PT6360 Series

EXCALIBUR

11 A 12-V Input Adjustable Integrated Switching Regulator

SLTS179A - JANUARY 2003 - REVISED APRIL 2003



Features

- 12 V Input
- 11 A Output Current
- DSP Compatible
- >90 % Efficiency
- Adjustable Output Voltage
- On/Off Inhibit Function
- Over-Current Protection
- Output Remote Sense
- Low-Profile (8 mm)
- Small Footprint (0.64 in², Suffix 'N')
- Surface Mountable
- IPC Lead Free 2

Description

The PT6360 Excalibur™ series of integrated switching regulators (ISRs) combines outstanding power density with a comprehensive list of features. They are an ideal choice for applications where board space is a premium and performance cannot be compromised. These modules provide up to 11 A of output current, yet are housed in a low-profile, 12-pin, package that is almost half the size of the previous product generation. The integral copper case construction requires no heatsink, and offers the advantages of solderability and a small footprint (0.64 in² for suffix 'N'). Both through-hole and surface mount pin configurations are available.

The PT6360 series operates from a 12-V input bus and provides a convenient point-of-load power source for the industry's latest high-performance DSPs and microprocessors. The series includes output voltage options as low as 1.0 VDC.

Other features include external output voltage adjustment, on/off inhibit, short circuit protection, and an output remote sense.

Ordering Information

PT6361❒	= 5.0 Volts
PT6362❒	= 3.3 Volts
PT6363❒	= 2.5 Volts
PT6364❒	= 1.8 Volts
PT6365❒	= 1.5 Volts
PT6366❒	= 1.2 Volts
PT6367❒	= 1.0 Volts

PT Series Suffix (PT1234x)

Case/Pin Configuration	Order Suffix	Package Code
Vertical	**N**	(EPH)
Horizontal	**A**	(EPJ)
SMD	**C**	(EPK)

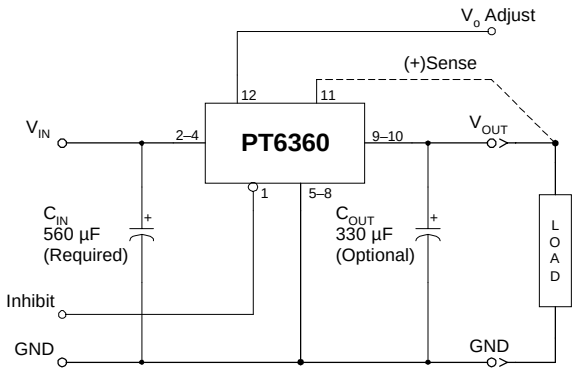
(Reference the applicable package code drawing for the dimensions and PC board layout)

Pin-Out Information

Pin	Function
1	Inhibit*
2	V_{in}
3	V_{in}
4	V_{in}
5	GND
6	GND
7	GND
8	GND
9	V_{out}
10	V_{out}
11	(+)Sense
12	V_o Adjust

** Denotes negative logic:*
Open = Output enabled
Ground = Output disabled

Standard Application



C_{in} = Required 560 µF
C_{out} = Optional 330 µF

Performance Specifications (Unless otherwise stated, T_a =25 °C, V_{in} =12 V, C_{in} =560 µF, C_{out} =0 µF, and I_o =$I_o$max)

Characteristics	Symbols	Conditions	PT6360 SERIES Min	Typ	Max	Units
Output Current	I_o	V_{in} =12 V, V_o < 3.3 V	0	—	11	A
		V_o ≥ 3.3 V	0	—	10	
Input Voltage Range	V_{in}	Over I_o range	10.8	—	13.2	V
Set-Point Voltage Tolerance	V_o tol		—	—	±2	%V_o
Temperature Variation	ΔReg_{temp}	–40 °C <T_a < +85 °C	—	±0.5	—	%V_o
Line Regulation	ΔReg_{line}	Over V_{in} range	—	±3	—	mV
Load Regulation	ΔReg_{load}	Over I_o range	—	±5	—	mV
Total Output Variation	ΔReg_{tot}	Includes set-point, line, load, –40 °C ≤ T_a ≤ +85 °C	—	—	±3	%V_o
Efficiency	η	I_o =8 A, PT6361 (5 V)	—	93	—	%
		PT6362 (3.3 V)	—	91	—	
		PT6363 (2.5 V)	—	90	—	
		PT6364 (1.8 V)	—	87	—	
		PT6365 (1.5 V)	—	85	—	
		PT6366 (1.2 V)	—	82	—	
		PT6367 (1.0 V)	—	80	—	
V_o Ripple (pk-pk)	V_r	20 MHz bandwidth, V_o = 5.0 V	—	50	—	mV_{pp}
		V_o = 3.3 V	—	25	—	
		V_o ≤ 2.5 V	—	15	—	
Transient Response		1 A/µs load step, 50 to 100 % $I_o$max, C_{out} =330 µF				
	t_{tr}	Recovery Time	—	50	—	µSec
	ΔV_{tr}	V_o over/undershoot	—	70	—	mV
Over-Current Threshold	I_{TRIP}	Reset, followed by auto-recovery	—	16	—	A
Output Voltage Adjust	V_o adj	With V_o Adjust	—	±15 (1)	—	%
Switching Frequency	f_s	Over V_{in} and I_o ranges	300	350	400	kHz
Inhibit Control (pin1)		Referenced to GND (pins 5–8)				
Input High Voltage	V_{IH}		2	—	Open (2)	V
Input Low Voltage	V_{IL}		–0.2	—	0.3	
Input Low Current	I_{IL}	Pin 1 to GND	—	–10	—	µA
Standby Input Current	I_{in} standby	Pin 1 to GND	—	5	—	mA
External Input Capacitance	C_{in}		560 (3)	—	—	µF
External Output Capacitance	C_{out}		0	330 (4)	5,000	µF
Operating Temperature Range	T_a	Over V_{in} range	–40	—	85 (5)	°C
Solder Reflow Temperature	T_{reflow}	Surface temperature of pins or case	—	—	215 (6)	°C
Storage Temperature	T_s	—	–40	—	125	°C
Reliability	MTBF	Per Bellcore TR-332 50% stress, T_a =40°C, ground benign	8.0	—	—	10^6 Hrs
Mechanical Shock		Mil-STD-883D, Method 2002.3 Half Sine, mounted to a fixture	—	500	—	G's
Mechanical Vibration		Mil-STD-883D, Method 2007.2, 20-2000 Hz, PCB mounted	—	20 (7)	—	G's
Weight	—	—	—	10	—	grams
Flammability	—	Materials meet UL 94V-0				

Notes: *(1) This is a typical value. For the adjustment limits of a specific model consult the related application note on output voltage adjustment.*

(2) The Inhibit control (pin 1) has an internal pull-up to Vin, and if left open-circuit the module will operate when input power is applied. A small low-leakage (<100 nA) MOSFET is recommended to control this input. See application notes for more information.

(3) A 560 µF electrolytic input capacitor is required for proper operation. The capacitor must be rated for a minimumm of 1.3 Arms of ripple current.

(4) An external output capacitor is not required for basic operation. Adding 330µF of distributed capacitance at the load will improve the transient response, and reduce output ripple voltage.

(5) See SOA curves or consult factory for the appropriate derating.

(6) During solder reflow of SMD package version do not elevate the module case, pins, or internal component temperatures above a peak of 215 °C. For further guidance refer to the application note, "Reflow Soldering Requirements for Plug-in Power Surface Mount Products," (SLTA051).

(7) The case pins on the through-hole package types (suffixes N & A) must be soldered. For more information see the applicable package outline drawing.

Pin Descriptions

Vin: The positive supply voltage input for the module with respect to the common *GND*.

Vout: This is the regulated output voltage from the module with respect to the common *GND*.

GND: The common node to which the input, output, and external control signals are referenced.

Inhibit*: This is an open-collector (open-drain) negative logic input, that is referenced to *GND*. Driving this pin to *GND* disables the module's output voltage. If *Inhibit** is left open-circuit, the output will be active whenever a valid input source is applied.

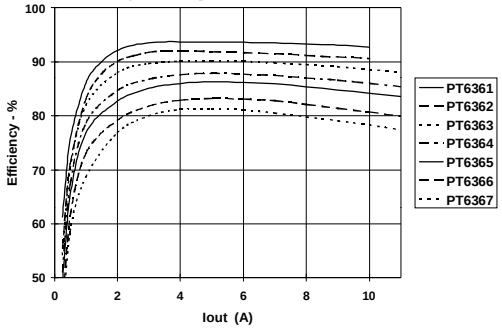
V_o Adjust: This pin is used to trim the output voltage to a value within the range of approximately ±15 % of nominal. The adjustment method uses an external resistor. The resistor is connected from *V_o Adjust* to either the *GND* or *(+)Sense*, in order to adjust the output either up or down, respectively.

(+)Sense: An external remote sense input is provided to allow the regulation circuit to compensate for voltage drop between the module and the load. For optimal voltage accuracy *(+)Sense* should be connected to V_{out}. If desired, *(+)Sense* may also be left open circuit.

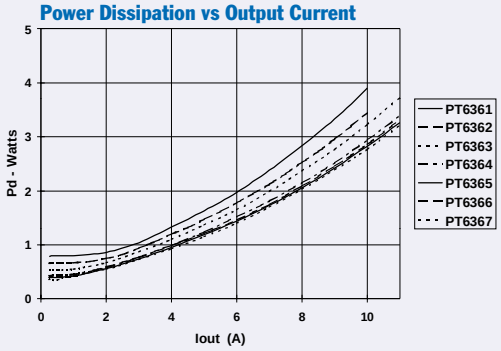
Typical Characteristics

Performance Data; V_{in} =12 V (See Note A)

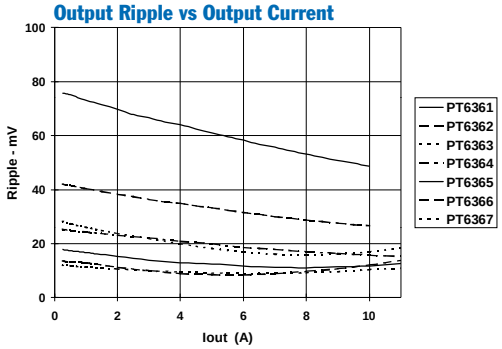
Efficiency vs Output Current



Power Dissipation vs Output Current



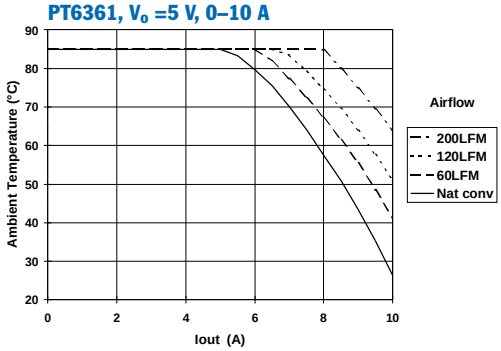
Output Ripple vs Output Current



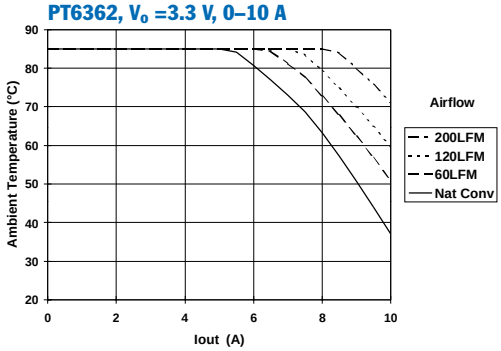
Note A: *Characteristic data has been developed from actual products tested at 25°C. This data is considered typical data for the ISR.*

Safe Operating Curves, V_{in} =12 V (See Note B)

PT6361, V_o =5 V, 0–10 A

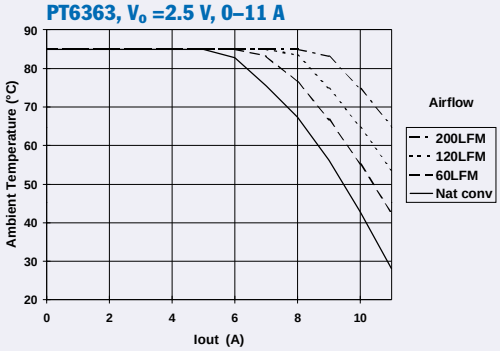


PT6362, V_o =3.3 V, 0–10 A

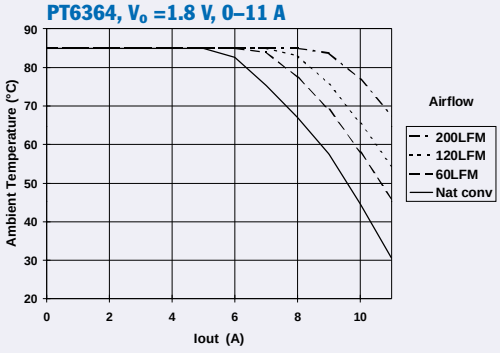


Safe Operating Curves, V_{in} =12 V (See Note B)

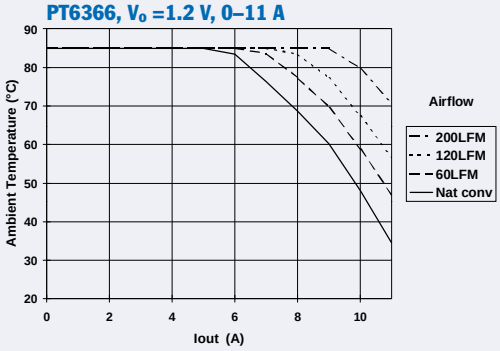
PT6363, V_o =2.5 V, 0–11 A



PT6364, V_o =1.8 V, 0–11 A



PT6366, V_o =1.2 V, 0–11 A



Note B: *SOA curves represent operating conditions at which internal components are at or below manufacturer's maximum rated operating temperatures.*

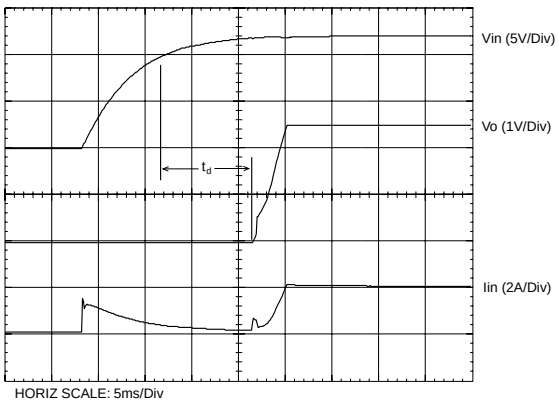
Operating Features and System Considerations for the PT6360 Regulator Series

The PT6360 is a series of integrated switching regulators (ISRs) that operate off a 12-V input to provide step-down voltage conversion for output loads of up to 11 A.

Power up & Soft-Start Timing

Following either the application of a valid input source voltage, or the removal of a ground signal to the *Inhibit* control pin (with input power applied), the regulator will initiate a soft-start power up. A soft start slows the rate at which the output voltage rises and introduces a short time delay, t_d (approx. 10 ms), into the power-up sequence. Figure 1-1 shows the power-up characteristic of a PT6363 (2.5-V output) with an 8.3-A load. Note that the initial step of input current when the input voltage begins to rise is the input capacitor(s) charging.

Figure 1-1



Over-Current Protection

To protect against load faults, these ISRs incorporate output over-current protection. Applying a load that exceeds the over-current threshold (see data sheet specifications) will cause the regulated output to shut down. Following shutdown the ISR will periodically attempt to recover by initiating a soft-start power-up. This is often described as a “hiccup” mode of operation, whereby the module continues in a cycle of successive shutdown and power up until the load fault is removed. During this period, the average current flowing into the fault is significantly reduced. Once the fault is removed, the converter automatically recovers and returns to normal operation.

Output Remote Sense

The *(+)Sense* pin allows the regulator to compensate for limited amounts of ‘IR’ voltage drop in the positive output connection resistance. This is the voltage drop incurred in the PCB trace between *Vout* (pins 9 & 10) of the regulator and the load some distance away. Connecting *(+)Sense* to the positive load terminal improves the voltage regulation at the load, particularly when the load current fluctuates. Although not recommended, leaving *(+)Sense* disconnected will not damage the regulator or the load circuitry. An internal 10 Ω resistor, connected between the sense pin and the output, keeps the output voltage in regulation.

With the sense pin connected, the difference between the voltage measured between V_{out} and *GND* at the regulator, and that measured from *(+)Sense* to *GND*, is the amount of IR drop being compensated by the regulator. This should be limited to 0.3 V maximum.

Note: The remote sense feature is not designed to compensate for the forward drop of non-linear or frequency dependent components that may be placed in series with the converter output. Examples include OR-ing diodes, filter inductors, ferrite beads, and fuses. When these components are enclosed by the remote sense connections they are effectively placed inside the regulation control loop, which can adversely affect the stability of the regulator.

Capacitor Recommendations for the PT6360 Series of Integrated Switching Regulators

Input Capacitor:

The recommended input capacitance is determined by 1.3-A minimum ripple current rating and 560 µF minimum capacitance.

Ripple current and <100 mΩ equivalent series resistance (ESR) values are the major considerations, along with temperature, when designing with different types of capacitors. Tantalum capacitors have a recommended minimum voltage rating of 2 × (max. dc voltage + ac ripple). This is necessary to insure reliability for input voltage bus applications.

Output Capacitors:

The recommended ESR of the output capacitor is 150mΩ. Electrolytic capacitors have marginal ripple performance at frequencies greater than 400kHz but excellent low frequency transient response. Above the ripple frequency, ceramic capacitors are necessary to improve the transient response and reduce any high frequency noise components apparent during higher current excursions. Preferred low ESR type capacitor part numbers are identified in Table 2-1.

Tantalum Capacitors

Tantalum type capacitors can be used for the output but only the AVX TPS, Sprague 593D/594/595 or Kemet T495/T510 series. These capacitors are recommended over many other tantalum types due to their higher rated surge, power dissipation, and ripple current capability. As a caution the TAJ series by AVX is not recommended. This series has considerably higher ESR, reduced power dissipation, and lower ripple current capability. The TAJ series is less reliable than the AVX TPS series when determining power dissipation capability. Tantalum or Oscon® types are recommended for applications where ambient temperatures fall below 0 °C.

Capacitor Table

Table 2-1 identifies the characteristics of capacitors from a number of vendors with acceptable ESR and ripple current (rms) ratings. The number of capacitors required at both the input and output buses is identified for each capacitor type.

This is not an extensive capacitor list. Capacitors from other vendors are available with comparable specifications. Those listed are for guidance. The RMS ripple current rating and ESR (Equivalent Series Resistance at 100 kHz) are critical parameters necessary to insure both optimum regulator performance and long capacitor life.

Table 2-1: Input/Output Capacitors

Capacitor Vendor/ Series	Capacitor Characteristics					Quantity		
	Working Voltage	Value (µF)	(ESR) Equivalent Series Resistance	105 °C Maximum Ripple Current (Irms)	Physical Size (mm)	Input Bus	Output Bus	Vendor Part Number
Panasonic FC (Radial)	35 V 25 V 25 V	680 330 1000	0.043 Ω 0.090 Ω 0.038 Ω	1655 mA 755 mA 1690mA	12.5×20 10×12.5 16×15	1 N/R (1) 1	1 1 1	EEUFC1V681 EEUFC1E331 EEUFC1E102S
FC/FK (Surface Mtg)	50 V 35 V	1000 680	0073 Ω 0.060 Ω	1610 mA 1100 mA	16×16.5 12.5×13.5	1 1 (2)	1 1	EEVFK1H102M EEVFK1V681Q **(Vo<2.6 V)**
United Chemi-con LXZ/LXV Series MVY (Surface Mtg)	35 V 35 V 25 V	680 680 330	0.037 Ω 0.068 Ω 0.15 Ω	1660 mA 1050 mA 670 mA	12.5×20 10×16 10×10.3	1 1 (2) N/R (1)	1 1 1	LXZ35VB681M12X20LL LXV35VB102M16X20LL **(Vo<2.6 V)** MVY25VC331M10X10TP
Nichicon PM Series	35 V 25 V 35 V	560 1200 820	0.048 Ω 0.039 Ω 0.038 Ω	1360 mA 1400 mA 1370 mA	16×15 16×15 18×15	1 1 1	1 1 1	UPM1V561MHH6 UPM1E122MHH6 UPM1V821MHH6
Os-con: SS SVP (surface Mount) Old SV Series	 10 V 16 V	 330 330	 0.025 Ω 0.016 Ω	 3500 mA 4700 mA	 10×10.5 11×12	 N/R (1) 2	 1 1	 10SS330M **(V_o<5.1 V)** 16SVP330M
AVX Tantalum TPS (Surface Mtgt)	10 V 10 V	330 330	0.1 Ω 0.06 Ω	>2500 mA >3000 mA	7.3L ×5.7W ×4.1H	N/R (1) N/R (1)	1 1	TPSE337M010R0100 **(V_o<5.1 V)** TPSV337M010R0060 **(V_o<5.1 V)**
Kemet Tantalum T520/T495 Series (Surface Mount)	10 V 6.3 V	330 220	0.040 Ω 0.07 Ω	1600 mA >2000 mA	4.3W ×7.3L ×4.0H	N/R (1) N/R (1)	1 1	520X337M010AS T495X227M0100AS
Sprague Tantalum 594D Series (Surface Mount)	10 V	330	0.045 Ω	2360 mA	7.2L ×6W ×4.1H	N/R (1)	1	594D337X0010R2T

(1) N/R –Not recommended. The voltage rating does not meet the minimum operating limits.
(2) Recommended Input capacitor when V_o<2.6 V; lower RMS mA required .

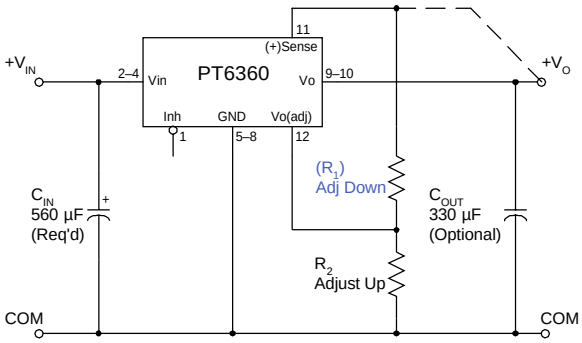
Adjusting the Output Voltage of the PT6360 Series of Integrated Switching Regulators

The output voltage of the PT6360 series of power modules may be adjusted higher or lower than the pre-set voltage with the addition of a single external resistor. Table 3-1 gives the allowable adjustment range for each model of the series as V_a (min) and V_a (max). The value of the external resistor can either be calculated using the formulas given below, or simply selected from the range of values given in Table 3-2. Refer to Figure 3-1 for the placement of the required resistor. Use the resistor R_1 to adjust up, and the resistor (R_2) to down.

Adjust Up: An increase in the output voltage is obtained by adding a resistor R_2, between *V_o adjust* (pin 12) and *GND* (pins 5-8).

Adjust Down: Add a resistor (R_1), between *V_o adjust* (pin 12) and *(+)Sense* (pin 11).

Figure 3-1



The values of (R_1) [adjust down], and R_2 [adjust up], can be calculated using the following formulas. Refer to Figure 3-1 for the placement of the required resistor; either (R_1) or R_2 as appropriate.

$$(R_1) = \frac{R_o\,(V_a - 0.8)}{V_o - V_a} - R_s \quad k\Omega$$

$$R_2 = \frac{0.8\,R_o}{V_a - V_o} - R_s \quad k\Omega$$

Where: V_o = Original output voltage
V_a = Adjusted output voltage
R_o = The resistance value from Table 3-1
R_s = The series resistance from Table 3-1

Notes:

1. Use a 1% (or better) tolerance resistor in either the (R_1) or R_2 location. Place the resistor as close to the ISR as possible.
2. Never connect capacitors from *V_o Adjust* to either *GND* or *V_{out}*. Any capacitance added to the *V_o Adjust* pin will affect the stability of the ISR.
3. If the remote sense feature is not being used, the adjust resistor (R_1) can also be connected to *V_{out}*, (pins 9–10) instead of *(+)Sense*.

Table 3-1

ISR OUTPUT VOLTAGE ADJUSTMENT RANGE AND FORMULA PARAMETERS

Series Pt. No.	PT6361	PT6362	PT6363	PT6364	PT6365	PT6366	PT6367
V_o (nom)	5.0 V	3.3 V	2.5 V	1.8 V	1.5 V	1.2 V	1.0 V
V_a (min)	3.35 V	2.6 V	2.0 V	1.52 V	1.31 V	1.1 V	0.95 V
V_a (max)	5.5 V	3.63 V	2.8 V	2.1 V	1.82 V	1.52 V	1.32 V
R_o (kΩ)	10.0	10.2	10.7	10.2	9.76	10.0	10.2
R_s (kΩ)	15.0	24.9	24.9	24.9	24.9	24.9	24.9

Table 3-2

ISR ADJUSTMENT RESISTOR VALUES

Series Pt. No.	PT6361	PT6362
V_o (nom)	5.0 V	3.3 V
V_a (req.d)		
5.50	1.0 kΩ	
5.40	5.0 kΩ	
5.30	11.7 kΩ	
5.20	25.0 kΩ	
5.10	65.0 kΩ	
5.00		
4.90	(395.0) kΩ	
4.80	(185.0) kΩ	
4.70	(115.0) kΩ	
4.60	(80.0) kΩ	
4.50	(59.0) kΩ	
4.40	(45.0) kΩ	
4.30	(35.0) kΩ	
4.20	(27.5) kΩ	
4.10	(21.7) kΩ	
4.00	(17.0) kΩ	
3.90	(13.2) kΩ	
3.80	(10.0) kΩ	
3.70	(7.3) kΩ	
3.60	(5.0) kΩ	2.3 kΩ
3.55	(4.0) kΩ	7.7 kΩ
3.50	(3.0) kΩ	15.9 kΩ
3.45	(2.1) kΩ	29.5 kΩ
3.40	(1.3) kΩ	56.7 kΩ
3.35	(0.5) kΩ	138.0 kΩ
3.30		
3.25		(475.0) kΩ
3.20		(220.0) kΩ
3.15		(135.0) kΩ
3.10		(92.4) kΩ
3.05		(66.9) kΩ
3.00		(49.9) kΩ
2.95		(37.5) kΩ
2.90		(28.6) kΩ
2.85		(21.6) kΩ
2.80		(15.9) kΩ
2.75		(11.3) kΩ
2.70		(7.4) kΩ
2.65		(4.1) kΩ
2.60		(1.3) kΩ

	PT6363	PT6364	PT6365	PT6366	PT6367
	2.5 V	1.8 V	1.5 V	1.2 V	1.0 V
V_a (req.d)					
2.800	3.6 kΩ				
2.750	9.3 kΩ				
2.700	17.9 kΩ				
2.650	32.2 kΩ				
2.600	60.7 kΩ				
2.550	146.0 kΩ				
2.500					
2.450	(328.0) kΩ				
2.400	(146.0) kΩ				
2.350	(85.7) kΩ				
2.300	(55.3) kΩ				
2.250	(37.2) kΩ				
2.200	(25.0) kΩ				
2.150	(16.4) kΩ				
2.100	(9.9) kΩ	2.3 kΩ			
2.050	(4.8) kΩ	7.7 kΩ			
2.000	(0.8) kΩ	15.9 kΩ			
1.950		29.5 kΩ			
1.900		56.7 kΩ			
1.850		138.0 kΩ			
1.800			1.1 kΩ		
1.750		(169.0) kΩ	6.3 kΩ		
1.700		(66.9) kΩ	14.1 kΩ		
1.650		(32.9) kΩ	27.2 kΩ		
1.600		(15.9) kΩ	53.2 kΩ		
1.550		(5.7) kΩ	131.0 kΩ		
1.500				1.8 kΩ	
1.475			(239.0) kΩ	4.2 kΩ	
1.450			(102.0) kΩ	7.1 kΩ	
1.425			(56.4) kΩ	10.7 kΩ	
1.400			(33.7) kΩ	15.1 kΩ	
1.375			(20.0) kΩ	20.8 kΩ	
1.350			(10.9) kΩ	28.4 kΩ	
1.325			(4.4) kΩ	39.1 kΩ	
1.300				55.1 kΩ	2.3 kΩ
1.275				81.8 kΩ	4.8 kΩ
1.250				135.0 kΩ	7.7 kΩ
1.225				295.0 kΩ	11.4 kΩ
1.200					15.9 kΩ
1.175				(125.0) kΩ	21.7 kΩ
1.150				(45.1) kΩ	29.5 kΩ
1.125				(18.4) kΩ	40.4 kΩ
1.100				(5.1) kΩ	56.7 kΩ
1.075					83.9 kΩ
1.050					138.0 kΩ
1.025					302.0 kΩ
1.000					
0.975					(46.5) kΩ
0.950					(5.7) kΩ

R_1 = (Blue) R_2 = Black

Using the Inhibit Control of the PT6360 Series of Integrated Switching Regulators

The PT6360 series of integrated switching regulators (ISRs) provide step-down voltage conversion for output loads of up to 11 A. For applications that require the output voltage to be held off, these ISRs incorporate an *Inhibit** control (pin 1). The *Inhibit** control input can be used for power-up sequencing or whenever there is a requirement for the output voltage from the ISR to be turned off.

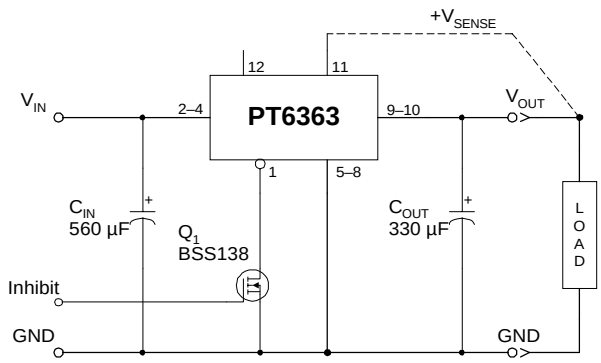
The ISR functions normally with pin 1 open circuit, providing a regulated output whenever a valid source voltage is applied between V_{in} (pins 2–3) and *GND* (pins 5–8). When a low-level ground signal is applied to pin 1, the regulator output is turned off [2] and the input current is significantly reduced [4].

Figure 4-1 shows the typical application of the *Inhibit** function. Note the discrete transistor, Q_1. The *Inhibit** control has its own internal pull-up to V_{in} potential. An open-collector or open-drain device is recommended to control this input [1]. The voltage thresholds are given in Table 4-1.

Table 4-1; Inhibit Control Requirements

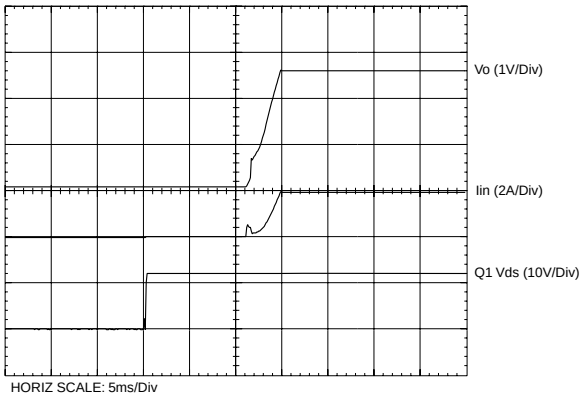
Parameter	Min	Typ	Max
Enable (V_{IH})	2.0 V	—	Vin
Disable (V_{IL})	–0.1 V	—	+0.3 V
I_{IL}	—	–0.5 mA	—

Figure 4-1



Turn-On Time: In the circuit of Figure 4-1, turning Q_1 [1] on applies a low-voltage to the *Inhibit** control (pin 1) and disables the output of the regulator [2]. If Q_1 is then turned off, the ISR executes a soft-start power up [3]. Power up consists of a short delay (approx. 10 msec), followed by a period in which the output voltage rises to the full regulation voltage. The module produces a regulated output voltage in approximately 15 msec. Figure 4-2 shows the rise in both the output voltage and input current for a PT6363 (2.5 V), following the turn-off of Q_1. The turn off of Q_1 corresponds to the rise in the waveform, Q_1 V_{ds}. The waveforms were measured with a 12 VDC input voltage, and 8.3-A load.

Figure 4-2

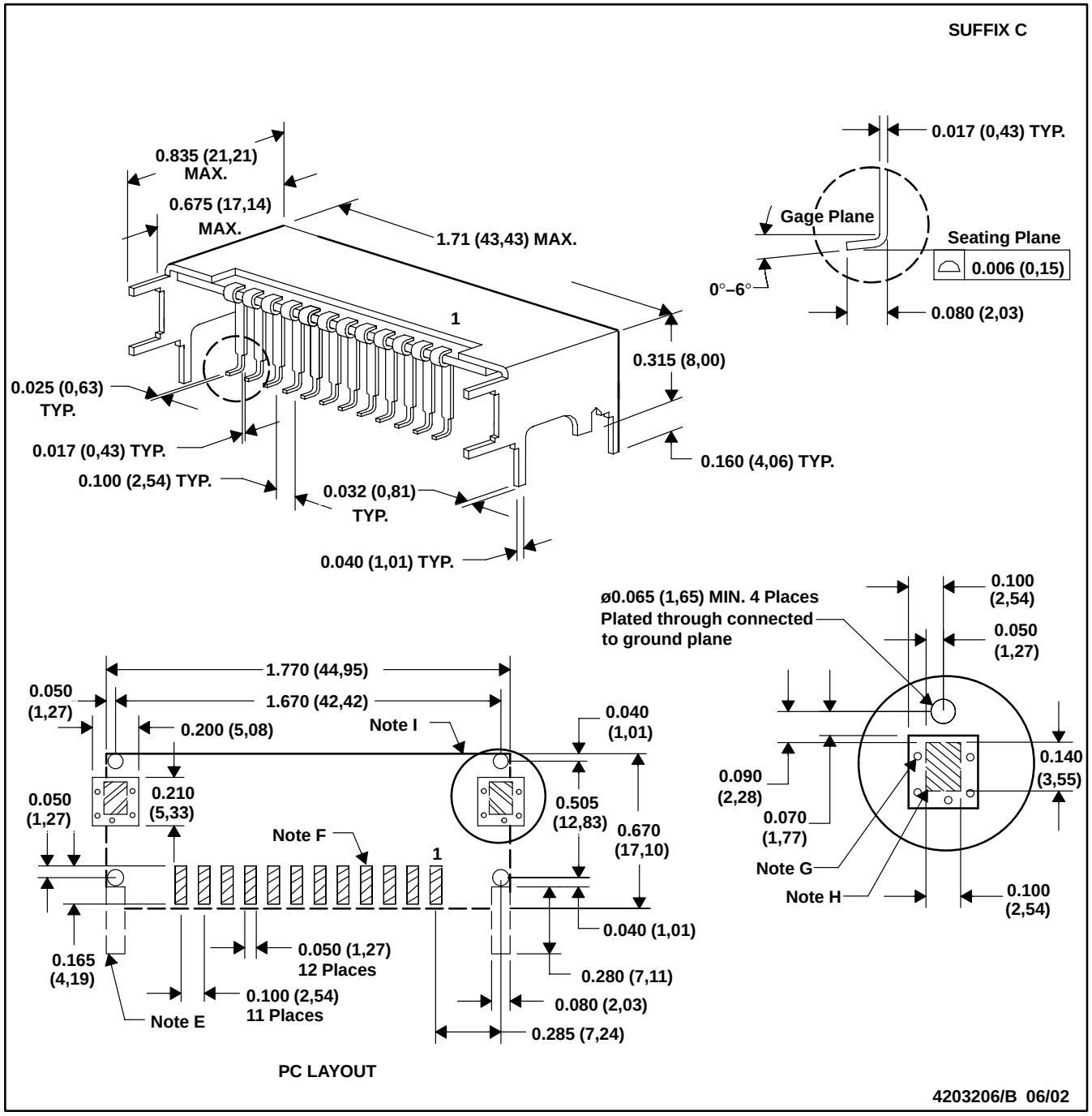


Notes:

1. Use an open-collector device with a breakdown voltage of at least 20 V (preferably a discrete transistor) for the *Inhibit** input. A pull-up resistor is not necessary. To disable the output voltage the control pin should be pulled low to less than +0.6 VDC.
2. When a ground signal is applied to the *Inhibit** control (pin 1) the module output is effectively turned off (tri-state). The output voltage decays to zero as the load impedance discharges the output capacitors.
3. When a ground signal to the *Inhibit** pin is removed, the regulator output initiates a soft-start cycle by first asserting a low impedance to ground. If an external voltage is applied to the regulator output it will sink current and possibly overstress the module.
4. When a ground signal is applied to the *Inhibit** pin, the module is effectively turned off and the input current is reduced to about 0.5 mA.

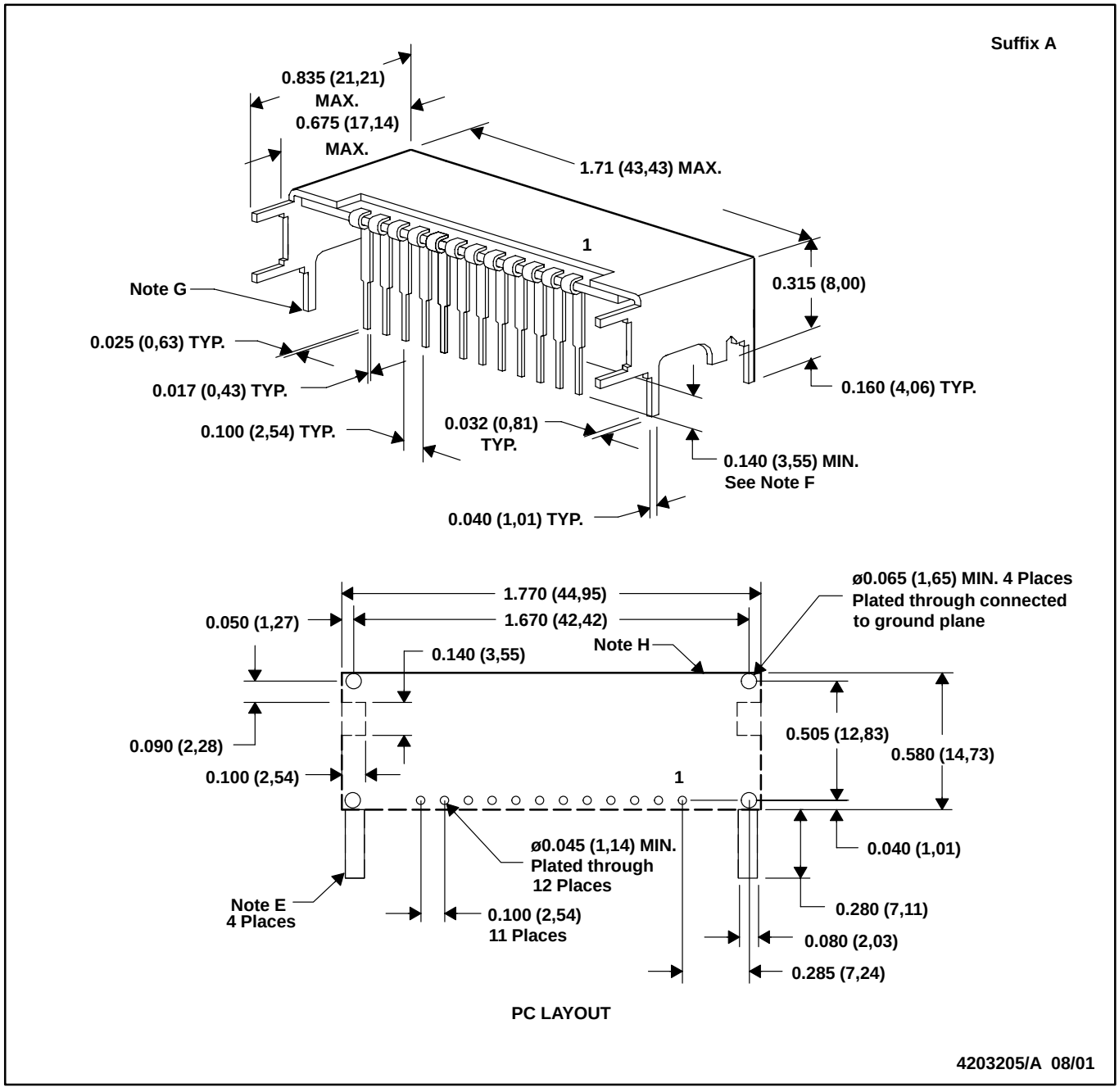
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EPK (R–MSIP–G12) **METAL SINGLE-IN-LINE MODULE**



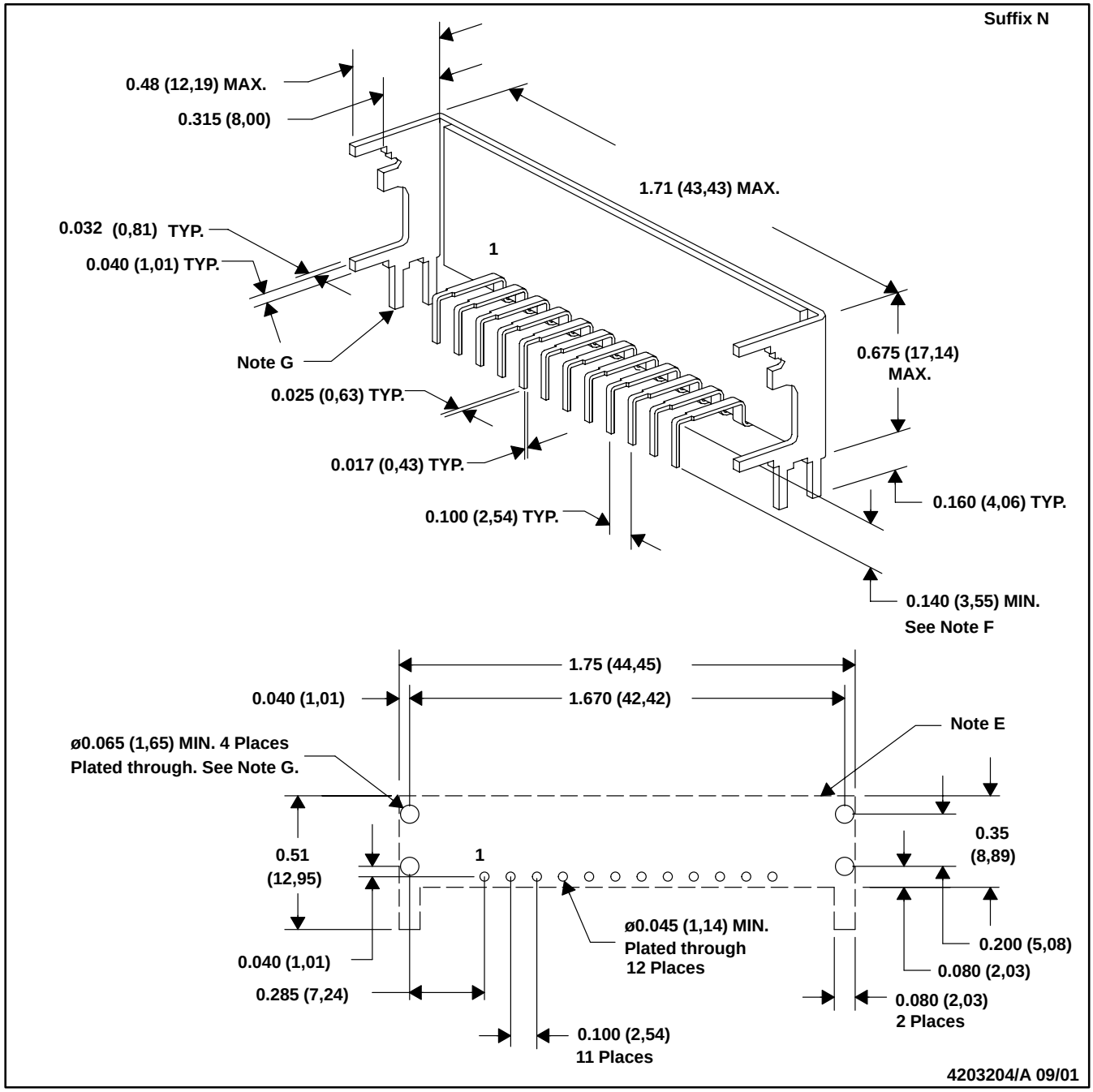
NOTES:
A. All linear dimensions are in inches (mm).
B. This drawing is subject to change without notice.
C. 2 place decimals are ± 0.030 (± 0, 76 mm).
D. 3 place decimals are ± 0.010 (± 0, 25 mm).
E. Recommended mechanical keep-out area.
F. Power pin connections should utilize two or more vias per input, ground and output pin.
G. Vias are recommended to improve copper adhesion.
H. Solder mask openings to copper island for solder joints to mechanical pins. Electrically connect case to ground plane.
I. Case outline reference.

EPJ (R–MSIP–G12) **METAL SINGLE-IN-LINE MODULE**



NOTES:
A. All linear dimensions are in inches (mm).
B. This drawing is subject to change without notice.
C. 2 place decimals are ± 0.030 (± 0,76 mm).
D. 3 place decimals are ± 0.010 (± 0,25 mm).
E. Recommended mechanical keep-out area.
F. Electrical pin length mounted on circuit board seating plane to pin end.
G. Electrically connect case to ground plane.
H. Case outline reference.

EPH (R–MSIP–T12) **METAL SINGLE-IN-LINE MODULE**



NOTES:
A. All linear dimensions are in inches (mm).
B. This drawing is subject to change without notice.
C. 2 place decimals are ±0.030 (±0,76mm).
D. 3 place decimals are ±0.010 (±0,25mm).
E. Recommended mechanical keep out area.
F. Electrical pin length mounted on circuit board seating plane to pin end.
G. Electrically connect case to ground plane.

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