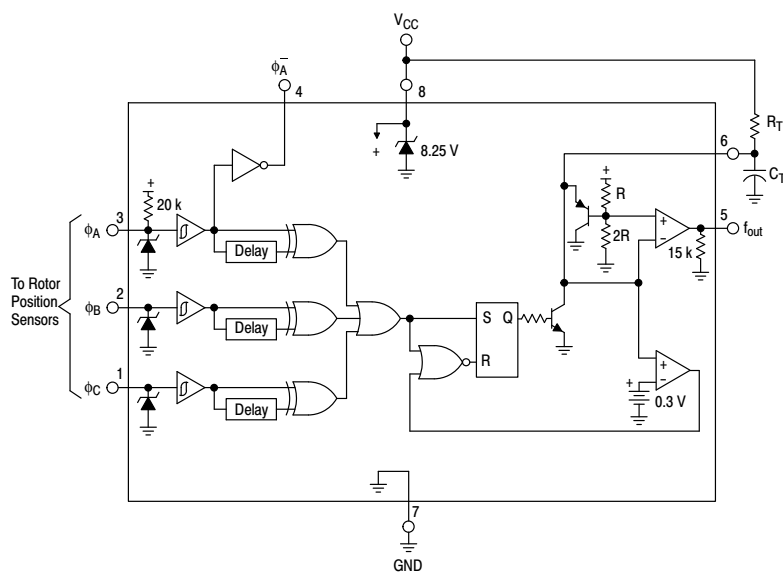


Closed Loop Brushless Motor Adapter

The MC33039 is a high performance closed-loop speed control adapter specifically designed for use in brushless DC motor control systems. Implementation will allow precise speed regulation without the need for a magnetic or optical tachometer. This device contains three input buffers each with hysteresis for noise immunity, three digital edge detectors, a programmable monostable, and an internal shunt regulator. Also included is an inverter output for use in systems that require conversion of sensor phasing. Although this device is primarily intended for use with the MC33035 brushless motor controller, it can be used cost effectively in many other closed-loop speed control applications.

Features

- Digital Detection of Each Input Transition for Improved Low Speed Motor Operation
- TTL Compatible Inputs With Hysteresis
- Operation Down to 5.5 V for Direct Powering from MC33035 Reference
- Internal Shunt Regulator Allows Operation from a Non-Regulated Voltage Source
- Inverter Output for Easy Conversion between 60°/300° and 120°/240° Sensor Phasing Conventions
- Pb-Free Packages are Available



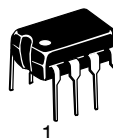
Representative Block Diagram



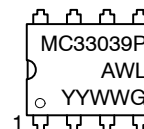
ON Semiconductor®

<http://onsemi.com>

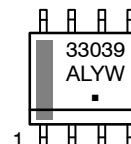
MARKING DIAGRAMS



PDIP-8
P SUFFIX
CASE 626

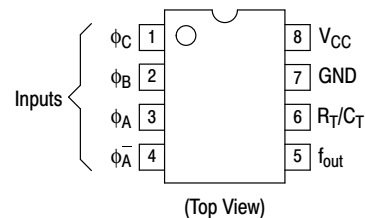


SOIC-8
D SUFFIX
CASE 751



A = Assembly Location
WL, L = Wafer Lot
YY, Y = Year
WW, W = Work Week
G or ■ = Pb-Free Package

PIN CONNECTIONS



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 6 of this data sheet.

MC33039, NCV33039

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
V _{CC} Zener Current	I _Z (V _{CC})	30	mA
Logic Input Current (Pins 1, 2, 3)	I _{IH}	5.0	mA
Output Current (Pins 4, 5), Sink or Source	I _{DRV}	20	mA
Power Dissipation and Thermal Characteristics			
Maximum Power Dissipation @ T _A = +85°C	P _D	650	mW
Thermal Resistance, Junction-to-Air	R _{θJA}	100	°C/W
Operating Junction Temperature	T _J	+150	°C
Operating Ambient Temperature Range	T _A	-40 to +85	°C
MC33039		-40 to +125	
NCV33039			
Storage Temperature Range	T _{stg}	-65 to +150	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

ELECTRICAL CHARACTERISTICS (V_{CC} = 6.25 V, R_T = 10 k, C_T = 22 nF, T_A = 25°C, unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
LOGIC INPUTS					
Input Threshold Voltage					V
High State	V _{IH}	2.4	2.1	–	
Low State	V _{IL}	–	1.4	1.0	
Hysteresis	V _H	0.4	0.7	0.9	
Input Current	I _{IH}				μA
High State (V _{IH} = 5.0 V)					
φ _A		– 40	– 60	– 80	
φ _B , φ _C		–	– 0.3	– 5.0	
Low State (V _{IL} = 0 V)	I _{IL}				
φ _A		– 190	– 300	– 380	
φ _B , φ _C		–	– 0.3	– 5.0	

MONOSTABLE AND OUTPUT SECTIONS

Output Voltage	V _{OH}				V
High State					
f _{out} (I _{source} = 5.0 mA)		3.60	3.95	4.20	
φ _A (I _{source} = 2.0 mA)		4.20	4.75	–	
Low State	V _{OL}				
f _{out} (I _{sink} = 10 mA)		–	0.25	0.50	
φ _A (I _{sink} = 10 mA)		–	0.25	0.50	
Capacitor C _T Discharge Current	I _{dischg}	20	35	60	mA
Output Pulse Width (Pin 5)	t _{PW}	205	225	245	μs

POWER SUPPLY SECTION

Power Supply Operating Voltage Range	V _{CC}	5.5	–	V _Z	V
MC33039 (T _A = –40° to +85°C)					
NCV33039 (T _A = –40° to +125°C)					
Power Supply Current	I _{CC}	1.8	3.9	5.0	mA
Zener Voltage (I _Z = 10 mA)	V _Z	7.5	8.25	9.0	V
Zener Dynamic Impedance (ΔI _Z = 10 mA to 20 mA, f ≤ 1.0 kHz)	Z _{ka}	–	2.0	5.0	Ω

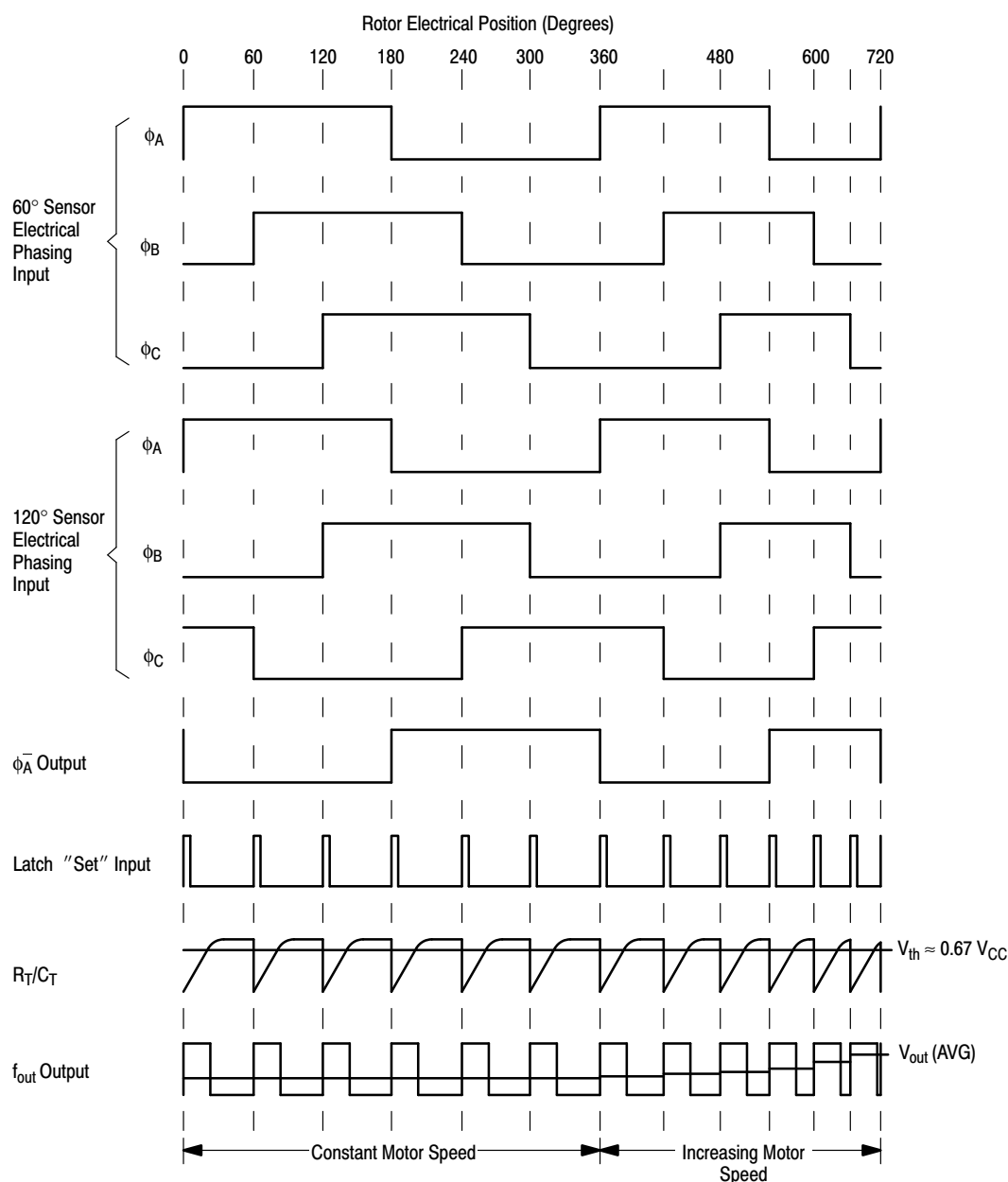


Figure 1. Typical Three Phase, Six Step Motor Application

OPERATING DESCRIPTION

The MC33039 provides an economical method of implementing closed-loop speed control of brushless DC motors by eliminating the need for a magnetic or optical tachometer. Shown in the timing diagram of Figure 1, the three inputs (Pins 1, 2, 3) monitor the brushless motor rotor position sensors. Each sensor signal transition is digitally detected, OR'ed at the Latch 'Set' Input, and causes C_T to discharge. A corresponding output pulse is generated at f_{out} (Pin 5) of a defined amplitude, and programmable width determined by the values selected for R_T and C_T (Pin 6). The average voltage of the output pulse train increases with motor speed. When fed through a low pass filter or integrator, a DC voltage proportional to speed is generated. Figure 2 shows the proper connections for a typical closed

loop application using the MC33035 brushless motor controller. Constant speed operation down to 100 RPM is possible with economical three phase four pole motors.

The ϕ_A inverter output (Pin 4) is used in systems where the controller and motor sensor phasing conventions are not compatible. A method of converting from either convention to the other is shown in Figure 3. For a more detailed explanation of this subject, refer to the text above Figure 39 on the MC33035 data sheet.

The output pulse amplitude V_{OH} is constant with temperature and controlled by the supply voltage on V_{CC} (Pin 8). Operation down to 5.5 V is guaranteed over temperature. For systems without a regulated power supply, an internal 8.25 V shunt regulator is provided.

The schematic diagram illustrates a motor control system. At the top, a motor assembly (Rotor Assy) is connected to a power source. The control system consists of two main ICs: the MC33039P (bottom) and the MC33035P (top). The MC33039P includes an oscillator (OSC), an error amplifier (EA), and a speed feedback loop with a resistor divider (R_T, C_T) and a reference voltage (REF). It also features a thermal protection circuit and a fault output. The MC33035P includes a position decoder (POS DEC), a pulse-width modulator (PWM), and a current limit circuit (I_{LIMIT}). The motor is connected to the output buffers of the MC33035P. The system is powered by a 24V supply, and the motor's back EMF is monitored via a voltage divider (V_M).

4

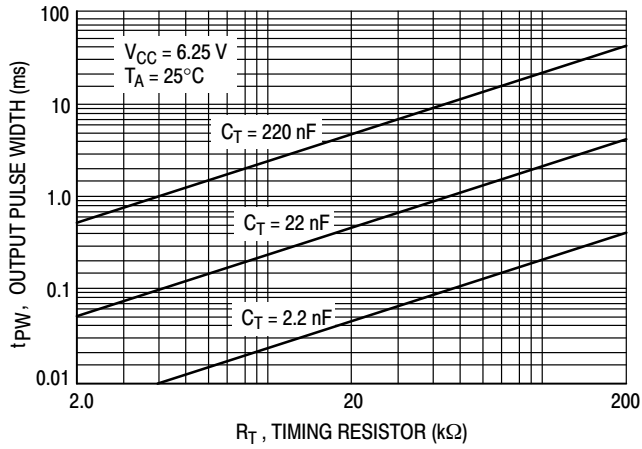


Figure 3. f_{out} , Pulse Width versus Timing Resistor

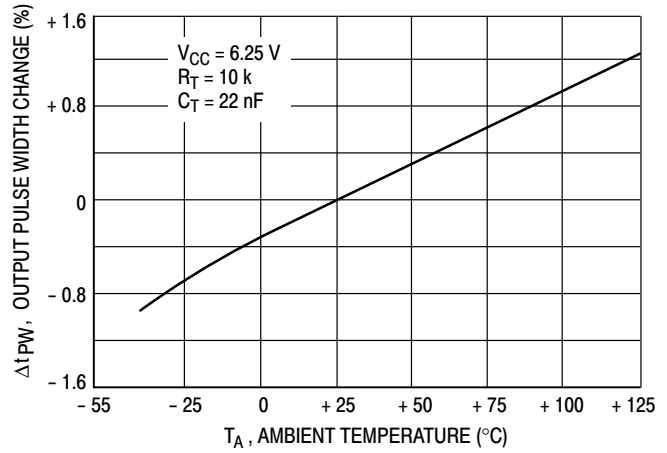


Figure 4. f_{out} , Pulse Width Change versus Temperature

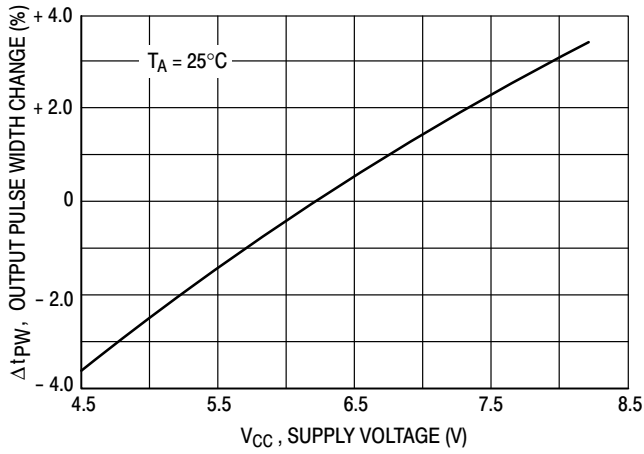


Figure 5. f_{out} , Pulse Width Change versus Supply Voltage

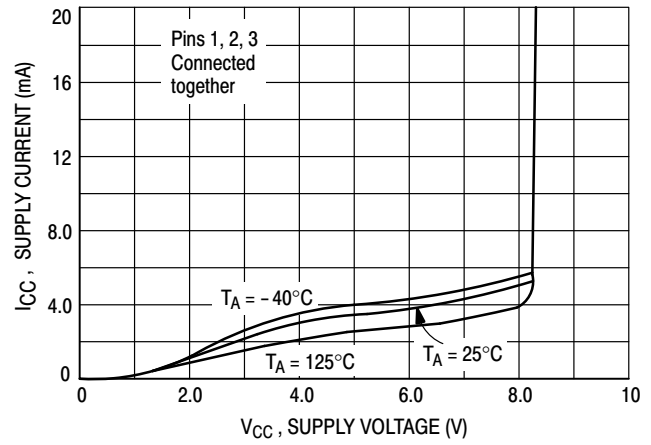


Figure 6. Supply Current versus Supply Voltage

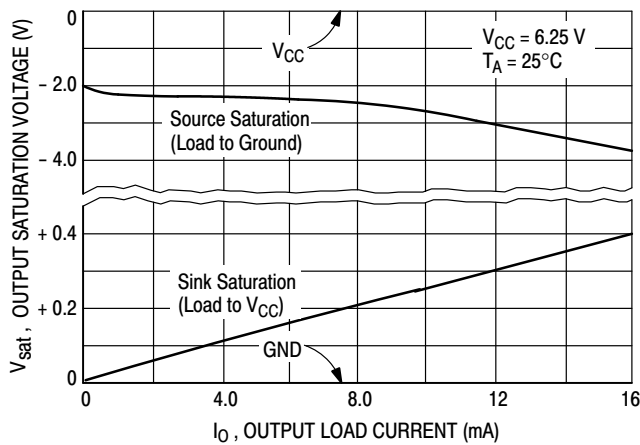


Figure 7. f_{out} , Saturation versus Load Current

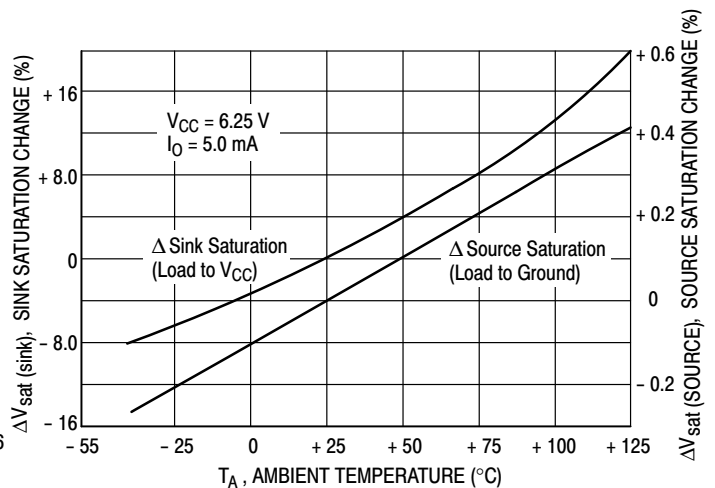


Figure 8. f_{out} , Saturation Change versus Temperature

MC33039, NCV33039

ORDERING INFORMATION

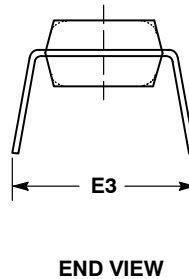
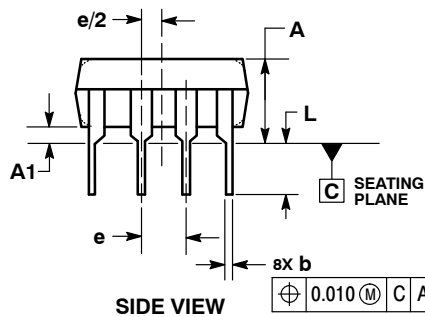
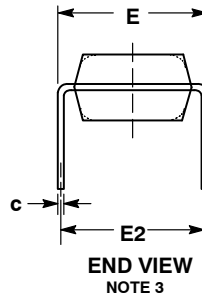
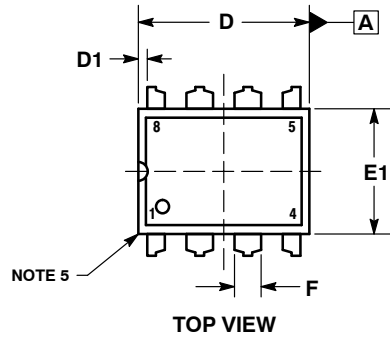
Device	Operating Temperature Range	Package	Shipping [†]
MC33039D	$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	SOIC-8	98 Units / Rail
MC33039DG			2500 / Tape & Reel
MC33039DR2			
MC33039DR2G			
MC33039P		PDIP-8	50 Units / Rail
MC33039PG			
NCV33039DR2*	$T_A = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$	SOIC-8	2500 / Tape & Reel
NCV33039DR2G*			

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

*NCV33039: $T_{\text{low}} = -40^{\circ}\text{C}$, $T_{\text{high}} = +125^{\circ}\text{C}$. Guaranteed by design. NCV prefix is for automotive and other applications requiring site and change control.

PACKAGE DIMENSIONS

P SUFFIX
CASE 626-05
ISSUE M



NOTES:

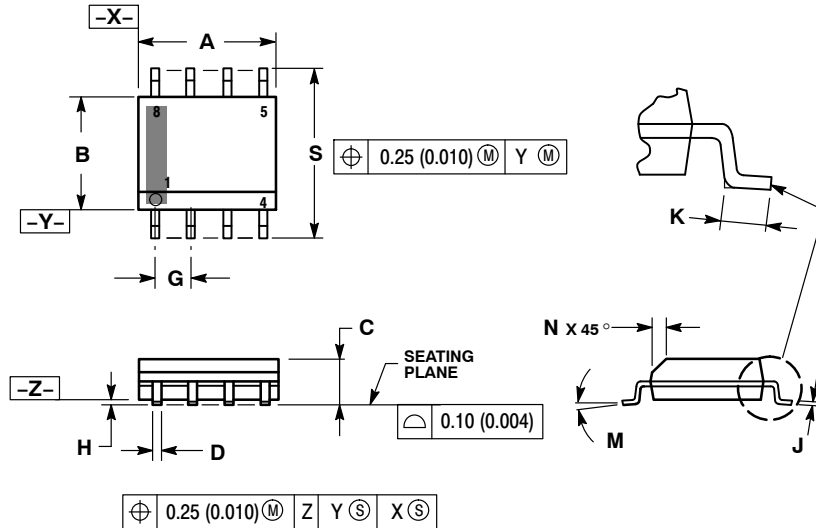
1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: INCHES.
3. DIMENSION E IS MEASURED WITH THE LEADS RESTRAINED PARALLEL AT WIDTH E2.
4. DIMENSION E1 DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES			MILLIMETERS		
	MIN	NOM	MAX	MIN	NOM	MAX
A	----	----	0.210	----	----	5.33
A1	0.015	----	----	0.38	----	----
b	0.014	0.018	0.022	0.35	0.46	0.56
C	0.008	0.010	0.014	0.20	0.25	0.36
D	0.355	0.365	0.400	9.02	9.27	10.02
D1	0.005	----	----	0.13	----	----
E	0.300	0.310	0.325	7.62	7.87	8.26
E1	0.240	0.250	0.280	6.10	6.35	7.11
E2	0.300 BSC			7.62 BSC		
E3	----	----	0.430	----	----	10.92
e	0.100 BSC			2.54 BSC		
L	0.115	0.130	0.150	2.92	3.30	3.81

MC33039, NCV33039

PACKAGE DIMENSIONS

SOIC-8 NB CASE 751-07 ISSUE AK

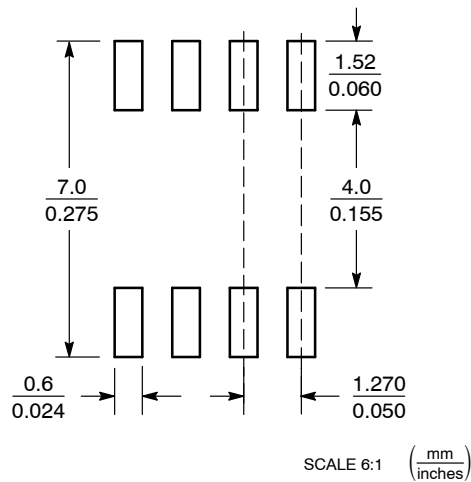


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.
6. 751-01 THRU 751-06 ARE OBSOLETE. NEW STANDARD IS 751-07.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.80	5.00	0.189	0.197
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.053	0.069
D	0.33	0.51	0.013	0.020
G	1.27 BSC		0.050 BSC	
H	0.10	0.25	0.004	0.010
J	0.19	0.25	0.007	0.010
K	0.40	1.27	0.016	0.050
M	0°	8°	0°	8°
N	0.25	0.50	0.010	0.020
S	5.80	6.20	0.228	0.244

SOLDERING FOOTPRINT*



*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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