

# TEA1751T; TEA1751LT

GreenChip III SMPS control IC

Rev. 02 — 23 December 2009

Product data sheet

## 1. General description

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The GreenChip III is the third generation of green Switched Mode Power Supply (SMPS) controller ICs. The TEA1751(L)T (TEA1751T and TEA1751LT) combines a controller for Power Factor Correction (PFC) and a flyback controller. Its high level of integration allows the design of a cost-effective power supply with a very low number of external components.

The special built-in green functions provide high efficiency at all power levels. This applies to quasi-resonant operation at high power levels, quasi-resonant operation with valley skipping, as well as to reduced frequency operation at lower power levels. At low power levels, the PFC switches off to maintain high efficiency.

During low power conditions, the flyback controller switches to frequency reduction mode and limits the peak current to 25 % of its maximum value. This will ensure high efficiency at low power and good standby power performance while minimizing audible noise from the transformer.

The TEA1751(L)T is a MultiChip Module, (MCM), containing two chips. The proprietary high voltage BCD800 process which makes direct start-up possible from the rectified universal mains voltage in an effective and green way. The second low voltage Silicon On Insulator (SIOI) is used for accurate, high speed protection functions and control.

The TEA1751(L)T enables highly efficient and reliable supplies with power requirements up to 250 W, to be designed easily and with a minimum number of external components.

## 2. Features

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### 2.1 Distinctive features

- Integrated PFC and flyback controller.
- Universal mains supply operation (70 V (AC) to 276 V (AC)).
- Dual boost PFC with accurate maximum output voltage (NXP patented).
- High level of integration, resulting in a very low external component count and a cost-effective design.

### 2.2 Green features

- On-chip start-up current source.

## 2.3 PFC green features

- Valley/zero voltage switching for minimum switching losses (NXP patented).
- Frequency limitation to reduce switching losses.
- PFC is switched off when a low load is detected at the flyback output.

## 2.4 Flyback green features

- Valley switching for minimum switching losses (NXP patented).
- Frequency reduction with fixed minimum peak current at low power operation to maintain high efficiency at low output power levels.

## 2.5 Protection features

- Safe restart mode for system fault conditions.
- Continuous mode protection by means of demagnetization detection for both converters (NXP patented).
- UnderVoltage Protection (UVP) (foldback during overload).
- Accurate OverVoltage Protection (OVP) for both converters (adjustable for flyback converter).
- Mains voltage independent OverPower Protection (OPP)
- Open control loop protection for both converters. The open loop protection on the flyback converter is latched on the TEA1751L and safe restart on the TEA1751.
- IC overtemperature protection.
- Low and adjustable OverCurrent Protection (OCP) trip level for both converters.
- General purpose input for latched protection, e.g. to be used for system OverTemperature Protection (OTP).

## 3. Applications

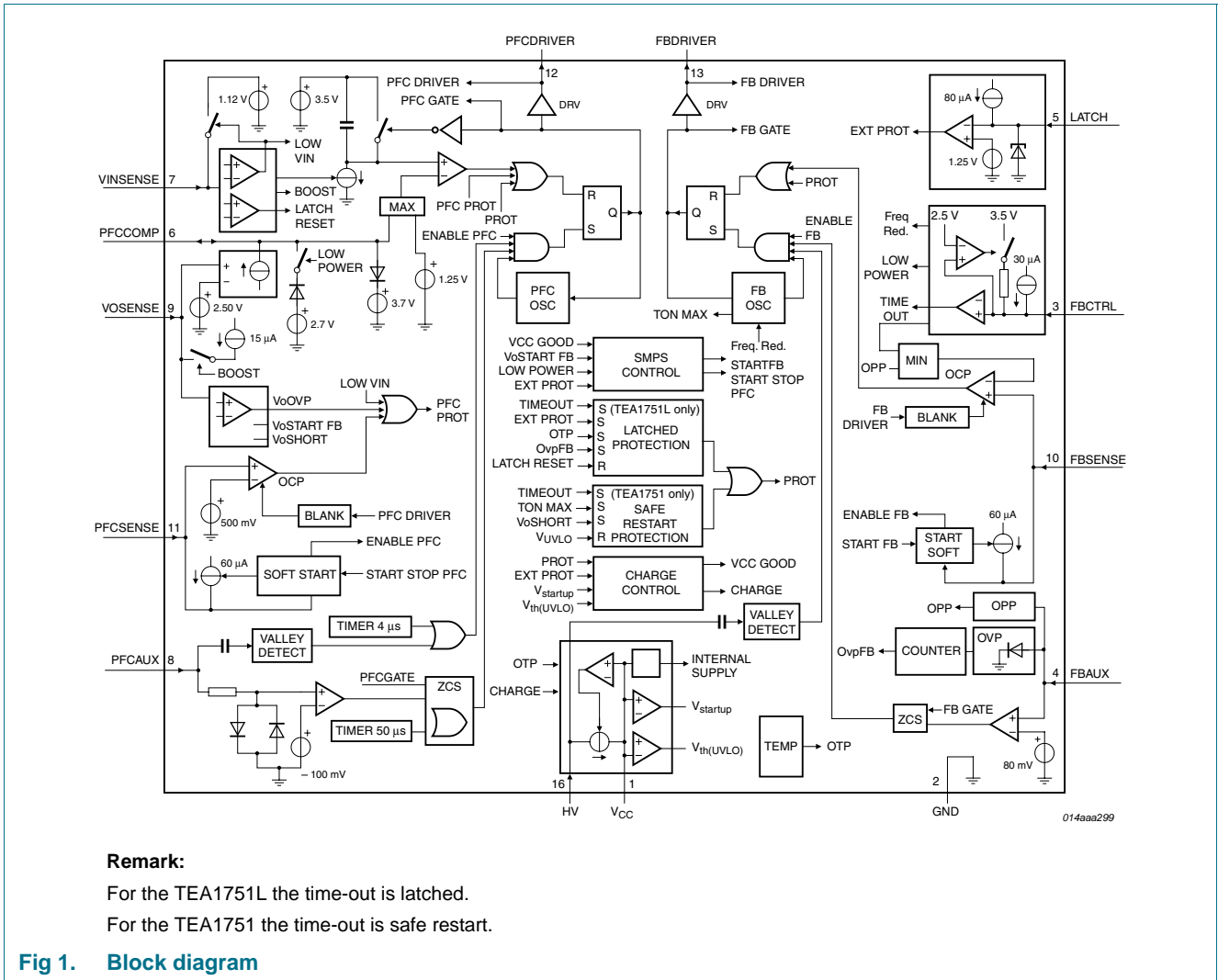
- The device can be used in all applications that require an efficient and cost-effective power supply solution up to 250 W. Notebook adapters in particular can benefit from the high level of integration.

## 4. Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
TEA1751T	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1
TEA1751LT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

5. Block diagram



## 6. Pinning information

### 6.1 Pinning

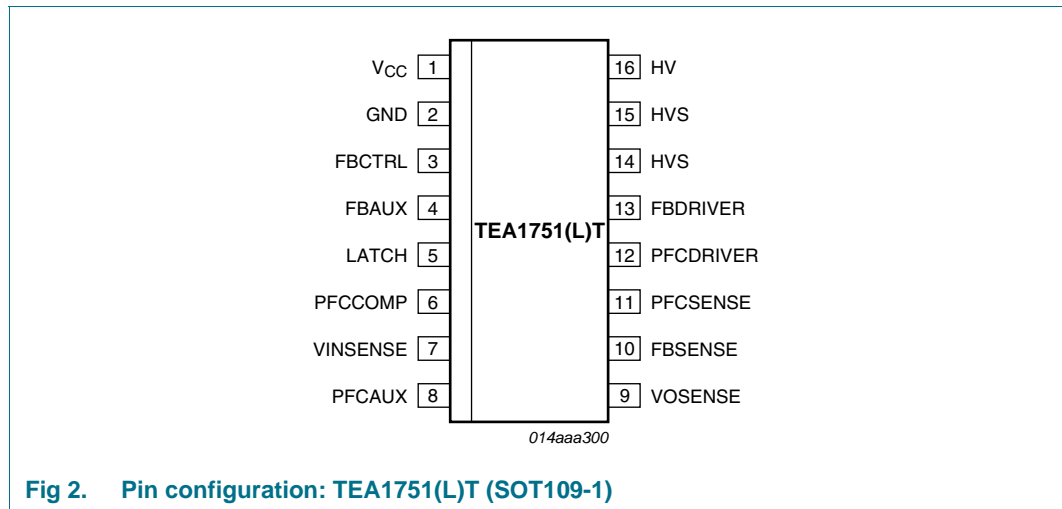


Fig 2. Pin configuration: TEA1751(L)T (SOT109-1)

### 6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
V <sub>CC</sub>	1	supply voltage
GND	2	ground
FBCTRL	3	control input for flyback
FBAUX	4	input from auxiliary winding for demagnetization timing and overvoltage protection for flyback
LATCH	5	general purpose protection input
PFCCOMP	6	frequency compensation pin for PFC
VINSENSE	7	sense input for mains voltage
PFCAUX	8	input from auxiliary winding for demagnetization timing for PFC
VOSENSE	9	sense input for PFC output voltage
FBSENSE	10	programmable current sense input for flyback
PFCSENSE	11	programmable current sense input for PFC
PFCDRIVER	12	gate driver output for PFC
FBDRIVER	13	gate driver output for flyback
HVS	14, 15	high voltage safety spacer, not connected
HV	16	high voltage start-up and valley sensing of flyback part

## 7. Functional description

### 7.1 General control

The TEA1751(L)T contains a controller for a power factor correction circuit as well as a controller for a flyback circuit. A typical configuration is shown in [Figure 3](#).

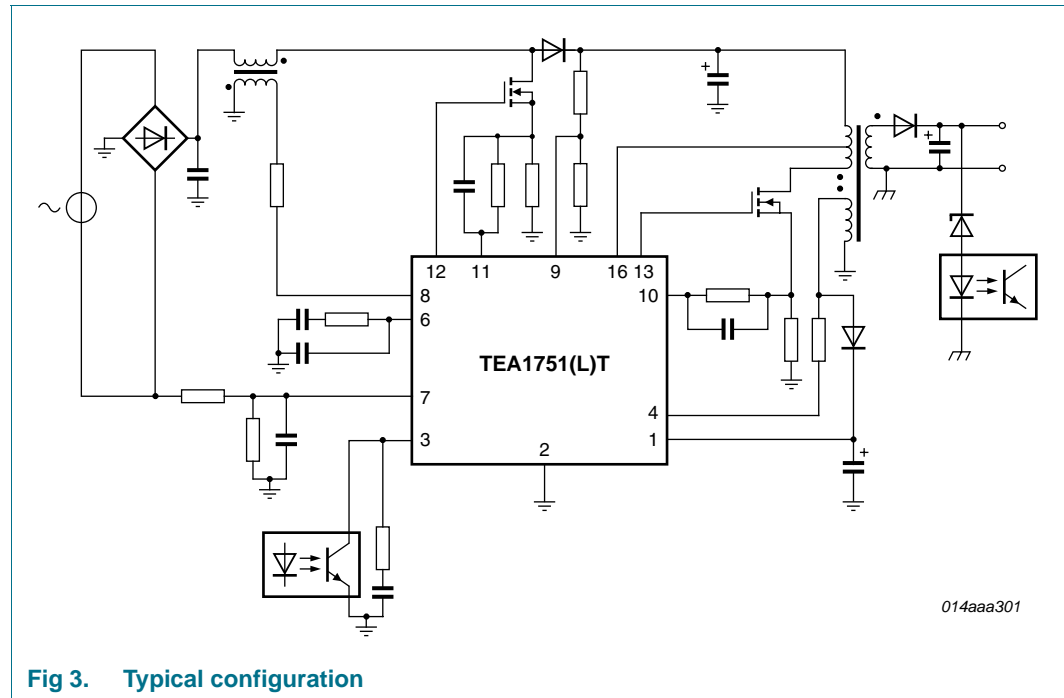


Fig 3. Typical configuration

#### 7.1.1 Start-up and UnderVoltage LockOut (UVLO)

Initially the capacitor on the  $V_{CC}$  pin is charged from the high voltage mains via the HV pin.

As long as  $V_{CC}$  is below  $V_{trip}$ , the charge current is low. This protects the IC if the  $V_{CC}$  pin is shorted to ground. For a short start-up time the charge current above  $V_{trip}$  is increased until  $V_{CC}$  reaches  $V_{th(UVLO)}$ . If  $V_{CC}$  is between  $V_{th(UVLO)}$  and  $V_{startup}$ , the charge current is low again, ensuring a low duty cycle during fault conditions.

The control logic activates the internal circuitry and switches off the HV charge current when the voltage on pin  $V_{CC}$  passes the  $V_{startup}$  level. First, the LATCH pin current source is activated and the soft start capacitors on the PFCSENSE and FBSENSE pins are charged. When the LATCH pin voltage exceeds the  $V_{en(LATCH)}$  voltage and the soft start capacitor on the PFCSENSE pin is charged, the PFC circuit is activated. Also the flyback converter is activated (providing the soft start capacitor on the FBSENSE pin is charged). The output voltage of the flyback converter is then regulated to its nominal output voltage. The IC supply is taken over by the auxiliary winding of the flyback converter. See [Figure 4](#).

If during start-up the LATCH pin does not reach the  $V_{en(LATCH)}$  level before  $V_{CC}$  reaches  $V_{th(UVLO)}$ , the LATCH pin output is deactivated and the charge current is switched on again.

As soon as the flyback converter is started, the voltage on the FBCTRL pin is monitored. If the output voltage of the flyback converter does not reach its intended regulation level in a predefined time, the voltage on the FBCTRL pin reaches the  $V_{to(FBCTRL)}$  level and an error is assumed. The TEA1751 then initiates a safe restart, while in the TEA1751L the protection is latched.

When one of the protection functions is activated, both converters stop switching and the  $V_{CC}$  voltage drops to  $V_{th(UVLO)}$ . A latched protection recharges the capacitor  $C_{VCC}$  via the HV pin, but does not restart the converters. For a safe restart protection, the capacitor is recharged via the HV pin and the device restarts (see block diagram, [Figure 1](#)).

In the event of an overvoltage protection of the PFC circuit,  $V_{VOSENSE} > V_{ovp(VOSENSE)}$ , only the PFC controller stops switching until the VOSENSE pin voltage drops below  $V_{OVP(VOSENSE)}$  again. Also, if a mains undervoltage is detected  $V_{VINSENSE} < V_{stop(VINSENSE)}$ , only the PFC controller stops switching until  $V_{VINSENSE} > V_{start(VINSENSE)}$  again.

When the voltage on pin  $V_{CC}$  drops below the undervoltage lockout level, both controllers stop switching and reenter the safe restart mode. In the safe restart mode the driver outputs are disabled and the  $V_{CC}$  pin voltage is recharged via the HV pin.

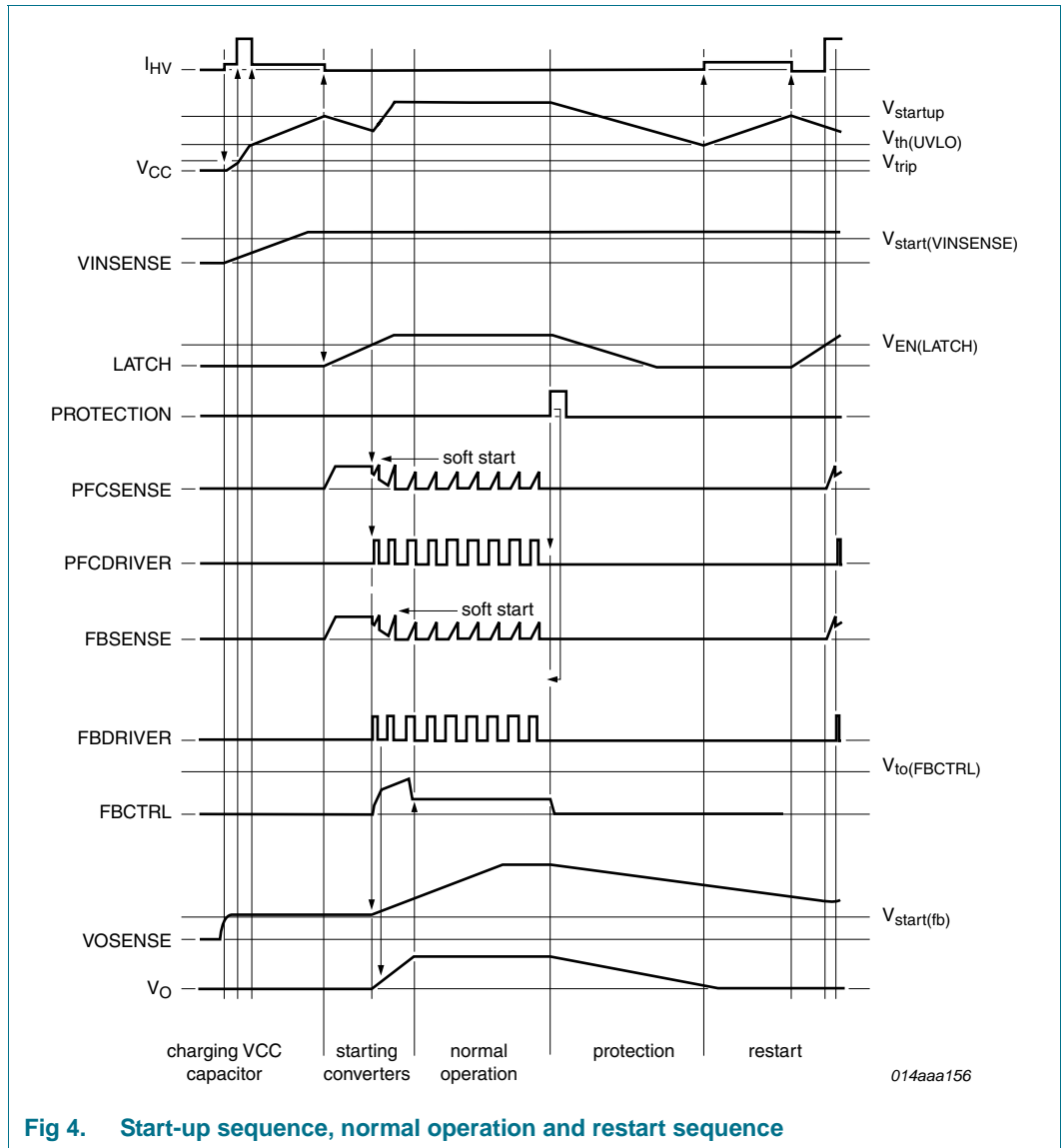


Fig 4. Start-up sequence, normal operation and restart sequence

### 7.1.2 Supply management

All internal reference voltages are derived from a temperature compensated and trimmed on-chip band gap circuit. Internal reference currents are derived from a temperature compensated and trimmed on-chip current reference circuit.

### 7.1.3 Latch input

Pin LATCH is a general purpose input pin, which can be used to switch off both converters. The pin sources a current  $I_{O(LATCH)}$  (80  $\mu$ A typical). Switching off both converters is stopped as soon as the voltage on this pin drops below 1.25 V.

At initial start-up the switching is inhibited until the capacitor on the LATCH pin is charged above 1.35 V (typical). No internal filtering is done on this pin. An internal zener clamp of 2.9 V (typical) protects this pin from excessive voltages.

#### 7.1.4 Fast latch reset

In a typical application the mains can be interrupted briefly to reset the latched protection. The PFC bus capacitor,  $C_{bus}$ , does not have to discharge for this latched protection to reset.

Typically the PFC bus capacitor,  $C_{bus}$ , has to discharge for the  $V_{CC}$  to drop to this reset level. When the latched protection is set, the clamping circuit of the VINSENSE circuit is disabled. (see also [Section 7.2.9](#)) As soon as the VINSENSE voltage drops below 750 mV (typical) and after that is raised to 870 mV (typical), the latched protection is reset.

The latched protection is also reset by removing both the voltage on pin  $V_{CC}$  and on pin HV.

#### 7.1.5 Overtemperature protection

An accurate internal temperature protection is provided in the circuit. When the junction temperature exceeds the thermal shutdown temperature, the IC stops switching. As long as OTP is active, the capacitor  $C_{VCC}$  is not recharged from the HV mains. The OTP circuit is supplied from the HV pin if the  $V_{CC}$  supply voltage is not sufficient.

OTP is a latched protection. It can be reset by removing both the voltage on pin  $V_{CC}$  and on pin HV or by the fast latch reset function. (See [Section 7.1.4](#))

### 7.2 Power factor correction circuit

The power factor correction circuit operates in quasi-resonant or discontinuous conduction mode with valley switching. The next primary stroke is only started when the previous secondary stroke has ended and the voltage across the PFC MOSFET has reached a minimum value. The voltage on the PFCAUX pin is used to detect transformer demagnetization and the minimum voltage across the external PFC MOSFET switch.

#### 7.2.1 $t_{on}$ control

The power factor correction circuit is operated in  $t_{on}$  control. The resulting mains harmonic reduction of a typical application is well within the class-D requirements.

#### 7.2.2 Valley switching and demagnetization (PFCAUX pin)

The PFC MOSFET is switched on after the transformer is demagnetized. Internal circuitry connected to the PFCAUX pin detects the end of the secondary stroke. It also detects the voltage across the PFC MOSFET. The next stroke is started when the voltage across the PFC MOSFET is at its minimum in order to reduce switching losses and ElectroMagnetic Interference (EMI) (valley switching).

If no demagnetization signal is detected on the PFCAUX pin, the controller generates a zero current signal (ZCS), 50  $\mu$ s (typical) after the last PFCGATE signal.

If no valley signal is detected on the PFCAUX pin, the controller generates a valley signal 4  $\mu$ s (typical) after demagnetization was detected.

To protect the internal circuitry during lightning events, for example, it is advisable to add a 5 k $\Omega$  series resistor to this pin. To prevent incorrect switching due to external disturbance, the resistor should be placed close to the IC on the printed-circuit board.



### 7.2.3 Frequency limitation

To optimize the transformer and minimize switching losses, the switching frequency is limited to  $f_{sw(PFC)max}$ . If the frequency for quasi-resonant operation is above the  $f_{sw(PFC)max}$  limit, the system switches over to discontinuous conduction mode. Also here, the PFC MOSFET is only switched on at a minimum voltage across the switch (valley switching).

### 7.2.4 Mains voltage compensation (VINSENSE pin)

The mathematical equation for the transfer function of a power factor corrector contains the square of the mains input voltage. In a typical application this results in a low bandwidth for low mains input voltages, while at high mains input voltages the Mains Harmonic Reduction (MHR) requirements may be hard to meet.

To compensate for the mains input voltage influence, the TEA1751(L)T contains a correction circuit. Via the VINSENSE pin the average input voltage is measured and the information is fed to an internal compensation circuit. With this compensation it is possible to keep the regulation loop bandwidth constant over the full mains input range, yielding a fast transient response on load steps, while still complying with class-D MHR requirements.

In a typical application, the bandwidth of the regulation loop is set by a resistor and two capacitors on the PFCCOMP pin.

### 7.2.5 Soft start-up (pin PFCSENSE)

To prevent audible transformer noise at start-up or during hiccup, the transformer peak current,  $I_{DM}$ , is increased slowly by the soft start function. This can be achieved by inserting  $R_{SS1}$  and  $C_{SS1}$  between pin PFCSENSE and current sense resistor  $R_{SENSE1}$ . An internal current source charges the capacitor to  $V_{PFCSENSE} = I_{start(soft)PFC} \times R_{SS1}$ . The voltage is limited to  $V_{start(soft)PFC}$ .

The start level and the time constant of the increasing primary current level can be adjusted externally by changing the values of  $R_{SS1}$  and  $C_{SS1}$ .

$$\tau_{softstart} = 3 \times R_{SS1} \times C_{SS1}$$

The charging current  $I_{start(soft)PFC}$  flows as long as the voltage on pin PFCSENSE is below 0.5 V (typ). If the voltage on pin PFCSENSE exceeds 0.5 V, the soft start current source starts limiting current  $I_{start(soft)PFC}$ . As soon as the PFC starts switching, the  $I_{start(soft)PFC}$  current source is switched off; see [Figure 5](#).

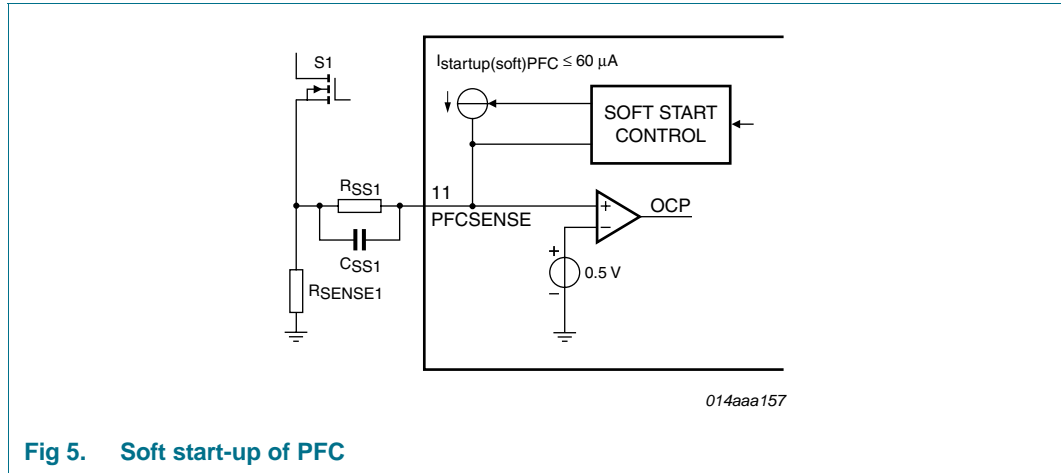


Fig 5. Soft start-up of PFC

### 7.2.6 Low power mode

When the output power of the flyback converter (see [Section 7.3](#)) is low, the flyback converter switches over to frequency reduction mode. When frequency reduction mode is entered by the flyback controller, the power factor correction circuit is switched off to maintain high efficiency.

During low power mode operation the PFCCOMP pin is clamped to a minimal voltage of 2.7 V (typical) and a maximum voltage of 3.9 V (typical). The lower clamp voltage limits the maximum power that is delivered when the PFC is switched on again. The upper clamp voltage ensures that the PFC can return to its normal regulation point in a limited amount of time when returning from low power mode.

As soon as the flyback converter leaves the frequency reduction mode, the power factor correction circuit restores normal operation. To prevent continuous switching on and off of the PFC circuit, a small hysteresis is build in, (60 mV (typical) on the FBCTRL pin).

### 7.2.7 Dual boost PFC

The PFC output voltage is modulated by the mains input voltage. The mains input voltage is measured via the VINSENSE pin. The current is sourced from the VOSENSE pin if the voltage on the VINSENSE pin drops below 2.2 V (typical). To ensure the stability of the switch-over 200 mV is inserted around the 2.2 V, see [Figure 6](#).

For low VINSENSE input voltages, the output current is 15 μA (typical). This output current, in combination with the resistors on the VOSENSE pin, sets the lower PFC output voltage level at low mains voltages. At high mains input voltages the current is switched to zero. The PFC output voltage will then be at its maximum. As this current is zero in this situation, it does not effect the accuracy of the PFC output voltage.

For proper switch-off behavior, the VOSENSE current is switched to its maximum value, (15 μA (typical)), as soon as the voltage on pin VOSENSE drops below 2.1 V (typical).

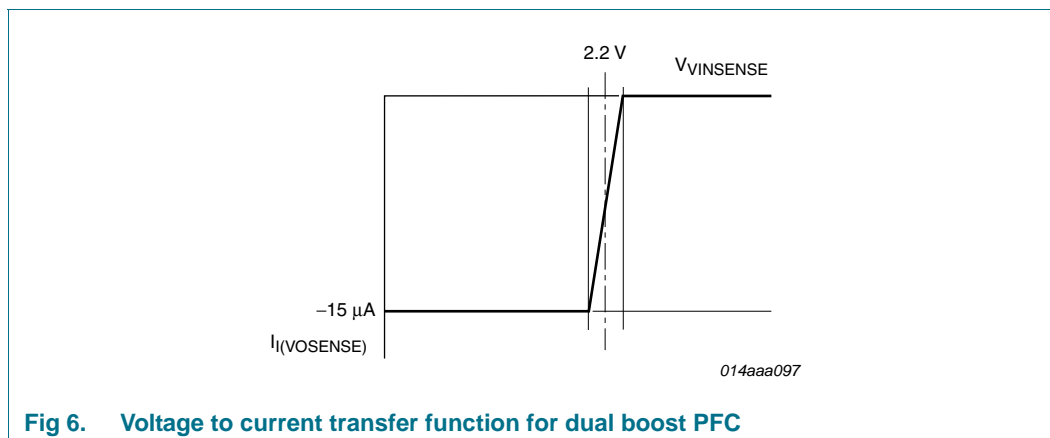


Fig 6. Voltage to current transfer function for dual boost PFC

### 7.2.8 Overcurrent protection (PFCSENSE pin)

The maximum peak current is limited cycle-by-cycle by sensing the voltage across an external sense resistor,  $R_{SENSE1}$ , on the source of the external MOSFET. The voltage is measured via the PFCSENSE pin.

### 7.2.9 Mains undervoltage lockout / brownout protection (VINSENSE pin)

To prevent the PFC from operating at very low mains input voltages, the voltage on the VINSENSE pin is sensed continuously. As soon as the voltage on this pin drops below the  $V_{stop(VINSENSE)}$  level, switching of the PFC is stopped.

The voltage on pin VINSENSE is clamped to a minimum value,  $V_{start(VINSENSE)} + \Delta V_{pu(VINSENSE)}$ , for a fast restart as soon as the mains input voltage is restored after a mains dropout.

### 7.2.10 Overvoltage protection (VOSENSE pin)

To prevent output overvoltage during load steps and mains transients, an overvoltage protection circuit is built in.

As soon as the voltage on the VOSENSE pin exceeds the  $V_{ovp(VOSENSE)}$  level, switching of the power factor correction circuit is inhibited. Switching of the PFC recommences as soon as the VOSENSE pin voltage drops below the  $V_{ovp(VOSENSE)}$  level again.

When the resistor between pin VOSENSE and ground is open, the overvoltage protection is also triggered.

### 7.2.11 PFC open loop protection (VOSENSE pin)

The power factor correction circuit does not start switching until the voltage on the VOSENSE pin is above the  $V_{th(ol)(VOSENSE)}$  level. This protects the circuit from open loop and VOSENSE short situations.

### 7.2.12 Driver (pin PFCDRIVER)

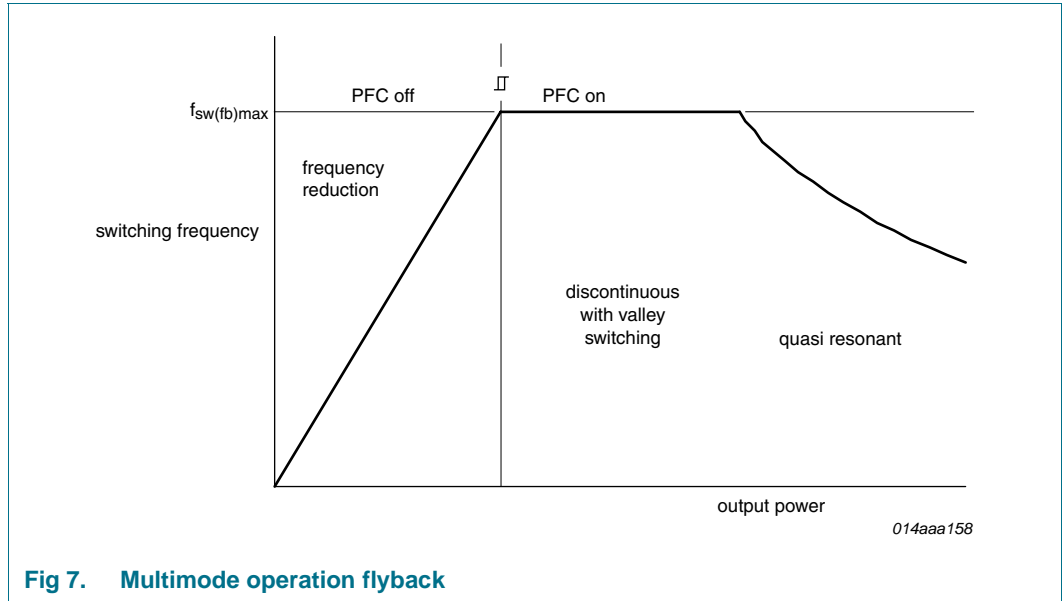
The driver circuit to the gate of the power MOSFET has a current sourcing capability of typically  $-500$  mA and a current sink capability of typically  $1.2$  A. This permits fast turn-on and turn-off of the power MOSFET for efficient operation.

**7.3 Flyback controller**

The TEA1751(L)T includes a controller for a flyback converter. The flyback converter operates in quasi-resonant or discontinuous conduction mode with valley switching. The auxiliary winding of the flyback transformer provides demagnetization detection and powers the IC after start-up.

**7.3.1 Multimode operation**

The TEA1751(L)T flyback controller can operate in several modes; see [Figure 7](#).



**Fig 7. Multimode operation flyback**

At high output power the converter switches to quasi-resonant mode. The next converter stroke is started after demagnetization of the transformer current. In quasi-resonant mode switching losses are minimized as the converter only switches on when the voltage across the external MOSFET is at its minimum (valley switching, see also [Section 7.3.2](#)).

To prevent high frequency operation at lower loads, the quasi-resonant operation changes to discontinuous mode operation with valley skipping in which the switching frequency is limited for EMI to  $f_{sw(fb)max}$  (125 kHz typical). Again, the external MOSFET is only switched on when the voltage across the MOSFET is at its minimum.

At very low power and standby levels the frequency is controlled down by a Voltage Controlled Oscillator (VCO). The minimum frequency can be reduced to zero. During frequency reduction mode, the primary peak current is kept at a minimal level of  $I_{pkmax}/4$  to maintain a high efficiency. ( $I_{pkmax}$  is the maximum primary peak current set by the sense resistor and the maximum sense voltage.) As the primary peak current is low in frequency reduction operation ( $I_{pk} = I_{pkmax}/4$ ), no audible noise is noticeable at switching frequencies in the audible range. Valley switching is also active in this mode.

In frequency reduction mode the PFC controller is switched off and the flyback maximum frequency changes linearly with the control voltage on the FBCTRL pin (see [Figure 8](#)). For stable on and off switching of the PFC, the FBCTRL pin has a 50 mV (typical) hysteresis. At no load operation the switching frequency can be reduced to (almost) zero.

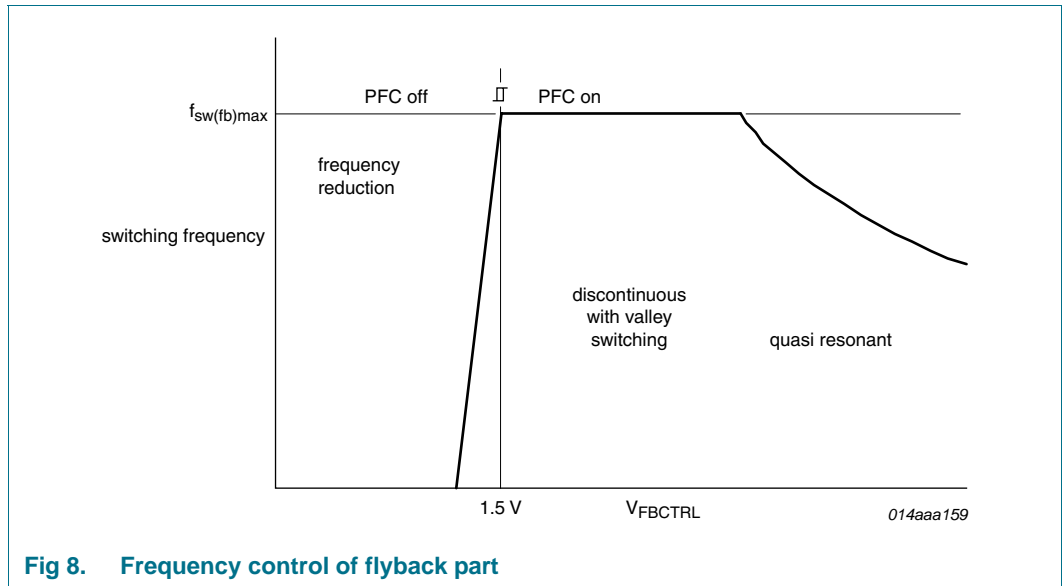


Fig 8. Frequency control of flyback part

### 7.3.2 Valley switching (HV pin)

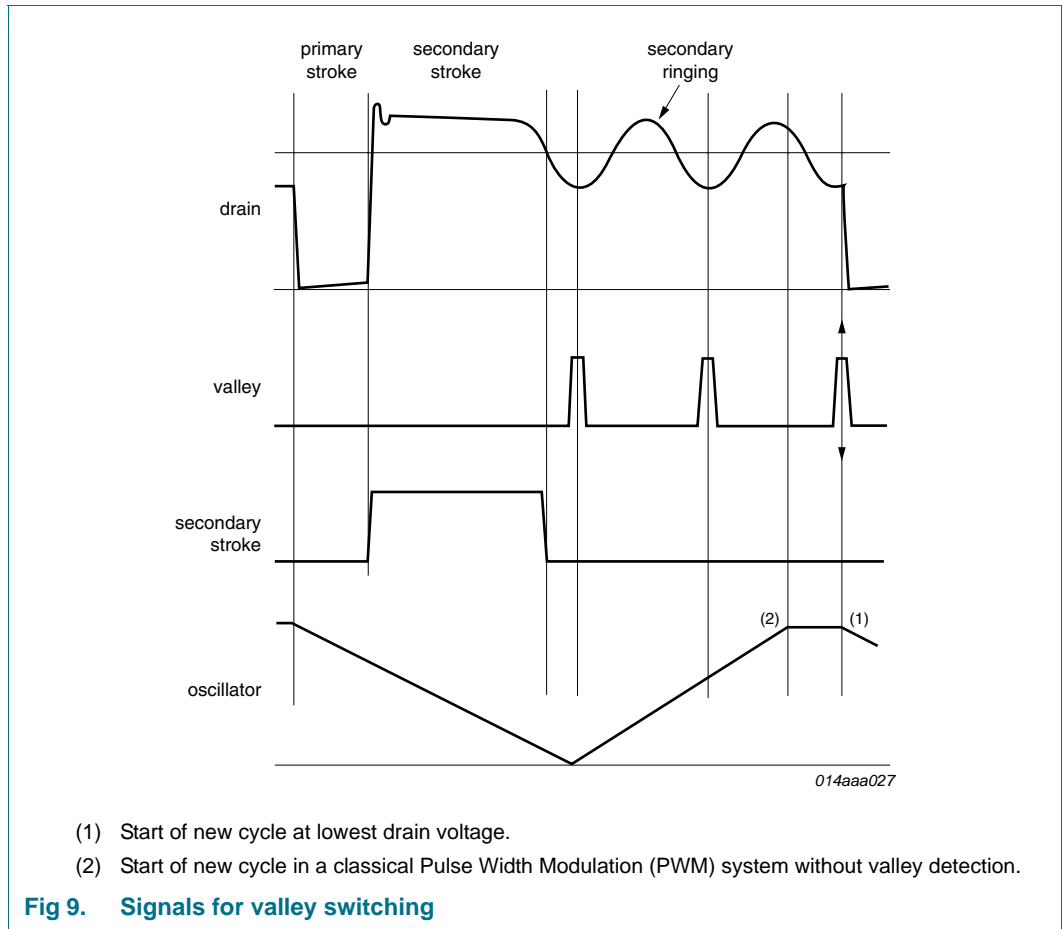
Refer to [Figure 9](#). A new cycle starts when the external MOSFET is activated. After the on-time (determined by the FBSENSE voltage and the FBCTRL voltage), the MOSFET is switched off and the secondary stroke starts. After the secondary stroke, the drain voltage shows an oscillation with a frequency of approximately  $\frac{1}{(2 \times \pi \times \sqrt{(L_p \times C_d)})}$  where  $L_p$  is

the primary self-inductance of the flyback transformer and  $C_d$  is the capacitance on the drain node.

As soon as the internal oscillator voltage is high again and the secondary stroke has ended, the circuit waits for the lowest drain voltage before starting a new primary stroke. [Figure 9](#) shows the drain voltage, valley signal, secondary stroke signal and the internal oscillator signal.

Valley switching allows high frequency operation as capacitive switching losses are reduced, see [Equation 1](#). High frequency operation makes small and cost-effective magnetics possible.

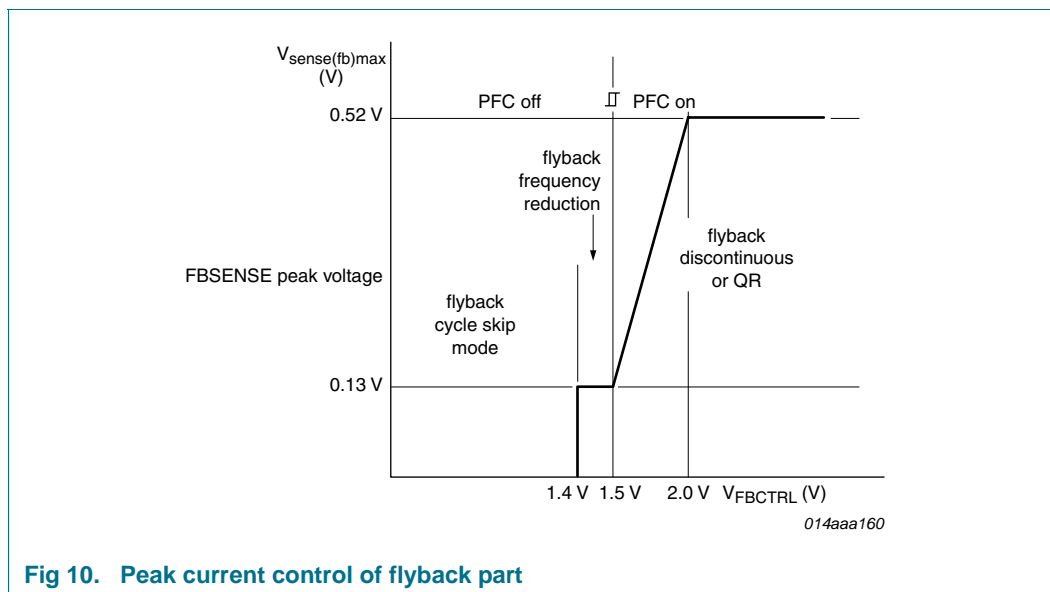
$$\left( P = \frac{1}{2} \times C_d \times V^2 \times f \right) \tag{1}$$



### 7.3.3 Current mode control (FBSENSE pin)

Current mode control is used for the flyback converter for its good line regulation.

The primary current is sensed by the FBSENSE pin across an external resistor and compared with an internal control voltage. The internal control voltage is proportional to the FBCTRL pin voltage, see [Figure 10](#).



**Fig 10. Peak current control of flyback part**

The driver output is latched in the logic, preventing multiple switch-on.

### 7.3.4 Demagnetization (FBAUX pin)

The system is always in quasi-resonant or discontinuous conduction mode. The internal oscillator does not start a new primary stroke until the previous secondary stroke has ended.

Demagnetization features a cycle-by-cycle output short circuit protection by immediately lowering the frequency (longer off-time), thereby reducing the power level.

Demagnetization recognition is suppressed during the first  $t_{sup}(xfmr\_ring)$  time (2  $\mu$ s typical). This suppression may be necessary at low output voltages and at start-up and in applications where the transformer has a large leakage inductance.

If pin FBAUX is open circuit or not connected, a fault condition is assumed and the converter stops operating immediately. Operation restarts as soon as the fault condition is removed.

### 7.3.5 Flyback control / time-out (FBCTRL pin)

The pin FBCTRL is connected to an internal voltage source of 3.5 V via an internal resistor (typical resistance is 3 k $\Omega$ ). As soon as the voltage on this pin is above 2.5 V (typical), this connection is disabled. Above 2.5 V the pin is biased with a small current. When the voltage on this pin rises above 4.5 V (typical), a fault is assumed and switching is inhibited. In the TEA1751 a restart will then be made, while in the TEA1751L the protection will be latched.

When a small capacitor is connected to this pin, a time-out function can be created to protect against an open control loop situation. (see [Figure 11](#) and [Figure 12](#)) The time-out function can be disabled by connecting a resistor (100 k $\Omega$ ) to ground on the FBCTRL pin.

If the pin is shorted to ground, switching of the flyback controller is inhibited.





**7.3.6 Soft start-up (pin FBSENSE)**

To prevent audible transformer noise during start-up, the transformer peak current,  $I_{DM}$  is slowly increased by the soft start function. This can be achieved by inserting a resistor and a capacitor between pin 10, FBSENSE, and the current sense resistor.

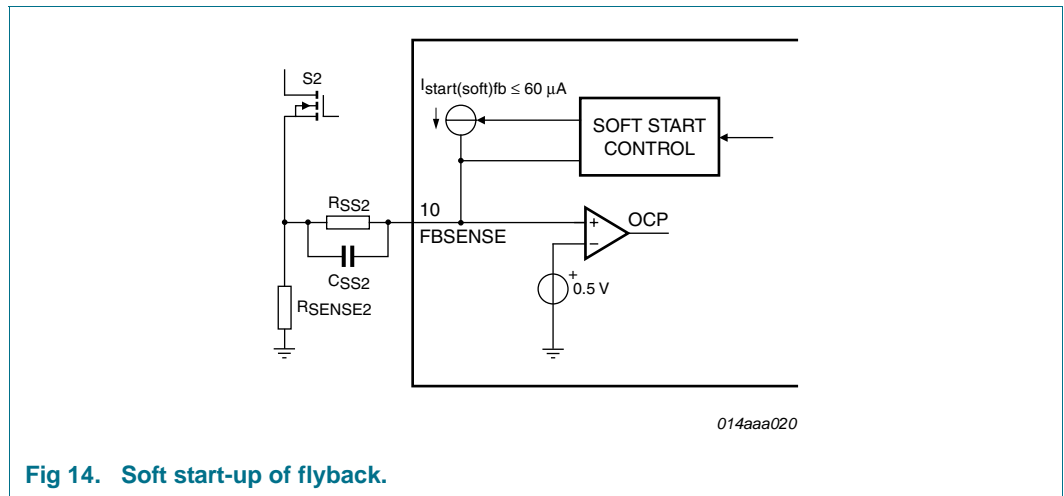
An internal current source charges the capacitor to  $V = I_{start(soft)fb} \times R_{SS2}$ , with a maximum of approximately 0.5 V.

The start level and the time constant of the increasing primary current level can be adjusted externally by changing the values of  $R_{SS2}$  and  $C_{SS2}$ .

$$\tau_{softstart} = 3 \times R_{SS2} \times C_{SS2}$$

The soft start current  $I_{start(soft)fb}$  is switched on as soon as  $V_{CC}$  reaches  $V_{startup}$ . When the voltage on pin FBSENSE has reached 0.5 V, the flyback converter starts switching.

The charging current  $I_{start(soft)(PFC)}$  flows as long as the voltage on pin FBSENSE is below approximately 0.5 V. If the voltage on pin FBSENSE exceeds 0.5 V, the soft start current source starts limiting the current. After the flyback converter has started, the soft start current source is switched off.



**Fig 14. Soft start-up of flyback.**

**7.3.7 Maximum on-time**

The flyback controller limits the ‘on-time’ of the external MOSFET to 40  $\mu s$  (typical). When the ‘on-time’ is longer than 40  $\mu s$ , the IC stops switching and enters the safe restart mode.

**7.3.8 Overvoltage protection (FBAUX pin)**

An output overvoltage protection is implemented in the GreenChip III series. This works for the TEA1751(L)T by sensing the auxiliary voltage via the current flowing into pin FBAUX during the secondary stroke. The auxiliary winding voltage is a well-defined replica of the output voltage. Voltage spikes are averaged by an internal filter.

If the output voltage exceeds the OVP trip level, an internal counter starts counting subsequent OVP events. The counter has been added to prevent incorrect OVP detection which might occur during ESD or lightning events. If the output voltage exceeds the OVP trip level a few times and not again in a subsequent cycle, the internal counter counts down at twice the speed it uses when counting up. However, when typically eight cycles of

subsequent OVP events are detected, the IC assumes a true OVP and the OVP circuit switches the power MOSFET off. As the protection is latched, the converter only restarts after the internal latch is reset. In a typical application the mains should be interrupted to reset the internal latch.

The output voltage  $V_{o(OVP)}$  at which the OVP function trips, can be set by the demagnetization resistor,  $R_{FBAUX}$  :

$$V_{o(OVP)} = \frac{N_s}{N_{aux}} (I_{ovp(FBAUX)} \times R_{FBAUX} + V_{clamp(FBAUX)})$$

where  $N_s$  is the number of secondary turns and  $N_{aux}$  is the number of auxiliary turns of the transformer. Current  $I_{ovp(FBAUX)}$  is internally trimmed.

The value of  $R_{FBAUX}$  can be adjusted to the turns ratio of the transformer, thus making an accurate OVP detection possible.

### 7.3.9 Overcurrent protection (FBSENSE pin)

The primary peak current in the transformer is measured accurately cycle-by-cycle using the external sense resistor  $R_{sense2}$ . The OCP circuit limits the voltage on pin FBSENSE to an internal level (see also [Section 7.3.3](#)). The OCP detection is suppressed during the leading edge blanking period,  $t_{leb}$ , to prevent false triggering caused by switch-on spikes.

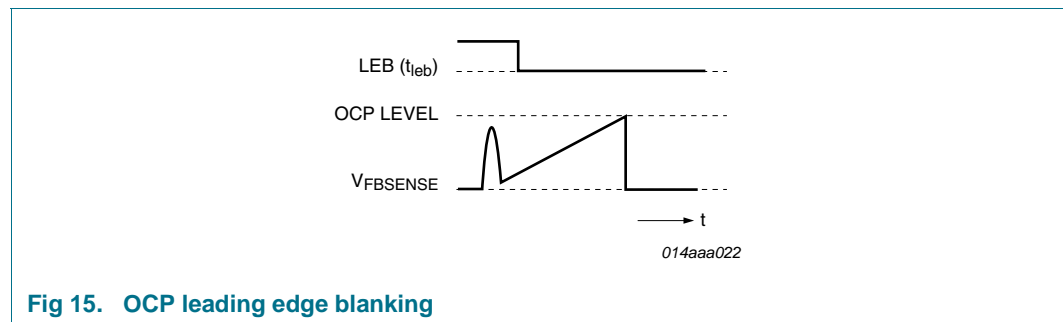


Fig 15. OCP leading edge blanking

### 7.3.10 Overpower protection

During the primary stroke of the flyback converter the input voltage of the flyback converter is measured by sensing the current that is drawn from the pin FBAUX.

The current information is used to adjust the peak drain current of the flyback converter, which is measured via pin FBSENSE. The internal compensation is such that an almost input voltage independent maximum output power can be realized.

The OPP curve is given in [Figure 16](#).

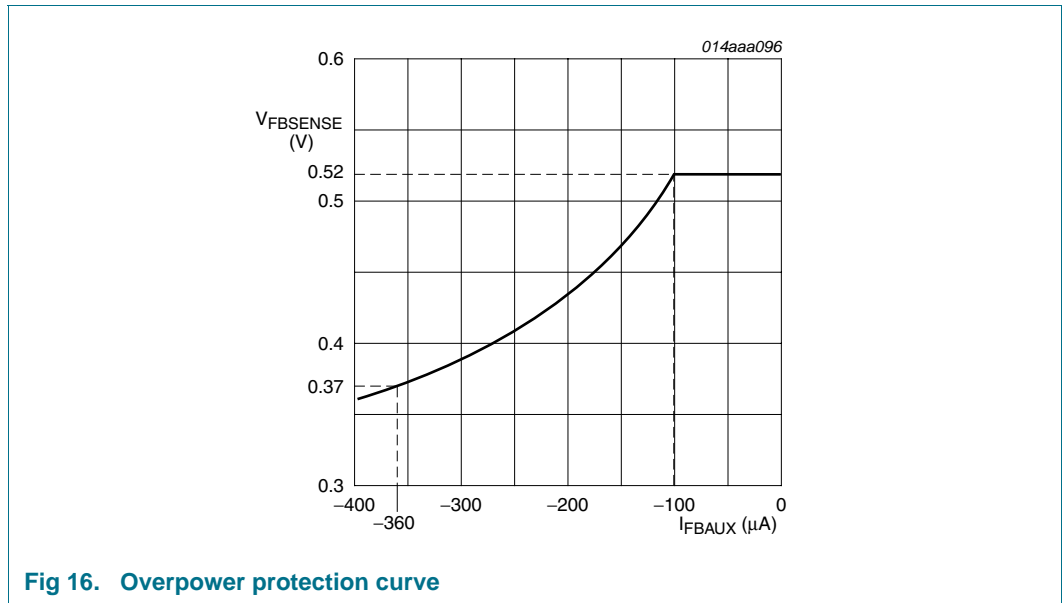


Fig 16. Overpower protection curve

### 7.3.11 Driver (pin FBDRIVER)

The driver circuit to the gate of the external power MOSFET has a current sourcing capability of typically -500 mA and a current sink capability of typically 1.2 A. This permits fast turn-on and turn-off of the power MOSFET for efficient operation.

## 8. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
<b>Voltages</b>					
$V_{CC}$	supply voltage		-0.4	+38	V
$V_{LATCH}$	voltage on pin LATCH	current limited	-0.4	+5	V
$V_{FBCTRL}$	voltage on pin FBCTRL		-0.4	+5	V
$V_{PFCCOMP}$	voltage on pin PFCCOMP		-0.4	+5	V
$V_{VINSENSE}$	voltage on pin VINSENSE		-0.4	+5	V
$V_{VOSENSE}$	voltage on pin VOSENSE		-0.4	+5	V
$V_{PFCAUX}$	voltage on pin PFCAUX		-25	+25	V
$V_{FBSENSE}$	voltage on pin FBSENSE	current limited	-0.4	+5	V
$V_{PFCSENSE}$	voltage on pin PFCSENSE	current limited	-0.4	+5	V
$V_{HV}$	voltage on pin HV		-0.4	+650	V
<b>Currents</b>					
$I_{FBCTRL}$	current on pin FBCTRL		-3	0	mA
$I_{FBAX}$	current on pin FBAX		-1	+1	mA
$I_{PFCSENSE}$	current on pin PFCSENSE		-1	+10	mA
$I_{FBSENSE}$	current on pin FBSENSE		-1	+10	mA
$I_{FBDRIVER}$	current on pin FBDRIVER	duty cycle < 10 %	-0.8	+2	A

**Table 3. Limiting values ...continued**  
 In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$I_{PFCDRIVER}$	current on pin PFCDRIVER	duty cycle < 10 %	-0.8	+2	A
$I_{HV}$	current on pin HV		-	5	mA
<b>General</b>					
$P_{tot}$	total power dissipation	$T_{amb} < 75\text{ °C}$	-	0.6	W
$T_{stg}$	storage temperature		-55	+150	°C
$T_j$	junction temperature		-40	+150	°C
<b>ESD</b>					
$V_{ESD}$	electrostatic discharge voltage	class 1 human body model			
		pins 1 to 13 [1]	-	2000	V
		pin 16 (HV) [1]	-	1500	V
		machine model [2]	-	200	V
		charged device model	-	500	V

[1] Equivalent to discharging a 100 pF capacitor through a 1.5 kΩ series resistor.

[2] Equivalent to discharging a 200 pF capacitor through a 0.75 μH coil and a 10 Ω resistor.

## 9. Thermal characteristics

**Table 4. Thermal characteristics**

Symbol	Parameter	Conditions	Typ	Unit
$R_{th(j-a)}$	thermal resistance from junction to ambient	in free air; JEDEC test board	124	K/W

## 10. Characteristics

**Table 5. Characteristics**

$T_{amb} = 25\text{ °C}$ ;  $V_{CC} = 20\text{ V}$ ; all voltages are measured with respect to ground (pin 2); currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
<b>Start-up current source (pin HV)</b>						
$I_{HV}$	current on pin HV	$V_{HV} > 80\text{ V}$				
		$V_{CC} < V_{trip}$ ; $V_{th(UVLO)} < V_{CC} < V_{startup}$	-	1.0	-	mA
		$V_{trip} < V_{CC} < V_{th(UVLO)}$	-	5.4	-	mA
		with auxiliary supply	8	20	40	μA
$V_{BR}$	breakdown voltage		650	-	-	V
<b>Supply voltage management (pin <math>V_{CC}</math>)</b>						
$V_{trip}$	trip voltage		0.55	0.65	0.75	V
$V_{startup}$	start-up voltage		21	22	23	V

**Table 5. Characteristics ...continued**

$T_{amb} = 25\text{ }^{\circ}\text{C}$ ;  $V_{CC} = 20\text{ V}$ ; all voltages are measured with respect to ground (pin 2); currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{th(UVLO)}$	undervoltage lockout threshold voltage		14	15	16	V
$V_{start(hys)}$	hysteresis of start voltage	during start-up phase	-	300	-	mV
$V_{hys}$	hysteresis voltage	$V_{startup} - V_{th(UVLO)}$	6.3	7	7.7	V
$I_{ch(low)}$	low charging current	$V_{HV} > 80\text{ V}$ ; $V_{CC} < V_{trip}$ or $V_{th(UVLO)} < V_{CC} < V_{startup}$	-1.2	-1.0	-0.8	mA
$I_{ch(high)}$	high charging current	$V_{HV} > 80\text{ V}$ ; $V_{trip} < V_{CC} < V_{th(UVLO)}$	-4.6	-5.4	-6.3	mA
$I_{CC(oper)}$	operating supply current	no load on pin FBDRIVER and PFCDRIVER	2.25	3	3.75	mA
<b>Input voltage sensing PFC (pin VINSENSE)</b>						
$V_{stop(VINSENSE)}$	stop voltage on pin VINSENSE		0.86	0.89	0.92	V
$V_{start(VINSENSE)}$	start voltage on pin VINSENSE		1.11	1.15	1.19	V
$\Delta V_{pu(VINSENSE)}$	pull-up voltage difference on pin VINSENSE	active after $V_{stop(VINSENSE)}$ is detected	-	-100	-	mV
$I_{pu(VINSENSE)}$	pull-up current on pin VINSENSE	active after $V_{stop(VINSENSE)}$ is detected	-55	-47	-40	$\mu\text{A}$
$V_{mvc(VINSENSE)max}$	maximum mains voltage compensation voltage on pin VINSENSE		4.0	-	-	V
$V_{flr}$	fast latch reset voltage	active after $V_{th(UVLO)}$ is detected	-	0.75	-	V
$V_{flr(hys)}$	hysteresis of fast latch reset voltage		-	0.12	-	V
$I_I(VINSENSE)$	input current on pin VINSENSE	$V_{VINSENSE} > V_{stop(VINSENSE)}$ after $V_{start(VINSENSE)}$ is detected	5	33	100	nA
$V_{bst(dual)}$	dual boost voltage	current switch-over point	-	2.2	-	V
		switch-over region	-	200	-	mV
<b>Loop compensation PFC (pin PFCCOMP)</b>						
$g_m$	transconductance	$V_{VOSENSE}$ to $I_O(PFCCOMP)$	60	80	100	$\mu\text{A/V}$
$I_O(PFCCOMP)$	output current on pin PFCCOMP	$V_{VOSENSE} = 3.3\text{ V}$	33	39	45	$\mu\text{A}$
		$V_{VOSENSE} = 2.0\text{ V}$	-45	-39	-33	$\mu\text{A}$
$V_{clamp(PFCCOMP)}$	clamp voltage on pin PFCCOMP	Low power mode; PFC off; lower clamp voltage <a href="#">[1]</a>	2.5	2.7	2.9	V
		Upper clamp voltage <a href="#">[1]</a>	-	3.9	-	V
$V_{ton(PFCCOMP)zero}$	zero on-time voltage on pin PFCCOMP		3.4	3.5	3.6	V
$V_{ton(PFCCOMP)max}$	maximum on-time voltage on pin PFCCOMP		1.20	1.25	1.30	V
<b>Pulse width modulator PFC</b>						
$t_{on(PFC)}$	PFC on-time	$V_{VINSENSE} = 3.3\text{ V}$ ; $V_{PFCCOMP} = V_{ton(PFCCOMP)max}$	3.6	4.5	5.0	$\mu\text{s}$
		$V_{VINSENSE} = 0.9\text{ V}$ ; $V_{PFCCOMP} = V_{ton(PFCCOMP)max}$	30	40	53	$\mu\text{s}$

**Table 5. Characteristics ...continued**

$T_{amb} = 25\text{ °C}$ ;  $V_{CC} = 20\text{ V}$ ; all voltages are measured with respect to ground (pin 2); currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
<b>Output voltage sensing PFC (pin VOSENSE)</b>							
$V_{th(ol)(VOSENSE)}$	open-loop threshold voltage on pin VOSENSE		-	1.15	-	V	
$V_{reg}(VOSENSE)$	regulation voltage on pin VOSENSE	for $I_{O(PFCOMP)} = 0$	2.475	2.500	2.525	V	
$V_{ovp}(VOSENSE)$	overvoltage protection voltage on pin VOSENSE		2.60	2.63	2.67	V	
$I_{bst(dual)}$	dual boost current	$V_{VINSENSE} < V_{bst(dual)}$ or $V_{VOSENSE} < 2.1\text{ V}$	-	-15	-	$\mu\text{A}$	
		$V_{VINSENSE} > V_{bst(dual)}$	-	-30	-	nA	
<b>Overcurrent protection PFC (pin PFCSENSE)</b>							
$V_{sense(PFC)max}$	maximum PFC sense voltage	$\Delta V/\Delta t = 50\text{ mV}/\mu\text{s}$	0.49	0.52	0.55	V	
		$\Delta V/\Delta t = 200\text{ mV}/\mu\text{s}$	0.52	0.55	0.57	V	
$t_{leb(PFC)}$	PFC leading edge blanking time		250	310	370	ns	
$I_{prot(PFCSENSE)}$	protection current on pin PFCSENSE		-50	-	-5	nA	
<b>Soft start PFC (pin PFCSENSE)</b>							
$I_{start(soft)PFC}$	PFC soft start current		-75	-60	-45	$\mu\text{A}$	
$V_{start(soft)PFC}$	PFC soft start voltage	enabling voltage	0.46	0.50	0.54	V	
$R_{start(soft)PFC}$	PFC soft start resistance		12	-	-	k $\Omega$	
<b>Oscillator PFC</b>							
$f_{sw(PFC)max}$	maximum PFC switching frequency		100	125	150	kHz	
$t_{off(PFC)min}$	minimum PFC off-time		1.1	1.4	1.7	$\mu\text{s}$	
<b>Valley switching PFC (pin PFCAUX)</b>							
$(\Delta V/\Delta t)_{vrec(PFC)}$	PFC valley recognition voltage change with time		-	-	1.7	V/ $\mu\text{s}$	
$t_{vrec(PFC)}$	PFC valley recognition time	$V_{PFCAUX} = 1\text{ V peak-to-peak}$	<a href="#">[2]</a>	-	-	300	ns
		demagnetization to $\Delta V/\Delta t = 0$	<a href="#">[3]</a>	-	-	50	ns
$t_{to(vrec)PFC}$	PFC valley recognition time-out time		3	4	6	$\mu\text{s}$	
<b>Demagnetization management PFC (pin PFCAUX)</b>							
$V_{th(comp)PFCAUX}$	comparator threshold voltage on pin PFCAUX		-150	-100	-50	mV	
$t_{to(demag)PFC}$	PFC demagnetization time-out time		40	50	60	$\mu\text{s}$	
$I_{prot(PFCAUX)}$	protection current on pin PFCAUX	$V_{PFCAUX} = 50\text{ mV}$	-75	-	-5	nA	
<b>Driver (pin PFCDRIVER)</b>							
$I_{src(PFCDRIVER)}$	source current on pin PFCDRIVER	$V_{PFCDRIVER} = 2\text{ V}$	-	-0.5	-	A	

**Table 5. Characteristics ...continued**

$T_{amb} = 25\text{ }^{\circ}\text{C}$ ;  $V_{CC} = 20\text{ V}$ ; all voltages are measured with respect to ground (pin 2); currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{\text{sink(PFCDRIVER)}}$	sink current on pin PFCDRIVER	$V_{\text{PFCDRIVER}} = 2\text{ V}$	-	0.7	-	A
		$V_{\text{PFCDRIVER}} = 10\text{ V}$	-	1.2	-	A
$V_{\text{O(PFCDRIVER)max}}$	maximum output voltage on pin PFCDRIVER		-	11	12	V
<b>Overvoltage protection flyback (pin FBAUX)</b>						
$I_{\text{ovp(FBAUX)}}$	overvoltage protection current on pin FBAUX		279	300	321	$\mu\text{A}$
$N_{\text{cy(ovp)}}$	number of overvoltage protection cycles		6	8	12	
<b>Demagnetization management flyback (pin FBAUX)</b>						
$V_{\text{th(comp)FBAUX}}$	comparator threshold voltage on pin FBAUX		60	80	110	mV
$I_{\text{prot(FBAUX)}}$	protection current on pin FBAUX	$V_{\text{FBAUX}} = 50\text{ mV}$	-50	-	-5	nA
$V_{\text{clamp(FBAUX)}}$	clamp voltage on pin FBAUX	$I_{\text{FBAUX}} = -500\text{ }\mu\text{A}$	-1.0	-0.8	-0.6	V
		$I_{\text{FBAUX}} = 500\text{ }\mu\text{A}$	0.5	0.7	0.9	V
$t_{\text{sup(xfmr\_ring)}}$	transformer ringing suppression time		1.5	2	2.5	$\mu\text{s}$
<b>Pulse width modulator flyback</b>						
$t_{\text{on(fb)min}}$	minimum flyback on-time		-	$t_{\text{leb}}$	-	ns
$t_{\text{on(fb)max}}$	maximum flyback on-time		32	40	48	$\mu\text{s}$
<b>Oscillator flyback</b>						
$f_{\text{sw(fb)max}}$	maximum flyback switching frequency		100	125	150	kHz
$V_{\text{start(VCO)FBCTRL}}$	VCO start voltage on pin FBCTRL		1.3	1.5	1.7	V
$V_{\text{hys(FBCTRL)}}$	hysteresis voltage on pin FBCTRL	[4]	-	60	-	mV
$\Delta V_{\text{VCO(FBCTRL)}}$	VCO voltage difference on pin FBCTRL		-	-0.1	-	V
<b>Peak current control flyback (pin FBCTRL)</b>						
$V_{\text{FBCTRL}}$	voltage on pin FBCTRL	for maximum flyback peak current	1.85	2.0	2.15	V
$V_{\text{to(FBCTRL)}}$	time-out voltage on pin FBCTRL	enable voltage	-	2.5	-	V
		trip voltage	4.2	4.5	4.8	V
$R_{\text{int(FBCTRL)}}$	internal resistance on pin FBCTRL		-	3	-	k $\Omega$
$I_{\text{O(FBCTRL)}}$	output current on pin FBCTRL	$V_{\text{FBCTRL}} = 0\text{ V}$	-1.4	-1.19	-0.93	mA
		$V_{\text{FBCTRL}} = 2\text{ V}$	-0.6	-0.5	-0.4	mA
$I_{\text{to(FBCTRL)}}$	time-out current on pin FBCTRL	$V_{\text{FBCTRL}} = 2.6\text{ V}$	-36	-30	-24	$\mu\text{A}$
		$V_{\text{FBCTRL}} = 4.1\text{ V}$	-34.5	-28.5	-22.5	$\mu\text{A}$
<b>Valley switching flyback (pin HV)</b>						
$(\Delta V/\Delta t)_{\text{vrec(fb)}}$	flyback valley recognition voltage change with time		-75	-	+75	V/ $\mu\text{s}$

**Table 5. Characteristics ...continued**

$T_{amb} = 25\text{ }^{\circ}\text{C}$ ;  $V_{CC} = 20\text{ V}$ ; all voltages are measured with respect to ground (pin 2); currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{d(\text{vrec-swon})}$	valley recognition to switch-on delay time		[5] -	150	-	ns
<b>Soft start flyback (pin FBSENSE)</b>						
$I_{\text{start(soft)fb}}$	flyback soft start current		-75	-60	-45	$\mu\text{A}$
$V_{\text{start(soft)fb}}$	flyback soft start voltage	enable voltage	0.43	0.49	0.54	V
$R_{\text{start(soft)fb}}$	flyback soft start resistance		12	-	-	$\text{k}\Omega$
<b>Overcurrent protection flyback (pin FBSENSE)</b>						
$V_{\text{sense(fb)max}}$	maximum flyback sense voltage	$\Delta V/\Delta t = 50\text{ mV}/\mu\text{s}$	0.49	0.52	0.55	V
		$\Delta V/\Delta t = 200\text{ mV}/\mu\text{s}$	0.52	0.55	0.58	V
$t_{\text{leb(fb)}}$	flyback leading edge blanking time		255	305	355	ns
$I_{\text{start(OPP)FBAUX}}$	OPP start current on pin FBAUX		-	-100	-	$\mu\text{A}$
$I_{\text{opp(red)FBAUX}}$	reduced overpower protection current on pin FBAUX	$V_{\text{sense(fb)max}}$ has reduced to 0.37 V	-	-360	-	$\mu\text{A}$
<b>Driver (pin FBDRIVER)</b>						
$I_{\text{src(FBDRIVER)}}$	source current on pin FBDRIVER	$V_{\text{FBDRIVER}} = 2\text{ V}$	-	-0.5	-	A
$I_{\text{sink(FBDRIVER)}}$	sink current on pin FBDRIVER	$V_{\text{FBDRIVER}} = 2\text{ V}$	-	0.7	-	A
		$V_{\text{FBDRIVER}} = 10\text{ V}$	-	1.2	-	A
$V_{\text{O(FBDRIVER)(max)}}$	maximum output voltage on pin FBDRIVER		-	11	12	V
<b>LATCH input (pin LATCH)</b>						
$V_{\text{prot(LATCH)}}$	protection voltage on pin LATCH		1.23	1.25	1.27	V
$I_{\text{O(LATCH)}}$	output current on pin LATCH	$V_{\text{prot(LATCH)}} < V_{\text{LATCH}} < V_{\text{oc(LATCH)}}$	-85	-80	-75	$\mu\text{A}$
$V_{\text{en(LATCH)}}$	enable voltage on pin LATCH	at start-up	1.30	1.35	1.40	V
$V_{\text{hys(LATCH)}}$	hysteresis voltage on pin LATCH	$V_{\text{en(LATCH)}} - V_{\text{prot(LATCH)}}$	80	100	140	mV
$V_{\text{oc(LATCH)}}$	open-circuit voltage on pin LATCH		2.65	2.9	3.15	V
<b>Temperature protection</b>						
$T_{\text{pl(IC)}}$	IC protection level temperature		130	140	150	$^{\circ}\text{C}$
$T_{\text{pl(IC)hys}}$	hysteresis of IC protection level temperature		-	10	-	$^{\circ}\text{C}$

[1] For a typical application with a compensation network on pin PFCCOMP, like the example in [Figure 3](#).

[2] Minimum required voltage change time for valley recognition on pin PFCAUX.

[3] Minimum time required between demagnetization detection and  $\Delta V/\Delta t = 0$  on pin PFCAUX.

[4] Hysteresis for PFC on/off control.

[5] Guaranteed by design.



## 11. Application information

A power supply with the TEA1751(L)T consists of a power factor correction circuit followed by a flyback converter. See [Figure 16](#).

Capacitor  $C_{VCC}$  buffers the IC supply voltage, which is powered via the high voltage rectified mains during start-up and via the auxiliary winding of the flyback converter during operation. Sense resistors  $R_{SENSE1}$  and  $R_{SENSE2}$  convert the current through the MOSFETs S1 and S2 into a voltage at pins PFCSENSE and FBSENSE. The values of  $R_{SENSE1}$  and  $R_{SENSE2}$  define the maximum primary peak current in MOSFETs S1 and S2. In the example given, the LATCH pin is connected to a Negative Temperature Coefficient

(NTC) resistor. When the resistance drops below  $\frac{V_{prot(LATCH)}}{I_{O(LATCH)}} = 15.6 \text{ k}\Omega$  (typ), the

protection is activated. A capacitor  $C_{TIMEOUT}$  is connected to the FBCTRL pin. For a 120 nF capacitor, typically after 10 ms the time-out protection is activated.  $R_{LOOP}$  is added so that the time-out capacitor does not interfere with the normal regulation loop.

$R_{S1}$  and  $R_{S2}$  are added to prevent the soft start capacitors from being charged during normal operation due to negative voltage spikes across the sense resistors.

Resistor  $R_{AUX1}$  is added to protect the IC from damage during lightning events.

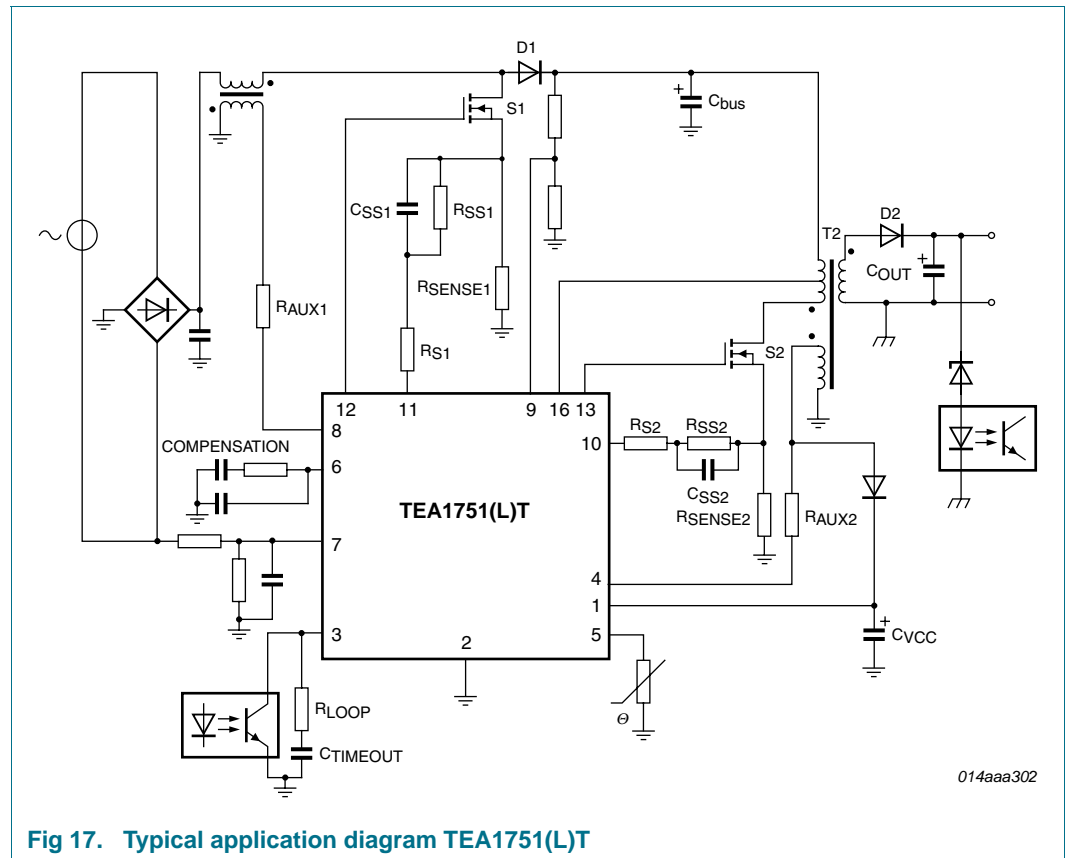


Fig 17. Typical application diagram TEA1751(L)T

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

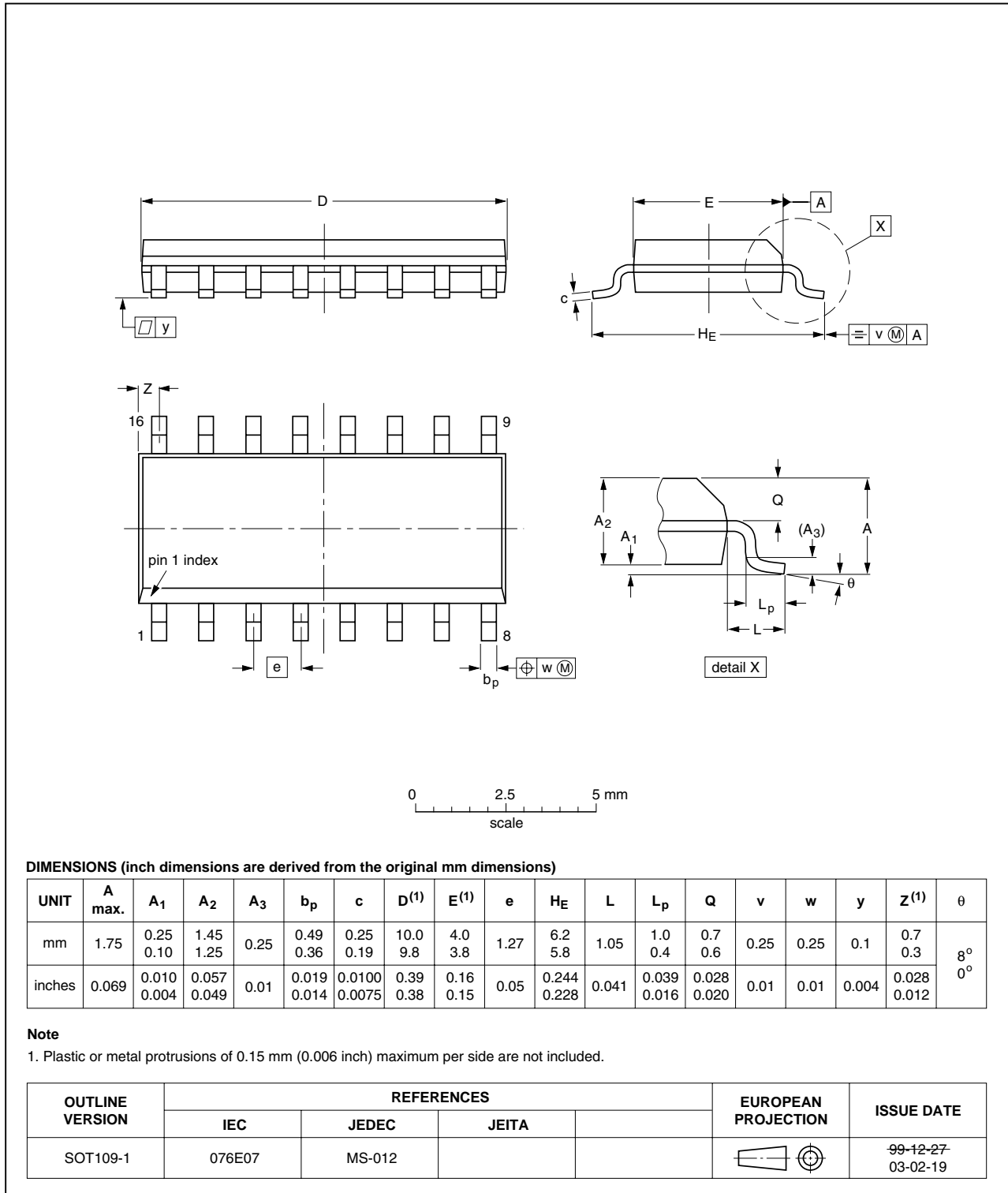


Fig 18. Package outline SOT109-1 (SO16)

## 13. Revision history

Table 6. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
TEA1751T_LT_2	20091223	Product data sheet	-	TEA1751T_LT_1
Modifications:	• Value for junction temperature ( $T_j$ ) changed in <a href="#">Table 3</a> .			
TEA1751T_LT_1	20090210	Product data sheet	-	-

## 14. Legal information

### 14.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

