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MB9B110T Series

32-bit ARM® Cortex®-M3 based Microcontroller
MB9BF116S/T, MB9BF117S/T, MB9BF118S/T

Data Sheet (Full Production)

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Publication Number MB9B110T-DS706-00016 Revision 3.0 Issue Date February 10, 2015

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When a product has been in production for a period of time such that no changes or only nominal changes are expected, the Preliminary designation is removed from the data sheet. Nominal changes may include those affecting the number of ordering part numbers available, such as the addition or deletion of a speed option, temperature range, package type, or VIO range. Changes may also include those needed to clarify a description or to correct a typographical error or incorrect specification. Spansion Inc. applies the following conditions to documents in this category:

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Data Sheet (Full Production)

■ Description

The MB9B110T Series are highly integrated 32-bit microcontrollers dedicated for embedded controllers with high-performance and competitive cost.

These series are based on the ARM Cortex-M3 Processor with on-chip Flash memory and SRAM, and have peripheral functions such as Motor Control Timers, ADCs and Communication Interfaces (UART, CSIO, I^2C, LIN).

The products which are described in this data sheet are placed into TYPE2 product categories in "FM3 Family PERIPHERAL MANUAL".

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■ Features

- 32-bit ARM Cortex-M3 Core
  - Processor version: r2p1
  - Up to 144 MHz Frequency Operation
  - Memory Protection Unit (MPU):improves the reliability of an embedded system
  - Integrated Nested Vectored Interrupt Controller (NVIC): 1 NMI (non-maskable interrupt) and 48 peripheral interrupts and 16 priority levels
  - 24-bit System timer (Sys Tick): System timer for OS task management

- On-chip Memories

[Flash memory]
  - Up to 1 Mbyte
  - Built-in Flash memory Accelerator System with 16 Kbyte trace buffer memory
    The read access to Flash memory can be achieved without wait cycle up to the operation frequency of 72MHz. Even at the operation frequency more than 72 MHz, an equivalent access to Flash memory can be obtained by Flash memory Accelerator System.
  - Security function for code protection

[SRAM]
This Series on-chip SRAM is composed of two independent SRAMs (SRAM0,SRAM1) . SRAM0 is connected to I-code bus and D-code bus of Cortex-M3 core. SRAM1 is connected to System bus.

  - SRAM0: Up to 64 Kbytes.
  - SRAM1: Up to 64 Kbytes.

- External Bus Interface
  - Supports SRAM, NOR and NAND Flash memory devices
  - Up to 8 chips selected
  - 8-/16-bit Data width
  - Up to 25-bit Address bit
  - Maximum area size : Up to 256 Mbytes
  - Supports Address/Data multiplex
  - Supports external RDY function

- Multi-function Serial Interface (Max 8 channels)
  - 4 channels with 16steps×9-bit FIFO (ch.4 to ch.7), 4 channels without FIFO (ch.0 to ch.3)
  - Operation mode is selectable from the followings for each channel.
    - UART
    - CSIO
    - LIN
    - I^2C

[UART]
  - Full-duplex double buffer
  - Selection with or without parity supported
  - Built-in dedicated baud rate generator
  - External clock available as a serial clock
  - Hardware Flow control : Automatically controls the transmission/reception with CTS/RTS (only for ch.4)
  - Various error detection functions available (parity errors, framing errors, and overrun errors)

[CSIO]
  - Full-duplex double buffer
  - Built-in dedicated baud rate generator
  - Overrun error detection function available

[LIN]
- LIN protocol Rev.2.1 supported
- Full-duplex double buffer
- Master/Slave mode supported
- LIN break field generation (can be changed to 13-bit length to 16-bit)
- LIN break delimiter generation (can be changed to 1-bit length to 4-bit)
- Various error detection functions available (parity errors, framing errors, and overrun errors)

[I^2C]

Standard-mode (Max 100 kbps) / Fast-mode (Max 400 kbps) supported

・ DMA Controller (8 channels)

The DMA Controller has a dedicated bus independent from the CPU, so CPU and DMA Controller can process simultaneously.

- 8 independently configured and operated channels
- Transfer can be started by software or request from the built-in peripherals
- Transfer address area: 32 bits (4 Gbytes)
- Transfer mode: Block transfer/Burst transfer/Demand transfer
- Transfer data type: byte/half-word/word
- Transfer block count: 1 to 16
- Number of transfers: 1 to 65536

・ A/D Converter (Max 32 channels)

[12-bit A/D Converter]
- Successive Approximation type
- Built-in 3units
- Conversion time: 1.0µs @ 5V
- Priority conversion available (priority at 2 levels)
- Scanning conversion mode
- Built-in FIFO for conversion data storage (for SCAN conversion: 16steps, for Priority conversion: 4steps)

・ Base Timer (Max 16 channels)

Operation mode is selectable from the followings for each channel.

- 16-bit PWM timer
- 16-bit PPG timer
- 16-/32-bit reload timer
- 16-/32-bit PWC timer

・ General-Purpose I/O Port

This series can use its pins as I/O ports when they are not used for an external bus or peripherals. Moreover, the port relocate function is built in. It can set which I/O port the peripheral function can be allocated to.

- Capable of pull-up control per pin
- Capable of reading pin level directly
- Built-in port relocate function
- Up to 154 fast I/O Ports@ 176 pin Package
- Some ports are 5 V tolerant I/O.
  See "■Pin Description" to confirm the corresponding pins.

- Multi-function Timer (Max 3 units)

  The Multi-function timer is composed of the following blocks.

  - 16-bit free-run timer × 3ch./unit
  - Input capture × 4ch./unit
  - Output compare × 6ch./unit
  - A/D activation compare × 3ch./unit
  - Waveform generator × 3ch./unit
  - 16-bit PPG timer × 3ch./unit

  The following function can be used to achieve the motor control.

  - PWM signal output function
  - DC chopper waveform output function
  - Dead time function
  - Input capture function
  - A/D convertor activate function
  - DTIF (Motor emergency stop) interrupt function

- Quadrature Position/Revolution Counter (QPRC) (Max 3 channels)

  The Quadrature Position/Revolution Counter (QPRC) is used to measure the position of the position encoder. Moreover, it is possible to use the counter as the up/down counter.

  - The detection edge of three external event input pins AIN, BIN and ZIN is configurable.
  - 16-bit position counter
  - 16-bit revolution counter
  - Two 16-bit compare registers

- Dual Timer (32-/16-bit Down Counter)

  The Dual Timer consists of two programmable 32-/16-bit down counters.
  Operation mode is selectable from the followings for each channel.

  - Free-running
  - Periodic (=Reload)
  - One-shot

- Watch Counter

  The Watch counter is used for wake up from low-power consumption mode.

  Interval timer: up to 64 s(Max)@ Sub Clock : 32.768 kHz

- External Interrupt Controller Unit
  - Up to 32 external interrupt input pins
  - One non-maskable interrupt (NMI) pin

- Watchdog Timer (2 channels)

  A watchdog timer can generate interrupts or a reset when a time-out value is reached.

  This series consists of two different watchdogs, a "Hardware" watchdog and a "Software" watchdog.

  The "Hardware" watchdog timer is operated by the built-in low-speed CR oscillator. Therefore, the "Hardware" watchdog is active in any low-power consumption mode except STOP mode.

- CRC (Cyclic Redundancy Check) Accelerator

  The CRC accelerator calculates the CRC which has a heavy software processing load, and achieves a reduction of the integrity check processing load for reception data and storage.

  CCITT CRC16 and IEEE-802.3 CRC32 are supported.

  - CCITT CRC16 Generator Polynomial: 0x1021
  - IEEE-802.3 CRC32 Generator Polynomial: 0x04C11DB7

- Clock and Reset

[Clocks]

Selectable from five clock sources (2 external oscillators, 2 built-in CR oscillators, and Main PLL).

- Main Clock: 4 MHz to 48 MHz
- Sub Clock: 32.768 kHz
- Built-in high-speed CR Clock: 4 MHz
- Built-in low-speed CR Clock: 100 kHz
- Main PLL Clock

[Resets]

- Reset requests from INITX pin
- Power-on reset
- Software reset
- Watchdog timers reset
- Low-voltage detection reset
- Clock supervisor reset

- Clock Super Visor (CSV)

  Clocks generated by built-in CR oscillators are used to supervise abnormality of the external clocks.

  - When external clock failure (clock stop) is detected, reset is asserted.
  - When external frequency anomaly is detected, interrupt or reset is asserted.

- Low-Voltage Detector (LVD)

  This Series includes 2-stage monitoring of voltage on the VCC pins. When the voltage falls below the voltage set, Low Voltage Detector generates an interrupt or reset.

  - LVD1: error reporting via interrupt
  - LVD2: auto-reset operation

- Low-Power Consumption Mode

  Three Low-Power Consumption modes supported.

  - SLEEP
  - TIMER
  - STOP

- Debug
  - Serial Wire JTAG Debug Port (SWJ-DP)
  - Embedded Trace Macrocells (ETM).

- Power Supply

  Wide range voltage VCC = 2.7 V to 5.5 V

■ Product Lineup

・ Memory size

Product name	MB9BF116S/T	MB9BF117S/T	MB9BF118S/T
On-chip Flash memory	512 Kbytes	768 Kbytes	1 Mbytes
On-chip SRAM	64 Kbytes	96 Kbytes	128 Kbytes

・ Function

Product name			MB9BF116S MB9BF117S MB9BF118S	MB9BF116T MB9BF117T MB9BF118T
Pin count			144	176/192
CPU			Cortex-M3	
	Freq.		144 MHz	
Supply voltage range			2.7 V to 5.5 V	
DMAC			8ch	
External Bus Interface			Addr:19-bit (Max) R/Wdata:8-/16-bit (Max) CS: 8 (Max) Support: SRAM, NOR & NAND Flash memory	Addr:25-bit (Max) R/Wdata:8-/16-bit (Max) CS:8 (Max) Support: SRAM, NOR & NAND Flash memory
Multi-function Serial Interface (UART/CSIO/LIN/I^{2}C)			8ch. (Max) ch.4 to ch.7: FIFO (16steps ×9 bits) ch.0 to ch.3: No FIFO	
Base Timer (PWC/ Reload timer/PWM/PPG)			16ch. (Max)	
MF-Timer	A/D activation compare	3ch.	3 units (Max)	
	Input capture	4ch.		
	Free-run timer	3ch.		
	Output compare	6ch.		
	Waveform generator	3ch.		
	PPG	3ch.		
QPRC			3ch. (Max)	
Dual Timer			1 unit	
Watch Counter			1 unit	
CRC Accelerator			Yes	
Watchdog timer			1ch. (SW) + 1ch. (HW)	
External Interrupts			32 pins (Max) + NMI pin× 1	
I/O ports			122 pins (Max)	154 pins (Max)
12-bit A/D converter			24ch. (3 units)	32ch. (3 units)
CSV (Clock Super Visor)			Yes	
LVD (Low-Voltage Detector)			2ch.	
Built-in CR	High-speed		4 MHz	
	Low-speed		100 kHz	
Debug Function			SWJ-DP/ETM	

Note: All signals of the peripheral function in each product cannot be allocated due to the pin count restriction of a package. It is necessary to use the port relocate function of the I/O port according to functions used. See "■ Electrical Characteristics 4.AC Characteristics (3)Built-in CR Oscillation Characteristics" for accuracy of built-in CR.

■ Packages

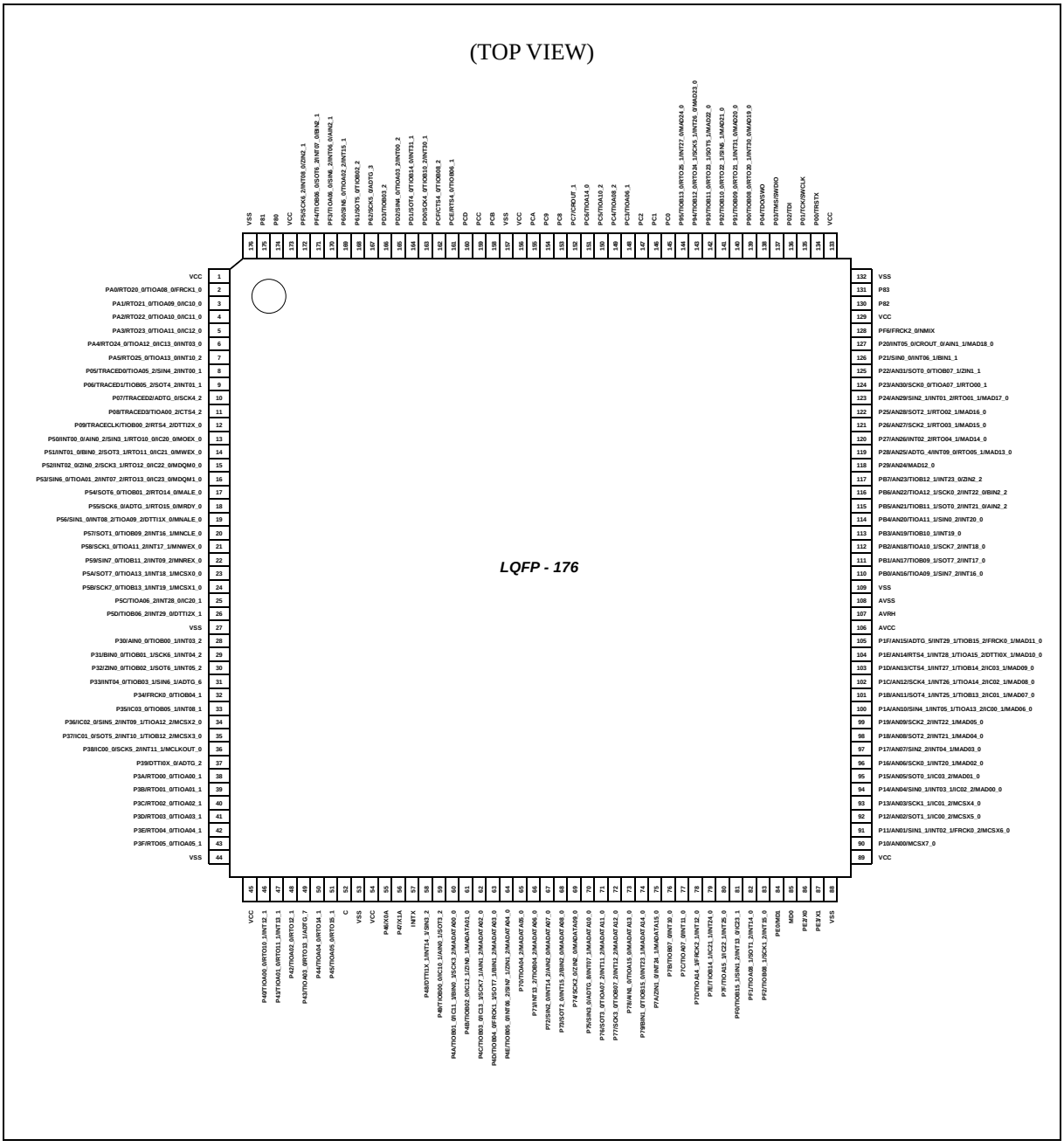
Package \ Product name	MB9BF116S MB9BF117S MB9BF118S	MB9BF116T MB9BF117T MB9BF118T
LQFP:FPT-144P-M08 (0.5 mm pitch)	❍	-
LQFP:FPT-176P-M07 (0.5 mm pitch)	-	❍
BGA:BGA-192P-M06 (0.8 mm pitch)	-	❍

❍: Supported

Note: See "■Package Dimensions" for detailed information on each package.

■ Pin Assignment

・ FPT-176P-M07

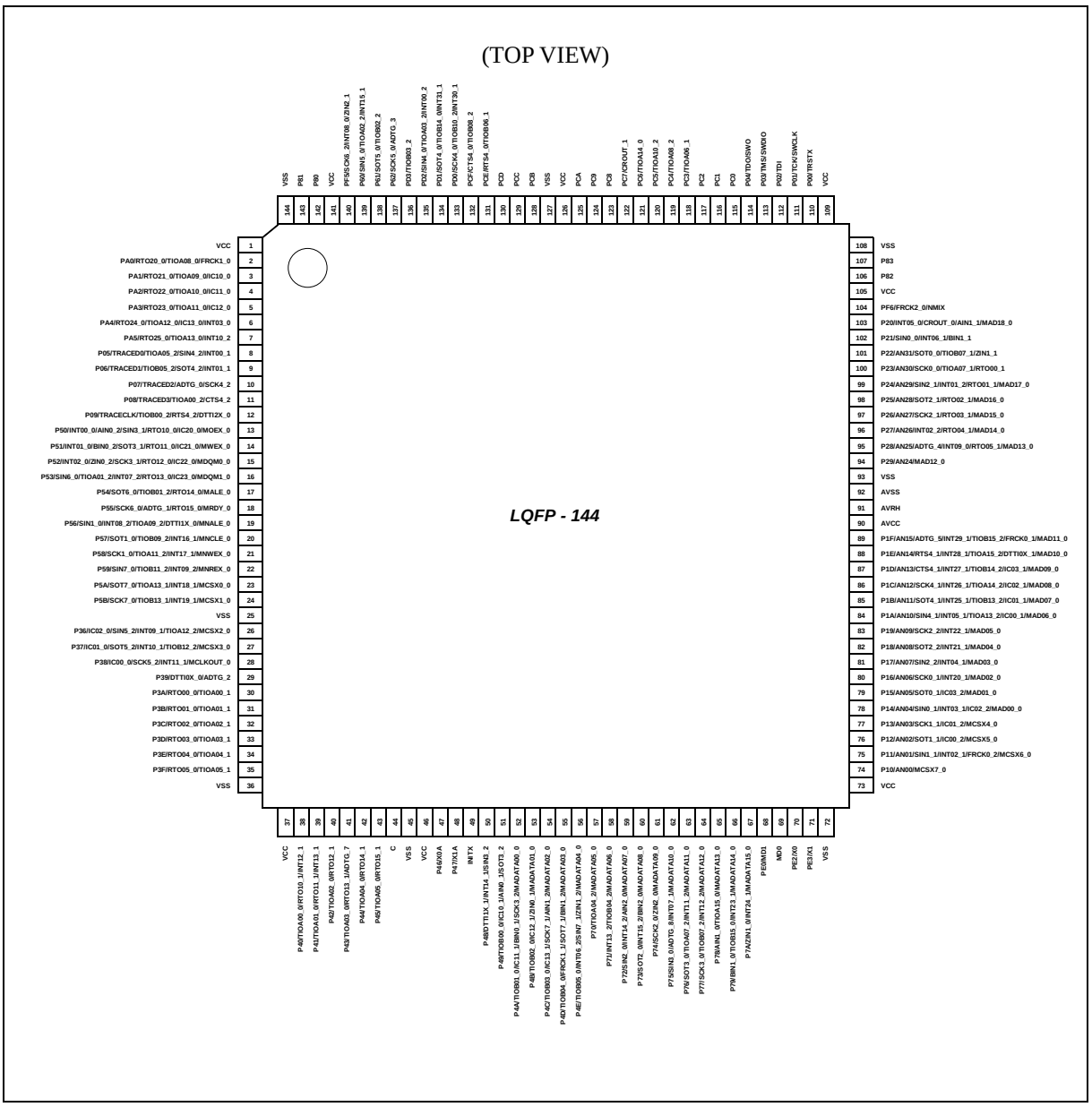


<Note>

The number after the underscore ("_") in pin names such as XXX_1 and XXX_2 indicates the relocated port number. For these pins, there are multiple pins that provide the same function for the same channel. Use the extended port function register (EPFR) to select the pin.

TIOA09_0, TIOA09_1, and TIOA09_2 cannot be used as the external startup trigger input (TGIN signal) at I/O mode 1 (timer full mode) of the Base Timer. See "●Base Timer" in "■Handling Devices" for details.

・ FPT-144P-M08

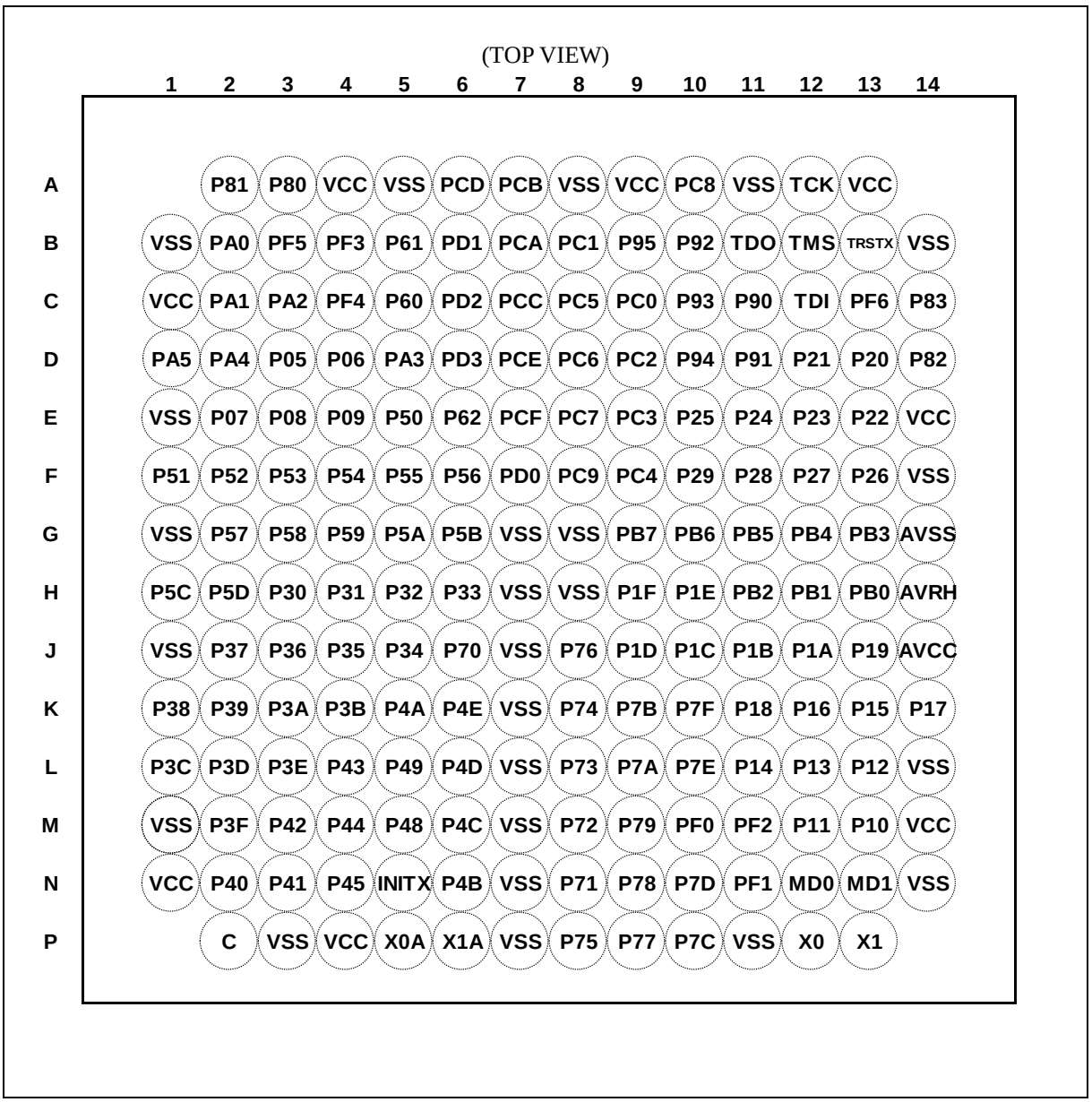


<Note>

The number after the underscore ("_") in pin names such as XXX_1 and XXX_2 indicates the relocated port number. For these pins, there are multiple pins that provide the same function for the same channel. Use the extended port function register (EPFR) to select the pin.

TIOA09_0, TIOA09_1, and TIOA09_2 cannot be used as the external startup trigger input (TGIN signal) at I/O mode 1 (timer full mode) of the Base Timer. See "●Base Timer" in "■Handling Devices" for details.

・ BGA-192P-M06



<Note>

The number after the underscore ("_") in pin names such as XXX_1 and XXX_2 indicates the relocated port number. For these pins, there are multiple pins that provide the same function for the same channel. Use the extended port function register (EPFR) to select the pin.

TIOA09_0, TIOA09_1, and TIOA09_2 cannot be used as the external startup trigger input (TGIN signal) at I/O mode 1 (timer full mode) of the Base Timer. See "●Base Timer" in "■Handling Devices" for details.

■ List of Pin Functions

- List of pin numbers

  The number after the underscore ("_") in pin names such as XXX_1 and XXX_2 indicates the relocated port number. For these pins, the same function is provided on the same channel. Use the extended port function register (EPFR) to select the pin.

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
1	1	C1	VCC	-	
2	2	B2	PA0	G	I
			RTO20_0		
			TIOA08_0		
			FRCK1_0		
3	3	C2	PA1	G	I
			RTO21_0		
			TIOA09_0		
			IC10_0		
4	4	C3	PA2	G	I
			RTO22_0		
			TIOA10_0		
			IC11_0		
5	5	D5	PA3	G	I
			RTO23_0		
			TIOA11_0		
			IC12_0		
6	6	D2	PA4	G	H
			RTO24_0		
			TIOA12_0		
			IC13_0		
			INT03_0		
7	7	D1	PA5	G	H
			RTO25_0		
			TIOA13_0		
			INT10_2		
8	8	D3	P05	E	F
			TRACED0		
			TIOA05_2		
			SIN4_2		
			INT00_1		
9	9	D4	P06	E	F
			TRACED1		
			TIOB05_2		
			SOT4_2		
			INT01_1		

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
10	10	E2	P07	E	G
			TRACED2		
			ADTG_0		
			SCK4_2		
11	11	E3	P08	E	G
			TRACED3		
			TIOA00_2		
			CTS4_2		
12	12	E4	P09	E	G
			TRACECLK		
			TIOB00_2		
			RTS4_2		
			DTTI2X_0		
13	13	E5	P50	E	H
			INT00_0		
			AIN0_2		
			SIN3_1		
			RTO10_0		
			IC20_0		
			MOEX_0		
14	14	F1	P51	E	H
			INT01_0		
			BIN0_2		
			SOT3_1		
			RTO11_0		
			IC21_0		
			MWEX_0		
15	15	F2	P52	E	H
			INT02_0		
			ZIN0_2		
			SCK3_1		
			RTO12_0		
			IC22_0		
			MDQM0_0		

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
16	16	F3	P53 SIN6_0 TIOA01_2 INT07_2 RTO13_0 IC23_0 MDQM1_0	E	H
17	17	F4	P54 SOT6_0 TIOB01_2 RTO14_0 MALE_0	E	I
18	18	F5	P55 SCK6_0 ADTG_1 RTO15_0 MRDY_0	E	I
19	19	F6	P56 SIN1_0 INT08_2 TIOA09_2 DTTI1X_0 MNALE_0	E	H
20	20	G2	P57 SOT1_0 TIOB09_2 INT16_1 MNCLE_0	E	H
21	21	G3	P58 SCK1_0 TIOA11_2 INT17_1 MNWEX_0	E	H
22	22	G4	P59 SIN7_0 TIOB11_2 INT09_2 MNREX_0	E	H

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
23	23	G5	P5A SOT7_0 TIOA13_1 INT18_1 MCSX0_0	E	H
24	24	G6	P5B SCK7_0 TIOB13_1 INT19_1 MCSX1_0	E	H
25	-	H1	P5C TIOA06_2 INT28_0 IC20_1	E	H
26	-	H2	P5D TIOB06_2 INT29_0 DTTI2X_1	E	H
27	25	J1	VSS	-	
28	-	H3	P30 AIN0_0 TIOB00_1 INT03_2	E	H
29	-	H4	P31 BIN0_0 TIOB01_1 SCK6_1 INT04_2	E	H
30	-	H5	P32 ZIN0_0 TIOB02_1 SOT6_1 INT05_2	E	H
31	-	H6	P33 INT04_0 TIOB03_1 SIN6_1 ADTG_6	E	H

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
32	-	J5	P34 FRCK0_0 TIOB04_1	E	I
33	-	J4	P35 IC03_0 TIOB05_1 INT08_1	E	H
34	26	J3	P36 IC02_0 SIN5_2 INT09_1 TIOA12_2 MCSX2_0	E	H
35	27	J2	P37 IC01_0 SOT5_2 INT10_1 TIOB12_2 MCSX3_0	E	H
36	28	K1	P38 IC00_0 SCK5_2 INT11_1 MCLKOUT_0	E	H
37	29	K2	P39 DTTI0X_0 ADTG_2	E	I
38	30	K3	P3A RTO00_0 TIOA00_1	G	I
39	31	K4	P3B RTO01_0 TIOA01_1	G	I
40	32	L1	P3C RTO02_0 TIOA02_1	G	I

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
41	33	L2	P3D	G	I
			RTO03_0		
			TIOA03_1		
42	34	L3	P3E	G	I
			RTO04_0		
			TIOA04_1		
43	35	M2	P3F	G	I
			RTO05_0		
			TIOA05_1		
44	36	M1	VSS	-	
45	37	N1	VCC	-	
46	38	N2	P40	G	H
			TIOA00_0		
			RTO10_1		
			INT12_1		
47	39	N3	P41	G	H
			TIOA01_0		
			RTO11_1		
			INT13_1		
48	40	M3	P42	G	I
			TIOA02_0		
			RTO12_1		
49	41	L4	P43	G	I
			TIOA03_0		
			RTO13_1		
			ADTG_7		
50	42	M4	P44	G	I
			TIOA04_0		
			RTO14_1		
51	43	N4	P45	G	I
			TIOA05_0		
			RTO15_1		
52	44	P2	C	-	
53	45	P3	VSS	-	
54	46	P4	VCC	-	
55	47	P5	P46	D	M
			X0A		
56	48	P6	P47	D	N
			X1A		
57	49	N5	INITX	B	C
58	50	M5	P48	E	H
			DTTI1X_1		
			INT14_1		
			SIN3_2		

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
59	51	L5	P49	E	I
			TIOB00_0		
			IC10_1		
			AIN0_1		
			SOT3_2		
60	52	K5	P4A	E	I
			TIOB01_0		
			IC11_1		
			BIN0_1		
			SCK3_2		
			MADATA00_0		
61	53	N6	P4B	E	I
			TIOB02_0		
			IC12_1		
			ZIN0_1		
			MADATA01_0		
62	54	M6	P4C	E	I
			TIOB03_0		
			IC13_1		
			SCK7_1		
			AIN1_2		
			MADATA02_0		
63	55	L6	P4D	E	I
			TIOB04_0		
			FRCK1_1		
			SOT7_1		
			BIN1_2		
			MADATA03_0		
64	56	K6	P4E	E	H
			TIOB05_0		
			INT06_2		
			SIN7_1		
			ZIN1_2		
			MADATA04_0		
65	57	J6	P70	E	I
			TIOA04_2		
			MADATA05_0		
66	58	N8	P71	E	H
			INT13_2		
			TIOB04_2		
			MADATA06_0		

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
67	59	M8	P72 SIN2_0 INT14_2 AIN2_0 MADATA07_0	E	H
68	60	L8	P73 SOT2_0 INT15_2 BIN2_0 MADATA08_0	E	H
69	61	K8	P74 SCK2_0 ZIN2_0 MADATA09_0	E	I
70	62	P8	P75 SIN3_0 ADTG_8 INT07_1 MADATA10_0	E	H
71	63	J8	P76 SOT3_0 TIOA07_2 INT11_2 MADATA11_0	E	H
72	64	P9	P77 SCK3_0 TIOB07_2 INT12_2 MADATA12_0	E	H
73	65	N9	P78 AIN1_0 TIOA15_0 MADATA13_0	E	I
74	66	M9	P79 BIN1_0 TIOB15_0 INT23_1 MADATA14_0	E	H
-	-	E1	VSS	-	
-	-	G1	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
75	67	L9	P7A ZIN1_0 INT24_1 MADATA15_0	E	H
76	-	K9	P7B TIOB07_0 INT10_0	E	H
77	-	P10	P7C TIOA07_0 INT11_0	E	H
78	-	N10	P7D TIOA14_1 FRCK2_1 INT12_0	E	H
79	-	L10	P7E TIOB14_1 IC21_1 INT24_0	E	H
80	-	K10	P7F TIOA15_1 IC22_1 INT25_0	E	H
81	-	M10	PF0 TIOB15_1 SIN1_2 INT13_0 IC23_1	I*	H
82	-	N11	PF1 TIOA08_1 SOT1_2 INT14_0	I*	H
83	-	M11	PF2 TIOB08_1 SCK1_2 INT15_0	I*	H
84	68	N13	PE0 MD1	C	P
85	69	N12	MD0	J	D
86	70	P12	PE2 X0	A	A
87	71	P13	PE3 X1	A	B
88	72	N14	VSS	-	
89	73	M14	VCC	-	
-	-	L7	VSS	-	
-	-	K7	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
90	74	M13	P10	F	K
			AN00		
			MCSX7_0		
91	75	M12	P11	F	L
			AN01		
			SIN1_1		
			INT02_1		
			FRCK0_2		
			MCSX6_0		
92	76	L13	P12	F	K
			AN02		
			SOT1_1		
			IC00_2		
			MCSX5_0		
93	77	L12	P13	F	K
			AN03		
			SCK1_1		
			IC01_2		
			MCSX4_0		
94	78	L11	P14	F	L
			AN04		
			SIN0_1		
			INT03_1		
			IC02_2		
			MAD00_0		
95	79	K13	P15	F	K
			AN05		
			SOT0_1		
			IC03_2		
			MAD01_0		
96	80	K12	P16	F	L
			AN06		
			SCK0_1		
			INT20_1		
			MAD02_0		
97	81	K14	P17	F	L
			AN07		
			SIN2_2		
			INT04_1		
			MAD03_0		
-	-	P7	VSS	-	
-	-	P11	VSS	-	
-	-	L14	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
98	82	K11	P18 AN08 SOT2_2 INT21_1 MAD04_0	F	L
99	83	J13	P19 AN09 SCK2_2 INT22_1 MAD05_0	F	L
100	84	J12	P1A AN10 SIN4_1 INT05_1 TIOA13_2 IC00_1 MAD06_0	F	L
101	85	J11	P1B AN11 SOT4_1 INT25_1 TIOB13_2 IC01_1 MAD07_0	F	L
102	86	J10	P1C AN12 SCK4_1 INT26_1 TIOA14_2 IC02_1 MAD08_0	F	L
103	87	J9	P1D AN13 CTS4_1 INT27_1 TIOB14_2 IC03_1 MAD09_0	F	L
104	88	H10	P1E AN14 RTS4_1 INT28_1 TIOA15_2 DTTI0X_1 MAD10_0	F	L

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
105	89	H9	P1F	F	L
			AN15		
			ADTG_5		
			INT29_1		
			TIOB15_2		
			FRCK0_1		
			MAD11_0		
106	90	J14	AVCC	-	
107	91	H14	AVRH	-	
108	92	G14	AVSS	-	
109	93	F14	VSS	-	
110	-	H13	PB0	F	L
			AN16		
			TIOA09_1		
			SIN7_2		
			INT16_0		
111	-	H12	PB1	F	L
			AN17		
			TIOB09_1		
			SOT7_2		
			INT17_0		
112	-	H11	PB2	F	L
			AN18		
			TIOA10_1		
			SCK7_2		
			INT18_0		
113	-	G13	PB3	F	L
			AN19		
			TIOB10_1		
			INT19_0		
114	-	G12	PB4	F	L
			AN20		
			TIOA11_1		
			SIN0_2		
			INT20_0		
115	-	G11	PB5	F	L
			AN21		
			TIOB11_1		
			SOT0_2		
			INT21_0		
			AIN2_2		
-	-	G7	VSS	-	
-	-	J7	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
116	-	G10	PB6 AN22 TIOA12_1 SCK0_2 INT22_0 BIN2_2	F	L
117	-	G9	PB7 AN23 TIOB12_1 INT23_0 ZIN2_2	F	L
118	94	F10	P29 AN24 MAD12_0	F	K
119	95	F11	P28 AN25 ADTG_4 INT09_0 RTO05_1 MAD13_0	F	L
120	96	F12	P27 AN26 INT02_2 RTO04_1 MAD14_0	F	L
121	97	F13	P26 AN27 SCK2_1 RTO03_1 MAD15_0	F	K
122	98	E10	P25 AN28 SOT2_1 RTO02_1 MAD16_0	F	K
123	99	E11	P24 AN29 SIN2_1 INT01_2 RTO01_1 MAD17_0	F	L

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
124	100	E12	P23	F	K
			AN30		
			SCK0_0		
			TIOA07_1		
			RTO00_1		
125	101	E13	P22	F	K
			AN31		
			SOT0_0		
			TIOB07_1		
			ZIN1_1		
126	102	D12	P21	E	H
			SIN0_0		
			INT06_1		
			BIN1_1		
127	103	D13	P20	E	H
			INT05_0		
			CROUT_0		
			AIN1_1		
			MAD18_0		
128	104	C13	PF6	I*	J
			FRCK2_0		
			NMIX		
129	105	E14	VCC	-	
130	106	D14	P82	H	O
131	107	C14	P83	H	O
132	108	B14	VSS	-	
133	109	A13	VCC	-	
134	110	B13	P00	E	E
			TRSTX		
135	111	A12	P01	E	E
			TCK		
			SWCLK		
136	112	C12	P02	E	E
			TDI		
137	113	B12	P03	E	E
			TMS		
			SWDIO		
138	114	B11	P04	E	E
			TDO		
			SWO		
139	-	C11	P90	E	H
			TIOB08_0		
			RTO20_1		
			INT30_0		
			MAD19_0		
-	-	A8	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
140	-	D11	P91	E	H
			TIOB09_0		
			RTO21_1		
			INT31_0		
			MAD20_0		
141	-	B10	P92	E	I
			TIOB10_0		
			RTO22_1		
			SIN5_1		
			MAD21_0		
142	-	C10	P93	E	I
			TIOB11_0		
			RTO23_1		
			SOT5_1		
			MAD22_0		
143	-	D10	P94	E	H
			TIOB12_0		
			RTO24_1		
			SCK5_1		
			INT26_0		
			MAD23_0		
144	-	B9	P95	E	H
			TIOB13_0		
			RTO25_1		
			INT27_0		
			MAD24_0		
145	115	C9	PC0	K	Q
146	116	B8	PC1	K	Q
147	117	D9	PC2	K	Q
148	118	E9	PC3	K	Q
			TIOA06_1		
149	119	F9	PC4	K	Q
			TIOA08_2		
150	120	C8	PC5	K	Q
			TIOA10_2		
-	-	A5	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
151	121	D8	PC6	K	Q
			TIOA14_0		
152	122	E8	PC7	L	Q
			CROUT_1		
153	123	A10	PC8	K	Q
154	124	F8	PC9	K	Q
155	125	B7	PCA	K	Q
156	126	A9	VCC	-	
157	127	A11	VSS	-	
158	128	A7	PCB	L	Q
159	129	C7	PCC	K	Q
160	130	A6	PCD	K	Q
161	131	D7	PCE	L	Q
			RTS4_0		
			TIOB06_1		
162	132	E7	PCF	L	Q
			CTS4_0		
			TIOB08_2		
163	133	F7	PD0	L	R
			SCK4_0		
			TIOB10_2		
			INT30_1		
164	134	B6	PD1	L	R
			SOT4_0		
			TIOB14_0		
			INT31_1		
-	-	N7	VSS	-	
-	-	G8	VSS	-	
-	-	H7	VSS	-	
-	-	H8	VSS	-	

Pin No			Pin Name	I/O circuit type	Pin state type
LQFP-176	LQFP-144	BGA-192			
165	135	C6	PD2	L	R
			SIN4_0		
			TIOA03_2		
			INT00_2		
166	136	D6	PD3	L	Q
			TIOB03_2		
167	137	E6	P62	E	Q
			SCK5_0		
			ADTG_3		
168	138	B5	P61	E	I
			SOT5_0		
			TIOB02_2		
169	139	C5	P60	E	H
			SIN5_0		
			TIOA02_2		
			INT15_1		
170	-	B4	PF3	I*	H
			TIOA06_0		
			SIN6_2		
			INT06_0		
			AIN2_1		
171	-	C4	PF4	I*	H
			TIOB06_0		
			SOT6_2		
			INT07_0		
			BIN2_1		
172	140	B3	PF5	I*	H
			SCK6_2		
			INT08_0		
			ZIN2_1		
173	141	A4	VCC	-	
174	142	A3	P80	H	O
175	143	A2	P81	H	O
176	144	B1	VSS	-	
-	-	M7	VSS	-	

*: 5 V tolerant I/O

- List of pin functions

  The number after the underscore ("_") in pin names such as XXX_1 and XXX_2 indicates the relocated port number. For these pins, the same function is provided on the same channel. Use the extended port function register (EPFR) to select the pin.

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
ADC	ADTG_0	A/D converter external trigger input pin	10	10	E2
	ADTG_1		18	18	F5
	ADTG_2		37	29	K2
	ADTG_3		167	137	E6
	ADTG_4		119	95	F11
	ADTG_5		105	89	H9
	ADTG_6		31	-	H6
	ADTG_7		49	41	L4
	ADTG_8		70	62	P8
	AN00	A/D converter analog input pin ANxx describes ADC ch.xx	90	74	M13
	AN01		91	75	M12
	AN02		92	76	L13
	AN03		93	77	L12
	AN04		94	78	L11
	AN05		95	79	K13
	AN06		96	80	K12
	AN07		97	81	K14
	AN08		98	82	K11
	AN09		99	83	J13
	AN10		100	84	J12
	AN11		101	85	J11
	AN12		102	86	J10
	AN13		103	87	J9
	AN14		104	88	H10
	AN15		105	89	H9
	AN16		110	-	H13
	AN17		111	-	H12
	AN18		112	-	H11
	AN19		113	-	G13
	AN20		114	-	G12
	AN21		115	-	G11
	AN22		116	-	G10
	AN23		117	-	G9
	AN24		118	94	F10
	AN25		119	95	F11
	AN26		120	96	F12
	AN27		121	97	F13
	AN28		122	98	E10
	AN29		123	99	E11
	AN30		124	100	E12
	AN31		125	101	E13

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Base Timer 0	TIOA0_0	Base timer ch.0 TIOA pin	46	38	N2
	TIOA0_1		38	30	K3
	TIOA0_2		11	11	E3
	TIOB0_0	Base timer ch.0 TIOB pin	59	51	L5
	TIOB0_1		28	-	H3
	TIOB0_2		12	12	E4
Base Timer 1	TIOA1_0	Base timer ch.1 TIOA pin	47	39	N3
	TIOA1_1		39	31	K4
	TIOA1_2		16	16	F3
	TIOB1_0	Base timer ch.1 TIOB pin	60	52	K5
	TIOB1_1		29	-	H4
	TIOB1_2		17	17	F4
Base Timer 2	TIOA2_0	Base timer ch.2 TIOA pin	48	40	M3
	TIOA2_1		40	32	L1
	TIOA2_2		169	139	C5
	TIOB2_0	Base timer ch.2 TIOB pin	61	53	N6
	TIOB2_1		30	-	H5
	TIOB2_2		168	138	B5
Base Timer 3	TIOA3_0	Base timer ch.3 TIOA pin	49	41	L4
	TIOA3_1		41	33	L2
	TIOA3_2		165	135	C6
	TIOB3_0	Base timer ch.3 TIOB pin	62	54	M6
	TIOB3_1		31	-	H6
	TIOB3_2		166	136	D6
Base Timer 4	TIOA4_0	Base timer ch.4 TIOA pin	50	42	M4
	TIOA4_1		42	34	L3
	TIOA4_2		65	57	J6
	TIOB4_0	Base timer ch.4 TIOB pin	63	55	L6
	TIOB4_1		32	-	J5
	TIOB4_2		66	58	N8
Base Timer 5	TIOA5_0	Base timer ch.5 TIOA pin	51	43	N4
	TIOA5_1		43	35	M2
	TIOA5_2		8	8	D3
	TIOB5_0	Base timer ch.5 TIOB pin	64	56	K6
	TIOB5_1		33	-	J4
	TIOB5_2		9	9	D4
Base Timer 6	TIOA6_0	Base timer ch.6 TIOA pin	170	-	B4
	TIOA6_1		148	118	E9
	TIOA6_2		25	-	H1
	TIOB6_0	Base timer ch.6 TIOB pin	171	-	C4
	TIOB6_1		161	131	D7
	TIOB6_2		26	-	H2

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Base Timer 7	TIOA07_0	Base timer ch.7 TIOA pin	77	-	P10
	TIOA07_1		124	100	E12
	TIOA07_2		71	63	J8
	TIOB07_0	Base timer ch.7 TIOB pin	76	-	K9
	TIOB07_1		125	101	E13
	TIOB07_2		72	64	P9
Base Timer 8	TIOA08_0	Base timer ch.8 TIOA pin	2	2	B2
	TIOA08_1		82	-	N11
	TIOA08_2		149	119	F9
	TIOB08_0	Base timer ch.8 TIOB pin	139	-	C11
	TIOB08_1		83	-	M11
	TIOB08_2		162	132	E7
Base Timer 9	TIOA09_0	Base timer ch.9 TIOA pin	3	3	C2
	TIOA09_1		110	-	H13
	TIOA09_2		19	19	F6
	TIOB09_0	Base timer ch.9 TIOB pin	140	-	D11
	TIOB09_1		111	-	H12
	TIOB09_2		20	20	G2
Base Timer 10	TIOA10_0	Base timer ch.10 TIOA pin	4	4	C3
	TIOA10_1		112	-	H11
	TIOA10_2		150	120	C8
	TIOB10_0	Base timer ch.10 TIOB pin	141	-	B10
	TIOB10_1		113	-	G13
	TIOB10_2		163	133	F7
Base Timer 11	TIOA11_0	Base timer ch.11 TIOA pin	5	5	D5
	TIOA11_1		114	-	G12
	TIOA11_2		21	21	G3
	TIOB11_0	Base timer ch.11 TIOB pin	142	-	C10
	TIOB11_1		115	-	G11
	TIOB11_2		22	22	G4
Base Timer 12	TIOA12_0	Base timer ch.12 TIOA pin	6	6	D2
	TIOA12_1		116	-	G10
	TIOA12_2		34	26	J3
	TIOB12_0	Base timer ch.12 TIOB pin	143	-	D10
	TIOB12_1		117	-	G9
	TIOB12_2		35	27	J2
Base Timer 13	TIOA13_0	Base timer ch.13 TIOA pin	7	7	D1
	TIOA13_1		23	23	G5
	TIOA13_2		100	84	J12
	TIOB13_0	Base timer ch.13 TIOB pin	144	-	B9
	TIOB13_1		24	24	G6
	TIOB13_2		101	85	J11

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Base Timer 14	TIOA14_0	Base timer ch.14 TIOA pin	151	121	D8
	TIOA14_1		78	-	N10
	TIOA14_2		102	86	J10
	TIOB14_0	Base timer ch.14 TIOB pin	164	134	B6
	TIOB14_1		79	-	L10
	TIOB14_2		103	87	J9
Base Timer 15	TIOA15_0	Base timer ch.15 TIOA pin	73	65	N9
	TIOA15_1		80	-	K10
	TIOA15_2		104	88	H10
	TIOB15_0	Base timer ch.15 TIOB pin	74	66	M9
	TIOB15_1		81	-	M10
	TIOB15_2		105	89	H9
Debugger	SWCLK	Serial wire debug interface clock input	135	111	A12
	SWDIO	Serial wire debug interface data input / output	137	113	B12
	SWO	Serial wire viewer output	138	114	B11
	TCK	J-TAG test clock input	135	111	A12
	TDI	J-TAG test data input	136	112	C12
	TDO	J-TAG debug data output	138	114	B11
	TMS	J-TAG test mode state input/output	137	113	B12
	TRACECLK	Trace CLK output of ETM	12	12	E4
	TRACED0	Trace data output of ETM	8	8	D3
	TRACED1		9	9	D4
	TRACED2		10	10	E2
	TRACED3		11	11	E3
	TRSTX	J-TAG test reset input	134	110	B13

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
External Bus	MAD00_0	External bus interface address bus	94	78	L11
	MAD01_0		95	79	K13
	MAD02_0		96	80	K12
	MAD03_0		97	81	K14
	MAD04_0		98	82	K11
	MAD05_0		99	83	J13
	MAD06_0		100	84	J12
	MAD07_0		101	85	J11
	MAD08_0		102	86	J10
	MAD09_0		103	87	J9
	MAD10_0		104	88	H10
	MAD11_0		105	89	H9
	MAD12_0		118	94	F10
	MAD13_0		119	95	F11
	MAD14_0		120	96	F12
	MAD15_0		121	97	F13
	MAD16_0		122	98	E10
	MAD17_0		123	99	E11
	MAD18_0		127	103	D13
	MAD19_0		139	-	C11
	MAD20_0		140	-	D11
	MAD21_0		141	-	B10
	MAD22_0		142	-	C10
	MAD23_0		143	-	D10
	MAD24_0		144	-	B9
	MCSX0_0	External bus interface chip select output pin	23	23	G5
	MCSX1_0		24	24	G6
	MCSX2_0		34	26	J3
	MCSX3_0		35	27	J2
	MCSX4_0		93	77	L12
	MCSX5_0		92	76	L13
	MCSX6_0		91	75	M12
	MCSX7_0		90	74	M13
	MDQM0_0	External bus interface byte mask signal output	15	15	F2
	MDQM1_0		16	16	F3
	MOEX_0	External bus interface read enable signal for SRAM	13	13	E5
	MWEX_0	External bus interface write enable signal for SRAM	14	14	F1

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
External Bus	MNALE_0	External bus interface ALE signal to control NAND Flash memory output pin	19	19	F6
	MNCLE_0	External bus interface CLE signal to control NAND Flash memory output pin	20	20	G2
	MNREX_0	External bus interface read enable signal to control NAND Flash memory	22	22	G4
	MNWEX_0	External bus interface write enable signal to control NAND Flash memory	21	21	G3
	MADATA00_0	External bus interface data bus (Multiplexed bus to address output for multiplex)	60	52	K5
	MADATA01_0		61	53	N6
	MADATA02_0		62	54	M6
	MADATA03_0		63	55	L6
	MADATA04_0		64	56	K6
	MADATA05_0		65	57	J6
	MADATA06_0		66	58	N8
	MADATA07_0		67	59	M8
	MADATA08_0		68	60	L8
	MADATA09_0		69	61	K8
	MADATA10_0		70	62	P8
	MADATA11_0		71	63	J8
	MADATA12_0		72	64	P9
	MADATA13_0		73	65	N9
	MADATA14_0		74	66	M9
	MADATA15_0		75	67	L9
	MALE_0	Address Latch enable signal for multiplex	17	17	F4
	MRDY_0	External RDY input signal	18	18	F5
	MCLKOUT_0	External bus clock output	36	28	K1

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
External Interrupt	INT00_0	External interrupt request 00 input pin	13	13	E5
	INT00_1		8	8	D3
	INT00_2		165	135	C6
	INT01_0	External interrupt request 01 input pin	14	14	F1
	INT01_1		9	9	D4
	INT01_2		123	99	E11
	INT02_0	External interrupt request 02 input pin	15	15	F2
	INT02_1		91	75	M12
	INT02_2		120	96	F12
	INT03_0	External interrupt request 03 input pin	6	6	D2
	INT03_1		94	78	L11
	INT03_2		28	-	H3
	INT04_0	External interrupt request 04 input pin	31	-	H6
	INT04_1		97	81	K14
	INT04_2		29	-	H4
	INT05_0	External interrupt request 05 input pin	127	103	D13
	INT05_1		100	84	J12
	INT05_2		30	-	H5
	INT06_0	External interrupt request 06 input pin	170	-	B4
	INT06_1		126	102	D12
	INT06_2		64	56	K6
	INT07_0	External interrupt request 07 input pin	171	-	C4
	INT07_1		70	62	P8
	INT07_2		16	16	F3
	INT08_0	External interrupt request 08 input pin	172	140	B3
	INT08_1		33	-	J4
	INT08_2		19	19	F6
	INT09_0	External interrupt request 09 input pin	119	95	F11
	INT09_1		34	26	J3
	INT09_2		22	22	G4
	INT10_0	External interrupt request 10 input pin	76	-	K9
	INT10_1		35	27	J2
	INT10_2		7	7	D1
	INT11_0	External interrupt request 11 input pin	77	-	P10
	INT11_1		36	28	K1
	INT11_2		71	63	J8
	INT12_0	External interrupt request 12 input pin	78	-	N10
	INT12_1		46	38	N2
	INT12_2		72	64	P9
	INT13_0	External interrupt request 13 input pin	81	-	M10
	INT13_1		47	39	N3
	INT13_2		66	58	N8
	INT14_0	External interrupt request 14 input pin	82	-	N11
	INT14_1		58	50	M5
	INT14_2		67	59	M8

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
External Interrupt	INT15_0	External interrupt request 15 input pin	83	-	M11
	INT15_1		169	139	C5
	INT15_2		68	60	L8
	INT16_0	External interrupt request 16 input pin	110	-	H13
	INT16_1		20	20	G2
	INT17_0	External interrupt request 17 input pin	111	-	H12
	INT17_1		21	21	G3
	INT18_0	External interrupt request 18 input pin	112	-	H11
	INT18_1		23	23	G5
	INT19_0	External interrupt request 19 input pin	113	-	G13
	INT19_1		24	24	G6
	INT20_0	External interrupt request 20 input pin	114	-	G12
	INT20_1		96	80	K12
	INT21_0	External interrupt request 21 input pin	115	-	G11
	INT21_1		98	82	K11
	INT22_0	External interrupt request 22 input pin	116	-	G10
	INT22_1		99	83	J13
	INT23_0	External interrupt request 23 input pin	117	-	G9
	INT23_1		74	66	M9
	INT24_0	External interrupt request 24 input pin	79	-	L10
	INT24_1		75	67	L9
	INT25_0	External interrupt request 25 input pin	80	-	K10
	INT25_1		101	85	J11
	INT26_0	External interrupt request 26 input pin	143	-	D10
	INT26_1		102	86	J10
	INT27_0	External interrupt request 27 input pin	144	-	B9
	INT27_1		103	87	J9
	INT28_0	External interrupt request 28 input pin	25	-	H1
	INT28_1		104	88	H10
	INT29_0	External interrupt request 29 input pin	26	-	H2
	INT29_1		105	89	H9
	INT30_0	External interrupt request 30 input pin	139	-	C11
	INT30_1		163	133	F7
	INT31_0	External interrupt request 31 input pin	140	-	D11
	INT31_1		164	134	B6
	NMIX	Non-Maskable Interrupt input	128	104	C13

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
GPIO	P00	General-purpose I/O port 0	134	110	B13
	P01		135	111	A12
	P02		136	112	C12
	P03		137	113	B12
	P04		138	114	B11
	P05		8	8	D3
	P06		9	9	D4
	P07		10	10	E2
	P08		11	11	E3
	P09		12	12	E4
	P10	General-purpose I/O port 1	90	74	M13
	P11		91	75	M12
	P12		92	76	L13
	P13		93	77	L12
	P14		94	78	L11
	P15		95	79	K13
	P16		96	80	K12
	P17		97	81	K14
	P18		98	82	K11
	P19		99	83	J13
	P1A		100	84	J12
	P1B		101	85	J11
	P1C		102	86	J10
	P1D		103	87	J9
	P1E		104	88	H10
	P1F		105	89	H9
	P20	General-purpose I/O port 2	127	103	D13
	P21		126	102	D12
	P22		125	101	E13
	P23		124	100	E12
	P24		123	99	E11
	P25		122	98	E10
	P26		121	97	F13
	P27		120	96	F12
	P28		119	95	F11
	P29		118	94	F10

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
GPIO	P30	General-purpose I/O port 3	28	-	H3
	P31		29	-	H4
	P32		30	-	H5
	P33		31	-	H6
	P34		32	-	J5
	P35		33	-	J4
	P36		34	26	J3
	P37		35	27	J2
	P38		36	28	K1
	P39		37	29	K2
	P3A		38	30	K3
	P3B		39	31	K4
	P3C		40	32	L1
	P3D		41	33	L2
	P3E		42	34	L3
	P3F		43	35	M2
	P40	General-purpose I/O port 4	46	38	N2
	P41		47	39	N3
	P42		48	40	M3
	P43		49	41	L4
	P44		50	42	M4
	P45		51	43	N4
	P46		55	47	P5
	P47		56	48	P6
	P48		58	50	M5
	P49		59	51	L5
	P4A		60	52	K5
	P4B		61	53	N6
	P4C		62	54	M6
	P4D		63	55	L6
	P4E		64	56	K6
	P50	General-purpose I/O port 5	13	13	E5
	P51		14	14	F1
	P52		15	15	F2
	P53		16	16	F3
	P54		17	17	F4
	P55		18	18	F5
	P56		19	19	F6
	P57		20	20	G2
	P58		21	21	G3
	P59		22	22	G4
	P5A		23	23	G5
	P5B		24	24	G6
	P5C		25	-	H1
	P5D		26	-	H2

Module	Pin name	Function	Pin No.		
			LQFP-176	LQFP-144	BGA-192
GPIO	P60	General-purpose I/O port 6	169	139	C5
	P61		168	138	B5
	P62		167	137	E6
	P70	General-purpose I/O port 7	65	57	J6
	P71		66	58	N8
	P72		67	59	M8
	P73		68	60	L8
	P74		69	61	K8
	P75		70	62	P8
	P76		71	63	J8
	P77		72	64	P9
	P78		73	65	N9
	P79		74	66	M9
	P7A		75	67	L9
	P7B		76	-	K9
	P7C		77	-	P10
	P7D		78	-	N10
	P7E		79	-	L10
	P7F		80	-	K10
	P80	General-purpose I/O port 8	174	142	A3
	P81		175	143	A2
	P82		130	106	D14
	P83		131	107	C14
	P90	General-purpose I/O port 9	139	-	C11
	P91		140	-	D11
	P92		141	-	B10
	P93		142	-	C10
	P94		143	-	D10
	P95		144	-	B9
	PA0	General-purpose I/O port A	2	2	B2
	PA1		3	3	C2
	PA2		4	4	C3
	PA3		5	5	D5
	PA4		6	6	D2
	PA5		7	7	D1
	PB0	General-purpose I/O port B	110	-	H13
	PB1		111	-	H12
	PB2		112	-	H11
	PB3		113	-	G13
	PB4		114	-	G12
	PB5		115	-	G11
	PB6		116	-	G10
	PB7		117	-	G9

Module	Pin name	Function	Pin No.		
			LQFP-176	LQFP-144	BGA-192
GPIO	PC0	General-purpose I/O port C	145	115	C9
	PC1		146	116	B8
	PC2		147	117	D9
	PC3		148	118	E9
	PC4		149	119	F9
	PC5		150	120	C8
	PC6		151	121	D8
	PC7		152	122	E8
	PC8		153	123	A10
	PC9		154	124	F8
	PCA		155	125	B7
	PCB		158	128	A7
	PCC		159	129	C7
	PCD		160	130	A6
	PCE		161	131	D7
	PCF		162	132	E7
	PD0	General-purpose I/O port D	163	133	F7
	PD1		164	134	B6
	PD2		165	135	C6
	PD3		166	136	D6
	PE0	General-purpose I/O port E	84	68	N13
	PE2		86	70	P12
	PE3		87	71	P13
	PF0	General-purpose I/O port F*	81	-	M10
	PF1		82	-	N11
	PF2		83	-	M11
	PF3		170	-	B4
	PF4		171	-	C4
	PF5		172	140	B3
	PF6		128	104	C13

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Serial 0	SIN0_0	Multi-function serial interface ch.0 input pin	126	102	D12
	SIN0_1		94	78	L11
	SIN0_2		114	-	G12
	SOT0_0 (SDA0_0)	Multi-function serial interface ch.0 output pin. This pin operates as SOT0 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA0 when it is used in an I^2C (operation mode 4).	125	101	E13
	SOT0_1 (SDA0_1)		95	79	K13
	SOT0_2 (SDA0_2)		115	-	G11
	SCK0_0 (SCL0_0)	Multi-function serial interface ch.0 clock I/O pin. This pin operates as SCK0 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL0 when it is used in an I^2C (operation mode 4).	124	100	E12
	SCK0_1 (SCL0_1)		96	80	K12
	SCK0_2 (SCL0_2)		116	-	G10
Multi-Function Serial 1	SIN1_0	Multi-function serial interface ch.1 input pin	19	19	F6
	SIN1_1		91	75	M12
	SIN1_2		81	-	M10
	SOT1_0 (SDA1_0)	Multi-function serial interface ch.1 output pin. This pin operates as SOT1 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA1 when it is used in an I^2C (operation mode 4).	20	20	G2
	SOT1_1 (SDA1_1)		92	76	L13
	SOT1_2 (SDA1_2)		82	-	N11
	SCK1_0 (SCL1_0)	Multi-function serial interface ch.1 clock I/O pin. This pin operates as SCK1 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL1 when it is used in an I^2C (operation mode 4).	21	21	G3
	SCK1_1 (SCL1_1)		93	77	L12
	SCK1_2 (SCL1_2)		83	-	M11

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Serial 2	SIN2_0	Multi-function serial interface ch.2 input pin	67	59	M8
	SIN2_1		123	99	E11
	SIN2_2		97	81	K14
	SOT2_0 (SDA2_0)	Multi-function serial interface ch.2 output pin. This pin operates as SOT2 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA2 when it is used in an I^2C (operation mode 4).	68	60	L8
	SOT2_1 (SDA2_1)		122	98	E10
	SOT2_2 (SDA2_2)		98	82	K11
	SCK2_0 (SCL2_0)	Multi-function serial interface ch.2 clock I/O pin. This pin operates as SCK2 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL2 when it is used in an I^2C (operation mode 4).	69	61	K8
	SCK2_1 (SCL2_1)		121	97	F13
	SCK2_2 (SCL2_2)		99	83	J13
Multi-Function Serial 3	SIN3_0	Multi-function serial interface ch.3 input pin	70	62	P8
	SIN3_1		13	13	E5
	SIN3_2		58	50	M5
	SOT3_0 (SDA3_0)	Multi-function serial interface ch.3 output pin. This pin operates as SOT3 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA3 when it is used in an I^2C (operation mode 4).	71	63	J8
	SOT3_1 (SDA3_1)		14	14	F1
	SOT3_2 (SDA3_2)		59	51	L5
	SCK3_0 (SCL3_0)	Multi-function serial interface ch.3 clock I/O pin. This pin operates as SCK3 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL3 when it is used in an I^2C (operation mode 4).	72	64	P9
	SCK3_1 (SCL3_1)		15	15	F2
	SCK3_2 (SCL3_2)		60	52	K5

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Serial 4	SIN4_0	Multi-function serial interface ch.4 input pin	165	135	C6
	SIN4_1		100	84	J12
	SIN4_2		8	8	D3
	SOT4_0 (SDA4_0)	Multi-function serial interface ch.4 output pin. This pin operates as SOT4 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA4 when it is used in an I^2C (operation mode 4).	164	134	B6
	SOT4_1 (SDA4_1)		101	85	J11
	SOT4_2 (SDA4_2)		9	9	D4
	SCK4_0 (SCL4_0)	Multi-function serial interface ch.4 clock I/O pin. This pin operates as SCK4 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL4 when it is used in an I^2C (operation mode 4).	163	133	F7
	SCK4_1 (SCL4_1)		102	86	J10
	SCK4_2 (SCL4_2)		10	10	E2
	RTS4_0	Multi-function serial interface ch.4 RTS output pin	161	131	D7
	RTS4_1		104	88	H10
	RTS4_2		12	12	E4
	CTS4_0	Multi-function serial interface ch.4 CTS input pin	162	132	E7
	CTS4_1		103	87	J9
	CTS4_2		11	11	E3
Multi-Function Serial 5	SIN5_0	Multi-function serial interface ch.5 input pin	169	139	C5
	SIN5_1		141	-	B10
	SIN5_2		34	26	J3
	SOT5_0 (SDA5_0)	Multi-function serial interface ch.5 output pin. This pin operates as SOT5 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA5 when it is used in an I^2C (operation mode 4).	168	138	B5
	SOT5_1 (SDA5_1)		142	-	C10
	SOT5_2 (SDA5_2)		35	27	J2
	SCK5_0 (SCL5_0)	Multi-function serial interface ch.5 clock I/O pin. This pin operates as SCK5 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL5 when it is used in an I^2C (operation mode 4).	167	137	E6
	SCK5_1 (SCL5_1)		143	-	D10
	SCK5_2 (SCL5_2)		36	28	K1

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Serial 6	SIN6_0	Multi-function serial interface ch.6 input pin	16	16	F3
	SIN6_1		31	-	H6
	SIN6_2		170	-	B4
	SOT6_0 (SDA6_0)	Multi-function serial interface ch.6 output pin. This pin operates as SOT6 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA6 when it is used in an I^2C (operation mode 4).	17	17	F4
	SOT6_1 (SDA6_1)		30	-	H5
	SOT6_2 (SDA6_2)		171	-	C4
	SCK6_0 (SCL6_0)	Multi-function serial interface ch.6 clock I/O pin. This pin operates as SCK6 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL6 when it is used in an I^2C (operation mode 4).	18	18	F5
	SCK6_1 (SCL6_1)		29	-	H4
	SCK6_2 (SCL6_2)		172	140	B3
Multi-Function Serial 7	SIN7_0	Multi-function serial interface ch.7 input pin	22	22	G4
	SIN7_1		64	56	K6
	SIN7_2		110	-	H13
	SOT7_0 (SDA7_0)	Multi-function serial interface ch.7 output pin. This pin operates as SOT7 when it is used in a UART/CSIO (operation modes 0 to 2) and as SDA7 when it is used in an I^2C (operation mode 4).	23	23	G5
	SOT7_1 (SDA7_1)		63	55	L6
	SOT7_2 (SDA7_2)		111	-	H12
	SCK7_0 (SCL7_0)	Multi-function serial interface ch.7 clock I/O pin. This pin operates as SCK7 when it is used in a UART/CSIO (operation modes 0 to 2) and as SCL7 when it is used in an I^2C (operation mode 4).	24	24	G6
	SCK7_1 (SCL7_1)		62	54	M6
	SCK7_2 (SCL7_2)		112	-	H11

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Timer 0	DTTI0X_0	Input signal of waveform generator to control outputs RTO00 to RTO05 of multi-function timer 0.	37	29	K2
	DTTI0X_1		104	88	H10
	FRCK0_0	16-bit free-run timer ch.0 external clock input pin	32	-	J5
	FRCK0_1		105	89	H9
	FRCK0_2		91	75	M12
	IC00_0	16-bit input capture input pin of multi-function timer 0 ICxx describes channel number.	36	28	K1
	IC00_1		100	84	J12
	IC00_2		92	76	L13
	IC01_0		35	27	J2
	IC01_1		101	85	J11
	IC01_2		93	77	L12
	IC02_0		34	26	J3
	IC02_1		102	86	J10
	IC02_2		94	78	L11
	IC03_0		33	-	J4
	IC03_1		103	87	J9
	IC03_2		95	79	K13
	RTO00_0 (PPG00_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG00 when it is used in PPG0 output modes.	38	30	K3
	RTO00_1 (PPG00_1)		124	100	E12
	RTO01_0 (PPG00_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG00 when it is used in PPG0 output modes.	39	31	K4
	RTO01_1 (PPG00_1)		123	99	E11
	RTO02_0 (PPG02_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG02 when it is used in PPG0 output modes.	40	32	L1
	RTO02_1 (PPG02_1)		122	98	E10
	RTO03_0 (PPG02_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG02 when it is used in PPG0 output modes.	41	33	L2
	RTO03_1 (PPG02_1)		121	97	F13
	RTO04_0 (PPG04_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG04 when it is used in PPG0 output modes.	42	34	L3
	RTO04_1 (PPG04_1)		120	96	F12
	RTO05_0 (PPG04_0)	Waveform generator output of multi-function timer 0 This pin operates as PPG04 when it is used in PPG0 output modes.	43	35	M2
	RTO05_1 (PPG04_1)		119	95	F11

Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Timer 1	DTTI1X_0	Input signal of waveform generator to control outputs RTO10 to RTO15 of multi-function timer 1.	19	19	F6
	DTTI1X_1		58	50	M5
	FRCK1_0	16-bit free-run timer ch.1 external clock input pin	2	2	B2
	FRCK1_1		63	55	L6
	IC10_0	16-bit input capture input pin of multi-function timer 1. ICxx describes channel number	3	3	C2
	IC10_1		59	51	L5
	IC11_0		4	4	C3
	IC11_1		60	52	K5
	IC12_0		5	5	D5
	IC12_1		61	53	N6
	IC13_0		6	6	D2
	IC13_1		62	54	M6
	RTO10_0 (PPG10_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG10 when it is used in PPG1 output modes.	13	13	E5
	RTO10_1 (PPG10_1)		46	38	N2
	RTO11_0 (PPG10_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG10 when it is used in PPG1 output modes.	14	14	F1
	RTO11_1 (PPG10_1)		47	39	N3
	RTO12_0 (PPG12_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG12 when it is used in PPG1 output modes.	15	15	F2
	RTO12_1 (PPG12_1)		48	40	M3
	RTO13_0 (PPG12_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG12 when it is used in PPG1 output modes.	16	16	F3
	RTO13_1 (PPG12_1)		49	41	L4
	RTO14_0 (PPG14_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG14 when it is used in PPG1 output modes.	17	17	F4
	RTO14_1 (PPG14_1)		50	42	M4
	RTO15_0 (PPG14_0)	Waveform generator output of multi-function timer 1. This pin operates as PPG14 when it is used in PPG1 output modes.	18	18	F5
	RTO15_1 (PPG14_1)		51	43	N4

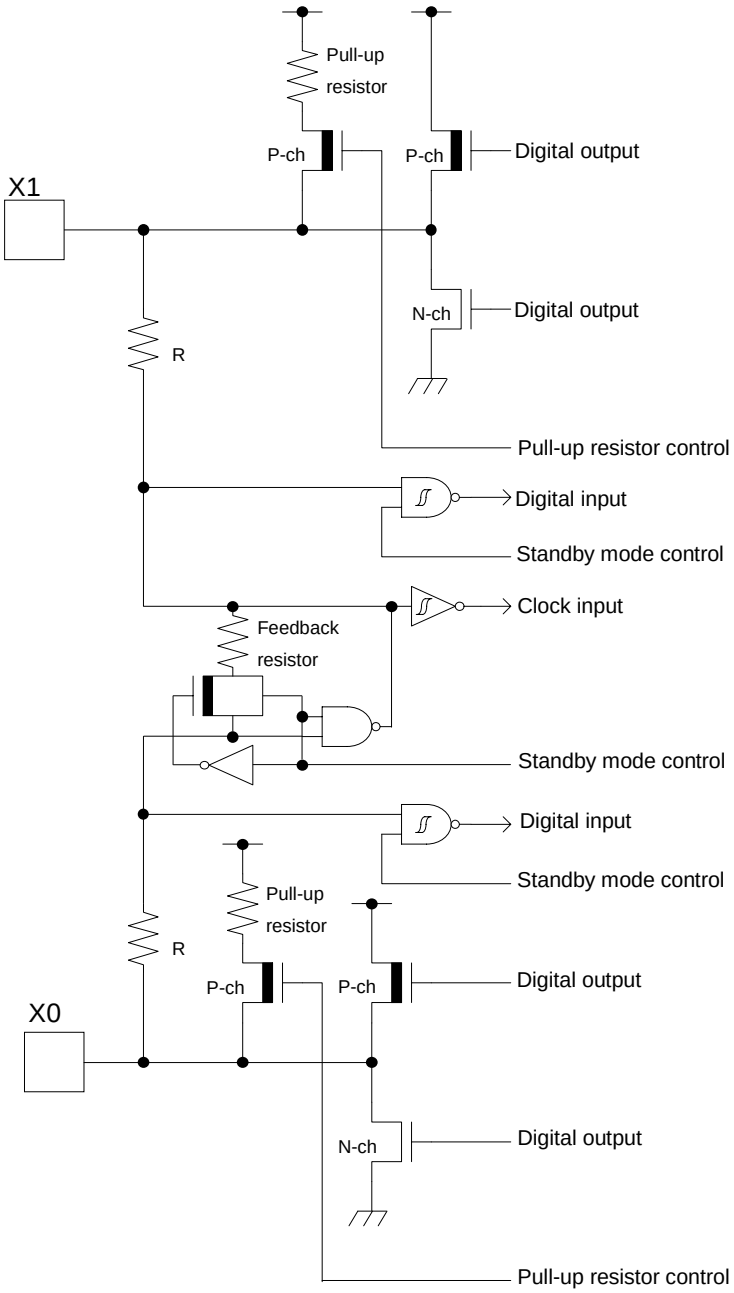
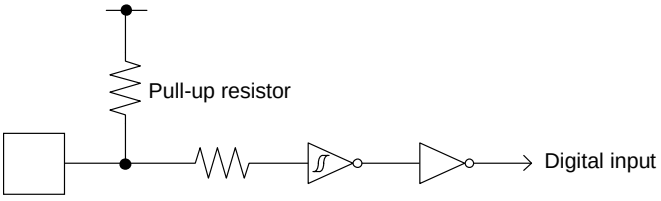
Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Multi-Function Timer 2	DTTI2X_0	Input signal of waveform generator to control outputs RTO20 to RTO25 of multi-function timer 2.	12	12	E4
	DTTI2X_1		26	-	H2
	FRCK2_0	16-bit free-run timer ch.2 external clock input pin	128	104	C13
	FRCK2_1		78	-	N10
	IC20_0	16-bit input capture input pin of multi-function timer 2. ICxx describes channel number.	13	13	E5
	IC20_1		25	-	H1
	IC21_0		14	14	F1
	IC21_1		79	-	L10
	IC22_0		15	15	F2
	IC22_1		80	-	K10
	IC23_0		16	16	F3
	IC23_1		81	-	M10
	RTO20_0 (PPG20_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG20 when it is used in PPG2 output modes.	2	2	B2
	RTO20_1 (PPG20_1)		139	-	C11
	RTO21_0 (PPG20_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG20 when it is used in PPG2 output modes.	3	3	C2
	RTO21_1 (PPG20_1)		140	-	D11
	RTO22_0 (PPG22_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG22 when it is used in PPG2 output modes.	4	4	C3
	RTO22_1 (PPG22_1)		141	-	B10
	RTO23_0 (PPG22_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG22 when it is used in PPG2 output modes.	5	5	D5
	RTO23_1 (PPG22_1)		142	-	C10
	RTO24_0 (PPG24_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG24 when it is used in PPG2 output modes.	6	6	D2
	RTO24_1 (PPG24_1)		143	-	D10
	RTO25_0 (PPG24_0)	Waveform generator output of multi-function timer 2. This pin operates as PPG24 when it is used in PPG2 output modes.	7	7	D1
	RTO25_1 (PPG24_1)		144	-	B9

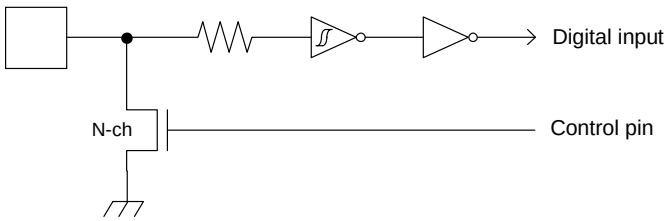
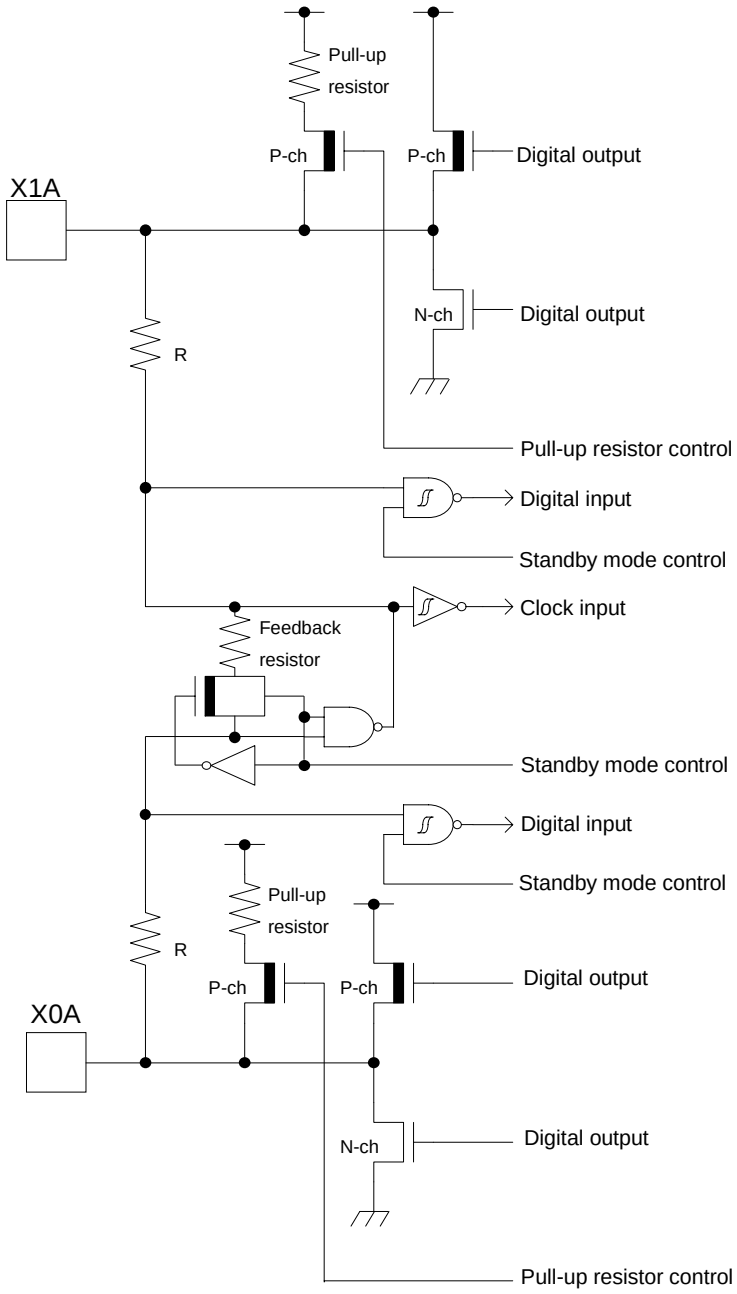
Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
Quadrature Position/ Revolution Counter 0	AIN0_0	QPRC ch.0 AIN input pin	28	-	H3
	AIN0_1		59	51	L5
	AIN0_2		13	13	E5
	BIN0_0	QPRC ch.0 BIN input pin	29	-	H4
	BIN0_1		60	52	K5
	BIN0_2		14	14	F1
	ZIN0_0	QPRC ch.0 ZIN input pin	30	-	H5
	ZIN0_1		61	53	N6
	ZIN0_2		15	15	F2
Quadrature Position/ Revolution Counter 1	AIN1_0	QPRC ch.1 AIN input pin	73	65	N9
	AIN1_1		127	103	D13
	AIN1_2		62	54	M6
	BIN1_0	QPRC ch.1 BIN input pin	74	66	M9
	BIN1_1		126	102	D12
	BIN1_2		63	55	L6
	ZIN1_0	QPRC ch.1 ZIN input pin	75	67	L9
	ZIN1_1		125	101	E13
	ZIN1_2		64	56	K6
Quadrature Position/ Revolution Counter 2	AIN2_0	QPRC ch.2 AIN input pin	67	59	M8
	AIN2_1		170	-	B4
	AIN2_2		115	-	G11
	BIN2_0	QPRC ch.2 BIN input pin	68	60	L8
	BIN2_1		171	-	C4
	BIN2_2		116	-	G10
	ZIN2_0	QPRC ch.2 ZIN input pin	69	61	K8
	ZIN2_1		172	140	B3
	ZIN2_2		117	-	G9

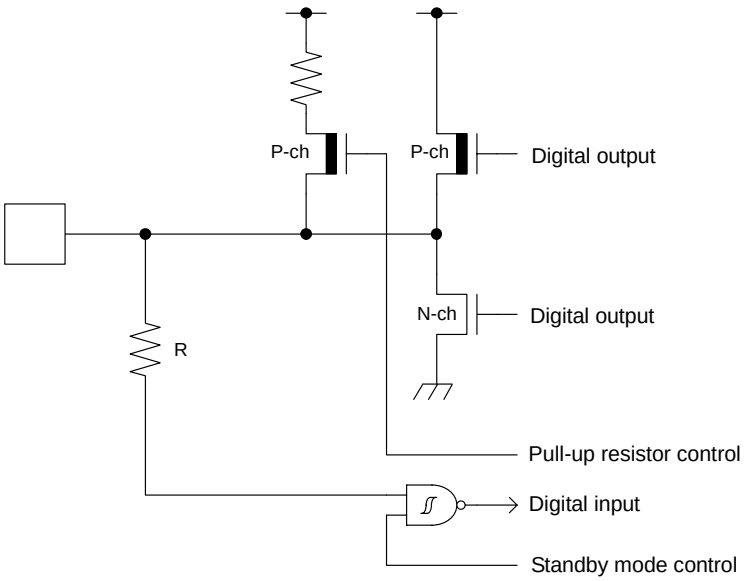
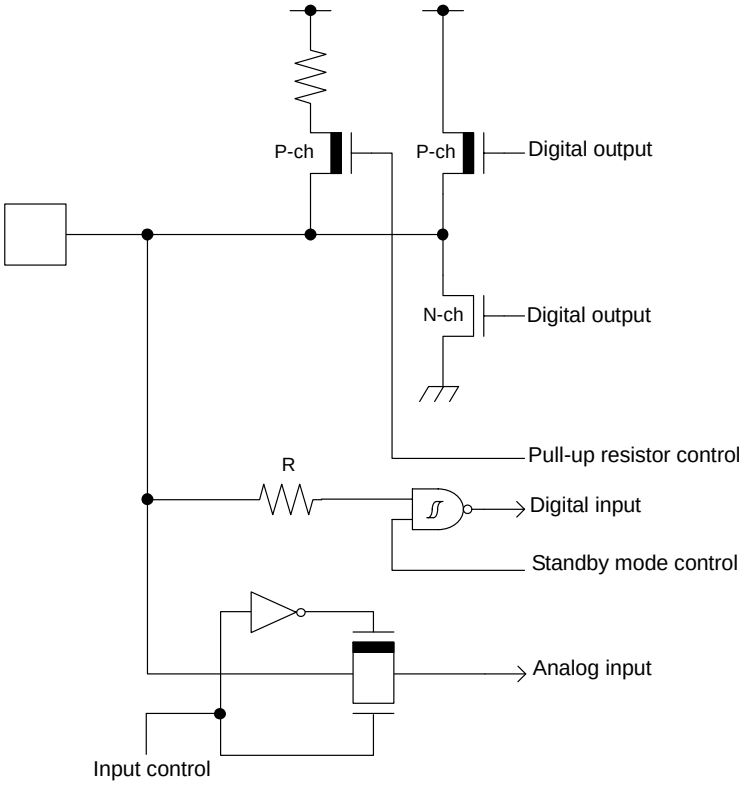
Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
RESET	INITX	External Reset Input. A reset is valid when INITX="L".	57	49	N5
Mode	MD0	Mode 0 Pin. During normal operation, MD0="L" must be input. During serial programming to Flash memory, MD0="H" must be input.	85	69	N12
	MD1	Mode 1 Pin. During serial programming to Flash memory, MD1="L" must be input.	84	68	N13
POWER	VCC	Power supply Pin	1	1	C1
	VCC	Power supply Pin	45	37	N1
	VCC	Power supply Pin	54	46	P4
	VCC	Power supply Pin	89	73	M14
	VCC	Power supply Pin	133	109	A13
	VCC	Power supply Pin	173	141	A4
	VCC	Power supply Pin	129	105	E14
	VCC	Power supply Pin	156	126	A9
GND	VSS	GND Pin	27	25	J1
	VSS	GND Pin	44	36	M1
	VSS	GND Pin	53	45	P3
	VSS	GND Pin	88	72	N14
	VSS	GND Pin	109	93	F14
	VSS	GND Pin	132	108	B14
	VSS	GND Pin	157	127	A11
	VSS	GND Pin	176	144	B1
	VSS	GND Pin	-	-	E1
	VSS	GND Pin	-	-	G1
	VSS	GND Pin	-	-	P7
	VSS	GND Pin	-	-	P11
	VSS	GND Pin	-	-	L14
	VSS	GND Pin	-	-	A8
	VSS	GND Pin	-	-	A5
	VSS	GND Pin	-	-	N7
	VSS	GND Pin	-	-	M7
	VSS	GND Pin	-	-	L7
	VSS	GND Pin	-	-	K7
	VSS	GND Pin	-	-	J7
	VSS	GND Pin	-	-	G7
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	VSS	GND Pin	-	-	G8

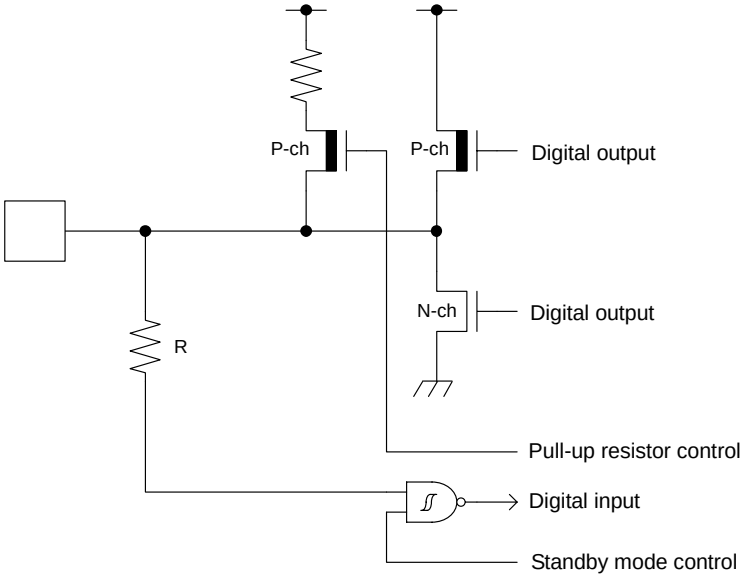
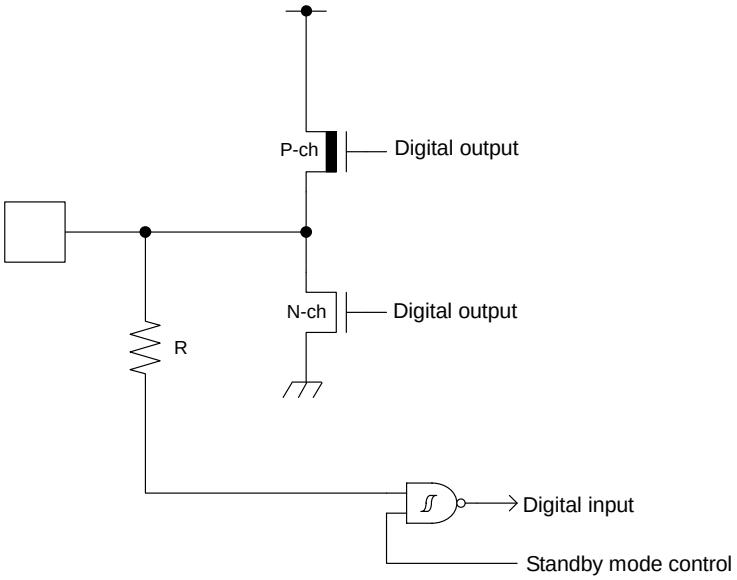
Module	Pin name	Function	Pin No		
			LQFP-176	LQFP-144	BGA-192
CLOCK	X0	Main clock (oscillation) input pin	86	70	P12
	X0A	Sub clock (oscillation) input pin	55	47	P5
	X1	Main clock (oscillation) I/O pin	87	71	P13
	X1A	Sub clock (oscillation) I/O pin	56	48	P6
	CROUT_0	Built-in high-speed CR oscillation clock output port	127	103	D13
	CROUT_1		152	122	E8
Analog POWER	AVCC	A/D converter analog power supply pin	106	90	J14
	AVRH	A/D converter analog reference voltage input pin	107	91	H14
Analog GND	AVSS	A/D converter GND pin	108	92	G14
C pin	C	Power supply stabilization capacity pin	52	44	P2

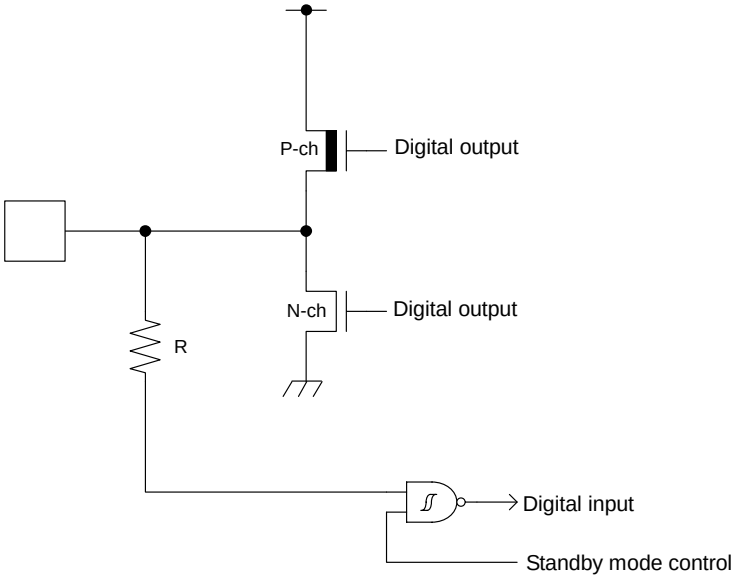
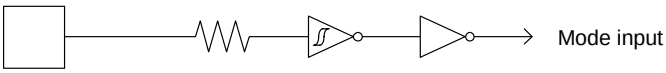
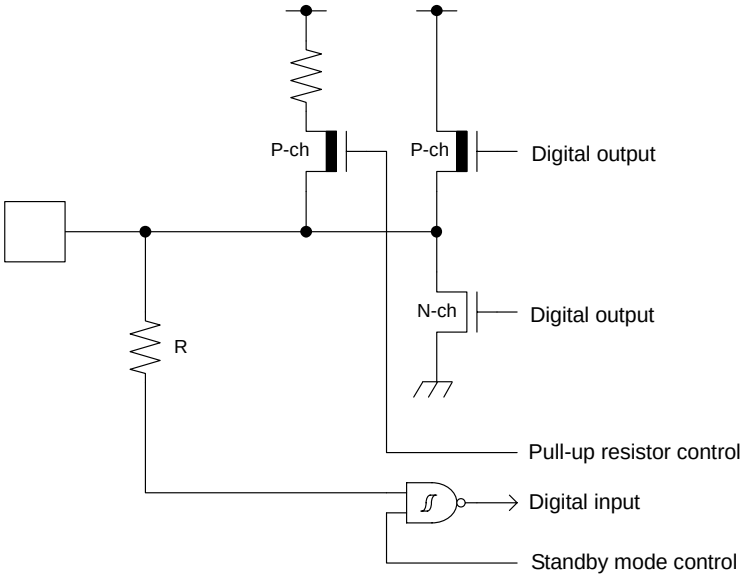
■ I/O Circuit Type

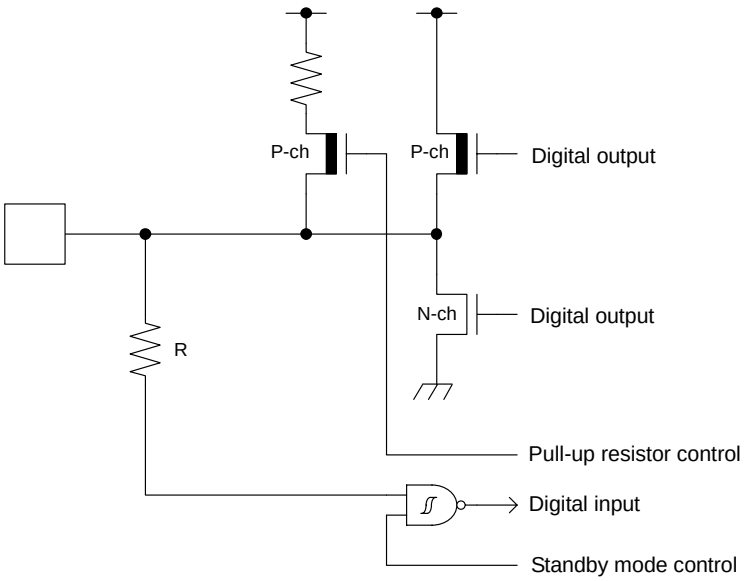
Type	Circuit	Remarks
A		It is possible to select the main oscillation / GPIO function When the main oscillation is selected. ・Oscillation feedback resistor : Approximately 1 MΩ ・With Standby mode control When the GPIO is selected. ・CMOS level output. ・CMOS level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH}= -4 mA, I_{OL}= 4 mA
B		・CMOS level hysteresis input ・Pull-up resistor : Approximately 50 kΩ

Type	Circuit	Remarks
C		・Open drain output ・CMOS level hysteresis input
D		It is possible to select the sub oscillation / GPIO function When the sub oscillation is selected. ・Oscillation feedback resistor : Approximately 5 MΩ ・With Standby mode control When the GPIO is selected. ・CMOS level output. ・CMOS level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH}= -4 mA, I_{OL}= 4 mA

Type	Circuit	Remarks
E		・CMOS level output ・CMOS level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH}= -4 mA, I_{OL}= 4 mA ・When this pin is used as an I2C pin, the digital output P-ch transistor is always off ・+B input is available
F		・CMOS level output ・CMOS level hysteresis input ・With input control ・Analog input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH}= -4 mA, I_{OL}= 4 mA ・When this pin is used as an I2C pin, the digital output P-ch transistor is always off ・+B input is available

Type	Circuit	Remarks
G		・CMOS level output ・CMOS level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH}= -12 mA, I_{OL}= 12 mA ・+B input is available
H		・CMOS level output ・CMOS level hysteresis input ・With standby mode control ・I_{OH}= -20.5 mA, I_{OL}=18.5 mA

Type	Circuit	Remarks
I		・CMOS level output ・CMOS level hysteresis input ・5 V tolerant ・With standby mode control ・I_{OH}= -4 mA, I_{OL}= 4 mA ・Available to control PZR registers. ・When this pin is used as an I2C pin, the digital output P-ch transistor is always off
J		CMOS level hysteresis input
K		・CMOS level output ・TTL level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH} = -4 mA, I_{OL}= 4 mA

Type	Circuit	Remarks
L		・CMOS level output ・CMOS level hysteresis input ・With pull-up resistor control ・With standby mode control ・Pull-up resistor : Approximately 50 kΩ ・I_{OH} = -8 mA, I_{OL}= 8 mA ・When this pin is used as an I2C pin, the digital output P-ch transistor is always off ・+B input is available

■ Handling Precautions

Any semiconductor devices have inherently a certain rate of failure. The possibility of failure is greatly affected by the conditions in which they are used (circuit conditions, environmental conditions, etc.). This page describes precautions that must be observed to minimize the chance of failure and to obtain higher reliability from your Spansion semiconductor devices.

1. Precautions for Product Design

This section describes precautions when designing electronic equipment using semiconductor devices.

・ Absolute Maximum Ratings

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of certain established limits, called absolute maximum ratings. Do not exceed these ratings.

・ Recommended Operating Conditions

Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their sales representative beforehand.

・ Processing and Protection of Pins

These precautions must be followed when handling the pins which connect semiconductor devices to power supply and input/output functions.

(1) Preventing Over-Voltage and Over-Current Conditions
Exposure to voltage or current levels in excess of maximum ratings at any pin is likely to cause deterioration within the device, and in extreme cases leads to permanent damage of the device. Try to prevent such overvoltage or over-current conditions at the design stage.

(2) Protection of Output Pins
Shorting of output pins to supply pins or other output pins, or connection to large capacitance can cause large current flows. Such conditions if present for extended periods of time can damage the device. Therefore, avoid this type of connection.

(3) Handling of Unused Input Pins
Unconnected input pins with very high impedance levels can adversely affect stability of operation. Such pins should be connected through an appropriate resistance to a power supply pin or ground pin.

・ Latch-up

Semiconductor devices are constructed by the formation of P-type and N-type areas on a substrate. When subjected to abnormally high voltages, internal parasitic PNPN junctions (called thyristor structures) may be formed, causing large current levels in excess of several hundred mA to flow continuously at the power supply pin. This condition is called latch-up.

CAUTION: The occurrence of latch-up not only causes loss of reliability in the semiconductor device, but can cause injury or damage from high heat, smoke or flame. To prevent this from happening, do the following:

(1) Be sure that voltages applied to pins do not exceed the absolute maximum ratings. This should include attention to abnormal noise, surge levels, etc.
(2) Be sure that abnormal current flows do not occur during the power-on sequence.

Code: DS00-00004-3E

- Observance of Safety Regulations and Standards

  Most countries in the world have established standards and regulations regarding safety, protection from electromagnetic interference, etc. Customers are requested to observe applicable regulations and standards in the design of products.

- Fail-Safe Design

  Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

- Precautions Related to Usage of Devices

  Spansion semiconductor devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

  CAUTION: Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

2. Precautions for Package Mounting

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under Spansion's recommended conditions. For detailed information about mount conditions, contact your sales representative.

- Lead Insertion Type

  Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

  Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to Spansion recommended mounting conditions.

  If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

- Surface Mount Type

  Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

  You must use appropriate mounting techniques. Spansion recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Spansion ranking of recommended conditions.

- Lead-Free Packaging

  CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

- Storage of Semiconductor Devices

  Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

  (1) Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
  (2) Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5°C and 30°C.
  When you open Dry Package that recommends humidity 40% to 70% relative humidity.
  (3) When necessary, Spansion packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
  (4) Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

- Baking

  Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Spansion recommended conditions for baking.

  Condition: 125°C/24 h

- Static Electricity

  Because semiconductor devices are particularly susceptible to damage by static electricity, you must take the following precautions:

  (1) Maintain relative humidity in the working environment between 40% and 70%. Use of an apparatus for ion generation may be needed to remove electricity.
  (2) Electrically ground all conveyors, solder vessels, soldering irons and peripheral equipment.
  (3) Eliminate static body electricity by the use of rings or bracelets connected to ground through high resistance (on the level of 1 MΩ).
  Wearing of conductive clothing and shoes, use of conductive floor mats and other measures to minimize shock loads is recommended.
  (4) Ground all fixtures and instruments, or protect with anti-static measures.
  (5) Avoid the use of styrofoam or other highly static-prone materials for storage of completed board assemblies.

3. Precautions for Use Environment

Reliability of semiconductor devices depends on ambient temperature and other conditions as described above.
For reliable performance, do the following:

(1) Humidity
Prolonged use in high humidity can lead to leakage in devices as well as printed circuit boards. If high humidity levels are anticipated, consider anti-humidity processing.

(2) Discharge of Static Electricity
When high-voltage charges exist close to semiconductor devices, discharges can cause abnormal operation. In such cases, use anti-static measures or processing to prevent discharges.

(3) Corrosive Gases, Dust, or Oil
Exposure to corrosive gases or contact with dust or oil may lead to chemical reactions that will adversely affect the device. If you use devices in such conditions, consider ways to prevent such exposure or to protect the devices.

(4) Radiation, Including Cosmic Radiation
Most devices are not designed for environments involving exposure to radiation or cosmic radiation. Users should provide shielding as appropriate.

(5) Smoke, Flame
CAUTION: Plastic molded devices are flammable, and therefore should not be used near combustible substances. If devices begin to smoke or burn, there is danger of the release of toxic gases.

Customers considering the use of Spansion products in other special environmental conditions should consult with sales representatives.

Please check the latest handling precautions at the following URL.
http://www.spansion.com/fjdocuments/fj/datasheet/e-ds/DS00-00004.pdf

■ Handling Devices

- Power supply pins

  In products with multiple VCC and VSS pins, respective pins at the same potential are interconnected within the device in order to prevent malfunctions such as latch-up. However, all of these pins should be connected externally to the power supply or ground lines in order to reduce electromagnetic emission levels, to prevent abnormal operation of strobe signals caused by the rise in the ground level, and to conform to the total output current rating.

  Moreover, connect the current supply source with each Power supply pins and GND pins of this device at low impedance. It is also advisable that a ceramic capacitor of approximately 0.1 µF be connected as a bypass capacitor between each Power supply pins and GND pins, between AVCC pin and AVSS pin near this device.

- Stabilizing power supply voltage

  A malfunction may occur when the power supply voltage fluctuates rapidly even though the fluctuation is within the recommended operating conditions of the VCC power supply voltage. As a rule, with voltage stabilization, suppress the voltage fluctuation so that the fluctuation in VCC ripple (peak-to-peak value) at the commercial frequency (50 Hz/60 Hz) does not exceed 10% of the VCC value in the recommended operating conditions, and the transient fluctuation rate does not exceed 0.1 V/µs when there is a momentary fluctuation on switching the power supply.

- Crystal oscillator circuit

  Noise near the X0/X1 and X0A/X1A pins may cause the device to malfunction. Design the printed circuit board so that X0/X1, X0A/X1A pins, the crystal oscillator and the bypass capacitor to ground are located as close to the device as possible.

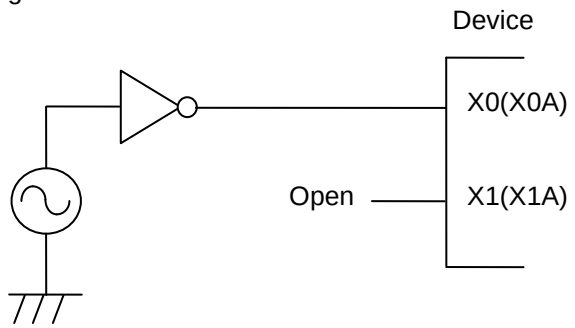
  It is strongly recommended that the PC board artwork be designed such that the X0/X1 and X0A/X1A pins are surrounded by ground plane as this is expected to produce stable operation.

  Evaluate oscillation of your using crystal oscillator by your mount board.

- Using an external clock

  When using an external clock, the clock signal should be input to the X0,X0A pin only and the X1 and X1A pins should be kept open.

  ・Example of Using an External Clock

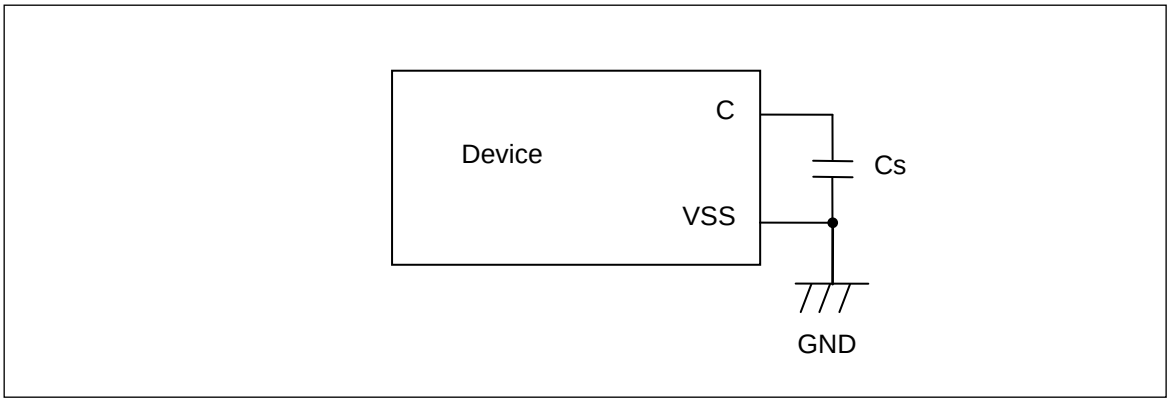


- Handling when using Multi-function serial pin as I^2C pin

  If it is using the multi-function serial pin as I^2C pins, P-ch transistor of digital output is always disabled. However, I^2C pins need to keep the electrical characteristic like other pins and not to connect to the external I^2C bus system with power OFF.

- C Pin

  This series contains the regulator. Be sure to connect a smoothing capacitor (C_S) for the regulator between the C pin and the GND pin. Please use a ceramic capacitor or a capacitor of equivalent frequency characteristics as a smoothing capacitor.
  However, some laminated ceramic capacitors have the characteristics of capacitance variation due to thermal fluctuation (F characteristics and Y5V characteristics). Please select the capacitor that meets the specifications in the operating conditions to use by evaluating the temperature characteristics of a capacitor.
  A smoothing capacitor of about 4.7µF would be recommended for this series.



- Mode pins (MD0)

  Connect the MD pin (MD0) directly to VCC or VSS pins. Design the printed circuit board such that the pull-up/down resistance stays low, as well as the distance between the mode pins and VCC pins or VSS pins is as short as possible and the connection impedance is low, when the pins are pulled-up/down such as for switching the pin level and rewriting the Flash memory data. It is because of preventing the device erroneously switching to test mode due to noise.

- Notes on power-on

  Turn power on/off in the following order or at the same time.
  If not using the A/D converter, connect AVCC =VCC and AVSS = VSS.

  Turning on :VCC → AVCC → AVRH
  Turning off : AVRH → AVCC → VCC

- Serial Communication

  There is a possibility to receive wrong data due to the noise or other causes on the serial communication. Therefore, design a printed circuit board so as to avoid noise.
  Consider the case of receiving wrong data due to noise, perform error detection such as by applying a checksum of data at the end. If an error is detected, retransmit the data.

- Differences in features among the products with different memory sizes and between Flash products and MASK products

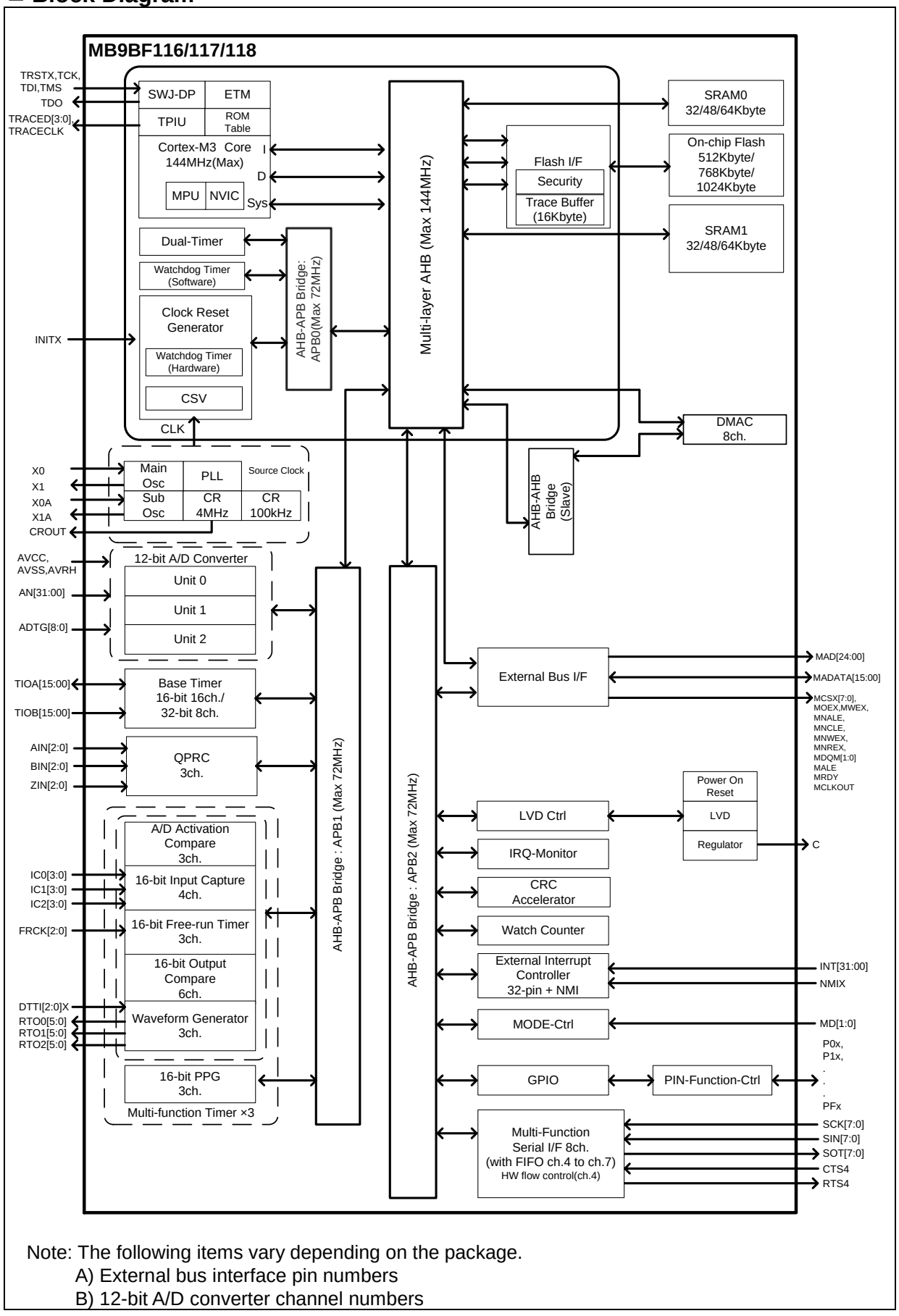
  The electric characteristics including power consumption, ESD, latch-up, noise characteristics, and oscillation characteristics among the products with different memory sizes and between Flash products and MASK products are different because chip layout and memory structures are different.

  If you are switching to use a different product of the same series, please make sure to evaluate the electric characteristics.

- Base Timer

  In the case of using ch.8 and ch.9 at I/O mode 1 (timer full mode), the TIOA09 pin cannot be used for external startup trigger input (TGIN).
  Be sure to use the pin with making ESG1 and ESG2 bits of the Timer Control Register (Ch.9-TMCR) in the Base Timer to be "0b00" in order to disable trigger input.

■ Block Diagram



Note: The following items vary depending on the package.

A) External bus interface pin numbers

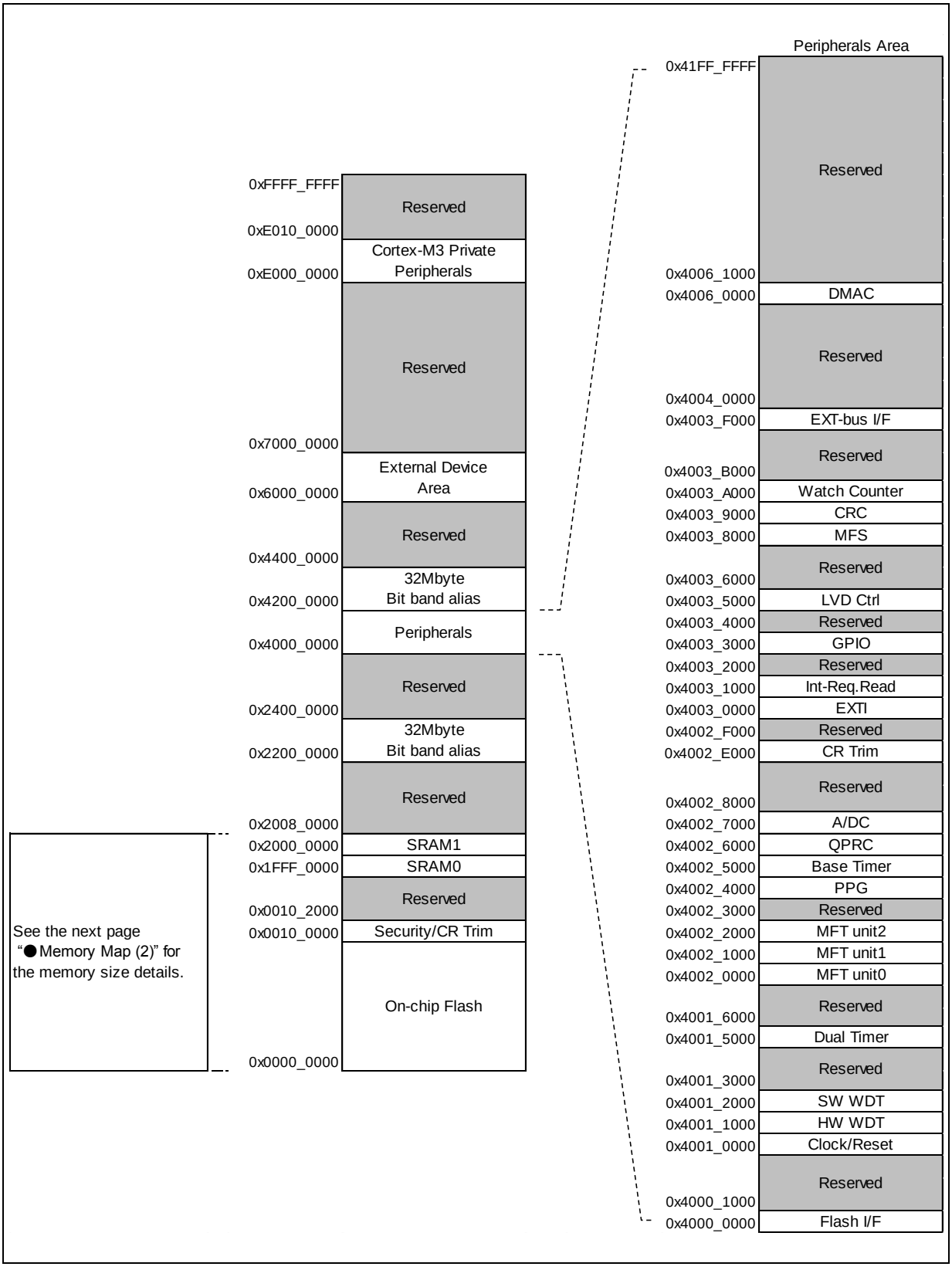
B) 12-bit A/D converter channel numbers

■ Memory Size

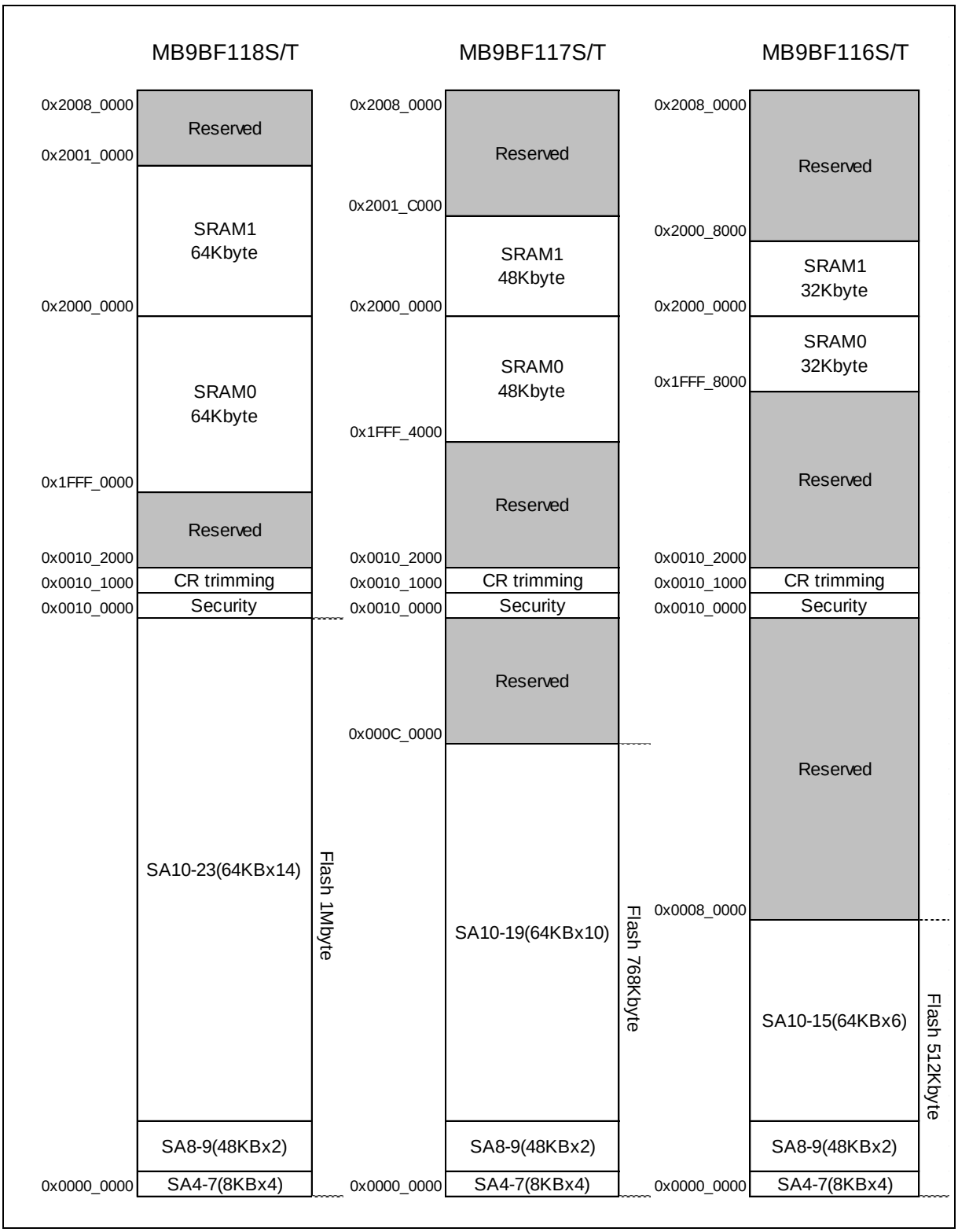
See "●Memory size" in "■Product Lineup" to confirm the memory size.

■ Memory Map

・ Memory Map (1)



・ Memory Map (2)



*: See "MB9BD10T/610T/510T/410T/310T/210T/110T Series Flash programming Manual" for sector structure of Flash.

・ Peripheral Address Map

Start address	End address	Bus	Peripherals
0x4000_0000	0x4000_0FFF	AHB	Flash memory I/F register
0x4000_1000	0x4000_FFFF		Reserved
0x4001_0000	0x4001_0FFF	APB0	Clock/Reset Control
0x4001_1000	0x4001_1FFF		Hardware Watchdog timer
0x4001_2000	0x4001_2FFF		Software Watchdog timer
0x4001_3000	0x4001_4FFF		Reserved
0x4001_5000	0x4001_5FFF		Dual-Timer
0x4001_6000	0x4001_FFFF		Reserved
0x4002_0000	0x4002_0FFF	APB1	Multi-function timer unit0
0x4002_1000	0x4002_1FFF		Multi-function timer unit1
0x4002_2000	0x4002_3FFF		Multi-function timer unit2
0x4002_4000	0x4002_4FFF		PPG
0x4002_5000	0x4002_5FFF		Base Timer
0x4002_6000	0x4002_6FFF		Quadrature Position/Revolution Counter (QPRC)
0x4002_7000	0x4002_7FFF		A/D Converter
0x4002_8000	0x4002_DFFF		Reserved
0x4002_E000	0x4002_EFFF		Built-in CR trimming
0x4002_F000	0x4002_FFFF		Reserved
0x4003_0000	0x4003_0FFF	APB2	External Interrupt
0x4003_1000	0x4003_1FFF		Interrupt Source Check Register
0x4003_2000	0x4003_2FFF		Reserved
0x4003_3000	0x4003_3FFF		GPIO
0x4003_4000	0x4003_4FFF		Reserved
0x4003_5000	0x4003_5FFF		Low-Voltage Detector
0x4003_6000	0x4003_7FFF		Reserved
0x4003_8000	0x4003_8FFF		Multi-function serial Interface
0x4003_9000	0x4003_9FFF		CRC
0x4003_A000	0x4003_AFFF		Watch Counter
0x4003_B000	0x4003_EFFF		Reserved
0x4003_F000	0x4003_FFFF		External bus interface
0x4004_0000	0x4005_FFFF	AHB	Reserved
0x4006_0000	0x4006_0FFF		DMAC register
0x4006_1000	0x41FF_FFFF		Reserved

■ Pin Status in Each CPU State

The terms used for pin status have the following meanings.

- INITX=0
  This is the period when the INITX pin is the "L" level.
- INITX=1
  This is the period when the INITX pin is the "H" level.
- SPL=0
  This is the status that the standby pin level setting bit (SPL) in the standby mode control register (STB_CTL) is set to "0".
- SPL=1
  This is the status that the standby pin level setting bit (SPL) in the standby mode control register (STB_CTL) is set to "1".
- Input enabled
  Indicates that the input function can be used.
- Internal input fixed at "0"
  This is the status that the input function cannot be used. Internal input is fixed at "L".
- Hi-Z
  Indicates that the pin drive transistor is disabled and the pin is put in the Hi-Z state.
- Setting disabled
  Indicates that the setting is disabled.
- Maintain previous state
  Maintains the state that was immediately prior to entering the current mode.
  If a built-in peripheral function is operating, the output follows the peripheral function.
  If the pin is being used as a port, that output is maintained.
- Analog input is enabled
  Indicates that the analog input is enabled.
- Trace output
  Indicates that the trace function can be used.

・ List of Pin Status

Pin status type	Function group	Power-on reset or low-voltage detection state	INITX input state	Device internal reset state	Run mode or sleep mode state	Timer mode or stop mode state	
		Power supply unstable	Power supply stable		Power supply stable	Power supply stable	
		-	INITX=0	INITX=1	INITX=1	INITX=1	
		-	-	-	-	SPL=0	SPL=1
A	GPIO selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
	Main crystal oscillator input pin	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled
B	GPIO selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
	Main crystal oscillator output pin	Hi-Z/ Internal input fixed at "0"/ or Input enable	Hi-Z/ Internal input fixed at "0"	Hi-Z/ Internal input fixed at "0"	Maintain previous state	Maintain previous state/ Hi-Z at oscillation stop*[1]/ Internal input fixed at "0"	Maintain previous state/ Hi-Z at oscillation stop*[1]/ Internal input fixed at "0"
C	INITX input pin	Pull-up/ Input enabled	Pull-up/ Input enabled	Pull-up/ Input enabled	Pull-up/ Input enabled	Pull-up/ Input enabled	Pull-up/ Input enabled
D	Mode input pin	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled
E	JTAG selected	Hi-Z	Pull-up/ Input enabled	Pull-up/ Input enabled	Maintain previous state	Maintain previous state	Maintain previous state
	GPIO selected	Setting disabled	Setting disabled	Setting disabled			Hi-Z/ Internal input fixed at "0"
F	Trace selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Trace output
	External interrupt enabled selected						Maintain previous state
	GPIO selected, or resource other than above selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled			Hi-Z/ Internal input fixed at "0"

Pin status type	Function group	Power-on reset or low-voltage detection state	INITX input state	Device internal reset state	Run mode or sleep mode state	Timer mode or stop mode state	
		Power supply unstable	Power supply stable		Power supply stable	Power supply stable	
		-	INITX=0	INITX=1	INITX=1	INITX=1	
		-	-	-	-	SPL=0	SPL=1
G	Trace selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Trace output
	GPIO selected, or resource other than above selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled			Hi-Z/ Internal input fixed at "0"
H	External interrupt enabled selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Maintain previous state
	GPIO selected, or resource other than above selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled			Hi-Z/ Internal input fixed at "0"
I	GPIO selected, resource selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
J	NMIX selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Maintain previous state
	GPIO selected, or resource other than above selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled			Hi-Z/ Internal input fixed at "0"

Pin status type	Function group	Power-on reset or low-voltage detection state	INITX input state	Device internal reset state	Run mode or sleep mode state	Timer mode or stop mode state	
		Power supply unstable	Power supply stable		Power supply stable	Power supply stable	
		-	INITX=0	INITX=1	INITX=1	INITX=1	
		-	-	-	-	SPL=0	SPL=1
K	Analog input selected	Hi-Z	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled
	GPIO selected, or resource other than above selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
L	External interrupt enabled selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Maintain previous state
	Analog input selected	Hi-Z	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled	Hi-Z/ Internal input fixed at "0"/ Analog input enabled
	GPIO selected, or resource other than above selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
M	GPIO selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
	Sub crystal oscillator input pin	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled

Pin status type	Function group	Power-on reset or low-voltage detection state	INITX input state	Device internal reset state	Run mode or sleep mode state	Timer mode or stop mode state	
		Power supply unstable	Power supply stable		Power supply stable	Power supply stable	
		-	INITX=0	INITX=1	INITX=1	INITX=1	
		-	-	-	-	SPL=0	SPL=1
N	GPIO selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
	Sub crystal oscillator output pin	Hi-Z/ Internal input fixed at "0"/ or Input enable	Hi-Z/ Internal input fixed at "0"	Hi-Z/ Internal input fixed at "0"	Maintain previous state	Maintain previous state/ Hi-Z at oscillation stop*2/ Internal input fixed at "0"	Maintain previous state/ Hi-Z at oscillation stop*2/ Internal input fixed at "0"
O	GPIO selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
P	Mode input pin	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled	Input enabled
	GPIO selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Hi-Z/ Input enabled
Q	GPIO selected, resource selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled	Maintain previous state	Maintain previous state	Hi-Z/ Internal input fixed at "0"
R	External interrupt enabled selected	Setting disabled	Setting disabled	Setting disabled	Maintain previous state	Maintain previous state	Maintain previous state
	GPIO selected, or resource other than above selected	Hi-Z	Hi-Z/ Input enabled	Hi-Z/ Input enabled			Hi-Z/ Internal input fixed at "0"

*1: Oscillation is stopped at Sub timer mode, Low-speed CR timer mode, and STOP mode.
*2: Oscillation is stopped at STOP mode.

■ Electrical Characteristics

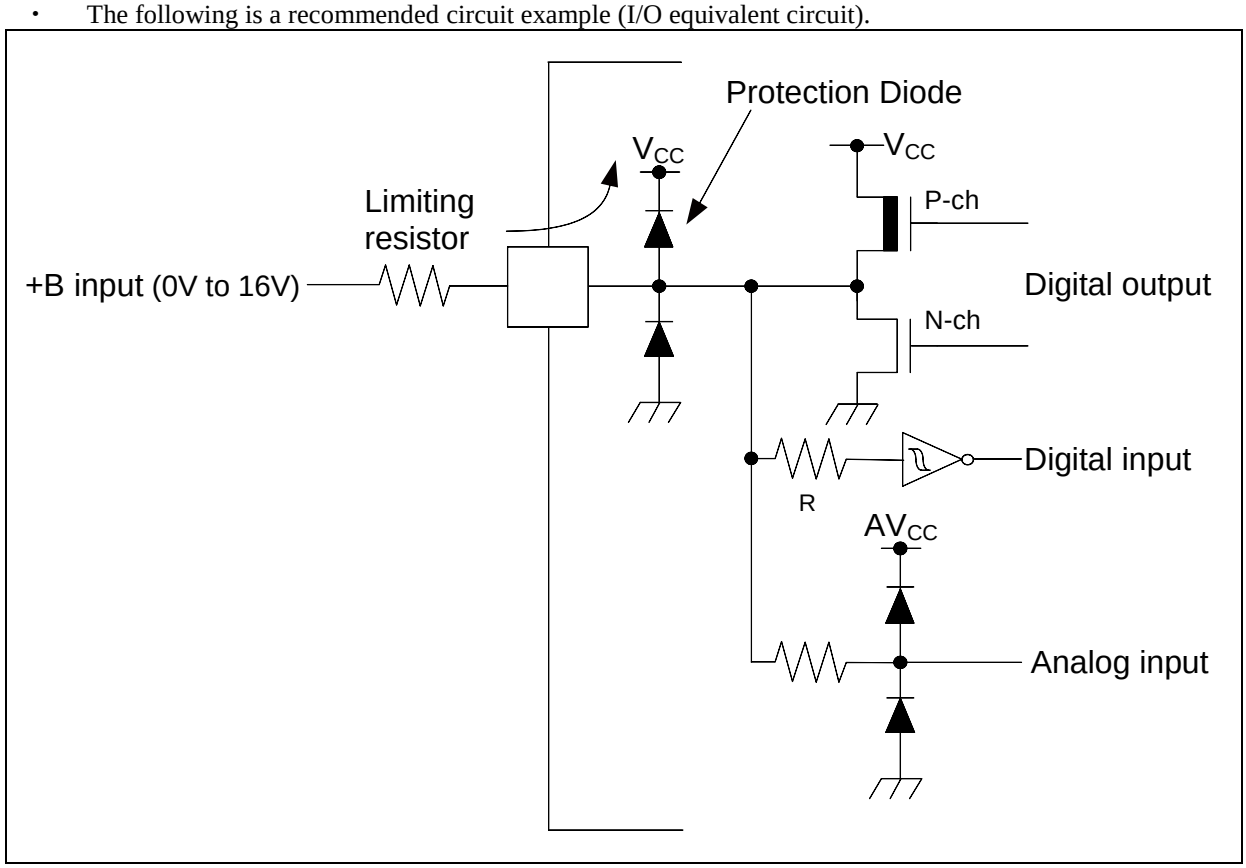
1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1,*2	Vcc	Vss - 0.5	Vss + 6.5	V	
Analog power supply voltage*1,*3	AVcc	Vss - 0.5	Vss + 6.5	V	
Analog reference voltage*1,*3	AVRH	Vss - 0.5	Vss + 6.5	V	
Input voltage*1	V_I	Vss - 0.5	Vcc + 0.5 (≤ 6.5V)	V	
		Vss - 0.5	Vss + 6.5	V	5 V tolerant
Analog pin input voltage*1	V_{IA}	Vss - 0.5	AVcc + 0.5 (≤ 6.5 V)	V	
Output voltage*1	V_O	Vss - 0.5	Vcc + 0.5 (≤ 6.5 V)	V	
Clamp maximum current	I_{CLAMP}	-2	+2	mA	*7
Clamp total maximum current	$\Sigma [I_{CLAMP}]$		+20	mA	*7
"L" level maximum output current*4	I_{OL}	-	10	mA	4 mA type
			20	mA	8 mA type
			20	mA	12 mA type
			39	mA	P80,P81,P82,P83
"L" level average output current*5	I_{OLAV}	-	4	mA	4 mA type
			8	mA	8 mA type
			12	mA	12 mA type
			18.5	mA	P80,P81,P82,P83
"L" level total maximum output current	$\sum I_{OL}$	-	100	mA	
"L" level total average output current*6	$\sum I_{OLAV}$	-	50	mA	
"H" level maximum output current*4	I_{OH}	-	- 10	mA	4 mA type
			- 20	mA	8 mA type
			- 20	mA	12 mA type
			- 39	mA	P80,P81,P82,P83
"H" level average output current*5	I_{OHAV}	-	- 4	mA	4 mA type
			- 8	mA	8 mA type
			- 12	mA	12 mA type
			- 20.5	mA	P80,P81,P82,P83
"H" level total maximum output current	$\sum I_{OH}$	-	- 100	mA	
"H" level total average output current*6	$\sum I_{OHAV}$	-	- 50	mA	
Power consumption	P_D	-	1000	mW	
Storage temperature	T_{STG}	- 55	+ 150	°C	

*1: These parameters are based on the condition that Vss = AVss = 0.0 V.
*2: Vcc must not drop below Vss - 0.5 V.
*3: Ensure that the voltage does not to exceed Vcc + 0.5 V, for example, when the power is turned on.
*4: The maximum output current is the peak value for a single pin.
*5: The average output is the average current for a single pin over a period of 100 ms.
*6: The total average output current is the average current for all pins over a period of 100 ms.

*7:

- See "■List of Pin Functions" and "■I/O Circuit Type" about +B input available pin.
- Use within recommended operating conditions.
- Use at DC voltage (current) the +B input.
- The +B signal should always be applied a limiting resistance placed between the +B signal and the device.
- The value of the limiting resistance should be set so that when the +B signal is applied the input current to the device pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the device drive current is low, such as in the low-power consumpsion modes, the +B input potential may pass through the protective diode and increase the potential at the VCC and AVCC pin, and this may affect other devices.
- Note that if a +B signal is input when the device power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.
- The following is a recommended circuit example (I/O equivalent circuit).



<WARNING>

Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

2. Recommended Operating Conditions

(Vss = AVss = 0.0V)

Parameter		Symbol	Conditions	Value		Unit	Remarks
				Min	Max		
Power supply voltage		Vcc	-	2.7*2	5.5	V	
Analog power supply voltage		AVcc	-	2.7	5.5	V	AVcc = Vcc
Analog reference voltage		AVRH	-	2.7	AVcc	V	
Smoothing capacitor		C_S	-	1	10	µF	for built-in regulator *1
Operating temperature	FPT-144P-M08, FPT-176P-M07, BGA-192P-M06	Ta	When mounted on four-layer PCB	- 40	+ 85	°C	

*1: See "●C pin" in "■Handling Devices" for the connection of the smoothing capacitor.

*2: In between less than the minimum power supply voltage and low voltage reset/interrupt detection voltage or more, instruction execution and low voltage detection function by built-in High-speed CR(including Main PLL is used) or built-in Low-speed CR is possible to operate only.

<WARNING>

The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

3. DC Characteristics

(1) Current Rating

(Vcc = AVcc = 2.7V to 5.5V, Vss = AVss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions		Value Typ*3	Value Max*4	Unit	Remarks
RUN mode current	Icc	VCC	PLL RUN mode	CPU : 144 MHz, Peripheral : 72 MHz, Flash 2 Wait, TraceBuffer : ON, FRWTR.RWT = 10, FSYNDN.SD = 000, FBFCR.BE = 1	100	180	mA	*1, *5
				CPU : 72 MHz, Peripheral : 72 MHz, Flash 0 Wait, TraceBuffer : OFF, FRWTR.RWT = 00, FSYNDN.SD = 000, FBFCR.BE = 0	65	135	mA	*1, *5
			High-speed CR RUN mode	CPU/ Peripheral : 4 MHz*2, Flash 0 Wait, FRWTR.RWT = 00, FSYNDN.SD = 000	6	57.8	mA	*1
			Sub RUN mode	CPU/ Peripheral : 32 kHz, Flash 0 Wait, FRWTR.RWT = 00, FSYNDN.SD = 000	1.3	51.7	mA	*1, *6
			Low-speed CR RUN mode	CPU/ Peripheral : 100 kHz, Flash 0 Wait, FRWTR.RWT = 00, FSYNDN.SD = 000	1.3	51.7	mA	*1
SLEEP mode current	Iccs		PLL SLEEP mode	Peripheral : 72 MHz	30	89	mA	*1, *5
			High-speed CR SLEEP mode	Peripheral : 4 MHz*2	4.5	55.9	mA	*1
			Sub SLEEP mode	Peripheral : 32 kHz	1.2	51.6	mA	*1, *6
			Low-speed CR SLEEP mode	Peripheral : 100 kHz	1.2	51.6	mA	*1

*1: When all ports are fixed.
*2: When setting it to 4 MHz by trimming.
*3: Ta=+25°C, V_{CC}=5.5 V
*4: Ta=+85°C, V_{CC}=5.5 V
*5: When using the crystal oscillator of 4 MHz(Including the current consumption of the oscillation circuit)
*6: When using the crystal oscillator of 32 kHz(Including the current consumption of the oscillation circuit)

(Vcc = AVcc = 2.7V to 5.5V, Vss = AVss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions		Value Typ*2	Value Max*2	Unit	Remarks
TIMER mode current	I_{CCT}	VCC	Main TIMER mode	Ta = + 25°C, When LVD is off	4	10	mA	*1, *3
				Ta = + 85°C, When LVD is off	-	55	mA	*1, *3
			Sub TIMER mode	Ta = + 25°C, When LVD is off	1.1	5	mA	*1, *4
				Ta = + 85°C, When LVD is off	-	50	mA	*1, *4
STOP mode current	I_{CCH}		STOP mode	Ta = + 25°C, When LVD is off	1	5	mA	*1
				Ta = + 85°C, When LVD is off	-	50	mA	*1

*1: When all ports are fixed.
*2: V_{CC}=5.5 V
*3: When using the crystal oscillator of 4 MHz(Including the current consumption of the oscillation circuit)
*4: When using the crystal oscillator of 32 kHz(Including the current consumption of the oscillation circuit)

・Low-Voltage Detection Current

(V_{CC} = 2.7V to 5.5V, V_{SS} = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value Typ	Value Max	Unit	Remarks
Low-voltage detection circuit (LVD) power supply current	I_{CCLVD}	VCC	At operation for interrupt	4	7	µA	At not detect

・Flash Memory Current

(V_{CC} = 2.7V to 5.5V, V_{SS} = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value Typ	Value Max	Unit	Remarks
Flash memory write/erase current	$I_{CCFLASH}$	VCC	At Write/Erase	12	14	mA	

・A/D Converter Current

(V_{CC} = AV_{CC} = 2.7V to 5.5V, V_{SS} = AV_{SS} = AVRL = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value Typ	Value Max	Unit	Remarks
Power supply current	I_{CCAD}	AVCC	At 1unit operation	0.57	0.72	mA	
			At stop	0.06	35	µA	
Reference power supply current	I_{CCAVRH}	AVRH	At 1unit operation AVRH=5.5 V	1.1	1.96	mA	
			At stop	0.06	4	µA	

(2) Pin Characteristics

(Vcc = AVcc = 2.7V to 5.5V, Vss = AVss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"H" level input voltage (hysteresis input)	V_{IHS}	CMOS hysteresis input pin, MD0, MD1	-	Vcc × 0.8	-	Vcc + 0.3	V	*1
		5 V tolerant input pin	-	Vcc × 0.8	-	Vss + 5.5	V	
		TTL Schmitt input pin	-	2.0	-	Vcc + 0.3	V	
"L" level input voltage (hysteresis input)	V_{ILS}	CMOS hysteresis input pin, MD0, MD1	-	Vss - 0.3	-	Vcc × 0.2	V	*1
		5 V tolerant input pin	-	Vss - 0.3	-	Vcc × 0.2	V	
		TTL Schmitt input pin	-	Vss - 0.3	-	0.8	V	
"H" level output voltage	V_{OH}	4 mA type	Vcc ≥ 4.5 V, I_{OH} = - 4 mA Vcc < 4.5 V, I_{OH} = - 2 mA	Vcc - 0.5	-	Vcc	V	*1
		8 mA type	Vcc ≥ 4.5 V, I_{OH} = - 8 mA Vcc < 4.5 V, I_{OH} = - 4 mA	Vcc - 0.5	-	Vcc	V	*1
		12 mA type	Vcc ≥ 4.5 V, I_{OH} = - 12 mA Vcc < 4.5 V, I_{OH} = - 8 mA	Vcc - 0.5	-	Vcc	V	
		P80, P81, P82, P83	Vcc ≥ 4.5 V, I_{OH} = - 20.5 mA Vcc < 4.5 V, I_{OH} = - 13.0 mA	Vcc - 0.4	-	Vcc	V	*2

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"L" level output voltage	V_{OL}	4 mA type	Vcc ≥ 4.5 V, I_{OL} = 4 mA Vcc < 4.5 V, I_{OL} = 2 mA	Vss	-	0.4	V	*1
		8 mA type	Vcc ≥ 4.5 V, I_{OL} = 8 mA Vcc < 4.5 V, I_{OL} = 4 mA	Vss	-	0.4	V	*1
		12 mA type	Vcc ≥ 4.5 V, I_{OL} = 12 mA Vcc < 4.5 V, I_{OL} = 8 mA	Vss	-	0.4	V	
		P80, P81, P82, P83	Vcc ≥ 4.5 V, I_{OL} = 18.5 mA Vcc < 4.5 V, I_{OL} = 10.5 mA	Vss	-	0.4	V	*2
Input leak current	I_{IL}	-	-	- 5	-	+ 5	µA	
Pull-up resistance value	R_{PU}	Pull-up pin	Vcc ≥ 4.5 V	25	50	100	kΩ	
			Vcc < 4.5 V	30	80	200		
Input capacitance	C_{IN}	Other than VCC, VSS, AVCC, AVSS, AVRH	-	-	5	15	pF	

4. AC Characteristics

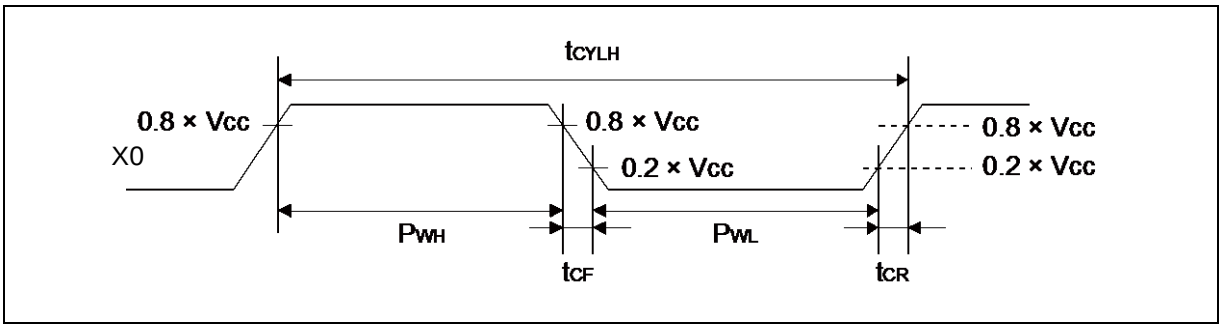
(1) Main Clock Input Characteristics

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input frequency	F_{CH}	X0, X1	Vcc ≥ 4.5 V	4	48	MHz	When crystal oscillator is connected
			Vcc < 4.5 V	4	20		
			Vcc ≥ 4.5 V	4	48	MHz	When using external clock
			Vcc < 4.5 V	4	20		
Input clock cycle	t_{CYLH}		Vcc ≥ 4.5 V	20.83	250	ns	When using external clock
			Vcc < 4.5 V	50	250		
Input clock pulse width	-		P_{WH}/t_{CYLH}, P_{WL}/t_{CYLH}	45	55	%	When using external clock
Input clock rise time and fall time	t_{CF}, t_{CR}		-	-	5	ns	When using external clock
Internal operating clock*1 frequency	F_{CM}	-	-	-	144	MHz	Master clock
	F_{CC}	-	-	-	144	MHz	Base clock (HCLK/FCLK)
	F_{CP0}	-	-	-	72	MHz	APB0 bus clock*2
	F_{CP1}	-	-	-	72	MHz	APB1 bus clock*2
	F_{CP2}	-	-	-	72	MHz	APB2 bus clock*2
Internal operating clock*1 cycle time	t_{CYCC}	-	-	6.94	-	ns	Base clock (HCLK/FCLK)
	t_{CYCP0}	-	-	13.8	-	ns	APB0 bus clock*2
	t_{CYCP1}	-	-	13.8	-	ns	APB1 bus clock*2
	t_{CYCP2}	-	-	13.8	-	ns	APB2 bus clock*2

*1: For more information about each internal operating clock, see "CHAPTER 2-1: Clock" in "FM3 Family PERIPHERAL MANUAL".

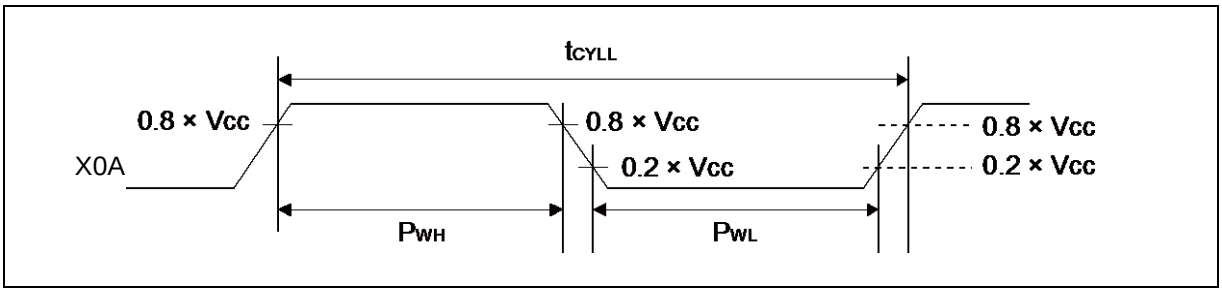
*2: For about each APB bus which each peripheral is connected to, see "■Block Diagram" in this data sheet.



(2) Sub Clock Input Characteristics

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input frequency	$1/t_{CYLL}$	X0A, X1A	-	-	32.768	-	kHz	When crystal oscillator is connected
			-	32	-	100	kHz	When using external clock
Input clock cycle	t_{CYLL}		-	10	-	31.25	µs	When using external clock
Input clock pulse width	-		P_{WH}/t_{CYLL}, P_{WL}/t_{CYLL}	45	-	55	%	When using external clock



(3) Internal CR Oscillation Characteristics

・ High-speed Internal CR

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	F_{CRH}	Ta = + 25°C	3.96	4	4.04	MHz	When trimming*
		Ta = 0°C to + 70°C	3.84	4	4.16		
		Ta = - 40°C to + 85°C	3.8	4	4.2		
		Ta = - 40°C to + 85°C	3	4	5		When not trimming
Frequency stability time	t_{CRWT}	-	-	-	90	µs	*2

*1: In the case of using the values in CR trimming area of Flash memory at shipment for frequency trimming.

*2: Frequency stable time is time to stable of the frequency of the High-speed CR.
clock after the trim value is set. After setting the trim value, the period when the frequency stability time passes can use the High-speed CR clock as a source clock.

・ Low-speed Internal CR

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	F_{CRL}	-	50	100	150	kHz	

(4-1) Operating Conditions of Main PLL (In the case of using main clock for input of PLL)

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
PLL oscillation stabilization wait time*1 (LOCK UP time)	t_{LOCK}	100	-	-	µs	
PLL input clock frequency	F_{PLLI}	4	-	16	MHz	
PLL multiple rate	-	13	-	75	multiple	
PLL macro oscillation clock frequency	F_{PLLO}	200	-	300	MHz	
Main PLL clock frequency*2	F_{CLKPLL}	-	-	144	MHz	

*1: Time from when the PLL starts operating until the oscillation stabilizes.

*2: For more information about Main PLL clock (CLKPLL), see "CHAPTER 2-1: Clock" in "FM3 Family PERIPHERAL MANUAL".

(4-2) Operating Conditions of Main PLL (In the case of using high-speed internal CR)

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

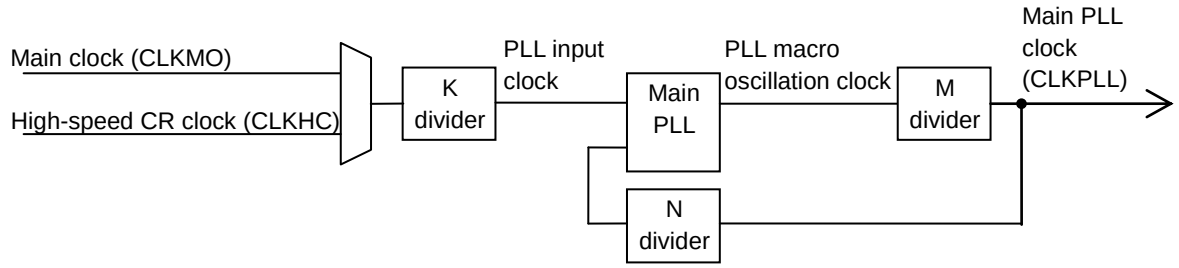
Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
PLL oscillation stabilization wait time*1 (LOCK UP time)	t_{LOCK}	100	-	-	µs	
PLL input clock frequency	F_{PLLI}	3.8	4	4.2	MHz	
PLL multiple rate	-	50	-	71	multiple	
PLL macro oscillation clock frequency	F_{PLLO}	190	-	300	MHz	
Main PLL clock frequency*2	F_{CLKPLL}	-	-	144	MHz	

*1: Time from when the PLL starts operating until the oscillation stabilizes.

*2: For more information about Main PLL clock (CLKPLL), see "CHAPTER 2-1: Clock" in "FM3 Family PERIPHERAL MANUAL".

Note: Make sure to input to the main PLL source clock, the high-speed CR clock (CLKHC) that the frequency has been trimmed.

Main PLL connection



(5) Reset Input Characteristics

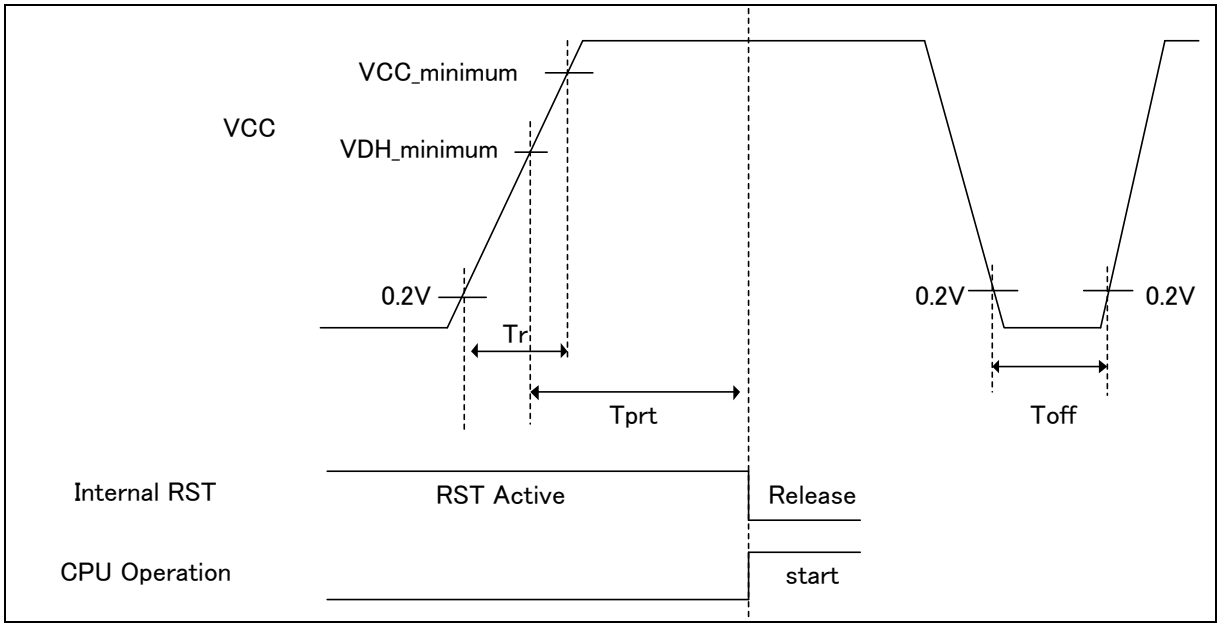
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Reset input time	t_{INITX}	INITX	-	500	-	ns	

(6) Power-on Reset Timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Value		Unit	Remarks
			Min	Max		
Power supply rising time	Tr	VCC	0	-	ms	
Power supply shut down time	Toff		1	-	ms	
Time until releasing Power-on reset	Tprt		0.46	0.76	ms	



Glossary

- VCC_minimum : Minimum V_{CC} of recommended operating conditions
- VDH_minimum : Minimum release voltage of Low-Voltage detection reset. See "6. Low-Voltage Detection Characteristics"

(7) External Bus Timing

- External bus clock output characteristics

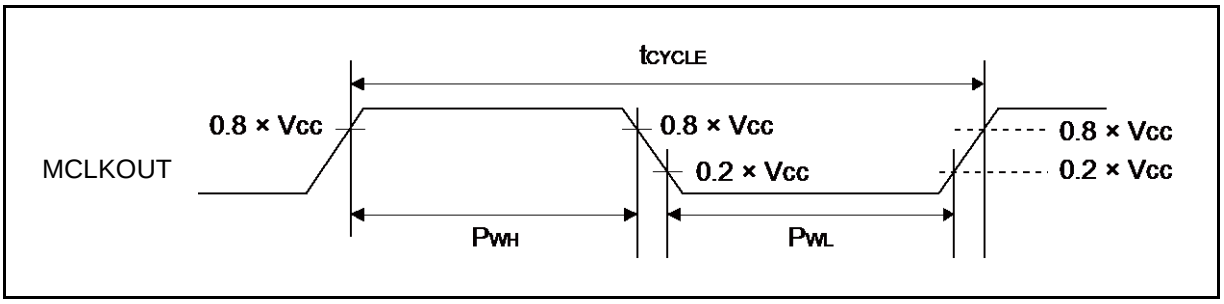
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Output frequency	t_{CYCLE}	MCLKOUT*1	Vcc ≥ 4.5 V	-	50*2	MHz
			Vcc < 4.5 V	-	32*3	MHz

*1: External bus clock (MCLKOUT) is divided clock of HCLK.
For more information about setting of clock divider, see "CHAPTER 12: External Bus Interface" in "FM3 Family PERIPHERAL MANUAL".
When external bus clock is not output, this characteristic does not give any effect on external bus operation.

*2: When AHB bus clock frequency is more than 100 MHz, the divider setting for MCLKOUT must be more than 4.

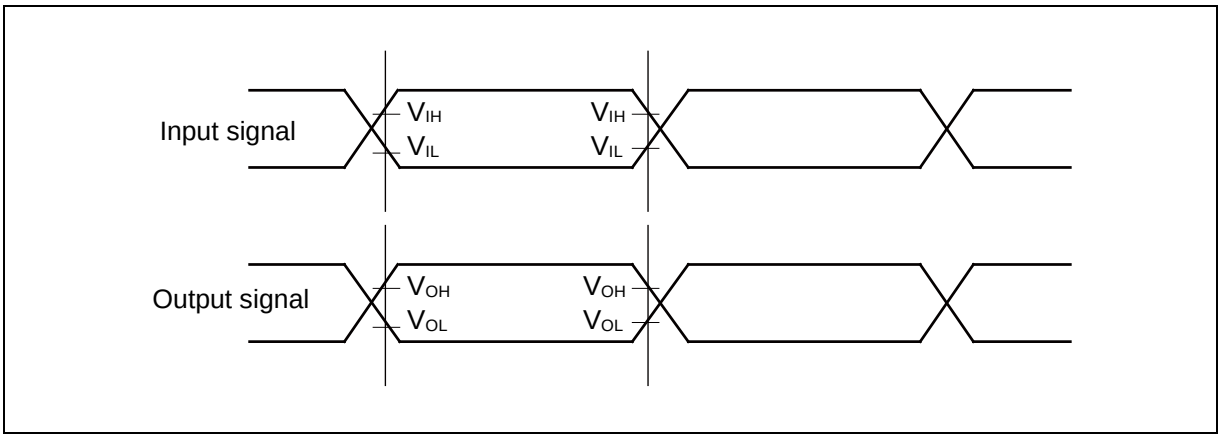
*3: When AHB bus clock frequency is more than 64 MHz, the divider setting for MCLKOUT must be more than 4.



- External bus signal input/output characteristics

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value	Unit	Remarks
Signal input characteristics	V_{IH}	-	0.8 × V_{CC}	V	
	V_{IL}		0.2 × V_{CC}	V	
Signal output characteristics	V_{OH}		0.8 × V_{CC}	V	
	V_{OL}		0.2 × V_{CC}	V	

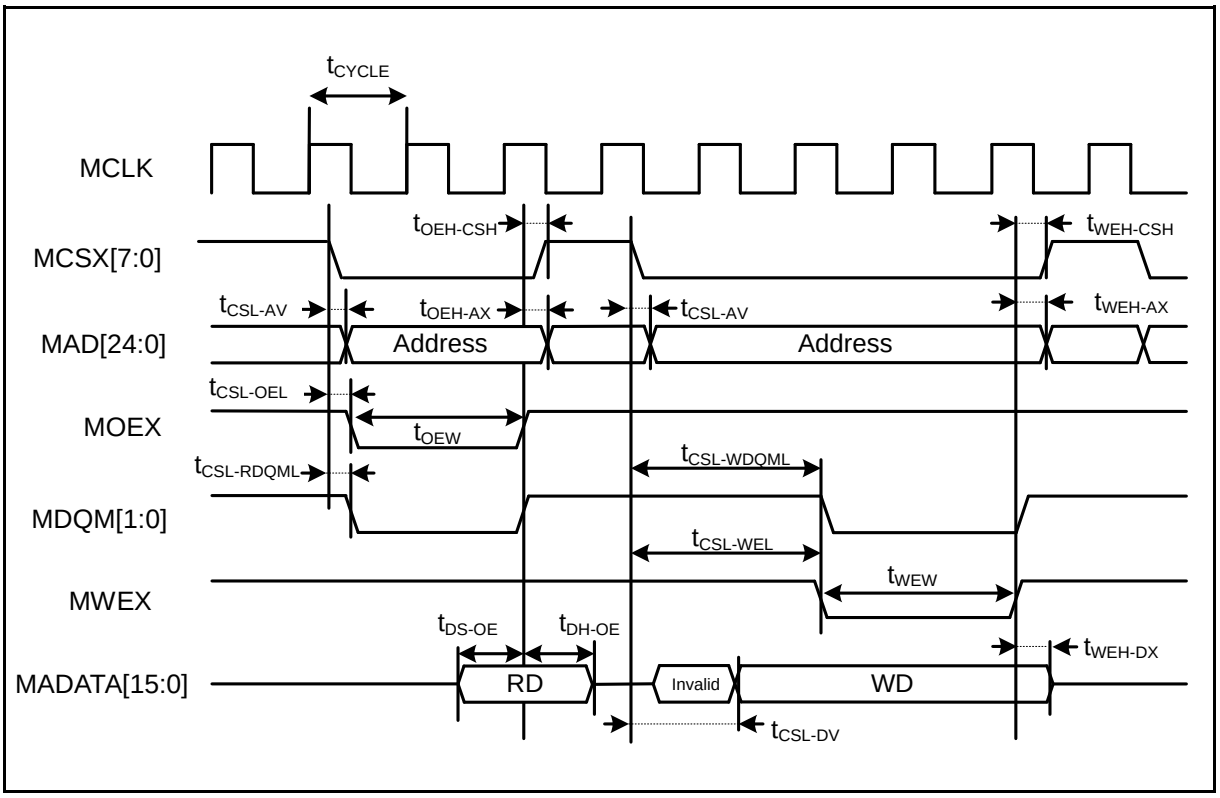


- Separate Bus Access Asynchronous SRAM Mode

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
MOEX Min pulse width	t_{OEW}	MOEX	Vcc ≥ 4.5 V	MCLK×n-3	-	ns
			Vcc < 4.5 V			
MCSX ↓ → Address output delay time	$t_{CSL - AV}$	MCSX[7:0], MAD[24:0]	Vcc ≥ 4.5 V	-9	+9	ns
			Vcc < 4.5 V	-12	+12	
MOEX ↑ → Address hold time	$t_{OEH - AX}$	MOEX, MAD[24:0]	Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	
MCSX ↓ → MOEX ↓ delay time	$t_{CSL - OEL}$	MOEX, MCSX[7:0]	Vcc ≥ 4.5 V	MCLK×m-9	MCLK×m+9	ns
			Vcc < 4.5 V	MCLK×m-12	MCLK×m+12	
MOEX ↑ → MCSX ↑ time	$t_{OEH - CSH}$		Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	
MCSX ↓ → MDQM ↓ delay time	$t_{CSL - RDQML}$	MCSX, MDQM[1:0]	Vcc ≥ 4.5 V	MCLK×m-9	MCLK×m+9	ns
			Vcc < 4.5 V	MCLK×m-12	MCLK×m+12	
Data set up → MOEX ↑ time	$t_{DS - OE}$	MOEX, MADATA[15:0]	Vcc ≥ 4.5 V	20	-	ns
			Vcc < 4.5 V	38	-	
MOEX ↑ → Data hold time	$t_{DH - OE}$	MOEX, MADATA[15:0]	Vcc ≥ 4.5 V	0	-	ns
			Vcc < 4.5 V			
MWEX Min pulse width	t_{WEW}	MWEX	Vcc ≥ 4.5 V	MCLK×n-3	-	ns
			Vcc < 4.5 V			
MWEX ↑ → Address output delay time	$t_{WEH - AX}$	MWEX, MAD[24:0]	Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	
MCSX ↓ → MWEX ↓ delay time	$t_{CSL - WEL}$	MWEX, MCSX[7:0]	Vcc ≥ 4.5 V	MCLK×n-9	MCLK×n+9	ns
			Vcc < 4.5 V	MCLK×n-12	MCLK×n+12	
MWEX ↑ → MCSX ↑ delay time	$t_{WEH - CSH}$		Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	
MCSX ↓ → MDQM ↓ delay time	$t_{CSL-WDQML}$	MCSX, MDQM[1:0]	Vcc ≥ 4.5 V	MCLK×n-9	MCLK×n+9	ns
			Vcc < 4.5 V	MCLK×n-12	MCLK×n+12	
MCSX ↓ → Data output time	$t_{CSL - DV}$	MCSX, MADATA[15:0]	Vcc ≥ 4.5 V	MCLK-9	MCLK+9	ns
			Vcc < 4.5 V	MCLK-12	MCLK+12	
MWEX ↑ → Data hold time	$t_{WEH - DX}$	MWEX, MADATA[15:0]	Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	

Note: When the external load capacitance = 30 pF. (m = 0 to 15, n = 1 to 16)

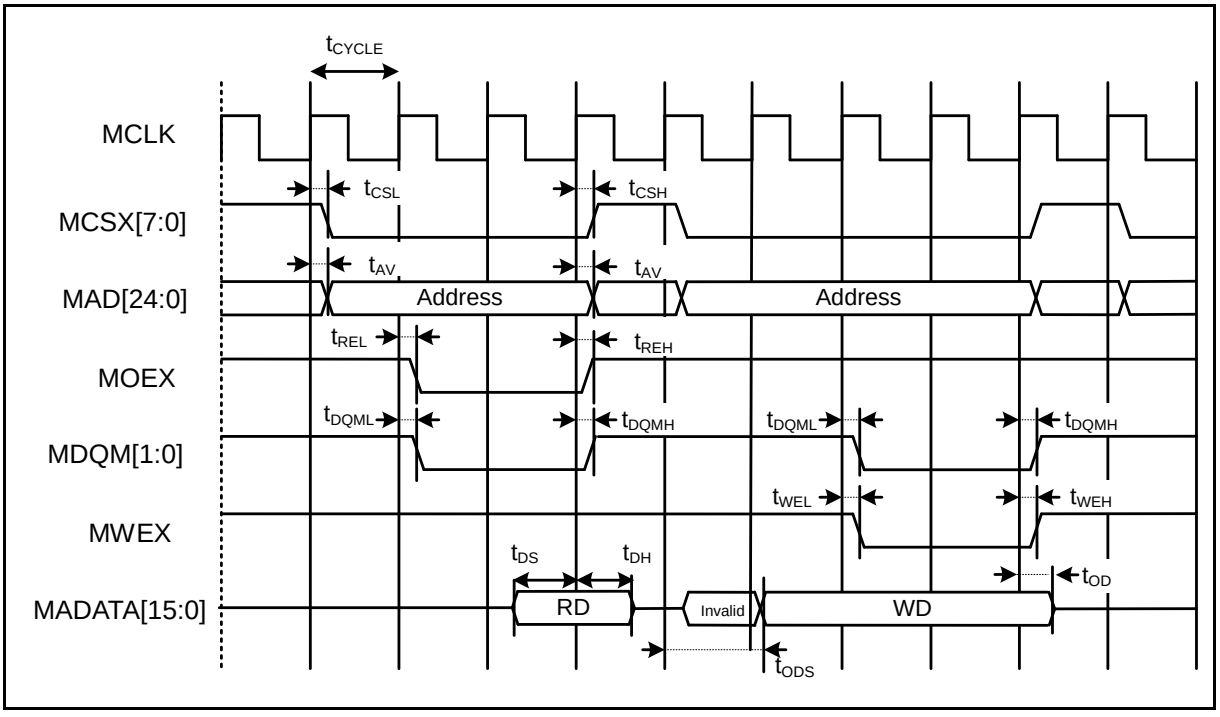

tCYCLE
MCLK
MCSX[7:0]
tOEH-CSH
tWEH-CSH
MAD[24:0]
tCSL-AV
tOEH-AX
tCSL-AV
tWEH-AX
Address
Address
MOEX
tCSL-OEL
tOEW
MDQM[1:0]
tCSL-RDQML
tCSL-WDQML
MWEX
tCSL-WEL
tWEW
MADATA[15:0]
tDS-OE
tDH-OE
tWEH-DX
RD
Invalid
WD
tCSL-DV

- Separate Bus Access Synchronous SRAM Mode

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Address delay time	t_{AV}	MCLK, MAD[24:0]	Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
MCSX delay time	t_{CSL}	MCLK, MCSX[7:0]	Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
	t_{CSH}		Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
MOEX delay time	t_{REL}	MCLK, MOEX	Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
	t_{REH}		Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
Data set up → MCLK ↑ time	t_{DS}	MCLK, MADATA[15:0]	Vcc ≥ 4.5 V	19	-	ns
			Vcc < 4.5 V	37		
MCLK ↑ → Data hold time	t_{DH}	MCLK, MADATA[15:0]	Vcc ≥ 4.5 V	0	-	ns
			Vcc < 4.5 V			
MWEX delay time	t_{WEL}	MCLK, MWEX	Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
	t_{WEH}		Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
MDQM[1:0] delay time	t_{DQML}	MCLK, MDQM[1:0]	Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
	t_{DQMH}		Vcc ≥ 4.5 V	1	9	ns
			Vcc < 4.5 V		12	
MCLK ↑ → Data output time	t_{OD}	MCLK, MADATA[15:0]	Vcc ≥ 4.5 V	MCLK+1	MCLK+18	ns
			Vcc < 4.5 V		MCLK+24	
MCLK ↑ → Data hold time	t_{OD}	MCLK, MADATA[15:0]	Vcc ≥ 4.5 V	1	18	ns
			Vcc < 4.5 V		24	

Note: When the external load capacitance = 30 pF.

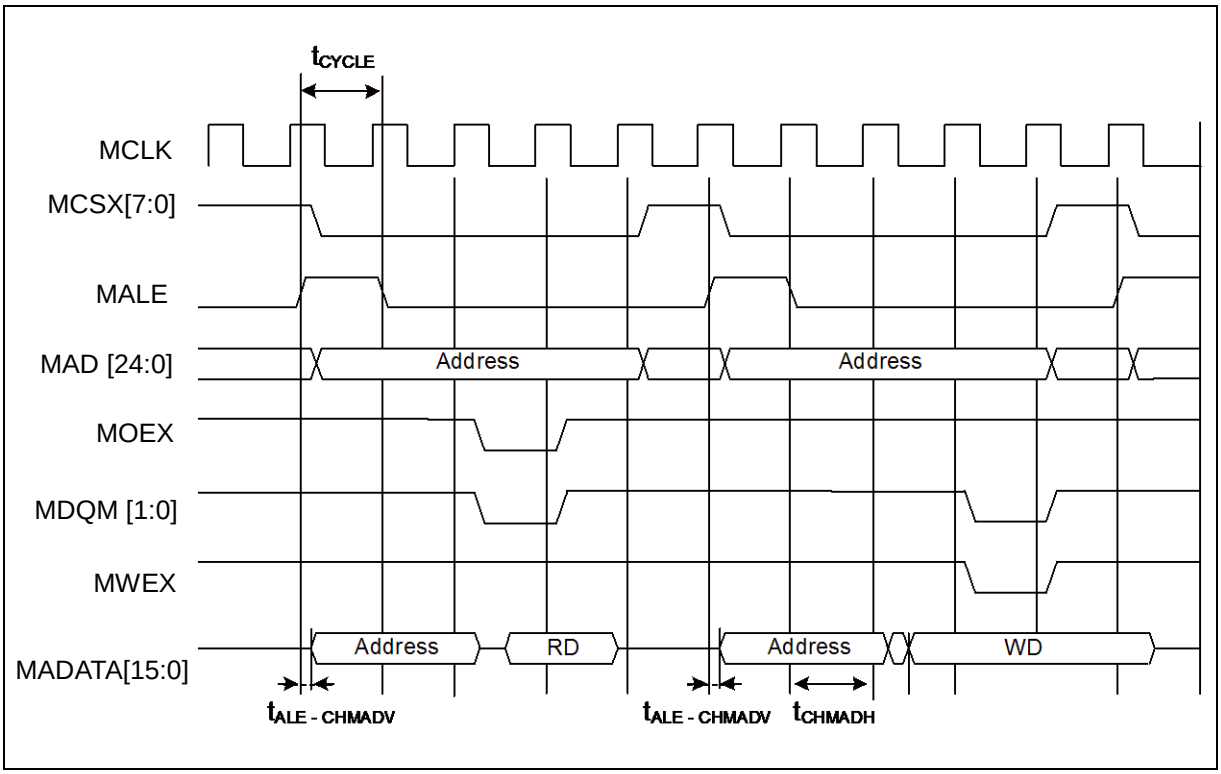


- Multiplexed Bus Access Asynchronous SRAM Mode

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Multiplexed address delay time	$t_{ALE-CHMADV}$	MALE, MADATA[15:0]	Vcc ≥ 4.5 V	0	10	ns
			Vcc < 4.5 V		20	
Multiplexed address hold time	t_{CHMADH}		Vcc ≥ 4.5 V	MCLK×n+0	MCLK×n+10	ns
			Vcc < 4.5 V	MCLK×n+0	MCLK×n+20	

Note: When the external load capacitance = 30 pF. (m = 0 to 15, n = 1 to 16)

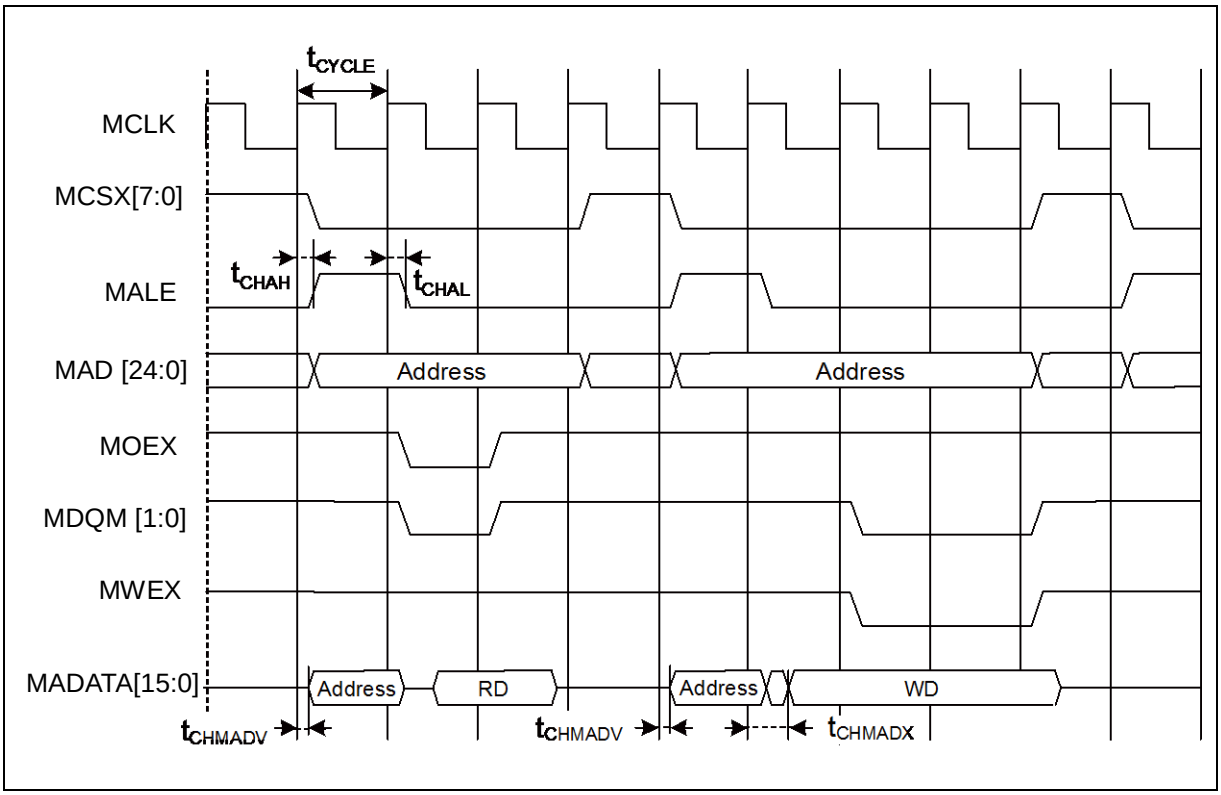


- Multiplexed Bus Access Synchronous SRAM Mode

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
MALE delay time	t_{CHAL}	MCLK, ALE	Vcc ≥ 4.5 V	1	9	ns	
			Vcc < 4.5 V		12	ns	
	t_{CHAH}		Vcc ≥ 4.5 V	1	9	ns	
			Vcc < 4.5 V		12	ns	
MCLK ↑ → Multiplexed Address delay time	t_{CHMADV}	MCLK, MADATA[15:0]	Vcc ≥ 4.5 V	1	t_{OD}	ns	
			Vcc < 4.5 V				
MCLK ↑ → Multiplexed Data output time	t_{CHMADX}		Vcc ≥ 4.5 V	1	t_{OD}	ns	
			Vcc < 4.5 V				

Note: When the external load capacitance = 30 pF.

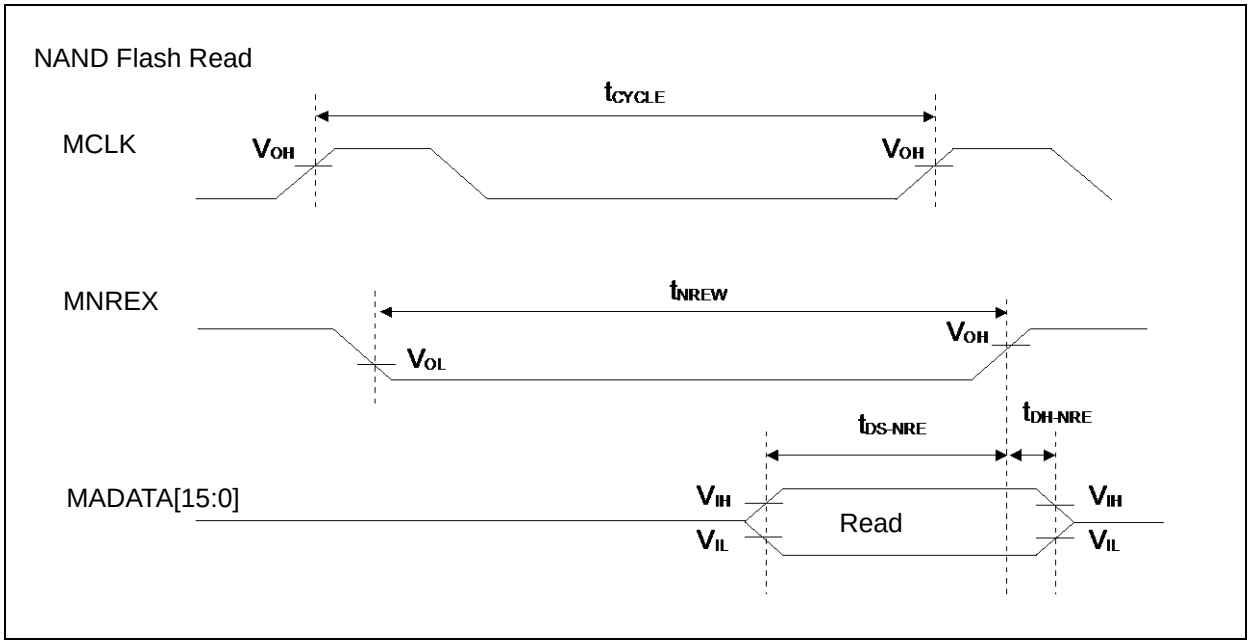


- NAND Flash Mode

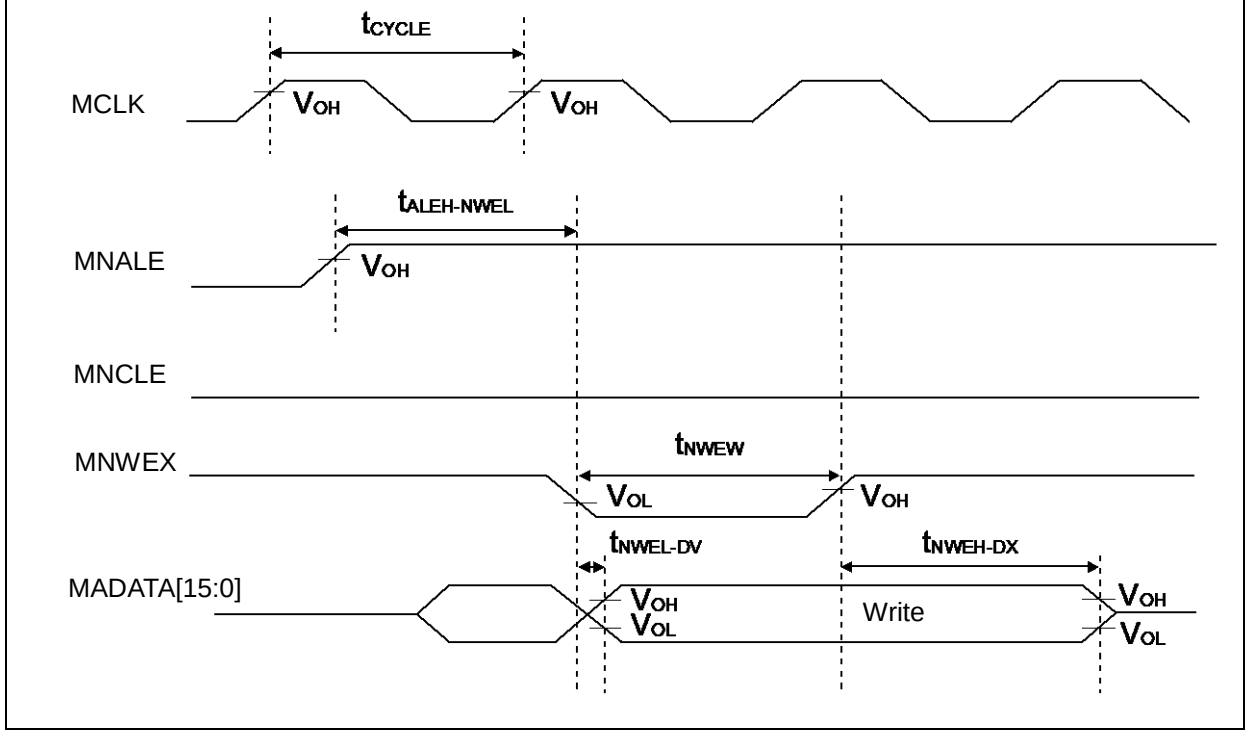
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
MNREX Min pulse width	t_{NREW}	MNREX	Vcc ≥ 4.5 V	MCLK×n-3	-	ns
			Vcc < 4.5 V			
Data setup → MNREX↑time	t_{DS-NRE}	MNREX, MADATA[15:0]	Vcc ≥ 4.5 V	20	-	ns
			Vcc < 4.5 V	38	-	
MNREX↑→ Data hold time	t_{DH-NRE}	MNREX, MADATA[15:0]	Vcc ≥ 4.5 V	0	-	ns
			Vcc < 4.5 V			
MNALE↑→ MNWEX delay time	$t_{ALEH-NWEL}$	MNALE, MNWEX	Vcc ≥ 4.5 V	MCLK×m-9	MCLK×m+9	ns
			Vcc < 4.5 V	MCLK×m-12	MCLK×m+12	
MNALE↓→ MNWEX delay time	$t_{ALEL-NWEL}$	MNALE, MNWEX	Vcc ≥ 4.5 V	MCLK×m-9	MCLK×m+9	ns
			Vcc < 4.5 V	MCLK×m-12	MCLK×m+12	
MNCLE↑→ MNWEX delay time	$t_{CLEH-NWEL}$	MNCLE, MNWEX	Vcc ≥ 4.5 V	MCLK×m-9	MCLK×m+9	ns
			Vcc < 4.5 V	MCLK×m-12	MCLK×m+12	
MNWEX↑→ MNCLE delay time	$t_{NWEH-CLEL}$	MNCLE, MNWEX	Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	
MNWEX Min pulse width	t_{NWEW}	MNWEX	Vcc ≥ 4.5 V	MCLK×n-3	-	ns
			Vcc < 4.5 V			
MNWEX↓→ Data output time	$t_{NWEL-DV}$	MNWEX, MADATA[15:0]	Vcc ≥ 4.5 V	-9	+9	ns
			Vcc < 4.5 V	-12	+12	
MNWEX↑→ Data hold time	$t_{NWEH-DX}$	MNWEX, MADATA[15:0]	Vcc ≥ 4.5 V	0	MCLK×m+9	ns
			Vcc < 4.5 V		MCLK×m+12	

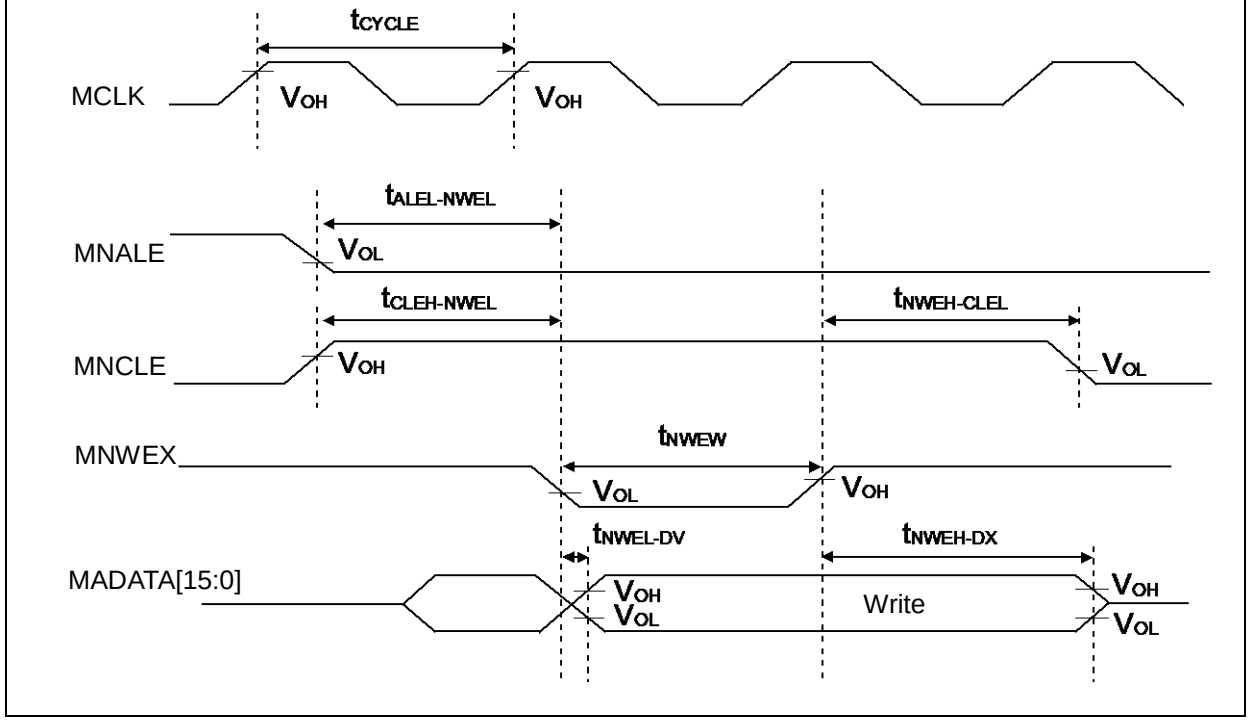
Note: When the external load capacitance = 30 pF. (m=0 to 15, n=1 to 16)



NAND Flash Address Write



NAND Flash Command Write

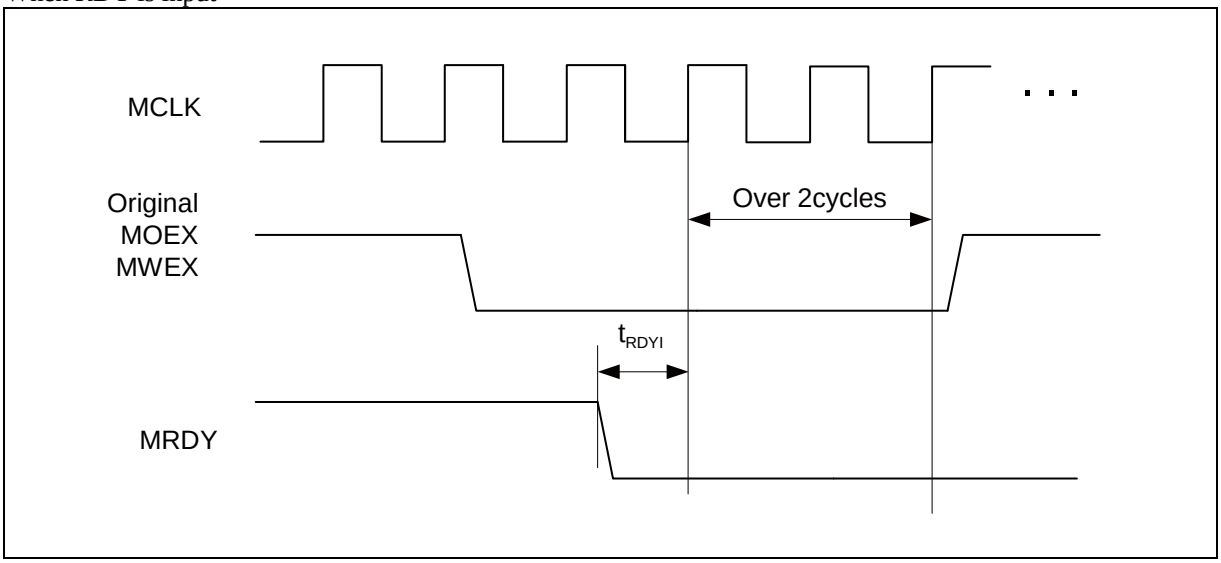


- External Ready Input Timing

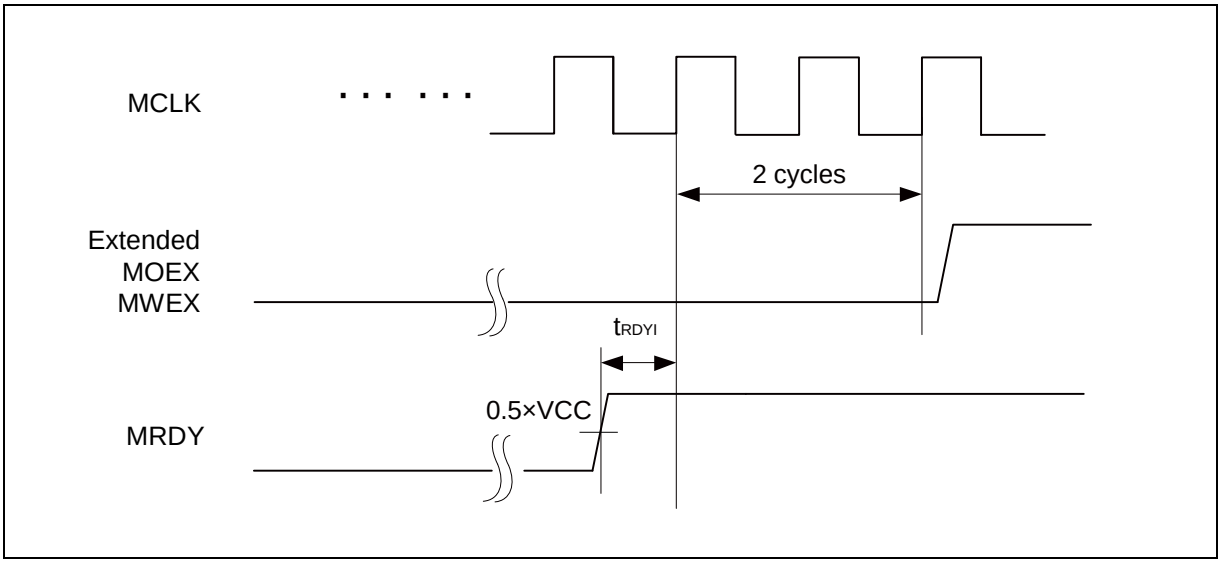
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
MCLK ↑ MRDY input setup time	t_{RDYI}	MCLK, MRDY	Vcc ≥ 4.5 V	19	-	ns	
			Vcc < 4.5 V	37			

When RDY is input



When RDY is released

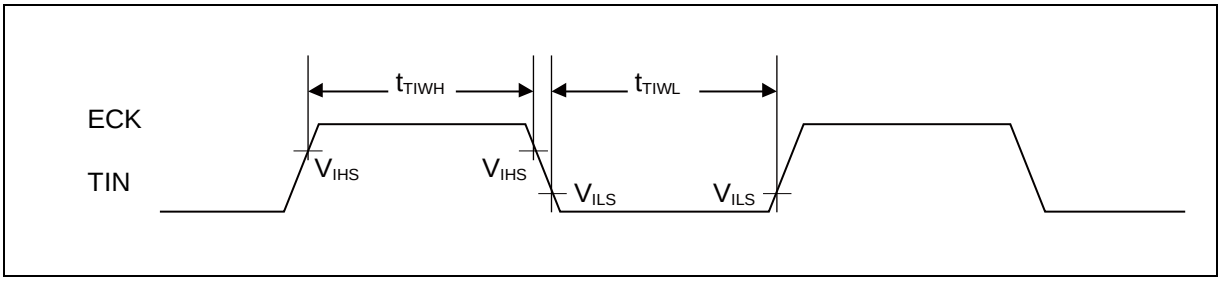


(8) Base Timer Input Timing

- Timer input timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

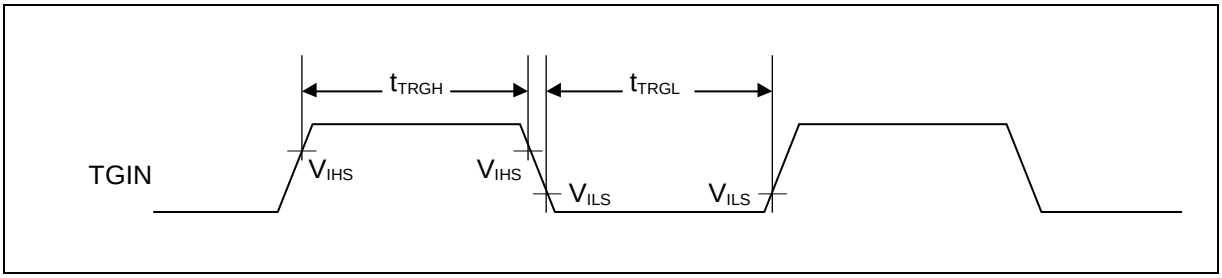
Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{TIWH}, t_{TIWL}	TIOAn/TIOBn (when using as ECK, TIN)	-	$2t_{CYCP}$	-	ns	



- Trigger input timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{TRGH}, t_{TRGL}	TIOAn/TIOBn (when using as TGIN)	-	$2t_{CYCP}$	-	ns	



Note: t_{CYCP} indicates the APB bus clock cycle time.
About the APB bus number which Base Timer is connected to, see "■Block Diagram" in this data sheet.

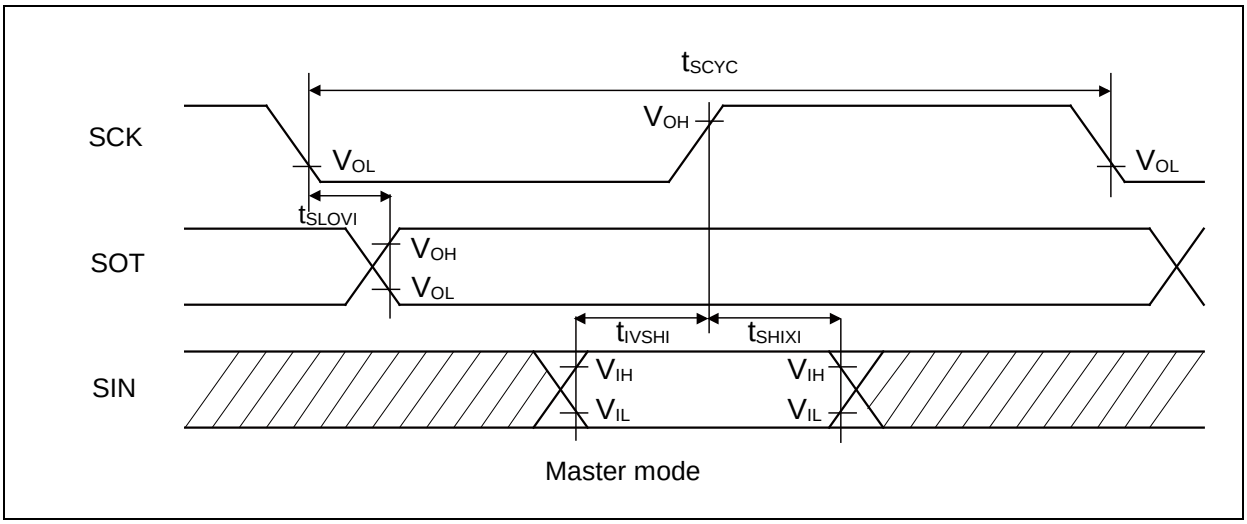
(9) CSIO/UART Timing

- CSIO (SPI = 0, SCINV = 0)

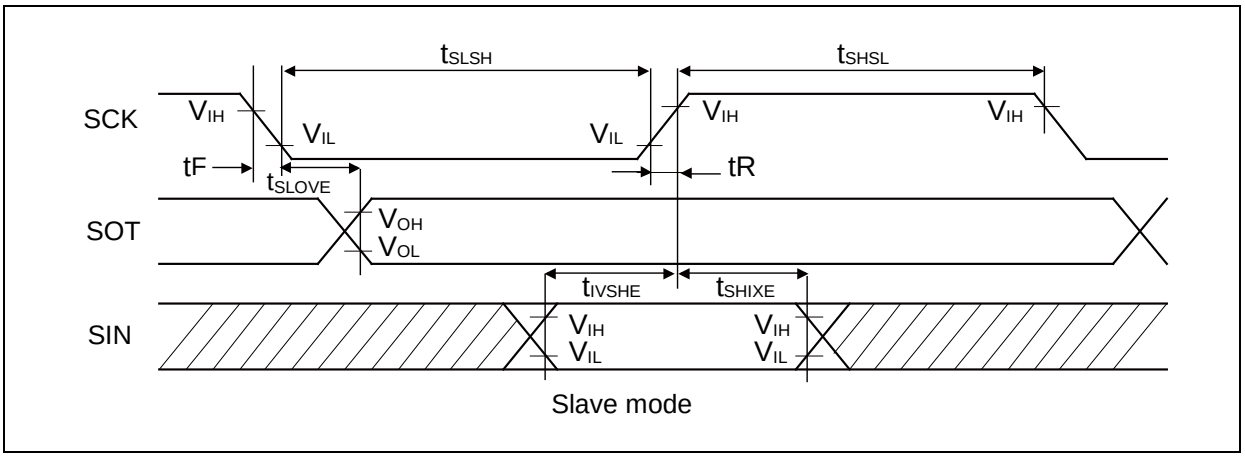
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Vcc < 4.5 V		Vcc ≥ 4.5 V		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t_{SCYC}	SCKx	Master mode	$4t_{CYCP}$	-	$4t_{CYCP}$	-	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCKx, SOTx		- 30	+ 30	- 20	+ 20	ns
SIN → SCK ↑ setup time	t_{IVSHI}	SCKx, SINx		50	-	30	-	ns
SCK ↑ → SIN hold time	t_{SHIXI}	SCKx, SINx		0	-	0	-	ns
Serial clock "L" pulse width	t_{SLSH}	SCKx	Slave mode	$2t_{CYCP}$ - 10	-	$2t_{CYCP}$ - 10	-	ns
Serial clock "H" pulse width	t_{SHSL}	SCKx		t_{CYCP} + 10	-	t_{CYCP} + 10	-	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCKx, SOTx		-	50	-	30	ns
SIN → SCK ↑ setup time	t_{IVSHE}	SCKx, SINx		10	-	10	-	ns
SCK ↑ → SIN hold time	t_{SHIXE}	SCKx, SINx		20	-	20	-	ns
SCK fall time	tF	SCKx		-	5	-	5	ns
SCK rise time	tR	SCKx		-	5	-	5	ns

Notes:
- The above characteristics apply to CLK synchronous mode.
- t_{CYCP} indicates the APB bus clock cycle time.
  About the APB bus number which Multi-function Serial is connected to, see "■Block Diagram" in this data sheet.
- These characteristics only guarantee the same relocate port number.
  For example, the combination of SCKx_0 and SOTx_1 is not guaranteed.
- When the external load capacitance = 30 pF.



Master mode



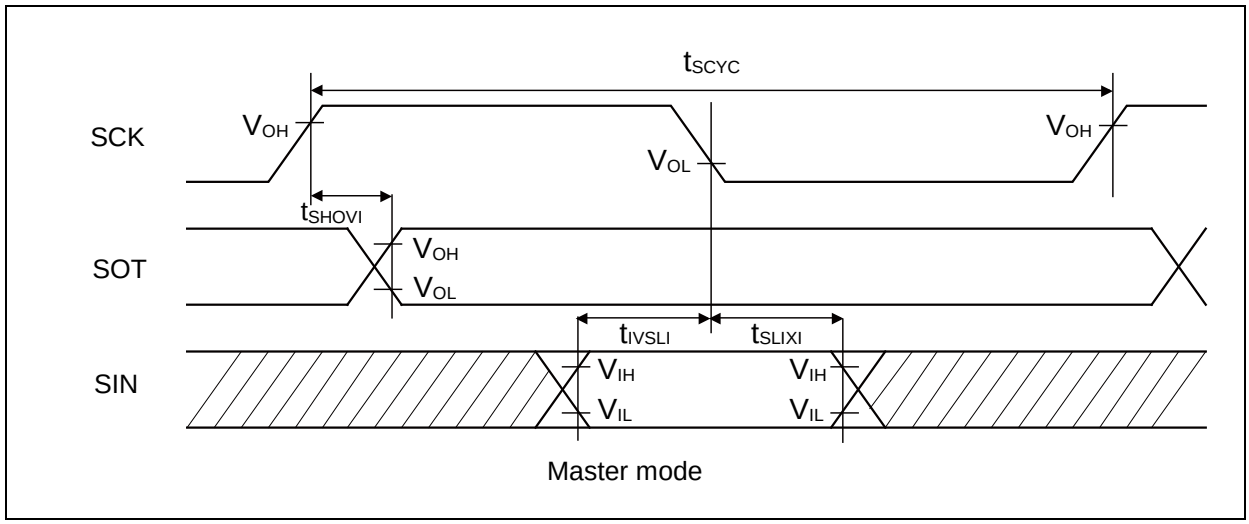
Slave mode

- CSIO (SPI = 0, SCINV = 1)

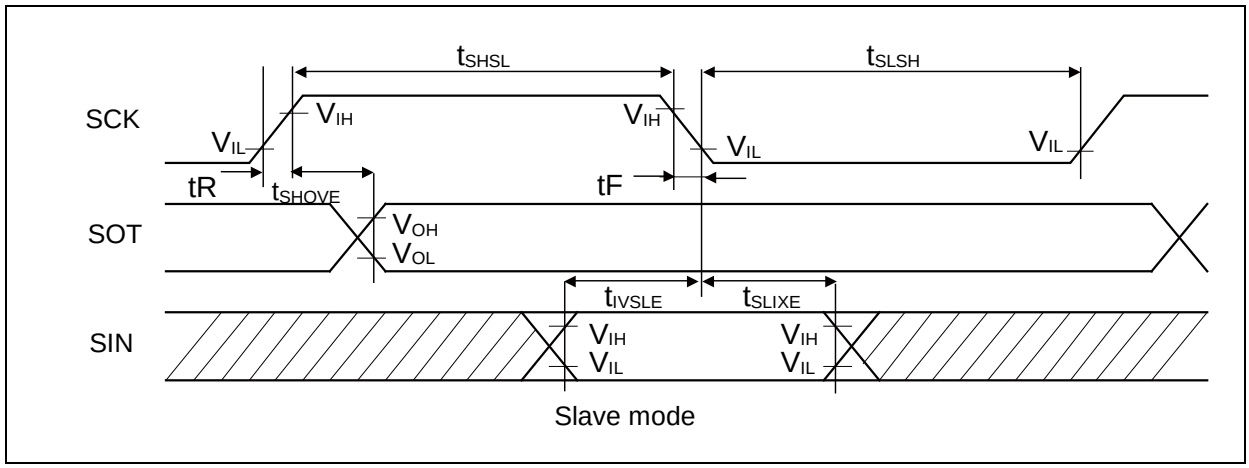
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Vcc < 4.5 V		Vcc ≥ 4.5 V		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t_{SCYC}	SCKx	Master mode	$4t_{CYCP}$	-	$4t_{CYCP}$	-	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCKx, SOTx		- 30	+ 30	- 20	+ 20	ns
SIN → SCK ↓ setup time	t_{IVSLI}	SCKx, SINx		50	-	30	-	ns
SCK ↓ → SIN hold time	t_{SLIXI}	SCKx, SINx		0	-	0	-	ns
Serial clock "L" pulse width	t_{SLSH}	SCKx	Slave mode	$2t_{CYCP}$ - 10	-	$2t_{CYCP}$ - 10	-	ns
Serial clock "H" pulse width	t_{SHSL}	SCKx		t_{CYCP} + 10	-	t_{CYCP} + 10	-	ns
SCK ↑ → SOT delay time	t_{SHOVE}	SCKx, SOTx		-	50	-	30	ns
SIN → SCK ↓ setup time	t_{IVSLE}	SCKx, SINx		10	-	10	-	ns
SCK ↓ → SIN hold time	t_{SLIXE}	SCKx, SINx		20	-	20	-	ns
SCK fall time	tF	SCKx		-	5	-	5	ns
SCK rise time	tR	SCKx		-	5	-	5	ns

Notes:
- The above characteristics apply to CLK synchronous mode.
- t_{CYCP} indicates the APB bus clock cycle time.
  About the APB bus number which Multi-function Serial is connected to, see "■Block Diagram" in this data sheet.
- These characteristics only guarantee the same relocate port number.
  For example, the combination of SCKx_0 and SOTx_1 is not guaranteed.
- When the external load capacitance = 30 pF.



Master mode



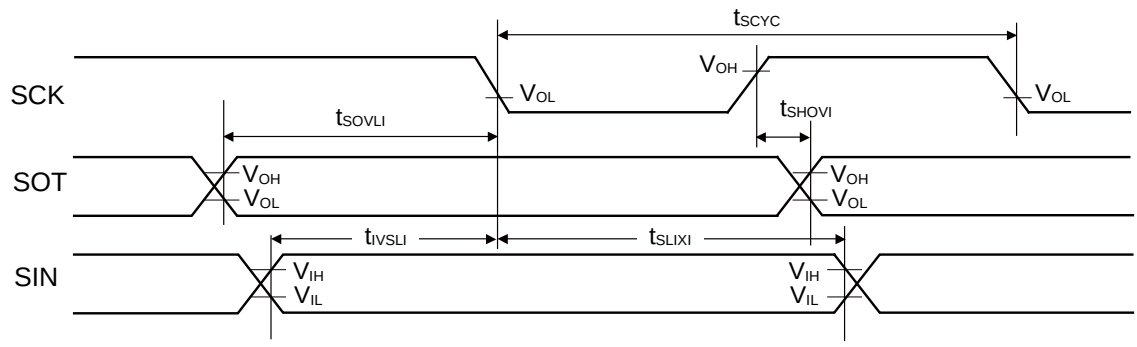
Slave mode

- CSIO (SPI = 1, SCINV = 0)

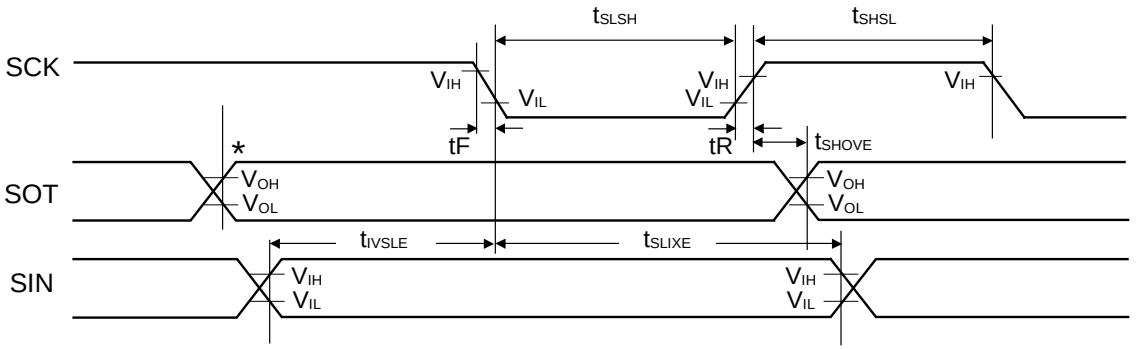
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Vcc < 4.5 V		Vcc ≥ 4.5 V		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t_{SCYC}	SCKx	Master mode	$4t_{CYCP}$	-	$4t_{CYCP}$	-	ns
SCK ↑ → SOT delay time	t_{SHOVI}	SCKx, SOTx		- 30	+ 30	- 20	+ 20	ns
SIN → SCK ↓ setup time	t_{IVSLI}	SCKx, SINx		50	-	30	-	ns
SCK ↓ → SIN hold time	t_{SLIXI}	SCKx, SINx		0	-	0	-	ns
SOT → SCK ↓ delay time	t_{SOVLI}	SCKx, SOTx		$2t_{CYCP}$ - 30	-	$2t_{CYCP}$ - 30	-	ns
Serial clock "L" pulse width	t_{SLSH}	SCKx	Slave mode	$2t_{CYCP}$ - 10	-	$2t_{CYCP}$ - 10	-	ns
Serial clock "H" pulse width	t_{SHSL}	SCKx		t_{CYCP} + 10	-	t_{CYCP} + 10	-	ns
SCK ↑ → SOT delay time	t_{SHOVE}	SCKx, SOTx		-	50	-	30	ns
SIN → SCK ↓ setup time	t_{IVSLE}	SCKx, SINx		10	-	10	-	ns
SCK ↓ → SIN hold time	t_{SLIXE}	SCKx, SINx		20	-	20	-	ns
SCK fall time	tF	SCKx		-	5	-	5	ns
SCK rise time	tR	SCKx		-	5	-	5	ns

Notes:
- The above characteristics apply to CLK synchronous mode.
- t_{CYCP} indicates the APB bus clock cycle time.
  About the APB bus number which Multi-function Serial is connected to, see "■Block Diagram" in this data sheet.
- These characteristics only guarantee the same relocate port number.
  For example, the combination of SCKx_0 and SOTx_1 is not guaranteed.
- When the external load capacitance = 30 pF.



Master mode



Slave mode

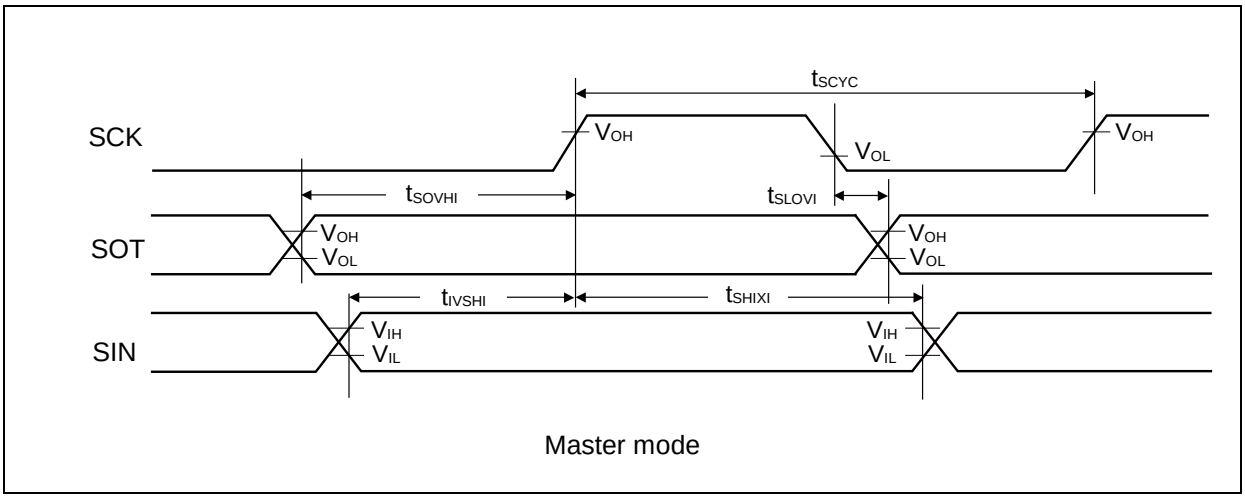
*: Changes when writing to TDR register

- CSIO (SPI = 1, SCINV = 1)

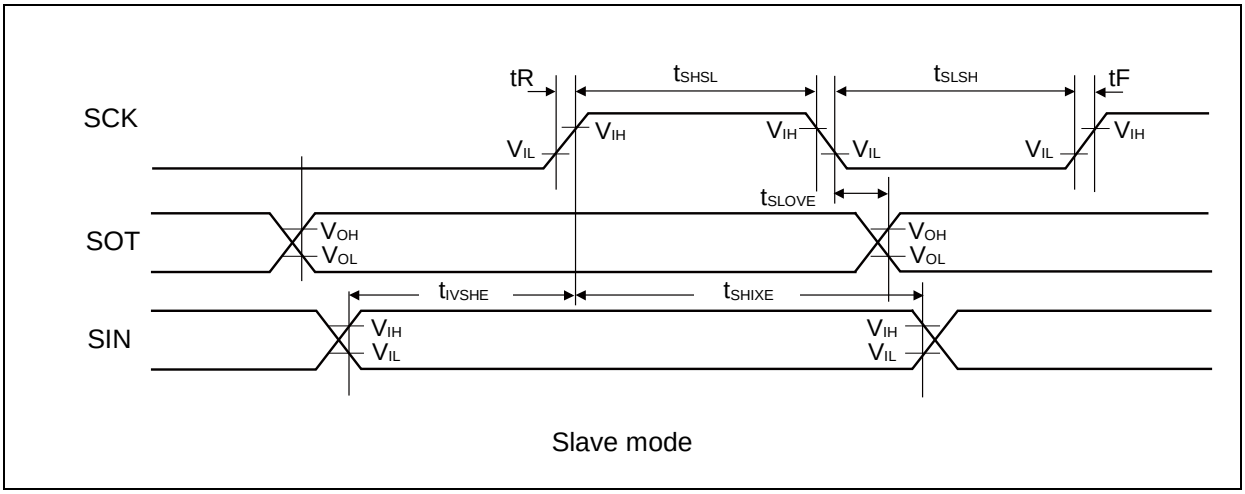
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Vcc < 4.5 V		Vcc ≥ 4.5 V		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t_{SCYC}	SCKx	Master mode	$4t_{CYCP}$	-	$4t_{CYCP}$	-	ns
SCK ↓ → SOT delay time	t_{SLOVI}	SCKx, SOTx		- 30	+ 30	- 20	+ 20	ns
SIN → SCK ↑ setup time	t_{IVSHI}	SCKx, SINx		50	-	30	-	ns
SCK ↑ → SIN hold time	t_{SHIXI}	SCKx, SINx		0	-	0	-	ns
SOT → SCK ↑ delay time	t_{SOVHI}	SCKx, SOTx		$2t_{CYCP}$ - 30	-	$2t_{CYCP}$ - 30	-	ns
Serial clock "L" pulse width	t_{SLSH}	SCKx	Slave mode	$2t_{CYCP}$ - 10	-	$2t_{CYCP}$ - 10	-	ns
Serial clock "H" pulse width	t_{SHSL}	SCKx		t_{CYCP} + 10	-	t_{CYCP} + 10	-	ns
SCK ↓ → SOT delay time	t_{SLOVE}	SCKx, SOTx		-	50	-	30	ns
SIN → SCK ↑ setup time	t_{IVSHE}	SCKx, SINx		10	-	10	-	ns
SCK ↑ → SIN hold time	t_{SHIXE}	SCKx, SINx		20	-	20	-	ns
SCK fall time	tF	SCKx		-	5	-	5	ns
SCK rise time	tR	SCKx		-	5	-	5	ns

Notes:
- The above characteristics apply to CLK synchronous mode.
- t_{CYCP} indicates the APB bus clock cycle time.
  About the APB bus number which Multi-function Serial is connected to, see "■Block Diagram" in this data sheet.
- These characteristics only guarantee the same relocate port number.
  For example, the combination of SCKx_0 and SOTx_1 is not guaranteed.
- When the external load capacitance = 30 pF.



Master mode

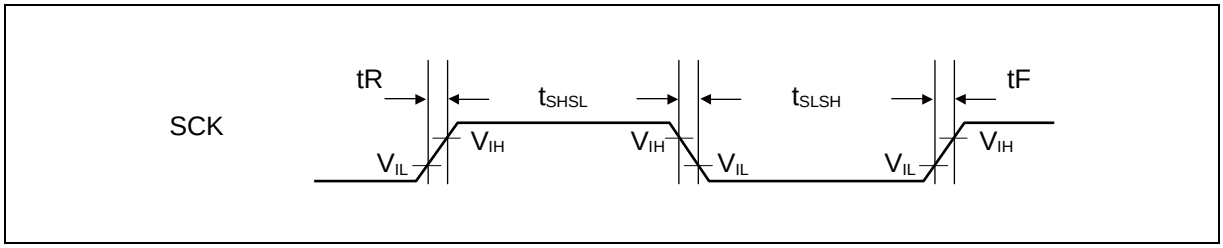


Slave mode

- UART external clock input (EXT = 1)

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value		Unit	Remarks
			Min	Max		
Serial clock "L" pulse width	t_{SLSH}	C_L = 30 pF	t_{CYCP} + 10	-	ns	
Serial clock "H" pulse width	t_{SHSL}		t_{CYCP} + 10	-	ns	
SCK fall time	tF		-	5	ns	
SCK rise time	tR		-	5	ns	

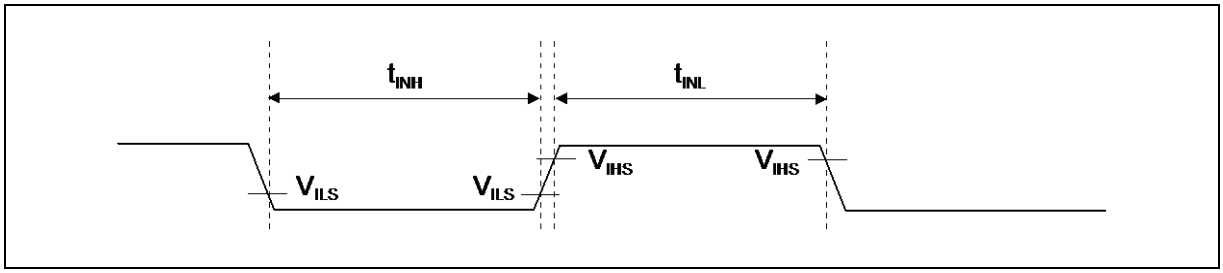


(10) External Input Timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{INH}, t_{INL}	ADTG	-	$2t_{CYCP}$*	-	ns	A/D converter trigger input
		FRCKx					Free-run timer input clock
		ICxx					Input capture
		DTTIxX	-	$2t_{CYCP}$*	-	ns	Wave form generator
		INTxx, NMIX	Except Timer mode, Stop mode	$2t_{CYCP}$ + 100*	-	ns	External interrupt NMI
			Timer mode, Stop mode	500	-	ns	

*: t_{CYCP} indicates the APB bus clock cycle time.
About the APB bus number which the A/D converter, Multi-function Timer, External interrupt are connected to, see "■Block Diagram" in this data sheet.

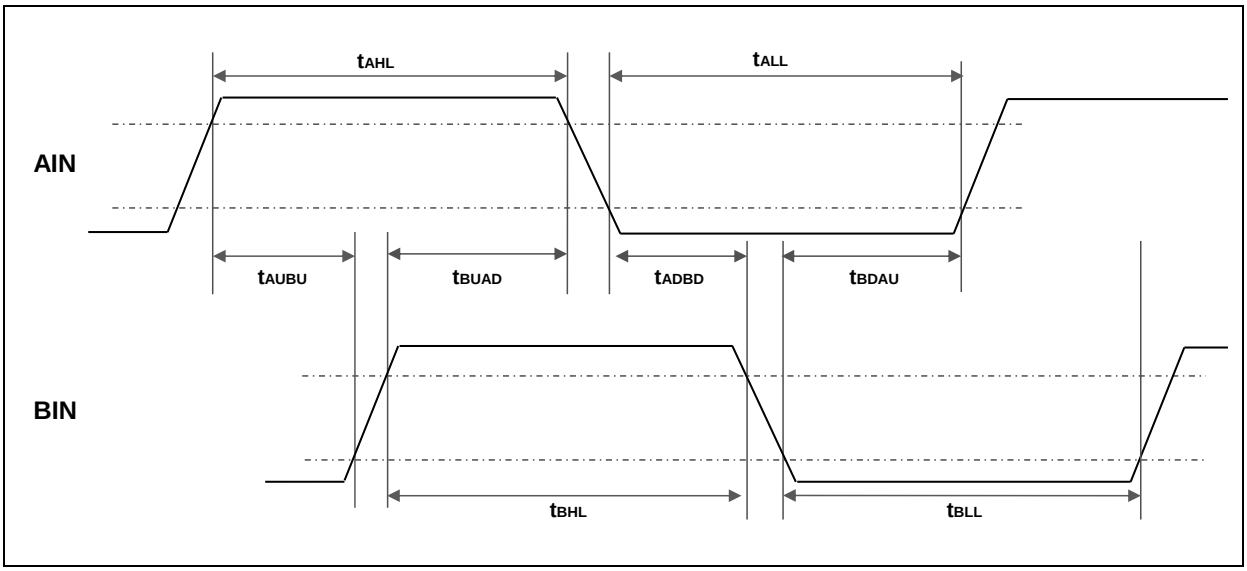


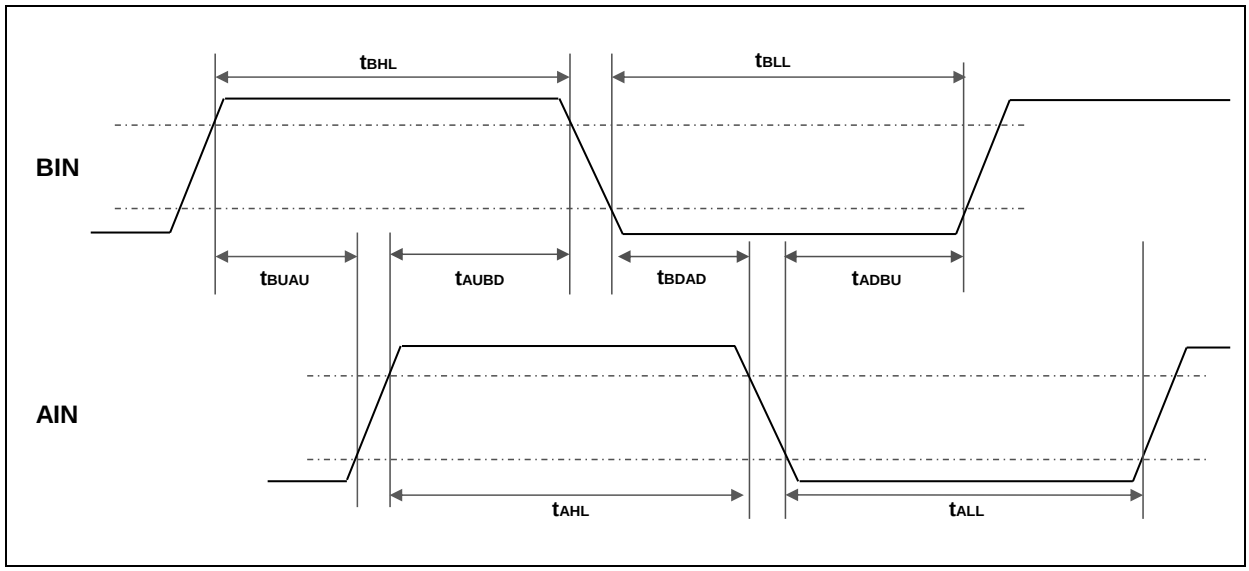
(11) Quadrature Position/Revolution Counter timing

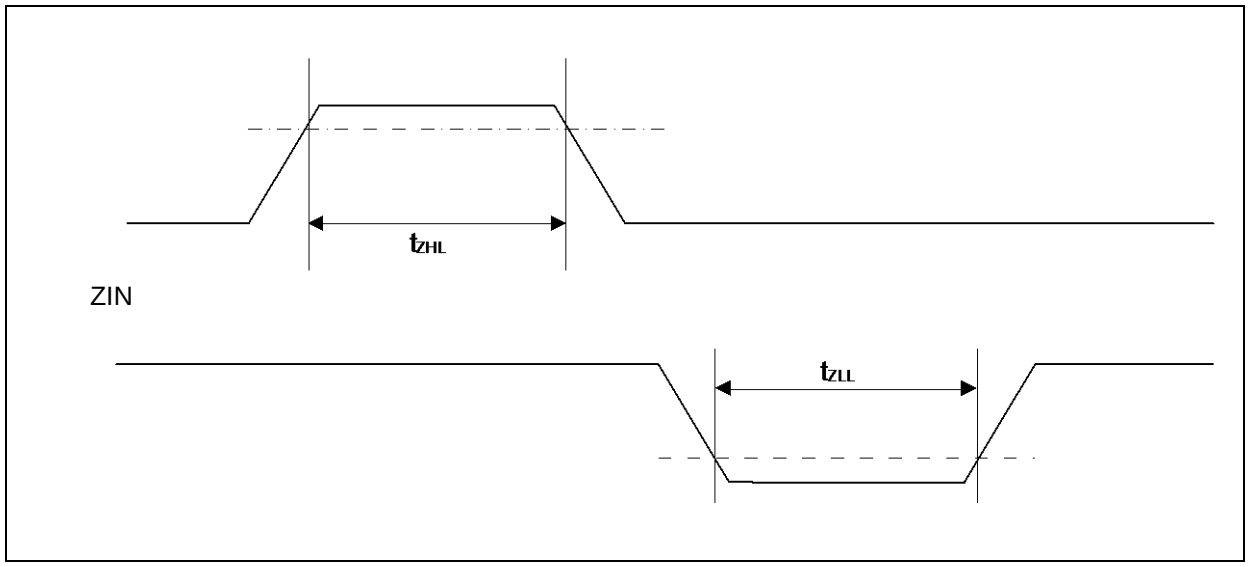
(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

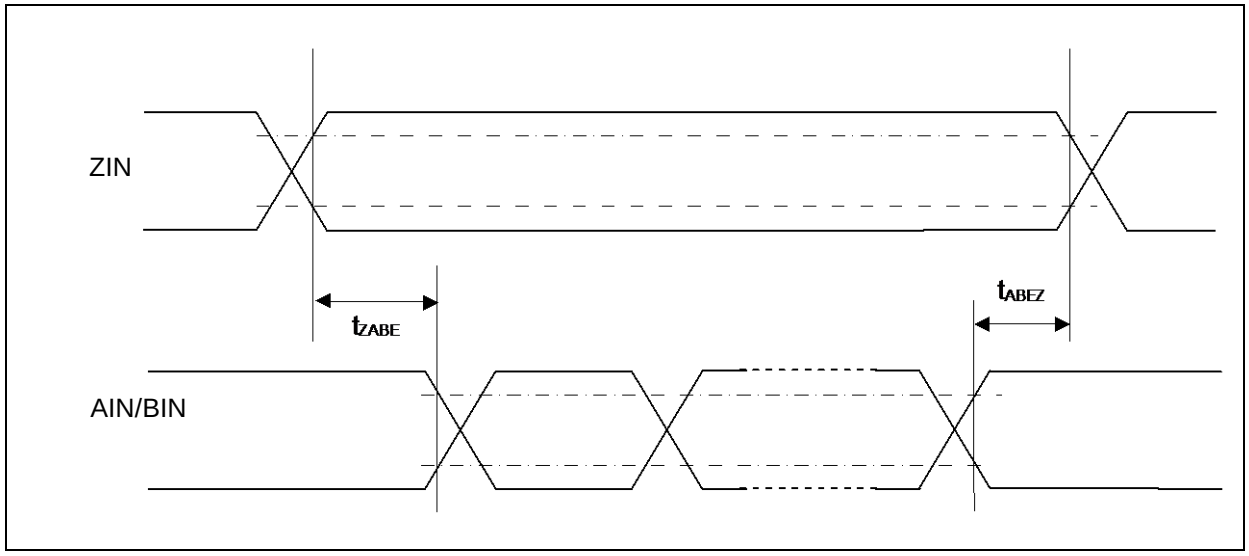
Parameter	Symbol	Conditions	Value		Unit
			Min	Max	
AIN pin "H" width	t_{AHL}	-	$2t_{CYCP}$*	-	ns
AIN pin "L" width	t_{ALL}	-			
BIN pin "H" width	t_{BHL}	-			
BIN pin "L" width	t_{BLL}	-			
BIN rise time from AIN pin "H" level	t_{AUBU}	PC_Mode2 or PC_Mode3			
AIN fall time from BIN pin "H" level	t_{BUAD}	PC_Mode2 or PC_Mode3			
BIN fall time from AIN pin "L" level	t_{ADBD}	PC_Mode2 or PC_Mode3			
AIN rise time from BIN pin "L" level	t_{BDAU}	PC_Mode2 or PC_Mode3			
AIN rise time from BIN pin "H" level	t_{BUAU}	PC_Mode2 or PC_Mode3			
BIN fall time from AIN pin "H" level	t_{AUBD}	PC_Mode2 or PC_Mode3			
AIN fall time from BIN pin "L" level	t_{BDAD}	PC_Mode2 or PC_Mode3			
BIN rise time from AIN pin "L" level	t_{ADBU}	PC_Mode2 or PC_Mode3			
ZIN pin "H" width	t_{ZHL}	QCR:CGSC="0"			
ZIN pin "L" width	t_{ZLL}	QCR:CGSC="0"			
AIN/BIN rise and fall time from determined ZIN level	t_{ZABE}	QCR:CGSC="1"			
Determined ZIN level from AIN/BIN rise and fall time	t_{ABEZ}	QCR:CGSC="1"			

*: t_{CYCP} indicates the APB bus clock cycle time.
About the APB bus number which Quadrature Position/Revolution Counter is connected to, see "■Block Diagram" in this data sheet.




tBHL
tBLL
BIN
tBUAU
tAUBD
tBDAD
tADBU
AIN
tAHL
tALL


tZHL
ZIN
tZLL


ZIN
tZABE
tABEZ
AIN/BIN

(12) I^2C Timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Standard-mode		Fast-mode		Unit	Remarks
			Min	Max	Min	Max		
SCL clock frequency	F_{SCL}	C_L = 30 pF, R = (Vp/I_{OL})*1	0	100	0	400	kHz	
(Repeated) START condition hold time SDA ↓ → SCL ↓	t_{HDSTA}		4.0	-	0.6	-	µs	
SCLclock "L" width	t_{LOW}		4.7	-	1.3	-	µs	
SCLclock "H" width	t_{HIGH}		4.0	-	0.6	-	µs	
(Repeated) START setup time SCL ↑ → SDA ↓	t_{SUSTA}		4.7	-	0.6	-	µs	
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*2	0	0.9*3	µs	
Data setup time SDA ↓ ↑ → SCL ↑	t_{SUDAT}		250	-	100	-	ns	
STOP condition setup time SCL ↑ → SDA ↑	t_{SUSTO}		4.0	-	0.6	-	µs	
Bus free time between "STOP condition" and "START condition"	t_{BUF}		4.7	-	1.3	-	µs	
Noise filter	t_{SP}	8 MHz ≤ t_{CYCP} ≤ 40 MHz	2 t_{CYCP}*4	-	2 t_{CYCP}*4	-	ns	*5
		40 MHz < t_{CYCP} ≤ 60 MHz	3 t_{CYCP}*4	-	3 t_{CYCP}*4	-	ns	*5
		60 MHz < t_{CYCP} ≤ 72 MHz	4 t_{CYCP}*4	-	4 t_{CYCP}*4	-	ns	*5

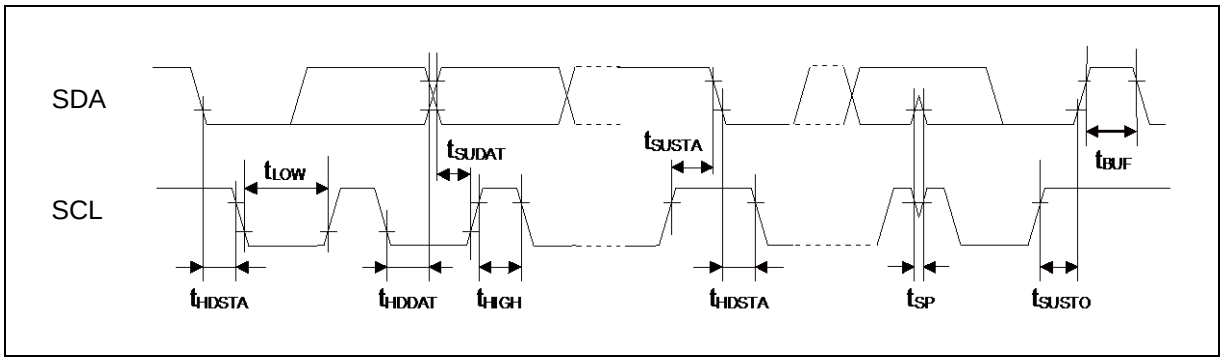
*1: R and C represent the pull-up resistance and load capacitance of the SCL and SDA lines, respectively. Vp indicates the power supply voltage of the pull-up resistance and I_{OL} indicates V_{OL} guaranteed current.

*2: The maximum t_{HDDAT} must satisfy that it does not extend at least "L" period (t_{LOW}) of device's SCL signal.

*3: A Fast-mode I^2C bus device can be used on a Standard-mode I^2C bus system as long as the device satisfies the requirement of "t_{SUDAT} ≥ 250 ns".

*4: t_{CYCP} is the APB bus clock cycle time.
About the APB bus number which I^2C is connected to, see "■Block Diagram" in this data sheet.
To use Standard-mode, set the APB bus clock at 2 MHz or more.
To use Fast-mode, set the APB bus clock at 8 MHz or more.

*5: The number of steps of the noise filter can be changed with register settings.
Change the number of the noise filter steps according to APB2 bus clock frequency.

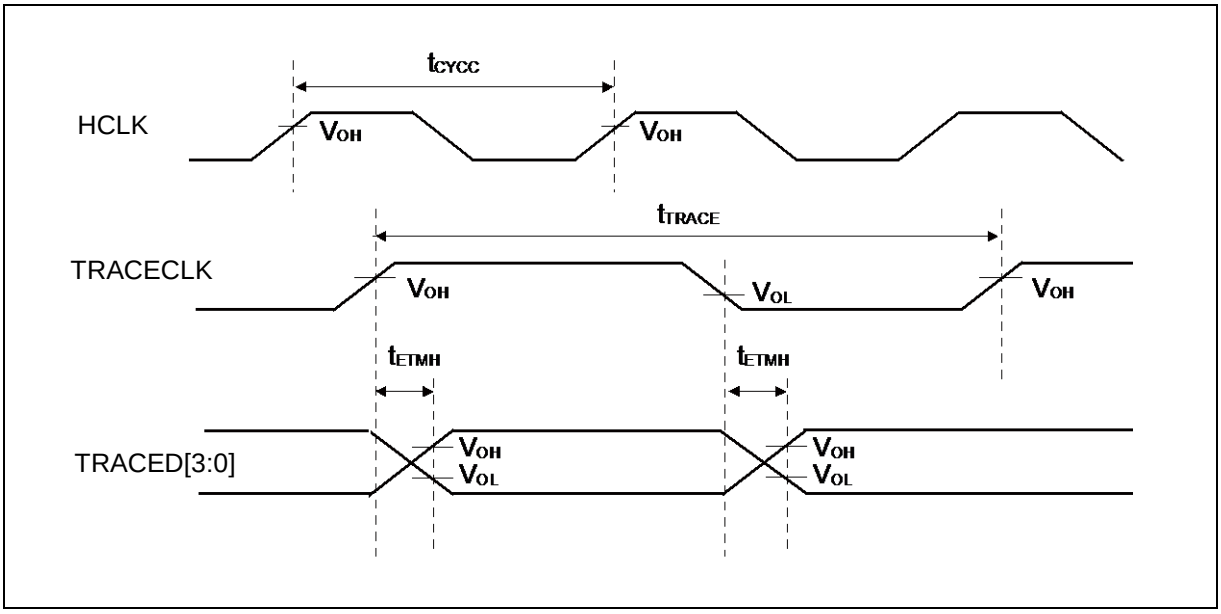


(13) ETM Timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Data hold	t_{ETMH}	TRACECLK, TRACED[3:0]	Vcc ≥ 4.5 V	2	9	ns	
			Vcc < 4.5 V	2	15		
TRACECLK frequency	1/ t_{TRACE}	TRACECLK	Vcc ≥ 4.5 V	-	50	MHz	
			Vcc < 4.5 V	-	32	MHz	
TRACECLK cycle time	t_{TRACE}		Vcc ≥ 4.5 V	20	-	ns	
			Vcc < 4.5 V	31.25	-	ns	

Note: When the external load capacitance = 30 pF.

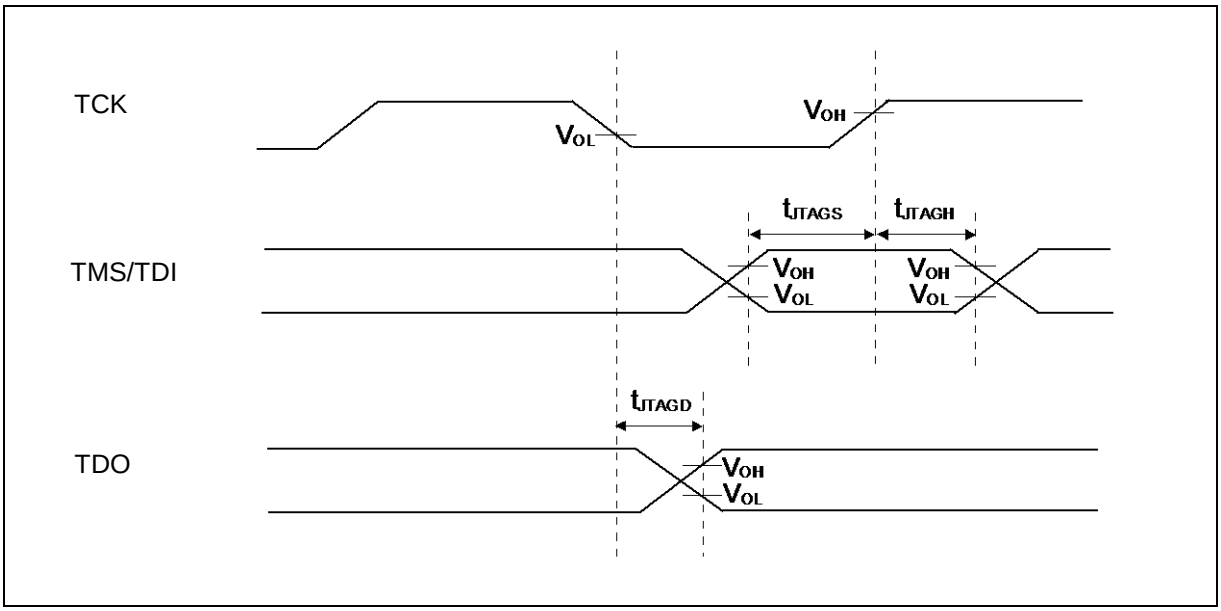


(14) JTAG Timing

(Vcc = 2.7V to 5.5V, Vss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
TMS, TDI setup time	t_{JTAGS}	TCK, TMS, TDI	Vcc ≥ 4.5 V	15	-	ns	
			Vcc < 4.5 V				
TMS, TDI hold time	t_{JTAGH}	TCK, TMS, TDI	Vcc ≥ 4.5 V	15	-	ns	
			Vcc < 4.5 V				
TDO delay time	t_{JTAGD}	TCK, TDO	Vcc ≥ 4.5 V	-	25	ns	
			Vcc < 4.5 V	-	45		

Note: When the external load capacitance = 30 pF.



5. 12-bit A/D Converter

- Electrical characteristics for the A/D converter

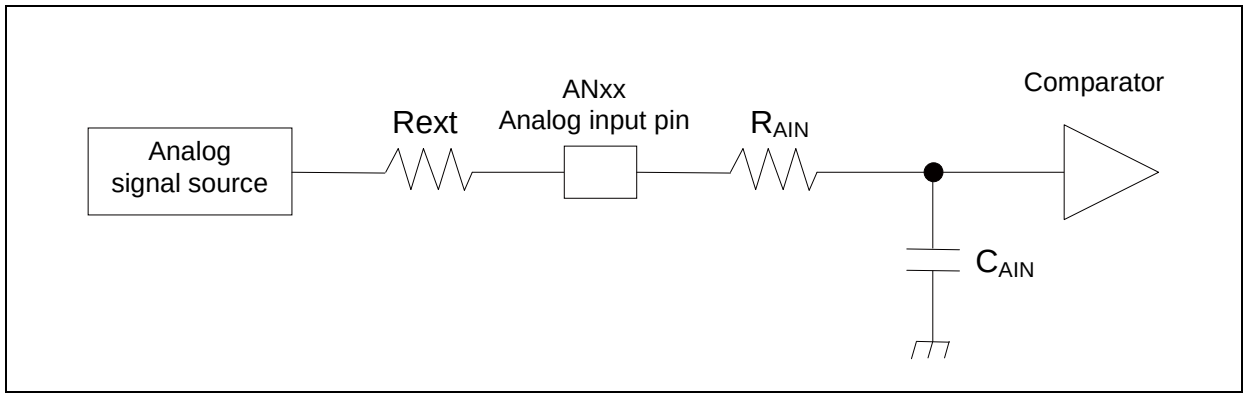
(Vcc = AVcc = 2.7V to 5.5V, Vss = AVss = 0V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	-	-	-	-	12	bit	
Integral Nonlinearity	-	-	-		± 4.5	LSB	AVRH = 2.7 V to 5.5 V
Differential Nonlinearity	-	-	-		± 2.5	LSB	
Zero transition voltage	V_{ZT}	ANxx	-		± 15	mV	
Full-scale transition voltage	V_{FST}	ANxx	-		AVRH ± 15	mV	
Conversion time	-	-	1.0*1	-	-	µs	AVcc ≥ 4.5 V
			1.2*1	-	-		AVcc < 4.5 V
Sampling time	Ts	-	*2	-	-	ns	AVcc ≥ 4.5 V
			*2	-	-		AVcc < 4.5 V
Compare clock cycle*3	Tcck	-	50	-	2000	ns	
State transition time to operation permission	Tstt	-	-	-	1.0	µs	
Analog input capacity	C_{AIN}	-	-	-	12.9	pF	
Analog input resistance	R_{AIN}	-	-	-	2	kΩ	AVcc ≥ 4.5 V
					3.8		AVcc < 4.5 V
Interchannel disparity	-	-	-	-	4	LSB	
Analog port input current	-	ANxx	-	-	5	µA	
Analog input voltage	-	ANxx	AV_{SS}	-	AVRH	V	
Reference voltage	-	AVRH	2.7	-	AV_{CC}	V	

*1: The Conversion time is the value of sampling time (Ts) + compare time (Tc).
The condition of the minimum conversion time is the following.
AVcc ≥ 4.5 V, HCLK=120 MHz sampling time: 300 ns compare time: 700 ns
AVcc < 4.5 V, HCLK=120 MHz sampling time: 500 ns compare time: 700 ns
Ensure that it satisfies the value of the sampling time (Ts) and compare clock cycle (Tcck).
For setting of the sampling time and compare clock cycle, see "CHAPTER 1-1: A/D Converter" in "FM3 Family PERIPHERAL MANUAL Analog Macro Part".
The registers setting of the A/D Converter are reflected in the operation according to the APB bus clock timing.
The sampling clock and compare clock is generated from the Base clock (HCLK).
About the APB bus number which the A/D Converter is connected to, see "■Block Diagram" in this data sheet.

*2: A necessary sampling time changes by external impedance.
Ensure that it set the sampling time to satisfy (Equation 1).

*3: Compare time (Tc) is the value of (Equation 2).



(Equation 1) $Ts \geq (R_{AIN} + Rext) \times C_{AIN} \times 9$

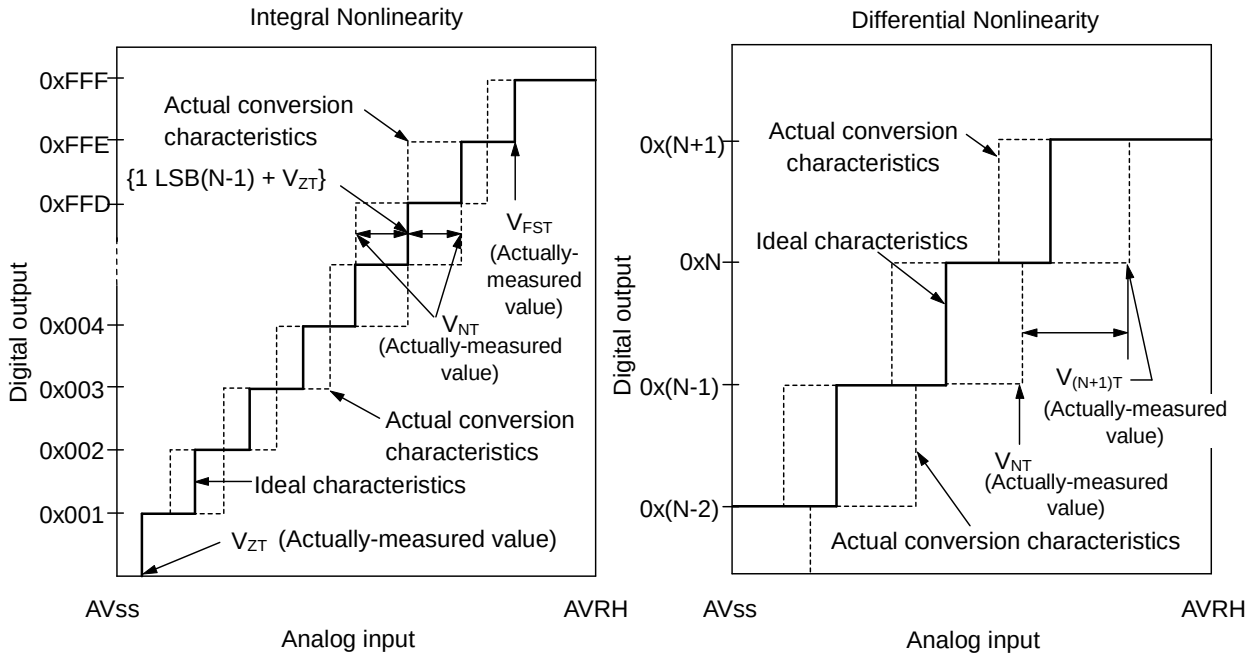
Ts:	Sampling time
R_{AIN}:	input resistance of A/D = 2 kΩ at $4.5 \leq AV_{CC} \leq 5.5$
	input resistance of A/D = 3.8 kΩ at $2.7 \leq AV_{CC} < 4.5$
C_{AIN}:	input capacity of A/D = 12.9 pF at $2.7 \leq AV_{CC} \leq 5.5$
Rext:	Output impedance of external circuit

(Equation 2) $Tc = Tcck \times 14$

Tc:	Compare time
Tcck:	Compare clock cycle

- Definition of 12-bit A/D Converter Terms

  - Resolution : Analog variation that is recognized by an A/D converter.
  - Integral Nonlinearity : Deviation of the line between the zero-transition point (0b000000000000←→0b000000000001) and the full-scale transition point (0b111111111110←→0b111111111111) from the actual conversion characteristics.
  - Differential Nonlinearity : Deviation from the ideal value of the input voltage that is required to change the output code by 1 LSB.



$$\text{Integral Nonlinearity of digital output N} = \frac{V_{NT} - \{1LSB \times (N - 1) + V_{ZT}\}}{1LSB} \text{ [LSB]}$$

$$\text{Differential Nonlinearity of digital output N} = \frac{V_{(N+1)T} - V_{NT}}{1LSB} - 1 \text{ [LSB]}$$

$$1LSB = \frac{V_{FST} - V_{ZT}}{4094}$$

N: A/D converter digital output value.
V_{ZT}: Voltage at which the digital output changes from 0x000 to 0x001.
V_{FST}: Voltage at which the digital output changes from 0xFFE to 0xFFF.
V_{NT}: Voltage at which the digital output changes from 0x(N − 1) to 0xN.

6. Low-Voltage Detection Characteristics

(1) Low-Voltage Detection Reset

(Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Detected voltage	VDL	-	2.25	2.45	2.65	V	When voltage drops
Released voltage	VDH	-	2.30	2.50	2.70	V	When voltage rises

(2) Interrupt of Low-Voltage Detection

(Ta = - 40°C to + 85°C)

Parameter	Symbol	Conditions	Value			Unit	Remarks
			Min	Typ	Max		
Detected voltage	VDL	SVHI = 0000	2.58	2.8	3.02	V	When voltage drops
Released voltage	VDH		2.67	2.9	3.13	V	When voltage rises
Detected voltage	VDL	SVHI = 0001	2.76	3.0	3.24	V	When voltage drops
Released voltage	VDH		2.85	3.1	3.34	V	When voltage rises
Detected voltage	VDL	SVHI = 0010	2.94	3.2	3.45	V	When voltage drops
Released voltage	VDH		3.04	3.3	3.56	V	When voltage rises
Detected voltage	VDL	SVHI = 0011	3.31	3.6	3.88	V	When voltage drops
Released voltage	VDH		3.40	3.7	3.99	V	When voltage rises
Detected voltage	VDL	SVHI = 0100	3.40	3.7	3.99	V	When voltage drops
Released voltage	VDH		3.50	3.8	4.10	V	When voltage rises
Detected voltage	VDL	SVHI = 0111	3.68	4.0	4.32	V	When voltage drops
Released voltage	VDH		3.77	4.1	4.42	V	When voltage rises
Detected voltage	VDL	SVHI = 1000	3.77	4.1	4.42	V	When voltage drops
Released voltage	VDH		3.86	4.2	4.53	V	When voltage rises
Detected voltage	VDL	SVHI = 1001	3.86	4.2	4.53	V	When voltage drops
Released voltage	VDH		3.96	4.3	4.64	V	When voltage rises
LVD stabilization wait time	T_{LVDW}	-	-	-	4032 × t_{CYCP}*	µs	

*: t_{CYCP} indicates the APB2 bus clock cycle time.

7. Flash Memory Write/Erase Characteristics

(1) Write / Erase time

(Vcc = 2.7V to 5.5V, Ta = - 40°C to + 85°C)

Parameter		Value		Unit	Remarks
		Typ*	Max*		
Sector erase time	Large Sector	0.7	3.7	s	Includes write time prior to internal erase
	Small Sector	0.3	1.1		
Half word (16-bit) write time		12	384	µs	Not including system-level overhead time.
Chip erase time		13.6	68	s	Includes write time prior to internal erase

*: The typical value is immediately after shipment, the maximam value is guarantee value under 100,000 cycle of erase/write.

(2) Write cycles and data hold time

Erase/write cycles (cycle)	Data hold time (year)	Remarks
1,000	20*	
10,000	10*	
100,000	5*	

*: At average + 85°C

8. Return Time from Low-Power Consumption Mode

(1) Return Factor: Interrupt

The return time from Low-Power consumption mode is indicated as follows. It is from receiving the return factor to starting the program operation.

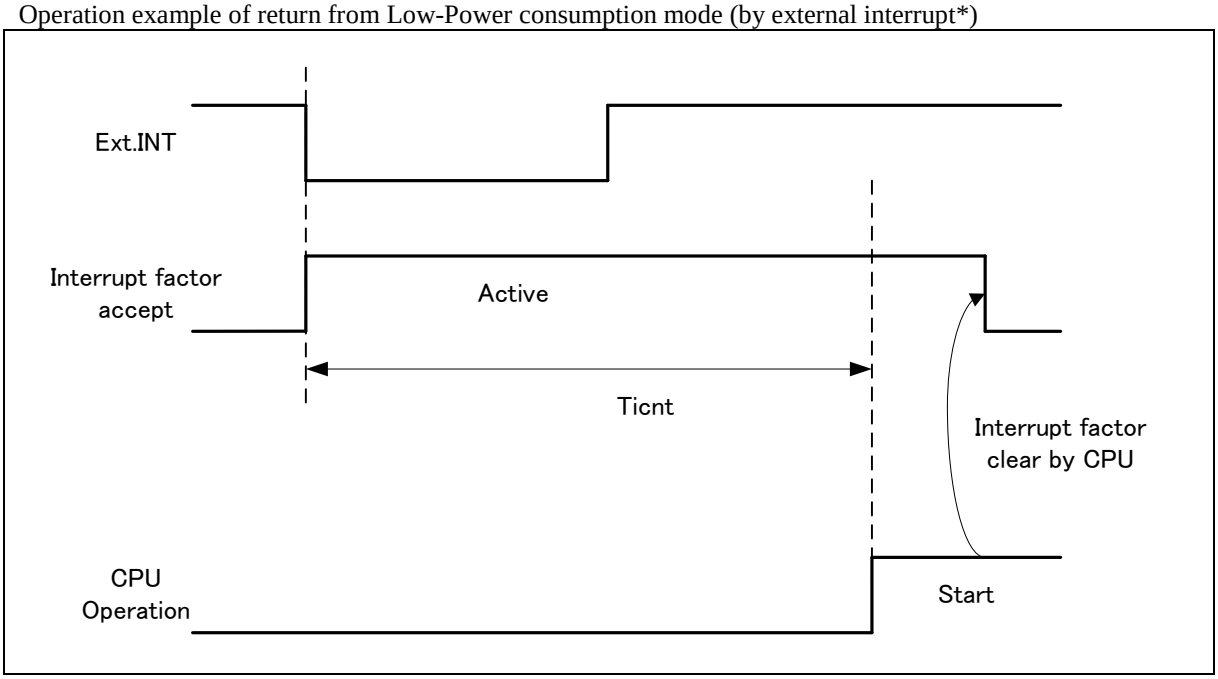
- Return Count Time

(V_{CC} = 2.7V to 5.5V, Ta = - 40°C to + 85°C)

Parameter	Symbol	Value		Unit	Remarks
		Typ	Max*		
SLEEP mode	Ticnt	t_{CYCC}		ns	
High-speed CR TIMER mode, Main TIMER mode, PLL TIMER mode		40	80	µs	
Low-speed CR TIMER mode		453	737	µs	
Sub TIMER mode		453	737	µs	
STOP mode		453	737	µs	

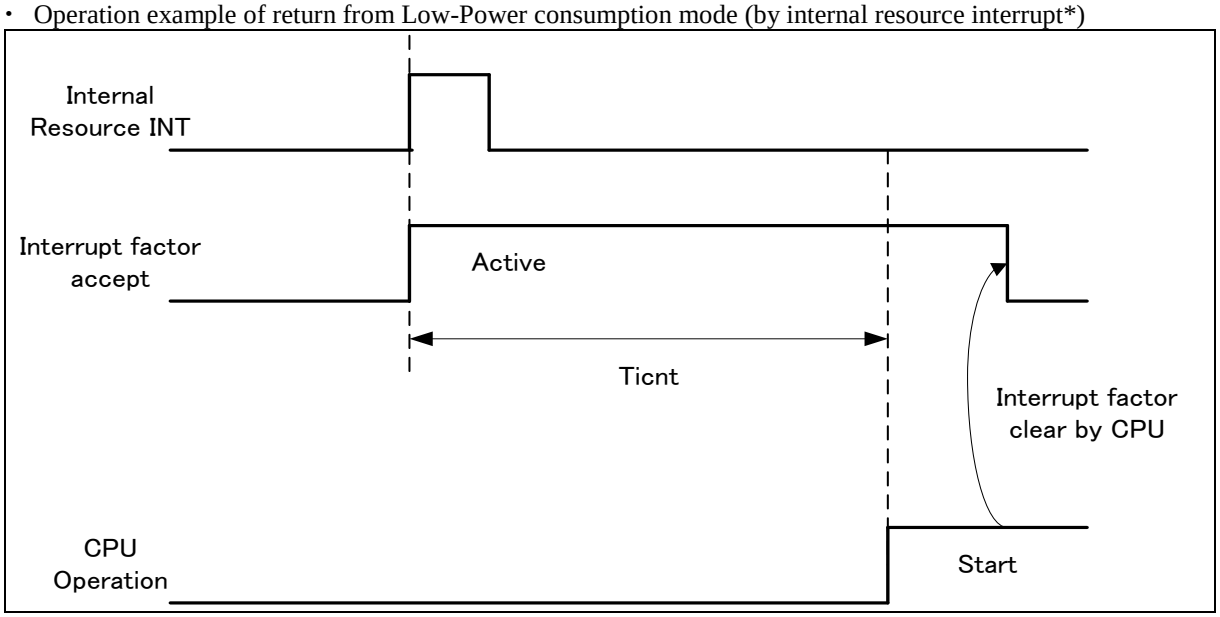
*: The maximum value depends on the accuracy of built-in CR.

- Operation example of return from Low-Power consumption mode (by external interrupt*)



*: External interrupt is set to detecting fall edge.

- Operation example of return from Low-Power consumption mode (by internal resource interrupt*)



*: Internal resource interrupt is not included in return factor by the kind of Low-Power consumption mode.

Notes:
- The return factor is different in each Low-Power consumption modes.
  See "CHAPTER 6: Low Power Consumption Mode" and "Operations of Standby Modes" in FM3 Family PERIPHERAL MANUAL about the return factor from Low-Power consumption mode.
- When interrupt recoveries, the operation mode that CPU recoveries depends on the state before the Low-Power consumption mode transition. See "CHAPTER 6: Low Power Consumption Mode" in "FM3 Family PERIPHERAL MANUAL".

(2) Return Factor: Reset

The return time from Low-Power consumption mode is indicated as follows. It is from releasing reset to starting the program operation.

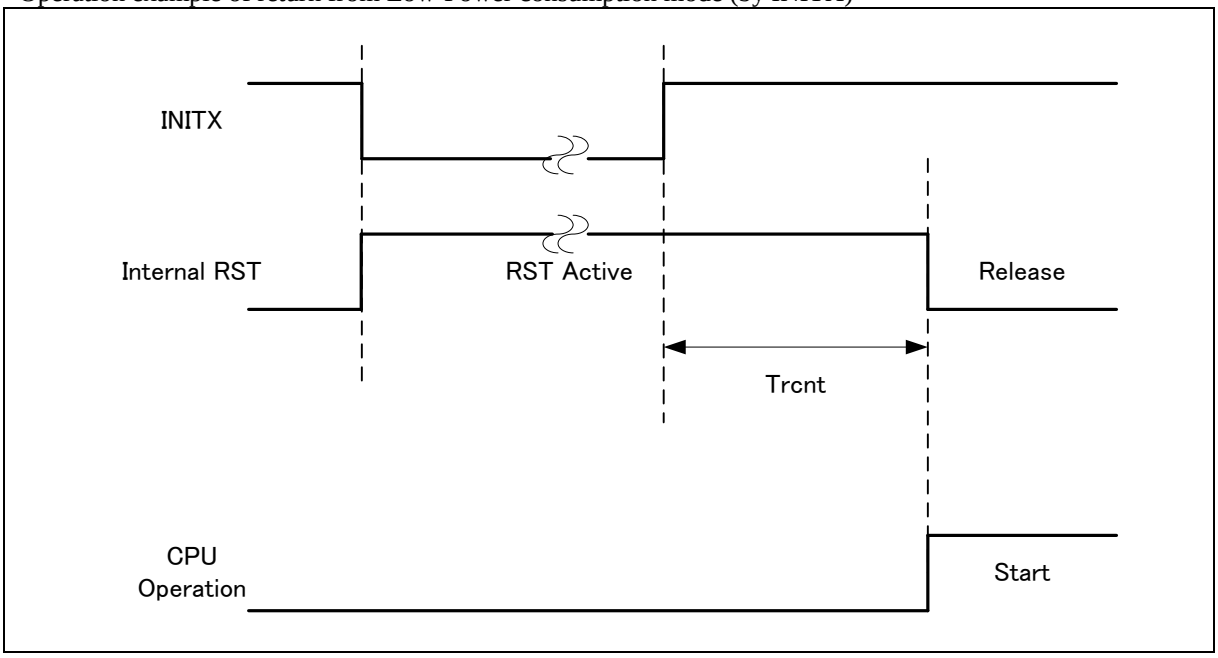
- Return Count Time

(V_{CC} = 2.7V to 5.5V, Ta = - 40°C to + 85°C)

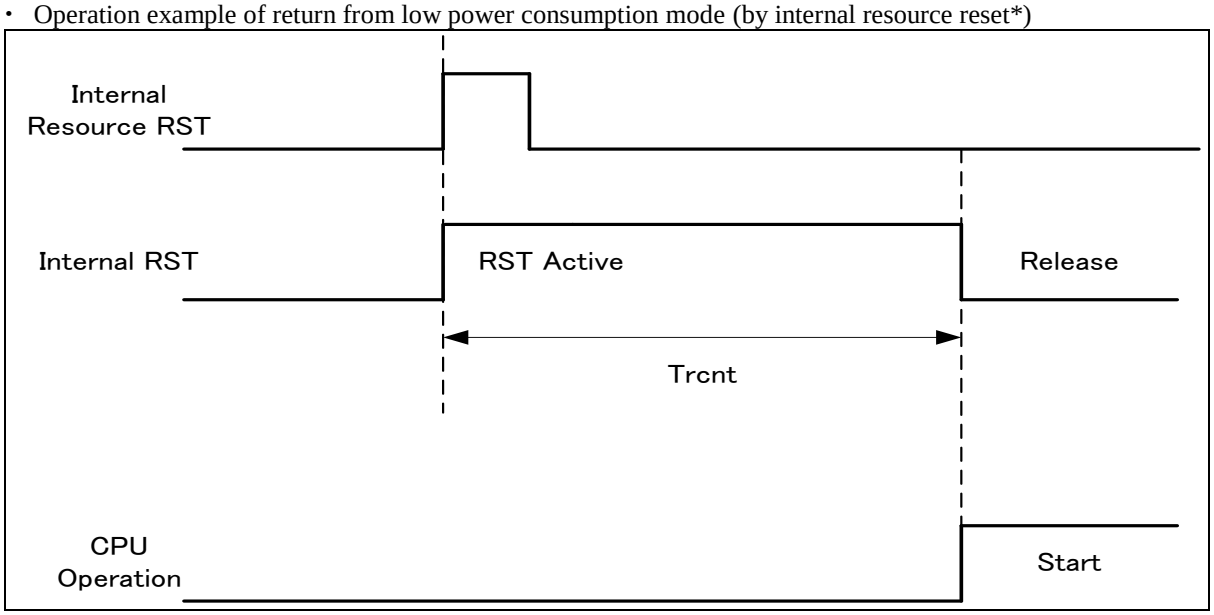
Parameter	Symbol	Value		Unit	Remarks
		Typ	Max*		
SLEEP mode	Trcnt	321	461	µs	
High-speed CR TIMER mode, Main TIMER mode, PLL TIMER mode		321	461	µs	
Low-speed CR TIMER mode		441	701	µs	
Sub TIMER mode		441	701	µs	
STOP mode		441	701	µs	

*: The maximum value depends on the accuracy of built-in CR.

- Operation example of return from Low-Power consumption mode (by INITX)



・ Operation example of return from low power consumption mode (by internal resource reset*)



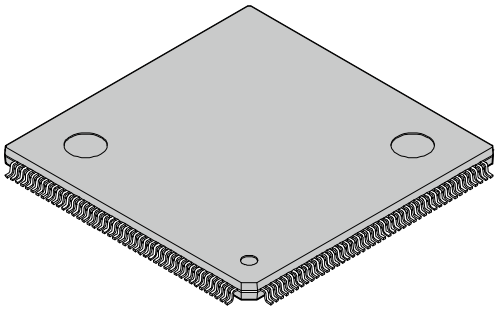
* : Internal resource reset is not included in return factor by the kind of Low-Power consumption mode.

Notes:
- The return factor is different in each Low-Power consumption modes. See "CHAPTER 6: Low Power Consumption Mode" and "Operations of Standby Modes" in FM3 Family PERIPHERAL MANUAL.
- When interrupt recoveries, the operation mode that CPU recoveries depends on the state before the Low-Power consumption mode transition. See "CHAPTER 6: Low Power Consumption Mode" in "FM3 Family PERIPHERAL MANUAL".
- The time during the power-on reset/low-voltage detection reset is excluded. See "(6) Power-on Reset Timing in 4. AC Characteristics in ■Electrical Characteristics" for the detail on the time during the power-on reset/low -voltage detection reset.
- When in recovery from reset, CPU changes to the high-speed CR run mode. When using the main clock or the PLL clock, it is necessary to add the main clock oscillation stabilization wait time or the main PLL clock stabilization wait time.
- The internal resource reset means the watchdog reset and the CSV reset.

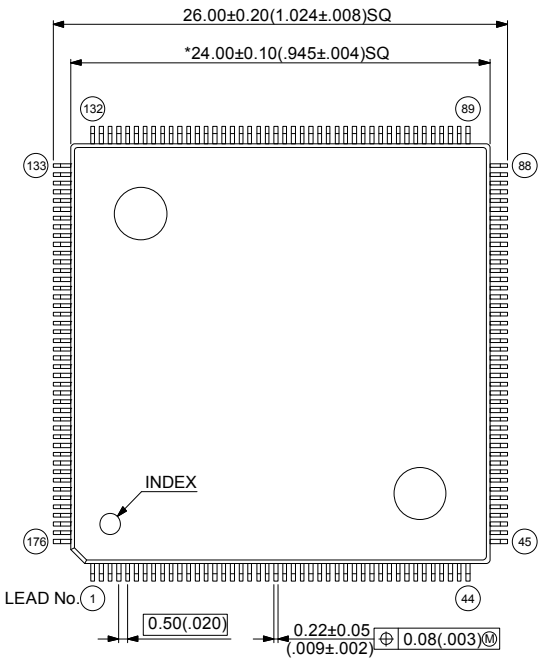
■ Ordering Information

Part number	On-chip Flash memory	On-chip SRAM	Package	Packing
MB9BF116SPMC-GE1	512 Kbyte	64 Kbyte	Plastic • LQFP 144-pin (0.5 mm pitch), (FPT-144P-M08)	Tray
MB9BF117SPMC-GE1	768 Kbyte	96 Kbyte		
MB9BF118SPMC-GE1	1 Mbyte	128 Kbyte		
MB9BF116TPMC-GE1	512 Kbyte	64 Kbyte	Plastic • LQFP 176-pin (0.5 mm pitch), (FPT-176P-M07)	
MB9BF117TPMC-GE1	768 Kbyte	96 Kbyte		
MB9BF118TPMC-GE1	1 Mbyte	128 Kbyte		
MB9BF116TBGL-GE1	512 Kbyte	64 Kbyte	Plastic • PFBGA 192-pin (0.8 mm pitch), (BGA-192P-M06)	
MB9BF117TBGL-GE1	768 Kbyte	96 Kbyte		
MB9BF118TBGL-GE1	1 Mbyte	128 Kbyte		

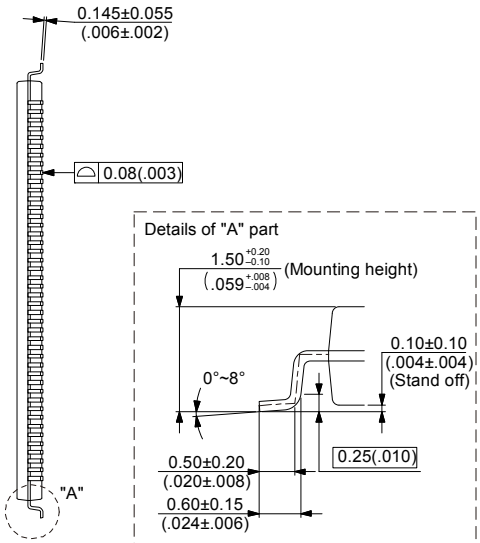
■ PACKAGE DIMENSIONS

176-pin plastic LQFP		
 (FPT-176P-M07)	Lead pitch	0.50 mm
	Package width × package length	24.0 × 24.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Code (Reference)	P-LQFP-0176-2424-0.50

176-pin plastic LQFP
(FPT-176P-M07)



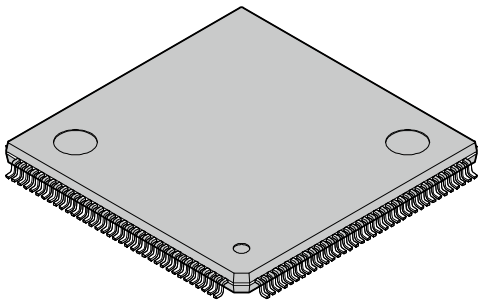
Note 1) * : Values do not include resin protrusion.
Resin protrusion is +0.25(.010)Max(each side).
Note 2) Pins width and pins thickness include plating thickness
Note 3) Pins width do not include tie bar cutting remainder.



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Dimensions in mm (inches).
Note: The values in parentheses are reference values.

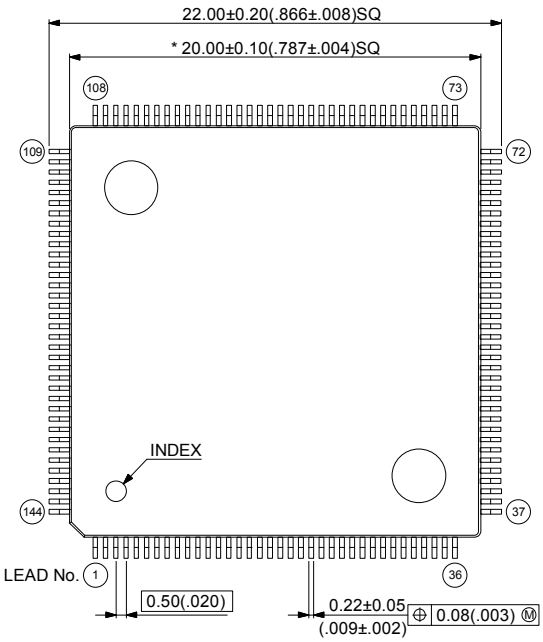
144-pin plastic LQFP

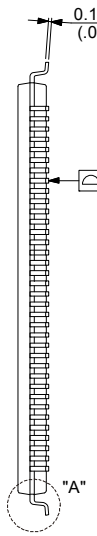


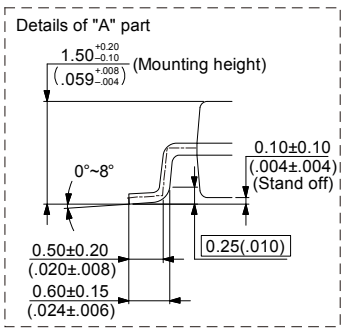
(FPT-144P-M08)

Lead pitch	0.50 mm
Package width × package length	20.0 × 20.0 mm
Lead shape	Gullwing
Sealing method	Plastic mold
Mounting height	1.70 mm MAX
Weight	1.20 g
Code (Reference)	P-LFQFP144-20×20-0.50

144-pin plastic LQFP
(FPT-144P-M08)



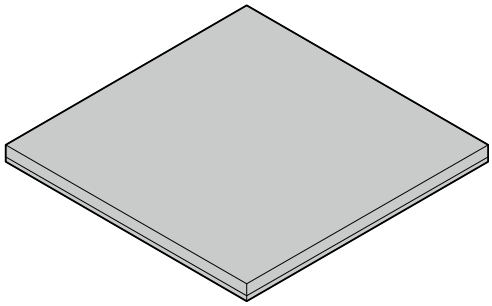




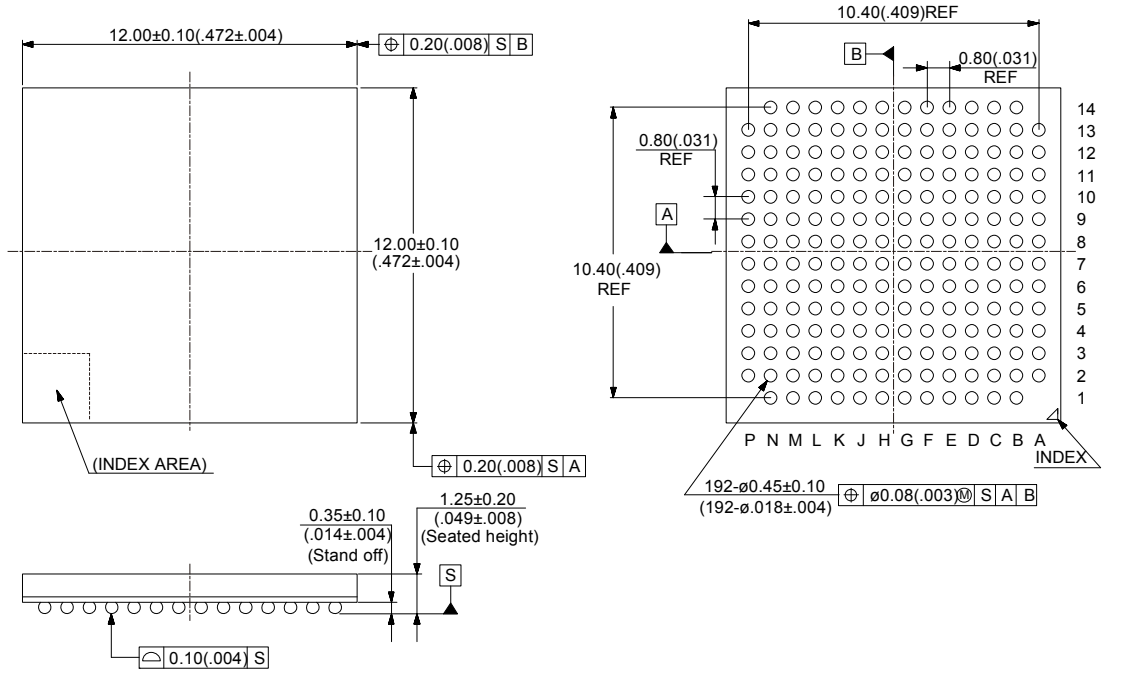
Note 1) *:Values do not include resin protrusion.
Resin protrusion is +0.25(.010)Max(each side).
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.

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Dimensions in mm (inches).
Note: The values in parentheses are reference values.

192-ball plastic FBGA		
	Ball pitch	0.80 mm
	Package width × package length	12.00 mm × 12.00 mm
	Lead shape	Ball
	Sealing method	Plastic mold
	Mounting height	1.45 mm Max.
	Weight	0.34 g
(BGA-192P-M06)		

192-ball plastic FBGA
(BGA-192P-M06)



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Dimensions in mm (inches).
Note: The values in parentheses are reference values.

■ Major Changes

Page	Section	Change Results
Revision 1.0		
-	-	Initial release
Revision 2.0		
8 to 10	■ PIN ASSIGNMENT	Added the description of "Note".
61, 62	■ HANDLING DEVICES	• Revised the description of "•C pin". • Added the description of "•Base Timer".
63	■ BLOCK DIAGRAM	Corrected the figure. - TIOA: input → input/output - TIOB: output → input
74	■ ELECTRICAL CHARACTERISTICS 2. Recommended Operating Conditions	• Added the "Smoothing capacitor (C_S)". • Added the footnote.
79	4. AC Characteristics (1) Main Clock Input Characteristics	Added "Internal operating clock frequency (F_{CM}): Master Clock".
81	(4-1) Operating Conditions of Main PLL (In the case of using main clock for input of PLL) (4-2) Operating Conditions of Main PLL (In the case of using built-in high-speed CR clock for the input clock of the main PLL)	Added "Main PLL clock frequency (F_{CLKPLL})".
109	5. 12-bit A/D Converter ● Electrical Characteristics for the A/D Converter	• Added the Symbol. • Deleted the following Pin name. - "Sampling time" - "Compare clock cycle" - "State transition time to operation permission" - "Analog input capacity" - "Analog input resistance" • Corrected the value of "Compare clock cycle (Tcck)". Max: 10000 → 2000
Revision 2.1		
-	-	Company name and layout design change
Revision 3.0		
2	■Features ●External Bus Interface	Added the description of Maximum area size
8, 9	■Pin Assignment	Added SWCLK and SWDIO and SWO
50 to 55	■I/O Circuit Type	· Added the description of I^2C to the type of E, F, I, L · Added about +B input
60	■Handling Devices	Added "●Stabilizing power supply voltage"
60	■Handling Devices ●Crystal oscillator circuit	Added the following description "Evaluate oscillation of your using crystal oscillator by your mount board."
61	■Handling Devices ●C Pin	Changed the description
63	■Block Diagram	Modified the block diagram
65	■Memory Map · Memory map(1)	Modified the area of "Extarnal Device Area"
66	■Memory Map · Memory map(2)	Added the summary of Flash memory sector and the note
73, 74	■Electrical Characteristics 1. Absolute Maximum Ratings	· Added the Clamp maximum current · Added the output current of P80, P81, P82, P83 · Added about +B input
75	■Electrical Characteristics 2. Recommended Operation Conditions	· Modified the minimum value of Analog reference voltage · Added Smoothing capacitor · Added the note about less than the minimum power supply voltage
76, 77	■Electrical Characteristics 3. DC Characteristics (1) Current rating	· Changed the table format · Added Main TIMER mode current · Added Flash Memory Current · Moved A/D Converter Current
81	■Electrical Characteristics 4. AC Characteristics (3) Built to in CR Oscillation Characteristics	Added Frequency stability time at Built to in high to speed CR
83	■Electrical Characteristics 4. AC Characteristics (6) Power to on Reset Timing	· Added Time until releasing Power to on reset · Changed the figure of timing
85 to 87	■Electrical Characteristics 4. AC Characteristics (7) External Bus Timing	Modified Data output time

Page	Section	Change Results
94 to 101	■Electrical Characteristics 4. AC Characteristics (9) CSIO/UART Timing	· Modified from UART Timing to CSIO/UART Timing · Changed from Internal shift clock operation to Master mode · Changed from External shift clock operation to Slave mode
108	■Electrical Characteristics 5. 12bit A/D Converter	· Added the typical value of Integral Nonlinearity, Differential Nonlinearity, Zero transition voltage and Full to scale transition voltage · Added Conversion time at AVcc < 4.5 V · Modified Stage transition time to operation permission · Modified the minimum value of Reference voltage
113 to 116	■Electrical Characteristics 8. Return Time from Low to Power Consumption Mode	Added Return Time from Low to Power Consumption Mode
117	■Ordering Information	Change to full part number

Colophon

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