DATA SHEET

TDA6101Q
Video output amplifier

Preliminary specification
Supersedes data of November 1991
File under Integrated Circuits, IC02

1995 Feb 07

Philips Semiconductors

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Video output amplifier TDA6101Q

FEATURES

- High bandwidth and high slew rate
- No external heatsink required
- Black-current measurement output for Automatic Black-current Stabilization (ABS)
- Two cathode outputs; one for DC currents, and one for transient currents
- A feedback output separated from the cathode outputs
- Internal protection against positive appearing Cathode-Ray Tube (CRT) flashover discharges
- ESD protection
- Simple application with a variety of colour decoders
- Differential input with a designed maximum common mode input capacitance of 3 pF, a maximum differential mode input capacitance of 0.5 pF and a differential input voltage temperature drift of 20 μV/K
- Defined switch-off behaviour.

GENERAL DESCRIPTION

The TDA6101Q is a video output amplifier with 9 MHz bandwidth. The device is contained in a single in-line 9-pin medium power (DBS9MPF) package, using high-voltage DMOS technology, intended to drive the cathode of a colour CRT.

QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V_{DDH}	high level supply voltage		0	–	250	V
V_{DDL}	low level supply voltage		0	–	14	V
I_{DDH}	quiescent high voltage supply current	$V_{oc} = 0.5V_{DDH}$	3.5	4.4	5.5	mA
I_{DDL}	quiescent low voltage supply current	$V_{oc} = 0.5V_{DDH}$	2.2	2.8	3.5	mA
V_I	input voltage		0	–	V_{DDL}	V
V_{oc}, V_{fb}	output voltage		V_{DDL}	–	V_{DDH}	V
T_{stg}	storage temperature		–55	–	+150	°C
T_{amb}	operating ambient temperature		–20	–	+65	°C

ORDERING INFORMATION

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
TDA6101Q	DBS9MPF	plastic DIL-bent-SIL medium power package with fin; 9 leads	SOT111-1

BLOCK DIAGRAM

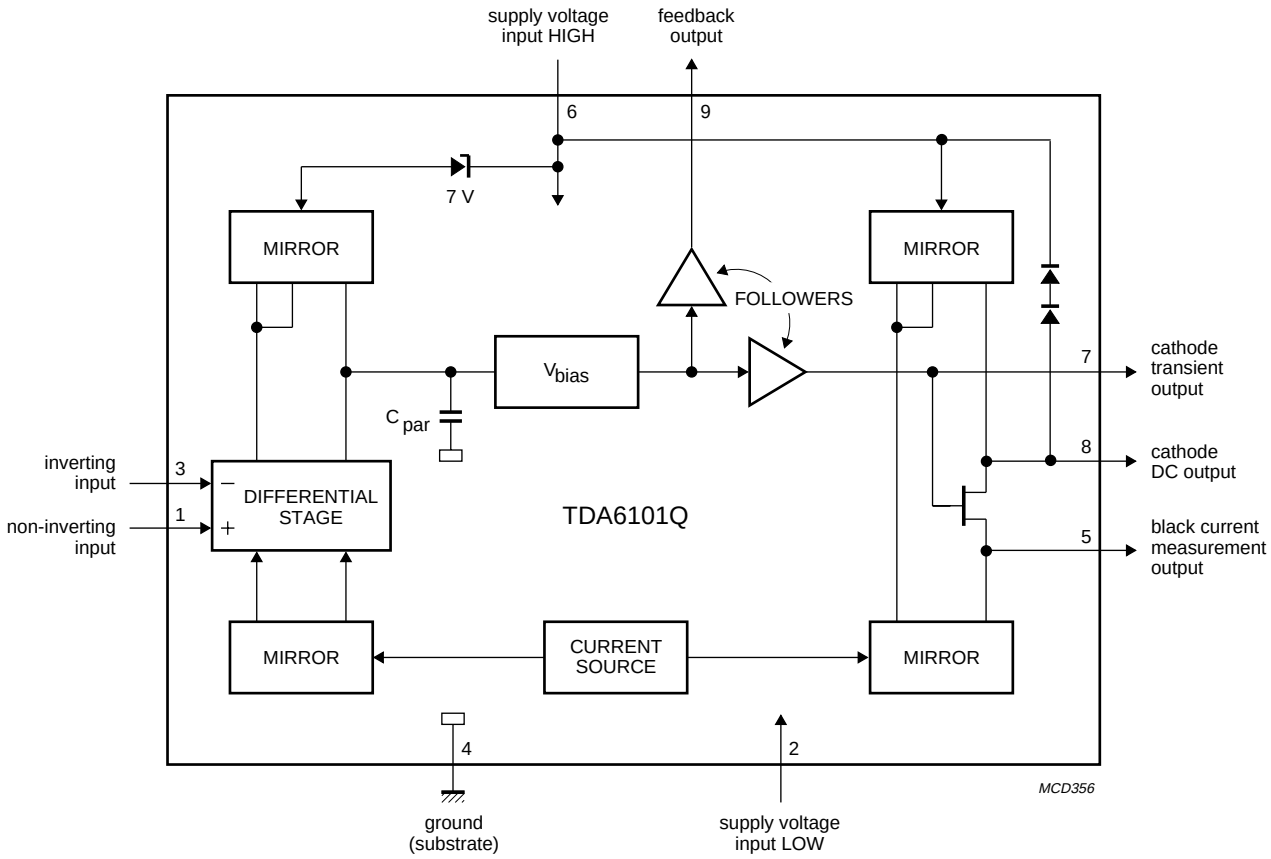


Fig.1 Block diagram.

PINNING

SYMBOL	PIN	DESCRIPTION
V_{ip}	1	non-inverting voltage input
V_{DDL}	2	supply voltage LOW
V_{in}	3	inverting voltage input
GND	4	ground, substrate
I_{om}	5	black current measurement output
V_{DDH}	6	supply voltage HIGH
V_{cn}	7	cathode transient voltage output
V_{oc}	8	cathode DC voltage output
V_{fb}	9	feedback voltage output

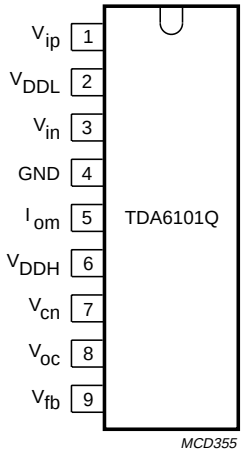


Fig.2 Pin configuration.

LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134). Voltages measured with respect to GND (pin 4); currents as specified in Fig.1; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V_{DDH}	high level supply voltage		0	250	V
V_{DDL}	low level supply voltage		0	14	V
V_I	input voltage		0	V_{DDL}	V
V_{Idm}	differential mode input voltage		–6	+6	V
V_{om}	measurement output voltage		0	V_{DDL}	
V_{oc}	cathode output voltage		V_{DDL}	V_{DDH}	V
V_{fb}	feedback output voltage		V_{DDL}	V_{DDH}	V
I_{in},I_{ip}	input current		0	1	mA
I_{ocsmL}	low non-repetitive peak cathode output current	flashover discharge = 100 μC	0	5	A
I_{ocsmH}	high non-repetitive peak cathode output current	flashover discharge = 100 nC	0	10	A
P_{tot}	total power dissipation		0	1.9	W
T_{stg}	storage temperature		–55	+150	°C
T_j	junction temperature		–20	+150	°C
V_{es}	electrostatic handling				
	human body model (HBM)		–	> 1500	V
	machine model (MM)		–	> 400	V

HANDLING

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take normal precautions appropriate to handling MOS devices (see *"Handling MOS Devices"*).

QUALITY SPECIFICATION

Quality specification *"SNW-FQ-611 part E"* is applicable, except for ESD Human body model see Chapter "Limiting values", and can be found in the *"Quality reference handbook"* (ordering number 9398 510 63011).

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER(1)	VALUE	UNIT
$R_{th\ j\text{-}a}$	thermal resistance from junction to ambient in free air	56	K/W
$R_{th\ j\text{-}c}$	thermal resistance from junction to case	12	K/W

Note

1. External heatsink not required.

CHARACTERISTICS

Operating range: T_{amb} = −20 to 65 °C; V_{DDH} = 180 to 210 V; V_{DDL} = 10.8 to 13.2 V; V_{ip} = 2.6 to 5 V; V_{om} = 1.4 V to V_{DDL}.

Test conditions (unless otherwise specified): T_{amb} = 25 °C; V_{DDH} = 200 V; V_{DDL} = 12 V; V_{ip} = 5 V; V_{om} = 6 V; C_L = 10 pF (C_L consists of parasitic and cathode capacitance); measured in test circuit Fig.3.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
I_{DDH}	quiescent HIGH voltage supply current	$V_{oc} = 0.5V_{DDH}$	3.5	4.4	5.5	mA
I_{DDL}	quiescent LOW voltage supply current	$V_{oc} = 0.5V_{DDH}$	2.2	2.8	3.5	mA
I_{bias}	input bias current	$V_{oc} = 0.5V_{DDH}$	0	–	20	µA
I_{offset}	input offset current	$V_{oc} = 0.5V_{DDH}$	−3	–	+3	µA
$I_{om(offset)}$	offset current of measurement output	I_{oc} = 0 µA; −1.0 V < V_{1-3} < 1.0 V; 1.4 V < V_{om} < V_{DDL}	−5	0	+5	µA
$\frac{\Delta I_{om}}{\Delta I_{oc}}$	linearity of current transfer	−10 µA < I_{oc} < 3 mA; −1.0 V < V_{1-3} < 1.0 V; 1.4 V < V_{om} < V_{DDL}	0.9	1.0	1.1	
V_{offset}	input offset voltage	$V_{oc} = 0.5V_{DDH}$	−50	–	+50	mV
$V_{oc(min)}$	minimum output voltage	V_{1-3} = −1 V	–	–	20	V
$V_{oc(max)}$	maximum output voltage	V_{1-3} = −1 V	V_{DDH} − 12	–	–	V
GB	gain-bandwidth product of open-loop gain: V_{fb} / $V_{i, dm}$	f = 500 kHz; V_{ocDC} = 100 V	–	0.8	–	GHz
B_S	small signal bandwidth	V_{ocAC} = 60 V (p-p); V_{ocDC} = 100 V	7	9	–	MHz
B_L	large signal bandwidth	V_{ocAC} = 100 V (p-p); V_{ocDC} = 100 V	5.5	7	–	MHz
t_{pd}	cathode output propagation delay time 50% input to 50% output	V_{ocAC} = 100 V (p-p); V_{ocDC} = 100 V square wave; f < 1 MHz; $t_r = t_f$ = 40 ns; see Figs 4 and 5	27	38	49	ns
t_r	cathode output rise time 10% output to 90% output	V_{oc} = 50 to 150 V square wave; f < 1 MHz; t_f = 40 ns; see Fig.4	43	55	68	ns
t_f	cathode output fall time 90% output to 10% output	V_{oc} = 150 to 50 V square wave; f < 1 MHz; t_r = 40 ns; see Fig.5	43	55	68	ns
t_s	settling time 50% input to (99% < output < 101%)	V_{ocAC} = 100 V (p-p); V_{ocDC} = 100 V square wave; f < 1 MHz; $t_r = t_f$ = 40 ns; see Figs 4 and 5	–	–	350	ns
SR	slew rate between 50 V to 150 V	V_{1-3} = 2 V (p-p) square wave; f < 1 MHz; $t_r = t_f$ = 40 ns	–	1700	–	V/µs

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
O_v	cathode output voltage overshoot	V_{ocAC} = 100 V (p-p); V_{ocDC} = 100 V square wave; f < 1 MHz; $t_r = t_f$ = 40 ns; see Figs 4 and 5; note 1	–	9	–	%
SVRRH	high supply voltage rejection ratio	f < 50 kHz; note 2	–	85	–	dB
SVRRL	low supply voltage rejection ratio	f < 50 kHz; note 2	–	70	–	dB

Notes

1. If the difference between V_{DDL} and V_{ip} is less than 7 V, overshoot cannot be specified.
2. SVRR: The ratio of the change in supply voltage to the change in input voltage when there is no change in output voltage.

Cathode output

The cathode output is protected against peak currents (caused by positive voltage peaks during high-resistance flash) of 5 A maximum with a charge content of 100 μC.

The cathode is also protected against peak currents (caused by positive voltage peaks during low-resistance flash) of 10 A maximum with a charge content of 100 nC.

Flashover protection

The TDA6101Q incorporates protection diodes against CRT flashover discharges that clamp the cathode output pin to the V_{DDH} pin. The DC supply voltage at the V_{DDH} pin has to be within the operating range of 180 to 210 V to ensure that the Absolute Maximum Rating for V_{DDH} of 250 V will not be exceeded during flashover. To limit the diode current, an external 820 Ω carbon high-voltage resistor in series with the cathode output and a 2 kV spark gap are needed (for this resistor-value, the CRT has to be connected to the main PCB). This addition produces an increase in the rise and fall times of approximately 5 ns and a decrease in the overshoot of approximately 3%.

V_{DDH} to GND must be decoupled:

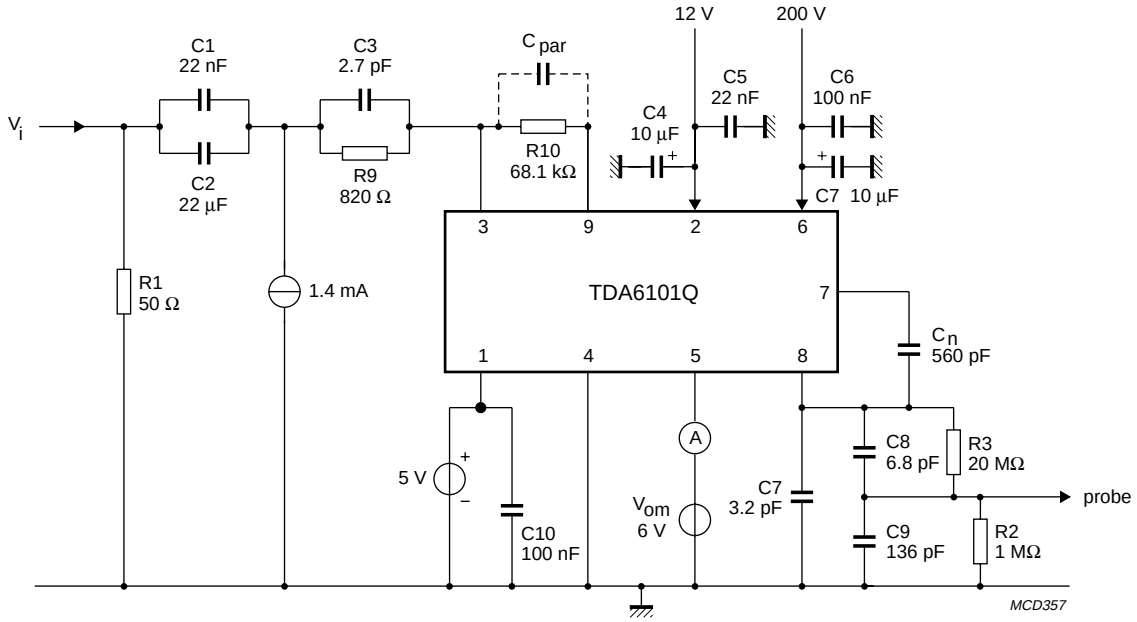
1. With a capacitor >20 nF with good HF behaviour (e.g. foil). This capacitance must be placed as close as possible to pins 6 and 4, but definitely within 5 mm.
2. With a capacitor >10 μF on the picture tube base print (common for three output stages).

V_{DDL} to GND must be decoupled:

1. With a capacitor >20 nF with good HF behaviour (e.g. ceramic). This capacitance must be placed as close as possible to pins 2 and 4, but definitely within 10 mm.

Switch-off behaviour

The switch-off behaviour of the TDA6101Q is defined: when the bias current becomes zero, at V_{DDL} (pin 2) lower than approximately 5 V, all the output pins (pins 7, 8 and 9) will be high.



C_{par} = 150 fF.

Fig.3 Test circuit with feedback factor $^{1}/_{83}$.

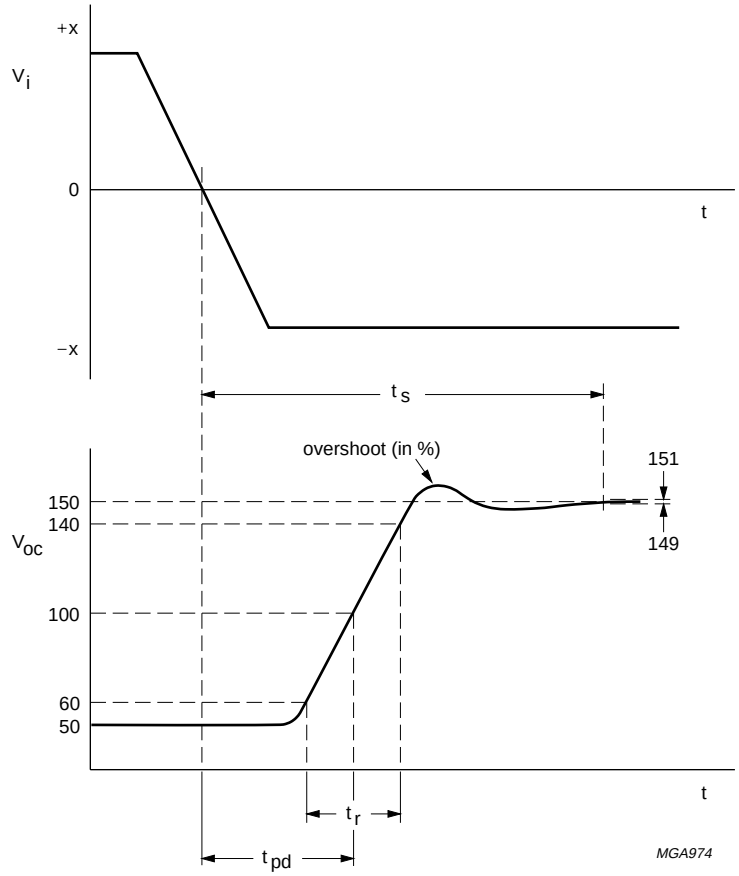


Fig.4 Output voltage (pin 8) rising edge as a function of the AC input signal.

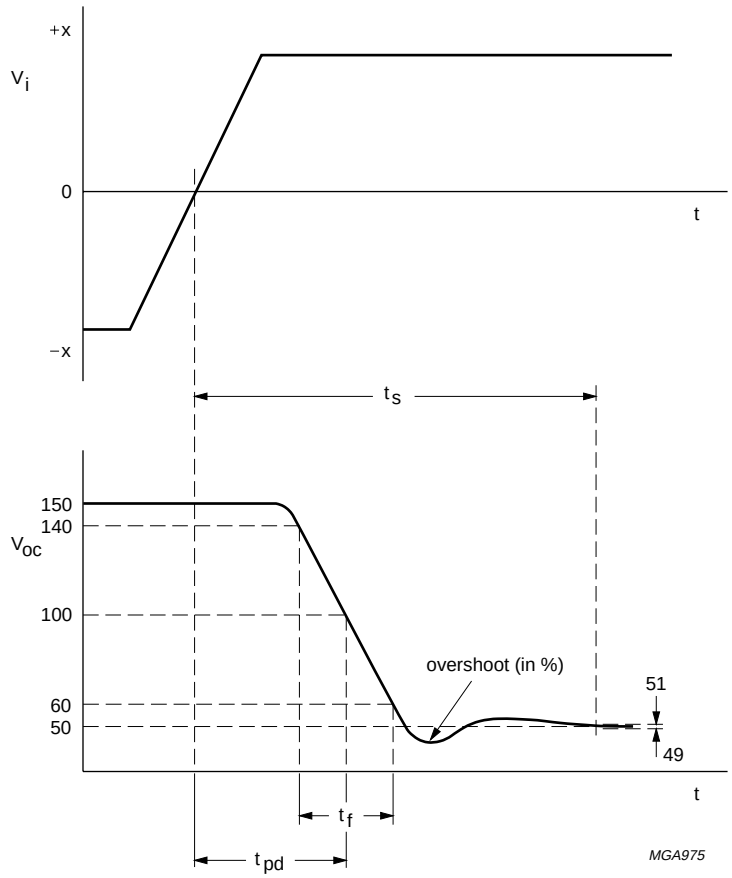


Fig.5 Output voltage (pins 8) falling edge as a function of the AC input signal.

TEST AND APPLICATION INFORMATION

Dissipation

Regarding dissipation, distinction must first be made between static dissipation (independent of frequency) and dynamic dissipation (proportional to frequency).

The static dissipation of the TDA6101Q is due to high and low voltage supply currents and load currents in the feedback network and CRT.

The static dissipation equals:

$$P_{stat} = V_{DDL} \times I_{DDL} + V_{DDH} \times I_{DDH} + V_{oc} \times I_{oc} - V_{fb} \times \left(\frac{V_{fb}}{R_{fb}} \right)$$

R_{fb} = value of feedback resistor.

I_{oc} = DC value of cathode current.

The dynamic dissipation equals:

$P_{dyn} = V_{DDH} \times (C_L + C_{fb} + C_{int}) \times f_i \times V_{o(p-p)} \times \delta$

C_L = load capacitance.

C_{fb} = feedback capacitance (≈ 150 fF).

C_{int} = internal load capacitance (≈ 4 pF).

f_i = input frequency.

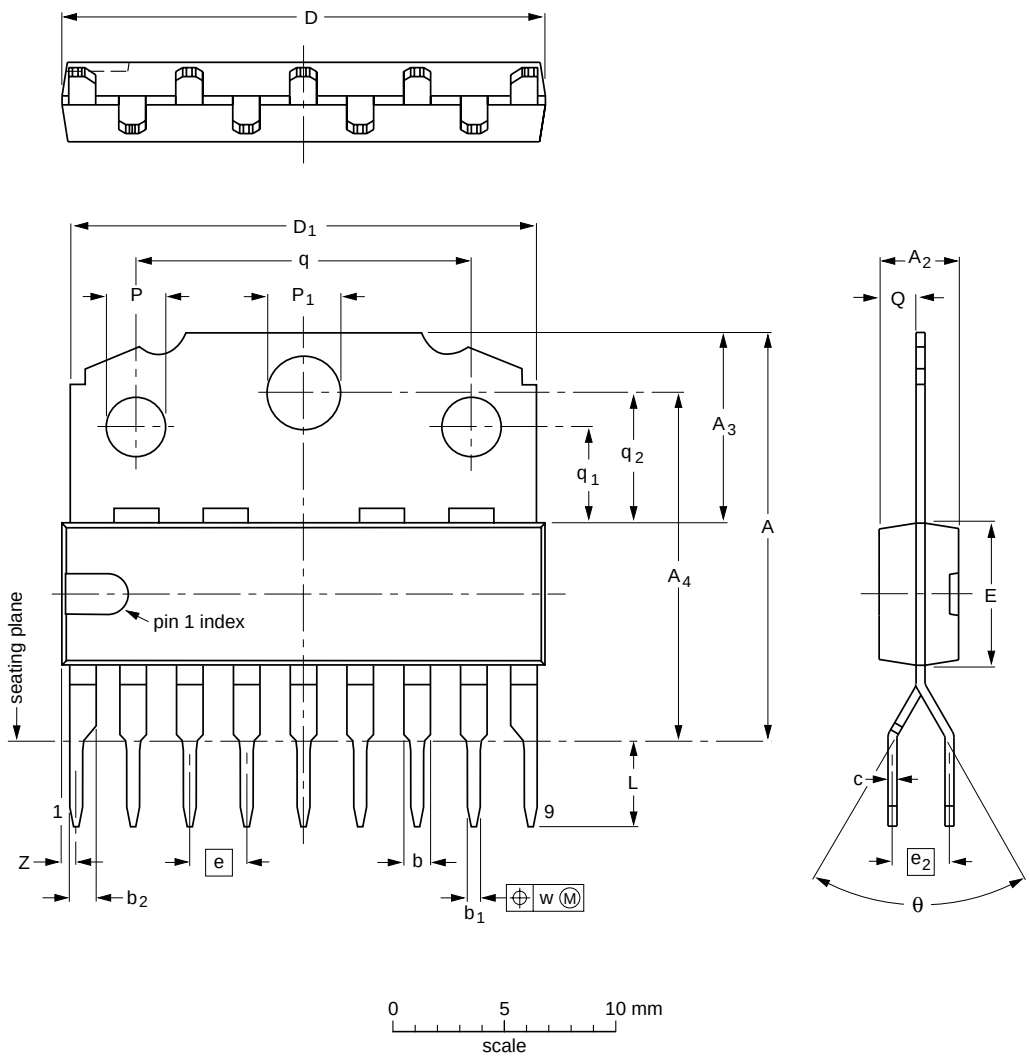
$V_{o(p-p)}$ = output voltage (peak-to-peak value).

δ = non-blanking duty-cycle (≈ 0.8).

The IC must be mounted on the picture tube base print to minimize the load capacitance (C_L).

PACKAGE OUTLINE

DBS9MPF: plastic DIL-bent-SIL medium power package with fin; 9 leads **SOT111-1**



DIMENSIONS (mm are the original dimensions)

UNIT	A	A_2 max.	A_3	A_4	b	b_1	b_2	c	$D^{(1)}$	D_1	$E^{(1)}$	e	e_2	L	P	P_1	Q	q	q_1	q_2	w	$Z^{(1)}$ max.	θ
mm	18.5 17.8	3.7	8.7 8.0	15.5 15.1	1.40 1.14	0.67 0.50	1.40 1.14	0.48 0.38	21.8 21.4	21.4 20.7	6.48 6.20	2.54	2.54	3.9 3.4	2.75 2.50	3.4 3.2	1.75 1.55	15.1 14.9	4.4 4.2	5.9 5.7	0.25	1.0	65^o 55^o

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT111-1						~~92-11-17~~ 95-03-11

SOLDERING

Plastic single in-line packages

BY DIP OR WAVE

The maximum permissible temperature of the solder is 260 °C; this temperature must not be in contact with the joint for more than 5 s. The total contact time of successive solder waves must not exceed 5 s.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified storage maximum. If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

REPAIRING SOLDERED JOINTS

Apply the soldering iron below the seating plane (or not more than 2 mm above it). If its temperature is below 300 °C, it must not be in contact for more than 10 s; if between 300 and 400 °C, for not more than 5 s.

DEFINITIONS

Data sheet status	
Objective specification	This data sheet contains target or goal specifications for product development.
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.
Product specification	This data sheet contains final product specifications.
Limiting values	
Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.	
Application information	
Where application information is given, it is advisory and does not form part of the specification.	

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NOTES

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