

## Features

- Fast read access time – 90ns
- Dual voltage range operation
  - Low voltage power supply range, 3.0V to 3.6V, or
  - Standard power supply range, 5V  $\pm$  10%
- Compatible with JEDEC standard Atmel® AT27C256R
- Low-power CMOS operation
  - 20 $\mu$ A max standby (less than 1 $\mu$ A, typical) for  $V_{CC}$  = 3.6V
  - 29mW max active at 5MHz for  $V_{CC}$  = 3.6V
- JEDEC standard package
  - 32-lead PLCC
- High-reliability CMOS technology
  - 2,000V ESD protection
  - 200mA latchup immunity
- Rapid programming algorithm – 100 $\mu$ s/byte (typical)
- CMOS- and TTL-compatible inputs and outputs
  - JEDEC standard for LVTTTL
- Integrated product identification code
- Industrial temperature range
- Green (Pb/halide-free) packaging option

## 1. Description

The Atmel AT27LV256A is a high-performance, low-power, low-voltage, 262,144-bit, one-time programmable, read-only memory (OTP EPROM) organized as 32K by 8 bits. It requires only one supply in the range of 3.0V to 3.6V in normal read mode operation, making it ideal for fast, portable systems using battery power.

The Atmel innovative design techniques provide fast speeds that rival 5V parts, while keeping the low power consumption of a 3.3V supply. At  $V_{CC}$  = 3.0V, any byte can be accessed in less than 90ns. With a typical power dissipation of only 18mW at 5MHz and  $V_{CC}$  = 3.3V, the AT27LV256A consumes less than one-fifth the power of a standard, 5V EPROM. Standby mode supply current is typically less than 1 $\mu$ A at 3.3V.

The AT27LV256A is available in an industry-standard, JEDEC-approved, one-time programmable (OTP) PLCC package. All devices feature two-line control ( $\overline{CE}$ ,  $\overline{OE}$ ) to give designers the flexibility to prevent bus contention.

The AT27LV256A operating with  $V_{CC}$  at 3.0V produces TTL-level outputs that are compatible with standard TTL logic devices operating at  $V_{CC}$  = 5.0V. The device is also capable of standard, 5V operation, making it ideally suited for dual supply range systems or card products that are pluggable in both 3V and 5V hosts.

The AT27LV256A has additional features to ensure high quality and efficient production use. The rapid programming algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100 $\mu$ s/byte. The integrated product identification code electronically identifies the device and manufacturer. This feature is used by industry standard programming equipment to select the proper programming algorithms and voltages. The AT27LV256A programs in exactly the same way as a standard, 5V Atmel AT27C256R, and uses the same programming equipment.



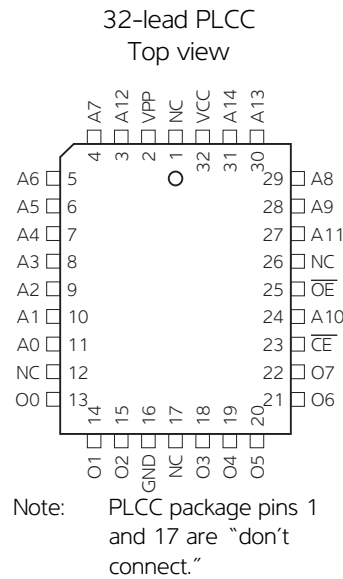
256K (32K x 8)  
Low Voltage,  
One-time  
Programmable,  
Read-only Memory

Atmel AT27LV256A



## 2. Pin configurations

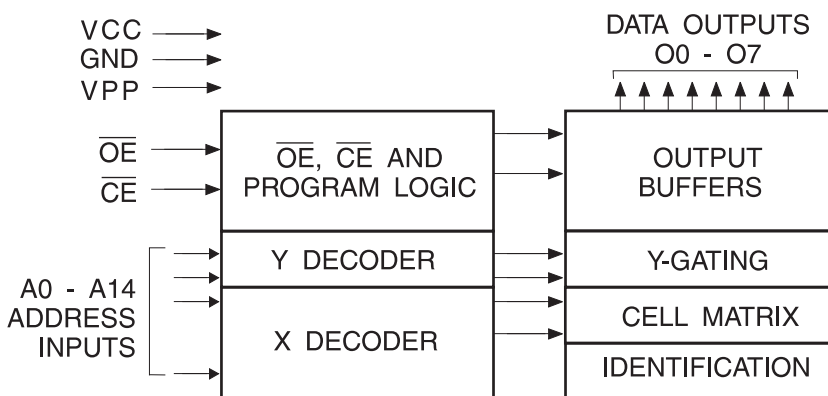
| Pin name        | Function      |
|-----------------|---------------|
| A0 - A14        | Addresses     |
| O0 - O7         | Outputs       |
| $\overline{CE}$ | Chip Enable   |
| $\overline{OE}$ | Output Enable |
| NC              | No Connect    |



## 3. System considerations

Switching between active and standby conditions via the chip enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device nonconformance. At a minimum, a 0.1 $\mu$ F, high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the  $V_{CC}$  and ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7 $\mu$ F bulk electrolytic capacitor should be utilized, again connected between the  $V_{CC}$  and ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

Figure 3-1. Block diagram



#### 4. Absolute maximum ratings\*

|                                                                |                                |
|----------------------------------------------------------------|--------------------------------|
| Temperature under bias .....                                   | -40°C to +85°C                 |
| Storage temperature .....                                      | -65°C to +125°C                |
| Voltage on any pin with<br>respect to ground .....             | -2.0V to +7.0V <sup>(1)</sup>  |
| Voltage on A9 with<br>respect to ground .....                  | -2.0V to +14.0V <sup>(1)</sup> |
| V <sub>pp</sub> supply voltage with<br>respect to ground ..... | -2.0V to +14.0V <sup>(1)</sup> |

\*NOTICE: Stresses beyond those listed under “Absolute maximum ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20ns. Maximum output pin voltage is V<sub>CC</sub> + 0.75V DC, which may be exceeded if certain precautions are observed (consult application notes), and which may overshoot to +7.0V for pulses of less than 20ns.

#### 5. DC and AC characteristics

Table 5-1. Operating modes

| Mode/Pin                                 | $\overline{CE}$  | $\overline{OE}$  | Ai                                                                                                          | V <sub>pp</sub> | V <sub>CC</sub> | Outputs             |
|------------------------------------------|------------------|------------------|-------------------------------------------------------------------------------------------------------------|-----------------|-----------------|---------------------|
| Read <sup>(2)</sup>                      | V <sub>IL</sub>  | V <sub>IL</sub>  | Ai                                                                                                          | V <sub>CC</sub> | V <sub>CC</sub> | D <sub>OUT</sub>    |
| Output disable <sup>(2)</sup>            | V <sub>IL</sub>  | V <sub>IH</sub>  | X <sup>(1)</sup>                                                                                            | V <sub>CC</sub> | V <sub>CC</sub> | High Z              |
| Standby <sup>(2)</sup>                   | V <sub>IH</sub>  | X <sup>(1)</sup> | X <sup>(1)</sup>                                                                                            | V <sub>CC</sub> | V <sub>CC</sub> | High Z              |
| Rapid program <sup>(3)</sup>             | V <sub>IL</sub>  | V <sub>IH</sub>  | Ai                                                                                                          | V <sub>pp</sub> | V <sub>CC</sub> | D <sub>IN</sub>     |
| PGM verify <sup>(3)</sup>                | X <sup>(1)</sup> | V <sub>IL</sub>  | Ai                                                                                                          | V <sub>pp</sub> | V <sub>CC</sub> | D <sub>OUT</sub>    |
| Optional PGM verify <sup>(3)</sup>       | V <sub>IL</sub>  | V <sub>IL</sub>  | Ai                                                                                                          | V <sub>CC</sub> | V <sub>CC</sub> | D <sub>OUT</sub>    |
| PGM inhibit <sup>(3)</sup>               | V <sub>IH</sub>  | V <sub>IH</sub>  | X <sup>(1)</sup>                                                                                            | V <sub>pp</sub> | V <sub>CC</sub> | High Z              |
| Product identification <sup>(3)(5)</sup> | V <sub>IL</sub>  | V <sub>IL</sub>  | A9 = V <sub>H</sub> <sup>(4)</sup><br>A0 = V <sub>IH</sub> or V <sub>IL</sub><br>A1 - A14 = V <sub>IL</sub> | V <sub>CC</sub> | V <sub>CC</sub> | Identification code |

- Notes: 1. X can be V<sub>IL</sub> or V<sub>IH</sub>.  
 2. Read, output disable, and standby modes require  $3.0V \leq V_{CC} \leq 3.6V$  or  $4.5V \leq V_{CC} \leq 5.5V$ .  
 3. Refer to programming characteristics. Programming modes require V<sub>CC</sub> = 6.5V.  
 4. V<sub>H</sub> = 12.0 ± 0.5V.  
 5. Two identifier bytes may be selected. All Ai inputs are held low (V<sub>IL</sub>) except A9, which is set to V<sub>H</sub>, and A0, which is toggled low (V<sub>IL</sub>) to select the manufacturer's identification byte and high (V<sub>IH</sub>) to select the device code byte.

Table 5-2. DC and AC operating conditions for read operation

|                                         | Atmel AT27LV256A |
|-----------------------------------------|------------------|
|                                         | -90              |
| Industrial operating temperature (case) | -40°C - 85°C     |
| V <sub>CC</sub> power supply            | 3.0V to 3.6V     |
|                                         | 5V ± 10%         |

Table 5-3. DC and operating characteristics for read operation

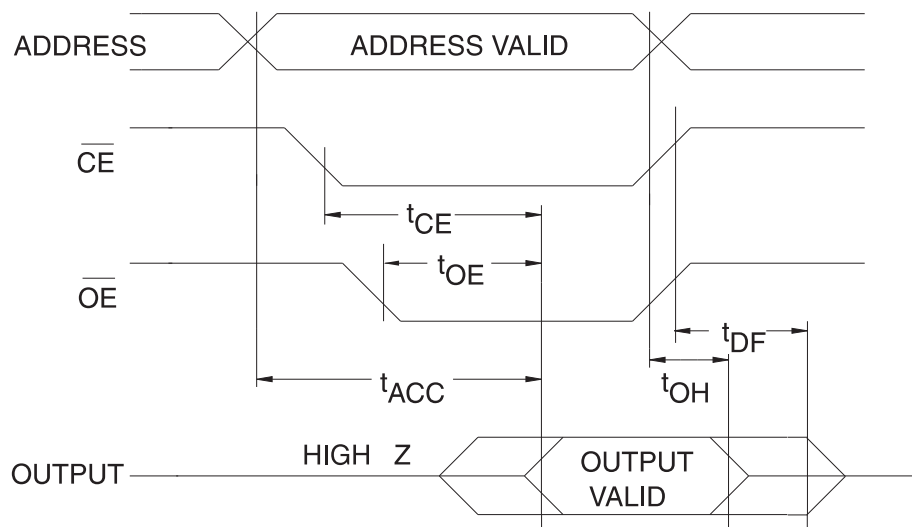
| Symbol                                                 | Parameter                           | Condition                                                 | Min  | Max            | Units   |
|--------------------------------------------------------|-------------------------------------|-----------------------------------------------------------|------|----------------|---------|
| <b><math>V_{CC} = 3.0V</math> to <math>3.6V</math></b> |                                     |                                                           |      |                |         |
| $I_{LI}$                                               | Input load current                  | $V_{IN} = 0V$ to $V_{CC}$                                 |      | $\pm 1$        | $\mu A$ |
| $I_{LO}$                                               | Output leakage current              | $V_{OUT} = 0V$ to $V_{CC}$                                |      | $\pm 5$        | $\mu A$ |
| $I_{PP1}^{(2)}$                                        | $V_{PP}^{(1)}$ read/standby current | $V_{PP} = V_{CC}$                                         |      | 10             | $\mu A$ |
| $I_{SB}$                                               | $V_{CC}^{(1)}$ standby current      | $I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$       |      | 20             | $\mu A$ |
|                                                        |                                     | $I_{SB2}$ (TTL), $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$ |      | 100            | $\mu A$ |
| $I_{CC}$                                               | $V_{CC}$ active current             | $f = 5MHz$ , $I_{OUT} = 0mA$ , $\overline{CE} = V_{IL}$   |      | 8              | mA      |
| $V_{IL}$                                               | Input low voltage                   |                                                           | -0.6 | 0.8            | V       |
| $V_{IH}$                                               | Input high voltage                  |                                                           | 2.0  | $V_{CC} + 0.5$ | V       |
| $V_{OL}$                                               | Output low voltage                  | $I_{OL} = 2.0mA$                                          |      | 0.4            | V       |
| $V_{OH}$                                               | Output high voltage                 | $I_{OH} = -2.0mA$                                         | 2.4  |                | V       |
| <b><math>V_{CC} = 4.5V</math> to <math>5.5V</math></b> |                                     |                                                           |      |                |         |
| $I_{LI}$                                               | Input load current                  | $V_{IN} = 0V$ to $V_{CC}$                                 |      | $\pm 1$        | $\mu A$ |
| $I_{LO}$                                               | Output leakage current              | $V_{OUT} = 0V$ to $V_{CC}$                                |      | $\pm 5$        | $\mu A$ |
| $I_{PP1}^{(2)}$                                        | $V_{PP}^{(1)}$ read/standby current | $V_{PP} = V_{CC}$                                         |      | 10             | $\mu A$ |
| $I_{SB}$                                               | $V_{CC}^{(1)}$ standby current      | $I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$       |      | 100            | $\mu A$ |
|                                                        |                                     | $I_{SB2}$ (TTL), $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$ |      | 1              | mA      |
| $I_{CC}$                                               | $V_{CC}$ active current             | $f = 5MHz$ , $I_{OUT} = 0mA$ , $\overline{CE} = V_{IL}$   |      | 20             | mA      |
| $V_{IL}$                                               | Input low voltage                   |                                                           | -0.6 | 0.8            | V       |
| $V_{IH}$                                               | Input high voltage                  |                                                           | 2.0  | $V_{CC} + 0.5$ | V       |
| $V_{OL}$                                               | Output low voltage                  | $I_{OL} = 2.1mA$                                          |      | 0.4            | V       |
| $V_{OH}$                                               | Output high voltage                 | $I_{OH} = -400\mu A$                                      | 2.4  |                | V       |

- Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$ , and removed simultaneously with or after  $V_{PP}$ .  
2.  $V_{PP}$  may be connected directly to  $V_{CC}$ , except during programming. The supply current would then be the sum of  $I_{CC}$  and  $I_{PP}$ .

Table 5-4. AC characteristics for read operation

$V_{CC} = 3.0V$  to  $3.6V$  and  $4.5V$  to  $5.5V$

| Symbol                            | Parameter                                                                               | Condition                                | Atmel AT27LV256A |     | Units |
|-----------------------------------|-----------------------------------------------------------------------------------------|------------------------------------------|------------------|-----|-------|
|                                   |                                                                                         |                                          | -90              |     |       |
|                                   |                                                                                         |                                          | Min              | Max |       |
| t <sub>ACC</sub> <sup>(3)</sup>   | Address to output delay                                                                 | $\overline{CE} = \overline{OE} = V_{IL}$ |                  | 90  | ns    |
| t <sub>CE</sub> <sup>(2)</sup>    | $\overline{CE}$ to output delay                                                         | $\overline{OE} = V_{IL}$                 |                  | 90  | ns    |
| t <sub>OE</sub> <sup>(2)(3)</sup> | $\overline{OE}$ to output delay                                                         | $\overline{CE} = V_{IL}$                 |                  | 50  | ns    |
| t <sub>DF</sub> <sup>(4)(5)</sup> | $\overline{OE}$ or $\overline{CE}$ high to output float, whichever occurred first       |                                          |                  | 40  | ns    |
| t <sub>OH</sub>                   | Output hold from address, $\overline{CE}$ or $\overline{OE}$ , whichever occurred first |                                          | 0                |     | ns    |

Figure 5-1. AC waveforms for read operation<sup>(1)</sup>

- Notes:
1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.
  2.  $\overline{OE}$  may be delayed up to  $t_{CE} - t_{OE}$  after the falling edge of  $\overline{CE}$  without impact on  $t_{CE}$ .
  3.  $\overline{OE}$  may be delayed up to  $t_{ACC} - t_{OE}$  after the address is valid without impact on  $t_{ACC}$ .
  4. This parameter is only sampled, and is not 100% tested.
  5. Output float is defined as the point when data is no longer driven.

Figure 5-2. Input test waveforms and measurement levels

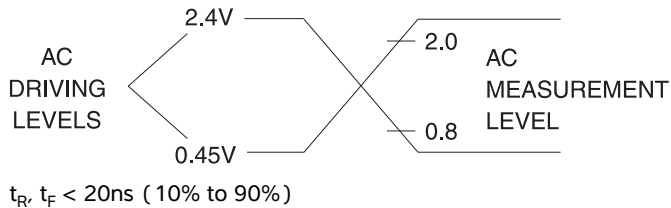
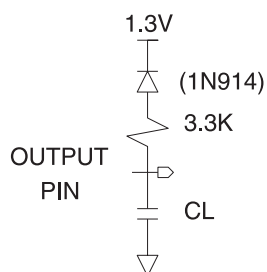


Figure 5-3. Output test load



Note: CL = 100pF including jig capacitance.

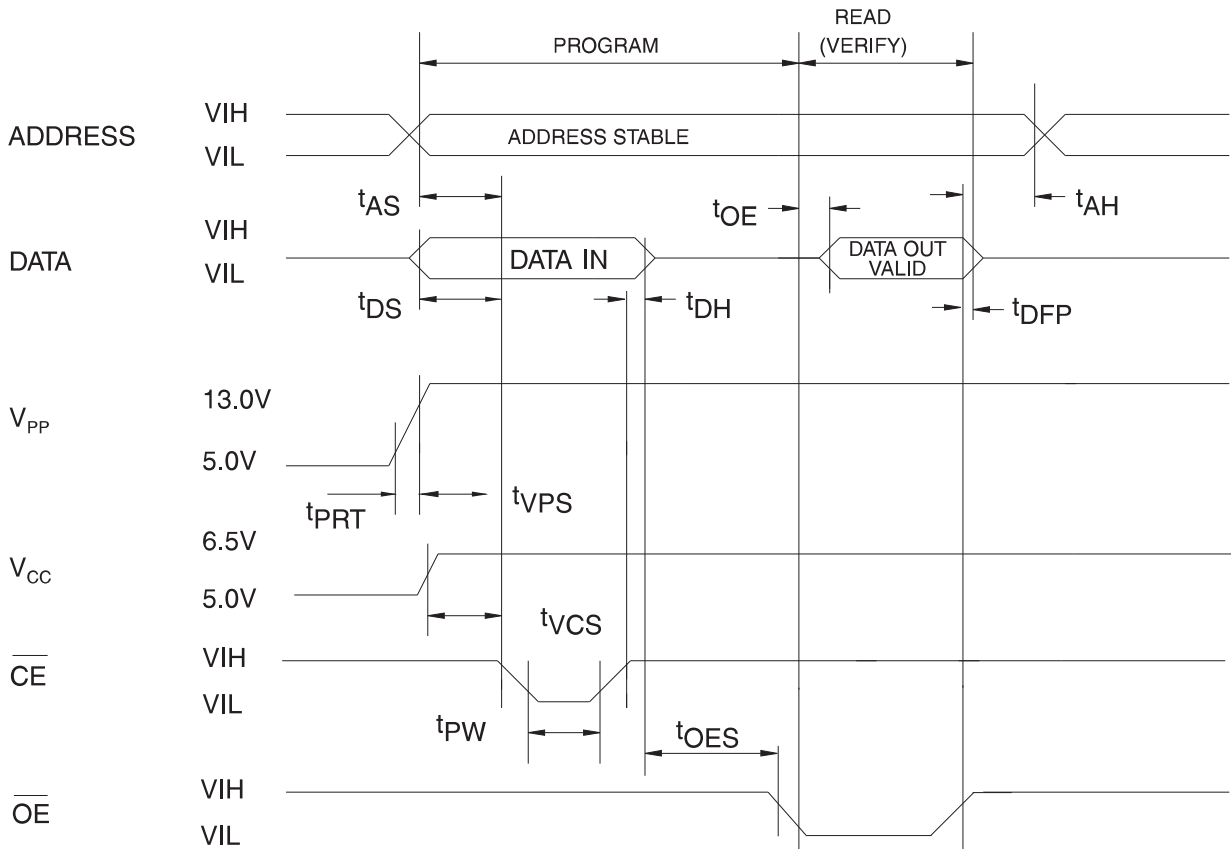
Table 5-5. Pin capacitance

$f = 1\text{MHz}$ ,  $T = 25^\circ\text{C}$ <sup>(1)</sup>

| Symbol           | Typ | Max | Units | Conditions                   |
|------------------|-----|-----|-------|------------------------------|
| $C_{\text{IN}}$  | 4   | 8   | pF    | $V_{\text{IN}} = 0\text{V}$  |
| $C_{\text{OUT}}$ | 8   | 12  | pF    | $V_{\text{OUT}} = 0\text{V}$ |

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.

Figure 5-4. Programming waveforms<sup>(1)</sup>



- Notes:
1. The input timing reference is 0.8V for  $V_{\text{IL}}$  and 2.0V for  $V_{\text{IH}}$ .
  2.  $t_{\text{OE}}$  and  $t_{\text{DFP}}$  are characteristics of the device, but must be accommodated by the programmer.
  3. When programming the Atmel AT27LV256A, a 0.1 $\mu\text{F}$  capacitor is required across  $V_{\text{PP}}$  and ground to suppress spurious voltage transients.

Table 5-6. DC programming characteristics

 $T_A = 25 \pm 5^\circ\text{C}$ ,  $V_{CC} = 6.5 \pm 0.25\text{V}$ ,  $V_{PP} = 13.0 \pm 0.25\text{V}$ 

| Symbol    | Parameter                                    | Test conditions            | Limits |                | Units         |
|-----------|----------------------------------------------|----------------------------|--------|----------------|---------------|
|           |                                              |                            | Min    | Max            |               |
| $I_{LI}$  | Input load current                           | $V_{IN} = V_{IL}, V_{IH}$  |        | $\pm 10$       | $\mu\text{A}$ |
| $V_{IL}$  | Input low level                              |                            | -0.6   | 0.8            | V             |
| $V_{IH}$  | Input high level                             |                            | 2.0    | $V_{CC} + 0.5$ | V             |
| $V_{OL}$  | Output low voltage                           | $I_{OL} = 2.1\text{mA}$    |        | 0.4            | V             |
| $V_{OH}$  | Output high voltage                          | $I_{OH} = -400\mu\text{A}$ | 2.4    |                | V             |
| $I_{CC2}$ | $V_{CC}$ supply current (program and verify) |                            |        | 25             | mA            |
| $I_{PP2}$ | $V_{PP}$ current                             | $\overline{CE} = V_{IL}$   |        | 25             | mA            |
| $V_{ID}$  | A9 product identification voltage            |                            | 11.5   | 12.5           | V             |

Table 5-7. AC programming characteristics

 $T_A = 25 \pm 5^\circ\text{C}$ ,  $V_{CC} = 6.5 \pm 0.25\text{V}$ ,  $V_{PP} = 13.0 \pm 0.25\text{V}$ 

| Symbol    | Parameter                                                 | Test conditions <sup>(1)</sup>                 | Limits |     | Units         |
|-----------|-----------------------------------------------------------|------------------------------------------------|--------|-----|---------------|
|           |                                                           |                                                | Min    | Max |               |
| $t_{AS}$  | Address setup time                                        | Input rise and fall times<br>(10% to 90%) 20ns | 2      |     | $\mu\text{s}$ |
| $t_{OES}$ | $\overline{OE}$ setup time                                |                                                | 2      |     | $\mu\text{s}$ |
| $t_{DS}$  | Data setup time                                           |                                                | 2      |     | $\mu\text{s}$ |
| $t_{AH}$  | Address hold time                                         | Input pulse levels<br>0.45V to 2.4V            | 0      |     | $\mu\text{s}$ |
| $t_{DH}$  | Data hold time                                            |                                                | 2      |     | $\mu\text{s}$ |
| $t_{DFP}$ | $\overline{OE}$ high to output float delay <sup>(2)</sup> |                                                | 0      | 130 | ns            |
| $t_{VPS}$ | $V_{PP}$ setup time                                       | Input timing reference level<br>0.8V to 2.0V   | 2      |     | $\mu\text{s}$ |
| $t_{VCS}$ | $V_{CC}$ setup time                                       |                                                | 2      |     | $\mu\text{s}$ |
| $t_{PW}$  | $\overline{CE}$ program pulse width <sup>(3)</sup>        | Output timing reference level<br>0.8V to 2.0V  | 95     | 105 | $\mu\text{s}$ |
| $t_{OE}$  | Data valid from $\overline{OE}$ <sup>(2)</sup>            |                                                |        | 150 | ns            |
| $t_{PRT}$ | $V_{PP}$ pulse rise time during programming               |                                                | 50     |     | ns            |

- Notes:
- $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously with or after  $V_{PP}$ .
  - This parameter is only sampled, and is not 100% tested. Output float is defined as the point where data is no longer driven. See timing diagram.
  - Program pulse width tolerance is  $100 \mu\text{sec} \pm 5\%$ .

Table 5-8. The Atmel AT27LV256A integrated product identification code<sup>(1)</sup>

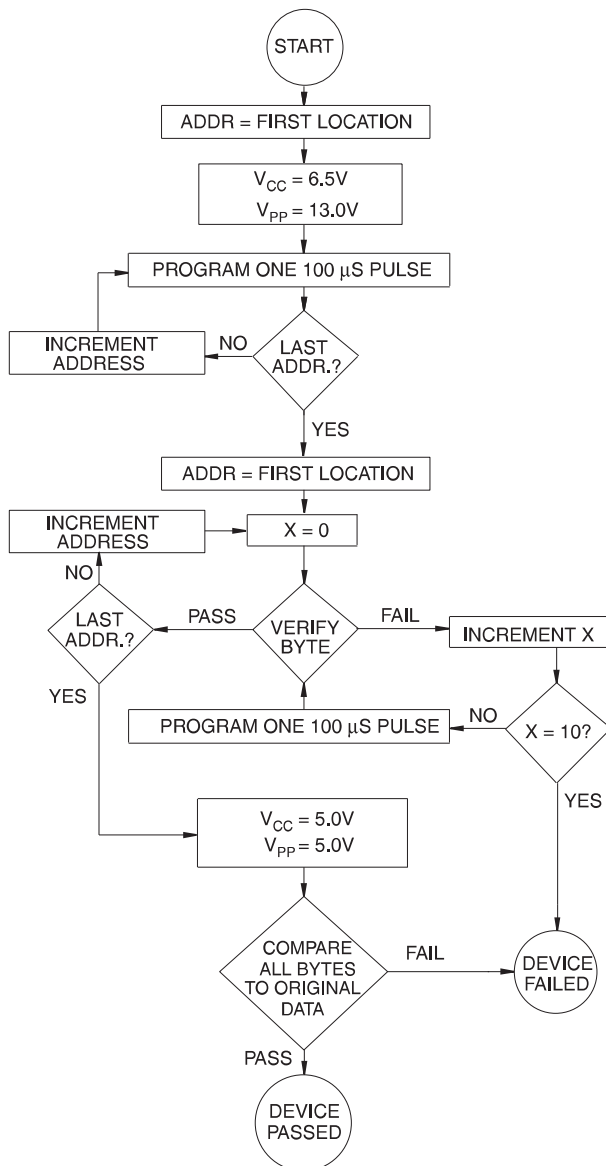
| Codes        | Pins |    |    |    |    |    |    |    |    | Hex data |
|--------------|------|----|----|----|----|----|----|----|----|----------|
|              | A0   | O7 | O6 | O5 | O4 | O3 | O2 | O1 | O0 |          |
| Manufacturer | 0    | 0  | 0  | 0  | 1  | 1  | 1  | 1  | 0  | 1E       |
| Device type  | 1    | 1  | 0  | 0  | 0  | 1  | 1  | 0  | 0  | 8C       |

- Note:
- The Atmel AT27LV256A has the same product identification code as the Atmel AT27C256R. Both are programming compatible.

## 6. Rapid programming algorithm

A  $100\mu\text{s}$   $\overline{\text{CE}}$  pulse width is used to program. The address is set to the first location.  $V_{\text{CC}}$  is raised to 6.5V and  $V_{\text{PP}}$  is raised to 13.0V. Each address is first programmed with one  $100\mu\text{s}$   $\overline{\text{CE}}$  pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive  $100\mu\text{s}$  pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked.  $V_{\text{PP}}$  is then lowered to 5.0V and  $V_{\text{CC}}$  to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.

Figure 6-1. Rapid programming algorithm



## 7. Ordering information

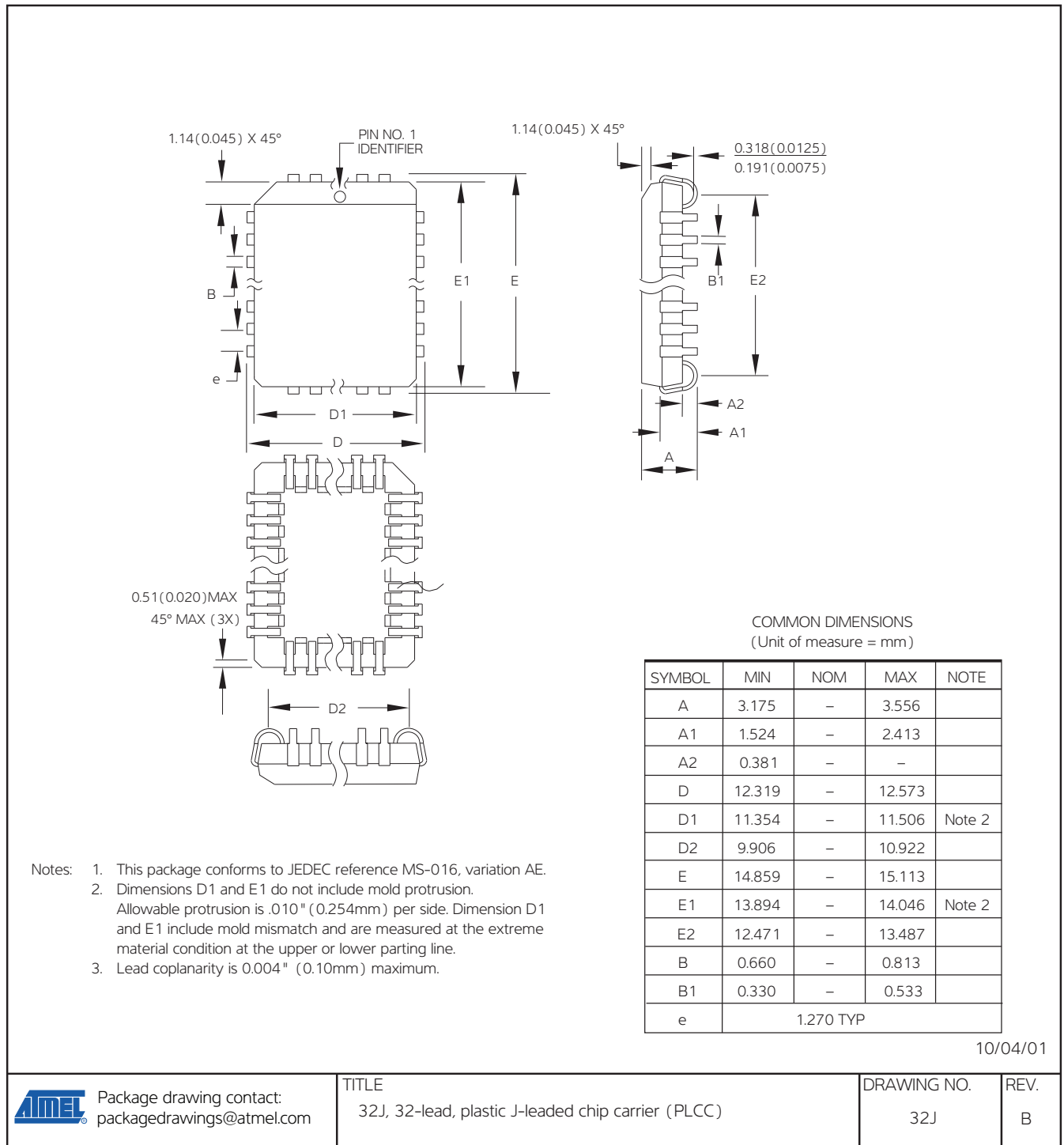
Green package option (Pb/halide-free)

| $t_{ACC}$<br>(ns) | $I_{CC}$ (mA) |         | Atmel ordering code | Package | Lead finish | Operation range               |
|-------------------|---------------|---------|---------------------|---------|-------------|-------------------------------|
|                   | Active        | Standby |                     |         |             |                               |
| 90                | 8             | 0.02    | AT27LV256A-90JU     | 32J     | Matte tin   | Industrial<br>(-40°C to 85°C) |

| Package type |                                                |
|--------------|------------------------------------------------|
| 32J          | 32-lead, plastic, J-leaded chip carrier (PLCC) |

## 8. Packaging information

### 32J – PLCC



## 9. Revision history

| Doc. rev. | Date    | Comments                                                                 |
|-----------|---------|--------------------------------------------------------------------------|
| 0547E     | 04/2011 | Remove SOIC and TSOP packages<br>Add lead finish to ordering information |
| 0547D     | 12/2007 |                                                                          |

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