32Mb LW R-R HSTL High Speed Synchronous SRAM (2Mb x 18)

**Preliminary** 

### **Description**

The CXK77K18R320GB is a high speed CMOS synchronous static RAM with common I/O pins, organized as 2,097,152 words by 18 bits. This synchronous SRAMs integrates input registers, high speed RAM, output registers, and a one-deep write buffer onto a single monolithic IC. Register - Register (R-R) read operations and Late Write (LW) write operations are supported, providing a high-performance user interface.

All address and control input signals except  $\overline{G}$  (Output Enable) and ZZ (Sleep Mode) are registered on the rising edge of the K differential input clock.

During read operations, output data is driven valid from the rising edge of K, one full clock cycle after the address is registered.

During write operations, input data is registered on the rising edge of K, one full clock cycle after the address is registered.

Sleep (power down) capability is provided via the ZZ input signal.

Output drivers are series terminated, and output impedance is programmable via the ZQ input pin. By connecting an external control resistor RQ between ZQ and  $V_{SS}$ , the impedance of the output drivers can be precisely controlled.

333 MHz operation is obtained from a single 1.8V power supply. JTAG boundary scan interface is provided using a subset of IEEE standard 1149.1 protocol.

#### **Features**

•	3 Speed Bins	Cycle Time / Access Time
	-3	3.0ns / 1.6ns
	-33	3.3ns / 1.6ns
	-4	4.0ns / 2.0ns

• Single 1.8V power supply  $(V_{DD})$ : 1.8V  $\pm$  0.1V

Note: 2.5V V<sub>DD</sub> is also supported. Please contact Sony Memory Marketing Department for further information.

- Dedicated output supply voltage (V<sub>DDO</sub>): 1.5V to 1.8V typical
- HSTL-compatible I/O interface with dedicated input reference voltage (V<sub>REF</sub>): V<sub>DDO</sub>/2 typical
- Register Register (R-R) read protocol
- Late Write (LW) write protocol
- Full read/write coherency
- · Byte Write capability
- Differential input clocks  $(K/\overline{K})$
- Asynchronous output enable  $(\overline{G})$
- Sleep (power down) mode via dedicated mode pin (ZZ)
- Programmable output driver impedance
- JTAG boundary scan (subset of IEEE standard 1149.1)
- 119 pin (7x17), 1.27mm pitch, 14mm x 22mm Ball Grid Array (BGA) package

# 2Mb x 18 Pin Assignment (Top View)

	1	2	3	4	5	6	7
A	$V_{DDQ}$	SA	SA	NC	SA	SA	$V_{\mathrm{DDQ}}$
В	NC	SA	SA	SA (32M)	SA	SA	NC
C	NC	SA	SA	V <sub>DD</sub>	SA	SA	NC
D	DQb	NC	V <sub>SS</sub>	ZQ	V <sub>SS</sub>	DQa	NC
E	NC	DQb	V <sub>SS</sub>	SS	V <sub>SS</sub>	NC	DQa
F	$V_{DDQ}$	NC	$V_{SS}$	$\overline{\mathrm{G}}$	V <sub>SS</sub>	DQa	$V_{\mathrm{DDQ}}$
G	NC	DQb	SBWb	NC	V <sub>SS</sub>	NC	DQa
Н	DQb	NC	$V_{SS}$	NC	$V_{SS}$	DQa	NC
J	$V_{DDQ}$	$V_{DD}$	$V_{REF}$	$V_{DD}$	V <sub>REF</sub>	$V_{DD}$	$V_{\mathrm{DDQ}}$
K	NC	DQb	$V_{SS}$	K	$V_{SS}$	NC	DQa
L	DQb	NC	$V_{SS}$	$\overline{\mathbf{K}}$	SBWa	DQa	NC
M	$V_{DDQ}$	DQb	$V_{SS}$	$\overline{\text{SW}}$	$V_{SS}$	NC	$V_{\mathrm{DDQ}}$
N	DQb	NC	$V_{SS}$	SA	$V_{SS}$	DQa	NC
P	NC	DQb	$V_{SS}$	SA	$V_{SS}$	NC	DQa
R	NC	SA	M1 <sup>(1)</sup>	$V_{DD}$	M2 <sup>(2)</sup>	SA	NC
T	NC	SA (x18)	SA	NC (x36)	SA	SA (x18)	ZZ
U	V <sub>DDQ</sub>	TMS	TDI	TCK	TDO	RSVD (3)	V <sub>DDQ</sub>

#### **Notes:**

- 1. Pad Location 3R is defined as an M1 mode pin in LW SRAMs. However, it must be tied "low" in this device.
- 2. Pad Location 5R is defined as an M2 mode pin in LW SRAMs. However, it must be tied "high" in this device.
- 3. Pad Location 6U must be left unconnected. It is used by Sony for internal test purposes.

# **Pin Description**

Symbol	Type	Description
SA	Input	Synchronous Address Inputs - Registered on the rising edge of K.
DQa, DQb	I/O	Synchronous Data Inputs / Outputs - Registered on the rising edge of K during write operations.  Driven from the rising edge of K during read operations.  DQa - indicates Data Byte a  DQb - indicates Data Byte b
$K, \overline{K}$	Input	Differential Input Clocks
SS	Input	
SW	Input	
SBWa, SBWb	Input	
G	Input	Asynchronous Output Enable Input - Deasserted (high) disables the data output drivers.
ZZ	Input	Asynchronous Sleep Mode Input - Asserted (high) forces the device into low-power mode.
M1, M2	Input	Read Operation Protocol Select - These mode pins must be tied "low" and "high" respectively to select Register - Register read operations.
ZQ	Input	Output Driver Impedance Control Resistor Input - This pin must be connected to $V_{SS}$ through an external resistor RQ to program data output driver impedance. See the Programmable Output Driver Impedance section for further information.
V <sub>DD</sub>		1.8V Core Power Supply - Core supply voltage.
V <sub>DDQ</sub>		Output Power Supply - Output buffer supply voltage.
V <sub>REF</sub>		Input Reference Voltage - Input buffer threshold voltage.
V <sub>SS</sub>		Ground
TCK	Input	JTAG Clock
TMS	Input	JTAG Mode Select - Weakly pulled "high" internally.
TDI	Input	JTAG Data In - Weakly pulled "high" internally.
TDO	Output	JTAG Data Out
RSVD		Reserved - This pin is reserved for Sony test purposes. It must be left unconnected.
NC		No Connect - These pins are true no-connects, i.e. there is no internal chip connection to these pins. They can be left unconnected or tied directly to $V_{DD}$ , $V_{DDQ}$ , or $V_{SS}$ .

#### •Clock Truth Table

K	ZZ	$\overline{SS}$ $(t_n)$	$\overline{SW}$ $(t_n)$	$\overline{SBW}x$ $(t_n)$	G	Operation	DQ (t <sub>n</sub> )	DQ (t <sub>n+1</sub> )
X	1	X	X	X	X	Sleep (Power Down) Mode	Hi - Z	Hi - Z
$\uparrow$	0	1	X	X	X	Deselect	***	Hi - Z
$\uparrow$	0	0	1	X	1	Read	Hi - Z	Hi - Z
$\uparrow$	0	0	1	X	0	Read	***	Q(t <sub>n</sub> )
$\uparrow$	0	0	0	0	X	Write All Bytes	***	D(t <sub>n</sub> )
$\uparrow$	0	0	0	X	X	Write Bytes With $\overline{SBW}x = 0$	***	D(t <sub>n</sub> )
$\uparrow$	0	0	0	1	X	Abort Write	***	Hi - Z

#### **Notes:**

- 1. "1" = input "high"; "0" = input "low"; "X" = input "don't care".
- 2. "\*\*\*" indicates that the input requirement or output state is determined by the previous operation.
- 3. DQs are tri-stated in response to Write and Deselect commands, one cycle after the command is sampled.

## •Sleep (Power Down) Mode

Sleep (power down) mode is provided through the asynchronous input signal ZZ. When ZZ is asserted (high), the output drivers are disabled and the SRAM begins to draw standby current. Contents of the memory array are preserved. An enable time ( $t_{ZZE}$ ) must be met before the SRAM is guaranteed to be in sleep mode, and a recovery time ( $t_{ZZR}$ ) must be met before the SRAM can resume normal operation.

## •Programmable Impedance Output Drivers

These devices have programmable impedance output drivers. The output impedance is controlled by an external resistor RQ connected between the SRAM's ZQ pin and  $V_{SS}$ , and is equal to one-fifth the value of this resistor, nominally. See the DC Electrical Characteristics section for further information.

#### **Output Driver Impedance Power-Up Requirements**

Output driver impedance will reach the programmed value within 8192 cycles after power-up. Consequently, it is recommended that Read operations not be initiated until after the initial 8192 cycles have elapsed.

#### **Output Driver Impedance Updates**

Output driver impedance is updated during Write and Deselect operations when the output driver is disabled.

## Power-Up Sequence

For reliability purposes, Sony recommends that power supplies power up in the following sequence:  $V_{SS}$ ,  $V_{DD}$ ,  $V_{DDQ}$ ,  $V_{REF}$ , and Inputs.  $V_{DDQ}$  should never exceed  $V_{DD}$ . If this power supply sequence cannot be met, a large bypass diode may be required between  $V_{DD}$  and  $V_{DDQ}$ . Please contact Sony Memory Application Department for further information.

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## •Absolute Maximum Ratings

Parameter	Symbol	Rating	Units
Supply Voltage	$V_{DD}$	-0.5 to +2.5	V
Output Supply Voltage	$V_{\mathrm{DDQ}}$	-0.5 to +2.3	V
Input Voltage (Address, Control, Data, Clock)	V <sub>IN</sub>	$-0.5 \text{ to V}_{DDQ} + 0.5 (2.3 \text{V max})$	V
Input Voltage (M1, M2)	V <sub>MIN</sub>	$-0.5 \text{ to V}_{DD} + 0.5 (2.5 \text{V max})$	V
Input Voltage (TCK, TMS, TDI)	V <sub>TIN</sub>	$-0.5 \text{ to V}_{DD} + 0.5 (2.5 \text{V max})$	V
Operating Temperature	$T_{A}$	0 to 85	°C
Junction Temperature	$T_{J}$	0 to 110	°C
Storage Temperature	T <sub>STG</sub>	-55 to 150	°C

**Notes**: Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions other than those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

## •BGA Package Thermal Characteristics

Parameter	Symbol	Rating	Units
Junction to Case Temperature	$\Theta_{ m JC}$	3.6	°C/W

## •I/O Capacitance

 $(T_A = 25^{\circ}C, f = 1 \text{ MHz})$ 

Parameter		Symbol	Test conditions	Min	Max	Units
	Address	$C_{IN}$	$V_{IN} = 0V$		4.0	pF
Input Capacitance	Control	$C_{IN}$	$V_{IN} = 0V$		4.0	pF
	Clock	C <sub>KIN</sub>	$V_{KIN} = 0V$		4.5	pF
Output Capacitance	Data	$C_{OUT}$	$V_{OUT} = 0V$		5.0	pF

Note: These parameters are sampled and are not 100% tested.

## **•**DC Recommended Operating Conditions

 $(V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$ 

Parameter	Symbol	Min	Тур	Max	Units	Notes
Supply Voltage	$V_{DD}$	1.7	1.8	1.9	V	1
Output Supply Voltage	$V_{\mathrm{DDQ}}$	1.4		$V_{DD}$	V	
Input Reference Voltage	$V_{REF}$	V <sub>DDQ</sub> /2 - 0.1	$V_{\rm DDQ}/2$	$V_{DDQ}/2 + 0.1$	V	2
Input High Voltage (Address, Control, Data)	$V_{IH}$	V <sub>REF</sub> + 0.1		$V_{DDQ} + 0.3$	V	3
Input Low Voltage (Address, Control, Data)	$V_{\rm IL}$	-0.3		V <sub>REF</sub> - 0.1	V	4
Input High Voltage (M1, M2)	$V_{MIH}$	$V_{REF} + 0.3$		$V_{DD} + 0.3$	V	
Input Low Voltage (M1, M2)	$V_{ m MIL}$	-0.3		V <sub>REF</sub> - 0.3	V	
Clock Input Signal Voltage	V <sub>KIN</sub>	-0.3		$V_{DDQ} + 0.3$	V	
Clock Input Differential Voltage	$V_{\mathrm{DIF}}$	0.2		$V_{DDQ} + 0.6$	V	
Clock Input Common Mode Voltage	$V_{CM}$	V <sub>DDQ</sub> /2 - 0.1	V <sub>DDQ</sub> /2	$V_{DDQ}/2 + 0.1$	V	

<sup>1.</sup>  $V_{DD} = 2.5V + /-5\%$  is also supported. Please contact Sony Memory Marketing Department for further information.

<sup>2.</sup> The peak-to-peak AC component superimposed on  $V_{\mbox{\scriptsize REF}}$  may not exceed 5% of the DC component.

<sup>3.</sup>  $V_{IH}$  (max)  $AC = V_{DDQ} + 0.9V$  for pulse widths less than one-quarter of the cycle time ( $t_{CYC}/4$ ).

<sup>4.</sup>  $V_{IL}$  (min) AC = -0.9V for pulse widths less than one-quarter of the cycle time ( $t_{CYC}/4$ ).

## •DC Electrical Characteristics

$$(V_{DD} = 1.8V \pm 0.1V, \, V_{SS} = 0V, \, T_A = 0 \,\, to \,\, 85^oC)$$

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units	Notes
Input Leakage Current (Address, Control, Clock)	$I_{LI}$	$V_{IN} = V_{SS}$ to $V_{DDQ}$	-5		5	uA	
Input Leakage Current (M1, M2)	I <sub>MLI</sub>	$V_{MIN} = V_{SS}$ to $V_{DD}$	-5		5	uA	
Output Leakage Current	I <sub>LO</sub>	$\begin{aligned} &V_{OUT} = V_{SS} \text{ to } V_{DDQ} \\ &\overline{G} = V_{IH} \end{aligned}$	-5		5	uA	
Average Power Supply Operating Current	$I_{\mathrm{DD-3}} \\ I_{\mathrm{DD-33}} \\ I_{\mathrm{DD-4}}$	$I_{OUT} = 0 \text{ mA}$ $\overline{SS} = V_{IL}, ZZ = V_{IL}$		 	650 600 540	mA	
Power Supply Standby Current	$I_{SB}$	$I_{OUT} = 0 \text{ mA}$ $ZZ = V_{IH}$			180	mA	1
Output High Voltage	V <sub>OH</sub>	$I_{OH} = -6.0 \text{ mA}$ $RQ = 250\Omega$	V <sub>DDQ</sub> - 0.4			V	
Output Low Voltage	V <sub>OL</sub>	$I_{OL} = 6.0 \text{ mA}$ $RQ = 250\Omega$			0.4	V	
		$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $RQ < 150\Omega$			35 (30*1.15)	Ω	2
Output Driver Impedance	R <sub>OUT</sub>	$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $150\Omega \le RQ \le 300\Omega$	(RQ/5)* 0.85	RQ/5	(RQ/5)* 1.15	Ω	
		$V_{OH}$ , $V_{OL} = V_{DDQ}/2$ $RQ > 300\Omega$	51 (60*0.85)			Ω	3

<sup>1.</sup> This parameter is guaranteed at  $T_A = 0$  to  $55^{\circ}$ C.

<sup>2.</sup> For maximum output drive (i.e. minimum impedance), the ZQ pin can be tied directly to  $V_{SS}$ .

<sup>3.</sup> For minimum output drive (i.e. maximum impedance), the ZQ pin can be left unconnected or tied to  $V_{DDQ}$ .

## •AC Electrical Characteristics

$$(V_{DD}$$
 = 1.8V  $\pm$  0.1V,  $V_{SS}$  = 0V,  $T_{A}$  = 0 to 85°C)

Demogration	Carrala a l	-	3	-3	33	-	4	Units	Notes
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Units	Notes
Input Cycle Time	t <sub>KHKH</sub>	3.0		3.3		4.0		ns	
Input Clock High Pulse Width	t <sub>KHKL</sub>	1.2		1.3		1.5		ns	
Input Clock Low Pulse Width	t <sub>KLKH</sub>	1.2		1.3		1.5		ns	
Address Input Setup Time	t <sub>AVKH</sub>	0.3		0.3		0.3		ns	1
Address Input Hold Time	t <sub>KHAX</sub>	0.5		0.5		0.5		ns	
Write Enable Input Setup Time	t <sub>WVKH</sub>	0.3		0.3		0.3		ns	1
Write Enable Input Hold Time	t <sub>KHWX</sub>	0.5		0.5		0.5		ns	
Sync Select Input Setup Time	t <sub>SVKH</sub>	0.3		0.3		0.3		ns	1
Sync Select Input Hold Time	t <sub>KHSX</sub>	0.5		0.5		0.5		ns	
Data Input Setup Time	t <sub>DVKH</sub>	0.3		0.3		0.3		ns	1
Data Input Hold Time	t <sub>KHDX</sub>	0.5		0.5		0.5		ns	
Input Clock High to Output Data Valid	t <sub>KHQV</sub>		1.6		1.6		2.0	ns	
Input Clock High to Output Data Hold	t <sub>KHQX</sub>	0.5		0.5		0.5		ns	2
Input Clock High to Output Data Low-Z	t <sub>KHQX1</sub>	0.5		0.5		0.5		ns	2,3
Input Clock High to Output Data High-Z	t <sub>KHQZ</sub>		1.8		1.8		2.2	ns	2,3
Output Enable Low to Output Data Valid	t <sub>GLQV</sub>		2.5		2.5		2.5	ns	
Output Enable Low to Output Data Low-Z	t <sub>GLQX</sub>	0.3		0.3		0.3		ns	2,3
Output Enable High to Output Data High-Z	t <sub>GHQZ</sub>		2.5		2.5		2.5	ns	2,3
Sleep Mode Enable Time	t <sub>ZZE</sub>		15		15		15	ns	2
Sleep Mode Recovery Time	t <sub>ZZR</sub>	20		20		20		ns	2

<sup>1.</sup> These parameters are measured from  $V_{REF}\pm 200 \text{mV}$  to the clock mid-point.

<sup>2.</sup> These parameters are guaranteed by design through extensive corner-lot characterization.

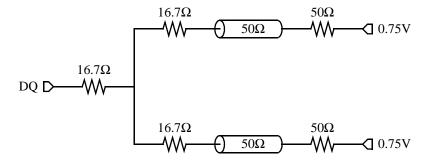
<sup>3.</sup> These parameters are measured at  $\pm\,50\text{mV}$  from steady state voltage.

# •AC Test Conditions ( $V_{DDQ} = 1.5V$ )

$$(V_{DD} = 1.8V \pm 0.1V, V_{DDQ} = 1.5V \pm 0.1V, T_A = 0 \text{ to } 85^{\circ}\text{C})$$

Item	Symbol	Conditions	Units	Notes
Input Reference Voltage	$V_{REF}$	0.75	V	
Input High Level	V <sub>IH</sub>	1.25	V	
Input Low Level	V <sub>IL</sub>	0.25	V	
Input Rise & Fall Time		2.0	V/ns	
Input Reference Level		0.75	V	
Clock Input High Voltage	V <sub>KIH</sub>	1.25	V	$V_{\rm DIF} = 1.0V$
Clock Input Low Voltage	V <sub>KIL</sub>	0.25	V	$V_{DIF} = 1.0V$
Clock Input Common Mode Voltage	$V_{CM}$	0.75	V	
Clock Input Rise & Fall Time		2.0	V/ns	
Clock Input Reference Level		K/K cross	V	
Output Reference Level		0.75	V	
Output Load Conditions		$RQ = 250\Omega$		See Figure 1 below

Figure 1: AC Test Output Load  $(V_{DDO} = 1.5V)$ 

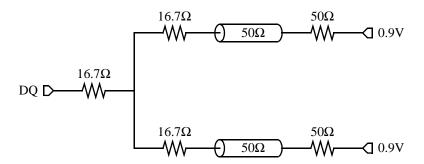


# •AC Test Conditions ( $V_{DDQ} = 1.8V$ )

$$(V_{DD} = V_{DDQ} = 1.8V \pm 0.1V, T_A = 0 \text{ to } 85^{\circ}C)$$

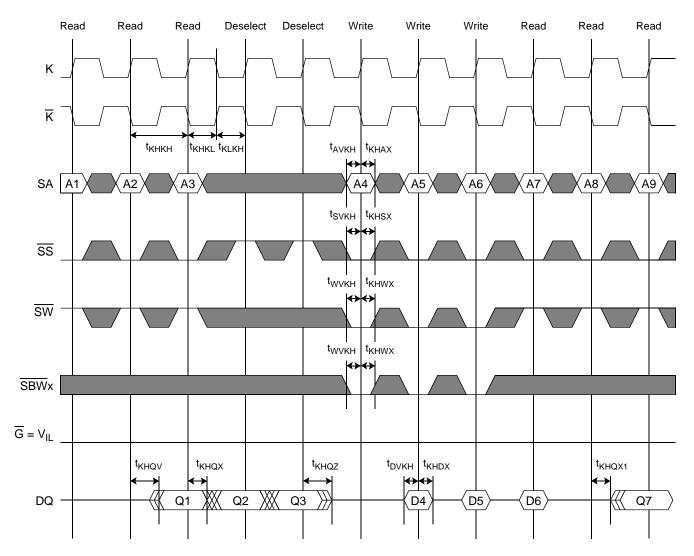
Item	Symbol	Conditions	Units	Notes
Input Reference Voltage	V <sub>REF</sub>	0.9	V	
Input High Level	V <sub>IH</sub>	1.4	V	
Input Low Level	V <sub>IL</sub>	0.4	V	
Input Rise & Fall Time		2.0	V/ns	
Input Reference Level		0.9	V	
Clock Input High Voltage	V <sub>KIH</sub>	1.4	V	$V_{\rm DIF} = 1.0 V$
Clock Input Low Voltage	V <sub>KIL</sub>	0.4	V	$V_{DIF} = 1.0V$
Clock Input Common Mode Voltage	$V_{CM}$	0.9	V	
Clock Input Rise & Fall Time		2.0	V/ns	
Clock Input Reference Level		K/K cross	V	
Output Reference Level		0.9	V	
Output Load Conditions		$RQ = 250\Omega$		See Figure 2 below

Figure 2: AC Test Output Load  $(V_{DDQ} = 1.8V)$ 



# $\label{eq:Read-Write-Read} \begin{array}{c} \textbf{Read-Write-Read Timing Diagram} \\ \textbf{Synchronously Controlled via } \overline{\textbf{SS}} \ \textbf{and Deselect Operations} \ (\overline{\textbf{G}} = Low) \end{array}$

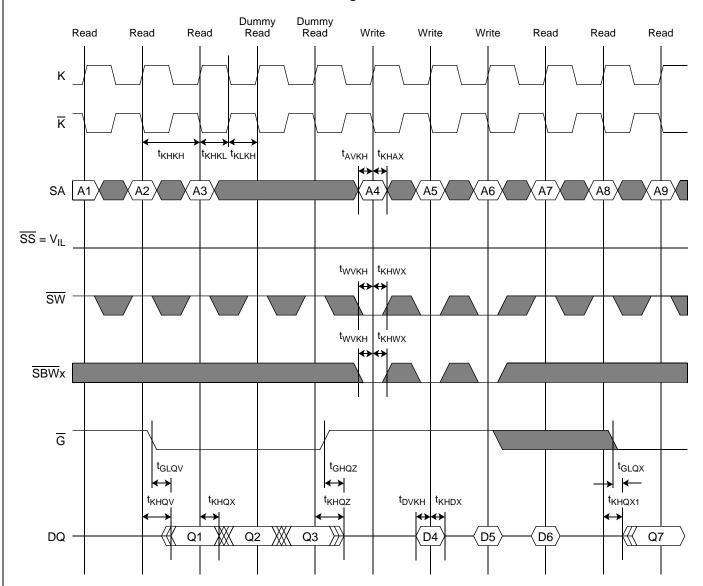
Figure 3



**Note**: In the diagram above, two Deselect operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Deselect operation may be sufficient.

# 

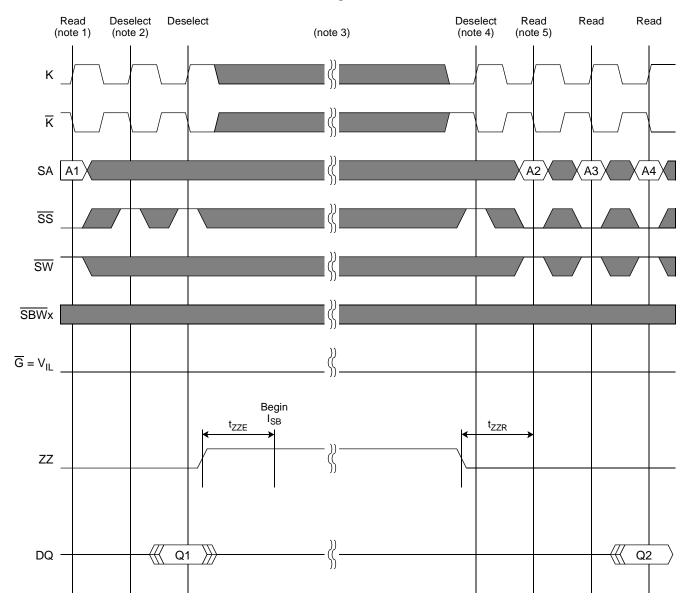
Figure 4



**Note**: In the diagram above, two Dummy Read operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Dummy Read operation may be sufficient.

## Sleep (Power-Down) Mode Timing Diagram

#### Figure 5



#### Notes:

- 1: This can be any operation. The depiction of a Read operation here is provided only as an example.
- 2: Before ZZ is asserted, at least two (2) Deselect operations must be initiated after the last Read or Write operation is initiated, in order to ensure the successful completion of the last Read or Write operation.
- 3: While ZZ is asserted, all of the SRAM's address, control, data, and clock inputs are ignored.
- 4: After ZZ is deasserted, Deselect operations must be initiated until the specified recovery time (t<sub>ZZR</sub>) has been met. Read and Write operations may NOT be initiated during this time.
- 5: This can be any operation. The depiction of a Read operation here is provided only as an example.

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## Test Mode Description

These devices provide a JTAG Test Access Port (TAP) and Boundary Scan interface using a limited set of IEEE std. 1149.1 functions. This test mode is intended to provide a mechanism for testing the interconnect between master (processor, controller, etc.), SRAMs, other components, and the printed circuit board.

In conformance with a subset of IEEE std. 1149.1, these devices contain a TAP Controller and four TAP Registers. The TAP Registers consist of one Instruction Register and three Data Registers (ID, Bypass, and Boundary Scan Registers).

The TAP consists of the following four signals:

TCK: Test Clock Induces (clocks) TAP Controller state transitions.

TMS: Test Mode Select Inputs commands to the TAP Controller. Sampled on the rising edge of TCK.
 TDI: Test Data In Inputs data serially to the TAP Registers. Sampled on the rising edge of TCK.
 TDO: Test Data Out Outputs data serially from the TAP Registers. Driven from the falling edge of TCK.

## **Disabling the TAP**

When JTAG is not used, TCK should be tied "low" to prevent clocking the SRAM. TMS and TDI should either be tied "high" through a pull-up resistor or left unconnected. TDO should be left unconnected.

**Note**: Operation of the TAP does not interfere with normal SRAM operation except when the SAMPLE-Z instruction is selected. Consequently, TCK, TMS, and TDI can be controlled any number of ways without adversely affecting the functionality of the device.

## JTAG DC Recommended Operating Conditions

$$(V_{DD} = 1.8V \pm 0.1V, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$$

Parameter	Symbol	Test Conditions	Min	Max	Units
JTAG Input High Voltage	$V_{TIH}$		1.2	$V_{DD} + 0.3$	V
JTAG Input Low Voltage	V <sub>TIL</sub>		-0.3	0.6	V
JTAG Output High Voltage (CMOS)	$V_{TOH}$	$I_{TOH} = -100uA$	V <sub>DD</sub> - 0.1		V
JTAG Output Low Voltage (CMOS)	V <sub>TOL</sub>	$I_{TOL} = 100uA$		0.1	V
JTAG Output High Voltage (TTL)	$V_{TOH}$	$I_{TOH} = -8.0 \text{mA}$	V <sub>DD</sub> - 0.4		V
JTAG Output Low Voltage (TTL)	V <sub>TOL</sub>	$I_{TOL} = 8.0 \text{mA}$		0.4	V
JTAG Input Leakage Current	$I_{TLI}$	$V_{TIN} = V_{SS}$ to $V_{DD}$	-10	10	uA

## **JTAG AC Test Conditions**

$$(V_{DD} = 1.8V \pm 0.1V, V_{SS} = 0V, T_A = 0 \text{ to } 85^{\circ}C)$$

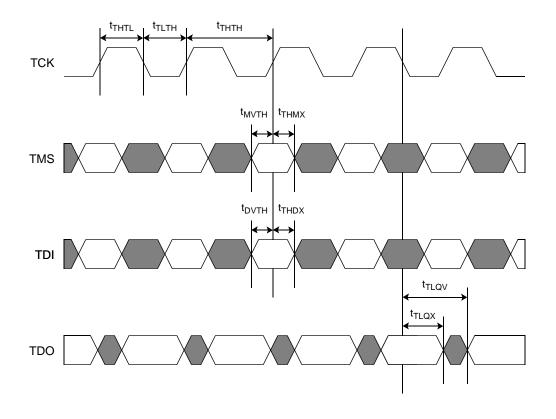
Parameter	Symbol	Conditions	Units	Notes
JTAG Input High Level	$V_{TIH}$	1.8	V	
JTAG Input Low Level	V <sub>TIL</sub>	0.0	V	
JTAG Input Rise & Fall Time		1.0	V/ns	
JTAG Input Reference Level		0.9	V	
JTAG Output Reference Level		0.9	V	
JTAG Output Load Condition				See Fig.2 (page 10)

# JTAG AC Electrical Characteristics

Parameter	Symbol	Min	Max	Unit
TCK Cycle Time	t <sub>THTH</sub>	50		ns
TCK High Pulse Width	t <sub>THTL</sub>	20		ns
TCK Low Pulse Width	t <sub>TLTH</sub>	20		ns
TMS Setup Time	t <sub>MVTH</sub>	5		ns
TMS Hold Time	t <sub>THMX</sub>	5		ns
TDI Setup Time	t <sub>DVTH</sub>	5		ns
TDI Hold Time	t <sub>THDX</sub>	5		ns
Capture Setup Time (Address, Control, Data, Clock)	t <sub>CS</sub>	5		ns
Capture Hold Time (Address, Control, Data, Clock)	t <sub>CH</sub>	5		ns
TCK Low to TDO Valid	t <sub>TLQV</sub>		10	ns
TCK Low to TDO Hold	t <sub>TLQX</sub>	0		ns

## **JTAG Timing Diagram**

Figure 6



## **TAP Controller**

The TAP Controller is a 16-state state machine that controls access to the various TAP Registers and executes the operations associated with each TAP Instruction. State transitions are controlled by TMS and occur on the rising edge of TCK.

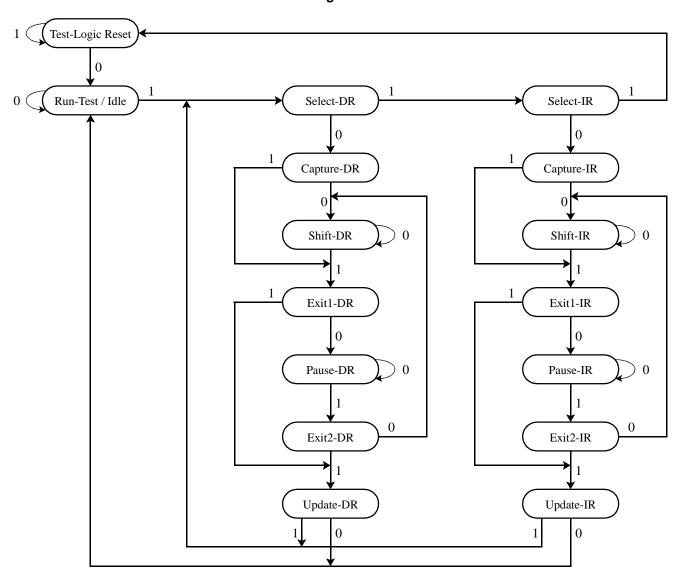
The TAP Controller enters the "Test-Logic Reset" state in one of two ways:

- 1. At power up.
- 2. When a logic "1" is applied to TMS for at least 5 consecutive rising edges of TCK.

The TDI input receiver is sampled only when the TAP Controller is in either the "Shift-IR" state or the "Shift-DR" state. The TDO output driver is active only when the TAP Controller is in either the "Shift-IR" state or the "Shift-DR" state.

## **TAP Controller State Diagram**

Figure 7



### **TAP Registers**

TAP Registers are serial shift registers that capture serial input data (from TDI) on the rising edge of TCK, and drive serial output data (to TDO) from the falling edge of TCK. They are divided into two groups: "Instruction Registers" (IR), which are manipulated via the "IR" states in the TAP Controller, and "Data Registers" (DR), which are manipulated via the "DR" states in the TAP Controller.

#### **Instruction Register (IR - 3 Bits)**

The Instruction Register stores the various TAP Instructions supported by these devices. It is loaded with the IDCODE instruction at power-up, and when the TAP Controller is in the "Test-Logic Reset" and "Capture-IR" states. It is inserted between TDI and TDO when the TAP Controller is in the "Shift-IR" state, at which time it can be loaded with a new instruction. However, newly loaded instructions are not executed until the TAP Controller has reached the "Update-IR" state.

The Instruction Register is 3 bits wide, and is encoded as follows:

Code (2:0)	Instruction	Description
000	BYPASS	See code "111".
001	IDCODE	Loads a predefined device- and manufacturer-specific identification code into the ID Register when the TAP Controller is in the "Capture-DR" state, and inserts the ID Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.
		See the ID Register description for more information.
010	SAMPLE-Z	Loads the individual logic states of all signals composing the SRAM's I/O ring into the Boundary Scan Register when the TAP Controller is in the "Capture-DR" state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.
		Also disables the SRAM's data output drivers.
		See the Boundary Scan Register description for more information.
011	PRIVATE	Do not use. Reserved for manufacturer use only.
100	SAMPLE	Loads the individual logic states of all signals composing the SRAM's I/O ring into the Boundary Scan Register when the TAP Controller is in the "Capture-DR" state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.  See the Boundary Scan Register description for more information.
101	PRIVATE	Do not use. Reserved for manufacturer use only.
110	PRIVATE	Do not use. Reserved for manufacturer use only.
111	BYPASS	Loads a logic "0" into the Bypass Register when the TAP Controller is in the "Capture-DR" state, and inserts the Bypass Register between TDI and TDO when the TAP Controller is in the "Shift-DR" state.
		See the Bypass Register description for more information.

Bit 0 is the LSB and Bit 2 is the MSB. When the Instruction Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

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#### Bypass Register (DR - 1 Bit)

The Bypass Register is one bit wide, and provides the minimum length serial path between TDI and TDO. It is loaded with a logic "0" when the BYPASS instruction has been loaded in the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the BYPASS instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

#### ID Register (DR - 32 Bits)

The ID Register is loaded with a predetermined device- and manufacturer-specific identification code when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

The ID Register is 32 bits wide, and contains the following information:

Device	Revision Number (31:28)	Part Number (27:12)	Sony ID (11:1)	Start Bit (0)
2Mb x 18	xxxx	0000 0000 0111 0100	0000 1110 001	1

Bit 0 is the LSB and Bit 31 is the MSB. When the ID Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

#### **Boundary Scan Registers (DR - 51 Bits)**

The Boundary Scan Register is equal in length to the number of active signal connections to the SRAM (excluding the TAP pins) plus a number of place holder locations reserved for functional and/or density upgrades. It is loaded with the individual logic states of all signals composing the SRAM's I/O ring when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the "Capture-DR" state. It is inserted between TDI and TDO when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the "Shift-DR" state.

The Boundary Scan Register contains the following bits:

2Mb x 18				
DQ	18			
SA	21			
$K, \overline{K}$	2			
$\overline{SS}$ , $\overline{SW}$ , $\overline{SBW}$ x	4			
G, ZZ	2			
ZQ, M1, M2	3			
Place Holder	1			

**Note**: K and  $\overline{K}$  are connected to a differential input receiver that generates a single-ended input clock signal to the device. Therefore, in order to capture deterministic values for these signals in the Boundary Scan Register, they must be at opposite logic levels when sampled.

**Note**: When an external resistor RQ is connected between the ZQ pin and  $V_{SS}$ , the value of the ZQ signal captured in the Boundary Scan Register is non-deterministic.

**Note**: Place Holders are required for some NC pins to allow for future density and/or functional upgrades. They are connected to  $V_{SS}$  internally, regardless of pin connection externally.

## **Boundary Scan Register Bit Order Assignments**

The tables below depict the order in which the bits are arranged in the Boundary Scan Register. Bit 1 is the LSB and bit 51 is the MSB. When the Boundary Scan Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

	2Mb x 18						
Bit	Signal	Pad	Bit	Signal	Pad		
1	M2	5R	36	SBWb	3G		
2	SA	6T	37	ZQ	4D		
3	SA	4P	38	SS	4E		
4	SA	6R	39	SA	4B		
5	SA	5T	40	NC <sup>(1)</sup>	4H		
6	ZZ	7T	41	SW	4M		
7	DQa	7P	42	DQb	2K		
8	DQa	6N	43	DQb	1L		
9	DQa	6L	44	DQb	2M		
10	DQa	7K	45	DQb	1N		
11	SBWa	5L	46	DQb	2P		
12	$\overline{\mathbf{K}}$	4L	47	SA	3T		
13	K	4K	48	SA	2R		
14	$\overline{\mathrm{G}}$	4F	49	SA	4N		
15	DQa	6Н	50	SA	2T		
16	DQa	7G	51	M1	3R		
17	DQa	6F					
18	DQa	7E					
19	DQa	6D					
20	SA	6A					
21	SA	6C					
22	SA	5C					
23	SA	5A					
24	SA	6B					
25	SA	5B					
26	SA	3B					
27	SA	2B					
28	SA	3A					
29	SA	3C					
30	SA	2C					
31	SA	2A					
32	DQb	1D					
33	DQb	2E					
34	DQb	2G					
35	DQb	1H					

Note 1: NC pin at pad location 4H is connected to  $V_{SS}$  internally, regardless of pin connection externally.

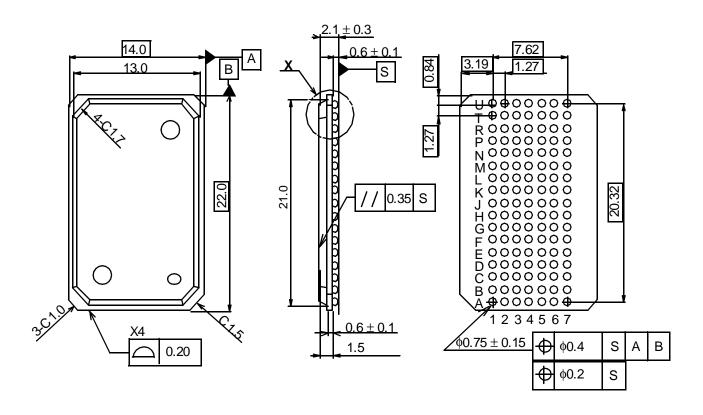
# •Ordering Information\_

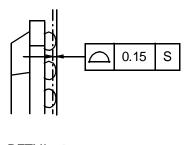
Part Number	$V_{DD}$	I/O Type	Size	Speed (Cycle Time / Access Time)
CXK77K18R320GB-3	1.8V	HSTL	2Mb x 18	3.0ns / 1.6ns
CXK77K18R320GB-33	1.8V	HSTL	2Mb x 18	3.3ns / 1.6ns
CXK77K18R320GB-4	1.8V	HSTL	2Mb x 18	4.0ns / 2.0ns

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## 119 Pin BGA Package Dimensions





## DETAIL A

SONY CODE	BGA-119P-021
EIAJ CODE	BGA119-P-1422
JEDEC CODE	

## PACKAGE STRUCTURE

PACKAGE MATERIAL	EPOXY RESIN
BORAD TREATMENT	COPPER-CLAD LAMINATE
LEAD MATERIAL	SOLDER
PACKAGE MASS	1.1g

This product utilizes lead (Pb) as one of the elements composing the package solder ball. The quantity of lead (Pb) per package is approxmiately 70.81mg (1.7mg per ball \* 119 balls \* 35%). Lead (Pb) has been shown to be hazardous to the environment, and therefore may be subject to regulations within each country.

# •Revision History

Rev. #	Rev. Date	Description of Modification			
rev 0.0	11/30/01	Initial Version			
rev 0.1	03/22/02	<ol> <li>Modified BGA Package Thermal Characteristics section (p. 6). Θ<sub>JC</sub></li> <li>Modified DC Recommended Operating Conditions section (p. 7 V<sub>DDQ</sub> (max) V<sub>REF</sub>, V<sub>CM</sub> (max)         Added note 1 regarding 2.5V V<sub>DD</sub> support.         Added note 2 regarding 1.8V V<sub>DDQ</sub> support.</li> <li>Modified DC Electrical Characteristics section (p. 8).         R<sub>OUT</sub> RQ/5 ± 10% (GBD) to 4. Modified AC Electrical Characteristics section (p. 9).         Removed "-25" bin. Added "-33" bin.         -3 t<sub>KHQV</sub></li></ol>	$V_{DD}$ to 1.6V 1.0V to 0.85V 0 RQ/5 ± 15% (TESTED) 1.7ns to 1.5ns 1.9ns to 1.7ns		
rev 0.2	04/02/02	1. Modified DC Recommended Operating Conditions section (p. 7  V <sub>DDQ</sub> (max)  V <sub>REF</sub> , V <sub>CM</sub> (min)  V <sub>REF</sub> , V <sub>CM</sub> (max)  2. Added 1.8V V <sub>DDO</sub> AC Test Conditions (p. 11).	7). $1.6 \text{V to V}_{\text{DD}} \\ 0.65 \text{V to V}_{\text{DDQ}} / 2 - 0.1 \text{V} \\ 0.85 \text{V to V}_{\text{DDQ}} / 2 + 0.1 \text{V}$		
rev 0.3	06/24/02	1. Modified AC Electrical Characteristics section (p. 9).  -3, -33  t <sub>AVKH</sub> , t <sub>WVKH</sub> , t <sub>SVKH</sub> , t <sub>DVKH</sub> -3, -33  t <sub>KHAX</sub> , t <sub>KHWX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub> 2. Modified JTAG DC Recommended Operating Conditions section V <sub>TIH</sub> (min)  V <sub>TIL</sub> (max)  3. Modified JTAG AC Electrical Characteristics section (p. 16).  TCK Cycle Time  TCK High / Low Pulse Widths  TMS/TDI Input Setup & Hold Times  TDO Output Valid Time  Added Capture Setup & Hold Times	0.5ns to 0.3ns 0.5ns to 0.3ns on (p. 15). 1.4V to 1.2V 0.8V to 0.6V 100ns to 50ns 40ns to 20ns 10ns to 5ns 20ns to 10ns 5ns		
rev 0.4	02/05/03	1. Removed all x36 information (created separate x36 data sheet).  2. Modified DC Electrical Characteristics section (p. 7).  I <sub>MLI</sub> , I <sub>LO</sub> (min/max)  Added preliminary I <sub>DD</sub> , I <sub>DD2</sub> , and I <sub>SB</sub> specifications.  3. Modified AC Electrical Characteristics section (p. 8).  -4  t <sub>AVKH</sub> , t <sub>WVKH</sub> , t <sub>SVKH</sub> , t <sub>DVKH</sub> -3, -33  t <sub>KHAX</sub> , t <sub>KHWX</sub> , t <sub>KHSX</sub> , t <sub>KHDX</sub> t <sub>KHQV</sub> t <sub>KHQZ</sub> , t <sub>GLQV</sub> , t <sub>GHQZ</sub> ,	± 10uA to ± 5uA  0.5ns to 0.3ns 0.3ns to 0.5ns 1.7ns to 1.6ns 1.9ns to 1.8ns		

Rev. #	Rev. Date	Description of Modification	
rev 0.5	06/09/03	Modified DC Electrical Characteristics section (p. 7).     Removed I <sub>DD2</sub> Power Supply Deselect Operating Current.     Modified JTAG ID Register definition (p. 18).     Changed Part Number code from T.B.D. to 0000 0000 0111 0100.	
rev 0.6	07/08/03	1. Modified AC Electrical Characteristics section (p. 8).  -3 t <sub>GLQV</sub> , t <sub>GHQZ</sub> -33 t <sub>GLQV</sub> , t <sub>GHQZ</sub> -4 t <sub>GLQV</sub> , t <sub>GHQZ</sub>	1.7ns to 2.5ns 1.8ns to 2.5ns 2.2ns to 2.5ns
rev 0.7	03/31/04	1. Modified I/O Capacitance section (p. 5).  C <sub>IN</sub> C <sub>KIN</sub> C <sub>OUT</sub> 2. Modified AC Electrical Characteristics section (p. 8).  -3 t <sub>KHQV</sub> t <sub>KHQZ</sub> 3. Added note to Package Dimensions section regarding lead content in section.	3.5pF to 4.0pF 3.5pF to 4.5pF 4.5pF to 5.0pF 1.5ns to 1.6ns 1.7ns to 1.8ns solder balls (p. 21).
rev 0.8	12/08/04	3. Modified AC Electrical Characteristics section (p. 8). Added Note 1.	