ADS7028 Small, 8-Channel, 12-Bit ADC With SPI Interface, GPIOs, and CRC

1 Features

- Small package size:
  - WQFN 3 mm × 3 mm
- 8 channels configurable as any combination of:
  - Up to 8 analog inputs, digital inputs, or digital outputs
- GPIOs for I/O expansion:
  - Open-drain, push-pull digital outputs
- Analog watchdog:
  - Programmable thresholds per channel
  - Event counter for transient rejection
- Wide operating ranges:
  - AVDD: 2.35 V to 5.5 V
  - DVDD: 1.65 V to 5.5 V
  - –40°C to +85°C temperature range
- Enhanced-SPI digital interface:
  - High-speed, 60-MHz interface
  - Achieve full throughput with >13.5-MHz SPI
- CRC for read/write operation:
  - CRC on data read/write
  - CRC on power-up configuration
- Programmable averaging filters
- Root-mean-square module:
  - 16-bit true RMS output
  - Programmable RMS time window
- Zero-crossing-detect module:
  - ZCD output corresponding to analog input
  - Built-in transient rejection and hysteresis
  - Digitally adjustable detection threshold

2 Applications

- Supervisory functions
- Portable instrumentation
- Appliances
- Telecommunication infrastructure
- Power-supply monitoring

3 Description

The ADS7028 is an easy-to-use, 8-channel, multiplexed, 12-bit, 1-MSPS, successive approximation register analog-to-digital converter (SAR ADC). The eight channels can be independently configured as either analog inputs, digital inputs, or digital outputs. The device has an internal oscillator for the ADC conversion process.

The ADS7028 communicates via an SPI-compatible interface and operates in either autonomous or single-shot conversion mode. The ADS7028 implements the analog watchdog function by event-triggered interrupts per channel using a digital window comparator with programmable high and low thresholds, hysteresis, and an event counter. The ADS7028 has a built-in cyclic redundancy check (CRC) for data read/write operations and the power-up configuration. The ADS7028 features a root-mean-square (RMS) module that computes a 16-bit true RMS result for any analog input channel. The integrated zero-crossing-detect (ZCD) module allows for transient rejection and hysteresis near the configurable threshold crossings.

Device Information[1]

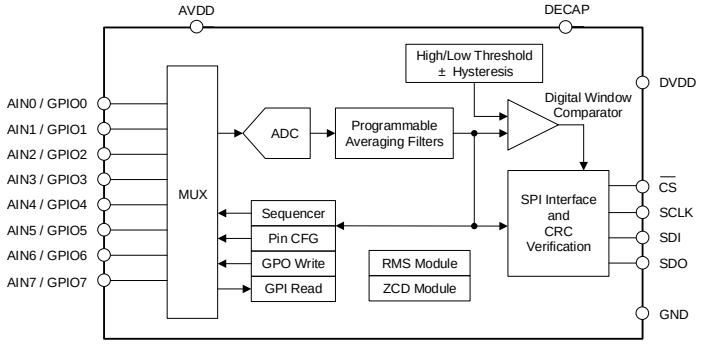
PART NUMBER	PACKAGE	BODY SIZE (NOM)
ADS7028	WQFN (16)	3.00 mm × 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.

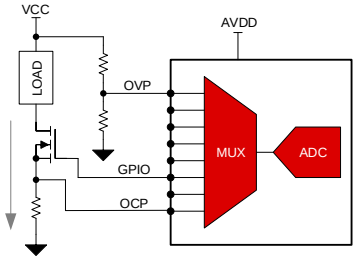
ADVANCE INFORMATION

ADS7028 Block Diagram and Applications

Device Block Diagram



Example System Architecture



OVP: Over voltage protection
OCP: Over current protection

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. ADVANCE INFORMATION for pre-production products; subject to change without notice.

Table of Contents

1 Features ... 1
2 Applications ... 1
3 Description ... 1
4 Revision History ... 2
5 Device Comparison Table ... 3
6 Pin Configuration and Functions ... 4
7 Specifications ... 5
7.1 Absolute Maximum Ratings ... 5
7.2 ESD Ratings ... 5
7.3 Recommended Operating Conditions ... 5
7.4 Thermal Information ... 5
7.5 Electrical Characteristics ... 6
7.6 Timing Requirements ... 6
7.7 Switching Characteristics ... 7
8 Detailed Description ... 9
8.1 Overview ... 9
8.2 Functional Block Diagram ... 9
8.3 Feature Description ... 10
8.4 Device Functional Modes ... 21
8.5 ADS7028 Registers ... 25
9 Application and Implementation ... 69
9.1 Application Information ... 69
9.2 Typical Applications ... 69
10 Power Supply Recommendations ... 71
10.1 AVDD and DVDD Supply Recommendations ... 71
11 Layout ... 72
11.1 Layout Guidelines ... 72
11.2 Layout Example ... 72
12 Device and Documentation Support ... 73
12.1 Receiving Notification of Documentation Updates 73
12.2 Community Resources ... 73
12.3 Trademarks ... 73
12.4 Electrostatic Discharge Caution ... 73
12.5 Glossary ... 73
13 Mechanical, Packaging, and Orderable Information ... 73

ADVANCE INFORMATION

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES
June 2019	*	Initial release.

Copyright © 2019, Texas Instruments Incorporated

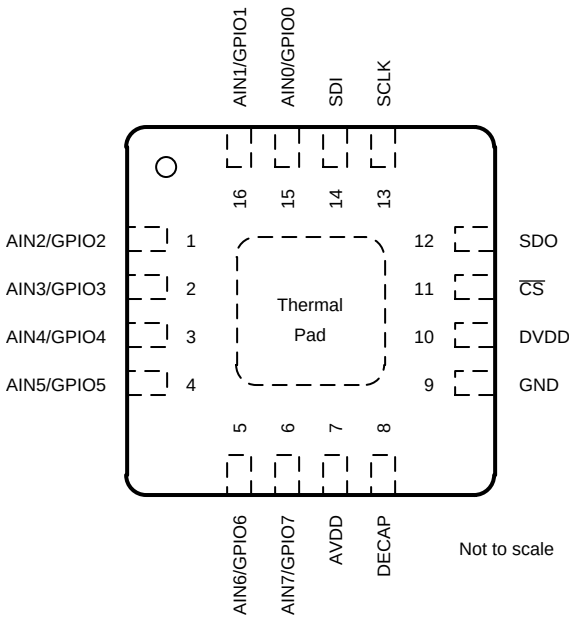
5 Device Comparison Table

PART NUMBER	DESCRIPTION	CRC MODULE	ZERO-CROSSING-DETECT (ZCD) MODULE	ROOT-MEAN-SQUARE (RMS) MODULE
ADS7028	8-channel, 12-bit ADC with SPI interface and GPIOs	Yes	Yes	Yes
ADS7038		Yes	No	No
ADS7038-Q1		Yes	No	No

ADVANCE INFORMATION

6 Pin Configuration and Functions

RTE Package
16-Pin WQFN
Top View



Pin Functions

PIN		FUNCTION(1)	DESCRIPTION
NAME	NO.		
AIN0/GPIO0	15	AI, DI, DO	Channel 0; can be configured as either an analog input (default), digital input, or digital output.
AIN1/GPIO1	16	AI, DI, DO	Channel 1; can be configured as either an analog input (default), digital input, or digital output.
AIN2/GPIO2	1	AI, DI, DO	Channel 2; can be configured as either an analog input (default), digital input, or digital output.
AIN3/GPIO3	2	AI, DI, DO	Channel 3; can be configured as either an analog input (default), digital input, or digital output.
AIN4/GPIO4	3	AI, DI, DO	Channel 4; can be configured as either an analog input (default), digital input, or digital output.
AIN5/GPIO5	4	AI, DI, DO	Channel 5; can be configured as either an analog input (default), digital input, or digital output.
AIN6/GPIO6	5	AI, DI, DO	Channel 6; can be configured as either an analog input (default), digital input, or digital output.
AIN7/GPIO7	6	AI, DI, DO	Channel 7; can be configured as either an analog input (default), digital input, or digital output.
AVDD	7	Supply	Analog supply input, also used as the reference voltage to the ADC; connect a 1-µF decoupling capacitor to GND.
$\overline{CS}$	11	DI	Chip-select input pin; active low. The device takes control of the data bus when $\overline{CS}$ is low. The device starts converting the active input channel on the rising edge of $\overline{CS}$. SDO goes hi-Z when $\overline{CS}$ is high.
DECAP	8	Supply	Connect a decoupling capacitor to this pin for the internal power supply.
DVDD	10	Supply	Digital I/O supply voltage; connect a 1-µF decoupling capacitor to GND.
GND	9	Supply	Ground for the power supply; all analog and digital signals are referred to this pin voltage.
SCLK	13	DI	Serial clock for the SPI interface.
SDI	14	DI	Serial data in for the device.
SDO	12	DO	Serial data out for the device.

(1) AI = analog input, DI = digital input, and DO = digital output.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

7 Specifications

7.1 Absolute Maximum Ratings

over operating ambient temperature range (unless otherwise noted)(1)

	MIN	MAX	UNIT
DVDD to GND	–0.3	5.5	V
AVDD to GND	–0.3	5.5	V
AINx / GPOx(2) to GND	GND – 0.3	AVDD + 0.3	V
Digital input to GND	GND – 0.3	5.5	V
Current through any pin except supply pins(3)	–10	10	mA
Junction temperature, T_J	–40	125	°C
Storage temperature, T_{stg}	–60	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Rating* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Condition*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) AINx / GPIOx refers to pins 1, 2, 3, 4, 5, 6, 15, and 16.
(3) Pin current must be limited to 10mA or less.

7.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins(1)	±2000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins(2)	±500	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)(1)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER SUPPLY						
AVDD	Analog supply voltage		2.35	3.3	5.5	V
DVDD	Digital supply voltage		1.65	3.3	5.5	V
ANALOG INPUTS						
FSR	Full-scale input range	AIN_X - GND	0		AVDD	V
V_{IN}	Absolute input voltage	AIN_X - GND	–0.1		AVDD + 0.1	V
TEMPERATURE RANGE						
T_A	Ambient temperature		–40	25	85	℃

(1) AINx refers to AIN0, AIN1, AIN2, AIN3, AIN4, AIN5, AIN6, and AIN7.

7.4 Thermal Information

THERMAL METRIC(1)		ADS7028 RTE (WQFN) 16 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	49.7	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	53.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	24.7	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	1.3	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	24.7	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	9.3	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

7.5 Electrical Characteristics

at AVDD = 5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +85°C; typical values at T_A = 25°C

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALOG INPUTS						
C_{SH}	Sampling capacitance			12		pF
DC PERFORMANCE						
	Resolution	No missing codes		12		bits
DNL	Differential nonlinearity		–0.9	±0.2	0.9	LSB
INL	Integral nonlinearity		–2	±0.5	2	LSB
$V_{(OS)}$	Input offset error	Post offset calibration	–2	±0.3	2	LSB
	Input offset thermal drift	Post offset calibration		±5		ppm/°C
G_E	Gain error		–0.1	±0.05	0.1	%FSR
	Gain error thermal drift			±5		ppm/°C
AC PERFORMANCE						
SINAD	Signal-to-noise + distortion ratio	AVDD = 5 V, f_{IN} = 2 kHz	68.5	71.5		dB
		AVDD = 3 V, f_{IN} = 2 kHz	67.5	70.5		
SNR	Signal-to-noise ratio	AVDD = 5 V, f_{IN} = 2 kHz	69	72		dB
		AVDD = 3 V, f_{IN} = 2 kHz	68	71		
	Isolation crosstalk	f_{IN} = 100 kHz		–100		dB
DECAP Pin						
	Decoupling capacitor on DECAP pin		0.1	1		µF
SPI INTERFACE ($\overline{CS}$, SCLK, SDI, SDO)						
V_{IH}	Input high logic level		0.7 x DVDD		5.5	V
V_{IL}	Input low logic level		–0.3		0.3 x DVDD	V
V_{OH}	Output high logic level	Source current = 2 mA, DVDD > 2 V	0.8 x DVDD		DVDD	V
		Source current = 2 mA, DVDD ≤ 2 V	0.7 x DVDD		DVDD	
V_{OL}	Output low logic level	Sink current = 2 mA, DVDD > 2 V	0		0.4	V
		Sink current = 2 mA, DVDD ≤ 2 V	0		0.2 x DVDD	
GPIOs						
V_{IH}	Input high logic level		0.7 x AVDD		AVDD + 0.3	V
V_{IL}	Input low logic level		–0.3		0.3 x AVDD	V
	Input leakge current	GPIO configured as input		10	100	nA
V_{OH}	Output high logic level	GPO_DRIVE_CFG = push-pull, I_{SOURCE} = 2 mA	0.8 x AVDD		AVDD	V
V_{OL}	Output low logic level	I_{SINK} = 2 mA	0		0.2 x AVDD	V
I_{OH}	Output high source current	V_{OH} > 0.7 x AVDD			5	mA
I_{OL}	Output low sink current	V_{OL} < 0.3 x AVDD			5	mA
POWER-SUPPLY CURRENTS						
I_{AVDD}	Analog supply current	Full throughput, AVDD = 5 V			2.66	mA
		Full throughput, AVDD = 3 V			1.56	
		No conversion, AVDD = 5 V		0.03	0.05	

7.6 Timing Requirements

at AVDD = 5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +85°C; typical values at T_A = 25°C

	MIN	MAX	UNIT
CONVERSION CYCLE			

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Timing Requirements (continued)

at AVDD = 5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +85°C; typical values at T_A = 25°C

		MIN	MAX	UNIT
f_{CYCLE}	Sampling frequency		1000	kSPS
t_{CYCLE}	ADC cycle-time period	1 / f_{CYCLE}		s
t_{ACQ}	Acquisition time	300		ns
t_{QT_ACQ}	Quiet acquisition time	10		ns
t_{D_CNVCAP}	Quiet conversion time	10		ns
t_{WH_CSZ}	Pulse duration: $\overline{CS}$ high	10		ns
t_{WL_CSZ}	Pulse duration: $\overline{CS}$ low	10		ns
SPI INTERFACE TIMINGS				
f_{CLK}	Maximum SCLK frequency		60	MHz
t_{CLK}	Minimum SCLK time period	16.67		ns
t_{PH_CK}	SCLK high time	0.45	0.55	t_{CLK}
t_{PL_CK}	SCLK low time	0.45	0.55	t_{CLK}
t_{SU_CSCK}	Setup time: $\overline{CS}$ falling to the first SCLK capture edge	5		ns
t_{SU_CKDI}	Setup time: SDI data valid to the SCLK capture edge	1.2		ns
t_{HT_CKDI}	Hold time: SCLK capture edge to data valid on SDI	0.65		ns
t_{D_CKCS}	Delay time: last SCLK falling to $\overline{CS}$ rising	5		ns

7.7 Switching Characteristics

at AVDD = 5 V, DVDD = 1.65 V to 5.5 V, and maximum throughput (unless otherwise noted); minimum and maximum values at T_A = –40°C to +85°C; typical values at T_A = 25°C

PARAMETER		Test Conditions	MIN	MAX	UNIT
CONVERSION CYCLE					
t_{CONV}	ADC conversion time			600	ns
t_{ACQ}	Acquisition time		400		ns
RESET and ALERT					
t_{PU}	Power-up time for device	AVDD ≥ 2.35 V, C_{DECAP} = 1 µF		5	ms
t_{RST}	Delay time; RST bit = 1b to device reset complete(1)			5	ms
t_{ALERT_HI}	ALERT high period	ALERT_LOGIC[1:0] = 1x	85	105	ns
t_{ALERT_LO}	ALERT low period	ALERT_LOGIC[1:0] = 1x	85	105	ns
SPI INTERFACE TIMINGS					
t_{DEN_CSDO}	Delay time: $\overline{CS}$ falling to data enable			15	ns
t_{DZ_CSDO}	Delay time: $\overline{CS}$ rising to SDO going Hi-Z			15	ns
t_{D_CKDO}	Delay time: SCLK launch edge to (next) data valid on SDO			15	ns

(1) RST bit is automatically reset to 0b after t_{RST}.

ADVANCE INFORMATION

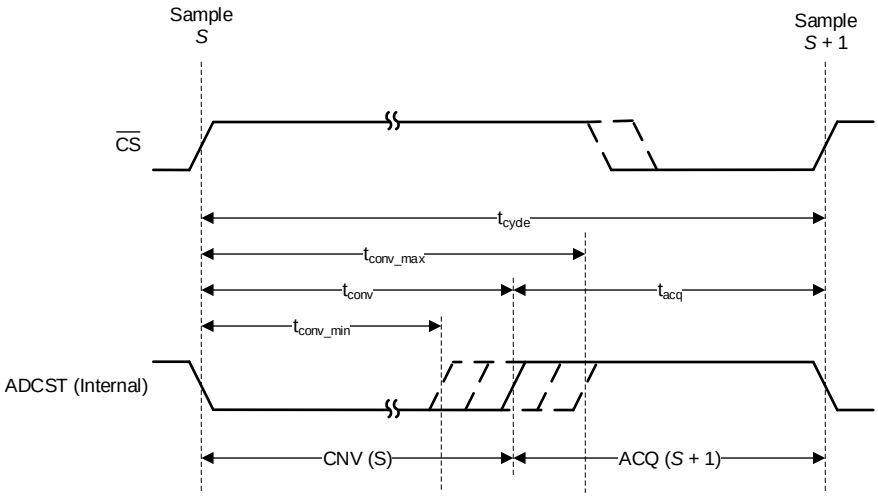
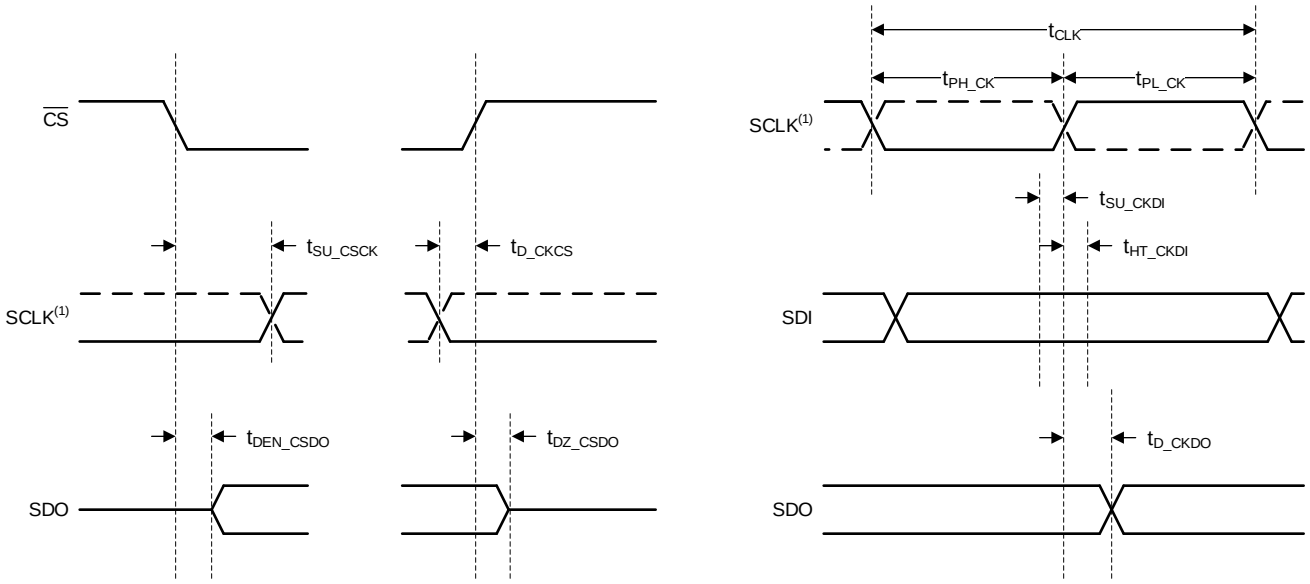


Figure 1. Conversion Cycle Timing



(1) The SCLK polarity, launch edge, and capture edge depend on the SPI protocol selected.

Figure 2. SPI-Compatible Serial Interface Timing

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

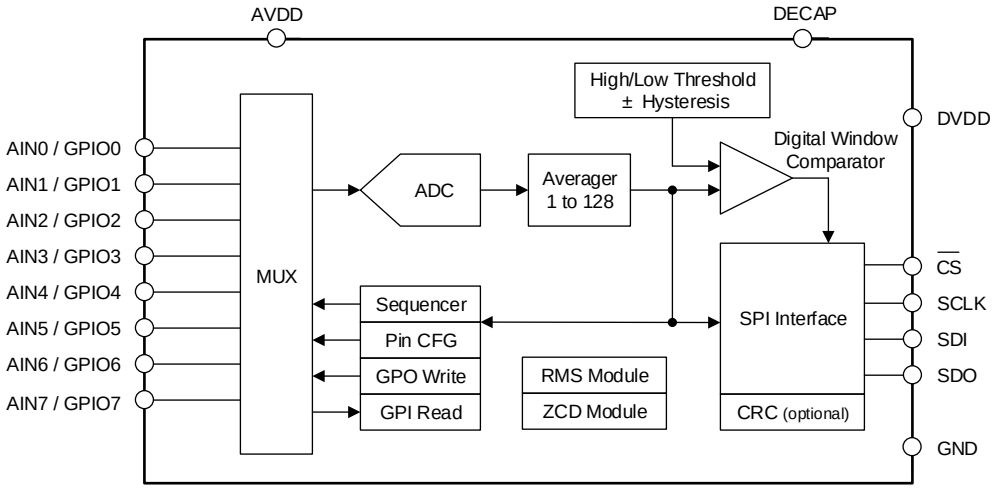
8 Detailed Description

8.1 Overview

The ADS7028 is a small, eight-channel, multiplexed, 12-bit, 1-MSPS, analog-to-digital converter (ADC) with an enhanced-SPI serial interface. The eight channels of the ADS7028 can be individually configured as either analog inputs, digital inputs, or digital outputs. The device includes a digital comparator which can be used to interrupt the host when a programmed high or low threshold is crossed on any input channel. The device uses an internal oscillator for conversion. The ADC can be used in manual mode for reading ADC data over the SPI interface or in autonomous mode for monitoring the analog inputs without an active SPI interface.

The device features a programmable averaging filter that outputs a 16-bit result for enhanced resolution. The root-mean-square (RMS) module computes a 16-bit true RMS result of any analog input channel over a configurable time window. The zero-crossing-detect (ZCD) module can be used to generate a digital output corresponding to the programmable threshold crossings of any analog input channel.

8.2 Functional Block Diagram



ADVANCE INFORMATION

8.3 Feature Description

8.3.1 Multiplexer and ADC

The eight channels of the multiplexer can be independently configured as ADC inputs or general-purpose inputs/outputs (GPIOs). Figure 3 shows that each input pin has ESD protection diodes to AVDD and GND. On power-up or after device reset, all eight multiplexer channels are configured as analog inputs.

Figure 3 shows an equivalent circuit for pins configured as analog inputs. The ADC sampling switch is represented by ideal switch (SW) in series with the resistor R_{SW} (typically 150 Ω) and the sampling capacitor, C_{SH} (typically 12 pF).

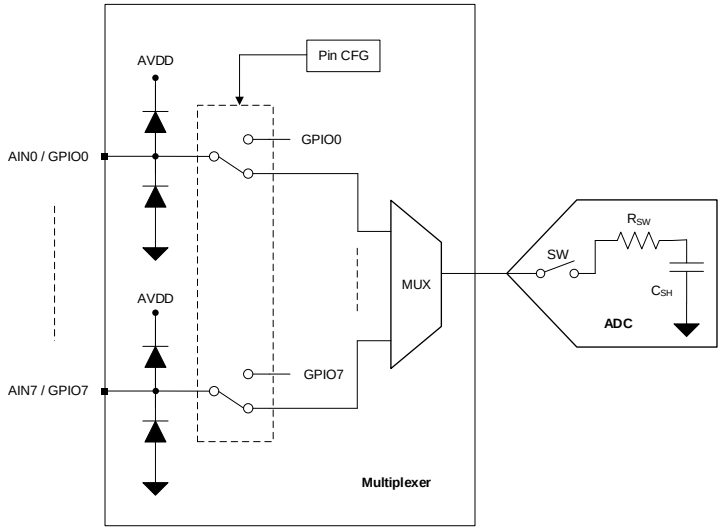


Figure 3. Analog Inputs, GPIOs, and ADC Connections

During acquisition, the SW switch is closed to allow the signal on the selected analog input channel to charge the internal sampling capacitor. During conversion, the SW switch is opened to disconnect the analog input channel from the sampling capacitor.

The multiplexer channels can be configured as GPIOs in the PIN_CFG register. The direction of a GPIO (either as an input or an output) can be set in the GPIO_CFG register. The logic level on the channels configured as digital inputs can be read from the GPI_VALUE register. The digital outputs can be accessed by writing to the GPO_OUTPUT_VALUE register. The digital outputs can be configured as either open-drain or push-pull in the GPO_DRIVE_CFG register.

8.3.2 Reference

The device uses the analog supply voltage (AVDD) as a reference for the analog-to-digital conversion process. TI recommends connecting a 1-µF, low-equivalent series resistance (ESR) ceramic decoupling capacitor between the AVDD and GND pins.

8.3.3 ADC Transfer Function

The ADC output is in straight binary format. Equation 1 computes the ADC resolution:

$$1\ LSB = V_{REF} / 2^N \quad (1)$$

where:

- V_{REF} = AVDD
- N = 12

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Feature Description (continued)

Figure 4 and Table 1 detail the transfer characteristics for the device.

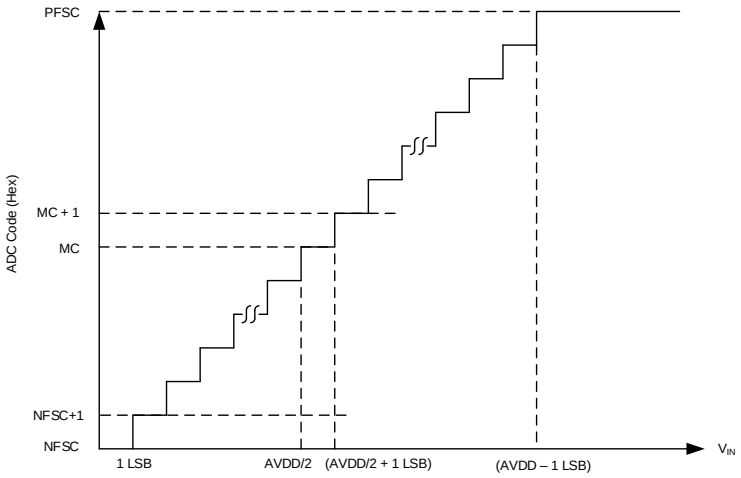


Figure 4. Ideal Transfer Characteristics

Table 1. Transfer Characteristics

INPUT VOLTAGE FOR SINGLE-ENDED INPUT	CODE	DESCRIPTION	IDEAL OUTPUT CODE
≤1 LSB	NFSC	Negative full-scale code	000
1 LSB to 2 LSBs	NFSC + 1	—	001
(AVDD / 2) to (AVDD / 2) + 1 LSB	MC	Mid code	800
(AVDD / 2) + 1 LSB to (AVDD / 2) + 2 LSB	MC + 1	—	801
≥ AVDD – 1 LSB	PFSC	Positive full-scale code	FFF

8.3.4 ADC Offset Calibration

The variation in ADC offset error resulting from changes in temperature or AVDD can be calibrated by setting the CAL bit in the GENERAL_CFG register. The CAL bit is reset to 0 after calibration. The host can poll the CAL bit to check the ADC offset calibration completion status.

ADVANCE INFORMATION

8.3.5 Programmable Averaging Filter

The ADS7028 features a built-in oversampling (OSR) function that can be used to average several samples. The averaging filter can be enabled by programming the OSR[2:0] bits in the OSR_CFG register. The averaging filter configuration is common to all analog input channels. Figure 5 shows that the averaging filter module output is 16 bits long. In manual conversion mode and auto-sequence mode, only the first conversion for the selected analog input channel must be initiated by the host; see the *Manual Mode* and *Auto-Sequence Mode* sections. As shown in Figure 5, any remaining conversions for the selected averaging factor are generated internally. The time required to complete the averaging operation is determined by the sampling speed and number of samples to be averaged. As shown in Figure 5, the 16-bit result can be read out after the averaging operation completes.

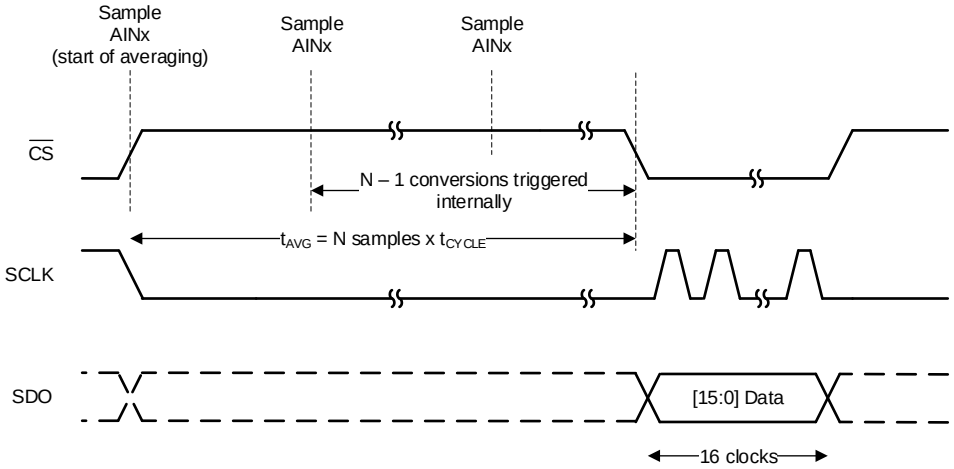


Figure 5. Averaging Example

In autonomous mode of operation, samples from analog input channels that are enabled in the AUTO_SEQ_CH_SEL register are averaged sequentially. The digital window comparator compares the top 12 bits of the 16-bit average result with the thresholds.

Equation 2 provides the LSB value of the 16-bit average result.

$$1\ LSB = \frac{AVDD}{2^{16}} \tag{2}$$

8.3.6 CRC on Data Interface

The ADS7028 features a cyclic redundancy check (CRC) module for checking the integrity of the data bits exchanged over the SPI interface. The CRC module is bidirectional, which appends an 8-bit CRC to every byte read from the device and also evaluates the CRC of every incoming byte over the SPI interface. The CRC module uses the CRC-8-CCITT polynomial ($x^8 + x^2 + x + 1$) for CRC computation.

To enable the CRC module, set the CRC_EN bit in the GENERAL_CFG register. Table 2 shows the different ways that a CRC error that occurs when configuring the ADS7028 can be detected.

Table 2. Configuring Notifications when CRC Error is Detected

CRC ERROR NOTIFICATION	CONFIGURATION	DESCRIPTION
ALERT	ALERT_CRCIN = 1b	ALERT (internal signal) is asserted if a CRC error is detected
Status flags	APPEND_STATUS = 10b	4-bit status flags are appended to the ADC data. See the *Output Data Format* section for details.
Register read	—	Read the CRCERR_IN bit to check if a CRC error was detected.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

When the ADS7028 detects a CRC error on the SPI interface, the erroneous data are ignored and the CRCERR_IN bit is set. Additional notifications can be enabled as described in Table 2. Further register writes are disabled until the CRCERR_IN bit is cleared by writing 1b to this bit. When using autonomous conversion mode, further conversions can be disabled on a CRC error on the SPI interface by setting CONV_ON_ERR = 1b.

8.3.7 General-Purpose I/Os

The eight channels of the ADS7028 can be independently configured as analog inputs, digital inputs, or digital outputs. Table 3 shows how the PIN_CFG and GPIO_CFG registers can be used to configure the device channels.

Table 3. Configuring Channels as Analog Inputs or GPIOs

PIN_CFG[7:0]	GPIO_CFG[7:0]	GPO_DRIVE_CFG[7:0]	CHANNEL CONFIGURATION
0	x	x	Analog input (default)
1	0	x	Digital input
1	1	0	Digital output; open-drain driver
1	1	1	Digital output; push-pull driver

Digital outputs can be configured to logic 1 or 0 by writing to the GPO_OUTPUT_VALUE register. Reading the GPI_VALUE register returns the logic level for all channels configured as digital inputs or digital outputs. The GPI_VALUE register can be read to detect a failure in external components, such as a floating pullup resistor or a low-impedance pulldown resistor, that prevents digital outputs being set to the desired logic level.

8.3.8 Oscillator and Timing Control

The device uses an internal oscillator for conversion. When using the averaging module, the host initiates the first conversion and subsequent conversions are generated internally by the device. Also, in autonomous mode of operation, the start of the conversion signal is generated by the device. Table 4 describes how the sampling rate can be controlled by the OSC_SEL and CLK_DIV[3:0] register fields when the device generates the start of the conversion.

Table 4. Configuring Sampling Rate for Internal Conversion Start Control

CLK_DIV[3:0]	OSC_SEL = 0		OSC_SEL = 1	
	SAMPLING FREQUENCY, f_{CYCLE} (kSPS)	CYCLE TIME, t_{CYCLE} (µs)	SAMPLING FREQUENCY, f_{CYCLE} (kSPS)	CYCLE TIME, t_{CYCLE} (µs)
0000b	1000	1	31.25	32
0001b	666.7	1.5	20.83	48
0010b	500	2	15.63	64
0011b	333.3	3	10.42	96
0100b	250	4	7.81	128
0101b	166.7	6	5.21	192
0110b	125	8	3.91	256
0111b	83	12	2.60	384
1000b	62.5	16	1.95	512
1001b	41.7	24	1.3	768
1010b	31.3	32	0.98	1024
1011b	20.8	48	0.65	1536
1100b	15.6	64	0.49	2048
1101b	10.4	96	0.33	3072

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

The conversion time of the device, given by t_{CONV} in the *Switching Characteristics* table, is independent of the OSC_SEL and CLK_DIV[3:0] configuration.

8.3.9 Output Data Format

Figure 6 shows various SPI frames for reading data. The data output is MSB aligned. If averaging is enabled the output data from the ADC are 16 bits long, otherwise the output data are 12 bits long. Optionally, a 4-bit channel ID or status flags can be appended at the end of the output data by configuring the APPEND_STATUS[1:0] field.

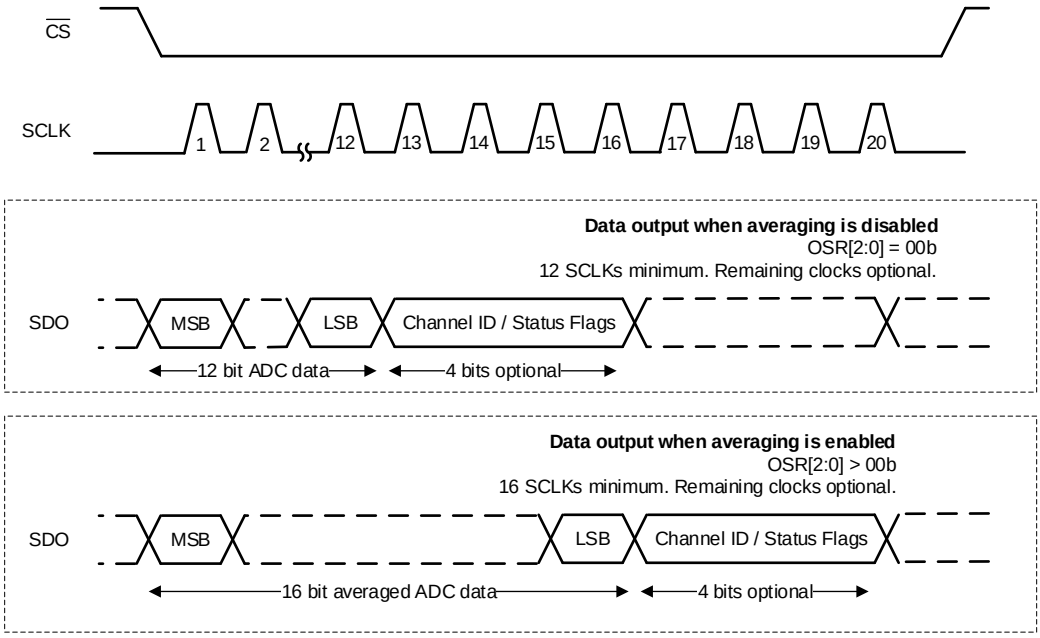


Figure 6. SPI Frames for Reading Data

8.3.10 Zero-Crossing-Detect Module

The zero-crossing-detect (ZCD) module generates a digital output corresponding to the designated analog input signal crossing a configured threshold. Figure 7 shows the digital output corresponding to the threshold crossings of an analog input. In order to detect the threshold crossings on a particular analog input, configure the 4-bit channel ID in the ZCD_CHID register. The threshold crossing to be detected can be configured in the corresponding HIGH_TH register. The output of the ZCD module can be connected to any digital output by configuring the ZCD_TRIG_EN and GPO_VALUE_ZCD registers.

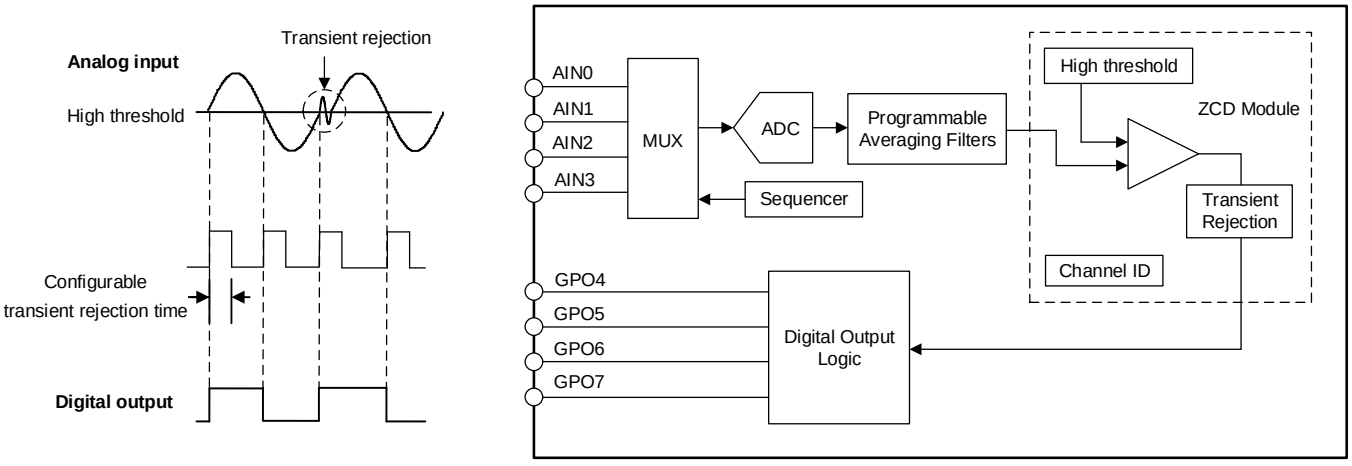


Figure 7. ZCD Module Operation and Block Diagram

Copyright © 2019, Texas Instruments Incorporated

ADVANCE INFORMATION

The ADC conversion result of the selected analog input channel is compared with the digital threshold that then sets the digital output accordingly. Transients near zero crossings can be rejected, as calculated in Equation 3, by configuring the ZCD_BLANKING register.

$$\text{transient rejection time} = \text{MULT_EN} \times \text{ZCD_BLANKING}[6:0] \times \frac{1}{\text{sampling rate for ZCD channel}} \text{seconds} \quad (3)$$

8.3.11 Digital Window Comparator

The internal digital window comparator (DWC) is available in both conversion modes (manual and autonomous). The DWC outputs an internal ALERT signal. The internal ALERT signal can be output on any one of the digital output channels by configuring the ALERT_PIN register. Figure 8 provides a block diagram for the digital window comparator.

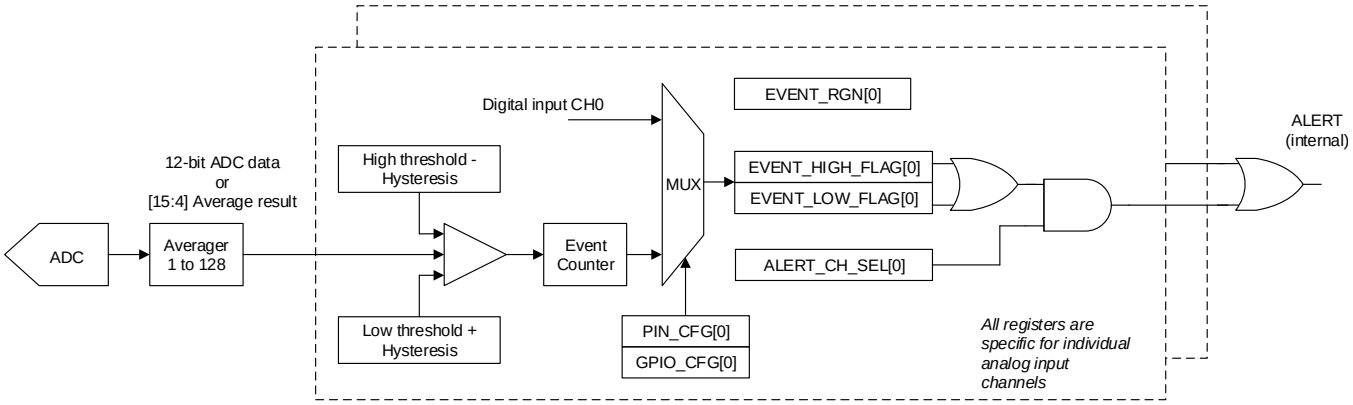


Figure 8. Digital Window Comparator Block Diagram

The low-side threshold, high-side threshold, event counter, and hysteresis parameters are independently programmable for each input channel. Figure 9 illustrates that the window comparator can monitor events for every analog input channel.

ADVANCE INFORMATION

ADVANCE INFORMATION

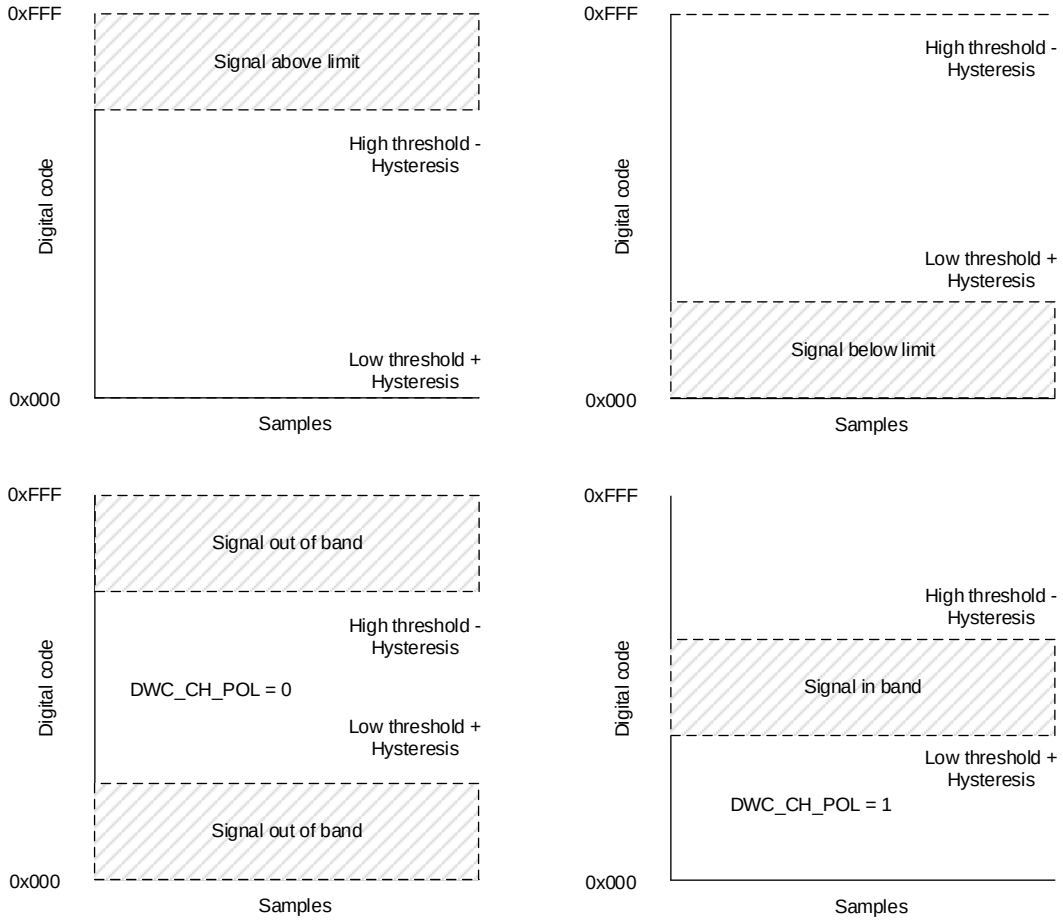


Figure 9. Event Monitoring With the Window Comparator

To enable the digital window comparator, set the DWC_EN bit in the GENERAL_CFG register. By default, hysteresis = 0, high threshold = 0xFFF, and low threshold = 0x000. For detecting when a signal is in-band, the EVENT_RGN register must be configured. In each of the cases shown in Figure 9, either or both ALERT_HIGH_FLAG and ALERT_LOW_FLAG can be set. The programmable event counter counts consecutive threshold violations before alert flags are set. The event count can be set to a higher value to avoid transients in the input signal setting the alert flags.

In order to assert the ALERT signal (internal) when the alert flag is set for a particular analog input channel, set the corresponding bit in the DWC_CH_SEL register. Alert flags are set, irrespective of the DWC_CH_SEL configuration, if DWC_EN = 1 and high or low thresholds are exceeded.

8.3.11.1 Interrupts From Digital Inputs

Table 5 shows that rising edge or falling edge events can be detected on channels configured as digital inputs.

Table 5. Configuring Interrupts From Digital Inputs

PIN_CFG[7:0]	GPIO_CFG[7:0]	EVENT_RGN[7:0]	EVENT DESCRIPTION
1	0	0	ALERT_HIGH_FLAG is set on the rising edge on the digital input channel
1	0	1	ALERT_LOW_FLAG is set on the falling edge on the digital input channel

Copyright © 2019, Texas Instruments Incorporated

8.3.11.2 Triggering Digital Outputs With Alert and ZCD

Figure 10 shows that digital outputs can be updated in response to alerts from individual channels or synchronous to the zero-crossing-detect signal.

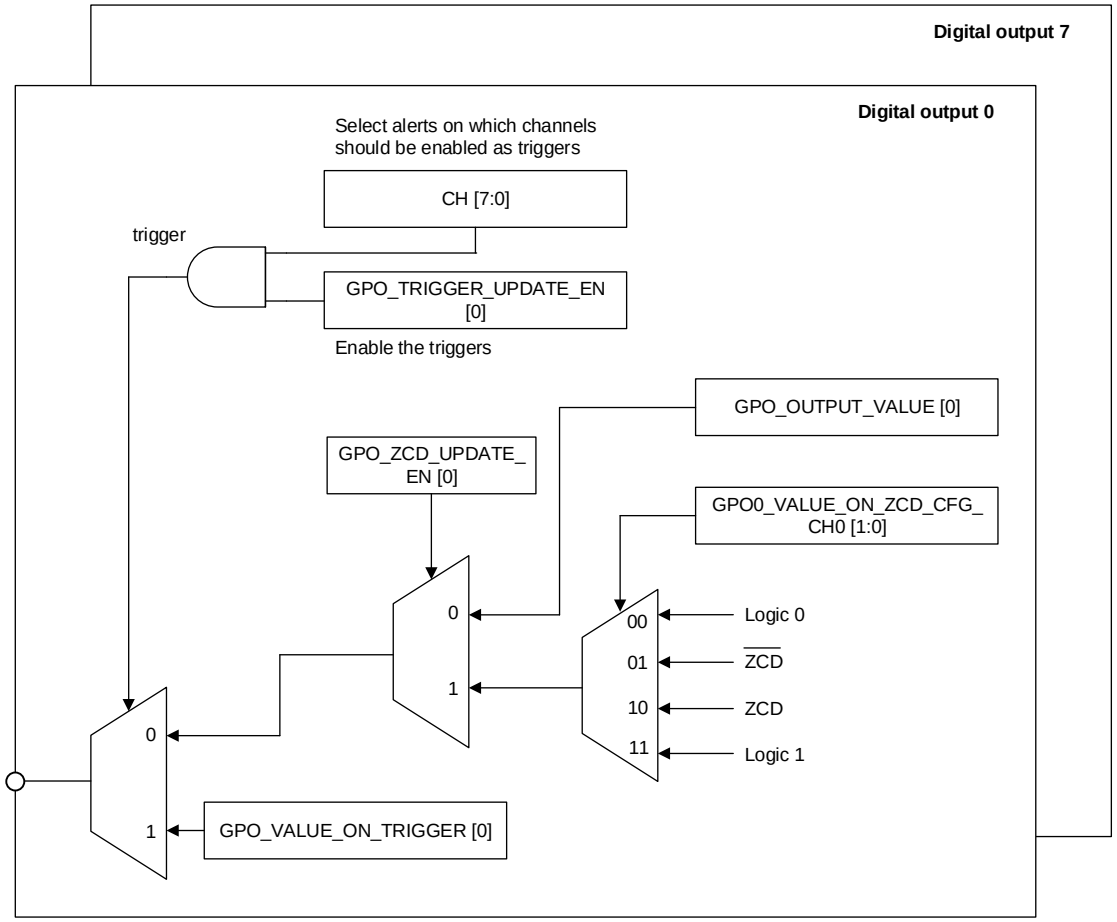


Figure 10. Block Diagram of the Digital Output Logic

8.3.11.2.1 Triggering Digital Outputs on Alerts

Any given digital output can be updated in response to an alert condition on one or more analog inputs and digital inputs. To update the digital output in response to alert conditions, configure the trigger and the value to be launched when the trigger occurs.

8.3.11.2.1.1 Trigger

The following events can act as triggers for updating the value on the digital output:

- An alert on one or more analog input channels. The digital window comparator must be enabled for these channels.
- An alert on one or more digital input channels. The digital window comparator must be enabled for these channels.

Configure the GPOx_TRIG_EVENT_SEL register to select which channels, analog inputs, or digital inputs can trigger an update on the digital output pin. After configuring the triggers for updating a digital output, the logic can be enabled by configuring the corresponding bit in the GPO_TRIGGER_UPDATE_EN register.

8.3.11.2.1.2 Output Value

The digital outputs can be set to logic 1 or logic 0 in response to triggers. The value to be updated on the digital output when a trigger event occurs can be configured in the GPO_VALUE_ON_TRIGGER register.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.3.11.2.2 Changing Digital Outputs Synchronous to ZCD

Individual digital outputs can be set to either logic 0, logic 1, ZCD, or $\overline{ZCD}$ synchronous to the zero-crossing-detect signal. This function can be enabled for individual digital outputs by configuring the GPO_VALUE_ON_ZCD_CFG_CHx field and setting the corresponding bit in the GPO_ZCD_UPDATE_EN [7:0] register. See the *Zero-Crossing-Detect Module* section for details about the operation of ZCD module and Figure 10 for a block diagram detailing controlling the digital outputs with the ZCD signal.

8.3.12 Root-Mean-Square Module

In the ADS7028, any one analog input channel can be selected for computing the RMS result. The RMS result is computed over a block of samples from the selected channel and result can be read from the RMS_RESULT_LSB and RMS_RESULT_MSB registers. As shown in Equation 4, compute the RMS result with the 16-bit square root mean of the accumulated result of the squares of the ADC conversion data.

$$RMS = \sqrt{\left(\frac{{D_1}^2 + {D_2}^2 + {D_3}^2 + \cdots + {D_N}^2}{N}\right) - b \times \left(\frac{D_1 + D_2 + D_3 + \cdots + D_N}{N}\right)^2}\ LSB \quad (4)$$

AC component DC component

In Equation 4, D is the data corresponding to the analog input channel selected for RMS measurement and N is the number of samples over which RMS is computed. The DC offset must be subtracted from the AC component because the analog input signal to the ADC is unipolar. DC subtraction can be enabled or disabled, given by b in Equation 4, by configuring the DC_SUB field. The size of a 1-LSB RMS result is given in Equation 5 and the RMS result is 16 bits long.

$$1\ LSB = AVDD / 2^{16} \quad (5)$$

The procedure for using the RMS module is outlined in the steps below:

1. Select the channel for RMS computation using the RMS_CHID field in the RMS_CFG register.
2. Define the time over which RMS is to be computed by configuring the RMS_SAMPLES field.
3. Start RMS computation by setting RMS_EN = 1 in the GENERAL_CFG register.
4. The RMS result is ready when the sample size defined by RMS_SAMPLES has been converted on the analog input channel selected for RMS computation.
5. To monitor for completion of the RMS computation, poll the RMS_DONE bit in the SYSTEM_STATUS register. The ALERT pin can also be used for requesting an interrupt by configuring the ALERT_RMS bit in the ALERT_MAP register.
6. For starting a new RMS measurement, write 1 to the RMS_EN bit in the GENERAL_CFG register.

8.3.13 Minimum, Maximum, and Latest Data Registers

The ADS7028 can record the minimum, maximum, and latest code (statistics registers) for every analog input channel. To enable or re-enable recording statistics, set the STATS_EN bit in the GENERAL_CFG register. Writing 1 to the STATS_EN bit reinitializes the statistics module. Afterwards, results from new conversions are recorded in the statistics registers.. Previous values can be read from the statistics registers until a new conversion result is available. Before reading the statistics registers, set STATS_EN = 0 to prevent any updates to this block of registers.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.3.14 Device Programming

8.3.14.1 Enhanced-SPI Interface

The device features an enhanced-SPI interface that allows the host controller to operate at slower SCLK speeds and still achieve full throughput. As described in Table 6, the host controller can use any of the four SPI-compatible protocols (SPI-00, SPI-01, SPI-10, or SPI-11) to access the device.

Table 6. SPI Protocols for Configuring the Device

PROTOCOL	SCLK POLARITY (At the $\overline{CS}$ Falling Edge)	SCLK PHASE (Capture Edge)	CPOL_CPHA[1:0]	DIAGRAM
SPI-00	Low	Rising	00b	Figure 11
SPI-01	Low	Falling	01b	Figure 12
SPI-10	High	Falling	10b	Figure 11
SPI-11	High	Rising	11b	Figure 12

On power-up or after coming out of any asynchronous reset, the device supports the SPI-00 protocol for data read and data write operations. To select a different SPI-compatible protocol, program the CPOL_CPHA[1:0] field. This first write operation must adhere to the SPI-00 protocol. Any subsequent data transfer frames must adhere to the newly-selected protocol.

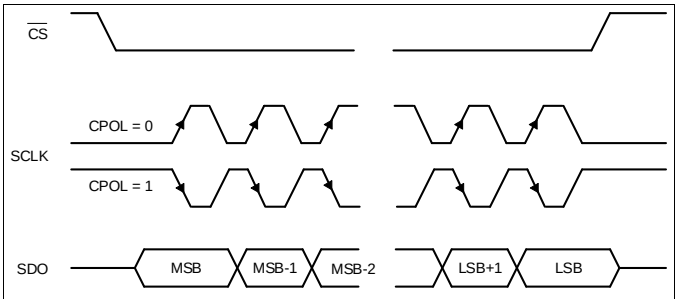


Figure 11. Standard SPI Timing Protocol (CPHA = 0)

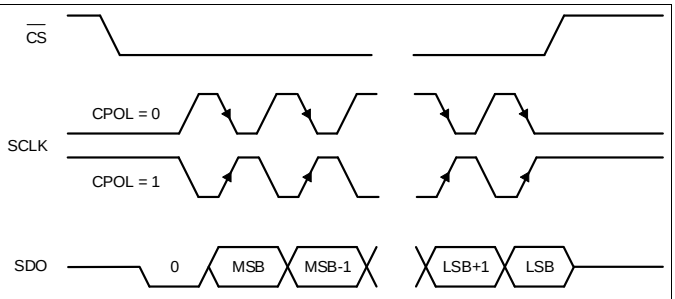


Figure 12. Standard SPI Timing Protocol (CPHA = 1)

8.3.14.2 Register Read/Write Operation

The device supports the commands listed in Table 7 to access the internal configuration registers.

Table 7. Opcodes for Commands

OPCODE	COMMAND DESCRIPTION
0000 0000b	No operation
0001 0000b	Single register read
0000 1000b	Single register write
0001 1000b	Set bit
0010 0000b	Clear bit

ADVANCE INFORMATION

8.3.14.2.1 Register Write

A 24-bit SPI frame is required for writing data to configuration registers. The 24-bit data on SDI, as shown in Figure 13. consists of an 8-bit write command (0000 1000b), an 8-bit register address, and 8-bit data. The write command is decoded on the $\overline{CS}$ rising edge and the specified register is updated with the 8-bit data specified during the register write operation.

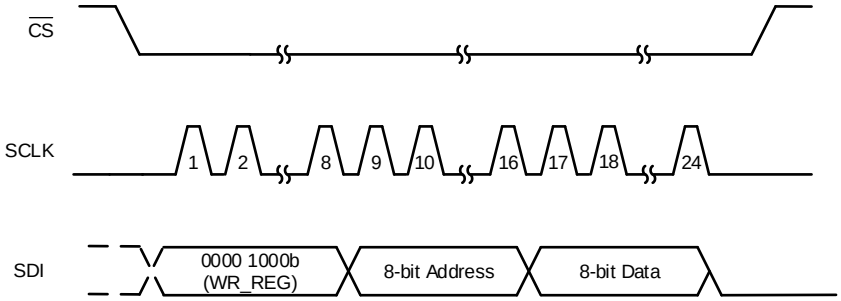


Figure 13. Register Write Operation

8.3.14.2.2 Register Read

Register read operation consists of two SPI frames: the first SPI frame initiates a register read and the second SPI frame reads data from the register address provided in the first frame. As shown in Figure 14, the 8-bit register address and the 8-bit dummy data are sent over the SDI pin during the first 24-bit frame with the read command (0001 0000b). On the rising edge of $\overline{CS}$, the read command is decoded and the requested register data are available for reading during the next frame. During the second frame, the first eight bits on SDO correspond to the requested register read. During the second frame, SDI can be used to initiate another operation or can be set to 0.

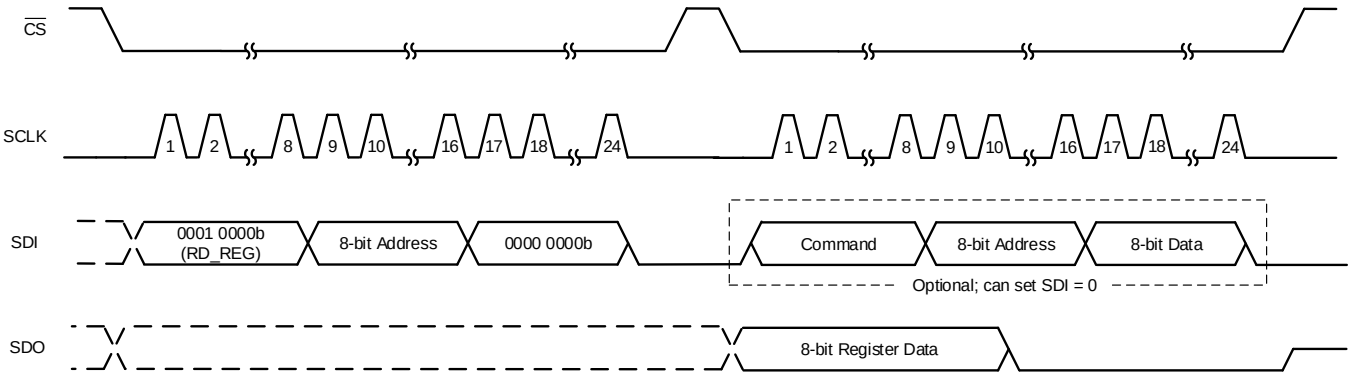


Figure 14. Register Read Operation

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.4 Device Functional Modes

Table 8 lists the functional modes supported by the ADS7028.

Table 8. Functional Modes

FUNCTIONAL MODE	CONVERSION CONTROL	MUX CONTROL	CONV_MODE[1:0]	SEQ_MODE[1:0]
Manual	$\overline{CS}$ rising edge	Register write to MANUAL_CHID	00b	00b
On-the-fly	$\overline{CS}$ rising edge	First 5 bits after the $\overline{CS}$ falling edge	00b	10b
Auto-sequence	$\overline{CS}$ rising edge	Channel sequencer	00b	01b
Autonomous	Internal to the device	Channel sequencer	01b	01b

The device powers up in manual mode and can be configured into either of these modes by writing the configuration registers for the desired mode.

8.4.1 Device Power-Up and Reset

On power-up, the BOR bit is set indicating a power-cycle or reset event. The device can be reset by setting the RST bit or by recycling the power on the AVDD pin.

8.4.2 Manual Mode

Manual mode allows the external host processor to directly select the analog input channel. Figure 15 shows the steps for operating the device in manual mode.

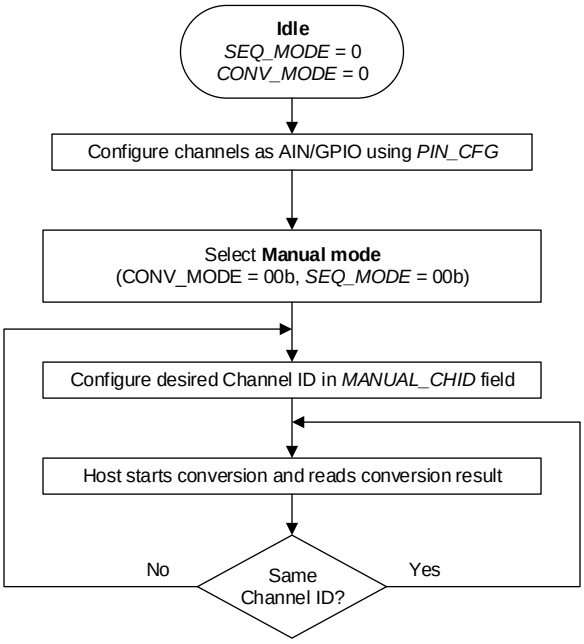


Figure 15. Device Operation in Manual Mode

In manual mode, the command to switch to a new channel (indicated by cycle N in Figure 16) is decoded by the device on the $\overline{CS}$ rising edge. The $\overline{CS}$ rising edge is also the start of the conversion signal, and therefore the device samples the previously selected MUX channel in cycle N+1. The newly selected analog input channel data are available in cycle N+2. For switching the analog input channel, a register write to the MANUAL_CHID field requires 24 clocks; see the *Register Write* section for more details. After a channel is selected, the number of clocks required for reading the output data depends on the device output data frame size; see the *Output Data Format* section for more details.

ADVANCE INFORMATION

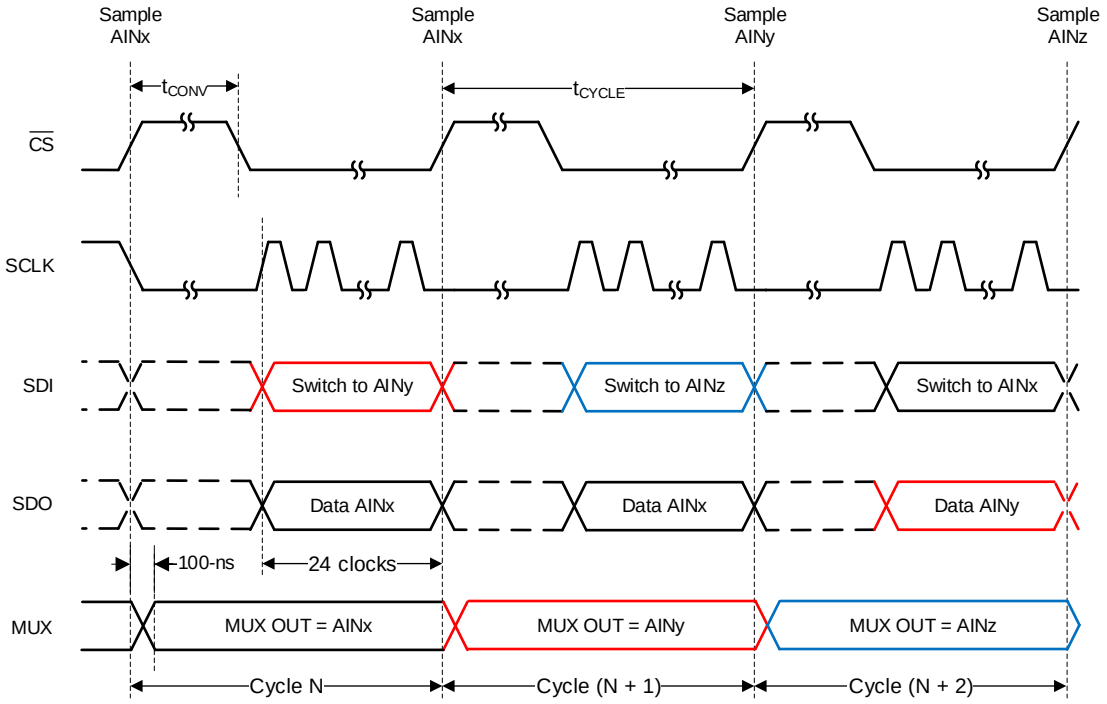


Figure 16. Starting Conversions and Reading Data in Manual Mode

8.4.3 On-the-Fly Mode

In the on-the-fly mode of operation, the analog input channel is selected, as shown in Figure 17, using the first five bits on SDI without waiting for the $\overline{CS}$ rising edge. Thus, the ADC samples the newly selected channel on the $\overline{CS}$ edge and there is no latency between the channel selection and the ADC output data.

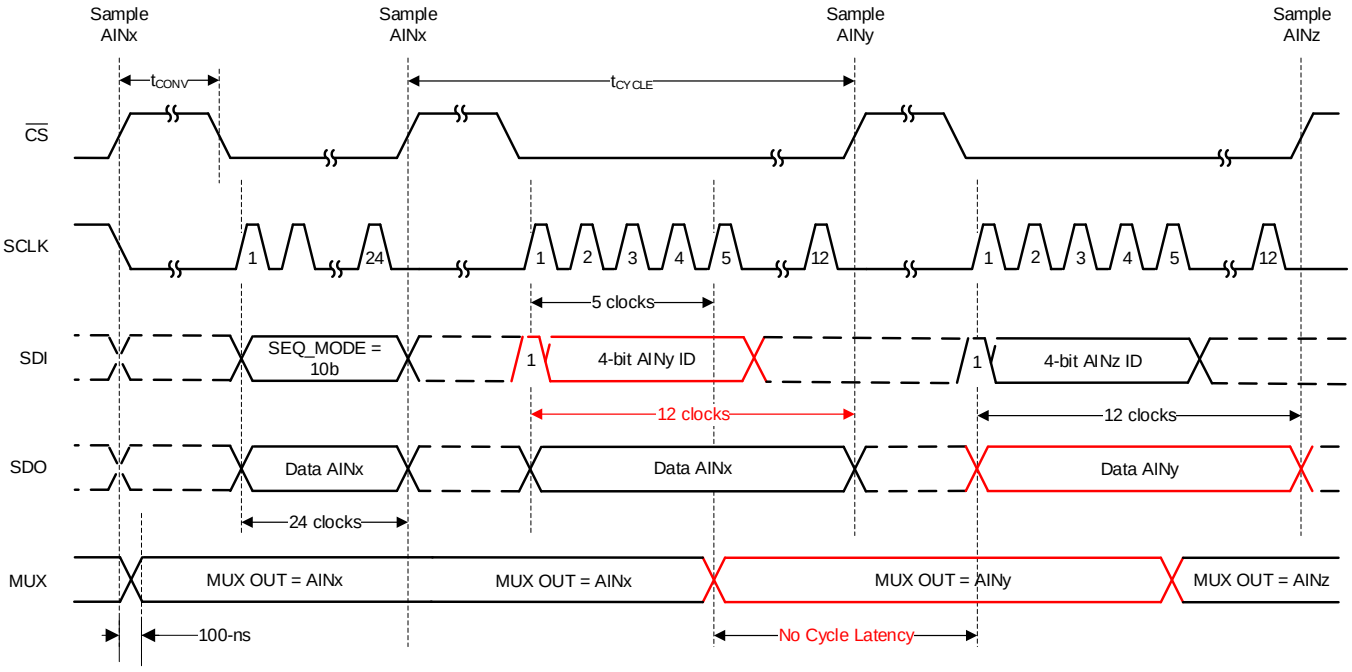


Figure 17. Starting Conversions and Reading Data in On-the-Fly Mode

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

The number of clocks required for reading the output data depends on the device output data frame size; see the *Output Data Format* section for more details.

8.4.4 Auto-Sequence Mode

In auto-sequence mode, the internal channel sequencer switches the multiplexer to the next analog input channel after every conversion. The desired analog input channels can be configured for sequencing in the AUTO_SEQ_CHSEL register. To enable the channel sequencer, set SEQ_START = 1b. After every conversion, the channel sequencer switches the multiplexer to the next analog input in ascending order. To stop the channel sequencer from selecting channels, set SEQ_START = 0b.

In the example shown in Figure 18, AIN2 and AIN6 are enabled for sequencing in AUTO_SEQ_CHSEL. The channel sequencer loops through AIN2 and AIN6 and repeats until SEQ_START is set to 0b. The number of clocks required for reading the output data depends on the device output data frame size; see the *Output Data Format* section for more details.

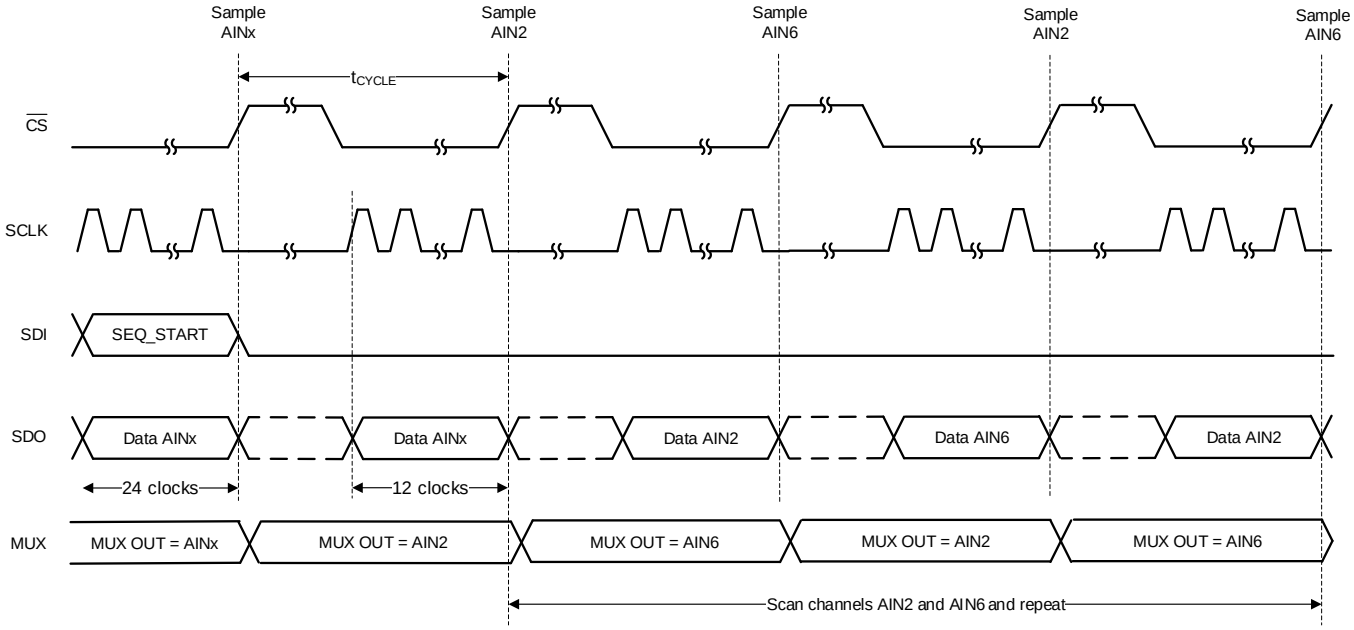


Figure 18. Starting Conversions and Reading Data in Auto-Sequence Mode

8.4.5 Autonomous Mode

In autonomous mode, the device can be programmed to monitor the voltage applied on the analog input pins of the device and generate an ALERT signal internal to the device when the programmable high or low threshold values are crossed. The internal ALERT signal can be mapped to any one digital output channel by configuring the channel ID in the ALERT_PIN[3:0] register field. In autonomous mode, the device generates the start of conversion using the internal oscillator. The first start of conversion must be provided by the host and the device generates the subsequent start of conversions.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 19 shows the steps for configuring the functional mode to autonomous mode. Abort the on-going sequence by setting the SEQ_START to 0b before changing the functional mode or configuration of device.

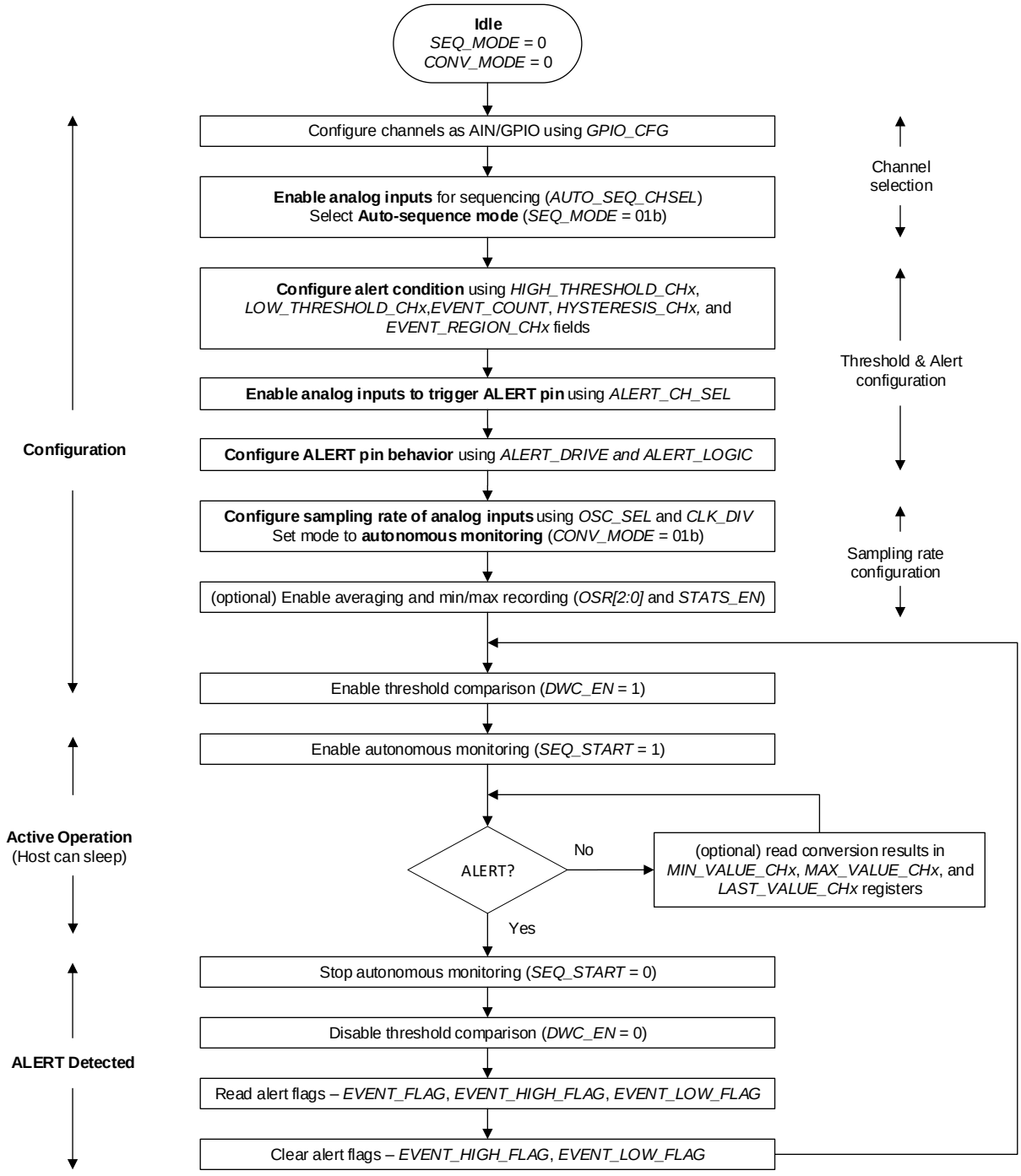


Figure 19. Configuring the Device in Autonomous Mode

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5 ADS7028 Registers

Table 9 lists the ADS7028 registers. All register offset addresses not listed in Table 9 should be considered as reserved locations and the register contents should not be modified.

Table 9. ADS7028 Registers

Address	Acronym	Register Name	Section
0x0	SYSTEM_STATUS		SYSTEM_STATUS Register (Address = 0x0) [reset = 0x81]
0x1	GENERAL_CFG		GENERAL_CFG Register (Address = 0x1) [reset = 0x0]
0x2	DATA_CFG		DATA_CFG Register (Address = 0x2) [reset = 0x0]
0x3	OSR_CFG		OSR_CFG Register (Address = 0x3) [reset = 0x0]
0x4	OPMODE_CFG		OPMODE_CFG Register (Address = 0x4) [reset = 0x0]
0x5	PIN_CFG		PIN_CFG Register (Address = 0x5) [reset = 0x0]
0x7	GPIO_CFG		GPIO_CFG Register (Address = 0x7) [reset = 0x0]
0x9	GPO_DRIVE_CFG		GPO_DRIVE_CFG Register (Address = 0x9) [reset = 0x0]
0xB	GPO_OUTPUT_VALUE		GPO_OUTPUT_VALUE Register (Address = 0xB) [reset = 0x0]
0xD	GPI_VALUE		GPI_VALUE Register (Address = 0xD) [reset = 0x0]
0xF	ZCD_BLANKING_CFG		ZCD_BLANKING_CFG Register (Address = 0xF) [reset = 0x0]
0x10	SEQUENCE_CFG		SEQUENCE_CFG Register (Address = 0x10) [reset = 0x0]
0x11	CHANNEL_SEL		CHANNEL_SEL Register (Address = 0x11) [reset = 0x0]
0x12	AUTO_SEQ_CH_SEL		AUTO_SEQ_CH_SEL Register (Address = 0x12) [reset = 0x0]
0x14	ALERT_CH_SEL		ALERT_CH_SEL Register (Address = 0x14) [reset = 0x0]
0x16	ALERT_MAP		ALERT_MAP Register (Address = 0x16) [reset = 0x0]
0x17	ALERT_PIN_CFG		ALERT_PIN_CFG Register (Address = 0x17) [reset = 0x0]
0x18	EVENT_FLAG		EVENT_FLAG Register (Address = 0x18) [reset = 0x0]
0x1A	EVENT_HIGH_FLAG		EVENT_HIGH_FLAG Register (Address = 0x1A) [reset = 0x0]
0x1C	EVENT_LOW_FLAG		EVENT_LOW_FLAG Register (Address = 0x1C) [reset = 0x0]
0x1E	EVENT_RGN		EVENT_RGN Register (Address = 0x1E) [reset = 0x0]
0x20	HYSTERESIS_CH0		HYSTERESIS_CH0 Register (Address = 0x20) [reset = 0xF0]
0x21	HIGH_TH_CH0		HIGH_TH_CH0 Register (Address = 0x21) [reset = 0xFF]
0x22	EVENT_COUNT_CH0		EVENT_COUNT_CH0 Register (Address = 0x22) [reset = 0x0]
0x23	LOW_TH_CH0		LOW_TH_CH0 Register (Address = 0x23) [reset = 0x0]
0x24	HYSTERESIS_CH1		HYSTERESIS_CH1 Register (Address = 0x24) [reset = 0xF0]
0x25	HIGH_TH_CH1		HIGH_TH_CH1 Register (Address = 0x25) [reset = 0xFF]
0x26	EVENT_COUNT_CH1		EVENT_COUNT_CH1 Register (Address = 0x26) [reset = 0x0]
0x27	LOW_TH_CH1		LOW_TH_CH1 Register (Address = 0x27) [reset = 0x0]
0x28	HYSTERESIS_CH2		HYSTERESIS_CH2 Register (Address = 0x28) [reset = 0xF0]
0x29	HIGH_TH_CH2		HIGH_TH_CH2 Register (Address = 0x29) [reset = 0xFF]
0x2A	EVENT_COUNT_CH2		EVENT_COUNT_CH2 Register (Address = 0x2A) [reset = 0x0]
0x2B	LOW_TH_CH2		LOW_TH_CH2 Register (Address = 0x2B) [reset = 0x0]
0x2C	HYSTERESIS_CH3		HYSTERESIS_CH3 Register (Address = 0x2C) [reset = 0xF0]
0x2D	HIGH_TH_CH3		HIGH_TH_CH3 Register (Address = 0x2D) [reset = 0xFF]
0x2E	EVENT_COUNT_CH3		EVENT_COUNT_CH3 Register (Address = 0x2E) [reset = 0x0]
0x2F	LOW_TH_CH3		LOW_TH_CH3 Register (Address = 0x2F) [reset = 0x0]
0x30	HYSTERESIS_CH4		HYSTERESIS_CH4 Register (Address = 0x30) [reset = 0xF0]
0x31	HIGH_TH_CH4		HIGH_TH_CH4 Register (Address = 0x31) [reset = 0xFF]
0x32	EVENT_COUNT_CH4		EVENT_COUNT_CH4 Register (Address = 0x32) [reset = 0x0]
0x33	LOW_TH_CH4		LOW_TH_CH4 Register (Address = 0x33) [reset = 0x0]
0x34	HYSTERESIS_CH5		HYSTERESIS_CH5 Register (Address = 0x34) [reset = 0xF0]
0x35	HIGH_TH_CH5		HIGH_TH_CH5 Register (Address = 0x35) [reset = 0xFF]

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 9. ADS7028 Registers (continued)

Address	Acronym	Register Name	Section
0x36	EVENT_COUNT_CH5		EVENT_COUNT_CH5 Register (Address = 0x36) [reset = 0x0]
0x37	LOW_TH_CH5		LOW_TH_CH5 Register (Address = 0x37) [reset = 0x0]
0x38	HYSTERESIS_CH6		HYSTERESIS_CH6 Register (Address = 0x38) [reset = 0xF0]
0x39	HIGH_TH_CH6		HIGH_TH_CH6 Register (Address = 0x39) [reset = 0xFF]
0x3A	EVENT_COUNT_CH6		EVENT_COUNT_CH6 Register (Address = 0x3A) [reset = 0x0]
0x3B	LOW_TH_CH6		LOW_TH_CH6 Register (Address = 0x3B) [reset = 0x0]
0x3C	HYSTERESIS_CH7		HYSTERESIS_CH7 Register (Address = 0x3C) [reset = 0xF0]
0x3D	HIGH_TH_CH7		HIGH_TH_CH7 Register (Address = 0x3D) [reset = 0xFF]
0x3E	EVENT_COUNT_CH7		EVENT_COUNT_CH7 Register (Address = 0x3E) [reset = 0x0]
0x3F	LOW_TH_CH7		LOW_TH_CH7 Register (Address = 0x3F) [reset = 0x0]
0x60	MAX_CH0_LSB		MAX_CH0_LSB Register (Address = 0x60) [reset = 0x0]
0x61	MAX_CH0_MSB		MAX_CH0_MSB Register (Address = 0x61) [reset = 0x0]
0x62	MAX_CH1_LSB		MAX_CH1_LSB Register (Address = 0x62) [reset = 0x0]
0x63	MAX_CH1_MSB		MAX_CH1_MSB Register (Address = 0x63) [reset = 0x0]
0x64	MAX_CH2_LSB		MAX_CH2_LSB Register (Address = 0x64) [reset = 0x0]
0x65	MAX_CH2_MSB		MAX_CH2_MSB Register (Address = 0x65) [reset = 0x0]
0x66	MAX_CH3_LSB		MAX_CH3_LSB Register (Address = 0x66) [reset = 0x0]
0x67	MAX_CH3_MSB		MAX_CH3_MSB Register (Address = 0x67) [reset = 0x0]
0x68	MAX_CH4_LSB		MAX_CH4_LSB Register (Address = 0x68) [reset = 0x0]
0x69	MAX_CH4_MSB		MAX_CH4_MSB Register (Address = 0x69) [reset = 0x0]
0x6A	MAX_CH5_LSB		MAX_CH5_LSB Register (Address = 0x6A) [reset = 0x0]
0x6B	MAX_CH5_MSB		MAX_CH5_MSB Register (Address = 0x6B) [reset = 0x0]
0x6C	MAX_CH6_LSB		MAX_CH6_LSB Register (Address = 0x6C) [reset = 0x0]
0x6D	MAX_CH6_MSB		MAX_CH6_MSB Register (Address = 0x6D) [reset = 0x0]
0x6E	MAX_CH7_LSB		MAX_CH7_LSB Register (Address = 0x6E) [reset = 0x0]
0x6F	MAX_CH7_MSB		MAX_CH7_MSB Register (Address = 0x6F) [reset = 0x0]
0x80	MIN_CH0_LSB		MIN_CH0_LSB Register (Address = 0x80) [reset = 0xFF]
0x81	MIN_CH0_MSB		MIN_CH0_MSB Register (Address = 0x81) [reset = 0xFF]
0x82	MIN_CH1_LSB		MIN_CH1_LSB Register (Address = 0x82) [reset = 0xFF]
0x83	MIN_CH1_MSB		MIN_CH1_MSB Register (Address = 0x83) [reset = 0xFF]
0x84	MIN_CH2_LSB		MIN_CH2_LSB Register (Address = 0x84) [reset = 0xFF]
0x85	MIN_CH2_MSB		MIN_CH2_MSB Register (Address = 0x85) [reset = 0xFF]
0x86	MIN_CH3_LSB		MIN_CH3_LSB Register (Address = 0x86) [reset = 0xFF]
0x87	MIN_CH3_MSB		MIN_CH3_MSB Register (Address = 0x87) [reset = 0xFF]
0x88	MIN_CH4_LSB		MIN_CH4_LSB Register (Address = 0x88) [reset = 0xFF]
0x89	MIN_CH4_MSB		MIN_CH4_MSB Register (Address = 0x89) [reset = 0xFF]
0x8A	MIN_CH5_LSB		MIN_CH5_LSB Register (Address = 0x8A) [reset = 0xFF]
0x8B	MIN_CH5_MSB		MIN_CH5_MSB Register (Address = 0x8B) [reset = 0xFF]
0x8C	MIN_CH6_LSB		MIN_CH6_LSB Register (Address = 0x8C) [reset = 0xFF]
0x8D	MIN_CH6_MSB		MIN_CH6_MSB Register (Address = 0x8D) [reset = 0xFF]
0x8E	MIN_CH7_LSB		MIN_CH7_LSB Register (Address = 0x8E) [reset = 0xFF]
0x8F	MIN_CH7_MSB		MIN_CH7_MSB Register (Address = 0x8F) [reset = 0xFF]
0xA0	RECENT_CH0_LSB		RECENT_CH0_LSB Register (Address = 0xA0) [reset = 0x0]
0xA1	RECENT_CH0_MSB		RECENT_CH0_MSB Register (Address = 0xA1) [reset = 0x0]
0xA2	RECENT_CH1_LSB		RECENT_CH1_LSB Register (Address = 0xA2) [reset = 0x0]
0xA3	RECENT_CH1_MSB		RECENT_CH1_MSB Register (Address = 0xA3) [reset = 0x0]
0xA4	RECENT_CH2_LSB		RECENT_CH2_LSB Register (Address = 0xA4) [reset = 0x0]

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 9. ADS7028 Registers (continued)

Address	Acronym	Register Name	Section
0xA5	RECENT_CH2_MSB		RECENT_CH2_MSB Register (Address = 0xA5) [reset = 0x0]
0xA6	RECENT_CH3_LSB		RECENT_CH3_LSB Register (Address = 0xA6) [reset = 0x0]
0xA7	RECENT_CH3_MSB		RECENT_CH3_MSB Register (Address = 0xA7) [reset = 0x0]
0xA8	RECENT_CH4_LSB		RECENT_CH4_LSB Register (Address = 0xA8) [reset = 0x0]
0xA9	RECENT_CH4_MSB		RECENT_CH4_MSB Register (Address = 0xA9) [reset = 0x0]
0xAA	RECENT_CH5_LSB		RECENT_CH5_LSB Register (Address = 0xAA) [reset = 0x0]
0xAB	RECENT_CH5_MSB		RECENT_CH5_MSB Register (Address = 0xAB) [reset = 0x0]
0xAC	RECENT_CH6_LSB		RECENT_CH6_LSB Register (Address = 0xAC) [reset = 0x0]
0xAD	RECENT_CH6_MSB		RECENT_CH6_MSB Register (Address = 0xAD) [reset = 0x0]
0xAE	RECENT_CH7_LSB		RECENT_CH7_LSB Register (Address = 0xAE) [reset = 0x0]
0xAF	RECENT_CH7_MSB		RECENT_CH7_MSB Register (Address = 0xAF) [reset = 0x0]
0xC0	RMS_CFG		RMS_CFG Register (Address = 0xC0) [reset = 0x0]
0xC1	RMS_LSB		RMS_LSB Register (Address = 0xC1) [reset = 0x0]
0xC2	RMS_MSB		RMS_MSB Register (Address = 0xC2) [reset = 0x0]
0xC3	GPO0_TRIG_EVENT_SEL		GPO0_TRIG_EVENT_SEL Register (Address = 0xC3) [reset = 0x2]
0xC5	GPO1_TRIG_EVENT_SEL		GPO1_TRIG_EVENT_SEL Register (Address = 0xC5) [reset = 0x1]
0xC7	GPO2_TRIG_EVENT_SEL		GPO2_TRIG_EVENT_SEL Register (Address = 0xC7) [reset = 0x8]
0xC9	GPO3_TRIG_EVENT_SEL		GPO3_TRIG_EVENT_SEL Register (Address = 0xC9) [reset = 0x4]
0xCB	GPO4_TRIG_EVENT_SEL		GPO4_TRIG_EVENT_SEL Register (Address = 0xCB) [reset = 0x20]
0xCD	GPO5_TRIG_EVENT_SEL		GPO5_TRIG_EVENT_SEL Register (Address = 0xCD) [reset = 0x10]
0xCF	GPO6_TRIG_EVENT_SEL		GPO6_TRIG_EVENT_SEL Register (Address = 0xCF) [reset = 0x80]
0xD1	GPO7_TRIG_EVENT_SEL		GPO7_TRIG_EVENT_SEL Register (Address = 0xD1) [reset = 0x40]
0xE3	GPO_VALUE_ZCD_CFG_CH0_CH3		GPO_VALUE_ZCD_CFG_CH0_CH3 Register (Address = 0xE3) [reset = 0x0]
0xE4	GPO_VALUE_ZCD_CFG_CH4_CH7		GPO_VALUE_ZCD_CFG_CH4_CH7 Register (Address = 0xE4) [reset = 0x0]
0xE7	GPO_ZCD_UPDATE_EN		GPO_ZCD_UPDATE_EN Register (Address = 0xE7) [reset = 0x0]
0xE9	GPO_TRIGGER_CFG		GPO_TRIGGER_CFG Register (Address = 0xE9) [reset = 0x0]
0xEB	GPO_VALUE_TRIG		GPO_VALUE_TRIG Register (Address = 0xEB) [reset = 0x0]

Complex bit access types are encoded to fit into small table cells. Table 10 shows the codes that are used for access types in this section.

Table 10. ADS7028 Access Type Codes

Access Type	Code	Description
Read Type		
R	R	Read
Write Type		
W	W	Write
Reset or Default Value		
-n		Value after reset or the default value
Register Array Variables		

ADVANCE INFORMATION

Table 10. ADS7028 Access Type Codes (continued)

Access Type	Code	Description
i,j,k,l,m,n		When these variables are used in a register name, an offset, or an address, they refer to the value of a register array where the register is part of a group of repeating registers. The register groups form a hierarchical structure and the array is represented with a formula.
y		When this variable is used in a register name, an offset, or an address it refers to the value of a register array.

8.5.1 SYSTEM_STATUS Register (Address = 0x0) [reset = 0x81]

SYSTEM_STATUS is shown in Figure 20 and described in Table 11.

Return to the Summary Table.

Figure 20. SYSTEM_STATUS Register

7	6	5	4	3	2	1	0
RSVD	SEQ_STATUS	RESERVED	RMS_DONE	OSR_DONE	CRC_ERR_FUSE	CRC_ERR_IN	BOR
R-1b	R-0b	R-0b	R/W-0b	R/W-0b	R-0b	R/W-0b	R/W-1b

Table 11. SYSTEM_STATUS Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RSVD	R	1b	Reads return 1b.
6	SEQ_STATUS	R	0b	Status of the channel sequencer. 0b = Sequence stopped. 1b = Sequence in progress.
5	RESERVED	R	0b	Reserved. Reads return 0.
4	RMS_DONE	R/W	0b	RMS computation status. Clear this bit by writing 1b to this bit. 0b = RMS operation in progress or not started; RMS result not ready. 1b = RMS computation complete; RMS result ready.
3	OSR_DONE	R/W	0b	Averaging status. Clear this bit by writing 1b to this bit. 0b = Averaging in progress or not started; average result is not ready. 1b = Averaging complete; average result is ready.
2	CRC_ERR_FUSE	R	0b	Device power-up configuration CRC check status. To re-evaluate this bit, software reset the device or power cycle AVDD. 0b = No problems detected in power-up configuration. 1b = Device configuration not loaded correctly.
1	CRC_ERR_IN	R/W	0b	Status of CRC check on incoming data. Write 1b to clear this error flag. 0b = No CRC error. 1b = CRC error detected. All register writes, except to addresses 0x00 and 0x01, are blocked.
0	BOR	R/W	1b	Brown out reset indicator. This bit is set if brown out condition occurs or device is power cycled. Write 1b to this bit to clear the flag. 0b = No brown out from the last time this bit was cleared. 1b = Brown out condition detected or device power cycled.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.2 GENERAL_CFG Register (Address = 0x1) [reset = 0x0]

GENERAL_CFG is shown in Figure 21 and described in Table 12.

Return to the Summary Table.

Figure 21. GENERAL_CFG Register

7	6	5	4	3	2	1	0
RMS_EN	CRC_EN	STATS_EN	DWC_EN	RESERVED	CH_RST	CAL	RST
R/W-0b	R/W-0b	R/W-0b	R/W-0b	R-0b	R/W-0b	R/W-0b	W-0b

Table 12. GENERAL_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RMS_EN	R/W	0b	Enable or disable the RMS module. 0b = RMS module disabled. 1b = RMS module enabled; writing 1b to this bit clears RMS_RESULT registers and initiates new RMS computation.
6	CRC_EN	R/W	0b	Enable or disable CRC on device interface. 0b = CRC module disabled. 1b = CRC appended to data output. CRC check is enabled on incoming data.
5	STATS_EN	R/W	0b	Enable or disable the statistics module to update minimu, maximum, and latest output code registers. 0b = Statistics registers are not updated. 1b = Clear statistics registers and conitnue updating with new conversion results.
4	DWC_EN	R/W	0b	Enable or disable the digital window comparator. 0b = Reset or disable digital window comparator. 1b = Enable digital window comparator.
3	RESERVED	R	0b	Reserved. Reads return 0.
2	CH_RST	R/W	0b	Force all channels to be analog inputs. 0b = Normal operation. 1b = All channels are set as analog inputs irrespective of configuration in other registers.
1	CAL	R/W	0b	Calibrate ADC offset. 0b = Normal operation. 1b = ADC offset is calibrated. After calibration is complete, this bit is set to 0b.
0	RST	W	0b	Software reset all registers to default values. 0b = Normal operation. 1b = Device is reset. After reset is complete, this bit is set to 0b and BOR bit is set to 1b.

ADVANCE INFORMATION

8.5.3 DATA_CFG Register (Address = 0x2) [reset = 0x0]

DATA_CFG is shown in Figure 22 and described in Table 13.

Return to the Summary Table.

Figure 22. DATA_CFG Register

7	6	5	4	3	2	1	0
FIX_PAT	RESERVED	APPEND_STATUS[1:0]		RESERVED		CPOL_CPHA[1:0]	
R/W-0b	R-0b	R/W-0b		R-0b		R/W-0b	

Copyright © 2019, Texas Instruments Incorporated

Table 13. DATA_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	FIX_PAT	R/W	0b	Device outputs fixed data bits, which can be helpful for debugging communication with the device. 0b = Normal operation. 1b = Device outputs fixed code 0xA5A repetitively when reading ADC data.
6	RESERVED	R	0b	Reserved. Reads return 0.
5-4	APPEND_STATUS[1:0]	R/W	0b	Append 4-bit channel ID or status flags to output data. 0b = Channel ID and status flags are not appended to ADC data. 1b = 4-bit channel ID is appended to ADC data. 10b = 4-bit status flags are appended to ADC data. 11b = Reserved.
3-2	RESERVED	R	0b	Reserved. Reads return 0.
1-0	CPOL_CPHA[1:0]	R/W	0b	This field sets the polarity and phase of SPI communication. 0b = CPOL = 0, CPHA = 0. 1b = CPOL = 0, CPHA = 1. 10b = CPOL = 1, CPHA = 0. 11b = CPOL = 1, CPHA = 1.

8.5.4 OSR_CFG Register (Address = 0x3) [reset = 0x0]

OSR_CFG is shown in Figure 23 and described in Table 14.

Return to the Summary Table.

Figure 23. OSR_CFG Register

7	6	5	4	3	2	1	0
RESERVED					OSR[2:0]		
R-0b					R/W-0b		

Table 14. OSR_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	RESERVED	R	0b	Reserved. Reads return 0.
2-0	OSR[2:0]	R/W	0b	Selects the number of ADC output samples to average. 0b = No averaging 1b = 2 samples 10b = 4 samples 11b = 8 samples 100b = 16 samples 101b = 32 samples 110b = 64 samples 111b = 128 samples

8.5.5 OPMODE_CFG Register (Address = 0x4) [reset = 0x0]

OPMODE_CFG is shown in Figure 24 and described in Table 15.

Return to the Summary Table.

Figure 24. OPMODE_CFG Register

7	6	5	4	3	2	1	0
CONV_ON_ER R	CONV_MODE[1:0]		OSC_SEL	CLK_DIV[3:0]			
R/W-0b	R/W-0b		R/W-0b	R/W-0b			

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 15. OPMODE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	CONV_ON_ERR	R/W	0b	Control continuation of autonomous modes if CRC error is detected on communication interface. 0b = If CRC error is detected, device continues channel sequencing and pin configuration is retained. See the CRC_ERR_IN bit for more details. 1b = If CRC error is detected, device changes all channels to analog inputs and channel sequencing is paused until CRC_ERR_IN bit is set to 0b. After clearing CRC_ERR_IN flag, device resumes channel sequencing and pin confguration is restored.
6-5	CONV_MODE[1:0]	R/W	0b	These bits set the mode of conversion of the ADC. 0b = Manual mode; conversions are initiated by the host. 1b = Autonomous mode; conversions are initiated by the internal state machine.
4	OSC_SEL	R/W	0b	Selects the oscillator for internal timing generation. 0b = High-speed oscillator. 1b = Low-power oscillator.
3-0	CLK_DIV[3:0]	R/W	0b	Sampling speed control in autonomous monitoring mode (CONV_MODE = 01b). See the section on oscillator and timing control for details.

8.5.6 PIN_CFG Register (Address = 0x5) [reset = 0x0]

PIN_CFG is shown in Figure 25 and described in Table 16.

Return to the Summary Table.

Figure 25. PIN_CFG Register

7	6	5	4	3	2	1	0
PIN_CFG[7:0]							
R/W-0b							

Table 16. PIN_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	PIN_CFG[7:0]	R/W	0b	Configure device channels AIN / GPIO [7:0] as analog inputs or GPIOs. 0b = Channel is configured as analog input. 1b = Channel is configured as GPIO.

8.5.7 GPIO_CFG Register (Address = 0x7) [reset = 0x0]

GPIO_CFG is shown in Figure 26 and described in Table 17.

Return to the Summary Table.

Figure 26. GPIO_CFG Register

7	6	5	4	3	2	1	0
GPIO_CFG[7:0]							
R/W-0b							

Table 17. GPIO_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPIO_CFG[7:0]	R/W	0b	Configure GPIO[7:0] as either digital inputs or digital outputs. 0b = GPIO is configured as digital input. 1b = GPIO is configured as digital output.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.8 GPO_DRIVE_CFG Register (Address = 0x9) [reset = 0x0]

GPO_DRIVE_CFG is shown in Figure 27 and described in Table 18.

Return to the Summary Table.

Figure 27. GPO_DRIVE_CFG Register

7	6	5	4	3	2	1	0
GPO_DRIVE_CFG[7:0]							
R/W-0b							

Table 18. GPO_DRIVE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_DRIVE_CFG[7:0]	R/W	0b	Configure digital outputs GPO[7:0] as open-drain or push-pull outputs. 0b = Digital output is open-drain; connect external pullup resistor. 1b = Push-pull driver is used for digital output.

8.5.9 GPO_OUTPUT_VALUE Register (Address = 0xB) [reset = 0x0]

GPO_OUTPUT_VALUE is shown in Figure 28 and described in Table 19.

Return to the Summary Table.

Figure 28. GPO_OUTPUT_VALUE Register

7	6	5	4	3	2	1	0
GPO_OUTPUT_VALUE[7:0]							
R/W-0b							

Table 19. GPO_OUTPUT_VALUE Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_OUTPUT_VALUE[7:0]	R/W	0b	Logic level to be set on digital outputs GPO[7:0]. 0b = Digital output set to logic 0. 1b = Digital output set to logic 1.

8.5.10 GPI_VALUE Register (Address = 0xD) [reset = 0x0]

GPI_VALUE is shown in Figure 29 and described in Table 20.

Return to the Summary Table.

Figure 29. GPI_VALUE Register

7	6	5	4	3	2	1	0
GPI_VALUE[7:0]							
R-0b							

Table 20. GPI_VALUE Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPI_VALUE[7:0]	R	0b	Readback the logic level on GPIO[7:0]. 0b = GPIO is at logic 0. 1b = GPIO is at logic 1.

8.5.11 ZCD_BLANKING_CFG Register (Address = 0xF) [reset = 0x0]

ZCD_BLANKING_CFG is shown in Figure 30 and described in Table 21.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 30. ZCD_BLANKING_CFG Register

7	6	5	4	3	2	1	0
MULT_EN	ZCD_BLANKING[6:0]						
R/W-0b	R/W-0b						

Table 21. ZCD_BLANKING_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	MULT_EN	R/W	0b	Multiplier enable bit for the ZCD_BLANKING field. 0b = Blanking count = ZCD_BLANKING 1b = Blanking count = ZCD_BLANKING x 8
6-0	ZCD_BLANKING[6:0]	R/W	0b	This field defines the number of analog conversions, of the ZCD channel, which must be ignored before generating next ZCD event. The counting starts from ZCD event detection.

8.5.12 SEQUENCE_CFG Register (Address = 0x10) [reset = 0x0]

SEQUENCE_CFG is shown in Figure 31 and described in Table 22.

Return to the Summary Table.

Figure 31. SEQUENCE_CFG Register

7	6	5	4	3	2	1	0
RESERVED			SEQ_START	RESERVED		SEQ_MODE[1:0]	
R-0b			R/W-0b	R-0b		R/W-0b	

Table 22. SEQUENCE_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R	0b	Reserved. Reads return 0.
4	SEQ_START	R/W	0b	Control for start of channel sequence when using channel sequencer (SEQ_MODE = 01b). 0b = Stop channel sequencing. 1b = Start channel sequencing in ascending order for channels enabled in AUTO_SEQ_CHSEL register.
3-2	RESERVED	R	0b	Reserved. Reads return 0.
1-0	SEQ_MODE[1:0]	R/W	0b	Selects the mode of scanning of analog input channels. 0b = Manual sequence mode; channel selected by MANUAL_CHID field. 1b = Auto sequence mode; channel selected by internal channel sequencer. 10b = On-the-fly sequence mode. 11b = Reserved.

8.5.13 CHANNEL_SEL Register (Address = 0x11) [reset = 0x0]

CHANNEL_SEL is shown in Figure 32 and described in Table 23.

Return to the Summary Table.

Figure 32. CHANNEL_SEL Register

7	6	5	4	3	2	1	0
ZCD_CHID[3:0]				MANUAL_CHID[3:0]			
R/W-0b				R/W-0b			

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 23. CHANNEL_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	ZCD_CHID[3:0]	R/W	0b	Input channel to treat as ZCD input. If the selected channel is configured as an analog input, internally generated ZCD signal is used (setup thresholds accordingly). If the selected channel is a digital input, the digital signal on this channel is directly used as ZCD signal.
3-0	MANUAL_CHID[3:0]	R/W	0b	In manual mode (SEQ_MODE = 00b), this field contains the 4-bit channel ID of the analog input channel for next ADC conversion. For valid ADC data, the selected channel must not be configured as GPIO in PIN_CFG register. 0b = AIN0 1b = AIN1 10b = AIN2 11b = AIN3 100b = AIN4 101b = AIN5 110b = AIN6 111b = AIN7 1000b = Reserved.

8.5.14 AUTO_SEQ_CH_SEL Register (Address = 0x12) [reset = 0x0]

AUTO_SEQ_CH_SEL is shown in Figure 33 and described in Table 24.

Return to the Summary Table.

Figure 33. AUTO_SEQ_CH_SEL Register

7	6	5	4	3	2	1	0
AUTO_SEQ_CH_SEL[7:0]							
R/W-0b							

Table 24. AUTO_SEQ_CH_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	AUTO_SEQ_CH_SEL[7:0]	R/W	0b	Select analog input channels AIN[7:0] in for auto sequencing mode. 0b = Analog input channel is not enabled in scanning sequence. 1b = Analog input channel is enabled in scanning sequence.

8.5.15 ALERT_CH_SEL Register (Address = 0x14) [reset = 0x0]

ALERT_CH_SEL is shown in Figure 34 and described in Table 25.

Return to the Summary Table.

Figure 34. ALERT_CH_SEL Register

7	6	5	4	3	2	1	0
ALERT_CH_SEL[7:0]							
R/W-0b							

Table 25. ALERT_CH_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ALERT_CH_SEL[7:0]	R/W	0b	Select channels for which the alert flags can assert the ALERT signal. 0b = Alert flags for this channel do not assert the ALERT signal. 1b = Alert flags for this channel assert the ALERT signal.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.16 ALERT_MAP Register (Address = 0x16) [reset = 0x0]

ALERT_MAP is shown in Figure 35 and described in Table 26.

Return to the Summary Table.

Figure 35. ALERT_MAP Register

7	6	5	4	3	2	1	0
RESERVED						ALERT_RMS	ALERT_CRCIN
R-0b						R/W-0b	R/W-0b

Table 26. ALERT_MAP Register Field Descriptions

Bit	Field	Type	Reset	Description
7-2	RESERVED	R	0b	Reserved. Reads return 0.
1	ALERT_RMS	R/W	0b	Enable or disable asserting ALERT signal based on RMS computation status (RMS_DONE = 1b). 0b = ALERT signal is not asserted when RMS_DONE =1b. 1b = ALERT signal is asserted when RMS_DONE = 1b. Clear RMS_DONE flag to deassert the ALERT signal.
0	ALERT_CRCIN	R/W	0b	Enable or disable the alert notification for CRC error on input data (CRCERR_IN = 1b). 0b = ALERT signal is not asserted when CRCERR_IN = 1b. 1b = ALERT signal is asserted when CRCERR_IN = 1b. Clear CRCERR_IN for deasserting the ALERT signal.

8.5.17 ALERT_PIN_CFG Register (Address = 0x17) [reset = 0x0]

ALERT_PIN_CFG is shown in Figure 36 and described in Table 27.

Return to the Summary Table.

Figure 36. ALERT_PIN_CFG Register

7	6	5	4	3	2	1	0
ALERT_PIN[3:0]				RESERVED		ALERT_LOGIC[1:0]	
R/W-0b				R-0b		R/W-0b	

Table 27. ALERT_PIN_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	ALERT_PIN[3:0]	R/W	0b	Internal ALERT output of the digital window comparator will be output on this channel. This channel must be configured as digital output.
3-2	RESERVED	R	0b	Reserved. Reads return 0.
1-0	ALERT_LOGIC[1:0]	R/W	0b	Configure how ALERT signal is asserted. 0b = Active low. 1b = Active high. 10b = Pulsed low (one logic low pulse once per alert flag). 11b = Pulsed high (one logic high pulse once per alert flag).

8.5.18 EVENT_FLAG Register (Address = 0x18) [reset = 0x0]

EVENT_FLAG is shown in Figure 37 and described in Table 28.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 37. EVENT_FLAG Register

7	6	5	4	3	2	1	0
EVENT_FLAG[7:0]							
R-0b							

Table 28. EVENT_FLAG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	EVENT_FLAG[7:0]	R	0b	Alert flags indicating digital window comparator status for AIN/GPIO[7:0]. Write 0b to individual bits of EVENT_HIGH and EVENT_LOW flag registers to clear alert flag. 0b = Event condition not detected. 1b = Event condition detected.

8.5.19 EVENT_HIGH_FLAG Register (Address = 0x1A) [reset = 0x0]

EVENT_HIGH_FLAG is shown in Figure 38 and described in Table 29.

Return to the Summary Table.

Figure 38. EVENT_HIGH_FLAG Register

7	6	5	4	3	2	1	0
EVENT_HIGH_FLAG[7:0]							
R/W-0b							

Table 29. EVENT_HIGH_FLAG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	EVENT_HIGH_FLAG[7:0]	R/W	0b	Alert flag corresponding to high threshold of analog input or rising edge of digital input on CH[7:0]. Write 1b to clear this flag. 0b = No alert condition detected. 1b = Either high threshold was exceeded (analog input) or rising edge was detected (digital input).

8.5.20 EVENT_LOW_FLAG Register (Address = 0x1C) [reset = 0x0]

EVENT_LOW_FLAG is shown in Figure 39 and described in Table 30.

Return to the Summary Table.

Figure 39. EVENT_LOW_FLAG Register

7	6	5	4	3	2	1	0
EVENT_LOW_FLAG[7:0]							
R/W-0b							

Table 30. EVENT_LOW_FLAG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	EVENT_LOW_FLAG[7:0]	R/W	0b	Alert flag corresponding to low threshold of analog input or falling edge of digital input on CH[7:0]. Write 1b to clear this flag. 0b = No Event condition detected. 1b = Either low threshold was exceeded (analog input) or falling edge was detected (digital input).

8.5.21 EVENT_RGN Register (Address = 0x1E) [reset = 0x0]

EVENT_RGN is shown in Figure 40 and described in Table 31.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 40. EVENT_RGN Register

7	6	5	4	3	2	1	0
EVENT_RGN[7:0]							
R/W-0b							

Table 31. EVENT_RGN Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	EVENT_RGN[7:0]	R/W	0b	Choice of region used in monitoring analog/digital inputs CH[7:0]. 0b = Alert flag is set if: (conversion result andlt low threshold) or (conversion result andgt high threshold). For digital inputs, rising edge sets the alert flag. 1b = Alert flag is set if: (low threshold andgt conversion result andlt high threshold). For digital inputs, falling edge sets the alert flag.

8.5.22 HYSTERESIS_CH0 Register (Address = 0x20) [reset = 0xF0]

HYSTERESIS_CH0 is shown in Figure 41 and described in Table 32.

Return to the Summary Table.

Figure 41. HYSTERESIS_CH0 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH0_LSB[3:0]				HYSTERESIS_CH0[3:0]			
R/W-1111b				R/W-0b			

Table 32. HYSTERESIS_CH0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH0_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH0[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.23 HIGH_TH_CH0 Register (Address = 0x21) [reset = 0xFF]

HIGH_TH_CH0 is shown in Figure 42 and described in Table 33.

Return to the Summary Table.

Figure 42. HIGH_TH_CH0 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH0_MSB[7:0]							
R/W-11111111b							

Table 33. HIGH_TH_CH0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH0_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.24 EVENT_COUNT_CH0 Register (Address = 0x22) [reset = 0x0]

EVENT_COUNT_CH0 is shown in Figure 43 and described in Table 34.

Return to the Summary Table.

ADVANCE INFORMATION

Figure 43. EVENT_COUNT_CH0 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH0_LSB[3:0]				EVENT_COUNT_CH0[3:0]			
R/W-0b				R/W-0b			

Table 34. EVENT_COUNT_CH0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH0_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH0[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.25 LOW_TH_CH0 Register (Address = 0x23) [reset = 0x0]

LOW_TH_CH0 is shown in Figure 44 and described in Table 35.

Return to the Summary Table.

Figure 44. LOW_TH_CH0 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH0_MSB[7:0]							
R/W-0b							

Table 35. LOW_TH_CH0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH0_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.26 HYSTERESIS_CH1 Register (Address = 0x24) [reset = 0xF0]

HYSTERESIS_CH1 is shown in Figure 45 and described in Table 36.

Return to the Summary Table.

Figure 45. HYSTERESIS_CH1 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH1_LSB[3:0]				HYSTERESIS_CH1[3:0]			
R/W-1111b				R/W-0b			

Table 36. HYSTERESIS_CH1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH1_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH1[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.27 HIGH_TH_CH1 Register (Address = 0x25) [reset = 0xFF]

HIGH_TH_CH1 is shown in Figure 46 and described in Table 37.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 46. HIGH_TH_CH1 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH1_MSB[7:0]							
R/W-11111111b							

Table 37. HIGH_TH_CH1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH1_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.28 EVENT_COUNT_CH1 Register (Address = 0x26) [reset = 0x0]

EVENT_COUNT_CH1 is shown in Figure 47 and described in Table 38.

Return to the Summary Table.

Figure 47. EVENT_COUNT_CH1 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH1_LSB[3:0]				EVENT_COUNT_CH1[3:0]			
R/W-0b				R/W-0b			

Table 38. EVENT_COUNT_CH1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH1_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH1[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.29 LOW_TH_CH1 Register (Address = 0x27) [reset = 0x0]

LOW_TH_CH1 is shown in Figure 48 and described in Table 39.

Return to the Summary Table.

Figure 48. LOW_TH_CH1 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH1_MSB[7:0]							
R/W-0b							

Table 39. LOW_TH_CH1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH1_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.30 HYSTERESIS_CH2 Register (Address = 0x28) [reset = 0xF0]

HYSTERESIS_CH2 is shown in Figure 49 and described in Table 40.

Return to the Summary Table.

Figure 49. HYSTERESIS_CH2 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH2_LSB[3:0]				HYSTERESIS_CH2[3:0]			
R/W-1111b				R/W-0b			

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 40. HYSTERESIS_CH2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH2_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH2[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.31 HIGH_TH_CH2 Register (Address = 0x29) [reset = 0xFF]

HIGH_TH_CH2 is shown in Figure 50 and described in Table 41.

Return to the Summary Table.

Figure 50. HIGH_TH_CH2 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH2_MSB[7:0]							
R/W-11111111b							

Table 41. HIGH_TH_CH2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH2_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.32 EVENT_COUNT_CH2 Register (Address = 0x2A) [reset = 0x0]

EVENT_COUNT_CH2 is shown in Figure 51 and described in Table 42.

Return to the Summary Table.

Figure 51. EVENT_COUNT_CH2 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH2_LSB[3:0]				EVENT_COUNT_CH2[3:0]			
R/W-0b				R/W-0b			

Table 42. EVENT_COUNT_CH2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH2_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH2[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.33 LOW_TH_CH2 Register (Address = 0x2B) [reset = 0x0]

LOW_TH_CH2 is shown in Figure 52 and described in Table 43.

Return to the Summary Table.

Figure 52. LOW_TH_CH2 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH2_MSB[7:0]							
R/W-0b							

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 43. LOW_TH_CH2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH2_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.34 HYSTERESIS_CH3 Register (Address = 0x2C) [reset = 0xF0]

HYSTERESIS_CH3 is shown in Figure 53 and described in Table 44.

Return to the Summary Table.

Figure 53. HYSTERESIS_CH3 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH3_LSB[3:0]				HYSTERESIS_CH3[3:0]			
R/W-1111b				R/W-0b			

Table 44. HYSTERESIS_CH3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH3_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH3[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.35 HIGH_TH_CH3 Register (Address = 0x2D) [reset = 0xFF]

HIGH_TH_CH3 is shown in Figure 54 and described in Table 45.

Return to the Summary Table.

Figure 54. HIGH_TH_CH3 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH3_MSB[7:0]							
R/W-11111111b							

Table 45. HIGH_TH_CH3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH3_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.36 EVENT_COUNT_CH3 Register (Address = 0x2E) [reset = 0x0]

EVENT_COUNT_CH3 is shown in Figure 55 and described in Table 46.

Return to the Summary Table.

Figure 55. EVENT_COUNT_CH3 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH3_LSB[3:0]				EVENT_COUNT_CH3[3:0]			
R/W-0b				R/W-0b			

Table 46. EVENT_COUNT_CH3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH3_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 46. EVENT_COUNT_CH3 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-0	EVENT_COUNT_CH3[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.37 LOW_TH_CH3 Register (Address = 0x2F) [reset = 0x0]

LOW_TH_CH3 is shown in Figure 56 and described in Table 47.

Return to the Summary Table.

Figure 56. LOW_TH_CH3 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH3_MSB[7:0]							
R/W-0b							

Table 47. LOW_TH_CH3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH3_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.38 HYSTERESIS_CH4 Register (Address = 0x30) [reset = 0xF0]

HYSTERESIS_CH4 is shown in Figure 57 and described in Table 48.

Return to the Summary Table.

Figure 57. HYSTERESIS_CH4 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH4_LSB[3:0]				HYSTERESIS_CH4[3:0]			
R/W-1111b				R/W-0b			

Table 48. HYSTERESIS_CH4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH4_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH4[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.39 HIGH_TH_CH4 Register (Address = 0x31) [reset = 0xFF]

HIGH_TH_CH4 is shown in Figure 58 and described in Table 49.

Return to the Summary Table.

Figure 58. HIGH_TH_CH4 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH4_MSB[7:0]							
R/W-11111111b							

Table 49. HIGH_TH_CH4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH4_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.40 EVENT_COUNT_CH4 Register (Address = 0x32) [reset = 0x0]

EVENT_COUNT_CH4 is shown in Figure 59 and described in Table 50.

Return to the Summary Table.

Figure 59. EVENT_COUNT_CH4 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH4_LSB[3:0]				EVENT_COUNT_CH4[3:0]			
R/W-0b				R/W-0b			

Table 50. EVENT_COUNT_CH4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH4_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH4[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.41 LOW_TH_CH4 Register (Address = 0x33) [reset = 0x0]

LOW_TH_CH4 is shown in Figure 60 and described in Table 51.

Return to the Summary Table.

Figure 60. LOW_TH_CH4 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH4_MSB[7:0]							
R/W-0b							

Table 51. LOW_TH_CH4 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH4_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.42 HYSTERESIS_CH5 Register (Address = 0x34) [reset = 0xF0]

HYSTERESIS_CH5 is shown in Figure 61 and described in Table 52.

Return to the Summary Table.

Figure 61. HYSTERESIS_CH5 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH5_LSB[3:0]				HYSTERESIS_CH5[3:0]			
R/W-1111b				R/W-0b			

Table 52. HYSTERESIS_CH5 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH5_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH5[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.43 HIGH_TH_CH5 Register (Address = 0x35) [reset = 0xFF]

HIGH_TH_CH5 is shown in Figure 62 and described in Table 53.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 62. HIGH_TH_CH5 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH5_MSB[7:0]							
R/W-11111111b							

Table 53. HIGH_TH_CH5 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH5_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.44 EVENT_COUNT_CH5 Register (Address = 0x36) [reset = 0x0]

EVENT_COUNT_CH5 is shown in Figure 63 and described in Table 54.

Return to the Summary Table.

Figure 63. EVENT_COUNT_CH5 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH5_LSB[3:0]				EVENT_COUNT_CH5[3:0]			
R/W-0b				R/W-0b			

Table 54. EVENT_COUNT_CH5 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH5_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH5[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.45 LOW_TH_CH5 Register (Address = 0x37) [reset = 0x0]

LOW_TH_CH5 is shown in Figure 64 and described in Table 55.

Return to the Summary Table.

Figure 64. LOW_TH_CH5 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH5_MSB[7:0]							
R/W-0b							

Table 55. LOW_TH_CH5 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH5_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.46 HYSTERESIS_CH6 Register (Address = 0x38) [reset = 0xF0]

HYSTERESIS_CH6 is shown in Figure 65 and described in Table 56.

Return to the Summary Table.

Figure 65. HYSTERESIS_CH6 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH6_LSB[3:0]				HYSTERESIS_CH6[3:0]			
R/W-1111b				R/W-0b			

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 56. HYSTERESIS_CH6 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH6_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH6[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.47 HIGH_TH_CH6 Register (Address = 0x39) [reset = 0xFF]

HIGH_TH_CH6 is shown in Figure 66 and described in Table 57.

Return to the Summary Table.

Figure 66. HIGH_TH_CH6 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH6_MSB[7:0]							
R/W-11111111b							

Table 57. HIGH_TH_CH6 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH6_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.48 EVENT_COUNT_CH6 Register (Address = 0x3A) [reset = 0x0]

EVENT_COUNT_CH6 is shown in Figure 67 and described in Table 58.

Return to the Summary Table.

Figure 67. EVENT_COUNT_CH6 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH6_LSB[3:0]				EVENT_COUNT_CH6[3:0]			
R/W-0b				R/W-0b			

Table 58. EVENT_COUNT_CH6 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH6_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	EVENT_COUNT_CH6[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.49 LOW_TH_CH6 Register (Address = 0x3B) [reset = 0x0]

LOW_TH_CH6 is shown in Figure 68 and described in Table 59.

Return to the Summary Table.

Figure 68. LOW_TH_CH6 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH6_MSB[7:0]							
R/W-0b							

ADVANCE INFORMATION

Table 59. LOW_TH_CH6 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH6_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.50 HYSTERESIS_CH7 Register (Address = 0x3C) [reset = 0xF0]

HYSTERESIS_CH7 is shown in Figure 69 and described in Table 60.

Return to the Summary Table.

Figure 69. HYSTERESIS_CH7 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH7_LSB[3:0]				HYSTERESIS_CH7[3:0]			
R/W-1111b				R/W-0b			

Table 60. HYSTERESIS_CH7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	HIGH_THRESHOLD_CH7_LSB[3:0]	R/W	1111b	Lower 4-bits of high threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.
3-0	HYSTERESIS_CH7[3:0]	R/W	0b	4-bit hysteresis for high and low thresholds. This 4-bit hysteris is left shifted 3 times and applied on the lower 7-bits of the threshold. Total hysteresis = 7-bits [4-bits, 000b]

8.5.51 HIGH_TH_CH7 Register (Address = 0x3D) [reset = 0xFF]

HIGH_TH_CH7 is shown in Figure 70 and described in Table 61.

Return to the Summary Table.

Figure 70. HIGH_TH_CH7 Register

7	6	5	4	3	2	1	0
HIGH_THRESHOLD_CH7_MSB[7:0]							
R/W-11111111b							

Table 61. HIGH_TH_CH7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	HIGH_THRESHOLD_CH7_MSB[7:0]	R/W	11111111b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.52 EVENT_COUNT_CH7 Register (Address = 0x3E) [reset = 0x0]

EVENT_COUNT_CH7 is shown in Figure 71 and described in Table 62.

Return to the Summary Table.

Figure 71. EVENT_COUNT_CH7 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH7_LSB[3:0]				EVENT_COUNT_CH7[3:0]			
R/W-0b				R/W-0b			

Table 62. EVENT_COUNT_CH7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	LOW_THRESHOLD_CH7_LSB[3:0]	R/W	0b	Lower 4-bits of low threshold for analog input. These bits are compared with bits 3:0 of ADC conversion result.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 62. EVENT_COUNT_CH7 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-0	EVENT_COUNT_CH7[3:0]	R/W	0b	Configuration for checking 'n+1' consecutive samples exceeding either high or low threshold before setting alert flag.

8.5.53 LOW_TH_CH7 Register (Address = 0x3F) [reset = 0x0]

LOW_TH_CH7 is shown in Figure 72 and described in Table 63.

Return to the Summary Table.

Figure 72. LOW_TH_CH7 Register

7	6	5	4	3	2	1	0
LOW_THRESHOLD_CH7_MSB[7:0]							
R/W-0b							

Table 63. LOW_TH_CH7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LOW_THRESHOLD_CH7_MSB[7:0]	R/W	0b	MSB aligned high threshold for analog input. These bits are compared with top 8 bits of ADC conversion result.

8.5.54 MAX_CH0_LSB Register (Address = 0x60) [reset = 0x0]

MAX_CH0_LSB is shown in Figure 73 and described in Table 64.

Return to the Summary Table.

Figure 73. MAX_CH0_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH0_LSB[7:0]							
R-0b							

Table 64. MAX_CH0_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH0_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.55 MAX_CH0_MSB Register (Address = 0x61) [reset = 0x0]

MAX_CH0_MSB is shown in Figure 74 and described in Table 65.

Return to the Summary Table.

Figure 74. MAX_CH0_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH0_MSB[7:0]							
R-0b							

Table 65. MAX_CH0_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH0_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.56 MAX_CH1_LSB Register (Address = 0x62) [reset = 0x0]

MAX_CH1_LSB is shown in Figure 75 and described in Table 66.

Return to the Summary Table.

Figure 75. MAX_CH1_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH1_LSB[7:0]							
R-0b							

Table 66. MAX_CH1_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH1_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.57 MAX_CH1_MSB Register (Address = 0x63) [reset = 0x0]

MAX_CH1_MSB is shown in Figure 76 and described in Table 67.

Return to the Summary Table.

Figure 76. MAX_CH1_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH1_MSB[7:0]							
R-0b							

Table 67. MAX_CH1_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH1_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.58 MAX_CH2_LSB Register (Address = 0x64) [reset = 0x0]

MAX_CH2_LSB is shown in Figure 77 and described in Table 68.

Return to the Summary Table.

Figure 77. MAX_CH2_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH2_LSB[7:0]							
R-0b							

Table 68. MAX_CH2_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH2_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.59 MAX_CH2_MSB Register (Address = 0x65) [reset = 0x0]

MAX_CH2_MSB is shown in Figure 78 and described in Table 69.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 78. MAX_CH2_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH2_MSB[7:0]							
R-0b							

Table 69. MAX_CH2_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH2_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.60 MAX_CH3_LSB Register (Address = 0x66) [reset = 0x0]

MAX_CH3_LSB is shown in Figure 79 and described in Table 70.

Return to the Summary Table.

Figure 79. MAX_CH3_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH3_LSB[7:0]							
R-0b							

Table 70. MAX_CH3_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH3_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.61 MAX_CH3_MSB Register (Address = 0x67) [reset = 0x0]

MAX_CH3_MSB is shown in Figure 80 and described in Table 71.

Return to the Summary Table.

Figure 80. MAX_CH3_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH3_MSB[7:0]							
R-0b							

Table 71. MAX_CH3_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH3_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.62 MAX_CH4_LSB Register (Address = 0x68) [reset = 0x0]

MAX_CH4_LSB is shown in Figure 81 and described in Table 72.

Return to the Summary Table.

Figure 81. MAX_CH4_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH4_LSB[7:0]							
R-0b							

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 72. MAX_CH4_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH4_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.63 MAX_CH4_MSB Register (Address = 0x69) [reset = 0x0]

MAX_CH4_MSB is shown in Figure 82 and described in Table 73.

Return to the Summary Table.

Figure 82. MAX_CH4_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH4_MSB[7:0]							
R-0b							

Table 73. MAX_CH4_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH4_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.64 MAX_CH5_LSB Register (Address = 0x6A) [reset = 0x0]

MAX_CH5_LSB is shown in Figure 83 and described in Table 74.

Return to the Summary Table.

Figure 83. MAX_CH5_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH5_LSB[7:0]							
R-0b							

Table 74. MAX_CH5_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH5_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.65 MAX_CH5_MSB Register (Address = 0x6B) [reset = 0x0]

MAX_CH5_MSB is shown in Figure 84 and described in Table 75.

Return to the Summary Table.

Figure 84. MAX_CH5_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH5_MSB[7:0]							
R-0b							

Table 75. MAX_CH5_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH5_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.66 MAX_CH6_LSB Register (Address = 0x6C) [reset = 0x0]

MAX_CH6_LSB is shown in Figure 85 and described in Table 76.

Return to the Summary Table.

Figure 85. MAX_CH6_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH6_LSB[7:0]							
R-0b							

Table 76. MAX_CH6_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH6_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.67 MAX_CH6_MSB Register (Address = 0x6D) [reset = 0x0]

MAX_CH6_MSB is shown in Figure 86 and described in Table 77.

Return to the Summary Table.

Figure 86. MAX_CH6_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH6_MSB[7:0]							
R-0b							

Table 77. MAX_CH6_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH6_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.68 MAX_CH7_LSB Register (Address = 0x6E) [reset = 0x0]

MAX_CH7_LSB is shown in Figure 87 and described in Table 78.

Return to the Summary Table.

Figure 87. MAX_CH7_LSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH7_LSB[7:0]							
R-0b							

Table 78. MAX_CH7_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH7_LSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.69 MAX_CH7_MSB Register (Address = 0x6F) [reset = 0x0]

MAX_CH7_MSB is shown in Figure 88 and described in Table 79.

Return to the Summary Table.

ADVANCE INFORMATION

Figure 88. MAX_CH7_MSB Register

7	6	5	4	3	2	1	0
MAX_VALUE_CH7_MSB[7:0]							
R-0b							

Table 79. MAX_CH7_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MAX_VALUE_CH7_MSB[7:0]	R	0b	Maximum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0.

8.5.70 MIN_CH0_LSB Register (Address = 0x80) [reset = 0xFF]

MIN_CH0_LSB is shown in Figure 89 and described in Table 80.

Return to the Summary Table.

Figure 89. MIN_CH0_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH0_LSB[7:0]							
R-11111111b							

Table 80. MIN_CH0_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH0_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.71 MIN_CH0_MSB Register (Address = 0x81) [reset = 0xFF]

MIN_CH0_MSB is shown in Figure 90 and described in Table 81.

Return to the Summary Table.

Figure 90. MIN_CH0_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH0_MSB[7:0]							
R-11111111b							

Table 81. MIN_CH0_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH0_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.72 MIN_CH1_LSB Register (Address = 0x82) [reset = 0xFF]

MIN_CH1_LSB is shown in Figure 91 and described in Table 82.

Return to the Summary Table.

Figure 91. MIN_CH1_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH1_LSB[7:0]							
R-11111111b							

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 82. MIN_CH1_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH1_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.73 MIN_CH1_MSB Register (Address = 0x83) [reset = 0xFF]

MIN_CH1_MSB is shown in Figure 92 and described in Table 83.

Return to the Summary Table.

Figure 92. MIN_CH1_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH1_MSB[7:0]							
R-11111111b							

Table 83. MIN_CH1_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH1_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.74 MIN_CH2_LSB Register (Address = 0x84) [reset = 0xFF]

MIN_CH2_LSB is shown in Figure 93 and described in Table 84.

Return to the Summary Table.

Figure 93. MIN_CH2_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH2_LSB[7:0]							
R-11111111b							

Table 84. MIN_CH2_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH2_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.75 MIN_CH2_MSB Register (Address = 0x85) [reset = 0xFF]

MIN_CH2_MSB is shown in Figure 94 and described in Table 85.

Return to the Summary Table.

Figure 94. MIN_CH2_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH2_MSB[7:0]							
R-11111111b							

Table 85. MIN_CH2_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH2_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.76 MIN_CH3_LSB Register (Address = 0x86) [reset = 0xFF]

MIN_CH3_LSB is shown in Figure 95 and described in Table 86.

Return to the Summary Table.

Figure 95. MIN_CH3_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH3_LSB[7:0]							
R-11111111b							

Table 86. MIN_CH3_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH3_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.77 MIN_CH3_MSB Register (Address = 0x87) [reset = 0xFF]

MIN_CH3_MSB is shown in Figure 96 and described in Table 87.

Return to the Summary Table.

Figure 96. MIN_CH3_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH3_MSB[7:0]							
R-11111111b							

Table 87. MIN_CH3_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH3_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.78 MIN_CH4_LSB Register (Address = 0x88) [reset = 0xFF]

MIN_CH4_LSB is shown in Figure 97 and described in Table 88.

Return to the Summary Table.

Figure 97. MIN_CH4_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH4_LSB[7:0]							
R-11111111b							

Table 88. MIN_CH4_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH4_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.79 MIN_CH4_MSB Register (Address = 0x89) [reset = 0xFF]

MIN_CH4_MSB is shown in Figure 98 and described in Table 89.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 98. MIN_CH4_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH4_MSB[7:0]							
R-11111111b							

Table 89. MIN_CH4_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH4_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.80 MIN_CH5_LSB Register (Address = 0x8A) [reset = 0xFF]

MIN_CH5_LSB is shown in Figure 99 and described in Table 90.

Return to the Summary Table.

Figure 99. MIN_CH5_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH5_LSB[7:0]							
R-11111111b							

Table 90. MIN_CH5_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH5_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.81 MIN_CH5_MSB Register (Address = 0x8B) [reset = 0xFF]

MIN_CH5_MSB is shown in Figure 100 and described in Table 91.

Return to the Summary Table.

Figure 100. MIN_CH5_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH5_MSB[7:0]							
R-11111111b							

Table 91. MIN_CH5_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH5_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.82 MIN_CH6_LSB Register (Address = 0x8C) [reset = 0xFF]

MIN_CH6_LSB is shown in Figure 101 and described in Table 92.

Return to the Summary Table.

Figure 101. MIN_CH6_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH6_LSB[7:0]							
R-11111111b							

ADVANCE INFORMATION

Table 92. MIN_CH6_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH6_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.83 MIN_CH6_MSB Register (Address = 0x8D) [reset = 0xFF]

MIN_CH6_MSB is shown in Figure 102 and described in Table 93.

Return to the Summary Table.

Figure 102. MIN_CH6_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH6_MSB[7:0]							
R-11111111b							

Table 93. MIN_CH6_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH6_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.84 MIN_CH7_LSB Register (Address = 0x8E) [reset = 0xFF]

MIN_CH7_LSB is shown in Figure 103 and described in Table 94.

Return to the Summary Table.

Figure 103. MIN_CH7_LSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH7_LSB[7:0]							
R-11111111b							

Table 94. MIN_CH7_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH7_LSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

8.5.85 MIN_CH7_MSB Register (Address = 0x8F) [reset = 0xFF]

MIN_CH7_MSB is shown in Figure 104 and described in Table 95.

Return to the Summary Table.

Figure 104. MIN_CH7_MSB Register

7	6	5	4	3	2	1	0
MIN_VALUE_CH7_MSB[7:0]							
R-11111111b							

Table 95. MIN_CH7_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	MIN_VALUE_CH7_MSB[7:0]	R	11111111b	Minimum code recorded on the analog input channel from the last time this register was read. Reading the register will reset the value to 0xFF.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.86 RECENT_CH0_LSB Register (Address = 0xA0) [reset = 0x0]

RECENT_CH0_LSB is shown in Figure 105 and described in Table 96.

Return to the Summary Table.

Figure 105. RECENT_CH0_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH0_LSB[7:0]							
R-0b							

Table 96. RECENT_CH0_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH0_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.87 RECENT_CH0_MSB Register (Address = 0xA1) [reset = 0x0]

RECENT_CH0_MSB is shown in Figure 106 and described in Table 97.

Return to the Summary Table.

Figure 106. RECENT_CH0_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH0_MSB[7:0]							
R-0b							

Table 97. RECENT_CH0_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH0_MSB[7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.88 RECENT_CH1_LSB Register (Address = 0xA2) [reset = 0x0]

RECENT_CH1_LSB is shown in Figure 107 and described in Table 98.

Return to the Summary Table.

Figure 107. RECENT_CH1_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH1_LSB[7:0]							
R-0b							

Table 98. RECENT_CH1_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH1_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.89 RECENT_CH1_MSB Register (Address = 0xA3) [reset = 0x0]

RECENT_CH1_MSB is shown in Figure 108 and described in Table 99.

Return to the Summary Table.

Copyright © 2019, Texas Instruments Incorporated

Figure 108. RECENT_CH1_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH1_MSB[7:0]							
R-0b							

Table 99. RECENT_CH1_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH1_MSB [7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.90 RECENT_CH2_LSB Register (Address = 0xA4) [reset = 0x0]

RECENT_CH2_LSB is shown in Figure 109 and described in Table 100.

Return to the Summary Table.

Figure 109. RECENT_CH2_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH2_LSB[7:0]							
R-0b							

Table 100. RECENT_CH2_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH2_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.91 RECENT_CH2_MSB Register (Address = 0xA5) [reset = 0x0]

RECENT_CH2_MSB is shown in Figure 110 and described in Table 101.

Return to the Summary Table.

Figure 110. RECENT_CH2_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH2_MSB[7:0]							
R-0b							

Table 101. RECENT_CH2_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH2_MSB [7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.92 RECENT_CH3_LSB Register (Address = 0xA6) [reset = 0x0]

RECENT_CH3_LSB is shown in Figure 111 and described in Table 102.

Return to the Summary Table.

Figure 111. RECENT_CH3_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH3_LSB[7:0]							
R-0b							

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 102. RECENT_CH3_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH3_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.93 RECENT_CH3_MSB Register (Address = 0xA7) [reset = 0x0]

RECENT_CH3_MSB is shown in Figure 112 and described in Table 103.

Return to the Summary Table.

Figure 112. RECENT_CH3_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH3_MSB[7:0]							
R-0b							

Table 103. RECENT_CH3_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH3_MSB[7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.94 RECENT_CH4_LSB Register (Address = 0xA8) [reset = 0x0]

RECENT_CH4_LSB is shown in Figure 113 and described in Table 104.

Return to the Summary Table.

Figure 113. RECENT_CH4_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH4_LSB[7:0]							
R-0b							

Table 104. RECENT_CH4_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH4_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.95 RECENT_CH4_MSB Register (Address = 0xA9) [reset = 0x0]

RECENT_CH4_MSB is shown in Figure 114 and described in Table 105.

Return to the Summary Table.

Figure 114. RECENT_CH4_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH4_MSB[7:0]							
R-0b							

Table 105. RECENT_CH4_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH4_MSB[7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.96 RECENT_CH5_LSB Register (Address = 0xAA) [reset = 0x0]

RECENT_CH5_LSB is shown in Figure 115 and described in Table 106.

Return to the Summary Table.

Figure 115. RECENT_CH5_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH5_LSB[7:0]							
R-0b							

Table 106. RECENT_CH5_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH5_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.97 RECENT_CH5_MSB Register (Address = 0xAB) [reset = 0x0]

RECENT_CH5_MSB is shown in Figure 116 and described in Table 107.

Return to the Summary Table.

Figure 116. RECENT_CH5_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH5_MSB[7:0]							
R-0b							

Table 107. RECENT_CH5_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH5_MSB[7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.98 RECENT_CH6_LSB Register (Address = 0xAC) [reset = 0x0]

RECENT_CH6_LSB is shown in Figure 117 and described in Table 108.

Return to the Summary Table.

Figure 117. RECENT_CH6_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH6_LSB[7:0]							
R-0b							

Table 108. RECENT_CH6_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH6_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.99 RECENT_CH6_MSB Register (Address = 0xAD) [reset = 0x0]

RECENT_CH6_MSB is shown in Figure 118 and described in Table 109.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 118. RECENT_CH6_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH6_MSB[7:0]							
R-0b							

Table 109. RECENT_CH6_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH6_MSB [7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.100 RECENT_CH7_LSB Register (Address = 0xAE) [reset = 0x0]

RECENT_CH7_LSB is shown in Figure 119 and described in Table 110.

Return to the Summary Table.

Figure 119. RECENT_CH7_LSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH7_LSB[7:0]							
R-0b							

Table 110. RECENT_CH7_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH7_LSB[7:0]	R	0b	Next 8 bits of the last result for this analog input channel.

8.5.101 RECENT_CH7_MSB Register (Address = 0xAF) [reset = 0x0]

RECENT_CH7_MSB is shown in Figure 120 and described in Table 111.

Return to the Summary Table.

Figure 120. RECENT_CH7_MSB Register

7	6	5	4	3	2	1	0
LAST_VALUE_CH7_MSB[7:0]							
R-0b							

Table 111. RECENT_CH7_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	LAST_VALUE_CH7_MSB [7:0]	R	0b	MSB aligned first 8 bits of the last result for this analog input channel.

8.5.102 RMS_CFG Register (Address = 0xC0) [reset = 0x0]

RMS_CFG is shown in Figure 121 and described in Table 112.

Return to the Summary Table.

Figure 121. RMS_CFG Register

7	6	5	4	3	2	1	0
RMS_CHID[3:0]				RESERVED	RMS_DC_SUB	RMS_SAMPLES[1:0]	
R/W-0b				R-0b	R/W-0b	R/W-0b	

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 112. RMS_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	RMS_CHID[3:0]	R/W	0b	Select analog input channel for RMS computation.
3	RESERVED	R	0b	Reserved. Reads return 0.
2	RMS_DC_SUB	R/W	0b	Subtract DC component from the RMS result. 0b = Do not subtract DC component. 1b = Subtract DC component.
1-0	RMS_SAMPLES[1:0]	R/W	0b	Number of samples for computing RMS result. 0b = 1024 1b = 4096 10b = 16384 11b = 65536

8.5.103 RMS_LSB Register (Address = 0xC1) [reset = 0x0]

RMS_LSB is shown in Figure 122 and described in Table 113.

Return to the Summary Table.

Figure 122. RMS_LSB Register

7	6	5	4	3	2	1	0
RMS_RESULT_LSB[7:0]							
R-0b							

Table 113. RMS_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	RMS_RESULT_LSB[7:0]	R	0b	Lower 8-bits of RMS computation result.

8.5.104 RMS_MSB Register (Address = 0xC2) [reset = 0x0]

RMS_MSB is shown in Figure 123 and described in Table 114.

Return to the Summary Table.

Figure 123. RMS_MSB Register

7	6	5	4	3	2	1	0
RMS_RESULT_MSB[7:0]							
R-0b							

Table 114. RMS_MSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	RMS_RESULT_MSB[7:0]	R	0b	Upper 8-bits of RMS result.

8.5.105 GPO0_TRIG_EVENT_SEL Register (Address = 0xC3) [reset = 0x2]

GPO0_TRIG_EVENT_SEL is shown in Figure 124 and described in Table 115.

Return to the Summary Table.

Figure 124. GPO0_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO0_TRIG_EVENT_SEL[7:0]							
R/W-10b							

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 115. GPO0_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO0_TRIG_EVENT_SEL[7:0]	R/W	10b	Select the inputs AIN/GPIO[7:0] which can trigger an event based update on GPO0. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO0 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO0 output.

8.5.106 GPO1_TRIG_EVENT_SEL Register (Address = 0xC5) [reset = 0x1]

GPO1_TRIG_EVENT_SEL is shown in Figure 125 and described in Table 116.

Return to the Summary Table.

Figure 125. GPO1_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO1_TRIG_EVENT_SEL[7:0]							
R/W-1b							

Table 116. GPO1_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO1_TRIG_EVENT_SEL[7:0]	R/W	1b	Select the inputs AIN/GPIO[7:0] which can trigger an event based update on GPO1. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO1 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit ttrigger GPO1 output.

8.5.107 GPO2_TRIG_EVENT_SEL Register (Address = 0xC7) [reset = 0x8]

GPO2_TRIG_EVENT_SEL is shown in Figure 126 and described in Table 117.

Return to the Summary Table.

Figure 126. GPO2_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO2_TRIG_EVENT_SEL[7:0]							
R/W-1000b							

Table 117. GPO2_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO2_TRIG_EVENT_SEL[7:0]	R/W	1000b	Select the inputs AIN/GPIO[7:0] which can trigger an event based update on GPO2. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO2 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO2 output.

8.5.108 GPO3_TRIG_EVENT_SEL Register (Address = 0xC9) [reset = 0x4]

GPO3_TRIG_EVENT_SEL is shown in Figure 127 and described in Table 118.

Return to the Summary Table.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Figure 127. GPO3_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO3_TRIG_EVENT_SEL[7:0]							
R/W-100b							

Table 118. GPO3_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO3_TRIG_EVENT_SEL[7:0]	R/W	100b	Select the inputs AIN/GPIO[7:0] which can trigger an event based update on GPO3. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO3 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO3 output.

8.5.109 GPO4_TRIG_EVENT_SEL Register (Address = 0xCB) [reset = 0x20]

GPO4_TRIG_EVENT_SEL is shown in Figure 128 and described in Table 119.

Return to the Summary Table.

Figure 128. GPO4_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO4_TRIG_EVENT_SEL[7:0]							
R/W-100000b							

Table 119. GPO4_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO4_TRIG_EVENT_SEL[7:0]	R/W	100000b	Select the inputs AIN/GPIO[7:0] which can trigger an Event based update on GPO4. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO4 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO4 output.

8.5.110 GPO5_TRIG_EVENT_SEL Register (Address = 0xCD) [reset = 0x10]

GPO5_TRIG_EVENT_SEL is shown in Figure 129 and described in Table 120.

Return to the Summary Table.

Figure 129. GPO5_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO5_TRIG_EVENT_SEL[7:0]							
R/W-10000b							

Table 120. GPO5_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO5_TRIG_EVENT_SEL[7:0]	R/W	10000b	Select the inputs AIN/GPIO[7:0] which can trigger an Event based update on GPO5. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO5 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO5 output.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.111 GPO6_TRIG_EVENT_SEL Register (Address = 0xCF) [reset = 0x80]

GPO6_TRIG_EVENT_SEL is shown in Figure 130 and described in Table 121.

Return to the Summary Table.

Figure 130. GPO6_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO6_TRIG_EVENT_SEL[7:0]							
R/W-10000000b							

Table 121. GPO6_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO6_TRIG_EVENT_SEL[7:0]	R/W	10000000b	Select the inputs AIN/GPIO[7:0] which can trigger an Event based update on GPO6. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO6 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO6 output.

8.5.112 GPO7_TRIG_EVENT_SEL Register (Address = 0xD1) [reset = 0x40]

GPO7_TRIG_EVENT_SEL is shown in Figure 131 and described in Table 122.

Return to the Summary Table.

Figure 131. GPO7_TRIG_EVENT_SEL Register

7	6	5	4	3	2	1	0
GPO7_TRIG_EVENT_SEL[7:0]							
R/W-1000000b							

Table 122. GPO7_TRIG_EVENT_SEL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO7_TRIG_EVENT_SEL[7:0]	R/W	1000000b	Select the inputs AIN/GPIO[7:0] which can trigger an Event based update on GPO7. 0b = Alert flags for the AIN/GPIO corresponding to this bit do not trigger GPO7 output. 1b = Alert flags for the AIN/GPIO corresponding to this bit trigger GPO7 output.

8.5.113 GPO_VALUE_ZCD_CFG_CH0_CH3 Register (Address = 0xE3) [reset = 0x0]

GPO_VALUE_ZCD_CFG_CH0_CH3 is shown in Figure 132 and described in Table 123.

Return to the Summary Table.

Figure 132. GPO_VALUE_ZCD_CFG_CH0_CH3 Register

7	6	5	4	3	2	1	0
GPO_VALUE_ZCD_CFG_CH3[1:0]		GPO_VALUE_ZCD_CFG_CH2[1:0]		GPO_VALUE_ZCD_CFG_CH1[1:0]		GPO_VALUE_ZCD_CFG_CH0[1:0]	
R/W-0b		R/W-0b		R/W-0b		R/W-0b	

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 123. GPO_VALUE_ZCD_CFG_CH0_CH3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	GPO_VALUE_ZCD_CFG_CH3[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges
5-4	GPO_VALUE_ZCD_CFG_CH2[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges
3-2	GPO_VALUE_ZCD_CFG_CH1[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges
1-0	GPO_VALUE_ZCD_CFG_CH0[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges

8.5.114 GPO_VALUE_ZCD_CFG_CH4_CH7 Register (Address = 0xE4) [reset = 0x0]

GPO_VALUE_ZCD_CFG_CH4_CH7 is shown in Figure 133 and described in Table 124.

Return to the Summary Table.

Figure 133. GPO_VALUE_ZCD_CFG_CH4_CH7 Register

7	6	5	4	3	2	1	0
GPO_VALUE_ZCD_CFG_CH7[1:0]		GPO_VALUE_ZCD_CFG_CH6[1:0]		GPO_VALUE_ZCD_CFG_CH5[1:0]		GPO_VALUE_ZCD_CFG_CH4[1:0]	
R/W-0b		R/W-0b		R/W-0b		R/W-0b	

Table 124. GPO_VALUE_ZCD_CFG_CH4_CH7 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	GPO_VALUE_ZCD_CFG_CH7[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges
5-4	GPO_VALUE_ZCD_CFG_CH6[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Table 124. GPO_VALUE_ZCD_CFG_CH4_CH7 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
3-2	GPO_VALUE_ZCD_CFG_CH5[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges
1-0	GPO_VALUE_ZCD_CFG_CH4[1:0]	R/W	0b	Define the GPO value to be launched on ZCD rising and falling edges. 0b = Rising (0) and falling (0) -> logic 0 on both edges 1b = Rising (0) and falling (1) -> ZCD_bar 10b = Rising (1) and falling (0) -> ZCD 11b = Rising (1) and falling (1) -> logic 1 on both edges

8.5.115 GPO_ZCD_UPDATE_EN Register (Address = 0xE7) [reset = 0x0]

GPO_ZCD_UPDATE_EN is shown in Figure 134 and described in Table 125.

Return to the Summary Table.

Figure 134. GPO_ZCD_UPDATE_EN Register

7	6	5	4	3	2	1	0
GPO_ZCD_UPDATE_EN[7:0]							
R/W-0b							

Table 125. GPO_ZCD_UPDATE_EN Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_ZCD_UPDATE_EN[7:0]	R/W	0b	Update digital outputs GPO[7:0] synchronous to ZCD. 0b = Digital output not updated synchronous to ZCD. 1b = Digital output updated synchronous to ZCD. Configure GPO_VALUE_ON_ZCD_CFG register.

8.5.116 GPO_TRIGGER_CFG Register (Address = 0xE9) [reset = 0x0]

GPO_TRIGGER_CFG is shown in Figure 135 and described in Table 126.

Return to the Summary Table.

Figure 135. GPO_TRIGGER_CFG Register

7	6	5	4	3	2	1	0
GPO_TRIGGER_UPDATE_EN[7:0]							
R/W-0b							

Table 126. GPO_TRIGGER_CFG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_TRIGGER_UPDATE_EN[7:0]	R/W	0b	Update digital outputs GPO[7:0] when corresponding trigger is set. . 0b = Digital output is not updated in response to alert flags. 1b = Digital output is updated when corresponding alert flags are set. Configure GPOx_TRIG_EVENT_SEL register to select which alert flags can trigger an update on the desired GPO.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

8.5.117 GPO_VALUE_TRIG Register (Address = 0xEB) [reset = 0x0]

GPO_VALUE_TRIG is shown in Figure 136 and described in Table 127.

Return to the Summary Table.

Figure 136. GPO_VALUE_TRIG Register

7	6	5	4	3	2	1	0
GPO_VALUE_ON_TRIGGER[7:0]							
R/W-0b							

Table 127. GPO_VALUE_TRIG Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	GPO_VALUE_ON_TRIGGER[7:0]	R/W	0b	Value to be set on digital outputs GPO[7:0] when corresponding trigger occurs. GPO update on alert flags must be enabled in corresponding bit in GPO_TRIGGER_CFG register. 0b = Digital output set to logic 0. 1b = Digital output set to logic 1.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The two primary circuits required to maximize the performance of a high-precision, successive approximation register analog-to-digital converter (SAR ADC) are the input driver and the reference driver circuits. This section details some general principles for designing the input driver circuit, reference driver circuit, and provides some application circuits designed for the ADS7028.

9.2 Typical Applications

9.2.1 Mixed-Channel Configuration

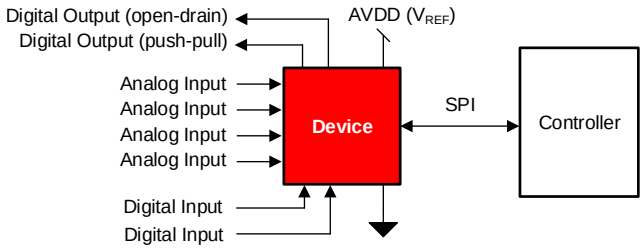


Figure 137. DAQ Circuit: Single-Supply DAQ

9.2.1.1 Design Requirements

The goal of this application is to configure some channels of the ADS7028 as digital inputs, open-drain digital outputs, and push-pull digital outputs.

9.2.1.2 Detailed Design Procedure

The ADS7028 can support GPIO functionality at each input pin. Any analog input pin can be independently configured as a digital input, a digital open-drain output, or a digital push-pull output though the PIN_CFG and GPIO_CFG registers; see Table 3.

9.2.1.2.1 Digital Input

The digital input functionality can be used to monitor a signal within the system. Figure 138 illustrates that the state of the digital input can be read from the GPI_VALUE register.

ADVANCE INFORMATION

Typical Applications (continued)

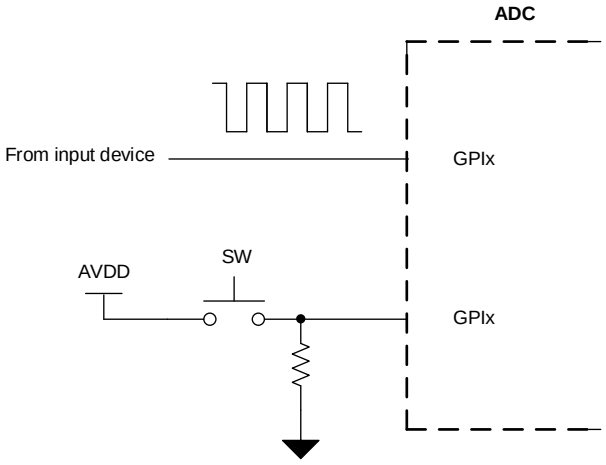


Figure 138. Digital Input

9.2.1.2.2 Digital Open-Drain Output

The channels of the ADS7028 can be configured as digital open-drain outputs supporting an output voltage up to 5.5 V. An open-drain output, as shown in Figure 139, consists of an internal FET (Q) connected to ground. The output is idle when not driven by the device, which means Q is off and the pullup resistor, R_{PULL_UP}, connects the GPOx node to the desired output voltage. The output voltage can range anywhere up to 5.5 V, depending on the external voltage that the GPIOx is pulled up to. When the device is driving the output, Q turns on, thus connecting the pullup resistor to ground and bringing the node voltage at GPOx low.

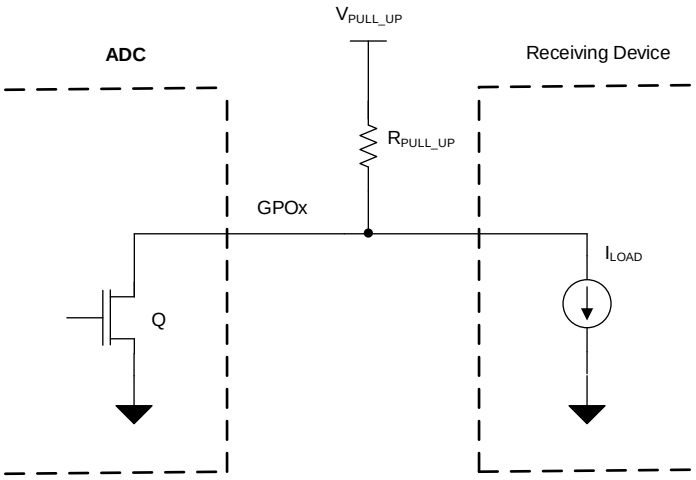


Figure 139. Digital Open-Drain Output

The minimum value of the pullup resistor, as calculated in Equation 6, is given by the ratio of V_{PULL_UP} and the maximum current supported by the device digital output (5 mA).

$$R_{MIN} = (V_{PULL_UP} / 5\ mA) \quad (6)$$

The maximum value of the pullup resistor, as calculated in Equation 7, depends on the minimum input current requirement, I_{LOAD}, of the receiving device driven by this GPIO.

$$R_{MAX} = (V_{PULL_UP} / I_{LOAD}) \quad (7)$$

Select R_{PULL_UP} such that $R_{MIN} < R_{PULL_UP} < R_{MAX}$.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

Typical Applications (continued)

9.2.2 Digital Push-Pull Output Configuration

The channels of the ADS7028 can be configured as digital push-pull outputs supporting an output voltage up to AVDD. As shown in Figure 140, a push-pull output consists of two mirrored opposite bipolar transistors, Q1 and Q2. The device can both source and sink current because only one transistor is on at a time (either Q2 is on and pulls the output low, or Q1 is on and sets the output high). A push-pull configuration always drives the line opposed to an open-drain output where the line is left floating.

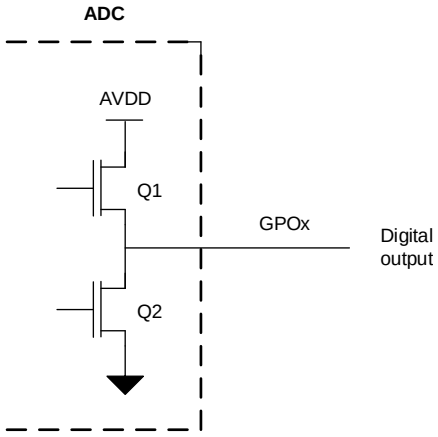


Figure 140. Digital Push-Pull Output

10 Power Supply Recommendations

10.1 AVDD and DVDD Supply Recommendations

The ADS7028 has two separate power supplies: AVDD and DVDD. The device operates on AVDD; DVDD is used for the interface circuits. For supplies greater than 2.35 V, AVDD and DVDD can be shorted externally if single-supply operation is desired. The AVDD supply also defines the full-scale input range of the device. Decouple the AVDD and DVDD pins individually, as shown in Figure 141, with 1-µF ceramic decoupling capacitors. The minimum capacitor value required for AVDD and DVDD is 200 nF and 20 nF, respectively. If both supplies are powered from the same source, a minimum capacitor value of 220 nF is required for decoupling.

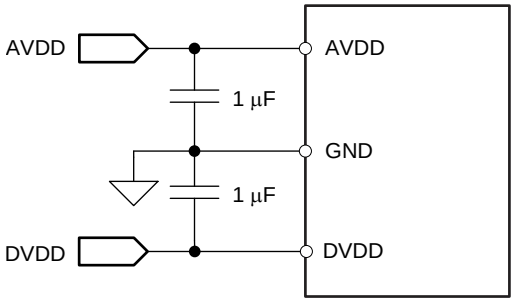


Figure 141. Power-Supply Decoupling

ADVANCE INFORMATION

11 Layout

11.1 Layout Guidelines

Figure 142 shows a board layout example for the ADS7028. Avoid crossing digital lines with the analog signal path and keep the analog input signals and the AVDD supply away from noise sources.

Use 1-µF ceramic bypass capacitors in close proximity to the analog (AVDD) and digital (DVDD) power-supply pins. Avoid placing vias between the AVDD and DVDD pins and the bypass capacitors. Connect the GND pin to the ground plane using short, low-impedance paths. The AVDD supply voltage also functions as the reference voltage for the ADS7028. Place the decoupling capacitor (C_{REF}) for AVDD close to the device AVDD and GND pins and connect C_{REF} to the device pins with thick copper tracks.

11.2 Layout Example

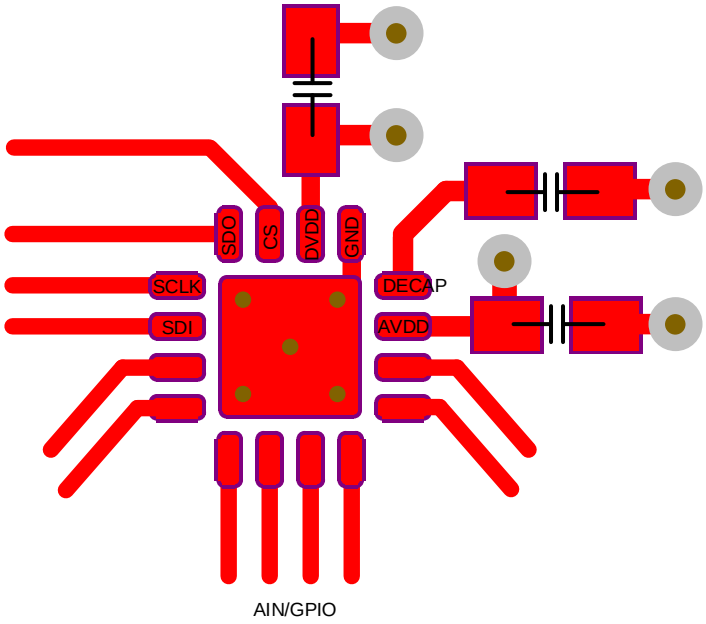


Figure 142. Example Layout

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

12 Device and Documentation Support

12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community ***TI's Engineer-to-Engineer (E2E) Community.*** Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support ***TI's Design Support*** Quickly find helpful E2E forums along with design support tools and contact information for technical support.

12.3 Trademarks

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

12.4 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.5 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

ADVANCE INFORMATION

Copyright © 2019, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS7028IRTER	PREVIEW	WQFN	RTE	16	3000	TBD	Call TI	Call TI	-40 to 85		
ADS7028IRTET	PREVIEW	WQFN	RTE	16	250	TBD	Call TI	Call TI	-40 to 85		
XADS7028IRTER	ACTIVE	WQFN	RTE	16	3000	TBD	Call TI	Call TI	-40 to 85		Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

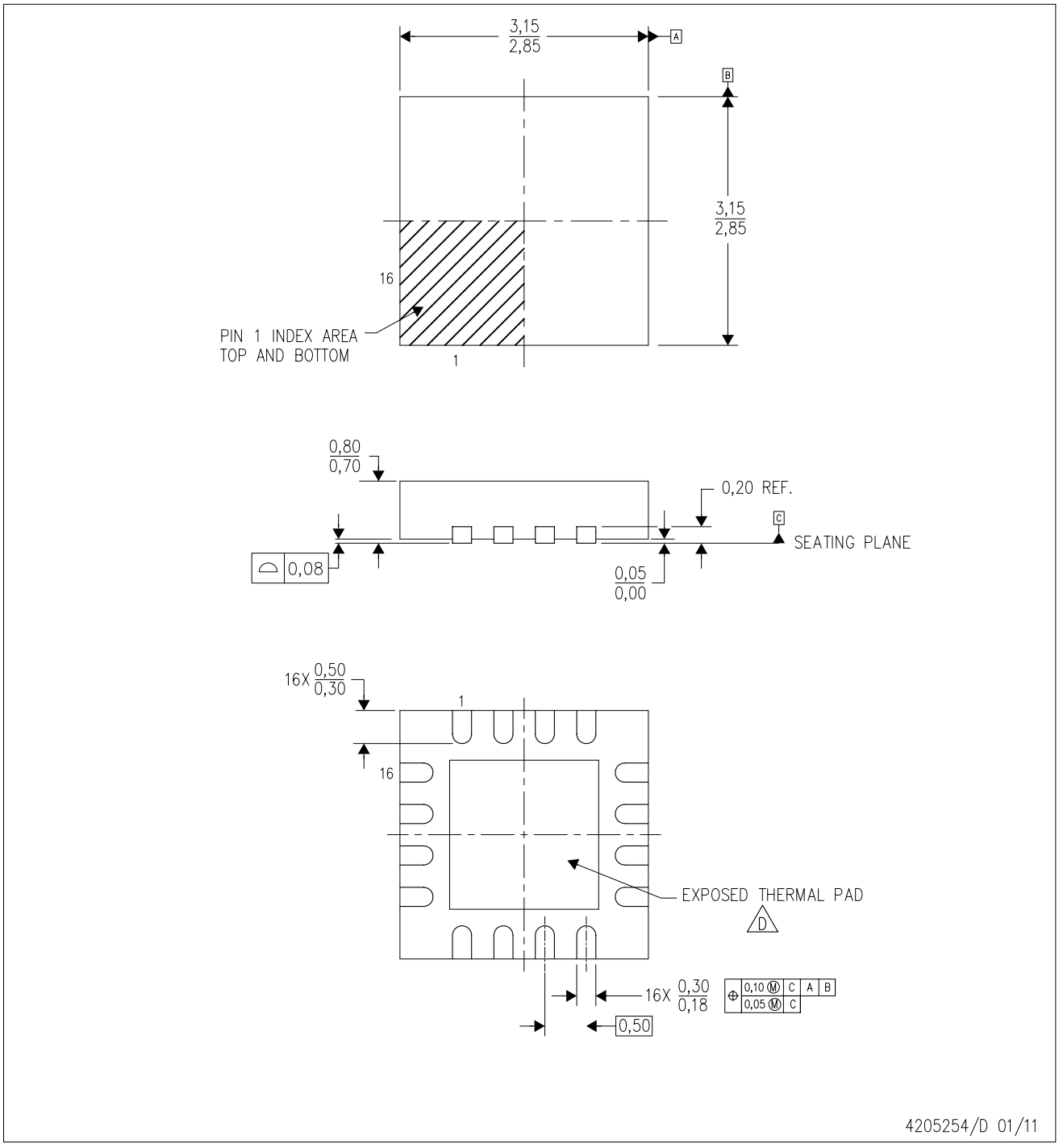
(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

RTE (S–PWQFN–N16) PLASTIC QUAD FLATPACK NO–LEAD



NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. Quad Flatpack, No–leads (QFN) package configuration.
D. The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
E. Falls within JEDEC MO–220.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI’s products are provided subject to TI’s Terms of Sale (www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI’s provision of these resources does not expand or otherwise alter TI’s applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2019, Texas Instruments Incorporated