# HMC1190ALP6NE

v02.0120

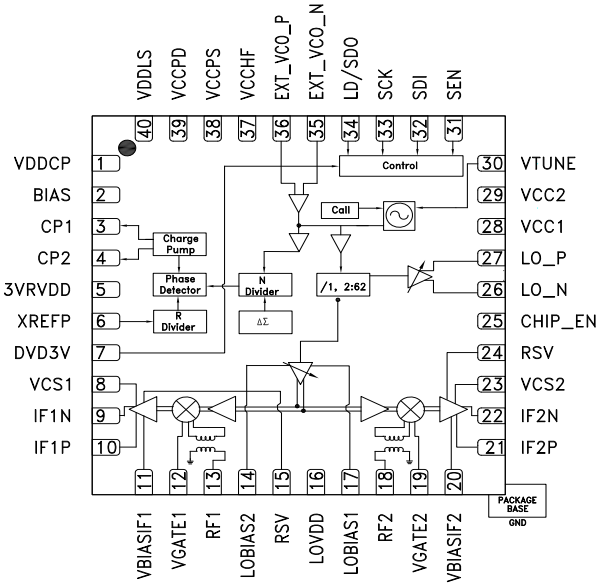
## BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER w/ Fractional-N PLL & VCO, 0.7 - 3.8 GHz

### Typical Applications

The HMC1190ALP6NE is Ideal for:

- Multiband/Multi-standard Cellular BTS Diversity Receivers
- GSM & 3G & LTE/WiMAX/4G
- MIMO Infrastructure Receivers
- Wideband Radio Receivers
- Multiband Basestations & Repeaters

### Functional Diagram




### Features

Broadband Operation with no external matching

High-side and Low-side LO injection Operation

High Input IP3 of +24 dBm

Power Conversion Gain of 8.9 dB

Input P1dB of 11 dBm

SSB Noise Figure of 9 dB

55 dBc Channel-to-Channel Isolation

Enable/Disable Mixer and PLLVCO independently

Single-ended RF input ports

Maximum Phase Detector Rate: 100 MHz

Low Phase Noise: -110 dBc/Hz in Band Typical

PLL FOM:

-230 dBc/Hz Integer Mode, -227 dBc/Hz Fractional Mode

< 180 fs Integrated RMS Jitter (1 kHz to 20 MHz)

LO Low Noise Floor: -165 dBc/Hz

Mixer Low Noise Floor: -161 dBc/Hz

Integrated VCO

External VCO Input, differential LO output

Exact Frequency Mode:
0 Hz Fractional Frequency Error

Programmable RF Output Phase

Output Phase Synchronous Frequency Changes

Output Phase Synchronization

LO Output Mute Function

Compact Solution, 6x6 mm Leadless QFN Package

### General Description

The HMC1190ALP6NE is a high linearity broadband dual channel downconverting mixer with integrated PLL and VCO optimized for multi-standard receiver applications that require a compact, low power design. Integrated wideband limiting LO amplifiers enable the HMC1190ALP6NE to achieve an unprecedented RF bandwidth of 700 MHz to 3800 MHz for applications including Cellular/3G, LTE/WiMAX/4G. Unlike conventional narrow-band downconverters, the HMC1190ALP6NE supports both high-side and low-side LO injection over all RF frequencies. The RF and LO input ports are internally matched to 50 Ohms.

The HMC1190ALP6NE features an integrated LO and RF baluns, enable control of IF and LO amplifiers and bias control interface to high linearity passive mixer cores. Balanced passive mixer combined with high-linearity IF amplifier architecture provides excellent LO-to-RF, LO-to-IF, and RF-to-IF isolations. Low noise figure of 9 dB, and high IIP3 of +24 dBm allow the HMC1190ALP6NE to be used in most demanding applications. External bias control pins enable optimization of already low power dissipation of 2.34 W (typical). Fast enable control interface reduces power consumption further in TDD applications.

External VCO input allows the HMC1190ALP6NE to lock external VCOs, and enables cascaded LO architectures for MIMO applications. Two separate Charge Pump (CP) outputs enable separate loop filters optimized for both integrated and external VCOs, and seamless switching between integrated or external VCOs during operation. Programmable RF output phase features can further phase adjust and synchronize multiple HMC1190ALP6NE's enabling scalable MIMO and beam-forming radio architectures.

Additional features include configurable LO output mute function, Exact Frequency Mode that enables the HMC1190ALP6NE to generate fractional frequencies with 0 Hz frequency error, and the ability to synchronously change frequencies without changing phase of the output signal that increases efficiency of digital pre-distortion loops. The HMC1190ALP6NE is housed in RoHS compliant compact 6x6 mm leadless QFN package.

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# BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER w/ Fractional-N PLL & VCO, 0.7 - 3.8 GHz



## Table 1. Electrical Specifications

*$T_A$ = +25°C, IF Frequency = 150 MHz, LO Power is set to '3' [1], RF Input Power = -5 dBm, LOVDD=3VRVDD=DVDD3V=CHIPEN= 3.3V, VDDCP=VCS1=VCS2=VBIASIF1=VBIASIF2=LOBIAS1=LOBIAS2=VCC1=VCC2=VGATE1=VGATE2=5V unless otherwise noted.*

| Parameter | Typical | | | | | | | | | | | | Units |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Mixer Core RF Input Frequency Range | 700 - 3800 | | | | | | | | | | | | MHz |
| Mixer Core IF Output Frequency Range | 50 - 350 | | | | | | | | | | | | MHz |
| RF Frequency | 900 | | 1900 | | 2200 | | 2700 | | 3500 | | 3800 | | MHz |
| Side Band[2] | LSB | USB | LSB | USB | LSB | USB | LSB | USB | LSB | USB | LSB | USB | |
| Conversion Gain[3] | 9 | 8.9 | 8.3 | 8.5 | 7.9 | 8.1 | 7.1 | 7.6 | 6 [4] | 6.2 [4] | 4.7 [4] | 4.7 [4] | dB |
| IIP3 | 24.5 | 22.7 | 26.5 | 25.5 | 26.9 | 26.2 | 27.1 | 27.5 | 27 | 27.9 | 27.1 | 28.3 | dB |
| Noise Figure (SSB) | 9.6 | 9.3 | 9.9 | 9.3 | 10.7 | 10.1 | 11.5 | 11 | 14 | 13.1 | 15.7 | 13.7 | dB |
| Input 1 dB Compression | 10.6 | 10.4 | 12.3 | 11.8 | 12.8 | 12.2 | 13.9 | 13.2 | 15.7 | 14.7 | 17.3 | 16.3 | dBm |
| LO Leakage at RF Port | -47.6 | -44.8 | -49.2 | -49.5 | -50.4 | -48.8 | -44.2 | -50.1 | -48.8 | -48.7 | -51.1 | -48.1 | dBm |
| RF to IF Isolation | 41.5 | 43.1 | 39.2 | 46.7 | 39.9 | 41.5 | 46.1 | 44.8 | 54.1 | 51 | 52 | 52.8 | dBc |
| Channel to Channel Isolation[5] | 56.1 | 55.9 | 52.6 | 53.5 | 51.4 | 51 | 49.4 | 49.8 | 43.5 | 44 | 43.5 | 44.3 | dBc |
| +2RF-2LO Response | 83 | 71.6 | 75.7 | 73.9 | 81.5 | 82.2 | 67.3 | 76.1 | 68.5 | 68 | 68.7 | 69.1 | dBc |
| +3RF-3LO Response | 89 | 73 | 75.3 | 74.8 | 86.7 | 74.1 | 79.7 | 73.6 | 75.2 | 71.8 | 75.5 | 69.9 | dBc |

[1] LO Power Level can be adjusted using Reg 16h

[2] LSB stands for lower side band and refers to RF<LO. USB stands for upper side band and refers to RF>LO.

[3] Balun losses at IF output ports are de-embedded.

[4] VGATE1 = VGATE2 = 4.9V

[5] RF1 input power= -5 dBm, measurement taken from IF2 output. RF2 and IF1 ports are terminated with 50 Ohms

## Table 2. DC Power Supply Specifications

| Parameter | Min. | Typ. | Max. | Units |
|---|---|---|---|---|
| 5V Supply Rails (VDDCP, VCS1, VCS2, VDDLS, VBIASIF1, VBIASIF2, LOBIAS1, LOBIAS2, VCC1, VCC2) | 4.8 | 5 | 5.2 | V |
| | 200 [1] | 330 | 556 [2] | mA |
| 3.3V Supply Voltage (LOVDD, 3VRVDD, DVDD3V, VCCPD, VCCPS, VCCHF) | 3.1 | 3.3 | 3.5 | V |
| | 142 [1] | 193 | 246 [2] | mA |
| VGATE1, VGATE2[3] | VDDIF-0.2 | 5 | VDDIF | V |
| 5V Supply Rails [4] (VDDCP, VCS1, VCS2, VDDLS, VBIASIF1, VBIASIF2, LOBIAS1, LOBIAS2, VCC1, VCC2) (5V) | 280.5 | 330 | 379.5 | mA |
| 3.3V Supply Voltage [4] (LOVDD, 3VRVDD, DVDD3V, VCCPD, VCCPS, VCCHF) (3.3V) | 164.05 | 193 | 221.95 | mA |

[1] LO Frequency=2400 MHz, LO_MIX is enabled in single ended mode, LO_OUT is disabled. LO_MIX power setting = 0, divide ratio = 1, divider stage high gain = 0

[2] LO Frequency=2400 MHz, LO_MIX and LO_OUT are both enabled in differential mode. LO_MIX and LO_OUT power setting = 3, divide ratio = 62, divider stage high gain = 1

[3] VGATE1 and VGATE2 are obtained through resistors which are connected to VDDIF

[4] LO Frequency=2400 MHz, LO_MIX is enabled in differential mode, LO_OUT is disabled. LO_MIX power setting = 3. When LO_OUT is enabled in differential mode the bias current increases by 34 mA (Typ.).

**Table 2. DC Power Supply Specifications** *(Continued)*

| Parameter | | Min. | Typ. | Max. | Units |
|---|---|---|---|---|---|
| Mixer Core Supply Currents when IF1EN and IF2EN are Enabled | VDDIF (5V) | 139 | 146 | 152 | mA |
| | VCS1 + VCS2 (5V) | 2.7 | 3 | 3.1 | mA |
| | VBIASIF1 + VBIASIF2 (5V) | 20 | 21.5 | 23 | mA |
| | VGATE1 + VGATE2 | 3 | 3 | 3 | mA |
| | LOBIAS1 + LOBIAS2 (5V) | 4 | 4 | 4 | mA |
| | LOVDD (3.3V) | 136 | 143 | 150 | mA |
| Mixer Core Supply Currents when IF1EN and IF2EN are Disabled | VDDIF (5V) | 0 | 0 | 0 | mA |
| | VCS1 + VCS2 (5V) | 3.2 | 3.45 | 3.6 | mA |
| | VBIASIF1 + VBIASIF2 (5V) | 1.3 | 1.6 | 1.9 | mA |
| | VGATE1 + VGATE2 (5V) | 0 | 0 | 0 | mA |
| | LOBIAS1 + LOBIAS2 (5V) | 4.5 | 4.9 | 5.2 | mA |
| | LOVDD (3.3V) | 3.2 | 3.45 | 3.6 | mA |
| PLL/VCO Core Supply Currents when CHIPEN is Enabled | LO_OUT differential, LO_MIXER off [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>126.65<br>40.8 | <br>149<br>48 | <br>171.35<br>55.2 | <br>mA<br>mA |
| | LO_OUT single-ended, LO_MIXER off [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>110.5<br>40.8 | <br>130<br>48 | <br>149.5<br>55.2 | <br>mA<br>mA |
| | LO_OUT off, LO_MIXER differential [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>126.65<br>40.8 | <br>149<br>48 | <br>171.35<br>55.2 | <br>mA<br>mA |
| | LO_OUT off, LO_MIXER single-ended [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>110.5<br>40.8 | <br>130<br>48 | <br>149.5<br>55.2 | <br>mA<br>mA |
| | LO_OUT differential, LO_MIXER differential [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>156.4<br>40.8 | <br>184<br>48 | <br>211.6<br>55.2 | <br>mA<br>mA |
| | LO_OUT single-ended, LO_MIXER single-ended [1]<br>5V Supplies (VDDLS, VCC1, VCC2, VDDCP)<br>3.3V Supplies (3VRVDD, DVDD3V, VCCHF, VCCPS, VCCPD) | <br>127.5<br>40.8 | <br>150<br>48 | <br>172.5<br>55.2 | <br>mA<br>mA |
| | VCCPD, VCCPS, VCCHF, DVDD3V, 3VRVDD (+3.3V) | 44.5 | 47 | 49.5 | mA |
| PLL/VCO Core Supply Currents when CHIPEN is Disabled | VDDCP, VCC1, VCC2, VDDLS (5V) [1] | 1 | 1 | 1 | mA |
| | 3VRVDD, DVDD3V, VCCPD, VCCPS, VCCHF (3.3V) [1] | 5 | 5 | 5 | mA |

[1] LO Frequency=2400 MHz, LO_MIX and LO_OUT outputs set to maximum gain.

### Table 3. PLL & VCO Specifications

| Parameter | Conditions | Min. | Typ. | Max. | Units |
|---|---|---|---|---|---|
| **Logic Inputs** | | | | | |
| Logic High | | 1.2 | | | V |
| Logic Low | | | | 0.6 | V |
| Input Current | | | | ±1 | uA |
| Input Capacitance | | | 2 | | pF |
| **LO Output Characteristics** | | | | | |
| LO Output Frequency | | 50 | | 4100 | MHz |
| VCO Frequency at PLL Input | | 2000 | | 4100 | MHz |
| VCO Fundamental Frequency | | 2000 | | 4100 | MHz |
| **VCO Output Divider** | | | | | |
| VCO Output Divider Range | 1, 2, 4, ... 60, 62 | 1 | | 62 | |
| **PLL RF Divider Characteristics** | | | | | |
| 19-Bit N Divider Range | Integer | 16 | | 524287 | |
| | Fractional | 20 | | 524283 | |
| **Phase Detector (PD)** | | | | | |
| PD Frequency | Fractional Mode | DC | | 100 | MHz |
| | Integer Mode | DC | | 100 | MHz |
| **Harmonics** | | | | | |
| fo Mode at 4000 MHz | 2nd / 3rd / 4th | | -30/-22/-32 | | dBc |
| **VCO Output Divider** | | | | | |
| VCO RF Divider Range | 1,2,4,6,8,... 62 | 1 | | 62 | |
| **PLL RF Divider Characteristics** | | | | | |
| 19-Bit N-Divider Range (Integer) | Max = $2^{19}$ - 1 | 16 | | 524,287 | |
| 19-Bit N-Divider Range (Fractional) | Fractional nominal divide ratio varies (-3 / +4) dynamically max | 20 | | 524,283 | |
| **REF Input Characteristics** | | | | | |
| Max Ref Input Frequency | | | | 350 | MHz |
| Ref Input Voltage | AC Coupled | 1 | 2 | 3.3 | Vpp |
| Ref Input Capacitance | | | | 5 | pF |
| 14-\Bit R-Divider Range | | 1 | | 16,383 | |
| **VCO Open Loop Phase Noise at fo @ 4 GHz** | | | | | |
| 10 kHz Offset | | | -78 | | dBc/Hz |
| 100 kHz Offset | | | -108 | | dBc/Hz |
| 1 MHz Offset | | | -134.5 | | dBc/Hz |
| 10 MHz Offset | | | -156 | | dBc/Hz |
| 100 MHz Offset | | | -167 | | dBc/Hz |

### Table 3. PLL & VCO Specifications *(Continued)*

| Parameter | Conditions | Min. | Typ. | Max. | Units |
|---|---|---|---|---|---|
| **VCO Open Loop Phase Noise at fo @ 3 GHz/2 = 1.5 GHz** | | | | | |
| 10 kHz Offset | | | -83 | | dBc/Hz |
| 100 kHz Offset | | | -113 | | dBc/Hz |
| 1 MHz Offset | | | -139.5 | | dBc/Hz |
| 10 MHz Offset | | | -165.5 | | dBc/Hz |
| 100 MHz Offset | | | -167 | | dBc/Hz |
| **Figure of Merit** | | | | | |
| Floor Integer Mode | Normalized to 1 Hz | | -230 | | dBc/Hz |
| Floor Fractional Mode | Normalized to 1 Hz | | -227 | | dBc/Hz |
| Flicker (Both Modes) | Normalized to 1 Hz | | -268 | | dBc/Hz |
| **VCO Characteristics** | | | | | |
| VCO Tuning Sensitivity at 3862 MHz | Measured at 2.5 V | | 15 | | MHz/V |
| VCO Tuning Sensitivity at 3643 MHz | Measured at 2.5 V | | 14.5 | | MHz/V |
| VCO Tuning Sensitivity at 3491 MHz | Measured at 2.5 V | | 16.2 | | MHz/V |
| VCO Tuning Sensitivity at 3044 MHz | Measured at 2.5 V | | 14.6 | | MHz/V |
| VCO Tuning Sensitivity at 2558 MHz | Measured at 2.5 V | | 15.4 | | MHz/V |
| VCO Tuning Sensitivity at 2129 MHz | Measured at 2.5 V | | 14.8 | | MHz/V |
| VCO Supply Pushing | Measured at 2.5 V | | 2 | | MHz/V |

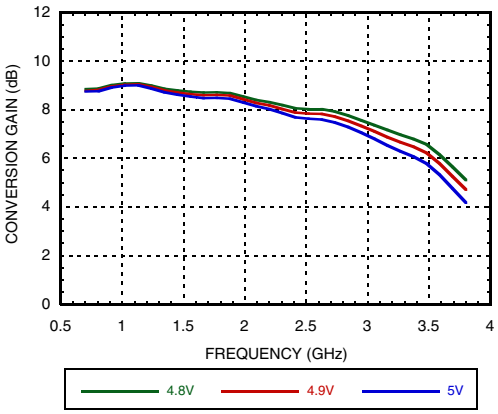
### Table 4. Enable/Disable Settling Time Specifications

| Parameter | Conditions | Min. | Typ. | Max. | Units |
|---|---|---|---|---|---|
| Enable Settling Time | Mixer Core Enabled | | 140 | | ns |
| Disable Settling Time | Mixer Core Disabled | | 110 | | ns |

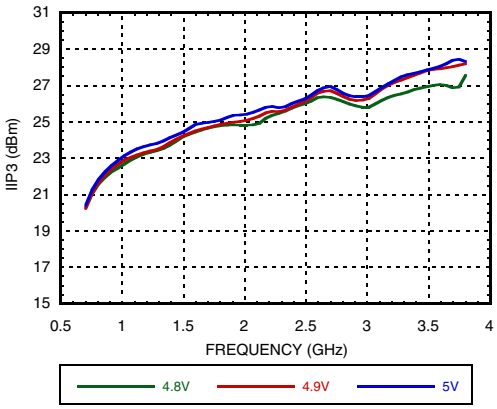
# BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER w/ Fractional-N PLL & VCO, 0.7 - 3.8 GHz



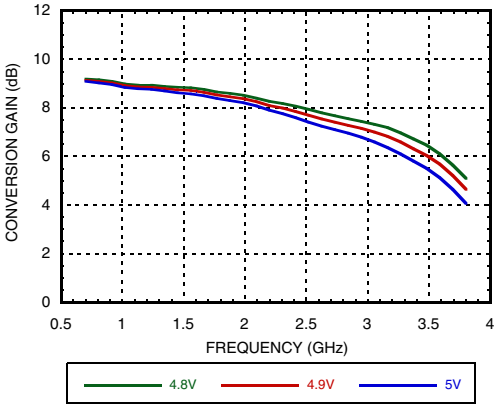
### Figure 1. Low Side LO Conversion Gain vs. VGATE [1] [2]



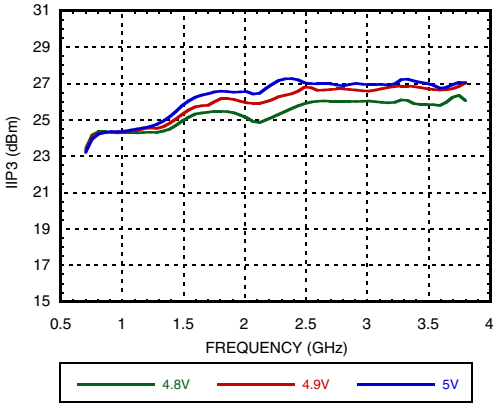

### Figure 2. Low Side LO Input IP3 vs. VGATE [1]



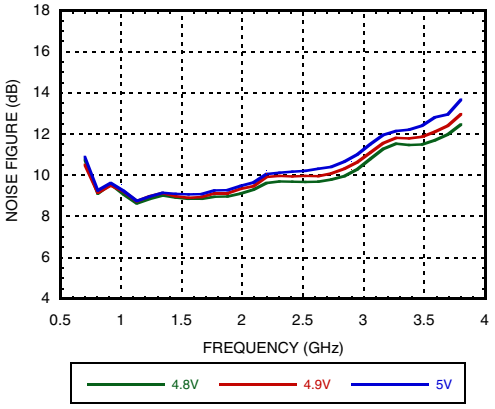

### Figure 3. High Side LO Conversion Gain vs. VGATE [1] [2]



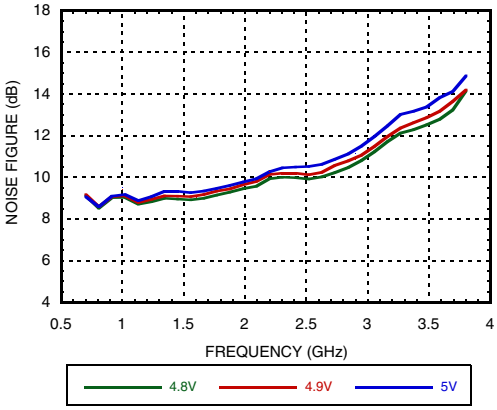

### Figure 4. High Side LO Input IP3 vs. VGATE [1]




### Figure 5. Low Side LO Noise Figure vs. VGATE [1]



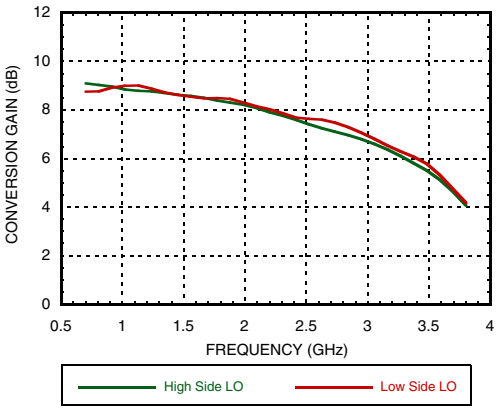

### Figure 6. High Side LO Noise Figure vs. VGATE [1]



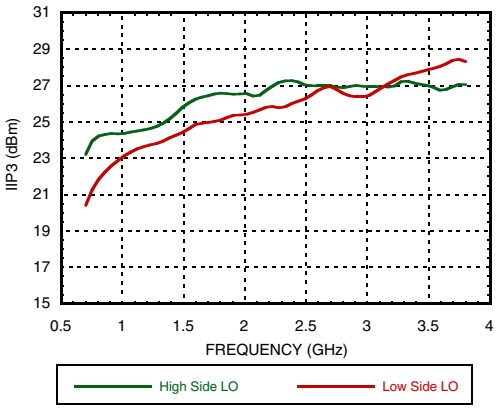

[1] VGATE is bias voltage for passive mixer cores (VGATE1 and VGATE2 pins). Refer to pin description table.

[2] Balun losses at IF output ports are de-embedded.

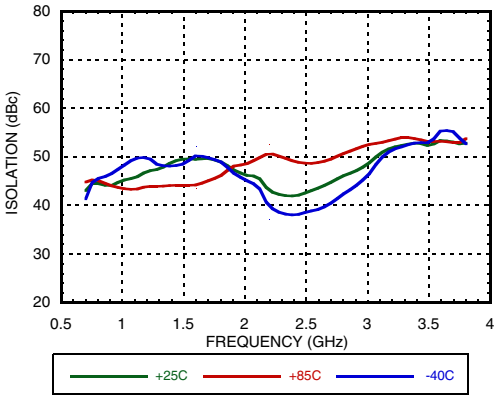
### Figure 7. Conversion Gain vs. High Side LO & Low Side LO [1][2]



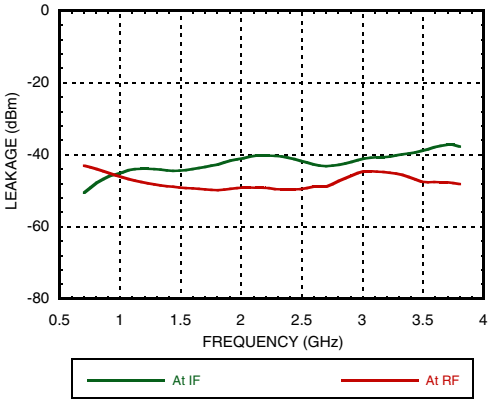

### Figure 8. Input IP3 vs. High Side LO & Low Side LO[2]



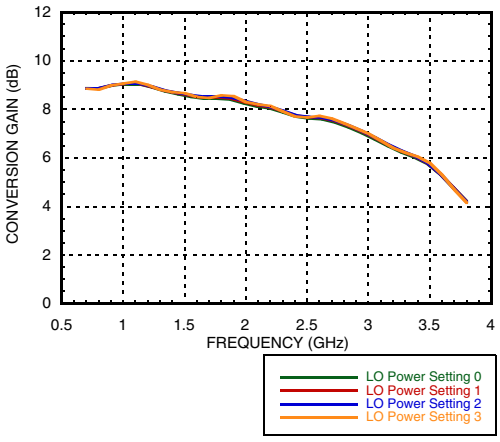

### Figure 9. RF/IF Isolation vs. Temperature[2][3]



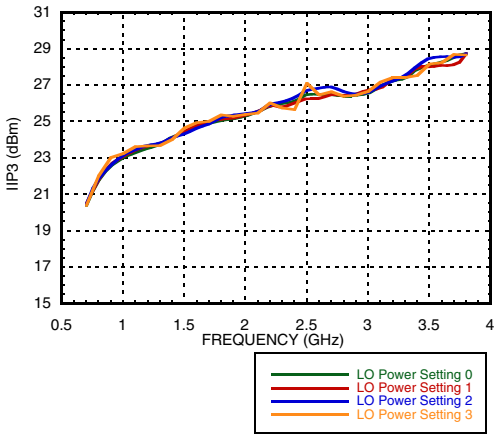

### Figure 10. LO Leakage vs. Frequency[2][3]




### Figure 11. Low Side LO Conversion Gain vs. LO Drive [1][2]




### Figure 12. Low Side LO Input IP3 vs. LO Drive[2]




[1] Balun losses at IF output ports are de-embedded.

[2] VGATE=5V

[3] For low side LO

**Figure 13. +2RF -2LO Response vs. Frequency over Temperature[1][2][3]**

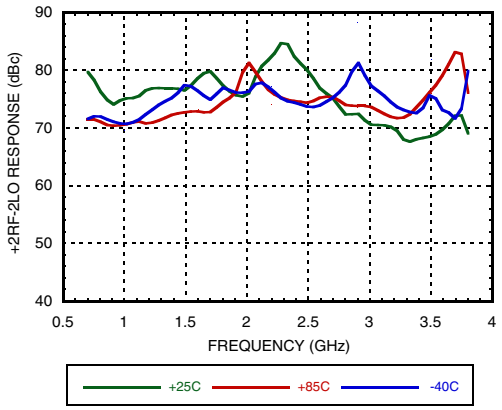



**Figure 14. +3RF -3LO Response vs. Frequency over Temperature[1][2][3]**

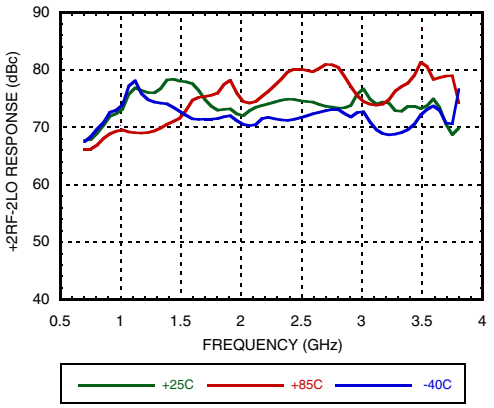



**Figure 15. RF Input Return Loss vs. Frequency over Temperature[3][4]**

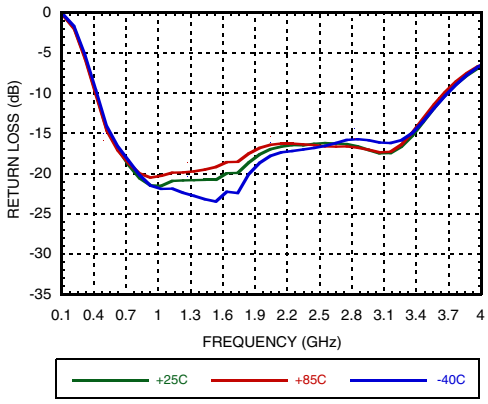



**Figure 16. IF Output Return Loss vs. Frequency over Temperature [3][4]**

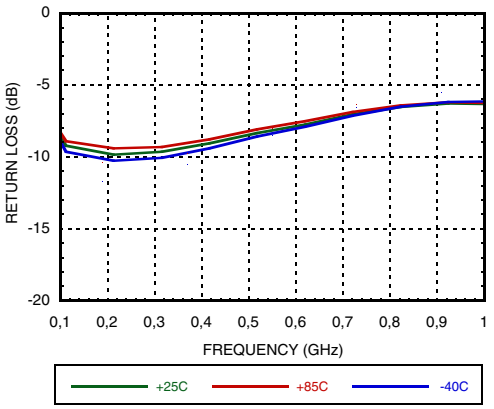



**Figure 17. High Side LO Input P1dB vs. Frequency over Temperature[3]**

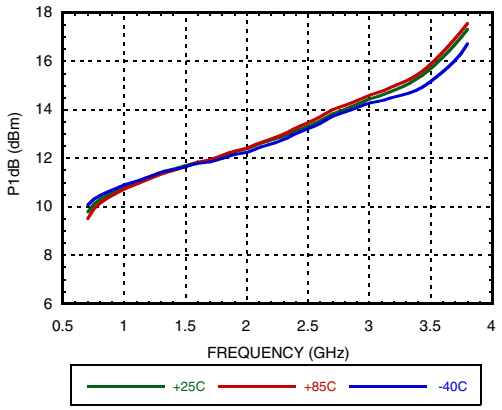
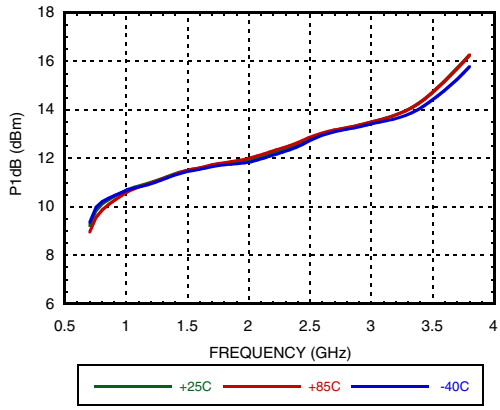



**Figure 18. Low Side LO Input P1dB vs. Frequency over Temperature[3]**




[1] Balun losses at IF output ports are de-embedded.

[2] Low side LO

[3] VGATE=5V

[4] LO input Frequency = 1900MHz, LO power setting is 3.

**Figure 19. Low Side LO Conversion Gain vs. Frequency at VGATE=5V [1][2]**

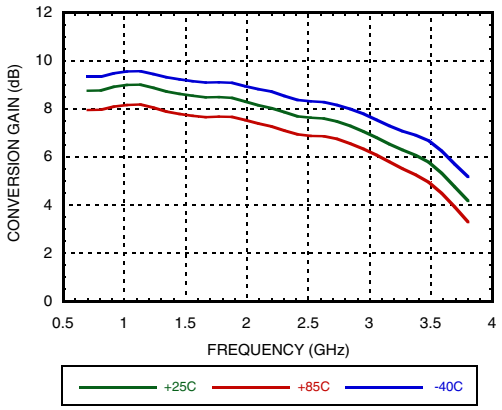



**Figure 20. Low Side LO Input IP3 vs. Frequency at VGATE=5V[2]**

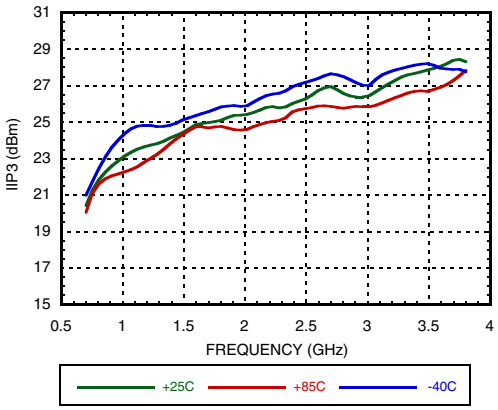



**Figure 21. High Side LO Conversion Gain vs. Frequency at VGATE=5V [1][2]**

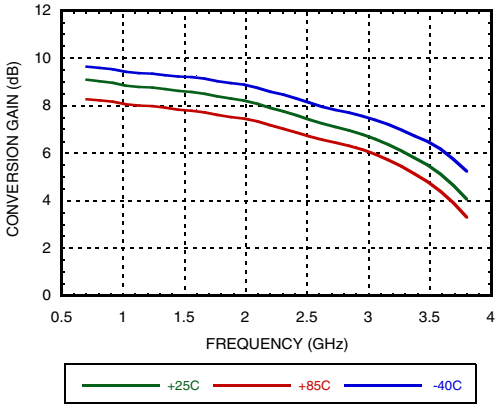



**Figure 22. High Side LO Input IP3 vs. Frequency at VGATE=5V[2]**

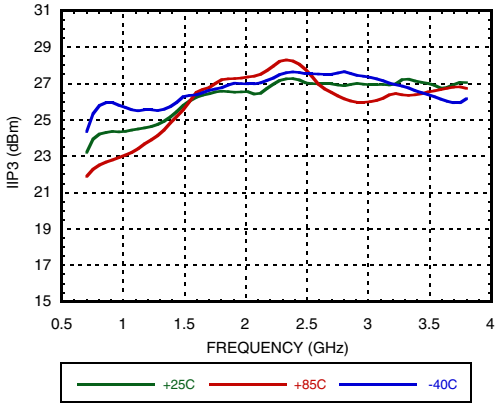



**Figure 23. Low Side LO Noise Figure vs. Temperature at VGATE=5V**

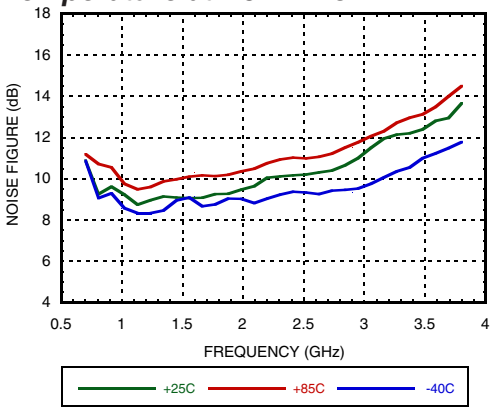
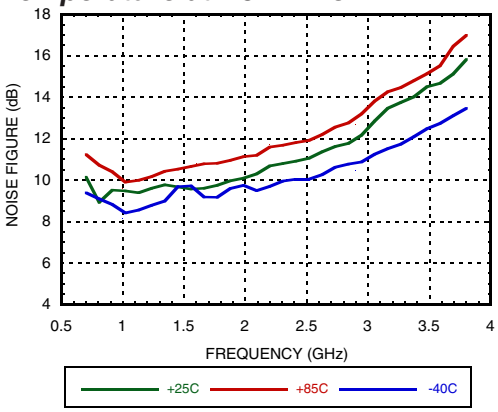



**Figure 24. High Side LO Noise Figure vs. Temperature at VGATE=5V**




[1] Balun losses at IF output ports are de-embedded.

[2] At room temperature

**Figure 25. Low Side LO Conversion Gain vs. Frequency at VGATE=4.9V [1][2]**

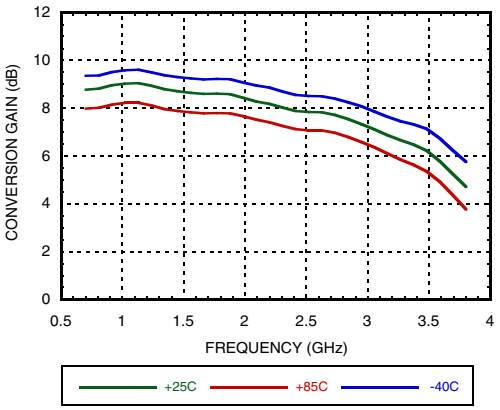



**Figure 26. Low Side LO Input IP3 vs. Frequency at VGATE=4.9V[2]**

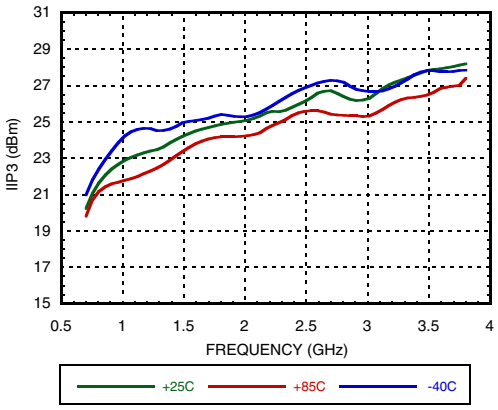



**Figure 27. High Side LO Conversion Gain vs. Frequency at VGATE=4.9V [1][2]**

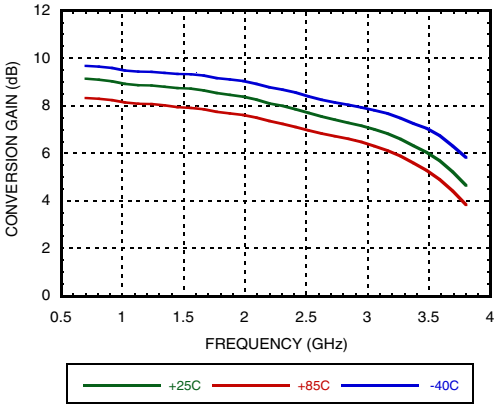



**Figure 28. High Side LO Input IP3 vs. Frequency at VGATE=4.9V[2]**

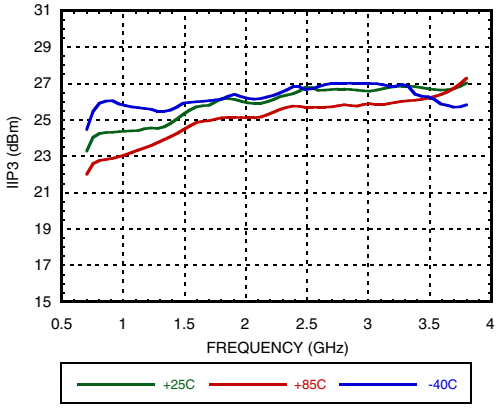



**Figure 29. Low Side LO Noise Figure vs. Temperature at VGATE=4.9V**

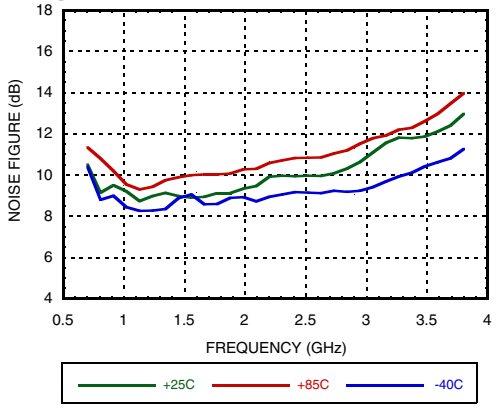
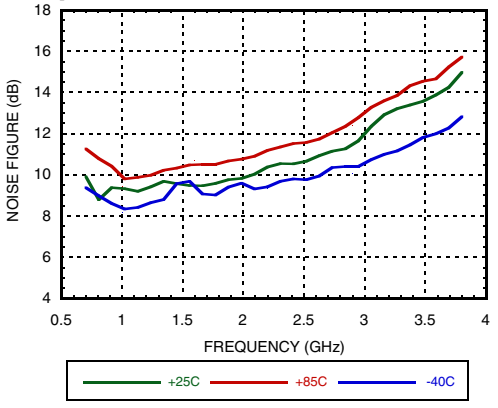



**Figure 30. High Side LO Noise Figure vs. Temperature at VGATE=4.9V**




[1] Balun losses at IF output ports are de-embedded.

[2] At room temperature

**Figure 31. Low Side LO Conversion Gain vs. Frequency at VGATE=4.8V [1][2]**

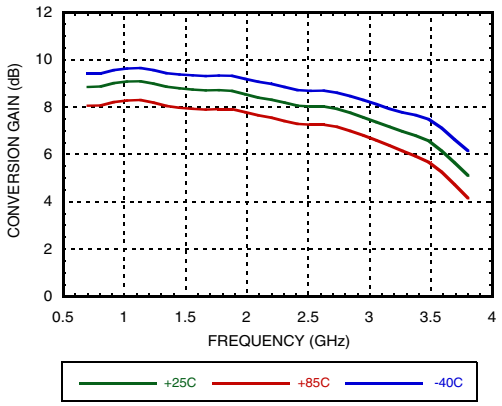



**Figure 32. Low Side LO Input IP3 vs. Frequency at VGATE=4.8V[2]**

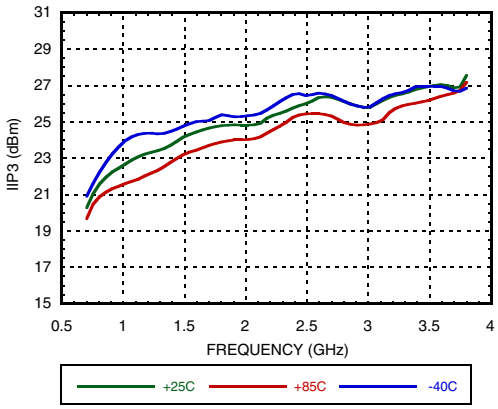



**Figure 33. High Side LO Conversion Gain vs. Frequency at VGATE=4.8V [1][2]**

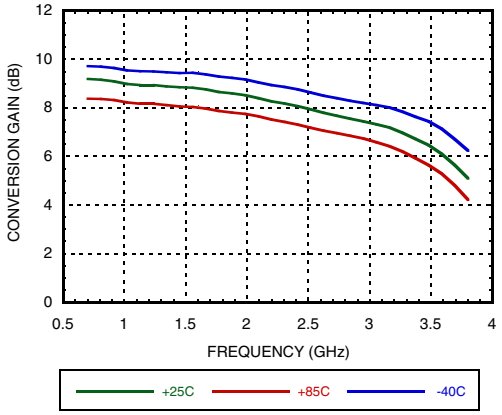



**Figure 34. High Side LO Input IP3 vs. Frequency at VGATE=4.8V[2]**

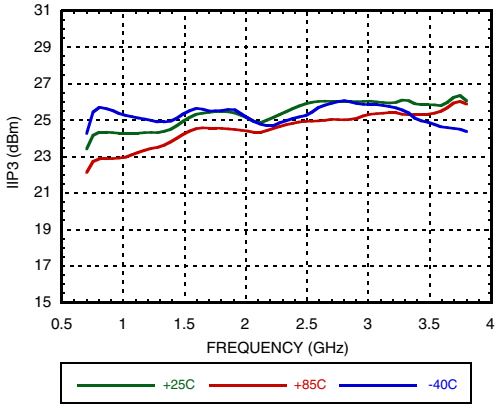



**Figure 35. Low Side LO Noise Figure vs. Temperature at VGATE=4.8V**

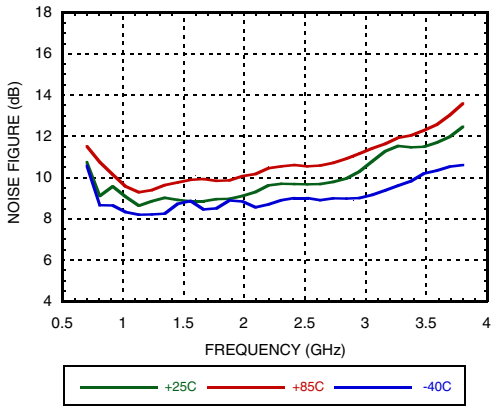
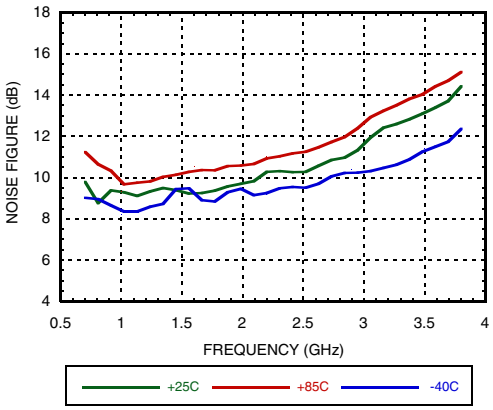


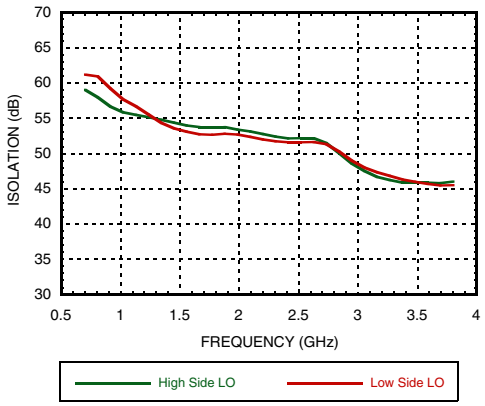

**Figure 36. High Side LO Noise Figure vs. Temperature at VGATE=4.8V**



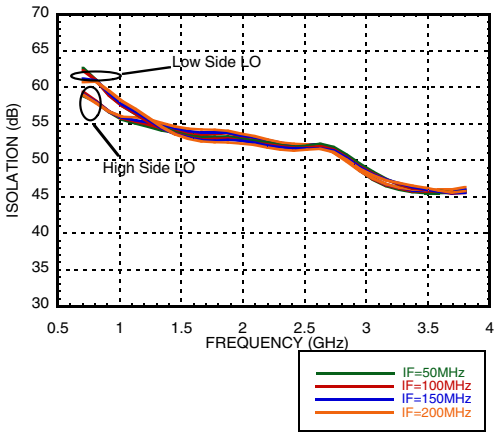

[1] Balun losses at IF output ports are de-embedded.

[2] At room temperature

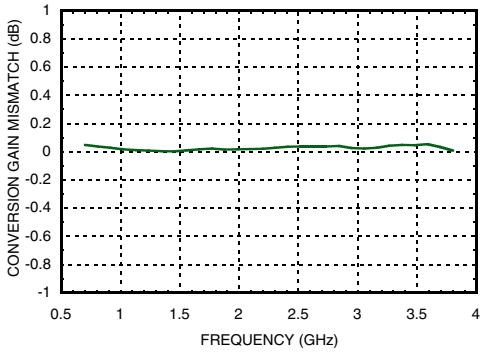
### Figure 37. Channel to Channel Isolation vs. Frequency



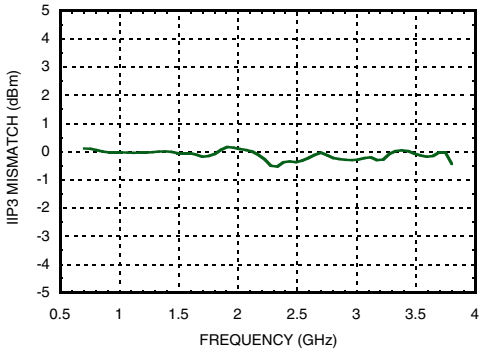

### Figure 38. Channel to Channel Isolation vs. IF Frequency



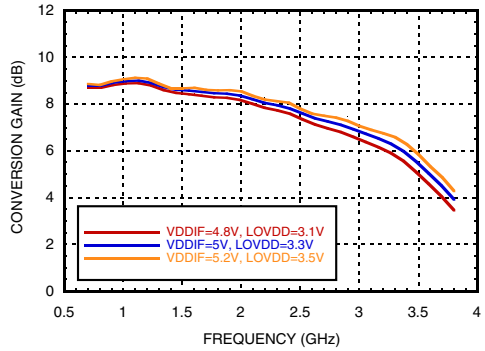

### Figure 39. Low Side LO Conversion Gain Mismatch at VGATE=5V [1]



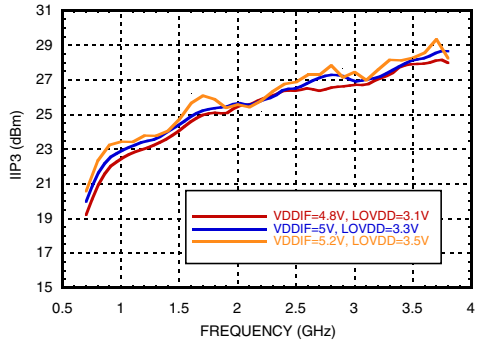

### Figure 40. Low Side LO Input IP3 Mismatch at VGATE=5V




### Figure 41. Low Side LO Conversion Gain vs. VGATE=VDDIF[1]




### Figure 42. Low Side LO Input IP3 vs. VGATE=VDDIF




[1] Balun losses at IF output ports are de-embedded.

**Figure 43. Conversion Gain vs. IF Frequency at RF=900 MHz, VGATE=5V [1]**

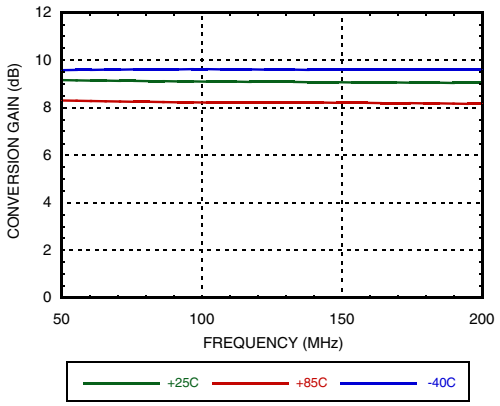



**Figure 44. IIP3 vs. IF Frequency at RF=900 MHz, VGATE=5V**

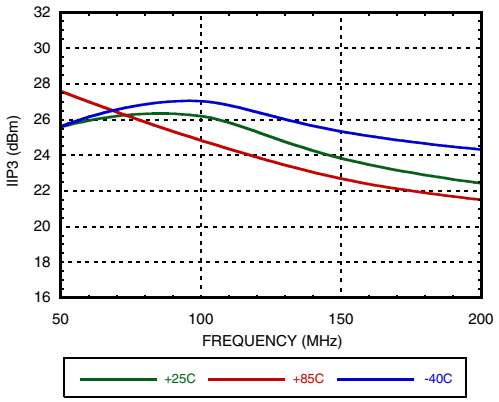



**Figure 45. Conversion Gain vs. IF Frequency at RF=1900 MHz, VGATE=5V [1]**

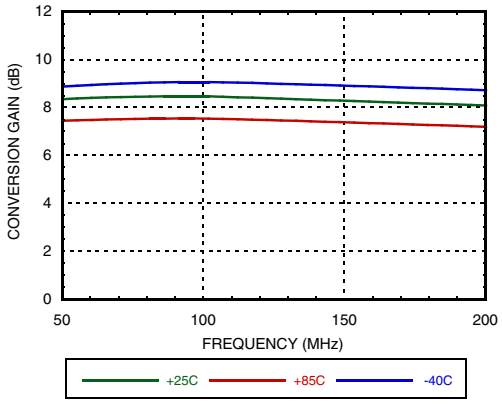



**Figure 46. IIP3 vs. IF Frequency at RF=1900 MHz, VGATE=5V**

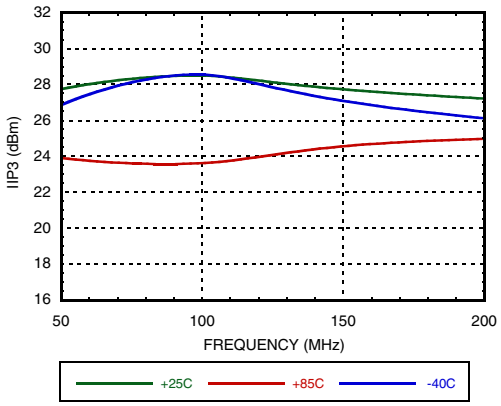



**Figure 47. Conversion Gain vs. IF Frequency at RF=2400 MHz, VGATE=5V [1]**

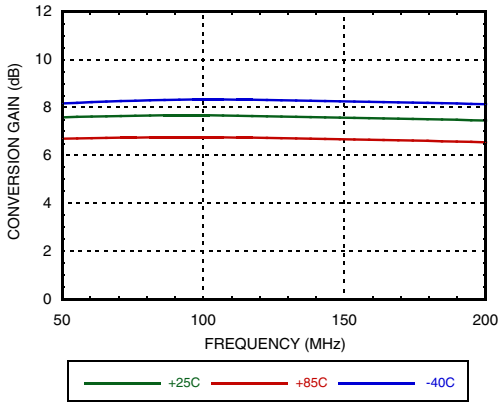
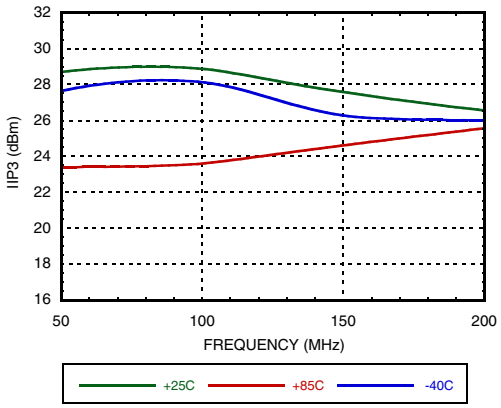



**Figure 48. IP3 vs. IF Frequency at RF=2400 MHz, VGATE=5V**




[1] Balun losses at IF output ports are de-embedded.

**Figure 49. Auxiliary LO Output, Open Loop Phase Noise at 3600 MHz**

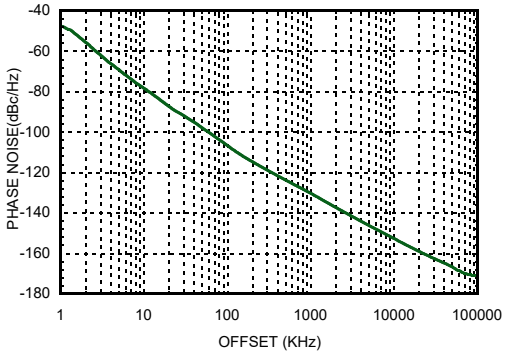



**Figure 50. Auxiliary LO Output, Fractional Mode Closed Loop Phase Noise at 3600 MHz with various divider ratios [1]**

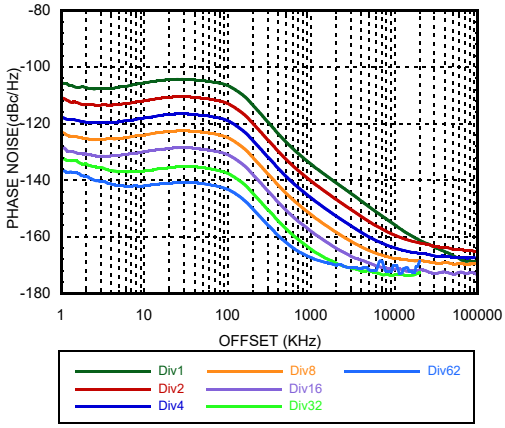



**Figure 51. Auxiliary LO Output, Open Loop Phase Noise at 4100 MHz**

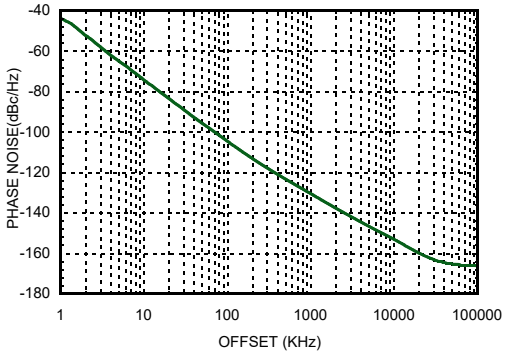



**Figure 52. Auxiliary LO Output, Fractional Mode Closed Loop Phase Noise at 4100 MHz with various divider ratios [1]**

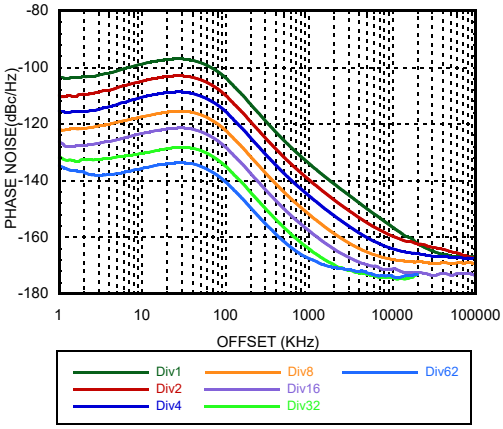
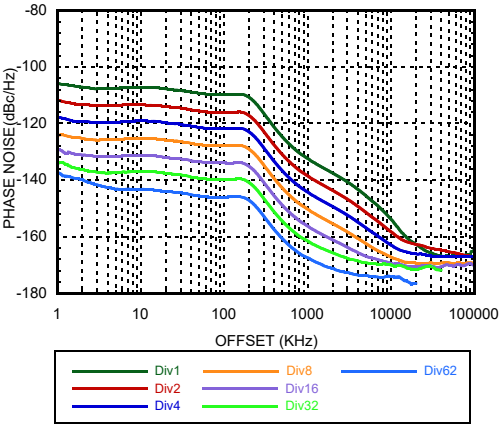


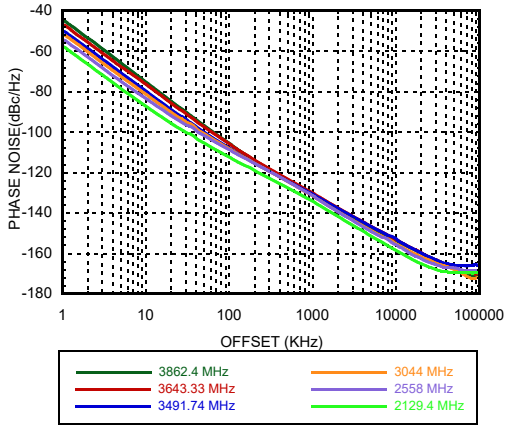

**Figure 53. Auxiliary LO Output, Fractional Mode Closed Loop Phase Noise at 3300 MHz with various divider ratios [2]**



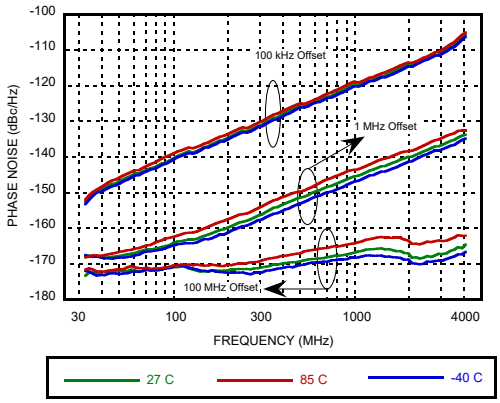

[1] Using 122.88 MHz clock input, 61.44 MHz PFD, 2.5 mA CP, 174 µA Leakage.

[2] Using 100 MHz clock input, 50MHz PFD, 2.5 mA CP, 174 µA Leakage

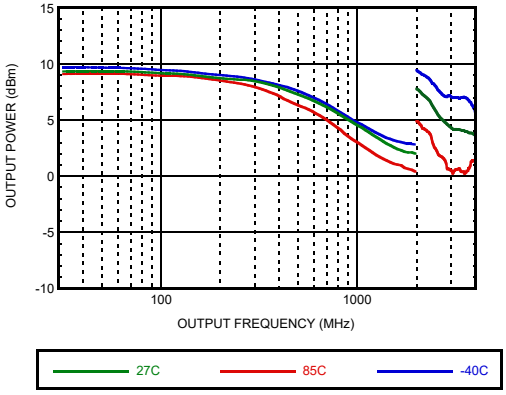
### Figure 54. Auxiliary LO Output, Open Loop Phase Noise vs. Frequency



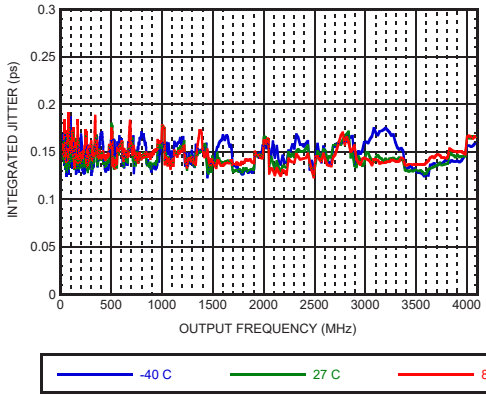

### Figure 55. Auxiliary LO Output, Open Loop Phase Noise vs. Temperature



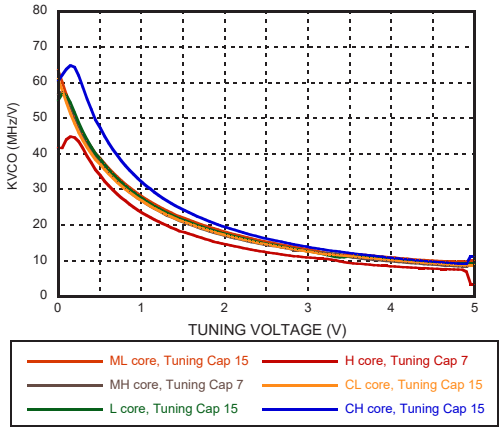

### Figure 56. Auxiliary LO Output Power vs. Temperature [1]



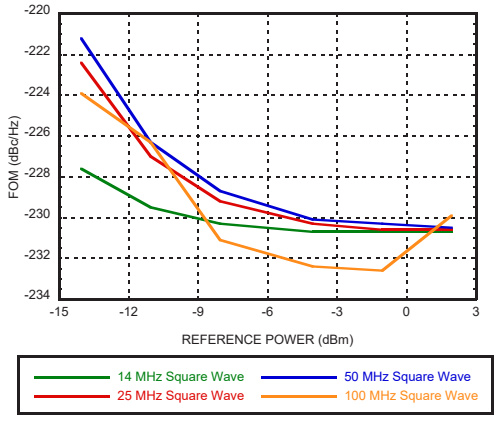

### Figure 57. Integrated RMS Jitter [2]




### Figure 58. Typical VCO Sensitivity

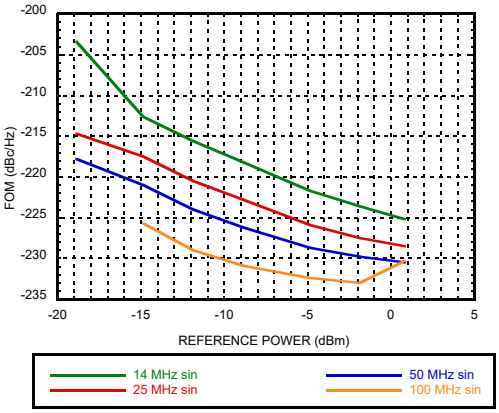



### Figure 59. Reference Input Sensitivity, Square Wave, 50 Ω [3]

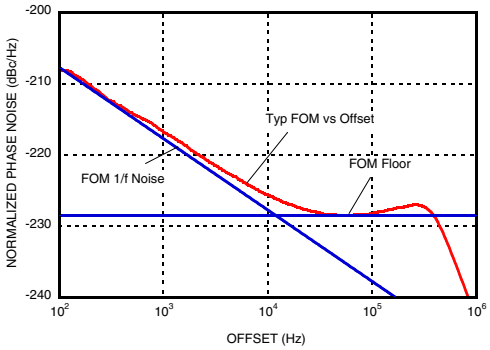



[1] Both Aux. LO and MOD LO Gain Set to '3' (Max Level), both Aux. LO and MOD LO Buffer Enabled, measured from Auxiliary LO Port.
[2] RMS Jitter data is measured in fractional mode using 50 MHz reference frequency, from 1 kHz to 100 MHz integration bandwidth.
[3] Measured from a 50 Ω source with a 100 Ω external resistor termination. See PLL with Integrated RF VCOs Operating Guide Reference Input Stage section for more details. Full FOM performance up to maximum 3.3 Vpp input voltage.

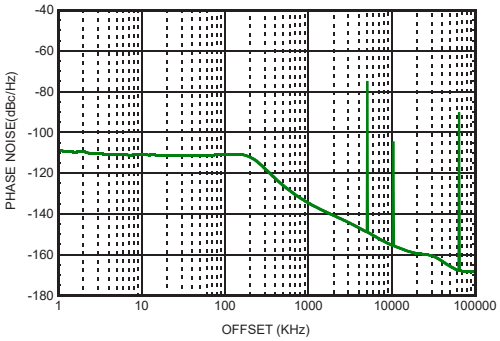
### Figure 60. Reference Input Sensitivity, Sinusoid Wave, 50 Ω [1]



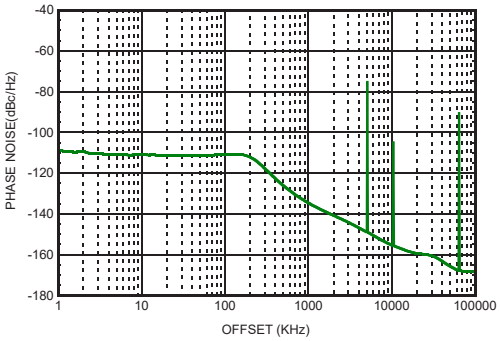

### Figure 61. Figure of Merit for PLL/VCO



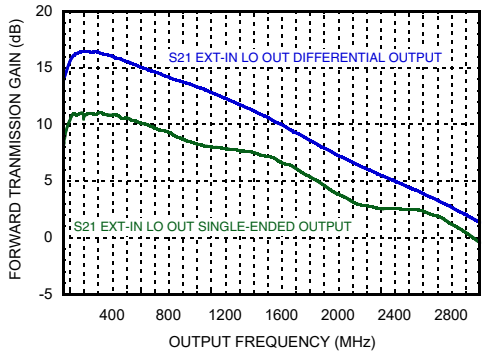

### Figure 62. Fractional-N Spurious Performance at 2646.96 MHz Exact Frequency Mode ON [2]



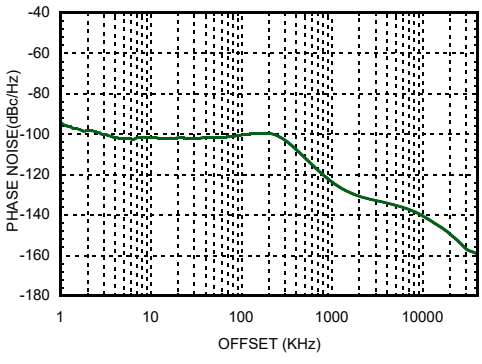

### Figure 63. Fractional-N Spurious Performance at 2646.96 MHz Exact Frequency Mode OFF [2]




### Figure 64. Forward Transmission Gain [3]




### Figure 65. Closed Loop Phase Noise With External VCO HMC384LP4E at 2200 MHz




[1] Measured from a 50 Ω source with a 100 Ω external resistor termination. See PLL with Integrated RF VCOs Operating Guide Reference Input Stage section for more details. Full FOM performance up to maximum 3.3 Vpp input voltage.

[2] 122.88 MHz clock input, PFD = 61.44 MHz, Channel Spacing = 240 kHz.

[3] S21 from Ext_VCO (pin 43, 44) in and LO (pin32, 33) out.

*Figure 66. Auxiliary LO Differential Output Return Loss*

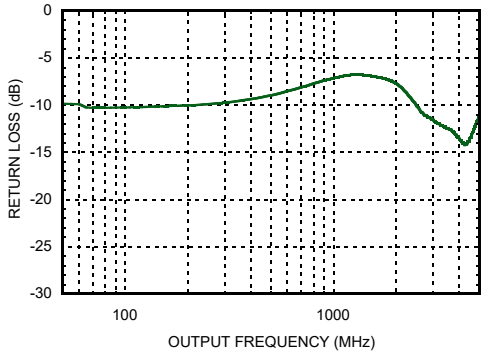



*Figure 67. Auxiliary LO Single Ended Output Return Loss*

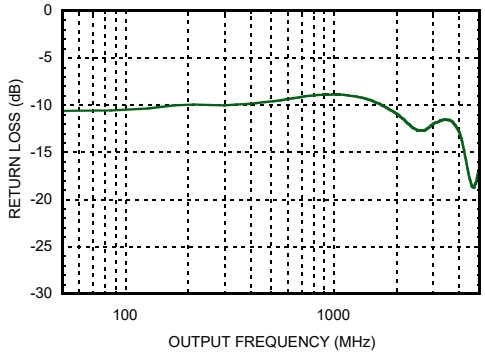
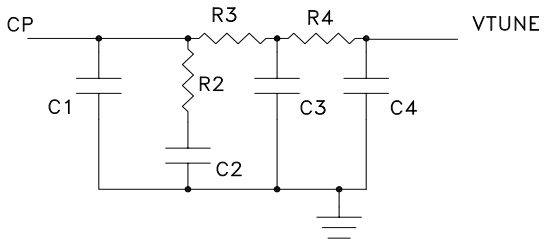



*Table 5. Loop Filter Configuration*

| Loop Filter BW (kHz) | C1 (pF) | C2 (nF) | C3 (pF) | C4 (pF) | R2 (kΩ) | R3 (kΩ) | R4 (kΩ) | Loop Filter Design |
|---|---|---|---|---|---|---|---|---|
| 156 | 180 | 6.8 | 47 | 47 | 2.2 | 1 | 1 |  |

### Table 6. Harmonics of LO

| | nLO Spur at RF Port | | | |
|---|---|---|---|---|
| LO Frequency (GHz) | 1 | 2 | 3 | 4 |
| 0.7 | -65 | -45 | -67 | -63 |
| 1.1 | -80 | -55 | -64 | -67 |
| 1.5 | -59 | -58 | -65 | -62 |
| 1.9 | -59 | -54 | -72 | -64 |
| 2.3 | -60 | -59 | -73 | -63 |
| 2.7 | -59 | -58 | -82 | -55 |
| 3.1 | -60 | -58 | -77 | -48 |
| 3.5 | -53 | -63 | -73 | -48 |

LO = Maximum level
All values in dBm measured at RF port.

### Table 7. MxN Spurious at IF Port

| | nLO | | | | |
|---|---|---|---|---|---|
| mRF | 0 | 1 | 2 | 3 | 4 |
| 0 | xx | -44 | -52 | -52 | -55 |
| 1 | -49 | 0 | -44 | -17 | -52 |
| 2 | -87 | -45 | -72 | -50 | -80 |
| 3 | -88 | -62 | -88 | -71 | -87 |
| 4 | -85 | -85 | -88 | -88 | -87 |

RF Frequency = 0.9 GHz at-5 dBm
LO Frequency = 0.8 GHz at maximum level
All values in dBc below IF power level (1RF - 1LO).

### Table 8. MxN Spurious at IF Port

| | nLO | | | | |
|---|---|---|---|---|---|
| mRF | 0 | 1 | 2 | 3 | 4 |
| 0 | xxx | -44 | -49 | -64 | -49 |
| 1 | -54 | 0 | -43 | -28 | -65 |
| 2 | -83 | -49 | -76 | -57 | -84 |
| 3 | -87 | -72 | -86 | -88 | -85 |
| 4 | -83 | -83 | -85 | -85 | -87 |

RF Frequency = 1.9 GHz at-5 dBm
LO Frequency = 1.8 GHz at maximum level
All values in dBc below IF power level (1RF - 1LO).

### Table 9. MxN Spurious at IF Port

| | nLO | | | | |
|---|---|---|---|---|---|
| mRF | 0 | 1 | 2 | 3 | 4 |
| 0 | xxx | -44 | -47 | -65 | -53 |
| 1 | -58 | 0 | -46 | -40 | -68 |
| 2 | -80 | -60 | -75 | -67 | -85 |
| 3 | -82 | -82 | -86 | -83 | -85 |
| 4 | -84 | -82 | -85 | -85 | -87 |

RF Frequency = 2.5 GHz at -5 dBm
LO Frequency = 2.4 GHz at maximum level
All values in dBc below IF power level (1RF - 1LO).

### Table 10. Truth Table [1]

| CHIPEN (V) | PLL/VCO |
|---|---|
| LOW | OFF |
| HIGH | ON |

[1] IF and LO amplifiers can be disabled through SPI bus. See `Enabling/Disabling Mixer Features` application section.

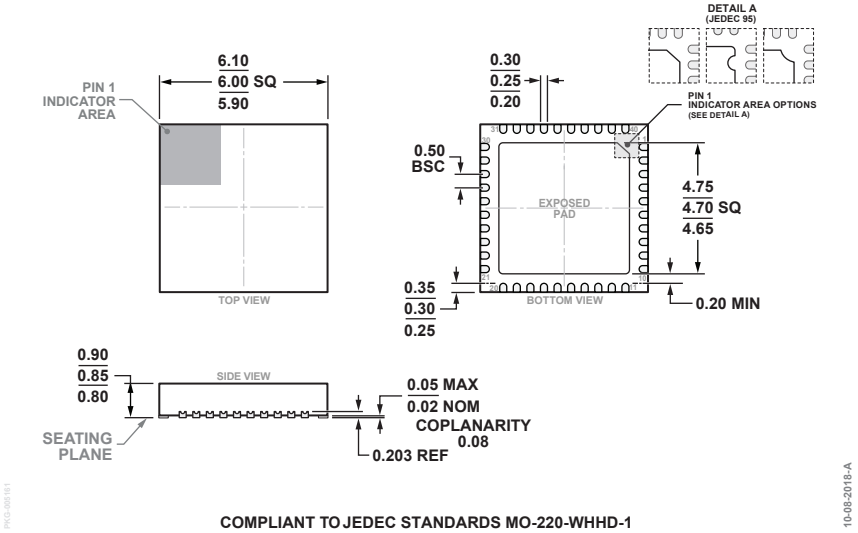
## Absolute Maximum Ratings

| | |
|---|---|
| RF Input Power (VBIASIF1,2= 5V, LOVDD=3.3V) | 20 dBm |
| VBIASIF1,2, LOVDD | 6V |
| VGATE1,2, VDDCP, VCS1, VCS2, LOVDD | -0.3V to 5.5V |
| 3VRVDD, DVDD3V | -0.3V to 3.6V |
| Max. Channel Temperature | 150°C |
| Thermal Resistance (channel to ground paddle) | 3.3°C/W |
| Storage Temperature | -65°C to 150°C |
| Operating Temperature | -40°C to 85°C |
| ESD Sensitivity (HBM) | Class 1B |
| ESD Sensitivity (FICDM) | Class IV |

## Recommended Operating Conditions

| | |
|---|---|
| VDDCP, VCS1, VCS2, VBIASIF1, VBIASIF2,LOBIAS1,LOBIAS2,VCC1,VCC2,VGATE1,VGATE2,VDDLS | 5 V |
| LOVDD, 3VRVDD, DVDD3V, VCCPD, VCCPS, VCCHF | 3.3 V |
| Operating Temperature | -40°C to +85°C |

## Outline Drawing




COMPLIANT TO JEDEC STANDARDS MO-220-WHHD-1

40-Lead Lead Frame Chip Scale Package [LFCSP]
6 mm × 6 mm Body and 0.85 mm Package Height
(CP-40-19)
Dimensions in millimeters

## Package Information

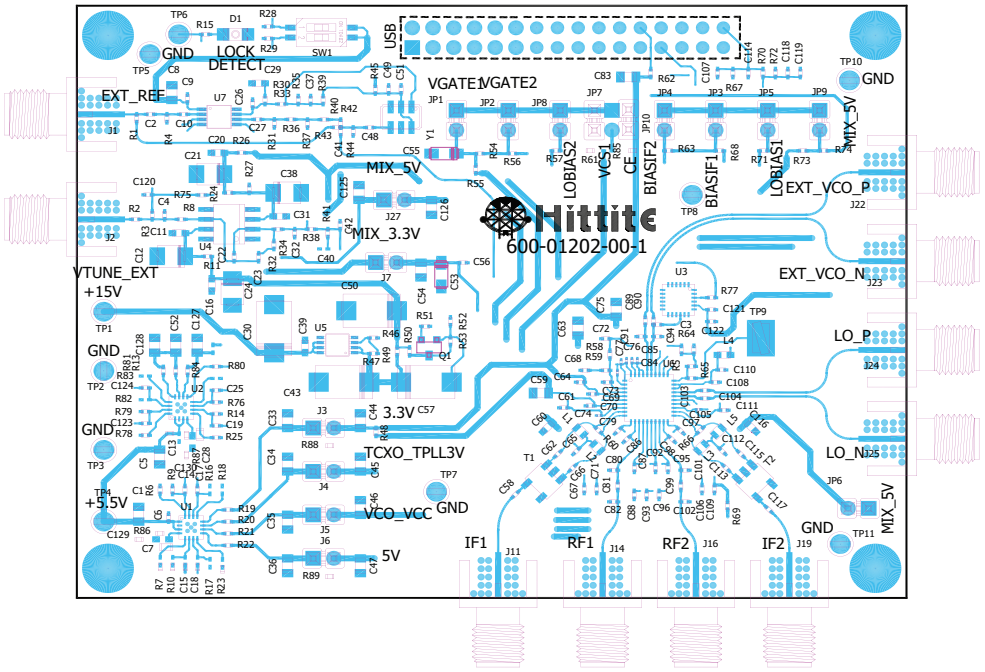
| Part Number | Package Body Material | Lead Finish | MSL Rating [2] | Package Marking [1] |
|---|---|---|---|---|
| HMC1190ALP6NE | RoHS-compliant Low Stress Injection Molded Plastic | NiPdAu | MSL3 | H1190A<br>XXXX |

[1] 4-Digit lot number XXXX
[2] Max peak reflow temperature of 260 °C

## Pin Descriptions

| Pin Number | Function | Description |
|---|---|---|
| 1 | VDDCP | Power Supply for Charge Pump Analog Section. |
| 2 | BIAS | External Bypass Decoupling for Precision Bias Circuits. |
| 3,4 | CP1,CP2 | Charge Pump Outputs. |
| 5 | 3VRVDD | Reference supply, 3.3 V nominal. |
| 6 | XREFP | Reference Input. The DC bias is generated internally. Normally, it is AC coupled externally. |
| 7 | DVDD3V | DC Power Supply for Digital (CMOS) Circuitry, 3.3 V nominal. |
| 8,23 | VCS1, VCS2 | Bias Control for IF Amplifiers. Connect these pins to a 5V supply through 590 Ohms resistors. Refer to application section for proper values of resistors to adjust IF amplifier current. |
| 9 | IF1N | Differential IF outputs. Connect these pins to a 5V supply through choke inductors. See the evaluation board schematic available on the HMC1190A product page. |
| 10 | IF1P | |
| 21 | IF2P | |
| 22 | IF2N | |
| 11, 20 | VBIASIF1, VBIASIF2 | Supply voltage pin for IF amplifier's bias circuits. Connect to 5V supply through filtering. |
| 12, 19 | VGATE1, VGATE2 | Bias pins for mixer cores. Set from 4.8V to 5V for operating frequency band. |
| 13, 18 | RF1, RF2 | RF Input Pins of the Mixer. These pins are internally matched to 50 Ohms. RF input pins require off chip DC blocking capacitors. See the evaluation board schematic available on the HMC1190A product page. |
| 14, 17 | LOBIAS2, LOBIAS1 | Bias control pins for Local Oscillator Amplifiers. Connect these pins to a 5V supply through 270 Ohms resistors. Refer to application section for proper values of resistors to adjust LO amplifier current. |
| 15,24 | RSV | Reserved. These pins are reserved for internal use; leave them floating. |
| 16 | LOVDD | 3.3V Bias Supply for LO Drive Stages. Refer to application circuit for appropriate filtering and bias generation information. |
| 25 | CHIP_EN | Chip Enable. Connect to logic high for normal operation. |
| 26 | LO_N | Negative Local Oscillator output. This pin is used for single-ended, differential, or dual output mode. |
| 27 | LO_P | Positive Local Oscillator output. This pin is used for differential or dual output mode only. Whereas it can drive a separate load from LO_N, it cannot be used when LO_N is disabled. |
| 28 | VCC1 | VCO Analog Supply1, 5V nominal. |
| 29 | VCC2 | VCO Analog Supply 2, 5V nominal. |
| 30 | VTUNE | VCO Varactor. VTUNE is the tuning port input. |
| 31 | SEN | PLL Serial Port Enable (CMOS) Logic Input. |
| 32 | SDI | PLL Serial Port Data (CMOS) Logic Input. |
| 33 | SCK | PLL Serial Port Clock (CMOS) Logic Input. |
| 34 | LD/SDO | Lock Detect/Serial Data or General Purpose (CMOS) Logic Output (GPO). This is a multifunction pin. |
| 35 | EXT_VCO_N | External VCO negative input |
| 36 | EXT_VCO_P | External VCO positive input. |
| 37 | VCCHF | Analog supply, 3.3 V nominal |
| 38 | VCCPS | Analog supply, Prescaler, 3.3 V nominal |
| 39 | VCCPD | Analog supply, Phase Detector, 3.3 V nominal |
| 40 | VDDLS | Analog supply, Charge Pump, 5 V nominal |

## Evaluation PCB




The circuit board used in the application should use RF circuit design techniques. Signal lines should have 50 Ohm impedance while the package ground leads and exposed paddle should be connected directly to the ground plane similar to that shown. A sufficient number of via holes should be used to connect the top and bottom ground planes. All evaluation board related drawings are available under Evaluation Kits tab of product page www.analog.com/HMC1190A

## Evaluation Order Information

| Item | Contents | Part Number |
|---|---|---|
| Evaluation PCB Only | HMC1190ALP6NE Evaluation PCB | EV1HMC1190ALP6N [1] |
| Evaluation Kit | HMC1190ALP6NE Evaluation PCB<br>USB Interface Board<br>6' USB A Male to USB B Female Cable | EK1HMC1190ALP6N [2] |

[1] Reference this number when ordering Evaluation PCB Only
[2] Reference this number when ordering an HMC1190ALP6NE Evaluation KIt

## 1.0 Theory of Operation

The block diagram of HMC1190ALP6NE PLL with Integrated VCO is shown in Figure 66

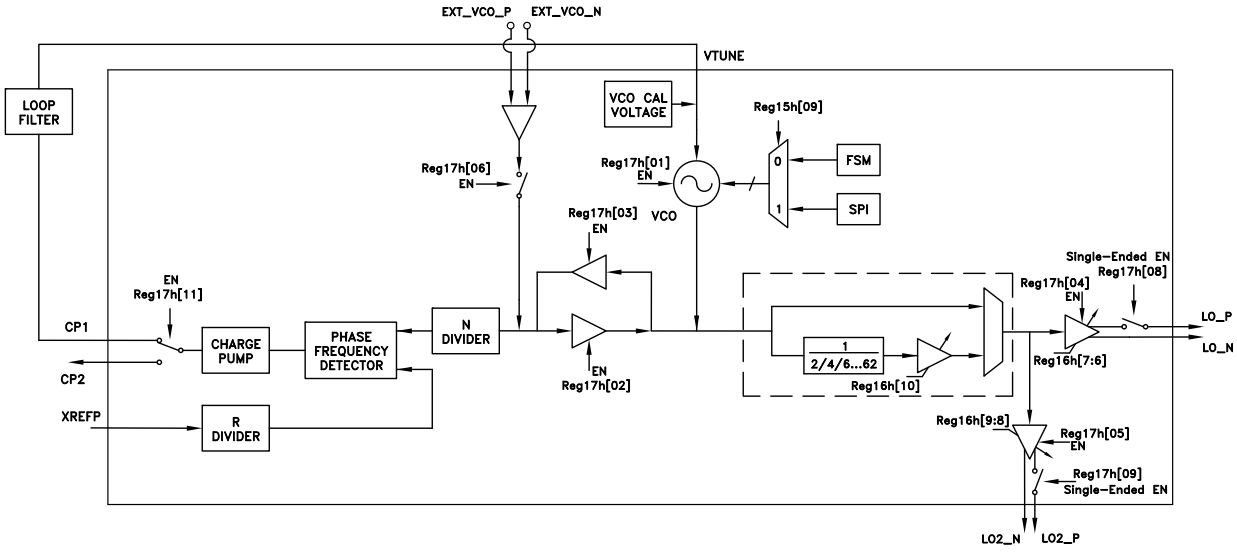



*Figure 66. HMC1190ALP6NE PLL VCO Block Diagram*

## 1.1 VCO Overview

The VCO consists of a capacitor switched step tuned VCO and an output stage. In typical operation, the VCO is programmed with the appropriate capacitor switch setting which is executed automatically by the PLL AutoCal state machine if AutoCal is enabled (Reg 0Ah[11] = 0, see section VCO Calibration for more information). The VCO tunes to the fundamental frequency (2050 MHz to 4100 MHz), and is locked by the CP output from the PLL subsystem. The VCO controls the output stage of the HMC1190ALP6NE enabling configuration of:

- VCO Output divider settings configured in Reg 16h (divide by 2/4/6...60/62 to generate frequencies from 33 MHz to 2050 MHz, or divide by 1 to generate fundamental frequencies between 2050 MHz and 4100 MHz)
- Output gain settings (Reg 16h[7:6], Reg 16h[9:8])
- Single-ended or differential output operation (Reg 17h[9:8])
- Always Mute (Reg 16h[5:0])
- Mute when unlock (Reg 17h[7])

### 1.1.1 VCO Calibration

#### 1.1.1.1 VCO Auto-Calibration (AutoCal)

The HMC1190ALP6NE uses a step tuned type VCO. A step tuned VCO is a VCO with a digitally selectable capacitor bank allowing the nominal center frequency of the VCO to be adjusted or 'stepped' by switching in/out VCO tank capacitors. A step tuned VCO allows the user to center the VCO on the required output frequency while keeping the varactor tuning voltage optimized near the mid-voltage tuning point of the HMC1190ALP6NE's charge pump. This enables the PLL charge pump to tune the VCO over the full range of operation with both a low tuning voltage and a low tuning sensitivity (kvco).

The VCO switches are normally controlled automatically by the HMC1190ALP6NE using the Auto-Calibration feature. The Auto-Calibration feature is implemented in the internal state machine. It manages the selection of the VCO sub-band (capacitor selection) when a new frequency is programmed. The VCO switches may also be controlled directly via register Reg 15h for testing or for other special purpose operation.

To use a step tuned VCO in a closed loop, the VCO must be calibrated such that the HMC1190ALP6NE knows which switch position on the VCO is optimum for the desired output frequency. The HMC1190ALP6NE supports Auto-Calibration (AutoCal) of the step tuned VCO. The AutoCal fixes the VCO tuning voltage at the optimum mid-point of the charge pump output, then measures the free running VCO frequency while searching for the setting which results in the free running output frequency that is closest to the desired phase locked frequency. This procedure results in a phase locked oscillator that locks over a narrow voltage range on the varactor. A typical tuning curve for a step tuned VCO is shown in Figure 67.Note how the tuning voltage stays in a narrow range over a wide range of output frequencies such as fast frequency hopping.

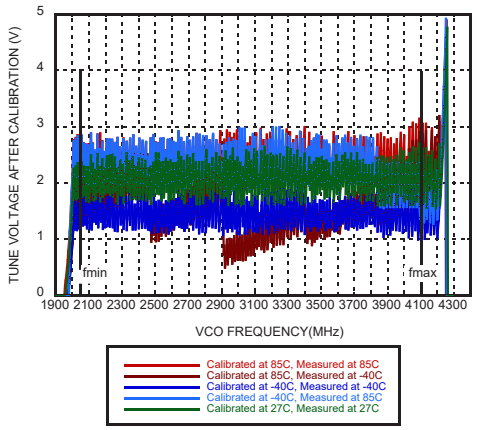



*Figure 67.Typical VCO Tuning Voltage After Calibration*

The calibration is normally run automatically once for every change of frequency. This ensures optimum selection of VCO switch settings vs. time and temperature. The user does not normally have to be concerned about which switch setting is used for a given frequency as this is handled by the AutoCal routine. The accuracy required in the calibration affects the amount of time required to tune the VCO. The calibration

routine searches for the best step setting that locks the VCO at the current programmed frequency, and ensures that the VCO will stay locked and perform well over it's full temperature range without additional calibration, regardless of the temperature that the VCO was calibrated at.

Auto-Calibration can also be disabled allowing manual VCO tuning. Refer to section Manual VCO Calibration for Fast Frequency Hopping for a description of manual tuning.

#### 1.1.1.1.1 Auto-reLock on Lock Detect Failure

It is possible by setting Reg 0Ah[17] to have the VCO subsystem automatically re-run the calibration routine and re-lock itself if Lock Detect indicates an unlocked condition for any reason. With this option the system will attempt to re-Lock only once.

#### 1.1.1.1.2 VCO AutoCal on Frequency Change

Assuming Reg 0Ah[11]=*0*, the VCO calibration starts automatically whenever a frequency change is requested. If it is desired to rerun the AutoCal routine for any reason, at the same frequency, simply rewrite the frequency change with the same value and the AutoCal routine will execute again without changing final frequency.

#### 1.1.1.1.3 VCO AutoCal Time & Accuracy

The VCO frequency is counted for $T_{mmt}$, the period of a single AutoCal measurement cycle.

$$T_{mmt} = T_{xtal} \cdot R \cdot 2^n \quad \text{(EQ 1)}$$

n — is set by Reg 0Ah[2:0] and results in measurement periods which are multiples of the PD period, $T_{xtal}R$.

*R* — is the reference path division ratio currently in use, Reg 02h

$T_{xtal}$ — is the period of the external reference (crystal) oscillator.

The VCO AutoCal counter will, on average, expect to register N counts, rounded down (floor) to the nearest integer, every PD cycle.

*N* — is the ratio of the target VCO frequency, $f_{vco}$, to the frequency of the PD, $f_{pd}$, where N can be any rational number supported by the N divider.

N is set by the integer ($N_{int}$ = Reg 03h) and fractional ($N_{frac}$ = Reg 04h) register contents

$$N = N_{int} + N_{frac} / 2^{24} \quad \text{(EQ 2)}$$

The AutoCal state machine runs at the rate of the FSM clock, $T_{FSM}$, where the FSM clock frequency cannot be greater than 50 MHz.

$$T_{FSM} = T_{xtal} \cdot 2^m \quad \text{(EQ 3)}$$

m — is 0, 2, 4 or 5 as determined by Reg 0Ah[14:13]

The expected number of VCO counts, V, is given by

$$V = floor\ (N \cdot 2^n) \quad \text{(EQ 4)}$$

The nominal VCO frequency measured, $f_{vcom}$, is given by

$$f_{vcom} = V \cdot f_{xtal} / (2^n \cdot R) \quad \text{(EQ 5)}$$

where the worst case measurement error, $f_{err}$ , is:

$$f_{err} \approx \pm f_{pd} / 2^{n+1} \quad \text{(EQ 6)}$$

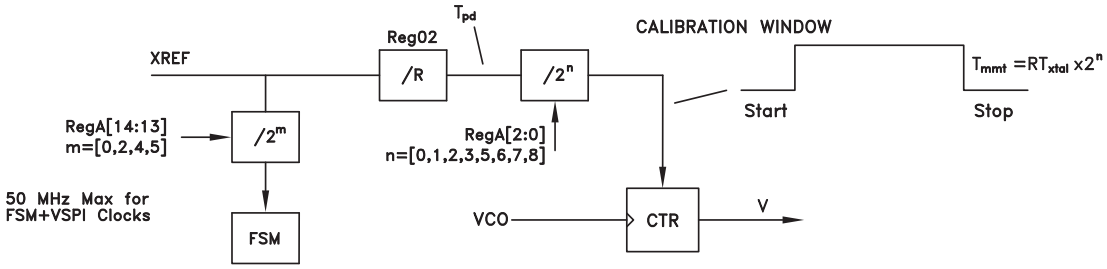



*Figure 68. VCO Calibration*

A 5-bit step tuned VCO, for example, nominally requires 5 measurements for calibration, worst case 6 measurements, and hence 7 VSPI data transfers of 20 clock cycles each. Total calibration time, worst case, is given by:

$$T_{cal} = k128T_{FSM} + 6T_{PD}\,2^{n} + 7 \cdot 20T_{FSM} \quad \text{(EQ 7)}$$

or equivalently

$$T_{cal} = T_{xtal}\,(6R \cdot 2^{n} + (140+(3 \cdot 128)) \cdot 2^{m}) \quad \text{(EQ 8)}$$

For guaranteed hold of lock, across temperature extremes, the resolution should be better than 1/8th the frequency step caused by a VCO sub-band switch change. Better resolution settings will show no improvement.

### 1.1.1.1.4 VCO AutoCal Example

The HMC1190ALP6NE must satisfy the maximum $f_{pd}$ limited by the two following conditions:

a. N ≥ 16 ($f_{int}$), N ≥ 20.0 ($f_{frac}$), where N = $f_{VCO}$ / $f_{pd}$

b. $f_{pd}$ ≤ 100 MHz

Suppose the HMC1190ALP6NE output frequency is to operate at 2.01 GHz. Our example crystal frequency is $f_{xtal}$ = *50 MHz, R=1, and m=0 (*Figure 68*)*, hence $T_{FSM}$ = 20 ns (50 MHz). Note, when using AutoCal, the maximum AutoCal Finite State Machine (FSM) clock cannot exceed 50 MHz (see Reg 0Ah[14:13]). The FSM clock does not affect the accuracy of the measurement, it only affects the time to produce the result. This same clock is used to clock the 16 bit VCO serial port.

If time to change frequencies is not a concern, then one may set the calibration time for maximum accuracy, and therefore not be concerned with measurement resolution.

Using an input crystal of 50 MHz (R=1 and $f_{pd}$=50 MHz) the times and accuracies for calibration using EQ 6 and EQ 8 are shown in Table 11 Where minimal tuning time is 1/8th of the VCO band spacing.

Across all VCOs, a measurement resolution better than 800 kHz will produce correct results. Setting m = 0, n = 5, provides 781 kHz of resolution and adds 8.6 µs of AutoCal time to a normal frequency hop. Once the AutoCal sets the final switch value, 8.64 µs after the frequency change command, the fractional register will be loaded, and the loop will lock with a normal transient predicted by the loop dynamics. Hence as shown in this example that AutoCal typically adds about 8.6 µs to the normal time to achieve frequency lock. Hence, AutoCal should be used for all but the most extreme frequency hopping requirements.

*Table 11. AutoCal Example with $F_{xtal}$ = 50 MHz, R = 1, m = 0*

| Control Value Reg0Ah[2:0] | n | $2^n$ | $T_{mmt}$ (µs) | $T_{cal}$ (µs) | $F_{err}$ Max |
|---|---|---|---|---|---|
| 0 | 0 | 1 | 0.02 | 4.92 | ± 25 MHz |
| 1 | 1 | 2 | 0.04 | 5.04 | ± 12.5 MHz |
| 2 | 2 | 4 | 0.08 | 5.28 | ± 6.25 MHz |
| 3 | 3 | 8 | 0.16 | 5.76 | ± 3.125 MHz |
| 4 | 5 | 32 | 0.64 | 8.64 | ± 781 kHz |
| 5 | 6 | 64 | 1.28 | 12.48 | ± 390 kHz |
| 6 | 7 | 128 | 2.56 | 20.16 | ± 195 kHz |
| 7 | 8 | 256 | 5.12 | 35.52 | ± 98 kHz |

#### 1.1.1.2 Manual VCO Calibration for Fast Frequency Hopping

If it is desirable to switch frequencies quickly it is possible to eliminate the AutoCal time by calibrating the VCO in advance and storing the switch number vs frequency information in the host. This can be done by initially locking the HMC1190ALP6NE on each desired frequency using AutoCal, then reading, and storing the selected VCO switch settings. The VCO switch settings are available in Reg 15h[8:1] after every AutoCal operation. The host must then program the VCO switch settings directly when changing frequencies. Manual writes to the VCO switches are executed immediately as are writes to the integer and fractional registers when AutoCal is disabled. Hence frequency changes with manual control and AutoCal disabled, requires a minimum of two serial port transfers to the HMC1190ALP6NE, once to set the VCO switches, and once to set the PLL frequency.

If AutoCal is disabled Reg 0Ah[11]=1, the VCO will update its registers with the value written via Reg 15h[8:1] immediately.

### 1.1.2 Registers Required for Frequency Changes in Fractional Mode

A large change of frequency, in fractional mode (Reg 06h[11]=1), may require Main Serial Port writes to:

1. The integer register intg, Reg 03h *(only required if the integer part changes)*
2. Manual VCO Tuning Reg 15h only required for manual control of VCO if Reg 0Ah[11]=1 *(AutoCal disabled)*
3. VCO Divide Ratio and Gain Register
   - Reg 16h[5:0] is required to change the VCO Output Divider value if needed.
   - Reg 16h[10:6] is required to change the Output Gain if needed.
4. The fractional register, Reg 04h. The fractional register write triggers AutoCal if Reg 0Ah[11]=0, and is loaded into the Delta Sigma modulator automatically after AutoCal runs. If AutoCal is disabled, Reg 0Ah[11]=1, the fractional frequency change is loaded into the Delta Sigma modulator immediately when the register is written with no adjustment to the VCO.

Small steps in frequency in fractional mode, with AutoCal enabled (Reg 0Ah[11]=0), usually only require a single write to the fractional register. Worst case, 3 Main Serial Port transfers to the HMC1190ALP6NE could be required to change frequencies in fractional mode. If the frequency step is small and the integer part of the frequency does not change, then the integer register is not changed. In all cases, in fractional mode, it is necessary to write to the fractional register Reg 04h for frequency changes.

### 1.1.3 Registers Required for Frequency Changes in Integer Mode

A change of frequency, in integer mode (Reg 06h[11]=0), requires Main Serial Port writes to:

1. VCO register
   - Reg 15h only required for manual control of VCO if Reg 0Ah[11]=1 (AutoCal disabled)
   - Reg 16h is required to change the VCO Output Divider value if needed
2. The integer register Reg 03h.
   - In integer mode, an integer register write triggers AutoCal if Reg 0Ah[11]=0, and is loaded into the prescaler automatically after AutoCal runs. If AutoCal is disabled, Reg 0Ah[11]=1, the integer frequency change is loaded into the prescaler immediately when written with no adjustment to the VCO. Normally changes to the integer register cause large steps in the VCO frequency, hence the VCO switch settings must be adjusted. AutoCal enabled is the recommended method for integer mode frequency changes. If AutoCal is disabled (Reg 0Ah[11]=1), a prior knowledge of the correct VCO switch setting and the corresponding adjustment to the VCO is required before executing the integer frequency change.

### 1.1.4 VCO Output Mute Function

The HMC1190ALP6NE features an intelligent output mute function with the capability to disable the VCO output while maintaining the PLL and VCO subsystems fully functional. The mute function is automatically controlled by the HMC1190ALP6NE, and provides a number of mute control options including:

1. Always mute (Reg 16h[5:0] = 0d). This mode is used for manual mute control.
2. Automatically mute the outputs during VCO calibration (Reg 17h[7] = 1) that occurs during output frequency changes.

This mode can be useful in eliminating any out of band emissions during freqeuncy changes, and ensuring that the system emits only desired frequencies. It is enabled by writing Reg 17h[7] = 1. Typical isolation when the HMC1190ALP6NE is muted is always better than 60 dB, and is ~ 30 dB better than disabling the output buffers of the HMC1190ALP6NE via Reg 17h[5:4].

## 1.2 PLL Overview

The PLL divides down the VCO output to the desired comparison frequency via the N-divider (integer value set in Reg 03h, fractional value set in Reg 04h), compares the divided VCO signal to the divided reference signal (reference divider set in Reg 02h) in the Phase Detector (PD), and drives the VCO tuning voltage via the Charge Pump (CP) (configured in Reg 09h) to the VCO subsystem. Some of the additional PLL subsystem functions include:

Delta Sigma configuration (Reg 06h)

Exact Frequency Mode (Configured in Reg 0Ch, Reg 06h, Reg 03h, and Reg 04h)

Lock Detect (LD) Configuration (Reg 07h to configure LD, and Reg 0Fh to configure LD_SDO output pin)

External CEN pin used as hardware enable pin.

Typically, only writes to the divider registers (integer part Reg 03h, fractional part Reg 04h,VCO Divide Ratio part Reg 04h) are required for HMC1190ALP6NE output frequency changes.

Divider registers of the PLL (Reg 03h, and Reg 04h), set the fundamental frequency (2050 MHz to 4100 MHz) of the VCO. Output frequencies ranging from 33 MHz to 2050 MHz are generated by tuning to the appropriate fundamental VCO frequency (2050 MHz to 4100 MHz) by programming N divider (Reg 03h,

and Reg 04h), and programming the output divider (divide by 1/2/4/6.../60/62, programmed in Reg 16h) in the VCO register.

For detailed frequency tuning information and example, please see Frequency Tuning section.

### 1.2.1 Charge Pump (CP) & Phase Detector (PD)

The Phase detector (PD) has two inputs, one from the reference path divider and one from the RF path divider. When in lock these two inputs are at the same average frequency and are fixed at a constant average phase offset with respect to each other. We refer to the frequency of operation of the PD as $f_{pd}$. Most formulae related to step size, delta-sigma modulation, timers etc., are functions of the operating frequency of the PD, $f_{pd}$. $f_{pd}$ is also referred to as the comparison frequency of the PD.

The PD compares the phase of the RF path signal with that of the reference path signal and controls the charge pump output current as a linear function of the phase difference between the two signals. The output current varies linearly over a full ±2π radians (±360°) of input phase difference.

#### 1.2.1.1 Charge Pump

A simplified diagram of the charge pump is shown in Figure 69. The CP consists of 4 programmable current sources, two controlling the CP Gain (Up Gain Reg 09h[13:7], and Down Gain Reg 09h[6:0]) and two controlling the CP Offset, where the magnitude of the offset is set by Reg 09h [20:14], and the direction is selected by Reg 09h [21]=1 for up and Reg 09h [22]=1 for down offset.

CP Gain is used at all times, while CP Offset is only recommended for fractional mode of operation. Typically the CP Up and Down gain settings are set to the same value (Reg 09h[13:7] = Reg 09h[6:0]).

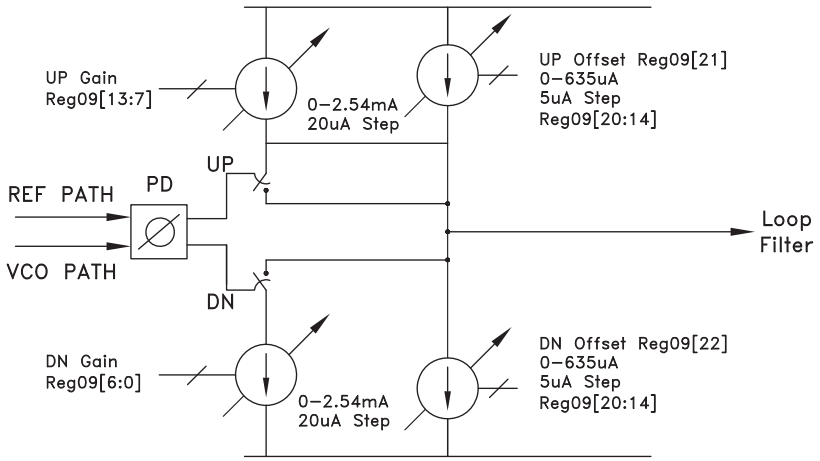



*Figure 69. Charge Pump Gain & Offset Control*

##### 1.2.1.1.1 Charge Pump Gain

Charge pump Up and Down gains are set by Reg 09h[13:7] and Reg 09h[6:0] respectively. The current gain of the pump in Amps/radian is equal to the gain setting of this register divided by 2π.

Typical CP gain setting is set to 2 to 2.5 mA, however lower values can also be used. Values < 1 mA may result in degraded Phase Noise performance.

For example, if both Reg 09h[13:7] and Reg 09h[6:0] are set to '50d' the output current of each pump will

be 1 mA and the phase frequency detector gain $k_p$ = 1 mA/2π radians, or 159 µA/rad.

#### 1.2.1.1.2 Charge Pump Phase Offset

In Integer Mode, the phase detector operates with zero offset. The divided reference signal and the divided VCO signal arrive at the phase detector inputs at the same time. Integer mode does not require any CP Offset current. When operating in Integer Mode simply disable CP offset in both directions (Up and down), by writing Reg 09h[22:21] = '00'b and set the CP Offset magnitude to zero by writing Reg 09h[20:14]= 0.

In Fractional Mode CP linearity is of paramount importance. Any non-linearity degrades phase noise and spurious performance.

In fractional mode, these non-linearities are eliminated by operating the PD with an average phase offset, either positive or negative (either the reference or the VCO edge always arrives first at the PD ie. leads).

A programmable CP offset current source is used to add DC current to the loop filter and create the desired phase offset. Positive current causes the VCO to lead, negative current causes the reference to lead.

The CP offset is controlled via Reg 09h[20:14]. The phase offset is scaled from 0 degrees, that is the reference and the VCO path arrive in phase, to 360 degrees, where they arrive a full cycle late.

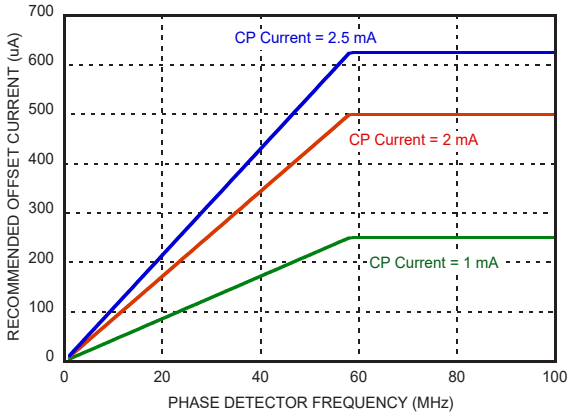
The specific level of charge pump offset current Reg 09h[20:14] is provided in EQ 9. It is also plotted in Figure 70 vs. PD frequency for typical CP Gain currents.

$$\text{Recommended CP Offset} = \min\left(4.3 \times 10^{-9} \times F_{PD} \times I_{CP}, 0.25 \times I_{CP}\right) \quad \text{(EQ 9)}$$

*where:*

$F_{PD}$*: Comparison frequency of the Phase Detector (Hz)*

$I_{CP}$*: is the full scale current setting (A) of the switching charge pump (set in Reg 09h[6:0], [13:7])*




*Recommended CP offset current vs PD frequency for typical CP gain currents. Calculated using EQ 9*

The required CP offset current should never exceed 25 % of the programmed CP current. It is recommended to enable the Up Offset and disable the Down Offset by writing Reg 09h[22:21] = '10'b.

Operation with CP offset influences the required configuration of the Lock Detect function. Refer to the description of Lock Detect function in section Lock Detect.

When operating with PD frequency >=80MHz, the CP Offset current should be disabled for the frequency change and then re-enabled after the PLL has settled. If the CP Offset current is enabled during a frequency change it may not lock.

### 1.2.1.2 Phase Detector Functions

Phase detector register Reg 0Bh allows manual access to control special phase detector features.

Setting Reg 0Bh[5] = 0, masks the PD up output, which prevents the charge pump from pumping up.`

Setting (Reg 0Bh[6]) = 0, masks the PD down output, which prevents the charge pump from pumping down.

Clearing both Reg 0Bh[5] and Reg 0Bh[6] tri-states the charge pump while leaving all other functions operating internally.

PD Force UP Reg 0Bh[9] = 1 and PD Force DN Reg 0Bh[10] = 1 allows the charge pump to be forced up or down respectively. This will force the VCO to the ends of the tuning range which can be useful in VCO testing.

### 1.2.2 Reference Input Stage

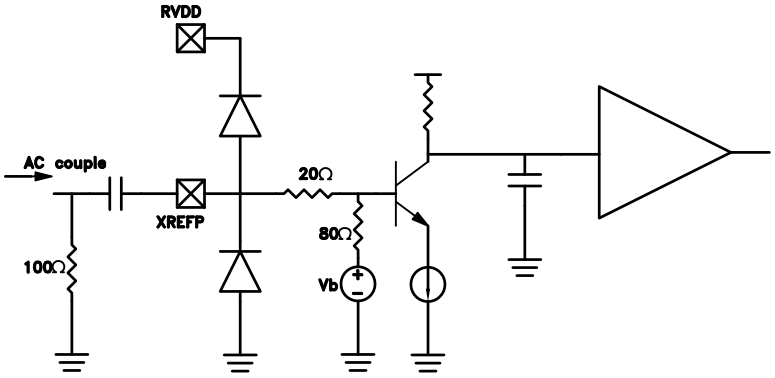



*Figure 70. Reference Path Input Stage*

The reference buffer provides the path from an external reference source (generally crystal based) to the R divider, and eventually to the phase detector. The buffer has two modes of operation controlled by Reg 08h[21]. High Gain (Reg 08h[21] = 0), recommended below 200 MHz, and High frequency (Reg 08h[21] = 1), for 200 to 350 MHz operation. The buffer is internally DC biased, with 100 Ω internal termination. For 50 Ω match, an external 100 Ω resistor to ground should be added, followed by an AC coupling capacitor (impedance < 1 Ω), then to the XREFP pin of the part.

At low frequencies, a relatively square reference is recommended to keep the input slew rate high. At higher frequencies, a square or sinusoid can be used. The following table shows the recommended operating regions for different reference frequencies. If operating outside these regions the part will normally still operate, but with degraded reference path phase noise performance.

*Table 12. Reference Sensitivity Table*

| Reference Input Frequency (MHz) | Square Input | | | Sinusoidal Input | | |
|---|---|---|---|---|---|---|
| | Slew > 0.5V/ns | Recommended Swing (Vpp) | | | Recommended Power Range (dBm) | |
| | Recommended | Min | Max | Recommended | Min | Max |
| < 10 | YES | 0.6 | 2.5 | x | x | x |
| 10 | YES | 0.6 | 2.5 | x | x | x |
| 25 | YES | 0.6 | 2.5 | ok | 8 | 15 |
| 50 | YES | 0.6 | 2.5 | YES | 6 | 15 |
| 100 | YES | 0.6 | 2.5 | YES | 5 | 15 |
| 150 | ok | 0.9 | 2.5 | YES | 4 | 12 |
| 200 | ok | 1.2 | 2.5 | YES | 3 | 8 |

Input referred phase noise of the PLL when operating at 50 MHz is between -148 and -150 dBc/Hz at 10 kHz offset depending upon the mode of operation. The input reference signal should be 10 dB better than this floor to avoid degradation of the PLL noise contribution. It should be noted that such low levels are only necessary if the PLL is the dominant noise contributor and these levels are required for the system goals.

### 1.2.2.1 Reference Path 'R' Divider

The reference path "R" divider is based on a 14-bit counter and can divide input signals by values from 1 to 16,383 and is controlled via Reg 02h.

### 1.2.3 RF Path 'N' Divider

The main RF path divider is capable of average divide ratios between $2^{19}$-5 (524,283) and 20 in fractional mode, and $2^{19}$-1 (524,287) to 16 in integer mode.

### 1.2.4 Lock Detect

The Lock Detect (LD) function indicates that the HMC1190ALP6NE is indeed generating the desired frequency. It is enabled by writing Reg 07h[11]=1. The HMC1190ALP6NE provides LD indicator in one of two ways:

- As an output available on the LD_SDO pin of the HMC1190ALP6NE, (Configuration is required to use the LD_SDO pin for LD purpose, for more information please see Configuring LD_SDO Pin for LD Output section).
- Or reading from Reg 12h[1], where Reg 12h[1] = 1 indicates locked and Reg 12h[1] = 0 indicates an unlocked condition.

The LD circuit expects the divided VCO edge and the divided reference edge to appear at the PD within a user specified time period (window), repeatedly. Either signal may arrive first, only the difference in arrival times is significant. The arrival of the two edges within the designated window increments an internal counter. Once the count reaches and exceeds a user specified value (Reg 07h[2:0]) the HMC1190ALP6NE declares lock.

Failure in registering the two edges in any one window resets the counter and immediately declares an un-locked condition. Lock is deemed to be reestablished once the counter reaches the user specified value (Reg 07h[2:0]) again.

### 1.2.4.1 Lock Detect Configuration

Optimal spectral performance in fractional mode requires CP current and CP offset current configuration discussed in detail in section Charge Pump

These settings in Reg 09h impact the required LD window size in fractional mode of operation. To function, the required lock detect window size is provided by EQ 10.

$$\text{LD Window (seconds)} = \frac{\left[\frac{I_{CP\,Offset}(A)}{F_{PD}(Hz)\cdot I_{CP}(A)} + 2.66\cdot 10^{-9}(\text{sec}) + \frac{1}{F_{PD}(Hz)}\right]}{2} \text{ in Fractional Mode}$$

$$\text{LD Window (seconds)} = \frac{1}{2\cdot F_{PD}} \text{ in Integer Mode} \qquad \text{(EQ 10)}$$

*where:*

$F_{PD}$*: is the comparison frequency of the Phase Detector*

$I_{CP\ Offset}$*: is the Charge Pump Offset Current Reg 09h[20:14]*

$I_{CP}$*: is the full scale current setting of the switching charge pump Reg 09h[6:0], or Reg 09h[13:7]*

If the result provided by EQ 10 is equal to 10 ns Analog LD can be used (Reg 07h[6] = 0). Otherwise Digital LD is necessary Reg 07h[6] = 1.

Table 13 provides the required Reg 07h settings to appropriately program the Digital LD window size. From Table 13, simply select the closest value in the “Digital LD Window Size” columns to the one calculated in EQ 10 and program Reg 07h[9:8] and Reg 07h[7:5] accordingly.

**Table 13. Typical Digital Lock Detect Window**

| LD Timer Speed Reg07[9:8] | Digital Lock Detect Window Size Nominal Value (ns) | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| Fastest 00 | 6.5 | 8 | 11 | 17 | 29 | 53 | 100 | 195 |
| 01 | 7 | 8.9 | 12.8 | 21 | 36 | 68 | 130 | 255 |
| 10 | 7.1 | 9.2 | 13.3 | 22 | 38 | 72 | 138 | 272 |
| Slowest 11 | 7.6 | 10.2 | 15.4 | 26 | 47 | 88 | 172 | 338 |
| **LD Timer Divide Setting Reg07[7:5]** | 000 | 001 | 010 | 011 | 100 | 101 | 110 | 111 |

#### 1.2.4.1.1 Digital Window Configuration Example

Assuming, fractional mode, with a 50 MHz PD and

- Charge Pump gain of 2 mA (Reg 09h[13:7] = 64h, Reg 09h[6:0] = 64h),
- Down Offset (Reg 09h[22:21] = ‘10’b)
- Offset current magnitude of +400 µA (Reg 09h[20:14] = 50h)

Applying EQ 11, the required LD window size is:

$$\text{LD Window (seconds)} = \frac{\left[\frac{0.4x10^{-3}(A)}{50\cdot 10^{6}(Hz)\cdot 2x10^{-3}(A)} + 2.66\cdot 10^{-9}(\text{sec}) + \frac{1}{50\cdot 10^{6}(Hz)}\right]}{2} = 13.33 \text{ nsec} \qquad \text{(EQ 11)}$$

Locating the Table 13 value that is closest to the EQ 11 result, in this case 13.3 ≈ 13.33. To set the Digital LD window size, simply program Reg 07h[9:8] = ‘10’b and Reg 07h[7:5] = ‘010’b according to Table 13.

There is always a good solution for the lock detect window for a given operating point. The user should understand however that one solution does not fit all operating points. As observed from EQ 11, If charge

pump offset or PD frequency are changed significantly then the lock detect window may need to be adjusted.

### 1.2.5 Configuring LD_SDO Pin for LD Output

Setting Reg 0Fh[4:0]=*1* will display the Lock Detect Flag on LD_SDO pin of the HMC1190ALP6NE. If locked, LD_SDO will be high. As the name suggests, LD_SDO pin is multiplexed between LD and SDO (Serial Data Out) signals. Hence LD is available on the LD_SDO pin at all times except when a serial port read is requested, in which case the pin reverts temporarily to the Serial Data Out pin, and returns to the Lock Detect Flag after the read is completed.

LD can be made available on LD_SDO pin at all times by writing Reg 0Fh[6] = 1. In that case the HMC1190ALP6NE will not provide any read-back functionality because the SDO signal is not available.

### 1.2.6 Cycle Slip Prevention (CSP)

When changing VCO frequency and the VCO is not yet locked to the reference, the instantaneous frequencies of the two PD inputs are different, and the phase difference of the two inputs at the PD varies rapidly over a range much greater than ±2π radians. Since the gain of the PD varies linearly with phase up to ±2π, the gain of a conventional PD will cycle from high gain, when the phase difference approaches a multiple of 2π, to low gain, when the phase difference is slightly larger than a multiple of 0 radians. The output current from the charge pump will cycle from maximum to minimum even though the VCO has not yet reached its final frequency.

The charge on the loop filter small cap may actually discharge slightly during the low gain portion of the cycle. This can make the VCO frequency actually reverse temporarily during locking. This phenomena is known as cycle slipping. Cycle slipping causes the pull-in rate during the locking phase to vary cyclically. Cycle Slipping increases the time to lock to a value greater than that predicted by normal small signal Laplace analysis.

The HMC1190ALP6NE PD features an ability to reduce cycle slipping during frequency tunning. The Cycle Slip Prevention (CSP) feature increases the PD gain during large phase errors.

### 1.2.7 Frequency Tuning

HMC1190ALP6NE VCO subsystem always operates in fundamental frequency of operation (2050 MHz to 4100 MHz). The HMC1190ALP6NE generates frequencies below its fundamental frequency (33 MHz to 2050 MHz) by tuning to the appropriate fundamental frequency and selecting the appropriate Output Divider setting (divide by 2/4/6.../60/62) in Reg 16h[5:0].

The HMC1190ALP6NE automatically controls frequency tuning in the fundamental band of operation, for more information see VCO Calibration.

To tune to frequencies below the fundamental frequency range (<2050 MHz) it is required to tune the HMC1190ALP6NE to the appropriate fundamental frequency, then select the appropriate output divider setting (divide by 2/4/6.../60/62) in Reg 16h[5:0].

#### 1.2.7.1 Integer Mode

The HMC1190ALP6NE is capable of operating in integer mode. For Integer mode set the following registers

a. Disable the Fractional Modulator, Reg 06h*[11]=0*
b. Bypass the Modulator circuit, Reg 06h*[7]=1*

In integer mode the VCO step size is fixed to that of the PD frequency. Integer mode typically has 3 dB lower phase noise than fractional mode for a given PD operating frequency. Integer mode, however, often requires a lower PD frequency to meet step size requirements. The fractional mode advantage is that higher PD frequencies can be used, hence lower phase noise can often be realized in fractional mode. Charge Pump offset should be disabled in integer mode Reg 09h[22:14] = 0h.

#### 1.2.7.1.1 Integer Frequency Tuning

In integer mode the digital ΔΣ modulator is shut off and the N divider (Reg 03h) may be programmed to any integer value in the range 16 to $2^{19}$-1. To run in integer mode configure Reg 06h as described, then program the integer portion of the frequency as explained by EQ 12, ignoring the fractional part.

a. Disable the Fractional Modulator, Reg 06h[11] = 0
b. Bypass the delta-sigma modulator Reg 06h[7] = 1
c. To tune to frequencies (<2050 MHz), select the appropriate output divider value Reg 16h[5:0].

### 1.2.7.2 Fractional Mode

The HMC1190ALP6NE is placed in fractional mode by setting the following registers:

a. Enable the Fractional Modulator, Reg 06h[11]=1
b. Connect the delta sigma modulator in circuit, Reg 06h*[7]=0*

#### 1.2.7.2.1 Fractional Frequency Tuning

This is a generic example, with the goal of explaining how to program the output frequency. Actual variables are dependant upon the reference in use.

The HMC1190ALP6NE in fractional mode can achieve frequencies at fractional multiples of the reference. The frequency of the HMC1190ALP6NE, $f_{vco}$, is given by

$$f_{vco} = \frac{f_{xtal}}{R}\ (N_{int} + N_{frac}) = f_{int} + f_{frac} \qquad \text{(EQ 12)}$$

$$f_{out} = f_{vco} / k \qquad \text{(EQ 13)}$$

Where:

| | |
|---|---|
| $f_{out}$ | is the output frequency after any potential dividers. |
| $k$ | is 1 for fundamental, or k = 2,4,6,…58,60,62 depending on the selected output divider value (Reg 16h[5:0]) |
| $N_{int}$ | is the integer division ratio, Reg 03h, an integer number between 20 and 524,284 |
| $N_{frac}$ | is the fractional part, from 0.0 to 0.99999...,$N_{frac}$=Reg 04h/$2^{24}$ |
| $R$ | is the reference path division ratio, Reg 02h |
| $f_{xtal}$ | is the frequency of the reference oscillator input |
| $f_{pd}$ | is the PD operating frequency, $f_{xtal}/R$ |

As an example:

| | |
|---|---|
| $f_{out}$ | 1402.5 MHz |
| $k$ | 2 |
| $f_{vco}$ | 2,805 MHz |
| $f_{xtal}$ | = 50 MHz |
| $R$ | = 1 |
| $f_{pd}$ | = 50 MHz |
| $N_{int}$ | = 56 |
| $N_{frac}$ | = 0.1 |

Reg 04h = round(0.1 x $2^{24}$) = round(1677721.6) = 1677722

$$f_{VCO} = \frac{50e6}{1}\left(56 + \frac{1677722}{2^{24}}\right) = 2805\ MHz + 1.192\ Hz\ error \quad \text{(EQ 14)}$$

$$f_{out} = \frac{f_{VCO}}{2} = 1402.5\ MHz + 0.596\ Hz\ error \quad \text{(EQ 15)}$$

In this example the output frequency of 1402.5 MHz is achieved by programming the 19-bit binary value of 56d = 38h into *intg_reg* in Reg 03h, and the 24-bit binary value of 1677722d = 19999Ah into *frac_reg* in Reg 04h. The 0.596 Hz quantization error can be eliminated using the exact frequency mode if required. In this example the VCO output fundamental 2805 MHz is divided by 2 (Reg 16h[5:0] = 2h) = 1402.5 MHz.

### 1.2.7.3 Exact Frequency Tuning

Due to quantization effects, the absolute frequency precision of a fractional PLL is normally limited by the number of bits in the fractional modulator. For example, a 24 bit fractional modulator has frequency resolution set by the phase detector (PD ) comparison rate divided by $2^{24}$. The value $2^{24}$ in the denominator is sometimes referred to as the modulus. Hittite PLLs use a fixed modulus which is a binary number. In some types of fractional PLLs the modulus is variable, which allows exact frequency steps to be achieved with decimal step sizes. Unfortunately small steps using small modulus values results in large spurious outputs at multiples of the modulus period (channel step size). For this reason Hittite PLLs use a large fixed modulus. Normally, the step size is set by the size of the fixed modulus. In the case of a 50 MHz PD rate, a modulus of $2^{24}$ would result in a 2.98 Hz step resolution, or 0.0596 ppm. In some applications it is necessary to have exact frequency steps, and even an error of 3 Hz cannot be tolerated.

Fractional PLLs are able to generate exact frequencies (with zero frequency error) if N can be exactly represented in binary (eg. N = 50.0,50.5,50.25,50.75 etc.). Unfortunately, some common frequencies cannot be exactly represented. For example, $N_{frac}$ = 0.1 = 1/10 must be approximated as round((0.1 x $2^{24}$)/ $2^{24}$ ) ≈ 0.100000024. At $f_{PD}$ = 50 MHz this translates to 1.2 Hz error. Hittite's exact frequency mode addresses this issue, and can eliminate quantization error by programming the channel step size to $F_{PD}$/10 in Reg 0Ch to 10 (in this example). More generally, this feature can be used whenever the desired frequency, $f_{VCO}$, can be exactly represented on a step plan where there are an integer number of steps (<$2^{24}$) across integer-N boundaries. Mathematically, this situation is satisfied if:

$$f_{VCOk} \bmod \left(\frac{f_{gcd}}{\left(\frac{f_{PD}}{2^{24}}\right)}\right) = 0 \quad \text{where } f_{gcd} = \gcd(f_{VCO1}, f_{PD}) \text{ and } f_{gcd} \left(\frac{f_{PD}}{2^{24}}\right) \quad \text{(EQ 16)}$$

Where:

gcd stands for Greatest Common Divisor

$f_N$ = maximum integer boundary frequency < $f_{VCO1}$

$f_{PD}$ = frequency of the Phase Detector

and $f_{VCOk}$ are the channel step frequencies where 0 < k < $2^{24}$-1, As shown in Figure 71.

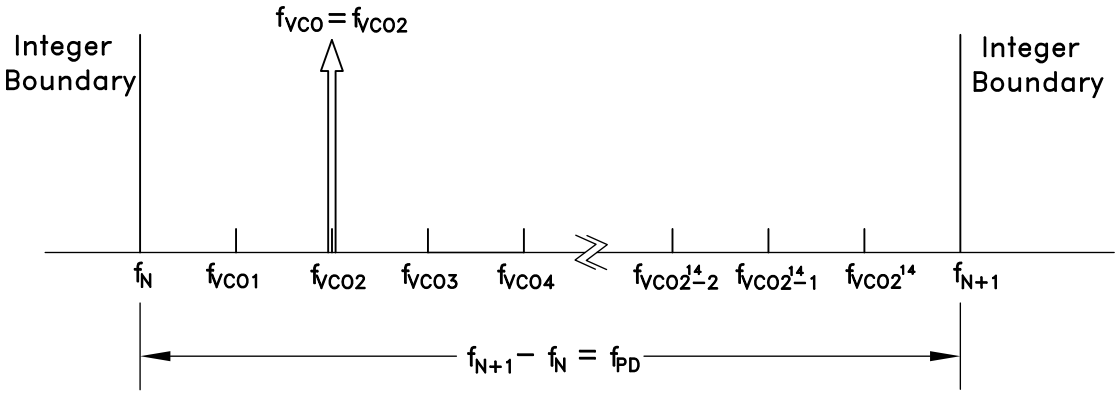



*Figure 71. Exact Frequency Tuning*

Some fractional PLLs are able to achieve this by adjusting (shortening) the length of the Phase Accumulator (the denominator or the modulus of the Delta-Sigma modulator) so that the Delta-Sigma modulator phase accumulator repeats at an exact period related to the interval frequency ($f_{VCOk}$ - $f_{VCO(k-1)}$) in Figure 71. Consequently, the shortened accumulator results in more frequent repeating patterns and as a result often leads to spurious emissions at multiples of the repeating pattern period, or at harmonic frequencies of $f_{VCOk}$ - $f_{VCO(k-1)}$. For example, in some applications, these intervals might represent the spacing between radio channels, and the spurious would occur at multiples of the channel spacing.

The Hittite method on the other hand is able to generate exact frequencies between adjacent integer-N boundaries while still using the full 24 bit phase accumulator modulus, thus achieving exact frequency steps with a high phase detector comparison rate, which allows Hittite PLLs to maintain excellent phase noise and spurious performance in the Exact Frequency Mode.

### 1.2.7.3.1 Using Hittite Exact Frequency Mode

If the constraint in EQ 16 is satisfied, HMC1190ALP6NE is able to generate signals with zero frequency error at the desired VCO frequency. Exact Frequency Mode may be re-configured for each target frequency, or be set-up for a fixed $f_{gcd}$ which applies to all channels.

### 1.2.7.3.2 Configuring Exact Frequency Mode For a Particular Frequency

1. Calculate and program the integer register setting Reg 03h = $N_{INT}$ = floor($f_{VCO}/f_{PD}$), where the floor function is the rounding down to the nearest integer. Then the integer boundary frequency $f_N = N_{INT} \cdot f_{PD}$
2. Calculate and program the exact frequency register value Reg 0Ch = $f_{PD}/f_{gcd}$, where $f_{gcd}$ = gcd($f_{VCO}$,$f_{PD}$)
3. Calculate and program the fractional register setting Reg 04h $N_{FRAC} = \text{ceil}\left[\frac{2^{24}\left(f_{VCOk} - f_N\right)}{f_{PD}}\right]$, where ceil is the ceiling function meaning "round up to the nearest integer."

*Example: To configure the HMC1190ALP6NE for exact frequency mode at $f_{VCO}$ = 2800.2 MHz where Phase Detector (PD) rate $f_{PD}$ = 61.44 MHz Proceed as follows:*

Check EQ 16 to confirm that the exact frequency mode for this $f_{VCO}$ is possible.

$$f_{gcd} = \text{gcd}(f_{VCO}, f_{PD}) \; and \; f_{gcd} \geq \left[\frac{f_{PD}}{2^{24}}\right]$$

$$f_{gcd} = \text{gcd}\left(2800.2 \cdot 10^6, 61.44 \cdot 10^6\right) = 120 \cdot 10^3 > \frac{61.44 \cdot 10^6}{2^{24}} = 3.662$$

Since EQ 16 is satisfied, the HMC1190ALP6NE can be configured for exact frequency mode at $f_{VCO}$ = 2800.2 MHz as follows:

1. $N_{INT}$ = Reg 03h = $floor\left(\frac{f_{VCO1}}{f_{PD}}\right) = floor\left(\frac{2800.2 \cdot 10^6}{61.44 \cdot 10^6}\right) = 45d = 2Dh$

2. Reg 0Ch = $\frac{f_{PD}}{\gcd\left(\left(f_{VCOk+1} - f_{VCOk}\right), f_{PD}\right)} = \frac{61.44 \cdot 10^6}{\gcd\left(100 \cdot 10^3, 61.44 \cdot 10^6\right)} = \frac{61.44 \cdot 10^6}{20000} = 3072d = C00h$

3. To program Reg 04h, the closest integer-N boundary frequency $f_N$ that is less than the desired VCO frequency $f_{VCO}$ must be calculated. $f_N = f_{PD} \cdot N_{INT}$. Using the current example:

$f_N = f_{PD} \cdot N_{INT} = 45 \cdot 61.44 \cdot 10^6 = 2764.8\,MHz$.

Then Reg04h = $ceil\left(\frac{2^{24}\left(f_{VCO} - f_N\right)}{f_{PD}}\right) = ceil\left(\frac{2^{24}\left(2800.2 \cdot 10^6 - 2764.8 \cdot 10^6\right)}{61.44 \cdot 10^6}\right) = 9666560d = 938000h$

### 1.2.7.3.3 Hittite Exact Frequency Channel Mode

If it is desirable to have multiple, equally spaced, exact frequency channels that fall within the same interval (ie. $f_N \le f_{VCOk} < f_{N+1}$) where $f_{VCOk}$ is shown in Figure 71 and $1 \le k \le 2^{24}$, it is possible to maintain the same integer-N (Reg 03h) and exact frequency register (Reg 0Ch) settings and only update the fractional register (Reg 04h) setting. The Exact Frequency Channel Mode is possible if EQ 16 is satisfied for at least two equally spaced adjacent frequency channels, i.e. the channel step size.

To configure the HMC1190ALP6NE for Exact Frequency Channel Mode, initially and only at the beginning, integer (Reg 03h) and exact frequency (Reg 0Ch) registers need to be programmed for the smallest $f_{VCO}$ frequency ($f_{VCO1}$ in Figure 71), as follows:

1. Calculate and program the integer register setting Reg 03h = $N_{INT}$ = floor($f_{VCO1}/f_{PD}$), where $f_{VCO1}$ is shown in Figure 71 and corresponds to minimum channel VCO frequency. Then the lower integer boundary frequency is given by $f_N = N_{INT} \cdot f_{PD}$.
2. Calculate and program the exact frequency register value Reg 0Ch = $f_{PD}/f_{gcd}$, where $f_{gcd}$ = gcd(($f_{VCOk+1}$ - $f_{VCOk}$),$f_{PD}$) = greatest common divisor of the desired equidistant channel spacing and the PD frequency (($f_{VCOk+1}$ - $f_{VCOk}$) and $f_{PD}$).

Then, to switch between various equally spaced intervals (channels) only the fractional register (Reg 04h) needs to be programmed to the desired VCO channel frequency $f_{VCOk}$ in the following manner:

Reg 04h = $N_{FRAC}$ = $ceil\left(\frac{2^{24}\left(f_{VCOk} - f_N\right)}{f_{PD}}\right)$ where $f_N$ = floor($f_{VCO1}/f_{PD}$), and $f_{VCO1}$, as shown in Figure 71, represents the smallest channel VCO frequency that is greater than $f_N$.

*Example: To configure the HMC1190ALP6NE for Exact Frequency Mode for equally spaced intervals of 100 kHz where first channel (Channel 1) = $f_{VCO1}$ = 2800.200 MHz and Phase Detector (PD) rate $f_{PD}$ = 61.44 MHz proceed as follows:*

First check that the exact frequency mode for this $f_{VCO1}$ = 2800.2 MHz (Channel 1) and $f_{VCO2}$ = 2800.2 MHz + 100 kHz = 2800.3 MHz (Channel 2) is possible.

$f_{gcd1} = \gcd(f_{VCO1}, f_{PD})$ and $f_{gcd1} \ge \frac{f_{PD}}{2^{24}}$ and $f_{gcd2} = \gcd(f_{VCO2}, f_{PD})$ and $f_{gcd2} \ge \frac{f_{PD}}{2^{24}}$

$f_{gcd1} = \gcd\left(2800.2 \cdot 10^6, 61.44 \cdot 10^6\right) = 120 \cdot 10^3 > \frac{61.44 \cdot 10^6}{2^{24}} = 3.662$

$f_{gcd2} = \gcd\left(2800.3 \cdot 10^6, 61.44 \cdot 10^6\right) = 20 \cdot 10^3 > \frac{61.44 \cdot 10^6}{2^{24}} = 3.662$

If EQ 16 is satisfied for at least two of the equally spaced interval (channel) frequencies $f_{VCO1}, f_{VCO2}, f_{VCO3}, ...$

$f_{VCON}$, as it is above, Hittite Exact Frequency Channel Mode is possible for all desired channel frequencies, and can be configured as follows:

1. Reg 03h = $floor\left(\frac{f_{VCO1}}{f_{PD}}\right) = floor\left(\frac{2800.2\cdot10^6}{61.44\cdot10^6}\right) = 45d = 2Dh$

2. Reg 0Ch = $\frac{f_{PD}}{\gcd\left(\left(f_{VCOk+1}-f_{VCOk}\right),f_{PD}\right)} = \frac{61.44\cdot10^6}{\gcd\left(100\cdot10^3,61.44\cdot10^6\right)} = \frac{61.44\cdot10^6}{20000} = 3072d = C00h$

   where ($f_{VCOk+1}$ - $f_{VCOk}$) is the desired channel spacing (100 kHz in this example).

3. To program Reg 04h the closest integer-N boundary frequency $f_N$ that is less than the smallest channel VCO frequency $f_{VCO1}$ must be calculated. $f_N$ = floor($f_{VCO1}/f_{PD}$). Using the current example:

   $f_N = f_{PD}\cdot floor\left(\frac{2800.2\cdot10^6}{61.44\cdot10^6}\right) = 45\cdot61.44\cdot10^6 = 2764.8\,MHz$ Then

   Reg 04h $= ceil\left(\frac{2^{24}\left(f_{VCO1}-f_N\right)}{f_{PD}}\right)$ for channel 1 where $f_{VCO1} = 2800.2\,MHz$

   $= ceil\left(\frac{2^{24}\left(2800.2\cdot10^6-2764.8\cdot10^6\right)}{61.44\cdot10^6}\right) = 9666560d = 938000h$

4. To change from channel 1 ($f_{VCO1}$ = 2800.2 MHz) to channel 2 ($f_{VCO2}$ = 2800.3 MHz), only Reg 04h needs to be programmed, as long as all of the desired exact frequencies $f_{VCOk}$ (Figure 71) fall between the same integer-N boundaries ($f_N < f_{VCOk} < f_{N+1}$). In that case

   Reg 04h = $ceil\left(\frac{2^{24}\left(2800.3\cdot10^6-2764.8\cdot10^6\right)}{61.44\cdot10^6}\right) = 9693867d = 93EAABh$ , and so on.

#### 1.2.7.3.4 Seed Register

The start phase of the fractional modulator digital phase accumulator (DPA) may be set to any desired phase relative to the reference frequency, The phase is programmed in Reg 1Ah, and Exact Frequency Mode is required. Phase = 2π x Reg1Ah/($2^{24}$) via the seed register Reg 1Ah[23:0]. The HMC1190ALP6NE will automatically reload the start phase (seed value) into the DPA every time a new fractional frequency is selected. Certain zero or binary seed values may cause spurious energy correlation at specific frequencies. For most cases a random, or non zero, non-binary start seed is recommended.

## 1.3 Soft Reset & Power-On Reset

The HMC1190ALP6NE features a hardware Power on Reset (POR). All chip registers will be reset to default states approximately 250 µs after power up.

The PLL subsystem SPI registers may also be soft reset by an SPI write to register Reg 00h.

## 1.4 Power Down Mode

Power down the HMC1190ALP6NE by pulling CEN pin (pin 17) low (assuming no SPI overrides (Reg 01h[0]=1)). This will result in all analog functions and internal clocks disabled. Current consumption will typically drop below 10 µA in Power Down state. The serial port will still respond to normal communication in Power Down mode.

It is possible to ignore the CEN pin, by setting Reg 01h[0]=0. Control of Power Down Mode then comes from the serial port register Reg 01h[1].

It is also possible to leave various blocks on when in Power Down *(see* Reg 01h*)*, including:

a. Internal Bias Reference Sources Reg 01h[2]
b. PD Block Reg 01h[3]
c. CP Block Reg 01h[4]
d. Reference Path Buffer Reg 01h[5]
e. VCO Path buffer Reg 01h[6]
f. Digital I/O Test pads Reg 01h[7]

To mute the output but leave the PLL and VCO locked please refer to VCO Output Mute Function section.

## 1.5 General Purpose Output (GPO) Pin

The PLL shares the LD_SDO (Lock-Detect/Serial Data Out) pin to perform various functions. While the pin is most commonly used to read back registers from chip via the SPI, it is also capable of exporting a variety of signals and real time test waveforms (including Lock Detect). It is driven by a tri-state CMOS driver with ~200 Ω Rout. It has logic associated with it to dynamically select whether the driver is enabled, and to decide which data to export from the chip.

In its default configuration, after power-on-reset, the output driver is disabled, and only drives during appropriately addressed SPI reads. This allows it to share the output with other devices on the same bus.

The pin driver is enabled if the chip is addressed - ie. The last 3 bits of SPI cycle = '000'b before the rising edge of SEN. If SEN rises before SCK has clocked in an 'invalid' (non-zero) chip -address, the HMC1190ALP6NE will start to drive the bus.

The BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER will naturally switch away from the GPO data and export the SDO during an SPI read. To prevent this automatic data selection, and always select the GPO signal, set "Prevent AutoMux of SDO" (Reg 0Fh[6] = 1). The phase noise performance at this output is poor and uncharacterized. The GPO output should not be toggling during normal operation because it may degrade the spectral performance.

Note that there are additional controls available, which may be helpful if sharing the bus with other devices:

- To disable the driver completely, set Reg 08h[5] = 0 (it takes precedence over all else).
- To disable either the pull-up or pull-down sections of the driver, Reg 0Fh[8] = 1 or Reg 0Fh[9] = 1 respectively.

Example Scenarios:

- Drive SDO during reads, tri-state otherwise (to allow bus-sharing)
  - No action required.
- Drive SDO during reads, Lock Detect otherwise
  - Set GPO Select Reg 0Fh [4:0] = '00001'b (which is default)
  - Set "Prevent GPO driver disable" (Reg 0Fh[7] = 1)
- Always drive Lock Detect
  - Set " Prevent AutoMux of SDO" Reg 0Fh[6] = 1
  - Set GPO Select Reg 0Fh[4:0]= 00001 (which is default)
  - Set "Prevent GPO driver disable" (Reg 0Fh[7] = 1))

The signals available on the GPO are selected in Reg 0Fh[4:0].

## 1.6 Chip Identification

The chip id information may be read by reading the content of read only register, chip_ID in Reg 00h. For HMC1190ALP6NE, chip id is C7701Ah.

## 1.7 Serial Port Overview

The SPI protocol has the following general features:

a. 3-bit chip address , enable the use of up to 8 devices connected to the serial bus
b. Simultaneous Write/Read during the SPI cycle
c. 5-bit address space
d. 3 wire for Write Only capability, 4 wire for Read/Write capability
Typical serial port operation can be run with SCLK at speeds up to 50 MHz.

### 1.7.1 Serial Port WRITE Operation

AVDD = DVDD = 3V, AGND = DGND = 0V

**Table 14. SPI WRITE Timing Characteristics**

| Parameter | Conditions | Min. | Typ. | Max | Units |
|---|---|---|---|---|---|
| $t_1$ | SDI setup time to SCLK Rising Edge | 3 | | | ns |
| $t_2$ | SCLK Rising Edge to SDI hold time | 3 | | | ns |
| $t_3$ | SEN low duration | 10 | | | ns |
| $t_4$ | SEN high duration | 10 | | | ns |
| $t_5$ | SCLK 32 Rising Edge to SEN Rising Edge | 10 | | | ns |
| $t_6$ | Recovery Time | 10 | | | ns |
| | Max Serial port Clock Speed | | 50 | | MHz |

A typical WRITE cycle is shown in Figure 72.

a. The Master (host) places 24-bit data, d23:d0, MSB first, on SDI on the first 24 falling edges of SCLK.
b. the slave (HMC1190ALP6NE) shifts in data on SDI on the first 24 rising edges of SCLK
c. Master places 5-bit register address to be written to, r4:r0, MSB first, on the next 5 falling edges of SCLK (25-29)
d. Slave shifts the register bits on the next 5 rising edges of SCLK (25-29).
e. Master places 3-bit chip address, a2:a0, MSB first, on the next 3 falling edges of SCLK (30-32). Hittite reserves chip address a2:a0 = 000 for HMC1190ALP6NE.
f. Slave shifts the chip address bits on the next 3 rising edges of SCLK (30-32).
g. Master asserts SEN after the 32nd rising edge of SCLK.
h. Slave registers the SDI data on the rising edge of SEN.
i. Master clears SEN to complete the WRITE cycle.

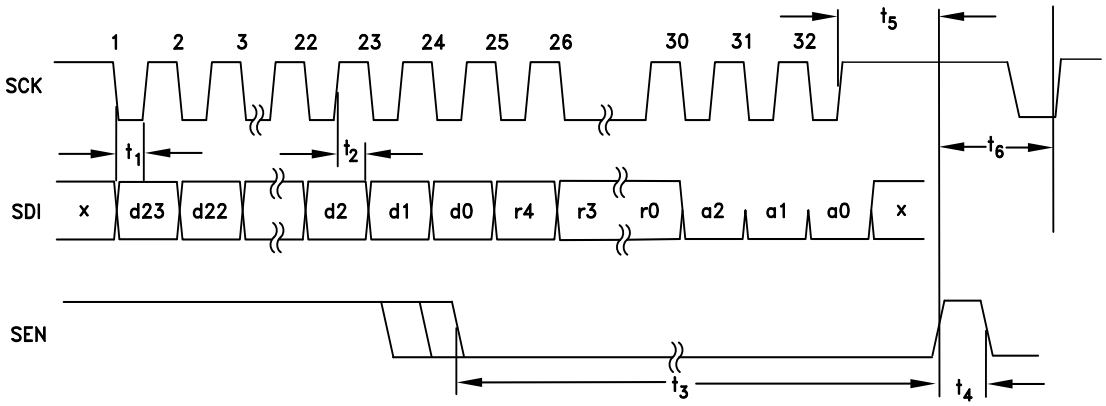



*Figure 72. Serial Port Timing Diagram - WRITE*

### 1.7.2 Serial Port READ Operation

A typical READ cycle is shown in Figure 73.

In general, the LD_SDO line is always active during the WRITE cycle. During any SPI cycle LD_SDO will contain the data from the current address written in Reg 00h[4:0]. If Reg 00h[4:0] is not changed then the same data will always be present on LD_SDO when an Open Mode cycle is in progress. If it is desired to READ from a specific address, it is necessary in the first SPI cycle to write the desired address to Reg 00h[4:0], then in the next SPI cycle the desired data will be available on LD_SDO.

An example of the two cycle procedure to read from any address follows:

a. The Master (host), on the first 24 falling edges of SCLK places 24-bit data, d23:d0, MSB first, on SDI as shown in Figure 73. d23:d5 should be set to zero. d4:d0 = address of the register to be READ on the next cycle.
b. the slave (HMC1190ALP6NE) shifts in data on SDI on the first 24 rising edges of SCK
c. Master places 5-bit register address , r4:r0, (the READ ADDRESS register), MSB first, on the next 5 falling edges of SCK (25-29). r4:r0=00000.
d. Slave shifts the register bits on the next 5 rising edges of SCK (25-29).
e. Master places 3-bit chip address, a2:a0, MSB first, on the next 3 falling edges of SCK (30-32). Chip address is always '000'b.
f. Slave shifts the chip address bits on the next 3 rising edges of SCK (30-32).
g. Master asserts SEN after the 32nd rising edge of SCK.
h. Slave registers the SDI data on the rising edge of SEN.
i. Master clears SEN to complete the the address transfer of the two part READ cycle.
j. If one does not wish to write data to the chip during the second cycle, then it is recommended to simply rewrite the same contents on SDI to Register zero on the READ back part of the cycle.
k. Master places the same SDI data as the previous cycle on the next 32 falling edges of SCK.
l. Slave (HMC1190ALP6NE) shifts the SDI data on the next 32 rising edges of SCK. On these same edges, the slave places the desired read data (ie. data from the address specified in Reg 00h[4:0] of the first cycle) on LD_SDO which automatically switches to SDO mode from LD mode, disabling the LD output.
m. Master asserts SEN after the 32nd rising edge of SCK to complete the cycle and revert back to Lock Detect on LD_SDO.

**Table 15. SPI Read Timing Characteristics**

| Parameter | Conditions | Min. | Typ. | Max | Units |
|---|---|---|---|---|---|
| $t_1$ | SDI setup time to SCK Rising Edge | 3 | | | ns |
| $t_2$ | SCK Rising Edge to SDI hold time | 3 | | | ns |
| $t_3$ | SEN low duration | 10 | | | ns |
| $t_4$ | SEN high duration | 10 | | | ns |
| $t_5$ | SCK Rising Edge to SDO time | | 8.2ns+0.2ns/pF | | ns |
| $t_6$ | Recovery TIme | 10 | | | ns |
| $t_7$ | SCK 32 Rising Edge to SEN Rising Edge | 10 | | | ns |

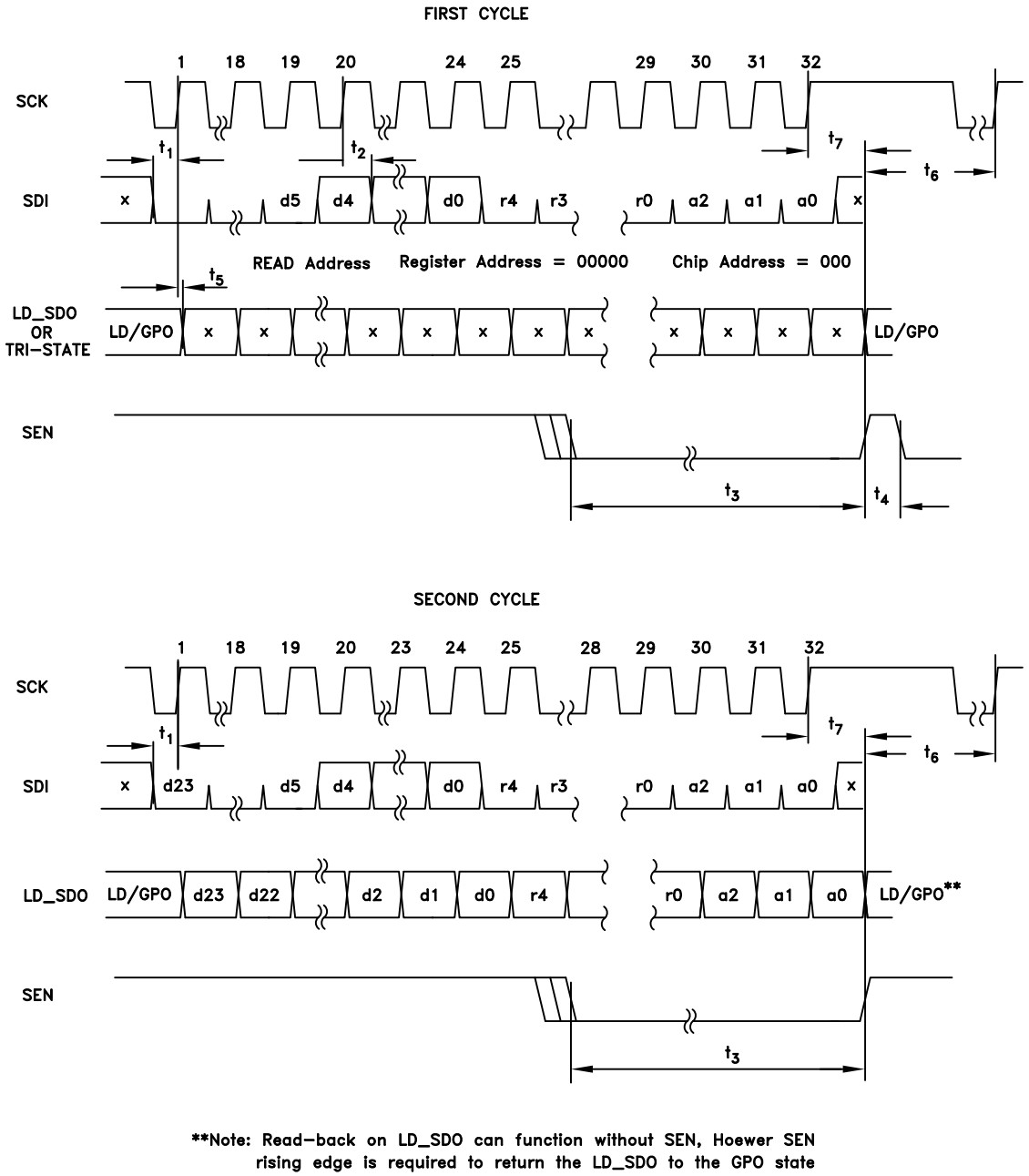



*Figure 73. Serial Port Timing Diagram - READ*

For more information on using the GPO pin while in SPI Mode please see section General Purpose Output (GPO) Pin

## 2.0 PLL Register Map

### 2.1 Reg 00h ID Register (Read Only) DEFAULT C7701A h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | RO | chip_ID | 24 | C7701A | Chip ID Number |

### 2.2 Reg 00h Open Mode Read Address/RST Strobe Register (Write Only)

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [4:0] | WO | Read Address | 5 | - | (WRITE ONLY) Read Address for next cycle |
| [5] | WO | Soft Reset | 1 | - | (WRITE ONLY) Soft Reset - (set to 0 during operation) |
| [23:6] | WO | Not Defined | 18 | - | Not Defined (set to write 0h) |

### 2.3 Reg 01h Chip Enable Register DEFAULT 3h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [0] | R/W | Chip Enable Pin Select | 1 | 1 | 1 = Chip enable via CHIP_EN pin, Reg 01h[0]=1 and CHIP_EN pin low places the HMC1190ALP6NE in Power Down Mode<br>0 = Chip enable via SPI - Reg 01h[0] = 0, CHIP_EN pin ignored (see Power Down Mode description for more details) |
| [1] | R/W | SPI Chip Enable | 1 | 1 | Controls Chip Enable (Power Down) if Reg 01h[0] =0<br>Reg 01h[0]=0 and Reg 01h[1]=1 - chip is enabled, CHIP_EN pin don't care<br>Reg 01h[0]=0 and Reg 01h[1]=0 - chip disabled, CHIP_EN pin don't care<br>(see Power Down Mode description for more information) |
| [2] | R/W | Keep Bias On | 1 | 0 | keeps internal bias generators on, ignores Chip enable control |
| [3] | R/W | Keep PFD Pn | 1 | 0 | keeps PFD circuit on, ignores Chip enable control |
| [4] | R/W | Keep CP On | 1 | 0 | keeps Charge Pump on, ignores Chip enable control |
| [5] | R/W | Keep Reference Buffer ON | 1 | 0 | keeps Reference buffer block on, ignores Chip enable control |
| [6] | R/W | Keep VCO on | 1 | 0 | keeps VCO divider buffer on, ignores Chip enable control |
| [7] | R/W | Keep GPO Driver ON | 1 | 0 | keeps GPO output Driver ON, ignores Chip enable control |
| [9:8] | R/W | Reserved | 2 | 0 | reserved |

### 2.4 Reg 02h REFDIV Register DEFAULT 1h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [13:0] | R/W | rdiv | 14 | 1 | Reference Divider 'R' Value (EQ 8)<br>min 1<br>max max $2^{14}$-1 = 3FFFh = 16383d |

### 2.5 Reg 03h Frequency Register - Integer Part DEFAULT 19h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [18:0] | R/W | Integer Setting | 19 | 25d<br>19h | Divider Integer part, used in all modes, see EQ 10<br><br>Fractional Mode<br>min 20d<br>max $2^{19}$ - 4 = 7FFFCh = 524,284d<br><br>Integer Mode<br>min 16d<br>max $2^{19}$-1 = 7FFFFh = 524,287d |

## 2.6 Reg 04h Frequency Register - Fractional Part DEFAULT 0h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | R/W | Fractional Setting | 24 | 0 | Divider Fractional part (24 bit unsigned) see Fractional Frequency<br>Tuning<br>Fractional Division Value = Reg4[23:0]/$2^{24}$<br>Used in Fractional Mode only<br><br>min 0<br>max $2^{24}$-1 = FFFFFFh = 16,777,215d |

## 2.7 Reg 05h Reserved

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | R/W | Reserved | 24 | 0 | Reserved |

## 2.8 Reg 06h Delta Sigma Modulator Register DEFAULT 30F0Ah

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [1:0] | R/W | Reserved | 2 | 2 | Reserved, Program to 0h |
| [3:2] | R/W | DSM Order | 2 | 2 | Select the Delta Sigma Modulator Type<br>0: 1st order<br>1: 2nd Order<br>2: 3rd Order - Recommended<br>3: Reserved |
| [4] | R/W | Synchronous SPI Mode | 1 | 0 | 0: Normal SPI Load - all register load on rising edge of SEN<br>1: Synchronous SPI - registers Reg 03h, Reg 04h , Reg 1Ah wait to load synchronously on the next internal clock cycle.<br><br>Normally (When this bit is 0) SPI writes into the internal state machines/counters happen asynchronously relative to the internal clocks. This can create freq/phase disturbances if writing register 3, 4 or 1A. When this bit is enabled, the internal SPI registers are loaded synchronously with the internal clock. This means that the data in the SPI shifter should be held constant for at least 2 PFD clock periods after SEN is asserted to allow this retiming to happen cleanly. |
| [5] | R/W | Exact Frequency Mode Enable | 1 | 0 | 1: Exact Frequency Mode Enabled<br>0: Exact Frequency Mode Disabled |
| [6] | R/W | Reserved | 1 | 0 | Reserved |
| [7] | R/W | Fractional Bypass | 1 | 0 | 0: Use Modulator, Required for Fractional Mode,<br>1: Bypass Modulator, Required for Integer Mode<br>Note: When enabled fractional modulator output is ignored, but fractional modulator continues to be clocked if Reg 06h[11] =1. This feature can be used to test the isolation of the digital fractional modulator from the VCO output in integer mode. |
| [8] | R/W | Autoseed EN | 1 | 1 | 1: loads the modulator seed (start phase) whenever the fractional register (Reg 04h) is written<br>0: when fractional register (Reg 04h) write changes frequency, modulator starts at previous value (phase) |
| [10:9] | R/W | Reserved | 2 | 3 | Reserved |
| [11] | R/W | Delta Sigma Modulator Enable | 1 | 1 | 0: Disable DSM, used for Integer Mode<br>1: Enable DSM Core, required for Fractional Mode |
| [23:12] | R/W | Reserved | 12 | 48d<br>30h | Reserved |

## 2.9 Reg 07h Lock Detect Register DEFAULT 200844 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [2:0] | R/W | lkd_wincnt_max | 3 | 4 | lock detect window<br>sets the number of consecutive counts of divided VCO that must land inside the Lock Detect Window to declare LOCK<br>0: 5<br>1: 32<br>2: 96<br>3: 256<br>4: 512<br>5: 2048<br>6: 8192<br>7: 65535 |
| [10:3] | R/W | Reserved | 8 | 8 | Reserved |
| [11] | R/W | LD Enable | 1 | 1 | 0: LD disable<br>1: LD enable |
| [19:12] | R/W | Reserved | 8 | 0 | Reserved |
| [20] | R/W | Lock Detect Training | 9 | 0 | 0 to 1 transition triggers the training. Lock Detect Training is only required after changing Phase Detector frequency. After changing PD frequency a toggle Reg 07h[20] from 0 to 1 retrains the Lock Detect. |
| [21] | R/W | CSP Enable | 1 | 1 | Cycle Slip Prevention enable.<br>When enabled, if the phase error becomes larger than approx 70% of the PFD period, the charge-pump gain is increased by approx 6mA for the duration of the cycle.. |
| [23:22] | R/W | Reserved | 2 | 0 | Reserved |

## 2.10 Reg 08h Analog EN Register DEFAULT 1BFFF h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [4:0] | R/W | Reserved | 5 | 31d | Reserved |
| [5] | R/W | GPO(General Purpose Output Pin Enable) | 1 | 1d | 0 - Pin LD_SDO disabled<br>1 - and Reg 0Fh[7]=1 , Pin LD_SDO is always driven, this is required for use of GPO port<br>1 - and Reg 0Fh[7]=0 LDO_SPI is off if chip address not equal to '000'b, allowing a shared SPI with other compatible parts |
| [9:6] | R/W | Reserved | 4 | 15d | Reserved |
| [10] | R/W | VCO Buffer and Prescaler Bias Enable | 1 | 1d | 0: VCO Buffer and Prescaler Bias Disable<br>1: VCO Buffer and Prescaler Bias Enable<br>Only applies to External VCO |
| [20:11] | R/W | Reserved | 10 | 55d | Reserved |
| [21] | R/W | High Frequency Reference | 1 | 0 | Program to 1 for XTAL > 200 MHz, 0 otherwise |
| [22] | R/W | SDO Output Level | 1 | 0d | Output Logic Level on LD/SDO pin<br>0: 1.8 V Logic Levels<br>1: DVDD3V Logic Level |
| [23] | R/W | Reserved | 1 | 0d | Reserved |

## 2.11 Reg 09h Charge Pump Register DEFAULT 547264 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [6:0] | R/W | CP DN Gain | 7 | 100d<br>64h | Charge Pump DN Gain Control 20 µA/step<br>Affects fractional phase noise and lock detect settings<br>0d = 0 µA<br>1d = 20 µA<br>2d = 40 µA<br>...<br>127d = 2.54mA Default 2mA |
| [13:7] | R/W | CP UP Gain | 7 | 100d<br>64h | Charge Pump UP Gain Control 20 µA per step<br>Affects fractional phase noise and lock detect settings<br>0d = 0 µA<br>1d = 20 µA<br>2d = 40 µA<br>...<br>127d = 2.54mA Default 2mA |
| [20:14] | R/W | Offset Magnitude | 7 | 81d | Charge Pump Offset Control 5 µA/step<br>Affects fractional phase noise and lock detect settings<br>0d = 0 µA<br>1d = 5 µA<br>2d = 10 µA<br>...<br>127d = 635 µA Default 405µA |
| [21] | R/W | Offset UP enable | 1 | 0 | Sets Direction of Reg 09h[20:14] Up, 0- UP Offset Off |
| [22] | R/W | Offset DN enable | 1 | 1 | Sets Direction of Reg 09h[20:14] Down, 0- DN Offset Off |
| [23] | R/W | HiK charge pump Mode | 1 | 0 | Only recommended with external VCOs and Active Loop Filters. When enabled the HMC1190ALP6NE increases CP current by 3 mA, thereby improving phase noise performance, and increasing loop bandwidth |

## 2.12 Reg 0Ah VCO AutoCal Configuration Register DEFAULT 2046 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [2:0] | R/W | Vtune Resolution | 3 | 6d | Used by internlan AutoCal state machine<br>R Divider Cycles<br>0 - 1<br>1 - 2<br>2 - 4<br>3 - 8<br>4 - 32<br>5 - 64<br>6 - 128<br>7 - 256<br>div cycles for frequency measurement. Measurement should last > 4 µsec.<br>Note: 1 does not work if R divider = 1. |
| [10:3] | R/W | Reserved | 8 | 16d | Reserved |
| [11] | R/W | AutoCal Disable | 1 | 0 | 0 = AutoCal Enabled<br>1 = AutoCal disabled |
| [12] | R/W | Reserved | 1 | 0 | Reserved |
| [14:13] | R/W | FSM/VSPI Clock Select | 2 | 1 | Set the AutoCal FSM and VSPI Clock (50 MHz maximum)<br>0: Input Crystal Reference<br>1: Input Crystal Reference/4<br>2: Input Crystal Reference/16<br>3: Input Crystal Reference/32 |
| [16:15] | R/W | Reserved | 2 | 0 | Reserved |
| [17] | R/W | Auto relock - one Try | 1 | 0 | 0: Does not attempt to relock if lock is lost<br>1: Attempts to relock if Lock Detect fails for any reason. Only tries once. |
| [23:18] | R/W | Reserved | 5 | 0 | Reserved |

## 2.13 Reg 0Bh PD/CP Register DEFAULT 78061 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [3:0] | R/W | Reserved | 4 | 1 | Reserved |
| [4] | R/W | PD Phase Select | 1 | 0 | Inverts the PD polarity (program to 0)<br>0- Use with a positive tuning slope VCO and Passive Loop Filter (default when using internal VCO)<br>1- Use with a Negative Slope VCO or with an inverting Active Loop Filter with a Positive Slope VCO (Only recommended when using an External VCO, and an active loop filter) |
| [5] | R/W | PD Up Output Enable | 1 | 1 | Enables the PD UP output, see also Reg 0Bh[9] |
| [6] | R/W | PD Down Output Enable | 1 | 1 | Enables the PD DN output, see also Reg 0Bh[10] |
| [8:7] | R/W | Reserved | 2 | 0 | Reserved, Program to 0d. |
| [9] | R/W | Force CP UP | 1 | 0 | Forces CP UP output on if CP is not forced down - Use for Test only |
| [10] | R/W | Force CP DN | 1 | 0 | Forces CP DN output on if CP is not forced up - Use for Test only |
| [11] | R/W | Force CP Mid Rail | 1 | 0 | Force CP MId Rail - Use for Test only (if Force CP UP or Force CP DN are enabled they have precedence) |
| [23:12] | R/W | Reserved | 12 | 120d<br>78h | Reserved. |

## 2.14 Reg 0Ch Exact Frequency Register

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | R/W | Number of Channels per Fpd | 24 | 0 | Comparison Frequency divided by the correction rate. Must be an integer. Frequencies at exactly the correction rate will have zero frequency error. Only works in modulator Mode B(3rd order recommended modulator type in Reg 06h[3:2]). Reg 0Ch must be 0 if using ohter DSM type<br>0: Disabled<br>1: Invalid<br>≥ 2 valid<br>max $2^{24}$-1 = FFFFFFh = 16,777,215d |

## 2.15 Reg 0Fh GPO Register

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [4:0] | R/W | GPO | 5 | 1 | Select signal to be output to SDO pin when enabled<br>DEFAULT LOCK DETECT<br><br>0: Data from Reg0F[5]<br>1: Lock Detect Output<br>2. Lock Detect Trigger<br>3: Lock Detect Window Output<br>4: Ring Osc Test<br>5. Pullup Hard from CSP<br>6. PullDN hard from CSP<br>7. Reserved<br>8: Reference Buffer Output<br>9: Ref Divider Output<br>10: VCO divider Output<br>11. Modulator Clock from VCO divider<br>12. Auxiliary Clock<br>13. Aux SPI Clock<br>14. Aux SPI Enable<br>15. Aux SPI Data Out<br>16. PD DN<br>17. PD UP<br>18. SD3 Clock Delay<br>19. SD3 Core Clock<br>20. AutoStrobe Integer Write<br>21. Autostrobe Frac Write<br>22. Autostrobe Aux SPI<br>23. SPI Latch Enable<br>24. VCO Divider Sync Reset<br>25. Seed Load Strobe<br>26.-29 Not Used<br>30. SPI Output Buffer En<br>31. Soft RSTB |
| [5] | R/W | GPO Test Data | 1 | 0 | 1 - GPO Test Data when GPO_Select = 0 |
| [6] | R/W | Prevent Automux SDO | 1 | 0 | 1- Outputs GPO data only<br>0- Automuxes between SDO and GPO data |
| [7] | R/W | Reserved | 1 | 0 | Reserved |
| [8] | R/W | Disable PFET | 1 | 0 | Program to 1 if external pull-ups are used on the SDO line<br>(Prevents conflicts on the SPI bus) |
| [9] | R/W | Disable NFET | 1 | 0 | Program to 1 if external pull-downs are used on the SDO line<br>(Prevents conflicts on the SPI bus) |
| [23:10] | R/W | Reserved | 14 | 0 | Reserved |

## 2.16 Reg 10h Tuning Register DEFAULT 80 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [7:0] | R | VCO Tune Curve | 8 | 16d<br>10h | VCO selection resulting from AutoCalibration.<br>0- maximum frequency<br>'1111 1111'b- minimum frequency |
| [8] | R | VCO Tuning Busy | 1 | 0 | Indicates if the VCO tuning is in process<br>1- Busy<br>0- Not Busy |

### 2.17 Reg 11h SAR Register (Read Only)

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [18:0] | R | SAR Error Magnitude Count | 19 | $2^{19}$- 1d<br>7FFFFh | SAR Error Magnitude Count |
| [19] | R | SAR Error Sign | 1 | 0 | SAR Error Sign<br>0: positive<br>1: negative |
| [23:20] | R | Reserved | 4 | 0 | Reserved |

### 2.18 Reg 12h GPO/LD Register (Read Only)

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [0] | R | GPO Out | 1 | 0 | GPO Output |
| [1] | R | Lock Detect Out | 1 | 0 | Lock Detect Output |
| [23:2] | R | Reserved | 22 | 7h | Reserved |

### 2.19 Reg 13h BIST Register (Read Only)

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [16:0] | R | Reserved | 16 | 4697d<br>1259h | Reserved |

## 2.20 Reg 14h Auxiliary SPI Register

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [0] | R/W | Aux SPI Mode | 1 | 0 | 1- Use the 3 outputs as an SPI port<br>0- Use the 3 outputs as a static GPO port along with Reg 14h[3:1] |
| [3:1] | R/W | Aux GPO Values | 3 | 0 | 3 Output values can be set indivually when Reg 10h [0] = 1 |
| [4] | R/W | Aux GPO 3.3 V | 1 | 0 | 0- 1.8 V output out of the Auxiliary GPO pins when Reg 10h [0] = 1<br>1- 3.3 V output out of the Auxiliary GPO pins when Reg 10h [0] = 1 |
| [8:5] | R/W | Reserved | 4 | 1 | Reserved |
| [9] | R/W | Phase Sync | 1 | 1 | When set, CHIP_EN pin is used as a trigger for phase synchronization. Can be used to synchronize multiple HMC1190ALP6NE, or to along with the Reg 1Ah value to phase step the output.<br>(Exact Frequency Mode must be enabled) |
| [11:10] | R/W | Aux SPI GPO Output | 2 | 0 | Option to send GPO multiplexed data (ex Lock Detect) to one of the auxiliary outputs<br>0- None<br>1 - to [0]<br>2 - to [1]<br>3 - to [2] |
| [13:12] | R/W | Aux SPI Outputs | 2 | 0 | When disabled:<br>0 - Outputs Hi Z<br>1 - Outputs stay driven<br>2 - Outputs driven to high<br>3 - Outputs driven to low |
| [23:14] | R/W | Reserved | 10 | 0 | Reserved |

## 2.21 Reg 15h Manual VCO Config Register Default F48A0 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [0] | R/W | Manual Calibration Mode | 1 | 0 | 1- VCO subsystem manual calibration enabled<br>0- VCO subsystem manual calibration disabled |
| [5:1] | R/W | Capacitor Switch Setting | 5 | 16d<br>10h | capacitor switch setting |
| [8:6] | R/W | Manual VCO Selection | 3 | 2 | selects the VCO core sub-band |
| [9] | R/W | Manual VCO Tune Enable | 1 | 0 | 1- Manual VCO tuning enabled<br>0- Manual VCO tuning disabled |
| [15:10] | R/W | Reserved | 6 | 18d<br>12h | Reserved |
| [16] | R/W | Enable Auto-Scale CP current | 1 | 1 | 1 - Automatically scale CP current based on VCO frequency and capacitor setting<br>0- Don't scale CP current |
| [23:17] | R/W | Reserved | 7 | 7d | Reserved |

### 2.22 Reg 16h Gain Divider Register Default 6C1 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [5:0] | R/W | RF Divide Ratio | 6 | 1 | 0 - Mute, VCO and PLL buffer On, RF output stages Off<br>1 - Fo<br>2 - Fo/2<br>3 - invalid, defaults to 2<br>4 - Fo/2<br>5 - invalid, defaults to 4<br>6 - Fo/6<br>...<br>60 - Fo/60<br>61 - invalid, defaults to 60<br>62 - Fo/62<br>> 62 - invalid, defaults to 62 |
| [7:6] | R/W | LO Output Buffer Gain Control | 2 | 3 | 3 - Max Gain<br>2 - Max Gain - 3 dB<br>1 - Max Gain - 6 dB<br>0 - Max Gain - 9 dB |
| [9:8] | R/W | LO2 Output Buffer gain Control | 2 | 2 | 3 - Max Gain<br>2 - Max Gain - 3 dB<br>1 - Max Gain - 6 dB<br>0 - Max Gain - 9 dB |
| [10] | R/W | Divider Output Stage Gain Control | 1 | 1 | 1 - Max Gain<br>0 - Max Gain - 3 dB |
| [23:11] | R/W | Reserved | 13 | 0 | Reserved |

## 2.23 Reg 17h Modes Register Default 1AB h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [0] | R/W | VCO SubSys Master Enable | 1 | 1 | Master enable for the entire VCO Subsystem<br>1 - Enable<br>0 - Disable<br>Chip Enable is also required to set as enable mode. |
| [1] | R/W | VCO Enable | 1 | 1 | |
| [2] | R/W | External VCO Buffer Enable | 1 | 0 | External VCO Buffer to output stage enable. Only used when locking an external VCO. |
| [3] | R/W | PLL Buffer Enable | 1 | 1 | PLL Buffer Enable. Used when using an internal VCO. |
| [4] | R/W | LO1 Output Buffer Enable | 1 | 0 | Enables LO1 (LO_P & LO_N pins) output buffer. |
| [5] | R/W | LO2 Output Buffer Enable | 1 | 1 | Enables the LO2 (LO2_N & LO2_P pins) output buffer |
| [6] | R/W | External Input Enable | 1 | 0 | Enables External VCO input |
| [7] | R/W | Pre Lock Mute Enable | 1 | 1 | Mute both output buffers until the PLL is locked |
| [8] | R/W | LO1 Output Single-Ended Enable | 1 | 1 | Enables Single-Ended output mode for LO output<br>1- Single-ended mode, LO_N pin is enabled, and LO_P pin is disabled<br>0- Differential mode, both LO_N and LO_P pins enabled<br>Please note that single-ended output is only available on LO_N pin. |
| [9] | R/W | LO2 Output Single-Ended Enable | 1 | 0 | Enables Single-Ended output mode for LO2 output<br>1- Single-ended mode, LO2_N pin is enabled, and LO2_P pin is disabled<br>0- Differential mode, both LO2_N and LO2_P pins enabled<br>Please note that single-ended output is only available on LO2_N pin. |
| [10] | R/W | Reserved | 1 | 0 | Reserved |
| [11] | R/W | Charge Pump Output Select | 1 | 0 | Connects CP to CP1 or CP2 output.<br>0: CP1<br>1: CP2 |
| [23:12] | R/W | Reserved | 12 | 0 | Reserved |

## 2.24 Reg 18h Bias Register Default 54C1 h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [18:0] | R/W | Reserved | 19 | 21697d<br>54C1h | Reserved |
| [19] | R/W | External Input buffer BIAS bit0 | 1 | 0 | External Input buffer BIAS bit0 |
| [20] | R/W | External Input buffer BIAS bit1 | 1 | 0 | External Input buffer BIAS bit1 |
| [23:21] | R/W | Reserved | 3 | 0 | Reserved |

## 2.25 Reg 19h Cals Register Default AAA h

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | R/W | Reserved | 2 | 2730d<br>AAAh | Reserved. Program to AB2h. |

## 2.26 Reg 1Ah Seed Register Default B29D0Bh

| Bit | Type | Name | Width | Default | Description |
|---|---|---|---|---|---|
| [23:0] | R/W | Delta Sigma Modulator Seed | 24 | 11705611d B29D0Bh | Used to program output phase relative to the reference frequency. (Exact Frequency Mode required). When not using Exact Frequency Mode and Auto seed Enable Reg 06h[8] =1, Reg 1Ah sets the start phase of output signal. If AutoSeed disable Reg 06h[8] =0, Reg 1Ah is the start phase of the signal after every frequency changel. (LO Phase = 2π xReg 1Ah/($2^{24}$) |

## 3.0 Application Information

The HMC1190ALP6NE is a broadband dual channel, high dynamic range, high gain, low noise, high-linearity down converting mixer with integrated Fractional-N Integer-N PLL and VCO, designed to cover RF frequencies from 700 MHz to 3.8 GHz. The HMC1190ALP6NE`s low noise and high linearity performance makes it suitable for a wide range of transmission standards, including TDD, FDD, LTE, WiMAX, CDMA,GSM, MC-GSM, W-CDMA, UMTS, TD-SCDMA applications.

The HMC1190ALP6NE offers an easy-to-use and complete frequency conversion solution for diversity and MIMO receiver applications in a highly compact 6x6 mm plastic QFN package. The HMC1190ALP6NE greatly simplifies the design of diversity and MIMO receiver applications by increasing the integration level and reducing the number of required circuit elements thereby reducing cost, area, and power consumption.

## 3.1 Principle of Operation

HMC1190ALP6NE's single-ended RF inputs are converted into differential through the on-chip integrated baluns. The single-ended RF inputs are internally broadband matched to 50 Ω and require only standard DC-blocking capacitors.

The HMC1190ALP6NE's IF amplifiers are designed for differential 200 Ω output load impedance. A few external components are required at these IF outputs for the broadband frequency response as recommended in the application circuit.

Refer to the IF output interface section for detailed information.

The HMC1190ALP6NE requires 5V, and 3.3V and supply voltages and external bias voltages. Bias voltages generate reference currents for the IF and LO amplifiers. 3.3V supply voltage and the external bias voltages can be generated from 5.5V supply voltage to operate with a single supply. Please refer to the bias voltage optimization section for more information.

The reference currents to the IF and LO amplifiers can be disabled through SPI interface. See Enabling / Disabling Mixer Features section for details.

## 3.2 Bias Voltage Optimization Using External Resistors

The VCS1, VCS2, LOBIAS1, LOBIAS2, VGATE1 and VGATE2 pins of HMC1190ALP6NE requires different supply voltages.

VGATE1, VGATE2, LOBIAS1, LOBIAS2, VCS1, VCS2 voltages are already generated from 5.5V supply voltage on evaluation board (See the evaluation board schematic available on the HMC1190A product page). These bias voltages can be optimized by external resistors (VCS1, VCS2, LOBIAS1, LOBIAS2, VGATE1, and VGATE2). The resistor values of VCS1, VCS2 on evaluation board are 590 Ohms. LOBIAS1 and LOBIAS2 series resistor values are 270 Ohms. Refer to the VCS Interface and LOBIAS Interface section for more information.

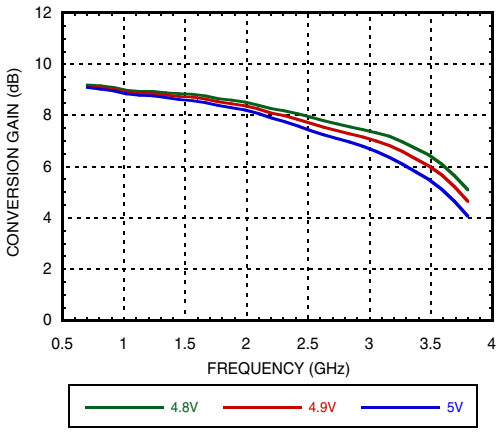
On the evaluation board, VGATE1, VGATE2 pin voltages are 5V; however VGATE1, VGATE2 pin voltages can be tuned between 4.8V and 5V for optimization of Input IP3 and conversion gain performances. After VGATE1, VGATE2 pin voltages are optimized, these pin voltages can be generated from 5V supply by changing the values of series resistors, R54 and R56. Refer to the VGATE interface section for more information.

## 3.3 VGATE Interface

The VGATE1, VGATE2 pins are bias pins for mixer cores. On evaluation board VGATE1, VGATE2 pin voltages are set to 5V. However voltage can be tuned between 4.8V and 5V for optimizing input IP3

and conversion gain performances for desired frequency band. Higher IIP3 values can be obtained by increasing the VGATE1, VGATE2 pin voltages but this will reduce HMC1190ALP6NE`s conversion gain. Figure 74 shows the measured conversion gain and IIP3 for four values of VGATE1, VGATE2 pin voltages.

**Conversion Gain vs. VGATE [1]**




**Input IP3 vs. VGATE [1]**

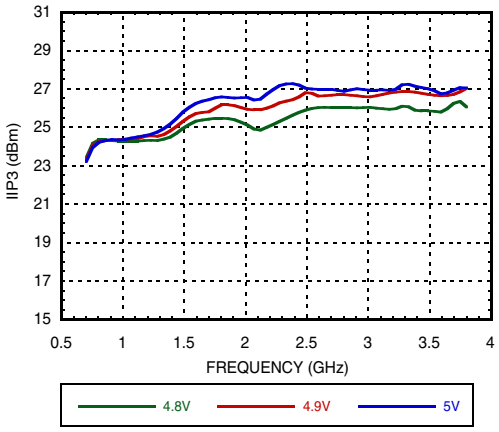



*Figure 74.* Conversion Gain & IIP3 vs. RF Frequency over VGATE Pin Voltage at 25C, IF =150 MHz

After the VGATE voltage is tuned for optimized IIP3 and conversion gain performance, the VGATE pin voltage can be generated from 5V supply voltage by changing the value of series resistors, R54 and R56 from 0 Ohm to an appropriate value.

Table 16 shows the typical resistor values that need to be added in series with VGATE1, VGATE2 pins for different VGATE voltages. A fine tune for R54 and R56 resistors can be used if a better fit is required.

**Table 16. Resistor values for Different VGATE Pin Voltages**

| VGATE1=VGATE2 | R54=R56 |
|---|---|
| 4.8 V | 120 Ohms |
| 4.9 V | 56 Ohms |
| 5 V | 0 Ohm |

## 3.4 VCS Interface and LOBIAS Interface

VCS1, VCS2 pins are bias pins for IF amplifiers on each channel and set the reference currents to these IF amplifiers.The VCS voltage is generated from the 5V supply by series resistors. Higher IIP3 values can be obtained by changing the values of these series resistors R61 and R73, which will change the total supply current of the IF amplifiers which can be seen on Table 17.

LOBIAS1, LOBIAS2 pins are bias pins for LO amplifiers and set the reference currents to these LO amplifiers. The LOBIAS voltage is generated from the 5V supply by series resistors R57 and R71. Changing LOBIAS2 voltage, changes current consumed by LOVDD pin, which can be seen at Table 18.

HMC1190ALP6NE`s flexible design allows users to choose best configuration for their needs. For higher power consumption, better OIP3 values can be achieved.

[1] Balun losses at IF output ports are de-embedded.

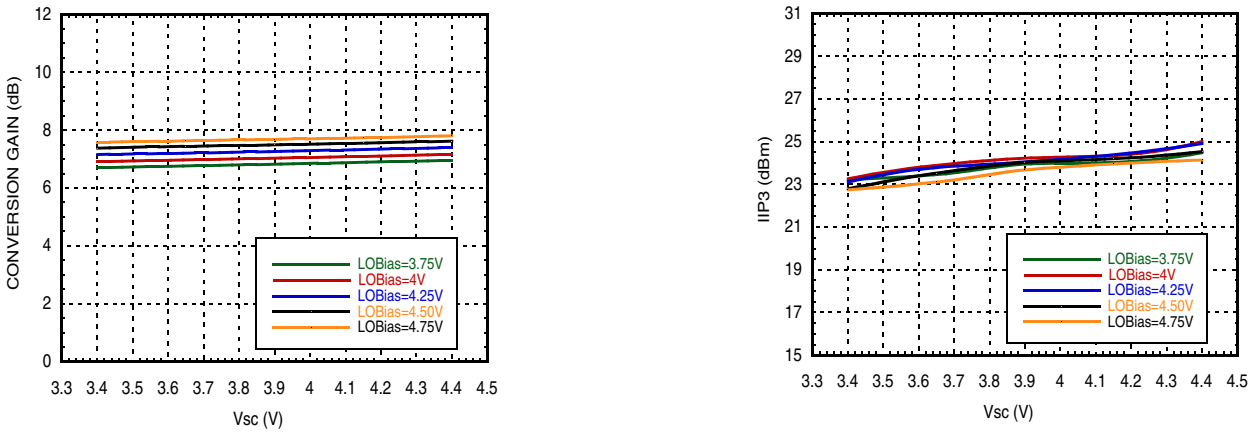



*Figure 75.* Conversion Gain, IIP3 vs. VCS1, VCS2 and LOBIAS2 voltages at 1900 MHz RF Input.

### Table 17. VCS Voltage vs IF Amplifier Currents

| VCS Jumper, J13 (V) | VCS Pin (V) | IF Amp (mA) | R61=R73 |
|---|---|---|---|
| 5 V | 4.37 | 152 | 440 Ohms |
| | 4.15 | 143 | 590 Ohms |
| | 3.94 | 133 | 740 Ohms |
| | 3.73 | 120 | 880 Ohms |
| | 3.56 | 110 | 1 kOhms |

### Table 18. LOBIAS Voltage vs LO Amplifier Currents

| LOBIAS Jumper, J12 (V) | LOBIAS2 Pin (V) | LO Amp (mA) | R57=R71 |
|---|---|---|---|
| 5 V | 4.8 | 146 | 110 Ohms |
| | 4.53 | 138 | 270 Ohms |
| | 4.26 | 129 | 420 Ohms |
| | 4 | 120 | 580 Ohms |
| | 3.74 | 112 | 740 Ohms |

## 3.5 High Band RF Matching and Optimization of CG and IIP3 for High IF Applications

The HMC1190ALP6NE`s RF inputs are internally broadband matched to 50Ω. RF inputs can be externally matched for a specific RF frequency band of interest to further improve Input IP3 (IIP3). Matching RF inputs to a specific RF frequency band can be easily accomplished by adding a series inductor and a shunt capacitor. See Table 19 for values of the external matching components for corresponding RF frequency bands.

LOBIAS1, LOBIAS2 pin voltages can be optimized for a specific RF frequency band by changing the resistor values in series with these pins. Table 18 shows the resistor values (R57, R71) for corresponding LOBIAS pin voltage.

[1] Balun losses at IF output ports are de-embedded.

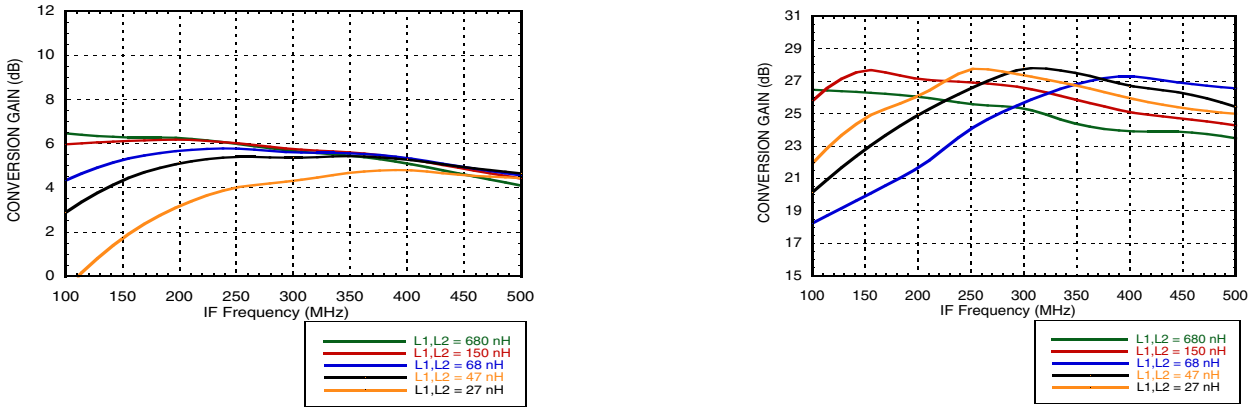



*Figure 76.* Conversion gain, IIP3 vs IF Frequency over IF Amplifier Choke Inductors [1][2]

### Table 19. Components for Selected Frequency Bands

| Tune Frequency | C82 | C81 | C80 | R57 = R71 (LOBias Resistors) |
|---|---|---|---|---|
| 3400 MHz to 3800 MHz | Open | 1 nH | 0.7 pF | 0 Ohms |

## 3.6 Input IP3 Dependence on RF Input Power

The HMC1190ALP6NE accepts a wide range of RF input power. Figure 77 shows the IIP3 vs. RF input power for 1900 MHz RF and 150 MHz IF.

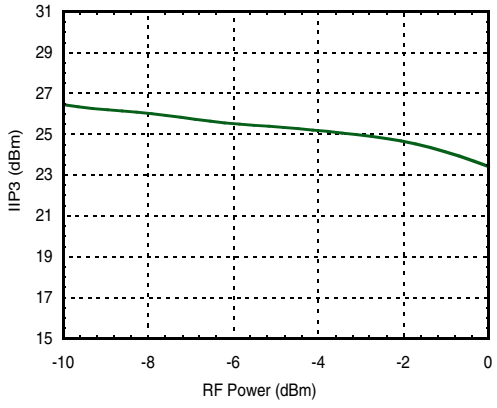



*Figure 77.* IIP3 vs. RF Input Power, RF= 1900 MHz, IF= 150 MHz, VGATE= 5V

## 3.7 Enabling / Disabling Mixer Features

HMC1190ALP6NE has a dual channel down converter core but it can also be configured as a single channel one. When single channel option is desired, HMC1190ALP6NE`s unused IF amplifier can be

[1] Balun losses at IF output ports are de-embedded.
[2] RF = 3400 MHz to 3800 MHz, LO = 3300 MHz, LOBias = 5V

disabled through SPI interface.

HMC1190ALP6NE can also be used as standalone PLL/VCO. In this case all IF and LO buffer amplifiers at mixer side can be disabled through SPI interface. Value of Reg14 should be changed in order to make necessary enable/disable changes. See Table 20 for details.

**Table 20. Mixer Enable / Disable**

| Reg 14h value | Function |
|---|---|
| 3F4 | IF2 disabled, IF1 and LO_Mixer enabled |
| 3F2 | IF1 disabled, IF2 and LO_Mixer enabled |
| 3F6 | IF1, IF2 and LO_Mixer disabled |
| 3F0 | IF1, IF2 and LO_Mixer enabled |

## 3.8 Using an External VCO

In order to configure HMC1190ALP6NE to use with an external VCO, Reg 17h needs to be configured to disable the on chip VCO and VCO to PLL path. Enable External Buffer, second CP link and External I/O switch. To make these changes Reg 17h [0:11] should be configured as 3157d.

Figure 79 shows HMC1190ALP6NE configured as PLL alone used with External VCO HMC384LP4E. Loop Filter components are used as below.

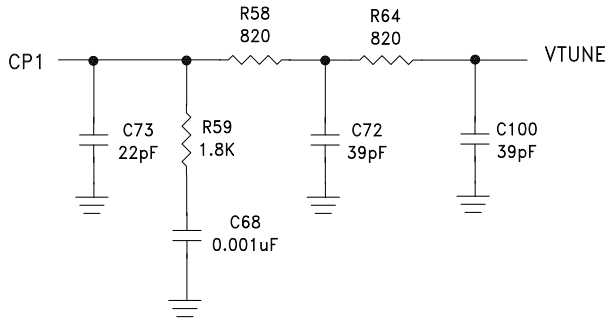



*Figure 78.* Loop filter components for HMC1190ALP6NE is configured as PLL alone used with external VCO HMC384LP4E

[1] Balun losses at IF output ports are de-embedded.

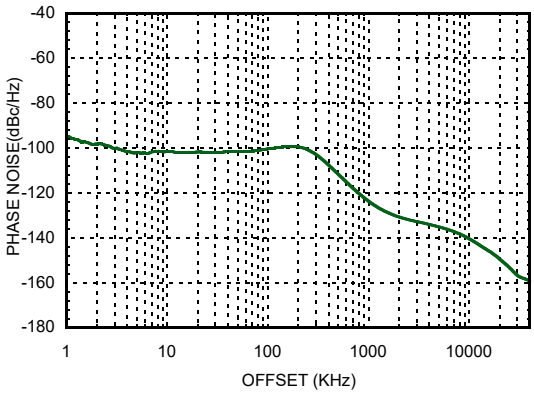



*Figure 79.* Closed Loop Phase Noise with External HMC384LP4E VCO at 2200 MHz.

For detailed theory of operation of PLL/VCO, please refer to the HMC1190A PLLs with Integrated VCOs - RF VCOs Operating Guide which will be provided under HMC1190ALP6NE web page.

# BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER w/ Fractional-N PLL & VCO, 0.7 - 3.8 GHz

# BROADBAND HIGH IP3 DUAL CHANNEL DOWNCONVERTER w/ Fractional-N PLL & VCO, 0.7 - 3.8 GHz