

TPS63900 1.8-V to 5.5-V, 400-mA, 200-nA Quiescent Current Buck-Boost Converter

1 Features

- Input voltage range: 1.8 V to 5.5 V
- Output voltage range: 1.8 V to 5 V (100-mV steps)
 - Programmable with external resistors
 - SEL pin to toggle between two output voltage presets
- > 400-mA output current for $V_I \geq 1.8$ V, $V_O = 3.3$ V (typical 1.9-A peak switching current limit)
- > 90% Efficiency at 10- μ A load current
 - 200-nA operating quiescent current
 - 60-nA shutdown current
- Single-mode operation
 - Eliminates mode transitions between buck, buck-boost and boost operation
 - Low output ripple
 - Excellent transient performance
- Safety and robust operation features
 - Integrated soft start
 - Programmable input current limit with eight settings (1 mA to 100 mA and unlimited)
 - Output short-circuit and overtemperature protection
- Tiny solution size
 - Small 2.2 μ H inductor, single 22- μ F output capacitor
 - 10-Pin, 2.5-mm x 2.5-mm, 0.5-mm pitch WSON package

2 Applications

- [Smart meters and sensor nodes](#)
- [Electronic smart locks](#)
- [Medical sensor patches and patient monitors](#)
- [Wearable electronics](#)
- [Asset tracking](#)
- [Industrial IoT \(smart sensors\) / NB-IoT](#)

3 Description

The TPS63900 device is a high-efficiency synchronous buck-boost converter with an extremely low quiescent current (200 nA typical). The device has 32 user-programmable output voltage settings from 1.8 V to 5 V.

A dynamic voltage-scaling feature lets applications switch between two output voltages during operation; for example, to save power by using a lower system supply voltage during standby operation.

With its wide supply voltage range and programmable input current limit (1 mA to 10 mA and unlimited), the device is ideal for use with a wide range of primary like 3S Alkaline, 1S Li-MnO₂ or 1S Li-SOCl₂, and secondary battery types.

The high-output current capability supports commonly-used RF standards like sub-1-GHz, BLE, LoRa, wM-Bus, and NB-IoT.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS63900	WSON (10)	2.5 mm x 2.5 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

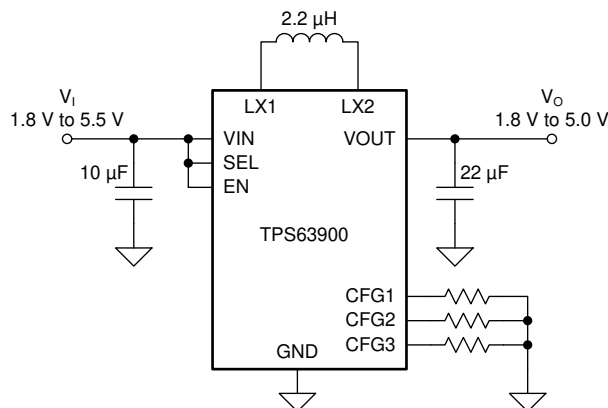


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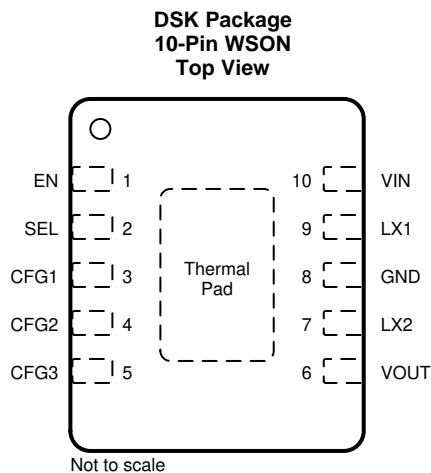
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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Original (March 2020) to Revision A	Page
• First public release	1

5 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NO.	NAME		
1	EN	I	Device enable. A high level applied to this pin enables the device and a low level disables it. It must not be left open.
2	SEL	I	Output voltage select. Selects $V_{O(2)}$ when a high level is applied to this pin. Selects $V_{O(1)}$ when a low level is applied to this pin. It must not be left open.
3	CFG1	I	Configuration pin 1. Connect a resistor between this pin and ground to set $V_{O(2)}$ and input current limit, must not be left open.
4	CFG2	I	Configuration pin 2. Connect a resistor between this pin and ground to set $V_{O(2)}$ and input current limit. Must not be left open.
5	CFG3	I	Configuration pin 3. Connect a resistor between this pin and ground to set $V_{O(1)}$. Must not be left open.
6	VOUT	—	Output voltage
7	LX2	—	Switching node of the boost stage
8	GND	—	Ground
9	LX1	—	Switching node of the buck stage
10	VIN	—	Supply voltage
—	Thermal Pad	—	Connect this pin to ground for correct operation.

ADVANCE INFORMATION

6 Specifications

CAUTION

The pre-production samples with XPS63900DSKT orderable part number (top marking: X639) have a silicon issue which causes leakage of around 300 μ A in normal operation. This leads to a reduced efficiency at light loads. Quiescent current into V_{IN} measurements on the pre-production silicon parts show 200 nA typical, if V_O is forced to 5 V.

The root cause of this leakage is understood and will be fixed for production units.

All other functions of the converter can be evaluated.

Production unit samples will be available in 3Q20.

For detailed information, contact bc_s_request_fs@list.ti.com.

6.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
V_I	Input voltage (V_{IN} , LX1, LX2, VOUT, EN, CFG1, CFG2, CFG3, SEL) ⁽²⁾	-0.3	5.9	V
T_J	Operating junction temperature	-40	150	°C
T_{stg}	Storage temperature	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground terminal, unless otherwise noted.

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±1000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 or ANSI/ESDA/JEDEC JS-002 ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V_I	Supply voltage	1.8		5.5	V
V_O	Output voltage	1.8		5.0	V
I_O	Output current ($V_I \geq 1.8$ V, $V_O = 3.6$ V)			0.4	A
C_I	Input capacitance ($V_I = 2.5$ V to 5 V, $V_O = 3.3$ V, $I_O = 0.4$ A) ⁽¹⁾	5			μ F
C_O	Output capacitance ($V_I = 2.5$ V to 5 V, $V_O = 3.3$ V, $I_O = 0.4$ A) ⁽¹⁾	10			μ F
$C_{(CFG)}$	Capacitance (CFG1, CFG2, CFG3)			10	pF
L	Inductance		2.2		μ H
I_{SAT}	Inductor saturation current rating	Unlimited current setting	2		A
		≤ 100 -mA current settings	1		
T_A	Operating ambient temperature	-40		85	°C
T_J	Operating junction temperature	-40		125	°C

- (1) Effective capacitance after DC bias effects have been considered.

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS63900	
		DSK Package (WSON)	
		10 PINS	
			UNIT
R _{θJA}	Junction-to-ambient thermal resistance	64.6	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	62.3	°C/W
R _{θJB}	Junction-to-board thermal resistance	31.1	°C/W
ψ _{JT}	Junction-to-top characterization parameter	1.6	°C/W
ψ _{JB}	Junction-to-board characterization parameter	31.0	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	10.0	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

Over operating junction temperature range and recommended supply voltage range (unless otherwise noted). Typical values are at V_I = 3.0 V, V_O = 2.5 V and T_J = 25°C (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY						
	Quiescent current into VIN	V _(EN) = 3 V, no load, not switching, "unlimited" current setting		0.2	1	μA
	Shutdown current into VIN	V _(EN) = 0 V		60		nA
V _{IT+(UVLO)}	Positive-going UVLO threshold voltage		1.73	1.75	1.77	V
V _{hys(UVLO)}	UVLO threshold voltage hysteresis		90	100	110	mV
I/O SIGNALS						
V _{IH}	High-level input voltage (EN, SEL)				1.2	V
V _{IL}	Low-level input voltage (EN, SEL)		0.4			V
	Input current (EN, SEL)	V _(EN) , V _(SEL) = 1.8 V or 0 V. T _J = 25°C		±1	±10	nA
POWER SWITCH						
r _{DS(on)}	On-state resistance	Q1	V _I = 3 V, V _O = 3.6 V, test current = 1 A	110		mΩ
		Q2		105		
		Q3		105		
		Q4		110		
CURRENT LIMIT						
	Peak current limit during Startup (Q1)	V _I = 3.6 V, unlimited current limit setting	0.48		0.83	A
	Peak current limit (Q1)	V _I = 1.8 V, V _O = 3.6 V, unlimited current limit setting	1.33	2.1	2.47	A
		V _I = 3.6 V, V _O = 3.3 V, 100-mA current limit setting	0.15	0.4	0.51	
	Average input current limit	T _J = -40°C to 85°C	1-mA setting	1		mA
			2.5-mA setting	2.5		
			5-mA setting	5		
			10-mA setting	10		
			25-mA setting	25		
			50-mA setting	50		
	100-mA setting	100				
OUTPUT						
	Output voltage DC accuracy	I _O = 1 mA, C _{O(eff)} = 4 μF, L _(eff) = 2.2 μH			±1.8	%
CONTROL						
	Internal reference resistor			33		kΩ

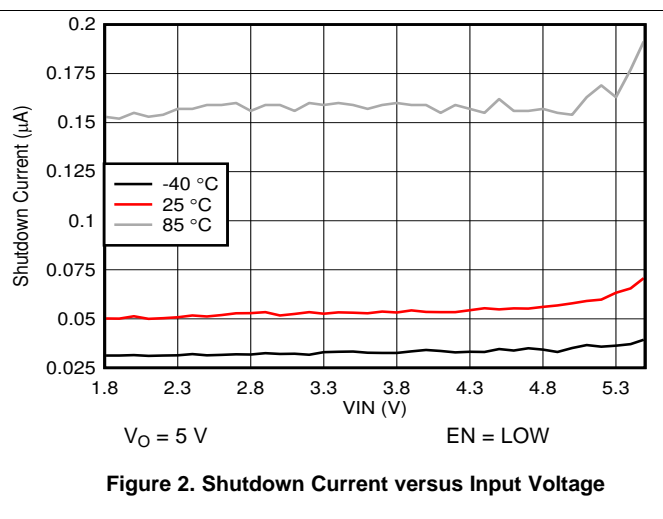
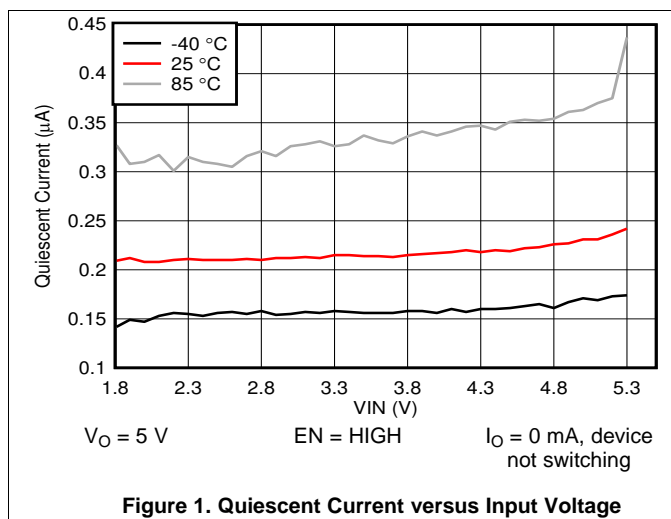
Electrical Characteristics (continued)

Over operating junction temperature range and recommended supply voltage range (unless otherwise noted). Typical values are at $V_I = 3.0\text{ V}$, $V_O = 2.5\text{ V}$ and $T_J = 25^\circ\text{C}$ (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
R_{CFG}	R2D setting #0			0	0.1	k Ω
	R2D setting #1		-3%	0.511	+3%	
	R2D setting #2		-3%	1.15	+3%	
	R2D setting #3		-3%	1.87	+3%	
	R2D setting #4		-3%	2.74	+3%	
	R2D setting #5		-3%	3.83	+3%	
	R2D setting #6		-3%	5.11	+3%	
	R2D setting #7		-3%	6.49	+3%	
	R2D setting #8		-3%	8.25	+3%	
	R2D setting #9		-3%	10.5	+3%	
	R2D setting #10		-3%	13.3	+3%	
	R2D setting #11		-3%	16.2	+3%	
	R2D setting #12		-3%	20.5	+3%	
	R2D setting #13		-3%	24.9	+3%	
	R2D setting #14		-3%	30.1	+3%	
R2D setting #15		-3%	36.5	+3%		
PROTECTION FEATURES						
	Thermal shutdown threshold temperature		140	150	160	$^\circ\text{C}$
	Thermal shutdown hysteresis		15	20	25	$^\circ\text{C}$
TIMING PARAMETERS						
$t_{d(POR)}$	POR signal delay after reaching POR threshold			3.8		ms
$t_{d(EN)}$	Delay between a rising edge on the EN pin and the start of the output voltage ramp	Supply voltage stable before EN pin goes high			1.5	ms
$t_{w(SS)}$	Soft-start step duration		100	125	150	μs
$t_{d(SEL)}$	Delay between a change in the state of the SEL pin and the first step change in the output voltage			30	40	μs
$t_{w(DVS)}$	Dynamic voltage scaling step duration		100	125	150	μs
	Overcurrent protection timeout	$R_L = 10\ \Omega$	0.8	1	1.2	ms
$t_{d(RESTART)}$	Restart delay after protection			10	11	ms

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6.6 Typical Characteristics



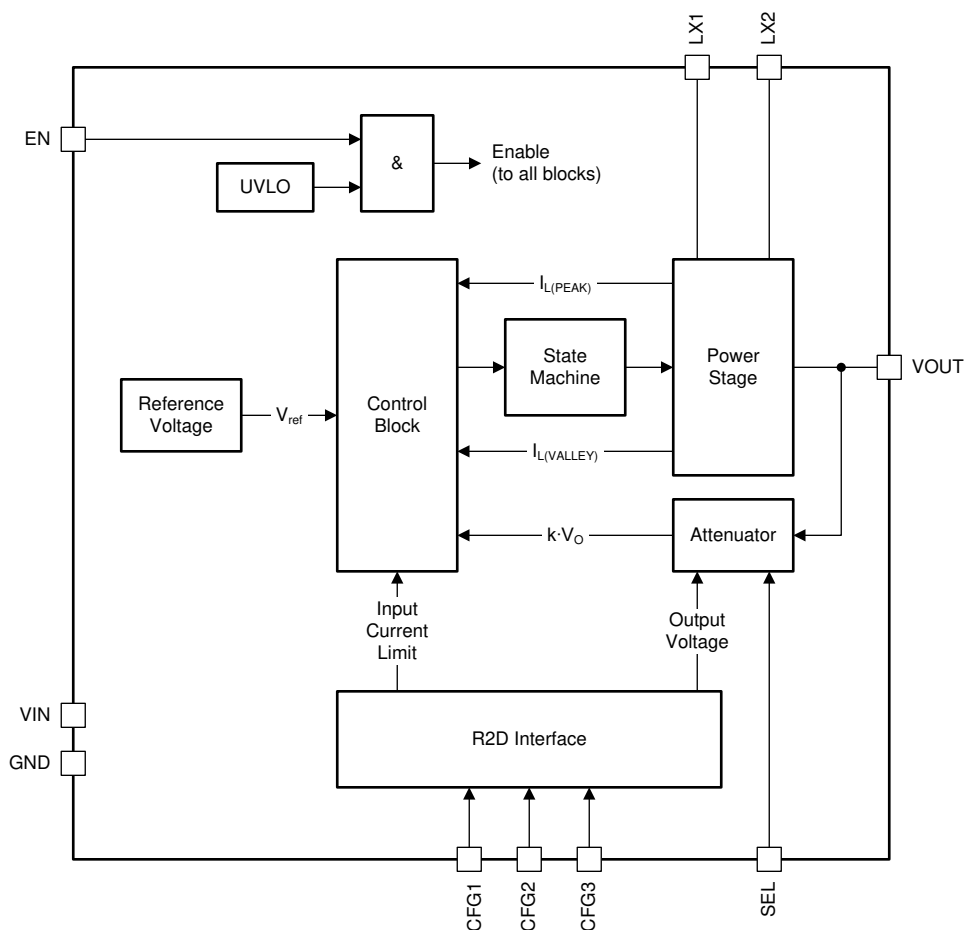
7 Detailed Description

7.1 Overview

The TPS63900 device is a four-switch synchronous buck-boost converter with a maximum output current of 400 mA. It has a single-mode operation that allows the device to regulate the output voltage to a level above, below, or equal to the input voltage without displaying the mode-switching transients and unpredictable inductor current ripple from which many other buck-boost devices suffer.

The switching frequency of the TPS63900 device varies with the operating conditions: it is lowest when I_O is low and increases smoothly as I_O increases.

7.2 Functional Block Diagram



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7.3 Feature Description

7.3.1 Trapezoidal Current Control

Figure 3 shows a simplified block diagram of the power stage of the device. Inductor current is sensed in series with Q1 (the peak current) and Q4 (the valley current).

Feature Description (continued)

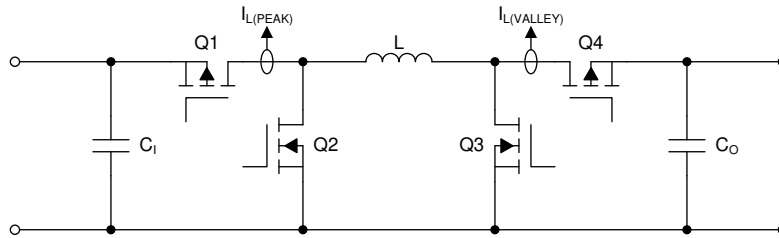


Figure 3. Power Stage Simplified Block Diagram

The device uses a trapezoidal inductor current to regulate its output under all operating conditions. Thus, the device only has one operating mode and does not display any of the mode-change transients or unpredictable switching displayed by many other buck-boost devices.

There are four phases of operation:

- Phase A – Q1 and Q3 are on and Q2 and Q4 are off
- Phase B – Q1 and Q4 are on and Q2 and Q3 are off
- Phase C – Q2 and Q4 are on and Q1 and Q3 are off
- Phase D – Q2 and Q3 are on and Q1 and Q4 are off

Figure 4 shows the inductor current waveform when $V_I > V_O$, Figure 5 shows the current waveform when $V_I = V_O$, and Figure 6 shows the current waveform when $V_I < V_O$.

Figure 4 through Figure 6 show the typical waveforms during continuous conduction mode (CCM) switching for three operating conditions. During discontinuous conduction mode (DCM), the typical inductor current waveforms look similar to CCM with Phase D at 0 A inductor current. In deep boost mode, where $V_I \ll V_O$, Phase C length gradually decreases to zero until the switching waveform becomes triangular.

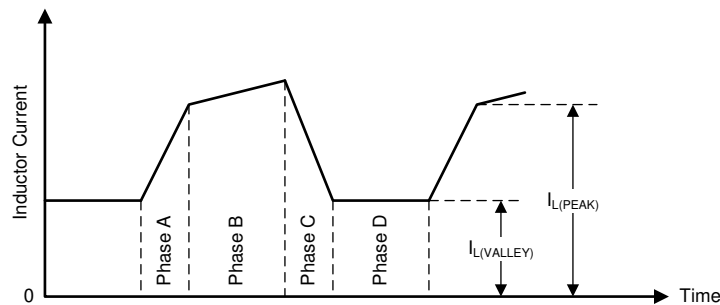


Figure 4. Inductor Current Waveform when $V_I > V_O$ (CCM)

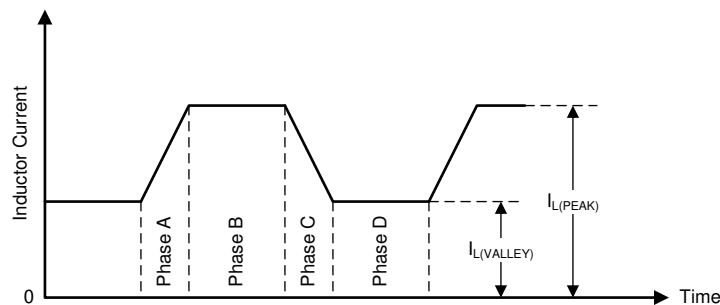


Figure 5. Inductor Current Waveform when $V_I = V_O$ (CCM)

Feature Description (continued)

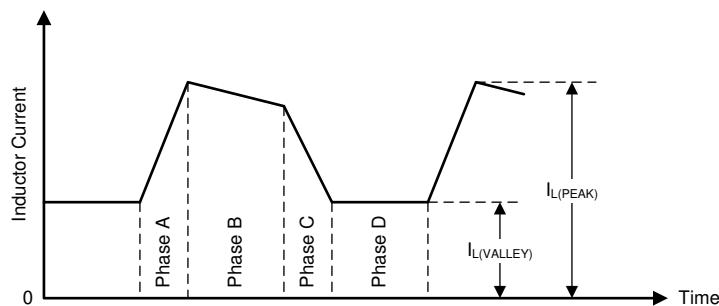


Figure 6. Inductor Current Waveform when $V_I < V_O$ (CCM)

The ideal relationship between V_I and V_O (that is, assuming no losses) is

$$V_O = V_I \left(\frac{t_{w(A)} + t_{w(B)}}{t_{w(B)} + t_{w(C)}} \right) \tag{1}$$

where

- V_I is the input voltage
- V_O is the output voltage
- $t_{w(A)}$ is the duration of phase A
- $t_{w(B)}$ is the duration of phase B
- $t_{w(C)}$ is the duration of phase C

(1)

By varying relative duration of each phase, the device can regulate V_O to be less than, equal to, or greater than V_I .

7.3.2 Device Enable / Disable

The device turns on when *all* the following conditions are true:

- The supply voltage is greater than the positive-going undervoltage lockout (UVLO) threshold.
- The EN pin is high.

The device turns off when *at least one* of the following conditions is true:

- The supply voltage is less than the negative-going UVLO threshold.
- The EN pin is low.

A complete state diagram is shown in [Figure 16](#).

After the device turns on, the internal reference system starts, then the trimming information and the CFG pins are read out. The device ignores any further changes to the CFG pins during device operation.

[Figure 7](#) shows the internal start-up sequence.

Feature Description (continued)

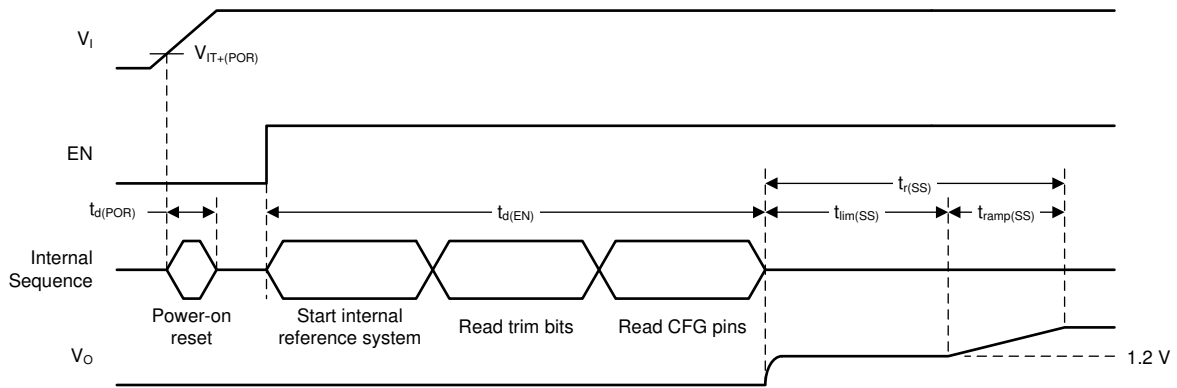


Figure 7. Internal Start-Up Sequence

7.3.3 Soft Start

NOTE

The pre-production samples with XPS63900DSKT orderable part number show a different start up behavior below $V_O = 1.8\text{ V}$ (see [Soft Start - Pre-production material](#) for details).

The device has a soft-start feature that starts the device typically with 500-mA peak current limit until $V_O = 1.8\text{ V}$ and 500 μs elapsed when the input current limit is set to unlimited (see the [Input Current Limit](#) section). Afterwards, the output voltage ramps in a series of discrete steps (see [Figure 8](#)).

- When $V_O \leq 1.8\text{ V}$, peak current is limited to 500 mA typical for 500 μs .
- When $V_O > 1.8\text{ V}$, each step is 100 mV high and has a duration of 125 μs .

The total start-up time can be calculated with [Equation 2](#).

$$t_{r(SS)} = V_O \times 1.25 \left[\frac{\text{ms}}{\text{V}} \right] - 1.75 [\text{ms}]$$

where

- $t_{r(SS)}$ is the rise time of the output voltage in milliseconds
- V_O is the output voltage in volts

(2)

[Figure 8](#) shows a typical start-up case.

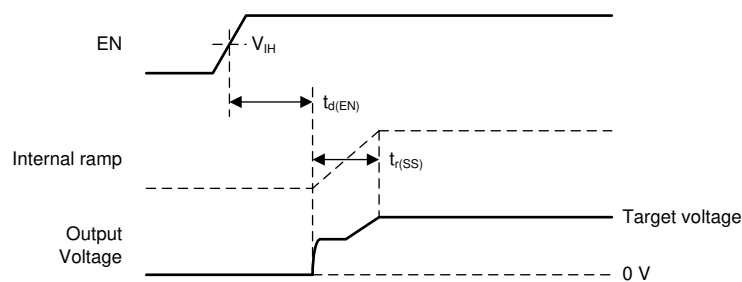


Figure 8. Start-Up Behavior

[Figure 9](#) illustrates the start-up step size behavior.

Feature Description (continued)

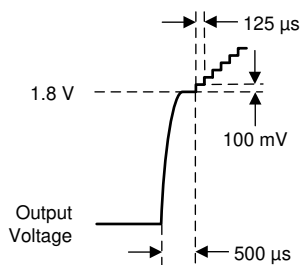


Figure 9. Typical Soft-Start Ramp Step Size

Table 1 shows the typical start-up time for a number of standard output voltages.

Table 1. Typical Start-Up Times

OUTPUT VOLTAGE	START-UP TIME
1.8 V	0.5 ms
2.5 V	1.375 ms
3.3 V	2.375 ms
5 V	4.5 ms

If the output is prebiased – that is, the initial output voltage is not zero – the start-up behavior is as follows:

- If the prebias voltage is *lower* than the target voltage, the device does not start switching until the ramping output voltage is greater than the prebias voltage (see Figure 10).
- If the prebias voltage is *higher* than the target voltage, the device does not start to switch until the output voltage has decreased to the target voltage (see Figure 11). The device cannot actively discharge the output to the target voltage and relies on the load current to discharge the output capacitor and decrease the output voltage to the target value.

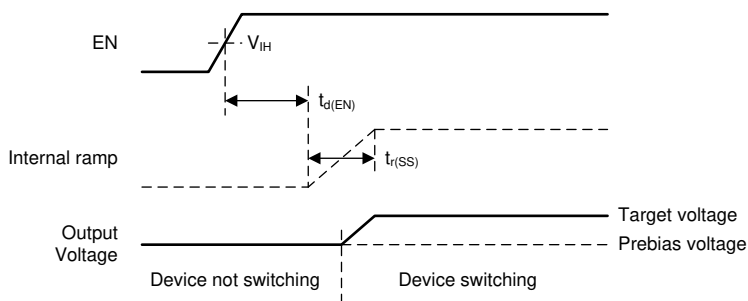


Figure 10. Start-Up Behavior into Prebiased (Low) Output

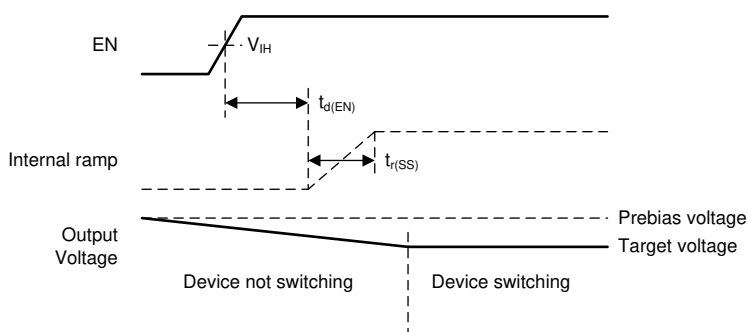


Figure 11. Start-Up Behavior into Prebiased (High) Output

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7.3.4 Soft Start - Pre-production material

NOTE

This section only applies to pre-production samples with XPS63900DSKT orderable part number.

The device has a soft-start feature that starts the device typically with 500-mA peak current limit until $V_O = 1.2\text{ V}$ and $750\ \mu\text{s}$ elapsed. Afterwards, the output voltage ramps in a series of discrete steps (see Figure 8).

- When $V_O \leq 1.2\text{ V}$, peak current is limited to 500 mA typical for $750\ \mu\text{s}$.
- When $V_O \leq 1.8\text{ V}$, each step is 200 mV high and has a duration of $125\ \mu\text{s}$.
- When $V_O > 1.8\text{ V}$, each step is 100 mV high and has a duration of $125\ \mu\text{s}$.

The total start-up time can be calculated with Equation 3.

$$t_{r(SS)} = V_O \times 1.25 \left[\frac{\text{ms}}{\text{V}} \right] - 1.125 [\text{ms}]$$

where

- $t_{r(SS)}$ is the rise time of the output voltage in milliseconds
- V_O is the output voltage in volts

(3)

Figure 12 illustrates the start-up step size behavior.

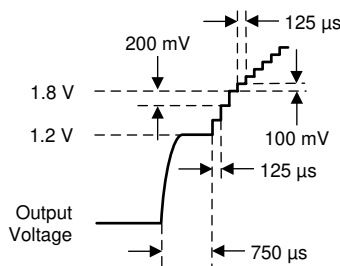


Figure 12. Typical Soft-Start Ramp Step Size

Table 2 shows the typical start-up time for a number of standard output voltages.

Table 2. Typical Start-Up Times

OUTPUT VOLTAGE	START-UP TIME
1.8 V	1.125 ms
2.5 V	2 ms
3.3 V	3 ms
5 V	5.125 ms

7.3.5 Input Current Limit

The device can limit the current drawn from its supply, so that it can be used with batteries that do not support high peak currents. The input current limit is active during normal operation and at start-up to avoid high inrush current. The device has eight current limit settings:

- 1 mA
- 2.5 mA
- 5 mA
- 10 mA
- 25 mA
- 50 mA
- 100 mA
- Unlimited

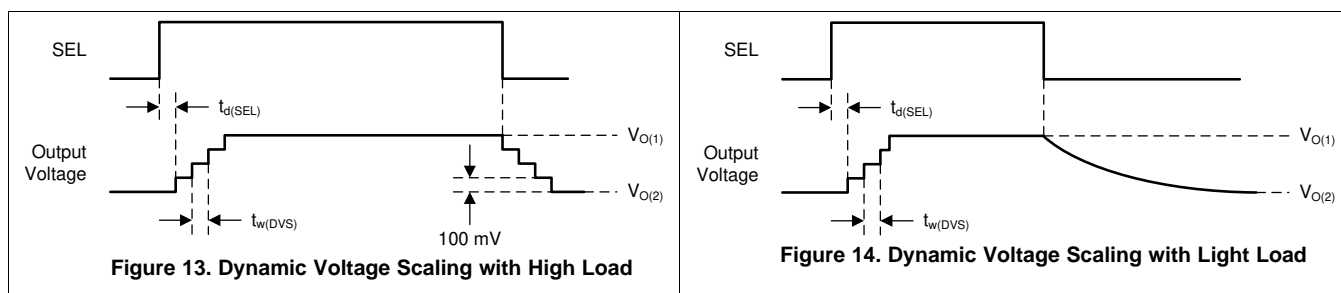
CFG1 and CFG2 pins select which setting is active (see the [Device Configuration \(Resistor-to-Digital Interface\)](#) section).

7.3.6 Dynamic Voltage Scaling

The device has a dynamic voltage scaling function to switch between the two output voltage settings. When the SEL pin changes state, the output voltage ramps to the new value in 100-mV steps. The duration of each step is 125 μs (see [Figure 13](#)).

The device does not actively discharge the output capacitor, when the output voltage ramps to a lower level. This leads to a longer output voltage settling time when light load is applied (see [Figure 14](#)). The settling time can be calculated with [Equation 4](#).

$$t_{\text{settle}} = C_O \times \frac{V_{O(\text{HIGH})} - V_{O(\text{LOW})}}{I_O} \tag{4}$$



7.3.7 Device Configuration (Resistor-to-Digital Interface)

The device has three configuration pins (CFG1, CFG2, and CFG3) that control its operation. When the device starts up, a resistor-to-digital (R2D) interface reads the values of the configuration resistors on the CFG pins and transfers the setting to an internal configuration register (see [Figure 15](#)).

- CFG1 and CFG2 set $V_{O(2)}$ level and the input current limit.
- CFG3 sets $V_{O(1)}$ level.

To reduce power consumption, the device reads the value of the resistors connected to the configuration pins during start-up and then disables these pins. Once the device has started to operate, changes to the configuration pins have no effect.

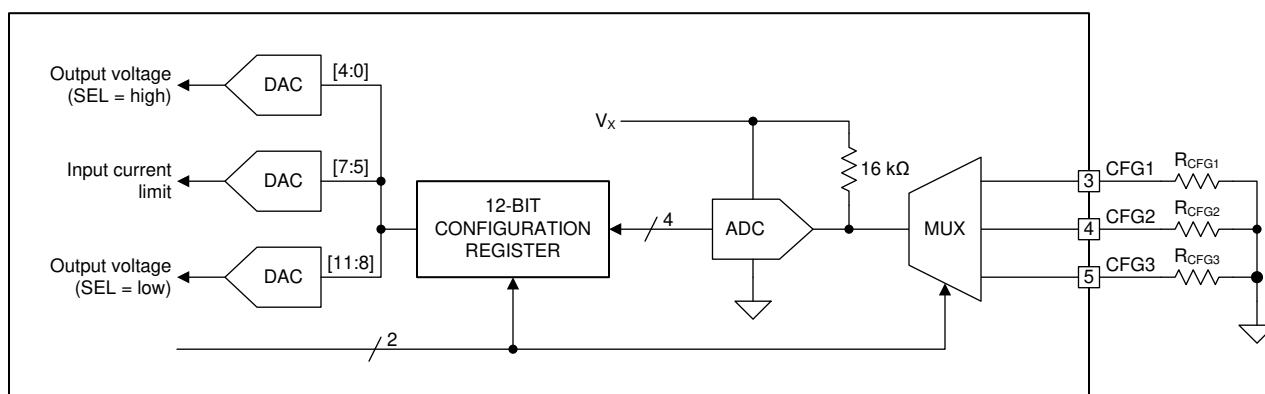


Figure 15. Resistor-to-Digital Interface Block Diagram

[Table 3](#) summarizes the resistor values needed to configure the device for different input current limit and output voltage (SEL = high) settings. For correct operation, use resistors with a tolerance of ±1% or better and a temperature coefficient of ±200 ppm or better.

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NOTE

For correct operation, TI recommends that the total RMS error of the configuration resistors—including initial tolerance, temperature drift, and ageing—is less than ±3%.

Table 3. Input Current Limit and Output Voltage (SEL = High) Settings

OUTPUT VOLTAGE - $V_{O(2)}$ (SEL = HIGH)		INPUT CURRENT LIMIT							
		Unlimited	100 mA	50 mA	25 mA	10 mA	5 mA	2.5 mA	1 mA
1.8 V	R _{CFG1}	0 Ω							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
1.9 V	R _{CFG1}	511 Ω							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.0 V	R _{CFG1}	1.15 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.1 V	R _{CFG1}	1.87 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.2 V	R _{CFG1}	2.74 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.3 V	R _{CFG1}	3.83 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.4 V	R _{CFG1}	5.11 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.5 V	R _{CFG1}	6.49 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.6 V	R _{CFG1}	8.25 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.7 V	R _{CFG1}	10.5 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.8 V	R _{CFG1}	13.3 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
2.9 V	R _{CFG1}	16.2 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
3.0 V	R _{CFG1}	20.5 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
3.1 V	R _{CFG1}	24.9 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
3.2 V	R _{CFG1}	30.1 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
3.3 V	R _{CFG1}	36.5 kΩ							
	R _{CFG2}	0 Ω	511 Ω	1.15 kΩ	1.87 kΩ	2.74 kΩ	3.83 kΩ	5.11 kΩ	6.49 kΩ
3.4 V	R _{CFG1}	0 Ω							
	R _{CFG2}	8.25 kΩ	10.5 kΩ	13.3 kΩ	16.2 kΩ	20.5 kΩ	24.9 kΩ	30.1 kΩ	36.5 kΩ
3.5 V	R _{CFG1}	511 Ω							
	R _{CFG2}	8.25 kΩ	10.5 kΩ	13.3 kΩ	16.2 kΩ	20.5 kΩ	24.9 kΩ	30.1 kΩ	36.5 kΩ
3.6 V	R _{CFG1}	1.15 kΩ							
	R _{CFG2}	8.25 kΩ	10.5 kΩ	13.3 kΩ	16.2 kΩ	20.5 kΩ	24.9 kΩ	30.1 kΩ	36.5 kΩ
3.7 V	R _{CFG1}	1.87 kΩ							
	R _{CFG2}	8.25 kΩ	10.5 kΩ	13.3 kΩ	16.2 kΩ	20.5 kΩ	24.9 kΩ	30.1 kΩ	36.5 kΩ

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Table 3. Input Current Limit and Output Voltage (SEL = High) Settings (continued)

OUTPUT VOLTAGE - $V_{O(2)}$ (SEL = HIGH)		INPUT CURRENT LIMIT							
		Unlimited	100 mA	50 mA	25 mA	10 mA	5 mA	2.5 mA	1 mA
3.8 V	R _{CFG1}	2.74 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
3.9 V	R _{CFG1}	3.83 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.0 V	R _{CFG1}	5.11 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.1 V	R _{CFG1}	6.49 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.2 V	R _{CFG1}	8.25 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.3 V	R _{CFG1}	10.5 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.4 V	R _{CFG1}	13.3 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.5 V	R _{CFG1}	16.2 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.6 V	R _{CFG1}	20.5 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.7 V	R _{CFG1}	24.9 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
4.8 V	R _{CFG1}	30.1 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω
5.0 V	R _{CFG1}	36.5 k Ω							
	R _{CFG2}	8.25 k Ω	10.5 k Ω	13.3 k Ω	16.2 k Ω	20.5 k Ω	24.9 k Ω	30.1 k Ω	36.5 k Ω

Table 4 summarizes the resistor values needed to configure the device for different output voltage (SEL = low) settings. For correct operation, use resistors with a tolerance of $\pm 1\%$ or better and a temperature coefficient of better than ± 200 ppm.

Table 4. Output Voltage (SEL Pin = Low) Settings

OUTPUT VOLTAGE - $V_{O(1)}$ (SEL = LOW)	R _{CFG3}
1.8 V	0 Ω
2.0 V	511 Ω
2.1 V	1.15 k Ω
2.2 V	1.87 k Ω
2.3 V	2.74 k Ω
2.4 V	3.83 k Ω
2.5 V	5.11 k Ω
2.6 V	6.49 k Ω
2.7 V	8.25 k Ω
2.8 V	10.5 k Ω
3.0 V	13.3 k Ω
3.3 V	16.2 k Ω
3.6 V	20.5 k Ω
4.0 V	24.9 k Ω
4.5 V	30.1 k Ω

Table 4. Output Voltage (SEL Pin = Low) Settings (continued)

OUTPUT VOLTAGE - $V_{O(1)}$ (SEL = LOW)	R_{CF63}
5.0 V	36.5 k Ω

7.3.8 SEL Pin

The SEL pin selects which configuration bits control the output voltage.

- When SEL = high, the output voltage $V_{O(2)}$ is set.
- When SEL = low, the output voltage $V_{O(1)}$ is set.

7.3.9 Short-Circuit Protection

7.3.9.1 Current Limit Setting = 'Unlimited'

The device has a function to limit the current through Q1. When the peak current is limited for longer than 1 ms, the device detects a short-circuit condition and turns off the output. The device automatically restarts operation after a delay of $t_{d(RESTART)}$.

7.3.9.2 Current Limit Setting = 1 mA to 100 mA

The input current limiting function automatically limits current during a short-circuit condition. The device regulates the average input current for as long as the short-circuit condition exists and does not turn off the output.

7.3.10 Thermal Shutdown

The device has a thermal shutdown function that disables the device if it gets too hot for correct operation. When the device cools down, it automatically restarts operation after a typical delay of $t_{d(RESTART)} = 10$ ms. The device starts with the soft-start feature (see the [Soft Start](#) section) and keeps the previously read CFG pin setting.

7.4 Device Functional Modes

The device has two functional modes: on and off. The device enters the on mode when the voltage on the VIN pin is higher than the UVLO threshold and a high logic level is applied to the EN pin. The device enters the off mode when the voltage on the VIN pin is lower than the UVLO threshold or a low logic level is applied to the EN pin.

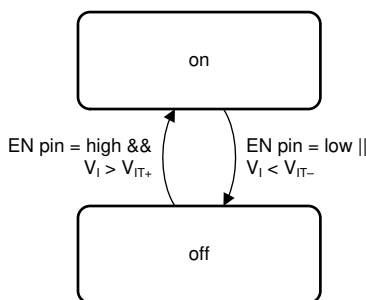


Figure 16. Device Functional Modes

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8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The TPS63900 is a high efficiency, non-inverting buck-boost converter with an extremely low quiescent current, suitable for applications that need a regulated output voltage from an input supply that can be higher or lower than the output voltage. The input current limit and output voltage are set through resistors connected to the three CFGx pins.

8.2 Typical Application

NOTE

The pre-production samples with XPS63900DSKT orderable part number need to be operated with 10 μ F output capacitor (0603). For the production material the minimum output capacitor is 22 μ F (0603).

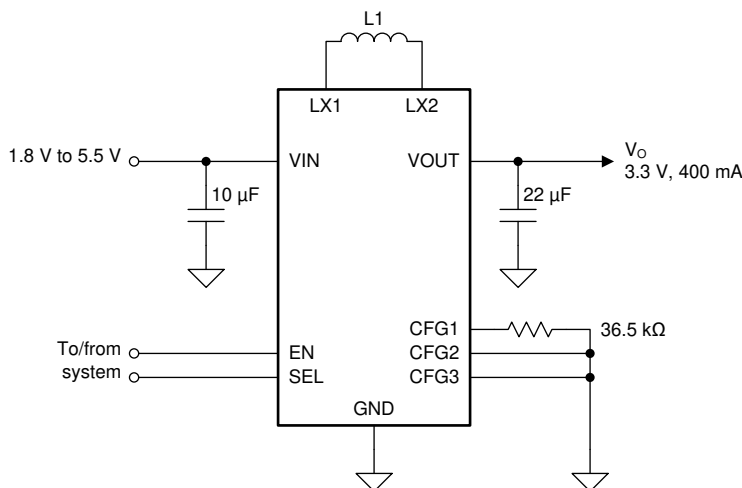


Figure 17. 3.3 V_{OUT} Typical Application

8.2.1 Design Requirements

The design guideline provides a component selection to operate the device within the *Recommended Operating Conditions*.

Table 5. Matrix of Output Capacitor and Inductor Combinations

Nominal Inductor Value [μ H] ⁽¹⁾	Nominal Output Capacitor Value [μ F] ⁽²⁾				
	22	47	66	100	≥ 300
2.2	+ ⁽³⁾	+	+	+	+ ⁽⁴⁾

- (1) Inductor tolerance and current derating is anticipated. The effective inductance can vary by 20% and –30%.
- (2) Capacitance tolerance and DC bias voltage derating is anticipated. The effective capacitance can vary by 20% and –50%.
- (3) Typical application. Other check marks indicate possible filter combinations.
- (4) Only with input current limit active.

8.2.2 Detailed Design Procedure

The first step is the selection of the output filter components. To simplify this process, the [Recommended Operating Conditions](#) outlines minimum and maximum values for inductance and capacitance. Tolerance and derating must be taken into account when selecting nominal inductance and capacitance.

8.2.2.1 Custom Design with WEBENCH Tools

[Click here](#) to create a custom design using the TPS63900 device with the WEBENCH® Power Designer.

1. Start by entering your V_{IN} , V_{OUT} and I_{OUT} requirements.
2. Optimize your design for key parameters like efficiency, footprint or cost using the optimizer dial and compare this design with other possible solutions from Texas Instruments.
3. WEBENCH Power Designer provides you with a customized schematic along with a list of materials with real time pricing and component availability.
4. In most cases, you will also be able to:
 - Run electrical simulations to see important waveforms and circuit performance,
 - Run thermal simulations to understand the thermal performance of your board,
 - Export your customized schematic and layout into popular CAD formats,
 - Print PDF reports for the design, and share your design with colleagues.
5. Get more information about WEBENCH tools at www.ti.com/webench.

8.2.2.2 Inductor Selection

The inductor selection is affected by several parameters such as inductor ripple current, output voltage ripple, transition point into Power Save Mode, and efficiency. See [Table 6](#) for typical inductors.

For high efficiencies, the inductor must have a low DC resistance to minimize conduction losses. Especially at high-switching frequencies, the core material has a high impact on efficiency. When using small chip inductors, the efficiency is reduced mainly due to higher inductor core losses. This needs to be considered when selecting the appropriate inductor. The inductor value determines the inductor ripple current. The larger the inductor value, the smaller the inductor ripple current and the lower the core and conduction losses of the converter. Conversely, larger inductor values cause a slower load transient response. To avoid saturation of the inductor, the peak current for the inductor in steady state operation is calculated using [Equation 6](#). Only the equation which defines the switch current in boost mode is shown, because this provides the highest value of current and represents the critical current value for selecting the right inductor.

$$\text{Duty Cycle Boost} \quad D = \frac{V_{OUT} - V_{IN}}{V_{OUT}} \quad (5)$$

$$I_{PEAK} = \frac{I_{out}}{\eta \times (1 - D)} + \frac{V_{in} \times D}{2 \times f \times L} \quad (6)$$

where:

- D = Duty Cycle in Boost mode
- f = Converter switching frequency
- L = Inductor value
- η = Estimated converter efficiency (use the number from the efficiency curves or 0.9 as an assumption)

NOTE

The calculation must be done for the minimum input voltage in boost mode.

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current of the inductor needed. It is recommended to choose an inductor with a saturation current 20% higher than the value calculated using [Equation 6](#). Possible inductors are listed in [Table 6](#).

Table 6. List of Recommended Inductors ⁽¹⁾

Inductor Value [μH]	Saturation Current [A]	DCR [mΩ]	Part Number	Manufacturer	Size (LxWxH mm)
2.2	3.5	21	XFL4020-222ME	Coilcraft	4 x 4 x 2
2.2	1.9	40	1231AS-H-2R2M	Murata	3.7 x 3.5 x 1.8
2.2	1.7	72	SRN3015TA-2R2M	Bourns	3 x 3 x 1.5
2.2	3.1	97	DFE252010F-2R2M	Murata	2.5 x 2 x 1

(1) See [Third-party Products Disclaimer](#)

8.2.2.3 Output Capacitor Selection

For the output capacitor, use of small ceramic capacitors placed as close as possible to the VOUT and GND pins of the IC is recommended. The recommended nominal output capacitor value is a single 22 μF. If, for any reason, the application requires the use of large capacitors which cannot be placed close to the IC, use a smaller ceramic capacitor in parallel to the large capacitor. The small capacitor must be placed as close as possible to the VOUT and GND pins of the IC.

It is important that the effective capacitance is given according to the recommended value in the [Recommended Operating Conditions](#). In general, consider DC bias effects resulting in less effective capacitance. The choice of the output capacitance is mainly a tradeoff between size and transient behavior as higher capacitance reduces transient response overshoot and undershoot and increases transient response time. Possible output capacitors are listed in [Table 7](#).

There is no upper limit for the output capacitance value.

Table 7. List of Recommended Capacitors ⁽¹⁾

Capacitor Value [μF]	Voltage Rating [V]	Part Number	Manufacturer	Size (Metric)
22	6.3	GRM187R60J226ME15	Murata	0603 (1608)
22	6.3	GRM219R60J476ME44	Murata	0805 (3210)
47	6.3	GRM188R60J476ME15	Murata	0603 (1608)

(1) See [Third-party Products Disclaimer](#)

8.2.2.4 Input Capacitor Selection

A 10-μF input capacitor is recommended to improve line transient behavior of the regulator and EMI behavior of the total power supply circuit. An X5R or X7R ceramic capacitor placed as close as possible to the VIN and GND pins of the IC is recommended. This capacitance can be increased without limit. If the input supply is located more than a few inches from the TPS63900 converter additional bulk capacitance can be required in addition to the ceramic bypass capacitors. An electrolytic or tantalum capacitor with a value of 47 μF is a typical choice.

Table 8. List of Recommended Capacitors ⁽¹⁾

Capacitor Value [μF]	Voltage Rating [V]	Part Number	Manufacturer	Size (Metric)
10	6.3	GRM188R60J106ME47	Murata	0603 (1608)
10	10	GRM188R61A106ME69	Murata	0603 (1608)
22	6.3	GRM187R60J226ME15	Murata	0603 (1608)

(1) See [Third-party Products Disclaimer](#)

8.2.2.5 Setting The Output Voltage

The output voltage is set with CFGx pins (see the [Device Configuration \(Resistor-to-Digital Interface\)](#) section).

8.2.3 Application Curves

NOTE

The pre-production samples with XPS63900DSKT orderable part number need to be operated with 10 μ F output capacitor (0603). For the production material the minimum output capacitor is 22 μ F (0603).

Table 9. Components for Application Characteristic Curves for $V_{OUT} = 3.3\text{ V}^{(1)(2)}$

Reference	Description	Part Number	Manufacturer
U1	400-mA ultra low Iq Buck-Boost Converter (2.5 mm x 2.5 mm QFN)	TPS63900DSK	Texas Instruments
L1	2.2 μ H, 4 mm x 4 mm x 2 mm, 3.5 A, 10 m Ω	XFL4020-222ME	Coilcraft
C1	10 μ F, 0603, Ceramic Capacitor, \pm 20%, 6.3 V	GRM188R60J106ME47	Murata
C2	22 μ F, 0603, Ceramic Capacitor, \pm 20%, 6.3 V	GRM187R60J226ME15	Murata
CFG1	36.5 k Ω , 0603 Resistor, 1%, 100 mW	Standard	Standard
CFG2	0 Ω , 0603 Resistor, 1%, 100 mW	Standard	Standard
CFG3	0 Ω , 0603 Resistor, 1%, 100 mW	Standard	Standard

- (1) See [Third-Party Products Disclaimer](#)
- (2) For other output voltages, refer to [Table 5](#) for resistor values.

Table 10. Typical Characteristics Curves

PARAMETER	CONDITIONS	FIGURE
Output Current Capability		
Typical Output Current Capability versus Input Voltage	$V_O = 1.8\text{ V to }5.0\text{ V}$	Figure 18
Typical Burst Switching Frequency versus Output Current	$V_O = 1.8\text{ V to }3.6\text{ V}$	Figure 19
Efficiency		
Efficiency versus Output Current	$V_I = 2.5\text{ V to }5.5\text{ V}, V_O = 3.3\text{ V}$	Figure 20
Efficiency versus Input Voltage	$I_O = 10\text{ mA to }500\text{ mA}, V_O = 3.3\text{ V}$	Figure 21
Switching Waveforms		
Switching Waveforms, Boost Operation	$V_I = 1.8\text{ V}, V_O = 3.3\text{ V}$	Figure 22
Switching Waveforms, Boost Operation	$V_I = 2.8\text{ V}, V_O = 3.3\text{ V}$	Figure 23
Switching Waveforms, Buck-Boost Operation	$V_I = 3.3\text{ V}, V_O = 3.3\text{ V}$	Figure 24
Switching Waveforms, Buck Operation	$V_I = 4.0\text{ V}, V_O = 3.3\text{ V}$	Figure 25
DVS (Digital Voltage Scaling)		
DVS Behavior at Light Load	$V_I = 3.3\text{ V}, V_{O(1)} = 2.2\text{ V}, V_{O(2)} = 3.6\text{ V}, \text{Load} = 1\text{ k}\Omega$	Figure 26
DVS Behavior at High Load	$V_I = 3.3\text{ V}, V_{O(1)} = 2.2\text{ V}, V_{O(2)} = 3.6\text{ V}, \text{Load} = 30\ \Omega$	Figure 27

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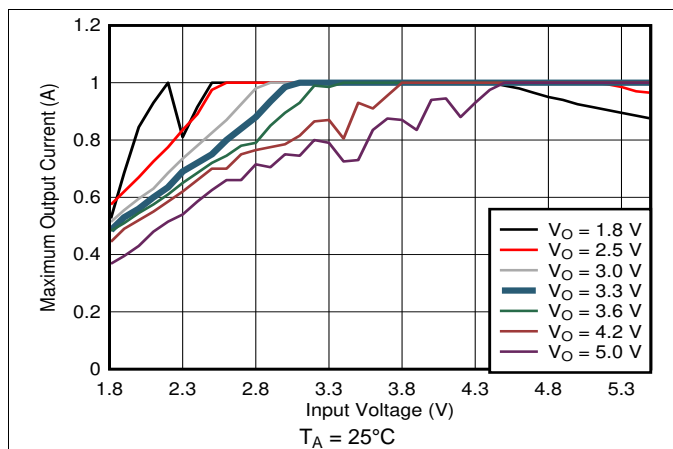


Figure 18. Typical Output Current Capability versus Input Voltage

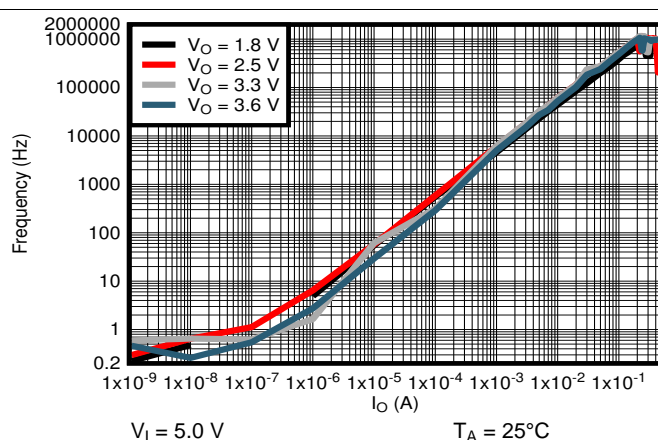


Figure 19. Typical Burst Switching Frequency versus Output Current

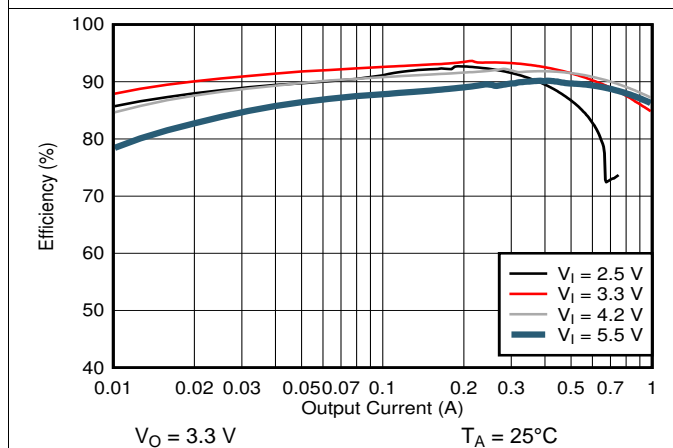


Figure 20. Efficiency versus Output Current

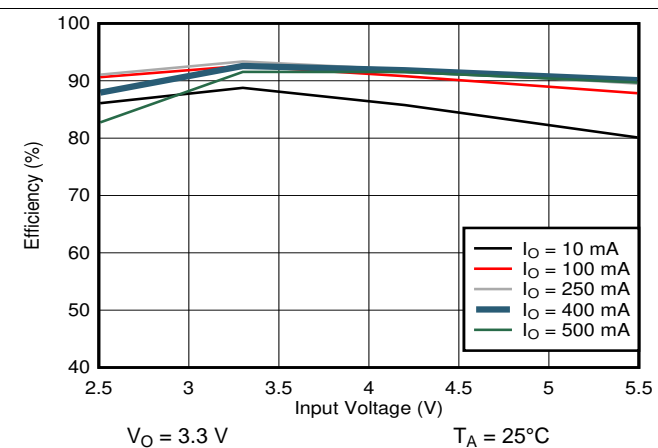


Figure 21. Efficiency versus Input Voltage

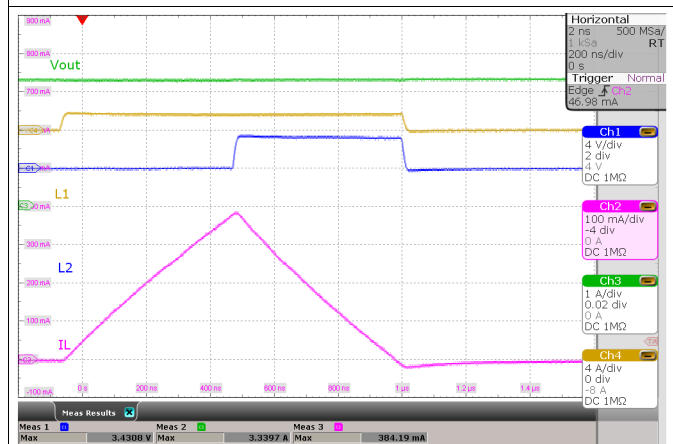


Figure 22. Switching Waveforms, PFM Boost Operation

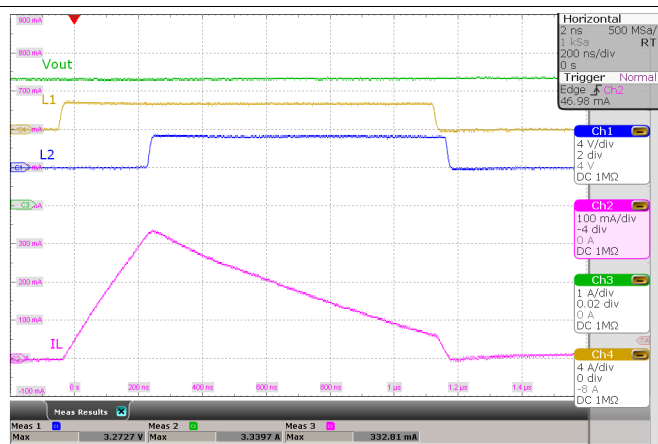
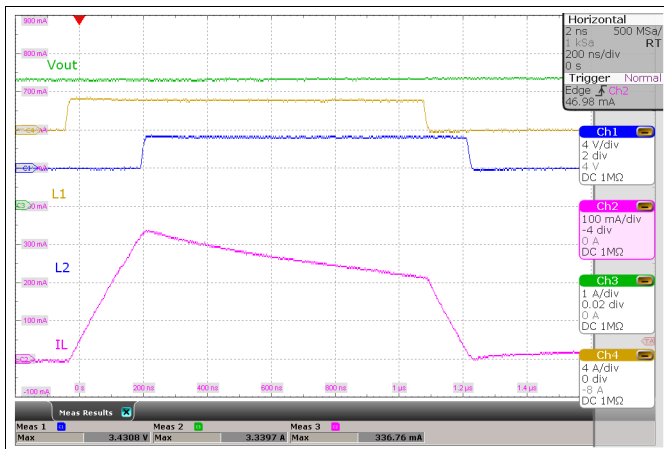


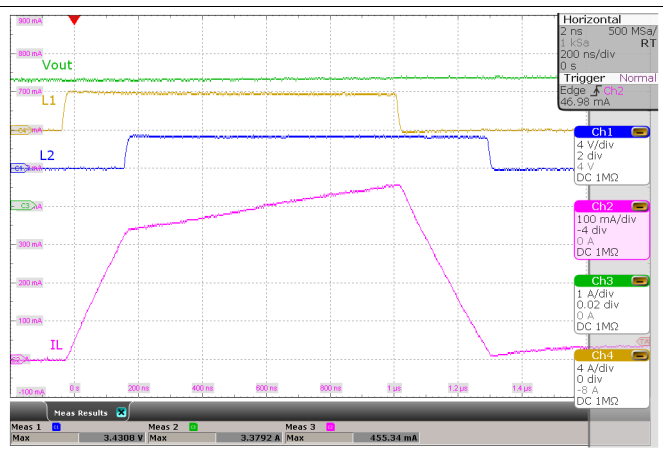
Figure 23. Switching Waveforms, PFM Buck-Boost Operation

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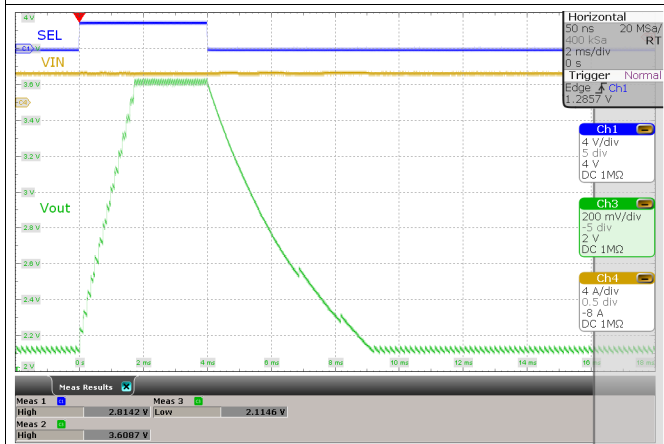
$V_I = 3.3 \text{ V}$, $V_O = 3.3 \text{ V}$ No load

Figure 24. Switching Waveforms, PFM Buck Operation



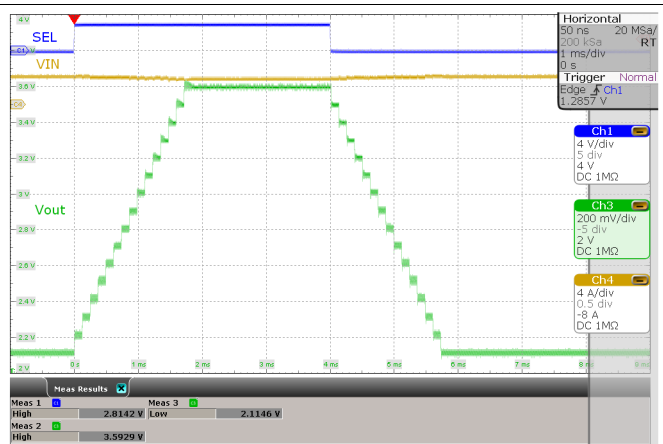
$V_I = 4.0 \text{ V}$, $V_O = 3.3 \text{ V}$ No load

Figure 25. Switching Waveforms, PWM Boost Operation



$V_I = 3.3 \text{ V}$, $V_{O(1)} = 2.2 \text{ V}$, $V_{O(2)} = 3.6 \text{ V}$ 1-k Ω resistive load

Figure 26. DVS Behavior at Light Load



$V_I = 3.3 \text{ V}$, $V_{O(1)} = 2.2 \text{ V}$, $V_{O(2)} = 3.6 \text{ V}$ 30- Ω resistive load

Figure 27. DVS Behavior at High Load

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9 Power Supply Recommendations

The TPS63900 device is designed to operate with input supplies from 1.8 V to 5.5 V. The input supply must be stable and free of noise to achieve the full performance of the device. If the input supply is located more than a few centimeters away from the device, additional bulk capacitance can be required. The input capacitance shown in the application schematics in this data sheet is sufficient for typical applications.

10 Layout

10.1 Layout Guidelines

PCB layout is an important part of any switching power supply design. A poor layout can cause unstable operation, load regulation problems, increased ripple and noise, and EMI issues.

The following PCB layout design guidelines are recommended:

- Place the input and output capacitors close to the device.
- Minimize the area of the input loop, and use short, wide traces on the top layer to connect the input capacitor to the VIN and GND pins.
- Minimize the area of the output loop, and use short, wide traces on the top layer to connect the output capacitor to the VOUT and GND pins.
- The location of the inductor on the PCB is less important than the location of the input and output capacitors. Place the inductor after the input and output capacitors have been placed close to the device. You can route the traces to the inductor on an inner layer if necessary.

10.2 Layout Example

Figure 28 shows an example of a PCB layout that follows the recommendations of the previous section.

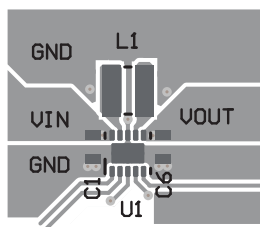


Figure 28. PCB Layout Example

11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

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11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

Texas Instruments, [TPS63900 EVM User Guide](#)

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Support Resources

TI E2E™ [support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

11.5 Trademarks

E2E is a trademark of Texas Instruments.

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11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

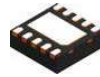
11.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

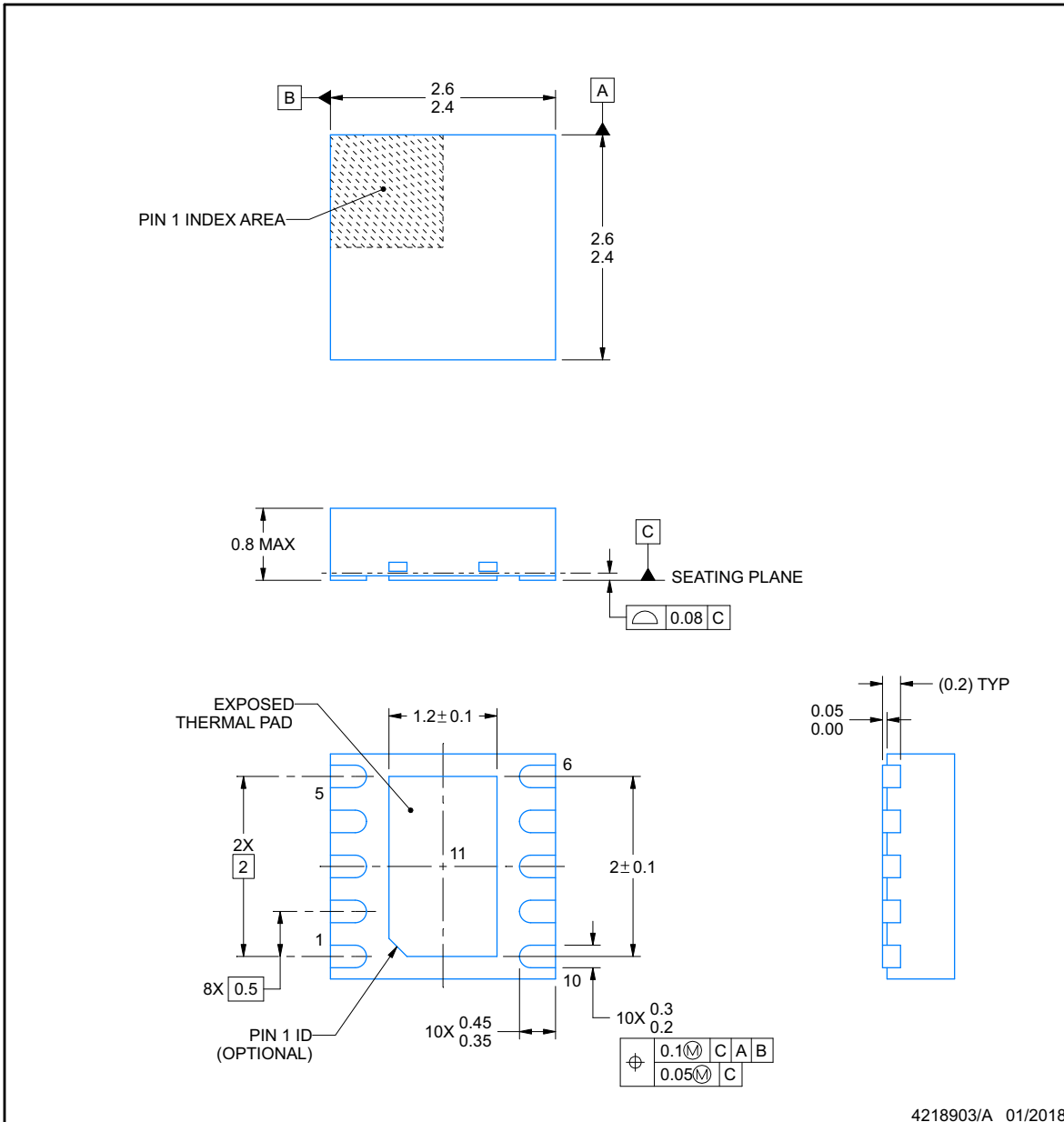


PACKAGE OUTLINE

DSK0010A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

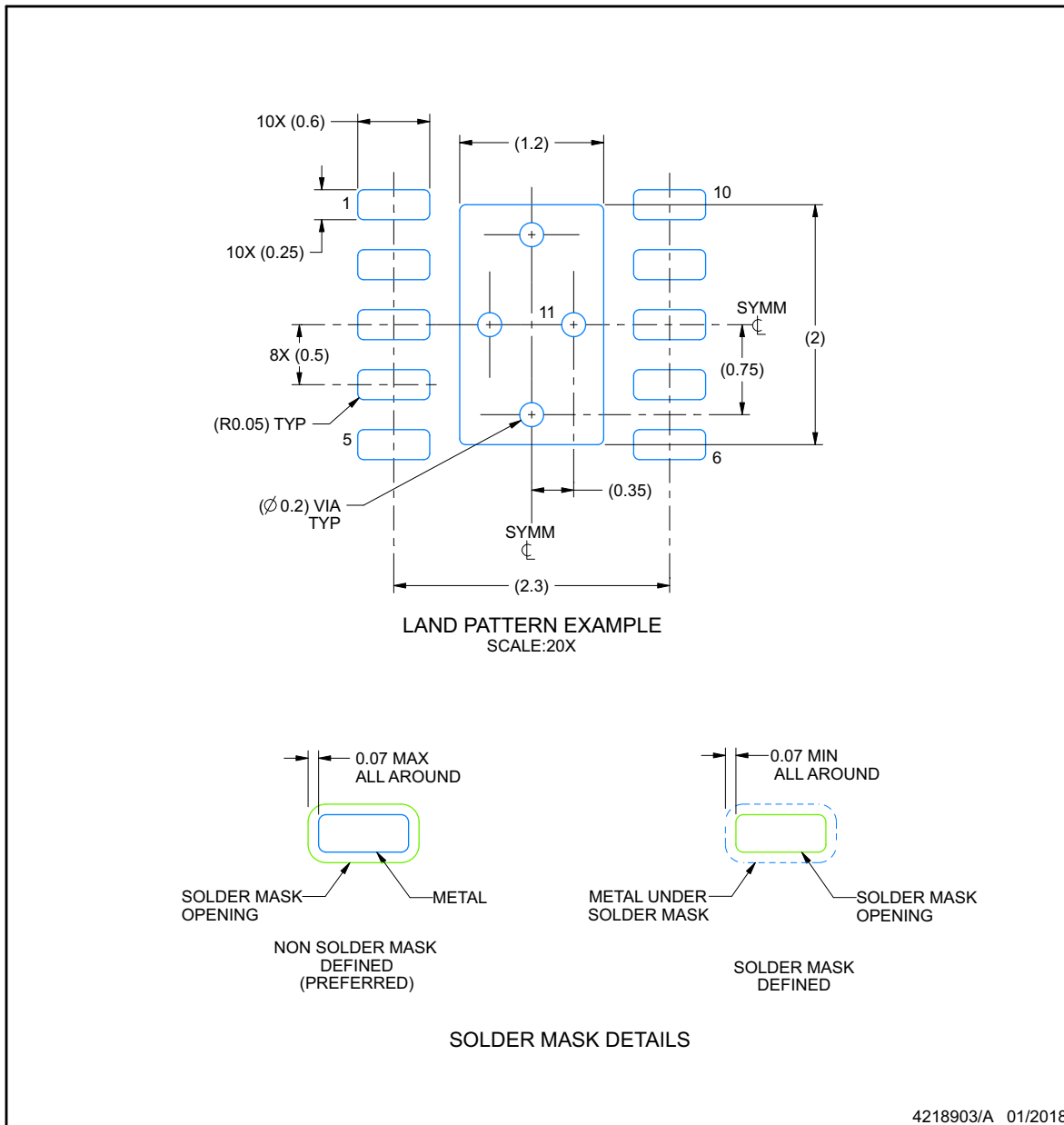
ADVANCE INFORMATION

EXAMPLE BOARD LAYOUT

DSK0010A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- Vias are optional depending on application, refer to device data sheet. If some or all are implemented, recommended via locations are shown.

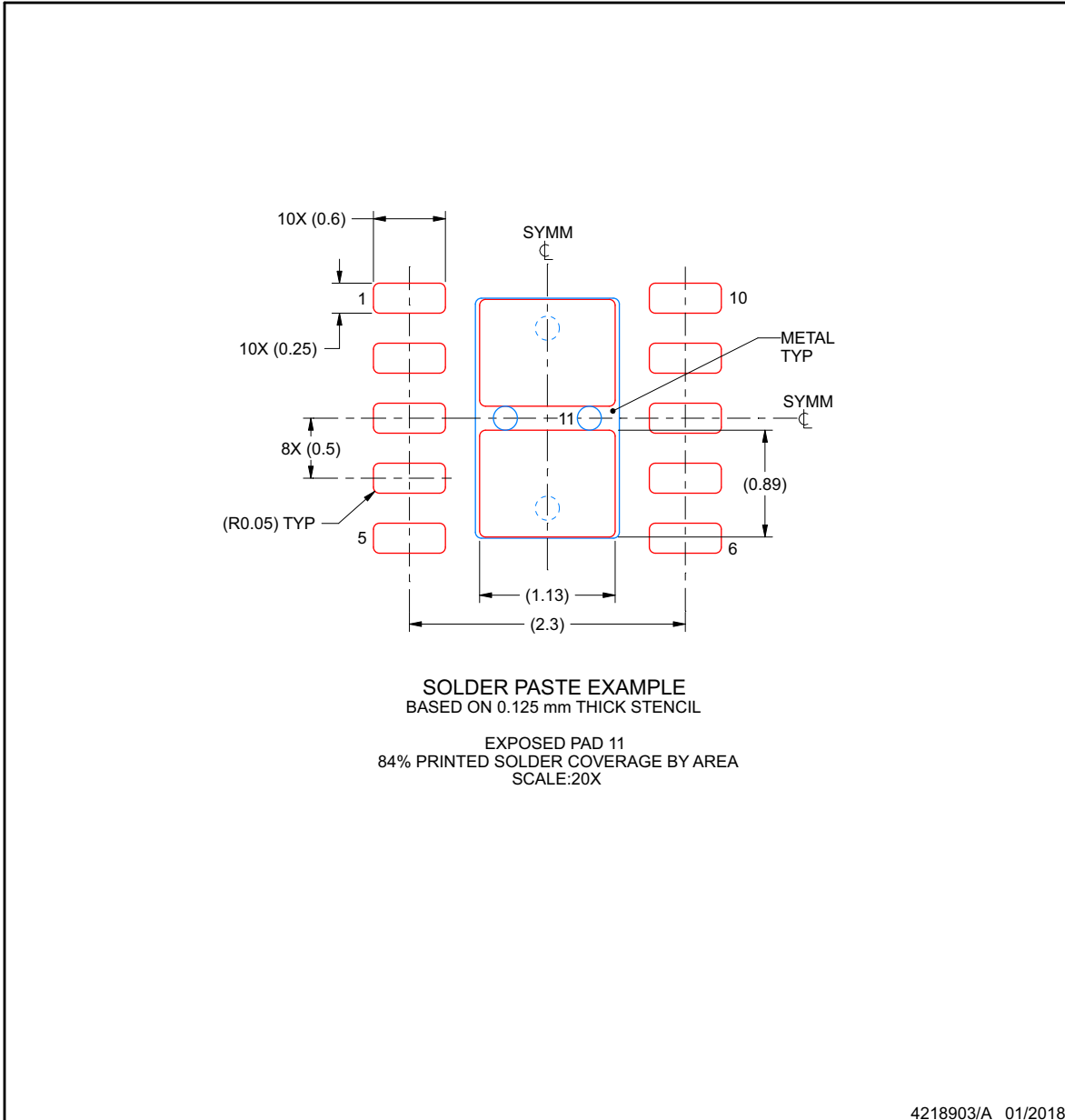
ADVANCE INFORMATION

EXAMPLE STENCIL DESIGN

DSK0010A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

- 6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

ADVANCE INFORMATION

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS63900DSKR	PREVIEW	SON	DSK	10	3000	TBD	Call TI	Call TI	-40 to 85		
TPS63900DSKT	PREVIEW	SON	DSK	10	250	TBD	Call TI	Call TI	-40 to 85		
XPS63900DSKT	ACTIVE	SON	DSK	10	250	TBD	Call TI	Call TI	-40 to 85		Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBsolete: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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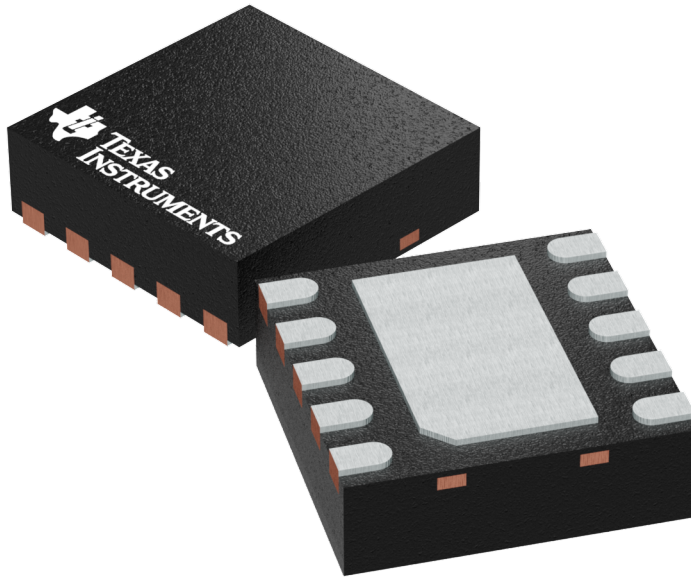
GENERIC PACKAGE VIEW

DSK 10

WSON - 0.8 mm max height

2.5 x 2.5 mm, 0.5 mm pitch

PLASTIC SMALL OUTLINE - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4225304/A

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