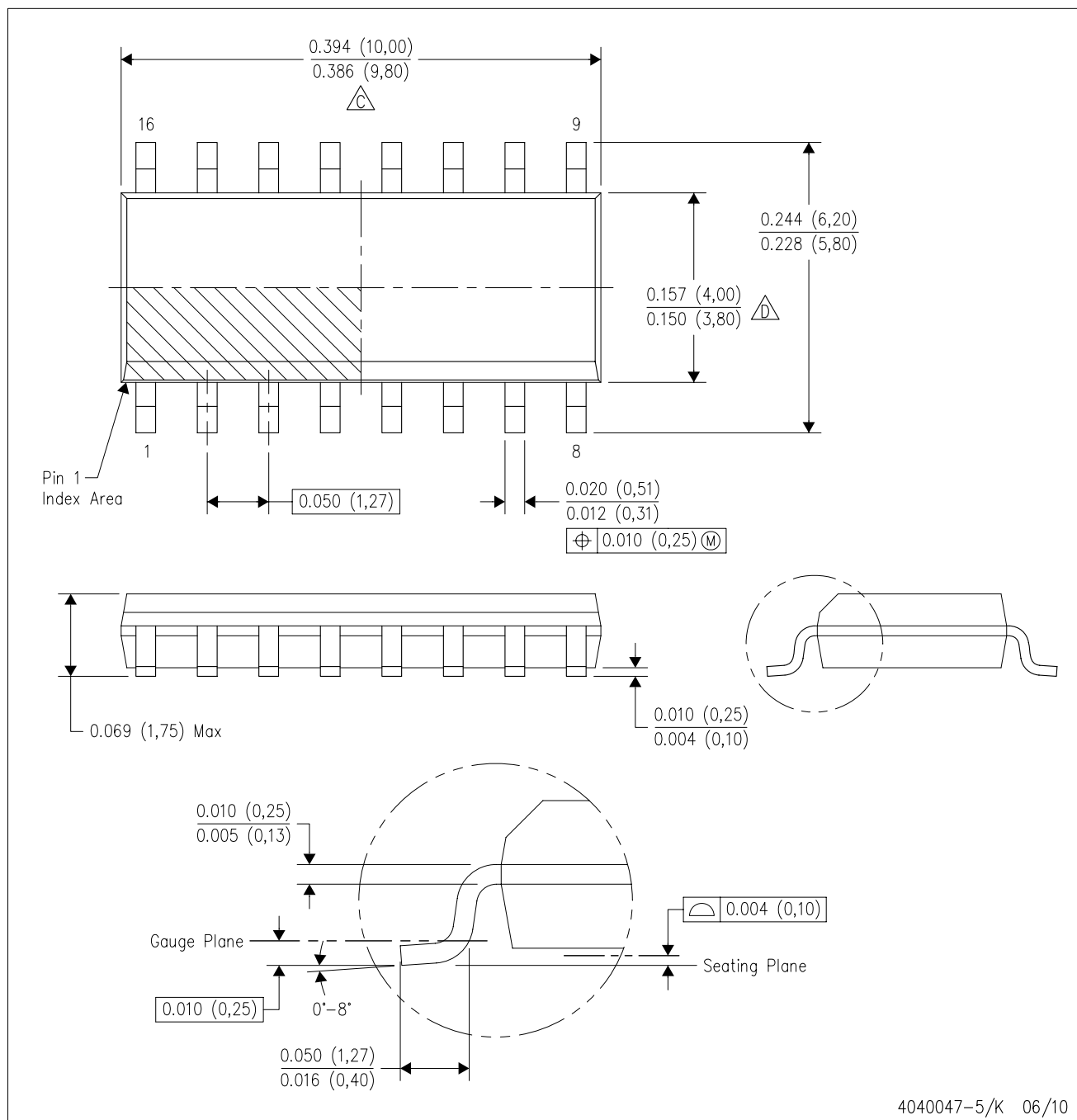
4040047-4/K 06/10

## NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.
- Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.
- E. Reference JEDEC MS-012 variation AB.

## D (R-PDSO-G16)

# PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).  
B. This drawing is subject to change without notice.  
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.  
D. Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.  
E. Reference JEDEC MS-012 variation AC.

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