

# Inductive positioning system PMI14V-F112-2EP-IO-V31

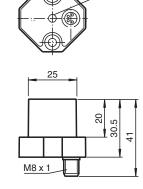
- Parameterization and diagnosis via IO-Link
- 2 configurable switching frames
- Measuring range 0 ... 14 mm

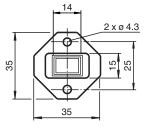






### **Dimensions**



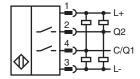


### **Technical Data**

General specifications		
Installation		flush
Object distance		max. 2.5 mm
Measurement range		0 14 mm
Nominal ratings		
Operating voltage	$U_B$	10 30 V
Reverse polarity protection		reverse polarity protected
Linearity error		± 0.3 mm
Repeat accuracy	R	± 0.05 mm
Resolution		33 μm

Technical Data		
Temperature drift		± 0.5 mm
No-load supply current	$I_0$	≤ 20 mA
Operating voltage indicator		LED green
Functional safety related parameters		
MTTF <sub>d</sub>		490 a
Mission Time (T <sub>M</sub> )		20 a
Diagnostic Coverage (DC)		0 %
Interface		
Interface type		IO-Link
Mode		COM 2 (38.4 kBaud)
Value range		0000h 7000h
Switching output		
Output type		2 Push-pull (4 in 1) outputs , short-circuit protected , reverse polarity protected , overvoltage protected , programmable
Operating current	IL	≤ 100 mA / output
Switching hysteresis		3-step, adjustable 0.2 m 0.8 mm
Voltage drop		≤3 V
Short-circuit protection		pulsing
Compliance with standards and directives		
Standard conformity		
Standards		EN 60947-5-2:2007 EN 60947-5-2:/A1:2012 IEC 60947-5-2:2007 IEC 60947-5-2 AMD 1:2012 IEC 61131-9:2013
Approvals and certificates		
UL approval		cULus Listed, Class 2 Power Source, Type 1 enclosure
CCC approval		CCC approval / marking not required for products rated ≤36 V
Ambient conditions		
Ambient temperature		-25 70 °C (-13 158 °F)
Mechanical specifications		
Connection type		M8 x 1 connector, 4-pin
Housing material		diecast zinc, not laquered or coated
Degree of protection		IP67
Material		
Target		mild steel, e. g. 1.0037, SR235JR (formerly St37-2)
Note		The data relating to accuracy only apply to a distance to the object to be detected of 1 $\dots$ 2.5 mm.

## Connection

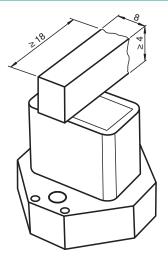


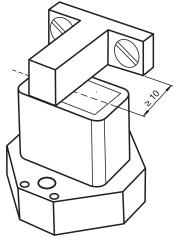
# 2 1 3

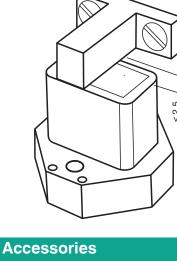
Wire colors in accordance with EN 60947-5-2

1 BN (brown)
2 WH (white)
3 BU (blue)
4 BK (black)

### **Installation Conditions**







4	BT-F90-W	Damping element for sensors of type F90, F112, and F166; side hole
	V31-GM-2M-PUR-V1-G	Double-ended cordset, M8 to M12, 4-pin, PUR cable
	BT-F90-G	Damping element for sensors of type F90, F112, and F166; front hole

### **Description of Sensor Functions**

### **Additional Functions and Parameters (IO-Link)**

Additional functions	Sensor temperature indicator
	Measuring range overrun and underrun indicator
Measuring range	Scalable measuring range
	Invertible measuring range
Switching outputs	Switching point can be parameterized/taught in
	Switching window can be parameterized/taught in
	Switching hysteresis can be parameterized
	Invertible switching output
	Selectable output type (high or low switched)

### Installation

### Information on Installation and Operation

### **Safety Information**



This product must not be used in applications in which the safety of persons depends on the function of the device. This product is not a safety component as specified in the EU Machinery Directive.

Warnung

### **Actuator**

The linear position measurement system is optimally aligned to the geometry of Pepperl+Fuchs actuators.

### **Using Your Own Actuators**

Generally speaking, it is possible for you to use your own actuators. The specified measurement accuracy of the sensor will be achieved only if the actuator has the following properties:

- Material: construction steel such as S235JR+AR (previously St37)
- Dimensions (L x W x H):  $\geq$  18 mm x 8 mm x  $\geq$  4 mm
- The active surface of the actuator must protrude across the entire sensor width.

### Note

The width of the actuator must be precisely 8 mm. If the width of the actuator deviates from this value, the position values will differ.

### Installation

- · It is possible to flush mount the device.
- The distance between the center of the measurement field (framed area on the front panel of the sensor) and the fixing base or fixing elements (e.g., protruding screw heads) of the actuator must be at least 10 mm.

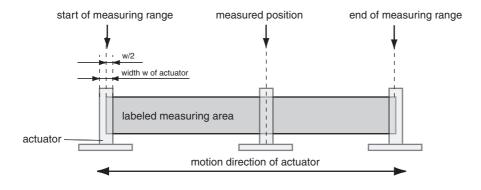
### **Operating Instructions**

The specified measurement accuracy is achieved if the distance of the actuator from the sensor surface is max. 2.5 mm.

### **Definition of the Measuring Range/Measured Position**

The measured position of the actuator is based on half of the width (center of the actuator).

The measuring range starts and ends when the actuator covers the measurement field marked on the sensor with half of its width in the course of its longitudinal movement.



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### **Parameterization**

### **Supported IO-Link device parameters**

Index	Subindex	Name			
Smart sensor profile parameters					
0x3A		Teach-In Channel			
0x3B		Teach-In Status			
0x3C	1, 2	BD1_SPV, Switching signal 1			
0x3D	1, 2, 3	BD1_SPV, Switching signal 1 configuration			
0x3E	1, 2	BD2_SPV, Switching signal 2			
0x3F	1, 2, 3	BD2_SPV, Switching signal 2 configuration			
0x4000	1, 2	BD3_SPV, Switching signal 3			
0x4001	1, 2, 3	BD3_SPV, Switching signal 3 configuration			
Device specific operation parameters					
0x40	1, 2, 3	Centered Window Width			
0x42	1, 2	AD_SPC, Analog signal setpoint value			
0x43	1, 2, 3	AD_SPC, Analog signal configuration			
0x5F	1, 2, 3, 4, 5	Measurement data collection			
Standard o	peration control				
0x70	1, 2, 3, 4, 5, 6, 7, 8	Output configuration			
0x74		Event configuration			
0x7F		Locator indication control			
User inform	User information				
0xC0		UT1, User tag 1			
0xC1		UT2, User tag 2			
Special fun	ction				
0xE2		Operating temperature			
0xE8	1, 2	Device characteristics			
Dotails of t	Details of the listed device parameters can be found in the manual				

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