# TUSB9261
## USB 3.0 TO SATA BRIDGE

# Data Manual

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# Contents

**1 MAIN FEATURES ..... 5**
1.1 TUSB9261 Features ..... 5
1.2 Target Applications ..... 5
**2 RELATED DOCUMENTS ..... 6**
2.1 TUSB9261 Related Documentation ..... 6
**3 INTRODUCTION ..... 7**
3.1 System Overview ..... 7
3.2 Device Block Diagram ..... 7
**4 OPERATION ..... 9**
4.1 General Functionality ..... 9
4.2 Firmware Support ..... 10
4.3 GPIO/PWM LED Designations ..... 10
4.4 Power Up and Reset Sequence ..... 11
**5 SIGNAL DESCRIPTIONS ..... 12**
**6 CLOCK CONNECTIONS ..... 16**
6.1 Clock Source Requirements ..... 16
6.2 Clock Source Selection Guide ..... 16
6.3 Oscillator ..... 17
6.4 Crystal ..... 17
**7 ELECTRICAL SPECIFICATIONS ..... 18**
7.1 Absolute Maximum Ratings ..... 18
7.2 Thermal Information ..... 18
7.3 Recommended Operating Conditions ..... 18
7.4 DC Electrical Characteristics for 3.3-V Digital I/O ..... 19
**8 POWER CONSUMPTION ..... 20**


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# List of Figures

3-1 Device Block Diagram ..... 8
6-1 Typical Crystal Connections ..... 16

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# List of Tables

4-1 GPIO/PWM LED Designations ..... 10
5-1 I/O Definitions ..... 12
5-2 Clock and Reset Signals ..... 12
5-3 SATA Interface Signals ..... 12
5-4 USB Interface Signals ..... 13
5-5 Serial Peripheral Interface (SPI) Signals ..... 13
5-6 JTAG, GPIO, and PWM Signals ..... 14
5-7 Power and Ground Signals ..... 15
6-1 Oscillator Specification ..... 17
6-2 Crystal Specification ..... 17
8-1 SuperSpeed USB Power Consumption ..... 20
8-2 High Speed USB Power Consumption ..... 20


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# USB 3.0 TO SATA BRIDGE

**Check for Samples: TUSB9261**

## 1 MAIN FEATURES

### 1.1 TUSB9261 Features

- Universal Serial Bus (USB)
  - SuperSpeed USB 3.0 Compliant - TID 340730020
    - Integrated Transceiver Supports SS/HS/FS Signaling
  - Best in Class Adaptive Equalizer
    - Allows for Greater Jitter Tolerance in the Receiver
  - USB Class Support
    - USB Attached SCSI Protocol (UASP)
    - USB Mass Storage Class Bulk-Only Transport (BOT)
    - Support for Error Conditions Per the 13 Cases (Defined in the BOT Specification)
    - USB Bootability Support
    - USB Human Interface Device (HID)
  - Supports Firmware Update Via USB, Using a TI Provided Application
- SATA Interface
  - Serial ATA Specification Revision 2.6
    - gen1i, gen1m, gen2i, and gen2m
  - Support for Mass-Storage Devices Compatible With the ATA/ATAPI-8 Specification
- Integrated ARM Cortex M3 Core
  - Customizable Application Code Loaded From EEPROM Via SPI Interface
  - Two Additional SPI Port Chip Selects for Peripheral Connection
  - Up to 12 GPIOs for End-User Configuration
    - 2 GPIOs Have PWM Functionality for LED Blink Speed Control
  - Serial Communications Interface for Debug (UART)
- General Features
  - Integrated Spread Spectrum Clock Generation Enables Operation from a Single Low Cost Crystal or Clock Oscillator
    - Supports 20, 25, 30 or 40 MHz
  - A JTAG Interface is Used for IEEE1149.1 and IEEE1149.6 Boundary Scan
  - Available in a Fully RoHS Compliant Package

### 1.2 Target Applications

- External HDD/SSD
- External DVD
- External CD
- HDD-Based Portable Media Player

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# 2 RELATED DOCUMENTS

## 2.1 TUSB9261 Related Documentation

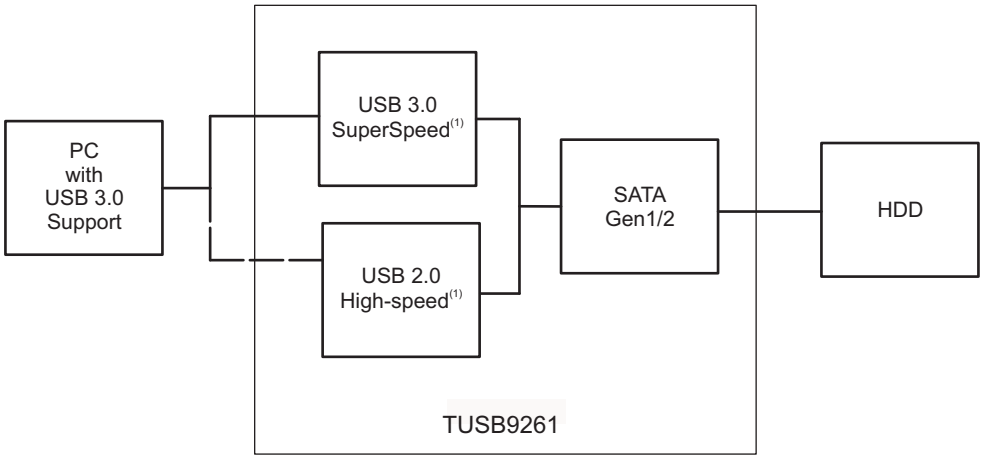
1. TUSB9260 Implementation Guide (SLLA301)
2. TUSB9260/TUSB9261 Flash Burner User Guide (SLLU125)


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# 3 INTRODUCTION

## 3.1 System Overview

The TUSB9261 is an ARM cortex M3 microcontroller based USB 3.0 to serial ATA bridge. It provides the necessary hardware and firmware to implement a USB attached SCSI protocol (UASP) compliant mass storage device suitable for bridging hard disk drives (HDD), solid state disk drives (SSD), optical drives and other compatible SATA 1.5-Gbps or SATA 3.0-Gbps devices to a USB 3.0 bus. In addition to UASP support, the firmware implements the mass storage class bulk-only transport (BOT), and USB human interface device (HID) interfaces.




(1) USB connection is made at either SuperSpeed or High-Speed depending on the upstream connection support.

## 3.2 Device Block Diagram

The major functional blocks are as follows:

- Cortex M3 microcontroller subsystem including the following peripherals:
  - Time interrupt modules, including watchdog timer
  - Universal asynchronous receive/transmit (SCI)
  - Serial peripheral interface (SPI)
  - General purpose input/output (GPIO)
  - PWM for support of PWM outputs (PWM)
- USB 3.0 Core (endpoint controller) and integrated USB 3.0 PHY
- AHCI compliant SATA controller and integrated SATA PHY
  - Supporting gen1i, gen1m, gen2i, and gen2m
- Chip level clock generation and distribution
- Support for JTAG 1149.1 and 1149.6

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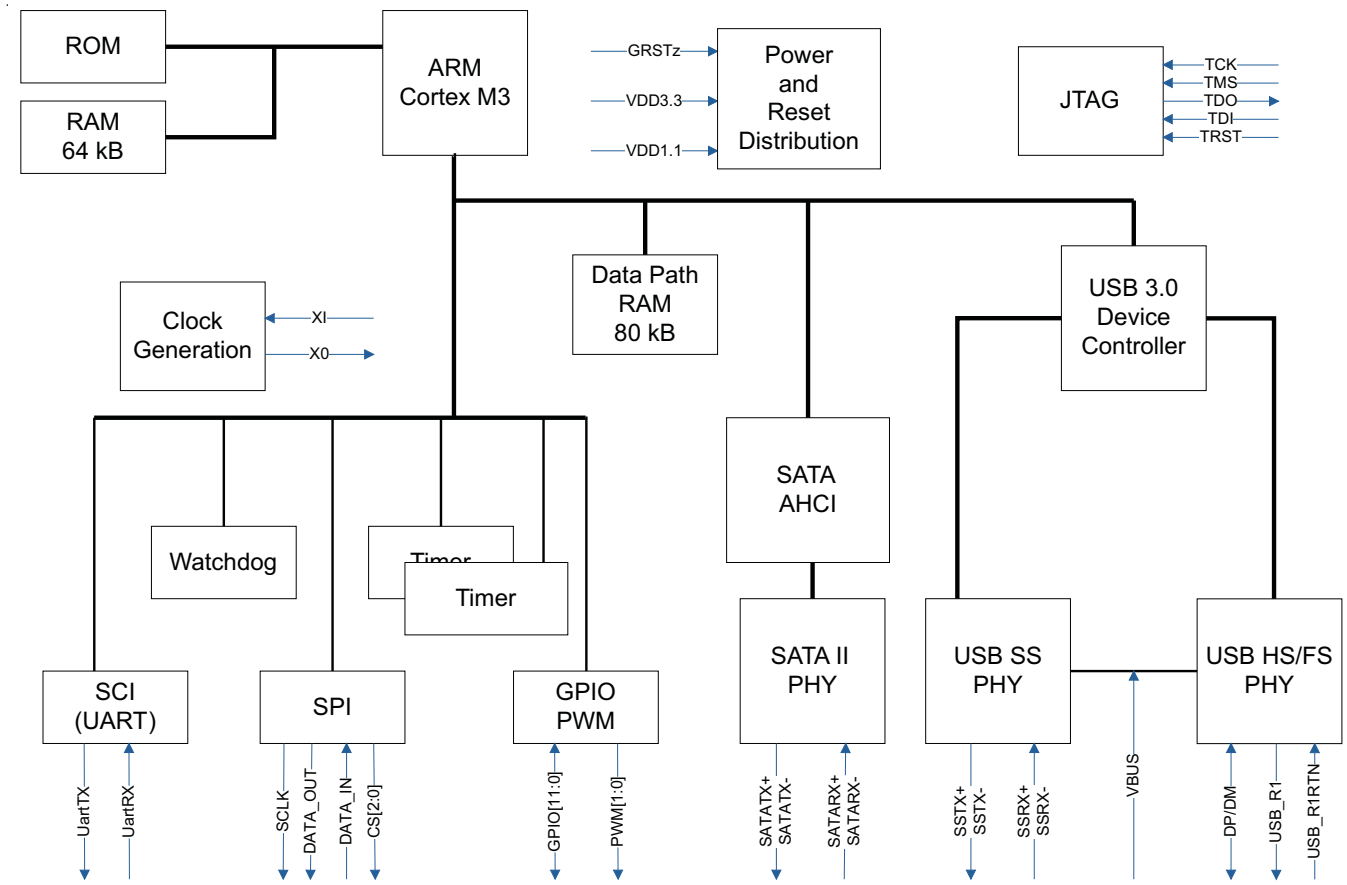



**Figure 3-1. Device Block Diagram**


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# 4 OPERATION

## 4.1 General Functionality

The TUSB9261 ROM contains boot code that executes after a global reset which performs the initial configuration required to load a firmware image from an attached SPI flash memory to local RAM. In the absence of an attached SPI flash memory or a valid image in the SPI flash memory, the firmware will idle and wait for a connection from a USB host through its HID interface which is also configured from the boot code. The latter can be accomplished using a custom application or driver to load the firmware from a file resident on the host system.

Once the firmware is loaded it configures the SATA advanced host controller interface host bus adapter (AHCI) and the USB device controller. In addition, the configuration of the AHCI includes a port reset which initiates an out of band (OOB) TX sequence from the AHCI link layer to determine if a device is connected, and if so negotiate the connection speed with the device (3.0 Gbps or 1.5 Gbps).

The configuration of the USB device controller includes creation of the descriptors, configuration of the device endpoints for support of UASP and USB mass storage class bulk-only transport (BOT), allocation of memory for the transmit request blocks (TRBs), and creation of the TRBs necessary to transmit and receive packet data over the USB. In addition, the firmware provides any other custom configuration required for application specific implementation, for example a HID interface for user initiated backup.

After USB device controller configuration is complete, if a SATA device was detected during the AHCI configuration the firmware connects the device to the USB bus when VBUS is detected. According to the USB 3.0 specification, the TUSB9261 will initially try to connect at SuperSpeed USB, if successful it will enter U0; otherwise, after the training time out it will enable the DP pull up and connect as a USB 2.0 high-speed or full-speed device depending on the speed supported by host or hub port.

When connected, the firmware presents the BOT interface as the primary interface and the UASP interface as the secondary interface. If the host stack is UASP aware, it can enable the UASP interface using a SET_INTERFACE request for alternate interface 1.

Following speed negotiation, the device should transmit a device to host (D2H) FIS with the device signature. This first D2H FIS is received by the link layer and copied to the port signature register. When firmware is notified of the device connection it queries the device for capabilities using the IDENTIFY DEVICE command. Firmware then configures the device as appropriate for its interface and features supported, for example an HDD that supports native command queuing (NCQ).

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## 4.2 Firmware Support

Default firmware support is provided for the following:

- SuperSpeed USB and USB 2.0 High-Speed and Full-Speed
- USB Attached SCSI Protocol (UASP)
- USB Mass Storage Class (MSC) Bulk-Only Transport (BOT)
  - Including the 13 Error Cases
- USB Mass Storage Specification for Bootability
- USB Device Class Definition for Human Interface Devices (HID)
  - Firmware Update and Custom Functionality (e.g. One-Touch Backup)
- Serial ATA Advanced Host Controller Interface (AHCI)
- General Purpose Input/Output (GPIO)
  - LED Control and Custom Functions (e.g. One-Touch Backup Control)
- Pulse Width Modulation (PWM)
  - LED Dimming Control
- Serial Peripheral Interface (SPI)
  - Firmware storage and storing Custom Device Descriptors
- Serial Communications Interface (SCI)
  - Debug Output Only

## 4.3 GPIO/PWM LED Designations

The default firmware provided by TI drives the GPIO and PWM outputs as listed in the table below.

**Table 4-1. GPIO/PWM LED Designations**

| | | |
|---|---|---|
| GPIO0 | SW heartbeat | |
| GPIO1/GPIO5 | USB3 power state (U0-U3) | 00: U3 state or default<br>01: U2 state<br>10: U1 state<br>11: U0 state |
| GPIO2 | HS/FS suspend | |
| GPIO3 | Push button input on customer board | |
| GPIO4 | Not used | |
| GPIO6 | FS/HS connected | |
| GPIO7 | SS connected | |
| PWM0 | Disk activity | |
| PWM1 | U3 or HS/FS suspend state (fades high and low) | |
| GPIO10 (SPICS1) | Not used | |
| GPIO11 (SPICS2) | Not used | |

The LED's on the TUSB9261 Product Development Kit (PDK) board are connected as in the table above. Please see the TUSB9261 PDK Guide for more information on GPIO LED connection and usage. This EVM is available for purchase, contact TI for ordering information.


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## 4.4 Power Up and Reset Sequence

The TUSB9261 does not have specific power sequencing requirements with respect to the core power (VDD), I/O power (VDD33), or analog power (VDDA33). The core power (VDD) or IO power (VDD33) may be powered up for an indefinite period of time while others are not powered up if all of these constraints are met:

- All maximum ratings and recommended operating conditions are observed.
- All warnings about exposure to maximum rated and recommended conditions are observed, par-ticularly junction temperature. These apply to power transitions as well as normal operation.
- Bus contention while VDD33 is powered up must be limited to 100 hours over the projected life-time of the device.
- Bus contention while VDD33 is powered down may violate the absolute maximum ratings.

A supply bus is powered up when the voltage is within the recommended operating range. It is powered down when it is below that range, either stable or in transition.

A minimum reset duration of 1 ms is required. This is defined as the time when the power supplies are in the recommended operating range to the de-assertion of GRSTz.

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# 5 SIGNAL DESCRIPTIONS

**Table 5-1. I/O Definitions**

| I/O TYPE | DESCRIPTION |
|---|---|
| I | Input |
| O | Output |
| I/O | Input - Output |
| PU | Internal pull-up resistor |
| PD | Internal pull-down resistor |
| PWR | Power signal |

**Table 5-2. Clock and Reset Signals**

| TERMINAL | | I/O | DESCRIPTION | | |
|---|---|---|---|---|---|
| NAME | PIN NO. | | | | |
| GRSTz | 4 | I PU | Global power reset. This reset brings all of the TUSB9261 internal registers to their default states. When GRSTz is asserted, the device is completely nonfunctional. | | |
| XI | 52 | I | Crystal input. This terminal is the crystal input for the internal oscillator. The input may alternately be driven by the output of an external oscillator. When using a crystal a 1-MΩ feedback resistor is required between X1 and XO. | | |
| XO | 54 | O | Crystal output. This terminal is the crystal output for the internal oscillator. If XI is driven by an external oscillator this pin may be left unconnected. When using a crystal a 1-MΩ feedback resistor is required between X1 and XO. | | |
| FREQSEL[1:0] | 31, 30 | I PU | Frequency select. These terminals indicate the oscillator input frequency and are used to configure the correct PLL multiplier. The field encoding is as follows: | | |
| | | | **FREQSEL[1]** | **FREQSEL[0]** | **INPUT CLOCK FREQUENCY** |
| | | | 0 | 0 | 20 MHz |
| | | | 0 | 1 | 25 MHz |
| | | | 1 | 0 | 30 MHz |
| | | | 1 | 1 | 40 MHz |

**Table 5-3. SATA Interface Signals(1)**

| TERMINAL | | I/O | DESCRIPTION |
|---|---|---|---|
| NAME | PIN NO. | | |
| SATA_TXP | 57 | O | Serial ATA transmitter differential pair (positive) |
| SATA_TXM | 56 | O | Serial ATA transmitter differential pair (negative) |
| SATA_RXP | 60 | I | Serial ATA receiver differential pair (positive) |
| SATA_RXM | 59 | I | Serial ATA receiver differential pair (negative) |

(1) Note that the default firmware and reference design for the TUSB9261 have the SATA TXP/TXM swapped for ease of routing in the reference design. If you plan to use the TI default firmware please review the reference design in the TUSB9261 DEMO User's Guide (SLLU139) for proper SATA connection.


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### Table 5-4. USB Interface Signals

| TERMINAL | | I/O | DESCRIPTION |
|---|---|---|---|
| NAME | PIN NO. | | |
| USB_SSTXP | 43 | O | SuperSpeed USB transmitter differential pair (positive) |
| USB_SSTXM | 42 | O | SuperSpeed USB transmitter differential pair (negative) |
| USB_SSRXP | 46 | I | SuperSpeed USB receiver differential pair (positive) |
| USB_SSRXM | 45 | I | SuperSpeed USB receiver differential pair (negative) |
| USB_DP | 36 | I/O | USB High-speed differential transceiver (positive) |
| USB_DM | 35 | I/O | USB High-speed differential transceiver (negative) |
| USB_VBUS | 50 | I | USB bus power |
| USB_R1 | 38 | O | Precision resistor reference. A 10-kΩ ±1% resistor should be connected between R1 and R1RTN. |
| USB_R1RTN | 39 | I | Precision resistor reference return |

### Table 5-5. Serial Peripheral Interface (SPI) Signals

| TERMINAL | | I/O | DESCRIPTION |
|---|---|---|---|
| NAME | PIN NO. | | |
| SPI_SCLK | 17 | O PU | SPI clock |
| SPI_DATA_OUT | 18 | O PU | SPI master data out |
| SPI_DATA_IN | 20 | I PU | SPI master data in |
| SPI_CS0 | 21 | O PU | Primary SPI chip select for Flash RAM |
| SPI_CS2/ GPIO11 | 23 | I/O PU | SPI chip select for additional peripherals. When not used for SPI chip select this pin may be used as general purpose I/O. |
| SPI_CS1/ GPIO10 | 22 | I/O PU | SPI chip select for additional peripherals. When not used for SPI chip select this pin may be used as general purpose I/O. |

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**Table 5-6. JTAG, GPIO, and PWM Signals**

| TERMINAL NAME | PIN NO. | I/O | DESCRIPTION |
|---|---|---|---|
| JTAG_TCK | 25 | I PD | JTAG test clock |
| JTAG_TDI | 26 | I PU | JTAG test data in |
| JTAG_TDO | 27 | O PD | JTAG test data out |
| JTAG_TMS | 28 | I PU | JTAG test mode select |
| JTAG_TRSTz | 29 | I PD | JTAG test reset |
| GPIO9/UART_TX | 6 | I/O PU | GPIO/UART transmitter. This terminal can be configured as a GPIO or as the transmitter for a UART channel. This pin defaults to a general purpose output. |
| GPIO8/UART_RX | 5 | I/O PU | GPIO/UART receiver. This terminal can be configured as a GPIO or as the receiver for a UART channel. This pin defaults to a general purpose output. |
| GPIO7 | 16 | I/O PD | Configurable as general purpose input/outputs |
| GPIO6 | 15 | I/O PD | |
| GPIO5 | 14 | I/O PD | |
| GPIO4 | 13 | I/O PD | |
| GPIO3 | 11 | I/O PD | |
| GPIO2 | 10 | I/O PD | |
| GPIO1 | 9 | I/O PD | |
| GPIO0 | 8 | I/O PD | |
| PWM0 | 2 | O PD(1) | Pulse Width Modulation (PWM). Can be used to drive status LED's. |
| PWM1 | 3 | O PD(1) | |

(1) PWM pull down resistors are disabled by default. A firmware modification is required to turn them on. All other internal pull up/down resistors are enabled by default.


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**Table 5-7. Power and Ground Signals**

| TERMINAL | | I/O | DESCRIPTION |
|---|---|---|---|
| NAME | PIN NO. | | |
| VDD | 1, 12, 19, 32, 33, 41, 47, 49, 55, 61, 63 | PWR | 1.1-V power rail |
| VDD33 | 7, 24, 51 | PWR | 3.3-V power rail |
| VDDA33 | 34, 40, 48, 62 | PWR | 3.3-V analog power rail |
| VSSOSC | 53 | PWR | Oscillator ground. If using a crystal, this should not be connected to PCB ground plane. If using an oscillator, this should be connected to PCB ground. See the Clock Source Requirements section for more details. |
| VSS | 44, 58 | PWR | Ground |
| VSS | 65 | PWR | Ground - Thermal Pad |
| NC | 37, 64 | — | No connect, leave floating |

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# 6 CLOCK CONNECTIONS

## 6.1 Clock Source Requirements

The TUSB9261 supports an external oscillator source or a crystal unit. If a clock is provided to XI instead of a crystal, XO is left open and VSSOSC should be connected to the PCB ground plane. Otherwise, if a crystal is used, the connection needs to follow the guidelines below.

Since XI and XO are coupled to other leads and supplies on the PCB, it is important to keep them as short as possible and away from any switching leads. It is also recommended to minimize the capacitance be-tween XI and XO. This can be accomplished by connecting the VSSOSC lead to the two external capaci-tors CL1 and CL2 and shielding them with the clean ground lines. The VSSOSC should not be connected to PCB ground when using a crystal.

Load capacitance ($C_{load}$) of the crystal varying with the crystal vendors is the total capacitance value of the entire oscillation circuit system as seen from the crystal. It includes two external capacitors CL1 and CL2 in Figure 6-1. The trace length between the decoupling capacitors and the corresponding power pins on the TUSB9261 needs to be minimized. It is also recommended that the trace length from the capacitor pad to the power or ground plane be minimized.

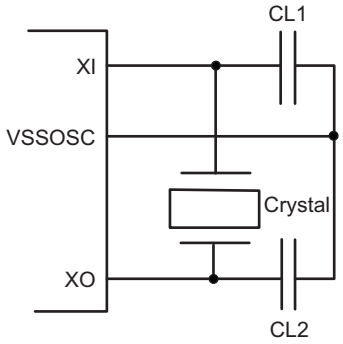



**Figure 6-1. Typical Crystal Connections**

## 6.2 Clock Source Selection Guide

Reference clock jitter is an important parameter. Jitter on the reference clock will degrade both the trans-mit eye and receiver jitter tolerance no matter how clean the rest of the PLL is, thereby impairing system performance. Additionally, a particularly jittery reference clock may interfere with PLL lock detection mechanism, forcing the Lock Detector to issue an Unlock signal. A good quality, low jitter reference clock is required to achieve compliance with supported USB3.0 standards. For example, USB3.0 specification requires the random jitter (RJ) component of either RX or TX to be 2.42 ps (random phase jitter calculated after applying jitter transfer function - JTF). As the PLL typically has a number of additional jitter components, the Reference Clock jitter must be considerably below the overall jitter budget.


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## 6.3 Oscillator

XI should be tied to the 1.8-V clock source and XO should be left floating.

VSSOSC should be connected to the PCB ground plane.

A 20-, 25-, 30- or 40-MHz clock can be used.

**Table 6-1. Oscillator Specification**

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|---|---|---|---|---|
| $C_{XI}$ | XI input capacitance | $T_J$ = 25°C | | 0.414 | | pF |
| $V_{IL}$ | Low-level input voltage | | | | 0.7 | V |
| $V_{IH}$ | High-level input voltage | | 1.05 | | | V |
| $T_{tosc_i}$ | Frequency tolerance | Operational temperature | –50 | | 50 | ppm |
| $T_{duty}$ | Duty cycle | | 45 | 50 | 55 | % |
| $T_R/T_F$ | Rise/Fall time | 20% - 80 % | | | 6 | ns |
| $R_J$ | Reference clock $R_J$ | JTF (1 sigma)(1)(2) | | | 0.8 | ps |
| $T_J$ | Reference clock $T_J$ | JTF (total p-p)(2)(3) | | | 25 | ps |
| $T_{p-p}$ | Reference clock jitter | (absolute p-p)(4) | | | 50 | ps |

(1) Sigma value assuming Gaussian distribution
(2) After application of JTF
(3) Calculated as 14.1 x $R_J$ + $D_J$
(4) Absolute phase jitter (p-p)

## 6.4 Crystal

A parallel, 20-pF load capacitor should be used if a crystal source is used.

VSSOSC should not be connected to the PCB ground plane.

A 20-, 25-, 30- or 40-MHz crystal can be used.

**Table 6-2. Crystal Specification**

| PARAMETER | | CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|---|---|---|---|---|
| | Oscillation mode | | Fundamental | | | |
| $f_O$ | Oscillation frequency | | | 20 | | MHz |
| | | | | 25 | | |
| | | | | 30 | | |
| | | | | 40 | | |
| ESR | Equivalent series resistance | 20 MHz and 25 MHz | | | 50 | Ω |
| | | 30 MHz | | | 40 | |
| | | 40 MHz | | | 30 | |
| $T_{tosc_i}$ | Frequency tolerance | Operational temperature | | | ±50 | ppm |
| | Frequency stability | 1 year aging | | | ±50 | ppm |
| $C_L$ | Load capacitance | | 12 | 20 | 24 | pF |
| $C_{SHUNT}$ | Crystal and board stray capacitance | | | | 4.5 | pF |
| | Drive level (max) | | | | 0.8 | mW |

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# 7 ELECTRICAL SPECIFICATIONS

## 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)

| | | VALUE | UNIT |
|---|---|---|---|
| VDD | Steady-state supply voltage | –0.3 to 1.4 | V |
| VDD33/ VDDA33 | Steady-state supply voltage | –0.3 to 3.8 | V |

## 7.2 Thermal Information

| THERMAL METRIC | | TUSB9261 PVP 64 PINS | UNITS |
|---|---|---|---|
| $\theta_{JA}$ | Junction-to-ambient thermal resistance(1) | 30.2 | °C/W |
| $\theta_{JCtop}$ | Junction-to-case (top) thermal resistance(2) | 11.0 | |
| $\theta_{JB}$ | Junction-to-board thermal resistance(3) | 6.1 | |
| $\psi_{JT}$ | Junction-to-top characterization parameter(4) | 0.4 | |
| $\psi_{JB}$ | Junction-to-board characterization parameter(5) | 6.1 | |
| $\theta_{JCbot}$ | Junction-to-case (bottom) thermal resistance(6) | 0.9 | |

(1) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
(2) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDEC-standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
(3) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
(4) The junction-to-top characterization parameter, $\psi_{JT}$, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining $\theta_{JA}$, using a procedure described in JESD51-2a (sections 6 and 7).
(5) The junction-to-board characterization parameter, $\psi_{JB}$, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).
(6) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | MIN | NOM | MAX | UNIT |
|---|---|---|---|---|---|
| VDD | Digital 1.1 supply voltage | 1.045 | 1.1 | 1.155 | V |
| VDD33 | Digital 3.3 supply voltage | 3 | 3.3 | 3.6 | V |
| VDDA33 | Analog 3.3 supply voltage | 3 | 3.3 | 3.6 | V |
| VBUS | Voltage at VBUS PAD | 0 | | 1.155 | V |
| $T_A$ | Operating free-air temperature range | -40 | | 85 | °C |
| $T_J$ | Operating junction temperature range | -40 | | 100 | °C |
| | HBM ESD | | | 2000 | V |
| | CDM ESD | | | 500 | V |


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## 7.4 DC Electrical Characteristics for 3.3-V Digital I/O

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---|---|---|---|---|---|---|
| **DRIVER** | | | | | | |
| $T_R$ | Rise time | 5 pF | | | 1.5 | ns |
| $T_F$ | Fall time | 5 pF | | | 1.53 | ns |
| $I_{OL}$ | Low-level output current | VDD33 = 3.3 V, $T_J$ = 25°C | | 6 | | mA |
| $I_{OH}$ | High-level output current | VDD33 = 3.3 V, $T_J$ = 25°C | | –6 | | mA |
| $V_{OL}$ | Low-level output voltage | $I_{OL}$ = 2 mA | | | 0.4 | V |
| $V_{OH}$ | High-level output voltage | $I_{OL}$ = –2 mA | 2.4 | | | V |
| $V_O$ | Output voltage | | 0 | | VDD33 | V |
| **RECEIVER** | | | | | | |
| $V_I$ | Input voltage | | 0 | | VDD33 | V |
| $V_{IL}$ | Low-level input voltage | | 0 | | 0.8 | V |
| $V_{IH}$ | High-level input voltage | | 2 | | | V |
| $V_{hys}$ | Input hysteresis | | 200 | | | mV |
| $t_T$ | Input transition time ($T_R$ and $T_F$) | | | | 10 | ns |
| $I_I$ | Input current | $V_I$ = 0 V to VDD33 | | | 5 | µA |
| $C_I$ | Input capacitance | VDD33 = 3.3 V, $T_J$ = 25°C | | 0.384 | | pF |

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# 8 POWER CONSUMPTION

**Table 8-1. SuperSpeed USB Power Consumption**

| POWER RAIL | TYPICAL ACTIVE CURRENT (mA)(1) | TYPICAL SUSPEND CURRENT (mA)(2) |
|---|---|---|
| VDD11 | 291 | 153 |
| VDD33(3) | 65 | 28 |

(1) Transferring data via SS USB to a SSD SATA Gen II device. No SATA power management, U0 only.
(2) SATA Gen II SSD attached no active transfer. No SATA power management, U0 only.
(3) All 3.3-V power rails connected together.

**Table 8-2. High Speed USB Power Consumption**

| POWER RAIL | TYPICAL ACTIVE CURRENT (mA)(1) | TYPICAL SUSPEND CURRENT (mA)(2) |
|---|---|---|
| VDD11 | 172 | 153 |
| VDD33(3) | 56 | 28 |

(1) Transferring data via HS USB to a SSD SATA Gen II device. No SATA power management.
(2) SATA Gen II SSD attached no active transfer. No SATA power management.
(3) All 3.3-V power rails connected together.


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## PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan (2) | Lead/ Ball Finish | MSL Peak Temp (3) | Samples (Requires Login) |
|---|---|---|---|---|---|---|---|---|---|
| TUSB9261PVP | ACTIVE | HTQFP | PVP | 64 | 250 | Green (RoHS & no Sb/Br) | CU NIPDAUAG | Level-4-260C-72 HR | |

(1) The marketing status values are defined as follows:
**ACTIVE:** Product device recommended for new designs.
**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.
**OBSOLETE:** TI has discontinued the production of the device.

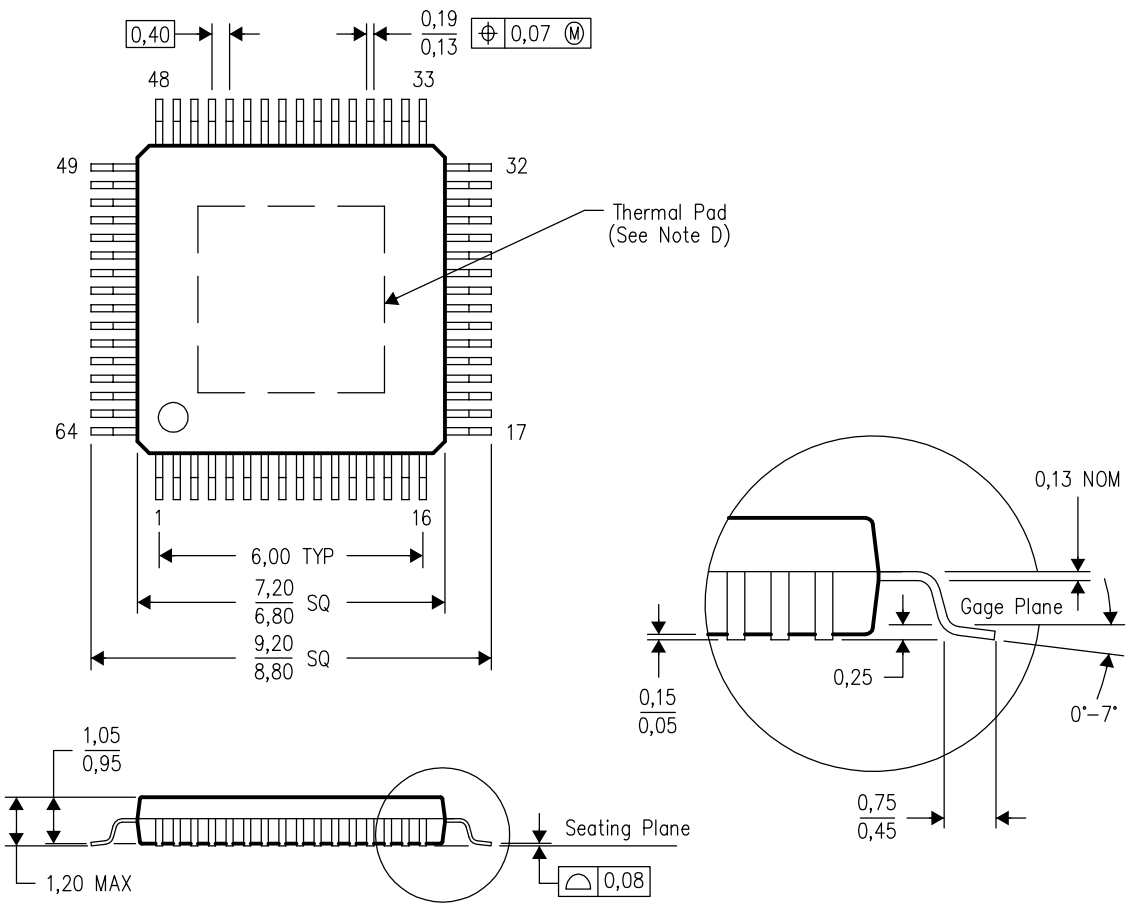
(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
**TBD:** The Pb-Free/Green conversion plan has not been defined.
**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.
**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## PVP (S–PQFP–G64) PowerPAD™ PLASTIC QUAD FLATPACK




NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion
D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <http://www.ti.com>.
E. Falls within JEDEC MS–026

**PowerPAD is a trademark of Texas Instruments.**

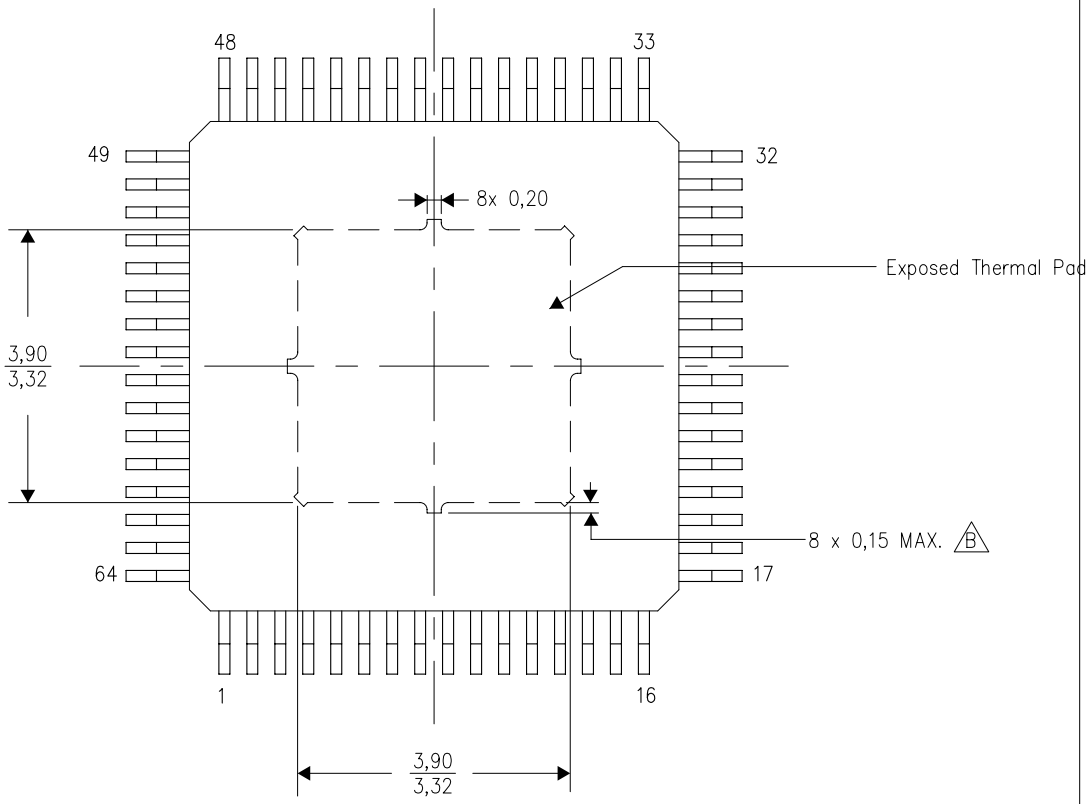
PVP (S–PQFP–G64) PowerPAD™ PLASTIC QUAD FLATPACK

THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.




Top View

Exposed Thermal Pad Dimensions

4211213/B 09/10

NOTES: A. All linear dimensions are in millimeters

B. Exposed tie strap features may not be present.

PowerPAD is a trademark of Texas Instruments.

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