



ACE726C

500KHz, 18V, 2A Synchronous Step-Down Converter

Description

The ACE726C is a fully integrated, high-efficiency 2A synchronous rectified step-down converter. The ACE726C operates at high efficiency over a wide output current loadrange.

This device offers two operation modes, PWM control and PFM Mode switching control, which allows a high efficiency over the wider range of the load.

The ACE726C requires a minimum number of readily available standard external components and is available in a 6-pin SOT23 ROHS compliant package.

Features

- High Efficiency: Up to 96%
- 500KHz Frequency Operation
- 2A Output Current
- No Schottky Diode Required
- 4.2V to 18V Input Voltage Range
- 0.8V Reference
- Slope Compensated Current Mode Control for Excellent Line and Load Transient Response
- Integrated internal compensation
- Stable with Low ESR Ceramic Output Capacitors
- Over Current Protection with Hiccup-Mode
- Thermal Shutdown
- Inrush Current Limit and Soft Start
- Available in SOT23-6
- -40°C to +85°C Temperature Range

Application

- Distributed Power Systems
- Digital Set Top Boxes
- Flat Panel Television and Monitors
- Wireless and DSL Modems
- Notebook Computer



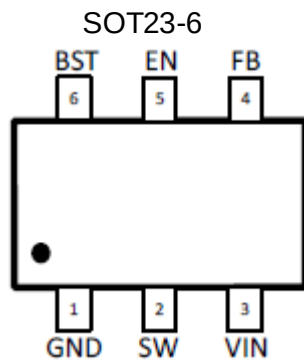
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Absolute Maximum Ratings

Parameter	Value
Supply Voltage V_{IN}	-0.3V to 19V
Switch Node Voltage V_{SW}	-0.3V to ($V_{IN}+0.5V$)
Boost Voltage V_{BST}	$V_{SW}-0.3V$ to $V_{SW}+5V$
Enable Voltage V_{EN}	-0.3V to 19V
All Other Pins	-0.3V to 6V
Operating Temperature Range	-40°C to 85°C
Storage Temperature Range	-65°C to 150°C
Lead Temperature (Soldering, 10s)	300°C

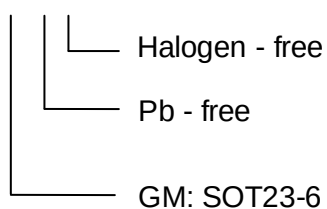
Packaging Type



Pin NO.	Description	Function
1	GND	Ground
2	SW	Switching Pin
3	VIN	Power supply Pin
4	FB	Adjustable version feedback input. Connect FB to the center point of the external resistor divider.
5	EN	Drive this pin to a logic-high to enable the IC. Drive to a logic-low to disable the IC and enter micro-power shutdown mode.
6	BST	Bootstrap. A capacitor connected between SW and BST pins is required to form a floating supply across the high-side switch driver.

Ordering information

ACE726C XX+ H





Typical Application

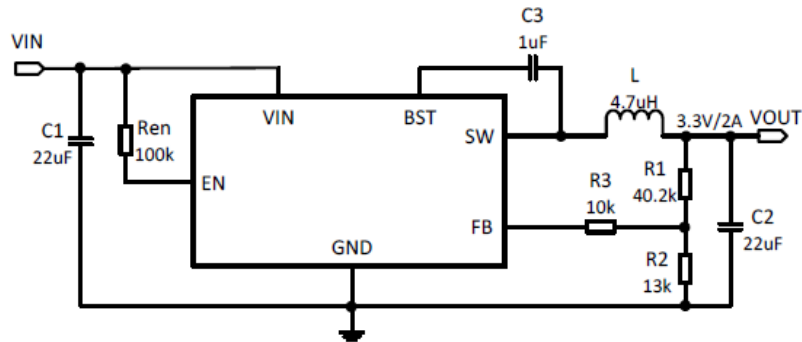


Figure 1.

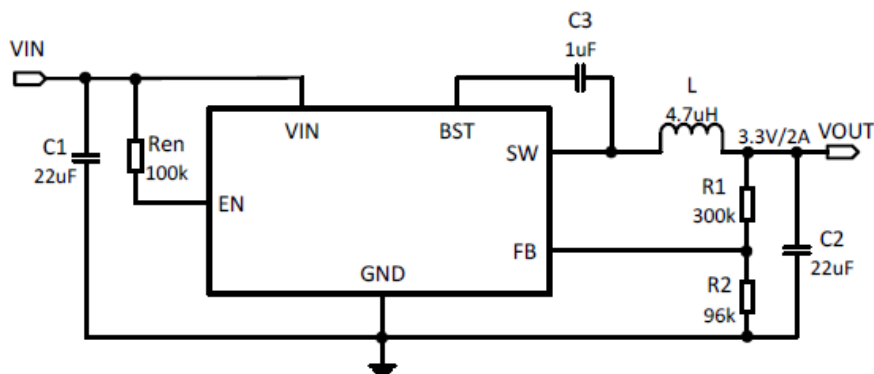
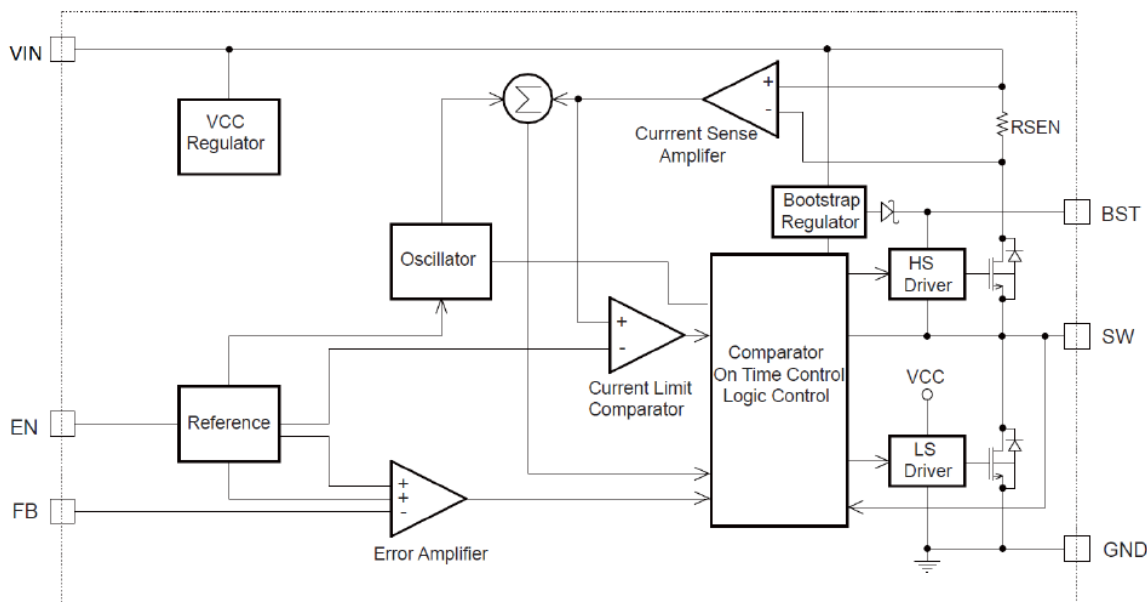


Figure 2.

Note:

1. C1 and C2 recommended using 22uF ceramic capacitors. If the electrolytic capacitor is used, it is recommended that the ceramic capacitor in parallel with a capacitance value of 0.1uF or more.
2. The resistance R3 in Figure 1 makes the loop more stable. If it isn't used, the resistance R1 、 R2 should be adjusted(See Figure2.). The value of R1 is recommended to be about 300kΩ.
3. C3 can be valued as 1uF, 0.1uF.

Block Diagram





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Electrical Characteristics

($V_{IN}=12V$, $V_{OUT}=5V$, $T_A=25^{\circ}C$, unless otherwise stated)

Parameter	Conditions	Min	Typ	Max	Unit
Input Voltage Range		4.2		18	V
UVLO Threshold			4.1		V
Supply Current in Operation	$V_{EN} = 2.0V$, $V_{FB} = 1.1V$		0.5		mA
Supply Current in Shutdown	$V_{EN} = 0V$ or $V_{EN} = GND$		5	10	uA
Regulated Feedback Voltage	$4.2V \leq V_{IN} \leq 18V$	0.784	0.8	0.816	V
High-side Switch On Resistance	$V_{BST-SW} = 5V$		150		m Ω
Low-side Switch On Resistance	$V_{IN} = 5V$		70		m Ω
High-side Switch Leakage Current	$V_{EN} = 0V$, $V_{SW} = 0V$		0	10	uA
Upper Switch Current Limit	Minimum Duty Cycle		3		A
Oscillation Frequency			500		KHz
Maximum Duty Cycle	$V_{FB} = 0.7V$		92		%
Minimum On Time			100		ns
EN Input Voltage "H"		1.5			V
EN Input Voltage "L"				0.6	V
Thermal Shutdown			160		$^{\circ}C$



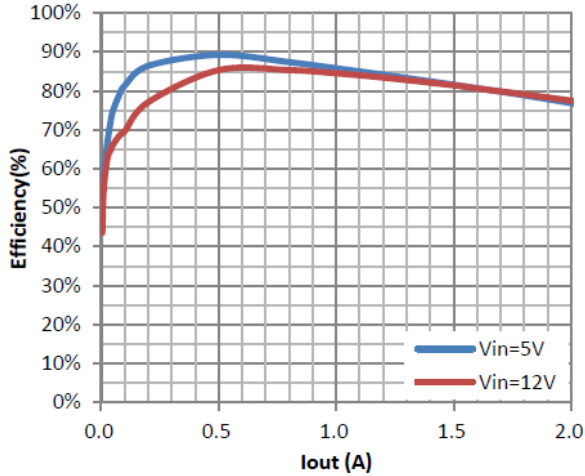
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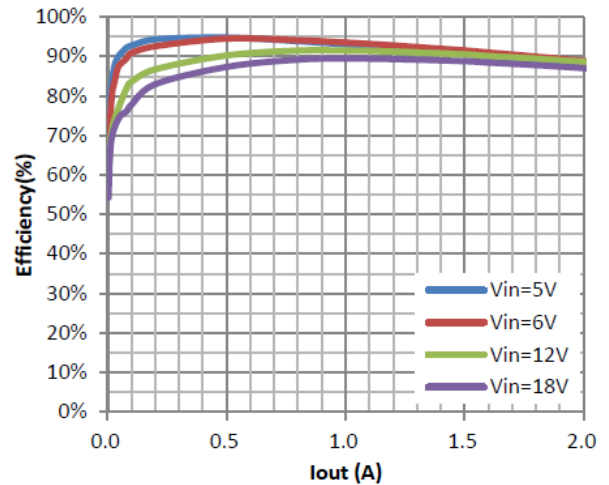
Electrical Performance

Tested under, $L=4.7\mu\text{H}$, $T_A=25^\circ\text{C}$, unless otherwise specified

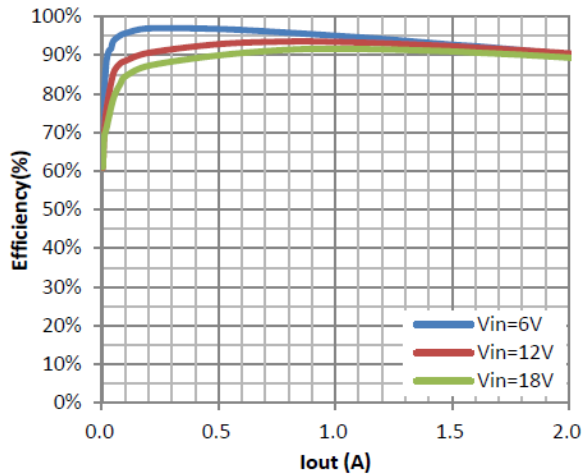
Efficiency vs. I_{out}
($V_{\text{out}}=1.2\text{V}$)



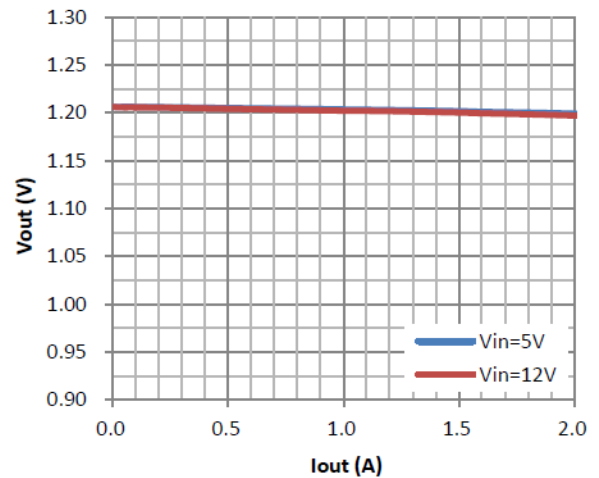
Efficiency vs. I_{out}
($V_{\text{out}}=3.3\text{V}$)



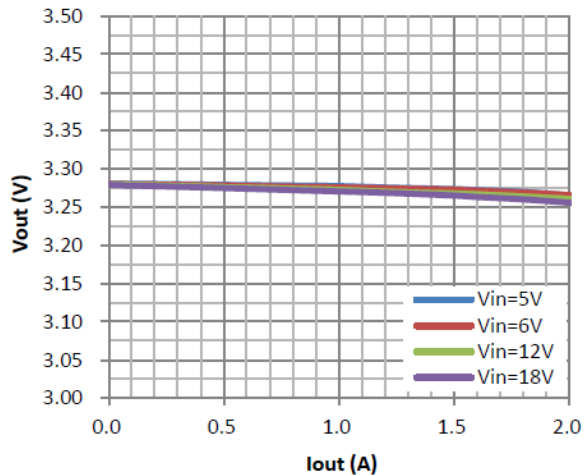
Efficiency vs. I_{out}
($V_{\text{out}}=5.0\text{V}$)



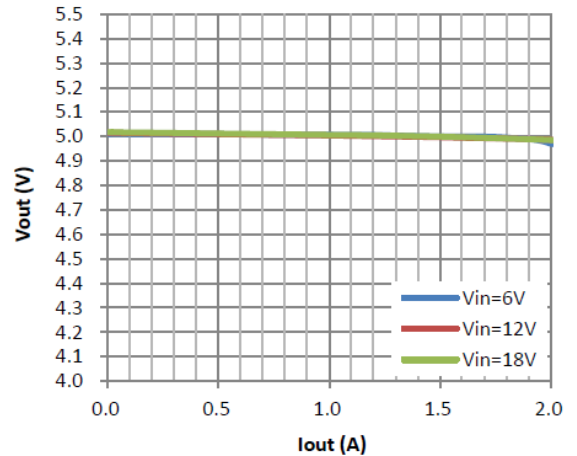
V_{out} vs. I_{out}
($V_{\text{out}}=1.2\text{V}$)



V_{out} vs. I_{out}
($V_{\text{out}}=3.3\text{V}$)



V_{out} vs. I_{out}
($V_{\text{out}}=5.0\text{V}$)

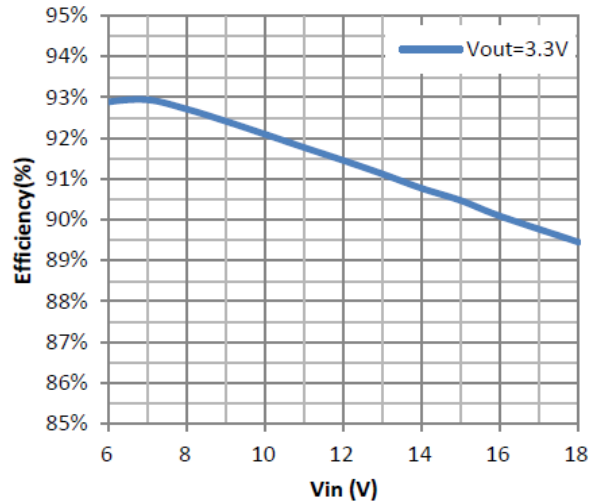




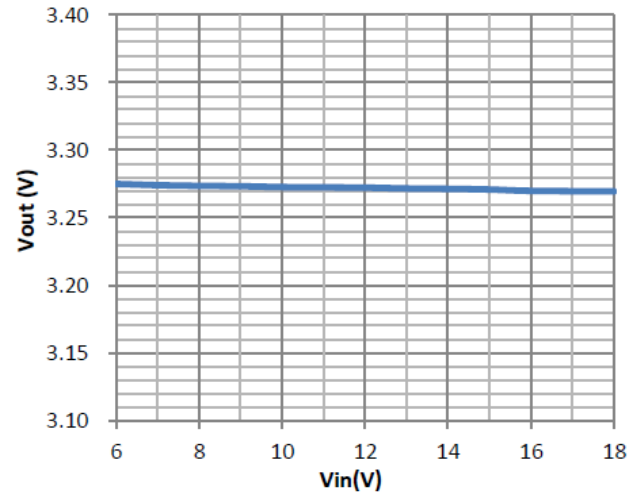
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Efficiency vs. Vin
 $I_{out}=1A$

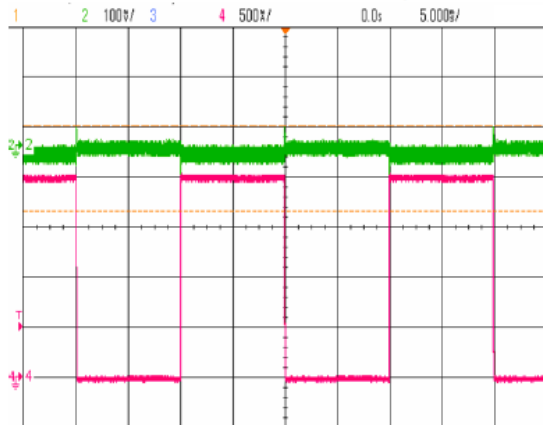


Vout vs. Vin
 $I_{out}=1A$



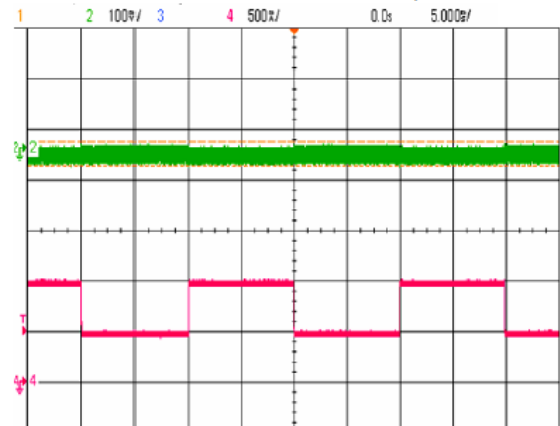
Load Transient

$V_{in}=12V$, $V_{out}=3.3V$, $I_{out}=0.01\sim 2A$
Ch2—Vout, Ch4--IL



Load Transient

$V_{in}=12V$, $V_{out}=3.3V$, $I_{out}=0.5\sim 1A$
Ch2—Vout, Ch4--IL





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Detailed Description

Internal Regulator

The ACE726C is a current mode step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains an internal, low resistance, high voltage power MOSFET, and operates at a high 500K operating frequency to ensure a compact, high efficiency design with excellent AC and DC performance.

Error Amplifier

The error amplifier compares the FB pin voltage with the internal FB reference (V_{FB}) and outputs a current proportional to the difference between the two. This output current is then used to charge or discharge the internal compensation network to form the COMP voltage, which is used to control the power MOSFET current. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

Internal Soft-Start

The soft-start is important for many applications because it eliminates power-up initialization problems. The controlled voltage ramp of the output also reduces peak inrush current during start-up, minimizing start-up transient events to the input power bus.

Over-Current-Protection and Hiccup

The ACE726C has a cycle-by-cycle over-current limit for when the inductor current peak value exceeds the set current-limit threshold. First, when the output voltage drops until FB falls below the Under-Voltage (UV) threshold (typically 140mV) to trigger a UV event, the ACE726C enters hiccup mode to periodically restart the part. This protection mode is especially useful when the output is dead-shortened to ground. This greatly reduces the average short-circuit current to alleviate thermal issues and to protect the regulator. The ACE726C exits hiccup mode once the overcurrent condition is removed.

Startup and Shutdown

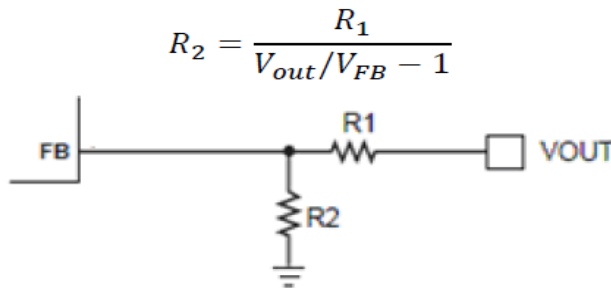
If both VIN and EN are higher than their appropriate thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip: EN low, VIN low and thermal shutdown. In the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.



Applications Information

Setting Output Voltages

The external resistor divider is used to set the output voltage (see Typical Application on page 1). The feedback resistor R1 also sets the feedback loop bandwidth with the internal compensation capacitor. Choose R1 to be around 300kΩ for optimal transient response. R2 is then given by:



Selecting the Inductor

Use a 2.2μH-to-10μH inductor with a DC current rating of at least 25% percent higher than the maximum load current for most applications. For highest efficiency, select an inductor with a DC resistance less than 15mΩ. For most designs, derive the inductance value from the following equation.

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times f_{osc}}$$

Where ΔIL is the inductor ripple current. Choose an inductor current approximately 30% of the maximum load current. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light-load conditions (below 100mA), use a larger inductor to improve efficiency.

Selecting the Output Capacitor

The output capacitor (C2) maintains the DC output voltage. Use ceramic, tantalum, or low- ESR electrolytic capacitors. Use low ESR capacitors to limit the output voltage ripple. Estimate the output voltage ripple with:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_S \times L} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right] \times \left[R_{ESR} + \frac{1}{8 \times f_S \times C_2} \right]$$



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Where L is the inductor value and $RESR$ is the equivalent series resistance (ESR) of the output capacitor. For ceramic capacitors, the capacitance dominates the impedance at the switching frequency and causes most of the output voltage ripple. For simplification, estimate the output voltage ripple with:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L \times C_2} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right]$$

For tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated with:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left[1 - \frac{V_{OUT}}{V_{IN}} \right] \times R_{ESR}$$

The characteristics of the output capacitor also affect the stability of the regulation system. The ACE726C can be optimized for a wide range of capacitance and ESR values.



Packing Information

Technical drawing of a 6-pin D-subminiature connector. The drawing includes a top view, a side view, and a perspective view. The top view shows a rectangular body with six pins, numbered 1 to 6. Dimensions include overall width 2.9 ± 0.2 , pin pitch 1.9 ± 0.2 , and pin diameter 0.95 . The side view shows the height of the body (1.6 ± 0.2) and the total height (2.8 ± 0.3). The perspective view shows the front of the connector with dimensions 1.1 ± 0.2 , 0.8 ± 0.1 , 0 to 0.1 , 0.15 ± 0.1 / -0.05 , and 0.2 MIN. The drawing is labeled "6-PIN D-SUBMINIATURE" and "FIG. 1".



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Notes

ACE does not assume any responsibility for use as critical components in life support devices or systems without the express written approval of the president and general counsel of ACE Electronics Co., LTD. As sued herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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