

ADS7066 Small, 8-Channel, 16-Bit SAR ADC With GPIOs

1 Features

- Small solution size:
 - 1.62-mm × 1.62-mm WCSP
 - Space-saving, capless, 2.5-V internal reference
- 8 channels configurable as any combination of:
 - Up to 8 analog inputs, digital inputs, or digital outputs
- Programmable averaging filters:
 - Programmable sample size for averaging
 - Averaging with internal conversions
 - 20-bit resolution for average output
- Low-leakage multiplexer with channel sequencer:
 - Manual mode
 - On-the-fly mode
 - Auto-sequence mode
- Excellent AC and DC performance:
 - SNR: 86 dB, THD: –100 dB
 - Improved SNR with programmable averaging filters
 - INL: ±1 LSB, 16-bit no missing codes
 - Internal calibration improves offset and drift
 - High sample rate with no latency output:
 - 250 kSPS
- Wide operating range:
 - ADC input range: 0 V to V_{REF} and $2 \times V_{REF}$
 - Analog supply: 3 V to 5.5 V
 - Digital supply: 1.65 V to 5.5 V
 - Temperature range: –40°C to +125°C
- Enhanced-SPI digital interface:
 - High-speed, 60-MHz SPI interface
 - Achieve full throughput with > 4.5-MHz SPI

2 Applications

- [Optical modules](#)
- [Optical line cards](#)
- [Multiparameter patient monitors](#)

3 Description

The ADS7066 is a small, 16-bit, 8-channel, high-precision successive-approximation register (SAR) analog-to-digital converter (ADC). The ADS7066 has an integrated capless reference and a reference buffer that helps reduce the overall solution size by requiring fewer external components. The wafer-level-chip-scale package and fewer external components make this device suitable for space-constrained applications.

The ADS7066 features built-in offset calibration for improved accuracy over wide operating conditions of the system. The programmable averaging filters enable higher resolution measurement. The eight channels of the ADS7066 can be individually configured as analog inputs, digital inputs, or digital outputs that enable smaller system size and simplify circuit design for mixed signal feedback and digital control.

The enhanced-SPI enables the ADS7066 in achieving high throughput at lower clock speeds, thereby simplifying the board layout and lowering system cost. The ADS7066 features a cyclic redundancy check (CRC) for data read and write operations and the power-up configuration.

Device Information⁽¹⁾

PART NAME	PACKAGE	BODY SIZE (NOM)
ADS7066	WCSP (16)	1.62 mm × 1.62 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

ADS7066 Block Diagram

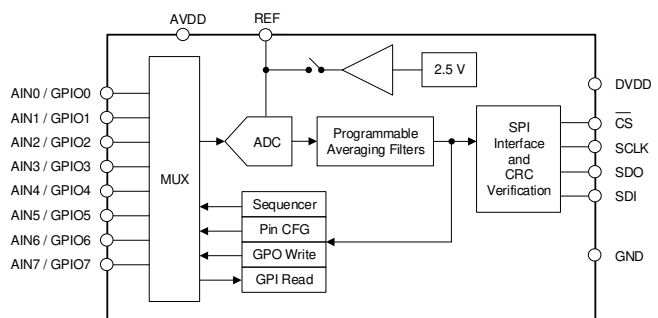


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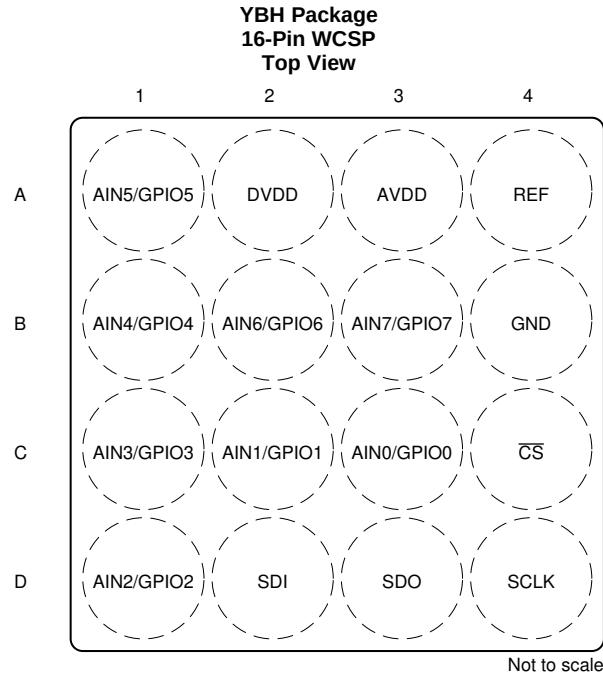
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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES
February 2020	*	Initial release.

5 Pin Configuration and Functions



Pin Functions

PIN		FUNCTION ⁽¹⁾	DESCRIPTION
NO.	NAME		
A1	AIN5/GPIO5	AI, DI, DO	Channel 5; configurable as either an analog input (default) or general-purpose input/output (GPIO).
A2	DVDD	P	Digital I/O supply voltage. Connect a 1-μF capacitor to GND.
A3	AVDD	P	Analog supply voltage. Connect a 1-μF capacitor to GND.
A4	REF	P	Internal reference buffer output; external reference input. Connect a 1-μF capacitor to GND.
B1	AIN4/GPIO4	AI, DI, DO	Channel 4; configurable as either an analog input (default) or GPIO.
B2	AIN6/GPIO6	AI, DI, DO	Channel 6; configurable as either an analog input (default) or GPIO.
B3	AIN7/GPIO7	AI, DI, DO	Channel 7; configurable as either an analog input (default) or GPIO.
B4	GND	P	Ground for power supply, all analog and digital signals are referred to this pin.
C1	AIN3/GPIO3	AI, DI, DO	Channel 3; configurable as either an analog input (default) or GPIO.
C2	AIN1/GPIO1	AI, DI, DO	Channel 1; configurable as either an analog input (default) or GPIO.
C3	AIN0/GPIO0	AI, DI, DO	Channel 0; configurable as either an analog input (default) or GPIO.
C4	$\overline{CS}$	DI	Chip-select input pin; active low. The device takes control of the data bus when $\overline{CS}$ is low. The SDO pin goes to Hi-Z when $\overline{CS}$ is high.
D1	AIN2/GPIO2	AI, DI, DO	Channel 2; configurable as either an analog input (default) or GPIO.
D2	SDI	DI	Serial data input pin for SPI interface.
D3	SDO	DO	Serial data output pin for SPI interface.
D4	SCLK	DI	Clock input pin for the SPI interface.

(1) AI = analog input, DI = digital input, DO = digital output, P = power supply.

6 Specifications

6.1 Absolute Maximum Ratings

over operating ambient temperature range (unless otherwise noted)⁽¹⁾

	MIN	MAX	UNIT
DVDD to GND	−0.3	5.5	V
AVDD to GND	−0.3	5.5	V
AINx/GPIOx ⁽²⁾ to GND	GND − 0.3	AVDD + 0.3	V
REF to GND	GND − 0.3	AVDD + 0.3	V
Digital inputs (CS, SDI, SCLK) to GND	GND − 0.3	5.5	V
Input current to any pin except supply pins ⁽³⁾	−10	10	mA
Junction temperature, T _J	−40	150	°C
Storage temperature, T _{stg}	−60	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Rating* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Condition*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) AINx/GPIOx refers to AIN0/GPIO0, AIN1/GPIO1, AIN2/GPIO2, AIN3/GPIO3, AIN4/GPIO4, AIN5/GPIO5, AIN6/GPIO6, and AIN7/GPIO7 pins.
- (3) Pin current must be limited to 10 mA or less.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±2000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SUPPLY						
AVDD	Analog power supply	AVDD to GND	3	3.3	5.5	V
DVDD	Digital power supply	DVDD to GND	1.65	3.3	5.5	V
REFERENCE VOLTAGE						
V _{REF}	Reference voltage to the ADC	Internal reference	2.5			V
		External reference	2.4	AVDD		
V _{IN}	Absolute input voltage	AINx ⁽¹⁾ to GND	−0.1	AVDD + 0.1		V
ANALOG INPUTS						
FSR	Full-scale input range	RANGE = 0b	0	V _{REF}		V
		RANGE = 1b	0	2 x V _{REF}		
TEMPERATURE RANGE						
T _A	Ambient temperature		−40	25	125	°C

- (1) AINx refers to analog inputs AIN0, AIN1, AIN2, AIN3, AIN4, AIN5, AIN6, and AIN7.

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		ADS7066	UNIT
		YBH (WCSP)	
		16 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	80.2	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	0.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	18.8	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	0.2	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	18.8	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics

at AVDD = 3 V to 5.5 V, DVDD = 1.65 V to 5.5 V, V_{REF} = 2.5 V (internal), and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = -40°C to +125°C; typical values at T_A = 25°C.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
ANALOG INPUTS							
C _{IN}	Input capacitance	ADC and MUX capacitance	30			pF	
DC PERFORMANCE							
	Resolution	No missing codes	16			Bits	
DNL	Differential nonlinearity		−0.75	±0.5	0.75	LSB	
INL	Integral nonlinearity		−4	±1	4	LSB	
V _(OS)	Input offset error ⁽¹⁾		−32	±8	32	LSB	
dV _{OS} /dT	Input offset thermal drift		±1			ppm/°C	
	Offset error match		−1	0.5	1	LSB	
G _E	Gain error ⁽²⁾		−0.05	±0.02	0.05	%FSR	
dG _E /dT	Gain error thermal drift		±1			ppm/°C	
	Gain error match		−0.005	±0.001	0.005	%FSR	
AC PERFORMANCE							
SINAD	Signal-to-noise + distortion ratio	f _{IN} = 2 kHz	84.7	86		dB	
SNR	Signal-to-noise ratio	f _{IN} = 2 kHz	85	86		dB	
SFDR	Spurious-free dynamic range	f _{IN} = 2 kHz	105			dB	
	Isolation crosstalk	f _{IN} = 10 kHz	−110			dB	
REFERENCE							
C _{REF}	Decoupling capacitor at REF pin		1		10	μF	
DIGITAL INPUTS							
V _{IL}	Input low logic level	For $\overline{\text{CS}}$, SCLK and SDI pins	−0.3	0.3 DVDD		V	
		For GPIO _X ⁽³⁾ pins	−0.3	0.3 AVDD			
V _{IH}	Input high logic level	For $\overline{\text{CS}}$, SCLK and SDI pins	0.7 DVDD	DVDD		V	
		For GPIO _X pins	0.7 AVDD	AVDD			
DIGITAL OUTPUTS							
	Output format	Straight binary					
V _{OL}	Output low logic level	For SDO pin, I _{OL} = 500 μA sink	0	0.2 DVDD		V	
		For GPIO _X ⁽³⁾ pins, I _{OL} = 500 μA sink	0	0.2 AVDD			
V _{OH}	Output high logic level	For SDO pin, I _{OH} = 500 μA source	0.8 DVDD	DVDD		V	
		For GPIO _X ⁽³⁾ pins, I _{OH} = 500 μA source	0.8 AVDD	AVDD			
POWER SUPPLY							
I _{AVDD}	Analog supply current	AVDD = 3.3 V, external reference	0.7			1	mA
		AVDD = 3.3 V, internal reference	1.2			1.6	mA
		No conversion, external reference	250				μA
		No conversion, internal reference	800				μA

(1) Post offset calibration.

(2) This specification is measured with respect to voltage at REF pin.

(3) GPIO_X refers to GPIO0, GPIO1, GPIO2, GPIO3, GPIO4, GPIO5, GPIO6, and GPIO7 pins.

6.6 Timing Requirements

at AVDD = 3 V to 5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +125°C; typical values at T_A = 25°C.

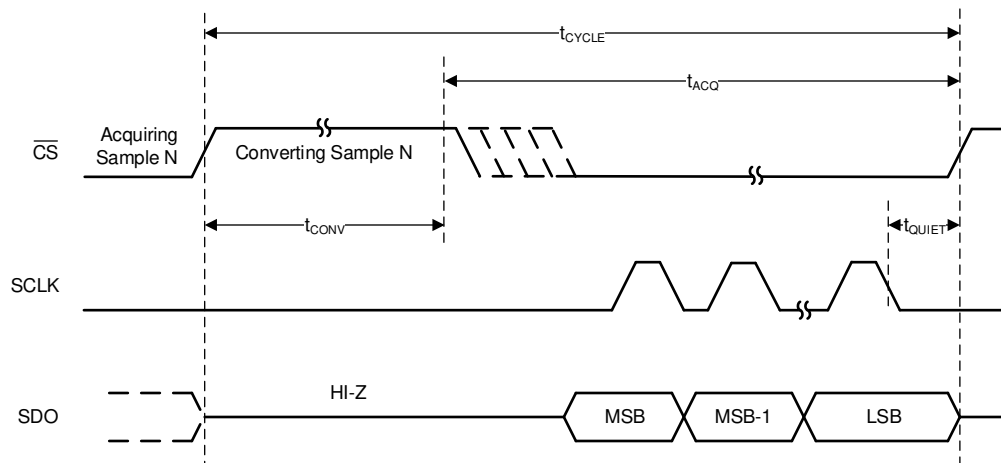
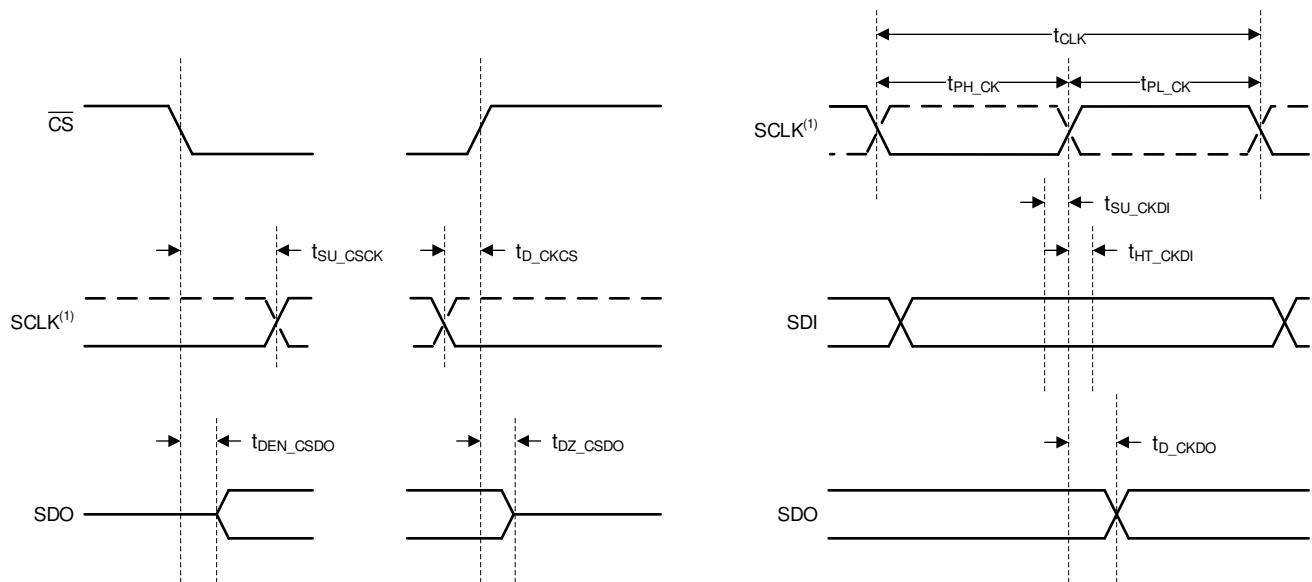
		MIN	MAX	UNIT
CONVERSION CYCLE				
f _{CYCLE}	Sampling frequency		250	kSPS
t _{CYCLE}	ADC cycle-time period	1/f _{CYCLE}		s
t _{QUIET}	Quiet acquisition time	20		ns
t _{WH_CSZ}	Pulse duration: $\overline{CS}$ high	60		ns
t _{WL_CSZ}	Pulse duration: $\overline{CS}$ low	210		ns
SPI INTERFACE TIMINGS				
f _{CLK}	Maximum SCLK frequency		60	MHz
t _{CLK}	Minimum SCLK time period	16.67		ns
t _{PH_CLK}	SCLK high time	0.45	0.55	t _{CLK}
t _{PL_CLK}	SCLK low time	0.45	0.55	t _{CLK}
t _{SU_CSCCK}	Setup time: $\overline{CS}$ falling to the first SCLK capture edge	15		ns
t _{SU_CKDI}	Setup time: SDI data valid to the SCLK capture edge	0.5		ns
t _{HT_CKDI}	Hold time: SCLK capture edge to data valid on SDI	1.6		ns
t _{D_CKCS}	Delay time: last SCLK falling to $\overline{CS}$ rising	0.5		ns

6.7 Switching Characteristics

at AVDD = 3 V to 5.5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +125°C; typical values at T_A = 25°C.

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
CONVERSION CYCLE					
t _{CONV}	ADC conversion time			3200	ns
t _{ACQ}	Acquisition time		800		ns
RESET					
t _{PU}	Power-up time for device	AVDD ≥ 3 V		5	ms
t _{RST}	Delay time; RST bit = 1b to device reset complete ⁽¹⁾			5	ms
SPI INTERFACE TIMINGS					
t _{DEN_CSDO}	Delay time: $\overline{CS}$ falling to data enable			22	ns
t _{DZ_CSDO}	Delay time: $\overline{CS}$ rising to SDO going Hi-Z			50	ns
t _{D_CKDO}	Delay time: SCLK launch edge to (next) data valid on SDO			16	ns

(1) RST bit is automatically reset to 0b after t_{RST}.


Figure 1. Conversion Cycle Timing

Figure 2. SPI Interface Timing

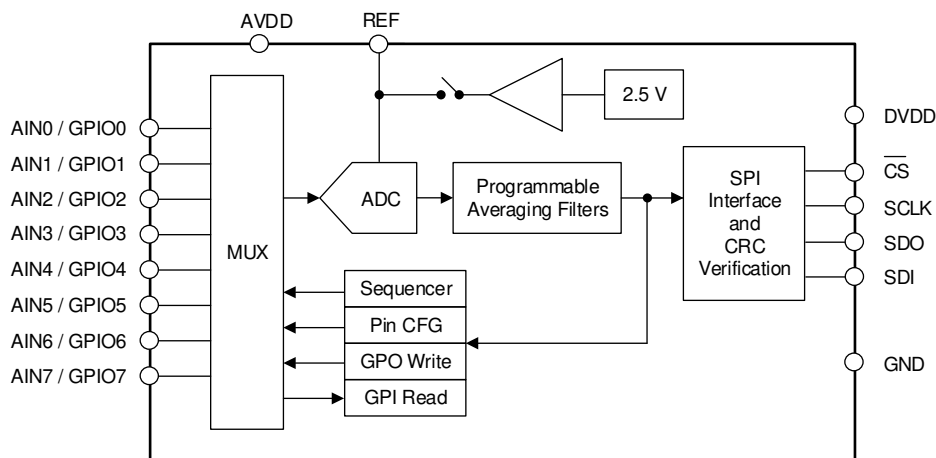
7 Detailed Description

7.1 Overview

The ADS7066 is a 16-bit, successive approximation register (SAR) analog-to-digital converter (ADC) with an analog multiplexer. This device integrates a reference, reference buffer, low-dropout regulator (LDO), and features high performance at full throughput and low-power consumption.

The ADS7066 supports unipolar, single-ended analog input signals. The internal reference generates a low-drift, buffered, 2.5-V reference output. The device uses an internal clock to perform conversions. At the end of the conversion process, the device enters an acquisition phase.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Analog Input and Multiplexer

The eight channels of the multiplexer can be independently configured as ADC inputs or general-purpose inputs/outputs (GPIOs). As shown in Figure 3, each input pin has ESD protection diodes to AVDD and GND. On power-up or after device reset, all eight channels of the multiplexer are configured as analog inputs.

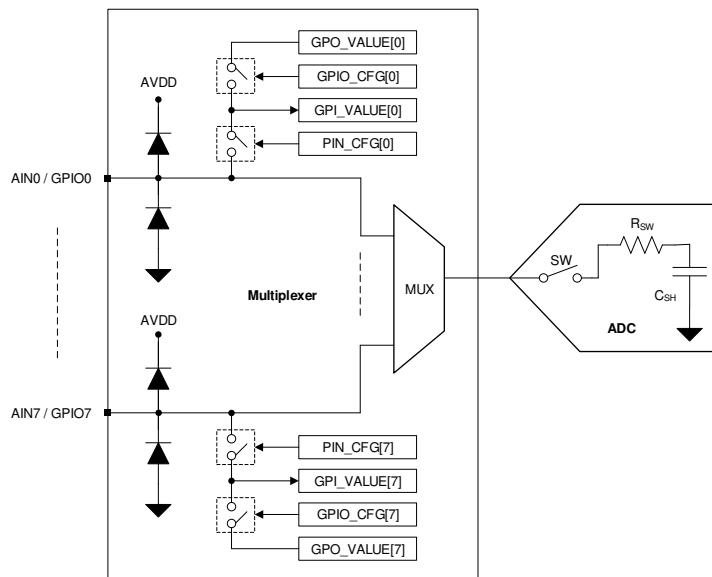


Figure 3. Analog Inputs, GPIOs, and ADC Connections

Feature Description (continued)

Figure 3 illustrates an equivalent circuit for the pins configured as analog inputs. The ADC sampling switch is represented by an ideal switch (SW) in series with a resistor (R_{SW} , typically 150 Ω) and a sampling capacitor (C_{SH} , typically 30 pF). During acquisition, the SW switch is closed to allow the signal on the selected analog input channel to charge the internal sampling capacitor. During conversion, the SW switch is opened to disconnect the analog input channel from the sampling capacitor.

The multiplexer channels can be configured as GPIOs in the PIN_CFG register. On power-up, all channels of the multiplexer are configured as analog inputs. The direction of a GPIO, input or output, can be set in the GPIO_CFG register. The logic level of channels configured as digital inputs can be read from the GPI_VALUE register. The digital outputs can be accessed by writing to the GPO_VALUE register. The digital outputs can be configured as open-drain or push-pull in the GPO_DRIVE_CFG register.

7.3.2 Reference

The ADS7066 has a precision, low-drift voltage reference internal to the device.

7.3.2.1 Internal Reference

The device features an internal reference source with a nominal output value of 2.5 V. On power-up, the internal reference is disabled by default. To enable the internal reference, set EN_REF = 1b in the GENERAL_CFG register. A minimum 0.1- μ F decoupling capacitor is recommended to be placed between the REF and GND pins. The capacitor must be placed as close to the REF pin as possible. The REF pin has ESD protection diodes connected to the AVDD and GND pins.

7.3.2.2 External Reference

An external reference voltage source can be connected to the REF pin with an appropriate decoupling capacitor placed between the REF and GND pins. Best SNR is achieved with a 5-V external reference because the internal reference is limited to 2.5 V. For improved thermal drift performance, a reference from the REF60xx family (REF6025, REF6030, REF6033, REF6041, REF6045, and REF6050) is recommended.

7.3.3 ADC Transfer Function

The ADC output is in straight binary format. The full-scale input range (FSR) of the ADC is determined by the RANGE bit. On power-up, the FSR is 0 V to V_{REF} . When using the $2 \times V_{REF}$ mode (RANGE = 1b), the ADC can measure analog inputs up to two times the voltage reference. Equation 1 can be used to compute the ADC resolution:

$$1 \text{ LSB} = \text{FSR} / 2^N$$

where:

- FSR = Full-scale input range of the ADC
- N = 16

(1)

Feature Description (continued)

Figure 4 and Table 1 show the ideal transfer characteristics for this device.

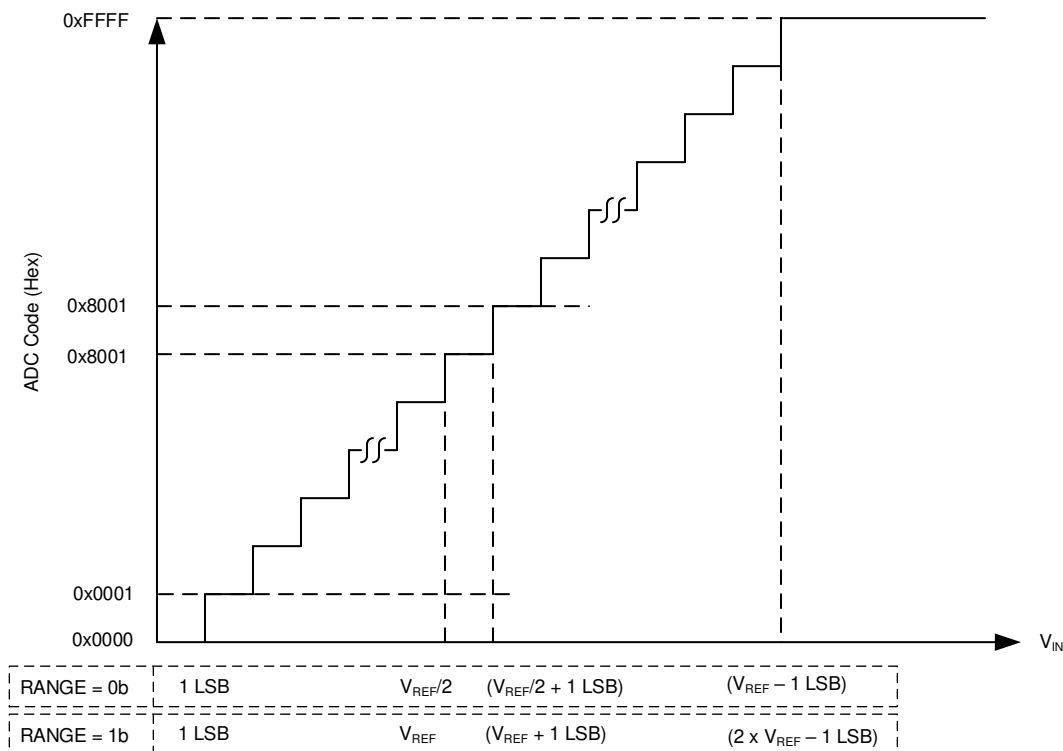


Figure 4. Ideal Transfer Characteristics

Table 1. Transfer Characteristics

INPUT VOLTAGE		CODE	IDEAL OUTPUT CODE
RANGE = 0b	RANGE = 1b		
$\leq 1 \text{ LSB}$	$\leq 1 \text{ LSB}$	Zero	0000
1 LSB to 2 LSBs	1 LSB to 2 LSBs	Zero + 1	0001
$(V_{REF} / 2)$ to $(V_{REF} / 2) + 1 \text{ LSB}$	V_{REF} to $V_{REF} + 1 \text{ LSB}$	Mid-scale code	8000
$(V_{REF} / 2) + 1 \text{ LSB}$ to $(V_{REF} / 2) + 2 \text{ LSBs}$	$V_{REF} + 1 \text{ LSB}$ to $V_{REF} + 2 \text{ LSBs}$	Mid-scale code + 1	8001
$\geq V_{REF} - 1 \text{ LSB}$	$\geq 2 \times V_{REF} - 1 \text{ LSB}$	Full-scale code	FFFF

7.3.4 ADC Offset Calibration

The variation in ADC offset error because of changes in temperature or reference voltage can be calibrated by setting the CAL bit in the GENERAL_CFG register. The CAL bit is reset to 0 after calibration. The host can poll the CAL bit to check the ADC offset calibration completion status.

7.3.5 Programmable Averaging Filters

The ADS7066 features a programmable averaging filter that can be used to average analog input samples to output a higher resolution measurement. The averaging filter can be enabled by programming the OSR[2:0] bits in the OSR_CFG register to the averaging factor desired. The averaging configuration is common to all analog input channels. As shown in Figure 5, the output of the averaging filter is 20 bits long. In manual mode and auto-sequence mode of conversion, only the first conversion for the selected analog input channel must be initiated by the host, as shown in Figure 5; any remaining conversions are generated internally. The time required to complete the averaging operation is determined by the sampling speed and number of samples to be averaged. After completion, the averaged 20-bit result, as shown in Figure 5, can be read-out.

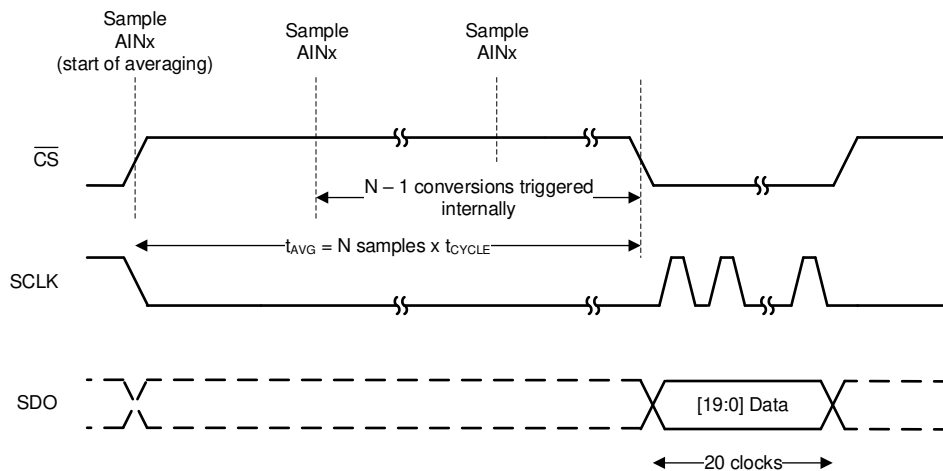


Figure 5. Averaging Example

In autonomous mode of operation, samples from analog input channels that are enabled in the AUTO_SEQ_CH_SEL register are averaged sequentially.

7.3.6 CRC on Data Interface

The cyclic redundancy check (CRC) is an error checking code that detects communication errors to and from the host. CRC is the division remainder of the data payload bytes by a fixed polynomial. The data payload is two or three bytes, depending on the output data format; see the [Output Data Format](#) section for details on output data format. The CRC mode is optional and is enabled by the CRC_EN bit in the GENERAL_CFG register.

The CRC data byte is the 8-bit remainder of the bitwise exclusive-OR (XOR) operation of the argument by a CRC polynomial. The CRC polynomial is based on the CRC-8-ATM (HEC): $X^8 + X^2 + X^1 + 1$. The nine binary polynomial coefficients are: 100000111. The CRC calculation is preset with 1 data values.

The host must compute and append the appropriate CRC to the command string in the same SPI frame (see the [Register Read/Write Operation](#) section). The ADC repeats the CRC calculation and compares the calculation to the received CRC. If the host and repeated ADC CRC values match, the command executes. If the operation is conversion data or register data read, the ADC responds with a second CRC that is computed over the requested data payload bytes. The response data payload is one, two, or three bytes depending on the data operation.

If the host CRC and repeated CRC values do not match, the command does not execute and the error condition can be detected, as listed in [Table 2](#), by either status flags or by a register read.

Table 2. Configuring Notifications when CRC Error is Detected

CRC ERROR NOTIFICATION	CONFIGURATION	DESCRIPTION
Status flags	APPEND_STATUS = 10b	4-bit status flags, containing the CRCERR_IN bit appended to the ADC data; see the Output Data Format section for details.
Register read	—	Read the CRCERR_IN bit to check if a CRC error was detected.

Further register writes are disabled until the CRCERR_IN bit is cleared by writing 1b to this bit. ADC conversion data and register data can continue to be read before clearing the CRCERR_IN bit.

7.3.7 Oscillator and Timing Control

The device uses an internal oscillator for conversion. When using the averaging module, the host initiates the first conversion and subsequent conversions are generated internally by the device. When the device generates the start of a conversion, the sampling rate can be controlled as described in [Table 3](#) by the OSC_SEL and CLK_DIV[3:0] register fields.

Table 3. Configuring the Sampling Rate for Internal Conversion Start Control

CLK_DIV[3:0]	OSC_SEL = 0		OSC_SEL = 1	
	SAMPLING FREQUENCY, f_{CYCLE} (kSPS)	CYCLE TIME, t_{CYCLE} (μs)	SAMPLING FREQUENCY, f_{CYCLE} (kSPS)	CYCLE TIME, t_{CYCLE} (μs)
0000b	Reserved. Do not use.	1	31.25	32
0001b	Reserved. Do not use.	1.5	20.83	48
0010b	Reserved. Do not use.	2	15.63	64
0011b	Reserved. Do not use.	3	10.42	96
0100b	250	4	7.81	128
0101b	166.7	6	5.21	192
0110b	125	8	3.91	256
0111b	83	12	2.60	384
1000b	62.5	16	1.95	512
1001b	41.7	24	1.3	768
1010b	31.3	32	0.98	1024
1011b	20.8	48	0.65	1536
1100b	15.6	64	0.49	2048
1101b	10.4	96	0.33	3072

The conversion time of the device, given by t_{CONV} in the [Switching Characteristics](#) table, is independent of the OSC_SEL and CLK_DIV[3:0] configuration.

7.3.8 Diagnostic Modes

The ADS7066 features a programmable test voltage generation circuit that can be used for ADC diagnostics.

7.3.8.1 Bit-Walk Test Mode

To enable write access to the configuration registers for diagnostics, write 0x96 in the DIAGNOSTICS_KEY register. To enable bit-walk test mode, configure BITWALK_EN = 1b. In the bit-walk test mode (see [Figure 3](#)), the sampling switch (SW) remains open and the test voltage is applied on the sampling capacitor (C_{SH}) during the acquisition phase of the ADC. In diagnostic mode, the conversion process of the ADC remains the same as when not in diagnostic mode. The ADC starts the conversion phase on the rising edge of CS and outputs the code corresponding to the sampled test voltage. The output code of the ADC is expected to be proportional to the test voltage, as shown in [Equation 2](#), after adjusting for DC errors (such as INL, gain error, offset error, and thermal drift of offset and gain errors).

$$\text{Output code} = \left(\frac{\text{Test voltage}}{V_{\text{REF}}} \times 2^{16} \right) \pm \text{TUE}$$

where

- TUE = Total unadjusted error, given by the root sum square of the offset error, gain error, and INL (2)

The test voltage is generated by a DAC configured by the BIT_SAMPLE_MSB and BIT_SAMPLE_LSB registers. Because the test voltage is derived from the ADC reference, as given by [Equation 3](#), this diagnostic mode is not sensitive to variations in reference voltage.

$$\text{Test voltage} = \frac{V_{\text{REF}}}{\text{BIT_SAMPLE}[15:0]} \pm \text{TUE} \quad (3)$$

To resume conversion of the ADC input signal, configure BITWALK_EN = 0b.

7.3.8.2 Fixed Voltage Test Mode

For diagnostics, the ADS7066 features a fixed 1.8 V (typical) test voltage which can be internally connected to AIN6. To connect AIN6 to the internal test voltage, set VTEST_EN = 1b. When using the fixed voltage test mode, AIN6 pin must be left floating and should not be connected to any external circuit.

If bit-walk test mode is enabled (that is, BITWALK_EN = 1b), enabling the fixed voltage test mode will connect AIN6 to the test voltage but the conversion result would be according to bit-walk test mode configuration.

7.3.9 Output Data Format

[Figure 6](#) illustrates that the output data payload consists of a combination of the conversion result, data bits from averaging filters, status flags, and channel ID. The conversion result is MSB aligned. If averaging is enabled, the output data from the ADC are 20 bits long, otherwise the data are 16 bits long. Optionally, the 4-bit channel ID or status flags can be appended at the end of the output data by configuring the APPEND_STATUS[1:0] fields.

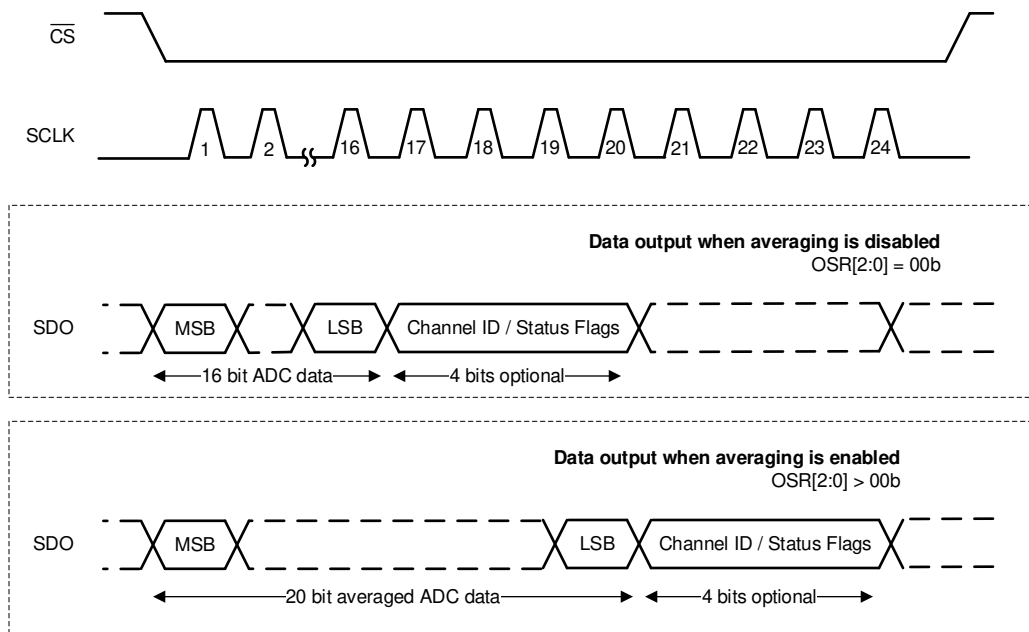


Figure 6. SPI Frames for Reading Data

7.3.9.1 Status Flags

Status flags can be appended to the ADC output by setting `APPEND_STATUS = 10b`. The status flag is appended only to frames where ADC data are being read. Status flags are not appended to register read data or when `FIX_PAT = 1b`. The 4-bit status flag field is constructed as follows:

Status flag[3:0] = { 1, `VTEST_MODE`, `CRCERR_IN`, `DIAG_MODE` }

where:

- `VTEST_MODE`: This flag is set if the current data frame corresponds to fixed voltage test mode (see the [Fixed Voltage Test Mode](#) section).
- `CRCERR_IN`: This flag indicates the status of the CRC verification of data received from the digital interface. This flag is the same as the `CRCERR_IN` bit in the `SYSTEM_STATUS` register.
- `DIAG_MODE`: This flag is set if the current data frame corresponds to the bit-walk test mode (see the [Bit-Walk Test Mode](#) section).

7.3.9.2 Output CRC (Device to Host)

A CRC byte can be appended to the output data by configuring `CRC_EN` to 1b. When the CRC module is enabled, the host must use 32-bit frames for SPI communication. The device outputs the data payload followed by the CRC byte computed over the data payload. Additional 0s can be appended by the ADC after the CRC byte to complete the 32-bit SPI frame (see [Table 4](#)). The host must compute the CRC corresponding to the data payload and match the computed CRC with the CRC received from the device. The additional 0s appended by the device after the CRC byte must be excluded by the host for computing the CRC.

7.3.9.3 Input CRC (Host to Device)

When the CRC module is enabled, the host must always communicate with the ADC using 32-bit SPI frames comprised of a 24-bit data payload and an 8-bit CRC byte. The host must calculate the CRC byte to be appended based on a 24-bit payload. The ADC computes a CRC over the 24-bit data payload and matches the computed CRC with the CRC received from the host.

The ADS7066 supports daisy-chain mode; see the [Daisy-Chain Mode](#) section for more details. The serial input data (SDI) are shifted on the serial data output (SDO) after 24 SCLKs. If the output data payload is less than 24 bits long, additional 0s are output until the 24th SCLK. Daisy-chain mode is not supported when the CRC module is enabled.

Table 4. Output Data Frames

CRC_EN	OSR[2:0]	APPEND_STATUS[1:0]	OUTPUT DATA FRAME	DAISY-CHAIN MODE
CRC module disabled (CRC_EN = 0)	No averaging	No flags (00b or 11b)	{Conversion result [15:0], 8'b0}	Supported
		Channel ID (01b)	{Conversion result [15:0], CHID[3:0], 4'b0}	Supported
		Status flags (10b)	{Conversion result [15:0], status flags[3:0], 4'b0}	Supported
	Averaging enabled	No flags (00b or 11b)	{Conversion result [19:0], 4'b0}	Supported
		Channel ID (01b)	{Conversion result [19:0], CHID[3:0]}	Supported
		Status flags (10b)	{Conversion result [19:0], status flags[3:0]}	Supported
CRC module enabled (CRC_EN = 1)	No averaging	No flags (00b or 11b)	{Conversion result [15:0], CRC[7:0], 8'b0}	Supported
		Channel ID (01b)	{Conversion result [15:0], CHID[3:0], 4'b0, CRC[7:0]}	Not supported
		Status flags (10b)	{Conversion result [15:0], status flags[3:0], 4'b0, CRC[7:0]}	Not supported
	Averaging enabled	No flags (00b or 11b)	{Conversion result [19:0], 4'b0, CRC[7:0]}	Not supported
		Channel ID (01b)	{Conversion result [19:0], CHID[3:0], CRC[7:0]}	Not supported
		Status flags (10b)	{Conversion result [19:0], status flags[3:0], CRC[7:0]}	Not supported

7.3.10 Device Programming

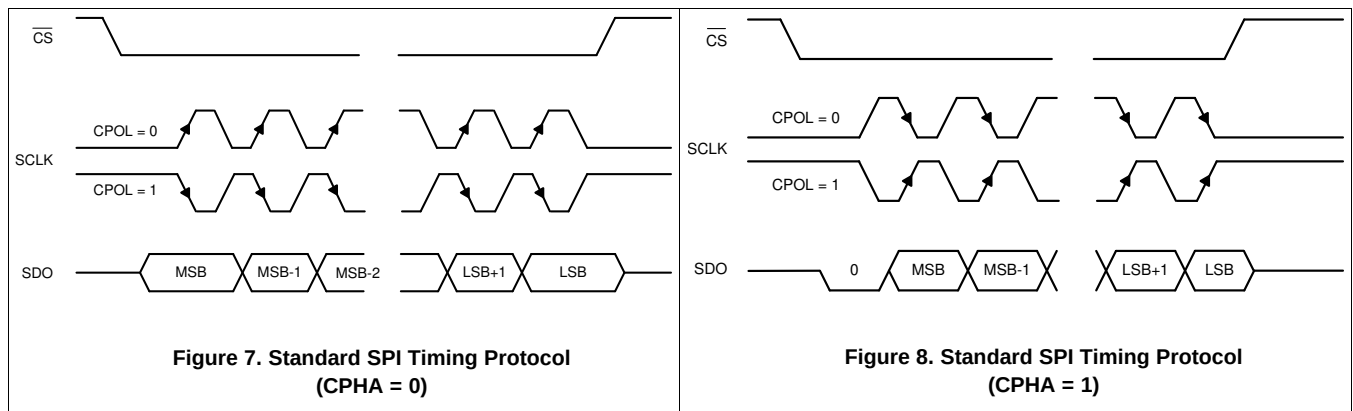
7.3.10.1 Enhanced-SPI Interface

The device features an enhanced-SPI interface that allows the host controller to operate at slower SCLK speeds and still achieve full throughput. As described in [Table 5](#), the host controller can use any of the four SPI-compatible protocols (SPI-00, SPI-01, SPI-10, or SPI-11) to access the device.

Table 5. SPI Protocols for Configuring the Device

PROTOCOL	SCLK POLARITY (At the CS Falling Edge)	SCLK PHASE (Capture Edge)	CPOL_CPHA[1:0]	DIAGRAM
SPI-00	Low	Rising	00b	Figure 7
SPI-01	Low	Falling	01b	Figure 8
SPI-10	High	Falling	10b	Figure 7
SPI-11	High	Rising	11b	Figure 8

On power-up, the device defaults to the SPI-00 protocol for data read and data write operations. To select a different SPI-compatible protocol, program the CPOL_CPHA[1:0] field. This first write operation must adhere to the SPI-00 protocol. Any subsequent data transfer frames must adhere to the newly-selected protocol.



7.3.10.2 Daisy-Chain Mode

The ADS7066 can operate as a single converter or in a system with multiple converters. System designers can take advantage of the simple, high-speed, enhanced-SPI serial interface by cascading converters in a daisy-chain configuration when multiple converters are used. No register configuration is required to enable daisy-chain mode. Figure 9 shows a typical connection of three converters in daisy-chain mode.

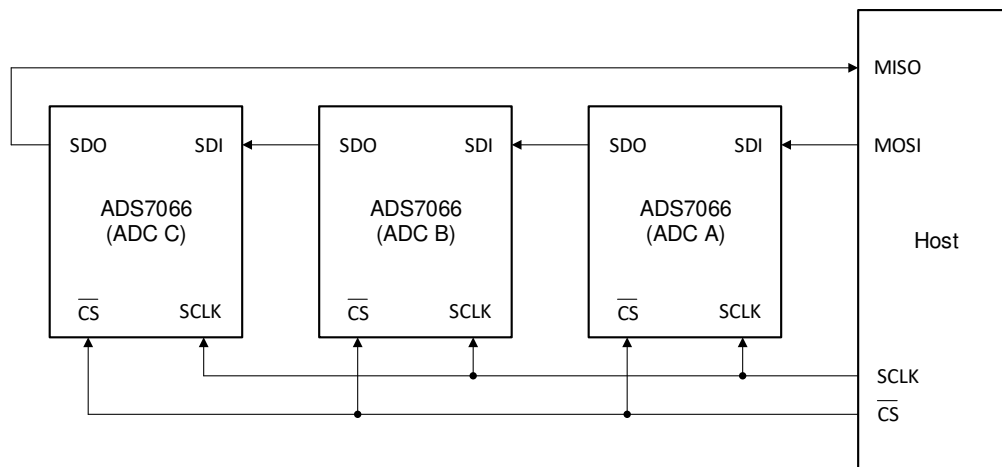


Figure 9. Multiple Converters Connected Using Daisy-Chain Mode

When the ADS7066 is connected in daisy-chain mode, the serial input data passes through the ADS7066 with a 24-SCLK delay, as long as $\overline{CS}$ is active. Figure 10 shows a detailed timing diagram of this mode. In Figure 10, the conversion in each converter is performed simultaneously.

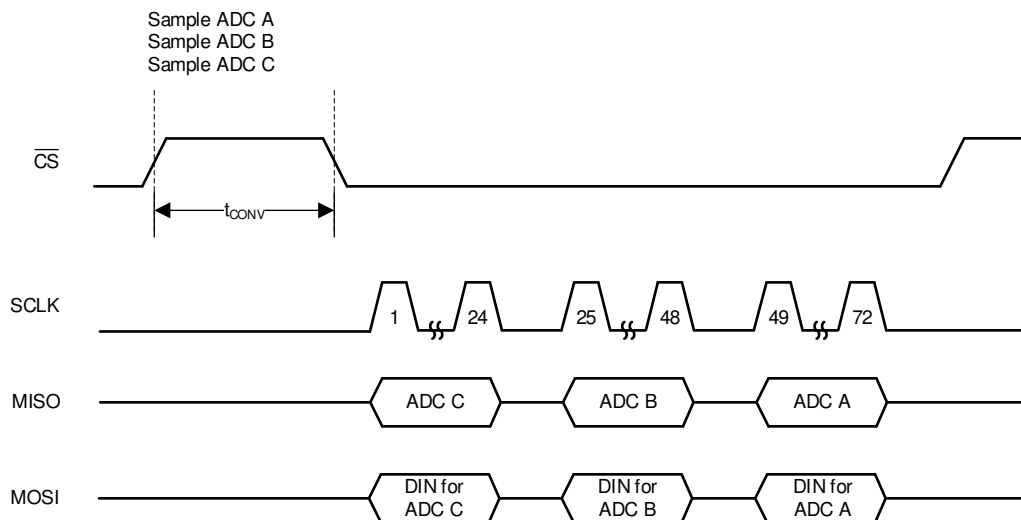


Figure 10. Simplified Daisy-Chain Mode Timing

The ADS7066 supports daisy-chain mode for output data payloads up to 24 bits long; see the [Output Data Format](#) section for more details. If either the status flags or channel ID are appended (APPEND_STATUS $\neq$ 00b) and the CRC module is enabled (CRC_EN = 1b), then the serial input data does not pass through the ADS7066 and daisy-chain mode is disabled.

7.3.10.3 Register Read/Write Operation

The device supports the commands listed in [Table 6](#) to access the internal configuration registers

Table 6. Opcodes for Commands

OPCODE	COMMAND DESCRIPTION
0000 0000b	No operation
0001 0000b	Single register read
0000 1000b	Single register write
0001 1000b	Set bit
0010 0000b	Clear bit

7.3.10.3.1 Register Write

A 24-bit SPI frame is required to write data to configuration registers. The 24-bit data on SDI, as shown in [Figure 11](#), consists of an 8-bit write command (0000 1000b), an 8-bit register address, and 8-bit data. The write command is decoded on the CS rising edge and the specified register is updated with the 8-bit data specified in the register write operation.

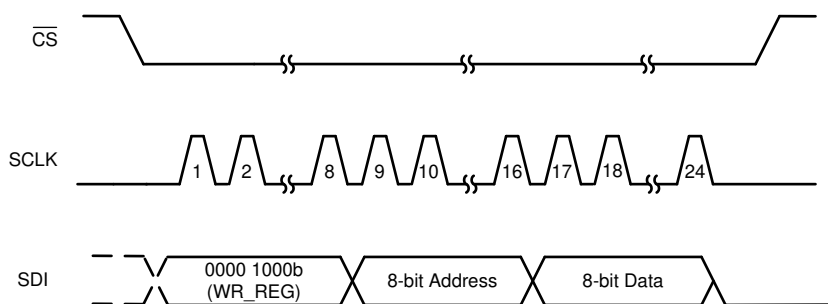


Figure 11. Register Write Operation

7.3.10.3.2 Register Read

A register read operation consists of two SPI frames: the first SPI frame initiates a register read and the second SPI frame reads data from the register address provided in the first frame. As shown in [Figure 12](#), the read command (0001 0000b), the 8-bit register address, and the 8-bit dummy data are sent over the SDI pin during the first 24-bit frame. On the rising edge of CS, the read command is decoded and the requested register data are available for reading during the next frame. During the second frame, the first eight bits on SDO correspond to the requested register read. During the second frame, SDI can be used to initiate another operation or can be set to 0.

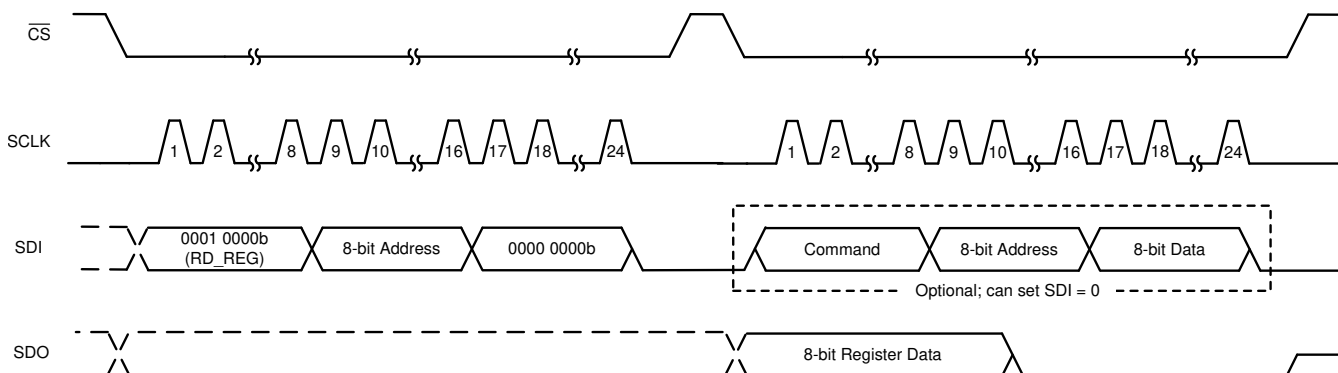


Figure 12. Register Read Operation

7.3.10.3.2.1 Register Read With CRC

A register read consists of two SPI frames, as described in the [Register Read](#) section. When the CRC module is enabled during a register read, as shown in [Figure 13](#), the device appends an 8-bit output CRC byte along with 8-bit register data. The output CRC is computed by the device on the 8-bit register data.

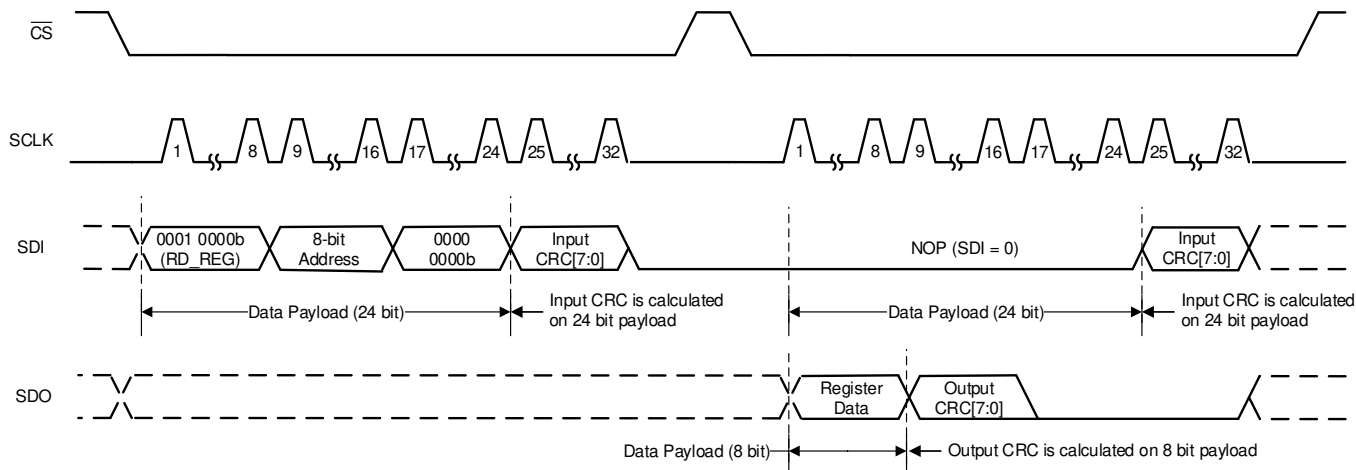


Figure 13. Register Read With CRC

7.4 Device Functional Modes

Table 7 lists the functional modes supported by the ADS7066.

Table 7. Functional Modes

FUNCTIONAL MODE	CONVERSION CONTROL	MUX CONTROL	SEQ_MODE[1:0]
Manual	$\overline{CS}$ rising edge	Register write to MANUAL_CHID	00b
On-the-fly	$\overline{CS}$ rising edge	First 5 bits after $\overline{CS}$ falling edge	10b
Auto-sequence	$\overline{CS}$ rising edge	Channel sequencer	01b

The device powers up in manual mode and can be configured into either of these modes by writing the configuration registers for the desired mode.

7.4.1 Device Power-Up and Reset

On power up, the BOR bit is set indicating a power-cycle or reset event. The device can be reset by setting the RST bit or by recycling the power on the AVDD pin.

7.4.2 Manual Mode

Manual mode allows the external host processor to directly select the analog input channel. Figure 14 shows steps for operating the device in manual mode.

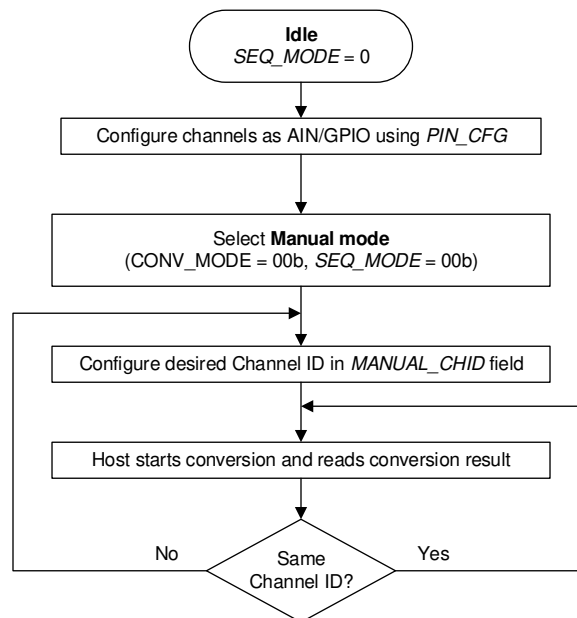


Figure 14. Device Operation in Manual Mode

In manual mode, the command to switch to a new channel, cycle N in Figure 15, is decoded by the device on the $\overline{CS}$ rising edge. The $\overline{CS}$ rising edge is also the start of the conversion signal, and thus the device samples the previously selected MUX channel in cycle N+1. The newly selected analog input channel data are available in cycle N+2. For switching the analog input channel, a register write to the MANUAL_CHID field requires 24 clocks; see the Register Write section for more details. After a channel is selected, the number of clocks required for reading the output data depends on the device output data frame size; see the Output Data Format section for more details.

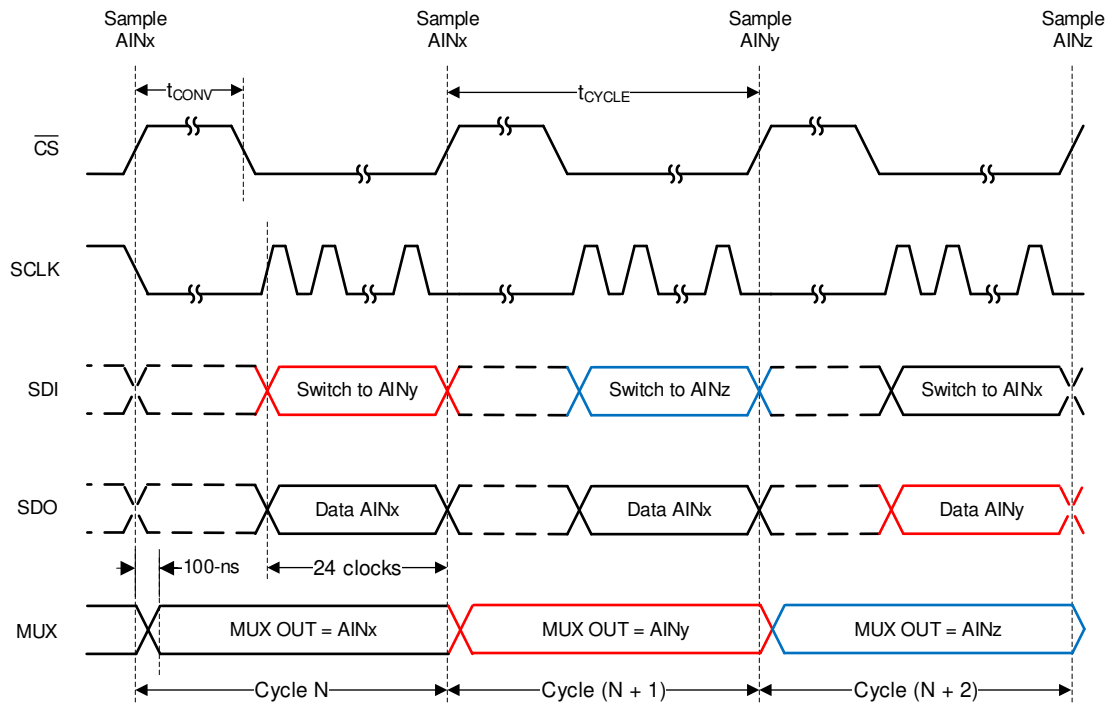


Figure 15. Starting a Conversion and Reading Data in Manual Mode

7.4.3 On-the-Fly Mode

In the on-the-fly mode of operation, as shown in Figure 16, the analog input channel is selected using the first five bits on SDI without waiting for the $\overline{CS}$ rising edge. Thus, the ADC samples the newly selected channel on the $\overline{CS}$ rising edge and there is no latency between the channel selection and the ADC output data. Table 8 lists the channel selection commands for this mode.

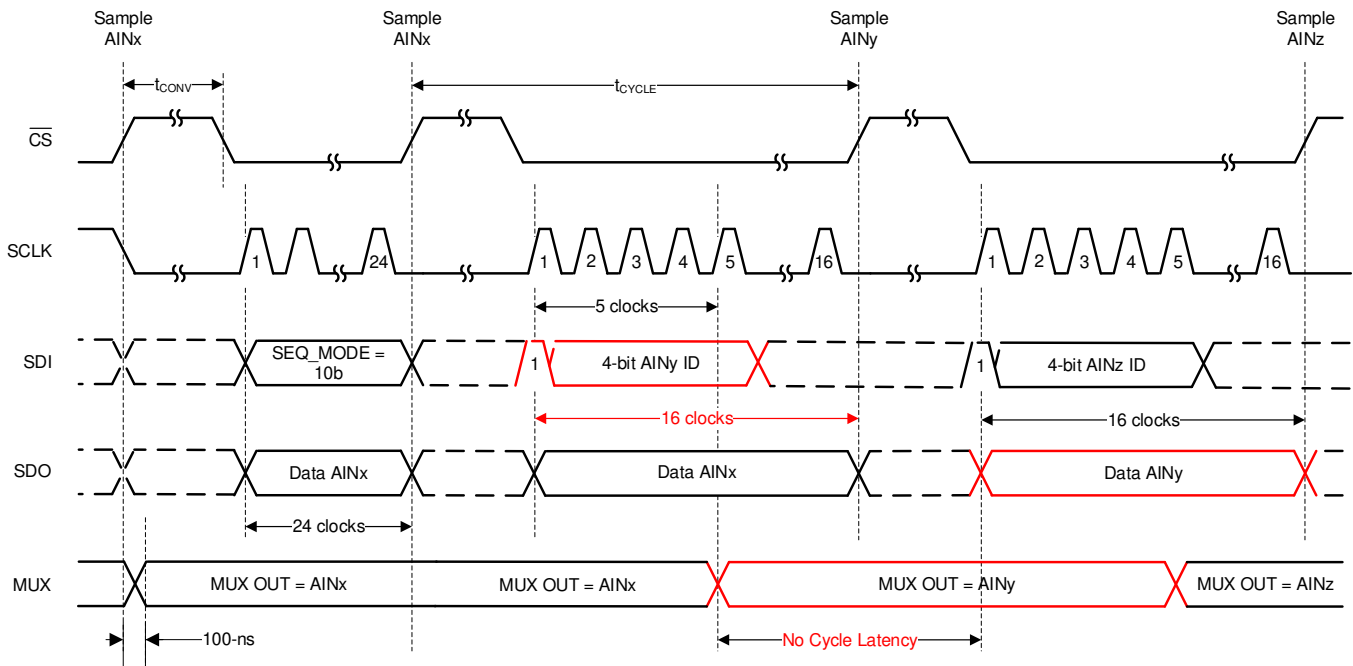


Figure 16. Starting a Conversion and Reading data in On-the-Fly Mode

Table 8. On-the-Fly Mode Channel Selection Commands

SDI BITS[15:11]	SDI BITS [10:0]	DESCRIPTION
1 0000	Don't care	Select analog input 0
1 0001	Don't care	Select analog input 1
1 0010	Don't care	Select analog input 2
1 0011	Don't care	Select analog input 3
1 0100	Don't care	Select analog input 4
1 0101	Don't care	Select analog input 5
1 0110	Don't care	Select analog input 6
1 0111	Don't care	Select analog input 7
1 1000 to 1 1111	Don't care	Reserved

The number of clocks required for reading the output data depends on the device output data frame size; see the [Output Data Format](#) section for more details.

7.4.4 Auto-Sequence Mode

In auto-sequence mode, the internal channel sequencer switches the multiplexer to the next analog input channel after every conversion. The desired analog input channels can be configured for sequencing in the AUTO_SEQ_CHSEL register. To enable the channel sequencer, set SEQ_START = 1b. After every conversion, the channel sequencer switches the multiplexer to the next analog input in ascending order. To stop the channel sequencer from selecting channels, set SEQ_START = 0b.

In the example shown in [Figure 17](#), AIN2 and AIN6 are enabled for sequencing in the AUTO_SEQ_CHSEL register. The channel sequencer loops through AIN2 and AIN6 and repeats until SEQ_START is set to 0b. The number of clocks required for reading the output data depends on the device output data frame size; see the [Output Data Format](#) section for more details.

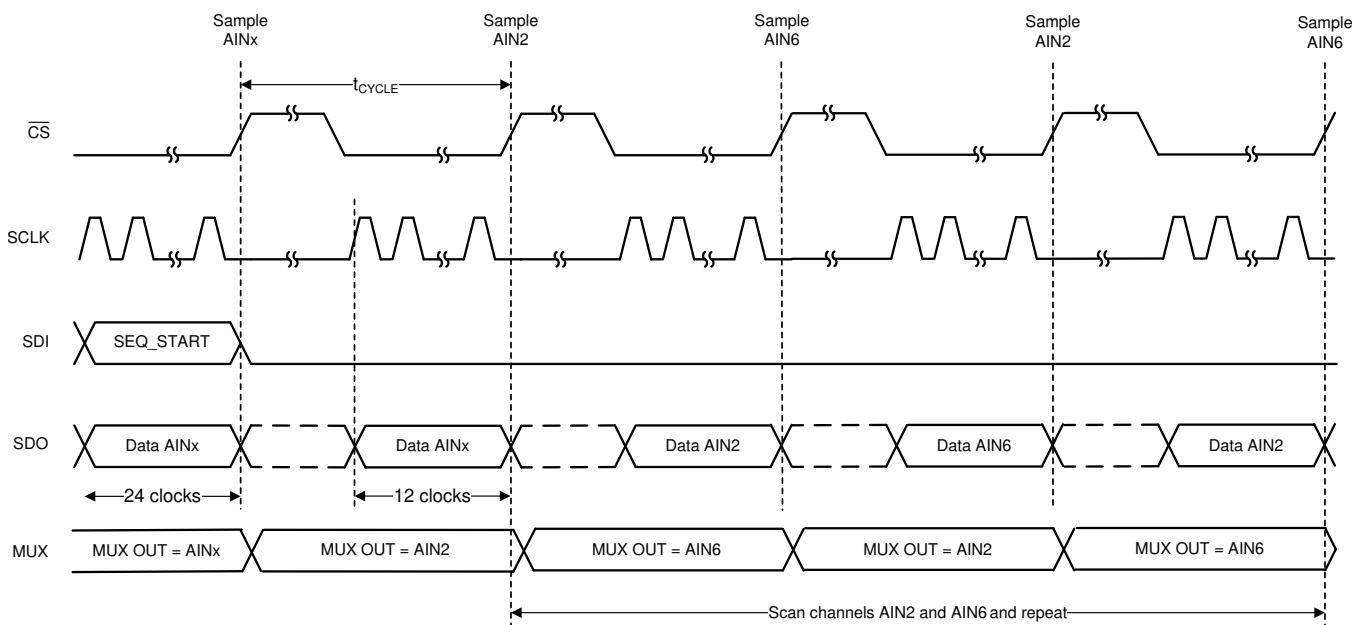


Figure 17. Starting Conversion and Reading Data in Auto-Sequence Mode

7.5 ADS7066 Registers

Table 9 lists the ADS7066 registers. All register offset addresses not listed in Table 9 should be considered as reserved locations and the register contents should not be modified.

Table 9. ADS7066 Registers

Address	Acronym	Register Name	Section
0x0	SYSTEM_STATUS	SYSTEM_STATUS Register (Address = 0x0) [reset = 0x81]	
0x1	GENERAL_CFG	GENERAL_CFG Register (Address = 0x1) [reset = 0x0]	
0x2	DATA_CFG	DATA_CFG Register (Address = 0x2) [reset = 0x0]	
0x3	OSR_CFG	OSR_CFG Register (Address = 0x3) [reset = 0x0]	
0x4	OPMODE_CFG	OPMODE_CFG Register (Address = 0x4) [reset = 0x0]	
0x5	PIN_CFG	PIN_CFG Register (Address = 0x5) [reset = 0x0]	
0x7	GPIO_CFG	GPIO_CFG Register (Address = 0x7) [reset = 0x0]	
0x9	GPO_DRIVE_CFG	GPO_DRIVE_CFG Register (Address = 0x9) [reset = 0x0]	
0xB	GPO_OUTPUT_VALUE	GPO_OUTPUT_VALUE Register (Address = 0xB) [reset = 0x0]	
0xD	GPI_VALUE	GPI_VALUE Register (Address = 0xD) [reset = 0x0]	
0x10	SEQUENCE_CFG	SEQUENCE_CFG Register (Address = 0x10) [reset = 0x0]	
0x11	CHANNEL_SEL	CHANNEL_SEL Register (Address = 0x11) [reset = 0x0]	
0x12	AUTO_SEQ_CH_SEL	AUTO_SEQ_CH_SEL Register (Address = 0x12) [reset = 0x0]	
0xBF	DIAGNOSTICS_KEY	DIAGNOSTICS_KEY Register (Address = 0xBF) [reset = 0x0]	
0xC0	DIAGNOSTICS_EN	DIAGNOSTICS_EN Register (Address = 0xC0) [reset = 0x0]	
0xC1	BIT_SAMPLE_LSB	BIT_SAMPLE_LSB Register (Address = 0xC1) [reset = 0x0]	
0xC2	BIT_SAMPLE_MSB	BIT_SAMPLE_MSB Register (Address = 0xC2) [reset = 0x0]	

Complex bit access types are encoded to fit into small table cells. Table 10 shows the codes that are used for access types in this section.

Table 10. ADS7066 Access Type Codes

Access Type	Code	Description
Read Type		
R	R	Read
Write Type		
W	W	Write
Reset or Default Value		
-n		Value after reset or the default value
Register Array Variables		
i,j,k,l,m,n		When these variables are used in a register name, an offset, or an address, they refer to the value of a register array where the register is part of a group of repeating registers. The register groups form a hierarchical structure and the array is represented with a formula.
y		When this variable is used in a register name, an offset, or an address it refers to the value of a register array.

7.5.1 SYSTEM_STATUS Register (Address = 0x0) [reset = 0x81]

SYSTEM_STATUS is shown in [Figure 18](#) and described in [Table 11](#).

Return to the [Summary Table](#).

Figure 18. SYSTEM_STATUS Register

7	6	5	4	3	2	1	0
RSVD	SEQ_STATUS	RESERVED			CRCERR_FUSE	CRCERR_IN	BOR
R-1b	R-0b	R-0b			R-0b	R/W-0b	R/W-1b

Table 11. SYSTEM_STATUS Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RSVD	R	1b	Reads return 1b.
6	SEQ_STATUS	R	0b	Status of the channel sequencer. 0b = Sequence stopped 1b = Sequence in progress
5-3	RESERVED	R	0b	Reserved. Reads return 0.
2	CRCERR_FUSE	R	0b	Device power-up configuration CRC check status. To re-evaluate this bit, software reset the device or power cycle AVDD. 0b = No problems detected in power-up configuration. 1b = Device configuration not loaded correctly.
1	CRCERR_IN	R/W	0b	Status of CRC check on incoming data. Write 1b to clear this error flag. 0b = No CRC error. 1b = CRC error detected. All register writes, except to addresses 0x00 and 0x01, are blocked.
0	BOR	R/W	1b	Brown out reset indicator. This bit is set if brown out condition occurs or device is power cycled. Write 1b to this bit to clear the flag. 0b = No brown out since last time this bit was cleared. 1b = Brown out condition detected or device power cycled.

7.5.2 GENERAL_CFG Register (Address = 0x1) [reset = 0x0]

GENERAL_CFG is shown in [Figure 19](#) and described in [Table 12](#).

Return to the [Summary Table](#).

Figure 19. GENERAL_CFG Register

7	6	5	4	3	2	1	0
REF_EN	CRC_EN	RESERVED		RANGE	CH_RST	CAL	RST
R/W-0b	R/W-0b	R-0b		R/W-0b	R/W-0b	R/W-0b	W-0b

Table 12. GENERAL_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	REF_EN	R/W	0b	Enable or disable the internal reference. 0b = Internal reference is powered down. 1b = Internal reference is enabled.
6	CRC_EN	R/W	0b	Enable or disable the CRC on device interface. 0b = CRC module disabled. 1b = CRC appended to data output. CRC check is enabled on incoming data.
5-4	RESERVED	R	0b	Reserved. Reads return 0.

Table 12. GENERAL_CFG Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3	RANGE	R/W	0b	Select the input range of the ADC. 0b = Input range of the ADC is 1x VREF 1b = Input range of the ADC is 2x VREF
2	CH_RST	R/W	0b	Force all channels to be analog inputs. 0b = Normal operation 1b = All channels will be set as analog inputs irrespective of configuration in other registers
1	CAL	R/W	0b	Calibrate ADC offset. 0b = Normal operation. 1b = ADC offset is calibrated. After calibration is complete, this bit is set to 0b.
0	RST	W	0b	Software reset all registers to default values. 0b = Normal operation. 1b = Device is reset. After reset is complete, this bit is set to 0b and BOR bit is set to 1b.

7.5.3 DATA_CFG Register (Address = 0x2) [reset = 0x0]

DATA_CFG is shown in [Figure 20](#) and described in [Table 13](#).

Return to the [Summary Table](#).

Figure 20. DATA_CFG Register

7	6	5	4	3	2	1	0
FIX_PAT	RESERVED	APPEND_STATUS[1:0]	RESERVED	RESERVED	RESERVED	CPOL_CPHA[1:0]	
R/W-0b	R-0b	R/W-0b	R-0b	R-0b	R-0b	R/W-0b	

Table 13. DATA_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	FIX_PAT	R/W	0b	Device outputs fixed data bits which can be helpful for debugging communication with the device. 0b = Normal operation. 1b = Device outputs fixed code 0xA5A5 repetitively when reading ADC data.
6	RESERVED	R	0b	Reserved. Reads return 0b.
5-4	APPEND_STATUS[1:0]	R/W	0b	Append 4-bit channel ID or status flags to output data. 0b = Channel ID and status flags are not appended to ADC data. 1b = 4-bit channel ID is appended to ADC data. 10b = 4-bit status flags are appended to ADC data. 11b = Reserved.
3-2	RESERVED	R	0b	Reserved. Reads return 0.
1-0	CPOL_CPHA[1:0]	R/W	0b	This field sets the polarity and phase of SPI communication. 0b = CPOL = 0, CPHA = 0. 1b = CPOL = 0, CPHA = 1. 10b = CPOL = 1, CPHA = 0. 11b = CPOL = 1, CPHA = 1.

7.5.4 OSR_CFG Register (Address = 0x3) [reset = 0x0]

OSR_CFG is shown in [Figure 21](#) and described in [Table 14](#).

Return to the [Summary Table](#).

Figure 21. OSR_CFG Register

7	6	5	4	3	2	1	0
RESERVED					OSR[2:0]		
R-0b					R/W-0b		

Table 14. OSR_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	RESERVED	R	0b	Reserved. Reads return 0.
2-0	OSR[2:0]	R/W	0b	Selects the oversampling ratio for ADC conversion result. 0b = No averaging 1b = 2 samples 10b = 4 samples 11b = 8 samples 100b = 16 samples 101b = 32 samples 110b = 64 samples 111b = 128 samples

7.5.5 OPMODE_CFG Register (Address = 0x4) [reset = 0x0]

OPMODE_CFG is shown in [Figure 22](#) and described in [Table 15](#).

Return to the [Summary Table](#).

Figure 22. OPMODE_CFG Register

7	6	5	4	3	2	1	0
RESERVED			OSC_SEL	CLK_DIV[3:0]			
R-0b			R/W-0b	R/W-0b			

Table 15. OPMODE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R	0b	Reserved. Reads return 0.
4	OSC_SEL	R/W	0b	Selects the oscillator for internal timing generation. 0b = High-speed oscillator. 1b = Low-power oscillator.
3-0	CLK_DIV[3:0]	R/W	0b	Sampling speed control when using averaging filters. Refer to section on oscillator and timing control for details.

7.5.6 PIN_CFG Register (Address = 0x5) [reset = 0x0]

PIN_CFG is shown in [Figure 23](#) and described in [Table 16](#).

Return to the [Summary Table](#).

Figure 23. PIN_CFG Register

7	6	5	4	3	2	1	0
PIN_CFG[7:0]							
R/W-0b							

Table 16. PIN_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	PIN_CFG[7:0]	R/W	0b	Configure device channels AIN/GPIO [7:0] as analog inputs or GPIOs. 0b = Channel is configured as analog input. 1b = Channel is configured as GPIO.

7.5.7 GPIO_CFG Register (Address = 0x7) [reset = 0x0]

GPIO_CFG is shown in [Figure 24](#) and described in [Table 17](#).

Return to the [Summary Table](#).

Figure 24. GPIO_CFG Register

7	6	5	4	3	2	1	0
GPIO_CFG[7:0]							
R/W-0b							

Table 17. GPIO_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPIO_CFG[7:0]	R/W	0b	Configure GPIO[7:0] as either digital inputs or digital outputs. 0b = GPIO is configured as digital input. 1b = GPIO is configured as digital output.

7.5.8 GPO_DRIVE_CFG Register (Address = 0x9) [reset = 0x0]

GPO_DRIVE_CFG is shown in [Figure 25](#) and described in [Table 18](#).

Return to the [Summary Table](#).

Figure 25. GPO_DRIVE_CFG Register

7	6	5	4	3	2	1	0
GPO_DRIVE_CFG[7:0]							
R/W-0b							

Table 18. GPO_DRIVE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_DRIVE_CFG[7:0]	R/W	0b	Configure digital outputs GPO[7:0] as open-drain or push-pull outputs. 0b = Digital output is open-drain; connect external pullup resistor. 1b = Push-pull driver is used for digital output.

7.5.9 GPO_OUTPUT_VALUE Register (Address = 0xB) [reset = 0x0]

GPO_OUTPUT_VALUE is shown in [Figure 26](#) and described in [Table 19](#).

Return to the [Summary Table](#).

Figure 26. GPO_OUTPUT_VALUE Register

7	6	5	4	3	2	1	0
GPO_OUTPUT_VALUE[7:0]							
R/W-0b							

Table 19. GPO_OUTPUT_VALUE Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_OUTPUT_VALUE[7:0]	R/W	0b	Logic level to be set on digital outputs GPO[7:0]. 0b = Digital output set to logic 0. 1b = Digital output set to logic 1.

7.5.10 GPI_VALUE Register (Address = 0xD) [reset = 0x0]

GPI_VALUE is shown in [Figure 27](#) and described in [Table 20](#).

Return to the [Summary Table](#).

Figure 27. GPI_VALUE Register

7	6	5	4	3	2	1	0
GPI_VALUE[7:0]							
R-0b							

Table 20. GPI_VALUE Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPI_VALUE[7:0]	R	0b	Readback the logic level on GPIO[7:0]. 0b = GPIO is at logic 0. 1b = GPIO is at logic 1.

7.5.11 SEQUENCE_CFG Register (Address = 0x10) [reset = 0x0]

SEQUENCE_CFG is shown in [Figure 28](#) and described in [Table 21](#).

Return to the [Summary Table](#).

Figure 28. SEQUENCE_CFG Register

7	6	5	4	3	2	1	0
RESERVED			SEQ_START	RESERVED		SEQ_MODE[1:0]	
R-0b			R/W-0b	R-0b		R/W-0b	

Table 21. SEQUENCE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R	0b	Reserved. Reads return 0.
4	SEQ_START	R/W	0b	Control for start of channel sequence when using auto sequence mode (SEQ_MODE = 01b). 0b = Stop channel sequencing. 1b = Start channel sequencing in ascending order for channels enabled in AUTO_SEQ_CH_SEL register.
3-2	RESERVED	R	0b	Reserved. Reads return 0.
1-0	SEQ_MODE[1:0]	R/W	0b	Selects the mode of scanning of analog input channels. 0b = Manual sequence mode; channel selected by MANUAL_CHID field. 1b = Auto sequence mode; channel selected by AUTO_SEQ_CHSEL. 10b = On-the-fly sequence mode. 11b = Reserved.

7.5.12 CHANNEL_SEL Register (Address = 0x11) [reset = 0x0]

CHANNEL_SEL is shown in [Figure 29](#) and described in [Table 22](#).

Return to the [Summary Table](#).

Figure 29. CHANNEL_SEL Register

7	6	5	4	3	2	1	0
RESERVED				MANUAL_CHID[3:0]			
R-0b				R/W-0b			

Table 22. CHANNEL_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	RESERVED	R	0b	Reserved. Reads return 0.
3-0	MANUAL_CHID[3:0]	R/W	0b	In manual mode (SEQ_MODE = 00b), this field contains the 4-bit channel ID of the analog input channel for next ADC conversion. For valid ADC data, the selected channel must not be configured as GPIO in PIN_CFG register. 1xxx = Reserved. 0b = AIN0 1b = AIN1 10b = AIN2 11b = AIN3 100b = AIN4 101b = AIN5 110b = AIN6 111b = AIN7 1000b = Reserved.

7.5.13 AUTO_SEQ_CH_SEL Register (Address = 0x12) [reset = 0x0]

AUTO_SEQ_CH_SEL is shown in [Figure 30](#) and described in [Table 23](#).

Return to the [Summary Table](#).

Figure 30. AUTO_SEQ_CH_SEL Register

7	6	5	4	3	2	1	0
AUTO_SEQ_CH_SEL[7:0]							
R/W-0b							

Table 23. AUTO_SEQ_CH_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	AUTO_SEQ_CH_SEL[7:0]	R/W	0b	Select analog input channels AIN[7:0] in for auto sequencing mode. 0b = Analog input channel is not enabled in scanning sequence. 1b = Analog input channel is enabled in scanning sequence.

7.5.14 DIAGNOSTICS_KEY Register (Address = 0xBF) [reset = 0x0]

DIAGNOSTICS_KEY is shown in [Figure 31](#) and described in [Table 24](#).

Return to the [Summary Table](#).

Figure 31. DIAGNOSTICS_KEY Register

7	6	5	4	3	2	1	0
DIAG_KEY[7:0]							
R/W-0b							

Table 24. DIAGNOSTICS_KEY Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	DIAG_KEY[7:0]	R/W	0b	Enable write access to diagnostics registers in address locations 0xC0, 0xC1, and 0xC2. Write 0x96 to this register to enable write access to diagnostics registers.

7.5.15 DIAGNOSTICS_EN Register (Address = 0xC0) [reset = 0x0]

DIAGNOSTICS_EN is shown in [Figure 32](#) and described in [Table 25](#).

Return to the [Summary Table](#).

Figure 32. DIAGNOSTICS_EN Register

7	6	5	4	3	2	1	0
RESERVED			VTEST_EN	RESERVED			BITWALK_EN
R-0b			R/W-0b	R-0b			R/W-0b

Table 25. DIAGNOSTICS_EN Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R	0b	Reserved. Reads return 0.
4	VTEST_EN	R/W	0b	Enable measurement of internal 1.8 V (typical) test voltage using AIN6. When using this mode, AIN6 pin should not be left floating and should not be connected to any external circuit. If BITWALK_EN = 1b, this bit has no effect. 0b = Normal operation. 1b = AIN6 is internally connected to 1.8V (typical) test voltage. AIN6 pin should be floating and should not be connected to any external circuit.
3-1	RESERVED	R	0b	Reserved. Reads return 0.
0	BITWALK_EN	R/W	0b	Enable bit-walk mode of the ADC bit decisions. 0b = Normal operation. 1b = Bit walk mode enabled.

7.5.16 BIT_SAMPLE_LSB Register (Address = 0xC1) [reset = 0x0]

BIT_SAMPLE_LSB is shown in [Figure 33](#) and described in [Table 26](#).

Return to the [Summary Table](#).

Figure 33. BIT_SAMPLE_LSB Register

7	6	5	4	3	2	1	0
BIT_SAMPLE_LSB[7:0]							
R/W-0b							

Table 26. BIT_SAMPLE_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	BIT_SAMPLE_LSB[7:0]	R/W	0b	Define the [7:0] bit positions during sampling phase of the ADC. This field has no effect when DIAG_EN = 0.

7.5.17 BIT_SAMPLE_MSB Register (Address = 0xC2) [reset = 0x0]

BIT_SAMPLE_MSB is shown in [Figure 34](#) and described in [Table 27](#).

Return to the [Summary Table](#).

Figure 34. BIT_SAMPLE_MSB Register

7	6	5	4	3	2	1	0
BIT_SAMPLE_MSB[7:0]							
R/W-0b							

Table 27. BIT_SAMPLE_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	BIT_SAMPLE_MSB[7:0]	R/W	0b	Define the [15:8] bit positions during sampling phase of the ADC. This field has no effect when DIAG_EN = 0.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The primary circuit required to maximize the performance of a high-precision, successive approximation register (SAR), analog-to-digital converter (ADC) is the input driver circuits. This section details some general principles for designing the input driver circuit for the ADS7066.

8.2 Typical Application

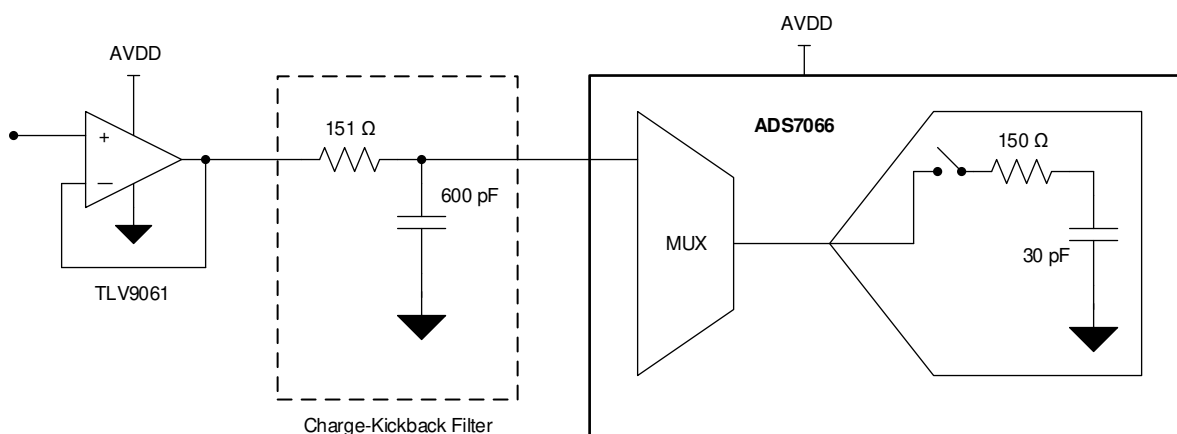


Figure 35. DAQ Circuit: Single-Supply DAQ

8.2.1 Design Requirements

The goal of this application is to design a single-supply digital acquisition (DAQ) circuit based on the ADS7066 with SNR greater than 80 dB and THD less than –80 dB for input frequencies of 2 kHz at full throughput.

8.2.2 Detailed Design Procedure

The optimal input driver circuit for a high-precision SAR ADC consists of a driving amplifier and a charge-kickback filter (RC filter). The amplifier driving the ADC must have low output impedance and be able to charge the internal sampling capacitor to a 16-bit settling level within the minimum acquisition time. The charge-kickback filter helps attenuate the sampling charge injection from the switched-capacitor input stage of the ADC and helps reduce the wide-band noise contributed by the front-end circuit.

Typical Application (continued)

8.2.2.1 Charge-Kickback Filter and ADC Amplifier

As illustrated in [Figure 35](#), a filter capacitor (C_{FLT}) is connected from each input pin of the ADC to ground. This capacitor helps reduce the sampling charge injection and provides a charge bucket to quickly charge the internal sample-and-hold capacitors during the acquisition process. This capacitor must be a COG- or NPO-type. One method for determining the required amplifier bandwidth and the values of the RC charge-kickback filter is provided in this section. This optimization and more details on the math behind the component selection are covered in [ADC Precision Labs](#).

The minimum bandwidth of the amplifier for driving the ADC can be computed using the settling accuracy (0.5 LSB) and settling time (acquisition time) information. [Equation 4](#), [Equation 5](#), [Equation 6](#), and [Equation 7](#) compute the unity-gain bandwidth (UGBW) of the amplifier.

$$LSB = \frac{V_{REF}}{2^N} = \frac{2.5 V}{2^{16}} = 38.2 \mu V \quad (4)$$

$$\tau_c = \frac{-t_{ACQ}}{\ln\left(\frac{0.5 \cdot LSB}{100 mV}\right)} = \frac{-800 ns}{\ln\left(\frac{0.5 \cdot (38.2 \mu V)}{100 mV}\right)} = 93.4 ns \quad (5)$$

$$\tau_{oa} = \frac{\tau_c}{\sqrt{17}} = \frac{93.4 ns}{\sqrt{17}} = 22.7 ns \quad (6)$$

$$UGBW = \frac{1}{2 \cdot \pi \cdot \tau_{oa}} = \frac{1}{2 \cdot \pi \cdot (22.7 ns)} = 7 MHz \quad (7)$$

Based on the result of [Equation 7](#), select an amplifier that has more than 7-MHz UGBW. For this example, [TLV9061](#) is used. The [OPA320](#) can be used for improved precision.

The value of C_{filt} is computed in [Equation 8](#) by taking 20 times the internal sample-and-hold capacitance. The factor of 20 is a rule of thumb that is intended to minimize the droop in voltage on the charge-bucket capacitor, C_{filt} , after the start of the acquisition period. The filter resistor, R_{filt} , is computed in [Equation 9](#) using the op-amp time constant and C_{filt} . [Equation 10](#) and [Equation 11](#) compute the minimum and maximum R_{filt} values, respectively.

$$C_{filt} = 20 \cdot C_{SH} = 20 \cdot (30 pF) = 600 pF \quad (8)$$

$$R_{filt} = \frac{4 \cdot \tau_{oa}}{C_{filt}} = \frac{4 \cdot (22.7 ns)}{600 pF} = 151 \Omega \quad (9)$$

$$R_{filtMin} = 0.25 \cdot R_{filt} = 0.25 \cdot (33 \Omega) = 37.7 \Omega \quad (10)$$

$$R_{filtMax} = 2 \cdot R_{filt} = 2 \cdot (33 \Omega) = 302.1 \Omega \quad (11)$$

9 Power Supply Recommendations

9.1 AVDD and DVDD Supply Recommendations

The ADS7066 has two separate power supplies: AVDD and DVDD. The device operates on AVDD; DVDD is used for the interface circuits. AVDD and DVDD can be independently set to any value within the permissible ranges. [Figure 36](#), decouple the AVDD and DVDD pins individually with 1- μ F ceramic decoupling capacitors.

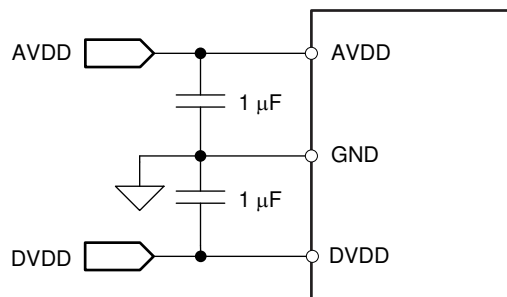


Figure 36. Power-Supply Decoupling

10 Layout

10.1 Layout Guidelines

Figure 37 shows a board layout example for the ADS7066. Avoid crossing digital lines with the analog signal path and keep the analog input signals and the reference input signals away from noise sources.

Use 1- μ F ceramic bypass capacitors in close proximity to the analog (AVDD) and digital (DVDD) power-supply pins. Avoid placing vias between the AVDD and DVDD pins and the bypass capacitors. Connect all ground pins to the ground plane using short, low-impedance paths.

Place the reference decoupling capacitor (C_{REF}) close to the device REF and GND pins. Avoid placing vias between the REF pin and the bypass capacitors.

The charge-kickback RC filters are placed close to the device. Among ceramic surface-mount capacitors, COG- or NPO-type ceramic capacitors provide the best capacitance precision. The type of dielectric used in COG- or NPO-type ceramic capacitors provides the most stable electrical properties over voltage, frequency, and temperature changes.

10.2 Layout Example

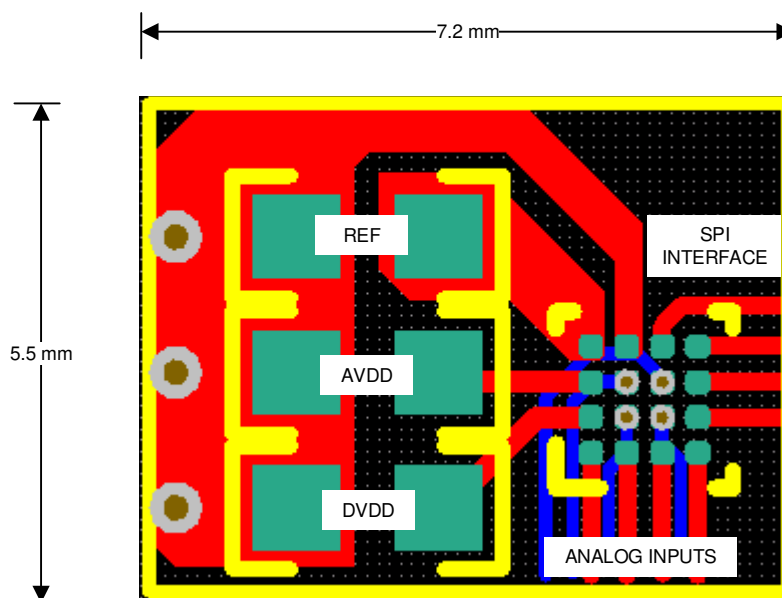


Figure 37. Example Layout

11 Device and Documentation Support

11.1 Device Support

11.1.1 Development Support

Texas Instruments, [ADC Precision Labs](#)

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [REF60xx High-Precision Voltage Reference With Integrated ADC Drive Buffer data sheet](#)
- Texas Instruments, [TLV906xS 10-MHz, RRIO, CMOS Operational Amplifiers for Cost-Sensitive Systems data sheet](#)
- Texas Instruments, [OPAx320x Precision, 20-MHz, 0.9-pA, Low-Noise, RRIO, CMOS Operational Amplifier With Shutdown data sheet](#)

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Community Resources

TI E2E™ [support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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11.5 Trademarks

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11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
XDS7066IYBHR	ACTIVE	DSBGA	YBH	16	3000	TBD	Call TI	Call TI	-40 to 125		Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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