AXL E PB DI8 DO8 M12 6P

**Axioline E PROFIBUS device, plastic housing,
8 inputs, 8 outputs, 24 V DC,
M12 fast connection technology**



Data sheet
8435_en_03

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1 Description

The Axioline E device is designed for use within a PROFIBUS network.

It is used to acquire and output digital signals.

PROFIBUS features

- Connection to PROFIBUS DP using M12 connectors (B-coded)
- DP/V1 for Class 1 and Class 2 masters
- Data transmission speed of 9.6 kbps up to 12 Mbps (automatic detection)
- Rotary encoding switches for setting the PROFIBUS address
- Supported PROFIBUS addresses 0 to 126
- PROFIBUS features: Sync mode, Freeze mode, I & M functions
- Device description using GSD file

Axioline E features

- Connection of digital sensors and actuators to M12 connectors (A-coded)
- Diagnostic and status indicators
- Short-circuit and overload protection of the sensor supply
- IP65/67 degree of protection

	This data sheet is only valid in association with the associated user manual.
	Make sure you always use the latest documentation. It can be downloaded from the product at phoenixcontact.net/products.

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3 Ordering data

Description	Type	Order No.	Pcs./Pkt.
Axioline E PROFIBUS device in a plastic housing with 8 digital inputs and 8 digital outputs, 24 V DC, M12 fast connection technology	AXL E PB DI8 DO8 M12 6P	2701497	1

Accessories	Type	Order No.	Pcs./Pkt.
An M12 screw plug for the unoccupied M12 sockets of the sensor/actuator cable, boxes and flush-type connectors (Protection and sealing elements)	PROT-M12	1680539	5
Bus system T-plug, PROFIBUS, M12 B-coded male plug to M12 B-coded male plug and M12 B-coded female plug, shielded (Connector/Adapter)	SAC-M12T/2XM12 PB DP	1507780	1
Terminating resistor PROFIBUS M12 (Connector/Adapter)	SAC-5P-M12MS PB TR	1507803	5
Snap-in markers, Sheet, white, unlabeled, can be labeled with: THERMOMARK CARD, BLUEMARK CLED, BLUEMARK LED, TOPMARK LASER, Mounting type: snapped into marker carrier, Lettering field: 7 x 10 mm (Marking)	UCT-EM (7X10)	0830765	10

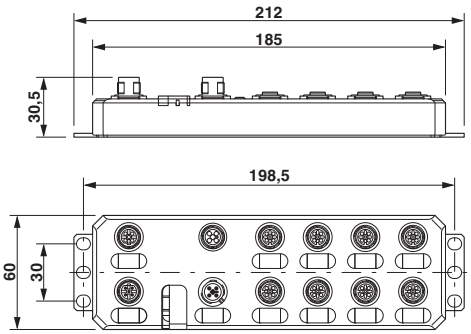
Documentation	Type	Order No.	Pcs./Pkt.
User manual, English, Axioline E: system and installation	UM EN AXL E SYS INST	-	-
Application note, English, Startup of Axioline E PROFIBUS devices on a SIMATIC® S7 controller (for experienced S7 users)	AH EN S7 - AXL E PB PRO	-	-

Additional ordering data

For additional accessories, visit phoenixcontact.net/products.

4 Technical data

Dimensions (nominal sizes in mm)



Width	60 mm
Height	185 mm
Depth	30.5 mm
Note on dimensions	The height is 212 mm including fixing clips.

General data

Housing material	Pocan®
Color	anthracite
Weight	480 g
Ambient temperature (operation)	-25 °C ... 60 °C

CAUTION: Risk of burns
If the device is used at an ambient temperature above 50°C, the contact temperature of metal surfaces may exceed 70°C.

Ambient temperature (storage/transport)	-25 °C ... 85 °C
Permissible humidity (operation)	5 % ... 95 %
Permissible humidity (storage/transport)	5 % ... 95 %
Air pressure (operation)	70 kPa ... 106 kPa (up to 3000 m above sea level)
Air pressure (storage/transport)	70 kPa ... 106 kPa (up to 3000 m above sea level)
Degree of protection	IP65/IP67
Protection class	III, IEC 61140, EN 61140, VDE 0140-1

Connection data

Connection method	M12 connector

Interface PROFIBUS DP

Number	2
Connection method	2x M12 connectors, B-coded
Designation connection point	Copper cable
Number of positions	5
Transmission speed	9,6 kBit/s ... 12 MBit/s (Automatic baud rate detection)
Transmission physics	PROFIBUS-DP-compliant copper cable

PROFIBUS DP

Equipment type	PROFIBUS slave
PROFIBUS protocols	DP V1

Supply: Module electronics and sensors (U_S)

Connection method	M12 connector (T-coded)
Number of positions	4
Supply voltage	24 V DC
Nominal supply voltage range	18 V DC ... 31.2 V DC (including all tolerances, including ripple)
Typical current consumption	165 mA ±15 % (at 24 V DC)
Current consumption	max. 12 A

Supply: Actuators (U_A)

Connection method	M12 connector (T-coded)
Number of positions	4
Supply voltage	24 V DC
Nominal supply voltage range	18 V DC ... 31.2 V DC (including all tolerances, including ripple)
Typical current consumption	30 mA ±15 % (at 24 V DC)
Current consumption	max. 12 A

Digital inputs

Number of inputs	8 (EN 61131-2 types 1 and 3)
Connection method	M12 connector, double occupancy
Connection method	2, 3, 4-wire
Nominal input voltage	24 V DC
Nominal input current	typ. 3 mA
Sensor current per channel	typ. 0.75 mA (from U_S)
Total sensor current	max. 0.6 A (per device)
Input voltage range "0" signal	-30 V DC ... 5 V DC
Input voltage range "1" signal	11 V DC ... 30 V DC
Input filter time	< 1000 µs
Permissible conductor length to the sensor	30 m
Overload protection, short-circuit protection of sensor supply	Yes

Digital outputs

Number of outputs	8
Connection method	M12 connector, double occupancy
Connection method	2, 3-wire
Nominal output voltage	24 V DC (from voltage U_A)
Maximum output current per channel	500 mA
Nominal load, ohmic	12 W (48 Ω; with nominal voltage)
Nominal load, inductive	12 VA (1.2 H; 48 Ω; with nominal voltage)
Signal delay	max. 150 µs (when switched on) max. 200 µs (when switched off)
Switching frequency	max. 5500 per second (with at least 50 mA load current)
Switching frequency	max. 1 per second (with inductive load)
Limitation of the voltage induced on circuit interruption	-28 V ... -17 V
Output voltage when switched off	max. 1 V
Output current when switched off	max. 20 µA
Behavior with overload	Auto restart
Reverse voltage resistance to short pulses	Reverse voltage proof
Overcurrent shut-down	min. 0.7 A
Overload protection, short-circuit protection of outputs	Electronic

Configuration data

ID number	0E5D
Input address area	8 Bit
Output address area	8 Bit

Electrical isolation/isolation of the voltage areas

Test section	Test voltage
24 V supply (communications power and sensor supply, digital inputs)/ bus connection	500 V AC, 50 Hz, 1 min
24 V supply (communications power and sensor supply, digital inputs)/FE	500 V AC, 50 Hz, 1 min
Bus connection / FE	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/ 24 V supply (communications power and sensor supply, digital inputs)	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/bus connection	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/FE	500 V AC, 50 Hz, 1 min

Mechanical tests

Vibration resistance in acc. with EN 60068-2-6/IEC 60068-2-6	5g
Shock in acc. with EN 60068-2-27/IEC 60068-2-27	30g, 11 ms period, half-sine shock pulse
Continuous shock according to EN 60068-2-27/IEC 60068-2-27	10g

Conformance with EMC Directive 2004/108/EC

Noise immunity test in accordance with EN 61000-6-2	
Electrostatic discharge (ESD) EN 61000-4-2/IEC 61000-4-2	Criterion B; 6 kV contact discharge, 8 kV air discharge
Electromagnetic fields EN 61000-4-3/IEC 61000-4-3	Criterion A; Field intensity: 10 V/m
Fast transients (burst) EN 61000-4-4/IEC 61000-4-4	Criterion B, 2 kV
Transient surge voltage (surge) EN 61000-4-5/IEC 61000-4-5	Criterion B; DC supply lines: ±0.5 kV/±0.5 kV (symmetrical/asymmetrical)
Conducted interference EN 61000-4-6/IEC 61000-4-6	Criterion A; Test voltage 10 V
Noise emission test as per EN 61000-6-4	
Radio interference properties EN 55022	Class A

Approvals

For the latest approvals, please visit phoenixcontact.net/products.

5 Internal circuit diagram

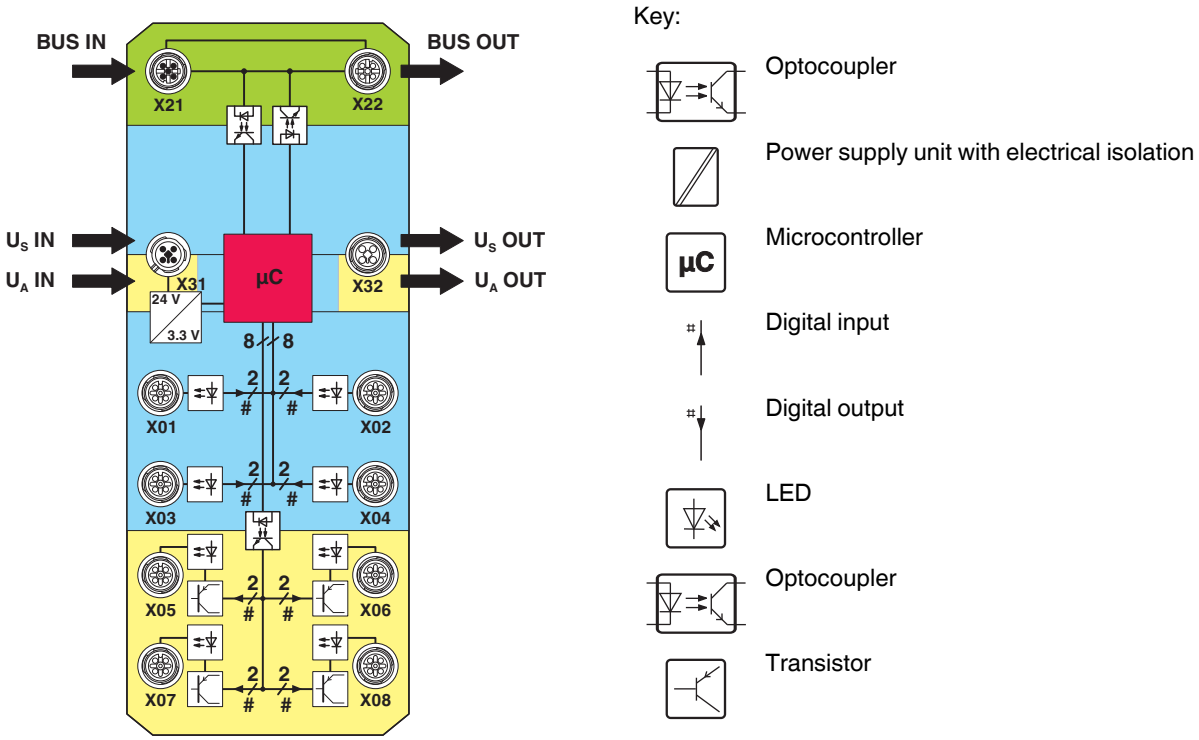


Figure 1 Internal wiring of connections

Key:

Green area:	Network
Blue area:	U_S
Yellow area:	U_A

6 Pin assignment

6.1 PROFIBUS and power supply connection

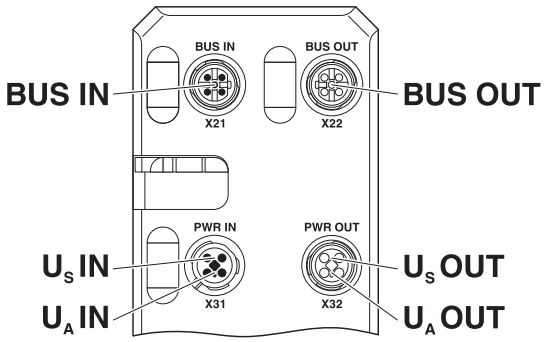


Figure 2 Connections for PROFIBUS and power supply

Designation	Meaning
BUS IN (X21)	PROFIBUS IN
BUS OUT (X22)	PROFIBUS OUT
U_S IN (X31)	Power supply IN (logic and sensors)
U_A IN (X31)	Power supply IN (actuators)
U_S OUT (X32)	Power supply OUT for additional devices
U_A OUT (X32)	Power supply OUT for additional devices

Ground the device by means of the mounting screws.

6.2 PROFIBUS pin assignment

The bus is connected via two B-coded M12 plug-in plugs. The incoming bus (IN) is a plug and the outgoing bus (OUT) is a socket.

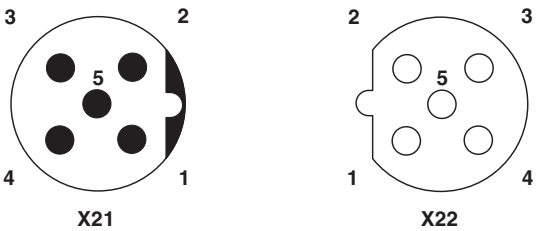


Figure 3 PROFIBUS pin assignment, B-coded

Pin	Signal	Specification	Description
1	VP	V	5 V termination resistor
2	RxD / TxD-N (A)	A, RS-485, PD	Inverted bus cable
3	DGND	V	0 V
4	RxD / TxD-P (B)	B, RS-485, PU	Non-inverted bus cable
5	Not used	-	-

A	=	A line
B	=	B cable
RS-485	=	RS-485 level, bidirectional
V	=	Power supply
PU	=	Pullup
PD	=	Pulldown

The shield is connected to FE in the device.

The thread is used for additional shielding.

6.3 Pin assignment of the power supply U_S/U_A

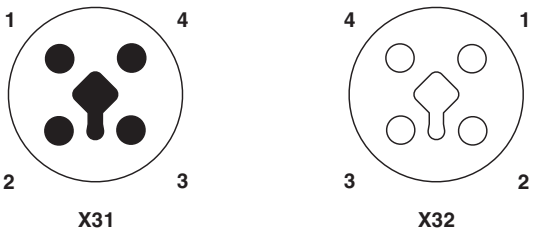


Figure 4 Pin assignment of the power supply, T-coded

Pin	IN	OUT	Conductor colors
1	+24 V DC (U_S)	+24 V DC (U_S)	Brown
2	GND (U_A)	GND (U_A)	White
3	GND (U_S)	GND (U_S)	Blue
4	+24 V DC (U_A)	+24 V DC (U_A)	Black

6.4 Connecting inputs and outputs

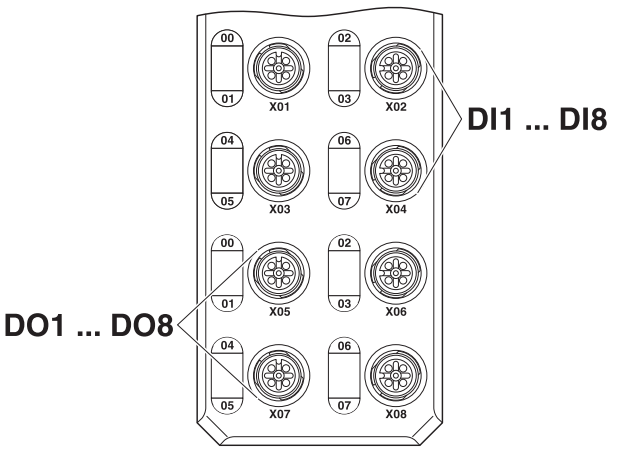


Figure 5 Input and output connections

Designation	Meaning
DI1 ... DI8 (X01 ... X04)	Inputs 1 ... 8
DO1 ... DO8 (X05 ... X08)	Outputs 1 ... 8

6.5 Pin assignment of the inputs and outputs

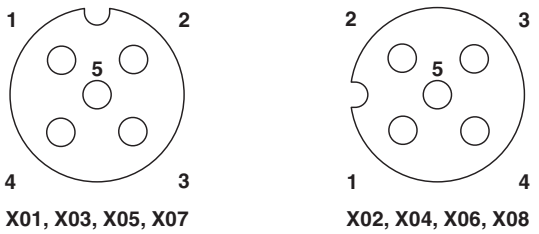


Figure 6 Pin assignment of the inputs and outputs, A-coded

Pin	Input socket	Output socket
1	+24 V DC (U_S)	Not used
2	Input 2, 4, 6, 8	Output 2, 4, 6, 8
3	GND	GND
4	Input 1, 3, 5, 7	Output 1, 3, 5, 7
5	FE	FE

7 Connection example

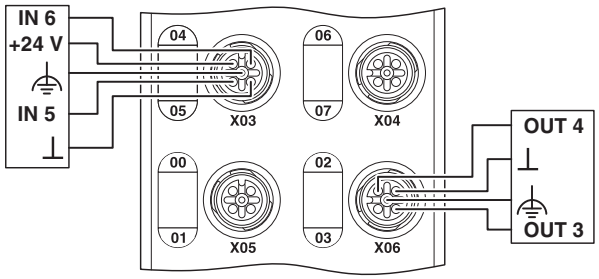


Figure 7 Example of connection of sensors and actuators

8 Connection notes

Note: data corruption or loss

Implement the FE connection using mounting screws, in order to ensure immunity to interference.

NOTE: device damage

To ensure IP65/IP67 protection, cover unused sockets with protective caps.

NOTE: Damage to the electronics

Only supply the sensors with the voltage U_S provided at the terminal points.

NOTE: Damage to the electronics

Observe the correct polarity of the supply voltages U_S and U_A in order to prevent damage to the device.

NOTE: Malfunction

When connecting the sensors and actuators, observe the assignment of the connections to the PROFIBUS input and output data.

Secure the device to a level surface or to a profile. Do not use this device to bridge gaps, in order to prevent forces being transmitted via the device.

Use standard M5 screws with toothed lock washer and self-locking nuts. Observe the maximum torque of the screws.

9 Configuration via rotary encoding switch

Addresses are set using two rotary coding switches. Switch x10 is used to set the position in tens (x10) and switch x1 is used to set the position in units (x1). The address can be set between 1 and 126.

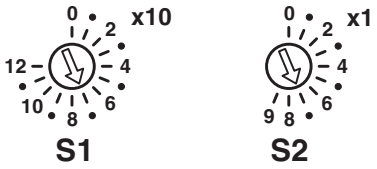


Figure 8 PROFIBUS rotary encoding switch

S1	S2	Code	Function
0	0	00	Reserved
0 ... 12	1 ... 5	01 ... 125	Manual address assignment
12	6	126	Setting the slave address (set slave address command)
12	7	127	Reserved
12	8	128	Reserved
12	9	129	Reserved

A new address value is only applied on device power up.

10 Local status and diagnostic indicators

10.1 Indicators for bus and power supply

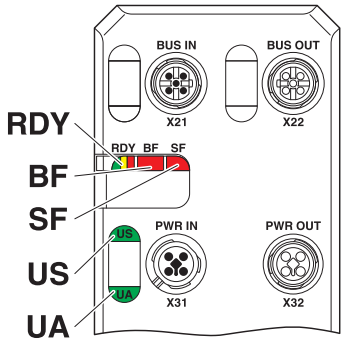


Figure 9 LEDs for bus and power supply

Designation	Color	Meaning	State	Description
RDY	Green/ yellow/ red	**Ready**	Green ON	Device ready to operate
			Yellow flashing	Firmware update is being performed.
			Flashing green/ yellow	Over- or undervoltage at U_S
				Temperature of the device is in the critical area.
				Failure of the actuator supply U_A
				Surge voltage/undervoltage of the actuator supply U_A
				And red US LED: sensor supply overload
			Red ON	Rotary encoding switches are set to an invalid/reserved position.
			OFF	Device is not ready for operation.
BF	Red	**B**us **F**ault	Red ON	No communication on PROFIBUS
				Device is starting up.
				No baud rate detected by device.
			Red flashing	Device has not been configured by the master.
				Device configuration does not match.
				Invalid parameter data received from the master.
				Invalid bus address
				The device is in the clear or stop state. The outputs are in the safe state.
			OFF	No error
SF	Red	Group error	Red ON	Device-specific diagnostics present, e.g., short circuit at the I/O devices.
				Hardware is faulty.
				Device data or parameter data do not match.
			OFF	No error
US	Green/ red	$U_{\mathbf{S}}$ensorik	Green ON	Communications power/sensor voltage present
			OFF	Communications power/sensor voltage not present or too low.
			Red ON	Sensor voltage overload
UA	Green	$U_{\mathbf{A}}$ktorik	ON	Actuator voltage present.
			OFF	Actuator voltage not present.

10.2 Input and output indicators

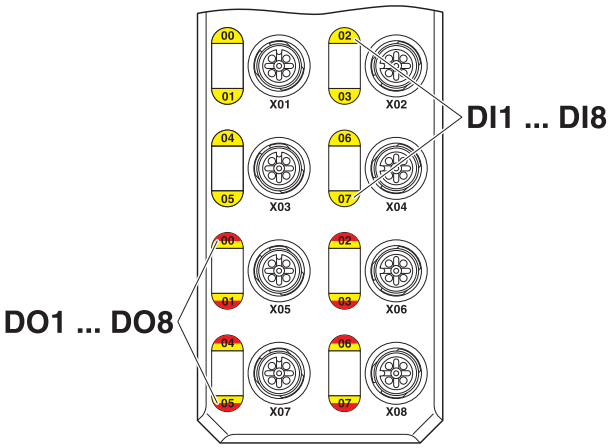


Figure 10 Input and output indicators

Designation	Color	Meaning	State	Description
00 ... 07	Yellow	Status of the inputs	ON	Input is set.
			OFF	Input is not set.
00 ... 07	Yellow/red	Status of the outputs	Yellow ON	Output is set.
			Red ON	Output is short circuited or overloaded.
			OFF	Output is not set.

The numbering of the LEDs is as follows: the first number specifies the byte, the second number specifies the bit.

11 Process data

11.1 Assignment of the terminal points to the IN process data

The I/O data are mapped as follows:

	Input process data							
Byte	**Byte 0**							
Bit	7	6	5	4	3	2	1	0
IN	07	06	05	04	03	02	01	00
Connection	X04		X03		X02		X01	
Pin	2	4	2	4	2	4	2	4
DI	8	7	6	5	4	3	2	1

Key:

Bit:	Process data assignment
IN:	LED marking
DI:	Input of the device

11.2 Assignment of the terminal points to the OUT process data

The I/O data are mapped as follows:

	Output process data							
Byte	**Byte 0**							
Bit	7	6	5	4	3	2	1	0
OUT	07	06	05	04	03	02	01	00
Connection	X08		X07		X06		X05	
Pin	2	4	2	4	2	4	2	4
DO	8	7	6	5	4	3	2	1

Key:

Bit:	Process data assignment
OUT:	LED marking
DO:	Output of the device

11.3 Status module

The device has a status module in slot 1.

The status is mapped as follows.

Bit 31 ... bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Supply of the module electronics and sensors (U_S)		Supply of the actuators (U_A)		Outputs	
Reserved	Undervoltage	Overload	Undervoltage	Short-circuit	Overload	Short-circuit

12 Parameterization

This section provides a detailed description of the format of the parameters for the input and output devices. This may be useful when setting parameters using acyclic services or if there is no user interface for the simple selection of parameters.

Byte	Meaning
1 ... 7	DP standard
8 ... 10	DP/V1 standard
11 ... 12	Module parameter

Module parameter			
Byte	**Meaning**	**Contents**	
11	Behavior of the device	Bit 0 and Bit 1	Substitute value behavior
			00_{bin}: “0” is output to all output bits
			01_{bin}: “1” is output to all output bits
			10_{bin}: hold last value
			11_{bin}: substitute value
		Other	Reserved
12	Substitute values of individual channels 1 ... 8	Bit 0	Substitute value for channel 1 (X05.00)
		Bit 1	Substitute value for channel 2 (X05.01)
		Bit 2	Substitute value for channel 3 (X06.02)
		Bit 3	Substitute value for channel 4 (X06.03)
		Bit 4	Substitute value for channel 5 (X07.04)
		Bit 5	Substitute value for channel 6 (X07.05)
		Bit 6	Substitute value for channel 7 (X08.06)
		Bit 7	Substitute value for channel 8 (X08.07)

13 I&M functions

The following Information & Maintenance functions are supported:

I&M 0

I&M data	Access / data type	Presets
MANUFACTURER_ID	Read / 2 bytes	$B0_{hex}$ (Phoenix Contact GmbH & Co. KG)
ORDER_ID	Read / 20 bytes	-
SERIAL_Number	Read / 16 bytes	-
HARDWARE_Revision	Read / 2 bytes	-
SOFTWARE_Revision	Read / 4 bytes	-
REVISION_Counter	Read / 2 bytes	0000_{hex} (reserved)
PROFILE_ID	Read / 2 bytes	$F600_{hex}$ (generic device)
PROFILE_SPECIFIC_TYPE	Read / 2 bytes	0003_{hex} (IO module)
IM_VERSION	Read / 2 bytes	0102_{hex} (Version 1.2)
IM_SUPPORTED	Read / 2 bytes	$000E_{hex}$ (I&M 1 ... 3)

I&M 1

I&M data	Access / data type	Presets
TAG_FUNCTION	Read/write / 32 bytes	“20_{hex}” (empty)
TAG_LOCATION	Read/write / 22 bytes	“20_{hex}” (empty)

I&M 2

I&M data	Access / data type	Presets
INSTALLATION_DATE	Read/write / 16 bytes	“20_{hex}” (empty)
RESERVED	Read/write / 38 bytes	0_{hex}

I&M 3

I&M data	Access / data type	Presets
DESCRIPTOR	Read/write / 54 bytes	“20_{hex}” (empty)

14 Sync/freeze mode

The device supports sync and freeze mode.

The functions must be activated by the PROFIBUS master in the parameter data.

Input and output data is written or read at defined times with the sync and freeze commands.

If the device receives a sync command from the PROFIBUS master at any given time, the current OUT process data is transferred and frozen until the next sync command.

Similarly, the states of the inputs are transferred on the respective freeze command and are frozen until the next freeze command.

15 Diagnostic alarms

PROFIBUS enables the PROFIBUS device to store diagnostic information together with the error location and error type.

In the default upon delivery the alarms are enabled, however, they can be disabled with parameters on startup.

An incoming alarm informs the PROFIBUS device that diagnostic information has been entered.

When the diagnostic information has been removed, an outgoing alarm is sent to the device.

If at least one piece of diagnostic information is stored, the SF LED is on. If no diagnostic information is present, the SF LED is off.

The following PROFIBUS diagnostic messages are indicated by the PROFIBUS device:

- Overtemperature of the device
- Surge voltage of U_S
- Overload of U_S
- Surge voltage of U_A
- Undervoltage of U_A
- Short circuit of U_A
- Short circuit of an output
- Output overload

16 Monitoring

A process data watchdog is integrated into the device to avoid uncontrolled setting/resetting of outputs in the event of an error.

If device outputs are set, the controlling process must be able to access the device.

In the event of an error, e.g., bus cable interrupted or function error in the controlling process, the device can respond appropriately via the process data watchdog.

When activating the process data watchdog, it is started by the first write process and the next write process is expected within the timeout period. During error-free operation, the write process is performed during the timeout period and the watchdog is restarted (triggered).



Reading calls do not trigger the process data watchdog.

If there is no triggering during the timeout period, an error occurred. Two responses follow:

- All outputs are set to the configured substitute value.
- The BF LED indicates the corresponding state.

17 Substitute value behavior

If PROFIBUS communication fails or if no valid process data is received from the PROFIBUS master, all device outputs are set to the parameterized substitute values.