Phase-sequence Phase-loss Relay

K8AB-PH

CSM_K8AB-PH_DS_E_2_1

Three-phase Phase-sequence Phase-loss Relay Using Voltage Detection Method

- Prevents reverse motor rotation due to incorrect wiring.
- Distinguishes between positive phases, reversed phases, and phase loss when power is turned ON.
- Voltage detection method enables application for any load current.
- One SPDT output relay, 6 A at 250 VAC (resistive load).
- Output status can be monitored using LED indicator.

⚠ Refer to *Safety Precautions for the K8AB Series*. Refer to page 5 for the Q&A section.

Model Number Structure

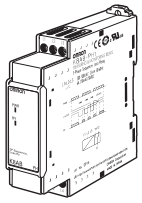
■ Model Number Legend

K8AB-□□
1 2 3

1. **Basic Model**
   K8AB: Measuring and Monitoring Relays
2. **Functions**
   PH: Phase-sequence Phase-loss Relay
3. **Rated Input Voltage**
   1: 200 to 500 VAC

Ordering Information

■ List of Models

Phase-sequence Phase-loss Relay	Functions	Rated input voltage (See note.)	Model
	Phase sequence and phase loss monitoring	200 to 500 VAC	**K8AB-PH1**

Note: The power supply is shared with the rated input voltage.

Ratings and Specifications

■ Ratings

Rated input voltage	Three-phase, three-wire mode, 200 to 500 VAC
Input load	15 VA max.
Reversed phase and phase loss operating time	0.1 s max.
Reset method	Automatic reset
Indicators	Power (PWR): Green, Relay output (RY): Yellow
Output relays	One SPDT relay (NC operation)
Output relay ratings	Rated load Resistive load 6 A at 250 VAC (cosϕ = 1) 6 A at 30 VDC (L/R = 0 ms) Inductive load 1 A at 250 VAC (cosϕ = 0.4) 1 A at 30 VDC (L/R = 7 ms) Maximum contact voltage: 250 VAC Maximum contact current: 6 A AC Maximum switching capacity: 1,500 VA Minimum load: 10 mA at 5 VDC Mechanical life: 10,000,000 operations Electrical life: Make: 50,000 times, Break: 30,000 times
Ambient operating temperature	−20 to 60°C (with no condensation or icing)
Storage temperature	−40 to 70°C (with no condensation or icing)
Ambient operating humidity	25% to 85% (with no condensation)
Storage humidity	25% to 85% (with no condensation)
Altitude	2,000 m max.
Terminal screw tightening torque	0.49 N·m
Terminal wiring method	Recommended wire Solid wire: 2.5 mm^2 Twisted wires: AWG16, AWG18 **Note: 1.** Ferrules with insulating sleeves must be used with twisted wires. **2.** Two wires can be twisted together. Recommended ferrules AI 1,5-8BK (for AWG16) manufactured by Phoenix Contact AI 1-8RD (for AWG18) manufactured by Phoenix Contact AI 0,75-8GY (for AWG18) manufactured by Phoenix Contact
Case color	Munsell 5Y8/1
Case material	ABS resin (self-extinguishing resin) UL94-V0
Weight	Approx. 110 g
Mounting	Mounted to DIN Track or via M4 screws (tightening torque: 1.2 N·m)
Dimensions	22.5 (W) × 90 (H) × 100 (D) mm

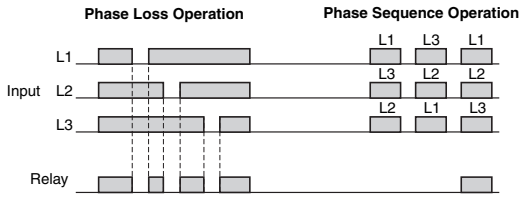
■ Specifications

Input voltage range		200 to 500 VAC
Input frequency range		45 to 65 Hz
Overload capacity		Continuous input: 115% of maximum input, 10 s max.: 125% of maximum input
Temperature influence		Operating time Fluctuation based on measured value at standard temperature: −20°C to standard temperature: ±10% max. Standard temperature to 60°C : ±10% max. (Humidity: 25% to 80%)
Humidity influence		Operating time Based on ambient room humidity 25% to 80%: ±10% max.
Influence of power supply voltage		Operating time: ±10% max. **Note:** The error in the operating value and operating time under standard conditions.
Influence of power supply frequency		Operating time: ±10% max. (at 45 to 65 Hz) **Note:** The error in the operating value and operating time under standard conditions.
Influence of input frequency		At 45 to 65 Hz Operating time ±10% max. **Note:** The error in the operating value and operating time under standard conditions.
Applicable standards	**Conforming standards**	EN60255-5 and EN60255-6 Installation environment (Pollution Degree 2, Overvoltage Category III)
	EMC	EN61326
	Safety standards	UL508
Insulation resistance		20 MΩ min. Between external terminals and case Between input terminals and output terminals
Dielectric strength		2,000 VAC for one minute Between external terminals and case Between input terminals and output terminals
Noise immunity		1,500 V power supply terminal common/normal mode Square-wave noise of ±1 μs/100 ns pulse width with 1-ns rise time
Vibration resistance		Frequency 10 to 55 Hz, 0.35-mm single amplitude, acceleration 50 m/s^2 10 sweeps of 5 min each in X, Y, and Z directions
Shock resistance		100 m/s^2, 3 times each in 6 directions along three axes (up/down, left/right, forward/backward)
Degree of protection		Terminal section: Finger protection

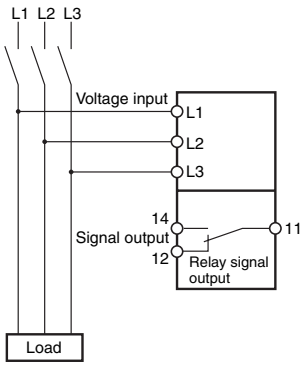
Connections

■ Wiring Diagram

Phase Sequence and Phase Loss Operation Diagram

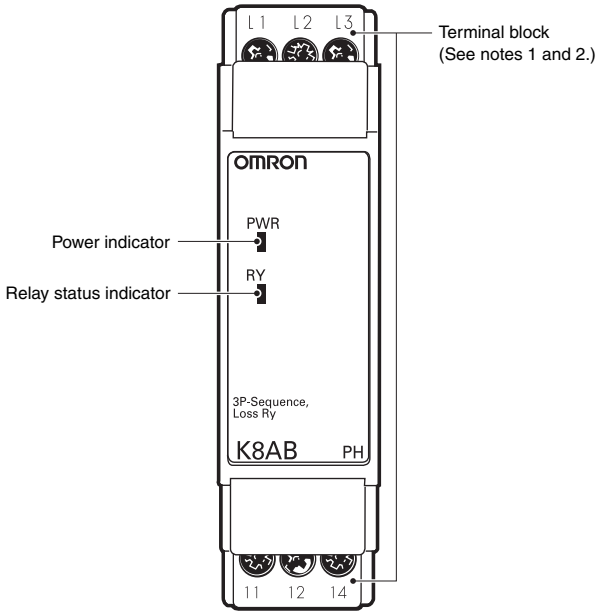


Note: **1.** Motor load phase loss cannot be detected. To detect motor load phase loss, use the K8AB-PM or K8AB-PA.
2. The K8AB-PH output relay is normally operative.
3. L1 and L3 function both as the power supply terminals and as input terminals. If the voltage drops below the minimum input voltage (60%), then the Relay will not operate due to an undervoltage.
4. Phase loss is detected based on the phase sequence, so phase loss cannot be detected for loads that generate inductive power, e.g., due to motor during operation.
5. Phase loss is detected based on voltage, so phase loss cannot be detected on the load side.



Nomenclature

■ Front

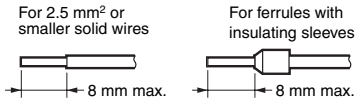


Indicators

Item	Meaning
Power indicator (PWR: Green)	Lit when power is being supplied (see note).
Relay status indicator (RY: Yellow)	Lit when relay is operating (normally lit).

Note: 1. The input across L1 and L3 is used for the internal power supply. Therefore, the power indicator will not be lit if there is no input across L1 and L3.

2. Use either a solid wire of 2.5 mm^2 maximum or a ferrule with insulating sleeve for the terminal connection.
The length of the exposed current-carrying part inserted into the terminal must be 8 mm or less to maintain dielectric strength after connection.



Recommended ferrules
Phoenix Contact
- AI 1,5-8BK (for AWG16)
- AI 1-8RD (for AWG18)
- AI 0,75-8GY (for AWG18)

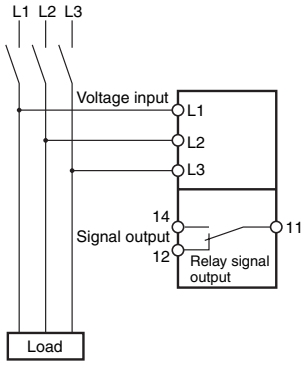
3. Tightening torque
Recommended: 0.49 N·m
Maximum: 0.54 N·m

■ Operation and Setting Methods

Connections

1. Input
Connect using L1, L2, and L3.
Make sure the phase sequence is wired correctly. The Unit will not operate normally if the phase sequence is incorrect.

2. Outputs
Terminals 11, 12, and 14 are output terminals for SPDT.

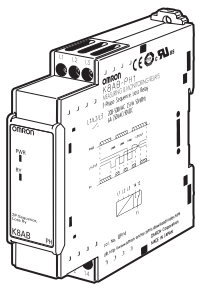


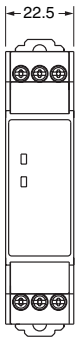
Dimensions

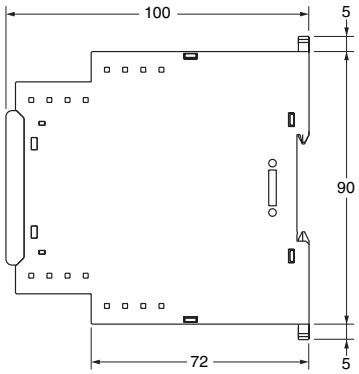
(Unit: mm)

Phase-sequence, Phase-loss Relays

K8AB-PH1







Questions and Answers

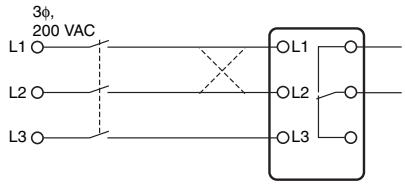
Q **Checking Operation**

A

Phase Sequence
Switch the wiring, as shown by the dotted lines in the connection diagram, to reverse the phase sequence and check that the K8AB operates.

Phase Loss
Create a phase loss for any input phase and check that the K8AB operates.

Connection Diagram



Q **Can phase loss be detected on the load side?**

A In principle, phase loss cannot be detected on the load side because the K8AB-PH1 measures three-phase voltage to determine phase loss.

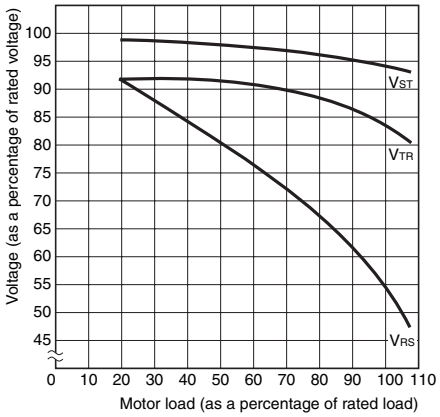
Q **Motor Load Phase Loss during Operation**

A Motor load phase loss cannot be detected during operation. It can be used to detect phase loss at startup.

Normally, three-phase motors will continue to rotate even if one phase is open. The three-phase voltage will be induced at the motor terminals. The diagram shows voltage induction at the motor terminals when phase R has been lost with a load applied to a three-phase motor. The horizontal axis shows the motor load as a percentage of the rated load, and the vertical axis shows voltage as a percentage of the rated voltage. The lines in the graph show the voltage induced at the motor terminals for each load when phase loss occurs during operation. As the graph shows, voltage is induced at the motor terminals even if there is phase loss for a motor load, so the K8AB-PH1 cannot detect phase loss for motor loads during operation. Use the K8AB-PH1 to detect phase loss at startup.

Characteristic Curve Diagram

Note: This characteristic curve shows the approximate values only.



Note: For phase loss of phase R. V_{ST}, V_{TR}, and V_{RS} indicate the motor terminal voltage at phase loss.

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To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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