

TPS62136, TPS621361 1-MHz High Accuracy 3-V to 17-V 4-A Step-Down Converters with DCS Control™

1 Features

- Output Voltage Accuracy $\pm 1\%$ (PWM mode)
- Input Voltage Range: 3 V to 17 V
- Quiescent Current 18 μA Typ
- Output Voltage from 0.8 V to 12 V
- Adjustable Soft-Start
- Forced PWM or PWM/PFM operation
- Typical switching frequency of 1 MHz in forced PWM
- Precise ENABLE input allows
 - User-Defined Undervoltage Lockout
 - Exact Sequencing
- 100% Duty Cycle Mode
- Automatic Efficiency Enhancement AEE™
- DCS-Control™ Topology
- Available with Active Output Discharge
- Optional HICCUP Overcurrent Protection
- Power Good Output
- Available in 3-mm x 2-mm VQFN Package

2 Applications

- Standard 12-V Rail Supplies
- POL for Connected Standby Requirements
- POL Supply from Single or Multiple Li-Ion Battery
- Gaming Consoles, SSD Drives
- Mobile and Embedded Computers

3 Description

The TPS62136 and TPS621361 are high efficiency and easy to use synchronous step-down DC-DC converters, based on the DCS-Control™ Topology. The devices wide input voltage range of 3-V to 17-V makes it suitable for multi-cell Li-Ion as well as 12-V intermediate supply rails. The devices provide 4-A continuous output current. The TPS62136 automatically enters Power Save Mode at light loads to maintain high efficiency across the whole load range. With that, the device is well suited for applications that require connected standby performance, like ultra low power computers. With the MODE pin set to low, the switching frequency of the device is adapted automatically based on the input and output voltage. This technique is called Automatic Efficiency Enhancement (AEE™) and maintains high conversion efficiency over the whole operation range. It provides a 1% output voltage accuracy in PWM mode and therefore enables the design of a power supply with high output voltage accuracy.

The device has a typical quiescent current of 18 μA . In shutdown mode the current is typically 1 μA and the output is actively discharged for TPS62136 while the output voltage discharge feature is disabled in TPS621361.

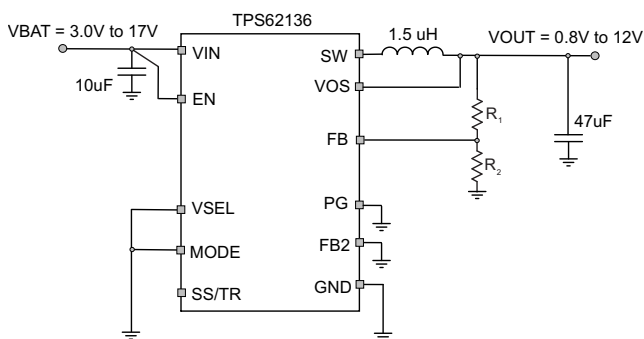
The TPS62136 is available as an adjustable version, packaged in a 3-mm x 2-mm VQFN package.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS62136	VQFN	3.00 mm x 2.00 mm
TPS621361	VQFN	3.00 mm x 2.00 mm

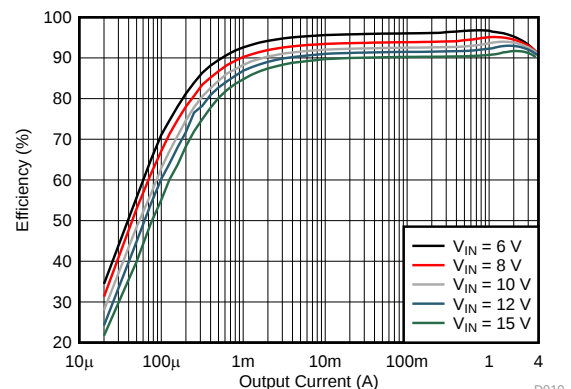
(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic



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Efficiency vs Output Current for Vo = 5 V



D010



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4 Revision History

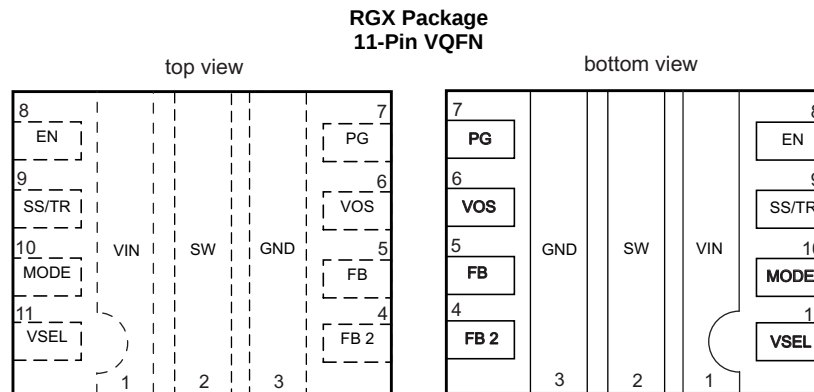
DATE	REVISION	NOTES
March 2017	*	Initial release.

5 Device Comparison Table

DEVICE NUMBER	FEATURES	OUTPUT VOLTAGE	MARKING
TPS62136RGX	nominal switching frequency = 1 MHz output voltage discharge voltage selection input / output VSEL/FB2 HICCUP current limit	adjustable	62136
TPS621361RGX	nominal switching frequency = 1 MHz voltage selection input / output VSEL/FB2	adjustable	621361
TPS62135RGX ⁽¹⁾	nominal switching frequency = 2.5 MHz output voltage discharge voltage selection input / output VSEL/FB2 HICCUP current limit	adjustable	62135
TPS621351RGX ⁽¹⁾	voltage selection input / output VSEL/FB2 nominal switching frequency = 2.5 MHz	adjustable	621351

(1) Please see the TPS62135, TPS621351 data sheet for details

6 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NUMBER		
EN	8	I	This is the enable pin of the device. Connect to logic low to disable the device. Pull high to enable the device. Do not leave this pin unconnected.
FB	5	I	Voltage feedback input, connect resistive output voltage divider to this pin.
FB2	4	O	Open drain of an internal switch to GND. Allows to turn on a resistor in parallel to the feedback resistor R2 and increase the output voltage with VSEL = high.
GND	3		Ground pin.
MODE	10	I	The device runs in PFM/PWM mode when this pin is pulled low. When the pin is pulled high, the device runs in forced PWM mode. Do not leave this pin unconnected.
PG	7	O	Open drain power good output.
SS/TR	9	I	Soft-Start / Tracking pin. An external capacitor connected from this pin to GND defines the rise time for the internal reference voltage. The pin can also be used as an input for tracking and sequencing - see Detailed Description section in this document.
SW	2		This is the switch pin of the converter and is connected to the internal Power MOSFETs.
VIN	1		Power supply input. Make sure the input capacitor is connected as close as possible between pin VIN and GND.
VOS	6	I	Output voltage sense pin. Connect directly to the positive pin of the output capacitor.
VSEL	11	I	Voltage scaling control input. Turns on an internal switch from FB2 to GND when this pin is set high.

7 Specifications

7.1 Absolute Maximum Ratings

		MIN	MAX	UNIT
Pin voltage range ⁽²⁾	V _{IN}	-0.3	20	V
	SW, VOS	-0.3	V _{IN} +0.3	V
	SW (transient for t<10ns) ⁽³⁾	-2	25.5	V
	EN, MODE, VSEL, PG, FB, FB2, SS/TR	-0.3	V _{IN} +0.3	V
Operating junction temperature, T _J		-40	150	°C
Storage temperature range, T _{stg}		-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages are with respect to network ground pin.
- (3) While switching

7.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human Body Model - (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
		Charge Device Model - (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating junction temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{IN}	Supply voltage range	3		17	V
V _{OUT}	Output voltage range	0.8		12	V
L	Effective inductance	0.7	1.5	2.9	μH
C _O	Effective output capacitance ⁽¹⁾	12	47	200 ⁽²⁾	μF
C _I	Effective input capacitance ⁽¹⁾⁽³⁾	3	10		μF
T _J	Operating junction temperature	-40		+125	°C

- (1) Due to the dc bias effect of ceramic capacitors, the effective capacitance is lower than the nominal value when a voltage is applied. This is why the capacitance is specified to allow the selection of the smallest capacitor required with the dc bias effect for this type of capacitor in mind. The nominal value given matches a typical capacitor to be chosen to meet the minimum capacitance required.
- (2) This is for capacitors directly at the output of the TPS62136x. More capacitance is allowed if there is a series resistance associated to the capacitors. See also the systems examples [Powering Multiple Loads](#) for applications where many distributed capacitors are connected to the output.
- (3) Larger values may be required if the source impedance can not support the transient requirements of the load.

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS62136, TPS621361	UNIT
		RGX (VQFN)	
		11 PIN	
R _{θJA}	Junction-to-ambient thermal resistance	38.4	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	2.0	°C/W
R _{θJB}	Junction-to-board thermal resistance	7.6	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	0.1	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	7.6	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	3.2	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report. Thermal data is taken according JEDEC 51-5 on a 4-layer pcb with 6 thermal vias.

7.5 Electrical Characteristics

over operating junction temperature (T_J = -40 °C to +125 °C) and V_{IN} = 3 V to 17 V. Typical values at V_{IN} = 12 V and T_A = 25 °C. (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY						
I _Q	Operating Quiescent Current	EN = high, I _{OUT} = 0 mA, Device not switching, T _j = 85 °C			35	μA
I _Q	Operating Quiescent Current	EN = high, I _{OUT} = 0 mA, Device not switching		18	46	μA
I _{SD}	Shutdown Current	EN = 0 V, Nominal value at T _j = 25 °C, Max value at T _j = 85 °C		1	8	μA
V _{UVLO}	Undervoltage Lockout Threshold	Rising Input Voltage	2.8	2.9	3.0	V
		Falling Input Voltage	2.5	2.6	2.7	V
T _{SD}	Thermal Shutdown Temperature	Rising Junction Temperature		160		°C
	Thermal Shutdown Hysteresis			20		
CONTROL (EN, SS/TR, PG, MODE, VSEL)						
V _{IH}	High Level Input Voltage for VSEL, MODE pin		0.9			V
V _{IL}	Low Level Input Voltage for VSEL, MODE pin				0.3	V
V _{IH}	Input Threshold Voltage for EN pin; rising edge		0.77	0.8	0.83	V
V _{IL}	Input Threshold Voltage for EN pin; falling edge		0.67	0.7	0.73	V
I _{LKG_EN}	Input Leakage Current for EN, VSEL, MODE	V _{IH} = V _{IN} or V _{IL} = GND			100	nA
V _{TH_PG}	Power Good Threshold Voltage; dc level	Rising (%V _{OUT})	93%	96%	98%	
	Hysteresis	Falling (%V _{OUT})	3%		4.5%	
V _{OL_PG}	Power Good Output Low Voltage	I _{PG} = 2 mA		0.07	0.3	V
I _{LKG_PG}	Input Leakage Current (PG)	V _{PG} = 5 V			100	nA
I _{SS/TR}	SS/TR pin source current			2.5		μA
	I _{SS/TR} tolerance	T _j = -40 °C to +125 °C		±0.2		μA
	Tracking gain	V _{FB} / V _{SS/TR}		1		
	Tracking offset	feedback voltage with V _{SS/TR} = 0 V		11		mV

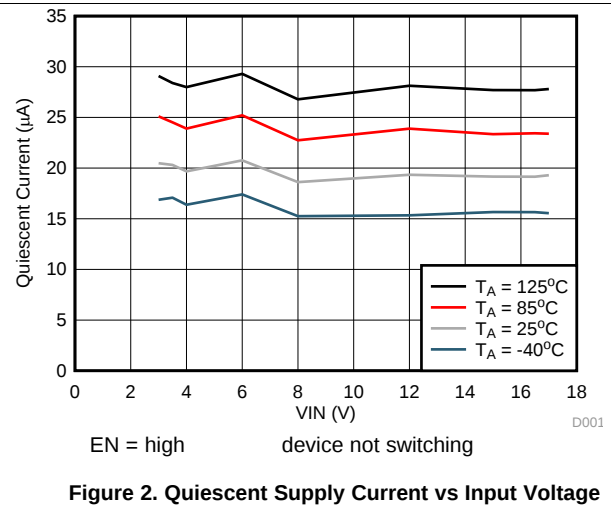
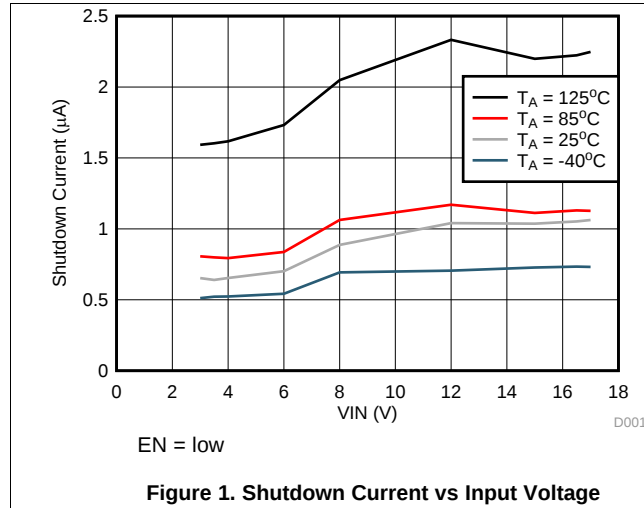
Electrical Characteristics (continued)

over operating junction temperature ($T_J = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$) and $V_{IN} = 3\text{ V}$ to 17 V . Typical values at $V_{IN} = 12\text{ V}$ and $T_A = 25\text{ }^{\circ}\text{C}$. (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
POWER SWITCH							
R _{DS(ON)}	High-Side MOSFET ON-Resistance	V _{IN} ≥ 4 V			100	180	mΩ
	Low-Side MOSFET ON-Resistance	V _{IN} ≥ 4 V			39	67	mΩ
I _{LIMH}	High-Side MOSFET Current Limit	dc value ⁽¹⁾		4.8	5.6	6.5	A
I _{LIML}	Low-Side MOSFET Current Limit	dc value ⁽¹⁾		4.8	5.6	6.5	A
I _{LIMNEG}	Negative current limit	dc value			1.5		A
f _{SW}	PWM Switching Frequency	MODE = high; V _{IN} = 12V, V _{OUT} = 3.3V; I _{OUT} = 1A			1		MHz
OUTPUT							
V _{FB}	Feedback Voltage				0.7		V
I _{LKG_FB}	Input Leakage Current (FB)	V _{FB} = 0.7 V			1	70	nA
V _{FB}	Feedback Voltage Accuracy ⁽²⁾	V _{IN} ≥ V _{OUT} +1 V	PWM mode	-1%		1%	
		V _{IN} ≥ V _{OUT} +1 V; V _{OUT} ≥ 1.5 V	PFM mode; Co,eff ≥ 47 μF, L = 1.5 μH	-1%		2%	
		1 V ≤ V _{OUT} < 1.5 V	PFM mode; Co,eff ≥ 60 μF, L = 1.5 μH	-1%		2.5%	
		V _{OUT} < 1 V	PFM mode; Co,eff ≥ 75 μF, L = 1.5 μH	-1%		2.5%	
V _{FB}	Feedback Voltage Accuracy with Voltage Tracking	V _{IN} ≥ V _{OUT} +1 V; V _{SS/TR} = 0.35 V	PWM mode	-2%		7.5%	
R _{DS(ON)}	FB2 resistance to GND when VSEL= high				10	30	Ω
I _{LKG_FB2}	Input Leakage Current in FB2 when VSEL = low				1	70	nA
	Load Regulation	PWM mode operation			0.05		%/A
	Line Regulation	PWM mode operation, I _{OUT} = 1 A, V _{IN} ≥ V _{out} + 1 V or V _{IN} ≥ 3.5 V whichever is larger			0.02		%/V
	Output Discharge Resistance	TPS62136 only			100		Ω
t _{delay}	Start-up Delay time	I _O = 0 mA, Time from EN=high to start switching; V _{IN} applied already			200	300	μs
t _{ramp}	Ramp time; SS/TR pin open	I _O = 0 mA, Time from first switching pulse until 95% of nominal output voltage; device not in current limit			150		μs

- (1) See also [HICCUP Current Limit And Short Circuit Protection \(TPS62136 only\)](#) and [Current Limit And Short Circuit Protection \(TPS621361 only\)](#).
- (2) The output voltage accuracy in Power Save Mode can be improved by increasing the output capacitor value, reducing the output voltage ripple (see [Pulse Width Modulation \(PWM\) Operation](#)).

7.6 Typical Characteristics



8 Parameter Measurement Information

8.1 Schematic

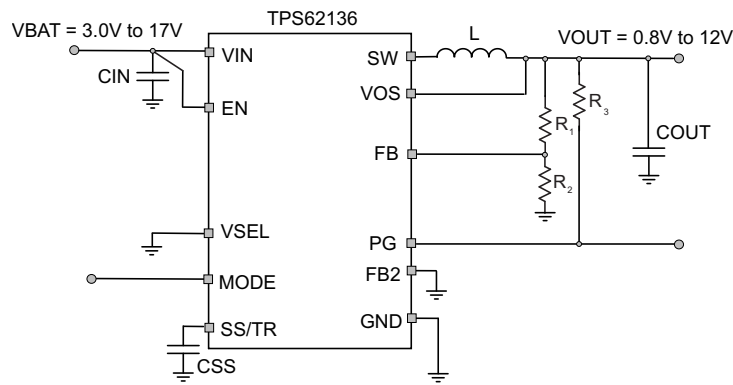


Figure 3. Measurement Setup

Table 1. List of Components

REFERENCE	DESCRIPTION	MANUFACTURER
IC	17 V, 4 A Step-Down Converter	TPS62136; Texas Instruments
L	1.5 µH inductor	XEL4020-152; Coilcraft
CIN	10 µF, 25 V, Ceramic, 0805	TMK212BBJ106MG-T; Taiyo Yuden
COUT	2 x 22 µF, 16 V, Ceramic, 0805; all VOUT except 9 V and 1.2 V	EMK212BBJ106MG-T; Taiyo Yuden
COUT	3 x 22 µF, 16 V, Ceramic, 0805 for VOUT = 1.2 V and VOUT = 9V	EMK212BBJ106MG-T; Taiyo Yuden
CSS	3.3 nF, 10 V, Ceramic, X7R	-
R1	Depending on Vout; see Table 5	Standard 1% metal film
R2	Depending on Vout; see Table 5	Standard 1% metal film
R3	470 kΩ, Chip, 0603, 1/16 W, 1%	Standard 1% metal film

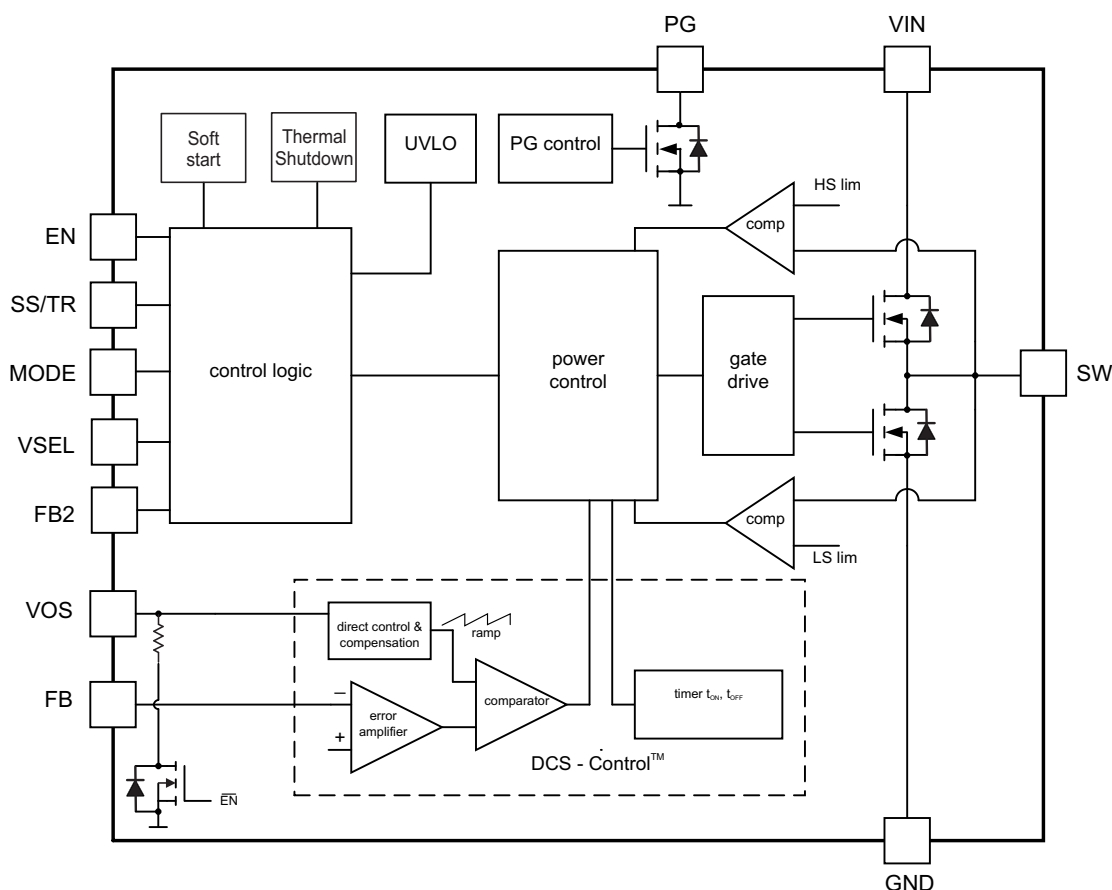
9 Detailed Description

9.1 Overview

The TPS62136 synchronous switched mode power converters are based on DCS-Control™ (Direct Control with Seamless Transition into Power Save Mode), an advanced regulation topology, that combines the advantages of hysteretic, voltage mode and current mode control. This control loop takes information about output voltage changes and feeds it directly to a fast comparator stage. It sets the switching frequency, which is constant for steady state operating conditions, and provides immediate response to dynamic load changes. To get accurate DC load regulation, a voltage feedback loop is used. The internally compensated regulation network achieves fast and stable operation with small external components and low ESR capacitors.

The DCS-Control™ topology supports PWM (Pulse Width Modulation) mode for medium and heavy load conditions and a Power Save Mode at light loads. During PWM, it operates at its nominal switching frequency in continuous conduction mode. This frequency is typically about 1 MHz with a controlled frequency variation depending on the input voltage. If the load current decreases, the converter enters Power Save Mode to sustain high efficiency down to very light loads. In Power Save Mode the switching frequency decreases linearly with the load current. Since DCS-Control™ supports both operation modes within one single building block, the transition from PWM to Power Save Mode is seamless without effects on the output voltage. An internal current limit supports nominal output currents of up to 4 A. The TPS62136x family offers both excellent DC voltage and superior load transient regulation, combined with very low output voltage ripple, minimizing interference with RF circuits.

9.2 Functional Block Diagram



The discharge switch on the VOS pin is only available in the TPS62136.

9.3 Feature Description

9.3.1 Precise Enable

The voltage applied at the Enable pin of the TPS62136x is compared to a fixed threshold of 0.8 V for a rising voltage. This allows to drive the pin by a slowly changing voltage and enables the use of an external RC network to achieve a power-up delay.

The Precise Enable input allows the use as a user programmable undervoltage lockout by adding a resistor divider to the input of the Enable pin.

The enable input threshold for a falling edge is typically 100 mV lower than the rising edge threshold. The TPS62136x starts operation when the rising threshold is exceeded. For proper operation, the EN pin must be terminated and must not be left floating. Pulling the EN pin low forces the device into shutdown, with a shutdown current of typically 1 μ A. In this mode, the internal high side and low side MOSFETs are turned off and the entire internal control circuitry is switched off.

9.3.2 Power Good (PG)

The TPS62136x has a built in power good (PG) function to indicate whether the output voltage has reached its target. The PG signal can be used for startup sequencing of multiple rails. The PG pin is an open-drain output that requires a pull-up resistor to any voltage up to a voltage level of the input voltage at VIN. It can sink 2 mA of current and maintain its specified logic low level. PG is low when the device is turned off due to EN, UVLO or thermal shutdown, so it can be used to actively discharge Vout. VIN must remain present for the PG pin to stay low.

In case VSEL is used to change the output voltage during operation, PG is not blanked for a change from low output voltage to high output voltage. It therefore will indicate "power bad" if the voltage step is large enough to trigger the power good comparator.

If the power good output is not used, it is recommended to tie to GND or leave open.

9.3.3 Pin-Selectable Output Voltage (VSEL and FB2)

The output voltage of the TPS62136x is set by the resistor divider from VOUT to FB to GND. The topology requires a voltage divider on FB, so the minimum output voltage is 0.8 V while the feedback voltage on the FB pin is 0.7 V.

VSEL and FB2 can optionally be used to enable a second resistor from FB2 to GND which increases the divider ratio, hence increasing the output voltage. See [Typical Application using VSEL and FB2](#).

9.3.4 MODE

When MODE is set low, the device operates in PWM or PFM mode depending on the output current. Automatic Efficiency Enhancement (AEE) is enabled for highest efficiency over a wide input voltage, output voltage and output current range. The MODE pin allows to force PWM mode when set high. In forced PWM mode, AEE is disabled. See also [Power Save Mode Operation \(PWM/PFM\)](#).

9.3.5 Undervoltage Lockout (UVLO)

If the input voltage drops, the undervoltage lockout prevents mis-operation of the device by switching off both the power FETs. The device is fully operational for voltages above the rising UVLO threshold and turns off if the input voltage trips below the threshold for a falling supply voltage.

9.3.6 Thermal Shutdown

The junction temperature (T_J) of the device is monitored by an internal temperature sensor. If T_J exceeds 160°C (typ), the device goes into thermal shutdown. Both the high-side and low-side power FETs are turned off and PG goes low. When T_J decreases below the hysteresis amount of typically 20°C, the converter resumes normal operation, beginning with Soft-Start. During a PFM skip pause, the thermal shutdown is not active. See also [Power Save Mode Operation \(PWM/PFM\)](#).

9.4 Device Functional Modes

9.4.1 Pulse Width Modulation (PWM) Operation

TPS62136x has two operating modes: Forced PWM mode discussed in this section and PWM/PFM as discussed in [Power Save Mode Operation \(PWM/PFM\)](#).

With the MODE pin set to high, the TPS62136x operates with pulse width modulation in continuous conduction mode (CCM). The AEE function in TPS62136 and TPS621361 adjust the on-time (TON) in forced PWM mode as well as in power save mode (PWM/PFM mode) depending on the input voltage and the output voltage to maintain highest efficiency. The on-time, in steady-state operation, can be estimated as:

$$TON = 250 \times \frac{VIN}{VIN - VOUT} [ns] \quad (1)$$

9.4.2 Power Save Mode Operation (PWM/PFM)

When the MODE pin is low, Power Save Mode is allowed. The device operates in PWM mode as long the output current is higher than half the inductor's ripple current. To maintain high efficiency at light loads, the device enters Power Save Mode at the boundary to discontinuous conduction mode (DCM). This happens if the output current becomes smaller than half the inductor's ripple current. For improved transient response, PWM mode is forced for 8 switching cycles if the output voltage is above target due to a load release. The Power Save Mode is entered seamlessly, if the load current decreases and the MODE pin is set low. This ensures a high efficiency in light load operation. The device remains in Power Save Mode as long as the inductor current is discontinuous.

In Power Save Mode the switching frequency decreases linearly with the load current maintaining high efficiency. The transition into and out of Power Save Mode is seamless in both directions.

The on-time (TON) in PFM mode is identical to the on-time in forced PWM mode:

$$TON = 250 \times \frac{VIN}{VIN - VOUT} [ns] \quad (2)$$

For very small output voltages, an absolute minimum on-time of about 50 ns is kept to limit switching losses. The operating frequency is thereby reduced from its nominal value, which keeps efficiency high. Using TON, the typical peak inductor current in Power Save Mode is approximated by:

$$ILPSM_{(peak)} = \frac{(VIN - VOUT)}{L} \times TON \quad (3)$$

There is a minimum off-time which limits the duty cycle of the TPS62136x. When VIN decreases to typically 15% above VOUT, the TPS62136x does not enter Power Save Mode, regardless of the load current. The device maintains output regulation in PWM mode.

The output voltage ripple in power save mode is given by [Equation 4](#):

$$\Delta V = \frac{L \times VIN^2}{200 \times C} \left(\frac{1}{VIN - VOUT} + \frac{1}{VOUT} \right) \quad (4)$$

9.4.3 100% Duty-Cycle Operation

The duty cycle of the buck converter operated in PWM mode is given as $D = VOUT/VIN$. The duty cycle increases as the input voltage comes close to the output voltage and the off-time gets smaller. When the minimum off-time of typically 80ns is reached, TPS62136x scales down its switching frequency while it approaches 100% mode. In 100% mode it keeps the high-side switch on continuously. The high-side switch stays turned on as long as the output voltage is below the internal set point. This allows the conversion of small input to output voltage differences, for example for longest operation time of battery-powered applications. In 100% duty cycle mode, the low-side FET is switched off.

The minimum input voltage to maintain output voltage regulation, depending on the load current and the output voltage level, can be calculated as:

$$VIN_{(min)} = VOUT + IOUT(R_{DS(on)} + RL) \quad (5)$$

Device Functional Modes (continued)

where:

- IO_{UT} is the output current,
- R_{DS(on)} is the on-state resistance of the high-side FET and
- R_L is the DC resistance of the inductor used.

9.4.4 HICCUP Current Limit And Short Circuit Protection (TPS62136 only)

The TPS62136 is protected against overload and short circuit events. If the inductor current exceeds the current limit I_{LIMH}, the high side switch is turned off and the low side switch is turned on to ramp down the inductor current. The high side FET turns on again only if the current in the low side FET has decreased below the low side current limit threshold. Once the high side switch current limit is triggered for 512 subsequent switching cycles, the device stops switching. After a typical delay of 800 μs, the device begins a new Soft-Start cycle. This is called HICCUP short circuit protection. TPS62136 repeats this mode until the short circuit condition disappears.

Due to internal propagation delay, the actual current can exceed the static current limit during that time. The dynamic current limit is given as:

$$I_{peak(typ)} = I_{LIMH} + \frac{V_L}{L} \times t_{PD} \quad (6)$$

where:

- I_{LIMH} is the static current limit as specified in the electrical characteristics
- L is the effective inductance at the peak current
- V_L is the voltage across the inductor (V_{IN} - V_{OUT}) and
- t_{PD} is the internal propagation delay of typically 50 ns.

The current limit can exceed static values, especially if the input voltage is high and very small inductances are used. The dynamic high side switch peak current can be calculated as follows:

$$I_{peak(typ)} = I_{LIMH} + \frac{V_{IN} - V_{OUT}}{L} \times 50 \text{ ns} \quad (7)$$

9.4.5 Current Limit And Short Circuit Protection (TPS621361 only)

The TPS621361 is protected by a current limit the same as the TPS62136 but does not turn off after a certain time. This allows it to provide the maximum current, for example, charging a large output capacitance without the need to increase the Soft-Start time. [Equation 6](#) and [Equation 7](#) also apply.

9.4.6 Soft-Start / Tracking (SS/TR)

The internal Soft-Start circuitry controls the output voltage slope during startup. This avoids excessive inrush current and ensures a controlled output voltage rise time. It also prevents unwanted voltage drops from high impedance power sources or batteries. When EN is set high to start operation, the device starts switching after a delay of about 200 μs then the internal reference and hence V_{OUT} rises with a slope controlled by an external capacitor connected to the SS/TR pin.

Leaving SS/TR pin un-connected provides fastest startup behavior with 150 μs typically.

If the device is set to shutdown (EN = GND), undervoltage lockout or thermal shutdown, an internal resistor pulls the SS/TR pin down to ensure a proper low level. Returning from those states causes a new startup sequence as set by the SS/TR connection.

A voltage supplied to SS/TR can be used to track a master voltage. The output voltage follows this voltage in both directions up and down in forced PWM mode. In PFM mode, the output voltage decreases based on the load current. The SS/TR pin of several devices must not be connected with each other.

Device Functional Modes (continued)

9.4.7 Output Discharge Function (TPS62136 only)

The purpose of the discharge function is to ensure a defined down-ramp of the output voltage when the device is being disabled but also to keep the output voltage close to 0 V when the device is off. The output discharge feature is only active once TPS62136 has been enabled at least once since the supply voltage was applied. The internal discharge resistor is connected to the VOS pin. The discharge function is enabled as soon as the device is disabled, in thermal shutdown or in undervoltage lockout. The minimum supply voltage required for the discharge function to remain active typically is 2 V. Output discharge is not activated during a HICCUP current limit event.

9.4.8 Starting into a Pre-Biased Load (TPS621361 only)

The TPS621361 is capable of starting into a pre-biased output. The device only starts switching when the internal Soft-Start ramp is equal or higher than the feedback voltage. If the voltage at the feedback pin is biased to a higher voltage than the nominal value, the TPS621361 does not start switching unless the voltage at the feedback pin drops to the target.

This functionality actually also applies to TPS62136 but the discharge function in TPS62136 keeps the voltage close to 0 V, so starting into a pre-biased output does not apply.

10 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

10.1 Application Information

10.1.1 Programming the Output Voltage

The output voltage of the TPS62136x is adjustable. It can be programmed for output voltages from 0.8 V to 12 V, using a resistor divider from VOUT to GND. The voltage at the FB pin is regulated to 700 mV. The value of the output voltage is set by the selection of the resistor divider from [Equation 8](#). It is recommended to choose resistor values which allow a current of at least 2 uA, meaning the value of R2 should not exceed 400 kΩ. Lower resistor values are recommended for highest accuracy and most robust design.

$$R_1 = R_2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1 \right) \quad (8)$$

10.1.2 External Component Selection

The external components have to fulfill the needs of the application, but also the stability criteria of the device's control loop. The TPS62136x is optimized to work within a range of external components. The LC output filters inductance and capacitance have to be considered together, creating a double pole, responsible for the corner frequency of the converter (see [Output Filter and Loop Stability](#)). [Table 2](#) can be used to simplify the output filter component selection.

Table 2. Recommended LC Output Filter Combinations⁽¹⁾

	10 μF	22 μF	47 μF	68 μF	100 μF	200 μF	≥400 μF
1.0 μH							
1.5 μH			√ ⁽²⁾	√	√	√	√ ⁽³⁾
2.2 μH			√	√	√	√	√ ⁽³⁾
3.3 μH							

(1) The values in the table are nominal values.

(2) This LC combination is the standard value and recommended for most applications. For lowest output voltage and inductor current ripple, a nominal 2.2μH inductor is recommended.

(3) Output capacitance needs to have a ESR of ≥ 10 mΩ for stable operation, see also [Powering Multiple Loads](#).

10.1.3 Inductor Selection

The TPS62136x is designed for a nominal 1.5-μH or 2.2-μH inductor. Please see the recommended operating conditions for the range of inductance. Smaller values than 1.5μH will cause a larger inductor current ripple which causes larger negative inductor current in forced PWM mode at low or no output current. Therefore they are not recommended at large voltages across the inductor as it is the case for high input voltages and low output voltages. With low output current in forced PWM mode this causes a larger negative inductor current peak which may exceed the negative current limit. At low or no output current and small inductor values the output voltage can therefore not be regulated any more.

The inductor selection is affected by several effects like inductor ripple current, output ripple voltage, PWM-to-PFM transition point and efficiency. In addition, the inductor selected has to be rated for appropriate saturation current and DC resistance (DCR). [Equation 9](#) calculates the maximum inductor current.

$$I_{L(max)} = I_{OUT(max)} + \frac{\Delta I_{L(max)}}{2} \quad (9)$$

$$\Delta I_{L(max)} = \frac{V_{IN(max)}}{L_{(min)}} \times 100ns \quad (10)$$

where:

$I_L(\text{max})$ is the maximum inductor current

ΔI_L is the Peak to Peak Inductor Ripple Current

$L(\text{min})$ is the minimum effective inductor value.

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current of the inductor needed. A margin of about 20% is recommended to add. A larger inductor value is also useful to get lower ripple current, but increases the transient response time and size as well. The following inductors have been used with the TPS62136x and are recommended for use:

Table 3. List of Inductors

TYPE	INDUCTANCE [μH]	CURRENT [A] ⁽¹⁾	DIMENSIONS [LxBxH] mm	MANUFACTURER
XEL4020-152ME	1.5 μH , $\pm 20\%$	5.2 (for 20°C temperature rise)	4 x 4 x 2.1	Coilcraft
XFL4020-152ME	1.5 μH , $\pm 20\%$	4.6	4 x 4 x 2.1	Coilcraft
XEL4030-152ME	1.5 μH , $\pm 20\%$	8.1	4 x 4 x 3.1	Coilcraft
XEL4030-222ME	2.2 μH , $\pm 20\%$	6.1	4 x 4 x 3.1	Coilcraft
DFE322512F-1R5M	1.5 μH , $\pm 20\%$	3.0 ⁽²⁾	3.2 x 2.5 x 1.2	Murata

(1) Lower of I_{RMS} at 40°C rise or I_{SAT} at 30% drop.

(2) For smallest size solutions that in average do not require the full output current TPS62136x can provide.

The inductor value also determines the load current at which Power Save Mode is entered:

$$I_{\text{load(PSM)}} = \frac{1}{2} \Delta I_L \quad (11)$$

10.1.4 Capacitor Selection

10.1.4.1 Output Capacitor

The recommended value for the output capacitor is 47 μF . The architecture of the TPS62136x allows the use of tiny ceramic output capacitors with low equivalent series resistance (ESR). These capacitors provide low output voltage ripple and are recommended. To keep its low resistance up to high frequencies and to get narrow capacitance variation with temperature, it is recommended to use X7R or X5R dielectric. Using a higher value has advantages like smaller voltage ripple and a tighter DC output accuracy in Power Save Mode (see [SLVA463](#)).

In Power Save Mode, the output voltage ripple depends on the output capacitance, its ESR, ESL and the peak inductor current. Using ceramic capacitors provides small ESR, ESL and low ripple. The output capacitor needs to be as close as possible to the device.

For large output voltages the dc bias effect of ceramic capacitors is large and the effective capacitance has to be observed.

10.1.4.2 Input Capacitor

For most applications, 10 μF nominal is sufficient and is recommended, though a larger value reduces input current ripple further. The input capacitor buffers the input voltage for transient events and also decouples the converter from the supply. A low ESR multilayer ceramic capacitor (MLCC) is recommended for best filtering and should be placed between VIN and GND as close as possible to those pins.

Table 4. List of Capacitors⁽¹⁾

TYPE	NOMINAL CAPACITANCE [μF]	VOLTAGE RATING [V]	SIZE	MANUFACTURER
TMK212BBJ106MG-T	10	25	0805	Taiyo Yuden
EMK212BBJ226MG-T	22	16	0805	Taiyo Yuden

(1) Lower of I_{RMS} at 40°C rise or I_{SAT} at 30% drop.

10.1.4.3 Soft-Start Capacitor

A capacitor connected between SS/TR pin and GND allows a user programmable start-up slope of the output voltage. A constant current source provides typically 2.5 μA to charge the external capacitance. The capacitor required for a given Soft-Start ramp time is given by:

$$C_{SS} = t_{SS} \times \frac{2.5\mu\text{A}}{0.7\text{V}} \text{ [F]} \quad (12)$$

where:

C_{SS} is the capacitance required at the SS/TR pin and

t_{SS} is the desired Soft-Start ramp time

The fastest achievable typical ramp time is 150 μs even if the external C_{SS} capacitance is lower than 680 pF or the pin is open.

10.1.5 Tracking Function

If a tracking function is desired, the SS/TR pin can be used for this purpose by connecting it to an external tracking voltage. The output voltage tracks that voltage with the typical gain and offset as specified in the electrical characteristics.

When the SS/TR pin voltage is above 0.7 V, the internal voltage is clamped and the device goes to normal regulation. This works for rising and falling tracking voltages with the same behavior, as long as the input voltage is inside the recommended operating conditions. For decreasing SS/TR pin voltage in PFM mode, the device does not sink current from the output. The resulting decrease of the output voltage may therefore be slower than the SS/TR pin voltage if the load is light. When driving the SS/TR pin with an external voltage, do not exceed the voltage rating of the SS/TR pin which is $V_{IN} + 0.3\text{ V}$. The SS/TR pin is internally connected with a resistor to GND when EN = 0.

If the input voltage drops below undervoltage lockout, the output voltage will go to zero, independent of the tracking voltage. [Figure 4](#) shows how to connect devices to get ratiometric and simultaneous sequencing by using the tracking function. See also [Voltage Tracking](#) in the systems examples. SS/TR is internally clamped to approximately 3 V.

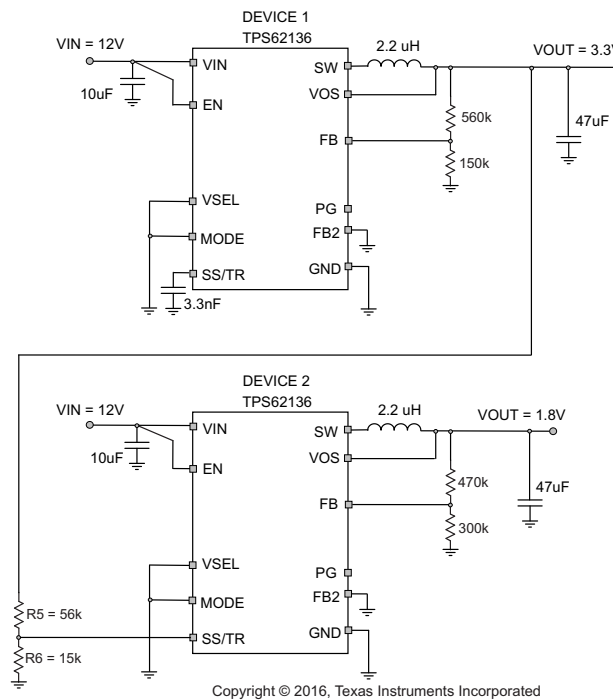


Figure 4. Schematic for Ratiometric and Simultaneous Startup

The resistive divider of R5 and R6 can be used to change the ramp rate of VOUT2 to be faster, slower or the same as VOUT1.

A sequential startup is achieved by connecting the PG pin of VOUT of DEVICE 1 to the EN pin of DEVICE2. PG requires a pull-up resistor. Ratiometric start up sequence happens if both supplies are sharing the same Soft-Start capacitor. Equation 12 gives the Soft-Start time, though the SS/TR current has to be doubled. Details about these and other tracking and sequencing circuits are found in SLVA470.

Note: If the voltage at the FB pin is below its typical value of 0.7 V, the output voltage accuracy may have a wider tolerance than specified. The current of 2.5 μ A out of the SS/TR pin also has an influence on the tracking function, especially for high resistive external voltage dividers on the SS/TR pin.

10.1.6 Output Filter and Loop Stability

The devices of the TPS6213X family are internally compensated to be stable with L-C filter combinations corresponding to a corner frequency to be calculated with Equation 13:

$$f_{LC} = \frac{1}{2\pi\sqrt{L \cdot C}} \quad (13)$$

Proven nominal values for inductance and ceramic capacitance are given in Table 2 and are recommended for use. Different values may work, but care has to be taken on the loop stability which is affected. More information including a detailed LC stability matrix can be found in SLVA463.

The TPS62136x devices include an internal 15 pF feedforward capacitor, connected between the VOS and FB pins. This capacitor impacts the frequency behavior and sets a pole and zero in the control loop with the resistors of the feedback divider, per equation Equation 14 and Equation 15:

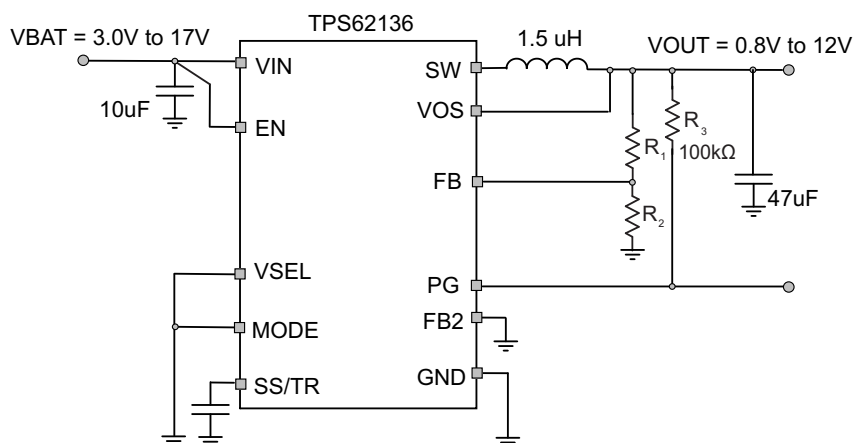
$$f_{zero} = \frac{1}{2\pi \times R_1 \times 15 pF} \quad (14)$$

$$f_{pole} = \frac{1}{2\pi \times 15 pF} \left(\frac{1}{R_1} + \frac{1}{R_2} \right) \quad (15)$$

Though the TPS62136x devices are stable without the pole and zero being in a particular location, adjusting their location to the specific needs of the application can provide better performance in Power Save mode and/or improved transient response. An external feedforward capacitor can also be added. A more detailed discussion on the optimization for stability versus transient response can be found in SLVA289 and SLVA466.

10.2 Typical Applications

10.2.1 Typical Application with Adjustable Output Voltage



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Figure 5. Typical Application

Typical Applications (continued)

10.2.1.1 Design Requirements

The design guideline provides a component selection to operate the device within the recommended operating conditions. See [Table 1](#) for the Bill of Materials used to generate the application curves.

10.2.1.2 Detailed Design Procedure

$$R_1 = R_2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1 \right) \quad (16)$$

With $V_{FB} = 0.7 \text{ V}$:

Table 5. Setting the Output Voltage

NOMINAL OUTPUT VOLTAGE	R1	R2	EXACT OUTPUT VOLTAGE
0.8 V	51 kΩ	360 kΩ	0.799 V
1.2 V	130 kΩ	180 kΩ	1.206 V
1.5 V	150 kΩ	130 kΩ	1.508 V
1.8 V	470 kΩ	300 kΩ	1.797 V
2.5 V	620 kΩ	240 kΩ	2.508 V
3.3 V	560 kΩ	150 kΩ	3.313 V
5 V	510 kΩ	82 kΩ	5.054 V
9 V	510 kΩ	43 kΩ	9.002 V
12 V	1000 kΩ	62 kΩ	11.99 V

10.2.1.3 Application Curves

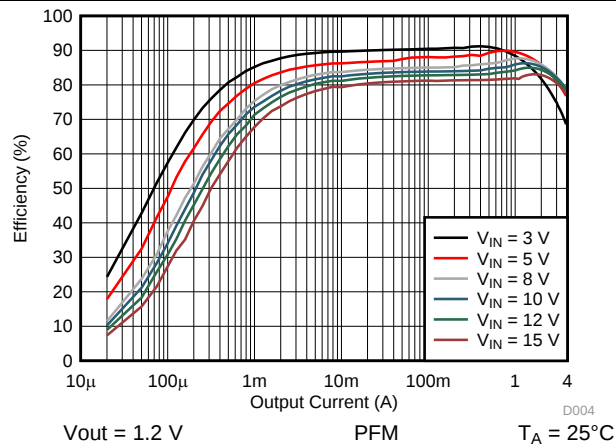


Figure 6. Efficiency vs Output Current

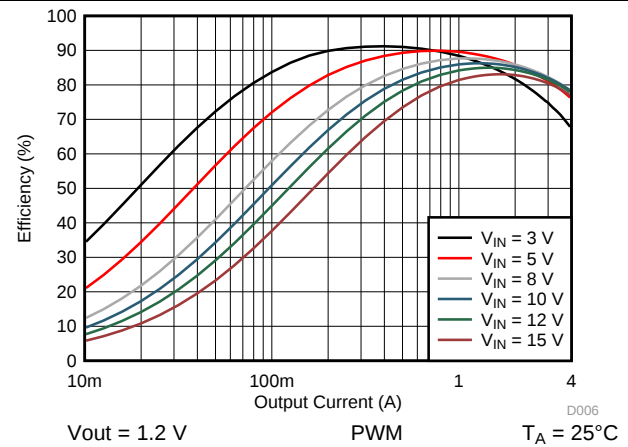


Figure 7. Efficiency vs Output Current

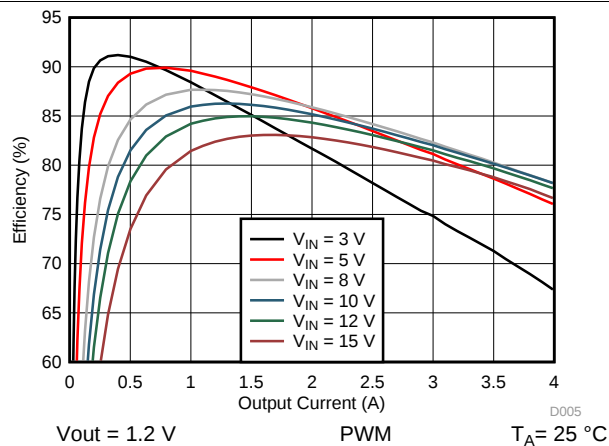


Figure 8. Efficiency vs Output Current

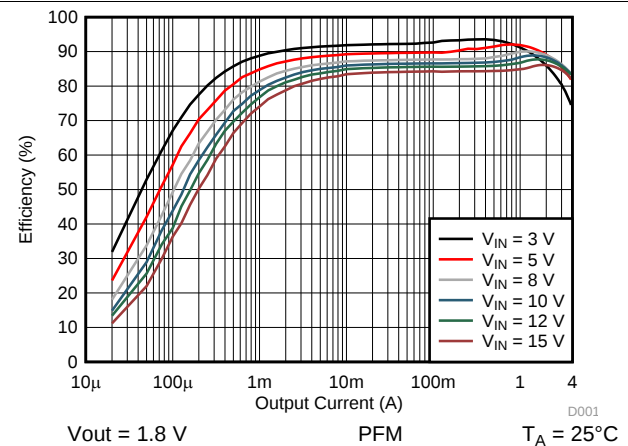


Figure 9. Efficiency vs Output Current

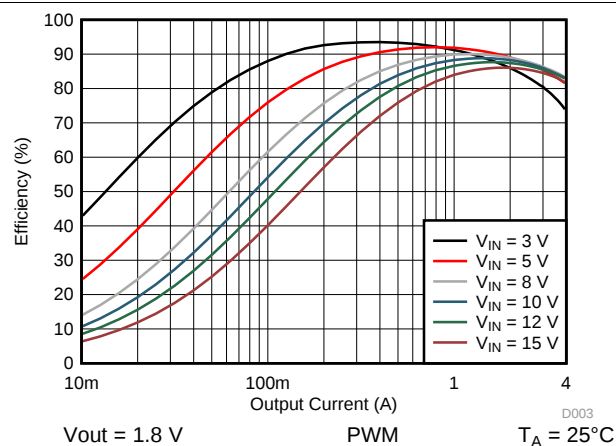


Figure 10. Efficiency vs Output Current

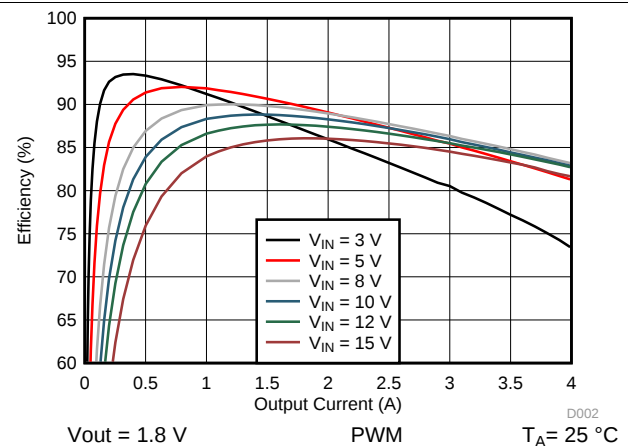


Figure 11. Efficiency vs Output Current

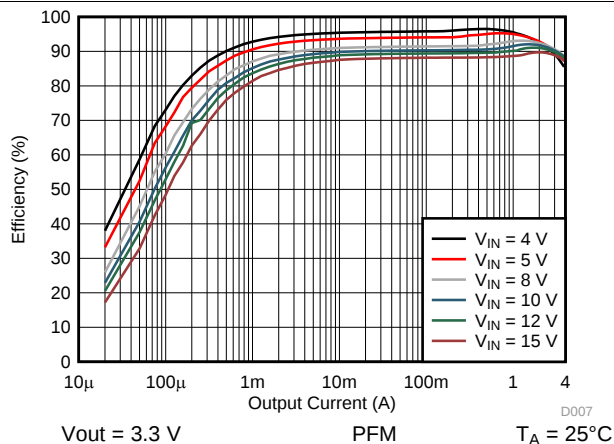


Figure 12. Efficiency vs Output Current

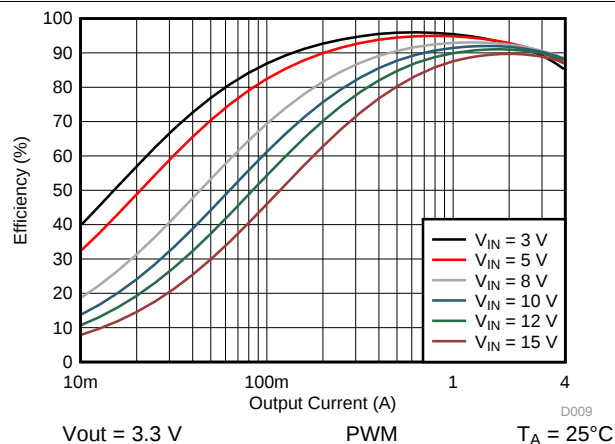


Figure 13. Efficiency vs Output Current

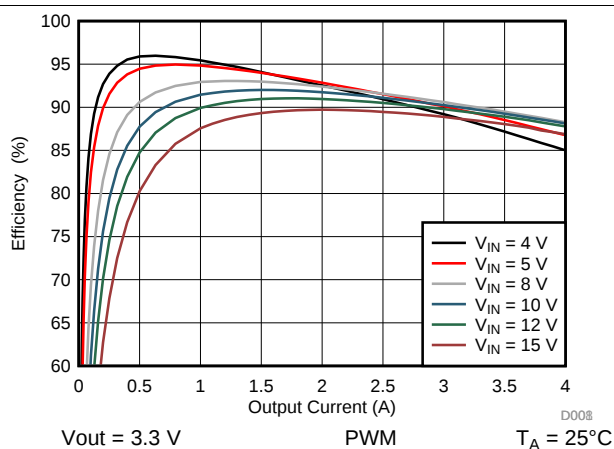


Figure 14. Efficiency vs Output Current

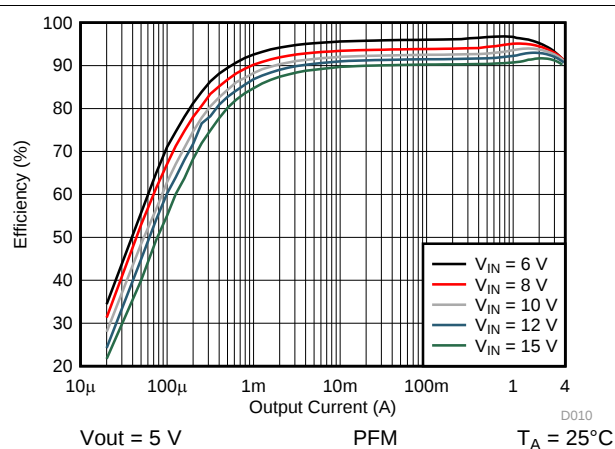


Figure 15. Efficiency vs Output Current

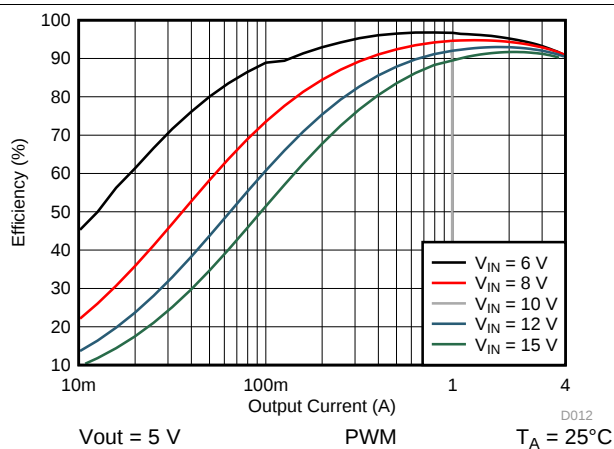


Figure 16. Efficiency vs Output Current

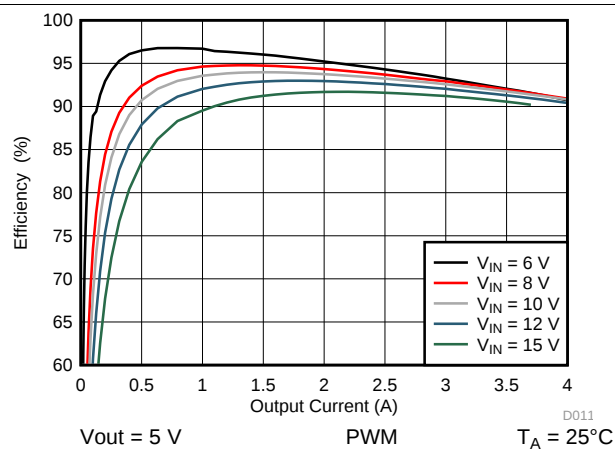


Figure 17. Efficiency vs Output Current

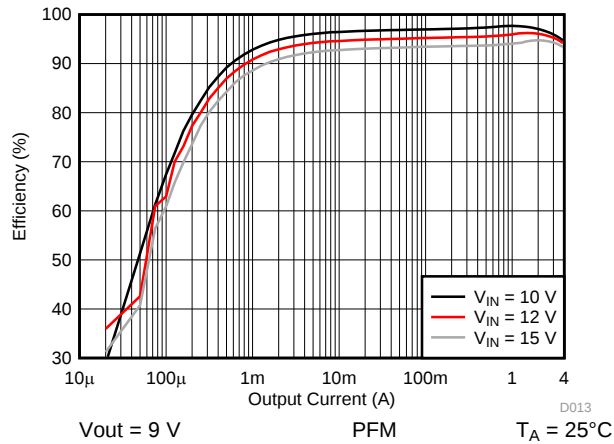


Figure 18. Efficiency vs Output Current

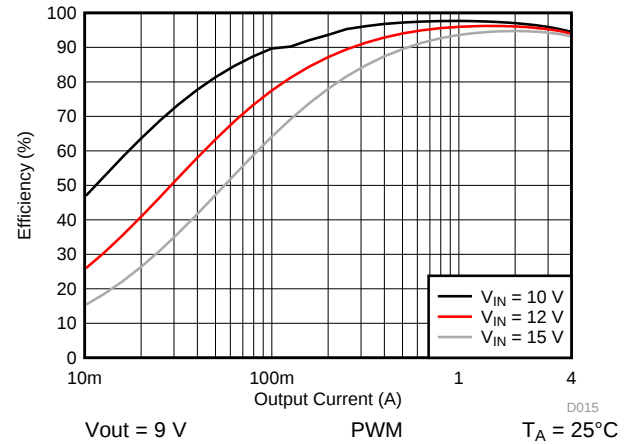


Figure 19. Efficiency vs Output Current

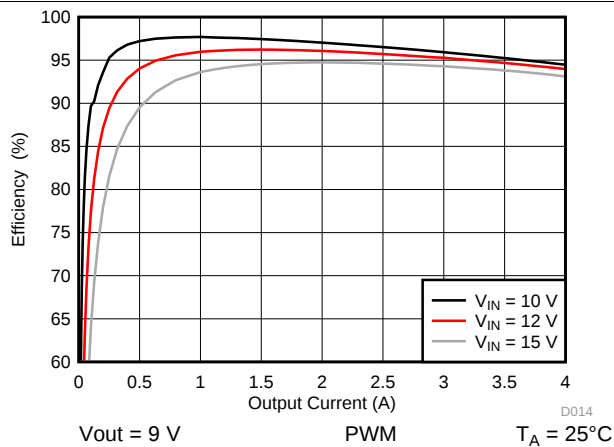


Figure 20. Efficiency vs Output Current

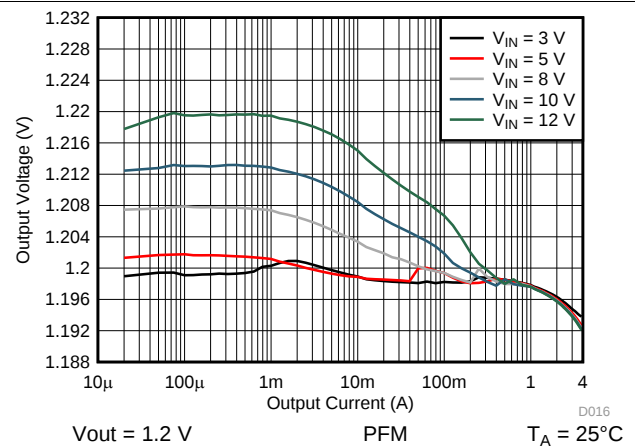


Figure 21. Output Voltage vs Output Current

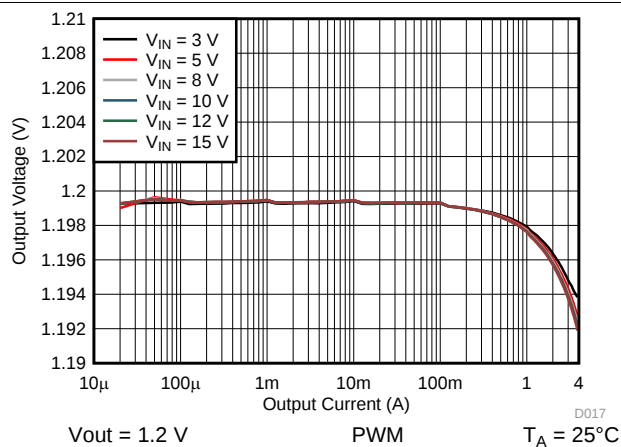


Figure 22. Output Voltage vs Output Current

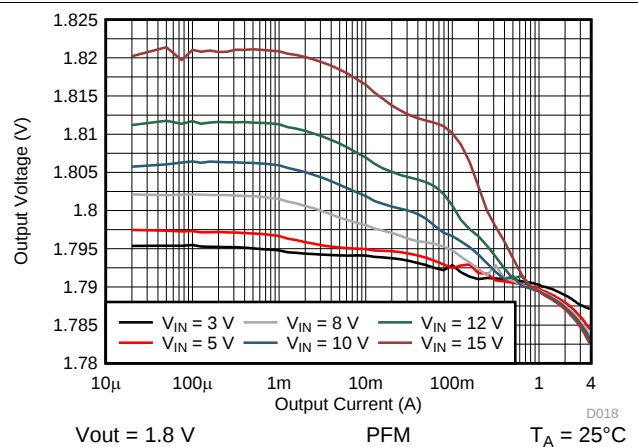


Figure 23. Output Voltage vs Output Current

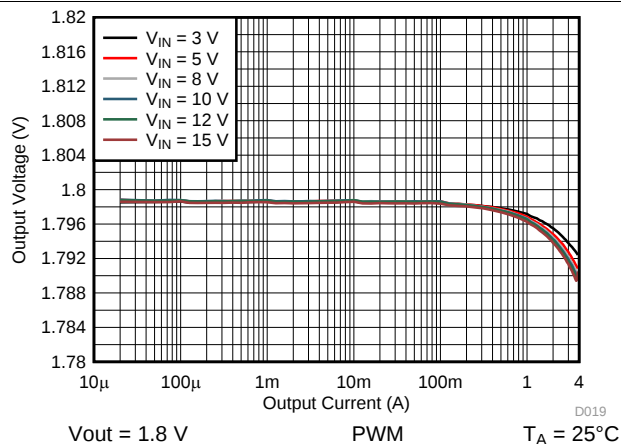


Figure 24. Output Voltage vs Output Current

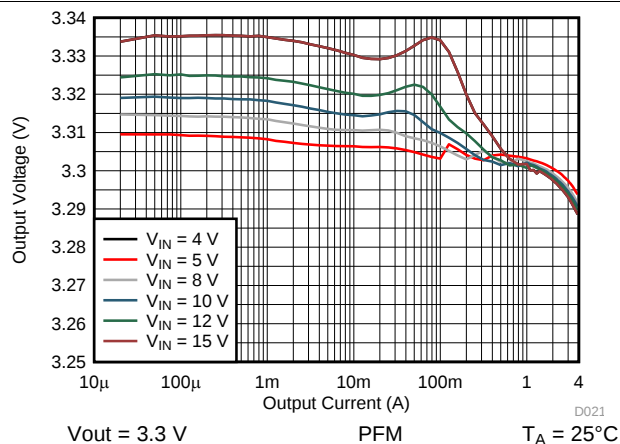


Figure 25. Output Voltage vs Output Current

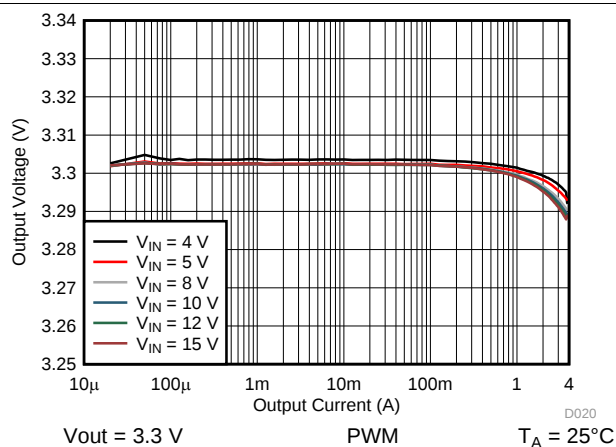


Figure 26. Output Voltage vs Output Current

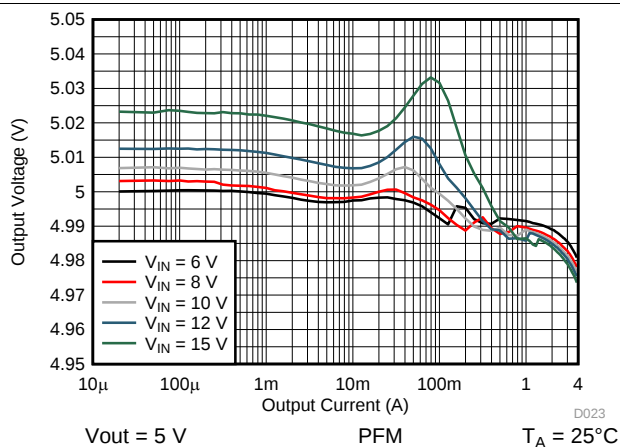


Figure 27. Output Voltage vs Output Current

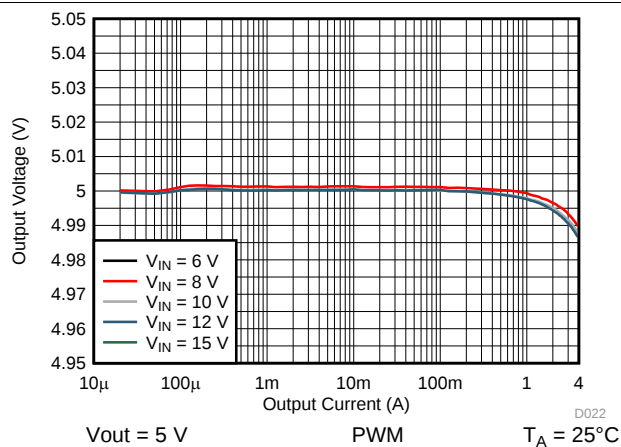


Figure 28. Output Voltage vs Output Current

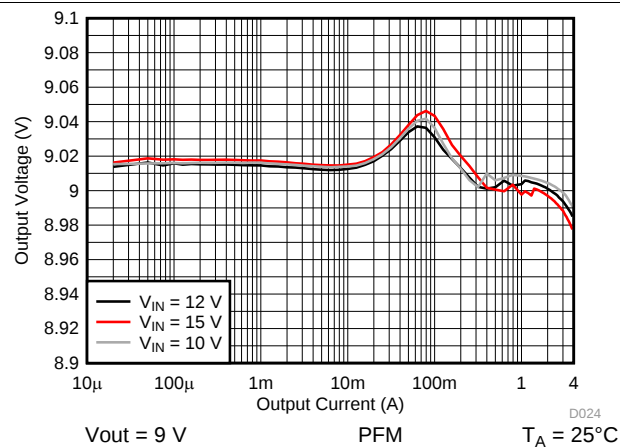


Figure 29. Output Voltage vs Output Current

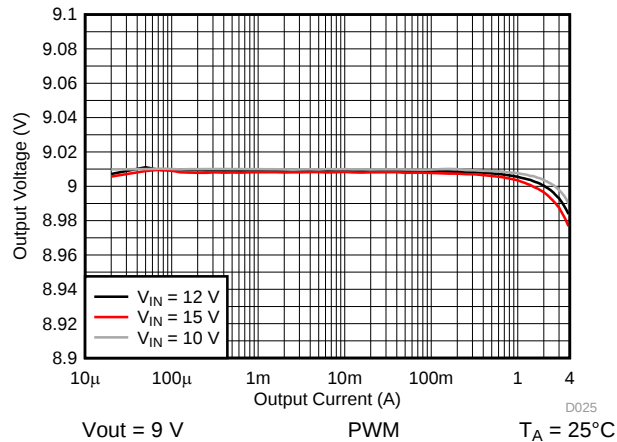


Figure 30. Output Voltage vs Output Current

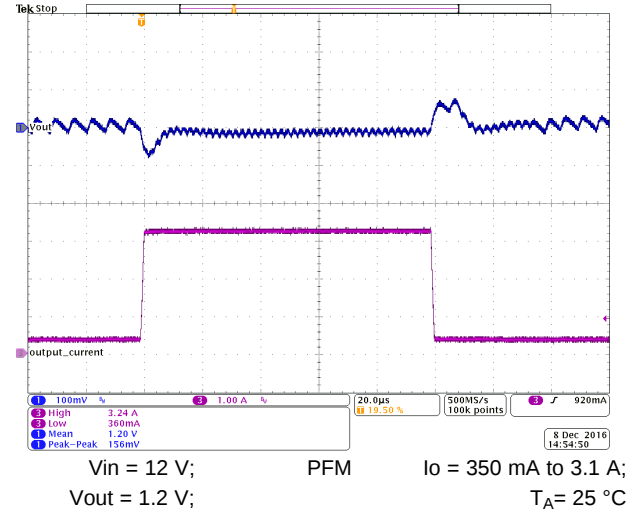


Figure 31. Load Transient Response

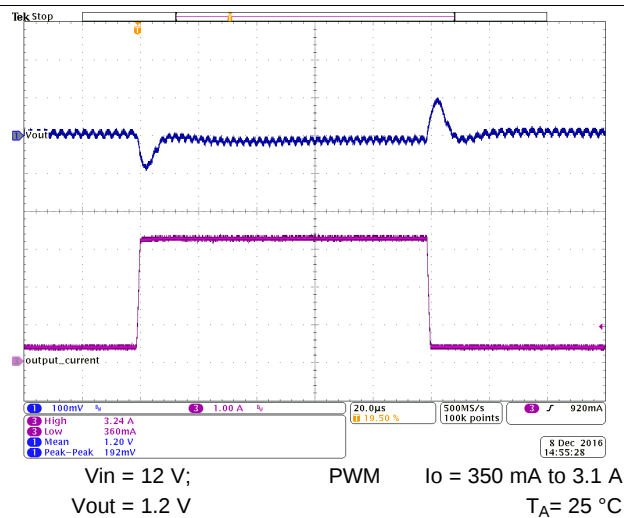


Figure 32. Load Transient Response

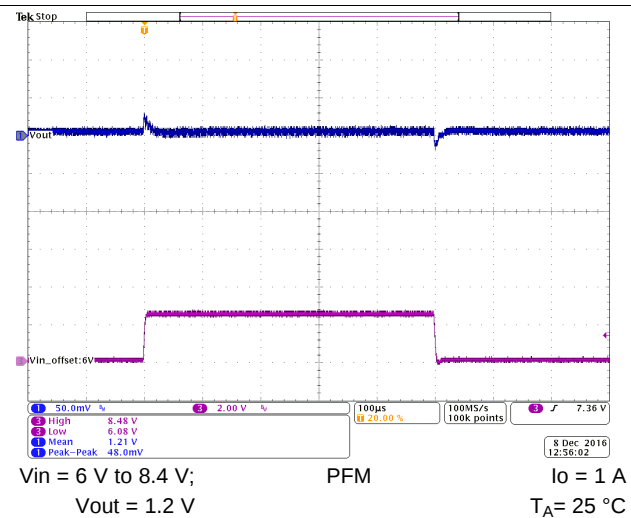


Figure 33. Line Transient Response

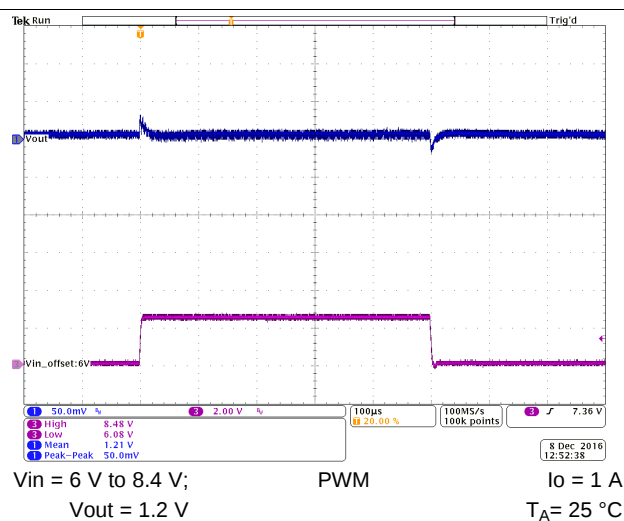


Figure 34. Line Transient Response

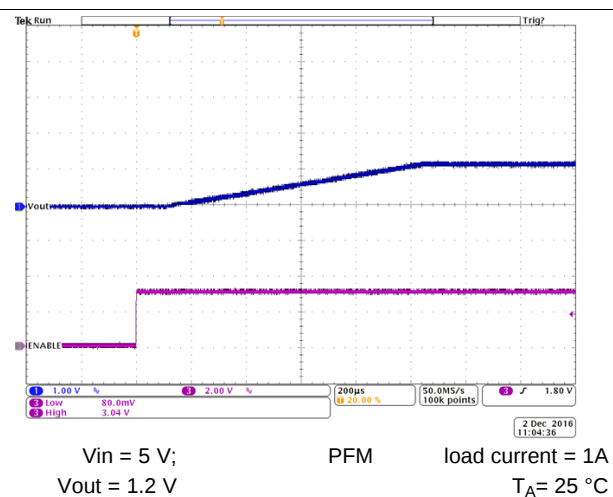


Figure 35. Start-Up Timing

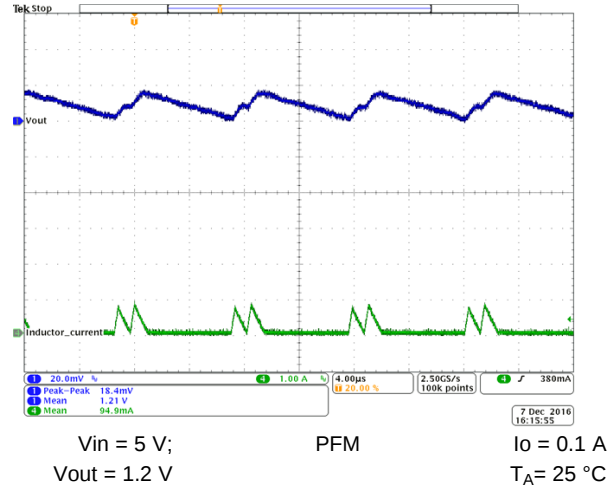


Figure 36. Output Voltage Ripple

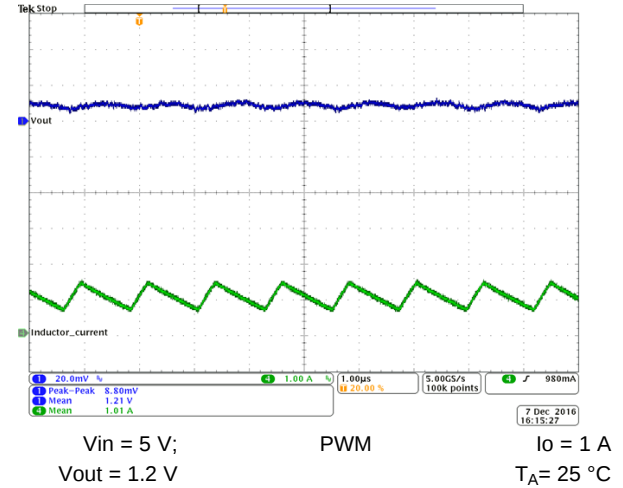


Figure 37. Output Voltage Ripple

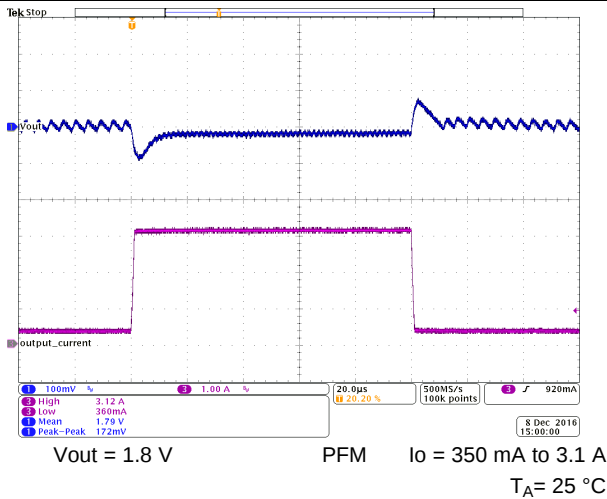


Figure 38. Load Transient Response

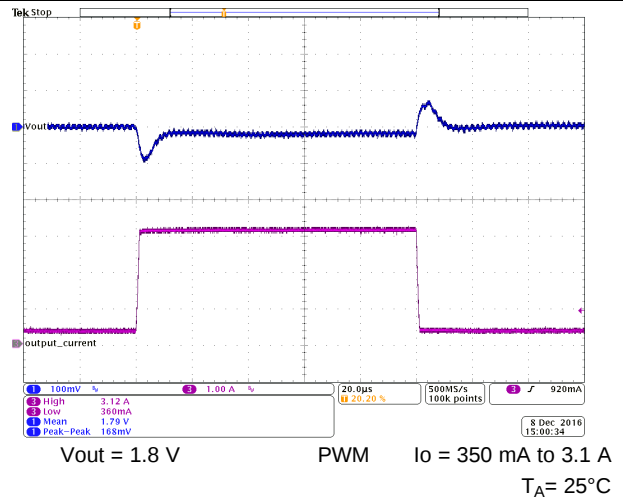


Figure 39. Load Transient Response

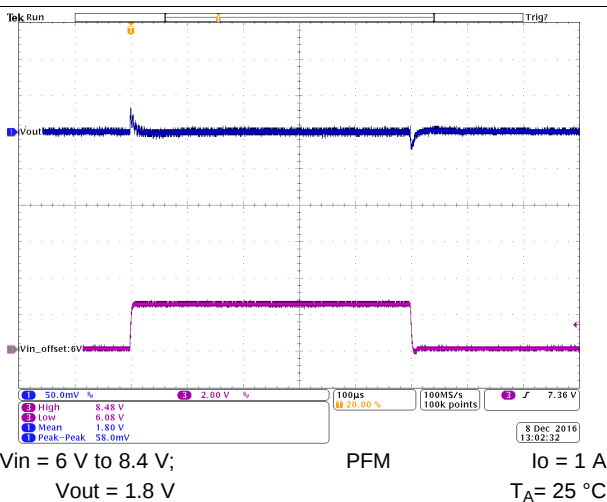


Figure 40. Line Transient Response

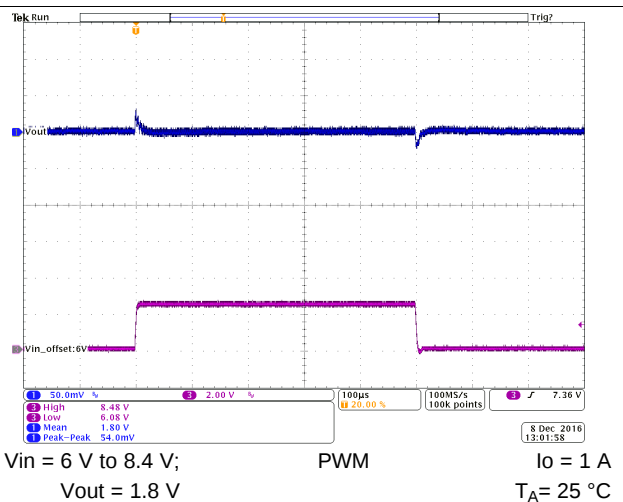


Figure 41. Line Transient Response

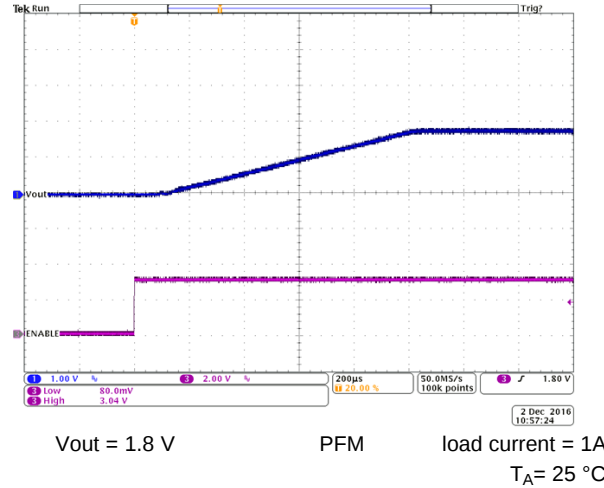


Figure 42. Start-Up Timing

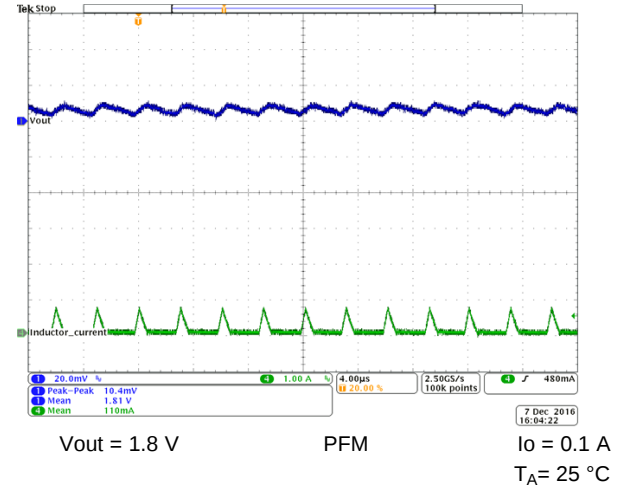


Figure 43. Output Voltage Ripple

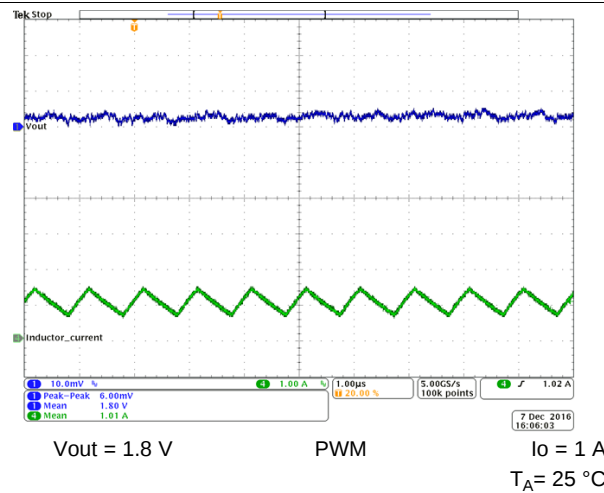


Figure 44. Output Voltage Ripple

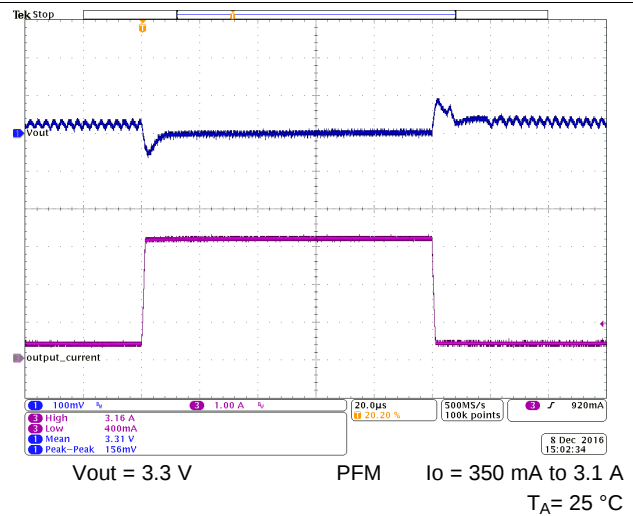


Figure 45. Load Transient Response

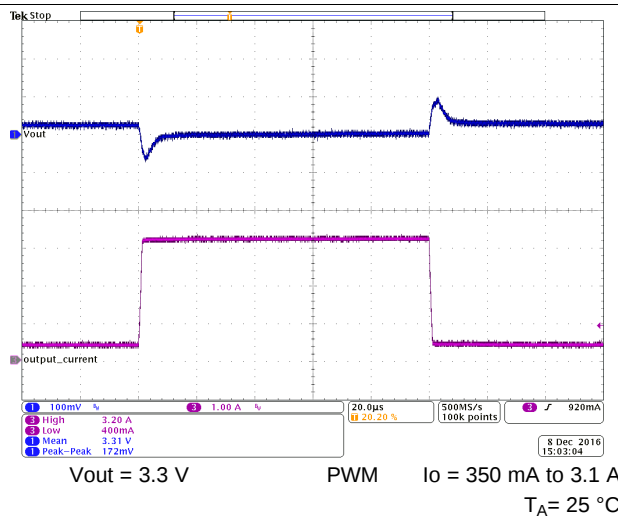


Figure 46. Load Transient Response

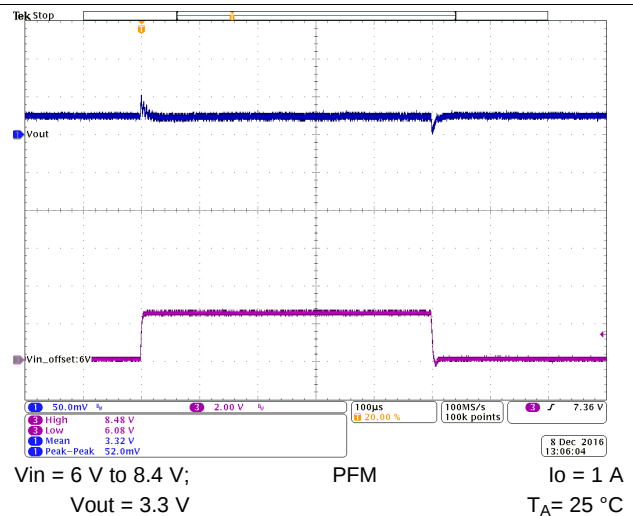


Figure 47. Line Transient Response

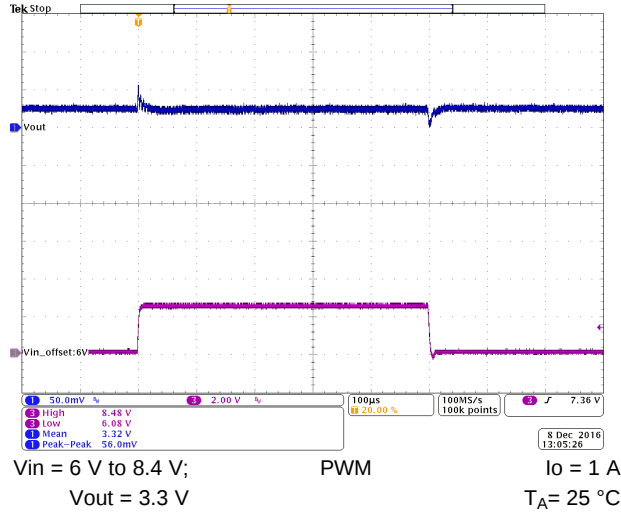


Figure 48. Line Transient Response

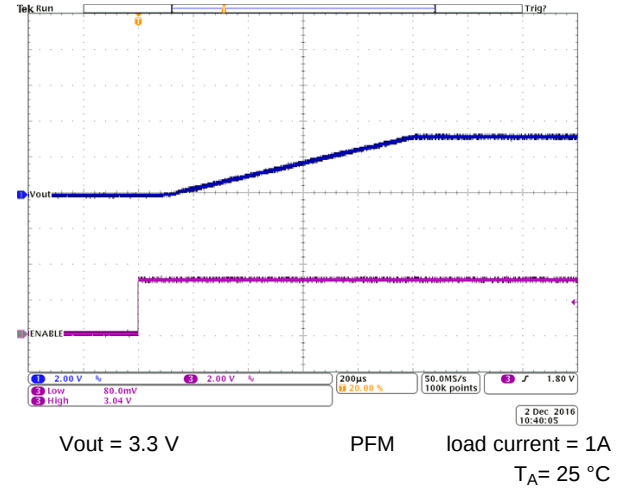


Figure 49. Start-Up Timing

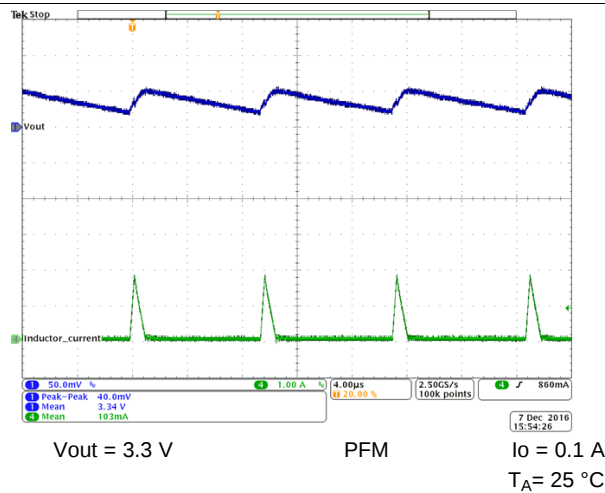


Figure 50. Output Voltage Ripple

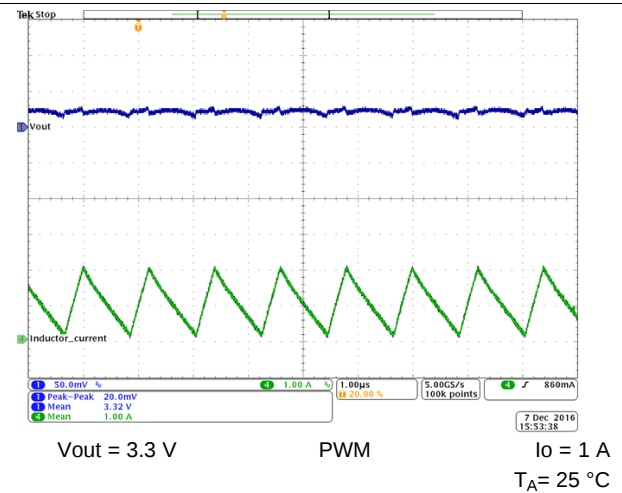


Figure 51. Output Voltage Ripple

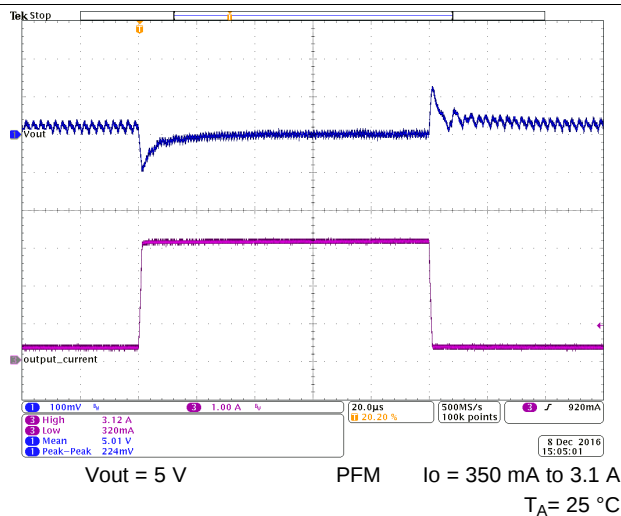


Figure 52. Load Transient Response

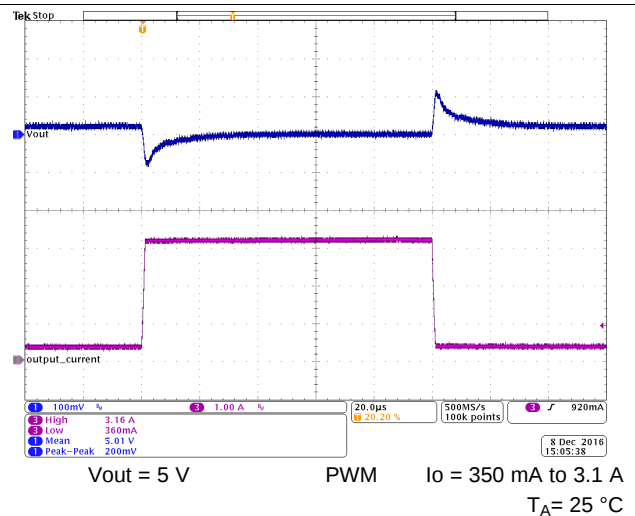


Figure 53. Load Transient Response

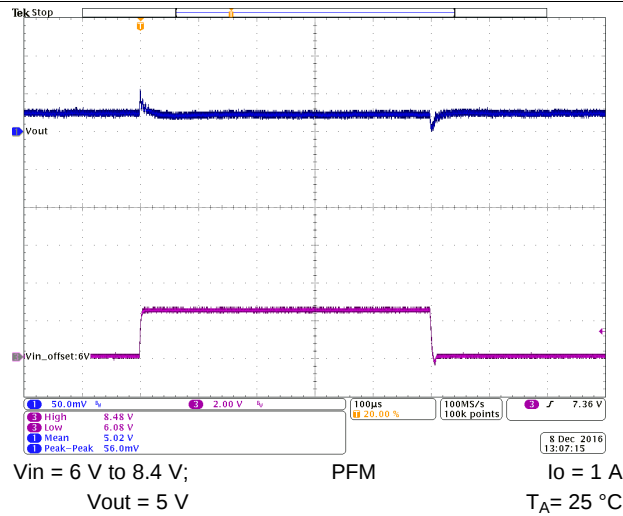


Figure 54. Line Transient Response

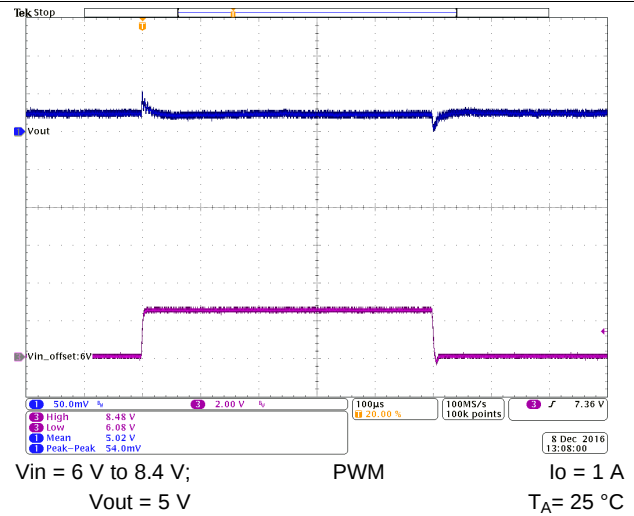


Figure 55. Line Transient Response

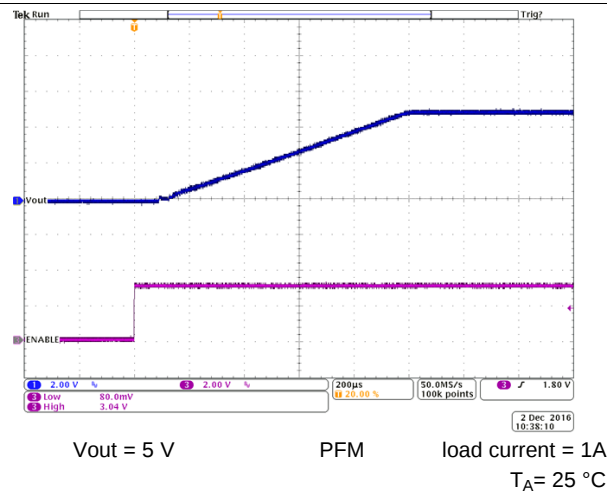


Figure 56. Start-Up Timing

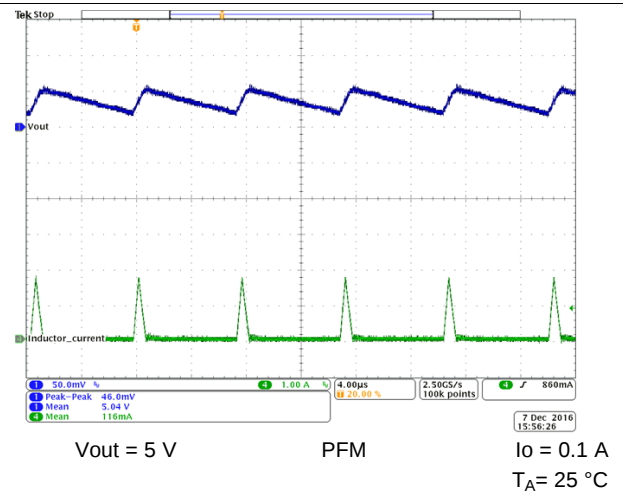


Figure 57. Output Voltage Ripple

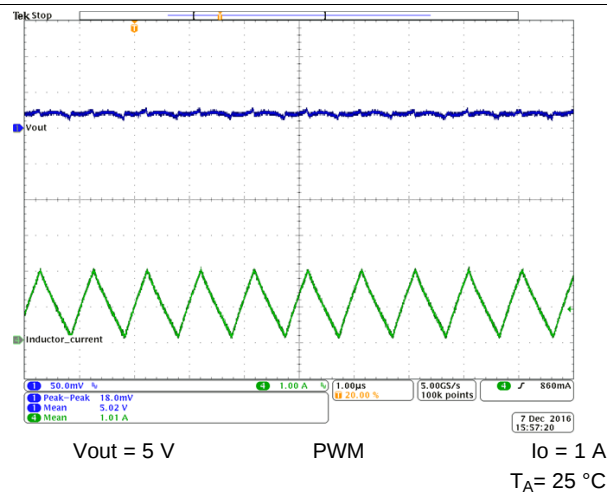


Figure 58. Output Voltage Ripple

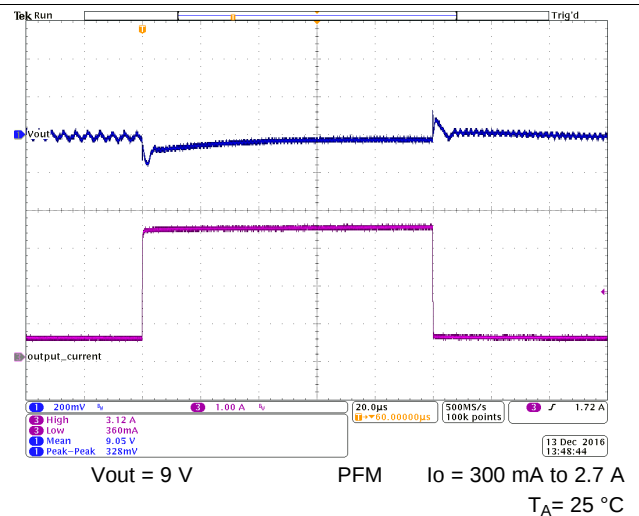


Figure 59. Load Transient Response

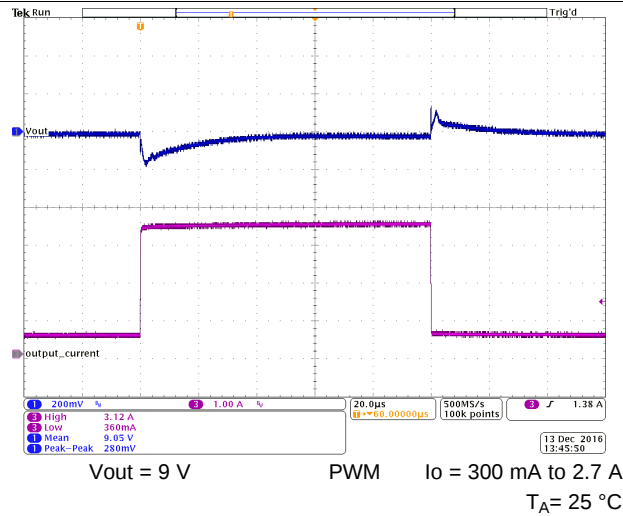


Figure 60. Load Transient Response

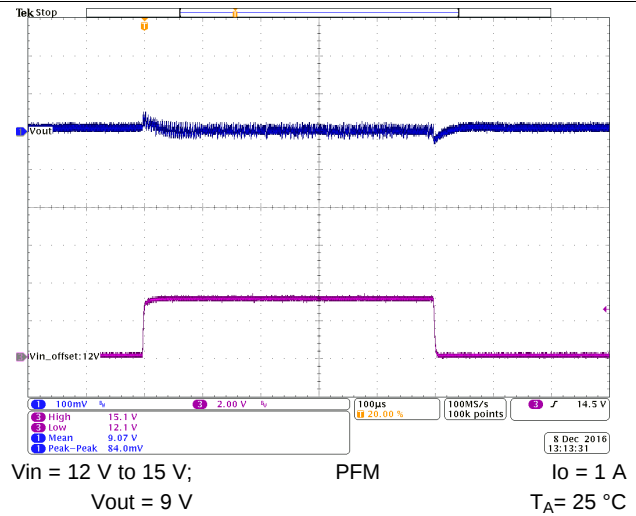


Figure 61. Line Transient Response

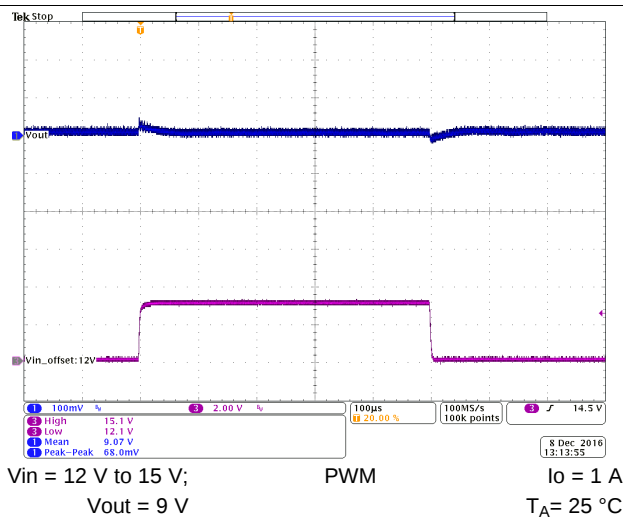


Figure 62. Line Transient Response

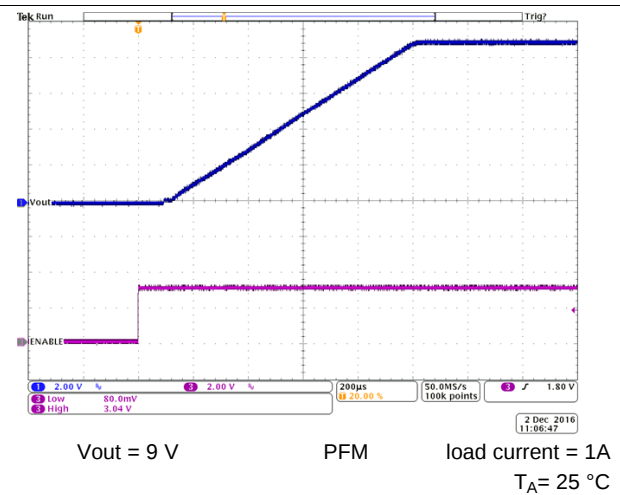


Figure 63. Start-Up Timing

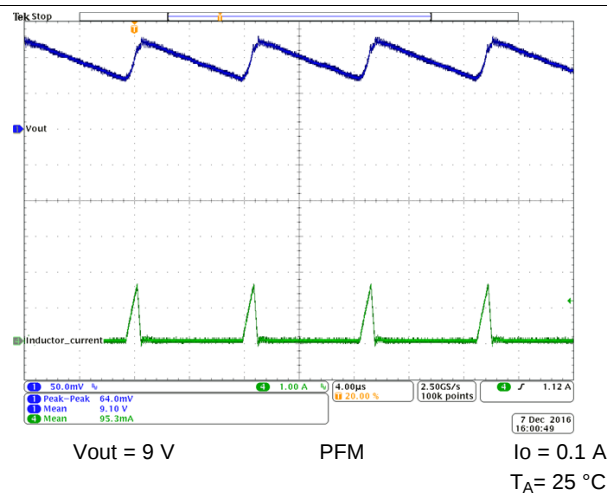


Figure 64. Output Voltage Ripple

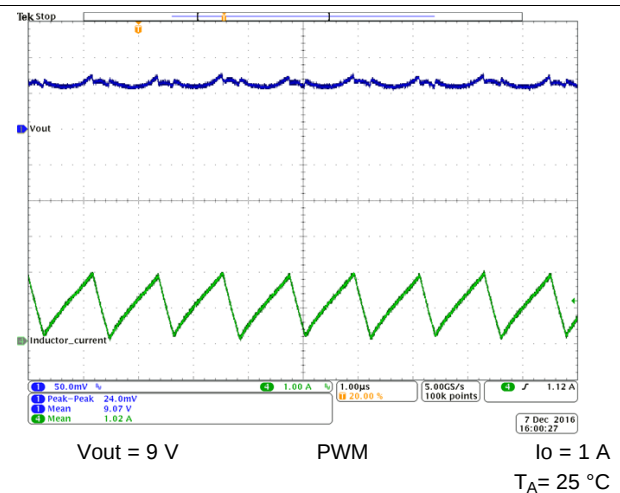
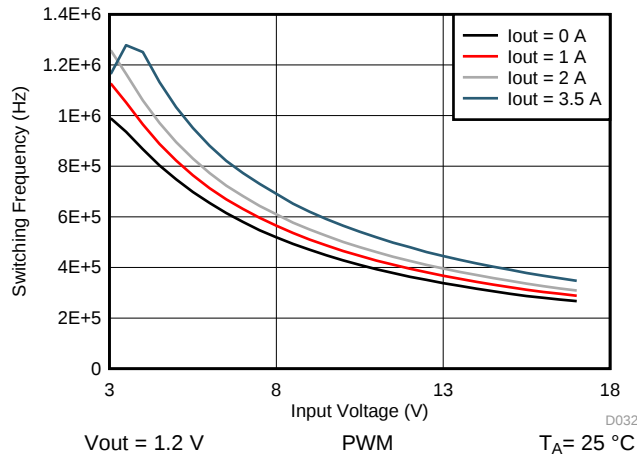
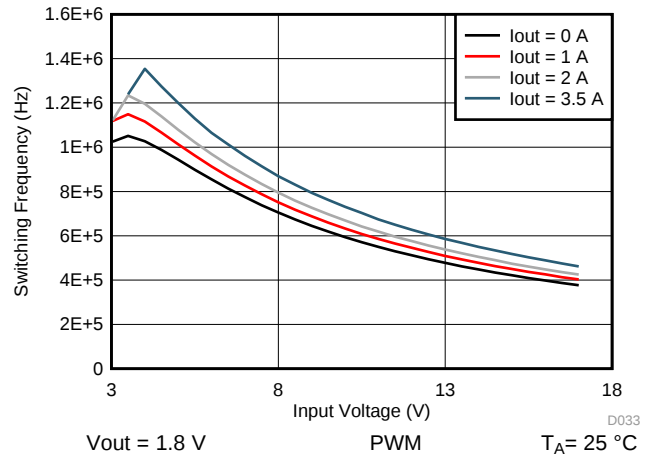
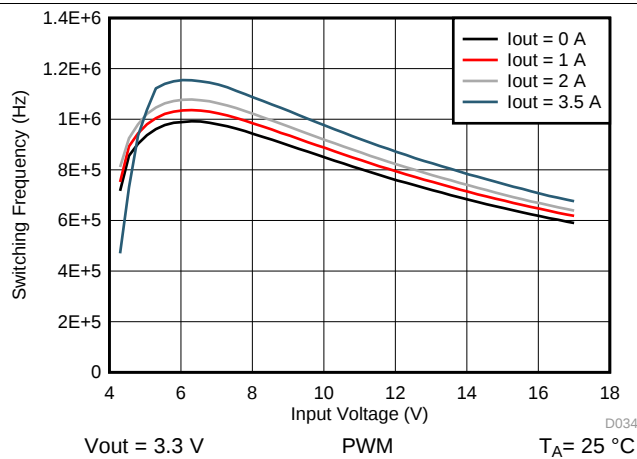
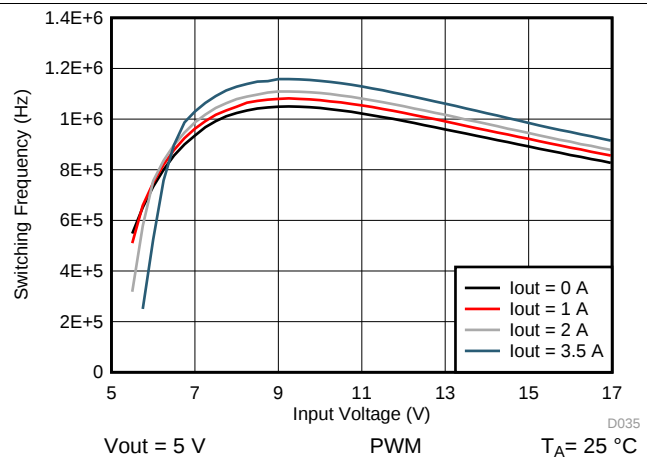
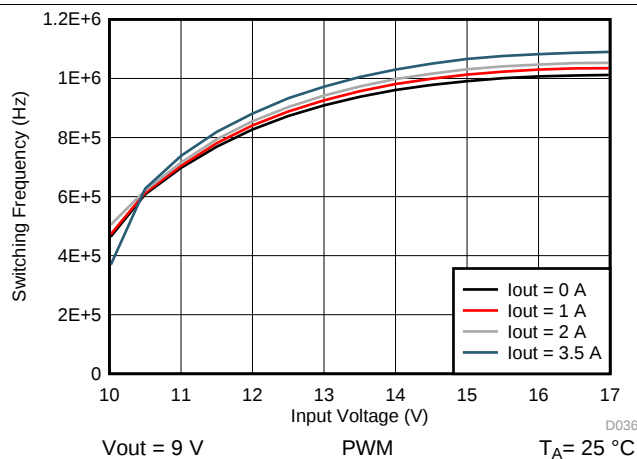
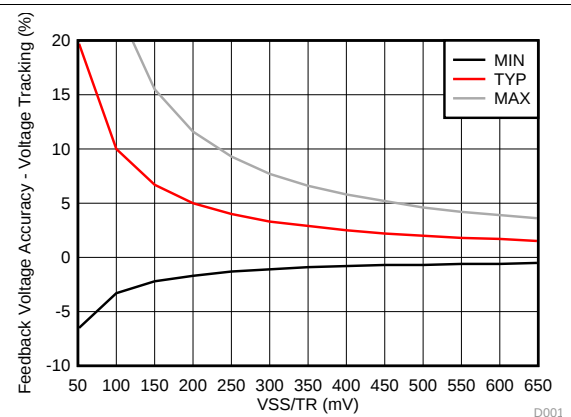
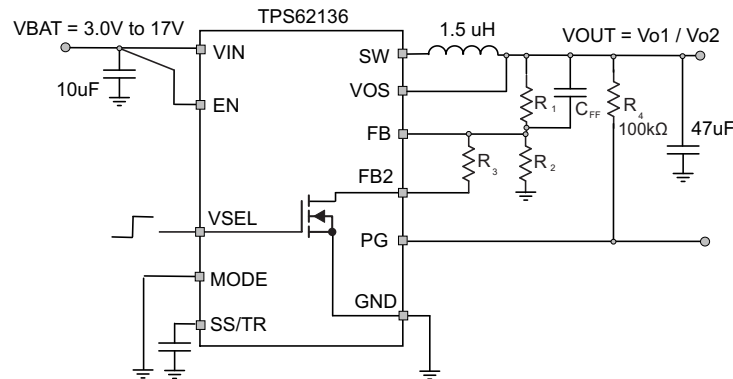


Figure 65. Output Voltage Ripple


Figure 66. Switching Frequency vs Input Voltage

Figure 67. Switching Frequency vs Input Voltage

Figure 68. Switching Frequency vs Input Voltage

Figure 69. Switching Frequency vs Input Voltage

Figure 70. Switching Frequency vs Input Voltage

Figure 71. Feedback Voltage Accuracy with Voltage Tracking vs Voltage at SS/TR Pin

10.2.2 Typical Application using VSEL and FB2



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Figure 72. Typical Application using VSEL

10.2.2.1 Design Requirements

VSEL allows to switch between two output voltages by changing the output voltage divider ratio. This is done by an internal MOSFET connecting resistor R3 to GND. Pulling VSEL high turns on the MOSFET that connects R3 in parallel to R2. The divider ratio is changed such that the output voltage increases from Vo1 to Vo2.

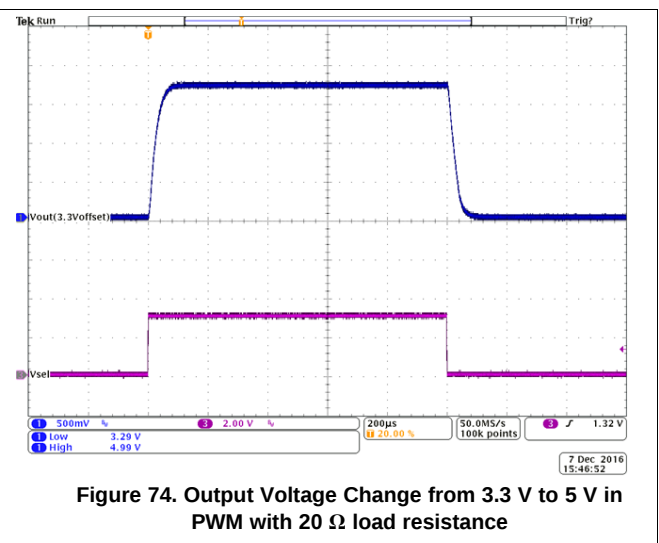
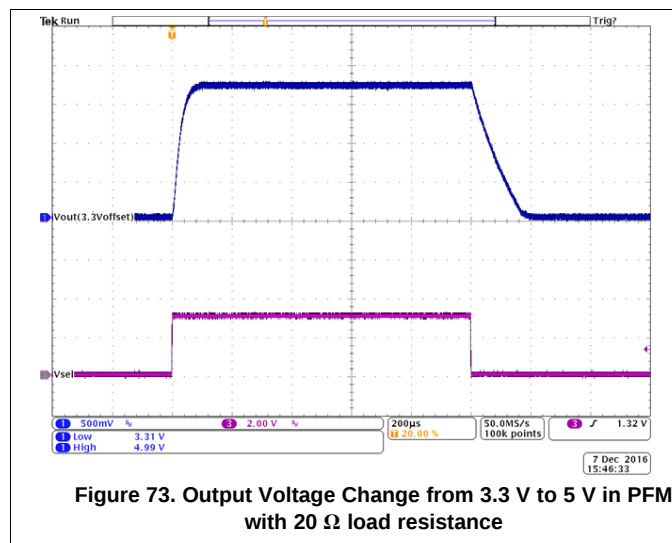
When the output voltage is ramped down and the device is in forced PWM mode, the device will sink current.

10.2.2.2 Detailed Design Procedure

TPS62136x typically does not require a feed forward capacitor in parallel to R1. For a large voltage change such as 3.3 V to 5 V, a small feed forward capacitor C_{FF} helps to improve the settling behavior. In order to switch from an output voltage of for example 3.3 V to an output voltage of 5 V, set the resistor divider for R1 and R2 to 3.3V and calculate R3 with Equation 17. With R1 = 560 kΩ and R2 = 150 kΩ this gives R3 = 232 kΩ. A feedforward capacitor of 12 pF was used to get a voltage transition as shown below.

$$R3 = \frac{Vo1 \times R1 \times R2^2}{(Vo2 - Vo1)(R1 \times R2 + R2^2)} \text{ for } Vo2 > Vo1 \quad (17)$$

10.2.2.3 Application Curves



10.3 System Examples

10.3.1 LED Power Supply

The TPS62136x can be used as a power supply for power LEDs. The FB pin can be easily set down to lower values than nominal by using the SS/TR pin. With that, the voltage drop on the sense resistor is low to avoid excessive power loss. Since this pin provides 2.5 μ A, the feedback pin voltage can be adjusted by an external resistor per Equation 18. This drop, proportional to the LED current, is used to regulate the output voltage (anode voltage) to a proper level to drive the LED. Both analog and PWM dimming are supported with the TPS62136x. Figure 75 shows an application circuit, tested with analog dimming:

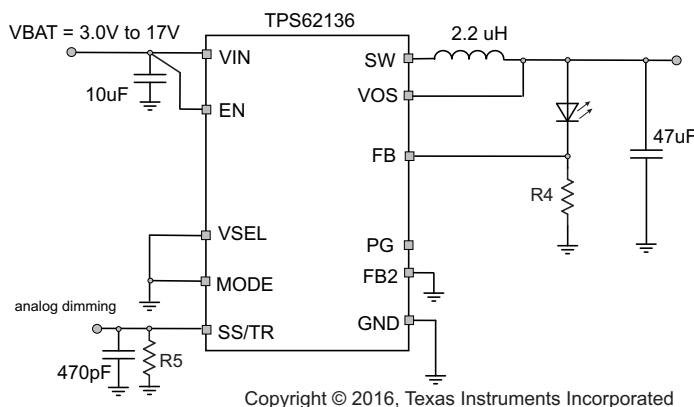


Figure 75. Single Power LED Supply

The resistor at SS/TR defines the FB voltage. It is set to 350 mV by $R5 = 140 \text{ k}\Omega$ using Equation 18. This cuts the losses on R4 to half from the nominal 0.7 V of feedback voltage while it still provides good accuracy.

$$V_{FB} = 2.5\mu A \times R_{SS/TR} + 11mV \quad (18)$$

The device now supplies a constant current set by resistor R4 from FB to GND. The minimum input voltage has to be rated according the forward voltage needed by the LED used. More information is available in the Application Note SLVA451.

10.3.2 Powering Multiple Loads

In applications where TPS62136x is used to power multiple load circuits, it may be the case that the total capacitance on the output is very large. In order to properly regulate the output voltage, there needs to be an appropriate AC signal level on the VOS pin. Tantalum capacitors have a large enough ESR to keep output voltage ripple sufficiently high on the VOS pin. With low ESR ceramic capacitors, the output voltage ripple may get very low, so it is not recommended to use a large capacitance directly on the output of the device. If there are several load circuits with their associated input capacitor on a pcb, these loads are typically distributed across the board. This adds enough trace resistance (R_{trace}) to keep a large enough AC signal on the VOS pin for proper regulation.

The minimum total trace resistance on the distributed load is 10 m Ω . The total capacitance $n \times C_{in}$ in the use case below was 32 x 47 uF of ceramic X7R capacitors.

System Examples (continued)

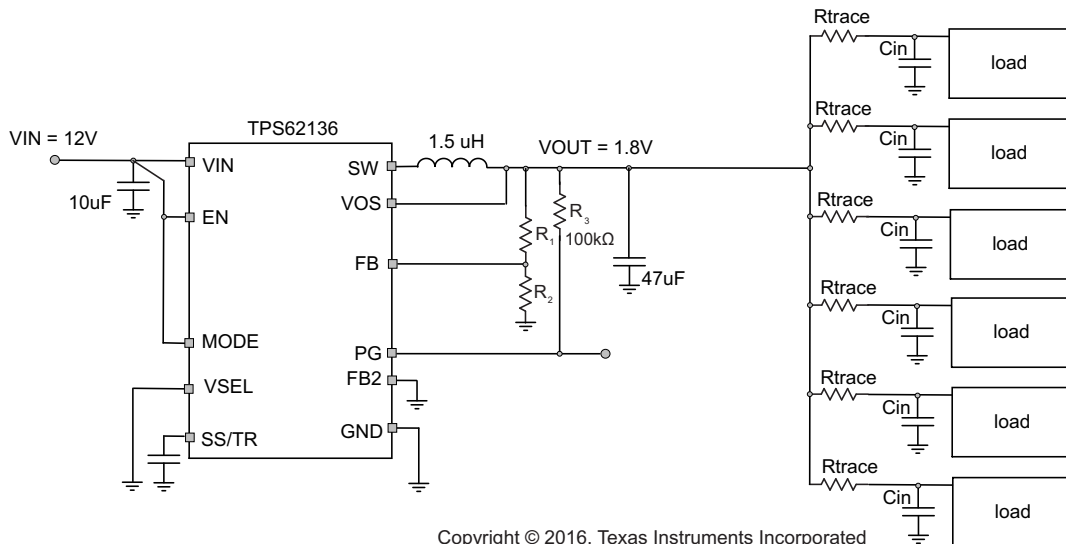


Figure 76. Multiple Loads

10.3.3 Voltage Tracking

DEVICE 2 follows the voltage applied to the SS/TR pin. A ramp on SS/TR to 0.7 V ramps the output voltage according to the 0.7 V reference.

Tracking the 3.3 V of DEVICE 1 requires a resistor divider on SS/TR of DEVICE 2 equal to the output voltage divider of DEVICE 1. The output current of 2.5μA from the SS/TR pin causes an offset voltage on the resistor divider formed by R5 and R6. The equivalent resistance of R6 // R5 should therefore be kept below 15kΩ.

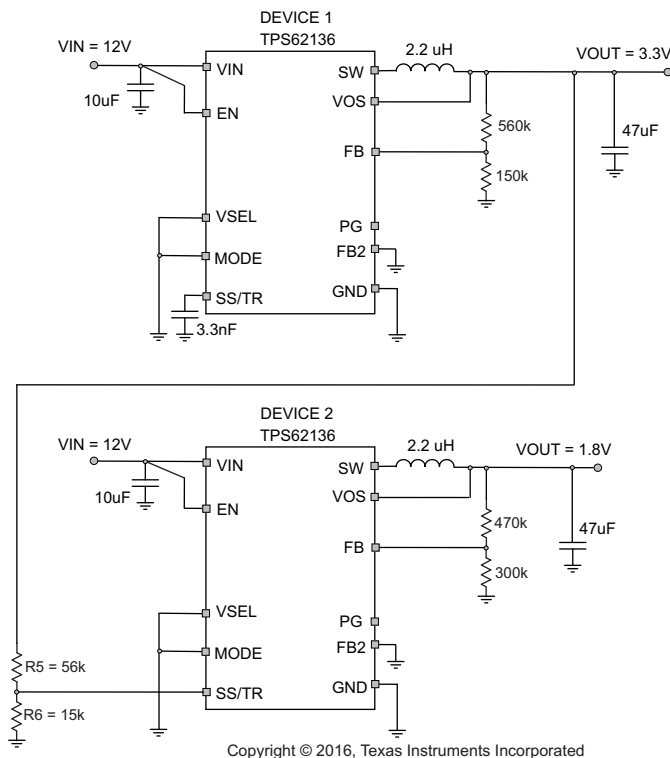


Figure 77. Tracking Example

System Examples (continued)

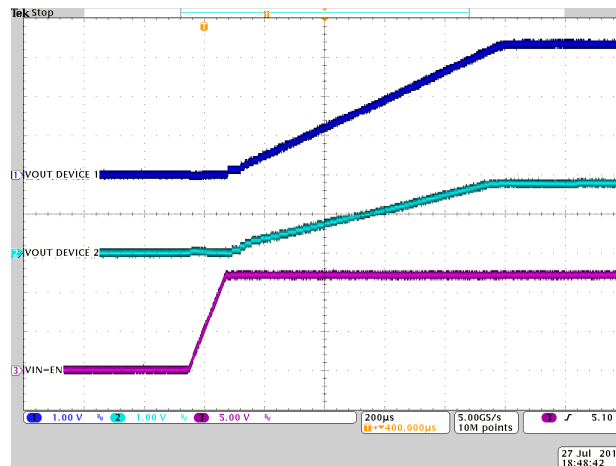


Figure 78. Tracking

10.3.4 Precise Soft-Start Timing

The SS/TR pin of the TPS62136x can be used for tracking as well as for setting the Soft-Start time. The TPS62136x has one GND terminal which is used for the power ground as well as for the analog ground connection. While starting the device with a load current above approximately 1 A, the noise on the GND connection can lead to a Soft-Start time shorter than calculated. There are two external work arounds as given below.

Adding a 10 kΩ resistor filters the noise on the GND connection and keeps the Soft-Start time at the value calculated.

[Figure 80](#) does not require an external component. It provides a connection to the internal analog ground by using the FB2 pin and its internal NMOS to that node. The internal NMOS needs to be turned ON by setting VSEL = high.

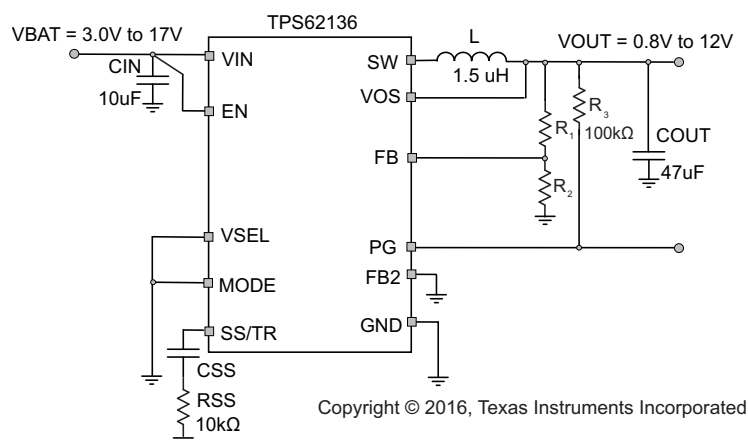


Figure 79. Adding a Series Resistor to CSS

System Examples (continued)

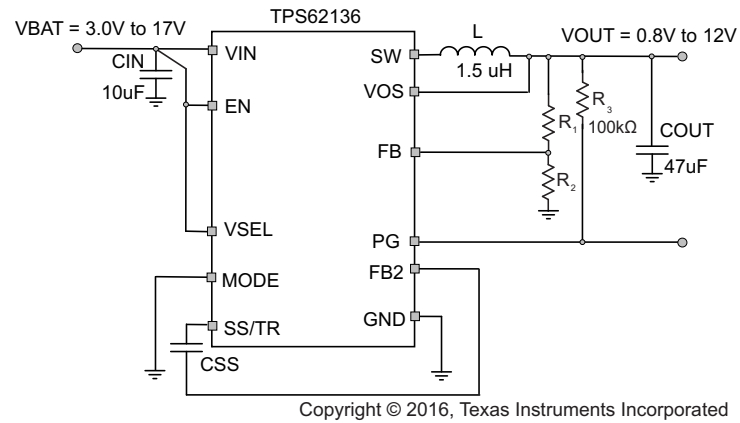


Figure 80. Connecting CSS to the Internal Analog Ground by using FB2

11 Power Supply Recommendations

The power supply to the TPS62136x needs to have a current rating according to the supply voltage, output voltage, and output current of the TPS62136x.

12 Layout

12.1 Layout Guidelines

A proper layout is critical for the operation of a switched mode power supply, even more at high switching frequencies. Therefore the PCB layout of the TPS62136x demands careful attention to ensure operation and to get the performance specified. A poor layout can lead to issues like poor regulation (both line and load), stability and accuracy weaknesses, increased EMI radiation and noise sensitivity.

See [Figure 81](#) for the recommended layout of the TPS62136x, which is designed for common external ground connections. The input capacitor should be placed as close as possible between the VIN and GND pin of TPS62136x. Also connect the VOS pin in the shortest way to VOUT at the output capacitor.

Provide low inductive and resistive paths for loops with high di/dt. Therefore paths conducting the switched load current should be as short and wide as possible. Provide low capacitive paths (with respect to all other nodes) for wires with high dv/dt. Therefore the input and output capacitance should be placed as close as possible to the IC pins and parallel wiring over long distances as well as narrow traces should be avoided. Loops which conduct an alternating current should outline an area as small as possible, as this area is proportional to the energy radiated.

Sensitive nodes like FB and VOS need to be connected with short wires and not nearby high dv/dt signals (for example SW). As they carry information about the output voltage, they should be connected as close as possible to the actual output voltage (at the output capacitor). The capacitor on the SS/TR pin as well as the FB resistors, R1 and R2, should be kept close to the IC and connect directly to those pins and the system ground plane. The same applies to R3 if FB2 is used to scale the output voltage.

The package uses the pins for power dissipation. Thermal vias on the VIN, GND and SW pins help to spread the heat through the pcb.

In case any of the digital inputs EN, VSEL or MODE need to be tied to the input supply voltage at VIN, the connection must be made directly at the input capacitor as indicated in the schematics.

The recommended layout is implemented on the EVM and shown in its User's Guide, [SLVUAI7](#).

12.2 Layout Example

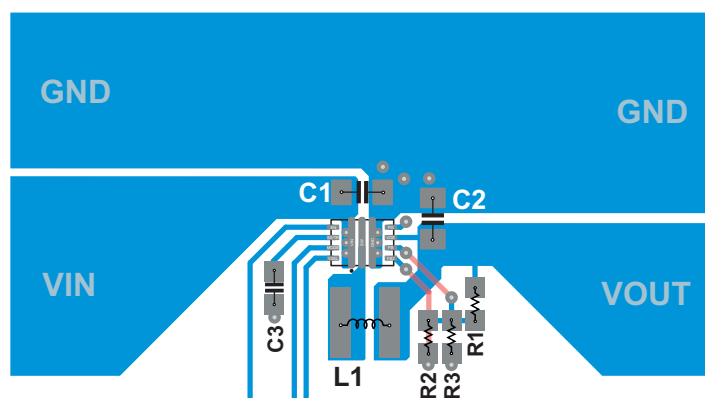


Figure 81. Layout

12.3 Thermal Considerations

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power-dissipation limits of a given component.

Three basic approaches for enhancing thermal performance are listed below:

- Improving the power dissipation capability of the PCB design, for example, increasing copper thickness, thermal vias, number of layers
- Introducing airflow in the system

For more details on how to use the thermal parameters, see the application notes: Thermal Characteristics Application Note ([SZZA017](#)), and ([SPRA953](#)).

The TPS62136x is designed for a maximum operating junction temperature (T_j) of 125 °C. Therefore the maximum output power is limited by the power losses that can be dissipated over the actual thermal resistance, given by the package and the surrounding PCB structures. If the thermal resistance of the package is given, the size of the surrounding copper area and a proper thermal connection of the IC can reduce the thermal resistance. To get an improved thermal behavior, it's recommended to use top layer metal to connect the device with wide and thick metal lines. Internal ground layers can connect to vias directly under the IC for improved thermal performance.

If short circuit or overload conditions are present, the device is protected by limiting internal power dissipation.

13 Device and Documentation Support

13.1 Device Support

13.1.1 Third-Party Products Disclaimer

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13.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

13.3 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to order now.

Table 6. Related Links

PARTS	PRODUCT FOLDER	ORDER NOW	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
TPS62136	Click here	Click here	Click here	Click here	Click here
TPS621361	Click here	Click here	Click here	Click here	Click here

13.4 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

13.5 Trademarks

AEE, DCS-Control, E2E are trademarks of Texas Instruments.
All other trademarks are the property of their respective owners.

13.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

13.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS621361RGXR	ACTIVE	VQFN-HR	RGX	11	3000	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 125	621361	Samples
TPS621361RGXT	ACTIVE	VQFN-HR	RGX	11	250	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 125	621361	Samples
TPS62136RGXR	ACTIVE	VQFN-HR	RGX	11	3000	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 125	62136	Samples
TPS62136RGXT	ACTIVE	VQFN-HR	RGX	11	250	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 125	62136	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION


*All dimensions are nominal

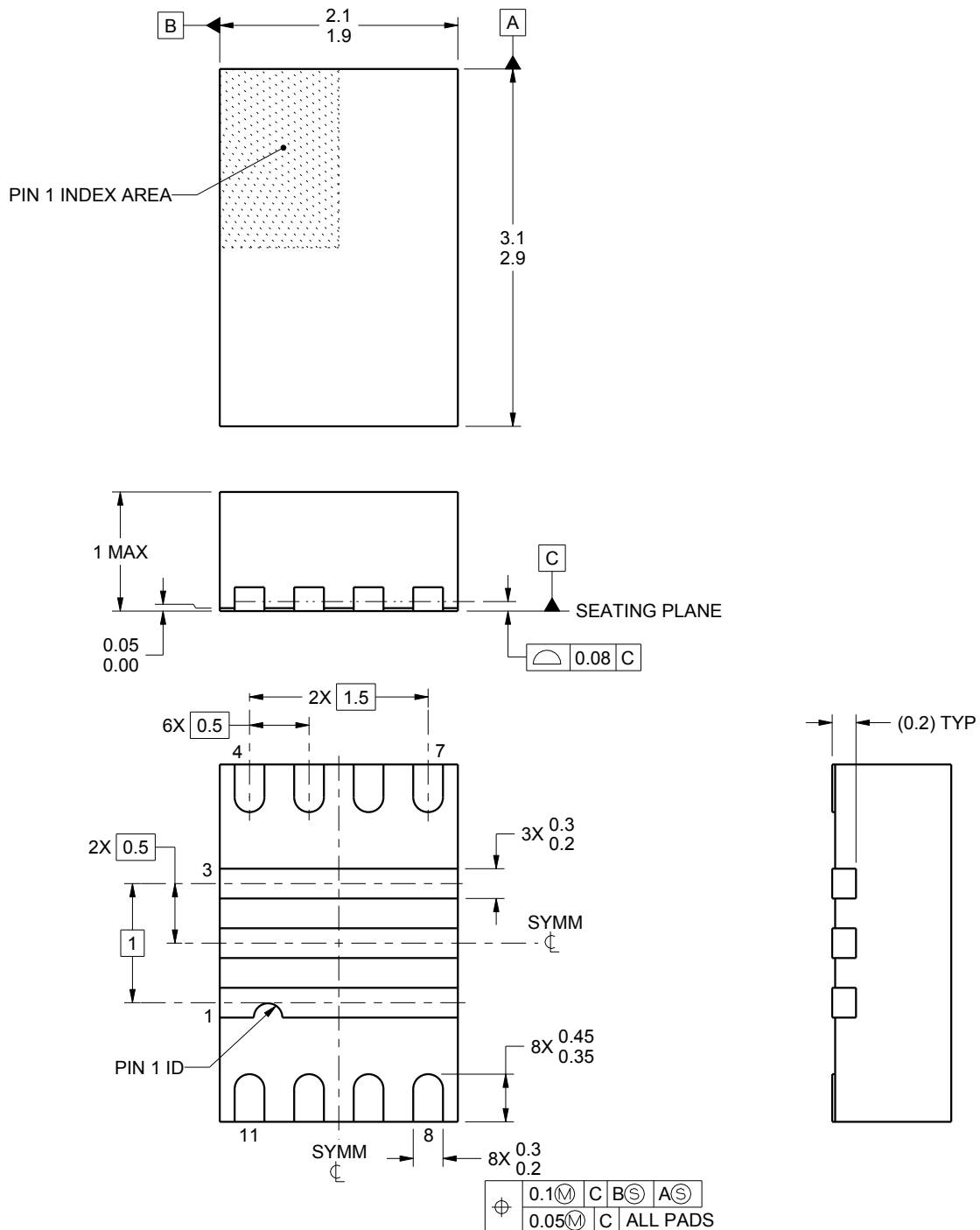
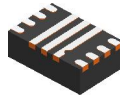
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS621361RGXR	VQFN-HR	RGX	11	3000	180.0	8.4	2.25	3.25	1.05	4.0	8.0	Q1
TPS621361RGXT	VQFN-HR	RGX	11	250	180.0	8.4	2.25	3.25	1.05	4.0	8.0	Q1
TPS62136RGXR	VQFN-HR	RGX	11	3000	180.0	8.4	2.25	3.25	1.05	4.0	8.0	Q1
TPS62136RGXT	VQFN-HR	RGX	11	250	180.0	8.4	2.25	3.25	1.05	4.0	8.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS621361RGXR	VQFN-HR	RGX	11	3000	182.0	182.0	20.0
TPS621361RGXT	VQFN-HR	RGX	11	250	182.0	182.0	20.0
TPS62136RGXR	VQFN-HR	RGX	11	3000	182.0	182.0	20.0
TPS62136RGXT	VQFN-HR	RGX	11	250	182.0	182.0	20.0



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NOTES:

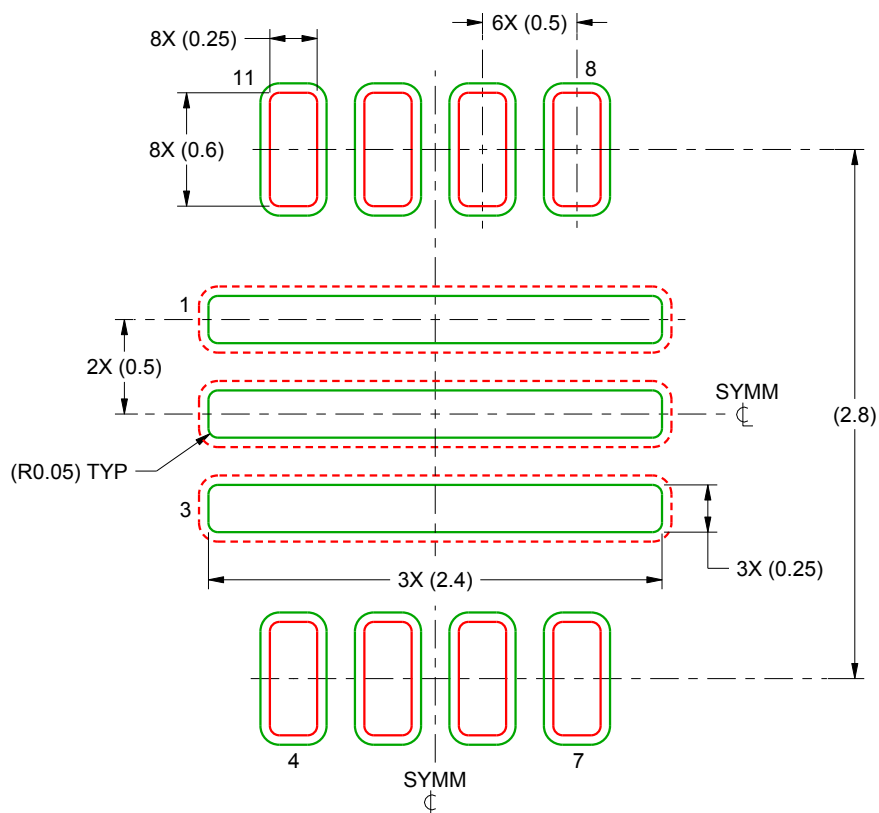
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

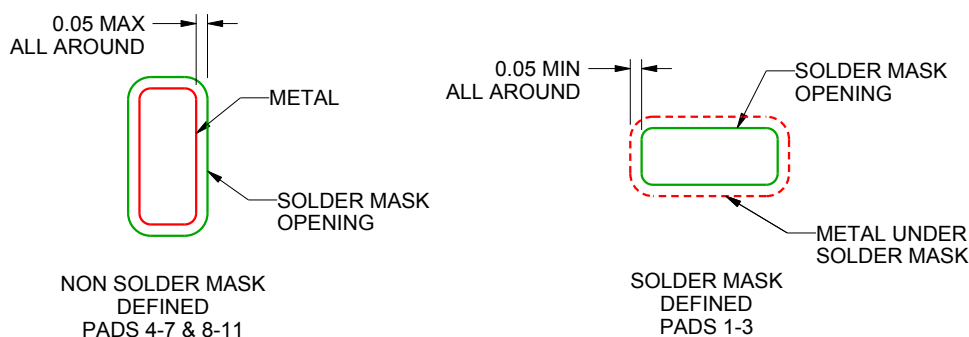
RGX0011A

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE
SCALE:25X



SOLDER MASK DETAILS

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NOTES: (continued)

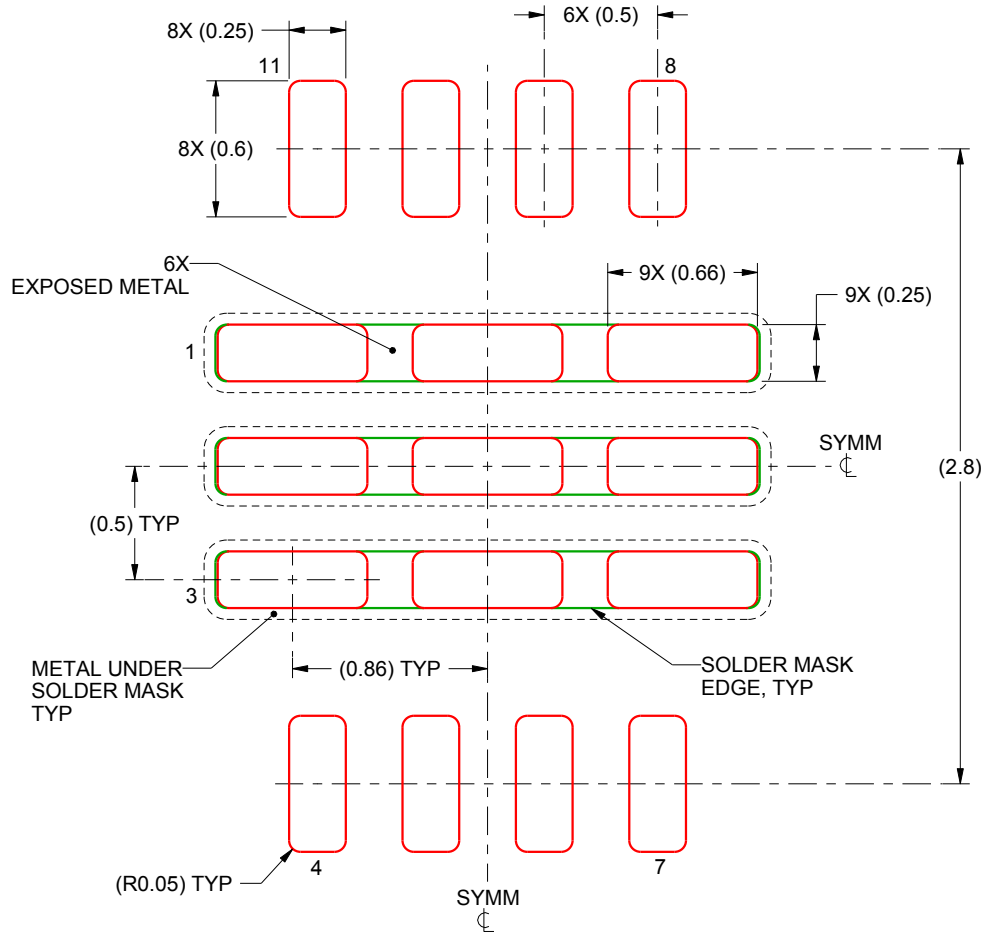
3. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
4. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

RGX0011A

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
FOR PADS 1-3
80% PRINTED SOLDER COVERAGE BY AREA
SCALE:30X

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NOTES: (continued)

5. For alternate stencil design recommendations, see IPC-7525 or board assembly site preference.

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