LED Drivers for LCD Backlights

# White Backlight LED Driver for Medium to Large LCD Panels (Switching Regulator Type)

**BD6142AMUV**

No.11040EAT11

## ●Description

This IC is white LED driver IC with PWM step-up DC/DC converter that can boost max 41V and current driver that can drive max 30mA. The wide and precision brightness can be controlled by external PWM pulse. This IC has very accurate current drivers, and it has few current errors between each strings. So, it will be helpful to reduce brightness spots on the LCD panel. Small package is suited for saving space.

## ●Features

1) High efficiency PWM step-up DC/DC converter (fsw=typ 1.25MHz, 0.60MHz ~ 1.6MHz)
2) High accuracy & good matching current drivers 8ch (MAX30mA/ch)
3) Integrated 50V power Nch MOSFET
4) Soft Start function
5) Drive up to 11 LEDs in series, 8 strings in parallel
6) Wide input voltage range (4.2V ~ 27V)
7) Rich safety functions
   - Over-voltage protection
   - External SBD open detect / Output Short protection
   - Over current limit
   - CH Terminal open / GND short protect
   - CH over voltage protect / LED short protect
   - hermal shutdown
   - UVLO
8) Analog Brightness Control
9) Small & thin package (VQFN024V4040) 4.0 × 4.0 × 1.0mm

## ●Applications

All medium sized LCD equipments, Backlight of Notebook PC, net book, monitor, light, Portable DVD player, light source etc.


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●**Absolute maximum ratings** (Ta=25℃)

| Parameter | Symbol | Ratings | Unit | Condition |
|---|---|---|---|---|
| Maximum applied voltage 1 | VMAX1 | 7 | V | VDC, ISET, ABC, COMP, FSET, TEST, FAULT |
| Maximum applied voltage 2 | VMAX2 | 45 | V | CH1 ~ CH8, LX, OVP |
| Maximum applied voltage 3 | VMAX3 | 30.5 | V | VIN, Enable |
| Maximum applied voltage 4 | VMAX4 | 15 | V | PWM |
| Power dissipation 1 | Pd1 | 500 *1 | mW | |
| Power dissipation 2 | Pd2 | 780 *2 | mW | |
| Power dissipation 3 | Pd3 | 1510 *3 | mW | |
| Operating temperature range | Topr | -40 ~ +85 | ℃ | |
| Storage temperature range | Tstg | -55 ~ +150 | ℃ | |

*1 Reduced 4.0mW/ ℃ With Ta>25℃ when not mounted on a heat radiation Board.
*2 1 layer (ROHM Standard board) has been mounted. Copper foil area 0mm$^2$, When it's used by more than Ta=25 ℃, it's reduced by 6.2mW/ ℃.
*3 4 layer (JEDEC Compliant board) has been mounted. Copper foil area 1layer 6.28mm$^2$, Copper foil area 2~4layers 5655.04mm$^2$, When it's used by more than Ta=25 ℃, it's reduced by 12.1mW/℃.

●**Operating conditions** (Ta=-40℃ ~ +85℃)

| Parameter | Symbol | Limits | | | Unit | Conditions |
|---|---|---|---|---|---|---|
| | | Min. | Typ. | Max. | | |
| Power supply voltage | VIN | 4.2 | 12.0 | 27.0 | V | |


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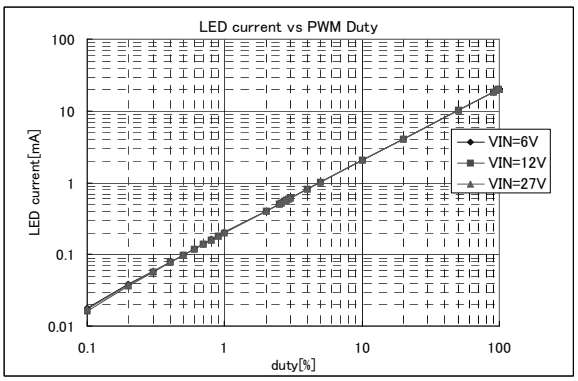
●**Electrical characteristics** (Unless otherwise specified, VIN=12V, Ta = +25℃)

| Parameter | Symbol | Limits | | | Unit | Conditions |
|---|---|---|---|---|---|---|
| | | Min. | Typ. | Max. | | |
| [General] | | | | | | |
| Quiescent Current | Iq | - | 1.6 | 4.4 | μA | Enable=0V |
| Current Consumption | Idd | - | 3.6 | 5.4 | mA | OVP=0V,ISET=36kΩ |
| Max. Output Voltage | MOV | - | - | 41 | V | |
| Under Voltage Lock Out | UVLO | 3.1 | 3.7 | 4.1 | V | VIN falling edge |
| [Enable Terminal] | | | | | | |
| Low Input Voltage range | EnL | 0.0 | - | 0.8 | V | |
| High Input Voltage range1 | EnH | 2.0 | - | VIN | V | |
| Pull down resistor | EnR | 100 | 300 | 500 | kΩ | Enable=3V |
| Output Current | ENIout | - | 0 | 2 | μA | Enable=0V |
| [PWM Terminal] | | | | | | |
| Low Input Voltage range | PWML | 0.0 | - | 0.8 | V | |
| High Input Voltage range2 | PWMH | 1.3 | - | 12.0 | V | |
| Pull down resistor | PWMR | 100 | 300 | 500 | kΩ | PWM=3V |
| Output Current | PWMIout | - | 0 | 2 | μA | PWM=0V |
| [FAULT] | | | | | | |
| Nch RON | FFCR | - | - | 3 | kΩ | Enable=PWM=3V, OVP=2V |
| [Regulator] | | | | | | |
| VDC Voltage | VREG | 4.2 | 5.0 | 6.0 | V | No load, VIN > 6V |
| [Switching Regulator] | | | | | | |
| LED Control voltage | VLED | 0.64 | 0.80 | 0.96 | V | |
| Switching frequency accuracy | Fsw | 1.00 | 1.25 | 1.50 | MHz | FSET=56kΩ |
| Duty cycle limit | Duty | 91.0 | 95.0 | 99.0 | % | CH1-8=0.3V, FSET=56kΩ |
| LX Nch FET RON | RON | - | 0.48 | 0.58 | Ω | ILX=80mA |
| [Protection] | | | | | | |
| Over Current Limit | Ocp | 1.5 | 2.5 | - | A | *1 |
| Over voltage limit Input | OVP | 1.16 | 1.20 | 1.24 | V | Detect voltage of OVP pin |
| Output Short Protect | OVPfault | 0.02 | 0.05 | 0.08 | V | Detect voltage of OVP pin |
| OVP leak current | OVIL | - | 0.1 | 1.0 | μA | |
| CH Terminal Over Voltage Protect accuracy | VSC | -15 | 0 | +15 | % | VSC=5V |
| [Current driver] | | | | | | |
| LED maximum current | ILMAX | - | - | 30 | mA | |
| LED current accuracy | ILACCU | - | - | ±2.5 | % | ILED=20mA (36kΩ) |
| LED current matching | ILMAT | - | - | 2.5 | % | (Max LED current – Min LED current)/ Ideal current (20mA) ILED=20mA |
| LED current matching2 | ILMAT2 | - | - | 1.5 | % | ▪Each LED current/Average (CH1- 8) ▪ILED=20mA |
| LED current limiter | ILOCP | - | 0 | 0.1 | mA | Current limit value at ISET Resistance 1kΩ setting |
| ISET voltage | Iset | - | 0.733 | - | V | |
| LED current accuracy2 | ILACCU2 | - | ±3.0 | - | % | ILED=20mA, ABC=0.733V |

*1 This parameter is tested with DC measurement.

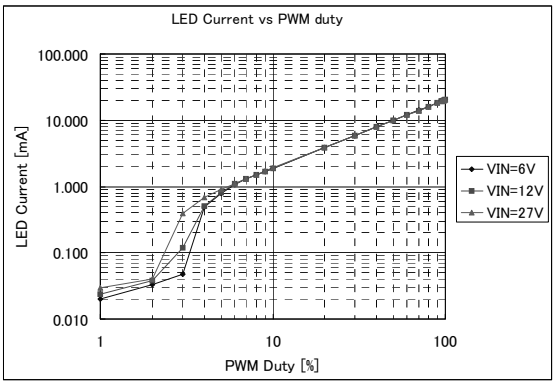

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## ●Reference data



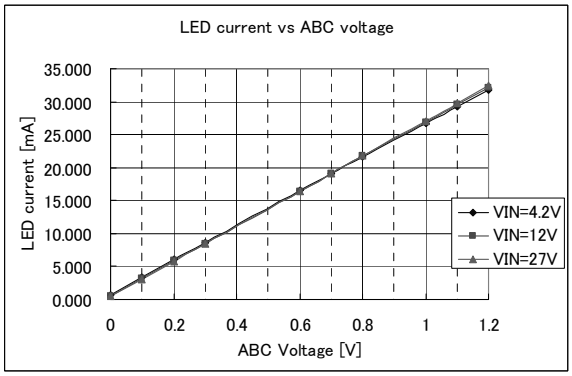

<Condition>
■10serial × 8parallel
■Ta = 25℃
■LED Current = 20mA
■PWM frequency = 200Hz
■Frequency = 1.25MHz(FSET=56kΩ)
■Coil = 10μH

Fig. 1 LED current characteristics PWM dimming



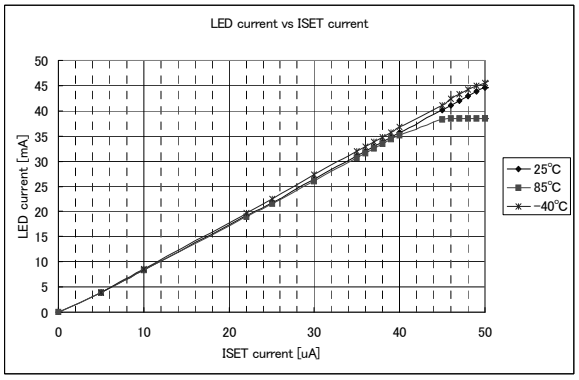

<Condition>
■10 serial × 8parallel
■Ta = 25℃
■LED Current = 20mA
■PWM frequency = 30kHz
■Frequency = 1.25MHz(FSET=56kΩ)
■Coil = 4.7μH

Fig. 2 LED current characteristics PWM dimming



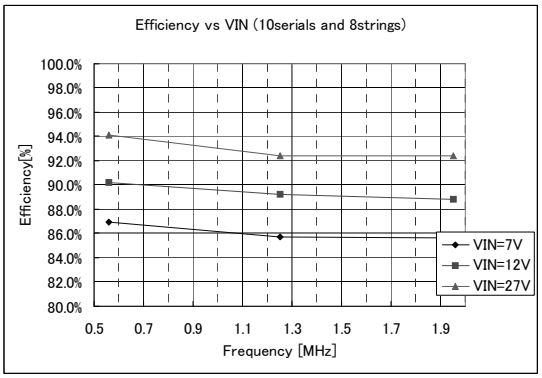

<Condition>
■Ta = 25℃
■ISET = 36kΩ
■CH1 = 0.8V

Fig. 3 LED current characteristics Analog dimming



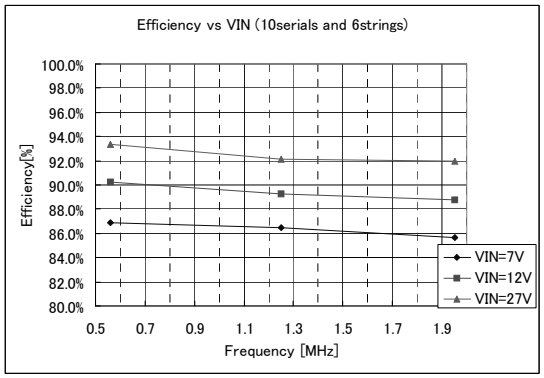

<Condition>
■VIN = 12V
■CH1 = 0.8V

Fig. 4 LED maximum current




<Condition>
■Ta = 25℃
■10 serial × 8parallel
■LED Current = 20mA
■Coil = TDK, LTF5022T-100M1R4-LC

Fig. 5 Efficiency




<Condition>
■Ta = 25℃
■10 serial × 6parallel
■LED Current = 20mA
■Coil = TDK, LTF5022T-100M1R4-LC

Fig. 6 Efficiency


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## ●Block diagram and pin configuration

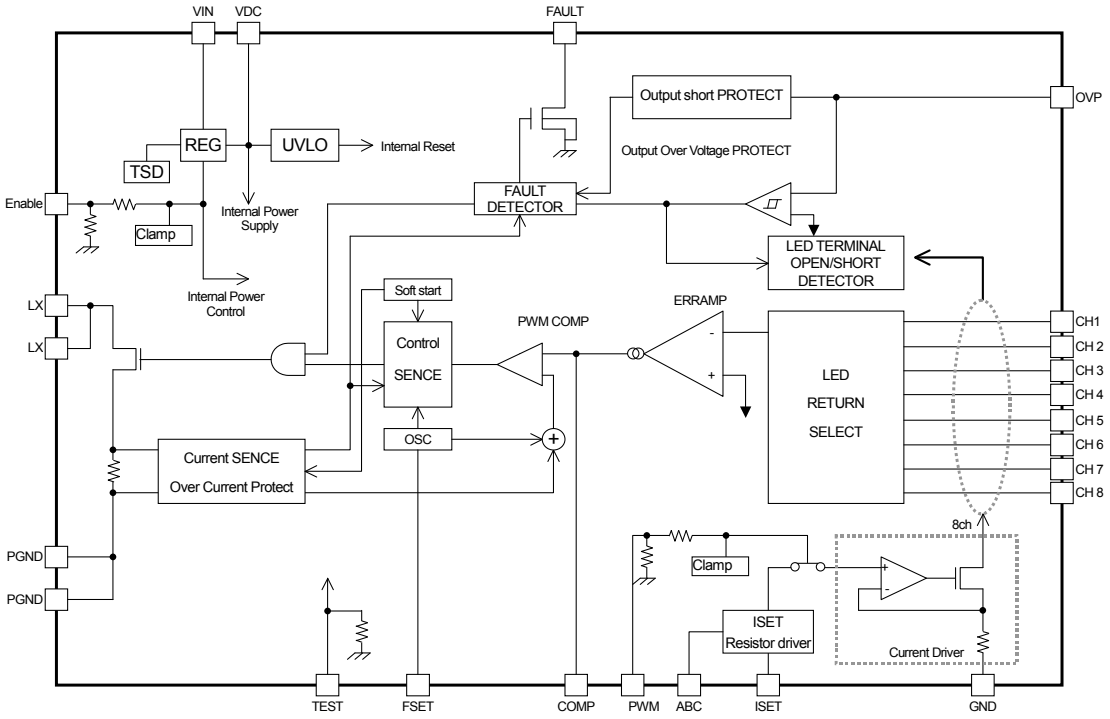
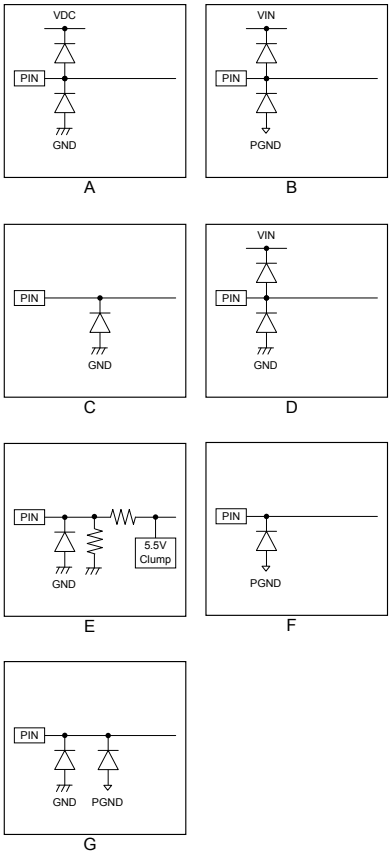



Fig. 7 Block diagram

## ●Pin assignment table

| Pin No. | Pin Name | IO | Function | Terminal diagram |
|---|---|---|---|---|
| 1 | Enable | In | PWM input pin for power ON/OFF or Power control | E |
| 2 | TEST | In | TEST signal (Pull down 100kΩ within IC) | E |
| 3 | FSET | In | Resister connection for frequency setting | A |
| 4 | ABC | In | Analog Brightness Control | C |
| 5 | GND | - | GND for Switching Regulator | B |
| 6 | PWM | In | PWM input pin for power ON/OFF only driver | E |
| 7 | CH8 | In | Current sink for CH8 | C |
| 8 | CH7 | In | Current sink for CH7 | C |
| 9 | CH6 | In | Current sink for CH6 | C |
| 10 | CH5 | In | Current sink for CH5 | C |
| 11 | ISET | In | Resister connection for LED current setting | A |
| 12 | CH4 | In | Current sink for CH4 | C |
| 13 | CH3 | In | Current sink for CH3 | C |
| 14 | CH2 | In | Current sink for CH2 | C |
| 15 | CH1 | In | Current sink for CH1 | C |
| 16 | OVP | In | Detect input for SBD open and OVP | C |
| 17 | PGND | - | PGND for switching Tr | D |
| 18 | | | | |
| 19 | LX | Out | Switching Tr drive terminal | F |
| 20 | | Out | Switching Tr drive terminal | F |
| 21 | FAULT | Out | Fault signal | C |
| 22 | COMP | Out | ERRAMP output | A |
| 23 | VIN | In | Battery input | G |
| 24 | VDC | Out | Regulator output / Internal power-supply | C |





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## ●Application example

Fig. 8, Fig. 9 and Fig. 10 are Application examples (15.4inch and 12inch and 10.1inch model). Recommended schematics and Layout are shown in Page. 21.

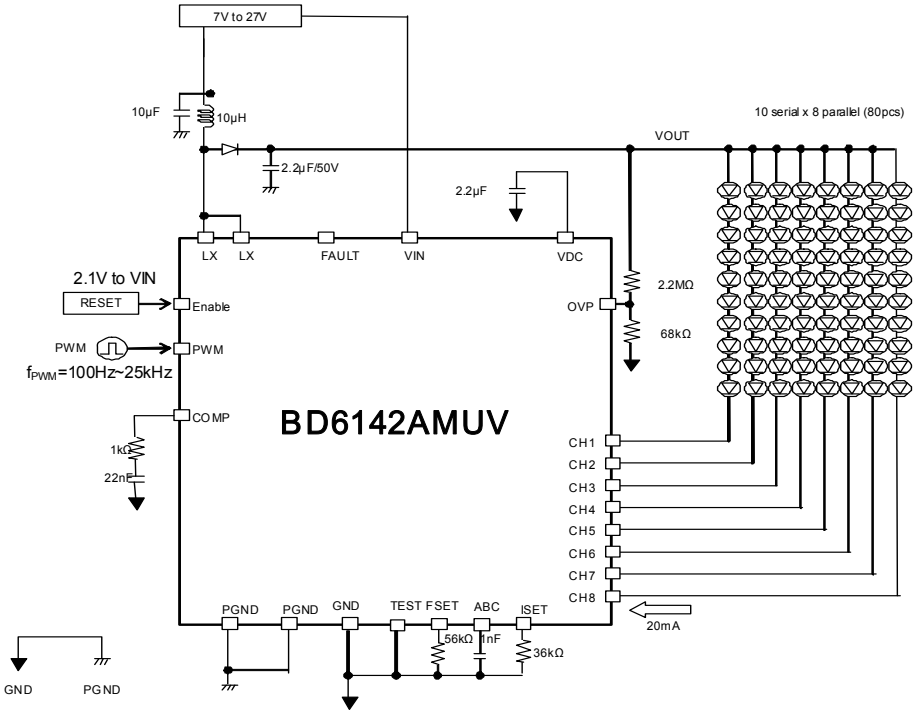



Fig. 8 BD6142A Application example (8 parallel)

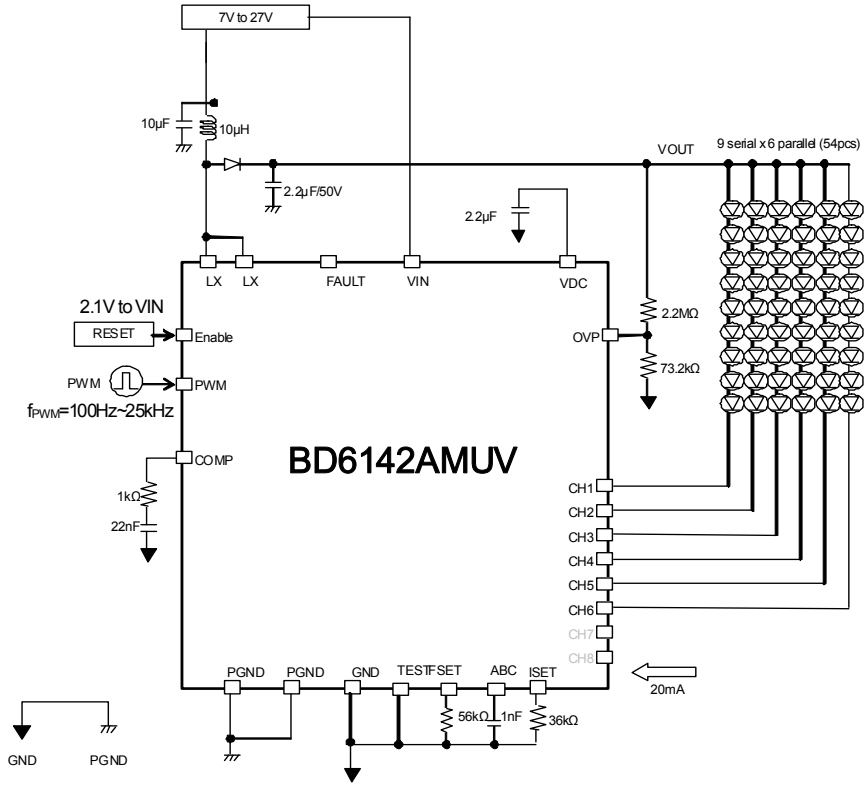



Fig. 9 BD6142A Application example (6 parallel)


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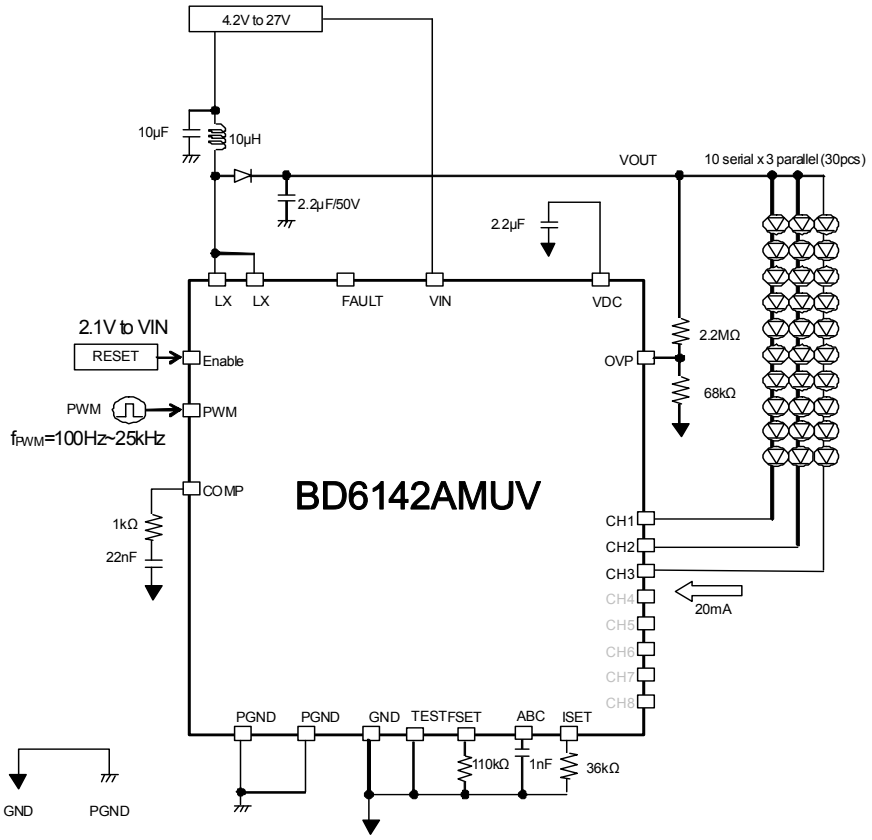



Fig. 10 BD6142A Application example (3 parallel)


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## ●Functional descriptions

1) PWM current mode DC/DC converter

While this IC is power ON, the lowest voltage of CH1, 2, 3, 4, 5, 6,7, 8 is detected, PWM duty is decided to be 0.8V and output voltage is kept invariably. As for the inputs of the PWM comparator as the feature of the PWM current mode, one is overlapped with error components from the error amplifier, and the other is overlapped with a current sense signal that controls the inductor current into Slope waveform to prevent sub harmonic oscillation. This output controls internal Nch Tr via the RS latch. In the period where internal Nch Tr gate is ON, energy is accumulated in the external inductor, and in the period where internal Nch Tr gate is OFF, energy is transferred to the output capacitor via external SBD.
This IC has many safety functions, and their detection signals stop switching operation at once.

2) Pulse skip control

This IC regulates the output voltage using an improved pulse-skip. In “pulse-skip” mode the error amplifier disables “switching” of the power stages when it detects low output voltage and high input voltage. The oscillator halts and the controller skip switching cycles. The error amplifier reactivates the oscillator and starts switching of the power stages again when this IC detects low input voltage.
At light loads a conventional “pulse-skip” regulation mode is used. The “pulse-skip” regulation minimizes the operating current because this IC does not switch continuously and hence the losses of the switching are reduced. When the error amplifier disables “switching”, the load is also isolated from the input. This improved “pulse-skip” control is also referred to as active-cycle control.

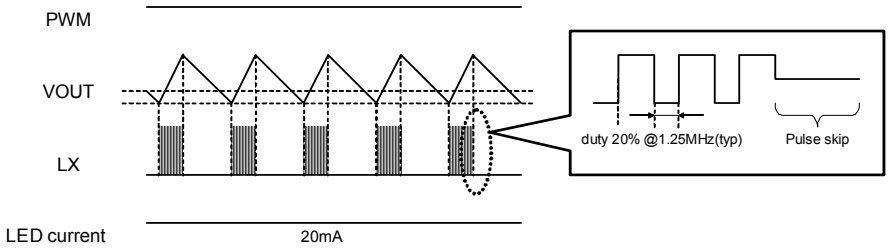



Fig. 11 Pulse-skip

3) Soft start

This IC has soft start function.
The soft start function prevents large coil current.
Rush current at turning on is prevented by the soft start function.
After Enable, PWM is changed ‘L’→ ‘H’, and UVLO is detected, soft start becomes effective for within typ 4.3ms and soft start doesn't become effective even if Enable is changed ‘L’ → ‘H’ after that.

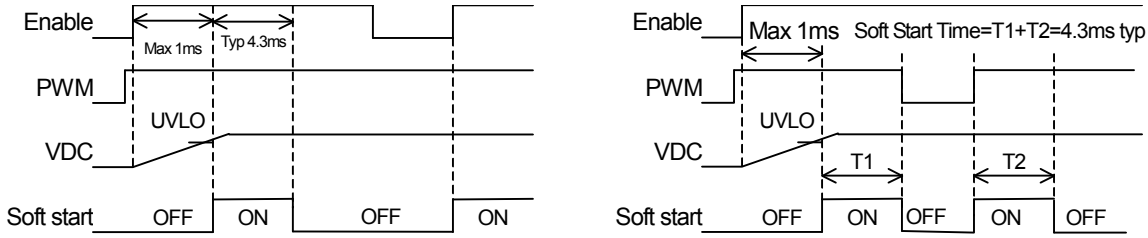



Fig. 12 Soft start

4) FAULT

When the error condition occurs, boost operating is stopped by the protection function, and the error condition is outputted from FAULT. After power ON, when the protection function is operating under about 4.3ms(typ.) have passed.
Once enable change to ‘L’, FAULT status is reset

Object of protect function is as shown below.

- Over-voltage protection (OVP)
- Thermal shut down (OTP)
- Over current limit (OCP)
- Output short protect
- LED Short (Latch)
- LED Open (Latch)

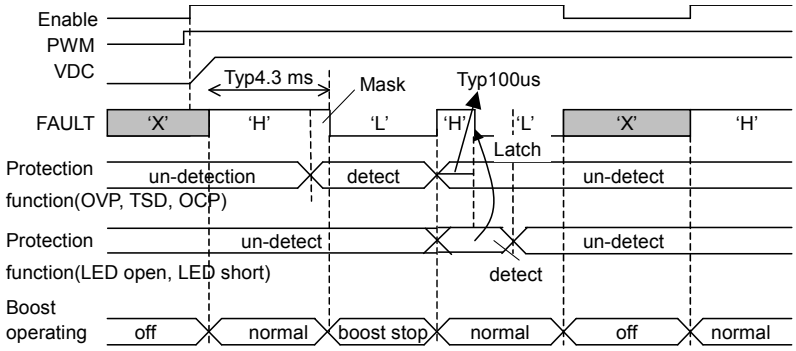



Fig. 13 FAULT operating description


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●Protection

PROTECTION TABLE

| CASE | FAILURE MODE | DETECTION MODE | FAIL CHANNEL | GOOD CHANNEL | VOUT REGULATED BY | FAULT Terminal |
|---|---|---|---|---|---|---|
| 1 | LED Short connected CH1 | CH1 > VSC(5V) | LED current stop and DC/DC feedback doesn't return | CH2 to CH8 Normal | Highest VF of CH2 to CH8 | 'H' → 'L' (Latch) |
| 2 | LED OPEN connected CH1 | CH1 < 0.2V and VOUT > VOVP | LED current stop and DC/DC feedback doesn't return | CH2 to CH8 Normal | Highest VF of CH2 to CH8 | 'H' → 'L' (Latch) |
| 3 | VOUT/LX GND SHORT | OVP < 50mV | FAULT change from L to H, and switching is stopped. When OVP>50mV, FAULT return L | | - | 'H' → 'L' |
| 4 | Output LED stack voltage too high | VOUT > VOVP | FAULT change from L to H, and switching is stopped. Even if OVP<1.2V, FAULT don't return L | | - | 'H' → 'L' |
| 5 | LX current too high | OCP > 2.5A or OTP > 130°C | FAULT change from L to H, and switching is stopped. Even if IC return normal status, FAULT don't return L | | - | 'H' → 'L' |

・Over voltage protection (OVP)

At such an error of output open as the output DC/DC and the LED is not connected to IC, the DC/DC will boost too much and the OVP terminal exceed the absolute maximum ratings, and may destruct the IC. Therefore, when OVP terminal becomes sensing voltage or higher, the over voltage limit protection works, and turns off the switching Tr, and DC/DC will be stopped.

At this moment, the IC changes from activation into non-activation, and the output voltage goes down slowly. And, when the Feedback of CH1 isn't returned, so that VOUT will return normal voltage.

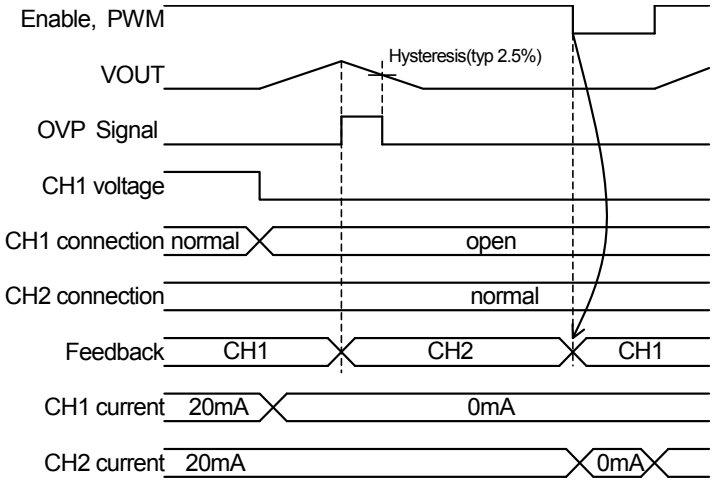



Fig. 14 OVP operating description


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This section is especially mentioned here because the spec shown electrical characteristic is necessary to explain this section.

| | | | |
|---|---|---|---|
| Over voltage limit | min 1.16V | typ 1.20V | max 1.24V |
| LED control voltage | min 0.64V | typ 0.80V | max 0.96V |
| LED terminal over voltage protect | min 4.25V | typ 5.00 V | max 5.75V |

1. Calculate the conditions that the total value of LED VF is MAX.
   Example) In the case of serial 8 LEDs with VF=2.9V(min), 3.2V(typ), 3.5V(max) => 3.5V x 8=28V

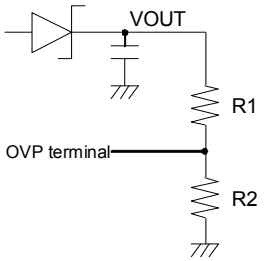
2. Then calculate the biggest value of output with the following formula.
   The biggest value of output = the biggest value calculated for 1 + the biggest value of LED terminal voltage. (0.96V)
   Example) The biggest value of output = 28V + 0.96V =28.96V

3. Set the smallest value of over voltage larger than the biggest value of output.
   If over voltage is closer to the total value of VF, it could be occurred to detect over voltage by ripple, noise, and so on.
   It is recommended that some margins should be left on the difference between over voltage and the total value of VF.
   This time around 6% margin is placed.
   Example) Against the biggest value of output = 28.96V, the smallest value of over voltage = 28.96V x 1.06 = 30.70V
   Ic over voltage limit min=1.16V, typ=1.20V, max=1.24V
   typ = 30.70V × (1.20V/1.16V) = 31.76V
   max = 31.76V × (1.26V/1.20V) = 33.35V

4. The below shows how to control resistor setting over voltage
   Please fix resistor high between OVP terminal and output and then set over voltage after changing resistor between OVP terminal and GND. While PWM is off, output voltage decreases by minimizing this resistor. Due to the decrease of output voltage, ripple of output voltage increases, and singing of output condenser also becomes bigger.
   Example) Selecting OVP resistor.

**・OVP resistor selection**

(Example. 1) VF=3.5V max, serial = 7 LED
OVP = 1.2V, R1 = 2.2MΩ, R2 = 95.3kΩ
VOUT = 1.2 × (2.2MΩ + 95.3kΩ)/ 95.3kΩ = 28.90V
(Example. 2) VF=3.5V max, serial = 8 LED
OVP = 1.2V, R1 = 2.2MΩ, R2 = 82kΩ
VOUT = 1.2 × (2.2MΩ + 82kΩ)/ 82kΩ = 33.40V
(Example. 3) VF=3.5V max, serial = 9 LED
OVP = 1.2V, R1 = 2.2MΩ, R2 = 73.2kΩ
VOUT = 1.2 × (2.2MΩ + 73.2kΩ)/ 73.2kΩ = 37.27V
(Example. 4) VF=3.5V max, serial = 10 LED
OVP = 1.2V, R1 = 2.2MΩ, R2 = 68kΩ
VOUT = 1.2 × (2.2MΩ + 68kΩ)/ 68kΩ = 40.02V




・External SBD open detect / Output Short protection

In the case of external SBD is not connected to IC, or VOUT is shorted to GND, the coil or internal Tr may be destructed. Therefore, at such an error as OVP becoming 50mV(typ.) or below, turns off the output Tr, and prevents the coil and the IC from being destructed.
And the IC changes from activation into non-activation, and current does not flow to the coil (0mA).

・Thermal shut down

This IC has thermal shut down function.
The thermal shut down works at 130°C (typ.) or higher, and the IC changes from activation into non-activation.


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●Operating of the application deficiency

1)When 1 LED or 1string OPEN during the operating

The LED string which became OPEN isn't lighting, but other LED strings are lighting.
Then LED terminal is 0V , output boosts up to the over voltage protection voltage. When over voltage is detected, the feedback of open string isn't returned, so that VOUT will return normal voltage.

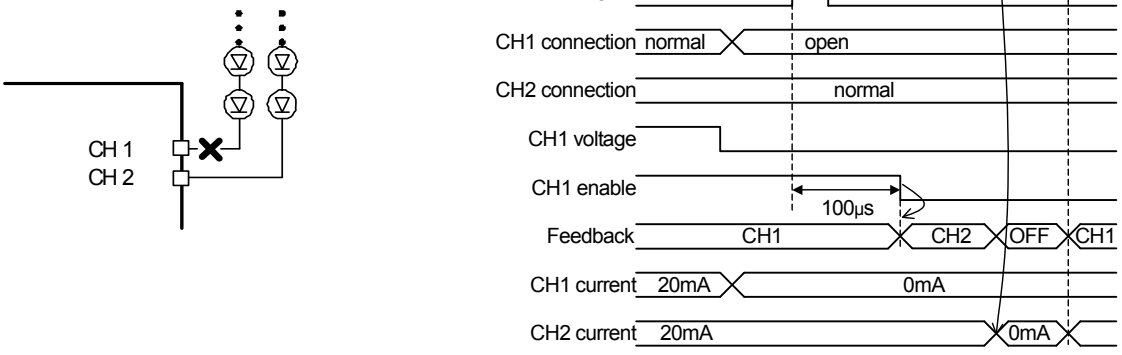



Fig. 15 LED open protect

2)When LED short-circuited in the plural

All LED strings is turned on unless CH1~8 terminal voltage is more than 5V(typ.).
When it was more than 5V only the strings which short-circuited is turned off normally and LED current of other lines continue to turn on. Short line(CH1) current is changed from 20mA to 0.05mA(typ), so CH1 terminal don't heat.

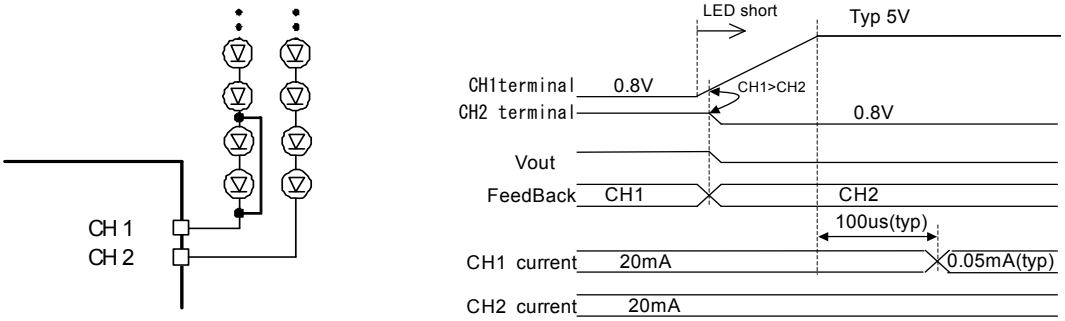



Fig. 16 LED short protect

3)When Schottky diode remove

All LED strings aren't turned on. Also, IC and a switching transistor aren't destroyed because boost operating stops by the Schottky diode open protected function.


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●Control Signal input timing

Timing sequence1

Referring to Fig.17, the recommended turn “on” sequence is VIN followed by ENABLE and PWM.
The recommended turn ”off” sequence is ENABLE and PWM followed by VIN. This sequence is recommendation.

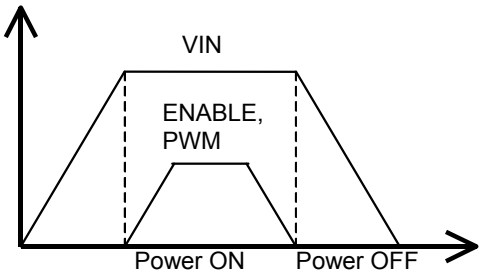
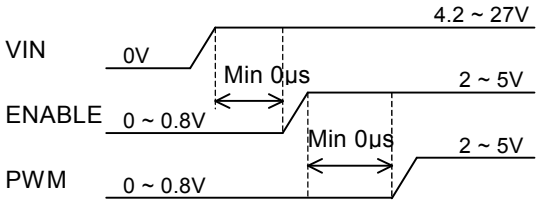


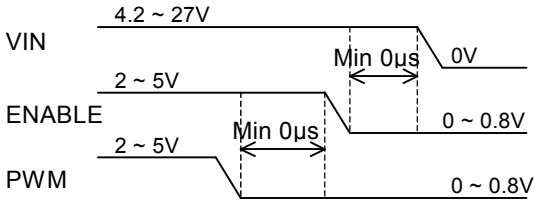

Fig. 17 Timing sequence1

LED IC Timing Sequence for PWM Control Turn-on




*other signal is input after a signal turned on.

LED IC Timing Sequence for PWM Control Turn-off




*other signal is input after a signal turned off.

Timing sequence2

Referring to Fig.18, the recommended turn “on” sequence is VIN, ENABLE followed by PWM.
The recommended turn “off” sequence is PWM followed by ENABLE and VIN.

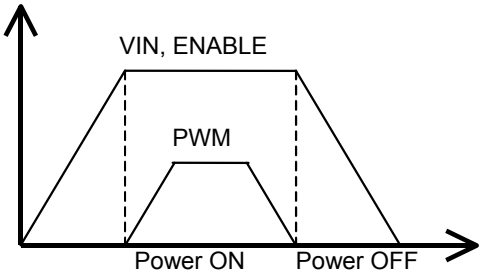
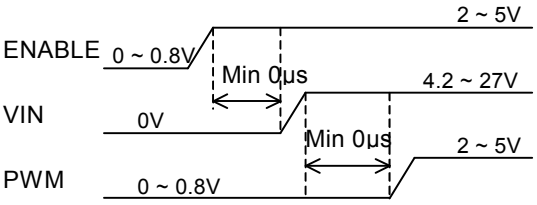


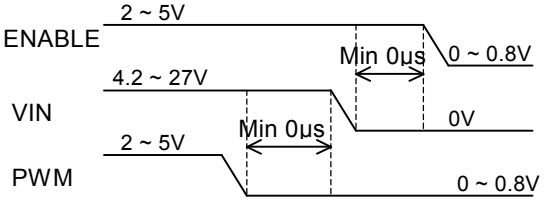

Fig. 18 Timing sequence2

LED IC Timing Sequence for PWM Control Turn-on




*other signal is input after a signal turned on.

LED IC Timing Sequence for PWM Control Turn-off




*Other signal is input after a signal turned off.


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Timing sequence3

Referring to Fig.19, the recommended turn “on” sequence is VIN, PWM followed by ENABLE.
The recommended turn “off” sequence is ENABLE followed by PWM and VIN.

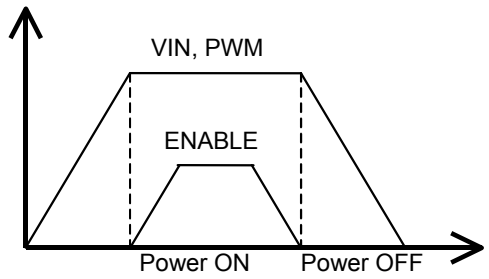
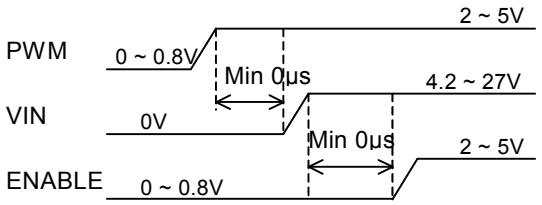


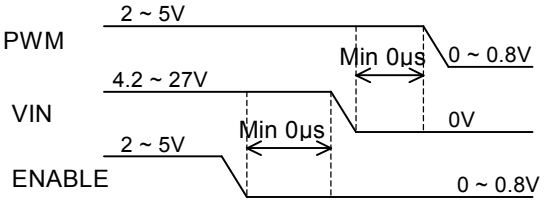

Fig. 19 Timing sequence3

LED IC Timing Sequence for PWM Control Turn-on




*other signal is input after a signal turned on.

LED IC Timing Sequence for PWM Control Turn-off




*other signal is input after a signal turned off.

VIN wake up speed

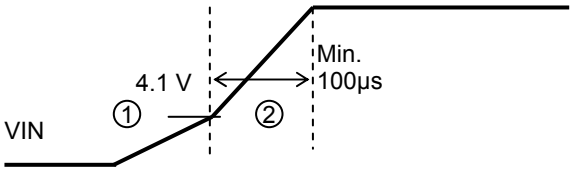



Fig. 20 control Signal timing

In case, there is PWM OFF status (min: 10ms) during operation as Fig. 21, ENABLE should turn from ‘H’ to ‘L’ as Fig.21.
If PWM stops and VOUT voltage is dropped, this IC will be condition of current limiter when PWM starts (no soft start).
If soft start isn’t needed, reset is no need.

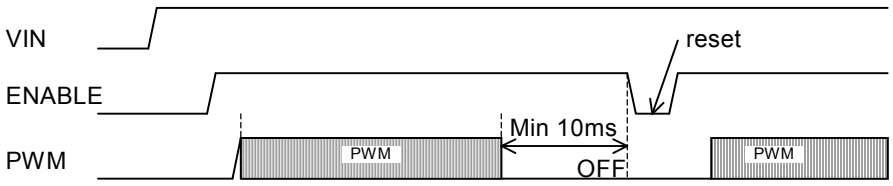



Fig. 21 PWM stop and ENABLE turn “off”


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●How to activate

Please be careful about the following when being activated.

- Regulator (VDC) operates after ENABLE=H. Inside circuit operates after releasing UVLO. When IC boosts after releasing UVLO, soft start function operates. (Refer to Fig.12, 7th page). Soft start circuit needs $t_{15}$ (more than 15μs) as Fig. 22 shows. Soft start operates for $T_{soft}$ time. Please make H width of PWM more than 15μs until soft start finishes.
- Please input PWM signal according to Fig. 23 after soft start finishes.

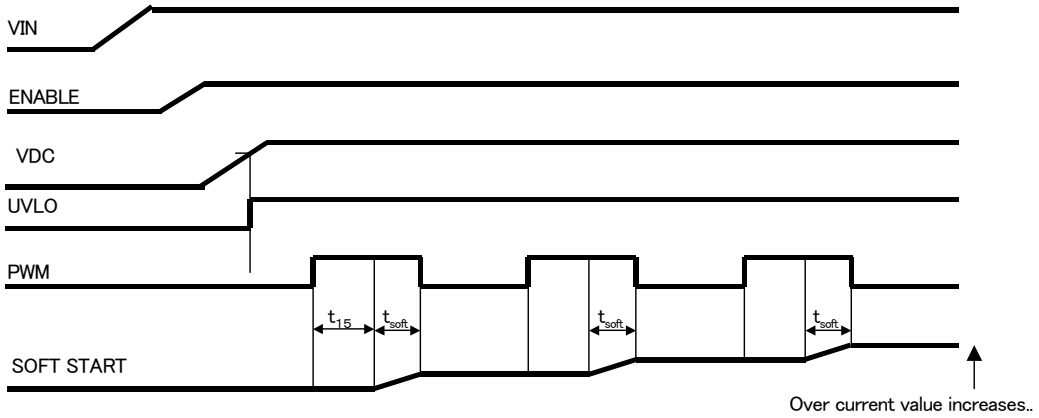



Fig. 22 Soft start

Example) Time until soft start finishes at PWM frequency 25kHz and PWM=H time16μs

According to soft start time typ4.3ms

$t_{soft}$ = 16μs – 15μs = 1μs

Soft start time/ $t_{soft}$ /PWM frequency = 4300μs / 1μs /25kHz = 4300 / 25kHz = 172ms

At light dimming of PWM terminal (after soft start finishes)

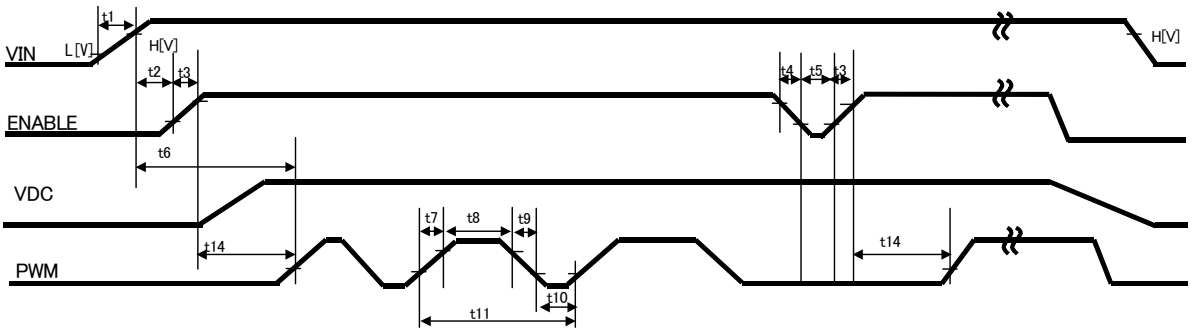



Fig. 23 Input timing (after soft start)

| | Name | Unit | Min. | Typ. | Max. |
|---|---|---|---|---|---|
| t1 | Power supply rising time | μs | 100 | - | - |
| t2 | Power supply-ENABLE time | μs | 0 | - | - |
| t3 | ENABLE rising time | μs | 0 | - | 100 |
| t4 | ENABLE falling time | μs | 0 | - | 100 |
| t5 | ENABLE low width | μs | 50 | - | - |
| t6 | Power supply-PWM time | μs | 0 | - | - |
| t7 | PWM rising time | μs | 0 | - | 100 |
| t8 | PWM high width | μs | 5 | - | - |
| t9 | PWM falling time | μs | 0 | - | 100 |
| t10 | PWM low width | μs | 5 | - | - |
| t11 | PWM frequency | μs | 40 | 5000 | 10000 |
| t12 | ENABLE (H)->PWM (H) time | μs | 0 | - | - |
| t13 | ENABLE (L)->PWM (L) time | μs | 0 | - | - |
| t14 | PWM (L)->ENABLE (L) time | μs | 0 | - | - |
| t15 | PWM high width (while soft start) | μs | 15 | - | - |
| H | Operating voltage | V | 4.2 | 12 | 27 |
| L | Non operating voltage | V | - | - | 4.2 |


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●How to select the number of LED strings of the current driver

When the number of LED strings of the current driver is reduced, the un-select can be set the matter that the unnecessary CH1 ~ 8 terminal is opened. When it uses with 6 lines and so on, it can correspond to it by becoming 2 unnecessary lines to open.

When VOUT wake up, VOUT boost up until OVP voltage. Once IC detect OVP, VOUT don't boost up until OVP from next start up. To set PWM and Enable to L, IC reset CH7, 8 status as Fig. 24. When VOUT wake up, CH8 (open terminal) and CH1 are selected as Fig. 25.

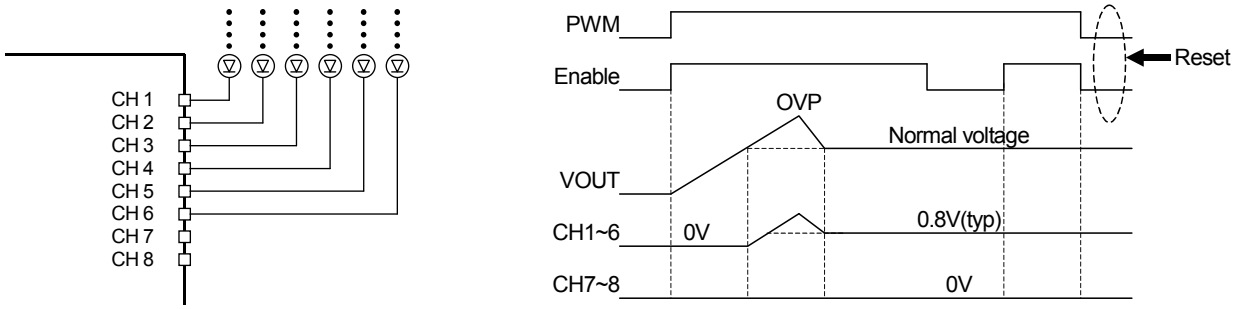



Fig. 24 Select the number of CH lines 1

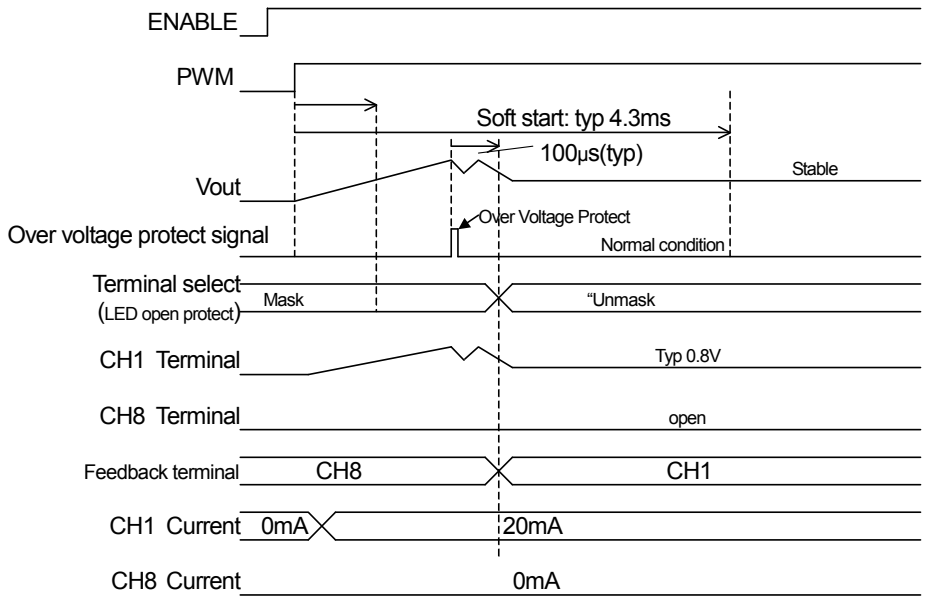



Fig. 25 Select the number of CH lines 2 (wake up)


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●Start control (Enable) and select LED current driver (PWM)

This IC can control the IC system by Enable, and IC can power off compulsory by setting 0.8V or below. Also, It powers on Enable is at more than 2.0V.
After it's selected to Enable=H, When it is selected at PWM=H, LED current decided with ISET resistance flow.
Next, When it is selected at PWM=L, LED current stop to flow.

| Enable | PWM | IC | LED current |
|---|---|---|---|
| 0 | 0 | Off | OFF |
| 1 | 0 | On | OFF |
| 0 | 1 | Off | OFF |
| 1 | 1 | On | Current decided with ISET |

●LED current setting range

LED current can set up Normal current by resistance value (RISET) connecting to ISET voltage.
Setting of each LED current is given as shown below.

RISET = 720/ILEDmax

Also, Normal current setting range is 10mA~30mA. LED current becomes a leak current MAX 2μA at OFF setting.

ISET Normal current setting example

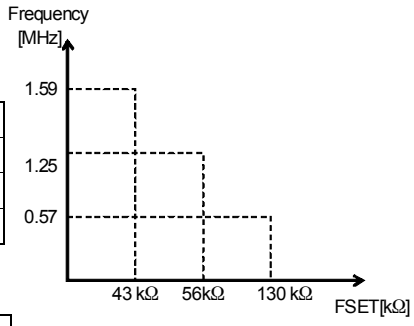
| RISET | LED current |
|---|---|
| 24kΩ (E24) | 30.0mA |
| 30kΩ (E24) | 24.0mA |
| 36kΩ (E24) | 20.0mA |
| 43kΩ (E24) | 16.7mA |
| 68kΩ (E12) | 10.6mA |

●Frequency setting range

Switching frequency can be set up by resistance value (RFSET) connecting to FSET port.
Setting of frequency is given as shown below.
Also, Frequency setting range is 0.60MHz~1.60MHz.

FSET frequency setting example

| RFSET | frequency |
|---|---|
| 130kΩ (E96) | 0.57MHz |
| 56kΩ (E24) | 1.25MHz |
| 43kΩ (E24) | 1.59MHz |




Max Duty example

| Frequency | Max Duty[%] | | |
|---|---|---|---|
| | Min | Typ | Max |
| 0.57MHz | - | 96.0 | - |
| 1.25MHz | 91.0 | 95.0 | 99.0 |
| 1.59MHz | - | 92.0 | - |

Min Duty example

| Frequency | Min Duty[%] | | |
|---|---|---|---|
| | Min | Typ | Max |
| 1.25MHz | - | 20 | - |


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## ●PWM dimming

Current driver PWM control is controlled by providing PWM signal to PWM port, as it is show in Fig. 26. The current set up with ISET is chosen as the H section of PWM and the current is off as the L section. Therefore, the average LED current is increasing in proportion to duty cycle of PWM signal. This method that it lets internal circuit and DC/DC to work, because it becomes to switch the driver, the current tolerance is a few when the PWM brightness is adjusted, it makes it possible to brightness control until 5μs (Min 0.1% at 200Hz). And, don't use for the brightness control, because effect of ISET changeover is big under 1μs ON time and under 1μs OFF time. Typical PWM frequency is 100Hz~25kHz.

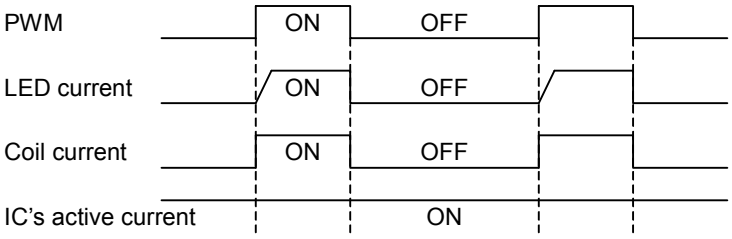
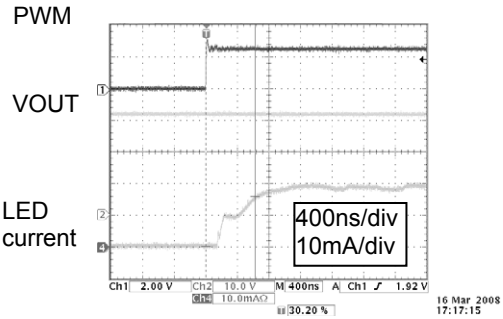
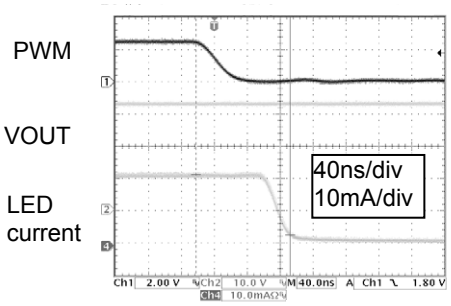



Fig. 26 PWM sequence

Conditions： 8serial 6parallel, LED current=20mA/ch,
VIN=7V, Ta=25℃, Output capacitor=2.2μF(50V/B3)




## ●Analog dimming

BD6142 control LED current according analog input (ABC terminal).
For ABC voltage = typ 0.733V, LED current can set up Normal current by resistance value (RISET) connecting to ISET voltage.
To decrease ABC voltage, LED current decrease, and to increase ABC voltage, LED current increase.

Please set max LED current to check LED current setting range of P.12
Please care that ABC voltage of max LED current is 0.733V
ABC input range is 0.05V～0.9V(Target).
This dimming is effected by ISET tolerance as follows.

When you don't use analog dimming, please set condenser to ABC terminal. Until the condenser of ABC terminal is finished to charge, LED current increase with that speed.
The resister between 1.2V and ABC terminal is 120.9kΩ.
Please select the capacitor to care charge time.

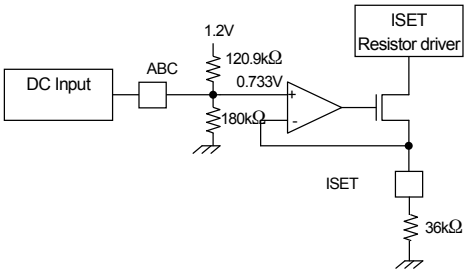



Fig. 27 Analog dimming application

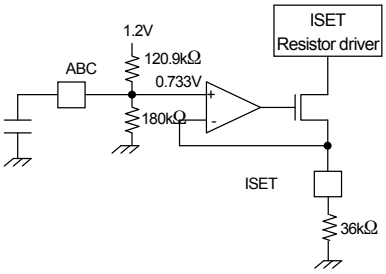



Fig. 28 PWM dimming application

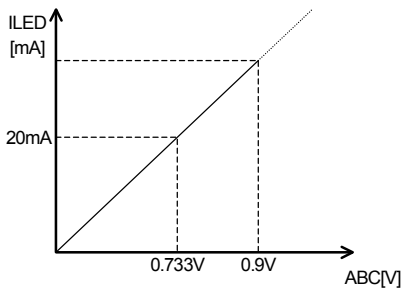



Fig. 29 ILED vs ABC voltage


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## ●Coil selection

The DC/DC is designed by more than 4.7μH. When L value sets to a lower value, it is possibility that the specific sub-harmonic oscillation of current mode DC / DC will be happened. Please do not let L value to 3.3μH or below.
And, L value increases, the phase margin of DC / DC becomes to zero. Please enlarge the output capacitor value when you increase L value. Please select lower DC resistance (DCR) type, efficiency still relies on the DCR of Inductor.
Please estimate Peak Current of Coil. Peak current can be calculated as following.

Peak Current calculation

<The estimate of the current value which need for the normal operation>
As over current detector of this IC is detected the peak current, it have to estimate peak current to flow to the coil by operating condition.

In case of,
- Supply voltage of coil = $V_{IN}$
- Inductance value of coil = L
- Switching frequency = fsw (Min=1.0MHz, Typ = 1.25MHz, Max = 1.5MHz)
- Output voltage = $V_{OUT}$
- Total LED current = $I_{LED}$
- Average current of coil = Iave
- Peak current of coil = Ipeak
- Cycle of Switching = T
- Efficiency = eff (Please set up having margin)
- ON time of switching transistor = Ton
- ON Duty = D

CCM: $I_{peak} = (V_{IN} / L) \times (1 / fsw) \times (1-( V_{IN} / V_{OUT}))$, DCM: $I_{peak} = (V_{IN} / L) \times Ton$

$I_{ave}=( V_{OUT} \times IOUT / V_{IN}) / eff$

$Ton=(I_{ave} \times (1- V_{IN} / V_{OUT}) \times (1/fsw) \times (L/ V_{IN}) \times 2)^{1/2}$

Each current is calculated.

As peak current varies according to whether there is the direct current superposed, the next is decided.

CCM: $(1- V_{IN} / V_{OUT}) \times (1/fsw) < Ton$ → peak current = Ipeak /2 + Iave

DCM: $(1- V_{IN} / V_{OUT}) \times (1/fsw) > Ton$ → peak current = $V_{IN} / L \times Ton$

(Example 1)

In case of, $V_{IN}$ = 7.0V, L = 10μH, fsw = 1.2MHz, $V_{OUT}$ = 32V, $I_{LED}$ = 120mA, Efficiency = 88%

$I_{ave} = (32 \times 120m / 7) / 88\% = 0.62A$

$Ton = (0.62 \times (1 - 7 / 32) \times (1 / 1.2M) \times (10\mu / 7) \times 2)^{1/2} = 1.07\mu s$

$(1- V_{IN} / V_{OUT}) \times (1 / fsw) = 0.65\mu s < Ton(1.07\mu s)$ CCM

$I_{peak} = (7 / 10\mu) \times (1 / 1.2M) \times (1 - (7 / 32)) = 0.46A$

Peak current = 0.46A / 2 + 0.62A = 0.85A

(Example 2)

In case of, $V_{IN}$ = 16.0V, L = 10μH, fsw = 1.2MHz, $V_{OUT}$ = 32V, $I_{LED}$ = 120mA, Efficiency = 88%

$I_{ave} = (32 \times 120m / 16.0) / 88\% = 0.27A$

$Ton = (0.27 \times (1-16 / 32) \times (1 / 1.2M) \times (10\mu / 16) \times 2)^{1/2} = 0.37\mu s$

$(1- V_{IN} / V_{OUT}) \times (1 / fsw)=0.41\mu s > Ton(0.37\mu s)$ DCM

$I_{peak} = V_{IN} / L \times Ton = 16 / 10\mu \times 0.37\mu s = 0.59A$

Peak current = 0.59A

*When too large current is set, output overshoot is caused, be careful enough because it is led to break down of the IC in case of the worst.

DCM/CCM calculation

Discontinuous Condition Mode (DCM) and Continuous Condition Mode (CCM) are calculated as following.

CCM: $L > V_{OUT} \times D \times (1 - D)^2 \times T / (2 \times I_{LED})$

DCM: $L < V_{OUT} \times D \times (1 - D)^2 \times T / (2 \times I_{LED})$

*$D = 1- V_{IN} / V_{OUT}$

(Example 1)

In case of, $V_{IN}$ = 7.0V, L = 10μH, fsw = 1.2MHz, $V_{OUT}$ = 32V, $I_{LED}$ = 120mA

$V_{OUT} \times D \times (1 - D)^2 \times T / (2 \times I_{LED}) = 32 \times (1 – 7 / 32) \times (7 / 32)^2 \times 1/(1.2 \times 10^6) / (2 \times 0.12) = 4.15\mu < L(10\mu H)$

→ CCM

(Example 2)

In case of, $V_{IN}$ = 12.0V, L = 10μH, fsw = 1.2MHz, $V_{OUT}$ = 32V, $I_{LED}$ = 60mA

$V_{OUT} \times D \times (1 - D)^2 \times T / (2 \times I_{LED}) = 32 \times (1 – 12 / 32) \times (12 / 32)^2 \times 1/(1.2 \times 10^6) / (2 \times 0.06) = 19.5\mu > L(10\mu H)$

→ DCM


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●OUTPUT Capacitor selection

Output Capacitor smoothly keeps output voltage and supplies LED current. Output Voltage consists of Charge (FET ON) and Discharge (LED current). So Output voltage has Output ripple Voltage every FET switching.
Output ripple voltage is calculated as following.

Output ripple Voltage

- Switching cycle = T
- Switching ON duty = D
- Output Capacitor = $C_{OUT}$
- Decreasing ratio of Capacitor = $C_{error}$
- Total LED current = $I_{LED}$
- Output ripple Voltage = $V_{ripple}$
- Output Capacitor (real value) = $C_{real}$

$C_{real} = C_{OUT} \times C_{error}$ (Capacitor value is decreased by Bias, so)

$C_{real} = I_{LED} \times (1-D) \times T / V_{ripple}$

$C_{OUT} = I_{LED} \times (1-D) \times T / V_{ripple} / C_{error}$

(Example 1)

In case of, $V_{IN}$=12.0V, fsw = 1.2MHz, $V_{OUT}$ =32V, $I_{LED}$ =120mA, $C_{OUT}$ = 8.8μF, $C_{error}$ = 50%

T = 1 / 1.2MHz

D = 1 – $V_{IN}$ / $V_{OUT}$ = 1 – 12/32

$V_{ripple}$ = $I_{LED} \times (1-D) \times T / (C_{OUT} \times C_{error})$ = 120mA × (12/32) / 1.2MHz / (8.8μF×0.5)
= 8.5mV

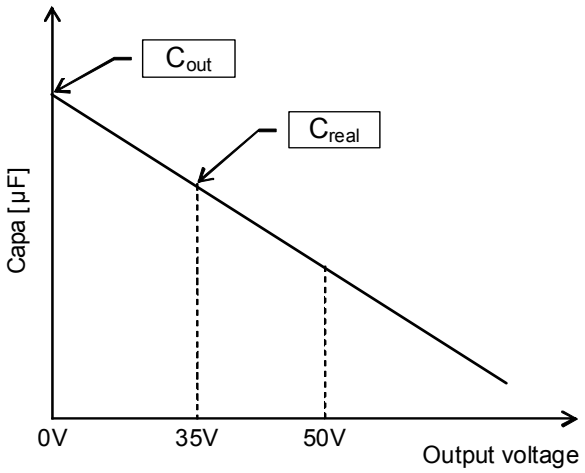



Fig. 30 Bias Characteristics of Capacitor


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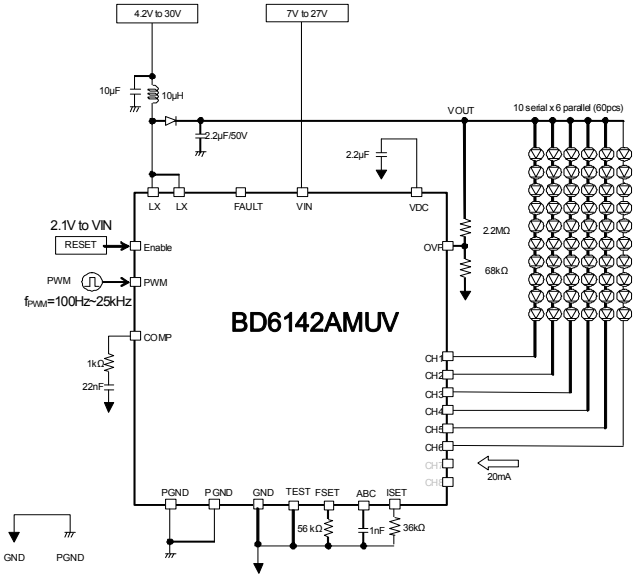
## ●The separations of the IC Power supply and coil Power supply

This IC can work in separating the power source in both IC power supply and coil power supply. With this application, it can obtain that decrease of IC power consumption, and the applied voltage exceeds IC rating 27V.

That application is shown in below Fig.31. The higher voltage source is applied to the power source of coil that is connected from an adapter etc. Next, the IC power supply is connected with a different coil power supply. Under the conditions for inputting from 4.2V to 5.5V into IC VIN, please follow the recommend design in Fig.31. It connects VIN terminal and VDC terminal together at IC outside.

When the coil power supply is applied, it is no any problem even though IC power supply is the state of 0V. Although IC power supply is set to 0V, pull-down resistance is arranged for the power off which cuts off the leak route from coil power supply in IC inside, the leak route is cut off. And, there is no power on-off sequence of coil power supply and IC power supply.

Separate VIN and Coil power supply




Connect VIN and VDC terminals

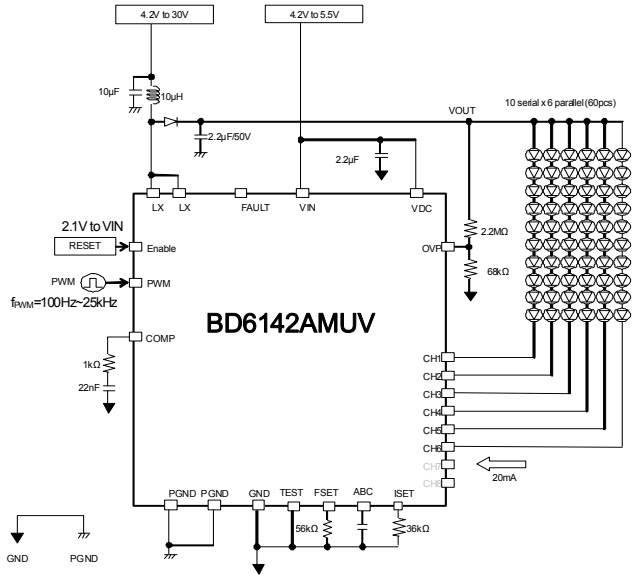



Fig. 31 Application at the time of power supply isolation


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## ●Layout

In order to make the most of the performance of this IC, its PCB layout is very important. Characteristics such as efficiency and ripple and the likes change greatly with layout patterns, which please note carefully.

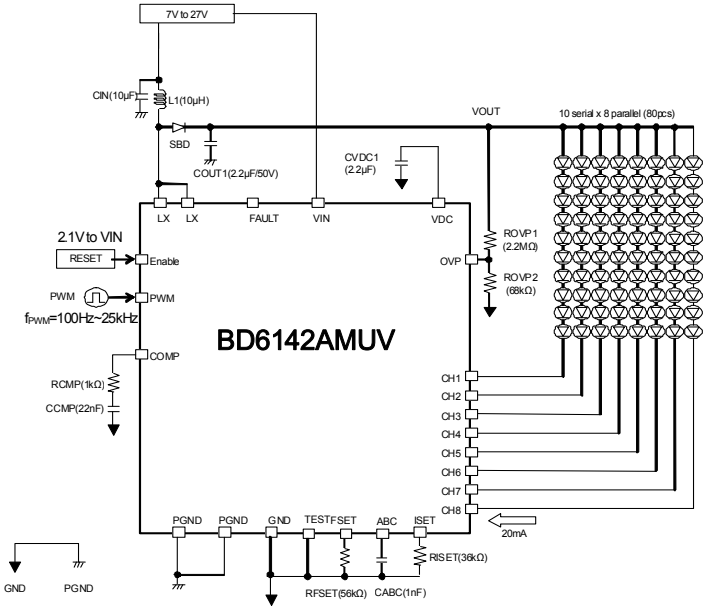



Fig. 32 Schematic

<Input bypath capacitor CIN (10μF)>

Put input bypath capacitor CIN (10μF) as close as possible between coilL1 and PGND pin.

<Smoothing capacitor CVDC1(2.2μF) of the regulator>

Connect smoothing capacitor CVDC1(2.2μF) as close as possible between VDC pin and GND.

<Schottky barrier diode SBD>

Connect schottky barrier diode SBD as close as possible between coil1and SW pin.

<Output capacitor COUT1>

Connect output capacitor COUT1 between cathode of SBD and PGND.
Make both PGND sides of CVIN and COUT1 as close as possible.

<LED current setting resistor RISET(36kΩ)>>

Connect LED current setting resistor RISET(36kΩ) as close as possible between ISET pin and GND.

**There is possibility to oscillate when capacity is added to ISET terminal, so pay attention that capacity isn't added.**

<Analog dimming pin smoothing capacitor CABC (1nF)>

Put analog dimming pin smoothing capacitor CABC (1nF) close to ABC pin and do not extend the wiring to prevent noise increasing and also LED current waving.

<Frequency setting resistor(56KΩ)>

Put frequency setting resistor(56KΩ) as close as possible between FSET pin and GND.

<Over voltage limit setting resistor ROVP1(2.2MΩ) and ROVP2(68KΩ)

Put over voltage limit setting resistor ROVP1(2.2MΩ) and ROVP2(68KΩ) as close as possible to OVP pin and do not extend the wiring to prevent noise increasing and also detecting over voltage protection in error.

<GMAMP setting resistor RCMP(1kΩ) and CCMP(1nF) for phase compensation >

Put GMAMP setting resistor RCMP(1KΩ) and CCMP(22nF) as close as possible to COMP pin and do not extend the wiring to prevent noise increasing and also oscillating.

<Connect to GND and PGND>

GND is analog ground, and PGND is power ground. PGND might cause a lot of noise due to the coil current of PGND. Try to connect with analog ground, after smoothing with input bypath capacitor CVIN and output capacitor COUT1.

<Heat radiation of back side PAD>

PAD is used for improving the efficiency of IC heat radiation. Solder PAD to GND pin (analog ground).
Moreover, connect ground plane of board using via as shown in the patterns of next page.
The efficiency of heat radiation improves according to the area of ground plane.

<Others>

When those pins are not connected directly near the chip, influence is give to the performance of BD6142AMUV, and may limit the current drive performance. As for the wire to the inductor, make its resistance component small so as to reduce electric power consumption and increase the entire efficiency.


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●Recommended PCB layout

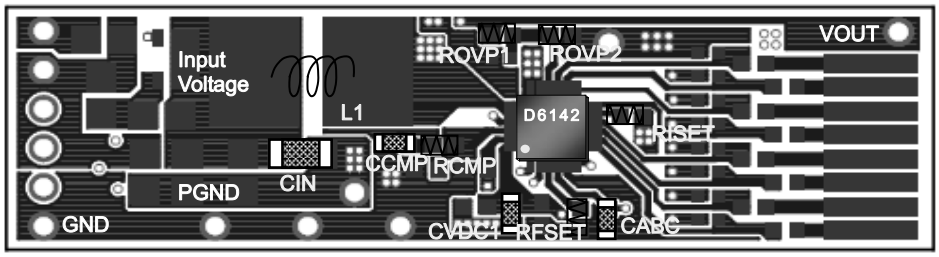



Fig. 33 Top Copper trace layer

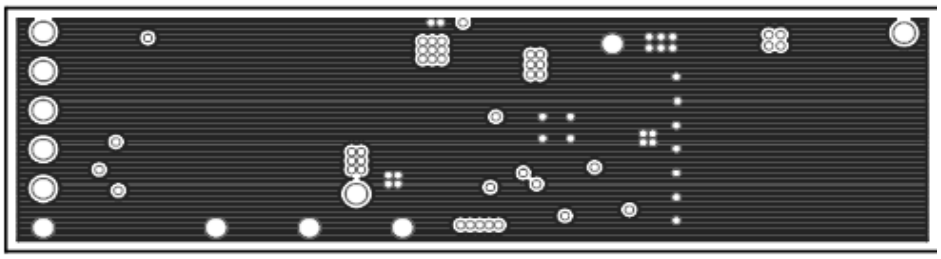


Fig. 34 Middle1 Copper trace layer

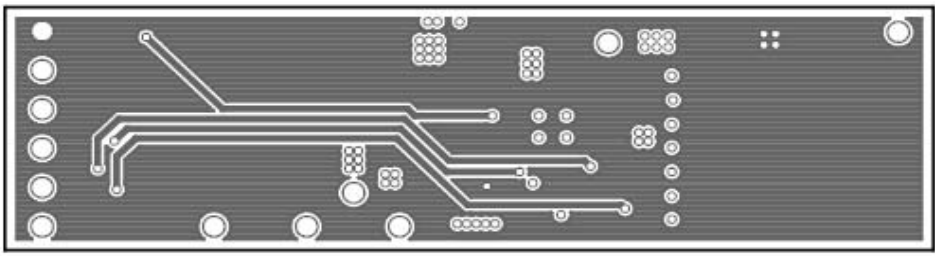


Fig. 35 Middle2 Copper trace layer

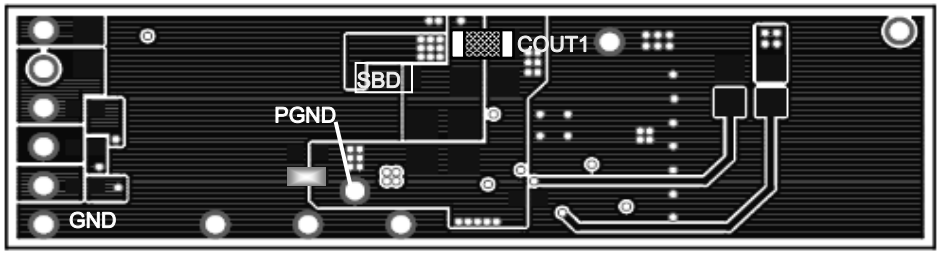



Fig. 36 Bottom Copper trace layer


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## ●Selection of external parts

Recommended external parts are as shown below.
When to use other parts than these, select the following equivalent parts.

・Coil

| Value | Manufacturer | Product number | Size (mm) | | | DC current (mA) | DCR (Ω) |
|---|---|---|---|---|---|---|---|
| | | | L | W | H (MAX) | | |
| 4.7μH | TDK | LTF5022T-4R7N2R0-LC | 5.0 | 5.2 | 2.2 | 2000 | 0.073 |
| 4.7μH | TOKO | A915AY-4R7M | 5.2 | 5.2 | 3.0 | 1870 | 0.045 |
| 10μH | TOKO | A915AY-100M | 5.2 | 5.2 | 3.0 | 1400 | 0.140 |
| 10μH | TDK | LTF5022T-100M1R4-LC | 5.0 | 5.2 | 2.2 | 1400 | 0.140 |
| 10μH | TOKO | B1047AS-100M | 7.6 | 7.6 | 5.0 | 2700 | 0.053 |

・Capacitor

| Value | Pressure | Manufacturer | Product number | Size | | |
|---|---|---|---|---|---|---|
| | | | | L | W | H |
| 10μF | 25V | MURATA | GRM31CB31E106KA75 | 3.2 | 1.6 | 1.6 |
| 4.7μF | 25V | MURATA | GRM319R61E475K | 3.2 | 1.6 | 0.85±0.1 |
| 2.2μF | 50V | TDK | C3225JB1H225K | 3.2 | 2.5 | 2.0±0.2 |
| 2.2μF | 50V | MURATA | GRM31CB31H225K | 3.2 | 1.6 | 1.6 |
| 2.2μF | 50V | Panasonic | ECJHVB1H225K | 3.2 | 1.6 | 0.85 |
| 2.2μF | 10V | MURATA | GRM188B31A225K | 1.6 | 0.8 | 0.8 |
| 0.1μF | 50V | MURATA | GRM188B31H104K | 1.6 | 0.8 | 0.8 |
| 0.1μF | 10V | MURATA | GRM188B31A104K | 1.6 | 0.8 | 0.8 |
| 0.022μF | 10V | MURATA | GRM155B31H223K | 1.0 | 0.5 | 0.5 |
| 470pF | 50V | MURATA | GRM155B11H471K | 1.0 | 0.5 | 0.5 |

・Resistor

| Value | Tolerance | Manufacturer | Product number | Size (mm) | | |
|---|---|---|---|---|---|---|
| | | | | L | W | H |
| 2.2MΩ | ±1.0% | ROHM | MCR03PZPZFX2204 | 1.6 | 0.8 | 0.45 |
| 91kΩ | ±0.5% | ROHM | MCR03PZPZD9102 | 1.6 | 0.8 | 0.45 |
| 75kΩ | ±0.5% | ROHM | MCR03PZPZD7502 | 1.6 | 0.8 | 0.45 |
| 68kΩ | ±0.5% | ROHM | MCR03PZPZD6802 | 1.6 | 0.8 | 0.45 |
| 56kΩ | ±0.5% | ROHM | MCR03PZPZD5602 | 1.6 | 0.8 | 0.45 |
| 36kΩ | ±0.5% | ROHM | MCR03PZPZD3602 | 1.6 | 0.8 | 0.45 |
| 10kΩ | ±1.0% | ROHM | MCR03PZPZF103 | 1.6 | 0.8 | 0.45 |
| 1kΩ | ±0.5% | ROHM | MCR03PZPZD1002 | 1.6 | 0.8 | 0.45 |
| 330Ω | ±0.5% | ROHM | MCR03PZPZD3300 | 1.6 | 0.8 | 0.45 |

・SBD

| Pressure | Manufacturer | Product number | Size (mm) | | |
|---|---|---|---|---|---|
| | | | L | W | H |
| 60V | ROHM | RB160M-60 | 3.5 | 1.6 | 0.8 |

The coil is the part that is most influential to efficiency. Select the coil whose direct current resistor (DCR) and current - inductance characteristic is excellent. BD6142A is designed for the inductance value of 10μH. Don't use the inductance value less than 3.3μH. Select a capacitor of ceramic type with excellent frequency and temperature characteristics.
Further, select Capacitor to be used with small direct current resistance.

## ●About heat loss

In heat design, operate the DC/DC converter in the following condition.
(The following temperature is a guarantee temperature, so consider the margin.)

1. Ambient temperature Ta must be less than 85℃.
2. The loss of IC must be less than dissipation Pd.


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## ●Application example

1. ESD & Flicker (wakeup (duty 5%@200Hz))
   LED current: 20mA (ISET = 36kΩ)
   LED: 10 LEDs in series, 3 strings in parallel

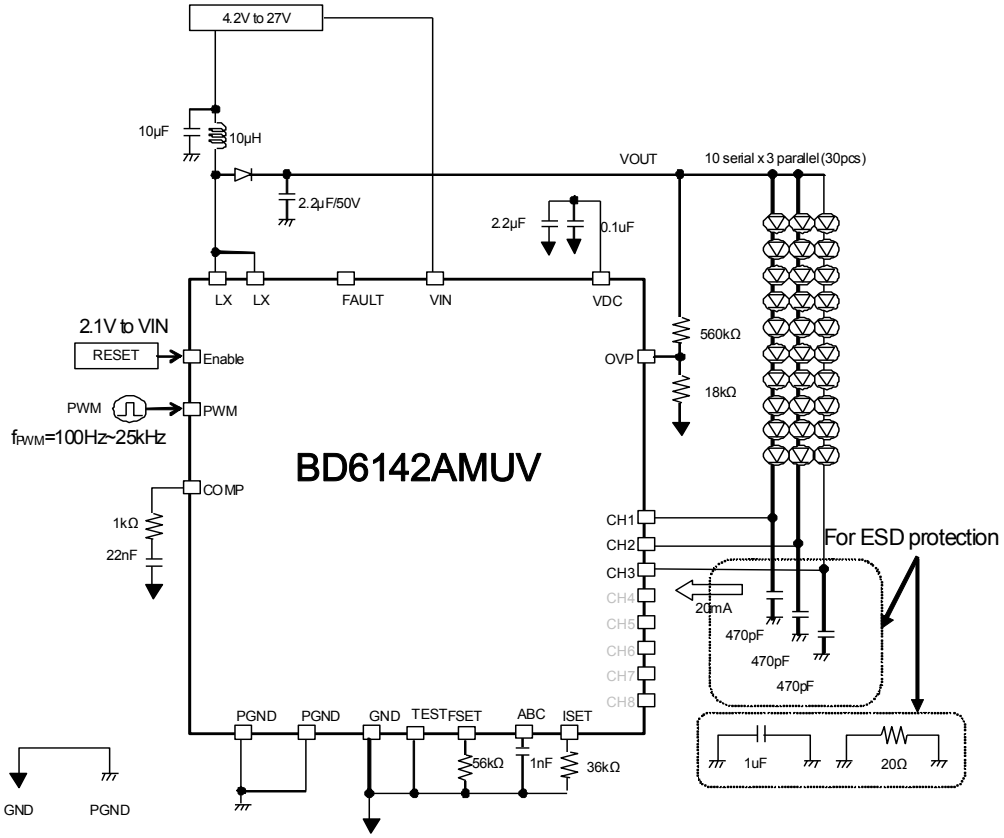



Fig. 37 Application example of 10inch panel

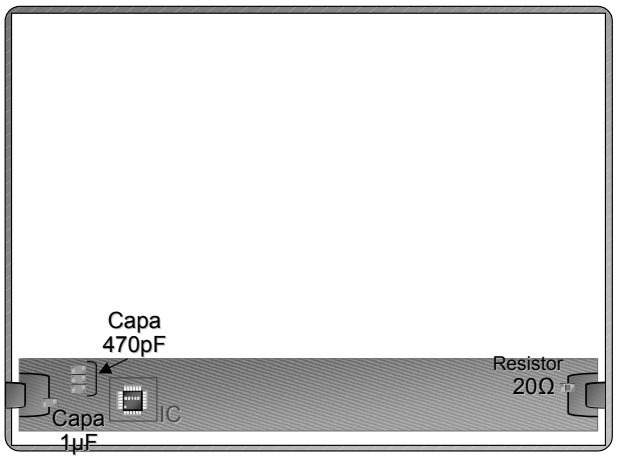



Fig. 38 Layout example for ESD protection


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2. Analog Dimming and monitoring FAULT terminal
LED current: 20mA (ISET = 36kΩ)
LED: 10 LEDs in series, 8 strings in parallel

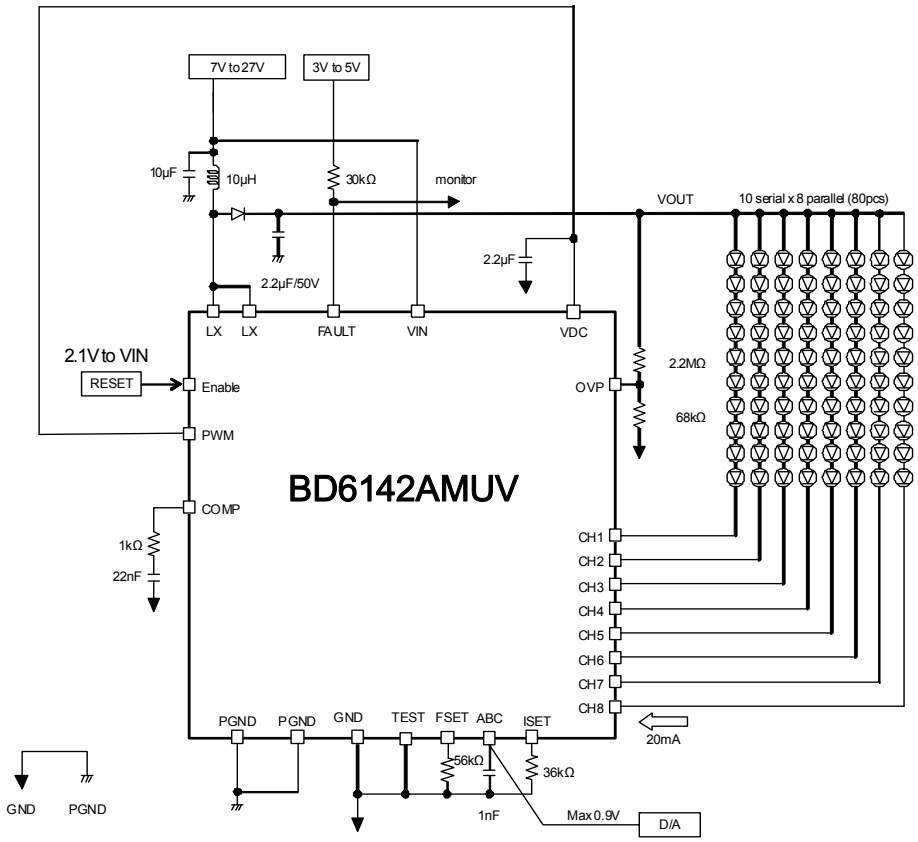



Fig. 39 Application example of Analog dimming


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●Notes for use

(1) Absolute Maximum Ratings
An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

(2) Operating conditions
These conditions represent a range within which characteristics can be provided approximately as expected. The electrical characteristics are guaranteed under the conditions of each parameter.

(3) Reverse connection of power supply connector
The reverse connection of power supply connector can break down ICs. Take protective measures against the breakdown due to the reverse connection, such as mounting an external diode between the power supply and the IC's power supply terminal.

(4) Power supply line
Design PCB pattern to provide low impedance for the wiring between the power supply and the GND lines. In this regard, for the digital block power supply and the analog block power supply, even though these power supplies has the same level of potential, separate the power supply pattern for the digital block from that for the analog block, thus suppressing the diffraction of digital noises to the analog block power supply resulting from impedance common to the wiring patterns. For the GND line, give consideration to design the patterns in a similar manner.
Furthermore, for all power supply terminals to ICs, mount a capacitor between the power supply and the GND terminal. At the same time, in order to use an electrolytic capacitor, thoroughly check to be sure the characteristics of the capacitor to be used present no problem including the occurrence of capacity dropout at a low temperature, thus determining the constant.

(5) GND voltage
Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

(6) Short circuit between terminals and erroneous mounting
In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

(7) Operation in strong electromagnetic field
Be noted that using ICs in the strong electromagnetic field can malfunction them.

(8) Inspection with set PCB
On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

(9) Input terminals
In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals, such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the power supply voltage or within the guaranteed value of electrical characteristics.

(10) Ground wiring pattern
If small-signal GND and large-current GND are provided, It will be recommended to separate the large-current GND pattern from the small-signal GND pattern and establish a single ground at the reference point of the set PCB so that resistance to the wiring pattern and voltage fluctuations due to a large current will cause no fluctuations in voltages of the small-signal GND. Pay attention not to cause fluctuations in the GND wiring pattern of external parts as well.

(11) External capacitor
In order to use a ceramic capacitor as the external capacitor, determine the constant with consideration given to a degradation in the nominal capacitance due to DC bias and changes in the capacitance due to temperature, etc.

(12) Thermal shutdown circuit (TSD)
When junction temperatures become 130℃ (typ) or higher, the thermal shutdown circuit operates and turns a switch OFF. The thermal shutdown circuit, which is aimed at isolating the LSI from thermal runaway as much as possible, is not aimed at the protection or guarantee of the LSI. Therefore, do not continuously use the LSI with this circuit operating or use the LSI assuming its operation.

(13) Thermal design
Perform thermal design in which there are adequate margins by taking into account the permissible dissipation (Pd) in actual states of use.

(14) Selection of coil
Select the low DCR inductors to decrease power loss for DC/DC converter.


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●**Ordering part number**

| B | D | 6 | 1 | 4 | 2 | A | M | U | V | - | E | 2 |
|---|---|---|---|---|---|---|---|---|---|---|---|---|

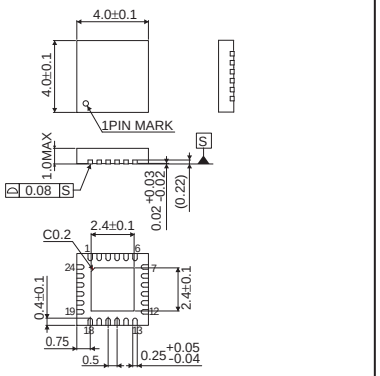
Part No. (BD)

Part No. (6142A)

Package
MUV: VQFN024V4040

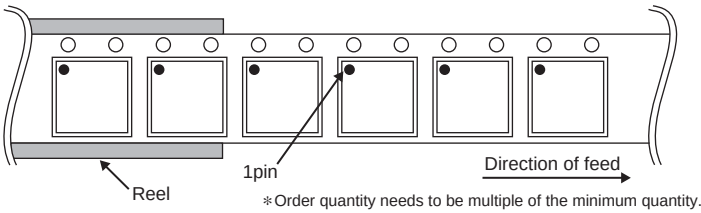
Packaging and forming specification
E2: Embossed tape and reel

**VQFN024V4040**




<Tape and Reel information>

| Tape | Embossed carrier tape |
|---|---|
| Quantity | 2500pcs |
| Direction of feed | E2<br>( The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand ) |




∗Order quantity needs to be multiple of the minimum quantity.


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