AEAT-6010/6012 Magnetic Encoder

10 or 12 bit Angular Detection Device

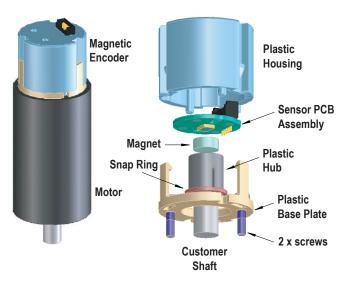


Data Sheet

Description

Avago Technologies' AEAT-60xx series of magnetic encoders provides an integrated solution for angular detection. With ease of use in mind, these magnetic encoders are ideal for angular detection within 360°. Based on magnetic technologies, the device is noncontact and ensures reliable operations. It is able to provide absolute angle detection upon power-up, with a resolution of 0.0879°(12 bits version) or 0.35°(10bits version), which is equivalent to 4096 and 1024 positions per revolution respectively. The positional data is provided in serial bit stream. There is no upper speed limit; the only restriction is that there will be fewer samples per revolution as the speed increases.

Exploded View



Features

- 10 or 12 bits resolution
- Contactless sensing technologies
- Wide temperature range from -40° to 125°C
- Absolute angular position detection
- Synchronous serial interface (SSI) output for absolute position data (binary format)
- Code monotony error = ± 1 LSB
- Single 5V supply
- Easy Assembly, No Signal Adjustment required
- Direct Connectivity through PCB
- RoHS compliant

Applications

- Flow meter
- Angular detection
- Knob control
- Rotary encoder

Device Selection Guide [1]

Part Number	Resolution (bit)	Operating Temperature (°C)	Output Communication	DC Supply Voltage (V), V _{DD}
AEAT-6012	12	-40 to +125	Serial	+5.0
AEAT-6010	10	-40 to +125	Serial	+5.0

Notes:

Table 1. Absolute Maximum Ratings [1, 2]

Parameter	Symbol	Limits	Units	Notes	
DC Supply Voltage at pin $V_{DD} = 5V$	V_{DD}	-0.3 to + 7	V		
Input Voltage	Vi	-0.3 to VDD+0.3	V		
Storage Temperature T _{STG}		-40 to 125	°C		

Notes:

Table 2. Recommended Operating Condition

Parameter	Symbol	Values	Units	Notes	
DC Supply Voltage at pin $V_{DD} = 5V$	V_{DD}	+4.5 / +5.5	V		
Ambient Temperature	T _{amb}	-40 to +125	°C		
Maximum Read-out Frequency	f _{CLK}	≤1	MHz	>0 MHz	

Table 3. DC Characteristics

DC Characteristics over Recommended Operating Range, typical at 25 °C

				Values			
Parameter	Symbol	Condition	Min	Тур.	Max	Units	Notes
VDD Supply Current	I _{DD}			16	20	mA	
Output High Voltage D0	V_{OH}		V _{DD} -0.5			V	
Output Low Voltage DO	V_{OL}				$V_{SS}+0.4$	V	
Output Current DO	I ₀				4	mA	V_{DD} pin = 4.5V
Input High Voltage CLK, CSn	V _{IH}		0.7*V _{DD}				1
Input Low Voltage CLK, CSn	V _{IL}				0.3*V _{DD}		

Notes

1. CSn is internal pull-up.

^{1.} For other options of Magnetic Encoder, please refer to factory.

^{1.} Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

^{2.} Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Table 4. Timing Characteristics

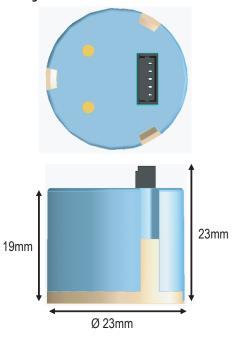
Timing Characteristics over Recommended Operating Range, typical at 25 °C

				Values			
Parameter	Symbol	Condition	Min	Тур.	Max	Units	Notes
Data output activated (logic high)	T _{DO active}				100	ns	2
First data shifted to output register	t _{CLK FE}		500			ns	3
Start of data output	T _{CLK/2}		500			ns	4
Data output valid	T _{DO valid}				375	ns	5
Data output tristate	T _{DO tristate}				100	ns	6
Pulse width of CSn	T _{CSn}		500			ns	7
Sampling rate for absolute output	f_{abs}		9.9	10.42	10.94	kHz	8

Notes:

- 2. Time between falling edge of CSn and data output activated
- 3. Time between falling edge of CSn and first falling edge of CLK
- 4. Rising edge of CLK shifts out one bit a time
- 5. Time between rising edge of CLK and data output valid
- 6. After the last bit DO changes back to "tristate"
- 7. CSn=high; To initiate read-out of next angular position
- 8. Internal sampling rate.

Package Dimensions



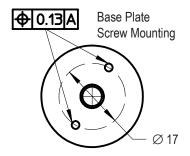


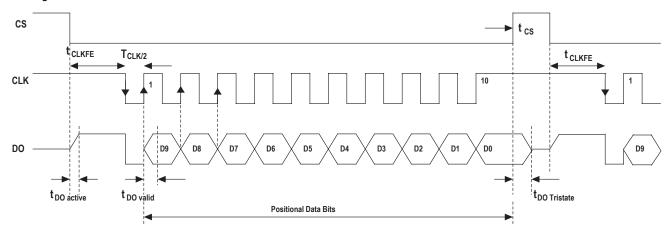
Figure 1. Package and recommended mounting dimension

Parameters

No.	Parameter	Value
1	Operating Temp(°C)	- 40 to +125
2	Shaft axial play (mm)	± 0.08
3	Shaft TIR (mm)	0.05
4	Mechanical speed (rpm)	12,000
5	Shaft diameter (mm)	6+0/-0.01
6	Moment inertia (g-cm^2)	0.104
7	Shaft length — (mm)	8.5 ±1.0
8	Mounting screw size (mm)	M2 x 0.4 x 4 (socket head cap screw, head \emptyset 3.8 \pm 0.18 mm)
9	Recommended screw torque	0.6 lb.inch
10	Encoder base plate thickness (mm)	2
11	Bolt circle	± 0.13

^{*} Note:- For high temperature application, it is highly recommended that adhesive be applied at least to the screw and the base plate interface. Refer Application Note for further details.

Timing Characteristics

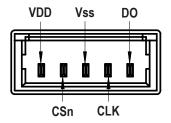


Notes:

- 1. Please refer to Table 4 for Timing Characteristics.
- 2. For 12 bits version; the Positional Data Bits will start with D11 instead and end at D0.

Figure 2. Timing Diagram for 10 bit Magnetic Encoder

Electrical Connections



Pin	Symbol	Description
1	VDD	5V Supply Voltage
2	CSn	Chip Select — Input (See Figure 2)
3	VSS	Supply Ground
4	CLK	Serial Clock - Input (See Figure 2)
5	DO	Serial Data - Output. (See Figure 2)

Figure 3. Electrical Connections

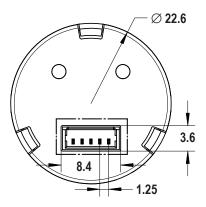


Figure 4. Basic connector dimensions

For product information and a complete list of distributors, please go to our web site: **www.avagotech.com**

