

Three Phase AC Controller Modules

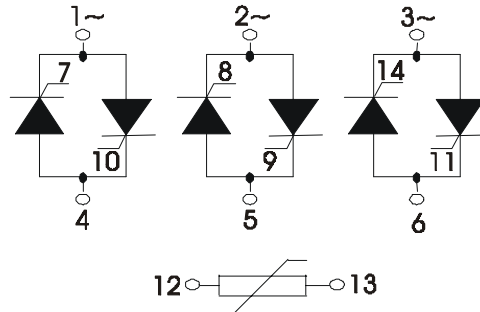
PSUT 145

I_{RMS}
 V_{RRM}

= 3 x 145A
= 800-1600 V

Preliminary Data Sheet

V_{RSM} V_{DSM}	V_{RRM} V_{DRM}	Type
900	800	PSUT 145/08
1300	1200	PSUT 145/12
1500	1400	PSUT 145/14
1700	1600	PSUT 145/16



Symbol	Test Conditions		Maximum Ratings	
I_{RMS}	$T_C = 85^\circ C$		145	A
	$T_C = 75^\circ C$		170	A
I_{TAVM}	$T_{VJ} = T_{VJM}$		120	A
I_{TSM}	$T_{VJ} = 25^\circ C$	$t = 10\text{ ms}$ (50 Hz), sine	1250	A
		$t = 8.3\text{ ms}$ (60 Hz), sine	1370	A
	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$ (50 Hz), sine	1050	A
		$t = 8.3\text{ ms}$ (60 Hz), sine	1150	A
$\int i^2 dt$	$T_{VJ} = 25^\circ C$	$t = 10\text{ ms}$ (50 Hz), sine	7800	$A^2 s$
		$t = 8.3\text{ ms}$ (60 Hz), sine	9380	$A^2 s$
	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$ (50 Hz), sine	4575	$A^2 s$
		$t = 8.3\text{ ms}$ (60 Hz), sine	5480	$A^2 s$
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50\text{ Hz}$ $I_G = 0.6\text{ A}$ $di_G/dt = 0.6\text{ A}/\mu s$		120	$A/\mu s$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $R_{GK} = \infty$, method 1 (linear voltage rise)	$V_{DR} = 0.67 V_{DRM}$	1000	$V/\mu s$
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_P = 30\mu s$	10	W
		$t_P = 300\mu s$	5	W
P_{GAVM}			0.5	W
V_{RGM}			10	V
T_{VJ}			-40 ... + 125	$^\circ C$
T_{VJM}			125	$^\circ C$
T_{stg}			-40 ... + 130	$^\circ C$
V_{ISOL}	50/60 HZ, RMS	$t = 1\text{ min}$	3000	V ~
	$I_{ISOL} \leq 1\text{ mA}$	$t = 1\text{ s}$	3600	V ~
M_d	Mounting torque	M6	6	Nm
	Terminal connection torque	M6	6	Nm
Weight	typ.		290	g

Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glasspassivated chips
- Package with metal base plate
- UL registered E 148688

Applications

- Switching and control of three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

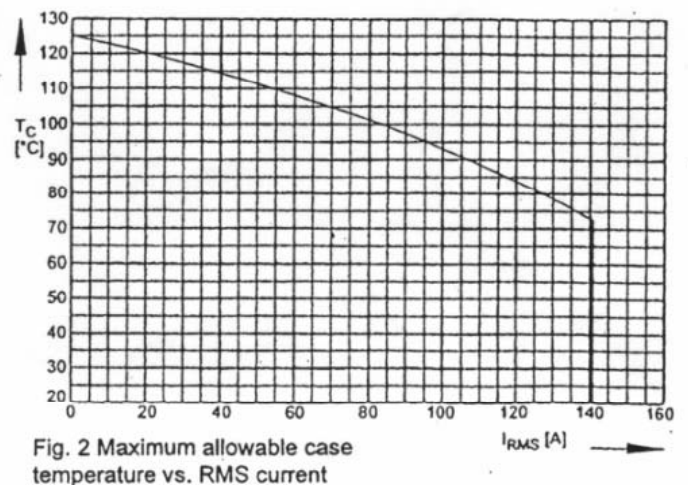
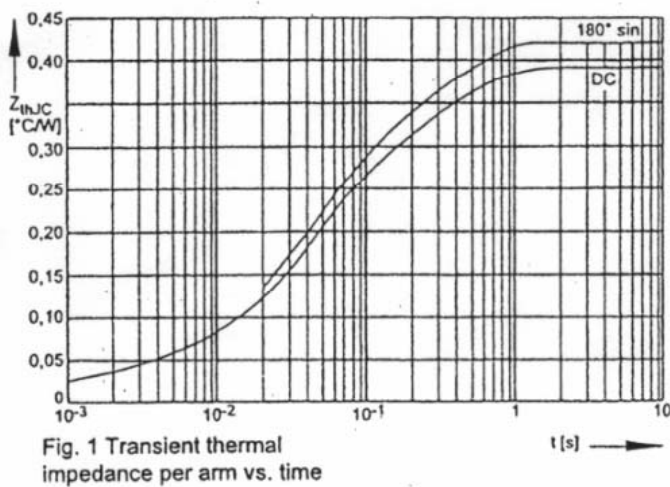
Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density

Symbol	Test Conditions	Characteristic Value
I_D, I_R	$T_{VJ} = T_{VJM}, V_R = V_{RRM}, V_D = V_{DRM}$	≤ 10 mA
V_T	$I_T = 200A, T_{VJ} = T_{VJM}$	≤ 1.87 V
V_{TO}	For power-loss calculations only ($T_{VJ} = T_{VJM}$)	0.95 V
r_T		3.2 m Ω
V_{GT}	$V_D = 6V, T_{VJ} = 25^\circ C$	≤ 2.5 V
I_{GT}	$V_D = 6V, T_{VJ} = 25^\circ C$	≤ 150 mA
V_{GD}	$T_{VJ} = T_{VJM}, V_D = 0,5 V_{DRM}$	≤ 0.2 V
I_{GD}	$T_{VJ} = T_{VJM}, V_D = 6 V$	≤ 5 mA
I_L	$T_{VJ} = 25^\circ C, t_p = 10\mu s$ $I_G = 0.6A, di_G/dt = 0.6A/\mu s$	≤ 600 mA
I_H	$T_{VJ} = 25^\circ C, V_D = 6V, R_A = 5\Omega$	≤ 200 mA
t_{gd}	$T_{VJ} = 25^\circ C,$ $I_G = 0.6A, di_G/dt = 0.6A/\mu s$	≤ 1.2 μs
t_q	$T_{VJ} = T_{VJM}, I_T = 50A, t_p = 200\mu s, V_R = 100V$ $-di/dt = 10A/\mu s, dv/dt = 20V/\mu s, V_D = 2/3 V_{DRM}$	190 μs
R_{thJC}	per thyristor; sine 180° el per module; sine 180° el	0.42 K/W 0.07 K/W
R_{thJK}	per thyristor per module	0.62 K/W 0.11 K/W
d_s	Creeping distance on surface	12.5 mm
a	Max. allowable acceleration	50 m/s ²

Temperature sensor

R_{25}	Rated resistance, $T_c = 25^\circ C$	5 k Ω
		$R_{100} = 493\Omega$
P_{25}	Power dissipation, $T_c = 25^\circ C$	max. 20 mW



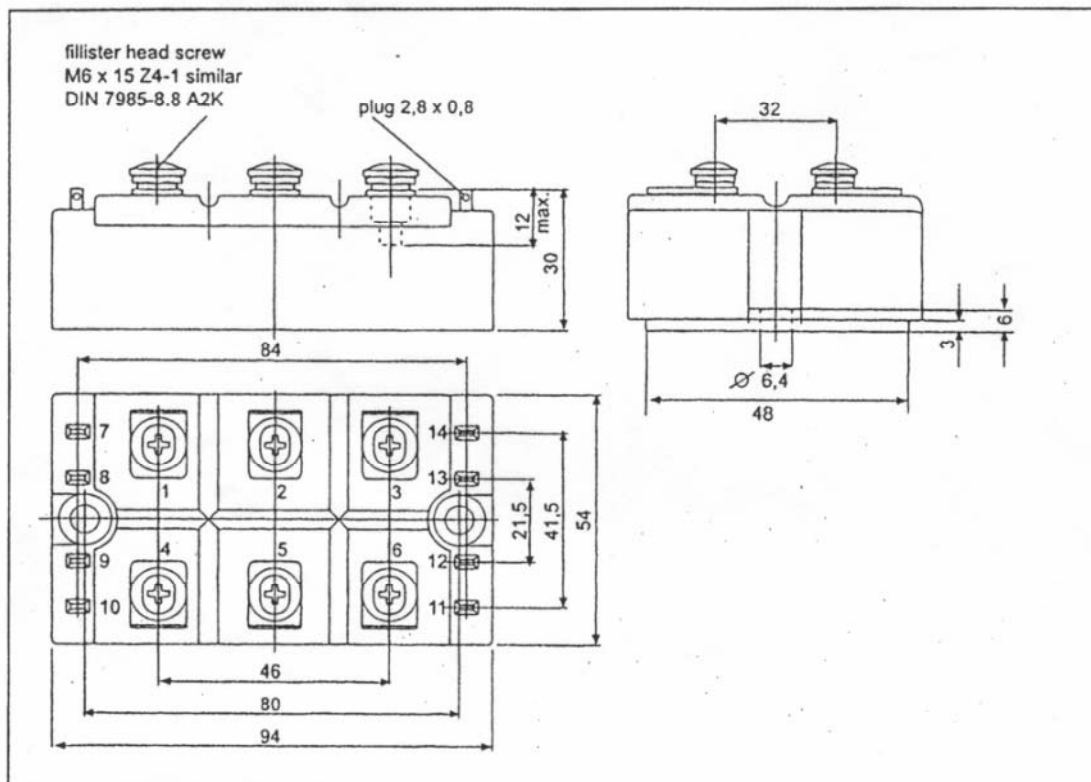


Fig. 5 Package style and outline