



Porting an application from the ST10F269 to the ST10F272B/E

Introduction

The ST10F272B and ST10F272E are members of the STMicroelectronics ST10 family of 16-bit single-chip CMOS microcontrollers. They are functionally upward compatible with the ST10F269.

The ST10F272B and the ST10F272E devices differ only in terms of XRAM memory size and XPeripherals. In this application note, the ST10F272B and ST10F272E will be referred to as ST10F272 for all aspects that are applicable to both products. For points specific to each product, the full name with the B or E extension will be used.

The goal of this document is to highlight the differences between ST10F269 and ST10F272 devices. It is intended for hardware or software designers who are adapting an existing application based on the ST10F269 to the ST10F272.

This document presents the ST10F272's modified functionalities and the new ones, and goes on to describe the modified and the new registers. For each part, the differences with the ST10F269 that may have an impact when replacing the ST10F269 by the ST10F272 are stressed and some advice is given on the way they can be handled.

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1 Modified features

1.1 Pinout

1.1.1 Pinout modification summary

Table 1 summarizes the modifications made to the pinout.

Table 1. Pinout modifications

Pin number	ST10F269		ST10F272	
	Name	Function	Name	Function
17	DC2	Internal voltage regulator decoupling. Connect to nearest V_{SS} via a 330nF capacitor.	V_{DD}	5V power supply pin
56	DC1	Internal voltage regulator decoupling. Connect to nearest V_{SS} via a 330nF capacitor.	V_{18}	Internal voltage regulator decoupling. Connect to nearest V_{SS} via a 10 - 100nF capacitor.
99	EA	Selects code execution out of internal Flash memory or external memory according to level during reset.	$\overline{EA}-V_{STBY}$	Selects code execution out of internal Flash memory or external memory according to level during reset. Power supply input for the standby mode.
143	V_{SS}	Ground pin	XTAL3	Input to the 32 kHz oscillator amplifier circuit. When not used, must be tied to ground to avoid consumption. Additionally, bit OFF32 in RTCCON register must be set.
144	V_{DD}	5V power supply pin	XTAL4	Output of the 32 kHz oscillator amplifier circuit. When not used, must be left open to avoid spurious consumption.

1.1.2 Pin 17

On the ST10F269, a decoupling capacitor of 330nF minimum has to be connected between the pin 17 (named DC2) and the nearest V_{SS} pin.

This is no longer the case for the ST10F272 device where pin 17 is a V_{DD} pin.

Hardware impact

PCB must be adapted.

Software impact

None.

1.1.3 Pin 56

On the ST10F269, a decoupling capacitor of 330nF minimum has to be connected between the pin 56 (named DC1) and the nearest V_{SS} pin.

On the ST10F272, pin 56 is named V_{18} and a capacitor of value between 10nF minimum and 100nF maximum must be connected between it and the nearest V_{SS} pin.

Hardware impact

Change on the capacitor value. As the value is much lower, the footprint of the capacitor might be smaller and then a modification of the PCB is needed.

Software impact

None.

1.1.4 Pin 99

On the ST10F269, pin 99 is \overline{EA} and used upon reset to select the start from the internal Flash memory or the external memory.

On the ST10F272, pin 99 has the additional function of providing the 5V power supply to the device in standby mode (new power-saving mode), it is called $\overline{EA}-V_{STBY}$.

Hardware impact

The modification depends on the previous use of the ST10F269 and on whether the Standby mode is used or not.

For an application where the Standby mode is not used, no change to the PCB is required. If the new application uses the Standby mode, the $\overline{EA}-V_{STBY}$ pin must be separated from the common 5V and have a specific supply path.

Software impact

None.

1.1.5 Pins 143 and 144

These pins are V_{SS} and V_{DD} , respectively, in the ST10F269. On the ST10F272 they are used as XTAL3 and XTAL4 for connection to an optional 32 kHz crystal to clock the Real Time Clock during power-down.

Hardware impact

PCB must be redesigned.

If the optional 32 kHz is not used:

- Pin 143 (XTAL3) must be linked to ground like on the ST10F269
- Pin 144 (XTAL4) must be left open. It can also be connected to ground via a capacitor to reduce the potential RF noise that might be propagated inside the device if the pin is left floating.

Software impact

In case the optional 32 kHz is not used, the OFF32 bit of the RTCCON register must be set. Prior to setting the OFF32 bit in the RTCCON register, the RTC must be enabled by setting RTCEN, bit 4 of XPERCON, and XPEN, bit 2 of SYSCON.

1.2 XRAM

The ST10F272B and ST10F272E devices do not have the same size of XRAM. Each configuration is detailed hereafter.

1.2.1 ST10F272B's XRAM

The ST10F269 and the ST10F272B have the same size of extension XRAM: 10 Kbytes.

The XRAM of the ST10F269 is divided into two ranges being XRAM1 of 2 Kbytes and XRAM2 of 8 Kbytes:

- The **XRAM1** address range is 00'E000h - 00'E7FFh if enabled (XPEN and XRAM1EN, bit 2 of SYSCON register and of XPERCON register, respectively, must both be set).
- The **XRAM2** address range is 00'C000h - 00'DFFFh if enabled (XPEN and XRAM2EN, bit 2 of SYSCON register and bit 3 of XPERCON register, respectively, must both be set).

The XRAM of the ST10F272 is divided into two ranges, XRAM1 of 2 Kbytes (compatible with the ST10F269) and XRAM2 of 8 Kbytes with a user re-programmable address range and the StandBy mode.

- The **XRAM1** address range is 00'E000h - 00'E7FFh if enabled (XPEN and XRAM1EN, bit 2 of SYSCON register and bit 2 of XPERCON register must both be set).
- The **XRAM2** address range is 09'0000h - 09'1FFFh, by default (mirrored every 16 Kbytes in the range 09'0000h -0F'FFFFh), if enabled (XPEN and XRAM2EN, bit 2 of SYSCON register and bit 3 of XPERCON register, must both be set).

Hardware impact

None.

Software impact

There is no change in the enabling of the XRAM blocks: XPERCON register bits, XRAM1EN and XRAM2EN, and SYSCON register bit, XPEN, are used to enable them.

The memory mapping of the application is impacted by the difference in XRAM2 location. A new register has been created in order to allow the user to remap XRAM2 (please refer to [Section 4.1: XADRS3 register on page 28](#) for details).

1.2.2 ST10F272E's XRAM

The ST10F269 has 10 Kbytes of extension RAM whereas the ST10F272E has 18 Kbytes.

The XRAM of the ST10F269 is divided into two ranges being XRAM1 of 2 Kbytes and XRAM2 of 8 Kbytes:

- The **XRAM1** address range is 00'E000h - 00'E7FFh if enabled.
- The **XRAM2** address range is 00'C000h - 00'DFFFh if enabled.

The XRAM of the ST10F272E is divided into two ranges being XRAM1 of 2 Kbytes (compatible with the ST10F269) and XRAM2 of 16 Kbytes with a user reprogrammable address range:

- The **XRAM1** address range is 00'E000h - 00'E7FFh if enabled (XPEN and XRAM1EN, bit 2 of SYSCON register and bit 2 of XPERCON register, respectively, must be set).
- The **XRAM2** address range is 09'0000h - 09'3FFFh, by default (mirrored every 16 Kbytes in the range 09'0000h - 0F'FFFFh), if enabled (XPEN and XRAM2EN, bit 2 of SYSCON register and bit 3 of XPERCON register, respectively, must be set).

Hardware impact

None.

Software impact

There is no change in the enabling of the XRAM blocks: XPERCON register bits, XRAM1EN and XRAM2EN, and SYSCON register bit, XPEN, are used to enable them.

The memory mapping of the application is impacted by the difference in XRAM size and by the location of XRAM2. A new register has been created in order to allow the user to remap the XRAM2 (please refer to [Section 4.1: XADRS3 register on page 28](#) for details).

1.3 Flash EEPROM

Table 2. Flash memory key characteristics

Characteristic	ST10F269	ST10F272
Flash size	256 Kbytes	256 Kbytes
Flash organization	7 blocks	8 blocks
Programming voltage	5 volts	5 volts
Programming method	Write/Erase Controller	Write/Erase Controller
Program / Erase cycles	100000 cycles	100000 cycles

Table 3. Flash memory mapping

Segment	ST10F269 Flash mapping		ST10F272 Flash mapping	
8	08'0000-08'FFFF	External memory	08'0000-08'FFFF	Flash registers
7..5	05'0000-07'FFFF	External memory	05'0000-07'FFFF	Reserved
4	04'0000-04'FFFF	Block6: 64 Kbytes	04'0000-04'FFFF	Block7: 64 Kbytes
3	03'0000-03'FFFF	Block5: 64 Kbytes	03'0000-03'FFFF	Block6: 64 Kbytes
2	02'0000-02'FFFF	Block4: 64 Kbytes	02'0000-02'FFFF	Block5: 64 Kbytes
1	01'8000-01'FFFF	Block3: 32 Kbytes	01'8000-01'FFFF	Block4: 32 Kbytes
	01'0000-01'7FFF	External memory or remap of Blocks 0-2	01'0000-01'7FFF	External memory or remap of Blocks 0-3
0	00'8000 - 00'FFFF	External memory Internal RAM and Registers	00'8000 - 00'FFFF	External memory Internal RAM and Registers
	00'6000 - 00'7FFF	Block 2: 8 Kbytes	00'6000 - 00'7FFF	Block3: 8 Kbytes
	00'4000 - 00'5FFF	Block 1: 8 Kbytes	00'4000 - 00'5FFF	Block2: 8 Kbytes
	00'0000 - 00'3FFF	Block 0: 16 Kbytes	00'2000 - 00'3FFF	Block1: 8 Kbytes
00'0000 - 00'1FFF			Block0: 8 Kbytes	

1.3.1 Hardware impact

None.

1.3.2 Software impact

As the first 32 Kbytes of Flash memory are now divided into four sectors of 8 Kbytes each in the ST10F272 whereas the ST10F269 had only three sectors, the mapping of the application is impacted.

Moreover, the Flash memory Write/Erase controller is different and therefore the programming routines must be updated.

When the bit ROMEN of the SYSCON register is set, that is, when the internal Flash memory is enabled, accesses to the address range 05'0000h - 07'FFFFh are not redirected to external memory. The linker-locator configuration of the toolchain should be checked in order to prevent any use of this memory range.

1.4 A/D converter

In the ST10F272, the analog/digital converter has been redesigned (compared to the A/D converter in the ST10F269). The ST10F272 still provides an analog/digital converter with 10-bit resolution and an on-chip sample and hold circuit.

1.4.1 Hardware / Software impact: conversion timing control

The A/D converter in the ST10F272 is not fully compatible with that of the ST10F269 (timing and programming model).

In the ST10F269, the sample time (to charge the capacitors) and the conversion time are programmable and can be adjusted to the external circuitry. The total conversion time is compatible with the formula used for ST10F269, whereas the meanings of the ADCTC and ADSTC bit fields are no longer compatible.

Table 4. ST10F272 conversion timing table

ADCTC	ADSTC	Sample	Comparison	Extra	Total conversion
00	00	TCL * 120	TCL * 240	TCL * 28	TCL * 388
00	01	TCL * 140	TCL * 280	TCL * 16	TCL * 436
00	10	TCL * 200	TCL * 280	TCL * 52	TCL * 532
00	11	TCL * 400	TCL * 280	TCL * 44	TCL * 724
11	00	TCL * 240	TCL * 120	TCL * 52	TCL * 772
11	01	TCL * 280	TCL * 560	TCL * 28	TCL * 868
11	10	TCL * 400	TCL * 560	TCL * 100	TCL * 1060
11	11	TCL * 800	TCL * 560	TCL * 52	TCL * 1444
10	00	TCL * 480	TCL * 960	TCL * 100	TCL * 1540
10	01	TCL * 560	TCL * 1120	TCL * 52	TCL * 1732
10	10	TCL * 800	TCL * 1120	TCL * 196	TCL * 2116
10	11	TCL * 1600	TCL * 1120	TCL * 164	TCL * 2884

The user should take care of the Sample time parameter: This is the time during which the capacitances of the converter are charged via the respective analog input pins. [Table 5](#) shows the differences in sample time.

Table 5. ST10F272 vs ST10F269 sample time comparison table

ADCTC	ADSTC	ST10F269 Sample time	ST10F272 Sample time	Ratio F272E_time / F269_time
00	00	TCL * 48	TCL * 120	2.5
00	01	TCL * 96	TCL * 140	1.46
00	10	TCL * 192	TCL * 200	1.04
00	11	TCL * 384	TCL * 400	1.04
11	00	TCL * 96	TCL * 240	2.5
11	01	TCL * 192	TCL * 280	1.46
11	10	TCL * 384	TCL * 400	1.04
11	11	TCL * 768	TCL * 800	1.04
10	00	TCL * 192	TCL * 480	2.08
10	01	TCL * 384	TCL * 560	1.46
10	10	TCL * 768	TCL * 800	1.04
10	11	TCL * 1536	TCL * 1600	1.04

In the default configuration the sample time of the ST10F272 is 2.5 times longer compared to that of the ST10F269. This has an impact on the frequency of the input signal that can be applied to the ST10F272.

1.4.2 Hardware impact: electrical characteristics

[Table 6](#) lists the differences in the DC characteristics of the two devices.

Table 6. ADC differences

Symbol	Parameter	Limit values for ST10F269		Limit values for ST10F272		Unit
		Min	Max	Min	Max	
V _{AREF}	Analog reference voltage	4.0	V _{DD} + 0.1	4.5	V _{DD}	V
V _{AIN}	Analog input voltage	V _{AGND}	V _{AREF}	V _{AGND}	V _{AREF}	V
C _{AIN}	ADC input capacitance (Port 5)				C _{P1} + C _{P2} + C _S	pF
	Not sampling	-	10	-	7	
	Sampling	-	15	-	10.5	
t _S	Sample time	48TCL	1536TCL	1μs 120TCL	1600TCL	
t _C	Conversion time	388TCL	2884TCL	388TCL	2884TCL	
TUE	Total Unadjusted Error (Port5)	-2.0	+2.0	-2.0	+2.0	LSB
R _{ASRC}	Internal resistance of analog source		t _S [ns] / 150 - 0.25			kΩ

Table 6. ADC differences (continued)

Symbol	Parameter	Limit values for ST10F269		Limit values for ST10F272		Unit
		Min	Max	Min	Max	
I _{AREF}	Reference supply current					
	Running mode	-	500	-	5000	μA
	Power-down mode	-	1	-	1	μA
DNL	Differential nonlinearity	-0.5	+0.5	-1	+1	LSB
INL	Integral nonlinearity	-1.5	+1.5	-1.5	+1.5	LSB
OFS	Offset error	-1.0	+1.0	-1.5	+1.5	LSB

Note: The V_{AREF} pin is also used as a supply pin for the ADC module. As there is a higher current sink on this pin on the ST10F272 compared to the ST10F269, it is recommended not to connect a resistor (for example, because of an RC filter), to prevent creating an offset in the reference.

1.4.3 Software impact

Self-calibration and ADC initialization routine

An automatic self-calibration adjusts the ADC module to process parameter variations at each reset event. After reset, the busy flag (read-only) ADBSY is set because the self-calibration is ongoing. The duration of self-calibration depends on the CPU clock: It may take up to 40.629 ± 1 clock pulses. The user must poll this bit to know when self-calibration is complete in order to initialize the ADC module.

This self-calibration is seen by the ST10F272 as a conversion and thus bit ADCIR is set. The software should perform a dummy read of the ADDAT register and clear the ADCIR and ADCEIR flags before configuring the ADC module and starting the first conversion.

New bit ADOFF, bit 6 of ADCON register

ADCON (FFA0h / A0h)											SFR				Reset value: 0000h	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
ADCTC		ADSTC		ADCRQ	ADCIN	ADWR	ADBSY	ADST	ADOFF	ADM		ADCH				
R/W		R/W		R/W	R/W	R/W	RO	R/W	R/W	R/W		R/W				

Table 7. ADCON register description

Bit	Function	Comment
ADOFF	ADC Disable 0: Analog circuitry of A/D converter is on 1: Analog circuitry of A/D converter is turned off	New bit valid only for the ST10F272. Reserved on ST10F269.

The bit 6 of the ADCON register, reserved in previous ST10 devices, is now used to enable and disable the ADC. By default this bit is cleared and the ST10F272 is compatible with the ST10F269. Therefore, there is no impact on the software, provided that this bit is not written to.

Additional channels on Port1 - only for the ST10F272E

A new multiplexer selects one out of up to 16 + 8 analog input channels (alternate functions of Port 5 and Port1). The selection of Port1 or Port5 as the input of the ADC is made via bit ADCMUX, bit 0 of the XMISC register. By default the multiplexer selects Port5, so there is no impact on the software as compared to an ST10F269 implementation. Note that XMISCEN, bit 10 of the XPERCON register, must be set to have access to the XMISC register.



Table 8. XMISC register description

Bit	Function
ADCMUX	ADC Multiplexer 0: Default configuration, analog inputs on port P5.y can be converted 1: Analog inputs on port P1.z can be converted, only 8 channels can be managed

Note: In the ST10F272B, the location of the ADCMUX bit is reserved and should not be written to, or only to value '0'.

1.5 Real time clock

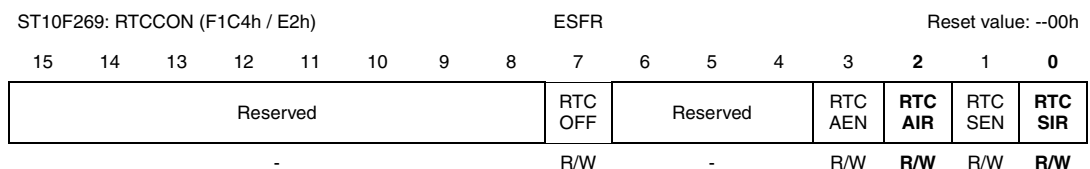
The RTC module can be clocked by two different sources: the main oscillator (pins XTAL1 and XTAL2) or the 32 kHz oscillator (pins XTAL3 and XTAL4). The selection of the clocking can be made via an additional bit in the RTCCON register.

1.5.1 Hardware impact

Check the usage of pins XTAL3 and XTAL4 (pins 143 and 144, respectively).

1.5.2 Software impact

The address range of the RTC registers has been modified from 00'EC00h - 00'ECFFh on the ST10F269, to 00'ED00h - 00'EDFFh on the ST10F272. This relocation has no impact if the software uses register names defined by the toolchain and if the CPU selection is changed to ST10F272. If the software was directly using the address of the RTC register, it must be modified according to the new mapping.



ST10F272: RTCCON (F1C4h / E2h) ESFR Reset value: 0000h

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Reserved						OFF 32	OSC	RTC OFF	Reserved			RTC AEN	RTC AIR	RTC SEN	RTC SIR
	-						R/W	RO	R/W	-			R/W	R/W	R/W	R/W

Table 9. RTCCON register description

Bit	Function	Reset value
RTCSIR	RTC Second Interrupt Request flag (every basic clock unit) 0: The bit was reset less than a Basic Clock unit ago. 1: The interrupt was triggered.	0
RTCSEN	RTC Second Interrupt Enable 0: RTC_SecIT is disabled. 1: RTC_SecIT is enabled; it is generated every basic clock unit.	0
RTCAIR	RTC Alarm Interrupt Request flag (when the alarm is triggered) 0: The bit was reset less than n Basic Clock units ago. 1: The interrupt was triggered.	0
RTCAEN	RTC Alarm Interrupt Enable 0: RTC_alarmIT is disabled. 1: RTC_alarmIT is enabled.	0
RTCOFF	RTC Switch Off bit 0: Clock oscillator and RTC keep on running even if ST10 is in Power Down mode. 1: Clock oscillator is switched off when ST10 enters Power Down mode. Additionally, when setting this bit, RTC dividers and counters are stopped and registers can be written.	0
OSC	Oscillator Selection Flag 0: The clock oscillator used by the RTC is the main oscillator. 1: The clock oscillator used by the RTC is the low power 32 kHz oscillator.	0
OFF32	32 kHz Oscillator Switch Off bit 0: The 32 kHz oscillator is enabled. The RTC is clocked with 32 kHz if there is a valid signal. 1: The 32 kHz oscillator is disabled. The RTC is clocked by the main oscillator.	0

The handling of the RTCAIR and RTCSIR flags (bits 2 and 0 of the RTCCON register, respectively) has also changed:

- In the ST10F272, these flags are cleared by writing them to '1'
- In the ST10F269, these flags are cleared by writing them to '0'

As these flags must be cleared by software when entering the corresponding interrupt service routine, a change in the application code is needed.

Example for RTCSIR flag

Replace ST10F269 code:

```
RTCCON &= 0xFFFE; // Clear RTCSIR flag
```

by the following code for ST10F272:

```
RTCCON |= 0x0001; // Write 1 into RTCSIR flag to clear it
```

1.6 CAN modules

The ST10F269 has two CAN modules of the B-CAN type.

The ST10F272 has two CAN modules of the C-CAN type. These modules are functionally compatible with the modules of the ST10F269.

The C-CAN cells provide additional Message Objects and new functionalities. The main difference is that the Message Objects are no longer directly accessed as memory but are available through a Message Interface. This changes the programming model of the modules.

1.6.1 Hardware impact

None.

1.6.2 Software impact

Rewrite the CAN drivers.

1.7 Port input control

In the ST10F269, the Port Input Control register PICON is used to select between TTL and CMOS-like input thresholds. The CMOS-like input thresholds are defined above the TTL levels and feature a hysteresis of 250mV to prevent the inputs from toggling while the respective input signal level is near the thresholds. This feature is available for all pins of Port 2, Port 3, Port4, Port 7 and Port 8.

In the ST10F272, Port 6 has been added. Moreover, the default hysteresis is now 500mV for TTL levels and 800mV for CMOS levels.

ST10F269: PICON (F1C4h / E2h)								ESFR				Reset value: --00h			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved								P8 LIN	P7 LIN	Res.	P4 LIN	P3 HIN	P3 LIN	P2 HIN	P2 LIN
-								R/W	R/W	-	R/W	R/W	R/W	R/W	R/W

ST10F272: PICON (F1C4h / E2h)								ESFR				Reset value: 0000h			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved								P8 LIN	P7 LIN	P6 LIN	P4 LIN	P3 HIN	P3 LIN	P2 HIN	P2 LIN
-								R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

Table 10. PICON register description

Bit	Function	Reset value
PxLIN	Port x Low Byte Input Level Selection 0: Pins Px.7..0 switch on standard TTL input levels 1: Pins Px.7..0 switch on CMOS input levels	0
PxHIN	Port x High Byte Input Level Selection 0: Pins Px.15..8 switch on standard TTL input levels 1: Pins Px.15..8 switch on CMOS input levels	0

1.7.1 Hardware impact

None.

1.7.2 Software impact

None if the software is not writing to PICON bit 5 (P6LIN).

1.8 Ports output control

In the ST10F269, the port output control registers POCOnx are used to select the output driver characteristics of a port. In this way, the output drivers can be adapted to the application's requirements, and eventually, the EMI behavior of the device can be improved. Two characteristics may be selected:

- **Edge characteristic** defines the rise/fall time for the respective outputs, that is, the transition time. Slow edge reduces the peak currents that are sunk/sourced when changing the voltage level of an external capacitive load.
- **Driver characteristic** defines either the general driving capability of the respective drivers, or if the driver strength is reduced after the target output level has been reached or not. Reducing the driver strength increases the output's internal resistance, which attenuates noise that is imported via the output line.

This feature is not available on the ST10F272.

1.8.1 Hardware impact

Some modifications might be needed depending on the usage of this functionality.

1.8.2 Software impact

Parts related to the initialization of the POCOnx registers should be suppressed.

1.9 PLL and main on-chip oscillator

Compared to the ST10F269, several modifications have been introduced:

- PLL multiplication factors have been adapted in order to match the new frequency range.
- On-chip main oscillator input frequency range has been reshaped, reducing it to 4 to 8 MHz: This allows the power consumption to be reduced when the Real Time Clock is

running in Power Down mode and the on-chip main oscillator clock is used as the reference.

- When the PLL is used, the CPU frequency range is 16 to 64 MHz.

Figure 1: ST10F272 clock generation diagram gives a simplified description of the CPU clock generation. Depending on the multiplication factor selected via Port0 at reset, values are set for each stage. The CPU clock is in fact generated mainly from a VCO with the following characteristics:

- input range: 1 to 3.5 MHz, which explains the Prescaler that divides the XTAL frequency
- output range: 64 to 128 MHz that is then divided through Divider1 to generate the CPU clock

Figure 1. ST10F272 clock generation diagram

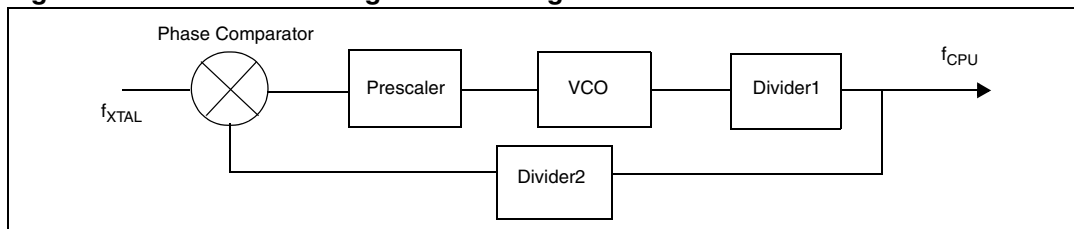


Table 11: ST10F269 vs ST10F272 PLL ratio lists the new PLL multiplication factors and the corresponding frequency ranges for the ST10F272.

Table 11. ST10F269 vs ST10F272 PLL ratio

P0.15-13 (P0H.7-5)	PLL multiplication factor		ST10F272 main oscillator	
	ST10F269	ST10F272	Input range (MHz)	CPU clock range (MHz)
1 1 1	x 4	x 4	4 to 8	16 to 32
1 1 0	x 3	x 3	5.34 to 8	16.02 to 24
1 0 1	x 2	x 8	4 to 8	32 to 64
1 0 0	x 5	x 5	6.4 to 8	32 to 40
0 1 1	x 1	x 1	1 to 64	1 to 64
0 1 0	x 1.5	x 10	4 to 6.4	40 to 64
0 0 1	x 0.5	x 0.5	4 to 8	2 to 4
0 0 0	x 2.5	x 16	4	64

1.9.1 Hardware impact

Port0 configuration might be changed with regards to the new PLL factor.

All configurations need a crystal (or ceramic resonator) to generate the CPU clock through the internal oscillator amplifier, except for the Direct Drive mode (oscillator amplifier disabled, so no crystal or resonator can be used). Vice versa, the clock can be forced through an external clock source only in Direct Drive mode.

The components on XTAL1 and XTAL2 (crystal and capacitors, or resonator) must be changed as:

- the input frequency range is now reduced
- it is no longer possible to use a crystal or a ceramic resonator in direct drive mode
- it is no longer possible to use a PLL factor with a frequency generator
- the electrical characteristics of the main oscillator have changed (transconductance)

1.9.2 Software impact

None.

2 New features

2.1 Additional XPeripherals

Some peripherals have been added to the ST10F272. They are mapped on the XBus and are linked to additional alternate functions of some ports of the ST10F272.

The additional XPeripherals are the following:

- A second SSC (SSC of ST10F269 becomes SSC0, while the new one is referred to as XSSC or simply SSC1). Note that some restrictions and functional differences due to the XBus peculiarities are present between the standard SSC, and the new XSSC.
- A second ASC (ASC0 of ST10F269 remains ASC0, while the new one is referred to as XASC or simply as ASC1). Note that some restrictions and functional differences due to the XBus peculiarities are present between the standard ASC, and the new XASC.
- An I2C interface is added (see X-I2C or simply I2C interface).

In addition to the previous XPeripherals, the ST10F272E also features a second PWM (PWM of ST10F269 becomes PWM0, while the new one is referred to as XPWM or simply as PWM1). Note that some restrictions and functional differences due to the XBus peculiarities are present between the standard PWM, and the new XPWM.

2.1.1 Hardware impact

None if the additional XPeripherals are not used.

2.1.2 Software impact

None if the additional Peripherals are not used. As they are XPeripherals, they can be enabled / disabled via the XPERCON and SYSCON registers. By default, the settings of XPERCON and SYSCON are compatible with the ST10F269.

2.2 Programmable divider on CLKOUT

A specific register mapped on the XBus is used to choose the division factor on the CLKOUT signal (P3.15).

XCLKOUTDIV (E902h)								XBUS								Reset value: --00h	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
Reserved								DIV									
R/W																	

Table 12. XCLKOUTDIV register description

Bit	Function
DIV	$f_{clkout} = f_{CPU} / (DIV + 1)$

2.2.1 Hardware impact

None.

2.2.2 Software impact

None if only CLKOUT is needed.

When the CLKOUT function is enabled by setting the CLKEN bit in the SYSCON register, by default the CPU clock is output on P3.15.

To have access to the XCLKOUTDIV register, and thus to program the clock pre-scaling factor, the XMISCEN bit in the XPERCON register and the XPEN bit in the SYSCON register must be set.

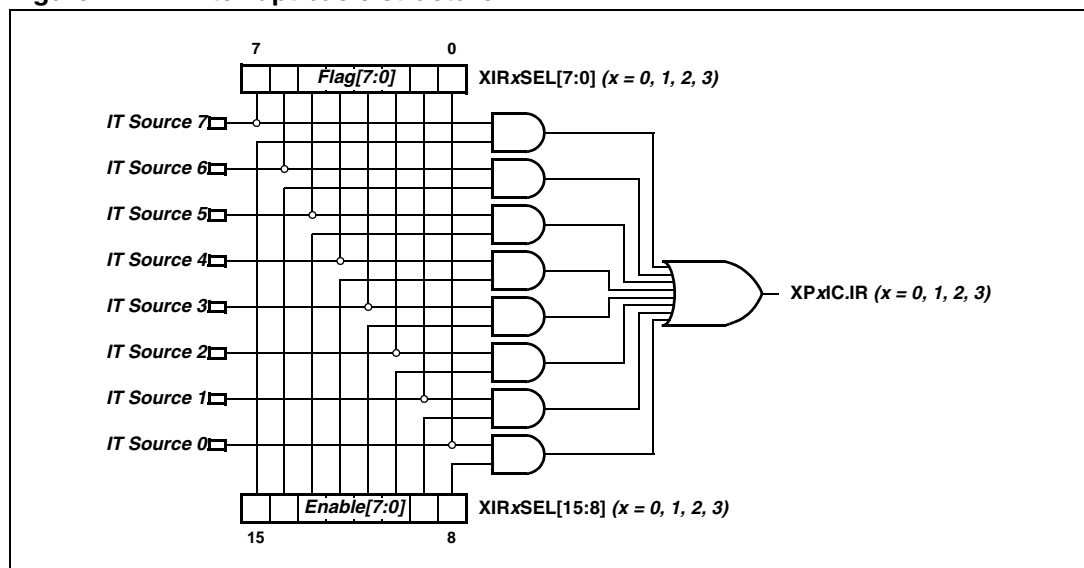
2.3 New multiplexer for X-Interrupts

The limited number of XBus interrupt lines of the present ST10 architecture imposes some constraints on the implementation of the new functionalities. In particular, the additional XPeripherals XSSC, XASC, XI2C and XPWM need some resources to implement interrupt and PEC transfer. For this reason, a complex but very flexible multiplexed structure for the interrupt is proposed. In *Figure 2*, the principle is represented through a simple diagram, which shows the basic structure replicated for each of the four X-interrupt vectors (XP0INT, XP1INT, XP2INT and XP3INT).

It is based on a new 16-bit register XIRxSEL (x = 0,1,2,3), divided into 2 bytes:

- Higher Byte (XIRxSEL[15:8]) Interrupt Enable bits
- Lower Byte (XIRxSEL[7:0]) Interrupt Flag bits

Figure 2. X-Interrupt basic structure



When different sources submit an interrupt request, the enable bits (Byte High of XIRxSEL register) define a mask which controls which sources will be associated with the unique available vector. If more than one source is enabled to issue the request, the service routine has to identify the real event to be serviced. This can easily be done by checking the flag

bits (Byte Low of XIRxSEL register). Note that the flag bit can provide information about events which are not currently serviced by the interrupt controller (since masked through the enable bits), allowing an effective software management also in the absence of the possibility to serve the related interrupt request: a periodic polling of the flag bits may be implemented inside the user application.

Table 13: X-Interrupt detailed mapping gives an overview of the different settings available.

Table 13. X-Interrupt detailed mapping

	XP0INT	XP1INT	XP2INT	XP3INT
CAN1 Interrupt	X			X
CAN2 Interrupt		X		X
I2C Receive	X	X	X	
I2C Transmit	X	X	X	
I2C Error				X
SSC1 Receive	X	X	X	
SSC1 Transmit	X	X	X	
SSC1 Error				X
ASC1 Receive	X	X	X	
ASC1 Transmit	X	X	X	
ASC1 Transmit Buffer	X	X	X	
ASC1 Error				X
PLL Unlock / OWD				X
PWM1 Channel 3...0			X	X

2.3.1 Hardware impact

None.

2.3.2 Software impact

First, the XMISCEN bit, that is, bit 10 of the XPERCON register, must be set to have access to these registers. Refer to [Section 3.1: XPERCON register](#) for more details.

Then, the XIRxSEL registers must be configured. If none of the new XPeripherals is used, that is, only the XPeripherals that were already present on the ST10F269 are used, the following values must be programmed:

- XIR0SEL = 0x0100, only the CAN1 interrupt is enabled and can generate an interrupt to the ST10 through XP0IC
- XIR1SEL = 0x0100, only the CAN2 interrupt is enabled and can generate an interrupt to the ST10 through XP1IC
- XIR2SEL = 0x0, not used
- XIR3SEL = 0x2000, only the PLL unlock interrupt is enabled and can generate an interrupt to the ST10 through XP3IC

Then, in the interrupt routines associated with the XPxIC, the respective flags in the XIRxSEL registers must be cleared. Since the XIRxSEL registers are not bit addressable, a pair of registers (a pair for each XIRxSEL) is provided to set and clear the bits of XIRxSEL without risking to overwrite requests coming after reading the register and before writing it. Therefore, the following registers must be written to clear the flags:

- in the CAN1 interrupt routine, XIR0CLR (@ EB14h) = 0x0001
- in the CAN2 interrupt routine, XIR1CLR (@ EB24h) = 0x0001
- in the PLL unlock interrupt routine, XIR3CLR (@ EB44h) = 0x0020

Additional information on the X-Interrupt multiplexer structure

Figure 2: X-Interrupt basic structure shows that the X-Interrupt sources are connected to the interrupt request flag of the XIRxSEL registers and to the XPxIR request flag via an AND gate with the enable bit. This AND gate is activated by a transition on the Interrupt source line and not by the latched value in the XIRxSEL register. This means that:

- A transition on the IT source line generates an interrupt to the ST10 core if the source is enabled.
- Writing to an interrupt request flag in an XIRxSEL register does not generate an interrupt to the ST10 core.

Example: If XIR0SEL = 0x0100: CAN1 interrupt enabled on XP0IC interrupt

To trigger by software the CAN1 interrupt routine with the XP0IC register, the following code must be used:

```
XIR0SET = 0x0001; /* Set CAN1 interrupt request Flag in XIR0SEL */  
XP0IC = XP0IC | 0x0080; /* Set XP0IR flag, generate an interrupt */
```

Executing only the first line only sets the flag in the XIR0SEL register but it is not seen by the AND gate and cannot set the XP0IR flag.

2.4 Additional ports input control

The possibility to select between TTL and CMOS-like input thresholds has been extended to Ports 0, 1 and 5 via the XPICON register.

ST10F272: XPICON (EB26h)											XREG			Reset value: --00h		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
Reserved											P5 HIN	P5 LIN	P1 HIN	P1 LIN	P0 HIN	P0 LIN
											R/W	R/W	R/W	R/W	R/W	R/W

Table 14. XPICON register description

Bit	Function	Reset value
PxLIN	Port x Low Byte Input Level Selection 0: Pins Px.7..0 switch on standard TTL input levels 1: Pins Px.7..0 switch on CMOS input levels	0
PxHIN	Port x High Byte Input Level Selection 0: Pins Px.15..8 switch on standard TTL input levels 1: Pins Px.15..8 switch on CMOS input levels	0

2.4.1 Hardware impact

None.

2.4.2 Software impact

None.

3 Modified registers

3.1 XPERCON register

In the ST10F272, new bits have been added with regards to the additional XPeripherals.

The XPERCON register allows the XBus peripherals to be separately selected and made visible to the user by means of the corresponding bits. If an XBus peripheral is not selected (not activated with a bit of XPERCON) **before** the XPEN bit in SYSCON is set, the corresponding address space, port pins and interrupts are not occupied by the peripheral, and thus this peripheral is not visible and not available.

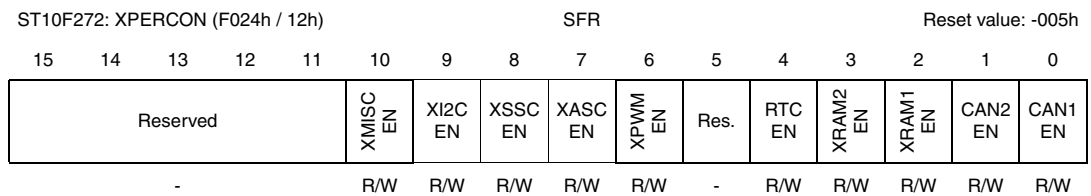


Table 15. XPERCON register description

Bit	Bit name	Function
15:11	-	Reserved
10	XMISCEN	XBUS Additional Features Enable Bit 0: Accesses to the Additional Miscellaneous Features is disabled. 1: The Additional Features are enabled and can be accessed.
9	XI2CEN	XI 2 C Enable Bit 0: Accesses to the on-chip XI 2 C are disabled, external access performed. 1: The on-chip XI 2 C is enabled and can be accessed.
8	XSSCEN	XSSC Enable Bit 0: Accesses to the on-chip XSSC are disabled, external access performed. 1: The on-chip XSSC is enabled and can be accessed.
7	XASCEN	XASC Enable Bit 0: Accesses to the on-chip XASC are disabled, external access performed. 1: The on-chip XASC is enabled and can be accessed.
6	XPWMEN	XPWM Enable 0: Accesses to the on-chip XPWM module are disabled, external access performed. 1: The on-chip XPWM module is enabled and can be accessed.
5	-	Reserved

Table 15. XPERCON register description (continued)

Bit	Bit name	Function
4	RTCEN	RTC Enable Bit 0: Accesses to the on-chip Real Time Clock are disabled, external access performed. 1: The on-chip Real Time Clock is enabled and can be accessed.
3	XRAM2EN	XRAM2 Enable Bit 0: Accesses to the on-chip XRAM2 block are disabled, external access performed. 1: The on-chip XRAM2 is enabled and can be accessed.
2	XRAM1EN	XRAM1 Enable Bit 0: Accesses to the on-chip XRAM1 block are disabled, external access performed. 1: The on-chip XRAM1 is enabled and can be accessed.
1	CAN2EN	CAN2 Enable Bit 0: Accesses to the CAN2 XPeripheral and its functions are disabled (P4.4 and P4.7 pins can be used as general purpose I/Os) 1: The CAN2 XPeripheral is enabled and can be accessed.
0	CAN1EN	CAN1 Enable Bit 0: Accesses to the CAN1 XPeripheral and its functions are disabled (P4.5 and P4.6 pins can be used as general purpose I/Os) 1: The CAN1 XPeripheral is enabled and can be accessed.

Accesses to the XPeripherals are configured through three pairs of specific XBus configuration registers, equivalent to the External Bus register BUSCONx and ADDRSELx. Therefore, several XPeripherals are sharing the same pair, with the consequence that accesses to a disabled XPeripherals are only redirected to external memory if all the other XPeripherals sharing the same pair of registers are disabled.

The XPeripherals are grouped as follows:

- CAN1, CAN2, XASC, XSSC, XI2C, XPWM, XRTC and XMISC: Accesses to the 00'E800h-00'EFFFh range are redirected to external memory only if all corresponding bits are cleared
- XRAM1: Accesses to the 00'E000h-00'E7FFh range are redirected to external memory if bit XRAM1EN is cleared
- XRAM2: Accesses the 09'0000h-0F'FFFFh range (default value in XADRS3 register, refer to [Section 4.1: XADRS3 register](#)) are redirected to external memory if bit XRAM2EN is cleared

3.1.1 Hardware impact

None.

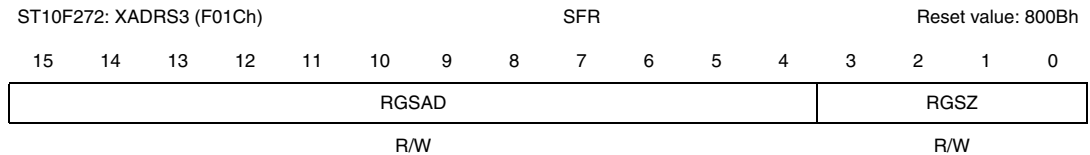
3.1.2 Software impact

None if the ST10F269 software is not writing to the reserved bit.

4 New registers

4.1 XADRS3 register

On previous ST10 devices, this register was already present but its value was mask programmed. On the ST10F272 this register has been made available to the user. In this way the address range of the XRAM2 memory is now user-programmable.



The register functionality is the same as that of ADDRSELx registers used for external address range selection, with some limitations:

- The address window can only be located in the first megabyte of addressable space, that is, in the 00'0000h-0F'FFFFh range
- The window start address must be aligned to a Range Size boundary

Table 16. XADRS3 register description

Bit	Bit name	Function
15:4	RGSAD	Range Start Address Defines the bits A19..A8 of the start address of the address window.
3:0	RGSZ	Range Size Selection Defines the size of the address window.

Table 17. Definition of address area

Bit field RGSZ	Selected window size	Relevant bit (R) of RGSAD	Selected range Start Address Relevant bit (R) of Address (A23 - A0)
0 0 0 0	256 bytes	RRRR RRRR RRRR	0000 RRRR RRRR RRRR xxxx xxxx
0 0 0 1	512 bytes	RRRR RRRR RRRx	0000 RRRR RRRR RRRx xxxx xxxx
...
1 0 1 0	256 Kbytes	RRxx xxxx xxxx	0000 RRxx xxxx xxxx xxxx xxxx
1 0 1 1	512 Kbytes	Rxxx xxxx xxxx	0000 Rxxx xxxx xxxx xxxx xxxx
1 1 x x	Reserved		

4.1.1 Hardware impact

None.

4.1.2 Software impact for the ST10F272B

On ST10F272B, this register must be programmed by the user before accessing XRAM2 so that:

- RGSZ defines an 8 Kbyte window size. RGSZ = 0101b
- RGSAD defines bits 8 to 19 of the window start address aligned to an 8 Kbyte boundary (the least significant bits of the field are not relevant).

By programming XADRS3 to 0C05h, the XRAM2 will be 8 Kbytes, mapped from 00'C000h to 00'DFFFh, exactly as in the ST10F269.

Note: XADRS3 cannot be changed after executing the EINIT instruction.

4.1.3 Software impact for the ST10F272E

On ST10F272E, this register must be programmed by the user before accessing XRAM2 so that:

- RGSZ defines a 16 Kbyte window size. RGSZ = 0110b
- RGSAD defines bits 8 to 19 of the window start address aligned to a 16-Kbyte boundary (the least significant bits of the field are not relevant).

In the ST10F272E, the XRAM2 cannot be located within page 3 of segment 0. The user can either:

- map the XRAM2 from anywhere above address 09'0000h
- map the XRAM2 in the 16-Kbyte page available in segment 0 in the 00'8000h - 00'BFFFh range.

The desired value should be written in XADRS3 register before enabling XRAM2 in the SYSCON and XPERCON registers.

Note: XADRS3 cannot be changed after executing the EINIT instruction.

Example

To map the 16-Kbyte XRAM2 onto page 60 (starting address 0F'0000h, compatible with the ST10F276E), then XADRS3 must be initialized with the value F006h.

To map the 16-Kbyte XRAM2 onto page 2 (starting address 00'8000h), then XADRS3 must be initialized with the value 0806h.

Variables and PEC transfers

For architecture reasons, the PEC destination and source pointers must be in the segment 0. Therefore, all RAM variables and arrays that are PEC-addressed must be located in RAM memory available in segment 0 (DPRAM + XRAM1, and XRAM2 if remapped onto page 2).

About Toolchain memory model

A change in the Toolchain configuration is needed to take into account the XRAM2's new location. In the ST10F269, all the XRAM is in page 3 and it is then automatically addressed using DPP3 that points to page 3 (in order to access the DPRAM and the SFR/ESFR). For the ST10F272, it is necessary to dedicate a DPP to access some of XRAM2.

Example in case of Small memory model with tasking toolchain

The Small memory model makes it possible to have a total code size up to 16 Mbytes, up to 64 Kbytes of fast accessible 'normal user data' in three different memory configurations and the possibility to access far/huge data, if more than 64 Kbytes of data is needed.

The three memory configurations possible for this 64 Kbytes of 'normal user data' are:

- **Default**
The four DPP registers are assumed to contain their system startup value (0-3), providing one linear data area of 64 Kbytes in the first segment (00'0000h - 00'FFFFh).
- **Addresses Linear**
DPP3 contains page number 3, allowing access to SYSTEM (extended) SFR registers and bit-addressable memory. DPP0 - DPP2 provide a linear data area of 48 Kbytes anywhere in memory.
- **Paged**
DPP3 contains page number 3, allowing access to SYSTEM (extended) SFR registers and bit-addressable memory. DPP0, DPP1 and DPP2 contain the page number of a data area of 16 Kbytes anywhere in memory.

Therefore, mapping the XRAM2 onto page 2 (segment 0) makes it available for PEC transfer and the default configuration of the C compiler toolchains can still be used.

4.2 XPEREMU register

This register has been added as a write-only register.

ST10F272: XPEREMU (EB7Eh)										XREG				Reset value: XXXXh	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserved					XMIS CEN	XI2 CEN	XSS CEN	XAS CEN	XPW MEN	Res.	XRT CEN	XRAM2 EN	XRAM1 EN	CAN2 EN	CAN1 EN
-					WO	WO	WO	WO	WO	-	WO	WO	WO	WO	WO

The bit meaning is exactly the same as in the XPERCON register.

4.2.1 Hardware impact

None.

4.2.2 Software impact

Once the XPEN bit of the SYSCON register is set and at least one of the XPeripherals (except for memories) is activated, the XPEREMU register must be written with the same contents as the XPERCON register: This is mandatory in order to allow a correct emulation of the new set of features introduced on XBus for the new ST10 generation. The following instructions must be added inside the initialization routine:

```
if (SYSCON.XPEN && (XPERCON & 0x07D3))
then {XPEREMU = XPERCON}
```

Of course, XPEREMU must be programmed after XPERCON and after SYSCON. In this way, the final configuration for XPeripherals is stored in XPEREMU and used for the emulation hardware setup.

4.3 Emulation-dedicated registers

A set of four additional registers is implemented for emulation purposes only. Similarly to the XPEREMU, they are write-only registers.

- XEMU0 (00'EB76h)
- XEMU1 (00'EB78h)
- XEMU2 (00'EB7Ah)
- XEMU3 (00'EB7Ch)

These registers are used by emulators. They have no user action on the ST10F272.

4.3.1 Hardware impact

None.

4.3.2 Software impact

None. On the ST10F269, the 00'E800h to 00'EBFFh address range was mapped to external memory but is recommended to reserve this space for upward compatibility.

4.4 XMISC register

This register has been created to handle some additional functionalities. To have access to this register, the XMISCEN bit, that is, bit 10 of XPERCON, must be set.

ST10F272: XMISC (EB46h)										XREG				Reset value: 0000h			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
Reserved												VREG OFF	CAN CK2	CAN PAR	ADC MUX		
												R/W	R/W	R/W	R/W		

Table 18. XMISC register description

Bit	Bit name	Function
15:4	-	Reserved
3	VREGOFF	Main Voltage Regulator disable in Power-Down mode 0: Default value after reset and when Power-Down is not used 1: On-chip Main Regulator is turned off when Power-Down mode is entered
2	CANCK2	CAN Clock divider by 2 disable 0: Clock provided to CAN modules is CPU clock divided by 2 (mandatory when f _{CPU} is higher than 40 MHz) 1: Clock provided to CAN modules is directly CPU clock

Table 18. XMISC register description (continued)

Bit	Bit name	Function
1	CANPAR	CAN Parallel Mode Selection 0: CAN2 is mapped on P4.4/P4.7, while CAN1 is mapped on P4.5/P4.6 1: CAN1 and CAN2 are mapped in parallel on P4.5/P4.6. This is effective only if both CAN1 and CAN2 are enabled (bits CAN1EN and CAN2EN set in XPERCON register). If CAN1 is disabled, CAN2 remains on P4.4/P4.7 even if the CANPAR bit is set.
0	ADCMUX	Port1L ADC Channels Enable 0: Analog inputs on port P5.y can be converted (default configuration) 1: Analog inputs on port P1.z can be converted. Only 8 channels can be managed

4.4.1 Hardware impact

None.

4.4.2 Software impact

None.

5 Electrical characteristics

Note: In the tables where the device provides signals with their respective timing characteristics, the symbol **CC** (Controller Characteristics) is included in the Symbol column.

In the tables where the external system must provide signals with their respective timing characteristics to the device, the symbol **SR** (System Requirement) is included in the Symbol column.

5.1 DC characteristics

5.1.1 Absolute maximum ratings

They are the same.

5.1.2 Overview of the DC characteristics

The pads of the ST10F272 have been redesigned according to the new technology and therefore the characteristics are different. The user should verify the DC characteristics.

[Table 19](#) lists the parameters that might be impacted most.

Table 19. DC characteristics

Symbol	Parameter	ST10F269 Limit values		ST10F272 Limit values		Unit
		Min	Max	Min	Max	
V_{IL} SR	Input low voltage (all inputs)	-0.5	$0.2 V_{DD} - 0.1$	-0.3	0.8	V
V_{ILS} SR		-0.5	2.0, special threshold	-0.3	$0.3 V_{DD}$, special threshold	
V_{IL1} SR	Input low voltage (\overline{RSTIN} , \overline{EA} , \overline{NMI} , and \overline{RPD})	N.A.	N.A.	-0.3	$0.3 V_{DD}$	V
V_{IL2} SR	Input low voltage (XTAL1 and XTAL3)			-0.3	$0.3 V_{DD}$	V
V_{IH} SR	Input high voltage (all except \overline{RPD} , XTAL1 and XTAL3)	$0.2 V_{DD} + 0.9$	$V_{DD} + 0.5$	2.0	$V_{DD} + 0.3$	V
V_{IHS} SR		$0.8 V_{DD} - 0.2$	$V_{DD} + 0.5$, special threshold	$0.7 V_{DD}$	$V_{DD} + 0.3$, special threshold	
HY CC	Input Hysteresis	N.A. 400, special threshold	-	400, default 750, special threshold	700 1400	mV
V_{HYS1} CC	Input Hysteresis \overline{RSTIN} , \overline{EA} , \overline{NMI}			750	1400	mV

Table 19. DC characteristics (continued)

Symbol	Parameter	ST10F269 Limit values		ST10F272 Limit values		Unit
		Min	Max	Min	Max	
V_{OLCC}	Output low voltage	– Port0, Port1, Port4, ALE, \overline{RD} , \overline{WR} , \overline{BHE} , CLKOUT, \overline{RSTOUT}	0.45 / $I_{OL} =$ 2.4mA	– Port6, ALE, CLKOUT, \overline{WR} , READY, \overline{BHE} , \overline{RD} , \overline{RSTOUT} , RSTIN	0.4 / $I_{OL} = 8mA$ 0.05 / $I_{OL} = 1mA$	V
V_{OL1CC}	Output low voltage (all other)	–	0.45 / $I_{OL} =$ 2.4mA	–	0.4 / $I_{OL} = 4mA$ 0.05 / $I_{OL} = 0.5mA$	V
V_{OHCC}	Output high voltage	0.9 V_{DD} / $I_{OH} =$ -0.5mA 2.4 / $I_{OH} = -2.4mA$	– Port0, Port1, Port4, \overline{RD} , ALE, \overline{BHE} , \overline{WR} , CLKOUT, \overline{RSTOUT}	$V_{DD} - 0.8$ / $I_{OH} =$ -8mA $V_{DD} - 0.08$ / $I_{OH} =$ -1mA	– Port6, ALE, CLKOUT, \overline{WR} , READY, \overline{BHE} , \overline{RD} , \overline{RSTOUT} , RSTIN	V
V_{OH1CC}	Output high voltage (all other)	0.9 V_{DD} / $I_{OH} =$ -0.25mA 2.4 / $I_{OH} = -1.6mA$	–	$V_{DD} - 0.8$ / $I_{OH} =$ -4mA $V_{DD} - 0.08$ / $I_{OH} =$ -0.5mA	–	V
I_{OZ1CC}	Input leakage current (Port 5)	–	±0.5	–	±0.2	µA
I_{OZ2CC}	Input leakage current (all other inputs)	–	±1	–	±0.5	µA

5.2 AC characteristics at 40 MHz

As the two devices have a different technology, the I/Os also present some differences in the AC behavior. The tables below ([Table 20](#) and [Table 21](#)) list all the timing differences. Please check carefully your design for possible impact.

5.2.1 External memory bus timings

Note that for CPU clock frequencies above 40 MHz, some numbers in the timing formulas become zero or negative, that in most of the cases is not acceptable or not meaningful at all. In these cases, it is necessary to reduce the speed of the bus setting properly t_A (ALE extension), t_C (Memory Cycle Time wait-states) and t_F (Memory tri-state time).

Multiplexed bus

Table 20. Multiplexed bus timings (ns)

Symbol	Parameter	ST10F269		ST10F272		ST10F269 @f _{CPU} = 40 MHz		ST10F272 @f _{CPU} = 40 MHz	
		Min	Max	Min	Max	Min	Max	Min	Max
t ₆ CC	Address setup to ALE	TCL - 10.5 + t _A	-	TCL - 11 + t _A	-	2 + t _A	-	1.5 + t _A	-
t ₁₆ SR	ALE low to valid data in	-	3 TCL - 19 + t _A + t _C	-	3 TCL - 20 + t _A + t _C	18.5 + t _A + t _C	-	17.5 + t _A + t _C	-
t ₁₇ SR	Address/Unlatched \overline{CS} to valid data in	-	4 TCL - 28 + 2t _A + t _C	-	4 TCL - 30 + 2t _A + t _C	22 + 2t _A + t _C	-	20 + 2t _A + t _C	-
t ₃₉ SR	Latched \overline{CS} low to valid data in	-	3 TCL - 19 + 2t _A + t _C	-	3 TCL - 21 + 2t _A + t _C	18.5 + 2t _A + t _C	-	16.5 + 2t _A + t _C	-
t ₄₄ CC	Address float after RdCS, WrCS (with RW delay)	-	0	-	1.5	-	0	-	1.5
t ₄₅ CC	Address float after RdCS, WrCS (no RW delay)	-	TCL	-	TCL + 1.5	-	12.5	-	14

Demultiplexed bus

Table 21. Demultiplexed bus timings

Symbol	Parameter	ST10F269		ST10F272		ST10F269 @f _{CPU} = 40 MHz		ST10F272 @f _{CPU} = 40 MHz	
		Min	Max	Min	Max	Min	Max	Min	Max
t ₆ CC	Address setup to ALE	TCL - 10.5 + t _A	-	TCL - 11 + t _A	-	2 + t _A	-	1.5 + t _A	-
t ₈₀ CC	Address/Unlatched \overline{CS} setup to RD, \overline{WR} (with RW delay)	-	2 TCL - 8.5 + 2t _A	-	2 TCL - 12.5 + 2t _A	16.5 + 2t _A	-	12.5 + 2t _A	-
t ₈₁ CC	Address/Unlatched \overline{CS} setup to RD, \overline{WR} (no RW delay)	-	TCL - 8.5 + 2t _A	-	TCL - 12 + 2t _A	4 + 2t _A	-	0.5 + 2t _A	-
t ₁₆ SR	ALE low to valid data in	-	3 TCL - 19 + t _A + t _C	-	3 TCL - 20 + t _A + t _C	18.5 + t _A + t _C	-	17.5 + t _A + t _C	-
t ₁₇ SR	Address/Unlatched \overline{CS} to valid data in	-	4 TCL - 28 + 2t _A + t _C	-	4 TCL - 30 + 2t _A + t _C	22 + 2t _A + t _C	-	20 + 2t _A + t _C	-

Table 21. Demultiplexed bus timings (continued)

Symbol	Parameter	ST10F269		ST10F272		ST10F269 @f _{CPU} = 40 MHz		ST10F272 @f _{CPU} = 40 MHz	
		Min	Max	Min	Max	Min	Max	Min	Max
t ₂₈ CC	Address/Unlatched \overline{CS} hold after \overline{RD} , \overline{WR}	0 (no t _F) -5 + t _F (t _F > 0)	-	0 + t _F	-	0 (no t _F) -5 + t _F (t _F > 0)	-	0 + t _F	-
t ₃₉ SR	Latched \overline{CS} low to valid data in	-	3 TCL - 19 + 2t _A + t _C	-	3 TCL - 21 + 2t _A + t _C	18.5 + 2t _A + t _C	-	16.5 + 2t _A + t _C	-
t ₈₂ CC	Address setup to \overline{RdCS} , \overline{WrCS} (with RW delay)	2 TCL - 10.5 + 2t _A	-	2 TCL - 11 + 2t _A	-	14.5 + 2t _A	-	14 + 2t _A	-

5.2.2 Hi-speed synchronous serial interface (SSC)

The maximum baudrate of the SSC in the ST10F272 is 8 Mbaud whereas it is 10 Mbaud in the ST10F269. For CPU frequencies strictly higher than 32 MHz, the minimum value in the SSCBR register (prescaler value) must not be lower than 2.

6 Referenced documents

The following documents were used to write this application note:

- *ST10F269 datasheet, 16-BIT MCU WITH MAC UNIT, 256K BYTE FLASH MEMORY AND 12K BYTE RAM*, revision of March 2003
- *ST10F272B-E Final Data, 16-bit MCU with 256 Kbyte Flash memory and 12/20 Kbyte RAM*, Rev. 1, 20 July 2006

7 Revision history

Table 22. Revision history

Date	Revision	Changes
November 2004	1	First Issue with the 2 devices in the same document Previously 2 separate documents for ST10F272B and ST10F272E (last version December 2003)
24-Jan-2007	2	Converted to new ST template <i>Chapter on page 1</i> : Minor editing changes Changed presentation of registers throughout document <i>Section 1.4.3: Software impact</i> : Changed name of bit 11 from ADCTC to ADCRQ <i>Table 8 on page 15</i> : Added bit name ADC Multiplexer to function field of bit ADCMUX <i>Table 9 on page 16</i> : Changed OSC reset value from "U" to "0" <i>Section 1.7: Port input control</i> : Replaced ST10F276 with ST10F272 in register name <i>Section 1.9: PLL and main on-chip oscillator</i> : Modified <i>Section 5: Electrical characteristics</i> : Added note explaining symbols CC and SR used in tables <i>Section 6: Referenced documents</i> : Modified Updated disclaimer (last page) to include a mention about the use of ST products in automotive applications
24-Sep-2013	3	Updated Disclaimer

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