8-BIT MICROCONTROLLER

Table of Contents-

1. GENERAL DESCRIPTION 4
2. FEATURES 5
3. PARTS INFORMATION LIST 6
   - 3.1 Lead Free (RoHS) Parts information list 6
4. PIN CONFIGURATION 7
5. PIN DESCRIPTION 8
6. FUNCTIONAL DESCRIPTION 9
   - 6.1 On-Chip Flash EPROM 9
   - 6.2 I/O Ports 9
   - 6.3 Serial I/O 9
   - 6.4 Timers 9
   - 6.5 Interrupts 9
   - 6.6 Data Pointers 10
   - 6.7 Architecture 10
     - 6.7.1 ALU 10
     - 6.7.2 Accumulator 10
     - 6.7.3 B Register 10
     - 6.7.4 Program Status Word: 10
     - 6.7.5 Scratch-pad RAM 11
     - 6.7.6 Stack Pointer 11
   - 6.8 Power Management 11
7. MEMORY ORGANIZATION 12
   - 7.1 Program Memory (on-chip Flash) 12
   - 7.2 Data Memory 12
   - 7.3 Register Map 13
   - 7.4 Working Registers 15
   - 7.5 Bit addressable Locations 15
   - 7.6 Stack 15
8. SPECIAL FUNCTION REGISTERS 16
9. INSTRUCTION SET 45
   - 9.1 Instruction Timing 53
10. POWER MANAGEMENT 56
    - 10.1 Idle Mode 56
    - 10.2 Power Down Mode 56
11. RESET CONDITIONS 57
    - 11.1 Sources of reset 57
      - 11.1.1 External Reset 57

11.1.2 Power-On Reset (POR) 57
11.1.3 Watchdog Timer Reset 57
11.2 Reset State 57
12. INTERRUPTS 60
12.1 Interrupt Sources 60
12.2 Priority Level Structure 62
12.3 Response Time 63
12.4 Interrupt Inputs 64
13. PROGRAMMABLE TIMERS/COUNTERS 66
13.1 Timer/Counters 0 & 1 66
13.1.1 Time-Base Selection 66
13.1.2 Mode 0 66
13.1.3 Mode 1 67
13.1.4 Mode 2 68
13.1.5 Mode 3 68
14. NVM MEMORY 70
15. WATCHDOG TIMER 71
15.1 WATCHDOG CONTROL 72
15.2 CLOCK CONTROL of Watchdog 73
16. SERIAL PORT (UART) 74
16.1 MODE 0 74
16.2 MODE 1 75
16.3 MODE 2 77
16.4 MODE 3 78
16.5 Framing Error Detection 79
16.6 Multiprocessor Communications 79
17. TIME ACCESS PROCTECTION 81
18. KEYBOARD INTERRUPT (KBI) 83
19. ANALOG COMPARATORS 84
20. I/O PORT CONFIGURATION 85
20.1 Quasi-Bidirectional Output Configuration 85
20.2 Open Drain Output Configuration 86
20.3 Push-Pull Output Configuration 87
20.4 Input Only Configuration 87
21. OSCILLATOR 88
21.1 On-Chip RC Oscillator Option 88
21.2 External Clock Input Option 88
21.3 CPU Clock Rate select 89
22. POWER MONITORING FUNCTION 90
22.1 Power On Detect 90
22.2 Brownout Detect 90
23. PULSE-WIDTH-MODULATED (PWM) OUTPUTS 91

24. I2C SERIAL CONTROL 95
24.1 SIO Port 95
24.2 The I2C Control Registers: 96
24.2.1 The Address Registers, I2ADDR 96
24.2.2 The Data Register, I2DAT 96
24.2.3 The Control Register, I2CON 97
24.2.4 The Status Register, I2STATUS 97
24.2.5 The I2C Clock Baud Rate Bits, I2CLK 97
24.3 Modes of Operation 98
24.3.1 Master Transmitter Mode 98
24.3.2 Master Receiver Mode 98
24.3.3 Slave Receiver Mode 99
24.3.4 Slave Transmitter Mode 99
24.4 Data Transfer Flow in Five Operating Modes 99
25. ICP (IN-CIRCUIT PROGRAM) FLASH PROGRAM 105
26. CONFIG BITS 106
26.1 CONFIG1 106
26.2 CONFIG2 107
27. ELECTRICAL CHARACTERISTICS 108
27.1 Absolute Maximum Ratings 108
27.2 DC ELECTRICAL CHARACTERISTICS 108
27.3 The COMPARATOR ELECTRICAL CHARACTERISTICS 110
27.4 AC ELECTRICAL CHARACTERISTICS 110
27.5 EXTERNAL CLOCK CHARACTERISTICS 110
27.6 AC SPECIFICATION 111
27.7 TYPICAL APPLICATION CIRCUITS 111
28. PACKAGE DIMENSIONS 112
28.1 20L SOP-300mil 112
28.2 20L PDIP 300mil 113
29. REVISION HISTORY 114

1. GENERAL DESCRIPTION

The W79E804 series are an 8-bit Turbo 51 microcontroller which has an in-system programmable Flash EPROM which Flash EPROM can program by ICP (In Circuit Program) or by hardware writer. The instruction set of the W79E804 series are fully compatible with the standard 8052. The W79E804 series contain a **8K/4K/2K** bytes of main Flash EPROM; a **256** bytes of RAM; **256** bytes NVM Data Flash EPROM; two 8-bit bi-directional, one 2-bit bi-directional and bit-addressable I/O ports; two 16-bit timer/counters; 4-channel 10-bit PWM; two serial ports that include a I2C and an enhanced full duplex serial port. These peripherals are supported by 12 sources four-level interrupt capability. To facilitate programming and verification, the Flash EPROM inside the W79E804 series allow the program memory to be programmed and read electronically. Once the code is confirmed, the user can protect the code for security.

2. FEATURES

- Fully static design 8-bit Turbo 51 CMOS microcontroller up to 20MHz when VDD=4.5V to 5.5V, 12MHz when VDD=2.7V to 5.5V
- **8K/4K/2K** bytes of AP Flash EPROM, with ICP and external writer programmable mode.
- **256** bytes of on-chip RAM.
- **256** bytes NVM Data Flash EPROM for customer data storage used and 10K writer cycles.
- Instruction-set compatible with MSC-51.
- On-chip configurable RC oscillator (6MHz).
- Two 8-bit bi-directional and one 2-bit bi-directional ports.
- Two 16-bit timer/counters.
- 12 interrupts source with four levels of priority.
- One enhanced full duplex serial port with framing error detection and automatic address recognition.
- The 4 outputs mode and TTL/Schmitt trigger selectable Port.
- Programmable Watchdog Timer.
- Four-channel 10-bit PWM (Pulse Width Modulator).
- One I2C communication port (Master / Slave).
- Eight keypad interrupt inputs.
- Two analog comparators.
- Configurable on-chip oscillator.
- LED drive capability (20mA) on all port pins.
- Low Voltage Detect interrupt and reset.
- Development Tools:
  - JTAG ICE(In Circuit Emulation) tool
  - ICP(In Circuit Programming) writer
- Packages:
  - Lead Free (RoHS) DIP 20: W79E804ADG
  - Lead Free (RoHS) SOP 20: W79E804ASG
  - Lead Free (RoHS) DIP 20: W79E803ADG
  - Lead Free (RoHS) SOP 20: W79E803ASG
  - Lead Free (RoHS) DIP 20: W79E802ADG
  - Lead Free (RoHS) SOP 20: W79E802ASG

3. PARTS INFORMATION LIST

3.1 Lead Free (RoHS) Parts information list

PART NO.	EPROM FLASH SIZE	RAM	NVM FLASH EPROM	PWM	PACKAGE	REMARK
W79E804ADG	8KB	256B	256B	4x10Bit	DIP-20 Pin	
W79E804ASG	8KB	256B	256B	4x10Bit	SOP-20 Pin	
W79E803ADG	4KB	256B	256B	4x10Bit	DIP-20 Pin	
W79E803ASG	4KB	256B	256B	4x10Bit	SOP-20 Pin	
W79E802ADG	2KB	256B	256B	4x10Bit	DIP-20 Pin	
W79E802ASG	2KB	256B	256B	4x10Bit	SOP-20 Pin	

Table 3-1: Lead Free (RoHS) Parts information list

4. PIN CONFIGURATION

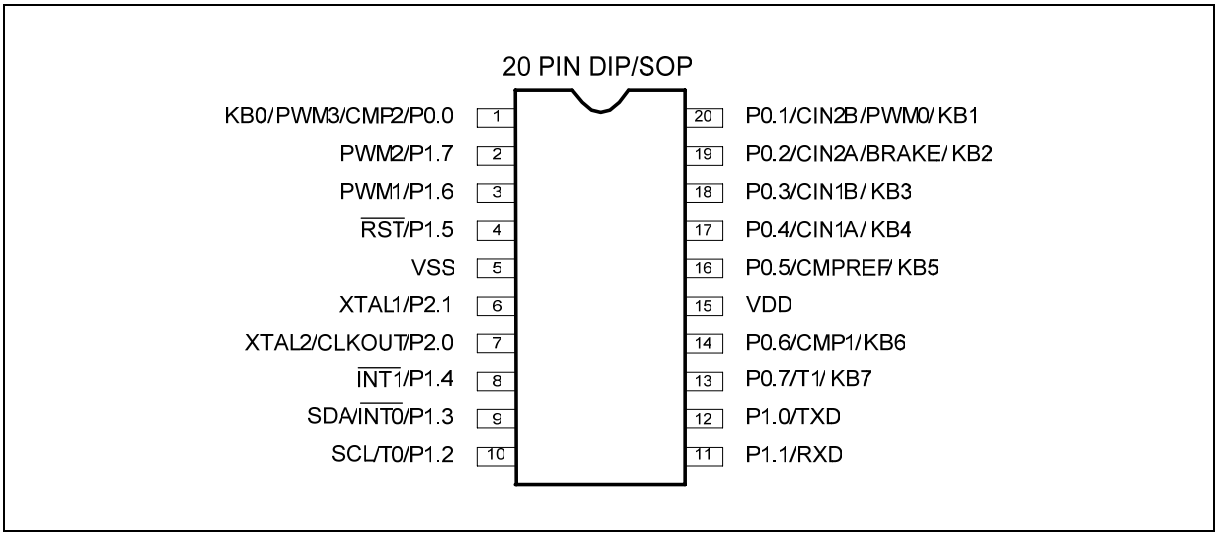


Figure 4-1: Pin Configuration

5. PIN DESCRIPTION

SYMBOL	TYPE	DESCRIPTIONS
$\overline{\text{RST}}$ (P1.5)	I	RESET: A low on this pin for two machine cycles while the oscillator is running resets the device.
XTAL1(P2.1)	I/O	CRYSTAL1: This is the crystal oscillator input. This pin may be driven by an external clock or configurable I/O pin.
XTAL2(P2.0)	I/O	CRYSTAL2: This is the crystal oscillator output. It is the inversion of XTAL1 or configurable I/O pin.
VSS	P	GROUND: Ground potential
VDD	P	POWER: SUPPLY: Supply voltage for operation.
P0.0–P0.7	I/O	PORT 0: Port 0 is four mode output pin and two mode input.
P1.0–P1.7	I/O	PORT 1: Port 1 is four mode output pin and two mode input. The P1.2 (SCL) and P1.3 (SDA) is only open drain circuit, and P1.5 only input pin.

* **TYPE:** P: power, I: input, O: output, I/O: bi-directional, H: pull-high, L: pull-low, D: open-drain**.**

Table 5-1: Pin Description

6. FUNCTIONAL DESCRIPTION

The W79E804 series architecture consist of a 4T 8051 core controller surrounded by various registers, **8K/4K/2K** bytes Flash EPROM, **256** bytes of RAM, **256** bytes NVM Data Flash EPROM, three general purpose I/O ports, two timer/counters, one serial port, one I2C serial I/O, 4 channel PWM with 10-bit counter, Flash EPROM program by Writer and ICP.

6.1 On-Chip Flash EPROM

The W79E804 series include one **8K/4K/2K** bytes of main Flash EPROM for application program. A Writer or ICP programming board is required to program the Flash EPROM or NVM Data Flash EPROM.

This ICP (In-Circuit Programming) feature makes the job easy and efficient when the application's firmware needs to be updated frequently. In some applications, the in-circuit programming feature makes it possible for the end-user to easily update the system firmware without opening the chassis.

6.2 I/O Ports

The W79E804 series have two 8-bit and one 2-bit port, up to 18 I/O pins using on-chip oscillator & /RST is input only by reset options. All ports can be used as four outputs mode when it may set by PxM1.y and PxM2.y SFR's registers, it has strong pull-ups and pull-downs, and does not need any external pull-ups. Otherwise it can be used as general I/O port as open drain circuit. All ports can be used bi-directional and these are as I/O ports. These ports are not true I/O, but rather are pseudo-I/O ports. This is because these ports have strong pull-downs and weak pull-ups.

6.3 Serial I/O

The W79E804 series have one serial port that is functionally similar to the serial port of the original 8032 family. However the serial port on the W79E804 series can operate in different modes in order to obtain timing similarity as well. The Serial port has the enhanced features of Automatic Address recognition and Frame Error detection.

6.4 Timers

The W79E804 series have two 16-bit timers that are functionally and similar to the timers of the 8052 family. When used as timers, the user has a choice of 12 or 4 clocks per count that emulates the timing of the original 8052.

6.5 Interrupts

The Interrupt structure in the W79E804 series is slightly different from that of the standard 8052. Due to the presence of additional features and peripherals, the number of interrupt sources and vectors has been increased.

6.6 Data Pointers

The data pointers of W79E804 series are same as 8052 that has dual 16-bit Data Pointers (DPTR) by setting DPS bit at AUXR1.0. The figure of dual DPTR is as below diagram.

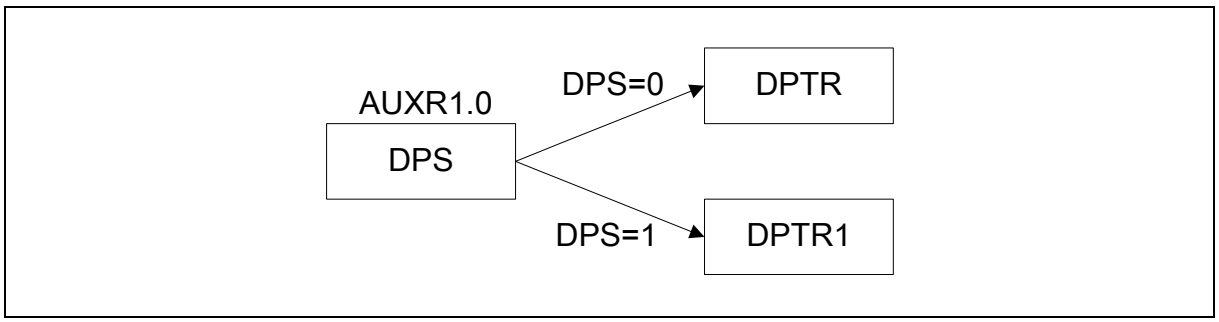


Figure 6-1: Dual DPTR

6.7 Architecture

The W79E804 series are based on the standard 8052 device. It is built around an 8-bit ALU that uses internal registers for temporary storage and control of the peripheral devices. It can execute the standard 8052 instruction set.

6.7.1 ALU

The ALU is the heart of the W79E804 series. It is responsible for the arithmetic and logical functions. It is also used in decision making, in case of jump instructions, and is also used in calculating jump addresses. The user cannot directly use the ALU, but the Instruction Decoder reads the op-code, decodes it, and sequences the data through the ALU and its associated registers to generate the required result. The ALU mainly uses the ACC which is a special function register (SFR) on the chip. Another SFR, namely B register is also used in Multiply and Divide instructions. The ALU generates several status signals which are stored in the Program Status Word register (PSW).

6.7.2 Accumulator

The Accumulator (ACC) is the primary register used in arithmetic, logical and data transfer operations in the W79E804 series. Since the Accumulator is directly accessible by the CPU, most of the high speed instructions make use of the ACC as one argument.

6.7.3 B Register

This is an 8-bit register that is used as the second argument in the MUL and DIV instructions. For all other instructions it can be used simply as a general purpose register.

6.7.4 Program Status Word:

This is an 8-bit SFR that is used to store the status bits of the ALU. It holds the Carry flag, the Auxiliary Carry flag, General purpose flags, the Register Bank Select, the Overflow flag, and the Parity flag.

6.7.5 Scratch-pad RAM

The W79E804 series have a **256** bytes on-chip scratch-pad RAM. These can be used by the user for temporary storage during program execution. A certain section of this RAM is bit addressable, and can be directly addressed for this purpose.

6.7.6 Stack Pointer

The W79E804 series have an 8-bit Stack Pointer which points to the top of the Stack. This stack resides in the Scratch Pad RAM in the W79E804 series. Hence the size of the stack is limited by the size of this RAM.

6.8 Power Management

Power Management like the standard 8052, the W79E804 series also have the IDLE and POWER DOWN modes of operation. In the IDLE mode, the clock to the CPU is stopped while the timers, serial ports and interrupt block continue to operate. In the POWER DOWN mode, all clocks are stopped and the chip operation is completely stopped. This is the lowest power consumption state.

7. MEMORY ORGANIZATION

The W79E804 series separate the memory into two separate sections, the Program Memory and the Data Memory. The Program Memory is used to store the instruction op-codes, while the Data Memory is used to store data or for memory mapped devices.

7.1 Program Memory (on-chip Flash)

The Program Memory on the W79E804 series can be up to **8K/4K/2K** bytes long. All instructions are fetched for execution from this memory area. The MOVC instruction can also access this memory region.

7.2 Data Memory

The NVM Data Memory of Flash EPROM on the W79E804 series can be up to **256** bytes long. The W79E804 series read the content of data memory by using “MOVC A, @A+DPTR”. To write data is by NVMADDR, NVMDAT and NVMCON SFR’s registers.

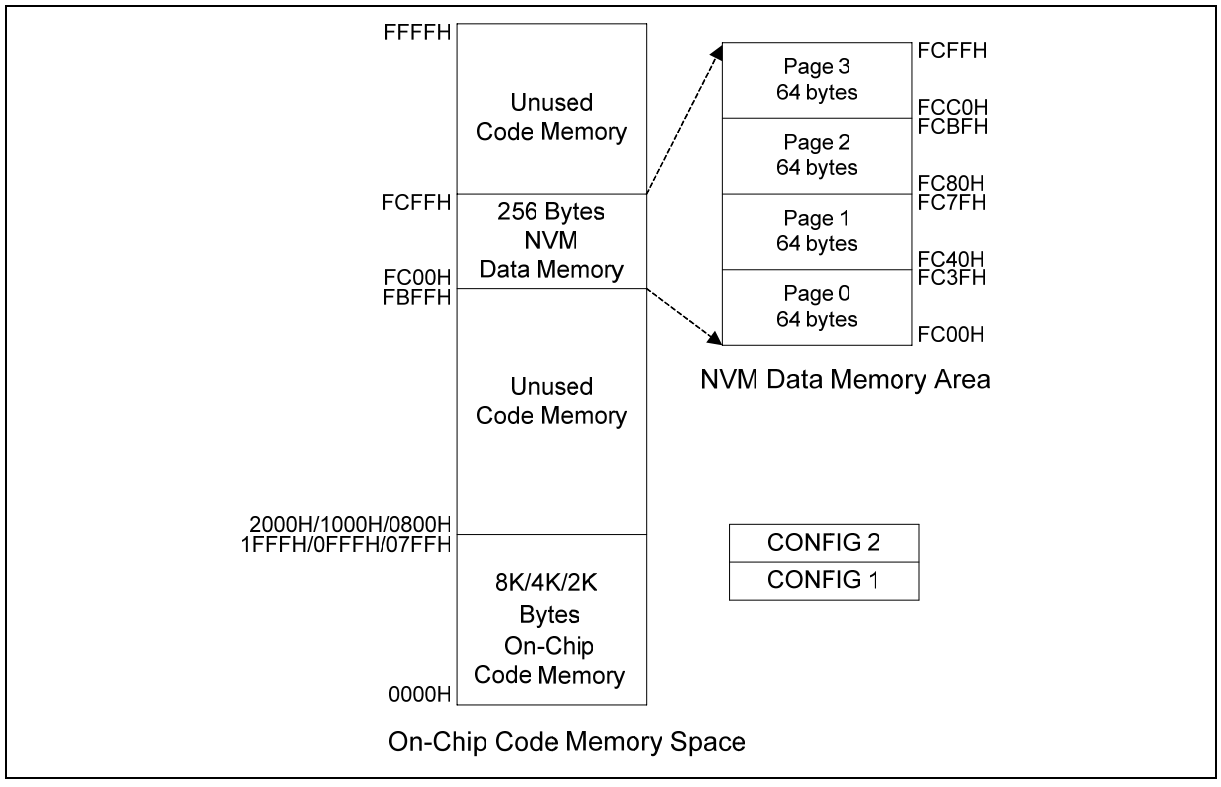


Figure 7-1: W79E804 series Memory Map

PART NO.	EPROM FLASH SIZE	ON-CHIP CODE MEMORY	
		START ADDRESS	END ADDRESS
W79E804	8KB	0000h	1FFFh
W79E803	4KB	0000h	0FFFh
W79E802	2KB	0000h	07FFh

Table 7-1: On-chip code memory address

7.3 Register Map

As mentioned before the W79E804 series have separate Program and Data Memory areas. The on-chip **256** bytes scratch pad RAM is in addition to the external memory. There are also several Special Function Registers (SFRs) which can be accessed by software. The SFRs can be accessed only by direct addressing, while the on-chip RAM can be accessed by either direct or indirect addressing.

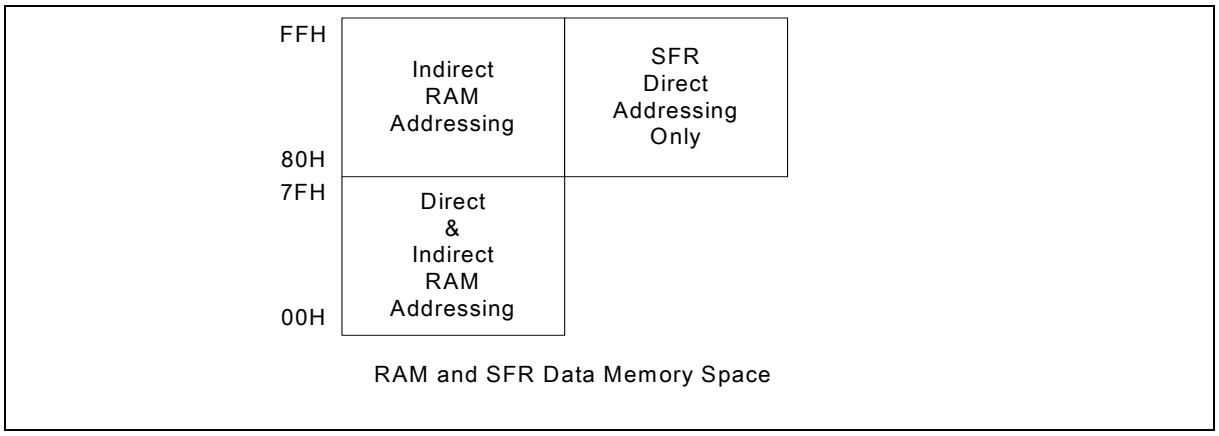


Figure 7-2: W79E804 series RAM and SFR memory map

Since the scratch-pad RAM is only **256** bytes it can be used only when data contents are small. There are several other special purpose areas within the scratch-pad RAM. These are described as follows.

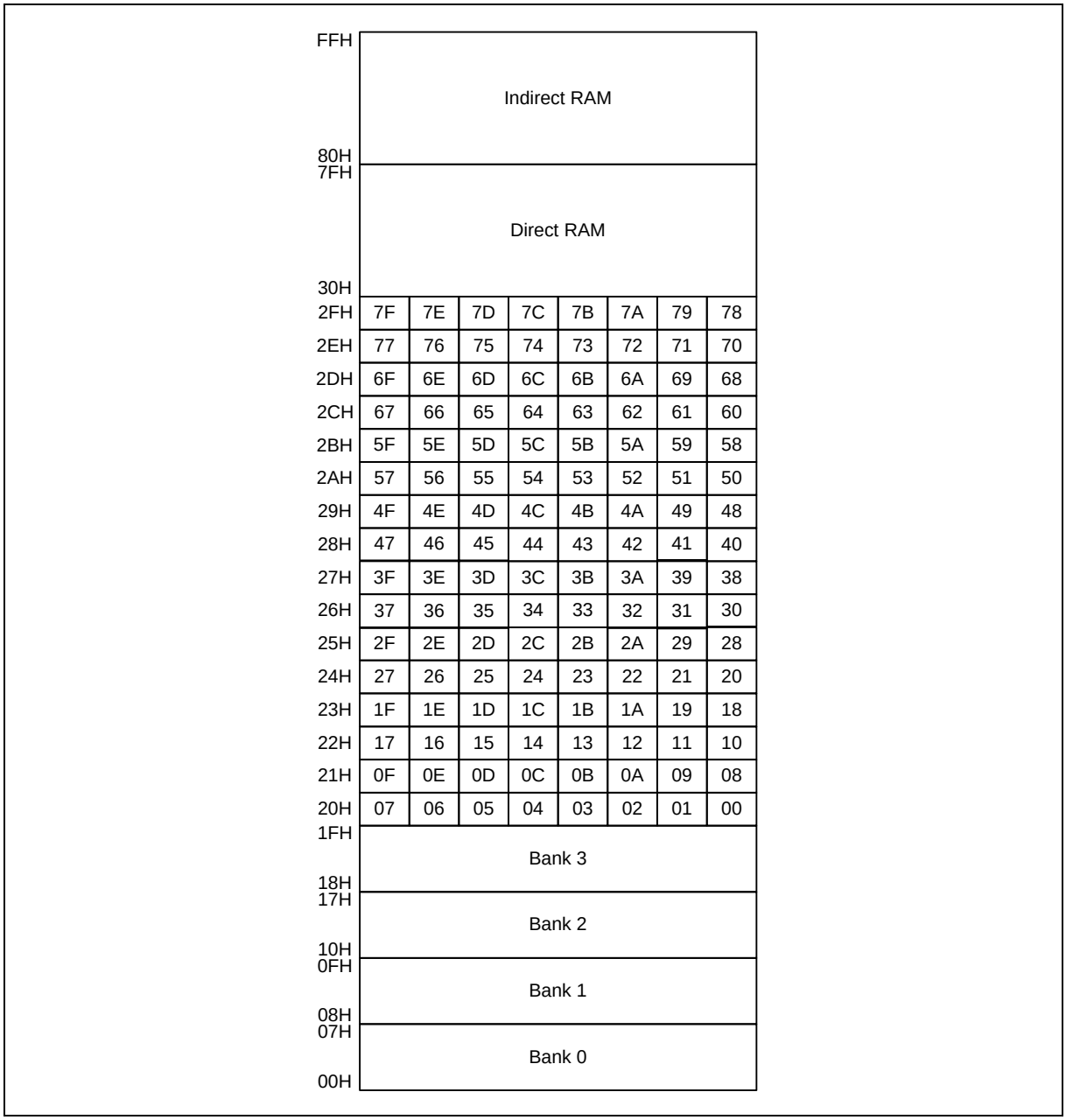


Figure 7-3: Scratch pad RAM

7.4 Working Registers

There are four sets of working registers, each consisting of eight 8-bit registers. These are termed as Banks 0, 1, 2, and 3. Individual registers within these banks can be directly accessed by separate instructions. These individual registers are named as R0, R1, R2, R3, R4, R5, R6 and R7. However, at one time the W79E804 series can work with only one particular bank. The bank selection is done by setting RS1-RS0 bits in the PSW. The R0 and R1 registers are used to store the address for indirect accessing.

7.5 Bit addressable Locations

The Scratch-pad RAM area from location 20h to 2Fh is byte as well as bit addressable. This means that a bit in this area can be individually addressed. In addition some of the SFRs are also bit addressable. The instruction decoder is able to distinguish a bit access from a byte access by the type of the instruction itself. In the SFR area, any existing SFR whose address ends in a 0 or 8 is bit addressable.

7.6 Stack

The scratch-pad RAM can be used for the stack. This area is selected by the Stack Pointer (SP), which stores the address of the top of the stack. Whenever a jump, call or interrupt is invoked the return address is placed on the stack. There is no restriction as to where the stack can begin in the RAM. By default however, the Stack Pointer contains 07h at reset. The user can then change this to any value desired. The SP will point to the last used value. Therefore, the SP will be incremented and then address saved onto the stack. Conversely, while popping from the stack the contents will be read first, and then the SP is decreased.

8. SPECIAL FUNCTION REGISTERS

The W79E804 series uses Special Function Registers (SFRs) to control and monitor peripherals and their Modes. The SFRs reside in the register locations 80-FFh and are accessed by direct addressing only. Some of the SFRs are bit addressable. This is very useful in cases where users wish to modify a particular bit without changing the others. The SFRs that are bit addressable are those whose addresses end in 0 or 8. The W79E804 series contain all the SFRs present in the standard 8052. However some additional SFRs are added. In some cases the unused bits in the original 8052, have been given new functions. The list of the SFRs is as follows.

F8	IP1							
F0	B						P0ID	IP1H
E8	EIE							
E0	ACC							
D8	WDCON	PWMPL	PWM0L	PWM1L	PWMCON1	PWM2L	PWM3L	PWMCON2
D0	PSW	PWMPH	PWM0H	PWM1H		PWM2H	PWM3H	PWMCON3
C8							NVMCON	NVMDAT
C0	I2CON	I2ADDR					NVMADDR	TA
B8	IP0	SADEN			I2DAT	I2STATUS	I2CLK	I2TIMER
B0		P0M1	P0M2	P1M1	P1M2	P2M1	P2M2	IP0H
A8	IE	SADDR			CMP1	CMP2		
A0	P2	KBI	AUXR1					
98	SCON	SBUF						
90	P1					DIVM		
88	TCON	TMOD	TL0	TL1	TH0	TH1	CKCON	
80	P0	SP	DPL	DPH				PCON

Table 8-1: Special Function Register Location Table

Note: 1. The SFRs in the column with dark borders are bit-addressable

2. The table is condensed with eight locations per row. Empty locations indicate that these are no registers at these addresses. When a bit or register is not implemented, it will read high.

SYMBOL	DEFINITION	ADDRESS	MSB	BIT_ADDRESS, SYMBOL						LSB	RESET
IP1	Interrupt priority 1	F8H	(FF) -	(FE) -	(FD) PPWM	(FC) PWDI	(FB) PC2	(FA) PC1	(F9) PKB	(F8) PI2	xx000000B
IP1H	Interrupt high priority 1	F7H	-	-	PPWMH	PWDIH	PC2H	PC1H	PKBH	PI2H	xx000000B
P0IDS	Port 0 Digital Input Disable	F6H									00000000B
B	B register	F0H	(F7)	(F6)	(F5)	(F4)	(F3)	(F2)	(F1)	(F0)	00000000B
EIE	External Interrupt enable	E8H	(EF) -	(EE) -	(ED) EPWM	(EC) EWDI	(EB) EC2	(EA) EC1	(E9) EKB	(E8) EI2	xx000000B
ACC	Accumulator	E0H	(E7)	(E6)	(E5)	(E4)	(E3)	(E2)	(E1)	(E0)	00000000B
PWMCON2	PWM control register 2	DFH	BKCH	BKPS	BPEN	BKEN	PWM3B	PWM2B	PWM1B	PWM0B	00000000B
PWM3L	PWM 3 low bits register	DEH	PWM3.7	PWM3.6	PWM3.5	PWM3.4	PWM3.3	PWM3.2	PWM3.1	PWM3.0	00000000B
PWM2L	PWM 2 low bits register	DDH	PWM2.7	PWM2.6	PWM2.5	PWM2.4	PWM2.3	PWM2.2	PWM2.1	PWM2.0	00000000B
PWMCON1	PWM control register 1	DCH	PWMRUN	load	CF	CLRPWM	PWM3I	PWM2I	PWM1I	PWM0I	00000000B
PWM1L	PWM 1 low bits register	DBH	PWM1.7	PWM1.6	PWM1.5	PWM1.4	PWM1.3	PWM1.2	PWM1.1	PWM1.0	00000000B
PWM0L	PWM 0 low bits register	DAH	PWM0.7	PWM0.6	PWM0.5	PWM0.4	PWM0.3	PWM0.2	PWM0.1	PWM0.0	00000000B
PWMPL	PWM counter low register	D9H	PWMP0.7	PWMP0.6	PWMP0.5	PWMP0.4	PWMP0.3	PWMP0.2	PWMP0.1	PWMP0.0	00000000B
WDCON	Watch-Dog control	D8H	(DF) WDRUN	(DE) -	(DD) WD1	(DC) WD0	(DB) WDIF	(DA) WTRF	(D9) EWRST	(D8) WDCLR	0x000000B
PWMCON3	PWM control register 3	D7H	-	-	-	-	-	-	-	BKF	xxxxxxx0B
PWM3H	PWM 3 high bits register	D6H	-	-	-	-	-	-	PWM3.9	PWM3.8	xxxxxx00B
PWM2H	PWM 2 high bits register	D5H	-	-	-	-	-	-	PWM2.9	PWM2.8	xxxxxx00B
PWM1H	PWM 1 high bits register	D3H	-	-	-	-	-	-	PWM1.9	PWM1.8	xxxxxx00B
PWM0H	PWM 0 high bits register	D2H	-	-	-	-	-	-	PWM0.9	PWM0.8	xxxxxx00B
PWMPH	PWM counter high register	D1H	-	-	-	-	-	-	PWMP0.9	PWMP0.8	xxxxxx00B
PSW	Program status word	D0H	(D7) CY	(D6) AC	(D5) F0	(D4) RS1	(D3) RS0	(D2) OV	(D1) F1	(D0) P	00000000B
NVMDATA	NVM Data	CFH									00000000B
NVMCON	NVM Control	CEH	EER	EWR	-	-	-	-	-	-	00000000B
TA	Timed Access Protection	C7H	TA.7	TA.6	TA.5	TA.4	TA.3	TA.2	TA.1	TA.0	00000000B
NVMADDR	NVM address	C6H									00000000B
I2ADDR	I2C address1	C1H	ADDR.7	ADDR.6	ADDR.5	ADDR.4	ADDR.3	ADDR.2	ADDR.1	GC	xxxxxxx0B
I2CON	I2C Control register	C0H	(CF) -	(CE) ENS1	(CD) STA	(CC) STO	(CB) SI	(CA) AA	(C9) -	(C8) -	x00000xxB
I2TIMER	I2C Timer Counter register	BFH	-	-	-	-	-	ENTI	DIV4	TIF	00000000B
I2CLK	I2C Clock Rate	BEH	I2CLK.7	I2CLK.6	I2CLK.5	I2CLK.4	I2CLK.3	I2CLK.2	I2CLK.1	I2CLK.0	00000000B
I2STATUS		BDH									00000000B
I2DAT		BCH	I2DAT.7	I2DAT.6	I2DAT.5	I2DAT.4	I2DAT.3	I2DAT.2	I2DAT.1	I2DAT.0	xxxxxxxxB
SADEN	Slave address mask	B9H									00000000B
IP0	Interrupt priority	B8H	(BF) -	(BE) -	(BD) PBO	(BC) PS	(BB) PT1	(BA) PX1	(B9) PT0	(B8) PX0	xx000000B
IP0H	Interrupt high priority	B7H	-	-	PBOH	PSH	PT1H	PX1H	PT0H	PX0H	xx000000B
P2M2	Port 2 output mode 2	B6H	-	-	-	-	-	-	P2M2.1	P2M2.0	xxxxxx00B
P2M1	Port 2 output mode 1	B5H	P2S	P1S	P0S	ENCLK	T1OE	T0OE	P2M1.1	P2M1.0	00000000B
P1M2	Port 1 output mode 2	B4H	P1M2.7	P1M2.6	-	P1M2.4	P1M2.3	P1M2.2	P1M2.1	P1M2.0	00000000B
P1M1	Port 1 output mode 1	B3H	P1M1.7	P1M1.6	-	P1M1.4	P1M1.3	P1M1.2	P1M1.1	P1M1.0	00000000B
P0M2	Port 0 output mode 2	B2H	P0M2.7	P0M2.6	P0M2.5	P0M2.4	P0M2.3	P0M2.2	P0M2.1	P0M2.0	00000000B
P0M1	Port 0 output mode 1	B1H	P0M1.7	P0M1.6	P0M1.5	P0M1.4	P0M1.3	P0M1.2	P0M1.1	P0M1.0	00000000B
CMP2	Comparator 2 control register	ADH	-	-	CE2	CP2	CN2	OE2	CO2	CMF2	00000000B
CMP1	Comparator 1 control register	ACH	-	-	CE1	CP1	CN1	OE1	CO1	CMF1	00000000B

Continued

SYMBOL	DEFINITION	ADDRESS	MSB			BIT_ADDRESS, SYMBOL				LSB	RESET
SADDR	Slave address	A9H									00000000B
IE	Interrupt enable	A8H	(AF) EA	(AE) -	(AD) EBO	(AC) ES	(AB) ET1	(AA) EX1	(A9) ET0	(A8) EX0	0x000000B
AUXR1	AUX function register	A2H	KBF	BOD	BOI	LPBOV	SRST	-	0	DPS	000x0x00B
KBI	Keyboard Interrupt	A1H									00000000B
P2	Port 2	A0H	(A7) -	(A6) -	(A5) -	(A4) -	(A3) -	(A2) -	(A1) XTAL1	(A0) XTAL2 CLKOUT	xxxxxx11B
SBUF	Serial buffer	99H									xxxxxxxxB
SCON	Serial control	98H	(9F) SM0/FE	(9E) SM1	(9D) SM2	(9C) REN	(9B) TB8	(9A) RB8	(99) TI	(98) RI	00000000B
DIVM	uC clock divide register	95H									00000000B
P1	Port 1	90H	(97) PWM2	(96) PWM1	(95) /RST	(94) /INT1	(93) /INT0 SDL	(92) T0 SCL	(91) RXD	(90) TXD	11111111B
CKCON	Clock control	8EH	-	-	-	T1M	T0M	-	-	-	xxx00xxxB
TH1	Timer high 1	8DH									00000000B
TH0	Timer high 0	8CH									00000000B
TL1	Timer low 1	8BH									00000000B
TL0	Timer low 0	8AH									00000000B
TMOD	Timer mode	89H	GATE	C/T	M1	M0	GATE	C/T	M1	M0	00000000B
TCON	Timer control	88H	(8F) TF1	(8E) TR1	(8D) TF0	(8C) TR0	(8B) IE1	(8A) IT1	(89) IE0	(88) IT0	00000000B
PCON	Power control	87H	SMOD	SMOD0	BOF	POR	GF1	GF0	PD	IDL	00xx0000B
DPH	Data pointer high	83H									00000000B
DPL	Data pointer low	82H									00000000B
SP	Stack pointer	81H									00000111B
P0	Port 0	80H	(87) T1 KB7	(86) CMP1 KB6	(85) CMPREF KB5	(84) CIN1A KB4	(83) CIN1B KB3	(82) BRAKE CIN2A KB2	(81) PWM0 CIN2B KB1	(80) PWM3 CMP2 KB0	11111111B

Table 8-2: Special Function Registers

PORT 0

Bit:	7	6	5	4	3	2	1	0
	P0.7	P0.6	P0.5	P0.4	P0.3	P0.2	P0.1	P0.0

Mnemonic: P0 Address: 80h

P0.7-0: General purpose Input/Output port. Most instructions will read the port pins in case of a port read access, however in case of read-modify-write instructions, the port latch is read. These alternate functions are described below:

BIT	NAME	FUNCTION
7	P0.7	Timer 1 pin or KB7 pin of keypad input.
6	P0.6	CMP1 pin of analog comparator or KB6 pin of keypad input.
5	P0.5	CMPREF pin of analog comparator or KB5 pin of keypad input.
4	P0.4	CIN1A pin of analog comparator or KB4 pin of keypad input.
3	P0.3	CIN1B pin of analog comparator or KB3 pin of keypad input.
2	P0.2	BRAKE pin of PWM or CIN2A pin of analog comparator or KB2 pin of keypad input.
1	P0.1	PWM0 pin or CIN2B pin of analog comparator or KB1 pin of keypad input.
0	P0.0	PWM3 pin or CMP2 pin of analog comparator or KB0 pin of keypad input.

Note: The initial value of the port is set by CONFIG1.PRHI bit. The default setting for CONFIG1.PRHI =1 which the alternative function output is turned on upon reset. If CONFIG1.PRHI is set to 0, the user has to write a 1 to port SFR to turn on the alternative function output.

STACK POINTER

Bit:	7	6	5	4	3	2	1	0
	SP.7	SP.6	SP.5	SP.4	SP.3	SP.2	SP.1	SP.0

Mnemonic: SP Address: 81h

BIT	NAME	FUNCTION
7-0	SP.[7:0]	The Stack Pointer stores the Scratch-pad RAM address where the stack begins. In other words it always points to the top of the stack.

DATA POINTER LOW

Bit:	7	6	5	4	3	2	1	0
	DPL.7	DPL.6	DPL.5	DPL.4	DPL.3	DPL.2	DPL.1	DPL.0

Mnemonic: DPL Address: 82h

BIT	NAME	FUNCTION
7-0	DPL.[7:0]	This is the low byte of the standard 8052 16-bit data pointer.

DATA POINTER HIGH

Bit:	7	6	5	4	3	2	1	0
	DPH.7	DPH.6	DPH.5	DPH.4	DPH.3	DPH.2	DPH.1	DPH.0

Mnemonic: DPH Address: 83h

BIT	NAME	FUNCTION
7-0	DPH.[7:0]	This is the high byte of the standard 8052 16-bit data pointer. This is the high byte of the DPTR 16-bit data pointer.

POWER CONTROL

Bit:	7	6	5	4	3	2	1	0
	SMOD	SMOD0	BOF	POR	GF1	GF0	PD	IDL

Mnemonic: PCON Address: 87h

BIT	NAME	FUNCTION
7	SMOD	1: This bit doubles the serial port baud rate in mode 1, 2, and 3.
6	SMOD0	0: Framing Error Detection Disable. SCON.7 (SM0/FE) bit is used as SM0 (standard 8052 function). 1: Framing Error Detection Enable. SCON.7 (SM0/FE) bit is used to reflect as Frame Error (FE) status flag.
5	BOF	0: Cleared by software. 1: Set automatically when a brownout reset or interrupt has occurred. Also set at power on.
4	POR	0: Cleared by software. 1: Set automatically when a power-on reset has occurred.
3	GF1	General purpose user flags.
2	GF0	General purpose user flags.
1	PD	1: The CPU goes into the POWER DOWN mode. In this mode, all the clocks are stopped and program execution is frozen.
0	IDL	1: The CPU goes into the IDLE mode. In this mode, the clocks CPU clock stopped, so program execution is frozen. But the clock to the serial, timer and interrupt blocks is not stopped, and these blocks continue operating.

TIMER CONTROL

Bit:	7	6	5	4	3	2	1	0
	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0

Mnemonic: TCON Address: 88h

BIT	NAME	FUNCTION
7	TF1	Timer 1 Overflow Flag. This bit is set when Timer 1 overflows. It is cleared automatically when the program does a timer 1 interrupt service routine. Software can also set or clear this bit.
6	TR1	Timer 1 Run Control. This bit is set or cleared by software to turn timer/counter on or off.
5	TF0	Timer 0 Overflow Flag. This bit is set when Timer 0 overflows. It is cleared automatically when the program does a timer 0 interrupt service routine. Software can also set or clear this bit.

Continued

BIT	NAME	FUNCTION
4	TR0	Timer 0 Run Control. This bit is set or cleared by software to turn timer/counter on or off.
3	IE1	Interrupt 1 Edge Detect Flag: Set by hardware when an edge/level is detected on $\overline{INT1}$. This bit is cleared by hardware when the service routine is vectored to only if the interrupt was edge triggered. Otherwise it follows the inverse of the pin.
2	IT1	Interrupt 1 Type Control. Set/cleared by software to specify falling edge/ low level triggered external inputs.
1	IE0	Interrupt 0 Edge Detect Flag. Set by hardware when an edge/level is detected on $\overline{INT0}$. This bit is cleared by hardware when the service routine is vectored to only if the interrupt was edge triggered. Otherwise it follows the inverse of the pin.
0	IT0	Interrupt 0 Type Control: Set/cleared by software to specify falling edge/ low level triggered external inputs.

TIMER MODE CONTROL

Bit:	7	6	5	4	3	2	1	0
	GATE	C/$\overline{T}$	M1	M0	GATE	C/$\overline{T}$	M1	M0
	TIMER1				TIMER0			

Mnemonic: TMOD Address: 89h

BIT	NAME	FUNCTION
7	GATE	Gating control: When this bit is set, Timer/counter 1 is enabled only while the $\overline{INT1}$ pin is high and the TR1 control bit is set. When cleared, the $\overline{INT1}$ pin has no effect, and Timer 1 is enabled whenever TR1 control bit is set.
6	C/$\overline{T}$	Timer or Counter Select: When clear, Timer 1 is incremented by the internal clock. When set, the timer counts falling edges on the T1 pin.
5	M1	Timer 1 mode select bit 1. See table below.
4	M0	Timer 1 mode select bit 0. See table below.
3	GATE	Gating control: When this bit is set, Timer/counter 0 is enabled only while the $\overline{INT0}$ pin is high and the TR0 control bit is set. When cleared, the $\overline{INT0}$ pin has no effect, and Timer 0 is enabled whenever TR0 control bit is set.
2	C/$\overline{T}$	Timer or Counter Select: When clear, Timer 0 is incremented by the internal clock. When set, the timer counts falling edges on the T0 pin.
1	M1	Timer 0 mode select bit 1. See table below.
0	M0	Timer 0 mode select bit 0. See table below.

M1, M0: Mode Select bits:

M1	M0	MODE
0	0	Mode 0: 8-bit timer/counter TLx serves as 5-bit pre-scale.
0	1	Mode 1: 16-bit timer/counter, no pre-scale.
1	0	Mode 2: 8-bit timer/counter with auto-reload from THx.
1	1	Mode 3: (Timer 0) TL0 is an 8-bit timer/counter controlled by the standard Timer0 control bits. TH0 is an 8-bit timer only controlled by Timer1 control bits. (Timer 1) Timer/Counter 1 is stopped.

TIMER 0 LSB

Bit:	7	6	5	4	3	2	1	0
	TL0.7	TL0.6	TL0.5	TL0.4	TL0.3	TL0.2	TL0.1	TL0.0

Mnemonic: TL0 Address: 8Ah

BIT	NAME	FUNCTION
7-0	TL0.[7:0]	Timer 0 LSB.

TIMER 1 LSB

Bit:	7	6	5	4	3	2	1	0
	TL1.7	TL1.6	TL1.5	TL1.4	TL1.3	TL1.2	TL1.1	TL1.0

Mnemonic: TL1 Address: 8Bh

BIT	NAME	FUNCTION
7-0	TL1.[7:0]	Timer 1 LSB.

TIMER 0 MSB

Bit:	7	6	5	4	3	2	1	0
	TH0.7	TH0.6	TH0.5	TH0.4	TH0.3	TH0.2	TH0.1	TH0.0

Mnemonic: TH0 Address: 8Ch

BIT	NAME	FUNCTION
7-0	TH0.[7:0]	Timer 0 MSB.

TIMER 1 MSB

Bit:	7	6	5	4	3	2	1	0
	TH1.7	TH1.6	TH1.5	TH1.4	TH1.3	TH1.2	TH1.1	TH1.0

Mnemonic: TH1 Address: 8Dh

BIT	NAME	FUNCTION
7-0	TH1.[7:0]	Timer 1 MSB.

CLOCK CONTROL

Bit:	7	6	5	4	3	2	1	0
	-	-	-	T1M	T0M	-	-	-

Mnemonic: CKCON Address: 8Eh

BIT	NAME	FUNCTION
7-5	-	Reserved.
4	T1M	Timer 1 clock select: 0: Timer 1 uses a divide by 12 clocks. 1: Timer 1 uses a divide by 4 clocks.
3	T0M	Timer 0 clock select: 0: Timer 0 uses a divide by 12 clocks. 1: Timer 0 uses a divide by 4 clocks.
2-0	-	Reserved.

PORT 1

Bit:	7	6	5	4	3	2	1	0
	P1.7	P1.6	P1.5	P1.4	P1.3	P1.2	P1.1	P1.0

Mnemonic: P1 Address: 90h

P1.7-0: General purpose Input/Output port. Most instructions will read the port pins in case of a port read access, however in case of read-modify-write instructions, the port latch is read. These alternate functions are described below:

BIT	NAME	FUNCTION
7	P1.7	PWM 2 Pin.
6	P1.6	PWM 1 Pin.
5	P1.5	/RST Pin or Input Pin by alternative.
4	P1.4	/INT1 interrupt.
3	P1.3	/INT0 interrupt or SDA of I2C.
2	P1.2	Timer 0 or SCL of I2C.
1	P1.1	RXD of Serial port.
0	P1.0	TXD of Serial port.

Note: The initial value of the port is set by CONFIG1.PRHI bit. The default setting for CONFIG1.PRHI =1 which the alternative function output is turned on upon reset. If CONFIG1.PRHI is set to 0, the user has to write a 1 to port SFR to turn on the alternative function output.

DIVIDER CLOCK

Bit:	7	6	5	4	3	2	1	0
	DIVM.7	DIVM.6	DIVM.5	DIVM.4	DIVM.3	DIVM.2	DIVM.1	DIVM.0

Mnemonic: DIVM Address: 95h

BIT	NAME	FUNCTION
7-0	DIVM.[7:0]	The DIVM register is clock divider of uC. Refer OSCILLATOR chapter.

SERIAL PORT CONTROL

Bit:	7	6	5	4	3	2	1	0
	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI

Mnemonic: SCON Address: 98h

BIT	NAME	FUNCTION
7	SM0/FE	Serial port mode select bit 0 or Framing Error Flag: The SMOD0 bit in PCON SFR determines whether this bit acts as SM0 or as FE. The operation of SM0 is described below. When used as FE, this bit will be set to indicate an invalid stop bit. This bit must be manually cleared in software to clear the FE condition.
6	SM1	Serial Port mode select bit 1. See table below.
5	SM2	Multiple processors communication. Setting this bit to 1 enables the multiprocessor communication feature in mode 2 and 3. In mode 2 or 3, if SM2 is set to 1, then RI will not be activated if the received 9th data bit (RB8) is 0. In mode 1, if SM2 = 1, then RI will not be activated if a valid stop bit was not received. In mode 0, the SM2 bit controls the serial port clock. If set to 0, then the serial port runs at a divide by 12 clock of the oscillator. This gives compatibility with the standard 8052. When set to 1, the serial clock become divide by 4 of the oscillator clock. This results in faster synchronous serial communication.
4	REN	Receive enable: 0: Disable serial reception. 1: Enable serial reception.
3	TB8	This is the 9th bit to be transmitted in modes 2 and 3. This bit is set and cleared by software as desired.
2	RB8	In modes 2 and 3 this is the received 9th data bit. In mode 1, if SM2 = 0, RB8 is the stop bit that was received. In mode 0 it has no function.
1	TI	Transmit interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or at the beginning of the stop bit in all other modes during serial transmission. This bit must be cleared by software.
0	RI	Receive interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or halfway through the stop bits time in the other modes during serial reception. However the restrictions of SM2 apply to this bit. This bit can be cleared only by software.

SM1, SM0: Mode Select bits:

MODE	SM1	SM0	DESCRIPTION	LENGTH	BAUD RATE
0	0	0	Synchronous	8	Tclk divided by 4 or 12
1	0	1	Asynchronous	10	Variable
2	1	0	Asynchronous	11	Tclk divided by 32 or 64
3	1	1	Asynchronous	11	Variable

SERIAL DATA BUFFER

Bit:	7	6	5	4	3	2	1	0
	SBUF.7	SBUF.6	SBUF.5	SBUF.4	SBUF.3	SBUF.2	SBUF.1	SBUF.0

Mnemonic: SBUF Address: 99h

BIT	NAME	FUNCTION
7-0	SBUF.[7:0]	Serial data on the serial port is read from or written to this location. It actually consists of two separate internal 8-bit registers. One is the receive resister, and the other is the transmit buffer. Any read access gets data from the receive data buffer, while write access is to the transmit data buffer.

PORT 2

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	P2.1	P2.0

Mnemonic: P2 Address: A0h

BIT	NAME	FUNCTION
7-2	-	Reserved
1	P2.1	XTAL1 clock input pin.
0	P2.0	XTAL2 or CLKOUT pin by alternative.

Note: The initial value of the port is set by CONFIG1.PRHI bit. The default setting for CONFIG1.PRHI =1 which the alternative function output is turned on upon reset. If CONFIG1.PRHI is set to 0, the user has to write a 1 to port SFR to turn on the alternative function output.

KEYBOARD INTERRUPT

Bit:	7	6	5	4	3	2	1	0
	KBI.7	KBI.6	KBI.5	KBI.4	KBI.3	KBI.2	KBI.1	KBI.0

Mnemonic: KBI Address: A1h

BIT	NAME	FUNCTION
7	KBI.7	1: Enable P0.7 as a cause of a Keyboard interrupt.
6	KBI.6	1: Enable P0.6 as a cause of a Keyboard interrupt.
5	KBI.5	1: Enable P0.5 as a cause of a Keyboard interrupt.
4	KBI.4	1: Enable P0.4 as a cause of a Keyboard interrupt.
3	KBI.3	1: Enable P0.3 as a cause of a Keyboard interrupt.
2	KBI.2	1: Enable P0.2 as a cause of a Keyboard interrupt.
1	KBI.1	1: Enable P0.1 as a cause of a Keyboard interrupt.
0	KBI.0	1: Enable P0.0 as a cause of a Keyboard interrupt.

AUX FUNCTION REGISTER 1

Bit:	7	6	5	4	3	2	1	0
	KBF	BOD	BOI	LPBOV	SRST	-	0	DPS

Mnemonic: AUXR1 Address: A2h

BIT	NAME	FUNCTION
7	KBF	Keyboard Interrupt Flag: 1: When any pin of port 0 that is enabled for the Keyboard Interrupt function goes low. Must be cleared by software.
6	BOD	Brown Out Disable: 0: Enable Brownout Detect function. 1: Disable Brownout Detect function and save power.
5	BOI	Brown Out Interrupt: 0: Disable Brownout Detect Interrupt function and it will cause chip reset when BOF is set. 1: This prevents Brownout Detection from causing a chip reset and allows the Brownout Detect function to be used as an interrupt.
4	LPBOV	Low Power Brown Out Detect control: 0: When BOD is enable, the Brown Out detect is always turned on by normal run or Power Down mode. 1: When BOD is enable, the Brown Out detect circuit is turned on by Power Down mode. This control can help save 15/16 of the Brownout circuit power. When uC is in Power Down mode, the BOD will enable internal RC OSC (2MHz~0.5MHZ)
3	SRST	Software reset: 1: reset the chip as if a hardware reset occurred.
2	-	Reserved.
1	0	Reserved.
0	DPS	Dual Data Pointer Select 0: To select DPTR of standard 8051. 1: To select DPTR1

INTERRUPT ENABLE

Bit:	7	6	5	4	3	2	1	0
	EA	-	EBO	ES	ET1	EX1	ET0	EX0

Mnemonic: IE Address: A8h

BIT	NAME	FUNCTION
7	EA	Global enable. Enable/Disable all interrupts.
6	-	Reserved.
5	EBO	Enable Brown Out interrupt.
4	ES	Enable Serial Port interrupt.
3	ET1	Enable Timer 1 interrupt.
2	EX1	Enable external interrupt 1.
1	ET0	Enable Timer 0 interrupt.
0	EX0	Enable external interrupt 0.

SLAVE ADDRESS

Bit:	7	6	5	4	3	2	1	0
	SADDR.7	SADDR.6	SADDR.5	SADDR.4	SADDR.3	SADDR.2	SADDR.1	SADDR.0

Mnemonic: SADDR Address: A9h

BIT	NAME	FUNCTION
7-0	SADDR.[7:0]	The SADDR should be programmed to the given or broadcast address for serial port to which the slave processor is designated.

COMPARATOR 1 CONTROL REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	CE1	CP1	CN1	OE1	CO1	CMF1

Mnemonic: CMP1 Address: ACh

BIT	NAME	FUNCTION
7	-	Reserved.
6	-	Reserved.
5	CE1	Comparator enable: 0: Disable Comparator. 1: Enabled Comparator. Comparator output need wait stable 10 us after CE1 is first set.
4	CP1	Comparator positive input select: 0: CIN1A is selected as the positive comparator input. 1: CIN1B is selected as the positive comparator input.
3	CN1	Comparator negative input select: 0: The comparator reference pin CMPREF is selected as the negative comparator input. 1: The internal comparator reference Vref is selected as the negative comparator input.

Continued

BIT	NAME	FUNCTION
2	OE1	Output enable: 1: The comparator output is connected to the CMP1 pin if the comparator is enabled (CE1 = 1). This output is asynchronous to the CPU clock.
1	CO1	Comparator output: Synchronized to the CPU clock to allow reading by software. Cleared when the comparator is disabled (CE1 = 0).
0	CMF1	Comparator interrupt flag: This bit is set by hardware whenever the comparator output CO1 changes state. This bit will cause a hardware interrupt if enabled and of sufficient priority. Cleared by software and when the comparator is disabled (CE1 = 0).

COMPARATOR 2 CONTROL REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	CE2	CP2	CN2	OE2	CO2	CMF2

Mnemonic: CMP2 Address: ADh

BIT	NAME	FUNCTION
7	-	Reserved.
6	-	Reserved.
5	CE2	Comparator enable: 0: Disable Comparator. 1: Enabled Comparator. Comparator output need wait stable 10 us after CE2 is first set.
4	CP2	Comparator positive input select: 0: CIN2A is selected as the positive comparator input. 1: CIN2B is selected as the positive comparator input.
3	CN2	Comparator negative input select: 0: The comparator reference pin CMPREF is selected as the negative comparator input. 1: The internal comparator reference Vref is selected as the negative comparator input.
2	OE2	Output enable: 1: The comparator output is connected to the CMP2 pin if the comparator is enabled (CE2 = 1). This output is asynchronous to the CPU clock.
1	CO2	Comparator output: Synchronized to the CPU clock to allow reading by software. Cleared when the comparator is disabled (CE2 = 0).
0	CMF2	Comparator interrupt flag: This bit is set by hardware whenever the comparator output CO2 changes state. This bit will cause a hardware interrupt if enabled and of sufficient priority. Cleared by software and when the comparator is disabled (CE2 = 0).

PORT 0 OUTPUT MODE 1

Bit:	7	6	5	4	3	2	1	0
	P0M1.7	P0M1.6	P0M1.5	P0M1.4	P0M1.3	P0M1.2	P0M1.1	P0M1.0

Mnemonic: P0M1 Address: B1h

BIT	NAME	FUNCTION
7-0	P0M1.[7:0]	To control the output configuration of P0 bits [7:0]

PORT 0 OUTPUT MODE 2

Bit:	7	6	5	4	3	2	1	0
	P0M2.7	P0M2.6	P0M2.5	P0M2.4	P0M2.3	P0M2.2	P0M2.1	P0M2.0

Mnemonic: P0M2 Address: B2h

BIT	NAME	FUNCTION
7-0	P0M2.[7:0]	To control the output configuration of P0 bits [7:0]

PORT 1 OUTPUT MODE 1

Bit:	7	6	5	4	3	2	1	0
	P1M1.7	P1M1.6	-	P1M1.4	P1M1.3	P1M1.2	P1M1.1	P1M1.0

Mnemonic: P1M1 Address: B3h

BIT	NAME	FUNCTION
7-0	P1M1.[7:0]	To control the output configuration of P1 bits [7:0]

PORT 1 OUTPUT MODE 2

Bit:	7	6	5	4	3	2	1	0
	P1M2.7	P1M2.6	-	P1M2.4	P1M2.3	P1M2.2	P1M2.1	P1M2.0

Mnemonic: P1M2 Address: B4h

BIT	NAME	FUNCTION
7-0	P1M2.[7:0]	To control the output configuration of P1 bits [7:0]

PORT 2 OUTPUT MODE 1

Bit:	7	6	5	4	3	2	1	0
	P2S	P1S	P0S	ENCLK	T1OE	T0OE	P2M1.1	P2M1.0

Mnemonic: P2M1 Address: B5h

BIT	NAME	FUNCTION
7	P2S	0: Disable Schmitt trigger inputs on port 2 and enable TTL inputs on port 2. 1: Enables Schmitt trigger inputs on Port 2.
6	P1S	0: Disable Schmitt trigger inputs on port 1 and enable TTL inputs on port 1. 1: Enables Schmitt trigger inputs on Port 1.
5	P0S	0: Disable Schmitt trigger inputs on port 0 and enable TTL inputs on port 0 1: Enables Schmitt trigger inputs on Port 0.
4	ENCLK	1: Enabled clock output to XTAL2 pin (P2.0)
3	T1OE	1: The P0.7 pin is toggled whenever Timer 1 overflows. The output frequency is therefore one half of the Timer 1 overflow rate.
2	T0OE	1: The P1.2 pin is toggled whenever Timer 0 overflows. The output frequency is therefore one half of the Timer 0 overflow rate.
1	P2M1.1	To control the output configuration of P2.1.
0	P2M1.0	To control the output configuration of P2.0.

PORT 2 OUTPUT MODE 2

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	P2M2.1	P2M2.0

Mnemonic: P2M2 Address: B6h

BIT	NAME	FUNCTION
7-2	-	Reserved.
1-0	P2M2.[1:0]	To control the output configuration of P2 bits [1:0]

Port Output Configuration Settings:

PXM1.Y	PXM2.Y	PORT INPUT/OUTPUT MODE
0	0	Quasi-bidirectional
0	1	Push-Pull
1	0	Input Only (High Impedance) P2M1.PxS=0, TTL input P2M1.PxS=1, Schmitt input
1	1	Open Drain

INTERRUPT HIGH PRIORITY

Bit:	7	6	5	4	3	2	1	0
	-	-	PBOH	PSH	PT1H	PX1H	PT0H	PX0H

Mnemonic: IP0H Address: B7h

BIT	NAME	FUNCTION
7	-	This bit is un-implemented and will read high.
6	-	Reserved.
5	PBOH	1: To set interrupt high priority of Brown Out Detector is highest priority level.
4	PSH	1: To set interrupt high priority of Serial port 0 is highest priority level.
3	PT1H	1: To set interrupt high priority of Timer 1 is highest priority level.
2	PX1H	1: To set interrupt high priority of External interrupt 1 is highest priority level.
1	PT0H	1: To set interrupt high priority of Timer 0 is highest priority level.
0	PX0H	1: To set interrupt high priority of External interrupt 0 is highest priority level.

INTERRUPT PRIORITY 0

Bit:	7	6	5	4	3	2	1	0
	-	-	PBO	PS	PT1	PX1	PT0	PX0

Mnemonic: IP Address: B8h

BIT	NAME	FUNCTION
7	-	This bit is un-implemented and will read high.
6	-	Reserved.
5	PBO	1: To set interrupt priority of Brown Out Detector is higher priority level.
4	PS	1: To set interrupt priority of Serial port 0 is higher priority level.
3	PT1	1: To set interrupt priority of Timer 1 is higher priority level.
2	PX1	1: To set interrupt priority of External interrupt 1 is higher priority level.
1	PT0	1: To set interrupt priority of Timer 0 is higher priority level.
0	PX0	1: To set interrupt priority of External interrupt 0 is higher priority level.

SLAVE ADDRESS MASK ENABLE

Bit:	7	6	5	4	3	2	1	0
	SADEN.7	SADEN.6	SADEN.5	SADEN.4	SADEN.3	SADEN.2	SADEN.1	SADEN.0

Mnemonic: SADEN Address: B9h

BIT	NAME	FUNCTION
7-0	SADEN [7:0]	This register enables the Automatic Address Recognition feature of the Serial port 0. When a bit in the SADEN is set to 1, the same bit location in SADDR will be compared with the incoming serial data. When SADEN is 0, then the bit becomes a "don't care" in the comparison. This register enables the Automatic Address Recognition feature of the Serial port 0. When all the bits of SADEN are 0, interrupt will occur for any incoming address.

SLAVE ADDRESS MASK ENABLE 1

Bit:	7	6	5	4	3	2	1	0
	I2DAT.7	I2DAT.6	I2DAT.5	I2DAT.4	I2DAT.3	I2DAT.2	I2DAT.1	I2DAT.0

Mnemonic: I2DAT Address: BCh

BIT	NAME	FUNCTION
7-0	I2DAT.[7:0]	The data register of I2C.

I2C STATUS REGISTER

Bit:	7	6	5	4	3	2	1	0
	I2STATUS.7	I2STATUS.6	I2STATUS.5	I2STATUS.4	I2STATUS.3	-	-	-

Mnemonic: I2STATUS Address: BDh

BIT	NAME	FUNCTION
7-0	I2STATUS.[7:0]	The status register of I2C: The three least significant bits are always 0. The five most significant bits contain the status code. There are 23 possible status codes. When I2STATUS contains F8H, no serial interrupt is requested. All other I2STATUS values correspond to defined I2C states. When each of these states is entered, a status interrupt is requested (SI = 1). A valid status code is present in I2STATUS one machine cycle after SI is set by hardware and is still present one machine cycle after SI has been reset by software. In addition, states 00H stands for a Bus Error. A Bus Error occurs when a START or STOP condition is present at an illegal position in the formation frame. Example of illegal position are during the serial transfer of an address byte, a data byte or an acknowledge bit.

I2C BAUD RATE CONTROL REGISTER

Bit:	7	6	5	4	3	2	1	0
	I2CLK.7	I2CLK.6	I2CLK.5	I2CLK.4	I2CLK.3	I2CLK.2	I2CLK.1	I2CLK.0

Mnemonic: I2CLK Address: BEh

BIT	NAME	FUNCTION
7-0	I2CLK.[7:0]	The I2C clock rate bits.

I2C TIMER COUNTER REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	ENTI	DIV4	TIF

Mnemonic: I2TIMER Address: BFh

BIT	NAME	FUNCTION
7~3	-	Reserved.
2	ENTI	Enable I2C 14-bits Timer Counter: 0: Disable 14-bits Timer Counter count. 1: Enable 14-bits Timer Counter count. After enable ENTI and ENSI, the 14-bit counter will be counted. When SI flag of I2C is set, the counter will stop to count and 14-bits Timer Counter will be cleared.
1	DIV4	I2C Timer Counter clock source divide function: 0: The 14-bits Timer Counter source clock is Fosc clock. 1: The 14-bits Timer Counter source clock is divided by 4.
0	TIF	The I2C Timer Counter count flag: 0: The 14-bits Timer Counter is not overflow. 1: The 14-bits Timer Counter is overflow. Before enable I2C Timer (both ENTI, ENSI = [1,1]) the SI must be cleared. If I2C interrupt is enabled. The I2C interrupt service routine will be executed. This bit is cleared by software.

I2C CONTROL REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	ENSI	STA	STO	SI	AA	-	-

Mnemonic: I2CON Address: C0h

BIT	NAME	FUNCTION
7	-	Reserved.
6	ENS1	0: Disable I2C Serial Function. The SDA and SCL output are in a high impedance state. SDA and SCL input signals are ignored, I2C is not in the addressed slave mode or it is not addressable, and STO bit in I2CON is forced to “0”. No other bits are affected. P1.2 (SCL) and P1.3 (SDA) may be used as open drain I/O ports. 1: Enable I2C Serial Function. The P1.2 and P1.3 port latches must be to logic 1.
5	STA	The START flag. 0: The STA bit is reset, no START condition or repeated START condition will be generated. 1: The STA bit is set to enter a master mode. The I2C hardware checks the status of I2C bus and generates a START condition if the bus is free. If bus is not free, then I2C waits for a STOP condition and generates a START condition after a delay. If STA is set while I2C is already in a master mode and one or more bytes are transmitted or received, I2C transmits a repeated START condition. STA may be set any time. STA may also be set when I2C interface is an addressed slave mode.

Continued

BIT	NAME	FUNCTION
4	STO	The bit STO bit is set while I2C is in a master mode. A STOP condition is transmitted to the I2C bus. When the STOP condition is detected on the bus, the I2C hardware clears the STO flag. In a slave mode, the STO flag may be set to recover from a bus error condition. In this case, no STOP condition is transmitted to the I2C bus. However, the I2C hardware behaves as if a STOP condition has been received and it switches to the not addressable slave receiver mode. The STO flag is automatically cleared by hardware. If the STA and STO bits are both set, then a STOP condition is transmitted to the I2C bus if I2C is in a master mode (in a slave mode, I2C generates an internal STOP condition which is not transmitted). I2C then transmits a START condition.
3	SI	0: When the SI flag is reset, no serial interrupt is requested, and there is no stretching on the serial clock on the SCL line. 1: When a new SIO state is present in the I2STATUS register, the SI flag is set by hardware, and, if the EA and ES bits (in IE register) are both set, a serial interrupt is requested when SI is set. The only state that does not cause SI to be set is state F8H, which indicates that no relevant state information is available. When SI is set, the low period of the serial clock on the SCL line is stretched, and the serial transfer is suspended. A high level on the SCL line is unaffected by the serial interrupt flag. SI must be cleared by software.
2	AA	The Assert Acknowledge Flag 0: A not acknowledge (high level to SDA) will be returned during the acknowledge clock pulse on SCL when: 1) A data has been received while SIO is in the master receiver mode. 2) A data byte has been received while SIO is in the addressed slave receiver mode. 1: An acknowledge (low level to SDA) will be returned during the acknowledge clock pulse on the SCL line when: 1) The own slave address has been received. 2) A data byte has been received while SIO is in the master receiver mode. 3) A data byte has been received while SIO is in the addressed slave receiver mode. 4) The General Call address has been received while the general call bit (GC) in I2ADDR is set.
1	-	Reserved.
0	-	Reserved.

I2C ADDRESS REGISTER

Bit:	7	6	5	4	3	2	1	0
	I2ADDR.7	I2ADDR.6	I2ADDR.5	I2ADDR.4	I2ADDR.3	I2ADDR.2	I2ADDR.1	GC

Mnemonic: I2ADDR Address: C1h

BIT	NAME	FUNCTION
7~1	I2ADDR.[7:1]	I2C Address register: The 8051 uC can read from and write to this 8-bit, directly addressable SFR. The content of this register is irrelevant when I2C is in master mode. In the slave mode, the seven most significant bits must be loaded with the MCU's own address. The I2C hardware will react if either of the address is matched.
0	GC	General Call Function. 0: Disable General Call Function. 1: Enable General Call Function.

NVM ADDRESS

Bit:	7	6	5	4	3	2	1	0
	NVMADDR.7	NVMADDR.6	NVMADDR.5	NVMADDR.4	NVMADDR.3	NVMADDR.2	NVMADDR.1	NVMADDR.0

Mnemonic: NVMADDR Address: C6h

BIT	NAME	FUNCTION
7~0	NVMADDR.[7:0]	The NVM address: The register indicates NVM data memory of low byte address on On-Chip code memory space.

TIMED ACCESS

Bit:	7	6	5	4	3	2	1	0
	TA.7	TA.6	TA.5	TA.4	TA.3	TA.2	TA.1	TA.0

Mnemonic: TA Address: C7h

BIT	NAME	FUNCTION
7-0	TA.[7:0]	The Timed Access register: The Timed Access register controls the access to protected bits. To access protected bits, the user must first write AAH to the TA. This must be immediately followed by a write of 55H to TA. Now a window is opened in the protected bits for three machine cycles, during which the user can write to these bits.

NVM CONTROL

Bit:	7	6	5	4	3	2	1	0
	EER	EWR	-	-	-	-	-	-

Mnemonic: NVMCON Address: CEh

BIT	NAME	FUNCTION
7	EER	NVM page(n) erase bit: 0: Without erase NVM page(n). 1: Set this bit to erase page(n) of NVM. The NVM has 4 pages and each page have 64 bytes data memory. Before select page by NVMADDR register that will automatic enable page area, after set this bit, the page will be erased and program counter will halt at this instruction. After finished, program counter will kept next instruction then executed. The NVM page's address is defined in table below.
6	EWR	NVM data write bit: 0: Without write NVM data. 1: Set this bit to write NVM bytes and program counter will halt at this instruction. After write is finished, program counter will kept next instruction then executed.
5-0	-	Reserved

NVM Page(n) Area Definition Table:

PAGE	START ADDRESS	END ADDRESS
0	00H	3FH
1	40H	7FH
2	***80H***	***BFH***
3	***C0H***	***FFH***

NVM DATA

Bit:	7	6	5	4	3	2	1	0
	NVMDAT.7	NVMDAT.6	NVMDAT.5	NVMDAT.4	NVMDAT3	NVMDAT.2	NVMDAT.1	NVMDAT.0

Mnemonic: NVMDATA Address: CFh

BIT	NAME	FUNCTION
7~0	NVMDAT.[7:0]	The NVM data write register. The read NVM data is by MOVC instruction.

PROGRAM STATUS WORD

Bit:	7	6	5	4	3	2	1	0
	CY	AC	F0	RS1	RS0	OV	F1	P

Mnemonic: PSW Address: D0h

BIT	NAME	FUNCTION
7	CY	Carry flag: Set for an arithmetic operation which results in a carry being generated from the ALU. It is also used as the accumulator for the bit operations.
6	AC	Auxiliary carry: Set when the previous operation resulted in a carry from the high order nibble.
5	F0	User flag 0: The General purpose flag that can be set or cleared by the user.
4~3	RS1~RS0	Register bank select bits.
2	OV	Overflow flag: Set when a carry was generated from the seventh bit but not from the 8th bit as a result of the previous operation, or vice-versa.
1	F1	User Flag 1: The General purpose flag that can be set or cleared by the user software.
0	P	Parity flag: Set/cleared by hardware to indicate odd/even number of 1's in the accumulator.

RS.1-0: Register Bank Selection Bits:

RS1	RS0	REGISTER BANK	ADDRESS
0	0	0	00-07h
0	1	1	08-0Fh
1	0	2	10-17h
1	1	3	18-1Fh

PWMP COUNTER HIGH BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	PWMP.9	PWMP.8

Mnemonic: PWMPH Address: D1h

BIT	NAME	FUNCTION
7-2	-	Reserved.
1-0	PWMP.[9:8]	The PWM Counter Register bits 9~8.

PWM 0 HIGH BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	PWM0.9	PWM0.8

Mnemonic: PWM0H Address: D2h

BIT	NAME	FUNCTION
7~2	-	Reserved.
1~0	PWM0.[9:8]	The PWM 0 High Bits Register bit 9~8.

PWM 1 HIGH BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	PWM1.9	PWM1.8

Mnemonic: PWM1H Address: D3h

BIT	NAME	FUNCTION
7~2	-	Reserved.
1~0	PWM1.[9:8]	The PWM 1 High Bits Register bit 9~8.

PWM 2 HIGH BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	PWM2.9	PWM2.8

Mnemonic: PWM2H Address: D5h

BIT	NAME	FUNCTION
7~2	-	Reserved.
1~0	PWM2.[9:8]	The PWM 2 High Bits Register bit 9~8.

PWM 3 HIGH BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	PWM3.9	PWM3.8

Mnemonic: PWM3H Address: D6h

BIT	NAME	FUNCTION
7~2	-	Reserved.
1~0	PWM3.[9:8]	The PWM 3 High Bits Register bit 9~8.

PWM CONTROL REGISTER 3

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	-	BKF

Mnemonic: PWMCON3 Address: D7h

BIT	NAME	FUNCTION
7-6	-	Reserved.
0	BKF	The external brake pin Flag. 0: The PWM is not brake. 1: The PWM is brake by external brake pin. It will be cleared by software.

WATCHDOG CONTROL

Bit:	7	6	5	4	3	2	1	0
	WDRUN	POR	WD1	WD0	WDIF	WTRF	EWRST	WDCLR

Mnemonic: WDCON Address: D8h

<table>
<tr><th>BIT</th><th>NAME</th><th>FUNCTION</th></tr>
<tr><td>7</td><td>WDRUN</td><td>0: The Watchdog is stopped.
1: The Watchdog is running.</td></tr>
<tr><td>6</td><td>-</td><td>Reserved.</td></tr>
<tr><td>5</td><td>WD1</td><td rowspan="2">Watchdog Timer Time-out Select bits. These bits determine the time-out period of the watchdog timer. The reset time-out period is 512 clocks longer than the watchdog time-out.

<table>
<tr><th>WD1</th><th>WD0</th><th>Interrupt time-out</th><th>Reset time-out</th></tr>
<tr><td>0</td><td>0</td><td>2^{17}</td><td>2^{17} + 512</td></tr>
<tr><td>0</td><td>1</td><td>2^{20}</td><td>2^{20} + 512</td></tr>
<tr><td>1</td><td>0</td><td>2^{23}</td><td>2^{23} + 512</td></tr>
<tr><td>1</td><td>1</td><td>2^{26}</td><td>2^{26} + 512</td></tr>
</table></td></tr>
<tr><td>4</td><td>WD0</td></tr>
<tr><td>3</td><td>WDIF</td><td>Watchdog Timer Interrupt Flag
0: If the interrupt is not enabled, then this bit indicates that the time-out period has elapsed. This bit must be cleared by software.
1: If the watchdog interrupt is enabled, hardware will set this bit to indicate that the watchdog interrupt has occurred.</td></tr>
<tr><td>2</td><td>WTRF</td><td>Watchdog Timer Reset Flag
1: Hardware will set this bit when the watchdog timer causes a reset. Software can read it but must clear it manually. A power-fail reset will also clear the bit. This bit helps software in determining the cause of a reset. If EWRST = 0, the watchdog timer will have no affect on this bit.</td></tr>
<tr><td>1</td><td>EWRST</td><td>0: Disable Watchdog Timer Reset.
1: Enable Watchdog Timer Reset.</td></tr>
<tr><td>0</td><td>WDCLR</td><td>Reset Watchdog Timer
This bit helps in putting the watchdog timer into a know state. It also helps in resetting the watchdog timer before a time-out occurs. Failing to set the EWRST before time-out will cause an interrupt, if EWDI (EIE.4) is set, and 512 clocks after that a watchdog timer reset will be generated if EWRST is set. This bit is self-clearing by hardware.</td></tr>
</table>

The WDCON SFR is set to 0x000000B on a reset. WTRF (WDCON.2) is set to a 1 on a Watchdog timer reset, but to a 0 on power on/down resets. WTRF (WDCON.2) is not altered by an external reset. EWRST (WDCON.1) is set to 0 on a Power-on reset, reset pin reset, and Watch Dog Timer reset.

All the bits in this SFR have unrestricted read access. EWRST, WDIF and WDCLR require Timed Access procedure to write. The remaining bits have unrestricted write accesses. Please refer TA register description.

```
TA          REG         C7H
WDCON       REG         D8H
MOV         TA, #AAH                ; To access protected bits
MOV         TA, #55H
SETB        WDCON.0                 ; Reset watchdog timer
ORL         WDCON, #00110000B       ; Select 26 bits watchdog timer
MOV         TA, #AAH
MOV         TA, #55H
ORL         WDCON, #00000010B       ; Enable watchdog
```

PWMP COUNTER LOW BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	PWMP.7	PWMP.6	PWMP.5	PWP.4	PWMP.3	PWMP.2	PWMP.1	PWMP.1

Mnemonic: PWMPL Address: D9h

BIT	NAME	FUNCTION
7~0	PWMP.[7:0]	PWM Counter Low Bits Register.

PWM0 LOW BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	PWM0.7	PWM0.6	PWM0.5	PWM0.4	PWM0.3	PWM0.2	PWM0.1	PWM0.1

Mnemonic: PWM0L Address: DAh

BIT	NAME	FUNCTION
7~0	PWM0.[7:0]	PWM 0 Low Bits Register.

PWM1 LOW BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	PWM1.7	PWM1.6	PWM1.5	PWM1.4	PWM1.3	PWM1.2	PWM1.1	PWM1.0

Mnemonic: PWM1L Address: DBh

BIT	NAME	FUNCTION
7~0	PWM1.[7:0]	PWM 1 Low Bits Register.

PWM CONTROL REGISTER 1

Bit:	7	6	5	4	3	2	1	0
	PWMRUN	Load	PWMF	CLRPWM	PWM3I	PWM2I	PWM1I	PWM0I

Mnemonic: PWMCON1 Address: DCh

BIT	NAME	FUNCTION
7	PWMRUN	0: The PWM is not running. 1: The PWM counter is running.
6	Load	0: The registers value of PWMP and PWMn are never loaded to counter and Comparator registers. 1: The PWMP and PWMn registers load value to counter and compare registers at the counter underflow. This bit is auto cleared by hardware at next clock cycle.
5	CF	0: The 10-bit counter down count is not underflow. 1: The 10-bit counter down count is underflow. This bit is Software clear.
4	CLRPWM	1: Clear 10-bit PWM counter to 000H. This bit is auto cleared by hardware.
3	PWM3I	0: PWM3 out is non-inverted. 1: PWM3 output is inverted.
2	PWM2I	0: PWM2 out is non-inverted. 1: PWM2 output is inverted.
1	PWM1I	0: PWM1 out is non-inverted. 1: PWM1 output is inverted.
0	PWM0I	0: PWM0 out is non-inverted. 1: PWM0 output is inverted.

PWM2 LOW BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	PWM2.7	PWM2.6	PWM2.5	PWM2.4	PWM2.3	PWM2.2	PWM2.1	PWM2.0

Mnemonic: PWM2L Address: DDh

BIT	NAME	FUNCTION
7~0	PWM2.[7:0]	PWM 2 Low Bits Register.

PWM3 LOW BITS REGISTER

Bit:	7	6	5	4	3	2	1	0
	PWM3.7	PWM3.6	PWM3.5	PWM3.4	PWM3.3	PWM3.2	PWM3.1	PWM3.0

Mnemonic: PWM2L Address: DEh

BIT	NAME	FUNCTION
7~0	PWM3.[7:0]	PWM 3 Low Bits Register.

PWM CONTROL REGISTER 2

Bit:	7	6	5	4	3	2	1	0
	BKCH	BKPS	BPEN	BKEN	PWM3B	PWM2B	PWM1B	PWM0B

Mnemonic: PWMCON2 Address: DFh

BIT	NAME	FUNCTION
7	BKCH	See the below table, when BKEN is set.
6	BKPS	0: Brake is asserted if P0.2 is low. 1: Brake is asserted if P0.2 is high
5	BPEN	See the below table, when BKEN is set.
4	BKEN	0: The Brake is never asserted. 1: The Brake is enabled, and see the below table.
3	PWM3B	0: The PWM3 output is low, when Brake is asserted. 1: The PWM3 output is high, when Brake is asserted.
2	PWM2B	0: The PWM2 output is low, when Brake is asserted. 1: The PWM2 output is high, when Brake is asserted.
1	PWM1B	0: The PWM1 output is low, when Brake is asserted. 1: The PWM1 output is high, when Brake is asserted.
0	PWM0B	0: The PWM0 output is low, when Brake is asserted. 1: The PWM0 output is high, when Brake is asserted.

Brake Condition Table:

BPEN	BKCH	BRAKE CONDITION
0	0	Brake On (software brake and keeping brake). Software brake condition. When active (BPEN=BKCH=0, and BKEN=1), PWM output follows PWMnB setting. This brake has no effect on PWMRUN bit, therefore, internal PWM generator continues to run. When the brake is released, the state of PWM output depends on the current state of PWM generator output during the release.
0	1	Brake On, when PWM is not running (PWMRUN=0), the PWM output condition follows PWMnB setting. When the brake is released (by disabling BKEN = 0), the PWM output resumes to the state when PWM generator stop running prior to enabling the brake. Brake Off, when PWM is running (PWMRUN=1).
1	0	Brake On, when Brake Pin asserted. External pin brake condition. When active (by external pin), PWM output follows PWMnB setting, PWMRUN will be cleared by hardware, and BKF flag will be set. When the brake is released (by de-asserting the external pin and disabling BKEN = 0), the PWM output resumes to the state of the PWM generator output prior to the brake.
1	1	No any active.

ACCUMULATOR

Bit:	7	6	5	4	3	2	1	0
	ACC.7	ACC.6	ACC.5	ACC.4	ACC.3	ACC.2	ACC.1	ACC.0

Mnemonic: ACC Address: E0h

BIT	NAME	FUNCTION
7-0	ACC.[7:0]	The A or ACC register is the standard 8052 accumulator

INTERRUPT ENABLE REGISTER 1

Bit:	7	6	5	4	3	2	1	0
	-	-	EPWM	EWDI	EC2	EC1	EKB	EI2

Mnemonic: EIE Address: E8h

BIT	NAME	FUNCTION
7	-	Reserved.
6	-	Reserved.
5	EPWM	0: Disable PWM Interrupt when external brake pin was brake. 1: Enable PWM Interrupt when external brake pin was brake.
4	EWDI	0: Disable Watchdog Timer Interrupt. 1: Enable Watchdog Timer Interrupt.
3	EC2	0: Disable Comparator 2 Interrupt. 1: Enable Comparator 2 Interrupt.
2	EC1	0: Disable Comparator 1 Interrupt. 1: Enable Comparator 1 Interrupt.
1	EKB	0: Disable Keypad Interrupt. 1: Enable Keypad Interrupt.
0	EI2	0: Disable I2C Interrupt. 1: Enable I2C Interrupt.

B REGISTER

Bit:	7	6	5	4	3	2	1	0
	B.7	B.6	B.5	B.4	B.3	B.2	B.1	B.0

Mnemonic: B Address: F0h

BIT	NAME	FUNCTION
7-0	B.[7:0]	The B register is the standard 8052 register that serves as a second accumulator.

PORT 0 DIGITAL INPUT DISABLE

Bit:	7	6	5	4	3	2	1	0
	P0ID.7	P0ID.6	P0ID.5	P0ID.4	P0ID.3	P0ID.2	P0ID.1	P0ID.0

Mnemonic: P0ID Address: F6h

BIT	NAME	FUNCTION
7~0	P0ID.[7:0]	Enable/Disable Port 0 digital inputs. 0: Enable Port 0 digital inputs. 1: Disable Port 0 digital inputs.

INTERRUPT HIGH PRIORITY 1

Bit:	7	6	5	4	3	2	1	0
	-	-	PPWMH	PWDIH	PC2H	PC1H	PKBH	PI2H

Mnemonic: IP1H Address: F7h

BIT	NAME	FUNCTION
7	-	Reserved.
6	-	Reserved.
5	PPWMH	1: To set interrupt high priority of PWM's brake is highest priority level.
4	PWDIH	1: To set interrupt high priority of Watchdog is highest priority level.
3	PC2H	1: To set interrupt high priority of Comparator 2 is highest priority level.
2	PC1H	1: To set interrupt high priority of Comparator 1 is highest priority level.
1	PKBH	1: To set interrupt high priority of Keypad is highest priority level.
0	PI2H	1: To set interrupt high priority of I2C is highest priority level.

EXTENDED INTERRUPT PRIORITY

Bit:	7	6	5	4	3	2	1	0
	-	-	PPWM	PWDI	PC2	PC1	PKB	PI2

Mnemonic: IP1 Address: F8h

BIT	NAME	FUNCTION
7	-	Reserved.
6	-	Reserved.
5	PPWM	1: To set interrupt priority of PWM's external brake is higher priority level.
4	PWDI	1: To set interrupt priority of Watchdog is higher priority level.
3	PC2	1: To set interrupt priority of Comparator 2 is higher priority level.
2	PC1	1: To set interrupt priority of Comparator 1 is higher priority level.
1	PKB	1: To set interrupt priority of Keypad is higher priority level.
0	PI2	1: To set interrupt priority of I2C is higher priority level.

9. INSTRUCTION SET

The W79E804 series execute all the instructions of the standard 8052 family. The operations of these instructions, as well as their effects on flag and status bits, are exactly the same. However, the timing of these instructions is different in two ways. Firstly, the machine cycle is four clock periods, while the standard-8051/52 machine cycle is twelve clock periods. Secondly, it can fetch only once per machine cycle (i.e., four clocks per fetch), while the standard 8051/52 can fetch twice per machine cycle (i.e., six clocks per fetch).

The timing differences create an advantage for the W79E804 series. There is only one fetch per machine cycle, so the number of machine cycles is usually equal to the number of operands in the instruction. (Jumps and calls do require an additional cycle to calculate the new address.) As a result, the W79E804 series reduces the number of dummy fetches and wasted cycles, and therefore improves overall efficiency, compared to the standard 8051/52.

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
NOP	00	1	1	4	12	3
ADD A, R0	28	1	1	4	12	3
ADD A, R1	29	1	1	4	12	3
ADD A, R2	2A	1	1	4	12	3
ADD A, R3	2B	1	1	4	12	3
ADD A, R4	2C	1	1	4	12	3
ADD A, R5	2D	1	1	4	12	3
ADD A, R6	2E	1	1	4	12	3
ADD A, R7	2F	1	1	4	12	3
ADD A, @R0	26	1	1	4	12	3
ADD A, @R1	27	1	1	4	12	3
ADD A, direct	25	2	2	8	12	1.5
ADD A, #data	24	2	2	8	12	1.5
ADDC A, R0	38	1	1	4	12	3
ADDC A, R1	39	1	1	4	12	3
ADDC A, R2	3A	1	1	4	12	3
ADDC A, R3	3B	1	1	4	12	3
ADDC A, R4	3C	1	1	4	12	3
ADDC A, R5	3D	1	1	4	12	3
ADDC A, R6	3E	1	1	4	12	3
ADDC A, R7	3F	1	1	4	12	3
ADDC A, @R0	36	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
ADDC A, @R1	37	1	1	4	12	3
ADDC A, direct	35	2	2	8	12	1.5
ADDC A, #data	34	2	2	8	12	1.5
SUBB A, R0	98	1	1	4	12	3
SUBB A, R1	99	1	1	4	12	3
SUBB A, R2	9A	1	1	4	12	3
SUBB A, R3	9B	1	1	4	12	3
SUBB A, R4	9C	1	1	4	12	3
SUBB A, R5	9D	1	1	4	12	3
SUBB A, R6	9E	1	1	4	12	3
SUBB A, R7	9F	1	1	4	12	3
SUBB A, @R0	96	1	1	4	12	3
SUBB A, @R1	97	1	1	4	12	3
SUBB A, direct	95	2	2	8	12	1.5
SUBB A, #data	94	2	2	8	12	1.5
INC A	04	1	1	4	12	3
INC R0	08	1	1	4	12	3
INC R1	09	1	1	4	12	3
INC R2	0A	1	1	4	12	3
INC R3	0B	1	1	4	12	3
INC R4	0C	1	1	4	12	3
INC R5	0D	1	1	4	12	3
INC R6	0E	1	1	4	12	3
INC R7	0F	1	1	4	12	3
INC @R0	06	1	1	4	12	3
INC @R1	07	1	1	4	12	3
INC direct	05	2	2	8	12	1.5
INC DPTR	A3	1	2	8	24	3
DEC A	14	1	1	4	12	3
DEC R0	18	1	1	4	12	3
DEC R1	19	1	1	4	12	3
DEC R2	1A	1	1	4	12	3
DEC R3	1B	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
DEC R4	1C	1	1	4	12	3
DEC R5	1D	1	1	4	12	3
DEC R6	1E	1	1	4	12	3
DEC R7	1F	1	1	4	12	3
DEC @R0	16	1	1	4	12	3
DEC @R1	17	1	1	4	12	3
DEC direct	15	2	2	8	12	1.5
MUL AB	A4	1	5	20	48	2.4
DIV AB	84	1	5	20	48	2.4
DA A	D4	1	1	4	12	3
ANL A, R0	58	1	1	4	12	3
ANL A, R1	59	1	1	4	12	3
ANL A, R2	5A	1	1	4	12	3
ANL A, R3	5B	1	1	4	12	3
ANL A, R4	5C	1	1	4	12	3
ANL A, R5	5D	1	1	4	12	3
ANL A, R6	5E	1	1	4	12	3
ANL A, R7	5F	1	1	4	12	3
ANL A, @R0	56	1	1	4	12	3
ANL A, @R1	57	1	1	4	12	3
ANL A, direct	55	2	2	8	12	1.5
ANL A, #data	54	2	2	8	12	1.5
ANL direct, A	52	2	2	8	12	1.5
ANL direct, #data	53	3	3	12	24	2
ORL A, R0	48	1	1	4	12	3
ORL A, R1	49	1	1	4	12	3
ORL A, R2	4A	1	1	4	12	3
ORL A, R3	4B	1	1	4	12	3
ORL A, R4	4C	1	1	4	12	3
ORL A, R5	4D	1	1	4	12	3
ORL A, R6	4E	1	1	4	12	3
ORL A, R7	4F	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
ORL A, @R0	46	1	1	4	12	3
ORL A, @R1	47	1	1	4	12	3
ORL A, direct	45	2	2	8	12	1.5
ORL A, #data	44	2	2	8	12	1.5
ORL direct, A	42	2	2	8	12	1.5
ORL direct, #data	43	3	3	12	24	2
XRL A, R0	68	1	1	4	12	3
XRL A, R1	69	1	1	4	12	3
XRL A, R2	6A	1	1	4	12	3
XRL A, R3	6B	1	1	4	12	3
XRL A, R4	6C	1	1	4	12	3
XRL A, R5	6D	1	1	4	12	3
XRL A, R6	6E	1	1	4	12	3
XRL A, R7	6F	1	1	4	12	3
XRL A, @R0	66	1	1	4	12	3
XRL A, @R1	67	1	1	4	12	3
XRL A, direct	65	2	2	8	12	1.5
XRL A, #data	64	2	2	8	12	1.5
XRL direct, A	62	2	2	8	12	1.5
XRL direct, #data	63	3	3	12	24	2
CLR A	E4	1	1	4	12	3
CPL A	F4	1	1	4	12	3
RL A	23	1	1	4	12	3
RLC A	33	1	1	4	12	3
RR A	03	1	1	4	12	3
RRC A	13	1	1	4	12	3
SWAP A	C4	1	1	4	12	3
MOV A, R0	E8	1	1	4	12	3
MOV A, R1	E9	1	1	4	12	3
MOV A, R2	EA	1	1	4	12	3
MOV A, R3	EB	1	1	4	12	3
MOV A, R4	EC	1	1	4	12	3
MOV A, R5	ED	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
MOV A, R6	EE	1	1	4	12	3
MOV A, R7	EF	1	1	4	12	3
MOV A, @R0	E6	1	1	4	12	3
MOV A, @R1	E7	1	1	4	12	3
MOV A, direct	E5	2	2	8	12	1.5
MOV A, #data	74	2	2	8	12	1.5
MOV R0, A	F8	1	1	4	12	3
MOV R1, A	F9	1	1	4	12	3
MOV R2, A	FA	1	1	4	12	3
MOV R3, A	FB	1	1	4	12	3
MOV R4, A	FC	1	1	4	12	3
MOV R5, A	FD	1	1	4	12	3
MOV R6, A	FE	1	1	4	12	3
MOV R7, A	FF	1	1	4	12	3
MOV R0, direct	A8	2	2	8	12	1.5
MOV R1, direct	A9	2	2	8	12	1.5
MOV R2, direct	AA	2	2	8	12	1.5
MOV R3, direct	AB	2	2	8	12	1.5
MOV R4, direct	AC	2	2	8	12	1.5
MOV R5, direct	AD	2	2	8	12	1.5
MOV R6, direct	AE	2	2	8	12	1.5
MOV R7, direct	AF	2	2	8	12	1.5
MOV R0, #data	78	2	2	8	12	1.5
MOV R1, #data	79	2	2	8	12	1.5
MOV R2, #data	7A	2	2	8	12	1.5
MOV R3, #data	7B	2	2	8	12	1.5
MOV R4, #data	7C	2	2	8	12	1.5
MOV R5, #data	7D	2	2	8	12	1.5
MOV R6, #data	7E	2	2	8	12	1.5
MOV R7, #data	7F	2	2	8	12	1.5
MOV @R0, A	F6	1	1	4	12	3
MOV @R1, A	F7	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
MOV @R0, direct	A6	2	2	8	12	1.5
MOV @R1, direct	A7	2	2	8	12	1.5
MOV @R0, #data	76	2	2	8	12	1.5
MOV @R1, #data	77	2	2	8	12	1.5
MOV direct, A	F5	2	2	8	12	1.5
MOV direct, R0	88	2	2	8	12	1.5
MOV direct, R1	89	2	2	8	12	1.5
MOV direct, R2	8A	2	2	8	12	1.5
MOV direct, R3	8B	2	2	8	12	1.5
MOV direct, R4	8C	2	2	8	12	1.5
MOV direct, R5	8D	2	2	8	12	1.5
MOV direct, R6	8E	2	2	8	12	1.5
MOV direct, R7	8F	2	2	8	12	1.5
MOV direct, @R0	86	2	2	8	12	1.5
MOV direct, @R1	87	2	2	8	12	1.5
MOV direct, direct	85	3	3	12	24	2
MOV direct, #data	75	3	3	12	24	2
MOV DPTR, #data 16	90	3	3	12	24	2
MOVC A, @A+DPTR	93	1	2	8	24	3
MOVC A, @A+PC	83	1	2	8	24	3
MOVX A, @R0	E2	1	2 - 9	8 - 36	24	3 - 0.66
MOVX A, @R1	E3	1	2 - 9	8 - 36	24	3 - 0.66
MOVX A, @DPTR	E0	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @R0, A	F2	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @R1, A	F3	1	2 - 9	8 - 36	24	3 - 0.66
MOVX @DPTR, A	F0	1	2 - 9	8 - 36	24	3 - 0.66
PUSH direct	C0	2	2	8	24	3
POP direct	D0	2	2	8	24	3
XCH A, R0	C8	1	1	4	12	3
XCH A, R1	C9	1	1	4	12	3
XCH A, R2	CA	1	1	4	12	3
XCH A, R3	CB	1	1	4	12	3
XCH A, R4	CC	1	1	4	12	3

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
XCH A, R5	CD	1	1	4	12	3
XCH A, R6	CE	1	1	4	12	3
XCH A, R7	CF	1	1	4	12	3
XCH A, @R0	C6	1	1	4	12	3
XCH A, @R1	C7	1	1	4	12	3
XCHD A, @R0	D6	1	1	4	12	3
XCHD A, @R1	D7	1	1	4	12	3
XCH A, direct	C5	2	2	8	12	1.5
CLR C	C3	1	1	4	12	3
CLR bit	C2	2	2	8	12	1.5
SETB C	D3	1	1	4	12	3
SETB bit	D2	2	2	8	12	1.5
CPL C	B3	1	1	4	12	3
CPL bit	B2	2	2	8	12	1.5
ANL C, bit	82	2	2	8	24	3
ANL C, /bit	B0	2	2	6	24	3
ORL C, bit	72	2	2	8	24	3
ORL C, /bit	A0	2	2	6	24	3
MOV C, bit	A2	2	2	8	12	1.5
MOV bit, C	92	2	2	8	24	3
ACALL addr11	71, 91, B1, 11, 31, 51, D1, F1	2	3	12	24	2
LCALL addr16	12	3	4	16	24	1.5
RET	22	1	2	8	24	3
RETI	32	1	2	8	24	3
AJMP ADDR11	01, 21, 41, 61, 81, A1, C1, E1	2	3	12	24	2
LJMP addr16	02	3	4	16	24	1.5
JMP @A+DPTR	73	1	2	6	24	3
SJMP rel	80	2	3	12	24	2
JZ rel	60	2	3	12	24	2

Continued

OP-CODE	HEX CODE	BYTES	W79E804 SERIES MACHINE CYCLE	W79E804 SERIES CLOCK CYCLES	8032 CLOCK CYCLES	W79E804 SERIES VS. 8032 SPEED RATIO
JNZ rel	70	2	3	12	24	2
JC rel	40	2	3	12	24	2
JNC rel	50	2	3	12	24	2
JB bit, rel	20	3	4	16	24	1.5
JNB bit, rel	30	3	4	16	24	1.5
JBC bit, rel	10	3	4	16	24	1.5
CJNE A, direct, rel	B5	3	4	16	24	1.5
CJNE A, #data, rel	B4	3	4	16	24	1.5
CJNE @R0, #data, rel	B6	3	4	16	24	1.5
CJNE @R1, #data, rel	B7	3	4	16	24	1.5
CJNE R0, #data, rel	B8	3	4	16	24	1.5
CJNE R1, #data, rel	B9	3	4	16	24	1.5
CJNE R2, #data, rel	BA	3	4	16	24	1.5
CJNE R3, #data, rel	BB	3	4	16	24	1.5
CJNE R4, #data, rel	BC	3	4	16	24	1.5
CJNE R5, #data, rel	BD	3	4	16	24	1.5
CJNE R6, #data, rel	BE	3	4	16	24	1.5
CJNE R7, #data, rel	BF	3	4	16	24	1.5
DJNZ R0, rel	D8	2	3	12	24	2
DJNZ R1, rel	D9	2	3	12	24	2
DJNZ R5, rel	DD	2	3	12	24	2
DJNZ R2, rel	DA	2	3	12	24	2
DJNZ R3, rel	DB	2	3	12	24	2
DJNZ R4, rel	DC	2	3	12	24	2
DJNZ R6, rel	DE	2	3	12	24	2
DJNZ R7, rel	DF	2	3	12	24	2
DJNZ direct, rel	D5	3	4	16	24	1.5

Table 9-1: Instruction Set for W79E804/803/802

9.1 Instruction Timing

This section is important because some applications use software instructions to generate timing delays. It also provides more information about timing differences between the W79E804 series and the standard 8051/52.

In W79E804 series, each machine cycle is four clock periods long. Each clock period is called a state, and each machine cycle consists of four states: C1, C2 C3 and C4, in order. Both clock edges are used for internal timing, so the duty cycle of the clock should be as close to 50% as possible to avoid timing conflicts.

The W79E804 series does one op-code fetch per machine cycle, so, in most instructions, the number of machine cycles required is equal to the number of bytes in the instruction. There are 256 available op-codes. 128 of them are single-cycle instructions, so many op-codes are executed in just four clocks period. Some of the other op-codes are two-cycle instructions, and most of these have two-byte op-codes. However, there are some instructions that have one-byte instructions yet take two cycles to execute. One important example is the MOVX instruction.

In the standard 8052, the MOVX instruction is always two machine cycles long. However, in the W79E804 series each machine cycle is made of only 4 clock periods compared to the 12 clock periods for the standard 8052. Therefore, even though the number of categories has increased, each instruction is at least 1.5 to 3 times faster than the standard 8052 in terms of clock periods.

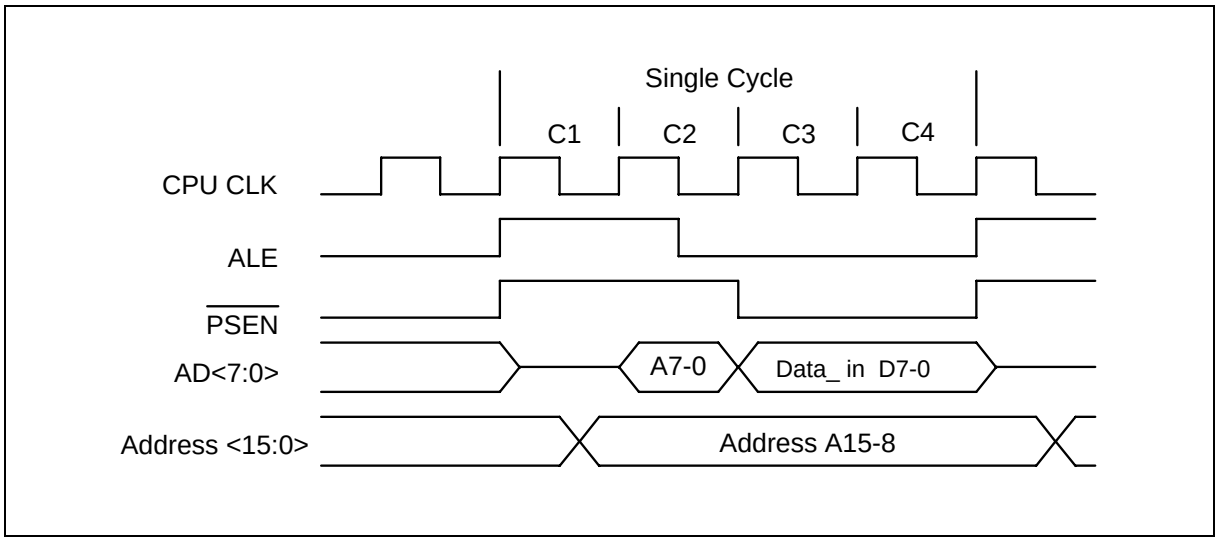


Figure 9-1: Single Cycle Instruction Timing

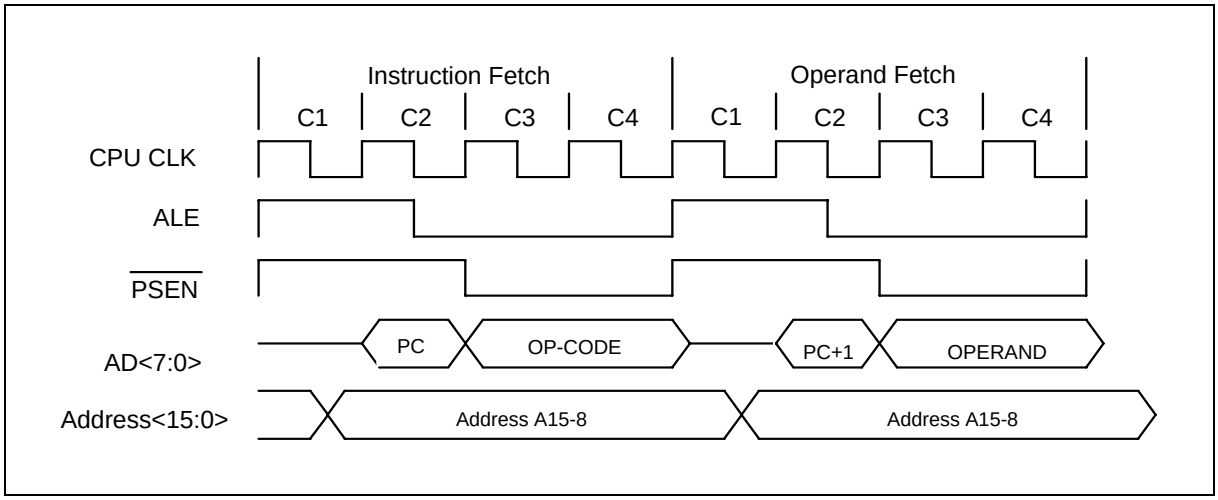


Figure 9-2: Two Cycles Instruction Timing

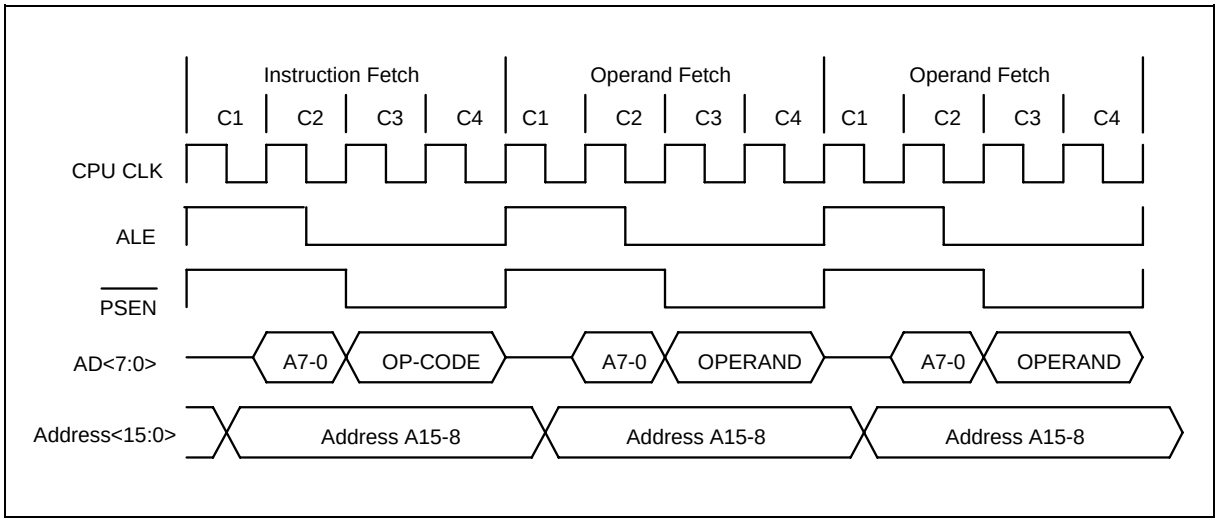


Figure 9-3: Three Cycles Instruction Timing

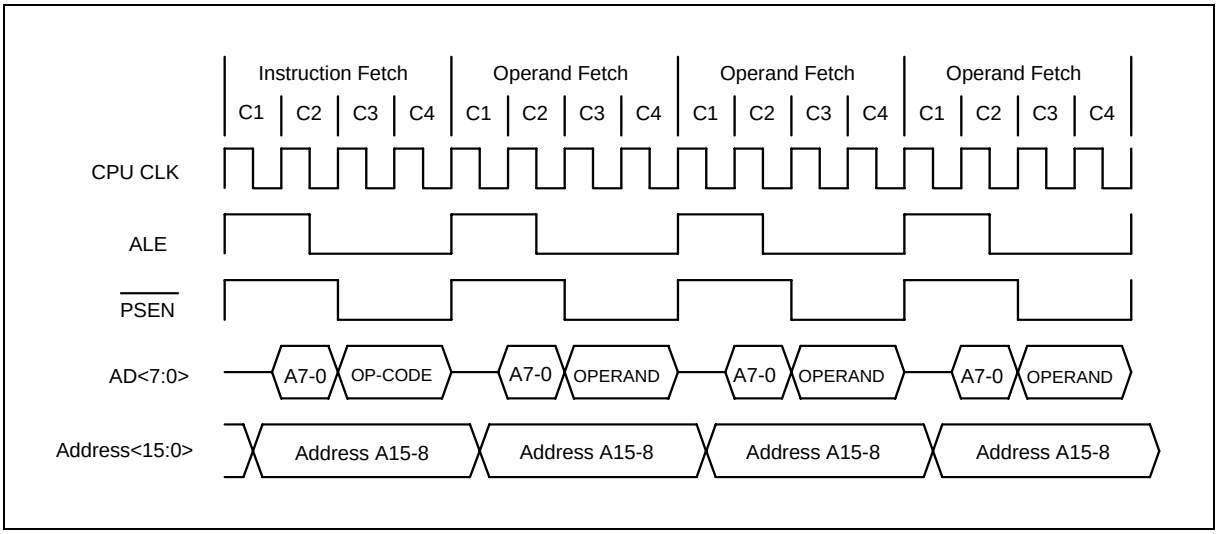


Figure 9-4: Four Cycles Instruction Timing

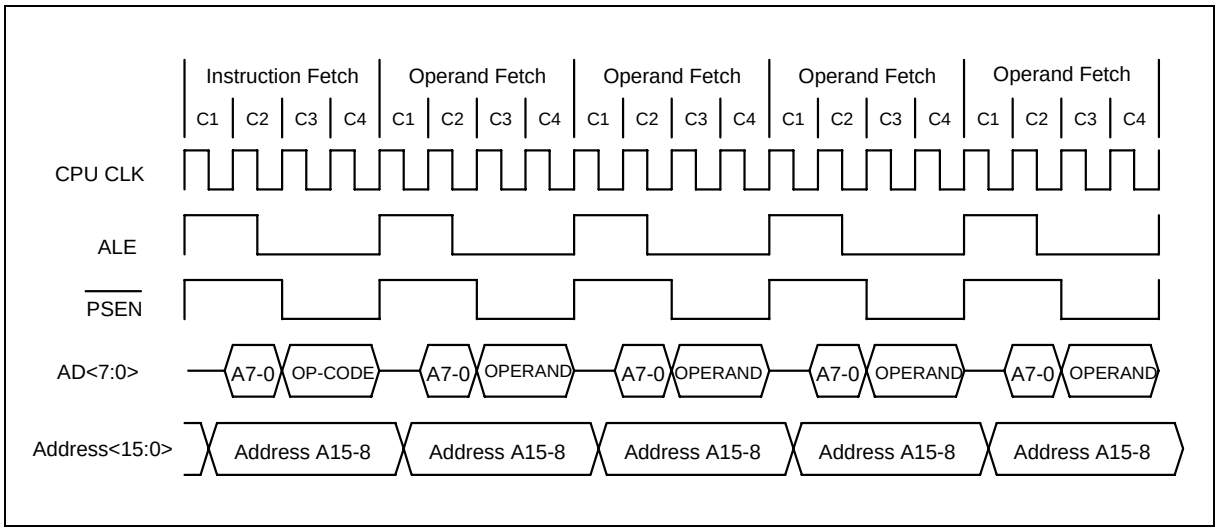


Figure 9-5: Five Cycles Instruction Timing

10. POWER MANAGEMENT

The W79E804 series has several features that help the user to control the power consumption of the device. These modes are discussed in the next two sections.

10.1 Idle Mode

The user can put the device into idle mode by writing 1 to the bit PCON.0. The instruction that sets the idle bit is the last instruction that will be executed before the device goes into Idle Mode. In the Idle mode, the clock to the CPU is halted, but not to the Interrupt, Timer, Watchdog timer, I2C, PWM and Serial port blocks. This forces the CPU state to be frozen; the Program counter, the Stack Pointer, the Program Status Word, the Accumulator and the other registers hold their contents. The port pins hold the logical states they had at the time Idle was activated. The Idle mode can be terminated in two ways. Since the interrupt controller is still active, the activation of any enabled interrupt can wake up the processor. This will automatically clear the Idle bit, terminate the Idle mode, and the Interrupt Service Routine (ISR) will be executed. After the ISR, execution of the program will continue from the instruction which put the device into Idle Mode.

The Idle mode can also be exited by activating the reset. The device can put into reset either by applying a low on the external /RST pin, a Power on reset condition or a Watchdog timer reset. The external reset pin has to be held low for at least two machine cycles i.e. 8 clock periods to be recognized as a valid reset. In the reset condition the program counter is reset to 0000h and all the SFRs are set to the reset condition. Since the clock is already running there is no delay and execution starts immediately. In the Idle mode, the Watchdog timer continues to run, and if enabled, a time-out will cause a watchdog timer interrupt which will wake up the device. The software must reset the Watchdog timer in order to preempt the reset which will occur after 512 clock periods of the time-out. When the W79E804 series are exiting from an Idle Mode with a reset, the instruction following the one which put the device into Idle Mode is not executed. So there is no danger of unexpected writes.

10.2 Power Down Mode

The device can be put into Power Down mode by writing 1 to bit PCON.1. The instruction that does this will be the last instruction to be executed before the device goes into Power Down mode. In the Power Down mode, all the clocks are stopped and the device comes to a halt. All activity is completely stopped and the power consumption is reduced to the lowest possible value. The port pins output the values held by their respective SFRs.

The W79E804 series will exit the Power Down mode with a reset or by an external interrupt pin. An external reset can be used to exit the Power down state. The low on /RST pin terminates the Power Down mode, and restarts the clock. The program execution will restart from 0000h. In the Power down mode, the clock is stopped, so the Watchdog timer cannot be used to provide the reset to exit Power down mode when its clock source is external OSC or crystal.

The sources that can wake up from the power down mode are external interrupts, keyboard interrupt (KBI), brownout reset (BOR), and comparator interrupt (CMF1, CMF2), and watchdog timer interrupt (if WDTE = 0).

The W79E804 series can be waken up from the Power Down mode by forcing an external interrupt pin activation, provided the corresponding interrupt is enabled, while the global enable (EA) bit is set. If these conditions are met, then either a low-level or a falling-edge at external interrupt pin will re-start the oscillator. The device will then execute the interrupt service routine for the corresponding external interrupt. After the interrupt service routine is completed, the program execution returns to the instruction after one which put the device into Power Down mode and continues from there. During Power down mode, if AUXR1.LPBOV = 1 and AUXR1.BOD = 0, the internal RC clock will be enabled and hence save power.

11. RESET CONDITIONS

The user has several hardware related options for placing the W79E804 series into reset condition. In general, most register bits go to their reset value irrespective of the reset condition, but there are a few flags whose state depends on the source of reset. The user can use these flags to determine the cause of reset using software.

11.1 Sources of reset

11.1.1 External Reset

The device samples the /RST pin every machine cycle during state C4. The /RST pin must be held low for at least two machine cycles before the reset circuitry applies an internal reset signal. Thus, this reset is a synchronous operation and requires the clock to be running.

The device remains in the reset state as long as /RST is low and remains low up to two machine cycles after /RST is deactivated. Then, the device begins program execution at 0000h. There are no flags associated with the external reset, but, since the other two reset sources do have flags, the external reset is the cause if those flags are clear.

11.1.2 Power-On Reset (POR)

If the power supply falls below V_{rst}, the device goes into the reset state. When the power supply returns to proper levels, the device performs a power-on reset and sets the POR flag. The software should clear the POR flag, or it will be difficult to determine the source of future resets.

11.1.3 Watchdog Timer Reset

The Watchdog Timer is a free-running timer with programmable time-out intervals. The program must clear the Watchdog Timer before the time-out interval is reached to restart the count. If the time-out interval is reached, an interrupt flag is set. 512 clocks later, if the Watchdog Reset is enabled and the Watchdog Timer has not been cleared, the Watchdog Timer generates a reset. The reset condition is maintained by the hardware for two machine cycles, and the WTRF bit in WDCON is set. Afterwards, the device begins program execution at 0000h.

11.2 Reset State

When the device is reset, most registers return to their initial state. The Watchdog Timer is disabled if the reset source was a power-on reset. The port registers are set to FFh, which puts most of the port pins in a high state. The Program Counter is set to 0000h, and the stack pointer is reset to 07h. After this, the device remains in the reset state as long as the reset conditions are satisfied.

Reset does not affect the on-chip RAM, however, so RAM is preserved as long as VDD remains above approximately 2 V, the minimum operating voltage for the RAM. If VDD falls below 2 V, the RAM contents are also lost. In either case, the stack pointer is always reset, so the stack contents are lost.

SFR RESET VALUE

SFR NAME	RESET VALUE	SFR NAME	RESET VALUE
P0	1111 1111B	I2DAT	xxxx xxxxB
SP	0000 0111B	I2STATUS	0000 0xxxB
DPL	0000 0000B	I2TIMER	0000 0000B
DPH	0000 0000B	I2CLK	0000 0000B
PCON	00xx 0000B	I2CON	0000 0000B
TCON	0000 0000B	I2ADDR	xxxx xxxxB
TMOD	0000 0000B	NVMADDR	0000 0000B
TL0	0000 0000B	TA	0000 0000B
TL1	0000 0000B	NVMDATA	0000 0000B
TH0	0000 0000B	NVMCON	00xx xxxxB
TH1	0000 0000B	PSW	0000 0000B
CKCON	0000 0000B	PWMPH	xxxx xx00B
P1	1111 xx11B	PWM0H	xxxx xx00B
DIVM	0000 0000B	PWM1H	xxxx xx00B
SCON	0000 0000B	PWM2H	xxxx xx00B
SBUF	xxxx xxxxB	PWM3H	xxxx xx00B
P2	xxx xx11B	PWMCON3	xxxx xxx0B
KBI	0000 0000B	WDCON	0x00 0000B
AUXR1	0000 0x00B	PWMPL	0000 0000B
IE	0x00 0000B	PWM0L	0000 0000B
SADDR	0000 0000B	PWM1L	0000 0000B
CMP1	0000 0000B	PWMCON1	0000 0000B
CMP2	0000 0000B	PWM2L	0000 0000B
P0M1	0000 0000B	PWM3L	0000 0000B
P0M2	0000 0000B	PWMCON2	0000 0000B
P1M1	0000 0000B	ACC	0000 0000B
P1M2	0000 0000B	EIE	xx000 000B
P2M1	0000 0000B	B	0000 0000B
P2M2	xxxx xx00B	P0IDS	0000 0000B
IP0H	xx00 0000B	IPH	xx00 0000B
IP0	xx00 0000B	IP1	xx00 0000B
SADEN	0000 0000B		

Table 11-1: SFR Reset Value

The WDCON SFR bits are set/cleared in reset condition depending on the source of the reset.

WDCON	Watch-Dog control	D8H	(DF) WDRUN	(DE) -	(DD) WD1	(DC) WD0	(DB) WDIF	(DA) WTRF	(D9) EWRST	(D8) WDCLR	External reset: 0x00 0000B Watchdog reset: 0x00 0100B Power on reset 0x000000B

The WDCON SFR is set to a 0x00 0000B on the reset. WTRF (WDCON.2) is set to a 1 on a Watchdog timer reset, but to a 0 on power on/down resets. WTRF (WDCON.2) is not altered by external reset. EWRST (WDCON.1) is cleared by any reset. Software or any reset will clear WDIF (WDCON.3) bit.

Some of the bits in the WDCON SFR (WDRUN, WDCLR, EWRST, WDIF, WD0 and WD1) have unrestricted read access which required Timed Access procedure to write. The remaining bits have unrestricted write accesses. Please refer TA register description.

12. INTERRUPTS

The W79E804 series have four priority level interrupts structure with 12 interrupt sources. Each of the interrupt sources has an individual priority bit, flag, interrupt vector and enable bit. In addition, the interrupts can be globally enabled or disabled.

12.1 Interrupt Sources

The External Interrupts $\overline{\text{INT0}}$ and $\overline{\text{INT1}}$ can be either edge triggered or level triggered, depending on bits IT0 and IT1. The bits IE0 and IE1 in the TCON register are the flags which are checked to generate the interrupt. In the edge triggered mode, the INTx inputs are sampled in every machine cycle. If the sample is high in one cycle and low in the next, then a high to low transition is detected and the interrupts request flag IEx in TCON is set. The flag bit requests the interrupt. Since the external interrupts are sampled every machine cycle, they have to be held high or low for at least one complete machine cycle. The IEx flag is automatically cleared when the service routine is called. If the level triggered mode is selected, then the requesting source has to hold the pin low till the interrupt is serviced. The IEx flag will not be cleared by the hardware on entering the service routine. If the interrupt continues to be held low even after the service routine is completed, then the processor may acknowledge another interrupt request from the same source.

The Timer 0 and 1 Interrupts are generated by the TF0 and TF1 flags. These flags are set by the overflow in the Timer 0 and Timer 1. The TF0 and TF1 flags are automatically cleared by the hardware when the timer interrupt is serviced. The Watchdog timer can be used as a system monitor or a simple timer. In either case, when the time-out count is reached, the Watchdog Timer interrupt flag WDIF (WDCON.3) is set. If the interrupt is enabled by the enable bit EIE.4, then an interrupt will occur.

The Serial block can generate interrupt on reception or transmission. There are two interrupt sources from the Serial block, which are obtained by the RI and TI bits in the SCON SFR. These bits are not automatically cleared by the hardware, and the user will have to clear these bits by software.

All the bits that generate interrupts can be set or reset by software, and thereby software initiated interrupts can be generated. Each of the individual interrupts can be enabled or disabled by setting or clearing a bit in the IE SFR. IE also has a global enable/disable bit EA, which can be cleared to disable all interrupts.

The two comparators can generate interrupt after comparator output has toggle occurs by CMF1 and CMF2. These bits are not automatically cleared by the hardware, and the user will have to clear these bits using software.

The I2C function can generate interrupt, if EI2C and EA bits are enabled, when SI Flag is set due to a new I2C status code is generated, SI flag is generated by hardware and must be cleared by software.

The PWM function can generate interrupt by BKF flag, after external brake pin has brake occurred. This bit will be cleared by software.

The interrupt flags are sampled every machine cycle. In the same machine cycle, the sampled interrupts are polled and their priority is resolved. If certain conditions are met then the hardware will execute an internally generated LCALL instruction which will vector the process to the appropriate interrupt vector address. The conditions for generating the LCALL are;

1. An interrupt of equal or higher priority is not currently being serviced.

2. The current polling cycle is the last machine cycle of the instruction currently being execute.

3. The current instruction does not involve a write to IE, EIE, IP0, IP0H, IP1 or IPH1 registers and is not a RETI.

If any of these conditions are not met, then the LCALL will not be generated. The polling cycle is repeated every machine cycle, with the interrupts sampled in the same machine cycle. If an interrupt flag is active in one cycle but not responded to, and is not active when the above conditions are met, the denied interrupt will not be serviced. This means that active interrupts are not remembered; every polling cycle is new.

The processor responds to a valid interrupt by executing an LCALL instruction to the appropriate service routine. This may or may not clear the flag which caused the interrupt. In case of Timer interrupts, the TF0 or TF1 flags are cleared by hardware whenever the processor vectors to the appropriate timer service routine. In case of external interrupts, $\overline{\text{INT0}}$ and $\overline{\text{INT1}}$, the flags are cleared only if they are edge triggered. In case of Serial interrupts, the flags are not cleared by hardware. The Watchdog timer interrupt flag WDIF has to be cleared by software. The hardware LCALL behaves exactly like the software LCALL instruction. This instruction saves the Program Counter contents onto the Stack, but does not save the Program Status Word PSW. The PC is reloaded with the vector address of that interrupt which caused the LCALL. These address of vector for the different sources are as follows:

VECTOR LOCATIONS FOR INTERRUPT SOURCES

SOURCE	VECTOR ADDRESS	SOURCE	VECTOR ADDRESS
External Interrupt 0	0003h	Timer 0 Overflow	000Bh
External Interrupt 1	0013h	Timer 1 Overflow	001Bh
Serial Port	0023h	Brownout Interrupt	002Bh
I2C Interrupt	0033h	KBI Interrupt	003Bh
Comparator 2 Interrupt	0043h	-	004Bh
Watchdog Timer	0053h	-	005Bh
Comparator 1 Interrupt	0063h	-	006Bh
PWM Brake Interrupt	0073h	-	007Bh

Table 12-1: Vector locations for interrupt sources

Execution continues from the vectored address till an RETI instruction is executed. On execution of the RETI instruction the processor pops the Stack and loads the PC with the contents at the top of the stack. The user must take care that the status of the stack is restored to what it was after the hardware LCALL, if the execution is return to the interrupted program. The processor does not notice anything if the stack contents are modified and will proceed with execution from the address put back into PC. Note that a RET instruction would perform exactly the same process as a RETI instruction, but it would not inform the Interrupt Controller that the interrupt service routine is completed, and would leave the controller still thinking that the service routine is underway.

12.2 Priority Level Structure

The W79E804 series uses a four priority level interrupt structure (highest, high, low and lowest) and supports up to 12 interrupt sources. The interrupt sources can be individually set to either high or low levels. Naturally, a higher priority interrupt cannot be interrupted by a lower priority interrupt. However there exists a pre-defined hierarchy amongst the interrupts themselves. This hierarchy comes into play when the interrupt controller has to resolve simultaneous requests having the same priority level. This hierarchy is defined as table below. This allows great flexibility in controlling and handling many interrupt sources.

PRIORITY BITS		INTERRUPT PRIORITY LEVEL
IPXH	IPX	
0	0	Level 0 (lowest priority)
0	1	Level 1
1	0	Level 2
1	1	Level 3 (highest priority)

Table 12-2: Four-level interrupt priority

Each interrupt source can be individually programmed to one of four priority levels by setting or clearing bits in the IP0, IP0H, IP1, and IP1H registers. An interrupt service routine in progress can be interrupted by a higher priority interrupt, but not by another interrupt of the same or lower priority. The highest priority interrupt service cannot be interrupted by any other interrupt source. So, if two requests of different priority levels are received simultaneously, the request of higher priority level is serviced.

If requests of the same priority level are received simultaneously, an internal polling sequence determines which request is serviced. This is called the arbitration ranking. Note that the arbitration ranking is only used to resolve simultaneous requests of the same priority level.

As below Table summarizes the interrupt sources, flag bits, vector addresses, enable bits, priority bits, arbitration ranking, and whether each interrupt may wake up the CPU from Power Down mode.

SOURCE	FLAG	VECTOR ADDRESS	INTERRUPT ENABLE BITS	INTERRUPT PRIORITY	FLAG CLEARED BY	ARBITRATION RANKING	POWER DOWN WAKEUP
External Interrupt 0	IE0	0003H	EX0 (IE0.0)	IP0H.0, IP0.0	Hardware, Follow the inverse of pin	1(highest)	Yes
Brownout Detect	BOF	002BH	EBO (IE.5)	IP0H.5, IP0.5	Software	2	Yes
Watchdog Timer	WDIF	0053H	EWDI (EIE.4)	IP1H.4, IP1.4	Software	3	Yes(1)

Continued

SOURCE	FLAG	VECTOR ADDRESS	INTERRUPT ENABLE BITS	INTERRUPT PRIORITY	FLAG CLEARED BY	ARBITRATION RANKING	POWER DOWN WAKEUP
Timer 0 Interrupt	TF0	000BH	ET0 (IE.1)	IP0H.1, IP0.1	Hardware, software	4	No
I2C Interrupt	SI	0033H	EI2 (EIE.0)	IP1H.0, IP1.0	Software	5	No
External Interrupt 1	IE1	0013H	EX1 (IE.2)	IP0H.2, IP0.2	Hardware, Follow the inverse of pin	6	Yes
KBI Interrupt	KBF	003BH	EKB (EIE.1)	IP1H.1, IP1.1	Software	7	Yes
Comparator 1 Interrupt	CMF 1	0063H	EC1 (EIE.2)	IP1H.2, IP1.2	Software	8	Yes
Timer 1 Interrupt	TF1	001BH	ET1 (IE.3)	IP0H.3, IP0.3	Hardware, software	9	No
Comparator 2 Interrupt	CMF2	0043H	EC2 (EIE.3)	IP1H.3, IP1.3	Software	10	Yes
Serial Port Tx and Rx	TI & RI	0023H	ES (IE.4)	IP0H.4, IP0.4	Software	11	No
PWM Interrupt	BKF	0073H	EPWM (EIE.5)	IP1H.5, IP1.5	Software	12 (lowest)	No

Note: 1. The Watchdog Timer can wake up Power Down Mode when its clock source is from internal RC.

Table 12-3: Vector location for Interrupt sources and power down wakeup

12.3 Response Time

The response time for each interrupt source depends on several factors, such as the nature of the interrupt and the instruction underway. In the case of external interrupts $\overline{\text{INT0}}$ and $\overline{\text{INT1}}$, they are sampled at C3 of every machine cycle and then their corresponding interrupt flags IEx will be set or reset. The Timer 0 and 1 overflow flags are set at C3 of the machine cycle in which overflow has occurred. These flag values are polled only in the next machine cycle. If a request is active and all three conditions are met, then the hardware generated LCALL is executed. This LCALL itself takes four machine cycles to be completed. Thus there is a minimum time of five machine cycles between the interrupt flag being set and the interrupt service routine being executed.

A longer response time should be anticipated if any of the three conditions are not met. If a higher or equal priority is being serviced, then the interrupt latency time obviously depends on the nature of the service routine currently being executed. If the polling cycle is not the last machine cycle of the instruction being executed, then an additional delay is introduced. The maximum response time (if no other interrupt is in service) occurs if the W79E804 series are performing a write to IE, EIE, IP0, IP0H,

IP1 or IP1H and then executes a MUL or DIV instruction. From the time an interrupt source is activated, the longest reaction time is 12 machine cycles. This includes 1 machine cycle to detect the interrupt, 2 machine cycles to complete the IE, EIE, IP0, IP0H, IP1 or IP1H access, 5 machine cycles to complete the MUL or DIV instruction and 4 machine cycles to complete the hardware LCALL to the interrupt vector location.

Thus in a single-interrupt system the interrupt response time will always be more than 5 machine cycles and not more than 12 machine cycles. The maximum latency of 12 machine cycles is 48 clock cycles. Note that in the standard 8051 the maximum latency is 8 machine cycles which equals 96 machine cycles. This is a 50% reduction in terms of clock periods.

12.4 Interrupt Inputs

The W79E804 series have 12 interrupts source, and two individual interrupt inputs sources, one is for IE0, IE1, BOF, KBF, WDT, CMF1 and CMF2, and other is IF0, IF1, RI+TI ,SI and BKF. Two interrupt inputs are identical to those present on the standard 80C51 microcontroller as show in below figures.

If an external interrupt is enabled when the W79E804 series are put into Power Down or Idle mode, the interrupt will cause the processor to wake up and resume operation.

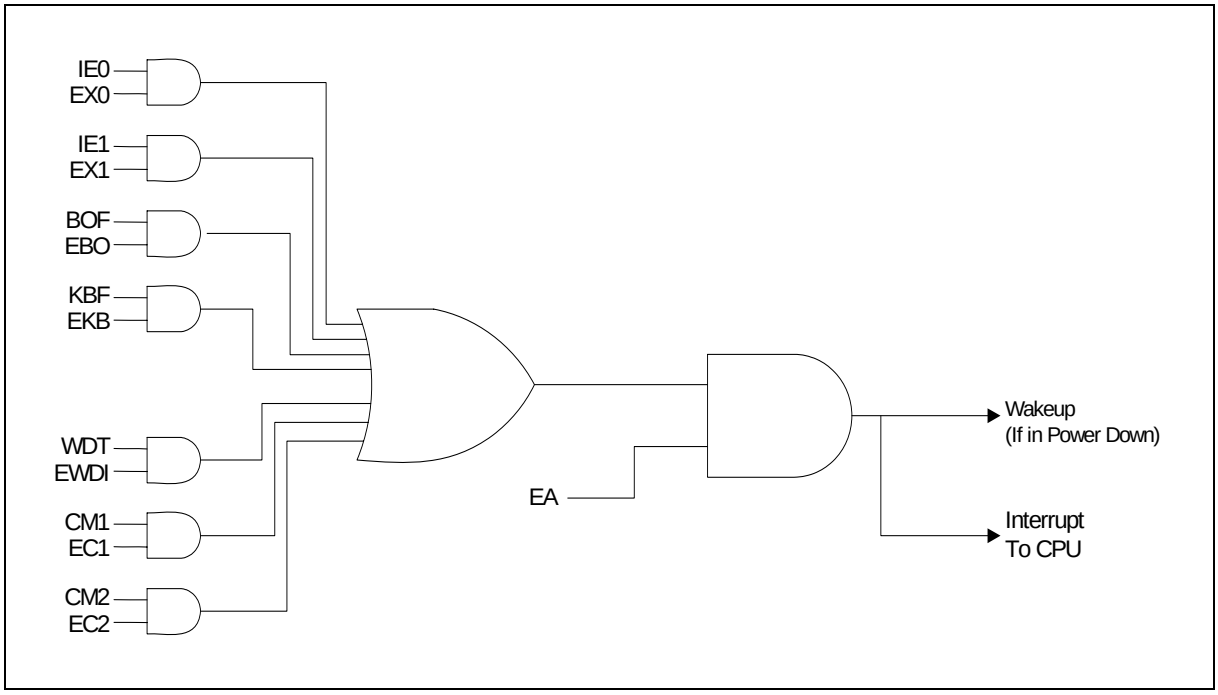


Figure 12-1: Interrupt Sources that can wake up from Power Down Mode

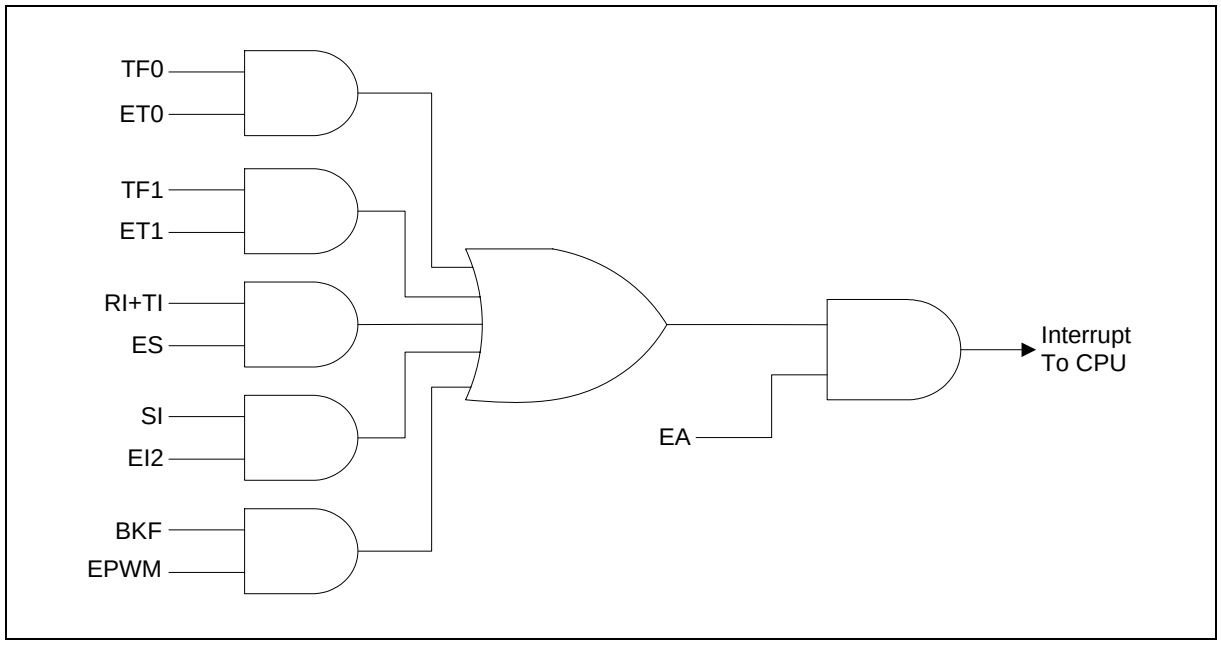


Figure 12-2: Interrupt Sources that cannot wake up from Power Down Mode

13. PROGRAMMABLE TIMERS/COUNTERS

The W79E804 series have two 16-bit programmable timer/counters and one programmable Watchdog Timer. The Watchdog Timer is operationally quite different from the other two timers. It's timer/counters have additional timer 0 or timer 1 overflow toggle output enable feature as compare to conventional timer/counters. This timer overflow toggle output can be configured to automatically toggle T0 or T1 pin output whenever a timer overflow occurs.

13.1 Timer/Counters 0 & 1

The W79E804 series have two 16-bit Timer/Counters. Each of these Timer/Counters has two 8 bit registers which form the 16 bit counting register. For Timer/Counter 0 they are TH0, the upper 8 bits register, and TL0, the lower 8 bit register. Similarly Timer/Counter 1 has two 8 bit registers, TH1 and TL1. The two can be configured to operate either as timers, counting machine cycles or as counters counting external inputs.

When configured as a "Timer", the timer counts clock cycles. The timer clock can be programmed to be thought of as 1/12 of the system clock or 1/4 of the system clock. In the "Counter" mode, the register is incremented on the falling edge of the external input pin, T0 for Timer 0, and T1 for Timer 1. The T0 and T1 inputs are sampled in every machine cycle at C4. If the sampled value is high in one machine cycle and low in the next, then a valid high to low transition on the pin is recognized and the count register is incremented. Since it takes two machine cycles to recognize a negative transition on the pin, the maximum rate at which counting will take place is 1/8 of the master clock frequency. In either the "Timer" or "Counter" mode, the count register will be updated at C3. Therefore, in the "Timer" mode, the recognized negative transition on pin T0 and T1 can cause the count register value to be updated only in the machine cycle following the one in which the negative edge was detected.

The "Timer" or "Counter" function is selected by the "$C/\overline{T}$" bit in the TMOD Special Function Register. Each Timer/Counter has one selection bit for its own; bit 2 of TMOD selects the function for Timer/Counter 0 and bit 6 of TMOD selects the function for Timer/Counter 1. In addition each Timer/Counter can be set to operate in any one of four possible modes. The mode selection is done by bits M0 and M1 in the TMOD SFR.

13.1.1 Time-Base Selection

The W79E804 series can operate like the standard 8051/52 family, counting at the rate of 1/12 of the clock speed, or in turbo mode, counting at the rate of 1/4 clock speed. The speed is controlled by the T0M and T1M bits in CKCON, and the default value is zero, which uses the standard 8051/52 speed.

13.1.2 Mode 0

In Mode 0, the timer/counter is a 13-bit counter. The 13-bit counter consists of THx (8 MSB) and the five lower bits of TLx (5 LSB). The upper three bits of TLx are ignored. The timer/counter is enabled when TRx is set and either GATE is 0 or $\overline{INTx}$ is 1. When $C/\overline{T}$ is 0, the timer/counter counts clock cycles; when $C/\overline{T}$ is 1, it counts falling edges on T0 (P1.2 for Timer 0) or T1 (P0.7 for Timer 1). For clock cycles, the time base may be 1/12 or 1/4 clock speed, and the falling edge of the clock increments the counter. When the 13-bit value moves from 1FFFh to 0000h, the timer overflow flag TFx is set, and an interrupt occurs if enabled. This is illustrated in next figure below.

In "Timer" mode, if output toggle enable bit of P2M1.T0OE or P2M1.T1OE is enabled, T0 or T1 output pin will toggle whenever a timer overflow occurs.

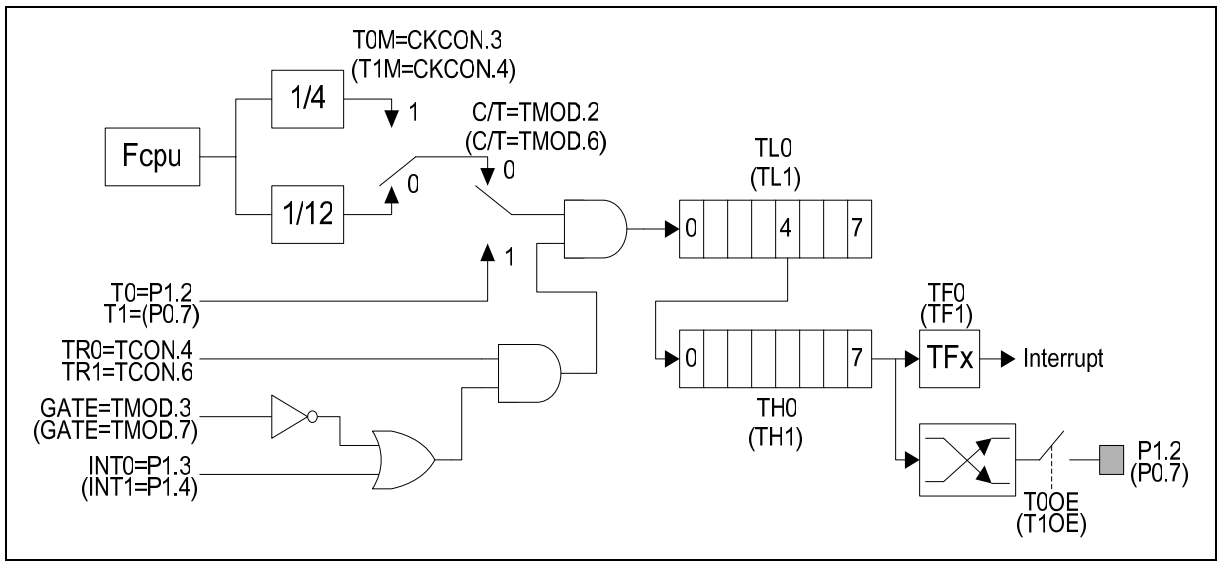


Figure 13-1: Timer/Counters 0 & 1 in Mode 0

13.1.3 Mode 1

Mode 1 is similar to Mode 0 except that the counting register forms a 16-bit counter, rather than a 13-bit counter. This means that all the bits of THx and TLx are used. Roll-over occurs when the timer moves from a count of FFFFh to 0000h. The timer overflow flag TFx of the relevant timer is set and if enabled an interrupt will occur. The selection of the time-base in the timer mode is similar to that in Mode 0. The gate function operates similarly to that in Mode 0.

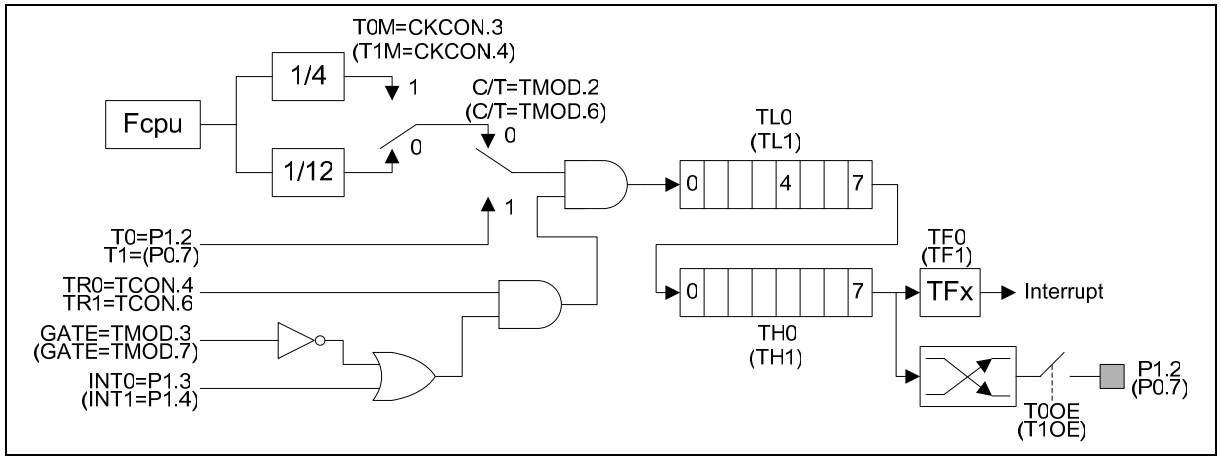


Figure 13-2: Timer/Counters 0 & 1 in Mode 1

13.1.4 Mode 2

In Mode 2, the timer/counter is in the Auto Reload Mode. In this mode, TLx acts as 8-bit count register, while THx holds the reload value. When the TLx register overflows from FFh to 00h, the TFx bit in TCON is set and TLx is reloaded with the contents of THx, and the counting process continues from here. The reload operation leaves the contents of the THx register unchanged. Counting is enabled by the TRx bit and proper setting of GATE and $\overline{\text{INTx}}$ pins. As in the other two modes 0 and 1 mode 2 allows counting of either clock cycles (clock/12 or clock/4) or pulses on pin Tn.

In "Timer" mode, if output toggle enable bit of P2M1.T0OE or P2M1.T1OE is enabled, T0 or T1 output pin will toggle whenever a timer overflow occurs.

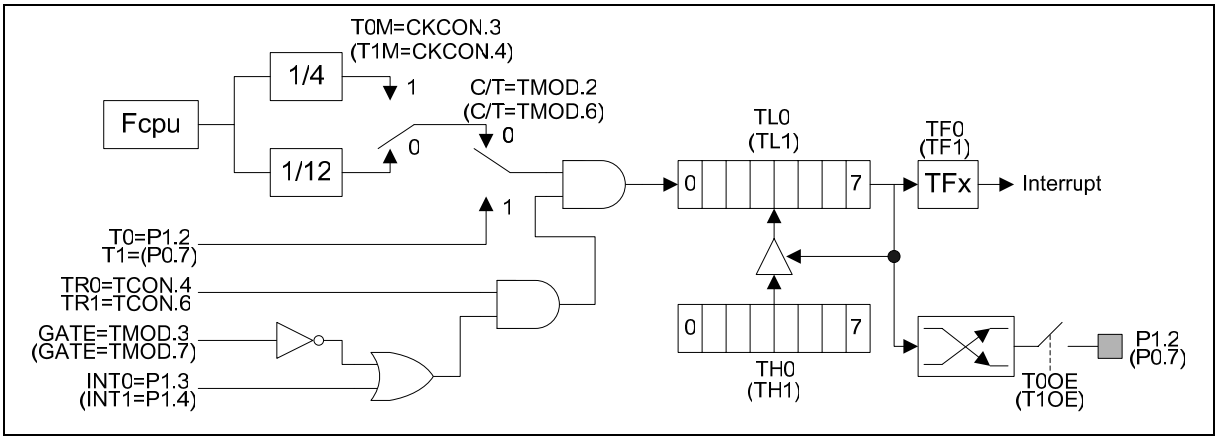


Figure 13-3: Timer/Counter 0 & 1 in Mode 2

13.1.5 Mode 3

Mode 3 has different operating methods for the two timer/counters. For timer/counter 1, mode 3 simply freezes the counter. Timer/Counter 0, however, configures TL0 and TH0 as two separate 8 bit count registers in this mode. The logic for this mode is shown in the figure. TL0 uses the Timer/Counter 0 control bits $C/\overline{T}$, GATE, TR0, $\overline{\text{INT0}}$ and TF0. The TL0 can be used to count clock cycles (clock/12 or clock/4) or 1-to-0 transitions on pin T0 as determined by C/T (TMOD.2). TH0 is forced as a clock cycle counter (clock/12 or clock/4) and takes over the use of TR1 and TF1 from Timer/Counter 1. Mode 3 is used in cases where an extra 8 bit timer is needed. With Timer 0 in Mode 3, Timer 1 can still be used in Modes 0, 1 and 2, but its flexibility is somewhat limited. While its basic functionality is maintained, it no longer has control over its overflow flag TF1 and the enable bit TR1. Timer 1 can still be used as a timer/counter and retains the use of GATE and INT1 pin. In this condition it can be turned on and off by switching it out of and into its own Mode 3. It can also be used as a baud rate generator for the serial port.

In "Timer" mode, if output toggle enable bit of P2M1.T0OE or P2M1.T1OE is enabled, T0 or T1 output pin will toggle whenever a timer overflow occurs.

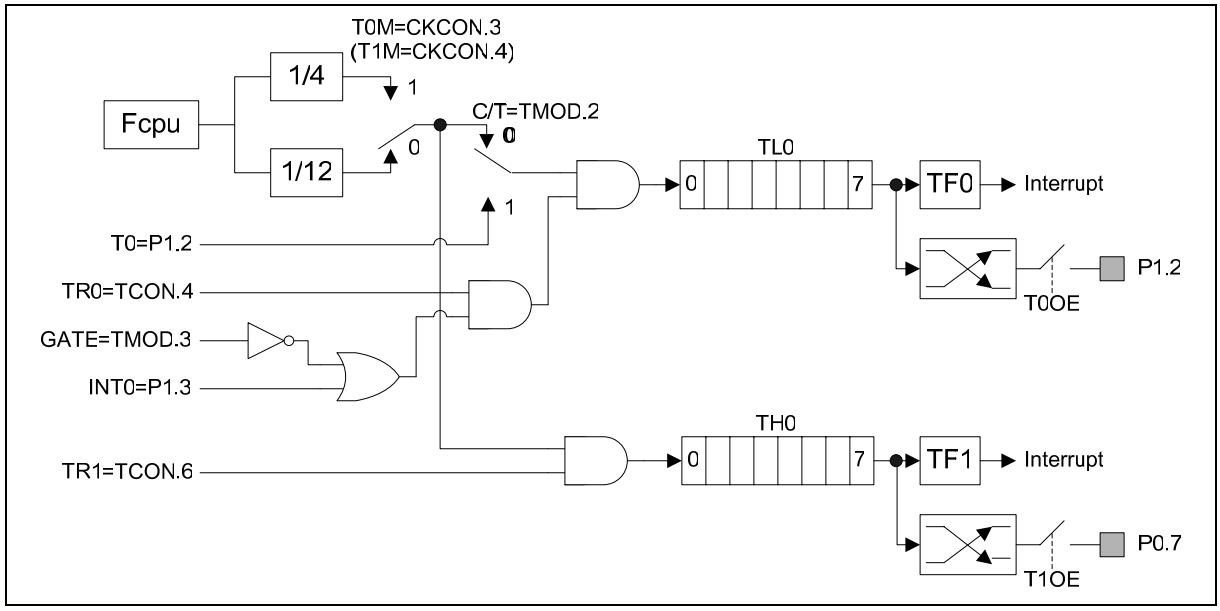


Figure 13-4: Timer/Counter Mode 3

14. NVM MEMORY

The W79E804 series have NVM data memory of **256** bytes for customer's data store used. The NVM data memory has **four** pages area and each page has 64 bytes as below figure. The **Page 0** address is from **FC00h ~ FC3Fh**, **Page 1** address is from **FC40h ~ FC7Fh**, **Page 2** address is from **FC80h ~ FCBFh**, and **Page 3** address is from **FCC0h ~ FCFFh**.

The NVM memory can be read/write by customer program to access. Read NVM data is by MOVC A,@A+DPTR instruction, and write data is by SFR of NVMADDR, NVMDAT and NVMCON. Before write data to NVM memory, the page must be erased by providing page address on NVMADDR, which low byte address of On-Chip Code Memory space will decode, then set EER of NVMCON.7. This will automatically hold fetch program code and PC Counter, and execute page erase. After finished, this bit will be cleared by hardware. The erase time is ~ 5ms.

For writing data to NVM memory, user must set address and data to NVMADDR and NVMDAT, then set EWR of NVMCON.6 to initiate nvm data write. The uC will hold program code and PC Counter, and then write data to mapping address. Upon write completion, the EWR bit will be cleared by hardware, the uC will continue execute next instruction. The program time is ~50us.

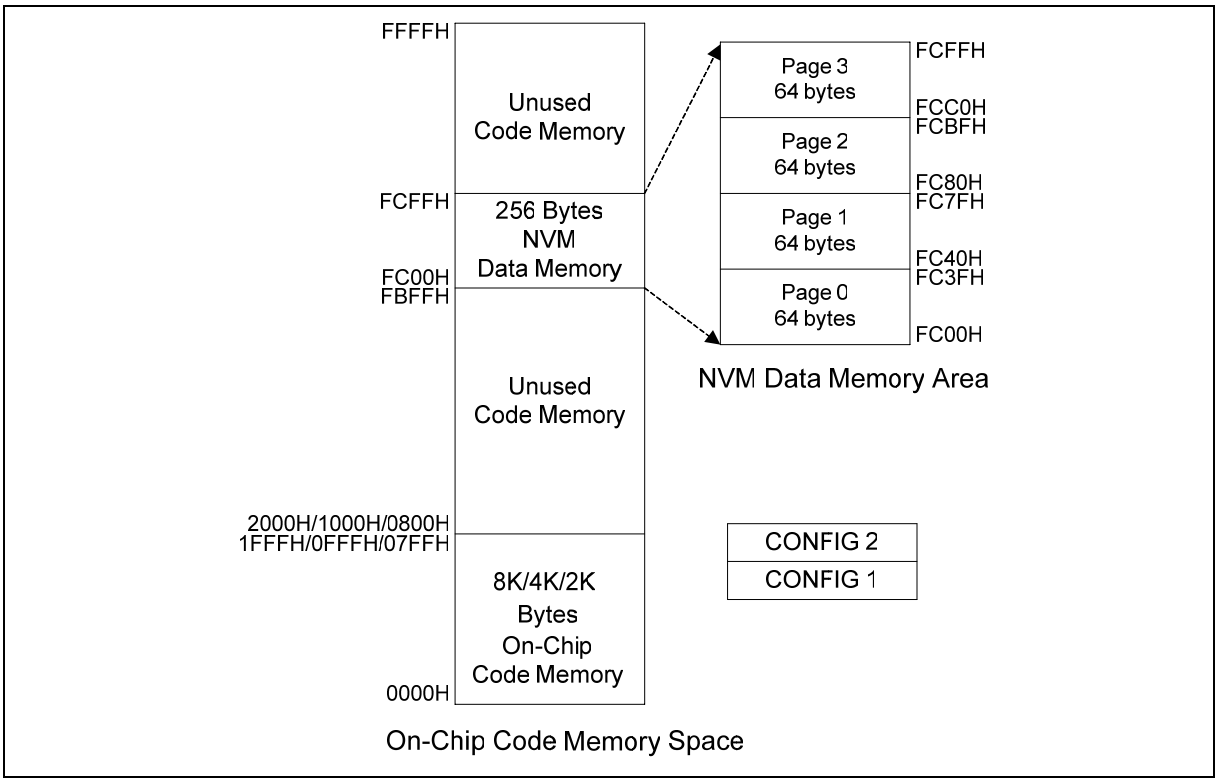


Figure 14-1: W79E804/803/802 Memory Map

15. WATCHDOG TIMER

The Watchdog Timer is a free-running Timer which can be programmed by the user to serve as a system monitor, a time-base generator or an event timer. It is basically a set of dividers that divide the system clock. The divider output is selectable and determines the time-out interval. When the time-out occurs a flag is set, which can cause an interrupt if enabled, and a system reset can also be caused if it is enabled. The interrupt will occur if the individual interrupt enable and the global enable are set. The interrupt and reset functions are independent of each other and may be used separately or together depending on the user's software.

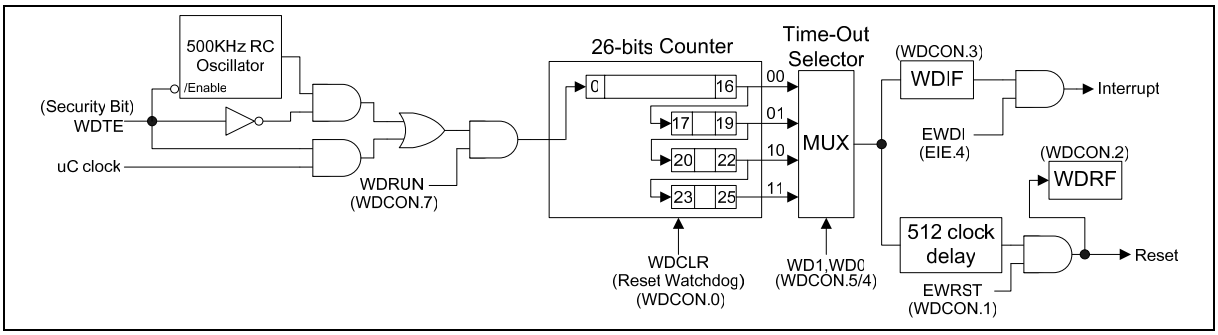


Figure 15-1: Watchdog Timer

The Watchdog Timer should first be restarted by using WDCLR. This ensures that the timer starts from a known state. The WDCLR bit is used to restart the Watchdog Timer. This bit is self clearing, i.e. after writing a 1 to this bit the software will automatically clear it. The Watchdog Timer will now count clock cycles. The time-out interval is selected by the two bits WD1 and WD0 (WDCON.5 and WDCON.4). When the selected time-out occurs, the Watchdog interrupt flag WDIF (WDCON.3) is set. After the time-out has occurred, the Watchdog Timer waits for an additional 512 clock cycles. If the Watchdog Reset EWRST (WDCON.1) is enabled, then 512 clocks after the time-out, if there is no WDCLR, a system reset due to Watchdog Timer will occur. This will last for two machine cycles, and the Watchdog Timer reset flag WTRF (WDCON.2) will be set. This indicates to the software that the Watchdog was the cause of the reset.

When used as a simple timer, the reset and interrupt functions are disabled. The timer will set the WDIF flag each time the timer completes the selected time interval. The WDIF flag is polled to detect a time-out and the WDCLR allows software to restart the timer. The Watchdog Timer can also be used as a very long timer. The interrupt feature is enabled in this case. Every time the time-out occurs an interrupt will occur if the global interrupt enable EA is set.

The main use of the Watchdog Timer is as a system monitor. This is important in real-time control applications. In case of some power glitches or electro-magnetic interference, the processor may begin to execute errant code. If this is left unchecked the entire system may crash. Using the watchdog timer interrupt during software development will allow the user to select ideal watchdog reset locations. The code is first written without the watchdog interrupt or reset. Then the Watchdog interrupt is enabled to identify code locations where interrupt occurs. The user can now insert instructions to reset the Watchdog Timer, which will allow the code to run without any Watchdog Timer interrupts. Now the Watchdog Timer reset is enabled and the Watchdog interrupt may be disabled. If

any errant code is executed now, then the reset Watchdog Timer instructions will not be executed at the required instants and Watchdog reset will occur.

The Watchdog Timer time-out selection will result in different time-out values depending on the clock speed. The reset, when enabled, will occur when 512 clocks after time-out has occurred.

WD1	WD0	INTERRUPT TIME-OUT	RESET TIME-OUT	NUMBER OF CLOCKS	TIME @ 10 MHZ
0	0	2^{17}	2^{17} + 512	131072	13.11 mS
0	1	2^{20}	2^{20} + 512	1048576	104.86 mS
1	0	2^{23}	2^{23} + 512	8388608	838.86 mS
1	1	2^{26}	2^{26} + 512	67108864	6710.89 mS

Table 15-2: Time-out values for the Watchdog Timer

The Watchdog Timer will be disabled by a power-on/fail reset. The Watchdog Timer reset does not disable the Watchdog Timer, but will restart it. In general, software should restart the timer to put it into a known state. The control bits that support the Watchdog Timer are discussed below.

15.1 WATCHDOG CONTROL

WDIF: WDCON.3 - Watchdog Timer Interrupt flag. This bit is set whenever the time-out occurs in the Watchdog Timer. If the Watchdog interrupt is enabled (EIE.4), then an interrupt will occur (if the global interrupt enable is set and other interrupt requirements are met). Software or any reset can clear this bit.

WTRF: WDCON.2 - Watchdog Timer Reset flag. This bit is set whenever a watchdog reset occurs. This bit is useful for determined the cause of a reset. Software must read it, and clear it manually. A Power-fail reset will clear this bit. If EWRST = 0, then this bit will not be affected by the Watchdog Timer.

EWRST: WDCON.1 - Enable Watchdog Timer Reset. This bit when set to 1 will enable the Watchdog Timer reset function. Setting this bit to 0 will disable the Watchdog Timer reset function, but will leave the timer running.

WDCLR: WDCON.0 - Reset Watchdog Timer. This bit is used to clear the Watchdog Timer and to restart it. This bit is self-clearing, so after the software writes 1 to it the hardware will automatically clear it. If the Watchdog Timer reset is enabled, then the WDCLR has to be set by the user within 512 clocks of the time-out. If this is not done then a Watchdog Timer reset will occur.

15.2 CLOCK CONTROL of Watchdog

WD1, WD0: WDCON.5, WDCON.4 - Watchdog Timer Mode select bits. These two bits select the time-out interval for the watchdog timer. The reset time is 512 clocks longer than the interrupt time-out value.

The default Watchdog time-out is 2^{17} clocks, which is the shortest time-out period. The EWRST, WDIF and WDCLR bits are protected by the Timed Access procedure. This prevents software from accidentally enabling or disabling the watchdog timer. More importantly, it makes it highly improbable that errant code can enable or disable the Watchdog Timer.

The security bit WDTE is located at bit 7 of CONFIG register. This bit is user to configure the clock source of watchdog timer either it is from the internal RC or from the uC clock.

When WDTE bit is cleared and 500KHz clock is used to run the watchdog timer, there is a chance that the watchdog timer would hang as the counter does not increment. This problem arises when the watchdog is set to run, (WDCON.7, WDRUN), the WDCLR bit (WDCON.0) is set to clear the watchdog timer and the next instruction is to set the PCON register for CPU to go into idle or power-down state. The reason this happens because the setting/clearing of WDCLR bit and the watchdog counter are running on different clock domains, CPU clock and internal RC clock respectively. When WDCLR bit is set, to reset it, the counter must be non-zero. Since the counter is running off a much slower clock, the counter may not have time to increment before the CPU clock halts as it entered the idle/power-down mode. This results in the WDCLR bit is always set & the watchdog counter remaining at zero. The solution to this problem is to monitor the WDCLR bit, ensuring that it's cleared before issue the instruction for the CPU to go into idle/power-down mode.

16. SERIAL PORT (UART)

Serial port in the W79E804 series is a full duplex port. The W79E804 series provide the user with additional features such as the Frame Error Detection and the Automatic Address Recognition. The serial ports are capable of synchronous as well as asynchronous communication. In Synchronous mode the W79E804 series generate the clock and operates in a half duplex mode. In the asynchronous mode, full duplex operation is available. This means that it can simultaneously transmit and receive data. The transmit register and the receive buffer are both addressed as SBUF Special Function Register. However any write to SBUF will be to the transmit register, while a read from SBUF will be from the receiver buffer register. The serial port can operate in four different modes as described below.

16.1 MODE 0

This mode provides synchronous communication with external devices. In this mode serial data is transmitted and received on the RXD line. TXD is used to transmit the shift clock. The TxD clock is provided by the W79E804 series whether the device is transmitting or receiving. This mode is therefore a half duplex mode of serial communication. In this mode, 8 bits are transmitted or received per frame. The LSB is Transmitted/Received first. The baud rate is fixed at 1/12 or 1/4 of the oscillator frequency. This Baud Rate is determined by the SM2 bit (SCON.5). When this bit is set to 0, then the serial port runs at 1/12 of the clock. When set to 1, the serial port runs at 1/4 of the clock. This additional facility of programmable baud rate in mode 0 is the only difference between the standard 8051 and the W79E804 series.

The functional block diagram is shown below. Data enters and leaves the Serial port on the RxD line. The TxD line is used to output the shift clock. The shift clock is used to shift data into and out of the W79E804 series and the device at the other end of the line. Any instruction that causes a write to SBUF will start the transmission. The shift clock will be activated and data will be shifted out on the RxD pin till all 8 bits are transmitted. If SM2 = 1, then the data on RxD will appear 1 clock period before the falling edge of shift clock on TxD. The clock on TxD then remains low for 2 clock periods, and then goes high again. If SM2 = 0, the data on RxD will appear 3 clock periods before the falling edge of shift clock on TxD. The clock on TxD then remains low for 6 clock periods, and then goes high again. This ensures that at the receiving end the data on RxD line can either be clocked on the rising edge of the shift clock on TxD or latched when the TxD clock is low.

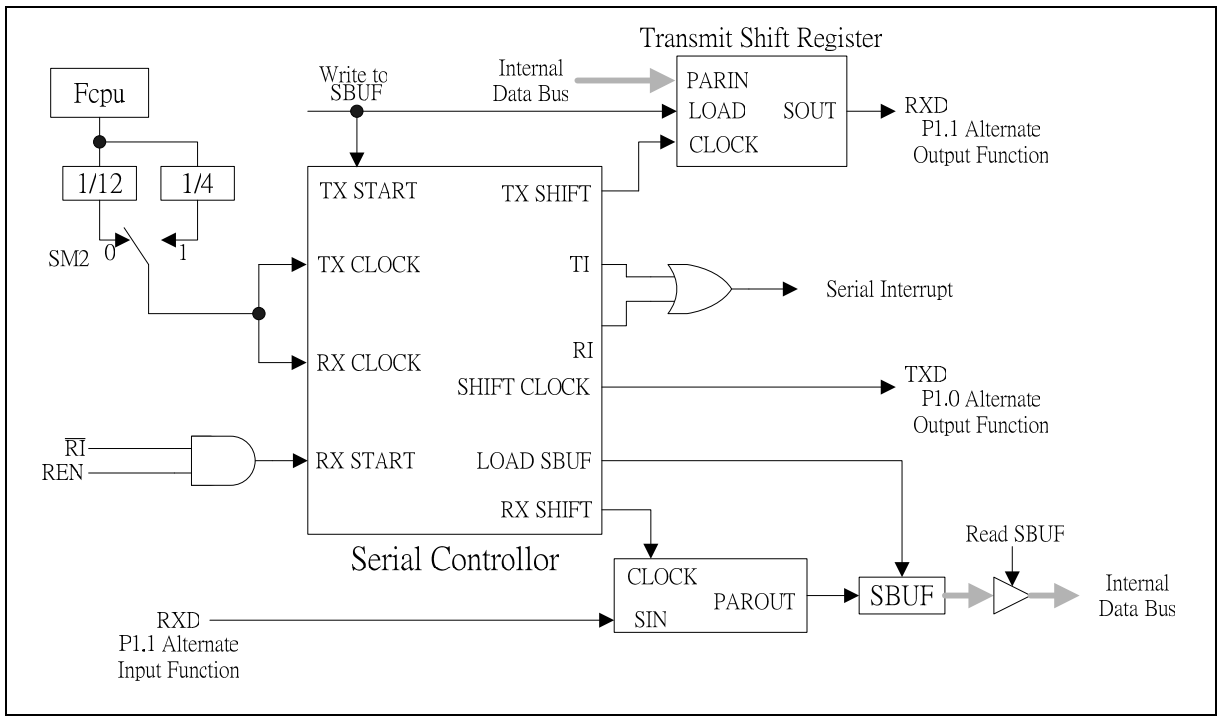


Figure 16-1: Serial Port Mode 0

The TI flag is set high in C1 following the end of transmission of the last bit. The serial port will receive data when REN is 1 and RI is zero. The shift clock (TxD) will be activated and the serial port will latch data on the rising edge of shift clock. The external device should therefore present data on the falling edge on the shift clock. This process continues till all the 8 bits have been received. The RI flag is set in C1 following the last rising edge of the shift clock on TxD. This will stop reception, till the RI is cleared by software.

16.2 MODE 1

In Mode 1, the full duplex asynchronous mode is used. Serial communication frames are made up of 10 bits transmitted on TXD and received on RXD. The 10 bits consist of a start bit (0), 8 data bits (LSB first), and a stop bit (1). On received, the stop bit goes into RB8 in the SFR SCON. The baud rate in this mode is variable. The serial baud can be programmed to be 1/16 or 1/32 of the Timer 1 overflow. Since the Timer 1 can be set to different reload values, a wide variation in baud rates is possible.

Transmission begins with a write to SBUF. The serial data is brought out on to TxD pin at C1 following the first roll-over of divide-by-16 counter. The next bit is placed on TxD pin at C1 following the next rollover of the divide-by-16 counter. Thus the transmission is synchronized to the divide-by-16 counter and not directly to the write to SBUF signal. After all 8 bits of data are transmitted, the stop bit is transmitted. The TI flag is set in the C1 state after the stop bit has been put out on TxD pin. This will be at the 10th rollover of the divide-by-16 counter after a write to SBUF.

Reception is enabled only if REN is high. The serial port actually starts the receiving of serial data,

with the detection of a falling edge on the RxD pin. The 1-to-0 detector continuously monitors the RxD line, sampling it at the rate of 16 times the selected baud rate. When a falling edge is detected, the divide–by-16 counter is immediately reset. This helps to align the bit boundaries with the rollovers of the divide-by-16 counter.

The 16 states of the counter effectively divide the bit time into 16 slices. The bit detection is done on a best of three bases. The bit detector samples the RxD pin, at the 8th, 9th and 10th counter states. By using a majority 2 of 3 voting system, the bit value is selected. This is done to improve the noise rejection feature of the serial port. If the first bit detected after the falling edge of RxD pin is not 0, then this indicates an invalid start bit, and the reception is immediately aborted. The serial port again looks for a falling edge in the RxD line. If a valid start bit is detected, then the rest of the bits are also detected and shifted into the SBUF.

After shifting in 8 data bits, there is one more shift to do, after which the SBUF and RB8 are loaded and RI is set. However certain conditions must be met before the loading and setting of RI can be done.

1. RI must be 0 and
2. Either SM2 = 0, or the received stop bit = 1.

If these conditions are met, then the stop bit goes to RB8, the 8 data bits go into SBUF and RI is set. Otherwise the received frame may be lost. After the middle of the stop bit, the receiver goes back to looking for a 1-to-0 transition on the RxD pin.

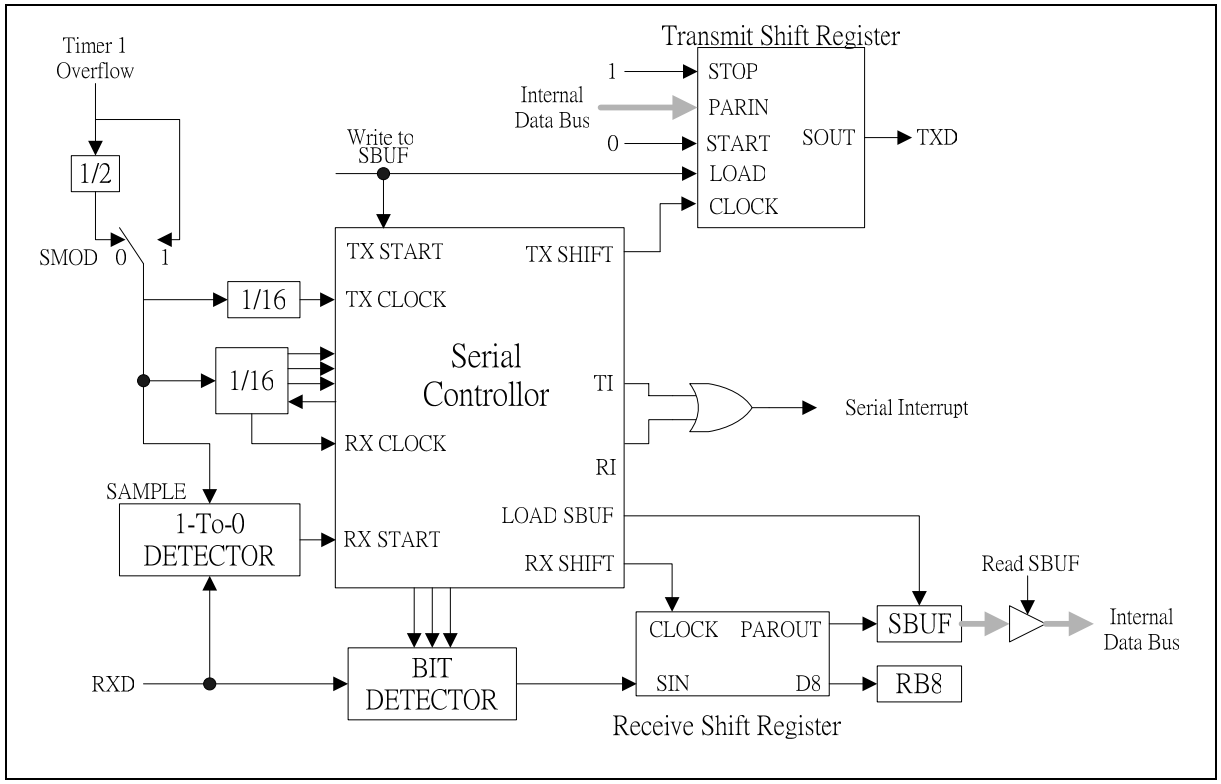


Figure 16-2: Serial Port Mode 1

16.3 MODE 2

This mode uses a total of 11 bits in asynchronous full-duplex communication. The functional description is shown in the figure below. The frame consists of one start bit (0), 8 data bits (LSB first), a programmable 9th bit (TB8) and a stop bit (0). The 9th bit received is put into RB8. The baud rate is programmable to 1/32 or 1/64 of the oscillator frequency, which is determined by the SMOD bit in PCON SFR. Transmission begins with a write to SBUF. The serial data is brought out on to TxD pin at C1 following the first roll-over of the divide-by-16 counter. The next bit is placed on TxD pin at C1 following the next rollover of the divide-by-16 counter. Thus the transmission is synchronized to the divide-by-16 counter, and not directly to the write to SBUF signal. After all 9 bits of data are transmitted, the stop bit is transmitted. The TI flag is set in the C1 state after the stop bit has been put out on TxD pin. This will be at the 11th rollover of the divide-by-16 counter after a write to SBUF. Reception is enabled only if REN is high. The serial port actually starts the receiving of serial data, with the detection of a falling edge on the RxD pin. The 1-to-0 detector continuously monitors the RxD line, sampling it at the rate of 16 times the selected baud rate. When a falling edge is detected, the divide- by-16 counter is immediately reset. This helps to align the bit boundaries with the rollovers of the divide-by-16 counter. The 16 states of the counter effectively divide the bit time into 16 slices. The bit detection is done on a best of three bases. The bit detector samples the RxD pin, at the 8th, 9th and 10th counter states. By using a majority 2 of 3 voting system, the bit value is selected. This is done to improve the noise rejection feature of the serial port.

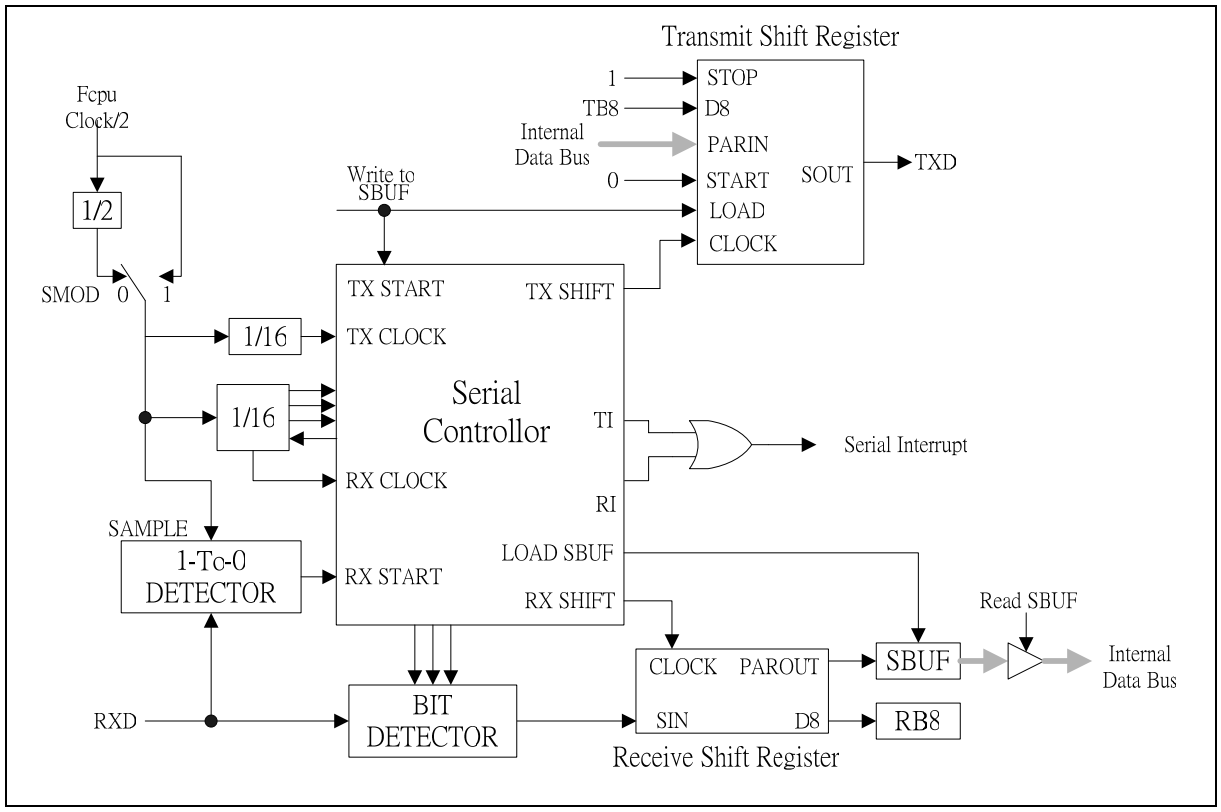


Figure 16-3: Serial Port Mode 2

If the first bit detected after the falling edge of RxD pin, is not 0, then this indicates an invalid start bit, and the reception is immediately aborted. The serial port again looks for a falling edge in the RxD line. If a valid start bit is detected, then the rest of the bits are also detected and shifted into the SBUF. After shifting in 9 data bits, there is one more shift to do, after which the SBUF and RB8 are loaded and RI is set. However certain conditions must be met before the loading and setting of RI can be done.

1. RI must be 0 and

2. Either SM2 = 0, or the received stop bit = 1.

If these conditions are met, then the stop bit goes to RB8, the 8 data bits go into SBUF and RI is set. Otherwise the received frame may be lost. After the middle of the stop bit, the receiver goes back to looking for a 1-to-0 transition on the RxD pin.

16.4 MODE 3

This mode is similar to Mode 2 in all aspects, except that the baud rate is programmable. The user must first initialize the Serial related SFR SCON before any communication can take place. This involves selection of the Mode and baud rate. The Timer 1 should also be initialized if modes 1 and 3 are used. In all four modes, transmission is started by any instruction that uses SBUF as a destination register. Reception is initiated in Mode 0 by the condition RI = 0 and REN = 1. This will generate a clock on the TxD pin and shift in 8 bits on the RxD pin. Reception is initiated in the other modes by the incoming start bit if REN = 1. The external device will start the communication by transmitting the start bit.

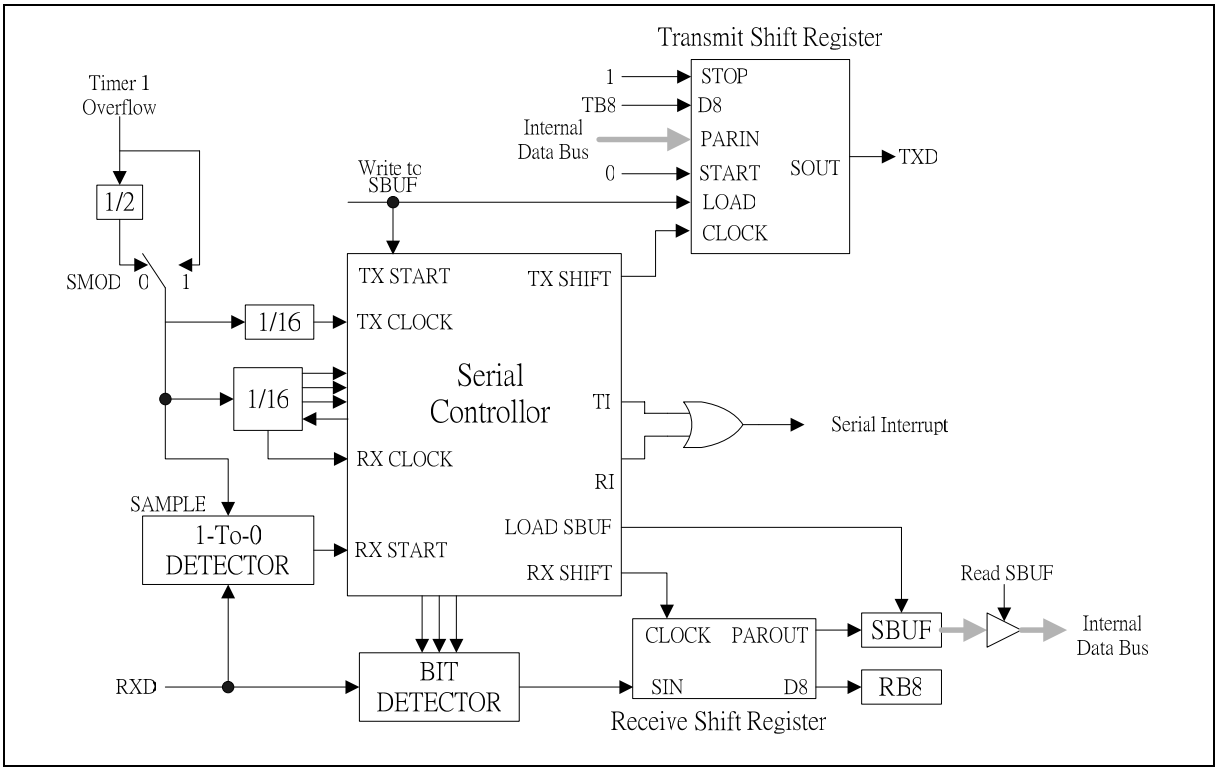


Figure 16-4: Serial Port Mode 3

SM0	SM1	MODE	TYPE	BAUD CLOCK	FRAME SIZE	START BIT	STOP BIT	9TH BIT FUNCTION
0	0	0	Synch.	4 or 12 TCLKS	8 bits	No	No	None
0	1	1	Asynch.	Timer 1	10 bits	1	1	None
1	0	2	Asynch.	32 or 64 TCLKS	11 bits	1	1	0, 1
1	1	3	Asynch.	Timer 1	11 bits	1	1	0, 1

Table 16-5: Serial Port Mode Summary Table

16.5 Framing Error Detection

A Frame Error occurs when a valid stop bit is not detected. This could indicate incorrect serial data communication. Typically the frame error is due to noise and contention on the serial communication line. The W79E804 series have the facility to detect such framing errors and set a flag which can be checked by software.

The Frame Error FE bit is located in SCON.7. This bit is normally used as SM0 in the standard 8051 family. However, in the W79E804 series it serves a dual function and is called SM0/FE. There are actually two separate flags, one for SM0 and the other for FE. The flag that is actually accessed as SCON.7 is determined by SMOD0 (PCON.6) bit. When SMOD0 is set to 1, then the FE flag is indicated in SM0/FE. When SMOD0 is set to 0, then the SM0 flag is indicated in SM0/FE.

The FE bit is set to 1 by hardware but must be cleared by software. Note that SMOD0 must be 1 while reading or writing to FE. If FE is set, then any following frames received without any error will not clear the FE flag. The clearing has to be done by software.

16.6 Multiprocessor Communications

Multiprocessor communications makes use of the 9th data bit in modes 2 and 3. In the W79E804 series, the RI flag is set only if the received byte corresponds to the Given or Broadcast address. This hardware feature eliminates the software overhead required in checking every received address, and greatly simplifies the software programmer task.

In the multiprocessor communication mode, the address bytes are distinguished from the data bytes by transmitting the address with the 9th bit set high. When the master processor wants to transmit a block of data to one of the slaves, it first sends out the address of the targeted slave (or slaves). All the slave processors should have their SM2 bit set high when waiting for an address byte. This ensures that they will be interrupted only by the reception of an address byte. The Automatic address recognition feature ensures that only the addressed slave will be interrupted. The address comparison is done in hardware not software.

The addressed slave clears the SM2 bit, thereby clearing the way to receive data bytes. With SM2 = 0, the slave will be interrupted on the reception of every single complete frame of data. The unaddressed slaves will be unaffected, as they will be still waiting for their address. In Mode 1, the 9th bit is the stop bit, which is 1 in case of a valid frame. If SM2 is 1, then RI is set only if a valid frame is received and the received byte matches the Given or Broadcast address.

The Master processor can selectively communicate with groups of slaves by using the Given Address. All the slaves can be addressed together using the Broadcast Address. The addresses for each slave are defined by the SADDR and SADEN SFRs. The slave address is an 8-bit value specified in the SADDR SFR. The SADEN SFR is actually a mask for the byte value in SADDR. If a bit position in SADEN is 0, then the corresponding bit position in SADDR is don't care. Only those bit positions in SADDR whose corresponding bits in SADEN are 1 are used to obtain the Given Address. This gives the user flexibility to address multiple slaves without changing the slave address in SADDR.

The following example shows how the user can define the Given Address to address different slaves.

Slave 1:

SADDR 1010 0100
SADEN 1111 1010
Given 1010 0x0x

Slave 2:

SADDR 1010 0111
SADEN 1111 1001
Given 1010 0xx1

The Given address for slave 1 and 2 differ in the LSB. For slave 1, it is a don't care, while for slave 2 it is 1. Thus to communicate only with slave 1, the master must send an address with LSB = 0 (1010 0000). Similarly the bit 1 position is 0 for slave 1 and don't care for slave 2. Hence to communicate only with slave 2 the master has to transmit an address with bit 1 = 1 (1010 0011). If the master wishes to communicate with both slaves simultaneously, then the address must have bit 0 = 1 and bit 1 = 0. The bit 3 position is don't care for both the slaves. This allows two different addresses to select both slaves (1010 0001 and 1010 0101).

The master can communicate with all the slaves simultaneously with the Broadcast Address. This address is formed from the logical OR of the SADDR and SADEN SFRs. The zeros in the result are defined as don't cares. In most cases the Broadcast Address is FFh. In the previous case, the Broadcast Address is (1111111x) for slave 1 and (11111111) for slave 2.

The SADDR and SADEN SFRs are located at address A9h and B9h respectively. On reset, these two SFRs are initialized to 00h. This results in Given Address and Broadcast Address being set as xxxx xxxx (i.e. all bits don't care). This effectively removes the multiprocessor communications feature, since any selectivity is disabled.

17. TIME ACCESS PROCTECTION

The W79E804 series have a new feature, like the Watchdog Timer which is a crucial to proper operation of the system. If left unprotected, errant code may write to the Watchdog control bits resulting in incorrect operation and loss of control. In order to prevent this, the W79E804 series have a protection scheme which controls the write access to critical bits. This protection scheme is done using a timed access.

In this method, the bits which are to be protected have a timed write enable window. A write is successful only if this window is active, otherwise the write will be discarded. This write enable window is open for 3 machine cycles if certain conditions are met. After 3 machine cycles, this window automatically closes. The window is opened by writing AAh and immediately 55h to the Timed Access (TA) SFR. This SFR is located at address C7h. The suggested code for opening the timed access window is

```
TA      REG   0C7h              ;Define new register TA, located at 0C7h
        MOV   TA, #0AAh
        MOV   TA, #055h
```

When the software writes AAh to the TA SFR, a counter is started. This counter waits for 3 machine cycles looking for a write of 55h to TA. If the second write (55h) occurs within 3 machine cycles of the first write (AAh), then the timed access window is opened. It remains open for 3 machine cycles, during which the user may write to the protected bits. Once the window closes the procedure must be repeated to access the other protected bits.

Examples of Timed Assessing are shown below.

Example 1: Valid access

```
        MOV     TA, #0AAh           ;3 M/C  Note: M/C = Machine Cycles
        MOV     TA, #055h           ;3 M/C
        MOV     WDCON, #00h         ;3 M/C
```

Example 2: Valid access

```
        MOV     TA, #0AAh           ;3 M/C
        MOV     TA, #055h           ;3 M/C
        NOP                         ;1 M/C
        SETB    EWRST               ;2 M/C
```

Example 3: Valid access

```
        MOV     TA, #0AAh           ;3 M/C
        MOV     TA, #055h           ;3 M/C
        ORL     WDCON, #00000010B   ;3M/C
```

Example 4: Invalid access

```
        MOV     TA, #0AAh           ;3 M/C
        MOV     TA, #055h           ;3 M/C
        NOP                         ;1 M/C
        NOP                         ;1 M/C
        CLR     EWT                 ;2 M/C
```

Example 5: Invalid Access

```
MOV     TA, #0AAh       ;3 M/C
NOP                     ;1 M/C
MOV     TA, #055h       ;3 M/C
SETB    EWT             ;2 M/C
```

In the first three examples, the writing to the protected bits is done before the 3 machine cycles window closes. In Example 4, however, the writing to the protected bit occurs after the window has closed, and so there is effectively no change in the status of the protected bit. In Example 5, the second write to TA occurs 4 machine cycles after the first write, therefore the timed access window is not opened at all, and the write to the protected bit fails.

18. KEYBOARD INTERRUPT (KBI)

The W79E804 series are provided with 8 keyboard interrupt function to detect keypad status which key is acted, and allow a single interrupt to be generated when any key is pressed on a keyboard or keypad connected to specific pins of the W79E804 series, as shown below Figure. This interrupt may be used to wake up the CPU from Idle or Power Down modes, after chip is in Power Down or Idle Mode.

Keyboard function is supported through Port 0. It can allow any or all pins of Port 0 to be enabled to cause this interrupt. Port pins are enabled by the setting of bits of KBI0 ~ KBI7 in the KBI register, as shown below Figure. The Keyboard Interrupt Flag (KBF) in the AUXR1 register is set when any enabled pin is pulled low while the KBI interrupt function is active, and the low pulse must more than 1 machine cycle, an interrupt will be generated if it has been enabled. The KBF bit set by hardware and must be cleared by software. In order to determine which key was pressed, the KBI will allow the interrupt service routine to poll port 0.

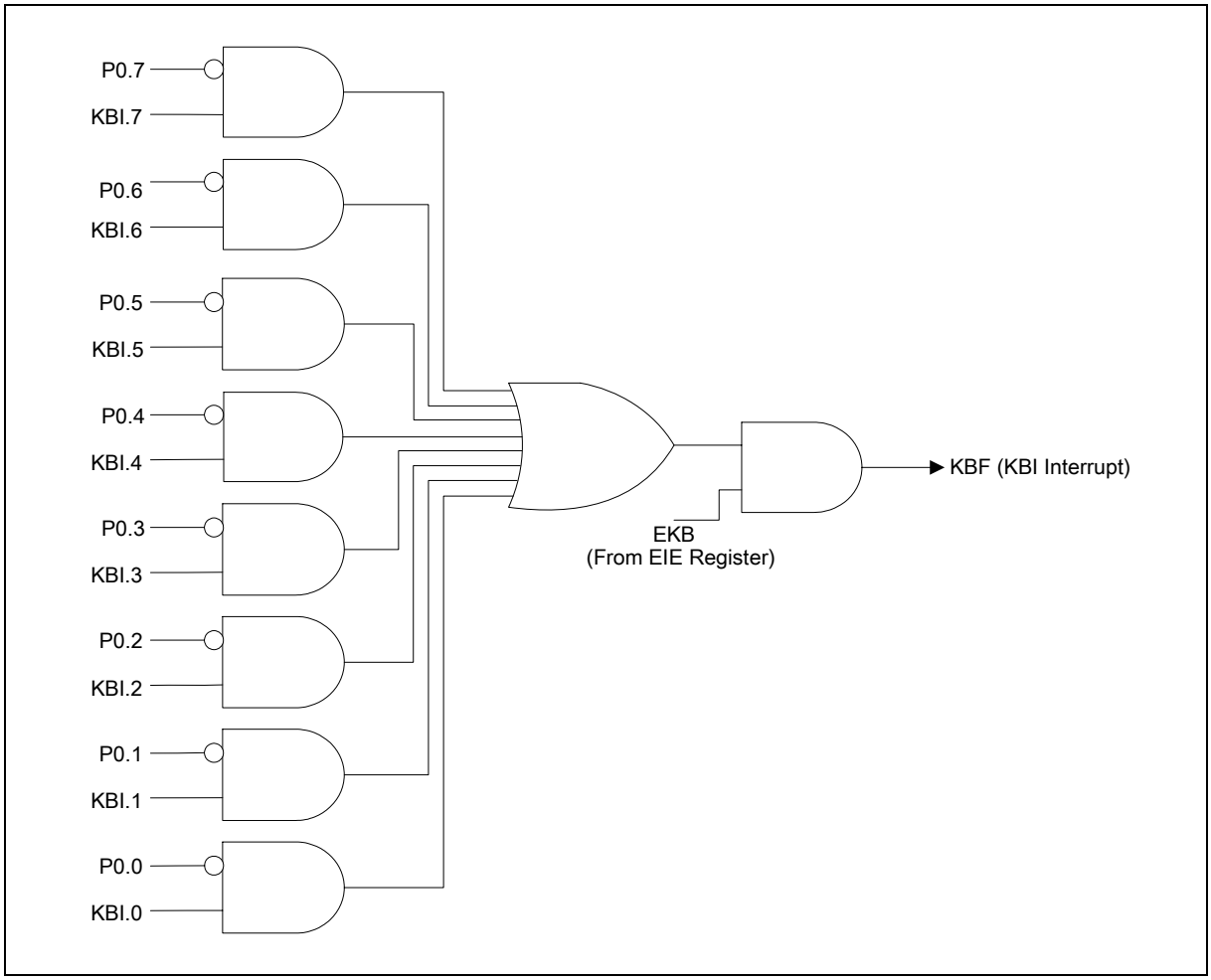


Figure 18-1: Keyboard Interrupt

19. ANALOG COMPARATORS

The W79E804 series are provided two Comparators. Input and output options allow use of the comparators in a number of different Configurations. The Comparator output is a logical one when its positive input is greater than its negative input. Otherwise, the output is a zero. Each Comparator can be configured to cause to an interrupt when the output value change. The block diagram is as below.

Each Comparator has a control register (CMP1 and CMP2), Both Inputs are CINnA, CINnB, CMPREF and internal reference voltage, and outputs are CMP1 and CMP2 by setting OEn bit. After enable Comparators the Comparator need waited stable time to guarantee Comparator output. If programmer used internal reference voltage, it will be set OEn bit to “1”. The value of internal reference voltage (Vref) is 1.19V +/- 10%.

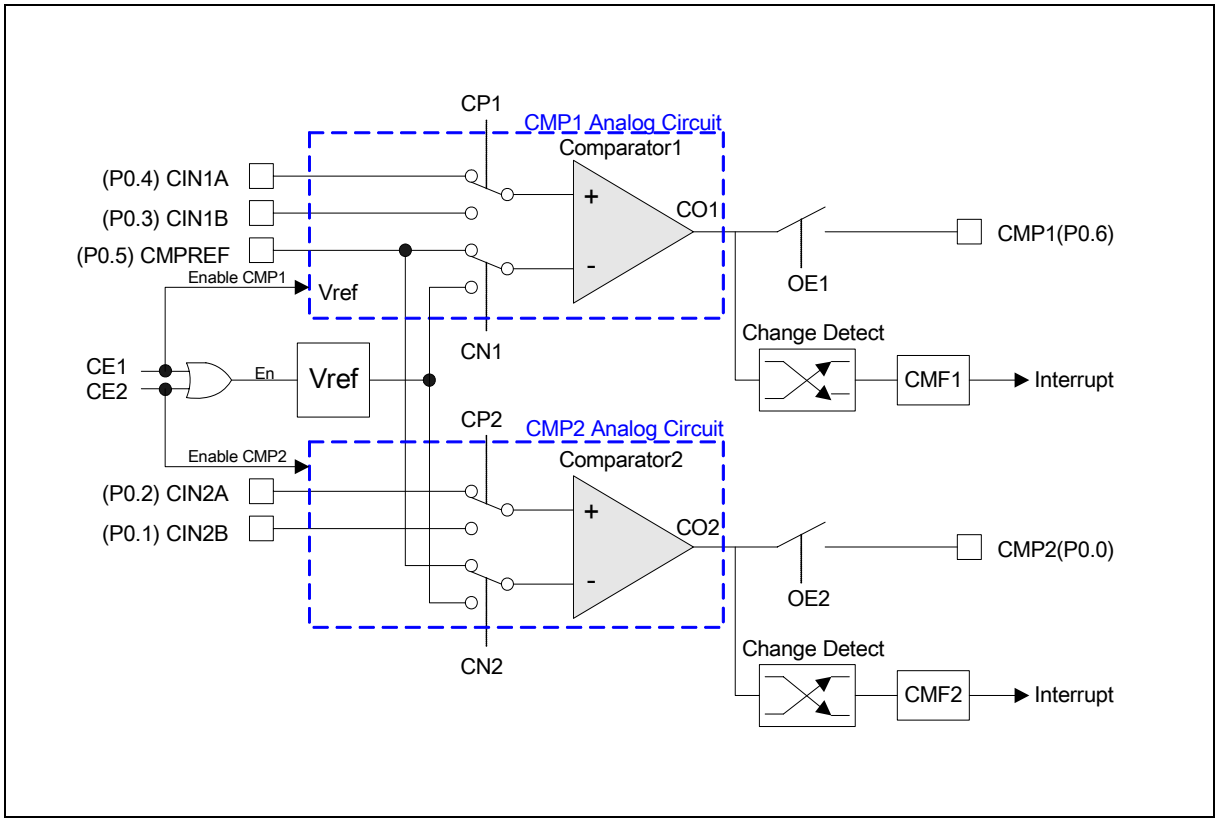


Figure 19-1: Analog Comparators

20. I/O PORT CONFIGURATION

The W79E804 series have three I/O ports, port 0, port 1 and port 2. All pins of I/O ports can be configured to one of four types by software except P1.5 is only input pin. When P1.5 is configured reset pin by RPD=0 in the CONFIG 1 register, the W79E804 series can support 15 pins by use Crystal. If used on-chip RC oscillator the P1.5 is configured input pin, the W79E804 series can be supported up to 18 pins. The I/O ports configuration setting as below table.

PXM1.Y	PXM2.Y	PORT INPUT/OUTPUT MODE
0	0	Quasi-bidirectional
0	1	Push-Pull
1	0	Input Only (High Impedance) P2M1.PxS=0, TTL input P2M1.PxS=1, Schmitt input
1	1	Open Drain

Table 20-1: I/O port Configuration Table

All port pins can be determined to high or low after reset by configure PRHI bit in the CONFIG1 register. After reset, these pins are in quasi-bidirectional mode. The port pin of P1.5 only is a Schmitt trigger input.

Enabled toggle outputs from Timer 0 and Timer 1 by T0OE and T1OE on P2M1 register, the output frequency of Timer 0 or Timer 1 is by Timer overflow.

Each I/O port of the W79E804 series may be selected to use TTL level inputs or Schmitt inputs by P(n)S bit on P2M1 register, where n is 0, 1 or 2. When P(n)S is set to 1, Ports are selected Schmitt trigger inputs on Port(n). The P2.0 (XTAL2) can be configured clock output when used on-chip RC or external Oscillator is clock source, and the frequency of clock output is divided by 4 on on-chip RC clock or external Oscillator.

20.1 Quasi-Bidirectional Output Configuration

After chip was power on or reset, the all ports output are this mode, and output is common with the 8051. This mode can be used as both an input and output without the need to reconfigure the port.

When the pin is pulled low, it is driven strongly and able to sink a fairly large current. These features are somewhat similar to an open drain output except that there are three pull-up transistors in the quasi-bidirectional output that serve different purposes.

This mode has three pull-up resisters that are “strong” pull-up, “weak” pull-up and “very weak” pull-up. The “strong” pull-up is used fast transition from logic “0” change to logic “1”, and it is fast latch and transition. When port pins is occur from logic “0” to logic “1”, the strong pull-up will quickly turn on two CPU clocks to pull high then turn off.

The “weak” pull-up is turned on when the input port pin is logic “1” level or itself is logic “1”, and it provides the most source current for a quasi-bidirectional pin that output is “1” or port latch is logic “0”’.

The “very weak” pull-up is turned on when the port latch is logic “1”. If port latch is logic “0”, it will be turned off. The very weak pull-up is support a very small current that will pull the pin high if it is left floating. And the quasi-bidirectional port configuration is shown as below figure.

If port pin is low, it can drives large sink current for output, and it is similar with push-pull and open drain on sink current output.

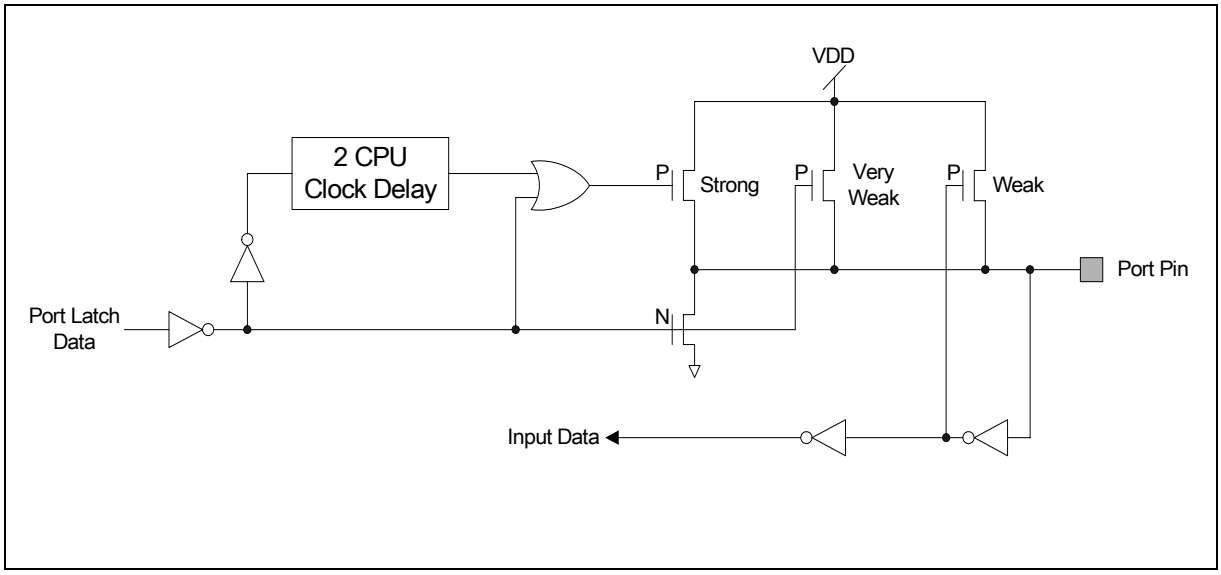


Figure 20-2: Quasi-Bidirectional Output

20.2 Open Drain Output Configuration

To configure this mode is turned off all pull-ups. If used similar as a logic output, the port must has an external pull-up resister. The open drain port configuration is shown as below.

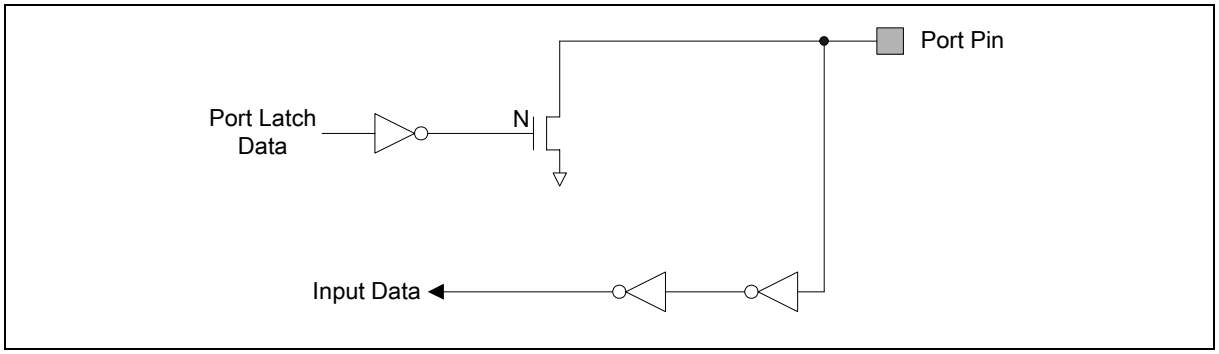


Figure 20-3: Open Drain Output

20.3 Push-Pull Output Configuration

The push-pull output mode has two strong pull-up and pull-down structure that support large source and sink current output. It removes “weak” pull-up and “very weak” pull-up resister and remain “strong pull-up resister on quasi-bidirectional output mode. The “strong” pull-up is always turns on when port latch is logic “1” to support source current. The push-pull port configuration is shown in below Figure.

The W79E804 series have three port pins that can’t be configured. They are P1.2, P1.3, and P1.5. The port pins P1.2 and P1.3 are configured to open drain outputs. They may be used as inputs by writing ones to their respective port latches.

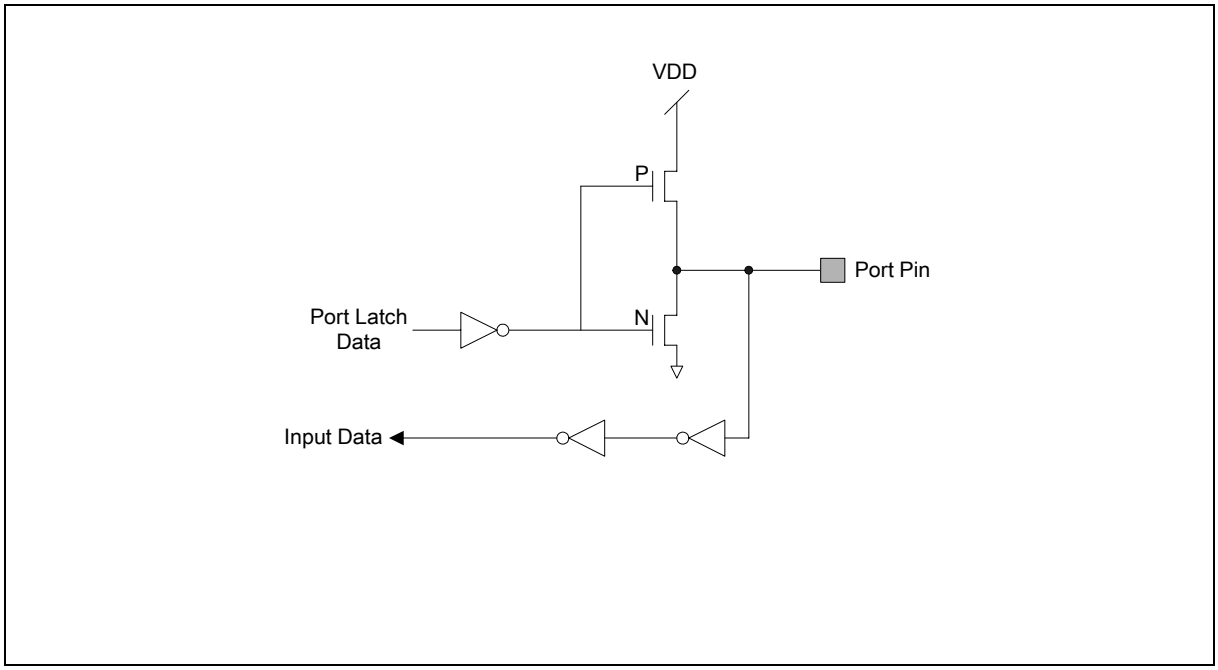


Figure 20-4: Push-Pull Output

20.4 Input Only Configuration

By configure this mode, the ports are only digital input and disable digital output. The W79E804 series can select input pin to Schmitt trigger or TTL level input by PxM1.y and PxM2.y registers.

21. OSCILLATOR

The W79E804 series provides three oscillator input option. These are configured at CONFIG register (CONFIG1) that include On-Chip RC Oscillator Option, External Clock Input Option and Crystal Oscillator Input Option. The Crystal Oscillator Input frequency may be supported from 4MHz to 20MHz, and without capacitor or resister.

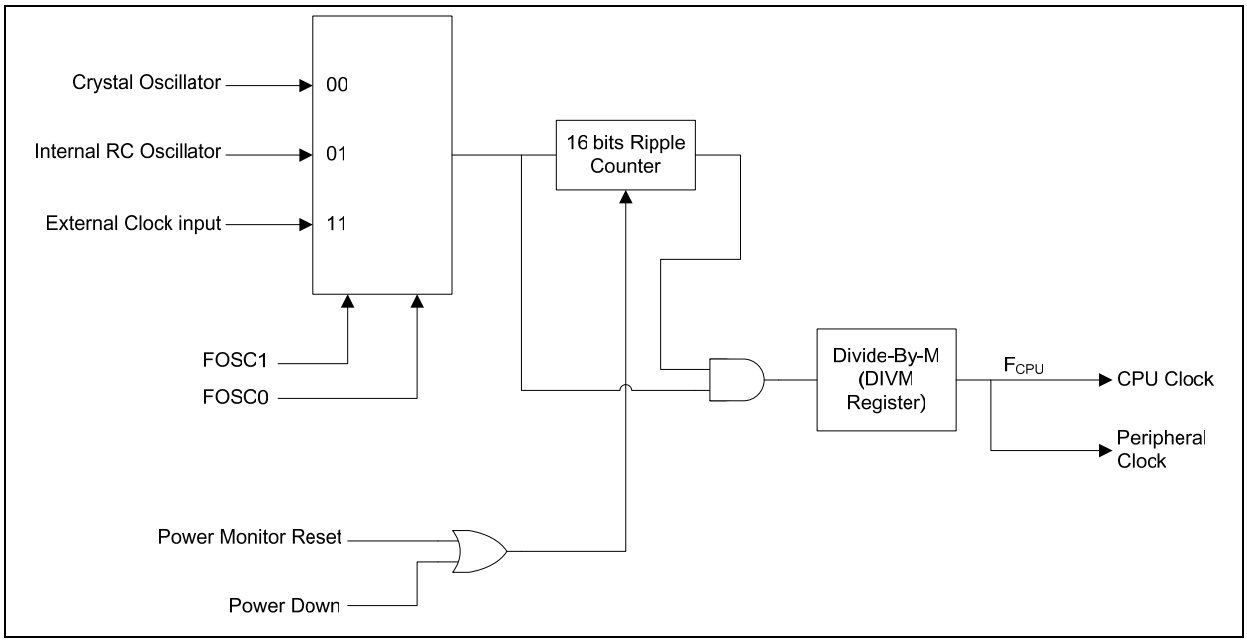


Figure 21-1: Oscillator

21.1 On-Chip RC Oscillator Option

The On-Chip RC Oscillator is fixed at 6MHz +/- 25% frequency to support clock source. When FOSC1, FOSC0 = 01H, the On-Chip RC Oscillator is enabled. A clock output on P2.0 (XTAL2) may be enabled when On-Chip RC oscillator is used.

21.2 External Clock Input Option

The clock source pin (XTAL1) is from External Clock Input by FOSC1, FOSC0 = 11H, and frequency range is form 0Hz up to 20MHz. A clock output on P2.0 (XTAL2) may be enabled when External Clock Input is used.

The W79E804 series supports a clock output function when either the on-chip RC oscillator or the external clock input options is selected. This allows external devices to synchronize to the W79E804 serial. When enabled, via the ENCLK bit in the P2M1 register, the clock output appears on the XTAL2/CLKOUT pin whenever the on-chip oscillator is running, including in Idle Mode. The frequency of the clock output is 1/4 of the CPU clock rate. If the clock output is not needed in Idle Mode, it may be turned off prior to entering Idle mode, saving additional power. The clock output may also be enabled when the external clock input option is selected.

21.3 CPU Clock Rate select

The CPU clock of W79E804 series may be selected by the DIVM register. If DIVM = 00H, the CPU clock is running at 4 CPU clock pre machine cycle, and without any division from source clock (Fosc). When the DIVM register is set to N value, the CPU clock is divided by 2(DVIM+1), so CPU clock frequency division is from 4 to 512. The user may use this feature to set CPU at a lower speed rate for reducing power consumption. This is very similar to the situation when CPU has entered Idle mode. In addition this frequency division function affect all peripheral timings as they are all sourcing from the CPU clock(Fcpu).

22. POWER MONITORING FUNCTION

Power-On Detect and Brownout are two additional power monitoring functions implemented in W79E804 series to prevent incorrect operation during power up and power drop or loss.

22.1 Power On Detect

The Power–On Detect function is a designed to detect power up after power voltage reaches to a level where Brownout Detect can work. After power on detect, the POR (PCON.4) will be set to “1” to indicate an initial power up condition. The POR flag will be cleared by software.

22.2 Brownout Detect

The Brownout Detect function is detect power voltage is drops to brownout voltage level, and allows preventing some process work or indicate power warming. The W79E804 series have two brownout voltage levels to select by BOV (CONFIG1.4). If BOV =0 that brownout voltage level is 3.8V, If BOV = 1 that brownout voltage level is 2.5V. When the Brownout voltage is drop to select level, the brownout detector will detect and keeps this active until VDD is returns to above brownout Detect voltage. The Brownout Detect block is as follow.

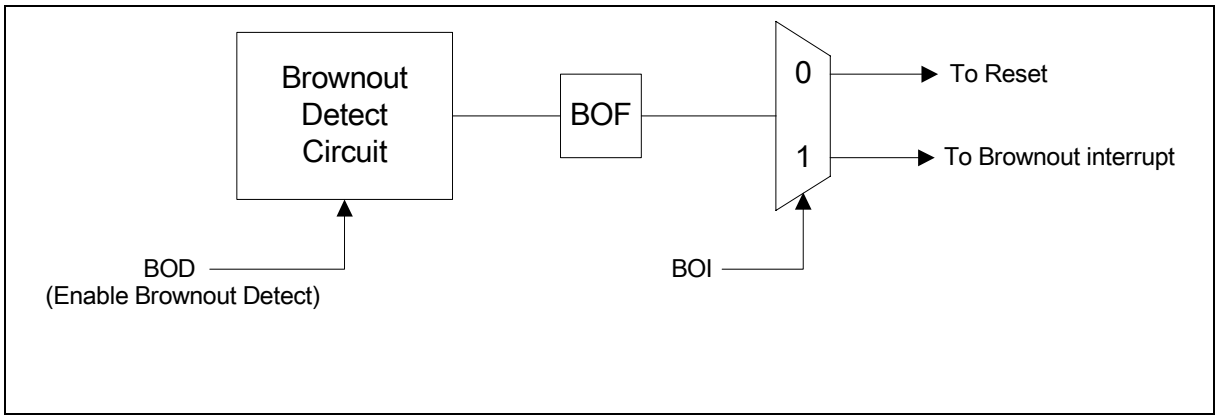


Figure 22-1: Brownout Detect Block

When Brownout Detect is enabled by BOD (AUXR1.6), the BOF (PCON.5) flag will be set and brownout reset will occur. If BOI (AUXR1.5) is set to “1”, the brownout detect will cause interrupt via the EA (IE.7) and EBO (IE.5) bits is set. BOF is cleared by software.

In order to guarantee a correct detection of Brownout, The VDD fail time must be slower than 50mV/us, and rise time is slower than 2mV/us to ensure a proper reset.

23. PULSE-WIDTH-MODULATED (PWM) OUTPUTS

The W79E804 series have four Pulse Width Modulated (PWM) channels, and the PWM outputs are PWM0 (P0.1), PWM1 (P1.6), PWM2 (P1.7) and PWM3 (P0.0). The initial PWM outputs level correspondingly depend on the PRHI level set prior to the chip reset. When PRHI set to high, PWM output will initialize to high after chip reset; if PRHI set to low, PWM output will be initialize to low after chip reset.

The W79E804 series support 10-bits down counter with cpu clock as its input. The PWM counter clock, has the same frequency as the clock source $F_{CPU} = F_{OSC}$. When the counter reaches underflow it will automatic reloaded from counter register. The PWM frequency is given by: $f_{PWM} = F_{CPU} / (PWMP+1)$, where PWMP is 10-bits register of PWMPH.1, PWMPH.0 and PWMPL.7~PWMPL.0.

The counter register will be loaded with the PWMP register value when PWMRUN, load and CF are equal to 1; the load bit will be automatically cleared to zero on the next clock cycle, and at the same time the counter register value will be loaded to the 10 bits down counter. CF flag is 10-bits down counter reaches underflow, the CF flag will be cleared by software.

The pulse width of each PWM output is determined by the Compare registers of PWM0L through PWM3L and PWM0H through PWM3H. When PWM compare register is greater than 10-bits counter register, the PWM output is low. Load bit has to be set to 1 for alteration of PWMn width. After the new values are written to the PWMn registers, and if load bit is set to 1, the new PWMn values will be loaded to the PWMn registers upon the next underflow. The PWM output high pulses width is given by:

t_{HI} = (PWMP – PWMn+1). **Notice, if compare register is set to 000H, the PWMn output will stay at high, and if compare register is set to 3FFH, the PWMn output will stuck at low until there is a change in the compare register.**

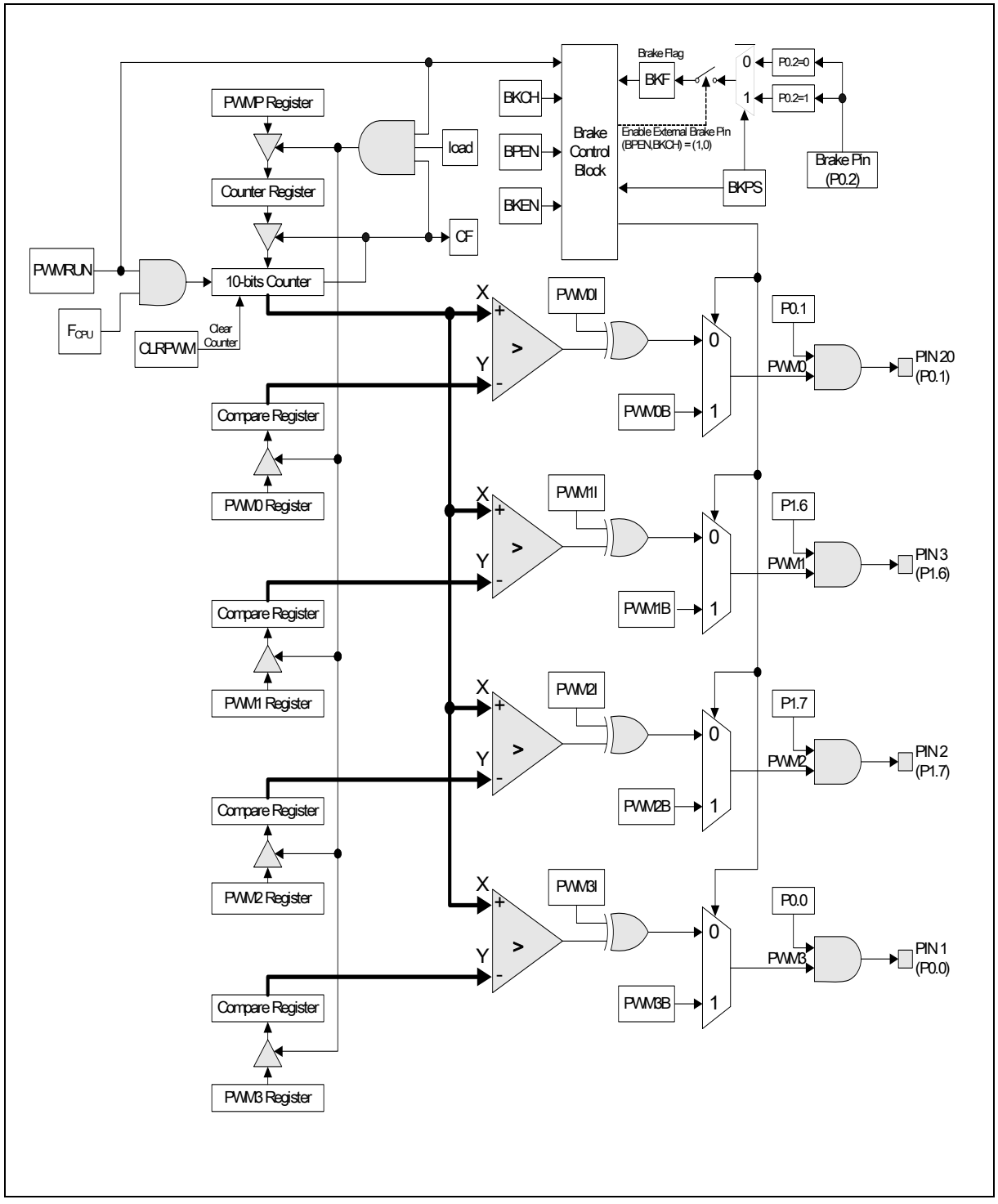


Figure 23-1: W79E804/803/802 PWM Block Diagram

The W79E804 series devices support brake function which can be activated by software or external pin (P0.2). The Brake function is controlled by the PWMCON2 register. The setting and details description of software brake and external pin brake can be found at the brake condition table at the SFR section.

As for external brake, the user program can poll the brake flag (BKF) or enable PWM's brake interrupt to determine when the external Brake Pin is asserted and causes a brake to occur. The brake pin (P0.2) can be set to trigger the brake function by either low or high level, by clearing or setting the PWMCON2.6 (BPKS) bit respectively. The details description of varies brake functions can be found in the brake condition table.

Since the Brake Pin being asserted will automatically clear the Run bit of PWMCON1.7 and BKF (PWMCON3.0) flag will be set, the user program can poll this bit or enable PWM's brake interrupt to determine when the Brake Pin causes a brake to occur. The other method for detecting a brake caused by the Brake Pin would be to tie the Brake Pin to one of the external interrupt pins. This latter approach is needed if the Brake signal is of insufficient length to ensure that it can be captured by a polling routine. When, after being asserted, the condition causing the brake is removed, the PWM outputs go to whatever state that had immediately prior to the brake. This means that in order to go from brake being asserted to having the PWM run without going through an indeterminate state, care must be taken. If the Brake Pin causes brake to be asserted, the following prototype code will allow the PWM to go from brake and then run smoothly after brake is released.

Note: Due to the initialization of PWM and switching to PWM channels to output ports, user should take note that the first PWM pulse may not be stable until the second PWM pulse.

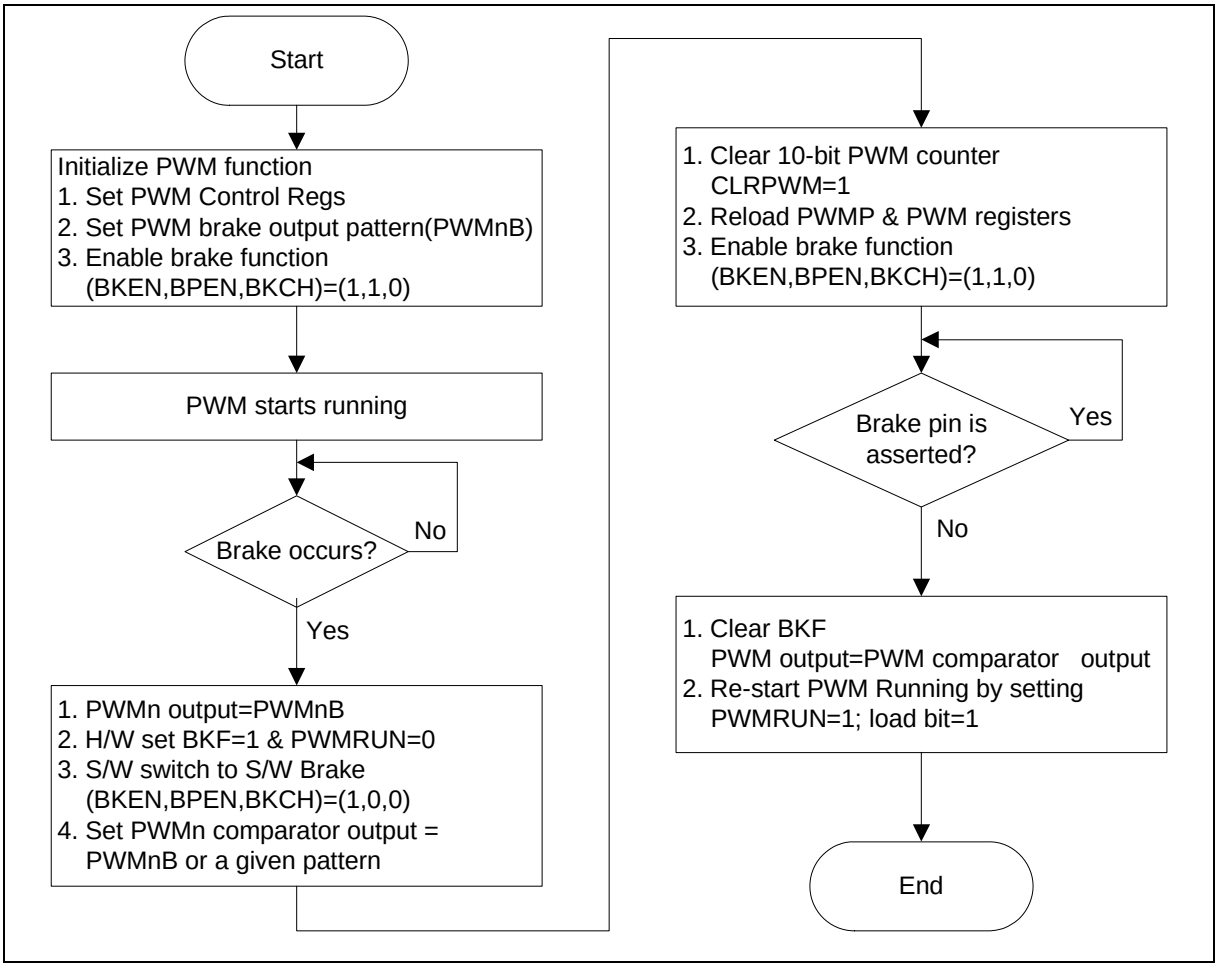


Figure 23-2: PWM Brake Function

24. I2C SERIAL CONTROL

The I2C bus uses two wires (SDA and SCL) to transfer information between devices connected to the bus. The main features of the bus are:

– Bidirectional data transfer between masters and slaves

– Multimaster bus (no central master)

– Arbitration between simultaneously transmitting masters without corruption of serial data on the bus

– Serial clock synchronization allows devices with different bit rates to communicate via one serial bus

– Serial clock synchronization can be used as a handshake mechanism to suspend and resume serial transfer

– The I2C bus may be used for test and diagnostic purposes

–

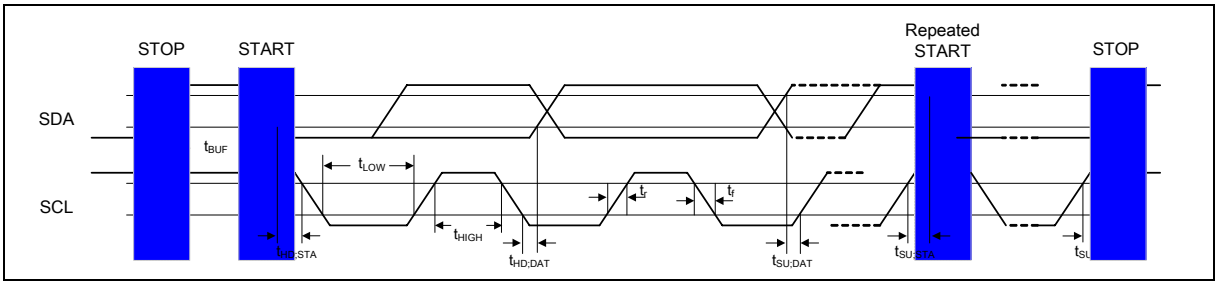


Figure 24-1: I2C Bus Timing

The device's on-chip I2C logic provides the serial interface that meets the I2C bus standard mode specification. The I2C logic handles bytes transfer autonomously. It also keeps track of serial transfers, and a status register (I2STATUS) reflects the status of the I2C bus.

The I2C port, SCL and SDA are at P1.2 and P1.3. When the I/O pins are used as I2C port, user must set the pins to logic high in advance. When I2C port is enabled by setting ENS to high, the internal states will be controlled by I2CON and I2C logic hardware. Once a new status code is generated and stored in I2STATUS, the I2C interrupt flag (SI) will be set automatically. If both EA and EI2C are also in logic high, the I2C interrupt is requested. The 5 most significant bits of I2STATUS stores the internal state code, the lowest 3 bits are always zero and the content keeps stable until SI is cleared by software.

24.1 SIO Port

The SIO port is a serial I/O port, which supports all transfer modes from and to the I2C bus. The SIO port handles byte transfers autonomously. To enable this port, the bit ENS1 in I2CON should be set to '1'. The CPU interfaces to the SIO port through the following six special function registers: **I2CON** (control register, C0H), **I2STATUS** (status register, BDH), **I2DAT** (data register, BCH), **I2ADDR** (address registers, C1H), **I2CLK** (clock rate register BEH) and **I2TIMER** (Timer counter register, BFH). The SIO H/W interfaces to the I2C bus via two pins: SDA (P1.3, serial data line) and SCL (P1.2, serial clock line). Pull up resistors are needed for Pin P1.2 and P1.3 for I2C operation as these are open drain pins.

24.2 The I2C Control Registers:

The I2C has 1 control register (I2CON) to control the transmit/receive flow, 1 data register (I2DAT) to buffer the Tx/Rx data, 1 status register (I2STATUS) to catch the state of Tx/Rx, recognizable slave address register for slave mode use and 1 clock rate control block for master mode to generate the variable baud rate.

24.2.1 The Address Registers, I2ADDR

I2C port is equipped with one slave address register. The contents of the register are irrelevant when I2C is in master mode. In the slave mode, the seven most significant bits must be loaded with the MCU's own slave address. The I2C hardware will react if the contents of I2ADDR are matched with the received slave address.

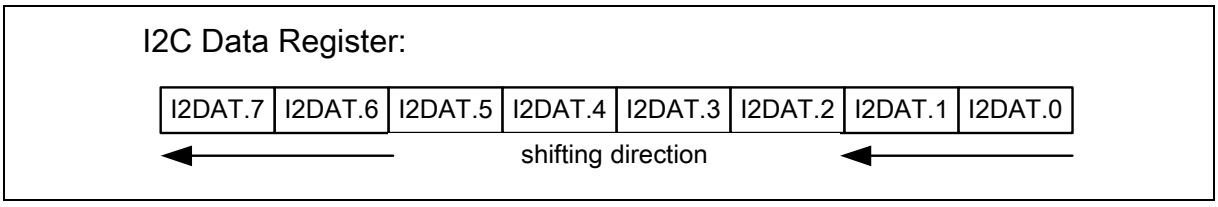
The I2C ports support the "General Call" function. If the GC bit is set the I2C port1 hardware will respond to General Call address (00H). Clear GC bit to disable general call function.

When GC bit is set, the I2C is in Slave mode, it can be received the general call address by 00H after Master send general call address to I2C bus, then it will follow status of GC mode. If it is in Master mode, the AA bit must be cleared when it will send general call address of 00H to I2C bus.

24.2.2 The Data Register, I2DAT

This register contains a byte of serial data to be transmitted or a byte which has just been received. The CPU can read from or write to this 8-bit directly addressable SFR while it is not in the process of shifting a byte. This occurs when SIO is in a defined state and the serial interrupt flag (SI) is set. Data in I2DAT remains stable as long as SI bit is set. While data is being shifted out, data on the bus is simultaneously being shifted in; I2DAT always contains the last data byte present on the bus. Thus, in the event of arbitration lost, the transition from master transmitter to slave receiver is made with the correct data in I2DAT.

I2DAT and the acknowledge bit form a 9-bit shift register, the acknowledge bit is controlled by the SIO hardware and cannot be accessed by the CPU. Serial data is shifted through the acknowledge bit into I2DAT on the rising edges of serial clock pulses on the SCL line. When a byte has been shifted into I2DAT, the serial data is available in I2DAT, and the acknowledge bit (ACK or NACK) is returned by the control logic during the ninth clock pulse. Serial data is shifted out from I2DAT on the falling edges of SCL clock pulses, and is shifted into I2DAT on the rising edges of SCL clock pulses.



24.2.3 The Control Register, I2CON

The CPU can read from and write to this 8-bit, directly addressable SFR. Two bits are affected by hardware: the SI bit is set when the I2C hardware requests a serial interrupt, and the STO bit is cleared when a STOP condition is present on the bus. The STO bit is also cleared when ENS = "0".

ENSI Set to enable I2C serial function block. When ENS=1 the I2C serial function enables. The port latches of SDA1 and SCL1 must be set to logic high.

STA I2C START Flag. Setting STA to logic 1 to enter master mode, the I2C hardware sends a START or repeat START condition to bus when the bus is free.

STO I2C STOP Flag. In master mode, setting STO to transmit a STOP condition to bus then I2C hardware will check the bus condition if a STOP condition is detected this flag will be cleared by hardware automatically. In a slave mode, setting STO resets I2C hardware to the defined “not addressed” slave mode. This means it is NO LONGER in the slave receiver mode to receive data from the master transmit device.

SI I2C Port 1 Interrupt Flag. When a new SIO state is present in the S1STA register, the SI flag is set by hardware, and if the EA and EI2C1 bits are both set, the I2C1 interrupt is requested. SI must be cleared by software.

AA Assert Acknowledge control bit. When AA=1 prior to address or data received, an acknowledged (low level to SDA) will be returned during the acknowledge clock pulse on the SCL line when 1.) A slave is acknowledging the address sent from master, 2.) The receiver devices are acknowledging the data sent by transmitter. When AA=0 prior to address or data received, a Not acknowledged (high level to SDA) will be returned during the acknowledge clock pulse on the SCL line.

24.2.4 The Status Register, I2STATUS

I2STATUS is an 8-bit read-only register. The three least significant bits are always 0. The five most significant bits contain the status code. There are 23 possible status codes. When I2STATUS contains F8H, no serial interrupt is requested. All other I2STATUS values correspond to defined SIO states. When each of these states is entered, a status interrupt is requested (SI = 1). A valid status code is present in I2STATUS one machine cycle after SI is set by hardware and is still present one machine cycle after SI has been reset by software.

24.2.5 The I2C Clock Baud Rate Bits, I2CLK

The data baud rate of I2C is determines by I2CLK register when SIO is in a master mode. It is not important when SIO is in a slave mode. In the slave modes, SIO will automatically synchronize with any clock frequency up to 400 KHz from master I2C device.

The data baud rate of I2C setting is Data Baud Rate of I2C = Fcpu / (I2CLK+1). The Fcpu=Fosc/4. If Fosc = 16MHz, the I2CLK = 40(28H), so data baud rate of I2C = 16MHz/(4X (40 +1)) = 97.56Kbits/sec. The block diagram is as below figure.

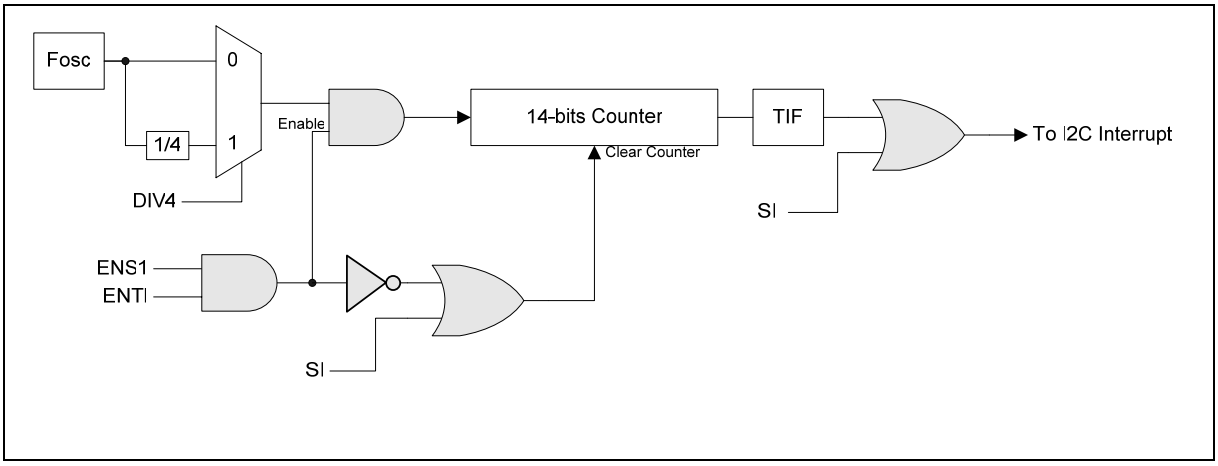


Figure 24-2: I2C Timer Count Block Diagram

24.3 Modes of Operation

The on-chip I2C ports support five operation modes, Master transmitter, Master receiver, Slave transmitter, Slave receiver, and GC call.

In a given application, I2C port may operate as a master or as a slave. In the slave mode, the I2C port hardware looks for its own slave address and the general call address. If one of these addresses is detected, and if the slave is willing to receive or transmit data from/to master(by setting the AA bit), acknowledge pulse will be transmitted out on the 9th clock, hence an interrupt is requested on both master and slave devices if interrupt is enabled. When the microcontroller wishes to become the bus master, the hardware waits until the bus is free before the master mode is entered so that a possible slave action is not interrupted. If bus arbitration is lost in the master mode, I2C port switches to the slave mode immediately and can detect its own slave address in the same serial transfer.

24.3.1 Master Transmitter Mode

Serial data output through SDA while SCL outputs the serial clock. The first byte transmitted contains the slave address of the receiving device (7 bits) and the data direction bit. In this case the data direction bit (R/W) will be logic 0, and it is represented by “W” in the flow diagrams. Thus the first byte transmitted is SLA+W. Serial data is transmitted 8 bits at a time. After each byte is transmitted, an acknowledge bit is received. START and STOP conditions are output to indicate the beginning and the end of a serial transfer.

24.3.2 Master Receiver Mode

In this case the data direction bit (R/W) will be logic 1, and it is represented by “R” in the flow diagrams. Thus the first byte transmitted is SLA+R. Serial data is received via SDA while SCL outputs the serial clock. Serial data is received 8 bits at a time. After each byte is received, an acknowledge bit is transmitted. START and STOP conditions are output to indicate the beginning and end of a serial transfer.

24.3.3 Slave Receiver Mode

Serial data and the serial clock are received through SDA and SCL. After each byte is received, an acknowledge bit is transmitted. START and STOP conditions are recognized as the beginning and end of a serial transfer. Address recognition is performed by hardware after reception of the slave address and direction bit.

24.3.4 Slave Transmitter Mode

The first byte is received and handled as in the slave receiver mode. However, in this mode, the direction bit will indicate that the transfer direction is reversed. Serial data is transmitted via SDA while the serial clock is input through SCL. START and STOP conditions are recognized as the beginning and end of a serial transfer.

24.4 Data Transfer Flow in Five Operating Modes

The five operating modes are: Master/Transmitter, Master/Receiver, Slave/Transmitter, Slave/Receiver and GC Call. Bits STA, STO and AA in I2CON register will determine the next state of the SIO hardware after SI flag is cleared. Upon complexion of the new action, a new status code will be updated and the SI flag will be set. If the I2C interrupt control bits (EA and EI2) are enable, appropriate action or software branch of the new status code can be performed in the Interrupt service routine.

Data transfers in each mode are shown in the following figures.

*** Legend for the following five figures:

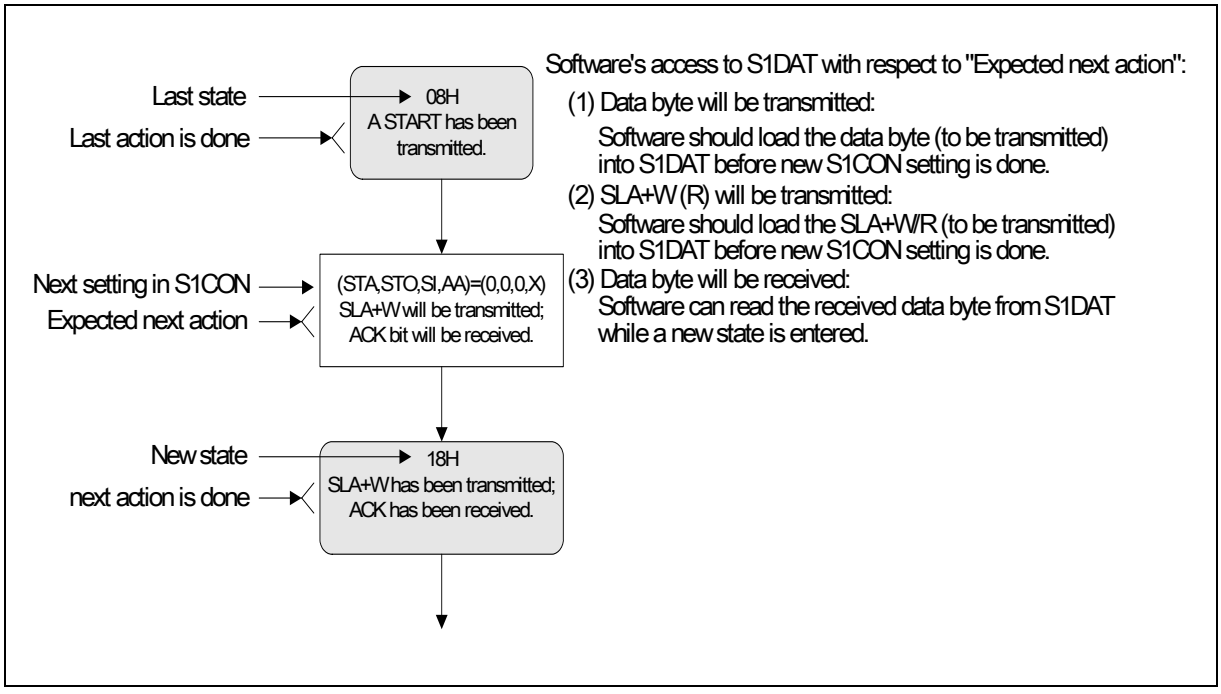


Figure 24-3: Legen for the following four figures

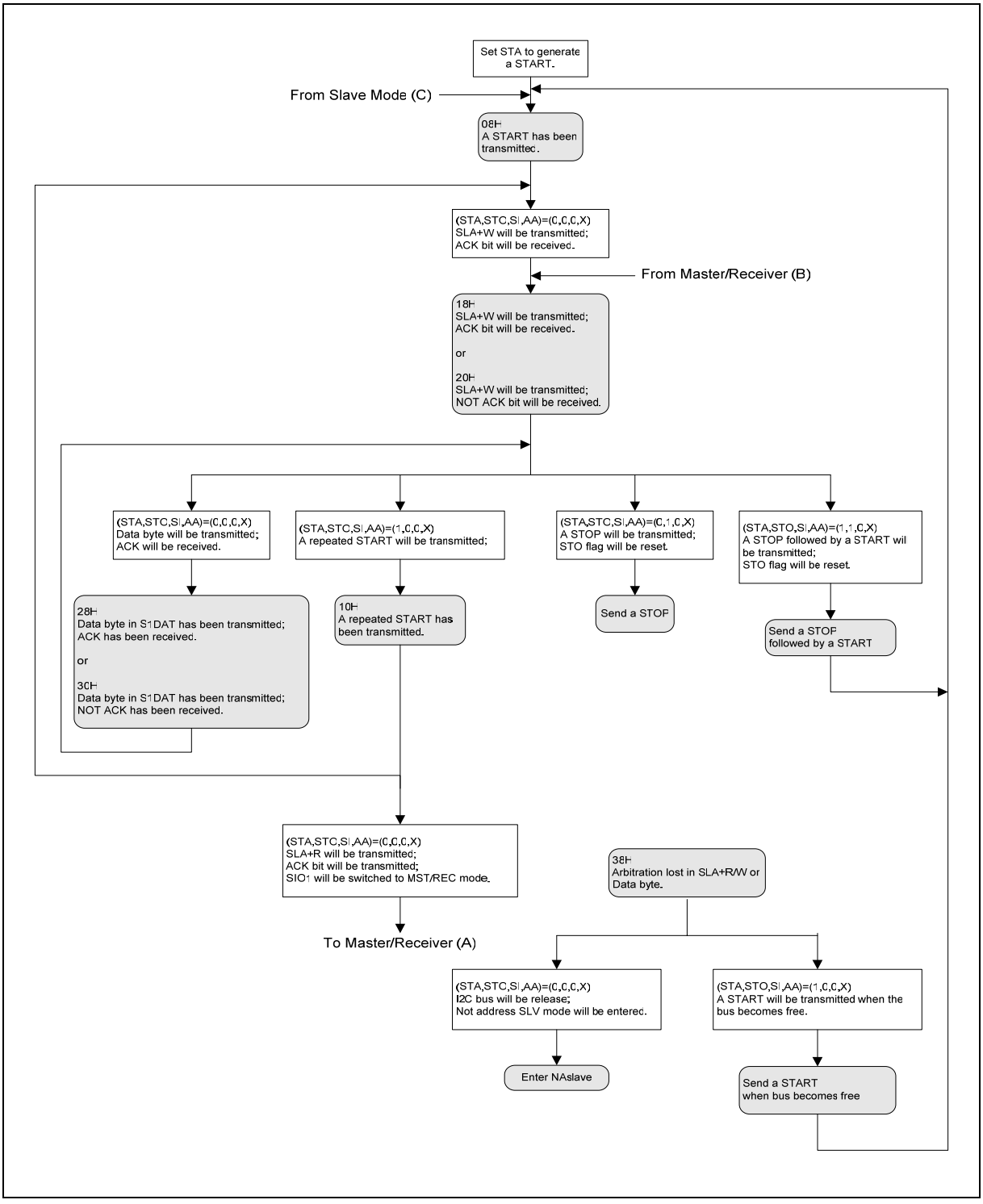


Figure 24-4: Master Transmitter Mode

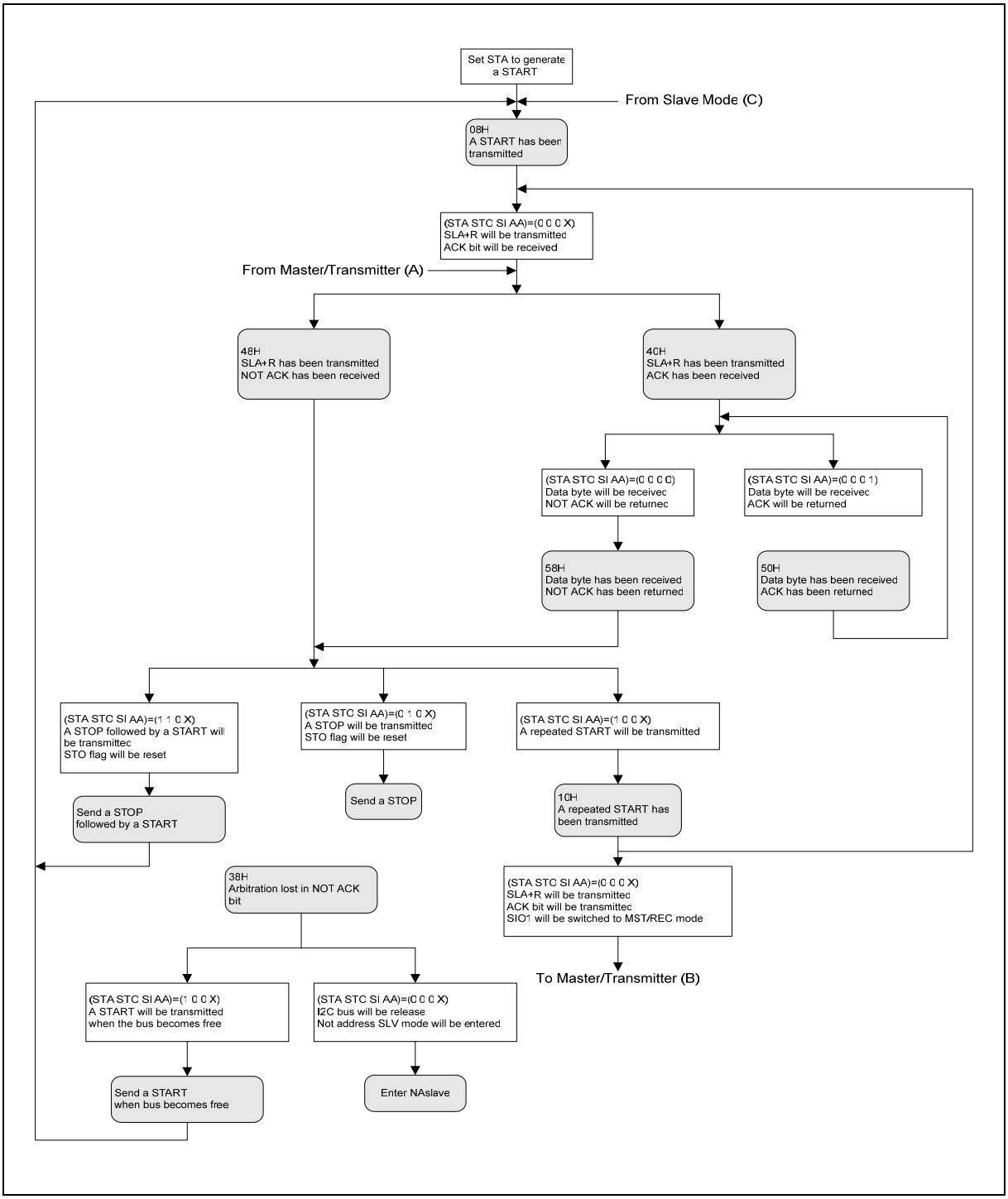


Figure 24-5: Master Receiver Mode

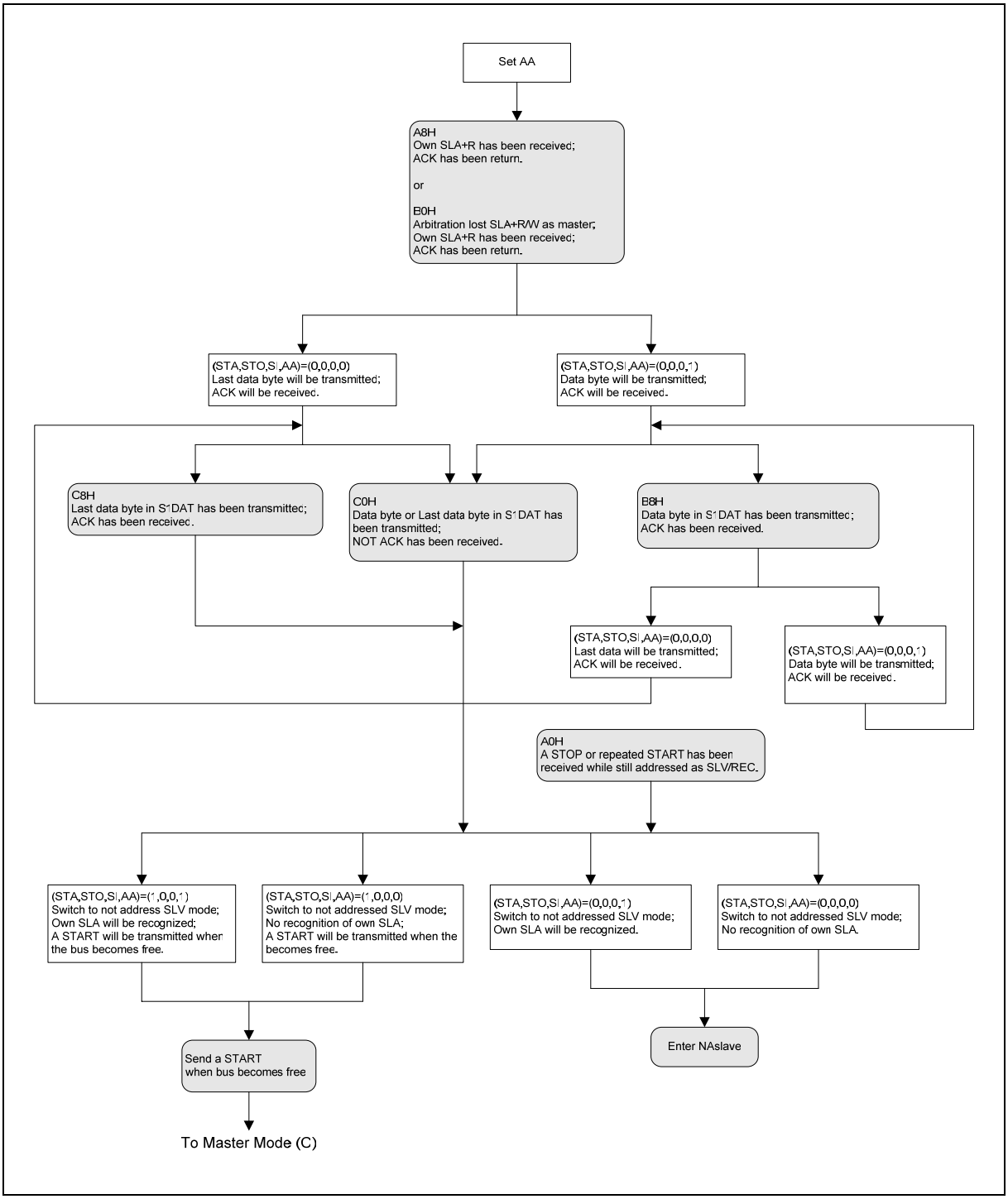


Figure 24-6: Slave Transmitter Mode

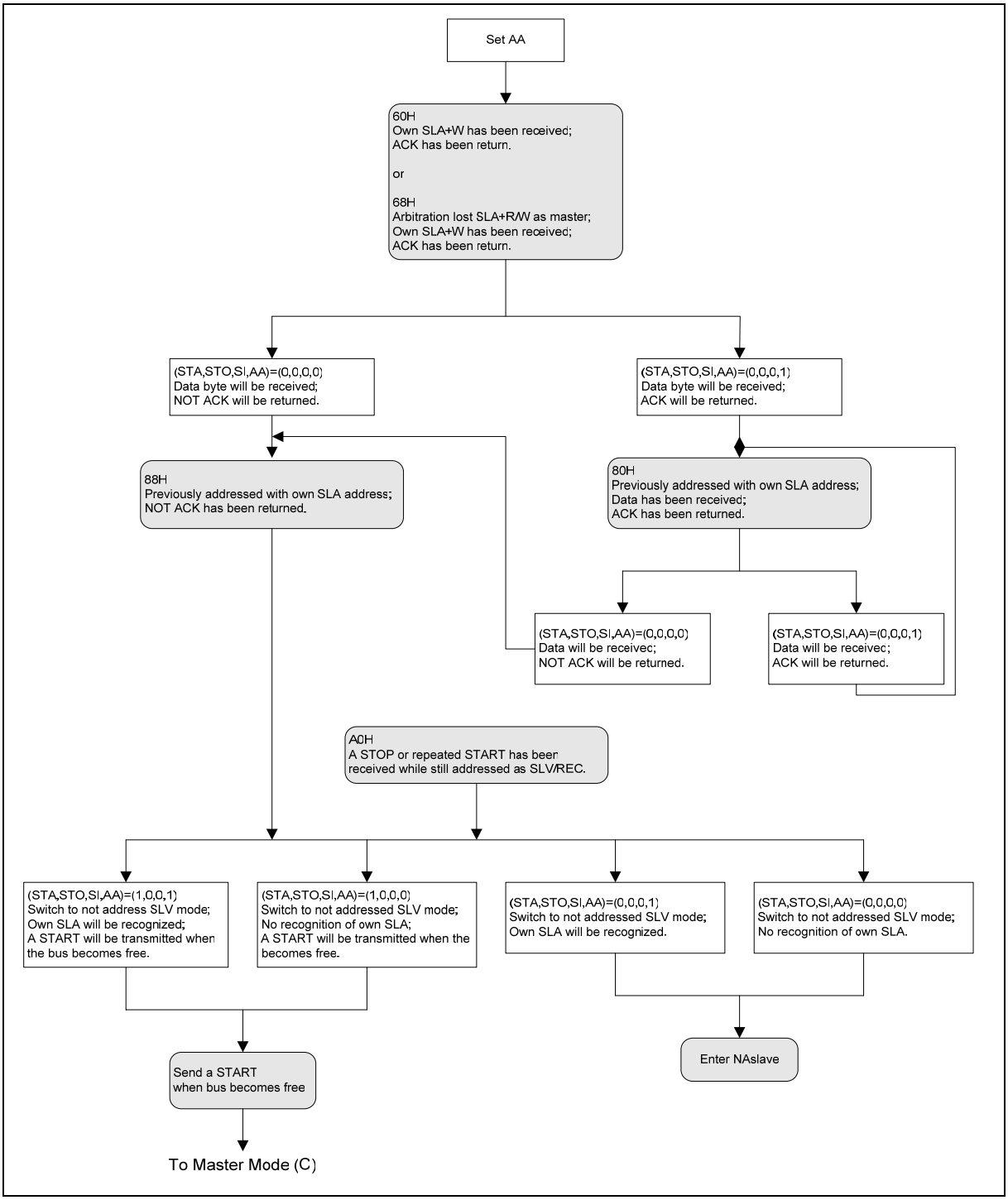


Figure 24-7:Slave Receiver Mode

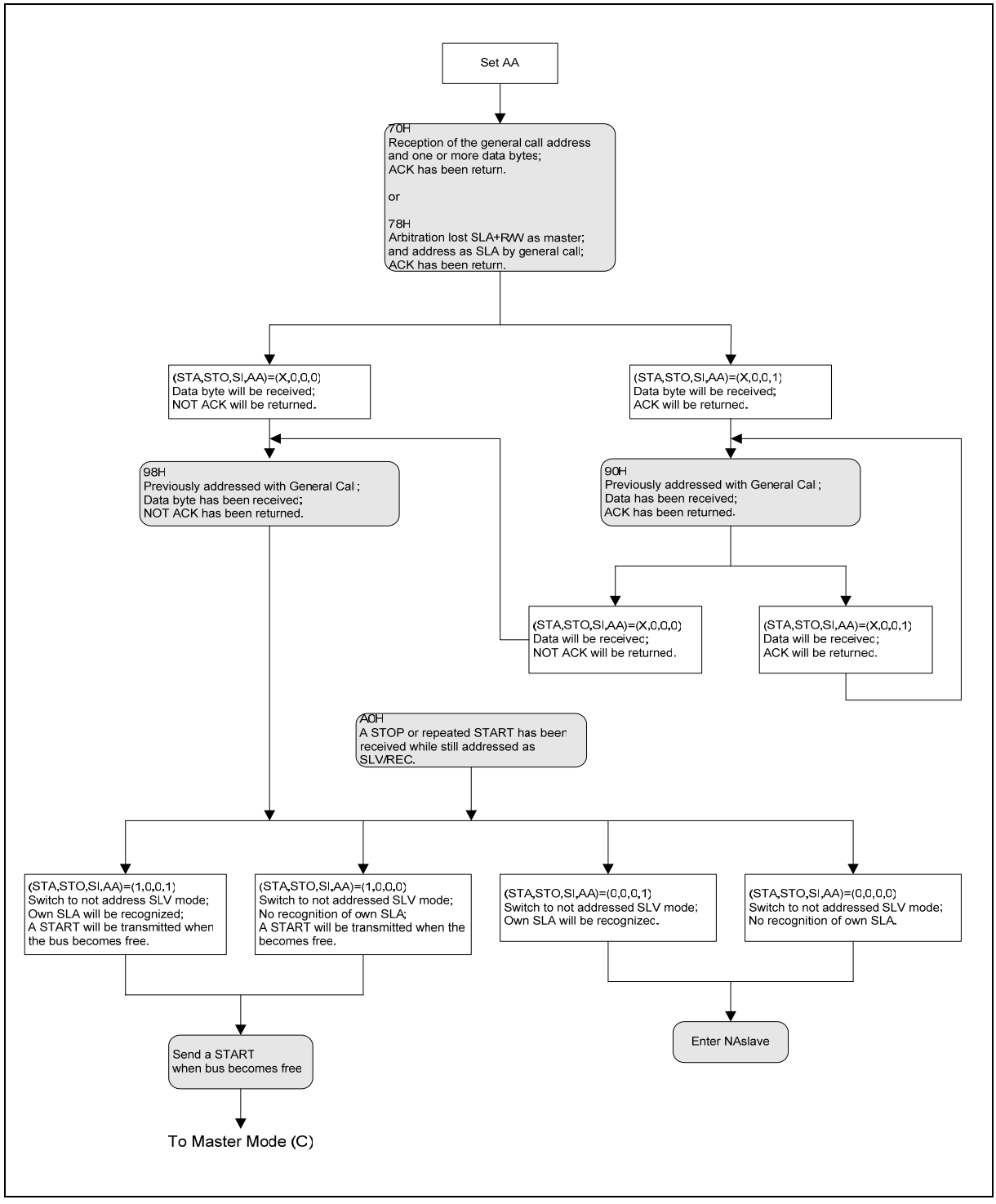


Figure 24-8: GC Mode

25. ICP (IN-CIRCUIT PROGRAM) FLASH PROGRAM

The contexts of flash in W79E804 series are empty by default. User must program the flash EPROM by external Writer device or by ICP (In-Circuit Program) tool.

In the ICP tool, the user must take note of ICP's program pins used in system board. In some application circuits, the pins are located at P1.5, P0.4 and P0.5, as below figure. During ICP programming, P1.5 must be set to high voltage (~10.5V), and keeping this voltage to update code, data and/or configure CONFIG bits. After programming completion, the high voltage of P1.5 should be released. So, it is highly recommended user power off then power on after ICP programming has completed on the system board.

Upon entry into ICP program mode, all pin will be set to quasi-bidirectional mode, and output to level "1".

The W79E804 series support programming of Flash EPROM (**8K/4K/2K** bytes AP Flash EPROM) and NVM data memory (**256** bytes). User has the option to program the AP flash and NVM either individually or both.

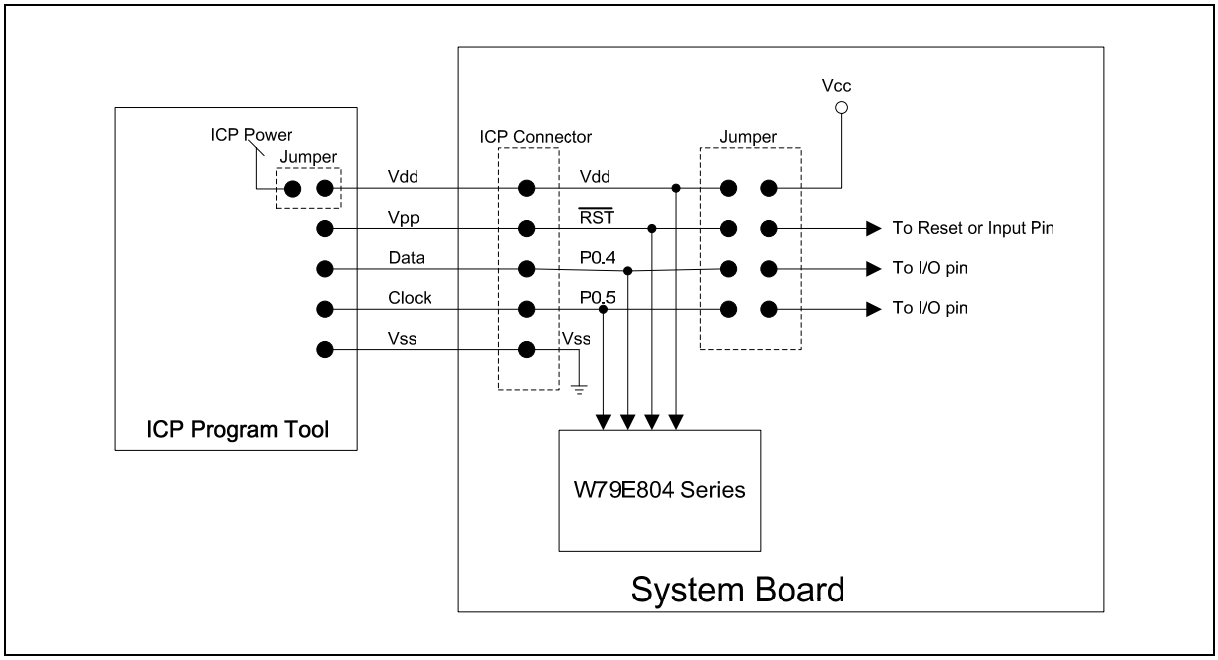


Figure 25-1: Application Circuit of ICP

Note: 1. When using ICP to upgrade code, the P1.5, P0.4 and P0.5 must be taken within design system board.
2. After program finished by ICP, to suggest system power must power off and remove ICP connector then power on.
3. It is recommended that user performs erase function and programming configure bits continuously without any interruption.

26. CONFIG BITS

The W79E804 series have two CONFIG bits (CONFIG1, CONFIG2) that must be define at power up and can not be set after the program start of execution. Those features are configured through the use of two flash EPROM bytes, and the flash EPROM can be programmed and verified repeatedly. Until the code inside the Flash EPROM is confirmed OK, the code can be protected. The protection of flash EPROM (CONFIG2) and those operations on it are described below. The data of these bytes may be read by the MOVX instruction at the addresses.

26.1 CONFIG1

7	6	5	4	3	2	1	0
WDTE	RPD	PRHI	BOV	-	-	Fosc1	Fosc0

WDTE: Watchdog Timer enable Bit
RPD: Reset Pin Disable Bit
PRHI: Port Reset High or Low Bit
BOV: Brownout voltage select Bit
Fosc1: CPU oscillator type select Bit1.
Fosc0: CPU oscillator type select Bit0.

CONFIG Register 1

BIT	NAME	FUNCTION
7	WDTE	Clock source of Watchdog Timer select bit: 0: The internal RC oscillator clock is for Watchdog Timer clock used. 1: The uC clock is for Watchdog Timer clock used.
6	RPD	Reset Pin Disable bit: 0: Enable Reset function of Pin 1.5. 1: Disable Reset function of Pin 1.5, and it to be used as an input port pin.
5	PRHI	Port Reset High or Low bit: 0: Port reset to low state. 1: Port reset to high state.
4	BOV	Brownout Voltage Select bit: 0: Brownout detect voltage is 3.8V. 1: Brownout detect voltage is 2.5V.
3	-	Reserved.
2	-	Reserved.
1	Fosc1	CPU Oscillator Type Select bit 1
0	Fosc0	CPU Oscillator Type Select bit 0

Oscillator Configuration bits:

FOSC1	FOSC0	OSC SOURCE
0	0	4MHz ~ 20MHz crystal
0	1	Internal RC Oscillator
1	0	Reserved
1	1	External Oscillator in XTAL1

26.2 CONFIG2

7	6	5	4	3	2	1	0
C7	C6	-	-	-	-	-	-

C7: 8K/4K2K bytes Flash EPROM Code Lock Bit
C6: 256 bytes Data Flash EPROM Lock Bit

CONFIG Register 2

C7: 8K/4K/2K bytes Flash EPROM Code Lock bit

This bit is used to protect the customer's program code. It may be set after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, both the Flash EPROM data and CONFIG Registers can not be accessed again.

C6: 256 bytes Data Flash EPROM Lock bit

This bit is used to protect the customer's data code. It may be set after the programmer finishes the programming and verifies sequence. Once this bit is set to logic 0, both the data Flash EPROM and CONFIG Registers can not be accessed again.

BIT 7	BIT 6	FUNCTION DESCRIPTION
1	1	Both security of **8KB/4KB/2KB** program code and **256** Bytes data area are unlocked. They can be erased, programmed or read by Writer or ICP.
0	1	The **8KB/4KB/2KB** program code area is locked. It can't be read by Writer or ICP.
1	0	Don't support (Invalid).
0	0	Both security of **8KB/4KB/2KB** program code and **256** Bytes data area are locked. They can't be read by Writer or ICP.

27. ELECTRICAL CHARACTERISTICS

27.1 Absolute Maximum Ratings

SYMBOL	PARAMETER	MIN	MAX	UNIT
DC Power Supply	VDD–VSS	-0.3	+7.0	V
Input Voltage	VIN	VSS-0.3	VDD+0.3	V
Operating Temperature	TA	-40	+85	°C
Storage Temperature	Tst	-55	+150	°C
Maximum Current into V_{DD}		-	120	mA
Maximum Current out of V_{SS}			120	mA
Maximum Current suck by a I/O pin			25	mA
Maximum Current sourced by a I/O pin			25	mA
Maximum Current suck by total I/O pins			75	mA
Maximum Current sourced by total I/O pins			75	mA

Note: Exposure to conditions beyond those listed under absolute maximum ratings may adversely affects the lift and reliability of the device.

27.2 DC ELECTRICAL CHARACTERISTICS

V_{SS} = 0V, T_A =-40~85° C, unless otherwise specified.

PARAMETER	SYM.	SPECIFICATION				TEST CONDITIONS
		MIN.	TYP.	MAX.	UNIT	
Operating Voltage	V_{DD}	2.7		5.5	V	V_{DD} =4.5V ~ 5.5V @ 20MHz V_{DD} =2.7V ~ 5.5V @ 12MHz
Operating Current	I_{DD1}		18	25	mA	V_{DD} = 5.0V @ 20MHz, No load, /RST = V_{ss}
			6	8	mA	V_{DD} = 3.0V @ 12MHz, No load, /RST = V_{ss}
	I_{DD2}		23	29	mA	V_{DD} = 5.0V @ 20MHz, No load, /RST = V_{DD}, Run NOP
			6.5	9	mA	V_{DD} = 3.0V @ 12MHz, No load, /RST = V_{DD}, Run NOP
Idle Current	I_{IDLE}		11.5	15	mA	V_{DD} = 5.5V, 20 MHz, no load
			5	6.5	mA	V_{DD} = 3.0V, 12 MHz, no load
Power Down Current	I_{PWDN}		1	10	µA	V_{DD} = 5.5V, no load @ Disable BOV function
			1	10	µA	V_{DD} = 3.0V, no load @ Disable BOV function
Input Current P0, P1, P2	I_{IN1}	-50	-	+15	µA	V_{DD} = 5.5V, V_{IN} = 0V<V_{IN}<V_{DD}

DC ELECTRICAL CHARACTERISTICS, continued

PARAMETER	SYM.	SPECIFICATION				TEST CONDITIONS
		MIN.	TYP.	MAX.	UNIT	
Input Current P1.5(RST pin)[1]	I_{IN2}	-55	-45	-30	µA	V_{DD} = 5.5V, V_{IN} = 0.45V
Input Leakage Current P0, P1, P2 (Open Drain)	I_{LK}	-10	-	+10	µA	V_{DD} = 5.5V, 0<V_{IN}<V_{DD}
Logic 1 to 0 Transition Current P0, P1, P2	I_{TL} [*3]	-500	-	-200	µA	V_{DD} = 5.5V, V_{IN}<2.0V
Input Low Voltage P0, P1, P2 (TTL input)	V_{IL1}	0	-	1.0	V	V_{DD} = 4.5V
		0	-	0.6		V_{DD} = 2.7V
Input High Voltage P0, P1, P2 (TTL input)	V_{IH1}	2.2	-	V_{DD} +0.2	V	V_{DD} = 5.5V
		1.8	-	V_{DD} +0.2		V_{DD} =3.0V
Input Low Voltage XTAL1[*2]	V_{IL3}	0	-	0.8	V	V_{DD} = 4.5V
		0	-	0.4		V_{DD} = 3.0V
Input High Voltage XTAL1[*2]	V_{IH3}	3.5	-	V_{DD} +0.2	V	V_{DD} = 5.5V
		2.4	-	V_{DD} +0.2		V_{DD} = 3.0V
Negative going threshold (Schmitt input)	V_{ILS}	-0.5	-	0.3V_{DD}	V	
Positive going threshold (Schmitt input)	V_{IHS}	0.7V_{DD}	-	V_{DD}+0.5	V	
Hysteresis voltage	V_{HY}		0.2V_{DD}		V	
Source Current P0, P1, P2 (Quasi-bidirectional and weak pull-up Mode)	I_{SR2}	-150	-210	-360	µA	V_{DD} = 4.5V, V_S = 2.4V
Sink Current P0, P1, P2 (Quasi-bidirectional and weak pull-up Mode)	I_{SK2}	13	18.5	24	mA	V_{DD} = 4.5V, V_S = 0.45V
Output Low Voltage P0, P1, P2 (PUSH-PULL Mode)	V_{OL1}	-	0.5	0.9	V	V_{DD} = 4.5V, I_{OL} = 20 mA
		-	0.1	0.4	V	V_{DD} = 2.7V, I_{OL} = 3.2 mA
Output High Voltage P0, P1, P2 (PUSH-PULL Mode)	V_{OH}	2.4	3.4	-	V	V_{DD} = 4.5V, I_{OH} = -16mA
		1.9	2.4	-		V_{DD} = 2.7V, I_{OH} = -3.2mA
Brownout voltage with BOV=1	$V_{BO2.5}$	2.4	-	2.7	V	
Brownout voltage with BOV=0	$V_{BO3.8}$	3.5	-	4	V	
Comparator Reference Voltage	Vref	1.02	1.20	1.31	V	

Notes:

*1. /RST pin has an internal pull-up resister.

*2. XTAL1 is a CMOS input.

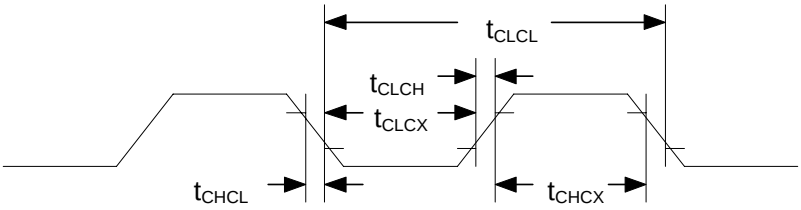
*3. Pins of P0, P1,P2 can source a transition current when they are being externally driven from 1 to 0. The transition current reaches its maximum value when Vin approximates to 2V.

27.3 The COMPARATOR ELECTRICAL CHARACTERISTICS

(V_{DD}–V_{SS} = 3.0~5V, TA = -40~85°C, Fosc = 20MHz, unless otherwise specified.)

PARAMETER	SYMBOL	SPECIFICATION				TEST CONDITIONS
		MIN.	TYP.	MAX.	UNIT	
Common mode range comparator inputs	V_{CR}	0		V_{DD}-0.3	V	
Common mode rejection ratio	CMRR			-50	dB	
Response time	t_{RS}	-	30	100	ns	
Comparator enable to output valid time	t_{EN}	-	1	5	us	
Input leakage current, comparator	I_{IL}	-10	0	10	uA	0< V_{IN} <V_{DD}

27.4 AC ELECTRICAL CHARACTERISTICS



Note: Duty cycle is 50%.

27.5 EXTERNAL CLOCK CHARACTERISTICS

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNITS	NOTES
Clock High Time	t_{CHCX}	12.5	-	-	nS	
Clock Low Time	t_{CLCX}	12.5	-	-	nS	
Clock Rise Time	t_{CLCH}	-	-	10	nS	
Clock Fall Time	t_{CHCL}	-	-	10	nS	

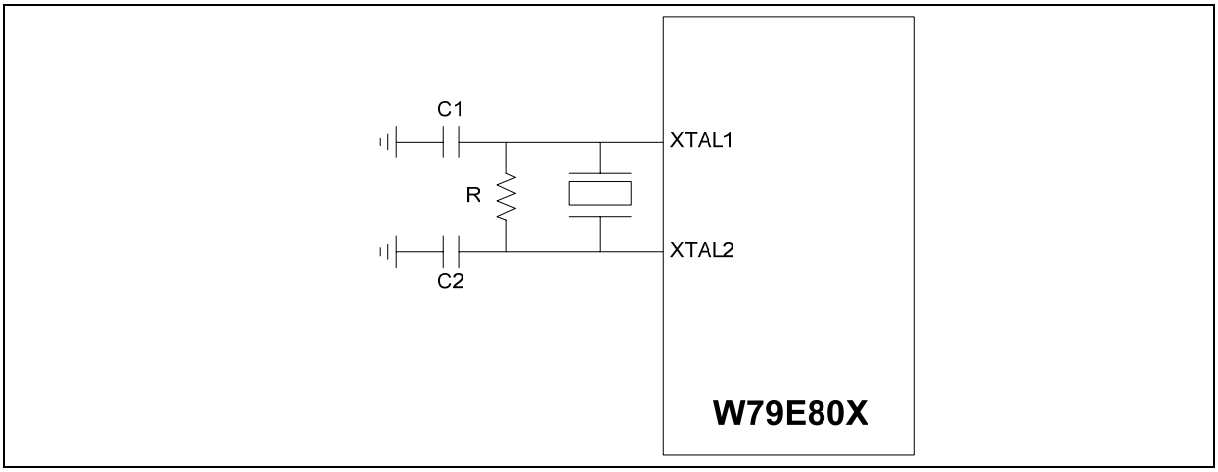
27.6 AC SPECIFICATION

PARAMETER	SYMBOL	VARIABLE CLOCK MIN.	VARIABLE CLOCK MAX.	UNITS
Oscillator Frequency	$1/t_{CLCL}$	0	20	MHz

27.7 TYPICAL APPLICATION CIRCUITS

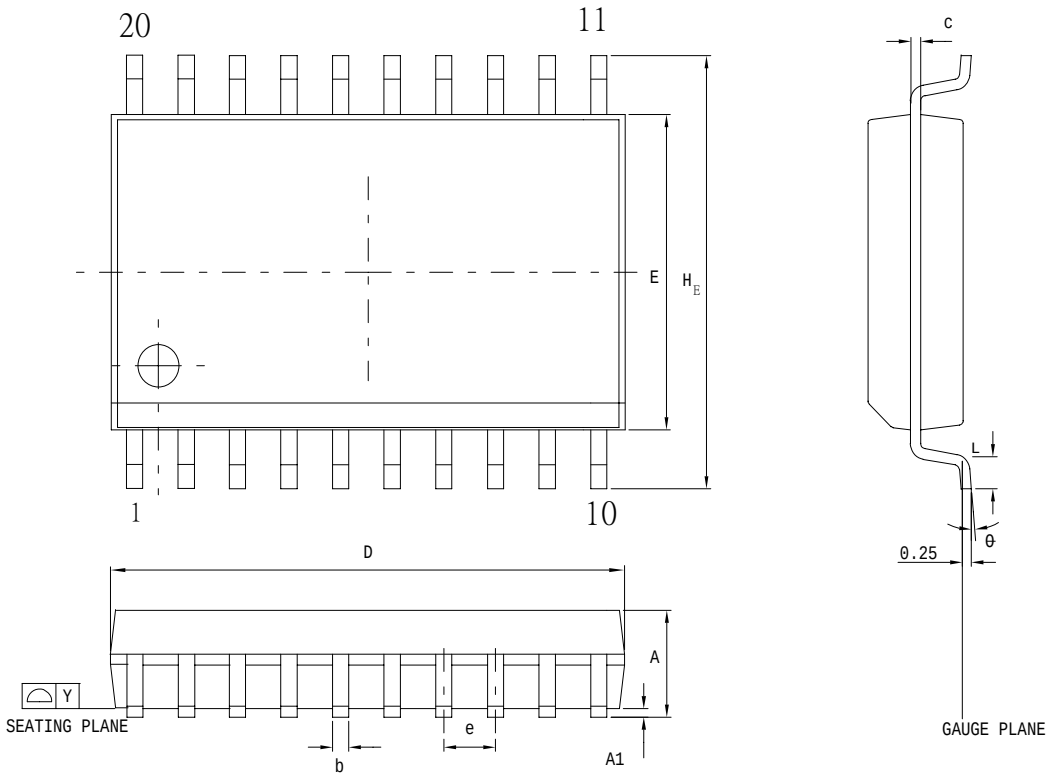
CRYSTAL	C1	C2	R
4MHz ~ 20 MHz	without	without	without

The above table shows the reference values for crystal applications.



28. PACKAGE DIMENSIONS

28.1 20L SOP-300mil

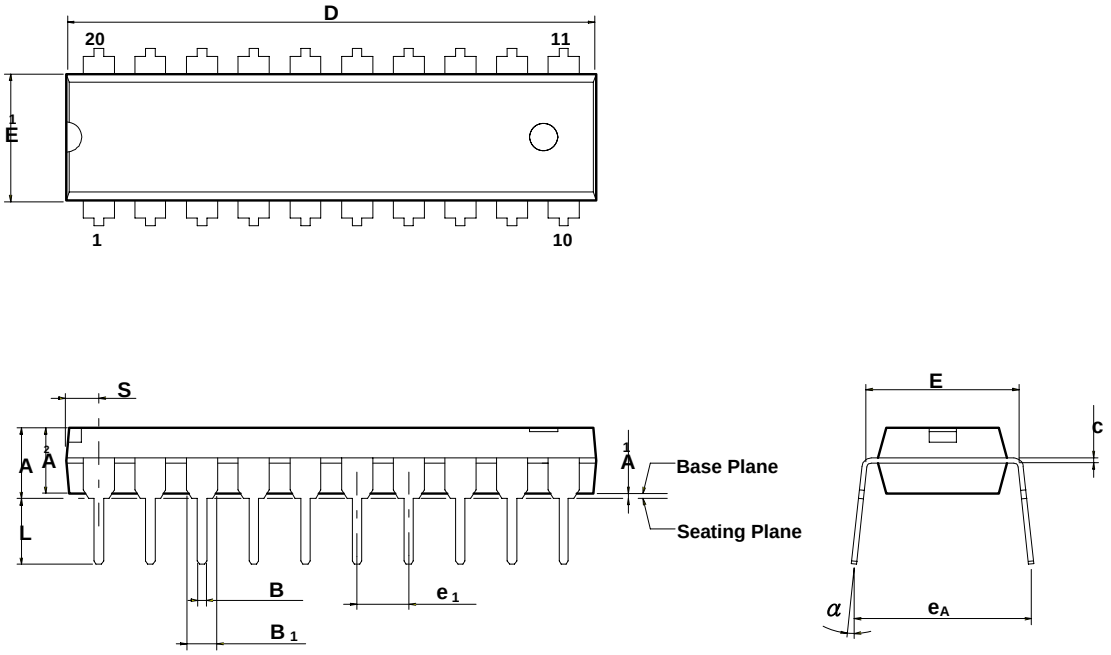


Control demensions are in milmeters .

SYMBOL	DIMENSION IN MM		DIMENSION IN INCH	
	MIN.	MAX.	MIN.	MAX.
A	2.35	2.65	0.093	0.104
A1	0.10	0.30	0.004	0.012
b	0.33	0.51	0.013	0.020
c	0.23	0.32	0.009	0.013
E	7.40	7.60	0.291	0.299
D	12.60	13.00	0.496	0.512
e	1.27 BSC		0.050 BSC	
H_E	10.00	10.65	0.394	0.419
Y	—	0.10	—	0.004
L	0.40	1.27	0.016	0.050
θ	0	8	0	8

Figure 28-1: 20L SOP-300mil

28.2 20L PDIP 300mil



Symbol	Dimension in inch			Dimension in mm		
	Min	Nom	Max	Min	Nom	Max
A	—	—	0.175	—	—	4.45
A_1	0.010	—	—	0.25	—	—
A_2	0.125	0.130	0.135	3.18	3.30	3.43
B	0.016	0.018	0.022	0.41	0.46	0.56
B_1	0.058	0.060	0.064	1.47	1.52	1.63
c	0.008	0.010	0.014	0.20	0.25	0.36
D	—	1.026	1.040	—	20.06	26.42
E	0.290	0.300	0.310	7.37	7.62	7.87
E_1	0.245	0.250	0.255	6.22	6.35	6.48
e_1	0.090	0.100	0.110	2.29	2.54	2.79
L	0.120	0.130	0.140	3.05	3.30	3.56
α	0	—	15	0	—	15
e_A	0.335	0.355	0.375	8.51	9.02	9.53
S	—	—	0.075	—	—	1.91

Figure 28-2: 20L PDIP 300mil

29. REVISION HISTORY

REVISION	DATE	PAGE	DESCRIPTION
A1	May 4, 2007	-	Initial Issued
A2	Jul. 16, 2007	16 28 29 56 60 105 88	1. Added SFR reg bit P1M1.2, P1M2.2, P1M1.3, P1M2.3. 2. Removed Port1 output mode reg bit P1M1.5, P1M2.5 3. Revised reg bit ENCLK description 4. Changed the “external reset pin has to be held low for at least two machine cycles”.(not held high) 5. Changed the “All the bits that generate interrupts can be set or reset by software”. (not by hardware) 6. Revised Figure 25-1: Application Circuit of ICP 7. Revised Figure 21-1: Oscillator

Important Notice

Winbond products are not designed, intended, authorized or warranted for use as components in systems or equipment intended for surgical implantation, atomic energy control instruments, airplane or spaceship instruments, transportation instruments, traffic signal instruments, combustion control instruments, or for other applications intended to support or sustain life. Further more, Winbond products are not intended for applications wherein failure of Winbond products could result or lead to a situation wherein personal injury, death or severe property or environmental damage could occur.

Winbond customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Winbond for any damages resulting from such improper use or sales.

Headquarters
No. 4, Creation Rd. III,
Science-Based Industrial Park,
Hsinchu, Taiwan
TEL: 886-3-5770066
FAX: 886-3-5665577
http://www.winbond.com.tw/

Winbond Electronics Corporation America
2727 North First Street, San Jose,
CA 95134, U.S.A.
TEL: 1-408-9436666
FAX: 1-408-5441798

Winbond Electronics (Shanghai) Ltd.
27F, 2299 Yan An W. Rd. Shanghai,
200336 China
TEL: 86-21-62365999
FAX: 86-21-62365998

Taipei Office
9F, No.480, Rueiguang Rd.,
Neihu District, Taipei, 114,
Taiwan, R.O.C.
TEL: 886-2-8177-7168
FAX: 886-2-8751-3579

Winbond Electronics Corporation Japan
7F Daini-ueno BLDG, 3-7-18
Shinyokohama Kohoku-ku,
Yokohama, 222-0033
TEL: 81-45-4781881
FAX: 81-45-4781800

Winbond Electronics (H.K.) Ltd.
Unit 9-15, 22F, Millennium City,
No. 378 Kwun Tong Rd.,
Kowloon, Hong Kong
TEL: 852-27513100
FAX: 852-27552064

Please note that all data and specifications are subject to change without notice.
All the trademarks of products and companies mentioned in this datasheet belong to their respective owners.