

**MICROCHIP****PIC18F2525/2620/4525/4620****PIC18F2525/2620/4525/4620 Rev. B4 Silicon Errata**

The PIC18F2525/2620/4525/4620 Rev. B4 parts you have received conform functionally to the Device Data Sheet (DS39626C), except for the anomalies described below. Any Data Sheet Clarification issues related to the PIC18F2525/2620/4525/4620 will be reported in a separate Data Sheet errata. Please check the Microchip web site for any existing issues.

The following silicon errata apply only to PIC18F2525/2620/4525/4620 devices with these Device/Revision IDs:

Part Number	Device ID	Revision ID
PIC18F2525	0000 1100 110	0 0110
PIC18F2620	0000 1100 100	0 0110
PIC18F4525	0000 1100 010	0 0110
PIC18F4620	0000 1100 000	0 0110

The Device IDs (DEVID1 and DEVID2) are located at addresses 3FFFFEh:3FFFFFh in the device's configuration space. They are shown in binary in the format "DEVID2 DEVID1".

1. Module: MSSP

In SPI Slave mode with slave select enabled (SSPM3:0 = 0100), the minimum time between the falling edge of the $\overline{SS}$ pin and the first SCK edge is greater than specified in parameter 70 in Table 26-16. The updated specification is shown in bold in Table 1.

The minimum time between $\overline{SS}$ pin low and an SSPBUF write is also 3 Tcy. If the falling edge of the $\overline{SS}$ pin occurs greater than 3 Tcy before the first SCK edge or loading SSPBUF, the peripheral will function correctly. Also, if SSPBUF is written prior to the $\overline{SS}$ pin going low, the peripheral will function correctly.

Work around

None.

Date Codes that pertain to this issue:

All engineering and production devices.

TABLE 1: EXAMPLE SPI MODE REQUIREMENTS (SLAVE MODE TIMING)

Param No.	Symbol	Characteristic	Min	Max	Units	Conditions
70	TssL2sch, TssL2scl	$\overline{SS}\downarrow$ to SCK $\downarrow$ or SCK $\uparrow$ Input	3 Tcy	—	ns	

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2. Module: MSSP

With MSSP in SPI Master mode, $F_{osc}/64$ or Timer2/2 clock rate, and $CKE = 0$, a write collision may occur if SSPBUF is loaded immediately after the transfer is complete. A delay may be required after the MSSP Interrupt Flag bit, SSPIF, is set or the Buffer Full bit, BF, is set and before writing SSPBUF. If the delay is insufficiently short, a write collision may occur as indicated by the WCOL bit being set.

Work around

Add a software delay of one SCK period after detecting the completed transfer and prior to updating the SSPBUF contents. Verify the WCOL bit is clear after writing SSPBUF. If the WCOL is set, clear the bit in software and rewrite the SSPBUF register.

Date Codes that pertain to this issue:

All engineering and production devices.

3. Module: Enhanced Capture/Compare/PWM (ECCP)

With the ECCP configured for Half-Bridge PWM mode ($CCP1M3:0 = 1110$), the output may be corrupted for particular duty cycle selections. Affected duty cycle values are 0 through 3, and every subsequent increment of 4 (i.e., 7, 11, 15, 19, etc.).

Work around

None.

Date Codes that pertain to this issue:

All engineering and production devices.

4. Module: Enhanced Universal Synchronous Receiver Transmitter (EUSART)

One bit has been added to the BAUDCON register and one bit has been renamed. The added bit is RXDTP and is in the location, $BAUDCON<5>$. The renamed bit is the TXCKP bit ($BAUDCON<4>$), which had been named SCKP.

The TXCKP ($BAUDCON<4>$) and RXDTP ($BAUDCON<5>$) bits enable the Asynchronous mode TX and RX signals to be inverted (polarity reversed). RXDTP has no effect on the Synchronous mode DT signal.

Register 18-3, on page 204, will be changed as shown on page 3.

Work around

None required.

Date Codes that pertain to this issue:

All engineering and production devices.

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REGISTER 18-3: BAUDCON: BAUD RATE CONTROL REGISTER

R/W-0	R-1	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
ABDOVF	RCIDL	RXDTP	TXCKP	BRG16	—	WUE	ABDEN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7 **ABDOVF**: Auto-Baud Acquisition Rollover Status bit
1 = A BRG rollover has occurred during Auto-Baud Rate Detect mode (must be cleared in software)
0 = No BRG rollover has occurred
- bit 6 **RCIDL**: Receive Operation Idle Status bit
1 = Receive operation is Idle
0 = Receive operation is Active
- bit 5 **RXDTP**: Receive Data Polarity Select bit (Asynchronous mode only)
Asynchronous mode:
1 = Receive data (RX) is inverted. Idle state is a low level.
0 = No inversion of receive data (RX). Idle state is a high level.
- bit 4 **TXCKP**: Transmit/Clock Polarity Select bit
Asynchronous mode:
1 = Transmit data (TX) is inverted. Idle state is a low level.
0 = No inversion of transmit data (TX). Idle state is a high level.
Synchronous mode:
1 = Idle state for clock (CK) is a high level
0 = Idle state for clock (CK) is a low level
- bit 3 **BRG16**: 16-bit Baud Rate Register Enable bit
1 = 16-bit Baud Rate Generator – SPBRGH and SPBRG
0 = 8-bit Baud Rate Generator – SPBRG only (Compatible mode); SPBRGH value ignored
- bit 2 **Unimplemented**: Read as '0'
- bit 1 **WUE**: Wake-up Enable bit
Asynchronous mode:
1 = EUSART will continue to sample the RX pin with the interrupt generated on the falling edge; bit cleared in hardware on following rising edge
0 = RX pin is not monitored or rising edge detected
Synchronous mode:
Unused in this mode.
- bit 0 **ABDEN**: Auto-Baud Detect Enable bit
Asynchronous mode:
1 = Enable baud rate measurement on the next character. Requires reception of a Sync field (55h); cleared in hardware upon completion.
0 = Baud rate measurement disabled or completed
Synchronous mode:
Unused in this mode.

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REVISION HISTORY

Rev A Document (07/2006)

First revision of this document. Silicon issues 1-2 (MSSP) and 3 (ECCP).

Rev B Document (04/2007)

Added silicon issue 4 (Enhanced Universal Synchronous Receiver Transmitter – EUSART).

Rev C Document (09/2007)

Modified silicon issue 4 (EUSART).

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