19-3243; Rev 1; 9/05

EVALUATION KIT AVAILABLE

Step-Up/Step-Down Li+ Battery Charger

MAX1870A

General Description

The MAX1870A step-up/step-down multichemistry battery charger charges with battery voltages above and below the adapter voltage. This highly integrated charger requires a minimum number of external components. The MAX1870A uses a proprietary step-up/step-down control scheme that provides efficient charging. Analog inputs control charge current and voltage, and can be programmed by the host or hardwired.

The MAX1870A accurately charges two to four lithium-ion (Li+) series cells at greater than 4A. A programmable input current limit is included, which avoids overloading the AC adapter when supplying the load and the battery charger simultaneously. This reduces the maximum adapter current, which reduces cost. The MAX1870A provides analog outputs to monitor the current drawn from the AC adapter and charge current. A digital output indicates the presence of an AC adapter. When the adapter is removed, the MAX1870A consumes less than 1µA from the battery.

The MAX1870A is available in a 32-pin thin QFN (5mm x 5mm) package and is specified over the -40°C to +85°C extended temperature range. The MAX1870A evaluation kit (MAX1870AEVKIT) is available to help reduce design time.

Applications

Notebook and Subnotebook Computers

Handheld Terminals

Features

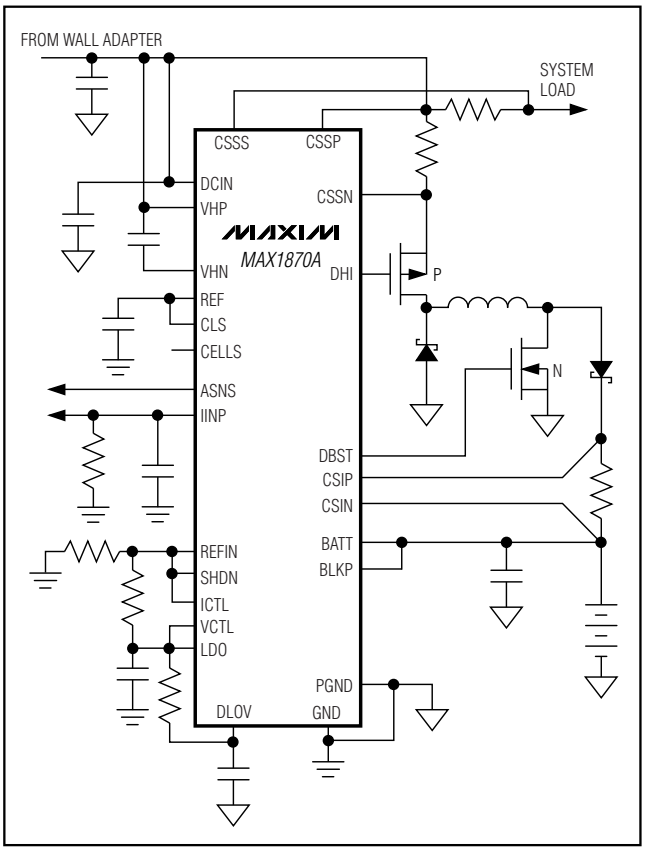
- ♦ Step-Up/Step-Down Control Scheme
- ♦ ±0.5% Charge-Voltage Accuracy
- ♦ ±9% Charge-Current Accuracy
- ♦ ±8% Input Current-Limit Accuracy
- ♦ Programmable Maximum Battery Charge Current
- ♦ Analog Inputs Control Charge Current, Charge Voltage, and Input Current Limit
- ♦ Analog Output Indicates Adapter Current
- ♦ Input Voltage from 8V to 28V
- ♦ Battery Voltage from 0 to 17.6V
- ♦ Charges Li+ or NiCd/NiMH Batteries
- ♦ Tiny 32-Pin Thin QFN (5mm x 5mm) Package

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX1870AETJ	-40°C to +85°C	32 Thin QFN
MAX1870AETJ+	-40°C to +85°C	32 Thin QFN

+Denotes lead-free package.

Typical Operating Circuit



Pin Configuration appears at end of data sheet.

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

Step-Up/Step-Down Li+ Battery Charger

ABSOLUTE MAXIMUM RATINGS

DCIN, CSSP, CSSS, CSSN, VHP, VHN, DHI to GND ..... -0.3V to +30V
VHP, DHI to VHN ..... -0.3V to +6V
BATT, CSIP, CSIN, BLKP to GND ..... -0.3V to +20V
CSIP to CSIN, CSSP to CSSN, CSSP to CSSS, PGND to GND ..... -0.3V to +0.3V
CCI, CCS, CCV, REF, IINP to GND ..... -0.3V to (V_{LDO} + 0.3V)
DBST to GND ..... -0.3V to (V_{DLOV} + 0.3V)
DLOV, VCTL, ICTL, REFIN, CELLS, CLS, LDO, ASNS, $\overline{SHDN}$ to GND ..... -0.3V to +6V
LDO Current 50mA
Continuous Power Dissipation (T_A = +70°C)
32-Pin Thin QFN 5mm x 5mm (derate 21mW/°C above +70°C) 1.7W
Operating Temperature Range
MAX1870AETJ ..... -40°C to +85°C
Storage Temperature Range ..... -60°C to +150°C
Lead Temperature (soldering, 10s) ..... +300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = 0°C to +85°C**, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
CHARGE-VOLTAGE REGULATION					
VCTL Range		0		3.6	V
Battery Regulation Voltage Accuracy	V_{VCTL} = V_{LDO} (2 cells)	-0.5		+0.5	%
	V_{VCTL} = V_{LDO} (3 cells)	-0.5		+0.5	
	V_{VCTL} = V_{LDO} (4 cells)	-0.5		+0.5	
	V_{VCTL} = V_{REFIN} (2 cells)	-0.8		+0.8	
	V_{VCTL} = V_{REFIN} (3 cells)	-0.8		+0.8	
	V_{VCTL} = V_{REFIN} (4 cells)	-0.8		+0.8	
	V_{VCTL} = V_{REFIN} / 20 (2 cells)	-1.2		+1.2	
	V_{VCTL} = V_{REFIN} / 20 (3 cells)	-1.2		+1.2	
	V_{VCTL} = V_{REFIN} / 20 (4 cells)	-1.2		+1.2	
VCTL Default Threshold	VCTL rising	4.0	4.1	4.2	V
VCTL Input Bias Current	0 < V_{VCTL} < V_{REFIN}	-1		+1	µA
	DCIN = 0, V_{REFIN} = V_{VCTL} = 3.6V	-1		+1	
	VCTL = DCIN = 0, V_{REFIN} = 3.6V	-1		+1	
CHARGE-CURRENT REGULATION					
ICTL Range		0		3.6	V
Quick-Charge-Current Accuracy	V_{ICTL} = V_{REFIN}	67	73	79	mV
	V_{ICTL} = V_{REFIN} x 0.8	54	59	64	
	V_{ICTL} = V_{REFIN} x 0.583	39	43	47	
Trickle-Charge-Current Accuracy	V_{ICTL} = V_{REFIN} x 0.0625	3.0	4.5	6.0	mV
BATT/CSIP/CSIN Input Voltage Range		0		19	V
CSIP Input Current	DCIN = 0		0.1	2	µA
	ICTL = 0		0.1	2	
	ICTL = REFIN		350	600	

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = 0°C to +85°C**, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
CSIN Input Current	DCIN = 0			0.1	2	µA
	ICTL = 0			0.1	2	
	ICTL = REFIN			0.1	2	
ICTL Power-Down-Mode Threshold Voltage			REFIN / 100	REFIN / 55	REFIN / 32	V
ICTL Input Bias Current	0 < V_{ICTL} < V_{REFIN}		-1		+1	µA
	ICTL = DCIN = 0, V_{REFIN} = 3.6V		-1		+1	
INPUT-CURRENT REGULATION						
Charger-Input Current-Limit Accuracy (V_{CSSP} - V_{CSSN})	CSSS = CSSP	CLS = REF	97	105	113	mV
		CLS = REF x 0.845	81	88	95	
System-Input Current-Limit Accuracy (V_{CSSP} - V_{CSSS})	CSSN = CSSP	CLS = REF	97	105	113	mV
		CLS = REF x 0.845	81	88	95	
CSSP/CSSS/CSSN Input Voltage Range			8		28	V
CSSP Input Current	V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{DCIN} = 6V		-1		+1	µA
	V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{DCIN} = 8V, 28V			700	1200	
CSSS/CSSN Input Current	V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{DCIN} = 6V		-1		+1	µA
	V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{DCIN} = 8V, 28V		-1		+1	
CLS Input Range			V_{REF} / 2		V_{REF}	V
CLS Input Bias Current	CLS = REF		-1		+1	µA
IINP Transconductance	V_{CSSP} - V_{CSSS} = 102mV, CSSN = CSSP		2.5	2.8	3.1	µA/mV
IINP Output Current	V_{CSSP} - V_{CSSN} = 200mV, V_{IINP} = 0V		350			µA
	V_{CSSP} - V_{CSSS} = 200mV, V_{IINP} = 0V		350			
IINP Output Voltage	V_{CSSP} - V_{CSSN} = 200mV, IINP float		3.5			V
	V_{CSSP} - V_{CSSS} = 200mV, IINP float		3.5			
SUPPLY AND LINEAR REGULATOR						
DCIN Input Voltage Range			8		28	V
DCIN Undervoltage Lockout	DCIN falling		4	6.2		V
	DCIN rising			6.3	7.85	
DCIN Quiescent Current	8.0V < V_{DCIN} < 28V			3.5	6	mA
BATT Input Voltage Range			0		19	V
BATT Input Bias Current	DCIN = 0			0.1	1	µA
	V_{BATT} = 2V to 19V			300	500	
LDO Output Voltage	No load		5.3	5.4	5.5	V
LDO Load Regulation	0 < I_{LDO} < 10mA			70	150	mV
LDO Undervoltage Lockout	V_{DCIN} = 8V, LDO rising		4.00	5.0	5.25	V

Step-Up/Step-Down Li+ Battery Charger

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = 0°C to +85°C**, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
REFERENCE					
REF Output Voltage	I_{REF} = 0µA	4.076	4.096	4.116	V
REF Load Regulation	0 < I_{REF} < 500µA		5	10	mV
REF Undervoltage-Lockout Trip Point	V_{REF} falling		3.1	3.9	V
REFIN Input Range		2.5		3.6	V
REFIN UVLO Rising			1.9	2.2	V
REFIN UVLO Hysteresis			50		mV
REFIN Input Bias Current	V_{DCIN} = 18V		50	100	µA
	DCIN = 0, V_{REFIN} = 3.6V	-1		+1	
SWITCHING REGULATOR					
Cycle-by-Cycle Step-Up Maximum Current-Limit Sense Voltage	V_{DCIN} = 12V, V_{BATT} = 16.8V	135	150	165	mV
Cycle-by-Cycle Step-Down Maximum Current-Limit Sense Voltage	V_{DCIN} = 19V, V_{BATT} = 16.8V	135	150	165	mV
Step-Down On-Time	V_{DCIN} = 18V, V_{BATT} = 16.8V	2.2	2.4	2.6	µs
Minimum Step-Down Off-Time	V_{DCIN} = 18V, V_{BATT} = 16.8V	0.15	0.4	0.50	µs
Step-Up Off-Time	V_{DCIN} = 12V, V_{BATT} = 16.8V	1.6	1.8	2.0	µs
Minimum Step-Up On-Time	V_{DCIN} = 12V, V_{BATT} = 16.8V	0.15	0.3	0.40	µs
MOSFET DRIVERS					
VHP - VHN Output Voltage	8V < V_{VHP} < 28V, no load	4.5	5	5.5	V
VHN Load Regulation	0 < I_{VHN} < 10mA		70	150	mV
DHI On-Resistance High	I_{SOURCE} = 10mA		2	5	Ω
DHI On-Resistance Low	I_{SINK} = 10mA		1	3	Ω
VHP Input Bias Current	DCIN = 0		0.1	1	µA
	V_{DCIN} = 18V		1.3	2	mA
BLKP Input Bias Current	ICTL = 0		0.1	2	µA
	V_{ICTL} = V_{REFIN} = 3.3V		100	400	
DLOV Supply Current	DBST low		5	10	µA
DBST On-Resistance High	I_{SOURCE} = 10mA		2	5	Ω
DBST On-Resistance Low	I_{SINK} = 10mA		1	3	Ω
ERROR AMPLIFIERS					
GMV Amplifier Loop Transconductance	VCTL = REFIN, V_{BATT} = 16.8V	0.05	0.1	0.20	µA/mV
GMI Amplifier Loop Transconductance	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 72mV	1.8	2.4	3.0	µA/mV

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = 0°C to +85°C**, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
GMS Amplifier Loop Transconductance	V_{CLS} = REF, V_{CSSP} - V_{CSSN} = 102mV, V_{CSSP} = V_{CSSS}	1.2	1.7	2.2	µA/mV
	V_{CLS} = REF, V_{CSSP} - V_{CSSS} = 102mV, V_{CSSP} = V_{CSSN}	1.2	1.7	2.2	
CCV Output Current	VCTL = REFIN, V_{BATT} = 15.8V	50			µA
	VCTL = REFIN, V_{BATT} = 17.8V			-50	
CCI Output Current	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 0mV	150			µA
	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 150mV			-150	
CCS Output Current	CLS = REF, V_{CSSP} = V_{CSSN}, V_{CSSP} = V_{CSSS}	100			µA
	CLS = REF, V_{CSSP} - V_{CSSN} = 200mV, V_{CSSP} - V_{CSSS} = 200mV			-100	
CCI/CCS/CCV Clamp Voltage	1.1V < V_{CCV} < 3.5V, 1.1V < V_{CCS} < 3.5V, 1.1V < V_{CCI} < 3.5V	100	300	500	mV
LOGIC LEVELS					
ASNS Output-Voltage Low	V_{IINP} = GND, I_{SINK} = 1mA			0.4	V
ASNS Output-Voltage High	V_{IINP} = 4V, I_{SOURCE} = 1mA	LDO - 0.5			V
ASNS Current Detect	V_{IINP} rising	1.1	1.15	1.2	V
	Hysteresis		50		mV
$\overline{SHDN}$ Input Bias Current	$V_{\overline{SHDN}}$ = 0 to V_{REFIN}	-1		+1	µA
	DCIN = 0, V_{REFIN} = 5V, $V_{\overline{SHDN}}$ = 0 to V_{REFIN}	-1		+1	
$\overline{SHDN}$ Threshold	$\overline{SHDN}$ falling, V_{REFIN} = 2.8V to 3.6V	22	23.5	25	% of REFIN
$\overline{SHDN}$ Hysteresis			1		% of REFIN
CELLS Input Low Voltage				0.75	V
CELLS Float Voltage		40	50	60	% of REFIN
CELLS Input High Voltage		REFIN - 0.75V			V
CELLS Input Bias Current	CELLS = 0 to REFIN	-2		+2	µA

Step-Up/Step-Down Li+ Battery Charger

ELECTRICAL CHARACTERISTICS

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = -40°C to +85°C**.) (Note 1)

PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
CHARGE-VOLTAGE REGULATION						
VCTL Range			0		3.6	V
Battery Regulation Voltage Accuracy	V_{VCTL} = V_{LDO} (2 cells)		-0.8		+0.8	%
	V_{VCTL} = V_{LDO} (3 cells)		-0.8		+0.8	
	V_{VCTL} = V_{LDO} (4 cells)		-0.8		+0.8	
	V_{VCTL} = V_{REFIN} (2 cells)		-1.2		+1.2	
	V_{VCTL} = V_{REFIN} (3 cells)		-1.2		+1.2	
	V_{VCTL} = V_{REFIN} (4 cells)		-1.2		+1.2	
	V_{VCTL} = V_{REFIN} / 20 (2 cells)		-1.4		+1.4	
	V_{VCTL} = V_{REFIN} / 20 (3 cells)		-1.4		+1.4	
	V_{VCTL} = V_{REFIN} / 20 (4 cells)		-1.4		+1.4	
VCTL Default Threshold	VCTL rising		4.0		4.2	V
CHARGE-CURRENT REGULATION						
ICTL Range			0		3.6	V
Quick-Charge-Current Accuracy	V_{ICTL} = V_{REFIN}		66		80	mV
	V_{ICTL} = V_{REFIN} x 0.8		53		65	
	V_{ICTL} = V_{REFIN} x 0.583		38		48	
BATT/CSIP/CSIN Input Voltage Range			0		19	V
CSIP Input Current	ICTL = REFIN				600	µA
ICTL Power-Down-Mode Threshold Voltage			REFIN / 100		REFIN / 32	V
INPUT-CURRENT REGULATION						
Charger-Input Current-Limit Accuracy (V_{CSSP} - V_{CSSN})	CSSS = CSSP	CLS = REF	95		115	mV
		CLS = REF x 0.845	79		97	
System-Input Current-Limit Accuracy (V_{CSSP} - V_{CSSS})	CSSN = CSSP	CLS = REF	95		115	mV
		CLS = REF x 0.845	79		97	
CSSP/CSSS/CSSN Input Voltage Range			8		28	V
CSSP Input Current	V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{DCIN} = 8V, 28V				1200	µA
CLS Input Range			V_{REF} / 2		V_{REF}	V
IINP Transconductance	V_{CSSP} - V_{CSSS} = 102mV, CSSN = CSSP		2.5		3.1	µA/mV
IINP Output Current	V_{CSSP} - V_{CSSN} = 200mV, V_{IINP} = 0V		350			µA
	V_{CSSP} - V_{CSSS} = 200mV, V_{IINP} = 0V		350			
IINP Output Voltage	V_{CSSP} - V_{CSSN} = 200mV, IINP float		3.5			V
	V_{CSSP} - V_{CSSS} = 200mV, IINP float		3.5			

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = -40°C to +85°C**.) (Note 1)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
SUPPLY AND LINEAR REGULATOR					
DCIN Input Voltage Range		8		28	V
DCIN Undervoltage Lockout	DCIN falling	4			V
	DCIN rising			7.85	
DCIN Quiescent Current	8.0V < V_{DCIN} < 28V			6	mA
BATT Input Voltage Range		0		19	V
BATT Input Bias Current	V_{BATT} = 2V to 19V			500	µA
LDO Output Voltage	No load	5.3		5.5	V
LDO Undervoltage Lockout	V_{DCIN} = 8V, LDO rising	4.00		5.25	V
REFERENCE					
REF Output Voltage	I_{REF} = 0µA	4.060		4.132	V
REF Load Regulation	0 < I_{REF} < 500µA			10	mV
REF Undervoltage-Lockout Trip Point	V_{REF} falling			3.9	V
REFIN Input Range		2.5		3.6	V
REFIN UVLO Rising				2.2	V
REFIN Input Bias Current	V_{DCIN} = 18V			100	µA
SWITCHING REGULATOR					
Cycle-by-Cycle Step-Up Maximum Current-Limit Sense Voltage	V_{DCIN} = 12V, V_{BATT} = 16.8V	130		170	mV
Cycle-by-Cycle Step-Down Maximum Current-Limit Sense Voltage	V_{DCIN} = 19V, V_{BATT} = 16.8V	130		170	mV
Step-Down On-Time	V_{DCIN} = 18V, V_{BATT} = 16.8V	2.2		2.6	µs
Minimum Step-Down Off-Time	V_{DCIN} = 18V, V_{BATT} = 16.8V	0.15		0.50	µs
Step-Up Off-Time	V_{DCIN} = 12V, V_{BATT} = 16.8V	1.6		2.0	µs
Minimum Step-Up On-Time	V_{DCIN} = 12V, V_{BATT} = 16.8V	0.15		0.40	µs
MOSFET DRIVERS					
VHP - VHN Output Voltage	8V < V_{VHP} < 28V, no load	4.5		5.5	V
VHN Load Regulation	0 < I_{VHN} < 10mA			150	mV
DHI On-Resistance High	I_{SOURCE} = 10mA			5	Ω
DHI On-Resistance Low	I_{SINK} = 10mA			3	Ω
VHP Input Bias Current	V_{DCIN} = 18V			2	mA
BLKP Input Bias Current	V_{ICTL} = V_{REFIN} = 3.3V			400	µA
DLOV Supply Current	DBST low			10	µA
DBST On-Resistance High	I_{SOURCE} = 10mA			5	Ω
DBST On-Resistance Low	I_{SINK} = 10mA			3	Ω

Step-Up/Step-Down Li+ Battery Charger

ELECTRICAL CHARACTERISTICS (continued)

(Circuit of Figure 2, V_{DCIN} = V_{CSSP} = V_{CSSN} = V_{CSSS} = V_{VHP} = 18V, V_{BATT} = V_{CSIP} = V_{CSIN} = V_{BLKP} = 12V, V_{REFIN} = 3.0V, V_{ICTL} = 0.75 x V_{REFIN}, VCTL = LDO, CELLS = FLOAT, GND = PGND = 0, V_{DLOV} = 5.4V, **T_A = -40°C to +85°C**.) (Note 1)

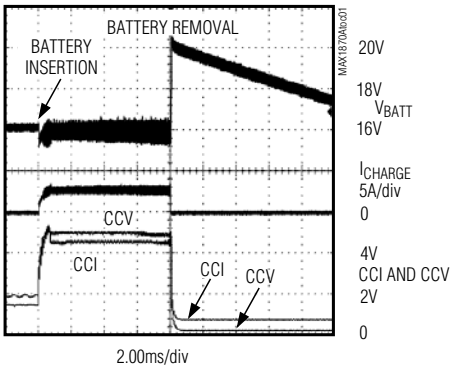
PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
ERROR AMPLIFIERS					
GMV Amplifier Loop Transconductance	VCTL = REFIN, V_{BATT} = 16.8V	0.05		0.20	µA/mV
GMI Amplifier Loop Transconductance	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 72mV	1.8		3.0	µA/mV
GMS Amplifier Loop Transconductance	V_{CLS} = REF, V_{CSSP} - V_{CSSN} = 102mV, V_{CSSP} = V_{CSSS}	1.2		2.2	µA/mV
	V_{CLS} = REF, V_{CSSP} - V_{CSSS} = 102mV, V_{CSSP} = V_{CSSN}	1.2		2.2	
CCV Output Current	VCTL = REFIN, V_{BATT} = 15.8V	50			µA
	VCTL = REFIN, V_{BATT} = 17.8V			-50	
CCI Output Current	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 0mV	150			µA
	ICTL = REFIN, V_{CSIP} - V_{CSIN} = 150mV			-150	
CCS Output Current	CLS = REF, V_{CSSP} = V_{CSSN}, V_{CSSP} = V_{CSSS}	100			µA
	CLS = REF, V_{CSSP} - V_{CSSN} = 200mV, V_{CSSP} - V_{CSSS} = 200mV			-100	
CCI/CCS/CCV Clamp Voltage	1.1V < V_{CCV} < 3.5V, 1.1V < V_{CCS} < 3.5V, 1.1V < V_{CCI} < 3.5V	100		500	mV
LOGIC LEVELS					
ASNS Output-Voltage Low	V_{IINP} = GND, I_{SINK} = 1mA			0.4	V
ASNS Output-Voltage High	V_{IINP} = 4V, I_{SOURCE} = 1mA	LDO - 0.5			V
ASNS Current Detect	V_{IINP} rising	1.1	1.15	1.2	V
$\overline{SHDN}$ Threshold	$\overline{SHDN}$ falling, V_{REFIN} = 2.8V to 3.6V	22		25	% of REFIN
CELLS Input Low Voltage				0.75	V
CELLS Float Voltage		40		60	% of REFIN
CELLS Input High Voltage		REFIN - 0.75V			V

Note 1: Specifications to -40°C are guaranteed by design, not production tested.

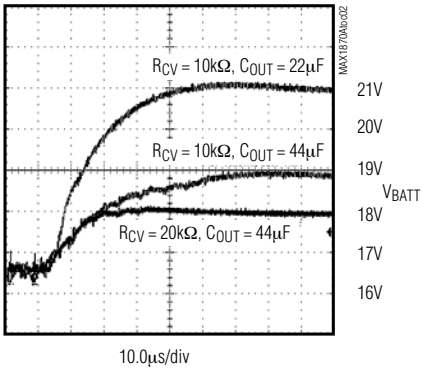
Typical Operating Characteristics

(Circuit of Figure 1, V_{DCIN} = 16V, CELLS = REFIN, V_{CLS} = V_{REF}, V_{ICTL} = V_{REFIN} = 3.3V, T_A = +25°C, unless otherwise noted.)

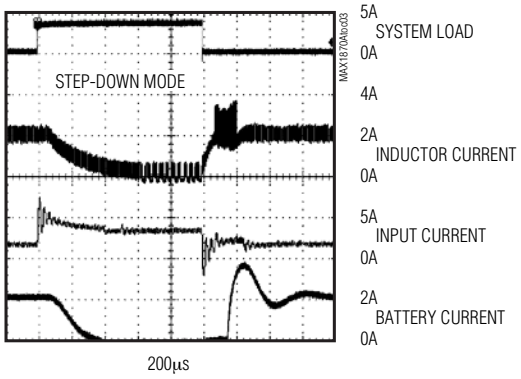
BATTERY INSERTION AND REMOVAL



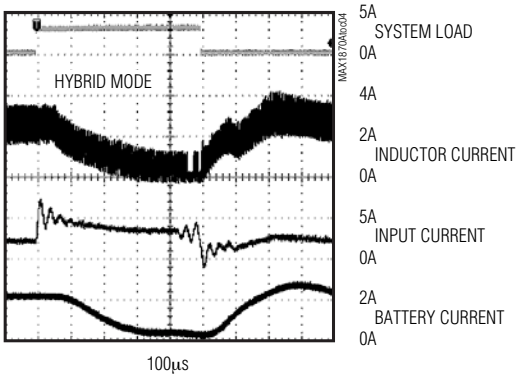
BATTERY-REMOVAL RESPONSE



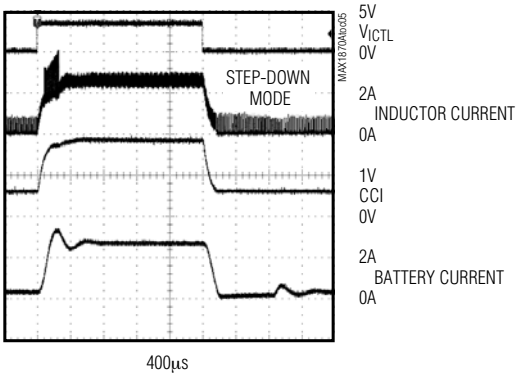
SYSTEM LOAD-TRANSIENT RESPONSE



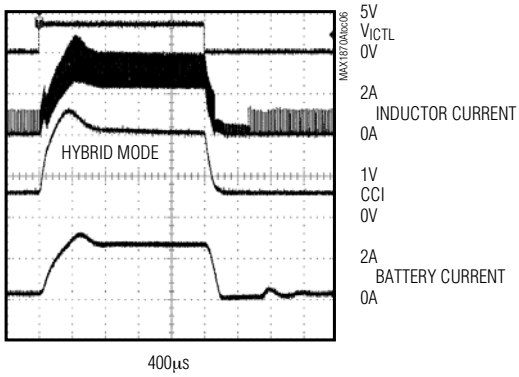
SYSTEM LOAD-TRANSIENT RESPONSE



CHARGE-CURRENT STEP RESPONSE



CHARGE-CURRENT STEP RESPONSE

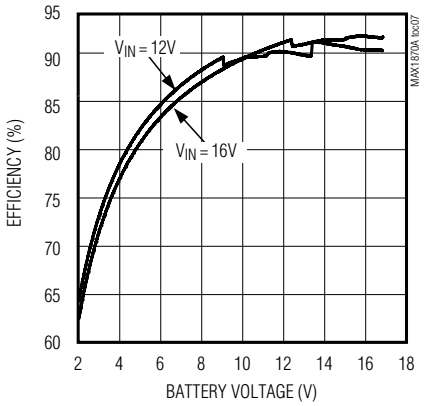


Step-Up/Step-Down Li+ Battery Charger

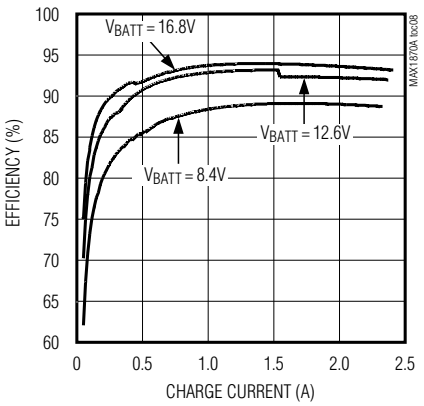
Typical Operating Characteristics (continued)

(Circuit of Figure 1, V_{DCIN} = 16V, CELLS = REFIN, V_{CLS} = V_{REF}, V_{ICTL} = V_{REFIN} = 3.3V, T_A = +25°C, unless otherwise noted.)

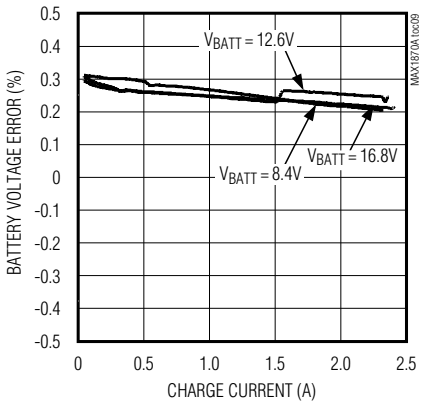
EFFICIENCY vs. BATTERY VOLTAGE



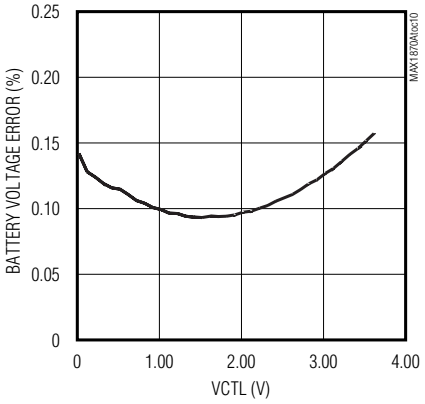
EFFICIENCY vs. CHARGE CURRENT



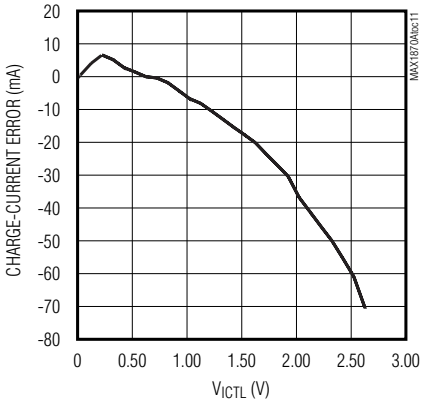
BATTERY VOLTAGE ERROR IN CV MODE



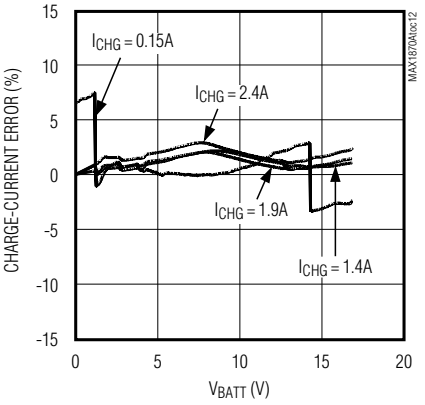
BATTERY VOLTAGE ERROR vs. VCTL



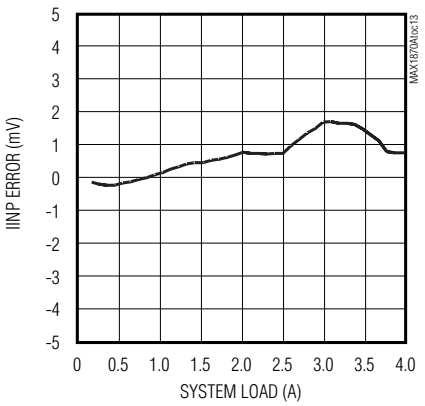
CHARGE-CURRENT ERROR vs. ICTL



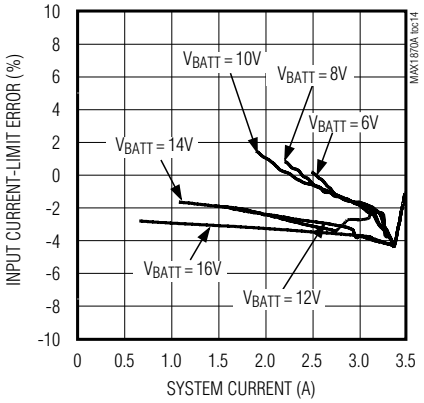
CHARGE-CURRENT ERROR vs. BATTERY VOLTAGE



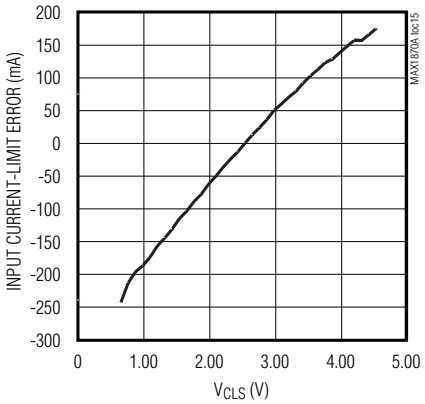
IINP ERROR vs. SYSTEM LOAD



INPUT CURRENT-LIMIT ERROR vs. SYSTEM CURRENT



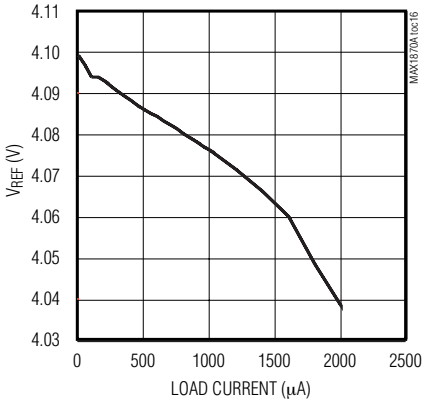
INPUT CURRENT-LIMIT ERROR vs. CLS



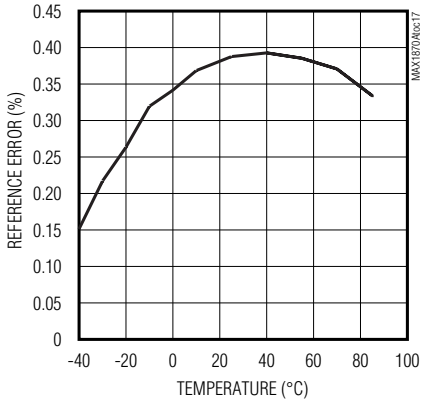
Typical Operating Characteristics (continued)

(Circuit of Figure 1, V_{DCIN} = 16V, CELLS = REFIN, V_{CLS} = V_{REF}, V_{ICTL} = V_{REFIN} = 3.3V, T_A = +25°C, unless otherwise noted.)

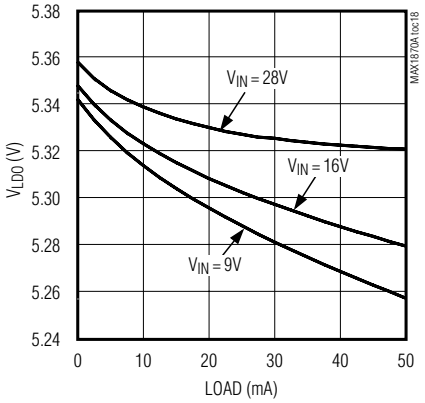
REF LOAD REGULATION



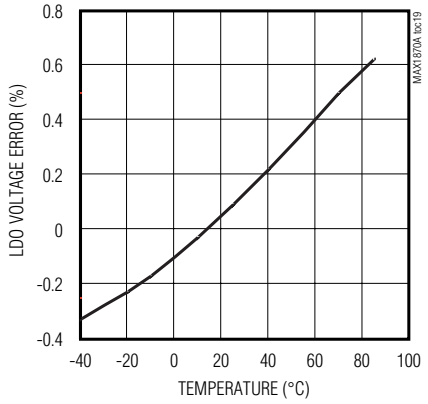
REFERENCE ERROR vs. TEMPERATURE



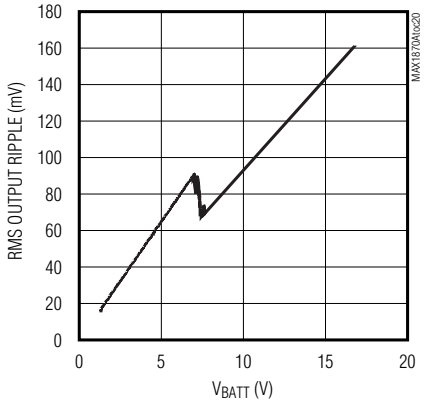
LDO LOAD REGULATION



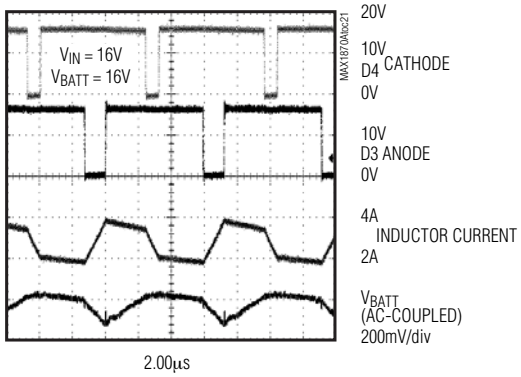
LDO vs. TEMPERATURE



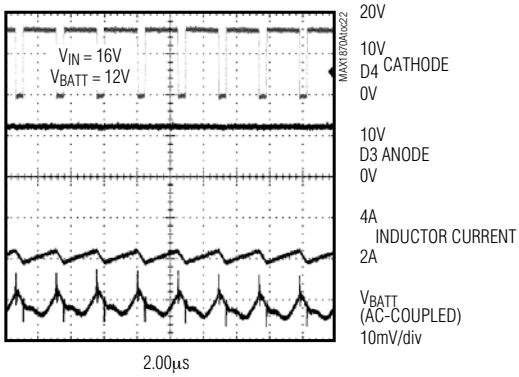
OUTPUT VOLTAGE RIPPLE vs. BATTERY VOLTAGE



STEP-UP/STEP-DOWN SWITCHING WAVEFORM



STEP-DOWN SWITCHING WAVEFORM

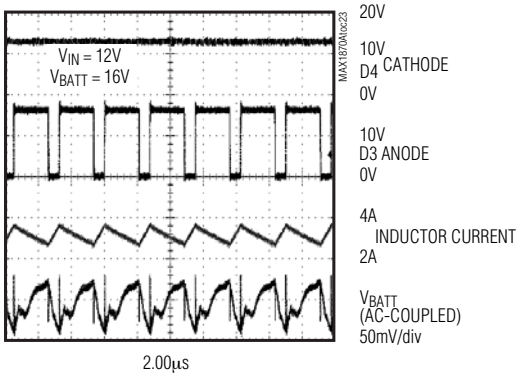


Step-Up/Step-Down Li+ Battery Charger

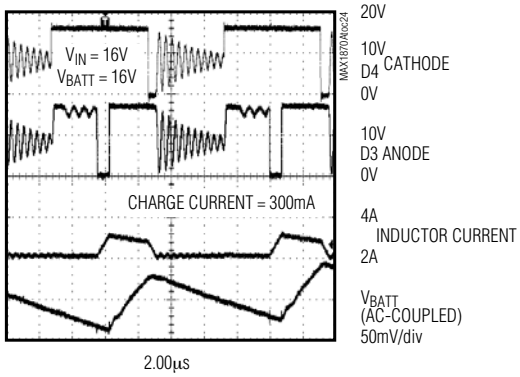
Typical Operating Characteristics (continued)

(Circuit of Figure 1, V_{DCIN} = 16V, CELLS = REFIN, V_{CLS} = V_{REF}, V_{ICTL} = V_{REFIN} = 3.3V, T_A = +25°C, unless otherwise noted.)

STEP-UP SWITCHING WAVEFORM



STEP-UP/STEP-DOWN LIGHT LOAD



Pin Description

PIN	NAME	FUNCTION
1	LDO	Device Power Supply. Output of the 5.4V linear regulator supplied from DCIN. Bypass LDO to GND with a 1µF or greater ceramic capacitor.
2	REF	4.096V Voltage Reference. Bypass REF to GND with a 1µF or greater ceramic capacitor.
3	CLS	Source Current-Limit Input. Voltage input for setting the current limit of the input source. See the *Setting the Input Current Limit* section.
4, 8	GND	Analog Ground
5	CCV	Voltage Regulation Loop Compensation Point. Connect a 10kΩ resistor in series with a 0.01µF capacitor to GND.
6	CCI	Charge-Current Regulation Loop Compensation Point. Connect a 0.01µF capacitor to GND.
7	CCS	Input-Current Regulation Loop Compensation Point. Connect a 0.01µF capacitor to GND.
9	REFIN	Reference Input. ICTL and VCTL are ratiometric with respect to REFIN for increased accuracy.
10	ASNS	Adapter Sense Output. Logic output is high when input current is greater than 1.5A (using 30mΩ sense resistors and a 10kΩ resistor from IINP to GND).
11	VCTL	Charge-Voltage Control Input. Drive VCTL from 0 to V_{REFIN} to adjust the charge voltage from 4V to 4.4V per cell. See the *Setting the Charge Voltage* section.

Pin Description (continued)

PIN	NAME	FUNCTION
12	ICTL	Charge-Current Control Input. Drive ICTL from V_{REFIN} / 32 to V_{REFIN} to adjust the charge current. See the *Setting the Charge Current* section. Drive ICTL to GND to disable charging.
13	CELLS	Cell-Count Selection Input. Connect CELLS to GND for two Li+ cells. Float CELLS for three Li+ cells, or connect CELLS to REFIN for four Li+ cells.
14	IINP	Input-Current Monitor Output. IINP is a replica of the input current sensed by the MAX1870. It represents the sum of the current consumed by the charger and the current consumed by the system. IINP has a transconductance of 2.8µA/mV.
15	$\overline{SHDN}$	Shutdown Comparator Input. Pull $\overline{SHDN}$ low to stop charging. Optionally connect a thermistor to stop charging when the battery temperature is too hot.
16	BATT	Battery-Voltage Feedback Input
17	CSIN	Charge Current-Sense Negative Input
18	CSIP	Charge Current-Sense Positive Input. Connect a current-sense resistor from CSIP to CSIN. Connect a 2.2µF capacitor from CSIP to GND.
19	BLKP	Power Connection for Current-Sense Amplifier. Connect BLKP to BATT.
20, 21	I.C.	Internally Connected. Do not connect this pin.
22	DBST	Step-Up Power MOSFET (NMOS) Gate-Driver Output
23	PGND	Power Ground
24	I.C.	Internally Connected. Do not connect this pin.
25	DLOV	Low-Side Driver Supply. Bypass DLOV with a 1µF capacitor to GND.
26	VHN	Power Connection for the High-Side MOSFET Driver. Bypass VHP to VHN with a 1µF or greater ceramic capacitor.
27	DHI	High-Side Power MOSFET (PMOS) Driver Output. Connect to the gate of the high-side step-down MOSFET.
28	VHP	Power Connection for the High-Side MOSFET Driver. Bypass VHP to VHN with a 1µF or greater ceramic capacitor.
29	CSSN	Negative Terminal for Current-Sense Resistor for Charger Current. Connect a 2.2µF capacitor from CSSN to GND.
30	CSSS	Negative Terminal for Current-Sense Resistor for System Load Current
31	CSSP	Positive Terminal for Input Current-Sense Resistors. Connect a current-sense resistor from CSSP to CSSN. Connect an equivalent sense resistor from CSSP to CSSS.
32	DCIN	DC Supply Voltage Input. Bypass DCIN with a 1µF or greater ceramic capacitor to power ground.
Paddle		Paddle. Connect to GND.

Step-Up/Step-Down Li+ Battery Charger

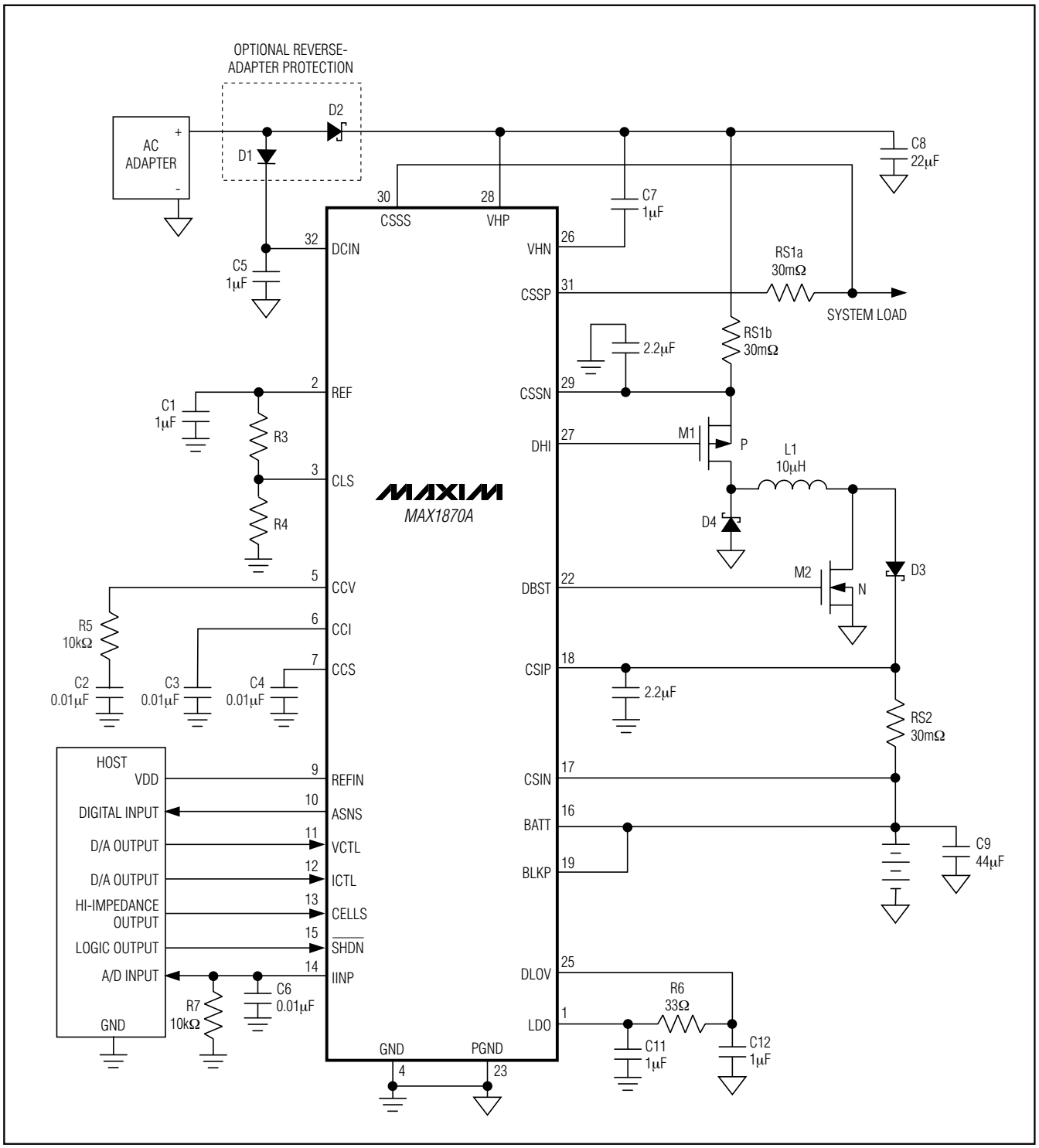


Figure 1. µC-Controlled Typical Application Circuit

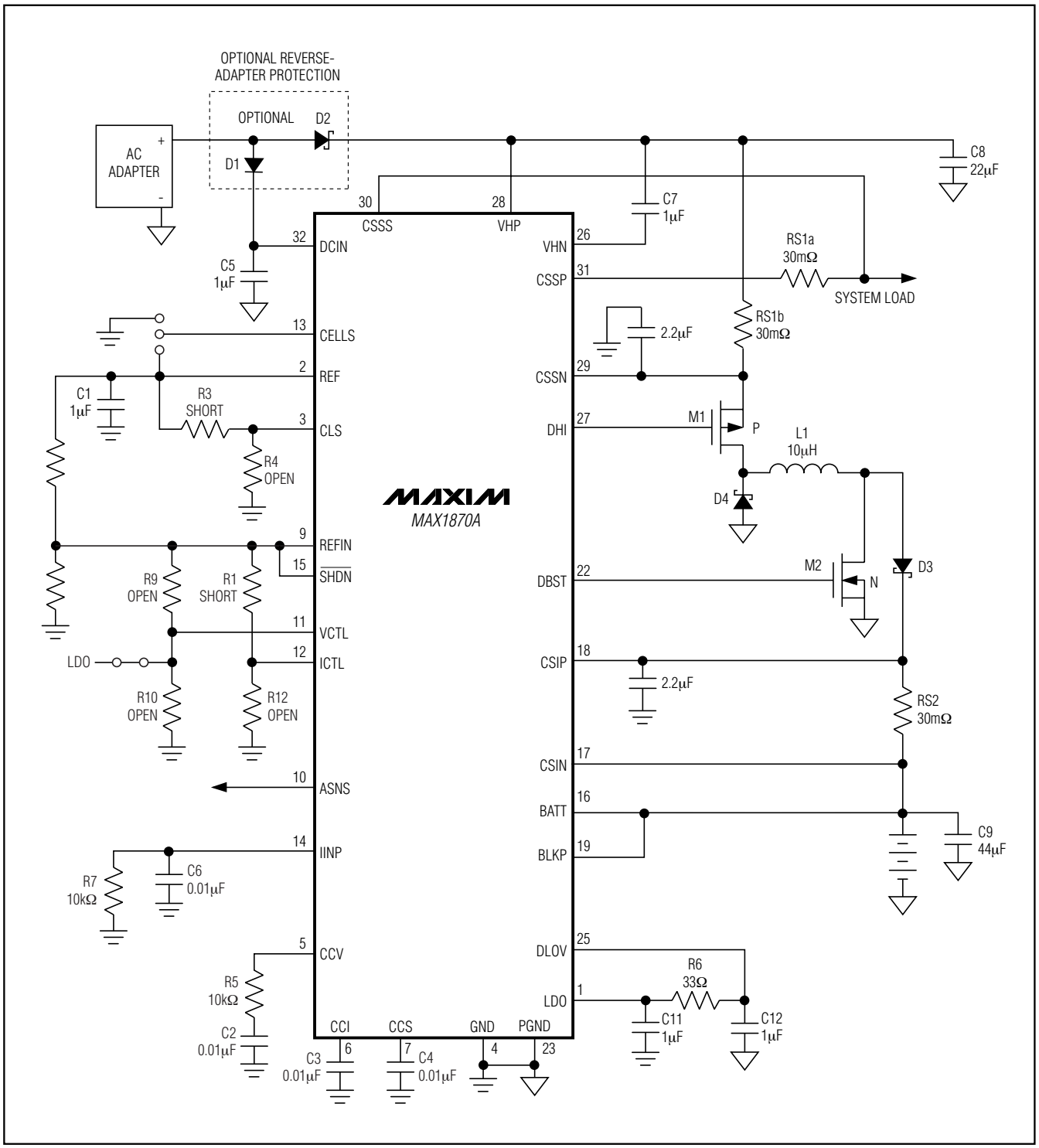


Figure 2. Stand-Alone Typical Application Circuit

Step-Up/Step-Down Li+ Battery Charger

Detailed Description

The MAX1870A includes all of the functions necessary to charge Li+, NiMH, and NiCd batteries. A high-efficiency H-bridge topology DC-DC converter controls charge voltage and current. A proprietary control scheme offers improved efficiency and smaller inductor size compared to conventional H-bridge controllers and operates from input voltages above and below the battery voltage. The MAX1870A includes analog control inputs to limit the AC adapter current, charge current, and battery voltage. An analog output (IINP) delivers a current proportional to the source current. The *Typical Application Circuit* shown in Figure 1 uses a microcontroller (µC) to control the charge current or voltage, while Figure 2 shows a typical application with the charge voltage and current fixed to specific values for the application. The voltage at ICTL and the value of RS2 set the charge current. The voltage at VCTL and the CELLS inputs set the battery regulation voltage for the charger. The voltage at CLS and the value of R3 and R4 set the source current limit.

The MAX1870A features a voltage-regulation loop (CCV) and two current-regulation loops (CCI and CCS). CCV is the compensation point for the battery voltage regulation loop. CCI and CCS are the compensation points for the battery charge current and supply current loops, respectively. The MAX1870A regulates the adapter current by reducing battery charge current according to system load demands.

Setting the Charge Voltage

The MAX1870A provides high-accuracy regulation of the charge voltage. Apply a voltage to VCTL to adjust the battery-cell voltage limit. Set VCTL to a voltage between 0 and V_{REFIN} for a 10% adjustment of the battery cell voltage, or connect VCTL to LDO for a default setting of 4.2V per cell. The limited adjustment range reduces the sensitivity of the charge voltage to external resistor tolerances. The overall accuracy of the charge voltage is better than ±1% when using ±1% resistors to divide down the reference to establish VCTL. The per-cell battery-termination voltage is a function of the battery chemistry and construction. Consult the battery manufacturer to determine this voltage. Calculate battery voltage using the following equation:

$$V_{BATT} = N_{CELLS} \times \left(4V + 0.4V \times \frac{V_{VCTL}}{V_{REFIN}}\right)$$

Table 1. Cell-Count Programming Table

CELLS	CELL COUNT
GND	2
Float	3
REFIN	4

where N_{CELLS} is the cell count selected by CELLS. VCTL is ratiometric with respect to REFIN to improve accuracy when using resistive voltage-dividers. Connect CELLS as shown in Table 1 to charge two, three, or four cells. The cell count can either be hardwired or software controlled. The internal error amplifier (GMV) maintains voltage regulation (see Figure 3 for the *Functional Diagram*). Connect a 10kΩ resistor in series with a 0.01µF capacitor from CCV to GND to compensate the battery voltage loop. See the *Voltage Loop Compensation* section for more information.

Setting the Charge Current

Set the maximum charge current using ICTL and the current-sense resistor RS2 connected between CSIP and CSIN. The current threshold is set by the ratio of V_{ICTL} / V_{REFIN}. Use the following equation to program the battery charge current:

$$I_{CHG} = \frac{V_{CSIT}}{R_{S2}} \times \frac{V_{ICTL}}{V_{REFIN}}$$

where V_{CSIT} is the full-scale charge current-sense threshold, 73mV (typ). The input range for ICTL is V_{REFIN} / 32 to V_{REFIN}. To shut down the MAX1870A, force ICTL below V_{REFIN} / 100.

The internal error amplifier (GMI) maintains charge-current regulation (see Figure 3 for the *Functional Diagram*). Connect a 0.01µF capacitor from CCI to GND to compensate the charge-current loop. See the *Charge-Current Loop Compensation* section for more information.

Setting the Input Current Limit

The total input current, from a wall adapter or other DC source, is a function of the system supply current and the battery charge current. The MAX1870A limits the wall adapter current by reducing the charge current when the input current exceeds the input current-limit set point. As the system supply current rises, the available charge current decreases linearly to zero in proportion to the system current. After the charge current has fallen to zero, the MAX1870A cannot further limit the wall adapter current if the system current continues to increase.

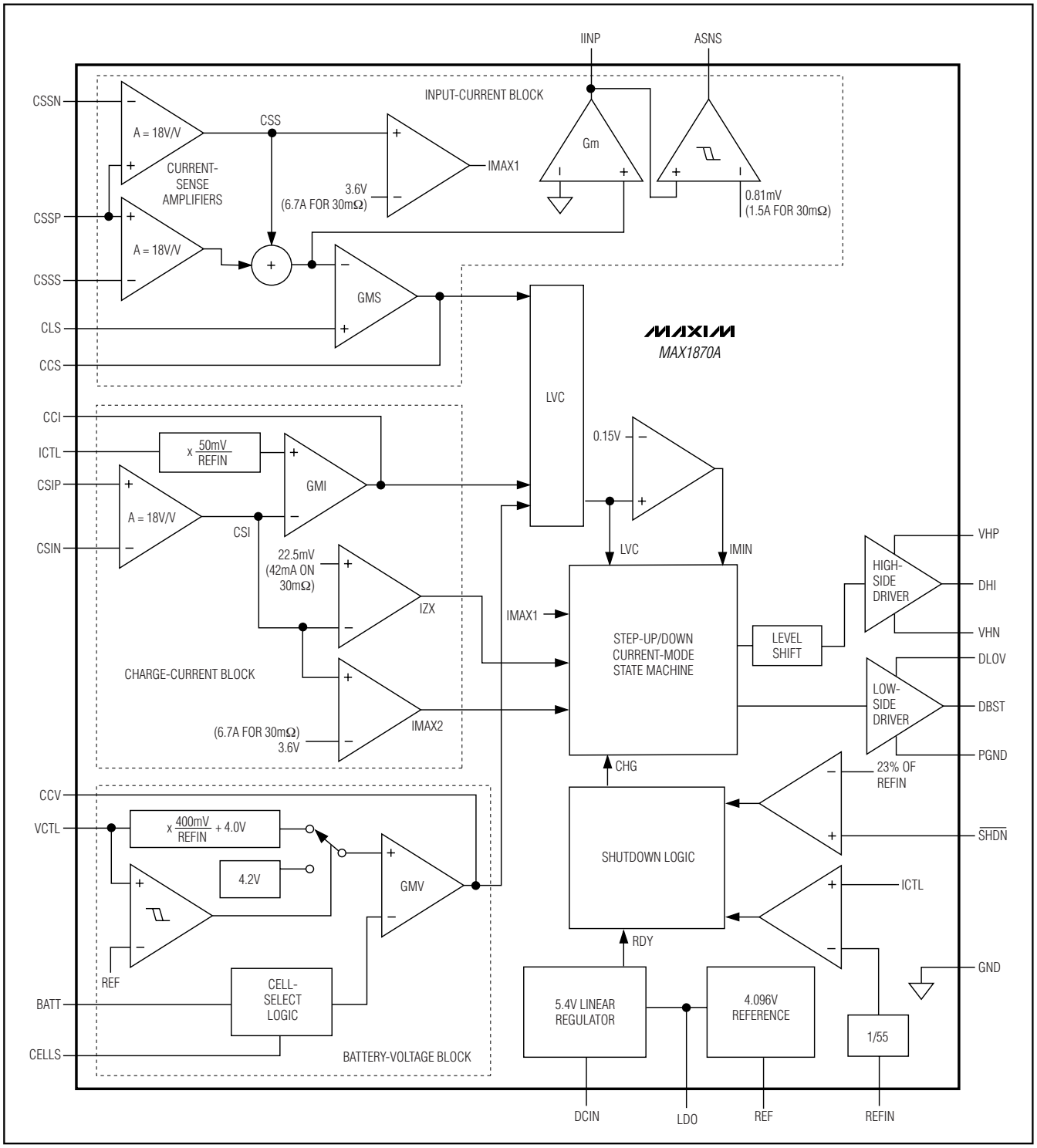


Figure 3. Functional Diagram

Step-Up/Step-Down Li+ Battery Charger

The input source current is the sum of the MAX1870A quiescent current, the charger input current, and the system load current. The MAX1870A's 6mA maximum quiescent current is minimal compared to the charge and load currents. The actual wall adapter current is determined as follows:

$$I_{ADAPTER} = I_{SYS_LOAD} + \frac{I_{CHARGE} \times V_{BATT}}{V_{IN} \times \eta}$$

where η is the efficiency of the DC-DC converter (85% to 95% typ), I_{SYS_LOAD} is the system load current, $I_{ADAPTER}$ is the adapter current, and I_{CHARGE} is the charge current.

By controlling the input current, the current requirements of the AC wall adapter are reduced, minimizing system size and cost. Since charge current is reduced to control input current, priority is given to system loads.

An internal amplifier compares the sum of (V_{CSSP} - V_{CSSN}) and (V_{CSSP} - V_{CSSS}) to a scaled voltage set by the CLS input. Drive V_{CLS} directly or set with a resistive voltage-divider between REF and GND. Connect CLS to REF for the maximum input current limit of 105mV. Sense resistors RS1a and RS1b set the maximum-allowable wall adapter current. Use the same values for RS1a, RS1b, and RS2. Calculate the maximum wall adapter current as follows:

$$I_{ADAPTER_MAX} = \frac{V_{CLS}}{V_{REF}} \times \frac{V_{CSST}}{RS1_}$$

where V_{CSST} is the full-scale source current-sense voltage threshold, and is 105mV (typ). The internal error amplifier (GMS) maintains input-current regulation (see Figure 3 for the *Functional Diagram*). Typically, connect a 0.01µF capacitor from CCS to GND to compensate the source current loop (GMS). See the *Charge-Current and Wall-Adapter-Current Loop Compensation* for more information.

Input Current Measurement

The MAX1870A includes an input-current monitor output, IINP. IINP is a scaled-down replica of the system load current plus the input-referred charge current. The output voltage range for IINP is 0 to 3.5V. The voltage of IINP is proportional to the output current by the following equation:

$$V_{IINP} = I_{ADAPTER} \times RS1_ \times G_{IINP} \times R7$$

where $I_{ADAPTER}$ is the DC current supplied by the AC adapter, G_{IINP} is the transconductance of IINP (2.8µA/mV typ), and R7 is the resistor connected between IINP and ground.

In the *Typical Application Circuit*, the duty cycle and AC load current affect the accuracy of V_{IINP} (see the *Typical Operating Characteristics*).

LDO Regulator

LDO provides a 5.4V supply derived from DCIN. The low-side MOSFET driver is powered by DLOV, which must be connected to LDO as shown in Figure 1. LDO also supplies the 4.096V reference (REF) and most of the internal control circuitry. Bypass LDO to GND with a 1µF or greater ceramic capacitor. Bypass DLOV to PGND with a 1µF or greater ceramic capacitor.

AC Adapter Detection

The MAX1870A includes a logic output, ASNS, which indicates AC adapter presence. When the system load draws more than 1.5A (for 30mΩ sense resistors and R7 is 10kΩ), the ASNS logic output pulls high.

Shutdown

When the AC adapter is removed, the MAX1870A shuts down to a low-power state, and typically consumes less than 1µA from the battery through the combined load of the CSIP, CSIN, BLKP, and BATT inputs. The charger enters this low-power state when DCIN falls below the undervoltage-lockout (UVLO) threshold of 7.5V.

Alternatively, drive $\overline{SHDN}$ below 23.5% of V_{REFIN} or drive ICTL below V_{REFIN} / 100 to inhibit charge. This suspends switching and pulls CCI, CCS, and CCV to ground. The LDO, input current monitor, and control logic all remain active in this state.

Step-Up/Step-Down DC-DC Controller

The MAX1870A is a step-up/step-down DC-DC controller. The MAX1870A controls a low-side n-channel MOSFET and a high-side p-channel MOSFET to a constant output voltage with input voltage variation above, near, and below the output. The MAX1870A implements a control scheme that delivers higher efficiency with smaller components and less output ripple when compared with other step-up/step-down control algorithms. This occurs because the MAX1870A operates with lower inductor currents, as shown in Figure 4.

The MAX1870A proprietary algorithm offers the following benefits:

- Inductor current requirements are minimized.
- Low inductor-saturation current requirements allow the use of physically smaller inductors.
- Low inductor current improves efficiency by reducing I^2R losses in the MOSFETs, inductor, and sense resistors.

• Continuous output current for V_{IN} > 1.4 x V_{OUT} reduces output ripple.

The MAX1870A uses the state machine shown in Figure 5. The controller switches between the states A, B, and C, depending on V_{IN} and V_{BATT}. State D provides PFM operation during light loads. Under moderate and heavy loads the MAX1870A operates in PWM.

Step-Down Operation (V_{IN} > 1.4 x V_{BATT})

During medium and heavy loads when V_{IN} > 1.4 x V_{BATT}, the MAX1870A alternates between state A and state B, keeping MOSFET M2 off (Figure 5). Figure 6 shows the inductor current in step-down operation. During this mode, the MAX1870A regulates the step-down off-time. Initially, DHI switches M1 off (state A) and the inductor current ramps down with a dI/dt of V_{BATT} / L until a target current is reached (determined by the error integrator). After the target current is reached, DHI switches M1 on (state B), and the inductor current ramps up with a dI/dt of (V_{IN} - V_{BATT}) / L. M1 remains on until a step-down on-time timer expires. This on-time is calculated based on the input and output voltage to maintain pseudo-fixed-frequency 400kHz operation. At the end of state B, another step-down off-time (state A) is initiated and the cycle repeats. The off-time is valley regulated according to the error signal. The error signal is set by the charge current or source current if either is at its limit, or the battery voltage if both charge current and source current are below their respective current limits.

During light loads, when the inductor current falls to zero during state A, the controller switches to state D to reduce power consumption and avoid shuttling current in and out of the output.

Step-Up Operation (V_{IN} < 0.9 x V_{BATT})

When V_{IN} < 0.9 x V_{BATT}, the MAX1870A alternates between state B and state C, keeping MOSFET M1 on. In this mode, the controller looks like a simple step-up controller. Figure 7 shows the inductor current in step-

Table 2. MAX1870A H-Bridge Controller Advantages

MAX1870A H-BRIDGE CONTROLLER	TRADITIONAL H-BRIDGE CONTROLLER
• Only 1 MOSFET switched per cycle • Continuous output current in step-down mode	• 2 MOSFETs switched per cycle • Always discontinuous output current (requires higher inductor currents)

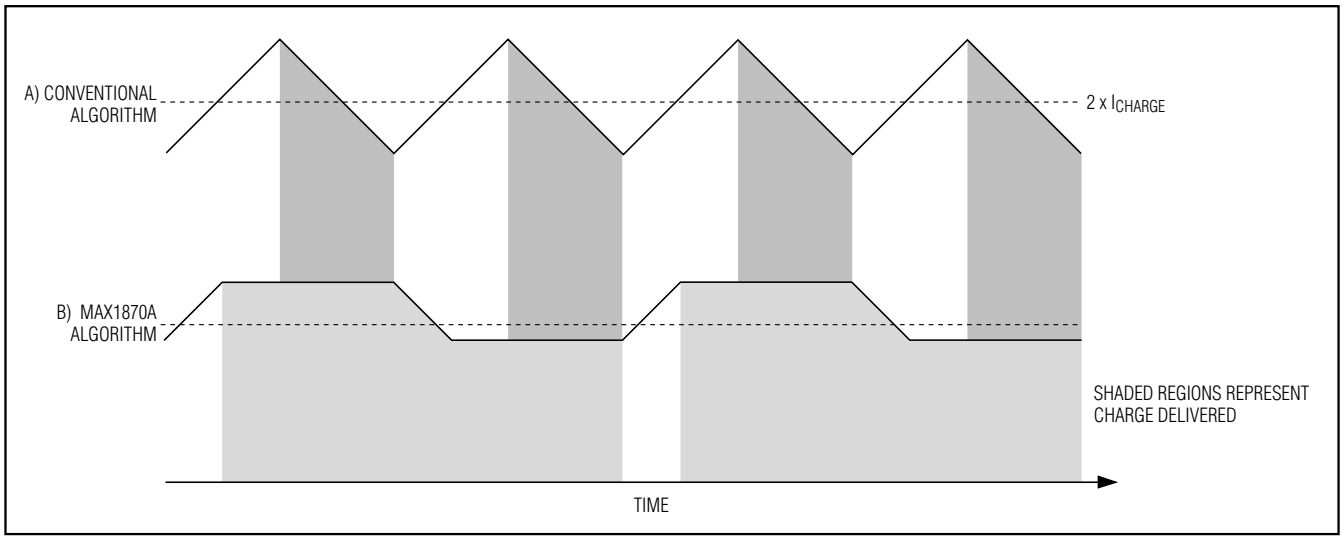


Figure 4. Inductor Current for V_{IN} = V_{BATT}

Step-Up/Step-Down Li+ Battery Charger

up operation. During this mode, the MAX1870A regulates the step-up on-time. Initially DBST switches M2 on (state C) and the inductor current ramps up with a dI/dt of V_{IN} / L. After the inductor current crosses the target current (set by the error integrators), DBST switches M2 off (state B) and the inductor current ramps down with a dI/dt of (V_{BATT} - V_{IN}) / L. M2 remains off until a step-up off-time timer expires. This off-time is calculated based on the input and output voltage to maintain 400kHz pseudo-fixed-frequency operation. The step-up on-time is regulated by the error signal, set according to the charge current or source current if either is at its limit, or the battery voltage if both charge current and source current are below their respective current limits.

Step-Up/Step-Down Operation (0.9 x V_{BATT} < V_{IN} < 1.4 x V_{BATT})

The MAX1870A features a step-up/step-down mode that eliminates dropout. Figure 8 shows the inductor current in step-up/step-down operation. When V_{IN} is within 10% of V_{BATT}, the MAX1870A alternates through states A, B, and C, following the order A, B, C, B, A, B, C, etc., with the majority of the time spent in state B. Since more time is spent in state B, the inductor ripple current is reduced, improving efficiency.

The time in state C is peak-current regulated, and the remaining time is spent in state B (Figure 8A). During this operating mode, the average inductor current is approximately 20% higher than the load current.

The time in state A is valley current and the remaining time is spent in state B (Figure 8B). During this mode, the average inductor current is approximately 10% higher than the load current.

Alternative algorithms require inductor currents twice as high, resulting in four times larger I^2R losses and inductors typically four times larger in volume.

IMIN, IMAX, CCMP, and ZCMP

The MAX1870A state machine utilizes five comparators to decide which state to be in and when to switch states (Figure 3). The MAX1870A generates an error

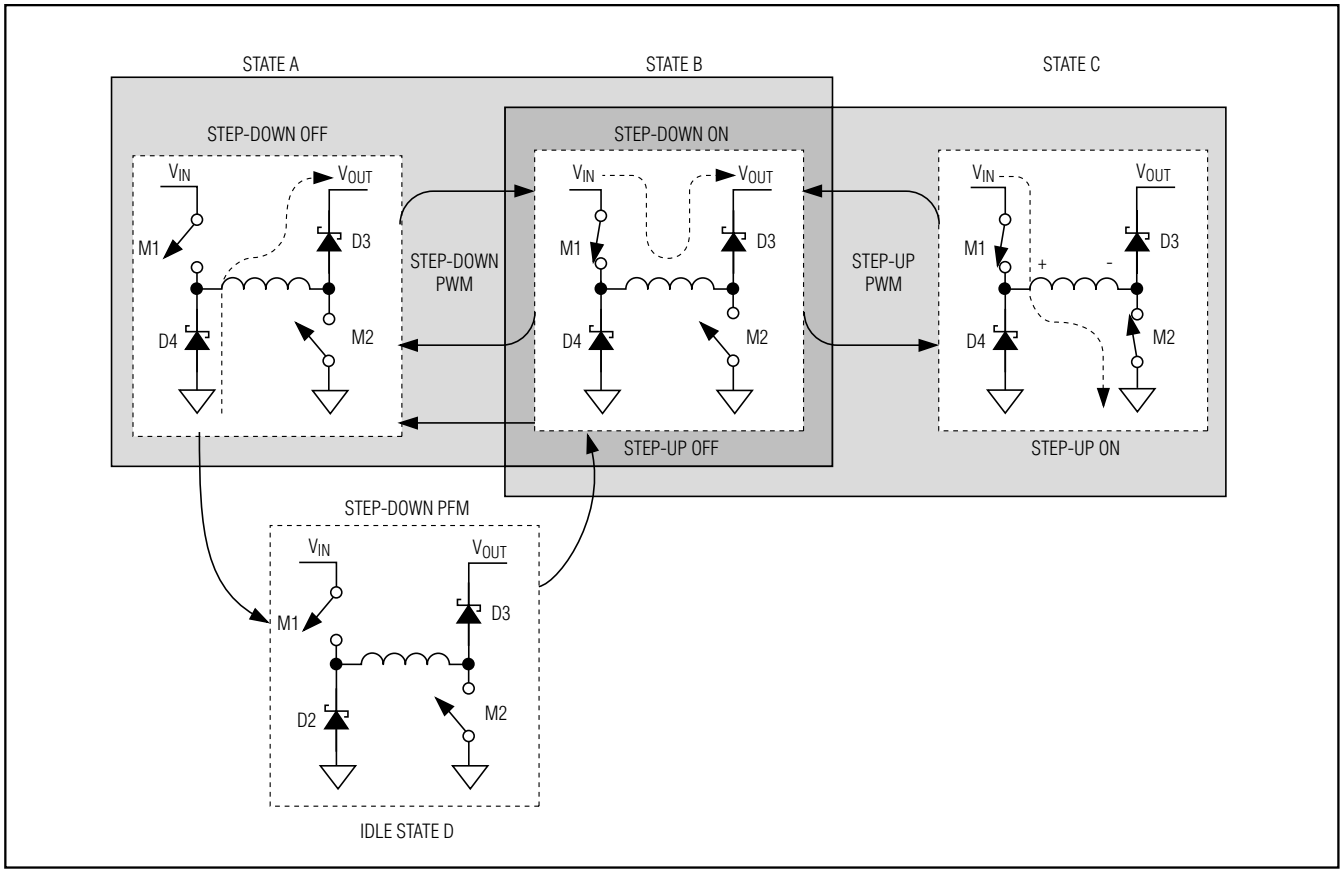


Figure 5. MAX1870A State Machine

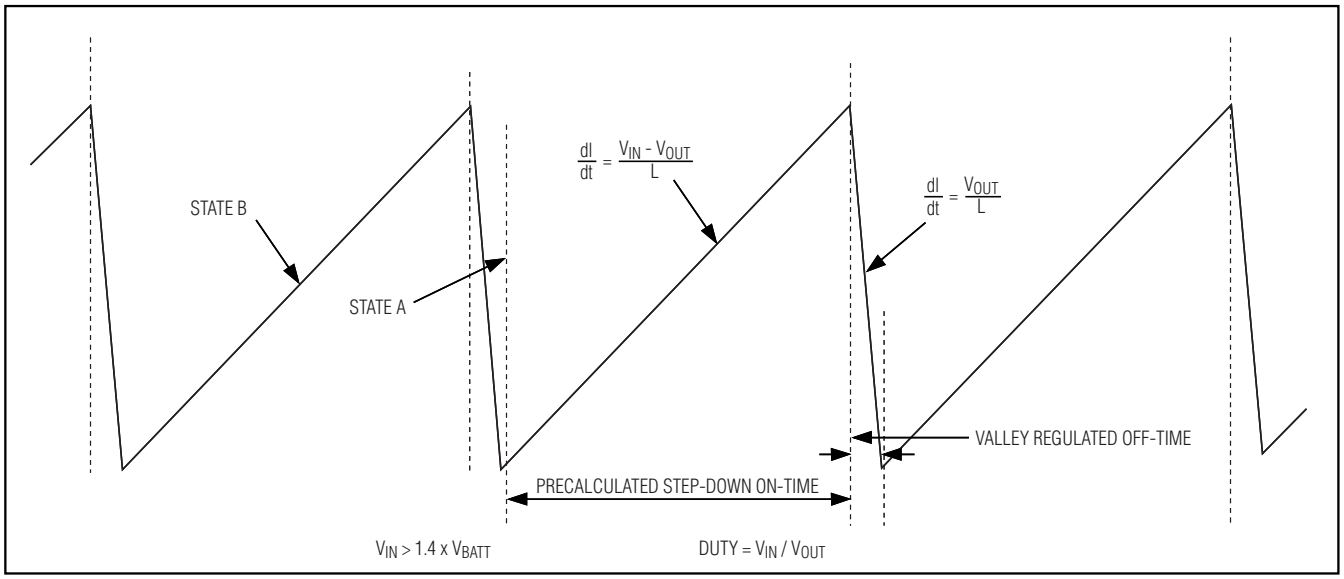


Figure 6. MAX1870A Step-Down Inductor Current Waveform

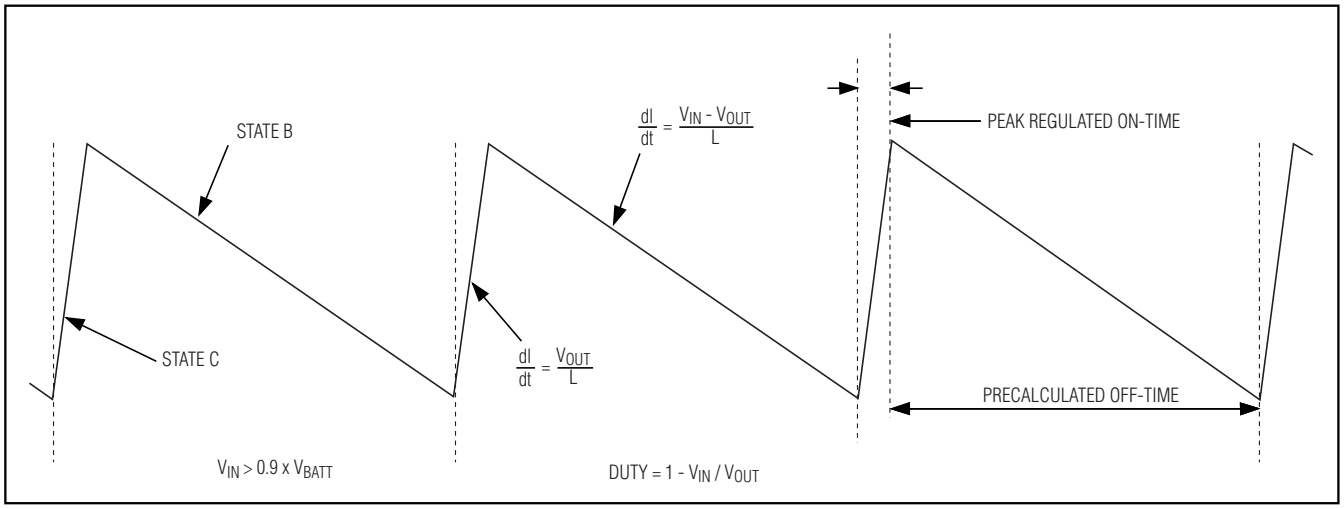


Figure 7. Step-Up Inductor-Current Waveform

signal based on the integrated error of the input current, charge current, and battery voltage. The error signal, determined by the lowest voltage clamp (LVC), sets the threshold for current-mode regulation. The following comparators are used for regulation:

- **IMIN:** The MAX1870A operates in discontinuous conduction if LVC is below 0.15V, and does not initiate another step-down on-time. In discontinuous step-up conduction, the peak current is set by IMIN. The peak inductor current in discontinuous step-up mode is:

$$I_{PK} > \frac{V_{IMIN}}{A_{CSI} \times RS2}$$

where VIMIN is the IMIN comparator threshold, 0.15V, and ACSI is the charge current-sense amplifier gain, 18V/V.

Step-Up/Step-Down Li+ Battery Charger

- **CCMP:** CCMP compares the current-mode control point, LVC, to the inductor current. In step-down mode, the off-time (state A) is terminated when the inductor current falls below the current threshold set by LVC. In step-up mode, the on-time (state C) is terminated when the inductor current rises above the current threshold set by LVC.
- **IMAX:** The IMAX comparators provide a cycle-by-cycle inductor current limit. This circuit compares the inductor current (CSI in step-down mode or CSS in step-up mode) to the internally fixed cycle-by-cycle current limit. The current-sense voltage limit is 200mV. With RS1_ = RS2 = 30mΩ, which corresponds to 6.7A. If the inductor current-sense voltage is greater than V_{IMAX} (200mV), a step-up on-time is terminated or a step-down on-time is not permitted.
- **ZCMP:** The ZCMP comparator detects when the inductor current crosses zero. If the ZCMP output goes high during a step-down off-time, the MAX1870A switches to the idle state (state D) to conserve power.

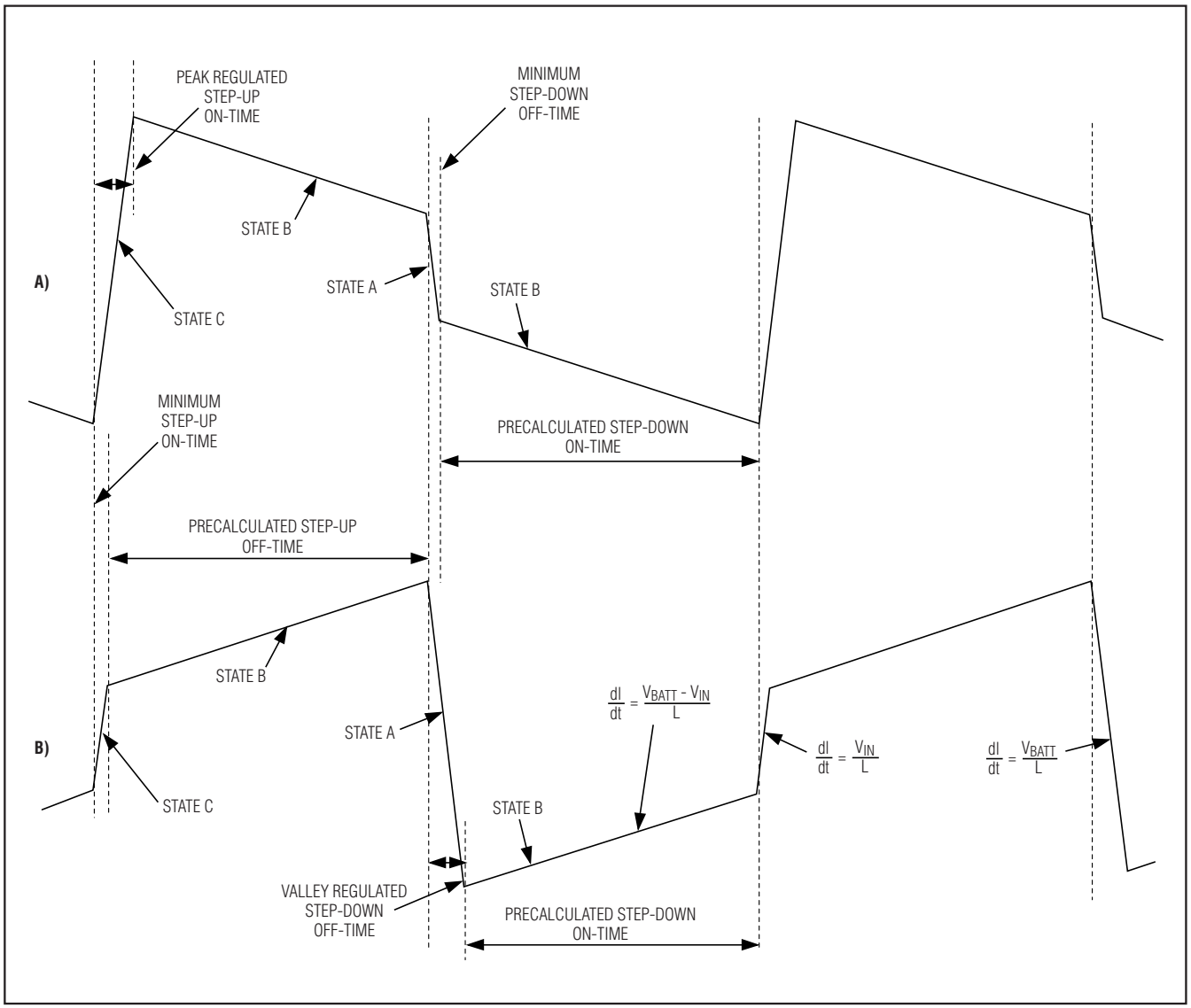


Figure 8. MAX1870A Step-Up/Step-Down Inductor-Current Waveform

Switching Frequency

The MAX1870A includes input and output-voltage feedforward to maintain pseudo-fixed-frequency (400kHz) operation. The time in state B is set according to the input voltage, output voltage, and a time constant. In step-up/step-down mode the switching frequency is effectively cut in half to allow for both the step-up cycle and the step-down cycle. The switching frequency is typically between 350kHz and 405kHz for V_{IN} between 8V and 28V. See the *Typical Operating Characteristics*.

Compensation

Each of the three regulation loops (the battery voltage, the charge current, and the input current limit) are compensated separately using the CCV, CCI, and CCS pins, respectively. Compensate the voltage regulation loop with a 10kΩ resistor in series with a 0.01µF capacitor from CCV to GND. Compensate the charge current loop and source current loop with 0.01µF capacitors from CCI to GND and from CCS to GND, respectively.

Voltage Loop Compensation

When regulating the charge voltage, the MAX1870A behaves as a current-mode step-down or step-up power supply. Since a current-mode controller regulates its output current as a function of the error signal, the duty-cycle modulator can be modeled as a GM stage (Figure 9). Results are similar in step-down, step-up, or step-up/down, with the exception of a load-dependent right-half-plane zero that occurs in step-up mode.

The required compensation network is a pole-zero pair formed with C_{CV} and R_{CV}. C_{CV} is chosen to be large enough that its impedance is relatively small compared to R_{CV} at frequencies near crossover. R_{CV} sets the gain of the error amplifier near crossover. R_{CV} and C_{OUT} determine the crossover frequency and, therefore, the closed-loop response of the system and the response time upon battery removal.

R_{ESR} is the equivalent series resistance (ESR) of the charger's output capacitor (C_{OUT}). R_L is the equivalent charger output load, $R_L = \Delta V_{BATT} / \Delta I_{CHG} = R_{BATT}$. The equivalent output impedance of the GMV amplifier, R_{OGMV}, is greater than 10MΩ. The voltage loop transconductance ($GMV = \Delta I_{CCV} / \Delta V_{BATT}$) scales inversely with the number of cells. GMV = 0.1µA/mV for four cells, 0.133µA/mV for three cells, and 0.2µA/mV for two cells. The DC-DC converter's transconductance depends upon the charge current-sense resistor RS2:

$$GM_{PWM} = \frac{1}{A_{CSI} \times RS2}$$

where A_{CSI} = 18, and RS2 = 30mΩ in the *Typical Application Circuits*, so GM_{PWM} = 1.85A/V.

Use the following equation to calculate the loop transfer function (LTF):

$$LTF = GM_{PWM} \times \frac{R_{OGMV} \times (1 + sC_{CV} R_{CV})}{(1 + sC_{CV} \times R_{OGMV})} \times \frac{R_L}{(1 + sC_{OUT} \times R_L)} \times G_{MV} \times (1 + sC_{OUT} \times R_{ESR})$$

The poles and zeros of the voltage-loop transfer function are listed from lowest frequency to highest frequency in Table 3.

Near crossover, C_{CV} has much lower impedance than R_{OGMV}. Since C_{CV} is in parallel with R_{OGMV}, C_{CV} dominates the parallel impedance near crossover. Additionally, R_{CV} has a much higher impedance than C_{CV} and dominates the series combination of R_{CV} and C_{CV}, so:

$$\frac{R_{OGMV} \times (1 + sC_{CV} \times R_{CV})}{(1 + sC_{CV} \times R_{OGMV})} \cong R_{CV}, \text{ near crossover}$$

C_{OUT} also has a much lower impedance than R_L near crossover, so the parallel impedance is mostly capacitive and:

$$\frac{R_L}{(1 + sC_{OUT} \times R_L)} \cong \frac{1}{sC_{OUT}}$$

If R_{ESR} is small enough, its associated output zero has a negligible effect near crossover and the loop transfer function can be simplified as follows:

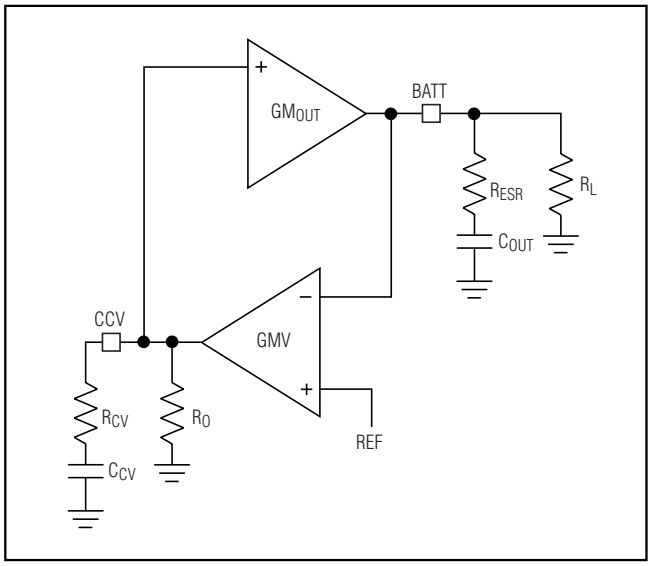


Figure 9. CCV Simplified Loop Diagram

Step-Up/Step-Down Li+ Battery Charger

$$LTF = GM_{PWM} \times \frac{R_{CV}}{sC_{OUT}} G_{MV}$$

Setting the LTF = 1 to solve for the unity-gain frequency yields:

$$f_{CO_CV} = GM_{PWM} \times G_{MV} \left(\frac{R_{CV}}{2\pi \times C_{OUT}} \right)$$

For stability, choose a crossover frequency lower than 1/10th of the switching frequency. The crossover frequency must also be below the RHP zero, calculated at maximum charge current, minimum input voltage, and maximum battery voltage.

Choosing a crossover frequency of 13kHz and solving for R_{CV} using the component values listed in Figure 1 yields:

MODE = V_{CC} (4 cells) GMV = 0.1µA/mV

C_{OUT} = 22µF GM_{PWM} = 1.85A/V

V_{BATT}= 16.8V f_{CO_CV} = 13kHz

$R_L = 0.2\Omega$ f_{OSC} = 400kHz

$$R_{CV} = \frac{2\pi \times C_{OUT} \times f_{CO_CV}}{GMV \times GM_{PWM}} = 10k\Omega$$

To ensure that the compensation zero adequately cancels the output pole, select $f_{Z_CV} \le f_{P_OUT}$.

$$C_{CV} \ge (R_L / R_{CV}) \times C_{OUT}$$

$$C_{CV} \ge 440pF$$

Figure 10 shows the Bode Plot of the voltage-loop frequency response using the values calculated above.

Charge-Current and Wall-Adapter-Current Loop Compensation

When the MAX1870A regulates the charge current or the wall adapter current, the system stability does not depend on the output capacitance. The simplified schematic in Figure 11 describes the operation of the MAX1870A when the charge-current loop (CCI) is in control. The simplified schematic in Figure 12 describes the operation of the MAX1870A when the source-current

Table 3. Constant Voltage Loop Poles and Zeros

NO.	NAME	CALCULATION	DESCRIPTION
1	CCV Pole	$f_{P_CV} = \frac{1}{2\pi \times R_{OGMV} C_{CV}}$	Lowest Frequency Pole created by C_{CV} and GMV's finite output resistance. Since R_{OGMV} is very large (R_{OGMV} > 10MΩ), this is a low-frequency pole.
2	CCV Zero	$f_{Z_CV} = \frac{1}{2\pi \times R_{CV} C_{CV}}$	Voltage-Loop Compensation Zero. If this zero is lower than the output pole, f_{P_OUT}, then the loop transfer function approximates a single-pole response near the crossover frequency. Choose C_{CV} to place this zero at least 1 decade below crossover to ensure adequate phase margin.
3	Output Pole	$f_{P_OUT} = \frac{1}{2\pi \times R_L C_{OUT}}$	Output Pole Formed with the Effective Load Resistance R_L and the Output Capacitance C_{OUT}. R_L influences the DC gain but does not affect the stability of the system or the crossover frequency.
4	Output Zero	$f_{Z_OUT} = \frac{1}{2\pi \times R_{ESR} C_{OUT}}$	Output ESR Zero. This zero can keep the loop from crossing unity gain if f_{Z_OUT} is less than the desired crossover frequency. Therefore, choose a capacitor with an ESR zero greater than the crossover frequency.
5	RHP Zero	$f_{RHPZ} = \frac{V_{IN}}{2\pi \times L I_L} = \frac{V_{IN}^2}{2\pi \times L I_{OUT} V_{OUT}}$	Step-Up Mode RHP Zero. This zero occurs because of the initial opposing response of a step-up converter. Efforts to increase the inductor current result in an immediate *decrease* in current delivered, although eventually result in an increase in current delivered. This zero is dependent on charge current and may cause the system to go unstable at high currents when in step-up mode. A right-half-plane zero is detrimental to both phase and gain. To ensure stability under maximum load in step-up mode, the crossover frequency must be lower than half of f_{RHPZ}.

loop (CCS) is in control. Since the output capacitor's impedance has little effect on the response of the current loop, only a single pole is required to compensate this loop. A_{CSI} and A_{CSS} are the internal gains of the current-sense amplifiers. RS2 is the charge current-sense resistor. RS1a and RS1b are the adapter current-sense resistors. R_{OGMI} and R_{OGMS} are the equivalent output impedance of the GMI and GMS amplifiers, which are greater than 10MΩ. GMI is the charge-current amplifier transconductance (2.4µA/mV). GMS is the adapter-current amplifier transconductance (1.7µA/mV.) GM_{PWM} is the DC-DC converter transconductance (1.85A/V).

Use the following equation to calculate the loop transfer function:

$$LTF = GM_{PWM} \times A_{CS_} \times RS_ \times GM_ \frac{R_{OGM_}}{1 + sR_{OGM_} \times C_{C_}}$$

which describes a single-pole system. Since $GM_{PWM} =$

$$\frac{1}{A_{CS_} \times RS_}$$

the loop-transfer function simplifies to:

$$LTF = GM_ \frac{R_{OGM_}}{1 + sR_{OGM_} \times C_{C_}}$$

Use the following equations to calculate the crossover frequency:

$$f_{CO_CI} = \frac{GMI}{2\pi C_{CI}}, f_{CO_CS} = \frac{GMS}{2\pi C_{CS}}$$

For stability, choose a crossover frequency lower than 1/10th of the switching frequency and lower than half of the RHP zero.

C_{CI} = 10 GMI / (2π x f_{OSC}), C_{CS} = 10 GMS / (2π x f_{OSC})

$$f_{RHPZ_WorstCase} = \frac{V_{IN_MIN}}{2\pi \times L \times I_L} = \frac{V_{IN_MIN}^2}{2\pi \times L \times I_{OUTMAX} \times V_{OUTMAX}}$$

This zero is inversely proportional to charge current and may cause the system to go unstable at high currents when in step-up mode. A right-half-plane zero is detrimental to both phase and gain. To also ensure stability under maximum load in step-up mode, the CCI crossover frequency must also be lower than f_{RHPZ}. The right-half-plane zero does not affect CCS.

Choosing a crossover frequency of 30kHz and using the component values listed in Figure 1 yields C_{CI} and $C_{CS_}$ > 10nF. Values for C_{CI} / C_{CS} greater than ten times the minimum value may slow down the current loop response excessively. Figure 13 shows the Bode Plot of the input-current frequency response using the values calculated above.

MOSFET Drivers

DHI and DBST are optimized for driving moderately-sized power MOSFETs. Use low-inductance and low-resistance traces from driver outputs to MOSFET gates.

DHI typically sources 1.6A and sinks 0.8A to or from the gate of the p-channel MOSFET. DHI swings from VHP to VHN. VHN is a negative LDO that regulates with respect to VHP to provide high-side gate drive. Connect VHP to DCIN. Bypass VHN with a 1µF capacitor to VHP.

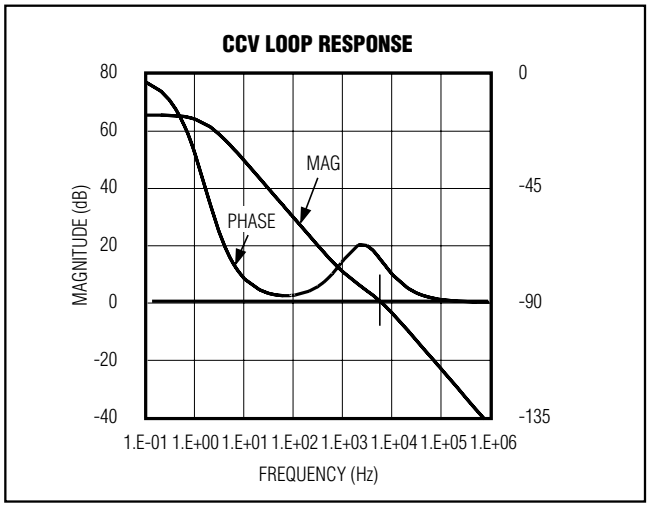


Figure 10. CCV Loop Response

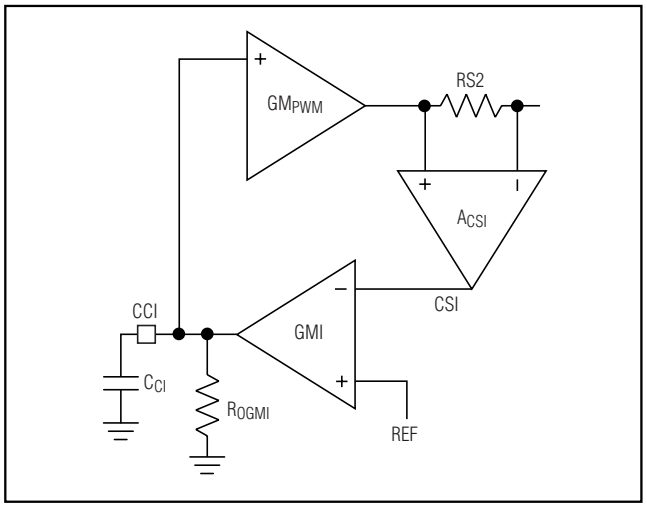


Figure 11. CCI Simplified Loop Diagram

Step-Up/Step-Down Li+ Battery Charger

LDO provides a 5.4V supply derived from DCIN and delivers over 10mA. The n-channel MOSFET driver DBST is powered by DLOV and can source 2.5A and sink 5A. Since LDO provides power to the internal analog circuitry, use an RC filter from LDO to DLOV as shown in Figure 1 to minimize noise at LDO. LDO also supplies the 4.096V reference (REF) and most of the internal control circuitry. Bypass LDO with a 1µF or greater capacitor to GND.

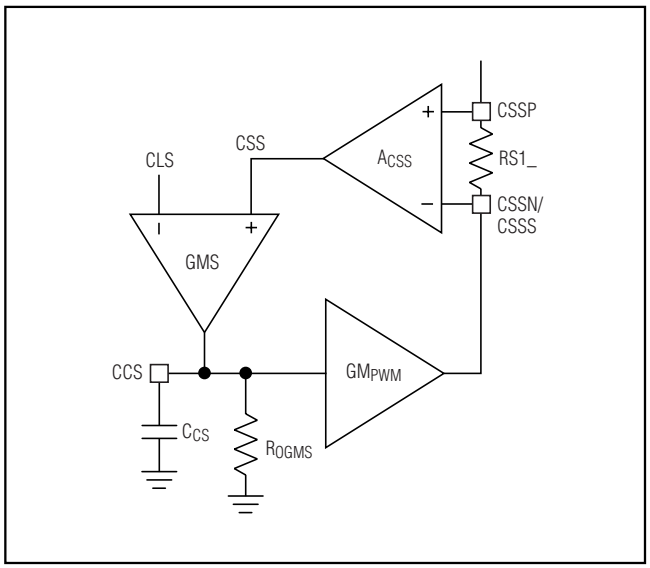


Figure 12. CCS Simplified Loop Diagram

Applications Information

Component Selection

Table 4 lists the recommended components and refers to the circuit of Figure 1. The following sections describe how to select these components.

MOSFETs

The MAX1870A requires one p-channel MOSFET and one n-channel MOSFET. Component substitutions are permissible as long as the on-resistance and gate charge are equal or lower and the voltage, current, and power-dissipation ratings are high enough. If using a lower-power application, scale down the MOSFETs with lower gate charge and the MOSFET's on-resistance can be scaled up. For example, in a system designed to deliver half as much current, MOSFETs selected with twice the on-resistance and half as much gate charge ensure equal or better efficiency, and reduce size and cost. If resistive losses dominate, it can be possible to reduce the gate charge at the cost of on-resistance and still achieve a similar efficiency.

Make sure that the linear regulators can drive the selected MOSFETs. The average current required to drive a given MOSFET is:

$$I_{LDO} = Q_{gM2} \times f_{switch}$$

$$I_{VHN} = Q_{gM1} \times f_{switch}$$

where f_{switch} is 400kHz (typ).

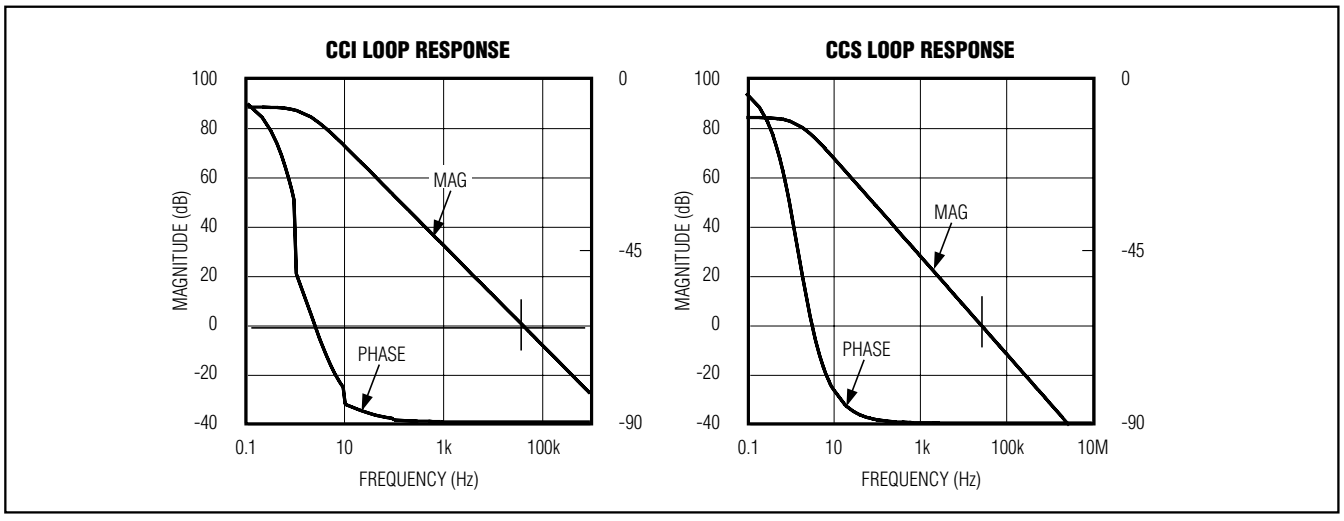


Figure 13. CCI and CCS Loop Response

MOSFET Power Dissipation

Table 5 shows the resistive losses and switching losses in each of the MOSFETs during either step-up or step-down operation. Table 5 provides a first-order estimate, but does not consider second-order effects such as ripple current or nonlinear gate drive.

For typical applications where $V_{BATT} / 2 < V_{IN} < 2 \times V_{BATT}$, the resistive losses are primarily dissipated in M1 since M2 operates at a lower duty cycle. Switching losses are dissipated in M1 when in step-down mode and in M2 when in step-up mode. Ratio the MOSFETs so that resistive losses roughly equal switching losses when at maximum load and typical input/output conditions. The resistive loss equations are a good approximation in hybrid mode (V_{IN} near V_{BATT}). Both M1 and M2 switching losses apply in hybrid mode.

Switching losses can become a heat problem when the maximum AC adapter voltage is applied in step-down operation or minimum AC adapter voltage is applied with a maximum battery voltage. This behavior occurs because of the squared term in the $CV^2 f$ switching-loss equation. Table 5 provides only an estimate and is not a substitute for breadboard evaluation.

Inductor Selection

Select the inductor to minimize power dissipation in the MOSFETs, inductor, and sense resistors. To optimize resistive losses and RMS inductor current, set the LIR (inductor current ripple) to 0.3. Because the maximum resistive power loss occurs at the step-up boundary of hybrid mode, select LIR for operating in this mode. Select the inductance according to the following equation:

$$L = \frac{2 \times V_{IN} \times t_{min}}{LIR \; I_{CHG}}$$

Larger inductance values can be used; however, they contribute extra resistance that can reduce efficiency. Smaller inductance values increase RMS currents and can also reduce efficiency.

Saturation Current Rating

The inductor must have a saturation current rating high enough so it does not saturate at full charge, maximum output voltage, and minimum input voltage. In step-up operation, the inductor carries a higher current than in step-down operation with the same load. Calculate the inductor saturation current rating by the following equation:

$$I_{SAT} \geq \frac{V_{OUT_MAX} \times I_{CHG_MAX}}{V_{IN_MIN}} + \frac{T \times V_{IN_MIN} \times \left(1 - \frac{V_{IN_MIN}}{V_{OUT_MAX}}\right)}{2 \times L}$$

Input-Capacitor Selection

The input capacitor must meet the ripple current requirement (I_{RMS}) imposed by the switching currents. Nontantalum chemistries (ceramic, aluminum, or OS-

Table 4. Component List

DESIGNATION	PART	SPECIFICATIONS
INDUCTORS		
L1	Sumida CDRH104R-100 Sumida CDRH104R-7R0 Sumida CDRH104R-5R2 Sumida CDRH104R-3R8	10µH, 4.4A, 35mΩ power inductor 7µH, 4.8A, 27mΩ power inductor 5.2µH, 5.5A, 22mΩ power inductor 3.8µH, 6A, 13mΩ power inductor
P-CHANNEL MOSFETs		
M1	Siliconix Si4435DY Fairchild FDC602P Fairchild FDS4435A Fairchild FDW256P	P-FET 35mΩ, Q_G = 17nC, V_{DSMAX} = 30V, 8-pin SO P-FET 35mΩ, Q_G = 14nC, V_{DSMAX} = 20V, 6-pin SuperSOT P-FET 25mΩ, Q_G = 21nC, V_{DSMAX} = 30V, 8-pin SO P-FET 20mΩ, Q_G = 28nC, V_{DSMAX} = 30V, 8-pin TSSOP
N/P-CHANNEL MOSFET PAIRS		
M1/M2	Fairchild FDW2520C (8-pin TSSOP)	N-FET 18mΩ, Q_G = 14nC, V_{DSMAX} = 20V, P-FET 35mΩ, Q_G = 14nC, V_{DSMAX} = 20V
N-CHANNEL MOSFETs		
M2	IRF7811W	N-FET, 9mΩ, Q_G = 18nC, V_{DSMAX} = 30V, 8-pin SO

Table 5. MOSFET Resistive and Switching Losses

DESIGNATION	STEP-DOWN MODE	STEP-UP MODE
	DC LOSSES	
M1	$\left(\frac{V_{BATT}}{V_{DCIN}}\right) \times I_{CHG}^2 \times R_{DS(ON)}$	$\left(\frac{V_{BATT}}{V_{DCIN}} \times I_{CHG}\right)^2 \times R_{DS(ON)}$
D4	$\left(1 - \frac{V_{BATT}}{V_{DCIN}}\right) \times I_{CHG}\ V_{Diode}$	0
M2	0	$\left(1 - \frac{V_{DCIN}}{V_{BATT}}\right) \times \left(\frac{V_{BATT}}{V_{DCIN}} \times I_{CHG}\right)^2 \times R_{DS(ON)}$
D3	$I_{CHG} \times V_{DIODE}$	$I_{CHG} \times V_{DIODE}$
	SWITCHING LOSSES	
M1	$\frac{V_{DCIN(MAX)}^2 \times C_{LX} \times f_{SW}\ I_{CHG}}{I_{GATE}}$	0
D4	0	0
M2	0	$\frac{V_{BATT(MAX)}^3 \times C_{LX} \times f_{SW}\ I_{CHG}}{I_{GATE} \times V_{DCIN(MAX)}}$
D3	0	0

Note: *C_{LX} is the total parasitic capacitance at the drain terminals of M1 and M2. I_{GATE} is the peak gate-drive source/sink current of M1 or M2.*

CON) are preferred due to their resilience to power-up surge currents.

The input capacitors should be sized so that the temperature rise due to ripple current in continuous conduction does not exceed approximately 10°C. Choose a capacitor with a ripple current rating higher than 0.5 x I_{CHG}.

Output-Capacitor Selection

The output capacitor absorbs the inductor ripple current in step-down mode, or a peak-to-peak ripple current equal to the inductor current when in step-up or hybrid mode. As such, both capacitance and ESR are important parameters in specifying the output capacitor. The actual amplitude of the ripple is the combination of the two. Ceramic devices are preferable because of their resilience to surge currents. The worst-case output ripple occurs during hybrid mode when the input voltage is at its minimum. See the *Typical Operating Characteristics*.

Select a capacitor that can handle 0.5 x I_{CHG} x V_{BATT} / V_{IN} while keeping the rise in capacitor temperature less than 10°C. Also, select the output capacitor to tolerate the surge current delivered from the battery when it is initially plugged into the charger.

Battery-Removal Response

Upon battery removal, the MAX1870A continues to regulate a constant inductor current until the battery voltage, V_{BATT}, exceeds the regulation threshold. The MAX1870A's response time depends on the bandwidth of the CCV loop, f_{CO} (see the *Voltage Loop Compensation* section). For applications where battery overshoot is critical, either increase C_{OUT} or increase f_{CO} by increasing R_{CV}. See *Battery Insertion and Removal* in the *Typical Operating Characteristics*.

System Load Transient

The MAX1870A battery charger features a very fast response time to system load transients. Since the input current loop is configured as a single-pole system, the MAX1870A responds quickly to system load transients (see the System Load-Transient Response graph in the *Typical Operating Characteristics*). This reduces the risk of tripping the overcurrent threshold of the wall adapter and minimizes requirements for adapter oversizing.

Layout and Bypassing

Bypass DCIN with a 1µF to ground (Figure 1). Optional diodes D1 and D2 protect the MAX1870A when the DC power-source input is reversed. A signal diode for D1 is adequate because DCIN only powers the LDO and the internal reference. Good PC board layout is required to achieve specified noise, efficiency, and stable performance. The PC board layout artist must be given explicit instructions—preferably, a pencil sketch showing the placement of the power-switching components and high-current routing. Refer to the PC board layout in the MAX1870A evaluation kit for examples. A ground plane is essential for optimum performance. In most applications, the circuit is located on a multilayer board, and full use of the four or more copper layers is recommended. Use the top layer for high-current connections (PGND, DHI, VHP, VHN, BLKP, and DLOV), the bottom layer for quiet connections (CSSP, CSSN, CSSS, CSIP, CSIN, REF, CCV, CCI, CCS, DCIN, LDO and GND), and the inner layers for an uninterrupted ground plane. Use the following step-by-step guide:

1) Place the high-power connections first, with their grounds adjacent:
   - Minimize the current-sense resistor trace lengths, and ensure accurate current sensing with Kelvin connections. Use independent branches for CSSP, CSSS, CSSN, CSIP, and CSIN.
   - Minimize ground trace lengths in the high-current paths.
   - Minimize other trace lengths in the high-current paths.
   - Use >5mm wide traces for high-current paths.

   Ideally, surface-mount power components are flush against one another with their ground terminals almost touching. These high-current grounds are then connected to each other with a wide, filled zone of top-layer copper, so they do not go through vias. Other high-current paths should also be minimized, but focus primarily on short ground and current-sense connections to eliminate about 90% of all PC board layout problems.
2) Place the IC and signal components. Keep the main switching nodes (inductor connections) away from sensitive analog components (current-sense traces and REF capacitor). **Important: the IC must be no further than 10mm from the current-sense resistors.** Keep the gate-drive traces (DHI and DBST) shorter than 20mm, and route them away from the current-sense lines and REF. Place ceramic bypass capacitors close to the IC. The bulk capacitors can be placed further away. Bypass CSSP, CSSN, CSIN, and CSIP to analog GND to reduce switching noise and maintain input-current and charger-current accuracy. Place the current-sense input filter capacitors under the part, connected directly to GND.
3) Use a single-point star ground placed directly below the part. Connect the input ground trace, power ground (subground plane), and normal ground to this node.

Figure 14 shows a partial layout of the power path and components. Refer to the EV kit data sheet for more information.

Step-Up/Step-Down Li+ Battery Charger

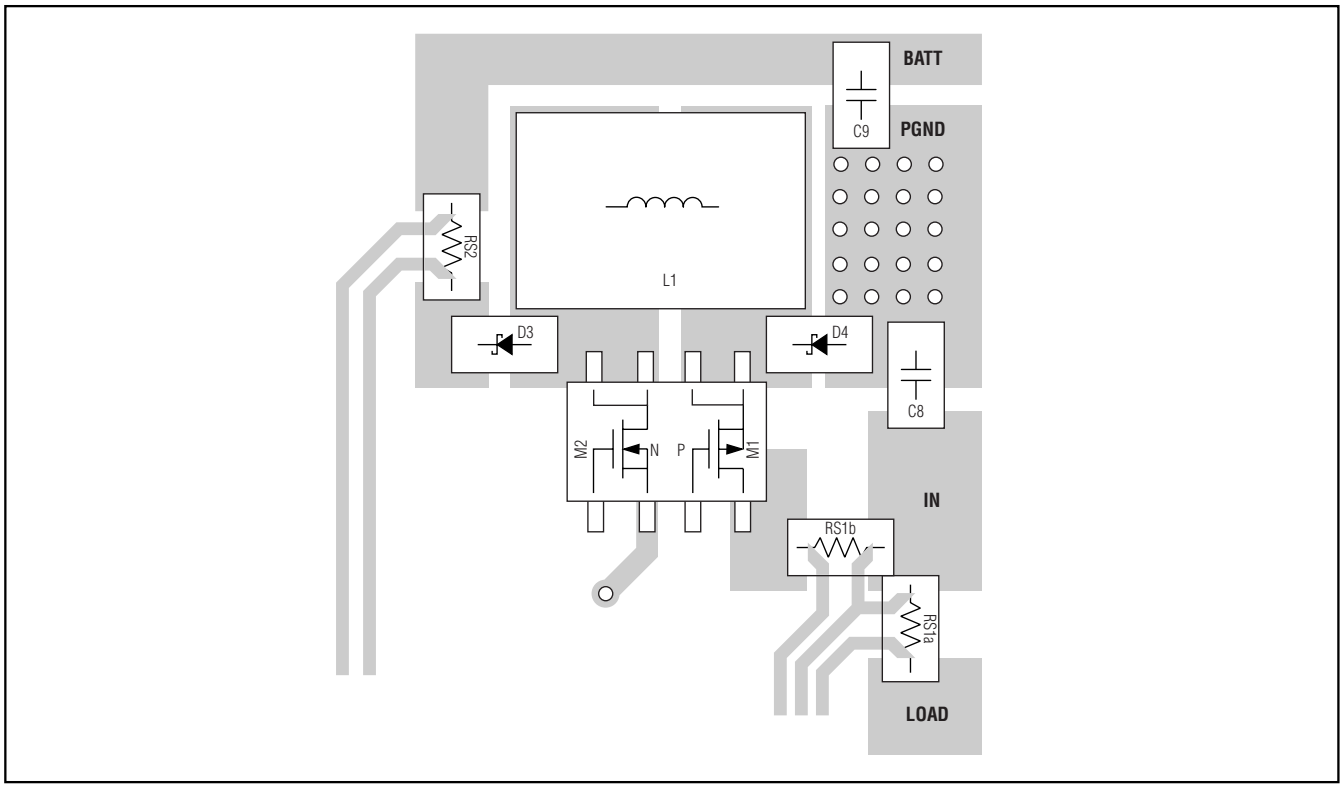
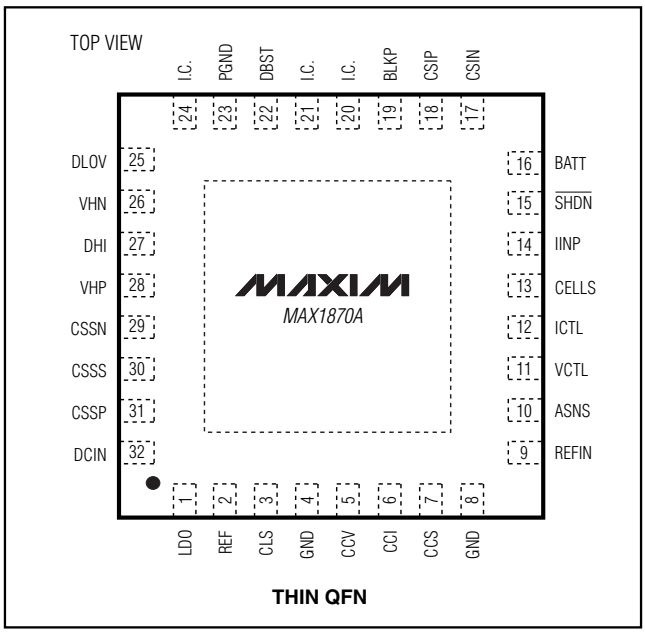


Figure 14. Recommended Layout for the MAX1870A

Pin Configuration



Chip Information

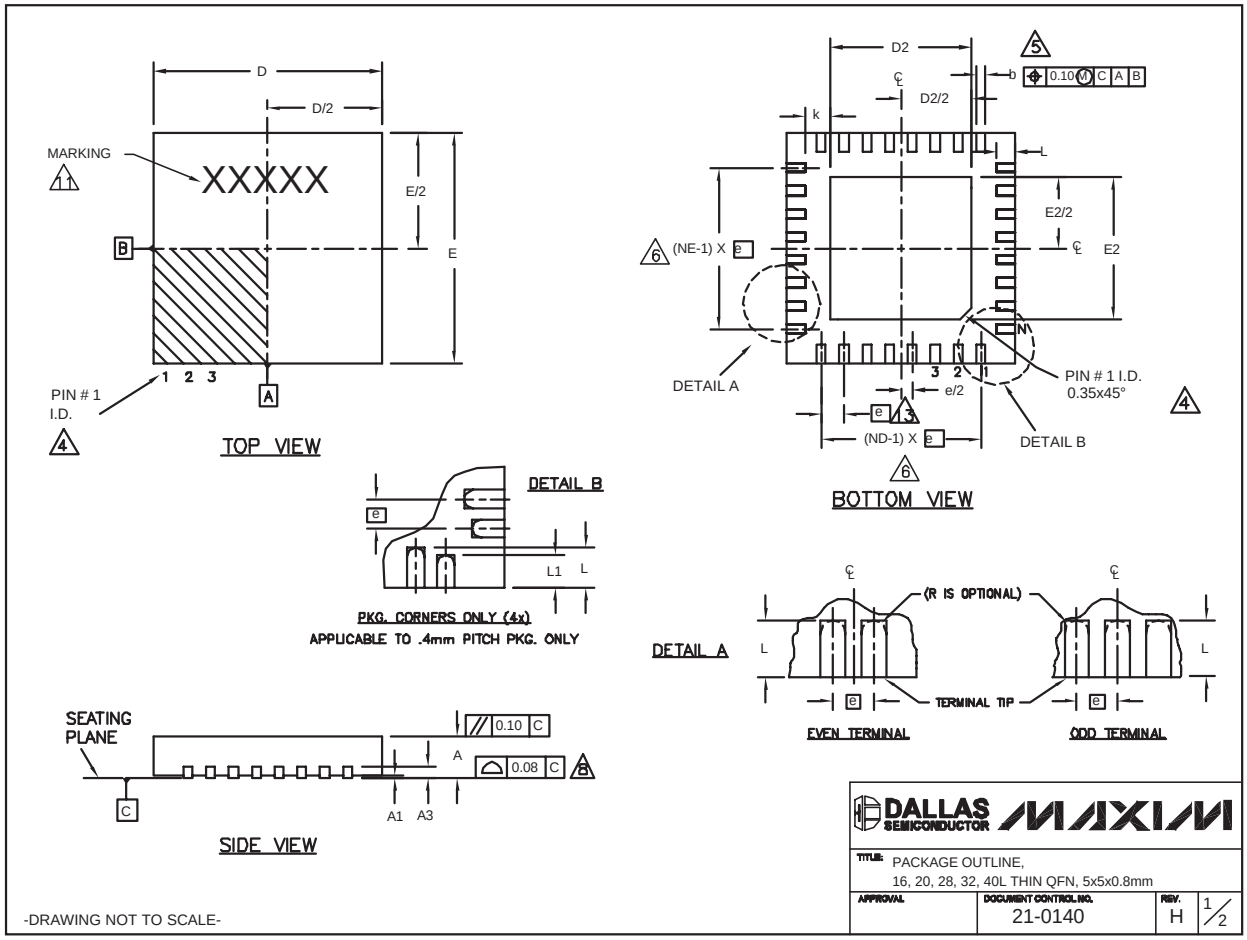
TRANSISTOR COUNT: 6484

PROCESS: BiCMOS

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

QFN THIN.EPS



Step-Up/Step-Down Li+ Battery Charger

Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

COMMON DIMENSIONS															
PKG.	16L 5x5			20L 5x5			28L 5x5			32L 5x5			40L 5x5		
SYMBOL	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80
A1	0	0.02	0.05	0	0.02	0.05	0	0.02	0.05	0	0.02	0.05	0	0.02	0.05
A3	0.20 REF.			0.20 REF.			0.20 REF.			0.20 REF.			0.20 REF.		
b	0.25	0.30	0.35	0.25	0.30	0.35	0.20	0.25	0.30	0.20	0.25	0.30	0.15	0.20	0.25
D	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10
E	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10	4.90	5.00	5.10
e	0.80 BSC.			0.65 BSC.			0.50 BSC.			0.50 BSC.			0.40 BSC.		
k	0.25	-	-	0.25	-	-	0.25	-	-	0.25	-	-	0.25	0.35	0.45
L	0.30	0.40	0.50	0.45	0.55	0.65	0.45	0.55	0.65	0.30	0.40	0.50	0.40	0.50	0.60
L1	-	-	-	-	-	-	-	-	-	-	-	-	0.30	0.40	0.50
N	16			20			28			32			40		
ND	4			5			7			8			10		
NE	4			5			7			8			10		
JEDEC	WHHB			WHHC			WHHD-1			WHHD-2			-----		

EXPOSED PAD VARIATIONS								
PKG. CODES	D2			E2			L	DOWN BONDS ALLOWED
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	±0.15	
T1655-1	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T1655-2	3.00	3.10	3.20	3.00	3.10	3.20	**	YES
T1655N-1	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T2055-2	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T2055-3	3.00	3.10	3.20	3.00	3.10	3.20	**	YES
T2055-4	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T2055-5	3.15	3.25	3.35	3.15	3.25	3.35	0.40	YES
T2855-1	3.15	3.25	3.35	3.15	3.25	3.35	**	NO
T2855-2	2.60	2.70	2.80	2.60	2.70	2.80	**	NO
T2855-3	3.15	3.25	3.35	3.15	3.25	3.35	**	YES
T2855-4	2.60	2.70	2.80	2.60	2.70	2.80	**	YES
T2855-5	2.60	2.70	2.80	2.60	2.70	2.80	**	NO
T2855-6	3.15	3.25	3.35	3.15	3.25	3.35	**	NO
T2855-7	2.60	2.70	2.80	2.60	2.70	2.80	**	YES
T2855-8	3.15	3.25	3.35	3.15	3.25	3.35	0.40	YES
T2855N-1	3.15	3.25	3.35	3.15	3.25	3.35	**	NO
T3255-2	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T3255-3	3.00	3.10	3.20	3.00	3.10	3.20	**	YES
T3255-4	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T3255N-1	3.00	3.10	3.20	3.00	3.10	3.20	**	NO
T4055-1	3.20	3.30	3.40	3.20	3.30	3.40	**	YES

** SEE COMMON DIMENSIONS TABLE

NOTES:

1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
3. N IS THE TOTAL NUMBER OF TERMINALS.
4. THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
5. DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
6. ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
7. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
8. COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
9. DRAWING CONFORMS TO JEDEC MO220, EXCEPT EXPOSED PAD DIMENSION FOR T2855-1, T2855-3, AND T2855-6.
10. WARPAGE SHALL NOT EXCEED 0.10 mm.
11. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
12. NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY.
13. LEAD CENTERLINES TO BE AT TRUE POSITION AS DEFINED BY BASIC DIMENSION "e", ±0.05.

-DRAWING NOT TO SCALE-

DALLAS SEMICONDUCTOR MAXIM

TITLE: PACKAGE OUTLINE, 16, 20, 28, 32, 40L THIN QFN, 5x5x0.8mm

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