Compact Intelligent Power Module Based Motor Evaluation Board with Interleaved Power Factor Correction

This User Guides refers to revision 0.4 of the SECO-1KW-MCTRL-GEVB evaluation board.

Description

This user guide provides practical guidelines for compact Intelligent Power Module (IPM) evaluation board with interleaved power factor Correction (PFC) SECO–1KW–MCTRL–GEVB including its main features and key data. The evaluation board is a complex solution which allows to control different types of motors (AC induction motor, PMSM, BLDC) by using various control algorithms implemented to microcontroller which can be connected via Arduino Due headers. The board was developed to support customers during their first steps designing application with IPM and PFC.

The design was tested as described in this document but not qualified regarding safety requirements or manufacturing and operation over the whole operating temperature range or lifetime. The board is intended for functional testing under laboratory conditions and by trained specialists only.

Collateral

- <u>SECO-1KW-MCTRL-GEVB</u>
- NFAQ1060L36T
- NCP1632
- FCPF125N65S3
- NCP1063
- NCS2003
- NCS2250



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EVAL BOARD USER'S MANUAL



Features

- 850 W complete motor control solution with AC mains supply 230 Vrms ±15 %, EMI filter, 2–channel interleaved Power Factor Correction (PFC)
- Highly integrated power module NFAQ1060L36T containing an inverter power stage for a high voltage 3-phase inverter in a DIP-S3 package
- PFC stage using NCP1632 controller, FCPF125N65S3 NMOS power transistors and FFSPF1065A diodes
- DC/DC converter producing auxiliary power supply 15VDC – non–isolated buck converter using NCP1063
- 3 phase current measurement using 3xNCS2003 operational amplifier
- Over current protection using NCS2250 comparator



Attention: The SECO-1 kW-MCTRL-GEVB is powered by AC Mains, and exposed to high voltage. Only trained personnel should manipulate and operate on the system. Ensure that all boards are properly connected before powering, and that power is off before disconnecting any boards. It is mandatory to read the Safety Precautions section before manipulating the board. Failure to comply with the described safety precautions may result in personal injury or death, or equipment damage.

Overview

The block diagram of the whole system is represented in Figure 1. The picture of the real board is in the Figure 2 and Figure 3.

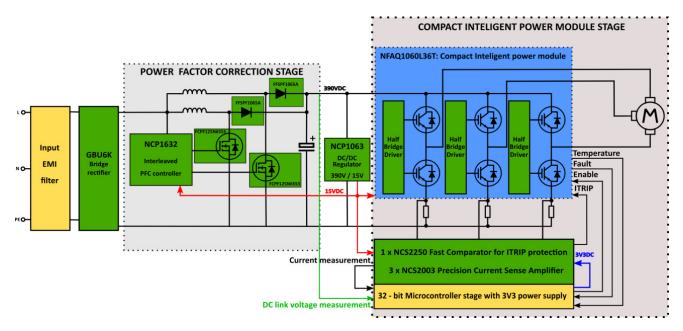


Figure 1. Block Diagram of the Evaluation Board

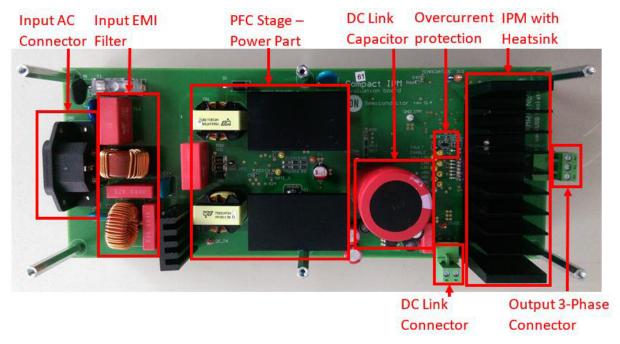
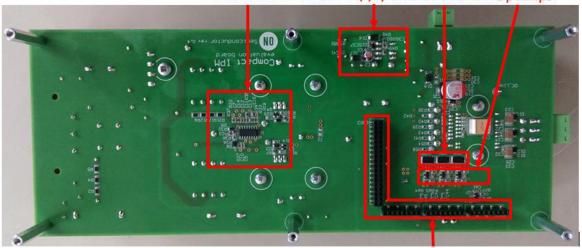


Figure 2. Picture of the Evaluation Board - Top Side

PFC Stage – 15V Auxiliary Current Sense Current Sense Control Part Power Supply Shunt Resistors Op Amps



Headers for Control Board with Microcontroller and 3V3 Power Supply

Figure 3. Picture of the Evaluation Board – Bottom Side

PREREQUISITES

Hardware

- SECO-1 kW-MCTRL-GEVB
- AC power cord one–phase
- Arduino DUE (compatible header) or other controller board with MCU

• USB isolator (5 kV optical isolation)

Software

- Downloadable GUI
- Binary file

SPECIFICATION

The specification and main features can be seen in the Table 1.

Table 1. EVALUATION BOARD SPECIFICATIONS

| Parameters | Values | Conditions/comments |
|---|---------------------------|--|
| INPUT | | |
| Voltage | 230 V _{rms} ±15% | |
| OUTPUT | | |
| Power | 850 W | Input 230 V _{AC} , f _{PWM} = 16 kHz, T _A = 25°C |
| Current per IPM leg | ±5 A _{rms} | $T_{C} = 100^{\circ}C$ |
| DC BUS Voltage | 390 V | Higher voltage value is created by interleaved PFC with NCP1632 working as a booster |
| CURRENT FEEDBACK | | |
| Current sensing resistors | 39 mΩ | |
| Op Amp power supply | 3.3 V | |
| Set Op Amp gain | 5 | |
| Set output offset | 1.65 V | Because of negative current measurement |
| Overcurrent protection | 9 A _{peak} | Configured by shunt resistors and comparator threshold (voltage divider) |
| AUXILIARY POWER SUPPLY | | |
| 15 V | 4.6 W | Used NCP1063 |
| CONTROL | | |
| Board with Microcontroller and 3V3 power supply | | Arduino DUE headers |
| Type of control | | V/f, Field Oriented Control (Sensor–less) |
| Supported type of motors | | ACIM, PMSM, BLDC |
| APPLICATION | | |
| White goods (washers), Industrial fans, Industrial au | tomation | |

SAFETY PRECAUTIONS

It is mandatory to read the following precautions before manipulating the SECO-1KW-MCTRL-GEVB.

Table 2.

| SECO-1KW-MCTRL-GEVB | | | | | |
|---------------------|---|--|--|--|--|
| <u>.</u> | The ground potential of the system is biased to a negative DC bus voltage potential. When measuring voltage waveform by oscilloscope, the scope's ground needs to be isolated. Failure to do so may result in personal injury or death | | | | |
| <u> </u> | The ground potential of the system is NOT biased to an earth (PE) potential. When connecting the MCU board via USB to the computer, the appropriate galvanically isolated USB isolator have to be used. The recommended isolation voltage of USB isolator is 5 kV | | | | |
| <u>.</u> | SECO-1KW-MCTRL-GEVB system contains DC bus capacitors which take time to discharge after removal of the main supply. Before working on the drive system, wait ten minutes for capacitors to discharge to safe voltage levels. Failure to do so may result in personal injury or death. | | | | |
| <u>.</u> | Only personnel familiar with the drive and associated machinery should plan or implement the installation, start-up and subsequent maintenance of the system. Failure to comply may result in personal injury and/or equipment damage. | | | | |
| <u>.</u> | The surfaces of the drive may become hot, which may cause injury. | | | | |
| <u>.</u> | SECO-1KW-MCTRL-GEVB system contains parts and assemblies sensitive to Electrostatic Discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to applicable ESD protection handbooks and guidelines. | | | | |
| <u>.</u> | A drive, incorrectly applied or installed, can result in component damage or reduction in product lifetime. Wiring or application errors such as under sizing the motor, supplying an incorrect or inadequate AC supply or excessive ambient temperatures may result in system malfunction. | | | | |
| <u>.</u> | Remove and lock out power from the drive before you disconnect or reconnect wires or perform service. Wait ten minutes after removing power to discharge the bus capacitors. Do not attempt to service the drive until the bus capacitors have discharged to zero. Failure to do so may result in personal injury or death. | | | | |
| <u>.</u> | SECO-1KW-MCTRL-GEVB system is shipped with packing materials that need to be removed prior to installation. Failure to remove all packing materials which are unnecessary for system installation may result in overheating or abnormal operating condition. | | | | |

SCHEMATICS AND LAYOUT

To meet customer requirements and make the evaluation board a basis for development, all necessary technical data like schematics, layout and components are included in this chapter. Also simple measurements were done to show the functionality of individual stages.

Input EMI Filter

Figure 4 depicts schematic from AC input to rectifier input. This circuitry include a passive EMI filter consisting of elements C16, L5, CY1, CY3, CY4, C51, L4 and C17.

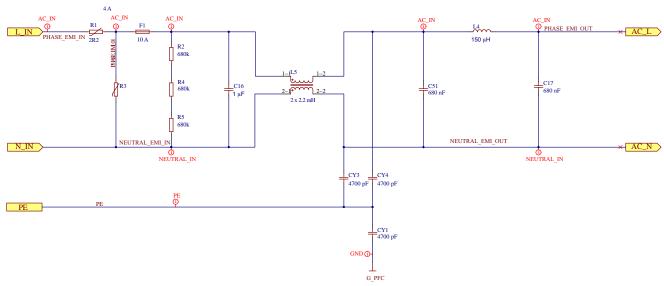


Figure 4. Schematic of EMI filter

Interleaved PFC Stage

In higher power applications to utilize full capacity power of mains and reduce harmonics is PFC–regulators generally required. This high power application use interleaved PFC stages, where may reduce inductor size, input and output capacitors ripple current. In overall, power components are smaller include capacitors. The NCP1632 as voltage mode IC for interleaved PFC applications used in conduction

critical mode. It drives two mosfets 180° phase shifted. The most important at design should be focused significant inductance value of selected PFC coils. It significantly specifies working range.

Figure 5 depicts schematic from rectifier input to DC link output. Activation of stage (connection to 15 V DC power supply) is via J2 (soldered pads).

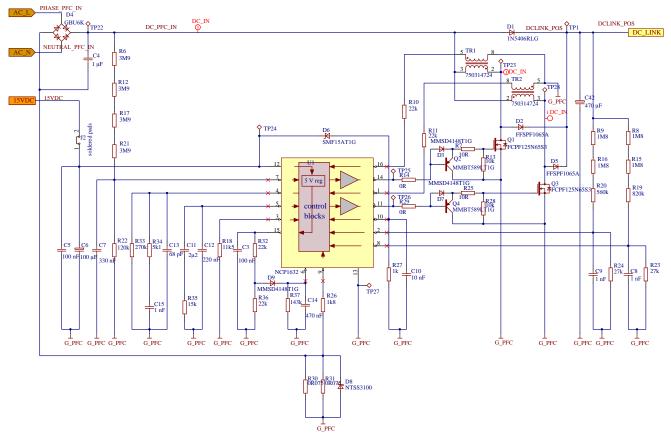


Figure 5. Schematic of interleaved PFC stage

Basic tests and measurements were done. The results of efficiency, power factor, power losses, load transients and

startup can be seen in the Figures 6–12. The used load was Halogen light bulb.

Efficiency PFC stage

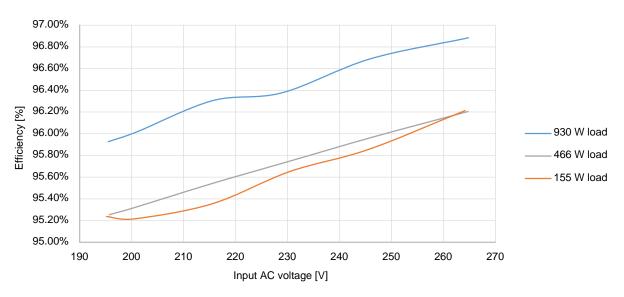


Figure 6. Efficiency of PFC Stage for Various Value of Input AC Voltage and Load

Power factor PFC stage

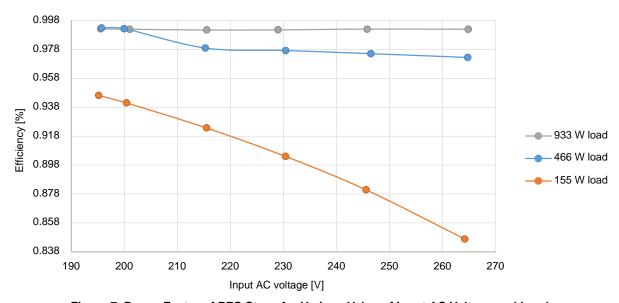


Figure 7. Power Factor of PFC Stage for Various Value of Input AC Voltage and Load

Power factor PFC stage

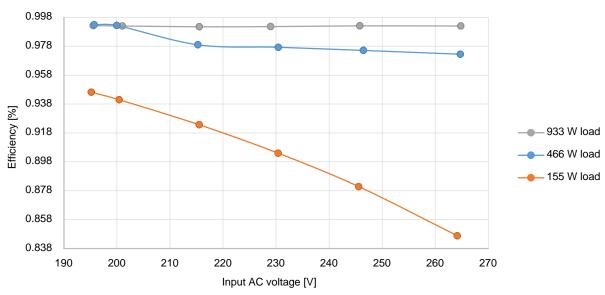


Figure 8. Power Losses of PFC Stage for Various Value of Input AC Voltage and Load

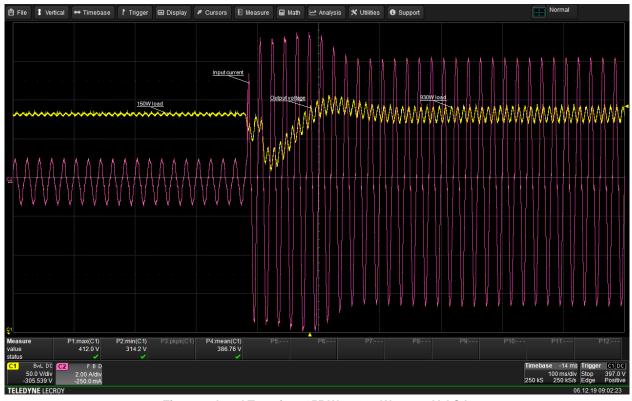


Figure 9. Load Transient 155 W to 930 W at 230 V AC Input



Figure 10. Load Transient 930 W to 155 W at 230 V AC Input



Figure 11. Start up to Open Circuit, 155 W and 930 W at 230 V AC Input

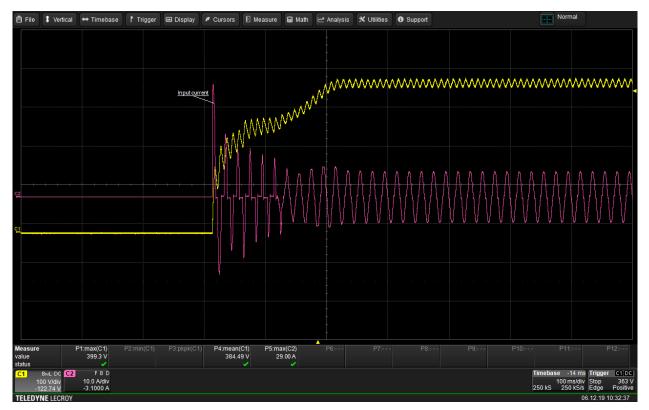


Figure 12. Start to 930 W at 230 V AC Input, Inrush Current

Auxiliary 15 V Power Supply

The NCP1063 is used as converter 390 V to 15 V output to supply PFC, IPM and Control board (Arduino Due). The maximal power delivered is up to 4.6 W. Figure 13 depicts

schematic of 15 V auxiliary power supply. Figure 14 shows startup of the converter.

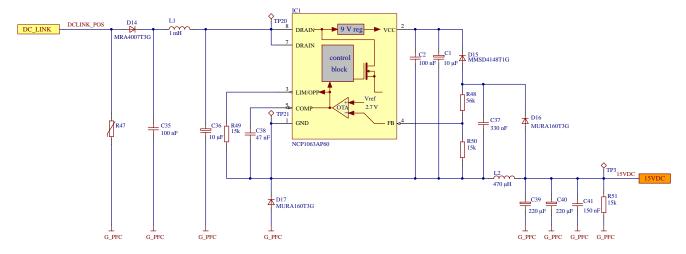


Figure 13. Schematic of Auxiliary 15V Power Supply

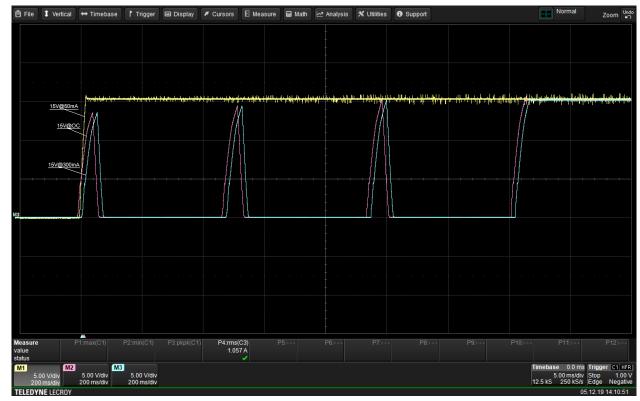


Figure 14. Start Up to Open Circuit, to 50 mA and to 300 mA at 390 V DC Input

IPM Stage

This stage uses NFAQ1060L36T IPM for 3-phase motor drives containing three-phase inverter, gate drivers for the inverter and a thermistor. It uses ON Semiconductor's Insulated Metal Substrate (IMS) Technology. Very important function is over-current protection which is deeply described in chapter – Current Measurement and Over-Current Protection. Module also contains fault pin

which is keeping high level during normal state. Activation of IPM stage (connection to 15 V DC power supply) is via J1 (soldered pads). In the figure 15 is shown schematics of IPM stage also with DC link voltage measurement (voltage divider containing R46, R52, R53 and R55). Signals from 39 m Ω shunt resistors are going to current measurement and over–current protection circuits.

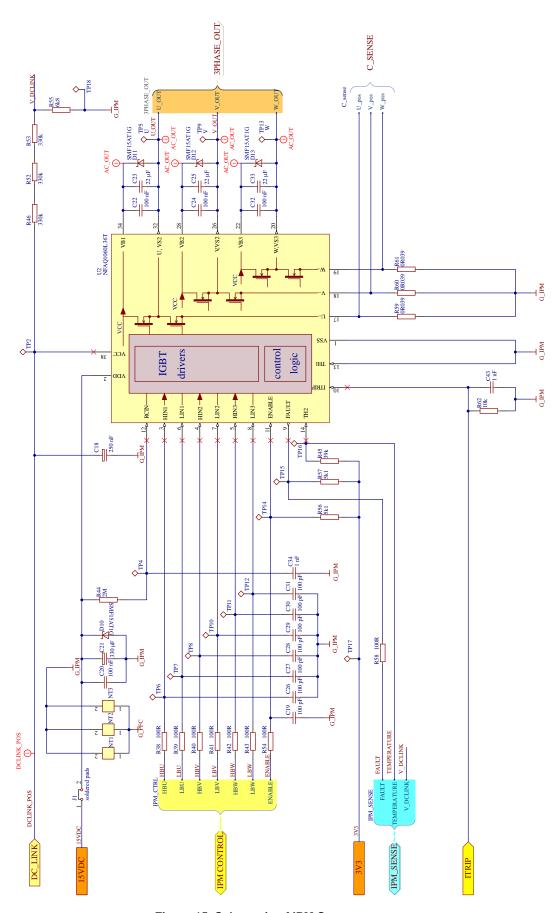


Figure 15. Schematic of IPM Stage

Current Measurement and Over-Current Protection

Schematic of current measurement and over–current protection can be seen in the Figure 16. Information about currents is provided via 39 m Ω shunt resistors. Voltage drop from shunt resistor is going to input of operational amplifier (op–amp) NCS2003 which gain is set to 4.99 with 1k resistor and 4k99 resistor connected as negative feedback. U7 (TLV431) is creating 1.65 V reference which is connected to non–inverting input of op–amps. This connection provides voltage offset at the output of op–amps, which is needed for negative current measurement.

Overcurrent protection is offered by NCS2250 comparator. Comparator threshold is set by voltage divider which consists of R68, R71 and C48. Signals from shunt resistors are going via R78, R81 and R84 connected to non–inverting input. These resistors together with C58 are also acting as low pass filter for high frequency signals interference. On the one hand, with insufficient filtering the over– current protection can react for lower values of current even if there is 350 ns blanking time on ITRIP pin of IPM to improve noise immunity (see datasheet of IPM). On the other hand, when we are designing this filter it is needed to

be careful about the maximal time constant value according short circuit safe operating area (see datasheet of IPM, NFAQ1060L36T– for $V_{CE} = 400 \text{ V}$ is 4 μs). Output from comparator is connected to ITRIP pin of IMP module. As was mentioned in previous chapter, IPM has fault pin and its voltage level is high during normal state. An over-current condition is detected if the voltage on the ITRIP pin is larger than the reference voltage (typically 0.5 V). After a shutdown propagation delay of typically 1.1 µs, the FAULT output is switched on. The FAULT output is held on for a time determined by the resistor and capacitor connected to the RCIN pin (IPM pin 12). If R44 = $2 \text{ M}\Omega$ and C34 = 1 nF, the FAULT output is switched on for 1.65 ms (typical). The over-current protection threshold should be set to be equal or lower to 2 times the module rated current. The reaction of the protection can be seen in the Figure 17 and 18. System is also using ENABLE pin of the IPM. After the over-current fault, fault signal is generated and sent to microcontroller which disable the IPM via ENABLE pin (programmed by user). New operation is possible after microcontroller reset.

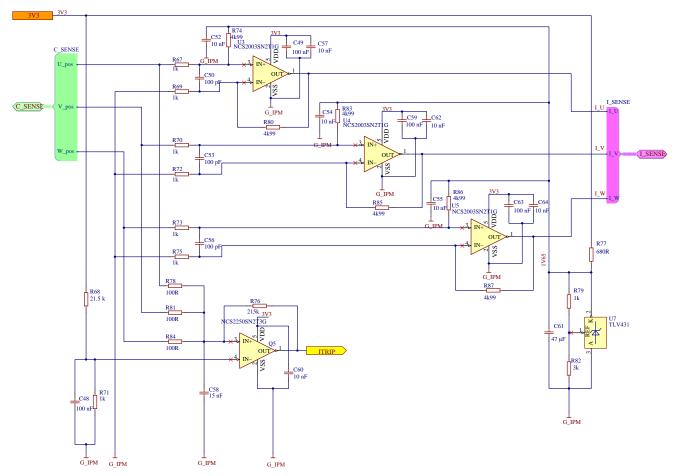


Figure 16. Schematic of Current Measurement and Overcurrent Protection

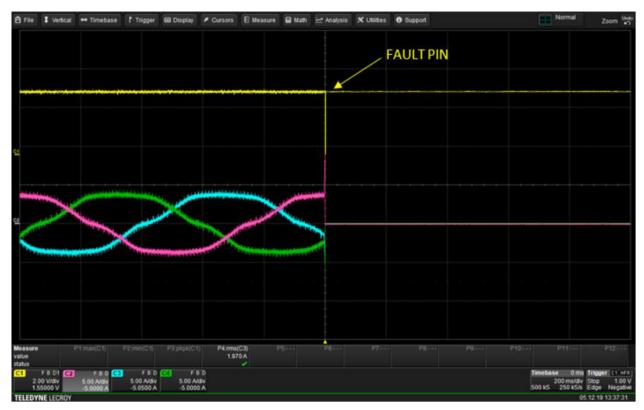


Figure 17. Reaction of Over-current Protection

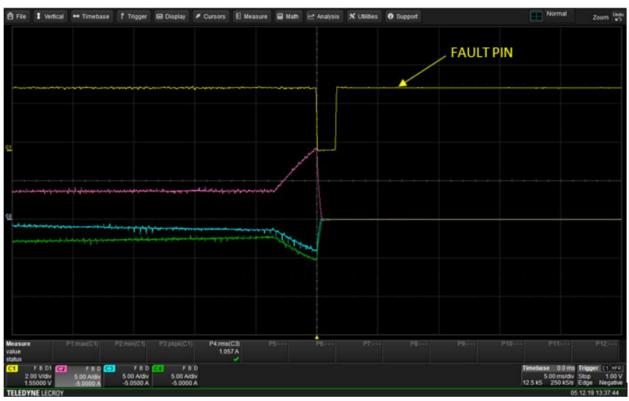


Figure 18. Reaction of Over-current Protection - Detail

Control Board Headers

Schematic of control board headers can be seen in the Figure 19. The headers have Arduino Due footprint. The applied control board has to contain 3V3 power supply as it is also used for supplying current measurement op amps and

comparator for over-current protection. Low pass filters for current and voltage measurement signals are placed closed to the headers (see CON4). When connecting the control board to the PC, do not forget to use isolator.

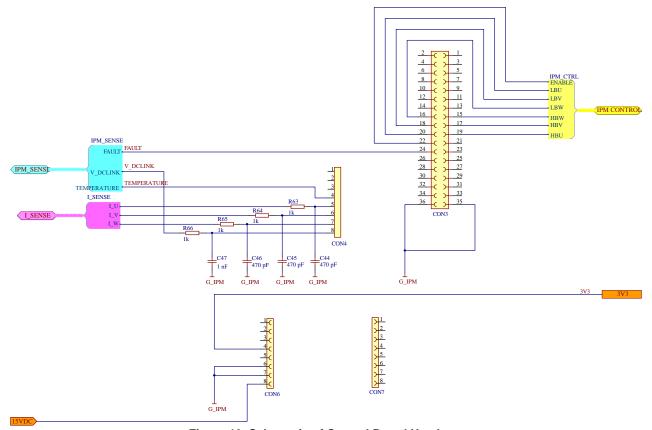


Figure 19. Schematic of Control Board Headers

Layout

Evaluation board consist of 4 layers. Following figures are showing all the layers. Board size is 280x112 mm.

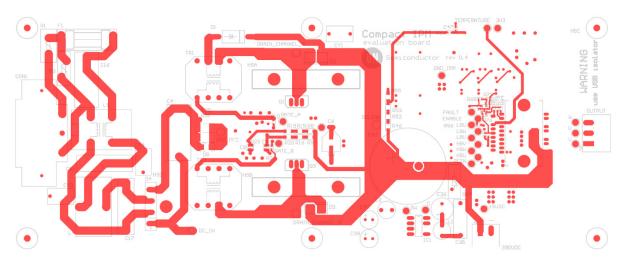


Figure 20. Top Layer Routing and Top Assembly

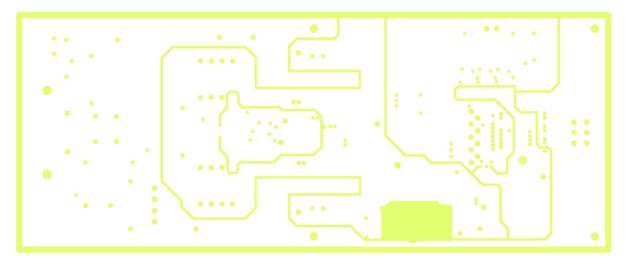


Figure 21. Internal Layer 1

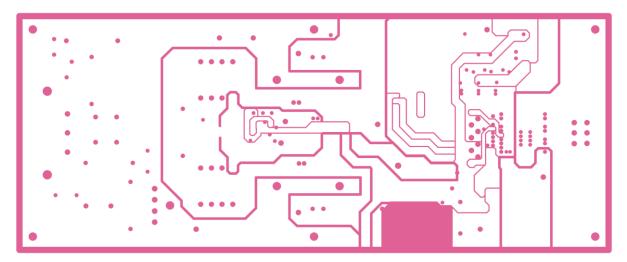


Figure 22. Internal Layer 2

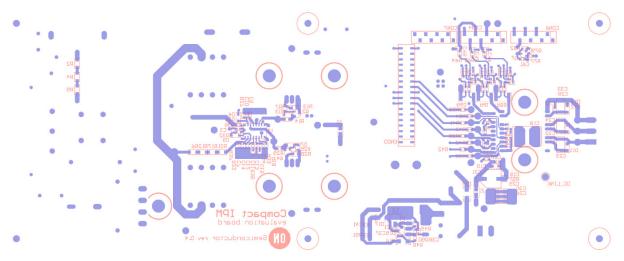


Figure 23. Bottom Layer Routing and Bottom Assembly

Bill of Materials

Table 3 provides bill of materials of the evaluation board.

Table 3. BILL OF MATERIALS OF THE EVALUATION BOARD

| No. | Designator | Comment | Manufacturer | Part number | Quantity |
|-----|---|----------------|-------------------|---------------------|----------|
| 1. | C1 | 10 μF | Würth Electronik | 865080540004 | 1 |
| 2. | C2 | 100 nF | Würth Electronik | 885012206071 | 1 |
| 3. | C3, C5 | 100 nF | Würth Electronik | 885012206095 | 2 |
| 4. | C4, C16 | 1 μF | Würth Electronik | 890334026027CS | 2 |
| 5. | C6 | 100 μF | Würth Electronik | 875115652007 | 1 |
| 6. | C7 | 330 nF | Murata | GRM188R71C334JA01D | 1 |
| 7. | C8, C9 | 1 nF | Würth Electronik | 885012006044 | 2 |
| 8. | C10, C52, C54, C55, C57, C62, C64 | 10 nF | Würth Electronik | 885012206089 | 7 |
| 9. | C11 | 2μ2 | Würth Electronik | 885012206027 | 1 |
| 10. | C12 | 220 nF | Murata | GRM188R71H224KAC4D | 1 |
| 11. | C13 | 68 pF | Murata | GRM1885C1H680JA01D | 1 |
| 12. | C14 | 470 nF | Murata | GRM188R61H474KA12D | 1 |
| 13. | C15 | 1 nF | Würth Electronik | 885012006063 | 1 |
| 14. | C17, C51 | 680 nF | Würth Electronik | 890334026020CS | 2 |
| 15. | C18 | 250 nF | TDK | B58031I9254M062 | 1 |
| 16. | C19, C26, C27, C28, C29, C30, C31, C50, C53, C56 | 100 pF | Würth Electronik | 885012006057 | 10 |
| 17. | C20 | 100 nF | Würth Electronik | 885012207072 | 1 |
| 18. | C21 | 330 μF | Würth Electronik | 875075661010 | 1 |
| 19. | C22, C24, C32 | 100 nF | Würth Electronik | 885012105018 | 3 |
| 20. | C23, C25, C33 | 22 μF | TDK | C4532X7R1E226M250KC | 3 |
| 21. | C34, C43, C47 | 1 nF | Würth Electronik | 885012206083 | 3 |
| 22. | C35 | 100 nF | Würth Electronik | 890334025017CS | 1 |
| 23. | C36 | 10 μF | Rubycon | 450BXF10M10X16 | 1 |
| 24. | C37 | 330 nF | Würth Electronik | 885012207101 | 1 |
| 25. | C38 | 47 nF | Würth Electronik | 885012206093 | 1 |
| 26. | C39, C40 | 220 μF | Würth Electronik | 860040474004 | 2 |
| 27. | C41 | 150 nF | Murata | GRM188R71H154KAC4D | 1 |
| 28. | C42 | 470 μF | Würth Electronik | 861141486024 | 1 |
| 29. | C44, C45, C46 | 470 pF | Würth Electronik | 885012006061 | 3 |
| 30. | C48, C49, C59, C63 | 100 nF | Wurth Electronics | 885012206046 | 4 |
| 31. | C58 | 15 nF | Würth Electronik | 885012206090 | 1 |
| 32. | C60 | 10 nF | Würth Electronik | 885012206065 | 1 |
| 33. | C61 | 47 μF | Murata | GRM188R60J476ME15D | 1 |
| 34. | CON1 | Black | TE Connectivity | 6ESRM-P | 1 |
| 35. | CON2 | Green | Würth Elektronik | 691313710003 | 1 |
| 36. | CON3 | 610 036 218 21 | Würth Elektronik | 61003621821 | 1 |

Table 3. BILL OF MATERIALS OF THE EVALUATION BOARD

| No. | Designator | Comment | Manufacturer | Part number | Quantity |
|-----|---------------------------|----------------------------------|------------------|--------------------|----------|
| 37. | CON4, CON6, CON7 | 610 008 13 321 | Würth Elektronik | 61000813321 | 3 |
| 38. | CON5 | 691 313 510 002 | Würth Elektronik | 691313510002 | 1 |
| 39. | CY1, CY3, CY4 | 4700 pF | Murata | DE1E3KX472MA4BN01F | 3 |
| 40. | D1 | 1N5406RLG | ON Semiconductor | 1N5406RLG | 1 |
| 41. | D2, D5 | FFSPF1065A | ON Semiconductor | FFSPF1065A | 2 |
| 42. | D3, D7, D9, D15 | MMSD4148T1G | ON Semiconductor | MMSD4148T1G | 4 |
| 43. | D4 | GBU6K | ON Semiconductor | GBU6K | 1 |
| 44. | D6, D10, D11, D12, D13 | SMF15AT1G | ON Semiconductor | SMF15AT1G | 5 |
| 45. | D8 | NTSS3100 | ON Semiconductor | NTSS3100T3G | 1 |
| 46. | D14 | MRA4007T3G | ON Semiconductor | MRA4007T3G | 1 |
| 47. | D16, D17 | MURA160T3G | ON Semiconductor | MURA160T3G | 2 |
| 48. | F1 | 10 A | Schurter | 0031.8201 | 1 |
| 49. | F2 | 4 A | Schurter | 0034.3123 | 1 |
| 50. | FC1 | Fuse cover | Schurter | 0853.0551 | 1 |
| 51. | HSA, HSB | SK 489 50 mm black anodized | | | 2 |
| 52. | HSC | SK 92 30 mm natural anodized | | | 1 |
| 53. | HSD | SK 447 37.5 mm black anodized | | | 1 |
| 54. | IC1 | NCP1063AP60 | ON Semiconductor | NCP1063AP60G | 1 |
| 55. | J_AC_OUT | 691 351 500 003 | Würth Elektronik | 691351500003 | 1 |
| 56. | J_DC390V | 691 351 500 002 | Würth Elektronik | 691351500002 | 1 |
| 57. | L1 | 1 mH | Würth Elektronik | 744731102 | 1 |
| 58. | L2 | 470 μΗ | Würth Elektronik | 744731471 | 1 |
| 59. | L4 | 150 μΗ | Würth Elektronik | 7447076 | 1 |
| 60. | L5 | 2 x 2.2 mH | Würth Elektronik | 744824622 | 1 |
| 61. | NAC1, NAC2 | nut M3 ISO4032 | | | 2 |
| 62. | Q1, Q3 | FCPF125N65S3 | ON Semiconductor | FCPF125N65S3 | 2 |
| 63. | Q2, Q4 | MMBT589LT1G | ON Semiconductor | MMBT589LT1G | 2 |
| 64. | Q5 | NCS2250SN2T3G | ON Semiconductor | NCS2250SN2T3G | 1 |
| 65. | R1 | 2R2 | TDK | B57237S0229M000 | 1 |
| 66. | R2, R4, R5 | 680k | Vishay | CRCW1206680KFKEA | 3 |
| 67. | R3, R47 | 320 V | TDK | B72214S0321K101 | 2 |
| 68. | R6, R12, R17, R21 | 3M9 | Vishay | CRCW12063M90FKEA | 4 |
| 69. | R7, R25 | 10R | Panasonic | ERJ6ENF10R0V | 2 |
| 70. | R8, R9, R15, R16 | 1M8 | Vishay | CRCW12061M80FKEA | 4 |
| 71. | R10, R11, R32, R36 | 22k | Panasonic | ERJ3EKF2202V | 4 |
| 72. | R13, R28 | 10k | Panasonic | ERJ6ENF1002V | 2 |
| 73. | R14, R29 | 0R | Panasonic | ERJ6GEY0R00V | 2 |
| 74. | R18 | 11k5 | Panasonic | ERJ3EKF1152V | 1 |

Table 3. BILL OF MATERIALS OF THE EVALUATION BOARD

| No. | Designator | Comment | Manufacturer | Part number | Quantity |
|------|--|----------------------------|--------------------------|--------------------|----------|
| 75. | R19 | 820k | Panasonic | ERJU08F8203V | 1 |
| 76. | R20 | 560k | Panasonic | ERJU08F5603V | 1 |
| 77. | R22 | 120k | Panasonic | ERJ3EKF1203V | 1 |
| 78. | R23, R24 | 27k | Panasonic | ERJ3EKF2702V | 2 |
| 79. | R26 | 1k8 | Panasonic | ERJ3EKF1801V | 1 |
| 80. | R27, R63, R64, R65, R71, R79 | 1k | Panasonic | ERJ3EKF1001V | 6 |
| 81. | R30, R31 | 0R075 | Bourns | CRA2512-FZ-R075ELF | 2 |
| 82. | R33 | 270k | Panasonic | ERJ3EKF2703V | 1 |
| 83. | R34, R56, R57 | 5k1 | Panasonic | ERJ3EKF5101V | 3 |
| 84. | R35, R49, R50, R51 | 15k | Panasonic | ERJ3EKF1502V | 4 |
| 85. | R37 | 143k | Panasonic | ERJ3EKF1433V | 1 |
| 86. | R38, R39, R40, R41, R42, R43, R54, R58, R78, R81, R84 | 100R | Panasonic | ERJ3EKF1000V | 11 |
| 87. | R44 | 2M | Vishay | CRCW06032M00FKEA | 1 |
| 88. | R45 | 39k | Panasonic | ERJ3EKF3902V | 1 |
| 89. | R46, R52, R53 | 330k | Vishay | CRCW1206330KFKEA | 3 |
| 90. | R48 | 56k | Panasonic | ERJ3EKF5602V | 1 |
| 91. | R55 | 6k8 | Panasonic | ERJP08F6801V | 1 |
| 92. | R59, R60, R61 | 0R039 | KOA SPEER ELECTRONICS | TLRH3AWTTE39L0F | 3 |
| 93. | R62 | 10k | Panasonic | ERJ3EKF1002V | 1 |
| 94. | R66, R67, R69, R70, R72, R73, R75 | 1k | Panasonic | ERJ3RBD1001V | 7 |
| 95. | R68 | 21k5 | Panasonic | ERJ3EKF2152V | 1 |
| 96. | R74, R80, R83, R85, R86, R87 | 4k99 | TT Electronics | PCF0603R-4K99BT1 | 6 |
| 97. | R76 | 215k | Panasonic | ERJ3EKF2153V | 1 |
| 98. | R77 | 680R | Panasonic | ERJ3EKF6800V | 1 |
| 99. | R82 | 3k | Panasonic | ERJ3EKF3001V | 1 |
| 100. | SAC1, SAC2, SHA1, SHA2, SHB1, SHB2, SHD1 | M3x8 DIN7985 | | | 7 |
| 101. | SB1, SB2, SB3, SB4, SB5, SB6 | Spacer M3 F/F 50 HEX7 | | | 6 |
| 102. | SDA, SDB, SDD, SHC1, SHC2, SQA, SQB | M3x16 DIN7985 | | | 7 |
| 103. | SHSA1, SHSA2, SHSB1, SHSB2 | spacer for M3 | Wurth Elektronik | 963030042 | 4 |
| 104. | ST1, ST2, ST3, ST4, ST5, ST6 | Spacer M3 M/F 6/30 HEX7 | | | 6 |
| 105. | TP1, TP2 | RED | Keystone Electronics | 5005 | 2 |

Table 3. BILL OF MATERIALS OF THE EVALUATION BOARD

| No. | Designator | Comment | Manufacturer | Part number | Quantity |
|------|---|-----------------------------|-------------------------|---------------|----------|
| 106. | TP3, TP17, TP24 | ORANGE | Keystone Electronics | 5008 | 3 |
| 107. | TP4, TP18, TP21 | WHITE | Keystone Electronics | 5007 | 3 |
| 108. | TP5, TP9, TP13, TP22 | BROWN | Keystone Electronics | 5120 | 4 |
| 109. | TP6, TP7, TP8, TP10, TP11, TP12, TP14, TP25, TP26 | YELLOW | Keystone Electronics | 5009 | 9 |
| 110. | TP15, TP16 | BLUE | Keystone Electronics | 5122 | 2 |
| 111. | TP20, TP23, TP28 | PURPLE | Keystone Electronics | 5124 | 3 |
| 112. | TP27 | BLACK | Keystone Electronics | 5006 | 1 |
| 113. | TR1, TR2 | 750314724 | Würth Elektronik | 750314724 | 2 |
| 114. | U1 | NCP1632 | ON Semiconductor | NCP1632DR2G | 1 |
| 115. | U2 | NFAQ1060L36T | ON Semiconductor | NFAQ1060L36T | 1 |
| 116. | U3, U4, U5 | NCS2003SN2T1G | ON Semiconductor | NCS2003SN2T1G | 3 |
| 117. | U7 | TLV431 | ON Semiconductor | TLV431CSN1T1G | 1 |
| 118. | WAC1, WAC2, WHSA1, WHSA2, WHSB1, WHSB2, WPDA, WPDB, WPDD, WPQA, WPQB, WSHC1, WSHC2, WSHD1 | plain washer M3 DIN125A | | | 14 |
| 119. | WHAD, WHAQ, WHBD, WHBQ | AOS 220 18x12x1.5 D3.1 | | | 4 |
| 120. | WSDA, WSDB, WSDD, WSQA, WSQB | spring washer M3 DIN7980 | | | 5 |

GRAPHICAL USER INTERFACE

For Arduino Due users, simple code for motor V/f control in open loop using Space Vector Modulation is available. It allows to set phase voltage amplitude and frequency. This can be done via graphical user interface (GUI) which is in the Figure 24. Also current of 3 phases can be displayed but

with limited sampling frequency as it is restricted by serial port speed. *During the communication with control board and PC, using of USB isolator is very important because of safety.* In the Figure 25 can be seen evaluation board with USB isolator (5 kV optical isolation).



Figure 24. Evaluation Board with Control Board and USB Isolator

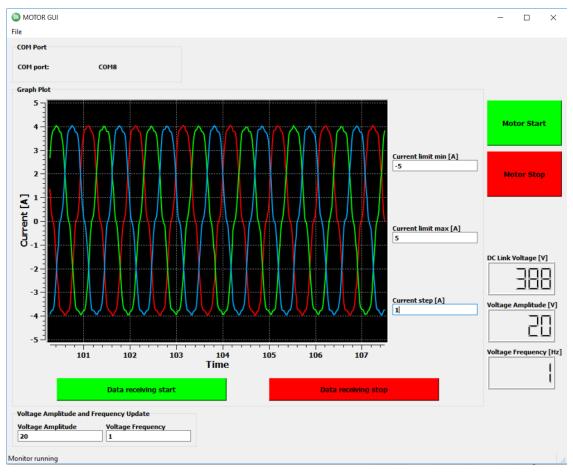


Figure 25. Graphical user Interface for Controlling The motor in the Open Loop

The way how to use GUI:

- 1. Connection to COM port:
- File -> Select COM port
- Choose the COM port
- File -> Start communication
- 2. DC link voltage, phase voltage amplitude, frequency and current measurement:
- Press button data receiving start/stop
- 3. Voltage amplitude and frequency update:
- Write demanded value to relevant box and press
 Enter. If the value is changed correctly, it should be visible also on LCD

- 4. Motor Start/Stop:
- Press Start/Stop button
- After Stop button is pressed, all motor phases are shorted (lower transistors of the IPM are ON, upper are OFF)

REFERENCES

- [1]. Datasheet of IPM NFAQ1060L36T, available on ON Semiconductor website
- [2]. Datasheet of NCP1632, available on ON Semiconductor website
- [3]. Application note Key Steps to Design an Interleaved PFC Stage Driven by the NCP1632, available on ON Semiconductor website
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- [5]. Application note Universal AC Input, 12V 0.35 A Output, 4.2 Watt Non–isolated Power Supply, available on ON Semiconductor website
- [6]. Datasheet of NCS2003, available on ON Semiconductor website
- [7]. Datasheet of NCS2250, available on ON Semiconductor website

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