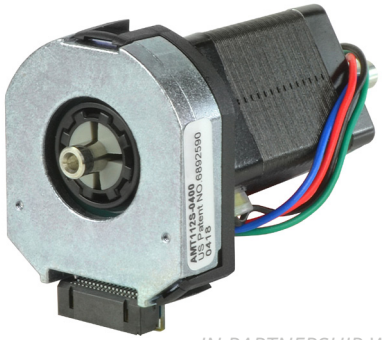
CUI DEVICES

SERIES: NEMA08-AMT112S | **DESCRIPTION:** STEPPER SERVO MOTOR

FEATURES

- CUI Devices AMT112S encoder + LIN Engineering stepper motor
- stepper motor with encoder for closed-loop mode when paired with a controller
- small, compact NEMA 08 frame size
- up to 4 oz-in (0.028 N-m) holding torque
- patented capacitive encoder ASIC technology
- incremental resolutions up to 4096 PPR
- resolutions programmable with AMT Viewpoint™ PC software
- digitally set zero position



IN PARTNERSHIP WITH

LIN ENGINEERING
The Step Motor Specialists
BACKED BY MOONS'

MODEL	step angle	current/ phase	resistance/ phase	inductance /phase	max holding torque	max optimal speed	body length
	(°)	(A)	typ (Ω±10%)	typ (mH±20%)	(oz-in)	(RPS)	max (inch)
NEMA08-13-01D-AMT112S	1.8	0.60	6.5	1.7	3.0	1	1.3
NEMA08-17-01D-AMT112S	1.8	0.80	5.4	1.5	4.0	1	1.7

AMT112S ENCODER

ELECTRICAL

parameter	conditions/description	min	typ	max	units
power supply	VDD	4.5	5	5.5	V
start up time			200		ms
current consumption	with unloaded output		16		mA
output high level		VDD-0.1			V
output low level				0.1	V
output current (per channel)				15	mA
rise/fall time			8		ns

INCREMENTAL CHARACTERISTICS

parameter	conditions/description	min	typ	max	units
channels	CMOS Voltage: A, B, Z				
waveform	CMOS voltage square wave				
phase difference	A leads B for CCW rotation (viewed from front)				
quadrature resolutions[1]	48, 96, 100, 125, 192, 200, 250, 256, 360, 384, 400, 500, 512, 768, 800, 1000, 1024, 1600, 2000, 2048, 2500, 4096				PPR
index[2]	one pulse per 360 degree rotation				
accuracy			0.2		degrees
quadrature duty cycle			50		%

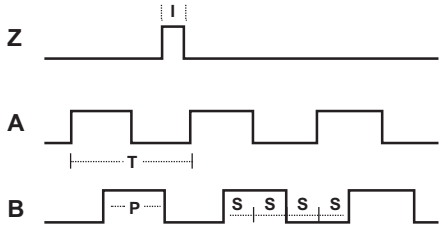
Notes: 1. Resolution programmed with AMT Viewpoint™ PC software. Default resolution set to 400 PPR.
2. Zero position alignment set with AMT One Touch Zero™ module, AMT Viewpoint™ PC software, or serial commands

MECHANICAL

parameter	conditions/description	min	typ	max	units
weight			15.7		g
rotational speed (at each resolution)	48, 96, 100, 125, 192, 200, 250, 256, 384, 400, 500, 512, 800, 1000, 1024, 2048			8000	RPM
	360, 768, 1600, 2000, 4096			4000	RPM
	2500			2500	RPM

ENCODER WAVEFORMS

Figure 1
Quadrature signals with index showing counter-clockwise rotation



The following parameters are defined by the resolution selected for each encoder, where R = resolution.

Parameter	Description	Expression	Units
T	period	360/R	mechanical degrees
P	pulse width	T/2	mechanical degrees
I	index width	P/2	mechanical degrees
S	A/B state width	P/2	mechanical degrees

STEPPER MOTOR

SPECIFICATIONS

parameter	conditions/description	min	typ	max	units
motor frame size	NEMA Size 08				
step angle			1.8		°
rated current/phase	see page 1 for details				
rated voltage			24-48		Vdc
resistance/phase	see page 1 for details				
inductance/phase	see page 1 for details				
connection type	bipolar				
rotor inertia			0.01		$oz\text{-}in^2$
max holding torque	see page 1 for details				
bearing type	ABEC3				
front shaft OD			4		mm
front shaft length			0.59		inch
max optimal speed	see page 1 for details				
max axial load				0.45	lb
radial play	at 1 lb load			0.001	inch
end play	at 2 lbs load			0.003	inch
shaft run out			0.002		inch TIR
dielectric strength			500		V
EMI/EMC	EN 55014-1:2007				

SWITCHING SEQUENCE

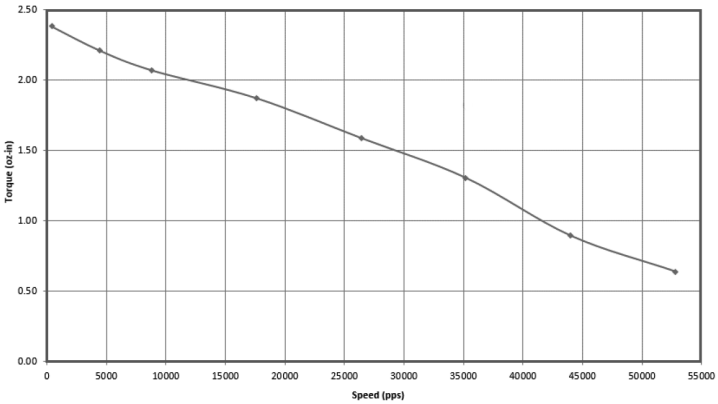
SWITCHING SEQUENCE					
CCW	STEP	A	A	B	B
↓	1	+	-	+	-
	2	+	-	-	+
	3	-	+	-	+
	4	-	+	+	-
	1	+	-	+	-
Motor Rotation Viewed from Front Shaft End					

ENVIRONMENTAL

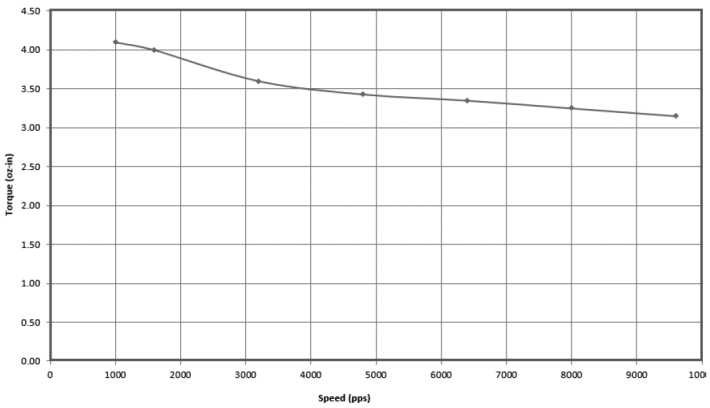
parameter	conditions/description	min	typ	max	units
operating temperature		-20		50	°C
storage temperature		-20		100	°C
humidity	non-condensing			85	%
vibration	10~500 Hz, 5 minute sweep, 2 hours on each XYZ			5	G
shock	3 pulses, 6 ms, 3 on each XYZ			200	G
RoHS	yes				

TORQUE CURVES

CUI Devices P/N NEMA08-13-01D-AMT112S
Lin Engineering P/N WO-208-13-01 (1.8 Step Motor)
24 Vdc, 0.60 Amp/Phase, IB462, 1/2 Stepping

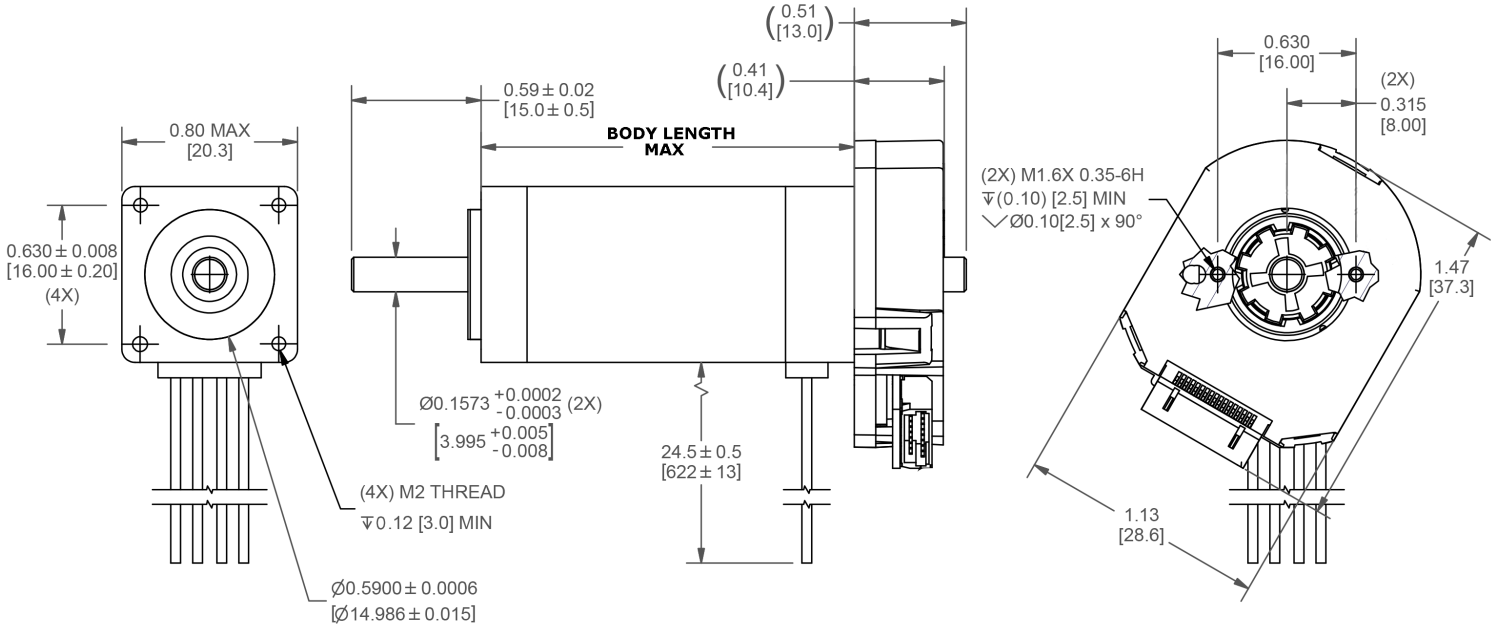


CUI Devices P/N NEMA08-17-01D-AMT112S
Lin Engineering P/N WO-208-17-01 (1.8 Step Motor)
24 Vdc, 0.80 Amp/Phase, IB462, 1/2 Stepping

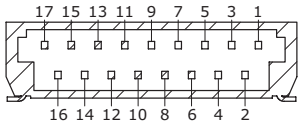


MECHANICAL DRAWING

units: inch [mm]
tolerance:
X.XX ±0.01 [±0.25]
X.XXX ±0.005 [±0.13]
X.XXXX ±0.0005 [±0.013]



MOTOR WIRE CONNECTIONS	
Color	Function
red	A
blue	$\overline{A}$
green	B
black	$\overline{B}$
26 AWG, PVC	



Mating Connector:
JAE FI-W17S

MODEL NO.	BODY LENGTH (inch)	WEIGHT (lb)
NEMA08-13-01D-AMT112S	1.3	0.10
NEMA08-17-01D-AMT112S	1.7	0.15

ENCODER CONNECTIONS	
#	Function
1	TX_ENC+
2	RX_ENC+
3	N/A
4	GND
5	N/A
6	+5 V
7	N/A
8	B+
9	N/A
10	A+
11	N/A
12	Z+
13	N/A
14	MCLRB
15	N/A
16	N/A
17	N/A

REVISION HISTORY

rev.	description	date
1.0	initial release	06/26/2018
1.01	brand update	02/21/2020

The revision history provided is for informational purposes only and is believed to be accurate.

CUI DEVICES

CUI Devices offers a one (1) year limited warranty. Complete warranty information is listed on our website.

CUI Devices reserves the right to make changes to the product at any time without notice. Information provided by CUI Devices is believed to be accurate and reliable. However, no responsibility is assumed by CUI Devices for its use, nor for any infringements of patents or other rights of third parties which may result from its use.

CUI Devices products are not authorized or warranted for use as critical components in equipment that requires an extremely high level of reliability. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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