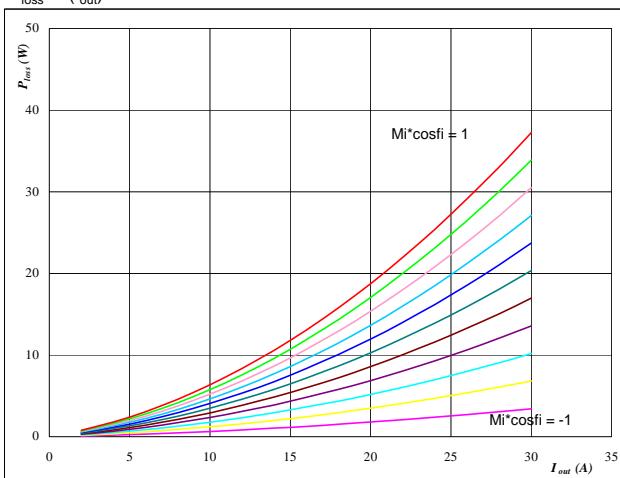


flowPIM 0
Output Inverter Application
600V/15A
General conditions
3phase SPWM

V_{GEon}	=	15 V
V_{GEOFf}	=	0 V
R_{gon}	=	16 Ω
R_{goff}	=	8 Ω

Figure 1
IGBT
Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$

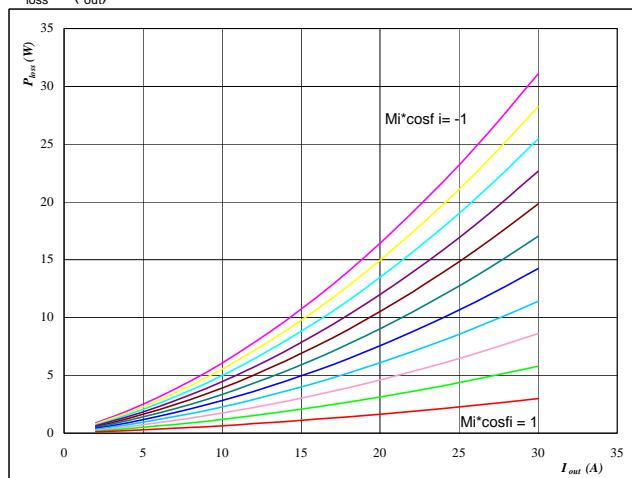

At

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\phi$ from -1 to 1 in steps of 0,2

Figure 2
FWD
Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$

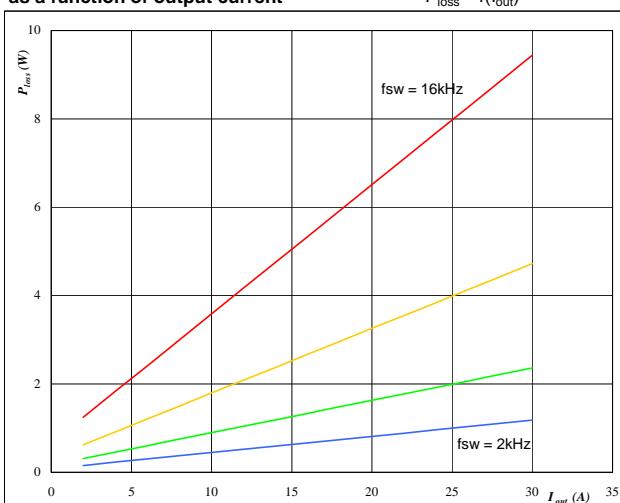

At

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\phi$ from -1 to 1 in steps of 0,2

Figure 3
IGBT
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$


At

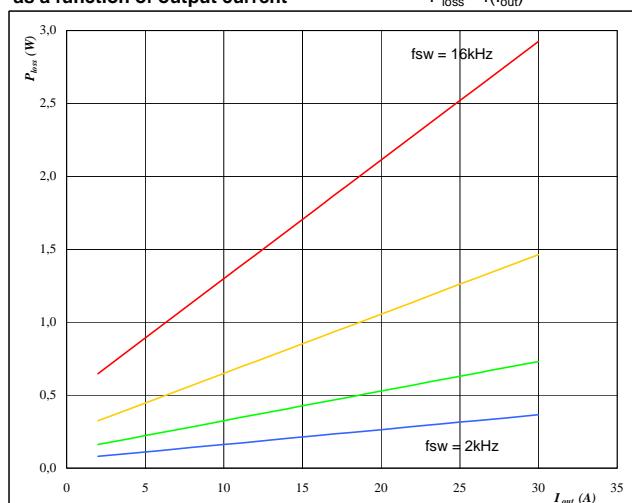
$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 320 \text{ } \text{V}$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 4
FWD
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$


At

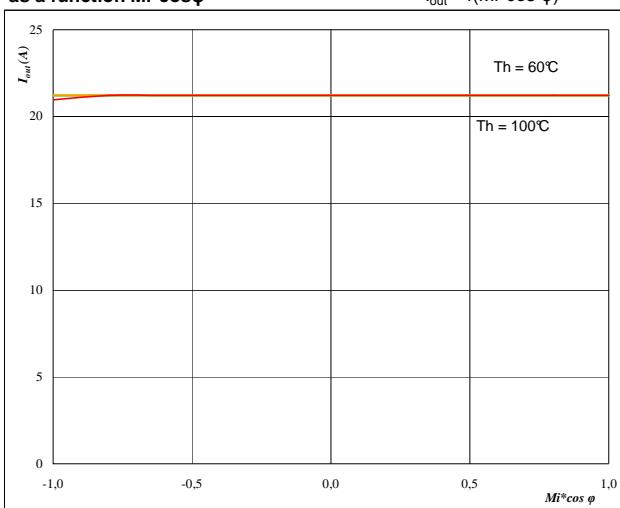
$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 320 \text{ } \text{V}$$

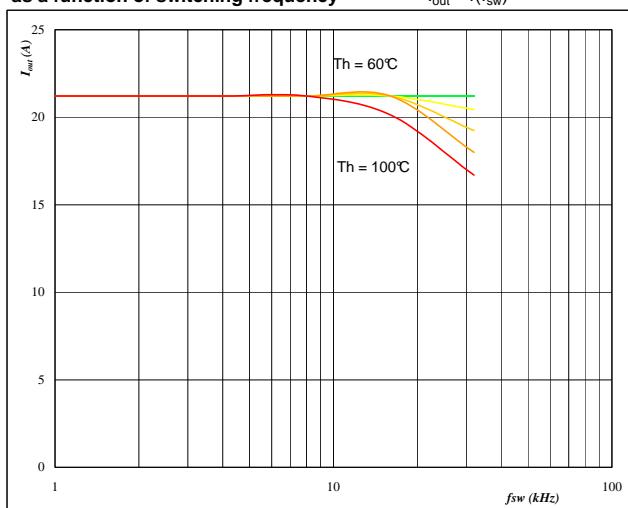
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

flowPIM 0
Output Inverter Application
600V/15A
Figure 5
**Typical available 50Hz output current
as a function $M_i \cos \varphi$**

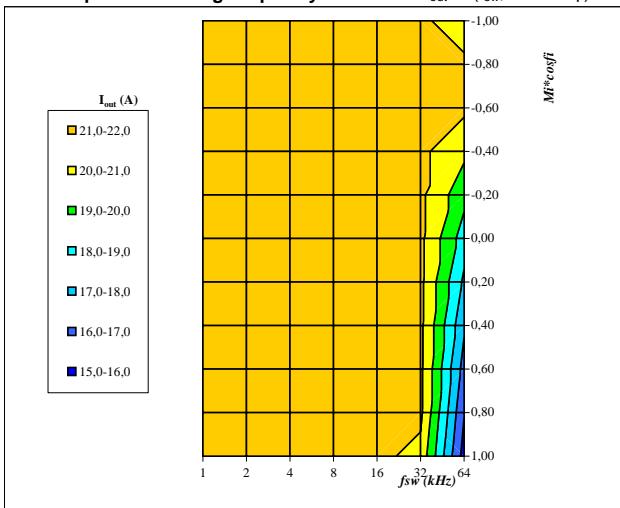
$$I_{out} = f(M_i \cos \varphi)$$


At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ V}$
 $f_{sw} = 4 \text{ kHz}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Phase
Figure 6
**Typical available 50Hz output current
as a function of switching frequency**

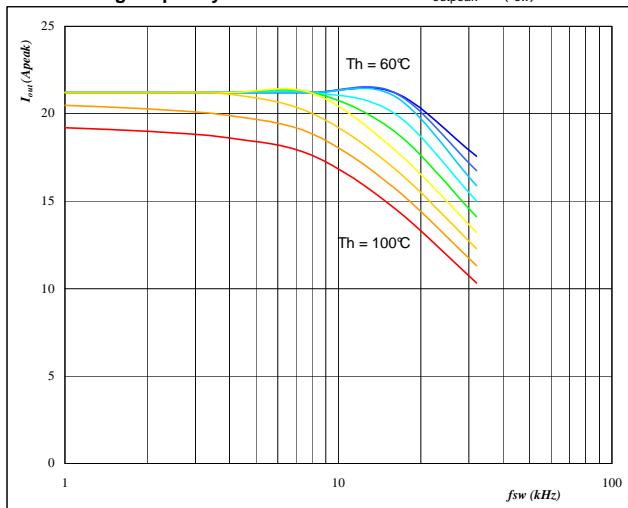
$$I_{out} = f(f_{sw})$$

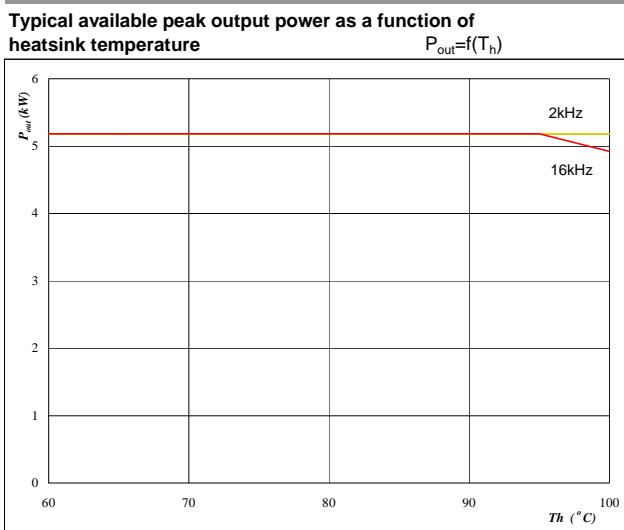

At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ V}$
 $M_i \cos \varphi = 0,8$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Phase
Figure 7
**Typical available 50Hz output current as a function of
 $M_i \cos \varphi$ and switching frequency**

$$I_{out} = f(f_{sw}, M_i \cos \varphi)$$

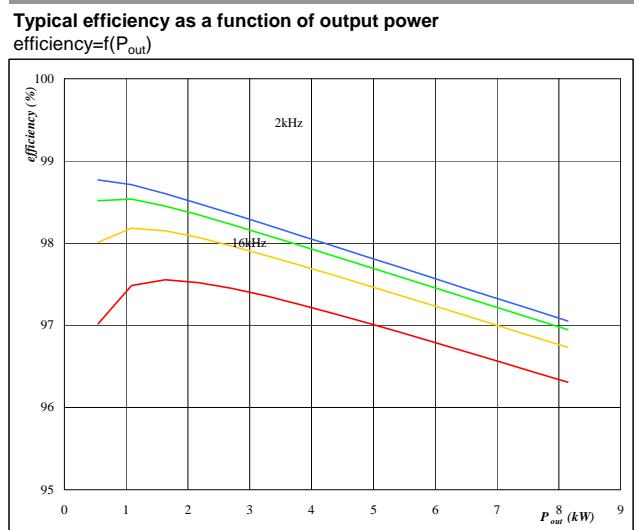

At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ V}$
 $T_h = 80 \text{ } ^\circ\text{C}$
Phase
Figure 8
**Typical available 0Hz output current as a function
of switching frequency**

$$I_{outpeak} = f(f_{sw})$$

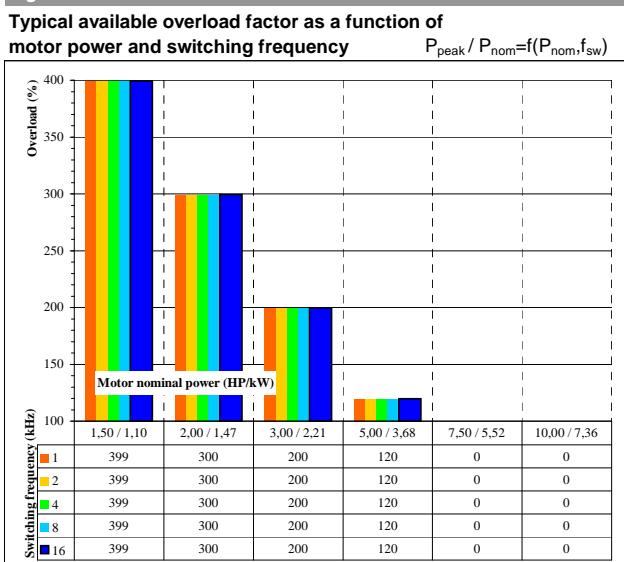

At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ V}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
 $M_i = 0$

flowPIM 0
Output Inverter Application
600V/15A
Figure 9

At

$T_j = 125 \text{ } ^\circ\text{C}$
 DC link = 320 V
 $M_i = 1$
 $\cos \varphi = 0,80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 10

At

$T_j = 125 \text{ } ^\circ\text{C}$
 DC link = 320 V
 $M_i = 1$
 $\cos \varphi = 0,80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 11

At

$T_j = 125 \text{ } ^\circ\text{C}$
 DC link = 320 V
 $M_i = 1$
 $\cos \varphi = 0,8$
 f_{sw} from 1 kHz to 16 kHz in steps of factor 2
 $T_h = 80 \text{ } ^\circ\text{C}$
 Motor eff = 0,85