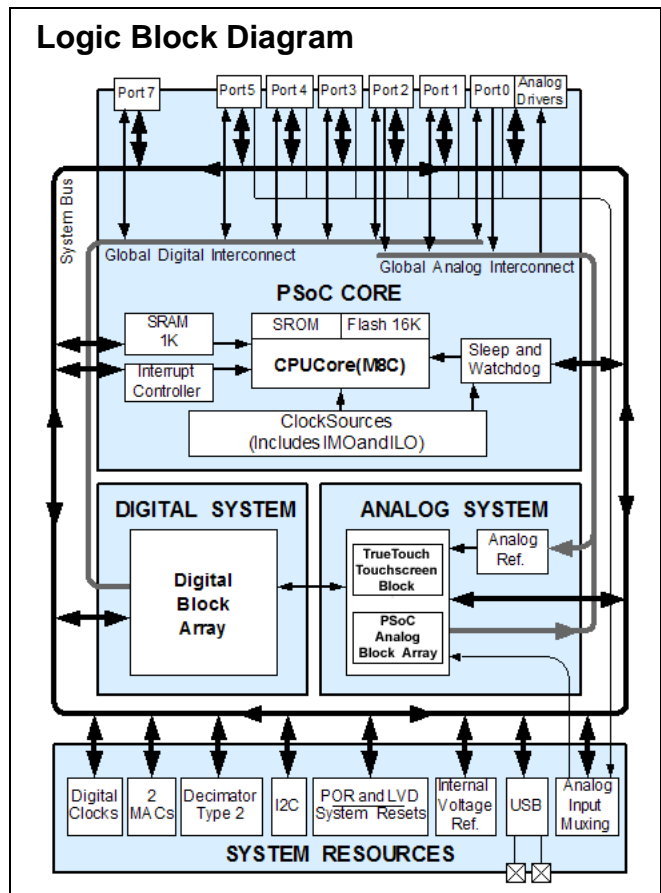


TrueTouch™ Multi-Touch Gesture Touchscreen Controller

Features

- TrueTouch™ Capacitive Touchscreen Controller
 - Supports Single-Touch and Multi-Touch Touchscreen Control
 - Supports up to 44 X/Y Sensor Inputs
 - Supports Screen Sizes 8.4" and Below
 - Supports Screen Sizes 8.4" and Below
 - Fast Scan Rates: Typical 0.5 ms per Sensor
 - High Resolution: Typical 480 x 360 for 3.5" Screen
 - Available in 56-Pin QFN Package
 - Seamless Transition up to Higher Function Multi-Touch All-Point Device
- Lowest Noise TrueTouch Device
- Highly Configurable Sensing Circuitry
 - Allows Maximum Design Flexibility
 - Allows Trade-Off Between Scan Time and Noise Performance
- Includes Gesture Detection Library
- Develop Customized User Defined Gestures
- Provides Maximum EMI Immunity
 - Selectable Spread-Spectrum Clock Source
- Powerful Harvard Architecture Processor
 - M8C Processor Speeds to 24 MHz
 - Two 8x8 Multiply, 32-Bit Accumulate
 - Low Power at High Speed
 - 3V to 5.25V Operating Voltage
 - Industrial Temperature Range: -40°C to +85°C
 - USB Temperature Range: -10°C to +85°C
- Full-Speed USB (12 Mbps)
 - Four Uni-Directional Endpoints
 - One Bi-Directional Control Endpoint
 - USB 2.0 Compliant
 - Dedicated 256 Byte Buffer
 - No External Crystal Required
- Flexible On-Chip Memory
 - 16K Flash Program Storage, 50000 Erase/Write Cycles
 - 1K SRAM Data Storage
 - In-System Serial Programming (ISSP)
 - Partial Flash Updates
 - Flexible Protection Modes
 - EEPROM Emulation in Flash
- Precision, Programmable Clocking
 - Internal ±4% 24 and 48 MHz Oscillator
 - Internal Oscillator for Watchdog and Sleep
 - 0.25% Accuracy for USB with no External Components
- Additional System Resources
 - I²C™ Slave, Master, and Multi-Master to 400 kHz
 - Watchdog and Sleep Timers
 - User-Configurable Low Voltage Detection
 - Integrated Supervisory Circuit
 - On-Chip Precision Voltage Reference
- Complete Development Tools
 - Free Development Software (PSoc Designer™)
 - TrueTouch Touchscreen Tuner
 - Full-Featured, In-Circuit Emulator and Programmer
 - Full Speed Emulation
 - Complex Breakpoint Structure
 - 128K Bytes Trace Memory
- Programmable Pin Configurations
 - 25 mA Sink, 10 mA Drive on All GPIO
 - Pull Up, Pull Down, High Z, Strong, or Open Drain Drive Modes on All GPIO
 - Configurable Interrupt on All GPIO



TrueTouch Functional Overview

The TrueTouch family provides the fastest and most efficient way to develop and tune a capacitive touchscreen application. A TrueTouch device includes the configurable TrueTouch block, configurable analog and digital logic, programmable interconnect, and an 8-bit CPU to run custom firmware. This architecture enables the user to create flexible, customized touchscreen configurations to match the requirements of each individual touchscreen application. Various configurations of Flash program memory, SRAM data memory, and configurable IO are included in a range of convenient pinouts.

The TrueTouch architecture is comprised of four main areas: the Core, Digital System, the TrueTouch Analog System, and System Resources including a full-speed USB port. Configurable global busing allows all the device resources to be combined into a complete custom touchscreen system. The CY8CTMG120 device can have up to seven IO ports that connect to the global digital and analog interconnects, providing access to four digital blocks and six analog blocks. Implementation of touchscreen application allows additional digital and analog resources to be used, depending on the touchscreen design. The CY8CTMG120 is offered in a 56-pin QFN package, with up to 48 general purpose IO (GPIO), and support of up to 44 X/Y sensors.

When designing touchscreen applications, refer to the UM data sheet for performance requirements to meet and detailed design process explanation.

The TrueTouch Core

The core includes a CPU, memory, clocks, and configurable GPIO (General Purpose IO).

The M8C CPU core is a powerful processor with speeds up to 24 MHz, providing a four MIPS 8-bit Harvard architecture microprocessor. The CPU uses an interrupt controller with up to 20 vectors, to simplify programming of real time embedded events. Program execution is timed and protected using the included Sleep and Watch Dog Timers (WDT).

Memory encompasses 16K of Flash for program storage, 1K of SRAM for data storage, and up to 2K of EEPROM emulated using the Flash. Program Flash uses four protection levels on blocks of 64 bytes, allowing customized software IP protection.

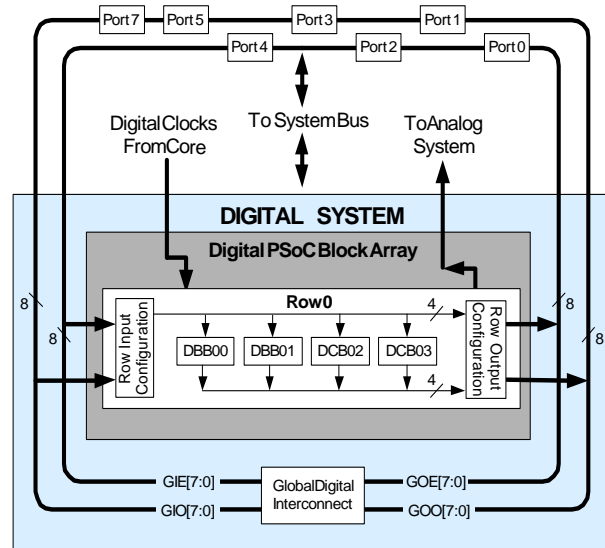
The TrueTouch device incorporates flexible internal clock generators, including a 24 MHz IMO (internal main oscillator) accurate to 8% over temperature and voltage. The 24 MHz IMO can also be doubled to 48 MHz for use by the digital system. A low power 32 kHz ILO (internal low speed oscillator) is provided for the Sleep timer and WDT. The clocks, together with programmable clock dividers (as a System Resource), provide the flexibility to integrate almost any timing requirement into the PSoC device. In USB systems, the IMO self-tunes to ± 0.25% accuracy for USB communication.

The GPIOs provide connection to the CPU, digital and analog resources of the device. Each pin's drive mode may be selected from eight options, allowing great flexibility in external interfacing. Every pin also has the capability to generate a system interrupt on high level, low level, and change from last read.

The Digital System

The Digital System is composed of 4 digital PSoC blocks. Each block is an 8-bit resource that can be used alone or combined with other blocks to form 8, 16, 24, and 32-bit peripherals, which are called user module references.

Figure 1. Digital System Block Diagram



Digital peripheral configurations include those listed below.

- Full-Speed USB (12 Mbps)
- PWMs (8 to 32 bit)
- PWMs with dead band (8 to 24 bit)
- Counters (8 to 32 bit)
- Timers (8 to 32 bit)
- UART 8 bit with selectable parity
- SPI master and slave
- I2C slave and multi-master
- Pseudo random sequence generators (8 to 32 bit)

The digital blocks are connected to any GPIO through a series of global buses that can route any signal to any pin. The buses also allow signal multiplexing and performing logic operations. This configurability frees your designs from the constraints of a fixed peripheral controller.

Digital blocks are provided in rows of four, where the number of blocks varies by TrueTouch device family. This allows optimum choice of system resources for your application. Family characteristics are shown in Table 1 on page 4.

The Analog System

The Analog System is composed of 6 configurable blocks, each comprised of an opamp circuit allowing the creation of complex analog signal flows. Analog peripherals are very flexible and can be customized to support specific application requirements. Some of the more common PSoC analog functions (most available as user modules) are listed below.

- Analog-to-digital converters (up to 2, with 6- to 14-bit resolution, selectable as Incremental, Delta Sigma, and SAR)
- Filters (2 and 4 pole band-pass, low pass, and notch)
- Amplifiers (up to 2, with selectable gain to 48x)
- Instrumentation amplifiers (1 with selectable gain to 93x)
- Comparators (up to 2, with 16 selectable thresholds)
- DACs (up to 2, with 6- to 9-bit resolution)
- Multiplying DACs (up to 2, with 6- to 9-bit resolution)
- High current output drivers (two with 30 mA drive as a PSoC Core Resource)
- 1.3V reference (as a System Resource)
- Modulators
- Correlators
- Peak detectors
- Many other topologies possible

Analog blocks are arranged in a column of three, which includes one CT (Continuous Time) and two SC (Switched Capacitor) blocks, as shown [Figure 2](#).

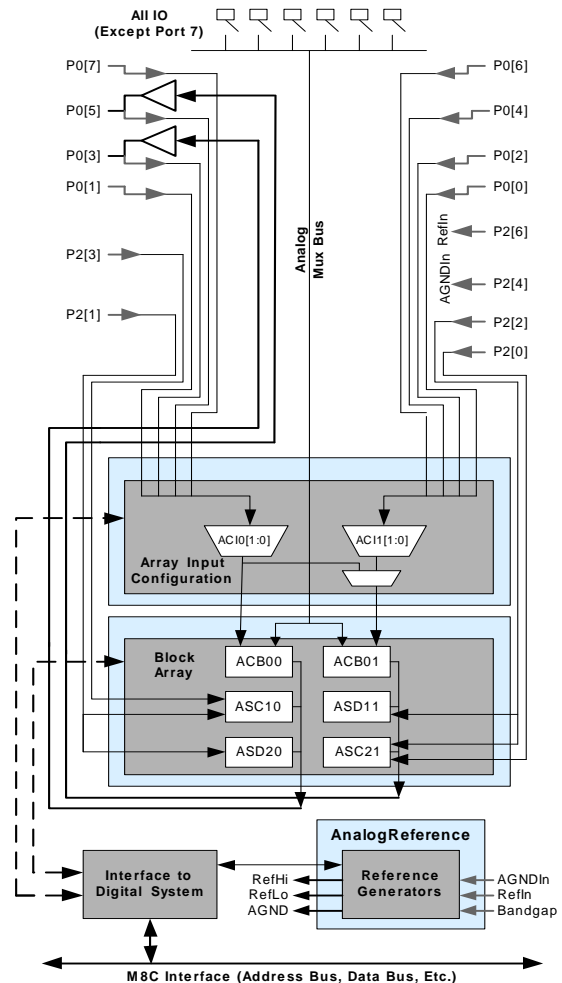
The Analog Multiplexer System

The Analog Mux Bus connects to every GPIO pin in ports 0-5. Pins are connected to the bus individually or in any combination. The bus also connects to the analog system for capacitive sensing with the TrueTouch block comparator. It can be split into two sections for simultaneous dual-channel processing. An additional 8:1 analog input multiplexer provides a second path to bring Port 0 pins to the analog array.

Switch control logic enables selected pins to switch dynamically under hardware control. This allows capacitive measurement for the touchscreen applications. Other multiplexer applications include:

- Chip-wide mux that allows analog input from up to 48 IO pins.
- Electrical connection between any IO pin combinations.

Figure 2. Analog System Block Diagram



Additional System Resources

System Resources, provide additional capability useful to complete systems. Additional resources include a multiplier, decimator, low voltage detection, and power on reset. Brief statements describing the merits of each resource follow.

- Full-Speed USB (12 Mbps) with 5 configurable endpoints and 256 bytes of RAM. No external components required except two series resistors. Wider than commercial temperature USB operation (-10°C to +85°C).
- Digital clock dividers provide three customizable clock frequencies for use in applications. The clocks can be routed to both the digital and analog systems. Additional clocks can be generated using digital PSoC blocks as clock dividers.
- Two multiply accumulates (MACs) provide fast 8-bit multipliers with 32-bit accumulate, to assist in both general math and digital filters.

- Decimator provides a custom hardware filter for digital signal processing applications including creation of Delta Sigma ADCs.
- The I2C module provides 100 and 400 kHz communication over two wires. Slave, master, multi-master are supported.
- Low Voltage Detection (LVD) interrupts signal the application of falling voltage levels, while the advanced POR (Power On Reset) circuit eliminates the need for a system supervisor.
- An internal 1.3V reference provides an absolute reference for the analog system, including ADCs and DACs.
- Versatile analog multiplexer system.

Getting Started

To understand the PSoC silicon, read this data sheet and use the PSoC Designer Integrated Development Environment (IDE). This data sheet is an overview of the PSoC integrated circuit and presents general silicon and electrical specifications. For in depth touchscreen application information, including touchscreen specific specifications, read the touchscreen user module data sheet that is supported by this specific device.

TrueTouch Device Characteristics

Depending on the TrueTouch device selected for a touchscreen application, characteristics and capabilities of each device change. Table 1 lists the touchscreen sensing capabilities available for specific TrueTouch devices. The TrueTouch device covered by this data sheet is highlighted in this table.

Table 1. TrueTouch Device Characteristics

| TrueTouch Part Number | Sensor Inputs | Max Screen Size (Inches) | Single-Touch | Multi-Touch Gesture | Multi-Touch All-Point | Scan Speed (ms) ^[1] | Current Consumption ^[2] | Flash Size | SRAM Size |
|-----------------------|---------------|--------------------------|--------------|---------------------|-----------------------|--------------------------------|------------------------------------|------------|-----------|
| CY8CTST110 | up to 24 | 4.3" | Y | N | N | 0.5 | 3 | 8K | 512 Bytes |
| CY8CTST120 | up to 44 | 8.4" | Y | N | N | 0.5 | 16 | 16K | 1K |
| CY8CTMG110 | up to 24 | 4.3" | Y | Y | N | 0.5 | 3 | 8K | 512 Bytes |
| CY8CTMG120 | up to 44 | 8.4 | Y | Y | N | 0.5 | 16 | 16K | 1K |
| CY8CTMA120 | up to 37 | 7.3" | Y | Y | Y | 0.12 | 16 | 16K | 1K |

Notes

1. Per sensor typical. Depends on touchscreen panel. For MA120 per X/Y crossing $V_{cc} = 3.3V$.
2. Average mA supply current. Based on 8 ms report rate, except for MA120.

Development Kits

Development Kits are available from the following distributors: Digi-Key, Avnet, Arrow, and Future. The Cypress Online Store contains development kits, C compilers, and all accessories for PSoC development. Go to the Cypress Online Store web site at <http://www.cypress.com>, click the Online Store shopping cart icon at the bottom of the web page, and click *PSoC (Programmable System-on-Chip)* to view a current list of available items.

Technical Training Modules

Free PSoC technical training modules are available for users new to PSoC. Training modules cover designing, debugging, advanced analog and CapSense. Go to <http://www.cypress.com/training>.

Consultants

Certified PSoC Consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC Consultant go to <http://www.cypress.com>, click on Design Support located on the left side of the web page, and select CYPros Consultants.

Technical Support

PSoC application engineers take pride in fast and accurate response. They are available with a four hour guaranteed response at <http://www.cypress.com/support/login.cfm>.

Application Notes

A long list of application notes assist you in every aspect of your design effort. To view the PSoC application notes, go to the <http://www.cypress.com> web site and select Application Notes under the Design Resources list located in the center of the web page. Application notes are listed by date as default.

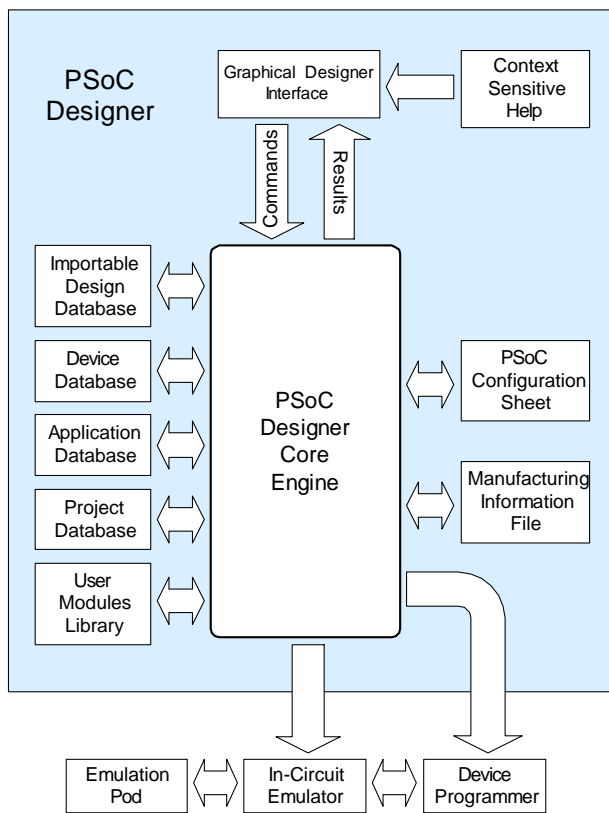
Development Tools

PSoC Designer is a Microsoft® Windows based, integrated development environment for the Programmable System-on-Chip (PSoC) devices. The PSoC Designer IDE and application runs on Windows NT 4.0, Windows 2000, Windows Millennium (Me), or Windows XP (see Figure 3 on page 5).

PSoC Designer helps the customer to select an operating configuration for the PSoC, write application code that uses the PSoC, and debug the application. This system provides design database management by project, an integrated debugger with In-Circuit Emulator (ICE), in-system programming support, and the CYASM macro assembler for the CPUs.

PSoC Designer also supports a high level C language compiler developed specifically for the devices in the family.

Figure 3. PSoC Designer Subsystems



PSoC Designer Software Subsystems

Device Editor

The Device Editor subsystem allows the user to select different onboard analog and digital components called user modules using the PSoC blocks. Examples of user modules are ADCs, DACs, amplifiers, and filters.

The device editor also supports easy development of multiple configurations and dynamic reconfiguration. Dynamic configuration allows changing configurations at run time.

PSoC Designer sets up power-on initialization tables for selected PSoC block configurations and creates source code for an application framework. The framework contains software to operate the selected components. If the project uses more than one operating configuration, then it contains routines to switch between different sets of PSoC block configurations at run time. PSoC Designer prints out a configuration sheet for a given project configuration for use during application programming in conjunction with the device data sheet. After the framework is generated, the user can add application-specific code to flesh out the framework. It is also possible to change the selected components and regenerate the framework.

Design Browser

The Design Browser allows users to select and import preconfigured designs into the user’s project. Users can easily browse a catalog of preconfigured designs to facilitate time-to-design.

Examples provided in the tools include a 300-baud modem, LIN Bus master and slave, fan controller, and magnetic card reader.

Application Editor

In the Application Editor you can edit your C language and Assembly language source code. You can also assemble, compile, link, and build.

Assembler. The macro assembler allows the assembly code to be merged seamlessly with C code. The link libraries automatically use absolute addressing or can be compiled in relative mode, and linked with other software modules to get absolute addressing.

C Language Compiler. A C language compiler is available that supports the PSoC family of devices. Even if you have never worked in the C language before, the product quickly allows you to create complete C programs for the PSoC family devices.

The embedded, optimizing C compiler provides all the features of C tailored to the PSoC architecture. It comes complete with embedded libraries providing port and bus operations, standard keypad and display support, and extended math functionality.

Debugger

The PSoC Designer Debugger subsystem provides hardware in-circuit emulation, allowing the designer to test the program in a physical system while providing an internal view of the PSoC device. Debugger commands allow the designer to read and program and read and write data memory, read and write IO registers, read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows the designer to create a trace buffer of registers and memory locations of interest.

Online Help System

The online help system displays online, context-sensitive help for the user. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an Online Support Forum to aid the designer in getting started.

Hardware Tools

In-Circuit Emulator

A low cost, high functionality ICE is available for development support. This hardware has the capability to program single devices.

The emulator consists of a base unit that connects to the PC by way of a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full speed (24 MHz) operation.

TrueTouch Touchscreen Tuner

The TrueTouch tuner is a Microsoft® Windows based graphical user interface allowing developers to set critical parameters and observe changes to the touchscreen application in real time. Optimal configuration from the tuner can be immediately applied to the TrueTouch user module settings.

Designing with User Modules

The development process for the PSoC device differs from that of a traditional fixed function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and by lowering inventory costs. These configurable resources, called PSoC Blocks, have the ability to implement a wide variety of user-selectable functions. Each block has several registers that determine its function and connectivity to other blocks, multiplexers, buses and to the IO pins. Iterative development cycles permit you to adapt the hardware and software. This substantially lowers the risk of having to select a different part to meet the final design requirements.

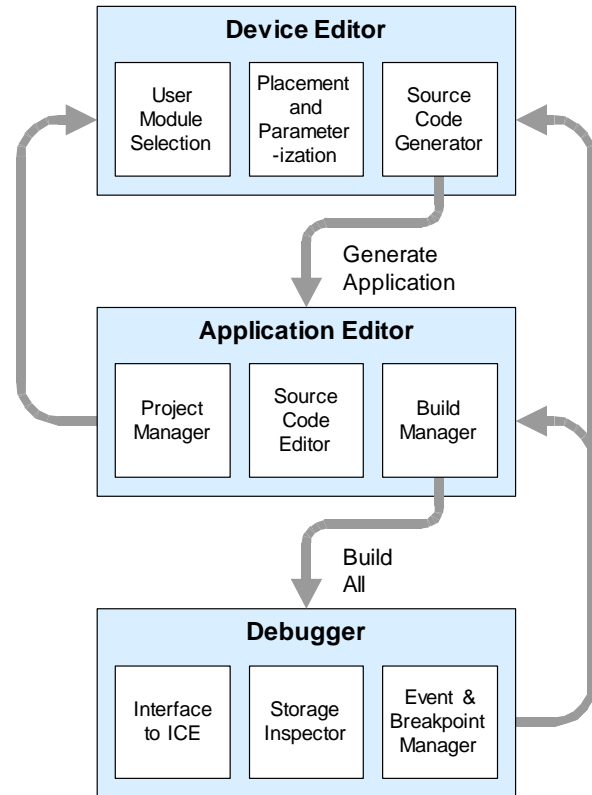
To speed the development process, the PSoC Designer IDE provides a library of pre-built, pre-tested hardware peripheral functions, called "User Modules." User modules make selecting and implementing peripheral devices simple, and come in analog, digital, and mixed signal varieties. The standard user module library contains over 50 common peripherals such as ADCs, DACs, timers, counters, UARTs, and other not so common peripherals such as DTMF generators and Bi-Quad analog filter sections.

Each user module establishes the basic register settings that implement the selected function. It also provides parameters that allow you to tailor its precise configuration to your particular application. For example, a Pulse Width Modulator User Module configures one or more digital PSoC blocks, one for each 8 bits of resolution. The user module parameters permit to establish the pulse width and duty cycle. User modules also provide tested software to cut development time. The user module application programming interface (API) provides high level functions to control and respond to hardware events at run-time. The API also provides optional interrupt service routines that are adapted as needed.

The API functions are documented in user module data sheets that are viewed directly in the PSoC Designer IDE. These data sheets explain the internal operation of the user module and provide performance specifications. Each data sheet describes the use of each user module parameter and documents the setting of each register controlled by the user module.

The development process starts when you open a new project and bring up the Device Editor, a graphical user interface (GUI) for configuring the hardware. Pick the user modules you need for your project and map them onto the PSoC blocks with point-and-click simplicity. Next, build signal chains by interconnecting user modules to each other and the IO pins. At this stage, also configure the clock source connections and enter parameter values directly or by selecting values from drop-down menus. When you are ready to test the hardware configuration or move on to developing code for the project, perform the "Generate Application" step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the high level user module API functions.

Figure 4. User Module and Source Code Development Flows



The next step is to write your main program, and any sub-routines using PSoC Designer's Application Editor subsystem. The Application Editor includes a Project Manager that allows you to open the project source code files (including all generated code files) from a hierarchal view. The source code editor provides syntax coloring and advanced edit features for both C and assembly language. File search capabilities include simple string searches and recursive "grep-style" patterns. A single mouse click invokes the Build Manager. It employs a professional strength "makefile" system to automatically analyze all file dependencies and run the compiler and assembler as necessary. Project level options control optimization strategies used by the compiler and linker. Syntax errors are displayed in a console window. Double click the error message to view the offending line of source code. When all is correct, the linker builds a HEX file image suitable for programming.

The last step in the development process takes place inside the PSoC Designer's Debugger subsystem. The Debugger downloads the HEX image to the ICE where it runs at full speed. Debugger capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint and watch-variable features, the Debugger provides a large trace buffer and allows you define complex breakpoint events that include monitoring address and data bus values, memory locations and external signals.

Document Conventions

Acronyms Used

The following table lists the acronyms that are used in this document.

| Acronym | Description |
|---------|---|
| AC | alternating current |
| ADC | analog-to-digital converter |
| API | application programming interface |
| CPU | central processing unit |
| CT | continuous time |
| DAC | digital-to-analog converter |
| DC | direct current |
| ECO | external crystal oscillator |
| EEPROM | electrically erasable programmable read-only memory |
| FSR | full scale range |
| GPIO | general purpose IO |
| GUI | graphical user interface |
| HBM | human body model |
| ICE | in-circuit emulator |
| ILO | internal low speed oscillator |
| IMO | internal main oscillator |
| IO | input/output |
| IPOR | imprecise power on reset |
| LSb | least-significant bit |
| LVD | low voltage detect |
| MSb | most-significant bit |
| PC | program counter |
| PLL | phase-locked loop |
| POR | power on reset |
| PPOR | precision power on reset |
| PSoC® | Programmable System-on-Chip™ |
| PWM | pulse width modulator |
| SC | switched capacitor |
| SRAM | static random access memory |

Units of Measure

A units of measure table is located in the Electrical Specifications section. [Table 4](#) on page 11 lists all the abbreviations used to measure the PSoC devices.

Numeric Naming

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase 'h' (for example, '14h' or '3Ah'). Hexadecimal numbers may also be represented by a '0x' prefix, the C coding convention. Binary numbers have an appended lowercase 'b' (for example, '01010100b' or '01000011b'). Numbers not indicated by an 'h', '0x', or 'b' are decimal.

100-Pin Part Pinout (On-Chip Debug)

The 100-pin TQFP part is the CY8CTMG120 On-Chip Debug (OCD) TrueTouch device.

Note This part is only used for in-circuit debugging. It is NOT available for production.

Figure 6. CY8CTMG120 OCD

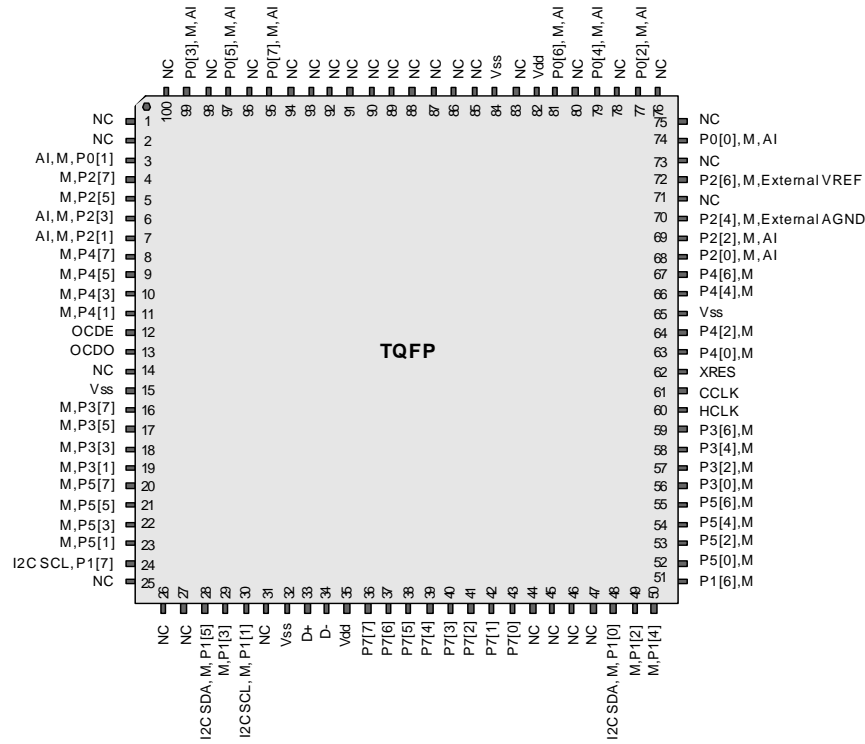


Table 3. 100-Pin Part Pinout (TQFP)

| Pin No. | Digital | Analog | Name | Description | Pin No. | Digital | Analog | Name | Description |
|---------|---------|--------|-------|--|---------|---------|--------|-------|--|
| 1 | | | NC | No connection. Leave floating. | 51 | IO | M | P1[6] | |
| 2 | | | NC | No connection. Leave floating. | 52 | IO | M | P5[0] | |
| 3 | IO | I, M | P0[1] | Analog column mux input. | 53 | IO | M | P5[2] | |
| 4 | IO | M | P2[7] | | 54 | IO | M | P5[4] | |
| 5 | IO | M | P2[5] | | 55 | IO | M | P5[6] | |
| 6 | IO | I, M | P2[3] | Direct switched capacitor block input. | 56 | IO | M | P3[0] | |
| 7 | IO | I, M | P2[1] | Direct switched capacitor block input. | 57 | IO | M | P3[2] | |
| 8 | IO | M | P4[7] | | 58 | IO | M | P3[4] | |
| 9 | IO | M | P4[5] | | 59 | IO | M | P3[6] | |
| 10 | IO | M | P4[3] | | 60 | | | HCLK | OCD high-speed clock output. |
| 11 | IO | M | P4[1] | | 61 | | | CCLK | OCD CPU clock output. |
| 12 | | | OCDE | OCD even data IO. | 62 | Input | | XRES | Active high pin reset with internal pull down. |
| 13 | | | OCD O | OCD odd data output. | 63 | IO | M | P4[0] | |
| 14 | | | NC | No connection. Leave floating. | 64 | IO | M | P4[2] | |
| 15 | Power | | Vss | Ground. Connect to circuit ground. | 65 | Power | | Vss | Ground. Connect to circuit ground. |
| 16 | IO | M | P3[7] | | 66 | IO | M | P4[4] | |
| 17 | IO | M | P3[5] | | 67 | IO | M | P4[6] | |

Table 3. 100-Pin Part Pinout (TQFP) (continued)

| Pin No. | Digital | Analog | Name | Description | Pin No. | Digital | Analog | Name | Description |
|---------|---------|--------|-------|---|---------|---------|--------|-------|---|
| 19 | IO | M | P3[1] | | 69 | IO | I, M | P2[2] | Direct switched capacitor block input. |
| 20 | IO | M | P5[7] | | 70 | IO | | P2[4] | External Analog Ground (AGND) input. |
| 21 | IO | M | P5[5] | | 71 | | | NC | No connection. Leave floating. |
| 22 | IO | M | P5[3] | | 72 | IO | | P2[6] | External Voltage Reference (VREF) input. |
| 23 | IO | M | P5[1] | | 73 | | | NC | No connection. Leave floating. |
| 24 | IO | M | P1[7] | I2C Serial Clock (SCL). | 74 | IO | I | P0[0] | Analog column mux input. |
| 25 | | | NC | No connection. Leave floating. | 75 | | | NC | No connection. Leave floating. |
| 26 | | | NC | No connection. Leave floating. | 76 | | | NC | No connection. Leave floating. |
| 27 | | | NC | No connection. Leave floating. | 77 | IO | I, M | P0[2] | Analog column mux input and column output. |
| 28 | IO | | P1[5] | I2C Serial Data (SDA) | 78 | | | NC | No connection. Leave floating. |
| 29 | IO | | P1[3] | | 79 | IO | I, M | P0[4] | Analog column mux input and column output. |
| 30 | IO | | P1[1] | Crystal (XTALin), I2C Serial Clock (SCL), ISSP SCLK ^[3] . | 80 | | | NC | No connection. Leave floating. |
| 31 | | | NC | No connection. Leave floating. | 81 | IO | I, M | P0[6] | Analog column mux input. |
| 32 | Power | | Vss | Ground. Connect to circuit ground. | 82 | Power | | Vdd | Supply voltage. Bypass to ground with 0.1 uF capacitor. |
| 33 | USB | | D+ | | 83 | | | NC | No connection. Leave floating. |
| 34 | USB | | D- | | 84 | Power | | Vss | Ground. Connect to circuit ground. |
| 35 | Power | | Vdd | Supply voltage. Bypass to ground with 0.1 uF capacitor. | 85 | | | NC | No connection. Leave floating. |
| 36 | IO | | P7[7] | | 86 | | | NC | No connection. Leave floating. |
| 37 | IO | | P7[6] | | 87 | | | NC | No connection. Leave floating. |
| 38 | IO | | P7[5] | | 88 | | | NC | No connection. Leave floating. |
| 39 | IO | | P7[4] | | 89 | | | NC | No connection. Leave floating. |
| 40 | IO | | P7[3] | | 90 | | | NC | No connection. Leave floating. |
| 41 | IO | | P7[2] | | 91 | | | NC | No connection. Leave floating. |
| 42 | IO | | P7[1] | | 92 | | | NC | No connection. Leave floating. |
| 43 | IO | | P7[0] | | 93 | | | NC | No connection. Leave floating. |
| 44 | | | NC | No connection. Leave floating. | 94 | | | NC | No connection. Leave floating. |
| 45 | | | NC | No connection. Leave floating. | 95 | IO | I, M | P0[7] | Analog column mux input. |
| 46 | | | NC | No connection. Leave floating. | 96 | | | NC | No connection. Leave floating. |
| 47 | | | NC | No connection. Leave floating. | 97 | IO | IO, M | P0[5] | Analog column mux input and column output. |
| 48 | IO | | P1[0] | Crystal (XTALout), I2C Serial Data (SDA), ISSP SDATA ^[3] . | 98 | | | NC | No connection. Leave floating. |
| 49 | IO | | P1[2] | | 99 | IO | IO, M | P0[3] | Analog column mux input and column output. |
| 50 | IO | | P1[4] | Optional External Clock Input (EXTCLK). | 100 | | | NC | No connection. Leave floating. |

LEGEND A = Analog, I = Input, O = Output, NC = No Connection, M = Analog Mux Input, OCD = On-Chip Debugger.

Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8CTMG120 TrueTouch device family. For the most up to date electrical specifications, confirm that you have the most recent data sheet by going to the web at <http://www.cypress.com/psoc>.

Specifications are valid for $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ and $T_J \leq 100^{\circ}\text{C}$, except where noted. Specifications for devices running at greater than 12 MHz are valid for $-40^{\circ}\text{C} \leq T_A \leq 70^{\circ}\text{C}$ and $T_J \leq 82^{\circ}\text{C}$.

Figure 7. Voltage versus CPU Frequency

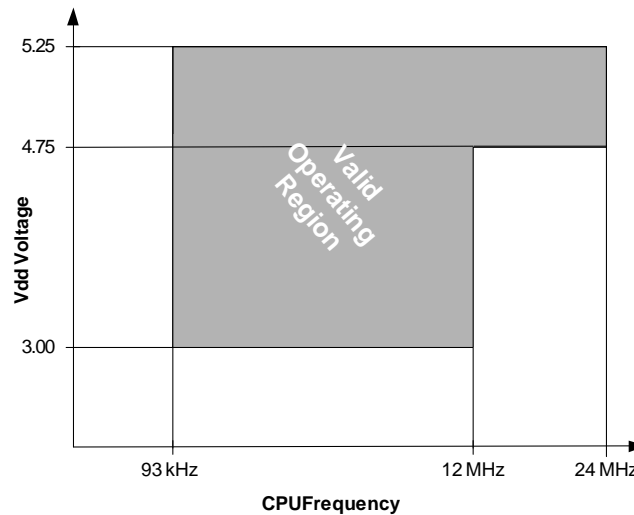


Table 4 lists the units of measure that are used in this section

Table 4. Units of Measure

| Symbol | Unit of Measure | Symbol | Unit of Measure |
|--------|-----------------------------|--------|-------------------------------|
| °C | degree Celsius | μW | microwatts |
| dB | decibels | mA | milli-ampere |
| fF | femto farad | ms | milli-second |
| Hz | hertz | mV | milli-volts |
| KB | 1024 bytes | nA | nanoampere |
| Kbit | 1024 bits | ns | nanosecond |
| kHz | kilohertz | nV | nanovolts |
| kΩ | kilohm | Ω | ohm |
| MHz | megahertz | pA | picoampere |
| MΩ | megaohm | pF | picofarad |
| μA | microampere | pp | peak-to-peak |
| μF | microfarad | ppm | parts per million |
| μH | microhenry | ps | picosecond |
| μs | microsecond | sps | samples per second |
| μV | microvolts | s | sigma: one standard deviation |
| μVrms | microvolts root-mean-square | V | volts |

Absolute Maximum Ratings

Table 5. Absolute Maximum Ratings

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-------------------|---|-----------|-----|-----------|-------|---|
| T _{STG} | Storage Temperature | -55 | 25 | +100 | °C | Higher storage temperatures reduces data retention time. Recommended storage temperature is +25°C ± 25°C. Extended duration storage temperatures above 65°C degrades reliability. |
| T _A | Ambient Temperature with Power Applied | -40 | – | +85 | °C | |
| V _{dd} | Supply Voltage on Vdd Relative to Vss | -0.5 | – | +6.0 | V | |
| V _{IO} | DC Input Voltage | Vss - 0.5 | – | Vdd + 0.5 | V | |
| V _{IO2} | DC Voltage Applied to Tri-state | Vss - 0.5 | – | Vdd + 0.5 | V | |
| I _{MIO} | Maximum Current into any Port Pin | -25 | – | +50 | mA | |
| I _{MAIO} | Maximum Current into any Port Pin Configured as Analog Driver | -50 | – | +50 | mA | |
| ESD | Electro Static Discharge Voltage ^[4] . | 2000 | – | – | V | Human Body Model ESD. |
| LU | Latch Up Current | – | – | 200 | mA | |

Operating Temperature

Table 6. Operating Temperature

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-------------------|--------------------------------------|-----|-----|------|-------|---|
| T _A | Ambient Temperature ^[5] . | -40 | – | +85 | °C | |
| T _{AUSB} | Ambient Temperature using USB | -10 | – | +85 | °C | |
| T _J | Junction Temperature | -40 | – | +100 | °C | The temperature rise from ambient to junction is package specific. See Thermal Impedance for the Package on page 30. The user must limit the power consumption to comply with this requirement. |

Notes

4. See the user module data sheet for touchscreen application related ESD testing
5. See the user module data sheet for touchscreen application related temperature testing.

DC Electrical Characteristics

The below electrical characteristics are for proper CPU core and I/O operation. For capacitive touchscreen electrical characteristics, refer to the touchscreen user module data sheet.

DC Chip Level Specifications

Table 7 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 7. DC Chip Level Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|------------------|--|-----|-----|------|-------|---|
| Vdd | Supply Voltage | 3.0 | – | 5.25 | V | See DC POR and LVD specifications, Table 19 on page 20. |
| I _{DD5} | Supply Current, IMO = 24 MHz (5V) | – | 14 | 27 | mA | Conditions are Vdd = 5.0V, T _A = 25 °C, CPU = 3 MHz, SYSCLK doubler disabled, VC1 = 1.5 MHz, VC2 = 93.75 kHz, VC3 = 93.75 kHz, analog power = off. |
| I _{DD3} | Supply Current, IMO = 24 MHz (3.3V) | – | 8 | 14 | mA | Conditions are Vdd = 3.3V, T _A = 25 °C, CPU = 3 MHz, SYSCLK doubler disabled, VC1 = 1.5 MHz, VC2 = 93.75 kHz, VC3 = 0.367 kHz, analog power = off. |
| I _{SB} | Sleep (Mode) Current with POR, LVD, Sleep Timer, and WDT. ^[6] | – | 3 | 6.5 | μA | Conditions are with internal slow speed oscillator, Vdd = 3.3V, $-40^{\circ}\text{C} \leq T_A \leq 55^{\circ}\text{C}$, analog power = off. |
| I _{SBH} | Sleep (Mode) Current with POR, LVD, Sleep Timer, and WDT at High Temperature. ^[6] | – | 4 | 25 | μA | Conditions are with internal slow speed oscillator, Vdd = 3.3V, $55^{\circ}\text{C} < T_A \leq 85^{\circ}\text{C}$, analog power = off. |

Note

6. Standby current includes all functions (POR, LVD, WDT, Sleep Time) needed for reliable system operation. This should be compared with devices that have similar functions enabled.

DC General Purpose IO Specifications

Table 8 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 8. DC GPIO Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|------------------|-----------------------------------|-----------------------|-----|------|------------|--|
| R _{PU} | Pull Up Resistor | 4 | 5.6 | 8 | k Ω | |
| R _{PD} | Pull Down Resistor | 4 | 5.6 | 8 | k Ω | |
| V _{OH} | High Output Level | V _{dd} - 1.0 | – | – | V | I _{OH} = 10 mA, V _{dd} = 4.75 to 5.25V (8 total loads, 4 on even port pins (for example, P0[2], P1[4]), 4 on odd port pins (for example, P0[3], P1[5])). 80 mA maximum combined IOH budget. |
| V _{OL} | Low Output Level | – | – | 0.75 | V | I _{OL} = 25 mA, V _{dd} = 4.75 to 5.25V (8 total loads, 4 on even port pins (for example, P0[2], P1[4]), 4 on odd port pins (for example, P0[3], P1[5])). 200 mA maximum combined IOL budget. |
| V _{IL} | Input Low Level | – | – | 0.8 | V | V _{dd} = 3.0 to 5.25. |
| V _{IH} | Input High Level | 2.1 | – | – | V | V _{dd} = 3.0 to 5.25. |
| V _H | Input Hysteresis | – | 60 | – | mV | |
| I _{IL} | Input Leakage (Absolute Value) | – | 1 | – | nA | Gross tested to 1 μA . |
| C _{IN} | Capacitive Load on Pins as Input | – | 3.5 | 10 | pF | Package and pin dependent. Temp = 25°C . |
| C _{OUT} | Capacitive Load on Pins as Output | – | 3.5 | 10 | pF | Package and pin dependent. Temp = 25°C . |

DC Full-Speed USB Specifications

Table 9 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-10^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-10^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 9. DC Full Speed (12 Mbps) USB Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-------------------|--------------------------------------|-----|-----|-----|---------------|---|
| USB Interface | | | | | | |
| V _{DI} | Differential Input Sensitivity | 0.2 | – | – | V | (D+) - (D-) |
| V _{CM} | Differential Input Common Mode Range | 0.8 | – | 2.5 | V | |
| V _{SE} | Single Ended Receiver Threshold | 0.8 | – | 2.0 | V | |
| C _{IN} | Transceiver Capacitance | – | – | 20 | pF | |
| I _{IO} | High-Z State Data Line Leakage | -10 | – | 10 | μA | $0\text{V} < V_{IN} < 3.3\text{V}$. |
| R _{EXT} | External USB Series Resistor | 23 | – | 25 | W | In series with each USB pin. |
| V _{UOH} | Static Output High, Driven | 2.8 | – | 3.6 | V | 15 k Ω \pm 5% to Ground. Internal pull-up enabled. |
| V _{UOHI} | Static Output High, Idle | 2.7 | – | 3.6 | V | 15 k Ω \pm 5% to Ground. Internal pull-up enabled. |
| V _{UOL} | Static Output Low | – | – | 0.3 | V | 15 k Ω \pm 5% to Ground. Internal pull-up enabled. |
| Z _O | USB Driver Output Impedance | 28 | – | 44 | W | Including R _{EXT} Resistor. |
| V _{CRS} | D+/D- Crossover Voltage | 1.3 | – | 2.0 | V | |

DC Operational Amplifier Specifications

Table 10 and Table 11 list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

The Operational Amplifier is a component of both the Analog Continuous Time PSoC blocks and the Analog Switched Capacitor PSoC blocks. The guaranteed specifications are measured in the Analog Continuous Time PSoC block.

Table 10. 5V DC Operational Amplifier Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|----------------|---|----------------|------|----------------|--------------------------------|---|
| $V_{OSO A}$ | Input Offset Voltage (absolute value) | – | 1.6 | 10 | mV | |
| | Power = Low, Opamp Bias = High | | 1.3 | 8 | mV | |
| | Power = Medium, Opamp Bias = High | | 1.2 | 7.5 | mV | |
| $TCV_{OSO A}$ | Average Input Offset Voltage Drift | – | 7.0 | 35.0 | $\mu\text{V}/^{\circ}\text{C}$ | |
| $I_{EBO A}$ | Input Leakage Current (Port 0 Analog Pins) | – | 20 | – | pA | Gross tested to 1 μA . |
| $C_{INO A}$ | Input Capacitance (Port 0 Analog Pins) | – | 4.5 | 9.5 | pF | Package and pin dependent. Temp = 25°C . |
| $V_{CMO A}$ | Common Mode Voltage Range | 0.0 | – | V_{DD} | V | The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer. |
| | Common Mode Voltage Range (high power or high opamp bias) | 0.5 | – | $V_{DD} - 0.5$ | | |
| $G_{OLO A}$ | Open Loop Gain | 60 | – | – | dB | |
| | Power = Low, Opamp Bias = High | | 60 | | | |
| | Power = Medium, Opamp Bias = High | | 80 | | | |
| $V_{OHIGHO A}$ | High Output Voltage Swing (internal signals) | $V_{DD} - 0.2$ | – | – | V | |
| | Power = Low, Opamp Bias = High | | – | – | V | |
| | Power = Medium, Opamp Bias = High | | – | – | V | |
| $V_{OLOWO A}$ | Low Output Voltage Swing (internal signals) | – | – | 0.2 | V | |
| | Power = Low, Opamp Bias = High | | – | 0.2 | V | |
| | Power = Medium, Opamp Bias = High | | – | 0.5 | V | |
| $I_{SO A}$ | Supply Current (including associated AGND buffer) | – | 400 | 800 | μA | |
| | Power = Low, Opamp Bias = Low | | 500 | 900 | μA | |
| | Power = Low, Opamp Bias = High | | 800 | 1000 | μA | |
| | Power = Medium, Opamp Bias = Low | | 1200 | 1600 | μA | |
| | Power = Medium, Opamp Bias = High | | 2400 | 3200 | μA | |
| | Power = High, Opamp Bias = Low | | 4600 | 6400 | μA | |
| $PSRR_{O A}$ | Supply Voltage Rejection Ratio | 65 | 80 | – | dB | $V_{SS} \leq V_{IN} \leq (V_{DD} - 2.25)$ or $(V_{DD} - 1.25\text{V}) \leq V_{IN} \leq V_{DD}$. |

Table 11. 3.3V DC Operational Amplifier Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|----------------|--|-------------------------------------|---|--|--|---|
| $V_{OSO A}$ | Input Offset Voltage (Absolute Value) Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = High High Power is 5V Only | – – | 1.65 1.32 | 10 8 | mV mV | |
| $TCV_{OSO A}$ | Average Input Offset Voltage Drift | – | 7.0 | 35.0 | $\mu V/^{\circ}C$ | |
| $I_{EBO A}$ | Input Leakage Current (Port 0 Analog Pins) | – | 20 | – | pA | Gross tested to 1 μA . |
| $C_{INO A}$ | Input Capacitance (Port 0 Analog Pins) | – | 4.5 | 9.5 | pF | Package and pin dependent. Temp = 25 $^{\circ}C$. |
| $V_{CMO A}$ | Common Mode Voltage Range | 0.2 | – | Vdd - 0.2 | V | The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer. |
| $G_{OLO A}$ | Open Loop Gain Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High, Opamp Bias = Low | 60 60 80 | – | – | dB | |
| $V_{OHIGHO A}$ | High Output Voltage Swing (internal signals) Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High is 5V only | Vdd - 0.2 Vdd - 0.2 Vdd - 0.2 | – – – | – – – | V V V | |
| $V_{OLOWO A}$ | Low Output Voltage Swing (internal signals) Power = Low, Opamp Bias = Low Power = Medium, Opamp Bias = Low Power = High, Opamp Bias = Low | – – – | – – – | 0.2 0.2 0.2 | V V V | |
| $I_{SO A}$ | Supply Current (including associated AGND buffer) Power = Low, Opamp Bias = Low Power = Low, Opamp Bias = High Power = Medium, Opamp Bias = Low Power = Medium, Opamp Bias = High Power = High, Opamp Bias = Low Power = High, Opamp Bias = High | – – – – – – | 400 500 800 1200 2400 4600 | 800 900 1000 1600 3200 6400 | μA μA μA μA μA μA | |
| $PSRR_{O A}$ | Supply Voltage Rejection Ratio | 65 | 80 | – | dB | $V_{SS} \leq V_{IN} \leq (V_{DD} - 2.25)$ or $(V_{DD} - 1.25V) \leq V_{IN} \leq V_{DD}$. |

DC Low Power Comparator Specifications

Table 12 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 2.4V to 3.0V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V at 25°C. These are for design guidance only.

Table 12. DC Low Power Comparator Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|--------------|--|-----|-----|--------------|---------------|-------|
| V_{REFLPC} | Low Power Comparator (LPC) Reference Voltage Range | 0.2 | – | $V_{DD} - 1$ | V | |
| I_{SLPC} | LPC Supply Current | – | 10 | 40 | μA | |
| V_{OSLPC} | LPC Voltage Offset | – | 2.5 | 30 | mV | |

DC IDAC Resolution

Table 13 lists IDAC typical resolution. Typical parameters apply to 5V at 25°C. These are for design guidance only.

Table 13. DC Low Power Comparator Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-----------|--------------------------------------|-----|-----|-----|-------|-------|
| I_{DAC} | Current Output of 1 LSB (1x Setting) | – | 75 | – | nA | |

DC Analog Output Buffer Specifications

Table 14 and Table 15 list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Table 14. 5V DC Analog Output Buffer Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|---------------|--|--|------------|--|--------------------------------|--|
| V_{OSOB} | Input Offset Voltage (Absolute Value) | – | 3 | 12 | mV | |
| $TCV_{OSO B}$ | Average Input Offset Voltage Drift | – | +6 | – | $\mu\text{V}/^{\circ}\text{C}$ | |
| V_{CMOB} | Common-Mode Input Voltage Range | 0.5 | – | $V_{DD} - 1.0$ | V | |
| R_{OUTOB} | Output Resistance Power = Low Power = High | – – | 0.6 0.6 | – – | W W | |
| $V_{OHIGHOB}$ | High Output Voltage Swing (Load = 32 ohms to $V_{DD}/2$) Power = Low Power = High | 0.5 x $V_{DD} + 1.1$ 0.5 x $V_{DD} + 1.1$ | – – | – – | V V | |
| V_{LOWOB} | Low Output Voltage Swing (Load = 32 ohms to $V_{DD}/2$) Power = Low Power = High | – – | – – | 0.5 x $V_{DD} - 1.3$ 0.5 x $V_{DD} - 1.3$ | V V | |
| I_{SOB} | Supply Current Including Bias Cell (No Load) Power = Low Power = High | – – | 1.1 2.6 | 5.1 8.8 | mA mA | |
| $PSRR_{OB}$ | Supply Voltage Rejection Ratio | 53 | 64 | – | dB | $(0.5 \times V_{DD} - 1.3) \leq V_{OUT} \leq (V_{DD} - 2.3)$. |

Table 15. 3.3V DC Analog Output Buffer Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|----------------------|---|--|------------|--|----------|---|
| V _{OSOB} | Input Offset Voltage (Absolute Value) | – | 3 | 12 | mV | |
| TCV _{OSOB} | Average Input Offset Voltage Drift | – | +6 | – | μV/°C | |
| V _{CMOB} | Common-Mode Input Voltage Range | 0.5 | - | V _{dd} - 1.0 | V | |
| R _{OUTOB} | Output Resistance Power = Low Power = High | – – | 1 1 | – – | W W | |
| V _{OHIGHOB} | High Output Voltage Swing (Load = 1K ohms to V _{dd} /2) Power = Low Power = High | 0.5 x V _{dd} + 1.0 0.5 x V _{dd} + 1.0 | – – | – – | V V | |
| V _{OLOWOB} | Low Output Voltage Swing (Load = 1K ohms to V _{dd} /2) Power = Low Power = High | – – | – – | 0.5 x V _{dd} - 1.0 0.5 x V _{dd} - 1.0 | V V | |
| I _{SOB} | Supply Current Including Bias Cell (No Load) Power = Low Power = High | – | 0.8 2.0 | 2.0 4.3 | mA mA | |
| PSRR _{OB} | Supply Voltage Rejection Ratio | 34 | 64 | – | dB | (0.5 x V _{dd} - 1.0) ≤ V _{OUT} ≤ (0.5 x V _{dd} + 0.9). |

DC Analog Reference Specifications

Table 16 and Table 17 list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

The guaranteed specifications are measured through the Analog Continuous Time PSoC blocks. The power levels for AGND refer to the power of the Analog Continuous Time PSoC block. The power levels for RefHi and RefLo refer to the Analog Reference Control register. The limits stated for AGND include the offset error of the AGND buffer local to the Analog Continuous Time PSoC block. Reference control power is high.

Table 16. 5V DC Analog Reference Specifications

| Symbol | Description | Min | Typ | Max | Units |
|--------|--|--------------------------------|---------------------------|--------------------------------|-------|
| BG | Bandgap Voltage Reference | 1.28 | 1.30 | 1.32 | V |
| – | AGND = V _{dd} /2 ^[7] | V _{dd} /2 - 0.04 | V _{dd} /2 - 0.01 | V _{dd} /2 + 0.007 | V |
| – | AGND = 2 x BandGap ^[7] | 2 x BG - 0.048 | 2 x BG - 0.030 | 2 x BG + 0.024 | V |
| – | AGND = P2[4] (P2[4] = V _{dd} /2) ^[7] | P2[4] - 0.011 | P2[4] | P2[4] + 0.011 | V |
| – | AGND = BandGap ^[7] | BG - 0.009 | BG + 0.008 | BG + 0.016 | V |
| – | AGND = 1.6 x BandGap ^[7] | 1.6 x BG - 0.022 | 1.6 x BG - 0.010 | 1.6 x BG + 0.018 | V |
| – | AGND Block to Block Variation (AGND = V _{dd} /2) ^[7] | -0.034 | 0.000 | 0.034 | V |
| – | RefHi = V _{dd} /2 + BandGap | V _{dd} /2 + BG - 0.10 | V _{dd} /2 + BG | V _{dd} /2 + BG + 0.10 | V |
| – | RefHi = 3 x BandGap | 3 x BG - 0.06 | 3 x BG | 3 x BG + 0.06 | V |
| – | RefHi = 2 x BandGap + P2[6] (P2[6] = 1.3V) | 2 x BG + P2[6] - 0.113 | 2 x BG + P2[6] - 0.018 | 2 x BG + P2[6] + 0.077 | V |
| – | RefHi = P2[4] + BandGap (P2[4] = V _{dd} /2) | P2[4] + BG - 0.130 | P2[4] + BG - 0.016 | P2[4] + BG + 0.098 | V |
| – | RefHi = P2[4] + P2[6] (P2[4] = V _{dd} /2, P2[6] = 1.3V) | P2[4] + P2[6] - 0.133 | P2[4] + P2[6] - 0.016 | P2[4] + P2[6] + 0.100 | V |

Note

7. AGND tolerance includes the offsets of the local buffer in the PSoC block. Bandgap voltage is 1.3V ± 0.02V.

Table 16. 5V DC Analog Reference Specifications (continued)

| Symbol | Description | Min | Typ | Max | Units |
|--------|---|------------------------|------------------------|------------------------|-------|
| – | RefHi = 3.2 x BandGap | 3.2 x BG - 0.112 | 3.2 x BG | 3.2 x BG + 0.076 | V |
| – | RefLo = Vdd/2 – BandGap | Vdd/2 - BG - 0.04 | Vdd/2 - BG + 0.024 | Vdd/2 - BG + 0.04 | V |
| – | RefLo = BandGap | BG - 0.06 | BG | BG + 0.06 | V |
| – | RefLo = 2 x BandGap - P2[6] (P2[6] = 1.3V) | 2 x BG - P2[6] - 0.084 | 2 x BG - P2[6] + 0.025 | 2 x BG - P2[6] + 0.134 | V |
| – | RefLo = P2[4] – BandGap (P2[4] = Vdd/2) | P2[4] - BG - 0.056 | P2[4] - BG + 0.026 | P2[4] - BG + 0.107 | V |
| – | RefLo = P2[4]-P2[6] (P2[4] = Vdd/2, P2[6] = 1.3V) | P2[4] - P2[6] - 0.057 | P2[4] - P2[6] + 0.026 | P2[4] - P2[6] + 0.110 | V |

Table 17. 3.3V DC Analog Reference Specifications

| Symbol | Description | Min | Typ | Max | Units |
|--------|---|-----------------------|-----------------------|-----------------------|-------|
| BG | Bandgap Voltage Reference | 1.28 | 1.30 | 1.32 | V |
| – | AGND = Vdd/2 ^[7] | Vdd/2 - 0.03 | Vdd/2 - 0.01 | Vdd/2 + 0.005 | V |
| – | AGND = 2 x BandGap ^[7] | Not Allowed | | | |
| – | AGND = P2[4] (P2[4] = Vdd/2) | P2[4] - 0.008 | P2[4] + 0.001 | P2[4] + 0.009 | V |
| – | AGND = BandGap ^[7] | BG - 0.009 | BG + 0.005 | BG + 0.015 | V |
| – | AGND = 1.6 x BandGap ^[7] | 1.6 x BG - 0.027 | 1.6 x BG - 0.010 | 1.6 x BG + 0.018 | V |
| – | AGND Column to Column Variation (AGND = Vdd/2) ^[7] | -0.034 | 0.000 | 0.034 | V |
| – | RefHi = Vdd/2 + BandGap | Not Allowed | | | |
| – | RefHi = 3 x BandGap | Not Allowed | | | |
| – | RefHi = 2 x BandGap + P2[6] (P2[6] = 0.5V) | Not Allowed | | | |
| – | RefHi = P2[4] + BandGap (P2[4] = Vdd/2) | Not Allowed | | | |
| – | RefHi = P2[4] + P2[6] (P2[4] = Vdd/2, P2[6] = 0.5V) | P2[4] + P2[6] - 0.075 | P2[4] + P2[6] - 0.009 | P2[4] + P2[6] + 0.057 | V |
| – | RefHi = 3.2 x BandGap | Not Allowed | | | |
| – | RefLo = Vdd/2 - BandGap | Not Allowed | | | |
| – | RefLo = BandGap | Not Allowed | | | |
| – | RefLo = 2 x BandGap - P2[6] (P2[6] = 0.5V) | Not Allowed | | | |
| – | RefLo = P2[4] – BandGap (P2[4] = Vdd/2) | Not Allowed | | | |
| – | RefLo = P2[4]-P2[6] (P2[4] = Vdd/2, P2[6] = 0.5V) | P2[4] - P2[6] - 0.048 | P2[4] - P2[6] + 0.022 | P2[4] - P2[6] + 0.092 | V |

DC Analog PSoC Block Specifications

Table 18 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 18. DC Analog PSoC Block Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-----------------|---|-----|------|-----|-------|-------|
| R _{CT} | Resistor Unit Value (Continuous Time) | – | 12.2 | – | kΩ | |
| C _{SC} | Capacitor Unit Value (Switched Capacitor) | – | 80 | – | fF | |

DC POR and LVD Specifications

Table 19 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V or 3.3V at 25°C . These are for design guidance only.

Note The bits PORLEV and VM in the table below refer to bits in the VLT_CR register.

Table 19. DC POR and LVD Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|---------------------|--|------|------|---------------------|-------|-------|
| V _{PPOR0R} | V _{dd} Value for PPOR Trip (positive ramp) PORLEV[1:0] = 00b | | 2.91 | | V | |
| V _{PPOR1R} | PORLEV[1:0] = 01b | – | 4.39 | – | V | |
| V _{PPOR2R} | PORLEV[1:0] = 10b | | 4.55 | | V | |
| V _{PPOR0} | V _{dd} Value for PPOR Trip (negative ramp) PORLEV[1:0] = 00b | | 2.82 | | V | |
| V _{PPOR1} | PORLEV[1:0] = 01b | – | 4.39 | – | V | |
| V _{PPOR2} | PORLEV[1:0] = 10b | | 4.55 | | V | |
| V _{PH0} | PPOR Hysteresis PORLEV[1:0] = 00b | – | 92 | – | mV | |
| V _{PH1} | PORLEV[1:0] = 01b | – | 0 | – | mV | |
| V _{PH2} | PORLEV[1:0] = 10b | – | 0 | – | mV | |
| V _{LVD0} | V _{dd} Value for LVD Trip VM[2:0] = 000b | 2.86 | 2.92 | 2.98 ^[8] | V | |
| V _{LVD1} | VM[2:0] = 001b | 2.96 | 3.02 | 3.08 | V | |
| V _{LVD2} | VM[2:0] = 010b | 3.07 | 3.13 | 3.20 | V | |
| V _{LVD3} | VM[2:0] = 011b | 3.92 | 4.00 | 4.08 | V | |
| V _{LVD4} | VM[2:0] = 100b | 4.39 | 4.48 | 4.57 | V | |
| V _{LVD5} | VM[2:0] = 101b | 4.55 | 4.64 | 4.74 ^[9] | V | |
| V _{LVD6} | VM[2:0] = 110b | 4.63 | 4.73 | 4.82 | V | |
| V _{LVD7} | VM[2:0] = 111b | 4.72 | 4.81 | 4.91 | V | |

Notes

8. Always greater than 50 mV above PPOR (PORLEV = 00) for falling supply.
9. Always greater than 50 mV above PPOR (PORLEV = 10) for falling supply.

DC Programming Specifications

Table 20 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 20. DC Programming Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-----------------------|--|----------------|-----|-----------------|-------|--------------------------------------|
| I_{DDP} | Supply Current During Programming or Verify | – | 15 | 30 | mA | |
| V_{ILP} | Input Low Voltage During Programming or Verify | – | – | 0.8 | V | |
| V_{IHP} | Input High Voltage During Programming or Verify | 2.1 | – | – | V | |
| I_{ILP} | Input Current when Applying V_{ilp} to P1[0] or P1[1] During Programming or Verify | – | – | 0.2 | mA | Driving internal pull-down resistor. |
| I_{IHP} | Input Current when Applying V_{ihp} to P1[0] or P1[1] During Programming or Verify | – | – | 1.5 | mA | Driving internal pull-down resistor. |
| V_{OLV} | Output Low Voltage During Programming or Verify | – | – | $V_{ss} + 0.75$ | V | |
| V_{OHV} | Output High Voltage During Programming or Verify | $V_{dd} - 1.0$ | – | V_{dd} | V | |
| Flash_{ENPB} | Flash Endurance (per block) | 50,000 | – | – | – | Erase/write cycles per block. |
| Flash_{ENT} | Flash Endurance (total) ^[10] | 1,800,000 | – | – | – | Erase/write cycles. |
| Flash_{DR} | Flash Data Retention | 10 | – | – | Years | |

Note

10. A maximum of 36 x 50,000 block endurance cycles is allowed. This may be balanced between operations on 36x1 blocks of 50,000 maximum cycles each, 36x2 blocks of 25,000 maximum cycles each, or 36x4 blocks of 12,500 maximum cycles each (to limit the total number of cycles to 36x50,000 and that no single block ever sees more than 50,000 cycles).

For the full industrial range, the user must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs Application Note AN2015 at <http://www.cypress.com> under Application Notes for more information.

AC Electrical Characteristics

AC Chip Level Specifications

Table 21 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Table 21. AC Chip Level Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|-----------------------|--|-------|------|-------------------------------|-------|--|
| F _{IMO245V} | Internal Main Oscillator Frequency for 24 MHz (5V) | 23.04 | 24 | 24.96 ^[11,12] | MHz | Trimmed for 5V operation using factory trim values. |
| F _{IMO243V} | Internal Main Oscillator Frequency for 24 MHz (3.3V) | 22.08 | 24 | 25.92 ^[12, 13] | MHz | Trimmed for 3.3V operation using factory trim values. |
| F _{IMOUSB5V} | Internal Main Oscillator Frequency with USB (5V) Frequency locking enabled and USB traffic present. | 23.94 | 24 | 24.06 ^[12] | MHz | $-10^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ $4.35 \leq V_{dd} \leq 5.15$ |
| F _{IMOUSB3V} | Internal Main Oscillator Frequency with USB (3.3V) Frequency locking enabled and USB traffic present. | 23.94 | 24 | 24.06 ^[12] | MHz | $-0^{\circ}\text{C} \leq T_A \leq 70^{\circ}\text{C}$ $3.15 \leq V_{dd} \leq 3.45$ |
| F _{CPU1} | CPU Frequency (5V Nominal) | 0.93 | 24 | 24.96 ^[11, 12] | MHz | |
| F _{CPU2} | CPU Frequency (3.3V Nominal) | 0.93 | 12 | 12.96 ^[12, 13] | MHz | |
| F _{BLK5} | Digital PSoC Block Frequency (5V Nominal) | 0 | 48 | 49.92 ^[11, 12, 14] | MHz | Refer to the AC digital block specifications. |
| F _{BLK3} | Digital PSoC Block Frequency (3.3V Nominal) | 0 | 24 | 25.92 ^[12, 14] | MHz | |
| F _{32K1} | Internal Low Speed Oscillator Frequency | 15 | 32 | 64 | kHz | |
| Jitter32k | 32 kHz Period Jitter | – | 100 | | ns | |
| Step24M | 24 MHz Trim Step Size | – | 50 | – | kHz | |
| F _{out48M} | 48 MHz Output Frequency | 46.08 | 48.0 | 49.92 ^[11, 13] | MHz | Trimmed. Utilizing factory trim values. |
| Jitter24M1 | 24 MHz Period Jitter (IMO) Peak-to-Peak | – | 300 | | ps | |
| F _{MAX} | Maximum Frequency of Signal on Row Input or Row Output. | – | – | 12.96 | MHz | |
| T _{RAMP} | Supply Ramp Time | 0 | – | – | μs | |

Figure 8. 24 MHz Period Jitter (IMO) Timing Diagram



Notes

11. 4.75V < V_{dd} < 5.25V.

12. Accuracy derived from Internal Main Oscillator with appropriate trim for V_{dd} range.

13. 3.0V < V_{dd} < 3.6V. See Application Note AN2012 "Adjusting PSoC Microcontroller Trims for Dual Voltage-Range Operation" for information on trimming for operation at 3.3V.

14. See the individual user module data sheets for information on maximum frequencies for user modules.

AC General Purpose IO Specifications

Table 22 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 22. AC GPIO Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|--------------------|--|-----|-----|-----|-------|-------------------------------|
| F_{GPIO} | GPIO Operating Frequency | 0 | – | 12 | MHz | Normal Strong Mode |
| T_{RiseF} | Rise Time, Normal Strong Mode, Cloud = 50 pF | 3 | – | 18 | ns | Vdd = 4.5 to 5.25V, 10% - 90% |
| T_{FallF} | Fall Time, Normal Strong Mode, Cloud = 50 pF | 2 | – | 18 | ns | Vdd = 4.5 to 5.25V, 10% - 90% |
| T_{RiseS} | Rise Time, Slow Strong Mode, Cloud = 50 pF | 10 | 27 | – | ns | Vdd = 3 to 5.25V, 10% - 90% |
| T_{FallS} | Fall Time, Slow Strong Mode, Cloud = 50 pF | 10 | 22 | – | ns | Vdd = 3 to 5.25V, 10% - 90% |

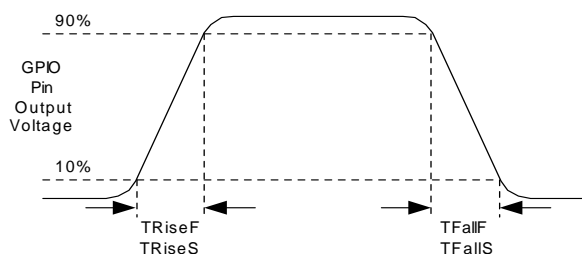
Figure 9. GPIO Timing Diagram

AC Full-Speed USB Specifications

Table 23 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-10^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-10^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 23. AC Full-Speed (12 Mbps) USB Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|----------------------|--|------------|-----|------------|-------|-----------------|
| T_{RFS} | Transition Rise Time | 4 | – | 20 | ns | For 50 pF load. |
| T_{FSS} | Transition Fall Time | 4 | – | 20 | ns | For 50 pF load. |
| T_{RFMFS} | Rise/Fall Time Matching: ($T_{\text{R}}/T_{\text{F}}$) | 90 | – | 111 | % | For 50 pF load. |
| T_{DRATEFS} | Full-Speed Data Rate | 12 - 0.25% | 12 | 12 + 0.25% | Mbps | |

AC Operational Amplifier Specifications

Table 24 and Table 25 list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Settling times, slew rates, and gain bandwidth are based on the Analog Continuous Time PSoC block.

Power = High and Opamp Bias = High is not supported at 3.3V.

Table 24. 5V AC Operational Amplifier Specifications

| Symbol | Description | Min | Typ | Max | Units |
|-------------------|---|------|-----|------|------------------|
| T _{ROA} | Rising Settling Time from 80% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain) | | | | |
| | Power = Low, Opamp Bias = Low | – | – | 3.9 | μs |
| | Power = Medium, Opamp Bias = High | – | – | 0.72 | μs |
| | Power = High, Opamp Bias = High | – | – | 0.62 | μs |
| T _{SOA} | Falling Settling Time from 20% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain) | | | | |
| | Power = Low, Opamp Bias = Low | – | – | 5.9 | μs |
| | Power = Medium, Opamp Bias = High | – | – | 0.92 | μs |
| | Power = High, Opamp Bias = High | – | – | 0.72 | μs |
| SR _{ROA} | Rising Slew Rate (20% to 80%)(10 pF load, Unity Gain) | | | | |
| | Power = Low, Opamp Bias = Low | 0.15 | – | – | V/ μs |
| | Power = Medium, Opamp Bias = High | 1.7 | – | – | V/ μs |
| | Power = High, Opamp Bias = High | 6.5 | – | – | V/ μs |
| SR _{FOA} | Falling Slew Rate (20% to 80%)(10 pF load, Unity Gain) | | | | |
| | Power = Low, Opamp Bias = Low | 0.01 | – | – | V/ μs |
| | Power = Medium, Opamp Bias = High | 0.5 | – | – | V/ μs |
| | Power = High, Opamp Bias = High | 4.0 | – | – | V/ μs |
| BW _{OA} | Gain Bandwidth Product | | | | |
| | Power = Low, Opamp Bias = Low | 0.75 | – | – | MHz |
| | Power = Medium, Opamp Bias = High | 3.1 | – | – | MHz |
| | Power = High, Opamp Bias = High | 5.4 | – | – | MHz |
| E _{NOA} | Noise at 1 kHz (Power = Medium, Opamp Bias = High) | – | 100 | – | nV/rt-Hz |

Table 25. 3.3V AC Operational Amplifier Specifications

| Symbol | Description | Min | Typ | Max | Units |
|-------------------|---|------|-----|------|------------------|
| T _{ROA} | Rising Settling Time from 80% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain) | – | – | 3.92 | μs |
| | Power = Medium, Opamp Bias = High | – | – | 0.72 | μs |
| T _{SOA} | Falling Settling Time from 20% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain) | – | – | 5.41 | μs |
| | Power = Medium, Opamp Bias = High | – | – | 0.72 | μs |
| SR _{ROA} | Rising Slew Rate (20% to 80%)(10 pF load, Unity Gain) | | | | |
| | Power = Medium, Opamp Bias = High | 0.31 | – | – | V/ μs |
| | Power = Low, Opamp Bias = Low | 2.7 | – | – | V/ μs |
| SR _{FOA} | Falling Slew Rate (20% to 80%)(10 pF load, Unity Gain) | | | | |
| | Power = Medium, Opamp Bias = High | 0.24 | – | – | V/ μs |
| | Power = Low, Opamp Bias = Low | 1.8 | – | – | V/ μs |
| BW _{OA} | Gain Bandwidth Product | | | | |
| | Power = Medium, Opamp Bias = High | 0.67 | – | – | MHz |
| | Power = Low, Opamp Bias = Low | 2.8 | – | – | MHz |
| E _{NOA} | Noise at 1 kHz (Power = Medium, Opamp Bias = High) | – | 100 | – | nV/rt-Hz |

AC Low Power Comparator Specifications

Table 26 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 2.4V to 3.0V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V at 25°C. These are for design guidance only.

Table 26. AC Low Power Comparator Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|------------|-------------------|-----|-----|-----|---------------|---|
| T_{RLPC} | LPC Response Time | – | – | 50 | μs | ≥ 50 mV overdrive comparator reference set within V_{REFLPC} . |

AC Digital Block Specifications

Table 27 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Table 27. AC Digital Block Specifications

| Function | Description | Min | Typ | Max | Units | Notes |
|-------------------|--|--------------------|-----|-------|-------|---|
| Timer | Capture Pulse Width | 50 ^[15] | – | – | ns | |
| | Maximum Frequency, No Capture | – | – | 49.92 | MHz | 4.75V < Vdd < 5.25V. |
| | Maximum Frequency, With Capture | – | – | 25.92 | MHz | |
| Counter | Enable Pulse Width | 50 ^[15] | – | – | ns | |
| | Maximum Frequency, No Enable Input | – | – | 49.92 | MHz | 4.75V < Vdd < 5.25V. |
| | Maximum Frequency, Enable Input | – | – | 25.92 | MHz | |
| Dead Band | Kill Pulse Width: | | | | | |
| | Asynchronous Restart Mode | 20 | – | – | ns | |
| | Synchronous Restart Mode | 50 ^[15] | – | – | ns | |
| | Disable Mode | 50 ^[15] | – | – | ns | |
| | Maximum Frequency | – | – | 49.92 | MHz | 4.75V < Vdd < 5.25V. |
| CRCPRS (PRS Mode) | Maximum Input Clock Frequency | – | – | 49.92 | MHz | 4.75V < Vdd < 5.25V. |
| CRCPRS (CRC Mode) | Maximum Input Clock Frequency | – | – | 24.6 | MHz | |
| SPIM | Maximum Input Clock Frequency | – | – | 8.2 | MHz | Maximum data rate at 4.1 MHz due to 2 x over clocking. |
| SPIS | Maximum Input Clock Frequency | – | – | 4.1 | MHz | |
| | Width of SS_ Negated Between Transmissions | 50 ^[15] | – | – | ns | |
| Transmitter | Maximum Input Clock Frequency | – | – | 24.6 | MHz | Maximum data rate at 3.08 MHz due to 8 x over clocking. |
| Receiver | Maximum Input Clock Frequency | – | – | 24.6 | MHz | Maximum data rate at 3.08 MHz due to 8 x over clocking. |

Note

15. 50 ns minimum input pulse width is based on the input synchronizers running at 24 MHz (42 ns nominal period).

AC External Clock Specifications

Table 28 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 28. AC External Clock Specifications

| Symbol | Description | Min | Typ | Max | Units | Notes |
|---------------------|--------------------------------|-------|-----|-------|-------|-------|
| F _{OSCEXT} | Frequency for USB Applications | 23.94 | 24 | 24.06 | MHz | |
| – | Duty Cycle | 47 | 50 | 53 | % | |
| – | Power up to IMO Switch | 150 | – | – | μs | |

AC Analog Output Buffer Specifications

Table 29 and Table 30 list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C . These are for design guidance only.

Table 29. 5V AC Analog Output Buffer Specifications

| Symbol | Description | Min | Typ | Max | Units |
|--------------------|--|------|-----|-----|-------|
| T _{ROB} | Rising Settling Time to 0.1%, 1V Step, 100pF Load Power = Low Power = High | – | – | 2.5 | μs |
| | | – | – | 2.5 | μs |
| T _{SOB} | Falling Settling Time to 0.1%, 1V Step, 100pF Load Power = Low Power = High | – | – | 2.2 | μs |
| | | – | – | 2.2 | μs |
| SR _{ROB} | Rising Slew Rate (20% to 80%), 1V Step, 100pF Load Power = Low Power = High | 0.65 | – | – | V/μs |
| | | 0.65 | – | – | V/μs |
| SR _{FOB} | Falling Slew Rate (80% to 20%), 1V Step, 100pF Load Power = Low Power = High | 0.65 | – | – | V/μs |
| | | 0.65 | – | – | V/μs |
| BW _{OBSS} | Small Signal Bandwidth, 20mV _{pp} , 3dB BW, 100pF Load Power = Low Power = High | 0.8 | – | – | MHz |
| | | 0.8 | – | – | MHz |
| BW _{OBLs} | Large Signal Bandwidth, 1V _{pp} , 3dB BW, 100pF Load Power = Low Power = High | 300 | – | – | kHz |
| | | 300 | – | – | kHz |

Table 30. 3.3V AC Analog Output Buffer Specifications

| Symbol | Description | Min | Typ | Max | Units |
|-------------------|--|-----|-----|-----|-------|
| T _{ROB} | Rising Settling Time to 0.1%, 1V Step, 100pF Load Power = Low Power = High | – | – | 3.8 | μs |
| | | – | – | 3.8 | μs |
| T _{SOB} | Falling Settling Time to 0.1%, 1V Step, 100pF Load Power = Low Power = High | – | – | 2.6 | μs |
| | | – | – | 2.6 | μs |
| SR _{ROB} | Rising Slew Rate (20% to 80%), 1V Step, 100pF Load Power = Low Power = High | 0.5 | – | – | V/μs |
| | | 0.5 | – | – | V/μs |
| SR _{FOB} | Falling Slew Rate (80% to 20%), 1V Step, 100pF Load Power = Low Power = High | 0.5 | – | – | V/μs |
| | | 0.5 | – | – | V/μs |

Table 30. 3.3V AC Analog Output Buffer Specifications (continued)

| Symbol | Description | Min | Typ | Max | Units |
|-------------------|---|-----|-----|-----|-------|
| BW _{OBS} | Small Signal Bandwidth, 20mV _{pp} , 3dB BW, 100pF Load | 0.7 | – | – | MHz |
| | Power = Low | 0.7 | – | – | MHz |
| BW _{OBS} | Large Signal Bandwidth, 1V _{pp} , 3dB BW, 100pF Load | 200 | – | – | kHz |
| | Power = High | 200 | – | – | kHz |

AC Programming Specifications

Table 31 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Table 31. AC Programming Specifications

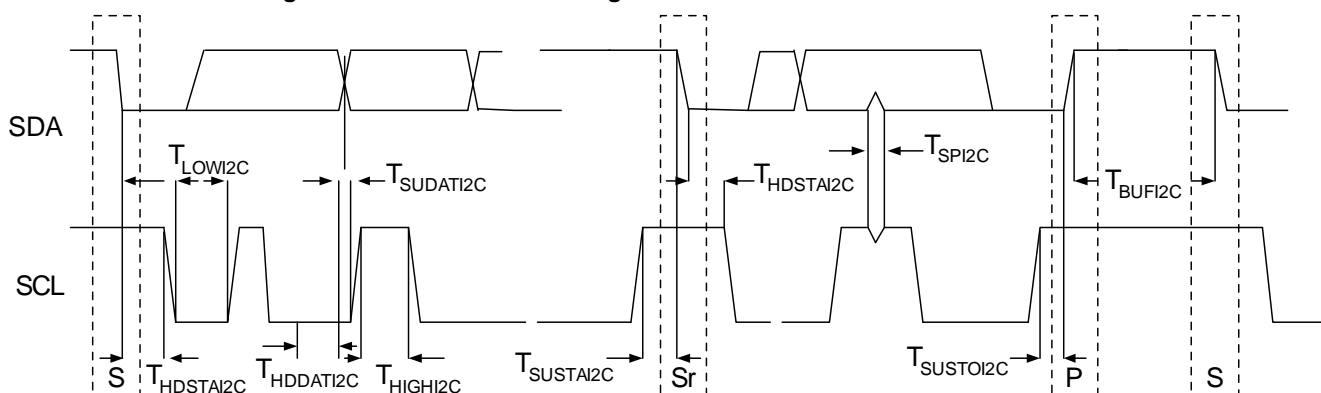
| Symbol | Description | Min | Typ | Max | Units | Notes |
|--------------------------|--|-----|-----|-----|-------|-----------------------------|
| T _{RSCLK} | Rise Time of SCLK | 1 | – | 20 | ns | |
| T _{FSCLK} | Fall Time of SCLK | 1 | – | 20 | ns | |
| T _{SSCLK} | Data Setup Time to Falling Edge of SCLK | 40 | – | – | ns | |
| T _{HSCLK} | Data Hold Time from Falling Edge of SCLK | 40 | – | – | ns | |
| F _{SCLK} | Frequency of SCLK | 0 | – | 8 | MHz | |
| T _{ERASE B} | Flash Erase Time (Block) | – | 10 | – | ms | |
| T _{WRITE} | Flash Block Write Time | – | 30 | – | ms | |
| T _{DSCLK} | Data Out Delay from Falling Edge of SCLK | – | – | 45 | ns | V _{dd} > 3.6 |
| T _{DSCLK3} | Data Out Delay from Falling Edge of SCLK | – | – | 50 | ns | 3.0 ≤ V _{dd} ≤ 3.6 |

AC I²C Specifications

Table 32 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and -40°C ≤ T_A ≤ 85°C, or 3.0V to 3.6V and -40°C ≤ T_A ≤ 85°C, respectively. Typical parameters apply to 5V and 3.3V at 25°C. These are for design guidance only.

Table 32. AC Characteristics of the I²C SDA and SCL Pins for V_{DD}

| Symbol | Description | Standard Mode | | Fast Mode | | Units | Notes |
|------------------------|--|---------------|-----|---------------------|-----|-------|-------|
| | | Min | Max | Min | Max | | |
| F _{SCL I2C} | SCL Clock Frequency | 0 | 100 | 0 | 400 | kHz | |
| T _{HDSTA I2C} | Hold Time (repeated) START Condition. After this period, the first clock pulse is generated. | 4.0 | – | 0.6 | – | μs | |
| T _{LOW I2C} | LOW Period of the SCL Clock | 4.7 | – | 1.3 | – | μs | |
| T _{HIGH I2C} | HIGH Period of the SCL Clock | 4.0 | – | 0.6 | – | μs | |
| T _{SUSTA I2C} | Setup Time for a Repeated START Condition | 4.7 | – | 0.6 | – | μs | |
| T _{HDDAT I2C} | Data Hold Time | 0 | – | 0 | – | μs | |
| T _{SUDAT I2C} | Data Setup Time | 250 | – | 100 ^[16] | – | ns | |
| T _{SUSTO I2C} | Setup Time for STOP Condition | 4.0 | – | 0.6 | – | μs | |
| T _{BUFI2C} | Bus Free Time Between a STOP and START Condition | 4.7 | – | 1.3 | – | μs | |
| T _{SPI2C} | Pulse Width of Spikes are Suppressed by the Input Filter. | – | – | 0 | 50 | ns | |

Figure 10. Definition for Timing for Fast/Standard Mode on the I²C Bus

Note

16. A Fast-Mode I²C-bus device can be used in a Standard-Mode I²C-bus system, but the requirement t_{SU, DAT} ≥ 250 ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line t_{rmax} + t_{SU, DAT} = 1000 + 250 = 1250 ns (according to the Standard-Mode I²C-bus specification) before the SCL line is released.

Packaging Information

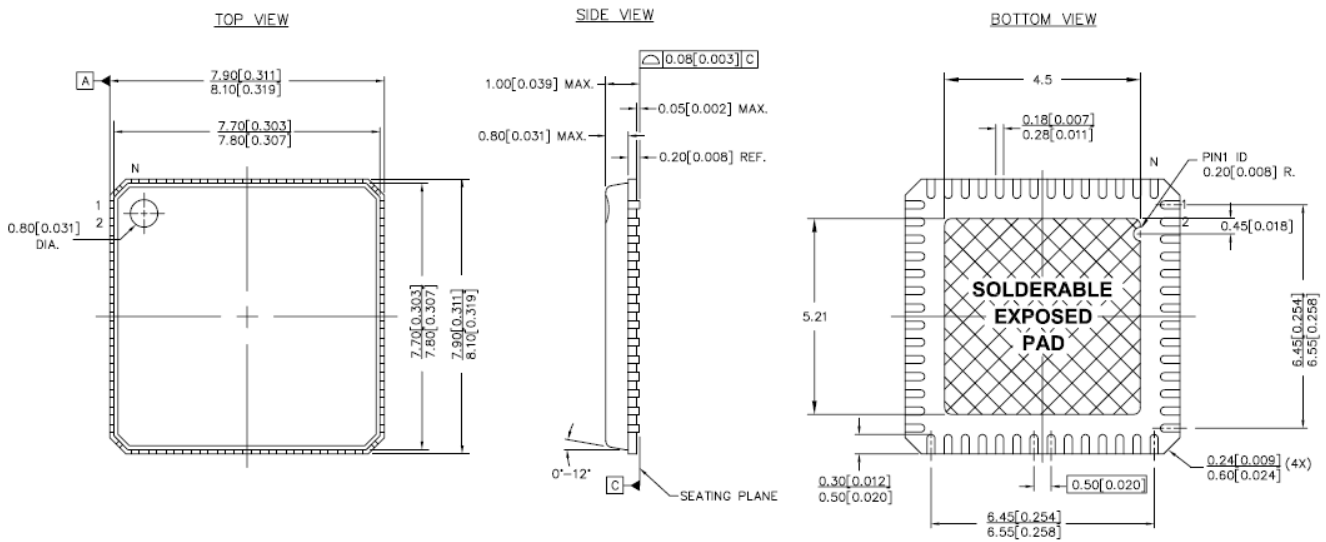
This section illustrates the package specification for the CY8CTMG120 TrueTouch devices, along with the thermal impedance for the package and solder reflow peak temperatures.

It is important to note that emulation tools may require a larger area on the target PCB than the chip's footprint. For a detailed description of the emulation tools' dimensions, refer to the document titled *PSoC Emulator Pod Dimensions* at <http://www.cypress.com/design/MR10161>.


For information on the preferred dimensions for mounting QFN packages, see the following Application Note at http://www.amkor.com/products/notes_papers/MLFAppNote.pdf.

Pinned vias for thermal conduction are not required for the low power PSoC device.

Figure 11. 56-Lead (8x8 mm) QFN



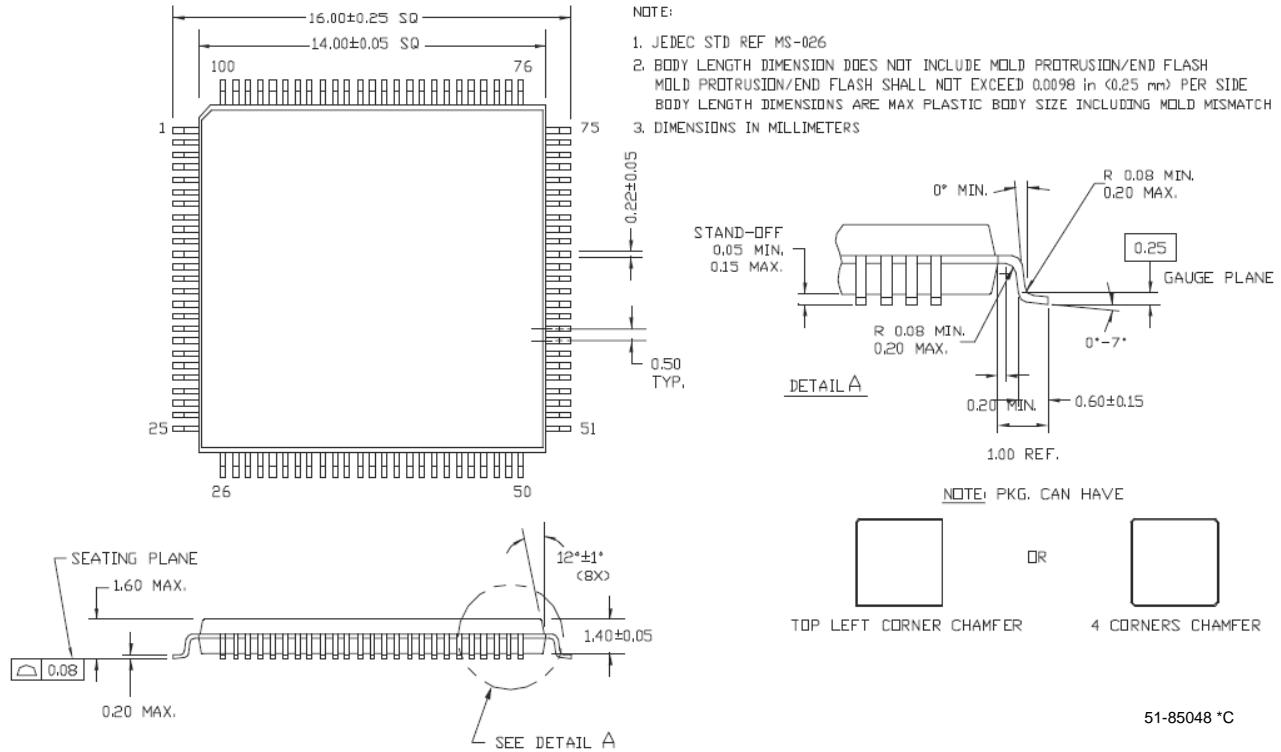
NOTES:

1.  HATCH AREA IS SOLDERABLE EXPOSED METAL.
2. REFERENCE JEDEC#: MO-220
3. PACKAGE WEIGHT: 0.162g
4. ALL DIMENSIONS ARE IN MM [MIN/MAX]
5. PACKAGE CODE

| PART # | DESCRIPTION |
|--------|-------------|
| LF56A | STANDARD |
| LY56A | PB-FREE |

001-12921 **

Figure 12. 1100-Lead (14x14 x 1.4 mm) TQFP



Thermal Impedance for the Package

| Package | Typical θ_{JA} [17] |
|-------------|----------------------------|
| 56 QFN [18] | 12.93 °C/W |
| 100 TQFP | 51 °C/W |

Solder Reflow Peak Temperature

Following is the minimum solder reflow peak temperature to achieve good solderability.

Table 33. Solder Reflow Peak Temperature

| Package | Minimum Peak Temperature [19] | Maximum Peak Temperature |
|---------|-------------------------------|--------------------------|
| 56 QFN | 240°C | 260°C |

Notes

17. $T_J = T_A + \text{Power} \times \theta_{JA}$.

18. To achieve the thermal impedance specified for the ** package, the center thermal pad is soldered to the PCB ground plane.

19. Higher temperatures is required based on the solder melting point. Typical temperatures for solder are $220 \pm 5^\circ\text{C}$ with Sn-Pb or $245 \pm 5^\circ\text{C}$ with Sn-Ag-Cu paste. Refer to the solder manufacturer specifications.

Development Tool Selection

Software

PSoC Designer

At the core of the PSoC development software suite is PSoC Designer. Used by thousands of PSoC developers, this robust software has been facilitating PSoC designs for half a decade. PSoC Designer is available free of charge at <http://www.cypress.com> under Design Resources > Software and Drivers.

PSoC Programmer

Flexible enough to be used on the bench in development, yet suitable for factory programming, PSoC Programmer works either as a standalone programming application or it can operate directly from PSoC Designer or PSoC Express. PSoC Programmer software is compatible with both PSoC ICE-Cube In-Circuit Emulator and PSoC MiniProg. PSoC programmer is available free of charge at <http://www.cypress.com/psocprogrammer>.

Hi-Tech C Lite Compiler

Hi-Tech C Lite is an ANSI C compiler optimized for PSoC to deliver dense, efficient executable code for a smaller-than-ever footprint. Hi-Tech C Lite is available for download at <http://www.cypress.htsoft.com>. To install the HI-TECH Lite version, download the compiler installation file from HI-TECH and choose the Lite option when prompted for a registration key. The Lite version can be upgraded to the 45-day full featured evaluation version or the PRO version at any time, however the PRO version can only be enabled with a purchased registration key.

Hi-Tech C Pro Compiler

Hi-Tech C Pro is an optional upgrade to PSoC Designer that offers all of the benefits of Hi-Tech C Lite with additional features. Hi-Tech C Pro is available for purchase either at the Cypress Online Store or at <http://www.cypress.htsoft.com>. Hi-Tech C Pro is recommended for touchscreen applications using the Multi-Touch All-Point CY8CTMA120 device.

CY3202-C iMAGEcraft C Compiler

CY3202 is the optional upgrade to PSoC Designer that enables the iMAGEcraft C compiler. It can be purchased from the Cypress Online Store. At <http://www.cypress.com>, click the Online Store shopping cart icon at the bottom of the web page, and click *PSoC (Programmable System-on-Chip)* to view a current list of available items.

Evaluation Tools

All evaluation tools can be purchased from the Cypress Online Store.

CY3210-MiniProg1

The CY3210-MiniProg1 kit allows a user to program PSoC devices through the MiniProg1 programming unit. The MiniProg is a small, compact prototyping programmer that connects to the PC through a provided USB 2.0 cable. The kit includes:

- MiniProg Programming Unit
- MiniEval Socket Programming and Evaluation Board
- 28-Pin CY8C29466-24PXI PDIP PSoC Device Sample
- 28-Pin CY8C27443-24PXI PDIP PSoC Device Sample
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

Device Programmers

All device programmers can be purchased from the Cypress Online Store.

CY3216 Modular Programmer

The CY3216 Modular Programmer kit features a modular programmer and the MiniProg1 programming unit. The modular programmer includes three programming module cards and supports multiple Cypress products. The kit includes:

- Modular Programmer Base
- 3 Programming Module Cards
- MiniProg Programming Unit
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

CY3207ISSP In-System Serial Programmer (ISSP)

The CY3207ISSP is a production programmer. It includes protection circuitry and an industrial case that is more robust than the MiniProg in a production-programming environment.

Note: CY3207ISSP needs special software and is not compatible with PSoC Programmer. The kit includes:

- CY3207 Programmer Unit
- PSoC ISSP Software CD
- 110 ~ 240V Power Supply, Euro-Plug Adapter
- USB 2.0 Cable

Accessories (Emulation and Programming)

Third Party Tools

Several tools have been specially designed by the following 3rd-party vendors to accompany PSoC devices during development and production. Specific details for each of these tools can be found at <http://www.cypress.com> under Design Resources > Evaluation Boards.

Build a PSoC Emulator into Your Board

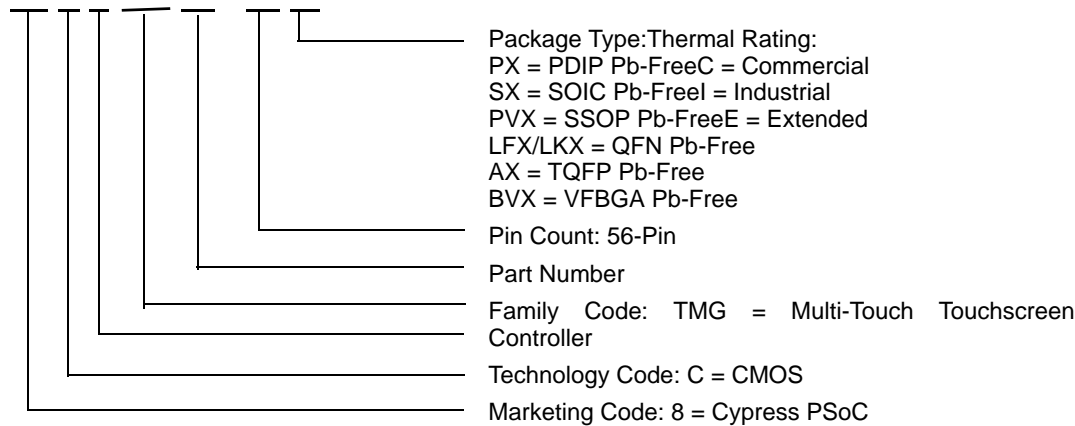
For details on how to emulate your circuit before going to volume production using an on-chip debug (OCD) non-production PSoC device, see application note AN2323 “Debugging - Build a PSoC Emulator into Your Board”.

Ordering Information.

| Package | Ordering Code | Flash (Bytes) | SRAM (Bytes) | Temperature Range | Single-Touch Enabled | Multi-Touch Gesture Enabled | Multi-Touch All-Point Enabled | X/Y Sensor Inputs |
|-------------------------------------|--------------------|---------------|--------------|-------------------|----------------------|-----------------------------|-------------------------------|-------------------|
| 56-Pin (8x8 mm) QFN | CY8CTMG120-56LFXI | 16K | 1K | -40C to +85C | Y | Y | N | Up to 44 |
| 56-Pin (8x8 mm) QFN (Tape and Reel) | CY8CTMG120-56LFXIT | 16K | 1K | -40C to +85C | Y | Y | N | Up to 44 |
| 100-Pin OCD TQFP | CY8CTMG120-00AXI | 16K | 1K | -40C to +85C | Y | Y | N | Up to 44 |

Ordering Code Definitions

CY 8 C TMG xxx-56xx



Document History Page

| Document Title: CY8CTMG120 TrueTouch™ Multi-Touch Gesture Touchscreen Controller | | | | |
|--|---------|-----------------|-----------------|--|
| Document Number: 001-46929 | | | | |
| Revision | ECN | Orig. of Change | Submission Date | Description of Change |
| ** | 2518134 | DSO/AESA | 06/18/08 | New data sheet |
| *A | 2523303 | DSO/PYRS | 06/30/08 | Updated X/Y sensor inputs to 44 and supported screen sizes to 8.4" and below |
| *B | 2549257 | YOM/PYRS | 08/06/08 | Added other sections based on PSoC data sheets |

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