

Description

The CXK77K18R320GB is a high speed CMOS synchronous static RAM with common I/O pins, organized as 2,097,152 words by 18 bits. This synchronous SRAMs integrates input registers, high speed RAM, output registers, and a one-deep write buffer onto a single monolithic IC. Register - Register (R-R) read operations and Late Write (LW) write operations are supported, providing a high-performance user interface.

All address and control input signals except $\overline{G}$ (Output Enable) and ZZ (Sleep Mode) are registered on the rising edge of the K differential input clock.

During read operations, output data is driven valid from the rising edge of K, one full clock cycle after the address is registered.

During write operations, input data is registered on the rising edge of K, one full clock cycle after the address is registered.

Sleep (power down) capability is provided via the ZZ input signal.

Output drivers are series terminated, and output impedance is programmable via the ZQ input pin. By connecting an external control resistor RQ between ZQ and V_{SS} , the impedance of the output drivers can be precisely controlled.

333 MHz operation is obtained from a single 1.8V power supply. JTAG boundary scan interface is provided using a subset of IEEE standard 1149.1 protocol.

Features

- | <u>3 Speed Bins</u> | <u>Cycle Time / Access Time</u> |
|---------------------|---------------------------------|
| -3 | 3.0ns / 1.6ns |
| -33 | 3.3ns / 1.6ns |
| -4 | 4.0ns / 2.0ns |
- Single 1.8V power supply (V_{DD}): $1.8V \pm 0.1V$
Note: 2.5V V_{DD} is also supported. Please contact Sony Memory Marketing Department for further information.
- Dedicated output supply voltage (V_{DDQ}): 1.5V to 1.8V typical
- HSTL-compatible I/O interface with dedicated input reference voltage (V_{REF}): $V_{DDQ}/2$ typical
- Register - Register (R-R) read protocol
- Late Write (LW) write protocol
- Full read/write coherency
- Byte Write capability
- Differential input clocks ($K/\overline{K}$)
- Asynchronous output enable ($\overline{G}$)
- Sleep (power down) mode via dedicated mode pin (ZZ)
- Programmable output driver impedance
- JTAG boundary scan (subset of IEEE standard 1149.1)
- 119 pin (7x17), 1.27mm pitch, 14mm x 22mm Ball Grid Array (BGA) package

2Mb x 18 Pin Assignment (Top View)

	1	2	3	4	5	6	7
A	V _{DDQ}	SA	SA	NC	SA	SA	V _{DDQ}
B	NC	SA	SA	SA (32M)	SA	SA	NC
C	NC	SA	SA	V _{DD}	SA	SA	NC
D	DQb	NC	V _{SS}	ZQ	V _{SS}	DQa	NC
E	NC	DQb	V _{SS}	$\overline{SS}$	V _{SS}	NC	DQa
F	V _{DDQ}	NC	V _{SS}	$\overline{G}$	V _{SS}	DQa	V _{DDQ}
G	NC	DQb	$\overline{SBWb}$	NC	V _{SS}	NC	DQa
H	DQb	NC	V _{SS}	NC	V _{SS}	DQa	NC
J	V _{DDQ}	V _{DD}	V _{REF}	V _{DD}	V _{REF}	V _{DD}	V _{DDQ}
K	NC	DQb	V _{SS}	K	V _{SS}	NC	DQa
L	DQb	NC	V _{SS}	$\overline{K}$	$\overline{SBWa}$	DQa	NC
M	V _{DDQ}	DQb	V _{SS}	$\overline{SW}$	V _{SS}	NC	V _{DDQ}
N	DQb	NC	V _{SS}	SA	V _{SS}	DQa	NC
P	NC	DQb	V _{SS}	SA	V _{SS}	NC	DQa
R	NC	SA	M1 ⁽¹⁾	V _{DD}	M2 ⁽²⁾	SA	NC
T	NC	SA (x18)	SA	NC (x36)	SA	SA (x18)	ZZ
U	V _{DDQ}	TMS	TDI	TCK	TDO	RSVD ⁽³⁾	V _{DDQ}

Notes:

1. Pad Location 3R is defined as an M1 mode pin in LW SRAMs. However, it must be tied “low” in this device.
2. Pad Location 5R is defined as an M2 mode pin in LW SRAMs. However, it must be tied “high” in this device.
3. Pad Location 6U must be left unconnected. It is used by Sony for internal test purposes.

Pin Description

Symbol	Type	Description
SA	Input	Synchronous Address Inputs - Registered on the rising edge of K.
DQa, DQb	I/O	Synchronous Data Inputs / Outputs - Registered on the rising edge of K during write operations. Driven from the rising edge of K during read operations. DQa - indicates Data Byte a DQb - indicates Data Byte b
K, $\overline{K}$	Input	Differential Input Clocks
$\overline{SS}$	Input	Synchronous Select Input - Registered on the rising edge of K. $\overline{SS} = 0$ enables the device to accept read and write commands $\overline{SS} = 1$ disables the device
$\overline{SW}$	Input	Synchronous Write Enable Input - Registered on the rising edge of K. $\overline{SW} = 0$ specifies a write operation when the device is enabled $\overline{SW} = 1$ specifies a read operation when the device is enabled
$\overline{SBWa}$, $\overline{SBWb}$	Input	Synchronous Byte Write Enable Inputs - Registered on the rising edge of K. $\overline{SBWa} = 0$ specifies write Data Byte a during a write operation $\overline{SBWb} = 0$ specifies write Data Byte b during a write operation
$\overline{G}$	Input	Asynchronous Output Enable Input - Deasserted (high) disables the data output drivers.
ZZ	Input	Asynchronous Sleep Mode Input - Asserted (high) forces the device into low-power mode.
M1, M2	Input	Read Operation Protocol Select - These mode pins must be tied “low” and “high” respectively to select Register - Register read operations.
ZQ	Input	Output Driver Impedance Control Resistor Input - This pin must be connected to V_{SS} through an external resistor R_Q to program data output driver impedance. See the Programmable Output Driver Impedance section for further information.
V_{DD}		1.8V Core Power Supply - Core supply voltage.
V_{DDQ}		Output Power Supply - Output buffer supply voltage.
V_{REF}		Input Reference Voltage - Input buffer threshold voltage.
V_{SS}		Ground
TCK	Input	JTAG Clock
TMS	Input	JTAG Mode Select - Weakly pulled “high” internally.
TDI	Input	JTAG Data In - Weakly pulled “high” internally.
TDO	Output	JTAG Data Out
RSVD		Reserved - This pin is reserved for Sony test purposes. It must be left unconnected.
NC		No Connect - These pins are true no-connects, i.e. there is no internal chip connection to these pins. They can be left unconnected or tied directly to V_{DD} , V_{DDQ} , or V_{SS} .

•Clock Truth Table

K	ZZ	$\overline{SS}$ (t_n)	$\overline{SW}$ (t_n)	$\overline{SBW}_x$ (t_n)	$\overline{G}$	Operation	DQ (t_n)	DQ (t_{n+1})
X	1	X	X	X	X	Sleep (Power Down) Mode	Hi - Z	Hi - Z
↑	0	1	X	X	X	Deselect	***	Hi - Z
↑	0	0	1	X	1	Read	Hi - Z	Hi - Z
↑	0	0	1	X	0	Read	***	Q(t_n)
↑	0	0	0	0	X	Write All Bytes	***	D(t_n)
↑	0	0	0	X	X	Write Bytes With $\overline{SBW}_x = 0$	***	D(t_n)
↑	0	0	0	1	X	Abort Write	***	Hi - Z

Notes:

1. “1” = input “high”; “0” = input “low”; “X” = input “don’t care”.
2. “***” indicates that the input requirement or output state is determined by the previous operation.
3. DQs are tri-stated in response to Write and Deselect commands, one cycle after the command is sampled.

•Sleep (Power Down) Mode

Sleep (power down) mode is provided through the asynchronous input signal ZZ. When ZZ is asserted (high), the output drivers are disabled and the SRAM begins to draw standby current. Contents of the memory array are preserved. An enable time (t_{ZZE}) must be met before the SRAM is guaranteed to be in sleep mode, and a recovery time (t_{ZZR}) must be met before the SRAM can resume normal operation.

•Programmable Impedance Output Drivers

These devices have programmable impedance output drivers. The output impedance is controlled by an external resistor RQ connected between the SRAM’s ZQ pin and V_{SS} , and is equal to one-fifth the value of this resistor, nominally. See the DC Electrical Characteristics section for further information.

Output Driver Impedance Power-Up Requirements

Output driver impedance will reach the programmed value within 8192 cycles after power-up. Consequently, it is recommended that Read operations not be initiated until after the initial 8192 cycles have elapsed.

Output Driver Impedance Updates

Output driver impedance is updated during Write and Deselect operations when the output driver is disabled.

•Power-Up Sequence

For reliability purposes, Sony recommends that power supplies power up in the following sequence: V_{SS} , V_{DD} , V_{DDQ} , V_{REF} and Inputs. V_{DDQ} should never exceed V_{DD} . If this power supply sequence cannot be met, a large bypass diode may be required between V_{DD} and V_{DDQ} . Please contact Sony Memory Application Department for further information.

•Absolute Maximum Ratings

Parameter	Symbol	Rating	Units
Supply Voltage	V_{DD}	-0.5 to +2.5	V
Output Supply Voltage	V_{DDQ}	-0.5 to +2.3	V
Input Voltage (Address, Control, Data, Clock)	V_{IN}	-0.5 to $V_{DDQ} + 0.5$ (2.3V max)	V
Input Voltage (M1, M2)	V_{MIN}	-0.5 to $V_{DD} + 0.5$ (2.5V max)	V
Input Voltage (TCK, TMS, TDI)	V_{TIN}	-0.5 to $V_{DD} + 0.5$ (2.5V max)	V
Operating Temperature	T_A	0 to 85	°C
Junction Temperature	T_J	0 to 110	°C
Storage Temperature	T_{STG}	-55 to 150	°C

Notes: Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions other than those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

•BGA Package Thermal Characteristics

Parameter	Symbol	Rating	Units
Junction to Case Temperature	Θ_{JC}	3.6	°C/W

•I/O Capacitance

($T_A = 25^\circ\text{C}$, $f = 1\text{ MHz}$)

Parameter		Symbol	Test conditions	Min	Max	Units
Input Capacitance	Address	C_{IN}	$V_{IN} = 0V$	---	4.0	pF
	Control	C_{IN}	$V_{IN} = 0V$	---	4.0	pF
	Clock	C_{KIN}	$V_{KIN} = 0V$	---	4.5	pF
Output Capacitance	Data	C_{OUT}	$V_{OUT} = 0V$	---	5.0	pF

Note: These parameters are sampled and are not 100% tested.

•DC Recommended Operating Conditions

(V_{SS} = 0V, T_A = 0 to 85°C)

Parameter	Symbol	Min	Typ	Max	Units	Notes
Supply Voltage	V _{DD}	1.7	1.8	1.9	V	1
Output Supply Voltage	V _{DDQ}	1.4	---	V _{DD}	V	
Input Reference Voltage	V _{REF}	V _{DDQ} /2 - 0.1	V _{DDQ} /2	V _{DDQ} /2 + 0.1	V	2
Input High Voltage (Address, Control, Data)	V _{IH}	V _{REF} + 0.1	---	V _{DDQ} + 0.3	V	3
Input Low Voltage (Address, Control, Data)	V _{IL}	-0.3	---	V _{REF} - 0.1	V	4
Input High Voltage (M1, M2)	V _{MIH}	V _{REF} + 0.3	---	V _{DD} + 0.3	V	
Input Low Voltage (M1, M2)	V _{MIL}	-0.3	---	V _{REF} - 0.3	V	
Clock Input Signal Voltage	V _{KIN}	-0.3	---	V _{DDQ} + 0.3	V	
Clock Input Differential Voltage	V _{DIF}	0.2	---	V _{DDQ} + 0.6	V	
Clock Input Common Mode Voltage	V _{CM}	V _{DDQ} /2 - 0.1	V _{DDQ} /2	V _{DDQ} /2 + 0.1	V	

1. V_{DD} = 2.5V +/- 5% is also supported. Please contact Sony Memory Marketing Department for further information.
2. The peak-to-peak AC component superimposed on V_{REF} may not exceed 5% of the DC component.
3. V_{IH} (max) AC = V_{DDQ} + 0.9V for pulse widths less than one-quarter of the cycle time (t_{CYC}/4).
4. V_{IL} (min) AC = -0.9V for pulse widths less than one-quarter of the cycle time (t_{CYC}/4).

•DC Electrical Characteristics

(V_{DD} = 1.8V ± 0.1V, V_{SS} = 0V, T_A = 0 to 85°C)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Units	Notes
Input Leakage Current (Address, Control, Clock)	I _{LI}	V _{IN} = V _{SS} to V _{DDQ}	-5	---	5	uA	
Input Leakage Current (M1, M2)	I _{MLI}	V _{MIN} = V _{SS} to V _{DD}	-5	---	5	uA	
Output Leakage Current	I _{LO}	V _{OUT} = V _{SS} to V _{DDQ} $\overline{G} = V_{IH}$	-5	---	5	uA	
Average Power Supply Operating Current	I _{DD-3} I _{DD-33} I _{DD-4}	I _{OUT} = 0 mA $\overline{SS} = V_{IL}$, ZZ = V _{IL}	---	---	650 600 540	mA	
Power Supply Standby Current	I _{SB}	I _{OUT} = 0 mA ZZ = V _{IH}	---	---	180	mA	1
Output High Voltage	V _{OH}	I _{OH} = -6.0 mA RQ = 250Ω	V _{DDQ} - 0.4	---	---	V	
Output Low Voltage	V _{OL}	I _{OL} = 6.0 mA RQ = 250Ω	---	---	0.4	V	
Output Driver Impedance	R _{OUT}	V _{OH} , V _{OL} = V _{DDQ} /2 RQ < 150Ω	---	---	35 (30*1.15)	Ω	2
		V _{OH} , V _{OL} = V _{DDQ} /2 150Ω ≤ RQ ≤ 300Ω	(RQ/5)* 0.85	RQ/5	(RQ/5)* 1.15	Ω	
		V _{OH} , V _{OL} = V _{DDQ} /2 RQ > 300Ω	51 (60*0.85)	---	---	Ω	3

1. This parameter is guaranteed at T_A = 0 to 55°C.
2. For maximum output drive (i.e. minimum impedance), the ZQ pin can be tied directly to V_{SS}.
3. For minimum output drive (i.e. maximum impedance), the ZQ pin can be left unconnected or tied to V_{DDQ}.

•AC Electrical Characteristics

(V_{DD} = 1.8V ± 0.1V, V_{SS} = 0V, T_A = 0 to 85°C)

Parameter	Symbol	-3		-33		-4		Units	Notes
		Min	Max	Min	Max	Min	Max		
Input Cycle Time	t _{KHKH}	3.0	---	3.3	---	4.0	---	ns	
Input Clock High Pulse Width	t _{KHKL}	1.2	---	1.3	---	1.5	---	ns	
Input Clock Low Pulse Width	t _{KLKH}	1.2	---	1.3	---	1.5	---	ns	
Address Input Setup Time	t _{AVKH}	0.3	---	0.3	---	0.3	---	ns	1
Address Input Hold Time	t _{KHAX}	0.5	---	0.5	---	0.5	---	ns	
Write Enable Input Setup Time	t _{WVKH}	0.3	---	0.3	---	0.3	---	ns	1
Write Enable Input Hold Time	t _{KHWX}	0.5	---	0.5	---	0.5	---	ns	
Sync Select Input Setup Time	t _{SVKH}	0.3	---	0.3	---	0.3	---	ns	1
Sync Select Input Hold Time	t _{KHSX}	0.5	---	0.5	---	0.5	---	ns	
Data Input Setup Time	t _{DVKH}	0.3	---	0.3	---	0.3	---	ns	1
Data Input Hold Time	t _{KHDX}	0.5	---	0.5	---	0.5	---	ns	
Input Clock High to Output Data Valid	t _{KHQV}	---	1.6	---	1.6	---	2.0	ns	
Input Clock High to Output Data Hold	t _{KHQX}	0.5	---	0.5	---	0.5	---	ns	2
Input Clock High to Output Data Low-Z	t _{KHQX1}	0.5	---	0.5	---	0.5	---	ns	2,3
Input Clock High to Output Data High-Z	t _{KHQZ}	---	1.8	---	1.8	---	2.2	ns	2,3
Output Enable Low to Output Data Valid	t _{GLQV}	---	2.5	---	2.5	---	2.5	ns	
Output Enable Low to Output Data Low-Z	t _{GLQX}	0.3	---	0.3	---	0.3	---	ns	2,3
Output Enable High to Output Data High-Z	t _{GHQZ}	---	2.5	---	2.5	---	2.5	ns	2,3
Sleep Mode Enable Time	t _{ZZE}	---	15	---	15	---	15	ns	2
Sleep Mode Recovery Time	t _{ZZR}	20	---	20	---	20	---	ns	2

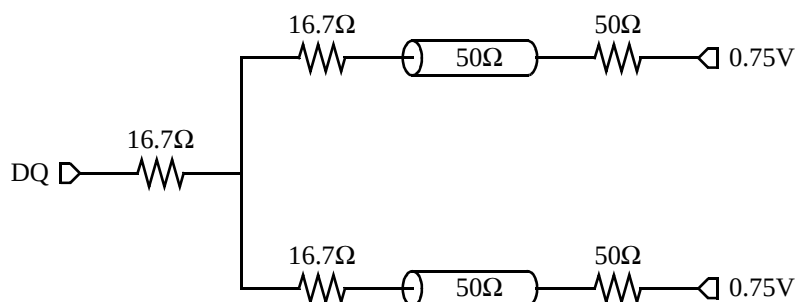
1. These parameters are measured from V_{REF} ± 200mV to the clock mid-point.

2. These parameters are guaranteed by design through extensive corner-lot characterization.

3. These parameters are measured at ± 50mV from steady state voltage.

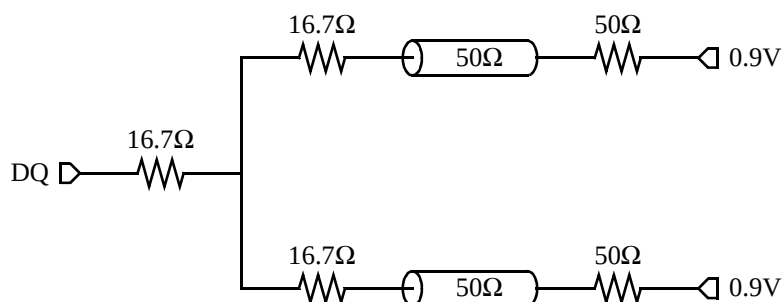
•AC Test Conditions ($V_{DDQ} = 1.5V$)($V_{DD} = 1.8V \pm 0.1V$, $V_{DDQ} = 1.5V \pm 0.1V$, $T_A = 0$ to $85^\circ C$)

Item	Symbol	Conditions	Units	Notes
Input Reference Voltage	V_{REF}	0.75	V	
Input High Level	V_{IH}	1.25	V	
Input Low Level	V_{IL}	0.25	V	
Input Rise & Fall Time		2.0	V/ns	
Input Reference Level		0.75	V	
Clock Input High Voltage	V_{KIH}	1.25	V	$V_{DIF} = 1.0V$
Clock Input Low Voltage	V_{KIL}	0.25	V	$V_{DIF} = 1.0V$
Clock Input Common Mode Voltage	V_{CM}	0.75	V	
Clock Input Rise & Fall Time		2.0	V/ns	
Clock Input Reference Level		K/ $\overline{K}$ cross	V	
Output Reference Level		0.75	V	
Output Load Conditions		$R_Q = 250\Omega$		See Figure 1 below

Figure 1: AC Test Output Load ($V_{DDQ} = 1.5V$)

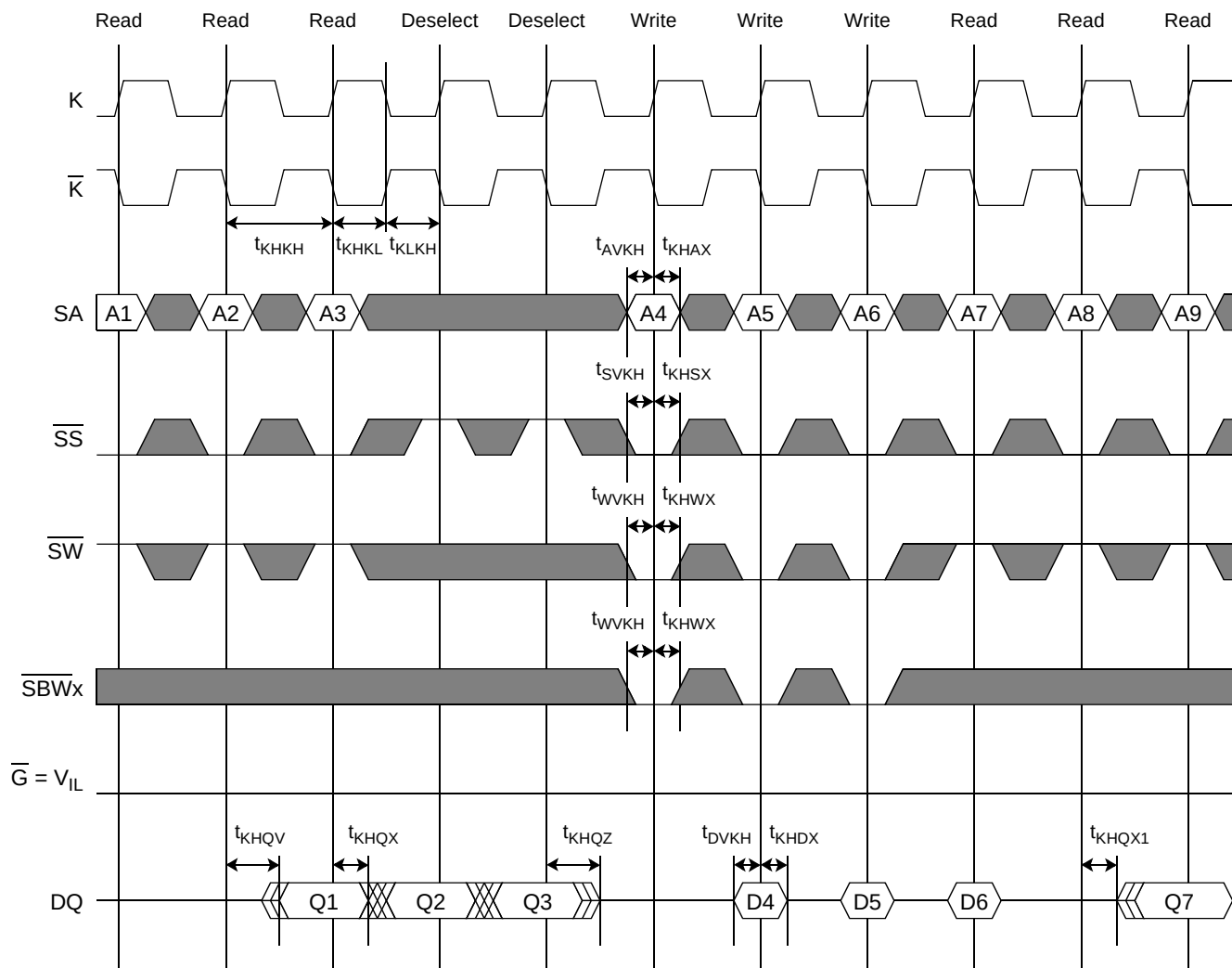
•AC Test Conditions ($V_{DDQ} = 1.8V$)($V_{DD} = V_{DDQ} = 1.8V \pm 0.1V$, $T_A = 0$ to $85^\circ C$)

Item	Symbol	Conditions	Units	Notes
Input Reference Voltage	V_{REF}	0.9	V	
Input High Level	V_{IH}	1.4	V	
Input Low Level	V_{IL}	0.4	V	
Input Rise & Fall Time		2.0	V/ns	
Input Reference Level		0.9	V	
Clock Input High Voltage	V_{KIH}	1.4	V	$V_{DIF} = 1.0V$
Clock Input Low Voltage	V_{KIL}	0.4	V	$V_{DIF} = 1.0V$
Clock Input Common Mode Voltage	V_{CM}	0.9	V	
Clock Input Rise & Fall Time		2.0	V/ns	
Clock Input Reference Level		K/ $\overline{K}$ cross	V	
Output Reference Level		0.9	V	
Output Load Conditions		$R_Q = 250\Omega$		See Figure 2 below

Figure 2: AC Test Output Load ($V_{DDQ} = 1.8V$)

Read-Write-Read Timing Diagram Synchronously Controlled via $\overline{SS}$ and Deselect Operations ($\overline{G} = \text{Low}$)

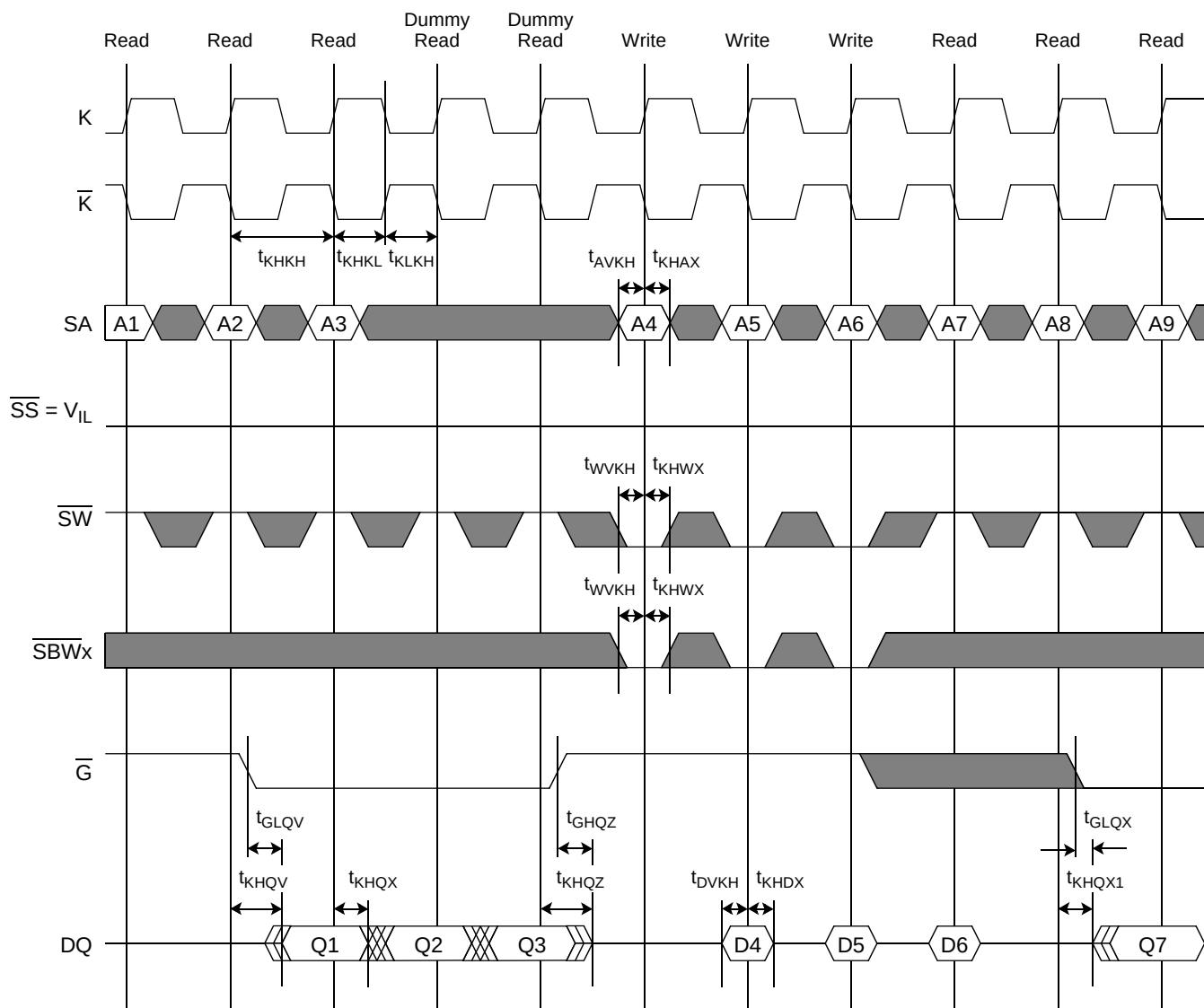
Figure 3



Note: In the diagram above, two Deselect operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Deselect operation may be sufficient.

Read-Write-Read Timing Diagram
Asynchronously Controlled via $\overline{G}$ and Dummy Read Operations ($\overline{SS} = \text{Low}$)

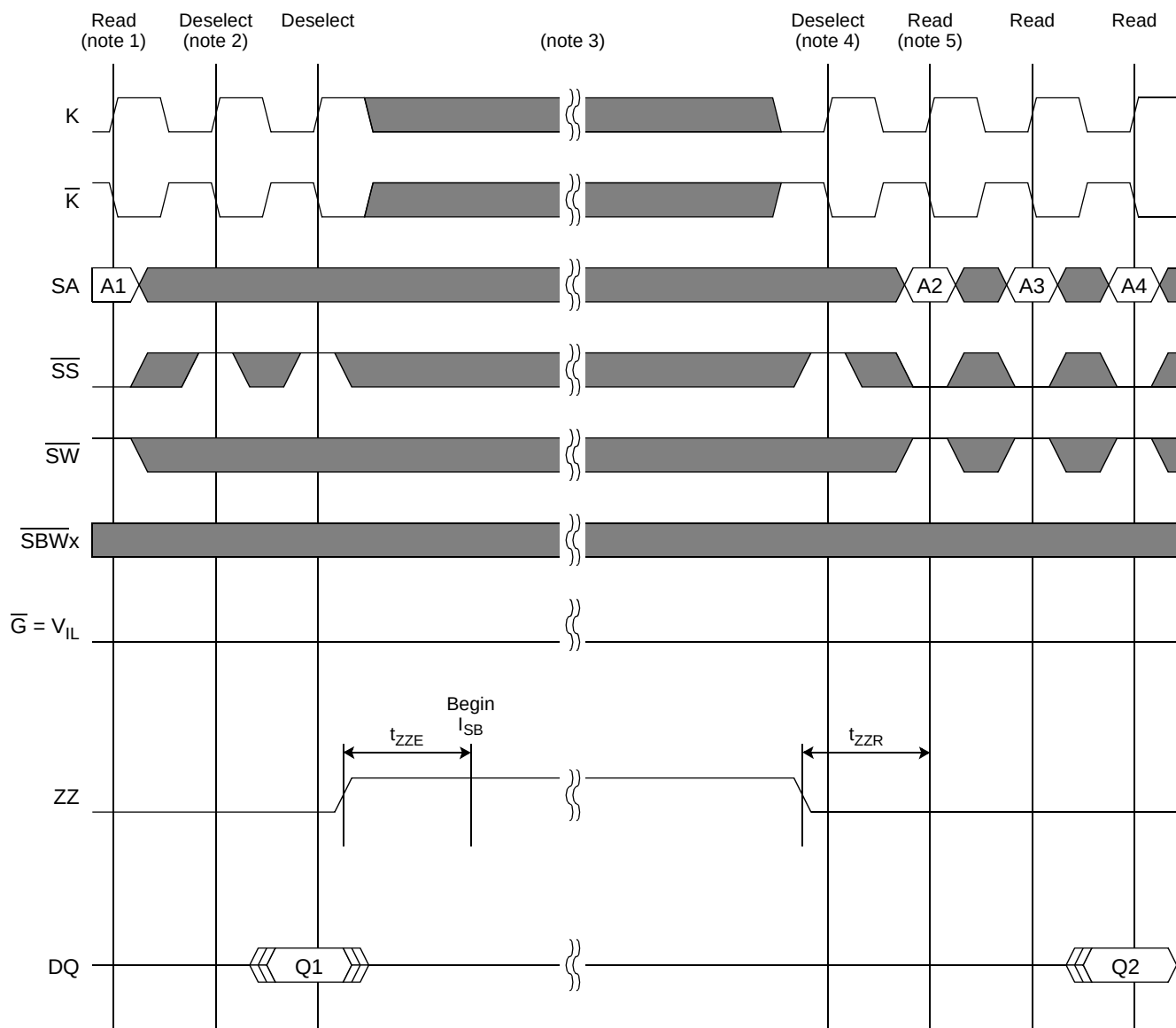
Figure 4



Note: In the diagram above, two Dummy Read operations are inserted between Read and Write operations to control the data bus transition from output to input. This depiction is for clarity purposes only. It is NOT a requirement. Depending on the application, one Dummy Read operation may be sufficient.

Sleep (Power-Down) Mode Timing Diagram

Figure 5

**Notes:**

- 1: This can be any operation. The depiction of a Read operation here is provided only as an example.
- 2: Before ZZ is asserted, at least two (2) Deselect operations must be initiated after the last Read or Write operation is initiated, in order to ensure the successful completion of the last Read or Write operation.
- 3: While ZZ is asserted, all of the SRAM's address, control, data, and clock inputs are ignored.
- 4: After ZZ is deasserted, Deselect operations must be initiated until the specified recovery time (t_{ZZR}) has been met. Read and Write operations may NOT be initiated during this time.
- 5: This can be any operation. The depiction of a Read operation here is provided only as an example.

•Test Mode Description

These devices provide a JTAG Test Access Port (TAP) and Boundary Scan interface using a limited set of IEEE std. 1149.1 functions. This test mode is intended to provide a mechanism for testing the interconnect between master (processor, controller, etc.), SRAMs, other components, and the printed circuit board.

In conformance with a subset of IEEE std. 1149.1, these devices contain a TAP Controller and four TAP Registers. The TAP Registers consist of one Instruction Register and three Data Registers (ID, Bypass, and Boundary Scan Registers).

The TAP consists of the following four signals:

TCK:	Test Clock	Induces (clocks) TAP Controller state transitions.
TMS:	Test Mode Select	Inputs commands to the TAP Controller. Sampled on the rising edge of TCK.
TDI:	Test Data In	Inputs data serially to the TAP Registers. Sampled on the rising edge of TCK.
TDO:	Test Data Out	Outputs data serially from the TAP Registers. Driven from the falling edge of TCK.

Disabling the TAP

When JTAG is not used, TCK should be tied “low” to prevent clocking the SRAM. TMS and TDI should either be tied “high” through a pull-up resistor or left unconnected. TDO should be left unconnected.

Note: Operation of the TAP does not interfere with normal SRAM operation except when the SAMPLE-Z instruction is selected. Consequently, TCK, TMS, and TDI can be controlled any number of ways without adversely affecting the functionality of the device.

JTAG DC Recommended Operating Conditions

($V_{DD} = 1.8V \pm 0.1V$, $V_{SS} = 0V$, $T_A = 0$ to $85^\circ C$)

Parameter	Symbol	Test Conditions	Min	Max	Units
JTAG Input High Voltage	V_{TIH}	---	1.2	$V_{DD} + 0.3$	V
JTAG Input Low Voltage	V_{TIL}	---	-0.3	0.6	V
JTAG Output High Voltage (CMOS)	V_{TOH}	$I_{TOH} = -100\mu A$	$V_{DD} - 0.1$	---	V
JTAG Output Low Voltage (CMOS)	V_{TOL}	$I_{TOL} = 100\mu A$	---	0.1	V
JTAG Output High Voltage (TTL)	V_{TOH}	$I_{TOH} = -8.0mA$	$V_{DD} - 0.4$	---	V
JTAG Output Low Voltage (TTL)	V_{TOL}	$I_{TOL} = 8.0mA$	---	0.4	V
JTAG Input Leakage Current	I_{TLI}	$V_{TIN} = V_{SS}$ to V_{DD}	-10	10	μA

JTAG AC Test Conditions

($V_{DD} = 1.8V \pm 0.1V$, $V_{SS} = 0V$, $T_A = 0$ to $85^\circ C$)

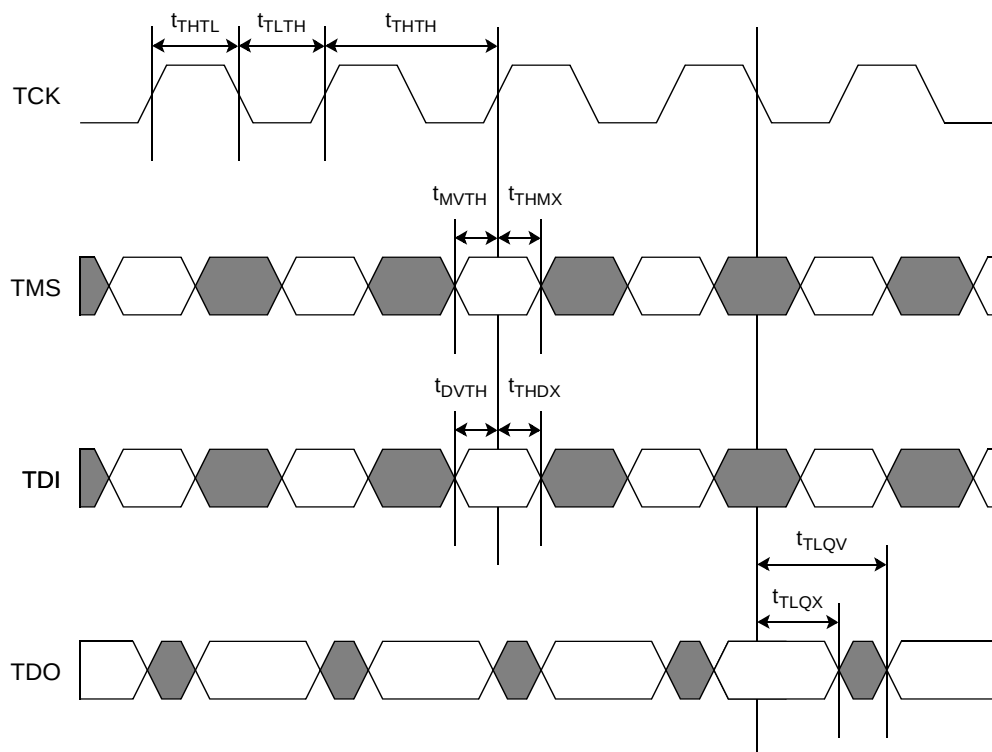
Parameter	Symbol	Conditions	Units	Notes
JTAG Input High Level	V_{TIH}	1.8	V	
JTAG Input Low Level	V_{TIL}	0.0	V	
JTAG Input Rise & Fall Time		1.0	V/ns	
JTAG Input Reference Level		0.9	V	
JTAG Output Reference Level		0.9	V	
JTAG Output Load Condition				See Fig.2 (page 10)

JTAG AC Electrical Characteristics

Parameter	Symbol	Min	Max	Unit
TCK Cycle Time	t_{THTH}	50		ns
TCK High Pulse Width	t_{HTL}	20		ns
TCK Low Pulse Width	t_{LTH}	20		ns
TMS Setup Time	t_{MVTH}	5		ns
TMS Hold Time	t_{THMX}	5		ns
TDI Setup Time	t_{DVTH}	5		ns
TDI Hold Time	t_{THDX}	5		ns
Capture Setup Time (Address, Control, Data, Clock)	t_{CS}	5		ns
Capture Hold Time (Address, Control, Data, Clock)	t_{CH}	5		ns
TCK Low to TDO Valid	t_{TLQV}		10	ns
TCK Low to TDO Hold	t_{TLQX}	0		ns

JTAG Timing Diagram

Figure 6



TAP Controller

The TAP Controller is a 16-state state machine that controls access to the various TAP Registers and executes the operations associated with each TAP Instruction. State transitions are controlled by TMS and occur on the rising edge of TCK.

The TAP Controller enters the “Test-Logic Reset” state in one of two ways:

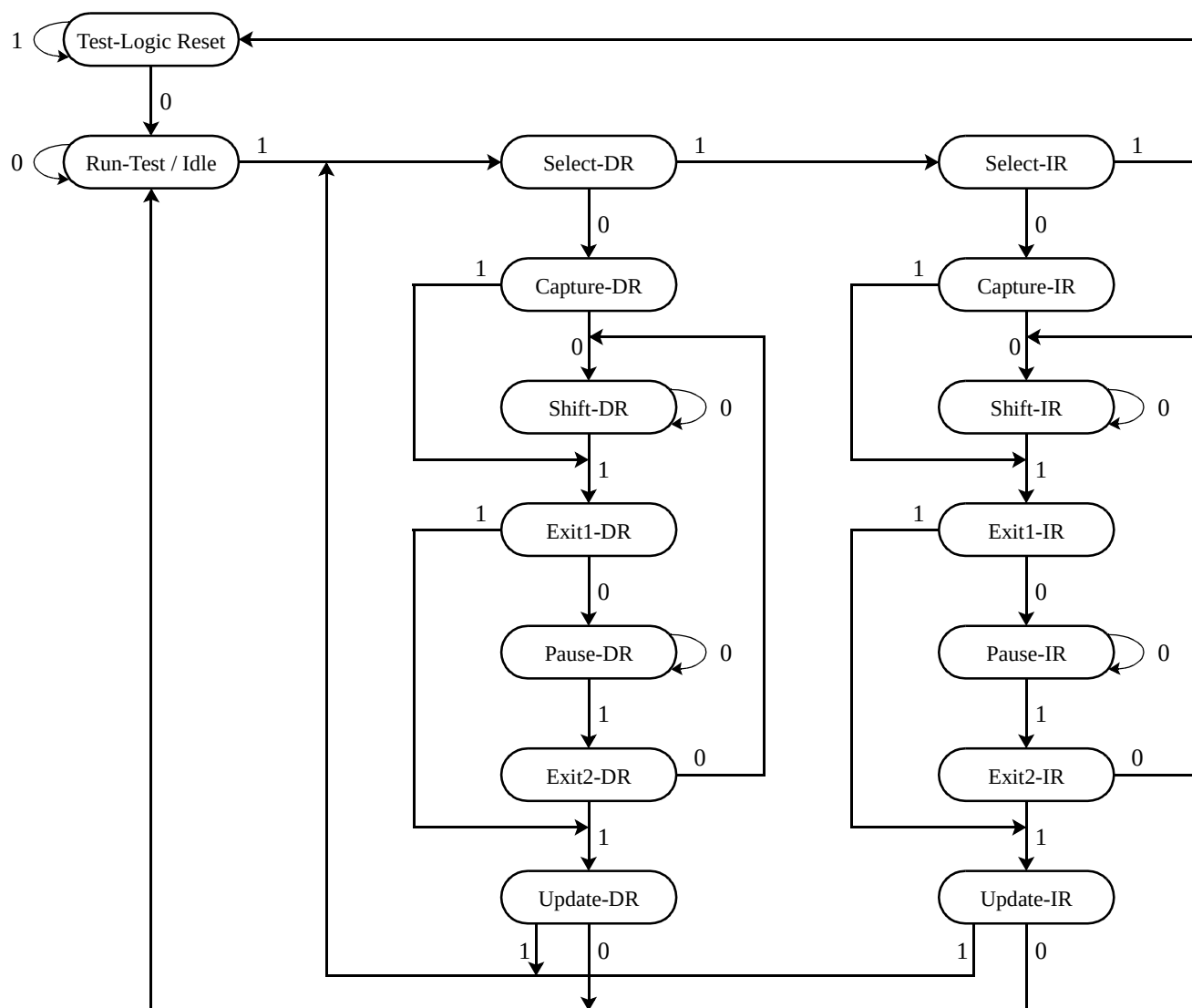
1. At power up.
2. When a logic “1” is applied to TMS for at least 5 consecutive rising edges of TCK.

The TDI input receiver is sampled only when the TAP Controller is in either the “Shift-IR” state or the “Shift-DR” state.

The TDO output driver is active only when the TAP Controller is in either the “Shift-IR” state or the “Shift-DR” state.

TAP Controller State Diagram

Figure 7



TAP Registers

TAP Registers are serial shift registers that capture serial input data (from TDI) on the rising edge of TCK, and drive serial output data (to TDO) from the falling edge of TCK. They are divided into two groups: “Instruction Registers” (IR), which are manipulated via the “IR” states in the TAP Controller, and “Data Registers” (DR), which are manipulated via the “DR” states in the TAP Controller.

Instruction Register (IR - 3 Bits)

The Instruction Register stores the various TAP Instructions supported by these devices. It is loaded with the IDCODE instruction at power-up, and when the TAP Controller is in the “Test-Logic Reset” and “Capture-IR” states. It is inserted between TDI and TDO when the TAP Controller is in the “Shift-IR” state, at which time it can be loaded with a new instruction. However, newly loaded instructions are not executed until the TAP Controller has reached the “Update-IR” state.

The Instruction Register is 3 bits wide, and is encoded as follows:

Code (2:0)	Instruction	Description
000	BYPASS	See code “111”.
001	IDCODE	Loads a predefined device- and manufacturer-specific identification code into the ID Register when the TAP Controller is in the “Capture-DR” state, and inserts the ID Register between TDI and TDO when the TAP Controller is in the “Shift-DR” state. See the ID Register description for more information.
010	SAMPLE-Z	Loads the individual logic states of all signals composing the SRAM’s I/O ring into the Boundary Scan Register when the TAP Controller is in the “Capture-DR” state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the “Shift-DR” state. Also disables the SRAM’s data output drivers. See the Boundary Scan Register description for more information.
011	PRIVATE	Do not use. Reserved for manufacturer use only.
100	SAMPLE	Loads the individual logic states of all signals composing the SRAM’s I/O ring into the Boundary Scan Register when the TAP Controller is in the “Capture-DR” state, and inserts the Boundary Scan Register between TDI and TDO when the TAP Controller is in the “Shift-DR” state. See the Boundary Scan Register description for more information.
101	PRIVATE	Do not use. Reserved for manufacturer use only.
110	PRIVATE	Do not use. Reserved for manufacturer use only.
111	BYPASS	Loads a logic “0” into the Bypass Register when the TAP Controller is in the “Capture-DR” state, and inserts the Bypass Register between TDI and TDO when the TAP Controller is in the “Shift-DR” state. See the Bypass Register description for more information.

Bit 0 is the LSB and Bit 2 is the MSB. When the Instruction Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

Bypass Register (DR - 1 Bit)

The Bypass Register is one bit wide, and provides the minimum length serial path between TDI and TDO. It is loaded with a logic “0” when the BYPASS instruction has been loaded in the Instruction Register and the TAP Controller is in the “Capture-DR” state. It is inserted between TDI and TDO when the BYPASS instruction has been loaded into the Instruction Register and the TAP Controller is in the “Shift-DR” state.

ID Register (DR - 32 Bits)

The ID Register is loaded with a predetermined device- and manufacturer-specific identification code when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the “Capture-DR” state. It is inserted between TDI and TDO when the IDCODE instruction has been loaded into the Instruction Register and the TAP Controller is in the “Shift-DR” state.

The ID Register is 32 bits wide, and contains the following information:

Device	Revision Number (31:28)	Part Number (27:12)	Sony ID (11:1)	Start Bit (0)
2Mb x 18	xxxx	0000 0000 0111 0100	0000 1110 001	1

Bit 0 is the LSB and Bit 31 is the MSB. When the ID Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

Boundary Scan Registers (DR - 51 Bits)

The Boundary Scan Register is equal in length to the number of active signal connections to the SRAM (excluding the TAP pins) plus a number of place holder locations reserved for functional and/or density upgrades. It is loaded with the individual logic states of all signals composing the SRAM’s I/O ring when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the “Capture-DR” state. It is inserted between TDI and TDO when the SAMPLE or SAMPLE-Z instruction has been loaded into the Instruction Register and the TAP Controller is in the “Shift-DR” state.

The Boundary Scan Register contains the following bits:

2Mb x 18	
DQ	18
SA	21
K, $\bar{K}$	2
$\bar{SS}$, $\bar{SW}$, $\bar{SBW}_x$	4
$\bar{G}$, ZZ	2
ZQ, M1, M2	3
Place Holder	1

Note: K and $\bar{K}$ are connected to a differential input receiver that generates a single-ended input clock signal to the device. Therefore, in order to capture deterministic values for these signals in the Boundary Scan Register, they must be at opposite logic levels when sampled.

Note: When an external resistor RQ is connected between the ZQ pin and V_{SS} , the value of the ZQ signal captured in the Boundary Scan Register is non-deterministic.

Note: Place Holders are required for some NC pins to allow for future density and/or functional upgrades. They are connected to V_{SS} internally, regardless of pin connection externally.

Boundary Scan Register Bit Order Assignments

The tables below depict the order in which the bits are arranged in the Boundary Scan Register. Bit 1 is the LSB and bit 51 is the MSB. When the Boundary Scan Register is selected, TDI serially shifts data into the MSB, and the LSB serially shifts data out through TDO.

2Mb x 18					
Bit	Signal	Pad	Bit	Signal	Pad
1	M2	5R	36	$\overline{\text{SBWb}}$	3G
2	SA	6T	37	ZQ	4D
3	SA	4P	38	$\overline{\text{SS}}$	4E
4	SA	6R	39	SA	4B
5	SA	5T	40	NC ⁽¹⁾	4H
6	ZZ	7T	41	$\overline{\text{SW}}$	4M
7	DQa	7P	42	DQb	2K
8	DQa	6N	43	DQb	1L
9	DQa	6L	44	DQb	2M
10	DQa	7K	45	DQb	1N
11	$\overline{\text{SBWa}}$	5L	46	DQb	2P
12	$\overline{\text{K}}$	4L	47	SA	3T
13	K	4K	48	SA	2R
14	$\overline{\text{G}}$	4F	49	SA	4N
15	DQa	6H	50	SA	2T
16	DQa	7G	51	M1	3R
17	DQa	6F			
18	DQa	7E			
19	DQa	6D			
20	SA	6A			
21	SA	6C			
22	SA	5C			
23	SA	5A			
24	SA	6B			
25	SA	5B			
26	SA	3B			
27	SA	2B			
28	SA	3A			
29	SA	3C			
30	SA	2C			
31	SA	2A			
32	DQb	1D			
33	DQb	2E			
34	DQb	2G			
35	DQb	1H			

Note 1: NC pin at pad location 4H is connected to V_{SS} internally, regardless of pin connection externally.

•Ordering Information

Part Number	V _{DD}	I/O Type	Size	Speed (Cycle Time / Access Time)
CXK77K18R320GB-3	1.8V	HSTL	2Mb x 18	3.0ns / 1.6ns
CXK77K18R320GB-33	1.8V	HSTL	2Mb x 18	3.3ns / 1.6ns
CXK77K18R320GB-4	1.8V	HSTL	2Mb x 18	4.0ns / 2.0ns

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Technical drawing of a rectangular plate with three views: top, side, and front.

Top View: Dimensions 14.0 x 22.0. Central hole diameter 13.0. Four corner holes, each with diameter 4C17. Surface finish symbols: 3C10, 4C17, C15, and X4 (0.20).

Side View: Thickness 2.1 ± 0.3. Central hole diameter 0.6 ± 0.1. Surface finish symbol: // 0.35 S.

Front View: Grid of 48 holes (8 rows by 6 columns). Dimensions 20.32 x 1.27. Hole diameters: 0.84, 3.19, 7.62, 1.27. Surface finish symbol: // 0.35 S.

Hole Diameter Table:

Row	Column	Hole Diameter	Surface Finish	Material	Notes
1	1	φ0.75 ± 0.15	φ0.4	S	A
1	2	φ0.75 ± 0.15	φ0.4	S	A
1	3	φ0.75 ± 0.15	φ0.4	S	A
1	4	φ0.75 ± 0.15	φ0.4	S	A
1	5	φ0.75 ± 0.15	φ0.4	S	A
1	6	φ0.75 ± 0.15	φ0.4	S	A
1	7	φ0.75 ± 0.15	φ0.4	S	A
2	1	φ0.75 ± 0.15	φ0.4	S	A
2	2	φ0.75 ± 0.15	φ0.4	S	A
2	3	φ0.75 ± 0.15	φ0.4	S	A
2	4	φ0.75 ± 0.15	φ0.4	S	A
2	5	φ0.75 ± 0.15	φ0.4	S	A
2	6	φ0.75 ± 0.15	φ0.4	S	A
2	7	φ0.75 ± 0.15	φ0.4	S	A
3	1	φ0.75 ± 0.15	φ0.4	S	A
3	2	φ0.75 ± 0.15	φ0.4	S	A
3	3	φ0.75 ± 0.15	φ0.4	S	A
3	4	φ0.75 ± 0.15	φ0.4	S	A
3	5	φ0.75 ± 0.15	φ0.4	S	A
3	6	φ0.75 ± 0.15	φ0.4	S	A
3	7	φ0.75 ± 0.15	φ0.4	S	A
4	1	φ0.75 ± 0.15	φ0.4	S	A
4	2	φ0.75 ± 0.15	φ0.4	S	A
4	3	φ0.75 ± 0.15	φ0.4	S	A
4	4	φ0.75 ± 0.15	φ0.4	S	A
4	5	φ0.75 ± 0.15	φ0.4	S	A
4	6	φ0.75 ± 0.15	φ0.4	S	A
4	7	φ0.75 ± 0.15	φ0.4	S	A
5	1	φ0.75 ± 0.15	φ0.4	S	A
5	2	φ0.75 ± 0.15	φ0.4	S	A
5	3	φ0.75 ± 0.15	φ0.4	S	A
5	4	φ0.75 ± 0.15	φ0.4	S	A
5	5	φ0.75 ± 0.15	φ0.4	S	A
5	6	φ0.75 ± 0.15	φ0.4	S	A
5	7	φ0.75 ± 0.15	φ0.4	S	A
6	1	φ0.75 ± 0.15	φ0.4	S	A
6	2	φ0.75 ± 0.15	φ0.4	S	A
6	3	φ0.75 ± 0.15	φ0.4	S	A
6	4	φ0.75 ± 0.15	φ0.4	S	A
6	5	φ0.75 ± 0.15	φ0.4	S	A
6	6	φ0.75 ± 0.15	φ0.4	S	A
6	7	φ0.75 ± 0.15	φ0.4	S	A
7	1	φ0.75 ± 0.15	φ0.4	S	A
7	2	φ0.75 ± 0.15	φ0.4	S	A
7	3	φ0.75 ± 0.15	φ0.4	S	A
7	4	φ0.75 ± 0.15	φ0.4	S	A
7	5	φ0.75 ± 0.15	φ0.4	S	A
7	6	φ0.75 ± 0.15	φ0.4	S	A
7	7	φ0.75 ± 0.15	φ0.4	S	A
8	1	φ0.75 ± 0.15	φ0.4	S	A
8	2	φ0.75 ± 0.15	φ0.4	S	A
8	3	φ0.75 ± 0.15	φ0.4	S	A
8	4	φ0.75 ± 0.15	φ0.4	S	A
8	5	φ0.75 ± 0.15	φ0.4	S	A
8	6	φ0.75 ± 0.15	φ0.4	S	A
8	7	φ0.75 ± 0.15	φ0.4	S	A

PACKAGE STRUCTURE

SONY CODE	BGA-119P-021
EIAJ CODE	BGA119-P-1422
JEDEC CODE	_____

PACKAGE MATERIAL	EPOXY RESIN
BORAD TREATMENT	COPPER-CLAD LAMINATE
LEAD MATERIAL	SOLDER
PACKAGE MASS	1.1g

December 8, 2004

•Revision History

Rev. #	Rev. Date	Description of Modification
rev 0.0	11/30/01	Initial Version
rev 0.1	03/22/02	- Modified BGA Package Thermal Characteristics section (p. 6). Θ_{JC} 1.0 °C/W to 3.6 °C/W - Modified DC Recommended Operating Conditions section (p. 7). V_{DDQ} (max) V_{DD} to 1.6V V_{REF}, V_{CM} (max) 1.0V to 0.85V Added note 1 regarding 2.5V V_{DD} support. Added note 2 regarding 1.8V V_{DDQ} support. - Modified DC Electrical Characteristics section (p. 8). R_{OUT} RQ/5 ± 10% (GBD) to RQ/5 ± 15% (TESTED) - Modified AC Electrical Characteristics section (p. 9). Removed “-25” bin. Added “-33” bin. -3 t_{KHQV} 1.7ns to 1.5ns t_{KHQZ}, t_{GLQV}, t_{GHQZ} 1.9ns to 1.7ns - Removed 1.8V V_{DDQ} AC Test Conditions. - Modified JTAG DC Recommended Operating Conditions section (p. 14). V_{TIH} (min) 1.2V to 1.4V V_{TIL} (max) 0.6V to 0.8V - Modified JTAG Instruction Register definition (p. 17). Changed codes “011” and “110” from BYPASS to PRIVATE. - Modified 119 Pin BGA Package Dimensions section (p. 21). Changed package from FC-BGA to WB-BGA.
rev 0.2	04/02/02	- Modified DC Recommended Operating Conditions section (p. 7). V_{DDQ} (max) 1.6V to V_{DD} V_{REF}, V_{CM} (min) 0.65V to $V_{DDQ}/2 - 0.1V$ V_{REF}, V_{CM} (max) 0.85V to $V_{DDQ}/2 + 0.1V$ - Added 1.8V V_{DDQ} AC Test Conditions (p. 11).
rev 0.3	06/24/02	- Modified AC Electrical Characteristics section (p. 9). -3, -33 t_{AVKH}, t_{WVKH}, t_{SVKH}, t_{DVKH} 0.5ns to 0.3ns -3, -33 t_{KHAX}, $t_{KH WX}$, t_{KHSX}, t_{KHDX} 0.5ns to 0.3ns - Modified JTAG DC Recommended Operating Conditions section (p. 15). V_{TIH} (min) 1.4V to 1.2V V_{TIL} (max) 0.8V to 0.6V - Modified JTAG AC Electrical Characteristics section (p. 16). TCK Cycle Time 100ns to 50ns TCK High / Low Pulse Widths 40ns to 20ns TMS/TDI Input Setup & Hold Times 10ns to 5ns TDO Output Valid Time 20ns to 10ns Added Capture Setup & Hold Times 5ns
rev 0.4	02/05/03	- Removed all x36 information (created separate x36 data sheet). - Modified DC Electrical Characteristics section (p. 7). I_{MLI}, I_{LO} (min/max) ± 10uA to ± 5uA Added preliminary I_{DD}, I_{DD2}, and I_{SB} specifications. - Modified AC Electrical Characteristics section (p. 8). -4 t_{AVKH}, t_{WVKH}, t_{SVKH}, t_{DVKH} 0.5ns to 0.3ns -3, -33 t_{KHAX}, $t_{KH WX}$, t_{KHSX}, t_{KHDX} 0.3ns to 0.5ns t_{KHQV} 1.7ns to 1.6ns t_{KHQZ}, t_{GLQV}, t_{GHQZ} 1.9ns to 1.8ns

Rev. #	Rev. Date	Description of Modification
rev 0.5	06/09/03	1. Modified DC Electrical Characteristics section (p. 7). Removed I_{DD2} Power Supply Deselect Operating Current. 2. Modified JTAG ID Register definition (p. 18). Changed Part Number code from T.B.D. to 0000 0000 0111 0100.
rev 0.6	07/08/03	1. Modified AC Electrical Characteristics section (p. 8). -3 t_{GLQV} , t_{GHQZ} 1.7ns to 2.5ns -33 t_{GLQV} , t_{GHQZ} 1.8ns to 2.5ns -4 t_{GLQV} , t_{GHQZ} 2.2ns to 2.5ns
rev 0.7	03/31/04	1. Modified I/O Capacitance section (p. 5). C_{IN} 3.5pF to 4.0pF C_{KIN} 3.5pF to 4.5pF C_{OUT} 4.5pF to 5.0pF 2. Modified AC Electrical Characteristics section (p. 8). -3 t_{KHQV} 1.5ns to 1.6ns t_{KHQZ} 1.7ns to 1.8ns 3. Added note to Package Dimensions section regarding lead content in solder balls (p. 21).
rev 0.8	12/08/04	3. Modified AC Electrical Characteristics section (p. 8). Added Note 1.