

MiniSKiiP® 1 PIM
Output Inverter Application
1200V / 8A
General conditions
3phase SPWM

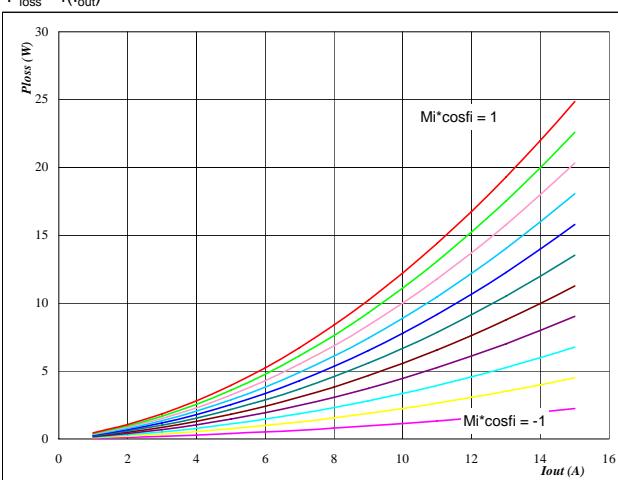
V_{GEon}	=	15 V
V_{GEoff}	=	-15 V
R_{gon}	=	64 Ω
R_{goff}	=	64 Ω

Figure 1

IGBT

Typical average static loss as a function of output current

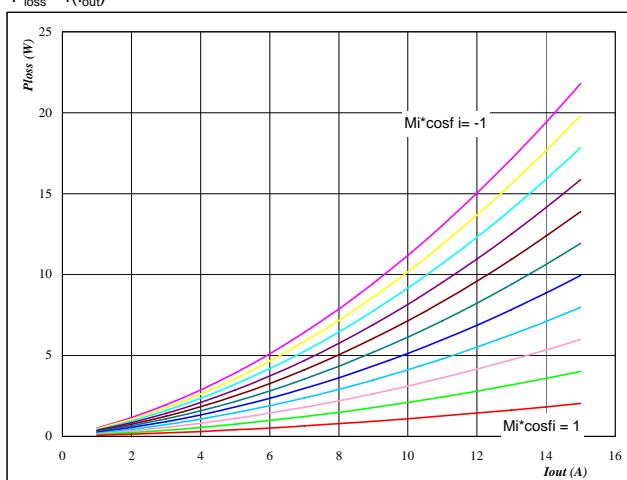
$$P_{loss} = f(I_{out})$$

**Figure 2**

FRED

Typical average static loss as a function of output current

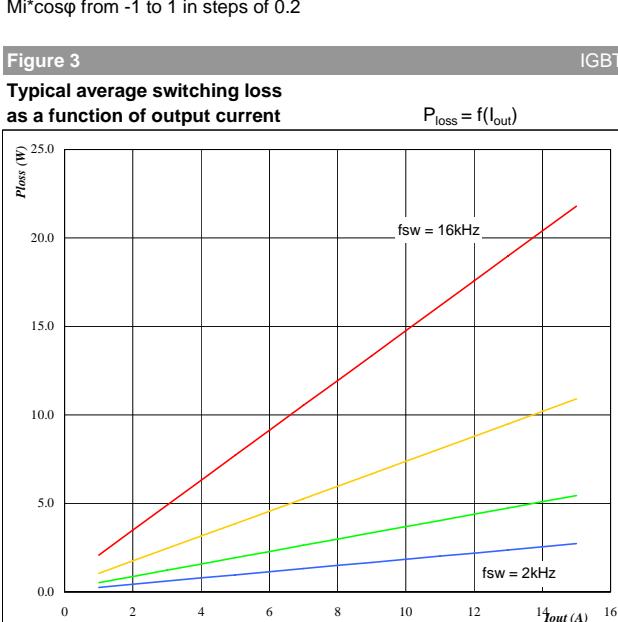
$$P_{loss} = f(I_{out})$$

**Figure 3**

IGBT

Typical average switching loss as a function of output current

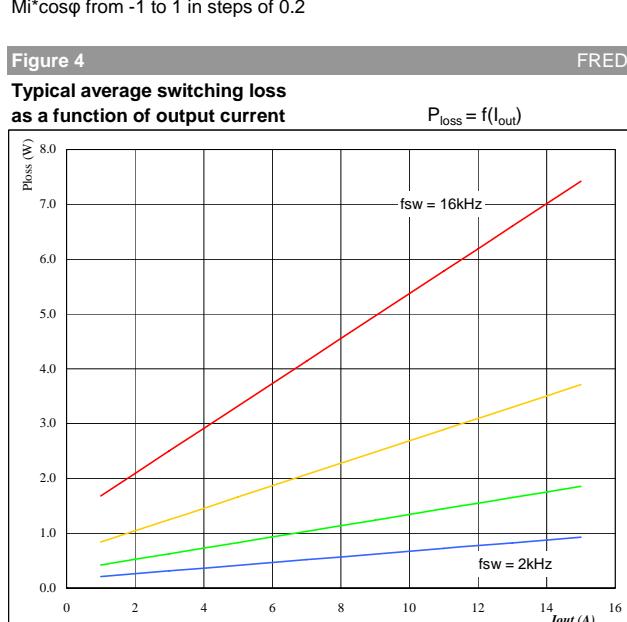
$$P_{loss} = f(I_{out})$$

**Figure 4**

FRED

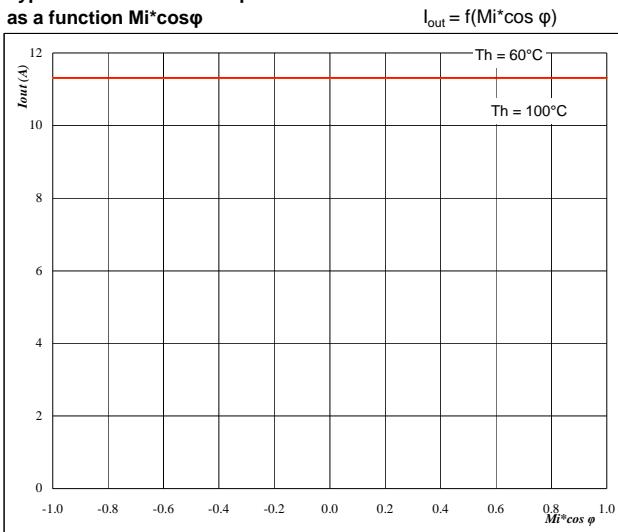
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$



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Figure 5

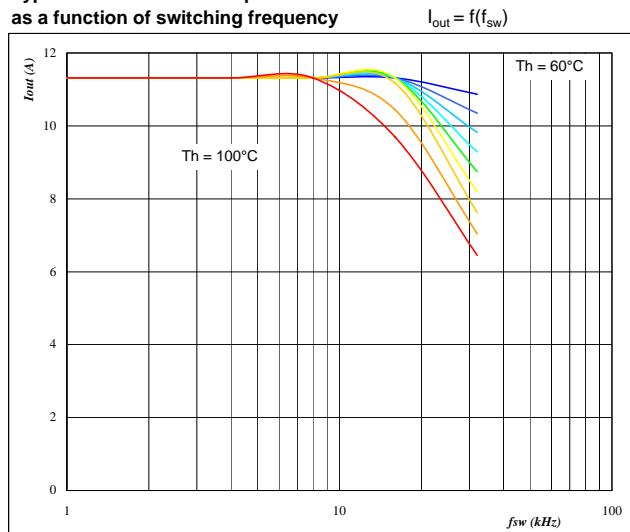
Typical available 50Hz output current as a function $M_i \cos \varphi$

**At**

$T_j = 150^\circ\text{C}$
DC link = 600 V
 $f_{sw} = 4\text{ kHz}$
 T_h from 60°C to 100°C in steps of 5°C

Phase**Figure 6**

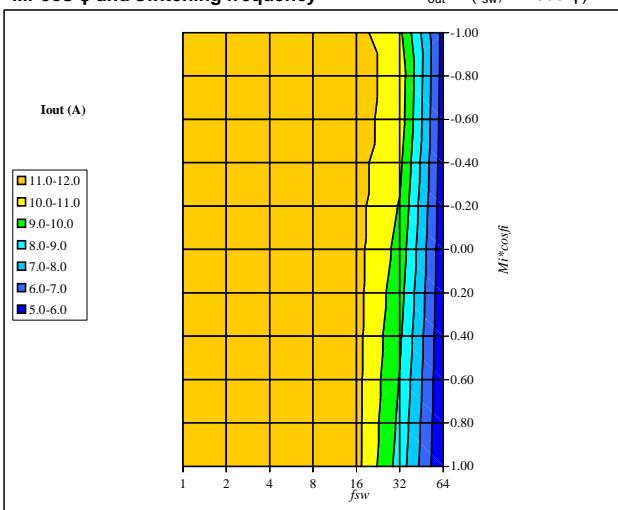
Typical available 50Hz output current as a function of switching frequency

**At**

$T_j = 150^\circ\text{C}$
DC link = 600 V
 $M_i \cos \varphi = 0.8$
 T_h from 60°C to 100°C in steps of 5°C

Figure 7

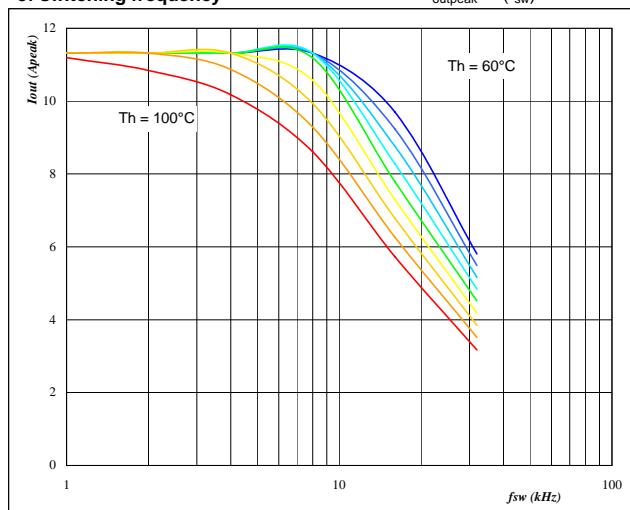
Typical available 50Hz output current as a function of $M_i \cos \varphi$ and switching frequency

**At**

$T_j = 150^\circ\text{C}$
DC link = 600 V
 $T_h = 80^\circ\text{C}$

Phase**Figure 8**

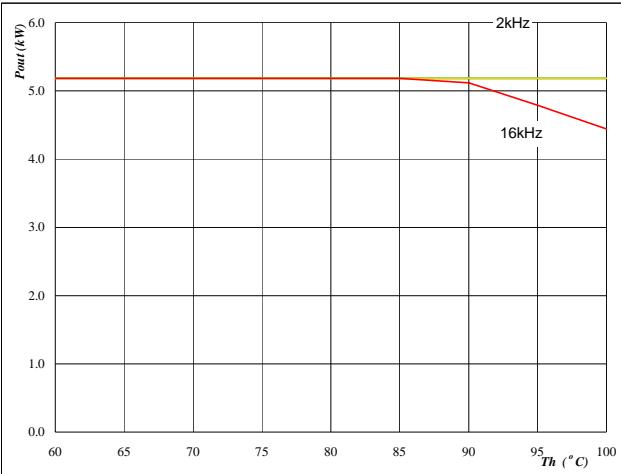
Typical available 0Hz output current as a function of switching frequency

**At**

$T_j = 150^\circ\text{C}$
DC link = 600 V
 T_h from 60°C to 100°C in steps of 5°C
 $M_i = 0$

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Figure 9

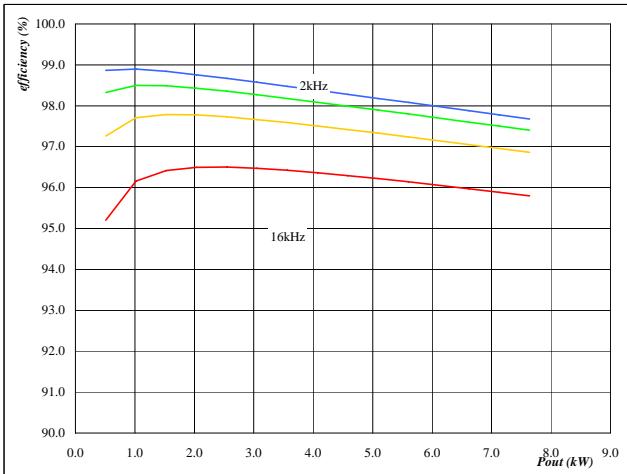
Typical available peak output power as a function of heatsink temperature
 $P_{out}=f(T_h)$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Inverter**Figure 10**

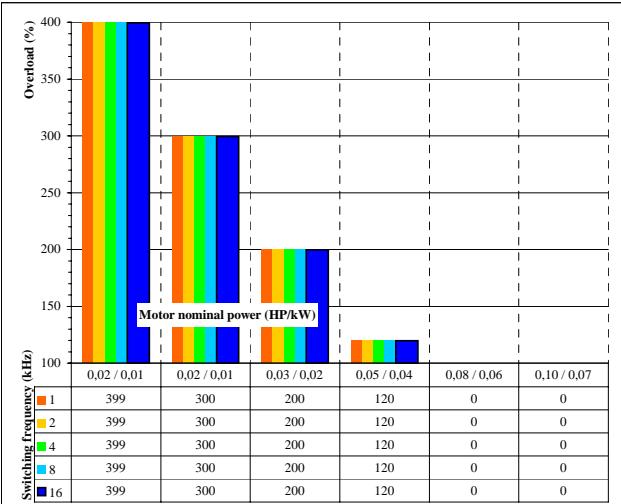
Typical efficiency as a function of output power
 $\text{efficiency}=f(P_{out})$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 11

Typical available overload factor as a function of motor power and switching frequency
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos \varphi = 0.8$
 f_{sw} from 1 kHz to 16 kHz in steps of factor 2
 $T_h = 80 \text{ } ^\circ\text{C}$
 Motor eff = 0.85