YAMAR
Datasheet

SIG100 – UART/LIN over Powerline Transceiver

1. Overview

The SIG100 modulates UART/LIN bytes over the DC powerline (DC-BUS). The device merges both data and power over the powerline, eliminating the need for control and data wires. The SIG100 is an advanced generation of the widely used SIG60 device with backward competability (see 2.3) Both devices use a unique multiplex digital signaling technology that overcomes the powerline noisy environment at bitrates up to 115.2Kbit/s. Sleep mode allows low power consumption when the device is not used. The QFN32 5x5 mm package delivers a small PCB footprint

The SIG100 powerline transceiver reduces wiring in a wide range of automotive, aerospace, and industrial applications. These include networks for sensor readings, actuator activation, battery monitoring (BMS), doors, seats, mirrors, climate control, lights, Truck-Trailer communication, etc.

Applications

- **Vehicle sub-bus (LIN-BUS)**
- **Battery management (BMS)**
- **Climate control network**
- **Sensors/actuators bus**
- **Robotics control networks**
- **Lighting control**
- **Truck-Trailer communication**
- **Multiple networks sharing the same powerline**

Features

- **Noise robust UART/LIN transceiver over DC powerline.**
- **Selectable bitrates from 9.6kbit/s up to 115.2kbit/s**
- **251 selectable carrier frequencies (5MHz to 30MHz) for multiple networks over a single powerline.**
- **No limit to the number of bytes in a message.**
- **Operates as a Master or as a Slave in a multiplex network.**
- **Communicates over a wide range of DC voltages.**
- **Eliminates data wire and transceiver in LIN bus**
- **Power management (Sleep modes) for low power consumption.**

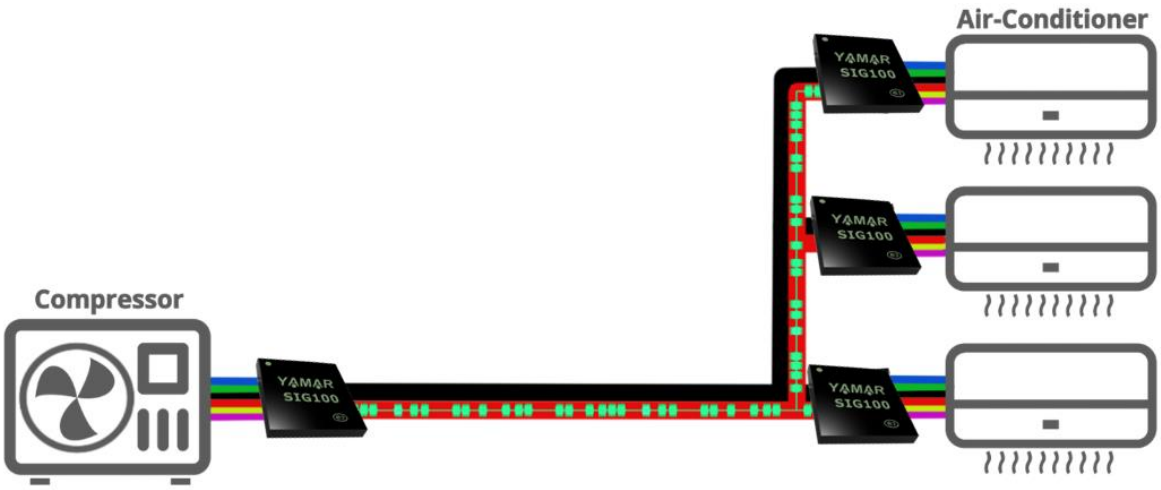


Figure 1- SIG100 climate control powerline network example

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2. Description

2.1 The SIG100 in a network

The SIG100 transfers over powerline half-duplex peer-to-peer communication or operates as Master-Slaves network of multiple SIG100. Users can define their protocol since there is no limit to the number of UART bytes in a message. Furthermore, the SIG100 operates on any selectable carrier frequency between 5MHz and 30MHz with 100 kHz spacing, allowing multiple independent networks to coexist on a single powerline by using different carrier frequencies for each network. It is recommended to keep at least 1MHz spacing between two carriers (networks).
Two alternate user-pre-defined frequencies allow hoping between these frequencies using *FREQ_SEL[1:0]* pins. This feature is useful when communication fails on the main frequency (see 3.4.2).

Figure 2 depicts a typical SIG100 network, demonstrating a single byte transmission from SIG100 TX device to three SIG100 RX devices coupled through a capacitor ($C_{coupling}$) to the same powerline. Upon detection of a start bit on the SIG100 TX device HDI pin, a modulated *PLC-byte* transmission starts. Then, the modulated *PLC-byte* is decoded back to a *byte-field* on SIG100 RX devices' HDO pin at a fixed latency of ~2.5 bits.

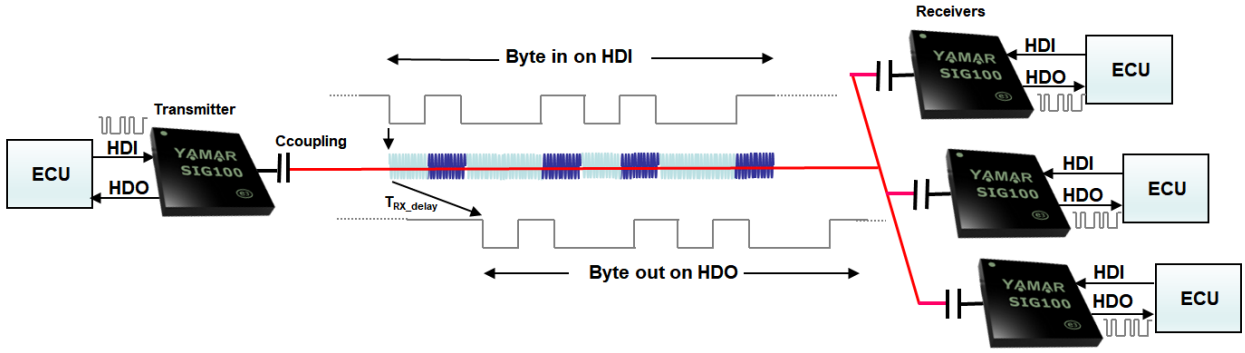


Figure 2 – SIG100 byte-oriented network

2.1.1 SIG100 channel parameters

Carrier frequency:	251 selectable frequencies between 5MHz - 30MHz with 100 kHz spacing.
Powerline bitrate:	9.6kbit/s, 10.4bit/s, 19.2Kbit/s, 38.4Kbit/s, 57.6kbit/s, and 115.2kbit/s.
Powerline voltage:	Any, with proper powerline coupling interfacing (see 2.6.9)
Cable length:	Depends on the powerline AC loads signal attenuation (100m is practical)
Cable type:	Any cable.

2.2 The Signaling technology

The SIG100 uses for its operation a unique Signaling technology. Each UART *byte-field* transferred to the device constructs a multiphase signaling *PLC-byte* carrier over the powerline that is decoded in the receiving device back into a UART *byte-field*. There is no restriction to the number of bytes transferred. The device supports also a *break-field* such as in LIN protocol by generating *PLC-Break* over the powerline that is translated back by all receiving devices back into *Break-field*. It allows seamless interfacing with the existing LIN network to be conveyed LIN over the powerline.

2.3 Backward competabilty with SIG60

The SIG100 is able to communicate transparnetly with the SIG60 device/s at the same carrier frequency settings of the SIG60 (5.5MHz/6MHz/6.5MHz/10.5MHz/13MHz).
To enable backward competabilty a WRITE-REG command (see 5.14.1) must beperformed as follows:

1st Byte	2nd Byte	3rd Byte
	Register address	**Data to write**
0xF5	**0x84**	**0x17**

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2.4 SIG100 architecture

Figure 3 depicts the SIG100 building blocks.

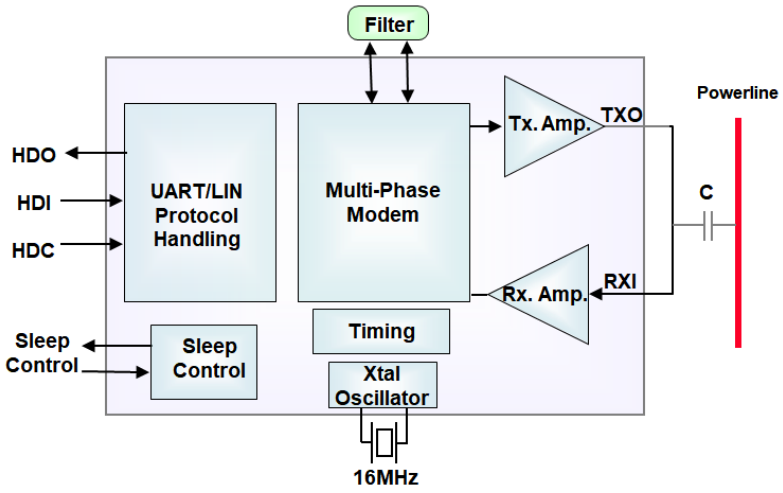


Figure 3- SIG100 Logical Blocks

The SIG100 main building blocks:

- **Protocol handler** - Interface with UART/LIN ECU.
- **Multi-Phase Modem -** Phase modulates and demodulates the UART bytes to/from the DC-BUS powerline.
- **Sleep control** - handles low power consumption during Sleep mode.

2.5 Pin configuration and function

2.5.1 Pin diagram

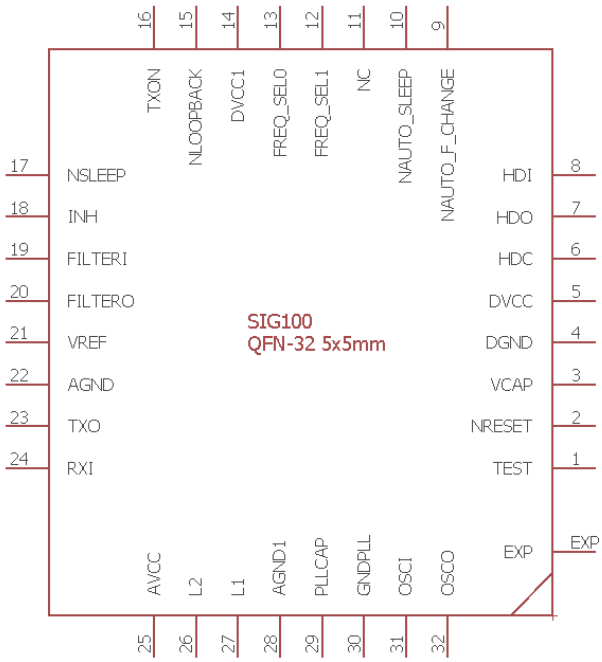


Figure 4 – SIG100 pinout diagram in QFN32 5x5mm package

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2.5.2 Signals and Pinout description

Table 1 - Pinout description

<table>
<tr><th>Name</th><th>Pin #</th><th>Pin type</th><th>Internal PU/PD</th><th>Description</th></tr>
<tr><td>HDO</td><td>7</td><td>Output 12mA</td><td></td><td>Outputs the received data from the powerline or from internal registers to the ECU.</td></tr>
<tr><td>HDI</td><td>8</td><td>Digital input</td><td>PU</td><td>Transfers data from the ECU to the powerline or the internal registers.</td></tr>
<tr><td>HDC</td><td>6</td><td>Digital input</td><td>PU</td><td>ECU Data / Command input. When low, enables read and write from/to the SIG100 control registers (see section 5.14).</td></tr>
<tr><td>TEST</td><td>1</td><td>Digital Input</td><td>PD</td><td>Should be connected to GND.</td></tr>
<tr><td>NRESET</td><td>2</td><td>Digital Input</td><td>PU</td><td>Reset, active low.</td></tr>
<tr><td>NSLEEP</td><td>17</td><td>Digital Input</td><td></td><td>Sleep mode control input (see section 4.3).
Should be pull-up to 3.3V when not in use.</td></tr>
<tr><td>NAUTO_F_CHANGE</td><td>9</td><td>Digital Input</td><td></td><td>When low, the SIG100 will automatically hop between the main carrier frequency and two alternate frequencies (see 3.4.4).</td></tr>
<tr><td>NAUTO_SLEEP</td><td>10</td><td>Digital Input</td><td></td><td>When low, the SIG100 automatically enters Sleep mode when there is no transmission or reception to/from the powerline longer than the AutoSleep-timeout setting (see 4.4).</td></tr>
<tr><td>NC</td><td>11</td><td></td><td></td><td>Should be left floated.</td></tr>
<tr><td>NLOOPBACK</td><td>15</td><td>Digital Input</td><td>PU</td><td>When high, loopback from HDO to HDI is disabled (see 3.4.5)</td></tr>
<tr><td>INH</td><td>18</td><td>Output 8mA</td><td></td><td>When high, SIG100 is in Normal mode
When low, SIG100 is in Sleep mode</td></tr>
<tr><td>FREQ_SEL0</td><td>13</td><td>Digital Input</td><td></td><td rowspan="2">Main and 2 alternate frequencies selection control (see 3.4.2)
<table>
<tr><th>FREQ_SEL[1:0]</th><th>Default Frequency [MHz]</th><th></th></tr>
<tr><td>'00','11'</td><td>13</td><td>Main</td></tr>
<tr><td>'01'</td><td>5</td><td>Alternate 1</td></tr>
<tr><td>'10'</td><td>22</td><td>Alternate 2</td></tr>
</table></td></tr>
<tr><td>FREQ_SEL1</td><td>12</td><td>Digital Input</td><td></td></tr>
<tr><td>TXON</td><td>16</td><td>Output 12mA</td><td></td><td>TX_ON output - High during transmission over the powerline.</td></tr>
<tr><td>TXO</td><td>23</td><td>Analog Output Max 66 mA</td><td></td><td>Powerline Transmit signal out
<table>
<tr><td>TXON State</td><td>REG_1[4]</td><td>TX level [V-p-p]</td><td>Impedance [Ω]</td></tr>
<tr><td rowspan="2">High</td><td>'0'</td><td>1</td><td rowspan="2">18 [1]</td></tr>
<tr><td>'1' (Default)</td><td>2</td></tr>
<tr><td>Low</td><td></td><td>High Z</td><td>5.3k [2]</td></tr>
</table>
[1] Series output impedance
[2] Input impedance referenced to VREF</td></tr>
<tr><td>RXI</td><td>24</td><td>Analog Input</td><td></td><td>Powerline receive Input</td></tr>
<tr><td>VREF</td><td>21</td><td>Analog Output</td><td></td><td>VCC/2 Analog voltage reference output to a filtering capacitor. Place 1uF between VREF to AGND. VREF is a virtual ground for the external analog circuitry.</td></tr>
<tr><td>FILTERI</td><td>19</td><td>Analog, Bi-directional</td><td></td><td>External filter I/O</td></tr>
<tr><td>FILTERO</td><td>20</td><td>Analog, Bi-directional</td><td></td><td>External filter I/O</td></tr>
<tr><td>OSCO</td><td>32</td><td>Analog output</td><td></td><td>16MHz Crystal Output</td></tr>
<tr><td>OSCI</td><td>31</td><td>Analog Input</td><td></td><td>16MHz Crystal Input</td></tr>
<tr><td>L1</td><td>27</td><td>Analog Input</td><td></td><td>External inductor L1 (keep short trace connection), see 2.6.4.</td></tr>
<tr><td>L2</td><td>26</td><td>Analog Input</td><td></td><td>External inductors L2 (optional), see 2.6.4.</td></tr>
<tr><td>AVCC</td><td>25</td><td>Power</td><td></td><td>Analog 3.3V supply</td></tr>
<tr><td>AGND</td><td>22,28</td><td>Power</td><td></td><td>Analog ground</td></tr>
<tr><td>VCAP</td><td>3</td><td>Power</td><td></td><td>1.8V core supply output to a filtering capacitor. Place 4.7uF between VCAP and DGND.</td></tr>
<tr><td>DGND</td><td>4</td><td>Power</td><td></td><td>Digital Ground</td></tr>
</table>

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Name	Pin #	Pin type	Internal PU/PD	Description
DVCC	5,14	Power		Digital 3.3V supply
GNDPLL	30	Power		Analog Ground
PLLCAP	29	Power		PLL 1.8V output to a filtering capacitor. Place 1uF between PLLCAP and GNDPLL.
EXP	33	Power		Expose pad, should be connected to DGND.

PD – Internal Pull-down resistor 50K Ω +/-%30
PU – Internal Pull-up resistor 50K Ω +/-%30

2.6 Implementation

2.6.1 SIG100 recommended schematic

Figure 5 depicts a typical SIG100 schematic.

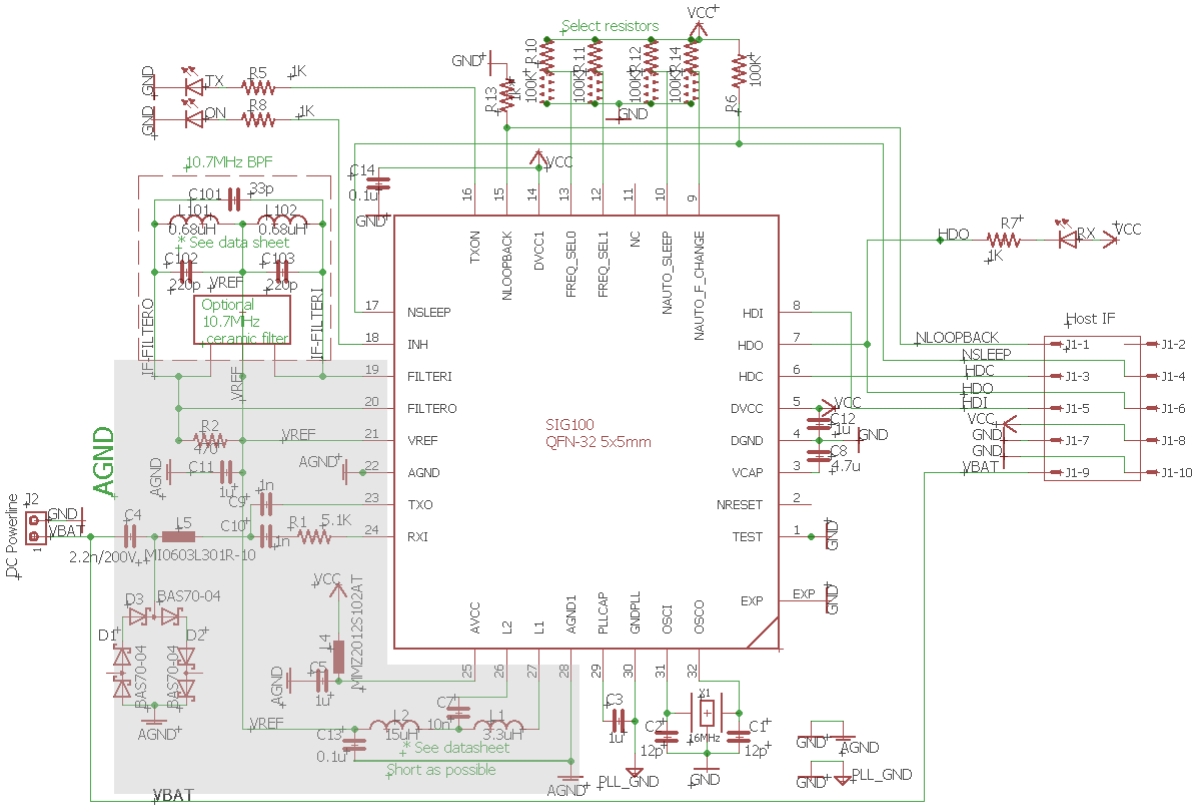


Figure 5 – SIG100 reference schematic

2.6.2 External 10.7MHz filter (BPF)

The SIG100 operates using an external 10.7MHz narrow bandpass filter. The minimum recommended filter bandwidth is 330 kHz @ 3dB. Narrower bandwidth limits the maximal SIG100 bitrate.

Figure 6 depicts the recommended 10.7MHz discrete filter**.**

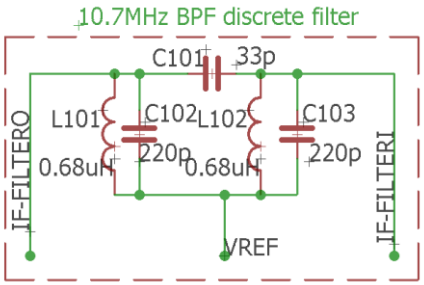


Figure 6 - 10.7MHz discrete bandpass filter

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Alternatively, Table 2 describes the recommended 10.7MHz ceramic filters.

Table 2 – Recommended 10.7MHz ceramic filters

Manufacturer	Part #	3dB BW [KHz] min.	Insertion loss [dB] max.	Stopband attenuation [kHz]	In/Out imped. [Ω]	Package
AEC	LTCV10.7MA19	350	3.0	950	470	 SMD
Strong-First	LTCV10.7MA20	330	3.0	680	330	 SMD
Murata	SFECF10M7EA00-R0	330	3.0	700	330	 SMD

2.6.3 External Crystal

The device operates with a low cost, small size 16MHz crystal connected between OSCI and OSCO pins. Each of these pins should be connected to the DGND via a load capacitor. The load capacitors values should be determined according to the crystal manufacturer's recommendations and the actual PCB layout. The PCB traces should be as short as possible.
The overall frequency tolerance should not exceed ± 50ppm.

- **Recommended crystals:**
  - **NDK - NX2520SA-16MHz, SMD, 2.5x2 mm**
  - **NDK - NX3225SA/GB-16MHz, SMD, 3.2x2.5mm**
  - **NDK - NX2016GC-16MHz, SMD, 2.0x1.6mm**
  - **ECS - ECS-160-12-37B-CTN-TR, SMD, 2.0x1.6mm**

2.6.3.1 16MHz clock from an external source

The device can operate from an external 16HMz clock that meets the requirements above.
Figure 7 depicts an external 16MHz clock connection to the device.

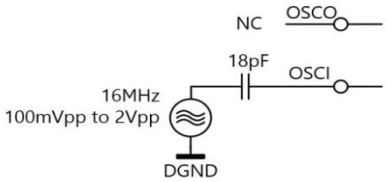


Figure 7 - External 16MHz clock connection

2.6.4 L1 and L2 inductors

The SIG100 requires one or two inductors for its operation, depending on the desired operating frequency.

- For full in-band operation, 5MHz - 30MHz:
  - L1 - 3.3uH
  - L2 - 15uH with 10nF series capacitor between L2 pin and L2 inductor.

- For low in-band operation, 5MHz -12MHz:
  - L1 - 18uH
  - L2 - NC

- For high in-band operation, 12MHz - 30MHz:
  - L1 - 3.3uH
  - L2 – NC

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Figure 8 depicts the in-band operation inductors' connection to pins L1 and L2.

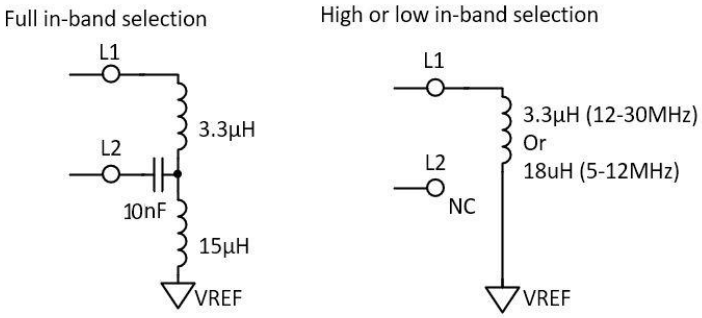


Figure 8 - L1 and L2 inductors connections

2.6.5 Recommended L1 & L2 inductors

Table 3 describes the recommended L1 and L2 inductors.

Table 3 - Recommended L1 and L2 manufacturers

Inductor	ABRACON	VISHAY	TDK
L1=3.3uH	815-AIML-0805-3R3K-T	ILSB0805ER3R3K	MLF2012A3R3JT000
L2=15uH	815-AIML-0805-150K-T	ILSB0805ER150K	MLF2012C150KT000
L1=18uH	815-AIML-0805-180K-T	ILSB0805ER180K	MLF2012C180KT000

2.6.6 Optional EMC chip-bead (L5)

For enhanced mitigation of high harmonics above 30MHz conducted over the powerline, it is recommended to add L5 in series to the coupling capacitor C4 (see Figure 5).

Table 4 describes the recommended EMC chip-beads.

Table 4 - Recommended L5 (optional)

LAIRD	MI0603L301R-10
LAIRD	HZ0603A222R-10
TDK	MMZ1608Q

2.6.7 Ceramic capacitors

Low ESR capacitors will provide better performance. X5R and X7R capacitors are recommended, especially for Vcap (C8) and PLLCAP (C3).

2.6.8 TXO output level and drive control

The TXO pin output level and drive capability to the powerline are controlled by REG_*1[4]*, as described in Table 5.

Table 5 - TXO signal level

TXON State	REG_1[4]	TX level [V-p-p]
High	'0'	1
	'1' (Default)	2
Low (Rx)		High Z

Set the TXO output drive capability by configuring REG_*1[7]*, as described in Table 6.

Table 6- TXO output drive control

TXON State	REG_1[7]	Output drive [A]	Impedance [Ω]
High	'0' (Default)	33mA	18 [1]
	'1'	66mA	
Low (Rx)		Disabled	5.3k [2]

[1]Series output impedance
[2]Input impedance referenced to VREF

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2.6.9 Powerline coupling interface

The SIG100 is coupled to the powerline through a single small footprint DC blocking ceramic capacitor, typically 2.2nF. The $C_{coupling}$ voltage rating depends on the powerline voltage and its expected impulses.
For high voltage powerline applications (e.g. battery monitoring system in EV or solar panels), it is required to add galvanic isolation.

2.6.10 External protection network

A simple external diode protection network is recommended before the $C_{coupling}$, to protect against high powerline pulses (above 2 V-P-P). The protection network consists of three low capacitance (< 10pF) fast Schottky diodes serially connected in both polarities (e.g. BAS70-04).

2.6.11 Recommended connection to power-supply

Power-supplies have filtering capacitors in their DC inputs. These capacitors attenuate strongly the SIG100 carrier signal. It is recommended to add an inductor (>22uH) or ferrite bead (>100Ω @ 5MHz-30MHz) in series to the power supply connection to the DC powerline to reduce the carrier signal attenuation.
Figure 9 depicts a typical SIG100 connection to a DC powerline and its 3.3V power supply.

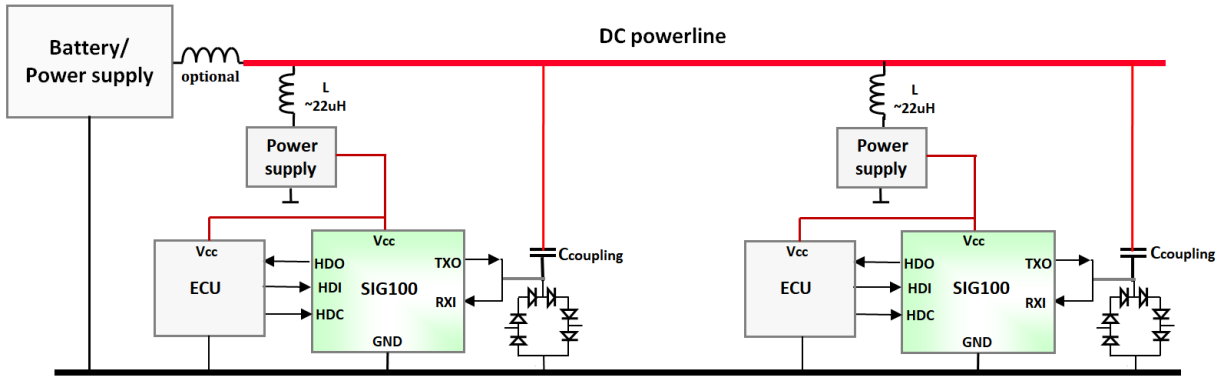


Figure 9 – SIG100 connection to 3.3V power-supply and powerline

3. Operation

3.1 Interfacing to UART/LIN ECU

The SIG100 interfaces directly to any uC UART/LIN I/O pins (3.3V logic).
The UART/LIN communication protocol uses four pins as described in Table 7.

Table 7 – UART/LIN interface pins

SIG100	ECU	Description
HDI	**Tx**	Data Input from the host ECU.
HDC	**GPO**	Data/Command select input. When pulled down, the SIG100 enters command mode, enabling access to SIG100 internal registers.
HDO	**Rx**	Data output to the host ECU.
NLOOPBACK	**GPO**	Enable loopback of HDI to HDO pin. When interfacing a UART port, ECU may disable/enable the loopback option. When interfacing a LIN transceiver, loopback disabled by keeping the pin floated (internal PU). When interfacing a LIN ECU, tie the pin to GND. HDI loops back to HDO.

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Figure 10 depicts a typical SIG100 to ECU UART/LIN interface connection.

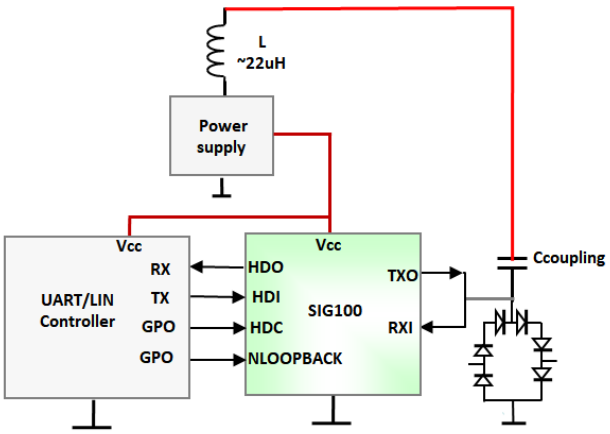


Figure 10 - Typical SIG100 to UART/LIN ECU interface

3.2 Interfacing to existing LIN module

When interfacing to a LIN module that has already a built-in LIN transceiver, an additional LIN transceiver is required to translate the signals to Tx and Rx 3.3V logic. The loopback between HDI and HDO pins has to be disabled. Keep NLOOPBACK pin floated.
Figure 11 depicts a typical SIG100 to LIN transceiver interface connection.

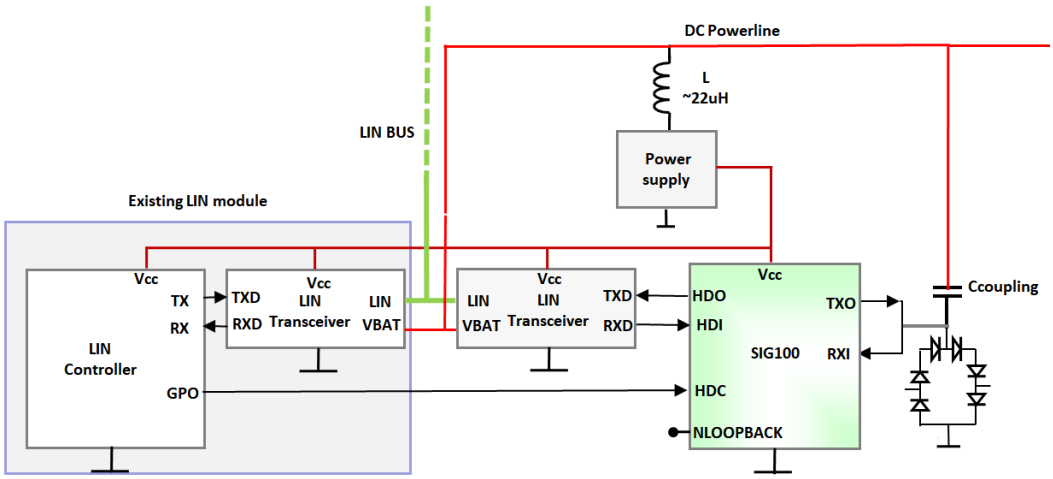


Figure 11 - Typical SIG100 to LIN transceiver interface

3.3 SIG100 messages

3.3.1 Message structure

The SIG100 supports UART and LIN protocols.

- A *byte-field (UART byte)* is defined with one start bit, 8 data bits, and one stop bit.
- A *PLC-byte* is defined as the signaling pattern of the *byte-field* over the powerline.
- A *break-field* is defined as one start bit, 12 to 30 zero bits, and one stop bit.
- A *PLC-break* is defined as the signaling pattern of the *break-field* over the powerline

The SIG100 is a byte-oriented powerline transceiver. Each UART/LIN *byte-field* on the HDI pin is encoded into a modulated powerline *PLC-byte* at the length of the ECU UART bitrate. At the receiving side, each *PLC-byte* is decoded back after a fixed delay of ~2.5T_{bit} to the HDO *byte-field*. A *break-field* at the beginning of a LIN message is handled the same.

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3.3.2 Transmit flow

Upon detection of a start bit on HDI, the SIG100 starts its *byte-field*/*break-field* transmission over the powerline until receiving a stop bit from ECU. In case of ECU transfers bytes continuously (i.e. inter-byte spacing between bytes < 1/3 T_{bit}), the SIG100 will not stop its transmission. If the inter-byte space is longer than 1/3 T_{bit}, the SIG100 will stop its transmission over the powerline and will wait for the next start bit.

3.3.3 Receive flow

Upon detection of a powerline *PLC-byte/PLC-break*, the SIG100 will decode the *PLC-byte* and transfer the *byte-field* to the receiving ECU's HDO pin (a start bit followed by the data bits and stop bit).

The delay (powerline latency) between Transmitter start bit drop on HDI to Receiver start bit drop is T_{RX_delay} = ~2.5 T_{bit}.

Figure 12 depicts a single *byte-field -> PLC-byte -> byte-field* TX-RX flow. ECU A transfers 0x55 *byte-field* on HDI with local loopback feedback on HDO (loopback is enabled). Upon start bit detection, a powerline transmission of *PLC-byte* 0x55 (length of 10 x T_{bit}), begins. Then, after T_{RX_delay} of ~2.5 T_{bit}, the *PLC-byte* is extracted on RX device B HDO pin to its ECU.

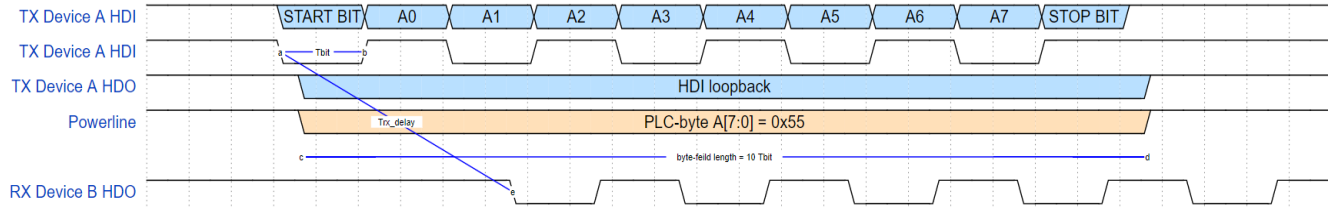


Figure 12 – SIG100 single *PLC-byte* TX-RX example

Figure 13 depicts a single *break-field* TX-RX flow. ECU A transfers a *break-field* on HDI with local loopback feedback on HDO (loopback is enabled). Upon start bit detection, a powerline transmission of *PLC-break* (length of 13 x T_{bit}), begins. Then, after T_{RX_delay} of ~2.5 T_{bit}, the *break-field* is extracted on RX device B HDO to its ECU.

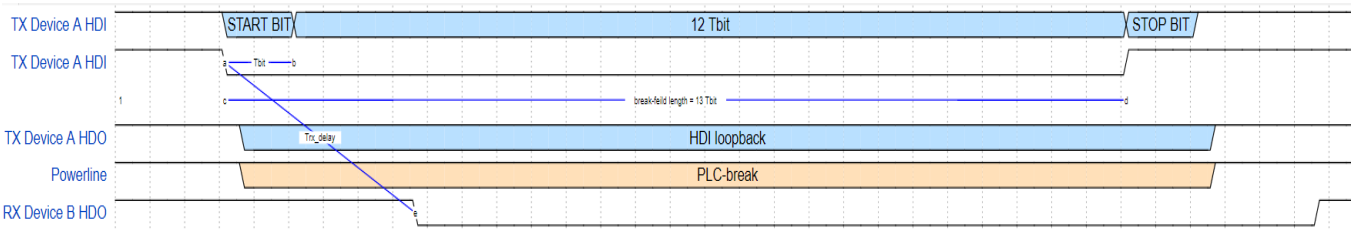


Figure 13 – SIG100 single *break-field* TX-RX example

3.4 Device configuration

3.4.1 Bitrate configuration

Table 8 describes the SIG100 supported bitrate selection.
Bitrate configuration is made by setting REG_0[2:0] bits using the *WRITE-REG* command (see 5.14.1).

Table 8 – Bitrate selection

REG_0 Bitrate_sel[2:0]	Bitrate [bit/s]	T_{bit} [µs]
000	9600	104
001	10417	96
010	19200 **(default)**	52
011	38400	26
100	57600	17.36
101	115200	8.68

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3.4.2 Carrier frequency management

The SIG100 operates on its configured main frequency. Two alternate frequencies (ALT1 and ALT2) are available for frequency hopping in case that the operating frequency is blocked by interference.
The active working frequency is determined by FREQ_SEL[1:0] hardware pins setting. For each change in FREQ_SEL[1:0] pins, the SIG100 will switch to the selected carrier frequency (Main/ALT1/ALT2) according to Table 9 mapping.
Set the Main/ALT1/ALT2 frequencies by configuring REG_2/ REG_3/ REG_4 respectively (see 5.14.1).
For each configuration of REG_2, the active frequency is automatically switched to the Main frequency (as set in REG_2), regardless of FREQ_SEL[1:0] pins set. Switching to ALT1/ALT2 again will take place only at the next change of FREQ_SEL[1:0] pins.
ECU may read the active operating carrier frequency value stored in read-only REG_5.
Table 9 describes the carrier frequency setting and control.

Table 9 – Carrier frequency setting and control

Carrier Frequency	FREQ_SEL[1:0]	Register name	Default Frequency [MHz]
Main	'00','11'	REG_2[7:0]	13
ALT1	'01'	REG_3[7:0]	5
ALT2	'10'	REG_4[7:0]	22

3.4.3 Carrier frequency configuration

ECU can define carrier frequency from 5MHz to 30MHz with a spacing of 100 kHz (Total of 251 selectable carriers). Upon completion of configuration (REG_2) or change of FREQ_SEL[1:0] pins, the SIG100 will update its operating carrier frequency within a 1msec period. During this period, the SIG100 is kept in *Soft-Reset* and will not communicate with its ECU nor detect new messages from the powerline and no other internal register configuration is allowed. It is recommended to place the carrier frequency configuration last during multiple registers configuration and wait at least 1ms after HDC is released.

When multiple SIG100 networks operate over a single powerline, it is recommended to select their carrier frequencies spaced more than 1MHz between each other.
The carrier-selected value is calculated as given in Equation (3).

Equation 1

$$\textbf{REG_2/3/4} = (\text{Carrier Freq. [MHz]} - 5) * 10 \qquad (1)$$

EXAMPLE 1

- When setting the frequency to 14.1MHz:
  REG_2/3/4 = (14.1 - 5) * 10 = **0x5B**

EXAMPLE 2

- When Setting to 5MHz:
  REG_2/3/4 = (5 - 5) * 10 = **0x00**

3.4.4 Auto frequency change mode

The Auto frequency change mode is enabled either by pull the NAUTO_F_CHANGE pin low or by clearing REG_0[3] bit. The last action prevails.
When enabled, the SIG100 automatically hops between Main, ALT1, or ALT2 configured frequencies when no powerline *PLC-byte* activity detected more than 2 sec. It indicates that neither transmission nor reception is detected over the powerline.
The hopping method is as follows:

Main ---> ALT1 ---> Main ---> ALT2 ---> Main …

3.4.5 Loopback

LOOPBACK between HDI and HDO is required when interfacing to a LIN ECU. Loopback has to be disabled when interfacing with a LIN transceiver (see 3.1).
Loopback is enabled either by pull the LOOPBACK pin low or by clearing *REG_0[5]*. The last action prevails.

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3.4.6 Remote loopback mode

The remote loopback function, when enabled, triggers the SIG100 to transmits-back its last received powerline *PLC-byte* over the powerline. This function is useful in point to point communication between two SIG100 devices as part of the ECU built-in ACK/NACK mechanism. For example, the checksum byte at the end of a message is returned to the transmitting Master to validate the integrity of the received message by the Slave.

Remote loopback mode is enabled by setting *REG_0[4]*. The SIG100 RX device will respond only when the powerline is idle for at least 3 x T_{bit} times after full reception of the last byte.

Figure 14 depicts an example of a remote loopback operation. ECU A transfers two data bytes [0x00][0x01] that are transmitted over the powerline to ECU B. Upon detecting the last transmitted 0x01 byte, SIG100 device B waits for 3 x T_{bit} time before automatically transmit-back 0x01 over the powerline to device A.

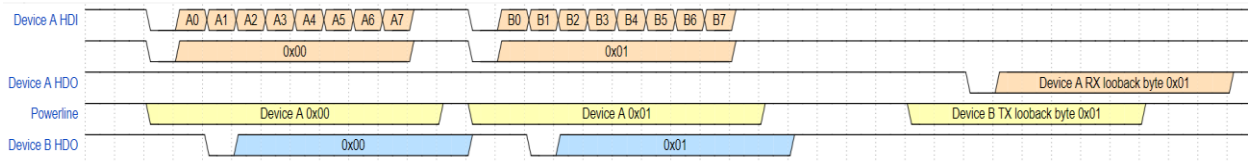


Figure 14 – Remote loopback example

3.4.7 SIG100 UUID

Each SIG100 device is hard-coded with a 48 bit universally unique identifier (UUID[47:0]).
The UUID is stored in REG_96 to REG_9B and can be retrieved using the READ-REG commands (see 5.8 to 5.13).

3.4.8 Typical set-up and operation example

1. Interface HDI, HDO, and HDC pins to the host ECU.
2. Enable/disable loopback of HDI pin to HDO pin (see 3.4.5).
3. Select SIG100 bitrate according to ECU UART/LIN bitrate (see3.4).
4. Select a carrier frequency (default 13MHz) (see 3.4.2).
5. Transmit bytes via HDI pin to the powerline.
6. Receive bytes from the powerline via HDO pin.

4. Power Operation Modes

The SIG100 has three power operation modes; Normal (RX/TX), Standby, and Sleep.

4.1 Normal mode

In Normal mode, the SIG100 is either in RX mode, listening for a powerline *PLC-byte* and *PLC-break*, or in TX mode, transmitting a message over the powerline.

4.2 Standby mode

The SIG100 enters Standby mode upon wake-up from Sleep mode, while the NSLEEP pin is still low. The SIG100 is kept in *Soft-Reset*, whereas communication with the ECU is suspended until the NSLEEP pin is set High.

4.3 Sleep modes (power-saving)

The SIG100 has four Sleep modes for best power consumption/performance during Sleep. During this mode, only a small amount of hardware operates to detect wake-up messages (*WUM*) from the powerline and return to Normal mode operation.

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Four interface pins are used for Sleep modes operation, as described in Table 10.

Table 10- Sleep interface pins

NSLEEP	Digital input	High - Normal mode is active. Low - Sleep /Standby mode is active. Upon transition from low to high, WUM is transmitted over the powerline.
INH	Digital output	Output indication to Inhibit the ECU. High - Normal mode is active. Low - Sleep mode is active.
HDO	Digital output	**Normal mode** - data output to ECU. **Sleep/Standby mode** - asserted low while wake-up message (WUM) is being detected/transmitted over the powerline.
HDC	Digital input	**Normal mode** – ECU's Host Command mode. **Sleep mode** - ECU wakes-up the SIG100 locally by toggling the HDC high-low-high. The SIG100 then exits the Sleep mode to Standby mode (NSLEEP still asserted low), or Normal mode (NSLEEP is high).

4.3.1 Wake-up message (*WUM)*

When *Auto-WUM* is enabled (*REG_6[6]='1'*), upon the rise of the NSLEEP pin the SIG100 transmits a *WUM* over the powerline to wake-up all network-connected devices.
ECU can configure the length of the WUM as described in Table 11.

Table 11 - Wake-up message length configuration

REG_6[4]	**Wake-up message length**
0	*SLP2* - 250usec / *SLP1, SLP3* - 75msec
1	*SLP2* - 1.5msec / *SLP1, SLP3* - 150msec

During WUM transmission, the HDO pin is asserted low until WUM transmission is completed, indicating to the ECU the wake-up process status. ECU shall wait for the HDO rise before initiating new bytes transfer.

4.3.2 Entering Sleep mode

During Sleep mode, the device is kept in *Soft-Reset* state and will not transfer bytes from the ECU nor receive bytes from the powerline. When the device enters Sleep mode, the INH pin is asserted low.
There are two ways to enter Sleep mode;

4.3.2.1 Enter Sleep by NSLEEP pin

By asserting the NSLEEP pin low, the SIG100 will enter Sleep mode.

4.3.2.2 Enter Sleep by register setting

By setting *REG_6[7]* high, the SIG100 will enter Sleep mode, and reset automatically *REG_6[7]* to low.

4.3.3 Exiting Sleep mode

There are three ways to exit Sleep mode. When exiting Sleep mode, the INH pin is raised and the device switches to Standby or Normal mode.

4.3.3.1 Exit Sleep by *WUM* detection

Upon detection of a *WUM*, the device exits Sleep mode, the INH pin raises and the device enters Standby mode.

In case the NSLEEP pin is low, the device remains in Standby mode, where the device is kept in *Soft-Reset*.
In case the NSLEEP pin is high, the device switches to Normal mode.

During WUM reception, the HDO pin is asserted low until WUM reception is completed, indicating the ECU on the wake-up process status. ECU shall wait for HDO to rise, before initiating new bytes transfer.

4.3.3.2 Exit sleep by NSLEEP pin

Upon detection of NSLEEP pin rise, the device exits Sleep mode, INH pin rises and enters Normal mode. When *Auto-WUM is* enabled, a WUM is transmitted over the powerline (see 4.3.1).

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4.3.3.3 Exit Sleep by HDC toggling

Upon detection of HDC pin toggle high-low-high, the device exits Sleep mode, INH pin rises, and enters Standby mode.
In case the NSLEEP pin is still low, the device remains in Standby mode, where the device is kept in *Soft-Reset*.
In case the NSLEEP pin is high, the device switches to Normal mode.
In this case, the **WUM is NOT transmitted** over the powerline.
ECU shall use the HDC pin to exit Sleep mode when the NSLEEP pin is not connected.

4.3.4 Sleep modes description

ECU can select between four Sleep modes (see 5.7). Table 12 describes the SIG100 sleep modes.

Table 12 - Sleep modes description

Sleep mode	Description	Typical Power consumption [A]	Performance
Enhanced sleep (SLP1)	The device wakes-up every 32ms to sense the powerline for WUM detection.	120µ	Wake-up detection with-in 64mSec. **Best detection in a noisy environment.**
Fast wake-up (SLP2)	The device continuously monitors the powerline for WUM detection.	1000µ	Fast wake-up detection with-in 250uSec.
Low-power (SLP3)	The device wakes-up every 32ms to sense the powerline for WUM detection.	85µ	Wake-up Detection with-in 64mSec.
Deep Sleep (SLP4)	The device does NOT wake-up to sense for bus activity, staying in deep sleep. Wake-up only locally by the ECU.	65µ	No bus wake-up detection.

4.3.4.1 Enhanced Sleep mode (*SLP1*)

By setting *REG_6[1:0] = '00'*, the enhanced Sleep mode (*SLP1*) is selected.
When entering *SLP1*, the device wakes-up every 32ms periodically to monitor (sense period) for activity on the powerline. If a WUM is detected, the device exits sleep mode as described in section 4.3.3.1, otherwise, the device returns to Sleep mode until the next sense period, and so on...

4.3.4.2 Fast wake-up Sleep mode (*SLP2*)

By setting *REG_6[1:0] = '01'*, the Fast wake-up Sleep mode (*SLP2*) is selected. The device continuously monitors the powerline for WUM detection. The WUM detection is within 250usec. When WUM is detected, the device exits Sleep mode as described in section 4.3.3.1.

4.3.4.3 Low-power Sleep mode (*SLP3*)

By setting *REG_6[1:0] = '10*', the low-power mode (*SLP3*) is selected. The device wakes-up every 32msec to sense activity on the powerline. If a WUM is detected, the device exits Sleep mode as described in section 4.3.3.1, otherwise, the device returns to Sleep until the next sense period, and so on.

4.3.4.4 Deep Sleep mode (*SLP4*)

By setting *REG_6[1:0] = '11'*, the Deep Sleep mode (*SLP4*) is selected. The device does NOT wake-up to sense the powerline for activity, rather than stay in deep sleep, whereas most of its hardware is shut down to maintain the lowest power consumption.
The device exits Deep Sleep mode only locally, either by NSLEEP or HDC pins (see 4.3.3.2 and 4.3.3.3).

4.4 Auto Sleep mode

Auto sleep mode is enabled either by pulling the NAUTO_SLEEP pin low or by clearing *REG_6[5].*
The last action prevails.
When enabled, the SIG100 automatically enters into Sleep mode when no Transmission or reception to/from the powerline (DC-BUS idle) for more than *AutoSleep-timeout* setting.
The SIG100 exits sleep mode in case of NSLEEP/HDC pin toggling, or by *WUM* detection (see 4.3.3).

Table 13 describes the *AutoSleep-timeout* configuration options.

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Table 13 - *AutoSleep-timeout* configuration

REG_6[3:2]	AutoSleep-timeout [Seconds]
00	Auto Sleep mode disabled
01	2
10	4
11	6 (default)

4.5 Sleep modes Examples

4.5.1.1 Sleep Example 1 - Enter by NSLEEP, Exit Sleep mode by *NSLEEP & WUM*

Figure 15 depicts entering sleep by NSLEEP and exit sleep by NSLEEP pin (Node A) and WUM detection (Node B).
In this example, the ECU wakes-up device Node A by raising the NSLEEP pin, causing the INH pin to raise, and a WUM is transmitted over the powerline (*Auto-WUM* is enabled) to wake-up Node B.
While transmitting the WUM, device Node A asserts HDO pin low. After completion of WUM transmission, the HDO pin is raised again (can be used as signal/interrupt to ECU). At the Node B side, during its sensing period (e.g. *SLP1),* the WUM is detected, and the INH pin rises while switching to Standby mode. Node B HDO pin is asserted low for the reaming duration of WUM reception. Then, ECU Node B raises the NSLEEP pin and the device switches to Normal mode.

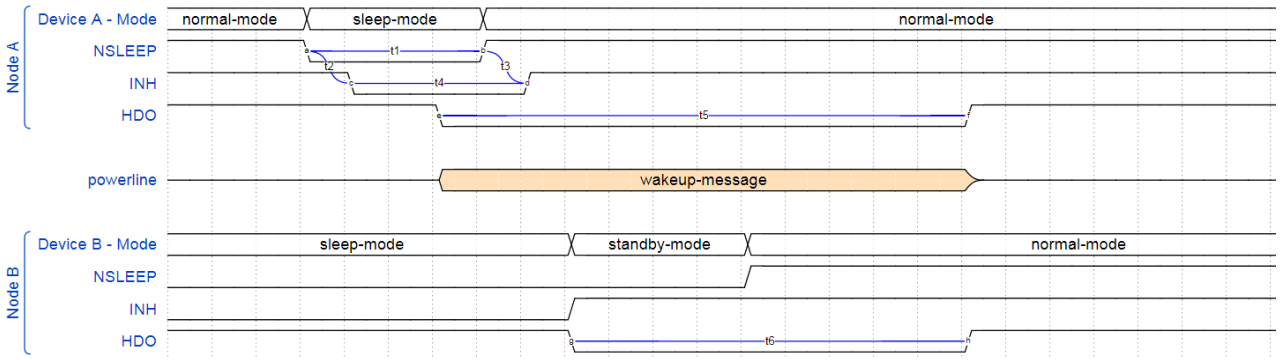


Figure 15 - Enter sleep by NSLEEP, Exit sleep by *NSLEEP & WUM*

4.5.1.1 Sleep Example 2 - Enter sleep by control register bit, exit sleep by HDC

Figure 16 depicts entering sleep by setting *REG_6[7]* high and exiting Sleep mode by toggling the HDC pin.
In this example, ECU configured *REG_6[7]* high using Command mode, the device enters Sleep mode, and INH pin drops. After a while, ECU toggle HDC pin low to high, and the device exits Sleep mode without transmitting the WUM, raising the INH pin and switching to Normal mode again.

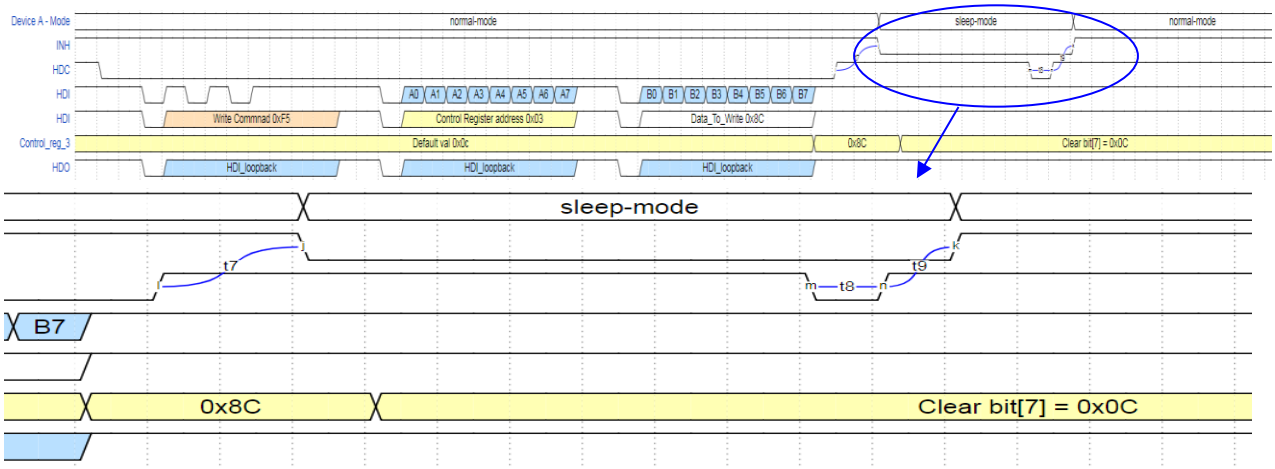


Figure 16 - Enter sleep by control register bit, Exit sleep by *HDC*

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5. SIG100 Registers

The SIG100 internal registers are used for configuration and status checks. Each register is accessible from its ECU for *Read* and *Write* operations. This section elaborates on the registers and their default values after power-up/reset. See section 0 for more details about the registers configuration method.

Table 14 - Registers summary table

Register name	Addr.	Description
REG_0 - 'Device Control 0'	0x00	Bitrate selection, Loopback, nAuto_freq_change
REG_1 - 'Device Control 1'	0x01	Transmit level control
REG_2 - 'Frequency Main select'	0x02	Main Carrier frequency selection
Reg_3 - 'Frequency ALT1 select'	0x03	Alternate frequency 1 selection
REG_4 - 'Frequency ALT2 select'	0x04	Alternate frequency 2 selection
REG_5 - 'Active frequency'	0x05	Read only – read the active frequency - Main/Alt1/Alt2
REG_6 - 'Sleep control'	0x06	Sleep mode selection and functionality
REG_96 - SIG100 UUID[47:40]	0x96	Read only - UUID[47:40]
REG_97 - SIG100 UUID[39:32]	0x97	Read only - UUID[39:32]
REG_98 - SIG100 UUID[31:24]	0x98	Read only - UUID[31:24]
REG_99 - SIG100 UUID[23:16]	0x99	Read only - UUID[23:16]
REG_9A- SIG100 UUID[15:8]	0x9A	Read only - UUID[15:8]
REG_9B - SIG100 UUID[7:0]	0x9B	Read only - UUID[7:0]

5.1 REG_0 - 'Device Control 0' (Address 0x00)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R/W[0]	R/W [1]	R/W [0]	R/W [1]	R/W [0]	R/W [1]	R/W [0]
Reserved	0	nLoopBack	Remote loopback	nAuto_Freq _change	Bitrate_sel[2:0]		

Bit [2:0] - Bitrate selection (see 3.4).
Bit [3] - nAuto_freq_change: '0' enables auto frequency change mode (see 3.4.4).
Bit [4] - Enable remote loopback mode (see 3.4.6).
Bit [5] - nLoopBack -Set this bit to disables loopback between HDI to HDO (see 3.4.5).
Bit [6] - Must be written as '0'
Bit [7] - Reserved
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.2 REG_1 - 'Device Control 1' (Address 0x01)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R/W [0]	R/W [0]	R/W[0]	R/W [1]	R/W [1]	R/W [1]	R/W [1]	R /W[1]
Enable TXO high power	0	0	TX signal level	1	1	1	1

Bit [3:0] - Must be written as '1111'
Bit [4] - TX signal level control at TXO pin: '0' - 1Vpp, '1'- 2Vpp (see 2.6.8).
Bit [6:5] - Must be written as '00'
Bit [7] - Enable TXO high power. Set this bit to enable maximal TXO drive of 66mA, clear this bit for maximal TXO drive of 33mA (see 2.6.8).
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.3 REG_2 - 'Main Frequency Select' (Address 0x02)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R/W [0]	R/W [1]	R/W [0]	R/W [1]	R/W [0]	R/W [0]	R/W [0]	R/W [0]
Main Carrier Frequency Configuration							

Bit [7:0] - Main Carrier Frequency configuration. The default configuration is 13MHz [1].

[1] After REG_2 configuration no other internal register configuration is allowed for 1ms. It is recommended to place the carrier frequency configuration last during multiple registers configuration and wait at least 1ms after HDC is released (See 3.4.3 - Carrier frequency configuration).

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5.4 REG_3 - 'ALT 1 Frequency Select' (Address 0x03)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R/W [0]	R/W [0]	R/W [0]	R/W [0]	R/W [0]	R/W [0]	R/W [0]	R/W [0]
Alternate Carrier Frequency 1 Configuration – ALT1							

Bit [7:0] - Alternate Carrier Frequency 1 configuration. Default configuration is 5MHz
(See section 3.4.3 Carrier frequency configuration).

5.5 REG_4 - 'ALT 2 Frequency Select' (Address 0x04)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R/W [1]	R/W [0]	R/W [1]	R/W [0]	R/W [1]	R/W [0]	R/W [1]	R/W [0]
Alternate Carrier Frequency 2 Configuration – ALT2							

Bit [7:0] - Alternate Carrier Frequency 2 configuration. The default configuration is 22MHz (See section 3.4.33.4.3).

5.6 REG_5 - 'Active Frequency Select' (Read-Only, Address 0x05)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
Current Active Carrier Frequency Configuration							

Bit [7:0] - Current Active Carrier Frequency (See section 3.4.33.4.3).

5.7 REG_6 - 'Sleep Control' (Address 0x06)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
W [0]	R/W [1]	R/W [1]	R/W [1]	R/W [1]	R/W [1]	R/W [0]	R/W [0]
Enter Sleep mode	Auto WUM	nAutoSleep	Long WUM	AutoSleep-timeout		Sleep modes selection	

Bit [1:0] '00' - Enhanced Sleep mode [*SLP1*],
'01' -Fast wake-up Sleep mode [*SLP2*],
'10' - Low-power sleep mode [*SLP3*],
'11' - Deep Sleep mode [*SLP4*] (see section4.3).
Bit [3:2] - *AutoSleep-timeout* - The time before entering into sleep mode (when AutoSleep mode is enabled). The duration is in seconds x 2 (i.e. default 6 sec), see 4.4.
Bit [4] - Wake-up message duration over the powerline (see Table 11).
Bit [6] - Auto wake-up message (WUM): '0' disables transmission of WUM upon NSLEEP pin wakeup.
Bit [7] - Enter Sleep mode reg. Activates the Sleep mode as selected in Bit [1:0] by setting bit[7]. Upon entering Sleep mode, bit [7] is automatically cleared to '0'.

R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.8 REG_96 – UUID[47:40] (Address 0x96)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[47:40]							

Bits [7:0] - UUID[47:40]

R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.9 REG_97– UUID[39:32] (Address 0x97)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[39:32]							

Bits [7:0] - UUID[39:32]

R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.10 REG_98 – UUID[31:24] (Address 0x98)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[31:24]							

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Bits [7:0] - UUID[31:24]
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.11 REG_99 – UUID[23:16] (Address 0x99)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[23:16]							

Bits [7:0] - UUID[23:16]
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.12 REG_9A – UUID[15:8] (Address 0x9A)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[15:8]							

Bits [7:0] - UUID[15:8]
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.13 REG_9B – UUID[7:0] (Address 0x9B)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R	R	R	R	R	R	R	R
UUID[7:0]							

Bits [7:0] - UUID[7:0]
R - Readable bit, W - Writeable bit [x] - Value on power-up. '1' - bit is set; '0' - bit is cleared

5.14 Registers configuration (Command mode)

The Command mode allows the ECU to access the SIG100 internal registers for write and read operations.
Enter the Command mode by lowering the HDC pin. During Command mode, the SIG100 is in *Soft-Reset* state. The device's powerline communication is disabled. Every register configuration is kept until the next power-up/reset event.
During command mode, the SIG100 will automatically learn the Host bitrate regardless of SIG100 configured bitrate. When exiting the command mode to normal mode, the SIG100 returns to its configured bitrate. This way, the host does not need to switch to SIG100 bitrate during configuration mode.
For example, upon hard-reset/ power-up , the default SIG100 bitrate is 19.2kbit/s. Host bitrate is set to 115.2 kbit/s. A host can configure the SIG100 bitrate REG_0[2:0] using 115.2kbit/s bitrate during configuration. When returning to normal mode, the SIG100 will be configured to 115.2kbit/s until the next hard-reset/power-cycle.

5.14.1 WRITE-REG command

Write register command consists of three bytes as described in Table 15.

Table 15 - WRITE-REG command structure

1st Byte	2nd Byte	3rd Byte
0xF5	**Register address**	**Data to write**

1st byte, 0xF5, is the write command byte.

2nd byte is the designated register address to write to.

3rd byte is the data byte value to be written.

For example, writing 0x34 to REG_3 (address 0x03) preformed as follows:

1. Lower the HDC pin (Enter Command mode).

2. Wait at least 100nsec

3. Transfer 3 bytes: [0xF5][0x03][0x34] - The value 0x34 is written to REG_3.

4. Wait for at least 100ns.

5. Raise the HDC pin (Exit Command mode to Normal mode).

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5.14.1.1 Example 1 - *WRITE-REG* command

Figure **17** depicts a *WRITE-REG* command sequence. First, the HDC is pulled low and the device enters the Command mode. The ECU sends the write command with the 1st byte of 0xF5, followed by the control register address byte (A[7:0]) and the data byte to be written (B[7:0]). After completing the write sequence, the HDC pin is pulled high and the device returns to Normal mode.

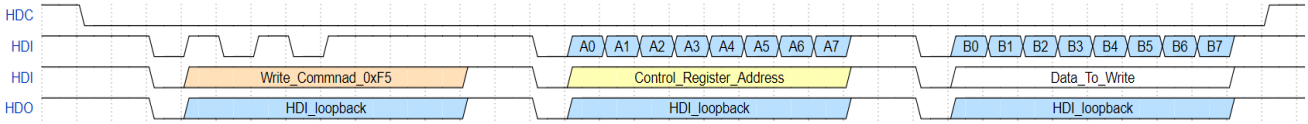


Figure 17- **WRITE-REG command sequence**

5.14.2 READ-REG command

A READ-REG command consists of 2 bytes as described in Table 16.

Table 16 - READ-REG command structure

1st Byte	2nd Byte
0xFD	**Register address**

1st byte, 0xFD, is the Read command byte.

2nd byte is the designated register address to read from.

Following the second byte, the SIG100 outputs the register value to ECU.

For example, reading from REG_5 (address 0x05) is performed as follows:

1. Lower the HDC pin (Enter Command mode).
2. Wait at least 100nsec
3. Transfer 2 bytes: [0xFD][0x05]
4. Wait for the SIG100 to output the value of REG_5.
5. Wait for at least 100ns.
6. Raise the HDC pin (Exit Command mode to Normal mode).

5.14.2.1 Example 2 - *READ-REG* command

Figure 18 depicts a *READ-REG* command sequence. First, the HDC is pulled low and the device enters the Command mode. The ECU sends the read command with the 1st byte of 0xFD, followed by the control register address byte (A[7:0]). Then the ECU receives the register internal value (B[7:0]). The HDC pulled back to high and the device returns to Normal mode.

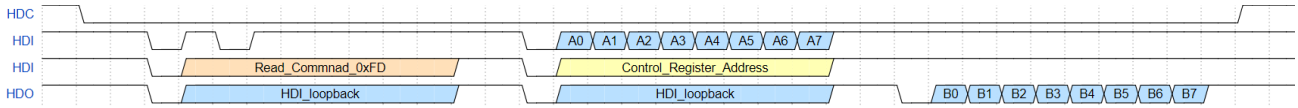


Figure 18 – READ-REG command sequence

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6. Specifications

Table 17 - Absolute maximal rating

Parameter	Symbol	Comments	Min.	Typ.	Max.	Unit
Input voltage, DC	V_{im}		-0.6	3.3	3.9	V
Output voltage, DC	V_{om}		-0.6	3.3	3.9	V
Ambient temperature	T_{am}		-40		125	°C
Storage temperature	T_{sm}		-55		150	°C

Table 18 - Recommended operation conditions

Parameter	Symbol	Comments	Min.	Typ.	Max.	Unit
Supply Voltage	V_{DVCC} V_{AVCC}		3.0	3.3	3.6	V
Supply Voltage ripple	V_{CC_RIP} A_{VCC_RIP}	Max 2.5MHz, waveform type of triangular		50m		V-p-p
Ambient operating temperature range	T_A		-40		105	°C
Minimum high-level input voltage	V_{IH}		2			V
Maximum low-level input voltage	V_{IL}				0.8	V
Minimum high-level output voltage	V_{OH}		2.4			V
Maximum low-level output voltage	V_{OL}				0.4	V
Maximal output current	I_{out}	see Table 1				
Maximum input current	I_{IN}		-1		1	µA

Table 19 - Device characteristics

Parameter	Symbol	Comments	Min.	Typ.	Max.	Unit
External components requierments						
Powerline coupling capacitor	$C_{coupling}$	Capacitor voltage rate should be selected with respect to powerline voltage	1.0	2.2	2.4	nF
Protection diodes capacitance	D_{protec}				10	pF
Capacitor at VCAP	V_{cap}		1	4.7		µF
Capacitor at PLLCAP	PLL_{cap}		1			µF
Capacitor at VREF	$VREF_{cap}$		1			µF
Inductor at L1	L1	see 2.6.4		3.3 / 18		µH
Inductor at L2	L2			15		µH
L1 pin input capacitance					1	pF
Crystal frequency	$Xtal_{freq}$	see2.6.2 2.6.2		16		MHz
Crystal frequency tolerance	$Xtal_{ppm}$				50	±ppm
AC signals characteristics						
Tx signal at TXO	TXO_{lev_1}	TXON high (transmission is active) see 2.6.8.		1		V-p-p
	TXO_{lev_2}			2		V-p-p
TXO input impedance	TXO_{In}	TXON low (transmission is not active)	5.3k			Ω
TXO output impedance	TXO_{out}	TXON high		18		Ω

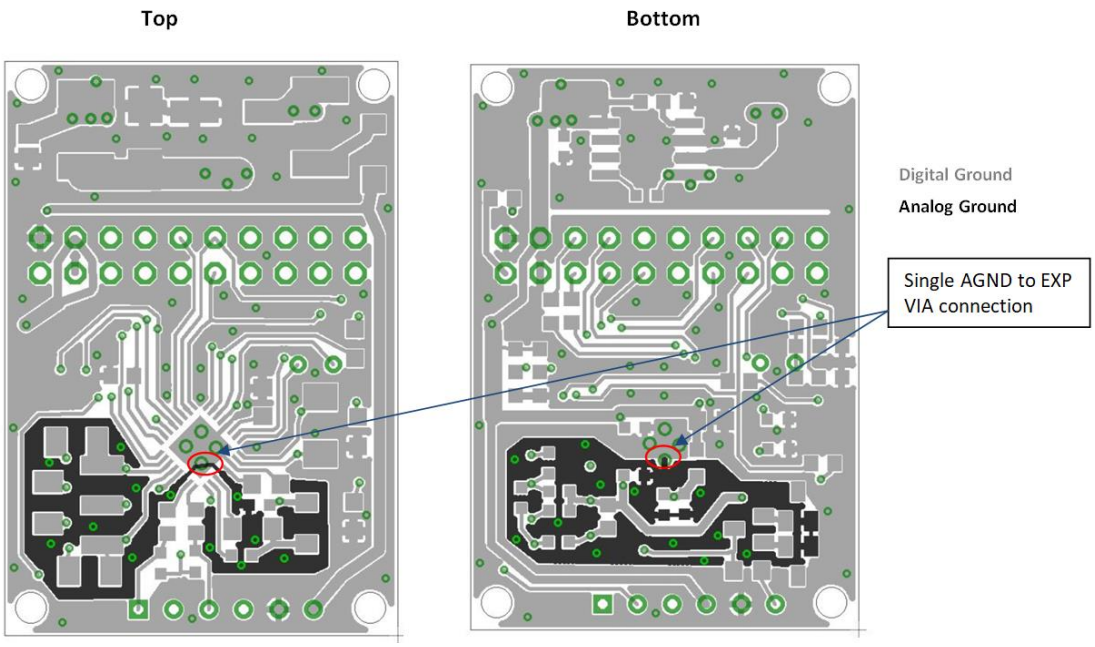
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Parameter	Symbol	Comments	Min.	Typ.	Max.	Unit
		(transmission is active)				
TXO driving current	I_{TXO}	TXON high (transmission is active)	33		66	mA
Rx signal at RXI	RXI_{lev}		10m		3.3	V-p-p
RXI input impedance	RXI_{In}		5.1k			Ω
Carrier Frequency in-band (channels selection)	F_c	Selection resolution is 100kHz, a total of 251 carrier frequencies, see 3.4.3	5		30	MHz
Adjacent channels spacing	F_{adj}	The space between two adjacent channels operating over the same powerline.	1			MHz
Timing requierments of UART/LIN interface						
UART bitrate	$UART_{br}$	ECU UART bitrate, see 3.4	9.6		115.2	kbit/s
Powerline latency	T_{RX_delay}	The delay from ECU starts bit transmission to ECU start bit reception.		2.5		T_{bit}
Powerline PLC-byte length	T_{pl_byte}			10		T_{bit}
Timing of device operation modes						
Power-up/ hard-reset	T_{init}	Initialization time after power-up or hard-reset event.		2		ms
Carrier frequency change	T_{freq_cng}	Carrier frequency change process time. During this period no-host operation is allowed.		1		ms
Register configuration	$T_{hdc_to_hdi}$	The minimal wait time from HDC drop/rise to HDI drop.	250			ns
Current Consumtption @ 3.3V						
Normal TX mode – low power	I_{Tx_lp}	TXON high (transmission is active)		60		mA
Normal TX mode – high power	I_{Tx_hp}			80		mA
Normal RX mode	I_{RX}	TXON low (transmission is not active)		30		mA
Enhanced sleep (SLP1)	I_{slp1}	see 4.3		120		µA
Fast wake-up (SLP2)	I_{slp2}	see 4.3		1000		µA
Low-power (SLP3)	I_{slp3}	see 4.3		85		µA
Deep Sleep (SLP4)	I_{slp4}	see 4.3		65		µA

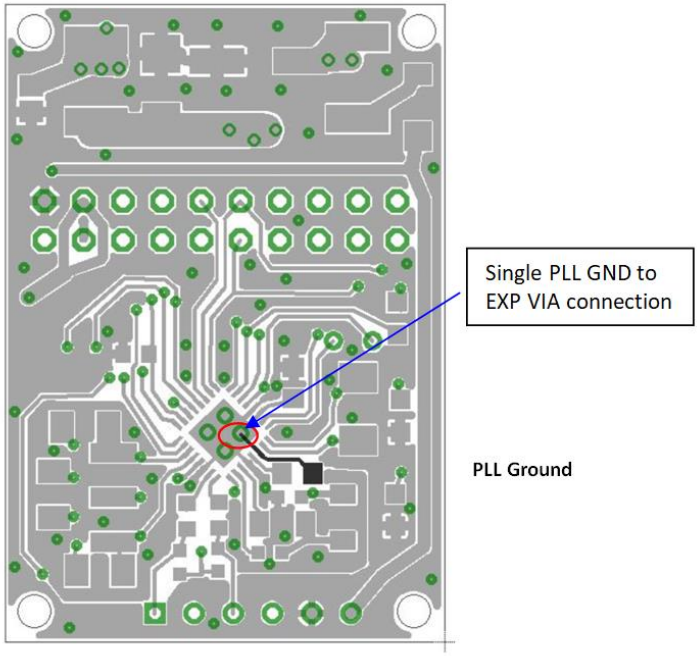
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7. SIG100 PCB layout recommendation

Note: Analog ground layer and GND PLL should be connected to the digital ground near the Exp pad.



TOP - PLL Ground connection to EXP



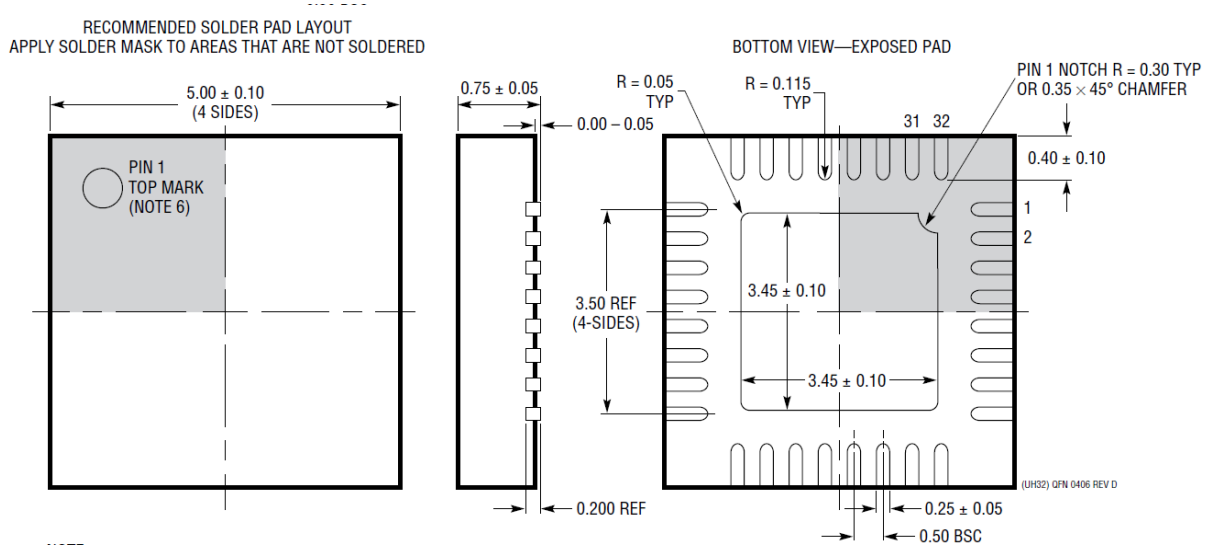
- ✓ VCC and DGND layout traces should be as wide as possible. Connect a 0.1uF capacitor between each VCC and DGND pins, as close as possible to the pins.
- ✓ Connect AGND to EXP with a single short trace.
- ✓ Connect PLL_GND to EXP with a single short trace.
- ✓ Connect L1, L2, C3, C5, C7, C8, C11, and C12 as close as possible to their pins.
- ✓ Connect R1 as close as possible to the RXI pin.
- ✓ Connect all filtering capacitors as close as possible to their pins.
- ✓ Connect crystal and its capacitors close to OSCI and OSCO pins. Keep DGND plan around them.

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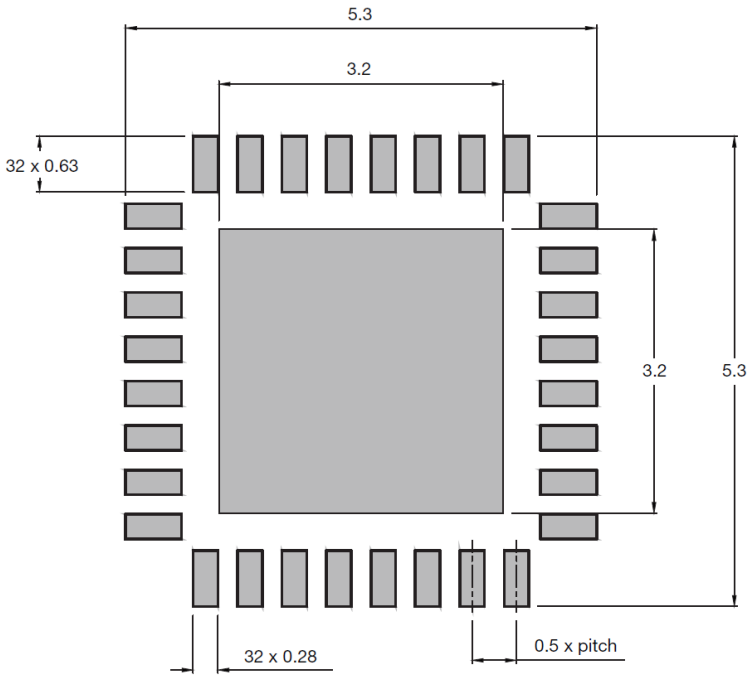
8. Package, Mechanical

The SIG100 package is QFN 32 5mm x 5mm.

8.1 Mechanical Drawing



8.2 PCB drawing



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8.3 Soldering profile

Soldering reflow profile is according to IPC/JEDEC J-STD-020 (MSL3).

- The peak temperature (TP) is 260°C.
- Holding time is between 60 sec to 120 sec between TH min 150°C to TH max 200°C.
- Liquidus temperature (TL) is 217 °C. Liquidus time is between 60 sec to 150 sec.
- TL to TP max ramp-up is 3°C/sec.
- TP to TL max cooldown rate is 6°C/sec.
- Max time above 255°C (Tp) is 30 sec.

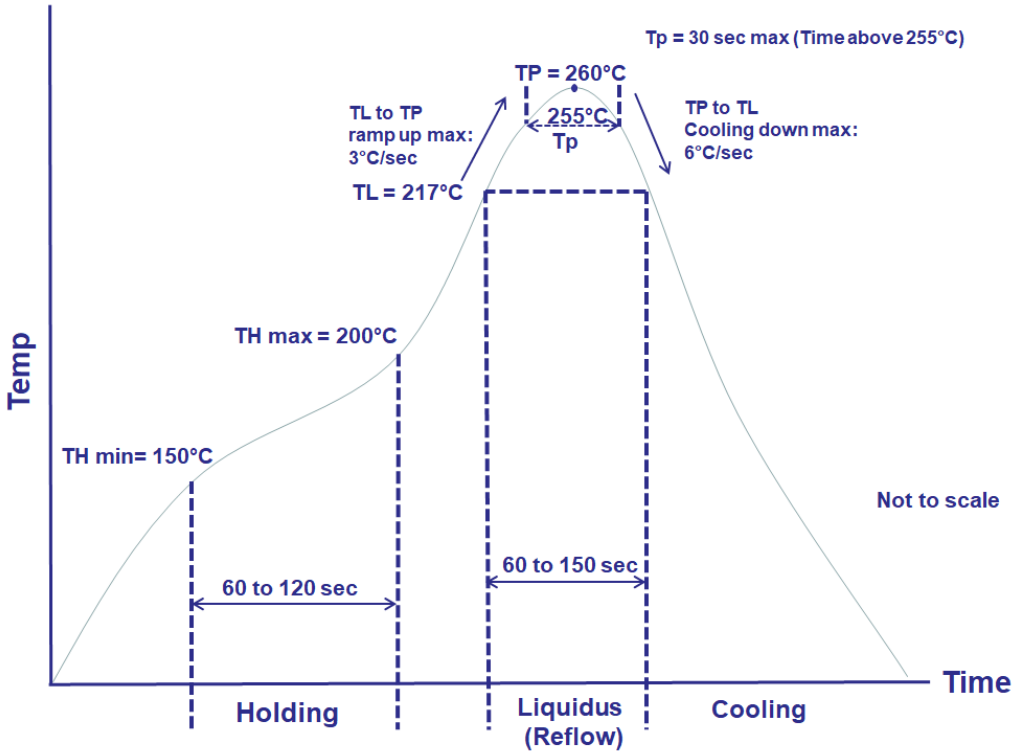


Figure 19 – Representation of IPC/JEDEC J-STD-020 (MSL3) profile

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9. Test Environment

Figure 20 depicts the DC-BUS Test environment that allows testing the SIG100 devices in Lab emulated DC powerline attenuation environment.

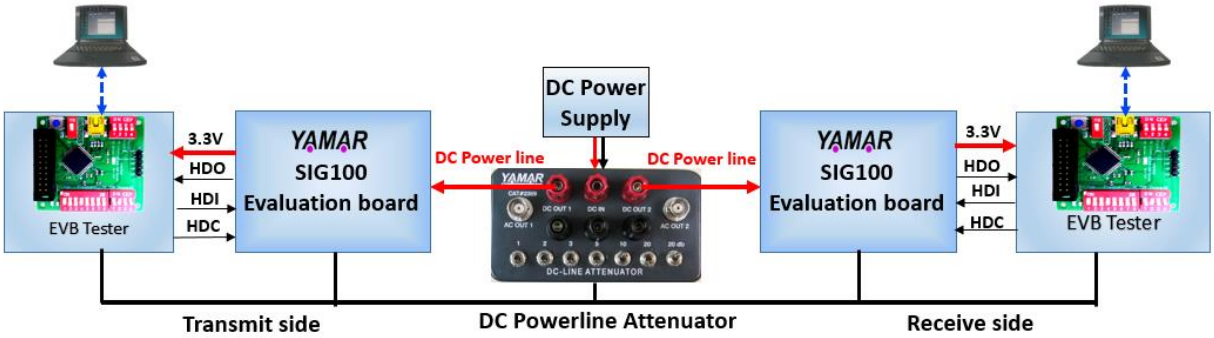


Figure 20 - DC-BUS Test environment

This test environment consists of two SIG100 evaluation boards (EVB), two EVB Testers, and a PC Test Program. The DC-Powerline Attenuator is optional.

On the transmitting side, when the USB interface is not connected to a PC, it can generate repeatedly a predefined test message [A B C ...X Y Z] saving the need for a second PC. At the receiver side, the received test message is transferred from the EVB through the USB interface to a PC. The Test program analyzes the received predefined messages and performs BER statistics including error byte, missed byte, and noise byte counting indications.

The DC-powerline attenuator is used to test the communication performance in variable attenuation levels (0-61dB), emulating a DC powerline environment. When connecting the EVB directly to a power supply, it is recommended to add in serial to the power supply an inductor (>22uH) to avoid strong attenuation due to power-supply input filtering capacitors.

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Revision History

Rev.	Date	Description
0.73	20/05/2019	Initial preliminary revision.
0.74	2/8/2019	Rearrange paragraphs
0.75	2/9/2019	Update schematics, Table 18.
0.76	23/09/2019	Editing.
0.77	02/10/2019	Update Table 3 and Figure 7.
0.78	14/11/2019	Update Figure 5 and NSLEEP pin description.
0.79	19/01/2020	Update Table 3.
0.80	19/02/2020	Update clause 2.5.3. Add UUID clause 3.4.7 Update clause 5 with UUID REGs.
0.81	21/04/2020	Add soldering profile description in section 8.3.
0.82	01/08/2020	Update 2.5.3, 2.5.6 and Table 19.
0.83	18/11/2020	Update section 3.4.3 description.
0.84	01/12/2020	Update Table 2.
0.85	12/01/2021	Editing.
0.86	01/07/2021	Add section 2.3.
0.87	16/01/2022	Update Table 3.

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